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STATIC, VACUUM, CYLINDRICAL AND PLANE SYMMETRIC SOLUTIONS
OF THE QUADRATIC POINCARÉ GAUGE FIELD EQUATIONS.

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ABSTRACT.

We present some static, cylindrically and plane symmetric solutions to the equations of the quadratic Poincare gauge field theory developed by Hehl and coworkers.

1. Introduction.

This paper contains some preliminary results in a search for static, vacuum, cylindrical and plane symmetric solutions to the equations of the quadratic Poincare gauge (QPG) field theory developed by Hehl and coworkers (See Hehl 1979 and Baekler, Hehl and Mielke 1980). In §2 a brief summary of the notation is given and the equations of the QPG theory are stated. A solution of the QPG field equations determines a Riemann-Cartan space-time which is specified by an orthonormal tetrad field (or, equivalently, a metric) and a metric-compatible non-symmetric connection. In the spherically symmetric solutions of Baekler et al. (1980) and Baekler (1982) the metric has the property of satisfying Einstein's equations with cosmological constant,

$$\tilde{R}_{\alpha\beta} = \Lambda g_{\alpha\beta} \quad (1.1)$$

where $\tilde{R}_{\alpha\beta}$ is the Ricci tensor for the symmetric Riemannian connection defined by the metric and the constant Λ involves certain coupling constants that occur in the QPG equations. Guided by these results we restrict ourselves here to looking for solutions which have this property. Accordingly, in §3, the complete solution of (1.1) for static, cylindrical and plane symmetric metrics is derived and, in §4, a number of special solutions to the QPG equations are derived corresponding to the metrics found in §3.

2. The QPG vacuum equations.

The underlying space-time is taken to be a differentiable

manifold with normal hyperbolic metric g and connection ∇ . It is assumed that the connection is compatible with the metric in the sense that

$$X\{g(Y,Z)\} = g(\nabla_X Y, Z) + g(Y, \nabla_X Z) \quad (2.1)$$

for arbitrary vector fields X, Y, Z .

Let e_α ($\alpha = 0, 1, 2, 3$) be an orthonormal tetrad field so that $g(e_\alpha, e_\beta) = \eta_{\alpha\beta} = \text{diag}(-1, 1, 1, 1)$. In terms of a local coordinate system $\{x^i\}$, $e_\alpha = e_\alpha^i(x) \partial_i$ where $\partial_i = \partial/\partial x^i$. The dual basis of one-forms will be denoted by $\theta^\alpha = e_\alpha^i(x) dx^i$, where $e_\alpha^i e_i^\beta = \delta_\alpha^\beta$, and their exterior derivatives (the object of anholonomy in Nehl's terminology) may be written in the form

$$d\theta^\alpha = \frac{1}{2} \Omega_{\mu\nu}^\alpha \theta^\mu \wedge \theta^\nu \quad (2.2)$$

where

$$\Omega_{\mu\nu}^\alpha = -\Omega_{\nu\mu}^\alpha = 2 \partial_{[i} e_{j]}^\alpha e_\mu^i e_\nu^j, \quad (2.3)$$

the square brackets denoting antisymmetrization.

The connection one-forms ω_α^β are defined by

$$\nabla_X e_\alpha = \omega_\alpha^\beta(X) e_\beta \quad (2.4)$$

for arbitrary vector field X , so that

$$\omega_\alpha^\beta = \Gamma_{\mu\alpha}^\beta \theta^\mu \quad (2.5)$$

where

$$\nabla_{e_\mu} e_\alpha = \Gamma_{\mu\alpha}^\beta e_\beta. \quad (2.6)$$

Since $g(e_\alpha, e_\beta)$ are constants, it follows from (2.1) and (2.6) that

$$\Gamma_{\alpha\beta\gamma} = -\Gamma_{\alpha\gamma\beta} \quad (2.7)$$

and hence

$$\Gamma_{\alpha\beta\gamma} = \Gamma_{[\alpha\beta]\gamma} - \Gamma_{[\beta\gamma]\alpha} + \Gamma_{[\gamma\alpha]\beta}. \quad (2.8)$$

