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1	Muscle fatigue increases beta-band coherence between the firing times of
2	simultaneously active motor units in the first dorsal interosseous muscle
3	by
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25 ABSTRACT

26 Synchronization between the firing times of simultaneously active motor units (MUs) is generally 27 assumed to increase during fatiguing contractions. To date, however, estimates of MU 28 synchronization have relied on indirect measures, derived from surface electromyographic (EMG) 29 interference signals. This study used intramuscular coherence to investigate the correlation between 30 MU discharges in the first dorsal interosseous muscle during and immediately following a 31 submaximal fatiguing contraction, and after rest. Coherence between composite MU spike trains, 32 derived from decomposed surface EMG, were examined in the delta (1-4 Hz), alpha (8-12 Hz), beta 33 (15-30 Hz) and gamma (30-60 Hz) band frequency ranges.

A significant increase in MU coherence was observed in the delta, alpha and beta frequency bands postfatigue. In addition, wavelet coherence revealed a tendency for delta, alpha and beta-band coherence to increase during the fatiguing contraction, with subjects exhibiting low initial coherence values displaying the greatest relative increase. This was accompanied by an increase in MU shortterm synchronization and a decline in mean firing rate of the majority of MUs detected during the sustained contraction.

A model of the motoneuron pool and surface EMG was used to investigate factors influencing the
coherence estimate. Simulation results indicated that changes in motoneuron inhibition and firing
rates alone could not directly account for increased beta-band coherence postfatigue. The observed
increase is, therefore, more likely to arise from an increase in the strength of correlated inputs to
MUs as the muscle fatigues.

45 Key words: motor unit coherence, isometric fatigue, intramuscular coherence, beta-band
46 coherence, short-term synchronization

47 **INTRODUCTION**

48 As muscle fatigue progresses, a number of adaptations develop within the central and peripheral 49 nervous system, several of which may serve as compensatory or protective mechanisms. These 50 include alterations in motor unit (MU) recruitment and firing rate (McManus et al. 2015a), changes 51 in reflex inputs from metabolically and mechanically sensitive muscle afferents (Macefield et al. 52 1991), and a progressive reduction in the ability to voluntarily activate the muscle with suboptimal 53 drive from the motor cortex (Gandevia 2001). In addition to these more well-established changes, it 54 is commonly suggested that fatigue also alters the degree of synchronization between the firing 55 times of simultaneously active motor units. Recent studies have added weight to this hypothesis, 56 reporting evidence of a fatigue-induced increase in synchronized motor unit firings using indirect 57 estimates of synchronization derived from surface EMG interference signals (Beretta-Piccoli et al. 58 2015; Holtermann et al. 2009; Talebinejad et al. 2010; Webber et al. 1995). The observed 59 synchronization of motor unit firing trains can be modulated in specific frequency ranges, including 60 the delta (1-4 Hz), alpha (8-12 Hz), beta (15-30 Hz) and gamma (30-60 Hz) frequency bands. Each 61 type of synchrony is purported to have distinct origins, with beta-band coherence of particular 62 interest, as it is believed to reflect information on oscillatory cortical and sub-cortical processes, and 63 has been shown to be directly correlated with short-term MU synchronization (Lowery et al. 2007). 64 Despite indications of increased MU synchronization postfatigue, direct evidence of an increase in 65 either short-term synchronization or coherent MU firings in the beta frequency range has never 66 been shown.

Previous studies using intramuscular EMG have reported no change in MU synchronization with fatigue (Contessa et al. 2009; Nordstrom et al. 1990), with the exception of an early study which reported increased motor unit synchrony following a sustained, fatiguing maximal contraction in the biceps (Buchthal and Madsen 1950). However, in that study MUs were recorded after the recovery of muscle force, which makes it unclear whether the increase in MU synchronization was due to

72 fatigue, or could be attributed to exercise-induced muscle damage (Dartnall et al. 2008). The 73 conflicting results obtained from intramuscular EMG studies may arise from the relatively low 74 number of motor units detected. This could also explain why methods based on non-linear analysis 75 of the surface EMG signal, which captures a larger representative sample of MU activity, have 76 consistently inferred that MU synchronization increases with fatigue (Beretta-Piccoli et al. 2015; 77 Holtermann et al. 2009; Talebinejad et al. 2010; Webber et al. 1995). Analysis of a greater number of 78 motor units spike trains using surface EMG decomposition techniques has the potential to enhance 79 the detection of correlated MU discharges.

80 Several recent studies have shown a fatigue-induced increase in intermuscular beta coherence 81 between surface EMG of synergistic index finger flexor muscles (Kattla and Lowery 2010), knee 82 extensor muscles (Chang et al. 2012), antagonistic elbow muscles (Wang et al. 2015) and during 83 three-digit grasping (Danna-Dos Santos et al. 2010). Furthermore, increased beta-band coherence 84 was observed between cortical neuron activity and EMG recordings following sustained maximal 85 (Tecchio et al. 2006) and submaximal fatiguing contractions (Ushiyama et al. 2011). Though 86 increases in beta frequency corticomuscular and intermuscular coherence postfatigue have been 87 reported, direct evidence of a similar change in coherent MU discharges within the same muscle has 88 not been shown. The aim of this study was to examine alterations in MU coherence during and after 89 a sustained submaximal fatiguing contraction in the first dorsal interosseous. To do this, a large 90 population of motor unit spike trains, decomposed from the surface EMG signal, were examined. 91 Coherence between groups of simultaneously active motor units was then calculated across a range 92 of frequency bands, before, during, and directly after the fatiguing contraction, and again following a 93 rest period. In addition, the temporal evolution of synchronized motor unit firing was investigated 94 over the course of the fatiguing contraction using wavelet coherence. Finally, model simulations 95 were used to explore whether changes in mean motor unit firing rates, or alterations in the direct 96 inhibition of motoneurons could account for the changes in coherence observed.

