

Googling the Brain: Discovering hierarchical and asymmetric network structures, with applications in neuroscience

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Abstract

Hierarchical organisation is a common feature of many directed networks arising in nature and technology. For example, a well-defined message-passing framework based on managerial status typically exists in a business organisation. However, in many real-world networks such patterns of hierarchy are unlikely to be quite so transparent. Due to the nature in which empirical data is collated the nodes will often be ordered so as to obscure any underlying structure. In addition, the possibility of even a small number of links violating any overall “chain of command” makes the determination of such structures extremely challenging. Here we address the issue of how to reorder a directed network in order to reveal this type of hierarchy. In doing so we also look at the task of quantifying the level of hierarchy, given a particular node ordering. We look at a variety of approaches. Using ideas from the graph Laplacian literature, we show that a relevant discrete optimization problem leads to a natural hierarchical node ranking. We also show that this ranking arises via a maximum likelihood problem associated with a new range-dependent hierarchical random graph model. This random graph insight allows us to compute a likelihood ratio that quantifies the overall tendency for a given network to be hierarchical. We also develop a generalization of this node ordering algorithm based on the combinatorics of directed walks. In passing, we note that Google’s PageRank algorithm tackles a closely related problem, and may also be motivated from a combinatoric, walk-counting viewpoint. We illustrate the performance of the resulting algorithms on synthetic network data,

and on a real-world network from neuroscience where results may be validated biologically.

1 Introduction

Determining hidden structure and substructure within a complex network provides us with a plethora of clues concerning both its functional capabilities and its evolutionary history. This motivates the need for quantitative tools to discover significant topological features, such as well-connected communities, bipartite structures, bottle-necks, motifs, hubs and authorities [6, 16, 17, 22, 33]. In this work we focus on a particular type of structure, namely that of a directed hierarchy; a notion that will be defined more precisely as we proceed.

We begin by noting that the phrase *hierarchical* may be used to denote a fractal type of network organisation, whereby smaller modules repeat in a self-similar manner [32, 38]. In this work we are using the alternative meaning of hierarchical to denote a directed network structure that supports a well defined message-passing or “chain of command” scenario, such that the processing of information or the exercise of managerial control proceeds sequentially in a top-to-bottom fashion. This is the viewpoint taken in the recent articles [4, 27, 35]. Our work differs in that we aim to use first principle arguments based on quantitative measures of network hierarchy in order to derive algorithms that reveal these structures. We also aim to provide a quantitative summary of the overall tendency of a given network to be hierarchical, and in doing so we introduce a new class of random graphs with a hierarchical structure.

We use the following notation. Given an unweighted, directed network consisting of N nodes, we denote by $A \in \mathbb{R}^{N \times N}$ the corresponding adjacency matrix. So A is generally unsymmetric and has $a_{ij} = 1$ if there is an edge from node i to node j , and $a_{ij} = 0$ otherwise. We assume $a_{ii} = 0$ for $i = 1, \dots, N$, discounting self-loops. The out and in degree of node k are specified as

$$\text{deg}_k^{\text{out}} := \sum_j a_{kj} \quad \text{and} \quad \text{deg}_k^{\text{in}} := \sum_i a_{ik},$$

respectively. We denote by \mathcal{P} the set of all permutations of the integers $1, 2, \dots, N$, and use p_i to denote the i th component of member $p \in \mathcal{P}$. The Euclidean vector norm is denoted by $\|\cdot\|_2$ and $\mathbf{1} \in \mathbb{R}^N$ represents the vector with all components equal to one.

The layout of the paper is as follows. In Section 2 we recall how the widely used Fiedler vector is relevant as the solution to an optimization problem that emphasizes similarity between nodes. We then introduce a new optimization problem as a means to quantify hierarchy, and show how it can be solved. This results in a simple network reordering algorithm based on the difference between out and in degrees. In Section 3 we exploit ideas from random graph theory that can be used to reorder a network from a maximum likelihood perspective. We show that the algorithm from Section 2 may be viewed as a maximum likelihood reordering under a new, directed, range-dependent random graph hypothesis. In addition to providing an alternative motivation for the algorithm, this viewpoint also allows us to quantify the level of hierarchy in a network by comparing log-likelihood ratios for hierarchical versus non-hierarchical range-dependent structure. We give some illustrative computational results on synthetically generated networks, quantifying the extent to which this approach is tolerant of noise. Section 4 then looks at an alternative, combinatoric approach. We show how the level of hierarchy in a particular node can be conveniently quantified by counting directed walks. We show in section 5 how Google’s PageRank algorithm performs a related task. In section 6 we evaluate the new methods on a neuronal network where the hierarchical structure has biological significance.

