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Clustering Objects For OODBs in a Multiple Relationship Environment

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Abstract

When data objects in databases are involved in more than one kind of relationships, we say that these objects are in a multiple relationship environment. Object-Oriented databases are an example of such in a multiple relationship environment. That is, an object in OODBs may participate in is-a, is-instance-of, part-of and other relationships. The main goal of this paper is to take into account of all of these relationships when clustering objects in secondary storage. We develop a distance metric for objects to measure the degree of interrelationship, and apply a greedy algorithm to order the objects. After this sequence is constructed, we then can easily put this object sequence onto the secondary storage and achieve the purpose of clustering. We also discuss in this paper the features of our method that make it different from the previous proposed methods.

1. Introduction

1.1 Overview of Clustering in OODBs

The Object-Oriented (OO) paradigm has been recognized as a useful approach in knowledge representation, programming languages, and software engineering. Besides, the OO concept has also been applied to the database systems recently because of its extensibility and semantic richness. Object-Oriented databases (OODBs) offer the next-generation database applications a good solution to the major shortcomings of traditional relational database systems. These are several characteristics of OODBs which we consider make it especially suitable for the newly-emerging applications, such as OIS, CASE, and CAD/CAM systems. These characteristics include 1) the support of complex objects that enable users to define new complex data types instead of only system-defined flattened primitive data types instead of only system-defined flattened primitive data types. 2) the inclusion of abstract data types which make it easier to describe the dynamic behavior of the data, thus increasing the level of abstraction. 3) the use of inheritance that facilitates the database designers to reuse the attribute/code definitions, and 4) the support of object identity that makes it more natural to model the real-world entities.

Many OO languages such as Smalltalk and CLOS have been extended with the functions of persistence and shareability in order to make them become database programming languages. These OO languages have both the advantages of object-orientation and database systems. However, in order for these Object-Oriented database systems to be more practical and useful, some other database features must be added [9][25][26]. For example, a declarative query language [18], concurrency management [14], authorization [12], and storage control [13] must also be reconsidered in OODBs. Especially, the functionality of managing large amount of data safely and efficiently is crucial for OODBs design. In this paper, we concentrate on discussing and proposing an approach for elustering in OODBs.

Clustering is an important issue in physical database design [23]. It is concerned with how to store the related data onto secondary storage as closely as possible in order to expedite

the efficiency of data retrieval. Therefore, clustering can improve the performance of the database systems, which is the a major problem of OODBs. In traditional relational database systems, each relation is independent. The relations are joined dynamically according to the inter-relationship of relations when a user's query is processed. Consequently, it is sufficient to use either the n-ary storage model (NSM) or the decomposition storage model (DSM) [3][10] for the relational database clustering. But in OODBs, clustering is complicated by the multiple relationships among the objects. That is, an object can be both an instance of a class and a component of a complex object. Besides these aggregation and generalization relationships, other structural relationships such as versions and configurations [1] can also exist. In this situation, the objects are in a multiple relationship environment. This environment affects the clustering methods that can be used because we have multidimensional goals while storing the related objects onto the single-dimensional storage. In order to solve this problem, we propose a method in this paper for compromising on the possible relationships among objects and then ordering the objects into a clustering sequence. After the sequence is constructed, we can then easily map the sequence into the secondary storage and preserve the multiple relationships of the objects, thus achieving the purpose of clustering.

