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Pattern Mining and Anomaly Detection based on Power System Synchrophasor Measurements

Huiying Ren¹ Zhangshuan Hou¹ Earth System Science Division¹ Pacific Northwest National Laboratory {Huiying.Ren | Zhangshuan.Hou} @pnnl.gov

Abstract

Real-time monitoring of power system dynamics using phasor measurement units (PMUs) data improves situational awareness and system reliability, and helps prevent electric grid blackouts due to early anomaly detection. The study presented in this paper is based on real PMU measurements of the U.S. Western Interconnection system. Given the nonlinear and non-stationary PMU data, we developed a robust anomaly detection framework that uses wavelet-based multi-resolution analysis with moving-window-based outlier detection and anomaly scoring to identify potential PMU events. Candidate events were evaluated via spatiotemporal correlation analysis and classified for a better understanding of event types, resulting in successful anomaly detection and classification of the recorded events.

1. Introduction

The phasor measurement units (PMUs) provide high-resolution, accurate, and synchronized information about power system state. Active deployment of PMUs enables a more reliable and efficient manner of power system operations by monitoring key metrics, such as angle and voltage stability, along with power system oscillations [1, 2]. According to North American Synchrophasor Initiative (NASPI), the installations of PMUs are rapidly increasing in the United States. In July of 2012, there were only about 500 PMUs installed across the country, but the number increased to over 2000 installed PMUs by 2015 [3]. Given the large coverage and rich capability of PMUs, extensive research in applying PMU measurements to enhance the situational awareness for the power grid has been conducted [5-9], and PMUs have been utilized for voltage stability improvements [4] and building of advanced Wide Area Monitoring Protection and control (WAMPC) systems [4].

Heng Wang², Dimitri Zarzhitsky³, Pavel Etingov² Electricity Infrastructure & Building Division², Computing and Analytics Division³ Pacific Northwest National Laboratory {Heng.Wang | Pavel.Etingov} @pnnl.gov

The magnitude phasors data from PMUs were used to analyze voltage stability in real time [10]. Also, studies of phasor angle data from PMUs were performed for line outages detection [11].

Since the amount of PMU data rapidly increased, implementation of data mining on PMUs can benefit the operator by tracking power system dynamics and detecting conditions that could result in system blackouts. For example, anomaly detection of PMU data has been done using transmission line parameters [12], where continuous monitoring of equivalent impedances of transmission lines is required. When Supervisory Control and Data Acquisition (SCADA) system data is available, a correlation examination of the PMU data can be useful [13] and optimal filtering and feature-based classification approaches to improve accuracy of PMU anomaly detection have been studied [14], [15].

Data mining is often referred to as knowledge discovery in databases (KDD), and finding or recognizing patterns can be thought of as fitting a model to the data. Pattern mining techniques can be used to analyze power system behaviors, such as frequency or voltage changes in the PMU measurements, as well as to localize these anomalous events.

Anomaly detection can be accomplished by several signal-processing approaches, such as Eigenvalue Analysis (EA), Fourier Transform (FT), Short Time Fourier Transform (STFT), Spectral Analysis (SA), and others. Since PMU signals are usually nonstationary, many standard FT methods unsuitable for PMU applications. It has been demonstrated that advanced algorithms based on FT [16] can be applied to PMU data to improve dynamic phasor estimates. However, with a large amount of PMU data, computational requirements are significant [17]. Likewise, because STFT and SA approaches are based on fixed-size windowing techniques, they are less accurate and efficient in tracking signals in both time and frequency domains.

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In contrast, the wavelet transform separates 1D signals into 2D components overlapping in time-frequency domain. The wavelet techniques have been widely used because of good multiple time-frequency resolution [18, 19]. Wavelet transforms have been proven to be very efficient [20] in signal analysis, with a reduction of the number of coefficients as the scaling factor increases. Discrete wavelet transform (DWT) is sufficient to decompose and reconstruct most power quality problems, which can analyze information accurately and efficiently [21]. Wavelet-based anomaly detection has been successfully applied for detecting network anomalies [22-26] for various systems and problems. Waveletbased multi-resolution analysis (MRA) uses a wavelet function and a scaling function to decompose and reconstruct the signal at different resolution levels, allowing the anomaly phenomena to be detected and localized at each resolution level.

