

 EXTRACTA MATHEMATICAE Vol. 27, Núm. 2, 301–308 (2012)

The Structure of a Class of Generalized Sasakian-Space-Forms

PRADIP MAJHI, U. C. DE

*Department of Pure Mathematics, University of Calcutta,
35 Ballygaunge Circular Road, Kolkata 700019, West Bengal, India
mpradipmajhi@gmail.com, uc_de@yahoo.com*

Presented by Manuel de León

Received February 14, 2012

Abstract: The object of the present paper is to study ξ -conformally flat and ϕ -conformally flat generalized Sasakian-space-forms.

Key words: ξ -conformally flat, ϕ -conformally flat, Sasakian manifold, Einstein manifold, η -Einstein manifold, conformally flat.

AMS *Subject Class.* (2010): 53C15, 53C25.

1. INTRODUCTION

The nature of a Riemannian manifold mostly depends on the curvature tensor R of the manifold. It is well known that the sectional curvatures of a manifold determine curvature tensor completely. A Riemannian manifold with constant sectional curvature c is known as real space-form and its curvature tensor is given by

$$R(X, Y)Z = c\{g(Y, Z)X - g(X, Z)Y\}.$$

A Sasakian manifold with constant ϕ -sectional curvature is a Sasakian-space-form and it has a specific form of its curvature tensor. Similar notion also holds for Kenmotsu and cosymplectic space-forms. In order to generalize such space-forms in a common frame P. Alegre, D.E. Blair and A. Carriazo introduced the notion of generalized Sasakian-space-forms in 2004 [1]. In this connection it should be mentioned that in 1989 Z. Olszak [13] studied generalized complex-space-forms and proved its existence. A generalized Sasakian-space-forms are defined as follows:

Given an almost contact metric manifold $M(\phi, \xi, \eta, g)$, we say that M is a generalized Sasakian-space-form if there exist three functions f_1, f_2, f_3 on M such that the curvature tensor R is given by

$$\begin{aligned}
R(X, Y)Z &= f_1\{g(Y, Z)X - g(X, Z)Y\} \\
&+ f_2\{g(X, \phi Z)\phi Y - g(Y, \phi Z)\phi X + 2g(X, \phi Y)\phi Z\} \\
&+ f_3\{\eta(X)\eta(Z)Y - \eta(Y)\eta(Z)X \\
&+ g(X, Z)\eta(Y)\xi - g(Y, Z)\eta(X)\xi\}.
\end{aligned} \tag{1.1}$$

for any vector fields X, Y, Z on M . In such a case we denote the manifold as $M(f_1, f_2, f_3)$. In [1] the authors cited several examples of generalized Sasakian-space-forms. If $f_1 = \frac{c+3}{4}$, $f_2 = \frac{c-1}{4}$ and $f_3 = \frac{c-1}{4}$, then a generalized Sasakian-space-form with Sasakian structure becomes Sasakian-space-form. In [12], U. K. Kim studied conformally flat generalized Sasakian-space-forms and locally symmetric generalized Sasakian-space-forms. He proved that some geometric properties of generalized Sasakian-space-form depend on the nature of the functions f_1, f_2 and f_3 . Generalized Sasakian-space-forms have also been studied in the papers [2], [3], [4], [5], [9], [10], [12] and [13].

Let M be an almost contact metric manifold equipped with an almost contact metric structure (ϕ, ξ, η, g) . At each point $p \in M$, decompose the tangent space T_pM into direct sum $T_pM = \phi(T_pM) \oplus \{\xi_p\}$, where $\{\xi_p\}$ is the 1-dimensional linear subspace of T_pM generated by ξ_p . Thus the conformal curvature tensor C is a map

$$C : T_pM \times T_pM \times T_pM \longrightarrow \phi(T_pM) \oplus \{\xi_p\}, \quad p \in M.$$

It may be natural to consider the following particular cases:

- (1) $C : T_p(M) \times T_p(M) \times T_p(M) \longrightarrow \{\xi_p\}$, i.e, the projection of the image of C in $\phi(T_p(M))$ is zero.
- (2) $C : T_p(M) \times T_p(M) \times T_p(M) \longrightarrow \phi(T_p(M))$, i.e, the projection of the image of C in $\{\xi_p\}$ is zero. This condition is equivalent to

$$C(X, Y)\xi = 0. \tag{1.2}$$

- (3) $C : \phi(T_p(M)) \times \phi(T_p(M)) \times \phi(T_p(M)) \longrightarrow \{\xi_p\}$, i.e, when C is restricted to $\phi(T_p(M)) \times \phi(T_p(M)) \times \phi(T_p(M))$, the projection of the image of C in $\phi(T_p(M))$ is zero. This condition is equivalent to

$$\phi^2 C(\phi X, \phi Y)\phi Z = 0. \tag{1.3}$$

A generalized Sasakian-space-form satisfying (1.2) and (1.3) is called ξ -conformally flat and ϕ -conformally flat respectively. A K -contact manifold satisfying the cases (1), (2) and (3) is considered in [14], [15] and [16] respectively.