1.2 Previous Related Work

Most previous papers on OODB clustering have been focusing on complex objects (nested objects). In [2] Banerjee and Kim studied the possible traversal methods of a DAG (Directed Acyclic Graph), which is in fact the complex object hierarchy. In [21] Dewitt discussed the representation of large complex objects and the algorithms to dynamically insert and delete objects in the large complex objects with an emphasis on optimizing performance. Another complex object storage model which is not based on the the object reference relationships but rather on the object identifiers was presented in [22]. But the above research only restricted their discussions to a single relationship between objects and did not cover the thorough semantics of the OO paradigm. [1] was the first paper to take into account the multiple relationships (Inheritance, Version, Configuration) in OODBs, and a smart clustering algorithm was also given that

could exploit these structural relationships for clustering objects. However, only one kind of relationship could be input into the smart algorithm instead of the all possible multiple relationships. The actual pioneering paper dealing with the clustering techniques in a multiple-relationship environment is [5]. In [5] related objects can be connected into a multi-graph by assigning a weight according to each relationship between each two objects. Then, a level clustering algorithm is used to construct a maximal spanning tree from this weighted multi-

graph. The clustering problem and our approach in this paper most resemble [5]. However, our approach is different from [5] in that we actually develop a metric to measure the distance between objects, which is a concrete calculation of the weight w in [5]. Besides, the distance metric in our approach also takes into account the cardinality (size) of each relationship set (explained later), which was not considered in [5].

The remaining sections of this paper are organized as follows: In Section 2 we give an OODB example model in order to clarify our problem and also pave the way for future discussions. Section 3 presents our proposed approach, including the distance metric and sequencing algorithm. In Section 4, we discuss the features of our approach and also give some conclusions.

2. The Example Model and Clustering Options

In order to better explain the clustering options in a multiple relationship environment and use this example as an illustration when we introduce our approach, we borrow a sample model from [8]. We choose this example for three One reason is that most of the important concepts of OO are incorporated into ORION [19], which make it a famous OODB. Another reason is that most of the major issues of ORION, including the query model [18], schema evolution [15], and transaction control [14] are already discussed in the literature. The third reason is that ORION system is not a only a proposed model but also implemented and operational [20]. The following graph is a scheme example of a mini-database in an OODB. Each square box is a class with attributes for that class defined inside the box. The dashed line represents the inheritance (is a) relationship and the solid line represents the aggregation (parl_of) relationship. The part_of relationship is the inter-object relationship or the above-mentioned complex object relationship, and the is_a relationship says that each instance of a subclass is also an instance of its supersclasses. Another relationship which is not explicit in this example is the instance of relationship. All of the instances belonging to the same class are considered to possess this relationship. In this paper, if only one kind of relationship was considered, we call that clustering in a single relationship environment, and if all relationships are considered, then clustering is in a multiple relationship environment .

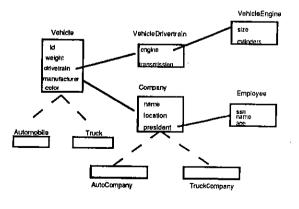


Figure 1: A sample detebase

Several clustering options for the above sample database may be adopted. Option 1 is to cluster all objects which belong to the same class. This involves storing objects according to the textrace-of relationship. For example, all objects in Vehicle would be stored together. Option 2 is to cluster all objects belonging to the same class hierarchy. This involves storing objects according to the is-a relationship. For example, all object in Vehicle, Automobile, and Truck would be stored together. Option 3 is to cluster objects that other objects interreference. This involves clustering objects according to the the part_of relationship. For example, the objects in Vehicle, Company, and Employee would be stored together. It should be noted that the above clustering options are just some of the possible relationships in OODBs. Other more complicated relationships from applications' semantics might also exist. For example, Figure 2 represents the version relationship for the sample database.

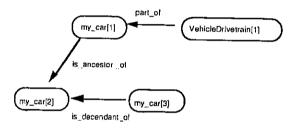


Figure 2: A version network

Each clustering option has major effects on the retrieval performance for the application's access pattern. The access pattern is defined as the traversal sequence for the classes involved in the user's query. We list several possible user's queries to the sample database. A class variable associated with a star (*), like Vehicle*, means to retrieve from this class and all of the subclasses rooted at that class.

