



Couce, E., Ridgwell, A., & Hendy, E. J. (2012). Environmental controls on the global distribution of shallow-water coral reefs. Journal of Biogeography, 39(8), 1508-1523. 10.1111/j.1365-2699.2012.02706.x

Link to published version (if available): 10.1111/j.1365-2699.2012.02706.x

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Article type: Original article

Environmental controls on the global distribution of shallow-water coral reefs

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Running head: global distribution models of shallow-water coral reefs Word count (abstract): 349 (main text body): 5818

1 **ABSTRACT**

2 **Aim**

Elucidating the environmental limits of coral reefs is central to projecting future climate
change impacts on these ecosystems and their global distribution. Recent developments
in Species Distribution Modelling (SDM) and the availability of comprehensive global
environmental datasets provide an opportunity to reassess the environmental factors
that control coral reef distribution at the global scale as well as compare the
performance of different SDM techniques.

9 **Location**

10 Shallow waters worldwide.

11 Methods

The SDM methods used include a presence-only technique: Maximum Entropy 12 13 (MaxEnt), and two presence/absence methods: Classification and Regression Trees 14 (CART) and Boosted Regression Trees (BRT). The predictive variables considered 15 include sea surface temperature (SST), salinity, aragonite saturation state (Ω_{Arag}), 16 nutrients, irradiance, water transparency, dust, and cyclone frequency and intensity. For many variables both mean and SD were considered, and at weekly, monthly and 17 18 annually-averaged timescales. All were transformed to a global 1°x1° grid to generate 19 coral reef probability maps for comparison with known locations in the ReefBase 20 (2000) dataset.

21 **Results**

Model performance was compared in terms of Receiver-Operating-Characteristic (ROC)
 curves and Area-Under-the-Curve (AUC) scores. BRT consistently outperformed other

24 methods (AUC 0.90), although MaxEnt was also within acceptable performance limits 25 (AUC 0.88). The dominant environmental predictors were the temperature variables; 26 annual mean SST, and monthly and weekly minimum SST, followed by and with their 27 relative importance differing between regions; nutrients, light availability and aragonite 28 saturation. Potential geographical bias was explored via misclassification maps of false 29 positive and negative errors on test data. While no systematic bias was found between 30 major coral provinces, false negatives were more likely for cells that corresponded to 31 'marginal' non-reef-forming coral communities e.g. southern Queensland, Australia and 32 Bermuda.

33 Main conclusions

Although SST-related variables dominate the coral reef distribution models, contributions from nutrient concentration, aragonite saturation and light availability were critical in developing models of reef presence in regions such as the Bahamas, south Pacific and Coral Triangle (particularly Sulu Sea and Spratly Is.). Agreement between BRT and MaxEnt models gives predictive confidence that they can be used to explore the environmental limits of coral reef ecosystems at a spatial scale relevant to global climate models (~1°x1°).

41

42 Keywords

Boosted Regression Trees (BRT), Classification and Regression Trees (CART), coral reef
biogeography, environmental limits, Maximum Entropy (MaxEnt), Species Distribution
Modelling (SDM).

46 **INTRODUCTION**

47 Coral reefs cover less than 0.1% of the world's oceans (Spalding & Grenfell, 1997) but constitute one of the most biologically diverse and economically valuable ecosystems on 48 Earth (e.g. Reaka-Kudla, 1997; Moberg & Folke, 1999). These 'oases' support levels of 49 50 productivity several hundred times higher than that of surrounding generally nutrient-51 poor areas (Hatcher, 1988). Symbiosis between scleractinian 'stony' coral and 52 photosynthesising unicellular algae (Symbiodinium spp.) make this possible, but also 53 limit coral reefs to the warm, shallow and clear waters of the tropics where sunlight is 54 readily available.

55

56 Reefs are vulnerable to anthropogenic disturbance, including overfishing and 57 overharvesting of coral, physical damage from destructive fishing and shipping, 58 increased sedimentation due to land use changes, and reduced water quality resulting 59 from coastal runoff. Combinations of these stresses are highly likely responsible for 60 observed declines of these emblematic ecosystems (reviewed in Carpenter et al., 2008). 61 Coral reefs now face additional pressures exerted by climate change. The increase in 62 global mean Sea Surface Temperature (SST) of at least 0.5°C since 1850 (Rayner et al., 63 2006) has been implicated in widespread coral bleaching events, and hence increased 64 mortality (Carpenter *et al.*, 2008). At the same time, the ocean uptake of CO_2 has 65 decreased seawater pH by an estimated -0.1 units since 1750 (Bindoff et al., 2007). 66 Ocean acidification may compromise the ability of reef-building corals and other 67 carbonate-producing organisms to calcify rapidly enough to maintain reef structures 68 (Kleypas et al., 2006). Recent observations of reduced calcification rates in massive

Porites colonies from the Great Barrier Reef (GBR) are consistent with this already
occurring (Cooper *et al.*, 2008; De'ath *et al.*, 2009), and in the near future, calcification
could potentially become marginal or strongly inhibited in most areas where reefs are
found today (Hoegh-Guldberg *et al.*, 2007; Cao & Caldeira, 2008).