2 Out Minus In Degree

To motivate the work in this section, we begin with the *two-sum* [2, 21]

$$\sum_{i=1}^N \sum_{j=1}^N (i - j)^2 a_{ij}.$$

This nonnegative quantity is small when the presence of edges is biased towards nodes that have nearby indices. Equivalently, it is small when the nonzeros in the adjacency matrix appear close to the diagonal. Reordering the nodes corresponds to mapping $i \rightarrow p_i$ for some permutation $p \in \mathcal{P}$, and the task of finding a minimum two-sum reordering may thus be written

$$\min_{p \in \mathcal{P}} \sum_{i=1}^N \sum_{j=1}^N (p_i - p_j)^2 a_{ij}. \tag{1}$$

In general, this discrete optimization problem is computationally intractable and it is therefore common to consider a relaxed version where p is allowed to take real values. To avoid redundancies from scaling and shifting, we also impose constraints $\|p\|_2 = 1$ and $p^T \mathbf{1} = 0$. This leads to

$$\min_{p \in \mathbb{R}^N, \|p\|_2=1, p^T \mathbf{1}=0} \sum_{i=1}^N \sum_{j=1}^N (p_i - p_j)^2 a_{ij}. \quad (2)$$

We may now introduce the graph Laplacian $L := D - B$, where $B := \frac{1}{2}(A + A^T)$ and the diagonal matrix D has $d_{ii} = \sum_k b_{ik}$. In the case where the graph represented by B is connected, L is symmetric positive semi-definite with a single eigenvalue equal to zero and corresponding eigenvector proportional to $\mathbf{1}$. It follows that (2) is solved by taking p to be the *Fiedler vector*, v ; that is, the eigenvector corresponding to the second smallest eigenvalue of L . We refer to [5, 34, 36] for further details, noting that most authors treat the case where A is symmetric. Having obtained a relaxed solution v , we may recover a permutation $p \in \mathcal{P}$ by the natural procedure of ordering the nodes according to their real-valued components. More precisely, we compute $p \in \mathcal{P}$ such that

$$v_i \leq v_j \iff p_i \leq p_j, \quad (3)$$

with some rule for treating ties.

To illustrate this idea, the upper left picture in Figure 1 shows the adjacency matrix for a network showing a strong preference for short-range edges (to produce this matrix, we computed an instance of Grindrod’s range-dependent random graph model described in Section 3, with $\beta = 0.015$ and $N = 100$). After applying a random shuffle to the nodes we obtain the adjacency matrix shown in the upper middle picture in Figure 1; any evidence of the range dependent structure has been completely destroyed. Finally, the upper right picture in Figure 1 shows the adjacency matrix when reordered via the Fiedler vector. We see that the hidden structure has been recovered. The respective values of the two-sum starting from left to right are 32037, 1283966 and 30155. As mentioned above, the reordering from the Fiedler vector is not guaranteed to minimize the two-sum, as it solves only a relaxed version of the problem. However, in this case we note that it gives a two-sum that is below the value produced by the original lattice ordering.

We now consider how this approach can be adapted to discover hierarchical structure. We use

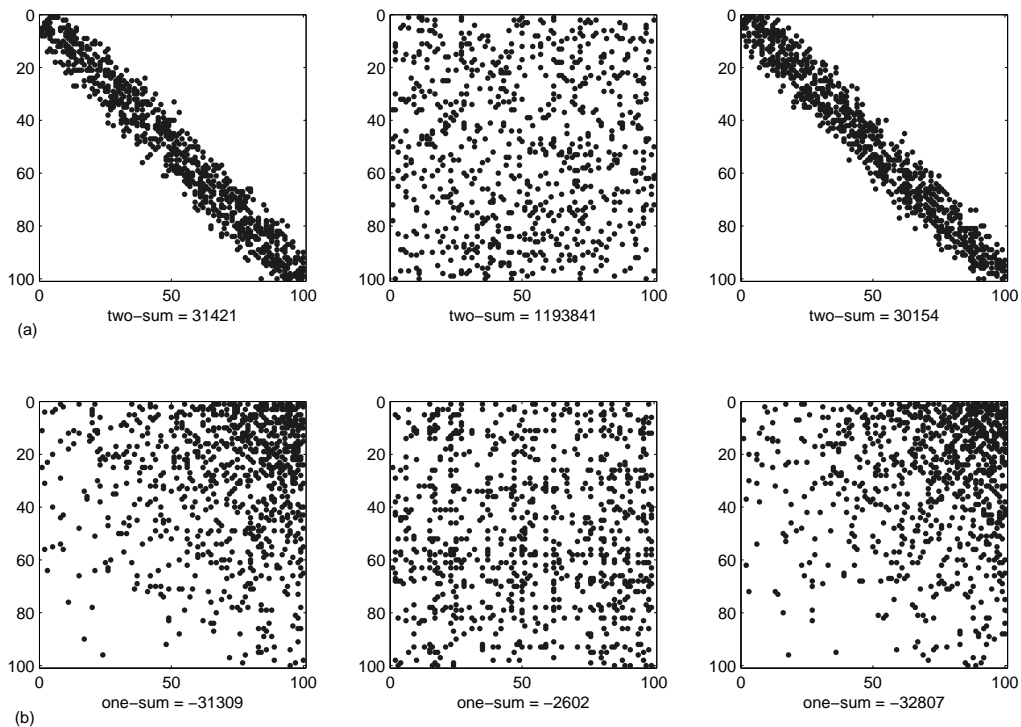


Figure 1: Left: adjacency matrix for a network with (a) short-range connectivity structure and (b) hierarchical connectivity structure. Middle: in both cases the connectivity structure is hidden via a random shuffle of the network nodes. Right: the respective structures are recovered via (a) a Fiedler vector reordering and (b) reordering based upon out-in degree (see (6)).