Query I: (Vehicle select :V (:V color = "blue"))

Query 2: (Vehicle select : V (: V drivetrain transmission = "
fuel" and (: V manufacturer name = "Ford")))

Query 3:(Vehicle* select :V(:V weight > 1000 and color = "
red"))

Query 4: (Vehicle* select :V (:V color = "blue"))
and (:V manufacturer name = "Ford")))

For each query above, there is a corresponding clustering option that makes the retrieval performance of that query more efficient. For example, the clustering option 1 favors query 1. Similarly, clustering option 2 favors query 2 and clustering option 3 favors query 3. However, no clustering option that we mentioned above favors query 4 because it involves more kinds of relationships than other queries. In summary, each clustering option might be optimal for some kinds of access patterns. Furthermore, dedicating the clustering to one kind of relationship will incur very poor access performance for other queries. For instance, clustering objects according to one kind of relationship in the same disk block will cause objects of any single class to be spread out over a larger number of pages than if the class is the only class to be stored in one block. However, the multiple relationship property is an inherent constraint for both Object-Oriented systems and next-generation applications. Therefore, some way to compromise all of these relationships while dealing with clustering must be developed in order to achieve a better average performance for users' ad hoc queries. This is the motivation for our method to solve this problem.

3. The Distance Metric and Clustering Algorithm

3.1 Outline of Our Approach

As mentioned before, we are going to use distance to measure the inter-relationship of objects. Each object, according to the kind of relationships in which it may participate, can be represented by an n-tuple of (category 1, category 2, ... category n) if there are n possible relationships involved in the system. For example, an object of (C1, CO1, V1) can be thought of as belonging to class C1, complex object CO1, and version network VI. One problem is that most of the values of each category in the n-tuple are qualitative and discrete data. This means that to calculate the distance between each two objects, some quantifying method must be used in order to convert the n-tuple into numeric data, from which a distance can be measured. There are two basic constraints which we consider must be satisfied if some quantifying method is to be used. The first constraint is that any quantifying configuration which faithfully represents the patterns existing among objects must guarantee that more related objects should be represented by points that are closer. The second constraint is that if two objects are non-comparably inter-related, then there should not be any less or greater distance comparison after the transformation. These two distance comparison after the transformation. constraints can rephrased as follows where in denotes the semantic relationships between objects and a denotes the closer than operator .

Constraint 1: $\Theta(01,02)$ α $\Theta(01,03) =>$ Distance(01,02) < Distance(01,03)

Constraint 2: not (($\Theta(01,02)$) α $\Theta(01,03)$) or ($\Theta(01,03)$) α $\Theta(01,02)$) => not ((Distance(01,02) < Distance(01,03)) or (Distance(01,03) < Distance(01,02)))

Our original idea was to quantize each object from a qualitative n-tuple to a numeric n dimensional coordinate system and apply a multivariate analysis method such as the principle component analysis [7] to project these n dimensional points into the principle component, and thus maximize the preservation of relationships from the original n dimensions space. We did not adopt this approach because when we quantize each object into an n-dimensional numeric coordinate, we will lose some semantics. This will not satisfy the second constraint. For example, if category 1 represents the class to which one object belong and we quantize class Vehicle as 1, Company as 2 and VehicleDrivetrain as 3, then this makes Vehicle more related to VehicleDrivetrain than to Company (3-1 > 3-2). However, this quantified transformation of the qualitative data is wrong. Therefore, we develop a metric to directly measure the distance between each two objects instead of transforming each object into an n-dimensional point. Our metric satisfies both the first and second constraints, thus does not lose any semantics of object inter-relationships.

3.2 Distance Metric

A relationship set is defined to be the set of objects that are constrained in the relationship and the size of the relationship set is defined to be the number of objects in this set. For example, one relationship set is the class Vehicle, and its size is the number of instances in Vehicle. Another relationship set is the complex object instance involved in Vehicle, Company, and Employee, and its size is the number of objects that comprise this complex object instance. In this paper, each relationship set will be denoted Rm and its size will be denoted Rm. We can now define the parameters and the distance metric, which is a measure of distance between each two objects, as follows.