The torsion two-forms are given by

$$\Theta^\alpha = d\theta^\alpha + \omega_\mu^\alpha \wedge \theta^\mu = \frac{1}{2} F_{\mu\nu}^\alpha \theta^\mu \wedge \theta^\nu \quad (2.9)$$

where, by (2.2) and (2.5),

$$F_{\mu\nu}^\alpha = \Omega_{\mu\nu}^\alpha + 2\Gamma_{[\mu\nu]}^\alpha \quad (2.10)$$

and hence, by (2.8),

$$\Gamma_{\mu\nu\alpha} = \frac{1}{2}(-\Omega_{\mu\nu\alpha} + \Omega_{\nu\alpha\mu} - \Omega_{\alpha\mu\nu} + F_{\mu\nu\alpha} - F_{\nu\alpha\mu} + F_{\alpha\mu\nu}). \quad (2.11)$$

The curvature two-forms are defined by

$$\Omega_\beta^\alpha = d\omega_\beta^\alpha + \omega_\mu^\alpha \wedge \omega_\beta^\mu = \frac{1}{2} F_{\mu\nu\beta}^\alpha \theta^\mu \wedge \theta^\nu, \quad (2.12)$$

so that

$$F_{\mu\nu\beta\alpha} = \partial_\mu \Gamma_{\nu\beta\alpha} - \partial_\nu \Gamma_{\mu\beta\alpha} + \Gamma_{\mu\sigma\alpha} \Gamma_{\nu\beta}^\sigma - \Gamma_{\nu\sigma\alpha} \Gamma_{\mu\beta}^\sigma + \Gamma_{\sigma\beta\alpha} \Omega_{\mu\nu}^\sigma, \quad (2.13)$$

where $\partial_\beta = e_\beta^i \partial_i$.

Finally, for later use in the field equations, one defines the modified torsion components

$$T_{\alpha\beta\gamma} = F_{\alpha\beta\gamma} + 2\eta_{[\alpha|\gamma]} F_{\beta]}, \quad (2.14)$$

where

$$F_\beta = F_{\beta\gamma}^\gamma; \quad (2.15)$$

also

$$T_{\beta}^{\gamma} = T_{\beta\gamma}^{\gamma} \quad \text{and} \quad \Gamma_{\beta} = \Gamma_{\gamma\beta}^{\gamma}. \quad (2.16)$$

The vacuum field equations of the quadratic Poincare gauge field theory for a particular choice of Lagrangian are given by equations (2.5) and (2.6) of Backler et al. (1980). These equations are written in terms of mixed coordinate and tetrad indices. Writing them entirely in terms of tetrad components one obtains the following equations (Hehl, private communication):

$$\begin{aligned} \Sigma_{\alpha\beta} &\equiv \partial_{\gamma} T_{\alpha\beta}^{\gamma} + (\Gamma_{\gamma}^{\gamma} - \frac{1}{2} T_{\gamma}^{\gamma}) T_{\alpha\beta}^{\gamma} - \Gamma_{\gamma\alpha}^{\mu} T_{\mu\beta}^{\gamma} - \Gamma_{\gamma\beta}^{\mu} T_{\alpha\mu}^{\gamma} \\ &\quad + \frac{1}{2} T_{\mu\alpha}^{\gamma} T_{\gamma\beta}^{\mu} + T_{\alpha}^{\gamma\mu} T_{\gamma\beta\mu} - \frac{1}{2} T_{\alpha}^{\gamma} T_{\beta}^{\gamma} + (\ell^2/\kappa) F_{\alpha\nu\sigma\tau} F_{\beta}^{\nu\sigma\tau} \\ &\quad - \frac{1}{2} n_{\alpha\beta} (T^{\gamma\sigma\mu} T_{\gamma\sigma\mu} - T^{\gamma} T_{\gamma}) + (\ell^2/\kappa) F_{\mu\nu\sigma\tau} F^{\mu\nu\sigma\tau} \\ &= 0, \end{aligned} \quad (2.17)$$

