

Orbit Structure of the Closure of a Homogeneous Cone

by

Hideyuki ISHI

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Dedicated to Professor Fumihiko Sato on the occasion of his 65th birthday

Abstract. Let Ω be a homogeneous cone on which a split solvable Lie group H acts linearly and simply transitively. We describe the closure relation between H -orbits in the closure $\overline{\Omega}$ of the cone Ω , and discuss related results in connection with the Riesz distributions on Ω .

1. Introduction

In studying the wave equation, M. Riesz [12] considered a family of tempered distributions $T_\alpha \in \mathcal{S}'(\mathbb{R}^n)$ ($\alpha \in \mathbb{C}$) obtained by the analytic continuation with respect to the parameter α of the function

$$2^{1-\alpha} \pi^{(2-n)/2} \Gamma\left(\frac{\alpha}{2}\right)^{-1} \Gamma\left(\frac{\alpha-n+2}{2}\right)^{-1} (x_1^2 - x_2^2 - \dots - x_n^2)^{(\alpha-n)/2}$$

on the Lorentz cone. For a positive integer m , the distribution T_{2m} is a fundamental solution of the differential operator $(\frac{\partial^2}{\partial x_1^2} - \frac{\partial^2}{\partial x_2^2} - \dots - \frac{\partial^2}{\partial x_n^2})^m$, and the validity of the Huygens principle of the operator depends on the nature of the support of T_{2m} . Gindikin [2] developed Riesz's idea in full generality in the theory of homogeneous cones. Let Ω be a homogeneous cone on which a split solvable Lie group H acts linearly and simply transitively. The Riesz distribution $\mathcal{R}_{\underline{s}}$ on Ω is defined by the analytic continuation with respect to the parameter $\underline{s} = (s_1, \dots, s_r) \in \mathbb{C}^r$ of the complex measure $\Gamma_\Omega(\underline{s})^{-1} f_1^{s_1} f_2^{s_2} \dots f_r^{s_r} d\mu_\Omega$, where f_k ($k = 1, \dots, r$) is a certain H -relatively invariant rational function, μ_Ω an H -relatively invariant measure on Ω , and $\Gamma_\Omega(\underline{s})$ an appropriate gamma factor. Then $\mathcal{R}_{\underline{m}}$ with a special value $\underline{m} \in \mathbb{Z}^r$ is the fundamental solution of a differential operator $F(\frac{\partial}{\partial x})$, where F is an H -relatively invariant polynomial associated to the dual cone of Ω ([2, 4, 9]). The description of the support of the distributions $\mathcal{R}_{\underline{s}}$ is of fundamental importance, and it is still an open problem. When $\mathcal{R}_{\underline{s}}$ is a positive measure, it plays significant roles in representation theory ([3, 7, 14]) and statistics ([5, 6]). The parameter set $\mathcal{E} := \{\underline{s} \in \mathbb{C}^r; \mathcal{R}_{\underline{s}} \text{ is positive}\}$ is determined first by Gindikin [3] (see also [1, Theorem VII.3.2] and [13]), while the support of each $\mathcal{R}_{\underline{s}}$ ($\underline{s} \in \mathcal{E}$) is given by [8, Theorem B]. Indeed, all positive $\mathcal{R}_{\underline{s}}$ are described explicitly in [8], related to the H -orbit structure of the closure $\overline{\Omega}$.

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In this paper, we discuss geometric structures of the H -orbits in $\overline{\Omega}$. Our main theorem is a simple criterion for the closure relation $\overline{\mathcal{O}_1} \subset \overline{\mathcal{O}_2}$ between H -orbits $\mathcal{O}_1, \mathcal{O}_2 \subset \overline{\Omega}$. The result is closely related to the study of Riesz distributions $\mathcal{R}_{\underline{s}}$. We can deduce a part of the main theorem from observation of the support of $\mathcal{R}_{\underline{s}}$. And we expect to utilize the theorem in future research on the distributions $\mathcal{R}_{\underline{s}}$.

Let us explain the present work in more detail. Let Ω be an open convex cone containing no line in a real vector space V . We assume that the cone Ω is homogeneous, that is, the linear automorphism group $GL(\Omega) := \{g \in GL(V); g\Omega = \Omega\}$ acts on Ω transitively. Let H be a maximal connected split solvable Lie subgroup of $GL(\Omega)$. Such H is unique up to inner automorphisms of $GL(\Omega)$, and H acts on Ω simply transitively ([16]). Moreover, if a Lie group $G \subset GL(\Omega)$ acts on Ω transitively and its Lie algebra $\text{Lie}(G)$ is algebraic, then there exists $g_0 \in G$ for which $g_0 H g_0^{-1} \subset G$. In this case, a G -orbit in V is a union of g_0 -images of H -orbits. This observation tells us the significance of investigation of the H -action in the theory of homogeneous cones.

Let \mathfrak{h} be the Lie algebra of H . Then the solvable Lie algebra $V \rtimes \mathfrak{h}$ admits a normal j -algebra structure ([8]), and one can make use of its root space decomposition due to Piatetskii-Shapiro [11]. As a result, there exist a commutative Cartan subalgebra \mathfrak{a} of $V \rtimes \mathfrak{h}$ and linear forms $\alpha_k : \mathfrak{a} \rightarrow \mathbb{R}$ ($k = 1, \dots, r$, $r := \dim \mathfrak{a}$) for which

$$(1.1) \quad \mathfrak{h} = \mathfrak{a} \oplus \sum_{1 \leq k < l \leq r}^{\oplus} \mathfrak{h}_{(\alpha_l - \alpha_k)/2},$$

$$(1.2) \quad V = \sum_{k=1}^r \oplus V_{\alpha_k} \oplus \sum_{1 \leq k < l \leq r}^{\oplus} V_{(\alpha_l + \alpha_k)/2},$$

where

$$\begin{aligned} \mathfrak{h}_{\alpha} &:= \{T \in \mathfrak{h}; [C, T] = \alpha(C)T \quad (\forall C \in \mathfrak{a})\}, \\ V_{\alpha} &:= \{x \in V; Cx = \alpha(C)x \quad (\forall C \in \mathfrak{a})\} \end{aligned}$$

for a linear form $\alpha \in \mathfrak{a}^*$. We have $\dim V_{\alpha_k} = 1$ for $k = 1, \dots, r$, while some $n_{lk} := \dim V_{(\alpha_l + \alpha_k)/2}$ ($1 \leq k < l \leq r$) may be zero. We can take $E_k \in V_{\alpha_k}$ ($k = 1, \dots, r$) so that $\sum_{k=1}^r E_k$ belongs to Ω . For $\underline{\varepsilon} = (\varepsilon_1, \dots, \varepsilon_r) \in \{0, 1\}^r$, let $E_{\underline{\varepsilon}}$ be the element $\sum_{k=1}^r \varepsilon_k E_k$ of V , and $\mathcal{O}_{\underline{\varepsilon}} \subset V$ the H -orbit through $E_{\underline{\varepsilon}}$. In particular, the cone Ω itself equals the H -orbit $\mathcal{O}_{(1, \dots, 1)}$. By [8, Theorem 3.5], the H -orbit decomposition of the closure of Ω is given by $\overline{\Omega} = \bigsqcup_{\underline{\varepsilon} \in \{0, 1\}^r} \mathcal{O}_{\underline{\varepsilon}}$. For $\underline{\varepsilon} \in \{0, 1\}^r$, we define $\underline{\sigma}(\underline{\varepsilon}) = (\sigma_1(\underline{\varepsilon}), \dots, \sigma_r(\underline{\varepsilon})) \in \mathbb{Z}^r$ by $\sigma_k(\underline{\varepsilon}) := \sum_{i=1}^k \varepsilon_i n_{ki}$ ($k = 1, \dots, r$), where we put $n_{kk} := \dim V_{\alpha_k} = 1$ for $k = 1, \dots, r$. Now we state our result.