DEFINITION 1.1. A $(2n + 1)$ -dimensional generalized Sasakian-space-form is said to be ξ -conformally flat if

$$C(X, Y)\xi = 0, \quad (1.4)$$

where $X, Y \in T(M)$.

DEFINITION 1.2. A $(2n + 1)$ -dimensional generalized Sasakian-space-form is said to be ϕ -conformally flat if

$$g(C(\phi X, \phi Y)\phi Z, \phi W) = 0. \quad (1.5)$$

In [15], it is proved that a K -contact manifold is ξ -conformally flat if and only if it is an η -Einstein Sasakian manifold. In [11], De and Biswas ξ -conformally flat $N(k)$ -contact metric manifolds. A compact ϕ -conformally flat K -contact manifold with regular contact vector field has been studied in [16]. Moreover, in [6], Arslan, Murathan and Özgür studied ϕ -conformally flat (k, μ) -contact metric manifold. Motivated by the above studies, in this paper we study ξ -conformally flat and ϕ -conformally flat generalized Sasakian-space-forms.

The present paper is organized as follows:

After preliminaries in Section 3, we study ξ -conformally flat generalized Sasakian-space-forms and prove that a generalized Sasakian-space-form is always ξ -conformally flat. Section 4 deals with ϕ -conformally flat generalized Sasakian-space-forms and we prove that the space-form is ϕ -conformally flat if and only if $f_2 = 0$. As a consequence of the result we obtain some important corollaries.

2. PRELIMINARIES

In an almost contact metric manifold we have ([7], [8])

$$\phi^2(X) = -X + \eta(X)\xi, \quad \phi\xi = 0, \quad (2.1)$$

$$\eta(\xi) = 1, \quad g(X, \xi) = \eta(X), \quad \eta(\phi X) = 0, \quad (2.2)$$

$$g(\phi X, \phi Y) = g(X, Y) - \eta(X)\eta(Y), \quad (2.3)$$

$$g(\phi X, Y) = -g(X, \phi Y), \quad g(\phi X, X) = 0, \quad (2.4)$$

$$g(\phi X, \xi) = 0. \quad (2.5)$$

Again for a $(2n+1)$ -dimensional generalized Sasakian-space-form we have ([1])

$$S(X, Y) = (2nf_1 + 3f_2 - f_3)g(X, Y) - (3f_2 + (2n - 1)f_3)\eta(X)\eta(Y), \quad (2.6)$$

$$QX = (2nf_1 + 3f_2 - f_3)X - (3f_2 + (2n - 1)f_3)\eta(X)\xi, \quad (2.7)$$

$$R(X, Y)\xi = (f_1 - f_3)[\eta(Y)X - \eta(X)Y], \quad (2.8)$$

$$R(\xi, X)Y = (f_1 - f_3)[g(X, Y)\xi - \eta(Y)X], \quad (2.9)$$

$$S(X, \xi) = 2n(f_1 - f_3)\eta(X), \quad (2.10)$$

$$S(\xi, \xi) = 2n(f_1 - f_3), \quad (2.11)$$

$$Q\xi = 2n(f_1 - f_3)\xi, \quad (2.12)$$

$$r = 2n(2n + 1)f_1 + 6nf_2 - 4nf_3, \quad (2.13)$$

where R , S and r are the curvature tensor, Ricci tensor and scalar curvature of the space-form respectively and Q is the Ricci operator defined by $g(QX, Y) = S(X, Y)$. We know (see [1]) that the ϕ -sectional curvature of a generalized Sasakian-space-form $M(f_1, f_2, f_3)$ is $f_1 + 3f_2$.

In a Riemannian manifold of dimension $(2n + 1)$ the Weyl conformal curvature tensor is given by

$$\begin{aligned} C(X, Y)Z &= R(X, Y)Z - \frac{1}{(2n - 1)}[S(Y, Z)X - S(X, Z)Y \\ &\quad + g(Y, Z)QX - g(X, Z)QY] \quad (2.14) \\ &+ \frac{r}{2n(2n - 1)}[g(Y, Z)X - g(X, Z)Y], \end{aligned}$$

for any X, Y and $Z \in T(M)$. A generalized Sasakian-space-form of dimension greater than three is said to be conformally flat if its Weyl conformal curvature tensor vanishes. It is known (see [12]) that a $(2n + 1)$ -dimensional ($n > 1$) generalized Sasakian-space-form is conformally flat if and only if $f_2 = 0$.

