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# Stochastic integrals and goodness-of-fit tests

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# Preface

I was first introduced to the subject of this book by Wim Albers in 1986. He showed me an early version of Akritas (1988), in which an apparently completely new  $\chi^2$ -test in the random censoring model was described. In the classical i.i.d. model the  $\chi^2$ -test statistic reduced to a simple functional of a process which was an intriguing transformation of the empirical distribution function.

Shortly after that, I learned more about this process from several other seemingly independent sources [in the end all sources trace back to Aalen (1976)]. In Aki (1986) the process was attributed to the innovation approach in Khmaladze (1981), and in Shorack and Wellner (1986) two chapters were dedicated to “the basic martingale”.

Provided that  $T$  is not too large, the basic martingale behaves on the interval  $[0, T]$  as a linear transformation of some empirical process. The recognition of this fact led to Einmahl and Koning (1992), in which several results for the empirical process were transferred to stochastic integrals with respect to the basic martingale. A main tool was a strong approximation on the interval  $[0, T]$ .

The work on that paper made the usefulness of a more general strong approximation clear to me, so I started investigating the interval  $[0, \infty)$ . A major difficulty is that on this interval the basic martingale no longer behaves as a linear transformation of an empirical process. As Theorem 2 on page 26 shows, this difficulty can be taken care of. In fact, Theorem 2 goes somewhat further than a strong approximation, since it also presents an exponential inequality governing the approximation. The combination of an approximation and an exponential inequality is referred to as a KMT-type inequality.

The major theme of this book is the statistical application of the KMT-type inequality Theorem 2, especially in the areas of testing, estimation, deviations, and efficiencies. In Chapter 1 an overview is presented. Some basic tools are described in Chapter 2. The theory is developed in Chapters 3 and 4, applied to the problem of testing exponentiality in Chapter 5, and supported by computer simulations in Chapter 6.

ALEX J. KONING

*May 1993*



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# Chapter 1

## An overview

This chapter is meant to provide an overview of the remainder of the book. Although some technical elements are outlined in section 1.9, the interested reader should consult the other chapters for full detail.

### 1.1 Introduction

The complexity of the finite sample distribution of a test statistic often makes approximation necessary. In most cases approximations are motivated by weak convergence arguments. However, such arguments fail to give insight into the accuracy of the approximation. Typically, the approximations are poor in the tail of the distribution, the region which is of importance in determining critical regions and probability values.

This book discusses the use of the approximation theory of Komlós, Major and Tusnády (1975) to construct approximations for test statistics themselves, rather than for their distribution functions. The accuracy of the approximations is indicated by accompanying probability inequalities.

These probability inequalities imply weak convergence. In fact, they have consequences which go far beyond weak convergence, such as deviation results [see section 1.2]. Thus, one may view the inequalities as refinements of the implied weak convergence results.

The test statistics considered mainly occur in the random censoring model, and are of the goodness-of-fit type. Section 1.2 pays some attention to goodness-of-fit tests in the i.i.d. model.

In section 1.2 the approximation of empirical processes is described. Sections 1.3 and 1.4 introduce the notion of KMT-type inequalities and the random censoring model, respectively. Section 1.5 addresses testing the simple null hypothesis. The transition to the composite null hypothesis, the subject of section 1.8, is made in sections 1.6 and 1.7.

## 1.2 KMT-inequalities for empirical processes

Many tests for assessing the fit of a cumulative distribution function  $F(t)$  to an i.i.d. sample are based on the empirical distribution function  $F_n$  of the sample. A vast majority of these so-called EDF tests have test statistics which can be expressed in terms of the empirical process

$$U_n(t) = n^{1/2}\{F_n(t) - F(t)\}. \quad (1.1)$$

Obviously, empirical process theory has direct implications for this class of EDF tests.

If the sample indeed originates from the distribution  $F$ , then it is noticed in Doob (1949) that as the sample size  $n$  tends to infinity, the empirical process seems to behave more and more as a familiar Gaussian process, Brownian bridge [with time  $F(t)$ ]. This observation has provided the inspiration for the so-called Empirical Central Limit Theorem [ECLT], which tells us that the empirical process converges in distribution to a Brownian bridge. The ECLT appears as Theorem 1 on page 19 of this book.

Although the ECLT is a very useful device, it only describes the asymptotic behavior of the empirical process. Hence, the question arises how well a Brownian bridge approximation to the empirical process performs for finite samples. This question was answered by Komlós, Major and Tusnády (1975) by giving their famous probability inequality, which appears as Inequality 2 on page 19.

Within the class of empirical process EDF tests there is the important subclass of tests based on statistics of the form  $T(U_n)$ , where  $T$  is a Lipschitz functional [see Definition 2 on page 27]. As examples of members of this subclass we mention Kolmogorov-Smirnov, Cramér-von Mises and  $\chi^2$  tests. Since according to the probability integral transformation we may take  $U_n$  and  $B_n$  to be equal to  $\tilde{U}_n \circ F$  and  $\tilde{B}_n \circ F$ , Inequality 2 implies that

$$P(|T(U_n) - T(B_n)| > c_T n^{-1/2}(c_2 \log n + x)) \leq c_3 \exp\{-c_4 x\}. \quad (1.2)$$

Hence, if we know the distribution of  $T(B_n)$  then we may use the KMT-inequality to bound probability values  $P(T(U_n) > x)$ .

The KMT-inequality implies that the difference between  $P(T(U_n) > x)$  and  $P(T(B_n) > x)$  soon becomes negligible if  $n$  tends to infinity, provided that  $x$  is kept fixed. However, if  $x$  tends to infinity and  $n$  is kept fixed,  $P(T(B_n) > x)$  typically behaves as  $\exp\{-ax^2\}$  for some  $a > 0$ , whereas the difference between  $P(T(U_n) > x)$  and  $P(T(B_n) > x)$  as indicated by the KMT-inequality behaves as  $\exp\{-bx\}$  for some  $b > 0$ . This difference will eventually become much larger than  $P(T(B_n) > x)$ . Thus, the usefulness of the KMT-inequality for bounding probability values depends on whether we let  $n$  or  $x$  tend to infinity.

This immediately raises the question what will happen if we let  $n$  and  $x$  simultaneously tend to infinity. In other words: what can be said about the

difference between  $P(T(U_n) > x_n)$  and  $P(T(B_n) > x_n)$  as  $n$  tends to infinity, and  $P(T(B_n) > x_n)$  behaves as  $\exp\{-a(x_n)^2\}$ ? This question is addressed in Inglot and Ledwina (1990) and Inglot, Kallenberg and Ledwina (1989).

It turns out that in case  $x_n \rightarrow \infty$  and  $x_n = o(n^{1/2})$  the difference becomes negligible with respect to  $P(T(B_n) > x_n)$ . Observe that in this situation  $P(T(U_n) > x_n)$  also behaves as  $\exp\{-a(x_n)^2\}$ . In mathematical statistics this is known as a deviation result. Deviation results are important in the evaluation of statistical tests, and are classified according to the rate at which  $x_n$  is allowed to converge to infinity. A moderate deviation result allows  $x_n = \mathcal{O}((\log n)^{1/2})$ , and is required in the computation of weak intermediate efficiency [see Kallenberg (1983)]. A Cramér type deviation result allows  $x_n = o(n^{1/6})$ , and is required in the computation of intermediate efficiency [see Kallenberg (1983)]. A Chernoff type deviation result allows  $x_n = \mathcal{O}(n^{1/2})$ , and is required in the computation of Bahadur efficiency [see Bahadur (1960)]. Observe that the deviation result implied by the KMT-inequality just falls short of being Chernoff type.

For the interesting examples of test statistics  $T(U_n)$  the deviation result just described was already known before. However, the earlier work on deviations of  $T(U_n)$  consists of separate results. A clear advantage of the KMT-inequality is that it enables a unified approach.

### 1.3 KMT-type inequalities

The KMT approach to the EDF statistics sketched above may be extended to statistics based on other stochastic processes. In particular, we are interested in statistics of processes  $Q_n(t)$  for which there exist a sequence of identically distributed approximating Gaussian processes  $W_n(t)$  such that the KMT-type inequality

$$P\left(\sup_{t \in [0, \infty)} |Q_n(t) - W_n(t)| > n^{-\gamma}(c_2 \log n + x)^\tau\right) \leq c_3 \exp\{-c_4 x\} \quad (1.3)$$

holds for  $0 < \gamma \leq 1/2$  and  $\tau > 0$ .

By setting  $x$  equal to  $\log n$ , it is easily seen that the supremum over  $t$  of  $Q_n(t) - W_n(t)$  remains bounded in probability, even after multiplication by  $n^\gamma(\log n)^\tau$ . This implies that  $Q_n$  converges weakly to a Gaussian process having the same distribution as  $W_1$ .

Although  $Q_n$  is asymptotically Gaussian, the asymptotic distribution of the statistic  $T(Q_n)$  is in general non-normal. Asymptotic Pitman efficacy can be defined for non-normal test statistics [see Rothe (1981)], but has the undesirable property of depending on the size of the test. Moreover, its computation is in most cases extremely troublesome. This makes it rather impracticable to use asymptotic Pitman efficacy to evaluate test statistics based on  $Q_n$ .

From the proof of Theorem 3 on page 43 we may infer that inequality (1.3) yields a deviation result for  $T(Q_n)$  allowing  $x_n = o(n^{\gamma/(2\tau-1)})$ , provided that

$P(T(Q_n) > x)$  behaves as  $\exp\{-ax^2\}$  for  $n$  tending to  $\infty$ . Deviation results shed light on the “tail” behavior of the approximation. Hence, we may view the number  $\gamma/(2\tau - 1)$  as an indicator of tail accuracy. It should be as high as possible.

The implications of KMT-type inequalities for intermediate efficiency and for the equivalence of limiting approximate Bahadur efficiency and limiting Pitman efficiency are discussed in Kallenberg and Koning (1993) [see also Appendix A]. Here the ratio  $\gamma/\tau$  is of importance.

In later sections in this chapter KMT-type inequalities for processes occurring in the random censoring model are described. The distribution of the approximating Gaussian process is in some cases omitted from the description, since it can be quite complex. Thus, our main focus in this chapter will be the accuracy of the approximation, as indicated by  $\gamma$  and  $\tau$ .

## 1.4 Censoring

In the analysis of failure time data we are interested in the time passing between a first event and a second event. Sometimes a third event makes the observation of the second event impossible. In this situation we only know a lower bound to the actual failure time. It follows that we have two types of observations, which we call “uncensored” or “censored”, depending on whether the second event is observed.

Techniques for the analysis of failure time data should distinguish between these two types of observations. Hence, tests based on the empirical process are in general not applicable.

Nevertheless, an abundance of tests is available for failure time data. A striking feature of the leading tests is that the central role of the empirical process has been taken over by another stochastic process, which was named the basic martingale in Shorack and Wellner (1986). This process will be discussed in later sections.

In what follows we shall assume that the so-called random censoring model holds. In this model we have two independent sequences  $X_1, \dots, X_n$  and  $Y_1, \dots, Y_n$  of non-negative i.i.d. random variables which are observed indirectly by means of the sample  $(Z_1, \delta_1), \dots, (Z_n, \delta_n)$ , defined by

$$Z_i = X_i \wedge Y_i, \quad \delta_i = 1_{\{X_i \leq Y_i\}}.$$

The distribution of  $X_i$  is of interest.

It is convenient to represent the sample  $(Z_1, \delta_1), \dots, (Z_n, \delta_n)$  by means of the empirical distribution functions

$$H_n^1(t) = n^{-1} \sum_{i=1}^n 1_{\{Z_i \leq t, \delta_i=1\}}, \quad H_{n-}(t) = n^{-1} \sum_{i=1}^n 1_{\{Z_i < t\}}. \quad (1.4)$$

One may show that results obtained under the random censoring model continue to hold if the random variables  $Y_1, \dots, Y_n$  are degenerated in  $+\infty$ . In this case the random censoring model reduces to the classical i.i.d. model.

## 1.5 Testing the simple null hypothesis

The fact that  $nH_n^1$  is a counting process provides the entry point for an approach of the random censoring model, which has become quite popular over the last fifteen years. A counting process is a nondecreasing process starting at zero, making jumps of length 1 at random points in time, and is constant elsewhere. To each counting process corresponds another stochastic process, referred to as the compensator, such that the difference between the counting process and its compensator has the martingale property: the conditional expectation of the process at some time  $t$  given all events occurring before time  $s < t$  is equal to the value attained by the process at time  $s$ . Observe that multiplying a martingale by a fixed constant does not affect the martingale property.

Let  $P_n$  be the probability measure generated by the pairs of random variables  $(X_1, Y_1), \dots, (X_n, Y_n)$ . Suppose there exists a cumulative distribution function  $F$ , indexed by  $\theta$  belonging to some set  $\Theta$ , such that  $P_n(X_1 \leq t) = F(t; \theta_n)$  for some  $\theta_n \in \Theta$ . Typically,  $\Theta$  is a very large class of distribution functions.

Now, suppose we are interested in testing the simple null hypothesis that  $\theta_n$  equals  $\theta_0$ , where  $\theta_0$  is some element of the set  $\Theta$ .

Let  $\Lambda(t; \theta)$  denote  $-\log(1 - F(t; \theta))$ , the cumulative hazard function belonging to  $F(t; \theta)$ . The counting process  $nH_n^1$  has compensator  $n \int_0^t (1 - H_{n-}(s)) d\Lambda(s; \theta_n)$ . The basic martingale

$$M_n(t; \theta_0) = n^{1/2} \left\{ H_n^1(t) - \int_0^t (1 - H_{n-}(s)) d\Lambda(s; \theta_0) \right\}, \quad (1.5)$$

is the difference between  $nH_n^1$  and its compensator under the null hypothesis, multiplied by  $n^{-1/2}$ . If the null hypothesis holds, then the basic martingale behaves approximately as a Wiener process with time

$$H^1(t; \theta_0) = \int_0^\infty P_n(Y_1 > s) dF(s; \theta_0). \quad (1.6)$$

Although this can be shown by Rebolledo's martingale central limit theorem, empirical process techniques [outlined briefly in section 1.9] are capable of providing a KMT-type probability inequality [with  $\gamma = 1/2$  and  $\tau = 2$ ]. Recall that KMT-type probability inequalities are refinements of central limit theorems.

Now that we are able to establish asymptotic properties of the  $M_n(t; \theta_0)$  without exploiting its martingale character, we may consider the martingale concepts discussed above merely as a natural way to arrive at a process which under the null hypothesis reflects the randomness in the sample. From a goodness-of-fit

0.0035, 0.0086, 0.0132, 0.0467, 0.0490\*, 0.0669, 0.0802, 0.0830, 0.1086,  
 0.1173, 0.1181\*, 0.1518\*, 0.1653\*, 0.1900\*, 0.2029\*, 0.2037, 0.2109\*, 0.2324,  
 0.2342, 0.2394, 0.2447\*, 0.2596\*, 0.2979\*, 0.3681, 0.4055, 0.5316\*.

Table 1.1: Data given in Woolson (1981). A suffix \* denotes that the observation was censored by the close of the study.

perspective the essential feature of  $M_n(t; \theta_0)$  is its functional dependence on the null hypothesis value of the parameter [just like the functional dependence on  $\mu_0$  of the classical one-sample  $t$ -test]. Thus, if the null hypothesis does not hold there is no guarantee that the null hypothesis behavior will still apply. Actually, drastically different behavior is what we are hoping for, since this will facilitate distinguishing between the null and the alternative hypothesis.

Observe that  $M_n(t; \theta_0)$  shares a time-transformation property with the empirical process: if we transform the data by applying a function  $\xi$  which is increasing almost everywhere with respect to  $F(t; \theta_0)$ , then the “new” basic martingale equals  $M_n(\xi(t); \theta_0)$ . Thus this type of transformation only has the effect of altering the time-scale.

There is one special transformation which stands out because of its simplifying effect. If the distribution  $F(t; \theta_0)$  is continuous, then transforming by applying the cumulative hazard function  $\Lambda(t; \theta_0)$  yields data which are under the null hypothesis standard exponentially distributed. This is convenient, since for testing standard exponentiality the basic martingale simplifies to

$$M_n(t; \theta_0) = n^{1/2} \{ H_n^1(t) - \int_0^t (1 - H_{n-}(s)) ds \}, \quad (1.7)$$

which is a spline function. Changes in slope relate to failure times, censored or uncensored. If a change in slope coincides with a jump, then the corresponding failure time is uncensored.

The transformation by means of the cumulative hazard function is exploited in Woolson (1981), where data obtained from a random sample of 26 psychiatric patients are analyzed. The random sample was drawn from all psychiatric patients who were first admitted to University of Iowa Hospitals during the years 1935-1948.

The cumulative hazard function was computed according to mortality tables for the State of Iowa. Observe that if there is no difference in mortality between the psychiatric patients and other residents of Iowa, then [and only then] the transformed data should have a standard exponential distribution, and hence the basic martingale takes the form (1.7). In Figure 1.1 this stochastic process is depicted.

Now the question arises whether Figure 1.1 corresponds to what we expect from the basic martingale under the null hypothesis. Informally, we could inspect

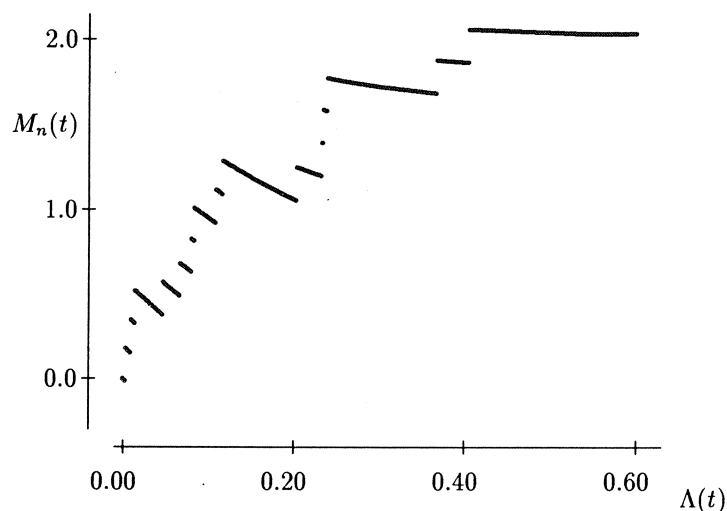


Figure 1.1: Basic martingale computed from [transformed] Woolson data.

Figure 1.1, having the properties of a Wiener process in mind. For instance, there is some drift away from the X-axis noticeable in the figure, which could be a sign that we are not dealing with a process close to a Wiener process. In other words: there is some reason to doubt the null hypothesis.

If we are not content with such loose findings, then a formal approach which uses the basic martingale to construct test statistics is more appropriate. In Woolson (1981) the test proposed by Breslow (1975) is applied. Fundamentally, the test of Breslow uses  $M_n(\infty; \theta_0)$  as test statistic. Under the null hypothesis  $M_n(\cdot; \theta_0)$  behaves approximately as a Wiener process with time  $H^1(\cdot; \theta_0)$  [see (1.6)], and thus  $M_n(\infty; \theta_0)$  behaves approximately as a normal random variable with mean 0 and variance  $H^1(\infty; \theta_0)$ . Because the distribution of  $Y_1$  is unknown, it becomes necessary to estimate  $H^1(\infty; \theta_0)$ . This is typically done using the estimator

$$\int_0^\infty (1 - H_{n-}(s)) d\Lambda(s; \theta_0) = \int_0^\infty (1 - H_{n-}(s)) ds, \quad (1.8)$$

which is the null hypothesis compensator of  $H_n^1(t)$  evaluated in  $\infty$ . In case of the Woolson data the estimator (1.8) takes the value 0.1794. As roughly can be inferred from Figure 1.7,  $M_n(\infty; \theta_0)$  itself takes the value 2.033. Thus, the test based on  $M_n(\infty; \theta_0)$  and estimated variance yields an asymptotic probability value 0.0000, which leads to rejection of the null hypothesis. Hence, the mortality of psychiatric patients differs from the mortality of other inhabitants of the State

of Iowa.

In Chapter 3 a broad class of tests based on sublinear Lipschitz functionals of stochastic integral with respect to the basic martingale is studied. Within this class the test statistics are of the form  $T(Q_n)$ , where  $Q_n(t)$  is defined as

$$Q_n(t) = \int_0^t L_n(s) dM_n(s; \theta_0), \quad (1.9)$$

$L_n(t)$  is a random element of  $D[0, \infty)$  satisfying certain properties, and  $T$  is sublinear [see Definition 1 on page 20] as well as Lipschitz.

An example of a sublinear Lipschitz functional is the projection in infinity  $T_R(\xi) = \xi(\infty)$ . Tests based on statistics of the form  $T_R(Q_n)$  are called generalized rank tests. Special cases are the aforementioned test of Breslow, and the generalized rank tests of Fleming and Harrington, having weight process

$$L_n(t) = (1 - F(t; \theta_0))^p \quad (1.10)$$

[see Fleming, O'Fallon, O'Brien and Harrington (1980), Fleming and Harrington (1981), Harrington and Fleming (1982), Fleming, Harrington and O'Sullivan (1987)]. Generalized rank test statistics are asymptotically normal.

The supremum functional  $T_S(\xi) = \sup_{t \in [0, \infty)} \xi(t)$  is another example of a sublinear Lipschitz functional. Tests of the form  $T_S(Q_n)$  are called supremum type tests. Special cases are the test studied by Aki (1986), and the supremum type tests of Fleming and Harrington, also having weight process (1.10). Supremum type test statistics have a non-normal asymptotic distribution.

The general KMT-inequality given in Theorem 2 on page 26 for an appropriately centered version of the stochastic integral  $Q_n(t)$  and its specialization for the null hypothesis [with  $\gamma = 1/6$  and  $\tau = 2$ ] enable the computation of various kinds of efficacies. These efficacies all coincide, and are maximized by generalized rank and supremum type tests based on a weight process which satisfies

$$L_n(t) \rightarrow_{P_0} \psi_a(t; \theta_0) \quad (1.11)$$

at a sufficient rate. Here  $P_0$  is the probability measure corresponding to the null hypothesis,  $\psi_a(t; \theta_0)$  is the score function [the evaluation in  $\theta_0$  of the partial derivative of  $\log \lambda(t; \theta)$  in the direction in which the alternative approaches the null hypothesis], and  $\lambda(t; \theta)$  is the derivative of  $\Lambda(t; \theta)$ . The generalized rank tests based on this type of weight process are asymptotically most powerful. The corresponding supremum type tests do not perform much less, since they have efficiency 1 [in the sense of approximate Bahadur efficiency, limiting approximate Bahadur efficiency, weak asymptotic intermediate efficiency, and - under extra conditions on  $L_n(t)$  - asymptotic intermediate efficiency] with respect to the asymptotically most powerful generalized rank tests.

This implies that the statistics  $T_R(M_n(\cdot; \theta_0))$  and  $T_S(M_n(\cdot; \theta_0))$  are recommended for testing against alternatives of the proportional hazard type, and



statistics  $T_R(\int_0^t (1 - F(s; \theta_0)) dM_n(s; \theta_0))$  and  $T_S(\int_0^t (1 - F(s; \theta_0)) dM_n(s; \theta_0))$  for testing against logistic shift alternatives.

In this respect the application of the test of Breslow to the Woolson data is certainly appropriate, since there are psychological motivations for assuming a proportional hazard model for psychiatric patients. This model states that the hazard of a psychiatric patient is proportional to the baseline hazard, in our case the hazard of an inhabitant of the State of Iowa.

## 1.6 Adjusting the null hypothesis

The fact that for the Woolson data  $T_R(M_n(\cdot; \theta_0))$  leads to rejection of the null hypothesis could be interpreted as an indication that a proportional hazard model is indeed more appropriate. But does it fit the data?

Recall that in the previous section it was convenient to apply the cumulative hazard function to the data, since in this way the general problem was reduced to the problem of testing standard exponentiality. Under the proportional hazard model it is convenient to apply the *baseline* cumulative hazard to the data, since the transformed data follow an exponential distribution with unknown mean, say  $v_n$ . The actual hazard experienced by a psychiatric patient is equal to the baseline hazard divided by  $v_n$ . Hence, the general problem of testing the proportional hazard model is now reduced to the problem of testing exponentiality.

Observe that the mean of the exponential distribution is not known. Our null hypothesis gives an incomplete specification of the distribution of the data, and is henceforth composite. The unknown mean is a nuisance parameter.

Let us return to a more abstract level: since the simple null hypothesis was rejected, we adjusted the null hypothesis by adding an extra nuisance parameter to our model. Section 4 hypothesized that  $P_n(X_1 \leq t)$  could be written as  $F(t; \theta_n)$ . From now on we write this probability as  $F(t; v_n, \theta_n)$  for some  $(v_n, \theta_n)$  in the set  $\Upsilon \times \Theta$ . Already anticipating the necessity of the inclusion of more nuisance parameters to make the model fit the data, we assume that  $\Upsilon$  is a subset of  $r$ -dimensional Euclidean space.

Let  $P_{v_0}$  denote the probability measure which corresponds to the point  $(v_0, \theta_0)$ . Observe that  $P_{v_0}$  "belongs" to the null hypothesis that  $\theta_n$  equals  $\theta_0$ .

## 1.7 M-estimation

Under  $P_{v_0}$  the basic martingale takes the form

$$M_n(t; v_0, \theta_0) = n^{1/2} \left\{ H_n^1(t) - \int_0^t (1 - H_{n-}(s)) d\Lambda(s; v_0, \theta_0) \right\}, \quad (1.12)$$

where  $\Lambda(t; v, \theta) = -\log(1 - F(t; v, \theta))$ . In practical situations we are faced with the problem that the null hypothesis does not provide any knowledge about the

actual value of  $v_0$ . Hence, we replace  $v_0$  by some random element  $v^{(n)} \in \Upsilon$  in an effort to obtain this knowledge elsewhere. Under  $P_{v_0}$  this random element should be an estimator of  $v_0$ .

A convenient class of estimators to use is the class of M-estimators as proposed by Hjort (1985). Within this class estimators are obtained as solutions to the set of M-equations

$$\Phi_{ni}(\infty; v^{(n)}) = 0, \quad i = 1, \dots, r, \quad (1.13)$$

where  $\Phi_{ni}(t; v)$  is defined as a stochastic integral with respect to the basic martingale

$$\Phi_{ni}(t; v) = \int_0^t \phi_i(s; v) dM_n(s; v, \theta_0). \quad (1.14)$$

The integrand  $\phi_i(t; v)$  is a given deterministic function. M-estimators are generalizations of the maximum likelihood estimator. The latter estimator was studied in this context by Borgan (1984), and is obtained by setting  $\phi_i(t; v)$  equal to the partial derivative of  $\log \lambda(t; v, \theta_0)$  with respect to the  $i^{\text{th}}$  component of  $v$ . Here  $\lambda(t; v, \theta)$  denotes the hazard function, the derivative with respect to  $t$  of the cumulative hazard function  $\Lambda(t; v, \theta)$ . A general theory of M-estimation is worked out in subsection 4.2.1 on page 52.

Consider the exponential distribution function  $F(t; v, \theta_0) = 1 - e^{-t/v}$ . Since the corresponding hazard function  $\lambda(t; v, \theta_0)$  equals  $v$ , the maximum likelihood estimator  $v^{(n)}$  is obtained by setting  $\phi_i(t; v)$  equal to  $1/v$ . Multiplying both sides of (1.13) by  $v$  yields the maximum likelihood equation

$$M_n(\infty; v^{(n)}, \theta_0) = 0. \quad (1.15)$$

For the Woolson data the maximum likelihood estimator of the unknown mean of the baseline cumulative hazard transformed data attains the value 0.309. This suggests that the baseline hazard is less than a third of the real hazard a psychiatric patient experiences, leading to the preliminary conclusion that the hazard of a psychiatric patient is more than three times as high as the hazard of an arbitrary resident of Iowa.

Of course, this only holds under the proportional hazard model. Before turning the preliminary conclusion into a definitive one, we should assess the validity of the model. This can be done by the methods described in the next section.

The stochastic integral  $M_n(t; v^{(n)}, \theta_0)$ , depicted in Figure 1.2, is closely related to a well-known and frequently used graphical technique for assessing exponentiality. The total time on test plot is constructed by plotting

$$\int_0^t (1 - H_{n-}(s)) d\Lambda(s; v^{(n)}, \theta_0)$$

versus  $H_n^1(t)$  [see Barlow and Proschan (1969), and for variants Gill (1986)]. Here  $v^{(n)}$  is the maximum likelihood estimator. If the data indeed follow an exponential

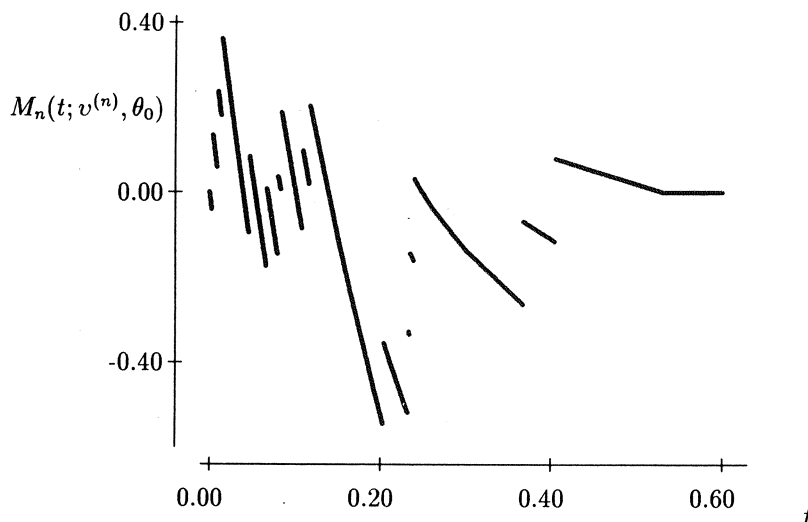


Figure 1.2: The stochastic integral involved in the construction of the maximum likelihood estimator.

distribution, then the total time on test plot should be approximately straight, making a 45 degree angle with the X-axis.

Observe that at  $x = \int_0^t (1 - H_{n-}(s)) d\Lambda(s; v^{(n)}, \theta_0)$  the vertical deviation of the total time on test plot from the ideal line equals  $n^{-1/2} M_n(t; v^{(n)}, \theta_0)$ .

## 1.8 Testing the composite null hypothesis

Now that we have the M-estimators at our disposal, it seems obvious to adapt the test statistics discussed earlier to the composite null hypothesis by simply plugging in these estimators. This leads to statistics  $T(Q_n(\cdot; v^{(n)}))$ , where  $T$  is as before and  $Q_n(t; v)$  is defined by

$$Q_n(t; v) = \int_0^t L_n(s; v) dM_n(s; v, \theta_0) \quad (1.16)$$

for some weight process  $L_n(t; v)$ . By exploiting the relation between M-estimators and stochastic integrals with respect to the basic martingale, the KMT-type inequalities for  $Q_n(t)$  can be extended to  $Q_n(t; v^{(n)})$ . However, we must pay a price for the plugged-in estimator: the accuracy of the probability inequalities governing the approximation decreases. This is reflected in the values  $\gamma = 1/6$  and  $\tau = 3$ .

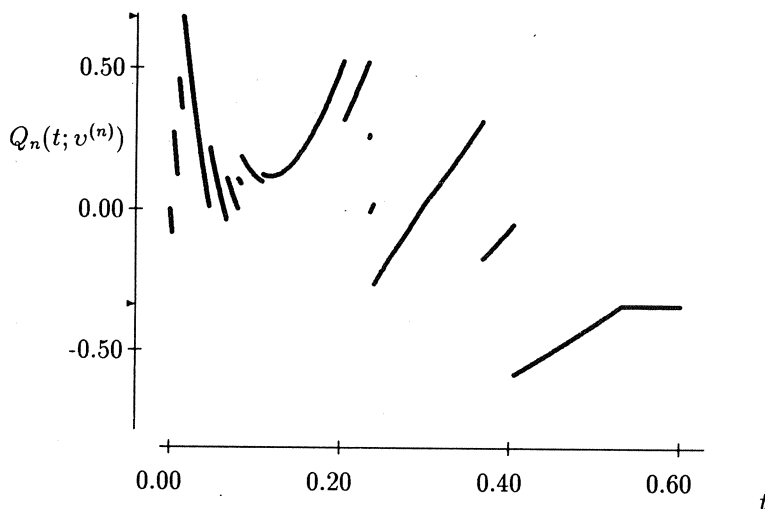


Figure 1.3: The stochastic integral leading to optimal generalized rank and supremum type tests for testing exponentiality versus logistic shift alternatives.

Again, the KMT-inequalities lead to various kinds of efficacy which all coincide and are maximized by generalized rank tests based on weight processes satisfying

$$L_n(t; v^{(n)}) \rightarrow_{P_{v_0}} \psi_{a|0}(t; v_0, \theta_0) + \sum_{i=1}^r c_i \phi_i(t; v_0), \quad (1.17)$$

and supremum type tests based on weight processes satisfying

$$L_n(t; v^{(n)}) \rightarrow_{P_{v_0}} \psi_{a|0}(t; v_0, \theta_0) \quad (1.18)$$

[see Theorem 13 on page 67]. Here the  $c_i$ 's are constants, and  $\psi_{a|0}(t; v, \theta_0)$  is the effective score function, i.e. a projected version of the score function  $\psi_a(t; v, \theta_0)$ , defined similar to the score function  $\psi_a(t; \theta_0)$  we encountered earlier. The convergence in  $P_{v_0}$ -probability should take place at a sufficient rate.

If the estimation method is maximum likelihood then the following holds. The optimal generalized rank tests have asymptotic relative Pitman efficiency 1 with respect to the generalized likelihood ratio test, and thus are asymptotically most powerful. The optimal supremum type tests have efficiency 1 [in the sense of approximate Bahadur, limiting asymptotic relative Pitman and weak intermediate efficiency] with respect to the optimal generalized rank test.

The effective score function  $\psi_{a|0}(t; v, \theta_0)$  also appears in Hjort (1990), in an investigation of  $\chi^2$ -tests based on  $Q_n(t; v^{(n)})$ . Although the argument there lacks

mathematical rigour, it underlines the universal importance of the effective score function as weight process.

As a direct consequence of (1.13), adding a term  $c_i\phi_i(t;v)$  to the weight process does not alter the generalized rank test. This property, reflected in (1.17), is especially convenient when the estimation method is maximum likelihood, since in this case the difference between  $\psi_{a|0}(t;v,\theta_0)$  and  $\psi_a(t;v,\theta_0)$  is a linear combination of the functions  $\phi_i(t;v)$ . It is easier to construct a weight process converging to  $\psi_a(t;v,\theta_0)$  than one converging to  $\psi_{a|0}(t;v,\theta_0)$ .

For given  $t$ , an optimal generalized rank test for testing the proportional hazards model versus alternatives where the ratio between the hazard and the baseline hazard function changes at point  $t$  is the statistic  $M_n(t;v^{(n)},\theta_0)$ , where  $v^{(n)}$  is the maximum likelihood estimator. Thus, the total time on test plot is in particular useful for the detection of change points in the hazard function.

Judged by the enormous popularity of the one-sample Wilcoxon test, logistic shift alternatives are of far greater practical importance than the change point alternatives just described. For testing exponentiality versus logistic shift alternatives the weight process

$$L_n(t;v) = (1 - F(t;v,\theta_0)) - \frac{\int_0^\infty 1 - F(s;v,\theta_0)(1 - H_{n-}(s))d\Lambda(s;v,\theta_0)}{H_n^1(\infty)} \quad (1.19)$$

leads in combination with maximum likelihood estimation to optimal generalized rank and supremum type tests [see subsection 5.3.2 on page 92]. For the Woolson data standardized versions of the corresponding test statistics attain values 0.338 and 0.711, leading to probability values 0.7355 and 0.8892 respectively. Hence, it is clear that the proportional hazards model should not be rejected, and that our earlier conclusion about the mortality of a psychiatric patient was justified.

## 1.9 Some technical details

In this section it is briefly outlined how the various KMT-type inequalities are derived from the original KMT-inequality, and how the sublinearity of  $T$  leads to deviation results. Of course, the remarks in this section hold only under appropriate conditions. These are given in the following chapters.

First we consider the simple null hypothesis. We may re-express  $M_n(t;\theta_0)$  as follows:

$$M_n(t;\theta_0) = U_n^1(t) + \int_0^t U_{n-}(s)d\Lambda(s;\theta_0) + n^{1/2}D(t;\theta_0,\theta_n). \quad (1.20)$$

[see page 24]. Here  $U_n^1(t)$  and  $U_{n-}(t)$  are empirical processes corresponding to  $H_n^1(t)$  and  $H_{n-}(t)$ , and  $D(t;\theta_0,\theta_n)$  is a deterministic function which is identical to zero if  $\theta_n$  equals  $\theta_0$ . Now applying the original KMT-inequality yields that a stochastic integral with respect to  $M_n(t;\theta_0) - n^{1/2}D(t;\theta_0,\theta_n)$  is approximated

by a Gaussian process. Under the null hypothesis the approximating process is time-transformed Wiener.

An alternative approach for obtaining KMT-type inequalities for  $M_n(t; \theta_0)$  under the simple null hypothesis is given in Koning (1993), and uses partial sum process techniques. The resulting KMT-type inequality has  $\gamma = 1/4$  and  $\tau = 1$ . The partial sum approach also has useful applications outside the random censoring model.

The transition from the simple to the null hypothesis is enabled by the two following facts. There exists an element  $v_{n0}$  in  $\Upsilon$  such that under  $P_n$  the random variable  $n^{1/2}(v^{(n)} - v_{n0})$  is closely approximated by a random vector with components

$$\int_0^\infty \phi_i(s; v_{n0}) d\{M_n(s; v_{n0}, \theta_0) - n^{1/2}D(s; v_{n0}, \theta_0, v_n, \theta_n)\} \quad (1.21)$$

[see Theorem 7 on page 55], where  $D(t; v_{n0}, \theta_0, v_n, \theta_n)$  is the obvious extension of  $D(t; \theta_0, \theta_n)$  [see (4.6) on page 54]. Moreover, there exists an  $r$ -dimensional function  $K_0(t; v_{n0})$  [defined by (4.16) on page 57] such that  $Q_n(t; v^{(n)})$  is approximated by

$$Q_n(t; v_{n0}) + n^{1/2}(v^{(n)} - v_{n0})^T K_0(t; v_{n0}). \quad (1.22)$$

Hence, after subtracting  $n^{1/2} \int_0^t L_n(s; v_{n0}) dD(s; v_{n0}, \theta_0, v_n, \theta_n)$  from  $Q_n(t; v^{(n)})$ , the resulting process is approximated by a zero mean Gaussian process. Even under  $P_{v_0}$  the covariance function of the latter process remains intricate [see Theorem 8 on page 58].

The theory of Borell (1975) describes the tail behavior of sublinear functionals of Gaussian processes [see Inequality 5 on page 21]. It follows that there exists nonnegative constants  $a, \check{a}$  such that

$$\lim_{x \rightarrow \infty} x^{-2} \log P_0(T(Q_n) > x) = a/2, \quad (1.23)$$

$$\lim_{x \rightarrow \infty} x^{-2} \log P_{v_0}(T(Q_n(\cdot; v^{(n)})) > x) = \check{a}/2. \quad (1.24)$$

Now the Lipschitz property of  $T$  enables us to obtain deviation results for  $T(Q_n)$  [ $x_n = o(n^{1/18})$  allowed] and  $T(Q_n(\cdot; v^{(n)}))$  [ $x_n = o(n^{1/30})$  allowed] from the KMT-type inequalities. The differences in rate are due to differences in accurateness of the corresponding inequalities.

## 1.10 Concluding remarks

In this chapter applications of KMT-type inequalities in the theory of goodness-of-fit tests were described. As the section on M-estimation indicates, there are other areas where KMT-type inequalities are of use as well.

In Castelle (1991) the study of stochastic integrals  $\int_0^t L_n(s) dH_n^1(s)$  leads to results for some well-known two-sample generalized rank tests and for maximum likelihood estimation in the Cox regression model.

The field of nonparametric estimation in the random censoring model is covered in Burke, Csörgő and Horváth (1981), where the Nelson-Aalen estimator of the cumulative hazard function  $\Lambda(t)$  and the Kaplan-Meier estimator of the distribution function  $F(t)$  are investigated. Processes related to these estimators can be expressed as stochastic integrals with respect to the basic martingale. Analogues for  $Q_n(t)$  of the Chibisov-O'Reilly theorem, the Lai-Wellner Glivenko-Cantelli theorem and the James law of the iterated logarithm are derived, and their implications for the Nelson-Aalen and the Kaplan-Meier estimator discussed in Einmahl and Koning (1992).

Other examples of KMT-type inequalities and their implications can be found in Csörgő and Horváth (1993).

The intricate asymptotic structure of  $Q_n(t; v^{(n)})$  shows some resemblance to the asymptotic structure of the empirical process with estimated parameters [see Durbin (1973)]. In Khamaladze (1981, 1982) a transformation of this process is constructed which converges to a time-transformed Wiener process. A similar transformation can be constructed for  $Q_n(t; v^{(n)})$ . However, this transformation is quite complex, and involves the in general unknown distribution function  $H^1(t; v_0, \theta_0)$ , the expectation of  $H_n^1(t)$  under  $P_{v_0}$ . Estimating this distribution function complicates matters even further.





## Chapter 2

# Tail probabilities of various suprema

### 2.1 The empirical process

Empirical processes have been the subject of ongoing investigations for over half a century. In this chapter we encounter the most important results. For a more elaborate survey we refer to Csörgő and Révész (1981) and to Shorack and Wellner (1986).

Let  $(\Omega, \mathcal{A}, \mathcal{P})$  be a probability space, and let  $\{\tilde{Z}_i\}_{i=1}^\infty$  be a sequence of random variables mapping  $(\Omega, \mathcal{A})$  into  $([0, 1], \mathcal{F})$ , where  $\mathcal{F} \subset \mathcal{B}[0, 1]$ . Let  $P$  be the probability measure induced by the sequence  $\{\tilde{Z}_i\}_{i=1}^\infty$ .

Suppose each of the random variables within this sequence has a standard uniform distribution under  $P$ . The [standard] uniform empirical process at stage  $n$  is defined by

$$\tilde{U}_n(t) = n^{-1/2} \sum_{i=1}^n (1_{\{\tilde{Z}_i \leq t\}} - t) \quad (2.1)$$

for  $0 \leq t \leq 1$ . It is easily seen that  $-\inf_{t \in [0, 1]} \tilde{U}_n(t)$  is equal in distribution to  $\sup_{t \in [0, 1]} \tilde{U}_n(t)$ . Moreover, we have

$$\begin{aligned} P(\sup_{t \in [0, 1]} |\tilde{U}_n(t)| > x) &\leq P(\sup_{t \in [0, 1]} \tilde{U}_n(t) > x) + P(-\inf_{t \in [0, 1]} \tilde{U}_n(t) > x) \\ &\leq 2P(\sup_{t \in [0, 1]} \tilde{U}_n(t) > x) \end{aligned} \quad (2.2)$$

Hence, bounds for tail probabilities of  $\sup_{t \in [0, 1]} \tilde{U}_n(t)$  directly translate into bounds for tail probabilities of  $-\inf_{t \in [0, 1]} \tilde{U}_n(t)$  and  $\sup_{t \in [0, 1]} |\tilde{U}_n(t)|$ .

An important early result for the tail probability of  $\sup_{t \in [0,1]} \tilde{U}_n(t)$  was derived in Smirnov (1944). Surprisingly, it is known under the name Birnbaum-Tingey formula, since it was also discovered in Birnbaum and Tingey (1951). It tells us that

$$\begin{aligned} P(\sup_{t \in [0,1]} \tilde{U}_n(t) > yn^{1/2}) \\ = \sum_{i=0}^{n(1-y)} y \binom{n}{i} (y + i/n)^{i-1} (1 - y - i/n)^{n-i} \end{aligned} \quad (2.3)$$

for  $0 < y < 1$ . Applying Stirling's formula to (2.3) yields that

$$\lim_{n \rightarrow \infty} P(\sup_{t \in [0,1]} \tilde{U}_n(t) > x) = \exp\{-2x^2\} \quad (2.4)$$

for  $x > 0$ . The Birnbaum-Tingey formula provided the basis of the following well-known equality.

**Inequality 1 (DKW-Inequality)** *There exists a positive constant  $c_1$  such that*

$$P(\sup_{t \in [0,1]} \tilde{U}_n(t) > x) \leq c_1 \exp\{-2x^2\}$$

for  $x > 0$ .

The DKW-inequality was first proven in Dvoretzky, Kiefer and Wolfowitz (1956). Observe that if we know a valid value of  $c_1$ , then the DKW-inequality enables us to construct a conservative version of a Kolmogorov goodness-of-fit test. The rather intriguing conjecture that  $c_1$  could be set equal to 1 was made in Birnbaum and McCarty (1958). Equation (2.4) shows that the Birnbaum-McCarty conjecture implies that constructing a Kolmogorov goodness-of-fit test by using asymptotic methods never yields an anti-conservative test.

For over thirty years the Birnbaum-McCarty conjecture remained an open question in empirical process theory. During these years various attempts have been made to prove it, resulting in steadily decreasing permitted minimal values of  $c_1$ . As recommended values of  $c_1$  have acted 305.2 [Devroye and Wise (1979)], 29 [Shorack and Wellner (1986)], and  $2^{3/2}$  [Hu (1985)]. Recently, the Birnbaum-McCarty conjecture was proven in Massart (1990) for a slightly modified version of the DKW-inequality which restricts attention to values of  $x$  satisfying  $\exp\{-2x^2\} \leq 1/2$ .

A generalization of the DKW-inequality, which can be applied in the non-i.i.d. case and not only to the empirical process but related processes as well, can be found in Marcus and Zinn (1984).

Asymptotic expansions of the distributions of  $\sup_{t \in [0,1]} \tilde{U}_n(t)$  are found in Lauwerier (1963), Penkov (1976) and Gnedenko, Korolyuk and Skorohod (1961), whereas other approximations to this distributions are contained in Stephens (1970) and Harter (1980).

## 2.2 The Brownian bridge approximation

In Doob (1949) it is noticed that as the sample size  $n$  tends to infinity, empirical processes seem to behave more and more like a Brownian bridge. This observation has provided the inspiration for the following result [also known as Donsker's Theorem, since it originally appeared in Donsker (1952)].

**Theorem 1 (Empirical Central Limit Theorem)** *The sequence of empirical processes  $\{\tilde{U}_n(t)\}_{n=1}^\infty$  converges in  $P$ -distribution, as random elements of  $D[0, 1]$ , to a Brownian bridge.*

As a consequence of the well-known Skorohod construction Theorem 1 implies the existence of a probability space on which we have a sequence of empirical processes and a Brownian bridge such that the supremum of the difference between each of the empirical processes and the Brownian bridge converges to zero in probability.

An alternative to the Skorohod construction [Skorohod (1956)] is the so-called Hungarian construction, given in Komlós, Major and Tusnády (1975). The Hungarian construction culminates into the following inequality.

**Inequality 2 (KMT-Inequality, Brownian bridge version)** *If the probability space  $(\Omega, \mathcal{A}, \mathcal{P})$  is sufficiently rich, then there exists a sequence  $\{\tilde{B}_n(t)\}_{n=1}^\infty$  of Brownian bridges such that*

$$P\left(\sup_{t \in [0,1]} |\tilde{U}_n(t) - \tilde{B}_n(t)| > n^{-1/2}(c_2 \log n + x)\right) \leq c_3 \exp\{-c_4 x\},$$

where  $c_2$ - $c_4$  are absolute constants.

In Bretagnolle and Massart (1989) it is shown that  $c_2$ ,  $c_3$  and  $c_4$  may be taken as 12, 2 and 1/6, respectively.

For some applications [for instance, the derivation of a law of the iterated logarithm] it is necessary to imbed the sequence of Brownian bridges into a Kiefer process [see Kiefer (1972)]. However, imposing this extra structure on the sequence of Brownian bridges seems to worsen the rate of convergence. The most far stretching result concerning the Kiefer process approximation is given by Inequality 3. This inequality requires that the underlying probability space is the same for every  $n \in \mathbb{N}$ . It is still an open question whether this inequality can be improved so as to yield the same rate of convergence as does Inequality 2.

**Inequality 3 (KMT-Inequality, Kiefer process version)** *If the probability space  $(\Omega, \mathcal{A}, \mathcal{P})$  is sufficiently rich, then there exists a Kiefer process  $\tilde{K}(t, n)$  such that*

$$P\left(\sup_{t \in [0,1]} |\tilde{U}_n(t) - n^{-1/2} \tilde{K}(t, n)| > n^{-1/2}(c_5 \log n + x) \log n\right) \leq c_6 \exp\{-c_7 x\},$$

where  $c_5$ - $c_7$  are absolute constants.

In Mason and van Zwet (1987) a refined KMT-inequality is given, which emphasizes the behavior of the approximation near 0 and 1. However, for our purposes the original KMT-inequality suffices.

### 2.3 The general Gaussian process

Among the Gaussian processes, the Wiener process  $W(t)$  takes first place. Results for the supremum of this process are well-known and can even be considered classical. The reflection principle yields

$$P(\sup_{t \in [0,1]} W(t) > x) = 2P(N(0,1) > x) \quad (2.5)$$

$$P(\sup_{t \in [0,1]} |W(t)| > x) = 4 \sum_{k=0}^{\infty} (-1)^k P(N(0,1) > (2k+1)x) \quad (2.6)$$

Interest in the supremum of a general Gaussian process came about relatively late, at the beginning of the seventies [Fernique 1970, 1971]), Landau and Shepp (1971) and Marcus and Shepp (1971)]. The following inequality was then obtained.

**Inequality 4 (Inequality of Fernique)** *There exist positive constants  $c_8$  and  $c_9$  such that for every  $x > 0$  and every separable Gaussian process  $Z(t)$  satisfying  $P(\sup_{t \in [0,\infty)} |Z(t)| < \infty) = 1$*

$$P(\sup_{t \in [0,\infty)} |Z(t)| > x \sqrt{\sup_{t \in [0,\infty)} \mathcal{E}\{Z(t)\}^2}) \leq c_8 \exp\{-c_9 x^2\}.$$

In Borell (1975) an inequality for the tail probability of sublinear functionals of a Gaussian process is given which relates this tail probability to the norm of the sublinear functional induced by the Gaussian process, and yields a finer result than Inequality 4 when applied to the supremum of a Gaussian process.

**Definition 1** *A functional  $T$  which maps  $D[0,\infty)$  into  $\mathbb{R}$  is said to be sublinear if  $T(\xi + \zeta) \leq T(\xi) + T(\zeta)$  and  $T(c\xi) = cT(\xi)$  for all  $c \geq 0$  and  $\xi, \zeta \in D[0,\infty)$ .*

Refer to Pollard (1984), page 108, for the definition of the function space  $D[0,\infty)$ .

The norm of a sublinear functional  $T$  induced by the Gaussian process  $Z(t)$  is defined as

$$\|T\|_{Z(t)} = \sup_{f \in O_{\mathcal{K}}} T(f), \quad (2.7)$$

where  $O_{\mathcal{K}}$  is the unit ball in  $\mathcal{K}$ , the reproducing kernel Hilbert space belonging to  $Z(t)$ . The theory of reproducing kernels is described extensively in Aronszajn

(1950). The reproducing kernel  $\mathcal{K}_W$  belonging to a standard Wiener process on  $[0,1]$  consist of functions  $f$  mapping  $[0,1]$  into  $\mathbb{R}$ , which are absolutely continuous and satisfy  $\int_0^1 (f'(s))^2 ds < \infty$ . The norm of an element of  $\mathcal{K}_W$  is equal to  $\int_0^1 (f'(s))^2 ds$ , and hence the unit ball in  $\mathcal{K}_W$  is the set  $\mathcal{S}$  of functions  $f$  mapping  $[0,1]$  into  $\mathbb{R}$ , which are absolutely continuous and satisfy  $\int_0^1 (f'(s))^2 ds \leq 1$  as well as  $f(0) = 0$ .

The set  $\mathcal{S}$  may seem familiar to statisticians and probabilists, since it also shows up in connection with the law of the iterated logarithm [see Strassen (1964)]. We shall refer to  $\mathcal{S}$  as the set of Strassen functions.

**Inequality 5 (Inequality of Borell)** *Let  $X(t)$  be a mean zero separable Gaussian process satisfying  $P(\sup_{t \in [0, \infty)} |X(t)| < \infty) = 1$ , and let  $T$  be a sublinear function. Assume that  $P(T(X) > u \|T\|_X) \leq 1/2$  for some  $u$ . Then for  $t \geq u$*

$$P(T(X) > t \|T\|_X) \leq P(N(0,1) > t - u).$$

**Corollary 1** *We have*

$$\lim_{t \rightarrow \infty} t^{-2} \log P(T(X) > t) = -(\|T\|_X)^{-2}/2.$$

Each of the Gaussian processes to which we shall apply Inequality 5 can be considered to be a linear transformation of some standard Wiener process. Thus, a sublinear functional  $T$  of such a Gaussian process  $Z(t)$  is in essence a sublinear functional  $T_{Z(t)}$  of the underlying standard Wiener process. This observation leads to

$$\|T\|_{Z(t)} = \sup_{f \in \mathcal{S}} T_{Z(t)}(f), \quad (2.8)$$

which makes the computation of norms as in (2.7) relatively easy.

The inequality of Fernique seems to imply that it is rather the variance function than the covariance function which determines the tail behavior of the supremum of a Gaussian process. However, the covariance function is not completely irrelevant, as some finer results show. In Adler and Samorodnitsky (1987) a refinement of the inequality of Fernique is given which is based on metric entropy methods [see Dudley (1967)]. Talagrand (1988) presents a necessary and sufficient condition for

$$\lim_{x \rightarrow \infty} \frac{P(\sup_{t \in [0, \infty)} Z(t) > x)}{P(N(0,1) > x \{ \sup_{t \in [0, \infty)} \mathcal{E}\{Z(t)\}^2 \}^{-1/2})} = 1 \quad (2.9)$$

to hold. This condition can be verified by metric entropy methods and entails the behavior of the covariance function near points where the variance function reaches its maximum.

For a completely different approach, treating suprema of Gaussian processes from a boundary crossing perspective, refer to Durbin (1985).