MAIN THEOREM . For $\underline{\varepsilon}^1, \underline{\varepsilon}^2 \in \{0, 1\}^r$, one has $\overline{\mathcal{O}_{\underline{\varepsilon}^1}} \subset \overline{\mathcal{O}_{\underline{\varepsilon}^2}}$ if and only if $\sigma_k(\underline{\varepsilon}^1) \leq \sigma_k(\underline{\varepsilon}^2)$ for all $k = 1, \dots, r$.

In order to study the H -orbits in $\overline{\Omega}$, we may assume that the cone $\Omega \subset V$ and the group H are realized as the set of matrices with specific block decompositions owing to the results in [10] about the symplectic representation of the normal j -algebra $V \rtimes \mathfrak{h}$. In section 2, we explain the detail of the matrix realization of a homogeneous cone, and present some results about geometry of H -orbits (Propositions 3 and 4). Main Theorem

is proved in section 3 by rather elementary argument of linear algebra. In section 4, after brief review of results about Riesz distributions, we obtain a refinement of the ‘if’ part of Main Theorem (Theorem 9 (ii)) by observing the support of positive Riesz distributions. We emphasize that the meaning of the integers $\sigma_k(\underline{\varepsilon})$ becomes clearer when it is related to the theory of Riesz distributions. As a biproduct, we obtain the path-connectedness of the parameter set \mathcal{E} (Theorem 10).

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2. Matrix realization of a homogeneous cone

In studying a homogeneous cone, we may discuss only the cone $\Omega_{\mathcal{V}}$ constructed in a specific way explained below without loss of generality because every homogeneous cone is shown to be linearly isomorphic to such a cone ([10, Theorem D]). In what follows, we denote by $\text{Mat}(p, q; \mathbb{R})$ the vector space of $p \times q$ real matrices, by $\text{Mat}(p, \mathbb{R})$ the space $\text{Mat}(p, p; \mathbb{R})$, and by $\text{Sym}(p, \mathbb{R})$ the vector space of $p \times p$ real symmetric matrices. The transpose of a matrix A is denoted by tA . Let us take a partition $N = v_1 + v_2 + \cdots + v_r$ ($v_k > 0$, $k = 1, \dots, r$) of a positive integer N , and $\mathcal{V} = \{V_{lk}\}_{1 \leq k \leq l \leq r}$ a system of vector spaces $V_{lk} \subset \text{Mat}(v_l, v_k; \mathbb{R})$ satisfying

- (V1) $A \in V_{lk}, B \in V_{ki} \Rightarrow AB \in V_{li}$ ($1 \leq i \leq k \leq l \leq r$),
- (V2) $A \in V_{li}, B \in V_{ki} \Rightarrow A {}^tB \in V_{lk}$ ($1 \leq i \leq k \leq l \leq r$),
- (V3) $A \in V_{lk} \Rightarrow A {}^tA \in \mathbb{R}I_{v_l}$ ($1 \leq k \leq l \leq r$),
- (V4) $V_{ll} = \mathbb{R}I_{v_l}$ ($l = 1, \dots, r$).

Let $\mathcal{Z}_{\mathcal{V}}$ be the vector space consisting of symmetric matrices $X \in \text{Sym}(N, \mathbb{R})$ of the form

$$X = \begin{pmatrix} X_{11} & {}^tX_{21} & \cdots & {}^tX_{r1} \\ X_{21} & X_{22} & & {}^tX_{r2} \\ \vdots & & \ddots & \\ X_{r1} & X_{r2} & \cdots & X_{rr} \end{pmatrix} \quad (X_{lk} \in V_{lk}, \quad 1 \leq k \leq l \leq r),$$

and $\Omega_{\mathcal{V}} \subset \mathcal{Z}_{\mathcal{V}}$ the subset $\{X \in \mathcal{Z}_{\mathcal{V}}; X \text{ is positive definite}\}$. Then $\Omega_{\mathcal{V}}$ is an open convex cone in the vector space $\mathcal{Z}_{\mathcal{V}}$. Let $\mathfrak{h}_{\mathcal{V}}$ be the vector space of lower triangular matrices $T \in \text{Mat}(N, \mathbb{R})$ of the form

$$T = \begin{pmatrix} T_{11} & & & \\ T_{21} & T_{22} & & \\ \vdots & & \ddots & \\ T_{r1} & T_{r2} & \cdots & T_{rr} \end{pmatrix} \quad (T_{lk} \in V_{lk}, \quad 1 \leq k \leq l \leq r).$$

Then $\mathfrak{h}_{\mathcal{V}}$ is an \mathbb{R} -subalgebra of the matrix algebra $\text{Mat}(N, \mathbb{R})$ by (V1). Diagonal components T_{kk} ($k = 1, \dots, r$) of $T \in \mathfrak{h}_{\mathcal{V}}$ are scalar matrices by (V4), that is, we have $T_{kk} = t_{kk}I_{v_k}$ with $t_{kk} \in \mathbb{R}$. Regarding $\mathfrak{h}_{\mathcal{V}}$ as a real Lie algebra, we denote by $H_{\mathcal{V}}$ the Lie group $\exp \mathfrak{h}_{\mathcal{V}} \subset GL(N, \mathbb{R})$. Then we have

$$H_{\mathcal{V}} = \{T \in \mathfrak{h}_{\mathcal{V}}; t_{kk} > 0 \quad (k = 1, \dots, r)\} \subset \mathfrak{h}_{\mathcal{V}}.$$

If $T \in H_{\mathcal{V}}$ and $X \in \mathcal{Z}_{\mathcal{V}}$, then $\rho(T)X := TX^{\dagger}T$ belongs to $\mathcal{Z}_{\mathcal{V}}$ thanks to (V1)–(V4). Moreover $\rho(H_{\mathcal{V}})$ acts on the cone $\Omega_{\mathcal{V}} \subset \mathcal{Z}_{\mathcal{V}}$ simply transitively (see [10, Proposition 3.2]). Namely, $\Omega_{\mathcal{V}}$ is a homogeneous cone. For instance, if $v_k = 1$ ($k = 1, \dots, r$) and $V_{lk} = \mathbb{R}$ ($1 \leq k \leq l \leq r$), then we have $\mathcal{Z}_{\mathcal{V}} = \text{Sym}(r, \mathbb{R})$, and $\Omega_{\mathcal{V}}$ is the cone $\text{Sym}^+(r, \mathbb{R})$ of positive definite symmetric matrices. See [5, p. 331] for other examples of the homogeneous cone $\Omega_{\mathcal{V}}$.

