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# Indefinite least-squares problems and pseudo-regularity 

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## A B S T R A C T

Given two Krein spaces $\mathcal{H}$ and $\mathcal{K}$, a (bounded) closed-range operator $C: \mathcal{H} \rightarrow \mathcal{K}$ and a vector $y \in \mathcal{K}$, the indefinite least-squares problem consists in finding those vectors $u \in \mathcal{H}$ such that

$$
[C u-y, C u-y]=\min _{x \in \mathcal{H}}[C x-y, C x-y] .
$$

The indefinite least-squares problem has been thoroughly studied before under the assumption that the range of $C$ is a uniformly $J$-positive subspace of $\mathcal{K}$. Along this article the range of $C$ is only supposed to be a $J$-nonnegative pseudo-regular subspace of $\mathcal{K}$. This work is devoted to present a description for the set of solutions of this abstract problem in terms of the family of $J$-normal projections onto the range of $C$.
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## 1. Introduction

In signal processing applications it is frequently assumed that the mathematical model, describing the physical phenomena under study, satisfies the following equation:

$$
z=H x+\eta
$$

where $H \in \mathbb{R}^{m \times n}$ is known and $x \in \mathbb{R}^{n}$ is a parameter that needs to be determined. Sometimes, due to physical restrictions, it is not possible to measure $x$, and it is necessary to estimate this vector based on

[^0]the measurement $z$, which is corrupted by noise $\eta$. According to the characteristics of the noise, different techniques may be used to estimate $x$. For instance, when no statistical information about the noise measurement is available, the $\mathcal{H}^{\infty}$-estimation technique has been proved to be an appropriate approach for several engineering problems. Given $\gamma>0$, the $\mathcal{H}^{\infty}$-estimation technique in $\mathbb{R}^{n}$ consists in finding an estimation $\hat{x}$ of the vector $x$, such that:
\[

$$
\begin{equation*}
\max _{x \in \mathbb{R}^{n}} \frac{\|x-\hat{x}\|^{2}}{\|z-H x\|^{2}} \leq \gamma^{2} \tag{1.1}
\end{equation*}
$$

\]

or equivalently,

$$
\begin{equation*}
\min _{x \in \mathbb{R}^{n}}\left(\|z-H x\|^{2}-\frac{1}{\gamma^{2}}\|x-\hat{x}\|^{2}\right) \geq 0 \tag{1.2}
\end{equation*}
$$

Note that the left hand side of (1.2) can be modeled as the minimization of an indefinite inner product on an affine manifold. In fact, $\mathbb{R}^{m+n}$ can be endowed with the indefinite inner product $[x, y]:=x^{T} J y, x, y \in$ $\mathbb{R}^{m+n}$, where $J \in L\left(\mathbb{R}^{m+n}\right)$ is the fundamental symmetry given by $J=\left(\begin{array}{rr}I_{m} & 0 \\ 0 & -I_{n}\end{array}\right)$. Then, considering $C:=\binom{H}{\gamma^{-1} I_{n}} \in L\left(\mathbb{R}^{n}, \mathbb{R}^{m+n}\right)$ and $y:=\binom{z}{\gamma^{-1} \hat{x}} \in \mathbb{R}^{m+n}$, the $\mathcal{H}^{\infty}$-estimation problem is equivalent to finding a vector $y$ (which depends on $z$ ) such that the following indefinite least-squares problem (ILSP) admits a solution:

$$
\begin{equation*}
\min _{x \in \mathbb{R}^{n}}[y-C x, y-C x] \tag{1.3}
\end{equation*}
$$

and to show that this minimum is nonnegative, see [8].
This work is devoted to studying an abstract ILSP: Given arbitrary Krein spaces $\mathcal{H}$ and $\mathcal{K}$, a closed-range operator $C \in L(\mathcal{H}, \mathcal{K})$ and a vector $y \in \mathcal{K}$, find the vectors $u \in \mathcal{H}$ such that

$$
[y-C u, y-C u]=\min _{x \in \mathcal{H}}[y-C x, y-C x] .
$$

In finite-dimensional spaces, the ILSP has been exhaustively studied see e.g. [13,14,21,8,15,20,7]. In these papers, if $J$ is the fundamental symmetry of $\mathcal{K}$, it is assumed that $C^{T} J C$ is a positive-definite matrix, which is a sufficient condition for the existence of a unique solution for the ILSP. This is equivalent to assuming that $C$ is injective and the range of $C$ (hereafter denoted by $R(C)$ ) is a uniformly $J$-positive subspace of $\mathcal{K}$. Then, the regularity of $R(C)$ plays an essential role, since it guarantees the existence of a $J$-selfadjoint projection onto $R(C)$, which determines the unique solution of the ILS problem (1.3).

Even for the general setting it is known that the ILSP admits a solution if and only if $R(C)$ is $J$-nonnegative and $y \in R(C)+R(C)^{[\perp]}$, see e.g. [6, Thm. 8.4]. Then, the ILSP is well-posed only for the vectors $y$ in the (not necessarily closed) subspace $R(C)+R(C)^{[\perp]}$. Moreover, given $y \in R(C)+R(C)^{[\perp]}$, $u \in \mathcal{H}$ is a solution of the ILSP if and only if $y-C u \in R(C)^{[\perp]}$ (see Lemma 3.1), i.e. if $u$ is a solution of the normal equation associated to $C x=y$ :

$$
C^{\#}(C x-y)=0,
$$

where $C^{\#}$ stands for the $J$-adjoint operator of $C$.
The assumption that $R(C)$ is a uniformly $J$-positive subspace of $\mathcal{K}$ implies that the ILSP is properly defined for every $y \in \mathcal{K}$, but this is a quite restrictive condition. Along this article (most of the time) it is assumed that $R(C)$ is a $J$-nonnegative pseudo-regular subspace of $\mathcal{K}$. Thus, the ILSP admits solutions for
every vector in the (proper) closed subspace $R(C)+R(C)^{[\perp]}$. The pseudo-regularity of $R(C)$ is equivalent to the closedness of $R\left(C^{\#} C\right)$, see Lemma 3.4. Hence, under this assumption, the Moore-Penrose inverse $\left(C^{\#} C\right)^{\dagger}$ of $C^{\#} C$ is bounded and the solutions of the normal equation, and therefore of the ILSP, are exactly those

$$
u \in u_{y}+N\left(C^{\#} C\right)
$$

where $u_{y}=\left(C^{\#} C\right)^{\dagger} C^{\#} y$ is the unique solution in $N\left(C^{\#} C\right)^{\perp}$.
It is also worthy to mention that if $\mathcal{K}$ is a Pontryagin space (i.e. $\kappa:=\min \left\{\operatorname{dim} \mathcal{K}_{+}, \operatorname{dim} \mathcal{K}_{-}\right\}<\infty$ for any fundamental decomposition $\mathcal{K}=\mathcal{K}_{+}[\dot{+}] \mathcal{K}_{-}$) then every closed subspace turns out to be pseudo-regular. Therefore, in this case the assumption reduces to assume that $R(C)$ is just $J$-nonnegative.

Another advantage of considering an operator $C$ with pseudo-regular range is that there is a family of $J$-normal projections onto $R(C)$. These projections, which have been previously studied in [19], are the main technical tool used along this work in order to characterize the set of solutions of the ILSP.

The article is organized as follows: Section 2 introduces the notation and terminology used along. It also contains some preliminaries on Krein spaces, mainly on pseudo-regularity and $J$-normal projections.

The indefinite least-squares problem is described in Section 3. After a brief reminder of the state of the art of the problem, it is studied under the assumption that the range of $C$ is a $J$-nonnegative pseudo-regular subspace of $\mathcal{K}$. Also, some considerations are made in order to compare the ILSP associated to $C x=y$ and the ILSP associated to another equation $C^{\prime} x=y$, where $C^{\prime}$ is a closed-range operator such that $R\left(C^{\prime}\right)$ is a uniformly $J$-positive subspace of $R(C)$.