the convention that nodes are to be ordered in descending order of importance, so node 1 is at the top of the hierarchy and node N at the bottom. For a given network and a given node ordering, we may then introduce the new concept of a *directed one-sum*

$$\sum_{i=1}^N \sum_{j=1}^N (i-j)a_{ij}, \quad (4)$$

to quantify the level of hierarchy. In this expression, each edge is involved in the overall sum. An edge that respects the hierarchy, $i < j$, contributes a negative amount, with the weight $i - j$ being more negative when i is further up the hierarchy than j . Similarly, an edge that violates the hierarchy, $i > j$, contributes a positive amount, with the weight $i - j$ being more positive when i is further down the hierarchy than j . It follows that a more negative value for the directed one-sum

corresponds to a more hierarchical combination of network and node ordering. In order to search for the best way to reorder a given network in a manner that reveals hierarchical structure, it is therefore reasonable to minimize the directed one sum:

$$\min_{p \in \mathcal{P}} \sum_{i=1}^N \sum_{j=1}^N (p_i - p_j) a_{ij}. \quad (5)$$

This is very simply re-written as

$$\min_{p \in \mathcal{P}} \sum_{i=1}^N p_i (\deg_i^{\text{out}} - \deg_i^{\text{in}}),$$

and it follows that the problem (5) is solved by ordering the nodes according to the difference between out and in degrees:

$$\deg_i^{\text{out}} - \deg_i^{\text{in}} \geq \deg_j^{\text{out}} - \deg_j^{\text{in}} \iff p_i \leq p_j. \quad (6)$$

We emphasize that, unlike in the two-sum case (1)–(3), this ordering solves the discrete formulation of the problem, not just a relaxed version of it.

To illustrate this idea, the lower left picture in Figure 1 shows the adjacency matrix for a network showing a strong hierarchical structure (to produce this matrix, we computed an instance of the directed range-dependent random graph model described in Section 3, with $\alpha = 0.025$ in (8) and $N = 100$). An arbitrary node shuffle produced the adjacency matrix shown in the lower middle picture in Figure 1. Finally, the lower right picture in Figure 1 shows the adjacency matrix when reordered via the out minus in degrees (6). We see that the hidden structure has been recovered. The respective one-sum values from left to right are -31309 , -2602 and -32807 , and we know from the derivation above that the latter value is the global minimum.

We note that the authors in [27] considered the *ratio* of in to out degree in order to rank a node within a hierarchy, without giving any justification for the measure. Of course, this is equivalent to a ranking based on the log-difference $\log(\deg_i^{\text{out}}) - \log(\deg_i^{\text{in}})$; whereas the ranking that we have derived via the directed one-sum does not use logs. Additionally, the new ranking derived here is also able to deal with nodes containing no out-going connections.

We also note a similarity between directed one-sum minimization and the task of finding a *topological ordering* of a directed graph. Such an ordering may be viewed as having no positive values in the directed one-sum (4). Alternatively it may be viewed as an ordering where all nonzeros in the adjacency matrix have been placed in the upper triangle. This is possible if and only if we have a directed acyclic graph (DAG) [1]. The minimization problem (5) has a different emphasis in that (a) we seek a complete ordering of the nodes rather than a partial ordering, (b) we wish to apply the concept to general directed networks rather than DAGs. Further, in (5) we measure the extent to which the hierarchy has been respected or violated in the sense that a link from node 1 to node 100 makes a more favorable contribution than a link from node 99 to node 100, and similarly, a link from node 100 to node 1 makes a more unfavorable contribution than a link from node 99 to node 100. However, in the spirit of topological ordering for DAGs, in section 6 we use the percentage of nonzeros in the upper triangle of the reordered adjacency matrix as one way to compare algorithms.

3 Random Graph Viewpoint

In this section we show that the out-in ordering (6) can also be justified via a random graph argument, and use this as a means to quantify the amount of hierarchy in a given network.

The general class of range-dependent random graphs introduced by Grindrod [18, 19] may be defined as follows.

Definition 3.1. *For a given function g that maps from $\{1, 2, \dots, N-1\}$ to $[0, 1]$, a range-dependent random graph (RDRG) is an undirected graph that has an edge from node i to node j with independent probability $g(|i - j|)$.*

With this definition we may think of node i as being positioned at location i on the integer lattice. The chance of two nodes being linked is then a function of their lattice distance, $|i - j|$. In the upper left picture of Figure 1 shows an instance of a RDRG with g taking the functional form of (10), with $\beta = 0.15$. Because g is a decaying function, ‘long-range’ connections are less likely than those at ‘short-range.’

We now introduce a natural analogue of Grindrod’s RDRG class of models that allows directed and hierarchical networks to be generated at random.

Definition 3.2. For a given function f that maps from $\{1, 2, \dots, 2N - 1\}$ to $[0, 1]$, a directed range-dependent random graph (*dRDRG*) has an edge from node i to node j with independent probability $f(i - j + N)$.

