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Departamento de Estadística y Econometria
Universidad Carlos III de Madrid
Caile Madrid, 126
28903 Getafe (Spain)
Fax (34)91 624-9849

# ASYMPTOTIC AND BOOTSTRAP SPECIFICATION TESTS OF NONLINEAR IN VARIABLES ECONOMETRIC MODELS. 

Miguel A. Delgado, Manuel A. Domínguez and Pascal Lavergne*


#### Abstract

We address the issue of consistent specification testing in general econometric models defined by multiple moment conditions. We develop two classes of moment corditions based tests. The first class of tests depends upon nonparametric functions that are estimated by kernel smoothers. The second class of tests depends upon a marked empirical process. Asymptotic and bootstrap versions of these tests are formally justified, and their finite sample performances are investigated by means of Monte-Carlo experiments.


Keywords:
Specification testing; Nonlinear in variable models; Smoothers; Marked empirical processes; Wild bootstrap.
*Delgado, Departamento de Estadística y Econometría, Universidad Carlos III de Madrid. C/ Madrid, 12628903 Madrid. Spain. Ph: 34-1-624.98.04; Fax: 34-1-624.98.49, e-mail: delgado@est-econ.uc3m.es; Dominguez, Departamento de Estadística y Economtería, Universidad Carlos III de Madrid; Lavergne, INRA-ESR, BP 27, 31326 Castanet-Tolosan Cedex Toulouse, France. This work was done while the third author was visiting Universidad Carlos III, Madrid.Financial support from the European Commission under grant SBR-9631212 and from the Spanish Dirección General de Esneñanza Superior reference PB95-0292 is gratefully acknowledge.

## 1 INTRODUCTION

A noticeable amount of recent statistical and econometric work has been devoted to consistent specification testing of univariate regression models. Two separate methodologies have been developed in the literature. The first approach consists of comparing parametric (or semiparametric) estimates with semi or nonparametric estimates, as done for instance in Härdle and Mammen (1993), Horowitz and Härdle (1993), Hong and White (1995), Gozalo (1993), Fan and Li (1996), Zheng (1996) and Rodriguez-Campos, González-Manteiga and Cao (1997). The second approach considers tests based on stochastic processes indexed by a "nuisance" parameter taking on an infinite number of values. This testing strategy was first proposed by Bierens (1982, 1990) and considered by Hong-Zhi and Bin (1991), Su and Wei (1991), Delgado (1993), Diebolt (1993), - Andrews (1997), Bierens and Ploberger (1997), De Jong and Bierens (1994), Delgado and Domínguez (1997) and Stute (1997) among others.

In this paper, we address the issue of specification testing in general parametric econometric models. Specifically, we consider models defined by multiple conditional moment restrictions that can be nonlinear in endogenous variables. This includes models with nonlinear transformations in the endogeneous variables and nonlinear in variables simultaneous equation models. In this aim, we simultaneously follow the two leading methodologies applied for specification testing of univariate regression models and extend them for jointly testing conditional moment restrictions. As a matter of fact, both approaches can be interpreted in the M-testing framework developed by Newey (1985) and Tauchen (1985), where unconditional restrictions are tested in place of conditional ones. The restrictions we consider are tailored to ensure consistency of the related testing procedures against any alternative. On the one hand, we consider moment conditions depending on unknown functions (regression curves and probability density functions), which can be estimated by means of kernel smoothers or other nonparametric estimation techniques. On the other hand, we consider an infinite number of orthogonality conditions indexed by a "nuisance" parameter. A test statistic can then be built as a functional of the empirical process indexed by this nuisance parameter.

We first study the asymptotic behavior of the proposed test statistics. However, relying only upon asymptotic analysis in implementing those testing pro-
cedures presents some difficulties. For the tests based on smoothers, the approximation quality of the null distribution of the test may be poor in small samples and is expected to be sensitive to the choice of a smoothing (or bandwidth) parameter and to the dimension of exogenous variables. For the tests based on empirical processes, the problem is even more acute, as the asymptotic null distribution depends on the (unknown) data generating process and can be easily tabulated only in exceptional circumstances. Therefore, we propose to approximate critical values of each test by "wild" bootstrap procedures, as done in regression contexts by Härdle and Mammen (1993) and Wang and Li (1996) for specification tests based on smoothers, and by Su and Wei (1991) and Stute, González-Manteiga and Presedo (1998) in specification tests based on certain empirical processes. Specifically, we propose two different bootstrap methods. The first one is based on test statistics obtained by plugging-in bootstraped analogs of the residuals in the initial statistics, as proposed in different contexts by Su and Wei (1991), Lewbel (1995), De Jong (1996) and Hansen (1996) among others. The consistency of the resulting bootstrap tests is formally justified and their behavior in small samples is illustrated by means of a Monte-Carlo experiment. The second method is the classical one, namely it uses conditional bootstrap to built bootstrap analogs to the sample test statistic. However, the formal asymptotic analysis of the resulting tests is complicated by the fact that the model can be nonlinear in the endogenous variables, so that a general asymptotic theory requires very specific conditions which are not needed when the model is linear in endogenous variables. We therefore discuss these difficulties and provide evidences on the performances of both bootstrap methods in small samples.

The paper is organized as follows. In the next section, we present the tests statistics and discuss their asymptotic properties. In Section 3, we study the bootstrap tests approximations, we justify the asymptotic validity of the bootstrap tests based on asymptotic expansions and we finally discuss implementation of the classical bootstrap tests. The small sample performances of the proposed asymptotic and bootstrap tests is studied in Section 4 by means of a Monte Carlo experiment. Proofs are confined to the Appendix.

## 2 ASYMPTOTIC TESTS

Suppose that $\mathcal{Y}_{n}=\left\{\left(Y_{i}, X_{i}\right), i=1, \ldots, n\right\}$ is a sample of independent observations, identically distributed as the vector $(Y, X)$, where $X=\left(X^{(1)}, X^{(2)}, \ldots, X^{(q)}\right)^{\prime}$ takes values in $\mathbb{R}^{\boldsymbol{q}}$ and $Y$ takes values in $\mathbb{R}^{d}$. The variables are supposed to be related according to a postulated parametric model which specification is determined by conditional moment restrictions of the form

$$
H_{0}: \exists \theta_{0} \in \Theta: \operatorname{Pr}\left\{E\left[\psi\left(Y, X ; \theta_{0}\right) \mid X\right]=0\right\}=1
$$

Here $\theta_{0}$ is an unknown vector of parameters, $\Theta \subset \mathbb{R}^{p}$ is the parameter space, $\psi$ : $\mathbb{R}^{d} \times \mathbb{R}^{q} \times \mathbb{R}^{p} \rightarrow \mathbb{R}^{m}$ is a vector of known functions such that $E\left\|\psi\left(Y, X ; \theta_{0}\right)\right\|<$ $\infty$, where $\|\cdot\|$ denotes Euclidean norm. The alternative hypothesis $H_{1}$ of incorrect specification is the negation of $H_{0}$. Most econometric models can be written in this form. It includes nonlinear regression models, but also general models that involve nonlinear transformations in the endogenous variables (e.g. Box-Cox transform) and nonlinear simultaneous equations models.

It turns out that $H_{0}$ is equivalent to any of the following conditions:

$$
\begin{equation*}
\exists \theta_{0} \in \Theta: E\left[\psi\left(Y, X ; \theta_{0}\right)^{\prime} W_{1}(X)\right]=0 \tag{1}
\end{equation*}
$$

or

$$
\begin{equation*}
\exists \theta_{0} \in \Theta: E\left[\psi\left(Y, X ; \theta_{0}\right) W_{2}(X, x)\right]=0, \forall x \in \mathcal{X}, \tag{2}
\end{equation*}
$$

where $W_{1}(X)=E\left[\psi\left(Y, X ; \theta_{0}\right) \mid X\right] f(X), W_{2}(X, x)=\prod_{j=1}^{q} 1\left(X^{(j)} \leq x^{(j)}\right)$, $1(A)$ is the indicator function of the event $A, x=\left(x^{(1)}, x^{(2)}, \ldots, x^{(q)}\right)^{\prime}$ and $\mathcal{X}$ denotes the support of $X$. Thus, $H_{0}$ can be tested by checking any of the above conditions. Other equivalent formulations of $H_{0}$ obviously exist, but they belong to one of the above types, i.e. they rely on an unknown weight function or they specify an infinite number of orthogonality conditions depending on a "nuisance" parameter.

The weight function $W_{1}$ (.) depends on unknown nonparametric functions, hence implementation of tests motivated by (1) requires nonparametric estimation. Define $\psi(\theta)=\psi(Y, X ; \theta)$ and $\psi_{i}(\theta)=\psi\left(Y_{i}, X_{i} ; \theta\right)$, with $k$-th coordinate denoted by $\psi^{(k)}(\theta)$ and $\psi_{i}^{(k)}(\theta)$ respectively. Given a suitable estimator $\hat{\theta}_{n}$ of $\theta_{0}$, the expectation in (1) can be estimated by

$$
T_{n}=\frac{1}{n} \sum_{i=1}^{n} \psi_{i}\left(\hat{\theta}_{n}\right)^{\prime} \hat{W}_{1}\left(X_{i}\right),
$$

where

$$
\hat{W}_{1}\left(X_{i}\right)=\frac{1}{(n-1) h^{q}} \sum_{\substack{j=1 \\ j \neq i}}^{n} \psi_{j}\left(\hat{\theta}_{n}\right) K_{i j}
$$

is a kernel estimator of $W_{1}\left(X_{i}\right), h=h(n)$ is a positive bandwidth number,

$$
K_{i j}=K\left(\frac{X_{i}-X_{j}}{h}\right)
$$

and $K():. \mathbb{R}^{q} \rightarrow \mathbb{R}$ is a symmetric kernel function. As we will show, a properly rescaled version of $T_{n}$ can be used as a test statistic for checking the specification of the econometric model.

The weight $W_{2}$ (.,.) depends on the nuisance parameter $x$, hence (2) specifies an infinite number of orthogonality conditions, one for each $x$. The expectation in (2) can be estimated by

$$
R_{n}(x)=\frac{1}{n} \sum_{i=1}^{n} \psi_{i}\left(\hat{\theta}_{n}\right) W_{2}\left(X_{i}, x\right)
$$

which is an empirical process of dimension $m$ marked by the "residual" functions $\psi_{i}\left(\hat{\theta}_{n}\right), i=1, . ., n$. Some suitable function of the process $R_{n}($.$) can then be$ used for testing $H_{0}$. We will consider a Cramer-von Mises type statistic, but a similar theory can be derived for any other statistic based on another norm.

The study of the asymptotic properties of $T_{n}$ and $R_{n}$ (.) requires the following usual regularity conditions.

A1 Under $H_{0}, \hat{\theta}_{n}$ admits the expansion,

$$
\hat{\theta}_{n}=\theta_{0}+\frac{1}{n} \sum_{i=1}^{n} \ell\left(Y_{i}, X_{i} ; \theta_{0}\right)+o_{p}\left(n^{-1 / 2}\right)
$$

for some interior point $\theta_{0}$ of $\theta$, a compact set in $\mathbb{R}^{q}$, and some vectorvalued function $\ell$ such that
(i) $E\left[\ell\left(Y, X ; \theta_{0}\right)\right]=0$,
(ii) $\mathrm{L}_{0}=E\left[\ell\left(Y, X ; \theta_{0}\right) \ell\left(Y, X ; \theta_{0}\right)^{\prime}\right]$ exists.

A2 For all $k=1, \ldots, m, \psi^{(k)}(\theta)$ has at least two continuous derivatives in an open neighborhood $N\left(\theta_{0}\right)$ of $\theta_{0}$ with respect to $\theta$, namely $\dot{\psi}^{(k)}(\theta)=$ $\partial \psi^{(k)}(\theta) / \partial \theta^{\prime}$ and $\ddot{\psi}^{(k)}(\theta)=\partial^{2} \psi^{(k)}(\theta) / \partial \theta \partial \theta^{\prime}$, where $E\left\|\dot{\psi}^{(k)}\left(\theta_{0}\right)\right\|<$ $\infty$, and there exists a function $N($.$) such that \sup _{\theta \in \mathcal{N}\left(\theta_{0}\right)}\left\|\ddot{\psi}^{(k)}(\theta)\right\| \leq$ $N(Y, X), k=1, . ., m$, with $E[N(Y, X)]<\infty$.

For instance, the estimator $\hat{\theta}_{n}$ can be a generalized method of moments (GMM) estimator defined as

$$
\begin{equation*}
\hat{\theta}_{n}=\arg \min _{\theta \in \Theta}\left[\sum_{i=1}^{n} A\left(X_{i}\right) \psi_{i}(\theta)\right]^{\prime} B_{n}\left[\sum_{i=1}^{n} A\left(X_{i}\right) \psi_{i}(\theta)\right], \tag{3}
\end{equation*}
$$

for a suitable $r \times m$ matrix of instruments $A(\cdot)$ and weighting matrix $B_{n}$ depending on the sample. Hence, under regularity conditions,

$$
\ell\left(Y_{i}, X_{i} ; \theta_{0}\right)=-\left(\mathcal{M}_{0}^{\prime} \mathcal{B}_{0} \mathcal{M}_{0}\right)^{-1} \mathcal{M}_{0}^{\prime} \mathcal{B}_{0} A\left(X_{i}\right) \psi_{i}\left(\theta_{0}\right),
$$

where

$$
\frac{1}{n} \sum_{i=1}^{n} A\left(X_{i}\right) \dot{\psi}_{i}\left(\theta_{0}\right) \xrightarrow{\text { a.s. }} \mathcal{M}_{0} \text { and } B_{n} \xrightarrow{\text { a.s. }} \mathcal{B}_{0},
$$

and $\dot{\psi}_{i}(\theta)=\left(\dot{\psi}_{i}^{(1)}(\theta)^{\prime}, \dot{\psi}_{i}^{(2)}(\theta)^{\prime}, \ldots, \dot{\psi}_{i}^{(m)}(\theta)^{\prime}\right)^{\prime}$, where $\dot{\psi}_{i}^{(k)}(\theta)=\partial \psi_{i}^{(k)}(\theta) / \partial \theta^{\prime}$, $k=1, . ., m$.

### 2.1 ASYMPTOTIC TEST BASED ON SMOOTHERS

We need the following minimal assumption on the kernel function.
K The kernel function $K$ is even, bounded, integrable, $\lim _{\|u\| \rightarrow \infty}\|u\|^{q}|K(u)|=$ $0, \int_{\mathbb{R}^{q}} K(u) d u>0$ and $\int_{\mathbb{R}^{q}} \int_{\mathbb{R}^{q}} K(u) K(u+v) d u d v<\infty$.
Since we are not assuming that $K($.$) integrates to one, T_{n}$ will not estimate the expectation in (1), but its product with $\int K(u) d u$. This is of no relevance with respect to the testing procedure. However, most kernels used in practice integrate to one. We also assume that certain nonparametric functions belong to a general class, defined through a Lipschitz condition as follows.

