

University College London

**Computational studies of magnetite Fe<sub>3</sub>O<sub>4</sub>  
and related spinel-structured materials**

Thesis submitted for the degree of Doctor of Philosophy (PhD) by

**David Santos Carballal**

Supervised by

Prof. Nora H. de Leeuw

University College London

Department of Chemistry

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# Declaration

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I, David Santos Carballal, confirm that the work presented in this thesis is my own.  
Where information has been derived from other sources, I confirm that this has been indicated in the thesis.

David Santos Carballal

March 2015

# Abstract

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This thesis presents the results of *ab initio* based simulation studies of magnetite ( $\text{Fe}_3\text{O}_4$ ) and related  $\text{FeM}_2\text{X}_4$  (thio)spinels with  $M = \text{Cr, Mn, Fe, Co}$  and  $\text{Ni}$  and  $X = \text{O}$  and  $\text{S}$ . Using density functional theory with long-range dispersion correction and on-site Coulomb interactions (DFT +  $U$  – D2), we have investigated a number of properties of these materials.

Firstly, we present a study of the inversion degree and its relevance in the electronic structure and magnetic properties of the spin filter candidates  $\text{FeM}_2\text{X}_4$ , which are one of the key devices in spintronic applications. We also analyze the role played by the size of the ions and by the crystal field stabilization effects in determining the equilibrium inversion degree. Secondly, we present the calculations of the elastic constants and other macroscopic mechanical properties by applying elastic strains on the unit cell of  $\text{Fe}_3\text{O}_4$ , which is the main component in different types of catalysts used in myriad of industrial processes. Thirdly, we calculate the geometries and surface free energies of a number of  $\text{Fe}_3\text{O}_4$  surfaces at different compositions, including the non-dipolar stoichiometric plane, and those with a deficiency or excess of oxygen atoms. We propose a morphology in thermodynamic equilibrium conditions for the nanocrystals of this compound. We also present the simulated scanning tunnelling microscopy images of the different terminations of the surfaces shown on the  $\text{Fe}_3\text{O}_4$  morphology. Finally, we investigate the initial oxidation stages of the greigite ( $\text{Fe}_3\text{S}_4$ ) (001) surface induced by water.  $\text{Fe}_3\text{S}_4$  is a mineral widely identified in anoxic aquatic environments and certain soils, which can be oxidised by these environments

## *Abstract*

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producing an extremely acid solution of sulfur-rich wastewater called acid mine drainage (AMD). We propose a number of mechanisms involving one or two water molecules and one OH group to explain the replacement of one sulfur by one oxygen atom in this mineral.

The findings presented in this thesis provide a theoretical insight into various bulk and surface properties of this group of compounds.

# Table of contents

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<b>Declaration</b> .....	2
<b>Abstract</b> .....	3
<b>Table of contents</b> .....	5
<b>Acknowledgments</b> .....	9
<b>List of publications</b> .....	10
<b>List of abbreviations</b> .....	11
<b>List of tables</b> .....	14
<b>List of figures</b> .....	17
<b>Chapter 1: Magnetite Fe<sub>3</sub>O<sub>4</sub> and related spinel-structured materials</b> .....	23
<b>1.1 Introduction</b> .....	23
<b>1.2 Natural occurrence and synthesis</b> .....	24
1.2.1 Rocks, ores and soils .....	24
1.2.2 Organisms .....	26
1.2.3 Synthetic preparation .....	27
<b>1.3 Crystal structure and morphology of spinels</b> .....	30
1.3.1 Crystal structure of spinels .....	30
1.3.2 Morphology of spinel crystals .....	31
<b>1.4 Magnetic and electric properties of spinels</b> .....	33
<b>1.5 Catalytic applications of Fe<sub>3</sub>O<sub>4</sub></b> .....	34
1.5.1 Haber-Bosch process for the production of ammonia .....	35
1.5.2 Fischer-Tropsch synthesis .....	36
1.5.3 Water gas shift reaction .....	38
1.5.4 Other applications of Fe <sub>3</sub> O <sub>4</sub> and the (thio)spinel .....	40
<b>1.6 Objectives of the thesis</b> .....	42
<b>Chapter 2: Methods for materials modelling</b> .....	43
<b>2.1 Introduction</b> .....	43
<b>2.2 The Schrödinger equation</b> .....	44
<b>2.3 Density functional theory</b> .....	46

## Table of contents

---

2.3.1 The Hohenberg-Kohn theorems	46
2.3.2 Kohn-Sham equations	47
2.3.3 Exchange-correlation functionals: LDA and GGA	48
<b>2.4 DFT + <math>U</math> method</b>	50
<b>2.5 Hybrid functionals</b>	52
<b>2.6 The electronic problem in periodic solids</b>	53
2.6.1 Bloch's theorem	53
2.6.2 Plane-wave expansion of the wavefunctions	54
<b>2.7 Pseudopotentials</b>	55
2.7.1 The projector augmented-wave method	56
<b>2.8 Dispersion interaction correction methods</b>	57
<b>2.9 Geometry optimizations</b>	59
2.9.1 Optimisation of ionic positions: the conjugate gradients method	60
2.9.2 Relaxation of cell parameters: Pulay stress and equation of state method	63
2.9.3 Transition states	64
<b>2.10 Analysis of optimized geometries</b>	65
2.10.1 Vibrational frequencies	65
2.10.2 Density of states	66
2.10.3 Bader analysis of the charges	66
<b>Chapter 3: Inversion thermodynamics and electronic structure of <math>\text{FeM}_2\text{X}_4</math> (thio)spinel (<math>M = \text{Cr, Mn, Fe, Co, Ni}</math>; <math>X = \text{O, S}</math>)</b>	68
<b>3.1 Introduction</b>	68
<b>3.2 Computational methods</b>	73
3.2.1 Calculation details	73
3.2.2 Configurational free energy of inversion	80
<b>3.3 Equilibrium structures</b>	81
<b>3.4 Equilibrium inversion degrees</b>	81
<b>3.5 Size of ions and crystal field stabilization effects</b>	88
<b>3.6 Atomic spin moments and charges</b>	90
<b>3.7 Electronic density of states</b>	95
3.7.1 $\text{FeCr}_2\text{X}_4$	95
3.7.2 $\text{FeMn}_2\text{X}_4$	98

## Table of contents

---

3.7.3 $\text{Fe}_3\text{X}_4$ .....	100
3.7.4 $\text{FeCo}_2\text{X}_4$ .....	101
3.7.5 $\text{FeNi}_2\text{X}_4$ .....	103
<b>3.8 Chapter conclusions</b> .....	<b>105</b>
<b>Chapter 4: Mechanical properties of magnetite</b> .....	<b>108</b>
4.1 Introduction .....	108
4.2 Computational details .....	110
4.3 Structural properties .....	113
4.4 Mechanical properties .....	115
4.5 Chapter conclusions .....	119
<b>Chapter 5: Structures, stabilities and redox behaviour of the major surfaces of <math>\text{Fe}_3\text{O}_4</math></b> .....	<b>120</b>
5.1 Introduction .....	120
5.2 Computational methods .....	127
5.2.1 Calculation details .....	127
5.2.2 Surface models .....	129
5.2.3 Calculation of surface energies .....	132
5.2.4 Redox processes of the (001) and (111) surfaces .....	134
5.2.5 Calculation of scanning tunnelling microscopy (STM) images .....	137
5.3 Stoichiometric surfaces .....	137
5.3.1 Morphology .....	147
5.3.2 Scanning tunnelling microscopy images simulation .....	149
5.4 Redox behaviour .....	152
5.4.1 Reduction of the (001) surface .....	153
5.4.2 Reduction of the (111) surface .....	155
5.4.3 Oxidation of the (001) surface .....	157
5.4.4 Oxidation of the (111) surface .....	159
5.5 Temperature and pressure effects .....	160
5.4 Chapter conclusions .....	166





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# List of publications

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The work described in this thesis has been published in the following papers:

Roldan, A., **Santos-Carballal, D.**, & de Leeuw, N. H. (2013). A Comparative DFT Study of the Mechanical and Electronic Properties of Greigite  $\text{Fe}_3\text{S}_4$  and Magnetite  $\text{Fe}_3\text{O}_4$ . *The Journal of Chemical Physics*, *138*(20), 204712. doi:10.1063/1.4807614.

**Santos-Carballal, D.**, Roldan, A., Grau-Crespo, R., & de Leeuw, N. H. (2014). A DFT Study of the Structures, Stabilities and Redox Behaviour of the Major Surfaces of Magnetite  $\text{Fe}_3\text{O}_4$ . *Physical Chemistry Chemical Physics*, *16*(39), 21082–21097. doi:10.1039/c4cp00529e.

**Santos-Carballal, D.**, Roldan, A., Grau-Crespo, R., & de Leeuw, N. H. (2014). First-Principles Study of the Inversion Thermodynamics and Electronic Structure of  $\text{FeM}_2\text{X}_4$  (Thio)Spinel ( $M = \text{Cr, Mn, Co, Ni}$ ;  $X = \text{O, S}$ ). *Submitted to Physical Review B*.

**Santos-Carballal, D.**, Roldan, A., & de Leeuw, N. H. (2014). Initial Oxidation of the Greigite  $\text{Fe}_3\text{S}_4(001)$  Surface Induced by Water: A Density Functional Theory Study. *To be submitted*.

# List of abbreviations

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**AES:** Auger electron spectroscopy

**AMD:** Acid mine drainage

**APDB:** Antiphase domain boundaries

**ARD:** Acid rock drainage

**CG:** Conjugate gradients

**DFT:** Density functional theory

**DFT – D2:** Method combining the DFT energy with a correction to the long-range dispersion interactions

**DFT +  $U$ :** Method combining a DFT Hamiltonian with a Hubbard Hamiltonian for the description of the on-site Coulomb interactions

**DOS:** Density of states

**GGA:** Generalized gradient approximation

**HF:** Hartree Fock

**HMF:** Half-metallic ferrimagnets

**HSE:** Hybrid density functional that incorporates 25% of Hartree Fock exchange developed by Heyd, Scuseria and Ernzerhof

**IDM:** Improved dimer method

*List of abbreviations*

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**KS:** Kohn-Sham

**LDA:** Local density approximation

**LDOS:** Local density of states

**LEED:** Low-energy electron diffraction

**LEEM:** Low-energy electron microscopy

**LEIS:** Low-energy ion scattering

**LPAW:** Linear augmented plane-wave

**ML:** Mono layer

**NCPP:** Norm-conserving pseudopotentials

**PAW:** Projector augmented-wave

**PBE:** Generalized gradient approximation density functional developed by Perdew, Burke and Ernzerhof

**PBEsol:** Revision of the PBE functional for solids

**PDOS:** Projected density of states

**PW91:** Generalized gradient approximation density functional developed by Perdew and Wang

**RHEED:** Reflection high-energy electron diffraction

**RMM-DIIS:** Residual minimisation method-direct inversion in the iterative subspace

*List of abbreviations*

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**SD:** Steepest descent

**SNG:** Substitute natural gas

**STM:** Scanning tunnelling microscopy

**STS:** Scanning tunnelling spectroscopy

**TS:** Tkatchenko-Scheffler

**USPP:** Ultrasoft pseudopotentials

**VASP:** Vienna *Ab-initio* Simulation Package

**VSEPR:** Valence Shell Electron Pair Repulsion

**VWN:** Vosko, Wilk and Nusair

**WGS:** Water gas shift

**XPD:** X-ray photoelectron diffraction

**XPS:** X-ray photoelectron spectroscopy

**XRD:** X-rays diffraction

# List of tables

---

<b>Table 3.1.</b> Summary of the optimum effective Hubbard parameter ( $U_{\text{eff}}$ ) in eV used through this work for the spinel oxides and sulfides. ....	76
<b>Table 3.2.</b> Summary of the initial unit cell lattice ( $a_0$ ) and anion ( $u_0$ ) parameters of $\text{FeM}_2\text{X}_4$ spinels used in this work. The relaxed $a$ and $u$ are also reported for $x = 0, 0.5$ and 1. Note that the origin is the center of symmetry. ....	79
<b>Table 3.3.</b> Summary of equilibrium inversion degree ( $x$ ) of $\text{FeM}_2\text{X}_4$ (thio)spinel from this work and previous reports. ....	85
<b>Table 3.4.</b> Atomic spin density per atom ( $m_s$ ) and total spin magnetization of saturation per formula unit ( $M_s$ ) both calculated by means of a Bader analysis and in $\mu\text{B}$ . ....	91
<b>Table 3.5.</b> Calculated Bader charges in the $\text{FeM}_2\text{X}_4$ spinels. ....	95
<b>Table 4.1.</b> Summary of geometric and electronic properties of bulk $\text{Fe}_3\text{O}_4$ . The properties listed are the mean value of the first-neighbours distance ( $d$ ), the charge ( $q$ ) and the spin densities ( $m_s$ ). The minus sign in the spin density represents the antiparallel alignment in the ferrimagnetic spinels. Previously reported values of its isostructural sulfide counterpart greigite ( $\text{Fe}_3\text{S}_4$ ) are shown for comparison. ....	114
<b>Table 4.2.</b> Physical properties of $\text{Fe}_3\text{O}_4$ derived from the elastic constants ( $C_{ij}$ ): bulk modulus ( $B$ ), shear modulus ( $G$ ), $B/G$ ratio, Young's modulus ( $Y$ ), Poisson's ratio ( $\sigma$ )	

and anisotropy factor ( $A$ ). Previously reported  $\text{Fe}_3\text{O}_4$  and  $\text{Fe}_3\text{S}_4$  values are shown for comparison. .... 116

**Table 5.1.** Calculated surface energies before ( $\gamma_u$ ) and after ( $\gamma_r$ ) relaxation for the different terminations of the three lowest Miller index surfaces of  $\text{Fe}_3\text{O}_4$ . .... 138

**Table 5.2.** Perpendicular movement ( $\Delta d_z$ ) of the  $\text{Fe}_3\text{O}_4$  surface species on the most stable (001) termination after relaxation. Note that a negative value indicates a movement towards the bulk. Distances are given in Å. .... 140

**Table 5.3.** Perpendicular movement ( $\Delta d_z$ ) of the  $\text{Fe}_3\text{O}_4$  surface species on the most stable (011) terminations after relaxation. Note that a negative value indicates a movement towards the bulk. Distances are given in Å. .... 143

**Table 5.4.** Perpendicular movement ( $\Delta d_z$ ) of the  $\text{Fe}_3\text{O}_4$  surface species on the most stable (111) terminations after relaxation. Note that a negative value indicates a movement towards the bulk. Distances are given in Å. .... 146

**Table 6.1.** Calculated bond distances (Å) and angles ( $^\circ$ ) at different minima states along the  $\text{Fe}_3\text{S}_4(001)$  surface oxidation following pathway 1. .... 178

**Table 6.2.** Calculated bond distances (Å) at different minima states along the  $\text{Fe}_3\text{S}_4(001)$  surface oxidation following pathway 2. .... 183

**Table 6.3.** Calculated bond distances (Å) and angles ( $^\circ$ ) at different minima states along the  $\text{Fe}_3\text{S}_4(001)$  surface oxidation following pathway 3. .... 189

*List of tables*

---

**Table 6.4.** Empirical expressions for the first ionization constant of H<sub>2</sub>S ( $K_{a1}$ ), vapour pressure of H<sub>2</sub>O ( $p_{H_2O}$ ) and Henry constant of H<sub>2</sub>S ( $K_{H_2S}$ ) as a function of the absolute temperature. .... 199



# List of figures

---

- Figure 2.1.** Profile representation of a local and global minima separated by a transition state, where  $E_a$  is the activation energy. ....60
- Figure 2.2.** Schematic illustration of (a) the steepest descent (SD) and (b) the conjugate gradients (CG) algorithms. ....61
- Figure 3.1.** Schematic representation of one full unit cell of a perfect spinel, highlighting one of the four primitive rhombohedral cells. The spinel structure has the symmetry group  $Fd\bar{3}m$  with three ion sites: tetrahedral (A), octahedral (B) cation positions and the anion (X) position. ....71
- Figure 3.2.** (a) Configurational inversion energy ( $\Delta E_{\text{config}}$ ) and (b) configurational inversion free energy ( $\Delta F_{\text{config}}$ ) as a function of the inversion degree for  $\text{FeM}_2\text{X}_4$  spinels. Inset shows enlargement of  $\Delta F_{\text{config}}$  for the  $\text{FeMn}_2\text{X}_4$  and  $\text{FeNi}_2\text{X}_4$  (thio)spinels. ....83
- Figure 3.3.** Atomic projections of the spin decomposed total density of states (PDOS) for  $\text{FeCr}_2\text{O}_4$  and  $\text{FeCr}_2\text{S}_4$ . Fe and Cr contributions are from the  $3d$  bands. O and S contributions are from the  $2p$  and  $3p$  orbitals respectively. ....97
- Figure 3.4.** Atomic projections of the spin decomposed total density of states (PDOS) for  $\text{FeMn}_2\text{O}_4$  and  $\text{FeMn}_2\text{S}_4$ . Fe and Mn contributions are from the  $3d$  bands. O and S contributions are from the  $2p$  and  $3p$  orbitals respectively. ....99

**Figure 3.5.** Atomic projections of the spin decomposed total density of states (PDOS) for Fe<sub>3</sub>O<sub>4</sub> and Fe<sub>3</sub>S<sub>4</sub>. Fe contributions are from the 3 *d* bands. O and S contributions are from the 2*p* and 3*p* orbitals respectively. .... 101

**Figure 3.6.** Atomic projections of the spin decomposed total density of states (PDOS) for FeCo<sub>2</sub>O<sub>4</sub> and FeCo<sub>2</sub>S<sub>4</sub>. Fe and Co contributions are from the 3*d* bands. O and S contributions are from the 2*p* and 3*p* orbitals respectively. .... 103

**Figure 3.7.** Atomic projections of the spin decomposed total density of states (PDOS) for FeNi<sub>2</sub>O<sub>4</sub> and FeNi<sub>2</sub>S<sub>4</sub>. Fe and Ni contributions are from the 3*d* bands. O and S contributions are from the 2*p* and 3*p* orbitals respectively. .... 105

**Figure 5.1.** View of the bulk structure of Fe<sub>3</sub>O<sub>4</sub>: (a) ball and stick model of the cubic unit cell and (b) polyhedral model showing the alternating layers of Fe<sub>B</sub> and Fe<sub>A</sub>-Fe<sub>B</sub> ions separated by O ions. Fe<sub>A</sub> ions are in grey, Fe<sub>B</sub> ions are in blue and O ions are in red. .... 122

**Figure 5.2.** Top and side view of the simulation slabs for terminations A and B of Fe<sub>3</sub>O<sub>4</sub>(001) surface. The surfaces are shown (column a) before, (column b) after relaxation and (column c) their stacking sequence. For the colour code see **Figure 5.1**. Layers with atoms with dangling bonds are highlighted. The crystallographic direction for the top view of (001) surface terminations is [100] for the abscissae towards the right. .... 141

**Figure 5.3.** Top and side view of the simulation slabs for terminations A and B of Fe<sub>3</sub>O<sub>4</sub>(011) surface. The surfaces are shown (column a) before, (column b) after relaxation and (column c) their stacking sequence. For the colour code see **Figure 5.1**.

Layers with atoms with dangling bonds are highlighted. The crystallographic direction for the top view of (011) surface terminations is  $[0\bar{1}1]$  for the abscissae towards the right. .... 144

**Figure 5.4.** Top and side view of the simulation slabs for terminations A and B of  $\text{Fe}_3\text{O}_4(111)$  surface. The surfaces are shown (column a) before, (column b) after relaxation and (column c) their stacking sequence. For the colour code see **Figure 5.1**.

Layers with atoms with dangling bonds are highlighted. The crystallographic direction for the top view of (111) surface terminations is  $[0\bar{1}1]$  for the longest axis towards the top. .... 147

**Figure 5.5.** (a) Equilibrium morphology for a  $\text{Fe}_3\text{O}_4$  crystal derived from a Wulff construction. (b) – (d) Schemes of the crystal cross-sectional planes along the  $\langle 100 \rangle$  and  $\langle 010 \rangle$  axes for different ratios of stabilities of the lateral surfaces, which illustrate why the (011) surface is absent in the equilibrium morphology. .... 148

**Figure 5.6.** Simulated STM images of (a) termination A of (001), (b) termination A of (111) and (c) termination B of (111) surfaces obtained using a bias of  $-2.5$  eV. Density ( $\rho$ ) and tip distance (d) are also indicated. Insets show enlargements of the STM images. In the inset,  $\text{Fe}_A$  ions are in grey,  $\text{Fe}_B$  ions are in blue and O ions are in red. .... 152

**Figure 5.7.** Top view of the schematic representation of the  $\text{Fe}_3\text{O}_4(001)$  surface before (top panels) and after relaxation (bottom panels) with different  $\Gamma$ . Stoichiometric ( $\Gamma = 0$ ); partially reduced ( $\Gamma = -1, -2$ ) and partially oxidized ( $\Gamma = +1, +2$ ).  $\text{Fe}_A$  ions are in

grey, Fe<sub>B</sub> ions are in blue and O ions are in red, removed O ions are in pale red and added O atoms are in dark red. Only the closest defects are highlighted indicating their relative position, while all of them are shown. The arrows indicate the [110] direction. Black lines indicate the surface unit cell. .... 154

**Figure 5.8.** Top view of the schematic representation of the Fe<sub>3</sub>O<sub>4</sub>(111) surface before (top panels) and after relaxation (bottom panels) with different  $\Gamma$ . Stoichiometric ( $\Gamma = 0$ ); partially reduced ( $\Gamma = -1, -2$ ) and partially oxidized ( $\Gamma = +1, +2$ ). Fe<sub>A</sub> ions are in grey, Fe<sub>B</sub> ions are in blue and O ions are in red, removed O ions are in pale red and added O atoms are in dark red. Only the closest defects are highlighted indicating their relative position, while all of them are shown. The arrows indicate the  $[0\bar{1}1]$  direction. Black lines indicate the surface unit cell. .... 156

**Figure 5.9.** (a)  $\mu_{\text{O}}$  in the gas phase as a function of the temperature and the logarithm of the oxygen partial pressure and relative surface free energies ( $\Delta\sigma$ ) for the Fe<sub>3</sub>O<sub>4</sub> (b) (001) and (c) (111) surfaces as a function of the oxygen chemical potential ( $\mu_{\text{O}}$ ). The areas corresponding to  $\mu_{\text{O}}$  smaller than  $-3.13$  eV, bigger than  $-2.44$  eV and between these two values represent the approximate conditions under which bulk FeO, Fe<sub>2</sub>O<sub>3</sub> and Fe<sub>3</sub>O<sub>4</sub> respectively are the stable oxides. .... 165

**Figure 6.1.** (a) Ball-and-stick model of the unit cell of Fe<sub>3</sub>S<sub>4</sub> showing the cubic spinel crystal structure and (b) top view of the space-filling model of its (001) surface. · 170

**Figure 6.2.** Charge density difference plot of the adsorption at different stages along the oxidation of the Fe<sub>3</sub>S<sub>4</sub>(001) surface following pathway 1. Isosurfaces of the

difference density are displayed at a value of  $\pm 0.05 \text{ e} \cdot \text{\AA}^{-3}$ , where purple and orange represent gain and lost electron density respectively. Light blue atoms represent  $\text{Fe}_A$ , dark blue for  $\text{Fe}_B$ , yellow for S, red for O and white for H. .... 178

**Figure 6.3.** (a) Schematic representation and (b) reaction profile for the oxidation of the  $\text{Fe}_3\text{S}_4(001)$  surface via pathway 1. Insets show side and top view of the structure of the numbered states. Only the surface and species adsorbed to it are shown. Light blue atoms represent  $\text{Fe}_A$ , dark blue for  $\text{Fe}_B$ , yellow for S, red for O and white for H. .... 181

**Figure 6.4.** Charge density difference plot of the adsorption at different stages along the oxidation of the  $\text{Fe}_3\text{S}_4(001)$  surface following pathway 2. Isosurfaces of the difference density are displayed at a value of  $\pm 0.05 \text{ e} \cdot \text{\AA}^{-3}$ , where purple and orange represent gain and lost electron density respectively. Light blue atoms represent  $\text{Fe}_A$ , dark blue for  $\text{Fe}_B$ , yellow for S, red for O and white for H. .... 183

**Figure 6.5.** (a) Schematic representation and (b) reaction profile for the oxidation of the  $\text{Fe}_3\text{S}_4(001)$  surface via pathway 2 (the red dashed line represents a variation of pathway 2 in which OH dissociation takes place first). Insets show side and top view of the structure of the numbered states. Only the surface and species adsorbed to it are shown. Light blue atoms represent  $\text{Fe}_A$ , dark blue for  $\text{Fe}_B$ , yellow for S, red for O and white for H. .... 186

**Figure 6.6.** Charge density difference plot of the adsorption at different stages along the oxidation of the  $\text{Fe}_3\text{S}_4(001)$  surface following pathway 3. Isosurfaces of the difference density are displayed at a value of  $\pm 0.05 \text{ e} \cdot \text{\AA}^{-3}$ , where purple and orange

*List of figures*

---

represent gain and lost electron density respectively. Light blue atoms represent Fe<sub>A</sub>, dark blue for Fe<sub>B</sub>, yellow for S, red for O and white for H. .... 188

**Figure 6.7.** Schematic representation or the oxidation of the Fe<sub>3</sub>S<sub>4</sub>(001) surface via pathway 3. Only the surface and species adsorbed to it are shown. .... 194

**Figure 6.8.** Reaction profile for the oxidation of the Fe<sub>3</sub>S<sub>4</sub>(001) surface via pathway 3. Insets show side and top view of the structure of the numbered states. Only the surface and species adsorbed to it are shown. Light blue atoms represent Fe<sub>A</sub>, dark blue for Fe<sub>B</sub>, yellow for S, red for O and white for H. .... 195

**Figure 6.9.** Comparison of the entropy as a function of temperature reported by Chase (1998) and calculated using statistical thermodynamics for gaseous H<sub>2</sub>S and H<sub>2</sub>O. .... 201

**Figure 6.10.** Calculated dependence of (a) [H<sub>2</sub>S] and (b) pH with respect to *T* for the partial oxidation of the Fe<sub>3</sub>S<sub>4</sub>(001) surface following pathway 2. The dotted and dashed lines are added for comparison porpoises and they represent processes with  $\Delta H^\ominus = -10$  and 10 eV respectively. .... 201

# Magnetite $\text{Fe}_3\text{O}_4$ and related spinel-structured materials

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## 1.1 Introduction

In this thesis, we present a computational investigation of the solid state chemistry of (thio)spinel and the surface chemistry of magnetite ( $\text{Fe}_3\text{O}_4$ ) and greigite ( $\text{Fe}_3\text{S}_4$ ). These group of compounds occur naturally in many of the Earth's layers, such as the lithosphere, pedosphere and biosphere, where they play an important role in the interrelationship between them via cyclic processes of redistribution and transformation. Therefore, (thio)spinel are of interest in various scientific disciplines and their research has led to a vast collection of interdisciplinary communications whose outcomes have been rather inconclusive at times. For instance, the conduction and magnetic properties of the (thio)spinel and their relationship with the equilibrium inversion degree have not yet been systematically explained, which is essential for spintronic applications. The nature of the forces operating on  $\text{Fe}_3\text{O}_4$  and their effect on the mechanical and dynamical properties of this compound have not yet been elucidated. Moreover, although  $\text{Fe}_3\text{O}_4$  is widely used as the main component of

industrial catalysts in myriad processes, there is no agreement in either the termination of its main surfaces or the thermodynamics of the redox reactions taking place on them. Similarly, the initial oxidation process of the Fe<sub>3</sub>S<sub>4</sub>(001) surface is still largely unknown. Fe<sub>3</sub>S<sub>4</sub> is a mineral thought to have played an important catalytic role in the iron-sulfur origin of life theory (Russell and Hall, 1997) and may contribute to the formation of acid mine drainage (AMD).

In this chapter, we review the natural occurrences of these materials, especially Fe<sub>3</sub>O<sub>4</sub>, and their synthetic preparation. We present the common characteristics of the crystal structure and morphology of the spinel group and discuss the electronic and magnetic properties of this group of materials and their applications, mainly as catalysts.

## **1.2 Natural occurrence and synthesis**

### **1.2.1 Rocks, ores and soils**

**Magnetite** also known as “lodestone” or “loadstone”, which is a portmanteau of the words “leading” and “stone”, has been used as the orientation element since the earliest compasses due to its magnetic properties. Its name derives possibly from the Greek region of Magnesia (Anthony *et al.*, n.d.). Fe<sub>3</sub>O<sub>4</sub> is found ubiquitously in all of the three groups of rocks forming the lithosphere, *i.e.* magmatic (Frost and Lindsley, 1991), metamorphic (Frost, 1991) and sedimentary (Morad and Aldahan, 1986) rocks. In all these environments, and especially in the magmatic rocks, magnetite appears forming solid solutions known generically as titanomagnetites (Fe<sub>3-x</sub>Ti<sub>x</sub>O<sub>4</sub>) (Grant, 1985), where usually  $0.0 < x < 0.8$  (Frost and Lindsley, 1991). Other ions such as Ni,



Cr, Mn and Co, can also replace Fe in small amounts (Sidhu *et al.*, 1980, 1978). Sedimentary Fe<sub>3</sub>O<sub>4</sub> is found forming deposits of banded iron formation (Huberty *et al.*, 2012), iron stones in purely sedimentary ores (Torres-Ruiz, 1983) or deep sea sediments (Petersen *et al.*, 1986) with both detrital and biogenic origin. Fe<sub>3</sub>O<sub>4</sub> is also found in certain soils of the pedosphere, where two formation routes are suggested, namely *in situ* inorganic formation of this mineral (Maher and Taylor, 1988) or its accumulation from dead magnetotactic bacteria (Fassbinder *et al.*, 1990). Finally, Fe<sub>3</sub>O<sub>4</sub> is an important component of meteorites coming from Mars, which suggests the presence of this iron oxide phase on that planet's surface (Bradley *et al.*, 1996).

**Greigite** is named after Dr JW Greig (1895–1977), who was an American mineralogist and physical chemist (Anthony *et al.*, n.d.). Although Fe<sub>3</sub>S<sub>4</sub> is not the most stable iron sulfide structure, it has been widely identified in anoxic aquatic environments, such as marine (Roberts and Turner, 1993), brackish (Jelinowska *et al.*, 1998) or fresh water (Jelinowska *et al.*, 1995; Snowball, 1991) as well as during the formation of certain soils (Fassbinder *et al.*, 1990; Fassbinder and Stanjek, 1994). Layers of Fe<sub>3</sub>S<sub>4</sub> have been found in lacustrine sediments consisting of interbedded clastics, aragonite, silt, sand or clay (Frank *et al.*, 2007) as well as in varved-like laminae of alternating sulfide-bearing and sulfide-free layers (Skinner *et al.*, 1964).

**Chromite** (FeCr<sub>2</sub>O<sub>4</sub>) derives its name from its content of chromium (Anthony *et al.*, n.d.). FeCr<sub>2</sub>O<sub>4</sub> is an accessory cumulus mineral in layered peridotites (Cameron, 1978), an ultramafic rock classified as magmatic, which has low silica and high iron and magnesium content. The presence of FeCr<sub>2</sub>O<sub>4</sub> on mafic and ultramafic rocks can also

have a detrital origin (Lee, 1999). Relic FeCr<sub>2</sub>O<sub>4</sub> is also common in fossil meteorites (Bunch *et al.*, 1967; Nyström *et al.*, 1988; Ramdohr, 1967) and in those meteorites coming from the mare regions of the moon (Arai *et al.*, 1996; Papike *et al.*, 1976).

**Daubréelite** (FeCr<sub>2</sub>S<sub>4</sub>) is named in honour to Professor GA Daubrée (1814–1896), who was a French meteorite researcher (Anthony *et al.*, n.d.). Small amounts of FeCr<sub>2</sub>S<sub>4</sub> are found naturally only in meteorites (Chikamii *et al.*, 1999; El Goresy, 1967).

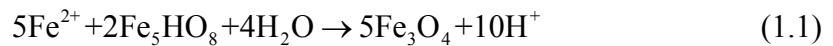
**Violarite** (FeNi<sub>2</sub>S<sub>4</sub>) derives its name from the violet colour of its polished surface (Anthony *et al.*, n.d.). FeNi<sub>2</sub>S<sub>4</sub> occurs rarely as a product of the initial alteration of nickel ores near the earth surface (Arnold and Malik, 1974).

### 1.2.2 Organisms

Biominerals are inorganic solids produced by living organisms. The formation of these minerals can follow one of two routes according to the level of complexity of the producing organism. For example, (1) in animals, biominerals formation is mediated by an organic support or membrane surface, while in (2) some bacterial and algae species, the biomineralization process is induced by favourable chemical conditions (Lowenstam, 1981). Amongst all the compounds relevant to this thesis, only Fe<sub>3</sub>O<sub>4</sub> and Fe<sub>3</sub>S<sub>4</sub> are biotically formed.

**Magnetite** formed biotically has been reported in the teeth of chitons (Lowenstam, 1962). Biogenic Fe<sub>3</sub>O<sub>4</sub> has also been found in magnetotactic bacteria (the type of microorganisms that use this mineral for orientation porpoises) in marine environments (Blakemore, 1975), anaerobic soils (Fassbinder *et al.*, 1990) and in lakes

(Vali and Kirschvink, 1991) as well as in magnetotactic algae in brackish sediments (Torres de Araujo *et al.*, 1986). Fe<sub>3</sub>O<sub>4</sub> is also found in honey bees (Gould *et al.*, 1978) and in the skull of homing pigeons (Walcott *et al.*, 1979), where it seems to have the same function than in magnetotactic bacteria. In the chitons (Kirschvink and Lowenstam, 1979; Lowenstam, 1981; Nesson and Lowenstam, 1985) and bacteria (Mann *et al.*, 1989), the mechanism for the Fe<sub>3</sub>O<sub>4</sub> biomineralization is supposed to be similar and it involves the reaction of ferrihydrite with dissolved Fe<sup>2+</sup>, according to the following process:



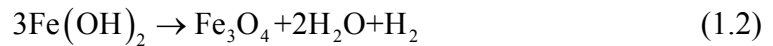
Biogenic **greigite** has also been identified in magnetotactic bacteria from brackish, sulfide-rich waters and sediments (Mann *et al.*, 1990) as well as in the scales of a hydrothermal vent gastropod (Goffredi *et al.*, 2004). Biologically produced Fe<sub>3</sub>O<sub>4</sub> and Fe<sub>3</sub>S<sub>4</sub> may persist once the organism that formed it has died and may therefore, contribute to the natural magnetic remanence of sediments (Stolz *et al.*, 1986), as was discussed above.

To the best of our knowledge, **FeNi<sub>2</sub>O<sub>4</sub>**, **FeMn<sub>2</sub>O<sub>4</sub>**, **FeMn<sub>2</sub>S<sub>4</sub>**, **FeCo<sub>2</sub>O<sub>4</sub>** and **FeCo<sub>2</sub>S<sub>4</sub>** do not occur naturally in the lithosphere, pedosphere or biosphere.

### 1.2.3 Synthetic preparation

**Magnetite** is usually extracted from rock ores, which are the primary source of iron oxides (Cornell and Schwertmann, 2003). Fe<sub>3</sub>O<sub>4</sub> can also be synthesised in the laboratory by a number of different hydrothermal methods. The first method reported

for the synthesis of Fe<sub>3</sub>O<sub>4</sub>, known as Schikorr reaction (Schikorr, 1929), involves the oxidation of Fe(OH)<sub>2</sub>, obtained from the alkaline hydrolysis of FeSO<sub>4</sub>, using heat under inert atmosphere, as follows:



However, this method was never very convenient due to complicated side reactions and it was later modified by starting from various Fe<sup>2+</sup> salts in solution and adding different types of oxidizing agents (David and Welch, 1956; Regazzoni *et al.*, 1981; Sarel *et al.*, 1989). There are other types of methods for synthesising Fe<sub>3</sub>O<sub>4</sub> that instead favour the reduction of Fe<sup>3+</sup> compounds (Booy and Swaddle, 1978; Kominami *et al.*, 1999) or the combination of Fe<sup>2+</sup>/Fe<sup>3+</sup> ions in solution (Regazzoni *et al.*, 1981).

**Greigite** is formed as an intermediate in the solid-state transformation of mackinawite (FeS) into pyrite (FeS<sub>2</sub>) (Benning *et al.*, 2000; Dekkers and Schoonen, 1996; Hunger and Benning, 2007; Wilkin and Barnes, 1996). The model for the FeS to Fe<sub>3</sub>S<sub>4</sub> transition proposed by Lennie *et al.* (1997) requires the diffusion of approximately two of every four Fe<sup>2+</sup> cations from tetrahedral sites in FeS to octahedral sites in Fe<sub>3</sub>S<sub>4</sub>, with the concomitant oxidation of half the migrating Fe<sup>2+</sup> to Fe<sup>3+</sup>. Fe<sub>3</sub>S<sub>4</sub> can also be formed via a hydrothermal method, in which a solution of sulfide and elemental sulfur is mixed with heat in stoichiometric proportions with another containing an Fe<sup>2+</sup> salt (Dekkers and Schoonen, 1994; Horiuchi *et al.*, 1974).

**Chromite** crystals can be grown in the laboratory through the chemical vapour transport method. This technique requires high temperatures to heat a stoichiometric mixture of FeO and Cr<sub>2</sub>O<sub>3</sub> inside an evacuated quartz tube to obtain a polycrystalline

powder of FeCr<sub>2</sub>O<sub>4</sub>. This sample requires further thermic treatment in presence of CrCl<sub>3</sub>, the transport agent, to obtain single crystals (Bordács *et al.*, 2009; Ohgushi *et al.*, 2008). FeCr<sub>2</sub>O<sub>4</sub> is also formed by firing a mixture of Fe<sub>2</sub>O<sub>3</sub> and Cr<sub>2</sub>O<sub>3</sub> in an atmosphere of CO<sub>2</sub> and H<sub>2</sub> or CO at 950 – 1300 °C (Klemme *et al.*, 2000; Tanaka *et al.*, 1966), or in vacuum by adding also pure Fe and heating (Shirane *et al.*, 1964). FeCr<sub>2</sub>O<sub>4</sub> can also be prepared through combustion of a mixture of the stoichiometric amounts of aqueous saturated solutions of Fe(NO<sub>3</sub>)<sub>2</sub>, Cr(NO<sub>3</sub>)<sub>3</sub> and urea (Manoharan and Patil, 1992).

**Daubréelite** polycrystalline powders are prepared from a heated mixture of the stoichiometric amount of elemental Fe, Cr and S (Kim, 2004; Ramirez *et al.*, 1997; Shirane *et al.*, 1964). Further heating of FeCr<sub>2</sub>S<sub>4</sub> powder in the presence of transport agent can also lead to single crystals (Ohgushi *et al.*, 2008). FeCr<sub>2</sub>S<sub>4</sub> nanocrystals are also formed via a wet chemistry method, where iron(II) acetylacetonate, chromium(III) acetylacetonate and 1-dodecanethiol in stoichiometric amounts are dissolved in oleylamine and heated at 335 °C for 30 minutes (Mao and Lee, 2014).

**FeNi<sub>2</sub>O<sub>4</sub>** is synthesised by co-precipitating the hydroxides of iron and nickel with NaOH, followed by heat treatment at a pressure of 140 atm (Shafer, 1962). **Violarite** is formed by heating a stoichiometric mixture of elemental Fe, Ni and S (Tenailleau *et al.*, 2006; Townsend *et al.*, 1977).

**FeCo<sub>2</sub>O<sub>4</sub>** is synthesised by heating a mixture of Fe<sub>2</sub>O<sub>3</sub> and Co<sub>2</sub>O<sub>3</sub> in stoichiometric proportions (Murray and Linnett, 1976; Muthuselvam and Bhowmik, 2009). FeCo<sub>2</sub>O<sub>4</sub> is also prepared by co-precipitating the iron and cobalt hydroxydes, from an aqueous

solution of FeCl<sub>3</sub> and CoCl<sub>2</sub> prepared in 1:2 molar ratio, by adding a basic solution under heat (Ferreira *et al.*, 2003). A *chimie douce* method has been used for the preparation of FeCo<sub>2</sub>O<sub>4</sub>, where a concentrated solution of FeCl<sub>2</sub> and CoCl<sub>2</sub>, prepared in a 1:2 ratio, is made to react with oxalic acid to precipitate an oxalate precursor, which transforms into the spinel with heat (Le Trong *et al.*, 2008).

The synthesis of **FeCo<sub>2</sub>S<sub>4</sub>**, **FeMn<sub>2</sub>O<sub>4</sub>** and **FeMn<sub>2</sub>S<sub>4</sub>** have not been reported until this date.

## **1.3 Crystal structure and morphology of spinels**

### 1.3.1 Crystal structure of spinels

The spinel structure is named after the mineral spinel MgAl<sub>2</sub>O<sub>4</sub>. This structure is characteristic of compounds with chemical formula  $M'M_2X_4$ , where  $M'$  and  $M$  represent metallic cations and  $X$  is an oxygen or bivalent chalcogen anion (in this thesis,  $M' = \text{Fe}$ ;  $M = \text{Cr, Mn, Fe, Co, Ni}$  and  $X = \text{O, S}$ ). The spinel structure is composed by a face-centred cubic unit cell based on 32  $X$  anions which are nearly regularly close packed. Amongst the holes created by the anions' arrangement, 8 of the tetrahedral (A) and 16 of the octahedral (B) are occupied by cations. For the compounds of interest in this thesis where all Fe ions are in the tetrahedral positions, the symmetry corresponds to the  $Fd\bar{3}m$  space group (Krupicka and Novak, 1982). The most common oxidation states of the transition metals in spinels are 2+, 3+ and 4+ which leads to two types of spinels. The 2–3 type has two 3+ and one 2+ cations per formula unit while the 4–2

type has two 2+ and one 4+ cations per formula unit. According to this classification, all the compositions studied in this thesis are 2–3 spinels.

**Magnetite** has the cubic spinel structure (Bragg, 1915) above the Verwey temperature ( $T_V = 122$  K) (Verwey, 1939) and below this temperature it becomes monoclinic (Wright *et al.*, 2002). **Chromite** and **FeMn<sub>2</sub>O<sub>4</sub>** also have the cubic spinel structure above the Jahn-Teller temperature ( $T_{JT} = 135$  (Shirane *et al.*, 1964) and 473 K respectively (Van Landuyt *et al.*, 1972)). Below these temperatures, the crystals become tetragonal.

**Gregite**, **daubréelite**, **FeNi<sub>2</sub>O<sub>4</sub>**, **violarite** and **FeCo<sub>2</sub>O<sub>4</sub>** have no first-order phase transition found.

### 1.3.2 Morphology of spinel crystals

**Magnetite** crystals, both synthetic and natural, have been described with octahedral morphologies enclosed by (111) planes and octahedral with truncated corners morphologies by adding the (001) surfaces. Twinning has also been reported and it occurs on the (111) plane. Hydrothermal methods usually produce rounded, cubic or octahedral crystals, whose dimensions can be controlled by modifying the initial reactants and chemical conditions. For example, precipitation of Fe<sub>3</sub>O<sub>4</sub> in neutral (Regazzoni *et al.*, 1981; Taylor and Schwertmann, 1974) and mild acid (Couling and Mann, 1985; Sidhu *et al.*, 1978) conditions give particles sized smaller than 0.1 μm. Larger (0.03–1.1 μm) octahedral and sphere particles can be obtained in mild basic conditions (David and Welch, 1956; Sugimoto and Matijević, 1980), while a strong basic environment favours cubic crystals (Feitknecht, 1959). Fe<sub>3</sub>O<sub>4</sub> crystals capping

the teeth of chitons display different sizes and morphologies (Towe and Lowenstam, 1967; Webb *et al.*, 1989). However, those found in magnetotactic bacteria are hexagonal, rectangular, cubic, bullet shaped (Schüler, 1999) or forming twins (Devouard *et al.*, 1998). These morphologies are based on the octahedral and elongated hexagonal prism which can be obtained combining the (111), (001) and (010) surfaces (Devouard *et al.*, 1998; Mann and Frankel, 1989).

**Greigite** from sediments also shows octahedral crystal morphology (Roberts and Weaver, 2005; Skinner *et al.*, 1964) or platy and needle-like particles 5–15 µm size (Snowball and Thompson, 1990a, 1990b). Biogenic Fe<sub>3</sub>S<sub>4</sub> crystals have octahedral shape with truncated corners (Heywood *et al.*, 1990), a morphology which is also found, along with polyhedral crystals, in hydrothermally synthesised Fe<sub>3</sub>S<sub>4</sub> (Chang *et al.*, 2008).

Natural **chromite** in magmatic rocks shows octahedral morphologies with rounded edges or hollow prismatic crystals with octahedral terminations (Leblanc, 1980). FeCr<sub>2</sub>O<sub>4</sub> synthesised using the chemical vapour transport method gives octahedral crystals (Ohgushi *et al.*, 2008).

Similarly, **daubréelite** synthesised via the chemical vapour transport method (Ohgushi *et al.*, 2008) or found in meteorites (Chikamii *et al.*, 1999) have octahedral morphologies. Those FeCr<sub>2</sub>S<sub>4</sub> particles formed through the wet chemistry method tend to give spherical shapes (Mao and Lee, 2014).

For **FeNi<sub>2</sub>O<sub>4</sub>**, **violarite**, **FeCo<sub>2</sub>O<sub>4</sub>**, **FeCo<sub>2</sub>S<sub>4</sub>**, **FeMn<sub>2</sub>O<sub>4</sub>** and **FeMn<sub>2</sub>S<sub>4</sub>**, there are no studies of the crystal morphologies to the best of our knowledge.



## 1.4 Magnetic and electric properties of spinels

The magnetic properties in most of the (thio)spinel are based on the Néel's two sublattice model of ferrimagnetism (Néel, 1948). These sublattices are defined as the tetrahedral and octahedral positions while the model itself is based on the molecular field method. According to this model, the superexchange interaction between paramagnetic ions occupying different sublattices is negative and stronger than for those cations within any of the sublattices. These interactions lead to the so-called collinear Néel configuration, where the spins in tetrahedral and octahedral sublattices are aligned antiparallely and the total magnetization is the difference between the magnetizations of the two sublattices. Additionally, two other types of magnetic structures can exist in spinel compounds, *i.e.* the Yafet-Kittel triangular canting (Yafet and Kittel, 1952) and the spiral (Kaplan *et al.*, 1961) configurations. Unless otherwise stated, in the below description of the magnetic and electronic properties, all the (thio)spinel are Néel type ferrimagnets.