Until this point the Krein space structure of $\mathcal{H}$, the domain of $C$, was unnecessary. However, Section 4 is devoted to consider a minimization problem among the indefinite least-squares solutions of $C x=y$. A minimal least-squares solution (MILSS) of $C x=y$ is a vector $w \in u_{y}+N\left(C^{\#} C\right)$ such that

$$
[w, w]=\min _{u \in u_{y}+N\left(C \#_{C}\right)}[u, u]
$$

If the ILSP associated to $C x=y$ admits solutions, in order to guarantee the existence of a MILSS of $C x=y$ it is necessary and sufficient that $N\left(C^{\#} C\right)$ is $J$-nonnegative and that the affine manifold $u_{y}+N\left(C^{\#} C\right)$ intersects $N\left(C^{\#} C\right)^{[\perp]}$, see Proposition 4.1. If it is also assumed that $N\left(C^{\#} C\right)$ and $R(C)$ are pseudo-regular subspaces of $\mathcal{H}$ and $\mathcal{K}$, respectively, then the set of MILSS can be computed in terms of the $J$-normal projections onto these subspaces and the Moore-Penrose inverse of $C$, see Theorem 4.3.

Finally, in Section 5 the operators used in Theorem 4.3 to describe the MILSS of $C x=y$ are shown to be a family of generalized inverses of a fixed operator $C^{\prime}$ with regular range.

## 2. Preliminaries

Along this work $\mathcal{H}$ denotes a complex (separable) Hilbert space. If $\mathcal{K}$ is another Hilbert space then $L(\mathcal{H}, \mathcal{K})$ is the algebra of bounded linear operators from $\mathcal{H}$ into $\mathcal{K}$ and $L(\mathcal{H})=L(\mathcal{H}, \mathcal{H})$.

If $T \in L(\mathcal{H}, \mathcal{K})$ then $R(T)$ stands for its range and $N(T)$ for its nullspace.
Given two closed subspaces $\mathcal{S}$ and $\mathcal{T}$ of a Hilbert space $\mathcal{H}, \mathcal{S} \dot{\mathcal{T}}$ denotes the direct sum of them. Moreover, $\mathcal{S} \oplus \mathcal{T}$ stands for their (direct) orthogonal sum and $\mathcal{S} \ominus \mathcal{T}:=\mathcal{S} \cap(\mathcal{S} \cap \mathcal{T})^{\perp}$.

If $\mathcal{H}=\mathcal{S} \dot{+}, P_{\mathcal{S} / / \mathcal{T}}$ denotes the (unique, bounded) projection onto $\mathcal{S}$ along $\mathcal{T}$. In the particular case of $\mathcal{T}=\mathcal{S}^{\perp}$, the orthogonal projection onto $\mathcal{S}$ is denoted by $P_{\mathcal{S}}$.

In what follows we present the standard notation and some basic results on Krein spaces. For a complete exposition on the subject see $[6,2,1]$.

Given a Krein space $(\mathcal{H},[]$,$) with a fundamental decomposition \mathcal{H}=\mathcal{H}_{+} \dot{+} \mathcal{H}_{-}$, the direct (orthogonal) sum of the Hilbert spaces $\left(\mathcal{H}_{+},[],\right)$and $\left(\mathcal{H}_{-},-[],\right)$is denoted by $(\mathcal{H},\langle\rangle$,$) .$

Observe that the inner products of $\mathcal{H}$ are related by means of a fundamental symmetry, i.e. a unitary selfadjoint operator $J \in L(\mathcal{H})$ which satisfies:

$$
[x, y]=\langle J x, y\rangle, \quad x, y \in \mathcal{H}
$$

If $\mathcal{H}$ and $\mathcal{K}$ are Krein spaces, $L(\mathcal{H}, \mathcal{K})$ stands for the vector space of linear transformations which are bounded with respect to the associated Hilbert spaces $\left(\mathcal{H},\langle,\rangle_{\mathcal{H}}\right)$ and $\left(\mathcal{K},\langle,\rangle_{\mathcal{K}}\right)$. Given $T \in L(\mathcal{H}, \mathcal{K})$, the $J$-adjoint operator of $T$ is defined by $T^{\#}=J_{\mathcal{H}} T^{*} J_{\mathcal{K}}$, where $J_{\mathcal{H}}$ and $J_{\mathcal{K}}$ are the fundamental symmetries associated to $\mathcal{H}$ and $\mathcal{K}$, respectively. An operator $T \in L(\mathcal{H})$ is $J$-selfadjoint if $T=T^{\#}$.

A vector $x \in \mathcal{H}$ is $J$-positive if $[x, x]>0$. A subspace $\mathcal{S}$ of $\mathcal{H}$ is $J$-positive if every $x \in \mathcal{S}, x \neq 0$, is a $J$-positive vector. $J$-nonnegative, $J$-neutral, $J$-negative and $J$-nonpositive vectors and subspaces are defined analogously.

Given a subspace $\mathcal{S}$ of a Krein space $\mathcal{H}$, the $J$-orthogonal subspace to $\mathcal{S}$ is defined by

$$
\mathcal{S}^{[\perp]}=\{x \in \mathcal{H}:[x, s]=0, \text { for every } s \in \mathcal{S}\} .
$$

The isotropic part of $\mathcal{S}, \mathcal{S}^{\circ}:=\mathcal{S} \cap \mathcal{S}^{[\perp]}$ can be a non-trivial subspace. It holds that

$$
\mathcal{H}=\overline{\mathcal{S}+\mathcal{S}^{[\perp]}} \oplus J\left(\mathcal{S}^{\circ}\right)
$$

see [2, Prop. 1.7.6]. A subspace $\mathcal{S}$ of $\mathcal{H}$ is $J$-non-degenerated if $\mathcal{S} \cap \mathcal{S}^{[\perp]}=\{0\}$. Otherwise, it is a $J$-degenerated subspace of $\mathcal{H}$.

A (closed) subspace $\mathcal{S}$ of $\mathcal{H}$ is regular if $\mathcal{S} \dot{+} \mathcal{S}^{[\perp]}=\mathcal{H}$. Equivalently, $\mathcal{S}$ is regular if and only if there exists a (unique) $J$-selfadjoint projection $E$ onto $\mathcal{S}$, see e.g. [2, Thm. 1.7.16].

On the other hand, a closed subspace $\mathcal{S}$ of $\mathcal{H}$ is called pseudo-regular if the algebraic sum $\mathcal{S}+\mathcal{S}^{[\perp]}$ is closed. Equivalently, $\mathcal{S}$ is pseudo-regular if there exists a regular subspace $\mathcal{M}$ such that $\mathcal{S}=\mathcal{S}^{\circ}[\dot{+}] \mathcal{M}$, where [ $\dot{[ }]$ stands for the $J$-orthogonal direct sum of the subspaces, see [9].

The importance of pseudo-regular subspaces lies in the fact that they enable to generalize some Pontryagin spaces arguments to general Krein spaces. They have also been used as a technical tool for the study of spectral functions (and distributions) for particular classes of operators in Krein spaces [10,11,17,18,22] and to extend the Beurling-Lax theorem for shifts in indefinite metric spaces [3,4].

