

Dec 7th, 8:30 AM - 9:00 AM

## Wavemaker Improvements at the University of New Orleans Towing Tank

Ryan D. Thiel  
*University of New Orleans*

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<https://scholarworks.uno.edu/oceanwaves/2017/Introduction/1>

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December 07, 2017

# Wavemaker Improvements at the University of New Orleans Towing Tank

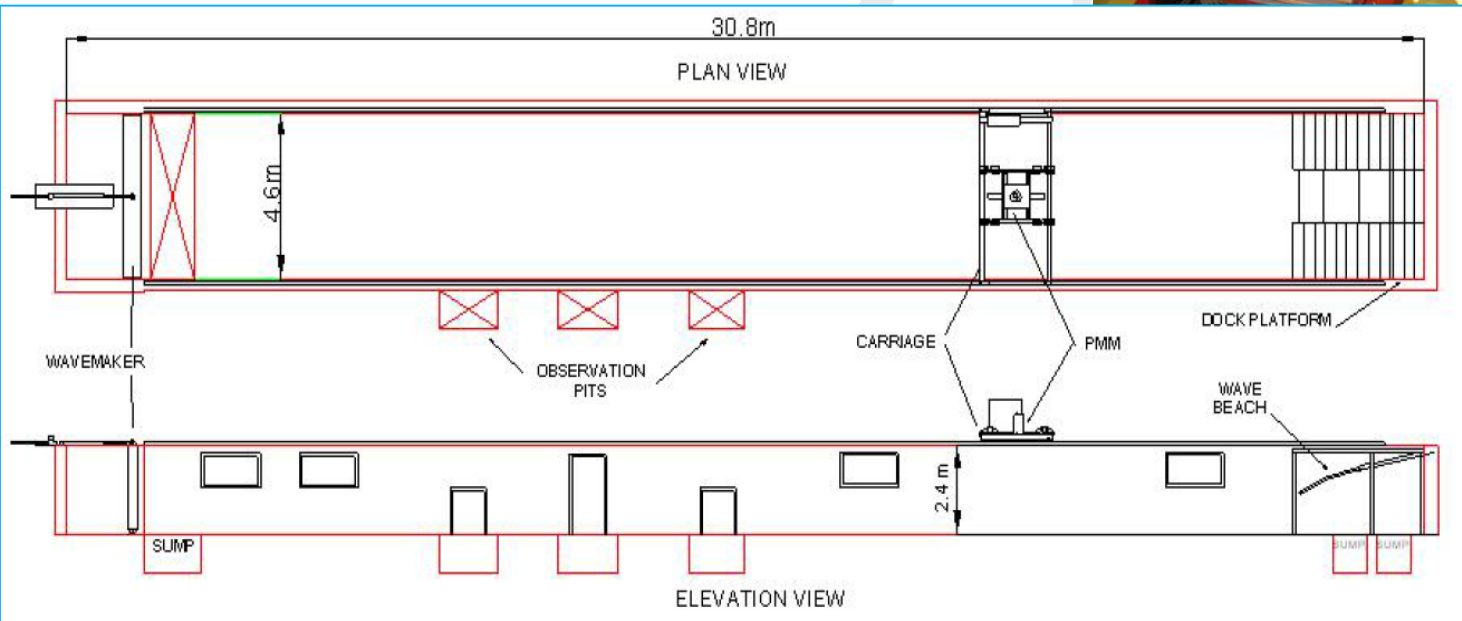
Ryan D. Thiel

School of Naval Architecture and Marine Engineering

College of Engineering - University of New Orleans

# UNO Towing Tank

- 30.8m long x 4.6m wide x 2.4m deep
- Carriage with a tow speed of 3.1 m/s
- Wave maker



# UNO Wavemaker

## Education/Research

- NA&ME Class Labs
- Graduate Theses

## Commercial

- Offshore Platforms
- Energy Conversion Device

## Other

- Movie Monster!



# UNO Wavemaker

Originally Designed and Built by Arctec Offshore Corporation circa 1990

- Hinged Single Flap
- Flooded Back
- Hydraulically Actuated
- Computer Controlled

Included

- Data Acquisition
- Wave Probes

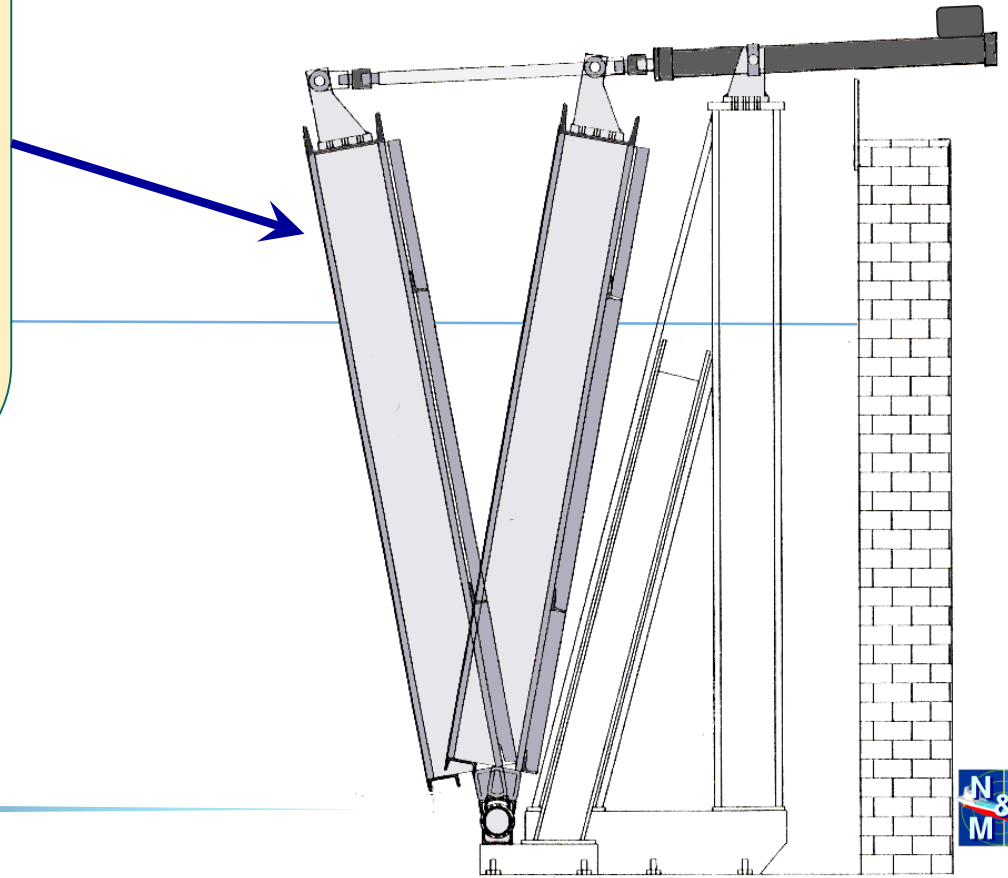


# UNO Wavemaker

## Original 1990 Configuration

### Single Wave Board

- Bottom Hinged
- Flooded Back
- A36 Steel
- Zinc Primer
- Epoxy Top Coat





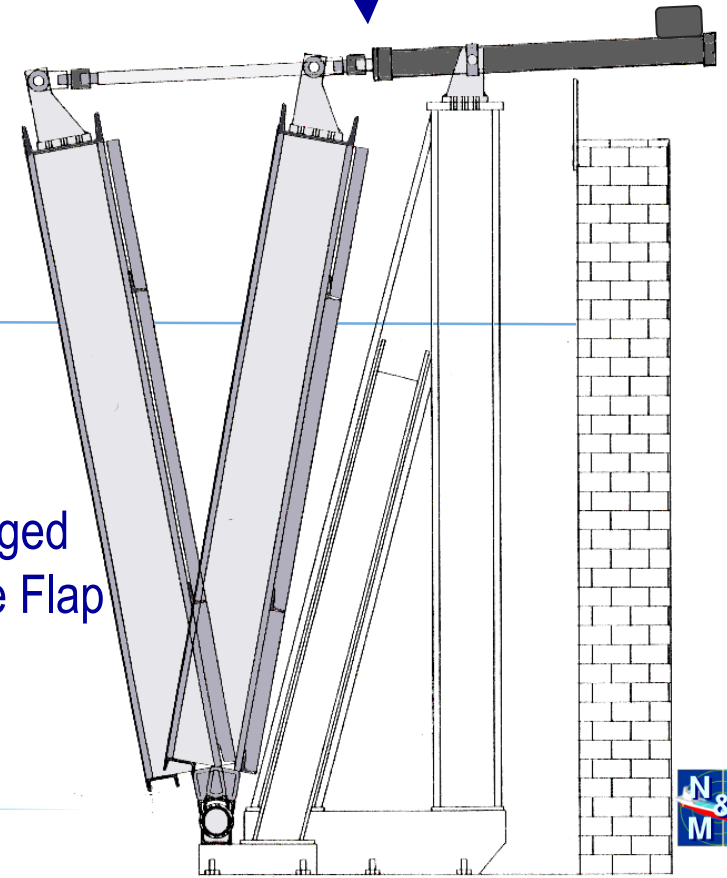
# UNO Wavemaker

## Original 1990 Configuration

### Linear Hydraulic Actuator

- 2" Bore
- 30 inch stroke
- 3000 psi
- LDT Feedback Sensor

Hinged  
Wave Flap



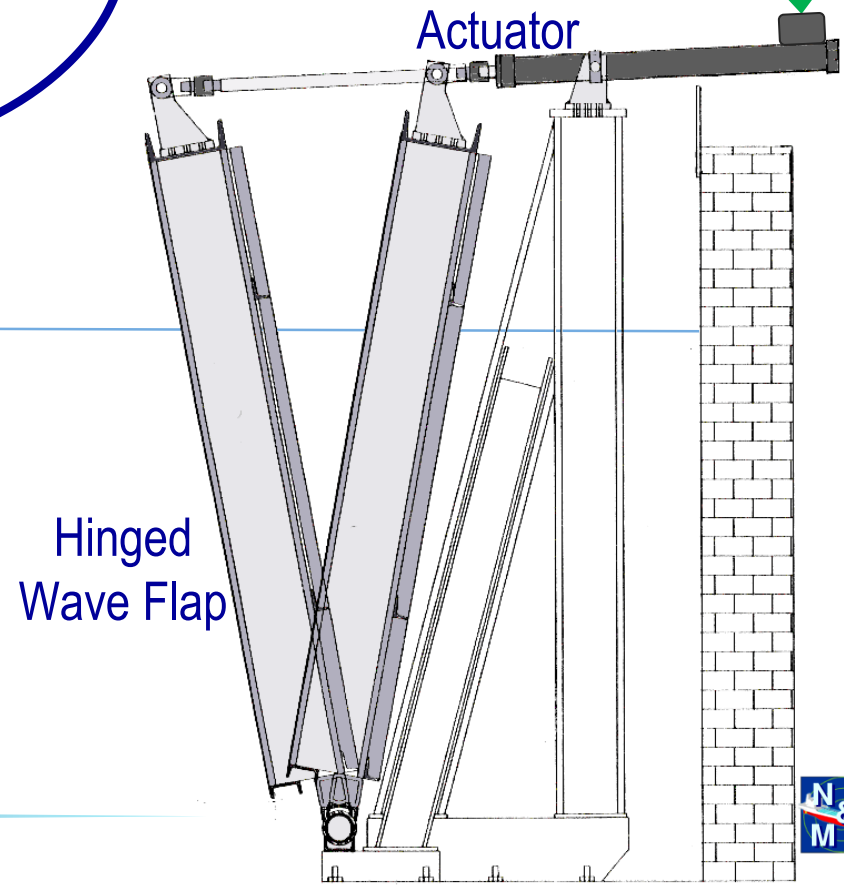
# UNO Wavemaker

Original 1990 Configuration



## Hydraulic Power Unit

- 480 Volt
- 40 Horsepower
- 3000 PSI
- Replaced in 2006





# UNO Wavemaker

## Original 1990 Configuration

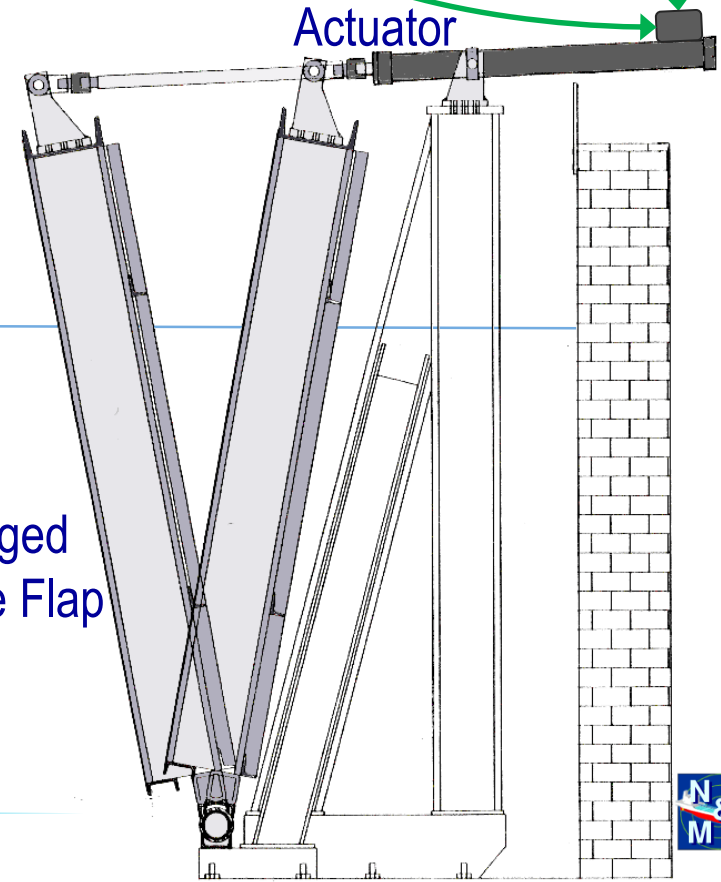


### Moog Servocontroller

- Proportional Control of Actuator Position
- Accepts Voltage Input Signal Proportional to Actuator Position

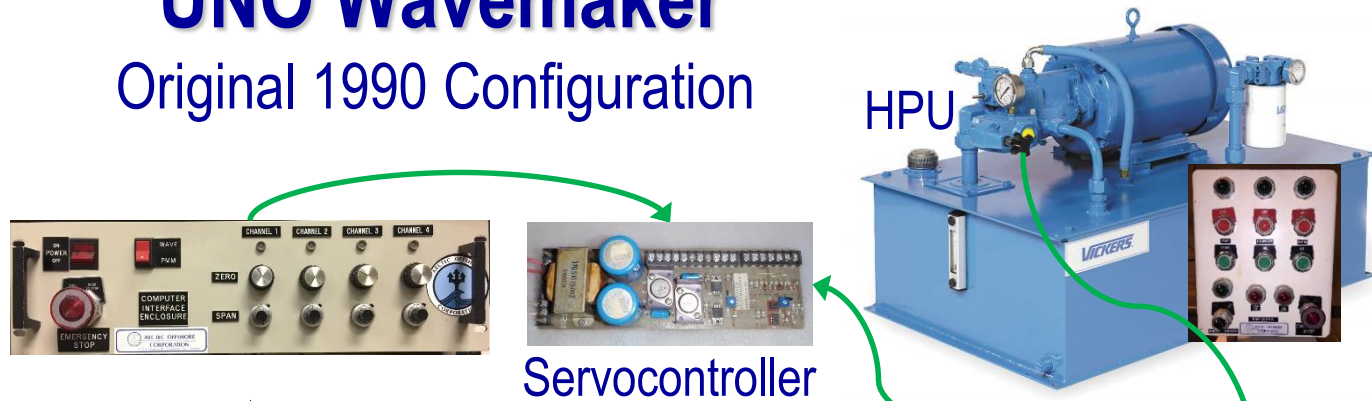
Actuator

Hinged Wave Flap



# UNO Wavemaker

## Original 1990 Configuration



HPU

Servocontroller

Actuator

### Computer Interface Enclosure

- Signal conditioning
  - Wave output signal
  - Wave probes
- Interfaces with PC