Let \mathfrak{a} be the subspace of \mathfrak{h} consisting of diagonal matrices, that is,

$$\mathfrak{a} := \left\{ C = \begin{pmatrix} c_1 I_{v_1} & & & \\ & c_2 I_{v_2} & & \\ & & \ddots & \\ & & & c_r I_{v_r} \end{pmatrix} ; c_1, c_2, \dots, c_r \in \mathbb{R} \right\},$$

and $\alpha_k \in \mathfrak{a}^*$ ($k = 1, \dots, r$) the linear form given by $\alpha_k(C) := 2c_k$ ($C \in \mathfrak{a}$). Then the root space decompositions (1.1) and (1.2) coincide with the block decompositions of $\mathfrak{h}_{\mathcal{V}}$ and $\mathcal{Z}_{\mathcal{V}}$ respectively, where $\mathfrak{h}_{(\alpha_l - \alpha_k)/2}$ and $V_{(\alpha_l + \alpha_k)/2}$ naturally correspond to V_{lk} for $1 \leq k < l \leq r$.

For $\underline{\varepsilon} \in \{0, 1\}^r$, let $E_{\underline{\varepsilon}}$ be the element of $\mathcal{Z}_{\mathcal{V}}$ given by

$$E_{\underline{\varepsilon}} := \begin{pmatrix} \varepsilon_1 I_{v_1} & & & \\ & \ddots & & \\ & & \ddots & \\ & & & \varepsilon_r I_{v_r} \end{pmatrix},$$

and $\mathcal{O}_{\underline{\varepsilon}}$ the $H_{\mathcal{V}}$ -orbit $\rho(H_{\mathcal{V}})E_{\underline{\varepsilon}} \subset \mathcal{Z}_{\mathcal{V}}$ through $E_{\underline{\varepsilon}}$. In particular, if we write $\underline{0}$ and $\underline{1}$ for $(0, \dots, 0)$ and $(1, \dots, 1)$ respectively, then $\mathcal{O}_{\underline{0}}$ is the origin $\{0\}$, and $\mathcal{O}_{\underline{1}} = \rho(H_{\mathcal{V}})I_N$ equals the cone $\Omega_{\mathcal{V}}$.

THEOREM 1 ([8, Theorem 3.5]). *The $H_{\mathcal{V}}$ -orbit decomposition of the closure $\overline{\Omega_{\mathcal{V}}}$ of the homogeneous cone $\Omega_{\mathcal{V}}$ is given by*

$$\overline{\Omega_{\mathcal{V}}} = \bigsqcup_{\underline{\varepsilon} \in \{0, 1\}^r} \mathcal{O}_{\underline{\varepsilon}}.$$

We denote by $H_{\underline{\varepsilon}}$ the stabilizer subgroup $\{T \in H_{\mathcal{V}}; \rho(T)E_{\underline{\varepsilon}} = E_{\underline{\varepsilon}}\}$ of $H_{\mathcal{V}}$ at $E_{\underline{\varepsilon}}$. Then we see easily that $H_{\underline{\varepsilon}}$ equals

$$\{T \in H_{\mathcal{V}}; \text{if } \varepsilon_k = 1, \text{ then } T_{kk} = I_{v_k} \text{ and } T_{lk} = 0 \ (l > k)\}.$$

Let $H(\mathcal{O}_{\underline{\varepsilon}})$ be the group $H_{\underline{1}-\underline{\varepsilon}}$, that is,

$$H(\mathcal{O}_{\underline{\varepsilon}}) := \{T \in H_{\mathcal{V}}; \text{if } \varepsilon_k = 0, \text{ then } T_{kk} = I_{v_k} \text{ and } T_{lk} = 0 \ (l > k)\}.$$

Then the Lie algebra of $H(\mathcal{O}_{\underline{\varepsilon}})$ is

$$(2.1) \quad \begin{aligned} \mathfrak{h}(\mathcal{O}_{\underline{\varepsilon}}) &:= \{T \in \mathfrak{h}; \text{if } \varepsilon_k = 0, \text{ then } T_{lk} = 0 \ (l \geq k)\} \\ &= \{T \in \mathfrak{h}; TE_{\underline{\varepsilon}} = T\}. \end{aligned}$$

We set

$$\mathfrak{h}^+(\mathcal{O}_{\underline{\varepsilon}}) := \{T \in \mathfrak{h}(\mathcal{O}_{\underline{\varepsilon}}); \text{if } \varepsilon_k = 1, \text{ then } t_{kk} > 0\} \subset \mathfrak{h}(\mathcal{O}_{\underline{\varepsilon}}),$$

so that we have a bijection

$$\mathfrak{h}^+(\mathcal{O}_{\underline{\varepsilon}}) \ni T \xrightarrow{\sim} E_{1-\underline{\varepsilon}} + T \in H(\mathcal{O}_{\underline{\varepsilon}}).$$

Though the following results are shown in [5] and [8], we give the proofs here for reader's convenience.

- LEMMA 2. (i) *One has a diffeomorphism $\mathfrak{h}^+(\mathcal{O}_{\underline{\varepsilon}}) \ni T \mapsto T^{\dagger}T \in \mathcal{O}_{\underline{\varepsilon}}$.*
(ii) *The group $H(\mathcal{O}_{\underline{\varepsilon}})$ acts on $\mathcal{O}_{\underline{\varepsilon}}$ simply transitively.*
(iii) *The closure of the orbit $\mathcal{O}_{\underline{\varepsilon}}$ is described as*

$$\overline{\mathcal{O}_{\underline{\varepsilon}}} = \left\{ T^{\dagger}T; T \in \mathfrak{h}(\mathcal{O}_{\underline{\varepsilon}}) \right\}.$$

Proof. Let X be an element of the $H_{\mathcal{V}}$ -orbit of $\mathcal{O}_{\underline{\varepsilon}}$. Then there exists $\tilde{T} \in H_{\mathcal{V}}$ for which $X = \rho(\tilde{T})E_{\underline{\varepsilon}}$. Put $T := \tilde{T}E_{\underline{\varepsilon}} \in \mathfrak{h}^+(\mathcal{O}_{\underline{\varepsilon}})$. We observe

$$\begin{aligned} X &= \tilde{T}E_{\underline{\varepsilon}}^{\dagger}\tilde{T} = (\tilde{T}E_{\underline{\varepsilon}})^{\dagger}(\tilde{T}E_{\underline{\varepsilon}}) = T^{\dagger}T \\ &= (E_{1-\underline{\varepsilon}} + T)E_{\underline{\varepsilon}}^{\dagger}(E_{1-\underline{\varepsilon}} + T) = \rho(E_{1-\underline{\varepsilon}} + T)E_{\underline{\varepsilon}}. \end{aligned}$$