Also, $\mathcal{S}$ is pseudo-regular if and only if $\mathcal{S}$ is the range of a $J$-normal projection, i.e. if there exists a projection $Q \in L(\mathcal{H})$ with $R(Q)=\mathcal{S}$ such that $Q Q^{\#}=Q^{\#} Q$, see [19, Thm. 4.3]. In particular, given a pseudo-regular subspace $\mathcal{S}, Q_{0}=P_{\mathcal{S} / / \mathcal{S}^{[ \lrcorner]} \ominus \mathcal{S}^{\circ}+J\left(\mathcal{S}^{\circ}\right)}$ is a $J$-normal projection onto $\mathcal{S}$. However, if $\mathcal{S}^{\circ} \neq\{0\}$ then there are infinitely many $J$-normal projections $Q$ satisfying $R(Q)=\mathcal{S}$. In what follows, $\mathcal{Q}_{\mathcal{S}}$ stands for the set of $J$-normal projections onto the pseudo-regular subspace $\mathcal{S}$, i.e.

$$
\mathcal{Q}_{\mathcal{S}}=\left\{Q \in L(\mathcal{H}): Q^{2}=Q, Q Q^{\#}=Q^{\#} Q \text { and } R(P)=\mathcal{S}\right\} .
$$

The next is a technical remark that will be frequently used along this work. It shows that, given a vector $y \in \mathcal{S}+\mathcal{S}^{[\perp]}$, the $J$-normal projections onto $\mathcal{S}$ provide the different decompositions of $y$ as a sum of a vector in $\mathcal{S}$ and a vector in $\mathcal{S}^{[\perp]}$, i.e. if $Q \in \mathcal{Q}_{\mathcal{S}}$ then

$$
y=Q y+(I-Q) y, \quad \text { where } \quad Q y \in \mathcal{S} \quad \text { and } \quad(I-Q) y \in \mathcal{S}^{[\perp]}
$$

Remark 2.1. If $\mathcal{S}$ is a pseudo-regular subspace of $\mathcal{H}$ and $y \in \mathcal{S}+\mathcal{S}^{[\perp]}$, given any $Q \in \mathcal{Q}_{\mathcal{S}}$, then

$$
Q^{\#}(I-Q) y=0 .
$$

Indeed, if $P=Q(I-Q)^{\#}$ then $R(P)=\mathcal{S} \cap N\left(Q^{\#}\right)=\mathcal{S} \cap \mathcal{S}^{[\perp]}=\mathcal{S}^{\circ}$ and $N\left(P^{\#}\right)=R(P)^{[\perp]}=\left(\mathcal{S}^{\circ}\right)^{[\perp]}=$ $\mathcal{S}+\mathcal{S}^{[\perp]}$. Therefore, if $y \in \mathcal{S}+\mathcal{S}^{[\perp]}$ then $Q^{\#}(I-Q) y=P^{\#} y=0$. In particular, $(I-Q) y \in N\left(Q^{\#}\right)=$ $R(Q)^{[\perp]}=\mathcal{S}^{[\perp]}$.

The following results belong to [19]. Their statements are included in order to make the paper selfcontained.

Proposition 2.2. A bounded projection $Q$ acting on $\mathcal{H}$ is J-normal if and only if there exist a J-selfadjoint projection $E \in L(\mathcal{H})$ and a projection $P \in L(\mathcal{H})$ satisfying $P P^{\#}=P^{\#} P=0$ such that

$$
Q=E+P
$$

The projections $E$ and $P$ are uniquely determined by $Q$. More precisely, $E=Q Q^{\#}$ and $P=Q\left(I-Q^{\#}\right)$.

Projections $P \in L(\mathcal{H})$ satisfying $P P^{\#}=P^{\#} P=0$ were previously considered in [17,11], in connection with neutral dual companions. If $\mathcal{S}$ is a fixed (closed) $J$-neutral subspace of $\mathcal{H}$, a neutral dual companion of $\mathcal{S}$ is another (closed) $J$-neutral subspace $\mathcal{T}$ of $\mathcal{H}$ such that $\mathcal{H}=\mathcal{S} \dot{+} \mathcal{T}^{[\perp]}$ holds. If $\mathcal{T}$ is a neutral dual companion of $\mathcal{S}$ then also $\mathcal{H}=\mathcal{T}+\mathcal{S}^{[\perp]}$ holds. So, the pair of subspaces $(\mathcal{S}, \mathcal{T})$ is called a neutral dual pair. Note that in this case $\mathcal{S}+\mathcal{T}$ is a regular subspace of $\mathcal{H}$.

A $J$-neutral subspace $\mathcal{N}$ of $\mathcal{H}$ is said to be a hypermaximal $J$-neutral subspace if it is simultaneously both maximal $J$-nonnegative and maximal $J$-nonpositive. Equivalently, $\mathcal{N}$ is a hypermaximal $J$-neutral subspace if and only if $\mathcal{N}=\mathcal{N}^{[\perp]}$, see [2, Prop. 1.4.19].

Given $C \in L(\mathcal{H}, \mathcal{K})$, its restriction $\left.C\right|_{N(C)^{\perp}}: N(C)^{\perp} \rightarrow R(C)$ admits a linear inverse $\left(\left.C\right|_{N(C)^{\perp}}\right)^{-1}:$ $R(C) \rightarrow N(C)^{\perp}$. Then, the Moore-Penrose inverse of $C$ is the linear operator $C^{\dagger}: R(C)+R(C)^{\perp} \rightarrow \mathcal{H}$ defined by

$$
C^{\dagger} y=\left\{\begin{array}{cl}
\left(\left.C\right|_{N(C)^{\perp}}\right)^{-1} y & \text { if } y \in R(C) \\
0 & \text { if } y \in R(C)^{\perp}
\end{array}\right.
$$

Note that $C^{\dagger}$ is densely-defined on $\mathcal{K}$, and it is well-known that $C^{\dagger} \in L(\mathcal{K}, \mathcal{H})$ if and only if $R(C)$ is closed.
Hereafter, given two Hilbert spaces $\mathcal{H}$ and $\mathcal{K}$, let $C R(\mathcal{H}, \mathcal{K})$ denotes the set of bounded closed-range operators from $\mathcal{H}$ into $\mathcal{K}$. The following are some properties of the Moore-Penrose inverse of a closed-range operator:

Proposition 2.3. Given $C \in C R(\mathcal{H}, \mathcal{K})$,

1. $C C^{\dagger}=P_{R(C)}$ and $C^{\dagger} C=P_{N(C)^{\perp}}$, the orthogonal projections onto $R(C)$ and $N(C)^{\perp}$, respectively. In particular, $C C^{\dagger} C=C$ and $C^{\dagger} C C^{\dagger}=C^{\dagger}$.
2. $C^{*} \in C R(\mathcal{K}, \mathcal{H})$ and $\left(C^{*}\right)^{\dagger}=\left(C^{\dagger}\right)^{*}$.
3. If $U \in L(\mathcal{K}), V \in L(\mathcal{H})$ are unitary operators, then $(U C V)^{\dagger}=V^{*} C^{\dagger} U^{*}$.

The Moore-Penrose inverse has been thoroughly studied along the years, see e.g. [5] for a complete exposition on this subject.

As a consequence of Proposition 2.3, if $\mathcal{H}$ and $\mathcal{K}$ are two Krein spaces and $C \in C R(\mathcal{H}, \mathcal{K})$ then $C^{\#} \in$ $C R(\mathcal{K}, \mathcal{H})$ and $\left(C^{\#}\right)^{\dagger}=\left(C^{\dagger}\right)^{\#}$.

## 3. Indefinite least-squares problems

Along this work, the following indefinite least-squares problem is considered: Let $\mathcal{H}$ and $\mathcal{K}$ be two Krein spaces with fundamental symmetries $J_{\mathcal{H}}$ and $J_{\mathcal{K}}$, respectively. Given an operator $C \in C R(\mathcal{H}, \mathcal{K})$ and a vector $y \in \mathcal{K}$, find $u \in \mathcal{H}$ such that

$$
\begin{equation*}
[y-C u, y-C u]_{\mathcal{K}}=\min _{x \in \mathcal{H}}[y-C x, y-C x]_{\mathcal{K}} . \tag{3.1}
\end{equation*}
$$

The next lemma shows necessary and sufficient conditions for the existence of indefinite least-squares solutions (ILSS) of the equation $C x=y$. A proof can be found in [6, Theorem 8.4] or in [12, Lemma 3.1].