**Magnetite** is a ferrimagnetic material at ambient conditions and has a Néel temperature ( $T_N$ ) of 850 K, the temperature at which it becomes paramagnetic.  $Fe_3O_4$  is also half-metallic at ambient conditions due to an insulator band gap in the majority channel of the spins, which is associated with the tetrahedral sublattice (Zhang and Satpathy, 1991). Below the Verwey temperature ( $T_V = 122$  K), together with the first-order phase transition,  $Fe_3O_4$  becomes fully insulator (Verwey, 1939).

**Greigite** is also a ferrimagnetic half-metal with a Néel temperature reported for a very wide range going from  $\sim 300$  to  $\sim 530$  °C (Dekkers *et al.*, 2000).

**Chromite, daubréelite, FeCo<sub>2</sub>O<sub>4</sub> and FeMn<sub>2</sub>O<sub>4</sub>** are ferrimagnetic below the Néel temperature ( $T_N = 80$  (Shirane *et al.*, 1964), 180 (Shirane *et al.*, 1964), 450 (Kawano *et al.*, 1976) and 383 K (Van Landuyt *et al.*, 1972) respectively). FeCr<sub>2</sub>O<sub>4</sub> has also a spin rearrangement temperature ( $T_s = 35$  K), below which the spins are no longer collinear and have a spiral structure (Shirane *et al.*, 1964). FeMn<sub>2</sub>O<sub>4</sub> is semiconducting at least up to 900 K (Kulkarni and Darshane, 1985).

Magnetization measured in **FeNi<sub>2</sub>O<sub>4</sub>** (Shafer, 1962) and **FeNi<sub>2</sub>S<sub>4</sub>** (Vaughan and Craig, 1985) shows that these are paramagnetic compounds. As **FeCo<sub>2</sub>S<sub>4</sub>** and **FeMn<sub>2</sub>S<sub>4</sub>** do not occur naturally and have they been synthesised before, there is no experimental information about their magnetic or electronic properties.

## **1.5 Catalytic applications of Fe<sub>3</sub>O<sub>4</sub>**

Magnetite is one of the principal types of iron oxides used as the main component of industrial heterogeneous catalysts because of its stability, availability and cost. Due to its electronic properties, Fe<sub>3</sub>O<sub>4</sub> can catalyse both oxidation/reduction and acid/base reactions (Cornell and Schwertmann, 2003). For example, Fe<sub>3</sub>O<sub>4</sub> is part of the catalysts used in processes such as the production of ammonia (NH<sub>3</sub>) from H<sub>2</sub> and N<sub>2</sub> (the Haber-Bosch process) and the conversion of CO and H<sub>2</sub> into hydrocarbons (Fischer-Tropsch process). Fe<sub>3</sub>O<sub>4</sub> also catalyses the water gas shift (WGS) reaction, which supplies H<sub>2</sub> to the Haber-Bosch and Fischer-Tropsch processes.

### 1.5.1 Haber-Bosch process for the production of ammonia

Ammonia is the primary feedstock for the production of fertilizers and nitric acid. More than 90 % of  $NH_3$  is manufactured through the process described below which was developed by Fritz Haber and Carl Bosch between 1905 and 1910 (Topham, 1985). The reaction of formation of  $NH_3$  from elemental hydrogen and nitrogen can be written as,



As the reaction is exothermic ( $\Delta H = -108.7 \text{ kJ} \cdot \text{mol}^{-1}$ ), the highest equilibrium yield is obtained at low temperatures and high pressures. However, the catalyst-free homogeneous gas phase equation (1.3) is hindered kinetically by the large activation energy (estimated between 230 – 420  $\text{kJ} \cdot \text{mol}^{-1}$  (Appl, 2012)). The largest contribution to the activation energy is due to the high stability of molecular  $N_2$ , which has a dissociation energy significantly larger than that of  $H_2$ .

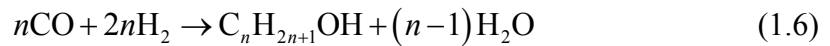
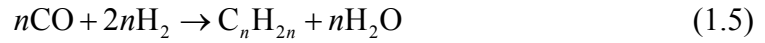
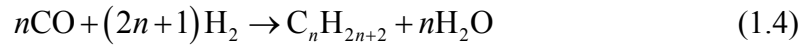
Pure Fe-based heterogeneous catalysts reduce the activation energy of the rate determining step in the mechanism of  $NH_3$  formation to  $81.17 \text{ kJ} \cdot \text{mol}^{-1}$  (Spencer *et al.*, 1982). This step was initially suggested by experiments (Emmett and Brunauer, 1934; Scholten *et al.*, 1959) and later confirmed by microkinetic modelling (Aparicio and Dumesic, 1994) to be the  $N_2$  adsorption and dissociation.  $Fe_3O_4$  is the most suitable industrial catalyst for  $NH_3$  production as portions of its surface can be reduced *in situ* by  $H_2$  into the catalytically active  $\alpha\text{-Fe}$  (Almquist and Crittenden, 1926), where the chemisorption of  $N_2$  is neither too strong nor too weak (Aika *et al.*, 1973; Logan

and Kemball, 1960). The catalyst surface has an interconnected system of pores, which represent 44 – 46 % of the volume of the catalyst granule (Nielsen, 1981), where NH<sub>3</sub> formation takes place. Al<sub>2</sub>O<sub>3</sub>, the structural promoter and one of the additives of the catalyst, forms a solid solution with Fe<sub>3</sub>O<sub>4</sub> (Dry and Ferreira, 1967; Garbassi *et al.*, 1972; Westrik, 1953), which favours  $\alpha$ -Fe crystallites nucleation (Bogdandy *et al.*, 1963) (of high surface area) instead of their growth (Bare *et al.*, 1986). In the catalytically active (reduced) Fe<sub>3</sub>O<sub>4</sub>, the electronic promoter (K<sub>2</sub>O, another additive of the catalyst) is atomically adsorbed and covers 20 – 50 % of the catalyst surface (Ertl, 1983), reducing its electron work function (Appl, 2012). This reduces the activation energy for the dissociative adsorption of N<sub>2</sub> and the adsorption energy of NH<sub>3</sub>, which can desorb easily from the surface leaving it free to interact with more H<sub>2</sub> and N<sub>2</sub> molecules (Ertl, 1983). The activity of the catalyst is also enhanced by trace amounts of other additives, some of which are impurities in the original ore (Bond, 1974; Bridger and Snowden, 1970). During the manufacture of the catalyst, Fe<sub>3</sub>O<sub>4</sub> together with the additives are melted electrically or in electric arc furnaces and the cooled melt is ground to the proper particle size (Appl, 2012).

### 1.5.2 Fischer-Tropsch synthesis

The Fischer-Tropsch process is named after Franz Fischer and Hans Tropsch, who developed it in 1926. This process is the best-known indirect coal liquefaction method where syngas (a mixture of CO and H<sub>2</sub>) is transformed to a variety of useful products, such as substitute natural gas (SNG), gasoline, diesel oil, wax and alcohols (Kaneko

*et al.*, 2012). The non-selective production of these products by the Fischer-Tropsch synthesis can be represented as follows:



where  $n$  is an integer, equation (1.4) represents the reaction of formation of alkanes, equation (1.5) of alkenes and equation (1.6) of alcohols.

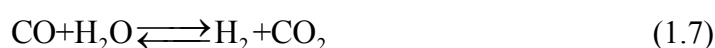
For the above reactions to take place, CO and  $H_2$  molecules need to be activated by a heterogeneous catalyst's surface. There are three theories for the general mechanism of C–C bonds formation in these reactions. The first mechanism postulates that these bonds are formed via polymerization of  $-CH_2-$  fragments. The second pathway proposes that they are formed through the condensation of hydroxymethylene groups ( $-CHOH$ ) with elimination of one  $H_2O$  molecule (Kummer and Emmett, 1953). The third scheme indicates that C–C bonds are formed through the insertion of CO into any of the metal-alkyl bonds (Henrici-Olive and Olive, 1976; Pichler and Schulz, 1970). Nevertheless, in any of these theories, the addition of hydrogen to the carbon intermediate has been suggested to be the rate-determining step (Huff and Satterfield, 1984).

$Fe_3O_4$  is one of the main components of the catalysts normally used for the Fischer-Tropsch synthesis. However, the working catalyst is only achievable once  $Fe_3O_4$  is exposed to the syngas and is reduced to a mixture of  $\alpha$ -Fe and iron carbide ( $\gamma$ - $Fe_5C_2$ ),

with high quantity of remnant Fe<sub>3</sub>O<sub>4</sub> (Satterfield *et al.*, 1986). Cu and a SiO<sub>2</sub> support are additives of the catalyst that promote the reduction of Fe<sub>3</sub>O<sub>4</sub> and avoid the sintering of the  $\alpha$ -Fe phase respectively (Jin and Datye, 2000). Other additives, such as various alkali and alkaline earth metal oxides, increase the basicity of the Fe<sub>3</sub>O<sub>4</sub> catalyst surface, which reduces the CH<sub>4</sub> selectivity during Fischer-Tropsch synthesis (Dry and Oosthuizen, 1968).

### 1.5.3 Water gas shift reaction

The water-gas shift (WGS) reaction is an important step in the production of H<sub>2</sub> for various industrial processes. This reaction is considered as a pre-step in the Fischer-Tropsch synthesis and therefore part of the indirect coal liquefaction process. Initially, coal is reacted with steam and O<sub>2</sub> to produce a mixture of CO and H<sub>2</sub> (syngas mixture). During the water-gas shift reaction, the ratio of H<sub>2</sub> to CO is adjusted to the requirements of the desired (Fischer-Tropsch) synthesis by means of the following equilibrium (Kaneko *et al.*, 2012):



The equilibrium of equation (1.7) is independent of pressure and is moderately exothermic ( $\Delta H = -41.16 \text{ kJ} \cdot \text{mol}^{-1}$ ). This limits the production of H<sub>2</sub> at high temperatures, the condition at which the reaction is kinetically favourable (Rhodes *et al.*, 1995). There are two mechanistic pathways proposed to explain how the water-gas shift reaction occurs: associative or regenerative (Armstrong and Hilditch, 1920). In the associative mechanism, CO and H<sub>2</sub>O molecules are initially adsorbed onto the

catalyst to form an intermediate that decomposes into the H<sub>2</sub> and CO<sub>2</sub>. The regenerative mechanism proposes that H<sub>2</sub>O forms H<sub>2</sub> and oxidises the catalyst's surface, which is the rate-limiting step (Nakamura *et al.*, 1990). This step is followed by the regeneration of the initial state of the catalyst, which oxidises the CO to CO<sub>2</sub>.

Fe<sub>2</sub>O<sub>3</sub>/Cr<sub>2</sub>O<sub>3</sub> are the main components of the modern catalysts used for the high temperature water-gas shift reaction (310–450 °C), where the regenerative mechanism is believed to be the dominant pathway (Rethwisch and Dumesic, 1986). This initial process is followed by a low temperature step using a Cu-based catalyst in order to achieve low-levels output of CO (Rhodes *et al.*, 1995). In the Cu-based catalysts, there is still uncertainty on which is the dominant pathway taking place (Campbell and Daube, 1987; Koryabkina *et al.*, 2003; Liu and Rodriguez, 2007). We are not going to describe the low-temperature catalysts in this section, as these materials and processes are out of the scope of this thesis.

In the high temperature process, the catalyst becomes active after it is carefully reduced to Fe<sub>3</sub>O<sub>4</sub> by the initial syngas mixture (Gonzalez *et al.*, 1986).  $\alpha$ -Fe and iron carbides formed due to over-reduction of Fe<sub>2</sub>O<sub>3</sub> are undesirable (Gonzalez *et al.*, 1986), as they are known to be catalysts of the Fischer-Tropsch process, where H<sub>2</sub> and CO are consumed (Kaneko *et al.*, 2012). The Fe<sup>2+</sup>/Fe<sup>3+</sup> pair occupying the octahedral positions in Fe<sub>3</sub>O<sub>4</sub> acts as a redox couple to dissociate H<sub>2</sub>O into H<sub>2</sub> and adsorbed oxygen (Rhodes *et al.*, 1995). Cr<sub>2</sub>O<sub>3</sub> is a structural promoter, which avoids the thermal sintering of the Fe<sub>3</sub>O<sub>4</sub> crystallites formed (Domka *et al.*, 1983) and keeps a high ratio of the surface area to the mass of the catalyst. Traces of Pb<sup>4+</sup> salts increase the

covalency and electron transport capabilities of Fe<sub>3</sub>O<sub>4</sub>, which favours the H<sub>2</sub>O reduction (Topsøe and Boudart, 1973).

#### 1.5.4 Other applications of Fe<sub>3</sub>O<sub>4</sub> and the (thio)spinel

Fe<sub>3</sub>O<sub>4</sub> has a number of other applications, such as being part of materials for potentially remediating chromium-contaminated groundwater (dos Santos Coelho *et al.*, 2008). A Fe/Fe<sub>3</sub>O<sub>4</sub> composite is the reactive reductant material where surface Fe<sub>B</sub><sup>2+</sup> from Fe<sub>3</sub>O<sub>4</sub> plays an important role in the reaction. As the reduction takes place, metallic Fe transfers an electron to Fe<sub>3</sub>O<sub>4</sub> to reduce Fe<sub>B</sub><sup>3+</sup> and regenerate the active ion. This reactive composite could also be used together with H<sub>2</sub>O<sub>2</sub> for the oxidation of organic contaminants via an heterogeneous Fenton process (Costa *et al.*, 2008; Moura *et al.*, 2006).

Nanosized Fe<sub>3</sub>O<sub>4</sub> particles are another promising component of anode materials with excellent cycling and rate performance for the next generation of high-performance lithium-ion batteries. Amongst the different construction proposals are highly dispersed and superparamagnetic Fe<sub>3</sub>O<sub>4</sub> nanoparticles encapsulated by a carbon matrix forming a homogeneous Fe<sub>3</sub>O<sub>4</sub>@C composite (Cui *et al.*, 2009); superparamagnetic (Zhang and Zhang, 2009) Fe<sub>3</sub>O<sub>4</sub> nanowires carbon coated (Muraliganth *et al.*, 2009) and Cu nanorods covered by a plating of Fe<sub>3</sub>O<sub>4</sub> (Taberna *et al.*, 2006).

Fe<sub>3</sub>O<sub>4</sub> nanoparticles can also have possible application as part of anticancer drug therapies. Fe<sub>3</sub>O<sub>4</sub> magnetic nanoparticles enclosed by human serum albumin can act as drug carriers that can be magnetically guided to the target area and have sustained-



release properties due to the slow decomposition of the albumin (Lin *et al.*, 2007). Fe<sub>3</sub>O<sub>4</sub> nanoparticles capped with tetraheptylammonium can be magnetically oriented to leukemia cells and improve the uptake of the antitumoral drug daunorubicin by them. The nanoparticle binds competitively to a glycoprotein of the membrane of the cell, inhibiting it and synergistically allowing drug accumulation within the cell (Wang *et al.*, 2007).

Fe<sub>3</sub>O<sub>4</sub> magnetic nanoparticles have a further application as one of the components of highly sensitive and selective analytical sensors. These nanoparticles can act as peroxidase mimetics that catalyse the oxidation of a substrate with H<sub>2</sub>O<sub>2</sub> (Wei and Wang, 2008; Zhu and Diao, 2011) or glucose (Wei and Wang, 2008) to give a coloured product and provide a colorimetric detection of these molecules. These types of catalytic properties of Fe<sub>3</sub>O<sub>4</sub> can also offer other great potential applications as biosensors in the future.

The structural analogy between Fe<sub>3</sub>S<sub>4</sub> and FeNi<sub>2</sub>S<sub>4</sub> with certain contemporary enzymes cofactors in the form of (Fe,Ni)S clusters (Russell and Martin, 2004) has led to proposals that these minerals could have played an important catalytic role in the primordial metabolism (Huber and Wächtershäuser, 1997). The iron-sulfur membrane theory, as this origin of life theory is known (Russell and Hall, 1997), suggests that initially FeS and NiS membranes precipitated due to specific pH and ionic conditions near the ocean floor *circa* 4 billion years ago (Russell and Martin, 2004). The first organic molecules were then formed after the reduction of CO<sub>2</sub> catalysed by the oxidation of Fe<sup>2+</sup> ions probably through a mechanism similar to the modern-day

acetyl-coenzyme A pathway (Ferry, 1995; Huber and Wächtershäuser, 1997; Russell and Martin, 2004). Bio-inspired by this theory, the catalytic properties of Fe<sub>3</sub>S<sub>4</sub> and FeNi<sub>2</sub>S<sub>4</sub> towards carbon-activation could lead to economically viable applications to convert industrially produced CO<sub>2</sub> into fine chemicals and mitigate the consequences of climate change.

## **1.6 Objectives of the thesis**

A literature review about the occurrences as well as structural, magnetic, electric and catalytic properties of FeM<sub>2</sub>X<sub>4</sub> (thio)spinel shows the importance of this group of compounds. However, more work is needed to increase the understanding of these properties. In this thesis, we have employed computational modelling tools, which are summarized in Chapter 2, with the aim to study a number of bulk and surface properties of FeM<sub>2</sub>X<sub>4</sub>. Chapter 3 provides details of the calculated equilibrium inversion degree and electronic structure of FeM<sub>2</sub>X<sub>4</sub>. Chapter 4 and 5 present the calculated mechanical properties as well as the structure, stabilities and redox behaviour of the major surfaces of Fe<sub>3</sub>O<sub>4</sub> respectively. Chapter 6 gives a theoretical insight into the initial oxidation of Fe<sub>3</sub>S<sub>4</sub>(001) surface induced by H<sub>2</sub>O. The results presented in these chapters will help to gain a deeper understanding of the surface chemistry and bulk properties of FeM<sub>2</sub>X<sub>4</sub> and will contribute to our general knowledge of the catalytic and electronic applications of these group of materials.

# Methods for materials modelling

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## 2.1 Introduction

In this chapter we review the methods, models and tools for materials modelling that have been used to carry out the research presented in this thesis. We have chosen to use *ab initio* quantum chemistry methods and in particular the density functional theory (DFT) approximation, as it provides details of the electronic structure of the systems under consideration. Within this framework, we have used throughout this thesis the Vienna *Ab-initio* Simulation Package (VASP) (Kresse and Furthmüller, 1996a, 1996b; Kresse and Hafner, 1994, 1993).

We present the time-independent nonrelativistic Schrödinger equation and the indispensable Born-Oppenheimer approximation in order to describe the motion of many electrons in a field of static nuclei. We also introduce the Hartree-Fock method for solving multi-electronic systems. We discuss a different approach: the Hohenberg-Kohn theorems of the density functional theory and how they became applicable through the Kohn-Sham equations as well as two levels of approximation of this theory. We describe two alternatives to improve the exchange term, namely *via* a Hubbard Hamiltonian method or hybrid functionals. We are also concerned with the simplification of the number of electrons to consider in the simulations of periodic

solids and atoms through plane-wave basis sets and pseudopotentials respectively. We present a methodology to improve the description of the long range dispersion interactions. We discuss how the geometry optimization is carried out and how work the different methods for searching them. Finally, we introduce different techniques for the characterization of the optimized geometries, such as vibrational frequencies, density of states and Bader analysis of the charges.

## 2.2 The Schrödinger equation

Electronic structure methods are based on the explicit consideration of the  $M$  nuclei and  $N$  electrons forming a chemical system. The problem of the interaction of these  $M + N$  particles can be described using the non-relativistic time-independent Schrödinger equation:

$$E\Psi = \left[ -\sum_{i=1}^N \frac{1}{2} \nabla_i^2 - \sum_{A=1}^M \frac{1}{2M_A} \nabla_A^2 - \sum_{i=1}^N \sum_{A=1}^M \frac{Z_A}{r_{iA}} + \sum_{i=1}^{N-1} \sum_{j>i}^N \frac{1}{r_{ij}} + \sum_{A=1}^{M-1} \sum_{B>A}^M \frac{Z_A Z_B}{R_{AB}} \right] \Psi \quad (2.1)$$

The above expression is given in atomic units, where  $E$  represents the energy and  $\Psi$  is the wavefunction.  $r_{iA}$ ,  $r_{ij}$  and  $R_{AB}$  are the  $i$ th electron -  $A$ th nucleus,  $i$ th -  $j$ th electrons as well as  $A$ th -  $B$ th nuclei distances, respectively.  $Z_A$  is the atomic number of nucleus  $A$  and  $M_A$  represents the ratio of its mass to the mass of an electron. The Laplace operator ( $\nabla$ ) represents the second derivative with respect to the spatial coordinates of the nucleus or electron. The terms within the operator in the right hand side of the equation (2.1) represent, in this order, the kinetic energy of the electrons; the kinetic

energy of the nuclei; the coulomb attraction between electrons and nuclei; the coulomb repulsion between electrons and the coulomb repulsion between nuclei, respectively.

By solving equation (2.1), it is possible to obtain all the physical-chemical properties (except for the relativistic effects) of the system under study. However, equation (2.1) has the problem of two sets of related variables: electrons and nuclei.

A simplification to the above problem is based on the fact that the mass of an electron is approximately 1830 times smaller than the mass of a proton, for which it is possible to assume that electrons move much faster than nuclei. The Born-Oppenheimer approximation (Born and Oppenheimer, 1927) simplifies the Schrödinger equation by separating electronic and nuclear coordinates in the many-body wavefunction by neglecting the kinetic energy of the nuclei and considering the nuclei repulsion to be constant. The simplified equation describes the motion of electrons in an arrangement of static nuclei:

$$E\Psi = \left[ -\sum_{i=1}^N \frac{1}{2} \nabla_i^2 - \sum_{i=1}^N \sum_{A=1}^M \frac{Z_A}{r_{iA}} + \sum_{i=1}^{N-1} \sum_{j>i}^N \frac{1}{r_{ij}} \right] \Psi \quad (2.2)$$

The Schrödinger equation in the above form only has an exact solution for hydrogen-like atoms (those composed of a nucleus of any size and a single electron) and additional simplifications are required for multi-electronic or poly-atomic systems.

For systems with more than one electron, the coulomb repulsion between electrons is difficult to evaluate and other approximations are required. Among the earlier approximations of the Schrödinger equation were those aimed to reduce the electronic interaction to one-electron problem. This is the foundation of the Hartree-Fock (HF)

method, which considers every electron interacting with a mean-field of all the other electrons. The HF method has the disadvantage that it only correlates the motion of electrons with parallel spins, which makes the total energy given by the HF method to differ by the correlation energy from the exact total energy. Although some refinements have been developed (the so-called post-HF methods) to improve the difference of energies, the density functional theory (DFT) method is the one usually preferred in the context of solid state modelling.

## **2.3 Density functional theory**

### **2.3.1 The Hohenberg-Kohn theorems**

A fresh approach for bypassing the many-body problem of the Schrödinger equation was proposed by Hohenberg and Kohn (1964). They showed that the electronic density  $\rho(\mathbf{r})$  of the ground state of the system uniquely determines the Hamiltonian and therefore all the properties of a physical system, such as the total external potential acting on the electrons  $V(\mathbf{r})$ .

They also proved that a functional  $F[\rho(\mathbf{r})]$  is needed to calculate the energy  $E[\rho(\mathbf{r})]$  of an electronic system. Therefore, combining the two previous theorems, it is possible to express  $E[\rho(\mathbf{r})]$  as:

$$E[\rho(\mathbf{r})] = \int V(\mathbf{r})\rho(\mathbf{r})d\mathbf{r} + F[\rho(\mathbf{r})] \quad (2.3)$$

where  $V(\mathbf{r})$ , for atomic systems, is the coulomb attraction between nuclei and electrons and  $F[\rho(\mathbf{r})]$  contains the kinetic energy as well as inter-electronic coulomb repulsion, exchange and correlation energies.

The variational principle is used to minimize the value of  $E[\rho(\mathbf{r})]$  in order to obtain the ground state energy of the real system, the exact  $\rho(\mathbf{r})$  and the rest of its properties. Despite all of the above demonstrations, the new approach still faced the difficulty of solving the electron-electron term in the Hamiltonian, see equation (2.2).

### 2.3.2 Kohn-Sham equations

Kohn and Sham (1965) refined the early density functional theory by stating that a fictitious system of non-interacting electrons has the same density as the real system of interacting electrons, whose energy can be separated into the following terms:

$$E[\rho(\mathbf{r})] = T_{ni}[\rho(\mathbf{r})] + V_{ne}[\rho(\mathbf{r})] + V_{ee}[\rho(\mathbf{r})] + E_{xc}[\rho(\mathbf{r})] \quad (2.4)$$

where  $T_{ni}[\rho(\mathbf{r})]$  represents the kinetic energy of the non-interacting electrons,  $V_{ne}[\rho(\mathbf{r})]$  represents the nuclei-electron interaction,  $V_{ee}[\rho(\mathbf{r})]$  represents the inter-electronic repulsion and  $E_{xc}[\rho(\mathbf{r})]$  represents the exchange-correlation energy. The last term is a correction to the kinetic energy and the non-classical inter-electronic repulsion due to exchange and correlation.

In order to minimize the energy  $E[\rho(\mathbf{r})]$ , it is convenient to express it as a function of one-electron orbitals  $\psi_i$ , as:

$$E[\rho(\mathbf{r})] = \sum_{i=1}^N \left\langle \psi_i \left| -\frac{1}{2} \nabla^2 - \sum_{A=1}^M \frac{Z_A}{|\mathbf{r} - \mathbf{R}_A|} + \frac{1}{2} \int \frac{\rho(\mathbf{r}')}{|\mathbf{r} - \mathbf{r}'|} d\mathbf{r}' \right| \psi_i \right\rangle + E_{xc}[\rho(\mathbf{r})] \quad (2.5)$$

where

$$\rho(\mathbf{r}) = \sum_{i=1}^N |\psi_i|^2 \quad (2.6)$$

The problem of finding the one-electron orbitals that minimize the equation of energy is then solved via the Kohn-Sham equation:

$$\hat{h}^{KS} \psi_i = \left[ -\frac{1}{2} \nabla^2 - \sum_{A=1}^M \frac{Z_A}{|\mathbf{r} - \mathbf{R}_A|} + \frac{1}{2} \int \frac{\rho(\mathbf{r}')}{|\mathbf{r} - \mathbf{r}'|} d\mathbf{r}' + V_{xc}(\mathbf{r}) \right] \psi_i = \epsilon_i^{KS} \psi_i \quad (2.7)$$

where the functional derivative  $V_{xc}(\mathbf{r})$  is equal to  $\delta E_{xc}[\rho(\mathbf{r})]/\delta\rho(\mathbf{r})$ .

The Kohn-Sham equation is then solved self-consistently, which means that a model density is given to the equation (2.4) to obtain an energy that is used to solve equation (2.7) and find the new density  $\rho(\mathbf{r})$  from equation (2.6).

However, the form of  $E_{xc}[\rho(\mathbf{r})]$  is important in DFT and two approximations for its calculation are discussed in the next section.

### 2.3.3 Exchange-correlation functionals: LDA and GGA

In this section, we discuss two levels of approximation for the calculation of the exchange-correlation energy, namely the local density approximation (LDA) and the generalized gradient approximation (GGA).



In the LDA (or LSDA, after Local Spin Density Approximation, for spin polarized systems) approximation, the exchange-correlation energy is calculated as:

$$E_{xc}^{LDA} = \int d^3\mathbf{r} \rho(\mathbf{r}) \varepsilon_{xc}^{LDA} \quad (2.8)$$

where  $\varepsilon_{xc}^{LDA}$  is the exchange-correlation energy per particle of a uniform electron gas (jellium). The Vosko, Wilk and Nusair (VWN) functional, one of the most common of this type, was developed by fitting the results from Quantum Monte Carlo Calculations (Ceperley and Alder, 1980) to mathematical expressions (Perdew and Zunger, 1981; Vosko *et al.*, 1980). The LDA is a good approximation for systems where the density varies slowly or moderately over space, like metals.

A more elaborated approach to calculate the exchange-correlation energy is by considering the variation of the electronic density in the vicinity of the integration point and not only its value in such a point, as in LDA. By making  $\varepsilon_{xc}$  depend additionally on the gradients of the electronic density  $\nabla\rho(\mathbf{r})$ , it is possible to introduce non-local effects on the functional, which leads to the generalized gradient approximation (GGA):

$$E_{xc}^{GGA} = \int d^3\mathbf{r} (\rho(\mathbf{r}), \nabla\rho(\mathbf{r})) \quad (2.9)$$

There are several implementations of GGA functionals and all of them describe more accurately the system under investigation than LDA functionals. Popular GGA exchange-correlation functionals include the one developed by Perdew and Wang (PW91) (Perdew *et al.*, 1993, 1992) which was constructed using data from LDA, improving the results of pure local approximation methods (Burke *et al.*, 1998, 1995;

Hammer *et al.*, 1993; Stixrude *et al.*, 1994). Another example is the Perdew, Burke and Ernzerhof (PBE) (Perdew *et al.*, 1997, 1996a) and its revision for solids PBEsol (Perdew *et al.*, 2008). In this thesis we have used the PW91 functional in Chapters 4 and 6, PBE functional in Chapter 5 and PBEsol functional in Chapter 3. For example, the optimized lattice parameter of Fe<sub>3</sub>O<sub>4</sub> obtained using the PW91 functional (8.390 Å) reproduces in very good agreement the experimental one (8.390 Å), while PBE overestimates it slightly (8.398 Å) and PBEsol underestimates it (8.345 Å). Note that the above results were obtained including the corrections described in the following sections that affect the performance of pure GGA functionals.

## **2.4 DFT + *U* method**

The electronic self-interaction is another shortcoming associated with most of the DFT methods. It arises when the correlation term is not treated exactly and produces artificially delocalized electron densities. In materials with strongly interacting and very localized electrons, such as in many transition metal oxides, the DFT method is unable to reproduce a realistic electronic structure, as it fails to open the band gap (Leung *et al.*, 1991; Terakura *et al.*, 1984) or underestimates it (Sawatzky and Allen, 1984; Zaanen *et al.*, 1985). This DFT limitation is not only exclusive to transition metal oxides, but is also found in rare earth compounds and some non-metal oxides (Pacchioni, 2001).

The incorporation of a Hubbard Hamiltonian (Hubbard, 1963) is one of the solutions used to overcome the electron self-interaction in DFT, which is known as DFT + *U*

(Anisimov *et al.*, 1991). The added  $U$  parameter enhances the on-site Coulomb repulsion between electrons in the same  $d$ -bands by penalizing the double occupation of these bands. This can be seen as an increment in energy associated with the introduction of an electron in certain  $d$ -orbitals, *i.e.*  $U = E(d^{n+1}) + E(d^{n-1}) - 2E(d)$ , which opens band gaps close to the experimental ones or those obtained from more demanding computational methods.

There are two types of DFT +  $U$  methods and in this thesis we have used the Hamiltonian in the version proposed by Dudarev *et al.* (1998) which takes the form:

$$E_{DFT+U} = E_{DFT} + \frac{U_{\text{eff}}}{2} \sum_{\sigma} [\rho^{\sigma} - \rho^{\sigma} \rho^{\sigma}] \quad (2.10)$$

where  $\rho^{\sigma}$  is the on-site density matrix of the  $d$ -electrons with spin  $\sigma$  and  $U_{\text{eff}}$  is equal to the difference between  $U$ , the spherically averaged Hubbard parameter, and  $J$ , the screened exchange energy.

The DFT +  $U$  method only makes physical sense when  $U_{\text{eff}}$  and  $[\rho^{\sigma} - \rho^{\sigma} \rho^{\sigma}]$  are both bigger than 0. The latter can be shown easily in the idempotency limit of  $\rho^{\sigma}$ . This means that the eigenvalue of this matrix is either 0 to 1, which are values associated with fully unoccupied or occupied  $d$ -levels. The net result is a DFT +  $U$  energy which is always bigger than the pure DFT energy.

The DFT +  $U$  method can be applied to both local and gradient corrected functionals. However, better results are typically obtained with GGA while different  $U$  values are usually required for each type of functional to obtain comparable results (Rohrbach *et*

*al.*, 2003). The method also affects geometrical factors indirectly after the variation of electronic properties (Rohrbach *et al.*, 2003; Rollmann *et al.*, 2004). In this thesis, the  $U_{\text{eff}}$  values used to describe adequately the  $d$  bands of each transition metal ion were dependant of the functional used. The optimal  $U_{\text{eff}}$  values were determined by fitting the calculated band gap to the experimental one, where this information was available, or the calculated positions of the  $d$  band centres to those obtained from using hybrid functionals, a more demanding calculation method described in the following section.

## 2.5 Hybrid functionals

Another solution used to improve the description of the exchange term in DFT calculations is based on the partial ( $0 < a < 1$ ) incorporation of an exact exchange part from HF in hybrid functionals:

$$E_{xc} = (1-a)E_x^{\text{DFT}} + aE_x^{\text{HF}} + aE_c^{\text{HF}} \quad (2.11)$$

The incorporation of the non-local HF exchange part also provides some degree of self-interaction cancellation, as this term and the classical Coulomb interaction have opposite signs. The use of only the exact HF exchange,  $a = 1$  in equation (2.11), worsen the hybrid functional results as there is an important error cancellation element taking place between the DFT exchange and correlation functionals (Ivanov *et al.*, 1999).

In Chapter 3 of this thesis we have used the Heyd-Scuseria-Ernzerhof (HSE) functional (Heyd *et al.*, 2006, 2003) which includes 25% of the HF exchange and is one of the most widely used functionals in solid state modelling.

## 2.6 The electronic problem in periodic solids

So far, we have seen how several methods are able to break down the multi-electronic problem into accurate one-electron expressions. However, for crystalline solids, symmetry elements can also be taken into account to reduce the number of atoms, and therefore electrons, considered in the simulation of those in the unit cell. In this section we analyse how plane-wave basis sets are able to handle this simplification.

### 2.6.1 Bloch's theorem

The wavefunction of a free electron is described by a plane wave  $\psi \sim e^{i\mathbf{k}\cdot\mathbf{r}}$  where the points with constant value form a plane perpendicular to the vector  $\mathbf{k}$ . Another property of the wavefunction of one electron  $\psi_{i,\mathbf{k}}(\mathbf{r})$  moving in a periodic potential is its similarity to the one of a free electron  $e^{i\mathbf{k}\cdot\mathbf{r}}$  only modulated by the function  $f_{i,\mathbf{k}}(\mathbf{r})$  (Bloch, 1929):

$$\psi_{i,\mathbf{k}}(\mathbf{r}) = f_{i,\mathbf{k}}(\mathbf{r})e^{i\mathbf{k}\cdot\mathbf{r}} \quad (2.12)$$

The function  $f_{i,\mathbf{k}}(\mathbf{r})$  also has the same periodic character as the crystal. This means that  $f_{i,\mathbf{k}}(\mathbf{r})$  has the same value when the input argument is  $\mathbf{r}$  or any translational vector  $\mathbf{T}$  with the same periodicity of the crystal.

The expansion of  $f_{i,\mathbf{k}}(\mathbf{r})$  as a Fourier series of the vectors  $\mathbf{G}$  in the reciprocal lattice:

$$f_{i,\mathbf{k}}(\mathbf{r}) = \sum_{\mathbf{G}} c_{i,\mathbf{k},\mathbf{G}} e^{i\mathbf{G}\cdot\mathbf{r}} \quad (2.13)$$

where the vectors  $\mathbf{G}$  are defined by the expression  $e^{i\mathbf{G}\cdot\mathbf{T}} = 1$ .

From the above equations, it is easy to see that solutions for wavefunctions with index  $\mathbf{k}+\mathbf{G}$  are identical to those with index  $\mathbf{k}$ . Therefore, it is enough to find solutions only for the values of  $\mathbf{k}$ -points in the first Brillouin zone, which is the primitive cell in reciprocal space.

There are several methods aimed at providing good choices of  $\mathbf{k}$ -points such as the improved tetrahedron method (Blöchl *et al.*, 1994) which breaks up the cell in the reciprocal space into tetrahedra as well as the Monkhorst and Pack method (Monkhorst and Pack, 1976), that generates a set of special points in the Brillouin zone.

### 2.6.2 Plane-wave expansion of the wavefunctions

Each wavefunction can also be expressed as an expansion in a basis set of planes waves by substituting equation (2.13) in (2.12):

$$\psi_{i,\mathbf{k}}(\mathbf{r}) = \sum_{\mathbf{G}} c_{i,\mathbf{k}+\mathbf{G}} e^{i(\mathbf{k}+\mathbf{G})\cdot\mathbf{r}} \quad (2.14)$$

The electronic wavefunction is only described exactly by an infinite plane-wave basis set. However, in practice, as the  $c_{i,\mathbf{k}+\mathbf{G}}$  coefficients tend to zero for plane-waves of high kinetic energy, it is truncated to include only those plane waves with kinetic energy  $(\hbar/2m)|\mathbf{k}+\mathbf{G}|^2$  below certain cut-off.

Since the wavefunction  $\psi_{i,\mathbf{k}}(\mathbf{r})$  depends on the plane wave coefficients  $C_{i,\mathbf{k}+\mathbf{G}}$ , the problem of solving the Kohn-Sham equation is reduced to find the set of  $C_{i,\mathbf{k}+\mathbf{G}}$  that minimizes the energy.

Although the size of the wavefunction is determined by the cut-off of the kinetic energy of the plane waves, it is still large for systems that comprise both the core and valence electrons. In the next section, we are going to analyse the pseudopotential approximation that reduces this problem by considering explicitly only the valence electrons of the system.

## **2.7 Pseudopotentials**

The pseudopotential theory also aims to reduce the complexity of the calculations. It works by replacing the Coulomb potential of the core electrons and nucleus with a potential acting on the valence electrons, based on the low chemical reactivity of the core electrons.

One of the most common forms are the norm-conserving pseudopotentials (NCP) which were developed from atomic calculations. This type of pseudopotential can then be subsequently used in calculations where those atoms are also combined forming compounds.

In the core region of any atom, the core wavefunctions oscillate rapidly due to the strong Coulomb potential. However, under the NCP methodology, this part of the

wavefunction is replaced by a soft nodeless pseudo-wavefunction with the same charge as the all-electron wavefunction within this region (Hamann *et al.*, 1979).

There are several variations of this approach, like the ultrasoft pseudopotentials (USPP). In the USPP methodology, the charge of the core electrons is allowed to change, whose variation is compensated with the introduction of localized atom-centred augmentation charges (Vanderbilt, 1990).

### 2.7.1 The projector augmented-wave method

The most robust of the pseudopotential methods developed so far is the projector augmented-wave (PAW) method (Blöchl, 1994), which borrows ideas from the all-electron linear augmented plane-wave (LAPW) method (Andersen, 1975).

In the PAW approximation, the wavefunction can be expressed as:

$$\psi(\mathbf{r}) = \tilde{\psi}(\mathbf{r}) + \sum_{\Lambda} [\phi_{\Lambda}(\mathbf{r}) - \tilde{\phi}_{\Lambda}(\mathbf{r})] \langle \tilde{p}_{\Lambda} | \tilde{\psi} \rangle \quad (2.15)$$

where  $|\psi\rangle$  and  $|\tilde{\psi}\rangle$  are the wavefunction and pseudo-wavefunction respectively,  $|\phi_{\Lambda}\rangle$  and  $|\tilde{\phi}_{\Lambda}\rangle$  are the one-electron Schrödinger equations for the isolated atom (partial waves) and auxiliary pseudo partial waves respectively and  $\tilde{p}_{\Lambda}$  are the projector functions.

In this formalism,  $|\psi\rangle$  behaves like an atom within the atomic (augmentation) regions and outside (interstitial regions), it is identical to  $|\tilde{\psi}\rangle$ . The basis set in the augmentation region is formed by the solutions of  $|\phi_{\Lambda}\rangle$ , which have a nodal behaviour.



Within the augmentation regions,  $|\tilde{\psi}\rangle$  is cancelled out by the expansion of  $|\tilde{\phi}_\Lambda\rangle$  that is chosen in such a way that equals  $|\phi_\Lambda\rangle$  in the interstitial regions.

Although equation (2.15) is exact for a complete expansion of  $|\phi_\Lambda\rangle$ , this term is in practice truncated, which contributes to its fast convergence. This also leads to some contribution of  $|\tilde{\psi}\rangle$  in the augmentation regions.

In this method, while core electrons are considered frozen at the atomic solutions, the full all-electron wavefunction is used, which enables the calculation of properties that depend on the full charge and spin density, such as hyperfine parameters (Cottenier *et al.*, 2005). Moreover, the convergence of  $|\tilde{\psi}\rangle$  is faster in PAW than in NCPP and USPP due to the truncation of  $|\phi_\Lambda\rangle$ .

We have used the PAW method in the result chapters of this thesis in the implementation in VASP by Kresse and Joubert (1999).

## 2.8 Dispersion interaction correction methods

Another limitation of any implementation of pure DFT is its lack of a proper way to describe long-range dispersion interactions. Due to the local character of its functionals, the method fails to correlate the electronic movement of remote atoms (Ruzsinszky *et al.*, 2005). The most common form to overcome this restriction is to

add a correction ( $E_{\text{vdW}}$ ) within certain cutoff to the conventional Kohn-Sham DFT energy ( $E_{\text{KS-DFT}}$ ):

$$E_{\text{DFT-vdW}} = E_{\text{KS-DFT}} + E_{\text{vdW}} \quad (2.16)$$

The correction term ( $E_{\text{vdW}}$ ) can be calculated using a dispersion interaction method. Among these, one of the most robusts is the D2 method of Grimme (2006), which has been proved to provide better structural and mechanical energies predictions in crystals of different nature in comparison to standard DFT functionals, at low computational costs (Bučko *et al.*, 2010) and is the one used in this thesis. According to the D2 method, the  $E_{\text{vdW}}$  contribution is expressed as:

$$E_{\text{vdW}} = -\frac{s_6}{2} \sum_{A=1}^M \sum_{B=1}^M \sum_L \frac{C_{6,AB}}{R_{AB,L}^6} f_{d,6}(R_{AB,L}) \quad (2.17)$$

where the sums are over the total number of atoms  $M$ ,  $C_{6,AB}$  is the dispersion coefficient for the atom pair  $AB$ ,  $R_{AB,L}$  represents the distance between atom  $A$  located in the reference cell and atom  $B$  in the translation of the unit cell  $L$  and  $s_6$  is a global scaling parameter that has been optimized for different DFT functionals.  $f_{d,6}$  is a Fermi-type damping function introduced to minimize contributions from interactions within typical bond distances calculated as:

$$f_{d,6}(R_{AB,L}) = \frac{1}{1 + e^{-d(R_{AB}/R_{\text{vdW-}AB} - 1)}} \quad (2.18)$$

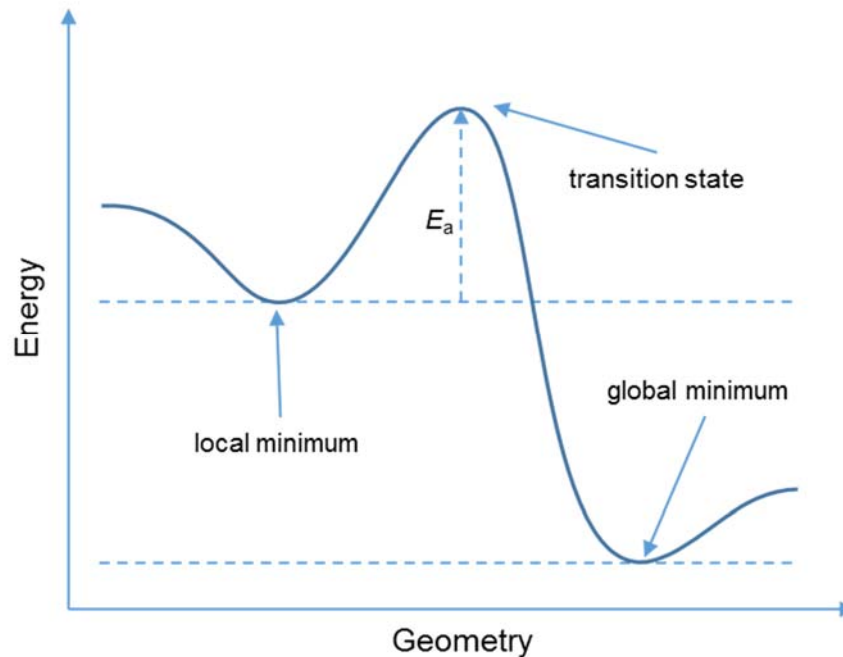
where  $d$  is the damping parameter.

The dispersion coefficient  $C_{6AB}$  is calculated using the geometric mean of the atomic  $C_{6A}$  and  $C_{6B}$  parameters.  $R_{\text{vdW-}AB}$  is the sum of the atomic van der Waals radii of the atoms  $A$  and  $B$  and together with the atomic  $C_{6A}$  have been tabulated for each element and have been determined in a rather non-sensitive way to the chemical environment.

The D2 method has been subject of variations, such as the D3 method of Grimme *et al.* (2010), the D3 (zero) damping method (Grimme *et al.*, 2011), the Tkatchenko-Scheffler (TS) method (Tkatchenko and Scheffler, 2009), the TS + SCS self-consistent screening method (Tkatchenko *et al.*, 2012). However, D3 and D3(zero) method add a higher level of complexity to the expressions and TS as well as TS + SCS make strongly ionic systems to outperform (Bučko *et al.*, 2013).

## 2.9 Geometry optimizations

In this section, we comment on the optimization of atomic positions and cell parameters. These procedures are based not only on finding the minimum of the electronic energy but also of the inter-nuclear Coulomb energies (total energy, by combining both) at 0 K, see **Figure 2.1**.



**Figure 2.1.** Profile representation of a local and global minima separated by a transition state, where  $E_a$  is the activation energy.