 $Distance(o_i,o_j) =$

$$\sum_{m=1}^{n} P_{m} * (\delta_{i,j,Rm} * (1/2) * |Rm| + \beta_{i,j,Rm} * (1/2) * L) * s$$

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n : number of relationship sets k : number of objects in the system

s : object sizes

L : total size of all objects (L = k * s)

b : disk block size

The above formula is rather generalized since it encompasses every possible relationship in the system and is calculated by compromising the effects of all relationships. In this formula, we have assumed that the size for each object in the system is the same, and is equal to s. Pm is the probability that the system is clustered by relationship Rm. This probability comes from the probabilistic distribution of applications' access patterns and can be specified by system designers. If some access pattern occurs more often or is more important, then its corresponding probability will also be larger. However, we assume that each probability Pm is the same and is equal to 1/n in the discussion below. We now explain the meaning of this distance metric. It is the expected value of the object distance by considering all semantic relationships. This expected distance is formed by summing the product of the probability Pm and the average distance (see Figure 3) of objects clustered by each possible relationship. The objects are represented by an n-dimensional coordinate.

 $\delta_{i,j,Rm}$ and $\beta_{i,j,Rm}$ are mutually-inverse characteristic functions that have values either 1 or 0. They can be stated as follows:

Now assume the simple case that only instance of and part-of relationships exist in the system. Suppose that the instance-of relationship is indexed as R1 and part-of relationship is indexed as R2. We show how the distance of each two objects of the example in Section 2 can be calculated. Because we assume that P1 and P2 are the same, they will be both equal to 1/2.

R1 1/2 *(1/2 * | Cr | + 1/2 * L) Case 1: if oi and oj are in the same class Cr but not in the same complex object Case 2: 1/2 *(1/2 * L if of and of are not in the same class but are in the same complex object COr 1/2 *(1/2 * ICr11 + 1/2 * ICOrpl) Case 3: if oi and oj are in the same class Cr1 and are also in the same complex object. COro 1/2 *(1/2 * L Case 4: if oi and of are not in the same class and are not in the same complex object

For example, the distance between two objects in class Vehicle will be 1/2(1/2 * IVehicle! + 1/2 * L) if they are not

cyclically referenced. However, if oi and oj are further recursively referenced [16], then the distance will be 1/2(1/2 IVehicle! + 1/2 ICOp!) where COp is the complex instance that contains oi and oj. It can be shown that the distance for the above case has the property that distance (case 3) < distance(case 1) < distance (case 4) and distance (case 3) < distance(case 2) < distance (case 4). This satisfies our constraint 1 because more related objects have less distance. However, the distance for case 1 and case 2 is non-comparable. It depends on the size of the relationship set (ICI and ICOI). This also satisfies our constraint 2 because the closeness relationship is also not comparable. If ol and o2 are in the same class and ol and o3 are in the same complex object, then no absolute semantic closeness can be stated for ol to o2 and ol to o3. The two constraints will be satisfied because the expression IRil < L holds for every relationship set in the system. We now explain how the relationship size is included in the formula. This can be demonstrated in Figure 3. If two objects are in the same class and we also cluster by the instance-of relationship, then the distance will be the the average of the class size. Figure 3 explains how the distance between oi and oj is obtained for Case 1.

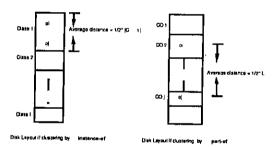


Figure 3 Clustering options for a two-relationship simple case

A similarity matrix [24] can then be constructed. This is a k^*k matrix where each entry of the matrix is the distance between any two objects ($M(i,j) = distance(o_i,o_j)$). This matrix is symmetric with all diagonal elements equal to 0. From this matrix, we can then find a spanning path which includes all of these k objects by applying the sequencing algorithm in the next section.

