# Low Regularity Exponential-Type Integrators for Semilinear Schrödinger Equations 

Alexander Ostermann ${ }^{1}$ • Katharina Schratz ${ }^{2}$

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#### Abstract

We introduce low regularity exponential-type integrators for nonlinear Schrödinger equations for which first-order convergence only requires the boundedness of one additional derivative of the solution. More precisely, we will prove first-order convergence in $H^{r}$ for solutions in $H^{r+1}$ (with $r>d / 2$ ) of the derived schemes. This allows us lower regularity assumptions on the data than for instance required for classical splitting or exponential integration schemes. For one-dimensional quadratic Schrödinger equations, we can even prove first-order convergence without any loss of regularity. Numerical experiments underline the favorable error behavior of the newly introduced exponential-type integrators for low regularity solutions compared to classical splitting and exponential integration schemes.


Keywords Nonlinear Schrödinger equations • Exponential-type time integrator • Low regularity • Convergence

Mathematics Subject Classification 65M12 • 65M70 • 35Q41

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$\boxtimes$ Alexander Ostermann
alexander.ostermann@uibk.ac.at
Katharina Schratz
katharina.schratz@kit.edu
1 Department of Mathematics, University of Innsbruck, Technikerstr. 13, 6020 Innsbruck, Austria
2 Fakultät für Mathematik, Karlsruhe Institute of Technology, Englerstr. 2, 76131 Karlsruhe, Germany

## 1 Introduction

Semilinear Schrödinger equations, in particular those of type

$$
\begin{equation*}
i \partial_{t} u=-\Delta u+\mu|u|^{2 p} u, \quad p \in \mathbb{N} \tag{1}
\end{equation*}
$$

with $\mu \in \mathbb{R}$ are nowadays extensively studied numerically. In this context, splitting methods (where the right-hand side is split into the kinetic and nonlinear part, respectively) as well as exponential integrators (including Lawson-type Runge-Kutta methods) contribute particularly attractive classes of integration schemes. For an extensive overview on splitting and exponential integration methods, we refer to [ $14,16,18,26]$, and for their rigorous convergence analysis in the context of semilinear Schrödinger equations, we refer to $[2,4,6,8,9,11,12,25,31]$ and the references therein. However, within the construction of all these numerical methods the stiff part (i.e., the terms involving the differential operator $\Delta$ ) is approximated in one way or another which generally requires the boundedness of two additional spatial derivatives of the exact solution. In particular, convergence of a certain order only holds under sufficient additional regularity assumptions on the solution. In the following, we will illustrate the local error behavior of classical splitting and exponential integration methods and the thereby introduced smoothness requirements.
Splitting schemes The Strang splitting for the cubic Schrödinger equation (i.e., $p=1$ )

$$
\begin{aligned}
u_{-}^{n+1 / 2} & =\mathrm{e}^{i \frac{\tau}{2} \Delta} u^{n}, \\
u_{+}^{n+1 / 2} & =\mathrm{e}^{-i \tau \mu\left|u_{-}^{n+1 / 2}\right|^{2}} u_{-}^{n+1 / 2}, \\
u^{n+1} & =\mathrm{e}^{i \frac{\tau}{2} \Delta} u_{+}^{n+1 / 2}
\end{aligned}
$$

where the right-hand side is split into the kinetic $T(u)=i \Delta u$ and nonlinear part $V(u)=-i \mu|u|^{2} u$ is rigorously analyzed in [25]. In particular, its second-order convergence in $H^{r}$ for solutions in $H^{r+4}$ and its first-order convergence in $H^{r}$ for solutions in $H^{r+2}$ holds for all $r \geq 0$, see [25] and [10], respectively. The result follows from the fact that the local error of the splitting scheme can be expressed through the double Lie commutator $[T,[T, V]](u)$ and the Lie commutator $[T, V](u)$ for second- and first-order methods, respectively. The latter reads

$$
\frac{1}{2 \mu}[T, V](u)=(\nabla u \cdot \nabla \bar{u}) u+(\nabla u \bar{u}) \cdot \nabla u+(u \nabla \bar{u}) \cdot \nabla u+(u \overline{\Delta u}) u,
$$

see [25, Section 4.2]. Due to the appearance of $\overline{\Delta u}$ in the local error, the boundedness of at least two additional derivatives of the exact solution is required. Based on [25], fractional error estimates for the Strang splitting were established in [10] which require the boundedness of $2+2 \gamma$ additional derivatives for convergence of order $1+\gamma$, with $0<\gamma<1$. Furthermore, in [19] first-order convergence of a filtered Lie splitting method for Schrödinger equations of type (1) with $1 \leq 2 p<4 / d$ was shown in $L^{2}\left(\mathbb{R}^{d}\right)$ for solutions in $H^{2}\left(\mathbb{R}^{d}\right)$.

Classical exponential integrators The classical first-order exponential integrator in the cubic case reads

$$
\begin{equation*}
u^{n+1}=\mathrm{e}^{i \tau \Delta} u^{n}-i \mu \tau \varphi_{1}(i \tau \Delta)\left(\left|u^{n}\right|^{2} u^{n}\right) \text { with } \quad \varphi_{1}(z)=\frac{\mathrm{e}^{z}-1}{z} . \tag{2}
\end{equation*}
$$

Its construction is based on Duhamel's formula

$$
u\left(t_{n}+\tau\right)=\mathrm{e}^{i \tau \Delta} u\left(t_{n}\right)-i \mu \int_{0}^{\tau} \mathrm{e}^{i(\tau-s) \Delta}\left|u\left(t_{n}+s\right)\right|^{2 p} u\left(t_{n}+s\right) \mathrm{d} s
$$

by applying the approximation

$$
\begin{equation*}
u\left(t_{n}+s\right) \approx u\left(t_{n}\right) \tag{3}
\end{equation*}
$$

in the integral terms and solving the remaining integral over the free Schrödinger group $\mathrm{e}^{i(\tau-s) \Delta}$ exactly. Due to the approximation (3), the above scheme introduces a local error of the form

$$
\partial_{t}\left(i|u|^{2} u\right)=i \overline{\partial_{t} u} u^{2}+2 i|u|^{2} \partial_{t} u=\mu|u|^{4} u-2|u|^{2} \Delta u+u^{2} \overline{\Delta u},
$$

see [16]. Hence, first-order convergence also requires the boundedness of at least two derivatives of the exact solution due to the appearance of $\Delta u$ and its complex conjugate counterpart.

The main novelty in this work lies in the development and analysis of a first-order exponential-type integrator for Schrödinger equations of type (1)

$$
\begin{equation*}
u^{n+1}=\mathrm{e}^{i \tau \Delta}\left[u^{n}-i \mu \tau\left(u^{n}\right)^{p+1}\left(\varphi_{1}(-2 i \tau \Delta)\left(\overline{u^{n}}\right)^{p}\right)\right] \quad \text { with } \quad \varphi_{1}(z)=\frac{\mathrm{e}^{z}-1}{z} \tag{4}
\end{equation*}
$$

which only requires the boundedness of one additional derivative of the exact solution. The construction is based on Duhamel's formula looking at the twisted variable $v(t)=$ $\mathrm{e}^{-i t \Delta} u(t)$ and treating the dominant term triggered by $\bar{u}^{2 p}$ in an exact way. This idea of twisting the variable is widely used in the analysis of partial differential equations in low regularity spaces (see for instance [3]) and also well known in the context of numerical analysis, see [24] for the introduction of Lawson-type Runge-Kutta methods. However, instead of approximating the appearing integrals with a Runge-Kutta method (see for instance [20]) we integrate the dominant second-order stiff parts exactly.

A similar approach has been successfully applied to the one-dimensional KdV equation, see [17]. However, due to the Burgers-type nonlinearity, additional smoothness assumptions on the exact solution are necessary. More precisely, first-order convergence in $H^{1}$ is only guaranteed for solutions in $H^{3}$ in the KdV setting. The introduced exponential integrators for nonlinear Schrödinger equations are in contrast first-order convergent in $H^{r}$ for solutions in $H^{r+1}$ (with $r>d / 2$ ). Furthermore, we show that our approach yields methods for quadratic nonlinearities of type $u^{2}$ and $|u|^{2}$ in one dimension which are convergent in $H^{r}$ for solutions in $H^{r}$, i.e., no additional
smoothness of the solution is required. Such generous convergence results for nonlinear Schrödinger equations are up to our knowledge not yet know in the numerical analysis literature.

For practical implementation issues, we impose periodic boundary conditions and refer to [3] for local wellposedness (LWP) results of nonlinear Schrödinger equations in $H^{r}\left(\mathbb{T}^{d}\right)$. Note that in the case of a cubic nonlinearity we obtain LWP for $r>1 / 2$ if $d \leq 3$. In the case of a quadratic nonlinearity of type $u^{2}$ (or $\bar{u}^{2}$ ), LWP can be pushed down to $r>-1 / 2$ on the one-dimensional torus, see [21]. In the following let $r>d / 2$. We denote by $\|\cdot\|_{r}$ the standard $H^{r}=H^{r}\left(\mathbb{T}^{d}\right)$ Sobolev norm. In particular, we exploit the well-known bilinear estimate

$$
\begin{equation*}
\|f g\|_{r} \leq c_{r, d}\|f\|_{r}\|g\|_{r} \tag{5}
\end{equation*}
$$

which holds for some constant $c_{r, d}>0$. Furthermore, we denote by $c$ a generic constant which may depend on $r, d, p$ and $\mu$.