### 2.9.1 Optimisation of ionic positions: the conjugate gradients method

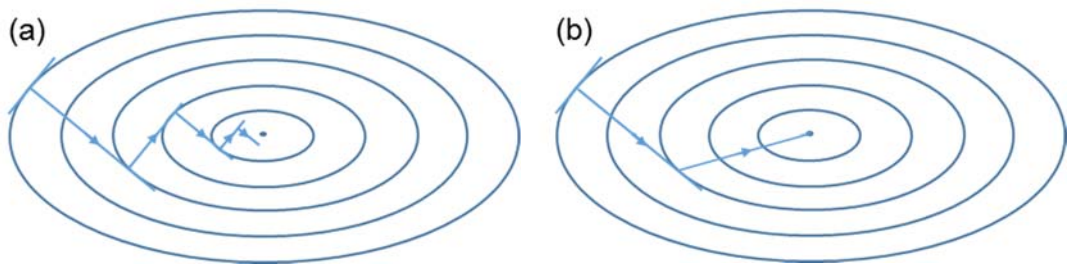
The conjugate gradients (CG) is one among the various algorithms (Gill *et al.*, 1981) developed to find the minimum of a function of several variables. In the context of an ionic system, this method works by calculating the energy function  $E(\mathbf{R})$  and its gradient with respect to the ion's (nuclei) coordinates  $\mathbf{R}$ . As  $-\partial E(\mathbf{R})/\partial \mathbf{R}$  is, by definition, the force  $\mathbf{F}$  on the ions, its calculation is reduced to solve the Hellmann-Feynman theorem for a given system.

The CG method is based on the steepest descent (SD) algorithm, where atoms are moved in the direction of  $\mathbf{F}$ , see **Figure 2.2 (a)**. In the SD technique, the evaluation

of  $E(\mathbf{R})$  is first carried out along a line at regular intervals between two points. For a given initial position  $\mathbf{R}_1$ , the new position will be:

$$\mathbf{R}_2 = \mathbf{R}_1 + b_1 \mathbf{F}(\mathbf{R}_1) \quad (2.19)$$

where  $b_1$  is chosen to make  $\mathbf{F}(\mathbf{R}_2) \cdot \mathbf{F}(\mathbf{R}_1)$  equal to zero.



**Figure 2.2.** Schematic illustration of (a) the steepest descent (SD) and (b) the conjugate gradients (CG) algorithms.

The new gradient  $\mathbf{F}(\mathbf{R}_2)$  is perpendicular to the previous line and the procedure is repeated from the new point to the direction of  $\mathbf{F}(\mathbf{R}_2)$  until the minimum is located.

The SD method has the disadvantage of only allowing perpendicularly related directions in searching for a minimum. This causes the SD algorithm to require, in some cases, a large number of iterations to converge.

Although the first step of the CG and SD techniques is the same, in the CG method, the direction of successive displacements is allowed to take any direction, which can be expressed as:

$$\mathbf{R}_{m+1} = \mathbf{R}_m + b_m \mathbf{S}_m \quad (2.20)$$

Now the search vector  $\mathbf{S}_m$  contains information from the gradient and the search direction from the previous step:

$$\mathbf{S}_m = \mathbf{F}(\mathbf{R}_m) + \gamma_m \mathbf{S}_{m-1} \quad (2.21)$$

where the scalar coefficient  $\gamma_m$  is zero for  $m=1$  and for the successive steps it is defined by Fletcher and Reeves (1964) as:

$$\gamma_m = \frac{\mathbf{F}(\mathbf{R}_m) \cdot \mathbf{F}(\mathbf{R}_m)}{\mathbf{F}(\mathbf{R}_{m-1}) \cdot \mathbf{F}(\mathbf{R}_{m-1})} \quad (2.22)$$

The main advantage of the CG with respect to the SD method is that it reduces considerably the number of iterations (search steps) needed to locate the minimum of the energy function. In the CG algorithm, search directions are optimally independent (*conjugate*) from each other, which allows for a quadratic function of  $M$  variables to find the minimum in  $M$  steps, see **Figure 2.2 (b)**.

In the VASP code, after the initial SD iteration, the subsequent line minimization of the CG method has been programmed in several steps: i) a trial step into the search direction (scaled gradients) is carried out, where the energy and forces are recalculated. ii) From the change of the energy and forces calculated in the previous step, the total energy is cubically (or quadratically) interpolated and its approximate minimum is calculated, to where the corrector step is performed. iii) After the corrector step, the forces and energy are recalculated and VASP checks whether there is a significant component of the forces parallel to the previous search direction. If this is the case, the line minimization is improved by further corrector steps.

In the above explanation, we have assumed that the energy function has a single minimum. In the case that it has several minima, the method described will locate the minimum in whose basin the initial sampling point lies.

### 2.9.2 Relaxation of cell parameters: Pulay stress and equation of state method

If not only the atoms' positions but also the cell parameters are being optimized, then the "Pulay stress" may arise (Francis and Payne, 1990).

The reason for this error is that plane wave basis set is not complete with respect to changes of the volume. It means that the energy cut-off and size of the reciprocal lattice cell determine the number of basis functions. The variation of the volume of the crystal cell, due to the optimization of the lattice parameter, will change the number of plane waves in the basis set for the same energy cut-off. The effect of this error is equivalent to a pressure bigger than 0, or stress which tends to decrease the volume.

Usually, setting an energy cut-off ~30% higher than that required for energy convergence is enough for achieving the stress tensor convergence. The higher cut-off has, however, the disadvantage of making the calculations more computationally demanding.

An alternative method to avoid the Pulay stress is to carry out volume conserving relaxations, where only ion coordinates and cell shape are allowed to relax. Therefore, the basis set is constant and this type of relaxation does not have the same problems, as the Pulay stress depends mainly on the volume. The resulting energy *versus* volume points are fitted to a cubic equation of state, whose minimum gives the equilibrium volume of the cell.

### 2.9.3 Transition states

The transition state is at the top of the lowest energy path (saddle point) between two stable configurations and it defines the reaction coordinate for transitions such as chemical reactions or diffusion processes, see **Figure 2.1**. Finding this point also allows the estimation of the activation energy barrier required for this process to happen.

Among the different methods developed to find saddle points (Henkelman *et al.*, 2002), in this thesis we have used a combination of two: the climbing image nudged elastic band (cNEB) method (Henkelman *et al.*, 2000; Sheppard *et al.*, 2008) and the improved dimer method (IDM) (Heyden *et al.*, 2005). The cNEB is based on the NEB (Jónsson *et al.*, 1998; Mills *et al.*, 1995; Sheppard *et al.*, 2008) method, where a series of images along the reaction coordinate (band) are created and kept equidistant during relaxation by adding spring forces between. A constrained optimization of all images except the initial and final ones is carried out using the residual minimisation method-direct inversion in the iterative subspace (RMM-DIIS) (Pulay, 1980; Wood and Zunger, 1985). This is a quasi-Newton algorithm based only on the forces and stress tensor in which the norm of the residual vector is minimised by diagonalising the inverse of the Hessian matrix. The climbing image NEB (cNEB) is a simplification of this method, where the total number of images are reduced and the accuracy of the saddle point is increased. In the cNEB, the image with highest energy is freed from the spring constraints and its force along the tangent is inverted to allow this image to maximize its energy along the band and minimize it in all other directions. The saddle



point is the optimized image. A further modification of cNEB method is the improved tangent (Henkelman and Jónsson, 2000; Sheppard *et al.*, 2008), designed to avoid possible kinks along the band.

The IDM is the form in which the dimer method (Henkelman and Jónsson, 1999; Olsen *et al.*, 2004) has been implemented in VASP. This algorithm has been designed to find the transition state by knowing only the initial configuration and giving to the calculation the initial dimer axis, which is the one with the unstable (negative) vibrational mode.

## **2.10 Analysis of optimized geometries**

In this section we present the methodologies we have used to obtain the properties that characterise the optimized geometries, such as: vibrational frequencies, density of states, atomic charges and atomic spin densities.

### **2.10.1 Vibrational frequencies**

In any optimized geometry, the gradients of each vibrational mode are equal to zero. The minimum, either local or global, has all second derivatives positive, which means that all vibrational frequencies are real. A transition state, on the other hand, has one imaginary frequency, for which one of the second derivatives is negative.

In VASP, the second derivative from the energy gradients variation is calculated numerically from small displacements (in the harmonic region) of each atom at each Cartesian coordinate. In systems composed by a surface and an adsorbate, the phonons

of the former and the vibrational frequencies of the latter can be, to a good approximation, considered to be decoupled. Therefore, the calculations can be further simplified by neglecting the phonons of the surface. The Hessian matrix (matrix of the second derivative of the energy with respect to the atomic positions) is determined from the forces. Its eigenvalues are the vibrational frequencies and the eigenvectors are the vibrational normal modes of the system.

### 2.10.2 Density of states

In periodic solid systems, where there is a large number of atoms, the individual discrete energy levels are so close together that they form continuous bands. Density of states (DOS) plots are a convenient way to characterise these energy bands as they represent the number of states available to be occupied by electrons per unit cell at a specified energy. The DOS also hold information about the site-projected DOS (PDOS) as well as the up ( $\alpha$ ) and down ( $\beta$ ) electronic states. PDOS are essential to study the bands involved in chemical bonds. Modifications in their intensity and position indicate charge transfers as well as ionic or covalent interactions.

### 2.10.3 Bader analysis of the charges

The ‘atoms in molecules’ theory was proposed by Bader based initially on the Lewis model and the Valence Shell Electron Pair Repulsion (VSEPR) for the topological analysis of the electronic density (Bader, 1994, 1990; Bader *et al.*, 1994, 1988). This is a methodology for partitioning atomic charges which is also applicable and convenient to use in condensed matter as it is based upon the electronic density and its gradient, which are magnitudes easily obtained from DFT calculations. The chemical

bond between two atoms has the highest electronic density between the two nuclei where the electron density gradient vectors start and end. ‘Atoms in molecules’ simply defines an atom as bound by a cavity whose surface has zero flux of the gradient vectors. Several atomic properties, such as charge and spin density can be integrated over this space and give a result not sensitive to the basis set used, unlike wavefunction population schemes (Ángyán *et al.*, 1994; De Proft *et al.*, 2002; Wiberg and Rablen, 1993).

# 3

## **Inversion thermodynamics and electronic structure of $\text{FeM}_2\text{X}_4$ (thio)spinel ( $M = \text{Cr, Mn, Fe, Co, Ni}$ ; $X = \text{O, S}$ )**

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### **3.1 Introduction**

The electronics industry has been revolutionized over the last four decades due to the continuous miniaturization of integrated circuits. Spintronics, short for spin electronics, has emerged as the basis for the next generation of electronic devices (Felser *et al.*, 2007). The concept of spintronics is to take advantage of both the electron charge and spin in solid-state systems, and therefore its applications require magnetic materials with highly spin-polarized electrons at the Fermi energy (Žutić *et al.*, 2004). This can be achieved by half-metallic ferrimagnets (HMF) (Coey and Venkatesan, 2002) with Curie temperature higher than room temperature. The spin-polarized density of states (DOS) of these compounds has a marked asymmetry around the Fermi energy, where one of the spin channels is a conductor while the other one

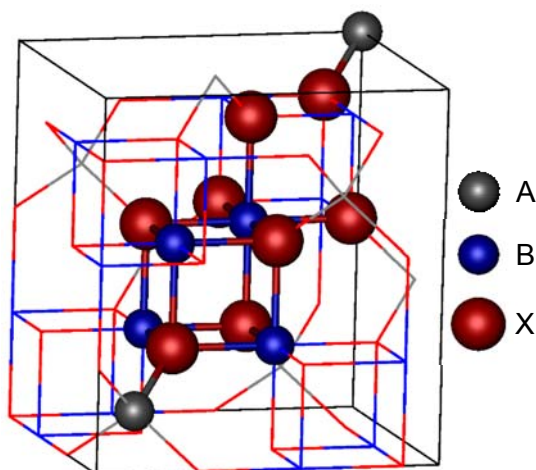
behaves as an insulator (de Groot *et al.*, 1983), making them electronic spin filters. Spintronic applications are based on spin valves (Nozaki *et al.*, 2013; Sukegawa *et al.*, 2012), where two HMF layers are sandwiching a non-magnetic layer. In spintronic applications of high efficiency, the resistivity of the spin valve is required to be extremely sensible to the magnetic field (magnetoresistance) (Felser *et al.*, 2007).

The magnetoresistive behavior (Berdunov *et al.*, 2004b; Eerenstein *et al.*, 2002), and the half-metallic and ferrimagnetic (Kida *et al.*, 2011; Piekarz *et al.*, 2010; Roldan *et al.*, 2013; Zhang and Satpathy, 1991) nature of the inverse spinel magnetite ( $Fe_3O_4$ ), together with the ubiquity of this iron oxide (Cornell and Schwertmann, 2003), indicates its suitability for spintronic applications (Coey and Chien, 2011; Felser *et al.*, 2007; Szotek *et al.*, 2006). The origin of these properties in  $Fe_3O_4$  has been traditionally rationalized in terms of its inverse spinel structure. The ferrimagnetism in  $Fe_3O_4$  arises from the antiparallel alignment of the magnetic moments of the ions in the tetrahedral and octahedral sublattices (which is known as collinear Néel configuration) (Néel, 1948), while the hopping of the extra electron in the minority channel of the spins explains the half-metallic properties (Zhang and Satpathy, 1991). Greigite ( $Fe_3S_4$ ) has been shown to have a similar electronic structure to its oxide counterpart  $Fe_3O_4$  (Roldan *et al.*, 2013). Both compounds are sometimes found associated with other transition metals of similar ionic radii (Shannon, 1976) and valence as Fe, such as Mn, Co, Ni and Cr (Slick, 1980), forming spinel compounds of formula  $FeM_2X_4$  (Brabers, 1995). In these systems,  $M$  represents the transition metal and  $X$  represents the oxygen or sulfur atom, where the sulfide spinels are usually called

thiospinels (Charnock *et al.*, 1990; Vaughan and Craig, 1985; Vaughan and Tossell, 1981). The substituted spinels could retain the type of magnetic behavior of their parent compounds (magnetite or greigite), which is driven by a negative superexchange interaction that is stronger between ions occupying different sublattices than between ions within the same sublattice (Néel, 1948).

The crystal structure of a (thio)spinel is face-centered-cubic and the space group is  $Fd\bar{3}m$ . The cubic unit cell contains eight units of  $FeM_2X_4$  where the 32 anions are in a cubic closed packed arrangement, while 8 of the tetrahedral holes and 16 of the octahedral ones are occupied by all the cations, see **Figure 3.1**. As originally suggested by Barth and Posnjak (1932), different cation arrangements of the (thio)spinel formula can be rewritten as  $(Fe_{1-x}M_x)_A (Fe_xM_{2-x})_B X_4$ , where A and B denote tetrahedral and octahedral sites respectively, while  $x$  is the degree of inversion. In normal spinels ( $x = 0$ ), Fe ions occupy exclusively the A sublattice and  $M$  is confined to the B sublattice. In inverted spinels ( $x = 1$ ), the A sublattice holds half of the  $M$  cations and the B sublattice is equally populated with Fe and  $M$  ions. When  $0 < x < 1$ , Fe and  $M$  have an intermediate degree of distribution within the A and B sublattices. For all the inversion degrees, the  $Fd\bar{3}m$  symmetry of the spinel is often retained, as long as all cations are fully randomly distributed within each sublattice, which makes all the sites within each sublattice effectively equivalent. In such cases the cation distribution is fully characterized by the inversion degree  $x$ . The degree of inversion in spinels has been found to be affected by different factors, including the ionic radii of the distributed species, the electronic configuration, the electrostatic energy of the lattice, the short-

range Born repulsion energy, crystal field effects, and polarization effects (Brabers, 1995; Slick, 1980).



**Figure 3.1.** Schematic representation of one full unit cell of a perfect spinel, highlighting one of the four primitive rhombohedral cells. The spinel structure has the symmetry group  $Fd\bar{3}m$  with three ion sites: tetrahedral (A), octahedral (B) cation positions and the anion (X) position.

Structural aspects of  $\text{FeM}_2\text{X}_4$  (thio)spinel have been reported extensively in the literature, sometimes also addressing their influence on the magnetic and electronic properties. For example, these studies include: (1) the mixing, non-stoichiometry (Andersson and Stanek, 2013) and magnetic properties as a function of the cation site distribution of the  $\text{Fe}_3\text{O}_4$ - $\text{FeCr}_2\text{O}_4$  system (Robbins *et al.*, 1971); (2) the magnetic ordering of  $\text{FeCr}_2\text{O}_4$  (Bacchella and Pinot, 1964; Bordács *et al.*, 2009; Klemme *et al.*, 2000; Kocsis *et al.*, 2013) and  $\text{FeMn}_2\text{O}_4$  (Van Landuyt *et al.*, 1972) upon crystal symmetry lowering; (3) the relevance of the electronic structure to the magnetic

properties of  $FeCr_2X_4$  (Ohgushi *et al.*, 2008); (4) the transport properties based on the half-metallic electronic structure of  $FeCr_2S_4$  (Park *et al.*, 1999); (5) the magnetic structures in  $FeCr_2X_4$  (Shirane *et al.*, 1964) and the colossal magnetoresistance in  $FeCr_2S_4$  (Ramirez *et al.*, 1997); (6) the degree of inversion in  $FeMn_2O_4$  (Boucher *et al.*, 1969; Buhl, 1969; Kulkarni and Darshane, 1985; Sinha *et al.*, 1957) and  $FeCo_2O_4$  (Ferreira *et al.*, 2003; Le Trong *et al.*, 2008; Liu *et al.*, 2013); (7) the structural phase stability and magnetism in  $FeCo_2O_4$  (Muthuselvam and Bhowmik, 2009); (8) the structural and magnetic properties of  $FeNi_2O_4$  (Shafer, 1962), as well as (9) the thermodynamic stability (Haider *et al.*, 2012) and cation distribution of  $FeNi_2S_4$  (Tenailleau *et al.*, 2006; Waldner, 2009). Nevertheless, in compounds such as these (thio)spinel, where the other transition metal's atomic number differs only by 1 from Fe, the X-ray diffraction intensities are very similar for any inversion degree, which makes it difficult experimentally to differentiate the location of the cations in the structure.

Owing to the experimental limitations for the determination of the cation arrangement in  $FeM_2X_4$  (thio)spinel, in the present work we have used DFT+ $U$  calculations to investigate systematically how modifying the spinel composition affects the equilibrium inversion degree and how this determines the magnetic and electronic properties at a given composition. We study the influence of the nature of the  $M$  and  $X$  ions ( $M = Cr, Mn, Fe, Co, Ni$  and  $X = O, S$ ) on these properties, a type of investigation that has been undertaken previously for other groups of oxide spinel (Szotek *et al.*, 2006) and Heusler alloys (Balke *et al.*, 2008; Galanakis *et al.*, 2002)



with potential application in spintronic devices. We will discuss from a thermodynamic point of view the equilibrium cation distribution of these (thio)spinels and the role of the ions' sizes and crystal field stabilization effects. We will also analyze the dependence of the electronic and magnetic structure on the degree of inversion for the normal and completely inverse systems.

## **3.2 Computational methods**

### **3.2.1 Calculation details**

We have carried out spin-polarized quantum mechanical calculations using density functional theory (DFT) as implemented in the Vienna *Ab-initio* Simulation Package (VASP) (Kresse and Furthmüller, 1996a, 1996b; Kresse and Hafner, 1994, 1993). The Perdew-Burke-Ernzerhof functional revised for solids (PBEsol) (Perdew *et al.*, 2008) was the version of the generalized gradient approximation (GGA) used as exchange-correlation functional for all geometry optimizations and for the calculation of all density of states (DOS), because PBEsol provides a better description of the structure of solids than its parent functional (De La Pierre *et al.*, 2011).

The semiempirical method of Grimme (D2) was also included in our calculations for modelling the long-range van der Waals interactions (Grimme, 2006). Even when these interactions are not expected to affect significantly the bulk properties of the hard solids investigated here, we have included the D2 correction at this stage because in future work we expect to study the surfaces of these solids and their interactions

with adsorbates, where dispersion effects may play a significant role (Dzade *et al.*, 2014, 2013; Haider *et al.*, 2014; Irrera *et al.*, 2013; Santos-Carballal *et al.*, 2014; Tafreshi *et al.*, 2014). The projector augmented wave (PAW) pseudopotential method (Blöchl, 1994; Kresse and Joubert, 1999) was used to describe the core electrons and their interaction with the valence electrons, *i.e.* those in level  $4d$  for Fe, Co and Ni,  $3p4d$  for Cr and Mn,  $2s2p$  for O and  $3s3p$  for S. The kinetic energy cutoff for the plane-wave basis set expansion was set at 520 eV for the geometry optimizations in order to avoid the Pulay stress arising from the cell shape relaxations. A Monkhorst-Pack grid of  $7 \times 7 \times 7$   $\Gamma$ -centred  $k$ -points (Baldereschi, 1973; Chadi and Cohen, 1973; Monkhorst and Pack, 1976) was used for all calculations. During relaxation, Feynman forces on each atom were minimized until they were less than  $0.01 \text{ eV} \cdot \text{\AA}^{-1}$ . For the calculation of the DOS we applied the tetrahedral method with Blöchl corrections. Atomic charges and atomic spin moments were analyzed using the Bader partition methodology (Bader, 1990) in the implementation of Henkelman and collaborators (Henkelman, Arnaldsson, & Jónsson, 2006; Sanville, Kenny, Smith, & Henkelman, 2007; Tang, Sanville, & Henkelman, 2009).

In order to improve the description of the highly correlated  $3d$  electrons in the spinels under study, we have included the Dudarev *et al.* (1998) approach for the  $d$  orbital correction within the DFT +  $U$  method (Anisimov *et al.*, 1992). We report in **Table 3.1** the values used for the on-site Coulomb interaction term of  $d$  Fe and  $d$   $M$ . These values were determined by fitting the calculated positions of the  $d$  band centers to those obtained from calculations using the screened hybrid functional of Heyd-

Scuseria-Ernzerhof (HSE06) (Heyd and Scuseria, 2004a, 2004b; Heyd *et al.*, 2006, 2005, 2003; Krukau *et al.*, 2006; Peralta *et al.*, 2006), which provides band gaps of better quality than semilocal functionals (Henderson *et al.*, 2011). The HSE06 is made from the Perdew-Burke-Ernzerhof functional (PBE) (Perdew *et al.*, 1997, 1996a) exchange and correlation components mixed with 25% of short-range Hartree-Fock (HF) exchange (Heyd *et al.*, 2003). The Coulomb potential exchange is replaced by a screened potential (with screening parameter  $\omega = 0.207 \text{ \AA}^{-1}$ ) in order to define the separation between the short- and long-range components of the HF exchange (Krukau *et al.*, 2006). While the amount of short-range HF is a constant determined by perturbation theory, making HSE06 an adiabatic connection functional in this part of the potential (Perdew *et al.*, 1996b), its screening parameter is a reasonable system-averaged value across a wide variety of systems, giving better agreement with experiments in the case of semiconductors than for metals or insulators (Henderson *et al.*, 2011).

For the fitting, we carried out single-point calculations with both PBEsol +  $U$  and HSE06, using unrelaxed structures with normal cation distributions ( $a_0$  and  $u_0$  were taken from experiment for these calculations, values are listed in **Table 3.2**). In a first step, we determine  $U_{\text{eff}}$  for Fe, by considering the  $Fe_3O_4$  and  $Fe_3S_4$  electronic structures (which have been studied before) (Devey *et al.*, 2009; Haider *et al.*, 2012; Roldan *et al.*, 2013). We then keep these values for Fe and perform a set of DFT +  $U$  calculations where the effective Hubbard parameter ( $U_{\text{eff}}$ ) of the  $M$  ion was changed in steps of 0.5

eV from 0 to 6.0 eV. In all the HSE06 calculations, we used the same settings as for the PBEsol simulations.

**Table 3.1.** Summary of the optimum effective Hubbard parameter ( $U_{\text{eff}}$ ) in eV used through this work for the spinel oxides and sulfides.

	Cr	Mn	Fe	Co	Ni
$\text{FeM}_2\text{O}_4$	4.0	3.5	4.0	1.5	5.5
$\text{FeM}_2\text{S}_4$	2.0	2.5	3.5	0.5	4.5

We found that the optimum  $U_{\text{eff}}$  values for the Cr, Mn and Fe ions in the spinel oxides are within 0.5 eV of the ones previously found for PBE +  $U$  by Wang *et al.* (2006) via comparison of experimental and theoretical formation energies of metal oxides. The two exceptions are the  $U_{\text{eff}}$  values for Co and Ni which differ, according to our methodology, by 1.8 and 0.9 eV respectively from the ones reported by Wang *et al.* (2006) The smaller  $U_{\text{eff}}$  values of the thiospinels, compared to their oxide counterparts, reflect their more covalent character. The  $U_{\text{eff}}$  for Mn-based thiospinel compares well with the value reported by Rohrbach *et al.* (2003), while, according to our methodology, the one for Fe is 1.5 eV above the one used by the same authors. Hence, in general our  $U_{\text{eff}}$  are similar to previously employed values, with some small differences which can be expected from the use of a different starting functional (PBEsol in our case), the implementation of the method, different compound or different fitting procedure.

All the calculations were performed in the rhombohedral primitive unit cell of the  $\text{FeM}_2\text{X}_4$  spinels, which comprises 14 atoms, see **Figure 3.1**. For each composition of  $(\text{Fe}_{1-x}\text{M}_x)_\text{A}(\text{Fe}_x\text{M}_{2-x})_\text{B}\text{X}_4$ , we considered three values of  $x$  (0, 0.5 and 1.0). When using this cell, the site occupancy artificially lowers the symmetry from space group  $Fd\bar{3}m$  (No. 227) in the normal spinel to  $R3m$  (No. 160) in the half-inverted and to  $Imma$  (No. 74) in the fully-inverted spinel (Fritsch and Ederer, 2010). The use of the primitive cell ensures that there is a single cation configuration for each of these three degrees of inversion, which simplifies the simulations, allowing us to scan a wide range of  $\text{FeM}_2\text{X}_4$  compositions in the present study. This approximation follows previous work where the use of the primitive cell model has been found to adequately describe experimental properties of half- and fully-inverted spinels (Fritsch and Ederer, 2011a, 2010; Seminovski *et al.*, 2012; Walsh *et al.*, 2007; Wei and Zhang, 2001). However, we cannot rule out that the use of larger supercells could actually lead to cation configurations with lower energies for the same inversion degree, *e.g.* as found in a recent study of  $\text{CoFe}_2\text{O}_4$  (Fritsch and Ederer, 2011b).

Following the collinear Néel model, the initial magnetic moments of the atoms within each sublattice were set parallel among themselves and antiparallel to those of the other sublattice. For each inversion degree, we run several calculations specifying different initial magnetic moments, corresponding to different combinations of low- and high-spin states for the transition metal ions in each sublattice, in order to find the ground state. The magnetic moments were allowed to relax during each of the calculations. It should be noted that the magnetic structure with antiparallel

sublattices is not strictly valid in the case of  $\text{FeCr}_2\text{O}_4$ , which is known to have a spiral magnetic structure (Shirane *et al.*, 1964). However, for the sake of comparison with the other spinel systems, we have not considered its different magnetic structure in this study.

The experimental lattice ( $a_0$ ) and anion ( $u$ ) parameters (defining the anion position in the crystal) of the spinels are shown on **Table 3.2**. These were used as the starting structures for our simulations, where  $a_0$  and the internal coordinates were allowed to relax fully for each inversion degree. We kept the cell shape perfectly rhombohedral in such a way that the conventional cell was always cubic. As  $\text{FeMn}_2\text{S}_4$  and  $\text{FeCo}_2\text{S}_4$  spinels have not been characterized so far, we postulated an initial hypothetical structure for both. For the Mn- and Co-based thiospinels, we kept the same initial anion parameter as in their oxide counterparts and scaled up their initial lattice parameter according to the equation:

$$a_0(\text{FeM}_2\text{S}_4) = \frac{a_0(\text{Fe}_3\text{S}_4) \cdot a_0(\text{FeM}_2\text{O}_4)}{a_0(\text{Fe}_3\text{O}_4)} \quad (3.1)$$

which gives the estimates shown in **Table 3.2**.

**Table 3.2.** Summary of the initial unit cell lattice ( $a_0$ ) and anion ( $u_0$ ) parameters of  $FeM_2X_4$  spinels used in this work. The relaxed  $a$  and  $u$  are also reported for  $x = 0, 0.5$  and  $1$ . Note that the origin is the center of symmetry.

Structure	Experimental		$x = 0$		$x = 0.5$		$x = 1$	
	$a_0$ (Å)	$u$	$a$ (Å)	$u$	$a$ (Å)	$u$	$a$ (Å)	$u$
$FeCr_2O_4^A$	8.38	0.261	8.351	0.261	8.372	0.261	8.392	0.265
$FeCr_2S_4^A$	10.00	0.259	9.830	0.258	9.855	0.262	9.898	0.260
$FeMn_2O_4^B$	8.51	0.250	8.420	0.256	8.436	0.265	8.446	0.267
$FeMn_2S_4^C$	10.04	0.250	9.911	0.255	9.949	0.260	9.983	0.263
$Fe_3O_4^D$	8.390	0.255	8.345	0.254	--	--	--	--
$Fe_3S_4^E$	9.88	0.251	9.764	0.255	--	--	--	--
$FeCo_2O_4^F$	8.24	0.259	8.196	0.256	8.168	0.259	8.119	0.271
$FeCo_2S_4^C$	9.73	0.259	9.363	0.263	9.286	0.260	9.297	0.250
$FeNi_2O_4^G$	8.29	0.258	8.124	0.259	8.123	0.260	8.133	0.255
$FeNi_2S_4^H$	9.47	0.257	9.463	0.260	9.438	0.257	9.396	0.251

<sup>A</sup> Shirane *et al.* (1964)

<sup>B</sup> Montoro (1938)

<sup>C</sup> Experimental information is not available. Parameters are obtained by scaling the values for the corresponding oxides.

<sup>D</sup> Wright *et al.* (2002)

<sup>E</sup> Skinner *et al.* (1964)

<sup>F</sup> Ferreira *et al.* (2003)

<sup>G</sup> Shafer (1962)

<sup>H</sup> Tenailleau *et al.* (2006)

### 3.2.2 Configurational free energy of inversion

The calculation of the inversion degree in spinels containing two different cations is based on the thermodynamic considerations of Navrotsky and Keppla (1967), which have proved to agree well with experiments (Ndione *et al.*, 2014; Palin *et al.*, 2008; Seko *et al.*, 2010; Seminovski *et al.*, 2012; Tielens *et al.*, 2006). This methodology is based on the treatment of the spinels' cation distribution as a chemical equilibrium. We calculated the configurational free energy of inversion per formula unit  $\Delta F_{\text{config}}$  as,

$$\Delta F_{\text{config}} = \Delta E_{\text{config}} - T \cdot \Delta S_{\text{config}} \quad (3.2)$$

where  $\Delta E_{\text{config}}$  is the inversion energy per formula unit,  $T$  is the temperature and  $\Delta S_{\text{config}}$  is the ideal configurational entropy also per formula unit, which is calculated as,

$$\Delta S_{\text{config}} = -R \left[ x \ln x + (1-x) \ln(1-x) + x \ln \frac{x}{2} + (2-x) \ln \left( 1 - \frac{x}{2} \right) \right] \quad (3.3)$$

where  $R$  is the ideal gas constant.  $\Delta S_{\text{config}} = 0$  and  $11.59 \text{ J}\cdot\text{mol}^{-1}\cdot\text{K}^{-1}$  for  $x = 0$  and  $1$  respectively, while it reaches the maximum value  $15.88 \text{ J}\cdot\text{mol}^{-1}\cdot\text{K}^{-1}$  for the complete random distribution at  $x = 2/3$ . The above expression means that we have only considered ideal contributions to the configurational entropy, in line with previous work (Seko *et al.*, 2010; Seminovski *et al.*, 2012; Tielens *et al.*, 2006). We are also ignoring vibrational contributions to  $\Delta F$ , as their contributions are typically small compared to configurational energies and entropies (Seminovski *et al.*, 2012; Tielens *et al.*, 2006).



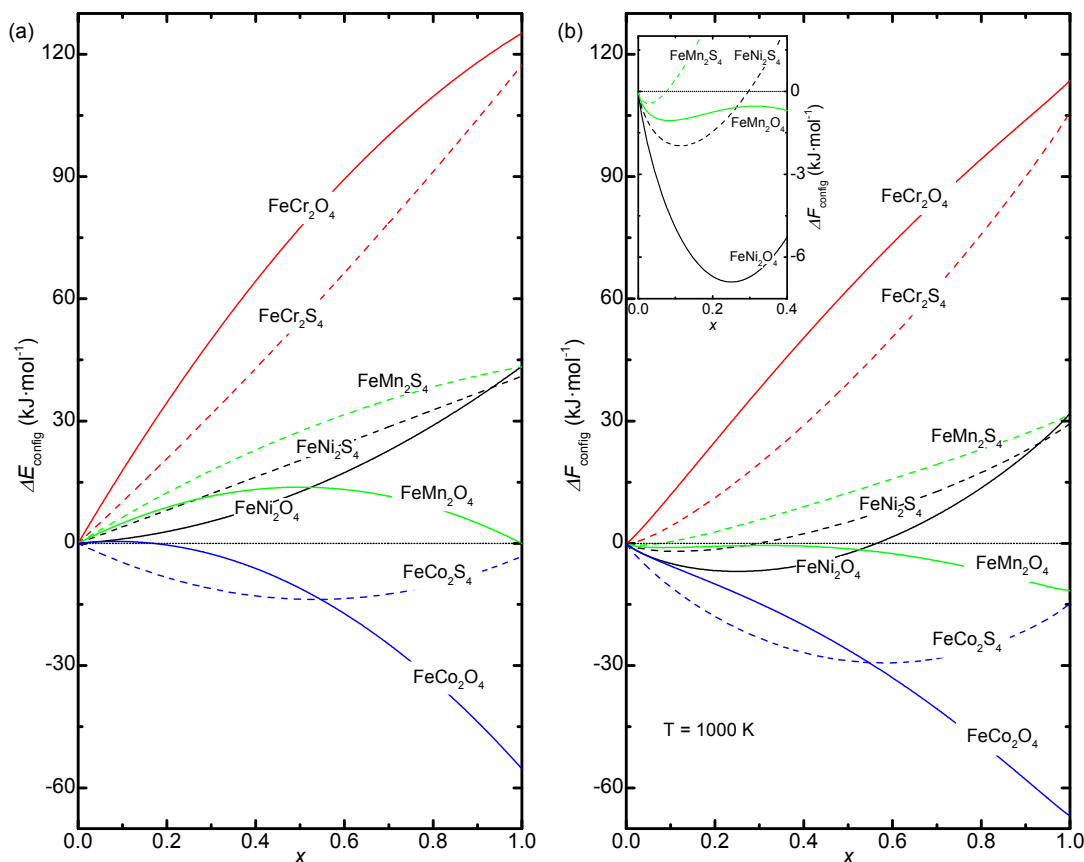
### 3.3 Equilibrium structures

**Table 3.2** shows the optimized  $a$  and  $u$  for the three inversion degrees considered ( $x = 0, 0.5$  and  $1.0$ ). In general, the optimized lattice parameter is within 2% from the experimental value, where this is available. However, the relaxed lattice parameter for  $FeCo_2S_4$ , in the best case ( $x = 0$ ), is 3.8% away from the initial estimated value, which may be an artefact due to the assumption of linearity between the lattice constants of  $Fe_3O_4$ ,  $FeCo_2O_4$  and their sulfide counterparts. After relaxation of the structures,  $u$  was still different from the value of  $1/4$  that it has in the perfect spinel. This deviation reflects the displacement, in the (111) direction, of the anion from its ideal position in order to accommodate cations of specific volume. The biggest deviation in  $u$  in comparison with the experimental value was for the inverse Mn- and Co-based oxide spinels, **Table 3.2**. We see that in general,  $u$  and  $a$  values are sensitive to the cation distribution, although no systematic rule can be derived from their dependence.

### 3.4 Equilibrium inversion degrees

The configurational inversion energy per formula unit ( $\Delta E_{\text{config}}$ ) was fitted *versus* the degree of inversion ( $x$ ) using a quadratic regression curve, see **Figure 3.2 (a)**. More details regarding the empirical relationship (Kriessman and Harrison, 1956) and theoretical justification (O'Neill and Navrotsky, 1983) of the above fitting in terms of  $x$ ,  $a$  and  $u$  can be found elsewhere. In this fitting, we defined the normal spinel as the standard state for a given condition of temperature and pressure.

Using the quadratic equation for  $\Delta E_{\text{config}}$ , it is possible to interpolate the inversion energy for any value of  $x$  between 0 and 1. Based on this protocol, we have also estimated the configurational free energy of inversion for a typical firing temperature of 1000 K (Muthuselvam and Bhowmik, 2009; Ohgushi *et al.*, 2008; Shafer, 1962; Tenailleau *et al.*, 2006) (among the known cases in this study,  $\text{FeNi}_2\text{S}_4$  is an exception, as it is usually prepared at 573 K (Tenailleau *et al.*, 2006; Townsend *et al.*, 1977) because it decomposes at 734 K (Craig, 1971)) by using equations (3.2) and (3.3). Compounds are usually quenched after synthesis at the firing temperature, retaining the equilibrium cation distribution. We analysed the  $\Delta E_{\text{config}}$  dependence with  $x$  and provided the equilibrium values of  $x$ , *i.e.* the ones that satisfy  $\partial F_{\text{config}}/\partial x = 0$  at 1000 K, see **Figure 3.2 (b)**.



**Figure 3.2.** (a) Configurational inversion energy ( $\Delta E_{\text{config}}$ ) and (b) configurational inversion free energy ( $\Delta F_{\text{config}}$ ) as a function of the inversion degree for  $FeM_2X_4$  spinels. Inset shows enlargement of  $\Delta F_{\text{config}}$  for the  $FeMn_2X_4$  and  $FeNi_2X_4$  (thio)spinel.

We found the minimum of  $\Delta E_{\text{config}}$  to correspond to a normal distribution of cations, with the exception of Co-based systems and  $FeMn_2O_4$ , **Figure 3.2 (a)**. The lowest value of  $\Delta E_{\text{config}}$  for  $FeCo_2O_4$  spinel is found to be an inverse cation distribution, whereas for  $FeMn_2O_4$ , both normal and inverse cation distribution structures lie at similar energies, while the intermediate degree of inversion ( $x = 0.5$ ) is only  $\sim 14$   $\text{kJ}\cdot\text{mol}^{-1}$  above the ground state.  $FeCo_2S_4$  is an atypical thiospinel in this study, in the

sense that it shows a critical point of low energy with intermediate cation distribution, at  $x = 0.53$ .

**$\text{FeCr}_2\text{X}_4$ .** From **Figure 3.2 (b)**, we deduced that at 1000 K, the Cr-based (thio)spinel are normal under equilibrium conditions, as a result of a highly endothermic process of inversion. This normal cation distribution of  $\text{FeCr}_2\text{X}_4$  is supported by powder neutron diffraction intensities (Shirane *et al.*, 1964) at room temperature and for the oxide by Mössbauer measurements (Robbins *et al.*, 1971) and DFT calculations (Andersson and Stanek, 2013), see **Table 3.3**.

**Table 3.3.** Summary of equilibrium inversion degree ( $x$ ) of  $FeM_2X_4$  (thio)spinel from previous reports and this work.

	$x$	$x$ at 1000 K
$FeCr_2O_4$	$\sim 0.0^A$	0.00
	$0.00^B$	
$FeCr_2S_4$	$\sim 0.0^C$	0.00
$FeMn_2O_4$	$0.5^D$	0.10 and 1.00
	$0.91^E$	
$FeMn_2S_4$	-- <sup>F</sup>	0.03
$FeCo_2O_4$	$0.52^G$	1.00
	$0.54^H$	
	$0.565^I$	
	$0.605^J$	
	$0.7^K$	
	$1.0^L$	
$FeCo_2S_4$	-- <sup>F</sup>	0.48
$FeNi_2O_4$	-- <sup>F</sup>	0.25
$FeNi_2S_4$	$\sim 0.05^M$	0.12
	$0.82$ or $1.00^N$	
	$1.00^O$	

<sup>A</sup> Andersson and Stanek (2013) and Shirane *et al.* (1964)

<sup>B</sup> Robbins *et al.* (1971)

<sup>C</sup> Shirane *et al.* (1964)

<sup>D</sup> Kulkarni and Darshane (1985) and Sinha *et al.* (1957)

<sup>E</sup> Boucher *et al.* (1969) and Buhl (1969)

<sup>F</sup> Experimental information is not available.

<sup>G</sup> Smith *et al.* (1978)

<sup>H</sup> Ferreira *et al.* (2003)

<sup>I</sup> Liu *et al.* (2013)

<sup>J</sup> Takahashi and Fine (1972)

<sup>K</sup> Murray and Linnett (1976)

<sup>L</sup> Blasse (1963) and Lotgering (1956)

<sup>M</sup> Cemič and Kleppa (1987)

<sup>N</sup> Vaughan and Craig (1985)

<sup>O</sup> Charnock *et al.* (1990), Tenailleau *et al.* (2006) and Waldner (2009)

**FeMn<sub>2</sub>X<sub>4</sub>**. At 1000 K, the scenario for FeMn<sub>2</sub>O<sub>4</sub> is unique in this study, as in addition to the global minimum of  $\Delta F_{\text{config}}$  at  $x = 1$ , it has a local one at  $x = 0.1$ . The local minimum is within a portion of shallow inversion free energy ( $0 < x < 0.3$ ), which may lead to a metastable inversion degree anywhere within this range, for this spinel's equilibrium structure, see **Figure 3.2 (b)**. The behaviour of this thermodynamic property in FeMn<sub>2</sub>O<sub>4</sub> can be rationalized in terms of the small change of  $\Delta E_{\text{config}}$  with  $x$  as well as in  $E_{x=0} \approx E_{x=1}$ . The upper limit ( $x = 0.3$ ) of the shallow inversion free energy that we predicted agrees semiquantitatively with the experimental inversion degree ( $x = 0.5$ ) found for FeMn<sub>2</sub>O<sub>4</sub> in a conductivity and thermopower (Kulkarni and Darshane, 1985) investigation, as well as inferred from the study of a series of spinels (Sinha *et al.*, 1957), see **Table 3.3**. The inversion degree has also been found in neutron diffraction experiments to be at  $x = 0.91$  (Boucher *et al.*, 1969; Buhl, 1969) which is in reasonably good agreement with the global minimum calculated here. We speculate that the two inversion degrees of FeMn<sub>2</sub>O<sub>4</sub> may be hampered by kinetic control by a barrier that is just around  $4 \text{ kJ}\cdot\text{mol}^{-1}$  below  $2k_{\text{B}}T$  (when  $T = 1000 \text{ K}$ ), which explains the different cation arrangements described in the literature. According

to our calculations, samples of  $\text{FeMn}_2\text{O}_4$  synthesized above 1150 K can only have inverse cation distribution, as the metastable inversion degree vanishes.  $\text{FeMn}_2\text{S}_4$ , on the other hand, is predicted to be mostly normal ( $x = 0.03$ ) under equilibrium conditions, **Figure 3.2 (b)**.

**$\text{FeCo}_2\text{X}_4$ .**  $\text{FeCo}_2\text{O}_4$  is the only completely inverse spinel under equilibrium conditions, due to the highly exothermic process of inversion, which agrees with experimental evidence (Blasse, 1963; Lotgering, 1956). Nevertheless, our results for the Co-based oxide disagree with the equilibrium inversion degree of  $x = 0.565$  and  $0.605$  obtained by means of fitting the dependence of the magnetic moment with  $x$  (Liu *et al.*, 2013; Takahashi and Fine, 1972) and the similar values within the range  $0.52 \leq x \leq 0.7$  derived from Mössbauer spectra (Ferreira *et al.*, 2003; Murray and Linnett, 1976; Smith *et al.*, 1978), see **Table 3.3**. Its sulfide counterpart, which has not been studied experimentally, shows an equilibrium inversion degree of  $x = 0.48$  in our calculations.

**$\text{FeNi}_2\text{X}_4$ .**  $\text{FeNi}_2\text{O}_4$  (and to a lesser extent  $\text{FeNi}_2\text{S}_4$ ) is predicted to have an intermediate distribution of the cations under equilibrium conditions of around  $x = 0.25$  ( $x = 0.12$  for the thiospinel case). Our results agree with suggestions of partially inverted  $\text{FeNi}_2\text{S}_4$ , based on a high temperature calorimetry study of natural samples (Cemič and Kleppa, 1987), see **Table 3.3**. However, they disagree with the more recent description of synthetic  $\text{FeNi}_2\text{S}_4$  samples as completely inverse spinel based on a neutron powder diffraction measurements at temperatures between 100 and 573 K (Tenailleau *et al.*, 2006), thermodynamic-based modelling (Waldner, 2009), EXAFS experiment (Charnock *et al.*, 1990) and Mössbauer data (Vaughan and Craig, 1985). Based on our

calculations and the fact that synthetic  $FeNi_2S_4$  samples cannot be annealed to temperatures higher than 734 K (Craig, 1971), as they decompose, we propose a rationalization of the different cation arrangements found in natural and synthetic samples of this mineral. We suggest that synthesis produces a kinetic product (with  $x \sim 1.00$ ) and that these conditions cannot reproduce the hypogene processes occurring in the ores deep below the Earth's surface that lead to the thermodynamic product found in natural samples ( $x \sim 0$ ).

### 3.5 Size of ions and crystal field stabilization effects

We analyze now the effect of cation size and crystal field stabilization energy on the distribution of cations under equilibrium conditions.

Assuming the hard-sphere model, where the ions are spherical, rigid and in contact, the ratio between the tetrahedral ( $R_A$ ) and octahedral ( $R_B$ ) bond distances will depend solely on  $u$ . The tetrahedral holes are smaller than the octahedral ones for  $u < 0.2625$  (Hill *et al.*, 1979). Taking into account that for most systems under study here,  $u$  is below that value (with a few exceptions in the relaxed structures, see **Table 3.2**), we can consider that  $R_A < R_B$  is expected for a stable spinel.

