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THE SOLUTION OF THE ORDER EQUATIONS OF A FOUR-POINT,
FOURTH ORDER, TWO-STEP RUNGE-KUTTA METHOD

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The solution of the order equations of a four-point, fourth order, two-step Runge-Kutta method

by

P.A. Beentjes

ABSTRACT

In this report we present solutions of the order equations of a class of four-point, fourth order, two-step Runge-Kutta method. The solutions include possible variation of integration steps.

KEY WORDS & PHRASES: *Differential equations, explicit Runge-Kutta methods.*

1. STATEMENT OF THE PROBLEM

In [1] VAN DER HOUWEN presents the following multipoint two-step Runge-Kutta method

$$(1.1) \quad \vec{y}_{n+1} = (a-1)\vec{y}_n + b\vec{y}_{n-1} + ch_n \vec{f}(\vec{y}_{n-1}) + \vec{y}_{n+1}^{(RK)},$$

where $\vec{y}_{n+1}^{(RK)}$ is the result of a single-step Runge-Kutta formula which can be characterized by the array of Runge-Kutta parameters

$$A = \begin{pmatrix} \lambda_{10} & \cdot & \cdot & 0 \\ \vdots & & & \\ \lambda_{m-1} & 0 & \cdot & \lambda_{m-1} \quad m-2 \\ \theta_0 & \cdot & \cdot & \theta_{m-2} \quad \theta_{m-1} \end{pmatrix}.$$

Fourth order consistency of (1.1) leads to the equations

$$(1.2) \quad a + b = 1,$$

$$(1.3) \quad \sum_{i=0}^{m-1} \theta_i = \alpha_0,$$

$$(1.4) \quad \sum_{i=1}^{m-1} \theta_i \mu_i = \frac{1}{2} \alpha_1,$$

$$(1.5) \quad \sum_{i=2}^{m-1} \theta_i \sum_{j=1}^{i-1} \lambda_{ij} \mu_j = \frac{1}{6} \alpha_2,$$

$$(1.6) \quad \sum_{i=1}^{m-1} \theta_i \mu_i^2 = \frac{1}{3} \alpha_2,$$

$$(1.7) \quad \sum_{i=3}^{m-1} \theta_i \sum_{j=2}^{i-1} \lambda_{ij} \sum_{k=1}^{j-1} \lambda_{jk} \mu_k = \frac{1}{24} \alpha_3,$$

$$(1.8) \quad \sum_{i=2}^{m-1} \theta_i \sum_{j=1}^{i-1} \lambda_{ij} \mu_j^2 = \frac{1}{12} \alpha_3,$$

$$(1.9) \quad \sum_{i=2}^{m-1} \theta_i \mu_i \sum_{j=1}^{i-1} \lambda_{ij} \mu_j = \frac{1}{8} \alpha_3,$$

$$(1.10) \quad \sum_{i=1}^{m-1} \theta_i \mu_i^3 = \frac{1}{4} \alpha_3,$$

where

$$\alpha_i = 1 - q^i (bq + (i+1)c), \quad i = 0, 1, 2, 3, \quad (q = -h_{n-1}/h_n),$$

and

$$\mu_i = \sum_{j=0}^{i-1} \lambda_{ij}, \quad i = 1(1)m-1.$$

Shanks has already given the complete solution of fourth order, four-point, single-step Runge-Kutta formulas (see [2]); in section 2 we will generalize these results for a four-point, fourth order formula using two steps in a similar way.

2. SOLUTION OF THE PROBLEM

We will consider three different types of solutions.

Case I. μ_1, μ_2 and μ_3 are distinct.

From (1.4), (1.6) and (1.10) follow

$$\theta_1 = \frac{\frac{1}{2} \alpha_1 \mu_2 \mu_3 - \frac{1}{3} \alpha_2 (\mu_2 + \mu_3) + \frac{1}{4} \alpha_3}{\mu_1 (\mu_2 - \mu_1) (\mu_3 - \mu_1)}$$

and similar expressions for θ_2 and θ_3 .

(1.5) and (1.9) lead to

$$(2.1) \quad \lambda_{31} \mu_1 + \lambda_{32} \mu_2 = \frac{\frac{1}{6} \alpha_2 \mu_2 - \frac{1}{8} \alpha_3}{\theta_3 (\mu_2 - \mu_3)}.$$

Next, from (1.8) and (2.1), we get

$$\lambda_{32} = \frac{\frac{1}{6} \alpha_2^{\mu_1} - \frac{1}{12} \alpha_3}{\theta_3^{\mu_2(\mu_1 - \mu_2)}} .$$

Now only (1.7) is not yet fulfilled. A straightforward calculation, using the expressions above, results in

$$\theta_3^{\lambda_{32}} \lambda_{21}^{\mu_1} = \frac{(\frac{1}{6} \alpha_2^{\mu_1} - \frac{1}{12} \alpha_3)(\frac{1}{6} \alpha_2^{\mu_3} - \frac{1}{8} \alpha_3)}{\frac{1}{2} \alpha_1^{\mu_1 \mu_3} - \frac{1}{3} \alpha_2^{(\mu_1 + \mu_3)} + \frac{1}{4} \alpha_3} = \frac{1}{24} \alpha_3 ,$$

and gives the following condition

$$\mu_3 = \frac{\alpha_2 \alpha_3}{4\alpha_2^2 - 3\alpha_1 \alpha_3} .$$

Thus, case I gives a two-parameter (μ_1, μ_2) family of solutions.