97 Direct evidence of an increase in short-term MU synchronization and correlated MU firings in the 98 beta-band range during fatigue within a single muscle has been presented for the first time in this 99 study. An increase in delta-band coherence, which is equivalent to the "common drive" modulation 100 of motor unit firing rates (Myers et al. 2004), and alpha-band coherence were also reported both 101 during the sustained contraction and postfatigue. The increase in delta-band coherence was 102 correlated with increases in force variability. A progressive decrease in motor unit mean firing rates 103 was observed during the fatiguing contraction, however, model simulations indicated that changes 104 in firing rates alone were unlikely to account for the increase in coherence postfatigue. Preliminary 105 results from this study were presented at the 7th Annual International IEEE EMBS Conference on 106 Neural Engineering (McManus et al. 2015b).

107 METHODS

108 Experimental Procedure

109 Written informed consent and ethical approval was obtained for fifteen subjects (8 female,) to 110 examine EMG activity of the FDI muscle during isometric abduction of the right index finger. Details of the experimental procedure have been reported previously in McManus et al. (2015a). Briefly, 111 112 subjects performed a series of six isometric voluntary contractions prefatigue, the force trajectory 113 contained a 3 s quiescent period for baseline noise calculation, an up-ramp increasing at 10% 114 maximum voluntary contraction (MVC) per second, a constant force of 20% MVC for 10 s, a down-115 ramp decreasing at 10% MVC/s, and a final 3 s quiescent period. After the six prefatigue trials, a 116 sustained isometric contraction was performed at 30% MVC until task failure, defined as the point at 117 which the subject's force dropped 10% below the required output for 5 or more seconds. Additional 118 verbal encouragement was provided during the contraction. A single MVC was performed directly 119 following task failure, followed by six 10 s contractions at 20% MVC with no rest period between 120 trials to minimize recovery. Subjects were then allowed a 10 minute recovery period before a series 121 of four more 10 s contractions at 20% MVC.

122 Data Analysis – Motor unit acceptance

123 Discriminable MUs were extracted from the surface EMG recorded using the decomposition 124 algorithms described in Nawab et al. (2010) (Delsys, version 4.1.1.0). For each identified MU, the 125 output of the algorithm consisted of MU firing times and 4 motor unit action potential (MUAP) 126 waveforms corresponding to 4 pairs of electrode channels. The identified firing times for each MU 127 were used to spike trigger average (STA) the surface EMG signal on each channel, resulting in 4 128 representative STA MUAP estimates for each MU. Two separate reliability tests were performed to 129 determine which decomposed MUs would be retained for further analysis, using the procedure 130 outlined in Hu et al. (2013). To quantify the variation of the STA MUAP over time, the coefficient of 131 variation was calculated for the peak-to-peak amplitude of the MUAP templates. The maximum 132 linear correlation coefficient between the STA estimate (calculated over the entire trial duration) 133 and the decomposition-estimated templates was also computed. MUs with an average correlation 134 coefficient (between the STA MUAP estimate and the decomposition MUAP template) > 0.7 and the 135 coefficient of variation of the peak-to-peak amplitude < 0.3 across all four channels were selected 136 for further analysis.

137 In the present study, the MUs identified by the decomposition algorithm during the fatiguing 138 contraction were additionally required to have a correlation coefficient (between the STA MUAP 139 template and the decomposition MU template and between each consecutive STA MUAP template 140 and the average STA MUAP template) > 0.8 and a peak-to-peak MUAP amplitude variation < 0.2 141 (both between consecutive STA MUAP templates and across all STA MUAP templates), on a 142 minimum of two channels to be selected for further analysis. A 400 ms Hanning window filter was 143 applied to the firing time data to analyze trends in MU mean firing times over the course of the 144 fatiguing contraction. The change in firing rate was examined for each motor unit by fitting a least-145 squares regression line to the mean firing rate data.

146

147 Data Analysis – Motor unit coherence, wavelet coherence and short-term synchronization

148 The number of MU spike trains used for the coherence analysis was chosen to be the maximum 149 number of MU spike trains available across all accepted trials and conditions for each subject. This 150 ensured that an equal sample of MU spike trains were analyzed within each condition. For trials that 151 contained more than the chosen number of motor units for that subject, motor unit spike trains were selected randomly for further analysis. The spike trains from multiple trials were pooled 152 153 together for each condition, with the same number of trials analyzed per condition. The pooled 154 motor unit trains were then divided into two groups, and the firing instances in each group were 155 summed to obtain two composite spike trains, Figure 1. The composite spike train method has been 156 previously applied to examine corticomuscular coherence and low frequency (<10 Hz) intramuscular 157 coherence during fatigue among a small number of subjects (Castronovo et al. 2015). A pair of 158 composite spike trains was obtained for every available combination of two groups from the pooled 159 MUs. For each subject, the number of paired combinations of composite trains analyzed was 160 constant across prefatigue, postfatigue and recovery conditions.

161 Figure 1

162 The magnitude squared coherence, $C_{xy}(f)$, was calculated for each pair of composite spike trains, x(t)163 and y(t), as a function of their power spectral densities, $P_{xx}(f)$ and $P_{yy}(f)$, and cross power spectral 164 density, $P_{xy}(f)$.

165
$$C_{xy}(f) = \frac{|P_{xy}(f)|^2}{P_{xx}(f)P_{yy}(f)}$$
(1)

The level at which the magnitude squared coherence was considered significant for overlapping windows with 75% overlap was calculated at the 0.05 significance level (Terry and Griffin 2008). The coherence in each frequency band was estimated as the integral of the magnitude-squared coherence above the significance level, for the delta (1-4 Hz), alpha (8-12 Hz), beta (15-30 Hz) and gamma (30-60 Hz) frequency bands. The coherence was estimated for three conditions, prefatigue,
postfatigue and following the recovery period.