According to the Shannon effective radii (Shannon, 1976), which depend on the coordination number and oxidation state,  $Fe_A^{2+}$  cation has bigger radius than  $Cr_B^{3+}$ ,  $Co_B^{3+}$  and  $Ni_B^{3+}$  leading to an inverse cation distribution. This agrees very well with our thermodynamic DFT +  $U$  calculations for  $FeCo_2O_4$  and moderately with the



partially inverse ( $x = 0.48$ )  $FeCo_2S_4$  spinel. However, we found the opposite equilibrium distribution for the  $FeCr_2X_4$  system and a very small inversion degree ( $x < 0.25$ ) for the  $FeNi_2X_4$ , indicating that this factor is not the key parameter governing the inversion degree in these compounds. On the other hand, the  $Mn_B^{3+}$  Shannon radius is bigger than that of  $Fe_A^{2+}$ , predicting a normal (thio)spinel. Yet, whereas the sulfide compound is a completely normal spinel, the oxide has a local minimum for  $0 < x < 0.3$  and the global one at  $x = 1$ .

Since we are dealing with open shell  $d$  transition metals, the crystal field is also an important effect to consider. McClure (1957), and independently Dunitz and Orgel (1957), derived the crystal field stabilization energy for ions (in oxides) with tetrahedral and octahedral environments, to estimate the relative stability of normal and inverse spinels. Subtracting the tetrahedral stabilization energy from the octahedral one (octahedral site preference energy – OSPE) gives an idea of the octahedral site preference. The OSPE for  $Fe^{2+}$  (16.3 kJ/mol) is smaller than for the rest of the cations under consideration here, *i.e.* 195.4 kJ/mol for  $Cr^{3+}$ , 105.9 kJ/mol for  $Mn^{3+}$ , 79.5 kJ/mol for  $Co^{3+}$  and 95.4 kJ/mol for  $Ni^{2+}$  (note that to date no estimation of OSPE for  $Ni^{3+}$  is reported). These OSPEs clearly show the preference for normal spinels.

The ambiguities in our results are probably not surprising, because earlier attempts to correlate cation distribution with their size and crystal field effects were also not

successful, or at least, unable to provide a complete prediction of the degrees of inversion (Cormack *et al.*, 1988).

### 3.6 Atomic spin moments and charges

In this and the next section we analyze the electronic and magnetic properties of the spinel materials for the extreme cases of  $x = 0$  and  $x = 1$ .

The total magnetization of saturation ( $M_s$ ) is defined experimentally as the maximum magnetic moment per formula unit of a compound under an increasing magnetic field. This magnitude can also be calculated according to the Néel model as the sum of the atomic spin densities ( $m_s$ ) in the tetrahedral and octahedral sublattices per formula unit (Néel, 1948). **Table 3.4** shows the atomic spin densities for all the compounds under study here. When  $x = 0$  in the oxide spinels,  $m_s(Fe_A)$  is around  $4 \mu_B/\text{atom}$ , which is in good agreement with a high-spin electronic distribution for  $Fe_A^{2+} : e_{\uparrow}^2 e_{\downarrow}^1 t_{2\uparrow}^3$ , with the exception of the deviation in the Cr-based compound. For the normal thiospinels there is more consistency in the  $m_s(Fe_A)$  values, as they lie in the range  $-3.41$  and  $-3.53 \mu_B/\text{atom}$  and only in semiquantitative agreement with the Néel model. For the  $M$  cation in the normal Cr- and Mn-based (thio)spinel, the atomic spin densities are also in good agreement with high-spin electronic distributions. We found that our DFT+ $U$  calculations underestimated the atomic spin moment of  $FeCo_2O_4$  (when  $x = 0$ ) by  $1.28 \mu_B/\text{atom}$  compared with the one expected from the Néel model for the high-spin distribution of  $Co_B^{3+} : t_{2g\uparrow}^3 t_{2g\downarrow}^1 e_g^2$ . In its sulfide counterpart with normal distribution, our

calculated value compares well with the one predicted from a low-spin distribution of  $Co_B^{3+}$ , which renders the ions as non-magnetic. In the case of  $Ni_B^{3+}$ , we also found it to be low spin  $t_{2g}^3 e_g^1$ , although our results overestimated by  $0.39 \mu_B/\text{atom}$  and underestimated by  $0.10 \mu_B/\text{atom}$  the expected value for the oxide and sulfide respectively. This agrees with the low-spin cation occupying the octahedral positions in violarite, interpreted previously as  $Fe^{2+}$  (Vaughan and Craig, 1985).

**Table 3.4.** Atomic spin density per atom ( $m_s$ ) and total spin magnetization of saturation per formula unit ( $M_S$ ) both calculated by means of a Bader analysis and in  $\mu_B$ .

Spinel	$x$	$m_s$				$M_S$	$m_s$				$M_S$
		A	B1	B2	$X=O$		A	B1	B2	$X=S$	
$FeCr_2X_4$	0	-3.72	2.92	--	-0.03	2.00	-3.46	2.95	--	-0.11	2.00
$FeCr_2X_4$	1	-3.50	2.82	4.09	0.15	4.00	-3.28	2.86	3.79	0.16	4.00
$FeMn_2X_4$	0	-3.97	4.16	--	-0.09	4.00	-3.53	4.03	--	-0.13	4.00
$FeMn_2X_4$	1	-4.49	3.73	4.17	0.15	4.00	-4.17	3.94	3.84	0.10	4.02
$Fe_3X_4$	--	-4.04	3.91	--	0.05	4.00	-3.44	3.43	--	0.04	3.60
$FeCo_2X_4$	0	-3.95	2.72	--	0.13	2.00	-3.45	-0.04	--	-0.08	-3.87
$FeCo_2X_4$	1	-2.44	0.01	4.11	0.08	2.00	-0.91	0.03	3.32	0.00	2.46
$FeNi_2X_4$	0	-4.04	1.39	--	-0.18	-2.00	-3.41	0.90	--	-0.02	-1.69
$FeNi_2X_4$	1	-1.89	1.59	4.10	0.05	4.00	-0.52	0.86	3.50	0.04	4.00

In the inverse (thio)spinels, the calculated spin densities for  $Fe_{B2}^{2+}$  were slightly overestimated in the oxides compared with the Néel model, while they were more moderately underestimated in the sulfides considering a high-spin electronic

distribution of  $t_{2g\uparrow}^3 t_{2g\downarrow}^1 e_g^2$  for these ions, see **Table 3.4**. The calculated atomic spin densities of the inverse Cr- and Mn-based (thio)spinels agree better, especially in the cations occupying the octahedral (B1) positions, with the high-spin electronic distribution for these ions, as described for the normal spinels. However, in the Co- and Ni-based inverse compounds, we found low-spin densities for these atoms in the B1 positions, where the nearly diamagnetic  $Co_{B1}$  in the inverse  $FeCo_2O_4$  agrees with experiments (Blasse, 1963; Lotgering, 1956). Notable exceptions are the  $Co_A^{3+}$  in the thiospinel and  $Ni_A^{3+}$  in both oxide and sulfide compounds, where our calculations shift  $m_s$  by more than 1  $\mu_B$ /atom with the expected value (in the best case) from a low-spin electronic distribution for these atoms.

There is a disagreement between the  $Fe_3X_4$  atomic spin moment expected from the Néel model and the one obtained from our DFT +  $U$  calculations. Assuming an inverse cation distribution, for  $Fe_A^{3+}$ , the high spin electronic distribution  $e_{\uparrow}^2 t_{2\uparrow}^3$  predicts an atomic spin density of 5  $\mu_B$ , which is approximately 1 and 1.6  $\mu_B$  underestimated by our calculations for the oxide and sulfide respectively. The spin density of the  $Fe_B$  ions is also underestimated from a high spin intermediate between  $Fe^{2+}$  and  $Fe^{3+}$ . An excellent agreement is found for  $Fe_3O_4$ , as the calculated  $M_s = 4.00 \mu_B$ /f.u. is equal to the one found previously (Roldan *et al.*, 2013; Santos-Carballal *et al.*, 2014; Zhang and Satpathy, 1991). Although the magnetization of saturation of  $Fe_3S_4$  should be treated more cautiously, as different values have been found depending on the method used (2.0 (Coey *et al.*, 1970), 3.44 (Roldan *et al.*, 2013), 3.13  $\mu_B$ /f.u. (Chang *et al.*,

2008)), our calculated value compares well with reference (Roldan *et al.*, 2013). For  $\text{Fe}_3\text{X}_4$ , the calculated spin magnetization of saturation also fits the model of inverse spinels with the highest charged Fe filling the tetrahedral positions (Spender *et al.*, 1972; Vaughan and Ridout, 1971; Zhang and Satpathy, 1991).

The most stable normal cation distribution of  $\text{FeCr}_2\text{O}_4$  gave the closest  $M_s$  to the experimental one, although still overestimated by  $1.35 \mu_B/\text{f.u.}$ , as this measurement was carried out at a temperature in which the spins are not collinear anymore (Shirane *et al.*, 1964). In the case of its normal sulfide counterpart, the difference in spin magnetization of saturation with the experiments is smaller ( $0.41 \mu_B/\text{f.u.}$ ) (Shirane *et al.*, 1964).

The Ni-based (thio)spinel are found experimentally to be paramagnetic (Shafer, 1962; Townsend *et al.*, 1977; Vaughan and Craig, 1985). In the oxide this has been explained as being due to high-spin  $\text{Fe}^{3+}$  ions exclusively localized on the A sublattice whose spins compensate completely the  $[\text{Ni}^{2+}\text{Ni}^{3+}]$  occupying the octahedral positions (Shafer, 1962). In the sulfide this has been rationalized on the basis of an A sublattice filled by  $\text{Ni}^{3+}$  and low-spin  $\text{Fe}^{2+}$  occupying octahedral positions (Vaughan and Craig, 1985). Here, based on our calculated spin magnetization of saturation and assuming intermediate degrees of cation distribution, we present a fresh explanation for the paramagnetism of  $\text{FeNi}_2\text{X}_4$ . Considering that  $M_s$  changes linearly with  $x$ , we may postulate that the oxide and sulfide will be paramagnetic when  $x = 0.33$  and  $0.30$  respectively. Although this suggestion agrees with the oxide and sulfide equilibrium inversion degree calculated in section 3.1, it shows that paramagnetism in these

compounds may be due not to the canonical inverse spinel structure with integer oxidation numbers, but to intermediate inversion degrees.

To the best of our knowledge, there is no experimental determination of the saturation magnetization of either  $FeCo_2S_4$  or  $FeMn_2S_4$ . Although we found both compounds to be ferrimagnetic, the measurement of  $M_s$  for  $FeCo_2S_4$  may be essential to determine the inversion degree of this spinel, as our calculation of the normal and inverse cation distributions show different magnetizations of saturation. Our results agree with the ferrimagnetic behaviour described for  $Fe_3O_4$  (Verwey, 1939),  $Fe_3S_4$  (Chang *et al.*, 2009, 2008; Coey *et al.*, 1970; Dekkers *et al.*, 2000; Devey *et al.*, 2009; Spender *et al.*, 1972; Vandenberghe *et al.*, 1991; Vaughan and Tossell, 1981),  $FeCo_2O_4$  (Kawano *et al.*, 1976) and  $FeMn_2O_4$  (Van Landuyt *et al.*, 1972), below the Curie (Néel) temperature.

**Table 3.5** shows the charges ( $q$ ) gained or lost by an atom with respect to the neutral atom in the  $FeM_2X_4$  spinels. We clearly appreciate, that charges are systematically underestimated for all the  $FeM_2X_4$  (thio)spinel. For  $Fe_3S_4$  as well as the Cr- and Mn-based (thio)spinel,  $q_A$  is frankly smaller than  $q_B$  for any inversion degree and also for the inverse  $FeCo_2O_4$ . However, for the Co- and Ni-based systems, the relative charges of the atoms in the tetrahedral and octahedral positions is different in the oxide and sulfide. In the spinel oxides, together with  $Fe_3O_4$  and the normal Co- and Ni-thiospinels,  $q_A$  is bigger than  $q_B$ , while in the inverse thiospinels, it is the other way round.

**Table 3.5.** Calculated Bader charges in the  $\text{FeM}_2\text{X}_4$  spinels.

Spinel	$x$	A	B1	B2	$X = \text{O}$	A	B1	B2	$X = \text{S}$
$\text{FeCr}_2\text{X}_4$	0	1.33	1.75	--	-1.21	0.92	1.22	--	-0.84
$\text{FeCr}_2\text{X}_4$	1	1.47	1.76	1.58	-1.20	1.11	1.22	1.12	-0.86
$\text{FeMn}_2\text{X}_4$	0	1.50	1.56	--	-1.16	0.95	1.18	--	-0.83
$\text{FeMn}_2\text{X}_4$	1	1.41	1.69	1.68	-1.20	1.08	1.21	1.17	-0.86
$\text{Fe}_3\text{X}_4$	--	1.65	1.51	--	-1.16	0.93	1.00	--	-0.73
$\text{FeCo}_2\text{X}_4$	0	1.52	1.34	--	-1.05	0.86	0.54	--	-0.49
$\text{FeCo}_2\text{X}_4$	1	1.30	1.31	1.68	-1.07	0.46	0.60	0.95	-0.50
$\text{FeNi}_2\text{X}_4$	0	1.61	1.18	--	-0.99	0.86	0.57	--	-0.50
$\text{FeNi}_2\text{X}_4$	1	1.27	1.16	1.67	-1.03	0.26	0.61	0.99	-0.46

### 3.7 Electronic density of states

#### 3.7.1 $\text{FeCr}_2\text{X}_4$

The density of states (DOS) in **Figure 3.3** show that at  $x = 0$ ,  $\text{FeCr}_2\text{X}_4$  is half-metallic, which we confirmed by the integer value of total spin magnetization ( $M_S = 2.00 \mu_B/\text{f.u.}$ ), see **Table 3.4**. An integer value of the total spin magnetization discriminates half-metals and insulators from metals. The total number of electrons of any stoichiometric system is integer ( $n$ ) and if it has a band gap at least in one spin channel, there is an integer number of electrons ( $n'$ ) there too. This makes the difference ( $n'' = n - n'$ ), which is the number of electrons on the band that crosses the Fermi level also integer. Therefore, the magnetization of saturation, *i.e.* the difference of  $n'$  and

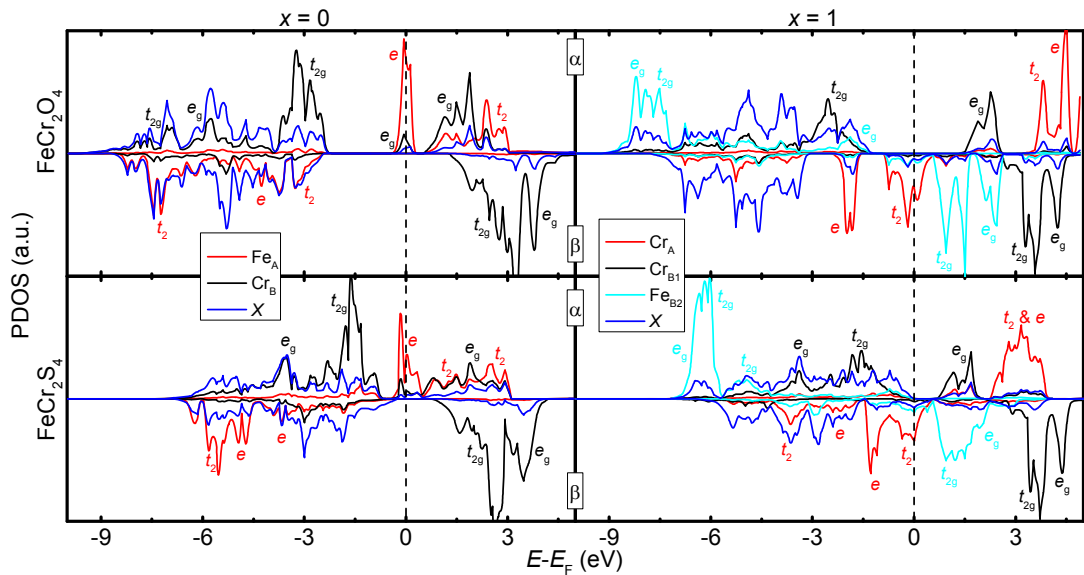
$n''$ , is also integer (Coey and Chien, 2011; Coey and Sanvito, 2004; Coey and Venkatesan, 2002; Coey *et al.*, 2001).

The DOS shows a sharp peak of the partially-occupied  $e$  level of  $Fe_A$  ions in the majority spin channel ( $\alpha$ ) crossing the Fermi energy, which is weakly hybridized with the empty Cr  $e_g$  level in the oxide spinel, while the minority spin channel ( $\beta$ ) shows a gap near  $E_F$ . There is a nearly equally intense band due to the occupied  $Cr_B t_{2g}$  level in the majority channel of the spins at  $-3.0$  eV in the oxide ( $-1.75$  eV in the sulfide), which suggests that the half-metallic properties do not involve the sublattice B. In the oxide, the other valence bands of the  $Fe_A$  ions ( $t_2$  and  $e$  levels) appear in the minority channel of the spins below  $-2.5$  eV, always strongly hybridized with the O  $2p$  orbitals. However, the Cr  $t_{2g}$  level, together with a small contribution from the  $e_g$  orbitals, in the valence part of the majority spin channel are weakly hybridized with the O  $2p$  orbitals. The unoccupied  $t_2$  bands of  $Fe_A$  appear at  $3.0$  eV in the majority channel of the spins while  $Cr_B$  has the unoccupied  $t_{2g}$  band in the majority channel of the spins ( $1.5$  eV) and the  $t_{2g}$  and  $e_g$  levels in the minority channel of the spins ( $2.5$  and  $4.0$  eV).

The inversion of half of the Cr cations to the tetrahedral positions in  $FeCr_2X_4$ , generates four non-equivalent types of atoms (B1 and B2 are the two types of atoms occupying B positions), see **Figure 3.3** right panels. With this cation distribution, the (thio)spinel is still half-metallic ( $M_S = 4.00 \mu_B/\text{f.u.}$ , see **Table 3.4**), but unlike in the normal spinel structure, through the minority channel of the spins due to the partially-occupied  $t_2$  level of the  $Cr_A$  ions. All the  $Cr_A$  bands are shifted towards higher energy values with respect to  $Fe_A$  in the normal (thio)spinel. The  $Cr_{B1} d$  bands appear roughly in the same



position as in the normal (thio)spinel, although less intense. The  $e_g$  and  $t_{2g}$  levels of  $Fe_{B2}$ , which lie very close, are around  $-8.0$  and  $1.5$  eV in the  $\alpha$  and  $\beta$  channel of the spins, respectively. As a result of the cations' shifted and split bands, there is less hybridization of the O  $2p$  orbitals in the valence regions compared to the normal spinel, which are prominent in this section. The main difference, for any cation distribution, between the DOS of  $FeCr_2S_4$  and its oxide counterpart is that all the bands in the sulfide are squeezed towards the Fermi energy.



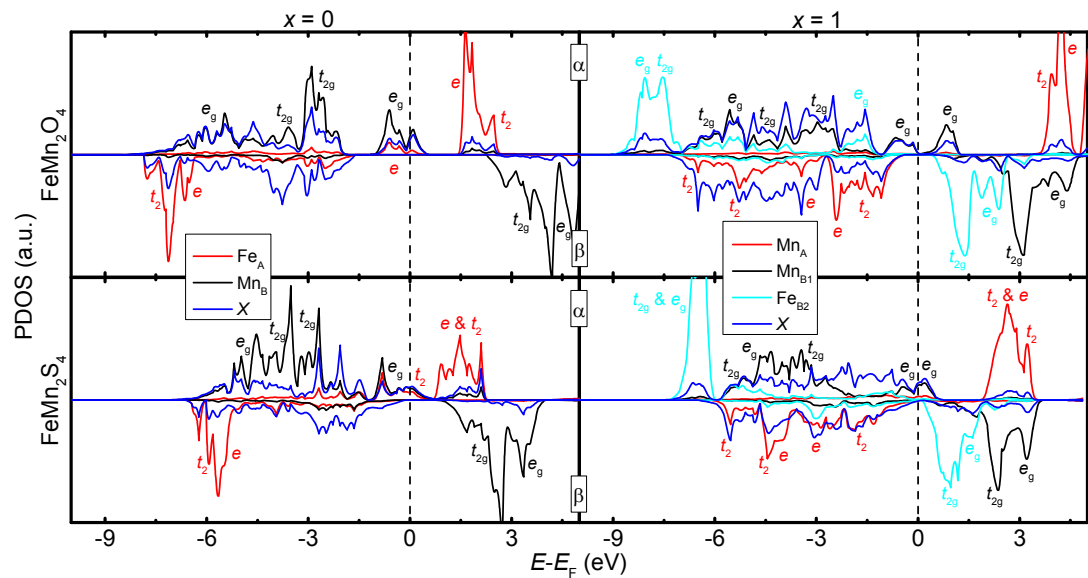
**Figure 3.3.** Atomic projections of the spin decomposed total density of states (PDOS) for  $FeCr_2O_4$  and  $FeCr_2S_4$ . Fe and Cr contributions are from the  $3d$  bands. O and S contributions are from the  $2p$  and  $3p$  orbitals respectively.

### 3.7.2 $\text{FeMn}_2\text{X}_4$

When the  $\text{FeMn}_2\text{X}_4$  (thio)spinel is normal ( $x = 0$ ), the  $\text{Fe}_A$   $e$  and  $t_2$  bands, which are hybridized, appear in the maximum of the valence and minimum of the conduction bands in the minority and majority channel respectively, see **Figure 3.4** left panels. The half-metallic character of the normal  $\text{FeMn}_2\text{X}_4$  (thio)spinel is also confirmed by the spin density analysis, showing a spin magnetization per formula unit of  $M_S = 4.00 \mu_B$ , see **Table 3.4**. At the Fermi energy, the spin up partially-occupied  $e_g$  band of  $\text{Mn}_B$  appears highly hybridized with the  $X p$  orbitals and with the  $\text{Fe}_A$   $e$  and  $t_2$  levels in the oxide and sulfide respectively, in agreement with the bigger atomic volume, enhancing orbital overlapping. The rest of the density of states is essentially the same as in the Cr-material, while in the Mn-based spinels the valence band is slightly shifted towards the Fermi energy and the  $\text{Fe}_A$   $t_2$  and  $e$  bands in the  $\beta$  channel of the spins appear more prominently. With the normal cation distribution, the bands of  $\text{FeMn}_2\text{S}_4$  (**Figure 3.4** bottom-left panel), as in the case of  $\text{FeCr}_2\text{S}_4$ , are shifted towards the Fermi energy, except for the  $\text{Mn}_B$   $t_{2g}$  and  $e_g$  bands in the  $\alpha$  channel of the spins.

When  $\text{FeMn}_2\text{O}_4$  is a completely inverse spinel ( $x = 1$ ), the system becomes half-semiconductor with a negligible band-gap, which has also been found experimentally (Kulkarni and Darshane, 1985), see **Figure 3.4** top-right panel and also note in **Table 3.4** the integer  $M_S = 4.00 \mu_B/\text{f.u.}$ , typical of materials with band gaps. The partially-occupied and split  $\text{Mn}_{B1}$   $e_g$  bands appear close to the Fermi energy in the majority channel of the spins, where the  $t_{2g}$  level, with a small contribution from the  $e_g$  level, in the conduction band is highly hybridized with the  $\text{O } p$  orbitals. The  $\text{Mn}_A$   $t_2$  and  $e$  levels

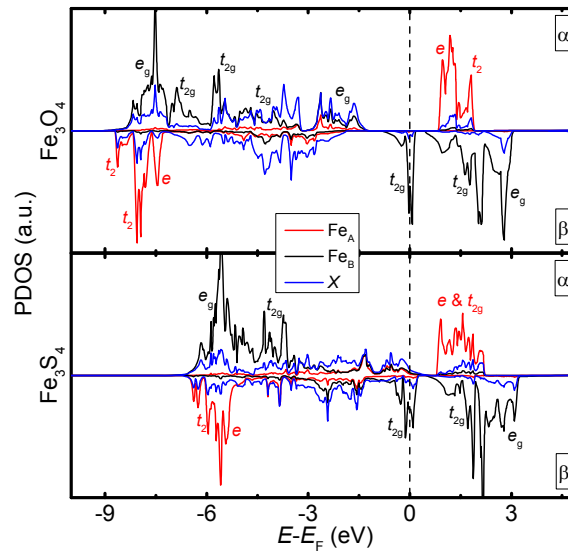
in the minority channel of the spins, are merged altogether and appear as a wide conduction band. In the inverse  $\text{FeMn}_2\text{S}_4$  spinel, the bands are squeezed towards the Fermi energy, becoming a metal in both channels of the spins. The bands responsible for the conductivity properties are associated with the  $\text{Mn}_{\text{B1}}$   $e_g$  level and with the  $\text{Fe}_{\text{B2}}$   $t_{2g}$  level in the majority and minority channel of the spins respectively, see **Figure 3.4** bottom-right panel and the decimal  $M_S = 4.02 \mu_B/\text{f.u.}$ , typical of metals in **Table 3.4**. In general, we see that for any inversion degree, upon exchange of Cr by Mn cations, the bands responsible for the conduction properties are no longer the ones belonging to the atoms occupying the tetrahedral positions but those of  $\text{Mn}_{\text{B}(1)}$ .



**Figure 3.4.** Atomic projections of the spin decomposed total density of states (PDOS) for  $\text{FeMn}_2\text{O}_4$  and  $\text{FeMn}_2\text{S}_4$ . Fe and Mn contributions are from the 3d bands. O and S contributions are from the 2p and 3p orbitals respectively.

### 3.7.3 $\text{Fe}_3\text{X}_4$

The distribution of the bands in  $\text{Fe}_3\text{O}_4$  and  $\text{Fe}_3\text{S}_4$  are similar between them (see **Figure 3.5**). The  $\text{Fe}_B$   $e_g$  bands in the majority spin channel appear at the low end energy of the valence band. Part of the  $\text{Fe}_B$   $t_{2g}$  level in the conduction band and the minority spin channel is overlapped with the Fermi energy, giving the half-metallic properties to  $\text{Fe}_3\text{O}_4$  ( $M_S = 4.00 \mu_B$ ), see **Table 3.4**. This supports the traditional explanation of electrons hopping from  $\text{Fe}^{2+}$  to  $\text{Fe}^{3+}$  in the octahedral sublattice, which renders all cations within this sublattice with the same charge and justifies the half-metallic properties of  $\text{Fe}_3\text{O}_4$  (Zhang and Satpathy, 1991), which has led to its proposal for spintronic applications (Felser *et al.*, 2007). As a result of bands pushed towards  $E_F$  in  $\text{Fe}_3\text{S}_4$ , they overlap with the Fermi energy not only in the minority channel. In the majority spin, although weakly, S  $p$  orbitals also cross the  $E_F$  which are hybridized with the  $\text{Fe}_A$   $d$  bands, giving the characteristic metallic decimal magnetization of saturation ( $M_S = 3.60 \mu_B$ ), **Table 3.4**. This result disagrees with previous evidence of  $\text{Fe}_3\text{S}_4$  having half-metallic (Devey *et al.*, 2009) or semiconducting (Vaughan and Tossell, 1981) properties.



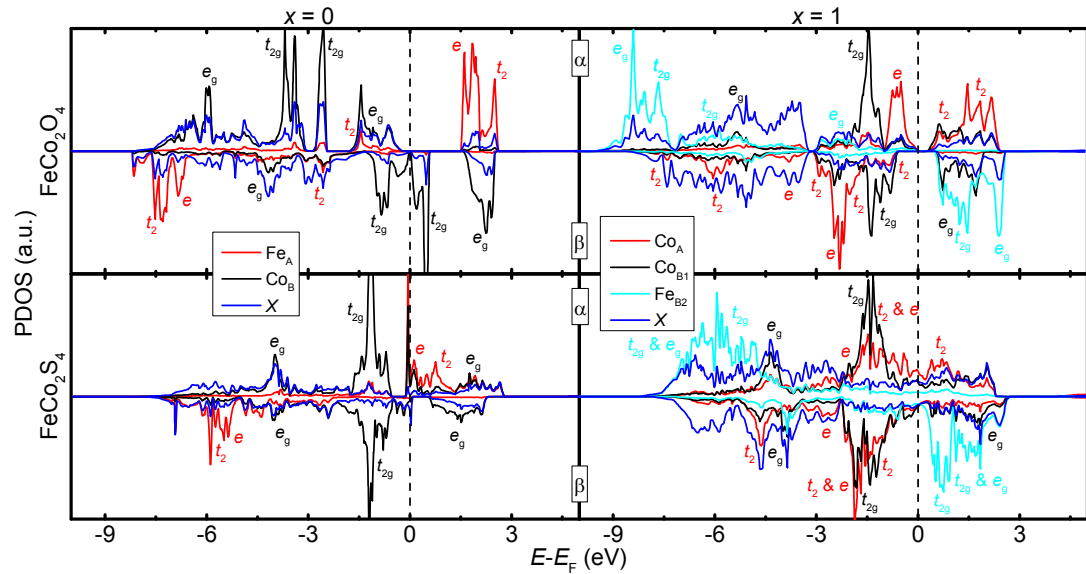
**Figure 3.5.** Atomic projections of the spin decomposed total density of states (PDOS) for  $\text{Fe}_3\text{O}_4$  and  $\text{Fe}_3\text{S}_4$ . Fe contributions are from the 3  $d$  bands. O and S contributions are from the 2 $p$  and 3 $p$  orbitals respectively.

### 3.7.4 $\text{FeCo}_2\text{X}_4$

When  $\text{FeCo}_2\text{O}_4$  has a normal distribution, all the bands are pushed slightly towards the Fermi energy and especially those due to  $\text{Co}_B$ , see **Figure 3.6** top-left panel. As a result, the partially-occupied  $\text{Co}_B$   $t_{2g}$  band that crosses the Fermi energy has a minimal band gap in the minority channel of the spins, making the normal  $\text{FeCo}_2\text{O}_4$  spinel almost a half-metal, see also the integer value of the spin magnetization of saturation in **Table 3.4**. On the other hand, the sulfide counterpart has all the bands closer to the Fermi energy with symmetrical  $\text{Co}_B$  bands in the minority and majority spin channels (**Figure 3.6** bottom-left panel), due to the fully-occupied  $t_{2g}$  level which indicates non-magnetic behaviour for this atom (see **Table 3.4**). There is a peak at the Fermi energy,

in the majority spin channel, with contributions from the partially-occupied  $Fe_A$   $e$  and  $Co_B$   $e_g$  levels. In the minority spin channel, the normal  $FeCo_2S_4$  spinel is weakly conducting, as there is a small  $Co_B$  fully-occupied  $t_{2g}$  band strongly hybridized with  $S$   $p$  orbitals that ends shortly after the Fermi energy in the conduction band side. Overall, the sulfide counterpart is metallic which is confirmed by a decimal spin magnetization of saturation, **Table 3.4**.

When the Co-based (thio)spinel has an inverse cation distribution, all the bands are slightly pushed away from the Fermi energy compared to the normal cation distribution, especially in the oxide, see **Figure 3.6** right panels.  $Fe_{B2}$   $d$  bands appear in the typical range described so far for both oxide and sulfide spinels. For the oxide,  $Co_A$  valence  $d$  bands are in both spin channels, while in the  $\alpha$  spin channel the partially-occupied  $t_2$  level appears exclusively in the conduction part. The fully-occupied  $Co_{B1}$  valence  $t_{2g}$  bands are nearly symmetrically placed in both spin channels, rendering this atom as non-magnetic, see  $m_s$  in **Table 3.4**. The inverse cation distribution of the oxide has insulating properties, see also  $M_S$  in **Table 3.4**. Although the sulfide counterpart has the  $Co_A$  and  $Co_{B1}$  bands symmetrically placed in both channels of the spins, the bands crossing the Fermi energy give it metallic properties (see the decimal value of the spin magnetization of saturation  $M_S = 2.46 \mu_B/f.u.$  in **Table 3.4**, typical of metals). These properties are due to the hybridized partially-occupied  $Co_A$   $t_2$  and fully-occupied  $Co_{B1}$   $t_{2g}$  levels and to the merged  $Co_A$   $t_2$ ,  $Co_{B1}$   $t_{2g}$  and  $Fe_{B2}$   $t_{2g}$  levels in the majority and minority channel of spins, respectively.



**Figure 3.6.** Atomic projections of the spin decomposed total density of states (PDOS) for  $FeCo_2O_4$  and  $FeCo_2S_4$ . Fe and Co contributions are from the  $3d$  bands. O and S contributions are from the  $2p$  and  $3p$  orbitals respectively.

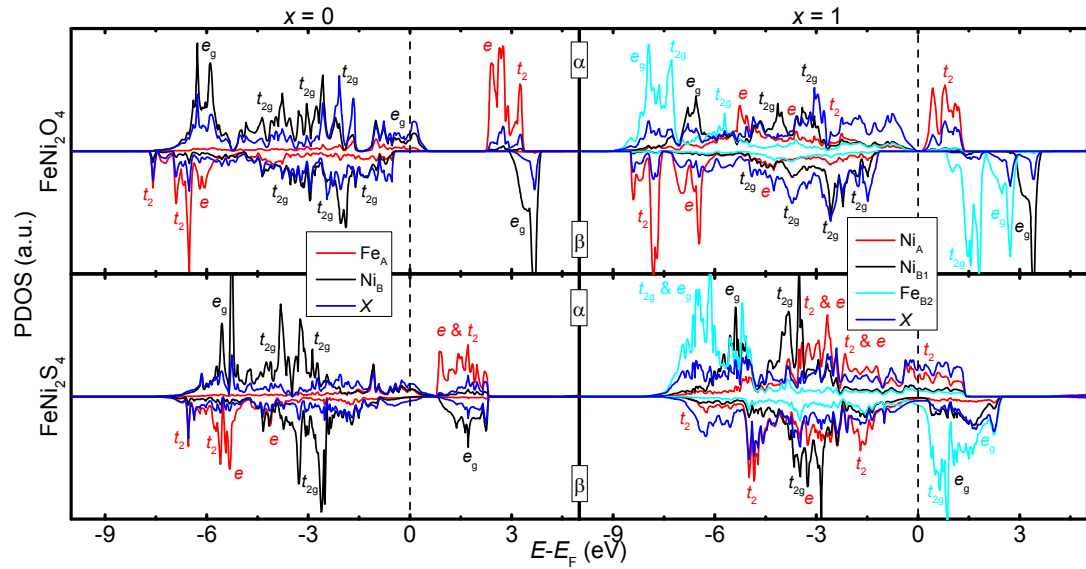
### 3.7.5 $FeNi_2X_4$

For both Ni-based (thio)spinel, when  $x = 0$ , the bands' pattern is similar and follows the same distribution as described in previous cases, see **Figure 3.7** left panels. The oxide is half-metal due to a strong hybridization of the partially-occupied  $Ni_B e_g$  bands with the  $O p$  orbitals that cross the Fermi energy in the majority channel of the spins, see also the integer value of  $M_s$  in **Table 3.4**. The main difference between oxide and sulfide lies in the fact that bands in the latter are closer to the Fermi energy in both spin channels, thus becoming a metallic system. The thiospinel's metallic character is given by the  $S p$  orbitals with a small hybridization (only in the majority channel of

the spins) with the partially-occupied  $\text{Fe}_A$   $e$  and  $t_{2g}$  levels bands, see the decimal  $M_S$  in **Table 3.4**.

When Ni is filling the A sublattice, the Ni-based spinel becomes half-semiconductor with a band gap of 0.20 and 2.05 eV in the majority and minority channels of the spins, respectively, see **Figure 3.7** top right panel. While the position and distribution of the bands due to the ions occupying different positions is equivalent to what we have presented in previous cases, for inverse  $\text{FeNi}_2\text{O}_4$  spinel, nonetheless, this is not the case for the sulfide counterpart. In the inverse  $\text{FeNi}_2\text{S}_4$  system, the  $\text{Ni}_A$  and  $\text{Ni}_{B1}$  ions are less magnetic than expected and the valence and conduction bands are merged together, making this compound metallic for any inversion degree. The inverse Ni-based (thio)spinel have integer values of  $M_S$  (see **Table 3.4**) regardless of whether they are insulator or metal. Note that in the case of the metal inverse  $\text{FeNi}_2\text{S}_4$  spinel, the decimal number in  $M_S = 4.00 \mu_B/\text{f.u.}$  is a special case. In  $\text{FeNi}_2\text{S}_4$ , for any inversion degree, the metallic character agrees with the experimental findings (Townsend *et al.*, 1977; Vaughan and Craig, 1985).





**Figure 3.7.** Atomic projections of the spin decomposed total density of states (PDOS) for  $FeNi_2O_4$  and  $FeNi_2S_4$ . Fe and Ni contributions are from the 3d bands. O and S contributions are from the 2p and 3p orbitals respectively.

### 3.8 Chapter conclusions

We have performed systematic electronic structure calculations for a series of (thio)spinel, which elucidate the cation distribution as well as the magnetic and electronic properties of these materials.

We have determined the thermodynamic inversion degree for the  $FeM_2X_4$  (thio)spinel at temperatures used typically in their synthesis, which agrees reasonably well with available experimental evidence. More quantitative results could be expected if additional values of inversion degrees and different cations arrangements to those explored in this work are considered for the spinel compositions, although we do not expect this to change the trend of our results. We have found that  $FeM_2X_4$  spinel are

more likely to have a normal distribution of cations when  $M$  is one of the two atoms to the left of Fe in the periodic table.  $\text{FeMn}_2\text{O}_4$  has a metastable intermediate inversion degree that could only be found by considering entropic factors, which also agrees with experiment. It may be that the global minimum, *i.e.* the inverse spinel, is difficult to attain due to kinetic control. When  $M$  is one of the two atoms to the right of Fe in the periodic table, with the exception of  $\text{FeCo}_2\text{O}_4$ , the spinels have an intermediate inversion degree ranging between 10 to 50%. Finally, the oxidic spinel of Co and Fe has a completely inverse distribution of the cations. The small equilibrium inversion degree of  $\text{FeNi}_2\text{S}_4$  agrees acceptably well with the one found in natural samples. Fitting the experimental spin magnetization of saturation of  $\text{FeNi}_2\text{X}_4$  to the ones calculated for the normal and inverse structures gives inversion degrees with a similar trend to those calculated using thermodynamic arguments. This procedure could also be applied to  $\text{FeCo}_2\text{S}_4$  and  $\text{FeNi}_2\text{O}_4$  if the magnetizations of saturation are known experimentally.

No single factor among those analyzed, *i.e.* neither crystal field stabilization effects nor the size of the cations, can account by themselves for the equilibrium inversion degree.

For the two extreme scenarios, namely the completely normal and inverse spinels, we have calculated the electronic and magnetic properties of the metal atoms as well as the electronic properties of the bulk phase. We found that the majority of the spinels for any extreme inversion degree are half-metals in the ferrimagnetic state. Notable exceptions are the inverse Co and Ni oxide spinels, which are insulators, and their

sulfide counterparts that are metallic for any inversion degree, together with the inverse  $\text{FeMn}_2\text{S}_4$ . Notably, we found that hard anions stretch the band structure, giving the biggest band gaps and therefore the best half-metallic properties.

Finally, we have proposed a theoretical structure for  $\text{FeMn}_2\text{S}_4$  and  $\text{FeCo}_2\text{S}_4$  and have predicted their electronic and magnetic properties and equilibrium inversion degree.

# 4

## Mechanical properties of magnetite

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### 4.1 Introduction

Iron is the third most abundant element on the earth's surface and it is present as iron oxide minerals in nearly every type of rock and soil (Cornell and Schwertmann, 2003). These minerals have been known and used as a source of colouring agents (Hofmann, 1962; Middleton, 1987; Noll, 1980; Pomiès *et al.*, 1999; Rigby *et al.*, 1989) and metallic iron since ancient times and in the modern world they are used additionally as ores for the steel industry. It is estimated that currently more than 99 % of the total iron oxides mined worldwide are used in the iron and steel industry (Cornell and Schwertmann, 2003). Most of the iron oxide phases, in very small amounts, are also part of the biominerals in living organisms, where they are metabolic byproducts or have functions such as magnetotaxis, teeth hardening, navigation or iron storage (Addadi and Weiner, 1992; Bazylinski and Moskowitz, 1998; Frankel, 1991; Kirschvink *et al.*, 1985; Konhauser, 1998). Presently, for instance, as rocks containing iron oxides are weathered to form soils, iron is channelled into the global cycle of the elements (Cornell and Schwertmann, 2003). Oxides of iron occur frequently with Fe in different oxidation states, yielding various types of natural iron oxides. In general, iron oxide minerals display interesting magnetic and electrical properties, which are

strongly related to the stoichiometric ratio between Fe and O atoms and their crystalline structure. These minerals are classified according to their Fe:O ratio as wüsite ( $0.83 < \text{Fe:O} < 0.95$ ), magnetite ( $\text{Fe}_3\text{O}_4$ ) as well as the polymorph hematite  $\alpha$ -, maghemite  $\gamma$ -,  $\beta$ - and  $\varepsilon$ - phases of  $\text{Fe}_2\text{O}_3$ .

Magnetite, together with hematite, is one of the most thermodynamically stable and therefore widely distributed iron oxide phases (Cornell and Schwertmann, 2003).  $\text{Fe}_3\text{O}_4$  is formed as the final product in the mild reduction of akaganéite ( $\beta$ - $\text{FeOOH}$ ) (Blesa *et al.*, 1986) or hematite (Sapieszko and Matijević, 1980) with hydrazine or via combination in solution of lepidocrocite ( $\gamma$ - $\text{FeOOH}$ ) (Tamura *et al.*, 1983) or ferrihydrite (Mann *et al.*, 1989; Sugimoto and Matijević, 1980) with  $\text{Fe}^{2+}$  ions, proceeding all the reactions through a dissolution-recrystallization mechanism. It is of significant research interest that  $\text{Fe}_3\text{O}_4$  is a common inverse spinel mineral. Its cubic unit cell consists of eight  $\text{Fe}_3\text{O}_4$  subunits with a lattice parameter of  $\sim 8.390 \text{ \AA}$  (Wright *et al.*, 2002). The inverse spinel arrangement is reflected by the formula  $\text{Fe}^{3+}(\text{Fe}^{3+}\text{Fe}^{2+})\text{O}_4$ , where there are two possible locations for the Fe ions: the tetrahedral sites, filled by  $\text{Fe}^{3+}$  ions, and the octahedral sites, where both  $\text{Fe}^{3+}$  and  $\text{Fe}^{2+}$  ions reside. The spins in tetrahedral and octahedral Fe are aligned antiparallel with respect to each other, indicating ferrimagnetic (Néel, 1948; Shull *et al.*, 1951) and half-metallic properties (Zhang and Satpathy, 1991).  $\text{Fe}_3\text{O}_4$  magnetization of saturation, as well as the Curie temperature, have been reported to be  $4.00 \mu_{\text{B}}/\text{f.u.}$  (Zhang and Satpathy, 1991) and 858 K (Mulakaluri *et al.*, 2009; Pentcheva *et al.*, 2005) respectively for both natural and synthetic samples. In addition, the particle size is important for magnetism measurements, as it determines the contribution of the

external shell in relation to the bulk-core, where ultrafine magnetic particles produce superparamagnetic behaviour (Néel, 1954).

In this chapter, we have used DFT +  $U$  methodology to report intrinsic and mechanical properties of  $\text{Fe}_3\text{O}_4$ , including its elastic constants, and compared these with the same properties reported of  $\text{Fe}_3\text{S}_4$ . The elastic constants provide important information concerning the nature of the forces operating in the solids and form a link between mechanical and dynamical properties. These properties predict a more ionic character for  $\text{Fe}_3\text{O}_4$  than for its isostructural sulfide counterpart  $\text{Fe}_3\text{S}_4$ . The results presented in this chapter have been published (Roldan *et al.*, 2013).

## **4.2 Computational details**

We have used the VASP code to carry out spin-polarized calculations within the usual Kohn-Sham (KS) implementation of density functional theory (DFT) (Kresse and Furthmüller, 1996a, 1996b; Kresse and Hafner, 1994, 1993). The generalized gradient approximation (GGA) was employed with the PW91 functional (Perdew *et al.*, 1993, 1992), with the spin interpolation formula of Vosko *et al.* (1980) and long-range dispersion interactions correction via the semiempirical D2 method of Grimme (2006). The inner electrons consisting of orbitals up to, and including, the  $3p$  levels for Fe and the  $1s$  for O, were described by the projector augmented wave (PAW) method (Blöchl, 1994). KS valence states were expanded in a plane-wave basis set with a cut off at 520 eV for the kinetic energy. This high value ensured that no Pulay stresses occurred within the cell during relaxations. An energy threshold defining the self-consistency

of the electron density was set to  $10^{-5}$  eV. In order to improve the convergence of the Brillouin-zone integrations, the partial occupancies were determined using the tetrahedron method with Blöchl corrections. The optimization of the structures was conducted via a conjugate gradients technique, which uses the total energy and the Hellmann-Feynman forces on the atoms, where in this chapter the break condition for the ionic relaxation loop was set at 0.01 eV/Å. Spin-orbit coupling was not considered as its influence is negligible on the atomic magnetic moments (Zhang *et al.*, 2012).

Within the VASP code, it is possible to assign an initial spin population and orientation at each atom, where the system will converge to the ground state spin configuration, but keeping the same orientation on the spins. Thus, the initial magnetic moment was described by a high spin ferrimagnetic distribution on both types of Fe. However, to describe the magnetic behaviour properly, an accurate treatment of the electron correlation in the localized *d*-Fe orbitals is crucial. Hence, we have used the Hubbard approximation (Anisimov *et al.*, 1992; Dudarev *et al.*, 1998) to improve the description of localized states in this type of system, where standard LDA and GGA functionals fail (Moreira *et al.*, 2002). The disadvantage of this approximation is the rather empirical character of the  $U_{\text{eff}}$  parameter choice, a feature that also appears when using hybrid functionals since the amount of Fock exchange is system-dependent (Ciofini *et al.*, 2004; Corà, 2005; Illas and Martin, 1998; Moreira *et al.*, 2002; Muñoz *et al.*, 2004). We fitted the  $U_{\text{eff}}$  versus the band gap in the low-symmetry unit cell of Fe<sub>3</sub>O<sub>4</sub>, below the Verwey temperature (Wright *et al.*, 2002), which presents some insulating character shown by a small band gap of ~0.14 eV (Chainani *et al.*, 1995; Park *et al.*, 1997, 1998). As we found that  $U_{\text{eff}} = 3.8$  eV opens a band gap of 0.14 eV,

we have considered this value in the calculations of the 56 atoms high-symmetry unit cell.