Hinged Wave Flap

# UNO Wavemaker

## Original 1990 Configuration



Computer Interface  
Enclosure

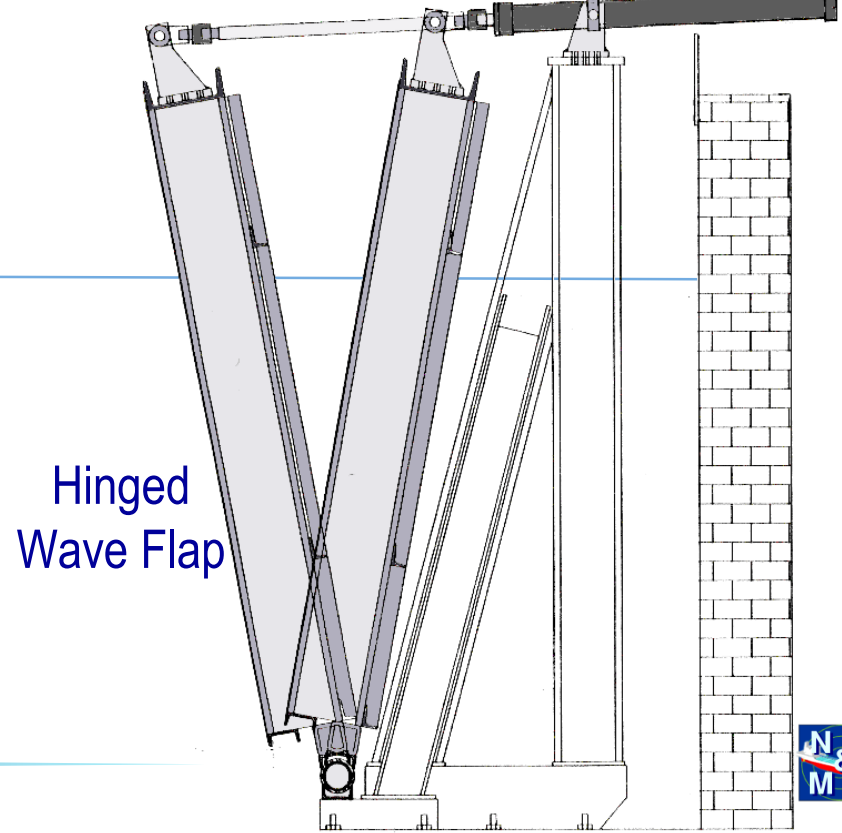


Servocontroller



HPU

Actuator



Hinged  
Wave Flap

### IBM 80386Sx

- 16 MHz Processor
- 1MB RAM
- 65 MB HDD
- Hercules Graphics Monochrome Monitor
- Dot-Matrix Printer



# UNO Wavemaker

## Original 1990 Configuration



Computer Interface  
Enclosure

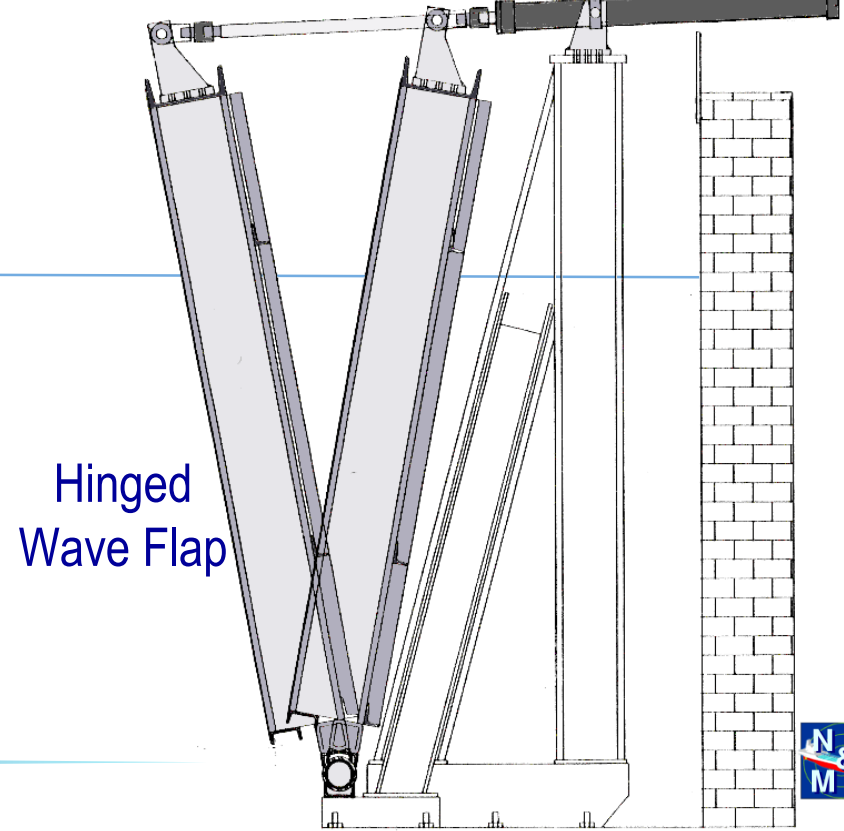


Servocontroller



HPU

Actuator



Hinged  
Wave Flap

Software:

MKWAVES

- Create regular and irregular waves

ACQSYS

- Run experiments and record data





# UNO Wavemaker

## Original 1990 Configuration



IBM 386SX PC  
MKWAVES  
ACQSYS



Computer Interface  
Enclosure



Servocontroller

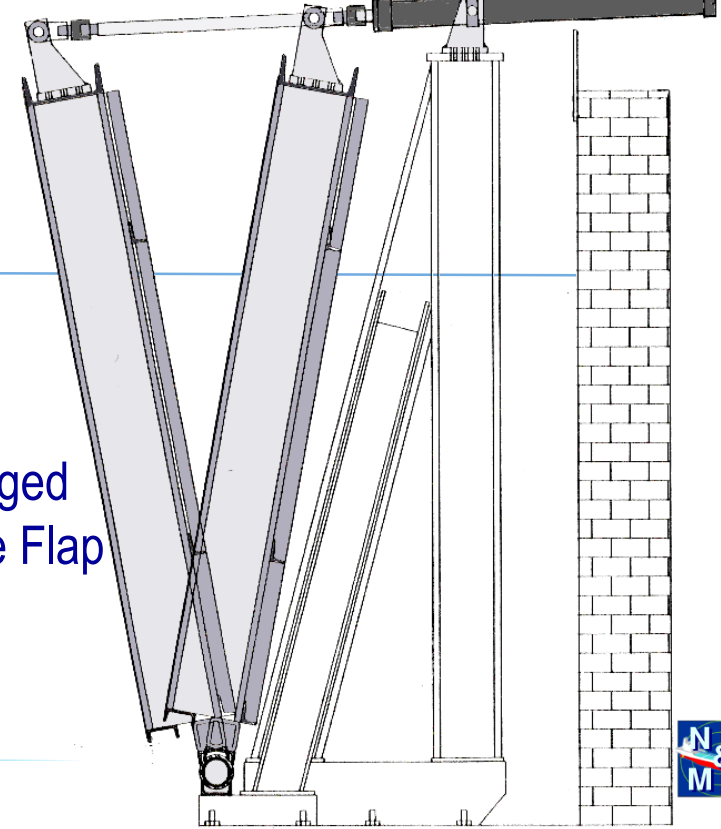


HPU

Actuator



Hinged  
Wave Flap



### Capacitance Wave Probe

- Measures wave elevation

# UNO Wavemaker

## Original 1990 Configuration



IBM 386SX PC  
MKWAVES  
ACQSYS



Computer Interface  
Enclosure



Servocontroller



HPU

Actuator

Arctec Capacitance  
Wave Probe

Hinged  
Wave Flap





# UNO Wavemaker

Original 1990 Configuration



IBM 386SX PC  
MKWAVES  
ACQSYS



Computer Interface  
Enclosure



Servocontroller



HPU

Actuator

Arctec Capacitance  
Wave Probe

Hinged  
Wave Flap

# UNO Wavemaker

## Original 1990 Configuration



Computer Interface Enclosure



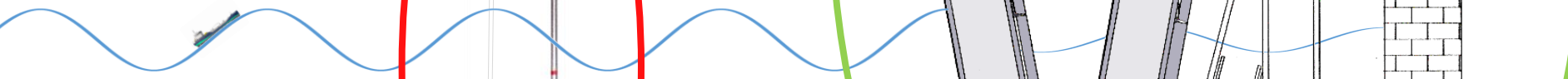
Servocontroller



Actuator

Arctec Capacitance Wave Probe

Hinged Wave Flap



# UNO Wavemaker

## Original 1990 Configuration



IBM 386SX PC  
MKWAVES  
ACQSYS



Computer Interface  
Enclosure



Servocontroller



HPU

Actuator

Arctec Capacitance  
Wave Probe

Hinged  
Wave Flap

# UNO Wave Probes

Original 1990 Configuration



Computer Interface Enclosure

## Arctec Wave Probes

- Capacitance Type Wave Probe
- Signal conditioning is part of Computer Interface Enclosure

Arctec Capacitance Wave Probe

## Disadvantages

- Difficult to use with other measurement systems
- Long immersion time causes drift.

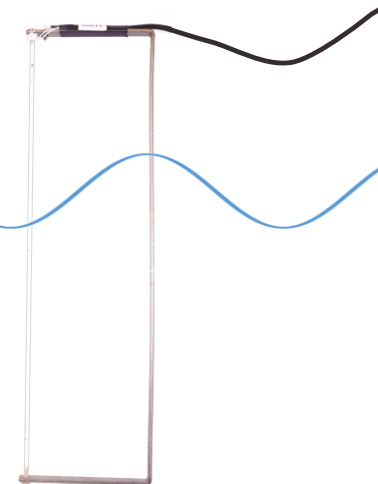
# UNO Wave Probes

## RBR WG-50

RBR WG-50 wave probes were purchased to replace the Arctec Probes, circa 2003

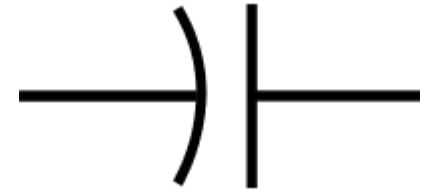
RBR WG-50

- Voltage Output
- PTFE insulated
- Capacitance Type



# UNO Wave Probes

## Capacitance Wave Probes

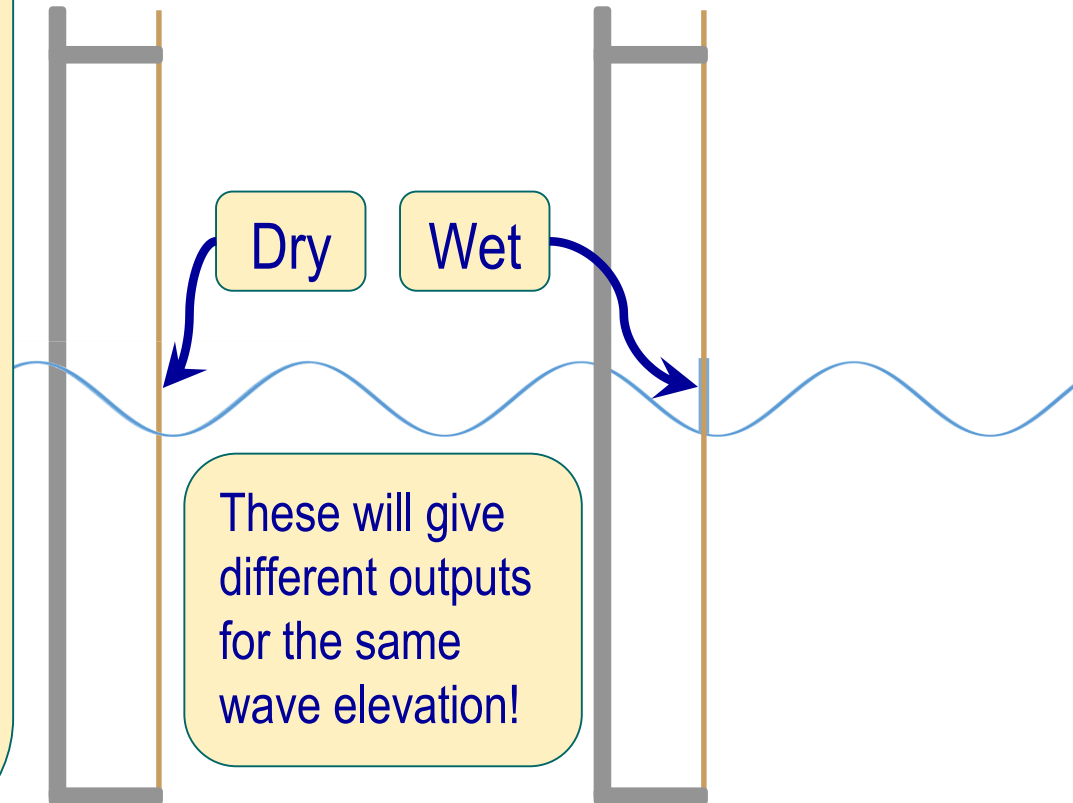


### The Problem:

When the un-immersed part of the probe gets wet, it temporarily stays wet.

The capacitance is changed until the probe dries, usually a few minutes.

This gives an error of up to  $\frac{1}{4}$  inch which slowly decreases.





# UNO Wave Probes

## Senix Ultra-S

### Senix Ultra-S

- Ultrasonic
- Non-contact
- Voltage, Current, or Serial Output



### Problem:

Poor performance when measuring short wavelength waves.

# UNO Wave Probes

Conductance Wave Probes

aka Resistance Wave Probes

## UNO Conductance Probe Prototype

- Designed in-house
- 3 units constructed
- Currently in use



# UNO Wavemaker

Original 1990 Configuration



IBM 386SX PC  
MKWAVES  
ACQSYS



Computer Interface  
Enclosure



Servocontroller



HPU

Actuator

Arctec Capacitance  
Wave Probe

Hinged  
Wave Flap

# UNO Wavemaker

## Upgrade Progress



IBM 386SX PC  
MKWAVES  
ACQSYS



Computer Interface  
Enclosure



Servocontroller



HPU

Actuator

UNO Conductance  
Wave Probe

Hinged  
Wave Flap



# UNO Wavemaker

## Upgrade Progress



Computer Interface Enclosure



Servocontroller



HPU



Actuator

UNO Conductance Wave Probe

Hinged Wave Flap

# UNO Wavemaker

## Original Software



IBM 386SX PC  
MKWAVES  
ACQSYS

### MKWAVES and ACQSYS Software

- DOS based software.
- Required native DOS system
- Would not run in DOS Emulator
- Primary outputs are to the printer



# UNO Wavemaker

## Original Computer Hardware



IBM 386SX PC  
MKWAVES  
ACQSYS

### IBM 386SX

- Hardware was upgraded as far as it could go.
- The data card required an ISA bus.
- Eventually became unusable.