Case II. $\mu_1 = \mu_2$.

Defining $\tilde{\theta}_2 = \theta_1 + \theta_2$ it follows from (1.4), (1.6) and (1.10)

$$\tilde{\theta}_2 = \frac{\frac{1}{2} \alpha_1^{\mu_3} - \frac{1}{3} \alpha_2}{\mu_2(\mu_3 - \mu_2)} \quad (\text{similar expression for } \theta_3)$$

and

$$\mu_3 = \frac{\frac{1}{3} \alpha_2^{\mu_2} - \frac{1}{4} \alpha_3}{\frac{1}{2} \alpha_1^{\mu_2} - \frac{1}{3} \alpha_2} .$$

From (1.5) and (1.8) it is easily verified that

$$\mu_2 = \frac{\alpha_3}{2\alpha_2} ,$$

thus, giving as in case I,

$$\mu_3 = \frac{\alpha_2 \alpha_3}{4\alpha_2^2 - 3\alpha_1 \alpha_3} .$$

To obtain expressions for the remaining parameters we proceed as in case I. From (1.5) and (1.9) follow

$$\lambda_{31} + \lambda_{32} = \frac{\frac{1}{24} \alpha_3}{\theta_3 \mu_2 (\mu_3 - \mu_2)}$$

and

$$\lambda_{21} = \frac{\frac{1}{6} \alpha_2 \mu_3 - \frac{1}{8} \alpha_3}{\theta_2 \mu_2 (\mu_3 - \mu_2)} .$$

Finally we get from (1.7)

$$\lambda_{32} = \frac{\frac{1}{24} \alpha_3}{\theta_3 \lambda_{21} \mu_2} .$$

Thus, case II results in a one-parameter (e.g. θ_2) family of solutions.

Case III. $\mu_1 = \mu_3$.

Proceeding as in case I and case II, we find

$$\theta_3 = \tilde{\theta}_3 - \theta_1, \quad \tilde{\theta}_3 = \frac{\frac{1}{2} \alpha_1 \mu_2 - \frac{1}{3} \alpha_2}{\mu_3 (\mu_2 - \mu_3)} ,$$

$$\theta_2 = \frac{\frac{1}{2} \alpha_1 \mu_3 - \frac{1}{3} \alpha_2}{\mu_2 (\mu_3 - \mu_2)} ,$$

$$\lambda_{21} = \frac{\mu_2^2}{2\mu_3} ,$$

$$\lambda_{32} = \frac{\frac{1}{6} \alpha_2 \mu_3 - \frac{1}{12} \alpha_3}{\theta_3 \mu_2 (\mu_3 - \mu_2)} , \quad \lambda_{31} = \frac{\frac{1}{6} \alpha_2 - \theta_2 \lambda_{21} \mu_3 - \theta_3 \lambda_{32} \mu_2}{\theta_3 \mu_3} ,$$

$$\mu_2 = \frac{\alpha_3}{2\alpha_2} ,$$

$$\mu_3 = \frac{\alpha_2 \alpha_3}{4\alpha_2^2 - 3\alpha_1 \alpha_3} .$$

Case III also gives a one-parameter (e.g. θ_1) family of solutions.

We now show that the choice $\mu_2 = \mu_3$ leads to a contradiction. (1.4), (1.6) and (1.10) give the condition

$$(2.2) \quad \mu_1 = \frac{\frac{1}{3} \alpha_2 \mu_2 - \frac{1}{4} \alpha_3}{\frac{1}{2} \alpha_1 \mu_2 - \frac{1}{3} \alpha_2}.$$

(1.5) and (1.9) lead to $\mu_2 = \frac{3\alpha_3}{4\alpha_2}$, which, substituted in (2.2) delivers $\mu_1 = 0$. But $\mu_1 = 0$ contradicts with (1.7).

3. EXAMPLES

Below, we present two schemes, both representing case II of section 2.

(i) $b=1, c = \frac{1}{3}, q = -1.$

These values lead to the following formula

$$\vec{y}_{n+1} = -\vec{y}_n + \vec{y}_{n-1} + \frac{1}{3} h \vec{f}(\vec{y}_{n-1}) + \vec{y}_n^{(RK)},$$

with

$$\Lambda = \begin{bmatrix} \frac{2}{3} & & & 0 \\ \frac{1}{3} & \frac{1}{3} & & \\ \frac{1}{4} & 0 & \frac{3}{4} & \\ \frac{4}{3} & 0 & 0 & \frac{1}{3} \end{bmatrix}.$$

(ii) $b = .3, c = .1, q = -1.$

The scheme is given by

$$\vec{y}_{n+1} = .3(\vec{y}_{n-1} - \vec{y}_n) + .1 h \vec{f}(\vec{y}_{n-1}) + \vec{y}_n^{(RK)}$$

and

$$\Lambda = \begin{pmatrix} \frac{11}{20} & & & 0 \\ 0 & \frac{11}{20} & & \\ \frac{330}{10609} & \frac{66000}{1092727} & \frac{1067000}{1092727} & \\ \frac{3717913}{7042200} & \frac{9100}{35211} & \frac{9100}{35211} & \frac{1092727}{7042200} \end{pmatrix} .$$

Note, that the choice $q = -1$ refers to constant step integration. Furthermore, we remark that the term $-\vec{y}_n$ (of scheme (i)) and the term \vec{y}_n appearing in $\vec{y}_n^{(RK)}$, cancel out.

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