

Column Imprints: A Secondary Index Structure

Lefteris Sidirouros
CWI
Amsterdam, The Netherlands
lsidir@cwi.nl

Martin Kersten
CWI
Amsterdam, The Netherlands
mk@cwi.nl

ABSTRACT

Large scale data warehouses rely heavily on secondary indexes, such as bitmaps and b-trees, to limit access to slow IO devices. However, with the advent of large main memory systems, cache conscious secondary indexes are needed to improve also the transfer bandwidth between memory and cpu. In this paper, we introduce *column imprint*, a simple but efficient cache conscious secondary index. A column imprint is a collection of many small bit vectors, each indexing the data points of a single cacheline. An imprint is used during query evaluation to limit data access and thus minimize memory traffic. The compression for imprints is cpu friendly and exploits the empirical observation that data often exhibits local clustering or partial ordering as a side-effect of the construction process. Most importantly, column imprint compression remains effective and robust even in the case of unclustered data, while other state-of-the-art solutions fail. We conducted an extensive experimental evaluation to assess the applicability and the performance impact of the column imprints. The storage overhead, when experimenting with real world datasets, is just a few percent over the size of the columns being indexed. The evaluation time for over 40000 range queries of varying selectivity revealed the efficiency of the proposed index compared to zonemaps and bitmaps with WAH compression.

Categories and Subject Descriptors

H.3 [Information Storage and Retrieval]: Content Analysis and Indexing

Keywords

Secondary Index; Columnar Databases;

1. INTRODUCTION

Indexes are a vital component of a database system. They allow the system to efficiently locate and retrieve data that is relevant to the users' queries. Despite the large body of research literature, just a few solutions have found their respective places in a database

system [3, 10, 12, 19]. Nevertheless, the pursuit for more efficient and succinct indexing structures remains.

Indexes are divided into *primary* and *secondary* according to their ability to govern the placement of the data. Primary indexes combine navigational structures with physical data clustering to achieve fast access. The benefit is that relevant data is placed in adjacent pages and thus significantly improving the evaluation of range queries. However, each additional primary index on the same relation calls for a complete copy of the data, rendering the storage overhead prohibitive. Similarly, secondary indexes are auxiliary structures that speed up search, but they do not change the order of the data in the underlying physical storage. Secondary indexes are typically much smaller than the referenced data and, therefore, faster to access and query. However, retrieving the relevant data from disk can be a costly operation since it may be scattered over many pages. As long as the time to scan the secondary index is significantly less than accessing the data, and the selectivity of the query is high, secondary indexes can significantly improve the query evaluation time.

Most structures designed for primary indexing, such as B-tree and hash tables, can also be used for secondary indexing. However, they are not as lightweight as one would wish. Bitmaps, or variations of bitmaps, are more often used for this task [21]. Bitmaps work by mapping individual values to an array of bits. At query time, the bitmap is examined and whenever the bits that correspond to the query's predicates are set, the mapped data is retrieved for further processing. Bitmaps are traditionally used for attributes with low cardinality [17], although bit-binning techniques make them suitable for larger domains too [7, 20].

With the introduction of column stores and the shift of the memory bottleneck [15], the need for designing *hardware-conscious* secondary indexes becomes more evident. In a main memory DBMS, the problem of efficiently accessing disk blocks is replaced with the problem of minimizing cache misses. In addition, algorithms require a more careful implementation. There is much less design space to hide an inefficient implementation behind the latency of accessing a disk block.

A second paradigm shift concerns the volume and the nature of the data. Most notable of them all are scientific database applications that stress the limits of modern designs by including hundreds of attributes in a single relation. In addition, the value domains are often of double precision, rather than the traditional categorical ones encountered in business applications. Column stores are the prime candidates for providing solutions for such demanding applications. On high-end servers, with large main memories, it is even possible to keep many columns with billions of elements in memory over a long period of time. Nevertheless, fast access, supported

Permission to make digital or hard copies of all or part of this work for personal or classroom use is granted without fee provided that copies are not made or distributed for profit or commercial advantage and that copies bear this notice and the full citation on the first page. To copy otherwise, to republish, to post on servers or to redistribute to lists, requires prior specific permission and/or a fee.

SIGMOD'13, June 22–27, 2013, New York, New York, USA.

Copyright 2013 ACM 978-1-4503-2037-5/13/06 ...\$15.00.

by light-weight indexing structures, remains in demand to improve the interactive scientific exploration process.

To address these challenges, we propose a simple but efficient secondary indexing structure, called *column imprints*. A column imprint is a cache conscious secondary indexing structure suitable for both low and high cardinality columns. Given a column with values from domain \mathcal{D} , we derive a small sample to approximate a histogram of a few (typically 64 or less) equal-height bins. The entire column is then scanned, and for every cacheline of data, a bit vector is created. The bits in each vector correspond to the bins of the histogram. A bit is set if at least one value in the cacheline falls into the corresponding bin. The resulting bit vector is an *imprint* of the current cacheline that describes which buckets of the approximated histogram the values of the cacheline fall into. The collection of all the resulting bit vectors form a unique *column imprint*. Consequently, by examining an imprint of a column, the execution engine can decide—in a cacheline granularity—which parts of the column data are relevant to the query predicates, and only then fetch them for further processing. A column imprint is particularly suited for evaluating both range and point queries on unsorted data. Contrary to existing work, a column imprint is a *non-dense* bit indexing scheme, i.e., only one bit is set for all equal values in a cacheline, instead of the traditional approach where each data point is always mapped to a different bit.

To reduce the memory footprint of a column imprint, we introduce a simple compression scheme based on a run-length encoding of imprints. Consecutive and identical bit vectors are compressed together and annotated with a counter. Paraphrasing, our compression schema can be characterized as row-wise, i.e., it compresses bit vectors horizontally, contrary to the more common column-wise approach that partitions a bitmap vertically and compress it per column [23]. The horizontal compression exploits our empirical observation that, in most data warehouses that we explored, data suitable for secondary indexing exhibits, in the cacheline level, some degree of clustering or partial ordering. These desirable properties stem either from the regular and canonical data insertion procedure, or from the production of the data itself, or even indirectly imposed by the other primary indexed attributes of the same relation. Column imprints are designed such that any clustering or partial ordering is naturally exploited without the need for extra pasteurization. In other words, they are less susceptible to the order in which individual values appear in a cacheline, while more opportunities for compression are presented. In addition, because of this immunity to value order within a cacheline, a column imprint remains robust even in the case of highly unclustered data. We experimentally demonstrate that imprints perform well and behave as intended even in the presence of skewed data, where other state-of-the-art bitmap compression techniques, such as WAH [23], are less effective.

The contributions of our work can be summarized as follows:

- We introduce column imprints, a light-weight secondary index structure for main memory database systems.
- We detail the algorithms and the implementation details for constructing and compressing a column imprint.
- We present the algorithms to efficiently evaluate range queries with the use of column imprints.
- We study the effect on imprints when updating the values of a column.
- We quantify the amount of local clustering by introducing a metric called *column entropy*.

- We conduct an extensive comparative experimental evaluation of the imprint index structure using thousands of columns taken from several real-world datasets.

The remainder of the paper is organized as follows. In Section 2 we detail the ideas and the algorithms for constructing a column imprint. In Section 3 we present the algorithms for querying the proposed index. Next, we study the different cases of updating column imprints in Section 4. Section 5 presents the related work. In Section 6 we present an extensive experimental evaluation for column imprints. We conclude in Section 7.

2. SECONDARY INDEX WITH IMPRINTS

An imprint index is an efficient and concise secondary index for range and point queries. It is designed for columnar databases where multiple memory-resident or memory-mapped columns are repeatedly scanned. Imprints provide a coarse-grain filtering over the data, aimed at reducing expensive loading from memory to the cpu cache. Deployment of column imprints is suited for those cases where alternative properties do not hold. For example, if a column is already sorted, the proper use of binary search algorithms largely alleviates the overhead of accessing non-relevant memory pages. If the data is appended out of order, or the order is disturbed by updates, then column imprints can be considered as a fast access method to locate relevant data. An efficient column imprint maximizes the filtering capabilities with minimal storage overhead.

Columnar databases decompose a relation into its attributes and sequentially store the values of each column. This differs from the traditional approach of row-stores that place complete tuples in adjacent pages. To enable tuple reconstruction in a column store, an ordered list of (*id*, *value*) pairs is maintained, where *ids* are unique and increasing identifiers. Values from different columns, but with the same *id*, belong to the same tuple. Typically, a column is implemented by a single dense array, thus *ids* need not be materialized since they can be easily derived from the position of the values in the array.

Figure 1 shows a column with 15 integer values in the range of 1 to 8. The values are unsorted because the column corresponds to one of the unordered attributes of a relation. In the absence of any secondary index, a complete scan is needed to locate all values that satisfy the predicates of a query. The result of such a scan is the positions in the array of the qualifying values. It is preferred to return the positions rather than the actual values because of the *late materialization* strategies usually used in column stores [1]. However, instead of scanning the entire column, secondary indexes can be used to avoid accessing data that is certain not to be part of the query result.