3.3 Sequencing Algorithm

Since we must eventually put all of the objects onto the linear secondary storage, a better way is to sort the objects of the system into a one-dimensional data structure. Then the mapping of the one-dimensional data structure to the secondary storage will be straightforward. The previous research in [5] constructed objects into a maximally weighted spanning tree. However, because a tree is a two-dimensional data structure, some traversal methods such as DFS or NFS must then be applied in order to linearize the spanning tree. We consider this to be disadvantageous because when we linearize the spanning tree, some distance relationships, which are also semantic relationships of objects, may be compromised. Therefore, our sequencing algorithm outputs the result as a spanning path, by which all of the multiple relationships can still be preserved to some degree.

After the distance matrix is constructed by assigning the distance between each two objects, the following sequencing algorithm [11] can be used to order the objects into a path sequence. The input of this algorithm is the distance matrix which can represent the weighted average of each relationship between each 2 objects. We also assume that there are totally k objects in the system. Each one of these k objects can be a member of more than one kind of relationship set. This algorithm is based on the greedy strategy because it works by including one object at a time into the current spanning path. This can be done by selecting an unprocessed object which adds the minimum distance to the total distance of the current spanning path.

[Totally Shorter Spanning Path Algorithm]

Input : Similarity matrix M[i,j].

Output: a spanning path that includes {01,02,...ok}.

Step 1: Let i = 1, W = {o1,o2,...ok}, and current spanning path P = [].

Randomly select an object o from the unprocessed objects W.

Detete o from W.

Step 2: Choose an object ou from the remaining k-i objects in W such that M(Rt, ou) + M(ou, Rt+1) - M(Rt,Rt+1) is minimized.

Insert ou into the current spanning path to be P=[R1,...,Rt,ou,Rt+1,...,Ri].

Delete ou from W. (See Figure 4)

Step 3: if i < k then i = i + 1, go to Step 2.

Step 4 : Output P as the clustering sequence.

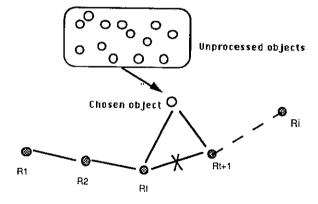


Figure 4 Insert one chosen object into the current spanning path

The problems of finding the optimal clustering scheme for generalized access patterns and the finding of a shortest-spanning-path (STSP) are both NP-Complete [11][17]. Our Totally Shorter Spanning Path (TSSP) algorithm was inspired by the Shorter-Spanning-Path (SSP) algorithm proposed in [11]. The main difference between TSSP and SSP is that in Step 2 SSP randomly chooses an object from W and inserts it into the current spanning path at a particular position which adds the minimum extra distance but TSSP iterates over all of the unprocessed objects in W to find the minimum added distance. The total distance of the resulting spanning path for TSSP is less than that of SSP because in TSSP the checking of all of the unprocessed objects in W also covers the checking of the randomly selected object from W in SSP. In order to clarify the difference between these three spanning path constructing algorithms, we compare STSP, TSSP, and SSP with respect to time complexity and optimality in the following:

Optimality: STSP > TSSP > SSP

Execution time : $SSP(O(k^2)) > TSSP(O(k^3)) > STSP(exponential)$

Because the secondary storage access unit is a disk segment or a block, the spanning path must be be cut into path segments according to the ratio of the object size to the block size (b/s). Notice that our clustering sequence is not interrupted by segmenting the spanning path. The change only occurs at the segmentation boundary. This can still be compensated for by placing the adjacent path segments into the contiguous neighboring blocks, which can save disk access time. In the next section, we discuss the common features of clustering in database systems and compare our approach with the previous proposed methods.

4. Discussion of Our Approach and Conclusions

4.1 Discussion

In this section, we discuss several features of our approach, which are also the criteria for clustering. We only list those points that we consider different from previous proposed approaches.