where κ and ℓ^2 are coupling constants, and

$$\begin{aligned} \tau_{\alpha\beta}^{\gamma} &\equiv \partial_{\mu} F_{\alpha\beta}^{\gamma\mu} - \Gamma_{\nu\alpha}^{\mu} F_{\mu\beta}^{\gamma\nu} + \Gamma_{\nu\beta}^{\mu} F_{\mu\alpha}^{\gamma\nu} + \Gamma_{\mu}^{\gamma} F^{\mu\alpha\beta} \\ &\quad + (\Gamma_{\nu\mu}^{\gamma} + \frac{1}{2} T_{\mu\nu}^{\gamma}) F^{\mu\nu\alpha\beta} + (\kappa/\ell^2) T_{[\alpha\beta]}^{\gamma} \\ &= 0. \end{aligned} \quad (2.18)$$

The procedure in looking for solutions of (2.17) and (2.18) is to regard them as equations for the "unknown" functions e_1^{α} and $F_{\alpha\beta\gamma}$. In analogy with the the spherically symmetric solutions of Backler et al. (1980) and Backler (1982) we restrict ourselves to

solutions of (2.17) , (2.18) for which the metric components $g_{ij} = \eta_{\alpha\beta}^{\alpha\beta} g_{ij}$ are solutions of Einstein's equations with cosmological constant,

$$\tilde{R}_{ij} = \Lambda g_{ij} , \quad (2.19)$$

where \tilde{R}_{ij} is the Ricci tensor for the symmetric Riemannian connection defined by g_{ij} and $\Lambda = \pm 3\kappa/4k^2$ (See equation (7.5) of Backler et al. 1980, where however it is only the + sign that occurs). The first step therefore is to solve (2.19) for static, cylindrical and plane symmetric space-times.

3. Einstein equations with cosmological constant.

Consider a static space-time which, in addition to the timelike hypersurface-orthogonal Killing vector field, has two spacelike Killing fields. We furthermore assume that the three Killing fields are mutually orthogonal and commute among themselves. One can then choose the coordinates so that

$$ds^2 = - e^{2u} dt^2 + e^{2v} dy^2 + e^{2w} dz^2 + dx^2, \quad (3.1)$$

where u , v and w are functions of x only. If the coordinate lines of y (say) are closed with $0 \leq y \leq 2\pi$ and $-\infty < z < \infty$, $0 < x < \infty$, the metric is cylindrically symmetric with y as the angular, x the cylindrical radial and z the longitudinal coordinate. If $-\infty < x, y, z < \infty$, the symmetry may be called pseudo-planar (See Bronnikov and Kovalchuk 1979). From the point of view of the local field equations both cases may be treated simultaneously. For the vacuum field equations with zero cosmological constant one may transform to Weyl canonical coordinates

with only two independent functions in the metric. However this is not possible here.

The field equations (2.19) for the metric (3.1) yield

$$v'' + w'' + v'^2 + w'^2 + v'w' = \Lambda, \quad (3.2)$$

$$w'' + u'' + w'^2 + u'^2 + u'w' = \Lambda, \quad (3.3)$$

$$u'' + v'' + u'^2 + v'^2 + u'v' = \Lambda, \quad (3.4)$$

$$v'w' + w'u' + u'v' = \Lambda, \quad (3.5)$$

where a prime denotes differentiation with respect to x . Let $\xi = u + v + w$, $\eta = u - v$, $\beta = v - w$ and $\alpha = w - u$. Then (2.3) - (2.6) give

$$\xi'' + \xi'^2 = 3\Lambda, \quad (3.6)$$

$$\eta' = ae^{-\xi}, \quad \beta' = be^{-\xi}, \quad \alpha' = ce^{-\xi}, \quad (3.7)$$

where a , b and c are constants of integration, with

$$a + b + c = 0. \quad (3.8)$$

We distinguish the cases for which $\Lambda > 0$ and $\Lambda < 0$.