Bulk calculations were carried out on a spinel cubic cell containing 56 atoms, of which 24 were Fe atoms and 32 were O atoms. All atoms were fully relaxed until the required accuracy was reached. Calculations were carried out in the reciprocal space of the cell and were described by a Monkhorst-Pack grid (Monkhorst and Pack, 1976) of  $4 \times 4 \times 4$   $\Gamma$ -centred  $k$ -points, which ensures the electronic and ionic convergence. Higher numbers of  $k$ -points were tested but these led to an energy difference of less than 0.01 eV.

The elastic tensors were determined using the standard finite difference technique, where the calculation of the second order elastic constants is achieved through the description of a linear elastic strain response of the material as it opposes to a certain stress. Each elastic constant ( $C_{ij}$ ) is a component of a matrix, denoted by Voigt notation as subscript. We have derived each  $C_{ij}$  via the second-order Taylor expansion of the total energy with respect to the applied distortion, equation (4.1), where  $E$  is the total energy of the stressed cell,  $\varepsilon$  is the component of the applied strain and  $V$  is the equilibrium volume (Ainsworth *et al.*, 2011; Devey *et al.*, 2008).

$$C_{ij} = \frac{1}{V} \frac{\partial^2 E}{\partial \varepsilon_i \partial \varepsilon_j} \quad (4.1)$$

We have optimized both the lattice parameters and the internal atomic coordinates to avoid residual stresses, which is essential in the performance of an accurate comparison. The strain applied was up to  $\pm 0.4$  % of the cell parameter keeping a



constant volume as described by Ainsworth *et al.* (2011). Due to the crystal symmetry, the minimum linearly independent sets of strains to determine the elastic constants are two, leading to the  $C_{11}$ ,  $C_{12}$  and  $C_{44}$  matrix components. For less symmetric crystals, such as orthorhombic, monoclinic or triclinic, space groups up to six sets need to be determined.

### **4.3 Structural properties**

After geometry optimisation, the calculated cubic cell parameter for  $\text{Fe}_3\text{O}_4$  is 8.390 Å while the experimental value is 8.390405 Å (Wright *et al.*, 2002). The optimized lattice parameter is in good agreement with the experiment considering that GGA functionals typically underestimate the structural properties of strongly correlated magnetic systems, such as metal oxides, due to the underestimation of exchange-splitting (Hafner, 2008). The mean distance between octahedral Fe and surrounding O atoms is  $d(\text{Fe}_{\text{Oh}}-\text{O}) = 2.05$  Å, which is slightly larger than for tetrahedral Fe  $d(\text{Fe}_{\text{Td}}-\text{O}) = 1.89$  Å, with both distances differing less than 0.01 Å from reported measurements (Fleet, 1982). As expected, both distances are shorter in magnetite than in its isostructural sulfide counterpart greigite, where the reported mean distances are  $d(\text{Fe}_{\text{Oh}}-\text{S}) = 2.37$  Å and  $d(\text{Fe}_{\text{Td}}-\text{S}) = 2.18$  Å (Roldan *et al.*, 2013). We carried out Bader analysis to obtain the arrangement of charge and spin densities along the unit cells, which, considering the electron delocalisation by using DFT, do not provide enough information to determine the electronic structure and supplementary techniques as density of states are required. Structural data of  $\text{Fe}_3\text{O}_4$  and its isostructural sulfide

counterpart  $\text{Fe}_3\text{S}_4$  is summarised on **Table 4.1**. We have also carried out a DF Perturbation theory (Wu *et al.*, 2005) calculation with fully relaxed cell vectors and ionic coordinates to obtain the phonon vibrations, where the 3N vibrational frequencies range between 674–142  $\text{cm}^{-1}$  for  $\text{Fe}_3\text{O}_4$  which are, as expected from more polar bonds, considerably higher than 385–59  $\text{cm}^{-1}$  for its isostructural sulfide counterpart  $\text{Fe}_3\text{S}_4$  (Roldan *et al.*, 2013).

**Table 4.1.** Summary of geometric and electronic properties of bulk  $\text{Fe}_3\text{O}_4$ . The properties listed are the mean value of the first-neighbours distance ( $d$ ), the charge ( $q$ ) and the spin densities ( $m_s$ ). The minus sign in the spin density represents the antiparallel alignment in the ferrimagnetic spinels. Previously reported values of its isostructural sulfide counterpart greigite ( $\text{Fe}_3\text{S}_4$ ) are shown for comparison.

	$\text{Fe}_3\text{O}_4$ bulk	$\text{Fe}_3\text{S}_4$ bulk <sup>A</sup>
$d(\text{Fe}_{\text{Td}})$ (Å)	1.890	2.180
$d(\text{Fe}_{\text{Oh}})$ (Å)	2.050	2.370
$d(\text{O/S})$ (Å)	2.010	2.323
$q(\text{Fe}_{\text{Td}})$ ( $e^-$ )	1.8	1.1
$q(\text{Fe}_{\text{Oh}})$ ( $e^-$ )	1.7	1.0
$q(\text{S})$ ( $e^-$ )	-1.3	-0.8
$m_s(\text{Fe}_{\text{Td}})$ ( $\mu_B$ )	-4.0	-2.8
$m_s(\text{Fe}_{\text{Oh}})$ ( $\mu_B$ )	3.9	3.0
$m_s(\text{O/S})$ ( $\mu_B$ )	0.1	0.1

<sup>A</sup> Roldan *et al.* (2013)

## 4.4 Mechanical properties

An accurate experimental determination of elastic constants needs large pure single crystals that are difficult to obtain, and it is hence not surprising that there are relatively few reports about the mechanical properties of  $\text{Fe}_3\text{O}_4$  available in the literature (Alexandrov and Ryzhova, 1961; Hearmon, 1984; Isida *et al.*, 1996; Moran and Lüthi, 1969; Reichmann and Jacobsen, 2004; Siratori and Kino, 1980). We have derived the elastic constants  $C_{11}$ ,  $C_{12}$  and  $C_{44}$  of the  $\text{Fe}_3\text{O}_4$  cubic cell. These elastic constants, summarised in **Table 4.2**, quantify the response of the crystal to external forces, and are related to macroscopic parameters obtained from an average of randomly oriented polycrystals.

The elastic constant  $C_{11}$  (and equivalent:  $C_{22}$  and  $C_{33}$ ) measures the response of the cell to a pressure applied perpendicular to each cell face.  $C_{11}$  is calculated at 242 GPa for  $\text{Fe}_3\text{O}_4$  (**Table 4.2**). The calculated value of  $C_{11}$  is clearly higher for  $\text{Fe}_3\text{O}_4$  than for  $\text{Fe}_3\text{S}_4$  (Roldan *et al.*, 2013), with the  $C_{11}$  of  $\text{Fe}_3\text{O}_4$  fairly close to the accepted experimental value of 260.5 GPa (Reichmann and Jacobsen, 2004). This early result corroborates the suggestion that oxide is harder to compress than the sulfide. A distortion along two different axes leads to  $C_{12}$ ,  $C_{21}$ ,  $C_{23}$  and  $C_{32}$ , which are equivalent elastic constants. The calculated  $C_{12}$  for  $\text{Fe}_3\text{O}_4$  differs less than 19 GPa from the experimental value (Reichmann and Jacobsen, 2004) while it is 118.1 GPa smaller than  $C_{12}(\text{Fe}_3\text{S}_4)$  (Roldan *et al.*, 2013). For the last independent elastic constant,  $C_{44}$ , we obtain a value of 55 GPa for  $\text{Fe}_3\text{O}_4$  which is just 16 GPa above  $C_{44}(\text{Fe}_3\text{S}_4)$  (Roldan *et al.*, 2013). The calculated elastic constants for  $\text{Fe}_3\text{O}_4$  compare well with the

experimental benchmark (Reichmann and Jacobsen, 2004) with a maximum discrepancy of 13 %.

**Table 4.2.** Physical properties of Fe<sub>3</sub>O<sub>4</sub> derived from the elastic constants ( $C_{ij}$ ): bulk modulus ( $B$ ), shear modulus ( $G$ ),  $B/G$  ratio, Young's modulus ( $Y$ ), Poisson's ratio ( $\sigma$ ) and anisotropy factor ( $A$ ). The optimized lattice parameter of Fe<sub>3</sub>O<sub>4</sub> is 8.390 Å. Previously reported Fe<sub>3</sub>O<sub>4</sub> and Fe<sub>3</sub>S<sub>4</sub> values are shown for comparison.

	Fe <sub>3</sub> O <sub>4</sub>	Fe <sub>3</sub> O <sub>4</sub> (Experimental)	Fe <sub>3</sub> S <sub>4</sub> <sup>B</sup>
$C_{11}$ (GPa)	242.3	260.5 ± 1.0 <sup>A</sup>	104.7
$C_{12}$ (GPa)	159.9	148.3 ± 3.0 <sup>A</sup>	41.8
$C_{44}$ (GPa)	55.0	63.3 ± 1.5 <sup>A</sup>	39.0
$B$ (GPa)	187.4	185.7 ± 3.0 <sup>A</sup>	62.8
$G$ (GPa)	49.5	60.3 ± 3.0 <sup>A</sup>	36.0
$B/G$	3.8	3.1	1.7
$Y$ (GPa)	136.5	163.5	90.6
$\sigma$	0.40	0.36	0.29
$A$	1.34	1.13	1.24

<sup>A</sup> Reichmann and Jacobsen (2004)

<sup>B</sup> Roldan *et al.* (2013)

We have calculated the Fe<sub>3</sub>O<sub>4</sub> bulk and shear moduli by equating the uniform strain in the crystal aggregates to the external isostrain in the Voigt approximation (Voigt, 1928). Further, we have derived other elastic properties such as the Young's modulus, the Poisson's coefficient and the shear anisotropy factor (Wu and Hu, 2007). The elastic moduli, thus, are useful in predicting the structural stability of materials: the

bulk modulus ( $B$ ), from equation (4.2), represents the resistance to fracture, while the shear modulus ( $G$ ), equation (4.3), measures the resistance to a plastic deformation.

$$B = \frac{C_{11} + 2C_{12}}{3} \quad (4.2)$$

$$G = \frac{C_{11} - C_{12} + 3C_{44}}{5} \quad (4.3)$$

The calculated bulk modulus for  $\text{Fe}_3\text{O}_4$  is 124.6 GPa, which is 62.8 GPa bigger than its sulfide analogue (Roldan *et al.*, 2013), whereas it differs by only 1.7 GPa from the reported value (Reichmann and Jacobsen, 2004). The shear modulus is also bigger in  $\text{Fe}_3\text{O}_4$  than in the sulfide by 13.5 GPa (Roldan *et al.*, 2013). These values already depict a  $\text{Fe}_3\text{O}_4$  less deformable than  $\text{Fe}_3\text{S}_4$ , which can also be explained by the relationship between  $B$  and  $G$ , which provides information about the material's fragility/ductility. A ratio of  $B/G > 1.75$  is associated with ductility, whereas a lower value corresponds to a brittle material (Pugh, 1954). Given a  $B/G$  ratio of 3.8 for  $\text{Fe}_3\text{O}_4$  (or 3.1 as derived from Reichmann and Jacobsen (2004)) and 1.74 for  $\text{Fe}_3\text{S}_4$  (Roldan *et al.*, 2013), our calculations show that the anionic species in the iron spinels have a significant effect on their properties.  $\text{Fe}_3\text{O}_4$  is softer but less liable to break or shatter compared to the same structure with sulfur as its anion, which is less ductile.

The Young's modulus and Poisson's ratio (equations (4.4) and (4.5) respectively) are characteristic properties of a material, related to its elasticity, and are often used to provide a measure of the stiffness of a solid.

$$Y = \frac{9BG}{3B + G} \quad (4.4)$$

$$\sigma = \frac{C_{12}}{C_{11} + C_{12}} \quad (4.5)$$

The Fe<sub>3</sub>O<sub>4</sub> Young's modulus is bigger than the one of Fe<sub>3</sub>S<sub>4</sub> by 45.9 GPa (Roldan *et al.*, 2013), showing that the Fe<sub>3</sub>O<sub>4</sub> structure is less susceptible to physical changes than the sulfide, which is a metastable iron sulfide phase (Lennie *et al.*, 1997). Poisson's ratio ( $\sigma$ ) measures the stability of the crystal to shear and provides more information about the interatomic forces than any other elastic property. A Poisson's ratio above 0.25 means that the interaction between atoms is mainly through central forces (with ionic character); whereas lower values indicate that large volume changes occur during uniaxial deformation. A Poisson's ratio below 0.1 is characteristic of covalent materials (Shein and Ivanovskii, 2008), this ratio is therefore a measure of bond-covalency. The values of  $\sigma(\text{Fe}_3\text{O}_4) = 0.40$  and  $\sigma(\text{Fe}_3\text{S}_4) = 0.29$  (Roldan *et al.*, 2013) show that the governing force between Fe–O atoms in Fe<sub>3</sub>O<sub>4</sub> is more ionic than in greigite. This result is in full agreement with the little Fe–O orbital overlap observed in the density of states, see Chapter 3, indicating a lower degree of covalency in Fe<sub>3</sub>O<sub>4</sub> compared to Fe<sub>3</sub>S<sub>4</sub>.

Elastic anisotropy ( $A$ ) (equation (4.6)) of a crystal is correlated with the tendency of the material to form micro-cracks. While a perfectly isotropic crystal would have  $A = 1$ , we calculate a value  $A(\text{Fe}_3\text{O}_4) = 1.34$ , which is just 0.10 above the reported value of  $A(\text{Fe}_3\text{S}_4)$  (Roldan *et al.*, 2013) indicating that Fe<sub>3</sub>O<sub>4</sub> behaviour slightly depends more on the stress direction than Fe<sub>3</sub>S<sub>4</sub>.

$$A = \frac{2C_{44}}{C_{11} - C_{12}} \quad (4.6)$$

The overall description derived from the elastic properties is that magnetite is less liable to deformations than  $\text{Fe}_3\text{S}_4$  (large elastic moduli and anisotropy values) and the forces between the ions are more localised in the oxide comparing with a softer anion such as in the sulfide greigite (large Poisson's ratio). As we have shown in Chapter 3, the present mechanical description agrees with the description derived from the electronic structure.

#### **4.5 Chapter conclusions**

In the present work, we have used the DFT +  $U$  approach ( $U_{\text{eff}} = 3.8$  eV) to carry out a systematic study of the properties of magnetite ( $\text{Fe}_3\text{O}_4$ ) and compare them with experiments and greigite ( $\text{Fe}_3\text{S}_4$ ). The calculated first neighbour distances in the  $\text{Fe}_3\text{O}_4$  material differ by less than  $0.01$  Å from previous reports. However, the average distance between the Fe and the corresponding anion is different enough ( $\sim 0.3$  Å) to provide a clear differentiation between the pure oxide and the sulfide compound, hardly distinguishable in synthetic samples. Furthermore, we have derived a number of mechanical properties from the independent elastic constants  $C_{11}$ ,  $C_{12}$  and  $C_{44}$  corresponding to  $\text{Fe}_3\text{O}_4$ . The ratio of the bulk to shear moduli allowed us to evaluate the effect of the anionic species in the material, *i.e.* magnetite is harder than greigite, but less liable to fracture and Fe–O interaction has a more ionic character than Fe–S in the sulfide.

# 5

## Structures, stabilities and redox behaviour of the major surfaces of $\text{Fe}_3\text{O}_4$

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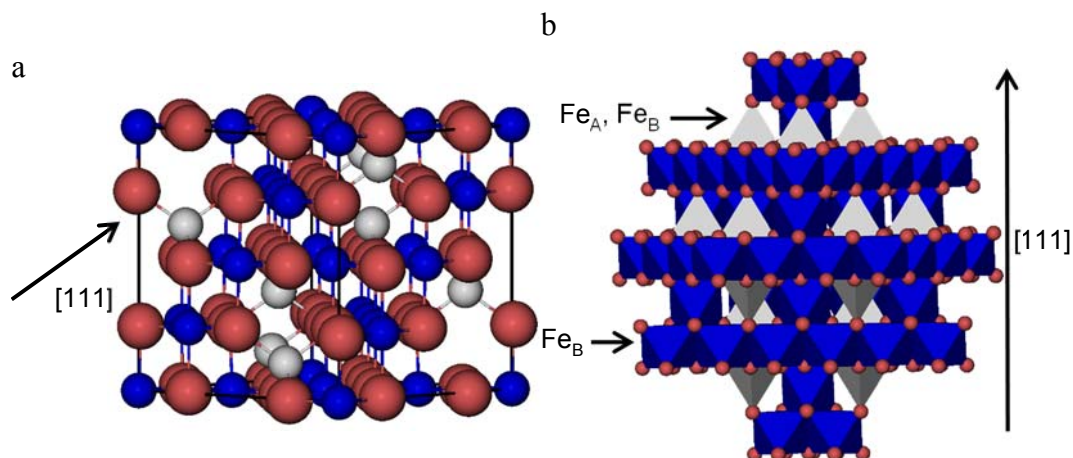
### 5.1 Introduction

Magnetite,  $\text{Fe}_3\text{O}_4$ , is of significant importance as the main component of industrial catalysts in, for example, the dehydrogenation of ethylbenzene (Weiss and Ranke, 2002) which is used as the primary feedstock for the production of 85% of commercial styrene (Chen and Updated by Staff, 2006; James and Castor, 2012).  $\text{Fe}_3\text{O}_4$  is also used as a catalyst for the water gas shift (WGS) reaction, where molecular hydrogen is formed from carbon monoxide and water (Campbell *et al.*, 1970; Gonzalez *et al.*, 1986; Rethwisch *et al.*, 1985), the Fischer-Tropsch synthesis of hydrocarbons (Li *et al.*, 2001) and the Haber-Bosch process for the production of ammonia (Bond, 1974; Bridger and Snowden, 1970; Somorjai and Salmeron, 1986; Topham, 1985). The high stability and catalytic activity as well as its low cost make  $\text{Fe}_3\text{O}_4$  the catalyst of choice for these heterogeneous processes (Cornell and Schwertmann, 2003). Furthermore,  $\text{Fe}_3\text{O}_4$  is important in other applications, such as groundwater remediation (dos Santos Coelho *et al.*, 2008), and potentially in spintronic devices due to the conducting



properties of only one channel of spins (Roldan *et al.*, 2013; Zhang and Satpathy, 1991).

Above 120 K, Fe<sub>3</sub>O<sub>4</sub> crystallizes in the spinel structure (Hill *et al.*, 1979) with space group  $Fd\bar{3}m$  (cubic) (Wright *et al.*, 2002), but when cooled below that temperature, it undergoes a phase transition known as the Verwey transition, where the space group changes to  $P2_1/m$  (monoclinic) (Wright *et al.*, 2002). Thus, at room temperature, Fe<sub>3</sub>O<sub>4</sub> has the spinel face-centred cubic unit cell, on which we will focus in this chapter. In this structure, the oxygen ions are regularly close packed along the [111] direction, separating layers of Fe ions, which appear in two different alternate arrangements. One is composed of Fe ions occupying two types of positions (octahedral (Fe<sub>B</sub>) and tetrahedral (Fe<sub>A</sub>)) and the other one has only Fe<sub>B</sub>, shown in the scheme in **Figure 5.1**. The experimental lattice constant for Fe<sub>3</sub>O<sub>4</sub> is  $a = 8.390 \text{ \AA}$  (Wright *et al.*, 2002) and each unit cell is composed of eight formula units (four rhombohedral primitive cells). Unlike the rest of the iron oxides, Fe<sub>3</sub>O<sub>4</sub> has Fe ions in mixed valence states, with the chemical formula often written as  $\text{Fe}_A^{3+} [\text{Fe}^{2+}\text{Fe}^{3+}]_B \text{O}_4$ , where A and B represent the tetrahedral and octahedral sites, respectively. The distribution where the 3+ cations occupy the A sites, while the B sites contain a mixture of 2+ and 3+ cations, is called *inverse* (in contrast with the *normal* spinel where the 2+ cations are all located in the A site).



**Figure 5.1.** View of the bulk structure of Fe<sub>3</sub>O<sub>4</sub>: (a) ball and stick model of the cubic unit cell and (b) polyhedral model showing the alternating layers of Fe<sub>B</sub> and Fe<sub>A</sub>-Fe<sub>B</sub> ions separated by O ions. Fe<sub>A</sub> ions are in grey, Fe<sub>B</sub> ions are in blue and O ions are in red.

Biological (Faivre and Schüler, 2008; Lins *et al.*, 2007), extra-terrestrial (Bradley *et al.*, 1996; McKay *et al.*, 1996) and synthetic (Faivre *et al.*, 2005; Zhao *et al.*, 2008) Fe<sub>3</sub>O<sub>4</sub> crystals have been described by several authors. Among all the crystal habits in which this mineral has been found, the three most common are the octahedral morphology enclosed by (111) surfaces; a truncated octahedron by adding the (001) plane and as twinning on the (111) surface (Cornell and Schwertmann, 2003; Zhao *et al.*, 2008). Zhao *et al.* (2008) synthesized Fe<sub>3</sub>O<sub>4</sub> under a systematic range of conditions using a polyol process, where the crystals obtained ranged from cubic, truncated octahedral to octahedral shapes, depending on pH.

The stacking sequence of the atomic planes perpendicular to the [001] direction can be represented as Fe<sub>A</sub>-(O-Fe<sub>B</sub>) (atoms inside brackets are within the same layer), leading in principle to two different bulk-like terminations for the (001) surface, which

are both polar. There are also two possible non-dipolar reconstructions of this surface, *i.e.* when the slab is terminated by either 0.5 mono layers (ML) Fe<sub>A</sub> or 0.5 ML O-Fe<sub>B</sub> in both the top and bottom surface. Experimentally, this surface has been found to have a  $(\sqrt{2} \times \sqrt{2})R45^\circ$  reconstruction for which different rationalizations have been given. Studies combining low-energy electron diffraction (LEED), X-ray photoelectron spectroscopy (XPS), X-ray photoelectron diffraction (XPD) and scanning tunnelling microscopy (STM) (Chambers *et al.*, 2000), as well as another work combining LEED with low-energy ion scattering (LEIS) (Mijiritskii and Boerma, 2001), have suggested a (001) surface terminated by the reconstructed non-dipolar 0.5 ML of Fe<sub>A</sub>. On the other hand, a different study, combining STM, LEED, LEIS and XPS, has suggested a surface terminated by the reconstructed charge-compensated O-Fe<sub>B</sub> with one oxygen vacancy per unit cell (Stanka *et al.*, 2000). Meanwhile, Voogt *et al.* (1999) were unable to differentiate them based on reflection high-energy electron diffraction (RHEED) and LEED, suggesting as possible terminations: the reconstructed non-dipolar 0.5 ML Fe<sub>A</sub> layer or the reconstructed charge-compensated O-Fe<sub>B</sub> layer with oxygen vacancies or hydroxyl groups (Voogt *et al.*, 1999). More recently, Parkinson *et al.* (2011) have identified experimentally, using STM and LEED images, that the (001) surface terminations are temperature dependent. The 0.5 ML O-Fe<sub>B</sub> termination or one with *wavelike* structure and small defects, such as hydroxyl groups, is thermodynamically more stable at 923 K, while at lower temperatures (623 K) the surface terminated by 0.5 ML of Fe<sub>A</sub> is observed, although some point-defects may stabilise other terminations (Parkinson *et al.*, 2011).

To date, most computational efforts have concentrated on explaining the stability of the bulk-like dipolar O-Fe<sub>B</sub> termination, leaving largely ignored the reconstructed non-dipolar 0.5 ML Fe<sub>A</sub> termination. Pentcheva *et al.* (2005) have studied the stability under varying redox conditions of one ideal and reconstructed stoichiometric (0.5 ML Fe<sub>A</sub>) and several non-stoichiometric terminations using spin-polarised density functional theory (DFT) calculations. These authors found that the modified polar bulk-like O-Fe<sub>B</sub> termination was the most stable for the whole range of chemical potential (Pentcheva *et al.*, 2005), which was validated by experimental X-rays diffraction (XRD) (Pentcheva *et al.*, 2005) and by the *wavelike* pattern along the [011] direction observed on experimental STM images (Fonin *et al.*, 2005). Further studies by Parkinson *et al.* (2012) of this surface termination using spin-polarized DFT + *U* calculations supported the Jahn-Teller distortion of this surface based on simulation of STM images of antiphase domain boundaries (APDBs) (Parkinson *et al.*, 2012).

In the [011] direction, Fe<sub>3</sub>O<sub>4</sub> is composed of alternating layers of (Fe<sub>A</sub>-Fe<sub>B</sub>-O) and (Fe<sub>B</sub>-O). After reconstruction, two non-dipolar terminations are possible: one terminated by the (Fe<sub>B</sub>-O) layer with 0.25 ML Fe<sub>A</sub> on top and another terminated by the (Fe<sub>A</sub>-Fe<sub>B</sub>-O) layer with 0.25 ML of Fe<sub>A</sub> vacancies. Single crystal studies carried out on this surface, involving the use of STM, LEED, scanning tunnelling spectroscopy (STS) and Auger electron spectroscopy (AES), have found a one-dimensional reconstruction along the [01 $\bar{1}$ ] direction, which was concluded not to have a simple bulk iron-oxide termination (Jansen *et al.*, 1996, 1995). Subsequent studies, supported by atomically resolved STM (G. Maris *et al.*, 2006; Gabriela Maris

*et al.*, 2006a, 2006b), suggested a model based on a surface terminated by a polar ( $\text{Fe}_A\text{-Fe}_B\text{-O}$ ) bulk-like layer, in order to explain the atomic rows observed on the tops of ridges along the  $[01\bar{1}]$  direction. However, the authors also left open the possibility of alternative models, including surface reconstruction, to interpret the STM images (G. Maris *et al.*, 2006).

The (111) surface is the dominant cleavage plane of  $\text{Fe}_3\text{O}_4$ , and the stacking of the atomic layers perpendicular to this surface is  $\text{Fe}_{A1}\text{-Fe}_{B1}\text{-Fe}_{A2}\text{-O}_1\text{-Fe}_{B2}\text{-O}_2$ . All of the six possible different bulk-like surface terminations are dipolar. Only two reconstructions lead to non-dipolar terminations, *i.e.* 0.5 ML  $\text{Fe}_{B1}$  or 0.5 ML  $\text{Fe}_{B2}$ . Several possible terminations have been described from LEED and STM results: one dipolar plane showing close packed features (due to 0.75 ML of  $\text{Fe}_{B2}$  and 0.25 ML of  $\text{O}_2$  over a close packed  $\text{O}_1$  layer) (Lennie *et al.*, 1996); a reconstructed non-dipolar honeycomb plane (due to 0.5 ML of  $\text{Fe}_{B1}$ ), which was the most stable one (Lennie *et al.*, 1996); a reconstructed dipolar 0.25 ML  $\text{Fe}_{A1}$  plane (Ritter and Weiss, 1999); as well as a regular bulk-like dipolar  $\text{Fe}_{A1}$  termination and an intermediate case between the former two, which were obtained as a function of the annealing temperature (Berdunov *et al.*, 2004a). Again, most of the computational studies have been directed towards the dipolar bulk-like terminations of the (111) surface. Martin *et al.* (2009) used spin-polarized DFT calculations to study the dipolar non-stoichiometric bulk-like  $\text{Fe}_{B1}$  and  $\text{Fe}_{A1}$  terminations of the (111) surface and they found  $\text{Fe}_{B1}$  to be the more stable of the two, which they validated through comparison with experimental STM images (Martin *et al.*, 2009). Berdunov *et al.* (2004b) used DFT to study the dipolar

non-stoichiometric bulk-like O<sub>2</sub> termination of the (111) surface which was also validated via comparison with experimental STM images (Berdunov *et al.*, 2004b). Kiejna *et al.* (2012) studied the non-stoichiometric bulk-like dipolar terminations of the (111) surface using DFT + *U*, and although they did not calculate the stoichiometric slab, they predicted the Fe<sub>A1</sub> termination as the most stable for the whole range of chemical potential they considered (Kiejna *et al.*, 2012). Reduced surfaces of the Fe<sub>3</sub>O<sub>4</sub>(111) surface show superstructures with Fe<sub>1-x</sub>O(111) islands (Condon *et al.*, 1997), which makes the surface even richer in possible terminations.

Following the seminal work by Tasker (1979) on the surface properties of ionic solids, in this chapter we have used DFT + *U* to investigate the non-dipolar stoichiometric terminations of the low Miller index surfaces of Fe<sub>3</sub>O<sub>4</sub>, in order to complement previous experimental and computational studies. We report the equilibrium morphology of the crystals enclosed by stoichiometric non-dipolar surfaces and the factors that govern the redox properties of the most common surfaces, (001) and (111), which are also the most prominent surfaces of Fe<sub>3</sub>O<sub>4</sub> moieties (Gaines *et al.*, 1997; Kostov, 1968). We have also calculated the STM images of the different stoichiometric non-dipolar terminations of these surfaces to determine the most likely to appear in nanocrystals through comparisons with available experimental STM data. We have studied the redox processes by the systematic formation of single O vacancies and the adsorption of single O on the surface, as opposed to previous computational studies which have focused on bulk-like terminations and their modifications. This approach allows us to explore how these redox processes determine the surface

properties by finely tuning the conditions of temperature and oxygen partial pressure on the stoichiometric non-dipolar surfaces. The results presented in this chapter have been published (Santos-Carballal *et al.*, 2014).

## **5.2 Computational methods**

### **5.2.1 Calculation details**

We have used the Vienna *Ab-initio* Simulation Package (VASP) (Kresse and Furthmüller, 1996a, 1996b; Kresse and Hafner, 1994, 1993) to carry out quantum mechanical calculations within the usual Kohn-Sham (KS) implementation of DFT. The Perdew-Burke-Ernzerhof (PBE) (Perdew *et al.*, 1997, 1996a) version of the generalized gradient approximation (GGA) was employed as the exchange-correlation potential, together with the semiempirical method D2 of Grimme (2006) to model the long-range dispersion interactions. The core electrons, up to and including the  $3p$  levels of Fe and the  $1s$  of O, were frozen and their interaction with the valence electrons was described by the projector augmented wave (PAW) method (Blöchl, 1994; Kresse and Joubert, 1999). KS valence states were expanded in a plane-wave basis set with a cutoff of 400 eV for the kinetic energy. An energy threshold-defining self-consistency of the electron density was set to  $10^{-5}$  eV and the optimization of the structures was conducted via a conjugate gradients technique, which stops when the Hellmann-Feynman forces on all atoms are less than  $0.01 \text{ eV} \cdot \text{Å}^{-1}$ .

All calculations were spin-polarised, but spin-orbit coupling was not considered. Within the VASP code, it is possible to assign an initial spin population and orientation to each atom of the system, to converge to a particular spin configuration. Thus, the initial magnetic moments were set following a high-spin ferrimagnetic structure, *i.e.* with opposite spins in the tetrahedral and octahedral sites, in agreement with experiment (Néel, 1948; Shull *et al.*, 1951). In order to describe the electronic and magnetic behaviour properly, an accurate treatment of the electron correlation in the localized *d*-Fe orbitals is crucial. Hence, we have used the Dudarev *et al.* (1998) approach within the DFT + *U* (Anisimov *et al.*, 1992) for improving the description of these localized states. This is a correction typically used where standard LDA and GGA functionals fail to describe the electronic structure properly (Moreira *et al.*, 2002). The value for the on-site Coulomb interaction term in this study was  $U_{\text{eff}} = 3.7$  eV, which was obtained following the procedure described in Chapter 4 but adjusted to a different DFT functional. The limitation of this approximation is the difficulty in choosing an adequate value for the  $U_{\text{eff}}$  parameter, which is usually property dependent (Grau-Crespo *et al.*, 2006a; Loschen *et al.*, 2007; Wang *et al.*, 2006). An alternative computational approach is the use of hybrid functionals, although in that case the calculated properties also depend on the fraction of the exact Hartree-Fock exchange that is added to the DFT exchange term (Ciofini *et al.*, 2004; Corà, 2005; Illas and Martin, 1998; Moreira *et al.*, 2002; Muñoz *et al.*, 2004), and the calculations are too computationally expensive to be applied to the large surface models employed in this study.



Bulk calculations were performed using the rhombohedral primitive unit cell containing 14 atoms ( $\text{Fe}_6\text{O}_8$ ). Integrations in the reciprocal space were performed using a Monkhorst-Pack grid of  $7 \times 7 \times 7$   $\Gamma$ -centred  $k$ -points (Baldereschi, 1973; Chadi and Cohen, 1973; Monkhorst and Pack, 1976), which ensured electronic and ionic convergence. Test calculations with a higher number of  $k$ -points led to an energy difference smaller than 1 meV per cell.  $k$ -point grids for the surface calculations were chosen in such a way that a similar spacing of points in the reciprocal space was maintained.

Within this setup, we calculated a lattice constant for the bulk  $\text{Fe}_3\text{O}_4$  unit cell of  $a = 8.398 \text{ \AA}$ , in excellent agreement with the experimental value of  $8.390 \text{ \AA}$  (Wright *et al.*, 2002), and an equilibrium volume of  $V = 74.043 \text{ \AA}^3$  per formula unit. The calculated total spin magnetization per formula unit,  $M_s = 4.00 \mu_B$  lies very close to the  $4.05 \mu_B$ , measured experimentally at 4.2 K (Kakol and Honig, 1989), and the atomic spin moments,  $m_s(\text{Fe}_A) = -4.03 \mu_B$ ,  $m_s(\text{Fe}_B) = 3.91 \mu_B$  and  $m_s(\text{O}) = 0.06 \mu_B$  have the ferromagnetic orientation observed before (Roldan *et al.*, 2013; Shull *et al.*, 1951), following very closely the Néel model (Néel, 1948), where the electronic configurations are  $e_{\uparrow}^2 t_{2\uparrow}^3$  for  $\text{Fe}_A$  and  $t_{2g\uparrow}^3 t_{2g\downarrow}^1 e_{g\uparrow}^2$  as well as  $t_{2g\uparrow}^3 e_{g\uparrow}^2$  for  $\text{Fe}_B$ . Calculated charges for  $\text{Fe}_A$ ,  $\text{Fe}_B$  and O atoms are 1.59, 1.52 and  $-1.16 e^-$  respectively.

## 5.2.2 Surface models

In order to build slab models of the  $\text{Fe}_3\text{O}_4$  surfaces, two models are used in the literature to explain the reconstructions found in polar surface terminations: the

electron-counting (Pashley, 1989) and the dipole method (Tasker, 1979). Both models are based on the condition that the net surface charge or dipole perpendicular to the surface, respectively, must be zero.

A surface structure satisfies the model of electron-counting (*i.e.*, it is charge- or auto-compensated) if all the partially filled dangling bonds in the cations are empty and the partially filled dangling bonds in the anions are full. It assumes that the atomic orbitals are in the conduction or valence band respectively. To achieve this, the model postulates that a stable surface structure will be the one that (after reconstruction) is able to accommodate exactly all the electrons of the partially filled orbitals of the cations (in the conduction band) into the partially filled orbitals of the anions (valence band). However, the disadvantage of this approach is that this condition directly links to the conducting properties of the material under investigation. If the surface satisfies this model, it will be a semi-conductor; otherwise the remnant electrons will lead to a metallic surface.

The dipole method for reconstructing dipolar surfaces is a more robust option, at least with half-metallic materials like  $\text{Fe}_3\text{O}_4$  (Roldan *et al.*, 2013), because it is not connected to the conducting properties of the structure. This method, pioneered by Tasker (1979), considers the crystal as a stack of planes, where three possibilities can arise. In type 1, each plane has overall zero charge because it is composed of anions and cations in stoichiometric ratio which makes it non-dipolar, whereas in type 2 the stacking of three symmetrically charged planes cancels out the dipole moment perpendicular to the surface. In type 1 and 2, no reconstruction of the surface is needed

because the repeat unit is non-dipolar perpendicular to the surface. However, in type 3 surfaces, alternating charged planes stack in a sequence that produces a dipole moment perpendicular to the surface, but the surface can be reconstructed through moving half of the ions with the same charge from the top to the bottom of the slab. This method also guarantees that the surface does not generate an electrical field within the crystal and therefore the potential felt at each ion site reaches the constant bulk value, a condition that is not necessarily satisfied by the electron-counting model.

All the surfaces in this study were created by cutting the geometry optimised bulk using the dipole method implemented in METADISE (Watson *et al.*, 1996). The resulting slabs are represented by keeping fixed the bottom atoms at their *ab-initio* relaxed bulk positions to simulate the bulk phase of Fe<sub>3</sub>O<sub>4</sub> and by relaxing the rest of the slab during the optimization, giving a single relaxed surface. The slabs comprise 56 atoms (8 formula units), with 24 Fe and 32 O atoms. The Fe<sub>3</sub>O<sub>4</sub> (001), (011) and (111) surfaces were modelled with slabs having surface areas of 70.5, 99.7 and 61.1 Å<sup>2</sup>, respectively, and they were constructed of 9, 5 and 13 atomic layers, respectively.

**Figures 5.2, 5.3 and 5.4 (c)** provide a representation of their stacking sequence in each direction. For the (001) and (111) surfaces, the simulation slabs were symmetrical along the *z* axis. Top species in the (001) surface were (0.5 ML) Fe<sub>A</sub> atom and 2 Fe<sub>B</sub> and 4 O atoms (equivalent to 0.5 ML for each of the ions) for terminations A and B respectively, see **Figure 5.2**. For the (111) surface, terminations A and B were terminated by half of the (Fe<sub>B</sub>)<sub>6</sub> and (Fe<sub>B</sub>)<sub>2</sub> bulk layers respectively. However, the simulation slabs for the (011) surface were asymmetrical along the *z* axis, with

complementary top and bottom layers. Top layer of termination A was a single (0.25 ML) Fe<sub>A</sub> atom above a bulk-like O-Fe<sub>B</sub> layer, while its bottom layer was a bulk-like Fe<sub>A</sub>-Fe<sub>B</sub>-O layer with one (0.25 ML) Fe<sub>A</sub> vacancy. For termination B, top and bottom layers were the other way round.

In every simulation cell, a vacuum region of 12 Å was added perpendicular to the surface to avoid interaction between the periodic slabs. Different slab and vacuum thicknesses as well as numbers of relaxed layers were tested until convergence within 1 meV per cell was achieved. Since we are going to remove and add O atoms to the surfaces at one side of the slab only, we applied dipole corrections perpendicular to all surfaces in the calculations to enhance the electronic convergence (Makov and Payne, 1995; Neugebauer and Scheffler, 1992). We have used Bader analysis (Bader, 1990) in the implementation of Henkelman and co-workers (Henkelman *et al.*, 2006; Sanville *et al.*, 2007; Tang *et al.*, 2009) to analyse the charge transfer around the defects introduced in the stoichiometric surfaces. We have chosen this methodology for partitioning atomic charges, as it is based upon the charge density, which is insensitive to the metal oxidation state and the basis set used, unlike wavefunction-based population schemes (Ángyán *et al.*, 1994; De Proft *et al.*, 2002; Wiberg and Rablen, 1993).

### 5.2.3 Calculation of surface energies

We have carried out energy minimisations of the (001), (011) and (111) slabs to obtain their surface energies. We derived the surface energy of the unrelaxed surface ( $\gamma_u$ )

from a single point calculation of the pristine symmetric stoichiometric slab before relaxation, via equation:

$$\gamma_u = \frac{E_{\text{slab,u}} - E_{\text{bulk}}}{2A} \quad (5.1)$$

where  $E_{\text{slab,u}}$  is the total energy of the unrelaxed slab,  $E_{\text{bulk}}$  is the energy of the bulk containing the same number of formula units as in the slab and  $A$  is the surface area of one side of the slab. During relaxation, the top surface was allowed to relax and the bottom one was kept fixed. As this slab model does not provide an isolated relaxed surface and both sides of the symmetric stoichiometric slabs are considered in the calculation of the energy, their surface energies ( $\gamma_r$ ) and ( $\gamma_u$ ), for the relaxed and unrelaxed sides respectively, are related by equation (5.2), where  $E_{\text{slab,r}}$  is the slab total energy after relaxation.

$$\gamma_r + \gamma_u = \frac{E_{\text{slab,r}} - E_{\text{bulk}}}{A} \quad (5.2)$$

At this point it is also worth noting that equations (5.1) and (5.2) are only useful for calculating the average surface energy of terminations A and B of (011), as the slabs are asymmetric and complementary. The cleavage energy ( $E_{\text{cleav}} = 2 \cdot \gamma_r$ ) is thus related to the energy required to create both top and bottom surfaces of the slab.

We have also calculated the degree of relaxation of each surface as a percentage (for (011)  $\gamma_r \sim E_{\text{cleav}}/2$ ):

$$\text{Relaxation} = \frac{\gamma_u - \gamma_r}{\gamma_u} \cdot 100 \quad (5.3)$$

The equilibrium morphology of a Fe<sub>3</sub>O<sub>4</sub> crystal is determined by the surface free energies and the related growth rates of the various surfaces, which provides a measure of the relative stabilities of the surfaces. The morphology is constructed according to Wulff's theorem (Wulff, 1901), where the distance from the centre of the particle to the surface is proportional to the surface energy. It is based on the Gibbs approach (Gibbs, 1928), who proposed that under thermodynamic control the equilibrium form of a crystal should possess minimal total surface free energy for a given volume. Previous studies have shown (Cooper and de Leeuw, 2006; de Leeuw and Cooper, 2007) that using surface energies to calculate crystal morphologies provides good agreement with experiment as the difference in entropy between bulk and surface is small.

#### 5.2.4 Redox processes of the (001) and (111) surfaces

We have also examined the redox properties of the most common Fe<sub>3</sub>O<sub>4</sub> surfaces, the (001) and (111), by removing or adding O atoms to form non-stoichiometric compositions of the top atomic layer. We have based the discussion of the stabilities of the non-stoichiometric terminations on the *ab-initio* thermodynamics formalism (Wang *et al.*, 1998) where the surface free energy ( $\sigma$ ) is calculated according to the equation:

$$\begin{aligned}\sigma(T, p) &= \gamma_r + \Delta\sigma(T, p) \\ \Delta\sigma(T, p) &= \frac{E_{\text{slab},r}^{\Gamma_{\text{O}} \neq 0} - E_{\text{slab},r}^{\Gamma_{\text{O}} = 0}}{A} - \frac{\Gamma_{\text{O}}}{A} \cdot \mu_{\text{O}}\end{aligned}\quad (5.4)$$

where  $\Delta\sigma(T, p)$  is the difference between the surface energy of the stoichiometric surface and the surface free energy of the non-stoichiometric plane and  $\Gamma_{\text{O}}$  is the excess of O ions at the top surface of the slab expressed in equation (5.5) ( $N_{\text{O}}$  and  $N_{\text{Fe}}$  are the number of O and Fe ions in the slab model respectively).

$$\Gamma_{\text{O}} = N_{\text{O}} - \frac{4}{3}N_{\text{Fe}} \quad (5.5)$$

It is possible to express the chemical potential of molecular  $\text{O}_2$  ( $\mu_{\text{O}}$ ) in the gas phase as:

$$\mu_{\text{O}}(T, p) = \frac{1}{2} \left( E_{\text{O}_2} + \Delta g_{\text{O}_2}(T, p_0) + k_{\text{B}}T \ln \frac{p}{p_0} \right) \quad (5.6)$$

Here the first term within the bracket is the DFT energy of the  $\text{O}_2$  molecule. The second term is the difference in the Gibbs free energy per  $\text{O}_2$  molecule at  $p_0 = 1$  bar between 0 K and  $T$ , which in this study has been extracted from thermodynamic tables (Chase, 1998) to avoid its calculation in the gas phase (Grau-Crespo *et al.*, 2007; Reuter and Scheffler, 2001). The last term represents the change in free energy of the  $\text{O}_2$  gas (assuming ideal gas behaviour) at constant temperature ( $T$ ) when its partial pressure changes from  $p_0$  to  $p$ .

We express  $\mu_{\text{O}}$  with respect to half the energy of the  $\text{O}_2$  molecule. The above convention makes  $\mu_{\text{O}}$  a function of only experimental quantities. For consistency in the evaluation of the slab energies, we must subtract half of the energy of the  $\text{O}_2$  molecule for each O atom in the slab. Expressing  $\mu_{\text{O}}$  as described, it is possible to plot the surface free energies given by equation (5.4) for different surface compositions as a function of  $\mu_{\text{O}}$ , and discuss the redox behaviour of the surface (Grau-Crespo *et al.*, 2007; Reuter and Scheffler, 2001).

Finally, for the calculation of the energy required to create an O atom vacancy or to add the atom on the surfaces, we need the energy of the  $\text{O}_2$  molecule. However, it is known that GGA calculations fail in the description of the binding energy for this particular molecule, as is shown in the (over)binding of the  $\text{O}_2$  molecule (Perdew *et al.*, 1996a).

According to our calculations, the  $\text{O}_2$  triplet ground state has an equilibrium bond length of 1.23 Å and a binding energy of  $-6.08$  eV (with respect to triplet oxygen atoms), comparing well with previous computational studies (Grau-Crespo *et al.*, 2006b; Mellan and Grau-Crespo, 2012; Wang *et al.*, 2006). However, this value lies 0.91 eV below the experimental binding energy ( $-5.17$  eV) (Haynes, 2012). Therefore, we have considered that half of the over-binding of the  $\text{O}_2$  molecule, 0.46 eV, will be added to correct the adsorption or vacancy formation energies with respect to one O atom. The redox processes in the following sections are all reported with respect to the corrected value.



### 5.2.5 Calculation of scanning tunnelling microscopy (STM) images

The STM images were simulated according to the basic formulation of the Tersoff-Hamann approach (Tersoff and Hamann, 1985) where the STM tip was approximated to an infinitely small point source. The tunnelling current between the surface and the tip in the STM experiments is proportional to the local density of the states (LDOS) integrated between the Fermi energy and the sample bias. We have used the program HIVE (Vanpoucke and Brocks, 2008) for the production of our STM topographic images, where the DFT-based partial charge density was integrated from  $-2.5$  eV to the Fermi energy. In the constant current mode, the tip of the STM is moved across the surface where its height varies to keep the charge density at a constant value, which is given by a constant LDOS. We map the simulated STM images by means of the heights as a function of the position of the tip over the surface. More details about the method can be found elsewhere (Irrera *et al.*, 2013).