# Chapter 3

## The simple null hypothesis

### 3.1 Introduction

In this chapter, which contains the material of Koning (1991), we consider the situation where  $(\Omega, \mathcal{A}, \mathcal{P})$  is a probability space,  $\mathcal{F}_n$  is a subset of  $\mathcal{B}[0, \infty)$ , and at stage  $n$  each of the independent random variables  $X_1, \dots, X_n, Y_1, \dots, Y_n$  maps  $(\Omega, \mathcal{A})$  into  $([0, \infty), \mathcal{F}_n)$ . The probability measure induced by these random variables is denoted by  $P_n$ . Each pair  $(X_i, Y_i)$  is assumed to have the same distribution.

The censoring distribution, the distribution of the censoring time  $Y_i$ , does not depend on  $n$ . Hence, there exists a cumulative distribution  $G$  such that  $G(t) = P_n(Y_i \leq t)$  for each  $n$ . Defectiveness of  $G(t)$  is allowed.

The failure time distribution, the distribution of  $X_i$ , is more complicated since it depends on  $n$ . This dependence is given structure in the following way: there exists a cumulative distribution function  $F$ , indexed by  $\theta$  belonging to some set  $\Theta$ , and a sequence of points  $\{\theta_n\}_{n=1}^\infty$  such that  $F(t; \theta_n) = P_n(X_i \leq t)$  for every  $n \in \mathcal{N}$  [that is,  $\theta_n$  is the actual value of  $\theta$  at stage  $n$ ].

Now suppose  $\theta_0$  is an element of  $\Theta$  which is of special interest to us, say because we want to know whether  $\theta_n$  could possibly be equal to  $\theta_0$  for every  $n \in \mathcal{N}$ .

If  $\theta_n$  equals  $\theta_0$  [denote the probability measure corresponding to this situation by  $P_0$ , the expectation operator based on this probability measure by  $\mathcal{E}_0$  and the situation itself by “under  $P_0$ ”], then the basic martingale takes the form

$$M_n(t; \theta_0) = n^{1/2} \{ H_n^1(t) - \int_0^t (1 - H_{n-}(s)) d\Lambda(s; \theta_0) \}, \quad (3.1)$$

where  $\Lambda(t; \theta) = -\log(1 - F(t; \theta))$  is the cumulative hazard function belonging to  $F(t; \theta)$  and  $H_n^1(t)$  and  $H_{n-}(t)$  are given by (1.4) on page 4. Note that we only know that  $M_n(t; \theta_0)$  is a martingale under  $P_0$ . If  $\theta_n$  is arbitrary [refer to this situation as “under  $P_n$ ”, and denote the expectation operator belonging to  $P_n$  by  $\mathcal{E}_n$ ] then the process  $M_n(t; \theta_0)$  is in general not a martingale. Nevertheless, we

also call  $M_n(t; \theta_0)$  a basic martingale. Although misleading, this does not lead to difficulties since we do not encounter the original basic martingale  $M_n(t; \theta_n)$  anymore.

In section 3.3 we study tests based on a special type of functional of a weighted version of a process  $Q_n(t)$ , which is a stochastic integral with respect to the basic martingale, that is

$$Q_n(t) = \int_0^t L_n(s) dM_n(s; \theta_0). \quad (3.2)$$

Here the weight process  $L_n(t)$  is a random element of  $D[0, \infty)$  which possesses certain properties.

The probability theory underlying the results in section 3.3 is presented in section 3.2, where the process  $Q_n(t)$  is approximated. The common way to approach a stochastic integral with respect to the basic martingale is by martingale methods, but in this chapter an empirical process approach is followed, fundamented on an alternative representation of  $M_n(t; \theta_0)$  in terms of empirical processes. A slight drawback of the empirical process approach is that we must assume that both  $F(t; \theta)$  and  $G(t)$  are continuous on the complete real line. However, this assumption has its rewards: the knowledge obtained by the empirical process approach is far more precise than can be obtained by using standard martingale methods such as Rebolledo's Central Limit Theorem.

Define the cumulative distribution functions  $H^1(t; \theta_n)$  and  $H(t; \theta_n)$  by

$$H^1(t; \theta_n) = P_n(Z_1 \leq t, \delta_1 = 1) = \int_0^t (1 - G(s)) dF(s; \theta_n), \quad (3.3)$$

$$H(t; \theta_n) = P_n(Z_1 \leq t) = 1 - (1 - G(t))(1 - F(t; \theta_n)), \quad (3.4)$$

and the empirical processes  $U_n^1(t; \theta_n)$  and  $U_{n-}(t; \theta_n)$  by

$$U_n^1(t; \theta_n) = n^{1/2} \{H_n^1(t) - H^1(t; \theta_n)\}, \quad (3.5)$$

$$U_{n-}(t; \theta_n) = n^{1/2} \{H_{n-}(t) - H(t; \theta_n)\}. \quad (3.6)$$

Then we may decompose  $M_n(t; \theta_0)$  conveniently into three parts

$$M_n(t; \theta_0) = U_n^1(t; \theta_n) + \int_0^t U_{n-}(s; \theta_n) d\Lambda(s; \theta_0) + n^{1/2} D(t; \theta_0, \theta_n) \quad (3.7)$$

[compare to the decomposition given in equation (7.1.2) in Shorack and Wellner (1986)]. The first two parts involve empirical processes, and can be handled by empirical process theory. The third part is nonrandom and involves the function

$$D(t; \theta_0, \theta) = \int_0^t (1 - H(s; \theta)) \{d\Lambda(s; \theta) - d\Lambda(s; \theta_0)\}. \quad (3.8)$$

Observe that if  $\theta$  coincides with  $\theta_0$ , then  $D(t; \theta_0, \theta)$  is identical to zero. As can be expected, the function  $D(t; \theta_0, \theta)$  will show up frequently in our results. Loosely



speaking, it reflects the distance between the distribution functions  $F(t; \theta)$  and  $F(t; \theta_0)$ .

Although for the empirical process approach it is needed that  $G$  is continuous on the complete real line, we may show that our approximation results remain true on  $[0, t^*)$ , where  $t^* = \sup\{t : G(t) < 1\}$  is finite, if  $G$  is continuous only on  $(-\infty, t^*)$ , by appropriately modifying  $G$  on the interval  $[t^*, \infty)$ . Thus, our results also have implications for Type I censoring.

Moreover, the assumption of independence between  $X_i$  and  $Y_i$  may be relaxed. However, it is crucial that (3.4) still holds.

Finally, we point out to the reader that sections 3.2 and 3.3 contain results only, and that proofs are gathered in section 3.4.

## 3.2 Probability inequalities

In this section we present probability inequalities which concern the approximation on the halfline  $[0, \infty)$  of [a centered version of] the process  $Q_n(t)$  by a one-parameter Gaussian process, both under  $P_n$  as under  $P_0$ . For treatment of the former situation, the following condition is needed.

**Condition 1** *There exists constants  $0 < \alpha < 1/2$  and  $c_\alpha < \infty$  such that*

$$\int_0^\infty (1 - F(s; \theta))^\alpha d\Lambda(s; \theta_0) < c_\alpha$$

for every  $\theta \in \Theta$ .

Essentially, Condition 1 relates the right tail behavior of  $F(t; \theta)$  to the right tail behavior of  $F(t; \theta_0)$ . Note that if  $(1 - F(t; \theta))/(1 - F(t; \theta_0))$  remains uniformly bounded in  $\theta$ , then Condition 1 is satisfied for any  $\alpha > 0$ . Observe that Condition 1 implies

$$|D(t_1; \theta_0, \theta) - D(t_2; \theta_0, \theta)| \leq c_{10}(1 - H(t_1 \wedge t_2; \theta))^{1-\alpha}, \quad (3.9)$$

where  $c_{10} = c_\alpha + 1/\alpha$ . From (3.9) it immediately follows that  $D(t; \theta_0, \theta)$  remains bounded by  $c_{10}$ .

The weight process  $L_n(t)$  is assumed to satisfy Condition 2.

**Condition 2** *There exists a positive non-decreasing function  $q(t)$  such that*  
**a**  $L_n(\cdot)/q(\cdot)$  *is a random element in [the left continuous right limits version of]*  
 $D[0, \infty)$  *endowed with the  $\mathcal{J}_1$  metric.*

**b** *There exists a constant  $c_{11}$  not depending on  $\theta_n$  such that*

$$\sup_{t \in [0, \infty)} |L_n(t)|/q(t) < c_{11}, \quad V(L_n(\cdot)/q(\cdot)) < c_{11}$$

with  $P_n$ -probability 1 [here  $V(f)$  denotes the total variation of  $f$ ].

c There exists a deterministic function  $L(t; \theta_n)$  such that for every  $\beta < 1/2$

$$P_n\left(\sup_{t \in [0, \infty)} |L_n(t) - L(t; \theta_n)|/q(t) > c_{12}n^{-\beta}\right) \leq c_{13}n^{-c_{14}},$$

where  $c_{12}-c_{14}$  are positive constants not depending on  $\theta_n$ .

d There exist constants  $c_{15}-c_{17} > 0$  such that for every  $x > 0$

$$\begin{aligned} P_0\left(\sup_{t \in [0, \infty)} |L_n(t) - L(t; \theta_0)|/q(t) > n^{-1/2}(c_{15} \log n + x)\right) \\ \leq c_{16} \exp\{-c_{17}x\}. \end{aligned}$$

Both  $\sup_{t \in [0, \infty)} |L(t; \theta_n)|/q(t)$  and  $V(L(\cdot; \theta_n)/q(\cdot))$  do not exceed  $c_{11}$  as a consequence of Condition 2.

Subsequent results may be viewed as bearing upon  $Q_n(t)/q(t)$  rather than upon  $Q_n(t)$  itself. Hence, the choice of  $q(t)$  will often be inflicted by the projected application of these results. Typically, one chooses  $q(t) = (1 - F(t; \theta_0))^{-\rho}$  for some  $\rho \geq 0$ .

Under Conditions 1 and 2 we have the following result.

**Theorem 2** *There exists a sequence  $\{W_n(t)\}_{n=1}^{\infty}$  of mean zero Gaussian processes which have covariance function*

$$\begin{aligned} \mathcal{E}_n W_n(t_1)W_n(t_2) &= H^1(t_1 \wedge t_2; \theta_n) \\ &+ \int_0^{t_1 \wedge t_2} \{2D(s; \theta_0, \theta_n) - D(t_1; \theta_0, \theta_n) - D(t_2; \theta_0, \theta_n)\} d\Lambda(s; \theta_0) \\ &- D(t_1; \theta_0, \theta_n)D(t_2; \theta_0, \theta_n) \end{aligned} \quad (3.10)$$

such that for every  $\beta < (1/2 - \alpha) \wedge 1/6$  there exist positive constants  $c_{18}-c_{20}$  not depending on  $\theta_n$  such that

$$\begin{aligned} P_n\left(\sup_{t \in [0, \infty)} \left| \{Q_n(t) - n^{1/2} \int_0^t L_n(s) dD(s; \theta_0, \theta_n)\} \right. \right. \\ \left. \left. - \int_0^t L(s; \theta_n) dW_n(s) \right|/q(t) > c_{18}n^{-\beta}\right) \leq c_{19}n^{-c_{20}}. \end{aligned} \quad (3.11)$$

Moreover, there exist positive constants  $c_{21}-c_{23}$  such that for every  $x > 0$

$$\begin{aligned} P_0\left(\sup_{t \in [0, \infty)} \left| Q_n(t) - \int_0^t L(s; \theta_0) dW_n(s) \right|/q(t) \right. \\ \left. > n^{-1/6}(c_{21} \log n + x)^2\right) \leq c_{22} \exp\{-c_{23}x\}. \end{aligned} \quad (3.12)$$

**Corollary 2** *The sequence  $\{Q_n(t)/q(t)\}_{n=1}^\infty$  converges in  $P_0$ -distribution to  $X(t; \theta_0)/q(t)$ , where  $X(t; \theta_0)$  is a time-transformed Wiener process with variance function  $\int_0^t (L(s; \theta_0))^2 dH^1(s; \theta_0)$ .*

In Theorem 2 a stochastic integral with respect to a Gaussian process appears. This integral is defined in the usual way, that is  $\int_0^t L(s; \theta_n) dW_n(s)$  denotes  $L(t; \theta_n)W_n(t) - \int_0^t W_n(s)dL(s; \theta_n)$ .

There is a refinement of Theorem 2 worth mentioning. If the stochastic process  $L_n(t)$  coincides with the function  $L(t; \theta_n)$  with  $P_n$ -probability 1, then (3.11) holds for every  $\beta < (1/2 - \alpha)$ . Moreover, the term  $n^{-1/6}$  in (3.12) may be replaced by  $n^{-1/2}$ .

An approximation of  $Q_n(t)$  by a two-parameter Gaussian process, only valid under  $P_0$  and on some fixed closed interval, can be found in Einmahl and Koning (1992), where it is used to derive complete analogues of the Chibisov-O'Reilly theorem, the Lai-Wellner Glivenko-Cantelli theorem and the James law of the iterated logarithm.

Convergence in  $P_0$ -distribution of the sequence  $\{Q_n(t)/q(t)\}_{n=1}^\infty$  may also be obtained by using Rebolledo's martingale central limit theorem [Shorack and Wellner (1986), p. 895], provided that the weight process  $L_n(t)$  is predictable. However, such an approach does not lead to probability inequalities of the same type as (3.12), which will prove to be essential for deriving moderate deviation results for the test statistics considered in the next section.

### 3.3 Sublinear tests

In this section we study sublinear tests for the simple null hypothesis that  $\theta_n$  equals  $\theta_0$ . These tests are based on statistics of the form  $T(Q_n(\cdot)/q(\cdot))$ , where  $T$  is a special type functional mapping  $D[0, \infty)$  into  $\mathbb{R}$ . We consider the behavior of these test statistics under the null hypothesis and under fixed and local alternatives, as well as efficiencies of the corresponding tests. Generalized rank and supremum type tests receive special attention, and are shown to be in some sense optimal for specific choices of the weight process.

**Definition 2** *A functional  $T$  mapping  $D[0, \infty)$  into  $\mathbb{R}$  is said to be Lipschitz if there exists a constant  $c_T$  such that*

$$|T(\xi) - T(\zeta)| \leq c_T \sup_{t \in [0, \infty)} |\xi(t) - \zeta(t)|$$

for every  $\xi, \zeta \in D[0, \infty)$ .

**Condition 3** *The functional  $T$  is sublinear and Lipschitz.*

Since  $T$  is sublinear, the tail behavior of a random variable obtained by applying  $T$  to some Gaussian process  $\xi$  is described by Inequality 5. The Lipschitz property, which is borrowed from Inglot and Ledwina (1990), enables us to carry these results to some extent over to non-Gaussian processes close to  $\xi$ .

### 3.3.1 Deviations

Let  $\mathcal{S}$  be the set of Strassen-functions and define

$$a = \left\{ \sup_{f \in \mathcal{S}} T \left( \int_0^1 L(s; \theta_0) f'(H^1(s; \theta_0)) dH^1(s; \theta_0) / q(\cdot) \right) \right\}^{-2}. \quad (3.13)$$

One may interpret  $a^{-1/2}$  as the norm of the functional  $T$  induced by the reproducing kernel Hilbert space of the Gaussian process  $X(t; \theta_0)/q(t)$ , the limit in  $P_0$ -distribution of the sequence  $\{Q_n(t)/q(t)\}_{n=1}^\infty$ . Suppose that

**Condition 4** *The number  $a$  is positive.*

Theorem 3 describes the tail behavior of  $T(X(\cdot; \theta_0)/q(\cdot))$  [and thus the tail behavior of the asymptotic distribution of  $T(Q_n(\cdot)/q(\cdot))$ ], and presents a moderate deviation result for  $T(Q_n(\cdot)/q(\cdot))$ . It holds if equation (3.12) and Conditions 3 and 4 hold.

**Theorem 3** *We have*

$$\lim_{t \rightarrow \infty} t^{-2} \log P_0(T(X(\cdot; \theta_0)/q(\cdot)) > t) = -a/2. \quad (3.14)$$

Furthermore,

$$\lim_{n \rightarrow \infty} (s_n)^{-2} \log P_0(T(Q_n(\cdot)/q(\cdot)) > s_n) = -a/2 \quad (3.15)$$

for any sequence  $\{s_n\}_{n=1}^\infty$  such that  $s_n \rightarrow \infty$  and  $s_n = o(n^{1/18})$  as  $n \rightarrow \infty$ .

Since  $s_n = \mathcal{O}((\log n)^{1/2})$  is a special case of  $s_n = o(n^{1/18})$ , Theorem 3 implies that a moderate deviation result holds for  $T(Q_n(\cdot)/q(\cdot))$ . Moderate deviation results are important from a statistical perspective, because they play a role in evaluating the performance of a test.

As with Theorem 2, Theorem 3 can be refined in the special case where  $L_n(t)$  coincides with  $L(t; \theta_0)$  with  $P_0$ -probability 1. Now  $s_n = o(n^{1/18})$  may be replaced by  $s_n = o(n^{1/6})$ , and thus we have obtained a Cramér type large deviation result. A Cramér type large deviation result should be distinguished from a Chernoff type large deviation result which allows  $s_n = \mathcal{O}(n^{1/2})$ .

To transform (3.14) into a moderate or large deviation result, probability inequalities of the type (3.12) are needed. Hence, Theorem 3 does not follow from Rebolledo's Central Limit Theorem.

It is possible to generalize Theorem 3 by relaxing the Lipschitz requirement in Condition 3. For example, in Inglot and Ledwina (1989) it is assumed that there exists a constant  $c_T > 0$  and a weight function  $\tilde{q}(t)$  belonging to some special class such that

$$|T(\xi) - T(\zeta)| \leq c_T \sup_{t \in [0, \infty)} |\xi(t) - \zeta(t)| / \tilde{q}(t) \quad \text{for all } \xi, \zeta \in D[0, \infty).$$

However, since the functionals of our primary interest, the generalized rank and supremum type functionals, already are Lipschitz, we have preferred to present Theorem 3 in the simple version.

Since in general the distribution function  $H^1(t; \theta_0)$  is involved in  $a$ , practical problems arise when the censoring distribution  $G$  is unknown. In this case it seems best to multiply the original weight process by the square root of an estimator for  $a$ . Typically, estimators for  $a$  are obtained by replacing  $H^1(t; \theta_0)$  by  $\int_0^t (1 - H_{n-}(s)) d\Lambda(s; \theta_0)$ . Of course, it should be verified whether the newly constructed weight process meets all requirements.

### 3.3.2 Behavior under the alternative hypothesis

Next, we consider the behavior of  $T(Q_n(\cdot)/q(\cdot))$  under the alternative hypothesis. Before turning to local alternatives, we first briefly discuss the behavior under a fixed alternative. Suppose that  $\theta$  is an element of  $\Theta$ , not necessarily equal to  $\theta_0$ , and that we have  $\theta_n = \theta$  for all  $n \in \mathbb{N}$  [we shall refer to this situation as “under  $P_\theta$ ”]. Combining equation (3.11) with Conditions 2c, and 3 yields for every  $\beta > 0$

$$n^{-\beta} |T(Q_n(\cdot)/q(\cdot)) - n^{1/2} T(\int_0^\cdot L(s; \theta) dD(s; \theta_0, \theta) / q(\cdot))| \xrightarrow{P_\theta} 0. \quad (3.16)$$

To make treatment of the behavior under local alternatives possible we need additional notation and conditions. First we assume

**Condition 5**  $\Theta$  is a convex subset of  $\mathbb{R}^p$ .

The hazard function  $\lambda(t; \theta)$  is defined as the derivative with respect to  $t$  of  $\Lambda(t; \theta)$ . Let  $\psi_i(t; \theta)$  denote the first order partial derivative of  $\log \lambda(t; \theta)$  with respect to the  $i^{\text{th}}$  component of  $\theta$ , and  $\psi_{ij}^{(1)}(t; \theta)$  the second order partial derivative of  $\log \lambda(t; \theta)$  with respect to the  $i^{\text{th}}$  and  $j^{\text{th}}$  components of  $\theta$ .

**Condition 6** For every  $\theta \in \Theta$  and  $i, j = 1, \dots, p$  the functions  $\lambda(t; \theta)$ ,  $\psi_i(t; \theta)$  and  $\psi_{ij}^{(1)}(t; \theta)$  exist. For some  $\beta > 0$  there exists a constant  $c_{24}$  such that for every  $\theta \in \Theta$  and  $i, j = 1, \dots, p$

$$\int_0^\infty (\psi_i(s; \theta))^2 (1 - H(s; \theta))^{(1-2\alpha)-\beta} d\Lambda(s; \theta) < c_{24},$$

$$\int_0^\infty (\psi_{ij}^{(1)}(s; \theta))^2 (1 - H(s; \theta))^{2(1-2\alpha)-\beta} d\Lambda(s; \theta) < c_{24}.$$

In the description of the behavior of the test statistics under local alternatives, the  $p$ -dimensional vector function  $K_a(t)$  is involved. The  $i^{\text{th}}$  element of  $K_a(t)$  is defined by

$$K_{ai}(t) = \int_0^t L(s; \theta_0) \psi_i(s; \theta_0) dH^1(s; \theta_0). \quad (3.17)$$

It is easily proved that  $K_{ai}(t)/q(t)$  remains uniformly bounded in  $t$  and  $\theta_0$  under Conditions 1 and 6.

Recall that  $L(t; \theta)$  is the limiting function of the process  $L_n(t)$  under  $P_\theta$ . Let  $L_i^{(1)}(t; \theta)$  denote the first order partial derivative of  $L(t; \theta)$  with respect to the  $i^{\text{th}}$  component of  $\theta$ , and  $L_{ij}^{(2)}(t; \theta)$  the second order partial derivative of  $L(t; \theta)$  with respect to the  $i^{\text{th}}$  and  $j^{\text{th}}$  components of  $\theta$ .

**Condition 7** For every  $\theta \in \Theta$  and  $i, j = 1, \dots, p$  the functions  $L_i^{(1)}(t; \theta)$  and  $L_{ij}^{(2)}(t; \theta)$  exist. There exists a constant  $c_{25}$  such that for every  $\theta \in \Theta$  and for  $i, j = 1, \dots, p$

$$\sup_{t \in [0, \infty)} (1 - H(t; \theta))^{1/2} |L_i^{(1)}(t; \theta)| / q(t) < c_{25},$$

$$\sup_{t \in [0, \infty)} (1 - H(t; \theta))^{1-\alpha} |L_{ij}^{(2)}(t; \theta)| / q(t) < c_{25}.$$

**Theorem 4** Suppose the sequence  $\{\theta_n\}_{n=1}^\infty$  converges to the point  $\theta_0$ . Let  $h$  be the  $p$ -dimensional unit vector defined by  $h = \lim_{n \rightarrow \infty} (\theta_n - \theta_0) / |\theta_n - \theta_0|$ , and let  $\sigma$  denote  $\lim_{n \rightarrow \infty} n^{1/2} |\theta_n - \theta_0|$ .

- a If  $\sigma = \infty$  then  $(n^{1/2} |\theta_n - \theta_0|)^{-1} T(Q_n(\cdot) / q(\cdot))$  converges in  $P_n$ -probability to  $T(h^T K_a(\cdot) / q(\cdot))$ .
- b If  $\sigma < \infty$  then  $\{T(Q_n(\cdot) / q(\cdot))\}_{n=1}^\infty$  converges in  $P_n$ -distribution to the random variable  $T(\{X(\cdot; \theta_0) + \sigma h^T K_a(\cdot)\} / q(\cdot))$ .

Theorem 4 reveals three types of behavior of the sequence of test statistics  $\{T(Q_n(\cdot) / q(\cdot))\}_{n=1}^\infty$ , depending on the rate at which the alternatives converge to the null hypothesis. If the rate is faster than  $n^{-1/2}$  then we have convergence in distribution to the same limit as under the null hypothesis. If the rate is of the order  $n^{-1/2}$  then we also have convergence in distribution, but to a limit different from the one under the null hypothesis. If the rate is slower than  $n^{-1/2}$  then the convergence in distribution is lost, since the sequence of test statistics blows up as  $n$  tends to infinity.

### 3.3.3 Efficiencies

Now that we have investigated the behavior of the test statistics, it is time to evaluate the corresponding tests. For assessing the performance of a test a multitude of efficiency concepts are available. A few of them are discussed.

To introduce these concept, consider two infinite sequences of tests. Each of the tests in these two sequences has the same size, that is the same probability of falsely rejecting the null hypothesis. For ease of exposition, suppose that the  $n^{\text{th}}$  test in the  $i^{\text{th}}$  sequence [ $i = 1, 2$ ] is based on the test statistic  $T_{in}$ , rejects the null hypothesis if  $T_{in} > t_{in}$ , and does not reject if  $T_{in} < t_{in}$ . We have no knowledge about the action taken if  $T_{in} = t_{in}$ . Hence, the power of the  $n^{\text{th}}$  test in the  $i^{\text{th}}$  sequence under  $P_\theta$  is bounded from below by  $P_\theta(T_{in} > t_{in})$  and from below by  $P_\theta(T_{in} \geq t_{in})$ .

The definition of asymptotic relative Pitman efficiency that follows next is adopted from Wieand (1976).

**Definition 3** For a given function  $\tilde{\beta} : \Theta \rightarrow [0, 1]$ , let  $\bar{N}_i^{\tilde{\beta}}(\theta)$  be the largest sample size such that  $P_\theta(T_{in} \geq t_{in}) < \tilde{\beta}(\theta)$ . If for a unit vector  $h \in \mathbb{R}^p$  there exists a constant  $e_{12}^{\tilde{\beta}}(h)$  such that

$$\liminf_{j \rightarrow \infty} \frac{\bar{N}_2^{\tilde{\beta}}(\theta_j)}{\bar{N}_1^{\tilde{\beta}}(\theta_j)} \geq e_{12}^{\tilde{\beta}}(h)$$

and

$$\limsup_{j \rightarrow \infty} \frac{\bar{N}_2^{\tilde{\beta}}(\theta_j)}{\bar{N}_1^{\tilde{\beta}}(\theta_j)} \leq e_{12}^{\tilde{\beta}}(h)$$

for any sequence  $\{\theta_j\}_{j=1}^\infty$  tending to  $\theta_0$  while satisfying  $\lim_{j \rightarrow \infty} \tilde{\beta}(\theta_j) \in (0, 1)$  and  $\lim_{j \rightarrow \infty} (\theta_j - \theta_0)/|\theta_j - \theta_0| = h$ , then  $e_{12}^{\tilde{\beta}}(h)$  is the asymptotic relative Pitman efficiency in the direction  $h$  of the first sequence of tests with respect to the second.

By using this general definition one allows the asymptotic relative Pitman efficiency to depend on both size and power [which are kept under control] of the tests. In Rothe (1981) an alternative definition is given which involves  $\liminf_{j \rightarrow \infty} \underline{N}_2^{\tilde{\beta}}(\theta_j)/\underline{N}_1^{\tilde{\beta}}(\theta_j)$  and  $\limsup_{j \rightarrow \infty} \bar{N}_2^{\tilde{\beta}}(\theta_j)/\bar{N}_1^{\tilde{\beta}}(\theta_j)$ , where  $\underline{N}_i^{\tilde{\beta}}(\theta)$  is the smallest sample size such that  $P_\theta(T_{in} > t_{in}) \geq \tilde{\beta}(\theta)$ . In case there is a transformation of the test statistics available so as to obtain transformed test statistics which are asymptotically normal and have asymptotic variance 1 for any sequence  $\{\theta_n\}_{n=1}^\infty$  such that  $\lim_{n \rightarrow \infty} n^{1/2}|\theta_n - \theta_0| < \infty$ , then the asymptotic relative Pitman efficiency does not depend on size and power. The asymptotic mean of these transformed test statistics divided by  $\lim_{n \rightarrow \infty} n^{1/2}|\theta_n - \theta_0|$  is the square root of what is called the efficacy of the sequence of test statistics. For two such sequences the asymptotic relative Pitman efficiency is equal to the ratio of their respective efficacies. Unfortunately, since the efficacy approach can not be followed for general sublinear tests [the supremum type tests are for instance explicitly non-normal], the task of establishing asymptotic relative Pitman efficiencies becomes too formidable.

Under these circumstances approximate Bahadur efficiencies are often much easier to compute.

**Definition 4** A sequence of test statistics  $\{T_{in}\}_{n=1}^{\infty}$  is said to be a standard sequence if the following three conditions are satisfied.

- a The sequence  $\{T_{in}\}_{n=1}^{\infty}$  converges in  $P_0$ -distribution to a random variable  $T_i$ .
- b There exists a constant  $a_i > 0$  such that

$$\lim_{t \rightarrow \infty} t^{-2} \log P_0(T_i > t) = -a_i/2.$$

- c For every fixed  $\theta \in \Theta - \{\theta_0\}$  there exists a constant  $b_i(\theta) > 0$  such that  $|n^{-1/2}T_{in} - b_i(\theta)|$  converges to zero in  $P_\theta$ -probability.

The approximate Bahadur slope of a standard sequence  $\{T_{in}\}_{n=1}^{\infty}$  is defined as  $a_i(b_i(\theta))^2$ . The approximate Bahadur efficiency of a standard sequence  $\{T_{1n}\}_{n=1}^{\infty}$  with respect to another standard sequence  $\{T_{2n}\}_{n=1}^{\infty}$  is defined as the ratio of their respective Bahadur slopes  $a_1(b_1(\theta))^2/a_2(b_2(\theta))^2$ .

By Corollary 2 and equations (3.14) and (3.16) it immediately follows that the approximate Bahadur slope of the sequence  $\{T(Q_n(\cdot)/q(\cdot))\}_{n=1}^{\infty}$  is given by  $a\{T(\int_0^1 L(s; \theta)dD(s; \theta_0, \theta)/q(\cdot))\}^2$ .

Approximate Bahadur efficiency has been subject to some criticism. Already in Bahadur (1960) it is advocated that conclusions should not be entirely based on approximate Bahadur slopes. In Wieand (1976) a condition is given under which the existence of the limiting [as the alternative approaches the null hypothesis] approximate Bahadur efficiency implies the existence of the limiting [as the size of the test approaches zero] asymptotic relative Pitman efficiency and the equality of the two limits. This condition obviates most of the difficulties involved in the interpretation of approximate Bahadur efficiencies, at least for  $\theta$  in the vicinity of  $\theta_0$ .

**Definition 5** A standard sequence  $\{T_{in}\}_{n=1}^{\infty}$  is said to be a Wieand sequence if there is a constant  $\epsilon^* > 0$  such that for every  $\epsilon > 0$  and  $\delta \in (0, 1)$  there exists an integer  $N$  such that

$$P_\theta(|n^{-1/2}T_{in} - b_i(\theta)| > \epsilon b_i(\theta)) < \delta$$

for every fixed  $\theta$  satisfying  $|\theta - \theta_0| < \epsilon^*$  and  $n > N/(b_i(\theta))^2$ .

**Theorem 5 (Wieand (1976))** Let  $\{T_{1n}\}_{n=1}^{\infty}$  and  $\{T_{2n}\}_{n=1}^{\infty}$  be two Wieand sequences. Suppose  $\lim_{\theta \rightarrow \theta_0} b_i(\theta) = 0$  for  $i = 1, 2$  and suppose that for every  $p$ -dimensional unit vector  $h$  the limit

$$\lim_{\theta \rightarrow \theta_0} \{a_1(b_1(\theta))^2\}/\{a_2(b_2(\theta))^2\} \quad (3.18)$$

exists if  $(\theta - \theta_0)/|\theta - \theta_0|$  tends to  $h$ . Then the limiting [as the size of the tests approaches zero] asymptotic relative Pitman efficiency exists and is equal to the limit given in (3.18).



Theorem 5 is not valid if Rothe's definition of asymptotic relative Pitman efficiency is used. See Appendix A for more details.

Obviously, the limiting asymptotic relative Pitman efficiency does not depend on the size. Surprisingly, by letting the size of the test tend to zero, the dependence on the power has also vanished.

**Theorem 6** *Let  $h$  be a  $p$ -dimensional unit vector, and let  $\theta$  approach  $\theta_0$  from the direction  $h$  [that is,  $\lim_{\theta \rightarrow \theta_0} (\theta - \theta_0)/|\theta - \theta_0| = h$ ]. If*

$$e(h) = a\{T(h^T K_a(\cdot)/q(\cdot))\}^2 \quad (3.19)$$

*is not equal to zero, then  $\{T(Q_n(\cdot)/q(\cdot))\}_{n=1}^\infty$  is a Wieand sequence with approximate Bahadur slope of the form*

$$|\theta - \theta_0|^2 \{e(h) + o(1)\}. \quad (3.20)$$

The Wieand approach to efficiency is based on letting both the size of the test tend to zero and the alternative tend to the null hypothesis. However, both operations are done separately. In Kallenberg (1983) a concept of efficiency is proposed based on performing both operations simultaneously. It can be considered as intermediate between the Pitman and the exact Bahadur approach.

**Definition 6** *A sequence of test statistics  $\{T_{in}\}_{n=1}^\infty$  is said to be a Kallenberg sequence if the following conditions are satisfied.*

a *There exists a constant  $a_i > 0$  such that*

$$\lim_{n \rightarrow \infty} (s_n)^{-2} \log P_0(T_{in} > s_n) = -a_i/2$$

*for all sequences  $\{s_n\}_{n=1}^\infty$  such that  $s_n \rightarrow \infty$  and  $s_n = o(n^{1/6})$  as  $n \rightarrow \infty$ .*

b *There exists a positive function  $b_i(\theta)$  such that  $n^{-1/2}T_{in}/b_i(\theta_n) \rightarrow 1$  in  $P_n$ -probability for all sequences  $\{\theta_n\}_{n=1}^\infty$  such that  $\theta_n \rightarrow \theta_0$  and  $n^{1/2}|\theta_n - \theta_0| \rightarrow \infty$  as  $n$  tends to infinity.*

*If the sequences  $\{T_{1n}\}_{n=1}^\infty$  and  $\{T_{2n}\}_{n=1}^\infty$  both are Kallenberg and if the limit  $\lim_{n \rightarrow \infty} a_1(b_1(\theta_n))^2/a_2(b_2(\theta_n))^2$  exists, then the asymptotic intermediate efficiency of  $\{T_{1n}\}_{n=1}^\infty$  with respect to  $\{T_{2n}\}_{n=1}^\infty$  is defined as this limit.*

Typically,  $b_i(\theta)$  behaves near  $\theta_0$  as a linear function of  $|\theta - \theta_0|$ , which justifies introducing the intermediate slope  $\lim_{n \rightarrow \infty} a_i(b_i(\theta_n)/|\theta_n - \theta_0|)^2$ . If the weight process  $L_n(t)$  coincides with  $L(t; \theta_0)$  with  $P_n$ -probability 1, then  $T(Q_n(\cdot)/q(\cdot))\}_{n=1}^\infty$  is a Kallenberg sequence with intermediate slope equal to the quantity  $e(h)$  defined by (3.19), as follows from Theorem 4 and the refinement of Theorem 3.

A variant of asymptotic intermediate efficiency, also proposed in Kallenberg (1983), is weak asymptotic intermediate efficiency. Here only sequences  $\{s_n\}_{n=1}^\infty$  such that  $s_n \rightarrow \infty$  and  $s_n = \mathcal{O}((\log n)^{1/2})$  as  $n \rightarrow \infty$  are considered. Observe

that the sequence  $\{T(Q_n(\cdot)/q(\cdot))\}_{n=1}^{\infty}$  has weak intermediate slope  $e(h)$ , even if the weight process does not coincide with its limiting weight function. Hence, the weak intermediate approach yields the same picture as the Wieand approach.

The concepts in Kallenberg (1983) were proposed so as to correspond with several types of moderate and large deviation results. In the light of Theorem 3 it is tempting to propose a variant of asymptotic intermediate efficiency, which considers sequences  $\{s_n\}_{n=1}^{\infty}$  such that  $s_n \rightarrow \infty$  and  $s_n = o(n^{1/18})$  as  $n$  tends to infinity.

In the beginning of this section we assumed that the functional  $T$  is sublinear. A close look reveals that sublinearity is used in the derivation of (3.14) only. Thus, we may set up an equivalent theory for functionals other than sublinear, provided a result similar to (3.14) holds. As examples we mention the functionals occurring in Cramér-von Mises and chi-square tests [see Durbin (1973)].

However, we have preferred to restrict our attention to the class of sublinear tests, since it comprises two particularly appealing subclasses, the class of generalized rank tests, based on the generalized rank functional  $T_R$ , and the class of supremum type tests, based on the supremum functional  $T_S$ . The remainder of this section is devoted to these two subclasses. We should warn that all the attention given here to generalized rank and supremum type tests could falsely yield the impression that they are the only sublinear tests worth notice. For instance, refer to Aki and Kashiwagi (1989) for a sublinear test based on a functional other than  $T_R$  and  $T_S$ .

### 3.3.4 Generalized rank and supremum type tests

It is easily seen that both  $T_R$  and  $T_S$  satisfy Condition 3. Hence, our theory applies [set  $q(t)$  equal to 1 for all  $t \in [0, \infty)$ ]. An application of the Cauchy-Schwarz inequality yields

$$\left(\sup_{f \in \mathcal{S}} \int_0^t L(s; \theta_0) f'(H^1(s; \theta_0)) dH^1(s; \theta_0)\right)^2 \leq \int_0^t (L(s; \theta_0))^2 dH^1(s; \theta_0)$$

for every  $t \in [0, \infty)$ . Moreover, the right-hand side of latter inequality is achieved and bounded by  $\int_0^\infty (L(s; \theta_0))^2 dH^1(s; \theta_0)$ . Thus, defining  $a_R$  and  $a_S$  according to (3.13), with  $T$  replaced by  $T_R$  and  $T_S$  respectively, it follows that

$$a_R = a_S = \left\{ \int_0^\infty (L(s; \theta_0))^2 dH^1(s; \theta_0) \right\}^{-1}. \quad (3.21)$$

Similarly defining  $e_R(h)$  and  $e_S(h)$  according to (3.19), we obtain

$$e_R(h) = a_R \{h^T K_a(\infty)\}^2, \quad (3.22)$$

$$e_S(h) = a_S \left\{ \sup_{t \in [0, \infty)} h^T K_a(t) \right\}^2. \quad (3.23)$$

It should be noted that if the weight process coincides with its limiting function with  $P_n$ -probability 1, then  $T_R(Q_n)$  can be written as the sum of i.i.d. random variables [see Proposition 3.1 in Aki (1986)], and hence results for this special type generalized rank test may be proven in a simpler manner. For instance, Theorem 3 is now an immediate consequence of Theorem 1 on page 549 of Feller (1971). Observe that this alternative proof also leads to a Cramér type large deviation result.

As opposed to general sublinear tests, generalized rank tests do allow us to compute asymptotic relative Pitman efficiencies. By Corollary 2 and Theorem 4b, it follows that the asymptotic power against local alternatives  $\theta_n = \theta_0 + n^{-1/2}h$  of the test based on  $T_R(Q_n)$  of size  $\tilde{\alpha}$  equals

$$P_0(X(\infty; \theta_0) > z_{\tilde{\alpha}}(a_R)^{-1/2} - h^T K_a(\infty)),$$

where  $z_{\tilde{\alpha}}$  is the  $(1 - \tilde{\alpha})$  quantile of the standard normal distribution. This implies that the efficacy of the sequence of test statistics  $\{T_R(Q_n)\}_{n=1}^{\infty}$  is equal to  $e_R(h)$ .

Since applying the Cauchy-Schwarz inequality to  $h^T K_a(\infty)$  yields

$$e_R(h) \leq \int_0^{\infty} (h^T \psi(s; \theta_0))^2 dH^1(s; \theta_0), \quad (3.24)$$

where  $\psi(t; \theta_0)$  is the  $p$ -dimensional vector with elements  $\psi_i(t; \theta_0)$ , it follows that  $e_R(h)$  [and hence asymptotic relative Pitman efficiency, limiting approximate Bahadur efficiency and weak intermediate efficiency of generalized rank tests] is maximized by those tests based on weight processes with limiting weight function satisfying

$$L(t; \theta_0) \propto h^T \psi(t; \theta_0). \quad (3.25)$$

From the following lemma it follows that the upper bound for the efficacy derived in Rao (1963) coincides with the right hand side of inequality (3.24), and thus generalized rank tests based on weight processes with limiting weight function satisfying (3.25) are asymptotically most powerful.

**Lemma 1** *The Fisher information matrix  $I(\theta_0)$  equals the  $p \times p$  matrix with elements*

$$I_{ij}(\theta_0) = \int_0^{\infty} \psi_i(s; \theta_0) \psi_j(s; \theta_0) dH^1(s; \theta_0).$$

Clearly, the use of a generalized rank test instead of a classical test [the likelihood ratio test, say] does not have to result in loss of asymptotic relative efficiency. This raises the question whether the same conclusion holds for a supremum type test. After all, in contrast to the generalized rank test which is not consistent against alternatives approaching the null hypothesis in a direction perpendicular to  $K_a(\infty)$ , the supremum type test has the character of an omnibus test. Needless to say, it is rather attractive to have an efficient omnibus test at our disposal.

In virtually the same way as with  $e_R(h)$ , we obtain that  $e_S(h)$  is maximized by supremum type tests based on weight processes with limiting weight function satisfying (3.25). Furthermore, it is easily seen that these tests have efficiency 1 with respect to the optimal test in the sense of limiting asymptotic relative Pitman efficiency, limiting approximate Bahadur efficiency and weak intermediate efficiency.

This last result may impel to question the usefulness of concepts which are not able to distinguish between generalized rank tests and supremum type tests. However, as recent results on the tail behavior of the supremum of a Gaussian process show, this inability is basically a consequence of letting the size of the test tend to zero, which is the sensible thing to do if we are committed to avoiding making errors, Type I as well as Type II. From Rubin and Sethuraman (1965) it follows that minimizing the Bayes risk leads to letting the size of the test tend to zero at a rate  $n^{-1}$ . Observe that this is exactly the situation to which weak intermediate efficiency refers.

### 3.4 Proofs

In this section we prove the theorems presented in sections 3.2 and 3.3.

**Proof of Theorem 2** As in Einmahl and Koning (1992), proof of Proposition 1 [see also Theorem 3.1 in Burke, Csörgő and Horváth (1981)], let  $\tilde{U}_n$  denote the empirical process based on the uniform (0,1) random variables

$$\tilde{Z}_i = \delta_i H^1(Z_i; \theta_n) + (1 - \delta_i) \{H^1(\infty; \theta_n) + H^0(Z_i; \theta_n)\},$$

where

$$H^0(t; \theta_n) = H(t; \theta_n) - H^1(t; \theta_n)$$

is the cumulative distribution function of the censored failure times under  $P_n$ . Note that

$$U_n^1(t; \theta_n) = \tilde{U}_n(H^1(t; \theta_n)),$$

$$U_{n-}(t; \theta_n) = \tilde{U}_{n-}(H^1(t; \theta_n))$$

$$+ \tilde{U}_{n-}(H^1(\infty; \theta_n) + H^0(t; \theta_n)) - \tilde{U}_{n-}(H^1(\infty; \theta_n)),$$

where  $\tilde{U}_{n-}(t)$  denotes the left continuous version of  $\tilde{U}_n(t)$ . Inequality 2 yields the existence of a sequence  $\{\tilde{B}_n(t)\}_{n=1}^\infty$  of Brownian bridges with continuous sample paths such that for all  $x > 0$

$$P_n\left(\sup_{t \in [0, \infty)} |\tilde{U}_n(t) - \tilde{B}_n(t)| > n^{-1/2}(c_2 \log n + x)\right) \leq c_3 \exp\{-c_4 x\}. \quad (3.26)$$

Now define mean zero Gaussian processes  $B_n^1(t)$ ,  $B_n(t)$  and  $W_n(t)$  by

$$B_n^1(t) = \tilde{B}_n(H^1(t; \theta_n));$$

$$\begin{aligned} B_n(t) &= \tilde{B}_n(H^1(t; \theta_n)) \\ &\quad + \tilde{B}_n(H^1(\infty; \theta_n) + H^0(t; \theta_n)) - \tilde{B}_n(H^1(\infty; \theta_n)), \end{aligned}$$

$$W_n(t) = B_n^1(t) + \int_0^t B_n(s) d\Lambda(s; \theta_0).$$

The processes  $B_n^1(t)$  and  $B_n(t)$  are used to approximate  $U_n^1(t; \theta_n)$  and  $U_{n-}(t; \theta_n)$ , respectively. Thus, it follows by (3.7) that  $W_n(t)$  approximates  $M_n(t; \theta_0) - n^{1/2}D(t; \theta_0, \theta_n)$ . Before studying the implications of this approximation, we first pay attention to the covariance structure of  $W_n(t)$ . Covariance calculations yield

$$\mathcal{E}_n B_n^1(t_1) B_n^1(t_2) = H^1(t_1 \wedge t_2; \theta_n) - H^1(t_1; \theta_n) H^1(t_2; \theta_n),$$

$$\mathcal{E}_n B_n^1(t_1) B_n(t_2) = H^1(t_1 \wedge t_2; \theta_n) - H^1(t_1; \theta_n) H(t_2; \theta_n),$$

$$\mathcal{E}_n B_n(t_1) B_n(t_2) = H(t_1 \wedge t_2; \theta_n) - H(t_1; \theta_n) H(t_2; \theta_n),$$

and hence (3.10). Observe that (3.10) implies

$$\begin{aligned} \mathcal{E}_n \{W_n(t_1) - W_n(t_2)\}^2 &= H^1(t_1 \vee t_2; \theta_n) - H^1(t_1 \wedge t_2; \theta_n) \\ &\quad + 2 \int_{t_1 \wedge t_2}^{t_1 \vee t_2} \{D(s; \theta_0, \theta_n) - D(t_1 \vee t_2; \theta_0, \theta_n)\} d\Lambda(s; \theta_0) \\ &\quad - (D(t_1; \theta_0, \theta_n) - D(t_2; \theta_0, \theta_n))^2, \end{aligned} \tag{3.27}$$

from which we may infer by (3.9)

$$\begin{aligned} \mathcal{E}_n \{W_n(t_1) - W_n(t_2)\}^2 &\leq H^1(t_1 \vee t_2; \theta_n) - H^1(t_1 \wedge t_2; \theta_n) \\ &\quad + 2c_{10} \int_{t_1 \wedge t_2}^{t_1 \vee t_2} (1 - H(s; \theta_n))^{1-\alpha} d\Lambda(s; \theta_0) \\ &\leq c_{26} \int_{t_1 \wedge t_2}^{t_1 \vee t_2} (1 - H(s; \theta_n))^\alpha \{d\Lambda(s; \theta_n) + d\Lambda(s; \theta_0)\}, \end{aligned} \tag{3.28}$$

where  $c_{26} = 1 + 2c_{10}$ . To gain some probabilistic insight in the process  $W_n(t)$ , remark that

$$W_n(t) - \int_0^t \frac{B_n(s)}{1 - H(s; \theta_n)} dD(s; \theta_0, \theta_n)$$

is a time-transformed Wiener process with variance function  $H^1(t; \theta_n)$ . Moreover, the process  $B_n(t)/1 - H(t; \theta_n)$  is a time-transformed Wiener process with variance function  $H(t; \theta_n)/(1 - H(t; \theta_n))$ .

Recall that  $W_n(t)$  approximates  $M_n(t; \theta_0) - n^{1/2}D(t; \theta_0, \theta_n)$ . As a direct consequence we have that  $\int_0^t L_n(s) \{dM_n(s; \theta_0) - n^{1/2}dD(s; \theta_0, \theta_n)\}$  is approximated by  $\int_0^t L_n(s) dW_n(s)$ . Unfortunately, the latter process is not easy to work with [it may not even be Gaussian], so we prefer replacing  $\int_0^t L_n(s) dW_n(s)$  by  $\int_0^t L(s; \theta_n) dW_n(s)$ . To evaluate the effects of this replacement, we make use of a pure jump process  $J_n(t)$ , which is defined by

$$J_n(t) = W_n(x_{i,n}) \quad \text{for } t \in I_{i,n}, \quad (3.29)$$

where  $I_{i,n} = [x_{i,n}, x_{i+1,n})$  and  $0 = x_{0,n} < x_{1,n} < \dots < x_{m(n),n} = \infty$  is a grid chosen so as to satisfy

$$\begin{aligned} & \int_{I_{i,n}} (1 - H(s; \theta_n))^\alpha \{d\Lambda(s; \theta_n) + d\Lambda(s; \theta_0)\} \\ & \leq n^{-1/3} \int_0^\infty (1 - H(s; \theta_n))^\alpha \{d\Lambda(s; \theta_n) + d\Lambda(s; \theta_0)\} \end{aligned} \quad (3.30)$$

for  $i = 0, \dots, m(n) - 1$ . If the grid is chosen carefully, then there is no need for  $m(n)$  to exceed  $n^{1/3} + 1$ . We shall assume that this is indeed the case.

It follows by (3.28) that the variance of the mean zero Gaussian process  $W_n(t)$  is bounded by  $c_{26}c_{10}$ , whereas the variance of the mean zero Gaussian process  $J_n(t) - W_n(t)$  is bounded by  $c_{26}c_{10}n^{-1/3}$ . Hence, by applying Inequality 4 we obtain

$$\begin{aligned} P_n(\sup_{t \in [0, \infty)} |J_n(t)| > x) & \leq P_n(\sup_{t \in [0, \infty)} |W_n(t)| > x) \\ & \leq c_8 \exp\{-c_{27}x^2\}, \end{aligned} \quad (3.31)$$

$$P_n(\sup_{t \in [0, \infty)} |J_n(t) - W_n(t)| > xn^{-1/6}) \leq c_8 \exp\{-c_{27}x^2\}, \quad (3.32)$$

where  $c_{27} = c_9/(c_{26}c_{10})$ . Note that the application of Inequality 4 to  $J_n(t) - W_n(t)$  is justified since this process is separable.

For any sequence  $\{d_n\}_{n=1}^\infty$  of points in  $(0, \infty)$  we may now write

$$\begin{aligned} & \sup_{t \in [0, \infty)} |\{Q_n(t) - n^{1/2} \int_0^t L_n(s) dD(s; \theta_0, \theta_n)\} \\ & \quad - \int_0^t L(s; \theta_n) dW_n(s)|/q(t) \leq \sum_{i=1}^6 \Delta_{ni}, \end{aligned} \quad (3.33)$$

where

$$\begin{aligned}\Delta_{n1} &= \sup_{t \in [0, d_n]} |Q_n(t) - \int_0^t L_n(s) \{dW_n(s) + n^{1/2} dD(s; \theta_0, \theta_n)\}|/q(t), \\ \Delta_{n2} &= \sup_{t \in [d_n, \infty)} |Q_n(t) - Q_n(d_n)|/q(t), \\ \Delta_{n3} &= \sup_{t \in [d_n, \infty)} \left| \int_{d_n}^t L_n(s) dW_n(s) \right|/q(t), \\ \Delta_{n4} &= n^{1/2} \sup_{t \in [d_n, \infty)} \left| \int_{d_n}^t L_n(s) dD(s; \theta_0, \theta_n) \right|/q(t), \\ \Delta_{n5} &= \sup_{t \in [0, \infty)} \left| \int_0^t L_n(s) \{dW_n(s) - dJ_n(s)\} \right|/q(t), \\ \Delta_{n6} &= \sup_{t \in [0, \infty)} \left| \int_0^t \{L_n(s) - L(s; \theta_n)\} dJ_n(s) \right|/q(t).\end{aligned}$$

Observe that the terms  $\Delta_{n5}$  and  $\Delta_{n6}$  relate to the replacement of  $\int_0^t L_n(s) dW_n(s)$  by  $\int_0^t L(s; \theta_n) dW_n(s)$ .

Later in this proof we will meet two specific choices of  $\{d_n\}_{n=1}^\infty$ . A first choice leads to (3.11), and a second to (3.12). Both choices have in common that  $d_n \rightarrow \infty$  as  $n \rightarrow \infty$ . But before these choices are made, we explore the behavior of  $\Delta_{ni}$ ,  $i=1, \dots, 6$  for general sequences. Integration by parts yields with  $P_n$ -probability 1

$$\begin{aligned}\Delta_{n1} &\leq \left\{ \sup_{t \in [0, \infty)} |L_n(t)/q(t)| + V(L_n(\cdot)/q(\cdot)) \right\} \\ &\quad \times \left\{ \sup_{t \in [0, d_n]} |M_n(t; \theta_0) - n^{1/2} D(t; \theta_0, \theta_n) - W_n(t)| \right\} \\ &\leq 2c_{11} \left\{ \sup_{t \in [0, d_n]} |U_n^1(t; \theta_n) - B_n^1(t)| \right. \\ &\quad \left. + \sup_{t \in [0, d_n]} \left| \int_0^t (U_{n-}(s; \theta_n) - B_n(s)) d\Lambda(s; \theta_0) \right| \right\} \\ &\leq 2c_{11} (1 + 3\Lambda(d_n; \theta_0)) \sup_{t \in [0, 1]} |\tilde{U}_n(t) - \tilde{B}_n(t)|.\end{aligned}$$

and therefore it follows by (3.26) that

$$P_n(\Delta_{n1} > 2c_{11}(1 + 3\Lambda(d_n; \theta_0))n^{-1/2}(c_2 \log n + x)) \leq c_3 \exp\{-c_4 x\}. \quad (3.34)$$

Observing that  $\Delta_{n2} = 0$  if  $Z_{n:n} < d_n$ , where  $Z_{n:n}$  denotes the largest order statistic of the sample  $Z_1, \dots, Z_n$ , we obtain

$$P_n(\Delta_{n2} \neq 0) \leq P_n(Z_{n:n} \geq d_n)$$

$$\begin{aligned}
&\leq 1 - (H(d_n; \theta_n))^n \\
&\leq n(1 - H(d_n; \theta_n)). \tag{3.35}
\end{aligned}$$

Twice integrating by parts yields with  $P_n$ -probability 1

$$\begin{aligned}
\Delta_{n3} &\leq \{V(L_n(\cdot)/q(\cdot)) + \sup_{t \in [0, \infty)} |L_n(t)|/q(t)\} \\
&\quad \times \{ \sup_{t \in [d_n, \infty)} | \int_{d_n}^t q(s) dW_n(s) | / q(t) \} \\
&\leq 4c_{11} \sup_{t \in [d_n, \infty)} |W_n(t) - W_n(d_n)|.
\end{aligned}$$

Thus, applying Inequality 4 yields

$$P_n(\Delta_{n3} > 4c_{11}x \{ \sup_{t \in [d_n, \infty)} \mathcal{E}_n \{ W_n(t) - W_n(d_n) \}^2 \}^{1/2}) \leq c_8 \exp\{-c_9 x^2\}. \tag{3.36}$$

Similarly, combining integration by parts with inequality (3.32) produces

$$P_n(\Delta_{n5} > 4c_{11}x n^{-1/6}) \leq c_8 \exp\{-c_{27} x^2\}. \tag{3.37}$$

Furthermore, we have with  $P_n$ -probability 1

$$\begin{aligned}
\Delta_{n6} &\leq \{ \sup_{t \in [0, \infty)} | \int_0^t q(s) dJ_n(s) | / q(t) \} \\
&\quad \times \{ \{ \sum_{i=0}^{m(n)-1} | \{ L_n(x_{i+1,n}) - L(x_{i+1,n}; \theta_n) \} / q(x_{i+1,n}) \\
&\quad \quad - \{ L_n(x_{i,n}) - L(x_{i,n}; \theta_n) \} / q(x_{i,n}) \} | \} \\
&\quad + \sup_{t \in [0, \infty)} |L_n(t) - L(t; \theta_n)| / q(t) \} \\
&\leq (4n^{1/3} + 6) \{ \sup_{t \in [0, \infty)} |J_n(t)| \} \\
&\quad \times \{ \sup_{t \in [0, \infty)} |L_n(t) - L(t; \theta_n)| / q(t) \}. \tag{3.38}
\end{aligned}$$

A general investigation of the behavior of  $\Delta_{n4}$  is rather useless, since it depends too much on the actual situation. Thus, we content ourselves with (3.34)-(3.38).

