

UNIFORMLY ACCURATE OSCILLATORY INTEGRATORS FOR THE KLEIN-GORDON-ZAKHAROV SYSTEM FROM LOW- TO HIGH-PLASMA FREQUENCY REGIMES

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ABSTRACT. We present a novel class of oscillatory integrators for the Klein-Gordon-Zakharov system which are uniformly accurate with respect to the plasma frequency c . Convergence holds from the slowly-varying low-plasma up to the highly oscillatory high-plasma frequency regimes without any step size restriction and, especially, uniformly in c . The introduced schemes are moreover asymptotic consistent and approximates the solutions of the corresponding Zakharov limit system in the high-plasma frequency limit ($c \rightarrow \infty$). We in particular present the construction of the first- and second-order uniformly accurate oscillatory integrators and establish rigorous, uniform error estimates. Numerical experiments underline our theoretical convergence results.

1. INTRODUCTION

The Klein-Gordon-Zakharov (KGZ) system

$$(1) \quad \begin{aligned} c^{-2} \partial_{tt} z - \Delta z + c^2 z &= -nz, & z(0) &= z_0, \partial_t z(0) = c^2 z'_0, \\ \partial_{tt} n - \Delta n &= \Delta |z|^2, & n(0) &= n_0, \partial_t n(0) = \dot{n}_0 \end{aligned}$$

describes the interaction of Langmuir waves (oscillations of the electron density) with ion sound waves in a plasma. For existence and uniqueness of (global) smooth solutions and physical applications of the system we refer to [7, 25, 26, 29] and the references therein.

The so-called *low-plasma frequency regime* $c = 1$ of the Klein-Gordon-Zakharov system is nowadays well understood and extensively studied numerically, see, e.g., [32] for an energy conservative finite difference method and [1, 33] for exponential wave integrator methods.

From an analytical point of view, also the *high-plasma frequency regime* $c \gg 1$ has gained a lot of attention lately and is, meanwhile, in large parts well understood mathematically. In particular, the high-plasma frequency limit, i.e., $c \rightarrow \infty$, where the Klein-Gordon-Zakharov system (1) converges to the Zakharov system

$$(2) \quad \begin{aligned} 2i \partial_t z - \Delta z &= -nz, \\ \partial_{tt} n - \Delta n &= \frac{1}{2} \Delta |z|^2 \end{aligned}$$

is nowadays extensively studied mathematically, see, e.g., [8, 25, 26, 31] and the references therein.

In contrast, only very little is known in the numerical analysis of the KGZ system (1) in *weakly to strongly high-plasma frequency regimes* $c > 1$ up to $c \gg 1$. The main challenge in these regimes lies in the fact that the solution becomes highly oscillatory in time. Classical numerical schemes fail to resolve these oscillations correctly, and, in particular, severe step size restrictions need to be imposed to allow a sufficient close approximation to exact solutions. This,

however, leads to huge computational efforts and non optimal convergence. For an introduction to the numerical analysis of highly oscillatory problems we refer to [13, 20] and in the context of the classical Klein-Gordon equation in particular to [5, 15], as well as the references therein.

In recent years, many achievements have been accomplished in the numerical analysis of the classical Klein-Gordon equation (i.e., $n = -|z|^2$ in KGZ)

$$(3) \quad c^{-2}\partial_{tt}z - \Delta z + c^2z = |z|^2z$$

in the highly oscillatory so-called non-relativistic regime $c \gg 1$. In particular, uniformly accurate schemes for the classical Klein-Gordon equation (3) were derived in [3, 10, 6] based on multiscale and modulated Fourier expansion techniques. For the latter, see also [11, 12, 19, 20] and the references therein. The great benefit of *uniformly accurate numerical schemes* lies in their optimal approximation property: They allow convergence independently of the parameter c , i.e., from classical slowly-varying $c = 1$ up to highly oscillatory $c \gg 1$ regimes. Nevertheless, note that the Klein-Gordon equation (3) benefits from a much simpler mathematical structure than the KGZ system (1) which makes it, compared to the KGZ system, a much easier task to construct uniformly accurate methods and establish the corresponding rigorous error estimates.

A uniformly accurate multiscale time integrator spectral method for the KGZ system (1) was recently introduced in [2] and its convergence was extensively studied numerically. However, a rigorous convergence analysis is still lacking and, up to our knowledge, no rigorous error analysis for numerical schemes for the KGZ system (1) in weakly to strongly high-plasma frequency regimes is known so far due to the difficult coupling of the problem.

In this work we introduce a novel concept of *uniformly accurate oscillatory integrators for the KGZ system* (1) which converge uniformly in the parameter c . The new techniques developed in this work in particular allow us to establish rigorous error estimates not only in low-plasma, but for the first time also in weakly to strongly high-plasma frequency regimes. Our idea is thereby inspired by the recent work [18] which allowed us to *numerically overcome the loss of derivative* within the Zakharov limit system (2) as well as techniques related to *twisting the variable* in order to precisely capture the oscillations within the solution. The latter was introduced for the classical Klein-Gordon equation in [6] (see also [23, 27] for similar ideas in the context of Korteweg-de Vries and nonlinear Schrödinger equations, respectively). The proposed novel class of integrators is in particular asymptotic consistent and converges in the high-plasma frequency limit, i.e., for $c \rightarrow \infty$, towards solutions of the corresponding Zakharov limit system (2).

Note that in contrast to previous works (e.g., [3, 6, 10, 18]) the construction of the numerical schemes and their corresponding error analysis is here much more challenging due to the the resonant coupling of the highly oscillatory parts triggered by the critical high-plasma frequency c and the loss of derivative stemming from the nonlinear wave coupling.

For practical implementation issues, we will consider periodic boundary conditions, i.e., consider z and n as functions defined on $(t, x) \in \mathbb{R} \times \mathbb{T}^d$ with values in \mathbb{R} , a finite time interval $(0, T)$ and smooth initial values. Note that our result can be easily extended to complex valued solutions $z(t, x) \in \mathbb{C}$, however, for clarity of presentation we restrict our attention to the real setting. Furthermore, in the following we assume that $r > d/2$ and, to simplify notation, we restrict our attention to dimensions $d \leq 3$. We denote by $\|\cdot\|_r$ the standard $H^r = H^r(\mathbb{T}^d)$ Sobolev norm and exploit the well-known bilinear estimate

$$(4) \quad \|fg\|_r \leq K_{r,d}\|f\|_r\|g\|_r$$

which holds for some constant $K_{r,d} > 0$.

2. REFORMULATION OF THE SYSTEM

For a given $c > 0$ we define the following operator (*Japanese bracket*)

$$\langle \nabla \rangle_c = \sqrt{-\Delta + c^2}.$$

Note that $\langle \nabla \rangle_c$ is well defined since $-\Delta$ is a positive operator. Furthermore, it is a local operator considered on \mathbb{T}^d with its k -th Fourier coefficient given by

$$(5) \quad (\langle \nabla \rangle_c)_k = \sqrt{|k|^2 + c^2}.$$

Next we rewrite the Klein-Gordon part z in (1) as a first-order system in time via the transformation (see, e.g., [25, 26])

$$(6) \quad u = z - ic^{-1} \langle \nabla \rangle_c^{-1} \partial_t z$$

such that as $z(t, x) \in \mathbb{R}$ we have

$$(7) \quad z = \frac{1}{2}(u + \bar{u}).$$

With the transformation (6) at hand, the original problem (1) can be rewritten as follows

$$(8) \quad \begin{aligned} i\partial_t u &= -c\langle \nabla \rangle_c u - \frac{1}{2}c\langle \nabla \rangle_c^{-1}n(u + \bar{u}), \\ \partial_{tt}n &= \Delta n + \frac{1}{4}\Delta|u + \bar{u}|^2. \end{aligned}$$

Remark 1 (Nonlinear coupling). Note that the coupling in the Klein-Gordon and wave part is driven by the operator $c\langle \nabla \rangle_c^{-1}$ and $\langle \nabla \rangle_0$, respectively. With the aid of the Fourier expansion we easily see that the coupling operator $c\langle \nabla \rangle_c^{-1} \times \langle \nabla \rangle_0$ satisfies

$$\|c\langle \nabla \rangle_c^{-1} \langle \nabla \rangle_0 f\|_r^2 = \sum_{k \in \mathbb{Z}} \left| \frac{ck}{\sqrt{c^2 + k^2}} \right|^2 |\hat{f}_k|^2$$

which implies that

$$\|c\langle \nabla \rangle_c^{-1} \langle \nabla \rangle_0 f\|_r^2 \leq c\|f\|_r \quad \text{as well as} \quad \|c\langle \nabla \rangle_c^{-1} \langle \nabla \rangle_0 f\|_r^2 \leq \|f\|_{r+1}.$$

From the first bound we can easily deduce that no loss of derivative occurs when $c = \mathcal{O}(1)$, and hence the KGZ system (1) can be solved much more easily in the low-plasma frequency regime $c = 1$. However, standard techniques fail in the high-plasma frequency regime $c \gg 1$ due to the loss of derivative highlighted through the second bound.

To overcome this *loss of derivative* in the high-plasma frequency regime we pursue the following strategy: Inspired by the numerical analysis of the Zakharov system given in [18], see also [28] for the original idea in context of the local wellposedness analysis of the Zakharov system, we introduce the new variable

$$F = \partial_t u$$

and will further look at (8) as a system in $(u, \partial_t u, n, \partial_t n) = (u, F, n, \dot{n})$. Note that with this notation at hand the equation in u given in (8) can be expressed as follows

$$(9) \quad c\langle \nabla \rangle_c u = -iF - \frac{1}{2}c\langle \nabla \rangle_c^{-1}n(u + \bar{u}).$$

Furthermore, taking the time derivative in the first line of (8) yields by the product formula that

$$(10) \quad i\partial_t F = -c\langle \nabla \rangle_c F - \frac{1}{2}c\langle \nabla \rangle_c^{-1} \left\{ \partial_t n(u + \bar{u}) + n\partial_t(u + \bar{u}) \right\}.$$

As n is real valued we have that

$$\begin{aligned}\partial_t u &= +ic\langle\nabla\rangle_c u + i\frac{1}{2}c\langle\nabla\rangle_c^{-1}n(u + \bar{u}), \\ \partial_t \bar{u} &= -ic\langle\nabla\rangle_c \bar{u} - i\frac{1}{2}c\langle\nabla\rangle_c^{-1}n(u + \bar{u})\end{aligned}$$

which implies that

$$(11) \quad \partial_t(u + \bar{u}) = ic\langle\nabla\rangle_c(u - \bar{u}).$$

Plugging (11) into (10) yields with the notation $\partial_t n = \dot{n}$ that

$$(12) \quad i\partial_t F = -c\langle\nabla\rangle_c F - \frac{1}{2}c\langle\nabla\rangle_c^{-1}\left\{\dot{n}(u + \bar{u}) + inc\langle\nabla\rangle_c(u - \bar{u})\right\}.$$

System (8) together with equation (9) and (12) thus takes the form

$$(13) \quad \begin{aligned}i\partial_t F &= -c\langle\nabla\rangle_c F - \frac{1}{2}c\langle\nabla\rangle_c^{-1}\left\{\dot{n}(u + \bar{u}) + inc\langle\nabla\rangle_c(u - \bar{u})\right\}, \\ \partial_{tt}n &= \Delta n + \frac{1}{4}\Delta|u + \bar{u}|^2, \\ u &= (c\langle\nabla\rangle_c)^{-1}\left\{-iF - \frac{1}{2}c\langle\nabla\rangle_c^{-1}n\left(u(0) + \int_0^t F(\xi)d\xi + \overline{u(0) + \int_0^t F(\xi)d\xi}\right)\right\}.\end{aligned}$$

Thereby, we use that $c\langle\nabla\rangle_c$ is invertible for all $c \neq 0$ as well as the representation

$$(14) \quad u(t) = u(0) + \int_0^t F(\xi)d\xi.$$

3. CONSTRUCTION OF THE FIRST ORDER SCHEME

In this section we develop a first order *uniformly accurate numerical scheme* which allows us to approximate solutions of the KGZ system (8) with order $\mathcal{O}(\tau)$ uniformly in the parameter c . Our approach is thereby based on looking at the reformulated system (13) and approximating the corresponding Duhamel's formula in $(F, n, \partial_t n = \dot{n})$. However, and in great difference to classical exponential and trigonometric integration techniques (cf., e.g., [16, 18, 20, 22]), we will carefully treat the highly oscillatory phases triggered by the plasma frequency c in an exact way.

Duhamel's formula in (F, n, \dot{n}) reads (see (13))

$$(15) \quad \begin{aligned}F(t_\ell + \tau) &= e^{i\tau c\langle\nabla\rangle_c} F(t_\ell) + \frac{i}{2}c\langle\nabla\rangle_c^{-1} \int_0^\tau e^{i(\tau-\xi)c\langle\nabla\rangle_c} \left\{ \dot{n}(t_\ell + \xi)(u(t_\ell + \xi) + \bar{u}(t_\ell + \xi)) \right. \\ &\quad \left. + in(t_\ell + \xi)c\langle\nabla\rangle_c(u(t_\ell + \xi) - \bar{u}(t_\ell + \xi)) \right\} d\xi, \\ n(t_\ell + \tau) &= \cos(\tau\langle\nabla\rangle_0) n(t_\ell) + \langle\nabla\rangle_0^{-1} \sin(\tau\langle\nabla\rangle_0) \dot{n}(t_\ell) \\ &\quad + \frac{1}{4}\langle\nabla\rangle_0^{-1} \int_0^\tau \sin((\tau - \xi)\langle\nabla\rangle_0) \Delta|u(t_\ell + \xi) + \bar{u}(t_\ell + \xi)|^2 d\xi, \\ \dot{n}(t_\ell + \tau) &= -\langle\nabla\rangle_0 \sin(\tau\langle\nabla\rangle_0) n(t_\ell) + \cos(\tau\langle\nabla\rangle_0) \dot{n}(t_\ell) \\ &\quad + \frac{1}{4} \int_0^\tau \cos((\tau - \xi)\langle\nabla\rangle_0) \Delta|u(t_\ell + \xi) + \bar{u}(t_\ell + \xi)|^2 d\xi.\end{aligned}$$

Furthermore, observe that for u we have (see (8))

$$(16) \quad u(t_\ell + \tau) = e^{i\tau c\langle\nabla\rangle_c} u(t_\ell) + \frac{i}{2}c\langle\nabla\rangle_c^{-1} \int_0^\tau e^{i(\tau-\xi)c\langle\nabla\rangle_c} n(t_\ell + \xi)(u(t_\ell + \xi) + \bar{u}(t_\ell + \xi)) d\xi.$$

Remark 2. Note that $\partial_t u = F = \mathcal{O}(c\langle\nabla\rangle_c)$. Thus, if we would approximate the integrals in (15) by employing the classical Taylor series expansion

$$u(t_\ell + \xi) = u(t_\ell) + \mathcal{O}(\xi\partial_t u) = u(t_\ell) + \mathcal{O}(\xi c\langle\nabla\rangle_c)$$

(or a classical quadrature formula) this would yield a local error of order $\mathcal{O}(\tau^2 c^2)$ and, in particular, not the aimed uniform approximation property. Henceforth, standard exponential integrator techniques (cf. [22]) fail, and a more careful approximation technique has to be applied.