2.1 State of the Art in Secondary Indexes

Zonemaps is a common choice for indexing secondary attributes. A zonemap index notes the minimum and the maximum values found across a predefined number of consecutive values, called the zones. The zonemap index of Figure 1 partitions the column into 5 zones. In this example, each zone has the size of a cacheline that fits exactly 3 values. The first zone contains the values 1, 8, and 4. The minimum value is 1 and the maximum is 8. Similarly, for the second zone the minimum value is 1 and maximum 6, and so on for the remaining zones. To evaluate a query using zonemaps, the minimum and maximum values of each zone are compared with the predicates of the query. If the predicates' ranges overlap with the range of a zone, then the zone (i.e., the cacheline) is retrieved and the exact positions of only the *qualifying* values are returned.

	column	Zone Map	BitMap	Column Imprint
cacheline	1	[1, 8]	1 0 0 0 0 0 0 0	10010001
	8		0 0 0 0 0 0 0 0	
	4		0 0 0 1 0 0 0 0	
cacheline	6	[1, 7]	0 0 0 0 0 0 1 0	10000110
	7		0 0 0 0 0 0 0 1	
cacheline	1	[3, 7]	1 0 0 0 0 0 0 0	00110010
	4		0 0 0 1 0 0 0 0	
	7		0 0 0 0 0 0 0 1	
cacheline	3	[2, 6]	0 0 1 0 0 0 0 0	01001100
	2		0 1 0 0 0 0 0 0	
cacheline	5	[1, 8]	0 0 0 0 0 1 0 0	11000001
	6		0 0 0 0 0 0 1 0	
	8		0 0 0 0 0 0 0 1	
cacheline	2		0 1 0 0 0 0 0 0	
cacheline	1		1 0 0 0 0 0 0 0	

Figure 1: A simple column and an example of zonemaps, bitmaps, and imprints indexes.

Note that the ranges of the predicates and the zone may overlap but not be strictly inclusive.

Bitmaps are another popular choice for secondary indexing. They work by mapping the column domain to bit vectors. Each vector has as many bits as the size of the column. For each value found in a specific position of the column, the corresponding bit in the mapping bitvector is set. The mapping can be $1 - 1$ if the cardinality of the column is low, or $N - 1$, with the help of binning strategies, if the cardinality is high. A bitmap index uses significantly less storage than the column, thus making it cheaper to scan. Deciding if a value satisfies a query involves first checking the corresponding bitmap, and returning only the position of the bits that are set. The checking is done with bitwise operators, making the process faster than the value comparison needed by zonemaps. Figure 1 details a bitmap index with 15 bits per bit vector, where each bit corresponds to one position of the column. There are 8 such bit vectors (drawn vertically in the figure), where the first one maps value 1, the second one value 2, and so on. Bits are set as follows: the 11th position of the column contains the value 5, therefore, in the 5th bit vector, the 11th bit is set. Similarly, the 3rd value of the column is 4, hence the 3rd bit of the 4th bitmap is set. In this example there is a 1-1 mapping between the eight unique values of the column and the eight vectors of the bitmap index.

2.2 Column Imprints

We propose *column imprints* as an alternative secondary index that best combines the benefits of the aforementioned state-of-the-art indexes. Column imprints map the values of a column to a vector of bits. However, instead of allocating one such vector per value, imprints allocate one vector per cacheline. We call the vectors of a column imprints index *imprint vectors* to distinguish them from the bitvectors of a bitmap index. An imprint vector does not have only one bit set per position, but as many bits as are needed to map all distinct values of a cacheline. To decide if a cacheline contains values that satisfy the predicates of a query, first the imprint vectors are checked. If at least one common bit between the

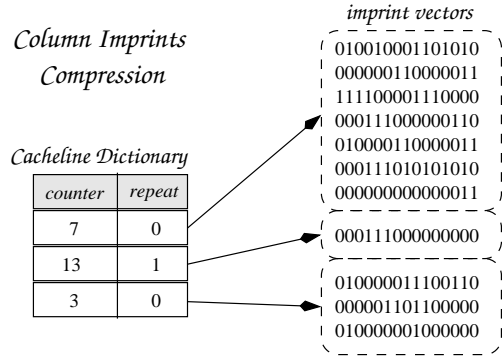


Figure 2: Column imprint index with compression (23 cachelines).

bitvector that maps the query's predicates and the imprint vector is set, then the entire cacheline is fetched for further processing. The imprint is checked with the bitwise operator AND thus making the initial filtering very fast, while the number of imprint vectors to be checked is significantly reduced because of having one per cacheline instead of one per value. The rightmost index in Figure 1 depicts the imprint index of the example column. Each imprint vector uses 8 bits per cacheline, while three bits are set. The partitioning of the column is done per cacheline, same as the zones of the zonemap index. The imprint vector corresponding to the first cacheline has the 1st, 4th, and 8th bit set, since the first three values of the column are 1, 8 and 4. For the second cacheline the 1st, 6th, and 7th bits are set, and so on for the rest of the cachelines. There are in total five imprint vectors to index the column of Figure 1. The example is designed with the cardinality of the column to be small enough to allow a 1-1 mapping between values and bits. In the more common cases of large cardinality, imprints use approximated equi-width histograms to divide the domain into ranges and map one bit per range. We detail this technique in the following subsection along with all the construction algorithms for column imprints.

Column imprints inherit many of the good properties of both zonemaps and bitmaps, while avoiding their pitfalls. First, although imprints are defined per cacheline, they are resilient to skewed data distribution, where zonemaps typically fail. If each cacheline contains both the minimum and the maximum value of the domain and one random value in between, zonemaps are practically useless, but imprints will have a different bit set for each of these random values. In addition, checking imprints is faster than zonemaps because there is no value comparison. Compared to bitmaps, imprints need less space since they are defined per cacheline and not per value. Finally, as we will demonstrate, imprints compress significantly better than state-of-the-art compression scheme for bitmaps.

2.3 Imprints Compression

We develop a compression scheme similar to a run-length encoding but for imprint vectors. The compression scheme combined with bit-binning, makes column imprints an efficient solution for indexing very large columns with high cardinality of any type, such as doubles, floats, etc. The compression scheme benefits from our empirical observation that local clustering is a common phenomenon even for secondary attributes. In addition to that, the opportunities for compression also increase because of the non-dense nature of column imprints. Most importantly, even for cases where there is no clustering at all, column imprints remain space effective.

The compression works by *i*) grouping together imprint vectors that are identical and consecutive, and *ii*) implying the *id* of the values with a concise numbering schema for the indexed cachelines. More specifically, we keep track of which imprints map to which cachelines by defining a *cacheline dictionary* with two entries, a *counter* and a *repeat* flag. By knowing the number of the cacheline we can easily compute the *id*'s of the values of the specific cacheline, since each cacheline contains a fixed number of values.

The cacheline dictionary contains two types of *counter* entries, distinguished by the *repeat* flag. Assume that the *counter* has the value x . If *repeat* is unset, then the next x cachelines have all different imprint vectors. If, however, *repeat* is set, then the next x cachelines all have the same imprint vector, thus only one vector needs to be stored. Figure 2 shows an example of the column imprints compression schema. Assume a column that can be partitioned to 23 cachelines and that each imprint vector has 15 bits. From the *cacheline dictionary* of Figure 2 we can deduce that the first 7 cachelines all contain random values, thus each of them map to a different imprint vector. Therefore, the first 7 imprint vectors correspond to the first 7 cachelines. The next imprint vector, i.e., the 8th, corresponds to the next thirteen cachelines, which according to the cacheline dictionary all have an identical imprint since *repeat* is set. Finally, the last 3 cachelines are mapped by the last 3 imprints.

In the next subsection we demonstrate the technical details to create a column imprint. We build our ideas on top of the MonetDB architecture [16]. The choice of a specific columnar database architecture allows us to better present the details of our implementation, however, imprints can also be implemented with minor adjustments on other columnar architectures, such as C-Store [14] and MonetDB/X100 [5]. The most important design decision is how many values of a column an imprint vector covers. The decision is based on the size of the block managed by the specific database buffer pool. The *access granularity* of the underlying system design determines the number of values that each vector of an imprint covers. For example, if the execution model of the database engine is based on vectorization, then the size of the data vectors is used. In our scenario, where typically the database hot-set fits into main memory, our goal is to optimize the cpu cache access. For that reason, a column imprint consist of one vector per cacheline. The size of the cacheline is determined by the underlying hardware. In this work we assume the commonly used size of 64 bytes.

2.4 Imprints Construction Algorithm

The first step to create an imprint index for a column is to build a non-materialized histogram by sampling the values of that column. Then the imprint vectors are created with as many bits as the number of bins in the histogram, but never more than 64 bits. Each imprint covers a cacheline of 64 bytes. For all values in a cacheline, the bins of the histogram into which they fall is located, and the corresponding bits are set. The process is repeated such that all cachelines are mapped by imprints. If consecutive imprint vectors are identical they are compressed to one and the counters of the cacheline dictionary are updated.