73

74 Central to projecting future impacts of climate change and ocean acidification on these 75 ecosystems is a better understanding of what controls the biogeography of coral reefs 76 today. This question has been pursued since Dana (1843), but the seminal study of 77 global reef distribution as a function of environmental factors is Kleypas et al. (1999), in 78 which lower limits of SST, aragonite saturation state (Ω_{Arag}) and light availability were 79 identified as key factors determining coral reef distribution. The range of Ω_{Arag} values 80 within which current coral reefs were found has proved particularly influential, and has been adopted as a critical threshold on coral reef distribution under future climate 81 82 change and ocean acidification scenarios (e.g., Hoegh-Guldberg et al., 2007; Cao & 83 Caldeira, 2008).

84

Since the 1999 Kleypas *et al.* study, new global ocean environmental datasets have become available and significant advances have been made in the emerging field of Species Distribution Modelling (SDM, see Guisan & Zimmermann, 2000; Elith *et al.*, 2006; and Franklin, 2009 for an overview). These new statistical methods have been developed to meet an increasing demand from conservation planning, ecological and risk assessments, and ecosystem management amongst other fields. Assessment tools to evaluate and compare models' performance in different contexts have been

92 developed and improved (Fielding & Bell, 1997; Manel et al., 2001; Johnson & 93 Gillingham, 2005), and the limitations of SDM better assessed and documented. The 94 latter include the effects of sample size (Hernandez et al., 2006) and sample bias (Costa et al., 2010), spatial scale (Seo et al., 2009), species prevalence (Manel et al., 2001), 95 variations amongst predictions from different models (Johnson & Gillingham, 2005), 96 97 and limitations of their use in global change studies (Thuiller, 2004; Botkin et al., 2007). 98 SDM methods have been used to analyse environmental controls on coral reef 99 distribution on a regional scale, for example cross-shelf and latitudinal changes of water 100 quality measures within the GBR (De'ath & Fabricius, 2010), and deep water 101 azooxanthellate coral on a global scale (Tittensor et al., 2009).

102

103 Here we make use of recent methodological developments to revisit the question of 104 what environmental factors control surface water coral reef distribution at the global 105 scale. The predictive variables we have considered that may directly influence (or co-106 vary with other driving factors) coral reef distributions, include: temperature, aragonite 107 saturation state, salinity, nutrients, indicators of upwelling (e.g. dissolved oxygen and 108 nutrient concentrations below the photic zone), irradiance, water transparency, dust, 109 and cyclone frequency and intensity. For many of these variables we considered both 110 mean and SD at weekly, monthly, and annual time periods. We compare the predictions 111 and performance of three different SDM statistical methods: Maximum Entropy 112 (MaxEnt), Classification And Regression Trees (CART) and Boosted Regression Trees 113 (BRT). The dominant environmental controls in different geographical areas were 114 identified by studying a series of different variable combinations and mapping the

predicted coral reef distribution. Although too coarse for elucidating detailed biological requirements of coral organisms, the 1°x1° spatial scale we use in our analysis is compatible with current global climate models. Combining climate model output with these statistical environmental models of potential reef distribution could provide a valuable tool for projecting future reef distributions under anthropogenic global warming and ocean acidification.

121

122 MATERIALS AND METHODS

123 **Reef location data**

124 The point coordinates of over 11,000 coral reefs used in the study were obtained from 'ReefBase', version 2000 (ReefBase, 2000). ReefBase is a composite of published and 125 126 unpublished sources (e.g. peer-reviewed journal articles, field surveys, and other 127 reports) of coral reef presence. The database includes entries for both 'reef' and 'non-128 reef coral communities'; the latter characterised by the inability to accumulate calcium 129 carbonate. The presence records were mapped onto a 1°x1° global grid, with the cells 130 designated as 'presence' sites if they contained one or more 'ReefBase' entries (a total of 131 1242 presence sites), and 'absence' sites if the grid cell did not contain any ReefBase 132 entries. A fixed-degree projection was used instead of equal-area for convenience 133 because most environmental datasets are provided on degree-based grids. A similar 134 global analysis for stony corals on seamounts by Tittensor et al. (2009) found no 135 difference between using 1°x1° resolution and an equal-area projection.

137 Environmental data

138 The environmental variables tested in our analysis are listed in Table 1. This includes 139 variables previously considered by Kleypas et al. (1999), plus nitrate and phosphate 140 concentrations at 100m water depth, dissolved oxygen concentrations on the surface and 100m water depth, current strength, cyclone activity, atmospheric dust content, 141 142 and SST variability at various time scales. Of these, nutrient and dissolved oxygen 143 concentrations at 100m water depth were tested as proxies for upwelling regions. 144 Surface dissolved oxygen provides an additional non-linear response to temperature via 145 its solubility. Current strength and cyclone action were considered as proxies for 146 potential physical destruction of structural framework and inhibition of carbonate 147 accumulation (Riegl, 2001), while high levels of dust have previously been linked to reef 148 decline and reduced coral settlement (e.g. Shinn et al., 2000). Finally, weekly, monthly, 149 and inter-annual standard deviation (SD) of SST captures the degree to which a site is 150 exposed to highly variable conditions. For example, SST fluctuations can be associated 151 with stratification and high UV penetration, or climate phenomena such as the El Niño 152 Southern Oscillation, all contributing factors to recent mass bleaching events (e.g. Glynn 153 & Colgan, 1992; Fitt et al., 2001; Berkelmans et al., 2004).

