



THE UNIVERSITY *of* EDINBURGH

Edinburgh Research Explorer

Derived deformations of schemes

Citation for published version:

Pridham, JP 2012, 'Derived deformations of schemes' Communications in Analysis and Geometry, vol 20, no. 3, pp. 529-563. DOI: <http://dx.doi.org/10.4310/CAG.2012.v20.n3.a4>

Digital Object Identifier (DOI):

[DOI: http://dx.doi.org/10.4310/CAG.2012.v20.n3.a4](http://dx.doi.org/10.4310/CAG.2012.v20.n3.a4)

Link:

[Link to publication record in Edinburgh Research Explorer](#)

Document Version:

Early version, also known as pre-print

Published In:

Communications in Analysis and Geometry

General rights

Copyright for the publications made accessible via the Edinburgh Research Explorer is retained by the author(s) and / or other copyright owners and it is a condition of accessing these publications that users recognise and abide by the legal requirements associated with these rights.

Take down policy

The University of Edinburgh has made every reasonable effort to ensure that Edinburgh Research Explorer content complies with UK legislation. If you believe that the public display of this file breaches copyright please contact openaccess@ed.ac.uk providing details, and we will remove access to the work immediately and investigate your claim.



DERIVED DEFORMATIONS OF SCHEMES

J.P.PRIDHAM

ABSTRACT. We introduce a new approach to constructing derived deformation groupoids, by considering them as parameter spaces for strong homotopy bialgebras. This allows them to be constructed for all classical deformation problems, such as deformations of an arbitrary scheme, in any characteristic.

INTRODUCTION

In [Pri2], the theory of simplicial deformation complexes (SDCs) was expounded as a means of governing deformation problems, giving an alternative to the theory of differential graded Lie algebras (DGLAs). The main advantages of SDCs over DGLAs are that they can be constructed canonically (and thus for a wider range of problems), and are valid in all characteristics.

In [Man2], Manetti showed that given a DGLA, or even an SHLA, governing a deformation problem, it is possible to define an extended deformation functor. The approach in this paper can almost be regarded as opposite to this — we try, for any deformation problem, to define an extended deformation functor with a geometric interpretation, meaning that the functor still parametrises geometric objects. We then see how this functor can be recovered from the SDC governing the problem.

Since almost all examples of SDCs come from monadic and comonadic adjunctions, in Section 4 we look at how to extend deformation groupoids in these scenarios. For a monad \mathbb{T} , the solution is to look at the strong homotopy \mathbb{T} -algebras, as defined by Lada in [CLM]. The idea is that the monadic axioms are only satisfied up to homotopy, with the homotopies satisfying further conditions up to homotopy, and so on. This approach allows us to define a quasi-smooth extended deformation functor associated to any SDC, with the same cohomology.

Using the constructions of §§3.2 and 3.3, we describe extended deformations of morphisms and diagrams (giving new results even for the problems in [Pri2]). This defines cohomology of a morphism in any such category, giving a variant of Van Osdol's bicohomology ([VO]). One consequence is that the space describing extended deformations of the identity morphism on an object D is just the loop space of the space of extended deformations of D .

The structure of the paper is as follows. Sections 1 and 2 are introductory, summarising results from [Pri5] and properties of monads and comonads, respectively. Section 3 reprises material from [Pri2] on SDCs, and includes new results constructing SDCs associated to diagrams in §§3.2 and 3.3. The key motivating examples of deformations of a scheme are described in Examples 3.8 and 3.19.

Section 4 then gives the construction of the derived deformation functor (Definition 4.4), together with a simplified description of derived deformations of a morphism (Proposition 4.9), and the characterisation of derived deformations of an identity morphism as a loop space (Proposition 4.10).

This work was supported by Trinity College, Cambridge; and by the Engineering and Physical Sciences Research Council [grant number EP/F043570/1].