Since $E_{1-\underline{\varepsilon}} + T \in H(\mathcal{O}_{\underline{\varepsilon}})$, the orbit map $H(\mathcal{O}_{\underline{\varepsilon}}) \ni T^0 \mapsto \rho(T^0)E_{\underline{\varepsilon}} \in \mathcal{O}_{\underline{\varepsilon}}$ is surjective, while it is injective because $H(\mathcal{O}_{\underline{\varepsilon}}) \cap H_{\underline{\varepsilon}} = \{I_N\}$. Therefore (i) and (ii) hold. Let us prove (iii). We consider the quadratic map

$$q_{\underline{\varepsilon}} : \mathfrak{h}(\mathcal{O}_{\underline{\varepsilon}}) \ni T \mapsto T^{\dagger}T \in \mathcal{Z}_{\mathcal{V}}.$$

It follows from (i) that the image $q_{\underline{\varepsilon}}(\mathfrak{h}(\mathcal{O}_{\underline{\varepsilon}}))$ is contained in $\overline{\mathcal{O}_{\underline{\varepsilon}}}$. Thus it is sufficient to show that $q_{\underline{\varepsilon}}(\mathfrak{h}(\mathcal{O}_{\underline{\varepsilon}}))$ is a closed set in $\mathcal{Z}_{\mathcal{V}}$. In general, for a real vector space W , we denote by $\mathbb{P}(W)$ the projective space $(W \oplus \mathbb{R} \setminus \{(0, 0)\})/\mathbb{R}^{\times}$, and by ι_W the projective imbedding $\iota_W : W \ni w \mapsto [w, 1] \in \mathbb{P}(W)$. We extend the map $q_{\underline{\varepsilon}} : \mathfrak{h}(\mathcal{O}_{\underline{\varepsilon}}) \rightarrow \mathcal{Z}_{\mathcal{V}}$ to the continuous map $\tilde{q}_{\underline{\varepsilon}} : \mathbb{P}(\mathfrak{h}(\mathcal{O}_{\underline{\varepsilon}})) \ni [T, c] \mapsto [T^{\dagger}T, c^2] \in \mathbb{P}(\mathcal{Z}_{\mathcal{V}})$, noting that $T^{\dagger}T \neq 0$ if $T \neq 0$. The image $\tilde{q}_{\underline{\varepsilon}}(\mathbb{P}(\mathfrak{h}(\mathcal{O}_{\underline{\varepsilon}})))$ is compact, so that the set $q_{\underline{\varepsilon}}(\mathfrak{h}(\mathcal{O}_{\underline{\varepsilon}})) = \iota_{\mathcal{Z}_{\mathcal{V}}}^{-1}(\tilde{q}_{\underline{\varepsilon}}(\mathbb{P}(\mathfrak{h}(\mathcal{O}_{\underline{\varepsilon}}))))$ is closed in $\mathcal{Z}_{\mathcal{V}}$. \square

We see from Lemma 2 (i) that the $H_{\mathcal{V}}$ -orbit $\mathcal{O}_{\underline{\varepsilon}}$ is homeomorphic to a vector space. Furthermore, we deduce the following.

PROPOSITION 3 ([8, Proposition 3.6]). *Let $\underline{\varepsilon}$ and $\underline{\varepsilon}'$ be elements of $\{0, 1\}^r$ for which $\underline{\varepsilon} + \underline{\varepsilon}' \in \{0, 1\}^r$. Then one has a bijection*

$$\mathcal{O}_{\underline{\varepsilon}} \times \mathcal{O}_{\underline{\varepsilon}'} \ni (X, X') \mapsto X + X' \in \mathcal{O}_{\underline{\varepsilon} + \underline{\varepsilon}'}$$

Proof. Clearly the map

$$\mathfrak{h}^+(\mathcal{O}_{\underline{\varepsilon}}) \times \mathfrak{h}^+(\mathcal{O}_{\underline{\varepsilon}'}) \ni (T, T') \mapsto T + T' \in \mathfrak{h}^+(\mathcal{O}_{\underline{\varepsilon} + \underline{\varepsilon}'})$$

is bijective, and we have $(T + T')^{\dagger}(T + T') = T^{\dagger}T + T'^{\dagger}T'$. These observations together with Lemma 2 (i) imply the statement. \square

Let $\mathcal{C} \subset \mathbb{R}^n$ be a closed convex cone. For $x \in \mathcal{C}$, we say that the half line $\mathbb{R}_{+}x = \{\lambda x; \lambda > 0\}$ is an extremal ray of \mathcal{C} if $x = x' + x''$ with $x', x'' \in \mathcal{C}$ implies $x', x'' \in \mathbb{R}_{+}x$. We denote by $\text{Ex}(\mathcal{C})$ the set of $x \in \mathcal{C}$ for which $\mathbb{R}_{+}x$ is an extremal ray of \mathcal{C} .

PROPOSITION 4. *Let $\underline{\delta}(k) \in \{0, 1\}^r$ be the element of $\{0, 1\}^r$ whose k -th component is 1 and other components are 0. Then one has*

$$\text{Ex}(\overline{\mathcal{O}\mathcal{Y}}) = \bigsqcup_{k=1}^r \mathcal{O}_{\underline{\delta}(k)}.$$

Proof. If $X \in \mathcal{O}_{\underline{\varepsilon}}$ with $\underline{\varepsilon} \neq \underline{\delta}(k)$ for $k = 1, \dots, r$, then \mathbb{R}_+X is not an extremal ray because of Proposition 3. Thus it is sufficient to show that $\mathbb{R}_+E_{\underline{\delta}(k)}$ is an extremal ray for $k = 1, \dots, r$. Suppose $E_{\underline{\delta}(k)} = X' + X''$ with $X', X'' \in \overline{\mathcal{O}\mathcal{Y}}$. By (V4), we have $X'_{ii} = x'_{ii}I_{v_i}$ and $X''_{ii} = x''_{ii}I_{v_i}$ with $x'_{ii}, x''_{ii} \in \mathbb{R}$ for $i = 1, \dots, r$. Since X' and X'' are positive semi-definite, we have $x'_{ii} \geq 0$ and $x''_{ii} \geq 0$. On the other hand, if $i \neq k$, we have $x'_{ii} + x''_{ii} = 0$. Thus $X'_{ii} = X''_{ii} = 0$, which together with the positive semi-definiteness of X' and X'' implies that the off-diagonal (l, i) -components X'_{li} and X''_{li} equal 0 also for $1 \leq i < l \leq r$. Therefore X' and X'' belong to $\mathbb{R}_+E_{\underline{\delta}(k)}$, which completes the proof. \square

3. Main result

We put $n_{lk} := \dim V_{lk}$ ($1 \leq k \leq l \leq r$). For $\underline{\varepsilon} \in \{0, 1\}^r$, define $\underline{\sigma}(\underline{\varepsilon}) = (\sigma_1(\underline{\varepsilon}), \dots, \sigma_r(\underline{\varepsilon})) \in \mathbb{Z}^r$ by

$$(3.1) \quad \sigma_k(\underline{\varepsilon}) := \sum_{i=1}^k \varepsilon_i n_{ki} \quad (k = 1, \dots, r).$$