A hierarchical structure will arise when f is monotonically decreasing in this dRDRG setting: in that case the edge from node $i = 1$ to node $j = N$ is the most likely and the reverse edge from $i = N$ to $j = 1$ is the least likely.

Given a network and an ordering, the likelihood that this data came from the dRDRG model is given by

$$\prod_{a_{ij}=1} f(i - j + N) \times \prod_{a_{ij}=0} (1 - f(i - j + N)).$$

We may then ask for the reordering that is most likely under this model:

$$\max_{p \in \mathcal{P}} \prod_{a_{ij}=1} f(p_i - p_j + N) \times \prod_{a_{ij}=0} (1 - f(p_i - p_j + N)). \quad (7)$$

The next result connects this problem to the directed one-sum minimization.

Result 1. The one-sum minimization problem (5) is equivalent to the maximum likelihood reordering problem (7) when the directed range dependency takes the form

$$f(i - j + N) = \frac{e^{-\alpha(i-j+N)}}{1 + e^{-\alpha(i-j+N)}}, \quad (8)$$

for any fixed $\alpha > 0$.

Proof. We may follow the technique used in [18] from the undirected case by re-writing (7) as

$$\max_{p \in \mathcal{P}} \prod_{a_{ij}=1} \frac{f(p_i - p_j + N)}{1 - f(p_i - p_j + N)} \times \prod_{\text{all } i, j} (1 - f(p_i - p_j + N)).$$

The second factor, the probability of a null graph, is independent of p , so an equivalent problem is

$$\max_{p \in \mathcal{P}} \prod_{a_{ij}=1} \frac{f(p_i - p_j + N)}{1 - f(p_i - p_j + N)}.$$

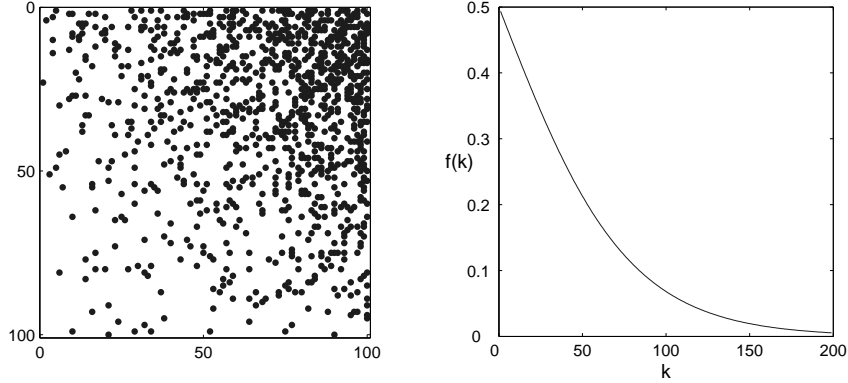


Figure 2: An instance of a hierarchical dRDRG with $N = 100$ and $\alpha = 0.0262$ (left). The model connects node i to node j with probability $f(i - j + N)$, where f has the form shown on the right.

When f has the form in (8), this may be re-written as

$$\max_{p \in \mathcal{P}} \prod_{a_{ij}=1} e^{-\alpha(p_i - p_j + N)}.$$

Taking logs and negating the objective function leads to

$$\min_{p \in \mathcal{P}} \alpha \sum_{i=1}^N \sum_{j=1}^N (p_i - p_j + N) a_{ij},$$

which is clearly equivalent to (5). □

The picture on the left in Figure 2 shows an instance of the hierarchical dRDRG model, with the nodes ordered according to the range-dependency, in the case where $N = 100$ and $\alpha = 0.0262$ in (8). We see that the structure is consistent with the aims of the directed one-sum minimization—nonzeros are most prevalent at the upper right hand corner of the matrix, and the density decreases as we move towards the lower left hand corner. In the right of the figure we plot the range-dependency function, f , from (8).

We see from Definition 3.1 that with Grindrod's RDRG model we have, for a given decay function g , $a_{ij} = 1$ with probability $g(|i - j|)$ and $a_{ij} = 0$ otherwise. It was shown in [21] that the

corresponding maximum likelihood reordering problem

$$\max_{p \in \mathcal{P}} \prod_{a_{ij}=1} g(|p_i - p_j|) \times \prod_{a_{ij}=0} (1 - g(|p_i - p_j|)) \quad (9)$$

is equivalent to two-sum minimization (1) for the particular range dependency

$$g(|i - j|) = \frac{e^{-\beta(i-j)^2}}{1 + e^{-\beta(i-j)^2}}, \quad (10)$$

where we have introduced a free parameter $\beta > 0$ to be compatible with the general case specified in Result 1.

This insight puts us in a position to compare the likelihood that a given network arose from each of these two model classes. We may summarize such an algorithm as follows.

Step 1 Fit the parameters α and β in the two models. This can be done by matching the number of edges in the given network to the expected number of edges in the random graph model. The latter is a monotonic function of the free parameter in both cases, so a simple bisection root-finding method is guaranteed to succeed.