3. ξ -CONFORMALLY FLAT GENERALIZED SASAKIAN-SPACE-FORMS

In this section we study ξ -conformally flat generalized Sasakian-space-form. Let $M(f_1, f_2, f_3)$ be a generalized Sasakian-space-forms. Putting $Z = \xi$ in (2.15), we obtain

$$\begin{aligned}
 C(X, Y)\xi = R(X, Y)\xi - \frac{1}{(2n - 1)} [S(Y, \xi)X - S(X, \xi)Y \\
 + \eta(Y)QX - \eta(X)QY] \\
 + \frac{r}{2n(2n + 1)} [\eta(Y)X - \eta(X)Y].
 \end{aligned}
 \tag{3.1}$$

Using (2.7), (2.8) and (2.10) in (3.1), yields

$$\begin{aligned}
 C(X, Y)\xi = \left[(f_1 - f_3) + \frac{r}{2n(2n - 1)} \right. \\
 \left. - \frac{4nf_1 + 3f_2 - (2n + 1)f_3}{(2n + 1)} \right] [\eta(Y)X - \eta(X)Y].
 \end{aligned}
 \tag{3.2}$$

Putting the value of r from (2.13) in (3.2), we get

$$C(X, Y)\xi = 0.
 \tag{3.3}$$

Therefore we conclude that the generalized Sasakian-space-form is ξ -conformally flat. Thus we can state the following:

THEOREM 3.1. *A $(2n + 1)$ -dimensional generalized Sasakian-space-form $M(f_1, f_2, f_3)$ is always ξ -conformally flat.*

4. ϕ -CONFORMALLY FLAT GENERALIZED SASAKIAN-SPACE-FORMS

In this section we consider ϕ -conformally flat generalized Sasakian-space-forms. Let the generalized Sasakian-space-form $M(f_1, f_2, f_3)$ be ϕ -conformally flat, i.e.,

$$g(C(\phi X, \phi Y)\phi Z, \phi W) = 0.
 \tag{4.1}$$

Now,

$$\begin{aligned}
 g(C(\phi X, \phi Y)\phi Z, \phi W) &= g(R(\phi X, \phi Y)\phi Z, \phi W) \\
 &\quad - \frac{1}{2n-1} [S(\phi Y, \phi Z)g(\phi X, \phi W) \\
 &\quad \quad - S(\phi X, \phi Z)g(\phi Y, \phi W) \\
 &\quad \quad + g(\phi Y, \phi Z)S(\phi X, \phi W) \\
 &\quad \quad - S(\phi Y, \phi W)g(\phi X, \phi Z)] \\
 &\quad + \frac{r}{2n(2n-1)} [g(\phi Y, \phi Z)g(\phi X, \phi W) \\
 &\quad \quad - g(\phi Y, \phi W)g(\phi X, \phi Z)].
 \end{aligned} \tag{4.2}$$

Using (1.1), (2.6) and (2.13) in (4.2), we obtain

$$\begin{aligned}
 g(C(\phi X, \phi Y)\phi Z, \phi W) &= f_2 \left[\{2g(\phi X, Y)g(Z, \phi W) \right. \\
 &\quad + g(\phi X, Z)g(Y, \phi W) \\
 &\quad \left. - g(\phi Y, Z)g(X, \phi W)\} \right. \\
 &\quad \left. - \frac{3}{(2n-1)} \{g(\phi Y, \phi Z)g(\phi X, \phi W) \right. \\
 &\quad \left. - g(\phi X, \phi Z)g(\phi Y, \phi W)\} \right].
 \end{aligned} \tag{4.3}$$

Therefore from (4.1) and (4.3) we obtain either $f_2 = 0$, or

$$\begin{aligned}
 &\{2g(\phi X, Y)g(Z, \phi W) + g(\phi X, Z)g(Y, \phi W) - g(\phi Y, Z)g(X, \phi W)\} \\
 &\quad - \frac{3}{(2n-1)} \{g(\phi Y, \phi Z)g(\phi X, \phi W) - g(\phi X, \phi Z)g(\phi Y, \phi W)\} = 0.
 \end{aligned} \tag{4.4}$$

Putting $W = \phi W$ in (4.5) and using (2.1), we obtain

$$\begin{aligned}
 &\{-2g(\phi X, Y)g(Z, W) - g(\phi X, Z)g(Y, W) + g(\phi Y, Z)g(X, W)\} \\
 &\quad - \frac{3}{(2n-1)} \{-g(\phi Y, \phi Z)g(\phi X, W) + g(\phi X, \phi Z)g(\phi Y, W)\} = 0.
 \end{aligned} \tag{4.5}$$

Putting $Z = \xi$ in (4.5), yields

$$g(\phi X, Y)\eta(W) = 0, \tag{4.6}$$

which implies either $\eta = 0$ or $g(\phi X, Y) = 0$. Both the cases do not occur. Therefore ϕ -conformally flat generalized Sasakian-space-form implies $f_2 = 0$.