## 2 Low Regularity Exponential Integrators

We consider nonlinear Schrödinger equations (NLS) of type

$$
\begin{align*}
i \partial_{t} u(t, x) & =-\Delta u(t, x)+\mu|u(t, x)|^{2 p} u(t, x) \\
u(0, x) & =u^{0}(x), \quad(t, x) \in \mathbb{R} \times \mathbb{T}^{d}, \quad p \in \mathbb{N} \tag{6}
\end{align*}
$$

with $\mu \in \mathbb{R}$ and where we have set $\Delta=\sum_{k=1}^{d} \partial_{x_{k}}^{2}$. Furthermore, we employ the so-called $\varphi_{1}$ function defined as

$$
\varphi_{1}(z)=\frac{\mathrm{e}^{z}-1}{z} .
$$

In the following, we derive exponential-type integrators for Schrödinger equations of type (6) based on iterating Duhamel's formula in the twisted variable $v(t)=\mathrm{e}^{-i t \Delta} u(t)$. Note that the twisted variable satisfies

$$
\begin{equation*}
i \partial_{t} v(t)=\mu \mathrm{e}^{-i t \Delta}\left[\left|\mathrm{e}^{i t \Delta} v(t)\right|^{2 p} \mathrm{e}^{i t \Delta} v(t)\right], \quad v(0)=v^{0} \tag{7}
\end{equation*}
$$

with mild solution given by

$$
\begin{equation*}
v\left(t_{n}+\tau\right)=v\left(t_{n}\right)-i \mu \int_{0}^{\tau} \mathrm{e}^{-i\left(t_{n}+s\right) \Delta}\left[\left|\mathrm{e}^{i\left(t_{n}+s\right) \Delta} v\left(t_{n}+s\right)\right|^{2 p} \mathrm{e}^{i\left(t_{n}+s\right) \Delta} v\left(t_{n}+s\right)\right] \mathrm{d} s, \tag{8}
\end{equation*}
$$

where $t_{n}=n \tau$. In order to derive our numerical scheme, we proceed as follows. As $\mathrm{e}^{i t \Delta}$ is a linear isometry on $H^{r}$ for all $t \in \mathbb{R}$ and the bilinear estimate (5) holds we obtain that

$$
\begin{align*}
\left\|v\left(t_{n}+s\right)-v\left(t_{n}\right)\right\|_{r} & \leq|\mu| \int_{0}^{s}\left\|v\left(t_{n}+\xi\right)\right\|_{r}^{2 p+1} \mathrm{~d} \xi \\
& \leq s|\mu| \sup _{0 \leq \xi \leq s}\left\|v\left(t_{n}+\xi\right)\right\|_{r}^{2 p+1}, \quad r>d / 2 \tag{9}
\end{align*}
$$

In this sense, we have for $|s| \leq \tau$

$$
\begin{equation*}
v\left(t_{n}+s\right) \approx v\left(t_{n}\right) \tag{10}
\end{equation*}
$$

for a small time step $\tau$.
Remark 2.1 Note that the twisted variable allows the formal expansion

$$
v\left(t_{n}+s\right)-v\left(t_{n}\right)=\mathcal{O}\left(s|v|^{2 p} v\right)
$$

such that the approximation (10) holds without additional regularity assumptions (see (9) for the rigorous estimate). The classical exponential integrator (2), in contrast, is based on the approximation (3) for the original solution $u$. This approximation error is small only under additional smoothness assumptions, since

$$
u\left(t_{n}+s\right)-u\left(t_{n}\right)=\left(\mathrm{e}^{i s \Delta}-1\right) u\left(t_{n}\right)+\mathcal{O}\left(s|u|^{2 p} u\right)
$$

Plugging (10) into (8) yields the approximation

$$
\begin{equation*}
v\left(t_{n}+\tau\right) \approx v\left(t_{n}\right)-i \mu \int_{0}^{\tau} \mathrm{e}^{-i\left(t_{n}+s\right) \Delta}\left[\left|\mathrm{e}^{i\left(t_{n}+s\right) \Delta} v\left(t_{n}\right)\right|^{2 p} \mathrm{e}^{i\left(t_{n}+s\right) \Delta} v\left(t_{n}\right)\right] \mathrm{d} s \tag{11}
\end{equation*}
$$

which is the basis of our numerical scheme.
Hence, we are left with deriving a numerical approximation to the integral

$$
I_{p}^{\tau}\left(w, t_{n}\right):=\int_{0}^{\tau} \mathrm{e}^{-i\left(t_{n}+s\right) \Delta}\left[\left|\mathrm{e}^{i\left(t_{n}+s\right) \Delta} w\right|^{2 p} \mathrm{e}^{i\left(t_{n}+s\right) \Delta} w\right] \mathrm{d} s
$$

To illustrate the idea, we will first consider the cubic case $p=1$ in Sect. 2.1 below. In Sect. 2.2 we will deal with general nonlinearities $p \geq 1$. The special case of quadratic nonlinearities of type $u^{2}$ and $|u|^{2}$, respectively, will be treated in Sect. 4.

### 2.1 Cubic Nonlinearities $p=1$

For notational simplicity, we first illustrate the idea in one dimension. In Sect. 2.1.2 we will give the generalization to arbitrary dimensions $d \geq 1$.

### 2.1.1 Cubic Nonlinearities $p=1$ in Dimension $d=1$

Let $f \in L^{2}(\mathbb{T})$. Then, we will denote its Fourier expansion by $f(x)=\sum_{k \in \mathbb{Z}} \hat{f}_{k} \mathrm{e}^{i k x}$. Furthermore, we define a regularization of $\partial_{x}^{-1}$ through its action in Fourier space by

$$
\left(\partial_{x}^{-1}\right)_{k}:=\left\{\begin{array}{ll}
(i k)^{-1} & \text { if } k \neq 0 \\
0 & \text { if } k=0
\end{array} \text {, i.e., } \quad \partial_{x}^{-1} f(x)=\sum_{k \in \mathbb{Z} \backslash\{0\}}(i k)^{-1} \hat{f_{k}} \mathrm{e}^{i k x}\right.
$$

and, by continuity,

$$
\begin{equation*}
\left(\frac{\mathrm{e}^{i t \partial_{x}^{2}}-1}{i t \partial_{x}^{2}}\right)_{k \neq 0}=\frac{\mathrm{e}^{-i t k^{2}}-1}{-i t k^{2}}, \quad\left(\frac{\mathrm{e}^{i t \partial_{x}^{2}}-1}{i t \partial_{x}^{2}}\right)_{k=0}=1 . \tag{12}
\end{equation*}
$$

In the case of a cubic nonlinearity [i.e., $p=1$ in (6)] in one spatial dimension, the integral in (11) can be expressed in terms of the Fourier expansion as follows

$$
\begin{align*}
I_{1}^{\tau}\left(w, t_{n}\right)= & \int_{0}^{\tau} \mathrm{e}^{-i\left(t_{n}+s\right) \partial_{x}^{2}}\left[\left(\mathrm{e}^{-i\left(t_{n}+s\right) \partial_{x}^{2}} \bar{w}\right)\left(\mathrm{e}^{i\left(t_{n}+s\right) \partial_{x}^{2}} w\right)^{2}\right] \mathrm{d} s \\
= & \sum_{\ell \in \mathbb{Z}} \sum_{\substack{k_{1}, k_{2}, k_{3} \in \mathbb{Z} \\
\ell=-k_{1}+k_{2}+k_{3}}} \int_{0}^{\tau} \mathrm{e}^{i\left(t_{n}+s\right)\left[\ell^{2}+k_{1}^{2}-k_{2}^{2}-k_{3}^{2}\right]} \mathrm{d} s{\overline{\hat{w}_{k_{1}}}}_{\hat{w}_{k_{2}}} \hat{w}_{k_{3}} \mathrm{e}^{i \ell x} \\
= & \sum_{\ell \in \mathbb{Z}} \sum_{\substack{k_{1}, k_{2}, k_{3} \in \mathbb{Z} \\
\ell=-k_{1}+k_{2}+k_{3}}} \mathrm{e}^{i t_{n}\left[\ell^{2}+k_{1}^{2}-k_{2}^{2}-k_{3}^{2}\right]} \overline{\hat{w}_{k_{1}}} \hat{w}_{k_{2}} \hat{w}_{k_{3}} \mathrm{e}^{i \ell x}  \tag{13}\\
& \int_{0}^{\tau} \mathrm{e}^{i s\left[2 k_{1}^{2}-2 k_{1}\left(k_{2}+k_{3}\right)+2 k_{2} k_{3}\right]} \mathrm{d} s .
\end{align*}
$$

Naturally, the next step would be the exact integration of the appearing integral

$$
\begin{equation*}
\int_{0}^{\tau} \mathrm{e}^{i s\left[2 k_{1}^{2}-2 k_{1}\left(k_{2}+k_{3}\right)+2 k_{2} k_{3}\right]} \mathrm{d} s . \tag{14}
\end{equation*}
$$

However, the obtained convolution cannot be converted into the physical space straightforwardly and therefore only yields a practical scheme in dimension one as the iteration needs to be carried out fully in Fourier space. In order to obtain an efficient and practical low regularity implementation, we therefore only
treat the dominant quadratic term $2 k_{1}^{2}$ exactly.
For this purpose, we write the integrand in (14) as

$$
\begin{equation*}
\mathrm{e}^{i s\left[2 k_{1}^{2}-2 k_{1}\left(k_{2}+k_{3}\right)+2 k_{2} k_{3}\right]}=\mathrm{e}^{2 i s k_{1}^{2}}\left(1+|\beta|^{\gamma} \frac{\mathrm{e}^{i \beta}-1}{|\beta|^{\gamma}}\right) \tag{15}
\end{equation*}
$$


with $\beta=s\left(-2 k_{1}\left(k_{2}+k_{3}\right)+2 k_{2} k_{3}\right)$ and some $0 \leq \gamma \leq 1$. Inserting (15) into (13) and integrating the first term

$$
\int_{0}^{\tau} \mathrm{e}^{2 i s k_{1}^{2}} \mathrm{~d} s=\tau \varphi_{1}\left(2 i \tau k_{1}^{2}\right)
$$