# UNO Wavemaker

## Upgrade Progress



Computer Interface Enclosure



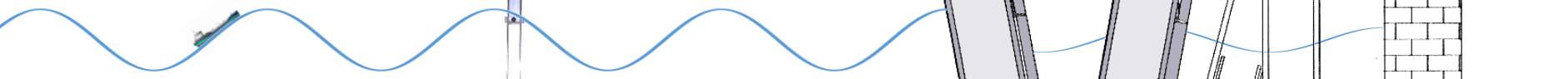
Servocontroller



Actuator

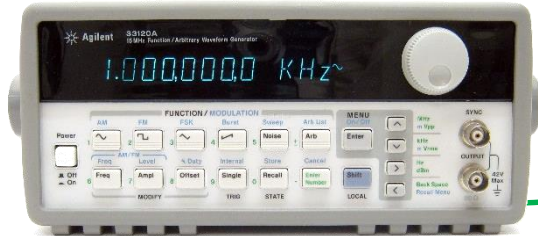
UNO Conductance Wave Probe

Hinged Wave Flap



# UNO Wavemaker

## Upgrade Progress



Function Generator

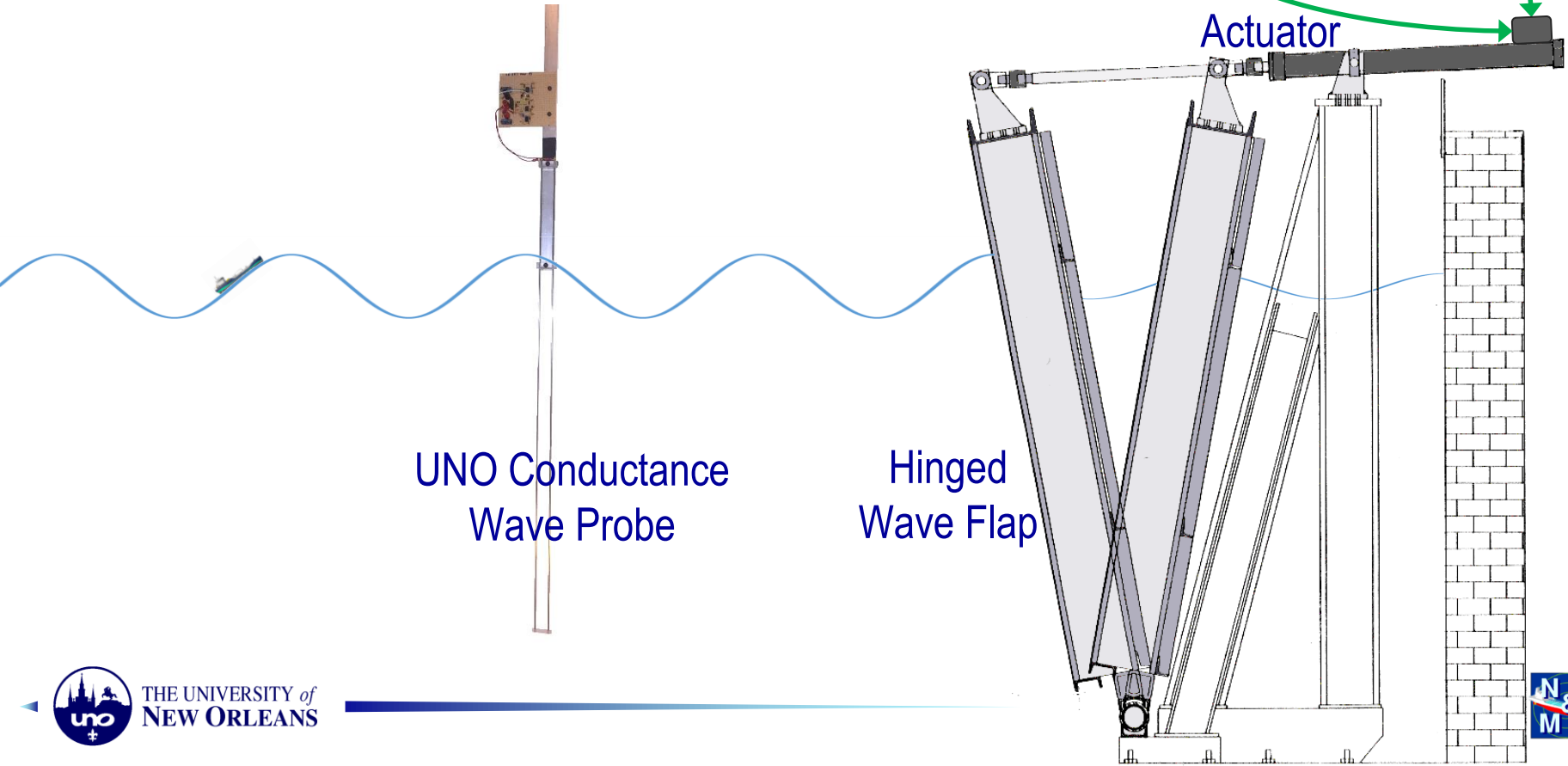


Servocontroller



HPU

Actuator



UNO Conductance Wave Probe

Hinged Wave Flap

# UNO Wavemaker

Upgrade Progress



Function Generator

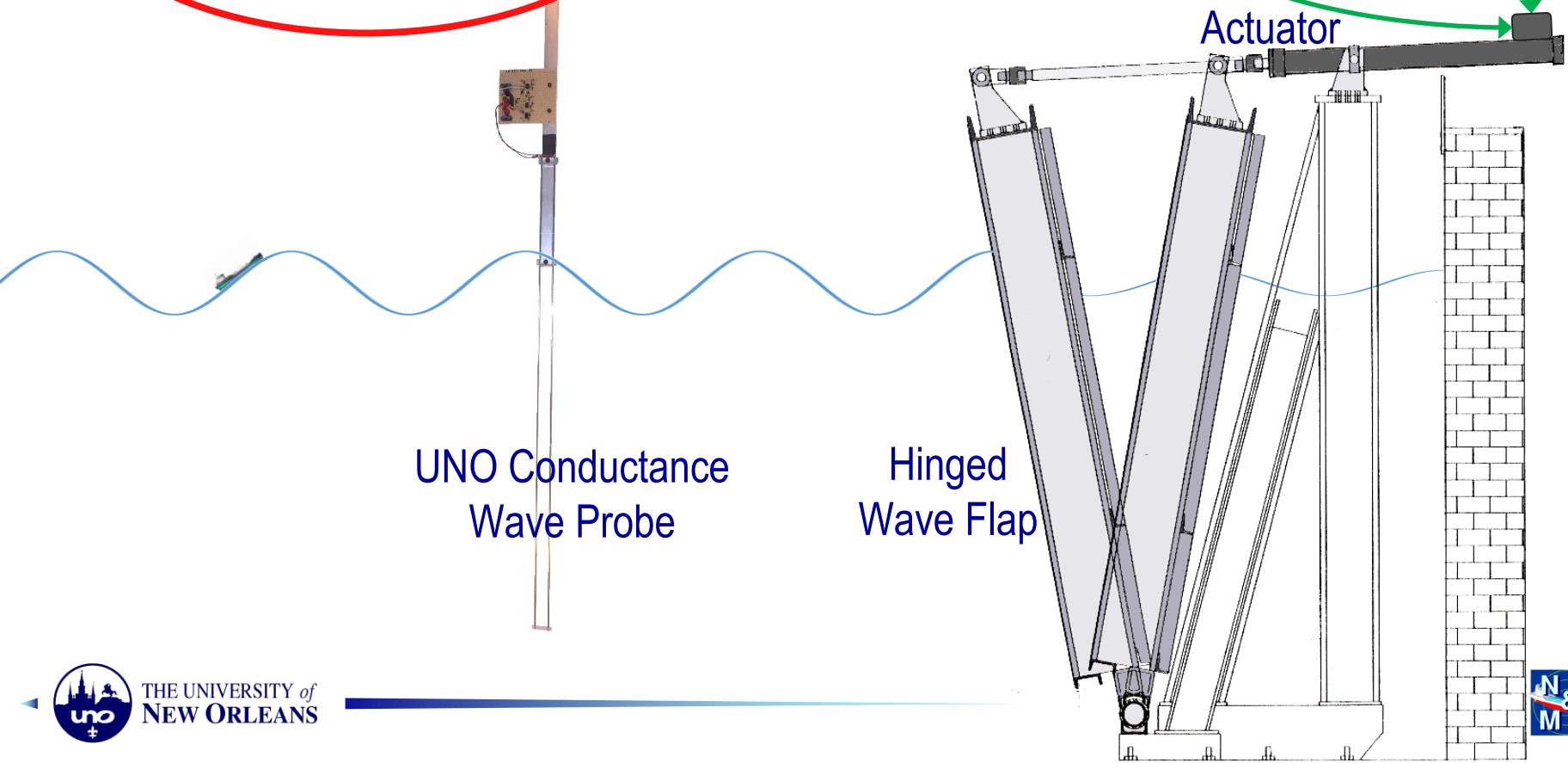


Servocontroller



HPU

Actuator



UNO Conductance Wave Probe

Hinged Wave Flap



# UNO Wavemaker

## Upgrade Progress



Actuator

Hinged Wave Flap

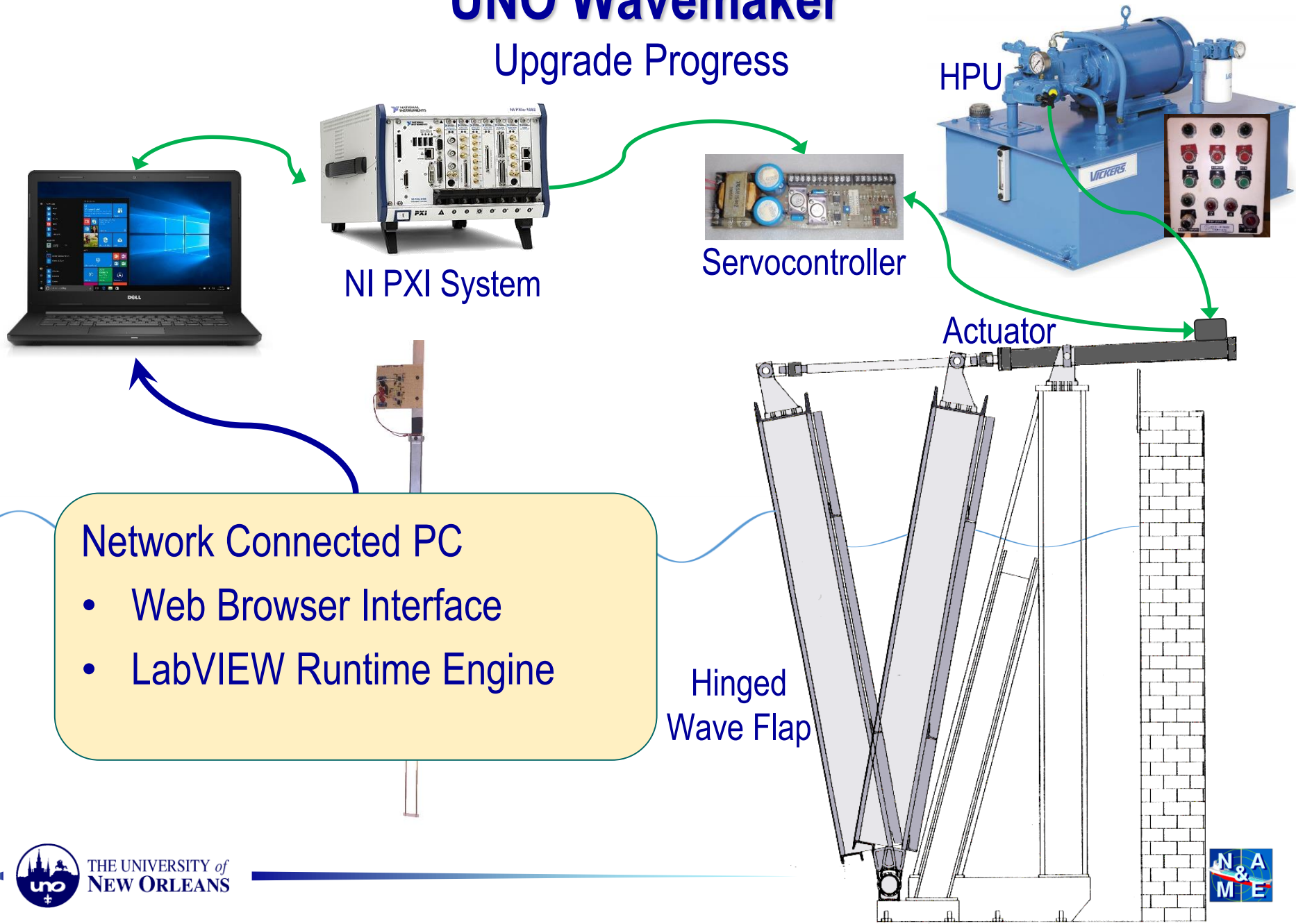
### National Instruments Hardware

- PXIe Embedded Controller
- Analog and Digital I/O
- Signal Conditioning



# UNO Wavemaker

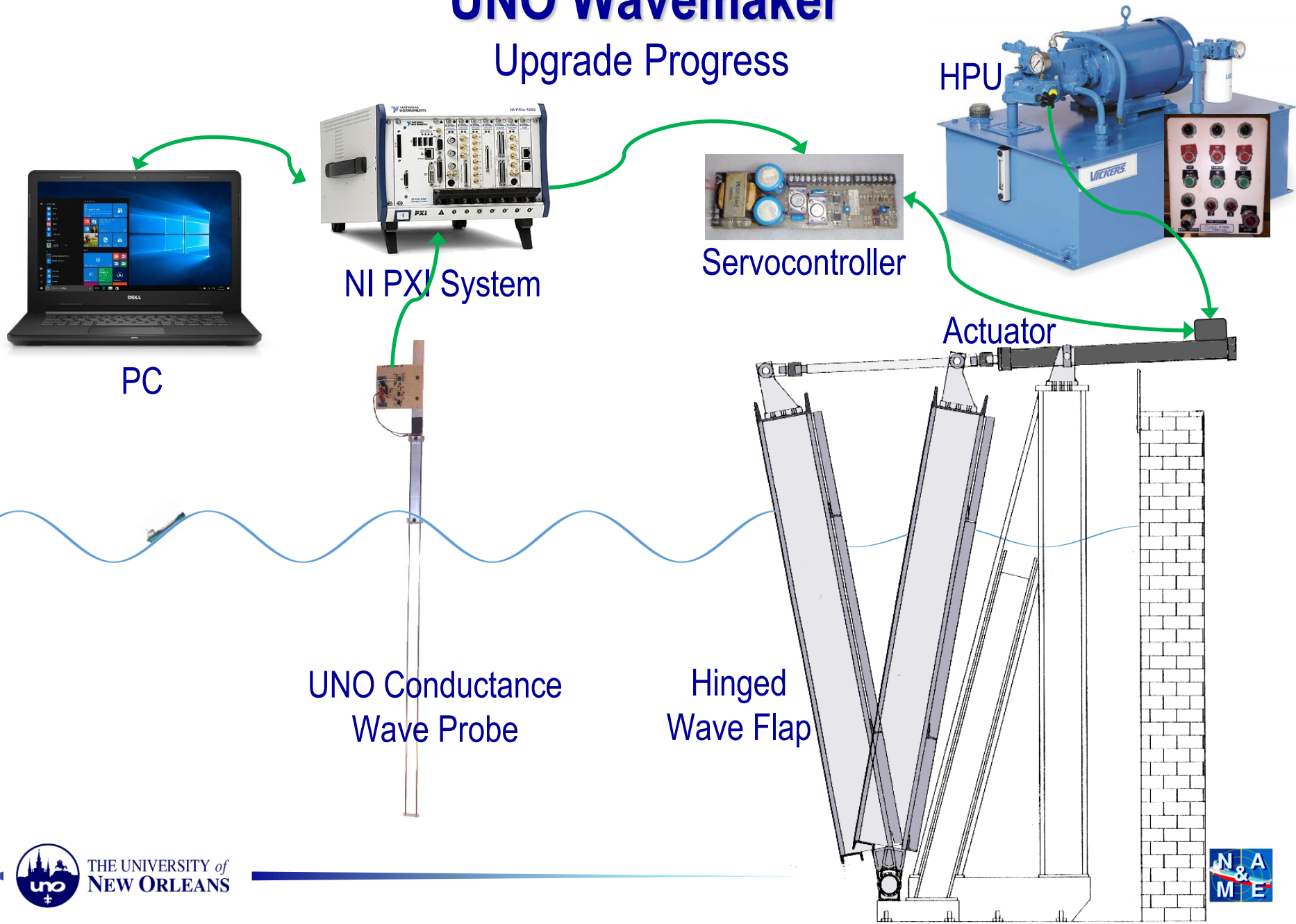
## Upgrade Progress



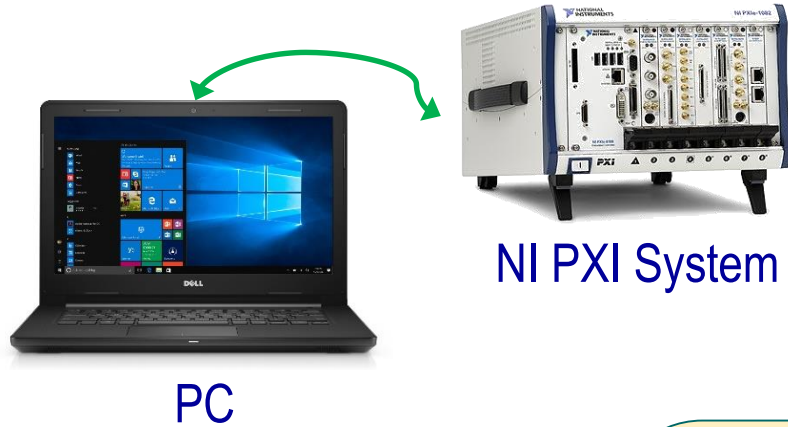


# UNO Wavemaker

## Upgrade Progress



# UNO Wavemaker Software



## Software

- Written in-house
- Runs on real-time embedded OS
- Written in LabVIEW
- Hosts webpage for user interface

# UNO Wavemaker

## User Interface

Hydraulics | DAQ Setup | DAQ | Make Wave Files | Play Wave Files | Regular Waves | Simulate | Settings | Help

PXIe-4300

Physical Channel	Range	Raw Voltage	Scale Factor	Scaled Value	Offset	Engr Value	Units
PXI1Slot2/ai0	±10V	-0.00072283	1	-0.00072283	0	-0.00072283	Volts
Channel Name	Sensor Type	Sensor Serial No	Notes				
Voltage_4300_0							

Physical Channel	Range	Raw Voltage	Scale Factor	Scaled Value	Offset	Engr Value	Units
PXI1Slot2/ai1	±10V	9.39145	1	9.39145	0	9.39145	Volts
Channel Name	Sensor Type	Sensor Serial No	Notes				