THEOREM 5. *For $\underline{\varepsilon}^1, \underline{\varepsilon}^2 \in \{0, 1\}^r$, one has $\overline{\mathcal{O}_{\underline{\varepsilon}^1}} \subset \overline{\mathcal{O}_{\underline{\varepsilon}^2}}$ if and only if $\sigma_k(\underline{\varepsilon}^1) \leq \sigma_2(\underline{\varepsilon}^2)$ for all $k = 1, \dots, r$.*

Proof. The key idea of the proof is to introduce the vector space $\mathfrak{v}_k(\underline{\varepsilon})$ ($1 \leq k \leq r$, $\underline{\varepsilon} \in \{0, 1\}^r$) below whose dimension is equal to $\sigma_k(\underline{\varepsilon})$. For $T \in \mathfrak{h}$ and $k = 1, \dots, r$, we set

$$R_k(T) := (T_{k1} \quad T_{k2} \quad \cdots \quad T_{kk}) \in \text{Mat}(v_k, v_1 + v_2 + \cdots + v_k; \mathbb{R}).$$

Namely, $R_k(T)$ is the r -th block row of the triangular matrix T . Put

$$\mathfrak{v}_k(\underline{\varepsilon}) := \{ R_k(T); T \in \mathfrak{h}(\mathcal{O}_{\underline{\varepsilon}}) \} \subset \text{Mat}(v_k, v_1 + v_2 + \cdots + v_k; \mathbb{R}).$$

Then we have $\dim \mathfrak{v}_k(\underline{\varepsilon}) = \sigma_k(\underline{\varepsilon})$. Similarly, we define

$$\check{R}_k(T) := (T_{k1} \quad T_{k2} \quad \cdots \quad T_{k,k-1}) \in \text{Mat}(v_k, v_1 + v_2 + \cdots + v_{k-1}; \mathbb{R})$$

for $k = 2, \dots, r$ and $T \in \mathfrak{h}$, and

$$\check{\mathfrak{v}}_k(\underline{\varepsilon}) := \{ \check{R}_k(T); T \in \mathfrak{h}(\mathcal{O}_{\underline{\varepsilon}}) \} \subset \text{Mat}(v_k, v_1 + v_2 + \cdots + v_{k-1}; \mathbb{R}).$$

Clearly, we have

$$(3.2) \quad \dim \check{\mathfrak{v}}_k(\underline{\varepsilon}) = \sigma_k(\underline{\varepsilon}) - \varepsilon_k.$$

Let us show the ‘only if’ part of the statement. Assume that $\overline{\mathcal{O}_{\underline{\varepsilon}^1}} \subset \overline{\mathcal{O}_{\underline{\varepsilon}^2}}$. Since $E_{\underline{\varepsilon}^1} \in \overline{\mathcal{O}_{\underline{\varepsilon}^2}}$, we can find $\tilde{T} \in \mathfrak{h}(\mathcal{O}_{\underline{\varepsilon}^2})$ for which $E_{\underline{\varepsilon}^1} = \tilde{T}^\dagger \tilde{T}$ because of Lemma 2 (iii).

Keeping (2.1) in mind, we have a linear map

$$\phi : \mathfrak{h}(\mathcal{O}_{\underline{\varepsilon}^1}) \ni T \mapsto T\tilde{T} \in \mathfrak{h}(\mathcal{O}_{\underline{\varepsilon}^2}).$$

We observe that ϕ is injective. Indeed, if $\phi(T) = 0$ for some $T \in \mathfrak{h}(\mathcal{O}_{\underline{\varepsilon}^1})$, then

$$0 = (T\tilde{T})^\dagger(T\tilde{T}) = TE_{\underline{\varepsilon}^1}^\dagger T = T^\dagger T,$$

so that $T = 0$. Let $\tilde{T}^{[k]}$ ($k = 1, \dots, r$) be the submatrix of \tilde{T} defined by

$$\tilde{T}^{[k]} := \begin{pmatrix} \tilde{T}_{11} & & \\ \vdots & \ddots & \\ \tilde{T}_{k1} & \cdots & \tilde{T}_{kk} \end{pmatrix} \in \text{Mat}(v_1 + \cdots + v_k; \mathbb{R}).$$

Let us consider a linear map

$$\phi_k : \mathfrak{v}_k(\underline{\varepsilon}^1) \ni R_k(T) \mapsto R_k(T)\tilde{T}^{[k]} = R_k(T\tilde{T}) \in \mathfrak{v}_k(\underline{\varepsilon}^2) \quad (T \in \mathfrak{h}(\mathcal{O}_{\underline{\varepsilon}^1})).$$

In a similar way to the case for ϕ , we see that ϕ_k is injective. Therefore we obtain $\dim \mathfrak{v}_k(\underline{\varepsilon}^1) \leq \dim \mathfrak{v}_k(\underline{\varepsilon}^2)$, which means that $\sigma_k(\underline{\varepsilon}^1) \leq \sigma_k(\underline{\varepsilon}^2)$.

Next we show the 'if' part. Assume that $\sigma_k(\underline{\varepsilon}^1) \leq \sigma_k(\underline{\varepsilon}^2)$ for $k = 1, \dots, r$. In order to show $\overline{\mathcal{O}_{\underline{\varepsilon}^1}} \subset \overline{\mathcal{O}_{\underline{\varepsilon}^2}}$, it is sufficient to find $\tilde{T} \in \mathfrak{h}(\mathcal{O}_{\underline{\varepsilon}^2})$ for which $E_{\underline{\varepsilon}^1} = \tilde{T}^\dagger \tilde{T}$ thanks to Lemma 2 (iii). Since $E_{\underline{\varepsilon}^1} = (E_{\underline{\varepsilon}^1} \tilde{T})^\dagger (E_{\underline{\varepsilon}^1} \tilde{T})$ and $E_{\underline{\varepsilon}^1} \tilde{T} \in \mathfrak{h}(\mathcal{O}_{\underline{\varepsilon}^2})$ for such \tilde{T} , we can assume further that the matrix \tilde{T} satisfies $\tilde{T} = E_{\underline{\varepsilon}^1} \tilde{T}$ without loss of generality. We shall get \tilde{T} by determining $\tilde{T}^{[k]}$ recursively for $k = 1, \dots, r$ so that

$$(3.3) \quad \tilde{T}^{[k] \dagger} \tilde{T}^{[k]} = \begin{pmatrix} \varepsilon_1^1 I_{v_1} & & \\ & \ddots & \\ & & \varepsilon_k^1 I_{v_k} \end{pmatrix} =: E_{\underline{\varepsilon}^1}^{[k]},$$

$$(3.4) \quad \tilde{T}^{[k]} E_{\underline{\varepsilon}^2}^{[k]} = \tilde{T}^{[k]},$$

and

$$(3.5) \quad E_{\underline{\varepsilon}^1}^{[k]} \tilde{T}^{[k]} = \tilde{T}^{[k]}.$$