yields that

$$
\begin{align*}
I_{1}^{\tau}\left(w, t_{n}\right)= & \tau \sum_{\ell \in \mathbb{Z}} \sum_{\substack{k_{1}, k_{2}, k_{3} \in \mathbb{Z} \\
\ell=-k_{1}+k_{2}+k_{3}}} \mathrm{e}^{i t_{n}\left[\ell^{2}+k_{1}^{2}-k_{2}^{2}-k_{3}^{2}\right]} \varphi_{1}\left(2 i \tau k_{1}^{2}\right) \overline{\hat{w}_{k_{1}}} \hat{w}_{k_{2}} \hat{w}_{k_{3}} \mathrm{e}^{i \ell x}  \tag{16}\\
& +\mathcal{R}_{1}^{\tau}\left(w, t_{n}\right) \\
= & \tau \mathrm{e}^{-i t_{n} \partial_{x}^{2}}\left[\left(\mathrm{e}^{i t_{n} \partial_{x}^{2}} w\right)^{2}\left(\varphi_{1}\left(-2 i \tau \partial_{x}^{2}\right) \mathrm{e}^{-i t_{n} \partial_{x}^{2}} \bar{w}\right)\right]+\mathcal{R}_{1}^{\tau}\left(w, t_{n}\right),
\end{align*}
$$

where

$$
\begin{aligned}
\left\|\mathcal{R}_{1}^{\tau}\left(w, t_{n}\right)\right\|_{r}^{2}= & \sum_{\ell \in \mathbb{Z}}(1+|\ell|)^{2 r}\left|\sum_{\substack{k_{1}, k_{2}, k_{3} \in \mathbb{Z} \\
\ell=-k_{1}+k_{2}+k_{3}}} \mathrm{e}^{i t_{n}\left[\ell^{2}+k_{1}^{2}-k_{2}^{2}-k_{3}^{2}\right]}\right| 2 k_{1}\left(k_{2}+k_{3}\right)-\left.2 k_{2} k_{3}\right|^{\gamma} \\
& \left.\overline{\hat{w}_{k_{1}}} \hat{w}_{k_{2}} \hat{w}_{k_{3}} \mathrm{e}^{i \ell x} \int_{0}^{\tau} \mathrm{e}^{2 i s k_{1}^{2}}\left(\frac{\mathrm{e}^{i s\left[-2 k_{1}\left(k_{2}+k_{3}\right)+2 k_{2} k_{3}\right]}-1}{s^{\gamma}\left|2 k_{1}\left(k_{2}+k_{3}\right)-2 k_{2} k_{3}\right|^{\gamma}}\right) s^{\gamma} \mathrm{d} s\right|^{2}
\end{aligned}
$$

Since $|\beta|^{-\gamma}\left(\mathrm{e}^{i \beta}-1\right)$ is uniformly bounded for $\beta \in \mathbb{R}$ and $0 \leq \gamma \leq 1$, the integral in the above formula is of the order $\tau^{1+\gamma}$. This shows that

$$
\begin{align*}
& \left\|\mathcal{R}_{1}^{\tau}\left(w, t_{n}\right)\right\|_{r}^{2} \leq c \tau^{2+2 \gamma} \sum_{\ell \in \mathbb{Z}}(1+|\ell|)^{2 r}\left(\sum_{\substack{k_{1}, k_{2}, k_{3} \in \mathbb{Z} \\
\ell=-k_{1}+k_{2}+k_{3}}}\left(\left|k_{1} k_{2}\right|+\left|k_{1} k_{3}\right|+\left|k_{2} k_{3}\right|\right)^{\gamma}\left|\hat{w}_{k_{1}}\right|\left|\hat{w}_{k_{2}}\right|\left|\hat{w}_{k_{3}}\right|\right)^{2} \\
& \quad \leq c \tau^{2+2 \gamma} \sum_{\ell \in \mathbb{Z}}(1+|\ell|)^{2 r}\left(\sum_{\substack{c_{1}, k_{2}, k_{2} \in \mathbb{Z} \\
\ell=-k_{1}+k_{2}+k_{3}}}\left(1+\left|k_{1}\right|\right)^{\gamma}\left(1+\left|k_{2}\right|\right)^{\gamma}\left(1+\left|k_{3}\right|\right)^{\gamma}\left|\hat{w}_{k_{1}}\right|\left|\hat{w}_{k_{2}}\right|\left|\hat{w}_{k_{3} \mid}\right|\right)^{2} \tag{17}
\end{align*}
$$

for some constant $c>0$ and $0 \leq \gamma \leq 1$.
Next we define the auxiliary function $g(x)=\sum_{k \in \mathbb{Z}} \hat{g}_{k} \mathrm{e}^{i k x}$ through its Fourier coefficients

$$
\begin{equation*}
\hat{g}_{k}=(1+|k|)^{\gamma}\left|\hat{w}_{k}\right| \tag{18}
\end{equation*}
$$

which allows us to express the bound on the remainder given in (17) as follows

$$
\left\|\mathcal{R}_{1}^{\tau}\left(w, t_{n}\right)\right\|_{r} \leq c \tau^{1+\gamma}\left\|g^{3}\right\|_{r} .
$$



With the aid of the bilinear estimate (5) we can thus conclude that for $r>1 / 2$

$$
\left\|\mathcal{R}_{1}^{\tau}\left(w, t_{n}\right)\right\|_{r} \leq c \tau^{1+\gamma}\|g\|_{r}^{3}=c \tau^{1+\gamma}\left(\sum_{k \in \mathbb{Z}}(1+|k|)^{2(r+\gamma)}\left|\hat{w}_{k}\right|^{2}\right)^{3 / 2}
$$

where we have used the definition of the Fourier coefficients in (18). Hence, we can conclude the following bound on the remainder

$$
\begin{equation*}
\left\|\mathcal{R}_{1}^{\tau}\left(w, t_{n}\right)\right\|_{r} \leq c \tau^{1+\gamma}\|w\|_{r+\gamma}^{3} \quad \text { for } \quad 0 \leq \gamma \leq 1, \quad r>1 / 2 \tag{19}
\end{equation*}
$$

for some constant $c>0$.
Next, we replace the integral in (11) with $v^{n}$ in place of $v\left(t_{n}\right)$ by the term (16) without remainder $\mathcal{R}_{1}^{\tau}$ and $w=v^{n}$. Twisting the solution back again, i.e., setting

$$
u^{n}:=\mathrm{e}^{i t_{n} \partial_{x}^{2}} v^{n}
$$

yields the following exponential-type integration scheme for the cubic NLS

$$
\begin{equation*}
u^{n+1}=\mathrm{e}^{i \tau \partial_{x}^{2}}\left[u^{n}-i \tau \mu\left(u^{n}\right)^{2}\left(\varphi_{1}\left(-2 i \tau \partial_{x}^{2}\right) \overline{u^{n}}\right)\right] . \tag{20}
\end{equation*}
$$

Next we generalize the above scheme to arbitrary dimensions $d \geq 1$.

### 2.1.2 Cubic Nonlinearities $p=1$ in Dimension $d \geq 1$

In the following we use the notation

$$
\mathbf{j}:=\left(j_{1}, \ldots, j_{d}\right) \in \mathbb{Z}^{d}, \quad \mathbf{j} \cdot \mathbf{x}:=j_{1} x_{1}+\cdots+j_{d} x_{d} .
$$

In the case of a cubic nonlinearity $p=1$ in dimension $d$, the integral in (11) can be expressed in terms of the Fourier expansion as follows

$$
\begin{aligned}
I_{1}^{\tau}\left(w, t_{n}\right) & =\int_{0}^{\tau} \mathrm{e}^{-i\left(t_{n}+s\right) \Delta}\left[\left(\mathrm{e}^{-i\left(t_{n}+s\right) \Delta} \bar{w}\right)\left(\mathrm{e}^{i\left(t_{n}+s\right) \Delta} w\right)^{2}\right] \mathrm{d} s \\
& =\sum_{\boldsymbol{\Omega} \in \mathbb{Z}^{d}} \sum_{\substack{\mathbf{j}, \mathbf{k}, \mathbf{,} \in \mathbb{Z}^{d} \\
\boldsymbol{\Omega}=-\mathbf{j}+\mathbf{k}+\mathbf{l}}} \int_{0}^{\tau} \mathrm{e}^{i\left(t_{n}+s\right)\left[\boldsymbol{\Omega}^{2}+\mathbf{j}^{2}-\mathbf{k}^{2}-\mathbf{l}^{2}\right] \mathrm{d} s \overline{\hat{w}}_{\mathbf{j}}} \hat{w}_{\mathbf{k}} \hat{w}_{\mathbf{l}} \mathrm{e}^{i \boldsymbol{\Omega} \cdot \mathbf{x}} .
\end{aligned}
$$

Note that we have

$$
\boldsymbol{\Omega}^{2}+\mathbf{j}^{2}-\mathbf{k}^{2}-\mathbf{l}^{2}=2 \mathbf{j}^{2}-2 \mathbf{j} \cdot(\mathbf{k}+\mathbf{l})+2 \mathbf{k} \cdot \mathbf{l} .
$$

In order to obtain an efficient and practical low regularity implementation, we again treat the dominant quadratic term $2 \mathbf{j}^{2}$ exactly.

This yields that

$$
\begin{align*}
I_{1}^{\tau}\left(w, t_{n}\right) & =\sum_{\boldsymbol{\Omega} \in \mathbb{Z}^{d}} \sum_{\substack{\mathbf{j}, \mathbf{k}, \mathbf{l} \in \mathbb{Z}^{d} \\
\boldsymbol{\Omega}=\mathbf{j}+\mathbf{k}+\mathbf{l}}} \mathrm{e}^{i t_{n}\left[\boldsymbol{\Omega}^{2}+\mathbf{j}^{2}-\mathbf{k}^{2}-\mathbf{l}^{2}\right]} \hat{w}_{\mathbf{j}} \hat{w}_{\mathbf{k}} \hat{w}_{\mathbf{w}} \mathrm{e}^{i \boldsymbol{\Omega} \cdot \mathbf{x}} \int_{0}^{\tau} \mathrm{e}^{2 i s \mathbf{j}^{2}} \mathrm{~d} s+\mathcal{R}_{1}^{\tau}\left(w, t_{n}\right) \\
& =\sum_{\boldsymbol{\Omega} \in \mathbb{Z}^{d}} \sum_{\substack{\mathbf{j}, \mathbf{k}, \mathbf{l} \in \mathbb{Z}^{d} \\
\boldsymbol{\Omega}=-\mathbf{j}+\mathbf{k}+\mathbf{l}}} \mathrm{e}^{i t_{n}\left[\boldsymbol{\Omega}^{2}+\mathbf{j}^{2}-\mathbf{k}^{2}-\mathbf{l}^{2}\right]} \hat{\hat{w}}_{\mathbf{j}} \hat{w}_{\mathbf{k}} \hat{w}_{1} \mathrm{e}^{i \boldsymbol{\Omega} \cdot \mathbf{x}} \varphi_{1}\left(2 i \tau \mathbf{j}^{2}\right)+\mathcal{R}_{1}^{\tau}\left(w, t_{n}\right), \tag{21}
\end{align*}
$$

where similarly to above [see (19)] we have that

$$
\left\|\mathcal{R}_{1}^{\tau}\left(w, t_{n}\right)\right\|_{r} \leq c \tau^{1+\gamma}\|w\|_{r+\gamma}^{3} \quad \text { for } \quad 0 \leq \gamma \leq 1, \quad r>d / 2
$$

for some constant $c>0$.
Inserting the approximation (21) into (11) and twisting the solution back again, i.e., setting

$$
u^{n}:=\mathrm{e}^{i t_{n} \Delta} v^{n}
$$

yields the generalization of the exponential-type integrator (20) to dimensions $d \geq 1$

$$
u^{n+1}=\mathrm{e}^{i \tau \Delta}\left[u^{n}-i \tau \mu\left(u^{n}\right)^{2}\left(\varphi_{1}(-2 i \tau \Delta) \overline{u^{n}}\right)\right] .
$$

Next we consider the general case of (6) with $p \in \mathbb{N}$.