I. $\Lambda > 0$.

The general solution of (3.6) is

$$\xi = \log(g e^{qx} + d e^{-qx}) \quad (3.9)$$

where $q = (3\Lambda)^{\frac{1}{2}}$, g and d are constants. The functions η ,

β and α are then obtained from (3.7) by a simple quadrature and hence u , v , and w are determined. On substituting (3.7) and (3.9) into (3.2) - (3.5) one obtains

$$a^2 + b^2 + c^2 = -8gdq^2. \quad (3.10)$$

We therefore have two subcases: Case I (a) for which $d = 0$, $g \neq 0$ (or $g = 0$, $d \neq 0$) and consequently, by (3.10), $a = b = c = 0$; Case I (b) for which both g and d are non-zero and, by (3.10), necessarily of opposite sign.

By some manipulation and rescaling of the coordinates one finally obtains the following forms for the functions in the metric (3.1):

Case I (a) ($d = 0$, $g \neq 0$):

$$u = v = w = qx/3. \quad (3.11)$$

If $g = 0$, $d \neq 0$, then $qx/3$ is replaced by $-qx/3$.

Case I (b) ($g \neq 0$, $d \neq 0$):

$$e^u = [\sinh(qx) f(x)^A]^{1/3} \quad (3.12)$$

$$e^v = [\sinh(qx) f(x)^B]^{1/3} \quad (3.13)$$

$$e^w = [\sinh(qx) f(x)^C]^{1/3} \quad (3.14)$$

where

$$f(x) = [\cosh(qx) - 1]/[\cosh(qx) + 1] \quad (3.15)$$

and

$$A + B + C = 0, \quad A^2 + B^2 + C^2 = 3/2. \quad (3.16)$$

By (3.16) the constants A, B and C may be expressed in terms of a single parameter p as follows:

$$A = \pm 3^{1/2} / [2(1+p)^2]^{1/2}, \quad B = pA, \quad C = -(1+p)A. \quad (3.17)$$

II. $\Lambda < 0$.

The general solution of (3.6) is then

$$\xi = \log[g \sin q(x+c)] \quad (3.18)$$

where $q = (-3\Lambda)^{1/2}$, g and c are constants. Again with some manipulation one can express the metric in the form (3.1) with

$$e^u = [\sin(qx) f(x)^A]^{1/3}, \quad (3.19)$$

$$e^v = [\sin(qx) f(x)^B]^{1/3} \quad (3.20)$$

$$e^w = [\sin(qx) f(x)^C]^{1/3} \quad (3.21)$$

where

$$f(x) = [1 - \cos(qx)] / [1 + \cos(qx)] \quad (3.22)$$

and A, B and C satisfy (3.16).

Note that for cylindrical symmetry, where y is the angular coordinate, the topological implications of rescaling y should be considered in all of the above cases.

Stationary, cylindrically symmetric solutions to Einstein's equations with cosmological constant have been treated by Krasinski (1975).

It is easy to verify that Case I (a) above is equivalent to the metric (9.3) of his paper, while a rather involved coordinate transformation shows Cases I (b) and II to be equivalent to his Type B solutions. However, the functions occurring in the Type B metrics of Krasinski are considerably more complicated containing, as they do, seven (constant) parameters instead of the two parameters q and p of the present paper.

4. Solutions of the QPG field equations.

In this section we present some special solutions of the QPG field equations (2.17) and (2.18). The metric is taken to be of the form (3.1) and the obvious orthonormal tetrad field,

$$e_1^0 dx^1 = e^u dt, \quad e_1^1 dx^1 = e^v dy, \quad e_1^2 dx^1 = e^w dz, \quad e_1^3 dx^1 = dx, \quad (4.1)$$

is chosen where $(x^0, x^1, x^2, x^3) = (t, y, z, x)$. We look for solutions of the equations (2.17) and (2.18) for which the functions $u, v,$ and w have the forms given in each of the three cases described in §3 and $\Lambda = 3\kappa/4l^2$ in Case I, $\Lambda = -3\kappa/4l^2$ in Case II. On making the substitutions (4.1) with the prescribed forms of u, v and w in each case, equations (2.17) and (2.18) become equations for the torsion components $F_{\alpha\beta\gamma} = -F_{\beta\gamma\alpha}$. In order to have manageable equations restrictions will also be imposed on the $F_{\alpha\beta\gamma}$ which will be specified when we come to deal with each case in turn.