Definition $1 G^{\alpha}, \alpha>0$, is the class of functions $g():. \mathbb{R}^{q} \rightarrow \mathbb{R}$, satisfying: there exists a $\rho>0$ such that for all $z \in \mathbb{R}^{q}, \sup _{y \in S_{x \rho}}|g(y)-g(z)| /\|y-z\| \leq$ $G(z)$, where $S_{z \rho}=\{y:\|y-z\| \leq \rho\}$, and $g($.$) and G($.$) have finite \alpha-$ th moments (or are bounded if $\alpha=+\infty$ ).
Let $\sigma_{k l}(x)=E\left[\psi^{(k)} \psi^{(l)} \mid X=x\right], \sigma_{k}^{4}(x)=E\left[\left(\psi^{(k)}\right)^{4} \mid X=x\right], \alpha_{k}(x)=$ $E\left[\left|\psi^{(k)}\right| \mid X=x\right], \gamma_{k}(x)=E\left[\dot{\psi}^{(k)} \mid X=x\right], k, l=1, \ldots, m$ and $\beta(x)=$ $E[N \mid X=x]$, where the functions $\psi^{(k)}$ are evaluated at $\theta_{0}$. The next assumption summarizes the smoothness conditions on the different nonparametric functions.

S $f(.) \in G^{\infty}$. For all $k, l=1, \ldots, m, \sigma_{k l}(.) \in G^{4}$, each element of $\gamma_{k}($.$) is in$ $G^{8 / 3}, \sigma_{k}^{4}(),. \alpha_{k}($.$) and \beta($.$) are in G^{2}$ and $E\left[\left\|\dot{\psi}^{(k)}\right\|^{8 / 3}\right]<\infty$.
Finally, we impose the standard assumptions on the rate of convergence of the bandwidth parameter.

B $\lim _{n \rightarrow \infty}\left\{h+\left(n h^{q}\right)^{-1}\right\}=0$.
To justify the asymptotic test, we first derive an asymptotic linearization of $T_{n}$.

Lemma 1 Under $H_{0}$ and Assumptions $A 1, A 2, K, S, B$,

$$
T_{n}=\binom{n}{2}^{-1} \sum_{i=1}^{n-1} \sum_{j=i+1}^{n} h^{-q} \psi_{i}\left(\theta_{0}\right)^{\prime} \psi_{j}\left(\theta_{0}\right) K_{i j}+O_{p}\left(n^{-1}\right)
$$

Since the leading term in the asymptotic linearization of $T_{n}$ is a degenerate $U$-statistic, its null distribution of $T_{n}$ is obtained by Theorem 1 in Hall (1984).

Theorem 1 Under $H_{0}$ and Assumptions $A 1, A 2, K, S, B$,

$$
n h^{q / 2} T_{n} \xrightarrow{d} N(0, V),
$$

where $V=2 E\left\{\sum_{k=1}^{m} \sum_{l=1}^{m} \sigma_{k l}^{2}(X) f(X)\right\} \int_{\mathbb{R}^{q}} K(u)^{2} d u$.
By analogy with $T_{n}$, the variance $V$ can be estimated by

$$
\hat{V}_{n}=\frac{2}{n(n-1) h^{q}} \sum_{k=1}^{m} \sum_{l=1}^{m} \sum_{i=1}^{n} \sum_{\substack{j=1 \\ j \neq i}}^{n} \psi_{i}^{(k)}\left(\hat{\theta}_{n}\right) \psi_{i}^{(l)}\left(\hat{\theta}_{n}\right) \psi_{j}^{(k)}\left(\hat{\theta}_{n}\right) \psi_{j}^{(l)}\left(\hat{\theta}_{n}\right) K_{i j}^{2}
$$

Therefore, an asymptotic one-sided test can be based on the statistic $t_{n}=$ $n h^{q / 2} T_{n} / \hat{V}_{n}^{1 / 2}$, as justified by the following corollary.

Corollary 1 Under Assumptions $A 1, A 2, K, S$ and $B, t_{n} \xrightarrow{d} N(0,1)$ under $H_{0}$ and $t_{n} \xrightarrow{p}+\infty$ under $H_{1}$ assuming that $A 1$ and $A 2$ hold with some $\theta_{1}$ in place of $\theta_{0}{ }^{1}$

[^0]Following the line of Theorem 1's proof, we could similarly show that the test is consistent in the direction of contiguous alternatives of the form

$$
H_{1 n}: E\left[\psi\left(Y, X ; \theta_{0}\right) \mid \dot{X}\right]=\frac{g(X)}{n^{1 / 2} h^{q / 4}} \text { a.s., }
$$

for some $\theta_{0} \in \Theta$, where $g($.$) is a generic non null function. Such alternatives$ converge to the null slower than the parametric rate $n^{-1 / 2}$. It is also possible to show that the test is able to detect alternatives of the form

$$
H_{2 n}: E\left[\psi\left(Y, X ; \theta_{0}\right) \mid X\right]=\eta_{n}(X) \text { a.s. }
$$

for some $\theta_{0} \in \Theta$, where

$$
\eta_{n}(x)=\alpha_{n} b\left(\frac{x-c}{\gamma_{n}}\right)
$$

where $c$ is a constant and $\alpha_{n}, \gamma_{n}$ are deterministic sequences converging to zero with the sample size at appropriate rates, $b$ (.) is an integrable and continuously differentiable function up to second order, with band limited with $h=o\left(\gamma_{n}\right)$. The magnitude of the indefinite integral of $\eta_{n}(x)$ is of order $\alpha_{n} \gamma_{n}$, which can be of magnitude $O\left(n^{-1 / 2}\right)$ or smaller by choosing the bandwidth $h, \alpha_{n}$ and $\gamma_{n}$ in a suitable way. These alternatives were first proposed by Rosenblatt (1975), and later used by Fan (1994) in the context of testing the parametric specification of a density function and by Fan and Li (1997) in the context of testing the goodness-of-fit of a parameterized regression model.

### 2.2 ASYMPTOTIC TEST BASED ON MARKED EMPIRICAL PROCESSES

To justify an asymptotic test, we first derive an asymptotic linearization of $R_{n}$ (.) using a standard mean value theorem argument.

Lemma 2 Under $H_{0}$ and Assumptions A1, A2,

$$
R_{n}(x)=\frac{1}{n} \sum_{i=1}^{n} r_{i}(x)+o_{p}\left(n^{-1 / 2}\right) \text { a.s., }
$$

uniformly in $x$, where

$$
r_{i}(x)=\left\{\psi_{i}\left(\theta_{0}\right) \Delta_{i}(x)+E\left[\dot{\psi}_{i}\left(\theta_{0}\right) \Delta_{i}(x)\right] l\left(Y_{i}, X_{i} ; \theta_{0}\right)\right\}
$$

with $\Delta_{i}(x)=W_{2}\left(X_{i}, x\right)=\prod_{j=1}^{q} 1\left(X_{i}^{(j)} \leq x^{(j)}\right)$, for $X=\left(X_{i}^{(1)}, \ldots, X_{i}^{(q)}\right)^{\prime}$ and $x=\left(x^{(1)}, . ., x^{(q)}\right)^{\prime}$.

The process $R_{n}($.$) is a random element in the Skorokhod space \times{ }_{l=1}^{m} D\left(\mathbb{R}^{q}\right)$, which is defined as the space of all real functions $h($.$) continuous from above in$ $\mathbb{R}^{q}$, such that for any $x$ and every sequence $\left\{x_{n}\right\}$ approaching to $x$ in some quadrant with corner $x, \lim _{n \rightarrow \infty} h\left(x_{n}\right)$ exists. The process is extended to $\times_{l=1}^{m} D\left[\mathbb{R}^{q}\right]$ by defining

$$
R_{n}(-\infty)=0, \text { and } R_{n}(\infty)=\frac{1}{n} \sum_{i=1}^{n} \psi_{i}\left(\hat{\theta}_{n}\right)
$$

see Stute (1997) for a discussion of convergence in this space. From the expansion of Lemma 2 it is straightforward to show that, for any finite $s$ and arbitrary $\left(x_{1}, . ., x_{s}\right),\left(\sqrt{n} R_{n}\left(x_{1}\right), . ., \sqrt{n} R_{n}\left(x_{s}\right)\right)$ converges under $H_{0}$ to a gaussian random vector $\left(R_{\infty}\left(x_{1}\right), \ldots, R_{\infty}\left(x_{s}\right)\right)$. By showing the tightness of the process, we obtain that $\sqrt{n} R_{n}$ (.) converges weakly to the $m$-valued gaussian process $R($.$) with$ $q$ parameters, whose projections on $\left(x_{1}, . ., x_{s}\right)$ are $\left(R_{\infty}\left(x_{1}\right), . ., R_{\infty}\left(x_{s}\right)\right.$ ), i.e. a $m$-variate gaussian sheet with $q$ parameters.

Theorem 2 Under $H_{0}$ and Assumptions A1, A2,

$$
\sqrt{n} R_{n}(.) \Rightarrow R_{\infty}(.) \text { on } \times_{l=1}^{m} D\left[\mathbb{R}^{q}\right]
$$

where $R_{\infty}($.$) is a centered m-variate gaussian sheet with q$ parameters and covariance structure $E\left[r_{i}\left(x_{1}\right) r_{i}\left(x_{2}\right)^{\prime}\right], \forall x_{1}, x_{2} \in \mathbb{R}^{q}$.

Thus, an asymptotic specification test can be based on some suitable function of $R_{n}$ (.). We choose to study a Cramer-von Mises' type test statistic defined as $c_{n}=n \int R_{n}^{\prime}(x) R_{n}(x) d F_{n}(x)=\sum_{i=1}^{n} R_{n}\left(X_{i}\right)^{\prime} R_{n}\left(X_{i}\right)$. Alternatively, we could also follow Bierens (1982) and integrate the process with respect to a measure different than the empirical distribution $F_{n}$ (.). However, the empirical measure seems a natural and convenient choice. The following corollary provides the asymptotic behavior of $c_{n}$.

Corollary 2 Under Assumptions $A 1$ and $A 2, c_{n} \xrightarrow{d} \int_{\mathbb{R}^{q}} R_{\infty}(x)^{\prime} R_{\infty}(x) d F(x)$ under $H_{0}$, where $F($.$) is the distribution function of X$, and $c_{n} \xrightarrow{p}+\infty$ under $H_{1}$ assuming that $A 1$ and $A 2$ hold with some $\theta_{1}$ in place of $\theta_{0} .^{2}$

[^1]The practical applicability of a test based on $c_{n}$ is hampered by the fact that the limiting distribution of the test statistic under the null hypothesis is casedependent, namely it depends of the unknown data-generating process, and therefore can not be tabulated. One way of solving this problem is to derive case-independent upperbounds of the asymptotic critical values, as proposed by Bierens and Ploberger (1997). Alternatively, we propose in Section 3 to implement bootstrap tests.

It can be shown that the (infeasible) test based on $c_{n}$ is consistent in the direction of contiguous alternatives of the form

$$
H_{3 n}: E\left[\psi\left(Y, X ; \theta_{0}\right) \mid X\right]=\frac{g(X)}{n^{1 / 2}} \text { a.s., }
$$

for some $\theta_{0} \in \Theta$, where $g($.$) is a nonnull generic function. { }^{3}$ Bierens and Ploberger (1997) and Stute (1997) show the consistency of some related sempirical process based tests under alternatives of type $H_{3 n}$ for regression models. The test based on smoothers cannot detect alternatives like $H_{3 n}$, but conversely the test based on a marked empirical process cannot detect alternatives like $H_{2 n}$. This fact was pointed out by Rosenblatt (1975) and has been recently studied by Fan and Li (1997) comparing Bierens' test and a test based on smoothers in the context of specification testing of regression models.

## 3 BOOTSTRAP TESTS

The practical implementation of the asymptotic testing procedures introduced in the previous section involves some difficulties. On the one hand, asymptotic tests based on smoothers can be very sensitive to the choice of the smoothing parameter, while the approximation to the asymptotic null distribution can be slow, depending on the number of exogenous variables $X$ in the model, see e.g. Härdle and Mammen (1993). On the other hand, the asymptotic behavior of $c_{n}$ is not distribution free, so that an asymptotic test can only be implemented in rare circumstances. ${ }^{4}$ Therefore, bootstrap tests are sorely needed. A bootstrap test relies on the quantiles of a bootstrap test statistic, that are computed from

[^2]artificial samples generated so as they mimic some features of the initial sample. These quantiles can be approximated as accurately as desired by Monte Carlo.

For testing procedures, it is the distribution under the null hypothesis that is of interest, so that the bootstrap sampling must impose the satisfaction of $H_{0}$. In the context of regression specification tests, Härdle and Mammen (1993) and Stute, González-Manteiga and Presedo (1997) have pointed out the necessity of applying a residual based bootstrap in order to resample under the null hypothesis of correct specification. In our general framework, the role of the residuals is played by the $\psi_{i}$ 's evaluated at $\hat{\theta}_{n}$. Let $V_{i}, i=1, \ldots, n$ be random numbers such that the following assumption holds.

V The $V_{i}$ 's are independently distributed with bounded support such that $E\left(V_{i}\right)=0$ and $E\left(V_{i}^{2}\right)=1, i=1, \ldots n$.

The bootstrap procedure consists in generating a great number of independent and identically distributed random samples of $V_{i}$ 's satisfying Assumption $V$ to obtain bootstrap samples $\hat{\psi}_{i}^{*}=\hat{\psi}_{i} V_{i}, i=1, \ldots, n$, that therefore satisfy the null hypothesis. Each bootstrap sample in turn forms a basis to construct a test statistic and the distribution of the resulting bootstrap statistics can therefore be used to estimate the critical regions of the test. Such a procedure for obtaining artificial samples is known as "wild bootstrap" and was introduced by Wu (1986) in the context of heteroskedastic linear models.

We propose two alternative methods of computing bootstrap test statistics. In the first method, we simply plug in the $\hat{\psi}_{i}^{*}$ 's in place of the initial $\psi_{i}$ 's to obtain a bootstrap test statistic. This naive plug-in procedure is similar to the one employed by Su and Wei (1991), Lewbel (1995), De Jong (1996) and Hansen (1996) in other contexts. In the second method, the bootstrapped $\hat{\psi}_{i}^{*}$ 's are used to obtain a resample $\mathcal{Y}_{n}^{*}=\left\{\left(Y_{i}^{*}, X_{i}\right), i=1, . ., n\right\}$ from the original sample $\mathcal{Y}_{n}$. We subsequently compute a test statistic from $\mathcal{Y}_{n}^{*}$ in the same way as the original test statistic has been derived from the original sample. This analog bootstrap method generalizes the method in Härdle and Mammen (1993), Wang and Li (1997) and Stute, González-Manteiga and Presedo (1997) in specification testing of regression models. The second method requires that we can retrieve the $Y_{i}^{* '}$ 's from the $\hat{\psi}_{i}^{*}$ 's, which may not always be possible. Moreover, it is computationally much more demanding than the first one. However, analog bootstrap tests are expected to share the excellent performances enjoyed, in
general, by bootstrap tests.
Suppose $\eta_{n}^{*}$ is the bootstrap statistic which distribution, conditional on the sample, is used for approximating the distribution of $\eta_{n}$ (i.e. $\eta_{n}$ can be $c_{n}$ or $t_{n}$ ). Suppose that under $H_{0}, \eta_{n} \xrightarrow{d} \eta$. First we must show that under $H_{0}, \eta_{n}^{*} \xrightarrow{d^{*}} \eta$ in probability (a.s.) where $\xrightarrow{\boldsymbol{d}^{-}}$in probability (a.s.) means weak convergence in bootstrap distribution in probability (a.s.) according to the following definition.