Coherence was estimated for each combination of composite MU trains. The prefatigue coherence estimates were standardized to have zero mean and unit variance, Figure 4. Postfatigue and recovery coherence estimates were then scaled using the prefatigue mean and variance for that subject. Fourier based coherence was used for the short duration contractions pre- and postfatigue, which were assumed to be stationary.

For the longer, non-stationary fatiguing contractions, wavelet coherence analysis was used to examine the temporal evolution of the intramuscular coherence (Lachaux et al. 2002). The wavelet transform, $W_x(b, s)$, of a signal x(u) is given by the convolution of the signal with a wavelet function, where b and s are the time shift and scale respectively. For this study, the Morlet waveform $\Psi_{s,b}(u)$ was chosen as it has both oscillatory features and is complex valued. Similar to Fourier based coherence, the wavelet coherence WCo(t, f) at a time t and frequency f between two signals x(t)and y(t) is defined by

$$WCo(t,f) = \frac{|SW_{xy}(t,f)|}{[SW_{xx}(t,f).SW_{yy}(t,f)]^{1/2}}$$
(2)

185 where $SW_{xy}(t, f)$ is the wavelet cross-spectrum between x(t) and y(t) and $SW_{xx}(t, f)$ and $SW_{yy}(t, f)$ the 186 auto-spectra of the two signals. In the wavelet coherence method, the length of the integration 187 window decreases with increasing frequency, which improves the temporal resolution of the 188 coherence estimate for higher frequencies. The number of cycles of the wavelet (n_{co} = 10) and the 189 number of cycles contained within the integration window (n_{cy} = 40) were chosen to focus on the 190 change in beta-band wavelet coherence. Delta-band coherence was analyzed separately and the 191 number of cycles of the wavelet was changed to improve the resolution in this frequency band (n_{co} = 192 1). Confidence levels for the detection of significant coherence were calculated for these values of 193 n_{co} and n_{cy} using surrogate white noise signals to compute the statistical thresholds (Lachaux et al. 194 2002). Wavelet coherence was used to examine the coherence between composite MU spike trains

195 over the fatiguing contraction. Each subject was required to have a minimum number of 8 motor 196 units pass the acceptance criteria to be used in the wavelet coherence analysis. For subjects with a 197 large number of motor units 100 combinations were randomly chosen for the coherence estimate. 198 For each subject, the integral of the coherence in the alpha, beta and gamma frequency bands was 199 calculated at each 1 ms time step over the course of the fatiguing contraction. The change in 200 coherence during the fatiguing contraction was examined for each subject by fitting a least-squares 201 regression line to the integral of the coherence in each frequency band against the percentage of 202 time to task failure, and using the equation of the line to calculate the estimates for the initial and 203 final coherence values. The percentage change in coherence in each frequency band was compared 204 to the percentage change in the coefficient of variation of the force trace, calculated during the first 205 and the last 10 seconds of the fatiguing contraction.

206 In the time-domain, short-term motor unit synchronization was quantified using the synchronization 207 index (SI) (De Luca et al., 1993). Cross-interval histograms were constructed between pulse trains 208 representing the firing times of pairs of motor units, for each possible pair of motor units. The cross-209 interval histogram was constructed by calculating the first order, forward and backward recurrence 210 times of the alternate motor unit with respect to the reference unit. The peak in the cross-interval 211 histogram was determined by locating bins within 6 ms of the zero time-lag, for which the total 212 number of occurrences lay above the mean number of occurrences at the 95% significance level. SI, 213 the percentage of synchronized firings in excess of what would be expected due to chance, was 214 defined as the ratio between the total number of firings within the peak in excess of the mean, and 215 half the total area under the cross-interval histogram. The synchronization between motor unit pairs 216 was calculated for the first and second half of each fatiguing contraction.

217 Model Simulation

A model of the motoneuron pool, surface EMG signal and force output of first dorsal interosseous
muscle was used to examine the degree to which synchronization and coherence between the

motor unit discharge times is affected by the strength of common pre-synaptic inputs to the
 motoneuron pool, and possible additional factors, including variations in mean motor unit firing rate
 and the introduction of a common inhibitory input.

The model was designed to produce motor unit activation patterns qualitatively similar to those recorded experimentally. The force generated by the model was continuously compared to a target force, and adjusted based on the difference between the two to emulate the experimental conditions in which a subject tracks a target force trajectory. The model of the motoneuron pool was based on the model described by Lowery and Erim (2005) and was comprised of 100 motoneurons, simulated using a single compartment threshold-crossing model (Powers 1993). Each motoneuron received three inputs: a constant activation current, and a common modulation or oscillatory

230 current, and an independent membrane noise voltage (Lowery and Erim 2005).

231 The motoneuron pool model was coupled to a model of the surface EMG signal based on that 232 described in Lowery et al. (2000) and adapted for the first dorsal interosseous muscle. The muscle 233 was assumed to be trapezoidal in shape with a width of 35 mm, height of 5 mm, and length of 11.5 234 mm on the medial side extending to 35 mm on the lateral side (Infantolino and Challis 2010). 235 Coordinates within the muscle cross-section for both MUs and fibers within each MU were randomly 236 generated for one hundred motor units using Sobol distributions. The number of fibers assigned to 237 each motor unit was assumed to increase linearly with recruitment threshold from 50 to 360 238 (Feinstein et al. 1955). Fiber diameters (0.052 – 0.068 mm, Freund (1983)) also increased linearly with motor unit size, and a muscle fiber density of 20 fibers per mm² was assumed (Buchthal et al. 239 1957). All muscle fibers were orientated with a pennation angle of 50° (Infantolino and Challis 2010). 240 241 The electrode was modelled as 5 point electrodes located at each of the corners and the center of a 242 5×5 mm square, based on the dimensions of the Delsys electrode used experimentally. It was 243 located 15 mm from the proximal end of the muscle and 11 mm from the lateral side of the muscle, 244 3.5 mm above most superficial muscle fibers, and rotated 20° with respect to the fiber direction to