Next we turn to the aforementioned specific choices of  $\{d_n\}_{n=1}^\infty$ . For both choices the inequalities just derived are sharpened, supplemented by an inequality for  $\Delta_{n4}$ , and combined.



To prove (3.11), choose  $\beta < (1/2 - \alpha) \wedge 1/6$ , and  $d_n$  so as to satisfy  $H(d_n; \theta_n) = 1 - n^{-(\gamma+1)}$ , where  $\gamma = (1/2 - \alpha - \beta)/\alpha$ . Note that  $\gamma > 0$ . Since

$$\begin{aligned} \Lambda(d_n; \theta_0) &< (1 - H(d_n; \theta_n))^{-\alpha} \int_0^{d_n} (1 - H(s; \theta_n))^\alpha d\Lambda(s; \theta_0) \\ &\leq c_\alpha n^{1/2-\beta}, \end{aligned} \quad (3.39)$$

it follows from (3.34) that

$$P_n(\Delta_{n1} > 2c_{11}(1 + 3c_\alpha)(1 + c_2)n^{-\beta} \log n) \leq c_3 n^{-c_4}. \quad (3.40)$$

By (3.35) we immediately have

$$P_n(\Delta_{n2} \neq 0) \leq n^{-\gamma}. \quad (3.41)$$

From (3.27) we may infer for  $t \geq d_n$

$$\mathcal{E}_n\{W_n(t) - W_n(d_n)\}^2 \leq c_{26}c_{10}(1 - H(d_n; \theta_n))^{1-2\alpha},$$

and hence (3.36) implies

$$P_n(\Delta_{n3} > 4c_{11}\{c_{26}c_{10}n^{-(\gamma+2\beta)} \log n\}^{1/2}) \leq c_8 n^{-c_9}. \quad (3.42)$$

Integration by parts yields with  $P_n$ -probability 1

$$\Delta_{n4} \leq 2c_{11}n^{1/2} \sup_{t \in [d_n, \infty)} |D(t; \theta_0, \theta_n) - D(d_n; \theta_0, \theta_n)|,$$

which leads in combination with (3.9) to

$$P_n(\Delta_{n4} > 2c_{11}c_{10}n^{-(\beta+\gamma)}) = 0. \quad (3.43)$$

From (3.37) we obtain

$$P_n(\Delta_{n5} > 4c_{11}n^{-1/6}(\log n)^{1/2}) \leq c_8 n^{-c_{27}}. \quad (3.44)$$

Combining Condition 2c with equations (3.31) and (3.38), it follows that

$$P_n(\Delta_{n6} > 10c_{12}n^{-\beta}(\log n)^{1/2}) \leq (c_{13} + c_8)n^{-(c_{14} \wedge c_{27})} \quad (3.45)$$

[note that we have used  $\beta + 1/3 < 1/2$ ]. Now, (3.40)–(3.45) together with (3.33) yield (3.11).

If  $\theta_n = \theta_0$ , then we may obtain a sharper result by making a different choice of  $d_n$ . Let  $x > 0$ , and choose  $d_n$  so as to satisfy  $H(d_n; \theta_0) = 1 - \exp\{-x\}/n$ . By

noting that  $\Lambda(d_n; \theta_0) \leq -\log(1 - H(d_n; \theta_0)) = \log n + x$ , we obtain from (3.34) for  $n > 1$

$$\begin{aligned} P_0(\Delta_{n1} > 2c_{11}n^{-1/2}(5\log n + 3x)(c_2\log n + x)) \\ \leq c_3 \exp\{-c_4x\}. \end{aligned} \quad (3.46)$$

Furthermore, we have by (3.35)

$$P_0(\Delta_{n2} \neq 0) \leq \exp\{-x\}, \quad (3.47)$$

and since by (3.27)

$$\begin{aligned} x \sup_{t \in [d_n, \infty)} \mathcal{E}_0\{W_n(t) - W_n(d_n)\}^2 \\ \leq x(H^1(\infty; \theta_0) - H^1(d_n; \theta_0)) \\ \leq x(1 - H(d_n; \theta_0)) \\ \leq n^{-1}, \end{aligned}$$

it follows by (3.36)

$$P_0(\Delta_{n3} > 4c_{11}n^{-1/2}) \leq c_8 \exp\{-c_9x\}. \quad (3.48)$$

As a simple consequence of the fact that  $D(t; \theta_0, \theta_0)$  is identical to zero, we have

$$P_0(\Delta_{n4} \neq 0) = 0. \quad (3.49)$$

Equation (3.37) implies

$$P_0(\Delta_{n5} > 4c_{11}n^{-1/6}x) \leq 2c_8 \exp\{-c_{27}x\}, \quad (3.50)$$

whereas combining Condition 2d with equations (3.31) and (3.38) yields

$$P_0(\Delta_{n6} > 10n^{-1/6}x^{1/2}(c_{15}\log n + x)) \leq (c_{16} + c_8) \exp\{-(c_{17} \wedge c_{27})x\}. \quad (3.51)$$

Hence, (3.46)–(3.51) together with (3.33) yield (3.12).

We conclude the proof of Theorem 2 with the remark that if  $L_n(t)$  coincides with  $L(t; \theta_n)$  with  $P_n$ -probability 1, it suffices to bound the left hand side of (3.33) by  $\sum_{i=1}^4 \Delta_{ni}$ . This yields the refinement of Theorem 2 mentioned at the end of section 2.  $\square$

**Proof of Theorem 3** Equation (3.14) directly follows from Corollary 1. To prove (3.15), observe that as a consequence of Theorem 2 there exists a process  $X_n(t; \theta_0)$ , equal in  $P_0$ -distribution to  $X(t; \theta_0)$ , which satisfies

$$\begin{aligned} P_0\left(\sup_{t \in [0, \infty)} |Q_n(t) - X_n(t; \theta_0)|/q(t) > n^{-c_{28}}(c_{21} \log n + x)^{c_{29}}\right) \\ \leq c_{22} \exp\{-c_{23}x\}, \end{aligned} \quad (3.52)$$

with  $c_{28} = 1/6$  and  $c_{29} = 2$ . Now, let  $c_{30} = c_{28}/(2c_{29} - 1)$  and choose  $c_{29}^{-1} < \beta < 2$ . Note that for  $n \rightarrow \infty$

$$\begin{aligned} n^{c_{30}(2-\beta)}(s_n)^\beta &\gg n^{c_{30}(2-\beta)} \gg \log n, \\ n^{c_{30}(2-\beta)}(s_n)^\beta &= (n^{-c_{30}} s_n)^{\beta-2} (s_n)^2 \gg (s_n)^2, \\ (n^{-c_{30}} s_n)^{c_{29}\beta-1} &\ll 1 \end{aligned}$$

[here  $a_n \gg b_n$  denotes  $b_n/a_n \rightarrow 0$ ], and hence (3.52) implies

$$\begin{aligned} P_0(|T(Q_n(\cdot)/q(\cdot)) - T(X_n(\cdot; \theta_0)/q(\cdot))| > c_T n^{c_{30}(1-c_{29}\beta)}(s_n)^{c_{29}\beta}) \\ \leq P_0\left(\sup_{t \in [0, \infty)} |Q_n(t) - X_n(t; \theta_0)|/q(t) > n^{c_{30}(1-c_{29}\beta)}(s_n)^{c_{29}\beta}\right) \\ \leq c_{22} \exp\{-c_{23}(n^{c_{30}(2-\beta)}(s_n)^\beta - c_{21} \log n)\} \\ \ll \exp\{-a(s_n)^2/2\}. \end{aligned} \quad (3.53)$$

Since  $T(X_n(\cdot; \theta_0)/q(\cdot))$  and  $T(X(\cdot; \theta_0)/q(\cdot))$  are equal in  $P_0$ -distribution, we may bound  $P_0(T(Q_n(\cdot)/q(\cdot)) > s_n)$  from below by

$$\begin{aligned} P_0(T(X(\cdot; \theta_0)/q(\cdot)) > s_n(1 + c_T(n^{-c_{30}} s_n)^{c_{29}\beta-1})) \\ - P_0(|T(X_n(\cdot; \theta_0)/q(\cdot)) - T(Q_n(\cdot)/q(\cdot))| > c_T n^{c_{30}(1-c_{29}\beta)}(s_n)^{c_{29}\beta}) \end{aligned}$$

and from above by

$$\begin{aligned} P_0(T(X(\cdot; \theta_0)/q(\cdot)) > s_n(1 - c_T(n^{-c_{30}} s_n)^{c_{29}\beta-1})) \\ + P_0(|T(X_n(\cdot; \theta_0)/q(\cdot)) - T(Q_n(\cdot)/q(\cdot))| > c_T n^{c_{30}(1-c_{29}\beta)}(s_n)^{c_{29}\beta}) \end{aligned}$$

and thus it follows that (3.14) and (3.53) together yield (3.15). This concludes the proof of Theorem 3.  $\square$

The proofs of Theorem 4 and Theorem 6 make repeated use of the following lemma, which holds under Conditions 1 and 6.

**Lemma 2** Let  $g(t; \theta)$  be a real valued function,  $g_i^{(1)}(t; \theta)$  the first order partial derivative of  $g(t; \theta)$  with respect to the  $i^{\text{th}}$  component of  $\theta$ . Suppose there exists a constant  $c_{31}$  such that

$$\sup_{t \in [0, \infty)} (1 - H(t; \theta))^{\frac{1}{2}} |g(t; \theta)| < c_{31}, \quad (3.54)$$

$$\sup_{t \in [0, \infty)} (1 - H(t; \theta))^{1-\alpha} |g_i^{(1)}(t; \theta)| < c_{31} \quad (3.55)$$

for every  $\theta \in \Theta$ . Then there exists a constant  $c_{32}$  such that

$$\sup_{t \in [0, \infty)} \left| \int_0^t g(s; \theta) dD(s; \theta_0, \theta) \right| \leq c_{32} |\theta - \theta_0|, \quad (3.56)$$

$$\sup_{t \in [0, \infty)} \left| \int_0^t g(s; \theta) dH^1(s; \theta) - \int_0^t g(s; \theta_0) dH^1(s; \theta_0) \right| \leq c_{32} |\theta - \theta_0| \quad (3.57)$$

for every  $\theta \in \Theta$ . Let  $g_{ij}^{(2)}(t; \theta)$  the second order partial derivative of  $g(t; \theta)$  with respect to the  $i^{\text{th}}$  and  $j^{\text{th}}$  components of  $\theta$ . If

$$\sup_{t \in [0, \infty)} (1 - H(t; \theta))^{\alpha} |g(t; \theta)| < c_{31}, \quad (3.58)$$

$$\sup_{t \in [0, \infty)} (1 - H(t; \theta))^{\frac{1}{2}} |g_i^{(1)}(t; \theta)| < c_{31}, \quad (3.59)$$

$$\sup_{t \in [0, \infty)} (1 - H(t; \theta))^{1-\alpha} |g_{ij}^{(2)}(t; \theta)| < c_{31} \quad (3.60)$$

then

$$\begin{aligned} & \sup_{t \in [0, \infty)} \left| \int_0^t g(s; \theta) dD(s; \theta_0, \theta) \right. \\ & \quad \left. - \int_0^t (\theta - \theta_0)^T \psi(s; \theta_0) g(s; \theta_0) dH^1(s; \theta_0) \right| \\ & \leq c_{32} |\theta - \theta_0|^2 \end{aligned} \quad (3.61)$$

for every  $\theta \in \Theta$ .

**Corollary 3** There exists a constant  $c_{32}$  such that

$$\sup_{t \in [0, \infty)} \left| \int_0^t (1 - H(s; \theta))^{-\frac{1}{2}} dD(s; \theta_0, \theta) \right| \leq c_{32} |\theta - \theta_0|.$$

for every  $\theta \in \Theta$ .

**Proof of Lemma 2** For convenience, we introduce the functions

$$\Lambda_0(t; \theta) = \Lambda(t; \theta) - \Lambda(t; \theta_0),$$

$$\lambda_0(t; \theta) = \lambda(t; \theta) - \lambda(t; \theta_0).$$

Let  $\Lambda_i^{(1)}(t; \theta)$  and  $\lambda_i^{(1)}(t; \theta)$  respectively denote the first order partial derivatives of  $\Lambda_0(t; \theta)$  and  $\lambda_0(t; \theta)$  with respect to the  $i^{\text{th}}$  component of  $\theta$ . Furthermore, let  $\Lambda_{ij}^{(2)}(t; \theta)$  and  $\lambda_{ij}^{(2)}(t; \theta)$  respectively denote the second order partial derivatives of  $\Lambda_0(t; \theta)$  and  $\lambda_0(t; \theta)$  with respect to the  $i^{\text{th}}$  and  $j^{\text{th}}$  components of  $\theta$ . By Condition 6 we have for every  $t \in [0, \infty)$

$$\begin{aligned} & \int_0^t (1 - H(s; \theta))^{\frac{1}{2} - \alpha} |\lambda_i^{(1)}(s; \theta)| ds \\ &= \int_0^t (1 - H(s; \theta))^{\frac{1}{2} - \alpha} |\psi_i(s; \theta)| d\Lambda(s; \theta) \\ &\leq \left\{ \int_0^\infty (1 - H(s; \theta))^\beta d\Lambda(s; \theta) \right\}^{1/2} \\ &\quad \times \left\{ \int_0^\infty (\psi_i(s; \theta))^2 (1 - H(s; \theta))^{1 - 2\alpha - \beta} d\Lambda(s; \theta) \right\}^{1/2} \\ &\leq (c_{24}/\beta)^{1/2}, \end{aligned} \tag{3.62}$$

and hence

$$\begin{aligned} & (1 - H(t; \theta))^{\frac{1}{2} - \alpha} |\Lambda_i^{(1)}(t; \theta)| \\ &= (1 - H(t; \theta))^{\frac{1}{2} - \alpha} \left| \int_0^t \lambda_i^{(1)}(s; \theta) ds \right| \\ &\leq \int_0^t (1 - H(s; \theta))^{\frac{1}{2} - \alpha} |\lambda_i^{(1)}(s; \theta)| ds \\ &\leq (c_{24}/\beta)^{1/2}. \end{aligned} \tag{3.63}$$

Now, we find by using the identity

$$1 - H(t; \theta) = (1 - H(t; \theta_0)) \exp\{-\Lambda_0(t; \theta)\}$$

that the first order partial derivative of  $\int_0^t g(s; \theta) \lambda_0(s; \theta) (1 - H(s; \theta)) ds$  with respect to the  $i^{\text{th}}$  component of  $\theta$  is given by

$$\int_0^t \{g_i^{(1)}(s; \theta) - g(s; \theta) \Lambda_i^{(1)}(s; \theta)\} \lambda_0(s; \theta) + g(s; \theta) \lambda_i^{(1)}(s; \theta) (1 - H(s; \theta)) ds,$$

and is bounded in  $t$  and  $\theta$ , as follows from Condition 1, (3.54), (3.55), (3.62) and (3.63). By expressing  $D(t; \theta_0, \theta)$  as  $\int_0^t (1 - H(s; \theta)) \lambda_0(s; \theta) ds$  we obtain (3.56)

As for (3.57), by writing  $H^1(t; \theta) = \int_0^t (1 - H(s; \theta)) \lambda(s; \theta) ds$ , it follows that the first order partial derivative of  $\int_0^t g(s; \theta) dH^1(s; \theta)$  with respect to the  $i^{\text{th}}$  component of  $\theta$  is given by

$$\int_0^t \{g_i^{(1)}(s; \theta) + g(s; \theta) \{\psi_i(s; \theta) - \Lambda_i^{(1)}(s; \theta)\} (1 - H(s; \theta)) \lambda(s; \theta) ds$$

and is bounded in  $t$  and  $\theta$ .

Finally (3.61). For every  $t \in [0, \infty)$  we have

$$\begin{aligned} & \int_0^t (1 - H(s; \theta))^{(1-2\alpha)} |\lambda_{ij}^{(2)}(s; \theta)| ds \\ &= \int_0^t (1 - H(s; \theta))^{(1-2\alpha)} |\psi_{ij}^{(1)}(s; \theta) + \psi_i(s; \theta) \psi_j(s; \theta)| d\Lambda(s; \theta) \\ &\leq \left\{ \int_0^\infty (1 - H(s; \theta))^\beta d\Lambda(s; \theta) \right\}^{1/2} \\ &\quad \times \left\{ \int_0^\infty (\psi_{ij}^{(1)}(s; \theta))^2 (1 - H(s; \theta))^{2(1-2\alpha)-\beta} d\Lambda(s; \theta) \right\}^{1/2} \\ &\quad + \left\{ \int_0^\infty (\psi_i(s; \theta))^2 (1 - H(s; \theta))^{1-2\alpha-\beta} d\Lambda(s; \theta) \right\}^{1/2} \\ &\quad \times \left\{ \int_0^\infty (\psi_j(s; \theta))^2 (1 - H(s; \theta))^{1-2\alpha-\beta} d\Lambda(s; \theta) \right\}^{1/2} \\ &\leq (c_{24}/\beta)^{1/2} + c_{24}, \end{aligned} \tag{3.64}$$

and

$$(1 - H(t; \theta))^{(1-2\alpha)} |\Lambda_{ij}^{(2)}(t; \theta)| \leq (c_{24}/\beta)^{1/2} + c_{24}. \tag{3.65}$$

Note that the first order partial derivative of  $\int_0^t g(s; \theta) \lambda_0(s; \theta) (1 - H(s; \theta)) ds$  with respect to the  $i^{\text{th}}$  component of  $\theta$  equals  $\int_0^t g(s; \theta_0) \psi_i(s; \theta_0) dH^1(s; \theta_0)$  when evaluated at  $\theta = \theta_0$ . Furthermore, the second order partial derivative with respect to the  $i^{\text{th}}$  and  $j^{\text{th}}$  component of  $\theta$  is given by

$$\begin{aligned} & \int_0^t \{ \{g_{ij}^{(2)}(s; \theta) - g_i^{(1)}(s; \theta) \Lambda_j^{(1)}(s; \theta) - g_j^{(1)}(s; \theta) \Lambda_i^{(1)}(s; \theta) \\ & \quad - g(s; \theta) \Lambda_{ij}^{(2)}(s; \theta) + g(s; \theta) \Lambda_i^{(1)}(s; \theta) \Lambda_j^{(1)}(s; \theta) \} \lambda_0(s; \theta) \\ & \quad + \{g_j^{(1)}(s; \theta) - g(s; \theta) \Lambda_j^{(1)}(s; \theta)\} \lambda_i^{(1)}(s; \theta) \\ & \quad + \{g_i^{(1)}(s; \theta) - g(s; \theta) \Lambda_i^{(1)}(s; \theta)\} \lambda_j^{(1)}(s; \theta) \\ & \quad + g(s; \theta) \lambda_{ij}^{(2)}(s; \theta) \} (1 - H(s; \theta)) ds. \end{aligned}$$

Hence, (3.61) follows from Condition 1, Condition 6, (3.55), (3.58), (3.60) and (3.62)-(3.65). This concludes the proof of Lemma 2.  $\square$

**Proof of Theorem 4** Let  $\{W_n(t)\}_{n=1}^\infty$  be the sequence of mean zero Gaussian processes given in Theorem 2. We may write

$$\sup_{t \in [0, \infty)} |Q_n(t) - n^{1/2} |\theta_n - \theta_0| h^T K_a(t) / q(t)| \leq \sum_{i=1}^4 \Delta_{ni}, \quad (3.66)$$

where

$$\begin{aligned} \Delta_{n1} &= \sup_{t \in [0, \infty)} \left| \{Q_n(t) - n^{1/2} \int_0^t L_n(s) dD(s; \theta_0, \theta_n)\} \right. \\ &\quad \left. - \int_0^t L(s; \theta_n) dW_n(s) / q(t) \right|, \\ \Delta_{n2} &= \sup_{t \in [0, \infty)} \left| \int_0^t L(s; \theta_n) dW_n(s) / q(t) \right|, \\ \Delta_{n3} &= n^{1/2} \sup_{t \in [0, \infty)} \left| \int_0^t (L_n(s) - L(s; \theta_n)) dD(s; \theta_0, \theta_n) / q(t) \right|, \\ \Delta_{n4} &= n^{1/2} \sup_{t \in [0, \infty)} \left| \int_0^t L(s; \theta_n) dD(s; \theta_0, \theta_n) - |\theta_n - \theta_0| h^T K_a(t) / q(t) \right|. \end{aligned}$$

By (3.11) we have for  $\beta < (1/2 - \alpha) \wedge 1/6$

$$P_n(\Delta_{n1} > c_{18} n^{-\beta}) \leq c_{19} n^{-c_{20}}. \quad (3.67)$$

From integration by parts we obtain with  $P_n$ -probability 1

$$\begin{aligned} \Delta_{n2} &\leq 2c_{11} \sup_{t \in [0, \infty)} \left| \int_0^t q(s) / q(t) dW_n(s) \right| \\ &\leq 2c_{11} \sup_{t \in [0, \infty)} 2 \sup_{0 \leq s \leq t} |W_n(s)| \\ &\leq 4c_{11} \sup_{t \in [0, \infty)} |W_n(t)|. \end{aligned}$$

Since by (3.28) and Condition 1 the variance function of the process  $W_n(t)$  is bounded by  $(c_{26})^2$ , it follows by Inequality 4

$$P_n(\Delta_{n2} > 4c_{11} c_{26} x) \leq c_8 \exp\{-c_9 x^2\}. \quad (3.68)$$

Lemma 2 yields the existence of a constant  $c_{33}$  such that

$$\Delta_{n4} \leq c_{33} n^{1/2} \{|\theta_n - \theta_0|^2 + |(\theta_n - \theta_0) - |\theta_n - \theta_0| h|\} \quad (3.69)$$

and for every  $\theta \in \Theta$  and  $\beta < 1/2$

$$\begin{aligned} &P_n(n^\beta \sup_{t \in [0, \infty)} \int_0^t (L_n(s) - L(s; \theta_n)) dD(s; \theta_0, \theta) / q(t) > c_{33} |\theta - \theta_0|) \\ &\leq P_n(n^\beta \sup_{t \in [0, \infty)} \sup_{0 \leq s \leq t} |L_n(s) - L(s; \theta_n)| / q(t) > c_{12}). \end{aligned}$$

Note that by Condition 2c this last inequality implies

$$P_n((n^{1/2}|\theta_n - \theta_0|)^{-1}\Delta_{n3} > c_{33}n^{-\beta}) \leq c_{13}n^{-c_{14}}. \quad (3.70)$$

The first part of the theorem is now easily proved by means of the inequality

$$\begin{aligned} & |(n^{1/2}|\theta_n - \theta_0|)^{-1}T(Q_n(\cdot)/q(\cdot)) - T(h^TK_a(\cdot)/q(\cdot))| \\ & \leq c_T(n^{1/2}|\theta_n - \theta_0|)^{-1} \sum_{i=1}^4 \Delta_{ni}, \end{aligned} \quad (3.71)$$

To prove the second part of the theorem, we first note that the supremum over  $t$  of the distance between the processes  $Q_n(t)/q(t)$  and  $\{\int_0^t L(s; \theta_n)dW_n(s) + n^{1/2}|\theta_n - \theta_0|h^TK_a(t)\}/q(t)$  is bounded by  $\Delta_{n1} + \Delta_{n3} + \Delta_{n4}$ , and hence converges to zero in  $P_n$ -probability if  $n^{1/2}|\theta_n - \theta_0|$  tends to a finite limit as  $n \rightarrow \infty$ . Thus, it remains to show that the latter process converges in  $P_n$ -distribution to  $\{X(t; \theta_0) + \sigma h^TK_a(t)\}/q(t)$ , which boils down to the convergence in  $P_n$ -distribution of  $\int_0^t L(s; \theta_n)dW_n(s)/q(t)$  to  $X(t; \theta_0)/q(t)$ .

Let  $B_n(t)$  be as defined in the proof of Theorem 2. Split  $\int_0^t L(s; \theta_n)dW_n(s)/q(t)$  into the two parts

$$\int_0^t L(s; \theta_n) \left\{ dW_n(s) - \frac{B_n(s)}{1 - H(s; \theta_n)} dD(s; \theta_0, \theta_n) \right\} / q(t)$$

and

$$\int_0^t L(s; \theta_n) \frac{B_n(s)}{1 - H(s; \theta_n)} dD(s; \theta_0, \theta_n) / q(t).$$

The first part may be interpreted as a time-transformed Wiener process divided by  $q(t)$ , the time transformed Wiener process having variance function  $\int_0^t (L(s; \theta_n))^2 dH^1(s; \theta_n) / (q(t))^2$ . It follows from our Lemma 2 and Theorem VI.10 in Pollard (1984) that the first part converges in  $P_n$ -distribution to  $X(t; \theta_0)/q(t)$ . Use Lemma 2 to show that the supremum over  $t$  of the second part converges to zero in  $P_n$ -probability. This completes the proof of Theorem 4.  $\square$

**Proof of Theorem 6** Let  $\Delta_{n1}, \Delta_{n2}, \Delta_{n3}$  and  $\Delta_{n4}$  be as in the proof of Theorem 4, and define  $b(\theta_n)$  as  $T(\int_0^t L(s; \theta_n)dD(s; \theta_0, \theta_n)/q(\cdot))$ . We may write

$$|n^{-1/2}T(Q_n(\cdot)/q(\cdot)) - b(\theta_n)| \leq c_T n^{-1/2} \{\Delta_{n1} + \Delta_{n2} + \Delta_{n3}\}. \quad (3.72)$$

Furthermore, we have

$$|b(\theta_n) - |\theta_n - \theta_0|T(h^TK_a(\cdot)/q(\cdot))| \leq c_T n^{-1/2} \Delta_{n4}. \quad (3.73)$$

Since  $e(h)$  is not equal to zero, this yields the existence of positive constants  $\epsilon^*$  and  $c_{34}$  such that for  $\theta_n$  satisfying  $|\theta_n - \theta_0| < \epsilon^*$

$$c_{34}|\theta_n - \theta_0| < b(\theta_n) < 1. \quad (3.74)$$



Now suppose  $\theta \in \Theta - \{\theta_0\}$  satisfies  $|\theta - \theta_0| < \epsilon^*$ , and set  $\theta_n$  equal to  $\theta$ . Choose  $\epsilon > 0$  and  $\delta \in (0, 1)$ . By (3.67) and (3.68) it follows that there exists an integer  $N_1$  not depending on  $\theta$  such that for  $n > N_1$

$$\begin{aligned} P_\theta(\Delta_{n1} > (N_1)^{1/2}\epsilon/4c_T) &< \delta/4, \\ P_\theta(\Delta_{n2} > (N_1)^{1/2}\epsilon/4c_T) &< \delta/4. \end{aligned}$$

Hence, for  $n > N_1/(b(\theta))^2$  we have

$$P_\theta(n^{-1/2}\{\Delta_{n1} + \Delta_{n2}\} > eb(\theta)/2c_T) < \delta/2, \quad (3.75)$$

since  $n > N_1$  and  $(N_1/n)^{1/2} < b(\theta)$ . Moreover, (3.70) implies the existence of an integer  $N > N_1$  not depending on  $\theta$  such that for  $n > N$

$$\begin{aligned} P_\theta(\Delta_{n3} > eb(\theta)/2c_T) \\ \leq P_\theta((n^{1/2}|\theta - \theta_0|)^{-1}\Delta_{n3} > c_{34}\epsilon) \\ < \delta/2. \end{aligned} \quad (3.76)$$

Combining (3.72)-(3.76) now yields that  $\{T(Q_n(\cdot)/q(\cdot))\}_{n=1}^\infty$  is indeed a Wieand sequence.

Finally, (3.20) immediately follows from (3.69) and (3.73). This concludes the proof of Theorem 6.  $\square$

**Proof of Lemma 1** The log-likelihood of the observation  $(Z_1, \delta_1)$  under  $P_\theta$  is

$$\ell(\theta; Z_1, \delta_1) = \delta_1 \log \lambda(Z_1; \theta) - \Lambda(Z_1; \theta)$$

[see Borgan (1984)]. This yields that

$$\frac{\partial}{\partial \theta_i} \ell(\theta; Z_1, \delta_1) = \delta_1 \psi_i(Z_1; \theta) - \int_0^{Z_1} \psi_i(s; \theta) d\Lambda(s; \theta)$$

is the score for the  $i^{\text{th}}$  component of  $\theta$ . Observe the close relation between  $\psi_i(t; \theta)$  and the score function. The information matrix  $I(\theta)$  has elements

$$\begin{aligned} I_{ij}(\theta) &= \mathcal{E}_\theta \left\{ \frac{\partial}{\partial \theta_i} \ell(\theta; Z_1, \delta_1) \right\} \left\{ \frac{\partial}{\partial \theta_j} \ell(\theta; Z_1, \delta_1) \right\} \\ &= \int_0^\infty \psi_i(t; \theta) \psi_j(t; \theta) dH^1(t; \theta) \\ &\quad - \int_0^\infty \psi_i(t; \theta) \int_0^t \psi_j(s; \theta) d\Lambda(s; \theta) dH^1(t; \theta) \\ &\quad - \int_0^\infty \psi_j(t; \theta) \int_0^t \psi_i(s; \theta) d\Lambda(s; \theta) dH^1(t; \theta) \\ &\quad + \int_0^\infty \int_0^t \psi_i(s; \theta) d\Lambda(s; \theta) \int_0^t \psi_j(u; \theta) d\Lambda(u; \theta) dH(t; \theta) \\ &= \int_0^\infty \psi_i(t; \theta) \psi_j(t; \theta) dH^1(t; \theta). \end{aligned}$$

The last line follows from

$$\begin{aligned}
& \int_0^\infty \psi_i(t; \theta) \int_0^t \psi_j(s; \theta) d\Lambda(s; \theta) dH^1(t; \theta) \\
& \quad + \int_0^\infty \psi_j(t; \theta) \int_0^t \psi_i(s; \theta) d\Lambda(s; \theta) dH^1(t; \theta) \\
& = \int_0^\infty \{ \psi_i(t; \theta) \int_0^t \psi_j(s; \theta) d\Lambda(s; \theta) \\
& \quad + \psi_j(t; \theta) \int_0^t \psi_i(s; \theta) d\Lambda(s; \theta) \} \int_t^\infty dH(u; \theta) d\Lambda(t; \theta) \\
& = \int_0^\infty \int_0^u \{ \psi_i(t; \theta) \int_0^t \psi_j(s; \theta) d\Lambda(s; \theta) \\
& \quad + \psi_j(t; \theta) \int_0^t \psi_i(s; \theta) d\Lambda(s; \theta) \} d\Lambda(t; \theta) dH(u; \theta) \\
& = \int_0^\infty \int_0^u \psi_i(t; \theta) d\Lambda(t; \theta) \int_0^u \psi_j(s; \theta) d\Lambda(s; \theta) dH(u; \theta).
\end{aligned}$$

This ends the proof of Lemma 1. □

## Chapter 4

# The composite null hypothesis

### 4.1 Introduction

In this chapter the results for the simple null hypothesis are extended to the composite null hypothesis, which involves estimation as well as testing. Though the lines of the previous chapter are followed rather closely, this chapter is made as self-contained as possible. As a consequence some of the remarks may seem familiar.

Again,  $(\Omega, \mathcal{A}, \mathcal{P})$  is a probability space, and  $\mathcal{F}_n \subset \mathcal{B}[0, \infty)$ . At stage  $n$  each of the independent random variables  $X_1, \dots, X_n, Y_1, \dots, Y_n$  maps  $(\Omega, \mathcal{A})$  into  $([0, \infty), \mathcal{F}_n)$ . The probability measure induced by these random variables is denoted by  $P_n$ . Each pair  $(X_i, Y_i)$  is assumed to have the same distribution. The censoring distribution, the distribution of the censoring time  $Y_i$ , does not depend on  $n$ . Hence, there exists a cumulative distribution  $G$  such that  $G(t) = P_n(Y_i \leq t)$  for each  $n$ . Defectiveness of  $G$  is allowed. The failure time distribution, the distribution of  $X_i$ , does depend on  $n$ .

However, the structure of the dependence of the failure time distribution on the sample size  $n$  is different. Now we suppose the existence of a cumulative distribution function  $F$ , indexed by  $(v, \theta)$  belonging to some set  $\Upsilon \times \Theta$ , and a sequence of points  $\{(v_n, \theta_n)\}_{n=1}^{\infty}$  such that  $F(t; v_n, \theta_n) = P_n(X_i \leq t)$ .

The set  $\Upsilon$  refers to the nuisance parameter, the parameter which value is not specified in the null hypothesis. Any information concerning these parameters must be supplied by the sample.

The set  $\Theta$  refers to the parameter of interest, the parameter which value is specified in the null hypothesis. Denote the value of the parameter of interest under the null hypothesis by  $\theta_0$ . Thus, at every stage  $n$  we want to test the null hypothesis that  $\theta_n$  equals  $\theta_0$ .

Let  $v_0$  be an *arbitrary* element of  $\Upsilon$ . If  $(v_n, \theta_n)$  equals  $(v_0, \theta_0)$  [denote the probability measure corresponding to this situation by  $P_{v_0}$ , the expectation operator belonging to this probability measure by  $\mathcal{E}_{v_0}$ , and the situation itself by

“under  $P_{v_0}$ ”] then the basic martingale takes the form

$$M_n(t; v_0, \theta_0) = n^{1/2} \left\{ H_n^1(t) - \int_0^t (1 - H_{n-}(s)) d\Lambda(s; v_0, \theta_0) \right\}, \quad (4.1)$$

where  $\Lambda(t; v, \theta) = -\log(1 - F(t; v, \theta))$  is the cumulative hazard function belonging to  $F(t; v, \theta)$ . If  $(v_n, \theta_n)$  is arbitrary [refer to this situation as “under  $P_n$ ” and denote the expectation operator by  $\mathcal{E}_n$ ] we also call  $M_n(t; v_0, \theta_0)$  a basic martingale, despite the fact that the martingale property is in general lacking.

In section 4.3 we study tests based on a sublinear Lipschitz functional of a process  $Q_n(t; v^{(n)})$ , where  $v^{(n)}$  is a random element of  $\Upsilon$  and

$$Q_n(t; v) = \int_0^t L_n(s; v) dM_n(s; v, \theta_0) \quad (4.2)$$

is a stochastic integral with respect to the basic martingale. Here the weight process  $L_n(t; v)$  is a stochastic process.

We restrict ourselves to the case where  $\Upsilon$  is a convex subset of  $\mathbb{R}^r$ . In section 4.2 the probability theory underlying the results in section 4.3 is presented. Proofs are gathered in section 4.4.

## 4.2 Probability inequalities

In this section we present probability inequalities which concern the approximation on the halfline  $[0, \infty)$  of [a centered version of] the process  $Q_n(t; v^{(n)})$  by a one-parameter Gaussian process, both under  $P_n$  as under  $P_{v_0}$ . For treatment of the former situation, the following condition, which relates the right tail behavior of  $F(t; v, \theta)$  to the right tail behavior of  $F(t; v_0, \theta_0)$ , is needed [compare with Condition 1].

**Condition 8** *There exists constants  $0 < \alpha < 1/2$  and  $c_\alpha < \infty$  such that*

$$\int_0^\infty (1 - F(s; v, \theta))^\alpha d\Lambda(s; v_0, \theta_0) < c_\alpha$$

*for every  $v, v_0 \in \Upsilon$  and  $\theta \in \Theta$ .*

### 4.2.1 The M-estimator $v^{(n)}$

Of course, before studying the process  $Q_n(t; v^{(n)})$  we must know the properties of the random variable  $v^{(n)}$ . It is desirable that, at least under the null hypothesis,  $v^{(n)}$  is an estimator for  $v_0$ . Hence, we let  $v^{(n)}$  belong to the class of M-estimators proposed by Hjort (1985). An M-estimator  $v^{(n)}$  is obtained as the solution in  $\Upsilon$  to the equations

$$\Phi_{ni}(\infty; v^{(n)}) = 0 \quad i = 1, \dots, r, \quad (4.3)$$

where  $\Phi_{ni}(t; v)$  is the stochastic integral

$$\Phi_{ni}(t; v) = \int_0^t \phi_i(s; v) dM_n(s; v, \theta_0), \quad (4.4)$$

and  $\phi_i(t; v)$  is a given function.

The most prominent example of an M-estimator is without any doubt the maximum likelihood estimator. Since under  $P_{v_0}$  the log-likelihood of the sample  $(Z_1, \delta_1), \dots, (Z_n, \delta_n)$  is given by

$$n \int_0^\infty \log \lambda(s; v_0, \theta_0) dH_n^1(s) - n \int_0^\infty (1 - H_{n-}(s)) d\Lambda(s; v_0, \theta_0), \quad (4.5)$$

where  $\lambda(t; v, \theta)$  is the hazard function, the derivative of the cumulative hazard function  $\Lambda(t; v, \theta)$  with respect to  $t$ , the maximum likelihood estimator is obtained as M-estimator by setting  $\phi_i(t; v)$  equal to  $\psi_i(t; v, \theta_0)$ , where  $\psi_i(t; v, \theta)$  denotes the first order partial derivative of  $\log \lambda(t; v, \theta)$  with respect to the  $i^{\text{th}}$  component of  $v$  [see Borgan (1984)].

The study of the behavior of  $v^{(n)}$  involves the following regularity conditions on  $\psi_i(t; v, \theta)$  and  $\phi_i(t; v)$ .

**Condition 9** *There exists a constant  $c_\psi$  such that for every  $i = 1, \dots, r$  and  $v \in \Upsilon$  the function  $\psi_i(t; v, \theta_0)$  exists, is bounded by  $c_\psi$  and has total variation bounded by  $c_\psi$ . The first order partial derivatives of  $\psi_i(t; v, \theta_0)$  with respect to the components of  $v$  exist, are bounded by  $(c_\psi)^2$ , and have total variation bounded by  $(c_\psi)^2$ .*

**Condition 10** *For every  $i = 1, \dots, r$  and  $v \in \Upsilon$  the function  $\phi_i(t; v)$  is bounded by  $(c_\psi)^{-2}$  and has total variation bounded by  $(c_\psi)^{-2}$ . The first order partial derivatives of  $\phi_i(t; v)$  with respect to the components of  $v$  exist, are bounded by  $(c_\psi)^{-1}$ , and have total variation bounded by  $(c_\psi)^{-1}$ . The second order partial derivatives of  $\phi_i(t; v)$  with respect to the components of  $v$  exist, are bounded by 1, and have total variation bounded by 1.*

Condition 10 is less restrictive than it might seem at first glance, since it is clear from (4.3) that multiplying  $\phi_i(t; v)$  by a nonzero constant has no effect on the estimator itself. Observe that the constant may even depend on  $v$ .

However, Condition 10 does involve restrictions on the behavior of the second order partial derivatives, which may prevent the maximum likelihood estimator from falling into the framework considered here. If this is the case, one may weigh replacing the maximum likelihood estimator by a closely related M-estimator, obtained by setting  $\phi_i(t; v)$  equal to a smoothed version of  $\psi_i(t; v, \theta_0)$ .

Before formulating two additional conditions, we first introduce the cumulative distribution functions

$$H^1(t; v_n, \theta_n) = P_n(X_1 \leq t, \delta_1 = 1),$$

$$H(t; v_n, \theta_n) = P_n(X_1 \leq t)$$

[note that  $H^1(t; v_n, \theta_n)$  is possibly defective]. Moreover, we define the function  $D(t; v', \theta_0, v, \theta)$  by

$$D(t; v', \theta_0, v, \theta) = \int_0^t (1 - H(s; v, \theta)) \{d\Lambda(s; v, \theta) - d\Lambda(s; v', \theta_0)\}. \quad (4.6)$$

**Condition 11** *There exists a function  $\pi : \Upsilon \times \Theta \rightarrow \Upsilon$  such that*

$$\int_0^\infty \phi_i(s; \pi(v, \theta)) dD(s; \pi(v, \theta), \theta_0, v, \theta) = 0$$

for  $i = 1, \dots, r$ ,  $v \in \Upsilon$  and  $\theta \in \Theta$ .

The function  $D(t; \pi(v, \theta), \theta_0, v, \theta)$  appears frequently in our results. To increase readability we shall abbreviate it by  $D(t; v, \theta)$ . It reflects the distance between the distribution  $F(t; v, \theta)$  and the set of distributions under the null hypothesis.

It is possible to choose  $\pi$  so as to satisfy  $\pi(v, \theta_0) = v$  for any  $v \in \Upsilon$ . We shall tacitly assume this is indeed the case. Hence, we may view  $(\pi(v, \theta), \theta_0)$  as a projection of the point  $(v, \theta)$  on  $\Upsilon \times \{\theta_0\}$ . Moreover, it immediately follows that  $D(t; v, \theta_0)$  equals zero for any  $t \in [0, \infty)$  and  $v \in \Upsilon$ .

Let  $\Xi_0(v, \theta)$  be the  $r \times r$  matrix with elements

$$\begin{aligned} \Xi_{0ij}(v, \theta) &= \int_0^\infty \phi_i(s; \pi(v, \theta)) \psi_j(s; \pi(v, \theta), \theta_0) dH^1(s; v, \theta) \\ &\quad - \int_0^\infty \{\phi_i(s; \pi(v, \theta)) \psi_j(s; \pi(v, \theta), \theta_0) \\ &\quad + \phi_{ij}^{(1)}(s; \pi(v, \theta), \theta_0)\} dD(s; v, \theta), \end{aligned}$$

where  $\phi_{ij}^{(1)}(t; v)$  denotes the first order partial derivative of  $\phi_i(t; v)$  with respect to the  $j^{\text{th}}$  component of  $v$ . We shall assume that  $\Xi_0$  satisfies Condition 12. Refer to the matrix  $AA^T$  as the square of the matrix  $A$ .

**Condition 12** *There exist a constant  $c_{35}$  such that the eigenvalues of the square of the matrix  $\Xi_0(v, \theta)$  all exceed  $(c_{35})^2$  for every  $v \in \Upsilon$  and  $\theta \in \Theta$ .*

The complexity of the last two conditions may seem discouraging. However, if we are only interested in what happens under the null hypothesis then we may set  $\Theta = \{\theta_0\}$  and the situation clarifies considerably. Now Condition 11 holds automatically as follows from setting  $\pi(v, \theta) = v$ . Moreover, Condition 12 only involves  $\Xi_0(v, \theta_0)$ . Observe that

$$\Xi_{0ij}(v, \theta_0) = \int_0^\infty \phi_i(s; v) \psi_j(s; v, \theta_0) dH^1(s; v, \theta_0).$$

Hence,  $\Xi_0(v, \theta_0)$  is of a much simpler nature than  $\Xi_0(v, \theta)$ .

To verify Condition 12 in the general case a two stage procedure could be successful. First show that the eigenvalues of the square of  $\Xi_0(v, \theta_0)$  are bounded from below, uniformly in  $v$ . Then try to show that the eigenvalues of the square of  $\Xi_0(v, \theta) - \Xi_0(\pi(v, \theta), \theta_0)$  remain small enough to guarantee that Condition 12 holds. Note that the elements of  $\Xi_0(v, \theta) - \Xi_0(\pi(v, \theta), \theta_0)$  are bounded by  $4(c_\psi)^{-1} \sup_{t \in [0, \infty)} D(t; v, \theta)$ . Thus this approach can be expected to work if  $\sup_{t \in [0, \infty)} D(t; v, \theta)$  is small, which occurs in the neighborhood of  $\theta_0$ .

Denote  $\pi(v_n, \theta_n)$  by  $v_{n0}$ ,  $\Xi_0(v_n, \theta_n)$  by  $\Xi_{0n}$  and  $\Xi_0(v_0, \theta_0)$  by  $\Sigma_{e0}$ , and let  $\phi(t; v)$  be the  $r$ -dimensional vector with elements  $\phi_i(t; v)$ .

**Theorem 7** *There exist positive constants  $c_{36}$ ,  $c_{37}$  not depending on  $v_n$  or  $\theta_n$  and a random variable  $S_n$  such that if*

$$S_n < n^{1/2}, \quad (4.7)$$

*then there exists a solution  $v^{(n)}$  to the equations (4.3) which satisfies*

$$n^{1/2}|v^{(n)} - v_{n0}| < c_{36}S_n \quad (4.8)$$

$$\begin{aligned} n^{1/2}|\Xi_{0n}^{-1} \int_0^\infty \phi(s; v_{n0})\{dM_n(s; v_{n0}, \theta_0) - dD(s; v_n, \theta_n)\} \\ - n^{1/2}(v^{(n)} - v_{n0})| < c_{37}\{S_n\}^2 \end{aligned} \quad (4.9)$$

*Furthermore, for every  $\beta > \alpha$  there exist positive constants  $c_{38}$ ,  $c_{39}$  not depending on  $v_n$  or  $\theta_n$ , such that*

$$P_n(S_n > c_{38}n^\beta(\log n)^{-1/2}) < c_{39}n^{-(\beta-\alpha)/\alpha}. \quad (4.10)$$

*Moreover, if  $(v_n, \theta_n) = (v_0, \theta_0)$ , then there exist positive constants  $c_{40} - c_{42}$  not depending on  $v_0$  such that*

$$P_{v_0}(S_n > x(c_{40} \log n + x^2)) \leq c_{41} \exp\{-c_{42}x^2\} \quad (4.11)$$

*for every  $x > (n^{1/2} \log n)^{-1}$ .*

The strength of inequality (4.9) depends on the behavior of the random variable  $n^{-1/2}\{S_n\}^2$ . In the following corollary this behavior is characterized.

**Corollary 4** *If  $\alpha < 1/4$ , then*

$$n^{-1/2}\{S_n\}^2 \rightarrow_{P_n} 0. \quad (4.12)$$

*If  $(v_n, \theta_n) = (v_0, \theta_0)$ , then*

$$P_{v_0}(n^{-1/2}\{S_n\}^2 > n^{-1/2}x(c_{40} \log n + x^2)) \leq c_{41} \exp\{-c_{42}x\} \quad (4.13)$$

*for every  $x > (n^{1/2} \log n)^{-2}$ .*

Our approximation of the process  $Q_n(t; v^{(n)})$  is based on (4.9) directly. However, (4.9) may also be used to prove asymptotic normality of the estimator  $v^{(n)}$ , since by the refinement of Theorem 2 we may approximate  $\int_0^\infty \phi(s; v_{n0}) \{dM_n(s; v_{n0}, \theta_0) - dD(s; v_n, \theta_n)\}$  by the  $r$ -dimensional Gaussian random variable  $\tilde{\Phi}_n$  defined by

$$\tilde{\Phi}_n = \int_0^\infty \phi(s; v_{n0}) dW_n(s; v_{n0}), \quad (4.14)$$

where  $W_n(t; v_{n0})$  is the Gaussian process of Theorem 2. Under  $P_n$  the covariance function of  $W_n(t; v_{n0})$  is somewhat intractable, and thus there is little use in giving an expression for the asymptotic variance of  $n^{1/2}(v^{(n)} - v_{n0})$  under  $P_n$ . But again, everything becomes more transparent if  $(v_n, \theta_n)$  equals  $(v_0, \theta_0)$ . Under  $P_{v_0}$  the process  $W_n(t; v_0)$  is a Wiener process with variance function  $H^1(t; v_0, \theta_0)$ , and hence the covariancematrix of  $\tilde{\Phi}_n$  is equal to  $\Sigma_{ee}$ , the  $r \times r$  matrix with elements

$$\Sigma_{eeij} = \int_0^\infty \phi_i(s; v_0) \phi_j(s; v_0) dH^1(s; v_0, \theta_0) \quad (4.15)$$

Hence, we arrive at the following corollary.

**Corollary 5** *If  $(v_n, \theta_n) = (v_0, \theta_0)$ , then there exists a sequence  $\{\tilde{\Phi}_n\}_{n=1}^\infty$  of  $r$ -dimensional Gaussian random vectors with zero expectation and covariance matrix  $\Sigma_{ee}$  such that*

$$|n^{1/2}(v^{(n)} - v_0) - \Sigma_{e0}^{-1} \tilde{\Phi}_n| = \mathcal{O}_{P_{v_0}}(n^{-1/2}(\log n)^2) \quad \text{as } n \rightarrow \infty.$$

The convergence in  $P_{v_0}$ -distribution of the sequence  $\{n^{1/2}(v^{(n)} - v_0)\}_{n=1}^\infty$  to a Gaussian random variate with zero expectation and covariance matrix  $\Sigma_{e0}^{-1} \Sigma_{ee} \Sigma_{0e}^{-1}$ , where  $\Sigma_{0e}$  denotes the transpose of  $\Sigma_{e0}$ , was proved for the maximum likelihood estimator by Borgan (1984) using martingale methods. Observe that in this case  $\Sigma_{e0}^{-1} \Sigma_{ee} \Sigma_{0e}^{-1}$  is equal to  $\Sigma_{ee}^{-1}$ . Hjort (1985) mentions that the approach of Borgan can be extended to M-estimators without difficulty. However, the results obtained in this way do not stretch as far as Corollary 4, which also conveys information about the rate of convergence.

#### 4.2.2 The process $Q_n(t; v^{(n)})$

Now that we have gained some knowledge about the M-estimator  $v^{(n)}$ , it is time to direct our attention to the process  $Q_n(t; v^{(n)})$ . But first we make some assumptions about the weight process  $L_n(t; v)$ .

**Condition 13** *The weight process  $L_n(t; v)$  satisfies*

- a**  $L_n(\cdot; v)$  is a random element in [the left continuous right limits version of]  $D[0, \infty]$  endowed with the  $\mathcal{J}_1$  metric. There exists a constant  $c_{43}$  not depending on  $v$ ,  $v_n$  or  $\theta_n$  such that  $L_n(t; v)$  is bounded by  $c_{43}$  and has total variation bounded by  $c_{43}$  with  $P_n$ -probability 1.



- b** There exists a deterministic function  $L(t; v, \theta)$  such that for every  $\beta < 1/2$  there exist positive constants  $c_{44}$ – $c_{46}$  not depending on  $v_n$  or  $\theta_n$  such that

$$P_n \left( \sup_{t \in [0, \infty)} |L_n(t; v_{n0}) - L(t; v_n, \theta_n)| > c_{44} n^{-\beta} \right) < c_{45} n^{-c_{46}}.$$

In addition, there exist positive constants  $c_{47}$ – $c_{49}$  not depending on  $v_0$ , such that for every  $x > 0$

$$\begin{aligned} P_{v_0} \left( \sup_{t \in [0, \infty)} |L_n(t; v_0) - L(t; v_0, \theta_0)| > n^{-1/2} (c_{47} \log n + x) \right) \\ < c_{48} \exp\{-c_{49} x\}. \end{aligned}$$

- c** The first order partial derivatives of  $L_n(t; v)$  with respect to the components of  $v$  are random elements of  $D[0, \infty)$ . With  $P_n$ -probability 1 they are bounded by  $c_{43}$ , and have total variation bounded by  $c_{43}$ .
- d** For every  $i = 1, \dots, r$  there exists a deterministic function  $L_i^{[1]}(t; v, \theta)$  such that for every  $\beta < 1/2$  there exist positive constants  $c_{44}$ – $c_{46}$  not depending on  $v_n$  or  $\theta_n$  such that

$$P_n \left( \sup_{t \in [0, \infty)} |L_{ni}^{(1)}(t; v_{n0}) - L_i^{[1]}(t; v_n, \theta_n)| > c_{44} n^{-\beta} \right) < c_{45} n^{-c_{46}},$$

where  $L_{ni}^{(1)}(t; v)$  is the first order partial derivative of  $L_n(t; v)$  with respect to the  $i^{\text{th}}$  component of  $v$ .

- e** With  $P_n$ -probability 1 the second order partial derivatives of  $L_n(t; v)$  with respect to the components of  $v$  are random elements of  $D[0, \infty)$ . They are bounded by  $c_{43}$ , and have total variation bounded by  $c_{43}$ .

Condition 13 asks of various random elements of  $D[0, \infty)$  that they are uniformly bounded and have uniformly bounded total variation with  $P_n$ -probability 1. However, if needed we may replace “ $P_n$ -probability 1” by “ $P_n$ -probability tending to 1 at a fast enough rate”. The rate at which  $P_n(S_n < cn^{1/2})$  tends to 1 is for any  $c > 0$  fast enough. In section 5.3 the relaxed version of Condition 13 is used.

To describe the effect of the M-estimator  $v^{(n)}$  on the process  $Q_n(t; v^{(n)})$ , we introduce the  $r$ -dimensional vector function  $K_0(t; v, \theta)$ . The  $i^{\text{th}}$  element of  $K_0(t; v, \theta)$  is defined by

$$\begin{aligned} K_{0i}(t; v, \theta) = & \int_0^t L(s; v, \theta) \psi_i(s; \pi(v, \theta), \theta_0) dH^1(s; v, \theta) \\ & + \int_0^t \{L(s; v, \theta) \psi_i(s; \pi(v, \theta), \theta_0) + L_i^{[1]}(s; v, \theta)\} dD(s; v, \theta). \end{aligned} \quad (4.16)$$

Observe that  $K_{0i}(t; v, \theta)$  remains bounded, uniformly in  $v$  and  $\theta$ . Moreover, we have under  $P_{v_0}$

$$K_0(t; v_0, \theta_0) = \int_0^t L(s; v_0, \theta_0) \psi(s; v_0, \theta_0) dH^1(s; v_0, \theta_0), \quad (4.17)$$

where  $\psi(t; v, \theta)$  is the  $r$ -dimensional vector with components  $\psi_i(t; v, \theta)$ .