154

As summarised in Table 1, mean annual and monthly values of SST (Locarnini *et al.*, 2006), and salinity (Antonov *et al.*, 2006), together with the annual averages of nitrate, phosphate (Garcia *et al.*, 2006a) and dissolved oxygen concentrations (Garcia *et al.*, 2006b) were obtained from the World Ocean Atlas (WOA) 2005 database. Satellitederived daily irradiance (1991-1993) is from the ISCCP project (Bishop & Rossow, 160 1991; Bishop et al., 1997) while depth of light penetration was estimated following 161 Kleypas et al. (1999), using light irradiance and satellite measurements of the diffuse 162 attenuation coefficient of (490 nm) light from GlobColour (2008). Aragonite saturation (Ω_{Arag}) data was calculated using 'CO2sys' version 1.05 (van Heuven *et al.*, 2009) from 163 164 GLODAP (Key *et al.*, 2004) alkalinity and total CO₂ together with WOA (2005) temperature, salinity, silicate and phosphate and the carbonate dissociation constants 165 166 of Dickson and Millero (1987) (Mehrbach et al's 1973 refit, see CO2sys' documentation 167 for details). Areas missing GLODAP data (e.g. Caribbean) were given Ω_{Arag} values taken from the UVic Earth system model (Weaver *et al.*, 2001; Turley *et al.*, 2010) following 168 169 the methodology of Cao and Caldeira (2008). Global dust data was obtained from NCAR 170 CCSM3 model output (Mahowald et al., 2006). The intensity of cyclone activity was the 171 "sum of wind" product obtained from UNEP/GRID-Europe (2009) and based on data of 172 >2800 historical cyclone events and modelled wind speed for 1977-2006. Weekly SST 173 data (1982-2009) was from NCEP Reynolds Optimally Interpolated SST product 174 (Reynolds et al., 2002) and was used to estimate the SD of average monthly SST in both 175 January and July and to obtain average maximum and minimum weekly temperatures. 176 Finally, annual average, monthly maximum and minimum current speeds (2002-2006) 177 were calculated from SODA version 2.0.4 (Carton & Giese, 2008).

178

179 Grid and Mask

All environmental variables were implemented on a $1^{\circ}x1^{\circ}$ grid between -60° and 60° latitude. A shallow-water mask (Fig. 1) was created from 30 second resolution SRTM30 Plus bathymetry data (Becker *et al.*, 2009). The $\pm 60^{\circ}$ latitude study region was 183 restricted to areas with a benthic substrate depth that solar light could reach, as 184 computed from the amount of Photosynthetically Active Radiation (PAR) reaching the 185 surface and the water's attenuation coefficient at a wavelength of 490 nm. To minimise 186 the number of isolated sea-mounts not resolved due to limitations in the resolution of 187 the bathymetry data, the mask was established as the grid cells with regions shallow 188 enough to be within twice the mean annual depth of light penetration. A total of 4649 189 grid cells passed the mask and contained 1115 of the 1242 designated reef presence 190 sites (see Fig. 1). The remaining 127 presence cells falling outside the mask were 191 discarded (>90% plotted on land or were incorrect/incomplete entries in the ReefBase 192 dataset). Variables missing information on a reef cell were approximated by linear 193 interpolation of neighbouring cells.

194

195 SDM methods

Three statistical methods were used to determine the relationship between the global
distribution of reefs and the environmental variables studied. These were Maximum
Entropy Modelling (MaxEnt), Classification and Regression Tree (CART), and Boosted
Regression Trees (BRT).

200

MaxEnt (Phillips *et al.*, 2006; Phillips & Dudik, 2008) is a widely used (e.g. Tittensor *et al.*, 2009; Bradley, 2010; Ficetola *et al.*, 2010) presence-only technique for the prediction of species geographic distributions (i.e. predictions are based only on the environmental conditions of sites of known occurrence). The method assumes that environmental factors act as constraints on the distribution of a species, and that within

206 those constraints, the species will tend to occupy all available habitat in a way that 207 maximises entropy (i.e., the species distribution is not restricted by any additional 208 unknown constraints). We used MaxEnt version 3.3.2, with the convergence threshold 209 value set to 10⁻⁵ and a maximum number of iterations of 500. The output was obtained 210 as the logistic prediction for presence of reefs, with values ranging from 0 (unsuitable) 211 to 1 (optimal conditions). MaxEnt's logistic prediction can be interpreted as the 212 probability of finding the species for a sampling effort similar to the one that produced 213 the training dataset (see Phillips & Dudik, 2008). As the sampling effort is typically 214 unknown, MaxEnt defaults to assuming an average 50% probability in locations where 215 conditions are favourable.

216

217 CART (Breiman et al., 1984; De'ath & Fabricius, 2000) and BRT (Friedman, 2001; 218 De'ath, 2007) are decision-tree based statistical techniques. A single tree (CART) is built 219 by repeatedly splitting the data using a simple rule each time, so that the homogeneity 220 of the resulting groups is maximised. The optimal size of the tree can be chosen from 221 different stopping criteria, such as cross-validation, to avoid over-fitting to training data 222 (De'ath & Fabricius, 2000). Decision trees have the advantages of being able to handle 223 non-linear relationships, high-order interactions, categorical or numerical data, and 224 missing data. For the BRT method a series of trees is produced instead of a single one. 225 Each tree is grown on reweighted versions of the original data, with an ever-increasing 226 weight being assigned to the cases misclassified by previous trees. The final prediction is obtained by the weighted average of predicted values across the sequence of trees. 227

BRT models have been shown to be extremely good predictors in ecological studies
(Leathwick *et al.*, 2006; Moisen *et al.*, 2006).