In [Pri2], it was shown that SDCs are equivalent to \mathbb{N}_0 -graded DGLAs in characteristic 0, in such a way that the associated deformation groupoids are equivalent. In Appendix A, we show how that the associated extended deformation functors are also equivalent.

CONTENTS

Introduction	1
1. Derived deformation functors	2
1.1. Simplicial Artinian rings	2
1.2. Properties of morphisms	3
1.3. Derived deformation functors	3
1.4. Quotient spaces	5
1.5. Cohomology and obstructions	5
1.6. Model structures	6
2. Monads and comonads	8
2.1. Algebras and coalgebras	8
2.2. Bialgebras	9
3. Constructing SDCs	9
3.1. SDCs from bialgebraic structures	10
3.2. SDCs from diagrams	11
3.3. Constrained deformations	13
4. Extended deformation functors from SDCs	14
4.1. Deformations of morphisms	16
Appendix A. Comparison with [Pri2]	17
A.1. DGLAs	18
A.2. Cosimplicial groups	18
A.3. The final comparison	20
References	21

1. DERIVED DEFORMATION FUNCTORS

With the exception of §1.4, the definitions and results in this section can all be found in [Pri5]. Fix a complete local Noetherian ring Λ , with maximal ideal μ and residue field k .

1.1. Simplicial Artinian rings.

Definition 1.1. Let \mathcal{C}_Λ denote the category of local Artinian Λ -algebras with residue field k . We define $s\mathcal{C}_\Lambda$ to be the category of Artinian simplicial local Λ -algebras, with residue field k .

Definition 1.2. Given a simplicial complex V_\bullet , recall that the normalised chain complex $N^s(V)_\bullet$ is given by $N^s(V)_n := \bigcap_{i>0} \ker(\partial_i : V_n \rightarrow V_{n-1})$, with differential ∂_0 . The simplicial Dold-Kan correspondence says that N^s gives an equivalence of categories between simplicial complexes and non-negatively graded chain complexes in any abelian category. Where no ambiguity results, we will denote N^s by N .

Lemma 1.3. *A simplicial complex A_\bullet of local Λ -algebras with residue field k and maximal ideal $\mathfrak{m}(A)_\bullet$ is Artinian if and only if:*

- (1) *the normalisation $N(\cot A)$ of the cotangent space $\cot A := \mathfrak{m}(A)/(\mathfrak{m}(A)^2 + \mu\mathfrak{m}(A))$ is finite-dimensional (i.e. concentrated in finitely many degrees, and finite-dimensional in each degree).*
- (2) *For some $n > 0$, $\mathfrak{m}(A)^n = 0$.*

Proof. [Pri5] Lemma 1.16 □

As in [Gro], we say that a functor is left exact if it preserves all finite limits. This is equivalent to saying that it preserves final objects and fibre products.

Definition 1.4. Define \mathbf{Sp} to be the category of left-exact functors from \mathcal{C}_Λ to \mathbf{Set} . Define \mathbf{cSp} to be the category of left-exact functors from $s\mathcal{C}_\Lambda$ to \mathbf{Set} .

Definition 1.5. Given a functor $F : \mathcal{C}_\Lambda \rightarrow \mathbf{Set}$, we write $F : s\mathcal{C}_\Lambda \rightarrow \mathbf{Set}$ to mean $A \mapsto F(A_0)$ (corresponding to the inclusion $\mathbf{Sp} \hookrightarrow \mathbf{cSp}$).

1.2. Properties of morphisms.

Definition 1.6. As in [Man1], we say that a functor $F : \mathcal{C}_\Lambda \rightarrow \mathbf{Set}$ is smooth if for all surjections $A \rightarrow B$ in \mathcal{C}_Λ , the map $F(A) \rightarrow F(B)$ is surjective.

Definition 1.7. We say that a map $f : A \rightarrow B$ in $s\hat{\mathcal{C}}_\Lambda$ is acyclic if $\pi_i(f) : \pi_i(A) \rightarrow \pi_i(B)$ is an isomorphism of pro-Artinian Λ -modules for all i . f is said to be surjective if each $f_n : A_n \rightarrow B_n$ is surjective.