Since $\varepsilon_1^1 = \sigma_1(\underline{\varepsilon}^1) \leq \sigma_1(\underline{\varepsilon}^2) = \varepsilon_1^2$, we set $\tilde{T}^{[1]} := \varepsilon_1^1 I_{v_1}$ which satisfies (3.3), (3.4) and (3.5) with $k = 1$. Assume that $\tilde{T}^{[k-1]}$ ($2 \leq k \leq r$) is determined. If $\varepsilon_k^1 \leq \varepsilon_k^2$, then we set

$$\tilde{T}^{[k]} := \begin{pmatrix} \tilde{T}^{[k-1]} & \\ 0 & \varepsilon_k^1 I_{v_k} \end{pmatrix}$$

for the required properties. Let us consider the case $\varepsilon_k^1 = 1$ and $\varepsilon_k^2 = 0$. By (3.2), we have $\dim \check{\mathfrak{v}}_k(\underline{\varepsilon}^1) = \sigma_k(\underline{\varepsilon}^1) - 1 < \sigma_k(\underline{\varepsilon}^2) = \dim \check{\mathfrak{v}}_k(\underline{\varepsilon}^2)$. Thus the linear map

$$\psi_k : \check{\mathfrak{v}}_k(\underline{\varepsilon}^1) \ni \check{R}_k(T) \mapsto \check{R}_k(T)\tilde{T}^{[k-1]} \in \check{\mathfrak{v}}_k(\underline{\varepsilon}^2) \quad (T \in \mathfrak{h}(\mathcal{O}_{\underline{\varepsilon}^1})).$$

is not surjective. We take a non-zero element \tilde{Y} of the orthogonal complement $(\text{Image } \psi_k)^\perp \subset \check{\mathfrak{v}}_k(\underline{\varepsilon}^2)$ with respect to the inner product defined by $(Y_1|Y_2) := \text{tr}(Y_1^\dagger Y_2)$ ($Y_1, Y_2 \in \check{\mathfrak{v}}_k(\underline{\varepsilon}^2)$). Then we have

$$(3.6) \quad 0 = (\tilde{Y}|\psi_k(Y)) = \text{tr}(\tilde{Y}^\dagger \tilde{T}^{[k-1] \dagger} Y)$$

for any $Y \in \check{\mathfrak{t}}_k(\underline{\varepsilon}^1)$. Since $\tilde{Y}^\dagger \tilde{Y} \in \mathbb{R}I_{v_k}$ by (V3), we can normalize \tilde{Y} so that

$$\tilde{Y}^\dagger \tilde{Y} = I_{v_k}.$$

On the other hand, we see from (V2) that $\tilde{Y}^\dagger \tilde{T}^{[k-1]}$ belongs to the space $\check{\mathfrak{t}}_k = \check{\mathfrak{t}}_k(1, \dots, 1)$, while we obtain $\tilde{Y}^\dagger \tilde{T}^{[k-1]} E_\varepsilon^{[k-1]} = \tilde{Y}^\dagger \tilde{T}^{[k-1]}$ by (3.5). Thus $\tilde{Y}^\dagger \tilde{T}^{[k-1]} \in \check{\mathfrak{t}}_k(\underline{\varepsilon}^1)$. Therefore, putting $Y = \tilde{Y}^\dagger \tilde{T}^{[k-1]}$ in (3.6), we have $\tilde{Y}^\dagger \tilde{T}^{[k-1]} = 0$. We set

$$\tilde{T}^{[k]} := \begin{pmatrix} \tilde{T}^{[k-1]} \\ \tilde{Y} & 0 \end{pmatrix},$$

so that (3.3), (3.4) and (3.5) are satisfied. In this way, we obtain $\tilde{T} = \tilde{T}^{[r]} \in \mathfrak{h}(\mathcal{O}_{\underline{\varepsilon}^2})$ for which $\tilde{T}^\dagger \tilde{T} = E_{\underline{\varepsilon}^1}$. \square

4. Riesz distribution

In this section, we investigate the $H_{\mathcal{V}}$ -orbits in $\overline{\Omega_{\mathcal{V}}}$ in connection with the theory of Riesz distributions, so that a refinement of the ‘if’ part of Theorem 5 is obtained (Theorem 9 (ii)). Let us recall the definition of Riesz distributions on the homogeneous cone $\Omega_{\mathcal{V}} \subset \mathcal{Z}_{\mathcal{V}}$ and their basic properties. See [5] and [8] for the details. For $\underline{s} = (s_1, \dots, s_r) \in \mathbb{C}^r$, let $\chi_{\underline{s}} : H_{\mathcal{V}} \rightarrow \mathbb{C}^\times$ be the one-dimensional representation of $H_{\mathcal{V}}$ given by $\chi_{\underline{s}}(T) := \prod_{k=1}^r t_{kk}^{2s_k}$ ($T \in H_{\mathcal{V}}$). Define $\Delta_{\underline{s}} : \Omega_{\mathcal{V}} \rightarrow \mathbb{C}$ by $\Delta_{\underline{s}}(X) := \chi_{\underline{s}}(T)$ ($X = T^\dagger T \in \Omega_{\mathcal{V}}$, $T \in H_{\mathcal{V}}$). Then $\Delta_{\underline{s}}$ is an $H_{\mathcal{V}}$ -relatively invariant function on the cone $\Omega_{\mathcal{V}}$. Moreover, $\Delta_{\underline{s}}$ can be expressed as a product of powers of minors as follows. For $p = 1, \dots, N$ and $S \in \text{Sym}(N, \mathbb{R})$, we denote by $\det^{[p]} S$ the principal minor $\det(S_{\alpha\beta})_{1 \leq \alpha \leq p, 1 \leq \beta \leq p}$ of degree p . Put $f_1 := \det^{[1]}$ and

$$f_k := \frac{\det^{[v_1 + \dots + v_{k-1} + 1]}}{\det^{[v_1 + \dots + v_{k-1}]}} \quad (k = 2, \dots, r).$$

Then we have $\Delta_{\underline{s}} = \prod_{k=1}^r f_k^{s_k}$.

Keeping (V3) in mind, we define an inner product on each V_{lk} ($1 \leq k \leq l \leq r$) by $(A|B) := (\text{tr } A^\dagger B) / v_l$ ($A, B \in V_{lk}$), so that

$$X_{lk}^\dagger X_{lk} = (X_{lk}|X_{lk}) I_{v_l} \quad (X_{lk} \in V_{lk}).$$

We denote by dX the Lebesgue measure $\prod_{1 \leq k \leq l \leq r} dX_{lk}$ on $\mathcal{Z}_{\mathcal{V}}$ normalized by the inner product. We define also $\underline{d} := (d_1, \dots, d_r) \in \mathbb{Z}^r/2$ by $d_k := 1 + (\sum_{i < k} n_{ki} + \sum_{l > k} n_{lk})/2$ for $k = 1, \dots, r$. Let $\mu_{\mathcal{V}}$ be a measure on the cone $\Omega_{\mathcal{V}}$ given by $d\mu_{\mathcal{V}}(X) := \Delta_{-\underline{d}}(X) dX$ ($X \in \Omega_{\mathcal{V}}$). Then $\mu_{\mathcal{V}}$ is invariant under the action of $H_{\mathcal{V}}$. For $X \in \mathcal{Z}$, we denote by x_{kk} ($k = 1, \dots, r$) the real number for which $X_{kk} = x_{kk} I_{v_k}$. It is shown in [2, Theorem 2.1] that the integral