Lemma 3.1. Let $C \in C R(\mathcal{H}, \mathcal{K})$ and $y \in \mathcal{K}$. Then, $u \in \mathcal{H}$ is an ILSS of the equation $C x=y$ if and only if $R(C)$ is $J_{\mathcal{K}}$-nonnegative and $y-C u \in R(C)^{[\perp]}$.

Hence, in order to have a well-posed indefinite least-squares problem it is necessary that $y \in R(C)+$ $R(C)^{[\perp]}$. Note that the set of admissible points $R(C)+R(C)^{[\perp]}$ is always dense in $\left(R(C)^{\circ}\right)^{[\perp]}$.

Proposition 3.2. Let $C \in C R(\mathcal{H}, \mathcal{K})$. Then, $C x=y$ admits an ILSS for every $y \in\left(R(C)^{\circ}\right)^{[\perp]}$ if and only if $R(C)$ is a $J_{\mathcal{K}}$-nonnegative pseudo-regular subspace of $\mathcal{K}$.

Proof. Note that $C x=y$ admits an ILSS for every $y \in\left(R(C)^{\circ}\right)^{[\perp]}$ if and only if $\left(R(C)^{\circ}\right)^{[\perp]} \subseteq R(C)+R(C)^{[\perp]}$ and $R(C)$ is $J_{\mathcal{K}}$-nonnegative. But

$$
\left(R(C)^{\circ}\right)^{[\perp]}=\overline{R(C)+R(C)^{[\perp]}}
$$

and the equivalence follows.
In particular, $C x=y$ admits an ILSS for every $y \in \mathcal{K}$ if and only if $R(C)$ is a uniformly $J$-positive subspace of $\mathcal{K}$, see also [12, Proposition 3.2].

Before describing the indefinite least-squares solutions of $C x=y$, observe that the minimum value of $L(x)=[y-C x, y-C x], x \in \mathcal{H}$, is attained at the projections (by means of normal projectors) of $y$ onto $R(C)$.

Lemma 3.3. Given $C \in C R(\mathcal{H}, \mathcal{K})$ such that $R(C)$ is a J-nonnegative pseudo-regular subspace of $\mathcal{K}$ and $y \in R(C)+R(C)^{[\perp]}$,

$$
\min _{x \in \mathcal{H}}[y-C x, y-C x]=[(I-Q) y,(I-Q) y],
$$

where $Q \in L(\mathcal{K})$ is any J-normal projection onto $R(C)$.
Proof. Since $R(C)$ is pseudo-regular, by [19, Thm. 4.3] there exists a $J$-normal projection $Q \in L(\mathcal{K})$ onto $R(C)$. Then, for any $x \in \mathcal{H}$,

$$
\begin{align*}
{[y-C x, y-C x] } & =[(y-Q y)+(Q y-C x),(y-Q y)+(Q y-C x)] \\
& =[(I-Q) y,(I-Q) y]+2 \operatorname{Re}[(I-Q) y, Q y-C x]+[Q y-C x, Q y-C x] \\
& \geq[(I-Q) y,(I-Q) y]+2 \operatorname{Re}[(I-Q) y, Q y-C x], \tag{3.2}
\end{align*}
$$

because $Q y-C x \in R(C)$ which is a $J_{\mathcal{K}}$-nonnegative subspace. Furthermore, by Remark 2.1, $y \in R(C)+$ $R(C)^{[\perp]}$ implies that $Q^{\#}(I-Q) y=0$ and

$$
[(I-Q) y, Q y-C x]=[(I-Q) y, Q(y-C x)]=\left[Q^{\#}(I-Q) y, y-C x\right]=0
$$

Therefore,

$$
[y-C x, y-C x] \geq[(I-Q) y,(I-Q) y] .
$$

Also, note that the pseudo-regularity of $R(C)$ is equivalent to the boundedness of the Moore-Penrose inverse of $C^{\#} C$ :

Lemma 3.4. Given $C \in C R(\mathcal{H}, \mathcal{K}), R(C)$ is pseudo-regular if and only if $R\left(C^{\#} C\right)$ is closed.
Proof. Since $R(C)$ is closed, note that $R\left(C^{\#} C\right)$ is closed if and only if $R(C)+N\left(C^{\#}\right)=R(C)+R(C)^{[\perp]}$ is closed, see [16, Corollary 2.5]. Thus, $R\left(C^{\#} C\right)$ is closed if and only if $R(C)$ is a pseudo-regular subspace of $\mathcal{K}$.

Given $C \in C R(\mathcal{H}, \mathcal{K})$ and $y \in R(C)+R(C)^{[\perp]}$, observe that $C^{\#} y \in R\left(C^{\#} C\right)$. Then,

$$
\begin{equation*}
u_{y}:=\left(C^{\#} C\right)^{\dagger} C^{\#} y \tag{3.3}
\end{equation*}
$$

is a solution of the normal equation:

$$
\begin{equation*}
C^{\#}(C x-y)=0 \tag{3.4}
\end{equation*}
$$

In particular, $u_{y}$ is the unique solution of the normal equation in $N\left(C^{\#} C\right)^{\perp}$ and the set of solutions of (3.4) is the affine manifold

$$
u_{y}+N\left(C^{\#} C\right)
$$

The following is the main result of this section. It shows that the solutions of the ILSP associated to the equation $C x=y$ are the solutions of the normal equation $C^{\#}(C x-y)=0$, but it also characterizes them in terms of the $J$-normal projections onto $R(C)$.

Theorem 3.5. Given $C \in C R(\mathcal{H}, \mathcal{K})$, if $R(C)$ is a J-nonnegative pseudo-regular subspace of $\mathcal{K}$ and $y \in$ $R(C)+R(C)^{[\perp]}$, the following conditions are equivalent:

1. $u \in \mathcal{H}$ is an ILSS of $C x=y$;
2. $u \in \mathcal{H}$ is a solution of the normal equation $C^{\#}(C x-y)=0$;
3. $C u-Q y \in R(C)^{\circ}$ for any J-normal projection $Q$ onto $R(C)$.

If $y \notin R(C)$ the above conditions are also equivalent to:
4. there exists a J-normal projection $Q$ onto $R(C)$ such that $C u=Q y$.

Moreover, the set of ILSS of $C x=y$ coincides with the affine manifold

$$
u_{y}+N\left(C^{\#} C\right),
$$

where $u_{y}=\left(C^{\#} C\right)^{\dagger} C^{\#} y$.

