

# CALCULATION OF THE FORCE ACTING ON NONMAGNETIC BODY IN MAGNETIC LIQUID IN THE PRESENCE OF INHOMOGENEOUS MAGNETIC FIELD

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**Abstract** Research of influence of form and size of particles on pushing out ability of magnetic fluid separator

**Keywords** Magnetic fluid, Magnetic fluid separator, Magnetic force

In magnetic fluid (MF) situated in inhomogeneous magnetic field physical effect of pushing out nonmagnetic bodies into the area where the field is weaker takes place. This effect is utilized in hydrostatic magnetic fluid separators (MFS) [1]-[3]. In the operating gap of MFS (fig. 1) inhomogeneous magnetic field throughout the height of a gap (in the direction of axis Y) is formed using the shape of polar tips. MF with density  $\rho$  and magnetization  $M$  is put between the polar tips. Pressure of MF near points 1 and 2 is equal to external pressure

$$p_1 = p_0, \quad p_2 = p_0. \quad (1)$$

Pressure variation in MF relative to external pressure is defined by evaluation

$$p = p_0 + \Delta p_G + \Delta p_M, \quad (2)$$

$$\Delta p_G = \rho \cdot g \cdot (y_2 - y), \quad \Delta p_M = u_M - u_{M2},$$

where  $\Delta p_G$  and  $\Delta p_M$  - pressure incrementation at the expense of gravitational and magnetic force respectively. From the direction of MF a force is acting on non-magnetic body with exterior surface  $\sigma$  and volume  $V$  submerged in it in the direction of axis Y

$$F_Y = -\oint_{\sigma} p \bar{e}_Y \cdot d\bar{\sigma} = F_A + F_{My}, \quad (3)$$

$$F_A = \rho \cdot g \cdot V, \quad F_{My} = -\oint_{\sigma} u_M \bar{e}_Y \cdot d\bar{\sigma}.$$

It consists of two parts: the first - force of Archimedes  $F_A$ , the second - magnetic force  $F_{My}$ , which depends upon distribution of specific magnetic energy of MF  $u_M$  on the surface of a particle. In its turn

$$u_M = \mu_0 \int_0^H M dH \quad (4)$$

depends upon the distribution of intensity  $H$  in the volume of MF.

By varying of the current in energizing winding of electromagnet it is possible to regulate the value of magnetic force  $F_{My}$ . Obviously, a particle with density

$\rho_p$  is affected by gravitation force  $\bar{F}_G = -\rho_p \cdot g \cdot V \cdot \bar{e}_Y$ . In MFS for lighter non-magnetic particles with density  $\rho_l$  a condition for their floating-up should be met, and for heavier particles with density  $\rho_h$  - a condition for their floating down.

$$\rho_l \cdot g \cdot V < (F_{My} + F_A), \quad \rho_h \cdot g \cdot V > (F_{My} + F_A). \quad (5)$$

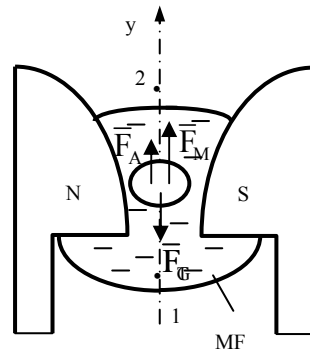


Fig. 1. Operating gap of hydrostatic MFS

In order to guarantee high precision of separation shape of polar tips of MFS should be chosen based on the condition  $F_{My} = \text{const}$ . Magnetic force depends upon distribution of intensity  $H$  in the volume of MF. Magnetic conductivity of non-magnetic particles equals to magnetic conductivity of vacuum  $\mu_0$ , which is lower than magnetic conductivity of MF  $\mu_K$ . This leads to change in distribution pattern of intensity  $H$  and specific magnetic energy  $u_M$  near non-magnetic particle. As a result a mechanism of volume value  $V$  and shape of non-magnetic body affection on the value of  $F_M$  takes place. Expression for  $F_M$  in (3) considers all these factors and is, apparently, the most precise. Relation [1]-[3] is often used for calculation of  $F_M$

$$\bar{F}_M = \bar{f}_M \cdot V, \quad \bar{f}_M = \mu_0 \cdot M \cdot \nabla H, \quad (6)$$

where magnetization  $M$  of MF and intensity gradient  $\nabla H$  are taken in the position of center of non-magnetic body upon condition of its absence in MF. It is fair if presence of non-magnetic body does not change distribution pattern of intensity  $H$  in operating gap of MFS.

In order to compare formulas (3) and (6) calculational research was conducted. On the ground of finite-element analysis of plane-parallel field in operating gap of MFS filled with MF with  $M_S = 17$  kA/m specific

force  $f_M$  for a rectangular cross-section body with width  $b$ , height  $h$  and unit length situated on symmetry line was defined.

TABLE I  
DEPENDANCE OF RELATIVE MAGNETIC FORCE ACTING  
ON NON-MAGNETIC BODY ON ITS VOLUME

h, mm	3	4	5	6	7	8	10
b, mm	4	6	8	10	12	14	19
V, mm <sup>3</sup>	12	24	40	60	84	112	190
$f_M$ , kN/m <sup>3</sup>	76,78	76,67	78,54	81,27	84,27	88,21	102,77

TABLE II  
DEPENDANCE OF RELATIVE MAGNETIC FORCE ACTING  
ON NON-MAGNETIC BODY ON ITS VOLUME WITH  
ALTERATION OF ITS VERTICAL DIMENSION ALONE

h, mm	4	5	6	7	8	9
b, mm	6	6	6	6	6	6
V, mm <sup>3</sup>	24	30	36	42	48	54
$f_M$ , kN/m <sup>3</sup>	76,67	75,19	74,06	72,74	70,88	68,59

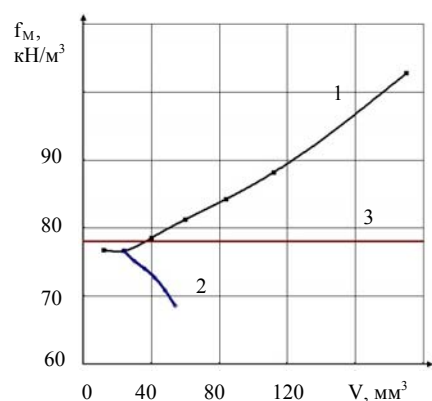


Fig. 2. Figures of dependencies of relative magnetic force on the size of non-magnetic body: 1 - size is changed along both directions, 2 - size is changed along direction of axis Y, 3 - calculated using (6).

Results of calculations show explicit dependence of  $f_M$  on the shape on size of the body. Ambiguousness of dependency is explained by type of pressure distribution in MF. In horizontal direction  $p$  increases from symmetry line to poles. Therefore force increases with the increase of dimension  $b$  (table 1, curve 1 on fig. 2). When  $b = \text{const}$  force decreases with the increase of height of the body (table 2, curve 2 on fig. 2). Results aquired using both formulas (3) and (6) coincide when body size is small and it affects distribution pattern of intensity  $H$  in MF weakly.

#### Acknowledgment

This financial support of the Grant РФФИ (RFBR) (project No. 09-08-97575-р\_центр\_a) is gratefully acknowledged.

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