Conversely, if $f_2 = 0$, then from (4.3) we obtain $g(C(\phi X, \phi Y)\phi Z, \phi W) = 0$ for all X, Y, Z and $W \in T(M)$. Thus $f_2 = 0$ implies the generalized Sasakian-space-form is ϕ -conformally flat.

Therefore we can state the following:

THEOREM 4.1. *A $(2n + 1)$ -dimensional generalized Sasakian-space-form $M(f_1, f_2, f_3)$ is ϕ -conformally flat if and only if $f_2 = 0$.*

In [12] U. K. Kim proved that for a $(2n+1)$ -dimensional generalized Sasakian-space-form the following holds:

- (i) If $n > 1$, then M is conformally flat if and only if $f_2 = 0$.
- (ii) If M is conformally flat and ξ is Killing vector field, then M is locally symmetric and has constant ϕ -sectional curvature.

Since conformally flatness implies ϕ -conformally flatness, hence in the view of the first part of the above theorem we have the following:

COROLLARY 4.1. *A $(2n + 1)$ -dimensional $(n > 1)$ generalized Sasakian-space-form $M(f_1, f_2, f_3)$ is ϕ -conformally flat if and only if it is conformally flat.*

Again, in the view of the second part of the above theorem we have the following:

COROLLARY 4.2. *For a $(2n + 1)$ -dimensional $(n > 1)$ ϕ -conformally flat generalized Sasakian-space-form $M(f_1, f_2, f_3)$ with ξ as a Killing vector field, the space-form is locally symmetric and has constant ϕ -sectional curvature.*

ACKNOWLEDGEMENTS

The authors are thankful to the referee for his valuable suggestions in the improvement of the paper.

REFERENCES

- [1] P. ALEGRE, D. BLAIR, A. CARRIAZO, Generalized Sasakian-space-forms, *Israel J.Math.* **141** (2004), 157–183.
- [2] P. ALEGRE, A. CARRIAZO, Submanifolds of generalized Sasakian-space-forms, *Taiwanese J. Math.* **13** (3) (2009), 923–941.
- [3] P. ALEGRE, A. CARRIAZO, Generalized Sasakian-space-forms and conformal changes of the metric, *Results Math.* **59** (3-4) (2011), 485–493.

- [4] P. ALEGRE, A. CARRIAZO, C. ÖZGÜR, S. SULAR, New examples of generalized Sasakian-space-forms, preprint.
- [5] P. ALEGRE, A. CARRIAZO, Structures on generalized Sasakian-space-forms, *Differential Geom. Appl.* **26** (6) (2008), 656–666.
- [6] K. ARSLAN, C. MURATHAN, C. ÖZGÜR, On ϕ -conformally flat contact metric manifolds, *Balkan J. Geom. Appl. (BJGA)* **5** (2) (2000), 1–7.
- [7] D.E. BLAIR, “Contact Manifolds in Riemannian Geometry”, Lecture Notes in Mathematics, 509, Springer-Verlag Berlin, 1976.
- [8] D.E. BLAIR, “Riemannian Geometry of Contact and Symplectic Manifolds”, Progress in Mathematics, 203, Birkhauser, Boston, 2002.
- [9] U.C. DE, A. SARKAR, On the projective curvature tensor of generalized Sasakian-space-forms, *Quaest. Math.* **33** (2) (2010), 245–252.
- [10] U.C. DE, A. SARKAR, Some results on generalized Sasakian-space-forms, *Thai J. Math.* **8** (1) (2010), 1–10.
- [11] U.C. DE, S. BISWAS, A note on ξ -conformally flat contact manifolds, *Bull. Malays. Math. Sci. Soc. (2)* **29** (1) (2006), 51–57.
- [12] U.K. KIM, Conformally flat generalized Sasakian-space-forms and locally symmetric generalized Sasakian-space-forms, *Note Mat.* **26** (1) (2006), 55–67.
- [13] Z. OLSZAK, On the existence of generalized complex space forms, *Israel J. Math.* **65** (2) (1989), 214–218.
- [14] G. ZHEN, On conformal symmetric K -contact manifolds, *Chinese Quart. J. Math.* **7** (1992), 5–10.
- [15] G. ZHEN, J.L. CABRERIZO, L.M. FERNANDEZ, M. FERNANDEZ, On ξ -conformally flat contact metric manifolds, *Indian J. Pure Appl. Math.* **28** (6) (1997), 725–734.
- [16] G. ZHEN, J.L. CABRERIZO, L.M. FERNANDEZ, M. FERNANDEZ, The structure of a class of K -contact manifolds, *Acta Math. Hungar.* **82** (4) (1999), 331–340.