Proof. By Lemma 3.1, assuming the $J$-nonnegativity of $R(C), u$ is an ILSS of $C x=y$ if and only if $y-C u \in R(C)^{[\perp]}=N\left(C^{\#}\right)$. Then, the equivalence 1. $\leftrightarrow 2$. follows.
2. $\leftrightarrow$ 3.: By Remark 2.1, $(I-Q) y \in R(C)^{[\perp]}=N\left(C^{\#}\right)$ for any $J$-normal projection $Q \in L(\mathcal{K})$ onto $R(C)$. Hence, $u \in \mathcal{H}$ is a solution of $C^{\#}(C x-y)=0$ if and only if $C^{\#}(C u-Q y)=0$, or equivalently, $C u-Q y \in R(C)^{\circ}$.
2. $\leftrightarrow 4$ 4: Assume that $y \notin R(C)$ and $u$ is a solution of $C \#(C x-y)=0$. Then, $y=C u+z$ with $z \in$ $R(C)^{[\perp]} \backslash R(C)$. So, there exists a regular subspace $\mathcal{T}$ of $R(C)^{[\perp]}$ such that $z \in \mathcal{T}$ and $R(C)^{[\perp]}=\mathcal{T}[\dot{+}] R(C)^{\circ}$. Also, consider a regular subspace $\mathcal{M}$ of $R(C)$ such that $R(C)=\mathcal{M}[\dot{+}] R(C)^{\circ}$. Then, note that $R(C)^{\circ}$ is a $J$-neutral subspace of the Krein space $\mathcal{K}^{\prime}=(\mathcal{M}+\mathcal{T})^{[\perp]}$. So, it is well-known that there exists a neutral dual companion $\mathcal{N}$ of $R(C)^{\circ}$ in $\mathcal{K}^{\prime}$, see [11]. Furthermore, $R(C)^{\circ}$ is a hypermaximal neutral subspace of $\mathcal{K}^{\prime}$ [2, Prop. 1.4.19] because

$$
\begin{aligned}
\left(R(C)^{\circ}\right)^{[\perp]_{\mathcal{K}^{\prime}}} & =\left(R(C)^{\circ}\right)^{[\perp]} \cap \mathcal{K}^{\prime} \\
& =\left(R(C)+R(C)^{[\perp]}\right) \cap(\mathcal{M}+\mathcal{T})^{[\perp]}= \\
& =\left(\mathcal{M}+\mathcal{T}+R(C)^{\circ}\right) \cap(\mathcal{M}+\mathcal{T})^{[\perp]}=R(C)^{\circ} .
\end{aligned}
$$

Thus, $(\mathcal{M}+\mathcal{T})^{[\perp]}=\mathcal{K}^{\prime}=\mathcal{N} \dot{+}\left(R(C)^{\circ}\right)^{[\perp]_{\mathcal{K}^{\prime}}}=\mathcal{N} \dot{+} R(C)^{\circ}$ and the following decomposition of $\mathcal{K}$ holds:

$$
\mathcal{K}=\mathcal{M}[\dot{+}]\left(R(C)^{\circ} \dot{+} \mathcal{N}\right)[\dot{+}] \mathcal{T} .
$$

Given the projection $Q=P_{R(C) / / \mathcal{T}+\mathcal{N}} \in L(\mathcal{K})$, it is easy to see that $Q^{\#}=P_{\mathcal{M}+\mathcal{N} / / R(C)}{ }^{[ \lrcorner]}$. Therefore, $Q$ is $J$-normal and it satisfies $Q y=Q(C u+z)=C u$.

Conversely, if $C u=Q y$ for some $J$-normal projection $Q \in L(\mathcal{K})$ onto $R(C)$ then, by Remark 2.1, $y-C u=(I-Q) y \in R(C)^{[\perp]}=N\left(C^{\#}\right)$. Therefore, $C^{\#}(C u-y)=0$.

Finally, recall that the set of solutions of the normal equation (which in this case coincides with the ILSS of $C x=y$ ) is the affine manifold $u_{y}+N\left(C^{\#} C\right)$, where $u_{y}=\left(C^{\#} C\right)^{\dagger} C^{\#} y$.

Remark 3.6. Given $C \in C R(\mathcal{H}, \mathcal{K})$ with pseudo-regular range $R(C)$, the equivalences 2. $\leftrightarrow 3$. $\leftrightarrow 4$. in Theorem 3.5 holds independently of the (semi)definiteness of the range. Hence, Theorem 3.5 also characterizes the solutions of the normal equation $C^{\#}(C x-y)=0$ for $C \in C R(\mathcal{H}, \mathcal{K})$ with an arbitrary pseudo-regular range $R(C)$.

If $C \in C R(\mathcal{H}, \mathcal{K})$ and $R(C)$ is pseudo-regular, the set $\mathcal{Q}_{R(C)}$ of $J$-normal projections onto $R(C)$ is related to a family of inner inverses of $C$, where $X \in L(\mathcal{K}, \mathcal{H})$ is an inner inverse of $C$ if $C X C=C$. Let $\mathcal{I}$ denote the set of solutions $D \in L(\mathcal{K}, \mathcal{H})$ of the equations

$$
\begin{equation*}
C X C=C, \quad(C X)^{\#} C X=C X(C X)^{\#} . \tag{3.5}
\end{equation*}
$$

Then, $D \in \mathcal{I}$ if and only if there exist $Q \in \mathcal{Q}_{R(C)}$ and $T \in L(\mathcal{K}, \mathcal{H})$ with $R(T) \subseteq N(C)$ such that

$$
D=C^{\dagger} Q+T
$$

Indeed, if $D \in L(\mathcal{K}, \mathcal{H})$ is a solution of (3.5) then $Q:=C D \in \mathcal{Q}_{R(C)}$ and $C^{\dagger} Q=C^{\dagger} C D=P_{N(C)^{\perp}} D$. So, $T:=P_{N(C)} D \in L(\mathcal{K}, \mathcal{H})$ satisfies $R(T) \subseteq N(C)$ and $D=C^{\dagger} Q+T$.

Conversely, given $Q \in \mathcal{Q}_{R(C)}$ and $T \in L(\mathcal{K}, \mathcal{H})$ with $R(T) \subseteq N(C)$, consider $D:=C^{\dagger} Q+T$. Then, $C D=C C^{\dagger} Q=P_{R(C)} Q=Q$ implies that $D$ is a solution of (3.5).

The following result describes the solutions of the ILSP associated to $C x=y$ in terms of these generalized inverses.

Proposition 3.7. Given $C \in C R(\mathcal{H}, \mathcal{K})$, if $R(C)$ is a J-nonnegative pseudo-regular subspace of $\mathcal{K}$ and $y \in$ $R(C)+R(C)^{[\perp]}$, the following conditions are equivalent:

1. $u \in \mathcal{H}$ is an ILSS of $C x=y$;
2. $D y-u \in N\left(C^{\#} C\right)$ for any solution $D \in L(\mathcal{K}, \mathcal{H})$ of (3.5).

If $y \notin R(C)$ the above conditions are also equivalent to:
3. there exists a solution of (3.5) such that $D y=u$.

Proof. 1. $\leftrightarrow$ 2.: Given a solution $D \in L(\mathcal{K}, \mathcal{H})$ of (3.5), consider $Q \in \mathcal{Q}_{R(C)}$ and $T \in L(\mathcal{K}, \mathcal{H})$ with $R(T) \subseteq N(C)$ such that $D=C^{\dagger} Q+T$. For $u \in \mathcal{H}$, follows that $D y-u \in N\left(C^{\#} C\right)$ if and only if $C^{\#}(Q y-C u)=0$, or equivalently, $Q y-C u \in R(C)^{\circ}$. Thus the equivalence follows from Theorem 3.5.

1. $\leftrightarrow$ 3.: Given $y \in\left(R(C)+R(C)^{[\perp]}\right) \backslash R(C)$, suppose that $u=D y$ where $D \in L(\mathcal{K}, \mathcal{H})$ is a solution of (3.5). It is easy to see that $Q=C D$ is a $J$-normal projection with $R(Q)=R(C)$. Furthermore, $C u=C D y=Q y$. By Theorem 3.5, this implies that $u$ is an ILSS of $C x=y$.

Conversely, if $u \in \mathcal{H}$ is an ILSS of $C x=y$, Theorem 3.5 states that $C u=Q y$ for some $J$-normal projection $Q \in L(\mathcal{K})$. Then, $u=C^{\dagger} Q y+w$, where $w \in N(C)$. Consider $T \in L(\mathcal{K}, \mathcal{H})$ with $R(T) \subseteq N(C)$ such that $T y=w$ and define $D=C^{\dagger} Q+T$. Thus, $D$ is a solution of (3.5) and $D y=C^{\dagger} Q y+T y=C^{\dagger} Q y+w=u$.