In this study, MRA was applied to the PMUs in a U.S. Western Electricity Coordinating Council (WECC) system. The paper is organized as follows: Section 2 describes the theoretical background of MRA, and moving-window-based outlier detection and anomaly scoring system. Section 3 demonstrates detection results using real-world PMU data, together with classification analyses of the verified events. The different scoring systems and spatiotemporal correlation analyses are discussed in Section 4.

2. Methodology

2.1. Multi-resolution analysis (MRA)

Wavelet process using DWT can filter the input signal with lowpass and highpass filters. Lowpass filter is defined by a scale function, that is,

$$\varphi_{j,k}(x) = 2^{\frac{j}{2}} \varphi(2^{j} x - k)$$
(1)

where k is the translation coefficient and j is the scale factor [27]. The expansion function of any subspace can be built from double-resolution copies of themselves [28], so the scaling function can be written as

$$\varphi(x) = \sum_{n} h_{\varphi}(n) \sqrt{2} \varphi(2x - n)$$
(2)

where h_{φ} represents the scaling function coefficients. The highpass filter is defined by a wavelet function,

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$$\psi_{j,k}(x) = 2^{\frac{j}{2}} \psi(2^{j} x - k)$$
(3)

It can be expanded to

$$\psi(x) = \sum_{n} h_{\psi}(n) \sqrt{2} \psi(2x - n) \tag{4}$$

where h_{ψ} contains the wavelet function coefficients. The DWT decomposes signals into the approximation (A) and detail (D) components, respectively. Approximation of the signal at resolutions 2^{-j} , j = 0, 1, 2 ... can be obtained at decreasing levels of detail. A detailed theory of MRA has been developed by Meyer [29], and can be mathematically expressed as

$$f(x) = \sum_{n} C_{o}(n)\varphi(x-n) + \sum_{n} \sum_{j=0}^{j-1} D_{j}(n) 2^{\frac{j}{2}} \psi(2^{j}x-n)$$
(5)

where C_o is the 0 level scaling coefficient and D_j is the wavelet coefficient at scale *j*. The scaled and translated wavelet $\psi(2^j x - n)$ in MRA is a decomposed signal in the time-frequency domain. Orthogonal wavelets expanded by 2^j carry signal variations at the resolution 2^{-j} . A number of wavelet families have been developed with different characteristics, and a well-known family is the Daubechies (db) [30]. In our paper, Haar (db1) wavelet is employed in the MRA. Haar's wavelet has 1 moment of wavelet function, which has a linear phase and a complete localization in the time domain [30] [31].

2.2. Anomaly scoring and classification

The raw PMU data that was used in this study contains 12 units representing signals at 12 different locations in the WECC system. For each PMU, there are four attributes, including the voltage, angle variation (lag 1 differences for PMU phasor angle), frequency, and rate of changes of frequency (ROCOF). The PMUs are stored in PDAT format [32], developed by the Bonneville Power Administration (BPA). The format was based on IEEE Std. C37.118.2-2011 data frames [33]. Each file contained 1 minute of PMU data at a 60 samples per second resolution. In this paper, the PMU signals were re-sampled at 1Hz for our framework since we focused on detecting anomalous events which usually lasted for a number of seconds and the variability within 1 second generally has weak correspondence to the potential events.