When written out in full the expressions for $\Sigma_{\alpha\beta}$ and $T_{\alpha\beta}^{\gamma}$ occurring in equations (2.17) and (2.18) are very long and

unwieldy. All the calculations have been done on a computer using a REDUCE programme and a certain degree of trial and error was involved. As it would be extremely tedious to reproduce the details of the calculations we shall simply describe the procedure used and state the results

Solution I (a):

Let c_1^a be given by (4.1) with u, v and w as in (3.11).

The only non-zero components of $\Omega_{\alpha\beta\gamma}$ (modulo the antisymmetry, $\Omega_{\alpha\beta\gamma} = -\Omega_{\beta\alpha\gamma}$) are then $\Omega_{030} = -\Omega_{131} = -\Omega_{232} = q/3$.

Using this as a guide we restrict ourselves to seeking solutions of (2.17, 18) for which

$$F_{030} = -F_{300} = U(x), \quad (4.2)$$

$$F_{131} = -F_{311} = F_{232} = -F_{322} = -U(x)$$

and $q^2 = \Omega_K/4\Omega^2$.

Substitution of (4.2) and (4.1), with u, v and w as in (3.11), into (2.18) yields just one independent equation for $U(x)$,

$$U'' + qU' = 2U^2(U - q). \quad (4.3)$$

On substituting (4.3) into (2.17) one obtains two independent equations,

$$3U'^2 + 2q(U + q)U' - U(3U^3 - 4qU^2 + 3q^2U - 2q^3) = 0 \quad (4.4)$$

and

$$9U'^2 + 2q(3U - q)U' - U(9U^3 - 12qU^2 + q^2U + 2q^3) = 0. \quad (4.5)$$

Eliminate U'^2 from (4.4) and (4.5) to get

$$U' = U(U - q), \quad (4.6)$$

which has

$$U = q/(1 - De^{qx}) \quad (4.7)$$

as its general solution, where D is an arbitrary constant. Finally one may verify that (remarkably!) (4.7) satisfies all of the equations (4.3) - (4.5).

Thus (4.1) and (4.2), with u, v, w and U given by (3.11) and (4.7), is a solution of the QPG equations (2.17, 18)

Solution I (b):

Let c_1^α be as in (4.1) with $e^u, e^v,$ and e^w given by (3.12) - (3.15). The only independent non-zero components of $\Omega_{\alpha\beta\gamma}$ are again $\Omega_{030}, \Omega_{131}$ and Ω_{232} . For this case we have so far looked only for solutions in which one of the independent components F_{030}, F_{131} or F_{232} is non-zero while all the other independent components vanish.

First of all let

$$F_{030} = -F_{300} = U(x), \quad (4.8)$$

all other components of $F_{\alpha\beta\gamma} = 0,$

and, as before, $q^2 = 9\kappa/4\lambda^2$. It is found that the only independent non-identically zero components of $\tau_{\alpha\beta}^Y$ (equation (2.18)) are τ_{03}^0, τ_{13}^1 and τ_{23}^2 . The equation $\tau_{03}^0 = 0$ yields

$$\sinh^2(qx)U'' + q \sinh(qx)\cosh(qx)U' - q^2U = 0, \quad (4.9)$$

the general solution of which is

$$U = (a \cosh(qx) + b)/\sinh(qx), \quad (4.10)$$

where a and b are constants of integration. The solution U(x) of (4.10) satisfies $\tau_{13}^1 = 0$ if and only if $a = 0$ and either

$$b = 2q/3, \quad A = 1, \quad B = -\frac{1}{2}, \quad C = -\frac{1}{2},$$

or

$$b = -2q/3, \quad A = -1, \quad B = \frac{1}{2}, \quad C = \frac{1}{2}.$$

Furthermore, with either of these two sets of values for the constants the equation $\tau_{23}^2 = 0$ and $F_{\alpha\beta}^1 = 0$ (equation (2.17)) are automatically satisfied.