The histogram serves as a way to divide the value domain \mathcal{D} of the column into equal ranges. For this, only the bounds of each bin need to be stored in the imprint index structure. The histogram is created by sampling a small number of values from the column, not more than 2048 in our implementation. The first bin always has values between $-\infty$ (i.e., the minimum value of the domain \mathcal{D}), up until the smallest value found in the sample. Similarly, the last bin contains all values greater than the largest sampled value up to $+\infty$. We expect that future inserts in the column will retain

Algorithm 1 Main function to create the column imprints index: `imprints()`

Input: column *col* of size *col_sz*

Output: imprints index structure *imp* for column *col*

```

typedef struct cache_dict {
    uint cnt:24;
    uint repeat:1;
    uint flags:7;
} cache_dict;

typedef struct imp_idx {
    cache_dict *cd;
    ulong *imprints;
    coltype b[64];
    uchar bins;
} imp_idx;

struct imp_idx imp; /* initialize the column imprints index structure */
char vpc; /* constant values per cacheline */
ulong i_cnt = 0; /* imprints count */
ulong d_cnt = 0; /* dictionary count */
ulong imprint_v = 0; /* the imprint vector */
binning(imp); /* determine the histogram's size and bin borders */
for i = 0 → col_sz - 1 do /* for all values in col */
    bin = getbin(imp, col[i]); /* locate bin */
    imprint_v = imprint_v | (1 << bin); /* set bit */
    if (i mod vpc - 1 ≡ 0) then /* end of cacheline reached */
        if (imp.imprints[i_cnt] ≡ imprint_v ∧ /* same imprint */
            imp.cd[d_cnt].cnt < max_cnt - 1) then /* cnt not full */
            if (imp.cd[d_cnt].repeat ≡ 0) then
                if (imp.cd[d_cnt].cnt ≠ 1) then
                    imp.cd[d_cnt].cnt - = 1; /* decrease count cnt */
                    d_cnt + = 1; /* increase dictionary count d_cnt */
                    imp.cd[d_cnt].cnt = 1; /* set count to 1 */
                end if
                imp.cd[d_cnt].repeat = 1; /* turn on flag repeat */
            end if
            imp.cd[d_cnt].cnt + = 1; /* increase cnt by 1 */
        else /* different imprint than previous */
            imp.imprints[i_cnt] = imprint_v;
            i_cnt + = 1;
            if (imp.cd[d_cnt].repeat ≡ 0 ∧
                imp.cd[d_cnt].cnt < max_cnt - 1) then
                imp.cd[d_cnt].cnt + = 1; /* increase cnt by 1 */
            else
                d_cnt + = 1; /* increase dictionary count d_cnt */
                imp.cd[d_cnt].cnt = 1; /* set count to 1 */
                imp.cd[d_cnt].repeat = 0; /* set flag repeat off */
            end if
        end if
        imprint_v = 0; /* reset imprint for next cacheline */
    end if
end for

```

the same distribution of the values, however, the left and right most bins serve as overflow bins for outlier values. If the sampling returns fewer than 62 unique values, then the imprint can be adjusted to have as many bits as needed to map the columns with low cardinality. If the number of distinct sampled values is more than 62, the domain is divided into 62 ranges, where each range contains the same count of sampled values, including in the count the multiple occurrences of the same value. Based on these ranges the borders of the histogram are deduced. By counting also duplicate sampled values, it allows us to roughly approximate an equal-height histogram, since repeated values are more likely to be sampled, creating smaller ranges for their respective bins. The ranges of each bin are defined to be inclusive on the left, and exclusive on the right. For example, if $b[i]$ defines the border of the i th bin, then if $b[3] = 10$ and $b[4] = 13$, all values that are equal or greater than 10 but less than 13 fall into the 4th bin with borders $[10, 13)$, while value 13 falls into the 5th bin.

For each imprint, an index number is needed to point to the corresponding cacheline. In practice, these pointers need not be materialized since the sequence of the imprint vectors indirectly provide

the numbering of the cachelines. However, since identical imprints tend to repeat multiple times, even if the data of the indexed column is not clustered or sorted, there is a great opportunity for compressing imprints together. With a 64-bit imprint vector one may encode hundreds, and in many cases thousands, of sequential cachelines. Therefore, the *cacheline dictionary* is needed to keep track of the count of the cachelines and imprints. We define the two structures to store and administer the column imprints index, namely *imp_idx* and *cache_dict* (see Algorithm 1). Structure *imp_idx* holds all the constructs needed to maintain the imprints index of one column. It consists of a pointer to the array of the cacheline dictionary (i.e., *cache_dict*), a pointer to the array of the imprint vectors, an array with 64 values that holds the bounds of the bins of the histogram, and the actual number of bins of the histogram. Recall that it may not be needed to have all 64 bins if the cardinality is small, e.g., an 8-bit imprint vector may be enough instead of a 64-bit vector. The dictionary structure *cache_dict* is a 4-byte value, split as follows: 24 bits are reserved for the counter *cnt*, 1 bit is to mark if the next imprint is repeated *cnt* times, or if the next *cnt* imprints correspond to one cacheline each. Finally, 7 bits of the cacheline dictionary structure are reserved for future use.

Algorithm 1 details the process of creating the column imprints index. Function `imprints()` receives as input a column *col* and its size *col_sz*. The function returns an imprints index structure *imp* containing an array of imprints and the cacheline dictionary. The algorithm works by first calling the `binning()` procedure, which is described in detail later on in the text. The result of the `binning()` procedure is the number of bins needed to partition the values of the columns, and the ranges of the bins. Next, for each value of the column, the `get_bin()` function is invoked in order to determine the bin the current value falls into. The corresponding bit in the imprint vector is then set. If the end of a cacheline has been reached, the current imprint vector must be stored and a new empty one must be created. However, in order to compress consecutive imprints, the algorithm checks if the imprint vector is equal to the previous one. If so, the count *cnt* field of the cacheline dictionary and the *repeat* flag is updated as follows. If the *repeat* of the previous entry in the cacheline dictionary is not set and the count *cnt* is greater than 1, a new entry is created. If the *repeat* of the previous entry is not set but the count *cnt* is 1, then the *repeat* is set and the count *cnt* is incremented to 2. If the imprint vector of the current cacheline is not equal to the previous one, then a slightly different procedure is followed to update the entries in the cacheline dictionary. If the current entry does not have the *repeat* flag set, then the counter *cnt* is simply increased. Otherwise, a new entry is created with count *cnt* = 1 and the *repeat* unset. After this, the cacheline dictionary is correctly updated and the imprint stored. Finally, a new imprint vector is created with all the bits off, the next value of the column is fetched, and the process is repeated.

2.5 Binning and Efficient Binary Search

Algorithm 2 describes the implementation of the `binning()` procedure. Given a column *col*, a uniform sample of 2048 values is created. Afterwards, the sample is sorted and all duplicates are removed. At this point the size of the sample *smp_sz* might be smaller than 2048. If *smp_sz* is less than 64, the cardinality of the column can be approximated to be equal to the number of unique values found in the sample. Therefore, each bin of the histogram can contain exactly one value. Even if this approximation is not precise, there is an extremely slim possibility to be much off. In such a case, simply more than one value will fall into the same bin. The next step of the algorithm is to fill the *b* array with the unique values of the sample, and to set the number of the *bins* to the next

Algorithm 2 Define the number of bins and the ranges of the bins of the histogram: `binning()`

Input: imprints index structure *imp*, column *col*

Output: number of bins *imp.bins* and the ranges *imp.b*

```
coltype *sample = uni_sample(col,2048); /* sample 2048 values */
sort(sample); /* sort the sample */
smp_sz = duplicate_elimination(sample); /* remove duplicates */
if (smp_sz < 64) then /* less than 64 unique values */
  for i = 0 → smp_sz - 1 do
    imp.b[i] = sample[i]; /* populate b with the unique values */
  end for
  if (i < 8) then imp.bins = 8; /* determine the number of bins */
  else if (i < 16) then imp.bins = 16;
  else if (i < 32) then imp.bins = 32;
  else imp.bins = 64;
  end if
  for i = i → 63 do
    imp.b[i] = coltype_MAX; /* default value */
  end for
else /* more than 64 unique values */
  double y = 0, ystep = smp_sz/62;
  for i = 0 → 62 do
    imp.b[i] = sample[(int)y]; /* set ranges for all bins */
    y += ystep;
  end for
  imp.b[63] = coltype_MAX;
end if
```

larger power of 2. Moreover, the remaining empty bins are assigned the maximum value of the domain. This is needed in order for the `get_bin()` procedure to work properly. If the total number of unique values of the sample is 64 or more, we need to divide the bins into larger ranges. This is done by dividing the *smp_sz* by 62 and assigning the result of the division to *ystep*. Notice that *ystep* is a double. This is necessary in order to guarantee an even spread of the ranges of the bins. For example, if the result of the division is 1.2, then the 5th bin should contain the 6th value of the sample, but if we kept the result as an integer, i.e., *ystep* = 1, the 5th value of the sample would be assigned to the 5th bin. Each bin *b* is assigned to be equal to the next *ystep* sampled value, until all bins are set.