230

231 Both CART and BRT were fitted in R (version 2.10.1, R Development Core Team, 2009). The spatial data was processed using the *sp* library, version 0.9-65 (Pebesma & Bivand, 232 233 2005; Bivand *et al.*, 2008), while single trees were generated with version 3.1-46 of the 234 *rpart* library (Therneau & Atkinson, 2010) and boosted trees with version 1.6-3.1 of the 235 *gbm* library (Ridgeway, 2007). The method adopted to generate boosted trees is the one 236 proposed by Elith *et al.* (2008). Generating a BRT model requires specifying a number of 237 parameters that control the process. These include the Tree Complexity (TC), which 238 determines the size of each individual tree, the Learning Rate (LR), which establishes 239 each tree's contribution to the final prediction, and the Bagging Fraction (BF), or 240 percentage of random test data used to generate each of the trees. For this study, in 241 order to generate each BRT model we tested TC values of 1, 3, 5, 7, and 10, LR values of 242 0.5, 0.1, 0.05, 0.01, 0.005, and 0.001, and BF of 0.5, 0.6 and 0.75 (values suggested by 243 Elith *et al.*, 2008). The combination that optimised the model's predictive deviance from 244 coral reef observations within reasonable time constraints was chosen in each case. An 245 example of the procedure is given in Appendix S1.1 in Supporting Information.

246

247 Methods for model comparison

The output from the three models was compared in terms of Receiver Operating Characteristic (ROC) curves (reviewed in Zweig & Campbell, 1993); graphical plots of the true positives versus false positives for a binary classifier system. A curve in true251 positives vs. false-positive space is obtained as the cut-off value for the probability at 252 which a cell is considered a presence site (the 'discrimination threshold') is allowed to 253 change. The ROC method, in addition to being independent of the discrimination 254 threshold, is less biased by the prevalence of the species under study than other 255 methods commonly used to test SDM output (Manel et al., 2001). Although ROC was 256 originally developed for presence/absence techniques, it can also be applied to 257 presence-only models. Typically this involves comparing prediction at presence sites 258 with prediction at sites chosen randomly from the study region (called 'pseudo-259 absences'). In our case, as absence data was available and used in the development of 260 the presence/absence models, in order to establish a meaningful comparison, MaxEnt's 261 ROC curve was also generated using true absence data. For techniques based on 262 decision trees (CART and BRT), model performance is indicated by a single point in 263 ROC-space, corresponding to a 50% probability of presence of the species/ecosystem 264 being studied. While the discrimination threshold has an obvious cut-off, the rest of the 265 ROC curve can still be obtained if the value is allowed to change. Average Area Under 266 the Curve (AUC) scores (Bradley, 1997) were obtained from the output of 10 different 267 model runs, generated each time from a random choice of 75% of the total data 268 (training data) and tested on the remaining 25% (evaluation data).

269

270 Methods for assessing environmental variables as model predictors

271 Some of the 31 environmental variables used in this study (Table 1) are strongly 272 correlated (Appendix S3; Fig. S3.1). In order to explore whether all potential 273 environmental variables were necessary to the overall prediction and assess how the

importance of different variables differ geographically, we created an ensemble of 274 275 models using different combinations of environmental variables (Table 1). In 276 Appendices S1 and S2 we included the results of a number of standard tests for exploring SDM output, such as 'variables' contribution indices' (Tables S1.1 and S2.1), 277 which aim to measure the relative relevance of each variable to the model, and 278 279 'marginal response curves' (Figs. S1.6 S2.2, S2.3), which are graphical representation of 280 the effect on the model's output of variations of a single variable while keeping the rest 281 fixed at their average value.

282

283 **RESULTS**

284 **Prediction maps**

285 The results from all three SDM techniques (Fig. 2) are consistent with the observed 286 major regions of coral reef presence (Fig 1). The probability maps (Fig. 2) use the 287 OPTIMAL set of variables (Table 1), identified as the optimal combination of 288 environmental variables to study present coral distribution (results from other models 289 will be discussed below). Modelled coral reef probabilities are plotted for the shallow 290 water mask with values from 0 (low probability; blue) to 1 (high probability; red). 291 MaxEnt (Fig. 2b) differs from the BRT model (Fig. 2a) in having a compressed 292 probability distribution, with predicted coral reef regions predominantly assigned 293 logistic predictions close to 0.5 with limited high-probability sites. This is a 294 characteristic of the MaxEnt method's default logistic output, which assumes that 295 typical presence localities have an average probability of presence of about 0.5. Tree-296 based methods, in contrast, attempt to assign high values to presence sites, and their

predictions are not directly comparable to MaxEnt's. In addition, the CART approach
demonstrates noticeable discretisation as a result of the small number of final states (or
terminal nodes) available (Fig 2c). Enlargements of the BRT and MaxEnt prediction
maps for the Coral Triangle region are given in Supporting Information (Fig. S1.9 &
S2.7).