Definition 2 Define $\operatorname{Pr}^{*}(\cdot)=\operatorname{Pr}\left(\cdot \mid \mathcal{Y}_{n}\right)$. Let $\eta_{n}^{*}$ be a bootstrap test statistic. It is said that $\eta_{n}^{*}$ converges weakly (almost surely) in bootstrap distribution to the random variable $\eta$, with distribution function $H($.$) , and it is denoted by$ $\eta_{n}^{*} \stackrel{d^{*}}{\rightarrow} \eta$ in probability (almost surely), whenever the sequence of random variables $\operatorname{Pr}^{*}\left(\eta_{n}^{*} \leq z\right)$ converges to $H(z)$ in probability (almost surely), for every continuity point $z$ of $H($.$) .$

Since under $H_{0}$, the conditional distribution of $\eta_{n}^{*}$ consistently estimates the distribution of $\eta_{n}$, we can use the quantiles, obtained from the empirical distribution of the Monte Carlo sample of $\eta_{n}^{*}$, as estimators of the corresponding quantiles of $\eta_{n}$. To ensure consistency of the bootstrap test, the bootstrap statistic $\eta_{n}^{*}$ only needs be bounded in probability (or a.s.) under $H_{1}$. For the smooth test, the test statistic is asymptotically pivotal, and hence converges under the alternative hypothesis to the same distribution as under the null hypothesis. For the empirical process based test, the limiting distribution of the test statistic depends upon the data generating process under $H_{1}$ as well as under $H_{0}$.

### 3.1 PLUG-IN BOOTSTRAP TESTS

The plug-in version on the smooth test approximates the distribution of $t_{n}$ by the conditional distribution of the bootstrap statistic

$$
t_{n}^{*}=\frac{n h^{q / 2} T_{n}^{*}}{\sqrt{\hat{V}_{n}}}, \text { where } T_{n}^{*}=\frac{1}{h^{q}}\binom{n}{2}^{-1} \sum_{i=1}^{n-1} \sum_{j=i+1}^{n} \hat{\psi}_{i}^{* \prime} \hat{\psi}_{j}^{*} K_{i j}
$$

The plug-in version on the empirical process test approximates the distribution of $c_{n}$ by the conditional distribution of the bootstrap statistic

$$
c_{n}^{*}=\sum_{i=1}^{n} R_{n}^{*}\left(X_{i}\right)^{\prime} R_{n}^{*}\left(X_{i}\right), \text { where } R_{n}^{*}(x)=\frac{1}{n} \sum_{i=1}^{n} r_{i}^{*}(x) \text { and }
$$

$$
r_{i}^{*}(x)=\left\{\hat{\psi}_{i} \Delta_{i}(x)+\left[\frac{1}{n} \sum_{i=1}^{n} \dot{\psi}_{i}\left(\hat{\theta}_{n}\right) \Delta_{i}(x)\right] l\left(Y_{i}, X_{i} ; \hat{\theta}_{n}\right)\right\} V_{i} .
$$

The next two theorems formally justify the use of the bootstrap tests.
Theorem 3 Under $V, A 1, A 2, K, S$ and $B$,

$$
t_{n}^{*} \xrightarrow{d^{*}} N(0,1) \text { in probability }
$$

under $H_{0}$, and under $H_{1}$ assuming that $A 1$ and $A 2$ hold with some $\theta_{1}$ in place of $\theta_{0}$.

Theorem 4 Let $i(\theta)=\partial l(Y, X ; \theta) / \partial \theta$. Assume that $\sup _{\theta \in \mathcal{N}\left(\theta_{0}\right)}\|i(\theta)\|^{2}<$ $\dot{L}(Y, X)$ with $E[\dot{L}(Y, X)]<\infty$ and that $V$ holds. Then, under $H_{0}$ and Assumptions A1, A2,

$$
c_{n}^{*} \stackrel{d^{*}}{\rightarrow} \int_{\mathbb{R}^{q}} R_{\infty}(x)^{\prime} R_{\infty}(x) d F(x) \text { a.s, }
$$

and under $H_{1}$, assuming that $A 1$ and $A 2$ hold with some $\theta_{1}$ in place of $\theta_{0}$,

$$
c_{n}^{*} \xrightarrow{d^{*}} \int_{\mathbb{R}^{q}} R_{\infty}^{1}(x)^{\prime} R_{\infty}^{1}(x) d F(x) \text { a.s. }
$$

where $R_{\infty}^{1}($.$) is a gaussian process centered at zero and with the same covariance$ structure than $R_{\infty}$ (.) with $\theta_{1}$ in place of $\theta_{0}$.

### 3.2 ANALOG BOOTSTRAP TESTS

When there are as many equations as response variables, i.e., when $m=d$, it can be possible to obtain a resample $\mathcal{Y}_{n}^{*}=\left\{\left(Y_{i}^{*}, X_{i}\right), i=1, \ldots, n\right\}$ from the bootstrapped $\hat{\psi}_{i}^{*}$ 's. Assume that $\psi(Y, X ; \theta)=\psi$ has an unique solution for $Y=$ $Y(\psi, X ; \theta)$ in a neighborhood of $\theta_{0}$ under $H_{0}$ and in a neighborhood of $\theta_{1}$ under $H_{1}$. A closed form of the solution is, in general, not available, but numerical methods can be used. Hence we obtain $Y_{i}^{*}$ by solving $\psi\left(Y_{i}^{*}, X_{i} ; \hat{\theta}_{n}\right)=\hat{\psi}_{i}^{*}, i=$ $1, . ., n$. The bootstrap analog of $\hat{\theta}_{n}$ in (3) is the solution to

$$
\hat{\theta}_{n}^{*}=\arg \min _{\theta \in \Theta} \phi_{n}^{*}(\theta)^{\prime} B_{n} \phi_{n}^{*}(\theta)
$$

where $\phi_{n}^{*}(\theta)=n^{-1} \sum_{i=1}^{n} A\left(X_{i}\right) \psi\left(Y_{i}^{*}, X_{i} ; \theta\right)$. In practice, the extremum estimator $\hat{\theta}_{n}^{*}$ may not actually be located, but rather the outcome of finitely many
iterations of some iterative procedure. A convenient form of Gauss-Newton iteration towards the solution is

$$
\hat{\theta}_{n}^{*(k+1)}=\hat{\theta}_{n}^{*(k)}-\left(M_{n}^{*}\left(\hat{\theta}_{n}\right)^{\prime} B_{n} M_{n}^{*}\left(\hat{\theta}_{n}\right)\right)^{-1} M_{n}^{*}\left(\hat{\theta}_{n}\right)^{\prime} B_{n} \phi_{n}^{*}\left(\hat{\theta}_{n}^{*(k)}\right),
$$

for $k=2,3, \ldots$, where $\hat{\theta}_{n}^{*(1)}=\hat{\theta}_{n}$ and $M_{n}^{*}(\theta)=n^{-1} \sum_{i=1}^{n} A\left(X_{i}\right) \dot{\psi}\left(Y_{i}^{*}, X_{i} ; \theta\right)$.
Let us denote $Z_{n}^{*}=o_{p^{*}}(1)$ a.s. (or in probability) if $\forall \varepsilon>0, \operatorname{Pr}^{*}\left(\left|Z_{n}^{*}\right|>\varepsilon\right) \xrightarrow{\text { a.s.(p) }}$
$0 .{ }^{5}$ By construction, we have

$$
\sqrt{n}\left(\hat{\theta}_{n}^{*(2)}-\hat{\theta}_{n}\right)=\frac{1}{\sqrt{n}} \sum_{i=1}^{n} \ell_{i n}^{*}\left(\hat{\theta}_{n}\right)
$$

where

$$
\ell_{i n}^{*}(\theta)=-\left(M_{n}^{*}(\theta)^{\prime} B_{n} M_{n}^{*}(\theta)\right)^{-1} M_{n}^{*}(\theta) B_{n} A\left(X_{i}\right) \psi\left(Y_{i}^{*}, X_{i} ; \theta\right)
$$

Therefore, the one-step estimator $\hat{\theta}_{n}^{*(2)}$ is consistent in bootstrap law, in the sense that $\hat{\theta}_{n}^{*(2)}=\hat{\theta}_{n}+o_{p^{*}}$ (1) a.s., whenever

$$
M_{n}^{*}\left(\bar{\theta}_{n}^{*}\right)=M_{n}^{*}\left(\hat{\theta}_{n}\right)+o_{p^{*}}(1) \text { a.s., } \forall \bar{\theta}_{n}^{*}: \bar{\theta}_{n}^{*}=\hat{\theta}_{n}+o_{p^{*}}(1) \text { a.s. }
$$

Similarly for all $k \geq 2, \hat{\theta}_{n}^{*(k)}$ is consistent in bootstrap law as

$$
\sqrt{n}\left(\hat{\theta}_{n}^{*(k)}-\hat{\theta}_{n}\right)=\frac{1}{\sqrt{n}} \sum_{i=1}^{n} \ell_{i n}^{*}\left(\hat{\theta}_{n}\right)+o_{p^{*}}(1) \text { a.s. }
$$

Let $\psi_{i}^{* *}(\theta) \equiv\left(\psi_{i}^{* *(1)}(\theta)^{\prime}, \psi_{i}^{* *(2)}(\theta)^{\prime}, \ldots, \psi_{i}^{* *(m)}(\theta)^{\prime}\right)^{\prime}=\psi\left(Y_{i}^{*}, X_{i} ; \theta\right)$ and $\tilde{\theta}_{n}^{*}=\hat{\theta}_{n}^{*(k)}$ for some $k>1$. The bootstrap analogs of $c_{n}$ and $t_{n}$ are thus

$$
c_{n}^{* *}=\sum_{i=1}^{n} R_{n}^{* *}\left(X_{i}\right)^{\prime} R_{n}^{* *}\left(X_{i}\right), \text { with } R_{n}^{* *}(x)=\frac{1}{n} \sum_{i=1}^{n} \psi_{i}^{* *}\left(\tilde{\theta}_{n}^{*}\right) \Delta_{i}(x)
$$

and

$$
\begin{aligned}
& t_{n}^{* *}=\frac{n h^{q / 2} T_{n}^{* *}}{\sqrt{\hat{V}_{n}^{*}}}, \text { with } T_{n}^{* *}=\frac{1}{n(n-1) h^{q}} \sum_{i=1}^{n} \sum_{\substack{j \neq i \\
j=1}}^{n} \psi_{i}^{* *}\left(\tilde{\theta}_{n}^{*}\right)^{\prime} \psi_{j}^{* *}\left(\tilde{\theta}_{n}^{*}\right) K_{i j}, \\
& \hat{V}_{n}^{*}=\frac{2}{n(n-1) h^{q}} \sum_{s=1}^{m} \sum_{l=1}^{m} \sum_{i=1}^{n} \sum_{\substack{j=1 \\
j \neq i}}^{n} \psi_{i}^{*(s)}\left(\tilde{\theta}_{n}^{*}\right) \psi_{i}^{*(l)}\left(\tilde{\theta}_{n}^{*}\right) \psi_{j}^{*(s)}\left(\tilde{\theta}_{n}^{*}\right) \psi_{j}^{*(l)}\left(\tilde{\theta}_{n}^{*}\right) K_{i j}^{2}
\end{aligned}
$$

[^3]For regression models, which are linear in the endogenous variables, the formal asymptotic analysis of bootstrap analogs of the test statistics is almost similar to the one of bootstrap tests based on asymptotic expansions. However, in the general case where the econometric model allows for nonlinear transformation in the endogenous variables, the analysis is much more complicated. One could derive some primitive assumptions that imply validity of our bootstrap tests, similar to those established by Hall and Horowitz (1996). We prefer not to address this issue, but rather we provide some conditions that ensure consistency of the tests based on $c_{n}^{* *}$ and $t_{n}^{* *}$ and discuss the implications for practical implementation of the tests.

Let us first consider the test based on $c_{n}^{* *}$. Assume that for any $\vec{\theta}_{n}^{*}$ (which may depend on the bootstrap sample) such that $\bar{\theta}_{n}^{*}=\hat{\theta}_{n}+o_{p^{*}}$ (1) a.s., and any measurable function $S($.$) ,$

$$
\begin{equation*}
\frac{1}{n} \sum_{i=1}^{n} S\left(X_{i}\right) \dot{\psi}\left(Y_{i}^{*}, X_{i} ; \bar{\theta}_{n}^{*}\right)=\frac{1}{n} \sum_{i=1}^{n} S\left(X_{i}\right) \dot{\psi}\left(Y_{i}^{*}, X_{i} ; \hat{\theta}_{n}\right)+o_{p^{-}}(1) \text { a.s. } \tag{4}
\end{equation*}
$$

and

$$
\begin{equation*}
E^{*}\left\{\frac{1}{n} \sum_{i=1}^{n} S\left(X_{i}\right) \dot{\psi}\left(Y_{i}^{*}, X_{i} ; \hat{\theta}_{n}\right)\right\}=\frac{1}{n} \sum_{i=1}^{n} S\left(X_{i}\right) \dot{\psi}\left(Y_{i}, X_{i} ; \hat{\theta}_{n}\right)+o_{p}(1) \text { a.s. } \tag{5}
\end{equation*}
$$

where $E^{* *}(\cdot)=E\left(\cdot \mid \mathcal{Y}_{n}\right)$. Then, it is straightforward to prove that $R_{n}^{* *}(x)=$ $R_{n}^{*}(x)+o_{p^{*}}(1)$ a.s. uniformly en $x$. The above conditions are therefore sufficient for the validity of the bootstrap test based on $c_{n}^{*}$. Condition (4) can be shown to follow assuming that $\psi$ (.) fulfills conditions similar to Assumption 3 of Hall and Horowitz (1996). Condition (5) is satisfied choosing appropriate $V_{i}$ 's, and the particular parametric form of $\psi($.$) can help to determine a suitable procedure$ to generate these random numbers. Moreover, when certain information on the data generating process is available, the $V_{i}$ 's can be chosen in a standard way. For instance, if the conditional density of $\psi(Y, X ; \theta)$ given $X$ is symmetric, we can choose $V_{i}$ such that $\operatorname{Pr}\left(V_{i}=1\right)=\operatorname{Pr}\left(V_{i}=-1\right)=1 / 2$, so that the right-hand side of (5) equals
$\frac{1}{2 n} \sum_{i=1}^{n} S\left(X_{i}\right) \dot{\psi}\left(Y\left(\hat{\psi}_{i}, X_{i} ; \hat{\theta}_{n}\right), X_{i} ; \hat{\theta}_{n}\right)+\frac{1}{2 n} \sum_{i=1}^{n} S\left(X_{i}\right) \dot{\psi}\left(Y\left(-\hat{\psi}_{i}, X_{i} ; \hat{\theta}_{n}\right), X_{i} ; \hat{\theta}_{n}\right)$,
which is a.s. equivalent to $n^{-1} \sum_{i=1}^{n} S\left(X_{i}\right) \dot{\psi}\left(Y_{i}, X_{i} ; \hat{\theta}_{n}\right)$ under classical regularity conditions.