3.1. Collection of essential lemma and notation. We start off by collecting some useful lemma which will be essential in the derivation of uniform approximations with respect to c . Thereby we will in particular exploit the following refined bilinear estimates: For $\sigma_1 + \sigma_2 \geq 0$ (and as we assume that $1 \leq d \leq 3$) it holds that

$$\begin{aligned} \|fg\|_\sigma &\leq K_{r,d} \|f\|_{\sigma_1} \|g\|_{\sigma_2} \quad \text{for all } \sigma \leq \sigma_1 + \sigma_2 - \frac{d}{2} \quad \text{with } \sigma_1, \sigma_2 \text{ and } -\sigma \neq \frac{d}{2}, \\ \|fg\|_\sigma &\leq K_{r,d} \|f\|_{\sigma_1} \|g\|_{\sigma_2} \quad \text{for all } \sigma < \sigma_1 + \sigma_2 - \frac{d}{2} \quad \text{with } \sigma_1, \sigma_2 \text{ or } -\sigma = \frac{d}{2}. \end{aligned}$$

In particular, by setting $\sigma = \sigma_1 = r - 1$ and $\sigma_2 = r$ we can thus conclude that

$$(17) \quad \|fg\|_{r-1} \leq K_{r,d} \|f\|_{r-1} \|g\|_r,$$

where we use that $\sigma_2 = r > d/2$ as well as $\sigma_1 + \sigma_2 = 2r - 1 > 0$.

Lemma 3. For all $t \in \mathbb{R}$ and $c \neq 0$ we have that

$$(18) \quad \begin{aligned} \|c\langle\nabla\rangle_c^{-1} f\|_r &\leq \|f\|_r, \quad \|e^{itc\langle\nabla\rangle_c} f\|_r = \|f\|_r, \quad \|(c\langle\nabla\rangle_c - c^2)f\|_r \leq \frac{1}{2} \|f\|_{r+2}, \\ \|(e^{-i\xi c\langle\nabla\rangle_c} - e^{-i\xi c^2})f\|_r &\leq \frac{1}{2} \xi \|f\|_{r+2}, \\ \|\langle\nabla\rangle_c^{-2} f\|_r &\leq \min\left(\frac{1}{c} \|f\|_{r-1}, \|f\|_{r-2}, \frac{1}{c^2} \|f\|_r\right), \quad \|\langle\nabla\rangle_c^{-2} (fc\langle\nabla\rangle_c g)\|_{r-1} \leq K \|f\|_{r-1} \|g\|_{r+1}. \end{aligned}$$

Proof. The estimates in the first and second row follow from [6]. Furthermore, observe that

$$\frac{1}{c^2 + k^2} \leq \min\left(\frac{1}{c|k|}, \frac{1}{k^2}, \frac{1}{c^2}\right) \quad \text{and} \quad \frac{\sqrt{c^2 + k^2}}{c} \leq \frac{c + |k|}{c} \leq 1 + c^{-1}|k|.$$

The second inequality together with the bilinear estimate (17) and the definition of $\langle\nabla\rangle_c$ in Fourier space (see (5)) in particular implies that

$$\|\langle\nabla\rangle_c^{-2} (fc\langle\nabla\rangle_c g)\|_{r-1} \leq \left\| f \frac{c\langle\nabla\rangle_c}{c^2} g \right\|_{r-1} \leq K \|f\|_{r-1} \left\| \frac{\langle\nabla\rangle_c}{c} g \right\|_r \leq K \|f\|_{r-1} \|g\|_{r+1}$$

for some constant $K > 0$ independent of c . This concludes the estimates in the last row of (18). \square

In the following we set

$$(19) \quad M_{T,r} = \max\left(\sup_{0 \leq t \leq T} \left\{ \|u(t)\|_{r+1} + \|(c\langle\nabla\rangle_c^{-1})F(t)\|_{r+1} + \|n(t)\|_r + \|\dot{n}(t)\|_{r-1} \right\}, 1\right)$$

and introduce a suitable definition for the occurring remainders.

Definition 4 (Remainder). We will denote all constants which can be chosen independently of c by K . Furthermore, we write

$$(20) \quad f = g + \mathcal{R}_{r+s} \quad \text{if} \quad \|f - g\|_r \leq KM_{T,r+s}^p$$

for some $p \in \mathbb{N}$ and $K > 0$ independent of c .

We will also make use of the so-called φ -functions.

Definition 5 (The φ - functions, see [22]). For $\zeta \in \mathbb{C}$ we set

$$(21) \quad \tau\varphi_1(\zeta\tau) := \int_0^\tau e^{\zeta\xi} d\xi = \tau \frac{e^{\zeta\tau} - 1}{\zeta\tau} \quad \text{and} \quad \tau^2\varphi_2(\zeta\tau) := \int_0^\tau \xi\varphi_1(\zeta\xi) d\xi = \tau^2 \frac{\varphi_1(\zeta\tau) - 1}{\zeta\tau}.$$

Furthermore, we set

$$\tau^2\Psi_2(\tau\zeta) := \int_0^\tau \xi e^{\xi\zeta} d\xi = \tau^2 \frac{\varphi_0(\tau\zeta) - \varphi_1(\tau\zeta)}{\tau\zeta}.$$

The following lemma will allow us to carry out a classical Taylor series expansions in $n(t_\ell + \xi)$ and $\dot{n}(t_\ell + \xi)$ in the construction of our numerical scheme without producing remainders which depend on c .

Lemma 6. *For all $\xi \in \mathbb{R}$ it holds that*

$$(22) \quad \|n(t_\ell + \xi) - n(t_\ell)\|_r + \|\dot{n}(t_\ell + \xi) - \dot{n}(t_\ell)\|_{r-1} \leq |\xi|KM_{r+1}^2$$

for some constant $K > 0$ which can be chosen independently of c such that in particular

$$(23) \quad n(t_\ell + \xi) = n(t_\ell) + \xi\mathcal{R}_{r+1}, \quad \dot{n}(t_\ell + \xi) = \dot{n}(t_\ell) + \xi\mathcal{R}_{r+2}.$$

Proof. Duhamel's formula (15) in (n, \dot{n}) yields

$$\begin{aligned} n(t_\ell + \xi) - n(t_\ell) &= (\cos(\xi\langle\nabla\rangle_0) - 1)n(t_\ell) + \xi\text{sinc}(\xi\langle\nabla\rangle_0)\dot{n}(t_\ell) + \xi\mathcal{R}_{r+1}, \\ \dot{n}(t_\ell + \xi) - \dot{n}(t_\ell) &= (\cos(\xi\langle\nabla\rangle_0) - 1)\dot{n}(t_\ell) - \xi\text{sinc}(\xi\langle\nabla\rangle_0)\langle\nabla\rangle_0^2 n(t_\ell) + \xi\mathcal{R}_{r+2}. \end{aligned}$$

The assertion thus follows by the estimates

$$(24) \quad \|(\cos(\xi\langle\nabla\rangle_0) - 1)f\|_r + \|(\text{sinc}(\xi\langle\nabla\rangle_0) - 1)f\|_r \leq 3\xi^2\|f\|_{r+2}$$

together with the bilinear estimate (4). \square

In the approximation of u , however, we need to be much more careful as a classical Taylor series expansion would lead to

$$u(t_\ell + \xi) = u(t_\ell) + \xi c\langle\nabla\rangle_c \mathcal{R}_r,$$

and trigger an error at order $\mathcal{O}(\xi c^2)$ (see also Remark 2).

Lemma 7. *For all $\xi \in \mathbb{R}$ it holds that*

$$(25) \quad \|u(t_\ell + \xi) - e^{ic^2\xi}u(t_\ell)\|_r + \|u(t_\ell + \xi) - e^{ic\langle\nabla\rangle_c\xi}u(t_\ell)\|_r \leq |\xi|K(M_{r+2} + M_r^2)$$

for some constant $K > 0$ which can be chosen independently of c such that in particular

$$(26) \quad u(t_\ell + \xi) = e^{ic\langle\nabla\rangle_c\xi}u(t_\ell) + \xi\mathcal{R}_r \quad \text{and} \quad u(t_\ell + \xi) = e^{ic^2\xi}u(t_\ell) + \xi\mathcal{R}_{r+2}.$$

Proof. Duhamel's formula in u (see (16)) implies that

$$u(t_\ell + \xi) = e^{i\xi c\langle \nabla \rangle_c} u(t_\ell) + \xi \mathcal{R}_r$$

which yields the first assertion. Furthermore, we can write

$$u(t_\ell + \xi) - e^{ic^2\xi} u(t_\ell) = \left(e^{i\xi c\langle \nabla \rangle_c} - e^{ic^2\xi} \right) u(t_\ell) + \xi \mathcal{R}_r.$$

Together with Lemma 3 this concludes the second assertion. \square

3.2. A first order uniformly accurate oscillatory integrator for the KGZ system.

3.2.1. *Approximation in F .* Recall Duhamel's formula in F (see (15))

$$(27) \quad \begin{aligned} F(t_\ell + \tau) &= e^{i\tau c\langle \nabla \rangle_c} F(t_\ell) \\ &+ \frac{i}{2} c\langle \nabla \rangle_c^{-1} \int_0^\tau e^{i(\tau-\xi)c\langle \nabla \rangle_c} \left\{ \dot{n}(t_\ell + \xi) (u(t_\ell + \xi) + \bar{u}(t_\ell + \xi)) \right. \\ &\quad \left. + in(t_\ell + \xi) c\langle \nabla \rangle_c (u(t_\ell + \xi) - \bar{u}(t_\ell + \xi)) \right\} d\xi. \end{aligned}$$

Multiplying the above formula with the operator $(c\langle \nabla \rangle_c)^{-1}$ and employing the expansions for $(n, \dot{n})(t_\ell + \xi)$ given (23) and for $u(t_\ell + \xi)$ given in (26) we obtain by Lemma 3 that

$$\begin{aligned} (c\langle \nabla \rangle_c)^{-1} F(t_\ell + \tau) &= e^{i\tau c\langle \nabla \rangle_c} (c\langle \nabla \rangle_c)^{-1} F(t_\ell) \\ &+ \frac{i}{2} \langle \nabla \rangle_c^{-2} \int_0^\tau e^{i(\tau-\xi)c\langle \nabla \rangle_c} \left\{ \dot{n}(t_\ell) (e^{ic^2\xi} u(t_\ell) + e^{-ic^2\xi} \bar{u}(t_\ell)) \right. \\ &\quad \left. + in(t_\ell) c\langle \nabla \rangle_c (e^{ic^2\xi} u(t_\ell) - e^{-ic^2\xi} \bar{u}(t_\ell)) \right\} d\xi \\ &+ \tau^2 \mathcal{R}_{r+2} \\ &= e^{i\tau c\langle \nabla \rangle_c} (c\langle \nabla \rangle_c)^{-1} F(t_\ell) \\ &+ \frac{i}{2} \langle \nabla \rangle_c^{-2} e^{i\tau c\langle \nabla \rangle_c} \int_0^\tau \left\{ e^{i\xi \frac{1}{2}\Delta} (\dot{n}(t_\ell) u(t_\ell)) + e^{-i\xi (c\langle \nabla \rangle_c + c^2)} (\dot{n}(t_\ell) \bar{u}(t_\ell)) \right. \\ &\quad \left. + ie^{i\xi \frac{1}{2}\Delta} (n(t_\ell) c\langle \nabla \rangle_c u(t_\ell)) - ie^{-i\xi (c\langle \nabla \rangle_c + c^2)} (n(t_\ell) c\langle \nabla \rangle_c \bar{u}(t_\ell)) \right\} d\xi \\ &+ \tau^2 \mathcal{R}_{r+2}. \end{aligned}$$

With the definition of the φ_1 function in (21) we furthermore obtain that

$$(28) \quad \begin{aligned} (c\langle \nabla \rangle_c)^{-1} F(t_\ell + \tau) &= e^{i\tau c\langle \nabla \rangle_c} (c\langle \nabla \rangle_c)^{-1} F(t_\ell) \\ &+ i \frac{\tau}{2} \langle \nabla \rangle_c^{-2} e^{i\tau c\langle \nabla \rangle_c} \varphi_1 \left(\frac{i}{2} \tau \Delta \right) \left(\dot{n}(t_\ell) u(t_\ell) + in(t_\ell) c\langle \nabla \rangle_c u(t_\ell) \right) \\ &+ i \frac{\tau}{2} \langle \nabla \rangle_c^{-2} e^{i\tau c\langle \nabla \rangle_c} \varphi_1 \left(-i\tau (c\langle \nabla \rangle_c + c^2) \right) \left(\dot{n}(t_\ell) \bar{u}(t_\ell) - in(t_\ell) c\langle \nabla \rangle_c \bar{u}(t_\ell) \right) \\ &+ \tau^2 \mathcal{R}_{r+2}. \end{aligned}$$

3.2.2. *Approximation in u .* Recall that at time $t = t_\ell$ we have that (see (13))

$$(29) \quad u(t_\ell) = (c\langle \nabla \rangle_c)^{-1} \left\{ -iF(t_\ell) - \frac{1}{2} c\langle \nabla \rangle_c^{-1} n(t_\ell) \left(I^F(t_\ell) + \overline{I^F(t_\ell)} \right) \right\},$$

where we have set

$$I^F(t_\ell) := u(0) + \int_0^{t_\ell} F(\xi) d\xi = u(0) + \sum_{k=0}^{\ell-1} \int_0^\tau F(t_k + \xi) d\xi.$$

To obtain an approximation to $I^F(t_\ell)$ we will use the approximation (28) which yields that

$$\begin{aligned} (30) \quad I^F(t_\ell) &= u(0) + \sum_{k=0}^{\ell-1} \int_0^\tau \left(e^{i\xi c \langle \nabla \rangle_c} F(t_k) + c^2 \xi (\mathcal{R}_{r+2})_k \right) d\xi \\ &= u(0) + \left(\tau \sum_{k=0}^{\ell-1} \varphi_1(i\tau c \langle \nabla \rangle_c) F(t_k) \right) + \tau c^2 t_\ell \mathcal{R}_{r+2}. \end{aligned}$$

In the following we set

$$(31) \quad S^F(t_\ell) = u(0) + \tau \sum_{k=0}^{\ell-1} \varphi_1(i\tau c \langle \nabla \rangle_c) F(t_k).$$