302

303 Histograms and misclassification maps

304 The predicted probability values for each model can also be visualised as histograms 305 (Fig. 3). These histograms separate the presence and absence sites according to 306 ReefBase data, and were obtained from 30 model runs, each using a randomly chosen 307 75% of the data for training, and the remaining 25% for model evaluation. The values 308 assigned to each cell correspond to the average of all runs in which the cell was selected 309 to evaluate the model. Fig. 3 also shows the percentage of false positives (cells without 310 reefs where the model predicts presence) and false negatives (cells with reefs where 311 the model predicts absence). BRT correctly predicted coral presence in over 60% of 312 actual reef cells, a percentage that dropped to 50% for CART. MaxEnt distribution has a 313 clear peak at 0.5, with 65% of reef cells being assigned logistic prediction values 314 between 0.4 and 0.6. Prediction errors (false positives and negatives) have also been 315 mapped in Fig. 4, to investigate possible spatial bias.

316

317 Assessment of model performance

The performance of the three SDM methods was assessed by means of ReceiverOperating Characteristic (ROC) curves. The curves in Fig. 5 correspond to the *OPTIMAL*

320 variable set (see Table 1 for variable choice). Ten models were developed, each using a 321 randomly chosen 75% of all the available data for model training; the curves (Fig. 5) 322 correspond to each model's performance evaluation on the remaining 25% data. The 323 average AUC-scores obtained from these curves are shown in Table 2. The presence/absence BRT model was the most successful, with an AUC score of 0.9, while 324 325 the presence-only MaxEnt model performed almost as well (Fig. 5, Table 2). AUC scores 326 above 0.9 correspond to 'highly accurate' models according to Swets (1988), with the 327 0.7-0.9 range corresponding to models with some useful applications and scores below 328 0.7 indicating 'low accuracy. BRT represents an upgrade of CART and clearly 329 outperforms it.

330

Prediction maps of coral reef distribution were developed with different subsets of the predictive variables using both BRT and MaxEnt (Fig. 6). Table 1 lists the model names and the selected variables used to develop each of the models. The probability histograms for each model and the comparison of their performance in ROC space are also provided in Appendix S3 (Figs. S3.2 and S3.3). Despite very similar, often overlapping results in ROC space, the models developed from different variable combinations display distinct spatial distribution predictions of coral reefs presence.

338

339 Discussion

340 **Coral biogeography and the spatial structure of environmental control**

All SDM models indicate that coral reef distribution is primarily limited to regions ofhigh SST, with high light availability, salinity, aragonite saturation state, and low

343 nutrient concentrations being of secondary significance. Levels of dust, current speed, 344 cyclone intensities, and inter-annual SST variability, are all typically assigned to be of 345 minor importance. The mean percentage contribution values and SD in 10 model runs 346 are given for both BRT and MaxEnt outputs (Tables S1.1 and S2.1). The BRT estimation 347 of percentage contribution takes into account the number of times each variables is 348 selected for splitting weighted by the square improvement of the model as a result of 349 those split and averaged across the sequence of trees (Friedman & Meulman, 2003). 350 Whereas, MaxEnt keeps track of the increase in gain due to each of the variables used in 351 fitting the model, and the normalised percentage contribution of all variables are 352 considered a measure of each variable's relevance to the final result (Phillips, 2006). 353 However, because some of the variables are highly correlated, caution is required in the 354 interpretation of these contribution values. An alternative for MaxEnt is Jackknife tests 355 (Appendix S2; Figs. S2.4-6). In order to explore the spatial structure of environmental 356 controls on coral reef biogeography, the relative contribution of each variable can also 357 be analysed in conjunction with the probability maps (Figs. 6 & 7). Testing different 358 combinations of potential predictive environmental variables provides insight into the 359 control of these highly correlated variables on model response and global distribution 360 of coral reefs.

361

In combination, SST variables contribute close to 50%-60% of the environmental controls on coral distributions according to all SDM methods (using *OPTIMAL* model variables; output Fig. 3). This is not surprising. First described in the 19th century (Dana, 1843), the high correlation between elevated surface temperature and coral 366 distribution has been well documented (e.g. Stoddart, 1969; Rosen, 1984; Veron & 367 Minchin, 1992). The majority of coral reefs are found in water temperatures with an 368 annual minimum SST greater than 18°C and average minimum weekly temperature 369 above 16°C (reviewed in Klevpas, 2007). The marginal response curves for both BRT and MaxEnt methods indicate threshold values for minimum monthly and weekly SST 370 371 that are consistent with these estimates (S2 and S3). Mechanisms through which high 372 SST favours the presence of coral reefs include positive physiological effects on growth 373 and calcification rates (Harriott, 1999; Lough & Barnes, 2000), increased reproductive 374 viability (reviewed in Harriott & Banks, 2002), and ecological advantages in the 375 competition with macro-algae (Johannes et al., 1983) linked to nutrient availability and 376 herbivory pressures (McCook et al., 2001; Smith, 2008).

377

378 Models based on SST variables alone (Table 1 model SST), however, provide limited 379 explanation of the global distribution of coral reefs (Figs. 6a & 7a) because they fail to 380 account for reefs in higher latitudes, such as the Southern GBR, New Caledonia, South 381 French Polynesia, and Northern Red Sea, South Japan and Ryukyu Islands. The 382 predictions for certain high-temperature regions (e.g. South China Sea/Sulu Sea and 383 South East Papua New Guinea) were also poor. Identifying what environmental factors 384 in addition to SST control distribution at these sites is particularly critical for 385 understanding how reefs will respond under future global change scenarios. Modelled 386 reef distribution is improved by the inclusion of light availability (Figs. 6d & 7d; model 387 *SST LDepth*), nutrients (Figs. 6e & 7e; model *SST Nutr*), aragonite saturation (Figs. 6b & 388 7b; model *SST_Arag*), and secondary SST variables (Figs. 6f & 7f; model *SST_2ndSST*).