Different conditions are required for the validity of the test based on $t_{n}^{* *}$. Assume that for any $\bar{\theta}_{n}^{*}$ and $\tilde{\theta}_{n}^{*}$ such that $\bar{\theta}_{n}^{*}=\hat{\theta}_{n}+o_{p}$. (1) a.s. and $\tilde{\theta}_{n}^{*}=$ $\hat{\theta}_{n}+o_{p}{ }^{*}$ (1) a.s.,

$$
\begin{gather*}
\widehat{S}_{1 n}^{*}=\binom{n}{2}^{-1} \sum_{i<j} \psi_{i}^{*}\left(\hat{\theta}_{n}\right) \dot{\psi}_{j}^{*}\left(\bar{\theta}_{n}^{*}\right) K_{i j}=O_{p^{*}}\left(n^{-1 / 2}\right) \text { a.s., }  \tag{6}\\
\widehat{S}_{2 n}^{*}=\binom{n}{2}^{-1} \sum_{i<j} \dot{\psi}_{i}^{*}\left(\bar{\theta}_{n}^{*}\right) \dot{\psi}_{j}^{*}\left(\tilde{\theta}_{n}^{*}\right) K_{i j}=O_{P^{*}}\left(n^{-1 / 2}\right) \text { a.s., }  \tag{7}\\
\hat{V}_{n}^{*}=\hat{V}_{n}+o_{p} \cdot(1) \text { a.s. } \tag{8}
\end{gather*}
$$

It is then easy to prove under the other regularity assumptions of Theorem 3 that $T_{n}^{* *}=T_{n}^{*}+o_{p}$. (1) a.s. Following the proof of Theorem 3, (6) holds if

$$
\hat{S}_{1 n}^{*}=\hat{S}_{1 n}+o_{p^{*}}(1) \text { a.s., where } \hat{S}_{1 n}=\binom{n}{2}^{-1} \sum_{i<j} \psi_{i}\left(\hat{\theta}_{n}\right) \dot{\psi}_{i}\left(\hat{\theta}_{n}\right) K_{i j}
$$

and (7) holds under a similar condition. Again, if the conditional density of $\psi(Y, X ; \theta)$ given $X$ is symmetric, choosing the distribution of the $V_{i}$ 's that assigns equal probability to 1 and -1 ensures (6)-(8).

## 4 MONTE CARLO STUDY

To investigate the small sample behavior of the tests we have proposed, we have performed Monte Carlo simulations for a well-studied model with a nonlinear transformation in the endogeneous variable, namely the arcsinh transformation. This model was proposed by Burbidge, Magee and Robb (1988) as an alternative to the Box-Cox transformation, and was used by Robinson (1991) among others. The hypothesis of interest here writes

$$
H_{0}: \exists\left(\lambda_{0}, \alpha_{0}, \beta_{0}\right): \operatorname{Pr}\left\{E\left[\left.\frac{\operatorname{arcsinh}\left(\lambda_{0} Y\right)}{\lambda_{0}}-\alpha_{0}-\beta_{0} X \right\rvert\, X\right]=0\right\}=1
$$

We consider the design

$$
\frac{\operatorname{arcsinh}\left(2 Y_{i}\right)}{2}=1+2 X_{i}+\sin \left(\delta \pi X_{i}\right)+u_{i}, i=1, \ldots, n,
$$

where the $u_{i}$ 's are iids $N(0,0.5)$ and independently distributed of the $X_{i}$ 's which are iids $N(0,1)$. The null hypothesis $D G P_{0}$ corresponds to $\delta=0$. We investigate three alternatives $D G P_{1}, D G P_{2}$ and $D G P_{3}$ corresponding to $\delta=1,2$ and 3 respectively. Increasing $\delta$, we obtain higher frequency alternatives that are more difficult to distinguish from pure noise.

The parameters are estimated by GMM with objective function as in (3) and vector of instruments $A\left(X_{i}\right)=\left(1, X_{i}, X_{i}^{2}\right)^{\prime}$ and $B_{n}=I_{3}$. For the tests based on smoothers, we choose the bandwidth following the rule-of-thumb, i.e. as $h=d n^{-1 / 5}$ for different values of $d$. Three different sample sizes, $n=50,100$ and 250 , are considered. Tables 1 to 4 report results obtained for each of the considered data generating processes using the five tests proposed in this paper. In each cell are reported the empirical frequencies of rejections of the null hypothesis at a $10 \%$ (first row) and a $5 \%$ (second row) nominal level.

The empirical sizes of our tests are reported in Table 1. The tests based on $t_{n}$ and $t_{n}^{*}$ are undersized for large and moderate bandwidths, i.e. for $d$ between 2 and 0.5 , irrespective of the sample size. Better empirical sizes are obtained for smaller bandwidths. On the whole, the smooth tests based on $t_{n}$ and $t_{n}^{*}$ lead to very similar results. Thus the plug-in bootstrap test does not seem able to improve on the size performances of the asymptotic smooth test for small and moderate samples. Similarly, the test based on $c_{n}^{*}$ is undersized in small samples, while its performance improves when the sample size grows. In contrast, the bootstrap analogs of the two tests exhibits empirical sizes very close to nominal sizes. This is attained even for a sample size as small as 50 , and for the smooth test irrespective of the bandwidth choice.

We now turn to the study of the empirical power. Under the first alternative $D G P_{1}$ (Table 2), the three smooth tests exhibits very good performances. For a sample size of 50 , empirical power is lower for very small bandwidths. When the sample size is 100 or higher the empirical power is greater than $85 \%$ for any bandwidth and attains $95 \%$ in most cases. In contrast, the test based on $c_{n}^{*}$ has quite small power against $D G P_{1}$ for $n=50$ or 100 . This is largely corrected by the bootstrap analog version of the test, whose empirical power increases with the sample size.

Under the second alternative which has higher frequency than $D G P_{1}$, the power of the three smooth tests deteriorates for small samples and large bandwidths. Indeed oversmoothing makes it difficult to detect highly variable pe-
riodic alternatives and bootstrap methods are not suitable to correct for this effect. However, the performance of all three tests highly improve for a moderate sample size of 250 . The comparison of Tables 1 and 2 indicates that the empirical power of the test based on $c_{n}^{* *}$ is also sensitive to the frequency of the alternative.

Results under alternative $D G P_{3}$ (Table 3) confirm these first findings. For bandwidths constants greater than 1.5, the three smooth tests perform poorly even for a sample size of 250 . However, their empirical power is acceptable in small samples for a bandwidth constant less than 1 and close to 1 for a sample size of 250 . The empirical power curve of these tests exhibits an inverse $U$ shape with respect to the smoothing number, with a maximum attained by undersmoothing relative to the rule-of-thumb. This fact has already be noted for other smooth specification tests, see Hart (1996). The test based on $c_{n}^{*}$ has low power for samples of size 50 and 100 . This is partly corrected by the bootstrap analog version of the empirical process based test.

To sum up, our results call for some caution in using plug-in bootstrap tests. For the smooth test, large undersmoothing is required to obtain good size and power properties. For the empirical process test, moderate sample sizes are necessary. In contrast, the bootstrap analogs of these tests appear to enjoy much better properties, though they are computationally more demanding. The bootstrap analog of the smooth test is able to correct for too small empirical sizes of the asymptotic test, and this for a large range of bandwidths. Therefore, only power considerations should drive the choice of the bandwidth parameter for the analog bootstrap tests. For alternatives of varying frequencies, slight undersmoothing with respect to the usual rule-of-thumb seems on the whole to lead to better results. Similarly, among the empirical process based tests, the analog bootstrap form appears to enjoy an accurate size and good empirical power under alternatives with different frequencies.

## APPENDIX

Henceforth, $\psi_{i}^{(k)}=\psi_{i}^{(k)}\left(\theta_{0}\right), \hat{\psi}_{i}^{(k)}=\psi_{i}^{(k)}\left(\hat{\theta}_{n}\right), \dot{\psi}_{i}^{(k)}=\dot{\psi}_{i}^{(k)}\left(\theta_{0}\right)$.

## PROOF OF LEMMA 1

Notice that $T_{n}=\sum_{k=1}^{m} T_{n}^{(k)}$, where

$$
T_{n}^{(k)}=\binom{n}{2}^{-1} \sum_{i=1}^{n-1} \sum_{j=i+1}^{n} H_{n}^{(k)}\left(Z_{i}, Z_{j}\right)+2 V_{1 n}^{(k)}+V_{2 n}^{(k)},
$$

and $H_{n}^{(k)}\left(Z_{i}, Z_{j}\right)=h^{-q} \psi_{i}^{(k)} \psi_{j}^{(k)} K_{i j}$,

$$
\begin{aligned}
& V_{1 n}^{(k)}=\frac{1}{n(n-1) h^{q}} \sum_{\substack{i=1}}^{n} \sum_{\substack{j=1 \\
j \neq i}}^{n} \psi_{i}^{(k)}\left(\hat{\psi}_{j}^{(k)}-\psi_{j}^{(k)}\right) K_{i j}, \\
& V_{2 n}^{(k)}=\frac{1}{n(n-1) h^{q}} \sum_{i=1}^{n} \sum_{\substack{j=1 \\
j \neq i}}^{n}\left(\hat{\psi}_{i}^{(k)}-\psi_{i}^{(k)}\right)\left(\hat{\psi}_{j}^{(k)}-\psi_{j}^{(k)}\right) K_{i j} .
\end{aligned}
$$

Hence, it suffices to prove that $V_{1 n}^{(k)}=O_{p}\left(n^{-1}\right)$ and $V_{2 n}^{(k)}=O_{p}\left(n^{-1}\right)$, for all $k=1, \ldots, m$.

Using a mean value theorem argument,

$$
V_{1 n}^{(k)}=\left(\hat{\theta}_{n}-\theta\right)^{\prime} S_{1 n}+\left(\hat{\theta}_{n}-\theta_{0}\right)^{\prime} S_{2 n}\left(\hat{\theta}_{n}-\theta_{0}\right),
$$

where

$$
\begin{aligned}
& S_{1 n}=\frac{1}{n(n-1) h^{q}} \sum_{i=1}^{n} \sum_{\substack{j=1 \\
j \neq i}}^{n} \psi_{i}^{(k)} \dot{\psi}_{j}^{(k)} K_{i j}, \\
& S_{2 n}=\frac{1}{n(n-1) h^{q}} \sum_{\substack{i=1}}^{n} \sum_{\substack{=1 \\
j \neq i}}^{n} \psi_{i}^{(k)} \ddot{\psi}_{j}^{(k)}\left(\bar{\theta}_{n}\right) K_{i j},\left\|\bar{\theta}_{n}-\theta_{0}\right\| \leq\left\|\hat{\theta}_{n}-\theta_{0}\right\| .
\end{aligned}
$$

The order of $S_{1 n}$ is obtained applying Lemma 3.1 of Powell, Stock and Stocker (1989), which is reported below.

Lemma 3 Consider a $U$-statistic of the form $U_{n}=\binom{n}{2}^{-1} \sum_{i=1}^{n-1} \sum_{j=i+1}^{n} H_{n}\left(Z_{i}, Z_{j}\right)$, where $H_{n}\left(Z_{i}, Z_{j}\right)$ is a symmetric kernel and the $Z_{i}$ s are iids observations. Let $q_{n}\left(Z_{i}\right)=E\left[H_{n}\left(Z_{i}, Z_{j}\right) \mid Z_{i}\right], \bar{q}_{n}=E\left(q_{n}\left(Z_{i}\right)\right)$ and $\hat{U}_{n}=\bar{q}_{n}+2 n^{-1} \sum_{i=1}^{n}\left[q_{n}\left(Z_{i}\right)-\bar{q}_{n}\right]$. If $E\left(\left\|H_{n}\left(Z_{1}, Z_{2}\right)\right\|^{2}\right)=o(n)$, then $U_{n}=\hat{U}_{n}+o_{p}\left(n^{-1 / 2}\right)$.

Since $S_{1 n}$ is a $U$-statistic with symmetric kernel

$$
H_{n}\left(Z_{1}, Z_{2}\right)=\left(h^{-q} \psi_{1}^{(k)} \dot{\psi}_{2}^{(k)} K_{12}+h^{-q} \psi_{2}^{(k)} \dot{\psi}_{1}^{(k)} K_{12}\right) / 2
$$

we have

$$
\begin{aligned}
E\left(\left\|H_{n}\left(Z_{1}, Z_{2}\right)\right\|^{2}\right) & =\frac{1}{h^{2 q}} E\left[\left(\dot{\psi}_{1}^{(k)}\right)^{2}\left(\psi_{2}^{(k)}\right)^{2} K_{12}^{2}\right] \\
& =\frac{1}{h^{q}} E\left[\left(\dot{\psi}_{1}^{(k)}\right)^{2} \int \sigma_{k k}\left(X_{1}+h u\right) f\left(X_{1}+h u\right) K(u)^{2} d u\right] \\
& =\frac{1}{h^{q}} E\left[\left(\dot{\psi}_{1}^{(k)}\right)^{2} \sigma_{k k}\left(X_{1}\right)\right] \int K(u)^{2} d u+o\left(\frac{1}{h^{q}}\right) \\
& =O\left(\frac{1}{h^{q}}\right)=o(n)
\end{aligned}
$$

by Assumptions $B$ and $S$, together with Hölder's inequality. As $\bar{q}_{n}=0$, we obtain by Lemma 3

$$
S_{1 n}=\frac{2}{n} \sum_{i=1}^{n} q_{n}\left(Z_{i}\right)+o_{p}\left(n^{-1 / 2}\right)
$$

with $q_{n}\left(Z_{i}\right)=h^{-q}\left(\psi_{i}^{(k)} E\left[\gamma_{k}\left(X_{j}\right) K_{i j} \mid X_{i}\right]+E\left[\psi_{j}^{(k)} K_{i j} \mid X_{i}\right] \gamma_{k}\left(X_{i}\right)\right) / 2$. Now it is easy to check that

$$
E\left[q_{n}^{2}(Z)\right]=E\left[\sigma_{k k}(X) \gamma_{k}^{2}(X) f(X)\right] \int K(u) d u+o(1)=O(1)
$$

so that $S_{1 n}=O_{p}\left(n^{-1 / 2}\right)$ by applying a central limit theorem argument. The order of $S_{2 n}$ is obtained using Assumptions $A 2$ and $S$ and applying standard kernel manipulations as follows:

$$
\begin{aligned}
E\left|S_{2 n}\right| & \leq \frac{1}{h^{q}} E\left\{\left|\psi_{1}^{(k)}\right| N\left(Y_{2}, X_{2}\right)\left|K_{12}\right|\right\} \\
& =\frac{1}{h^{q}} E\left\{N\left(Y_{2}, X_{2}\right) E\left[\alpha_{k}\left(X_{1}\right)\left|K_{12}\right| \mid Z_{2}\right]\right\} \\
& =E\left\{N\left(Y_{2,} X_{2}\right) \alpha_{k}\left(X_{2}\right) f\left(X_{2}\right)\right\} \int|K(u)| d u+o(1) \\
& =O(1)
\end{aligned}
$$

Hence, we obtain $V_{1 n}^{(k)}=O_{p}\left(n^{-1}\right)$ by Assumption $A 1$.
Using a mean value theorem argument,

$$
V_{2 n}^{(k)}=\left(\hat{\theta}_{n}-\theta_{0}\right)^{\prime} S_{3 n}\left(\hat{\theta}_{n}-\theta_{0}\right)
$$

where

$$
\begin{gathered}
S_{3 n}=\frac{1}{n(n-1) h^{q}} \sum_{\substack{i=1}}^{n} \sum_{\substack{j=1 \\
j \neq i}}^{n}\left[\dot{\psi}_{i}^{(k)}+\ddot{\psi}_{i}^{(k)}\left(\bar{\theta}_{n}\right)\left(\hat{\theta}_{n}-\theta_{0}\right)\right]\left[\dot{\psi}_{j}^{(k)}+\ddot{\psi}_{j}^{(k)}\left(\bar{\theta}_{n}\right)\left(\hat{\theta}_{n}-\theta_{0}\right)\right]^{\prime} K_{i j}, \\
\left\|\bar{\theta}_{n}-\theta_{0}\right\| \leq\left\|\hat{\theta}_{n}-\theta_{0}\right\| \text { and }\left\|\overline{\hat{\theta}}_{n}-\theta_{0}\right\| \leq\left\|\hat{\theta}_{n}-\theta_{0}\right\|
\end{gathered}
$$

We can decompose $S_{3 n}$ in different terms, and reasoning as before it is easy to check that $S_{3 n}=O_{p}(1)$, so that $V_{2 n}^{(k)}=O_{p}\left(n^{-1}\right)$.