## 5.3 Stoichiometric surfaces

We have modelled different terminations of the three lowest Miller index surfaces of  $\text{Fe}_3\text{O}_4$ , shown in **Figures 5.2, 5.3 and 5.4**, whereas **Table 5.1** summarises their surface energies before and after energy minimization. Before relaxation, the order of increasing surface energies, and therefore decreasing stability, is  $(001) < (111) < (011)$ , which remains the same after relaxation. Note that this order was established by taking into account only the most stable termination (with lowest  $\gamma$ ) per surface, as these terminations would be the most likely to appear for each plane.

**Table 5.1.** Calculated surface energies before ( $\gamma_u$ ) and after ( $\gamma_r$ ) relaxation for the different terminations of the three lowest Miller index surfaces of  $\text{Fe}_3\text{O}_4$ .

Surface	$\gamma_u$ ( $\text{J} \cdot \text{m}^{-2}$ )	$\gamma_r$ ( $\text{J} \cdot \text{m}^{-2}$ )	Relaxation (%)
(001) termination A	1.45	0.96	34.2
(001) termination B	3.28	2.17	33.9
(011) terminations A and B*	2.13	1.37	35.5
(111) termination A	2.75	1.09	60.3
(111) termination B	1.58	1.10	30.4

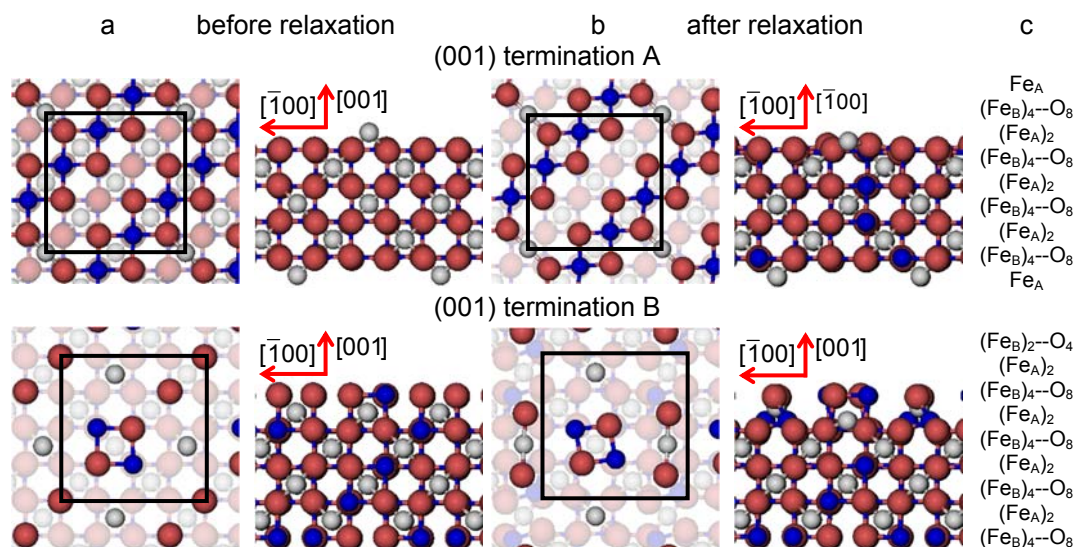
\* Note that for the (011) surface it is only possible to report the average surface energy, as terminations A and B are complementary.

Before geometry optimisation, termination A of the (001) slab was terminated by 0.5 ML of 2-coordinated  $\text{Fe}_A$  ions occupying a bridge site (above two O ions) with a  $(\sqrt{2} \times \sqrt{2})R45^\circ$  symmetry according to Wood's notation (Wood, 1964), which is a vectorial description of the surface structure. Beneath the surface, the slab shows a bulk structure consisting of single rows in the [110] direction of 5-coordinated  $\text{Fe}_B$  ions alternating every two single rows of O ions with cubic packing, see **Figure 5.2**. During energy minimization, the protruding  $\text{Fe}_A$  ions move 0.53 Å towards the bulk, *i.e.* they experienced ~50 % inward relaxation based on ~1.05 Å as the layer interspacing, thereby becoming closer to the nearest two O (0.25 ML of the 2<sup>nd</sup> layer), which displace 0.35 Å to the surface to accommodate this relaxation, see **Table 5.2**. The relaxation pattern of the top atomic layer of the surface slab agrees semi-quantitatively with the ~40 % inward relaxation reported for the topmost layer of this

termination based on LEIS analysis (Mijiritskii and Boerma, 2001), which is generally regarded to fit better than the more complex relaxation pattern reported before for this surface termination by Chambers *et al.* (2000). Previous studies, purely theoretical (Rustad *et al.*, 1999) or combined with experiments (Spiridis *et al.*, 2006), have concluded that the  $\text{Fe}_3\text{O}_4(001)$  surface terminates with Fe ion dimers with  $(\sqrt{2} \times \sqrt{2})R45^\circ$  symmetry. The second Fe may migrate from a sub-surface layer (Rustad *et al.*, 1999) or from a dipolar bulk-like  $\text{Fe}_A$  terminated (001) surface (Spiridis *et al.*, 2006). However, we have not included dimers here as this lies outside the scope of the present study. The surface energy of termination B of the (001) surface is also reported in **Table 5.1**, but we do not consider this plane for further analysis because of its high surface energy, which makes it very unlikely to appear in the  $\text{Fe}_3\text{O}_4$  crystal morphology.

**Table 5.2.** Perpendicular movement ( $\Delta d_z$ ) of the  $\text{Fe}_3\text{O}_4$  surface species on the most stable (001) termination after relaxation. Note that a negative value indicates a movement towards the bulk. Distances are given in Å.

(001) termination A		
layer	Species	$\Delta d_z$
1 <sup>st</sup>	$\text{Fe}_A$	-0.53
	O 0.50 ML	0.02
2 <sup>nd</sup>	$\text{Fe}_B$	-0.05
	0.25 ML	0.35
	O 0.25 ML	-0.08
3 <sup>rd</sup>	$\text{Fe}_A$	0.11
	O	-0.03
4 <sup>th</sup>	$\text{Fe}_B$	0.03
	O	0.05
5 <sup>th</sup>	$\text{Fe}_A$	-0.01
Bulk		



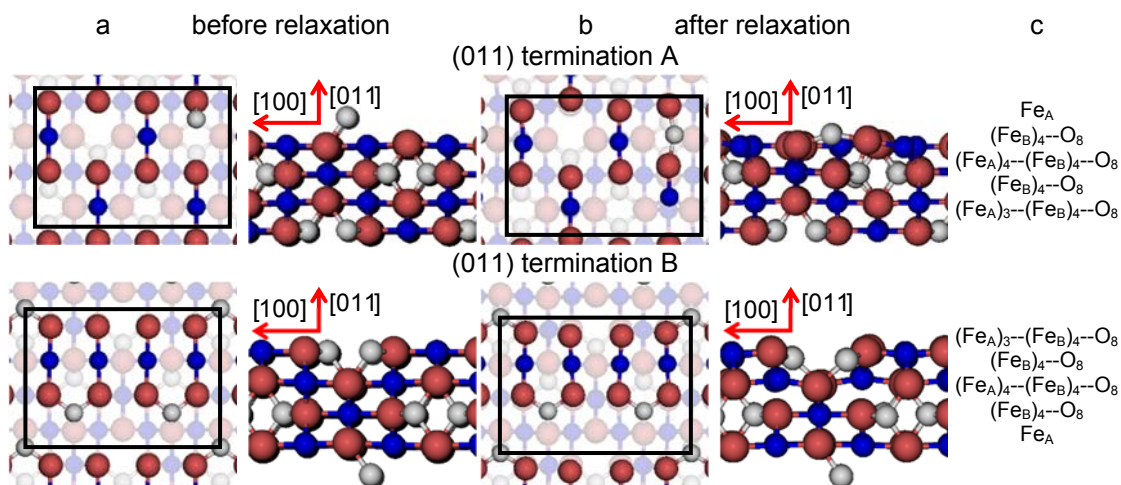
**Figure 5.2.** Top and side view of the simulation slabs for terminations A and B of  $\text{Fe}_3\text{O}_4(001)$  surface. The surfaces are shown (column a) before, (column b) after relaxation and (column c) their stacking sequence. For the colour code see **Figure 5.1**. Layers with atoms with dangling bonds are highlighted. The crystallographic direction for the top view of (001) surface terminations is  $[100]$  for the abscissae towards the right.

The stacking sequence of the  $\text{Fe}_3\text{O}_4(011)$  surface is shown in **Figure 5.3** and the vertical shifts of the ions towards the vacuum after energy minimization are listed in **Table 5.3**. One of the two lowest energy surface terminations, termination A, terminates with 0.25 ML of mono-coordinated  $\text{Fe}_A$  at the surface, followed by a bulk-like structure consisting of single rows of 4-coordinated  $\text{Fe}_B$  ions shifted 25% in the  $[01\bar{1}]$  direction and alternating with single rows of O ions with cubic packing. During energy minimisation, the protruding  $\text{Fe}_A$  ions move  $0.98 \text{ \AA}$  towards the bulk, thereby compressing the surface layer atoms underneath which move horizontally to accommodate this relaxation. Termination B has essentially the same relaxed surface

energy as termination A but it differs in its structure. It is terminated with a bulk-like structure consisting of a single row of 4-coordinated Fe<sub>B</sub> ions between two rows of O ions. The latter O atoms are in cubic packing and alternate with double rows of 3-coordinated Fe<sub>A</sub> ions in rhombohedral packing along the  $[01\bar{1}]$  direction. The double row of Fe<sub>A</sub> ions is partially vacant by 0.25 ML with  $p(1 \times 2)$  symmetry. During energy minimization, the top Fe<sub>A</sub> and Fe<sub>B</sub> ions shift towards the bulk by 0.27 Å and 0.11 Å respectively which generates a 0.23 Å movement towards the surface of the Fe<sub>B</sub> ions in the sub-surface layer. Based on the similarity between the relaxed structure of termination B, differing only by 0.25 ML Fe<sub>A</sub> vacancy from the bulk-like Fe<sub>A</sub>-Fe<sub>B</sub>-O termination proposed in ref 34, we can still compare some structural characteristics between them. The calculated Fe<sub>B</sub>-Fe<sub>B</sub> or O-O distance of the atoms lying in the same row along the  $[01\bar{1}]$  direction is 2.77 Å in termination B, which agrees well with their reported  $3.0 \pm 0.3$  Å (G. Maris *et al.*, 2006). Moreover, along the [001] direction, the calculated Fe<sub>B</sub>-O distance of 1.92 Å also compares well with  $2.1 \pm 0.3$  Å from STM experiments (G. Maris *et al.*, 2006).

**Table 5.3.** Perpendicular movement ( $\Delta d_z$ ) of the  $\text{Fe}_3\text{O}_4$  surface species on the most stable (011) terminations after relaxation. Note that a negative value indicates a movement towards the bulk. Distances are given in Å.

(011) termination A			(011) termination B		
layer	Species	$\Delta d_z$	layer	Species	$\Delta d_z$
1 <sup>st</sup>	Fe <sub>A</sub>	-0.98	Fe <sub>A</sub>		-0.27
	O	-0.02	1 <sup>st</sup>	Fe <sub>B</sub>	-0.11
2 <sup>nd</sup>	Fe <sub>B</sub>	-0.11	O		0.08
	O	-0.03	O		-0.06
	Fe <sub>A</sub>	-0.04	2 <sup>nd</sup>	Fe <sub>B</sub>	0.23
3 <sup>rd</sup>	Fe <sub>B</sub>	0.06	O		-0.04
	O	0.01	Fe <sub>A</sub>		0.02
			3 <sup>rd</sup>	Fe <sub>B</sub>	0.00
	Bulk		O		0.00
			Bulk		



**Figure 5.3.** Top and side view of the simulation slabs for terminations A and B of  $\text{Fe}_3\text{O}_4(011)$  surface. The surfaces are shown (column a) before, (column b) after relaxation and (column c) their stacking sequence. For the colour code see **Figure 5.1**. Layers with atoms with dangling bonds are highlighted. The crystallographic direction for the top view of (011) surface terminations is  $[0\bar{1}1]$  for the abscissae towards the right.

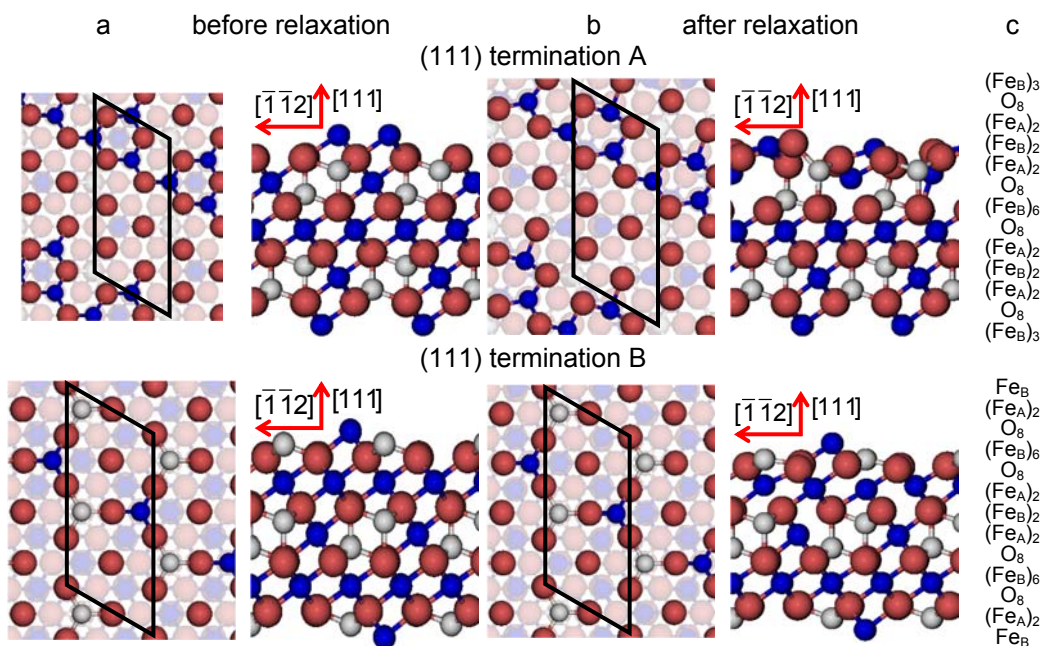
Finally, the bottom two panels of **Figure 5.4** represent the stacking sequence of the  $\text{Fe}_3\text{O}_4(111)$  surface terminations, while the vertical displacement of the ions in the surface regions during the optimisation are listed in **Table 5.4**. One of the two lowest energy terminations, termination A, contains 0.5 ML of 3-coordinated  $\text{Fe}_B$  ions with  $c(2 \times 4)$  symmetry, occupying hexagonal close packed (*hcp*) hollow positions in the top layer. The next layer has a bulk-like structure consisting of rows of O ions along the  $[0\bar{1}1]$  direction with rhombohedral packing. The percentage relaxation experienced by this surface termination is the largest of this study. During its geometry optimisation, the top  $\text{Fe}_B$  ions move towards the bulk by  $0.59 \text{ \AA}$ , causing 0.25 ML of the O in the layer underneath to move towards the surface by  $0.62 \text{ \AA}$ . As we can see



in **Table 5.4**, the fourth and fifth atomic layers are also affected by the surface relaxation. Termination B terminates with 0.5 ML of 3-coordinated Fe<sub>B</sub> with  $p(1 \times 2)$  symmetry, where these ions occupy hcp hollow sites, followed by a bulk-like structure consisting of rows of Fe<sub>A</sub> alternating along the  $[0\bar{1}1]$  direction with two rows of O ions with rhombohedral packing. During energy minimization, the top Fe<sub>B</sub> and Fe<sub>A</sub> ions move towards the bulk by 0.09 Å and 0.31 Å respectively. The mean Fe<sub>A</sub>-Fe<sub>B</sub> distance in the surface layer of the relaxed structure is 3.55 Å (as opposed to the calculated bulk value of 3.48 Å), which is in excellent agreement with  $3.6 \pm 0.4$  Å, the experimental distance reported between the two features (Fe<sub>A</sub> and Fe<sub>B</sub>) from an STM image (Lennie *et al.*, 1996).

**Table 5.4.** Perpendicular movement ( $\Delta d_z$ ) of the  $\text{Fe}_3\text{O}_4$  surface species on the most stable (111) terminations after relaxation. Note that a negative value indicates a movement towards the bulk. Distances are given in Å.

(111) termination A			(111) termination B		
layer	Species	$\Delta d_z$	layer	Species	$\Delta d_z$
1 <sup>st</sup>	$\text{Fe}_B$	-0.59	1 <sup>st</sup>	$\text{Fe}_B$	-0.09
2 <sup>nd</sup>	0.75 ML	-0.10	2 <sup>nd</sup>	$\text{Fe}_A$	-0.31
	0.25 ML	0.62	3 <sup>rd</sup>	O	-0.03
3 <sup>rd</sup>	$\text{Fe}_A$	0.09	4 <sup>th</sup>	$\text{Fe}_B$	0.06
4 <sup>th</sup>	$\text{Fe}_B$	0.41	5 <sup>th</sup>	O	0.03
5 <sup>th</sup>	$\text{Fe}_A$	-0.21	6 <sup>th</sup>	$\text{Fe}_A$	0.02
6 <sup>th</sup>	O	-0.08	7 <sup>th</sup>	$\text{Fe}_B$	0.03
7 <sup>th</sup>	$\text{Fe}_B$	0.00			
Bulk			Bulk		

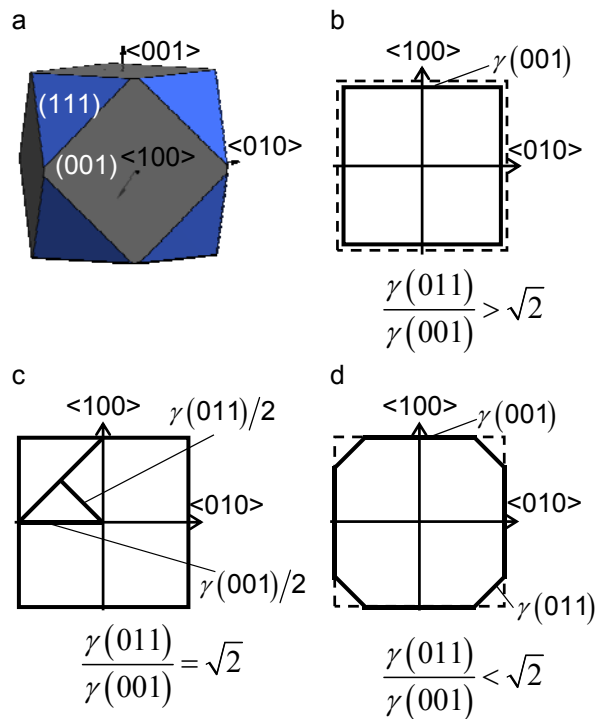


**Figure 5.4.** Top and side view of the simulation slabs for terminations A and B of  $\text{Fe}_3\text{O}_4(111)$  surface. The surfaces are shown (column a) before, (column b) after relaxation and (column c) their stacking sequence. For the colour code see **Figure 5.1**. Layers with atoms with dangling bonds are highlighted. The crystallographic direction for the top view of (111) surface terminations is  $[0\bar{1}1]$  for the longest axis towards the top.

### 5.3.1 Morphology

Since the morphology of  $\text{Fe}_3\text{O}_4$  crystals has been studied experimentally, we compare our results with those reported for synthetic  $\text{Fe}_3\text{O}_4$  crystals (Zhao *et al.*, 2008). We have derived a Wulff (1901) crystal morphology of pristine  $\text{Fe}_3\text{O}_4$  using the lowest surface energies for each Miller index. Its calculated equilibrium morphology is then expressed as a cubic shape with truncated corners, **Figure 5.5 (a)**. As expected, the (001) plane dominates the morphology, followed by the (111) surface truncating the corners of the cube. The (011) surface does not appear in the morphology of  $\text{Fe}_3\text{O}_4$

due to the mathematical relation between the energy of the surfaces and their position in the crystal (Mellan and Grau-Crespo, 2012). Despite the (011) surface having a surface energy of the same order of magnitude as the others, it is not expressed in the Wulff construction due to competition with the (001) surface. The ratio between their surface energies:  $\gamma(011)/\gamma(001) = 1.43 > \sqrt{2}$ , see **Figure 5.5 (b)**, and, as shown in **Figure 5.5 (d)**, the (011) surface would only become present in the crystal morphology if  $\gamma(011)/\gamma(001) < \sqrt{2}$ .



**Figure 5.5.** (a) Equilibrium morphology for a  $\text{Fe}_3\text{O}_4$  crystal derived from a Wulff construction. (b) – (d) Schemes of the crystal cross-sectional planes along the <100> and <010> axes for different ratios of stabilities of the lateral surfaces, which illustrate why the (011) surface is absent in the equilibrium morphology.

There are many ways to modify the shape of nanoparticles, such as solvent, media, capping agents, temperature or viscosity, but the Wulff morphology shown in **Figure 5.5 (a)** expresses a particle produced in conditions of perfect thermodynamic equilibrium, vacuum and at 0 K. Nevertheless, our results compare well with the morphologies of crystals synthesised by Zhao *et al.* (2008), who described the formation of Fe<sub>3</sub>O<sub>4</sub> under different pH conditions. They increased the OH<sup>-</sup> concentration and the resulting crystal shapes changed from cubic (or spherical – depending on other conditions-) at low pH via truncated octahedral to octahedral at high pH values. All their crystals showed mainly the (001) and (111) surfaces but, in some cases, a little (011) surface was expressed due to certain conditions which may modify the surfaces' relative energies. The occasional appearance of the (011) surface is rationalised in terms of kinetically-controlled anisotropic growth of the Fe<sub>3</sub>O<sub>4</sub> nanoparticles. Zhao *et al.* (2008) suggested that a high concentration of KOH in the solution can lead to selective adsorption of the hydroxyl anions to certain planes of the crystal, which slows down considerably their growth process. Therefore, the presence of these ions can affect the relative stabilities of the different crystal surfaces. The inversion of the nature of the inequality  $\gamma(011)/\gamma(001) > \sqrt{2}$ , which already lies close to  $\sqrt{2}$ , will cause the (011) plane to show up in the morphology.

### 5.3.2 Scanning tunnelling microscopy images simulation

From the optimised structures of the planes and terminations that are expressed in the morphology, *i.e.* termination A of (001) and terminations A and B of (111) surfaces, we have derived the topographical STM images. These images provide information

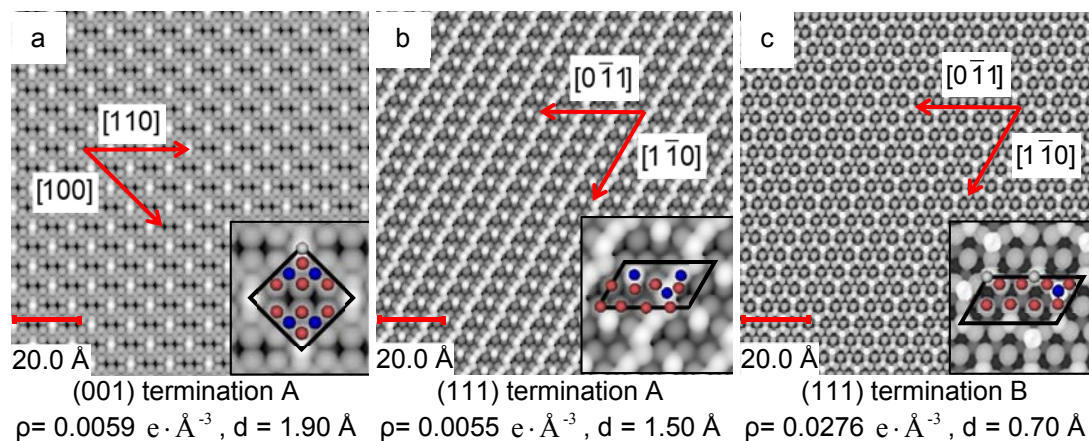
about the spatial distribution of the valence band states in the vicinity of the Fermi energy ( $E_F$ ). The above is particularly useful for systems where atoms (in our case O atoms) can be added or removed from many different positions on the surface. Modelled STM images may help to clarify experimental ones by direct comparison, for instance to identify between the two possible terminations of (111) surface, whose surface energies are very close, and also to validate the most stable termination of the (001) surface. The model also avoids any external perturbations, like the electric field of an STM experimental tip, which can influence the position of atomic species adsorbed on a surface (Irrera *et al.*, 2013).

The STM images in **Figure 5.6** are calculated on pristine  $\text{Fe}_3\text{O}_4$ (001) and (111) surfaces. **Figure 5.6 (a)** shows the STM image of the  $\text{Fe}_3\text{O}_4$ (001) surface, termination A, acquired at a distance ( $d$ ) of 1.90 Å to the tip and at a density ( $\rho$ ) of  $0.0059 \text{ e} \cdot \text{Å}^{-3}$ . This image resolves the protruding 2-coordinated  $\text{Fe}_A$  as the brightest spots with  $(\sqrt{2} \times \sqrt{2})R45^\circ$  symmetry. The O ions from the layer below are also clearly well-defined circles forming rows along the [110] direction and with cubic packing. The STM image of termination A of the (001) surface does not show the atomic positions of the  $\text{Fe}_B$  placed in the same layer as the O ions due to their low partial charges at this bias. We observed the reproduction of the  $\text{Fe}_A$  ions in the same symmetry in the STM image obtained from annealed  $\text{Fe}_3\text{O}_4$  at 623 K (Parkinson *et al.*, 2011).

The STM image of the  $\text{Fe}_3\text{O}_4$ (111) surface termination A is shown in **Figure 5.6 (b)** acquired at a density of  $0.0055 \text{ e} \cdot \text{Å}^{-3}$  and a distance of 1.50 Å to the tip. The image resolves the protruding  $\text{Fe}_B$  as the brightest spots along rows in the  $[1\bar{1}0]$  direction

and as dots in between these rows. The undulation of the rows is due to the 0.25 ML of O atoms in the 2<sup>nd</sup> layer that have moved towards the surface after minimization. From the modelled STM, we can even observe the rhombohedral packing of the sub-layer O ions.

The last STM image in **Figure 5.6 (c)** corresponds to termination B of the Fe<sub>3</sub>O<sub>4</sub>(111) surface obtained with a density of 0.0276 e·Å<sup>-3</sup> and the tip at 0.70 Å from the highest atom. The image acquired resolves the protruding Fe<sub>B</sub> as the brightest spots in the STM image with a *p*(1×2) symmetry and the Fe<sub>A</sub> ions from the layer below which are always bonded to three O atoms immediately underneath. This atomic arrangement forms a pattern of incomplete hexagons (with Fe atom vacancies in one vertex of the imaginary hexagon) which can be seen as a thermally equilibrated structure with vacancies evenly distributed. Details of the layers further below are also visible in our STM image. Experimental studies of the Fe<sub>3</sub>O<sub>4</sub>(111) surface (Lennie *et al.*, 1996) have shown that among the two different terminations considered there, the one with 0.50 ML of Fe atoms is more stable than the one with 0.75 ML of Fe atoms and 0.25 ML of O atoms, agreeing well with our model of termination B of the (111) surface, whose simulated STM is shown in **Figure 5.6 (c)**. The calculated vertical distance between the Fe<sub>A</sub> in the vertex of the hexagon and the O ion in its centre is 0.50 Å, which also agrees well with the value reported experimentally, 0.5 Å (Lennie *et al.*, 1996). This experimental termination shows regions with full hexagons and others with incomplete hexagons (due to Fe vacancies). This atomic rearrangement may be a consequence of the high temperatures to which the surface was exposed.



**Figure 5.6.** Simulated STM images of (a) termination A of (001), (b) termination A of (111) and (c) termination B of (111) surfaces obtained using a bias of  $-2.5$  eV. Density ( $\rho$ ) and tip distance ( $d$ ) are also indicated. Insets show enlargements of the STM images. In the inset,  $\text{Fe}_A$  ions are in grey,  $\text{Fe}_B$  ions are in blue and O ions are in red.

## 5.4 Redox behaviour

We have studied the redox properties of the most stable terminations, A and B, of the  $\text{Fe}_3\text{O}_4(001)$  and (111) surfaces, respectively, by comparing the surface free energies corresponding to different O to Fe ratios at the surface. We maintained the number of Fe atoms in the slab as in the stoichiometric surface, but we modified the number of O atoms in the top layer by  $\Gamma$  (given by equation (5.5)), as we were interested in studying the effect of different temperature and oxygen pressure on the stoichiometric non-dipolar surfaces. Because of the size of our supercells, and assuming that O atoms occupy bulk-like positions around the surface Fe atoms, 17 values of  $\Gamma$  are possible if we constrain the calculations to a maximum of one ML of adatoms or vacancies. However, due to the complexity of the (001) and (111) surfaces and in order to reduce



the number of  $\Gamma$  to small values that reflect realistic  $\mu_{\text{O}}$ , we have used only five values of  $\Gamma$ :  $\Gamma = 0$  is the stoichiometric surface,  $\Gamma = +1, +2$  are the partially oxidized surfaces, and  $\Gamma = -1, -2$  are the partially reduced surfaces. We have represented all of them schematically in **Figures 5.7** and **5.8**.

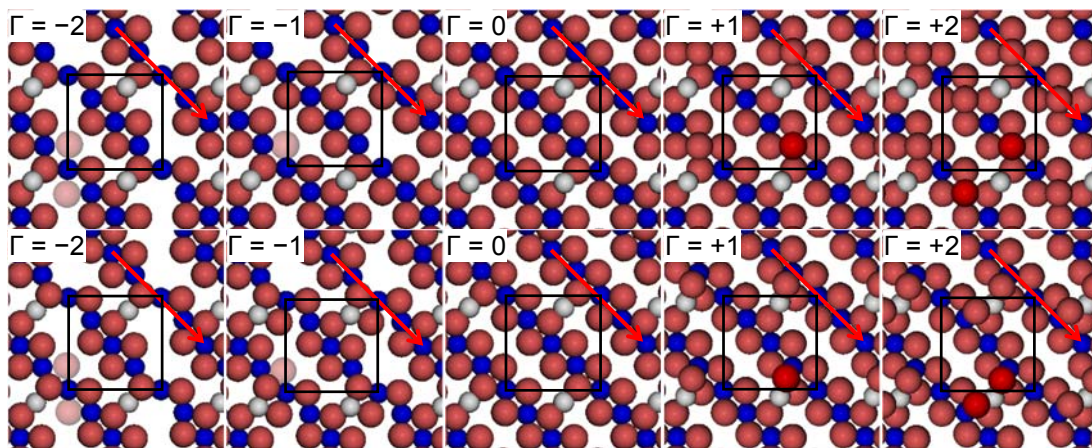
#### 5.4.1 Reduction of the (001) surface

We discuss the first reduction process  $\Gamma = -1$  by removing one O atom at the top surface of the slab, which leads to a 0.125 ML of O vacancies, with a vacancy formation energy ( $E_{\text{vac}}$ ) calculated as

$$E_{\text{vac}} = \frac{E_{\text{O}_2}}{2} + E_{\text{slab,r}}^{\Gamma=i-1} - E_{\text{slab,r}}^{\Gamma=i} \quad (5.7)$$

where  $i$  takes values 0 and  $-1$  in the first and second reduction respectively. At the surface there are three different types of O depending on the distance to the protruding 2-coordinated  $\text{Fe}_A$  ion, see **Figure 5.7**. Thus, the energy required to remove the first O from the surface is 2.60 eV for the atom furthest removed from this  $\text{Fe}_A$  (see **Figure 5.7** for  $\Gamma = -1$ ) and 3.28 eV for the one at intermediate distance. The vacancy created at the third type of O position has an even bigger energy and is therefore very unlikely. The comparison of these energies with the vacancy formation energy in the  $\text{Fe}_3\text{O}_4$  bulk (2.12 eV), suggests that under thermodynamic equilibrium any surface vacancies will migrate towards the bulk, a phenomenon that has also been observed to occur in another transition metal oxide  $\text{VO}_2$  (Mellan and Grau-Crespo, 2012). The tendency of the vacancy to migrate towards the bulk might seem contradictory with the fact that surface oxygen has a lower coordination number than bulk oxygen. However, this can

be rationalized in terms of the oxygen vacancy-containing bulk material undergoing a different degree of relaxation than the oxygen vacancy in the surface slab, thereby driving the creation of the oxygen vacancy in the bulk.



**Figure 5.7.** Top view of the schematic representation of the  $\text{Fe}_3\text{O}_4(001)$  surface before (top panels) and after relaxation (bottom panels) with different  $\Gamma$ . Stoichiometric ( $\Gamma = 0$ ); partially reduced ( $\Gamma = -1, -2$ ) and partially oxidized ( $\Gamma = +1, +2$ ).  $\text{Fe}_A$  ions are in grey,  $\text{Fe}_B$  ions are in blue and O ions are in red, removed O ions are in pale red and added O atoms are in dark red. Only the closest defects are highlighted indicating their relative position, while all of them are shown. The arrows indicate the  $[110]$  direction. Black lines indicate the surface unit cell.

We proceed with the second reduction of  $\text{Fe}_3\text{O}_4(001)$  leading to  $\Gamma = -2$ . We removed an O located in the pristine row along the  $[110]$  direction, see **Figure 5.7** for  $\Gamma = -2$ , which is at intermediate distance to  $\text{Fe}_A$ . This second vacancy is 3.23 eV less favourable than the previous state but it is just more likely than removing a more distant O ion from the row where the vacancy is now being created, 3.31 eV. This indicates that although the first vacancy is created preferentially in a position far away

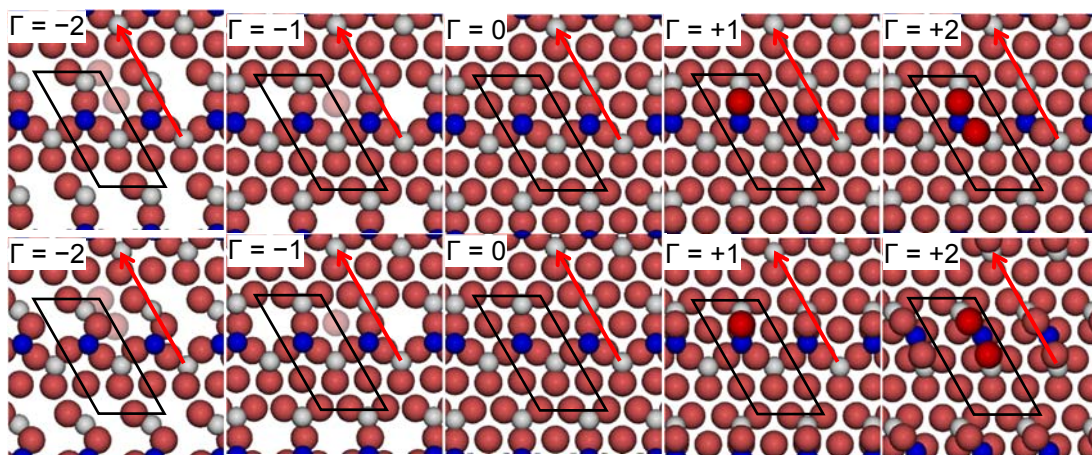
from the 2-coordinated  $\text{Fe}_A$ , the second reduction might lead to a vacancy in the following O row at an intermediate distance from  $\text{Fe}_A$ . As the energies to create the second vacancy in the two positions already described are within the DFT error, it might also be possible to find vacancies in the O positions further away from the row where the vacancy is now being created.

We have characterised the  $\Gamma = -1$  surface by means of a Bader analysis and compared the atomic charges with those on the pristine surface. The positive charge of the protruding  $\text{Fe}_A$  ion was increased by a negligible amount ( $< 0.05 e^-$ ), where this small variation can be accounted for by the defect that was created at the farthest O location. The surface  $\text{Fe}_B$  ions, however, are reduced, especially the ones closest to the vacancy with a variation in charge of  $0.25 - 0.37 e^-$ . This can be interpreted in terms of the number of O ions directly coordinated to the  $\text{Fe}_B$  ions, see **Figure 5.7** for  $\Gamma = -1$ , where just over 80 % of the electron density is transferred to the  $\text{Fe}_B$  ions after removing the O atoms.

#### 5.4.2 Reduction of the (111) surface

We have also explored different positions for the creation of the O ( $\Gamma = -1$ ) vacancies in the  $\text{Fe}_3\text{O}_4(111)$  surface to find the lowest-energy configuration for this particular surface. We found that the process is thermodynamically even more unfavourable than on the (001) surface by 0.24 eV. The most likely vacancy is created in the centre of an incomplete Fe-hexagon, see **Figure 5.8** for  $\Gamma = -1$ . To remove an O atom coordinated to the 3-coordinated  $\text{Fe}_A$  (opposite to the missing Fe in the incomplete hexagon)

requires an energy of 3.56 eV. As in the (001) surface, any vacancy created in the (111) surface will be thermodynamically prone to migrate towards the bulk.



**Figure 5.8.** Top view of the schematic representation of the  $\text{Fe}_3\text{O}_4(111)$  surface before (top panels) and after relaxation (bottom panels) with different  $\Gamma$ . Stoichiometric ( $\Gamma = 0$ ); partially reduced ( $\Gamma = -1, -2$ ) and partially oxidized ( $\Gamma = +1, +2$ ).  $\text{Fe}_A$  ions are in grey,  $\text{Fe}_B$  ions are in blue and O ions are in red, removed O ions are in pale red and added O atoms are in dark red. Only the closest defects are highlighted indicating their relative position, while all of them are shown. The arrows indicate the  $[0 \bar{1} 1]$  direction. Black lines indicate the surface unit cell.

Creating a second vacancy among the atoms coordinated to the 3-coordinated  $\text{Fe}_A$ , **Figure 5.8** for  $\Gamma = -2$  costs 3.45 eV, which is less costly by 0.19 eV than removing the left O within the hexagon. These energies provide information about the consecutive reduction mechanism, where the first O vacancy is created in the centre of the incomplete Fe-hexagons and the next in one of the atom positions coordinated to the 3-coordinated  $\text{Fe}_A$ .

The Bader analysis indicates that upon vacancy formation on the  $\Gamma = -1$  surface, charge transfer on the  $\text{Fe}_A$  is negligible and the protruding 3-coordinated  $\text{Fe}_B$  is only slightly reduced. However, the  $\text{Fe}_B$  ions whose charge is affected more are those in the 4<sup>th</sup> atomic layer (see **Figure 5.4**) below the removed O atom to which they were previously directly coordinated. Altogether, the charge on those three  $\text{Fe}_B$  is reduced by  $\sim 0.89 e^-$ , *i.e.* they have accepted 78.5 % of the electron density previously held by the removed O.

#### 5.4.3 Oxidation of the (001) surface

Another process we have studied is the surface oxidation by adsorption of one O atom leading to 0.125 ML of adatoms ( $\Gamma = +1$ ). This process involves an adsorption energy per adatom derived from the equation,

$$E_{\text{ads}} = E_{\text{slab}}^{\Gamma=j+1} - E_{\text{slab}}^{\Gamma=j} - \frac{E[\text{O}_2]}{2} \quad (5.8)$$

(where  $j$  takes values 0 and +1 in the first and second oxidation respectively). For  $j = 0$ ,  $E_{\text{ads}}$  is calculated at  $-1.87$  eV. We considered that the O adatom is located similarly to the bulk structure, interacting simultaneously with the protruding 2-coordinated  $\text{Fe}_A$  and one of the 5-coordinated surface  $\text{Fe}_B$ , see **Figure 5.7** for  $\Gamma = +1$ . Other configurations, like the one with the O adatom interacting only atop the protruding 2-coordinated  $\text{Fe}_A$ , release less energy per adatom,  $-1.14$  eV. The bond distance between the added O atoms and the Fe ions ( $1.87$  Å for  $\text{Fe}_A$  and  $1.83$  Å for  $\text{Fe}_B$ ) is shorter than the first neighbour distance to both types of Fe in the bulk ( $1.89$  Å for  $\text{Fe}_A$  and  $2.05$  Å for  $\text{Fe}_B$ ) (Roldan *et al.*, 2013), as is expected due to contraction of the top atomic

surface layers after relaxation. The strongly exothermic adsorption suggests a favourable oxidation process, but as it is affected by  $\mu_{\text{O}}$ , its evaluation requires a complete analysis of the gas partial pressure in equilibrium with the surface.

Adding a second O atom ( $\Gamma = +2$ ) is also an exothermic process, releasing 0.96 eV per adatom. The second O atom preferentially coordinates the protruding  $\text{Fe}_{\text{A}}$  and a 5-coordinated  $\text{Fe}_{\text{B}}$ , forming another O bridging structure colinear with the  $[\bar{1}10]$  direction, **Figure 5.7** for  $\Gamma = +2$ . As for  $\Gamma = +1$ , the top atomic contraction leads to short Fe–O distances, 1.85 Å. Another conformation for the second O adsorption is coordinating equivalent atoms but forming a V-shaped structure, leading to a weaker adsorption ( $E_{\text{ads}} = -0.80$  eV).

At this point, it is worth mentioning that although we started from the ideal terminations similar to the bulk when we added the first and second oxygen atom, this did not prevent them to relax to a different position. In fact, we can see in **Figure 5.7** for  $\Gamma = +1$  (and +2), that after surface relaxation, the added oxygen has moved from its bulk site to another position, closer to the protruding  $\text{Fe}_{\text{A}}$ . This finding agrees with the work of Reuter and Scheffler (2001), who found for  $\text{RuO}_2(110)$  that terminations at positions different from the bulk can be important in non-stoichiometric compositions.

The Bader analysis on the density of the ( $\Gamma = +1$ ) oxidised (001) surface shows the oxidation of the top layer  $\text{Fe}_{\text{B}}$  by  $0.60 e^-$  while the protruding 2-coordinated  $\text{Fe}_{\text{A}}$  ion only donates  $0.04 e^-$  to the newly added O atom. Hence, the O adatom gains  $1.00 e^-$

mainly from the surface metals whereas the charge of the surface anions (all of them more negative than the adatom) change by about  $0.02 e^-$ .

#### 5.4.4 Oxidation of the (111) surface

On the (111) surface, the adsorption of one O atom ( $\Gamma = +1$ ) led to the formation of a bridging structure between the protruding  $\text{Fe}_B$  and one of the three closest 3-coordinated  $\text{Fe}_A$  (see **Figure 5.8** for  $\Gamma = +1$ ) releasing 3.00 eV. A less stable configuration is the one where the O-adatom is sitting atop the protruding  $\text{Fe}_B$  providing an  $E_{\text{ads}}$  of  $-2.04$  eV.

The addition of a second O-adatom coordinating the protruding  $\text{Fe}_B$  and one of the other two closest unoccupied 3-coordinated  $\text{Fe}_A$  releases 2.30 eV; see the schematic representation in **Figure 5.8** for  $\Gamma = +2$ . During the optimisation, this second oxygen pushes the protruding 3-coordinated  $\text{Fe}_B$  out of its equilibrium position in the stoichiometric surface, thereby forming a  $\text{Fe}_A\text{-O-Fe}_B\text{-O-Fe}_A$  row of atoms along the  $[0\bar{1}1]$  direction. The equilibrium bond lengths,  $\text{Fe}_A\text{-O}$  and  $\text{Fe}_B\text{-O}$  are 1.86 Å and 1.80 Å respectively, which compares well with values reported before (between 1.80 – 1.85 Å) for the Fe-O distance at the  $\text{Fe}_3\text{O}_4(111)$  surface (Martin *et al.*, 2009). In the next most favourable conformation the second O is located atop one surface O coordinating only the  $\text{Fe}_A$ , but this process is endothermic by 0.43 eV. The calculations thus show that both the first and second adsorbed O preferentially coordinate the protruding 3-coordinated  $\text{Fe}_B$  and two of its  $\text{Fe}_A$  neighbours with a resulting bridging structure in the  $[0\bar{1}1]$  direction.

Unlike the (001) surface, where the added oxygen atoms moved during the energy minimization, in the (111) we observed instead that the protruding  $\text{Fe}_B$  ion moved from its bulk position after the addition of two defects ( $\Gamma = +2$ ), see **Figure 5.8**. This validates in our methodology the possibility of exploring non-bulk-like relaxed positions for any atom in the surface of our slab, as long as all non-equivalent bulk-like positions for the defects are carefully investigated.

The Bader analysis indicates that in the preferred structure for  $\Gamma = +1$ , the adatom gains  $1.04 e^-$ , where the charge of the other surface O atoms decreased as little as in the (001) surface. Amongst the two Fe ions coordinated to the added O atom,  $\text{Fe}_B$  increases its charge by  $0.08 e^-$ , but  $\text{Fe}_A$  by  $0.39 e^-$ . The charge on other surface  $\text{Fe}_A$  and  $\text{Fe}_B$  ions upon addition of the O atom changed by an average of  $0.03 e^-$  and  $-0.01 e^-$  respectively.

## **5.5 Temperature and pressure effects**

In this section, we discuss the thermodynamics of the redox processes at the (001) and (111) surfaces as a function of temperature and  $\text{O}_2$  partial pressure in the gas phase.

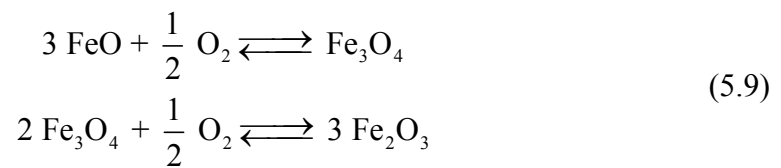
We express these macroscopic parameters by  $\mu_0$ .