245 replicate experimental placement of the electrode. The muscle fibers were located within 246 homogeneous cylindrically anisotropic muscle tissue, with radial and axial conductivities of 0.063 247 and 0.33 S/m, respectively. The single fiber action potential detected when each muscle fiber was 248 stimulated was calculated using an infinite volume conductor model for anisotropic muscle (Lowery 249 et al. 2000). The single fiber action potentials generated by all of the fibers in each motor unit 250 summed linearly to yield the MUAP. The common input was simulated by band-pass filtering a 251 random Gaussian signal between 9-25 Hz using a second order Butterworth filter, chosen to 252 generate motor unit coherence spectra qualitatively similar to those recorded experimentally. The 253 amplitude of the signal was varied between 0-0.6 mV to simulate changing levels of shared pre-254 synaptic input in the beta-band.

255 To investigate whether a net inhibition of motoneurons could affect the level of motor unit 256 coherence, inhibition to the motoneuron pool was simulated as follows. Firing of a motoneuron 257 resulted in the generation of an inhibitory post-synaptic potential (IPSP) at the input to that 258 motoneuron, and to its two neighboring motoneurons as defined in terms of the motoneuron 259 recruitment order. To replicate the changes in firing rate and recruitment that were observed 260 experimentally, a weighting function was assigned to the amplitude of the IPSPs such that the 261 earliest recruited motoneurons received the greatest level of inhibition. IPSPs were simulated as an 262 alpha function with a rise time of 5.5 ms and half-width of 18.5 ms, and ranged in amplitude from 5-263 60 μV according to a weighted sigmoidal function, based upon experimental data of Renshaw 264 inhibition (Hamm et al. 1987).

Spike triggered averaging was performed on the simulated EMG data to characterize the MU waveform, using the same acceptance criteria as in the experimental data. To estimate MU coherence from the motoneuron model, 26 MUs were randomly chosen from the pool and coherence was estimated for the composite spike trains for the first 10,000 combinations of two groups, as described previously for the experimental data.

270

271 Statistical Analysis

272

A repeated measure analysis of variance was conducted to compare motor unit mean firing rate 273 274 (MFR) and coherence in each frequency band prefatigue, postfatigue, and following the recovery 275 period. Mauchly's Test of Sphericity was implemented to check the assumption of sphericity, and if 276 violated, a Greenhouse-Geisser correction was applied. Post hoc tests to examine pairwise 277 differences between conditions were conducted using the Fisher's Least Significant Difference test. 278 The relationship between initial motor unit firing rate (the intercept of the regression line) and the 279 change in the motor unit firing rate over the course of the fatiguing contraction (slope of the line) 280 was examined using a Pearson product-moment correlation. The t-statistic was used to test for the 281 significance of the slope. The relationship between the change in motor unit mean firing rate and 282 the change in beta-band coherence was investigated using a Spearman's rank-order non-parametric 283 correlation. A Spearman's correlation was also used to assess the relationship between the initial 284 coherence and the percentage change in coherence over the course of the fatiguing contraction in 285 the delta, alpha, beta and gamma-bands, and the correlation between the percentage change in 286 coherence and the percentage change in the coefficient of variation of the force. Differences in the 287 median SI, between the first and second half of the fatiguing contraction, were tested using a paired 288 Wilcoxon signed rank test.

289 **Results**

290 Maximum voluntary force was significantly reduced (50.4 ± 11 N to 26 ± 12 N, p < .001) following the 291 sustained isometric fatiguing contraction (248 ± 174 seconds). MVC failed to recover after the period 292 of rest and remained significantly depressed (39.5 ± 15.9 N, p < .001), though still higher than 293 directly postfatigue (p < .005). The average number of motor units detected per trial was 17.6 ± 3 294 MUs prefatigue, 15.5 ± 3.5 postfatigue, and 17.2 ± 3.8 after recovery, with $80 \pm 10\%$ of MUs 295 accepted for further analysis. During the fatiguing contraction, 11 of 15 subjects had the minimum of

- 296 8 accepted MUs required to be included in the wavelet coherence analysis. For these subjects, an
- average of 70 ± 11 MUs were identified by the decomposition algorithm, but due to more stringent
- criteria applied to the sustained fatiguing contraction, just 27.7 ± 14 % of these MUs were accepted.
- 299 Motor unit properties pre and postfatigue
- 300 A small, though significant effect of fatigue on the MFR of the decomposed MUAPs was observed (F
- (2, 22) = 10.04, p < .001), Figure 2 (b). MU mean firing rates decreased significantly (p < .005) from
- 302 prefatigue to postfatigue conditions (10.8 ± 1.2 Hz vs. 10.0 ± 1.4 Hz, respectively). After the recovery
- 303 period MU firing rates increased (11.2 ± 1.2 Hz, p<.001), and were not statistically different from
- discharge rates observed before fatigue (p = .15).

305 Figure 2

The coherence between composite MU pulse trains is displayed in Figure 3, prefatigue, postfatigue and following a recovery period, for a representative subject. A significant increase in MU coherence was observed in the delta (0.64 ± 0.98 to 4.14 ± 2.4 , p < .0001), alpha (6.2 ± 3.6 to 10.8 ± 5 , p < .0001) and beta (13.9 ± 7.3 to 25.6 ± 10.2 , p < .0001) frequency bands postfatigue. The mean and standard deviation of the standardized coherence values across all motor unit combinations are presented in Figure 4 for the (a) delta, (b) alpha, (c) beta and (d) gamma frequency bands.