### 2.2 Nonlinearities with Integer $p$

In the case of a general nonlinearity $p \in \mathbb{N}$ in (6), the integral in (11) can be expressed in terms of the Fourier expansion as follows

$$
I_{p}^{\tau}\left(w, t_{n}\right)=\int_{0}^{\tau} \mathrm{e}^{-i\left(t_{n}+s\right) \Delta}\left[\left|\mathrm{e}^{i\left(t_{n}+s\right) \Delta} w\right|^{2 p} \mathrm{e}^{i\left(t_{n}+s\right) \Delta} w\right] \mathrm{d} s
$$

Similar observations to above (see also [28]) yield the following numerical scheme

$$
\begin{equation*}
v^{n+1}=v^{n}-i \mu \tau \mathrm{e}^{-i t_{n} \Delta}\left[\left(\mathrm{e}^{i t_{n} \Delta} v^{n}\right)^{p+1}\left(\varphi_{1}(-2 i \tau \Delta)\left(\mathrm{e}^{-i t_{n} \Delta \overline{v^{n}}}\right)^{p}\right)\right] \tag{22}
\end{equation*}
$$

which satisfies

$$
\begin{equation*}
v^{n+1}=v^{n}-i \mu I_{p}^{\tau}\left(v^{n}, t_{n}\right)-i \mu \mathcal{R}_{p}^{\tau}\left(v^{n}, t_{n}\right), \tag{23}
\end{equation*}
$$

with

$$
\begin{equation*}
\left\|\mathcal{R}_{p}^{\tau}\left(v^{n}, t_{n}\right)\right\|_{r} \leq c \tau^{1+\gamma}\left\|v^{n}\right\|_{r+\gamma}^{2 p+1} \quad \text { for } \quad 0 \leq \gamma \leq 1, \quad r>d / 2 \tag{24}
\end{equation*}
$$

for some constant $c>0$.


In the original variable $u$, the exponential-type integration scheme for the nonlinear Schrödinger equation (6) reads

$$
\begin{equation*}
u^{n+1}=\mathrm{e}^{i \tau \Delta}\left[u^{n}-i \mu \tau\left(u^{n}\right)^{p+1}\left(\varphi_{1}(-2 i \tau \Delta)\left(\overline{u^{n}}\right)^{p}\right)\right] . \tag{25}
\end{equation*}
$$

In the following section, we give an error analysis for the above scheme.

## 3 Error Analysis

In this section, we carry out the error analysis of the exponential-type integrator (22). In the following, we set

$$
\Phi_{t}^{\tau}(w):=w-i \mu \tau \mathrm{e}^{-i t \Delta}\left[\left(\mathrm{e}^{i t \Delta} w\right)^{p+1}\left(\varphi_{1}(-2 i \tau \Delta)\left(\mathrm{e}^{-i t \Delta} \bar{w}\right)^{p}\right)\right]
$$

such that in particular $v^{k+1}=\Phi_{t_{k}}^{\tau}\left(v^{k}\right)$.
Lemma 3.1 (Stability) Let $r>d / 2$ and $f, g \in H^{r}$. Then, for all $t \in \mathbb{R}$ we have

$$
\left\|\Phi_{t}^{\tau}(f)-\Phi_{t}^{\tau}(g)\right\|_{r} \leq(1+\tau|\mu| L)\|f-g\|_{r},
$$

where $L$ depends on $\|f\|_{r}$ and $\|g\|_{r}$.
Proof Note that for all $t \in \mathbb{R}$ and $w \in H^{r}$ it holds by (12) that

$$
\left\|\varphi_{1}(2 i t \Delta) w\right\|_{r} \leq c\|w\|_{r}
$$

Thus, as $\mathrm{e}^{i t \Delta}$ is a linear isometry on $H^{r}$ and $H^{r}$ is an algebra for $r>d / 2$ we obtain that

$$
\begin{aligned}
&\left\|\Phi_{t}^{\tau}(f)-\Phi_{t}^{\tau}(g)\right\|_{r} \leq\|f-g\|_{r}+\tau|\mu| \|\left(\mathrm{e}^{i t \Delta} f\right)^{p+1}\left(\varphi_{1}(-2 i \tau \Delta)\left(\mathrm{e}^{-i t \Delta} \bar{f}\right)^{p}\right) \\
&-\left(\mathrm{e}^{i t \Delta} g\right)^{p+1}\left(\varphi_{1}(-2 i \tau \Delta)\left(\mathrm{e}^{-i t \Delta} \bar{g}\right)^{p}\right) \|_{r} \\
& \leq\|f-g\|_{r}+\tau c|\mu|\|f-g\|_{r} \sum_{l=0}^{2 p}\|f\|_{r}^{2 p-l}\|g\|_{r}^{l}
\end{aligned}
$$

This proves the assertion.
Lemma 3.2 (Local error) Let $r>d / 2$ and $0 \leq \gamma \leq 1$. Assume that $v\left(t_{k}+t\right)=$ $\phi^{t}\left(v\left(t_{k}\right)\right) \in H^{r+\gamma}$ for $0 \leq t \leq \tau$, where $\phi^{t}$ denotes the exact flow of (7). Then,

$$
\left\|\phi^{\tau}\left(v\left(t_{k}\right)\right)-\Phi_{t_{k}}^{\tau}\left(v\left(t_{k}\right)\right)\right\|_{r} \leq c \tau^{1+\gamma}
$$

where $c$ depends on $\sup _{0 \leq t \leq \tau}\left\|\phi^{t}\left(v\left(t_{k}\right)\right)\right\|_{r+\gamma}$.

Proof Note that by (23) we have that

$$
\begin{aligned}
\Phi_{t_{k}}^{\tau}\left(v\left(t_{k}\right)\right)= & v\left(t_{k}\right)-i \mu \int_{0}^{\tau} \mathrm{e}^{-i\left(t_{k}+s\right) \Delta}\left[\left|\mathrm{e}^{i\left(t_{k}+s\right) \Delta} v\left(t_{k}\right)\right|^{2 p} \mathrm{e}^{i\left(t_{k}+s\right) \Delta} v\left(t_{k}\right)\right] \mathrm{d} s \\
& +i \mu \mathcal{R}_{p}^{\tau}\left(v\left(t_{k}\right), t_{k}\right) .
\end{aligned}
$$

Furthermore, (8) implies that

$$
\phi^{\tau}\left(v\left(t_{k}\right)\right)=v\left(t_{k}\right)-i \mu \int_{0}^{\tau} \mathrm{e}^{-i\left(t_{k}+s\right) \Delta}\left[\left|\mathrm{e}^{i\left(t_{k}+s\right) \Delta} v\left(t_{k}+s\right)\right|^{2 p} \mathrm{e}^{i\left(t_{k}+s\right) \Delta} v\left(t_{k}+s\right)\right] \mathrm{d} s
$$

Thus as $\mathrm{e}^{i t \Delta}$ is a linear isometry on $H^{r}$ and $H^{r}$ is an algebra for $r>d / 2$ we obtain that

$$
\begin{aligned}
\left\|\phi^{\tau}\left(v\left(t_{k}\right)\right)-\Phi_{t_{k}}^{\tau}\left(v\left(t_{k}\right)\right)\right\|_{r} \leq & |\mu| \sup _{0 \leq s \leq \tau}\left\|v\left(t_{k}+s\right)\right\|_{r}^{2 p} \int_{0}^{\tau}\left\|v\left(t_{k}+s\right)-v\left(t_{k}\right)\right\|_{r} \mathrm{~d} s \\
& +|\mu|\left\|\mathcal{R}_{p}^{\tau}\left(v\left(t_{k}\right), t_{k}\right)\right\|_{r} .
\end{aligned}
$$