Voltage_4300_1							

PXIe-6341

Physical Channel	Range	Raw Voltage	Scale Factor	Scaled Value	Offset	Engr Value	Units
PXI1Slot3/ai0	±10V	0.0427268	1	0.0427268	0	0.0427268	Volts
Channel Name	Sensor Type	Sensor Serial No	Notes				
Voltage_6341_0							

Physical Channel	Range	Raw Voltage	Scale Factor	Scaled Value	Offset	Engr Value	Units
PXI1Slot3/ai1	±10V	0.0410826	1	0.0410826	0	0.0410826	Volts
Channel Name	Sensor Type	Sensor Serial No	Notes				
Voltage_6341_1							

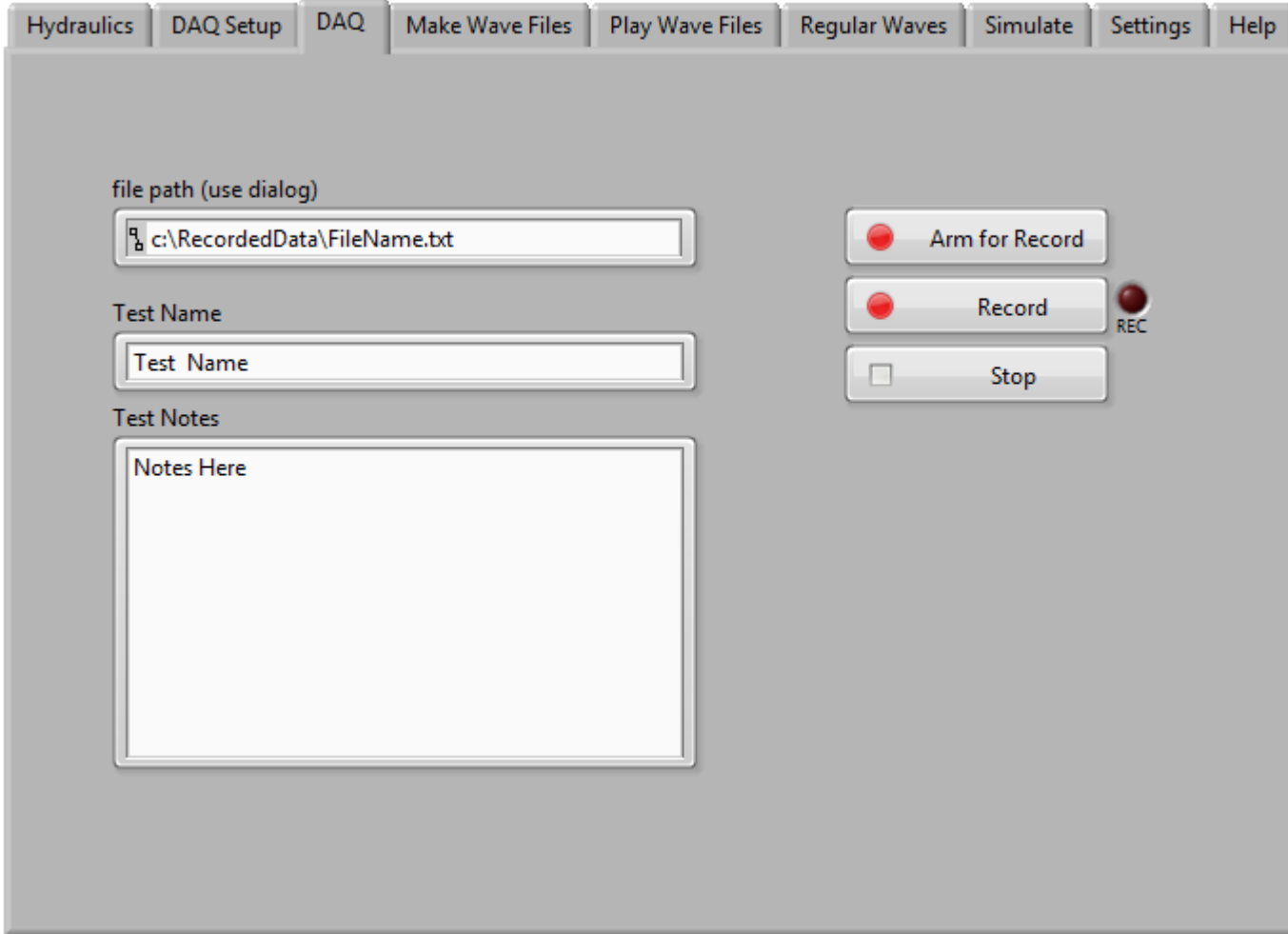
DAQ Setup

Configure DAQ Channels

Scale & Offset Measurements

# UNO Wavemaker

## User Interface



DAQ

Name File

Name Test

Write Notes

Start, Stop, and  
Arm Recording

# UNO Wavemaker

## User Interface

The screenshot shows the UNO Wavemaker software interface with the 'Regular Waves' tab selected. The interface includes a menu bar at the top with options: Hydraulics, DAQ Setup, DAQ, Make Wave Files, Play Wave Files, Regular Waves, Simulate, Settings, and Help. The main area is divided into several sections:

- Amplitude/Height:** A dropdown menu for 'Wave Amplitude' is set to '[centimeters]', and a numerical input field is set to '0'.
- Frequency/Period:** A dropdown menu for 'Frequency [Hz]' is set to '1', and a numerical input field is set to '1'.
- Wave Summary:** A text box displaying calculated values: Period = 1.000 [s], Wavelength = 1.561 [meters], Amplitude = 0.00000 [meters], Amplitude = 0.000 [Volts], and Steepness = 0.000.
- Errors and Warnings:** An empty text box for displaying any errors or warnings.
- Controls:** A 'Play' button with a play icon and a 'REC' indicator, and a 'Stop' button with a square icon.