312 Figure 3

- 313 Following the recovery period, coherence decreased significantly and was not significantly different
- from the estimated coherence prefatigue for the delta, alpha and beta frequency bands (p = .3, p =
- .9 and p = .42, respectively). The changes in gamma frequency coherence did not exhibit a
- statistically significant effect of condition (F (1.29, 18) = 3.1, p = .087), Figure 4 (d).
- 317 Figure 4
- 318

319 Fatiguing Contraction – MU Mean Firing Rate

320 To investigate the motor unit MFR changes in more detail, MU mean firing rate were analyzed for 11 321 subjects over the course of the fatiguing contraction, with an average of 16.9 ± 6.7 MUs per subject 322 and initial MFR of 12.8 ± 2.8 Hz. Across all subjects, there was a weak tendency for motor units with 323 higher firing rates to exhibit a decrease in discharge rate during the fatiguing contraction, and those 324 with lower firing rates to increase their MFR (r = -0.27, p < .001). For 6 of the 11 subjects there was a 325 significant, strong negative correlation between initial motor unit firing rate and the change in the 326 motor unit firing rate over the course of the contraction ($r=-0.7\pm0.09$), Figure 5 (a). Over all subjects, 327 a weak correlation between the two variables was still present (r=-0.27, p<0.001), Figure 5 (b). The 328 majority of MUs (74.4 %) exhibited a decline in MFR over the course of the fatiguing contraction, 329 though the average magnitude of the decline was small, $-10 \pm 9.4\%$, and there was a large variation 330 in the magnitude of MU MFR changes per subject. In the remaining motor units, the MFR increased 331 by an average of 14.7 ± 27.5%. Motor units recruited as the contraction progressed exhibited both 332 increases and decreases in their discharge rates.

333 Figure 5

334 Fatiguing Contraction – MU Coherence and Synchronization

335 Wavelet coherence and time domain synchronization between motor unit firing times were analyzed 336 for the same 11 subjects during the fatiguing contraction. The majority of subjects exhibited an 337 increase in coherence in the delta, alpha and beta-band over the course of the fatiguing contraction, 338 with median regression slopes of 0.004 \pm 0.006, 0.012 \pm 0.01 and 0.014 \pm 0.03 respectively. Motor 339 unit firing rates and the corresponding motor unit wavelet coherence during the fatiguing 340 contraction are shown for a representative subject in Figure 6 (a) & (b). In the gamma frequency 341 band only 5 subjects showed an increase in coherence, with positive regression slopes significantly 342 different to zero. There was a significant negative correlation between the initial value for delta, 343 alpha and beta-band coherence and the percentage change in coherence within that band over the

fatiguing contraction (r = -0.7, p = .019, r = -0.55, p < .01 and r = -0.71, p = .018, respectively), Figure 7 (a). However, this correlation was not significant for the gamma-band (r = -0.59, p = .055). No significant relationship was observed between the magnitude of the change in motor unit mean firing rates and the change in beta-band coherence ($r_s = -0.48$, p = .13), nor between the average MU firing rate and the strength of the beta coherence observed ($r_s = 0.4$, p = .2).

349 Figure 6

350 Synchronization was quantified only during the sustained fatiguing contraction, as the pre- and

351 postfatigue trials were not sufficiently long to obtain an accurate estimate. The percentage of MU

pairs that displayed significant synchronization was 88.7% and 92.9% in the first and second half of

the fatiguing contraction, respectively. In the second half of the contraction the mean

354 synchronization index of the MUs that displayed significant synchronization increased ($11 \pm 3 \%$ to

 $15 \pm 4.6 \%$, p < .001), Figure 7 (b). There was a significant correlation between the coefficient of

variation of the force and the percentage change in coherence within the delta ($r_s = 0.76$, p < .01),

Figure 7 (c), but not the alpha-band or beta frequency bands ($r_s = 0.5$, p = .11 and $r_s = 0.44$, p = .18,

358 respectively).

359 Figure 7

360 Simulation Results

Using the model, the effect of common or shared neural inputs to the motoneuron pool, changes in motor unit mean firing rate and inhibition of motoneurons were each examined to identify the factors that could contribute to the experimentally observed increase in beta band coherence. The magnitude of the common component of the input signal to the motoneuron pool was first increased to examine the effect on the beta coherence between MU firings, Figure 8 (a) & (b). The integral of the significant coherence in the beta-band in the model increased when a common input

amplitude of 0.4 mV was applied to the motoneuron pool, and increased further at a common input
amplitude of 0.6 mV, Figure 9 (b).

To examine the effect of MU mean firing rate on the coherence estimate, the median beta-band
coherence was examined at 3 different firing rates, with a shared beta-band input of 0.6 mV, Figure
8 (c) & (d). Increasing the mean firing rate of the motoneuron population from 11.3±3 Hz to 12.1±3
Hz resulted in an increase in the median coherence from 6.4 ± 1.4 to 8.6 ± 1.3. A further increase in
MFR from 12.1±3 Hz to 13.2±3 Hz increased the median coherence to 8.97±1.5.

374 Figure 8

- 375 Finally, to examine the possible effect of motoneuron inhibition on beta coherence, coherence was
- 376 estimated after the introduction of inhibition in the presence of a common input of amplitude 0.6
- mV (and a resulting reduction in MU MFR from 12.1±3 Hz to 10± 3 Hz), and were found to decrease
- 378 from 8.6 \pm 1.5 to 6.9 \pm 1.5. When an increase in the magnitude of the common input to the
- 379 motoneuron pool (0.6 mV to 0.8 mV) and an inhibition-induced reduction in motor unit firing rates
- 380 (12.1±3 Hz to 11 ± 3 Hz) were simultaneously simulated, the median coherence displayed an
- increase similar to what was observed experimentally $(8.6 \pm 1.3 \text{ to } 15 \pm 1.4)$, Figure 9.