Each model tends to reinforce *SST* predictions due to synergistic interactions, but also
demonstrates critical addition information that is needed for correctly modelling
particular geographical locations.

392

Water clarity, together with solar PAR irradiance, determine the amount of light 393 394 available and hence limit the depth of reef formation via depth-related control of coral 395 primary productivity and calcification rates (Gattuso *et al.*, 2006). Light availability, and 396 therefore the maximum depth of reef formation, decreases with increasing latitude 397 (Gattuso *et al.*, 2006). However, the addition of light penetration depth variables 398 improves predictions in both the Pacific and Caribbean regions (Figs. 6d & 7d) by 399 extending the latitudinal range of predicted reef habitats (e.g. to include southern 400 islands of French Polynesia). Including light availability also improves predictions for 401 the South China Sea/ Sulu Sea region and the Bahamas.

402

403 In general terms the inclusion of seawater nutrient (phosphate and nitrate) 404 concentrations is expected to exclude modelled reefs from areas enriched by riverine 405 discharge, upwelling along eastern equatorial ocean boundaries and higher latitudes in 406 response to the latitudinal gradient of increasing nutrients. Coral reef manipulation 407 studies reveal a more complex relationship, which is often species and region-408 dependant and with responses that are typically subtle (e.g. Koop *et al.*, 2001; Dizon & 409 Yap, 2005; Smith *et al.*, 2005). Instead, macroalgae abundance, which generally correlates with nutrient concentrations, may play a decisive controlling role (e.g. 410 411 Johannes *et al.*, 1983; Birkeland, 1988; De'ath & Fabricius, 2010). Macroalgae have been shown to directly interfere with coral recruitment, suppress coral growth and fecundity, increase disease-related mortality, and compete with coral for space (reviewed in McCook *et al.*, 2001; Smith *et al.*, 2006; Mumby & Steneck, 2008). The inclusion of surface nutrient concentrations is critical for modelling sites in the Southern GBR and

Southern Japan (Figs. 6e & 7e). These parameters also have the strongest influence onimproving SDM predictions across the Caribbean.

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419 Aragonite saturation has the largest effect in both BRT and MaxEnt after SST, light and 420 nutrient variables (Figs. 6b & 7b; Appendix Tables S1.1 & S2.1). There is a well-421 documented relationship between low Ω_{Arag} and reduced coral calcification rates 422 (experimental studies reviewed in Kleypas et al., 2006; e.g. field studies Cooper et al., 423 2008; De'ath et al., 2009). Low cementation of reef framework and high bioerosion 424 rates are also associated with low Ω_{Arag} (e.g. Manzello *et al.*, 2008; Silverman *et al.*, 425 2009). In addition, high magnesium calcite precipitating coralline algae, which play a 426 key role in the cementation of coral rubble into solid reef, are particularly sensitive to 427 carbonate saturation state (Kuffner et al., 2008). The SST_Arag model reinforces 428 predictions of reef presence in areas already picked up by the SST model, as expected 429 since both datasets are highly correlated (Appendix S3; Fig. S3.1). Although the addition 430 of Ω_{Arag} dramatically improves predictions in areas such as the Spratly Islands / Sulu Sea and Southern French Polynesia (Figs. 6b & 7b), predictions for the Northern GBR 431 432 deteriorate in the BRT model. The latter result potentially highlights an issue with the quality of the Ω_{Arag} dataset for this region. 433

435 Modelling probability of reef presence in the Southern GBR proves particularly 436 challenging (Figs. 6 &7), although the OPTIMAL variable selection is capable of 437 providing the information needed (Fig. 2). Reef formation in this area is apparently 438 controlled by a different combination of conditions than those acting on the Northern 439 section. Of all the variable models presented in Figs. 6 and 7, only the inclusion of 440 nutrients and secondary SST variables improve predictions for the Southern GBR. Other 441 regions challenging to model include the Galapagos Islands and Bermuda. In a sense it is 442 reassuring that the SDMs are failing to pick up these areas, because they correspond to 443 regions with known adverse conditions for present-day formation of reefs and currently 444 support low coral biodiversity (Glynn et al., 1983; Logan & Tomascik, 1991).

445

446 With a large enough number of explanatory variables, a statistical model may succeed in 447 explaining data by 'finding' causal relationships that are in fact dubious or nonexistent. 448 The process is known as over-fitting, and weakens the utility and applicability of the 449 model. Environmental variables having an effect which appear in conflict with biological 450 knowledge of coral habitat and physiology may indicate this occurring and hence can be 451 identified (and omitted) on this basis. This appears to be the case with the variables 452 included as indicators of upwelling (nutrients at 100m depth and dissolved oxygen both 453 at the surface and at 100m). By comparing the prediction maps for the SST and the 454 SST_upwllng models (Figs. 6a & c and 7a & c) it is obvious that the addition of the 455 upwelling indicators give an improved model 'prediction'. The prediction of habitat 456 suitability for coral reefs improves most, however, in areas that are either distant to 457 upwelling processes (such as Bermuda or Northern Red Sea) or where upwelling 458 conditions are expected to pose a serious challenge to reef presence, rather than be an
459 asset (e.g. Galapagos Islands). We highlight this example as a warning of how overfitting
460 could obscure important variables and responses in SDM. As a result we have opted for
461 not including these variables in our final predictor set and 'optimal' model (*OPTIMAL*).