### Regular Waves

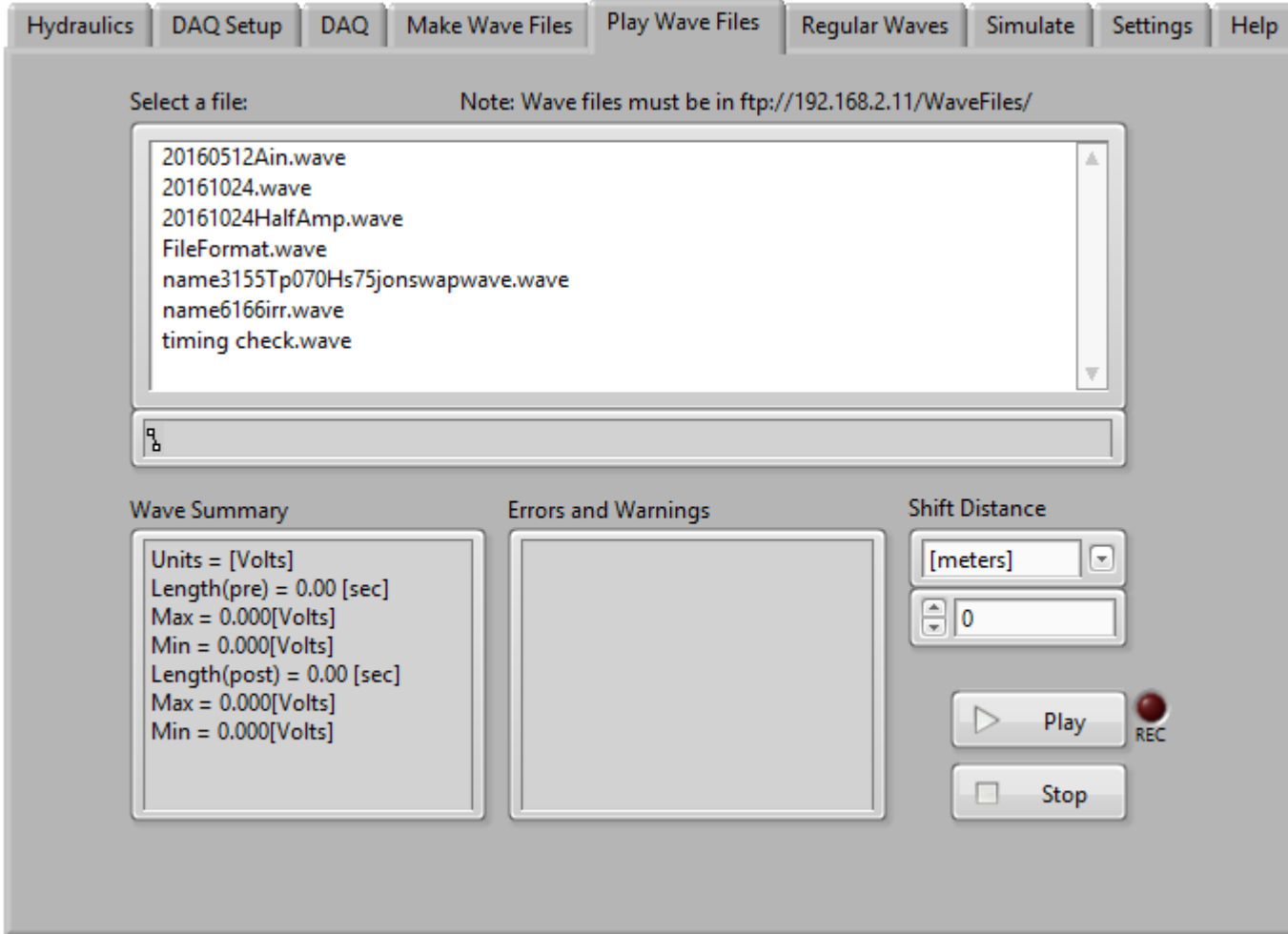
Specify wave height

Specify wave period, frequency, or wavelength



# UNO Wavemaker

## User Interface



Play Wave Files

Run premade  
wave files

Choose location  
along tank of  
time series

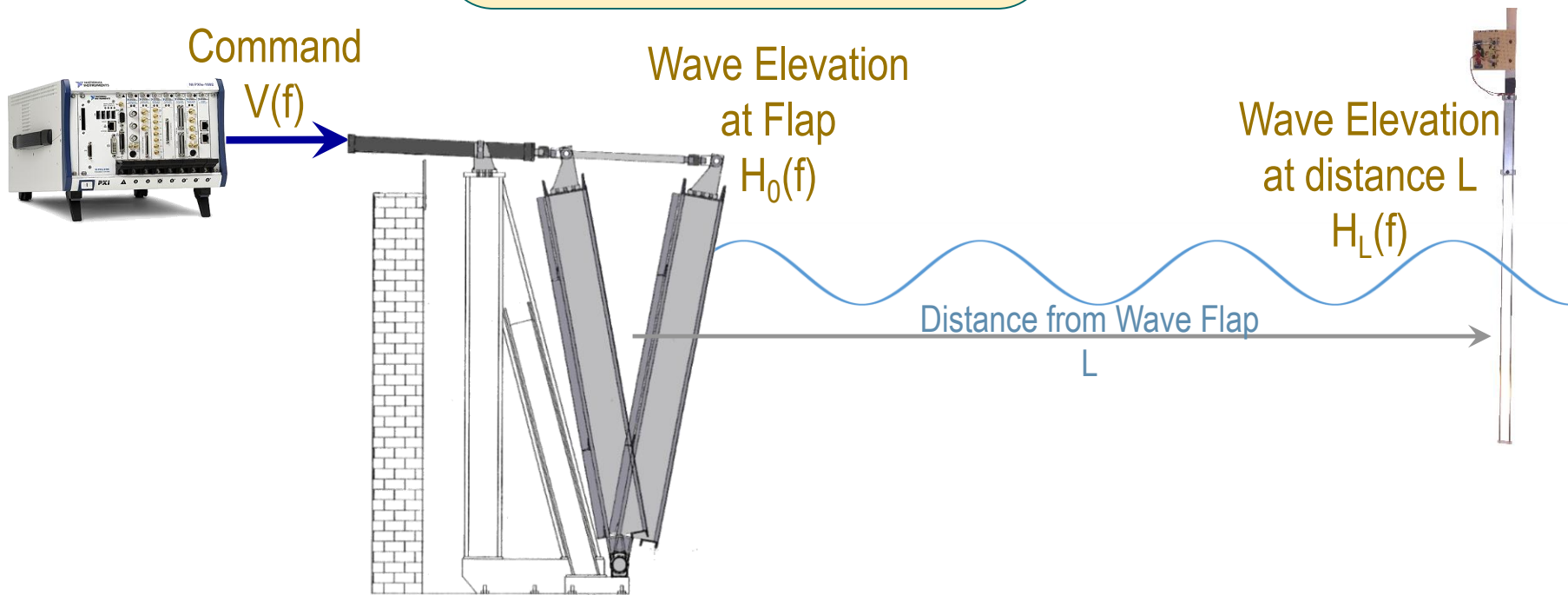
Filetype \*.wave

# UNO Wavemaker

## Wavemaker Theory

### Wavemaker Signals

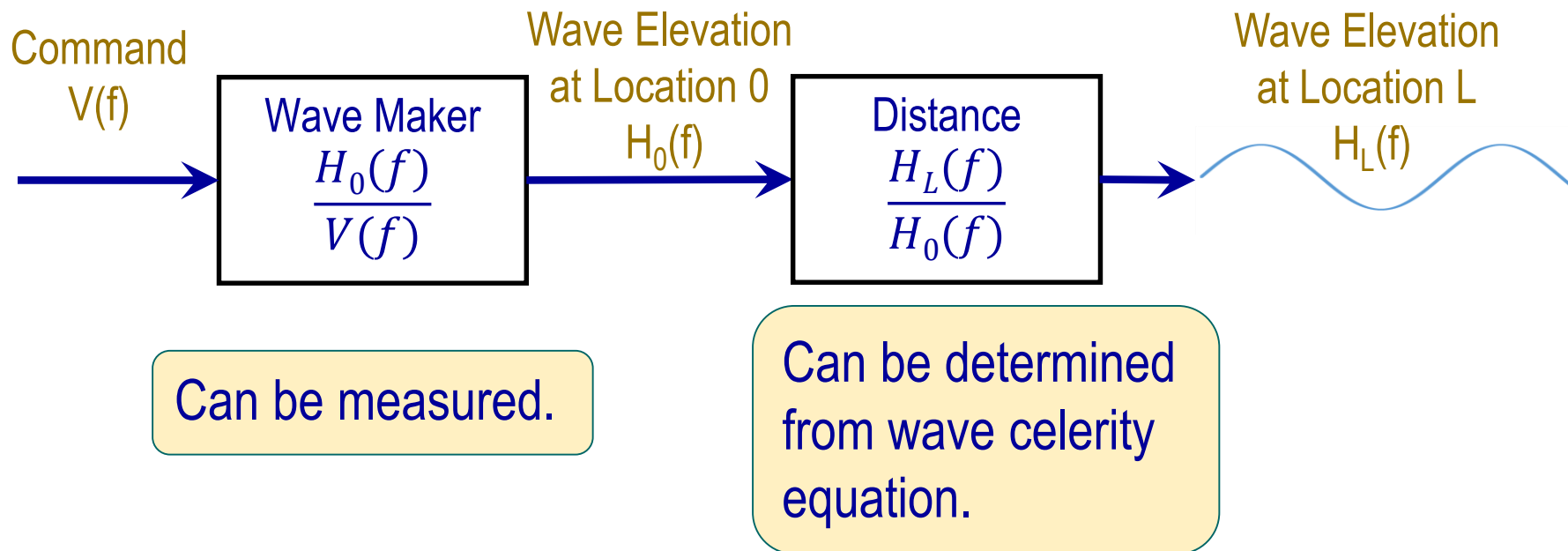
- Command Voltage
- Wave Elevations



# UNO Wavemaker

## Wavemaker Theory

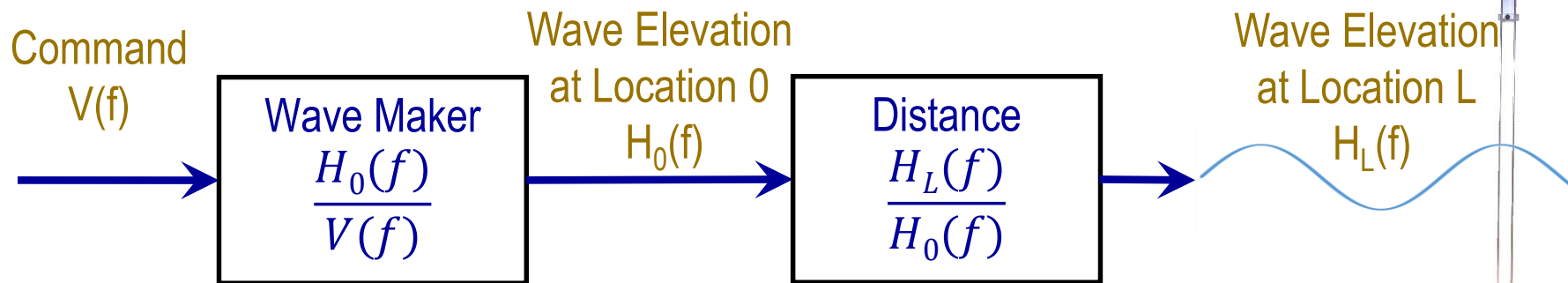
The parts of the wavemaker can be modeled as transfer functions if linear system behavior is assumed.



# UNO Wavemaker

## System Identification

To measure the system response, the wave elevation,  $h(t)$ , was measured at a distance  $L$  from the wave flap for a given input,  $v(t)$ .



The input signal was designed to include the frequency bandwidth of interest without wave-breaking and to have the entire wave pass the wave probe before reflections returned from the end of the tank.

# UNO Wavemaker

## System Identification

The response of the wavemaker was measured with a conductance wave probe and recorded.

Wiener deconvolution was used to determine the forward and inverse transfer functions from the input and output data.

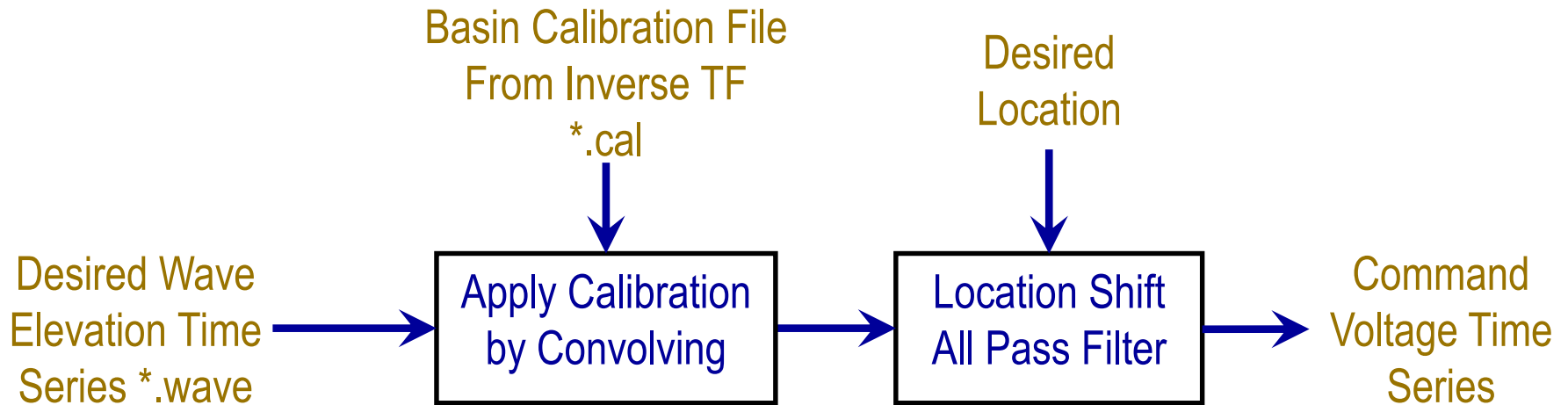
The inverse transfer function can now be used to determine the appropriate input signal for a desired wave elevation. It is described by its impulse response in a basin calibration file.



# UNO Wavemaker

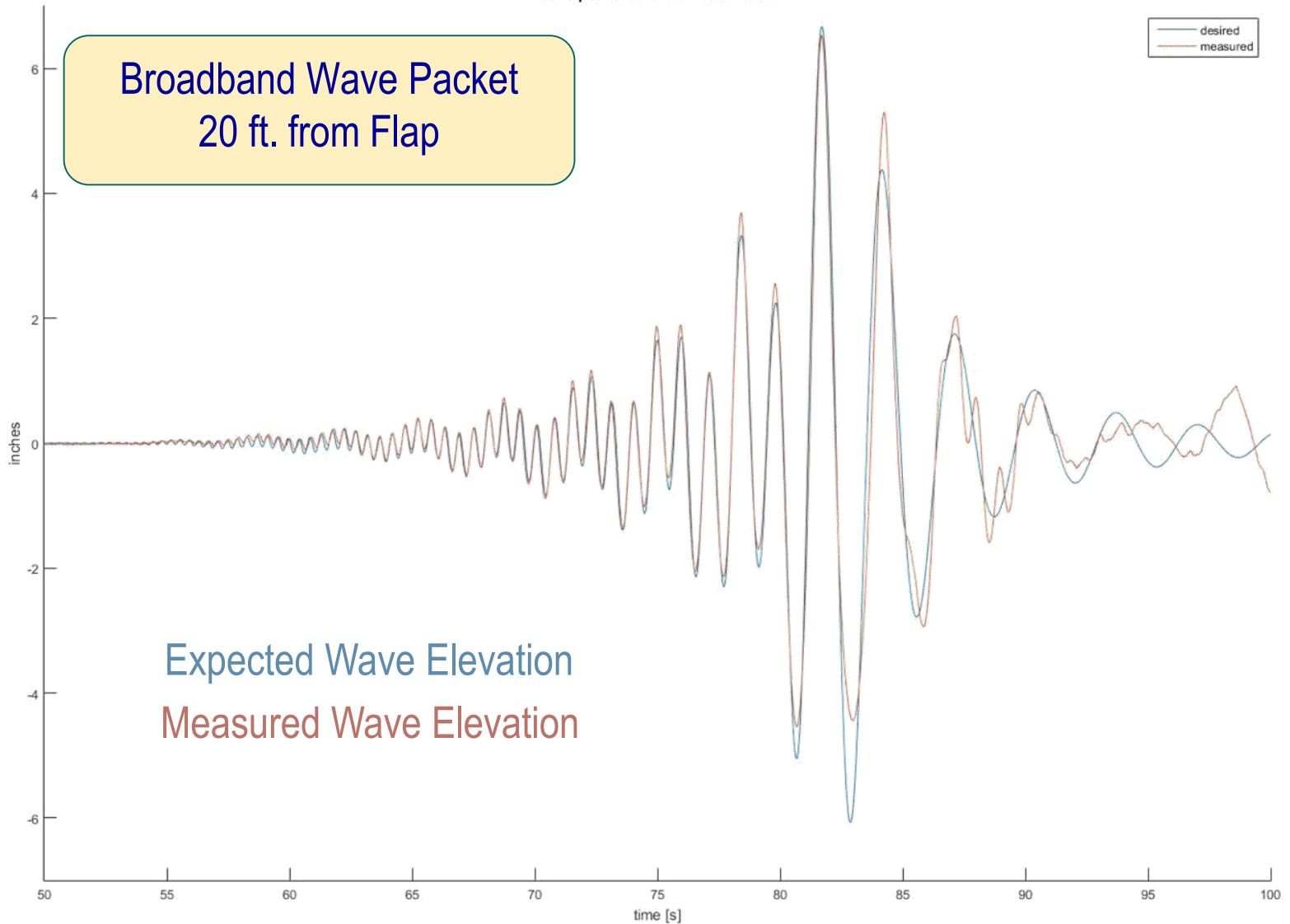
## Wavemaker Software

### Software Functional Diagram for Playing Wave Files

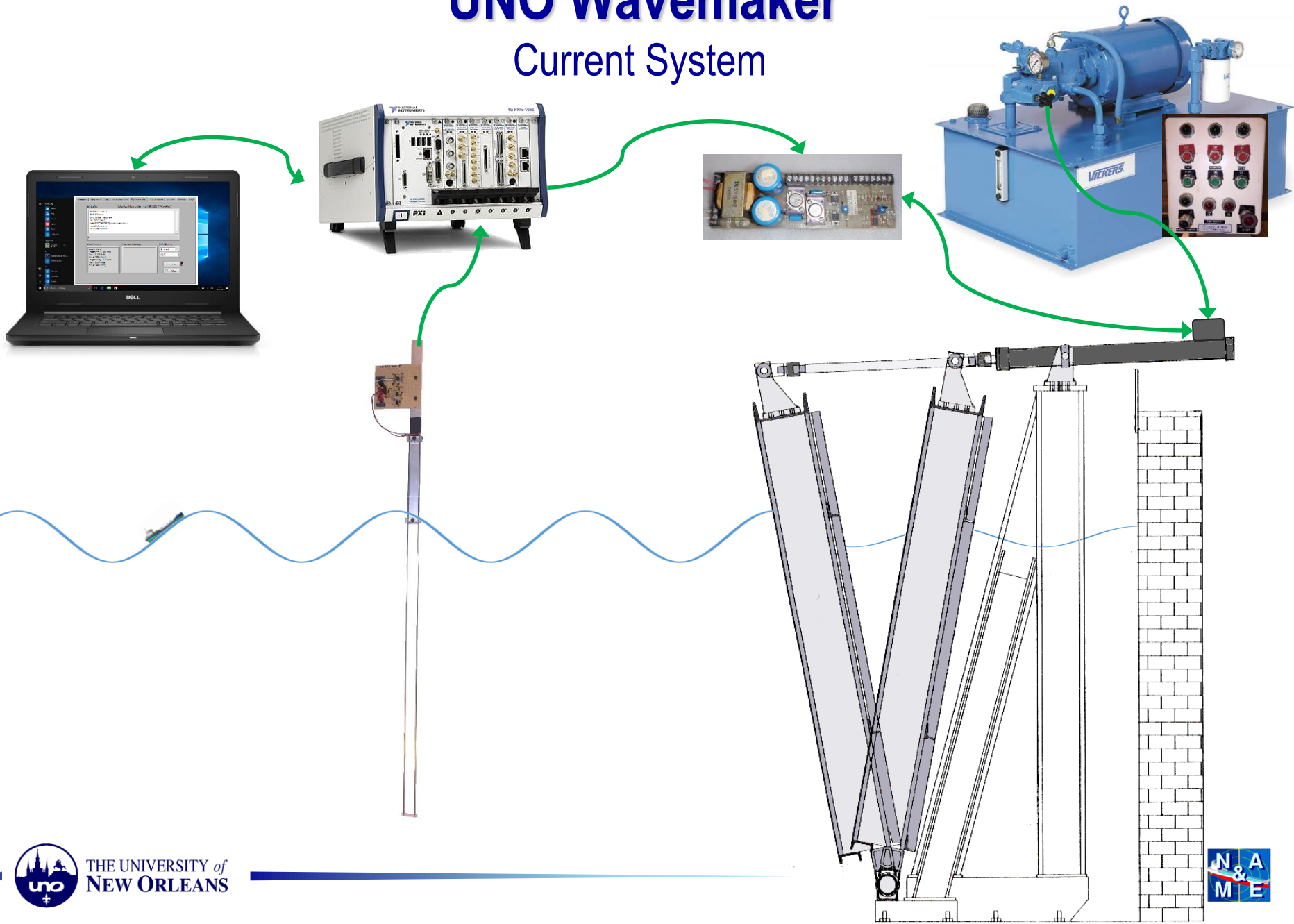


# UNO Wavemaker

wave packet 20ft from wavemaker



# UNO Wavemaker Current System



# UNO Wavemaker

## Future Work

### Theory

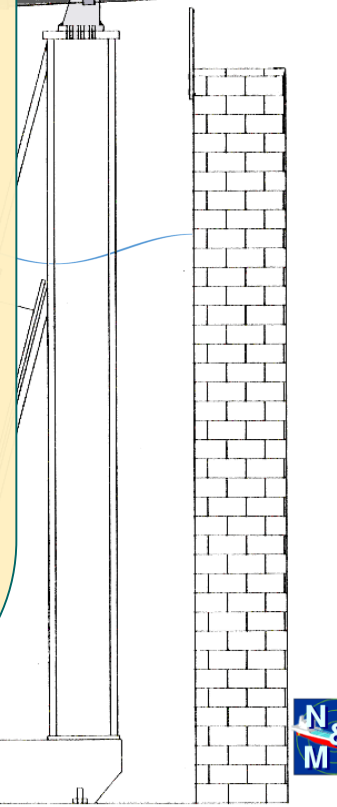
- Quantify limitations of LTI approach

### Software

- Control HPU
- Create wave files in application
- Automate series of tests
- Simulate waves from wave files