In order to determine the bin a value falls into, `get_bin()` is invoked. The approach taken is to perform a cache-conscious binary search over the 64 bins. For this, we use nested if-statements instead of a for-loop. We noticed during our experimentation that by explicitly unfolding the code for the binary search and by using if-statements without any else-branching, the search can become three times faster, or even more. This is because each if-statement is independent allowing the cpu to execute the branches in parallel. For this, three macros are defined. The macro `middle()`, checks if a value falls inside a range, and two others, called `left` and `right`, check if a value is smaller or larger than a range boundary. The algorithm then is constructed by repeatedly dividing the search space into half, and invoking the `right`, `middle` and `left` macros, in that order. Since there are no else-statements, many if-statement may evaluate to be true, but only the last assignment of the return variable *res* will hold. For this reason the search is performed by starting from the 63rd bin and decreasing.

The algorithms to construct the column imprint index are short and optimized to be cpu friendly. The complexity of `imprints()` function is linear to the size of the column. Assume that a column has *n* values, and each cacheline contains *c* values. The most costly part is the call to the `get_bin()` function which performs 3 comparisons before dividing the search space in half, thus it needs $3 \times \log 64 = 18$ comparisons for each value. Therefore, for creating the entire imprint index we need $18 \times n$ comparisons. The

call to `binning()` also involves one scan of the n values of the column but the rest of the operations are independent of the input. Finally, the update of the cacheline dictionary is only performed $\frac{n}{c}$ times, and the cost is negligible (5 comparisons in the worst case) compared to `get_bin()`. During our experimentation we thoroughly studied the effects of different design and implementation choices. Here, we presented the one that performed the best.

3. IMPRINTS QUERY EVALUATION

In this section we present the algorithms for evaluating range queries over the column imprints index. Given a range query $Q = [low, high]$, all values v in column col that satisfy $low \leq v \leq high$ need to be located. Since our setting is a columnar database, it suffices to return the id list of the qualifying values v .

Evaluating range queries over column imprints is a straightforward procedure. The first step is to create an empty bit-vector and set the bits that correspond to the bins that are included in the range of query Q . There might be more than one bits set, since the query range can span multiple bins. The query bit-vector is then checked against the imprint vectors, and if bitwise intersection indicates common bits set for both the query and the imprint vector, the corresponding cacheline is accessed for further processing. However, if all bits set correspond to bins that are fully included in the query range $[low, high]$ the cacheline need not be checked at all. Otherwise, the algorithm examines all values in the cacheline to weed out false positives. Finally, because of our compression schema, some administrative overhead to keep the cachelines and the imprint vectors aligned is needed.

Algorithm 3 presents the details for evaluating a range query using imprints. The constant vpc is set equal to the number of values that fit in a cacheline. This is needed to align ids with the cachelines. In addition, counters i_cnt and $cache_cnt$ are maintained to align imprints and cachelines, respectively. Next, two bit-vectors are produced, namely $mask$ and $innermask$. The $mask$ is a bit-vector that sets all bits that fall into the range $[low, high]$. The $innermask$ is a bit-vector with only the bits that fall entirely inside the query range set. More precisely, if a bin range contains one of the borders of the query range, the corresponding bit is not set. Therefore, if an imprint vector has only the bits from the $innermask$ set, then all values in the corresponding cacheline fall into the query range and no further check for false-positives is needed. The algorithm runs by iterating over all entries in the cacheline dictionary. If the $repeat$ flag is not set, then the next cnt imprint vectors correspond to cnt distinct cachelines. For any of these imprints, if there is at least one bit set in the same position as the ones in the $mask$ bit-vector, the cacheline contains values that satisfy the query range. If in addition, there are no bits set different than the bits of the $innermask$, then all the values of the cacheline satisfy the query. In any other case, we need to check each value of the cacheline individually. For all qualifying values, the corresponding ids are materialized in the result array. If however the $repeat$ flag is set, then by checking only one imprint vector we can determine if the next cnt cachelines contain values that fall into the range of the query. As before, an extra check with the $innermask$ bit-vector may result in avoiding the check of each individual value for false-positives.

Algorithm 3 returns a materialized list of the ids that satisfy the range query. This list is then passed to the next operator of the query evaluation engine. However, it might be the case that a user's query contains many predicates for more than one attribute of the same relation. In this case, the `query()` procedure of Algorithm 3 is invoked multiple times, one for each attribute, with possible different $[low, high]$ values. The most expensive part of Algorithm 3

Algorithm 3 Evaluate range queries over the column imprints index: `query()`

Input: imprints index structure imp , column col , query $Q = [low, high]$
Output: array res of ids

```

char vpc; /* constant values per cacheline */
ulong i_cnt = 0; /* imprints count */
ulong cache_cnt = 0; /* cacheline count */
ulong id = 0; /* ids counter */
ulong *res; /* large enough array to hold the result */
(mask, innermask) = make_masks(imp, [low, high]);
for i = 0 → d_cnt - 1 do /* iterate over the cacheline dictionary */
  if (imp.cd[i].repeat ≡ 0) then /* if repeat is not set */
    for j = i_cnt → i_cnt + imp.cd[i].cnt - 1 do
      if (imp.imprints[j]&mask) then /* if imprint vector matches mask */
        if ((imp.imprints[j]&~innermask) ≡ 0) then
          for id = cache_cnt × vpc → (cache_cnt × (vpc + 1)) - 1 do
            res = res ← id; /* add id to the result set res */
          end for
        else /* need to check for false-positives */
          for id = cache_cnt × vpc → (cache_cnt × (vpc + 1)) - 1 do
            if (col[id] < high ∧ col[id] ≥ low) then
              res = res ← id; /* add id to the result set res */
            end if
          end for
        end if
      end if
      cache_cnt + = 1; /* increase cache count by 1 */
    end for
    i_cnt + = imp.cd[i].cnt; /* increase imprint count */
  else /* repeat is set */
    if (imp.imprints[i_cnt]&mask) then /* if imprint vector match mask */
      if ((imp.imprints[i_cnt]&~innermask) ≡ 0) then
        for id = cache_cnt × vpc →
          (cache_cnt × vpc) + vpc × imp.cd[i].cnt - 1 do
          res = res ← id; /* add id to the result set res */
        end for
      else /* need to check for false-positives */
        for id = cache_cnt × vpc →
          (cache_cnt × vpc) + vpc × imp.cd[i].cnt - 1 do
          if (col[id] < high ∧ col[id] ≥ low) then
            res = res ← id; /* add id to the result set res */
          end if
        end for
      end if
    end if
    i_cnt + = 1; /* increase imprints count by 1 */
    cache_cnt + = imp.cd[i].cnt; /* increase cache count */
  end if
end for

```

is the check for false-positives and the materialization of the ids . But in the case of multiple range queries over many columns of the same table, both of these expensive operations can be postponed. This technique is known in the literature as late materialization. To achieve this, instead of producing the materialized id lists, Algorithm 3 has to return the list of the qualifying cachelines. After every range query is evaluated over the respective columns, the lists of cachelines are merge-joined, resulting in a smaller set of qualifying ids . This is based on the general expectation that the combination of many range queries will increase the selectivity of the final result set. After the merge-join, the qualifying ids that were common to all cachelines can be checked for false-positives. Note that the alternative indexing schemes used in the evaluation of Section 6 have been coded with the same rigidity.

4. UPDATING COLUMN IMPRINTS

Column imprints are designed to support read intensive database applications. In such scenarios, updates are a relatively rare event,

and when they occur, are performed in batches. The most common type of updates is appending new rows of data to the end of a table. Column imprints can easily cope with such updates. However, we can not exclude from our study updates that change an arbitrary value of a column, or insert/delete a row in the middle of a table.

4.1 Data Append

During data appends, any index that is based on bit vectors and bit-binning techniques has to perform two operations. The first one is to readjust, if necessary, the borders of the bins. Such a readjustment should be avoided since it calls for a complete rebuild of the index. For column imprints, this is very rare, since *i)* the first and last bins are used for overflow values, and *ii)* the bins were determined by sampling the active domain of the column. Any new data appended, need to have dramatically different value distribution to render the initial binning inefficient. The second operation is to update the bit vectors. For bitmap indexes this is a costly operation, since all bit vectors have to be updated, even those that are not mapping the new values [6]. For column imprints this is not necessary. The imprint vectors are horizontally compressed, thus data appends simply cause new imprint vectors to be appended to the end of the existing ones, without the need of accessing any of the previous imprint vectors.

4.2 Imprints and Delta Structures

In place updates are never performed in columnar databases because of the prohibitive cost they entail. Instead, a delta structure is used that keeps track of the updates, and merges them at query time. A delta structure can be as simple as two tables with insertions and deletions that need to be union-ed and difference-ed, respectively, with the base table, or it can be a more complex structure, such as positional update trees [11].