462

463 **Geographical bias and error analysis of mapped SDM predictions**

464 Misclassification maps (Fig. 4; based on the false positives and false negatives averaged 465 from evaluation data of 30 model runs) were used to test for geographical bias in the 466 predicted probabilities. From visual inspection, no systematic bias is apparent between 467 major coral provinces (i.e. Caribbean and Indo-Pacific regions); any clustering of errors 468 takes place at lower spatial scales. All three SDM techniques, MaxEnt, CART and BRT, 469 fail to model suitable habitat for coral reefs at certain sites for which there are ReefBase 470 entries (false negatives). Interestingly, the percentage of false negatives is much higher 471 for cells that according to the reef location database correspond to non reef-forming 472 coral communities. For BRT (and MaxEnt), a total of 53% (65%) of cells with non-reef 473 coral communities give false negatives, compared to only 37% (45%) of the remaining presence sites. Non-reef entries largely correspond to sites classified as 'marginal' by 474 475 Kleypas et al. (1999) and include the Pacific coast of Costa Rica and Panama, Bermuda, 476 the southern coasts of the main islands of Japan, southern Queensland, Australia and the 477 Galápagos Islands. Reef formation at these sites is known to be challenging (e.g. 478 mainland Japan, Veron & Minchin, 1992; Solitary Islands, Harriott et al., 1994; 479 Galápagos, Glynn *et al.*, 1983), and typically coral communities are present rather than 480 reefs (ReefBase, 2000) because of an inability to accumulate CaCO₃ and a diminished

481 presence of primary reef-building taxa such as Porites and Acropora (Buddemeier & 482 Smith, 1999; Harriott & Banks, 2002). On the Pacific coast of Costa Rica and Panama, 483 reef development is sporadic and mostly takes place around offshore islands. D'Croz & Robertson (1997) suggest this might be due to temperature extremes associated to El 484 485 Niño events and frequent cool upwelling episodes, with the formation of reef in the 486 coast further prevented by high concentration of nutrients, likely caused by terrestrial 487 runoff. The consistent SDM results across models hint that this region is currently 488 unsuitable for coral reef accretion. Missing input variable(s) may also explain some 489 consistent SDM output errors. For example, all three methods misclassify cells to give 490 false negatives across the region of the West Timor Sea and Rowley Shoals, off NW 491 Australia, where coral reefs are known to be present (Spalding *et al.*, 2001).

492

493 **Performance comparison of the different SDM techniques**

494 All three models were able to produce distributions that are consistent with the major 495 regions of coral reef distribution. However, the three SDM techniques used in this paper 496 are static, and therefore our underlying assumption is that surface water coral reefs are 497 in equilibrium (or quasi-equilibrium) with their environment (e.g. Peterson et al., 1999; 498 Pearman et al., 2008). Non-equilibrium situations are often considered more realistic in 499 an ecological context (Guisan & Zimmermann, 2000; Austin, 2002), but the required 500 global environmental datasets do not exist with the temporal frequency required to run 501 dynamic simulation models (Botkin et al., 2007). Instead, we considered transient 502 effects in the analysis by including them as additional predictive variables (e.g. tropical

storm frequency and intensity, standard deviations in SST at inter-annual and weeklytime scales). None were found to have a significant impact on the models.

505

506 Presence-only methods, such as MaxEnt, provide a test of the potential anomalies in 507 model results created by inaccuracies or incompleteness of the input datasets. For 508 example, SDM results for wide-ranging and tolerant species can be particularly sensitive 509 to absence data (Brotons et al., 2004). Hirzel et al. (2001) also showed that presence-510 only models seemed to perform better than presence/absence ones in out-of-511 equilibrium situations (i.e. when a species does not occupy all suitable habitat) and so 512 such models might be better suited to predict response to environmental change. A 513 limitation of static modelling is that the realised habitat is assumed to equal the 514 'fundamental' one (i.e. that coral reefs are present in all areas with an environment 515 compatible with requirements). However, even under equilibrium conditions, absence 516 might be due to dispersal limitations. For presence/absence models this can give rise to 517 an *a-priori* bias in the training data (Hutchinson, 1957; Pulliam, 2000; Phillips et al., 518 2006), and in out-of-equilibrium situations migration limitations can become a 519 significant source of uncertainty that is also difficult to estimate (reviewed in Thuiller et 520 al., 2008). Comparison with the output from presence-only methods can pinpoint the magnitude of some of these effects on model performance (Gu & Swihart, 2004). 521 522 Encouragingly for our study, the presence-only method, MaxEnt, and the 523 presence/absence method, BRT, perform almost equally well (Table 2) in evaluation 524 tests (e.g. for ability to separate presence/absence signal) and in comparisons between 525 modelled predictions and actual presence/absence data. The application of both SDM

approaches in parallel, therefore, increases confidence in the models as predictive tools
for understanding the global distribution of surface water coral reefs under present
conditions.