**Theorem 8** *There exists a sequence  $\{W_n(t; v_{n0})\}_{n=1}^\infty$  of mean zero Gaussian processes with covariance function*

$$\begin{aligned} \mathcal{E}_n W_n(t_1; v_{n0}) W_n(t_2; v_{n0}) &= H^1(t_1 \wedge t_2; v_n, \theta_n) \\ &\quad - \int_0^{t_1 \wedge t_2} \{D(t_1; v_n, \theta_n) + D(t_2; v_n, \theta_n) \\ &\quad \quad - 2D(s; v_n, \theta_n)\} d\Lambda(s; v_{n0}, \theta_0) \\ &\quad - D(t_1; v_n, \theta_n) D(t_2; v_n, \theta_n) \end{aligned} \quad (4.18)$$

such that for every  $\beta < (1/2 - 2\alpha) \wedge 1/6$  we have

$$\begin{aligned} P_n \left( \sup_{t \in [0, \infty)} \left| \{Q_n(t; v^{(n)}) - n^{1/2} \int_0^t L_n(s; v_{n0}) dD(s; v_n, \theta_n)\} \right. \right. \\ \left. \left. - \left\{ \int_0^t L(s; v_n, \theta_n) dW_n(s; v_{n0}) \right. \right. \right. \\ \left. \left. \left. - (K_0(t; v_n, \theta_n))^T \Xi_{0n}^{-1} \int_0^\infty \phi(s; v_{n0}) dW_n(s; v_{n0}) \right\} \right| \\ > c_{50} n^{-\beta} \right) \leq c_{51} n^{-c_{52}}, \end{aligned} \quad (4.19)$$

where  $c_{50} - c_{52}$  are positive constants not depending on  $v_n$  or  $\theta_n$ .

If in addition  $(v_n, \theta_n) = (v_0, \theta_0)$  then there exist positive constants  $c_{53} - c_{55}$ , not depending on  $(v_0, \theta_0)$ , such that

$$\begin{aligned} P_{v_0} \left( \sup_{t \in [0, \infty)} \left| Q_n(t; v^{(n)}) - \left\{ \int_0^t L(s; v_0, \theta_0) dW_n(s; v_0) \right. \right. \right. \\ \left. \left. \left. - (K_0(t; v_0, \theta_0))^T \Sigma_{e0}^{-1} \int_0^\infty \phi(s; v_0) dW_n(s; v_0) \right\} \right| \\ > n^{-1/6} (1+x) (c_{53} \log n + x)^2 \right) \leq c_{54} \exp\{-c_{55}x\}. \end{aligned} \quad (4.20)$$

Corollary 6 is based on the observation that the Gaussian process which is used in Theorem 8 to approximate  $Q_n(t; v^{(n)})$  under  $P_{v_0}$  may be written as  $\int_0^\infty L_0(s, t; v_0) dW_n(s; \theta_0)$ , where the function  $L_0(s, t; v_0)$  is defined by

$$L_0(s, t; v_0) = L(s; v_0, \theta_0) 1_{\{s \leq t\}} - (K_0(t; v_0, \theta_0))^T \Sigma_{e0}^{-1} \phi(s; v_0). \quad (4.21)$$

It seems that  $L_0(s, t; v_0)$  is an adapted version of  $L(s; v_0, \theta_0)$ , in which the influence of the M-estimator at the stochastic integral evaluated at point  $t$  is accounted for.

**Corollary 6** *The sequence  $\{Q_n(t; v^{(n)})\}_{n=1}^\infty$  converges in  $P_{v_0}$ -distribution to a mean zero Gaussian process  $\check{X}(t; v_0, \theta_0)$  with covariance function*

$$\begin{aligned} \mathcal{E}_{v_0} \check{X}(t_1; v_0, \theta_0) \check{X}(t_2; v_0, \theta_0) \\ = \int_0^\infty L_0(s, t_1; v_0) L_0(s, t_2; v_0) dH^1(s; v_0, \theta_0). \end{aligned} \quad (4.22)$$

Corollary 6 implies that the variance function of  $\check{X}(t; v_0, \theta_0)$  may be written as

$$\mathcal{E}_{v_0} \{\check{X}(t; v_0, \theta_0)\}^2 = \int_0^\infty (L_0(s, t; v_0))^2 dH^1(s; v_0, \theta_0). \quad (4.23)$$

Since we have

$$\int_0^\infty \int_0^\infty (L_0(s, t; v_0))^2 dH^1(s; v_0, \theta_0) dH^1(t; v_0, \theta_0) < \infty, \quad (4.24)$$

we may view the operator which assigns  $\int_0^\infty L_0(s, t; v_0) f(s) dH^1(s; v_0, \theta_0)$  to any  $f \in D[0, \infty)$  such that  $\int_0^\infty (f(s))^2 dH^1(s; v_0, \theta_0) < \infty$  as a Hilbert-Schmidt operator. This operator is used to transform  $W_n(t; v_0)$  into a Gaussian process which under  $P_{v_0}$  closely approximates  $Q_n(t; v^{(n)})$ . The relatively complicated form of the covariance function of  $Q_n(t; v^{(n)})$  gives rise to the interesting question whether there exists another operator which can be used to transform  $Q_n(t; v^{(n)})$  into a process closely approximated by  $W_n(t; v_0)$  under  $P_{v_0}$ . It is possible to solve this inverse problem by following the path set out by Khamaladze (1981, 1982) in his study of the empirical process with estimated parameters.

However, the derivation of probability inequalities of the type given in Theorems 2 and 8 for the transformed process would require additional notation and, above all, quite unpleasant conditions. Therefore, we do not pursue this point any further.

The second part of Condition 13b is only needed for verifying (4.20). Thus, (4.20) and Corollary 6 remain valid if the second part of Condition 13b is dropped.

The proof of Theorem 8 makes us of Theorem 1. Just like this theorem, Theorem 8 can be sharpened in the case where  $L_n(t; v_{n0})$  coincides with  $L(t; v_n, \theta_n)$  with  $P_n$ -probability 1. Then, (4.19) holds for every  $\beta < (1/2 - 2\alpha)$ , and in (4.20) the term  $n^{-1/6}$  may be replaced by  $n^{-1/2}$ .

Convergence in distribution of a sequence of processes strongly related to  $\{Q_n(t; v^{(n)})\}_{n=1}^\infty$  was obtained by Hjort (1984) [see also Hjort (1990)].

### 4.3 Sublinear tests

As in the previous chapter we may use a functional  $T$  mapping  $D[0, \infty)$  into  $\mathbb{R}$  to construct a goodness-of-fit test. Applying  $T$  to the process  $Q_n(t; v^{(n)})$ , we obtain a statistic which can be used to test the composite null hypothesis  $\theta_n = \theta_0$ .

In this section we study deviations, behavior under fixed and local alternatives, and efficiencies of sublinear tests, based on test statistics  $T(Q_n(t; v^{(n)}))$ , where  $T$  satisfies Condition 14.

**Condition 14** *The functional  $T$  is sublinear and Lipschitz.*

Observe that this condition is exactly the same as Condition 3. Thus, the remarks concerning Condition 3 also apply here.

#### 4.3.1 Deviations

Define

$$\check{a}(v_0) = \left\{ \sup_{f \in \mathcal{S}} T \left( \int_0^\infty L_0(s, \cdot; v_0) f'(H^1(s; v_0, \theta_0)) dH^1(s; v_0, \theta_0) \right) \right\}^{-2} \quad (4.25)$$

where  $\mathcal{S}$  is the set of Strassen functions. One may interpret  $(\check{a}(v_0))^{-1/2}$  as the norm of the functional  $T$ , this time induced by the reproducing kernel Hilbert space of the Gaussian process  $\check{X}(t; v_0, \theta_0)$ , the limit in  $P_{v_0}$ -distribution of the sequence  $\{Q_n(t; v^{(n)})\}_{n=1}^\infty$ . Suppose that

**Condition 15**  $\inf_{v_0 \in \Gamma} \check{a}(v_0)$  is positive.

Theorem 9 describes the tail behavior of  $T(\check{X}(\cdot; v_0, \theta_0))$  [and thus the tail behavior of the asymptotic distribution of  $T(Q_n(\cdot; v^{(n)}))$ ], and presents a deviation result for  $T(Q_n(\cdot; v^{(n)}))$ . It is valid whenever equation (4.20) and Conditions 14 and 15 hold.

**Theorem 9** *We have*

$$\lim_{t \rightarrow \infty} t^{-2} \inf_{v_0 \in \Gamma} (\check{a}(v_0))^{-1} \log P_{v_0}(T(\check{X}(\cdot; v_0, \theta_0)) > t) = -1/2. \quad (4.26)$$

$$\lim_{t \rightarrow \infty} t^{-2} \sup_{v_0 \in \Gamma} (\check{a}(v_0))^{-1} \log P_{v_0}(T(\check{X}(\cdot; v_0, \theta_0)) > t) = -1/2. \quad (4.27)$$

Furthermore,

$$\lim_{s_n \rightarrow \infty} (s_n)^{-2} \inf_{v_0 \in \Gamma} (\check{a}(v_0))^{-1} \log P_{v_0}(T(Q_n(\cdot; v^{(n)})) > s_n) = -1/2 \quad (4.28)$$

$$\lim_{s_n \rightarrow \infty} (s_n)^{-2} \sup_{v_0 \in \Gamma} (\check{a}(v_0))^{-1} \log P_{v_0}(T(Q_n(\cdot; v^{(n)})) > s_n) = -1/2 \quad (4.29)$$

for any sequence  $\{s_n\}_{n=1}^\infty$  such that  $s_n \rightarrow \infty$  and  $s_n = o(n^{1/30})$  as  $n \rightarrow \infty$ .

Obviously, (4.28) and (4.29) also hold for any sequence  $\{s_n\}_{n=1}^{\infty}$  such that  $s_n \rightarrow \infty$  and  $s_n = \mathcal{O}((\log n)^{1/2})$ . The deviation result based on the latter type of sequence is called moderate and is important from a statistical perspective, since it plays a role in evaluating the performance of a test.

As with Theorem 8, Theorem 9 can be refined in the special case where  $L_n(t; v_0)$  coincides with  $L(t; v_0, \theta_0)$  with  $P_{v_0}$ -probability 1. Now sequences  $\{s_n\}_{n=1}^{\infty}$  such that  $s_n \rightarrow \infty$  and  $s_n = o(n^{1/10})$  are allowed.

From a practical viewpoint it is desirable that a test for the composite null hypothesis is based on a test statistic which has under the null hypothesis an asymptotic distribution which does not depend on the actual value of the unknown parameter. Hence, the rate at which the tail of the distribution of the test statistic decays should not depend on the unknown parameter. Theorem 9 implies that in order for this latter situation to occur it is sometimes needed to multiply the original weight process by the square root of  $\check{a}(v)$ . Of course, it should be verified whether the newly constructed weight process meets all requirements.

Since in general the distribution function  $H^1(t; v_0, \theta_0)$  is involved in  $\check{a}(v)$ , a slight problem arises when the censoring distribution  $G$  is unknown. In this case it seems best to divide the weight process by the square root of an estimator for  $\check{a}(v)$ . Typically, estimators for  $\check{a}(v)$  are obtained by replacing  $H^1(t; v_0, \theta_0)$  by  $\int_0^t (1 - H_{n-}(s)) d\Lambda(s; v_0, \theta_0)$ .

### 4.3.2 Behavior under the alternative hypothesis

To describe the behavior of  $T(Q_n(\cdot; v^{(n)}))$  under a fixed alternative, suppose that  $v_n = v \in \Upsilon$  and  $\theta_n = \theta \in \Theta$  for every  $n \in \mathbb{N}$  [we shall refer to this situation as “under  $P_{(v, \theta)}$ ”]. Then for every  $\beta > (2\alpha - 1/2)^+$

$$n^{-\beta} |T(Q_n(\cdot; v^{(n)})) - n^{1/2} T(\int_0^\cdot L(s; v, \theta) dD(s; v, \theta))| \rightarrow_{P_{(v, \theta)}} 0. \quad (4.30)$$

as follows from combining (4.19) with Conditions 13 and 14.

The treatment of local alternatives requires a more substantial effort. First we impose structure on  $\Theta$ .

**Condition 16**  $\Theta$  is a convex subset of  $\mathbb{R}^p$ .

As an immediate consequence of Condition 16 we have that  $\Upsilon \times \Theta$  is a subset of  $\mathbb{R}^{r+p}$ . Hence, it is sensible to redefine  $\psi_i(t; v, \theta)$  as the first order partial derivative of  $\log \lambda(t; v, \theta)$  with respect to the  $i^{\text{th}}$  component of  $(v, \theta)$ ,  $i = 1, \dots, r + p$ . Note that this redefinition is consistent with the earlier definition. Likewise, redefine  $\psi_{ij}^{(1)}(t; v, \theta)$  as the second order partial derivative with respect to the  $i^{\text{th}}$  and  $j^{\text{th}}$  component of  $(v, \theta)$ .

**Condition 17** For every  $v \in \Upsilon$ ,  $\theta \in \Theta$  and  $i, j = 1, \dots, r + p$  the functions  $\lambda(t; v, \theta)$ ,  $\psi_i(t; v, \theta)$  and  $\psi_{ij}^{(1)}(t; v, \theta)$  exist. For some  $\beta > 0$  there exists a constant  $c_{56}$  such that for every  $v \in \Upsilon$ ,  $\theta \in \Theta$  and  $i, j = 1, \dots, r + p$

$$\int_0^\infty (\psi_i(s; v, \theta))^2 (1 - H(s; v, \theta))^{(1-2\alpha)-\beta} d\Lambda(s; v, \theta) < c_{56},$$

$$\int_0^\infty (\psi_{ij}^{(1)}(s; v, \theta))^2 (1 - H(s; v, \theta))^{2(1-2\alpha)-\beta} d\Lambda(s; v, \theta) < c_{56}.$$

Denote the  $p$ -dimensional vector with components  $\psi_{r+i}(t; v_0, \theta_0)$  by  $\psi_a(t; v_0, \theta_0)$ , and define

$$K_{a|0}(t; v_0) = \int_0^\infty L_0(s, t; v_0) \psi_a(s; v_0, \theta_0) dH^1(s; v_0, \theta_0) \quad (4.31)$$

[compare with (4.21)]. Observe that under Conditions 8 and 9 the components of  $K_{a|0}(t; v_0)$  remain uniformly bounded in  $t$ ,  $v_0$  and  $\theta_0$ .

Let  $\Lambda_i^{(1)}(t; v, \theta)$  denote the first order partial derivative of  $\Lambda(t; v, \theta)$  with respect to the  $i^{\text{th}}$  component of  $(v, \theta)$ . Define the  $r \times r$  matrix  $\Xi_b(v, \theta)$  by

$$\begin{aligned} \Xi_{bij}(v, \theta) &= \int_0^\infty \phi_i(s; \pi(v, \theta)) \psi_j(s; \pi(v, \theta), \theta_0) dH^1(s; v, \theta) \\ &+ \int_0^\infty \psi_i(s; \pi(v, \theta)) \Lambda_j^{(1)}(s; \pi(v, \theta), \theta_0) dD(s; v, \theta), \end{aligned} \quad (4.32)$$

**Condition 18** All eigenvalues of the square of the matrix  $\Xi_b(v, \theta)$  exceed  $(c_{35})^2$  for every  $v \in \Upsilon$  and  $\theta \in \Theta$ .

It should be noted that  $\Xi_b(v, \theta_0) = \Xi_0(v, \theta_0)$  for every  $v \in \Upsilon$ . Since the smallest eigenvalue of the square of  $\Xi_b(v, \theta)$  tends to the smallest eigenvalue of the square of  $\Xi_b(v, \theta_0)$  as  $\theta$  tends to  $\theta_0$ , the remarks on the verifiability of Condition 12 also apply to Condition 18.

The next condition concerns  $L_i^{(1)}(t; v, \theta)$ , the first order partial derivative of  $L(t; v, \theta)$  with respect to the  $i^{\text{th}}$  component of  $(v, \theta)$ , and  $L_{ij}^{(2)}(t; v, \theta)$ , the second order partial derivative of  $L(t; v, \theta)$  with respect to the  $i^{\text{th}}$  and  $j^{\text{th}}$  components of  $(v, \theta)$ .

**Condition 19** For every  $v \in \Upsilon$ ,  $\theta \in \Theta$  and  $i, j = 1, \dots, r + p$  the functions  $L_i^{(1)}(t; v, \theta)$  and  $L_{ij}^{(2)}(t; v, \theta)$  exist. There exists a constant  $c_{57}$  such that for every  $v \in \Upsilon$ ,  $\theta \in \Theta$  and  $i, j = 1, \dots, r + p$

$$\sup_{t \in [0, \infty)} (1 - H(t; v, \theta))^{1/2} |L_i^{(1)}(t; v, \theta)| < c_{57},$$

$$\sup_{t \in [0, \infty)} (1 - H(t; v, \theta))^{1-\alpha} |L_{ij}^{(2)}(t; v, \theta)| < c_{57}.$$

**Theorem 10** Suppose the sequence  $\{(v_n, \theta_n)\}_{n=1}^\infty$  converges to the point  $(v_0, \theta_0)$ . Let  $h$  be the  $p$ -dimensional unit vector defined by  $h = \lim_{n \rightarrow \infty} (\theta_n - \theta_0)/|\theta_n - \theta_0|$ , and let  $\sigma$  denote  $\lim_{n \rightarrow \infty} n^{1/2}|\theta_n - \theta_0|$ .

- a If  $\sigma = \infty$  then  $(n^{1/2}|\theta_n - \theta_0|)^{-1}T(Q_n(\cdot; v^{(n)}))$  converges in  $P_n$ -probability to  $T(h^T K_{a|0}(\cdot; v_0))$ .
- b If  $\alpha < 1/4$  and  $\sigma < \infty$  then  $\{T(Q_n(\cdot; v^{(n)}))\}_{n=1}^\infty$  converges in  $P_n$ -distribution to  $T(\tilde{X}(\cdot; v_0, \theta_0) + \sigma h^T K_{a|0}(\cdot; v_0))$ .

The proof of Theorem 10b makes use of the fact that (4.19) holds for some  $\beta > 0$ , which provides the reason for the occurrence of the restriction  $\alpha < 1/4$ .

If  $\alpha < 1/4$  then Theorem 10 reveals three types of behavior of the sequence of test statistics  $\{T(Q_n(\cdot; v^{(n)}))\}_{n=1}^\infty$ , depending on the rate at which the alternatives converge to the null hypothesis. If the rate is faster than  $n^{-1/2}$  then we have convergence in distribution to the same limit as under the null hypothesis. If the rate is of the order  $n^{-1/2}$  then we also have convergence in distribution, but to a limit different from the one under the null hypothesis. If the rate is slower than  $n^{-1/2}$  then the convergence in distribution is lost, since the sequence of test statistics blows up as  $n$  tends to infinity.

### 4.3.3 Efficiencies

In the previous chapter a number of efficiency concepts were introduced. However, the definitions given there only apply to the simple null hypothesis. We shall now carry these definitions over to the composite null hypothesis, and reflect on their implications.

Our definition of asymptotic relative Pitman efficiency is restricted to the situation in which we have two infinite sequences of tests of the same size, and where the  $n^{\text{th}}$  test in the  $i^{\text{th}}$  sequence is based on the test statistic  $T_{in}$ , rejects the null hypothesis if  $T_{in} > t_{in}$ , and does not reject if  $T_{in} < t_{in}$ . Again, we have no knowledge about the action taken if  $T_{in} = t_{in}$ .

**Definition 7** For a given function  $\tilde{\beta} : \Upsilon \times \Theta \rightarrow [0, 1]$ , let  $\bar{N}_i^{\tilde{\beta}}(v, \theta)$  be the largest sample size such that  $P_{(v, \theta)}(T_{in} \geq t_{in}) < \tilde{\beta}(v, \theta)$ . If for a unit vector  $h \in \mathbb{R}^p$  and every  $v_0 \in \Upsilon$  there exists a constant  $e_{12}^{\tilde{\beta}}(h; v_0)$  such that

$$\liminf_{j \rightarrow \infty} \frac{\bar{N}_2^{\tilde{\beta}}(v_j, \theta_j)}{\bar{N}_1^{\tilde{\beta}}(v_j, \theta_j)} \geq e_{12}^{\tilde{\beta}}(h; v_0)$$

and

$$\limsup_{j \rightarrow \infty} \frac{\bar{N}_2^{\tilde{\beta}}(v_j, \theta_j)}{\bar{N}_1^{\tilde{\beta}}(v_j, \theta_j)} \leq e_{12}^{\tilde{\beta}}(h; v_0)$$

for any sequence  $\{(v_j, \theta_j)\}_{j=1}^{\infty}$  tending to  $(v_0, \theta_0)$  while satisfying  $\lim_{j \rightarrow \infty} \tilde{\beta}(v_j, \theta_j) \in (0, 1)$  and  $\lim_{j \rightarrow \infty} (\theta_j - \theta_0)/|\theta_j - \theta_0| = h$ , then  $e_{12}^{\tilde{\beta}}(h; v_0)$  is the asymptotic relative Pitman efficiency of the first sequence of tests with respect to the second.

This definition allows the asymptotic relative Pitman efficiency to depend on both size and power of the tests. It does not involve  $N_i^{\tilde{\beta}}(v, \theta)$ , the smallest sample size such that  $P_{(v, \theta)}(T_{in} > t_{in}) \geq \tilde{\beta}(v, \theta)$ , as is propagated by Rothe (1981). An efficacy approach is possible if there is a transformation of the test statistics available such that the transformed test statistics are asymptotically normal and have asymptotic variance 1 for any sequence  $\{\theta_n\}_{n=1}^{\infty}$  such that  $\lim_{n \rightarrow \infty} n^{1/2}|\theta_n - \theta_0| < \infty$ . The asymptotic mean of the transformed test statistics divided by  $\lim_{n \rightarrow \infty} n^{1/2}|\theta_n - \theta_0|$  is the square root of what is called the efficacy of the sequence of test statistics. For two such sequences the asymptotic relative Pitman efficiency is equal to the ratio of their respective efficacies. In absence of such a transformation, the computation of asymptotic relative Pitman efficiency becomes too formidable for general sublinear tests.

**Definition 8** A sequence of test statistics  $\{T_{in}\}_{n=1}^{\infty}$  is said to be a standard sequence if the following three conditions are satisfied.

- a The sequence  $\{T_{in}\}_{n=1}^{\infty}$  converges in  $P_{v_0}$ -distribution to a random variable  $T_i$ .
- b There exists a constant  $a_i$  such that

$$\lim_{t \rightarrow \infty} t^{-2} \inf_{v_0 \in \Upsilon} \log P_{v_0}(T_i > t) = -a_i/2.$$

$$\lim_{t \rightarrow \infty} t^{-2} \sup_{v_0 \in \Upsilon} \log P_{v_0}(T_i > t) = -a_i/2.$$

- c There exists a positive function  $b_i(v, \theta)$  such that  $|n^{-1/2}T_{in} - b_i(v, \theta)|$  converges to zero in  $P_{(v, \theta)}$ -probability for every  $v \in \Upsilon$  and  $\theta \in \Theta - \{\theta_0\}$ .

The approximate Bahadur slope of a standard sequence  $\{T_{in}\}_{n=1}^{\infty}$  is defined as  $a_i(b_i(v, \theta))^2$ . The approximate Bahadur efficiency of a standard sequence  $\{T_{1n}\}_{n=1}^{\infty}$  with respect to another standard sequence  $\{T_{2n}\}_{n=1}^{\infty}$  is defined as the ratio of their respective Bahadur slopes  $a_1(b_1(v, \theta))^2/a_2(b_2(v, \theta))^2$ .

By Corollary 6 and equations (4.26), (4.27) and (4.30) it immediately follows that the approximate Bahadur slope of  $\{T(Q_n(\cdot; v^{(n)}))\}_{n=1}^{\infty}$  is given by  $\tilde{a}(v_0)\{T(\int_0 L(s; v, \theta)dD(s; v, \theta))\}^2$ .

**Definition 9** A standard sequence  $\{T_{in}\}_{n=1}^{\infty}$  is said to be a Wieand sequence if there is a constant  $\epsilon^* > 0$  such that for every  $\epsilon > 0$  and  $\delta \in (0, 1)$  there exists an integer  $N$  such that

$$P_{(v, \theta)}(|n^{-1/2}T_{in} - b_i(v, \theta)| > \epsilon b_i(v, \theta)) < \delta$$

for every  $v \in \Upsilon$ ,  $\theta \in \Theta - \{\theta_0\}$  satisfying  $|\theta - \theta_0| < \epsilon^*$  and  $n > N/(b_i(v, \theta))^2$ .



Since our definition of standard sequences slightly extends the one used in Wieand (1976) [it allows  $P_{v_0}(T_i > t)$  to depend on  $v_0$ ], an adaption of Wieand's result is in order.

**Theorem 11 (Wieand (1976), adapted)** *Let  $\{T_{1n}\}_{n=1}^{\infty}$  and  $\{T_{2n}\}_{n=1}^{\infty}$  be two Wieand sequences. Suppose  $\lim_{(v,\theta) \rightarrow (v_0,\theta_0)} b_i(v,\theta) = 0$  for  $i = 1, 2$  and suppose that for every  $p$ -dimensional unit vector  $h$  the limit*

$$\lim_{\theta \rightarrow \theta_0} \{a_1(b_1(v,\theta))^2\} / \{a_2(b_2(v,\theta))^2\} \quad (4.33)$$

*exists if  $(\theta - \theta_0)/|\theta - \theta_0|$  tends to  $h$ . Then the limiting (as the size of the tests approaches zero) asymptotic relative Pitman efficiency exists and is equal to the limit given in (4.33).*

Theorem 11 is not valid if variants of asymptotic relative Pitman efficiency such as in Rothe (1981) are used. See Appendix A for more details.

**Theorem 12** *Let  $h$  be a  $p$ -dimensional unit vector, let  $(v, \theta)$  approach  $(v_0, \theta_0)$  from the direction  $h$  [that is,  $h = \lim_{(v,\theta) \rightarrow (v_0,\theta_0)} (\theta - \theta_0)/|\theta - \theta_0|$ ], and define  $e(h; v_0)$  by*

$$e(h; v_0) = \ddot{a}(v_0) \{T(h^T K_{a|0}(\cdot; v_0))\}^2 \quad (4.34)$$

*If  $\inf_{v_0 \in \Upsilon} e(h; v_0)$  is not equal to zero, then  $\{T(Q_n(\cdot; v^{(n)}))\}_{n=1}^{\infty}$  is a Wieand sequence with approximate Bahadur slope of the form*

$$|\theta - \theta_0|^2 \{e(h; v_0) + o(1)\}. \quad (4.35)$$

**Definition 10** *A sequence of test statistics  $\{T_{in}\}_{n=1}^{\infty}$  is said to be a Kallenberg sequence if the following conditions are satisfied.*

**a** *There exists a constant  $a_i$  such that*

$$\lim_{n \rightarrow \infty} (s_n)^{-2} \inf_{v_0 \in \Upsilon} \log P_{v_0}(T_{in} > s_n) = -a_i/2$$

$$\lim_{n \rightarrow \infty} (s_n)^{-2} \sup_{v_0 \in \Upsilon} \log P_{v_0}(T_{in} > s_n) = -a_i/2$$

*for all sequences  $\{s_n\}_{n=1}^{\infty}$  such that  $s_n \rightarrow \infty$  and  $s_n = o(n^{1/6})$  as  $n \rightarrow \infty$ .*

**b** *There exists a positive function  $b_i(v, \theta)$  such that  $n^{-1/2} T_{in} / b_i(v_n, \theta_n)$  converges to 1 in  $P_n$ -probability for all sequences  $\{(v_n, \theta_n)\}_{n=1}^{\infty}$  tending to  $\Upsilon \times \{\theta_0\}$ .*

*If the sequences  $\{T_{1n}\}_{n=1}^{\infty}$  and  $\{T_{2n}\}_{n=1}^{\infty}$  both are Kallenberg and the limit  $\lim_{n \rightarrow \infty} a_1(b_1(v_n, \theta_n))^2 / a_2(b_2(v_n, \theta_n))^2$  exists, then the asymptotic intermediate efficiency of  $\{T_{1n}\}_{n=1}^{\infty}$  with respect to  $\{T_{2n}\}_{n=1}^{\infty}$  is defined as this limit.*

The typical behavior of  $b_i(v, \theta)$  near  $\Upsilon \times \{\theta_0\}$  is as a linear function of  $|\theta_n - \theta_0|$ . This brings us to call  $\lim_{n \rightarrow \infty} a_i(b_i(v_n, \theta_n)/|\theta_n - \theta_0|)^2$  the intermediate slope of the Kallenberg sequence  $\{T_{in}\}_{n=1}^\infty$ .

Theorem 9 does not ensure that  $\{T(Q_n(\cdot; v^{(n)}))\}_{n=1}^\infty$  is a Kallenberg sequence. Reason for us to turn to a variant of asymptotic intermediate efficiency, weak asymptotic intermediate efficiency. Here only sequences  $\{s_n\}_{n=1}^\infty$  such that  $s_n \rightarrow \infty$  and  $s_n = \mathcal{O}((\log n)^{1/2})$  as  $n \rightarrow \infty$  are considered. Observe that the sequence  $\{T(Q_n(\cdot; v^{(n)}))\}_{n=1}^\infty$  has weak intermediate slope  $e(h; v_0)$ . Hence, the weak intermediate approach yields the same picture as the Wieand approach. Theorem 9 shows that our tests may be evaluated using a variant of asymptotic intermediate efficiency which considers sequences  $\{s_n\}_{n=1}^\infty$  such that  $s_n \rightarrow \infty$  and  $s_n = o(n^{1/30})$  as  $n$  tends to infinity.

In the beginning of this section we assumed that the functional  $T$  is sublinear. A close look reveals that Condition 14b is used only in the derivation of (4.26) and (4.27). Thus, we may set up an equivalent theory for functionals other than sublinear, provided results similar to (4.26) and (4.27) hold.

#### 4.3.4 Generalized rank and supremum type tests

We have already seen that both  $T_R$  and  $T_S$  satisfy Condition 14. Hence, our theory applies. Defining  $a_R(v_0)$  and  $a_S(v_0)$  according to (4.25), with  $T$  replaced by  $T_R$  and  $T_S$  respectively, it follows that

$$a_R(v_0) = \left\{ \int_0^\infty (L_0(s, \infty; v_0))^2 dH^1(s; v_0, \theta_0) \right\}^{-1}, \quad (4.36)$$

$$a_S(v_0) = \left\{ \sup_{t \in [0, \infty)} \int_0^\infty (L_0(s, t; v_0))^2 dH^1(s; v_0, \theta_0) \right\}^{-1} \quad (4.37)$$

[discover the relation with the variance function of  $\tilde{X}(t; v_0, \theta_0)$  by comparing with equation (4.23)]. Similarly defining  $e_R(h, v_0)$  and  $e_S(h, v_0)$  according to (4.34), we obtain

$$e_R(h, v_0) = a_R(v_0) \{h^T K_{a|0}(\infty; v_0)\}^2, \quad (4.38)$$

$$e_S(h, v_0) = a_S(v_0) \left\{ \sup_{t \in [0, \infty)} h^T K_{a|0}(t; v_0) \right\}^2. \quad (4.39)$$

As opposed to general sublinear tests, generalized rank tests do allow us to compute asymptotic Pitman efficiencies. By Corollary 6 and Theorem 10b, it follows that the asymptotic power against local alternatives  $\theta_n = \theta_0 + n^{-1/2}h$  of the test based on  $T_R(Q_n(\cdot; v^{(n)}))$  of size  $\tilde{\alpha}$  equals

$$P_{v_0}(\tilde{X}(\infty; v_0, \theta_0) > z_{\tilde{\alpha}}(a_R(v_0))^{-1/2} - h^T K_{a|0}(\infty; v_0)),$$

where  $z_{\tilde{\alpha}}$  is the  $(1 - \tilde{\alpha})$  quantile of a standard normal distribution. This implies that the efficacy of the sequence of test statistics  $\{T_R(Q_n(\cdot; v^{(n)}))\}_{n=1}^\infty$  is equal to  $e_R(h, v_0)$ .

Let  $I(v_0, \theta_0)$  be the Fisher information matrix, the symmetric  $(r+p) \times (r+p)$  matrix with elements

$$I_{ij}(v_0, \theta_0) = \int_0^\infty \psi_i(t; v_0, \theta_0) \psi_j(t; v_0, \theta_0) dH^1(t; v_0, \theta_0). \quad (4.40)$$

Partition this matrix as follows

$$I(v_0, \theta_0) = \begin{pmatrix} I_{00} & I_{0a} \\ I_{a0} & I_{aa} \end{pmatrix}, \quad (4.41)$$

where  $I_{00}$  is an  $r \times r$  matrix. Define the effective score function  $\psi_{a|0}(t; v_0, \theta_0)$  by

$$\psi_{a|0}(t; v_0, \theta_0) = \psi_a(t; v_0, \theta_0) - I_{a0} I_{00}^{-1} \psi(t; v_0, \theta_0). \quad (4.42)$$

The effective score function may be interpreted as a projection of the score function  $\psi_a(t; v_0, \theta_0)$ . Observe that

$$\int_0^\infty \psi_a(t; v_0, \theta_0) (\psi_a(t; v_0, \theta_0))^T dH^1(t; v_0, \theta_0) = I_{aa} - I_{a0} I_{00}^{-1} I_{0a}. \quad (4.43)$$

The right-hand side of the latter equation is known as effective Fisher information.

**Theorem 13** *The maximized values of  $e_R(h, v_0)$  and  $e_S(h, v_0)$  are both equal to  $h^T \{I_{aa} - I_{a0} I_{00}^{-1} I_{0a}\} h$ . Generalized rank tests based on weight processes with limiting weight function satisfying*

$$L(t; v_0, \theta_0) \propto h^T \{ \psi_{a|0}(t; v_0, \theta_0) \} + \nu^T \phi(t; v_0), \quad (4.44)$$

where  $\nu$  is an arbitrary  $r$ -dimensional vector, are maximizing  $e_R(h, v_0)$ . Supremum type tests based on maximum likelihood estimation and weight processes with limiting weight function satisfying

$$L(t; v_0, \theta_0) \propto h^T \psi_{a|0}(t; v_0, \theta_0) \quad (4.45)$$

are maximizing  $e_S(h, v_0)$ .

One may infer from the proof of Theorem 13 that for every supremum type test with  $e_S(h, v_0) = h^T \{I_{aa} - I_{a0} I_{00}^{-1} I_{0a}\} h$  there exists a generalized rank test [based on either the same stochastic integral or a "killed" version  $Q_n(t \wedge \tau; v^{(n)})$ , where  $0 < \tau < \infty$  fixed] with  $e_R(h, v_0) = h^T \{I_{aa} - I_{a0} I_{00}^{-1} I_{0a}\} h$ . The reverse is not true. If the stochastic integral underlying a generalized rank test with  $e_R(h, v_0) = h^T \{I_{aa} - I_{a0} I_{00}^{-1} I_{0a}\} h$  does not converge in  $P_{v_0}$ -distribution to a Gaussian process attaining its maximum in  $\infty$ , then we have that  $e_S(h, v_0)$  is less than  $h^T \{I_{aa} - I_{a0} I_{00}^{-1} I_{0a}\} h$  for the supremum type test based on the same stochastic integral.

This fact makes the choice of the weight process more critical for supremum type tests than for generalized rank tests. Preferably, the construction of a weight process should lead to

$$\int_0^\infty (L_0(s, t; v_0))^2 dH^1(s; v_0, \theta_0) \leq \int_0^\infty (L_0(s, \infty; v_0))^2 dH^1(s; v_0, \theta_0).$$

That is, under maximum likelihood estimation the weight process should be based on (4.45) rather than on (4.44).

Shortly after Theorem 9 a method of standardizing a weight process was described. If we follow this method for weight processes with limiting weight function satisfying (4.45), we obtain that the standardized weight processes have limiting weight function

$$L(t; v, \theta_0) = \frac{h^T \psi_{a|0}(t; v, \theta_0)}{\sqrt{h^T \{I_{aa} - I_{a0} I_{00}^{-1} I_{0a}\} h}}. \quad (4.46)$$

As far as generalized rank tests are concerned, the choice of the M-estimator turns out to be of secondary importance. The maximized value of  $e_R(h, v_0)$  does not depend on the estimation procedure. Equation (4.46) does not depend on the estimation procedure. For a weight process constructed according to (4.46) we have  $a_R(v_0) = 1$ , so the asymptotic behavior of the test statistics under the null hypothesis is not influenced by the estimation procedure. This implies that the quantity  $e_R(h, v_0)/a_R(v_0)$ , which characterizes the behavior of the test statistic under the alternative hypothesis, does not depend on the estimation procedure.

The choice of the M-estimator is far more important for supremum type tests, because of its effect on the position where the variance function  $\int_0^\infty (L_0(s, t; v_0))^2 dH^1(s; v_0, \theta_0)$  is maximized. For a general M-estimation procedure this position is difficult to determine. Theorem 13 restricts itself in this respect to maximum likelihood estimation.

In Hjort (1990)  $\chi^2$ -tests constructed from  $Q_n(t; v^{(n)})$ , where  $v^{(n)}$  is the maximum likelihood estimator, are studied using martingale methods. The effective score function appearing in our (4.45) also shows up in Hjort's equation (5.7). Without rigorous mathematical support, Hjort states that as a weight process this function "is a very good choice".

The maximum likelihood procedure pays no attention to the alternative hypothesis. A modification of the maximum likelihood estimator is obtained by choosing

$$\phi(t; v) = \psi(t; v, \theta_0) - I_{0a} I_{aa}^{-1} \psi_a(t; v, \theta_0) \quad (4.47)$$

This choice sets  $\int_0^\infty \phi_i(s; v) \psi_{r+j}(s; v, \theta_0) dH^1(s; v, \theta_0)$  equal to zero for every  $v \in \Upsilon$ ,  $i = 1, \dots, r$  and  $j = 1, \dots, p$ . Hence, the  $r \times p$  matrix  $\Xi_a(v, \theta_0)$  defined in (4.100) on page 80 is a null matrix. Since this matrix is related to the  $r \times p$  matrix of partial derivatives of  $\pi(v, \theta)$  with respect to the components of  $\theta$  [see the proof of Lemma 3], we may say that estimation is in a sense performed

“perpendicular” to the alternative hypothesis. Again the situation where the censoring distribution  $G$  is unknown calls for extra attention, since  $G$  is involved in  $I_{0a}I_{aa}^{-1}$ . We may try to estimate this quantity, but then the resulting function  $\phi(t; v)$  is a random element of  $D[0, \infty)$ , and falls outside our framework.

## 4.4 Proofs

In this section the proofs of previously stated theorems are gathered, with exception of Theorem 11, which is proved in Appendix A.

**Proof of Theorem 7** Let  $\Phi_{ni}(v)$  be shorthand notation for  $\Phi_{ni}(\infty; v)$ . Then the  $i^{\text{th}}$  equation involved in the definition of the M-estimator  $v^{(n)}$  may be written as  $\Phi_{ni}(v^{(n)}) = 0$  [see equation (4.3) on page 52].

The proof is based on a second order expansion of  $\Phi_{ni}(v)$  around  $v_{n0}$ . The stochastic terms in the expansion are approximated by means of deterministic counterparts. The quality of these approximations is reflected by the random variable  $S_n$ , to be introduced later. Conditional on the event  $S_n < n^{1/2}$  we use the “approximated” expansion to show the existence of  $v^{(n)}$ , and prove (4.8) and (4.9). Subsequently, empirical process theory is used to study the behavior of the random variable  $S_n$  in some detail, yielding (4.10) and (4.11).

The first order partial derivative of  $\Phi_{ni}(v)$  with respect to the  $j^{\text{th}}$  component of  $v$  is given by

$$\begin{aligned} \Phi_{nij}^{(1)}(v) &= n^{-1/2} \int_0^\infty \phi_{ij}^{(1)}(s; v) dM_n(s; v, \theta_0) \\ &\quad - \int_0^\infty \phi_i(s; v) \psi_j(s; v, \theta_0) (1 - H_{n-}(s)) d\Lambda(s; v, \theta_0). \end{aligned} \quad (4.48)$$

Furthermore, the second order partial derivative of  $\Phi_{ni}(v)$  with respect to the  $j^{\text{th}}$  and  $k^{\text{th}}$  components of  $v$  is given by

$$\begin{aligned} \Phi_{nij k}^{(2)}(v) &= n^{-1/2} \int_0^\infty \phi_{ijk}^{(2)}(s; v) dM_n(s; v, \theta_0) \\ &\quad - \int_0^\infty \{ \phi_i(s; v) \{ \psi_{jk}^{(1)}(s; v, \theta_0) + \psi_j(s; v, \theta_0) \psi_k(s; v, \theta_0) \} \\ &\quad \quad \phi_{ij}^{(1)}(s; v) \psi_k(s; v, \theta_0) \} (1 - H_{n-}(s)) d\Lambda(s; v, \theta_0), \end{aligned} \quad (4.49)$$

where  $\phi_{ijk}^{(2)}(t; v)$  is the second order partial derivative of  $\phi_i(t; v)$  with respect to the  $j^{\text{th}}$  and the  $k^{\text{th}}$  components of  $v$ , and  $\psi_{jk}^{(1)}(t; v)$  is the first order partial derivative of  $\psi_j(t; v)$  with respect to the  $k^{\text{th}}$  component of  $v$ .

Let  $\Phi_n^{(1)}(v)$  denote the  $r \times r$  matrix with elements  $\Phi_{nij}^{(1)}(v)$ , and  $\Phi_n^{(2)}(v)$  the  $r \times r$  matrix with elements  $\Phi_{nij k}^{(2)}(v)$ . By making essentially the same expansion

as in Borgan (1984), we obtain

$$\Phi_{ni}(v) = \Phi_{ni}(v_{n0}) + \Phi_{ni}^{(1)}(v_{n0})(v - v_{n0}) + (v - v_{n0})^T \Phi_{ni}^{(2)}(v')(v - v_{n0})/2 \quad (4.50)$$

for every  $v \in \Upsilon$ . Here  $\Phi_{ni}^{(1)}(v_{n0})$  is the  $i^{\text{th}}$  row of  $\Phi_n^{(1)}(v_{n0})$ , and  $v'$  a point on the line segment between  $v$  and  $v_{n0}$ .

Now define constants  $c_{58}$ - $c_{60}$  by  $c_{58} = 4(1 + c_\alpha + 1/\alpha)$ ,  $c_{59} = c_{35}/6c_{58}r^3$ ,  $c_{60} = ((c_\psi)^2 c_{35} c_{59}/6r) \wedge (c_\psi c_{35}/2r^2) \wedge c_{58}$ , and let  $V_n$  denote the closed ball in  $\Upsilon$  with centre  $v_{n0}$  and radius  $c_{59}$ . Moreover, denote the empirical processes  $n^{1/2}\{H_n^1(t) - H^1(t; v_n, \theta_n)\}$  and  $n^{1/2}\{H_{n-}(t) - H(t; v_n, \theta_n)\}$  by  $U_n^1(t; v_n, \theta_n)$  and  $U_{n-}(t; v_n, \theta_n)$ , respectively. The random variable  $S_n$  is defined by

$$\begin{aligned} S_n &= (2/c_{60})\left\{ \sup_{t \in [0, \infty)} |U_n^1(t; v_n, \theta_n)| \right. \\ &\quad \left. + \sup_{t \in [0, \infty)} \sup_{v \in V_n} \int_0^t |U_{n-}(s; v_n, \theta_n)| d\Lambda(s; v, \theta_0) \right\}. \end{aligned} \quad (4.51)$$

Observe that for functions  $f, g$  which are bounded by 1 and have total variation not exceeding 1, we have for every  $v \in V_n$

$$\begin{aligned} &|n^{-1/2} \int_0^\infty f(s) dM_n(s; v, \theta_0) - \int_0^\infty g(s)(1 - H_{n-}(s)) d\Lambda(s; v, \theta_0) \\ &\quad - \int_0^\infty \{f(s) + g(s)\} dD(s; v, \theta_0, v_n, \theta_n) \\ &\quad + \int_0^\infty g(s) dH^1(s; v_n, \theta_n)| \\ &\leq |n^{-1/2} \int_0^\infty g(s) dU_n^1(s; v_n, \theta_n)| \\ &\quad + |n^{-1/2} \int_0^\infty \{f(s) + g(s)\} U_{n-}(s; v_n, \theta_n) d\Lambda(s; v, \theta_0)| \\ &\leq c_{60} n^{-1/2} S_n, \end{aligned}$$

where the last inequality follows from integration by parts. Hence, by Condition 9, Condition 10 and Condition 11 we have

$$n^{1/2}(c_\psi)^2 |\Phi_{ni}(v_{n0})| \leq c_{60} S_n, \quad (4.52)$$

$$n^{1/2} c_\psi |\Phi_{nij}^{(1)}(v_{n0}) + \Xi_{0nij}| \leq c_{60} S_n, \quad (4.53)$$

and for all  $v \in V_n$

$$n^{1/2} |\Phi_{nij}^{(2)}(v) + A_{nij}(v)| \leq c_{60} S_n,$$

where  $A_{nij k}(v)$  is defined by

$$\begin{aligned} A_{nij k}(v) &= \int_0^\infty \{ \phi_i(s; v) \{ \psi_{jk}^{(1)}(s; v, \theta_0) + \psi_j(s; v, \theta_0) \psi_k(s; v, \theta_0) \} \\ &\quad + \phi_{ij}^{(1)}(s; v) \psi(s; v, \theta_0) \} dH^1(s; v_n, \theta_n) \\ &\quad - \int_0^\infty \{ \phi_i(s; v) \{ \psi_{jk}^{(1)}(s; v, \theta_0) + \psi_j(s; v, \theta_0) \psi_k(s; v, \theta_0) \} \\ &\quad + \phi_{ijk}^{(2)}(s; v) + \phi_{ij}^{(1)}(s; v) \psi_k(s; v, \theta_0) \} dD(s; v, \theta_0, v_n, \theta_n). \end{aligned}$$

Note that  $|A_{nij k}(v)| \leq c_{58}$  for all  $v \in \Upsilon$ .

Assume that (4.7) holds. It follows that

$$|\Phi_{ni}(v_{n0})| < c_{35}c_{59}/6r, \quad (4.54)$$

$$|\Phi_{nij}^{(1)}(v_{n0}) + \Xi_{0nij}| < c_{35}/2r^2, \quad (4.55)$$

and for every  $v \in V_n$

$$|\Phi_{nij k}^{(2)}(v)| < 2c_{58}. \quad (4.56)$$

As a consequence of (4.55) and Condition 12 we have

$$|\Phi_n^{(1)}(v_{n0})(v - v_{n0})| > c_{35}|v - v_{n0}|/2. \quad (4.57)$$

We shall now prove the existence of a solution in  $V_n$  to the equations (4.3). Let  $R_n(v)$  be the  $r$ -dimensional function defined by

$$R_n(v) = v - \{\Phi_n^{(1)}(v_{n0})\}^{-1} \Phi_n(v),$$

where  $\Phi_n(v)$  is the  $r$ -dimensional function with elements  $\Phi_{ni}(v)$ . Then it suffices to show the existence of  $v^{(n)} \in V_n$  such that  $v^{(n)} = R_n(v^{(n)})$ .

For every  $v \in V_n$  we have for some  $v'$  on the line segment between  $v$  and  $v_{n0}$

$$\begin{aligned} |R_n(v) - v_{n0}| &< 2|\Phi_n^{(1)}(v_{n0})(v - v_{n0}) - \Phi_n(v)|/c_{35} \\ &< \sum_{i=1}^r \{2|\Phi_{ni}(v_{n0})| + \sum_{j=1}^r \sum_{k=1}^r |\Phi_{nij k}^{(2)}(v')|(|v - v_{n0}|)^2\}/c_{35} \\ &< 2c_{59}/3, \end{aligned} \quad (4.58)$$

and hence  $R_n(v)$  maps  $V_n$  into  $V_n$ . Furthermore, for every  $v, v^* \in V_n$  there exist points  $v', v''$  on the line segment between  $v$  and  $v^*$  such that

$$|R_n(v) - R_n(v^*)| = |\{\Phi_n^{(1)}(v_{n0})\}^{-1} \{\Phi_n^{(1)}(v_{n0}) - \Phi_n^{(1)}(v')\}(v - v^*)|$$

$$\begin{aligned}
&\leq 2|\{\Phi_n^{(1)}(v_{n0}) - \Phi_n^{(1)}(v^*)\}(v - v^*)|/c_{35} \\
&\leq 2\left\{\sum_{i=1}^r \sum_{j=1}^r \sum_{k=1}^r |\Phi_{nij}^{(2)}(v'')|\right\}(|v - v^*|)^2/c_{35} \\
&\leq 2|v - v^*|/3.
\end{aligned} \tag{4.59}$$

Set  $s_0$  equal to  $v_{n0}$ , and define the sequence  $\{s_i\}_{i=1}^\infty$  recursively by  $s_i = R_n(s_{i-1})$ . From (4.58) and (4.59) it follows that this sequence converges to a point  $v^{(n)} \in V_n$  which satisfies  $v^{(n)} = R_n(v^{(n)})$ .

Next we show (4.8) and (4.9). From (4.50), (4.56) and the fact that  $\Phi_{ni}(v^{(n)}) = 0$  for  $i = 1, \dots, r$ , we may derive

$$|\Phi_n(v_{n0}) - \Xi_{0n}(v^{(n)} - v_{n0})| \leq \xi_n |v^{(n)} - v_{n0}|, \tag{4.60}$$

where

$$\xi_n = c_{58}r^3 |v^{(n)} - v_{n0}| + \sum_{i=1}^r \sum_{j=1}^r |\Phi_{nij}^{(1)}(v_{n0}) + \Xi_{0nij}|. \tag{4.61}$$

Since  $|\Xi_{0n}(v^{(n)} - v_{n0})| > c_{35}|v^{(n)} - v_{n0}|$  and  $\xi_n \leq 3c_{35}/4$ , we obtain

$$|v^{(n)} - v_{n0}| \leq 4|\Phi_n(v_{n0})|/c_{35},$$

and hence it follows from (4.52) that choosing  $c_{36} = 4c_{60}r/c_{35}(c_\psi)^2$  yields (4.8). Combining (4.8), (4.53) and (4.61) gives

$$n^{1/2}\xi_n \leq \{c_{36}c_{58}r^3 + c_{60}r^2/c_\psi\}S_n, \tag{4.62}$$

which together with Condition 12, (4.8) and (4.60) leads to (4.9), with  $c_{37} = c_{36}\{c_{36}c_{58}r^3 + c_{60}r^2/c_\psi\}/c_{35}$ .

The remainder of this proof, the verification of (4.10) and (4.11), resembles part of the proof of Theorem 2. Let  $\tilde{U}_n(t)$  be the empirical process based on the uniform (0,1) random variables  $\tilde{Z}_1, \dots, \tilde{Z}_n$ , defined by

$$\tilde{Z}_i = \delta_i H^1(Z_i; v_n, \theta_n) + (1 - \delta_i)\{H^1(\infty; v_n, \theta_n) + H^0(Z_i; v_n, \theta_n)\},$$

where

$$H^0(t; v_n, \theta_n) = H(t; v_n, \theta_n) - H^1(t; v_n, \theta_n)$$

is the cumulative distribution function of the censored failure times under  $P_n$ . Inequality 1 yields

$$P_n\left(\sup_{t \in [0,1]} |\tilde{U}_n(t)| > x\right) \leq 2c_1 \exp\{-2x^2\}. \tag{4.63}$$



Let  $\{d_n\}_{n=1}^\infty$  be a sequence of points in  $[0, \infty)$ . Later in this proof we specify this sequence in two different ways, depending on whether we are checking (4.10) or (4.11). Since Condition 9 implies that for every  $t \in [0, \infty)$  and  $v \in V_n$

$$\lambda(t; v, \theta_0) \leq c_{61} \lambda(t; v_{n0}, \theta_0), \quad (4.64)$$

where  $c_{61} = 1 + rc_\psi c_{59}$ , it follows that

$$\Lambda(t; v, \theta_0) \leq c_{61} \Lambda(t; v_{n0}, \theta_0), \quad (4.65)$$

$$\begin{aligned} & \int_{d_n}^\infty (1 - H(s; v_n, \theta_n)) d\Lambda(s; v, \theta_0) \\ & \leq c_{61} \int_{d_n}^\infty (1 - H(s; v_n, \theta_n)) d\Lambda(s; v_{n0}, \theta_0). \end{aligned} \quad (4.66)$$

Furthermore, we may write

$$S_n \leq (2/c_{60}) \{\Delta_{1n} + \Delta_{2n} + \Delta_{3n}\}, \quad (4.67)$$

where as consequences of the construction of  $\tilde{U}_n(t)$  and (4.65) we have

$$\begin{aligned} \Delta_{1n} &= \sup_{t \in [0, \infty)} |U_n^1(t; v_{n0}, \theta_0)| \\ &\leq \sup_{t \in [0, 1]} |\tilde{U}_n(t)|, \end{aligned} \quad (4.68)$$

$$\begin{aligned} \Delta_{2n} &= \sup_{t \in [0, d_n]} \sup_{v \in V_n} \int_0^t |U_{n-}(s; v_n, \theta_n)| d\Lambda(s; v, \theta_0) \\ &\leq \left\{ \sup_{t \in [0, d_n]} |U_{n-}(s; v_n, \theta_n)| \right\} \left\{ \sup_{v \in V_n} \Lambda(d_n; v, \theta_0) \right\} \\ &\leq 3c_{61} \Lambda(d_n; v_{n0}, \theta_0) \sup_{t \in [0, 1]} |\tilde{U}_n(t)|, \end{aligned} \quad (4.69)$$

$$\Delta_{3n} = \sup_{t \in [d_n, \infty)} \sup_{v \in V_n} \int_{d_n}^t |U_{n-}(s; v_n, \theta_n)| d\Lambda(s; v, \theta_0). \quad (4.70)$$

Together with (4.68) and (4.69), inequality (4.63) yields

$$P_n(\Delta_{1n} + \Delta_{2n} > 4c_{61} \Lambda(d_n; v_{n0}, \theta_0)x) \leq 2c_1 \exp\{-2x^2\}. \quad (4.71)$$

Observing that (4.66) implies

$$\Delta_{3n} \leq n^{1/2} c_{61} \int_{d_n}^\infty (1 - H(s; v_n, \theta_n)) d\Lambda(s; v_{n0}, \theta_0) \quad \text{if } Z_{n:n} < d_n,$$

where  $Z_{n:n}$  denotes the largest order statistic of the sample  $Z_1, \dots, Z_n$ , we obtain

$$\begin{aligned} P_n(\Delta_{3n} > n^{1/2}c_{61} \int_{d_n}^{\infty} (1 - H(s; v_n, \theta_n))d\Lambda(s; v_{n0}, \theta_0)) \\ \leq n(1 - H(d_n; v_n, \theta_n)). \end{aligned} \quad (4.72)$$

Now choose  $\beta > \alpha$ , and  $d_n$  so as to satisfy  $H(d_n; v_n, \theta_n) = 1 - n^{-(1+\gamma)}$ , where  $\gamma = (\beta - \alpha)/\alpha$ . By Condition 8 we have

$$\Lambda(d_n; v_{n0}, \theta_0) < c_\alpha n^\beta,$$

$$\int_{d_n}^{\infty} (1 - H(s; v_n, \theta_n))d\Lambda(s; v_{n0}, \theta_0) < c_\alpha n^{\beta-(\gamma+1)},$$

it follows from (4.71) and (4.72) that

$$P_n(\Delta_{1n} + \Delta_{2n} > 4c_\alpha c_{61} n^\beta \sqrt{(\gamma \log n)/2}) \leq 2c_1 n^{-\gamma}, \quad (4.73)$$

$$P_n(\Delta_{3n} > c_\alpha c_{61} n^{\beta-(\gamma+1/2)}) \leq n^{-\gamma}, \quad (4.74)$$

and hence (4.10).