382 Figure 9

383 DISCUSSION

384 Since the appearance of grouped motor unit activity with muscle fatigue was first reported (Buchthal 385 and Madsen 1950), it has been widely accepted that an increase in the synchronization between the 386 firing times of simultaneously active motor units occurs with the onset of fatigue. However, while 387 estimates of MU synchronization inferred from the surface EMG interference signal support this 388 hypothesis (Beretta-Piccoli et al. 2015; Holtermann et al. 2009; Webber et al. 1995), direct evidence 389 of a fatigue-induced increase in short-term synchronization or beta-range oscillatory coupling 390 between the firing times of simultaneously active motor units within a single muscle has not yet 391 been shown. This study presents direct affirmation of an increase in beta-band MU coherence 392 postfatigue, within motor units of the same muscle, for the first time, Figure 4 (c). The increased 393 coherence postfatigue was preceded by increases in the beta-band MU coherence and short-term 394 MU synchronization over the course of the fatiguing contraction, Figure 6 (b) and Figure 7. Subjects 395 with high initial beta-band MU coherence showed little change in coherence during the fatiguing 396 contraction, possibly indicating a saturation effect, Figure 7 (a), whereby no further increase in 397 neural oscillatory activity is possible beyond a certain point. In addition, increases in delta and alpha-398 band coherence were observed both during the fatiguing contraction and directly postfatigue. After 399 10 minutes of recovery, there was no significant difference between the coherence estimates and 400 those obtained prefatigue, for any of the frequency bands.

This study extends the results of previous studies reporting a significant increase in beta-band
intermuscular coherence between surface EMG following isometric fatigue (Chang et al. 2012;
Danna-Dos Santos et al. 2010; Kattla and Lowery 2010; Wang et al. 2015). However, other studies
have reported no significant increase in beta-band EMG-EMG or motor unit coherence during
sustained fatiguing contractions in the elbow flexor muscles (Semmler et al. 2013) and in the tibialis
anterior muscle (Castronovo et al. 2015), respectively. Furthermore, although an increase in betaband corticomuscular coherence has been reported postfatigue in the extensor digitorum communis

408 (Tecchio et al. 2006) and the tibialis anterior (Ushiyama et al. 2011), a weakening of beta coherence 409 has also been reported during sustained (Yang et al. 2009) elbow flexion and in the flexor digitorum 410 profundus, but not flexor digitorum superficialis, following maximal, intermittent handgrip 411 contractions (Yang et al. 2010). These discrepancies highlight that the presence of correlated MU 412 firings in the beta-band is likely muscle specific and task dependent, and may relate to the weaker 413 contribution of the corticospinal pathway to proximal compared with distal muscles (Palmer and 414 Ashby 1992). Changes in intramuscular beta coherence may be a more accurate reflection of 415 underlying changes in the synchronous common inputs to the motoneuron pool than corresponding 416 alterations in inter-muscular coherence, as the motor unit spike trains used in the coherence 417 analysis were recorded within the same muscle, at the same force level. This may mitigate some of 418 the uncertainty in the synchronization estimate when comparing across muscles with different firing 419 characteristics, active at various force levels (Kline and De Luca 2015). Furthermore, MU coherence 420 estimates derived directly from MU spike trains limit sources of variability present in surface EMG 421 coherence that may arise from inter-subject differences in subcutaneous tissue and muscle 422 composition.

423 It remains unclear whether increased beta-band coherence has a functional role or whether it is 424 epiphenomenal in nature, reflecting underlying changes in cortical or other neural firing patterns. It 425 is possible that the increase in beta-band MU coherence and MU short-term synchronization 426 observed in this study may reflect higher attentional demands and a greater amount of motor-427 related neural processing as fatigue progresses (Schmied et al. 2000). A decrease in the magnitude 428 of oscillatory inputs to the motoneuron pool has been shown to cause more variability in motor unit 429 firing trains, and decrease the number of motoneurons recruited to the contraction (Parkis et al. 430 2003). Therefore, it is also possible that an increase in synchronized neural inputs may serve to 431 overcome reduced motoneuron excitability and increase recruitment after fatigue (Andersen et al. 432 2003).

433 The increase in correlated MU discharges in the delta and alpha frequency band observed in this 434 study has been previously reported following sustained submaximal fatiguing contractions in the 435 tibialis anterior muscle (Castronovo et al. 2015) and in elbow flexor muscles (Semmler et al. 2013). 436 Both synchronization and MU coherence (< 10 Hz) have been found to increase following muscle 437 damage induced by eccentric exercise (Dartnall et al. 2008). The restoration of low-frequency 438 coherence to prefatigue values after the rest period, however, suggests that muscle damage was not 439 a major factor in the coherence increase directly postfatigue. The increase in coherence MU 440 discharges in the delta-band range was observed in the present study was significantly correlated 441 with the coefficient of variation of the force trace, Figure 7 (c). Contessa et al. (2009) observed an 442 increase in the common drive during fatigue, defined in terms of the cross-correlation between MU 443 firing rates and analogous to MU coherence in the 0-4 Hz range (Myers et al. 2004), which was 444 similarly correlated with the force variability. Alpha and beta-band coherence were not significantly 445 correlated with force variability, which may be expected, as simulation studies have shown that 446 mean firing rate fluctuations in the 1-4 Hz range have the greatest relative effect on force variability 447 due to the low-pass filtering effect of the motor unit twitch response (Lowery and Erim 2005). Delta-448 band coherence may be influenced by recruitment via feedback from muscle spindles, and possibly 449 the Golgi tendon organs (De Luca et al. 2009). Synchrony in the alpha-band is also known to be 450 influenced by the modulation of muscle spindle activity in mechanical and reflex loop resonances 451 (Erimaki and Christakos 2008).