Then, plugging the approximation (30) into (29) yields thanks to the estimate $\|\langle \nabla \rangle_c^{-2} c^2\|_r \leq 1$ (see Lemma 3) that

$$\begin{aligned} (32) \quad u(t_\ell) &= (c \langle \nabla \rangle_c)^{-1} \left\{ -iF(t_\ell) - \frac{1}{2} c \langle \nabla \rangle_c^{-1} n(t_\ell) \left(S^F(t_\ell) + \overline{S^F(t_\ell)} \right) \right\} \\ &\quad + \frac{1}{2} \langle \nabla \rangle_c^{-2} \{ n(t_\ell) \tau c^2 \mathcal{R}_{r+2} \} \\ &= (c \langle \nabla \rangle_c)^{-1} \left\{ -iF(t_\ell) - \frac{1}{2} c \langle \nabla \rangle_c^{-1} n(t_\ell) \left(S^F(t_\ell) + \overline{S^F(t_\ell)} \right) \right\} \\ &\quad + \tau \mathcal{R}_{r+2}. \end{aligned}$$

3.2.3. *Approximation in (n, \dot{n}) .* Recall Duhamel's formula in (n, \dot{n}) (cf. (15))

$$\begin{aligned} n(t_\ell + \tau) &= \cos(\tau \langle \nabla \rangle_0) n(t_\ell) + \langle \nabla \rangle_0^{-1} \sin(\tau \langle \nabla \rangle_0) \dot{n}(t_\ell) \\ &\quad + \frac{1}{4} \langle \nabla \rangle_0^{-1} \int_0^\tau \sin((\tau - \xi) \langle \nabla \rangle_0) \Delta |u(t_\ell + \xi) + \bar{u}(t_\ell + \xi)|^2 d\xi, \\ \dot{n}(t_\ell + \tau) &= -\langle \nabla \rangle_0 \sin(\tau \langle \nabla \rangle_0) n(t_\ell) + \cos(\tau \langle \nabla \rangle_0) \dot{n}(t_\ell) \\ &\quad + \frac{1}{4} \int_0^\tau \cos((\tau - \xi) \langle \nabla \rangle_0) \Delta |u(t_\ell + \xi) + \bar{u}(t_\ell + \xi)|^2 d\xi. \end{aligned}$$

Employing the approximation of $u(t_\ell + \xi)$ given in (26) together with the trigonometric approximations

$$(33) \quad \|(\sin(\xi \langle \nabla \rangle_0) - \xi \langle \nabla \rangle_0) f\|_r + \|(\cos(\xi \langle \nabla \rangle_0) - 1) f\|_r + \|(\operatorname{sinc}(\xi \langle \nabla \rangle_0) - 1) f\|_r \leq 3\xi^2 \|f\|_{r+2}$$

we obtain that

$$\begin{aligned}
n(t_\ell + \tau) &= \cos(\tau\langle\nabla\rangle_0) n(t_\ell) + \langle\nabla\rangle_0^{-1} \sin(\tau\langle\nabla\rangle_0) \dot{n}(t_\ell) \\
&\quad + \frac{1}{4} \langle\nabla\rangle_0^{-1} \operatorname{sinc}(\tau\langle\nabla\rangle_0) \int_0^\tau ((\tau - \xi)\langle\nabla\rangle_0) \Delta \left\{ 2|u(t_\ell)|^2 + e^{2ic^2\xi} u(t_\ell)^2 + e^{-2ic^2\xi} \overline{u(t_\ell)}^2 \right\} d\xi, \\
&\quad + \tau^3 \mathcal{R}_{r+4}, \\
\dot{n}(t_\ell + \tau) &= -\langle\nabla\rangle_0 \sin(\tau\langle\nabla\rangle_0) n(t_\ell) + \cos(\tau\langle\nabla\rangle_0) \dot{n}(t_\ell) \\
&\quad + \frac{1}{4} \cos(\tau\langle\nabla\rangle_0) \int_0^\tau \Delta \left\{ 2|u(t_\ell)|^2 + e^{2ic^2\xi} u(t_\ell)^2 + e^{-2ic^2\xi} \overline{u(t_\ell)}^2 \right\} d\xi \\
&\quad + \tau^2 \mathcal{R}_{r+4}.
\end{aligned}$$

Together with the definition of the φ_1 and φ_2 function (see (21)) we thus derive that

$$\begin{aligned}
(34) \quad n(t_\ell + \tau) &= \cos(\tau\langle\nabla\rangle_0) n(t_\ell) + \langle\nabla\rangle_0^{-1} \sin(\tau\langle\nabla\rangle_0) \dot{n}(t_\ell) \\
&\quad + \frac{\tau^2}{4} \operatorname{sinc}(\tau\langle\nabla\rangle_0) \Delta \left\{ |u(t_\ell)|^2 + \varphi_2(2ic^2\tau) u(t_\ell)^2 + \varphi_2(-2ic^2\tau) \overline{u(t_\ell)}^2 \right\} \\
&\quad + \tau^3 \mathcal{R}_{r+4}, \\
\dot{n}(t_\ell + \tau) &= -\langle\nabla\rangle_0 \sin(\tau\langle\nabla\rangle_0) n(t_\ell) + \cos(\tau\langle\nabla\rangle_0) \dot{n}(t_\ell) \\
&\quad + \frac{\tau}{4} \cos(\tau\langle\nabla\rangle_0) \Delta \left\{ 2|u(t_\ell)|^2 + \varphi_1(2ic^2\tau) u(t_\ell)^2 + \varphi_1(-2ic^2\tau) \overline{u(t_\ell)}^2 \right\} \\
&\quad + \tau^2 \mathcal{R}_{r+4}.
\end{aligned}$$

3.2.4. *A uniformly accurate oscillatory integrator of first order.* Collecting the approximations in (28), (32) (together with (31)) and (34) motivate us to define our numerical scheme as follows:

For $0 \leq \ell \leq n-1$ we set

$$\begin{aligned}
(c\langle\nabla\rangle_c)^{-1} F_{\ell+1} &= e^{i\tau c\langle\nabla\rangle_c} (c\langle\nabla\rangle_c)^{-1} F_\ell \\
&\quad + i\frac{\tau}{2} \langle\nabla\rangle_c^{-2} e^{i\tau c\langle\nabla\rangle_c} \varphi_1\left(\frac{i}{2}\tau\Delta\right) \left(\dot{n}_\ell u_\ell + in_\ell c\langle\nabla\rangle_c u_\ell\right) \\
&\quad + i\frac{\tau}{2} \langle\nabla\rangle_c^{-2} e^{i\tau c\langle\nabla\rangle_c} \varphi_1\left(-i\tau(c\langle\nabla\rangle_c + c^2)\right) \left(\dot{n}_\ell \overline{u}_\ell - in_\ell c\langle\nabla\rangle_c \overline{u}_\ell\right) \\
n_{\ell+1} &= \cos(\tau\langle\nabla\rangle_0) n_\ell + \langle\nabla\rangle_0^{-1} \sin(\tau\langle\nabla\rangle_0) \dot{n}_\ell \\
(35) \quad &\quad + \frac{\tau^2}{4} \operatorname{sinc}(\tau\langle\nabla\rangle_0) \Delta \left\{ |u_\ell|^2 + \varphi_2(2ic^2\tau) u_\ell^2 + \varphi_2(-2ic^2\tau) \overline{u}_\ell^2 \right\} \\
\dot{n}_{\ell+1} &= -\langle\nabla\rangle_0 \sin(\tau\langle\nabla\rangle_0) n_\ell + \cos(\tau\langle\nabla\rangle_0) \dot{n}_\ell \\
&\quad + \frac{\tau}{4} \cos(\tau\langle\nabla\rangle_0) \Delta \left\{ 2|u_\ell|^2 + \varphi_1(2ic^2\tau) u_\ell^2 + \varphi_1(-2ic^2\tau) \overline{u}_\ell^2 \right\} \\
S_{\ell+1}^F &= S_\ell^F + \tau\varphi_1(i\tau c\langle\nabla\rangle_c) F_{\ell+1} \\
u_{\ell+1} &= c^{-1} \langle\nabla\rangle_c^{-1} \left\{ -iF_{\ell+1} - \frac{1}{2} c\langle\nabla\rangle_c^{-1} n_{\ell+1} \left(S_{\ell+1}^F + \overline{S_{\ell+1}^F} \right) \right\}
\end{aligned}$$

and choose the initial values (cf. (9))

$$\begin{aligned}
(36) \quad u_0 &:= u(0), \quad n_0 := n(0), \quad \dot{n}_0 := \partial_t n(0), \\
F_0 &:= ic\langle\nabla\rangle_c u_0 + \frac{i}{2} c\langle\nabla\rangle_c^{-1} n_0 (u_0 + \overline{u_0}), \\
S_0^F &:= u_0 + \tau\varphi_1(i\tau c\langle\nabla\rangle_c) F_0.
\end{aligned}$$

Remark 8. Note that for practical implementation issues we may write

$$\begin{aligned} S_{\ell+1}^F &= S_\ell^F + \tau\varphi_1(i\tau c\langle\nabla\rangle_c)F_{\ell+1} \\ &= S_\ell^F - i\left(e^{i\tau c\langle\nabla\rangle_c} - 1\right)(c\langle\nabla\rangle_c)^{-1}F_{\ell+1} \end{aligned}$$

thanks to the definition of the φ_1 -function given in (21). Note that the calculation of the inverse $(c\langle\nabla\rangle_c)^{-1}$ is thereby not necessary as $(c\langle\nabla\rangle_c)^{-1}F_{\ell+1}$ itself is computed in the iterative scheme (35).

In the next section we carry out the convergence analysis of the scheme (35).

4. CONVERGENCE ANALYSIS OF THE FIRST ORDER SCHEME

In the following we set (cf. (19))

$$(37) \quad B_{t_\ell, r} = \max\left(\sup_{0 \leq k \leq \ell} \{\|u_k\|_{r+1} + \|(c\langle\nabla\rangle_c)^{-1}F_k\|_{r+1} + \|n_k\|_r + \|\dot{n}_k\|_{r-1}\}, 1\right).$$

4.1. Error in F . Taking the difference of $F(t_\ell + \tau)$ given in (28) and $F_{\ell+1}$ defined in (35) we readily obtain thanks to the error bounds on the remainders (20) (see Definition 4), the bilinear estimate (4) and the isometric property $\|e^{i\tau c\langle\nabla\rangle_c}f\|_r = \|f\|_r$ (see Lemma 3) that

$$\begin{aligned} (38) \quad & \|(c\langle\nabla\rangle_c)^{-1}(F(t_\ell + \tau) - F_{\ell+1})\|_{r+1} \\ & \leq \|(c\langle\nabla\rangle_c)^{-1}(F(t_\ell) - F_\ell)\|_{r+1} \\ & \quad + \tau \|\langle\nabla\rangle_c^{-2}(\dot{n}(t_\ell)u(t_\ell) - \dot{n}_\ell u_\ell)\|_{r+1} \\ & \quad + \tau \|\langle\nabla\rangle_c^{-2}\varphi_1\left(\frac{i}{2}\tau\Delta\right)\left(n(t_\ell)c\langle\nabla\rangle_c u(t_\ell) - n_\ell c\langle\nabla\rangle_c u_\ell\right)\|_{r+1} \\ & \quad + \tau \|\langle\nabla\rangle_c^{-2}\varphi_1(-i\tau(c\langle\nabla\rangle_c + c^2))\left(n(t_\ell)c\langle\nabla\rangle_c \bar{u}(t_\ell) - n_\ell c\langle\nabla\rangle_c \bar{u}_\ell\right)\|_{r+1} \\ & \quad + \tau^2 KM_{t_{\ell+1}, r+3}^p \\ & =: \|(c\langle\nabla\rangle_c)^{-1}(F(t_\ell) - F_\ell)\|_{r+1} + T_1^F + T_2^F + T_3^F + \tau^2 KM_{t_{\ell+1}, r+3}^p, \end{aligned}$$

where we have used that the definition of the φ_1 function (see (21)) implies that

$$\|\varphi_1\left(\frac{i}{2}\tau\Delta\right)\|_r \leq 1 \quad \text{and} \quad \|\varphi_1(-i\tau(c\langle\nabla\rangle_c + c^2))\|_r \leq 1.$$

We will estimate the terms on the right hand side T_j^F separately.

4.1.1. Bound on the first term T_1^F . Note that

$$\begin{aligned} \dot{n}(t_\ell)u(t_\ell) - \dot{n}_\ell u_\ell &= \dot{n}(t_\ell)u(t_\ell) - (\dot{n}_\ell - \dot{n}(t_\ell) + \dot{n}(t_\ell))u_\ell \\ &= (\dot{n}(t_\ell) - \dot{n}_\ell)u_\ell + \dot{n}(t_\ell)(u(t_\ell) - u_\ell). \end{aligned}$$

Thanks to Lemma 3 and the bilinear estimate (17) we have that

$$\|\langle\nabla\rangle_c^{-2}(fg)\|_{r+1} \leq \|fg\|_{r-1} \leq K\|f\|_{r-1}\|g\|_{r+1}$$

which thus implies that

$$\begin{aligned} (39) \quad T_1^F &:= \tau \|\langle\nabla\rangle_c^{-2}(\dot{n}(t_\ell)u(t_\ell) - \dot{n}_\ell u_\ell)\|_{r+1} \\ &\leq \tau K (\|\dot{n}(t_\ell) - \dot{n}_\ell\|_{r-1}\|u_\ell\|_{r+1} + \|\dot{n}(t_\ell)\|_{r-1}\|u(t_\ell) - u_\ell\|_{r+1}) \\ &\leq \tau KM_{t_\ell, r} B_{t_\ell, r} (\|\dot{n}(t_\ell) - \dot{n}_\ell\|_{r-1} + \|u(t_\ell) - u_\ell\|_{r+1}) \end{aligned}$$

where $M_{t_\ell, r}$ and $B_{t_\ell, r}$ are defined in (19) and (37), respectively.

The second and third term have to be bounded more carefully.