In **Figure 5.9 (a)**, we have plotted  $\mu_0$  in terms of temperature and the  $\log p$ , along abscissas for easy comparison with the plots in **Figures 5.9 (b)** and **(c)**. All the information used for the construction of **Figure 5.9 (a)** comes from experiment (Chase, 1998) and is independent from the calculations (see Computational Methods section



on Chapter 5). Variations in  $T$  and  $p$  are necessary to modify the value of  $\mu_{\text{O}}$  as required and to reflect different reducing or oxidising conditions. For example, the oxygen chemical potential is  $-0.3$  eV (which is a typical oxidising value) at ambient conditions, *i.e.* at the intercept of  $T = 298.15$  K and  $p = 0.21$  bar, while more reducing conditions (lower values of  $\mu_{\text{O}}$ ) can be achieved by increasing  $T$  while keeping the pressure constant (*i.e.* horizontal solid line in **Figure 5.9 (a)**).

The area between the two vertical dashed lines ( $\mu_{\text{O}}$  from  $-3.13$  to  $-2.44$  eV) in **Figure 5.9** corresponds to the conditions where the  $\text{Fe}_3\text{O}_4$  bulk material is thermodynamically stable with respect to both  $\text{FeO}$  and  $\text{Fe}_2\text{O}_3$  bulk. We have derived these conditions ( $\mu_{\text{O}}$ ) from the experimental formation enthalpy of the three oxides (Haynes, 2012) and their increasing oxidation from  $\text{FeO}$  to  $\text{Fe}_2\text{O}_3$ , see equation (5.9). Under normal conditions,  $\text{Fe}_2\text{O}_3$  is the thermodynamically stable bulk phase, while the synthesis of  $\text{Fe}_3\text{O}_4$  requires high temperatures or a low pressure of  $\text{O}_2$  (which ultimately can lead to  $\text{FeO}$ ).



**Figures 5.9 (b)** and **(c)** show the variation of the surface free energies ( $\Delta\sigma$ ) of each surface composition versus  $\mu_{\text{O}}$ . Note that we have only used the most stable configuration for  $\Gamma = -2, -1, 0, +1, +2$ . Further degrees of reduction/oxidation ( $\Gamma = \pm 3$ ) could also be investigated but instead of exploring many different positions where to remove or add the O atoms, we have linearly fitted the intercept of the linear

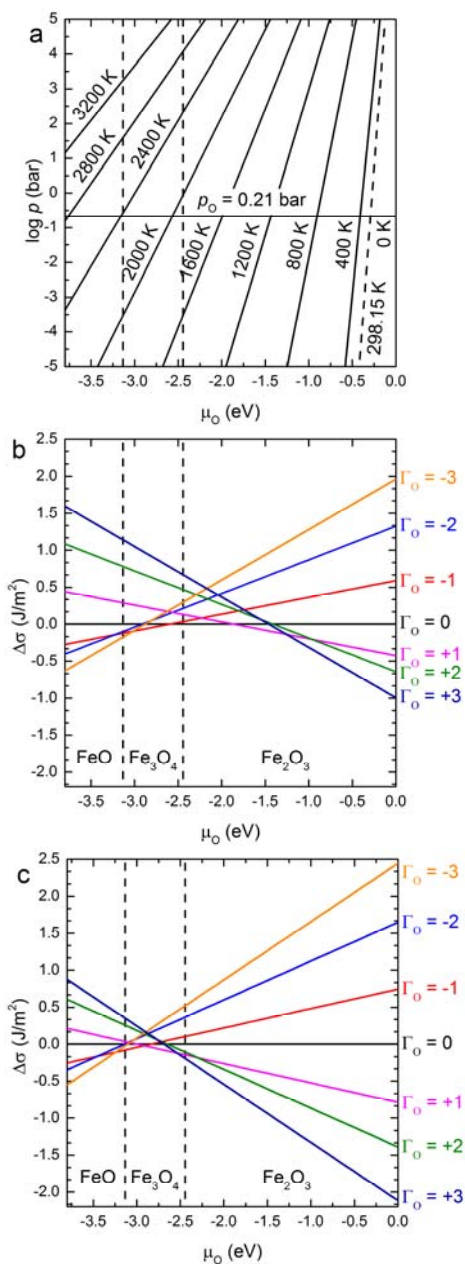
regressions in **Figure 5.9** as a function of  $\Gamma$  for inferring the intercepts of further oxidation/reduction of these surfaces. We have limited this treatment to three defects, as a higher number can lead to the formation of molecular oxygen in the case of oxidation or a new oxide phase in the case of reduction.

At  $\mu_{\text{O}} = -0.3$  eV (ambient conditions), the ( $\Gamma = +3$ ) oxidation of the  $\text{Fe}_3\text{O}_4(001)$  surface will take place, see **Figure 5.9 (b)**. For the conditions where bulk  $\text{Fe}_3\text{O}_4$  is the most stable oxide, the ( $\Gamma = +3$ ) oxidized (001) remains the most stable surface up to  $\mu_{\text{O}} = -1.25$  eV, from where the surface experiences a progressive reduction. In the early stages of this reduction, the unit cell loses two O atoms and remains so until  $\mu_{\text{O}} = -1.85$  eV. Beyond that chemical potential and until  $\mu_{\text{O}} = -2.60$  eV, which is just beyond the conditions in which the phase transition from  $\text{Fe}_2\text{O}_3$  to  $\text{Fe}_3\text{O}_4$  takes place, the most stable surface is the stoichiometric one. At lower values of  $\mu_{\text{O}} = -3.00$  eV (but still within the conditions in which  $\text{Fe}_3\text{O}_4$  is the most stable phase), the ( $\Gamma = -3$ ) reduced surface is the favoured system, until reaching the conditions where the reduced bulk phase of  $\text{FeO}$  is the most stable oxide. A recent publication by Nie *et al.* (2013) reports that the  $\text{Fe}_3\text{O}_4(001)$  surface is oxidised under exposure to  $4 \times 10^{-9}$  bar of oxygen at 923 K. They used low-energy electron microscopy (LEEM) and Raman spectroscopy to prove that  $\text{Fe}_3\text{O}_4$  grows at the expenses of Fe ions migrating from the bulk towards the surface. The Fe ion vacancies in the bulk, in turn, transform it into  $\alpha$ - $\text{Fe}_2\text{O}_3$  (hematite), which is the equilibrium iron oxide phase at the temperature and pressure of the experiment. Our results hence agree well with these experimental

findings, although they are close to the limit in which the stoichiometric surface is the most stable one. The experimental conditions described above correspond to  $\mu_{\text{O}} = -1.75$  eV according to equation (5.6), a value at which the  $\text{Fe}_3\text{O}_4(001)$  surface is prone to suffer oxidation (see **Figure 5.9 (b)**), by adding one O atom per surface unit cell around the protruding  $\text{Fe}_A$ . Our results, however, agree partially with those reported in a DFT study by Pentcheva *et al.* (2005) as those authors found that the modified non-stoichiometric polar bulk-like  $\text{Fe}_3\text{O}_4(001)$  surface ( $\text{Fe}_B\text{-O}$  layer) is the most stable under any chemical potential. However, the surface proposed by Pentcheva *et al.* (2005) is a generic oxidised (001) surface, created from a bulk-like termination, whereas our surface is gradually oxidised or reduced. However, regardless of terminations and reconstructions, we also predict our non-dipolar surface to be ( $\Gamma = +3$  and  $+1$ ) oxidized up to  $\mu_{\text{O}} = -1.85$  eV, but from this value of chemical potential onwards, our results predict a gradual reduction, which no longer agrees with the work by Pentcheva *et al.* (2005) as they predict the same oxidized surface for any value of  $\mu_{\text{O}}$ .

The redox behaviour of the  $\text{Fe}_3\text{O}_4(111)$  surface is shown in **Figure 5.9 (c)**. It indicates that the redox properties of the (111) surface are similar to the (001) surface, although the oxidized character extends to lower chemical potentials. The surface tends to be ( $\Gamma = +3$ ) oxidised under the condition where  $\text{Fe}_2\text{O}_3$  is the most stable phase and up to  $\mu_{\text{O}} = -2.45$  eV, which is within the region where  $\text{Fe}_3\text{O}_4$  is the thermodynamically most stable iron oxide. From here, the surface loses two O atoms for a very short range of chemical potential, until  $\mu_{\text{O}} = -2.95$  eV, from where the surface loses a further two

more O atoms, becoming now reduced up to  $\mu_{\text{O}} = -3.25$  eV. From this final value of the chemical potential, the surface becomes reduced ( $\Gamma = -3$ ). In a previous DFT +  $U$  study, Kiejna *et al.* (2012) studied the redox properties of the  $\text{Fe}_3\text{O}_4(111)$  surface. They only studied the non-stoichiometric dipolar bulk-like terminations and found that the  $\text{Fe}_{\text{A1}}$  surface, which corresponds with a generic oxidized one, is the most stable one up to  $\mu_{\text{O}} = -2.6$  eV, from which point their surfaces started to reduce gradually. Although we cannot make a direct comparison of our results due to the different terminations considered in both works, owing to our gradual redox processes, our results show the same trend.



**Figure 5.9.** (a)  $\mu_{\text{O}}$  in the gas phase as a function of the temperature and the logarithm of the oxygen partial pressure and relative surface free energies ( $\Delta\sigma$ ) for the Fe<sub>3</sub>O<sub>4</sub> (b) (001) and (c) (111) surfaces as a function of the oxygen chemical potential ( $\mu_{\text{O}}$ ). The areas corresponding to  $\mu_{\text{O}}$  smaller than  $-3.13$  eV, bigger than  $-2.44$  eV and between these two values represent the approximate conditions under which bulk FeO, Fe<sub>2</sub>O<sub>3</sub> and Fe<sub>3</sub>O<sub>4</sub> respectively are the stable oxides.

Comparing both ( $\Gamma = +3$ ) oxidised surfaces, the (111) is lower in energy than the (001) for the whole  $\mu_0$  scale considered. Therefore the (111) surface will remain oxidised even at  $\mu_0$  where  $\text{Fe}_3\text{O}_4(001)$  is not. We suggest then, from **Figure 5.9**, that under the conditions in which the bulk  $\text{Fe}_3\text{O}_4$  is the most stable oxide, the phase transformation of the reduction of  $\text{Fe}_3\text{O}_4$  towards  $\text{FeO}$  will start from the (001) surface. On the other hand,  $\text{Fe}_3\text{O}_4$  oxidation to  $\text{Fe}_2\text{O}_3$  would take place initially on the (111).

## **5.4 Chapter conclusions**

In this chapter, we have modelled three different surface orientations of  $\text{Fe}_3\text{O}_4$  crystals by using DFT methods within the GGA +  $U$  approximation. We have investigated the stabilities of their multiple (reconstructed) non-dipolar stoichiometric surface terminations and studied the redox properties of the most prominent surfaces. We have modified the redox conditions by creating O vacancies or adding O atoms to the most stable non-dipolar stoichiometric surface termination, under a wide range of chemical potentials, including ambient conditions and those conditions where bulk  $\text{Fe}_3\text{O}_4$  is the thermodynamically most stable oxide. In the initial stages of oxidation, the excess O atoms form bridging structures with the Fe ions at the surface, and in particular the Fe ions protruding from the surface. We found that some oxidised (non-stoichiometric) structures relaxed in such a way that it broke the bulk-like termination.

We conclude that the Fe-terminated (001) and (111) planes are the most stable  $\text{Fe}_3\text{O}_4$  surfaces, in agreement with previous experiments as shown by STM images. The

equilibrium morphology of  $\text{Fe}_3\text{O}_4$  was found to be cubic with truncated corners, which means that (001) and (111) are the main surfaces exposed in the crystals. Although both (001) and (111) surfaces will be oxidized under ambient conditions, both surfaces suffer a gradual reduction, that starts at lower chemical potentials for the (001) surface including the stoichiometric plane.

The reduction of the (001) and (111) surfaces is thermodynamically favourable at the low end of the  $\mu_{\text{O}}$  values in the region where  $\text{Fe}_3\text{O}_4$  is the most stable oxide. We found that, in both cases, the O vacancies are likely to migrate towards the bulk, thereby changing the phase structure.

# 6

## Early oxidation stages of greigite $\text{Fe}_3\text{S}_4(001)$ surface by water

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### 6.1 Introduction

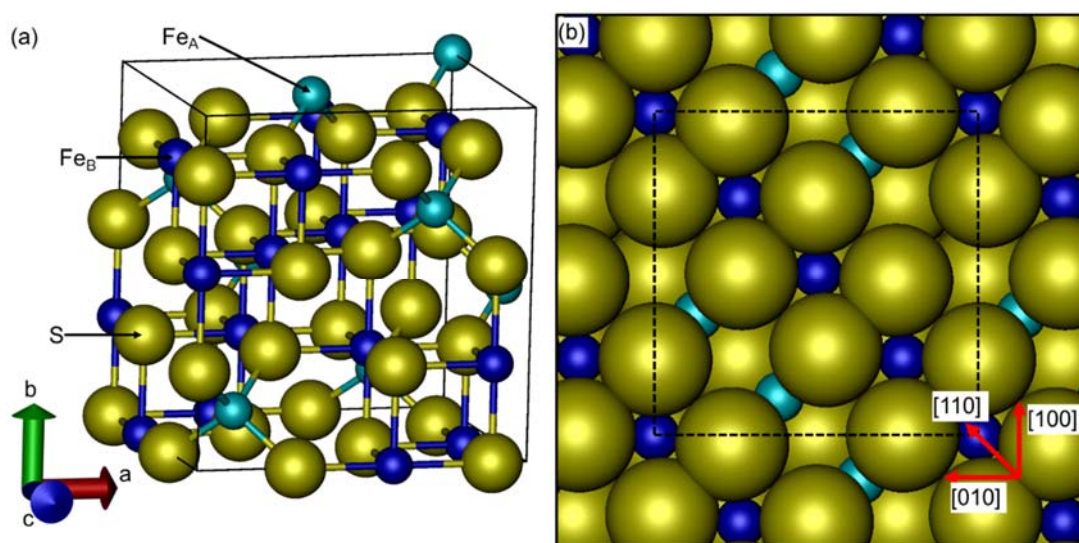
The extremely acidic sulfur-rich wastewaters are a current worldwide problem. The thereafter called acid mine drainage (AMD) or acid rock drainage (ARD) is associated with natural weathering of rock formations (Joeckel *et al.*, 2005) and, in particular, aggravated by existing and historic human activities such as the mining industry (Banks *et al.*, 1997; Bowen *et al.*, 1998; Younger, 2002). Once the mining or processing operations expose the metal sulfide compounds, in particular pyrite  $\text{FeS}_2$ , to weathering elements (Johnson, 2003) such as  $\text{O}_2$  and  $\text{H}_2\text{O}$  as well as certain microorganisms (Fowler *et al.*, 2001, 1999; Schippers and Sand, 1999), the minerals steadily oxidize. This results in reduction of the water pH (Hammarstrom *et al.*, 2003) and potentially high concentrations of toxic metallic and metalloid elements in these solutions (Matlock *et al.*, 2002), depending on the initial composition of the exposed minerals.



The chemical reactions leading to the oxidation and dissolution of metal sulfides have been studied and several types of mechanisms were suggested, depending on the minerals and the oxidizing agent present. In the polysulfide mechanism, characteristic of acid-soluble sulfides, *e.g.* sphalerite (ZnS), protons attack the mineral and produce H<sub>2</sub>S. Sulfur-oxidizing bacteria further oxidizes the H<sub>2</sub>S to SO<sub>4</sub><sup>2-</sup> and regenerates the protons (Schippers and Sand, 1999). In the thiosulfate mechanism, characteristic of non-acid-soluble sulfides, *e.g.* pyrite (FeS<sub>2</sub>) (Vaughan and Craig, 1978), initially aqueous iron(III) ions attack the metal sulfide mineral generating protons, thiosulfate (S<sub>2</sub>O<sub>3</sub><sup>2-</sup>) and iron(II). Secondly, this iron(II) is re-oxidized by iron-oxidizing bacteria, while following several steps, S<sub>2</sub>O<sub>3</sub><sup>2-</sup> decomposes into elemental sulfur and SO<sub>4</sub><sup>2-</sup> ions (Fowler *et al.*, 2001, 1999; Schippers and Sand, 1999).

Iron sulfides are the most predominant sulfides found in anoxic marine sediments (Morse *et al.*, 1987) and therefore one of the main sources of AMD (Akçil and Koldas, 2006; Johnson and Hallberg, 2005; Johnson, 2003). Although FeS<sub>2</sub> is a stable mineral in these environments (Berner, 1984, 1970; Morse *et al.*, 1987), important research have been devoted to study its oxidation (Chandra and Gerson, 2010; Fowler *et al.*, 2001, 1999; Gartman and Luther, 2014; Lawson, 1982; McKibben and Barnes, 1986; Moses *et al.*, 1987; Rimstidt and Vaughan, 2003; Williamson and Rimstidt, 1994) overlooking other iron sulfide minerals. Among them, greigite (Fe<sub>3</sub>S<sub>4</sub>) is an intermediate in the formation of FeS<sub>2</sub> (Benning *et al.*, 2000; Dekkers and Schoonen, 1996; Hunger and Benning, 2007; Lennie *et al.*, 1997; Wilkin and Barnes, 1996), which has a long environmental persistence (Stolz *et al.*, 1986) and can also be found

in aquatic environments (Frank *et al.*, 2007; Jelinowska *et al.*, 1998, 1995; Roberts and Turner, 1993; Skinner *et al.*, 1964; Snowball, 1991), soils (Fassbinder *et al.*, 1990; Fassbinder and Stanjek, 1994) as well as in magnetotactic bacteria (Mann *et al.*, 1990) and gastropods (Goffredi *et al.*, 2004).



**Figure 6.1.** (a) Ball-and-stick model of the unit cell of  $\text{Fe}_3\text{S}_4$  showing the cubic spinel crystal structure and (b) top view of the space-filling model of its (001) surface.

Taking into account the structural differences between  $\text{FeS}_2$  and  $\text{Fe}_3\text{S}_4$  and the decisive role of the persulfide group in dictating the mechanism of the oxidation reactions on metal sulfides (Schippers and Sand, 1999), we have used density functional theory (DFT) calculations to investigate the early oxidation processes of  $\text{Fe}_3\text{S}_4$  via a polysulfide mechanism, in order to explain this mineral's lability on a disturbed aqueous medium. We propose three mechanisms to account for the replacement of one S by one O atom on the top layer of the  $\text{Fe}_3\text{S}_4(001)$  surface, which appears to be the most prominent one (Roldan and de Leeuw, 2015). In any of these pathways,  $\text{H}_2\text{O}$

may oxidize the (001) surface with the resulting production of molecular H<sub>2</sub>S. We have also applied thermodynamic arguments to examine the pH conditions or H<sub>2</sub>S concentration, in aqueous solution, and temperatures at which these species are in equilibrium with the stoichiometric and oxidized Fe<sub>3</sub>S<sub>4</sub>(001) surface, which is relevant to the geochemical formation of AMD.

## **6.2 Computational methods**

We have performed spin-polarized calculations with the Vienna *Ab-initio* Simulation Package (VASP) (Kresse and Furthmüller, 1996a, 1996b; Kresse and Hafner, 1994, 1993). All simulations were carried out within the periodic plane-wave DFT framework. The projector augmented wave (PAW) method was used to describe the electron-ion interaction (Blöchl, 1994; Kresse and Joubert, 1999). The frozen core of the Fe, S and O elements was defined up to and including the 3*p*, 2*p* and 1*s* electrons respectively. At the level of the generalized gradient approximation (GGA), the exchange-correlation in the form of Perdew-Wang 91 (PW91) (Perdew *et al.*, 1993, 1992) functional was used together with the spin interpolation of Vosko *et al.* (1980). The long-range dispersion interactions were added *via* the D2 semiempirical method of Grimme (2006), using the global scaling factor parameter optimized for the Perdew-Burke-Ernzerhof (PBE) (Perdew *et al.*, 1997, 1996a) functional,  $s_6 = 0.75$ , which has shown to be successful in the modelling of a number of iron minerals (Dzade *et al.*, 2013; Haider *et al.*, 2014; Irrera *et al.*, 2013). Brillouin zone integrations were performed using a Monkhorst-Pack grid (Monkhorst and Pack, 1976) of 4×4×1 *Γ*-

centred  $k$ -points. In order to increase the integration efficiency in the reciprocal space, the partial occupancies for all calculations were determined using the tetrahedron method with Blöchl corrections (Blöchl *et al.*, 1994). Kohn-Sham (KS) states were expanded in a plane-wave basis set with the kinetic energy's cut-off fixed at 600 eV. The DFT +  $U$  (Anisimov *et al.*, 1992) version of Dudarev *et al.* (1998) was used for the description of the localized and strongly correlated  $d$  Fe electrons. Based on previous works, we have chosen a  $U_{\text{eff}}$  of 1.0 eV (Devey *et al.*, 2009; Haider *et al.*, 2012; Roldan and de Leeuw, 2015; Roldan *et al.*, 2013). Electronic density optimization was stopped when the total energy difference between two consecutive self-consistent loop steps was below  $10^{-5}$  eV. Atomic positions were relaxed to their ground state using the conjugates-gradient method and were considered converged when the Hellmann-Feynman forces on all atoms were smaller than  $0.02 \text{ eV}\cdot\text{\AA}^{-1}$ . The dimer method was used to search the transitions states (TS) (Henkelman and Jónsson, 1999; Heyden *et al.*, 2005), which were characterised by frequency calculations to confirm the existence of only one normal mode associated with an imaginary frequency corresponding to the reaction coordinate. Higher cut-off values and  $k$ -point grids as well as a lower self-consistent energy threshold were tested to ensure energies were converged within 1 meV per atom.

Greigite has a spinel crystal structure characterized by the space group  $Fd\bar{3}m$  (Skinner *et al.*, 1964). The face-centred cubic unit cell is composed by 32 sulfur anions, which are nearly regularly close packed along the [111] direction. This S arrangement generates 8 tetrahedral (A) and 16 octahedral (B) holes per unit cell occupied by Fe cations, giving a total of eight formula units (f.u.), see **Figure 6.1 (a)**. Fe<sub>3</sub>S<sub>4</sub> is a 2–3

type spinel, which is a classification based on the cation valency, that indicates the existence of one Fe<sup>2+</sup> and two Fe<sup>3+</sup> cations per formula unit. This spinel has an *inverse* cation distribution  $\text{Fe}_A^{3+} [\text{Fe}^{2+}\text{Fe}^{3+}]_B \text{S}_4$ , where half of the Fe<sup>3+</sup> cations are filling the A positions and all the Fe<sup>2+</sup> together with the rest of the Fe<sup>3+</sup> ions are occupying the B holes (Chang *et al.*, 2009; Dekkers *et al.*, 2000; Surerus *et al.*, 1989; Vaughan and Craig, 1985; Vaughan and Tossell, 1981). Initial magnetic moments of the A and B sublattices were set antiparallely, in line with previous studies (Devey *et al.*, 2009; Roldan *et al.*, 2013).

Surface calculations were carried out using the (001) slab model, see **Figure 6.1 (b)**, defined in a previous study of the catalytic dissociation of H<sub>2</sub>O on various Fe<sub>3</sub>S<sub>4</sub> surfaces (Roldan and de Leeuw, 2015). The topmost layer of the (001) surface is finished with a bulk-like structure containing single rows in the [110] direction of 5-coordinated Fe<sub>B</sub> ions alternating every two single rows of O ions with cubic packing. Beneath this layer, there are 1.5 monolayers (ML) of 4-coordinated Fe<sub>A</sub> forming also rows parallel to the S ones. From this layer, 0.5 ML with a  $(\sqrt{2} \times \sqrt{2})R45^\circ$  symmetry come from above the surface, which moved inward during relaxation. These slabs were composed by 8 formula units of Fe<sub>3</sub>S<sub>4</sub> and separated by 12 Å of vacuum in the direction perpendicular to the surface. The bottom 5 atomic layers were kept frozen at their relaxed bulk positions, while the remaining top layers were allowed to relax. This computational setup of the Fe<sub>3</sub>S<sub>4</sub> surfaces is equivalent to the one used before for the description of the non-dipolar stoichiometric surfaces of its oxide counterpart Fe<sub>3</sub>O<sub>4</sub> (Santos-Carballal *et al.*, 2014), which provided an accurate and realistic means for

calculating the surface properties of this mineral. Convergence of the slab energy within 1 meV was further tested with different slab and vacuum thickness as well as number of relaxed layers. In order to enhance the electronic convergence, dipole corrections perpendicular to the surface were included in our simulations to account for the dipole created due to the chemical species added in the relaxed surface of the slab (Makov and Payne, 1995; Neugebauer and Scheffler, 1992).

A Bader analysis was used to partition the charge density grid into atomic charges (Henkelman *et al.*, 2006; Sanville *et al.*, 2007; Tang *et al.*, 2009). Charge density difference diagrams were constructed by subtracting from the electronic charge density of the total adsorbate-surface system, the sum of the charge densities of the isolated adsorbate and clean surface in the same geometry.

The energy of the system along the profile of the proposed mechanisms was calculated according to the following equation,

$$E_{\text{state}} = E_{\text{system}} - nE_{\text{H}_2\text{O}} - E_{\text{slab}} \quad (6.1)$$

where  $n$  represents the number of H<sub>2</sub>O molecules and  $E_{\text{system}}$ ,  $E_{\text{H}_2\text{O}}$  and  $E_{\text{slab}}$  are the energy of the system, one isolated H<sub>2</sub>O molecule in vacuum and the pristine stoichiometric relaxed Fe<sub>3</sub>S<sub>4</sub>(001) surface slab respectively.

### **6.3 Fe<sub>3</sub>S<sub>4</sub>(001) surface oxidation**

We considered three main mechanisms for studying the oxidation of the Fe<sub>3</sub>S<sub>4</sub>(001) surface through the exchange of a S on the top layer by an O atom from the water

releasing one H<sub>2</sub>S molecule, as shown in **Figures 6.3 (a)**, **6.5 (a)** and **6.7**. In these schemes, the numbers identify a particular state in the mechanism,  $E_{\text{ads}}^i$  is the adsorption energy,  $E_{\text{diss}}^i$  is the dissociation energy of the specie  $i$ ,  $E_{A_j}$  is the activation energy of the step  $j$ ,  $E_{\text{prot}}^{\text{SH}}$  is the energy required to move one H atom from the H<sub>2</sub>O to the SH group and  $E_{\text{exch}}^{\text{O} \rightarrow \text{S}}$  is the total energy required to exchange one S atom in the mineral surface by an O atom from the water. In this paper, we do not analyse the dissociative adsorption of one or two H<sub>2</sub>O molecules (where only one dissociates) or the OH group as they have already been discussed before (Roldan and de Leeuw, 2015). Therefore, we have chosen the most favourable mode of adsorption of these states as the initial configurations in this work.

### 6.3.1 Pathway 1

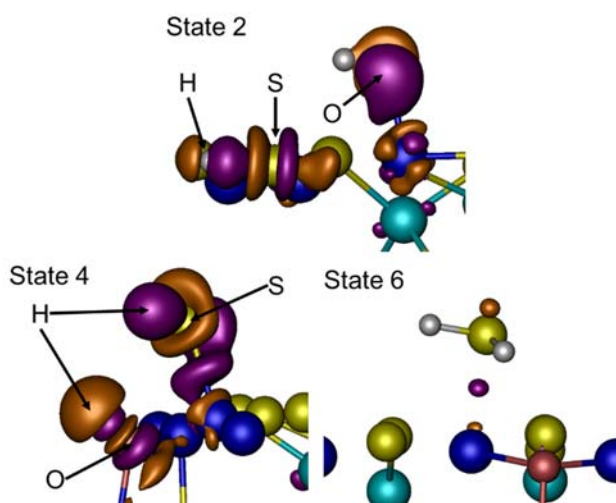
Dissociative adsorption on the (001) surface of one H<sub>2</sub>O molecule is thermodynamically more favourable to happen with its O atom coordinating one of the Fe<sub>B</sub> ions, at 1.83 Å of distance, see state 2 on **Table 6.1** and **Figure 6.3** (Roldan and de Leeuw, 2015). In the hydroxyl group, the O–H distance is 0.98 Å. Although all Fe<sub>B</sub> are equivalent in this surface, the existence of the Fe<sub>A</sub> ions and the newly absorbed H<sub>2</sub>O molecule generates four non-equivalent types of S ions around the hydroxylated Fe<sub>B</sub> ion. The dissociated H, in turn, is more probable to be found attached at 1.36 Å of distance to the S next to the hydroxylated Fe<sub>B</sub>. The H atom now bounded to the mineral surface is located between three S atoms, at the tetrahedral cavity of the Fe<sub>A</sub> row on the [110] direction. The charge analysis indicates that, after adsorption, there is a charge transfer mainly from the hydroxyl O and the protonated S to their

respective H, which indicates the covalent character interaction between these two pair of atoms. We have quantified the increase of charge of the O and S atoms as 1.0 and 1.1  $e^-$  respectively, while the H atoms reduced their charge by an average of 1.3  $e^-$ . This can be represented graphically in a charge density difference plot, illustrating density changes on the dissociative adsorption of one H<sub>2</sub>O molecule, **Figure 6.2**, where we can see that charge is mostly localized on the O–H and S–H bonds. We found that configuration 2 is 0.34 eV above the energy of the pristine Fe<sub>3</sub>S<sub>4</sub>(001) and one isolated H<sub>2</sub>O molecule. We also tested the possibility of the migration of the remaining H atom from the hydroxyl group to the protonated S atom, but several initial configurations led to OH + SH as O is more basic than SH. This agrees with the similar behaviour found for the (001) surface of FeNi<sub>2</sub>S<sub>4</sub> (Haider *et al.*, 2014), an intermediate spinel between the one under study in this work and Ni<sub>3</sub>S<sub>4</sub>.

The reaction profile for the exchange of one S by one O atom on the Fe<sub>3</sub>S<sub>4</sub>(001) surface, according to mechanism 1, is shown in **Figure 6.3**, where only one H<sub>2</sub>O molecule per surface unit cell is involved, equivalent to 0.25 ML of coverage. Note that we have defined a full ML as the amount of H<sub>2</sub>O required to hydrate the four Fe<sub>B</sub> ions per formula unit. The protonated S is the most available one to be exchanged by the OH group. In a concerted step, the SH group migrates to the top of the next Fe<sub>B</sub> ion on the surface layer, while the OH group takes its place, increasing its coordination number with three Fe ions. This is an exothermic process with an  $E_{\text{exch}}^{\text{O} \rightarrow \text{S}}$  of  $-0.24$  eV and an activation energy ( $E_{\text{A1}}$ ) of 0.80 eV. On the structure after the exchange of SH by OH, shown for the state 4 on **Figure 6.3**, the O atom lays at 0.63 Å below the average



position of the surface layer of S atoms, in part due to its smaller ionic radius with respect to the S ions. At the same state, the H of the hydroxyl is at 0.98 Å of the O atom, see **Table 6.1**, pointing upwards in such a way that it lies on the cavity of the Fe<sub>A</sub> row along the [110] direction, at the same level of the top S layer. The S–H and Fe<sub>B</sub>–S distances of the SH group are 1.35 and 2.27 Å respectively. The charge analysis shows that after the SH exchange by OH, the hydroxyl group has received 0.26 e<sup>-</sup> (where 0.18 e<sup>-</sup> were located on the O atom), donated by the H of the SH group (0.18 e<sup>-</sup>) and the Fe<sub>B</sub> binding it (0.11 e<sup>-</sup>). The charge transfers associated with the exchange process explains the availability of a protonated S ion to exchange its place with the more nucleophilic OH group. **Figure 6.2** shows the charge transfer mechanism, at the state 4, with respect to the oxidized surface and the H<sub>2</sub>S dissociative adsorption. While the electronic density located on the O–H bond comes primarily from the H, the S atom of the adsorbed SH gave its electrons to form the Fe<sub>B</sub>–S bond and reinforce the S–H one, in agreement with the atomic electronegativities.



**Figure 6.2.** Charge density difference plot of the adsorption at different stages along the oxidation of the  $\text{Fe}_3\text{S}_4(001)$  surface following pathway 1. Isosurfaces of the difference density are displayed at a value of  $\pm 0.05 \text{ e}\cdot\text{\AA}^{-3}$ , where purple and orange represent gain and lost electron density respectively. Light blue atoms represent  $\text{Fe}_A$ , dark blue for  $\text{Fe}_B$ , yellow for S, red for O and white for H.

**Table 6.1.** Calculated bond distances ( $\text{\AA}$ ) and angles ( $^\circ$ ) at different minima states along the  $\text{Fe}_3\text{S}_4(001)$  surface oxidation following pathway 1.

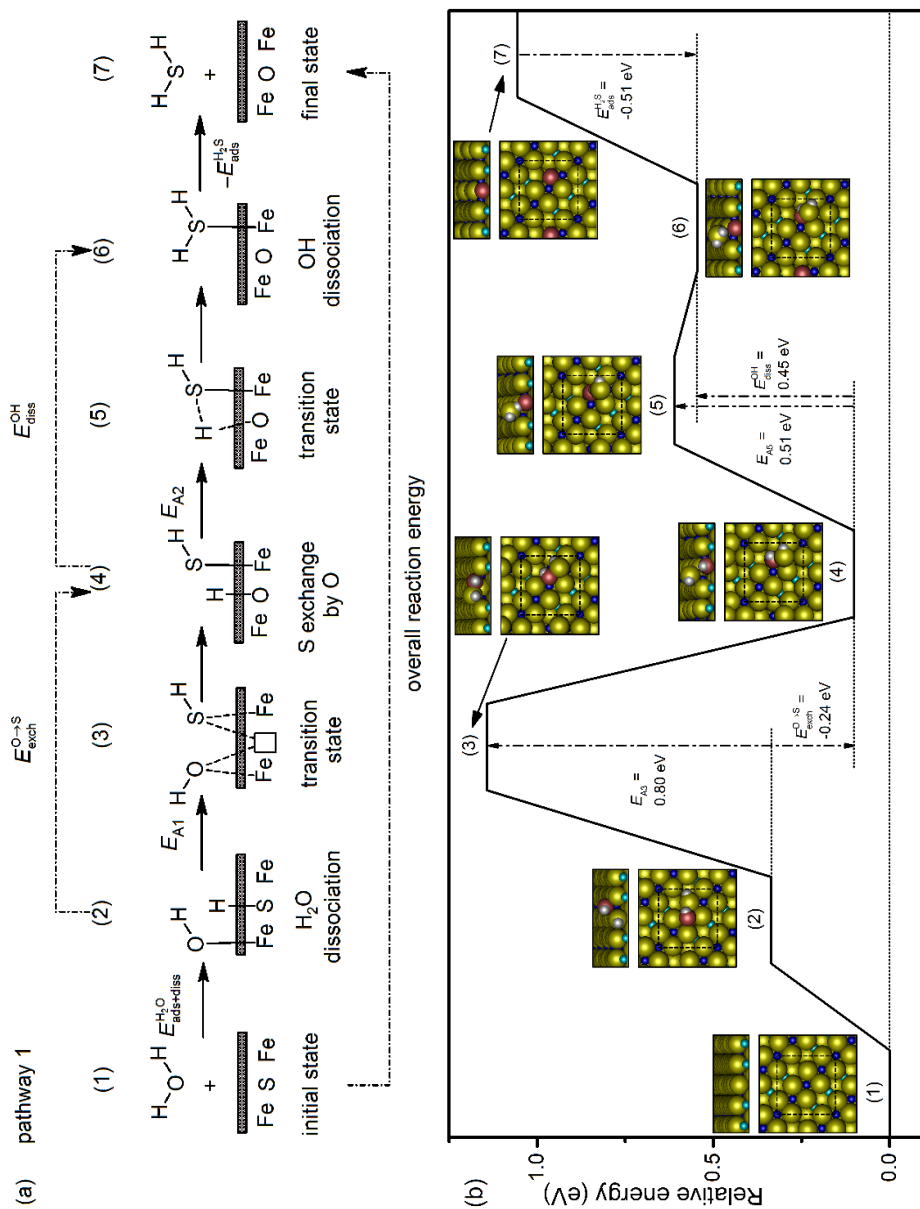
state	2	4	6
$d(\text{O}-\text{Fe}_{B1})$	1.83	--	--
$d(\text{S}-\text{Fe}_{B2})$	--	2.27	2.70
$d(\text{H}_1-\text{O})$	0.98	0.98	
$d(\text{H}_1-\text{S})$			1.35
$d(\text{H}_2-\text{S})$	1.36	1.35	1.35
$\angle \text{H}_1-\text{S}-\text{H}_2$	--	--	92.3

The next step in this mechanism is the generation of  $\text{H}_2\text{S}$  following the migration of the hydroxyl H, see state 6 on **Figure 6.3**. In the resulting structure, the O remains

slightly below the top S layer, but moved horizontally by 0.81 Å closer to the Fe<sub>B</sub> ion holding the H<sub>2</sub>S molecule. The H<sub>2</sub>S molecule is adsorbed nearly vertically on top of the Fe<sub>B</sub>, at 2.70 Å, see **Table 6.1**. The H atoms are equally separated from the S (1.35 Å), forming a bond angle of 92.3°, slightly bigger than for the isolated molecule (90°) related to a weak interaction with the oxidized surface. According to the charge analysis, the formation of the H<sub>2</sub>S molecule is accompanied by an increase of the positive charge at the S atom (by 0.8 e<sup>-</sup>), while the O atom reduces its negative charge by the same amount, followed by an electron rearrangement on the H<sub>2</sub>S hydrogens. The state 6 is 0.45 eV above state 4 in the energy profile, which means that the migration of the H is less favourable than the introduction of the OH group at the surface. The activation energy of this step ( $E_{A2}$ ) is 0.29 eV smaller than  $E_{A1}$  indicating that the exchange of the SH by OH group is the determinant step in this pathway. Moreover, the energies associated with the states 4, 5 and 6 show that the reverse process is thermodynamically and kinetically more favourable. Hence, in the reverse process, the dissociation of a H<sub>2</sub>S molecule adsorbed on a partially oxidized Fe<sub>3</sub>O<sub>4</sub>(001) has an activation energy of 0.04 eV, just above the thermal energy ( $2k_bT$ ) at 298 K.

H<sub>2</sub>S desorption is an unfavourable process as state 7 is 1.06 eV above the reference. Although the H<sub>2</sub>S desorption affects negligibly the surface structure, the charge analysis shows an increase of 0.9 e<sup>-</sup> on the Fe<sub>B</sub> atoms coordinated to the O, while the charge of the two S atoms, coordinated to the Fe<sub>B</sub> site and the subsurface Fe<sub>A</sub>, decreased by 0.6 e<sup>-</sup>.

According to this pathway, the position for the S substitution was dictated by the most stable adsorption site of the H. Nevertheless, test calculations revealed that the substituted S atom is not the most thermodynamically prone to be substituted, but any two of them coordinating the Fe<sub>A</sub> next to the cavity along the [110] direction. Therefore, we examined the possibility of the O diffusion towards the most stable substitution position. The solid state diffusion process stabilizes the surface slab by an additional 0.14 eV after overcoming a barrier of 2.14 eV. The high activation energy of the O diffusion suggests that this step is highly unlikely to happen in static conditions once the oxidation of the Fe<sub>3</sub>S<sub>4</sub>(001) surface has occurred. In the structure of this final configuration, the O atom moved outwards by 0.21 Å but still remained below the S top layer. The charge analysis reveals that, after the O diffusion, the three surface Fe<sub>B</sub> that were coordinating the O atom before and after this process reduce their overall charge by 0.7 e<sup>-</sup>. This electronic transfer happens in such a way, that 0.6 e<sup>-</sup> are drawn from two S atoms that become equally charged as the rest of the surface S atoms.



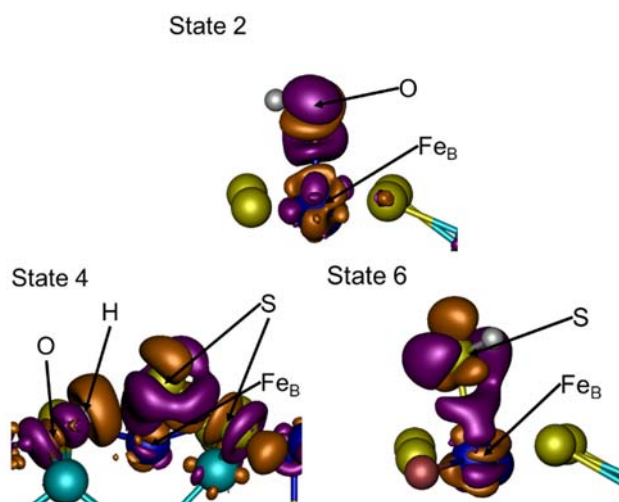
**Figure 6.3.** (a) Schematic representation and (b) reaction profile for the oxidation of the  $Fe_3S_4(001)$  surface via pathway 1. Insets show side and top view of the structure of the numbered states. Only the surface and species adsorbed to it are shown. Light blue atoms represent  $Fe_A$ , dark blue for  $Fe_B$ , yellow for S, red for O and white for H.

### 6.3.2 Pathway 2

A sensible alternative of the discussed pathway is to consider the H migration away from the  $Fe_B$ -OH centre. This situation leads us to pathway 2, shown in **Figure 6.5**, which depicts the oxidation of the surface by one OH group (coverage of 0.25 ML). Note that in agreement with the reference, the states 2 to 6 energies have been calibrated by considering the energy of one proton sitting onto the most stable position on the  $Fe_3S_4(001)$  surface.

In the hydroxylated surface, the O-H distance remains the same than in the  $H_2O$  of pathway 1, both at stage 2, see **Table 6.2**. However, the  $Fe_B$ -O bond length is 0.02 Å shorter, suggesting that the OH group is bonded slightly stronger in the absence of the second H atom. Our calculations show that this state is 0.09 eV lower in energy than the equivalent stage of pathway 1, which corroborates the thermodynamic feasibility of the H migration. The charge analysis showed that 0.6  $e^-$  were transferred from the  $Fe_B$  to the OH in agreement with this shortened bond. We also found that the absence of a proton attached nearby generates further changes on the surface electronic structure. For example, the OH-coordinated  $Fe_B$  and the three top  $Fe_A$  release 1.7  $e^-$  overall, 88 % of which is supplied to the topmost S atoms and to the hydroxyl (the O atom is 0.9  $e^-$  more negative than the same stage of pathway 1). This increase in the nucleophilic character makes the O more eager to coordinate cations, *i.e.* take a position on the surface and being surrounded by a higher number of Fe ions. The charge density difference of the second state is shown in **Figure 6.4**, illustrating that

much of the electronic density located between the  $\text{Fe}_B$  and O atoms originally came from the O electron lone pair.



**Figure 6.4.** Charge density difference plot of the adsorption at different stages along the oxidation of the  $\text{Fe}_3\text{S}_4(001)$  surface following pathway 2. Isosurfaces of the difference density are displayed at a value of  $\pm 0.05 \text{ e}\cdot\text{\AA}^{-3}$ , where purple and orange represent gain and lost electron density respectively. Light blue atoms represent  $\text{Fe}_A$ , dark blue for  $\text{Fe}_B$ , yellow for S, red for O and white for H.

**Table 6.2.** Calculated bond distances ( $\text{\AA}$ ) at different minima states along the  $\text{Fe}_3\text{S}_4(001)$  surface oxidation following pathway 2.

state	2	4	6
$d(\text{O}-\text{Fe}_{B1})$	1.81	--	--
$d(\text{S}-\text{Fe}_{B2})$	--	2.27	2.22
$d(\text{H}-\text{O})$	0.98	1.00	--
$d(\text{H}-\text{S})$	--	--	1.35
$d(\text{H}\cdots\text{S})$	--	2.07	--

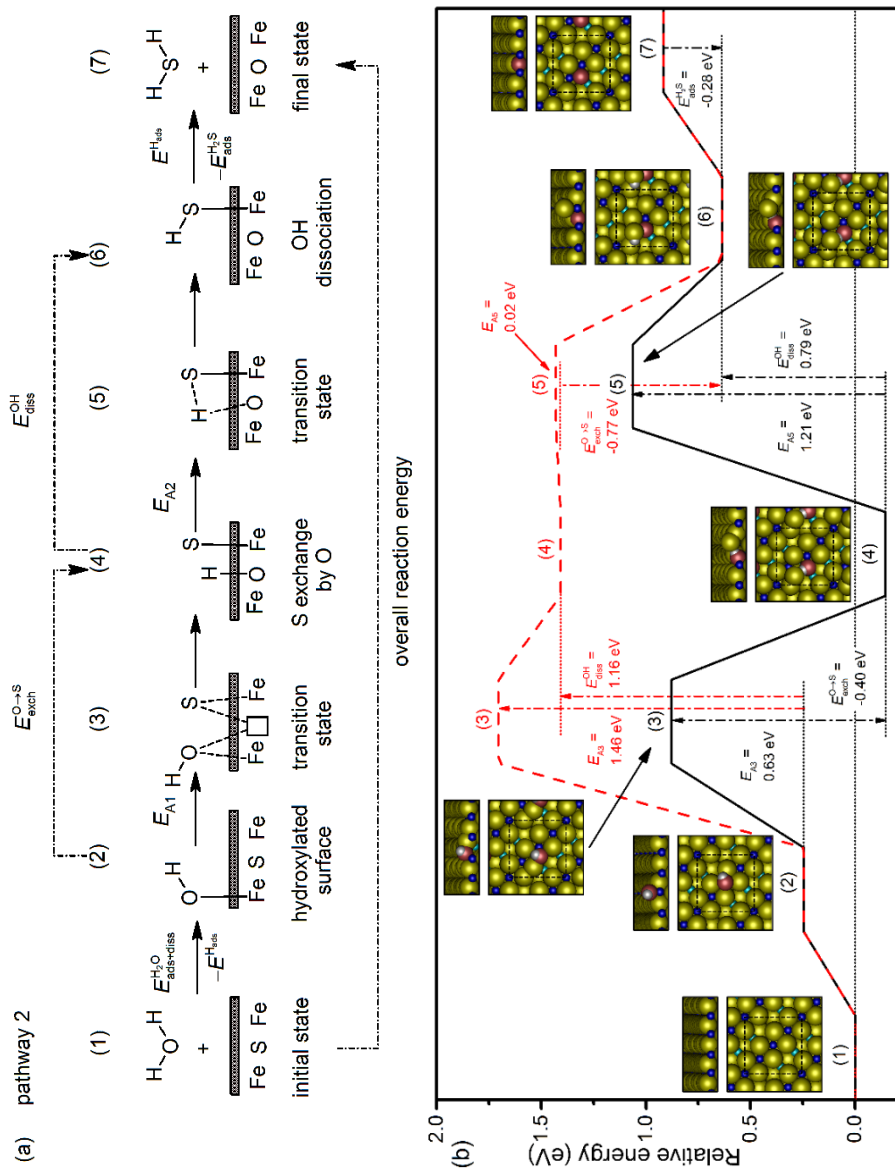
The hydroxylated Fe<sub>B</sub> is surrounded by four non-equivalent S atoms. In the absence of a protonated sulfur, the hydroxyl O replaces the S leading to the thermodynamic product, which is equivalent to the last configuration of pathway 1. Despite the similarities, as the replaced S atom remains unprotonated, it forms a hydrogen bond ( $d(\text{H}\cdots\text{S}) = 2.07 \text{ \AA}$ ) with the hydroxyl H, see state 4 on **Figure 6.5** and **Table 6.2**. The O–H bond distance is longer by 0.02 Å while the O is displaced outward the surface by 0.07 Å as well as along the [110] direction, with regard to the same stage of pathway 1. Moreover, the S atom leans towards the hydroxyl H, pushing the cation holding it across the [110] direction. The charge analysis shows a rearrangement of 0.4 e<sup>-</sup> involving the O atom as acceptor and the replaced S as donor. The adsorbed S atom is 1.0 e<sup>-</sup> more negative than the SH in pathway 1, which also explains its higher nucleophilicity. **Figure 6.4** shows the charge density difference plot for this stage, where it is possible to localize the charge around the adsorbed S. The energy of this state is 0.15 eV lower than the reference system, contrarily to 0.10 eV higher in pathway 1. Moreover, the activation energy required to take our system from state 2 to 4 is 0.17 eV lower than in pathway 1. The higher thermodynamic and kinetic tendency of our system to undergo the exchange step in pathway 2 is related with the absence of one water H and hence a more negatively charged hydroxyl O, which prefers higher coordination.