$$\Gamma_{\mathcal{V}}(\underline{s}) := \int_{\Omega_{\mathcal{V}}} e^{-\sum_{k=1}^r x_{kk}} \Delta_{\underline{s}}(X) d\mu_{\mathcal{V}}(X)$$

converges if and only if $2\Re s_k > p_k := \sum_{i < k} n_{ki}$ for $k = 1, \dots, r$, and in this case

$$\Gamma_{\mathcal{V}}(\underline{s}) = \pi^{(n-r)/2} \prod_{k=1}^r \Gamma\left(s_k - \frac{p_k}{2}\right),$$

where $n := \dim \mathcal{Z}_{\mathcal{V}} = \sum_{1 \leq k < l \leq r} n_{lk}$. Moreover, $\mathcal{R}_{\underline{s}} := \Gamma_{\mathcal{V}}(\underline{s})^{-1} \Delta_{\underline{s}} d\mu_{\mathcal{V}}$ defines a complex Radon measure on $\mathcal{Z}_{\mathcal{V}}$ when $\Gamma_{\mathcal{V}}(\underline{s})$ converges, and admits the analytic continuation to whole $\underline{s} \in \mathbb{C}^r$ as a tempered distribution.

For $\underline{\varepsilon} \in \{0, 1\}^r$, we define $p_k(\underline{\varepsilon}) := \sum_{i < k} \varepsilon_i n_{ki}$ ($k = 1, \dots, r$),

$$\mathcal{E}(\underline{\varepsilon}) := \left\{ \underline{s} \in \mathbb{R}^r; s_k = p_k(\underline{\varepsilon})/2 \text{ (if } \varepsilon_k = 0), \quad s_k > p_k(\underline{\varepsilon})/2 \text{ (if } \varepsilon_k = 1) \right\},$$

and $\mathcal{E} := \bigsqcup_{\underline{\varepsilon} \in \{0, 1\}^r} \mathcal{E}(\underline{\varepsilon})$.

THEOREM 6 ([8, Theorem B]). *The Riesz distribution $\mathcal{R}_{\underline{s}}$ is positive if and only if $\underline{s} \in \mathcal{E}$. Moreover, if $\underline{s} \in \mathcal{E}(\underline{\varepsilon})$, then $\mathcal{R}_{\underline{s}}$ is a measure on the $H_{\mathcal{V}}$ -orbit $\mathcal{O}_{\underline{\varepsilon}}$.*

Using the diffeomorphism $q_{\underline{\varepsilon}} : \mathfrak{h}^+(\mathcal{O}_{\underline{\varepsilon}}) \ni T \mapsto T^{\dagger}T \in \mathcal{O}_{\underline{\varepsilon}}$ in Lemma 2 as a coordinate map of $\mathcal{O}_{\underline{\varepsilon}}$, we can describe the measure $\mathcal{R}_{\underline{s}}$ on $\mathcal{O}_{\underline{\varepsilon}}$ for $\underline{s} \in \mathcal{E}(\underline{\varepsilon})$ as follows.

PROPOSITION 7 ([5, Proposition 3.10]). *If $\underline{s} \in \mathcal{E}(\underline{\varepsilon})$, one has*

$$d\mathcal{R}_{\underline{s}}(X) = \prod_{\varepsilon_k=1} \left\{ \frac{2(t_{kk})^{2s_k - p_k(\underline{\varepsilon}) - 1} dt_{kk}}{\Gamma(s_k - \frac{p_k(\underline{\varepsilon})}{2})} \cdot \prod_{l>k} \frac{dT_{lk}}{\pi^{n_{lk}/2}} \right\},$$

where $X = T^{\dagger}T \in \mathcal{O}_{\underline{\varepsilon}}$ with $T \in \mathfrak{h}^+(\mathcal{O}_{\underline{\varepsilon}})$.

We have a concise algorithm to know whether \underline{s} belongs to \mathcal{E} for a given $\underline{s} \in \mathbb{R}^r$.

PROPOSITION 8 ([8, Proposition 6.1]). *For $\underline{s} \in \mathbb{R}^r$, define $u_k^i \in \mathbb{R}$ ($1 \leq i \leq k \leq r$) by $u_k^1 := s_k$ ($k = 1, \dots, r$) and*

$$u_k^i := \begin{cases} u_k^{i-1} - n_{ki}/2 & \text{(if } u_{i-1}^{i-1} > 0), \\ u_k^{i-1} & \text{(if } u_{i-1}^{i-1} \leq 0) \end{cases}$$

for $2 \leq i \leq k \leq r$. Then $\underline{s} \in \mathcal{E}$ if and only if $u_k^k \geq 0$ for all $k = 1, \dots, r$. In this case, putting

$$\varepsilon_k := \begin{cases} 1 & \text{(if } u_k^k > 0), \\ 0 & \text{(if } u_k^k = 0) \end{cases}$$

for $k = 1, \dots, r$, one has $\underline{s} \in \mathcal{E}(\underline{\varepsilon})$.

Let us recall the parameter $\underline{\sigma}(\underline{\varepsilon}) = (\sigma_1(\underline{\varepsilon}), \dots, \sigma_r(\underline{\varepsilon})) \in \mathbb{Z}^r$ defined by (3.1). We note that $\underline{\sigma}(\underline{\varepsilon})/2$ ($\underline{\varepsilon} \in \{0, 1\}^r$) belongs to $\mathcal{E}(\underline{\varepsilon})$. Indeed, Proposition 7 tells us that $\mathcal{R}_{\underline{\sigma}(\underline{\varepsilon})/2}$ equals the image of the Lebesgue measure $\prod_{\varepsilon_k=1} \prod_{l>k} dt_{kk} dT_{lk}$ on $\mathfrak{h}^+(\mathcal{O}_{\underline{\varepsilon}})$ via the map $q_{\underline{\varepsilon}} : \mathfrak{h}^+(\mathcal{O}_{\underline{\varepsilon}}) \rightarrow \mathcal{O}_{\underline{\varepsilon}}$ up to a positive constant multiple.

THEOREM 9. Let $\underline{\varepsilon}^1$ and $\underline{\varepsilon}^2$ be elements of $\{0, 1\}^r$ such that $\sigma_k(\underline{\varepsilon}^1) \leq \sigma_k(\underline{\varepsilon}^2)$ for all $k = 1, \dots, r$. For $j = 1, \dots, r$ and $t \in [0, 1]$, define $\underline{s}(j, t) \in \mathbb{R}^r$ by

$$s_k(j, t) := \begin{cases} \sigma_k(\underline{\varepsilon}^1) & (k < j), \\ t\sigma_k(\underline{\varepsilon}^1) + (1-t)\sigma_k(\underline{\varepsilon}^2) & (k = j), \\ \sigma_k(\underline{\varepsilon}^2) & (k > j). \end{cases}$$

(i) For $j = 1, \dots, r$, there exists $\underline{\varepsilon}(j) \in \{0, 1\}^r$ such that $\underline{s}(j, t)/2 \in \mathcal{E}(\underline{\varepsilon}(j))$ for all $t \in [0, 1]$.