4.1.2. *Bound on the second term T_2^F .* Note that for $\zeta \in \mathbb{R}$ with $\zeta \neq 0$ we have that

$$(40) \quad \|\tau\varphi_1(i\tau\zeta)f\|_{r+1} = \left\| \tau \frac{e^{i\tau\zeta} - 1}{i\tau\zeta} f \right\|_{r+1} \leq \|(\zeta)^{-1}f\|_{r+1}.$$

Thanks to the relation

$$(41) \quad \begin{aligned} n(t_\ell)c\langle\nabla\rangle_c u(t_\ell) - n_\ell c\langle\nabla\rangle_c u_\ell &= n(t_\ell)c\langle\nabla\rangle_c u(t_\ell) - (n_\ell - n(t_\ell) + n(t_\ell))c\langle\nabla\rangle_c u_\ell \\ &= (n(t_\ell) - n_\ell)c\langle\nabla\rangle_c u_\ell + n(t_\ell)c\langle\nabla\rangle_c (u(t_\ell) - u_\ell) \end{aligned}$$

we thus obtain that

$$(42) \quad \begin{aligned} T_2^F &:= \tau \|\langle\nabla\rangle_c^{-2} \varphi_1\left(\frac{i}{2}\tau\Delta\right) \left(n(t_\ell)c\langle\nabla\rangle_c u(t_\ell) - n_\ell c\langle\nabla\rangle_c u_\ell \right)\|_{r+1} \\ &\leq \left\| \langle\nabla\rangle_c^{-2} \left(\tau\varphi_1\left(\frac{i}{2}\tau\Delta\right) \left((n(t_\ell) - n_\ell)c\langle\nabla\rangle_c u_\ell \right) \right) \right\|_{r+1} \\ &\quad + \tau \left\| \langle\nabla\rangle_c^{-2} \varphi_1\left(\frac{i}{2}\tau\Delta\right) \left(n(t_\ell)c\langle\nabla\rangle_c (u(t_\ell) - u_\ell) \right) \right\|_{r+1} \\ &\leq \left\| \langle\nabla\rangle_c^{-2} \left((n(t_\ell) - n_\ell)c\langle\nabla\rangle_c u_\ell \right) \right\|_{r-1} \\ &\quad + \tau \left\| \langle\nabla\rangle_c^{-2} \left(n(t_\ell)c\langle\nabla\rangle_c (u(t_\ell) - u_\ell) \right) \right\|_{r+1}. \end{aligned}$$

Thanks to the last estimate in Lemma 3 we have that

$$(43) \quad \left\| \langle\nabla\rangle_c^{-2} \left((n(t_\ell) - n_\ell)c\langle\nabla\rangle_c u_\ell \right) \right\|_{r-1} \leq K \|n(t_\ell) - n_\ell\|_{r-1} \|u_\ell\|_{r+1}.$$

Furthermore, the estimate $\frac{c|k|}{c(c+|k|)} \leq 1$ together with the definition of the operator $\langle\nabla\rangle_c$ in Fourier space (see (5)) yields that

$$\left\| \frac{c\langle\nabla\rangle_c}{c(c+\langle\nabla\rangle_0)} f \right\|_r \leq \|f\|_r.$$

Lemma 3 together with the above bound implies

$$(44) \quad \begin{aligned} &\tau \left\| \langle\nabla\rangle_c^{-2} \left(n(t_\ell)c\langle\nabla\rangle_c (u(t_\ell) - u_\ell) \right) \right\|_{r+1} \\ &\leq \tau \left\| \langle\nabla\rangle_c^{-2} \left(n(t_\ell) \frac{c\langle\nabla\rangle_c}{c(c+\langle\nabla\rangle_0)} c(c+\langle\nabla\rangle_0) (u(t_\ell) - u_\ell) \right) \right\|_{r+1} \\ &\leq \tau \left\| \langle\nabla\rangle_c^{-2} \left(n(t_\ell) \frac{c\langle\nabla\rangle_c}{c(c+\langle\nabla\rangle_0)} c^2 (u(t_\ell) - u_\ell) \right) \right\|_{r+1} + \tau \left\| \langle\nabla\rangle_c^{-2} \left(n(t_\ell) \frac{c\langle\nabla\rangle_c}{c(c+\langle\nabla\rangle_0)} c\langle\nabla\rangle_0 (u(t_\ell) - u_\ell) \right) \right\|_{r+1} \\ &\leq \tau \frac{1}{c^2} \left\| n(t_\ell) \frac{c\langle\nabla\rangle_c}{c(c+\langle\nabla\rangle_0)} c^2 (u(t_\ell) - u_\ell) \right\|_{r+1} + \tau \frac{1}{c} \left\| n(t_\ell) \frac{c\langle\nabla\rangle_c}{c(c+\langle\nabla\rangle_0)} c\langle\nabla\rangle_0 (u(t_\ell) - u_\ell) \right\|_r \\ &\leq \tau K \|n(t_\ell)\|_{r+1} \|u(t_\ell) - u_\ell\|_{r+1}. \end{aligned}$$

Plugging (43) and (44) into (42) we can thus conclude that

$$(45) \quad \begin{aligned} T_2^F &\leq K \left(\|n(t_\ell) - n_\ell\|_{r-1} \|u_\ell\|_{r+1} + \tau \|n(t_\ell)\|_{r+1} \|u(t_\ell) - u_\ell\|_{r+1} \right) \\ &\leq \tau K M_{t_\ell, r+1} B_{t_\ell, r} \left(\frac{1}{\tau} \|n(t_\ell) - n_\ell\|_{r-1} + \|u(t_\ell) - u_\ell\|_{r+1} \right). \end{aligned}$$

4.1.3. *Bound on the third term T_3^F .* Similarly to the bound on T_2^F we obtain by the relation (41) using (40) together with the estimate

$$\left\| \frac{1}{c\langle \nabla \rangle_c + c^2} f \right\|_r \leq \frac{1}{c^2} \|f\|_r$$

that

$$\begin{aligned} T_3^F &:= \left\| \langle \nabla \rangle_c^{-2} \varphi_1(-i\tau(c\langle \nabla \rangle_c + c^2)) \left(n(t_\ell)c\langle \nabla \rangle_c \bar{u}(t_\ell) - n_\ell c\langle \nabla \rangle_c \bar{u}_\ell \right) \right\|_{r+1} \\ &\leq \left\| \langle \nabla \rangle_c^{-2} \frac{1}{c\langle \nabla \rangle_c + c^2} \left((n(t_\ell) - n_\ell)c\langle \nabla \rangle_c \bar{u}_\ell \right) \right\|_{r+1} \\ &\quad + \tau \left\| \langle \nabla \rangle_c^{-2} \left(n(t_\ell)c\langle \nabla \rangle_c \overline{(u(t_\ell) - u_\ell)} \right) \right\|_{r+1} \\ &\leq \left\| (n(t_\ell) - n_\ell) \frac{c\langle \nabla \rangle_c}{c^2} \bar{u}_\ell \right\|_{r-1} \\ &\quad + \tau \left\| \langle \nabla \rangle_c^{-2} \left(n(t_\ell)c\langle \nabla \rangle_c \overline{(u(t_\ell) - u_\ell)} \right) \right\|_{r+1}. \end{aligned}$$

With similar arguments as above we can thus conclude

$$\begin{aligned} (46) \quad T_3^F &\leq K \left(\|n(t_\ell) - n_\ell\|_{r-1} \|u_\ell\|_{r+1} + \tau \|n(t_\ell)\|_{r+1} \|u(t_\ell) - u_\ell\|_{r+1} \right) \\ &\leq \tau K M_{t_\ell, r+1} B_{t_\ell, r} \left(\frac{1}{\tau} \|n(t_\ell) - n_\ell\|_{r-1} + \|u(t_\ell) - u_\ell\|_{r+1} \right). \end{aligned}$$

4.1.4. *Bound on error in F .* Plugging the bounds (39), (45) and (46) into (38) yields that

$$\begin{aligned} (47) \quad &\| (c\langle \nabla \rangle_c)^{-1} (F(t_\ell + \tau) - F_{\ell+1}) \|_{r+1} \\ &\leq \| (c\langle \nabla \rangle_c)^{-1} (F(t_\ell) - F_\ell) \|_{r+1} \\ &\quad + \tau K M_{t_\ell, r+1} B_{t_\ell, r} \left(\|u(t_\ell) - u_\ell\|_{r+1} + \frac{1}{\tau} \|n(t_\ell) - n_\ell\|_{r-1} + \|\dot{n}(t_\ell) - \dot{n}_\ell\|_{r-1} \right) \\ &\quad + \tau^2 K M_{t_{\ell+1}, r+3}^p. \end{aligned}$$

4.2. **Error in u .** Taking the difference of the approximation of $u(t_\ell)$ given in (32) and the numerical solution u_ℓ defined in (35) we readily obtain by the definition of the remainder \mathcal{R}_{r+2} (see Definition 4) together with the relation

$$\begin{aligned} n(t_\ell)S^F(t_\ell) - n_\ell S_\ell^F &= n(t_\ell)S^F(t_\ell) - (n_\ell - n(t_\ell) + n(t_\ell))S_\ell^F \\ &= (n(t_\ell) - n_\ell)S_\ell^F + n(t_\ell)(S^F(t_\ell) - S_\ell^F) \end{aligned}$$

that

$$\begin{aligned} (48) \quad &\|u(t_\ell) - u_\ell\|_{r+1} \leq \|c^{-1}\langle \nabla \rangle_c^{-1} (F_\ell - F(t_\ell))\|_{r+1} \\ &\quad + \|\langle \nabla \rangle_c^{-2} ((n(t_\ell) - n_\ell)S_\ell^F)\|_{r+1} + \|\langle \nabla \rangle_c^{-2} (n(t_\ell)(S^F(t_\ell) - S_\ell^F))\|_{r+1} \\ &\quad + \tau \mathcal{R}_{r+3}. \end{aligned}$$

Thanks to Lemma 3 we have

$$(49) \quad \|\langle \nabla \rangle_c^{-2} ((n(t_\ell) - n_\ell)S_\ell^F)\|_{r+1} \leq K \| (n(t_\ell) - n_\ell)S_\ell^F \|_{r-1} \leq K \left(\frac{1}{\tau} \|n(t_\ell) - n_\ell\|_{r-1} \right) (\tau \|S_\ell^F\|_{r+1}).$$

Furthermore, the bound (44) with $u(t_\ell) - u_\ell$ replaced by $(c\langle\nabla\rangle_c^{-1})(S^F(t_\ell) - S_\ell^F)$ implies that

$$(50) \quad \begin{aligned} \left\| \langle\nabla\rangle_c^{-2} \left(n(t_\ell) \left(S^F(t_\ell) - S_\ell^F \right) \right) \right\|_{r+1} &\leq \left\| \langle\nabla\rangle_c^{-2} \left(n(t_\ell) (c\langle\nabla\rangle_c) \left[(c\langle\nabla\rangle_c)^{-1} \left(S^F(t_\ell) - S_\ell^F \right) \right] \right) \right\|_{r+1} \\ &\leq K \|n(t_\ell)\|_{r+1} \left\| (c\langle\nabla\rangle_c)^{-1} \left(S^F(t_\ell) - S_\ell^F \right) \right\|_{r+1}. \end{aligned}$$

Plugging (49) and (50) into (48) yields that

$$(51) \quad \begin{aligned} \|u(t_\ell) - u_\ell\|_{r+1} &\leq \|c^{-1}\langle\nabla\rangle_c^{-1} (F_\ell - F(t_\ell))\|_{r+1} \\ &\quad + K \left(\frac{1}{\tau} \|n(t_\ell) - n_\ell\|_{r-1} \right) (\tau \|S_\ell^F\|_{r+1}) \\ &\quad + K \|n(t_\ell)\|_{r+1} \left\| (c\langle\nabla\rangle_c)^{-1} \left(S^F(t_\ell) - S_\ell^F \right) \right\|_{r+1} \\ &\quad + \tau \mathcal{R}_{r+3}. \end{aligned}$$

Taking the difference of $S^F(t_\ell)$ defined in (31) and S_ℓ^F given through (35) we obtain that

$$(52) \quad \begin{aligned} \left\| (c\langle\nabla\rangle_c)^{-1} \left(S^F(t_\ell) - S_\ell^F \right) \right\|_{r+1} &= \tau \sum_{k=0}^{\ell} \left\| (c\langle\nabla\rangle_c)^{-1} \varphi_1(i\tau c\langle\nabla\rangle_c) \left(F(t_k) - F_k \right) \right\|_{r+1} \\ &\leq \tau \sum_{k=0}^{\ell} \left\| (c\langle\nabla\rangle_c)^{-1} \left(F(t_k) - F_k \right) \right\|_{r+1}, \end{aligned}$$

where we have used that $\|\varphi_1(i\tau c\langle\nabla\rangle_c)\|_r \leq 1$.

The definition of S_ℓ^F (see (35) with initial value (87)) also yields that

$$\|S_\ell^F\|_{r+1} \leq \|u(0)\|_{r+1} + \tau \sum_{k=0}^{\ell} \|\varphi_1(i\tau c\langle\nabla\rangle_c) F_k\|_{r+1}.$$

From the estimate (40) we can furthermore conclude that

$$(53) \quad \begin{aligned} \tau \|S_\ell^F\|_{r+1} &\leq \tau \|u(0)\|_{r+1} + \tau \sum_{k=0}^{\ell} \|\tau \varphi_1(i\tau c\langle\nabla\rangle_c) F_k\|_{r+1} \\ &\leq \tau \|u(0)\|_{r+1} + \tau \sum_{k=0}^{\ell} \left\| (c\langle\nabla\rangle_c)^{-1} F_k \right\|_{r+1} \\ &\leq \tau \|u(0)\|_{r+1} + t_{\ell+1} \sup_{0 \leq k \leq \ell} \left\| (c\langle\nabla\rangle_c)^{-1} F_k \right\|_{r+1}. \end{aligned}$$

Plugging (52) and (53) into (51) we thus obtain by the definition of $B_{t_\ell, r}$ in (37) that

$$(54) \quad \begin{aligned} \|u(t_\ell) - u_\ell\|_{r+1} &\leq \|c^{-1}\langle\nabla\rangle_c^{-1} (F_\ell - F(t_\ell))\|_{r+1} \\ &\quad + K B_{t_\ell, r} t_\ell \left(\frac{1}{\tau} \|n(t_\ell) - n_\ell\|_{r-1} \right) \\ &\quad + K M_{t_\ell, r+1} \left(\tau \sum_{k=0}^{\ell} \left\| c^{-1}\langle\nabla\rangle_c^{-1} (F(t_k) - F_k) \right\|_{r+1} \right). \end{aligned}$$

4.3. **Error in (n, \dot{n}) .** In the following we define the rotation matrix

$$(55) \quad \mathcal{D}(\tau\langle\nabla\rangle_0) = \begin{pmatrix} \cos(\tau\langle\nabla\rangle_0) & \sin(\tau\langle\nabla\rangle_0) \\ -\sin(\tau\langle\nabla\rangle_0) & \cos(\tau\langle\nabla\rangle_0) \end{pmatrix}.$$

Taking the difference of the approximation to the exact solution $(n(t_{\ell+1}), \dot{n}(t_{\ell+1}))$ given in (34) and the numerical solution $(n_{\ell+1}, \dot{n}_{\ell+1})$ defined in (35) we readily obtain by the definition of the remainder \mathcal{R}_{r+2} (see Definition 4), the rotation matrix (55) and the relation

$$(56) \quad \begin{aligned} |u(t_\ell)| - |u_\ell^2| &= (u(t_\ell) - u_\ell)\overline{u(t_\ell)} + u_\ell\overline{(u(t_\ell) - u_\ell)}, \\ u(t_\ell)^2 - u_\ell^2 &= (u(t_\ell) - u_\ell)(u(t_\ell) + u_\ell) \end{aligned}$$