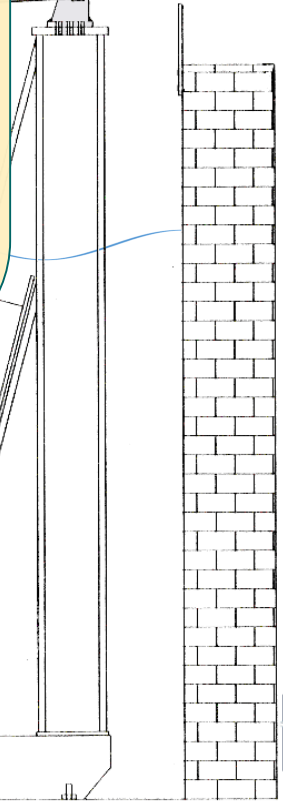
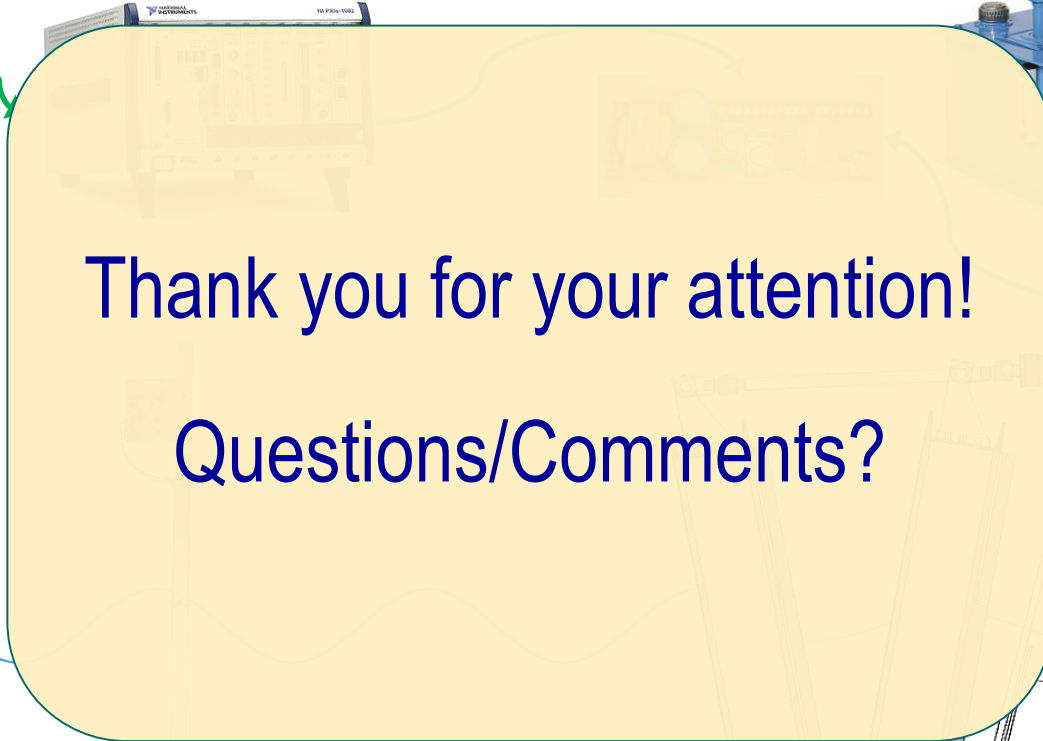
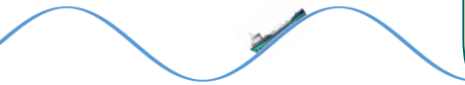
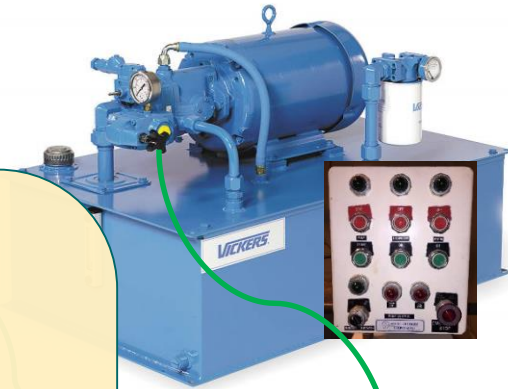
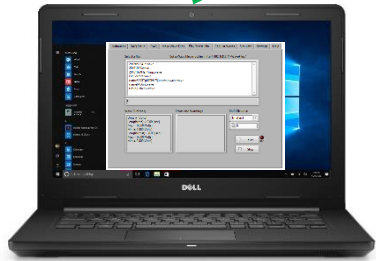
### Hardware

- Reduce Noise of HPU
- Create PCBs for wave probes
- Improve wave probe mounting and calibration hardware



# UNO Wavemaker Current System

Thank you for your attention!  
Questions/Comments?





# Backup Slides

Text box

# UNO Wave Probes

## Conductance Wave Probes

Theory:

Conductance,  $G$ , between submerged conductive probes is

$$G = z \frac{\pi d K}{D}$$

$z$  = immersion depth

$D$  = separation distance

$d$  = wire diameter

$K$  = conductivity of fluid

$$G \propto z$$

Conductance is  
proportional to  
immersion depth



# UNO Wave Probes

## Conductance Wave Probes

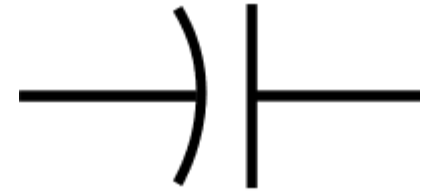
### Functional Description

- Two stainless steel rods 1" apart are partially immersed.
- An AC voltage is placed across the probes.
- The current through the circuit is measured, rectified, and filtered.
- The resulting signal  $\propto$  wave elevation.



# UNO Wave Probes

## Capacitance Wave Probes



### Capacitance Wave Probes

- Capacitance varies linearly with immersion
- Signal conditioning converts capacitance to voltage

Insulated  
Conductor

The water and insulated conductor act as two “plates” of a capacitor.

As immersion changes, the area between the two plates changes, changing the capacitance.

Conductive Frame

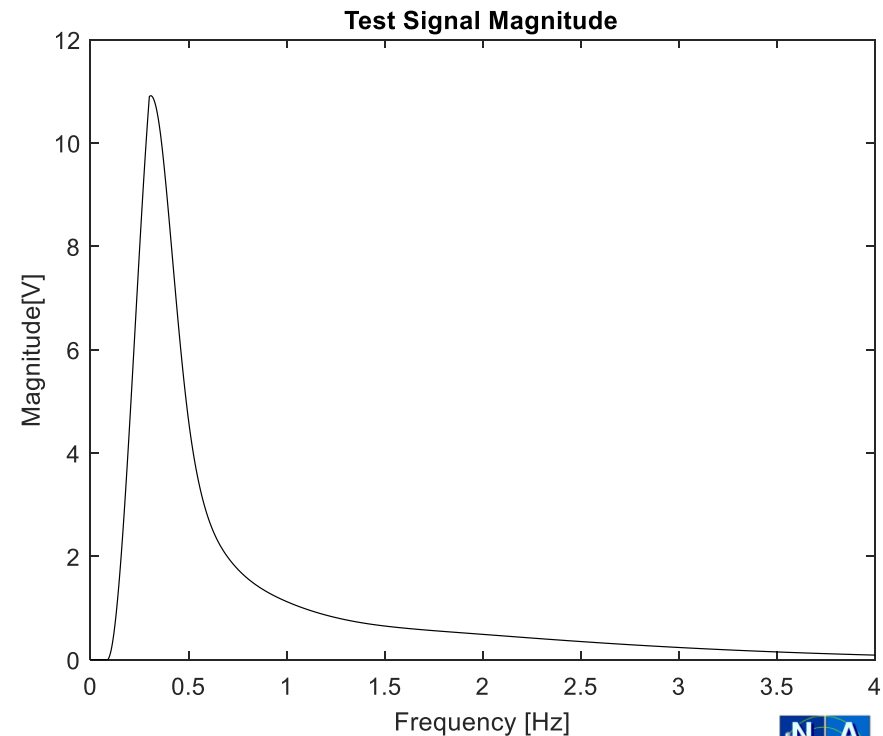
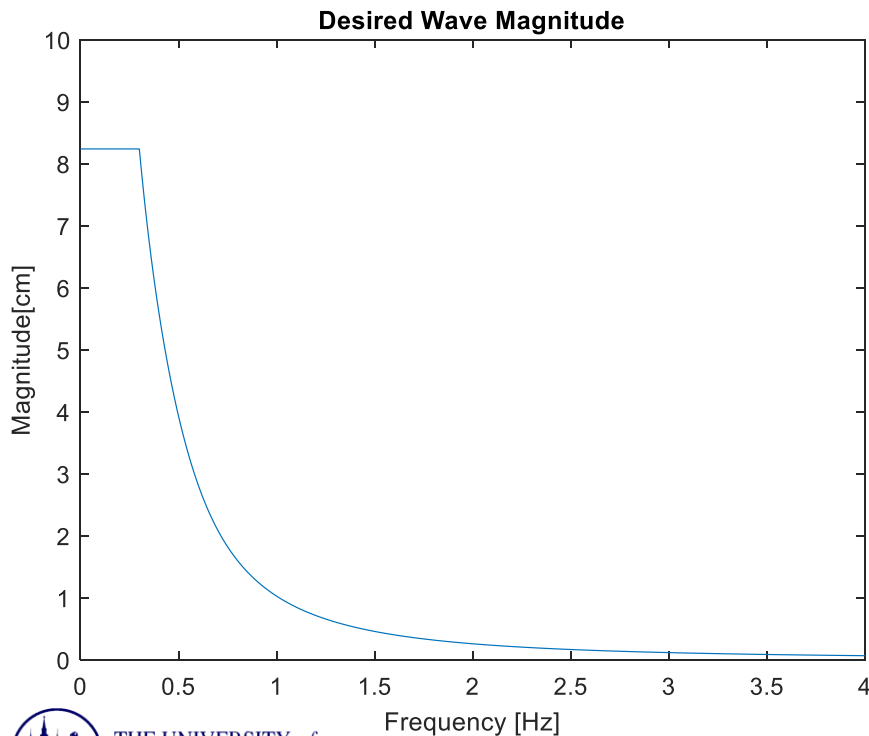


# UNO Wavemaker

## System Identification

Defined a desired wave elevation magnitude,  $H(f) = \frac{\text{Wavelength}}{\text{Constant}}$   
for a constant wave steepness.

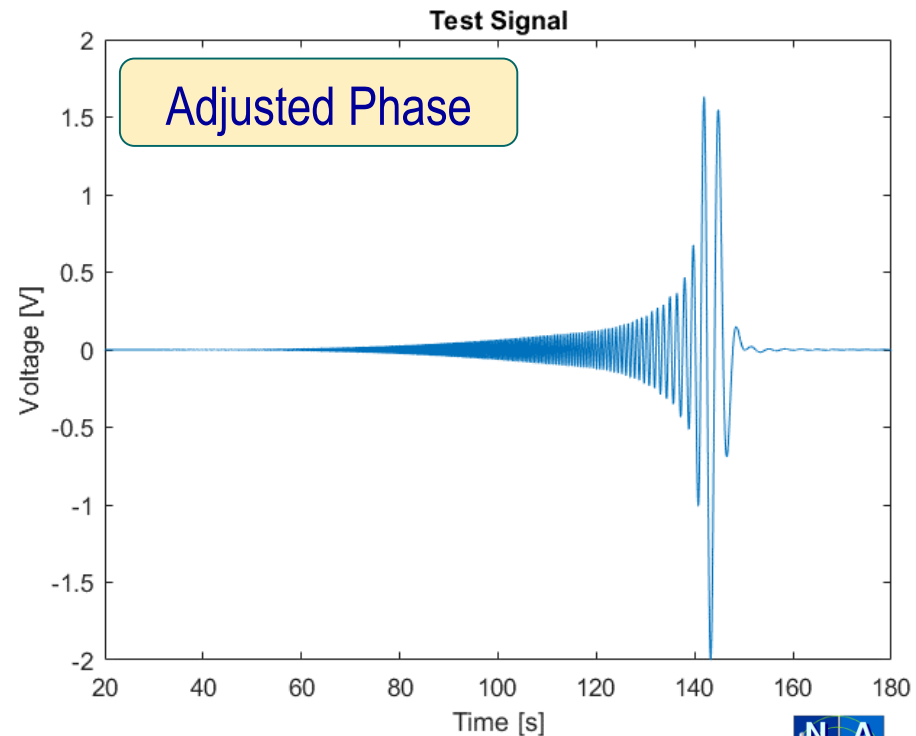
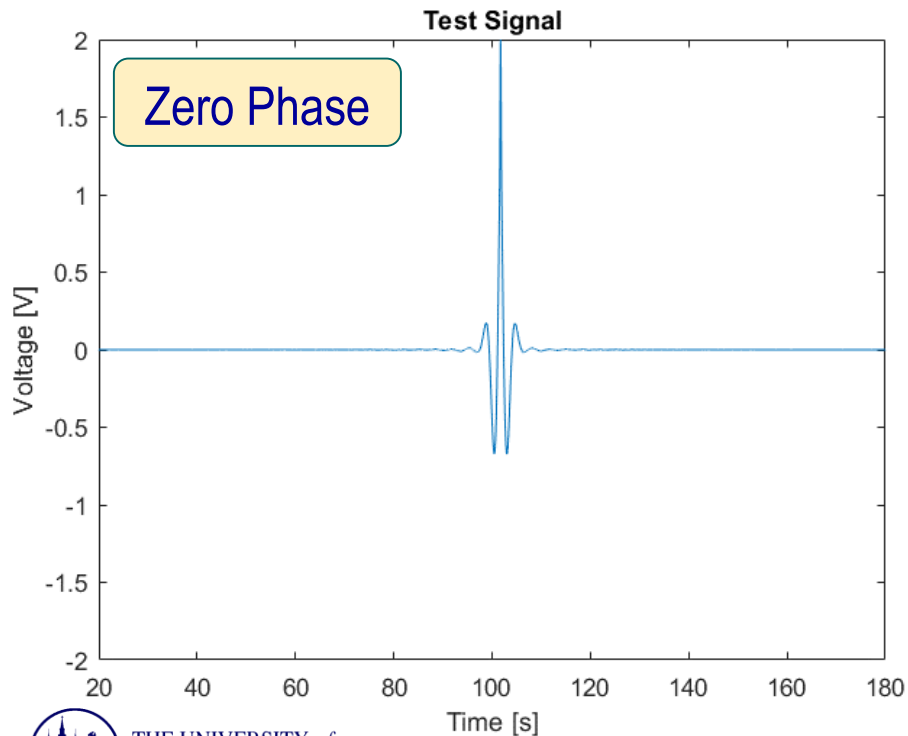
Determined a command signal based on a transfer function estimate.