Together with the estimate on the difference $v\left(t_{k}+s\right)-v\left(t_{k}\right)$ given in (9) and the estimate on the remainder $\mathcal{R}_{p}^{\tau}(v, t)$ given in (24) this yields for $r>d / 2$ and $0 \leq \gamma \leq$ that

$$
\left\|\phi^{\tau}\left(v\left(t_{k}\right)\right)-\Phi_{t_{k}}^{\tau}\left(v\left(t_{k}\right)\right)\right\|_{r} \leq \tau^{2} c|\mu|^{2} \sup _{0 \leq s \leq \tau}\left\|v\left(t_{k}+s\right)\right\|_{r}^{4 p+1}+\tau^{1+\gamma} c|\mu|\left\|v\left(t_{k}\right)\right\|_{r+\gamma}^{2 p+1}
$$

which concludes the stated local error bound.
These two lemmata allow us to prove the following convergence bound.
Theorem 3.3 Let $r>d / 2$ and $0<\gamma \leq 1$. Assume that the exact solution of (7) satisfies $v(t) \in H^{r+\gamma}$ for $0 \leq t \leq T$. Then, there exists a constant $\tau_{0}>0$ such that for all step sizes $0<\tau \leq \tau_{0}$ and $t_{n}=n \tau \leq T$ we have that the global error of (22) is bounded by

$$
\left\|v\left(t_{n}\right)-v^{n}\right\|_{r} \leq c \tau^{\gamma}
$$

where $c$ depends on $\sup _{0 \leq t \leq T}\|v(t)\|_{r+\gamma}$.
Proof The triangle inequality yields that

$$
\begin{aligned}
\left\|v\left(t_{k+1}\right)-v^{k+1}\right\|_{r} & =\left\|\phi^{\tau}\left(v\left(t_{k}\right)\right)-\Phi_{t_{k}}^{\tau}\left(v^{k}\right)\right\|_{r} \\
& \leq\left\|\phi^{\tau}\left(v\left(t_{k}\right)\right)-\Phi_{t_{k}}^{\tau}\left(v\left(t_{k}\right)\right)\right\|_{r}+\left\|\Phi_{t_{k}}^{\tau}\left(v\left(t_{k}\right)\right)-\Phi_{t_{k}}^{\tau}\left(v^{k}\right)\right\|_{r}
\end{aligned}
$$

Thus, we obtain with the aid of Lemmata 3.2 and 3.1 that as long as $v^{k} \in H^{r}$ we have that

$$
\begin{equation*}
\left\|v\left(t_{k+1}\right)-v^{k+1}\right\|_{r} \leq c \tau^{1+\gamma}+(1+\tau|\mu| L)\left\|v\left(t_{k}\right)-v^{k}\right\|_{r}, \tag{26}
\end{equation*}
$$

where $c$ depends on $\sup _{t_{k} \leq t \leq t_{k+1}}\|v(t)\|_{r+\gamma}$ and $L$ depends on $\left\|v\left(t_{k}\right)\right\|_{r}$ as well as on $\left\|v^{k}\right\|_{r}$ ．As long as $v\left(t_{k}\right) \in H^{r+\gamma}$ and $v^{k} \in H^{r}$ for $0 \leq k \leq n$ we therefore obtain by iterating the estimate（26）that

$$
\begin{aligned}
\left\|v\left(t_{n+1}\right)-v^{n+1}\right\|_{r} & \leq c \tau^{1+\gamma}+(1+\tau|\mu| L)\left\|v\left(t_{n}\right)-v^{n}\right\|_{r} \\
& \leq c \tau^{1+\gamma}+\mathrm{e}^{\tau|\mu| L}\left(c \tau^{1+\gamma}+(1+\tau|\mu| L)\left\|v\left(t_{n-1}\right)-v^{n-1}\right\|_{r}\right) \\
& \leq c n \tau^{1+\gamma} \mathrm{e}^{n \tau|\mu| L} \leq c t_{n} \tau^{\gamma} \mathrm{e}^{t_{n}|\mu| L}
\end{aligned}
$$

The assertion then follows by induction，respectively，a Lady Windermere＇s fan argu－ ment（see，for example［11，15，25］）．

The above theorem immediately yields a convergence result for the exponential－ type integration scheme（22）approximating the solution of the nonlinear Schrödinger equation（6）．

Corollary 3．4 Let $r>d / 2$ and $0<\gamma \leq 1$ ．Assume that the exact solution of（6） satisfies $u(t) \in H^{r+\gamma}$ for $0 \leq t \leq T$ ．Then，there exists a constant $\tau_{0}>0$ such that for all step sizes $0<\tau \leq \tau_{0}$ and $t_{n}=n \tau \leq T$ we have that the global error of（25） is bounded by

$$
\left\|u\left(t_{n}\right)-u^{n}\right\|_{r} \leq c \tau^{\gamma},
$$

where $c$ depends on $\sup _{0 \leq t \leq T}\|u(t)\|_{r+\gamma}$ ．
Proof As $\mathrm{e}^{i t \Delta}$ is a linear isometry on $H^{r}$ for all $t \in \mathbb{R}$ we have that

$$
\left\|u\left(t_{n}\right)-u^{n}\right\|_{r}=\left\|\mathrm{e}^{i t_{n} \Delta}\left(v\left(t_{n}\right)-v^{n}\right)\right\|_{r}=\left\|v\left(t_{n}\right)-v^{n}\right\|_{r} .
$$

Thus，the assertion follows from Theorem 3．3．

## 4 Quadratic Schrödinger Equations in One Space Dimension

In this section，we focus on quadratic nonlinear Schrödinger equations of type（see， e．g．，［1］）

$$
\begin{equation*}
i \partial_{t} u=-\partial_{x}^{2} u+\mu u^{2}, \quad u(0, x)=u^{0}(x), \quad(t, x) \in \mathbb{R} \times \mathbb{T}, \quad \mu \in \mathbb{R} \tag{27}
\end{equation*}
$$

as well as of type（see，e．g，［21］）

$$
\begin{equation*}
i \partial_{t} u=-\partial_{x}^{2} u+\mu|u|^{2}, \quad u(0, x)=u^{0}(x), \quad(t, x) \in \mathbb{R} \times \mathbb{T}, \quad \mu \in \mathbb{R} \tag{28}
\end{equation*}
$$

which have recently gained a lot of attention in the literature，see for instance $[1,3,5$ ， $13,21-23,27,29,32]$ and the references therein．

Here，the key relations

$$
\begin{equation*}
\left(k_{1}+k_{2}\right)^{2}-k_{1}^{2}-k_{2}^{2}=2 k_{1} k_{2} \tag{29}
\end{equation*}
$$

and

$$
\begin{equation*}
\left(k_{1}-k_{2}\right)^{2}-k_{1}^{2}+k_{2}^{2}=-2 k_{2}\left(k_{1}-k_{2}\right) \tag{30}
\end{equation*}
$$

allow us to derive first-order exponential-type integrators for Schrödinger equations of type (27) and (28) without imposing any additional regularity assumptions on the solution.

### 4.1 Quadratic Schrödinger Equations of Type (27)

Set $v(t)=\mathrm{e}^{-i t \partial_{x}^{2}} u(t)$, where $u$ is the solution of the Schrödinger equation (27). Then the twisted variable $v(t)$ satisfies

$$
\begin{equation*}
i \partial_{t} v=\mu \mathrm{e}^{-i t \partial_{x}^{2}}\left(\mathrm{e}^{i t \partial_{x}^{2}} v(t)\right)^{2} \tag{31}
\end{equation*}
$$

which by Duhamel's formula yields that

$$
\begin{equation*}
v\left(t_{n}+\tau\right)=v\left(t_{n}\right)-i \mu \int_{0}^{\tau} \mathrm{e}^{-i\left(t_{n}+s\right) \partial_{x}^{2}}\left(\mathrm{e}^{i\left(t_{n}+s\right) \partial_{x}^{2}} v\left(t_{n}+s\right)\right)^{2} \mathrm{~d} s \tag{32}
\end{equation*}
$$

To construct our numerical scheme, we proceed as above. We start from the following approximation

$$
\begin{equation*}
v\left(t_{n}+\tau\right) \approx v\left(t_{n}\right)-i \mu \int_{0}^{\tau} \mathrm{e}^{-i\left(t_{n}+s\right) \partial_{x}^{2}}\left(\mathrm{e}^{i\left(t_{n}+s\right) \partial_{x}^{2}} v\left(t_{n}\right)\right)^{2} \mathrm{~d} s=: \Phi_{t_{n}}^{\tau}\left(v\left(t_{n}\right)\right) \tag{33}
\end{equation*}
$$

and rewrite the above integral in Fourier space as follows

$$
\begin{aligned}
I^{\tau}\left(w, t_{n}\right) & =\int_{0}^{\tau} \mathrm{e}^{-i\left(t_{n}+s\right) \partial_{x}^{2}}\left(\mathrm{e}^{i\left(t_{n}+s\right) \partial_{x}^{2}} w\right)^{2} \mathrm{~d} s \\
& =\int_{0}^{\tau} \mathrm{e}^{-i\left(t_{n}+s\right) \partial_{x}^{2}}\left[\left(\mathrm{e}^{i\left(t_{n}+s\right) \partial_{x}^{2}} \sum_{k_{1}} \hat{w}_{k_{1}} \mathrm{e}^{i k_{1} x}\right)\left(\mathrm{e}^{i\left(t_{n}+s\right) \partial_{x}^{2}} \sum_{k_{2}} \hat{w}_{k_{2}} \mathrm{e}^{i k_{2} x}\right)\right] \mathrm{d} s \\
& \left.=\int_{0}^{\tau} \sum_{k_{1}, k_{2}} \mathrm{e}^{i\left(t_{n}+s\right)\left[\left(k_{1}+k_{2}\right)^{2}-k_{1}^{2}-k_{2}^{2}\right.}\right]_{\hat{w}_{k_{1}}} \hat{w}_{k_{2}} \mathrm{e}^{i\left(k_{1}+k_{2}\right) x} \mathrm{~d} s .
\end{aligned}
$$