(with the corresponding complex conjugate version) that

$$\begin{aligned} \begin{pmatrix} n(t_{\ell+1}) - n_{\ell+1} \\ \langle\nabla\rangle_0^{-1}(\dot{n}(t_\ell) - \dot{n}_\ell) \end{pmatrix} &= \mathcal{D}(\tau\langle\nabla\rangle_0) \begin{pmatrix} n(t_\ell) - n_\ell \\ \langle\nabla\rangle_0^{-1}(\dot{n}(t_\ell) - \dot{n}_\ell) \end{pmatrix} \\ &+ \frac{\tau}{4} \begin{pmatrix} \tau \frac{\sin(\tau\langle\nabla\rangle_0)}{\tau\langle\nabla\rangle_0} \langle\nabla\rangle_0^2 \left(p_1(u(t_\ell), u_\ell)(u(t_\ell) - u_\ell) \right) \\ \cos(\tau\langle\nabla\rangle_0) \langle\nabla\rangle_0 \left(p_2(u(t_\ell), u_\ell)(u(t_\ell) - u_\ell) \right) \end{pmatrix} + \begin{pmatrix} \tau^3 \text{sinc}(\tau\langle\nabla\rangle_0) \mathcal{R}_{r+4} \\ \tau^2 \mathcal{R}_{r+3} \end{pmatrix}. \end{aligned}$$

Thereby, p_1 and p_2 simply denote polynomials in $u(t_\ell), u_\ell$ (according to (56)) due to the bounds (see (21))

$$|\varphi_1(\pm 2ic^2)| \leq 1, \quad |\varphi_2(\pm 2ic^2)| \leq 1.$$

Solving the above recursion we obtain that

$$\begin{aligned} &\begin{pmatrix} n(t_{\ell+1}) - n_{\ell+1} \\ \langle\nabla\rangle_0^{-1}(\dot{n}(t_\ell) - \dot{n}_\ell) \end{pmatrix} \\ &= \frac{\tau}{4} \sum_{k=0}^{\ell} \mathcal{D}(\tau\langle\nabla\rangle_0)^k \begin{pmatrix} \tau \frac{\sin(\tau\langle\nabla\rangle_0)}{\tau\langle\nabla\rangle_0} \langle\nabla\rangle_0^2 \left(p_1(u(t_{n-k}), u_{n-k})(u(t_{n-k}) - u_{n-k}) \right) \\ \cos(\tau\langle\nabla\rangle_0) \langle\nabla\rangle_0 \left(p_2(u(t_{n-k}), u_{n-k})(u(t_{n-k}) - u_{n-k}) \right) \end{pmatrix} \\ &+ \ell\tau \begin{pmatrix} \tau^2 \text{sinc}(\tau\langle\nabla\rangle_0) \mathcal{R}_{r+4} \\ \tau \mathcal{R}_{r+3} \end{pmatrix} \\ &= \frac{\tau}{4} \sum_{k=1}^{\ell} \mathcal{D}(\tau\langle\nabla\rangle_0)^{k-1} \{ \mathcal{N}(u(t_{n-k}), u_{n-k}) \} \\ &+ \frac{\tau}{4} \begin{pmatrix} \tau \frac{\sin(\tau\langle\nabla\rangle_0)}{\tau\langle\nabla\rangle_0} \langle\nabla\rangle_0^2 \left(p_1(u(t_n), u_n)(u(t_n) - u_n) \right) \\ \cos(\tau\langle\nabla\rangle_0) \langle\nabla\rangle_0 \left(p_2(u(t_n), u_n)(u(t_n) - u_n) \right) \end{pmatrix} + t_\ell \begin{pmatrix} \tau^2 \text{sinc}(\tau\langle\nabla\rangle_0) \mathcal{R}_{r+4} \\ \tau \mathcal{R}_{r+3} \end{pmatrix}, \end{aligned}$$

where we have set

$$\begin{aligned} \mathcal{N}(u(t_{n-k}), u_{n-k}) &= \begin{pmatrix} \mathcal{N}_1(u(t_{n-k}), u_{n-k}) \\ \mathcal{N}_2(u(t_{n-k}), u_{n-k}) \end{pmatrix} \\ &:= \mathcal{D}(\tau\langle\nabla\rangle_0) \begin{pmatrix} \tau \frac{\sin(\tau\langle\nabla\rangle_0)}{\tau\langle\nabla\rangle_0} \langle\nabla\rangle_0^2 \left(p_1(u(t_{n-k}), u_{n-k})(u(t_{n-k}) - u_{n-k}) \right) \\ \cos(\tau\langle\nabla\rangle_0) \langle\nabla\rangle_0 \left(p_2(u(t_{n-k}), u_{n-k})(u(t_{n-k}) - u_{n-k}) \right) \end{pmatrix}. \end{aligned}$$

Note that for all $k \geq 1$ it holds that

$$(57) \quad \|\mathcal{D}(\tau\langle\nabla\rangle_0)^{k-1}\|_r \leq 1.$$

Together with the observation

$$\begin{aligned} \mathcal{N}_1(u(t_{n-k}), u_{n-k}) &= \cos(\tau\langle\nabla\rangle_0) \tau \frac{\sin(\tau\langle\nabla\rangle_0)}{\tau\langle\nabla\rangle_0} \langle\nabla\rangle_0^2 \left(p_1(u(t_{n-k}, u_{n-k})(u(t_{n-k}) - u_{n-k})) \right) \\ &\quad + \sin(\tau\langle\nabla\rangle_0) \cos(\tau\langle\nabla\rangle_0) \langle\nabla\rangle_0 \left(p_2(u(t_{n-k}, u_{n-k})(u(t_{n-k}) - u_{n-k})) \right) \\ &= \tau \cos(\tau\langle\nabla\rangle_0) \frac{\sin(\tau\langle\nabla\rangle_0)}{\tau\langle\nabla\rangle_0} \langle\nabla\rangle_0^2 \left\{ \left(p_1(u(t_{n-k}, u_{n-k})(u(t_{n-k}) - u_{n-k})) \right) \right. \\ &\quad \left. + \left(p_2(u(t_{n-k}, u_{n-k})(u(t_{n-k}) - u_{n-k})) \right) \right\} \end{aligned}$$

we thus obtain that

$$(58) \quad \|n(t_{\ell+1}) - n_{\ell+1}\|_{r-1} \leq \tau K M_{t_\ell, r} B_{t_\ell, r} \left(\tau \sum_{k=0}^{\ell} \|u(t_k) - u_k\|_{r+1} \right) + \tau^2 M_{t_{\ell+1}, r+3}^P$$

as well as the (classical) bound

$$\begin{aligned} \|n(t_{\ell+1}) - n_{\ell+1}\|_r + \|\langle\nabla\rangle_0^{-1}(\dot{n}(t_\ell) - \dot{n}_\ell)\|_{r-1} &\leq K M_{t_\ell, r} B_{t_\ell, r} \left(\tau \sum_{k=0}^{\ell} \|u(t_k) - u_k\|_{r+1} \right) \\ &\quad + \tau M_{t_{\ell+1}, r+3}^P. \end{aligned}$$

Hence, we can conclude that

$$(59) \quad \begin{aligned} &\frac{1}{\tau} \|n(t_{\ell+1}) - n_{\ell+1}\|_{r-1} + \|n(t_{\ell+1}) - n_{\ell+1}\|_r + \|\dot{n}(t_\ell) - \dot{n}_\ell\|_{r-1} \\ &\leq K M_{t_\ell, r} B_{t_\ell, r} \left(\tau \sum_{k=0}^{\ell} \|u(t_k) - u_k\|_{r+1} \right) + \tau M_{t_{\ell+1}, r+3}^P. \end{aligned}$$

4.4. The convergence theorem. The numerical solutions $(u_\ell, F_\ell, n_\ell, \dot{n}_\ell)$ defined by the oscillatory integration scheme (35) allows a first-order approximation to the exact solution $(u(t_\ell), F(t_\ell), n(t_\ell), \dot{n}(t_\ell))$ of the Klein-Gordon-Zakharov system (13) uniformly in c . More precisely, with

$$z_\ell := \frac{1}{2}(u_\ell + \bar{u}_\ell)$$

(recall the transformation (7)) the following convergence result holds.

Theorem 9 (Convergence). *Fix $r > d/2$. Assume that $(u(0), n(0), \dot{n}(0)) \in H^{r+4} \times H^{r+3} \times H^{r+2}$. Then there exist constants $T > 0, \tau_0 > 0, K > 0$ such that for all $t_\ell \leq T, \tau \leq \tau_0$ and all $c \geq 1$ we have that*

$$(60) \quad \|z(t_\ell) - z_\ell\|_{r+1} + \|n(t_\ell) - n_\ell\|_r + \|\dot{n}(t_\ell) - \dot{n}_\ell\|_{r-1} \leq K\tau,$$

where the constant K depends on T , on $M_{T, r+3}$ defined in (19), and on r , but can be chosen independently of c .

Proof. Due to the local wellposedness of the Klein-Gordon-Zakharov system (13) (see, e.g., [25, 26, 29]) we know that there exists a $T > 0$ such that $M_{T, r+3}$ defined in (19) is finite. Thereby, observe that by the definition of $F = \partial_t u$ we have (see (8))

$$iF = -c\langle\nabla\rangle_c u - \frac{1}{2}c\langle\nabla\rangle_c^{-1}n(u + \bar{u})$$

such that by Lemma 3 and the bilinear estimate (17) we obtain

$$\|(c\langle\nabla\rangle_c)^{-1}F\|_{r+1} \leq \|u\|_{r+1} + \|nu\|_{r-1} \leq \|u\|_{r+1} + K\|n\|_{r-1}\|u\|_{r+1}.$$

Collecting the error bounds (47), (54) and (59) yields that

$$\begin{aligned}
& \|(c\langle\nabla\rangle_c)^{-1}(F(t_\ell + \tau) - F_{\ell+1})\|_{r+1} \\
& \leq \|(c\langle\nabla\rangle_c)^{-1}(F(t_\ell) - F_\ell)\|_{r+1} \\
& \quad + \tau KM_{t_\ell, r+1} B_{t_\ell, r} \left(\|u(t_\ell) - u_\ell\|_{r+1} + \frac{1}{\tau} \|n(t_\ell) - n_\ell\|_{r-1} + \|\dot{n}(t_\ell) - \dot{n}_\ell\|_{r-1} \right) \\
& \quad + \tau^2 KM_{t_{\ell+1}, r+3}^p, \\
(61) \quad & \|u(t_{\ell+1}) - u_{\ell+1}\|_{r+1} \\
& \leq \|c^{-1}\langle\nabla\rangle_c^{-1}(F(t_{\ell+1}) - F_{\ell+1})\|_{r+1} \\
& \quad + KB_{t_\ell, r} t_\ell \left(\frac{1}{\tau} \|n(t_{\ell+1}) - n_{\ell+1}\|_{r-1} \right) \\
& \quad + KM_{t_\ell, r+1} \left(\tau \sum_{k=0}^{\ell+1} \|c^{-1}\langle\nabla\rangle_c^{-1}(F(t_k) - F_k)\|_{r+1} \right), \\
& \quad \frac{1}{\tau} \|n(t_{\ell+1}) - n_{\ell+1}\|_{r-1} + \|n(t_{\ell+1}) - n_{\ell+1}\|_r + \|\dot{n}(t_{\ell+1}) - \dot{n}_{\ell+1}\|_{r-1} \\
& \leq KM_{t_\ell, r} B_{t_\ell, r} \left(\tau \sum_{k=0}^{\ell} \|u(t_k) - u_k\|_{r+1} \right) + \tau M_{t_{\ell+1}, r+3}^p.
\end{aligned}$$

In the following we assume that

$$\text{for all } k \leq \ell \quad : \quad B_{t_\ell, r} \leq M_1, \quad M_{t_{\ell+1}, r+1} \leq M_2, \quad M_{t_{\ell+1}, r+3} \leq M_3.$$

Plugging the estimates on the error in n and \dot{n} into the error recursions in u and F yields together with

$$\tau \sum_{k=0}^{\ell} \|f_k\|_r \leq t_{\ell+1} \sup_{0 \leq k \leq \ell} \|f_k\|_r$$

by (61) that

$$\begin{aligned}
(62) \quad & \|(c\langle\nabla\rangle_c)^{-1}(F(t_\ell + \tau) - F_{\ell+1})\|_{r+1} \leq \|(c\langle\nabla\rangle_c)^{-1}(F(t_\ell) - F_\ell)\|_{r+1} \\
& \quad + \tau t_\ell \mathcal{K}_1(M_1, M_2, M_3) \sup_{0 \leq k \leq \ell} \|u(t_\ell) - u_\ell\|_{r+1} \\
& \quad + \tau^2 KM_{t_{\ell+1}, r+3}^p
\end{aligned}$$

as well as

$$\begin{aligned}
(63) \quad & \|u(t_{\ell+1}) - u_{\ell+1}\|_{r+1} \leq t_\ell \mathcal{K}_2(M_1, M_2, M_3) \sup_{0 \leq k \leq \ell} \|c^{-1}\langle\nabla\rangle_c^{-1}(F(t_{k+1}) - F_{k+1})\|_{r+1} \\
& \quad + \tau KB_{t_\ell, r} t_\ell M_{t_{\ell+1}, r+3}^p,
\end{aligned}$$

where the constants \mathcal{K}_1 and \mathcal{K}_2 depend on t_ℓ, M_1, M_2 and M_3 , but can be chosen independently of c .

Plugging (63) into (64) finally yields with the inductive assumption that the error in F is growing that

$$(64) \quad \begin{aligned} \|(c\langle\nabla\rangle_c)^{-1}(F(t_\ell + \tau) - F_{\ell+1})\|_{r+1} &\leq \left(1 + \tilde{\mathcal{K}}_1(t_\ell, M_1, M_2, M_3)\tau\right) \|(c\langle\nabla\rangle_c)^{-1}(F(t_\ell) - F_\ell)\|_{r+1} \\ &\quad + \tau^2 \tilde{\mathcal{K}}_2(t_\ell, M_1, M_2, M_3), \end{aligned}$$

where $\tilde{\mathcal{K}}_1$ and $\tilde{\mathcal{K}}_2$ depend on t_ℓ, M_1, M_2 and M_3 , but can be chosen independently of c .

Collecting the estimates in (64), (63) and (59) the assertion then follows by the transformation (7) together with an inductive, respectively, *Lady Windermere's fan* argument (see, for example [21, 24]). \square

The uniform convergence rate in c stated in Theorem 9 is numerically confirmed in Figure 1.

4.5. Asymptotic convergence. The oscillatory integrator (35) is *asymptotic preserving* in the sense that it converges asymptotically (i.e., for $c \rightarrow \infty$) to the solution of the corresponding Zakharov limit system (2) (for sufficiently smooth solutions).