## PROOF OF THEOREM 1

By Lemma 1,

$$
\begin{equation*}
n h^{q / 2} T_{n}=n h^{q / 2}\binom{n}{2}^{-1} \sum_{i=1}^{n-1} \sum_{j=i+1}^{n} h^{-q} \sum_{k=1}^{m} \psi_{1}^{(k)} \psi_{2}^{(k)} K_{12}+O\left(h^{q / 2}\right) \tag{9}
\end{equation*}
$$

Therefore, by Assumption $B$, it suffices to establish the asymptotic normality of the first term in (9). Lemma 3 is useless now, because we have a degenerated $U$-statistic. Thus, we make use of a result for degenerate $U$-statistic, which is stated below.

Lemma 4 (Hall, 1984) Let $U_{n}$ be as in Lemma 3, where $E\left[H_{n}\left(Z_{i}, Z_{j}\right) \mid Z_{i}\right]=$ 0 a.s. Define $G_{n}\left(Z_{1}, Z_{2}\right)=E\left[H_{n}\left(Z_{3}, Z_{1}\right) H_{n}\left(Z_{3}, Z_{2}\right) \mid Z_{1}, Z_{2}\right]$. If

$$
\lim _{n \rightarrow \infty} \frac{E\left[G_{n}\left(Z_{1}, Z_{2}\right)^{2}\right]+n^{-1} E\left[H_{n}\left(Z_{1}, Z_{2}\right)^{4}\right]}{\left\{E\left[H_{n}\left(Z_{1}, Z_{2}\right)^{2}\right]\right\}^{2}}=0
$$

then

$$
\frac{n U_{n}}{2\left\{E\left[H_{n}\left(Z_{1}, Z_{2}\right)^{2}\right]\right\}^{1 / 2}} \stackrel{d}{\rightarrow} N(0,1) .
$$

In our case, $H_{n}\left(Z_{1}, Z_{2}\right)=h^{-q} \sum_{k=1}^{m} \psi_{1}^{(k)} \psi_{2}^{(k)} K_{12}$. First,

$$
E\left[G_{n}\left(Z_{1}, Z_{2}\right)^{2}\right]=\sum_{k=1}^{m} \sum_{l=1}^{m} \sum_{k^{\prime}=1}^{m} \sum_{l^{\prime}=1}^{m} \lambda_{k k^{\prime} l^{\prime}}
$$

where each $\lambda_{k k^{\prime}} l^{\prime}$ is equal to

$$
\begin{aligned}
& h^{-4 q} E\left\{\sigma_{k k^{\prime}}\left(X_{1}\right) \sigma_{l^{\prime}}\left(X_{2}\right) E\left[K_{13} K_{23} \sigma_{k l}\left(X_{3}\right) \mid X_{1}, X_{2}\right] E\left[K_{13} K_{23} \sigma_{k^{\prime} l^{\prime}}\left(X_{3}\right) \mid X_{1}, X_{2}\right]\right\} \\
& =\frac{1}{h^{2 q}} E\left\{\sigma_{k k^{\prime}}\left(X_{1}\right) \sigma_{u^{\prime}}\left(X_{2}\right)\left[\int K(u) K\left(u+\frac{X_{2}-X_{1}}{h}\right) \sigma_{k l}\left(X_{1}+h u\right) f\left(X_{1}+h u\right) d u\right]\right. \\
& \left.\left[\int K\left(u^{\prime}\right) K\left(u^{\prime}+\frac{X_{2}-X_{1}}{h}\right) \sigma_{k^{\prime} l^{\prime}}\left(X_{1}+h u^{\prime}\right) f\left(X_{1}+h u^{\prime}\right) d u^{\prime}\right]\right\} \\
& =\frac{1}{h^{q}} E\left\{\sigma_{k k^{\prime}}\left(X_{1}\right) \sigma_{l^{\prime}}\left(X_{1}+h v\right)\left[\int K(u) K(u+v) \sigma_{k l}\left(X_{1}+h u\right) f\left(X_{1}+h u\right) d u\right]\right. \\
& \left.\left[\int K\left(u^{\prime}\right) K\left(u^{\prime}+v\right) \sigma_{k^{\prime} l^{\prime}}\left(X_{1}+h u^{\prime}\right) f\left(X_{1}+h u^{\prime}\right) d u^{\prime}\right] f\left(X_{1}+h v\right) d v\right\} \\
& =\frac{1}{h^{q}} E\left\{\sigma_{k k^{\prime}}\left(X_{1}\right) \sigma_{u^{\prime}}\left(X_{1}\right) \sigma_{k l}\left(X_{1}\right) \sigma_{k^{\prime} l^{\prime}}\left(X_{1}\right) f^{3}\left(X_{1}\right)\right\} \\
& {\left[\iiint K(u) K(u+v) K\left(u^{\prime}\right) K\left(u^{\prime}+v\right) d u d u^{\prime} d v\right]+o\left(h^{-q}\right)} \\
& =O\left(\frac{1}{h^{q}}\right),
\end{aligned}
$$

using Assumption $S$. Second,

$$
\begin{aligned}
& E\left[H_{n}\left(Z_{1}, Z_{2}\right)^{2}\right] \\
& =\sum_{k=1}^{m} \sum_{l=1}^{m} \frac{1}{h^{2 q}} E\left(K\left(\frac{X_{1}-X_{2}}{h}\right)^{2} \sigma_{k l}\left(X_{1}\right) \sigma_{k l}\left(X_{2}\right)\right) \\
& =\sum_{k=1}^{m} \sum_{l=1}^{m} \frac{1}{h^{q}} E\left(\sigma_{k l}\left(X_{1}\right) \int K(u)^{2} \sigma_{k l}\left(X_{1}+h u\right) f\left(X_{1}+h u\right) d u\right) \\
& =\sum_{k=1}^{m} \sum_{l=1}^{m} \frac{1}{h^{q}} E\left[\sigma_{k l}^{2}\left(X_{1}\right) f\left(X_{1}\right)\right] \int K(u)^{2} d u+o\left(h^{-q}\right)=O\left(\frac{1}{h^{q}}\right) .
\end{aligned}
$$

Third, denoting $K\left[\left(X_{1}-X_{2}\right) / h\right]$ by $K_{12}$,

$$
\begin{aligned}
& E\left[H_{n}\left(Z_{1}, Z_{2}\right)^{4}\right] \\
& =\sum_{k=1}^{m} \sum_{l=1}^{m} \sum_{k^{\prime}=1}^{m} \sum_{l^{\prime}=1}^{m} \frac{1}{h^{4 q}} E\left[K_{12}^{4} \psi_{1}^{(k)} \psi_{2}^{(k)} \psi_{1}^{\left(k^{\prime}\right)} \psi_{2}^{\left(k^{\prime}\right)} \psi_{1}^{(l)} \psi_{2}^{(l)} \psi_{1}^{\left(l^{\prime}\right)} \psi_{2}^{\left(l^{\prime}\right)}\right] \\
& \leq \sum_{k=1}^{m} \sum_{l=1}^{m} \sum_{k^{\prime}=1}^{m} \sum_{l^{\prime}=1}^{m} \frac{1}{h^{3 q}} \prod_{p \in\left\{k, l, k^{\prime}, l^{\prime}\right\}}\left\{E\left[h^{-q} K_{12}^{4} \sigma_{p}^{4}\left(X_{1}\right) \sigma_{p}^{4}\left(X_{2}\right)\right]\right\}^{1 / 4} \\
& \leq \sum_{k=1}^{m} \sum_{l=1}^{m} \sum_{k^{\prime}=1}^{m} \sum_{l^{\prime}=1}^{m} \frac{1}{h^{3 q}} \prod_{p \in\left\{k, l, k^{\prime}, l^{\prime}\right\}}\left\{E\left[\sigma_{p}^{4}\left(X_{1}\right) \sigma_{p}^{4}\left(X_{1}\right) f\left(X_{1}\right)\right]\right\}^{1 / 4}+o\left(h^{-3 q}\right) \\
& \leq O\left(\frac{1}{h^{3 q}}\right) .
\end{aligned}
$$

Therefore,
$\lim _{n \rightarrow \infty} \frac{E\left[G_{n}\left(Z_{1}, Z_{2}\right)^{2}\right]+n^{-1} E\left[H_{n}\left(Z_{1}, Z_{2}\right)^{4}\right]}{\left\{E\left[H_{n}\left(Z_{1}, Z_{2}\right)^{2}\right]\right\}^{2}}=\lim _{n \rightarrow \infty}\left(h^{q}+\left(n h^{q}\right)^{-1}\right)=o(1)$,
by Assumption $B$, and Lemma 4 allows to conclude.

## PROOF OF COROLLARY 1

Let us first consider the properties of $T_{n}$ under $H_{1}$. Notice that $T_{n}=$ $\sum_{k=1}^{m} T_{n}^{(k)}$, where

$$
T_{n}^{(k)}=\binom{n}{2}^{-1} \sum_{i=1}^{n-1} \sum_{j=i+1}^{n} H_{n}^{(k)}\left(Z_{i}, Z_{j}\right)+2 V_{1 n}^{(k)}+V_{2 n}^{(k)}
$$

and $H_{n}^{(k)}\left(Z_{i}, Z_{j}\right)=h^{-q} \psi_{i}^{(k)}\left(\theta_{1}\right) \psi_{j}^{(k)}\left(\theta_{1}\right) K_{i j}$,

$$
\begin{aligned}
V_{1 n}^{(k)} & =\frac{1}{n(n-1) h^{q}} \sum_{i=1}^{n} \sum_{\substack{j=1 \\
j \neq i}}^{n} \psi_{i}^{(k)}\left(\theta_{1}\right)\left(\hat{\psi}_{j}^{(k)}-\psi_{j}^{(k)}\left(\theta_{1}\right)\right) K_{i j} \\
V_{2 n}^{(k)} & =\frac{1}{n(n-1) h^{q}} \sum_{i=1}^{n} \sum_{\substack{j=1 \\
j \neq i}}^{n}\left(\hat{\psi}_{i}^{(k)}-\psi_{i}^{(k)}\left(\theta_{1}\right)\right)\left(\hat{\psi}_{j}^{(k)}-\psi_{j}^{(k)}\left(\theta_{1}\right)\right) K_{i j}
\end{aligned}
$$

Reasoning as in the proof of Lemma 1 and using $A 1$ with $\theta_{1}$ in place of $\theta_{0}$, we can easily show that $V_{1 n}^{(k)}=o_{p}(1)$ and $V_{2 n}^{(k)}=o_{p}(1)$, all $k=1, \ldots, m$. Now using Lemma 3 and a central limit theorem argument, we have

$$
\begin{aligned}
& \sum_{k=1}^{m}\binom{n}{2}^{-1} \sum_{i=1}^{n} \sum_{j=i+1}^{n-1} H_{n}^{(k)}\left(Z_{i}, Z_{j}\right) \\
& =\sum_{k=1}^{m} E\left[H_{n}^{(k)}\left(Z_{i}, Z_{j}\right)\right]+O_{p}\left(n^{-1 / 2}\right) \\
& =\sum_{k=1}^{m} E\left[E^{2}\left[\psi^{(k)}\left(Y, X ; \theta_{1}\right) \mid X\right] f(X)\right] \int K(u) d u+O_{p}\left(n^{-1 / 2}\right)
\end{aligned}
$$

This shows that $T_{n}$ converges to a strictly positive limit under $H_{1}$.
By a similar reasoning, it is easily shown that, either under $H_{0}$ or $H_{1}$,

$$
\hat{V}_{n}=\frac{2}{n(n-1) h^{q}} \sum_{k=1}^{m} \sum_{l=1}^{m} \sum_{i=1}^{n} \sum_{\substack{j=1 \\ j \neq i}}^{n} \widehat{\psi}_{i}^{(k)} \widehat{\psi}_{i}^{(l)} \widehat{\psi}_{j}^{(k)} \widehat{\psi}_{j}^{(l)} K_{i j}^{2}=V+o_{p}(1)
$$

## Corollary 1 then follows.

## PROOF OF LEMMA 2

Lemma 2 follows straightforwardly after applying a mean value theorem argument, the Lindeberg-Levy central limit theorem and the strong law of large numbers.

## PROOF OF THEOREM 2

The convergence of the finite dimensional distributions of $R_{n}$ (.) follows from Lemma 2 and applying the Linderberg-Levy central limit theorem. Thus, the theorem follows by proving tightness.

Let $D_{1}=(s, t]=x_{k=1}^{q}\left(s_{j}, t_{j}\right], D_{2}=\left(s^{\prime}, t^{\prime}\right]=x_{k=1}^{q}\left(s_{j}^{\prime}, t_{j}^{\prime}\right]$ two neighbors intervals in $\mathbb{R}^{q}$, i.e., they abut and for some $j \in\{1,2, . ., q\}$, they have the same $j$ th-face $x_{k \neq j}\left(s_{k}, t_{k}\right]=x_{k \neq j}\left(s_{k}^{\prime}, t_{k}^{\prime}\right]$. Let $W_{n}(t)$ be any empirical process on $D\left[\mathbb{R}^{q}\right]$. Define
$W_{n}\left(D_{1}\right)=\sum_{e_{1}=0,1} \cdots \sum_{e_{q}=0,1}(-1)^{q-\sum_{p} e_{p}} W_{n}\left(s_{1}+e_{1}\left(t_{1}-s_{1}\right), \cdots, s_{q}+e_{q}\left(t_{q}-s_{q}\right)\right)$.