529

530 **Conclusions**

531 We have used three SDM methods to predict coral reef presence/absence based on 532 environmental factors at 1° resolution. At this scale, SST-related variables are found to 533 be dominant in explaining the current biogeography of coral reefs, but alone are 534 insufficient to give an accurate picture of global distribution. Surface nutrient 535 concentration, aragonite saturation and light availability prove critical in accurately 536 defining the limits of coral reef ecosystems in both the Caribbean and Pacific. We find 537 that light availability is particularly crucial for the South Pacific, with the exception of 538 the Southern GBR, where nutrient concentrations are key. The Coral Triangle region is 539 poorly modelled using just SST variables, and an accurate prediction requires a 540 combination of nutrients, light availability and most significantly, aragonite saturation.

541

We have tested model performance on evaluation data, and find that BRT, a presence/absence technique, performs slightly better than presence-only MaxEnt. Our prediction confidence is strengthened by this result because any major inconsistencies between the two would indicate issues associated with the input data, underlying assumptions, or model selection.

Although the 1°x1° scale of our analysis is too coarse to capture local environmental 548 549 controls at reef sites and their impact on local-scale distribution, our chosen resolution 550 is consistent with the current generation of global climate models (ca. 1°x1°) and the 551 available global environmental data sets. Aggregation to coarser spatial scales also 552 increases the reliability of a species absence (McPherson *et al.*, 2006), and can thus 553 offset limitations in the reef location database. Explicit linking of environmental-554 biogeographical and climate models will facilitate the generation of future (and past) 555 projections (and sensitivities) of coral reef biogeography to global environmental 556 change.

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801	Supporting Information
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803	Additional Supporting Information may be found in the online version of this article:
804	
805	Appendix S1 BRT model optimisation, output and analysis.
806	Appendix S2 MaxEnt model output and analysis.
807	Appendix S3 Environmental variable correlations and contributions.
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810	Acknowledgements
811	E.C. is funded by a U. Bristol PhD scholarship, A.R. by the Royal Society, and E.J.H by a
812	RCUK Academic Fellowship and additional support from a NERC Fellowship
813	(NE/D010012/1). The authors greatly valued the constructive insights and suggestions
814	of the Reviewers and the Editor. E.C. also wishes to acknowledge Hannah Rose and Dr.
815	Kelvyn Jones for their suggestions and help regarding SDM methods.

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817 Biosketch

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840 Figure headings:

841

Figure 1. Mask used for the study (grey), corresponding to shallow waters between -60°
and 60° latitude. Presence cells (those containing at least one entry from the ReefBase
version 2000 dataset) are shown in black. The areas not included in the analysis are
white. Behrmann Projection.

846

Figure 2. Predicted probability ((a) BRT and (c) CART) or logistic prediction ((b)

848 MaxEnt) of a coral reef being present based on the environmental variables from the

849 *OPTIMAL* model variable dataset (Table 1) and using the complete dataset for training.

Each cell is designated a likelihood value for the predicted probability or logistic

prediction from 0 (unlikely; in blue) to 1 (highly likely habitat; in red).

852

853 Figure 3. Histogram for the average modelled probabilities (BRT and CART), or logistic 854 prediction (MaxEnt), of a coral reef being present in the shallow-water grid cells using 855 BRT (a), MaxEnt (b) or CART (c). Cells where coral reefs or communities are present 856 according to the ReefBase dataset are shown in grey, absence sites in white. The 857 probability (logistic prediction in MaxEnt's case) assigned to each cell is the average of 858 the runs in which it is taken as evaluation data out of a total of 30 random runs. The 859 distribution of model results that are false positives (red) or false negatives (blue) is 860 also shown.

Figure 4. Maps showing the spatial distribution of false positives (red) and false
negatives (blue) obtained for evaluation cells in 30 runs of BRT (a), MaxEnt (b) and
CART (c) models. Areas in grey in the MaxEnt map indicate cells where environmental
data was missing (e.g. areas missing aragonite saturation data) because predictions can
not be obtained using MaxEnt at sites with missing environmental data; in contrast
tree-based techniques are able to look for alternative variables.

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Figure 5. ROC curves for the three model techniques and using 25% evaluation data
chosen randomly for each of 10 model runs. The optimal point in ROC space for BRT
(circles) and CART (triangles) corresponds to a threshold value of 50% probability of
presence.

873

Figure 6. Prediction maps for BRT models using various combinations of environmental
variables to evaluate predictor contributions to model performance. The predictor
subset used in each of the models are given in Table 1; SST variables (a), SST variables
plus aragonite saturation state (b), SST plus upwelling variables (c), SST plus light
variables (d), SST plus nutrient variables, (e) SST plus secondary SST variables
capturing SST variability on various timescales (f).

Figure 7. Prediction maps for MaxEnt models (given in Table 1) using various

882 combinations of environmental data to evaluate individual variable contributions to

model performance. As for Figure 6, the predictor subset used in each of the models are

given in Table 1; SST variables (a), SST variables plus aragonite statuation state (b),

- 885 SST plus upwelling variables (c), SST plus light variables (d), SST plus nutrient
- 886 variables, (e) SST plus secondary SST variables capturing SST variability on various
- timescales (f).





Figure 2.



Figure 3.



Figure 4.



Figure 5.