Remark 10 (The Zakharov limit). Note that exact solutions (z, n) of the Klein-Gordon-Zakharov system (1) converge asymptotically to the Zakharov system (2) in the following sense: For sufficiently smooth solutions we have that (see, e.g., [8, 25, 26, 31])

$$(65) \quad \begin{aligned} z(t, x) &= \frac{1}{2} \left(e^{ic^2t} u^\infty(t, x) + e^{-ic^2t} \overline{u}^\infty(t, x) \right) + c^{-2} \mathcal{R}_{r+4}, \\ n(t, x) &= n^\infty(t, x) + c^{-2} \mathcal{R}_{r+5}, \end{aligned}$$

where (u^∞, n^∞) solve the Zakharov system (cf. (2))

$$(66) \quad \begin{aligned} 2i\partial_t u^\infty &= \Delta u^\infty - n^\infty u^\infty, \\ \partial_{tt} n^\infty - \Delta n^\infty &= \frac{1}{2} \Delta |u^\infty|^2 \end{aligned}$$

equipped with the initial values

$$u^\infty(0) = z(0) - ic^{-2}\partial_t z(0), \quad n^\infty(0) = n(0) \quad \text{and} \quad \dot{n}^\infty(0) = \dot{n}(0).$$

Formally, the Zakharov limit system (66) can be derived by introducing the *twisted variable* (cf. e.g., [25, 26])

$$(67) \quad u_*(t) := e^{-ic^2t} u(t).$$

The product rule together with equation (8) yields the following equation in u_*

$$(68) \quad \begin{aligned} i\partial_t u_* &= c^2 u_* + e^{-ic^2t} \partial_t u \\ &= -(c\langle\nabla\rangle_c - c^2) u_* - \frac{1}{2} c\langle\nabla\rangle_c^{-1} n \left(u_* + e^{-2ic^2t} \overline{u_*} \right). \end{aligned}$$

Together with the approximations (cf. Lemma 3)

$$c\langle\nabla\rangle_c - c^2 \rightarrow -\frac{1}{2}\Delta + \mathcal{O}(c^{-2}\Delta^2), \quad c\langle\nabla\rangle_c^{-1} \rightarrow 1 + \mathcal{O}(c^{-2}\Delta)$$

we formally obtain that

$$2i\partial_t u_* = \Delta u_* - n u_* - e^{-2ic^2t} n \overline{u_*} + c^{-2} \mathcal{R}_{r+4}.$$

The equation in n in terms of u_* is given by (see (8))

$$\partial_{tt} n - \Delta n = \frac{1}{4} \Delta \left(2|u_*|^2 + e^{2ic^2t} (u_*)^2 + e^{-2ic^2t} (\overline{u_*})^2 \right).$$

For a smooth function f we furthermore have (by integration by parts) that

$$\begin{aligned} \int_0^t e^{\pm 2ic^2\xi} f(u^*(\xi), n(\xi)) \, d\xi &= \frac{1}{\pm 2ic^2} \left(e^{\pm 2ic^2t} f(u^*(t), n(t)) - f(u^*(0), n(0)) \right) \\ &\quad + \frac{1}{\mp 2ic^2} \int_0^t e^{\pm 2ic^2\xi} \partial_\xi f(u^*(\xi), n(\xi)) \, d\xi. \end{aligned}$$

We can thus conclude the Zakharov limit system (66) (for sufficiently smooth solutions) thanks to the uniform boundedness of $\partial_t u^*$ and $\partial_t n$:

$$\|\partial_\xi u^*(\xi)\|_{r+1} + \|\partial_\xi n(\xi)\|_r \leq KM_{T,r+2}$$

which hold thanks to Lemma 3 and Lemma 6 for some constant $K > 0$ independent of c and $M_{T,r}$ defined in (19).

Theorem 9 together with the approximation in (65) implies that the oscillatory integrator (35) converges at order $\tau + c^{-2}$ towards the limit solutions of the Zakharov system. More precisely, for sufficiently smooth solutions the scheme (35) allows an approximation towards the solutions (u^∞, n^∞) of the Zakharov limit system (66) with the convergence rate

$$\|u^\infty(t_\ell) - e^{-ic^2t_\ell} u_\ell\|_{r+1} + \|n^\infty(t_\ell) - n_\ell\|_r + \|\dot{n}^\infty(t_\ell) - \dot{n}_\ell\|_{r-1} \leq K(\tau + c^{-2})$$

for some constant $K > 0$ which is independent of τ and c . With the transformation (7) at hand we can in particular deduce for

$$z^\infty := \frac{1}{2} \left(e^{ic^2t} u^\infty(t, x) + e^{-ic^2t} \overline{u^\infty}(t, x) \right) \quad \text{and} \quad z_\ell := \frac{1}{2}(u_\ell + \overline{u}_\ell)$$

that

$$(69) \quad \|z^\infty(t_\ell) - z_\ell\|_{r+1} + \|n^\infty(t_\ell) - n_\ell\|_r + \|\dot{n}^\infty(t_\ell) - \dot{n}_\ell\|_{r-1} \leq K(\tau + c^{-2}).$$

The asymptotic convergence (69) of our scheme (35) towards the solutions of the Zakharov limit system (66) is numerically confirmed in Figure 2.

5. A SECOND ORDER UNIFORMLY ACCURATE OSCILLATORY INTEGRATOR FOR KGZ

Our novel technique allows us to develop higher-order uniformly accurate scheme for the Klein-Gordon-Zakharov system (1) which confirm uniformly in c . In this section we develop a *second-order uniformly accurate integrator* which allows an error at order $\mathcal{O}(\tau^2)$ uniformly in c . The construction of the second order scheme is based on iterating Duhamel's formula (15) in (F, n, \dot{n}) and integrating the occurring highly oscillatory phases e^{ikc^2t} ($k \in \mathbb{Z}$) and their interactions exactly.

5.1. Collection of essential lemma and notation.

Definition 11. In the following we define the operator

$$\mathcal{A}_c = c\langle \nabla \rangle_c - c^2.$$

Lemma 12. *Locally second-order uniform approximations to $(u, n, \dot{n})(t_\ell + \xi)$ are given by*

$$\begin{aligned} u(t_\ell + \xi) &= e^{i\xi c \langle \nabla \rangle_c} u(t_\ell) + i\xi \frac{1}{2} c \langle \nabla \rangle_c^{-1} e^{ic^2 \xi} \left\{ n(t_\ell) u(t_\ell) + \varphi_1(-i\xi(c \langle \nabla \rangle_c + c^2)) (n(t_\ell) \bar{u}(t_\ell)) \right\} \\ &\quad + \xi^2 \mathcal{R}_{r+4}, \\ n(t_\ell + \xi) &= n(t_\ell) + \xi \dot{n}(t_\ell) + \xi^2 \mathcal{R}_{r+4}, \\ \dot{n}(t_\ell + \xi) &= -\xi \langle \nabla \rangle_0^2 n(t_\ell) + \dot{n}(t_\ell) + \frac{\xi}{4} \Delta \left\{ 2|u(t_\ell)|^2 + \varphi_1(2ic^2 \xi) u(t_\ell)^2 + \varphi_1(-2ic^2 \xi) \overline{u(t_\ell)}^2 \right\} + \xi^2 \mathcal{R}_{r+4}. \end{aligned}$$

Proof. Duhamel's formula in u (see (16)) together with the approximations (see Lemma 3)

$$u(t_\ell + \zeta) = e^{i\zeta^2 \zeta} u(t_\ell) + \zeta \mathcal{R}_{r+2}, \quad e^{i\zeta(c^2 - c \langle \nabla \rangle_c)} = e^{i\zeta \frac{1}{2} \Delta} + \zeta \mathcal{R}_{r+4}$$

implies by the definition of the φ_1 -function (see (21)) that

$$(70) \quad \begin{aligned} u(t_\ell + \xi) &= e^{i\xi c \langle \nabla \rangle_c} u(t_\ell) + \frac{i}{2} \xi c \langle \nabla \rangle_c^{-1} e^{i\xi c \langle \nabla \rangle_c} \left(\varphi_1(i\xi \frac{1}{2} \Delta) (n(t_\ell) u(t_\ell)) \right. \\ &\quad \left. + \varphi_1(-i\xi(c \langle \nabla \rangle_c + c^2)) (n(t_\ell) \bar{u}(t_\ell)) \right) + \xi^2 \mathcal{R}_{r+4}. \end{aligned}$$

Using the estimate in (24) and the expansion $\varphi_1(i\xi \frac{1}{2} \Delta) = 1 + \mathcal{O}(\xi \Delta)$ implies the assertion together with (34) by replacing τ with ξ in the formulas for (n, \dot{n}) . \square

5.2. Construction of the second order scheme.

5.2.1. *Approximation in F .* Lemma 12 together with the expansion $\varphi_1(-i\xi(c \langle \nabla \rangle_c + c^2)) = 1 + \mathcal{O}(\xi c^2)$ implies (as $n(t)$ is real valued) that

$$(71) \quad u(t_\ell + \xi) + \bar{u}(t_\ell + \xi) = e^{i\xi c \langle \nabla \rangle_c} u(t_\ell) + e^{-i\xi c \langle \nabla \rangle_c} \bar{u}(t_\ell) + c^2 \xi^2 \mathcal{R}_{r+4}$$

Furthermore, we obtain with the aid of Lemma 12 that

$$(72) \quad \begin{aligned} n(t_\ell + \xi) &= n(t_\ell) + \xi \dot{n}(t_\ell) + \xi^2 \mathcal{R}_{r+4}, \\ \dot{n}(t_\ell + \xi) &= \dot{n}(t_\ell) + \xi \Delta (n(t_\ell) + \frac{1}{4}(u(t_\ell) + \bar{u}(t_\ell))^2) + c^2 \xi^2 \mathcal{R}_{r+4}. \end{aligned}$$

Thanks to the relation (29) and approximation (28) we furthermore obtain (as $n(t)$ is real-valued) and $\|\langle \nabla \rangle_c^{-2} c \langle \nabla \rangle_c\|_r \leq 1$ that

$$(73) \quad \begin{aligned} &ic \langle \nabla \rangle_c (u(t_\ell + \xi) - \bar{u}(t_\ell + \xi)) \\ &= (F(t_\ell + \xi) + \bar{F}(t_\ell + \xi)) \\ &= e^{i\xi c \langle \nabla \rangle_c} F(t_\ell) + e^{-i\xi c \langle \nabla \rangle_c} \bar{F}(t_\ell) \\ &\quad - \frac{\xi}{2} c \langle \nabla \rangle_c^{-1} (nc \langle \nabla \rangle_c (e^{ic^2 \xi} u(t_\ell) + e^{-ic^2 \xi} \bar{u}(t_\ell))) \\ &\quad + \frac{\xi}{2} c \langle \nabla \rangle_c^{-1} \left(e^{ic^2 \xi} \varphi_1(-i\xi(c \langle \nabla \rangle_c + c^2)) nc \langle \nabla \rangle_c \bar{u}(t_\ell) + e^{-ic^2 \xi} \varphi_1(i\xi(c \langle \nabla \rangle_c + c^2)) nc \langle \nabla \rangle_c u(t_\ell) \right) \\ &\quad + c^2 \xi^2 \mathcal{R}_{r+4}. \end{aligned}$$

Plugging the expansions (71), (72) and (73) into Duhamel's formula for $(c\langle\nabla\rangle_c)^{-1}F$ given in (15) yields as $\|c^2\langle\nabla\rangle_c^{-2}\|_r \leq 1$ that

$$(74) \quad \begin{aligned} & (c\langle\nabla\rangle_c)^{-1}F(t_\ell + \tau) = e^{i\tau c\langle\nabla\rangle_c} (c\langle\nabla\rangle_c)^{-1}F(t_\ell) \\ & + \frac{i}{2} e^{i\tau c\langle\nabla\rangle_c} \langle\nabla\rangle_c^{-2} \int_0^\tau e^{-i\xi c\langle\nabla\rangle_c} \left\{ \left(\dot{n}(t_\ell) + \xi \Delta(n(t_\ell) + \frac{1}{4}(u(t_\ell) + \bar{u}(t_\ell))^2) \right) \left(e^{i\xi c\langle\nabla\rangle_c} u(t_\ell) + e^{-i\xi c\langle\nabla\rangle_c} \bar{u}(t_\ell) \right) \right. \\ & \left. + \left(n(t_\ell) + \xi \dot{n}(t_\ell) \right) \left(F(t_\ell + \xi) + \bar{F}(t_\ell + \xi) \right) \right\} d\xi + \tau^3 \mathcal{R}_{r+4}. \end{aligned}$$

In the following we set

$$(75) \quad \mathcal{I}_0(u(t_\ell), n(t_\ell)) := u(t_\ell) \Delta(n(t_\ell) + \frac{1}{4}(u(t_\ell) + \bar{u}(t_\ell))^2) + i \dot{n}(t_\ell) \mathcal{A}_c u(t_\ell).$$

With the aid of the expansion $e^{i\xi c\langle\nabla\rangle_c} = e^{i\xi c^2} (1 + i\xi \mathcal{A}_c) + \mathcal{O}(\xi^2 \mathcal{A}_c^2)$ we then obtain together with Definition 5 that

$$(76) \quad \begin{aligned} & \int_0^\tau e^{-i\xi c\langle\nabla\rangle_c} \left(\dot{n}(t_\ell) + \xi \Delta(n(t_\ell) + \frac{1}{4}(u(t_\ell) + \bar{u}(t_\ell))^2) \right) \left(e^{i\xi c\langle\nabla\rangle_c} u(t_\ell) + e^{-i\xi c\langle\nabla\rangle_c} \bar{u}(t_\ell) \right) d\xi \\ & = \int_0^\tau e^{-i\xi(c\langle\nabla\rangle_c - c^2)} \dot{n}(t_\ell) (1 + i\xi \mathcal{A}_c) u(t_\ell) + e^{-i\xi(c\langle\nabla\rangle_c + c^2)} \dot{n}(t_\ell) (1 - i\xi \mathcal{A}_c) \bar{u}(t_\ell) d\xi \\ & + \int_0^\tau \xi e^{-i\xi c\langle\nabla\rangle_c} (e^{i\xi c^2} u(t_\ell) + e^{-i\xi c^2} \bar{u}(t_\ell)) \Delta(n(t_\ell) + \frac{1}{4}(u(t_\ell) + \bar{u}(t_\ell))^2) d\xi \\ & = \tau \varphi_1(-i\tau \mathcal{A}_c) \dot{n}(t_\ell) u(t_\ell) + \tau \varphi_1(-i\tau(c\langle\nabla\rangle_c + c^2)) \dot{n}(t_\ell) \bar{u}(t_\ell) \\ & + \tau^2 \Psi_2(-i\tau \mathcal{A}_c) \mathcal{I}_0(u(t_\ell), n(t_\ell)) + \tau^2 \overline{\Psi_2(-i\tau(c\langle\nabla\rangle_c + c^2))} \overline{\mathcal{I}_0(u(t_\ell), n(t_\ell))}. \end{aligned}$$