By Condition (2.1.8) in Gaenssler and Stute (1979), a sufficient condition for tightness in $D\left[\mathbb{R}^{q}\right]$ is

$$
\begin{equation*}
\operatorname{Pr}\left(\left|W_{n}\left(D_{1}\right)\right|>\delta ;\left|W_{n}\left(D_{2}\right)\right|>\delta\right) \leq C \delta^{-a}\left(\mu\left(D_{1} \cup D_{2}\right)\right)^{b} \tag{11}
\end{equation*}
$$

where $\mu(\cdot)$ is an arbitrary measure with continuous marginals and $a, b$ and $C$ are arbitrary constants such that $b>1$ and $C \geq 0$. Using Markov inequality, a sufficient condition for (11) is

$$
\begin{equation*}
E\left(\left|W_{n}\left(D_{1}\right)\right|\left|W_{n}\left(D_{2}\right)\right|\right)^{2} \leq C\left(\mu\left(D_{1} \cup D_{2}\right)\right)^{b} \tag{12}
\end{equation*}
$$

Without loss of generality we will prove tightness for $q=2$. From Lemma 2, we can write

$$
R_{n}(t)=R_{n}^{0}(t)+R_{n}^{1}(t),
$$

where

$$
\begin{aligned}
& R_{n}^{0}(t)=\frac{1}{n} \sum_{i=1}^{n} \psi_{i} \Delta_{i}(t) \\
& R_{n}^{1}(t)=E\left[\dot{\psi}_{i}\left(\theta_{0}\right) \Delta_{i}(t)\right] \frac{1}{n} \sum_{i=1}^{n} l\left(Y_{i}, X_{i} ; \theta_{0}\right)
\end{aligned}
$$

with $k$-th coordinate denoted by $R_{n}^{j(k)}, j=0,1$, i.e. $R_{n}^{0(k)}(t)=\frac{1}{n} \sum_{i=1}^{n} \psi_{i}^{(k)} \Delta_{i}(t)$, and $R_{n}^{1(k)}(t)=E\left[\dot{\psi}_{i}^{(k)}\left(\theta_{0}\right) \Delta_{i}(t)\right] \frac{1}{n} \sum_{i=1}^{n} l\left(Y_{i}, X_{i} ; \theta_{0}\right)$, where $\dot{\psi}_{i}^{(k)}\left(\theta_{0}\right)$ is the $k$-th row in $\dot{\psi}_{i}\left(\theta_{0}\right)$. Then, applying definition in (10) to $R_{n}^{0(k)}($.$) ,$

$$
\begin{align*}
\sqrt{n} R_{n}^{0(k)}\left(D_{1}\right) & =\frac{1}{\sqrt{n}} \sum_{i=1}^{n} \psi_{i}^{(k)}\left(\Delta_{i}\left(t_{1}, t_{2}\right)-\Delta_{i}\left(s_{1}, t_{2}\right)-\Delta_{i}\left(t_{1}, s_{2}\right)+\Delta_{i}\left(s_{1}, s_{2}\right)\right) \\
& =\frac{1}{\sqrt{n}} \sum_{i=1}^{n} \psi_{i}^{(k)} \Delta_{i}\left(D_{1}\right) \tag{13}
\end{align*}
$$

where $\Delta_{i}\left(D_{j}\right)=1\left(X_{i} \in D_{j}\right)$. Lemma 5.1 in Stute (1997) assures that if $\left\{\left(\alpha_{i}, \beta_{i}\right)\right\}_{i=1}^{n}$ are $n$ iid square integrable random vectors with $E\left(\alpha_{1}\right)=E\left(\beta_{1}\right)=0$, then

$$
\begin{equation*}
E\left(\left(\sum_{i=1}^{n} \alpha_{i}\right)^{2}\left(\sum_{i=1}^{n} \beta_{i}\right)^{2}\right) \leq n E\left(\alpha_{1}^{2} \beta_{1}^{2}\right)+3 n(n-1) E\left(\alpha_{1}^{2}\right) E\left(\beta_{1}^{2}\right) \tag{14}
\end{equation*}
$$

Let $\alpha_{i}=\psi_{i}^{(k)} \Delta_{i}\left(D_{1}\right)$ and $\beta_{i}=\psi_{i}^{(k)} \Delta_{i}\left(D_{2}\right)$, then $\alpha_{1}^{2} \beta_{1}^{2}=0$ and applying (14) we get

$$
\begin{aligned}
n^{2} E\left(\left(R_{n}^{0(k)}\left(D_{1}\right)\right)^{2}\left(R_{l n}^{0(k)}\left(D_{2}\right)\right)^{2}\right) & \leq \frac{3 n(n-1)}{n^{2}} E\left(\psi_{1}^{(k)} \Delta_{1}\left(D_{1}\right)\right)^{2} E\left(\psi_{1}^{(k)} \Delta_{1}\left(D_{2}\right)\right)^{2} \\
& \leq 3\left(E\left(\left[\psi_{1}^{(k)}\right]^{2} \Delta_{1}\left(D_{1} \cup D_{2}\right)\right)\right)^{2} .
\end{aligned}
$$

Then (12) holds for $R_{n}^{0(k)}($.$) and this process is tight for arbitrary k=1, . ., m$. Because the index parameter in $R_{n}^{1(k)}(t)$ is included in a deterministic continuous bounded function, it is straightforward to check that it is tight.

Recall that a sequence of stochastic process $\left\{W_{n}, n=1, \ldots,+\infty\right\}$ is said to be tight if and only if for every $\varepsilon>0$, there exists a compact set $K$ such that $\sup _{n} \operatorname{Pr}\left\{W_{n} \in K\right\}>1-\varepsilon$, i.e. if there exists a compact set of the sample space where the process is included, with arbitrary high probability uniformly in $n$. Let $K^{j(k)}$ be the compact sets that includes each $R_{n}^{j(k)}($.$) with arbitrary high$ probability, $j=0,1, k=1, \ldots, m$. By Tychonoff Theorem (see Dudley, 1989, Th 2.2.8), the set $K^{(k)}=\left\{c^{(k)}=\left(c^{0}, c^{1}\right): c^{j} \in K^{j(k)}, j=1,2\right\}$ is compact within the product topology. Because summation is a continuous operator in $D\left[\mathbb{R}^{q}\right]$, it preserves compactness and the set $K^{(k)+}=\left\{c^{(k)+}=c^{0}+c^{1}:\left(c^{0}, c^{1}\right) \in K^{(k)}\right\}$ is compact. Therefore, the process $R_{n}^{(k)}($.$) is tight. By Tychonoff Theorem$ again, the set $K=\left\{c=\left(c^{(1)+}, c^{(2)+}, . ., c^{(m)+}\right): c^{(k)+} \in K^{(k)+}, k=1, \ldots, m\right\}$ is compact within the product topology. Since $R_{n}(t) \in K$ with arbitrary high probability uniformly in $n$, it is tight and the proof is completed.

## PROOF OF THEOREM 3

Henceforth, $\psi_{i}^{*(k)}=V_{i} \psi_{i}^{(k)}\left(\theta_{0}\right)$ and $\hat{\psi}_{i}^{*(k)}=V_{i} \psi_{i}^{(k)}(\hat{\theta})$ and $E^{*}[.] \equiv E\left[. \mid \mathcal{Y}_{n}\right]$. Notice that $T_{n}^{*}=\sum_{k=1}^{m} T_{n}^{*(k)}$, where

$$
T_{n}^{*(k)}=\widetilde{T}_{n}^{*(k)}+2 V_{1 n}^{*(k)}+V_{2 n}^{*(k)},
$$

where

$$
\begin{aligned}
& \tilde{T}_{n}^{*(k)}=\binom{n}{2}^{-1} \sum_{i=1}^{n-1} \sum_{j=i+1}^{n} h_{j}^{-q} \psi_{i}^{*(k)} \psi_{j}^{*(k)} K_{i j}, \\
& V_{1 n}^{*(k)}=\frac{1}{n(n-1) h^{q}} \sum_{i=1}^{n} \sum_{\substack{j=1 \\
j \neq i}}^{n} \psi_{i}^{*(k)}\left(\widehat{\psi}_{j}^{*(k)}-\psi_{j}^{*(k)}\right) K_{i j}, \\
& V_{2 n}^{*(k)}=\frac{1}{n(n-1) h^{q}} \sum_{i=1}^{n} \sum_{\substack{j=1 \\
j \neq i}}^{n}\left(\widehat{\psi}_{i}^{*(k)}-\psi_{i}^{*(k)}\right)\left(\hat{\psi}_{j}^{*}(k)-\psi_{j}^{*(k)}\right) K_{i j} .
\end{aligned}
$$

We will prove that $V_{1 n}^{*(k)}=O_{p} .\left(n^{-1}\right)$ and $V_{2 n}^{*(k)}=O_{p} .\left(n^{-1}\right)$ in probability for all $k=1, \ldots, m$. Using a mean value theorem argument,

$$
V_{1 n}^{*(k)}=\left(\hat{\theta}_{n}-\theta_{0}\right)^{\prime} S_{1 n}^{*}+\left(\hat{\theta}_{n}-\theta_{0}\right)^{\prime} S_{2 n}^{*}\left(\hat{\theta}_{n}-\theta_{0}\right),
$$

where

$$
\begin{aligned}
& S_{1 n}^{*}=\frac{1}{n(n-1) h^{q}} \sum_{\substack{i=1}}^{n} \sum_{\substack{j=1 \\
j \neq i}}^{n} \psi_{i}^{*(k)} \dot{\psi}_{j}^{*(k)} K_{i j}, \\
& S_{2 n}^{*}=\frac{1}{n(n-1) h^{q}} \sum_{\substack{i=1}}^{n} \sum_{\substack{j=1 \\
j \neq i}}^{n} \psi_{i}^{*(k)} \ddot{\psi}_{j}^{*(k)}\left(\bar{\theta}_{n}\right) K_{i j},\left\|\bar{\theta}_{n}-\theta_{0}\right\| \leq\left\|\hat{\theta}_{n}-\theta_{0}\right\|,
\end{aligned}
$$

$\dot{\psi}_{j}^{*(k)}=\dot{\psi}_{j}^{(k)} V_{j}$, and $\ddot{\psi}_{j}^{(k)}(\theta)=\ddot{\psi}^{(k)}\left(Y_{j}^{*}, X_{j} ; \theta\right) V_{j}$. Since $E^{*}\left(V_{j} V_{j}\right)=0$ for $j \neq j, S_{1 n}^{*}$ and $S_{2 n}^{*}$ are degenerate $U$-statistics. Hence, $E^{*}\left[S_{1 n}^{*}\right]=0$ and

$$
\begin{aligned}
E^{*}\left[S_{1 n}^{*}\right] & =\left[\frac{1}{n(n-1) h^{q}}\right]^{2} \sum_{i=1}^{n} \sum_{\substack{j=1 \\
j \neq i}}^{n} E^{*}\left[\psi_{i}^{*(k)} \dot{\psi}_{j}^{*(k)} K_{i j}\right]^{2} \\
& =\left[\frac{1}{n(n-1) h^{q}}\right]^{2} \sum_{i=1}^{n} \sum_{\substack{j=1 \\
j \neq i}}^{n}\left(\psi_{i}^{(k)}\right)^{2}\left(\dot{\psi}_{j}^{(k)}\right)^{2} K_{i j} .
\end{aligned}
$$

Now, using similar arguments than in the proof of Lemma 1,

$$
E\left[E^{*}\left[S_{1 n}^{* 2}\right]\right]=\left[\frac{1}{n(n-1) h^{q}}\right]^{2} n(n-1) O\left(h^{q}\right)=O\left(n^{-2} h^{-q}\right)
$$

so that $S_{1 n}^{*}=O_{p^{*}}\left(n^{-1} h^{-q / 2}\right)$ in probability. Similarly, we can prove that $E^{*}\left|S_{2 n}^{*}\right|=O_{p^{*}}$ (1) in probability, so that $S_{2 n}^{*}=O_{p^{*}}$ (1) in probability. As $\left(\hat{\theta}-\theta_{0}\right)=O_{p}\left(n^{-1 / 2}\right)$, we get that $n h^{q / 2} V_{1 n}^{*(k)}=o_{p^{-}}$(1) in probability. Similarly, $n h^{q / 2} V_{2 n}^{*(k)}=o_{p^{*}}$ (1) in probability.

Concerning asymptotic normality, we will treat the case where $m=1$ for the sake of simplicity, so that we consider

$$
\widetilde{T}_{n}^{*}=\binom{n}{2}^{-1} \sum_{i=1}^{n-1} \sum_{j=i+1}^{n} H_{n}^{*}\left(Z_{i}, Z_{j}\right)=\binom{n}{2}^{-1} \sum_{i=1}^{n-1} \sum_{j=i+1}^{n} h_{j}^{-q} \psi_{i}^{*} \psi_{j}^{*} K_{i j},
$$

Notice that $E^{*}\left[H_{n}^{*}\left(Z_{i}, Z_{j}\right) \mid V_{i}\right]=0$, for all $i$. Let us define

$$
\begin{aligned}
& \sigma_{n}^{2} \equiv E^{*}\left[\widetilde{T}_{n}^{2}\right] \\
& =\binom{n}{2}^{-2} \sum_{i=1}^{n-1} \sum_{j=i+1}^{n} \sum_{i=1}^{n-1} \sum_{j=i+1}^{n} E^{*}\left[H_{n}^{*}\left(Z_{i}, Z_{j}\right) H_{n}^{*}\left(Z_{i}, Z_{j}\right)\right] \\
& =\binom{n}{2}^{-2} \sum_{i=1}^{n} \sum_{j=1}^{n} h_{j}^{-2 q}\left(\psi_{i}\right)^{2}\left(\psi_{j}\right)^{2} K_{i j}^{2}=\frac{1}{n(n-1) h^{q}} \widehat{V}_{n}, \\
& \\
& G_{1} \equiv\binom{n}{2}^{-4} \sum_{i=1}^{n-1} \sum_{j=i+1}^{n} E^{*}\left[H_{n}^{* 4}\left(Z_{i}, Z_{j}\right)\right] \\
& \\
& =E^{2}\left(V_{1}^{4}\right)\binom{n}{2}^{-4} \sum_{i=1}^{n-1} \sum_{j=i+1}^{n} h_{j}^{-4 q} \psi_{i}^{4} \psi_{j}^{4} K_{i j}^{4}, \\
& \\
& =\binom{n}{2}^{-4} \sum_{i=1}^{n-2} \sum_{j=i+1}^{n-1} \sum_{k=j+1}^{n} E^{*}\left[V_{1}^{4}\right)\binom{n}{2}^{-4} \sum_{i=1}^{n-2} \sum_{j=i+1}^{n-1} \sum_{k=j+1}^{n} h_{j}^{-4 q} \psi_{i}^{4} \psi_{j}^{2} \psi_{k}^{2} K_{i j}^{2} K_{i k}^{2}, \\
& \left.G_{3}\left(Z_{i}, Z_{k}\right)\right] \\
& \equiv\binom{n}{2}^{-4} \sum_{i=1}^{n-3} \sum_{j=i+1}^{n-2} \sum_{k=j+1}^{n-1} \sum_{l=k+1}^{n} E^{*}\left[H_{n}^{*}\left(Z_{i}, Z_{j}\right) H_{n}^{*}\left(Z_{i}, Z_{k}\right) H_{n}^{*}\left(Z_{l}, Z_{j}\right) H_{n}^{*}\left(Z_{l}, Z_{k}\right)\right] \\
& =\binom{n}{2}^{-4} \sum_{i=1}^{n-3} \sum_{j=i+1}^{n-2} \sum_{k=j+1}^{n-1} \sum_{l=k+1}^{n} h_{j}^{-4 q} \psi_{i}^{2} \psi_{j}^{2} \psi_{k}^{2} \psi_{l}^{2} K_{i j} K_{i k} K_{l j} K_{l k} .
\end{aligned}
$$

By Proposition 3.2 in De Jong (1987), we have $\sigma_{n}^{-1} \tilde{T}_{n}^{*} \xrightarrow{d^{*}} N(0,1)$ in probability if $G_{1}, G_{2}$ and $G_{3}$ are of lower order in probability than $\left(\sigma_{n}^{2}\right)^{2}$. Now, $G_{1}, G_{2}$ and $\left(\sigma_{n}^{2}\right)^{2}$ are positive and it is not difficult to check, as in the proof of Theorem 1 , that

$$
\begin{aligned}
E\left[\left(\sigma_{n}^{2}\right)^{2}\right] & =E\left[\binom{n}{2}^{-2} \sum_{\substack{i=1}}^{n} \sum_{\substack{j=1 \\
j \neq i}}^{n} h_{j}^{-2 q}\left(\psi_{i}\right)^{2}\left(\psi_{j}\right)^{2} K_{i j}^{2}\right]^{2} \\
& =n^{-8} O\left[n^{2} h^{-3 q}+n^{3} h^{-2 q}+n^{4} h^{-2 q}\right]=O\left(n^{-4} h^{-2 q}\right), \\
E\left[G_{1}\right] & =O\left(n^{-6} h^{-3 q}\right), \\
E\left[G_{2}\right] & =O\left(n^{-5} h^{-2 q}\right), \\
E\left|G_{3}\right| & =O\left(n^{-4} h^{-q}\right) .
\end{aligned}
$$

Hence, the condition is fulfilled and we get the desired result. It is straightforward while cumbersome to check the result for arbitrary $m$.