Step 2 Compute the maximum likelihood from the hierarchical model, say \mathcal{L}_h , which is given by inserting the minimum directed one-sum ordering into the objective function in (7) with f defined in (8). Compute the approximate¹ maximum likelihood from the non-hierarchical model, say \mathcal{L}_{nh} , which is given by inserting the Fiedler vector ordering into the objective function in (9) with g defined in (10).

Step 3 Compute the normalized log likelihood ratio

$$L := \frac{2}{N(N-1)} \log \left(\frac{\mathcal{L}_{nh}}{\mathcal{L}_h} \right). \quad (11)$$

A negative ratio indicates that the network data supports the hierarchical range-dependency over the non-hierarchical alternative.

As a proof-of-principle, we give results for a large-scale experiment using synthetically generated networks. In each test, we began with an instance of a network from one of the two random

¹This is approximate because the Fiedler vector solves a relaxed version of the minimum two-sum problem.

s	N				
	50	100	200	500	1000
0.1	0.1150	0.1147	0.1149	0.1122	0.1151
0.2	0.1360	0.1354	0.1370	0.1361	0.1359
0.3	0.1472	0.1472	0.1479	0.1471	0.1478
0.4	0.1548	0.1552	0.1550	0.1547	0.1546
0.5	0.1572	0.1573	0.1577	0.1571	0.1572

Table 1: Proportion of spurious links tolerated when discovering a hierarchical dRDRG network.

s	N				
	50	100	200	500	1000
0.1	0.1290	0.1259	0.1256	0.1271	0.1274
0.2	0.1356	0.1339	0.1352	0.1353	0.1348
0.3	0.1366	0.1360	0.1368	0.1363	0.1357
0.4	0.1362	0.1362	0.1360	0.1365	0.1359
0.5	0.1359	0.1358	0.1358	0.1357	0.1355

Table 2: Proportion of spurious links tolerated when discovering a non-hierarchical RDRG network.

classes under consideration. To assess robustness to noise we then added spurious links at random. For each network instance, we placed a new link between all possible pairs of nodes with small independent probability, q . If the likelihood ratio correctly identified the structure of interest, we increased the noise parameter q and repeated the analysis. Tables 1 and 2 record the smallest value of q (averaged over an ensemble of 1000 random graphs) for which the likelihood ratio incorrectly classified the structure. We used graphs of order $N = 50, 100, 200, 500, 1000$, which had on average $(N^2 - N) \times s$ edges; here $s \in \{0.1, 0.2, 0.3, 0.4, 0.5\}$ denotes the proportion of edges present, on average, for each network instance.

From Tables 1 and 2, we see that the likelihood approach continues to classify the network models correctly even after some 10%–15% of additional links have been added. Note that robustness generally improves as we increase the proportion of connections present in the initial instance; a trend that is particularly evident for the hierarchical model. This observation is consistent with the idea that the presence of additional links translates into additional information concerning network architecture. To match the case of typical real networks, we have focussed on sparse structures. If we tuned α and β to allow for increasingly dense connectivity patterns, then, intuitively, we would expect to see the test become less reliable—as both networks models approach the complete graph,

they become indistinguishable.

4 Directed Walks and Matrix Functions

The out-in ordering studied in the previous two sections is computationally convenient and was justified from first principles. However, it has the possible drawback that, being based on integer-valued quantities, nodes may frequently be tied. In particular, for the simple case of a directed binary tree, all nodes except the root have an equal out-in score.

A more global strategy that looks beyond the degree structure was considered in [27], where the concept of *attraction basin hierarchy* was introduced. The resulting algorithm is based upon counting the number of shortest paths to/from a particular node from/to all other nodes, which is a hard combinatorial problem in general. Here, we propose an alternative measure that uses directed walks rather than paths². Recent work has shown that walk-based measures provide an effective tool for determining other types of connectivity patterns [7, 11, 12, 20], and there are at least four specific arguments in their favour:

- information does not generally flow along geodesics [3, 28],
- walk counts are less sensitive than pathlength counts to spurious or missing edges [20],
- walk counts can be computed conveniently using basic operations in linear algebra [15],
- as we will show below, Google’s successful PageRank algorithm has a walk-based interpretation.

The computational convenience arises because the element $(A^n)_{ij}$ counts the number of directed walks of length n that start at node i and terminate at node j . We may then introduce coefficients $c_0, c_1, c_2, c_3 \dots$ and consider the expansion

$$F(A) = c_0 I + c_1 A + c_2 A^2 + c_3 A^3 + \dots \quad (12)$$

Because longer walks are generally (a) more numerous, and (b) less important than shorter walks, it is reasonable to choose a decreasing sequence of coefficients. Estrada and Rodríguez-Velázquez

²A walk differs from a path in that nodes and edges may be re-used during the traversal.

[14] suggested $c_k = 1/(k!)$, so that $F(A) = \exp(A)$, and this choice has proved to be very useful in many scenarios [7, 8, 10, 11, 12, 13]. The resolvent function $F(A) = (I - \delta A)^{-1}$, corresponding to $c_k = \delta^k$, was considered in [15] and can be traced back to earlier work on node centrality indices in social network analysis [24, 29]. It is also possible to interpret δ as the probability that a message will successfully traverse an edge.