Column imprints can cope with inter-column operations, such as unions and differences, by first applying them to the cacheline dictionaries, such that a candidate list of qualifying cachelines is created for both operands. The details of inter-column operations are out of the scope of this paper, and are left to be presented in the future. Nevertheless, even without such a functionality, column imprints can be used to access the base table to create a candidate list of qualifying cachelines. The underlying delta structure may then hold in addition the cacheline counter where an update has been performed in order to merge to the final result.

Moreover, imprints can produce false positives, thus a deletion can be ignored by the corresponding imprint vector. An insertion however, will call for additional bits to be set to the imprint corresponding to the affected cachelines. Such an approach will eventually saturate the imprint index. In these cases, it is not uncommon to disregard the entire secondary index and rebuild it during the next query scan. The overhead for rebuilding an imprint index during a regular scan is minimal, such that it will go undetected by the user.

5. RELATED WORK

Column imprints can be viewed as a new member of the big family of bitmapped based indexes. Bitmapped indexes have become the prime solution to deal with the dimensionality curse of traditional index structures such as B-trees and R-trees. Their contribution to speed up processing has been credited to Patrick O’Neil through the work on the Model 204 Data Management System [17, 18]. Since then, database engines include bitmapped indexes for both fast access over persistent data and as intermediate storage scheme during query processing, e.g. Sybase IQ, Postgresql, IBM DB2, Oracle. Besides traditional bitmaps, Bloom filters [4] have

Dataset	Size	#Col	Value types	Max rows
Routing	5.4G	4	int, long	240M
SDSS	6.2G	4008	real, double, long	47M
Cnet	12G	2991	int, char	1M
Airtraffic	29G	93	int, short, char, str	126M
TPC-H 100	168G	61	int, date, str	600M

Table 1: Dataset statistics.

been used to decide if a record can be found in a relation, and thus postponing bringing the data into memory. However, Bloom filters are not suited for range queries, the target of column imprints.

Bitmap indexing relies on three orthogonal techniques [25]: binning, encoding and compression. Binning concerns the decision of how many bit vectors to define. For low cardinality domains, a single bit vector for each distinct value is used. High cardinality domains are dealt with each bit vector representing a set of values. The common strategy is to use a data value histogram to derive a number of equally sized bins. Although binning reduces the number of bit vectors to manage, it also requires a post analysis over the underlying table to filter out false positives during query evaluation. Column imprints use similar binning techniques.

Since each record turns on a single bit in one bit vector of the index only, the bitmaps become amenable to compression. Variations of run-length encoded compression have been proposed. The state-of-the art approach is the Word-Aligned Hybrid (WAH) [23, 26] storage scheme. WAH forms the heart of the open-source package FastBit¹, which is a mature collection of independent tools and a C++ library for indexing file repositories. Consequently, column imprints use another variation of run-length encoded but for identical cacheline mappings instead of consecutive equal values.

Bitmap indexing has been used in large scientific database applications, such as high-energy physics, network traffic analysis, lasers, and earth sciences. However, deployment of bitmap indexing over large-scale scientific databases is disputed. [20] claims that based on information theoretic constructs, the length of a compressed interval encoded bitmap is too large when high cardinality attributes are indexed. The storage size may become orders of magnitude larger than the base data. Instead, a multi-level indexing scheme is proposed to aid in the design of an optimal binning strategy. They extend the work on bit binning [9, 24]. Alternatively, the data distribution in combination with query workload can be used to refine the binning strategy [13, 7].

With the advent of multi-core and gpu processors it becomes attractive to exploit data parallel algorithms to speed up processing. Bit vectors carry the nice property of being small enough to fit in the limited gpu memory, while most bit operations nicely fall in the SIMD algorithm space. Promising results have been reported in [8]. Similar, re-engineering the algorithms to work well in a flash storage architecture have shown significant improvements [22].

6. EXPERIMENTAL EVALUATION

We performed an extensive experimental study to gain insights into the applicability of the imprints index, the storage overhead and creation time, as well as the query performance. We compare our index with two state-of-the-art commonly used secondary index solutions, namely *zonemaps* and *bit-binning* with *WAH encoding*. We also provide, for a baseline comparison, the time measurements for sequential scan. In order to study the impacts of different value types, different column sizes, and different value distributions, we

¹<http://crd-legacy.lbl.gov/~kewu/fastbit/>

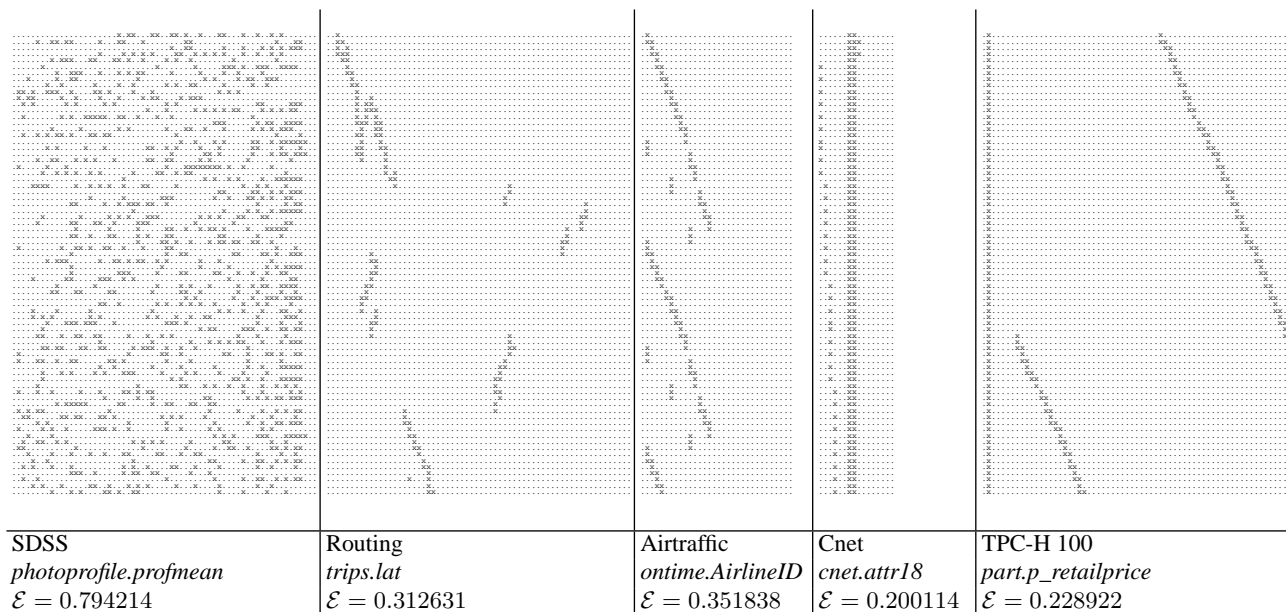


Figure 3: Prints of column imprint indexes ('x' = bit set, '.' = bit unset) and the respective column entropy \mathcal{E} .

used real world datasets gathered from various test cases. These datasets are either publicly available or part of in-house projects.

Column imprints, zonemaps, and WAH are all implemented in C, and the code is available for review upon request. The implementation of zonemaps and WAH follow the same coding style and rules as imprints to ensure fairness of comparison. Each experimental run is done by first copying a column into main memory, and then creating the zonemap, imprints and WAH indexes. The timer is always started during the snippets of code that implement each index, thus avoiding measuring administrative overhead, which may not be common for all indexes. We report the wall-clock time as returned by the timing facilities of the `time.h` library of C. All code has been compiled with the `clang` compiler with optimization level 3.

Zonemaps are implemented as two arrays containing the min and max values of each zone. The size of the zones is chosen to be equal to the size that each imprint vector covers, i.e., the size of the cache-line. The min and max arrays are aligned with the zone numbering, i.e., the first min and max values correspond to the minimum and maximum values found in the first zone, and so on. For the bit-binning approach of bitmaps, the bins used are identical to those used for the imprints index, as described in the `binning()` procedure of Algorithm 2. Using this binning scheme, each value of the column sets the appropriate bit on a vector large enough to hold all records. To compress the resulting bit-vectors we apply WAH compression with word size 32 bits, as described in [23].

All experiments were conducted on an Intel^R CoreTM i7-2600 cpu @ 3.40GHz machine with 8 cores and 8192 KB cache size. The available main memory was 16 GB, while the secondary storage was provided by a Seagate^R ConstellationTM SATA 1-TB hard drive and capable of reading data with a rate of 140MB/sec.