Finally, assume  $(v_n, \theta_n) = (v_0, \theta_0)$ . Choose  $d_n$  so as to satisfy  $H(d_n; v_0, \theta_0) = 1 - \exp\{-2x^2\}/n$ , where  $x > (n^{1/2} \log n)^{-1}$ . By noting that

$$\Lambda(d_n; v_0, \theta_0) < \log n + 2x^2,$$

$$\begin{aligned} \int_{d_n}^{\infty} (1 - H(s; v_0, \theta_0))d\Lambda(s; v_0, \theta_0) &< \exp\{-2x^2\}/n \\ &< (n^{-1/2} \log n)x, \end{aligned}$$

we obtain from (4.71) and (4.72)

$$P_n(\Delta_{1n} + \Delta_{2n} > 4c_{61}x(\log n + 2x^2)) < 2c_1 \exp\{-2x^2\}, \quad (4.75)$$

$$P_{v_0}(\Delta_{3n} > c_{61}x \log n) \leq \exp\{-2x^2\}, \quad (4.76)$$

by which (4.11) readily follows. This concludes the proof of Theorem 7.  $\square$

**Proof of Theorem 8** The proof is based on replacing stochastic terms in a second order expansion of  $Q_n(t; v)$  by deterministic counterparts. The ‘‘approximated’’ expansion is applied to  $Q_n(t; v^{(n)})$ , and combined with (4.9) and Theorem 2.

The first order partial derivative of  $Q_n(t; v)$  with respect to the  $i^{th}$  component of  $v$  is given by

$$\begin{aligned} Q_{ni}^{(1)}(t; v) &= \int_0^t L_{ni}^{(1)}(s; v) dM_n(s; v, \theta_0) \\ &\quad - n^{1/2} \int_0^t L_n(s; v) \psi_i(s; v, \theta_0) (1 - H_{n-}(s)) d\Lambda(s; v, \theta_0), \end{aligned} \quad (4.77)$$

and the second order partial derivative of  $Q_n(t; v)$  with respect to the  $i^{th}$  and  $j^{th}$  components of  $v$  is given by

$$\begin{aligned} Q_{nij}^{(2)}(t; v) &= \int_0^t L_{nij}^{(2)}(s; v) dM_n(s; v, \theta_0) \\ &\quad - n^{1/2} \int_0^t \{L_n(s; v) \{\psi_{ij}^{(1)}(s; v, \theta_0) + \psi_i(s; v, \theta_0) \psi_j(s; v, \theta_0)\} \\ &\quad \quad + L_{nj}^{(1)}(s; v) \psi_i(s; v, \theta_0) \\ &\quad \quad + L_{ni}^{(1)}(s; v) \psi_j(s; v, \theta_0)\} (1 - H_{n-}(s)) d\Lambda(s; v, \theta_0). \end{aligned} \quad (4.78)$$

Here  $L_{nij}^{(2)}(t; v)$  denotes the second order partial derivative of  $L_n(t; v)$  with respect to the  $i^{th}$  and  $j^{th}$  components of  $v$ .

Now define

$$\begin{aligned} \tilde{Q}_{ni}^{(1)}(t; v) &= n^{1/2} \int_0^t L_n(s; v) \psi_i(s; v, \theta_0) dH^1(s; v_n, \theta_n) \\ &\quad - n^{1/2} \int_0^t \{L_n(s; v) \psi_i(s; v, \theta_0) \\ &\quad \quad + L_{ni}^{(1)}(s; v)\} dD(s; v, \theta_0, v_n, \theta_n), \end{aligned} \quad (4.79)$$

$$\begin{aligned} \tilde{Q}_{nij}^{(2)}(t; v) &= n^{1/2} \int_0^t \{L_{nj}^{(1)}(s; v) \psi_i(s; v, \theta_0) + L_{ni}^{(1)}(s; v) \psi_j(s; v, \theta_0) \\ &\quad + L_n(s; v) \{\psi_{ij}^{(1)}(s; v, \theta_0) \\ &\quad \quad + \psi_i(s; v, \theta_0) \psi_j(s; v, \theta_0)\}\} dH^1(s; v_n, \theta_n) \\ &\quad - n^{1/2} \int_0^t \{L_{nj}^{(1)}(s; v) \psi_i(s; v, \theta_0) + L_{ni}^{(1)}(s; v) \psi_j(s; v, \theta_0) \\ &\quad \quad + L_n(s; v) \{\psi_{ij}^{(1)}(s; v, \theta_0) + \psi_i(s; v, \theta_0) \psi_j(s; v, \theta_0)\} \\ &\quad \quad + L_{nij}^{(2)}(s; v)\} dD(s; v, \theta_0, v_n, \theta_n). \end{aligned} \quad (4.80)$$

By Condition 9, Condition 13 and integration by parts we obtain the existence of a constant  $c_{62}$ , not depending on  $v_n$  or  $\theta_n$ , such that

$$\begin{aligned} & \sup_{t \in [0, \infty)} |K_{0i}(t; v_n, \theta_n) - n^{-1/2} \tilde{Q}_{ni}^{(1)}(t; v_{n0})| \\ & \leq c_{62} \left\{ \sup_{t \in [0, \infty)} |L_n(t; v_{n0}) - L(t; v_n, \theta_n)| \right. \\ & \quad \left. + \sup_{t \in [0, \infty)} |L_{ni}^{(1)}(t; v_{n0}) - L_i^{[1]}(t; v_n, \theta_n)| \right\}, \end{aligned} \quad (4.81)$$

$$\sup_{t \in [0, \infty)} |Q_{ni}^{(1)}(t; v_{n0}) + \tilde{Q}_{ni}^{(1)}(t; v_{n0})| \leq c_{62} S_n, \quad (4.82)$$

and for every  $v \in V_n$

$$\sup_{t \in [0, \infty)} |Q_{nij}^{(2)}(t; v) + \tilde{Q}_{nij}^{(2)}(t; v)| \leq c_{62} S_n. \quad (4.83)$$

Next we introduce the set  $\Omega_n$ , consisting of all  $\omega \in \Omega$  such that  $S_n \leq n^{1/2}$  and that all random elements in  $D[0, \infty)$  occurring in Condition 13 are bounded and have bounded variation as specified in this condition. By noting that there exists a constant  $c_{63}$ , not depending on  $v_n$  or  $\theta_n$ , such that for  $\omega \in \Omega_n$

$$\sup_{t \in [0, \infty)} |\tilde{Q}_{nij}^{(2)}(t; v)| \leq c_{63} n^{1/2},$$

it follows from (4.83) that for  $\omega \in \Omega_n$  and  $v \in V_n$

$$\sup_{t \in [0, \infty)} |Q_{nij}^{(2)}(t; v)| \leq (c_{62} + c_{63}) n^{1/2},$$

and hence by (4.8)

$$\sup_{t \in [0, \infty)} |(v^{(n)} - v_{n0})^T Q_n^{(2)}(t; v)(v^{(n)} - v_{n0})| \leq c_{64} n^{-1/2} \{S_n\}^2, \quad (4.84)$$

where  $Q_n^{(2)}(t; v)$  is the  $r \times r$  matrix with elements  $Q_{nij}^{(2)}(t; v)$  and  $c_{64} = (c_{62} + c_{63})(c_{36}r)^2$ .

Furthermore, letting  $Q_n^{(1)}(t; v)$  denote the  $r$ -dimensional vector with elements  $Q_{ni}^{(1)}(t; v)$ , we obtain by (4.8), (4.81) and (4.82) for every  $\omega \in \Omega_n$

$$\begin{aligned} & \sup_{t \in [0, \infty)} |(v^{(n)} - v_{n0})^T \{Q_n^{(1)}(t; v_{n0}) + n^{1/2} K_0(t; v_n, \theta_n)\}| \\ & \leq |v^{(n)} - v_{n0}| \sum_{i=1}^r \left\{ \sup_{t \in [0, \infty)} |Q_{ni}^{(1)}(t; v_{n0}) + \tilde{Q}_{ni}^{(1)}(t; v_{n0})| \right. \\ & \quad \left. + \sup_{t \in [0, \infty)} |\tilde{Q}_{ni}^{(1)}(t; v_{n0}) - n^{1/2} K_{0i}(t; v_n, \theta_n)| \right\} \end{aligned}$$

$$\begin{aligned}
&\leq c_{36}c_{62}n^{-1/2}S_n \sum_{i=1}^r \{S_n \\
&\quad + n^{1/2} \sup_{t \in [0, \infty)} |L_n(t; v_{n0}) - L(t; v_n, \theta_n)| \\
&\quad + n^{1/2} \sup_{t \in [0, \infty)} |L_{ni}^{(1)}(t; v_{n0}) - L_i^{[1]}(t; v_n, \theta_n)|\}. \tag{4.85}
\end{aligned}$$

Since for every  $v \in V_n$  and  $t \in [0, \infty)$  we may find a point  $v'$  on the line segment between  $v$  and  $v_{n0}$  such that

$$\begin{aligned}
Q_n(t; v) &= Q_n(t; v_{n0}) + (v - v_{n0})^T Q_n^{(1)}(t; v_{n0}) \\
&\quad + (v - v_{n0})^T Q_n^{(2)}(t; v')(v - v_{n0})/2, \tag{4.86}
\end{aligned}$$

it follows from (4.84) and (4.85) that for every  $\omega \in \Omega_n$

$$\begin{aligned}
&\sup_{t \in [0, \infty)} |Q_n(t; v^{(n)}) - Q_n(t; v_{n0}) + n^{1/2}(v^{(n)} - v_{n0})^T K_0(t; v_n, \theta_n)| \\
&\leq (c_{64} + c_{36}c_{62})n^{-1/2}S_n \sum_{i=1}^r \{S_n \\
&\quad + n^{1/2} \sup_{t \in [0, \infty)} |L_n(t; v_{n0}) - L(t; v_n, \theta_n)| \\
&\quad + n^{1/2} \sup_{t \in [0, \infty)} |L_{ni}^{(1)}(t; v_{n0}) - L_i^{[1]}(t; v_n, \theta_n)|\}.
\end{aligned}$$

[here we have used  $v^{(n)} \in V_n$  if  $\omega \in \Omega_n$ ]. Hence, by (4.9) and the fact that  $K_0(t; v, \theta)$  remains bounded, uniformly in  $v$  and  $\theta$  [say by  $c_{65}$ ], we obtain

$$\begin{aligned}
&\sup_{t \in [0, \infty)} |Q_n(t; v^{(n)}) - Q_n(t; v_{n0}) + (K_0(t; v_n, \theta_n))^T \Xi_{0n}^{-1} \\
&\quad \int_0^\infty \phi(s; v_{n0}) \{dM_n(s; v_{n0}, \theta_0) - dD(s; v_n, \theta_n)\}| \\
&\leq (c_{64} + c_{36}c_{62} + c_{37}c_{65})n^{-1/2}S_n \sum_{i=1}^r \{S_n \\
&\quad + n^{1/2} \sup_{t \in [0, \infty)} |L_n(t; v_{n0}) - L(t; v_n, \theta_n)| \\
&\quad + n^{1/2} \sup_{t \in [0, \infty)} |L_{ni}^{(1)}(t; v_{n0}) - L_i^{[1]}(t; v_n, \theta_n)|\} \tag{4.87}
\end{aligned}$$

for every  $\omega \in \Omega_n$ . Now, (4.19) follows from (4.10), Condition 13 and by applying Theorem 2 to  $Q_n(t; v_{n0})$  and  $\int_0^\infty \phi(s; v_{n0})dM_n(s; v_{n0}, \theta_0)$  separately.

For the special case  $(v_n, \theta_n) = (v_0, \theta_0)$ , we may replace (4.81) by

$$\begin{aligned} & \sup_{t \in [0, \infty)} |K_{0i}(t; v_n, \theta_n) - n^{1/2} \tilde{Q}_{ni}^{(1)}(t; v_{n0})| \\ & \leq c_{62} \sup_{t \in [0, \infty)} |L_n(t; v_{n0}) - L(t; v_n, \theta_n)|, \end{aligned} \quad (4.88)$$

and hence (4.87) simplifies to

$$\begin{aligned} & \sup_{t \in [0, \infty)} |Q_n(t; v^{(n)}) - Q_n(t; v_{n0}) \\ & \quad + (K_0(t; v_0, \theta_0))^T \Sigma_{e0}^{-1} \int_0^\infty \phi(s; v_0) dM_n(s; v_0, \theta_0)| \\ & \leq (c_{64} + c_{36}c_{62} + c_{37}c_{65})n^{-1/2} S_n \sum_{i=1}^r \{S_n \\ & \quad + n^{1/2} \sup_{t \in [0, \infty)} |L_n(t; v_0) - L(t; v_0, \theta_0)|\} \end{aligned} \quad (4.89)$$

for every  $\omega \in \Omega_n$ . Applying Theorem 2 twice, together with Condition 13 and (4.11) yields (4.20). This concludes the proof of Theorem 8.  $\square$

**Proof of Theorem 9** Equations (4.26) and (4.27) are obtained along the lines of the proof of Theorem 5.2 in Borell (1975).

To prove (4.28) and (4.29), define the mean zero Gaussian process  $\check{X}_n(t; v_n, \theta_n)$  by

$$\begin{aligned} \check{X}_n(t; v_n, \theta_n) &= \int_0^t L(s; v_n, \theta_n) dW_n(s; v_{n0}) \\ &\quad - (K_0(t; v_{n0}, \theta_0))^T \Xi_{0n}^{-1} \int_0^\infty \phi(s; v_{n0}) dW_n(s; v_{n0}), \end{aligned}$$

Observe that  $\check{X}_n(t; v_0, \theta_0)$  is equal in  $P_{v_0}$ -distribution to  $\check{X}(t; v_0, \theta_0)$ . Moreover, by Theorem 8 we have

$$\begin{aligned} & P_{v_0} \left( \sup_{t \in [0, \infty)} |Q_n(t; v^{(n)}) - \check{X}_n(t; v_0, \theta_0)| > n^{-c_{28}} (c_{40} \log n + x)^{c_{29}} \right) \\ & \leq c_{41} \exp\{-c_{42}x\}, \end{aligned} \quad (4.90)$$

with  $c_{28} = 1/6$  and  $c_{29} = 3$ . Let  $c_{30} = c_{28}/(2c_{29} - 1)$  and choose  $c_{29}^{-1} < \beta < 2$ . By the same methods as used in the proof of Theorem 3 one may show

$$\begin{aligned} & P_{v_0} (|T(Q_n(\cdot; v^{(n)})) - T(\check{X}_n(\cdot; v_0, \theta_0))| > c_T n^{c_{30}(1-c_{29}\beta)} (s_n)^{c_{29}\beta}) \\ & \ll \exp\left\{-\inf_{v_0 \in \Gamma} \check{a}(v_0)(s_n)^2/2\right\}. \end{aligned} \quad (4.91)$$

Now (4.28) and (4.29) follow from bounding  $P_{v_0}(T(Q_n(\cdot; v^{(n)})) > s_n)$  between

$$\begin{aligned} P_{v_0}(T(\check{X}(\cdot; v_0, \theta_0)) > s_n(1 + c_T(n^{-c_{30}} s_n)^{c_{29}\beta-1})) \\ - P_{v_0}(T(\check{X}_n(\cdot; v_0, \theta_0)) - T(Q_n(\cdot; v^{(n)}))) > c_T n^{c_{30}(1-c_{29}\beta)} (s_n)^{c_{29}\beta} \end{aligned}$$

and

$$\begin{aligned} P_{v_0}(T(\check{X}(\cdot; v_0, \theta_0)) > s_n(1 - c_T(n^{-c_{30}} s_n)^{c_{29}\beta-1})) \\ + P_{v_0}(T(\check{X}_n(\cdot; v_0, \theta_0)) - T(Q_n(\cdot; v^{(n)}))) > c_T n^{c_{30}(1-c_{29}\beta)} (s_n)^{c_{29}\beta}. \end{aligned}$$

This concludes the proof of Theorem 9.  $\square$

To prove Theorems 10 and 12 we need the following lemma, a “composite null hypothesis” version of Lemma 2.

**Lemma 3** *Let  $g(t; v, \theta)$  be a real valued function,  $g_i^{(1)}(t; v, \theta)$  the first order partial derivative with respect to the  $i^{\text{th}}$  component of  $(v, \theta)$ . Suppose there exists a constant  $c_{66}$  such that*

$$\sup_{t \in [0, \infty)} (1 - H(t; v, \theta))^{\frac{1}{2}} |g(t; v, \theta)| \leq c_{66}, \quad (4.92)$$

$$\sup_{t \in [0, \infty)} (1 - H(t; v, \theta))^{1-\alpha} |g_i^{(1)}(t; v, \theta)| \leq c_{66} \quad (4.93)$$

for every  $v \in \Upsilon$  and  $\theta \in \Theta$ . Then there exists a constant  $c_{67}$  such that

$$\sup_{t \in [0, \infty)} \left| \int_0^t g(s; v, \theta) dD(s; v, \theta) \right| \leq c_{67} |\theta - \theta_0|, \quad (4.94)$$

$$\begin{aligned} \sup_{t \in [0, \infty)} \left| \int_0^t g(s; v, \theta) dH^1(s; v, \theta) \right. \\ \left. - \int_0^t g(s; \pi(v, \theta), \theta_0) dH^1(s; \pi(v, \theta), \theta_0) \right| \\ \leq c_{67} |\theta - \theta_0|. \end{aligned} \quad (4.95)$$

for every  $v \in \Upsilon$  and  $\theta \in \Theta$ . Let  $g_{ij}^{(2)}(t; v, \theta)$  the second order partial derivative of  $g(t; v, \theta)$  with respect to the  $i^{\text{th}}$  and  $j^{\text{th}}$  components of  $(v, \theta)$ . If

$$\sup_{t \in [0, \infty)} (1 - H(t; v, \theta))^\alpha |g(t; v, \theta)| \leq c_{66}, \quad (4.96)$$

$$\sup_{t \in [0, \infty)} (1 - H(t; v, \theta))^{\frac{1}{2}} |g_i^{(1)}(t; v, \theta)| \leq c_{66}, \quad (4.97)$$

$$\sup_{t \in [0, \infty)} (1 - H(t; v, \theta))^{1-\alpha} |g_{ij}^{(2)}(t; v, \theta)| \leq c_{66} \quad (4.98)$$

then there exists an  $r$ -dimensional function  $K_{a|0}^g(t; v)$  such that

$$\begin{aligned} \sup_{t \in [0, \infty)} \left| \int_0^t g(s; v, \theta) dD(s; v, \theta) - (\theta - \theta_0)^T K_{a|0}^g(t; \pi(v, \theta)) \right| \\ \leq c_{67} |\theta - \theta_0|^2 \end{aligned} \quad (4.99)$$

for every  $v \in \Upsilon$  and  $\theta \in \Theta$ .

**Proof of Lemma 3** Let the  $\Xi_a(v, \theta)$  be the  $r \times p$  matrix with elements

$$\begin{aligned} \Xi_{a|ij}(v, \theta) = \int_0^\infty \phi_i(s; \pi(v, \theta)) \psi_{r+j}(s; \pi(v, \theta), \theta_0) dH^1(s; v, \theta) \\ + \int_0^\infty \psi_i(s; \pi(v, \theta)) \Lambda_{r+j}^{(1)}(s; \pi(v, \theta), \theta_0) dD(s; v, \theta), \end{aligned} \quad (4.100)$$

and define  $K_{a|0}^g(t; v)$  by

$$\begin{aligned} K_{a|0}^g(t; v) = \int_0^\infty g(s; v, \theta_0) \{ \psi_a(s; v, \theta_0) \\ - (\{\Xi_0(v, \theta_0)\}^{-1} \Xi_a(v, \theta_0))^T \psi(s; v, \theta_0) \} dH^1(s; v, \theta_0). \end{aligned} \quad (4.101)$$

The Implicit Function Theorem tells us that the  $r \times r$  matrix of partial derivatives of  $\pi(v, \theta)$  with respect to the components of  $v$  equals

$$-\{\Xi_0(v, \theta)\}^{-1} \Xi_b(v, \theta),$$

and that the  $r \times p$  matrix of partial derivatives of  $\pi(v, \theta)$  with respect to the components of  $\theta$  equals

$$-\{\Xi_0(v, \theta)\}^{-1} \Xi_a(v, \theta).$$

Now fix  $v' \in \Upsilon$  and define the function  $\kappa : \Theta \rightarrow \Upsilon$  by

$$\pi(\kappa(\theta), \theta) = v'.$$

A second application of the Implicit Function Theorem yields that the  $r \times p$  matrix of partial derivatives of  $\kappa$  with respect to the components of  $\theta$  equals

$$-\{\Xi_b(\pi(v, \theta), \theta_0)\}^{-1} \Xi_a(\pi(v, \theta), \theta_0).$$

The elements of this matrix and the partial derivatives of these elements with respect to the components of  $\theta$  are uniformly bounded in  $v'$ ,  $v$  and  $\theta$ .



Let  $\tilde{g}(t; v)$  be defined as  $g(t; \kappa(\theta), \theta)$ , let  $\tilde{g}_i^{(1)}(t; v)$  be the first order partial derivative with respect to the  $i^{\text{th}}$  component of  $\theta$ , and let  $\tilde{g}_{ij}^{(2)}(t; v)$  denote the second order partial derivative of  $\tilde{g}(t; v)$  with respect to the  $i^{\text{th}}$  and  $j^{\text{th}}$  components of  $\theta$ . We have

$$\begin{aligned} \sup_{t \in [0, \infty)} (1 - H(t; \pi(v, \theta), \theta_0))^{\frac{1}{2}} |\tilde{g}(t; v)| &\leq c_{68}, \\ \sup_{t \in [0, \infty)} (1 - H(t; \pi(v, \theta), \theta_0))^{1-\alpha} |\tilde{g}_i^{(1)}(t; v)| &\leq c_{68} \end{aligned}$$

for some constant  $c_{68}$ . Moreover, if (4.96)-(4.98) hold, then we have

$$\begin{aligned} \sup_{t \in [0, \infty)} (1 - H(t; \pi(v, \theta), \theta_0))^\alpha |\tilde{g}(t; v)| &\leq c_{68}, \\ \sup_{t \in [0, \infty)} (1 - H(t; \pi(v, \theta), \theta_0))^{\frac{1}{2}} |\tilde{g}_i^{(1)}(t; v)| &\leq c_{68}, \\ \sup_{t \in [0, \infty)} (1 - H(t; \pi(v, \theta), \theta_0))^{1-\alpha} |\tilde{g}_{ij}^{(2)}(t; v)| &\leq c_{68}. \end{aligned}$$

Hence we are in the position to apply Lemma 2. By noting that  $c_{68}$  may be chosen independently of  $v'$  our lemma follows.  $\square$

**Proof of Theorem 10** Let  $\{W_n(t; v_{n0})\}_{n=1}^\infty$  be the sequence of mean zero Gaussian processes given in Theorem 8. We may write

$$\begin{aligned} \sup_{t \in [0, \infty)} |Q_n(t; v^{(n)}) - n^{1/2} |\theta_n - \theta_0| h^T K_{a|0}(t; v_0)| \\ \leq \Delta_{1n} + \Delta_{2n} + \Delta_{3n} + \Delta_{4n} + \Delta_{5n}, \end{aligned}$$

where

$$\begin{aligned} \Delta_{1n} = \sup_{t \in [0, \infty)} &|\{Q_n(t; v^{(n)}) - n^{1/2} \int_0^t L_n(s; v_{n0}) dD(s; v_n, \theta_n)\} \\ &- \{ \int_0^t L(s; v_n, \theta_n) dW_n(s; v_{n0}) \\ &- (K_0(t; v_n, \theta_n))^T \Xi_{0n}^{-1} \int_0^\infty \phi(s; v_{n0}) dW_n(s; v_{n0}) \}|, \end{aligned}$$

$$\begin{aligned} \Delta_{2n} = \sup_{t \in [0, \infty)} &| \int_0^t L(s; v_n, \theta_n) dW_n(s; v_{n0}) \\ &- (K_0(t; v_n, \theta_n))^T \Xi_{0n}^{-1} \int_0^\infty \phi(s; v_{n0}) dW_n(s; v_{n0}) |, \end{aligned}$$

$$\Delta_{3n} = n^{1/2} \sup_{t \in [0, \infty)} | \int_0^t \{L_n(s; v_{n0}) - L(s; v_n, \theta_n)\} dD(s; v_n, \theta_n) |$$

$$\Delta_{4n} = n^{1/2} \sup_{t \in [0, \infty)} \left| \int_0^t L(s; v_n, \theta_n) dD(s; v_n, \theta_n) \right. \\ \left. - |\theta_n - \theta_0| h^T K_{a|0}(t; v_{n0}) \right|,$$

$$\Delta_{5n} = n^{1/2} |\theta_n - \theta_0| \sup_{t \in [0, \infty)} \{h^T K_{a|0}(t; v_{n0}) - h^T K_{a|0}(t; v_0)\}.$$

By (4.19) we have for  $\beta < (1/2 - 2\alpha) \wedge 1/6$

$$P_n(\Delta_{1n} > c_{50} n^{-\beta}) \leq c_{51} n^{-c_{52}}. \quad (4.102)$$

Recall that  $K_{0i}(t; v, \theta)$  is bounded by  $c_{65}$ . It follows that the  $r$  components of  $(\Xi_{0n}^{-1})^T K_0(t; v_n, \theta_n)$  are bounded by  $c_{35} c_{65}$ , and hence we obtain by integration by parts with  $P_n$ -probability 1

$$\Delta_{2n} \leq 2(c_{43} + c_{35} c_{65} r) \sup_{t \in [0, \infty)} |W_n(t; v_{n0})|$$

The variance function of the process  $W_n(t; v_{n0})$  is bounded by  $(1 + 4(c_\alpha + 1/\alpha))^2$ , and thus Inequality 4 leads to

$$P_n(\Delta_{2n} > c_{69} x) \leq c_{37} \exp\{-c_{38} x^2\}, \quad (4.103)$$

where  $c_{69} = 2(c_{43} + c_{35} c_{65} r)(1 + 4(c_\alpha + 1/\alpha))$ . By observing that  $K_{a|0}^g(t; v)$  equals  $K_{a|0}(t; v)$  if  $g(t; v, \theta)$  is equal to  $L(t; v, \theta)$ , and that the components of  $K_{a|0}(t; v)$  remain bounded, it follows from Lemma 3 that there exists a constant  $c_{70}$  such that

$$\Delta_{4n} \leq c_{70} n^{1/2} \{|\theta_n - \theta_0|^2 + |(\theta_n - \theta_0) - (|\theta_n - \theta_0| h)|\}, \quad (4.104)$$

and for every  $v \in \Upsilon$ ,  $\theta \in \Theta$  and  $\beta > 1/2$

$$P_n(n^\beta \sup_{t \in [0, \infty)} \int_0^t (L_n(s; v_{n0}) - L(s; v_n, \theta_n)) dD(s; v, \theta) > c_{70} |\theta - \theta_0|) \\ \leq P_n(n^\beta \sup_{t \in [0, \infty)} |L_n(t; v_{n0}) - L(t; v_n, \theta_n)| > c_{44}).$$

Note that by Condition 13 this last inequality implies

$$P_n((n^{1/2} |\theta_n - \theta_0|)^{-1} \Delta_{3n} > c_{70} n^{-\beta}) \leq c_{45} n^{-c_{46}}. \quad (4.105)$$

Finally, there exists a constant  $c_{71}$  such that

$$\Delta_{5n} \leq c_{71} n^{1/2} (|\theta_n - \theta_0|) (|v_n - v_0|). \quad (4.106)$$

The first part of the theorem is now easily proved by combining the inequality

$$\begin{aligned} & |(n^{1/2}|\theta_n - \theta_0|)^{-1}T(Q_n(t; v^{(n)})) - T(h^T K_{a|0}(\cdot; v_0))| \\ & \leq c_T(n^{1/2}|\theta_n - \theta_0|)^{-1}(\Delta_{1n} + \Delta_{2n} + \Delta_{3n} + \Delta_{4n} + \Delta_{5n}). \end{aligned}$$

with (4.102)-(4.106).

In the proof of Theorem 9 we introduced the mean zero Gaussian process  $\check{X}_n(t; v_n, \theta_n)$ . Observe that

$$\begin{aligned} & \sup_{t \in [0, \infty)} |Q_n(t; v^{(n)}) - \{\check{X}_n(t; v_n, \theta_n) + n^{1/2}|\theta_n - \theta_0|h^T K_{a|0}(t; v_{n0})\}| \\ & \leq \Delta_{1n} + \Delta_{3n} + \Delta_{4n}. \end{aligned}$$

Since the right hand side of this inequality converges to zero in  $P_n$ -probability because  $\sigma$  is finite, we may prove the second part of the theorem by showing that the process  $\check{X}_n(t; v_n, \theta_n) + n^{1/2}|\theta_n - \theta_0|h^T K_{a|0}(t; v_{n0})$  converges in  $P_n$ -distribution to  $\check{X}(t; v_0, \theta_0) + \sigma h^T K_{a|0}(t; v_0)$ . This boils down to verifying the convergence in  $P_n$ -distribution of  $\check{X}_n(t; v_n, \theta_n)$  to  $\check{X}(t; v_0, \theta_0)$ , which can be done by using Lemma 3 to check the conditions of Theorem VI.10 in Pollard (1984). This completes the proof of Theorem 10.  $\square$

**Proof of Theorem 12** Let  $\Delta_{1n}$ ,  $\Delta_{2n}$ ,  $\Delta_{3n}$  and  $\Delta_{4n}$  be as in the proof of Theorem 10, and define  $b(v_n, \theta_n)$  as  $T(\int_0^\infty L(s; v_n, \theta_n)dD(s; v_n, \theta_n))$ . We may write

$$|n^{-1/2}T(Q_n(\cdot; v^{(n)})) - b(v_n, \theta_n)| \leq c_T n^{-1/2} \{\Delta_{1n} + \Delta_{2n} + \Delta_{3n}\}. \quad (4.107)$$

Furthermore, we have

$$|b(v_n, \theta_n) - |\theta_n - \theta_0|T(h^T K_{a|0}(\cdot; v_{n0}))| \leq c_T n^{-1/2} \Delta_{4n}. \quad (4.108)$$

Since  $\inf_{v_0 \in \Upsilon} e(h; v_0)$  is not equal to zero, this yields the existence of positive constants  $\epsilon^*$  and  $c_{72}$  such that

$$c_{72}|\theta_n - \theta_0| < b(v_n, \theta_n) < 1 \quad (4.109)$$

for  $\theta_n$  satisfying  $|\theta_n - \theta_0| < \epsilon^*$ .

Now suppose  $\theta \in \Theta - \{\theta_0\}$  satisfies  $|\theta_n - \theta_0| < \epsilon^*$ , and set  $(v_n, \theta_n)$  equal to  $(v, \theta)$  for every  $n \in \mathbb{N}$ . Choose  $\epsilon > 0$  and  $\delta \in (0, 1)$ . By (4.102) and (4.103) it follows that there exists an integer  $N_1$  not depending on  $v$  or  $\theta$  such that for  $n > N_1$

$$P_{(v, \theta)}(\Delta_{1n} > (N_1)^{1/2} \epsilon / 4c_T) < \delta/4,$$

$$P_{(v, \theta)}(\Delta_{2n} > (N_1)^{1/2} \epsilon / 4c_T) < \delta/4.$$

Hence, for  $n > N_1/(b(v, \theta))^2$  we have

$$P_{(v, \theta)}(n^{-1/2}\{\Delta_{1n} + \Delta_{2n}\} > \epsilon b(v, \theta)/2c_T) < \delta/2, \quad (4.110)$$

since  $n > N_1$  and  $(N_1/n)^{1/2} < b(v, \theta)$ . Moreover, (4.105) implies the existence of an integer  $N > N_1$  not depending on  $v$  or  $\theta$  such that for  $n > N$

$$\begin{aligned} P_{(v, \theta)}(\Delta_{3n} > \epsilon b(v, \theta)/2c_T) \\ \leq P_{(v, \theta)}((n^{1/2}|\theta_n - \theta_0|)^{-1}\Delta_{3n} > c_{T2}\epsilon) \\ < \delta/2. \end{aligned} \quad (4.111)$$

Combining (4.107)-(4.111) now yields that  $\{T(Q_n(\cdot; v^{(n)}))\}_{n=1}^{\infty}$  is indeed a Wieand sequence.

Finally, (4.35) immediately follows from (4.104) and (4.108). This concludes the proof of Theorem 12.  $\square$

**Proof of Theorem 13** Observe that for any  $r$ -dimensional vector  $\eta$  and every  $t \in [0, \infty) \cup \{\infty\}$

$$\begin{aligned} \int_0^{\infty} \eta^T \psi(s; v_0, \theta_0) L_0(s, t; v_0) dH^1(s; v_0, \theta_0) \\ = \eta^T K_0(t; v_0, \theta_0) - \eta^T \Sigma_{0e} \Sigma_{0e}^{-1} K_0(t; v_0, \theta_0) \\ = 0. \end{aligned}$$

By choosing  $\eta$  equal to  $I_{00}^{-1} I_{0a} h$  it follows that we may write  $h^T K_{a|0}(t; v_0)$  as

$$\int_0^{\infty} h^T \{\psi_a(s; v_0, \theta_0) - I_{a0} I_{00}^{-1} \psi(s; v_0, \theta_0)\} L_0(s, t; v_0) dH^1(s; v_0, \theta_0),$$

and hence we have by the Cauchy-Schwarz inequality that  $\{h^T K_{a|0}(t; v_0)\}^2$  is bounded by

$$h^T \{I_{aa} - I_{a0} I_{00}^{-1} I_{0a}\} h \int_0^{\infty} (L_0(s, t; v_0))^2 dH^1(s; v_0, \theta_0)$$

for every  $t \in [0, \infty) \cup \{\infty\}$ . This immediately yields that both  $e_R(h, v_0)$  and  $e_S(h, v_0)$  are bounded by  $h^T \{I_{aa} - I_{a0} I_{00}^{-1} I_{0a}\} h$ . It is easily established that this upper bound is achieved by generalized rank tests based on (4.44) and by supremum type tests based on maximum likelihood estimation and (4.45).  $\square$

## Chapter 5

# Testing exponentiality

### 5.1 The exponential distribution

If  $E_i$  is a random variable having an exponential distribution with mean  $e^{-\nu}$  then it follows that

$$P(E_i > t) = \exp\{-e^\nu t\}.$$

The parametrization chosen here is fairly uncommon. But, as we shall see later, for our purposes it is rather convenient. The standard exponential distribution is worth special mention. Here  $\nu$  equals zero.

It is easily seen that the cumulative hazard function belonging to the exponential distribution is linear with intercept 0 and slope  $e^\nu$ . Note that the corresponding basic martingale is a spline.

In this chapter the standard exponential distribution is used to generate samples  $X_1, \dots, X_n$  under the null hypothesis. Moreover, when investigating the effect of censoring various exponential distributions are used to generate samples  $Y_1, \dots, Y_n$ . In this respect note that if  $X_i$  has a standard exponential distribution and  $Y_i$  an exponential distribution with mean  $e^{-\nu}$ , then the probability that  $X_i$  is censored by  $Y_i$  is given by

$$P(X_i > Y_i) = \frac{e^\nu}{1 + e^\nu}.$$

### 5.2 Harrington and Fleming alternatives

In the results of previous chapters the functions  $\psi(t; \theta_0)$  and  $\psi(t; \nu_0, \theta_0)$  show up regularly. Hence, the applicability of these results depend heavily on the complexity of these functions. In Harrington and Fleming (1982) a family of distributions indexed by a single location parameter is constructed such that

$$\psi(t; \theta_0) = (1 - F(t; \theta_0))^\rho \tag{5.1}$$

for some fixed  $\rho \geq 0$ . The distributions within this family correspond to random variables which are allowed to take values anywhere on the real line. In this section we study an extended Harrington and Fleming family, indexed by two parameters, and always containing the exponential distribution as special case.

### 5.2.1 Derivation

The fact that we are dealing with a location parameter enables us to write

$$\lambda(t; \theta) = \lambda(t - \theta + \theta_0; \theta_0)$$

for all  $t \in \mathbb{R}$ . Hence, we have

$$\psi(t; \theta_0) = \frac{\lambda'(t; \theta_0)}{\lambda(t; \theta_0)},$$

where  $\lambda'(t; \theta_0)$  denotes the derivative of  $\lambda(t; \theta_0)$ . Thus, to find a family such that (5.1) holds, we must solve the equation

$$\frac{\lambda'(t; \theta_0)}{\lambda(t; \theta_0)} = (1 - F(t; \theta_0))^\rho, \quad (5.2)$$

which is actually a second order differential equation in disguise, as can be noted by writing  $1 - F(t; \theta_0) = \exp\{-\Lambda(t; \theta_0)\}$ . Let us for a moment restrict ourselves to positive values of  $\rho$ . Then the solution to the differential equation (5.2) is given by

$$F(t; \theta_0) = 1 - (1 + \rho e^t)^{-1/\rho}. \quad (5.3)$$

Note that for  $\rho = 1$  we obtain the logistic distribution.

Unfortunately, the Harrington and Fleming distributions do not fit into our framework, since they put positive mass on the negative part of the real line. Nevertheless, they indicate the way to construct other families of distributions better suited for our purposes. Observe that (5.3) implies

$$1 - F(t; \theta) = [1 + ((1 - F(t; \theta_0))^{-\rho} - 1)e^{\theta - \theta_0}]^{-1/\rho}. \quad (5.4)$$

Replacing  $F(t; \theta_0)$  by the distribution of an exponential random variable with mean  $e^{-v}$ , we obtain from (5.4)

$$1 - F(t; v, \theta) = [1 + (\exp\{-\rho e^v t\} - 1)e^{\theta - \theta_0}]^{-1/\rho} \quad (5.5)$$

Now let us derive the Harrington and Fleming distribution for  $\rho$  equal to zero. In this case the solution to (5.2) is given by

$$F(t; \theta_0) = 1 - \exp\{-e^t\},$$

which implies

$$1 - F(t; \theta) = (1 - F(t; \theta_0))^{\exp\{\theta - \theta_0\}},$$

and hence the failure time is an exponential random variable with mean  $e^{\theta_0 - \theta - v}$ . Of course, this distribution can be considered to be a special case of the distribution  $F(t; v, \theta)$ , so no adjustments of (5.5) are needed to include the case  $\rho = 0$ . We shall refer to the family of distributions  $F(t; v, \theta)$  as the family of Harrington and Fleming alternatives to the exponential distribution. We point out that for small values of  $\rho$ , the Harrington and Fleming alternatives closely resemble the exponential distribution. In fact, for  $\rho$  equal to zero we cannot speak of alternatives anymore.

By rewriting (5.4) in the intriguing form

$$\frac{(1 - F(t; \theta))^{-\rho} - 1}{(1 - F(t; \theta_0))^{-\rho} - 1} = e^{\theta - \theta_0}$$

it follows that

$$1 - F(t; \theta_0) = [1 + ((1 - F(t; \theta))^{-\rho} - 1)e^{\theta_0 - \theta}]^{-1/\rho}$$

by which the inverse of  $F(t; v, \theta)$  is readily calculated. When applied to uniform random variables this inverse generates random variables having distribution  $F(t; v, \theta)$ . However, we shall generate latter random variables in an alternative though strongly related way. Suppose  $E_i$  is a standard exponential random variable. Then

$$(\rho e^v)^{-1} \log(1 + (e^{\rho E_i} - 1)e^{\theta_0 - \theta}) \quad (5.6)$$

is a random variable with distribution  $F(t; v, \theta)$ .

### 5.2.2 Maximum likelihood estimation

Testing whether the random variables  $X_1, \dots, X_n$  follow an exponential distribution with unknown mean involves estimation of this mean under the null-hypothesis. Since we have

$$\Lambda(t; v, \theta_0) = e^v t,$$

it follows that

$$\psi_1(t; v, \theta_0) = 1,$$

and hence the maximum likelihood estimator  $v^{(n)}$  can be found by solving the likelihood equation

$$H_n^1(\infty) - \exp\{v^{(n)} - v_0\} \int_0^\infty (1 - H_{n-}(t)) d\Lambda(s; v_0, \theta_0) = 0$$

(here  $v_0$  is some arbitrary element of  $\Upsilon$ ), which yields

$$v^{(n)} = v_0 + \log H_n^1(\infty) - \log \int_0^\infty (1 - H_{n-}(t)) d\Lambda(s; v_0, \theta_0).$$

Condition 11 on page 54 requires the existence of a certain function  $\pi(v, \theta)$ , related to the M-estimator. This function indeed exists and is given by

$$\pi(v, \theta) = v_0 + \log H^1(\infty; v, \theta) - \log \int_0^\infty (1 - H(s; v, \theta)) d\Lambda(s; v_0, \theta_0).$$

The description of the behavior of  $v^{(n)}$  involves the  $1 \times 1$  matrices  $\Xi_0(v, \theta)$ ,  $\Xi_a(v, \theta)$  and  $\Xi_b(v, \theta)$ . For the maximum likelihood estimator both  $\Xi_0(v, \theta_0)$  and  $\Xi_b(v, \theta_0)$  have  $H^1(\infty; v, \theta_0)$  as single element. Hence for Conditions 12 and 18 to hold it is necessary that  $H^1(\infty; v, \theta_0)$ , the proportion uncensored observations under the null hypothesis, remains bounded away from zero. Observe that since in our framework the censoring distribution does not depend on  $v_n$  or  $\theta_n$ , the presence of censoring leads to the requirement that  $e^{-v}$  should not exceed a certain limit. However, it is possible [at the cost of additional complexity] to extend our framework by allowing the censoring distribution to depend on the parameters of the failure time distribution. This extension, which involves a straightforward generalization of Lemma 3, enables us to consider types of censoring in which the censoring distribution is linked to the failure time distribution.

If the proportion of uncensored observations remains indeed bounded away from zero, then Lemma 3 may be used to show that Conditions 12 and 18 hold if  $\Theta$  is appropriately chosen. The single element of  $\Xi_a(v, \theta_0)$  is equal to  $\mu_\rho(v)$ , where  $\mu_\beta(v)$  is defined by

$$\mu_\beta(v) = \int_0^\infty (1 - F(s; v, \theta_0))^\beta dH^1(s; v, \theta_0).$$

It should be stressed that the form of the function  $\psi_1(t; v, \theta_0)$  depends on the actual parametrization of the failure times. For instance, parametrizing the exponential distribution in the common way [using the reciprocal of the mean as parameter] leads to a different function  $\psi_1(t; v, \theta_0)$ , and hence to a different maximum likelihood estimator.

### 5.2.3 Modified maximum likelihood estimation

In the preceding chapter a modification of the maximum likelihood estimator was introduced, which was constructed “perpendicular” to the null hypothesis. In the situation considered here, this estimator is based on the function

$$\phi_1(t; v) = \frac{\mu_\rho(v)}{\mu_{2\rho}(v)} (1 - F(s; v, \theta_0))^\rho - 1.$$

Now  $\Xi_0(v, \theta_0)$  and  $\Xi_a(v, \theta_0)$  have as single element  $\mu_0(v) - (\mu_\rho(v))^2 / \mu_{2\rho}(v)$  and zero, respectively. The matrix  $\Xi_b(v, \theta_0)$  is equal to  $\Xi_0(v, \theta_0)$ . Observe that due to the involvement of the censoring distribution  $G$  in  $\mu_\rho(v)$  and  $\mu_{2\rho}(v)$  the modified maximum likelihood estimator can only be constructed if  $G$  is known. If there



is no censoring present, then  $\mu_\beta(v) = (1 + \beta)^{-1}$ , and hence  $\phi_1(t; v)$  takes the relatively easy form

$$\phi_1(t; v) = \frac{1 + 2\rho}{1 + \rho} \exp\{-\rho e^v t\} - 1,$$

while the single elements of the matrices  $\Xi_0(v, \theta_0)$  and  $\Xi_a(v, \theta_0)$  equal  $\rho^2/(2\rho + 1)$ .

Without knowledge of the censoring distribution, we can not apply the modified maximum likelihood estimation procedure to the Woolson data. Thus, to illustrate this procedure we introduce a second data set.

In Proschan (1963) a sample of 15 failure times of airconditioning equipment in aircraft is given. In this data set the phenomenon of censoring is absent. Nevertheless, when applied to the Proschan data the modified maximum likelihood procedure fails to yield an estimate for  $v^{(n)}$ .

The estimator  $v^{(n)}$  should satisfy  $\Phi_{n1}(\infty; v^{(n)}) = 0$  by equation (4.3) on page 52. In Figure 5.1  $\Phi_{n1}(\infty; v)$  is displayed as a function of  $v$ . As one can see it takes positive values only, leaving the modified maximum likelihood estimator undefined. Of course, it is possible to extend the definition of an M-estimator so as to cover this case also. E.g. rather than setting  $\Phi_{n1}(\infty; v^{(n)})$  equal to zero we could minimize the absolute value of  $\Phi_{n1}(\infty; v^{(n)})$ . For the Proschan data this extended procedure yields -5.3474 as an estimate for  $v_n$ . In contrast, the maximum likelihood estimate is -4.7980.

Without question the phenomenon observed here is undesirable, but understanding may enable us to avoid it. To arrive at an explanation view the basic martingale  $M_n(t; v, \theta_0)$  as the difference between the "counting process" part  $n^{1/2}H_n^1(t)$  and the "compensator" part  $\exp\{v - v_0\} \int_0^t (1 - H_{n-}(s)) d\Lambda(s; v_0, \theta_0)$ . Note that the latter part can alternatively be represented as  $\exp\{v - v_{n0}\} \int_0^t (1 - H_{n-}(s)) d\Lambda(s; v_{n0}, \theta_0)$ . As  $v$  tends to  $-\infty$  the process  $M_n(t; v, \theta_0)$  behaves more and more like the counting process part. The compensator part becomes dominant as  $v$  tends to  $+\infty$ .

Now observe that for fixed  $t$  the function  $\phi_1(t; v)$  changes sign from positive to negative as  $v$  travels from  $-\infty$  to  $+\infty$ . As a consequence  $\Phi_{n1}(\infty; v)$  is positive for values of  $v$  close to either  $-\infty$  or  $+\infty$ . Thus, in order for  $\Phi_{n1}(\infty; v)$  to have a zero, there must be a deep enough "dip" somewhere in its graph. As we can see from Figure 5.1 the dip exists, but is not deep enough.

74,	57,	48,	29,	502,
12,	70,	21,	29,	386,
59,	27,	153,	26,	326.

Table 5.1: Data given in Proschan (1963).

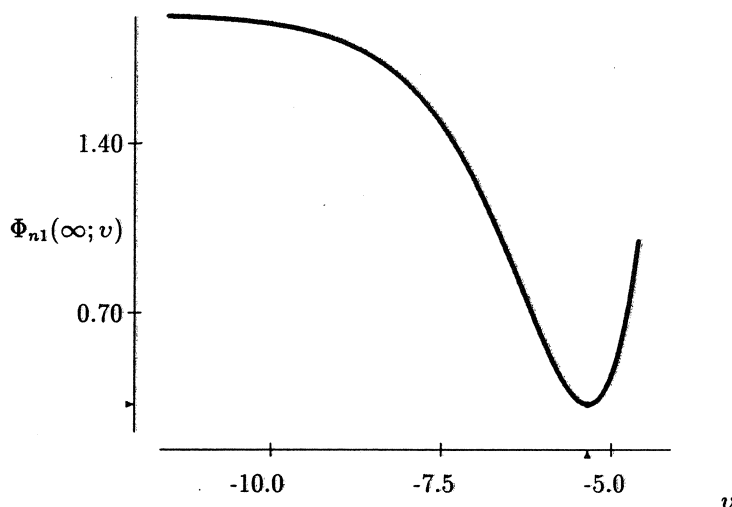


Figure 5.1:  $\Phi_{n1}(\infty; v)$  for modified maximum likelihood estimation procedure, applied to the Proschan data. Minimized value is 0.32467.

In case the dip was deep enough we would have had the choice between [at least] two zeroes. Our theory leads us to expect that  $\Phi_{n1}(\infty; v)$  seen as a function of  $v$  has a positive derivative near  $v^{(n)}$ . Hence, if there are two zeroes we should choose the one to the right of the point where the dip is maximal. In this respect it is noteworthy that for the Proschan data the maximum likelihood estimate is larger than the estimate based on the generalized definition of the modified maximum likelihood estimation procedure.

In the previous chapter we concluded that the estimation procedure was of secondary importance as far as asymptotic properties were concerned. However, at this moment it seems that we should prefer a function  $\phi_1(t; v)$  which does not change sign [say, which is nonnegative]. By using similar arguments as above it follows that such a function leads to  $\Phi_{n1}(\infty; v)$  being positive for values of  $v$  close to  $-\infty$ , being negative for values of  $v$  close to  $+\infty$ , and hence having an odd number of zeroes.

An additional advantage of a nonnegative function  $\phi_1(t; v)$  is that Condition 11 holds automatically. The integral  $\int_0^\infty \phi_1(s; v') dD(s; v', \theta_0, v, \theta)$  is positive for values of  $v'$  close to  $-\infty$ , and negative for values of  $v'$  close to  $+\infty$ . This can be seen by viewing the function  $D(t; v', \theta_0, v, \theta)$  as the difference between  $\int_0^t (1 - H(s; v, \theta)) d\Lambda(s; v, \theta)$  and its counterpart  $\int_0^t (1 - H(s; v', \theta)) d\Lambda(s; v', \theta)$ .

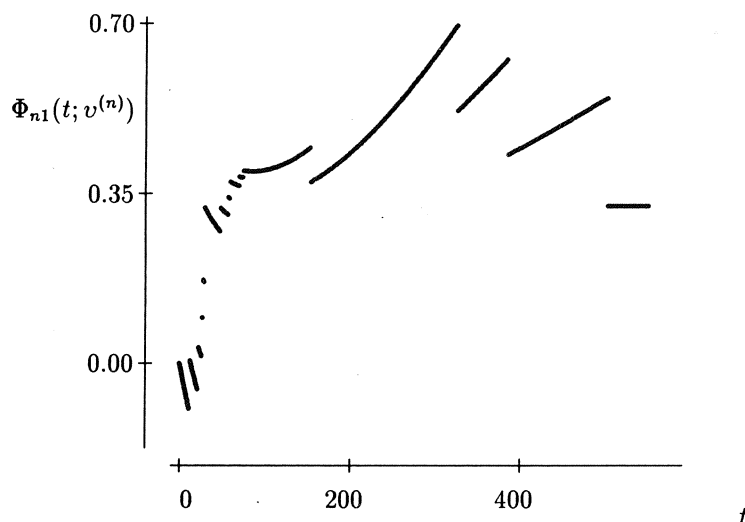


Figure 5.2: Stochastic integral related to the modified maximum likelihood estimator, constructed from the Proschan data. The value of  $v^{(n)}$  is -5.3474.

### 5.3 Weight processes

In this section we are dealing with a sample  $(Z_1, \delta_1), \dots, (Z_n, \delta_n)$  arising from a Harrington and Fleming alternative to the exponential distribution [that is,  $F(t; v_n, \theta_n)$  is defined according to (5.5)], and we discuss appropriate choices of the weight process which lead to optimal generalized rank and supremum type tests for the composite null hypothesis that the sample comes from an exponential distribution with unknown mean. The choices have in common that their limiting weight functions satisfy

$$L(t; v, \theta_0) = \frac{(1 - F(t; v, \theta_0))^\rho - \mu_\rho(v)/\mu_0(v)}{\sqrt{\mu_{2\rho}(v) - (\mu_\rho(v))^2/\mu_0(v)}}. \quad (5.7)$$

(compare with (4.46)). Hence, we always have  $a_R(v_0) = a_S(v_0) = 1$ . Moreover,  $e_R(h, v_0) = e_S(h, v_0) = \sqrt{\mu_{2\rho}(v_0) - (\mu_\rho(v_0))^2/\mu_0(v_0)}$ .

#### 5.3.1 Known censoring distribution

If the censoring distribution is known then we are in the position to make the obvious choice of using the limiting weight function  $L(t; v, \theta_0)$  as weight process.