We may now classify the hierarchical rank of a node by measuring

- $\sum_{j \neq i} (F(A))_{ij}$, which quantifies how effectively node i is able to pass information to or exert control over the other nodes in the network, and
- $\sum_{j \neq i} (F(A))_{ji}$, which quantifies how effectively the other nodes in the network are able to pass information to or exert control over node i .

We therefore propose that node i be assigned the hierarchical ranking

$$r_i = \sum_{j \neq i} (F(A))_{ij} - \sum_{j \neq i} (F(A))_{ji}, \quad (13)$$

leading to a reordering in descending rank order; that is

$$r_i \geq r_j \iff p_i \leq p_j.$$

Note that the walk based hierarchy measure of (13) can be considered as a natural generalisation of the degree based algorithm introduced earlier, in the sense that by choosing $F(A) = A$ we recover the out-in degree ordering.

5 Links to Google's PageRank

The well-known PageRank algorithm is used by Google to quantify the importance of web pages based on the hyperlink topology of the WWW [25, 30]. Letting A represent the web adjacency matrix, so $a_{ij} = 1$ means that page i has a hyperlink to page j , this algorithm assigns rank according to the vector

$$(I - \theta A^T D^{\text{out}^{-1}})^{-1} \mathbf{1}, \quad (14)$$

with a higher value in component i denoting more importance for page i . Here $\theta \in (0, 1)$ is a free parameter and D^{out} is the diagonal out degree matrix, so $D_{ii}^{\text{out}} = \text{deg}_i^{\text{out}}$. We assume for the moment that $\text{deg}_i^{\text{out}} \geq 1$ for all i . Writing $\widehat{A} := A^T D^{\text{out}-1}$ we see that, for sufficiently small θ , the ranking in (14) may be expanded as

$$\left(I + \theta \widehat{A} + \theta^2 \widehat{A}^2 + \theta^3 \widehat{A}^3 + \dots \right) \mathbf{1}.$$

This shows that PageRank may be interpreted as a directed walk counting algorithm, with a few twists³.

Link direction is reversed and edges are scaled. The new matrix \widehat{A} has $\widehat{a}_{ij} \neq 0$ if and only if there is a hyperlink from page j to page i . This is intuitively reasonable—the $j \mapsto i$ hyperlink may be interpreted as page j deferring to, or handing control over to, page i . (In the WWW context it is also extremely pertinent that page i has no direct influence over the creation of a $j \mapsto i$ hyperlink. This makes it difficult to boost artificially your own page’s ranking.) Supposing that the hyperlinks $i_{k+1} \mapsto i_k, i_k \mapsto i_{k-1}, \dots, i_2 \mapsto i_1$ exist on the WWW. Then the walk of length k given by $i_1 \rightarrow i_2 \rightarrow \dots \rightarrow i_{k+1}$ exists in the reversed network, but in addition to the θ^k scaling that penalizes long walks, there is also a scaling

$$\frac{1}{\text{deg}_2^{\text{out}}} \frac{1}{\text{deg}_3^{\text{out}}} \dots \frac{1}{\text{deg}_{k+1}^{\text{out}}}$$

penalizing walks involving “promiscuous” nodes that make themselves available for many other such walks. This method for nullifying the influence of overactive nodes that are likely to be lowly ranked is clearly relevant in the WWW setting. However, in the context of this work, where we are seeking to discover a hierarchical “chain of command,” it seems less appropriate to normalize in this way. If node i gives orders to (i.e. has a hyperlink from) a node that also gets orders from (i.e. has hyperlinks to) many other nodes, then this could be regarded as sound evidence for placing node i near the top of the hierarchy.

Closed walks are considered. Node i is given a ranking based on the sum over all j of a weighted count of directed walks that begin at i and end at j , including the closed walk case $j = i$.

³We note that this is distinct from the well-known *random walk* interpretation of PageRank [25, 30].

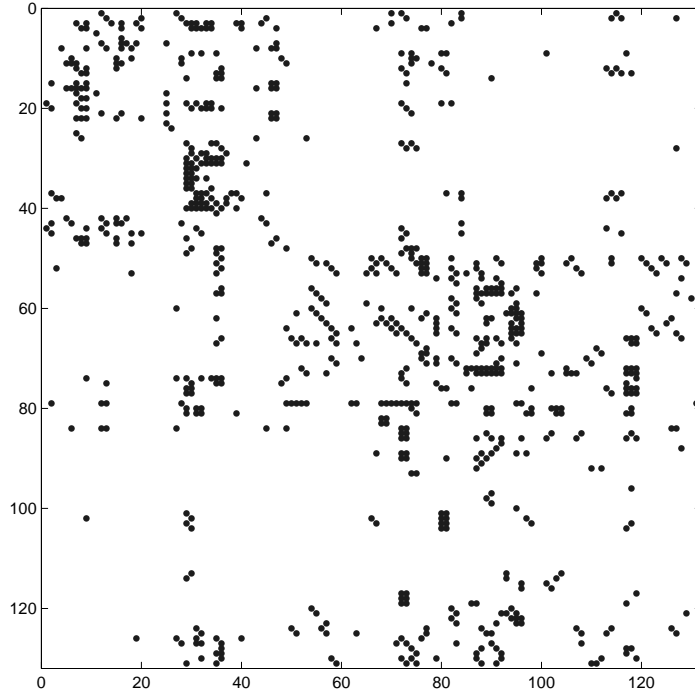


Figure 3: Adjacency matrix for the local network of 131 frontal neurons for *C. elegans*.