Using (56) we similarly obtain that

$$(77) \quad \begin{aligned} & \int_0^\tau e^{-i\xi c\langle\nabla\rangle_c} \left(\left(n(t_\ell) + \xi \dot{n}(t_\ell) \right) \left(F(t_\ell + \xi) + \bar{F}(t_\ell + \xi) \right) \right) d\xi \\ & = \int_0^\tau \left\{ e^{-i\xi \mathcal{A}_c} n(t_\ell) (1 + i\xi \mathcal{A}_c) F(t_\ell) + e^{-i\xi(c\langle\nabla\rangle_c + c^2)} n(t_\ell) (1 - i\xi \mathcal{A}_c) \bar{F}(t_\ell) \right. \\ & - \frac{\xi}{2} n(t_\ell) c\langle\nabla\rangle_c^{-1} \left(e^{-i\xi \mathcal{A}_c} n c\langle\nabla\rangle_c u(t_\ell) + e^{-i(c\langle\nabla\rangle_c + c^2)\xi} n c\langle\nabla\rangle_c \bar{u}(t_\ell) \right) \\ & \left. + \frac{\xi}{2} n(t_\ell) c\langle\nabla\rangle_c^{-1} \left(\varphi_1(-i\xi(c\langle\nabla\rangle_c + c^2)) n c\langle\nabla\rangle_c \bar{u}(t_\ell) + e^{-2i\xi c^2} \varphi_1(i\xi(c\langle\nabla\rangle_c + c^2)) n c\langle\nabla\rangle_c u(t_\ell) \right) \right\} d\xi \\ & + \int_0^\tau \left\{ \xi e^{-i\xi \mathcal{A}_c} (\dot{n}(t_\ell) F(t_\ell)) + \xi e^{-i\xi(c\langle\nabla\rangle_c + c^2)} (\dot{n}(t_\ell) \bar{F}(t_\ell)) \right\} d\xi \\ & = \tau \varphi_1(-i\tau \mathcal{A}_c) n(t_\ell) F(t_\ell) + \tau \varphi_1(-i\tau(c\langle\nabla\rangle_c + c^2)) n(t_\ell) \bar{F}(t_\ell) \\ & + \tau^2 \Psi_2(-i\tau \mathcal{A}_c) \left(i n(t_\ell) \mathcal{A}_c F(t_\ell) + \dot{n}(t_\ell) F(t_\ell) \right) + \tau^2 \Psi_2(-i(c\langle\nabla\rangle_c + c^2)) \left(-i n(t_\ell) \mathcal{A}_c \bar{F}(t_\ell) + \dot{n}(t_\ell) \bar{F}(t_\ell) \right) \\ & + \frac{\tau^2}{2} n(t_\ell) c\langle\nabla\rangle_c^{-1} \left\{ \left(-\Psi_2(-i\tau \mathcal{A}_c) + \frac{\varphi_1(i\tau \mathcal{A}_c) - \varphi_1(-2i\xi c^2 \tau)}{i\tau(c\langle\nabla\rangle_c + c^2)} \right) n c\langle\nabla\rangle_c u(t_\ell) \right. \\ & \left. + \left(-\Psi_2(-i(c\langle\nabla\rangle_c + c^2)\tau) + \varphi_2(-i\tau(c\langle\nabla\rangle_c + c^2)) \right) n c\langle\nabla\rangle_c \bar{u}(t_\ell) \right\}. \end{aligned}$$

Now we set

$$(78) \quad \mathcal{I}(u(t_\ell), n(t_\ell)) := u(t_\ell)\Delta(n(t_\ell) + \frac{1}{4}(u(t_\ell) + \bar{u}(t_\ell))^2) + \dot{n}(t_\ell)(i\mathcal{A}_c u(t_\ell) + F(t_\ell)) + in(t_\ell)\mathcal{A}_c F(t_\ell).$$

Plugging the calculations (76) and (77) into (74) yields together with (75) that

$$(79) \quad \begin{aligned} (c\langle\nabla\rangle_c)^{-1}F(t_\ell + \tau) &= e^{i\tau c\langle\nabla\rangle_c}(c\langle\nabla\rangle_c)^{-1}F(t_\ell) + \tau\frac{i}{2}e^{i\tau c\langle\nabla\rangle_c}\langle\nabla\rangle_c^{-2} \\ &\quad \left\{ \varphi_1(-i\tau\mathcal{A}_c)\left(\dot{n}(t_\ell)u(t_\ell) + n(t_\ell)F(t_\ell)\right) + \varphi_1(-i\tau(c\langle\nabla\rangle_c + c^2))\left(\dot{n}(t_\ell)\bar{u}(t_\ell) + n(t_\ell)\overline{F}(t_\ell)\right) \right. \\ &\quad + \tau\Psi_2(-i\tau\mathcal{A}_c)\mathcal{I}(u(t_\ell), n(t_\ell)) + \tau\Psi_2(-i\tau(c\langle\nabla\rangle_c + c^2))\overline{\mathcal{I}(u(t_\ell), n(t_\ell))} \\ &\quad \left. + \frac{\tau}{2}n(t_\ell)c\langle\nabla\rangle_c^{-1}\left[\left(-\Psi_2(-i\tau\mathcal{A}_c) + \frac{\varphi_1(i\tau\mathcal{A}_c) - \varphi_1(-2ic^2\tau)}{i\tau(c\langle\nabla\rangle_c + c^2)}\right)nc\langle\nabla\rangle_c u(t_\ell) \right. \right. \\ &\quad \left. \left. + \left(-\Psi_2(-i(c\langle\nabla\rangle_c + c^2)\tau) + \varphi_2(-i\tau(c\langle\nabla\rangle_c + c^2))\right)nc\langle\nabla\rangle_c\bar{u}(t_\ell)\right]\right\} + \tau^3\mathcal{R}_{r+4} \end{aligned}$$

with $\mathcal{I}(u(t_\ell), n(t_\ell))$ defined in (78).

5.2.2. *Approximation in u.* We have that (see (13))

$$(80) \quad u(t_\ell) = (c\langle\nabla\rangle_c)^{-1}\left\{-iF(t_\ell) - \frac{1}{2}c\langle\nabla\rangle_c^{-1}n(t_\ell)\left(I^F(t_\ell) + \overline{I^F(t_\ell)}\right)\right\}$$

with

$$I^F(t_\ell) := u(0) + \int_0^{t_\ell} F(\xi)d\xi = u(0) + \sum_{k=0}^{\ell-1} \int_0^\tau F(t_k + \xi)d\xi.$$

Note that the expansion (28) implies that

$$(81) \quad \begin{aligned} I^F(t_\ell) &= u(0) + \sum_{k=0}^{\ell-1} \int_0^\tau \left\{ e^{i\xi c\langle\nabla\rangle_c} F(t_k) + i\frac{\xi}{2}c\langle\nabla\rangle_c^{-1}e^{ic^2\xi}\varphi_1(i\xi\frac{1}{2}\Delta)\left(\dot{n}(t_k)u(t_k) + in(t_k)c\langle\nabla\rangle_c u(t_k)\right) \right. \\ &\quad \left. + i\frac{\xi}{2}c\langle\nabla\rangle_c^{-1}e^{ic^2\xi}\varphi_1(-i\xi(c\langle\nabla\rangle_c + c^2))\left(\dot{n}(t_k)\bar{u}(t_k) - in(t_k)c\langle\nabla\rangle_c\bar{u}(t_k)\right) \right\} d\xi + \tau^2\mathcal{R}_{r+4}. \end{aligned}$$

Setting

$$(82) \quad \begin{aligned} S^{F,2}(t_\ell) &:= \sum_{k=0}^{\ell-1} \left\{ \tau\varphi_1(i\tau c\langle\nabla\rangle_c)F(t_k) + i\frac{\tau^2}{2}c\langle\nabla\rangle_c^{-1}\Psi_2(ic^2\tau)\varphi_1(i\tau\frac{1}{2}\Delta)\left(\dot{n}(t_k)u(t_k) + in(t_k)c\langle\nabla\rangle_c u(t_k)\right) \right. \\ &\quad \left. + i\frac{\tau}{2}c\langle\nabla\rangle_c^{-1}\frac{i\tau c^2}{-i(c\langle\nabla\rangle_c + c^2)}\frac{\varphi_1(-i\tau c\langle\nabla\rangle_c) - \varphi_1(i\tau c^2)}{i\tau c^2}\left(\dot{n}(t_k)\bar{u}(t_k) - in(t_k)c\langle\nabla\rangle_c\bar{u}(t_k)\right) \right\} \end{aligned}$$

yields together with Definition 5 that

$$(83) \quad u(t_\ell) = (c\langle\nabla\rangle_c)^{-1}\left\{-iF(t_\ell) - \frac{1}{2}c\langle\nabla\rangle_c^{-1}n(t_\ell)\left(u(0) + S^{F,2}(t_\ell) + \overline{u(0) + S^{F,2}(t_\ell)}\right)\right\} + \tau^2\mathcal{R}_{r+4}.$$

5.2.3. *Approximation in (n, \dot{n}) .* In the following we set

$$\mathcal{J}(u(t_\ell), n(t_\ell), \xi) := \frac{1}{2} c \langle \nabla \rangle_c^{-1} \left\{ n(t_\ell) u(t_\ell) + \varphi_1(-i\xi(c \langle \nabla \rangle_c + c^2)) (n(t_\ell) \bar{u}(t_\ell)) \right\}.$$

Plugging the expansion given in Lemma 12 into Duhamel's formula (15) we obtain with the aid of (24) and the observation

$$\begin{aligned} \left| e^{i\xi c \langle \nabla \rangle_c} u(t_\ell) \right|^2 &= \left((e^{i\xi \mathcal{A}_c} - 1) u(t_\ell) \right) \bar{u}(t_\ell) + u(t_\ell) e^{-i\xi \mathcal{A}_c} \bar{u}(t_\ell) + \mathcal{O}(\xi^2 \mathcal{A}_c u(t_\ell)) \\ \left(e^{i\xi c \langle \nabla \rangle_c} u(t_\ell) \right)^2 &= -e^{2ic^2 \xi} u^2(t_\ell) + 2u(t_\ell) e^{i\xi(c^2 + c \langle \nabla \rangle_c)} u(t_\ell) + \mathcal{O}(\xi^2 \mathcal{A}_c u(t_\ell)) \end{aligned}$$

that

$$\begin{aligned} \dot{n}(t_\ell + \tau) &= -\langle \nabla \rangle_0 \sin(\tau \langle \nabla \rangle_0) n(t_\ell) + \cos(\tau \langle \nabla \rangle_0) \dot{n}(t_\ell) \\ &\quad + \frac{1}{4} \Delta \int_0^\tau \left\{ 2\bar{u}(t_\ell) (e^{i\xi \mathcal{A}_c} - 1) u(t_\ell) + 2u(t_\ell) e^{-i\xi \mathcal{A}_c} \bar{u}(t_\ell) \right. \\ &\quad - e^{2ic^2 \xi} u^2(t_\ell) + 2u(t_\ell) e^{i\xi(c^2 + c \langle \nabla \rangle_c)} u(t_\ell) - e^{-2ic^2 \xi} \bar{u}^2(t_\ell) + 2\bar{u}(t_\ell) e^{-i\xi(c^2 + c \langle \nabla \rangle_c)} \bar{u}(t_\ell) \\ &\quad + 2i\xi \left(e^{2ic^2 \xi} u(t_\ell) \mathcal{J}(u(t_\ell), n(t_\ell), \xi) - e^{-2ic^2 \xi} \bar{u}(t_\ell) \overline{\mathcal{J}(u(t_\ell), n(t_\ell), \xi)} \right) \\ &\quad \left. + 2i\xi \left(-u(t_\ell) \overline{\mathcal{J}(u(t_\ell), n(t_\ell), \xi)} + \bar{u}(t_\ell) \mathcal{J}(u(t_\ell), n(t_\ell), \xi) \right) \right\} d\xi \\ &\quad + \tau^3 \mathcal{R}_{r+5}. \end{aligned}$$

Note that

$$\begin{aligned} (84) \quad & 2i \int_0^\tau \xi e^{2ic^2 \xi} u(t_\ell) \mathcal{J}(u(t_\ell), n(t_\ell), \xi) d\xi \\ &= i \int_0^\tau \xi e^{2ic^2 \xi} u(t_\ell) c \langle \nabla \rangle_c^{-1} (n(t_\ell) u(t_\ell)) d\xi + i \int_0^\tau \xi e^{2ic^2 \xi} u(t_\ell) c \langle \nabla \rangle_c^{-1} \varphi_1(-i\xi(c \langle \nabla \rangle_c + c^2)) (n(t_\ell) \bar{u}(t_\ell)) d\xi \\ &= i\tau^2 \operatorname{sinc}(\tau \langle \nabla \rangle_0) \Psi_2(2ic^2 \tau) u(t_\ell) c \langle \nabla \rangle_c^{-1} (n(t_\ell) u(t_\ell)) \\ &\quad + i\tau u(t_\ell) \frac{1}{-i(\langle \nabla \rangle_c + c)} \left(\varphi_1(-i\tau \mathcal{A}_c) - \varphi_1(2ic^2 \tau) \right) \langle \nabla \rangle_c^{-1} (n(t_\ell) \bar{u}(t_\ell)) =: \tau \mathcal{J}_1^{\dot{n}}(u(t_\ell), n(t_\ell), \tau) \\ & 2i \int_0^\tau \xi \bar{u}(t_\ell) \mathcal{J}(u(t_\ell), n(t_\ell), \xi) d\xi \\ &= i \operatorname{sinc}(\tau \langle \nabla \rangle_0) \int_0^\tau \xi \bar{u}(t_\ell) c \langle \nabla \rangle_c^{-1} (n(t_\ell) u(t_\ell)) d\xi \\ &\quad + i \operatorname{sinc}(\tau \langle \nabla \rangle_0) \int_0^\tau \xi \bar{u}(t_\ell) c \langle \nabla \rangle_c^{-1} \varphi_1(-i\xi(c \langle \nabla \rangle_c + c^2)) (n(t_\ell) \bar{u}(t_\ell)) d\xi + \tau^3 \mathcal{R}_{r+3} \\ &= i \frac{\tau^2}{2} \operatorname{sinc}(\tau \langle \nabla \rangle_0) \bar{u}(t_\ell) c \langle \nabla \rangle_c^{-1} (n(t_\ell) u(t_\ell)) \\ &\quad + i\tau^2 \operatorname{sinc}(\tau \langle \nabla \rangle_0) \left(\bar{u}(t_\ell) \varphi_2(-i\tau(c \langle \nabla \rangle_c + c^2)) c \langle \nabla \rangle_c^{-1} (n(t_\ell) \bar{u}(t_\ell)) \right) + \tau^3 \mathcal{R}_{r+3} \\ &=: \tau \mathcal{J}_2^{\dot{n}}(u(t_\ell), n(t_\ell), \tau). \end{aligned}$$