In the following it is shown that the ILSP associated to the equation $C x=y$ can be rewritten as an ILSP associated to another equation $C^{\prime} x=y$, where $C^{\prime} \in C R(\mathcal{H}, \mathcal{K})$ and $R\left(C^{\prime}\right)$ is a uniformly $J$-positive subspace of $\mathcal{K}$. But this is only true if the vector $y \in \mathcal{K}$ is admissible for the ILSP associated to the equation $C x=y$ (recall that the ILSP associated to the equation $C^{\prime} x=y$ is always well-posed).

If $R(C)$ is a $J_{\mathcal{K}}$-nonnegative pseudo-regular subspace of $\mathcal{K}$ and $y \in R(C)+R(C)^{[\perp]}$, then

$$
u \in \mathcal{H} \text { is an ILSS of } C x=y \quad \Leftrightarrow \quad u \in \mathcal{H} \text { is an } \operatorname{ILSS} \text { of }(E C) x=y,
$$

where $E=Q Q^{\#}$ and $Q$ is any $J$-normal projection onto $R(C)$.
First, observe that $R(E C)=E(R(C)+N(E))=R(E)$ since $R(E) \subset R(C)$. Hence, $R(E C)$ is uniformly $J_{\mathcal{K}}$-positive and the indefinite least-squares problem associated to the equation $E C x=y$ is well-posed. Then, by Theorem 3.5, $u \in \mathcal{H}$ is an ILSS of $C x=y$ if and only if $C u-Q y \in R(C)^{\circ}$. But, $R(C)^{\circ} \subset N(E)$ implies that

$$
E C u=E(C u-Q y)+E Q y=E y
$$

and $E$ is the $J$-selfadjoint projection onto $R(E C)$. Then, $u$ is an ILSS of $E C x=y$, see e.g. [12, Prop. 3.2].
Proposition 3.8. Let $C \in C R(\mathcal{H}, \mathcal{K})$ be such that $R(C)$ is a pseudo-regular subspace of $\mathcal{K}$. Then, $C^{\prime}=$ $C P_{N(C \# C)^{\perp}} \in C R(\mathcal{H}, \mathcal{K})$ has regular range and, if $y \in R(C)+R(C)^{[\perp]}$,

$$
u \in \mathcal{H} \text { is an ILSS of } C x=y \quad \Leftrightarrow \quad u \in \mathcal{H} \text { is an ILSS of } C^{\prime} x=y .
$$

Proof. Given $C \in C R(\mathcal{H}, \mathcal{K})$, consider the operator $E_{0}:=C\left(C^{\#} C\right)^{\dagger} C^{\#}$. By Lemma 3.4, $E_{0} \in L(\mathcal{K})$ and it is easy to check that $E_{0}^{2}=E_{0}$. As a consequence of Proposition 2.3 the projection $E_{0}$ is $J$-selfadjoint, and $R\left(E_{0}\right)$ is obviously contained in $R(C)$. Then, $R\left(E_{0} C\right)=E_{0}\left(R(C)+N\left(E_{0}\right)\right)=R\left(E_{0}\right)$ and note that

$$
E_{0} C=C\left(C^{\#} C\right)^{\dagger} C^{\#} C=C P_{N\left(C Z^{\#} C\right)^{\perp}}=C^{\prime}
$$

Therefore, $R\left(C^{\prime}\right)=R\left(E_{0} C\right)=R\left(E_{0}\right)$ is regular.

Also, $R\left(E_{0}\right) \cap R(C)^{\circ}=\{0\}$ because $R(C)^{\circ} \subseteq R(C)^{[\perp]}=N\left(C^{\#}\right) \subseteq N\left(E_{0}\right)$. Since $C=C^{\prime}+C P_{N(C \# C)}$ and the range of $C P_{N\left(C \#_{C)}\right)}$ coincides with $R(C)^{\circ}$, it follows that

$$
R(C)=R\left(C P_{N(C \# C)^{\perp}}\right)+R(C)^{\circ}=R\left(E_{0} C\right)+R(C)^{\circ}=R\left(E_{0}\right) \dot{+} R(C)^{\circ} .
$$

Therefore, $E_{0}$ is a $J$-selfadjoint projection onto a regular complement of $R(C)^{\circ}$ in $R(C)$ and, by [19, Thm. 6.9] there exist (at least) a $J$-normal projection $Q \in L(\mathcal{K})$ such that $E_{0}=Q Q^{\#}$. Finally, if $y \in R(C)+R(C)^{[\perp]}$ the discussion above shows that the ILSS of $C x=y$ and $C^{\prime} x=y$ coincide.

## 4. Minimizers among indefinite least-squares solutions

The following paragraphs are devoted to consider a minimization problem among the indefinite leastsquares solutions of $C x=y$, where $C \in C R(\mathcal{H}, \mathcal{K})$ and $y \in R(C)+R(C)^{[\perp]}$.

Definition 1. A vector $w \in \mathcal{H}$ is a minimal least-squares solution (hereafter MILSS) of $C x=y$ if $w$ is an ILSS of $C x=y$ and

$$
[w, w]_{\mathcal{H}} \leq[u, u]_{\mathcal{H}}, \quad \text { for every ILSS } u \text { of } C x=y
$$

It follows from Theorem 3.5 that, if $R(C)$ is a pseudo-regular $J_{\mathcal{K}}$-nonnegative subspace of $\mathcal{K}$ and $y \in$ $R(C)+R(C)^{[\perp]}$, the set of ILSS of $C x=y$ coincides with

$$
u_{y}+N\left(C^{\#} C\right),
$$

where $u_{y}=\left(C^{\#} C\right)^{\dagger} C^{\#} y$. So, $w \in \mathcal{H}$ is a MILSS of $C x=y$ if and only if

$$
\begin{equation*}
[w, w]=\min _{z \in N(C \# C)}\left[u_{y}+z, u_{y}+z\right] . \tag{4.1}
\end{equation*}
$$

Thus, if $P_{N(C \# C)}$ is the orthogonal projection onto $N\left(C^{\#} C\right)$ and $w=u_{y}+z_{w}$ is the orthogonal decomposition of $w$ according to $\mathcal{H}=N\left(C^{\#} C\right)^{\perp} \oplus N\left(C^{\#} C\right)$, note that (4.1) can be rewritten as

$$
\begin{aligned}
{\left[u_{y}+z_{w}, u_{y}+z_{w}\right] } & =\min _{z \in N(C \# C)}\left[u_{y}+z, u_{y}+z\right] \\
& =\min _{x \in \mathcal{H}}\left[u_{y}+P_{N(C \# C)} x, u_{y}+P_{N(C \# C)} x\right] .
\end{aligned}
$$

Hence, if $w=u_{y}+z_{w} \in u_{y}+N\left(C^{\#} C\right)$,

$$
\begin{equation*}
w \text { is a MILSS of } C x=y \quad \Leftrightarrow \quad z_{w} \text { is an ILSS of } P_{N(C \# C)} x=-u_{y} . \tag{4.2}
\end{equation*}
$$