## PROOF OF THEOREM 4

Using the independence of the sequence $\left\{V_{i}\right\}$, we obtain the covariance structure

$$
n E^{*}\left(R_{n}^{*}\left(x_{1}\right) R_{n}^{*}\left(x_{2}\right)^{\prime}\right)=\frac{1}{n} \sum_{i=1}^{n} \hat{r}_{i}\left(x_{1}\right) \hat{r}_{i}\left(x_{2}\right)^{\prime}
$$

where $\hat{r}_{i}(x)=\hat{\psi}_{i} \Delta_{i}(x)+\left(\frac{1}{n} \sum_{i=1}^{n} \dot{\psi}_{i}\left(\hat{\theta}_{n}\right) \Delta_{i}(x)\right) l\left(Y_{i}, X_{i} ; \hat{\theta}_{n}\right)$. By A2, Slutsky theorem and the strong law of large numbers,

$$
n E^{*}\left(R_{n}^{*}\left(x_{1}\right) R_{n}^{*}\left(x_{2}\right)^{\prime}\right) \xrightarrow{\text { a.s. }} E\left(r_{i}\left(x_{1}\right) r_{i}\left(x_{2}\right)^{\prime}\right),
$$

so the process has the same covariance structure. Let $\lambda \in \mathbb{R}^{m}$ such that $\|\lambda\|=1$. To obtain gaussianity, we check the conditions of the Lindeberg-Feller central limit theorem. Define

$$
\hat{r}_{i}^{*}(x)=\sigma(x) b_{n}(x) d_{i n}^{*}(x), \text { where } d_{i n}^{*}(x)=n^{-1 / 2} \lambda^{\prime} \hat{r}_{i}(x) V_{i} / \hat{\sigma}_{n}(x),
$$

$b_{n}(x)=\hat{\sigma}_{n}(x) / \sigma(x), \hat{\sigma}_{n}^{2}(x)=\lambda^{\prime} n^{-1} \sum_{i=1}^{n} \hat{r}_{i}(x) \hat{r}_{i}(x)^{\prime} \lambda$ and $\sigma^{2}(x)=\lambda^{\prime} E\left(r_{i}(x) r_{i}(x)^{\prime}\right) \lambda$. The triangular array $\left\{d_{i n}^{*}(x): i=1, \ldots, n, n=1, \ldots+\infty\right\}$ has rows elements that are independent conditionally on $\mathcal{Y}_{n}$, with

$$
E^{*}\left[d_{i n}^{*}(x)\right]=n^{-1 / 2} \lambda^{\prime} \hat{r}_{i}(x) E^{*}\left[V_{i}\right] / \hat{\sigma}_{n}(x)=0 \text { a.s. }
$$

and

$$
\operatorname{Var}^{*}\left[\sum_{i=1}^{n} d_{i n}^{*}(x)\right]=\hat{\sigma}_{n}^{-2}(x) \lambda^{\prime} n^{-1} \sum_{i=1}^{n} \hat{r}_{i}(x) \hat{r}_{i}^{\prime}(x) \lambda \operatorname{Var}^{*}\left[V_{i}\right]=1 \text { a.s. }
$$

Let $k_{V}=\sup \left|V_{i}\right|$. We can check that the Lindeberg condition holds for $d_{i n}^{*}(x)$ with probability one as follows

$$
\begin{aligned}
& \sum_{i=1}^{n} E^{*}\left[d_{i n}^{* 2}(x) 1\left(\left|d_{i n}^{*}(x)\right|>\delta\right)\right] \\
& =\frac{1}{n} \hat{\sigma}_{n}^{-2}(x) \lambda^{\prime} \sum_{i=1}^{n} \hat{r}_{i}(x) \hat{r}_{i}^{\prime}(x) \lambda E^{*}\left[V_{i} 1\left(\left|n^{-1 / 2} \lambda^{\prime} \hat{r}_{i}(x) V_{i} / \hat{\sigma}_{n}(x)\right|>\delta\right)\right] \\
& \leq \frac{1}{n} \hat{\sigma}_{n}^{-2}(x) \lambda^{\prime} \sum_{i=1}^{n} \hat{r}_{i}(x) \hat{r}_{i}^{\prime}(x) \lambda k_{V} E^{*}\left[1\left(\left|n^{-1 / 2} \lambda^{\prime} \hat{r}_{i}(x) / \hat{\sigma}_{n}(x)\right|>\delta\right)\right] \\
& \leq \frac{1}{n} \hat{\sigma}_{n}^{-2}(x) \lambda^{\prime} \sum_{i=1}^{n} \hat{r}_{i}(x) \hat{r}_{i}^{\prime}(x) \lambda k_{V} 1\left(\left|\lambda^{\prime} \hat{r}_{i}(x) / \hat{\sigma}_{n}(x)\right|>\delta n^{1 / 2}\right) \\
& =\frac{1}{n} \hat{\sigma}_{n}^{-2}(x) \lambda^{\prime} \sum_{i=1}^{n} r_{i}(x) r_{i}^{\prime}(x) \lambda k_{V} 1\left(\left|\lambda^{\prime} r_{i}(x) / \sigma_{n}(x)\right|>\delta n^{1 / 2}\right)+o_{p}(1) a . s . \\
& =o_{p}(1) \text { a.s. }
\end{aligned}
$$

Hence $\sum_{i=1}^{n} d_{i n}^{*}(x) \xrightarrow{d} N\left(0, I_{m}\right)$ almost surely. Since $b_{n}(x) \xrightarrow{\text { a.s. }} 1$, applying Slutsky theorem gives that $R_{n}^{*}\left(x_{1}\right) \xrightarrow{d^{*}} N(0, \sigma(x))$ with probability one. The convergence of the vector ( $R_{n}^{*}\left(x_{1}\right), . ., R_{n}^{*}\left(x_{s}\right)$ ) can be proved using analogous methods. Therefore, the convergence of finite dimensional distributions follows almost surely.

Tightness of the $k$-th coordinate of $R_{n}(x)$ is shown using Condition (2.1.8) in Gaenssler and Stute (1979). We define the vector

$$
R_{n}^{0 *}(x)=\frac{1}{n} \sum_{i=1}^{n} \hat{\psi}_{i} \Delta_{i}(x) V_{i}
$$

with $k$-th coordinate denoted by $R_{n}^{0(k) *}(x)$. Applying Equation (10) as in (13) we denote

$$
\sqrt{n} R_{n}^{0(k) *}\left(D_{j}\right)=\frac{1}{\sqrt{n}} \sum_{i=1}^{n} \hat{\psi}_{i}^{(k)} \Delta_{i}\left(D_{j}\right) V_{i}, \quad j=1,2
$$

where $D_{1}, D_{2}$ are two neighbors intervals. Thus a slight extension of the argu-
ments in Lemma 5.1 in Stute (1997) yields

$$
\begin{aligned}
n^{2} E^{*}\left(R_{n}^{0(k) *}\left(D_{1}\right) R_{n}^{0(k) *}\left(D_{2}\right)\right)^{2} & \leq \frac{C}{n^{2}} \sum_{\substack{i, j=1 \\
i \neq j}}^{n} E^{*}\left(\hat{\psi}_{i}^{(k)} \Delta_{i}\left(D_{1}\right) V_{i}\right)^{2} E^{*}\left(\hat{\psi}_{j}^{(k)} \Delta_{i}\left(D_{2}\right) V_{j}\right)^{2} \\
& \leq\left[\frac{C}{n} \sum_{i=1}^{n} E^{*}\left(\hat{\psi}_{i}^{(k)} \Delta_{i}\left(D_{1} \cup D_{2}\right) V_{i}\right)^{2}\right]^{2} \\
& =\left[\frac{C}{n} \sum_{i=1}^{n} \hat{\psi}_{i}^{(k) 2} \Delta_{i}\left(D_{1} \cup D_{2}\right)\right]^{2} \\
& \xrightarrow{\text { a.a. }} C\left[E\left(\psi_{i}^{(k) 2} \Delta_{i}\left(D_{1} \cup D_{2}\right)\right)\right]^{2},
\end{aligned}
$$

for some constant $C>0$ and (12) holds for $R_{n}^{0(k) *}$ (.) with probability one. Using the same arguments as in Theorem 2, tightness of the $k$-th coordinate is extended to the whole process $R_{n}^{*}(x)$.

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Table 1:

|  |  | $\left\|\begin{array}{ll} 0 & 2 \\ -1 \\ 0 & 0 \\ 0 \end{array}\right\|$ | $\left\|\begin{array}{ll} 1 & 9 \\ -1 & 0 \\ -0 & 0 \end{array}\right\|$ | $\begin{cases}20 & 0 \\ -7 \\ 0 & 0 \\ 0 & 0\end{cases}$ |  | $\begin{cases}\mathbf{O}_{0} & 0 \\ 0 \\ 0 & 0 \\ 0\end{cases}$ | $\left\{\left.\begin{array}{cc} \infty & \infty \\ 7 & 0 \\ 0 & 0 \\ 0 & 0 \end{array} \right\rvert\,\right.$ | $\left\|\begin{array}{cc} 40 \\ 0 & 10 \\ 0 & 0 \\ 0 \end{array}\right\|$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | $\begin{array}{ll} \sim_{2} & 2 \\ -2 & 0 \\ 0 & 0 \end{array}$ | $\begin{array}{ll} 0 & 2 \\ 0 & 8 \\ 0 & 0 \\ 0 & 0 \end{array}$ | $\begin{array}{ll} \mathbf{U}_{0} & 9 \\ 0 & 0_{1} \\ \hline \end{array}$ | $\begin{array}{ll} 8 & 0 \\ 0 & 0 \\ 0 & 0 \\ 0 \end{array}$ | $0 \begin{array}{ll} \infty \\ 0 \\ 0 \\ 0 & 0 \\ 0 \end{array}$ |  | $\begin{array}{ll} 8 & 0 \\ 0 \\ 0 & 0 \\ 0 & 0 \end{array}$ | $\begin{aligned} & 0_{0} \\ & 0 \\ & 0 \end{aligned}$ |
| $\left\lvert\, \begin{aligned} & 0 \\ & 0 \\ & 0 \\ & 0 \end{aligned}\right.$ |  | $\left\|\begin{array}{cc} 80 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{array}\right\|$ | $\begin{array}{ll} N_{2} & 2 \\ & 0 \\ 0 & 0 \end{array}$ | $\begin{array}{ll} y_{0} & 8 \\ 0 & 0 \\ 0 & 0 \end{array}$ | $\begin{array}{ll} 0 & 0 \\ 0 \\ 0 & 0 \\ 0 & 0 \end{array}$ | $\begin{array}{ll} \hat{b} \\ 0 \\ 0 & 0 \\ 0 \end{array}$ |  | $\begin{array}{lll} n & 0 \\ 0 & 0 \\ 0 \\ 0 \end{array}$ |
|  | 4 | \% | \% | \# | \% | \# | \% | * |
|  |  |  |  | $\left[\begin{array}{lll} \infty & 0 \\ 0 & 0 \\ 0 & 0 \\ 0 \end{array}\right.$ |  |  | $\left[\left.\begin{array}{cc} 0 & n \\ 0 \\ 0 & 0 \\ 0 & 0 \end{array} \right\rvert\,\right.$ | $\left\lvert\, \begin{array}{ll} 20 \\ 0 \\ 0 \\ 0 \\ 0 & 0 \\ 0 \end{array}\right.$ |
| $\frac{8}{21}$ |  |  | Fr | en io | $\left\|\begin{array}{cc} n \\ 0 & 8 \\ 0 \\ 0 \\ 0 \end{array}\right\|$ | $0$ | $\begin{array}{\|cc\|} \hline y_{0}^{\infty} \\ 0 \\ 0 \\ 0 \end{array}$ |  |
| $\left\lvert\, \begin{gathered} 0 \\ i 01 \\ i=1 \end{gathered}\right.$ | No | no | $$ | $\left\lvert\, \begin{array}{cc} 0 & \infty \\ 0 & 0 \\ 0 & 0 \end{array}\right.$ | $\begin{array}{ll} \infty \\ 0 & 1 \\ 0 & 0 \\ 0 & 0 \end{array}$ | $\begin{array}{ll} n & 0 \\ 0 \\ 0 & 0 \\ 0 & 0 \end{array}$ | $\begin{aligned} & 0 \\ & 0 \\ & 0 \\ & 0 \\ & 0 \\ & 0 \end{aligned}$ |  |
|  | * | * | * | * | * | * | * | F |
|  | $0$ |  | $\left.\right]$ |  | $0$ | $\begin{array}{ll} z_{0} & \mathbf{~} \\ 0 & 0 \end{array}$ | $\begin{array}{ll} \infty & 0 \\ 0 & 8 \\ 0 & 0 \\ 0 \end{array}$ |  |
|  | Or |  |  | $\left\|\begin{array}{cc} \text { R } \\ \hline \end{array}\right\|$ | $0$ | $\begin{array}{ll} 0_{0} & 0 \\ 0 & 0 \\ \hline \end{array}$ | $\left\|\begin{array}{cc} 7 \\ \hline 0 \\ 0 & 8 \\ 0 \end{array}\right\|$ |  |
|  | A | $\begin{array}{lll} \hat{W} \\ 0 & 0 \\ 0 & 0 \\ 0 \\ 0 & 0 \end{array}$ |  | $\left\lvert\, \begin{array}{cc} 0 & \sharp \\ 0 \\ 0 \\ 0 \end{array}\right.$ | $0$ | $\left\|\begin{array}{cc} 0 & 0 \\ 0 & 0 \\ 0 & 0 \\ 0 & 0 \end{array}\right\|$ | $\begin{array}{cc} 0 \\ 0 & 0 \\ 0 \\ 0 & 0 \\ 0 \end{array}$ |  |
|  | $\stackrel{ }{*}$ | $\stackrel{5}{ }$ | 5 | $s$ | 5 | 5 | $\stackrel{5}{ }$ |  |
| 0 | $\stackrel{\sim}{i}$ | $\stackrel{3}{\sim}$ | $\bigcirc$ | $\stackrel{3}{0}$ | ${ }^{\circ}$ | $\stackrel{\circ}{\circ}$ | N్రి |  |