Together with Definition 5 we thus obtain that

$$\begin{aligned}
(85) \quad \dot{n}(t_\ell + \tau) &= -\langle \nabla \rangle_0 \sin(\tau \langle \nabla \rangle_0) n(t_\ell) + \cos(\tau \langle \nabla \rangle_0) \dot{n}(t_\ell) \\
&+ \frac{1}{4} \tau \Delta \left\{ 2\bar{u}(t_\ell) (\varphi_1(i\tau \mathcal{A}_c) - 1) u(t_\ell) + 2u(t_\ell) \varphi_1(-i\tau \mathcal{A}_c) \bar{u}(t_\ell) - \varphi_1(2ic^2\xi) u^2(t_\ell) \right. \\
&+ 2u(t_\ell) \varphi_1(i\xi(c^2 + c\langle \nabla \rangle_c)) u(t_\ell) - \varphi_1(-2ic^2\tau) \bar{u}^2(t_\ell) + 2\bar{u}(t_\ell) \varphi_1(-i\tau(c^2 + c\langle \nabla \rangle_c)) \bar{u}(t_\ell) \\
&+ \mathcal{J}_1^{\dot{n}}(u(t_\ell), n(t_\ell), \tau) + \overline{\mathcal{J}_1^{\dot{n}}(u(t_\ell), n(t_\ell), \tau)} + \mathcal{J}_2^{\dot{n}}(u(t_\ell), n(t_\ell), \tau) + \overline{\mathcal{J}_2^{\dot{n}}(u(t_\ell), n(t_\ell), \tau)} \left. \right\} \\
&+ \tau^3 \mathcal{R}_{r+5}.
\end{aligned}$$

5.2.4. *A uniformly accurate oscillatory integrator of second order.* Collecting the results (79) and (83) (together with (82)) as well as the approximation (34) for n and (85) for \dot{n} motivates us to define our second order numerical scheme as follows:

For $0 \leq \ell \leq n-1$ we set

$$\begin{aligned}
(86) \quad (c\langle \nabla \rangle_c)^{-1} F_{\ell+1} &= e^{i\tau c\langle \nabla \rangle_c} (c\langle \nabla \rangle_c)^{-1} F_\ell + \tau \frac{i}{2} e^{i\tau c\langle \nabla \rangle_c} \langle \nabla \rangle_c^{-2} \\
&\left\{ \varphi_1(-i\tau \mathcal{A}_c) (\dot{n}_\ell u_\ell + (\psi n_\ell) F_\ell) + \varphi_1(-i\tau(c\langle \nabla \rangle_c + c^2)) (\dot{n}_\ell \bar{u}_\ell + (\psi n_\ell) \bar{F}_\ell) \right. \\
&+ \tau \psi \Psi_2(-i\tau \mathcal{A}_c) \mathcal{I}(u_\ell, n_\ell) + \tau \Psi_2(-i\tau(c\langle \nabla \rangle_c + c^2)) \overline{\mathcal{I}(u_\ell, n_\ell)} \\
&+ \frac{\tau}{2} \psi (n_\ell c\langle \nabla \rangle_c^{-1} \left[(\Psi_2(-i\tau \mathcal{A}_c) + \frac{\varphi_1(i\tau \mathcal{A}_c) - \varphi_1(-2ic^2\tau)}{i\tau(c\langle \nabla \rangle_c + c^2)}) n c\langle \nabla \rangle_c u_\ell \right. \\
&\quad \left. \left. + (-\Psi_2(-i(c\langle \nabla \rangle_c + c^2)\tau) + \varphi_2(-i\tau(c\langle \nabla \rangle_c + c^2))) n c\langle \nabla \rangle_c \bar{u}_\ell \right] \right\} \\
n_{\ell+1} &= \cos(\tau \langle \nabla \rangle_0) n_\ell + \langle \nabla \rangle_0^{-1} \sin(\tau \langle \nabla \rangle_0) \dot{n}_\ell \\
&+ \frac{\tau^2}{4} \text{sinc}(\tau \langle \nabla \rangle_0) \Delta \{ |u_\ell|^2 + \varphi_2(2ic^2\tau) u_\ell^2 + \varphi_2(-2ic^2\tau) \bar{u}_\ell^2 \} \\
\dot{n}_{\ell+1} &= -\langle \nabla \rangle_0 \sin(\tau \langle \nabla \rangle_0) n_\ell + \cos(\tau \langle \nabla \rangle_0) \dot{n}_\ell \\
&+ \frac{1}{4} \tau \Delta \left\{ 2\bar{u}_\ell (\varphi_1(i\tau \mathcal{A}_c) - 1) u_\ell + 2u_\ell \varphi_1(-i\tau \mathcal{A}_c) \bar{u}_\ell - \varphi_1(2ic^2\xi) u_\ell^2 \right. \\
&+ 2u_\ell \varphi_1(i\xi(c^2 + c\langle \nabla \rangle_c)) u_\ell - \varphi_1(-2ic^2\tau) \bar{u}_\ell^2 + 2\bar{u}_\ell \varphi_1(-i\tau(c^2 + c\langle \nabla \rangle_c)) \bar{u}_\ell \\
&+ \mathcal{J}_1^{\dot{n}}(u_\ell, n_\ell, \tau) + \overline{\mathcal{J}_1^{\dot{n}}(u_\ell, n_\ell, \tau)} + \mathcal{J}_2^{\dot{n}}(u_\ell, n_\ell, \tau) + \overline{\mathcal{J}_2^{\dot{n}}(u_\ell, n_\ell, \tau)} \left. \right\} \\
S_{\ell+1}^{F,2} &= S_\ell^{F,2} + \tau \varphi_1(i\tau c\langle \nabla \rangle_c) F_\ell \\
&+ i \frac{\tau^2}{2} \langle \nabla \rangle_c^{-2} \Psi_2(i\tau c^2) \varphi_1(i\tau \frac{1}{2} \Delta) (\dot{n}_\ell u_\ell + i n_\ell c\langle \nabla \rangle_c u_\ell) \\
&+ i \frac{\tau^2}{2} c\langle \nabla \rangle_c^{-1} \frac{c^2}{-(c\langle \nabla \rangle_c + c^2)} \frac{\varphi_1(-i\tau c\langle \nabla \rangle_c) - \varphi_1(i\tau c^2)}{i\tau c^2} (\dot{n}_\ell \bar{u}_\ell - i n_\ell c\langle \nabla \rangle_c \bar{u}_\ell) \\
u_{\ell+1} &= (c\langle \nabla \rangle_c)^{-1} \left\{ -i F_{\ell+1} - \frac{1}{2} c\langle \nabla \rangle_c^{-1} n_{\ell+1} (u_0 + S_{\ell+1}^{F,2} + \overline{u_0 + S_{\ell+1}^{F,2}}) \right\}
\end{aligned}$$

with $\mathcal{I}(u_\ell, n_\ell)$ defined in (78), $\mathcal{J}_1^{\dot{n}}$ and $\mathcal{J}_2^{\dot{n}}$ given in (84), the initial values

$$\begin{aligned}
(87) \quad u_0 &:= u(0), \quad n_0 := n(0), \quad \dot{n}_0 := \partial_t n(0), \\
F_0 &:= ic\langle \nabla \rangle_c u_0 + \frac{i}{2} c\langle \nabla \rangle_c^{-1} n_0 (u_0 + \bar{u}_0), \quad S_0^{F,2} := 0
\end{aligned}$$

and where we have included the filter function $\psi = \text{sinc}(\tau \frac{1}{2} \Delta)$.

5.3. Convergence of the second order scheme. The numerical solutions $(u_\ell, F_\ell, n_\ell, \dot{n}_\ell)$ defined by the oscillatory integration scheme (86) allow a second-order approximation to the exact solution $(u(t_\ell), F(t_\ell), n(t_\ell), \dot{n}(t_\ell))$ of the Klein-Gordon-Zakharov system (13) uniformly in c . More precisely, with

$$z_\ell := \frac{1}{2}(u_\ell + \bar{u}_\ell)$$

(recall the transformation (7)) the following convergence result holds.

Theorem 13 (Second order convergence). *Fix $r > d/2$. Assume that $(u(0), n(0), \dot{n}(0)) \in H^{r+6} \times H^{r+5} \times H^{r+4}$. Then there exist constants $T > 0, \tau_0 > 0, K > 0$ such that for all $t_\ell \leq T, \tau \leq \tau_0$ and all $c \geq 1$ we have that*

$$(88) \quad \|z(t_\ell) - z_\ell\|_{r+1} + \|n(t_\ell) - n_\ell\|_r + \|\dot{n}(t_\ell) - \dot{n}_\ell\|_{r-1} \leq K\tau^2,$$

where the constant K depends on T , on $M_{T, r+5}$ defined in (19), and on r , but can be chosen independently of c .

Proof. The convergence analysis of the second order scheme (86) follows the line of argumentation taken in Section 4 in the analysis of the first order scheme (see also the proof of Theorem 9). Therefore we only give the central steps.

Local error: The local error bound at order $\mathcal{O}(\tau^3)$ uniformly in c under the stated regularity assumptions follows by construction (e.g., taking the difference of the exact solution (79), (83), (85) and the numerical scheme (86)) together with the observation

$$\|(\psi - 1)f\|_r = \|(\text{sinc}(\tau \frac{1}{2} \Delta) - 1)f\|_r \leq \frac{1}{4}\tau^2 \|f\|_{r+4}$$

which implies that $\tau\|(\psi - 1)n(t_\ell)\|_{r+1} \leq \tau^3 \|n(t_\ell)\|_{r+5}$.

Stability: The stability analysis follows the line of argumentation given in Section 4 for the first order scheme. The essential estimates

$$\begin{aligned} \|\langle \nabla \rangle_c^{-2} (f c \langle \nabla \rangle_c g)\|_{r-1} &\leq K \|f\|_{r-1} \|g\|_{r+1} \\ \tau \|\Phi(i\tau \frac{1}{2} \Delta) f\|_{r+1} + \tau \|\Phi(-i\tau (c \langle \nabla \rangle_c + c^2)) f\|_{r+1} &\leq 2 \|f\|_{r-2} \quad \text{for } \Phi = \psi, \varphi_1, \varphi_2, \Psi_2 \end{aligned}$$

which follow from Lemma 3 and Definition 5 yield the estimate (61) with the local error increased by one order. The assertion then follows by a *Lady Windermere's fan* argument (see, for example [21, 24]), see also the proof of Theorem 9. \square

Remark 14. The second-order scheme (86) asymptotically converges to the Zakharov limit system (2) (see also Remark 10).

6. NUMERICAL EXPERIMENTS

In this section we numerically underline the theoretical convergence results presented in Theorem 9 and 13. The numerical experiments in particular confirm the uniform convergence property in the high-plasma frequency c . In the numerical experiments (see Figure 1) we observe that the error does not increase for $c \rightarrow \infty$ which is the main objective of the derived oscillatory integrator (35) and (86). Furthermore, we numerically underline the asymptotic convergence (see Section 4.5) at order c^{-2} of the scheme (35) towards solutions of the Zakharov limit system (66) (see Figure 2).

In the numerical experiments we use a standard Fourier pseudo spectral spatial discretization with the largest Fourier mode $K = 2^6$ which corresponds to a spatial mesh size $\Delta x = 0.19$. Furthermore, we choose the (c -dependent) initial values

$$z(0, x) = \frac{1}{4} \frac{\sin(x)}{2 - \cos(2x)}, \quad \partial_t z(0, x) = c^2 z(0, x), \quad n(0, x) = \frac{\sin(x) \cos(x)}{2 - \sin(2x)}, \quad \partial_t n(0, x) = \frac{1}{2} \sin(x)$$

which we integrate up to $T = 1$. In Figure 1 we plot the time-step size versus the error of the oscillatory integration schemes of first- (35) and second-order (86) for different values of c . The error in z and n is thereby measured in a discrete H^1 and L^2 norm, respectively. As a reference solution we use the scheme itself with a finer time step size $\tau \approx 6 \cdot 10^{-4}$.

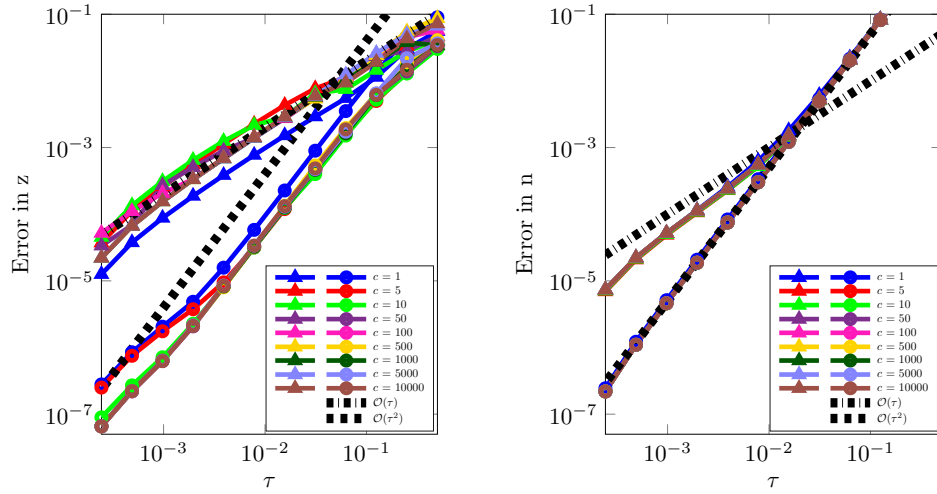


FIGURE 1. Order plot of the oscillatory integration scheme of first-order (35) and second-order (86) (double logarithmic scale): Error versus time step size. The slope of the dashed-dotted line is one and of the dashed line is two.

In Figure 2 we numerically confirm the theoretical convergence rate at order c^{-2} given in (69) of the oscillatory integration scheme (35) towards solutions of the Zakharov limit system (66) (see also Section 4.5). Thereby, we use the trigonometric integrator derived in [18] to solve the Zakharov limit system (66) numerically. Note that in [18] the complex conjugated version of (2) is considered (i.e., the equation in \bar{z}) with a scaling factor $\frac{1}{2}$. The simulation is carried out with step size $\tau \approx 10^{-6}$.

Remark 15. The numerical experiments confirm our theoretical convergence results and in particular stress the uniform convergence property of the novel first-order (35) and second-order (86) oscillatory integrators with respect to the high-plasma frequency c (cf. Theorem 9 and Theorem 13, respectively) as well as asymptotic convergence (cf. (69)) towards the Zakharov limit system. The numerical experiments suggest that the error constant of the second-order scheme (86) is even smaller for large values of c . In nonstiff regimes $c = 1$ energy conservative schemes for the KGZ system (8) have been naturally proposed in literature (see, e.g., [32] for a classical finite difference discretization and [1, Section 2.2.] for a finite difference integrator

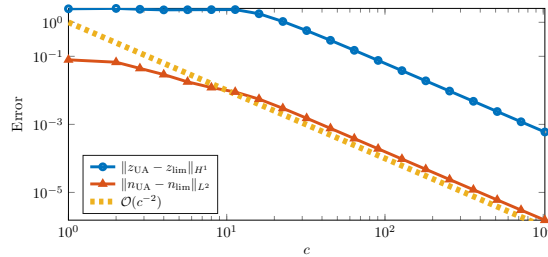


FIGURE 2. Asymptotic convergence plot (double logarithmic scale): Error versus c . The oscillatory integrator (35) converges asymptotically with rate c^{-2} to the numerical solution of the corresponding Zakharov limit system (66).

sine pseudospectral method). The new class of oscillatory integrators is in contrast based on an exponential-type discretization which is not symplectic (see also [6] for the classical Klein-Gordon setting $n = -|z|^2$). Numerical schemes which are both energy conserving *and* at the same time uniformly accurate pose an interesting open research question.

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