452

453 Firing Rate

454

The mean firing rates of the motor unit population decreased immediately postfatigue, and 455 456 recovered following the 10 minute rest period, Figure 2. In addition there was a reduction in the 457 firing rates of the majority of motor units (75%) during the sustained fatiguing contraction, Figure 5 458 and Figure 6 (a). This mirrors the results of previous studies that have shown a reduction in MU firing 459 rate during intermittent and constant force submaximal isometric fatiguing contractions (Duchateau 460 et al. 2002; Garland et al. 1994). Garland et al. (1994) observed changes in the discharge rates of 461 single motor units in the biceps brachii, held just above their threshold of recruitment force. In the 462 present study, changes in discharge rate in a large sample of motor units, concurrently active at the 463 same relative force level, were examined for the first time during a sustained, fatiguing contraction. 464 Though relatively small, the magnitude of the changes in MU MFR during and postfatigue, were 465 comparable to the modest increase in interpulse interval reported in the biceps brachii (Garland et 466 al. 1994). There is evidence that metabolically and mechanically sensitive group III and IV afferents 467 are in part responsible for the decline in motoneuron discharge rate in fatiguing contractions at 468 maximal force levels (Bigland-Ritchie et al. 1986; Garland and McComas 1990), acting at the spinal 469 and/or the supraspinal level (Gandevia 2001). However, a withdrawal of Ia facilitation from muscle 470 spindles (Macefield et al. 1991) or intrinsic motoneuron properties (Spielmann et al. 1993) could also 471 contribute. The alterations in MU coherence postfatigue and during recovery followed a similar time 472 course to the changes observed in the motor unit firing rate and action potential duration presented 473 in McManus et al. (2015a). Sensory ascending pathways can modulate the strength of beta-range 474 corticomuscular coupling (McClelland et al. 2012), though the contribution of various afferent 475 groups are not yet clear (Schmied et al. 2014). It is therefore possible that both the magnitude of 476 MU firing rates and the degree of synchronized MU firings could be affected by increased afferent 477 feedback in response to ionic and metabolic changes within the muscle.

478

479 Model Simulation

480

The increase in MU coherence immediately postfatigue and during the sustained fatiguing 481 482 contraction is likely to be multifactorial, but the relative contribution of each factor is not clear. 483 Model simulation was used to investigate how alterations in mean MU firing rate and the 484 introduction of inhibitory feedback to the motoneuron pool can affect the coherence estimate 485 obtained. The simulation studies, however, indicated that neither changes in mean motor unit firing 486 rate of the magnitude observed experimentally, nor simulated inhibition of the motoneuron pool 487 could individually account for the change in coherence observed, Figure 8 (c) & (d). 488 In the model, when the mean firing rate increased towards the median frequency of the common 489 input an increase in the estimated coherence was observed without any corresponding increase in 490 the amplitude of the shared input, Figure 8, as previously demonstrated in simulation studies 491 (Lowery et al. 2007). The efficacy of a shared oscillatory inputs in eliciting synchronized motoneuron 492 firings increases when the motoneuron firing rates and the frequency of the oscillatory input are 493 similar (Lowery and Erim 2005). In the experimental data, however, the observed reduction in motor 494 unit mean firing rates is unlikely to have affected the coherence estimate, due to the already low 495 average values (10.8 ± 1.2 Hz). The introduction of inhibition in the model, in the presence of a 496 common correlated input to the motoneuron pool, decreased the coherence estimate by 20%. An 497 increase in the ratio between the independent components of the synaptic input to the motoneuron 498 pool, in this case direct inhibition, and the common correlated inputs may be expected to reduce 499 motor unit coherence estimates. However, in experimental conditions, the possibility that afferent 500 inputs indirectly enhance the coherence estimate via supraspinal centres cannot be ruled out 501 (Gandevia 2001).

In contrast to the moderate differences in the coherence estimate induced by alterations in MU
 mean firing rates and the introduction of inhibition, a large increase in the coherence estimate was
 observed by raising the amplitude of the common input shared across the motoneuron pool. The

magnitude of the change in the coherence spectrum observed experimentally (84%) could be
approximated by increasing the amplitude of the shared beta input (74%), while fatigue-induced
reductions in MU MFR were replicated with simulated inhibition, Figure 9.

508 Study Limitations

509

510 In this study, decomposition of the surface EMG signal was used to obtain the spike trains 511 representing the firing times of individual motor units within a single muscle. The accuracy of the 512 results depends on the accuracy of the decomposition method. To ensure the reliability of the data, 513 the stability of the MUAP waveform was assessed during the pre and postfatigue contractions, and 514 during the sustained fatiguing task, to select the most reliable motor unit firing times for further 515 analysis (Hu et al. 2013). Despite the stringent criteria applied, particularly for the MU trains 516 decomposed from the long fatiguing contraction, there may be inaccuracies in individual firing times 517 present in the spike trains. Frequency domain MU coherence analysis has been shown to be less 518 sensitive to motor unit firing rates than traditional synchronization-based measures of time domain 519 correlation (Lowery et al. 2007), which may make it more robust to the presence of some firing time 520 inaccuracies. In addition, the use of composite spike trains may provide a more aggregate measure 521 of the overall coherence in the motor unit sample and mitigate the influence of minor sources of 522 error. The strict acceptance criteria applied to the stability of the MU waveform may have rejected 523 an undesirably large number of reliable MUs in this study and introduced a possible sampling bias. 524 The large inter-subject variability associated with coherence estimation is a potential limitation of

the coherence analysis. The variability in the coherence estimates obtained for each individual may be due to limitations of coherence as an accurate reflection of shared motoneuronal inputs, intrinsic differences in corticomuscular coupling among individuals, or a combination of both. As previously discussed, the interaction between firing rate and coherence may also skew the coherence estimate in some subjects, for example, when the firing rate of the detected MUs is close to the frequency of the observed coherence. Relatively more synchronous firing instances may also be detected if the

531 MU sample for a subject displays a particularly narrow range of firing rates (Kline and De Luca 2015). 532 Nevertheless, consistent results in terms of the direction of the change in coherence were observed 533 across all frequency bands, with all subjects showing an increase in coherence in the delta range 534 postfatigue, and 14 out of 15 subjects displaying an increase in the alpha and beta-band ranges.