To localize anomalies at each decomposed resolution level, a moving-window-based outlier detection approach was proposed. The moving window can retain both reliability and sensitivity of the detection performance. The anomalous score was set to be 1 if an anomaly was detected at each resolution level. The anomaly score matrices were the summation of scores at multiresolution levels across 12 units for each PMU attribute. The anomalous scores can be used to rank the 'likelihood' of events. Given the fact that the recorded actual events last between 5 and 20 seconds, the detected anomalies were further prescreened by the event durations. Spatiotemporal correlation analysis were applied to the anomaly candidates to distinguish between false alarms and real events. The false alarms are expected to have weak spatiotemporal correlations due to locality and weak continuity, although local events may actually occur for only a few PMUs. In general, strong correlations across units should verify and confirm the real events [34].

For the verified events, we deployed the cluster analvsis and Principal Component Analysis (PCA) for identifying similarities between the events. Clustering groups multiple objects by putting similar objects in the same group. The appropriate clustering algorithm and clustering model parameters are problem-dependent. In this study, we used Expectation Maximization [35] algorithm for clustering analysis [35-37]. EM-clustering is a general model-based approach for approximating maximum likelihood estimations using Bayesian information criterion (BIC) [38]. PCA is also useful for similarity identification; it converts observations of possibly correlated variables into a set of values of linearly uncorrelated variables (called principal components) using orthogonal transformation. The first principal component has the largest possible variance and the most variability. By combining quantitative clustering methods, PCA helps highlight which attributes are useful for discriminating the individual events.

The framework of wavelet-based anomaly detection and classification is illustrated in Figure 1. In the next section, we will present the detection results using the proposed framework.



Figure 1. Wavelet-based PMU anomaly detection and classification framework.

3. Results

We evaluated our detection framework on the actual Western Interconnection synchrophasor data. The raw PMU signals were down-sampled to 1Hz, so the time resolution for the MRA procedure was 1 second, and the first three levels of MRA, D1, D2 and D3, have resolutions of 2-, 4- and 8-seconds, respectively. The 2D timefrequency representation of real-world PMUs has significant benefits compared to the regular 1D data in the time domain for event detection perspective. Figure 2 illustrates MRA and moving-window outlier detection results for the first unit of PMUs (PMU1) using the frequency attribute. Given the observations of the signal and detailed wavelet coefficients, the events are more evidenced from the D3, D2, and D1 coefficients than from the original, and it thus helps to increase event localization accuracy. This increase with detail coefficients is the key-component of our event detection algorithm. The recorded historical events were marked in red in Figure 2(a), which shows that the anomalous candidates have been identified at each resolution level using our detection framework.

In this study, we used a 30-day real-world PMU dataset to test the framework, with 32 historical events that were recorded during the 30-day testing time period. We analyzed four attributes, including the voltage, angle variation, frequency and ROCOF for each PMU dataset. In general, the ROCOF attribute has nosier signals than the rest of the attributes, and the detected candidates have weak spatiotemporal correlations. As observed in [14], ROCOF has large variance which reduces the event detection accuracy due to sensor and grid dynamics. The angle variation attribute contains similar (and relatively redundant) information to the frequency attribute because the frequency is derived from the angel variation. Therefore, it is warranted to focus on the voltage and frequency attributes for event detection in this evaluation.



Figure 2. An MRA example using PMU 1 frequency attribute. The detected events at each scale are marked in red.

In our study, all recorded events have been detected with high scores. For example, Figure 3 illustrates one event occurred at all 12 units, which is detected based on the frequency attribute. At the time of event, the frequency amplitude jumped from 59.96 to 60.01 Hz within 10 seconds. The 12 units behave consistently at the moment of event occurrence, resulting in strong spatial correlations. This warrants increased situational awareness and indicates systematic behavior and areawide situation to be monitored. The same event was also detected from the voltage attribute, with strong correlations across all units as shown in Figure 4. The amplitude of voltage for each unit increased by over 1000 Volts within 10 seconds. After the event, the voltage stabilized, but did not necessarily return to the same voltage level as prior to the event.

Two other recorded historical events were reported during the same day. In fact, according to the scoring system, the event in Figure 3 was ranked #7 in terms of the frequency magnitude. The other two were ranked #1 and #2 respectively. Their ranks in terms of voltage events are #2 (the event in Figure 4), #3 and #6 respectively. Besides recorded under-frequency events, we also detected several over-frequency events with comparable or even higher scores.