By Lemma 3.1, the existence of an ILSS of $P_{N\left(C \#_{C}\right)} x=-u_{y}$ is equivalent to

$$
u_{y} \in N\left(C^{\#} C\right)+N\left(C^{\#} C\right)^{[\perp]}
$$

and the $J_{\mathcal{H}}$-nonnegativity of $N\left(C^{\#} C\right)$. Therefore,
Proposition 4.1. Let $C \in C R(\mathcal{H}, \mathcal{K})$ be such that $R(C)$ is a $J_{\mathcal{K}}$-nonnegative pseudo-regular subspace of $\mathcal{K}$ and consider $y \in R(C)+R(C)^{[\perp]}$. Then, there exists a MILSS $w \in \mathcal{H}$ of $C x=y$ if and only if $N\left(C^{\#} C\right)$ is $J_{\mathcal{H}}$-nonnegative and $u_{y} \in N\left(C^{\#} C\right)+N\left(C^{\#} C\right)^{[\perp]}$. In this case, the set of MILSS of $C x=y$ coincides with

$$
\left(u_{y}+N\left(C^{\#} C\right)\right) \cap N\left(C^{\#} C\right)^{[\perp]} .
$$

Proof. The equivalence between the existence of a MILSS for $C x=y$ and the conditions on $N\left(C^{\#} C\right)$ and $u_{y}$ follows from the discussion above. Also, note that $u_{y} \in N\left(C^{\#} C\right)+N\left(C^{\#} C\right)^{[\perp]}$ if and only if

$$
\left(u_{y}+N\left(C^{\#} C\right)\right) \cap N\left(C^{\#} C\right)^{[\perp]} \neq \varnothing .
$$

Now, assume that $w \in \mathcal{H}$ is a MILSS of $C x=y$. Then, there exists $z_{w} \in N\left(C^{\#} C\right)$ such that $w=u_{y}+z_{w}$ and $z_{w}$ is an ILSS of $P_{N\left(C \#_{C)}\right.} x=-u_{y}$. By Lemma 3.1, $-u_{y}-P_{N(C \# C)} z_{w} \in N\left(C^{\#} C\right)^{[\perp]}$. So,

$$
w=u_{y}+z_{w}=u_{y}+P_{N(C \# C)} z_{w} \in\left(u_{y}+N\left(C^{\#} C\right)\right) \cap N\left(C^{\#} C\right)^{[\perp]} .
$$

Conversely, suppose that $w \in\left(u_{y}+N\left(C^{\#} C\right)\right) \cap N\left(C^{\#} C\right)^{[\perp]}$. Then, $w$ is an ILSS of $C x=y$ because $w \in u_{y}+N\left(C^{\#} C\right)$. Also, there exists $z_{w} \in N\left(C^{\#} C\right)$ such that $w=u_{y}+z_{w}$. Furthermore, since

$$
-u_{y}-P_{N(C \# C)} z_{w}=-u_{y}-z_{w}=-w \in N\left(C^{\#} C\right)^{[\perp]},
$$

$z_{w} \in N\left(C^{\#} C\right)$ is an ILSS of $P_{N\left(C{ }^{\#} C\right)} x=-u_{y}$. So, (4.2) implies that $w=u_{y}+z_{w}$ is a MILSS of $C x=y$.
In the rest of this section it is assumed that $N\left(C^{\#} C\right)$ is a $J_{\mathcal{H}}$-nonnegative pseudo-regular subspace of $\mathcal{H}$, aiming to describe the set of MILSS of $C x=y$ in terms of $J$-normal projections.

Let $C \in C R(\mathcal{H}, \mathcal{K})$ be such that $R(C)$ is pseudo-regular and consider $y \in R(C)+R(C)^{[\perp]}$. Then, note that

$$
u_{y}=\left(C^{\#} C\right)^{\dagger} C^{\#} y=0 \quad \text { if and only if } \quad y \in R(C)^{[\perp]} .
$$

In this case, $u \in \mathcal{H}$ is an ILSS of $C x=y$ if and only if $u \in N\left(C^{\#} C\right)$. Moreover, by Proposition 4.1, $u \in \mathcal{H}$ is a MILSS of $C x=y$ if and only if $u \in N\left(C^{\#} C\right)^{\circ}$.

Lemma 4.2. Let $C \in C R(\mathcal{H}, \mathcal{K})$ be such that $R(C)$ is a $J_{\mathcal{K}}$-nonnegative pseudo-regular subspace of $\mathcal{K}$ and consider $y \in\left(R(C)+R(C)^{[\perp]}\right) \backslash R(C)^{[\perp]}$. Assume also that $N\left(C^{\#} C\right)$ is a $J_{\mathcal{H}}$-nonnegative pseudo-regular subspace of $\mathcal{H}$. Then, $w \in \mathcal{H}$ is a MILSS of $C x=y$ if and only if there exists $P \in \mathcal{Q}_{N\left(C \#_{C)}\right.}$ such that

$$
\begin{equation*}
w=(I-P) u_{y} . \tag{4.3}
\end{equation*}
$$

Proof. Given $C \in C R(\mathcal{H}, \mathcal{K})$ with $J_{\mathcal{K}}$-nonnegative pseudo-regular range $R(C)$, let $y \in\left(R(C)+R(C)^{[\perp]}\right) \backslash$ $R(C)^{[\perp]}$. By the above remark, $u_{y} \neq 0$.

If $w \in \mathcal{H}$ is a MILSS of $C x=y$, consider its orthogonal decomposition $w=u_{y}+z$, where $z \in N\left(C^{\#} C\right)$. Then, by (4.2), $z$ is an ILSS of the equation $P_{N(C \# C)} x=-u_{y}$. Also $u_{y} \in N\left(C^{\#} C\right)^{\perp}$ and, by Theorem 3.5, there exists $P \in \mathcal{Q}_{N(C \# C)}$ such that

$$
z=P_{N\left(C \#_{C}\right)} z=P\left(-u_{y}\right)=-P u_{y} .
$$

Thus, $w=u_{y}+z=u_{y}-P u_{y}=(I-P) u_{y}$ for some $P \in \mathcal{Q}_{N\left(C \#_{C)}\right.}$.
Conversely, if $w=(I-P) u_{y}$ for some $P \in \mathcal{Q}_{N\left(C{ }^{\#} C\right)}$ then, since $u_{y} \in N\left(C^{\#} C\right)+N\left(C^{\#} C\right)^{[\perp]}$,

$$
w=(I-P) P^{\#} u_{y}+(I-P)(I-P)^{\#} u_{y}=(I-P)(I-P)^{\#} u_{y},
$$

because, by Proposition 4.1,

$$
u_{y} \in R(P)+R(P)^{[\perp]}=R(P)+N\left(P^{\#}\right)=N\left((I-P) P^{\#}\right) .
$$

Then, $w \in N\left(C^{\#} C\right)^{[\perp]}$ and, by Proposition 4.1, $w$ is a MILSS of $C x=y$.

If $R(C)$ is a pseudo-regular subspace of $\mathcal{K}$, consider $E_{0}=C\left(C^{\#} C\right)^{\dagger} C^{\#}$. If $y \in R(C)+R(C)^{[\perp]}$ then $C u_{y}=E_{0} y$ and

$$
u_{y}=C^{\dagger} C u_{y}=C^{\dagger} E_{0} y
$$

because $u_{y} \in N\left(C^{\#} C\right)^{\perp} \subseteq N(C)^{\perp}$. Moreover, if $y \in\left(R(C)+R(C)^{[\perp]}\right) \backslash R(C)^{[\perp]}$, applying this identity in (4.3) it follows that if $w \in \mathcal{H}$ is a MILSS of $C x=y$ then there exists $P \in \mathcal{Q}_{N(C \# C)}$ such that

$$
w=(I-P) u_{y}=(I-P) C^{\dagger} E_{0} y
$$

Furthermore, following the construction made in the proof of Theorem 3.5, it is easy to see that there exists $Q_{0} \in \mathcal{Q}_{R(C)}$ such that $E_{0}=Q_{0}^{\#} Q_{0}$. Hence, by Remark 2.1, $Q_{0}^{\#}\left(I-Q_{0}\right) y=0$ and