The key relation (29) now shows that

$$
\begin{aligned}
I^{\tau}\left(w, t_{n}\right)= & \sum_{\substack{k_{1}, k_{2} \\
k_{1}, k_{2} \neq 0}} \mathrm{e}^{i t_{n}\left[\left(k_{1}+k_{2}\right)^{2}-k_{1}^{2}-k_{2}^{2}\right]} \frac{\mathrm{e}^{i \tau\left[\left(k_{1}+k_{2}\right)^{2}-k_{1}^{2}-k_{2}^{2}\right]}-1}{2 i k_{1} k_{2}} \hat{w}_{k_{1}} \hat{w}_{k_{2}} \mathrm{e}^{i\left(k_{1}+k_{2}\right) x} \\
& +2 \tau \hat{w}_{0} \sum_{k_{1} \neq 0} \hat{w}_{k_{1}} \mathrm{e}^{i k_{1} x}+\tau \hat{w}_{0}^{2}
\end{aligned}
$$

$$
\begin{aligned}
= & \frac{i}{2} \sum_{\substack{k_{1}, k_{2} \\
k_{1}, k_{2} \neq 0}} \mathrm{e}^{i t_{n}\left[\left(k_{1}+k_{2}\right)^{2}-k_{1}^{2}-k_{2}^{2}\right]} \frac{\mathrm{e}^{i \tau\left[\left(k_{1}+k_{2}\right)^{2}-k_{1}^{2}-k_{2}^{2}\right]}-1}{\left(i k_{1}\right)\left(i k_{2}\right)} \hat{w}_{k_{1}} \hat{w}_{k_{2}} \mathrm{e}^{i\left(k_{1}+k_{2}\right) x} \\
& +2 \tau \hat{w}_{0} \sum_{k_{1} \in \mathbb{Z}} \hat{w}_{k_{1}} \mathrm{e}^{i k_{1} x}-\tau \hat{w}_{0}^{2} \\
= & \frac{i}{2} \mathrm{e}^{-i t_{n} \partial_{x}^{2}}\left[\mathrm{e}^{-i \tau \partial_{x}^{2}}\left(\mathrm{e}^{i\left(t_{n}+\tau\right) \partial_{x}^{2}} \partial_{x}^{-1} w\right)^{2}-\left(\mathrm{e}^{i t_{n} \partial_{x}^{2}} \partial_{x}^{-1} w\right)^{2}\right] \\
& +2 \tau \hat{w}_{0} w-\tau \hat{w}_{0}^{2} .
\end{aligned}
$$

Together with the approximation in (33) this yields the following integration scheme:

$$
\begin{align*}
v^{n+1}= & \Phi_{t_{n}}^{\tau}\left(v^{n}\right) \\
= & \left(1-2 i \mu \tau \hat{v}_{0}^{n}\right) v^{n}+i \mu \tau\left(\hat{v}_{0}^{n}\right)^{2}  \tag{34}\\
& +\frac{\mu}{2} \mathrm{e}^{-i t_{n} \partial_{x}^{2}}\left[\mathrm{e}^{-i \tau \partial_{x}^{2}}\left(\mathrm{e}^{i\left(t_{n}+\tau\right) \partial_{x}^{2}} \partial_{x}^{-1} v^{n}\right)^{2}-\left(\mathrm{e}^{i t_{n} \partial_{x}^{2}} \partial_{x}^{-1} v^{n}\right)^{2}\right] .
\end{align*}
$$

In order to obtain an approximation to the original solution $u(t)$ of the quadratic Schrödinger equation (27) at time $t_{n}=n \tau$, we twist the variable back again, i.e., we set $u^{n}:=\mathrm{e}^{i t_{n} \partial_{x}^{2}} v^{n}$. This yields the following exponential-type integrator

$$
\begin{equation*}
u^{n+1}=\left(1-2 i \mu \tau \hat{u}_{0}^{n}\right) \mathrm{e}^{i \tau \partial_{x}^{2}} u^{n}+i \mu \tau\left(\hat{u}_{0}^{n}\right)^{2}+\frac{\mu}{2}\left(\mathrm{e}^{i \tau \partial_{x}^{2}} \partial_{x}^{-1} u^{n}\right)^{2}-\frac{\mu}{2} \mathrm{e}^{i \tau \partial_{x}^{2}}\left(\partial_{x}^{-1} u^{n}\right)^{2} . \tag{35}
\end{equation*}
$$

### 4.2 Quadratic Schrödinger Equations of Type (28)

For the quadratic Schrödinger equation (28), the equation in the twisted variable $v(t)=$ $\mathrm{e}^{-i t \partial_{x}^{2}} u(t)$ reads

$$
i \partial_{t} v=\mu \mathrm{e}^{-i t \partial_{x}^{2}}\left|\mathrm{e}^{i t \partial_{x}^{2}} v(t)\right|^{2}
$$

To construct our numerical scheme, we proceed as above. We start from the following approximation

$$
\begin{equation*}
v\left(t_{n}+\tau\right) \approx v\left(t_{n}\right)-i \mu \int_{0}^{\tau} \mathrm{e}^{-i\left(t_{n}+s\right) \partial_{x}^{2}}\left|\mathrm{e}^{i\left(t_{n}+s\right) \partial_{x}^{2}} v\left(t_{n}\right)\right|^{2} \mathrm{~d} s \tag{36}
\end{equation*}
$$

and rewrite the above integral in Fourier space as follows

$$
\begin{aligned}
I^{\tau}\left(w, t_{n}\right) & =\int_{0}^{\tau} \mathrm{e}^{-i\left(t_{n}+s\right) \partial_{x}^{2}}\left|\mathrm{e}^{i\left(t_{n}+s\right) \partial_{x}^{2}} w\right|^{2} \mathrm{~d} s \\
& =\int_{0}^{\tau} \sum_{k_{1}, k_{2}} \mathrm{e}^{i\left(t_{n}+s\right)\left[\left(k_{1}-k_{2}\right)^{2}-k_{1}^{2}+k_{2}^{2}\right]} \hat{w}_{k_{1}} \overline{\hat{w}}_{k_{2}} \mathrm{e}^{i\left(k_{1}-k_{2}\right) x} \mathrm{~d} s .
\end{aligned}
$$

The key relation (30) now shows that

$$
\begin{aligned}
& I^{\tau}\left(w, t_{n}\right)= \sum_{\substack{k_{1}, k_{2} \\
k_{1} \neq k_{2}, k_{2} \neq 0}} \mathrm{e}^{i t_{n}\left[\left(k_{1}-k_{2}\right)^{2}-k_{1}^{2}+k_{2}^{2}\right]} \frac{\mathrm{e}^{i \tau\left[\left(k_{1}-k_{2}\right)^{2}-k_{1}^{2}+k_{2}^{2}\right]}-1}{-2 i k_{2}\left(k_{1}-k_{2}\right)} \hat{w}_{k_{1}} \overline{\hat{w}}_{k_{2}} \mathrm{e}^{i\left(k_{1}-k_{2}\right) x} \\
& \quad+\tau \overline{\hat{w}}_{0} \sum_{k_{1}} \hat{w}_{k_{1}} \mathrm{e}^{i k_{1} x}+\tau\|w\|_{L^{2}}^{2} \\
&= \frac{i}{2} \partial_{x}^{-1} \mathrm{e}^{-i\left(t_{n}+\tau\right) \partial_{x}^{2}}\left[\left(\mathrm{e}^{i\left(t_{n}+\tau\right) \partial_{x}^{2}} w\right)\left(\mathrm{e}^{-i\left(t_{n}+\tau\right) \partial_{x}^{2}} \partial_{x}^{-1} \bar{w}\right)\right] \\
& \quad-\frac{i}{2} \partial_{x}^{-1} \mathrm{e}^{-i t_{n} \partial_{x}^{2}}\left[\left(\mathrm{e}^{i t_{n} \partial_{x}^{2}} w\right)\left(\mathrm{e}^{-i t_{n} \partial_{x}^{2}} \partial_{x}^{-1} \bar{w}\right)\right]+\tau \overline{\hat{w}}_{0} w+\tau\|w\|_{L^{2}}^{2} .
\end{aligned}
$$

Together with the approximation in (36) this yields (by twisting the variable back again) the following integration scheme in the original solution $u(t)=\mathrm{e}^{i t_{n} \partial_{x}^{2}} v(t)$

$$
\begin{align*}
u^{n+1}= & \left(1-i \mu \tau \overline{\hat{u}}_{0}^{n}\right) \mathrm{e}^{i \tau \partial_{x}^{2}} u^{n}-i \mu \tau\left\|u^{n}\right\|_{L^{2}}^{2} \\
& +\frac{\mu}{2} \partial_{x}^{-1}\left[\left(\mathrm{e}^{i \tau \partial_{x}^{2}} u^{n}\right)\left(\mathrm{e}^{-i \tau \partial_{x}^{2}} \partial_{x}^{-1} \bar{u}^{n}\right)-\mathrm{e}^{i \tau \partial_{x}^{2}}\left(u^{n} \partial_{x}^{-1} \bar{u}^{n}\right)\right] \tag{37}
\end{align*}
$$

### 4.3 Error Analysis

In this section, we carry out the error analysis of the exponential-type integrators (35) and (37). In the following let $r>1 / 2$.

We commence with the quadratic Schrödinger equation of type (27). Let $\phi^{t}$ denote the exact flow of (31), i.e., $v(t)=\phi^{t}(v(0))$. The following lemma provides a local error bound of the scheme (34).
Lemma 4.1 Let $r>1 / 2$ and assume that $v\left(t_{k}+t\right)=\phi^{t}\left(v\left(t_{k}\right)\right) \in H^{r}$ for $0 \leq t \leq \tau$, where $\phi^{t}$ denotes the exact flow of (27). Then

$$
\left\|\phi^{\tau}\left(v\left(t_{k}\right)\right)-\Phi_{t_{k}}^{\tau}\left(v\left(t_{k}\right)\right)\right\|_{r} \leq c \tau^{2}
$$

where $c$ depends on $\sup _{0 \leq t \leq \tau}\left\|\phi^{t}\left(v\left(t_{k}\right)\right)\right\|_{r}$.
Proof As $\mathrm{e}^{i t \partial_{x}^{2}}$ is a linear isometry on $H^{r}$ for all $t \in \mathbb{R}$ we obtain by taking the difference of (32) with the approximation (33) and using the bilinear estimate (5) that

$$
\begin{aligned}
& \left\|\phi^{\tau}\left(v\left(t_{k}\right)\right)-\Phi_{t_{k}}^{\tau}\left(v\left(t_{k}\right)\right)\right\|_{r} \leq|\mu| \int_{0}^{\tau}\left\|\left(\mathrm{e}^{i\left(t_{k}+s\right) \partial_{x}^{2}} v\left(t_{k}+s\right)\right)^{2}-\left(\mathrm{e}^{i\left(t_{k}+s\right) \partial_{x}^{2}} v\left(t_{k}\right)\right)^{2}\right\|_{r} \mathrm{~d} s \\
& \quad \leq c|\mu| \tau \sup _{0 \leq s \leq \tau}\left(\left\|\mathrm{e}^{i\left(t_{k}+s\right) \partial_{x}^{2}}\left(v\left(t_{k}+s\right)-v\left(t_{k}\right)\right)\right\|_{r}\left\|\mathrm{e}^{i\left(t_{k}+s\right) \partial_{x}^{2}}\left(v\left(t_{k}+s\right)+v\left(t_{k}\right)\right)\right\|_{r}\right) \\
& \quad \leq c|\mu| \tau \sup _{0 \leq s \leq \tau}\left\|v\left(t_{k}+s\right)-v\left(t_{k}\right)\right\|_{r} \\
& \quad \leq c|\mu|^{2} \tau \sup _{0 \leq s \leq \tau} \int_{0}^{s}\left\|\left(\mathrm{e}^{i\left(t_{k}+\xi\right) \partial_{x}^{2}} v\left(t_{k}+\xi\right)\right)^{2}\right\|_{r} \mathrm{~d} \xi,
\end{aligned}
$$

where $c$ depends on $\sup _{0 \leq s \leq \tau}\left\|\phi^{s}\left(v\left(t_{k}\right)\right)\right\|_{r}$. This yields the assertion.