Table 2
Empirical frequencies of rejections under $D G P_{1}(\delta=1)$ ．

|  |  | O | \％ | Rot | On in |  | 若 | － |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | O |  |  | $n_{n}^{2}$ |  |  |
|  |  | $\left\|\begin{array}{cc} \infty \\ 0 & 10 \\ 0 \\ 0 \\ 0 \end{array}\right\|$ | $\begin{array}{lll} A_{0}^{2} \\ 0 & 0 \\ 0 & 0 \\ 0 & 0 \\ 0 \end{array}$ |  | O |  |  | Or |
|  | 4 | \％ | 4 | \％ | \％ | is | \％ | ＊ |
|  |  |  |  |  |  |  |  |  |
|  | O |  | O |  |  |  | $\left\|\begin{array}{ll} \infty & 1 \\ 0 & + \\ 0 & \infty \\ 0 & 0 \end{array}\right\|$ |  |
|  | $\left(\begin{array}{ll} \infty & \underset{y}{\infty} \\ \infty \\ \infty \\ \infty & 0 \\ \hline \end{array}\right.$ |  | $\mathbf{n}_{0}^{2}$ |  |  | $\left\lvert\, \begin{array}{\|cc\|} \hline 1 \\ \hline \end{array}\right.$ |  | $0_{0}^{0}{ }^{2}$ |
|  | $\pm$ | ＊ | ： | ＊ | ＊ | ＊ | ＊ | 5 |
|  | Briri | ర్ర్రి | $\underset{\sim}{8} 8$ | O | $\mathbf{C O}_{i} 8$ |  | $\left\lvert\, \begin{array}{cc} 8 & 2 \\ 8 \\ 0 \\ 0 \\ \hline \end{array}\right.$ |  |
|  | O |  | O | $\mathbf{o l}_{\infty}^{\infty}$ | $\begin{array}{lll} \infty & 0 \\ 0 & 0 \\ 0 & 0 \\ 0 & 0 \\ 0 \end{array}$ | Her er ex ed ed |  |  |
|  | $\begin{array}{ll} ⿵_{0}^{\infty} \\ 0 \\ 0 \\ 0 \end{array}$ |  | Ro |  |  |  |  |  |
|  | 5 | 5 | 5 | 5 | 5 | 5 | $\sim$ |  |
| $\checkmark$ | 운 | $\stackrel{3}{9}$ | $\bigcirc$ | $\stackrel{3}{8}$ | $\vec{O}$ | O | 遃 |  |

Table 3:

| $\left\|\begin{array}{c} 0 \\ \\ \text { N } \\ \text { II } \end{array}\right\|$ | $\left\|\begin{array}{cc} \infty & \infty \\ 0 & 0 \\ 0 & 0 \\ 0 \end{array}\right\|$ | $\left\lvert\, \begin{array}{ll} 20 & 8 \\ 0 & 0 \\ 0 & 0 \\ 0 & 0 \end{array}\right.$ | $\left\lvert\, \begin{array}{ll} 8 \\ \hline 8 \\ \hline \end{array}\right.$ | $\begin{array}{ll} 8 & 8 \\ 0 \\ -1 \\ -1 \\ \hline 1 \end{array}$ | $\left\lvert\, \begin{array}{cc} 8 \\ \hline 8 \\ -1 & 8 \\ i \end{array}\right.$ | $\left\lvert\, \begin{aligned} & 8 \\ & \hline 8 \\ & -1 \\ & \hline 1 \\ & \hline \end{aligned}\right.$ |  | Nom |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\begin{aligned} & 8 \\ & -8 \\ & 11 \\ & a \end{aligned}$ | $\begin{array}{ll} 7 \\ \text { Ho } \\ 0 & 0 \\ 0 & 0 \end{array}$ | $\begin{array}{\|c} 10 \\ N \\ \\ 0 \end{array}$ | $\left\|\begin{array}{ll} \mathbf{N} & 20 \\ N & \mathbf{O} \\ \mathbf{C} & \mathbf{O} \\ \mathbf{O} & 0 \end{array}\right\|$ |  | $\left\|\begin{array}{ll} \hat{8} & \mathbf{8} \\ 0 & 8 \\ 0 \\ 0 & 0 \end{array}\right\|$ | $\left\|\begin{array}{ll} 2 & \infty \\ \hline & \infty \\ \mathbf{O} & 0 \\ 0 \end{array}\right\|$ | $\left.\begin{array}{ll} \mathbf{N} & 0 \\ \mathbf{N} \\ \mathbf{O} \\ \mathbf{O} & 0 \\ \hline 0 & 0 \end{array} \right\rvert\,$ | $\left\|\begin{array}{ll} \infty & 1 \\ & 1 \\ 0 & 1 \\ 0 & 1 \\ 0 & 0 \end{array}\right\|$ |
| $\left.\begin{aligned} & 0 \\ & 20 \\ & 10 \\ & 10 \end{aligned} \right\rvert\,$ | $\underset{\sim}{\sim}$ | Nr |  | $\begin{array}{ll} 1 & 2 \\ \hline 0 & 2 \\ 0 & 0 \\ 0 & 0 \end{array}$ | $\left\|\begin{array}{cc} 0 & \\ \mathbf{O} & \mathbf{B} \\ \mathbf{0} & \mathbf{O} \end{array}\right\|$ | $\left\|\begin{array}{cc} 1 & 5 \\ \infty & 5 \\ 0 & 0 \\ 0 & 0 \end{array}\right\|$ | $\stackrel{\sim}{2}$ | $\left.\right\|_{0} ^{\infty}$ |
|  | ${ }^{*}$ | ${ }_{*}^{*}$ | \% | 5 | $\pm$ | * | ${ }^{*}$ | * |
| $\left\|\begin{array}{c} \underset{\sim}{2} \\ \underset{y}{11} \\ \underline{a} \end{array}\right\|$ | $\begin{aligned} & 8 \\ & \hline 8 \\ & \hline-8 \\ & \hline-8 \end{aligned}$ | ${ }_{8}^{8} 8$ | $\left\|\begin{array}{ll} 8 & 8 \\ 0 & 8 \\ -i & 0 \\ -1 \end{array}\right\|$ | O | $\begin{array}{ll} 8 \\ \hline 8 \\ \hline & 8 \\ -1 \\ \hline \end{array}$ | $\left\lvert\, \begin{array}{cc} 8 \\ 8 & 8 \\ \hline \end{array}\right.$ | $\begin{array}{ll} 8 & 8 \\ \hline 0 \\ \hline \end{array}$ | $\left\lvert\, \begin{array}{ll} 0 & 0 \\ 0 & 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{array}\right.$ |
| $\left\lvert\, \begin{aligned} & 8 \\ & \frac{11}{11} \\ & \hline \end{aligned}\right.$ | $\begin{array}{ll} 1 & 0 \\ 20 & 0 \\ 0 & 0 \\ 0 & 0 \end{array}$ | $\left\|\begin{array}{ll} 0 & 0 \\ 0 & 0 \\ 0 & 0 \\ 0 & 0 \\ 0 & 0 \end{array}\right\|$ | $\begin{array}{\|c} \substack{8 \\ \hline \\ \hline \\ \hline \\ \hline \\ \hline \\ \hline \\ \hline} \\ \hline \end{array}$ | $\begin{array}{ll} 8 & 8 \\ \hline 6 \\ \hline \end{array}$ | $\begin{aligned} & 88 \\ & \hline 0 \\ & \hline \end{aligned}$ |  | $\left\|\begin{array}{cc} 0 & \mathbb{2} \\ 0 & 0 \\ 0 & 0 \\ 0 & 0 \end{array}\right\|$ | $\begin{array}{ll} 1 & 0 \\ 7 & 3 \\ 0 & 0 \\ 0 \end{array}$ |
| $\left\|\begin{array}{c} 0 \\ i 00 \\ i=1 \end{array}\right\|$ | $\left\|\begin{array}{cc} 7 \\ -7 & 8 \\ 0 & 0 \\ 0 \end{array}\right\|$ | $\stackrel{n}{2}$ |  | $$ |  | $\left\|\begin{array}{ll} 1 & 2 \\ \infty & 0 \\ \infty & 0 \\ 0 & 0 \\ 0 & 0 \end{array}\right\|$ | $\left\|\begin{array}{ll} \infty & 0 \\ & 0 \\ 0 & 0 \\ 0 & 0 \end{array}\right\|$ | $\stackrel{\sim}{2}$ |
|  | $*$ | $*$ | $\pm$ | $*$ | * | \# | $\pm$ | ${ }^{5}$ |
| $\left\|\begin{array}{c} \underset{N}{2} \\ 11 \\ \end{array}\right\|$ |  | $\begin{aligned} & 0 \\ & \hline 0 \\ & \hline 0 \\ & -1 \\ & \hline-1 \\ & \hline \end{aligned}$ |  | $\begin{aligned} & 8 \\ & \hline 8 \\ & \hline 10 \\ & \hline 1 \end{aligned}$ | $\left\|\begin{array}{cc} 8 & 8 \\ \hline 8 \\ \hline-i & 0 \\ \hline \end{array}\right\|$ |  | $\begin{aligned} & 8 \\ & \hline 8 \\ & \hline 8 \\ & \hline 1 \\ & \hline \end{aligned}$ |  |
| $\begin{array}{\|c} 8 \\ \mathbf{T} \\ \underline{a} \end{array}$ | $1 \begin{array}{ll} 1 & 9 \\ 0 & 9 \\ 0 & 0 \end{array}$ |  | $\left\|\begin{array}{rr} 8 & 8 \\ \hline & 0 \\ -i & 0 \\ \hline \end{array}\right\|$ | O | $\begin{array}{\|cc\|} \hline 8 & 8 \\ 0 \\ -1 \\ \hline \end{array}$ | $\left.\left\lvert\, \begin{array}{ll} 8 & 8 \\ \hline & 8 \\ 0 & 0 \\ 0 \end{array}\right.\right)$ | $\left\|\begin{array}{ll} \hline & 0 \\ \hline & 0 \\ 0 \\ 0 & 0 \\ \hline \end{array}\right\|$ |  |
| $\left\|\begin{array}{c} 0 \\ 0 \\ i j \\ i \end{array}\right\|$ |  | 资号 | $\left\|\begin{array}{ll} \infty & 2 \\ x_{0} & 8 \\ 0 & 0 \\ 0 \end{array}\right\|$ | O |  |  |  |  |
|  | 5 | $\stackrel{5}{*}$ | $\stackrel{5}{5}$ | 5 | 5 | $\stackrel{5}{ }$ | 5 |  |
| 0 | 웃 | $\xrightarrow{\sim}$ | $\stackrel{\text { 안 }}{ }$ | OٌO | $\stackrel{\rightharpoonup}{0}$ | $\stackrel{10}{\circ}$ | 능 |  |


| d |  | $\mathrm{n}=50$ | $\mathrm{n}=100$ | $\mathrm{n}=250$ |  | $\mathrm{n}=50$ | $\mathrm{n}=100$ | $\mathrm{n}=250$ |  | $\mathrm{n}=50$ | $\mathrm{n}=100$ | $\mathrm{n}=250$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 2.0 | $t_{n}$ | 0.124 | 0.064 | 0.006 | $t_{n}^{*}$ | 0.124 | 0.064 | 0.006 | $t_{n}^{* *}$ | 0.229 | 0.090 | 0.006 |
| 2.0 | $t_{n}$ | 0.105 | 0.061 | 0.006 |  | 0.090 | 0.055 | 0.006 |  | 0.166 | 0.073 | 0.006 |
| 1.5 |  | 0.102 | 0.054 | 0.017 | $t_{n}^{*}$ | 0.098 | 0.055 | 0.010 | $t_{n}^{* *}$ | 0.124 | 0.059 | 0.020 |
| 1.5 | $t_{n}$ | 0.091 | 0.052 | 0.011 |  | 0.071 | 0.047 | 0.010 |  | 0.103 | 0.053 | 0.018 |
| 1.0 | $t_{n}$ | 0.151 | 0.914 | 1.000 | $t_{n}^{*}$ | 0.144 | 0.909 | 1.000 | $t_{n}^{* *}$ | 0.214 | 0.711 | 0.979 |
| 1.0 | $t_{n}$ | 0.124 | 0.826 | 1.000 |  | 0.102 | 0.715 | 1.000 |  | 0.143 | 0.559 | 0.954 |
| 0.5 | $t$ | 0.994 | 1.000 | 1.000 | $t_{n}^{*}$ | 0.991 | 1.000 | 1.000 | $t_{n}^{* *}$ | 0.946 | 0.992 | 1.000 |
| 0.5 | $t_{n}$ | 0.975 | 1.000 | 1.000 |  | 0.963 | 1.000 | 1.000 |  | 0.884 | 0.984 | 1.000 |
| 0.1 |  | 0.968 | 1.000 | 1.000 | $t_{n}^{*}$ | 0.964 | 1.000 | 1.000 | $t_{n}^{* *}$ | 0.943 | 0.998 | 1.000 |
| 0.1 | $t_{n}$ | 0.923 | 0.999 | 1.000 |  | 0.919 | 0.999 | 1.000 |  | 0.876 | 0.993 | 1.000 |
|  |  | 0.900 | 0.998 | 1.000 | $t_{n}^{*}$ | 0.884 | 0.998 | 1.000 | $t_{n}^{* *}$ | 0.828 | 0.990 | 1.000 |
| 0.05 | $t_{n}$ | 0.792 | 0.996 | 1.000 |  | 0.799 | 0.995 | 1.000 |  | 0.722 | 0.982 | 1.000 |
| 0.025 |  | 0.723 | 0.983 | 1.000 | $t_{n}^{*}$ | 0.728 | 0.979 | 1.000 | $t_{n}^{* *}$ | 0.643 | 0.961 | 0.961 |
| 0.025 | $t_{n}$ | 0.487 | 0.964 | 0.999 |  | 0.594 | 0.961 | 0.999 |  | 0.490 | 0.926 | 0.926 |
|  |  |  |  |  | $c_{n}^{*}$ | 0.132 | 0.135 | 0.901 | $c_{n}^{* *}$ | 0.265 | 0.435 | 0.890 |
|  |  |  |  |  |  | 0.125 | 0.065 | 0.655 |  | 0.188 | 0.266 | 0.803 |


[^0]:    ${ }^{1}$ The assumption of $\theta_{1}$ being an interior point of $\theta$ is not formally needed if we consider directional derivatives through the interior of $\theta$ in the proofs.

[^1]:    ${ }^{2}$ The assumption of $\theta_{1}$ being an interior point of $\theta$ is not formally needed if we consider directional derivatives through the interior of $\Theta$ in the proofs.

[^2]:    ${ }^{3}$ For $H_{3 n}$ to be an alternative that can be distinguished from $H_{0}$ at a parametric rate, the function $g($. $)$ must be orthogonal to $E\left[\psi\left(Y, X ; \theta_{0}\right) \mid X=.\right]$, see Bierens and Ploberger (1997) for a discussion on this point.
    ${ }^{4}$ This is the case when testing the significance of one explanatory variable in a regression model, see Delgado and Domínguez (1995).

[^3]:    ${ }^{5}$ In this subsection, one can read almost surely (or in probability) any time we use a.s.