6 Local *C. elegans* Network

In his PhD thesis in 1987, Durbin [9] went about the task of sorting the neurons in the nerve ring of *C. elegans*⁴ vertically, in such a way that as many of the synapses as possible pointed downwards. Durbin used an ad hoc combinatoric algorithm to create an ordering. Here, we propose to repeat Durbin’s analysis using the automated algorithms that we have derived. We consider a local subnetwork of 131 frontal neurons and 782 chemical synapses of the neuronal network for *C. elegans* [23, 31, 37]. We exclude gap junctions⁵ from the analysis since (a) it remains an open question whether or not such connections exhibit directionality; and (b) current experimental techniques are unable to extract this information regardless. The adjacency matrix is shown in Figure 3.

Figure 4 shows the results of reordering the local *C. elegans* network based upon (i) out-in degree, (ii) the walk based measure (13) with $F(A) = \exp(A)$, (iii) the walk based measure (13)

⁴A 1mm long, transparent, roundworm.

⁵Gap junctions are channels that provide electrical coupling between neurons.

	out minus in	exponential	resolvent ($\delta = 0.025$)	PageRank
Directed one-sum	-32857	-27198	-32809	-22649
Proportion of non-zeros in upper triangle	0.8095	0.7724	0.8056	0.7366

Table 3: Hierarchy scores for the *C. elegans* network.

with $F(A) = (I - \delta A)^{-1}$ and $\delta = 0.025$, and (iv) Google’s PageRank. In the latter case, dangling nodes, where $\text{deg}_i^{\text{out}} = 0$, require a slight modification of the Google matrix in (14) [25]. We used the widely quoted teleporting parameter value $\theta = 0.85$.

Table 3 quantifies the ability of each method to discover hierarchical structure. The first row gives the directed one-sum; that is, the objective function in (5), for each ordering. We note from Result 1 that the out-in degree ordering minimizes this quantity. From Table 3 we see that the directed one-sum in (4) attains a minimum value of -32857 ; next came the walk based algorithms, with scores of -32809 using the resolvent function and -27198 using the matrix exponential; finally, the ordering obtained via the PageRank algorithm performed poorest according to this measure with a score of -22649 . The second row in Table 3 records the proportion of nonzeros in the upper triangle of the adjacency matrix. With this alternative measure, there is no extra benefit/penalty from violating/exploiting the hierarchy with a ‘long-range’ link that spans many intermediate nodes. Instead we simply count the proportion of links that respect the hierarchy. We see from the table that the out-in ordering is marginally better than that given by the walk based algorithms according to this measure; all methods scoring between 77% to 81%, whilst PageRank achieved around 73%.

To justify the choice of $\delta = 0.025$ in the resolvent-based reorderings, Figure 5 shows how the proportion of non-zeros in the upper triangle (left) and directed one-sum (right) vary as a function of δ —both measures start to degrade beyond this level.

The normalized log likelihood ratio in (11) was $L = -1.9319$, giving further support for the visually compelling evidence in Figure 4 that this network has a strong hierarchical element.

Let us now focus on biological significance of these results in the particular case of the walk based measure with $F(A) = (I - \delta A)^{-1}$ and $\delta = 0.025$. Table 4 summarizes the results for the reordered *C. elegans* data, where we report those neuronal classes represented by nodes in the top and bottom 10% of the reordered network. Perhaps most noteworthy is the fact that neuronal