Next we state the stability estimate.
Lemma 4.2 Let $r>1 / 2$ and $f, g \in H^{r}$. Then, for all $t \in \mathbb{R}$ we have

$$
\left\|\Phi_{t}^{\tau}(f)-\Phi_{t}^{\tau}(g)\right\|_{r} \leq(1+\tau|\mu| L)\|f-g\|_{r},
$$

where $L$ depends on $\|f+g\|_{r}$.
Proof The assertion follows from the representation of the numerical flow given in (33) together with the bilinear estimate (5).

The above lemmata allow us to prove the following global convergence result.
Theorem 4.3 Let $r>1 / 2$. Assume that the exact solution of (31) satisfies $v(t) \in H^{r}$ for $0 \leq t \leq T$. Then, there exists a constant $\tau_{0}>0$ such that for all step sizes $0<\tau \leq \tau_{0}$ and $t_{n}=n \tau \leq T$ we have that the global error of (34) is bounded by

$$
\left\|v\left(t_{n}\right)-v^{n}\right\|_{r} \leq c \tau
$$

where c depends on $\sup _{0 \leq t \leq T}\|v(t)\|_{r}$.
Proof The proof follows the line of argumentation to the proof of Theorem 3.3 thanks to the local error bound in Lemma 4.1 and the stability estimate of Lemma 4.2.

The above theorem immediately yields first-order convergence of the exponentialtype integrator (35) (in $H^{r}$ ) without any additional smoothness assumptions on the exact solution of (27).

Corollary 4.4 Letr $>1 / 2$. Assume that the exact solution of (27) satisfies $v(t) \in H^{r}$ for $0 \leq t \leq T$. Then, there exists a constant $\tau_{0}>0$ such that for all step sizes $0<\tau \leq \tau_{0}$ and $t_{n}=n \tau \leq T$ we have that the global error of (35) is bounded by

$$
\left\|u\left(t_{n}\right)-u^{n}\right\|_{r} \leq c \tau,
$$

where $c$ depends on $\sup _{0 \leq t \leq T}\|u(t)\|_{r}$.
Proof The bound follows directly from Theorem 4.3 as $\mathrm{e}^{i t \partial_{x}^{2}}$ is a linear isometry on $H^{r}$ for all $t \in \mathbb{R}$.

Similarly to above we obtain the following first-order convergence result for the exponential-type integrator (37) approximating the solution of the quadratic Schrödinger equation (28).
Corollary 4.5 Letr $>1 / 2$. Assume that the exact solution of (28) satisfies $v(t) \in H^{r}$ for $0 \leq t \leq T$. Then, there exists a constant $\tau_{0}>0$ such that for all step sizes $0<\tau \leq \tau_{0}$ and $t_{n}=n \tau \leq T$ we have that the global error of (37) is bounded by

$$
\left\|u\left(t_{n}\right)-u^{n}\right\|_{r} \leq c \tau,
$$

where $c$ depends on $\sup _{0 \leq t \leq T}\|u(t)\|_{r}$.
Proof The proof is similar to that of Corollary 4.4 and will therefore be omitted here.

## 5 Numerical Experiments

In this section, we compare the newly developed exponential-type integrator (25) applied to Schrödinger equations with low regularity solutions in the energy space with the classical Lie splitting, the classical Strang splitting and the classical firstorder exponential integrator. In the numerical experiments, we use a standard Fourier pseudospectral method for the space discretization where we choose the largest Fourier mode $K=2^{10}$ (i.e., the spatial mesh size $\Delta x=0.0061$ ). The numerical experiments show that the new integrator (25) is preferable over the classical splitting and exponential integration methods for low regularity solutions. In particular, the experiments indicate that the proposed integrator (25) is convergent of order one even for rough solutions whereas the classical methods suffer from order reduction.

Although the new integrator (25) was derived for nonlinearities with integer $p \geq 1$, it can be applied to problem (6) with non-integer $p$ as well. Preliminary numerical results for small non-integer values of $p$ are presented in Sect. 5.3.

### 5.1 Numerical Experiments for Schrödinger Equations of Type (6)

In this section, we consider nonlinear Schrödinger equations of type (6). The associated Lie splitting (of classical order one) reads

$$
\begin{align*}
u_{L}^{n+1 / 2} & =\mathrm{e}^{i \tau \Delta} u_{L}^{n} \\
u_{L}^{n+1} & =\mathrm{e}^{-i \tau \mu\left|u_{L}^{n+1 / 2}\right|^{2 p}} u_{L}^{n+1 / 2}, \tag{38}
\end{align*}
$$

and the associated Strang splitting (of classical order two) is given by

$$
\begin{align*}
u_{-}^{n+1 / 2} & =\mathrm{e}^{i \frac{\tau}{2} \Delta} u_{S}^{n} \\
u_{+}^{n+1 / 2} & =\left.\left.\mathrm{e}^{-i \tau \mu}\right|_{-} ^{n+1 / 2}\right|^{2 p} u_{-}^{n+1 / 2},  \tag{39}\\
u_{S}^{n+1} & =\mathrm{e}^{i \frac{\tau}{2} \Delta} u_{+}^{n+1 / 2}
\end{align*}
$$

Furthermore, the classical first-order exponential integrator (of classical order one) is defined through

$$
\begin{equation*}
u_{E}^{n+1}=\mathrm{e}^{i \tau \Delta} u_{E}^{n}-i \mu \tau \varphi_{1}(i \tau \Delta)\left(\left|u_{E}^{n}\right|^{2 p} u_{E}^{n}\right) . \tag{40}
\end{equation*}
$$

In our numerical experiments, we choose $\mu=1$ (unless otherwise noted) and set

$$
\begin{equation*}
\mathcal{U}^{K}:=\left[u\left(0, x_{1}\right), u\left(0, x_{2}\right), \ldots, u\left(0, x_{2 K}\right)\right]=\operatorname{rand}(2 K, 1)+i \operatorname{rand}(2 K, 1) \in \mathbb{C}^{2 K}, \tag{41}
\end{equation*}
$$

where $x_{j}=\left(-1+\frac{j}{K}\right) \pi$ and $\operatorname{rand}(2 K, 1)$ return $2 K$ uniformly distributed random numbers between 0 and 1 . We compare the above schemes with the newly derived exponential-type integrator (25) for initial values



Fig. 1 Initial values (42) normalized in $L^{2}$ for two different values of $\vartheta$. Left $\vartheta=\frac{3}{2}$. Right $\vartheta=5$


Fig. 2 (cubic NLS) Error in the energy space $H^{1}$ of the Lie splitting (38) (blue, dotted), Strang splitting (39) (magenta, solid line), classical exponential integrator (40) (green, dashed) and exponential-type integration scheme (25) (red, squares). Left picture $H^{3 / 2}$ solutions. Right picture $H^{2}$ solutions. The slope of the continuous lines is one half and one, respectively (Color figure online)

$$
u_{\vartheta}^{K}=\left|\partial_{x, K}\right|^{-\vartheta} \mathcal{U}^{K}, \quad\left(\left|\partial_{x, K}\right|^{-\vartheta}\right)_{k}:= \begin{cases}|k|^{-\vartheta} & \text { if } k \neq 0,  \tag{42}\\ 0 & \text { if } k=0\end{cases}
$$

for different values of $\vartheta$ normalized in $L^{2}$. (For typical initial values, see Fig. 1.) All experiments are carried out with constant step sizes $\tau=\frac{j}{512}$ for $j=1, \ldots, 512$.

### 5.1.1 Cubic Schrödinger Equations

In this section, we consider the classical cubic Schrödinger equation, i.e., $p=1$ in (6). The error at time $T=1$ measured in a discrete $H^{1}$ norm of the exponential-type integrator (25), the Lie splitting scheme (38), the Strang splitting scheme (39) as well as the classical exponential integrator (40) for the initial value (42) normalized in $L^{2}$ is illustrated in Fig. 2 for $\vartheta=3 / 2$, respectively, $\vartheta=2$ and in Fig. 3 for $\vartheta=3$, respectively, $\vartheta=5$. As a reference solution, we take the schemes themselves with a very small time step size if $\vartheta \neq 5$. For $\vartheta=5$ we take the Strang splitting scheme (39) with a very small time step size as the reference solution for all schemes. The experiments show that Strang splitting is second-order convergent for $\vartheta \geq 5$, and


Fig. 3 (cubic NLS) Error in the energy space $H^{1}$ of the Lie splitting (38) (blue, dotted), Strang splitting (39) (magenta, solid line), classical exponential integrator (40) (green, dashed) and exponential-type integration scheme (25) (red, squares). Left picture $H^{3}$ solutions. Right picture $H^{5}$ solutions. The slope of the continuous lines is one and two, respectively (Color figure online)
that Lie splitting is first-order convergent for $\vartheta \geq 3$. These observations are in line with the convergence proofs from the literature [10,25], see also our discussion in the introduction. For smaller values of $\vartheta$, both Lie and Strang splitting show a zigzag behavior, depending on whether the local errors accumulate or happy error cancelation occurs. The classical exponential integrator of order one is first-order convergent for $\vartheta \geq 3$ as expected (see the discussion in the introduction). For smaller values of $\vartheta$, the convergence behavior of the exponential integrator gets less regular and order reduction occurs. On the other hand, the new exponential-type integrator introduced in this paper is first-order convergent for all $\vartheta \geq 2$. This behavior is in line with Theorem 3.3. The integrator even shows first-order convergence and small errors for $\vartheta=\frac{3}{2}$.