Figure 3. An example of frequency event occurred across all units. The detected events for each unit are marked in red. The recorded historical events are marked in green.



Figure 4. An example of voltage event occurred across all units. The detected events for each unit are marked in red. The recorded historical events are marked in green.

Our framework also enables detection of anomalies when they are local. During another time period on the same testing day, two voltage events were detected, as shown in Figure 5, where 7 out of the 12 units did not show evidence of the same anomalies. The first event occurred at unit 9 only, and the second event happened at units 3, 5, 8 and 10, respectively. Figure 6 shows the frequency signals for the same time period as in Figure 5, with no frequency events detected, suggesting that the events that happened during this time period were mainly voltage-related. Special attention is needed for these types of events as they cannot be treated as "bad data" although the spatiotemporal correlations are relatively weak.



Figure 5. Two examples of voltage events detected at different local units. The detected events for each unit are marked in red. No historical events were recorded during this time period.



Figure 6. PMU Frequency during the same time period as Figure 6. No frequency events were detected.

PCA were applied to evaluate and classify the identified events. The PCA result is illustrated in Figure 7. The left panel shows the first two principal components of three attributes (voltage, angle variation, and frequency). The events can be grouped easily based on the Biplot. For example, anomalies #83, #108, #109 and #142 have outstanding differences in both frequency and angle variation compared to other anomalies; while anomalies #11 and #141 have outstanding voltages among the anomalies. Another unsurprising observation is that the angle variation has a strong correlation with the frequency, and the two have redundant information with very similar behaviors contributing mainly to the first principal component. The variability of voltage is the major contributor to the second component. By removing the redundant angle variation in PCA, the voltage and frequency are nearly orthogonal factors as shown in the right panel in Figure 7. PCA helps classify the identified events to be either frequency-related or voltage-related. However, there are a few exceptions; for example, events #2, #85, #113 and #116 are clearly identifiable using both frequency and voltage factors. And three of them were actually the historical recorded events, which were detected using both voltage and frequency attributes.



Figure 7. PCA Biplots of detected events using different PMU attributes. The historical recorded events are circled in blue.

EM-clustering was used to assign the events to different classes. The goal of EM clustering is to estimate the means and standard deviations for each cluster so as to maximize the likelihood of the observed data. The Rpackage mclust [39] was used for the clustering, and the optimum number of clusters was determined to be 3, based on voltage, angle difference, and frequency attributes. The clustering results are shown in Figure 8. Note that the recorded actual events were all clustered into the same group (i.e., class 2) with the smallest group size. The events falling into the same class (i.e., class 2) as the recorded ones are potential events of interest. The clustering approach helps reduce the number of events, and therefore reduce the chance of false alarms. The historical recorded events tend to have outstanding anomalies in terms of both voltage and frequency, and therefore can be considered as voltage-frequency-related events, as do the events in the entire cluster 2.



Figure 8. Clustering analysis of detected events using three PMU attributes including voltage, angle variation, and frequency. The historical recorded events are marked in blue.

4. Discussion

We described and developed a PMU signal analysis framework that features a scoring system for the anomaly detection as explained in Section 2. We also evaluated the effect of an alternative scoring system on our detection framework. Compared with the additive scoring system, the alternative multiplicative scoring system is much stricter, because the score for each MRA scale at each unit is multiplied to obtain scores of either 0 or 1. This multiplicative scoring system, reduced both the false alarm and anomaly detection rates. Future work will address techniques for enhancing the ratio of anomaly detection over false alarms.

Wu and Xie's work [34] shows that spatiotemporal analysis can be applied to reduce the false alarm rate effectively. In general, real events have strong spatial and temporal correlation, but this is not always true due to measurement errors, bad data, and local events. Further investigation of the real-world PMU data from a variety of sources and scenarios will be needed, especially for those units/regions where local events are likely to occur.

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