Table 1 lists the name, the size in gigabytes, the total number of columns, the column types, and the maximum number of rows of the datasets used for our experimentation. The first dataset, denoted as Routing, is a collection of over 240 million geographical records (i.e., longitude, latitude, trip-id, and timestamp) of “trips” as logged by gps devices. The next dataset, SDSS, is a 6.2 GB sample of the astronomy database SkyServer. This database con-

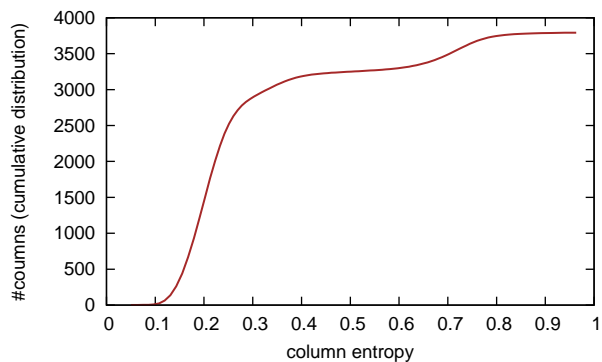


Figure 4: Cumulative distribution of the columns' entropy \mathcal{E} .

tains scientific data, with many double precision and floating point columns following a uniform distribution, thus stressing compression techniques to their limits. Cnet is a categorical dataset describing the properties of technological products. All data are stored on a single but very wide table, where each column is very sparse, thus presenting ample opportunities for compression. The dataset was re-created based on the study of J.Beckham [2]. The Airtraffic delay database represents an ever growing data warehouse with statistics about flight delays, landing times, and other flight statistics. The data are updated per month, leading to many time-ordered clustered sequences. Lastly, we used the TPC-H benchmark dataset with scale factor 100, in order to compare against a well recognizable dataset.

6.1 Column Entropy

We wish to better study the properties of the columns that are typically not ordered, part of very wide tables, and eligible for secondary indexing. Our initial motivation was based on the observation that “secondary data” exhibit some degree of clustering, either inherited during the creation process of the data, or indirectly imposed by the few columns that are ordered because of primary

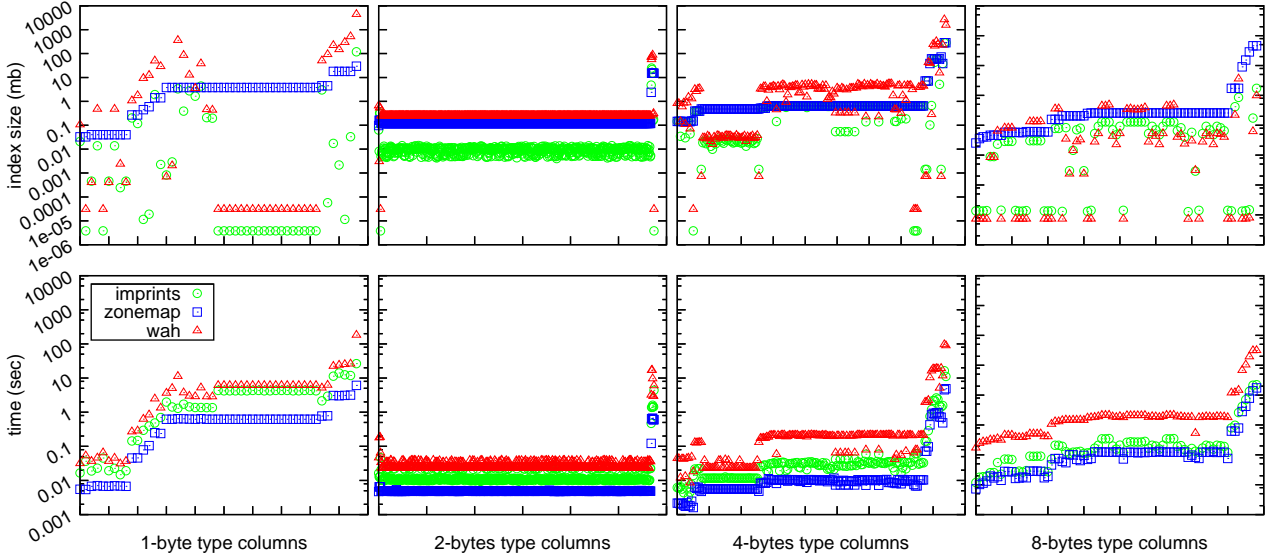


Figure 5: Index size and creation time for different types of columns (x -axis enumerates the columns, ordered by size).

indexing. Column imprints are designed such that this clustering is naturally exploited without the need of explicit configuration. This is why imprints are built per block and compressed row-wise per imprint vector, instead of vertically per bin. To better understand and quantify the degree of clustering found in data, we define a new metric, called *column entropy*. Column entropy measures how close a column is to being ordered, or, in other words, the amount of clustering found in a column when the values are partitioned into bins. More formally, column entropy \mathcal{E} is defined to be

$$\mathcal{E} = \frac{\sum_{i=2}^n d(i, i-1)}{2 \times \sum_{i=1}^n b(i)}$$

where $d(i, i-1)$ is the *edit distance* between bit-vector i and $i-1$, and $b(i)$ is the number of bits that are set in bit-vector i . We define the edit distance between two bit-vectors to be the number of bits that need to be set and unset in the first bit-vector in order to become the second. Column entropy \mathcal{E} takes values between 0.0 and 1.0. The higher the entropy \mathcal{E} the more random the data is and the less clustered it appears to be.

To give a more intuitive view of *column entropy*, we print a small portion of the column imprint index of five columns, one from each dataset, and list them in Figure 3, together with their respective entropy value \mathcal{E} . The prints in Figure 3 correspond to the actual imprint indexes as constructed in our code for the experiments. If a bit is set then an 'x' is printed, otherwise an '.'. The first column imprint of Figure 3 corresponds to a column from the SkyServer dataset. It is of type real and has a high entropy value of almost 0.8 which implies that each next imprint vector is significantly different from the previous one. Such columns with high entropy, as demonstrated in the next section, are harder to compress. The next imprint is the latitude attribute of the Routing dataset. It exhibits nice clustering properties, something to be expected since the dataset is taken from real observations, and thus trips are continuous without any jumps, unless the trip-id changes. The next two imprints are taken from the Airtraffic and Cnet dataset. These are categorical datasets, with low cardinality – hence the smaller bit-vectors – and with low entropy value. The last imprint index is the *retail_price* attribute of table *part* of TPC-H. This dataset is created to contain a sequence of prices that are not ordered, but they are still the same

repeated permutation of an order. Such an organization of data resembles closely an ordered column, and thus also has a low entropy value.

Figure 4 depicts the cumulative distribution of the entropy \mathcal{E} for all columns of all datasets that we used in our experiments. We exclude all columns that are less than 1 megabyte in size, since they are of minimal interest and introduce outliers in our measurements. More than 3000 columns have entropy smaller than 0.4, thus supporting our claim that data often tend to exhibit good local clustering and ordering properties. Nevertheless, there are almost a thousand columns that have high entropy values, up to almost 1.0. Those columns are not to be ignored since they sum up to over 20% of the total data. A secondary index should be immune to such high entropy, and still be able to take advantage of any opportunities for compression. In the next section we study the storage overhead of imprints and other state-of-the-art secondary indexes, while giving emphasis to their behavior on columns with high entropy. We show that imprints are robust against columns with high entropy, while bitmaps with WAH fail to achieve a good compression rate.

6.2 Index Size and Creation Time

We analyze the storage overhead introduced by the column imprints index and compare it with that of zonemaps and WAH. The upper row of the graphs in Figure 5 depict the sizes of the indexes over all columns and all datasets. Each graph corresponds to a different value type. For presentation reasons, we divide the types according to their size in bytes. For example, char is 1-byte, short is 2-byte, int and date are 4-byte, and long and double 8-byte types. The y -axis depicts the size of the indexes measured in megabytes, starting from a few bytes for the smaller columns to almost one gigabyte for the large ones. Notice that y -axis is *log-scaled*. The x -axis orders the columns according to their size (in increasing order). However, because many columns have exactly the same size, since they originate from the same tables, we distinguish them by placing them next to each other. As a result, the flat horizontal patterns appearing in the graphs correspond to different columns of the same size, while the “stepping” effect corresponds to the next group of larger columns.

The red triangle points mark the size of the bit-binning index

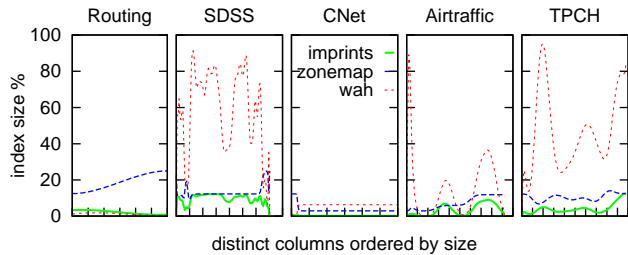


Figure 6: Index size overhead % over the size of the columns.

with WAH compression, the blue squares mark the size of zonemaps, and the green circles mark the size of the column imprints index. The general picture drawn for all types is that WAH index entails the largest storage overhead, zonemaps come second, while imprints have the least requirements of storage space. More specifically, the general trend is that imprints are between one and two orders of magnitude more space efficient than zonemaps and WAH. However, there are exceptions to that rule, especially for WAH indexing, which depicts the biggest fluctuation in storage needs. For 1-byte types, there are cases where WAH achieves better compression and reaches that of imprints. By examining the data closer we noticed that this is true for columns that although they have more than 126 million rows (taken from the Airtraffic dataset), they only contain two distinct values, thus allowing both WAH and imprints to fully compress their bit-vectors. Another point of interest is found in the case of 8-byte types, where WAH can become a bit more space efficient than imprints. This is true for those columns that contain primary keys (e.g., bigint identifiers) and in addition are ordered. Although we are studying secondary indexes that typically apply to unordered columns, we did not exclude any ordered columns from our experimental datasets for completeness.