$$
w=(I-P) C^{\dagger} E_{0} y=(I-P) C^{\dagger} Q_{0}^{\#} y
$$

Theorem 4.3. Let $C \in C R(\mathcal{H}, \mathcal{K})$ such that $R(C)$ is a $J_{\mathcal{K}}$-nonnegative pseudo-regular subspace of $\mathcal{K}$ and consider $y \in\left(R(C)+R(C)^{[\perp]}\right) \backslash R(C)^{[\perp]}$. Assume also that $N\left(C^{\#} C\right)$ is a $J_{\mathcal{H}}$-nonnegative pseudo-regular subspace of $\mathcal{H}$. Then, $w \in \mathcal{H}$ is a MILSS of $C x=y$ if and only if there exists $P \in \mathcal{Q}_{N\left(C \#_{C)}\right.}$ and $Q \in \mathcal{Q}_{R(C)}$ such that

$$
\begin{equation*}
w=(I-P) C^{\dagger} Q^{\#} y=(I-P) C^{\dagger} E y \tag{4.4}
\end{equation*}
$$

where $E=Q Q^{\#}$.
Proof. Under these assumptions, there exists a MILSS of $C x=y$. Furthermore, in the discussion above it was shown that, if $w \in \mathcal{H}$ is a MILSS of $C x=y$ then there exists $P \in \mathcal{Q}_{N\left(C \#_{C)}\right.}$ and $Q_{0} \in \mathcal{Q}_{R(C)}$ such that

$$
w=(I-P) u_{y}=(I-P) C^{\dagger} Q_{0}^{\#} y=(I-P) C^{\dagger} E_{0} y
$$

Conversely, given $P \in \mathcal{Q}_{N\left(C{ }^{\#} C\right)}$ and $Q \in \mathcal{Q}_{R(C)}$, consider the vector $w=(I-P) C^{\dagger} Q^{\#} y$. By Remark 2.1 it follows that $Q^{\#}(I-Q) y=0$ and $x:=C^{\dagger} Q^{\#} y=C^{\dagger} Q Q^{\#} y$. Then, $C x=P_{R(C)} Q Q^{\#} y=Q^{\#} Q y$ and

$$
Q y-C x=Q y-Q Q^{\#} y=Q\left(I-Q^{\#}\right) y \in R(C)^{\circ} .
$$

So, by Theorem 3.5, $x \in u_{y}+N\left(C^{\#} C\right)$. Also, $w=(I-P) x=(I-P) u_{y}$ and, following the same arguments as in Lemma 4.2, $w \in N\left(C^{\#} C\right)^{[\perp]}$. Therefore, by Proposition 4.1, $w$ is a MILSS of $C x=y$.

In the description obtained for the MILSS of $C x=y$ in the above theorem, the family of operators

$$
\left.\left\{(I-P) C^{\dagger} E: P \in \mathcal{Q}_{N(C}{ }^{\#} C\right)\right\}
$$

appears, where $E$ is the $J$-selfadjoint projection onto an arbitrary complement of $R(C)^{\circ}$ in $R(C)$. Along the next section, this family is related to some of the generalized inverses of $C^{\prime}:=E C$. Note that, under the assumptions of Theorem 4.3, $R\left(C^{\prime}\right)=R(E)$ is regular and $N\left(C^{\prime}\right)=N\left(C^{\#} C\right)$ is pseudo-regular.

## 5. Generalized inverses related to indefinite least-squares problems

The next result describes a family of generalized inverses of a closed-range operator with pseudo-regular range and nullspace.

Proposition 5.1. Suppose that $C \in C R(\mathcal{H}, \mathcal{K})$ is such that $R(C)$ and $N(C)$ are pseudo-regular subspaces of $\mathcal{K}$ and $\mathcal{H}$, respectively. Then, $D \in L(\mathcal{K}, \mathcal{H})$ is a solution of

$$
\left\{\begin{array}{l}
C X C=C  \tag{5.1}\\
X C X=X \\
(C X)(C X)^{\#}=(C X)^{\#}(C X) \\
(X C)(X C)^{\#}=(X C)^{\#}(X C)
\end{array}\right.
$$

if and only if there exist $Q \in \mathcal{Q}_{R(C)}$ and $P \in \mathcal{Q}_{N(C)}$ such that $D=(I-P) C^{\dagger} Q$.
Proof. Given $Q \in \mathcal{Q}_{R(C)}$ and $P \in \mathcal{Q}_{N(C)}$, consider $D=(I-P) C^{\dagger} Q$. Since $C P=0$,

$$
C D=C(I-P) C^{\dagger} Q=C C^{\dagger} Q=P_{R(C)} Q=Q
$$

Also,

$$
D C=(I-P) C^{\dagger} Q C=(I-P) C^{\dagger} C=(I-P) P_{N(C)^{\perp}}=I-P,
$$

because $R(P)=N(C)$. Therefore, $C D$ is a $J_{\mathcal{K}}$-normal projection and $D C$ is a $J_{\mathcal{H}}$-normal projection. Furthermore,

$$
C D C=(C D) C=Q C=C \quad \text { and } \quad D C D=(D C) D=(I-P) D=D .
$$

Conversely, assume that $D \in L(\mathcal{K}, \mathcal{H})$ satisfies the equations in (5.1). Then, note that $Q:=C D \in \mathcal{Q}_{R(C)}$, $P:=I-D C \in \mathcal{Q}_{N(C)}$ and

$$
(I-P) C^{\dagger} Q=(D C) C^{\dagger}(C D)=D\left(C C^{\dagger} C\right) D=D C D=D
$$

Let $E \in L(\mathcal{K})$ be a $J$-selfadjoint projection such that $R(E)+R(C)^{\circ}=R(C)$. Applying the above proposition to $C^{\prime}=E C$ it is possible to reinterpret the operators of the form $(I-P) C^{\dagger} E$ (with $P \in$ $\left.\mathcal{Q}_{N(C \neq C)}\right)$ as a particular family of generalized inverses of $C^{\prime}$.

Corollary 5.2. Suppose that $C \in C R(\mathcal{H}, \mathcal{K})$ is such that $R(C)$ and $N\left(C^{\#} C\right)$ are pseudo-regular subspaces of $\mathcal{K}$ and $\mathcal{H}$, respectively. Consider a J-selfadjoint projection $E \in L(\mathcal{K})$ such that $R(E)+R(C)^{\circ}=R(C)$. If $C^{\prime}=E C$ then the operators in the set

$$
\left\{(I-P) C^{\dagger} E: \quad P \in \mathcal{Q}_{N(C \# C)}\right\}
$$

are the solutions in $L(\mathcal{K}, \mathcal{H})$ of

$$
\left\{\begin{align*}
C^{\prime} X C^{\prime} & =C^{\prime}  \tag{5.2}\\
X C^{\prime} X & =X \\
C^{\prime} X & =E \\
\left(X C^{\prime}\right)\left(X C^{\prime}\right)^{\#} & =\left(X C^{\prime}\right)^{\#}\left(X C^{\prime}\right)
\end{align*}\right.
$$

Proof. Consider a $J$-selfadjoint projection $E \in L(\mathcal{K})$ such that $R(E)+R(C)^{\circ}=R(C)$. If $C^{\prime}=E C$ note that

$$
R\left(C^{\prime}\right)=R(E) \quad \text { and } \quad N\left(C^{\prime}\right)=N\left(C^{\#} C\right)
$$

Then, apply Proposition 5.1 to $C^{\prime}$.

Thus, the statement of Theorem 4.3 can be rephrased as: $w \in \mathcal{H}$ is a MILSS of $C x=y$ if and only if $u=D y$ where $D \in L(\mathcal{K}, \mathcal{H})$ is a solution of Eq. (5.2).

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