Thus (4.1) and (4.8), with u, v and w given by (3.12) - (3.15), is a solution of the QPG equations (2.17, 18) if and only if either

$$U(x) = 2q/3\sinh(qx), \quad A = 1, \quad B = -\frac{1}{2}, \quad C = -\frac{1}{2}, \quad (4.11)$$

or

$$U(x) = -2q/3\sinh(qx), \quad A = -1, \quad B = \frac{1}{2}, \quad C = \frac{1}{2}. \quad (4.12)$$

By a similar procedure the following solutions for the metric of Case I (b) may also be found:

$$F_{131} = -F_{311} = 2q/3\sinh(qx), \quad A = \frac{1}{2}, \quad B = -1, \quad C = \frac{1}{2}, \quad (4.13)$$

or

$$F_{131} = -F_{311} = -2q/3\sinh(qx), \quad A = -\frac{1}{2}, \quad B = 1, \quad C = -\frac{1}{2}, \quad (4.14)$$

all other $F_{\alpha\beta\gamma}$ being equal to zero, and

$$F_{232} = -F_{322} = 2q/3\sinh(qx), \quad A = \frac{1}{2}, \quad B = \frac{1}{2}, \quad C = -1 \quad (4.15)$$

or

$$F_{232} = -F_{322} = -2q/3\sinh(qx), \quad A = -\frac{1}{2}, \quad B = -\frac{1}{2}, \quad C = 1, \quad (4.16)$$

all other $F_{\alpha\beta\gamma}$ being equal to zero.

Case II:

An attempt to find solutions in this case along the lines of the preceding example proves to be unsuccessful. Take e^{α} as in (4.1) with e^u , e^v and e^w given by (3.19) - (3.22) and the torsion as in (4.8). Proceeding exactly as before, it is found that (2.18) is satisfied if and only if either

$$U(x) = 2q(2\cos qx + 3)/3\sin qx, \quad A = 1, \quad B = -\frac{1}{2}, \quad C = -\frac{1}{2} \quad (4.17)$$

or

$$U(x) = 2q(2\cos qx - 3)/3\sin qx, \quad A = -1, \quad B = \frac{1}{2}, \quad C = \frac{1}{2}. \quad (4.18)$$

However, on substituting these solutions into (2.17) one obtains

$$\Sigma_{\alpha\beta} = -(2q^2/3)\eta_{\alpha\beta}, \quad (4.19)$$

so there is no vacuum solution of this form for Case II.

Similarly, further solutions of equation (2.18) are given by

$$F_{131} = -2q(2\cos qx - 3)/3\sin qx, \quad A = \frac{1}{2}, \quad B = -1, \quad C = \frac{1}{2} \quad (4.20)$$

or

$$F_{131} = -2q(2\cos qx + 3)/3\sin qx, \quad A = -\frac{1}{2}, \quad B = 1, \quad C = -\frac{1}{2}, \quad (4.21)$$

all other independent $F_{\alpha\beta\gamma}$ being equal to zero, and the obvious corresponding solution for the case in which all the $F_{\alpha\beta\gamma}$ vanish except for $F_{232} = -F_{322}$. Substitution of these solutions into (2.17) again yields (4.19).

The lack of success in finding a vacuum solution for this case, where $\Lambda = -3\kappa/4l^2$ instead of $+3\kappa/4l^2$ as in Case I, would seem to indicate that, in general, the QPG equations are sensitive to the sign of Λ in (2.19).

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