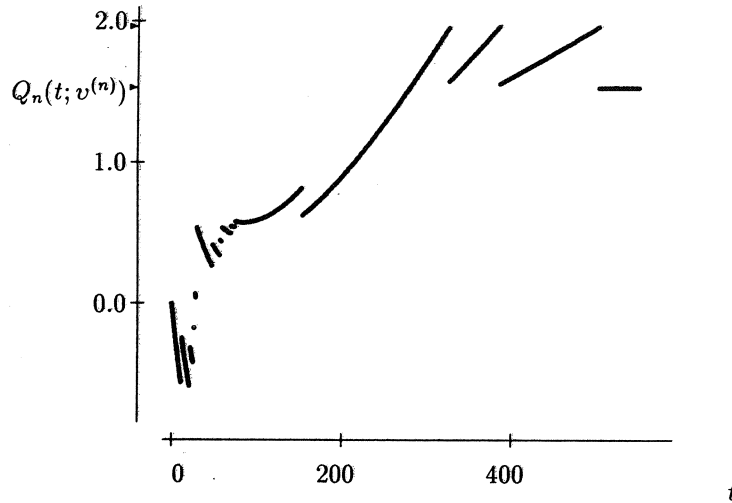


Figure 5.3: Stochastic integral based on maximum likelihood estimation and weight process for known censoring distribution, constructed from the Proschan data. The value of  $v^{(n)}$  is -4.7980. The two-sided generalized rank and supremum type test statistics attain values 1.529 and 1.967, respectively. The corresponding asymptotic probability values are 0.1262 and 0.0983.

The most important case of a known censoring distribution is the absence of censoring. Here we have  $\mu_\beta(v) = (1 + \beta)^{-1}$ , and hence setting the weight process equal to the right-hand side of (5.7) results in

$$L_n(t; v) = \frac{\sqrt{1 + 2\rho}}{\rho} [(1 + \rho) \exp\{-\rho e^v t\} - 1]. \quad (5.8)$$

Observe that

$$\begin{aligned} L_{n1}^{(1)}(t; v) &= -(1 + \rho) \sqrt{1 + 2\rho} e^v t \exp\{-\rho e^v t\} \\ L_{n1}^{(2)}(t; v) &= -(1 + \rho) \sqrt{1 + 2\rho} (\rho e^v - 1) e^v t \exp\{-\rho e^v t\} \end{aligned}$$

Moreover, using the fact that  $L(t; v, \theta) = L_n(t; \pi(v, \theta))$  for every  $v \in \Upsilon$  and  $\theta \in \Theta$ , it is easily seen that the weight process in (5.8) satisfies Condition 13.

### 5.3.2 Unknown censoring distribution

If  $G$  is unknown then it will not be possible to compute  $\mu_\beta(v)$ , and thus we are forced to estimate it. As remarked before, the common way to obtain estimators

for quantities involving  $H^1(t; v, \theta_0)$  is to replace this distribution function by  $\int_0^t (1 - H_{n-}(s)) d\Lambda(s; v, \theta_0)$ . This procedure yields as weight process

$$L_n(t; v) = \frac{(1 - F(t; v, \theta_0))^\rho - \hat{\mu}_\rho(v)/\hat{\mu}_0(v)}{\sqrt{\hat{\mu}_{2\rho}(v) - (\hat{\mu}_\rho(v))^2/\hat{\mu}_0(v)}}, \quad (5.9)$$

where

$$\begin{aligned} \hat{\mu}_\beta(v) &= \int_0^\infty (1 - F(s; v, \theta_0))^\beta (1 - H_{n-}(s)) d\Lambda(s; v, \theta_0) \\ &= \int_0^\infty \exp\{-\beta e^v s\} (1 - H_{n-}(s)) e^v ds. \end{aligned} \quad (5.10)$$

To verify Condition 13 we need some insight into the random behavior of  $\hat{\mu}_\beta(v)$ . Lemma 4 supplies us with the necessary knowledge, by relating the difference between a generalized version of  $\hat{\mu}_\beta(v)$  and its deterministic counterpart to the random variable  $S_n$  of Theorem 7 on page 55.

**Lemma 4** *Let  $g(t; v)$  be a real valued function, and define*

$$\hat{\mu}(v; g) = \int_0^\infty g(s; v) (1 - H_{n-}(s)) d\Lambda(s; v, \theta_0),$$

$$\mu(v, \theta; g) = \int_0^\infty g(s; \pi(v, \theta)) (1 - H(s; v, \theta)) d\Lambda(s; \pi(v, \theta), \theta_0).$$

*If the function  $g(t; v)$  remains uniformly bounded in  $t$  and  $v$ , then there exists a constant  $c_{73}$  such that for every  $\omega \in \Omega$*

$$|\hat{\mu}(v_{n0}; g) - \mu(v_n, \theta_n; g)| \leq c_{73} n^{-1/2} S_n.$$

**Corollary 7** *If for every  $i = 1, \dots, r$  the function  $g_i^{(1)}(t; v)$ , the first order partial derivative of  $g(t; v)$  with respect to the  $i^{\text{th}}$  component of  $v$ , remains uniformly bounded in  $t$  and  $v$ , then there exists a constant  $c_{73}$  and a function  $\mu_i^{[1]}(v, \theta; g)$  such that for every  $\omega \in \Omega$*

$$|\hat{\mu}_i^{(1)}(v_{n0}; g) - \mu_i^{[1]}(v_n, \theta_n; g)| \leq c_{73} n^{-1/2} S_n.$$

where  $\hat{\mu}_i^{(1)}(v; g)$  is the first order partial derivative of  $\hat{\mu}(v; g)$  with respect to the  $i^{\text{th}}$  component of  $v$ .

*If in addition the function  $g_{ij}^{(2)}(t; v)$ , the second order partial derivative of  $g(t; v)$  with respect to the  $i^{\text{th}}$  and  $j^{\text{th}}$  components of  $v$ , remains uniformly bounded in  $t$  and  $v$ , then there exists a constant  $c_{73}$  and a function  $\mu_{ij}^{[2]}(v, \theta; g)$  such that for every  $\omega \in \Omega$*

$$|\hat{\mu}_{ij}^{(2)}(v_{n0}; g) - \mu_{ij}^{[2]}(v_n, \theta_n; g)| \leq c_{73} n^{-1/2} S_n.$$

where  $\hat{\mu}_{ij}^{(2)}(v; g)$  is the first order partial derivative of  $\hat{\mu}(v; g)$  with respect to the  $i^{\text{th}}$  and  $j^{\text{th}}$  components of  $v$ .

**Proof of Lemma 4** From (4.51) we obtain

$$\begin{aligned}
& |\hat{\mu}(v_{n0}; g) - \mu(v_n, \theta_n; g)| \\
&= \left| \int_0^\infty g(s; v_{n0}) \{H_{n-}(s) - H(s; v_n, \theta_n)\} d\Lambda(s; v_{n0}, \theta_0) \right| \\
&\leq |g(t; v_{n0})| n^{-1/2} \sup_{t \in [0, \infty)} \left| \int_0^t U_{n-}(s; v_n, \theta_n) d\Lambda(s; v_{n0}, \theta_0) \right| \\
&\leq \sup_{t \in [0, \infty)} |g(t; v_{n0})| (c_{60}/6) n^{-1/2} S_n.
\end{aligned}$$

□

**Proof of Corollary 7** Define

$$\begin{aligned}
g_i^*(t; v) &= g_i^{(1)}(t; v) + g(t; v) \psi_i(t; v, \theta_0), \\
g_{ij}^*(t; v) &= g_{ij}^{(2)}(t; v) + g_i^{(1)}(t; v) \psi_j(t; v, \theta_0) \\
&\quad + g_j^{(1)}(t; v) \psi_i(t; v, \theta_0) + g(t; v) \psi_{ij}^{(1)}(t; v, \theta_0).
\end{aligned}$$

Then we have

$$\begin{aligned}
\hat{\mu}_i^{(1)}(v; g) &= \mu(v; g_i^*), \\
\hat{\mu}_{ij}^{(2)}(v; g) &= \mu(v; g_{ij}^*).
\end{aligned}$$

Since both  $g_i^*(t; v)$  and  $g_{ij}^*(t; v)$  remain uniformly bounded in  $t$  and  $v$ , we are in the position to apply Lemma 3, which yields the desired result. □

## 5.4 Total time on test plots

The weight processes of the previous section were derived so as to yield generalized rank and supremum type tests which are optimal against a specific alternative. However, in some circumstances the choice for some test statistic is not based on specific optimality, but on consistency against a broad class of alternatives instead. In this respect statistics based on total time on test plots are worth mentioning.

Total time on test plots are discussed in Barlow and Proschan (1969) and in Gill (1986). According to the former paper, they are obtained by plotting  $\int_0^t (1 - H_{n-}(s)) d\Lambda(s; v^{(n)}, \theta_0)$  versus  $H_n^1(t)$ , where  $v^{(n)}$  is the maximum likelihood

estimator. Under Type II censoring these plots allow to make assessments concerning the hazard function underlying the data. In particular, monotone hazard functions are easily recognized: depending on whether the hazard function is increasing or decreasing, the plot shows a convex or concave curve.

If the underlying distribution function is exponential [corresponding to a constant hazard function], then the total time on test plot should reflect a straight line through the origin, making a 45 degree angle with the  $X$ -axis. The deviations from this line are connected to the process  $M_n(t; v^{(n)}, \theta_0)$ . Not surprisingly, many proposals for tests for exponentiality inspired by the total time on test plot turn out to be based on functionals of  $M_n(t; v^{(n)}, \theta_0)$ . The supremum type test was mentioned in Barlow and Campo (1975). Observe that the generalized rank test does not make much sense, since it follows from the definition of the maximum likelihood estimator that  $M_n(\infty; v^{(n)}, \theta_0)$  is zero.

The asymptotic theory for  $M_n(t; v^{(n)}, \theta_0)$  is simply derived from the fact that for this process we have

$$L_0(s, t; v_0) = 1_{\{s \leq t\}} - \frac{H^1(t; v_0, \theta_0)}{H^1(\infty; v_0, \theta_0)}.$$

That is, the sequence  $\{M_n(t; v^{(n)}, \theta_0)\}_{n=1}^{\infty}$  converges in  $P_{v_0}$ -distribution to a mean zero Gaussian process with covariance function

$$\frac{H^1(t_1 \wedge t_2; v_0, \theta_0)(1 - H^1(t_1 \vee t_2; v_0, \theta_0))}{H^1(\infty; v_0, \theta_0)}.$$

For a better understanding of the qualities of the total time on test plot, consider the cumulative distribution function

$$F(t; v, \theta) = \begin{cases} 1 - \exp\{-e^{v+\theta}t\} & \text{if } t \leq \tau, \\ 1 - \exp\{-e^{v+\theta}\tau - e^{v-\theta}(t - \tau)\} & \text{if } t > \tau, \end{cases}$$

where  $\tau \in [0, \infty)$  is fixed. It follows that

$$\psi_1(t; v, \theta) = 1, \\ \psi_2(t; v, \theta) = \begin{cases} 1 & \text{if } t \leq \tau, \\ -1 & \text{if } t > \tau. \end{cases}$$

Now suppose that our knowledge of the censoring distribution is sufficient to determine  $H^1(\tau; v, \theta_0)$  and  $H^1(\infty; v, \theta_0)$ . In order to find optimal generalized rank and supremum type tests, we choose a weight process recommended by Theorem 13, yielding

$$L_n(t; v) = \begin{cases} \frac{1 - H^1(\tau; v, \theta_0)}{H^1(\infty; v, \theta_0)} & \text{if } t \leq \tau, \\ -\frac{H^1(\tau; v, \theta_0)}{H^1(\infty; v, \theta_0)} & \text{if } t > \tau. \end{cases}$$

The resulting stochastic integral satisfies

$$\begin{aligned} TR(Q_n(\cdot; v^{(n)})) &= Q_n(\tau; v^{(n)}) + (Q_n(\infty; v^{(n)}) - Q_n(\tau; v^{(n)})) \\ &= M_n(\tau; v^{(n)}, \theta_0). \end{aligned}$$

Hence, we may view the test based on the statistic  $M_n(\tau; v^{(n)}, \theta_0)$  as an optimal generalized rank test for the composite null hypothesis  $\theta = \theta_0$  in the example above. With some more effort we may show that the test based on either  $\sup_{0 \leq t \leq \tau} M_n(t; v^{(n)}, \theta_0)$  or  $\sup_{\tau \leq t \leq \infty} M_n(t; v^{(n)}, \theta_0)$ , depending on whether  $\mathcal{E}_{v_0} \{M_n(\tau; v^{(n)}, \theta_0)\}^2$  is equal to  $\sup_{0 \leq t \leq \tau} \mathcal{E}_{v_0} \{M_n(t; v^{(n)}, \theta_0)\}^2$  or equal to  $\sup_{\tau \leq t \leq \infty} \mathcal{E}_{v_0} \{M_n(t; v^{(n)}, \theta_0)\}^2$ , is an optimal supremum type test for the same testing problem.



## Chapter 6

# Small sample characteristics

### 6.1 Simulations

The theory of the preceding chapters is asymptotic of nature. It can be expected to work if the sample size  $n$  is large, but there is no absolute guarantee that this theory is also applicable in situations where the sample size is relatively small.

In this chapter we investigate which are the limitations to our theory with respect to sample size. The investigation is conducted by means of simulation experiments in situations described in section 5.1 and subsection 5.2.1.

Within the class of goodness-of-fit tests considered in our theory, a test is determined by four items: the estimation procedure, the weight process  $L_n(t; v)$ , the functional  $T$ , and the testsize. In the simulations choices are made for each of these items.

- If we count “no estimation” [that is, replace  $v^{(n)}$  by  $v_0$ ] as an estimation procedure, then two different estimation procedures are available, the other procedure being maximum likelihood. The modified maximum likelihood procedure, introduced in section 4.3, is not included in the simulations because of the weaknesses discussed in section 5.2.
- The weight process  $L_n(t; v)$  is always a linear function of  $\exp\{-\rho e^v t\}$ , where  $\rho$  equals 1. For administrative reasons the weight process is identified by a two-digit identification code, which determines the coefficients of the linear function. The first digit indicates whether the coefficients are deterministic [1; involve  $\mu_\beta(v)$ ] or random [2; involve  $\hat{\mu}_\beta(v)$ ]. The second digit marks the kind of weight process; it can be either 1 [one-sample log-rank: slope of the linear function is equal to zero], 2 [one-sample generalized Wilcoxon: intercept of the linear function is equal to zero] or 3 [weight process advocated in section 5.3].
- A description of the functionals  $T$  used is given in Table 6.1. For each test statistic an asymptotic P-value is computed. For generalized rank tests this

is done by means of the standard normal distribution, while for supremum type tests the distribution of the supremum of a standard Wiener process on  $[0, 1]$  is used. Observe that for a supremum type test with underlying stochastic integral not weakly converging to some time-transformed Wiener process, the asymptotic P-value is asymptotic in two respects: not only the sample size  $n$  should be large enough, the observed value of the test statistic should be large as well.

The asymptotic P-value facilitates intercomparison, since it transforms the various test statistics under study to statistics which have nearly the same null-distribution, while preserving the characteristics of the resulting test.

- Each test statistic is combined with 5 different test sizes, running from  $0.5/n$  to  $2.5/n$ .

During the simulations, a histogram of the asymptotic P-values is constructed. This histogram, which has interval width  $(5n)^{-1}$ , is used afterwards for density estimation.

The estimated density under the null hypothesis serves as the basis for the construction of critical points of the P-values. If Table 6.4b tells us that the critical point of the left-sided generalized rank test is 0.0136 for size 0.020, this means that rejecting the null hypothesis if and only if the asymptotic P-value is less than or equal to 0.0136 yields a test with size 0.020 “exactly”, implying that we would obtain an anticonservative test if we were to use the asymptotic P-value as an approximation to the exact P-value [that is, rejection only takes place if the asymptotic P-value is less than or equal to 0.020].

Subsequently, power is estimated by computing the left tail probability belonging to a critical point of the asymptotic P-value. This computation takes place according to the estimated density under one of the four alternative hypotheses.

The sample sizes used are 25, 50 and 100. For each of these sample sizes we construct 10000 replications of five types of censored and five types of uncensored samples. For the construction of censored samples the standard exponential distribution serves as censoring distribution.

<i>Test</i>	<i>Functional T(ξ)</i>		
	Leftsided	Rightsided	Twosided
Generalized rank	$-\xi(\infty)$	$\xi(\infty)$	$ \xi(\infty) $
Supremum type	$\sup_{t \in [0, \infty)} -\xi(t)$	$\sup_{t \in [0, \infty)} \xi(t)$	$\sup_{t \in [0, \infty)}  \xi(t) $

Table 6.1: Functionals used.

## 6.2 The simple null hypothesis

The simulated samples are drawn from a distribution  $F(t; v_n, \theta_n)$  belonging to the family of Harrington and Fleming alternatives to the exponential distribution, as described in Section 5.2. The value of  $v_n$  and  $\rho$  are always 0 and 1, respectively. Hence, we are considering logistic shift alternatives to the standard exponential distribution.

The parameter of interest  $\theta_n$  varies in the following way with sample size:

$$\theta_n = c_H \sqrt{\frac{2 \log n}{n \mu_{2\rho}(v_0)}}, \quad (6.1)$$

where  $c_H$  is chosen according to the type of hypothesis under which simulation takes place. There are five types of hypotheses:  $H_{LL}$ ,  $H_L$ ,  $H_0$ ,  $H_R$  and  $H_{RR}$ ; the respective choices of  $c_H$  are -1.0, -0.5, 0.0, 0.5 and 1.0. The resulting values of  $\theta_n$  are displayed in Table 6.2. The value of  $\theta_n$  under  $H_0$  coincides with  $\theta_0$ .

The asymptotic power of a generalized rank test is equal to the probability that a standard normal random variable exceeds  $z_{\tilde{\alpha}} - (\theta_n - \theta_0) \sqrt{ne_R(h)}$ , where  $z_{\tilde{\alpha}}$  is the  $(1 - \tilde{\alpha})$  quantile of the standard normal distribution.

Approximating  $z_{\tilde{\alpha}}$  by  $\sqrt{-2 \log \tilde{\alpha}}$ , we find that equation (6.1) implies that under  $H_{LL}$  and  $H_{RR}$  the power of a size  $1/n$  one-sided generalized rank test based on stochastic integral 12 [for which  $e_R(h) = \mu_{2\rho}(v_0)$ ] will tend to 0.5 as  $n$  tends to infinity. However, the power of such a test will still be far away from 0.5 in the region of the sample sizes we are considering, due to poor quality of the approximation of  $z_{\tilde{\alpha}}$ . Table 6.3 indicates the power we could expect from the generalized rank test based on stochastic integral 12.

Observe that the same crude approximation of  $z_{\tilde{\alpha}}$  is used under similar conditions in the weak intermediate efficiency concept.

Sample size	Type of Censoring	$H_{LL}$	$H_L$	$H_0$	$H_R$	$H_{RR}$
25	None	-0.8789	-0.4395	0.0000	0.4395	0.8789
25	Exp(1)	-1.0149	-0.5075	0.0000	0.5075	1.0149
50	None	-0.6852	-0.3426	0.0000	0.3426	0.6852
50	Exp(1)	-0.7912	-0.3956	0.0000	0.3956	0.7912
100	None	-0.5257	-0.2628	0.0000	0.2628	0.5257
100	Exp(1)	-0.6070	-0.3035	0.0000	0.3035	0.6070

Table 6.2: Values of  $\theta_n$ . The values of  $v_n$ ,  $\theta_0$  and  $\rho$  are always equal to 0, 0 and 1, respectively.

Size of test	One-sided test				Two-sided test			
	$H_{LL}$	$H_L$	$H_R$	$H_{RR}$	$H_{LL}$	$H_L$	$H_R$	$H_{RR}$
Sample size 25								
0.020	0.686	0.216	0.216	0.686	0.584	0.145	0.145	0.584
0.040	0.784	0.315	0.315	0.784	0.686	0.217	0.217	0.686
0.060	0.837	0.387	0.387	0.837	0.744	0.271	0.271	0.744
0.080	0.871	0.446	0.446	0.871	0.784	0.316	0.316	0.784
0.100	0.895	0.495	0.495	0.895	0.814	0.355	0.355	0.814
Sample size 50								
0.010	0.681	0.177	0.177	0.681	0.588	0.120	0.120	0.588
0.020	0.771	0.256	0.256	0.771	0.681	0.177	0.177	0.681
0.030	0.820	0.315	0.315	0.820	0.735	0.220	0.220	0.735
0.040	0.852	0.362	0.362	0.852	0.771	0.257	0.257	0.771
0.050	0.875	0.403	0.403	0.875	0.799	0.288	0.288	0.799
Sample size 100								
0.005	0.677	0.145	0.145	0.677	0.590	0.099	0.099	0.590
0.010	0.761	0.209	0.209	0.761	0.677	0.145	0.145	0.677
0.015	0.806	0.257	0.257	0.806	0.727	0.180	0.180	0.727
0.020	0.837	0.296	0.296	0.837	0.761	0.209	0.209	0.761
0.025	0.859	0.329	0.329	0.859	0.786	0.235	0.235	0.786

Table 6.3: Asymptotic power of generalized rank test based on stochastic integral 12 (no estimation). Also valid for generalized rank test based on stochastic integral 13 (maximum likelihood estimation).

### 6.2.1 Stochastic integral 11

The first stochastic integral we encounter, type 11 [no estimation], is based on the weight process

$$L_n(t; v) = (\mu_0(v))^{-1/2}. \quad (6.2)$$

Hence, this stochastic integral yields the same tests as the basic martingale  $M_n(t; v_0, \theta_0)$ . The generalized rank test is the well-known test of Breslow (1975), a one-sample logrank test. The supremum type test was investigated by Aki (1986). Both tests are indicated for detecting proportional hazards alternatives. In our simulations the alternatives are of a different type, namely logistic shift. We have  $a_R = a_S = 1$  and

$$e_R(h) = e_S(h) = \frac{(\mu_\rho(v_0))^2}{\mu_0(v_0)}. \quad (6.3)$$

In the absence of censoring this becomes  $e_R(h) = e_S(h) = 1/4$ .

To obtain some intuition about how the small sample behavior deviates from the asymptotic behavior, we first pay some attention to  $M_1(\infty; v_0, \theta_0)$ , the basic

martingale for sample size 1, evaluated at infinity. Remark that  $M_n(\infty; \nu_0, \theta_0)$  is an appropriately scaled sum of  $n$  independent copies of  $M_1(\infty; \nu_0, \theta_0)$ .

We may view  $M_1(\infty; \nu_0, \theta_0)$  as a difference between two nonnegative random variables  $\delta_1$  and  $\Lambda(Z_1; \nu_0, \theta_0)$ , which do not have much in common. The former takes values 0 and 1 only [in the absence of censoring it even becomes degenerate], and hence is bounded. The latter takes values everywhere on the complete halfline, and in general has a distinct tail. Thus, for small sample sizes we may encounter asymmetric behavior of the basic martingale. Since the limiting process of the basic martingale is Gaussian the asymmetry should vanish as the sample size becomes larger.

Under  $H_0$  both random variables have mean  $H^1(\infty; \nu_0, \theta_0)$ , and hence we expect that the mean of  $M_n(\infty; \nu_0, \theta_0)$  is equal to zero. Tables 6.4a, 6.5a and 6.6a show that this expectation, which also could be inferred from martingale theory, becomes true.

Moreover, these tables reflect the asymmetry of the basic martingale. Under  $H_L$  and  $H_{LL}$  the mean of  $M_n(\infty; \nu_0, \theta_0)$  deviates more from zero than under their counterparts  $H_R$  and  $H_{RR}$ . This is in part compensated by the standard deviation, which tends to inflate under  $H_L$  and  $H_{LL}$  and to deflate under  $H_R$  and  $H_{RR}$ .

If we conclude from Tables 6.4a, 6.5a and 6.6a that the generalized rank test based on  $M_n(t; \nu_0, \theta_0)$  is more sensitive to the left than to the right, then we are drawing our conclusions too hastily. The asymmetry of the basic martingale is also reflected in the tail behavior under  $H_0$ , since the left tail of  $M_n(\infty; \nu_0, \theta_0)$  is more outstretched than the right tail.

The adverse location of the left-sided critical points annuls the initial higher sensitivity on the left side, and even makes the left-sided generalized rank test less sensitive than the right-sided generalized rank test.

Tables 6.4, 6.5 and 6.6 also indicate that the effects of the asymmetry of the basic martingale are even worse for supremum type tests.

### 6.2.2 Stochastic integral 21

The stochastic integral type 21 [no estimation] is a variant of stochastic integral 11, having weight process

$$L_n(t; \nu) = (\hat{\mu}_0(\nu))^{-1/2}. \quad (6.4)$$

Hence, it is obtained by dividing the basic martingale by the square root of the variance estimator  $\hat{\mu}_0(\nu_0) = \int_0^\infty (1 - H_{n-}(s)) d\Lambda(s; \nu_0, \theta_0)$ . By making this division the martingale property is lost. The quantities  $e_R(h)$  and  $e_S(h)$  are the same as for stochastic integral 11, and are given by (6.3).

Before looking at the simulation results, we first investigate the behavior of stochastic integral 21 evaluated at  $\infty$  for sample size 1 by viewing it as the difference between the random variables  $\delta_1(\Lambda(Z_1; \nu_0, \theta_0))^{-1/2}$  and  $(\Lambda(Z_1; \nu_0, \theta_0))^{1/2}$ .

Both are nonnegative and take values everywhere on the complete halfline. In general, the former random variable is heavier tailed than the latter. Moreover, under  $H_0$  the random variables differ in mean. To exemplify, suppose censoring is absent. Now we have

$$P_0\left(\frac{\delta_1}{\sqrt{\Lambda(Z_1; v_0, \theta_0)}} \leq x\right) = \exp\{-x^{-2}\},$$

$$P_0(\sqrt{\Lambda(Z_1; v_0, \theta_0)} \leq x) = 1 - \exp\{-x^2\}.$$

The tail of  $\delta_1(\Lambda(Z_1; v_0, \theta_0))^{-1/2}$ , which vanishes at a rate  $x^{-2}$ , is quite heavy, whereas the tail of  $(\Lambda(Z_1; v_0, \theta_0))^{1/2}$  is moderate [that is, comparable to the tail of a Gaussian random variable]. Moreover, under  $P_0$  the mean of  $\delta_1(\Lambda(Z_1; v_0, \theta_0))^{-1/2}$  is equal to  $\pi^{1/2}$  and differs from the mean of  $(\Lambda(Z_1; v_0, \theta_0))^{1/2}$ , which is equal to  $\pi^{1/2}/2$ . It seems that the behavior of stochastic integral 21 shows asymmetry that is in some sense opposite to asymmetry in the behavior of stochastic integral 11. This is also reflected in Tables 6.7, 6.8 and 6.9.

Though  $e_R(h)$  and  $e_S(h)$  coincide, the supremum type tests surpass the generalized rank test in simulated power. This is not only true for stochastic integral 21, but also for stochastic integral 11, and underlines the omnibus character of the supremum type tests.

Surprisingly, Tables 6.4c and 6.7c show that the simulated power of one-sided tests based on stochastic integral 21 do not differ much from the simulated power of the corresponding tests based on stochastic integral 11. This is certainly not true for the two-sided tests. Two-sided tests based on stochastic integral 21 are relatively more sensitive to positive and less sensitive to negative values of  $\theta_n$ .

### 6.2.3 Stochastic integral 12

The weight process underlying stochastic integral 12 is given by

$$L_n(t; v) = (\mu_\rho(v))^{-1/2} \exp\{-\rho e^{vt}\}. \quad (6.5)$$

The generalized rank test based on stochastic integral 12, a one-sample version of the two-sample generalized Wilcoxon test, was recommended by Harrington and Fleming (1982) as a test against the alternatives proposed in the same paper [which we have highlighted in section 5.2], to be used if there is no censoring present. Their recommendation followed from heuristic arguments. Indeed, the theory in section 3.3 shows that this test is optimal.

For stochastic integral 12 we have

$$e_R(h) = e_S(h) = \mu_{2\rho}(v_0) \quad (6.6)$$

If there is no censoring present we have  $e_R(h) = e_S(h) = 1/3$ . If the censoring distribution is standard exponential then  $e_R(h) = e_S(h) = 1/4$ .

The stochastic integral evaluated at infinity may be viewed as the scaled sum of  $n$  independent copies of the random variable  $(1 - F(Z_1; v_0, \theta_0))\delta_1 - F(Z_1; v_0, \theta_0)$ , which takes values between -1 and 1. For instance, under  $H_0$  and in the absence of censoring this random variable is uniformly distributed on the interval  $[-1, 1]$ .

This suggests that the behavior of the stochastic integral is very close to symmetry, an impression confirmed by the uncensored sample simulation results. The censored sample simulations show a slight difference between the left- and right-sided critical values, and a higher sensitivity to negative values of  $\theta_n$ .

The simulated power of the generalized rank test is in accordance with the asymptotic power given in Table 6.3.

As we compare with the simulation results for stochastic integral 11, we see that the one-sided tests indeed yield higher power. However, the two-sided supremum type test gets the worst of it under  $H_L$  and  $H_{LL}$ .

#### 6.2.4 Stochastic integral 22

Stochastic integral 22 is a variant of stochastic integral 21, to be used if the censoring distribution is unknown. Its weight process is

$$L_n(t; v) = (\hat{\mu}_\rho(v))^{-1/2} \exp\{-\rho e^v t\}. \quad (6.7)$$

The generalized rank test based on stochastic integral 22 appeared in Harrington and Fleming (1982). The quantities  $e_R(h)$  and  $e_S(h)$  are given by (6.6).

As we compare the uncensored sample results of stochastic integral 22 and stochastic integral 12, we do not spot many differences in simulated power of the one-sided tests. This in contrast to two-sided tests: those based on stochastic integral 22 are relatively more sensitive to positive and less sensitive to negative values of  $\theta_n$ . Observe that we reached the same conclusion in the comparison of stochastic integral 12 with stochastic integral 11, suggesting that the use of a variance estimator does not have much effect on the power of one-sided tests, but shifts the sensitivity of two-sided tests to the right. In censored samples, the shift in sensitivity is also noticeable for one-sided tests.

With respect to stochastic integral 21, the stochastic integral clearly yields higher simulated power, especially for generalized rank tests.

	$H_{LL}$	$H_L$	$H_0$	$H_R$	$H_{RR}$
mean $Q_n(\infty; v_0)$	-2.5089	-1.1775	-0.0006	1.0270	1.8984
st.dev. $Q_n(\infty; v_0)$	1.2064	1.1066	0.9935	0.9013	0.7754
skewness $Q_n(\infty; v_0)$	-0.2450	-0.2967	-0.3690	-0.4190	-0.4382
kurtosis $Q_n(\infty; v_0)$	0.0579	0.0787	0.1239	0.2699	0.3639

a

Size of test	Generalized rank test			Supremum type test		
	Left-Sided	Right-Sided	Two-Sided	Left-Sided	Right-Sided	Two-Sided
0.020	0.0136	0.0340	0.0216	0.0082	0.0544	0.0154
0.040	0.0299	0.0539	0.0422	0.0209	0.0832	0.0370
0.060	0.0510	0.0741	0.0642	0.0350	0.1092	0.0599
0.080	0.0713	0.0914	0.0852	0.0509	0.1334	0.0809
0.100	0.0923	0.1094	0.1053	0.0692	0.1592	0.1045

b

Size of test	One-sided test				Two-sided test			
	$H_{LL}$	$H_L$	$H_R$	$H_{RR}$	$H_{LL}$	$H_L$	$H_R$	$H_{RR}$
Generalized rank test								
0.020	0.579	0.175	0.194	0.572	0.550	0.157	0.063	0.332
0.040	0.690	0.253	0.278	0.673	0.643	0.215	0.129	0.464
0.060	0.763	0.325	0.349	0.740	0.699	0.262	0.189	0.561
0.080	0.806	0.377	0.395	0.782	0.737	0.300	0.235	0.620
0.100	0.837	0.426	0.440	0.815	0.766	0.330	0.278	0.668
Supremum type test								
0.020	0.626	0.188	0.214	0.644	0.619	0.183	0.023	0.199
0.040	0.740	0.281	0.303	0.746	0.725	0.267	0.068	0.376
0.060	0.798	0.347	0.376	0.808	0.780	0.326	0.121	0.487
0.080	0.842	0.406	0.433	0.848	0.814	0.370	0.165	0.565
0.100	0.874	0.459	0.486	0.878	0.845	0.411	0.212	0.633

c

Table 6.4: Tests based on stochastic integral type 11 (no estimation) and  $n = 25$ . No censoring.

a: description stochastic integral;

b: critical points asymptotic P-values;

c: simulated power generalized rank and supremum type tests.



	$H_{LL}$	$H_L$	$H_0$	$H_R$	$H_{RR}$
mean $Q_n(\infty; v_0)$	-2.6880	-1.2767	0.0009	1.1440	2.1442
st.dev. $Q_n(\infty; v_0)$	1.1637	1.0741	1.0096	0.9064	0.8265
skewness $Q_n(\infty; v_0)$	-0.1545	-0.2768	-0.3440	-0.3658	-0.3906
kurtosis $Q_n(\infty; v_0)$	0.0754	0.0255	0.0323	0.2722	0.2386

a

Size of test	Generalized rank test			Supremum type test		
	Left-Sided	Right-Sided	Two-Sided	Left-Sided	Right-Sided	Two-Sided
0.010	0.0054	0.0205	0.0091	0.0041	0.0290	0.0077
0.020	0.0124	0.0320	0.0195	0.0096	0.0470	0.0172
0.030	0.0205	0.0431	0.0295	0.0156	0.0592	0.0272
0.040	0.0290	0.0520	0.0411	0.0226	0.0699	0.0365
0.050	0.0385	0.0612	0.0522	0.0304	0.0818	0.0483

b

Size of test	One-sided test				Two-sided test			
	$H_{LL}$	$H_L$	$H_R$	$H_{RR}$	$H_{LL}$	$H_L$	$H_R$	$H_{RR}$
Generalized rank test								
0.010	0.533	0.121	0.160	0.574	0.514	0.111	0.040	0.303
0.020	0.633	0.183	0.227	0.657	0.601	0.164	0.087	0.435
0.030	0.701	0.231	0.275	0.711	0.655	0.198	0.122	0.510
0.040	0.746	0.271	0.310	0.745	0.701	0.232	0.162	0.575
0.050	0.782	0.309	0.345	0.773	0.733	0.258	0.196	0.620
Supremum type test								
0.010	0.599	0.145	0.179	0.633	0.592	0.141	0.024	0.243
0.020	0.697	0.214	0.261	0.733	0.684	0.204	0.056	0.385
0.030	0.758	0.262	0.308	0.777	0.741	0.249	0.091	0.479
0.040	0.801	0.309	0.345	0.808	0.777	0.282	0.118	0.539
0.050	0.832	0.351	0.381	0.836	0.808	0.318	0.153	0.595

c

Table 6.5: Tests based on stochastic integral type 11 (no estimation) and  $n = 50$ . No censoring.

a: description stochastic integral;

b: critical points asymptotic P-values;

c: simulated power generalized rank and supremum type tests.

	$H_{LL}$	$H_L$	$H_0$	$H_R$	$H_{RR}$
mean $Q_n(\infty; v_0)$	-2.8722	-1.3656	0.0048	1.2636	2.3894
st.dev. $Q_n(\infty; v_0)$	1.1257	1.0725	1.0015	0.9377	0.8719
skewness $Q_n(\infty; v_0)$	-0.1833	-0.0575	-0.1562	-0.1560	-0.3505
kurtosis $Q_n(\infty; v_0)$	0.1006	-0.0101	0.1590	0.0286	0.0881

a

Size of test	Generalized rank test			Supremum type test		
	Left-Sided	Right-Sided	Two-Sided	Left-Sided	Right-Sided	Two-Sided
0.005	0.0024	0.0084	0.0038	0.0018	0.0106	0.0033
0.010	0.0061	0.0142	0.0091	0.0050	0.0208	0.0089
0.015	0.0097	0.0183	0.0137	0.0082	0.0275	0.0124
0.020	0.0153	0.0238	0.0185	0.0119	0.0319	0.0175
0.025	0.0208	0.0293	0.0236	0.0167	0.0382	0.0229

b

Size of test	One-sided test				Two-sided test			
	$H_{LL}$	$H_L$	$H_R$	$H_{RR}$	$H_{LL}$	$H_L$	$H_R$	$H_{RR}$
	Generalized rank test							
0.005	0.506	0.089	0.111	0.512	0.483	0.080	0.032	0.293
0.010	0.617	0.146	0.161	0.605	0.579	0.126	0.072	0.417
0.015	0.676	0.181	0.192	0.653	0.631	0.154	0.098	0.482
0.020	0.734	0.226	0.228	0.697	0.670	0.177	0.119	0.529
0.025	0.771	0.258	0.256	0.730	0.701	0.200	0.143	0.571
	Supremum type test							
0.005	0.562	0.104	0.120	0.576	0.559	0.101	0.024	0.271
0.010	0.685	0.172	0.193	0.692	0.672	0.162	0.057	0.424
0.015	0.747	0.213	0.233	0.741	0.712	0.188	0.079	0.480
0.020	0.790	0.251	0.258	0.764	0.754	0.219	0.104	0.541
0.025	0.825	0.288	0.291	0.793	0.785	0.246	0.128	0.589

c

Table 6.6: Tests based on stochastic integral type 11 (no estimation) and  $n = 100$ . No censoring.

a: description stochastic integral;

b: critical points asymptotic P-values;

c: simulated power generalized rank and supremum type tests.

	$H_{LL}$	$H_L$	$H_0$	$H_R$	$H_{RR}$
mean $Q_n(\infty; v_0)$	-1.9871	-0.9820	0.1001	1.2910	2.5929
st.dev. $Q_n(\infty; v_0)$	0.8302	0.9106	1.0119	1.1623	1.3168
skewness $Q_n(\infty; v_0)$	0.1902	0.1855	0.2282	0.2734	0.3854
kurtosis $Q_n(\infty; v_0)$	0.1021	0.0295	0.1244	0.0630	0.1389

a

Size of test	Generalized rank test			Supremum type test		
	Left-Sided	Right-Sided	Two-Sided	Left-Sided	Right-Sided	Two-Sided
0.020	0.0328	0.0110	0.0178	0.0258	0.0172	0.0217
0.040	0.0543	0.0256	0.0377	0.0459	0.0378	0.0430
0.060	0.0776	0.0433	0.0563	0.0658	0.0596	0.0632
0.080	0.0989	0.0599	0.0774	0.0821	0.0849	0.0845
0.100	0.1194	0.0783	0.0966	0.1024	0.1084	0.1050

b

Size of test	One-sided test				Two-sided test			
	$H_{LL}$	$H_L$	$H_R$	$H_{RR}$	$H_{LL}$	$H_L$	$H_R$	$H_{RR}$
Generalized rank test								
0.020	0.580	0.176	0.194	0.570	0.329	0.058	0.180	0.549
0.040	0.689	0.253	0.278	0.673	0.463	0.112	0.244	0.635
0.060	0.762	0.323	0.348	0.740	0.546	0.156	0.291	0.686
0.080	0.806	0.377	0.396	0.781	0.618	0.201	0.334	0.727
0.100	0.837	0.427	0.440	0.815	0.666	0.236	0.368	0.753
Supremum type test								
0.020	0.624	0.185	0.213	0.632	0.446	0.093	0.172	0.573
0.040	0.737	0.280	0.300	0.737	0.585	0.162	0.236	0.663
0.060	0.801	0.353	0.370	0.799	0.665	0.215	0.278	0.714
0.080	0.838	0.404	0.433	0.845	0.722	0.267	0.318	0.751
0.100	0.873	0.459	0.478	0.874	0.764	0.307	0.352	0.781

c

Table 6.7: Tests based on stochastic integral type 21 (no estimation) and  $n = 25$ . No censoring.

a: description stochastic integral;

b: critical points asymptotic P-values;

c: simulated power generalized rank and supremum type tests.

	$H_{LL}$	$H_L$	$H_0$	$H_R$	$H_{RR}$
mean $Q_n(\infty; v_0)$	-2.2409	-1.1183	0.0731	1.3365	2.6797
st.dev. $Q_n(\infty; v_0)$	0.8588	0.9193	1.0127	1.0923	1.2178
skewness $Q_n(\infty; v_0)$	0.1778	0.0907	0.0592	0.1204	0.1574
kurtosis $Q_n(\infty; v_0)$	0.0927	-0.0266	-0.0785	0.0741	0.0863

a

Size of test	Generalized rank test			Supremum type test		
	Left-Sided	Right-Sided	Two-Sided	Left-Sided	Right-Sided	Two-Sided
0.010	0.0145	0.0078	0.0104	0.0133	0.0104	0.0115
0.020	0.0255	0.0155	0.0209	0.0229	0.0220	0.0234
0.030	0.0360	0.0244	0.0302	0.0325	0.0312	0.0352
0.040	0.0462	0.0320	0.0397	0.0412	0.0407	0.0448
0.050	0.0566	0.0404	0.0500	0.0510	0.0515	0.0545

b

Size of test	One-sided test				Two-sided test			
	$H_{LL}$	$H_L$	$H_R$	$H_{RR}$	$H_{LL}$	$H_L$	$H_R$	$H_{RR}$
	Generalized rank test							
0.010	0.533	0.122	0.161	0.576	0.360	0.054	0.132	0.529
0.020	0.635	0.184	0.226	0.657	0.478	0.093	0.187	0.611
0.030	0.702	0.232	0.275	0.711	0.542	0.126	0.225	0.653
0.040	0.747	0.271	0.310	0.745	0.588	0.156	0.252	0.687
0.050	0.781	0.309	0.346	0.773	0.630	0.182	0.280	0.715
	Supremum type test							
0.010	0.603	0.148	0.177	0.628	0.457	0.079	0.128	0.558
0.020	0.700	0.216	0.260	0.725	0.580	0.136	0.190	0.645
0.030	0.761	0.268	0.303	0.771	0.653	0.182	0.232	0.699
0.040	0.802	0.312	0.342	0.805	0.697	0.213	0.263	0.727
0.050	0.833	0.354	0.382	0.832	0.730	0.241	0.286	0.753

c

Table 6.8: Tests based on stochastic integral type 21 (no estimation) and  $n = 50$ . No censoring.

a: description stochastic integral;

b: critical points asymptotic P-values;

c: simulated power generalized rank and supremum type tests.

	$H_{LL}$	$H_L$	$H_0$	$H_R$	$H_{RR}$
mean $Q_n(\infty; \nu_0)$	-2.4953	-1.2375	0.0551	1.4118	2.8098
st.dev. $Q_n(\infty; \nu_0)$	0.8843	0.9496	1.0046	1.0812	1.1612
skewness $Q_n(\infty; \nu_0)$	0.0675	0.2184	0.1538	0.1735	0.0019
kurtosis $Q_n(\infty; \nu_0)$	0.0828	0.0387	0.1109	0.0353	0.0139

a

Size of test	Generalized rank test			Supremum type test		
	Left-Sided	Right-Sided	Two-Sided	Left-Sided	Right-Sided	Two-Sided
0.005	0.0064	0.0031	0.0036	0.0060	0.0039	0.0038
0.010	0.0125	0.0065	0.0083	0.0117	0.0090	0.0095
0.015	0.0177	0.0094	0.0131	0.0166	0.0135	0.0157
0.020	0.0251	0.0135	0.0169	0.0220	0.0172	0.0209
0.025	0.0317	0.0176	0.0215	0.0283	0.0223	0.0254

b

Size of test	One-sided test				Two-sided test			
	$H_{LL}$	$H_L$	$H_R$	$H_{RR}$	$H_{LL}$	$H_L$	$H_R$	$H_{RR}$
	Generalized rank test							
0.005	0.509	0.091	0.112	0.514	0.320	0.036	0.089	0.457
0.010	0.615	0.146	0.160	0.602	0.440	0.067	0.130	0.547
0.015	0.676	0.181	0.192	0.653	0.513	0.092	0.161	0.604
0.020	0.735	0.227	0.229	0.697	0.553	0.112	0.183	0.639
0.025	0.771	0.258	0.255	0.729	0.591	0.132	0.204	0.669
	Supremum type test							
0.005	0.583	0.112	0.124	0.580	0.400	0.049	0.087	0.494
0.010	0.689	0.173	0.188	0.683	0.547	0.094	0.136	0.604
0.015	0.747	0.213	0.225	0.731	0.623	0.135	0.176	0.668
0.020	0.791	0.253	0.256	0.762	0.671	0.161	0.200	0.702
0.025	0.827	0.291	0.290	0.791	0.702	0.182	0.219	0.725

c

Table 6.9: Tests based on stochastic integral type 21 (no estimation) and  $n = 100$ . No censoring.

a: description stochastic integral;

b: critical points asymptotic P-values;

c: simulated power generalized rank and supremum type tests.

	$H_{LL}$	$H_L$	$H_0$	$H_R$	$H_{RR}$
mean $Q_n(\infty; v_0)$	-2.4705	-1.2552	-0.0056	1.2677	2.4906
st.dev. $Q_n(\infty; v_0)$	0.9437	0.9867	0.9935	0.9986	0.9411
skewness $Q_n(\infty; v_0)$	0.1673	0.0898	-0.0437	-0.0476	-0.0150
kurtosis $Q_n(\infty; v_0)$	-0.0295	-0.0596	0.0041	-0.0771	-0.1089

a

Size of test	Generalized rank test			Supremum type test		
	Left-Sided	Right-Sided	Two-Sided	Left-Sided	Right-Sided	Two-Sided
0.020	0.0205	0.0202	0.0213	0.0201	0.0245	0.0231
0.040	0.0409	0.0420	0.0407	0.0422	0.0484	0.0441
0.060	0.0605	0.0607	0.0619	0.0624	0.0733	0.0680
0.080	0.0827	0.0830	0.0826	0.0798	0.0993	0.0918
0.100	0.1018	0.1041	0.1023	0.1007	0.1214	0.1123

b

Size of test	One-sided test				Two-sided test			
	$H_{LL}$	$H_L$	$H_R$	$H_{RR}$	$H_{LL}$	$H_L$	$H_R$	$H_{RR}$
	Generalized rank test							
0.020	0.679	0.216	0.223	0.681	0.576	0.142	0.152	0.582
0.040	0.783	0.316	0.329	0.793	0.678	0.215	0.224	0.682
0.060	0.836	0.388	0.394	0.840	0.740	0.273	0.283	0.746
0.080	0.876	0.452	0.458	0.879	0.783	0.319	0.328	0.791
0.100	0.899	0.497	0.507	0.902	0.814	0.359	0.363	0.820
	Supremum type test							
0.020	0.634	0.194	0.217	0.675	0.546	0.139	0.135	0.557
0.040	0.746	0.299	0.314	0.780	0.648	0.207	0.206	0.660
0.060	0.800	0.365	0.391	0.840	0.716	0.266	0.264	0.727
0.080	0.834	0.413	0.454	0.875	0.758	0.316	0.307	0.771
0.100	0.866	0.466	0.498	0.894	0.786	0.348	0.343	0.802

c

Table 6.10: Tests based on stochastic integral type 12 (no estimation) and  $n = 25$ . No censoring.

a: description stochastic integral;

b: critical points asymptotic P-values;

c: simulated power generalized rank and supremum type tests.

	$H_{LL}$	$H_L$	$H_0$	$H_R$	$H_{RR}$
mean $Q_n(\infty; v_0)$	-2.7531	-1.4008	0.0090	1.3952	2.7374
st.dev. $Q_n(\infty; v_0)$	0.9678	0.9949	1.0041	0.9878	0.9591
skewness $Q_n(\infty; v_0)$	0.0421	-0.0946	-0.0353	-0.0335	-0.0963
kurtosis $Q_n(\infty; v_0)$	-0.0557	-0.0788	-0.1121	-0.0061	0.0510

a

Size of test	Generalized rank test			Supremum type test		
	Left-Sided	Right-Sided	Two-Sided	Left-Sided	Right-Sided	Two-Sided
0.010	0.0107	0.0117	0.0125	0.0099	0.0117	0.0130
0.020	0.0187	0.0223	0.0229	0.0199	0.0237	0.0220
0.030	0.0282	0.0318	0.0313	0.0284	0.0343	0.0324
0.040	0.0367	0.0415	0.0404	0.0376	0.0430	0.0434
0.050	0.0473	0.0514	0.0498	0.0477	0.0529	0.0518

b

Size of test	One-sided test				Two-sided test			
	$H_{LL}$	$H_L$	$H_R$	$H_{RR}$	$H_{LL}$	$H_L$	$H_R$	$H_{RR}$
Generalized rank test								
0.010	0.678	0.186	0.189	0.688	0.599	0.137	0.132	0.601
0.020	0.755	0.250	0.271	0.777	0.688	0.192	0.187	0.686
0.030	0.810	0.305	0.325	0.819	0.731	0.227	0.222	0.730
0.040	0.840	0.349	0.371	0.851	0.767	0.260	0.258	0.765
0.050	0.869	0.392	0.409	0.874	0.794	0.288	0.286	0.790
Supremum type test								
0.010	0.628	0.164	0.172	0.661	0.569	0.131	0.121	0.578
0.020	0.729	0.237	0.253	0.759	0.644	0.173	0.166	0.652
0.030	0.776	0.287	0.306	0.805	0.698	0.212	0.208	0.707
0.040	0.810	0.335	0.343	0.830	0.742	0.248	0.242	0.747
0.050	0.841	0.376	0.380	0.855	0.766	0.273	0.265	0.771

c

Table 6.11: Tests based on stochastic integral type 12 (no estimation) and  $n = 50$ . No censoring.

a: description stochastic integral;

b: critical points asymptotic P-values;

c: simulated power generalized rank and supremum type tests.

	$H_{LL}$	$H_L$	$H_0$	$H_R$	$H_{RR}$
mean $Q_n(\infty; v_0)$	-3.0270	-1.5210	0.0066	1.5154	2.9940
st.dev. $Q_n(\infty; v_0)$	0.9825	1.0059	0.9934	1.0063	0.9878
skewness $Q_n(\infty; v_0)$	0.0169	0.1574	0.0199	0.0238	-0.1805
kurtosis $Q_n(\infty; v_0)$	0.0282	0.0133	0.0289	0.0087	-0.0607

a

Size of test	Generalized rank test			Supremum type test		
	Left-Sided	Right-Sided	Two-Sided	Left-Sided	Right-Sided	Two-Sided
0.005	0.0042	0.0055	0.0042	0.0042	0.0057	0.0043
0.010	0.0110	0.0109	0.0092	0.0101	0.0121	0.0099
0.015	0.0168	0.0160	0.0150	0.0172	0.0174	0.0159
0.020	0.0211	0.0213	0.0219	0.0230	0.0236	0.0230
0.025	0.0261	0.0257	0.0282	0.0278	0.0276	0.0286

b

Size of test	One-sided test				Two-sided test			
	$H_{LL}$	$H_L$	$H_R$	$H_{RR}$	$H_{LL}$	$H_L$	$H_R$	$H_{RR}$
	Generalized rank test							
0.005	0.660	0.135	0.155	0.676	0.565	0.090	0.090	0.563
0.010	0.777	0.223	0.220	0.759	0.670	0.141	0.141	0.655
0.015	0.823	0.276	0.265	0.801	0.732	0.182	0.183	0.718
0.020	0.845	0.303	0.302	0.832	0.777	0.222	0.221	0.760
0.025	0.864	0.334	0.332	0.853	0.805	0.253	0.248	0.788
	Supremum type test							
0.005	0.626	0.124	0.143	0.660	0.541	0.088	0.084	0.542
0.010	0.739	0.199	0.214	0.752	0.649	0.137	0.134	0.644
0.015	0.798	0.259	0.254	0.790	0.708	0.176	0.172	0.702
0.020	0.829	0.301	0.293	0.824	0.754	0.212	0.209	0.746
0.025	0.846	0.327	0.316	0.840	0.777	0.237	0.233	0.770

c

Table 6.12: Tests based on stochastic integral type 12 (no estimation) and  $n = 100$ . No censoring.

a: description stochastic integral;

b: critical points asymptotic P-values;

c: simulated power generalized rank and supremum type tests.



	$H_{LL}$	$H_L$	$H_0$	$H_R$	$H_{RR}$
mean $Q_n(\infty; v_0)$	-2.6827	-1.3144	-0.0069	1.2127	2.2095
st.dev. $Q_n(\infty; v_0)$	0.9600	0.9889	0.9949	0.9891	0.9857
skewness $Q_n(\infty; v_0)$	0.1601	-0.0420	0.1245	0.1567	-0.0424
kurtosis $Q_n(\infty; v_0)$	0.0668	0.0678	-0.0579	-0.0133	-0.0032

a

Size of test	Generalized rank test			Supremum type test		
	Left-Sided	Right-Sided	Two-Sided	Left-Sided	Right-Sided	Two-Sided
0.020	0.0244	0.0195	0.0218	0.0269	0.0229	0.0255
0.040	0.0435	0.0401	0.0435	0.0463	0.0464	0.0498
0.060	0.0612	0.0602	0.0637	0.0658	0.0693	0.0710
0.080	0.0806	0.0779	0.0836	0.0853	0.0926	0.0921
0.100	0.0986	0.0988	0.1024	0.1062	0.1154	0.1150

b

Size of test	One-sided test				Two-sided test			
	$H_{LL}$	$H_L$	$H_R$	$H_{RR}$	$H_{LL}$	$H_L$	$H_R$	$H_{RR}$
	Generalized rank test							
0.020	0.776	0.257	0.197	0.560	0.665	0.160	0.138	0.466
0.040	0.846	0.344	0.295	0.679	0.762	0.240	0.208	0.580
0.060	0.882	0.410	0.366	0.740	0.809	0.294	0.259	0.642
0.080	0.906	0.469	0.417	0.781	0.841	0.340	0.302	0.684
0.100	0.923	0.514	0.471	0.821	0.864	0.375	0.337	0.714
	Supremum type test							
0.020	0.756	0.245	0.183	0.535	0.651	0.160	0.128	0.441
0.040	0.823	0.331	0.276	0.650	0.745	0.236	0.193	0.549
0.060	0.862	0.396	0.346	0.716	0.792	0.287	0.239	0.604
0.080	0.889	0.451	0.400	0.760	0.823	0.332	0.275	0.649
0.100	0.909	0.500	0.449	0.794	0.847	0.373	0.312	0.685

c

Table 6.13: Tests based on stochastic integral type 12 (no estimation) and  $n = 25$ .

Standard exponential censoring.

a: description stochastic integral;

b: critical points asymptotic P-values;

c: simulated power generalized rank and supremum type tests.