# UNO Wavemaker

## System Identification

The phase of the test signal was chosen such that the entire wave would pass the wave probe before reflections from the end of the tank returned. This is based on the wave celerity equations.



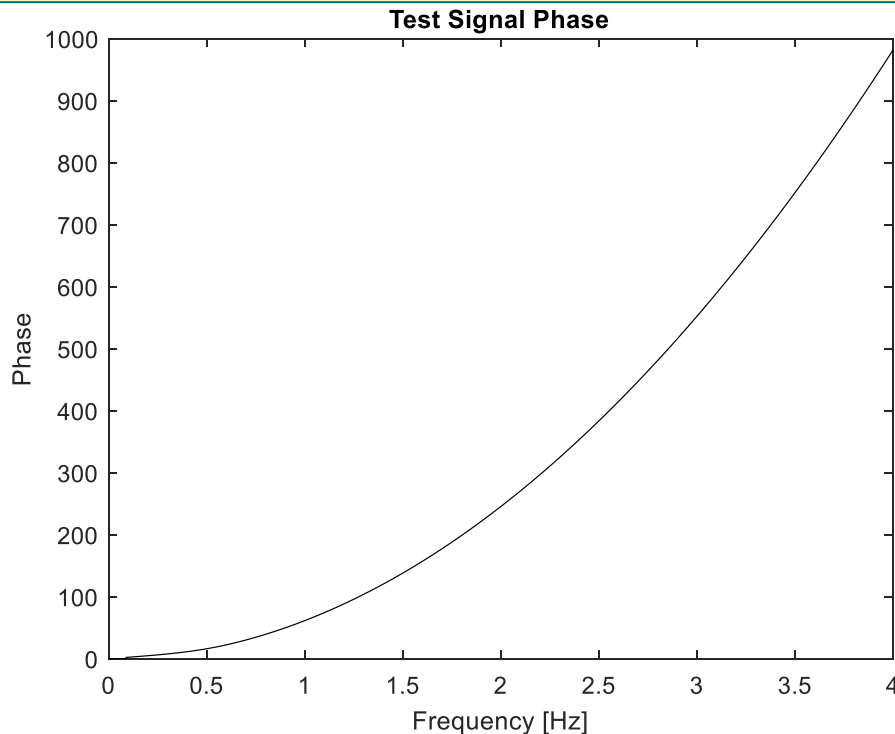


# UNO Wavemaker

## Wavemaker Theory

Designing the test signal  $v(t)$

Based on wave celerity and wave probe position, the phase of the signal was chosen to locate the concentration point past the probe.

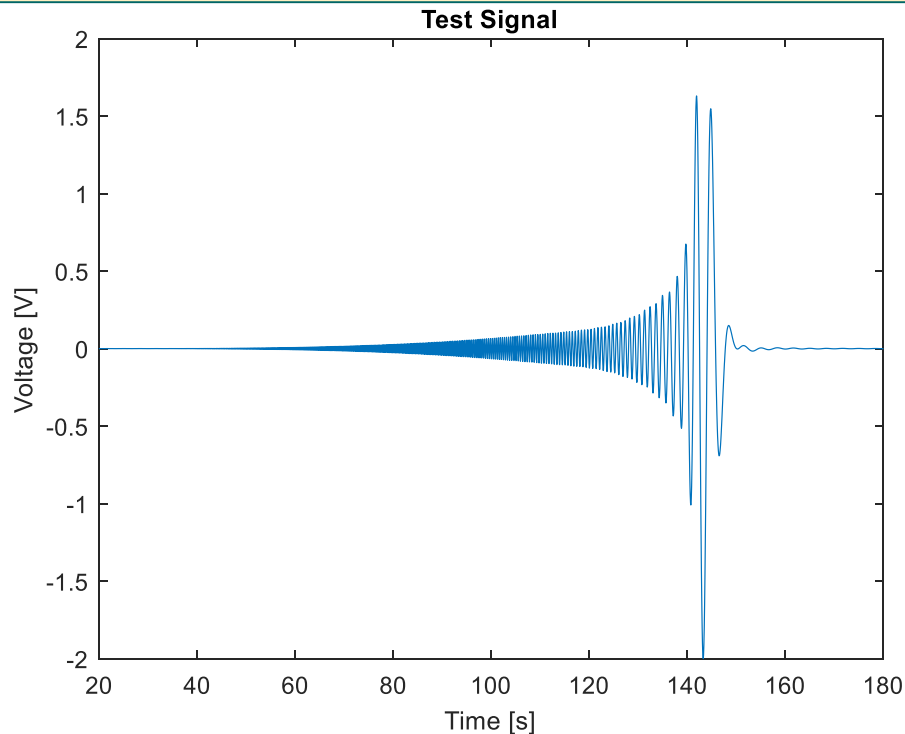


# UNO Wavemaker

## Wavemaker Theory

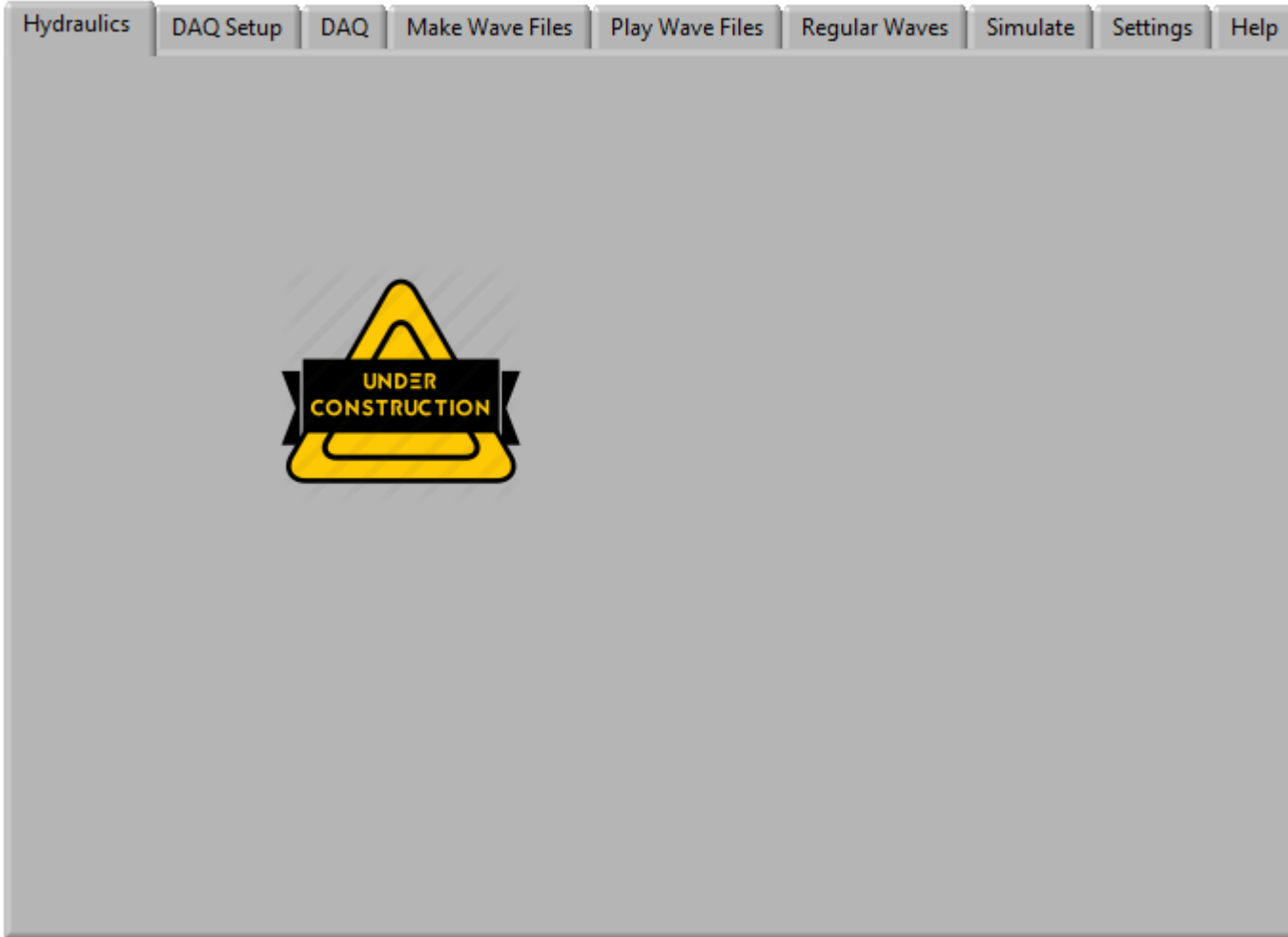
Designing the test signal  $v(t)$

Combing the magnitude and phase, then taking the inverse Fourier transform yields the time domain test signal.



# UNO Wavemaker

## User Interface



To Come:

Hydraulic Interface

Make Wave Files

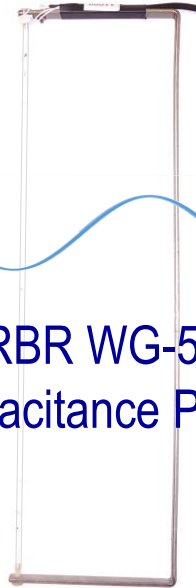
Simulate Waves

# UNO Wave Probes

## Wave Probe Comparison



Arctec  
Capacitance Probe



RBR WG-50  
Capacitance Probe



Senix Ultra-S  
Ultrasonic

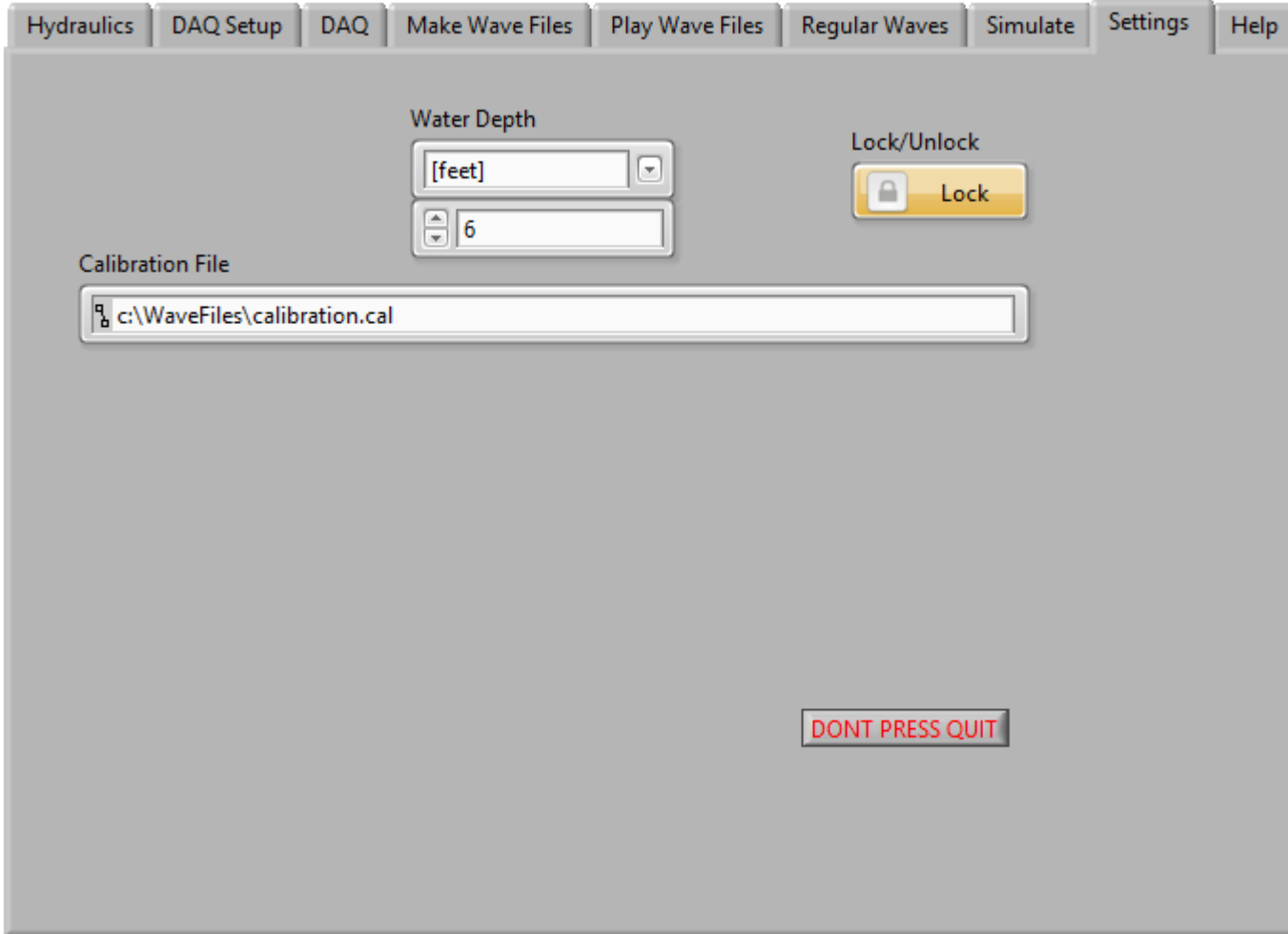


UNO  
Conductance Probe



# UNO Wavemaker

## User Interface



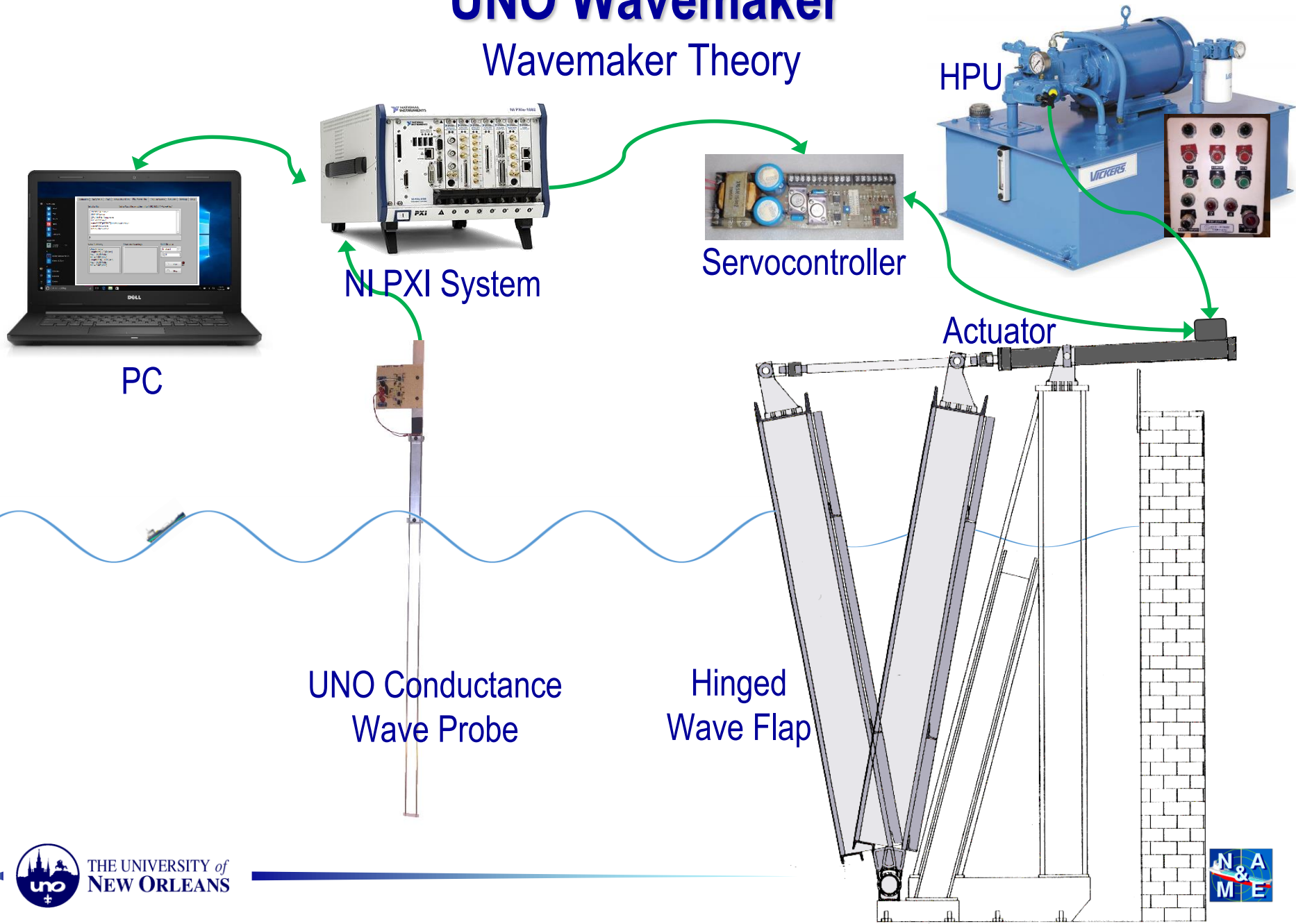
Settings

Water Depth

Calibration File

# UNO Wavemaker

## Wavemaker Theory





# UNO Wavemaker

## Wavemaker Theory



NI PXI System

Command  
 $v(t)$



Servocontroller

One objective of the software is to provide the appropriate Command signal  $v(t)$  to produce a desired Wave Elevation  $h(t)$ .

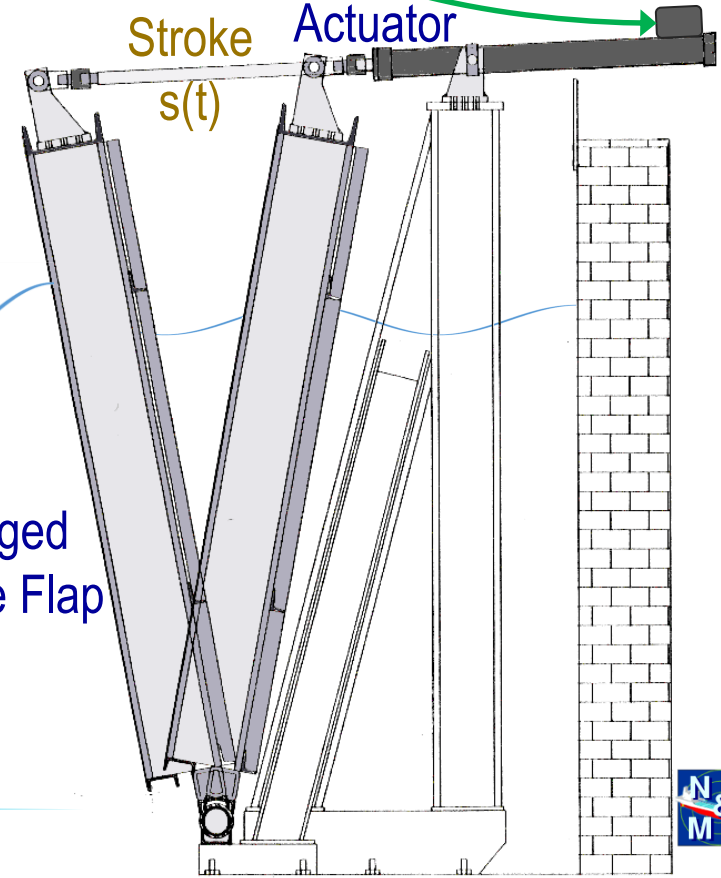
The desired wave time series  $h(t)$  is described by the user in a \*.wave file.

Wave Elevation  
 $h_L(t)$

Stroke  
 $s(t)$

Actuator

Hinged  
Wave Flap

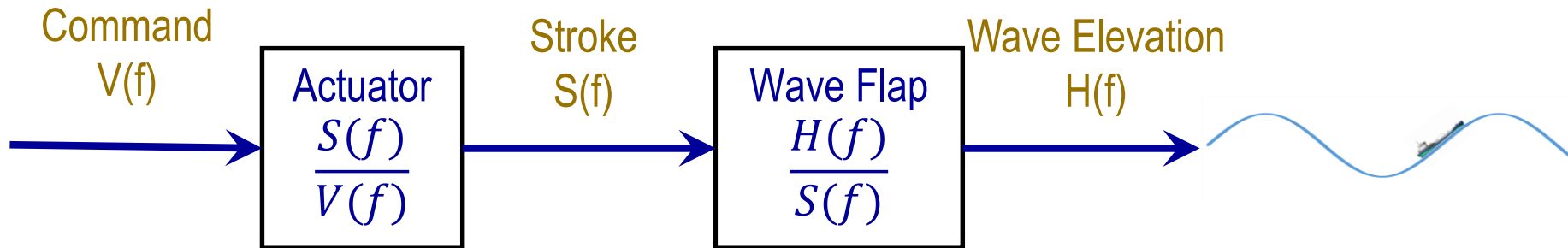


# UNO Wavemaker

## Wavemaker Theory

The Wavemaker can be modeled as a linear system.

Transfer Function Block Diagram of System

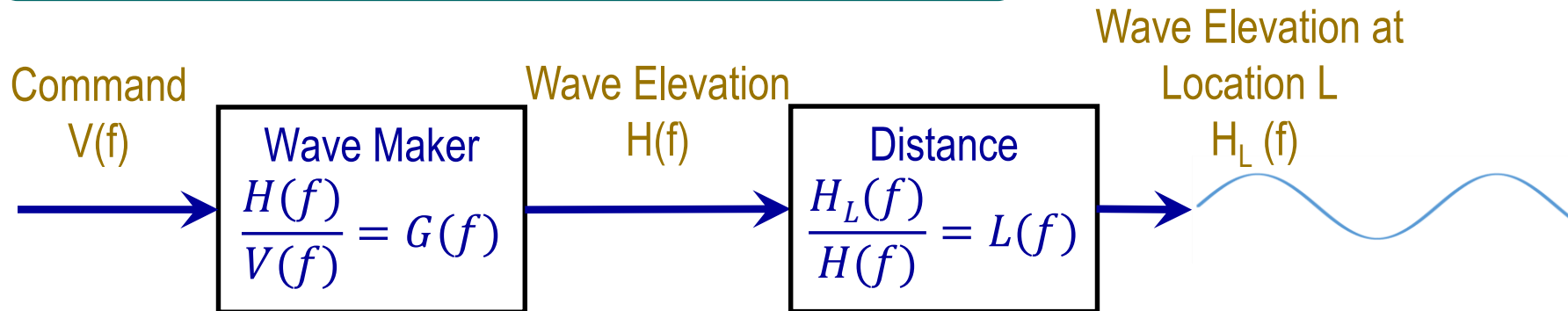


Biesel and Suquet 1954 describe the magnitude of this TF

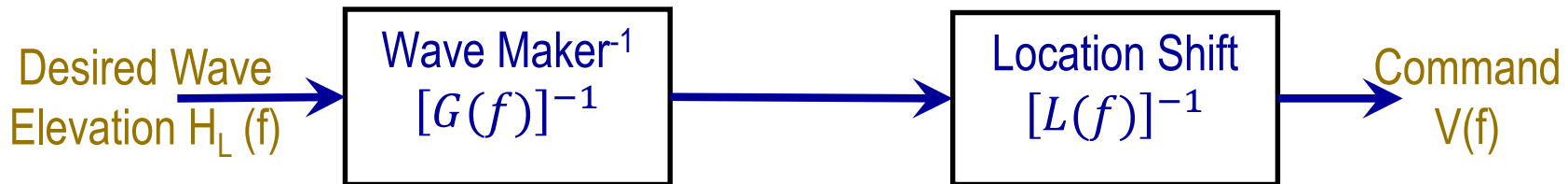
# UNO Wavemaker

## Wavemaker Theory

### Wavemaker Transfer Function Block Diagram



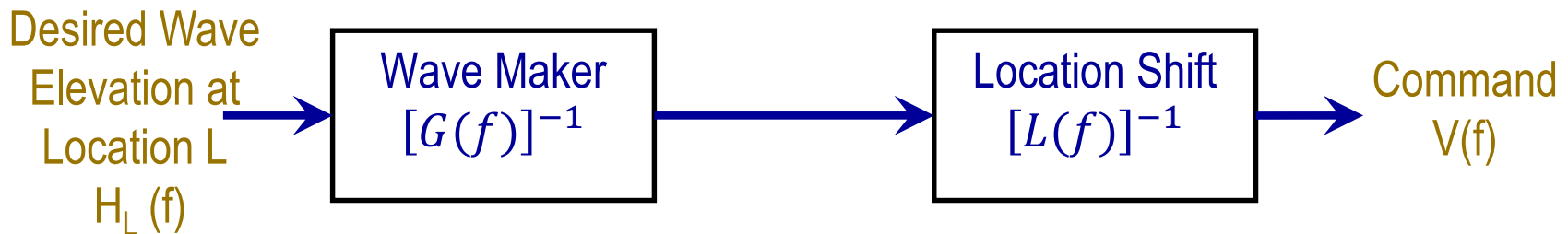
To Calculate the Command Signal from the desired wave the Inverse Transfer Function was determined.



# UNO Wavemaker

## Wavemaker Theory

### Inverse Transfer Function Block Diagram

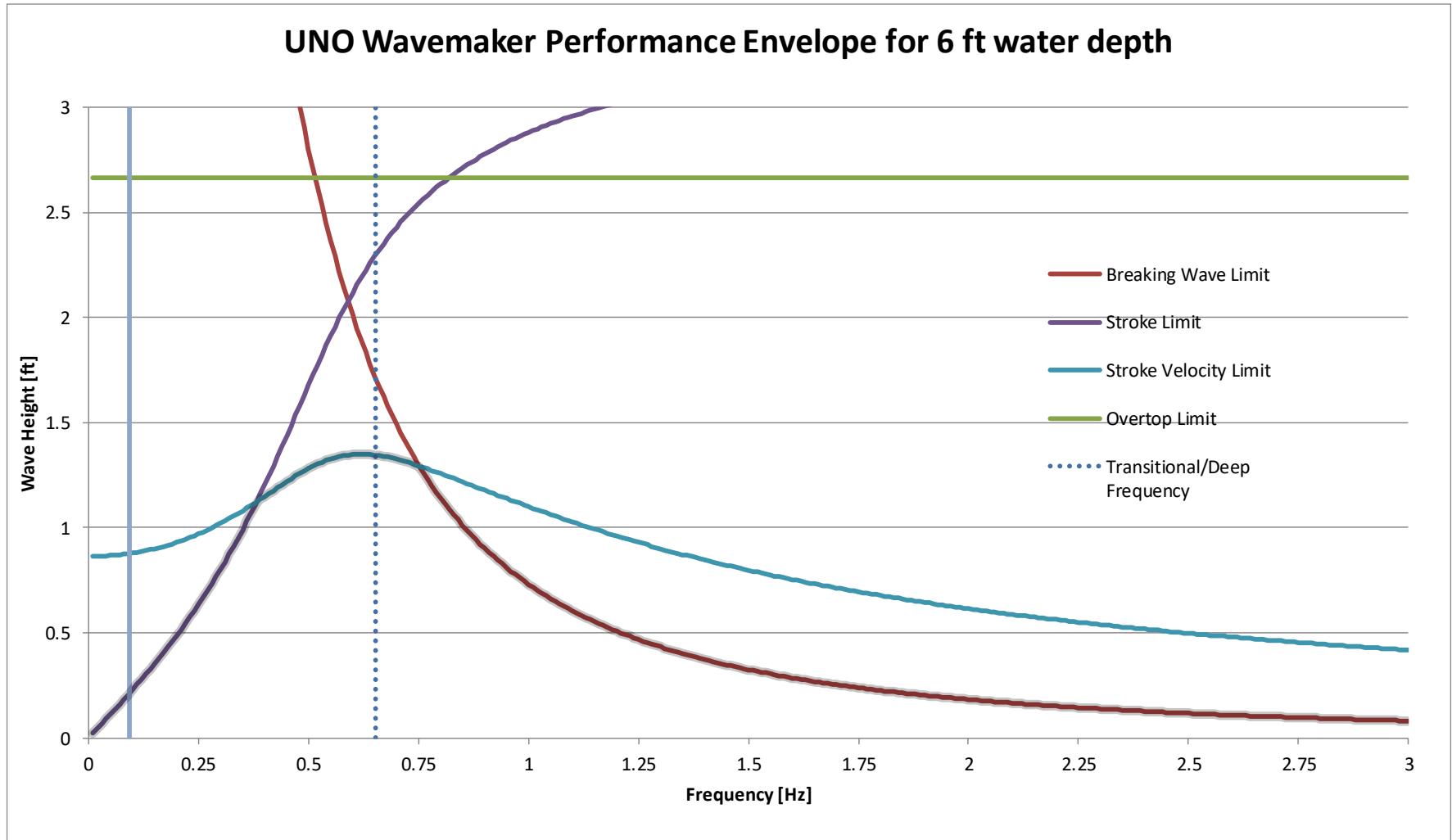


The time domain representation of the  $[G(f)]^{-1}$  is used to create the Basin Calibration File, \*.cal.

The location shift is calculated based on the given distance and wave celerity. It is implemented as an all-pass filter.

# UNO Wavemaker

## Wavemaker Envelope



# UNO Wavemaker

## Wavemaker Envelope