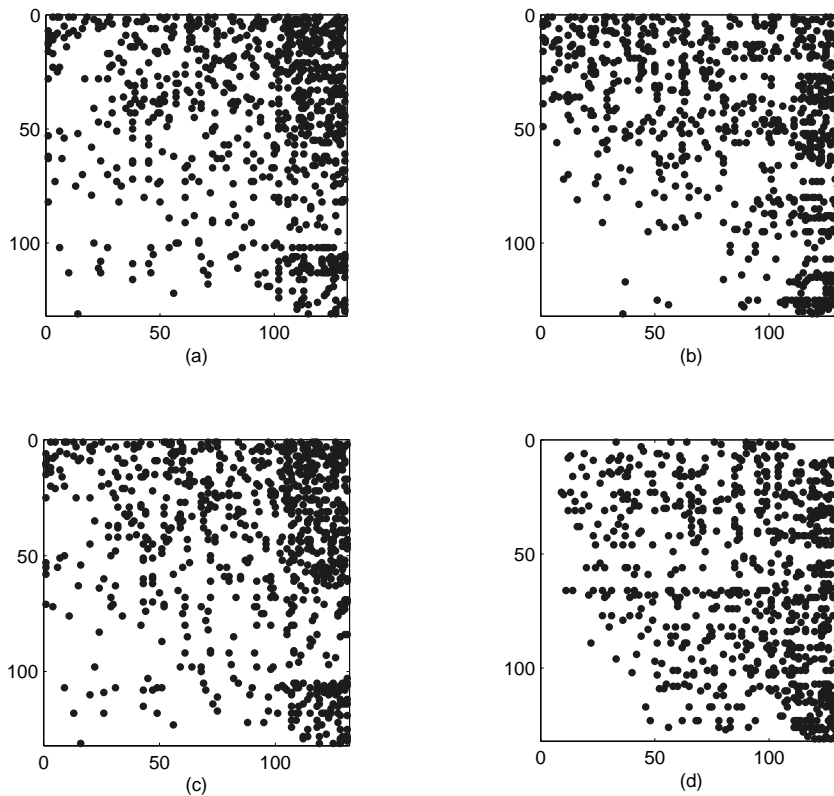


Figure 4: Results for the *C. elegans* neuronal network: (a) reordered using out-in degree; (b) reordered using the walk based measure with $F(A) = \exp(A)$; (c) reordered using the walk based measure with $F(A) = (I - \delta A)^{-1}$ and $\delta = 0.025$; and (d) reordered using Google's PageRank algorithm.

classes representing sensory neurons are highly prevalent at the top of the hierarchy (some 85%), whilst the foot of the hierarchy consists wholly of a mixture of motor neurons and command interneurons. In general, we found that the ordering returned was in good agreement with that of Durbin's, with sensory neurons placed at the top, motor neurons at the bottom, and interneurons placed in between.

The command interneuron classes AVA, AVB, AVD and AVE appearing at the bottom of the hierarchy in Table 4 have been identified in previous studies [26] as being highly connected to both sensory and motor neurons. This suggests that they should lie in the middle of the global hierarchy. However, we note that the majority of postsynaptic connections made by these neurons are with motor neurons outside of the local subnetwork studied here, which justifies their placement within

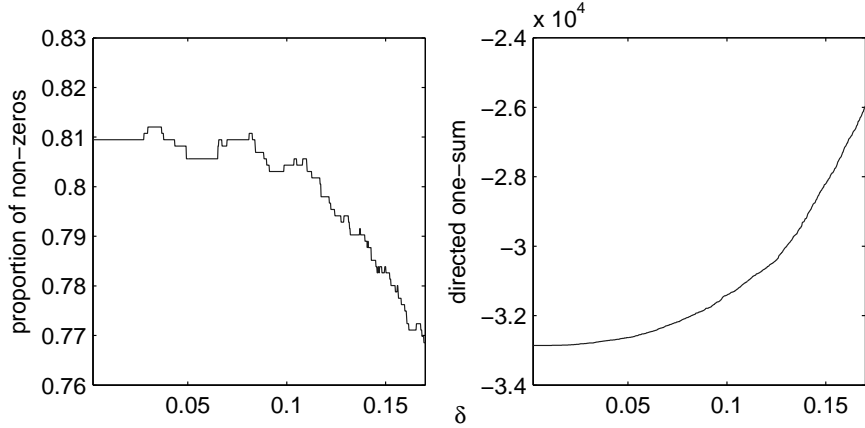


Figure 5: Plots of both hierarchy scores versus δ when using the resolvent function, $F(A) = (I - \delta A)^{-1}$, to reorder the *C. elegans* network.

Top 10%		Bottom 10%	
Neuronal Class	Description	Neuronal Class	Description
R1H	Ring interneuron	AVA	Command interneuron
ADL	Amphid sensory neuron	AVE	Command interneuron
CEP	Head sensory neuron	RMD	Ring motor
IL2	Head sensory neuron	RME	Ring motor
OLL	Head sensory neuron	AVB	Command interneuron
AVH	Interneuron	SMD	Ring motor
URY	Head sensory neuron	AVD	Command interneuron

Table 4: Neuronal class and type for those nodes contained within the top and bottom 10% after reordering the *C. elegans* network based upon the walk based measure with $F(A) = (I - \delta A)^{-1}$ and $\delta = 0.025$.

this subnetwork.

7 Discussion

This work considered a range of measures and algorithms relevant to discovering and quantifying hierarchical structure in a given network. The basic out minus in degree ordering (6) has the benefit of being the exact solution to an appropriate discrete optimization problem. Also its connection to a random graph model model allows it to be incorporated into a likelihood test (11) for hierarchical versus non-hierarchical structure. Walk-based measures of the form (13) directly generalize this approach and have the appeal of taking a more global view of the network topology. Also, as shown

in Figure 5, they can be used in conjunction with hierarchy measures to fine-tune parameters in the algorithm.

These new reordering approaches use extremely simple combinatorics, and hence they scale favourably for large, sparse networks. If the expansion (12) is truncated after a finite number, K , of terms (for example, $K = 10$) then the walk-based ranking (13) requires only K sparse matrix-vector multiplications. This gives an overall complexity proportional to the number of edges. The degree-based ordering is comparable with the use of a single term in (12) and also has complexity proportional to the number of edges.

Overall, we believe that this is a very promising methodology for discovering and quantifying hierarchy in large, complex, directed networks.

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