### 5.1.2 Quintic Schrödinger Equations

In this section, we consider the quintic Schrödinger equation, i.e., $p=2$ in (6), which appears for instance as the mean field limit of a Boson gas with three-body interactions, see [7]. The error at time $T=1$ measured in a discrete $H^{1}$ norm of the exponentialtype integrator (25), the Lie splitting scheme (38), the Strang splitting scheme (39) as well as the classical exponential integrator (40) for the initial value (42) normalized in $L^{2}$ is illustrated in Fig. 4 for $\vartheta=3 / 2$, respectively, $\vartheta=2$ and in Fig. 5 for $\vartheta=3$, respectively, $\vartheta=5$. As a reference solution we take the schemes themselves with a very small time step size if $\vartheta \neq 5$. For $\vartheta=5$ we take the Strang splitting scheme (39) with a very small time step size as the reference solution for all schemes. The outcome of these numerical experiments is almost the same as for the cubic nonlinear Schrödinger equation. The only notable difference is the exponential-type integrator for $\vartheta=\frac{3}{2}$, where the convergence behavior is now less regular. Note, however, that the errors are still much smaller compared to the other methods.


Fig. 4 (quintic NLS) Error in the energy space $H^{1}$ of the Lie splitting (38) (blue, dotted), Strang splitting (39) (magenta, solid line), classical exponential integrator (40) (green, dashed) and exponential-type integration scheme (25) (red, squares). Left picture $H^{3 / 2}$ solutions. Right picture $H^{2}$ solutions. Left picture The slope of the continuous lines is one quarter and one, respectively. Right picture The slope of the continuous lines is one half and one, respectively (Color figure online)


Fig. 5 (quintic NLS) in the energy space $H^{1}$ of the Lie splitting (38) (blue, dotted), Strang splitting (39) (magenta, solid line), classical exponential integrator (40) (green, dashed) and exponential-type integration scheme (25) (red, squares). Left picture $H^{3}$ solutions. Right picture $H^{5}$ solutions. The slope of the continuous lines is one and two, respectively (Color figure online)

### 5.2 Numerical Experiments for Quadratic Schrödinger Equations

In this section, we consider quadratic Schrödinger equations of type (27). In order to derive the splitting methods, we split the right-hand side of (27) into the linear and nonlinear part, respectively. Note that (for sufficiently small $t$ ) the exact solution of the subproblem

$$
i u^{\prime}(t)=\mu u(t)^{2}
$$

is given by

$$
u(t)=\frac{u(0)}{1+i \mu t u(0)} .
$$

Thus, the associated Lie splitting scheme (of classical order one) reads

$$
\begin{equation*}
u_{L}^{n+1}=\mathrm{e}^{i \tau \partial_{x}^{2}}\left(\frac{u_{L}^{n}}{1+i \mu \tau u_{L}^{n}}\right) \tag{43}
\end{equation*}
$$

and the associated Strang splitting scheme (of classical order two) is given by

$$
\begin{align*}
u_{S}^{n+1 / 2} & =\mathrm{e}^{i \frac{\tau}{2} \partial_{x}^{2}} u_{S}^{n} \\
u_{S}^{n+1} & =\mathrm{e}^{i \frac{\tau}{2} \partial_{x}^{2}}\left(\frac{u_{S}^{n+1 / 2}}{1+i \mu \tau u_{S}^{n+1 / 2}}\right) . \tag{44}
\end{align*}
$$

In Examples 5.1 and 5.2, we compare the above splitting methods as well as the classical first-order exponential integration scheme

$$
\begin{equation*}
u_{E}^{n+1}=\mathrm{e}^{i \tau \partial_{x}^{2}} u_{E}^{n}-i \mu \tau \varphi_{1}\left(i \tau \partial_{x}^{2}\right)\left(u_{E}^{n}\right)^{2} \tag{45}
\end{equation*}
$$

with the newly derived exponential-type integrator (35) for smooth and non-smooth solutions, respectively, where we set $\mu=1$ and integrate up to $T=1$. The numerical experiments in particular indicate that the exponential-type integrator (35) is preferable over the commonly used splitting methods for low regularity solutions. This is due to the fact that within this exponential integration scheme all the stiff parts (i.e., the terms involving the differential operator $\partial_{x}^{2}$ ) are solved exactly.

In Example 5.3 we consider a quadratic Schrödinger equation of type (27) with a small nonlinearity on a longer time interval $T=10$. The numerical experiment indicates the favorable behavior of the exponential integrator (35) even in the smooth case. This is due to the fact that its error constant is triggered by the nonlinearity (and not by the differential operator $\partial_{x}^{2}$ ).

Example 5.1 (Smooth solutions) We choose the smooth initial value

$$
\begin{equation*}
u(0, x)=\sin x \cos x \in \mathcal{C}^{\infty}(\mathbb{T}) \tag{46}
\end{equation*}
$$

normalized in $L^{2}$. The error at time $T=1$ measured in a discrete $L^{2}$ norm of the exponential-type integrator (35), the Lie splitting scheme (43), the Strang splitting scheme (44) and the classical exponential integrator (45) is illustrated in Fig. 6. As a reference solution, we take the Strang splitting scheme (44) with a very small time step size. All the methods show their classical orders of convergence, as expected.

Example 5.2 (Non-smooth solutions) We choose the non-smooth initial value (41) normalized in $L^{2}$. The error at time $T=1$ measured in a discrete $L^{2}$ norm of the exponential-type integrator (35), the Lie splitting scheme (43), the Strang splitting scheme (44) and the classical exponential integrator (45) is illustrated in Fig. 7. As a reference solution, we take the schemes themselves with a very small time step size. For this example, the classical exponential integrator is not convergent. Lie and Strang splitting suffer from a strong order reduction (down to order one half). Here, the new

Fig. 6 (quadratic NLS) Error of the Lie splitting (43) (blue, dotted), Strang splitting (44) (magenta, solid line), classical exponential integrator (45) (green, dashed) and exponential-type integration scheme (35) (red, squares) for a smooth solution with initial value (46) and $\mu=1$. The slope of the continuous lines is one and two, respectively (Color figure online)


Fig. 7 (quadratic NLS) Error of the Lie splitting (43) (blue, dotted), Strang splitting (44) (magenta, solid line), classical exponential integrator (45) (green, dashed) and exponential-type integration scheme (35) (red, squares) for a non-smooth solution with initial value (41) and $\mu=1$. The slope of the continuous lines is one half and one, respectively (Color figure online)

exponential-type integrator is by far the best method. It is first-order convergent, as predicted by Theorem 4.3.

Example 5.3 (Small nonlinearity) We consider the quadratic Schrödinger equation of type (27) with small nonlinearity, i.e.,

$$
\begin{equation*}
i \partial_{t} u=-\partial_{x}^{2} u+\mu u^{2}, \quad \mu=0.01, \quad T=10 \tag{47}
\end{equation*}
$$

The error at time $T=10$ measured in a discrete $L^{2}$ norm of the exponential-type integrator (35), the Lie splitting scheme (43), the Strang splitting scheme (44) and the classical exponential integrator (45) for smooth and non-smooth solutions is illustrated in Fig. 8 left and right, respectively. As a reference solution, we take the Strang splitting scheme for smooth and the schemes themselves for non-smooth solutions with a very small time step size. For smooth initial data, all methods show their classical orders of convergence. The new exponential-type integrator, however, is by far the most accurate scheme (for the considered range of step sizes). For non-smooth initial data, the classical exponential integrator does not converge; Lie and Strang splitting suffer


Fig. 8 (quadratic NLS) Error of the Lie splitting (43) (blue, dotted), Strang splitting (44) (magenta, solid line), classical exponential integrator (45) (green, dashed) and exponential-type integration scheme (35) (red, squares) for a small nonlinearity (47). Left picture Smooth initial value (46). The slope of the continuous lines is one and two, respectively. Right picture Non-smooth initial value (41). The slope of the continuous lines is one half, and one, respectively (Color figure online)


Fig. 9 Exponent $p=1$ (upper row, left) and $p=\frac{3}{4}$ (upper row, right), $p=\frac{1}{2}$ (lower row, left) and $p=\frac{1}{4}$ (lower row, right). Error in the energy space $H^{1}$ of the Lie splitting (38) (blue, dotted), Strang splitting (39) (magenta, solid line), classical exponential integrator (40) (green, dashed) and exponential-type integration scheme (25) (red, dash dotted) with smooth initial value (48). The slope of the continuous and dotted line is one and two, respectively (Color figure online)
again from a strong order reduction down to order one half. Only the new exponentialtype integrator is very accurate and first-order convergent, as expected.

### 5.3 Numerical Experiments for Semilinear Schrödinger Equations with Non-integer Exponents $\boldsymbol{p}$

In this section, we numerically investigate the convergence rates in the case of semilinear Schrödinger equations of type (6) with non-integer exponents $p$. In Fig. 9 we plot the error at time $T=1$ measured in a discrete $H^{1}$ norm of the exponential-type integrator (25), the Lie splitting scheme (38), the Strang splitting scheme (39) as well as the classical exponential integrator (40) for different values of $p>0$. In all the simulations, we take the smooth initial value

$$
\begin{equation*}
u(0, x)=\sin x \in \mathcal{C}^{\infty}(\mathbb{T}) \tag{48}
\end{equation*}
$$

and $\mu=1$. Note, however, that the nonlinearity is only smooth for $p>\frac{1}{2}$.
For $p=1$, all methods show their classical orders of convergence, as expected. For smaller values of $p$, however, the convergence behavior of Strang and Lie splitting deteriorates. Surprisingly, both exponential integrators retain their first-order convergence down to very small values of $p$. This is the subject of future research.

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