(ii) One has $\overline{\mathcal{O}_{\underline{\varepsilon}^1}} \subset \overline{\mathcal{O}_{\underline{\varepsilon}(r)}} \subset \dots \subset \overline{\mathcal{O}_{\underline{\varepsilon}(2)}} \subset \overline{\mathcal{O}_{\underline{\varepsilon}(1)}} = \overline{\mathcal{O}_{\underline{\varepsilon}^2}}$.

Proof. We show the assertion (i) by induction on j . Let us consider the case $j = 1$. By the assumption, we have $\varepsilon_1^1 = \sigma_1(\underline{\varepsilon}^1) \leq \sigma_1(\underline{\varepsilon}^2) = \varepsilon_1^2$. If $\varepsilon_1^1 = \varepsilon_1^2$, then $\underline{s}(1, t) = \underline{\sigma}(\underline{\varepsilon}^2)$ for $t \in [0, 1]$, so that the claim holds with $\underline{\varepsilon}(1) = \underline{\varepsilon}^2$. For the case $\varepsilon_1^1 = 0$ and $\varepsilon_1^2 = 1$, we have $s_1(1, t) = 1 - t > 0$ for $t \in [0, 1)$ and $s_k(1, t) = \sigma_k(\underline{\varepsilon}^2)$ ($k = 2, \dots, r$). Thus $\underline{s}(1, t)/2 \in \mathcal{E}(\underline{\varepsilon}(1))$ with $\underline{\varepsilon}(1) = \underline{\varepsilon}^2$ again.

Assume that the claim holds for $j = i < r$. Let φ be any non-negative function on $\mathcal{Z}_{\mathcal{V}}$ with compact support. Since $\mathcal{R}_{\underline{s}(i,t)/2}$ is a positive measure on $\overline{\mathcal{O}_{\underline{\varepsilon}(i)}}$ for $t \in [0, 1)$ by the induction hypothesis and Theorem 6, we have

$$(4.1) \quad \langle \mathcal{R}_{\underline{s}(i,1)/2}, \varphi \rangle = \lim_{t \rightarrow 1-0} \langle \mathcal{R}_{\underline{s}(i,t)/2}, \varphi \rangle \geq 0.$$

Therefore the distribution $\mathcal{R}_{\underline{s}(i,1)/2}$ is positive, so that Theorem 6 tells us the existence of $\underline{\varepsilon}(i+1) \in \{0, 1\}^r$ for which

$$\underline{s}(i, 1)/2 \in \mathcal{E}(\underline{\varepsilon}(i+1)).$$

Furthermore, (4.1) implies that $\overline{\mathcal{O}_{\underline{\varepsilon}(i+1)}} = \text{supp } \mathcal{R}_{\underline{s}(i,1)/2}$ is contained in $\overline{\mathcal{O}_{\underline{\varepsilon}(i)}} = \text{supp } \mathcal{R}_{\underline{s}(i,t)/2}$ ($t \in [0, 1)$). We note that $\underline{s}(i+1, 0) = \underline{s}(i, 1)$ by definition. Let us check that $p_{i+1}(\underline{\varepsilon}(i+1)) = \sum_{h=1}^i \varepsilon_h(i+1)n_{i+1,h}$ is equal to $p_{i+1}(\underline{\varepsilon}^1)$. In view of Proposition 8, we see that the h -th component $\varepsilon_h(i+1)$ of $\underline{\varepsilon}(i+1)$ is determined from $s_\alpha(i+1, 1)$ ($\alpha = 1, \dots, h$), which is equal to $\sigma_\alpha(\underline{\varepsilon}^1)$ if $h \leq i$. Thus $\varepsilon_h(i+1) = \varepsilon_h^1$ for $h = 1, \dots, i$, so that

$$p_{i+1}(\underline{\varepsilon}(i+1)) = p_{i+1}(\underline{\varepsilon}^1) \leq \sigma_{i+1}(\underline{\varepsilon}^1) \leq \sigma_{i+1}(\underline{\varepsilon}^2).$$

It follows that

$$p_{i+1}(\underline{\varepsilon}(i+1)) \leq s_{i+1}(i+1, t) \leq \sigma_{i+1}(\underline{\varepsilon}^2) \quad (0 \leq t \leq 1).$$

Moreover, $s_{i+1}(i+1, t) > p_{i+1}(\underline{\varepsilon}(i+1))$ for all $t \in [0, 1)$ if and only if $\sigma_{i+1}(\underline{\varepsilon}^2) > p_{i+1}(\underline{\varepsilon}(i+1))$. Therefore we see that $\underline{s}(i+1, t)/2 \in \mathcal{E}(\underline{\varepsilon}(i+1))$ for all $t \in [0, 1)$. The assertion (i) is verified.

For the assertion (ii), it remains to check that $\overline{\mathcal{O}_{\underline{\varepsilon}^1}} \subset \overline{\mathcal{O}_{\underline{\varepsilon}(r)}}$, which follows from $\mathcal{R}_{\underline{\sigma}(\underline{\varepsilon}^1)/2} = \mathcal{R}_{\underline{s}(r,1)/2} = \lim_{t \rightarrow 1-0} \mathcal{R}_{\underline{s}(r,t)/2}$. \square

Let L_j be the segment $\{\underline{s}(j, t)/2; t \in [0, 1]\} \subset \mathbb{R}^r$ for $j = 1, \dots, r$. Theorem 9 (i) tells us that the union $\bigcup_{j=1}^r L_j$ gives the path from $\underline{\sigma}(\underline{\varepsilon}^2)/2$ to $\underline{\sigma}(\underline{\varepsilon}^1)/2$ in the set $\mathcal{E} = \bigsqcup_{\underline{\varepsilon} \in \{0,1\}^r} \mathcal{E}(\underline{\varepsilon})$. In particular, putting $\underline{\varepsilon}^1 := \underline{0}$ and $\underline{\varepsilon}^2 := \underline{\varepsilon}$ for any $\underline{\varepsilon} \in \{0, 1\}^r$, we see

that $\underline{\sigma}(\varepsilon)/2$ is connected to $\underline{0} = \underline{\sigma}(\underline{0})/2$ by the path, while any $\underline{s} \in \underline{\mathcal{E}}(\varepsilon)$ is connected to $\underline{\sigma}(\varepsilon)/2$ by a segment because $\underline{\mathcal{E}}(\varepsilon)$ is a convex set. As a result, we obtain the final result:

THEOREM 10. *The parameter set $\mathcal{E} \subset \mathbb{R}^r$ is path-connected.*

We note that \mathcal{E} is not a convex set in general. Indeed, if $\Omega_{\mathcal{V}}$ is an irreducible symmetric cone, the set $\{\alpha \in \mathbb{R}; (\alpha, \dots, \alpha) \in \mathcal{E}\}$ coincides with the so-called Wallach set, which is of the form $\{0, \frac{d}{2}, \dots, \frac{(r-1)d}{2}\} \cup (\frac{(r-1)d}{2}, +\infty)$ with some positive integer d ([1, Theorem VII.3.1]).

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Graduate School of Mathematics
Nagoya University
Chikusa-ku, Nagoya 464–8602
Japan