Since it is impractical and hard to explicitly show the size of each individual column, we compute the percentage of the size of the indexes over the size of the column. Figure 6 shows such a graph. In addition, instead of grouping on value type, we group columns from the same datasets together, such that more insights about the different applications, and hence different value distributions can be gained. The categorical data Cnet which has columns with low cardinality, as well as the nicely clustered routing dataset, achieve the best compression for both imprints and WAH, thus requiring in many cases less than 10% space overhead. However, the same can not be said for broader value domains and uniform distributions. Specifically, the scientific dataset of SkyServer, consisting of many columns with real and double values, with high cardinality and no apparent clustering, makes the WAH index very unstable and induces high storage overhead. Imprints perform fairly stably and much better than WAH, with space overhead closer to zonemaps. The failure of WAH is expected due to the high randomness of the values in SkyServer, which allows for very few compression opportunities. However, imprints do not suffer from the same problem. Since one imprint vector is constructed for each cacheline, the space requirements are less than bitmaps, while the chance of consecutive imprint vectors to be identical, and thus compressible, is increased.

Figure 7 depicts the index size overhead of both imprints and WAH as percentage of the size of the column, ordered over the entropy \mathcal{E} . Imprints achieve storage overhead less than 10% for columns with low entropy, i.e., up to 0.4. The same observation holds with few exceptions for WAH indexing. However, the picture changes for columns with entropy of 0.5 and higher. Imprints

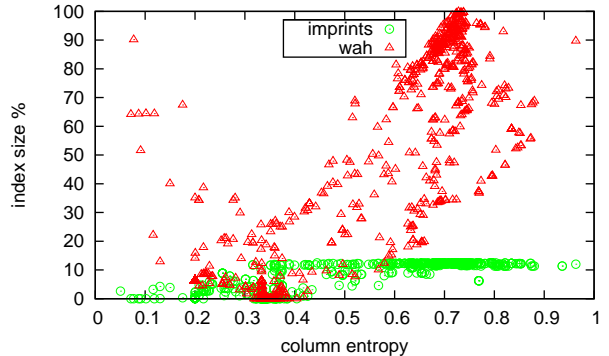


Figure 7: Index size overhead % over column entropy \mathcal{E} .

exhibit a steady storage overhead that hardly exceeds 12%. WAH indexing suffers more, with up to almost 100% of storage overhead on the size of the column. Imprints on the one hand need at most 64 bits per cacheline unit, making them immune to high entropy, while benefiting from low entropy. On the other hand, WAH can potentially become very inefficient. If there are very few opportunities for compression, most 32-bit words will be aligned with 31-bit literals, i.e., no big long sequences of same bits will be found in the bit-vectors. In addition, since we use a 64 bit-binning approach, there will potentially be 64 uncompressed bits per value. All in all, WAH is more suitable for low entropy data, while imprints are more stable and with better compression for the entire range of entropy values, i.e., they work even if data are not locally clustered.

Another concern is the time spent to create each secondary index. The bottom row of graphs in Figure 5 depicts the creation time for WAH, zonemaps, and imprints. As expected the zonemaps are the fastest to create. For each row only two comparisons have to be made to determine the minimum and the maximum values for the current zone. The slowest is the WAH index, since there is significantly more work to be done in order to compress the bit-vectors. Imprints on the other hand, always perform between zonemaps and WAH. The overall differences of the construction time between the three indexes is steady and to be expected since each of them require a different amount of work per value. Most importantly, the time for all indexes increases linearly to the size of the columns, thus making them a cost-effective solution for secondary indexing.

6.3 Query Performance

Next, we turn our attention to the performance analysis of evaluating range queries. The execution scenario for this set of experiments is as follows. For each column, ten different range queries with varying selectivity are created. The selectivity starts from less than 0.1 and increases each time by 0.1, until it surpasses 0.9. These 10 queries are then fired against the three indexes (i.e., zonemaps, WAH, and imprints) defined over the column, and also evaluated with a complete scan over that column. The result set of each query is a materialized ordered list of *id*'s. The ordering of *id*'s is guaranteed by the sequential scan, the zonemap index, and the imprints index. However, this is not true for WAH, since each pass over the different bit-vectors will produce a new set of *id*'s which needs to be merged. The merging is done by defining another bit-vector aligned with the *id*'s. The bits that are set in this *id* bit-vector correspond to the *id*'s that satisfy the range query. In this way no final merge is needed, just the materialization of the *id*'s. This implementation only adds a small, but necessary for fairness, overhead to WAH compared to the other indexes.

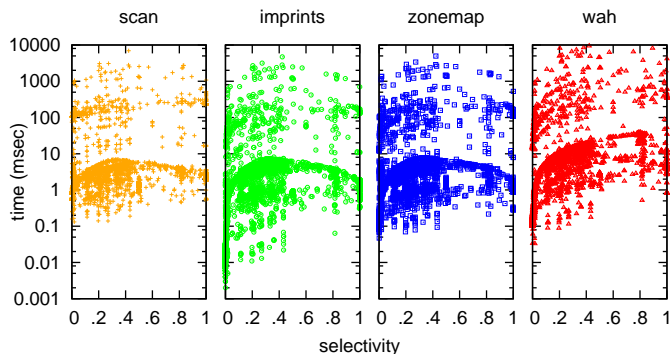


Figure 8: Query time for decreasing selectivity.

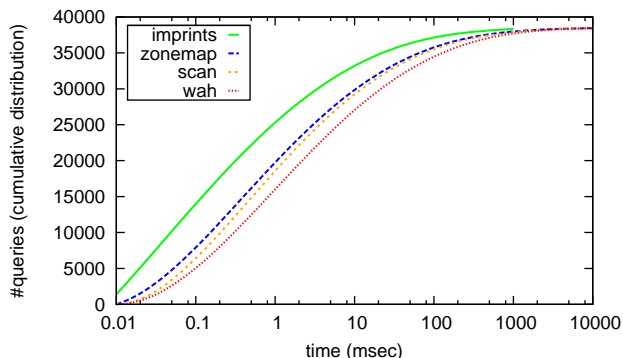


Figure 9: Cumulative distribution of query times.

Figure 8 plots the query times of over 40,000 queries evaluated over each index. The queries are ordered on the x -axis according to their selectivity. If the selectivity is 0.1, the query returns 10% of the total values in the column, while 0.9 returns 90% of the total values. All three indexes and the sequential scan produce the same graph patterns for query times. However, these patterns are shifted along the y -axis. Imprints is the fastest index overall since the points in the graph are shifted the most to the bottom. As expected, if the selectivity of the query is low and thus more data are returned, the smaller the differences that are observed between indexes. In fact, sequential scans then also become competitive. This is due to the fact that the overhead of decompressing the data, and materializing almost all of the id 's, surpasses the time needed to sequentially scan the entire column and check each value. In addition, zonemaps exhibits query times similar to that of sequential scan for low selectivity queries, since zonemaps require the least administration overhead compared to imprints and bitmaps with WAH.

To better understand the behavior of zonemap, WAH, and imprints, for queries with high selectivity, and compare them with sequential scans, we plot in Figure 9 the cumulative distribution of the queries over time. More precisely, we count the queries that finish execution at each time frame, and cumulatively sum them up. The steeper the graph in Figure 9 the more queries finish in a shorter time, thus the more efficient the index is overall. Figure 9 shows that almost 15,000 queries need each of them less than 0.1 milliseconds to be evaluated with imprints index. Zonemaps, which is the second best, manage to evaluate just over 7,500 queries in the same time frame. However, as the evaluation time increases the time gap between the different approaches is reduced.