I. Access performance: Clustering fastens the access performance of related data in the databases. The related data are correlated by multiple kinds of relationships. Therefore, the access performance is the expected average access cost of all possible access patterns, each of which retrieves data according to some relationship. Because there are n kinds of relationships in the system, n kinds of access patterns (queries) denoted QR1.QR2...., and QRn may be issued to the databases. We also assume that each clustering scheme based on relationship set m favors access pattern QRm. The retrieval cost of objects for QRm will be proportional to the distance of any two objects belonging to relationship set Rm. If all of the access patterns are considered, then the average retrieval cost for Q_{R1}, Q_{R2}, \ldots , and Q_{Rn} , which equals $(P_1 * Cost(Q_{R1}) + P_2 * Cost(Q_{R2}) + \ldots + P_n * Cost(Q_{Rn})$), will be proportional to our distance metric, if the access probability of QRm is Pm. This means that our distance metric is also based on the expected average access cost for possible access patterns QR1,QR2,..., and QRn. Our approach gains in access performance in that we are constructing a totally shorter spanning path that sums up less total access cost. Therefore, our approach has a better chance to induce better average access performance. We want to emphasize that the optimal access performance is very hard to achieve because it's an intractable problem. The advantages of our approach come from the merits of the shorter spanning path (SSP), which are shown in [11]. Furthermore, our sequencing algorithm results in a TSSP which is better than SSP

2. Automatic and adaptive: Many DBMS adopt the scheme of receiving hints from users, which are frequent access patterns, and support a default strategy if hints are not Two drawbacks might exist for this scheme. specified by users. One is that users have to deal with the multiple relationships of objects, which are intrinsically multiply-dimensional and which could even conflict with each other. Users probably are able to specify one kind of relationship but are unable to combine all of the relationships and then give hints to the DBMS. The other problem is that sometimes users will need to specify a subgraph of the nested schema graph of a class for clustering For example, it may be useful for users to give hints to store physical components of a vehicle object in the same block, but not the Company objects for the manufacturer attribute of the Vehicle objects. This problem comes from the fact that users have little knowledge of the extensional information, such as the class size, the actual object reference relationships and object sharing relationships, of the databases. Therefore, a better approach is for the system to automatically cluster objects, because the system knows more information for clustering than the users. Our approach is automatic because the calculation of the distance metric and the sequencing process are all done by the system. However, our approach is

also adaptive. This is from our sequencing algorithm Step 2 that when there are several chosen objects that all satisfy the condition ($M(R_t, o_u) + M(o_u, R_{t+1}) - M(R_t, R_{t+1})$ is minimized). Users can then be involved in which object should be chosen. That means our clustering method is adaptive when the system has alternatives to decide and the users help to make the decisions

3. Declustering: Declustering in databases is used to divide the database into homogeneous groups and store each homogeneous group in a multi-disk system of distributed environment in order to exploit the parallel access of related data [4][6]. Our sequencing algorithm outputs the result as a path sequence. This sequence can then be cut to form homogeneous groups, which we call path segments above. Each path segment can be allocated to a site in distributed environments or to each block in a multi-disk system and a parallel search techniques may be used to fasten the access speed for the users' queries [6].

4.2 Conclusions

A method of measuring distances between objects and a sequencing algorithm are proposed in this paper. Our distance metric covers the thorough semantic relationships of objects in This is important for Object-Oriented database the OODBs. clustering because the OODBs applications impose more complicated access patterns than traditional relational database applications. Any clustering scheme for OODBs which is offered to versatile applications should not favor some special access pattern but sacrifice others. A better average performance for each kind of access pattern ought to be achieved in order to generalize the uses of the Object-Oriented database system. Our method is based on the simplicity of calculating distance but without losing flexibly to consider multiple kinds of object without tosing liexiony to consider motions a series relationships. It is further enhanced by our sequencing algorithm, which finds a direct mapping between the object sequence and secondary storage. Because of the importance of improving the efficiency of OODB access times, including for we feel that clustering in multipledistributed systems, relationship environments should remain a major research issue for some time to come.

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