	$H_{LL}$	$H_L$	$H_0$	$H_R$	$H_{RR}$
mean $Q_n(\infty; v_0)$	-2.9356	-1.4346	0.0160	1.3357	2.5290
st.dev. $Q_n(\infty; v_0)$	0.9731	0.9889	0.9887	0.9866	0.9940
skewness $Q_n(\infty; v_0)$	0.1730	0.0761	-0.0530	0.0011	0.0696
kurtosis $Q_n(\infty; v_0)$	-0.0120	0.0398	-0.0368	-0.0892	-0.0176

a

Size of test	Generalized rank test			Supremum type test		
	Left-Sided	Right-Sided	Two-Sided	Left-Sided	Right-Sided	Two-Sided
0.010	0.0133	0.0100	0.0116	0.0138	0.0115	0.0140
0.020	0.0241	0.0196	0.0233	0.0261	0.0216	0.0252
0.030	0.0346	0.0285	0.0336	0.0357	0.0314	0.0362
0.040	0.0457	0.0384	0.0435	0.0481	0.0416	0.0466
0.050	0.0547	0.0492	0.0535	0.0572	0.0539	0.0574

b

Size of test	One-sided test				Two-sided test			
	$H_{LL}$	$H_L$	$H_R$	$H_{RR}$	$H_{LL}$	$H_L$	$H_R$	$H_{RR}$
	Generalized rank test							
0.010	0.771	0.214	0.158	0.576	0.671	0.134	0.115	0.499
0.020	0.837	0.294	0.229	0.676	0.755	0.200	0.172	0.601
0.030	0.872	0.353	0.283	0.731	0.796	0.242	0.212	0.654
0.040	0.898	0.403	0.333	0.778	0.825	0.277	0.243	0.691
0.050	0.912	0.435	0.379	0.814	0.848	0.310	0.275	0.722
	Supremum type test							
0.010	0.745	0.202	0.148	0.558	0.664	0.138	0.113	0.491
0.020	0.819	0.284	0.216	0.652	0.735	0.194	0.157	0.571
0.030	0.851	0.332	0.264	0.708	0.777	0.233	0.195	0.627
0.040	0.881	0.387	0.306	0.748	0.807	0.268	0.225	0.665
0.050	0.895	0.418	0.351	0.787	0.828	0.298	0.252	0.695

c

Table 6.14: Tests based on stochastic integral type 12 (no estimation) and  $n = 50$ . Standard exponential censoring.

a: description stochastic integral;

b: critical points asymptotic P-values;

c: simulated power generalized rank and supremum type tests.

	$H_{LL}$	$H_L$	$H_0$	$H_R$	$H_{RR}$
mean $Q_n(\infty; v_0)$	-3.1813	-1.5650	-0.0012	1.4840	2.8180
st.dev. $Q_n(\infty; v_0)$	0.9902	1.0035	0.9990	0.9930	0.9735
skewness $Q_n(\infty; v_0)$	0.0615	-0.0067	0.0172	0.0445	0.0627
kurtosis $Q_n(\infty; v_0)$	0.0272	0.0634	-0.0628	-0.0304	-0.1104

a

Size of test	Generalized rank test			Supremum type test		
	Left-Sided	Right-Sided	Two-Sided	Left-Sided	Right-Sided	Two-Sided
0.005	0.0062	0.0050	0.0055	0.0059	0.0056	0.0061
0.010	0.0108	0.0096	0.0112	0.0116	0.0098	0.0116
0.015	0.0155	0.0139	0.0157	0.0177	0.0152	0.0167
0.020	0.0210	0.0204	0.0205	0.0225	0.0206	0.0214
0.025	0.0263	0.0252	0.0249	0.0267	0.0268	0.0274

b

Size of test	One-sided test				Two-sided test			
	$H_{LL}$	$H_L$	$H_R$	$H_{RR}$	$H_{LL}$	$H_L$	$H_R$	$H_{RR}$
	Generalized rank test							
0.005	0.753	0.175	0.134	0.599	0.661	0.115	0.096	0.515
0.010	0.813	0.232	0.193	0.685	0.741	0.167	0.144	0.613
0.015	0.847	0.277	0.234	0.731	0.781	0.198	0.173	0.660
0.020	0.875	0.315	0.286	0.779	0.807	0.227	0.200	0.692
0.025	0.893	0.349	0.317	0.807	0.826	0.251	0.221	0.718
	Supremum type test							
0.005	0.725	0.161	0.128	0.575	0.646	0.115	0.091	0.498
0.010	0.796	0.227	0.176	0.655	0.723	0.159	0.130	0.581
0.015	0.838	0.279	0.225	0.714	0.762	0.193	0.161	0.633
0.020	0.862	0.308	0.262	0.751	0.788	0.219	0.186	0.668
0.025	0.876	0.335	0.299	0.785	0.813	0.247	0.213	0.700

c

Table 6.15: Tests based on stochastic integral type 12 (no estimation) and  $n = 100$ . Standard exponential censoring.

a: description stochastic integral;

b: critical points asymptotic P-values;

c: simulated power generalized rank and supremum type tests.

	$H_{LL}$	$H_L$	$H_0$	$H_R$	$H_{RR}$
mean $Q_n(\infty; v_0)$	-2.2360	-1.1624	0.0380	1.4089	2.9266
st.dev. $Q_n(\infty; v_0)$	0.8033	0.9057	1.0068	1.1480	1.2667
skewness $Q_n(\infty; v_0)$	0.3294	0.3004	0.2372	0.2789	0.3802
kurtosis $Q_n(\infty; v_0)$	0.1695	0.1496	0.2227	0.1071	0.1084

a

Size of test	Generalized rank test			Supremum type test		
	Left-Sided	Right-Sided	Two-Sided	Left-Sided	Right-Sided	Two-Sided
0.020	0.0295	0.0115	0.0172	0.0316	0.0129	0.0193
0.040	0.0519	0.0306	0.0386	0.0577	0.0318	0.0425
0.060	0.0721	0.0479	0.0600	0.0790	0.0541	0.0634
0.080	0.0943	0.0695	0.0801	0.0981	0.0795	0.0876
0.100	0.1140	0.0908	0.0995	0.1192	0.1007	0.1112

b

Size of test	One-sided test				Two-sided test			
	$H_{LL}$	$H_L$	$H_R$	$H_{RR}$	$H_{LL}$	$H_L$	$H_R$	$H_{RR}$
Generalized rank test								
0.020	0.680	0.217	0.222	0.682	0.448	0.083	0.196	0.648
0.040	0.783	0.316	0.331	0.796	0.597	0.156	0.276	0.742
0.060	0.837	0.388	0.395	0.842	0.684	0.222	0.330	0.794
0.080	0.876	0.452	0.458	0.879	0.736	0.269	0.369	0.825
0.100	0.900	0.498	0.508	0.903	0.777	0.312	0.403	0.846
Supremum type test								
0.020	0.631	0.193	0.219	0.679	0.410	0.074	0.194	0.647
0.040	0.744	0.297	0.316	0.784	0.553	0.142	0.272	0.737
0.060	0.798	0.363	0.393	0.842	0.632	0.195	0.316	0.783
0.080	0.834	0.412	0.458	0.876	0.695	0.248	0.362	0.817
0.100	0.865	0.463	0.499	0.895	0.738	0.293	0.399	0.845

c

Table 6.16: Tests based on stochastic integral type 22 (no estimation) and  $n = 25$ . No censoring.

a: description stochastic integral;

b: critical points asymptotic P-values;

c: simulated power generalized rank and supremum type tests.

	$H_{LL}$	$H_L$	$H_0$	$H_R$	$H_{RR}$
mean $Q_n(\infty; v_0)$	-2.5403	-1.3217	0.0401	1.5004	3.0692
st.dev. $Q_n(\infty; v_0)$	0.8433	0.9244	1.0094	1.0916	1.1856
skewness $Q_n(\infty; v_0)$	0.1642	0.0602	0.1406	0.1864	0.1680
kurtosis $Q_n(\infty; v_0)$	0.0072	-0.0212	-0.0447	0.0576	0.1438

a

Size of test	Generalized rank test			Supremum type test		
	Left-Sided	Right-Sided	Two-Sided	Left-Sided	Right-Sided	Two-Sided
0.010	0.0157	0.0073	0.0113	0.0158	0.0066	0.0108
0.020	0.0249	0.0156	0.0213	0.0280	0.0154	0.0210
0.030	0.0349	0.0240	0.0313	0.0378	0.0243	0.0312
0.040	0.0447	0.0334	0.0395	0.0483	0.0318	0.0412
0.050	0.0553	0.0426	0.0492	0.0591	0.0411	0.0514

b

Size of test	One-sided test				Two-sided test			
	$H_{LL}$	$H_L$	$H_R$	$H_{RR}$	$H_{LL}$	$H_L$	$H_R$	$H_{RR}$
	Generalized rank test							
0.010	0.682	0.188	0.190	0.691	0.511	0.094	0.170	0.663
0.020	0.756	0.251	0.269	0.777	0.614	0.146	0.226	0.736
0.030	0.808	0.303	0.324	0.820	0.682	0.187	0.269	0.778
0.040	0.842	0.351	0.373	0.852	0.719	0.216	0.296	0.800
0.050	0.869	0.392	0.409	0.875	0.754	0.250	0.327	0.821
	Supremum type test							
0.010	0.630	0.165	0.175	0.666	0.453	0.080	0.161	0.645
0.020	0.727	0.236	0.254	0.760	0.561	0.126	0.217	0.719
0.030	0.776	0.286	0.307	0.807	0.628	0.164	0.256	0.762
0.040	0.810	0.334	0.344	0.832	0.676	0.195	0.287	0.791
0.050	0.840	0.374	0.382	0.857	0.713	0.224	0.315	0.811

c

Table 6.17: Tests based on stochastic integral type 22 (no estimation) and  $n = 50$ . No censoring.

a: description stochastic integral;

b: critical points asymptotic P-values;

c: simulated power generalized rank and supremum type tests.

	$H_{LL}$	$H_L$	$H_0$	$H_R$	$H_{RR}$
mean $Q_n(\infty; v_0)$	-2.8397	-1.4559	0.0280	1.5959	3.2537
st.dev. $Q_n(\infty; v_0)$	0.8787	0.9488	0.9965	1.0835	1.1513
skewness $Q_n(\infty; v_0)$	0.1150	0.2746	0.1530	0.1764	-0.0241
kurtosis $Q_n(\infty; v_0)$	0.0801	0.0891	0.0922	0.0397	-0.0521

a

Size of test	Generalized rank test			Supremum type test		
	Left-Sided	Right-Sided	Two-Sided	Left-Sided	Right-Sided	Two-Sided
0.005	0.0062	0.0034	0.0044	0.0066	0.0031	0.0049
0.010	0.0145	0.0079	0.0096	0.0140	0.0082	0.0097
0.015	0.0211	0.0123	0.0141	0.0225	0.0124	0.0154
0.020	0.0255	0.0169	0.0200	0.0295	0.0175	0.0202
0.025	0.0310	0.0211	0.0262	0.0346	0.0212	0.0260

b

Size of test	One-sided test				Two-sided test			
	$H_{LL}$	$H_L$	$H_R$	$H_{RR}$	$H_{LL}$	$H_L$	$H_R$	$H_{RR}$
	Generalized rank test							
0.005	0.661	0.135	0.153	0.675	0.503	0.069	0.125	0.631
0.010	0.779	0.224	0.221	0.762	0.620	0.113	0.179	0.714
0.015	0.825	0.276	0.267	0.804	0.679	0.147	0.212	0.752
0.020	0.845	0.302	0.303	0.834	0.730	0.180	0.244	0.785
0.025	0.865	0.335	0.334	0.854	0.766	0.211	0.274	0.810
	Supremum type test							
0.005	0.627	0.124	0.141	0.656	0.482	0.065	0.127	0.630
0.010	0.737	0.197	0.217	0.754	0.581	0.103	0.172	0.702
0.015	0.797	0.259	0.255	0.791	0.650	0.138	0.211	0.749
0.020	0.830	0.302	0.293	0.824	0.689	0.164	0.235	0.773
0.025	0.846	0.327	0.316	0.841	0.726	0.190	0.260	0.796

c

Table 6.18: Tests based on stochastic integral type 22 (no estimation) and  $n = 100$ . No censoring.

a: description stochastic integral;

b: critical points asymptotic P-values;

c: simulated power generalized rank and supremum type tests.

	$H_{LL}$	$H_L$	$H_0$	$H_R$	$H_{RR}$
mean $Q_n(\infty; v_0)$	-2.2593	-1.1703	0.0334	1.4153	2.9081
st.dev. $Q_n(\infty; v_0)$	0.7537	0.8685	1.0072	1.1883	1.4242
skewness $Q_n(\infty; v_0)$	0.3465	0.1826	0.3746	0.4447	0.2876
kurtosis $Q_n(\infty; v_0)$	0.3054	0.2065	0.1635	0.3483	0.2306

a

Size of test	Generalized rank test			Supremum type test		
	Left-Sided	Right-Sided	Two-Sided	Left-Sided	Right-Sided	Two-Sided
0.020	0.0328	0.0115	0.0183	0.0391	0.0128	0.0199
0.040	0.0533	0.0293	0.0413	0.0615	0.0321	0.0462
0.060	0.0734	0.0479	0.0620	0.0821	0.0511	0.0712
0.080	0.0919	0.0651	0.0813	0.1004	0.0745	0.0932
0.100	0.1095	0.0875	0.1011	0.1233	0.0973	0.1142

b

Size of test	One-sided test				Two-sided test			
	$H_{LL}$	$H_L$	$H_R$	$H_{RR}$	$H_{LL}$	$H_L$	$H_R$	$H_{RR}$
Generalized rank test								
0.020	0.725	0.224	0.225	0.656	0.469	0.076	0.207	0.633
0.040	0.811	0.316	0.327	0.750	0.636	0.155	0.288	0.714
0.060	0.860	0.385	0.400	0.805	0.714	0.216	0.334	0.756
0.080	0.891	0.443	0.448	0.838	0.766	0.264	0.375	0.786
0.100	0.910	0.490	0.500	0.867	0.802	0.307	0.409	0.811
Supremum type test								
0.020	0.694	0.209	0.224	0.653	0.412	0.062	0.202	0.629
0.040	0.779	0.292	0.323	0.748	0.586	0.137	0.282	0.713
0.060	0.826	0.359	0.386	0.794	0.673	0.195	0.337	0.757
0.080	0.857	0.409	0.446	0.832	0.727	0.240	0.374	0.785
0.100	0.884	0.463	0.491	0.860	0.764	0.280	0.404	0.805

c

Table 6.19: Tests based on stochastic integral type 22 (no estimation) and  $n = 25$ .

Standard exponential censoring.

a: description stochastic integral;

b: critical points asymptotic P-values;

c: simulated power generalized rank and supremum type tests.

	$H_{LL}$	$H_L$	$H_0$	$H_R$	$H_{RR}$
mean $Q_n(\infty; \nu_0)$	-2.5515	-1.3127	0.0446	1.4920	3.0873
st.dev. $Q_n(\infty; \nu_0)$	0.7966	0.8895	0.9965	1.1267	1.3034
skewness $Q_n(\infty; \nu_0)$	0.3045	0.2346	0.1233	0.1841	0.2629
kurtosis $Q_n(\infty; \nu_0)$	0.0985	0.1021	0.0337	0.0002	0.1047

a

Size of test	Generalized rank test			Supremum type test		
	Left-Sided	Right-Sided	Two-Sided	Left-Sided	Right-Sided	Two-Sided
0.010	0.0182	0.0059	0.0095	0.0199	0.0064	0.0096
0.020	0.0304	0.0139	0.0210	0.0331	0.0147	0.0223
0.030	0.0408	0.0221	0.0307	0.0462	0.0230	0.0334
0.040	0.0533	0.0313	0.0404	0.0586	0.0315	0.0438
0.050	0.0630	0.0414	0.0517	0.0694	0.0414	0.0551

b

Size of test	One-sided test				Two-sided test			
	$H_{LL}$	$H_L$	$H_R$	$H_{RR}$	$H_{LL}$	$H_L$	$H_R$	$H_{RR}$
	Generalized rank test							
0.010	0.724	0.192	0.179	0.656	0.494	0.070	0.163	0.633
0.020	0.805	0.271	0.259	0.746	0.637	0.127	0.228	0.715
0.030	0.845	0.324	0.314	0.796	0.698	0.170	0.269	0.756
0.040	0.879	0.380	0.365	0.828	0.742	0.206	0.302	0.787
0.050	0.896	0.415	0.404	0.855	0.780	0.242	0.337	0.811
	Supremum type test							
0.010	0.688	0.174	0.174	0.653	0.439	0.059	0.154	0.624
0.020	0.768	0.245	0.251	0.737	0.591	0.112	0.225	0.711
0.030	0.818	0.305	0.302	0.784	0.658	0.152	0.264	0.751
0.040	0.849	0.353	0.343	0.813	0.703	0.186	0.295	0.779
0.050	0.871	0.391	0.383	0.840	0.739	0.217	0.324	0.800

c

Table 6.20: Tests based on stochastic integral type 22 (no estimation) and  $n = 50$ . Standard exponential censoring.

a: description stochastic integral;

b: critical points asymptotic P-values;

c: simulated power generalized rank and supremum type tests.



	$H_{LL}$	$H_L$	$H_0$	$H_R$	$H_{RR}$
mean $Q_n(\infty; v_0)$	-2.8453	-1.4611	0.0189	1.6074	3.2586
st.dev. $Q_n(\infty; v_0)$	0.8423	0.9220	1.0016	1.0965	1.1892
skewness $Q_n(\infty; v_0)$	0.1730	0.1140	0.1342	0.1735	0.1851
kurtosis $Q_n(\infty; v_0)$	0.0830	0.1155	-0.0324	0.0143	-0.0617

a

Size of test	Generalized rank test			Supremum type test		
	Left-Sided	Right-Sided	Two-Sided	Left-Sided	Right-Sided	Two-Sided
0.005	0.0087	0.0034	0.0051	0.0091	0.0036	0.0059
0.010	0.0139	0.0071	0.0102	0.0161	0.0071	0.0101
0.015	0.0195	0.0107	0.0149	0.0231	0.0108	0.0156
0.020	0.0254	0.0165	0.0198	0.0282	0.0159	0.0201
0.025	0.0314	0.0207	0.0244	0.0329	0.0207	0.0263

b

Size of test	One-sided test				Two-sided test			
	$H_{LL}$	$H_L$	$H_R$	$H_{RR}$	$H_{LL}$	$H_L$	$H_R$	$H_{RR}$
	Generalized rank test							
0.005	0.714	0.158	0.157	0.670	0.530	0.070	0.138	0.642
0.010	0.781	0.213	0.217	0.743	0.638	0.114	0.189	0.710
0.015	0.823	0.261	0.257	0.781	0.693	0.144	0.222	0.748
0.020	0.853	0.300	0.309	0.825	0.734	0.172	0.248	0.773
0.025	0.876	0.332	0.338	0.845	0.762	0.198	0.274	0.794
	Supremum type test							
0.005	0.678	0.147	0.152	0.663	0.506	0.068	0.139	0.642
0.010	0.760	0.207	0.209	0.730	0.591	0.100	0.180	0.699
0.015	0.807	0.257	0.249	0.771	0.657	0.133	0.218	0.739
0.020	0.830	0.286	0.291	0.808	0.695	0.157	0.242	0.765
0.025	0.850	0.312	0.323	0.831	0.732	0.182	0.269	0.790

c

Table 6.21: Tests based on stochastic integral type 22 (no estimation) and  $n = 100$ . Standard exponential censoring.

a: description stochastic integral;

b: critical points asymptotic P-values;

c: simulated power generalized rank and supremum type tests.

Sample size	Type of Censoring	$H_{LL}$	$H_L$	$H_0$	$H_R$	$H_{RR}$
25	None	-1.7579	-0.8789	0.0000	0.8789	1.7579
25	Exp(1)	-3.0447	-1.5224	0.0000	1.5224	3.0447
50	None	-1.3703	-0.6852	0.0000	0.6852	1.3703
50	Exp(1)	-2.3735	-1.1867	0.0000	1.1867	2.3735
100	None	-1.0513	-0.5257	0.0000	0.5257	1.0513
100	Exp(1)	-1.8209	-0.9105	0.0000	0.9105	1.8209

Table 6.22: Values of  $\theta_n$ . The value of  $v_n$ ,  $v_0$ ,  $\theta_0$  and  $\rho$  are always equal to 0, 0, 0 and 1, respectively.

### 6.3 The composite null hypothesis

As in the previous section, the simulated samples are drawn from a distribution  $F(t; v_n, \theta_n)$  belonging to the family of Harrington and Fleming alternatives to the exponential distribution. The values of  $v_n$  and  $\rho$  are 0 and 1, respectively. However, the parameter of interest  $\theta_n$  varies in a different way with sample size:

$$\theta_n = c_H \sqrt{\frac{2 \log n}{n \{ \mu_{2\rho}(v_0) - (\mu_\rho(v_0))^2 / \mu_0(v_0) \}}}, \quad (6.8)$$

where  $v_0$  is equal to zero. Again  $c_H$  is chosen according to the five types of hypotheses  $H_{LL}$ ,  $H_L$ ,  $H_0$ ,  $H_R$  and  $H_{RR}$  under which simulation takes place; the respective choices of  $c_H$  are -1.0, -0.5, 0.0, 0.5 and 1.0, resulting in the values of  $\theta_n$  listed in Table 6.22. The asymptotic power of the generalized rank test based on stochastic integral 13 and maximum likelihood estimation is given in Table 6.3. For size  $1/n$  the power of a one-sided version of this test will under  $H_{RR}$  and  $H_{LL}$  tend to 0.5 as  $n$  tends to infinity.

#### 6.3.1 The maximum likelihood estimator

On the basis of Theorem 7 and its corollaries we expect that  $v^{(n)}$  has a distribution which is close to Gaussian if the sample size is sufficiently large. Moreover, under  $H_0$  the mean is close to zero and the variance should be near  $(nH^1(\infty; v_0, \theta_0))^{-1}$ .

As far as  $H_0$  concerns, in Table 6.23 we see that although the mean of  $v^{(n)}$  deviates from zero in uncensored samples, it tends to zero rather quickly [roughly at a rate  $n^{-1}$ ]. For censored samples the deviation is unnoticeable. The variance of  $v^{(n)}$  is in both tables as indicated.

	$H_{LL}$	$H_L$	$H_0$	$H_R$	$H_{RR}$
	Sample size 25; no censoring				
mean $v^{(n)}$	-0.7436	-0.3936	0.0177	0.5029	1.0580
st.dev. $v^{(n)}$	0.1331	0.1643	0.2002	0.2496	0.3153
skewness $v^{(n)}$	0.2820	0.2259	0.2756	0.1672	0.0561
kurtosis $v^{(n)}$	0.0179	0.0488	0.1580	0.0956	-0.0528
	Sample size 50; no censoring				
mean $v^{(n)}$	-0.6023	-0.3167	0.0101	0.3782	0.7834
st.dev. $v^{(n)}$	0.1016	0.1201	0.1411	0.1694	0.2021
skewness $v^{(n)}$	0.0718	0.2544	-0.0947	0.1701	0.1833
kurtosis $v^{(n)}$	0.0658	0.0818	0.0426	0.0462	0.0115
	Sample size 100; no censoring				
mean $v^{(n)}$	-0.4773	-0.2475	0.0044	0.2824	0.5787
st.dev. $v^{(n)}$	0.0766	0.0875	0.0995	0.1143	0.1300
skewness $v^{(n)}$	0.1303	-0.0761	0.0374	0.1051	0.0959
kurtosis $v^{(n)}$	-0.0133	-0.0021	-0.0002	0.0058	0.0374
	Sample size 25; standard exponential censoring				
mean $v^{(n)}$	-1.5431	-0.8943	-0.0015	1.1522	2.5095
st.dev. $v^{(n)}$	0.2363	0.2581	0.2950	0.3486	0.3997
skewness $v^{(n)}$	-0.5300	-0.2887	-0.1889	-0.2045	-0.1894
kurtosis $v^{(n)}$	0.8844	0.5535	0.2429	0.1699	0.2315
	Sample size 50; standard exponential censoring				
mean $v^{(n)}$	-1.2828	-0.7154	0.0009	0.8723	1.8736
st.dev. $v^{(n)}$	0.1669	0.1812	0.2025	0.2336	0.2721
skewness $v^{(n)}$	-0.2753	-0.2176	-0.1274	-0.0040	-0.1408
kurtosis $v^{(n)}$	0.1905	0.2161	0.1948	0.1749	0.0635
	Sample size 100; standard exponential censoring				
mean $v^{(n)}$	-1.0317	-0.5621	0.0002	0.6539	1.3898
st.dev. $v^{(n)}$	0.1221	0.1313	0.1425	0.1586	0.1809
skewness $v^{(n)}$	-0.2834	-0.0988	0.0171	-0.0144	0.1241
kurtosis $v^{(n)}$	0.2477	0.1269	0.0046	-0.0584	0.0962

Table 6.23: Description of the behavior of the maximum likelihood estimator.

### 6.3.2 Stochastic integral 12

We have already encountered stochastic integral 12 in discussing the simulation results for the simple null hypothesis. The inclusion of this stochastic integral in the simulations for the composite null hypothesis is intended to show the perils of plugging in estimators and subsequently carrying on as under the simple null hypothesis.

Since stochastic integral 12 is scaled for the simple null hypothesis, we do not have that  $a_R(v_0)$  and  $a_S(v_0)$  are equal to 1. Instead, we have  $a_R(v_0) = 4$  and  $a_S(v_0)$  is even larger. As a consequence, the computed asymptotic P-values are far too conservative [see Tables 6.24b, 6.25b and 6.26b].

The magnitude of the computed asymptotic P-values raised some difficulties with the storage of the simulation results. These were solved by choosing the interval width of the histogram of the asymptotic P-values differently, which unfortunately made the precision of the simulated power decrease.

If we are using critical values as given in Tables 6.24b, 6.25b and 6.26b, then Theorem 13 on page 67 yields that the generalized rank test is optimal. However, the supremum type test is not. It is clear from Tables 6.24c, 6.25c and 6.26c that a supremum type test is outdistanced by the corresponding generalized rank test.

### 6.3.3 Stochastic integral 13

Stochastic integral 13 is based on the weight process for known censoring distribution proposed in section 5.3. The quantities  $e_R(h, v_0)$  and  $e_S(h, v_0)$  are given by

$$e_R(h, v_0) = e_S(h, v_0) = \sqrt{\mu_{2\rho}(v_0) - (\mu_\rho(v_0))^2 / \mu_0(v_0)}. \quad (6.9)$$

If censoring is absent then both  $e_R(h, v_0)$  and  $e_S(h, v_0)$  are equal to  $1/12$ . If the censoring distribution is standard exponential they become  $1/36$ .

Since the generalized rank tests based on stochastic integrals 12 and 13 differ from each other by a multitude of  $M_n(\infty; v^{(n)}, \theta_0)$ , which is zero by the definition of the maximum likelihood estimator, their power should be about the same. The differences between the simulated power of generalized rank tests in Table 6.24c and Table 6.27c should be addressed to the inaccuracy of the simulated power mentioned in the discussion of stochastic integral 12. The same holds for Tables 6.25c and 6.28c, and Tables 6.26c and 6.29c.

The supremum type tests based on stochastic integral 13 perform better than those based on stochastic integral 12. The only exception is the two-sided supremum type test when applied to a situation in which  $\theta_n$  is negative.

The simulated power of the generalized rank test tends to be lower than the asymptotic power given in Table 6.3, especially for the smaller test sizes. This effect is stronger for samples where censoring is present.

### 6.3.4 Stochastic integral 23

The weight process for unknown censoring distribution proposed in section 5.3 leads to stochastic integral 23. For this stochastic integral  $e_R(h, v_0)$  and  $e_S(h, v_0)$  coincide with those for stochastic integral 13, and hence are given by (6.9).

On the whole, tests based on stochastic integral 23 seem to be more sensitive to negative values, and less sensitive to positive values than the corresponding tests based on stochastic integral 13. The difference in sensitivity is stronger for two-sided tests than for one-sided tests, for supremum type tests than for generalized rank tests, and for small samples than for large samples. In rather surprising contrast to two-sided tests, the simulated power of one-sided tests in uncensored samples remains relatively unaffected by the choice between the two stochastic integrals.

	$H_{LL}$	$H_L$	$H_0$	$H_R$	$H_{RR}$
mean $Q_n(\infty; v^{(n)})$	-1.0809	-0.6409	-0.0898	0.5314	1.1619
st.dev. $Q_n(\infty; v^{(n)})$	0.3097	0.3921	0.4905	0.6101	0.7482
skewness $Q_n(\infty; v^{(n)})$	0.4893	0.3543	0.3055	0.3904	0.3986
kurtosis $Q_n(\infty; v^{(n)})$	0.3068	0.0904	0.2030	0.1534	0.1028

a

Size of test	Generalized rank test			Supremum type test		
	Left-Sided	Right-Sided	Two-Sided	Left-Sided	Right-Sided	Two-Sided
0.020	0.1583	0.1524	0.2536	0.0666	0.0896	0.1000
0.040	0.1865	0.2070	0.3105	0.0963	0.1324	0.1533
0.060	0.2065	0.2416	0.3548	0.1207	0.1689	0.1887
0.080	0.2268	0.2686	0.3862	0.1435	0.1983	0.2158
0.100	0.2436	0.2914	0.4135	0.1641	0.2253	0.2504

b

Size of test	One-sided test				Two-sided test			
	$H_{LL}$	$H_L$	$H_R$	$H_{RR}$	$H_{LL}$	$H_L$	$H_R$	$H_{RR}$
	Generalized rank test							
0.020	0.625	0.182	0.206	0.553	0.450	0.092	0.161	0.491
0.040	0.743	0.276	0.305	0.661	0.610	0.174	0.213	0.560
0.060	0.810	0.346	0.371	0.717	0.709	0.247	0.253	0.606
0.080	0.861	0.412	0.420	0.757	0.767	0.299	0.283	0.636
0.100	0.893	0.470	0.465	0.786	0.810	0.348	0.311	0.662
	Supremum type test							
0.020	0.542	0.155	0.180	0.496	0.453	0.107	0.103	0.368
0.040	0.669	0.243	0.262	0.599	0.593	0.186	0.158	0.458
0.060	0.744	0.311	0.326	0.668	0.662	0.239	0.193	0.510
0.080	0.797	0.367	0.373	0.708	0.706	0.278	0.222	0.544
0.100	0.836	0.421	0.415	0.738	0.756	0.325	0.256	0.586

c

Table 6.24: Tests based on stochastic integral type 12 (maximum likelihood estimation) and  $n = 25$ . No censoring.

a: description stochastic integral;

b: critical points asymptotic P-values;

c: simulated power generalized rank and supremum type tests.

	$H_{LL}$	$H_L$	$H_0$	$H_R$	$H_{RR}$
mean $Q_n(\infty; v^{(n)})$	-1.2453	-0.7006	-0.0607	0.6449	1.3887
st.dev. $Q_n(\infty; v^{(n)})$	0.3464	0.4138	0.4950	0.5834	0.6955
skewness $Q_n(\infty; v^{(n)})$	0.3151	0.3780	0.2343	0.1073	0.0958
kurtosis $Q_n(\infty; v^{(n)})$	0.0730	0.1572	0.0186	-0.1256	0.0173

a

Size of test	Generalized rank test			Supremum type test		
	Left-Sided	Right-Sided	Two-Sided	Left-Sided	Right-Sided	Two-Sided
0.010	0.1283	0.1230	0.2050	0.0434	0.0580	0.0641
0.020	0.1530	0.1576	0.2497	0.0662	0.0850	0.0997
0.030	0.1683	0.1819	0.2828	0.0841	0.1084	0.1244
0.040	0.1879	0.2001	0.3094	0.0992	0.1291	0.1484
0.050	0.1998	0.2148	0.3302	0.1122	0.1446	0.1698

b

Size of test	One-sided test				Two-sided test			
	$H_{LL}$	$H_L$	$H_R$	$H_{RR}$	$H_{LL}$	$H_L$	$H_R$	$H_{RR}$
	Generalized rank test							
0.010	0.644	0.150	0.188	0.622	0.496	0.078	0.145	0.562
0.020	0.748	0.222	0.269	0.705	0.626	0.140	0.191	0.626
0.030	0.798	0.273	0.319	0.753	0.706	0.187	0.232	0.669
0.040	0.849	0.340	0.361	0.783	0.753	0.227	0.263	0.698
0.050	0.875	0.378	0.392	0.804	0.788	0.262	0.285	0.720
	Supremum type test							
0.010	0.541	0.114	0.153	0.539	0.447	0.076	0.082	0.407
0.020	0.668	0.191	0.221	0.631	0.584	0.136	0.133	0.504
0.030	0.738	0.254	0.276	0.689	0.650	0.177	0.164	0.557
0.040	0.786	0.301	0.320	0.731	0.703	0.220	0.195	0.599
0.050	0.816	0.339	0.352	0.758	0.740	0.258	0.223	0.631

c

Table 6.25: Tests based on stochastic integral type 12 (maximum likelihood estimation) and  $n = 50$ . No censoring.

a: description stochastic integral;

b: critical points asymptotic P-values;

c: simulated power generalized rank and supremum type tests.

	$H_{LL}$	$H_L$	$H_0$	$H_R$	$H_{RR}$
mean $Q_n(\infty; v^{(n)})$	-1.3881	-0.7630	-0.0323	0.7286	1.5403
st.dev. $Q_n(\infty; v^{(n)})$	0.3779	0.4358	0.4986	0.5694	0.6417
skewness $Q_n(\infty; v^{(n)})$	0.1092	0.2182	0.2227	0.0705	0.0306
kurtosis $Q_n(\infty; v^{(n)})$	-0.0570	0.0015	0.0517	-0.0068	0.0099

a

Size of test	Generalized rank test			Supremum type test		
	Left-Sided	Right-Sided	Two-Sided	Left-Sided	Right-Sided	Two-Sided
0.005	0.1137	0.0877	0.1591	0.0339	0.0331	0.0440
0.010	0.1339	0.1142	0.1996	0.0489	0.0497	0.0672
0.015	0.1480	0.1334	0.2305	0.0588	0.0617	0.0834
0.020	0.1584	0.1471	0.2510	0.0696	0.0739	0.0985
0.025	0.1678	0.1598	0.2675	0.0798	0.0841	0.1109

b

Size of test	One-sided test				Two-sided test			
	$H_{LL}$	$H_L$	$H_R$	$H_{RR}$	$H_{LL}$	$H_L$	$H_R$	$H_{RR}$
	Generalized rank test							
0.005	0.691	0.157	0.139	0.610	0.484	0.067	0.121	0.579
0.010	0.775	0.220	0.200	0.698	0.614	0.114	0.165	0.653
0.015	0.821	0.265	0.247	0.746	0.699	0.161	0.204	0.701
0.020	0.846	0.299	0.281	0.777	0.743	0.192	0.227	0.729
0.025	0.867	0.330	0.313	0.799	0.774	0.220	0.248	0.747
	Supremum type test							
0.005	0.561	0.113	0.111	0.519	0.446	0.068	0.074	0.427
0.010	0.663	0.167	0.164	0.612	0.560	0.112	0.113	0.525
0.015	0.716	0.203	0.201	0.662	0.623	0.142	0.140	0.574
0.020	0.763	0.241	0.236	0.699	0.665	0.168	0.163	0.610
0.025	0.796	0.276	0.265	0.726	0.700	0.189	0.183	0.638

c

Table 6.26: Tests based on stochastic integral type 12 (maximum likelihood estimation) and  $n = 100$ . No censoring.

a: description stochastic integral;

b: critical points asymptotic P-values;

c: simulated power generalized rank and supremum type tests.



	$H_{LL}$	$H_L$	$H_0$	$H_R$	$H_{RR}$
mean $Q_n(\infty; v^{(n)})$	-2.1617	-1.2819	-0.1796	1.0628	2.3237
st.dev. $Q_n(\infty; v^{(n)})$	0.6195	0.7841	0.9811	1.2203	1.4965
skewness $Q_n(\infty; v^{(n)})$	0.4893	0.3543	0.3055	0.3903	0.3986
kurtosis $Q_n(\infty; v^{(n)})$	0.3068	0.0904	0.2030	0.1534	0.1028

a

Size of test	Generalized rank test			Supremum type test		
	Left-Sided	Right-Sided	Two-Sided	Left-Sided	Right-Sided	Two-Sided
0.020	0.0225	0.0198	0.0226	0.0422	0.0134	0.0222
0.040	0.0377	0.0512	0.0430	0.0699	0.0324	0.0474
0.060	0.0507	0.0806	0.0646	0.0920	0.0546	0.0722
0.080	0.0673	0.1082	0.0831	0.1180	0.0792	0.0985
0.100	0.0826	0.1360	0.1017	0.1404	0.1043	0.1246

b

Size of test	One-sided test				Two-sided test			
	$H_{LL}$	$H_L$	$H_R$	$H_{RR}$	$H_{LL}$	$H_L$	$H_R$	$H_{RR}$
Generalized rank test								
0.020	0.623	0.181	0.205	0.552	0.451	0.093	0.161	0.492
0.040	0.745	0.278	0.305	0.660	0.613	0.175	0.214	0.560
0.060	0.809	0.345	0.372	0.718	0.710	0.248	0.254	0.607
0.080	0.862	0.414	0.420	0.757	0.766	0.298	0.283	0.636
0.100	0.894	0.470	0.465	0.785	0.809	0.347	0.311	0.661
Supremum type test								
0.020	0.618	0.180	0.217	0.562	0.292	0.042	0.202	0.544
0.040	0.739	0.278	0.295	0.649	0.471	0.102	0.266	0.620
0.060	0.802	0.342	0.361	0.707	0.576	0.154	0.308	0.661
0.080	0.853	0.408	0.411	0.747	0.657	0.206	0.348	0.694
0.100	0.882	0.453	0.456	0.779	0.714	0.256	0.383	0.723

c

Table 6.27: Tests based on stochastic integral type 13 (maximum likelihood estimation) and  $n = 25$ . No censoring.

a: description stochastic integral;

b: critical points asymptotic P-values;

c: simulated power generalized rank and supremum type tests.

	$H_{LL}$	$H_L$	$H_0$	$H_R$	$H_{RR}$
mean $Q_n(\infty; v^{(n)})$	-2.4907	-1.4012	-0.1215	1.2897	2.7773
st.dev. $Q_n(\infty; v^{(n)})$	0.6929	0.8275	0.9900	1.1667	1.3910
skewness $Q_n(\infty; v^{(n)})$	0.3151	0.3780	0.2343	0.1073	0.0958
kurtosis $Q_n(\infty; v^{(n)})$	0.0730	0.1572	0.0186	-0.1256	0.0173

a

Size of test	Generalized rank test			Supremum type test		
	Left-Sided	Right-Sided	Two-Sided	Left-Sided	Right-Sided	Two-Sided
0.010	0.0117	0.0101	0.0112	0.0200	0.0061	0.0107
0.020	0.0203	0.0224	0.0215	0.0346	0.0154	0.0215
0.030	0.0274	0.0349	0.0320	0.0496	0.0250	0.0351
0.040	0.0381	0.0461	0.0419	0.0627	0.0354	0.0466
0.050	0.0461	0.0563	0.0516	0.0764	0.0444	0.0578

b

Size of test	One-sided test				Two-sided test			
	$H_{LL}$	$H_L$	$H_R$	$H_{RR}$	$H_{LL}$	$H_L$	$H_R$	$H_{RR}$
	Generalized rank test							
0.010	0.643	0.150	0.188	0.621	0.495	0.078	0.145	0.561
0.020	0.748	0.221	0.270	0.705	0.627	0.140	0.192	0.627
0.030	0.799	0.272	0.320	0.754	0.708	0.189	0.232	0.671
0.040	0.848	0.338	0.360	0.783	0.753	0.227	0.262	0.698
0.050	0.875	0.378	0.391	0.802	0.788	0.262	0.285	0.720
	Supremum type test							
0.010	0.630	0.144	0.179	0.603	0.357	0.040	0.171	0.592
0.020	0.738	0.218	0.259	0.692	0.501	0.081	0.223	0.656
0.030	0.800	0.281	0.313	0.739	0.603	0.128	0.272	0.705
0.040	0.839	0.325	0.351	0.772	0.661	0.164	0.305	0.732
0.050	0.866	0.372	0.384	0.794	0.705	0.192	0.328	0.751

c

Table 6.28: Tests based on stochastic integral type 13 (maximum likelihood estimation) and  $n = 50$ . No censoring.

a: description stochastic integral;

b: critical points asymptotic P-values;

c: simulated power generalized rank and supremum type tests.

	$H_{LL}$	$H_L$	$H_0$	$H_R$	$H_{RR}$
mean $Q_n(\infty; v^{(n)})$	-2.7763	-1.5259	-0.0645	1.4571	3.0805
st.dev. $Q_n(\infty; v^{(n)})$	0.7558	0.8716	0.9972	1.1389	1.2834
skewness $Q_n(\infty; v^{(n)})$	0.1092	0.2182	0.2227	0.0705	0.0306
kurtosis $Q_n(\infty; v^{(n)})$	-0.0570	0.0015	0.0517	-0.0068	0.0099

a

Size of test	Generalized rank test			Supremum type test		
	Left-Sided	Right-Sided	Two-Sided	Left-Sided	Right-Sided	Two-Sided
0.005	0.0080	0.0036	0.0049	0.0124	0.0026	0.0048
0.010	0.0134	0.0082	0.0104	0.0208	0.0058	0.0094
0.015	0.0179	0.0129	0.0163	0.0276	0.0102	0.0149
0.020	0.0226	0.0181	0.0214	0.0341	0.0138	0.0219
0.025	0.0267	0.0230	0.0260	0.0408	0.0182	0.0263

b

Size of test	One-sided test				Two-sided test			
	$H_{LL}$	$H_L$	$H_R$	$H_{RR}$	$H_{LL}$	$H_L$	$H_R$	$H_{RR}$
	Generalized rank test							
0.005	0.693	0.157	0.141	0.616	0.486	0.068	0.121	0.580
0.010	0.776	0.221	0.203	0.701	0.617	0.115	0.165	0.654
0.015	0.819	0.261	0.245	0.744	0.696	0.159	0.203	0.700
0.020	0.846	0.298	0.282	0.777	0.741	0.191	0.226	0.727
0.025	0.865	0.327	0.312	0.798	0.772	0.216	0.246	0.745
	Supremum type test							
0.005	0.674	0.146	0.139	0.605	0.387	0.043	0.135	0.600
0.010	0.760	0.212	0.194	0.681	0.500	0.074	0.177	0.662
0.015	0.803	0.253	0.242	0.733	0.579	0.101	0.214	0.704
0.020	0.832	0.288	0.271	0.759	0.651	0.133	0.248	0.739
0.025	0.856	0.317	0.304	0.785	0.686	0.154	0.266	0.755

c

Table 6.29: Tests based on stochastic integral type 13 (maximum likelihood estimation) and  $n = 100$ . No censoring.

a: description stochastic integral;

b: critical points asymptotic P-values;

c: simulated power generalized rank and supremum type tests.

	$H_{LL}$	$H_L$	$H_0$	$H_R$	$H_{RR}$
mean $Q_n(\infty; v^{(n)})$	-1.8702	-1.1822	-0.1362	0.9217	1.6082
st.dev. $Q_n(\infty; v^{(n)})$	0.7950	0.8010	0.9887	1.3607	1.7703
skewness $Q_n(\infty; v^{(n)})$	-0.3152	-0.1281	0.3725	0.7136	0.9926
kurtosis $Q_n(\infty; v^{(n)})$	-0.0514	0.1657	0.5918	1.0510	1.7083

a

Size of test	Generalized rank test			Supremum type test		
	Left-Sided	Right-Sided	Two-Sided	Left-Sided	Right-Sided	Two-Sided
0.020	0.0204	0.0188	0.0178	0.0353	0.0118	0.0151
0.040	0.0381	0.0464	0.0394	0.0657	0.0327	0.0407
0.060	0.0552	0.0733	0.0617	0.0945	0.0593	0.0690
0.080	0.0715	0.1030	0.0817	0.1200	0.0834	0.0958
0.100	0.0885	0.1310	0.1035	0.1449	0.1091	0.1255

b

Size of test	One-sided test				Two-sided test			
	$H_{LL}$	$H_L$	$H_R$	$H_{RR}$	$H_{LL}$	$H_L$	$H_R$	$H_{RR}$
	Generalized rank test							
0.020	0.396	0.138	0.180	0.336	0.256	0.073	0.140	0.278
0.040	0.527	0.224	0.253	0.421	0.389	0.135	0.187	0.342
0.060	0.615	0.294	0.304	0.475	0.481	0.190	0.224	0.386
0.080	0.679	0.354	0.351	0.520	0.543	0.237	0.252	0.415
0.100	0.728	0.409	0.391	0.555	0.599	0.280	0.278	0.440
	Supremum type test							
0.020	0.384	0.136	0.183	0.338	0.165	0.038	0.160	0.309
0.040	0.512	0.220	0.257	0.421	0.288	0.090	0.220	0.378
0.060	0.598	0.288	0.315	0.481	0.380	0.135	0.265	0.428
0.080	0.654	0.342	0.354	0.521	0.447	0.173	0.298	0.460
0.100	0.707	0.393	0.389	0.555	0.502	0.214	0.330	0.494

c

Table 6.30: Tests based on stochastic integral type 13 (maximum likelihood estimation) and  $n = 25$ . Standard exponential censoring.

a: description stochastic integral;

b: critical points asymptotic P-values;

c: simulated power generalized rank and supremum type tests.

	$H_{LL}$	$H_L$	$H_0$	$H_R$	$H_{RR}$
mean $Q_n(\infty; v^{(n)})$	-2.2354	-1.3145	-0.1076	1.2216	2.2743
st.dev. $Q_n(\infty; v^{(n)})$	0.7809	0.8333	0.9853	1.2965	1.7302
skewness $Q_n(\infty; v^{(n)})$	-0.1759	0.0189	0.2438	0.3669	0.7487
kurtosis $Q_n(\infty; v^{(n)})$	0.0986	0.1111	0.2499	0.4027	0.7663

a

Size of test	Generalized rank test			Supremum type test		
	Left-Sided	Right-Sided	Two-Sided	Left-Sided	Right-Sided	Two-Sided
0.010	0.0136	0.0079	0.0103	0.0222	0.0053	0.0081
0.020	0.0221	0.0186	0.0207	0.0376	0.0156	0.0226
0.030	0.0324	0.0332	0.0313	0.0516	0.0239	0.0347
0.040	0.0401	0.0458	0.0422	0.0657	0.0363	0.0469
0.050	0.0493	0.0587	0.0543	0.0776	0.0479	0.0602

b

Size of test	One-sided test				Two-sided test			
	$H_{LL}$	$H_L$	$H_R$	$H_{RR}$	$H_{LL}$	$H_L$	$H_R$	$H_{RR}$
	Generalized rank test							
0.010	0.498	0.143	0.171	0.426	0.322	0.066	0.148	0.388
0.020	0.604	0.201	0.238	0.501	0.444	0.118	0.190	0.449
0.030	0.685	0.258	0.298	0.560	0.528	0.157	0.224	0.486
0.040	0.731	0.294	0.338	0.595	0.594	0.194	0.251	0.513
0.050	0.771	0.339	0.366	0.627	0.646	0.232	0.278	0.538
	Supremum type test							
0.010	0.479	0.137	0.170	0.420	0.215	0.035	0.154	0.399
0.020	0.594	0.200	0.248	0.515	0.354	0.080	0.221	0.486
0.030	0.662	0.249	0.287	0.556	0.431	0.113	0.258	0.525
0.040	0.714	0.292	0.331	0.600	0.491	0.143	0.286	0.554
0.050	0.749	0.323	0.367	0.629	0.545	0.170	0.310	0.580

c

Table 6.31: Tests based on stochastic integral type 13 (maximum likelihood estimation) and  $n = 50$ . Standard exponential censoring.

a: description stochastic integral;

b: critical points asymptotic P-values;

c: simulated power generalized rank and supremum type tests.

	$H_{LL}$	$H_L$	$H_0$	$H_R$	$H_{RR}$
mean $Q_n(\infty; v^{(n)})$	-2.6127	-1.4708	-0.0769	1.4259	2.7542
st.dev. $Q_n(\infty; v^{(n)})$	0.7917	0.8383	1.0164	1.2443	1.5497
skewness $Q_n(\infty; v^{(n)})$	-0.0218	0.0448	0.1697	0.2699	0.2691
kurtosis $Q_n(\infty; v^{(n)})$	-0.0534	0.1373	0.1738	0.2143	0.0762

a

Size of test	Generalized rank test			Supremum type test		
	Left-Sided	Right-Sided	Two-Sided	Left-Sided	Right-Sided	Two-Sided
0.005	0.0050	0.0030	0.0037	0.0073	0.0021	0.0032
0.010	0.0107	0.0074	0.0076	0.0168	0.0055	0.0073
0.015	0.0147	0.0130	0.0129	0.0230	0.0097	0.0125
0.020	0.0192	0.0173	0.0190	0.0291	0.0133	0.0181
0.025	0.0229	0.0213	0.0233	0.0355	0.0185	0.0233

b

Size of test	One-sided test				Two-sided test			
	$H_{LL}$	$H_L$	$H_R$	$H_{RR}$	$H_{LL}$	$H_L$	$H_R$	$H_{RR}$
	Generalized rank test							
0.005	0.513	0.093	0.143	0.473	0.355	0.040	0.120	0.435
0.010	0.646	0.161	0.203	0.555	0.466	0.075	0.158	0.492
0.015	0.700	0.199	0.249	0.610	0.558	0.111	0.191	0.541
0.020	0.748	0.238	0.275	0.641	0.624	0.147	0.222	0.578
0.025	0.777	0.266	0.297	0.661	0.661	0.169	0.238	0.598
	Supremum type test							
0.005	0.486	0.084	0.138	0.462	0.258	0.023	0.124	0.442
0.010	0.631	0.157	0.195	0.546	0.372	0.048	0.169	0.511
0.015	0.686	0.196	0.238	0.598	0.459	0.075	0.205	0.558
0.020	0.725	0.230	0.268	0.628	0.521	0.099	0.232	0.592
0.025	0.759	0.259	0.301	0.657	0.566	0.119	0.255	0.615

c

Table 6.32: Tests based on stochastic integral type 13 (maximum likelihood estimation) and  $n = 100$ . Standard exponential censoring.

a: description stochastic integral;

b: critical points asymptotic P-values;

c: simulated power generalized rank and supremum type tests.

	$H_{LL}$	$H_L$	$H_0$	$H_R$	$H_{RR}$
mean $Q_n(\infty; v^{(n)})$	-2.5843	-1.4571	-0.2413	0.9568	2.0603
st.dev. $Q_n(\infty; v^{(n)})$	0.8544	0.9362	1.0125	1.1183	1.2755
skewness $Q_n(\infty; v^{(n)})$	0.1440	0.0118	-0.0374	0.0973	0.2046
kurtosis $Q_n(\infty; v^{(n)})$	-0.0257	-0.0991	0.0559	0.0741	0.1778

a

Size of test	Generalized rank test			Supremum type test		
	Left-Sided	Right-Sided	Two-Sided	Left-Sided	Right-Sided	Two-Sided
0.020	0.0101	0.0313	0.0154	0.0187	0.0255	0.0211
0.040	0.0214	0.0636	0.0313	0.0403	0.0499	0.0423
0.060	0.0337	0.0934	0.0473	0.0609	0.0742	0.0671
0.080	0.0482	0.1215	0.0660	0.0846	0.0997	0.0887
0.100	0.0629	0.1477	0.0865	0.1092	0.1261	0.1096

b

Size of test	One-sided test				Two-sided test			
	$H_{LL}$	$H_L$	$H_R$	$H_{RR}$	$H_{LL}$	$H_L$	$H_R$	$H_{RR}$
Generalized rank test								
0.020	0.618	0.178	0.209	0.558	0.575	0.151	0.095	0.379
0.040	0.744	0.274	0.303	0.658	0.694	0.232	0.145	0.463
0.060	0.812	0.349	0.369	0.717	0.760	0.289	0.185	0.520
0.080	0.862	0.414	0.419	0.757	0.810	0.346	0.221	0.566
0.100	0.893	0.470	0.464	0.786	0.849	0.395	0.257	0.606
Supremum type test								
0.020	0.620	0.178	0.213	0.555	0.521	0.124	0.132	0.441
0.040	0.747	0.278	0.292	0.646	0.641	0.192	0.196	0.532
0.060	0.811	0.349	0.356	0.699	0.717	0.253	0.245	0.595
0.080	0.859	0.412	0.408	0.742	0.762	0.293	0.280	0.632
0.100	0.889	0.464	0.452	0.775	0.795	0.331	0.311	0.658

c

Table 6.33: Tests based on stochastic integral type 23 (maximum likelihood estimation) and  $n = 25$ . No censoring.

a: description stochastic integral;

b: critical points asymptotic P-values;

c: simulated power generalized rank and supremum type tests.

	$H_{LL}$	$H_L$	$H_0$	$H_R$	$H_{RR}$
mean $Q_n(\infty; v^{(n)})$	-2.8551	-1.5364	-0.1641	1.1944	2.5041
st.dev. $Q_n(\infty; v^{(n)})$	0.8911	0.9439	1.0071	1.0731	1.1909
skewness $Q_n(\infty; v^{(n)})$	0.0749	0.1252	-0.0094	-0.0902	-0.0735
kurtosis $Q_n(\infty; v^{(n)})$	-0.0674	-0.0068	-0.0208	-0.1120	0.0969

a

Size of test	Generalized rank test			Supremum type test		
	Left-Sided	Right-Sided	Two-Sided	Left-Sided	Right-Sided	Two-Sided
0.010	0.0054	0.0156	0.0083	0.0094	0.0122	0.0105
0.020	0.0119	0.0303	0.0176	0.0202	0.0255	0.0213
0.030	0.0178	0.0443	0.0262	0.0312	0.0373	0.0320
0.040	0.0270	0.0563	0.0341	0.0431	0.0487	0.0436
0.050	0.0337	0.0672	0.0449	0.0568	0.0599	0.0562

b

Size of test	One-sided test				Two-sided test			
	$H_{LL}$	$H_L$	$H_R$	$H_{RR}$	$H_{LL}$	$H_L$	$H_R$	$H_{RR}$
	Generalized rank test							
0.010	0.635	0.145	0.187	0.620	0.599	0.124	0.090	0.457
0.020	0.749	0.221	0.268	0.704	0.710	0.189	0.137	0.549
0.030	0.801	0.274	0.322	0.754	0.762	0.233	0.171	0.597
0.040	0.849	0.340	0.361	0.783	0.794	0.268	0.196	0.630
0.050	0.874	0.377	0.392	0.803	0.829	0.311	0.229	0.668
	Supremum type test							
0.010	0.632	0.145	0.179	0.602	0.547	0.101	0.115	0.502
0.020	0.745	0.221	0.259	0.691	0.651	0.158	0.168	0.587
0.030	0.802	0.278	0.311	0.736	0.714	0.198	0.205	0.633
0.040	0.843	0.330	0.348	0.767	0.755	0.231	0.240	0.672
0.050	0.872	0.380	0.384	0.794	0.788	0.264	0.272	0.704

c

Table 6.34: Tests based on stochastic integral type 23 (maximum likelihood estimation) and  $n = 50$ . No censoring.

a: description stochastic integral;

b: critical points asymptotic P-values;

c: simulated power generalized rank and supremum type tests.