We are interested in the factor of improvement that is achieved

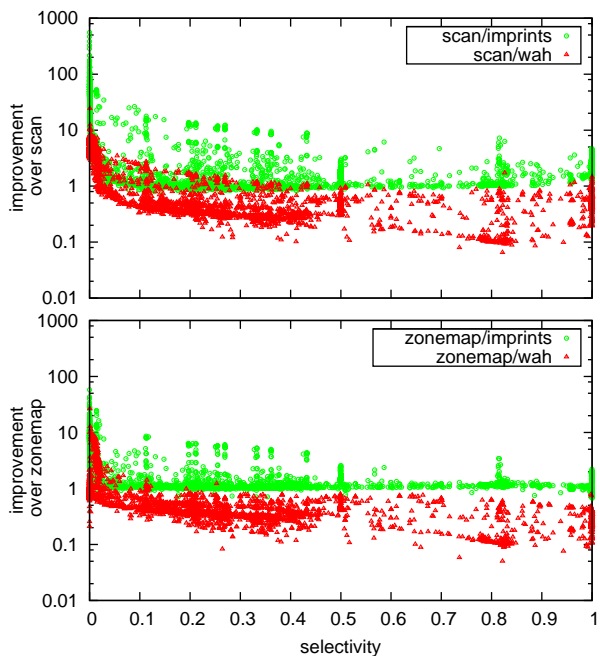


Figure 10: Factor of improvement over scan and zonemap.

by the imprints index over the sequential scan baseline and the competitive zonemap indexing. Figure 10 depicts the factor of improvement achieved for each query. A point above 1 is translated as a factor of improvement over the baseline, while a point below 1 shows how many times an approach is slower than the baseline. The upper graph of Figure 10 shows with green circle points the improvement of imprints over sequential scans, while the red triangles, the corresponding improvement of bitmaps with WAH over sequential scans. Both imprints and WAH, show a significant improvement for queries with high selectivity, i.e., when less than 20% of the tuples are returned. For imprints that improvement is in some cases almost a 1000 times faster, and for WAH over 10. However, for low selectivity queries, imprints become less competitive, while WAH can become significantly slower than scans. This observation is aligned with the strategy of most modern database systems, where, if the cost model of the query optimizer detects a low selectivity selection, a sequential scan is preferred over any index probing. Moreover, WAH is punished in a main memory setting. The processing overhead of the WAH compression outweighs the throughput of data that is achieved from main memory to the cpu cache. Therefore, WAH is more suitable for cases where data do not reside in memory, but need to be fetched from disk. Similarly, the bottom graph of Figure 10 depicts the same comparison, but with zonemap indexing being the baseline, instead of sequential scans. The same trend can be seen here, although zonemaps is more competitive and thus the improvement factor for imprints is closer to 100 times. However, in a few cases of low selectivity zonemaps can become faster than imprints due to less computation needs.

Finally, we compare the number of index probes and data comparisons performed (originating from testing for false positives) normalized over the number of records in a column. This experiment reveals implementation-independent statistics for column imprints in comparison with zonemaps and WAH. The top graph of Figure 11 shows the number of index probes, while the bottom the

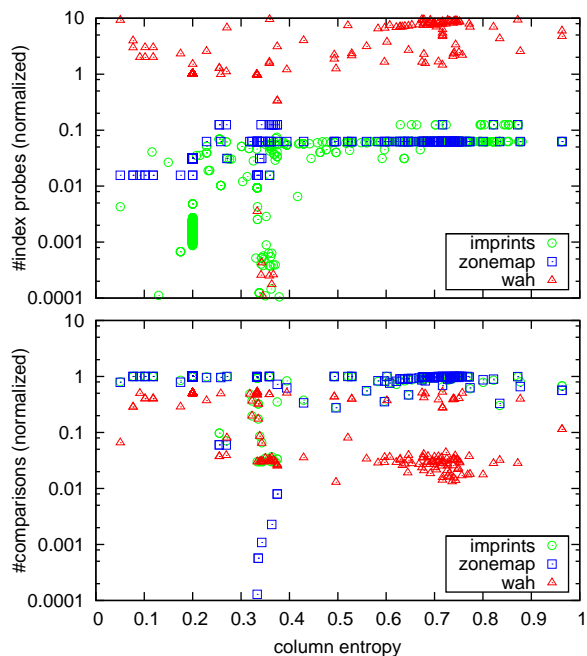


Figure 11: Number of index probes and value comparisons for queries with selectivity between 0.4 and 0.5.

number of comparisons, for all queries with selectivity between 0.4 and 0.5. The number of index probes for WAH is the highest of all indexes, almost always more than the number of total records. This is true since for each record many bit vectors have to be probed. However, WAH achieves the best filtering since the number of data comparisons is usually very low. On the other hand, zonemaps have a steady number of index probes, i.e., exactly the number of cache-lines of the column. The number of comparisons for zonemaps depends on the data skew and can vary. Column imprints achieve a balance between index probes and data comparisons. Columns with high entropy entail more index probes but less data comparisons. On the other hand, columns with low entropy will need less index probes but more data comparisons.

In conclusion, for high selectivity queries column imprints index can achieve a factor of 1000 improvement over sequential scans, and a factor of 100 over zonemap. Further experimentation, revealed that there is a correlation between the query evaluation time and the sizes of the column, or the size of the index, which in turn is correlated with the column entropy. We do not show these graphs since they do not reveal any new insights into the performance of imprints compared to zonemap or WAH index.

7. CONCLUSIONS AND FUTURE WORK

Column imprints is a light-weight secondary index with a small memory footprint suited for a main-memory setting. It belongs to the class of bitvector indexes, which has a proven track record of improving access in large-scale data warehouses. Our extensive experimental evaluation shows significant query evaluation speed-up against pure scans and the established indexing approaches of zonemaps and bitmaps with bit-binning and WAH compression. The storage overhead of column imprints is just a few percent, with a max of 12% over the base column.

Column imprints can be extended to exploit multi-core platforms during the construction phase and during multi-attribute query processing. Akin to prevailing techniques, such as [20, 22], judicious choice of the binning scheme, and a multi-level imprints organization, may lead to further improvements in specific application domains.

8. REFERENCES

- [1] D. J. Abadi, D. S. Myers, D. J. DeWitt, and S. R. Madden. Materialization Strategies in a Column-Oriented DBMS. In *Proc. of the 23rd ICDE*, 2007.
- [2] J. L. Beckham. The CNET E-Commerce Data Set, 2005.
- [3] N. Beckmann, H. P. Kriegel, R. Schneider, and B. Seeger. The R*-tree: an efficient and robust access method for points and rectangles. In *Proc. of the ACM SIGMOD*, 1990.
- [4] B. H. Bloom. Space/Time Trade-offs in Hash Coding with Allowable Errors. *Communications of the ACM*, 13(7), 1970.
- [5] P. Boncz, M. Zukowski, and N. Nes. MonetDB/X100: Hyper-Pipelining Query Execution. In *CIDR*, 2005.
- [6] G. Canahuete, M. Gibas, and H. Ferhatosmanoglu. Update Conscious Bitmap Indices. In *19th SSDBM*, 2007.
- [7] C. Chan and Y. Ioannidis. An efficient bitmap encoding scheme for selection queries. In *ACM SIGMOD*, 1999.
- [8] L. Gosink, K. Wu, E. Bethel, J. D. Owens, and K. I. Joy. Data Parallel Bin-Based Indexing for Answering Queries on Multi-core Architectures. In *Proc. of the SSDBM*, 2009.
- [9] N. Goyal and Y. Sharma. New binning strategy for bitmap indices on high cardinality attributes. In *Proc. of the 2nd Bangalore Annual Compute Conference*, 2009.
- [10] J. Hellerstein, J. Naughton, and A. Pfeffer. Generalized Search Trees for Database Systems. In *Proc. of the 21th VLDB*, 1995.
- [11] S. Heman, M. Zukowski, N. Nes, L. Sidirourgos, and P. Boncz. Positional Update Handling in Column Stores. In *Proc. of the ACM SIGMOD*, 2010.
- [12] S. Idreos, M. Kersten, and S. Manegold. Database Cracking. In *Proc. of the 3rd CIDR*, 2007.
- [13] N. Koudas. Space efficient bitmap indexing. In *Proc. of the 9th CIKM*, 2000.
- [14] M. Stonebraker et. al. C-Store: A Column Oriented DBMS. In *Proc. of the 31st VLDB*, 2005.
- [15] S. Manegold, M. Kersten, and P. Boncz. Database Architecture Evolution: Mammals Flourished long before Dinosaurs became Extinct. In *Proc. of the 35th VLDB*, 2009.
- [16] MonetDB. <http://www.monetdb.org>.
- [17] P. O’Neil. Model 204 Architecture and Performance. In *Proc. of the 2nd HPTS*, 1987.
- [18] P. O’Neil and G. Graefe. Multi-table joins through bitmapped join indices. *SIGMOD Rec.*, 24(3), 1995.
- [19] P. O’Neil and D. Quass. Improved Query Performance with Variant Indexes. In *Proc. of the ACM SIGMOD*, 1997.
- [20] R. R. Sinha and M. Winslett. Multi-resolution bitmap indexes for scientific data. *ACM Trans. Database Syst.*, 32(3), 2007.
- [21] H. Wong, H. Liu, F. Olken, D. Rotem, and L. Wong. Bit Transposed Files. In *Proc. of the 11th VLDB*, 1985.
- [22] K. Wu, K. Madduri, and S. Canon. Multi-level bitmap indexes for flash memory storage. In *Proc. of the 14th IDEAS*, 2010.
- [23] K. Wu, E. J. Otoo, and A. Shoshani. Compressing Bitmap Indexes for Faster Search Operations. In *Proc. of the 14th SSDBM*, 2002.
- [24] K. Wu, E. J. Otoo, and A. Shoshani. On the performance of bitmap indices for high cardinality attributes. In *Proc. of the 30th VLDB*, 2004.
- [25] K. Wu, E. J. Otoo, and A. Shoshani. Optimizing bitmap indices with efficient compression. *ACM Trans. Database Syst.*, 31(1), 2006.
- [26] K. Wu, A. Shoshani, and K. Stockinger. Analyses of multi-level and multi-component compressed bitmap indexes. *ACM Trans. Database Syst.*, 35(1), 2008.