535 Lastly, to investigate the effect of changing motor unit firing rates and increasing inhibitory inputs on 536 the MU coherence estimate, a simplified model of the motoneuron pool was used. As the respective 537 contribution, and distribution, of these inhibitory and excitatory inputs across the motoneuron pool 538 during fatigue are still unclear, the integrated effect of afferent activity was simplified as a net 539 inhibitory input, non-uniformly distributed over the motoneuron pool. Physiologically, no afferent 540 input reaches motoneurons exclusively by a monosynaptic path and combined interplay between 541 the many motoneuron inputs is complex (Gandevia 2001). However, these assumptions were made 542 in order to replicate the simultaneous decrease in motoneuron firing rates and continued motor unit 543 recruitment observed experimentally. It is possible that other forms of simulated inhibitory circuits 544 could enhance the motor unit coherence around the beta-band. Certain intrinsic properties of 545 motoneurons, such as persistent inward currents (Heckman et al. 2005), may have been altered 546 postfatigue but were not included in this model.

547 CONCLUSION

548

A significant increase was observed in motor unit coherence in the delta, alpha and beta-band ranges following a sustained, fatiguing contraction, which recovered following a period of rest. A progressive increase in delta, alpha and beta-band motor unit coherence was observed over the course of the fatiguing contraction, which was examined using wavelet coherence. The increase in motor unit coherence and short-term synchronization during fatigue were accompanied by a decline in the MFR of the majority of motor units, with larger reductions in MFR associated with higher initial MU firing rates in some subjects. Simulation results suggest that an increase in inhibitory

556 afferent activity postfatigue, and a resulting or independent reduction in motor unit MFR, cannot 557 account for the magnitude of the increase in beta-band coherence. The increase is, therefore, more 558 likely to arise from a corresponding increase in the correlated common input to the motoneuron 559 pool. Motor unit MFR and coherence recovered following rest, suggesting the possibility that both 560 are modulated by afferent feedback in response to fatigue-induced changes within the muscle. The 561 ability to infer information about oscillatory cortical and sub-cortical processes from the peripheral 562 signal gives a novel insight into the adaptations taking place in the central and peripheral nervous 563 system during fatigue.

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- 691

693 FIGURE CAPTIONS

- 694 Figure 1. Two sample groups of motor unit spike trains (a) and (b) pooled to form composite MU
- spike trains (c) and (d). The coherence between the two composite firing trains (c) and (d) was thenestimated.
- Figure 2: Probability density of MU MFR (a) for a single representative subject and (b) across allsubjects.
- 699 Figure 3. The highest coherence between composite MU spike trains observed across motor unit
- 700 combinations, prefatigue, postfatigue and following a recovery period for a representative subject
- 701 (with a 95% confidence interval).
- 702 Figure 4. The median and standard deviation of the standardized coherence values across all motor
- 703 unit combinations for the (a) common drive (1-4 Hz), (b) alpha (8-12 Hz), (c) beta (15-30 Hz) and (d)
- 704 gamma (30-60 Hz) frequency bands, *p < 0.001.
- Figure 5. The change in firing rate for each motor unit fatiguing contraction as a function of that
 unit's initial firing rate for (a) a single subject and (b) over all subjects, *p < 0.001.
- 707 Figure 6. (a) The force trace and time-varying mean firing rate of 8 motor units (obtained by low-pass
- 708 *filtering the impulse train with a Hanning window of 5 second duration) and (b) the median wavelet*
- 709 coherence between composite motor unit trains over the fatiguing contraction for the same subject.
- 710 Figure 7. (a) The relationship between the initial coherence in the alpha and beta-bands and the
- 711 percentage change in the integral of the wavelet coherence over the course of the fatiguing
- 712 contraction, (b) the median and standard deviation of the synchronization index across all subjects
- for the first and second half of the contraction (* p<0.001), and (c) the relationship between the
- 714 *percentage change in coherence and the percentage change in the coefficient of variation of the*
- 715 *force.*

- 716 Figure 8: (a) The MU coherence estimate with no common input to the motoneuron pool, a beta-
- 717 band input of magnitude 0.6 mV and 0.8 mV, with a median MFR of 12.2±3 Hz across the MU pool,
- 718 and (b) the median and standard deviation of the coherence estimates over all pairs of MU
- 719 composite trains. (c) The MU coherence estimate for varying motor unit mean firing rate and (d) the
- 720 median and standard deviation of the coherence estimates over all pairs of MU composite trains,
- 721 with a beta-band input of magnitude 0.6 mV for the 3 corresponding firing rates.
- 722 Figure 9: (a) The coherence spectrum for the pair of MU composite trains with the highest level of
- coherence with a beta-band input of magnitude 0.6 mV (prefatigue) and 0.8 mV with inhibition
- 724 (postfatigue) and (b) the median and standard deviation of the coherence estimates over all pairs of
- 725 *MU composite trains.*
- 726
- 727
- 728

729 FIGURES





731 Figure 1













741 Figure 4













750 Figure 7