The next step along the oxidation process is the formation of the SH group. The protonated S moves 2.22 Å nearly straight atop the Fe<sub>B</sub> ion, which relaxes to its original position within the atomic row along the [110] direction, see state 6 on **Figure 6.5** and **Table 6.2**. At this stage, the S–H bond length is equal to the one in the states



4 and 6 of pathway 1. Once the SH is formed, the O atom has moved horizontally along the [110] direction and 0.11 Å vertically towards the surface. An analysis of the charges reveals that after OH dissociation, the O atom together with the top Fe ions lose 0.5  $e^-$  overall, which is supplied to the S–H bond. The charge density difference representation, shown in **Figure 6.4**, illustrates the charge distribution after the SH formation onto the partially oxidized Fe<sub>3</sub>S<sub>4</sub>(001) surface. The OH dissociation process is endothermic (by 0.79 eV) and kinetically unfavourable, becoming the rate limiting step, which is determined by the O nucleophilicity. Thus, the O atom prefers to sit at the S place and retain the H, leaving the surface hydroxylated. The net energy change of the O–H dissociation is more endothermic and with higher activation energy than the second dissociation in pathway 1 by 0.34 and 0.70 eV respectively.

In the final step of pathway 2, the SH group interacts with a co-adsorbed H atom, leading to the formation and desorption of the H<sub>2</sub>S molecule. This leaves a partially oxidized surface slab identical to the one obtained after the solid state diffusion of pathway 1. We could also consider a variation of pathway 2, where the exchange of S by O takes place after the OH dissociation, see **Figure 6.5**. Nevertheless, the energies of the stationary states are higher than in the suggested pathway. Therefore, we do not describe the stationary points of this alternative mechanism as it is highly unlikely to be the one leading to the (001) surface oxidation.

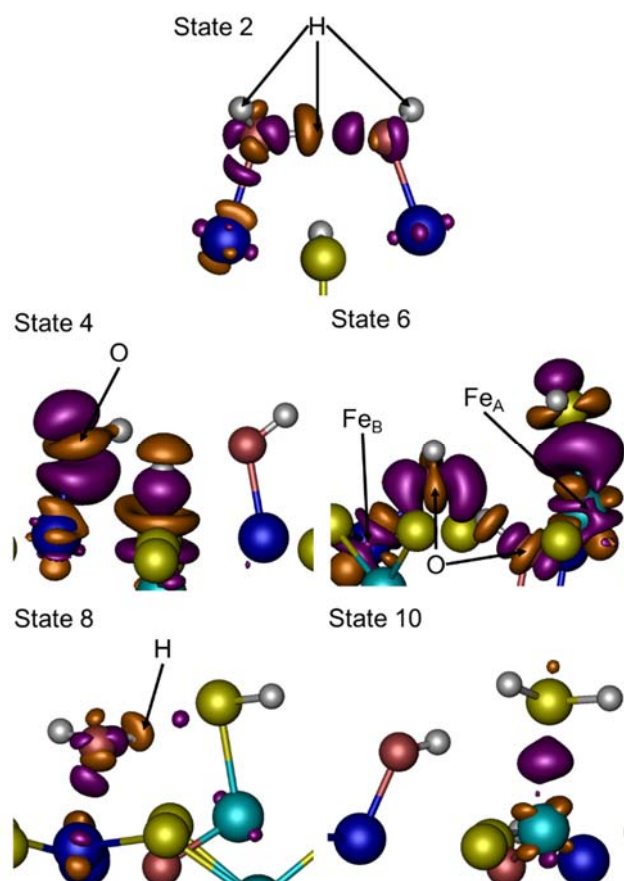


**Figure 6.5.** (a) Schematic representation and (b) reaction profile for the oxidation of the  $\text{Fe}_3\text{S}_4(001)$  surface via pathway 2 (the red dashed line represents a variation of pathway 2 in which OH dissociation takes place first). Insets show side and top view of the structure of the numbered states. Only the surface and species adsorbed to it are shown. Light blue atoms represent  $\text{Fe}_A$ , dark blue for  $\text{Fe}_B$ , yellow for S, red for O and white for H.

### 6.3.3 Pathway 3

We next investigated the effect of an extra  $\text{H}_2\text{O}$  molecule (0.50 ML) on the oxidation mechanism, see **Figures 6.7** and **6.8**. Previous works on  $\text{Fe}_3\text{S}_4$  and the analogue spinel  $\text{FeNi}_2\text{S}_4$  suggested that the adsorption of a second  $\text{H}_2\text{O}$  molecule after dissociation of the first one is most likely to take place on the surface  $\text{Fe}_B$  ion next to the protonated S, see state 2 on **Figure 6.8** and **Table 6.3** (Haider *et al.*, 2014; Roldan and de Leeuw, 2015). As a result of the interaction with the surface, the bond angle of the newly added  $\text{H}_2\text{O}$  molecule is increased to  $108.1^\circ$ , with respect to the  $104.7^\circ$  calculated for the isolated molecule, which is in excellent agreement with the value obtained from microwave spectroscopy (Harmony *et al.*, 1979). The O of the second  $\text{H}_2\text{O}$  molecule is at  $2.14 \text{ \AA}$  from the  $\text{Fe}_B$  ion and its O–H distances are  $0.97$  and  $1.04 \text{ \AA}$ . While the shortest OH bond distance indicates no bond alteration (Harmony *et al.*, 1979), the elongated one is orientated towards the O atom of the neighbour OH group, forming a hydrogen bond of  $1.56 \text{ \AA}$ . This makes both adsorbates,  $\text{H}_2\text{O}$  and OH, to be slightly bent with respect to the surface. Apart from the  $0.10 \text{ \AA}$  elongation induced to the Fe–OH bond, the structure of the dissociatively adsorbed  $\text{H}_2\text{O}$  molecule remains essentially the same than in pathway 1, see **Table 6.3**. We found that the addition of a second  $\text{H}_2\text{O}$  molecule stabilizes the system by  $0.56 \text{ eV}$  with regard to the reference system of two isolated  $\text{H}_2\text{O}$  molecules and the pristine slab, see **Figure 6.8**. The charge density difference of the molecularly adsorbed  $\text{H}_2\text{O}$  with respect to the slab containing the dissociatively adsorbed  $\text{H}_2\text{O}$  indicates the electronic density relocation between the  $\text{Fe}_B$  and the second  $\text{H}_2\text{O}$  together with the hydrogen bond formation, see state 2 in **Figure 6.6**. The charge analysis reveals that after the molecular adsorption, the

hydrated  $\text{Fe}_B$  ion together with both O atoms release altogether  $2.0 e^-$  which are supplied to the  $\text{H}_2\text{O}$  molecule.



**Figure 6.6.** Charge density difference plot of the adsorption at different stages along the oxidation of the  $\text{Fe}_3\text{S}_4(001)$  surface following pathway 3. Isosurfaces of the difference density are displayed at a value of  $\pm 0.05 e^- \text{\AA}^{-3}$ , where purple and orange represent gain and lost electron density respectively. Light blue atoms represent  $\text{Fe}_A$ , dark blue for  $\text{Fe}_B$ , yellow for S, red for O and white for H.

**Table 6.3.** Calculated bond distances (Å) and angles (°) at different minima states along the  $Fe_3S_4(001)$  surface oxidation following pathway 3.

state	2	4	6	8	10	11	13
$d(O_1-Fe_{B1})$	1.93	1.83	1.91	2.13	1.84	1.80	1.83
$d(O_2-Fe_{B2})$	2.14	1.85	--	--	--	--	--
$d(S_2-Fe_A)$	--	--	2.23	2.27	2.45	--	--
$d(H_1-O_1)$	0.97	0.98	0.97	0.98	0.98	0.99	0.97
$d(H_2-S_1)$	1.38	1.35	1.35	1.36	1.36	1.36	1.36
$d(H_3-O_2)$	1.04	0.97	1.09	--	--	--	--
$d(H_3-S_2)$	--	--	--	--	1.35	--	--
$d(H_3-O_1)$	--	--	--	1.01	--	--	--
$d(H_4-O_2)$	0.97	--	--	--	--	--	--
$d(H_4-S_2)$	--	1.37	1.35	1.35	1.35		
$d(H_1 \cdots O_2)$	--	--	--	--	--	1.77	--
$d(H_3 \cdots O_1)$	1.56	2.53	1.38	--	--	--	--
$d(H_3 \cdots S_2)$	--	--	--	2.20	--	--	--
$\angle H_1-O_1-H_3$	--	--	--	104.3	--	--	--
$\angle H_3-O_2-H_4$	108.1	--	--	--	--	--	--
$\angle H_3-S_2-H_4$	--	--	--	--	92.7	--	--

In order to generate a second SH group within close proximity to a subsurface  $Fe_A$  ion the dissociation of the molecular  $H_2O$  takes place, see state 4 in **Figure 6.8**. Hence, the two SH groups are bridging both hydroxylated  $Fe_B$  ions, which is a configuration similar to the one found on  $FeNi_2S_4$  (Haider *et al.*, 2014). We could also consider that this dissociation takes place towards the protonated S ion, but as we showed on pathway 1,  $H_2S$  is unstable near a co-adsorbed OH as it is more basic. Hence, the new

S–H bond is nearly perpendicular to the surface and has the same bond length than the existing one, see **Table 6.3**. Likewise, the two now similarly spaced FeO bonds are more parallel than in the OH–H<sub>2</sub>O co-adsorbed state, stretching the hydrogen bond by 0.97 Å. The weakening of the long-range hydrogen bond between the two OH groups is also expressed by the reduction of their intra bond length. The configuration with two adsorbed OH groups and two surface SH is 1.50 eV less stable than the OH–H<sub>2</sub>O co-adsorbed state which is reached after the system overcomes an energy barrier of 1.70 eV. The charge analysis shows that dissociation of the second H<sub>2</sub>O molecule is accompanied by the reduction of its charge by 0.9  $e^-$ , while the S and Fe<sub>B</sub> ions binding the dissociation products increased their charge by the same amount. The localization of charge between the S and H atoms and between the Fe<sub>B</sub> and OH group as well as the weakening of the hydrogen bond can be seen graphically in the charge density difference plot, see state 4 in **Figure 6.6**.

The protonated S binding the subsurface Fe<sub>A</sub> is the one most likely to be exchanged by an OH, see state 6 in **Figure 6.8**. After the exchange, the SH group is adsorbed at 2.23 Å from the Fe<sub>A</sub> ion, see **Table 6.3**, which has also migrated outwards the surface by 1.23 Å occupying a free neighbour octahedral position. At this point, it is worth noting that 1/3 of the top Fe<sub>A</sub> ions have high lability to move outward as their bulk-like position before relaxation of the pristine surface was just above the top S layer (Roldan and de Leeuw, 2015). The hydroxyl introduced on the Fe<sub>3</sub>S<sub>4</sub> surface, like in the two previously proposed pathways, lies at 0.47 Å below the topmost atomic layer. While the S–H bond length is the same for the two SH groups, the O–H distance of the mineralized OH group is 0.12 Å larger than the one of the adsorbed OH. The

OH $\cdots$ OH distance of 1.38 Å indicates a hydrogen bond between these OH groups. The adsorbed OH group is, in turn, tilted towards the mineralized OH, which results in a 0.08 Å increase of the Fe<sub>B</sub>–O distance. The absolute value of the energy released during the exchange step (1.00 eV), together with the activation energy (1.25 eV), are the largest of the three pathways we have studied for the oxidation of the Fe<sub>3</sub>S<sub>4</sub>(001). The charge analysis indicates a rearrangement of charges (quantified as 0.8 e<sup>-</sup>) from the adsorbed OH group and the labile Fe<sub>A</sub> ion to the mineralized OH and the cleared Fe<sub>B</sub>, which can be seen graphically in the charge density difference plot of state 6 in **Figure 6.6**. This figure illustrates the localization of charge between the adsorbed OH and SH groups and the Fe ions binding them and between the mineral and adsorbed OH groups, corroborating their strong interaction.

In the next step takes place the formation a co-adsorbed H<sub>2</sub>O molecule from the adsorbed OH, which receives the H atom from the mineralized OH group, see state 8 in **Figure 6.8**. This process requires 0.33 eV after overcoming an activation energy barrier of 0.36 eV, making it the less demanding step in this study, perhaps due to the equal nature of the donor and acceptor atoms. After the H migration step, the surface O atom moves inward by 0.09 Å while the H<sub>2</sub>O elongates 0.22 Å its distance with the Fe<sub>B</sub>, lying almost as an isolated molecule (Harmony *et al.*, 1979), see **Table 6.3**. The H<sub>2</sub>O is tilted towards the adsorbed SH group, establishing a weak hydrogen bond,  $d(\text{HOH}\cdots\text{SH}) = 2.20$  Å. The charge analysis reveals that after the H<sub>2</sub>O formation step, the migrating H and the mineral O ion have regained 0.8 e<sup>-</sup> and that 79% of it was drawn from the adsorbed OH group. The charge density difference plot of the adsorbed H<sub>2</sub>O molecule with respect to the partially oxidized surface with both SH groups, see

state 8 in **Figure 6.6**, illustrates the localization of electronic density in the H<sub>2</sub>O–Fe<sub>B</sub> bond as well as in the HOH···SH hydrogen bond.

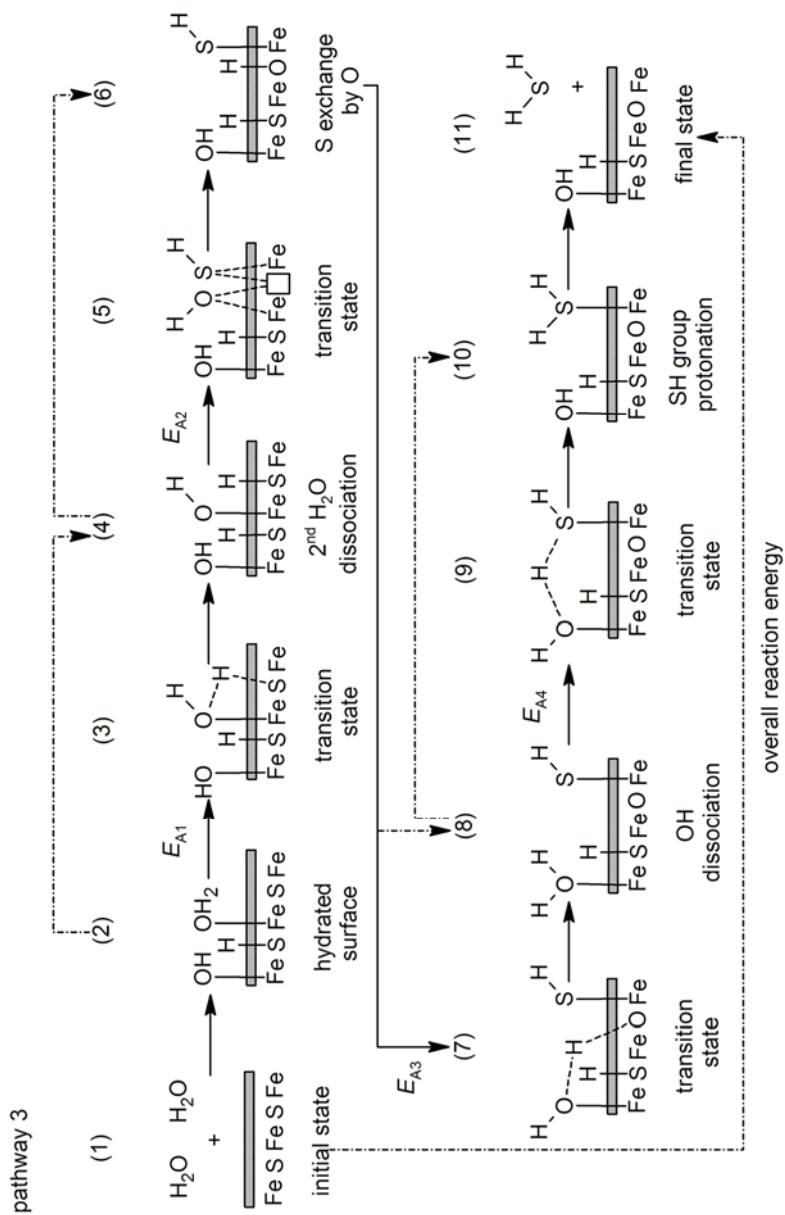
In the final step of the H<sub>2</sub>S formation, one of the H atoms from the H<sub>2</sub>O migrates to the SH group, see state 10 in **Figure 6.8**. This process is endothermic by 0.47 eV and its transition state has an energy barrier of 1.09 eV in agreement with their relative pK<sub>a</sub>. At this stage, the S of the H<sub>2</sub>S molecule moves 0.18 Å outwards and the Fe<sub>B</sub>–O distance is reduced by 0.29 Å, see **Table 6.3**. The calculated bond angle of the adsorbed H<sub>2</sub>S molecule is 92.7° and the two S–H bond distances are 1.35 Å. This geometry is very close to the one calculated for the isolated molecule (92.1° and 1.35 Å respectively) and found from microwave spectroscopy (92.1° and 1.34 Å respectively) (Harmony *et al.*, 1979). These results highlight the weak interaction between the H<sub>2</sub>S molecule and the partially oxidized surface. The charge analysis shows that after H<sub>2</sub>S formation, the migrating H leaves behind 0.7 e<sup>-</sup>, which results in the decrease of the charge of the adsorbed OH group and the increase of the charge of the SH group. The state 10 of **Figure 6.6** shows the charge density difference plot of the H<sub>2</sub>S molecule with respect to the partially oxidized surface containing the dissociated H<sub>2</sub>O, where we can notice a higher charge localization between H<sub>2</sub>S and the Fe<sub>A</sub> than in the state 6 of pathway 1 (**Figure 6.2**).

Desorption of the H<sub>2</sub>S molecule requires an energy of 0.74 eV, see state 11 in **Figure 6.8**. The release of the H<sub>2</sub>S molecule is accompanied by the formation of a hydrogen bond (at 1.77 Å) between the OH group and the mineral O atom, see **Table 6.3**. Nevertheless, the impact on the structure is minimal. A Bader analysis of the charges

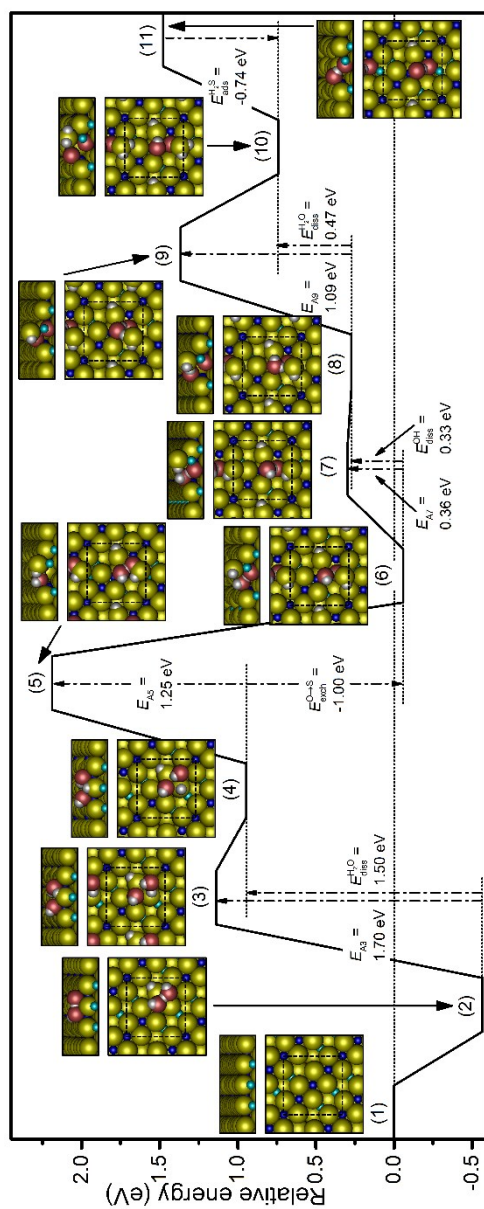


reveals that after H<sub>2</sub>S desorption, the mineral O atom has donated 0.2  $e^-$  of negative charge and that 50% of it was taken by the H<sub>2</sub>S molecule.

Unlike in pathways 1 and 2, the presence of the adsorbed OH group and the labile Fe<sub>A</sub> that moved to an octahedral site, makes the most stable oxidation product to be found when the mineral O diffuses and takes the place of the neighbour S on the same row of the  $[\bar{1}\bar{1}0]$  direction. This process further stabilizes the surface by a 0.40 eV, which is nearly 3 times more exothermic than the diffusion process of pathway 1. However, the barrier of the transition state in pathway 3 is 6.6 times higher than in pathway 1, making this solid state transformation step much less likely than in pathway 1. In the final configuration, the O is at 0.44 Å below the level of the surface atomic layer, which is comparable with the outcome of the previously discussed pathways. There is, however, a lasting impact of the oxidation through the last mechanism on the position of the labile Fe<sub>A</sub> ion, which remains in the octahedral cavity. The charge analysis indicates that the Fe<sub>A</sub> and Fe<sub>B</sub> ions coordinating the O have altogether lost 0.6  $e^-$ , a charge that was given to the same type of atoms coordinated to the O atom prior to its diffusion.



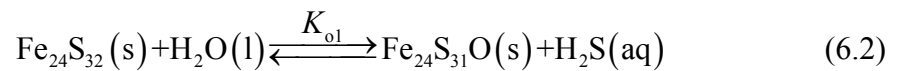
**Figure 6.7.** Schematic representation of the oxidation of the  $\text{Fe}_3\text{S}_4(001)$  surface via pathway 3. Only the surface and species adsorbed to it are shown.



**Figure 6.8.** Reaction profile for the oxidation of the  $\text{Fe}_3\text{S}_4(001)$  surface via pathway 3. Insets show side and top view of the structure of the numbered states. Only the surface and species adsorbed to it are shown. Light blue atoms represent Fe<sub>A</sub>, dark blue for Fe<sub>B</sub>, yellow for S, red for O and white for H.

### 6.3.4 Thermodynamics of H<sub>2</sub>S and its ionization products in aqueous solution

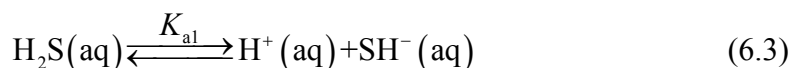
Because of the interest in preventing the H<sub>2</sub>S release from iron-sulfur compounds, and hence the acid mine drainage, we investigated the equilibrium concentration of these species in aqueous solution. We have calculated the concentration of aqueous H<sub>2</sub>S from the oxidation of the Fe<sub>3</sub>S<sub>4</sub>(001) surface and the pH of this solution as a function of temperature, in the range from 293 to 373 K. In order to calculate the concentrations of the species in aqueous solution in equilibrium with the pristine and partially oxidized Fe<sub>3</sub>S<sub>4</sub>(001) surfaces, we considered the process of partial oxidation of this surface by a H<sub>2</sub>O molecule, according to the following equation:



where the equilibrium constant ( $K_{o1}$ ) is equal to the [H<sub>2</sub>S] in equilibrium with the solid phases.

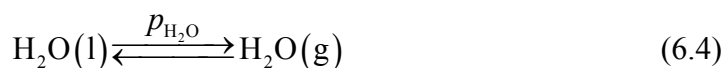
H<sub>2</sub>S is a diprotic acid with two dissociation steps. The ionization constant of the first dissociation, represented by equation (6.3), is written as  $K_{a1} = [\text{H}^+] \cdot [\text{SH}^-] \cdot [\text{H}_2\text{S}]^{-1}$  and its dependence with T at saturated water vapour pressure is shown in **Table 6.4**. We do not consider the second dissociation of H<sub>2</sub>S as its constant  $K_{a2}$  (Suleimenov and Seward, 1997) is at least 8 orders of magnitude smaller than  $K_{a1}$  (Giggenbach, 1971) for the range of temperature considered. We are also ignoring the autodissociation of H<sub>2</sub>O as its ionic product,  $K_w$ , is also at least 6 orders of magnitude smaller than  $K_{a1}$  in the range of temperatures of interest (Haynes, 2012). Consequently, the [H<sup>+</sup>] is

controlled by the first dissociation of H<sub>2</sub>S and the contribution of H<sup>+</sup> from the other processes is negligible.

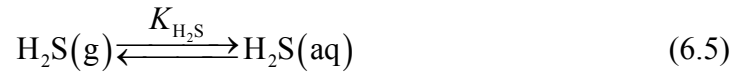


In order to link the gas phase state of the isolated molecules in our DFT simulations with the states in equation (6.2), we have considered the vapour pressure of H<sub>2</sub>O in equilibrium with its condensed phase and the solubility of gaseous H<sub>2</sub>S in water.

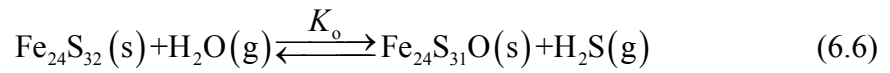
The vapour pressure is the partial pressure of a given gas above which, at constant temperature, the substance is going to condense into the liquid phase. This saturation property is a function of temperature and its empirical expression for H<sub>2</sub>O is represented in **Table 6.4** ( $p_{\text{H}_2\text{O}}$ ) while the equilibrium of H<sub>2</sub>O between its liquid and gas states is shown in equation (6.4). This property increases with temperature and when it equals the total external pressure, the compound starts to boil.



The solubility of a given gas in a given liquid is controlled by the Henry constant. This constant is a coefficient of proportionality between the partial pressure of the gas and the amount of it that can be dissolved in a given volume of the solvent at constant temperature. The Henry constant also depends on the temperature and the empirical expression for the solubility of H<sub>2</sub>S in H<sub>2</sub>O is represented in **Table 6.4** ( $K_{\text{H}_2\text{S}}$ ), while the equilibrium can be written as equation (6.5) and the equilibrium constant is  $K_{\text{H}_2\text{S}} = [\text{H}_2\text{S}] \cdot p_{\text{H}_2\text{S}}^{-1}$ .



The combination of equations (6.2), (6.4) and (6.5), leads to the reaction of the partial oxidation of Fe<sub>3</sub>S<sub>4</sub>(001) surface where H<sub>2</sub>O and H<sub>2</sub>S are in the reference state of our DFT calculations:



**Table 6.4.** Empirical expressions for the first ionization constant of  $H_2S$  ( $K_{a1}$ ), vapour pressure of  $H_2O$  ( $p_{H_2O}$ ) and Henry constant of  $H_2S$  ( $K_{H_2S}$ ) as a function of the absolute temperature.

equation for constant	units of constant
$\lg(K_{a1}) = a_1 + a_2T + a_3T^2 + a_4T^{-1} + a_5 \ln(T)$ $a_1 = 782.43945 \quad a_4 = -20565.7315$ $a_2 = 0.361261 \quad a_5 = -142.741722$ $a_3 = -1.6722 \cdot 10^{-4}$	molality <sup>A</sup>
$\ln(p_{H_2O}) = \frac{T_c}{T} [b_1\tau + b_2\tau^{1.5} + b_3\tau^3 + b_4\tau^{3.5} + b_5\tau^4 + b_6\tau^{7.5}] + \ln(p_c)$ $T_c = 647.096 \text{ K} \quad b_2 = 1.84408259$ $p_c = 2.2064 \cdot 10^7 \text{ Pa} \quad b_3 = -11.7866497$ $\tau = 1 - \theta \quad b_4 = 22.6807411$ $\theta = \frac{T}{T_c} \quad b_5 = -15.9618719$ $b_1 = -7.85951783 \quad b_6 = 1.80122502$	Pa <sup>B</sup>
$\lg(K_{H_2S}) = c_1 + c_2T + c_3T^2 + c_4T^{-1} + c_5 \lg(T)$ $c_1 = -0.6342702616 \cdot 10^3 \quad c_4 = 0.1671907660 \cdot 10^5$ $c_2 = -0.2709284796 \quad c_5 = 0.2619219571 \cdot 10^3$ $c_3 = 0.1113202904 \cdot 10^{-3}$	molality/bar <sup>C</sup>

<sup>A</sup> Suleimenov and Seward (1997)

<sup>B</sup> Wagner and Pruss (1993)

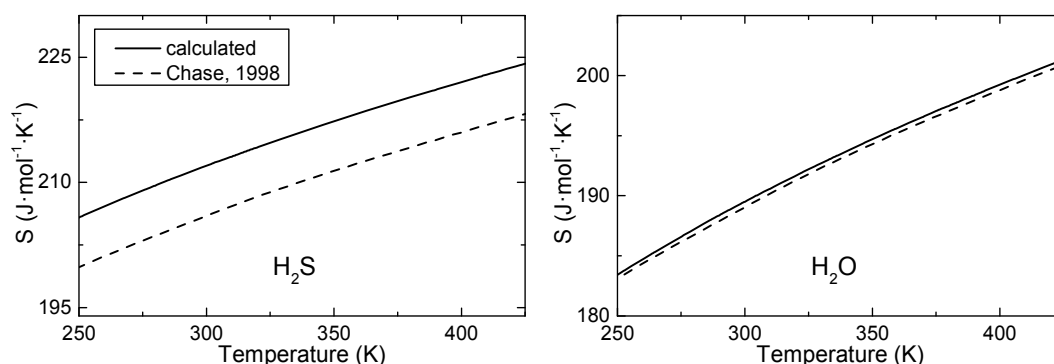
<sup>C</sup> Suleimenov and Krupp (1994)

$K_o$  is then calculated as shown in equation (6.7), from the Gibbs free energy ( $G$ ) of the partial oxidation of the  $Fe_3S_4(001)$  surface, where  $R$  and  $T$  are the ideal gas constant and the temperature of interest respectively.

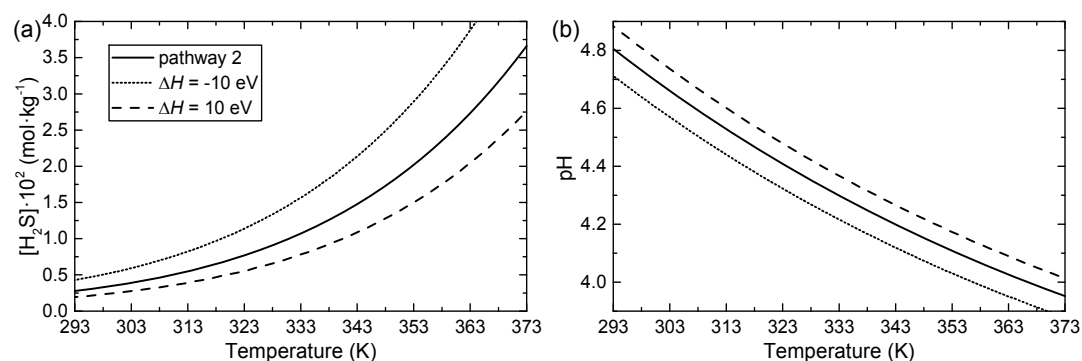
$$K_o = \frac{p_{H_2S}}{p_{H_2O}} = \frac{K_{o1}}{K_{H_2S} \cdot p_{H_2O}} = e^{-\Delta G^\ominus / RT} \quad (6.7)$$

The change in the standard Gibbs free energy ( $\Delta G^\ominus$ ) for the partial oxidation of the Fe<sub>3</sub>S<sub>4</sub>(001) surface according to equation (6.7) was calculated from  $\Delta G^\ominus = \Delta H^\ominus - T\Delta S^\ominus$ , where  $\Delta H^\ominus$  is the enthalpy of this process, per H<sub>2</sub>S molecule formed,  $\Delta S^\ominus$  is the change in entropy and  $T$  is the temperature. The enthalpies for the initial oxidation of the (001) surface according to the three pathways investigated in this study are obtained directly from our calculations assuming that their values, strictly calculated at  $T = 0$  K, will not depend appreciably on the temperature. We additionally assumed that the entropies of the solid phases remain largely unchanged through the oxidation reaction and that only the change in entropy due to the replacement of one of the gaseous H<sub>2</sub>O by one H<sub>2</sub>S molecule is necessary to take into account. Similar considerations have been used to explain the dehydration of a number of  $\alpha$ -FeO(OH) and  $\alpha$ -Fe<sub>2</sub>O<sub>3</sub> surfaces (de Leeuw and Cooper, 2007) and the dissolution/nucleation process at the  $\alpha$ -quartz (0001) surface in liquid H<sub>2</sub>O (Du and de Leeuw, 2006). We have used the entropies of H<sub>2</sub>O and H<sub>2</sub>S calculated at different temperatures using statistical thermodynamics (Dzade *et al.*, 2013; Roldán *et al.*, 2010; Stoltze, 2000). For the range of temperature between 250 and 425 K, the maximum error between the calculated and previously reported (Chase, 1998) entropy are 2.8 and 0.3 % for H<sub>2</sub>S and H<sub>2</sub>O respectively, see **Figure 6.9**. Combining  $K_0$  with  $K_{\text{H}_2\text{S}}$  and  $p_{\text{H}_2\text{O}}$ , as shown in equation (6.7), it is possible to determine the reaction constant  $K_{01}$  and therefore [H<sub>2</sub>S] and the pH as a function of the temperature when H<sub>2</sub>O is in the liquid state and H<sub>2</sub>S is dissolved in water.





**Figure 6.9.** Comparison of the entropy as a function of temperature reported by Chase (1998) and calculated using statistical thermodynamics for gaseous  $\text{H}_2\text{S}$  and  $\text{H}_2\text{O}$ .



**Figure 6.10.** Calculated dependence of (a)  $[\text{H}_2\text{S}]$  and (b) pH with respect to  $T$  for the partial oxidation of the  $\text{Fe}_3\text{S}_4(001)$  surface following pathway 2. The dotted and dashed lines are added for comparison purposes and they represent processes with  $\Delta H^\ominus = -10$  and  $10$  eV respectively.

The partial oxidation of the  $\text{Fe}_3\text{S}_4(001)$  surface in a wet environment, represented by the concentration of  $\text{H}_2\text{S}$  as a function of the temperature, is shown in **Figure 6.10 (a)**. This graph only shows the curve associated with pathway 2 ( $\Delta H^\ominus = -0.92$  eV), which is the most kinetically and thermodynamically favourable, since the curves related with the rest of the pathways are almost coincident with this. As expected of an

endothermic process, the increment of temperature brings an exponential increase of the concentration of products: [H<sub>2</sub>S] is equal to  $2.77 \cdot 10^{-3} \text{ mol} \cdot \text{kg}^{-1}$  at  $T = 293 \text{ K}$  and  $3.65 \cdot 10^{-2} \text{ mol} \cdot \text{kg}^{-1}$  at  $T = 393 \text{ K}$ . **Figure 6.10 (b)** shows how the pH decreases with temperature as it is also expected from a solution with an increasing concentration of a weak acid. In **Figure 6.10 (a)** and **(b)**, we have also added two auxiliary lines showing the behaviour of hypothetical pathways whose  $\Delta H^\ominus$  are  $\pm 10$  times bigger than pathway 2. These lines illustrate how noticeably the enthalpy of the process affects the dependence of [H<sub>2</sub>S] and pH with  $T$ . Since the pH is always below 4.81 in the range of temperatures from 293 K to 373 K and large Fe<sub>3</sub>S<sub>4</sub> deposits are present in aquatic environments, from our calculations it would appear that this mineral deposits could be significant contributors to acid mine drainage.

## 6.4 Chapter conclusions

In this paper, we have proposed and modelled three different pathways for the early steps of the oxidation of the Fe<sub>3</sub>S<sub>4</sub>(001) surface promoted by H<sub>2</sub>O. We used DFT methods with a Hubbard Hamiltonian and empirical long-range dispersion corrections to optimize the geometry of any intermediate in the thermodynamic and kinetic energy profile. In each of these mechanisms, one surface S atom is replaced by an O atom from H<sub>2</sub>O, producing one H<sub>2</sub>S molecule. We found that the step where the OH group replaces the S atom always take place before the OH losses its H atom. However, for the pathway 2, we could model the alternative reaction route and we found that all intermediates were between 1.56 and 0.37 eV higher in energy than in the OH

mineralization mechanism, which agrees with suggested mechanisms on sulfides. We have found that pathways 1 and 2 are the most effective routes to initiate the oxidation of the Fe<sub>3</sub>S<sub>4</sub>(001) surface. Although in pathway 1 the total  $\Delta H^\ominus$  (per H<sub>2</sub>S molecule formed) is 0.14 eV higher than in pathway 2, the rate-determining step in pathway 1 is 0.41 eV smaller than in pathway 2. The presence of the dissociated H<sup>+</sup> from the H<sub>2</sub>O on the vicinities of the reactive site on pathway 1 directs the oxidation reaction towards a kinetic product where the exchange of S by O becomes the step with highest activation energy. On the other hand, as the dissociated H<sup>+</sup> is absent from the vicinities of the reactive site on pathway 2, the oxidation product obtained directly is the most thermodynamic favourable and the O–H dissociation step becomes the rate-limiting one. When two H<sub>2</sub>O molecules are adsorbed around the reactive centre, pathway 3, they direct the oxidation reaction to a kinetic product, which is 0.42 eV higher in energy than the one obtained in pathway 1. Moreover, the highest activation energy calculated in this study is associated with the dissociation of the second H<sub>2</sub>O molecule in pathway 3, making it unlikely. The calculated [H<sub>2</sub>S] in aqueous solution, and therefore pH, in chemical equilibrium with the solid phases at a range of temperatures, show that Fe<sub>3</sub>S<sub>4</sub> may be amongst those minerals responsible for the AMD.

## Conclusions and future works

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### 7.1 Conclusions

We have presented a computational study of the inversion thermodynamics, the electronic and magnetic properties of  $\text{FeM}_2\text{X}_4$  (thio)spinel; the mechanical and surface redox properties of  $\text{Fe}_3\text{O}_4$  as well as the oxidation of the  $\text{Fe}_3\text{S}_4(001)$  surface, using first principles methods based on the density functional theory.

The thermodynamic inversion degree determined for the  $\text{FeM}_2\text{X}_4$  (thio)spinel at temperatures used typically in their synthesis agrees reasonably well with the experimental evidence, wherever this exists. The analysis of the configurational free energies showed that different behaviors are expected for the equilibrium cation distributions in these structures:  $\text{FeCr}_2\text{X}_4$  and  $\text{FeMn}_2\text{S}_4$  are fully normal,  $\text{FeNi}_2\text{X}_4$  and  $\text{FeCo}_2\text{S}_4$  are intermediate, and  $\text{FeCo}_2\text{O}_4$  and  $\text{FeMn}_2\text{O}_4$  are fully inverted. We also found that  $\text{FeMn}_2\text{O}_4$  presents a metastable intermediate inversion degree, which may be kinetically controlled. We found that none of the factors analyzed, *i.e.* the size of the ions and the crystal field stabilization effects, play a significant role in determining the equilibrium inversion degree of these compounds. We discussed how the electronic and magnetic structure of these spinels is modified by the degree of inversion, assuming that this could be varied from the equilibrium value. We obtained

electronic densities of states for the completely normal and completely inverse cation distribution of each compound.  $\text{FeCr}_2\text{X}_4$ ,  $\text{FeMn}_2\text{X}_4$ ,  $\text{FeCo}_2\text{O}_4$  and  $\text{FeNi}_2\text{O}_4$  are half-metals in the ferrimagnetic state when Fe is in tetrahedral positions. When  $M$  is filling the tetrahedral positions, the Cr containing compounds and  $\text{FeMn}_2\text{O}_4$  are half-metallic systems, while the Co and Ni spinels are insulator. The Co and Ni sulfide counterparts are metallic for any inversion degree together with the inverse  $\text{FeMn}_2\text{S}_4$ . Our calculations suggest that the spin filtering properties of the  $\text{FeM}_2\text{X}_4$  (thio)spinel could be modified via the control of the cation distribution by the synthesis conditions.

We investigated the elastic constants and other macroscopic properties of  $\text{Fe}_3\text{O}_4$  by applying elastic strains on the unit cell of this compound. The calculated properties are shown to be in excellent agreement with experiments. The comparison of the mechanical properties calculated for  $\text{Fe}_3\text{O}_4$  with those reported for its sulfide counterpart  $\text{Fe}_3\text{S}_4$  indicates that the oxide is harder than the sulfide, but less liable to fracture. The mechanical properties also showed that the Fe–O interaction is more ionic in  $\text{Fe}_3\text{O}_4$  than the Fe–S interaction in  $\text{Fe}_3\text{S}_4$ .

We have studied the geometries and surface free energies of a number of surfaces of  $\text{Fe}_3\text{O}_4$  at different compositions, including the stoichiometric plane, and those with a deficiency or excess of oxygen atoms. The most stable surfaces are the (001) and (111), leading to a cubic  $\text{Fe}_3\text{O}_4$  crystal morphology with truncated corners under equilibrium conditions. The scanning tunnelling microscopy images of the different terminations of the (001) and (111) stoichiometric surfaces were calculated. The  $\text{Fe}_3\text{O}_4$  morphology, together with the STM images of the surfaces expressed in it, were compared with

previous reports and found to be in excellent agreement with them. Our calculations showed that under reducing conditions, the creation of oxygen vacancies in the surface leads to the formation of reduced Fe species in the surface in the vicinity of the vacant oxygen. The (001) surface is slightly more prone to reduction than the (111), due to the higher stabilisation upon relaxation of the atoms around the oxygen vacancy, but molecular oxygen adsorbs preferentially at the (111) surface. In both oxidized surfaces, the oxygen atoms are located on bridge positions between two surface iron atoms, from which they attract electron density. The oxidised state is thermodynamically favourable with respect to the stoichiometric surfaces under ambient conditions, although not under the conditions when bulk  $\text{Fe}_3\text{O}_4$  is thermodynamically stable with respect to  $\text{Fe}_2\text{O}_3$ . This finding is important in the interpretation of the catalytic properties of  $\text{Fe}_3\text{O}_4$  due to the presence of oxidised species under experimental conditions.

Finally, we have investigated the replacement of one sulfur (forming  $\text{H}_2\text{S}$ ) by one oxygen atom (provided by  $\text{H}_2\text{O}$ ) at the  $\text{Fe}_3\text{S}_4(001)$  surface. We have proposed three pathways for the oxidation of this surface at different levels of  $\text{H}_2\text{O}$  coverage. One or two  $\text{H}_2\text{O}$  molecules on this surface give different intermediate oxidation products followed by diffusion of the introduced O atom towards the most stable position, while the OH group gives the thermodynamic product directly. Low levels of  $\text{H}_2\text{O}$  coverage seems to be essential to give the overall most favourable energetic landscape for the oxidation of the  $\text{Fe}_3\text{S}_4(001)$  surface. When the concentration of  $\text{H}_2\text{S}$  and  $\text{H}^+$ , in aqueous solution and thermodynamic equilibrium with the stoichiometric and partially oxidized  $\text{Fe}_3\text{S}_4(001)$  surface, is plotted against the temperature, taking into account

statistical entropies calculated for H<sub>2</sub>S and H<sub>2</sub>O and other experimental parameters, it appears that this mineral may well be among those responsible for the generation of acid mine drainage when it is exposed to weathering conditions.

The research presented in this thesis has provided a theoretical rationalization for a number of known structural, bulk and surface properties of Fe<sub>3</sub>O<sub>4</sub> and related spinel-structured materials. We have also postulated a theoretical spinel structure for FeMn<sub>2</sub>S<sub>4</sub> and FeCo<sub>2</sub>S<sub>4</sub> and predicted their equilibrium inversion degree and electronic and magnetic properties.

## **7.2 Future works**

Having investigated the inversion thermodynamics of the FeM<sub>2</sub>X<sub>4</sub> spinel-structured materials, where we proposed a theoretical spinel structure for FeMn<sub>2</sub>S<sub>4</sub> and FeCo<sub>2</sub>S<sub>4</sub>, we would like now to further this research by studying the mixing thermodynamics in Fe/Co and Fe/Mn thiospinels. We would also like to extend the investigation of the surface properties of Fe<sub>3</sub>O<sub>4</sub> by studying the interaction of its low index surfaces with small molecules such as H<sub>2</sub>O and CO<sub>2</sub>, with the final aim of modelling the surface carbonation and CO<sub>2</sub> conversion. A final direction for future research stemming from this thesis is the simulation of the oxidation of the rest of the low index surfaces of Fe<sub>3</sub>S<sub>4</sub>, considering O<sub>2</sub> and a mixture of O<sub>2</sub> and H<sub>2</sub>O as oxidants.

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