	$H_{LL}$	$H_L$	$H_0$	$H_R$	$H_{RR}$
mean $Q_n(\infty; v^{(n)})$	-3.0751	-1.6314	-0.0937	1.3753	2.8332
st.dev. $Q_n(\infty; v^{(n)})$	0.9156	0.9623	1.0027	1.0607	1.1205
skewness $Q_n(\infty; v^{(n)})$	-0.0646	0.0458	0.0515	-0.0831	-0.1074
kurtosis $Q_n(\infty; v^{(n)})$	-0.0999	-0.0676	-0.0034	-0.0067	0.0394

a

Size of test	Generalized rank test			Supremum type test		
	Left-Sided	Right-Sided	Two-Sided	Left-Sided	Right-Sided	Two-Sided
0.005	0.0045	0.0057	0.0053	0.0068	0.0051	0.0058
0.010	0.0085	0.0119	0.0104	0.0125	0.0097	0.0114
0.015	0.0129	0.0169	0.0146	0.0183	0.0159	0.0168
0.020	0.0164	0.0234	0.0196	0.0238	0.0199	0.0221
0.025	0.0202	0.0291	0.0247	0.0304	0.0254	0.0277

b

Size of test	One-sided test				Two-sided test			
	$H_{LL}$	$H_L$	$H_R$	$H_{RR}$	$H_{LL}$	$H_L$	$H_R$	$H_{RR}$
	Generalized rank test							
0.005	0.692	0.155	0.139	0.612	0.618	0.114	0.093	0.519
0.010	0.774	0.219	0.203	0.700	0.712	0.168	0.133	0.602
0.015	0.823	0.266	0.241	0.742	0.756	0.203	0.157	0.642
0.020	0.848	0.300	0.283	0.776	0.792	0.235	0.183	0.676
0.025	0.867	0.329	0.314	0.799	0.818	0.262	0.207	0.705
	Supremum type test							
0.005	0.678	0.148	0.139	0.605	0.557	0.092	0.104	0.540
0.010	0.758	0.210	0.192	0.675	0.651	0.134	0.147	0.620
0.015	0.807	0.255	0.242	0.732	0.708	0.169	0.178	0.660
0.020	0.834	0.290	0.268	0.755	0.743	0.197	0.203	0.691
0.025	0.861	0.324	0.302	0.783	0.771	0.221	0.226	0.717

c

Table 6.35: Tests based on stochastic integral type 23 (maximum likelihood estimation) and  $n = 100$ . No censoring.

a: description stochastic integral;

b: critical points asymptotic P-values;

c: simulated power generalized rank and supremum type tests.

	$H_{LL}$	$H_L$	$H_0$	$H_R$	$H_{RR}$
mean $Q_n(\infty; v^{(n)})$	-2.8138	-1.5424	-0.2213	0.7090	1.1824
st.dev. $Q_n(\infty; v^{(n)})$	0.9407	1.0018	1.0388	1.0960	1.2419
skewness $Q_n(\infty; v^{(n)})$	0.2262	0.0034	-0.0759	-0.0518	0.1543
kurtosis $Q_n(\infty; v^{(n)})$	-0.0464	-0.1069	-0.0652	0.0672	0.3960

a

Size of test	Generalized rank test			Supremum type test		
	Left-Sided	Right-Sided	Two-Sided	Left-Sided	Right-Sided	Two-Sided
0.020	0.0076	0.0330	0.0128	0.0134	0.0358	0.0195
0.040	0.0178	0.0583	0.0267	0.0297	0.0658	0.0417
0.060	0.0306	0.0865	0.0443	0.0502	0.0913	0.0637
0.080	0.0429	0.1139	0.0627	0.0730	0.1174	0.0901
0.100	0.0577	0.1374	0.0791	0.0947	0.1435	0.1150

b

Size of test	One-sided test				Two-sided test			
	$H_{LL}$	$H_L$	$H_R$	$H_{RR}$	$H_{LL}$	$H_L$	$H_R$	$H_{RR}$
	Generalized rank test							
0.020	0.663	0.191	0.153	0.288	0.642	0.173	0.051	0.140
0.040	0.773	0.294	0.216	0.374	0.742	0.256	0.088	0.195
0.060	0.836	0.373	0.275	0.438	0.802	0.325	0.123	0.246
0.080	0.873	0.434	0.327	0.491	0.838	0.378	0.160	0.288
0.100	0.899	0.492	0.367	0.531	0.864	0.419	0.185	0.324
	Supremum type test							
0.020	0.686	0.197	0.152	0.291	0.643	0.167	0.063	0.162
0.040	0.791	0.298	0.228	0.381	0.747	0.250	0.109	0.235
0.060	0.848	0.380	0.281	0.442	0.799	0.310	0.148	0.282
0.080	0.888	0.451	0.326	0.488	0.836	0.363	0.186	0.326
0.100	0.910	0.503	0.367	0.532	0.864	0.405	0.220	0.366

c

Table 6.36: Tests based on stochastic integral type 23 (maximum likelihood estimation) and  $n = 25$ . Standard exponential censoring.

a: description stochastic integral;

b: critical points asymptotic P-values;

c: simulated power generalized rank and supremum type tests.

	$H_{LL}$	$H_L$	$H_0$	$H_R$	$H_{RR}$
mean $Q_n(\infty; v^{(n)})$	-3.1650	-1.6180	-0.1682	1.0020	1.7408
st.dev. $Q_n(\infty; v^{(n)})$	0.9699	1.0124	1.0113	1.0526	1.1820
skewness $Q_n(\infty; v^{(n)})$	0.1576	0.0563	-0.0837	-0.2078	0.1002
kurtosis $Q_n(\infty; v^{(n)})$	-0.0450	-0.0851	-0.0480	0.0441	0.0562

a

Size of test	Generalized rank test			Supremum type test		
	Left-Sided	Right-Sided	Two-Sided	Left-Sided	Right-Sided	Two-Sided
0.010	0.0056	0.0171	0.0092	0.0094	0.0179	0.0125
0.020	0.0107	0.0308	0.0172	0.0180	0.0321	0.0256
0.030	0.0183	0.0442	0.0255	0.0278	0.0465	0.0359
0.040	0.0245	0.0605	0.0356	0.0398	0.0584	0.0482
0.050	0.0311	0.0733	0.0449	0.0496	0.0720	0.0589

b

Size of test	One-sided test				Two-sided test			
	$H_{LL}$	$H_L$	$H_R$	$H_{RR}$	$H_{LL}$	$H_L$	$H_R$	$H_{RR}$
Generalized rank test								
0.010	0.745	0.187	0.143	0.374	0.720	0.168	0.060	0.227
0.020	0.816	0.252	0.208	0.457	0.793	0.229	0.091	0.289
0.030	0.864	0.324	0.259	0.515	0.833	0.274	0.119	0.336
0.040	0.888	0.368	0.310	0.565	0.862	0.320	0.149	0.380
0.050	0.908	0.407	0.340	0.597	0.881	0.354	0.173	0.410
Supremum type test								
0.010	0.760	0.191	0.142	0.371	0.709	0.155	0.069	0.251
0.020	0.828	0.262	0.205	0.457	0.794	0.223	0.113	0.328
0.030	0.870	0.325	0.257	0.514	0.828	0.262	0.144	0.372
0.040	0.897	0.379	0.291	0.552	0.856	0.302	0.175	0.415
0.050	0.913	0.416	0.328	0.588	0.874	0.333	0.197	0.444

c

Table 6.37: Tests based on stochastic integral type 23 (maximum likelihood estimation) and  $n = 50$ . Standard exponential censoring.

a: description stochastic integral;

b: critical points asymptotic P-values;

c: simulated power generalized rank and supremum type tests.

	$H_{LL}$	$H_L$	$H_0$	$H_R$	$H_{RR}$
mean $Q_n(\infty; v^{(n)})$	-3.4306	-1.7217	-0.1192	1.2254	2.2003
st.dev. $Q_n(\infty; v^{(n)})$	0.9883	0.9882	1.0271	1.0378	1.1022
skewness $Q_n(\infty; v^{(n)})$	0.0873	0.0091	-0.0652	-0.1170	-0.1709
kurtosis $Q_n(\infty; v^{(n)})$	-0.0689	0.0228	-0.0293	0.0102	0.0174

a

Size of test	Generalized rank test			Supremum type test		
	Left-Sided	Right-Sided	Two-Sided	Left-Sided	Right-Sided	Two-Sided
0.005	0.0030	0.0070	0.0037	0.0041	0.0064	0.0056
0.010	0.0061	0.0129	0.0089	0.0096	0.0124	0.0111
0.015	0.0087	0.0195	0.0127	0.0142	0.0168	0.0170
0.020	0.0120	0.0258	0.0162	0.0188	0.0225	0.0212
0.025	0.0159	0.0312	0.0202	0.0238	0.0286	0.0266

b

Size of test	One-sided test				Two-sided test			
	$H_{LL}$	$H_L$	$H_R$	$H_{RR}$	$H_{LL}$	$H_L$	$H_R$	$H_{RR}$
	Generalized rank test							
0.005	0.754	0.149	0.117	0.411	0.697	0.114	0.050	0.263
0.010	0.824	0.215	0.164	0.493	0.794	0.184	0.089	0.357
0.015	0.856	0.256	0.211	0.551	0.829	0.220	0.111	0.399
0.020	0.882	0.295	0.246	0.592	0.850	0.248	0.128	0.431
0.025	0.902	0.336	0.274	0.626	0.870	0.274	0.145	0.460
	Supremum type test							
0.005	0.746	0.140	0.108	0.388	0.701	0.113	0.064	0.293
0.010	0.833	0.222	0.158	0.476	0.778	0.164	0.100	0.372
0.015	0.866	0.268	0.190	0.519	0.820	0.208	0.127	0.425
0.020	0.889	0.305	0.220	0.559	0.842	0.233	0.143	0.456
0.025	0.906	0.338	0.254	0.597	0.861	0.260	0.164	0.486

c

Table 6.38: Tests based on stochastic integral type 23 (maximum likelihood estimation) and  $n = 100$ . Standard exponential censoring.

a: description stochastic integral;

b: critical points asymptotic P-values;

c: simulated power generalized rank and supremum type tests.

## 6.4 Conclusion

Replacing  $\mu_\beta(v_0)$  by  $\hat{\mu}_\beta(v_0)$  in the weight process shifts the sensitivity. The direction of the shift depends on whether we are dealing with the simple [increased sensitivity to the right] or composite [increased sensitivity to the left] null hypothesis.

An exception should be made for one-sided tests. The indifference spotted here seems to suggest that the replacement has about the same effect as a monotone transformation of the test statistic.

If censoring occurs, then left-sided tests should be preferably be based on stochastic integral 12 [simple null hypothesis] or 23 [composite null hypothesis], and right-sided tests on stochastic integral 22 [simple null hypothesis] or 13 [composite null hypothesis]. No preference can be given for one-sided tests in the absence of censoring. The same is true for two-sided tests, since higher sensitivity to the left or right is no criterium for two-sided tests, where the user is supposed to be ignorant of direction.



# Appendix A

## On Wieand's theorem

This appendix contains the first three sections of Kallenberg and Koning (1993), which materialized in an effort to generalize Theorem 11, stated in section 4.3 on page 65.

Wieand's theorem on equivalence of limiting approximate Bahadur efficiency and limiting Pitman efficiency is extended in several ways. Conditions on monotonicity and continuity are obviated, composite null hypotheses are incorporated, and the implications of a weaker form of Wieand's Condition III\* are investigated.

### A.1 Introduction

To compare the performance of two sequences of test statistics, many efficiency concepts have been proposed. Probably the most widely used is asymptotic relative Pitman efficiency.

In Bahadur (1960) the concept of exact Bahadur efficiency was proposed. This concept requires large deviation results, the derivation of which often becomes the stumbling-block in the application. As a "quick and dirty" variant Bahadur simultaneously proposed approximate Bahadur efficiency, valid for comparison of so-called standard sequences. Since it is rather easy to verify whether a sequence of test statistics actually is standard, approximate Bahadur efficiency in spite of its apparent shortcomings [see Bahadur (1960)] has become quite popular.

In favour of approximate Bahadur efficiency, Bahadur argued that for many well-known test statistics the limiting [as the alternative approaches the null hypothesis] approximate Bahadur efficiency is equal to the asymptotic relative Pitman efficiency. Working with an extended version of asymptotic relative Pitman efficiency, Wieand (1976) elaborated this point by presenting a condition under which the limiting approximate Bahadur efficiency, coincided with the limiting [as the size of the test tends to zero] asymptotic relative Pitman efficiency.

Unfortunately, Wieand only proved the theorem which stated this coincidence for the simple null hypothesis. Moreover, he requires continuity and strict mono-

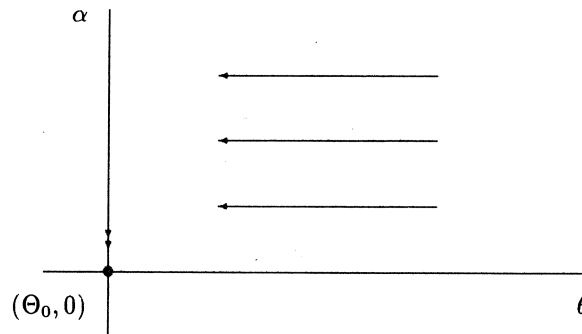


Figure A.1: Limiting Pitman efficiency.

tonicity of the tail of the asymptotic null distribution of the sequence of test statistics. In this note we extend Wieand's theorem to composite null hypotheses, while discarding continuity and strict monotonicity conditions.

Evaluating limiting Pitman efficiency means that the alternative is sent to the null hypothesis and afterwards the size  $\alpha$  to zero. This is outlined in Figure A.1.

The order of the operations is reversed for the limiting approximate Bahadur efficiency, as is sketched in Figure A.2.

Under Wieand's Condition III\* it holds for standard sequences of test statistics that both ways of approaching  $(\Theta_0, 0)$  yield the same result. In fact it can be shown that for *any* way in which  $(\theta, \alpha)$  tend to  $(\Theta_0, 0)$  the result is the same, provided that Wieand's Condition III\* holds.

Often, the knowledge of the behavior of the test statistics is available in great

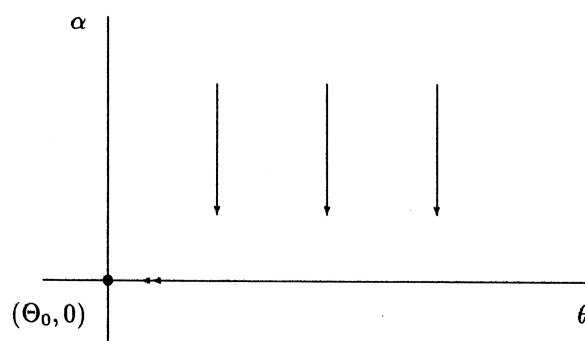


Figure A.2: Limiting Bahadur efficiency.



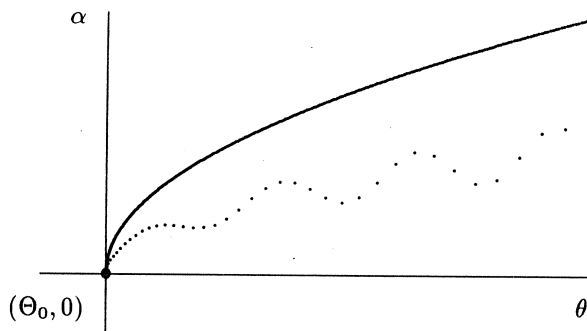


Figure A.3: The restricted area of admitted trajectories.

detail under the null hypothesis, but scarce under the alternative hypothesis. This may lead to problems with the verification of Wieand's Condition III\*, since it deals explicitly with the behavior under the alternative hypothesis. However, if a weaker form of the condition holds [cf. Definition 13 in section A.2] it still can be shown that we come close to the answer of the Bahadur approach for any trajectory in a restricted region, for instance trajectories as sketched in Figure A.3.

The closer we want to be to the answer of the Bahadur approach, the smaller the area of admitted trajectories. This is reflected by a lowering of the curve depicted in Figure A.3, and implies that we should restrict ourselves to tests of even smaller size.

Thus, the quality of the approximation of the finite sample relative efficiency by the approximate Bahadur efficiency for alternatives close to the null hypothesis is only guaranteed in case of (very) small levels.

The organization is as follows. In section A.2 notation is introduced and definitions are given, while section A.3 contains the results. Proofs can be found in Kallenberg and Koning (1993).

## A.2 Preliminaries

Consider the situation in which we have two infinite sequences of test statistics  $\{T_{1n}\}_{n=1}^{\infty}$  and  $\{T_{2n}\}_{n=1}^{\infty}$ , rejecting the null hypothesis  $H_0 : \theta \in \Theta_0$  for large values of the test statistics. The number  $n$  here refers to the number of available observations. The whole parameter space is denoted by  $\Theta$ , which is a metric space with metric  $d$ . For each  $\alpha \in (0, 1)$  the critical value is denoted by  $t_{in}(\alpha)$ . So,  $H_0$  is rejected if  $T_{in} > t_{in}(\alpha)$ , accepted if  $T_{in} < t_{in}(\alpha)$ , and

$$\sup_{\theta_0 \in \Theta_0} P_{\theta_0}(T_{in} > t_{in}(\alpha)) \leq \alpha \leq \sup_{\theta_0 \in \Theta_0} P_{\theta_0}(T_{in} \geq t_{in}(\alpha)). \quad (\text{A.1})$$

**Definition 11** For each  $\alpha, \beta \in (0, 1)$  and  $\theta \in \Theta - \Theta_0$ , let  $N_i(\alpha, \beta, \theta)$  be the largest sample size such that the power at  $\theta$  of the size  $\alpha$  test based on  $\{T_{in}\}_{n=1}^\infty$  is less than  $\beta$ .

The finite sample relative efficiency of  $\{T_{1n}\}_{n=1}^\infty$  with respect to  $\{T_{2n}\}_{n=1}^\infty$  is denoted by  $N_2(\alpha, \beta, \theta)/N_1(\alpha, \beta, \theta)$ . A value larger than 1 indicates that  $\{T_{1n}\}_{n=1}^\infty$  is preferred to  $\{T_{2n}\}_{n=1}^\infty$ , since  $\{T_{1n}\}_{n=1}^\infty$  needs less observations for the same performance.

**Definition 12**  $\{T_{in}\}_{n=1}^\infty$  is said to be a standard sequence if the following three conditions are satisfied.

- a There exists a nondecreasing function  $G_i$  such that  $\inf_{\theta_0 \in \Theta_0} P_{\theta_0}(T_{in} \leq t)$  tends to  $G_i(t)$  for all continuity points of  $G_i$ .
- b There exists a constant  $a_i > 0$  such that

$$\lim_{t \rightarrow \infty} t^{-2} \log(1 - G_i(t)) = -a_i/2. \tag{A.2}$$

- c There exists a positive function  $b_i(\theta)$  such that  $|n^{-1/2}T_{in} - b_i(\theta)|$  converges to zero in  $P_\theta$ -probability for every  $\theta \in \Theta - \Theta_0$ .

The approximate Bahadur slope of a standard sequence  $\{T_{in}\}_{n=1}^\infty$  is defined as  $a_i(b_i(\theta))^2$ . The approximate Bahadur efficiency of a standard sequence  $\{T_{1n}\}_{n=1}^\infty$  with respect to another standard sequence  $\{T_{2n}\}_{n=1}^\infty$  is defined as the ratio of their respective Bahadur slopes  $a_1(b_1(\theta))^2/[a_2(b_2(\theta))^2]$ .

This is a slightly weaker form of the definition of standard sequences given in Bahadur (1960), not requiring continuity of  $G_i$ .

For a standard sequence  $\{T_{in}\}_{n=1}^\infty$  define for each  $0 < \alpha < 1$

$$\underline{q}_i(\alpha) = \inf\{t : 1 - G_i(t) \leq \alpha\}, \quad \bar{q}_i(\alpha) = \sup\{t : 1 - G_i(t) \geq \alpha\}. \tag{A.3}$$

By this definition and the monotonicity of  $G_i$  we obtain

$$\begin{aligned} 1 - G_i(t) > \alpha & \text{ for all } t < \underline{q}_i(\alpha), & 1 - G_i(t) \geq \alpha & \text{ for all } t < \bar{q}_i(\alpha), \\ 1 - G_i(t) \leq \alpha & \text{ for all } t > \underline{q}_i(\alpha), & 1 - G_i(t) > \alpha & \text{ for all } t > \bar{q}_i(\alpha). \end{aligned}$$

It is easily seen that

$$\underline{q}_i(\alpha) \leq \bar{q}_i(\alpha). \tag{A.4}$$

In view of Definition 12a, denote for each  $\epsilon > 0$  and  $0 < \alpha < 1$  by  $\bar{n}_i = \bar{n}_i(\alpha, \epsilon)$  the smallest number such that for all  $n \geq \bar{n}_i(\alpha, \epsilon)$

$$1 - \inf_{\theta_0 \in \Theta_0} P_{\theta_0}(T_{in} \leq \bar{q}_i(\alpha)(1 + \epsilon)^{1/2}) < \alpha. \tag{A.5}$$

Similarly denote for each  $\epsilon > 0$  and  $0 < \alpha < 1$  by  $\underline{n}_i = \underline{n}_i(\alpha, \epsilon)$  the smallest number such that for all  $n \geq \underline{n}_i(\alpha, \epsilon)$

$$1 - \inf_{\theta_0 \in \Theta_0} P_{\theta_0}(T_{in} < \underline{q}_i(\alpha)(1 - \epsilon)^{1/2}) > \alpha. \quad (\text{A.6})$$

Define  $n_i(\alpha, \epsilon)$  by

$$n_i(\alpha, \epsilon) = \max(\bar{n}_i(\alpha, \epsilon), \underline{n}_i(\alpha, \epsilon)). \quad (\text{A.7})$$

Finally we present the weaker form of Wieand's Condition III\*.

**Definition 13** A standard sequence  $\{T_{in}\}_{n=1}^{\infty}$  is said to be a  $\{s_n\}_{n=1}^{\infty}$ -Wieand sequence if there is a constant  $\epsilon_i^* > 0$  such that for every  $\epsilon > 0$  and  $\delta \in (0, 1)$  there exists a constant  $C_i(\epsilon, \delta)$  such that

$$P_{\theta}(|n^{-1/2}T_{in} - b_i(\theta)| \geq \epsilon b_i(\theta)) < \delta \quad (\text{A.8})$$

for every  $\theta \in \Theta - \Theta_0$  satisfying  $\inf_{\theta_0 \in \Theta_0} d(\theta, \theta_0) < \epsilon_i^*$  and  $n^{1/2}b_i(\theta) > C_i(\epsilon, \delta)s_n$ .

It can be shown that a standard sequence  $\{T_{in}\}_{n=1}^{\infty}$  is a  $\{s_n\}_{n=1}^{\infty}$ -Wieand sequence if there exists a nondefective cumulative distribution function  $Q$  such that

$$P_{\theta}(|T_{in} - n^{1/2}b_i(\theta)| > xs_n) \leq 1 - Q(x) \quad (\text{A.9})$$

for every  $x > 0$  and  $\theta \in \Theta - \Theta_0$  satisfying  $\inf_{\theta_0 \in \Theta_0} d(\theta, \theta_0) < \epsilon_i^*$  [choose  $C_i(\epsilon, \delta)$  so as to satisfy  $Q(\epsilon C_i(\epsilon, \delta)) > 1 - \delta$ ]. Remark that if  $s_n$  remains bounded, Definition 13 reduces to Wieand's Condition III\* [in case of a simple null hypothesis], and the observation above is a consequence of the lemma given in section 4 in Wieand (1976). In the sequel we shall use the phrase "under Wieand's Condition III\*" to indicate that  $s_n$  remains bounded, thereby tacitly extending Wieand's original definition to general null hypotheses.

We close this section by introducing a set which plays a role in section A.3. For each  $\alpha, \epsilon, \delta \in (0, 1)$  let  $A(\alpha, \epsilon, \delta)$  be the set of points  $\theta \in \Theta - \Theta_0$  for which

$$n \geq \frac{-\log \alpha}{a_i \{b_i(\theta)\}^2} \quad \text{implies} \quad n^{1/2}b_i(\theta) > C_i(\epsilon, \delta)s_n \quad (\text{A.10})$$

for  $i = 1, 2$ . Lemma 5 sheds light on the relation between the set  $A(\alpha, \epsilon, \delta)$  and Wieand's Condition III\*. Observe that in case we have

$$\inf_{\theta \in \Theta - \Theta_0} b_i(\theta) = 0,$$

this lemma implies that  $A(\alpha, \epsilon, \delta)$  equals  $\Theta - \Theta_0$  for  $\alpha$  sufficiently small if and only if  $s_n$  is bounded.

**Lemma 5** If  $s_n$  remains bounded then for every  $\epsilon, \delta > 0$  there exists  $\alpha(\epsilon, \delta) > 0$  such that  $A(\alpha, \epsilon, \delta)$  coincides with  $\Theta - \Theta_0$  for every  $0 < \alpha < \alpha(\epsilon, \delta)$ . If  $\inf_{\theta \in A(\alpha, \epsilon, \delta)} b_i(\theta) = 0$  for some  $\alpha, \epsilon, \delta > 0$ , then  $s_n$  remains bounded.

### A.3 Results

Our main result is the following theorem, which shows where the finite sample relative efficiency  $N_2(\alpha, \beta, \theta)/N_1(\alpha, \beta, \theta)$  may be approximated by the approximate Bahadur efficiency  $a_1\{b_1(\theta)\}^2/[a_2\{b_2(\theta)\}^2]$ . (If limits are taken with  $\theta$  tending to some subset of  $\Theta_0$ , then of course  $\theta$  runs through  $\Theta - \Theta_0$ ; further the notation is explained in section A.2.)

**Theorem 14** *Let  $\{T_{1n}\}_{n=1}^\infty$  and  $\{T_{2n}\}_{n=1}^\infty$  be two  $\{s_n\}_{n=1}^\infty$ -Wieand sequences, and let  $\Theta_0^*$  be a subset of  $\Theta_0$ . Suppose that the limit*

$$\lim_{\theta \rightarrow \Theta_0^*} a_1\{b_1(\theta)\}^2/[a_2\{b_2(\theta)\}^2] =: e(\Theta_0^*) \quad (\text{A.11})$$

*exists. For each  $\alpha, \epsilon, \delta \in (0, 1)$ , let  $A^*(\alpha, \epsilon, \delta)$  be a subset of  $A(\alpha, \epsilon, \delta)$  satisfying*

$$\lim_{\epsilon \rightarrow 0} \limsup_{\alpha \rightarrow 0} \sup_{\theta \in A^*(\alpha, \epsilon, \delta)} \inf_{\theta_0 \in \Theta_0^*} d(\theta, \theta_0) = 0. \quad (\text{A.12})$$

*Assume that*

$$\limsup_{\epsilon \rightarrow 0} \limsup_{\alpha \rightarrow 0} \sup_{\theta \in A^*(\alpha, \epsilon, \delta)} \frac{n_i(\alpha, \epsilon)}{\left[\frac{-2 \log \alpha}{a_i\{b_i(\theta)\}^2}\right]} < 1. \quad (\text{A.13})$$

*Then for  $\beta \in [\delta, 1 - \delta]$  we have*

$$\lim_{\epsilon \rightarrow 0} \liminf_{\alpha \rightarrow 0} \inf_{\theta \in A^*(\alpha, \epsilon, \delta)} \frac{N_2(\alpha, \beta, \theta)}{N_1(\alpha, \beta, \theta)} = \lim_{\epsilon \rightarrow 0} \limsup_{\alpha \rightarrow 0} \sup_{\theta \in A^*(\alpha, \epsilon, \delta)} \frac{N_2(\alpha, \beta, \theta)}{N_1(\alpha, \beta, \theta)} = e(\Theta_0^*). \quad (\text{A.14})$$

When considering a specified trajectory  $\theta(\alpha, \epsilon, \delta)$ , along which  $\Theta_0^*$  is approached as  $\alpha \rightarrow 0$ , it seems obvious to choose  $A^*(\alpha, \epsilon, \delta)$  equal to the singleton containing  $\theta(\alpha, \epsilon, \delta)$ .

If Wieand's Condition III\* does not hold, the requirement that  $\theta(\alpha, \epsilon, \delta)$  should be an element of  $A(\alpha, \epsilon, \delta)$  limits the trajectories admitted for a fixed  $\epsilon > 0$ . The lower  $\epsilon$ , the smaller the area through which the trajectories are allowed to run. As already observed in section A.2, this is reflected in Figure A.3 by a lowering of the curve. For instance, if  $n^{1/2}/s_n$  is a monotone increasing function  $g$  of  $n$ , condition (A.10) holds if and only if

$$g\left(\frac{-\log \alpha}{a_i\{b_i(\theta)\}^2}\right) b_i(\theta) > C_i(\epsilon, \delta)$$

for  $i = 1, 2$ .

If Wieand's Condition III\* does hold, the set  $A(\alpha, \epsilon, \delta)$  equals  $\Theta - \Theta_0$  if  $0 < \alpha < \alpha(\epsilon, \delta)$ , where  $\alpha(\epsilon, \delta)$  is given by Lemma 5. It now easily follows that for every sequence  $\{(\theta_j, \alpha_j)\}_{j=1}^\infty$  tending to  $(\Theta_0^*, 0)$  we obtain

$$\frac{N_2(\alpha_j, \beta, \theta_j)}{N_1(\alpha_j, \beta, \theta_j)} \rightarrow e(\Theta_0^*), \quad (\text{A.15})$$

provided that

$$\limsup_{\epsilon \rightarrow 0} \lim_{j \rightarrow \infty} \frac{n_i(\alpha_j, \epsilon)}{\left[ \frac{-2 \log \alpha_j}{a_i \{b_i(\theta_j)\}^2} \right]} < 1,$$

as is formally seen by taking  $A^*(\alpha, \epsilon, \delta)$  equal to  $\{\theta_j\}$  if  $\alpha_j \leq \alpha < \alpha_{j-1}$ ,  $j = 1, 2, \dots$  [ $\alpha_0 = 1$ ]. This is closely related to intermediate efficiency [cf. Kallenberg (1983)].

Another consequence of Lemma 5 is that under Wieand's Condition III\* we may take  $A^*(\alpha, \epsilon, \delta)$  to be the intersection of  $\Theta - \Theta_0$  with an arbitrary environment of  $\Theta_0^*$ , shrinking to  $\Theta_0^*$  as  $\alpha \rightarrow 0$ , and [afterwards]  $\epsilon \rightarrow 0$ . More precisely, let

$$A^*(\alpha, \epsilon, \delta) = \{\theta \in A(\alpha, \epsilon, \delta) : \inf_{\theta_0 \in \Theta_0^*} d(\theta, \theta_0) < \epsilon, \frac{n_i(\alpha, \epsilon)}{1 + \epsilon} < \frac{-2 \log \alpha}{a_i \{b_i(\theta)\}^2}\}.$$

Then (A.12) and (A.13) are satisfied. Now consider a sequence  $\{\theta_j\}_{j=1}^\infty$  which tends to  $\Theta_0^*$  as  $j \rightarrow \infty$ . Assume that

$$\lim_{j \rightarrow \infty} b_i(\theta_j) = 0.$$

Let  $\alpha, \epsilon, \delta > 0$  satisfy  $\alpha < \alpha(\epsilon, \delta)$ , with  $\alpha(\epsilon, \delta)$  as in Lemma 5. Then there exists  $j(\alpha, \epsilon, \delta)$  such that for all  $j \geq j(\alpha, \epsilon, \delta)$  we have  $\theta_j \in A^*(\alpha, \epsilon, \delta)$ , and hence it follows that

$$\begin{aligned} \inf_{\theta \in A^*(\alpha, \epsilon, \delta)} \frac{N_2(\alpha, \beta, \theta)}{N_1(\alpha, \beta, \theta)} &\leq \liminf_{j \rightarrow \infty} \frac{N_2(\alpha, \beta, \theta_j)}{N_1(\alpha, \beta, \theta_j)} \\ &\leq \limsup_{j \rightarrow \infty} \frac{N_2(\alpha, \beta, \theta_j)}{N_1(\alpha, \beta, \theta_j)} \leq \sup_{\theta \in A^*(\alpha, \epsilon, \delta)} \frac{N_2(\alpha, \beta, \theta)}{N_1(\alpha, \beta, \theta)}. \end{aligned} \quad (\text{A.16})$$

Applying Theorem 14 we get

$$\begin{aligned} e(\Theta_0^*) &= \lim_{\epsilon \rightarrow 0} \liminf_{\alpha \rightarrow 0} \inf_{\theta \in A^*(\alpha, \epsilon, \delta)} \frac{N_2(\alpha, \beta, \theta)}{N_1(\alpha, \beta, \theta)} \\ &\leq \liminf_{\alpha \rightarrow 0} \liminf_{j \rightarrow \infty} \frac{N_2(\alpha, \beta, \theta_j)}{N_1(\alpha, \beta, \theta_j)} \leq \limsup_{\alpha \rightarrow 0} \limsup_{j \rightarrow \infty} \frac{N_2(\alpha, \beta, \theta_j)}{N_1(\alpha, \beta, \theta_j)} \\ &\leq \lim_{\epsilon \rightarrow 0} \limsup_{\alpha \rightarrow 0} \sup_{\theta \in A^*(\alpha, \epsilon, \delta)} \frac{N_2(\alpha, \beta, \theta)}{N_1(\alpha, \beta, \theta)} = e(\Theta_0^*) \end{aligned}$$

and therefore

$$\lim_{\alpha \rightarrow 0} \lim_{j \rightarrow \infty} \frac{N_2(\alpha, \beta, \theta_j)}{N_1(\alpha, \beta, \theta_j)} = e(\Theta_0^*).$$

Since the sequence  $\{\theta_j\}_{j=1}^\infty$  was arbitrarily chosen, it follows that

$$\lim_{\alpha \rightarrow 0} \lim_{\theta \rightarrow \Theta_0^*} \frac{N_2(\alpha, \beta, \theta)}{N_1(\alpha, \beta, \theta)} = e(\Theta_0^*).$$

This extends Wieand's theorem to testing problems with composite null hypotheses. Moreover, note that Wieand's conditions on continuity and monotonicity are not needed to obtain this result.

There exist alternative definitions of limiting Pitman efficiency which involve  $\underline{N}_i(\alpha, \beta, \theta)$ , the smallest sample size such that the power at  $\theta$  of the size  $\alpha$  test based on  $\{T_{in}\}_{n=1}^{\infty}$  is greater than or equal to  $\beta$ . Observe that there is a disproportionate effect of the behavior of  $T_{i1}$  on  $\underline{N}_i(\alpha, \beta, \theta)$ . Definition 13 only has meaning for sample sizes which are sufficiently large, and is therefore not capable of providing lower bounds for  $\underline{N}_i(\alpha, \beta, \theta)$ . It follows that the fact that  $\{T_{in}\}_{n=1}^{\infty}$  is a  $\{s_n\}_{n=1}^{\infty}$ -Wieand sequence does not shed light on asymptotic relative Pitman efficiency as defined in for instance Rothe (1981).

In absence of Wieand's Condition III\* the verification of (A.13) requires some effort. In case the test statistics are functionals of either the empirical process or the partial sum process, the approximation theorems available for these processes [see Komlós, Major and Tusnády (1975)] may lead to probability inequalities of the type considered in the following lemma.

**Lemma 6** *Suppose that  $\{T_{in}\}_{n=1}^{\infty}$  is a standard sequence for which there exist a random variable  $T_i$  with distribution function  $G_i$ , positive constants  $\tau, \gamma, \lambda$  and a sequence  $k_n = o(n^{\gamma/\tau})$  such that*

$$\sup_{\theta_0 \in \Theta_0} P_{\theta_0}(|T_{in} - T_i| > n^{-\gamma}(k_n + x)^\tau) \leq e^{-\lambda x}. \quad (\text{A.17})$$

*Then for every  $\epsilon > 0$  there exist a constant  $c(\epsilon)$  such that (A.13) holds for*

$$A^*(\alpha, \epsilon, \delta) = \{\theta \in A(\alpha, \epsilon, \delta) : a_i\{b_i(\theta)\}^2 < |\log \alpha|^{1-\tau/\gamma}/c(\epsilon)\}.$$

Typically, one finds  $\gamma \leq 1/2$ ,  $\tau \geq 1$  and  $k_n$  proportional to  $\log n$  [see Chapters 2-4, Koning (1993), and Csörgő and Horváth (1993)].

The magnitude of  $k_n$  allowed in Lemma 6 strongly suggests that it is essentially the tail rather than the center of the distribution of  $n^\gamma|T_{in} - T_i|$  which determines the shape of  $A^*(\alpha, \epsilon, \delta)$ .

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  - intermediate, 33, 66
- square of a matrix, 54
- standard sequence, 32, 64, 146
- standardizing the weight process, 61
- Strassen functions, 21, 28, 60
- sublinear functional, 20
- supremum functional, 8
- supremum type test, 8
- test of Breslow, 8, 100
- total time on test plots, 94
- uncensored observation, 4
  - under  $P_0$ , 23
  - under  $P_n$ , 23, 52
  - under  $P_{v_0}$ , 52
- weak asymptotic intermediate efficiency,
  - 3, 33, 66
- weak asymptotic intermediate slope, 33, 66
- Wieand sequence, 32, 64, 147
- Wieand's condition, 143, 148
- Wieand's Theorem, 32
  - adapted, 65
- Woolson data, 6, 89
- $\chi^2$  test, 2

## List of Symbols

- $a$  constant describing [asymptotic] tail behavior of  $T(Q_n(\cdot)/q(\cdot))$ , 28  
 $a_R$  constant describing tail behavior of  $T_R(Q_n)$ , 34  
 $a_R(v_0)$  constant describing tail behavior of  $T_R(Q_n(\cdot; v_0))$ , 66  
 $a_S$  constant describing tail behavior of  $T_S(Q_n)$ , 34  
 $a_S(v_0)$  constant describing tail behavior of  $T_S(Q_n(\cdot; v_0))$ , 66  
 $\tilde{a}(v_0)$  constant reflecting [asymptotic] tail behavior of  $Q_n(t; v^{(n)})$ , 60  
 $B_n^1(t)$  Gaussian process used to construct  $W_n(t)$ , 37  
 $B_n(t)$  Gaussian process used to construct  $W_n(t)$ , 37  
 $\tilde{B}_n(t)$  Brownian bridge approximating  $\tilde{U}_n(t)$ , 19  
 $D(t; \theta_0, \theta)$  function reflecting distance between  $F(t; \theta)$  and  $F(t; \theta_0)$ , 24  
 $D(t; v', \theta_0, v, \theta)$  function reflecting distance between  $\Lambda(t; v, \theta)$  and  $\Lambda(s; v', \theta_0)$ , 54  
 $D(t; v, \theta)$  abbreviation for  $D(t; \pi(v, \theta), \theta_0, v, \theta)$ , 54  
 $D[0, \infty)$  function space, 20  
 $e(h)$  limiting approximate Bahadur, limiting asymptotic relative Pitman and weak intermediate efficiency of test based on  $T(Q_n(\cdot)/q(\cdot))$ , 33  
 $e(h; v_0)$  limiting approximate Bahadur, limiting asymptotic relative Pitman and weak intermediate efficiency of  $T(Q_n(\cdot; v^{(n)}))$ , 65  
 $e_R(h)$  asymptotic relative Pitman, limiting approximate Bahadur and weak intermediate efficiency of test based on  $T_R(Q_n)$ , 34  
 $e_R(h, v_0)$  asymptotic relative Pitman, limiting approximate Bahadur and weak intermediate efficiency of  $T_R(Q_n(\cdot; v_0))$ , 66  
 $e_S(h)$  limiting approximate Bahadur, limiting asymptotic relative Pitman and weak intermediate efficiency of test based on  $T_S(Q_n)$ , 34  
 $e_S(h, v_0)$  limiting approximate Bahadur, limiting asymptotic relative Pitman, and weak intermediate efficiency of  $T_S(Q_n(\cdot; v_0))$ , 66  
 $e_{12}^{\hat{\beta}}(h)$  asymptotic relative Pitman efficiency in the direction  $h$ , 31  
 $e_{12}^{\hat{\beta}}(h; v_0)$  asymptotic relative Pitman efficiency, 64  
 $\mathcal{E}_0$  expectation under  $P_0$ , 23  
 $\mathcal{E}_n$  expectation under  $P_n$ , 23, 52  
 $\mathcal{E}_{v_0}$  expectation under  $P_{v_0}$ , 51  
 $F(t)$  cumulative distribution function of  $X_i$ , 2  
 $F(t; \theta_n)$  cumulative distribution function, simple null hypothesis, 5, 23  
 $F(t; v_n, \theta_n)$  cumulative distribution function of  $X_i$ , composite null hypothesis, 51  
 $F_n(t)$  empirical distribution function, 2  
 $G(t)$  cumulative distribution function of  $Y_i$ , 23, 51



- $H(t; \theta_n)$  cumulative distribution function of  $Z_1$  under  $P_n$ , simple null hypothesis, 24  
 $H(t; v_n, \theta_n)$  cumulative distribution function of  $Z_1$  under  $P_n$ , 53  
 $H^0(t; \theta_n)$  cumulative distribution function of censored failure times, 36  
 $H^0(t; v_n, \theta_n)$  cumulative distribution function of censored failure times, 72  
 $H^1(t; \theta_n)$  cumulative distribution function of observed failure times under  $P_n$ , simple null hypothesis, 5, 24  
 $H^1(t; v_n, \theta_n)$  cumulative distribution function of observed failure times under  $P_n$ , composite null hypothesis, 53  
 $H_n^1(t)$  empirical distribution function of observed failure times, 4  
 $H_n(t)$  empirical distribution function of all observations, 4  
 $I(\theta_0)$  Fisher information matrix, simple null hypothesis, 35  
 $I(v_0, \theta_0)$  Fisher information matrix, composite null hypothesis, 67  
 $I_{00}$   $r \times r$  submatrix of  $I(v_0, \theta_0)$ , 67  
 $I_{0a}$   $r \times p$  submatrix of  $I(v_0, \theta_0)$ , 67  
 $I_{a0}$   $p \times r$  submatrix of  $I(v_0, \theta_0)$ , 67  
 $I_{aa}$   $p \times p$  submatrix of  $I(v_0, \theta_0)$ , 67  
 $J_n(t)$  jump process approximating  $W_n(t)$ , 38  
 $K_0(t; v, \theta)$   $r$ -dimensional vector function describing effect of  $v^{(n)}$  on behavior  $Q_n(t; v^{(n)})$ , 57  
 $K_a(t)$   $p$ -dimensional vector function, 30  
 $K_{a|0}(t; v_0)$   $p$ -dimensional vector function, 62  
 $\tilde{K}(t, n)$  Kiefer process approximating  $\tilde{U}_n(t)$ , 19  
 $L(t; \theta_n)$  deterministic function approximating  $L_n(t)$  under  $P_n$ , 26  
 $L(t; v, \theta)$  limiting function of  $L_n(t; v)$ , 57  
 $L_i^{(1)}(t; \theta)$  first order partial derivative of  $L(t; \theta)$  with respect to the  $i^{th}$  component of  $\theta$ , 30  
 $L_i^{(1)}(t; v, \theta)$  first order partial derivative of  $L(t; v, \theta)$  with respect to the  $i^{th}$  component of  $(v, \theta)$ , 62  
 $L_{ni}^{(1)}(t; v)$  first order partial derivative of  $L_n(t; v)$  with respect to the  $i^{th}$  component of  $v$ , 57  
 $L_{ij}^{(2)}(t; \theta)$  second order partial derivative of  $L(t; \theta)$  with respect to the  $i^{th}$  and  $j^{th}$  components of  $\theta$ , 30  
 $L_{ij}^{(2)}(t; v, \theta)$  second order partial derivative of  $L(t; v, \theta)$  with respect to the  $i^{th}$  and  $j^{th}$  components of  $(v, \theta)$ , 62  
 $L_{nij}^{(2)}(t; v)$  second order partial derivative of  $L_n(t; v)$  with respect to the  $i^{th}$  and  $j^{th}$  components of  $v$ , 75  
 $L_i^{[1]}(t; v, \theta)$  limiting function of  $L_{ni}^{(1)}(t; v)$ , 57  
 $L_0(s, t; v_0)$  version of  $L(s; v_0, \theta_0, v_0, \theta_0)$ , in which the influence of the M-estimator at the stochastic integral evaluated at point  $t$  is accounted for, 58  
 $L_n(t)$  weight process, integrand stochastic integral  $Q_n(t)$ , 24  
 $L_n(t; v)$  weight process, integrand stochastic integral  $Q_n(t; v)$ , 52  
 $M_n(t; \theta_0)$  basic martingale, simple null hypothesis, 5, 23  
 $M_n(t; v_0, \theta_0)$  basic martingale, composite null hypothesis, 52  
 $\underline{N}_i^{\tilde{\beta}}(\theta)$  smallest sample size such that the power of the test is at least as desired under  $P_\theta$ , 31  
 $\underline{N}_i^{\tilde{\beta}}(v, \theta)$  smallest sample size such that the power of the test is at least as desired under  $P_{(v, \theta)}$ , 64  
 $\overline{N}_i^{\tilde{\beta}}(\theta)$  largest sample size such that the power of the test is less than desired under  $P_\theta$ , 31

- $\bar{N}_i^{\tilde{\beta}}(v, \theta)$  largest sample size such that the power of the test is less than desired under  $P_{(v, \theta)}$ , 63
- $P_0$  probability measure under the null hypothesis, simple null hypothesis, 23
- $P_n$  actual probability measure, 23, 51
- $P_{(v, \theta)}$  probability measure under fixed alternative  $v_n = v$  and  $\theta_n = \theta$ , 61
- $P_\theta$  probability measure under fixed alternative  $\theta_n = \theta$ , 29
- $P_{v_0}$  probability measure under the null hypothesis, composite null hypothesis, 51
- $Q_n^{(1)}(t; v)$   $r$ -dimensional vector with elements  $Q_{ni}^{(1)}(t; v)$ , 76
- $Q_{ni}^{(1)}(t; v)$  first order partial derivative of  $Q_n(t; v)$  with respect to the  $i^{\text{th}}$  component of  $v$ , 75
- $Q_n^{(2)}(t; v)$   $r \times r$  matrix with elements  $Q_{nij}^{(2)}(t; v)$ , 76
- $Q_{nij}^{(2)}(t; v)$  second order partial derivative of  $Q_n(t; v)$  with respect to the  $i^{\text{th}}$  and  $j^{\text{th}}$  components of  $v$ , 75
- $Q_n(t)$  stochastic integral with respect to  $M_n(t; \theta_0)$ , 24
- $Q_n(t; v)$  stochastic integral with respect to  $M_n(t; v, \theta_0)$ , 52
- $\tilde{Q}_{ni}^{(1)}(t; v)$  approximation of  $Q_{ni}^{(1)}(t; v)$ , 75
- $\tilde{Q}_{nij}^{(2)}(t; v)$  approximation of  $Q_{nij}^{(2)}(t; v)$ , 75
- $R_n(v)$   $r$ -dimensional function derived from M-equations, satisfying  $v^{(n)} = R_n(v^{(n)})$ , 71
- $\mathcal{S}$  set of Strassen functions, 21
- $S_n$  random variable describing behavior of M-estimator, 55, 70
- $T_R$  generalized rank functional, 8
- $T_S$  supremum functional, 8
- $U_n^1(t; \theta_n)$  empirical process based on  $H_n^1(t)$ , 24
- $U_n^1(t; v_n, \theta_n)$  empirical process, 70
- $U_n(t)$  empirical process, 2
- $U_{n-}(t; \theta_n)$  empirical process based on  $H_{n-}(t)$ , 24
- $U_{n-}(t; v_n, \theta_n)$  empirical process, 70
- $\tilde{U}_n(t)$  uniform empirical process, 17, 72
- $V_n$  closed ball in  $\Upsilon$  with centre  $v_{n0}$  and radius  $c_{59}$ , 70
- $W(t)$  standard Wiener process, 20
- $W_n(t)$  Gaussian process approximating [a centered version of] the basic martingale, 26, 37
- $W_n(t; v_{n0})$  mean zero Gaussian processes involved in approximation of  $Q_n(t; v^{(n)})$ , 58
- $X(t; \theta_0)$  limit in  $P_0$ -distribution of  $Q_n(t)$  in  $q$ -metric, 27
- $X_i$  failure time, 4
- $\tilde{X}(t; v_n, \theta_n)$  mean zero Gaussian process approximating centered version of  $Q_n(t; v^{(n)})$ , 59, 78
- $Y_i$  censoring time, 4
- $Z_i$  censored failure time, 4
- $\tilde{Z}_i$  transformation of  $(Z_i, \delta_i)$  to standard uniform random variable, 36, 72
- $\alpha$  constant, 25
- $\tilde{\beta}(\theta)$  desired power under  $P_\theta$ , 31
- $\tilde{\beta}(v, \theta)$  desired power under  $P_{(v, \theta)}$ , 63
- $\delta_i$  censoring indicator, 4
- $\theta_0$  value of parameter of interest under the null hypothesis, 23, 51
- $\theta_n$  actual value of parameter of interest, 23, 51
- $\theta$  parameter of interest, 23, 51
- $\lambda(t; \theta)$  hazard function, simple null hypothesis, 8, 29
- $\lambda(t; v, \theta)$  hazard function, composite null hypothesis, 53
- $\Lambda(t; \theta)$  cumulative hazard function belonging to  $X_i$ , simple null hypothesis, 5, 23

- $\Lambda(t; v, \theta)$  cumulative hazard function belonging to  $F(t; v, \theta)$ , composite null hypothesis, 52
- $\Lambda_i^{(1)}(t; v, \theta)$  first order partial derivative of  $\Lambda(t; v, \theta)$  with respect to the  $i^{\text{th}}$  component of  $(v, \theta)$ , 62
- $\mu_\beta(v)$  integral, 88
- $\hat{\mu}_\beta(v)$  estimator of  $\mu_\beta(v)$ , 93
- $\Xi_0(v, \theta)$   $r \times r$  matrix describing the behavior of M-estimator, 54
- $\Xi_b(v, \theta)$   $r \times r$  matrix, 62
- $\Xi_{0n}$  abbreviation for  $\Xi_0(v_n, \theta_n)$ , 55
- $\pi(v, \theta)$  projection related to M-estimator, mapping  $\Upsilon \times \Theta$  into  $\Upsilon$ , 54
- $\Sigma_{e0}$  abbreviation for  $\Xi_0(v_0, \theta_0)$ , 55
- $\Sigma_{ee}$  covariance matrix of  $\tilde{\Phi}_n$ , 56
- $v^{(n)}$  M-estimator, 52
- $v_0$  value of nuisance parameter under  $P_{v_0}$ , 51
- $v_n$  actual value of nuisance parameter, 51
- $v_{n0}$  abbreviation for  $\pi(v_n, \theta_n)$ , 55
- $v$  nuisance parameter, 51
- $\phi(t; v)$   $r$ -dimensional vector with elements  $\phi_i(t; v)$ , 55
- $\phi_{ijk}^{(2)}(t; v)$  second order partial derivative of  $\phi_i(t; v)$  with respect to the  $j^{\text{th}}$  and the  $k^{\text{th}}$  components of  $v$ , 69
- $\phi_i(t; v)$  function used for constructing an M-estimator, 53
- $\Phi_n^{(1)}(v)$   $r \times r$  matrix with elements  $\Phi_{nij}^{(1)}(v)$ , 69
- $\Phi_{nij}^{(1)}(v)$  first order partial derivative of  $\Phi_{ni}(v)$  with respect to the  $j^{\text{th}}$  component of  $v$ , 69
- $\Phi_{ni}^{(1)}(v_{n0})$   $i^{\text{th}}$  row of  $\Phi_n^{(1)}(v_{n0})$ , 70
- $\Phi_{nij}^{(2)}(v)$  second order partial derivative of  $\Phi_{ni}(v)$  with respect to the  $j^{\text{th}}$  and  $k^{\text{th}}$  components of  $v$ , 69
- $\Phi_{ni}^{(2)}(v)$   $r \times r$  matrix with elements  $\Phi_{nij}^{(2)}(v)$ , 69
- $\Phi_{ni}(v)$  shorthand notation for  $\Phi_{ni}(\infty; v)$ , 69
- $\Phi_{ni}(t; v)$  stochastic integral with integrand  $\phi_i(t; v)$ , involved in equations determining M-estimator, 53
- $\tilde{\Phi}_n$   $r$ -dimensional Gaussian random vector approximating  $n^{1/2}\Sigma_{e0}(v^{(n)} - v_{n0})$ , 56
- $\psi(t; v, \theta)$   $r$ -dimensional vector with components  $\psi_i(t; v, \theta)$ , 58
- $\psi_{ij}^{(1)}(t; \theta)$  second order partial derivative of  $\lambda(t; \theta)$  with respect to the  $i^{\text{th}}$  and  $j^{\text{th}}$  components of  $\theta$ , 29
- $\psi_{jk}^{(1)}(t; v)$  first order partial derivative of  $\psi_j(t; v)$  with respect to the  $k^{\text{th}}$  component of  $v$ , 69
- $\psi_a(t; \theta_0)$  score function, simple null hypothesis, 8
- $\psi_a(t; v_0, \theta_0)$   $p$ -dimensional vector function with elements  $\psi_{r+i}(t; v_0, \theta_0)$ , 62
- $\psi_i(t; \theta)$  first order partial derivative of  $\lambda(t; \theta)$  with respect to the  $i^{\text{th}}$  component of  $\theta$ , 29
- $\psi_i(t; v, \theta)$  first order partial derivative of  $\lambda(t; v, \theta)$  with respect to the  $i^{\text{th}}$  component of  $(v, \theta)$ , 53
- $\psi_{a|0}(t; v_0, \theta_0)$  effective score function, 67
- $\Omega_n$  subset of  $\Omega$ , 76
- $(\Omega, \mathcal{A}, \mathcal{P})$  underlying probability space, 17, 23, 51



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