Note that for any simplicial abelian group A , the homotopy groups can be calculated by $\pi_i A \cong H_i(NA)$, the homology groups of the normalised chain complex. These in turn are isomorphic to the homology groups of the unnormalised chain complex associated to A .

Definition 1.8. We define a small extension $e : I \rightarrow A \rightarrow B$ in $s\mathcal{C}_\Lambda$ to consist of a surjection $A \rightarrow B$ in $s\mathcal{C}_\Lambda$ with kernel I , such that $\mathfrak{m}(A) \cdot I = 0$. Note that this implies that I is a simplicial complex of k -vector spaces.

Lemma 1.9. *Every surjection in $s\mathcal{C}_\Lambda$ can be factorised as a composition of small extensions. Every acyclic surjection in $s\mathcal{C}_\Lambda$ can be factorised as a composition of acyclic small extensions.*

Proof. [Pri5] Lemma 1.23. □

Definition 1.10. We say that a morphism $\alpha : F \rightarrow G$ in \mathbf{cSp} is smooth if for all small extensions $A \twoheadrightarrow B$ in $s\mathcal{C}_\Lambda$, the map $F(A) \rightarrow F(B) \times_{G(B)} G(A)$ is surjective.

Similarly, we call α quasi-smooth if for all acyclic small extensions $A \rightarrow B$ in $s\mathcal{C}_\Lambda$, the map $F(A) \rightarrow F(B) \times_{G(B)} G(A)$ is surjective.

Lemma 1.11. *A morphism $\alpha : F \rightarrow G$ in \mathbf{Sp} is smooth if and only if the induced morphism between the objects $F, G \in \mathbf{cSp}$ is quasi-smooth, if and only if it is smooth.*

Proof. [Pri5] Lemma 1.31. □

1.3. Derived deformation functors.

Definition 1.12. Define the \mathbf{scSp} to be the category of left-exact functors from $s\mathcal{C}_\Lambda$ to the category \mathbb{S} of simplicial sets.

Definition 1.13. A morphism $\alpha : F \rightarrow G$ in \mathbf{scSp} is said to be smooth if

- (S1) for every acyclic surjection $A \rightarrow B$ in $s\mathcal{C}_\Lambda$, the map $F(A) \rightarrow F(B) \times_{G(B)} G(A)$ is a trivial fibration in \mathbb{S} ;
- (S2) for every surjection $A \rightarrow B$ in $s\mathcal{C}_\Lambda$, the map $F(A) \rightarrow F(B) \times_{G(B)} G(A)$ is a surjective fibration in \mathbb{S} .

A morphism $\alpha : F \rightarrow G$ in \mathbf{scSp} is said to be quasi-smooth if it satisfies (S1) and

- (Q2) for every surjection $A \rightarrow B$ in $s\mathcal{C}_\Lambda$, the map $F(A) \rightarrow F(B) \times_{G(B)} G(A)$ is a fibration in \mathbb{S} .

Definition 1.14. Given $A \in s\mathcal{C}_\Lambda$ and a finite simplicial set K , define $A^K \in \mathcal{C}_\Lambda$ by

$$(A^K)_i := \text{Hom}_{\mathbb{S}}(K \times \Delta^i, A) \times_{\text{Hom}_{\text{Set}}(\pi_0 K, k)} k.$$

Definition 1.15. Given $F \in sc\text{Sp}$, define $\underline{F} : s\mathcal{C}_\Lambda \rightarrow \mathbb{S}$ by

$$\underline{F}(A)_n := F_n(A^{\Delta^n}).$$

For $F \in c\text{Sp}$, we may regard F as an object of $sc\text{Sp}$ (with the constant simplicial structure), and then define \underline{F} as above.

Lemma 1.16. *A map $\alpha : F \rightarrow G$ in $c\text{Sp}$ is smooth (resp. quasi-smooth) if and only if the induced map of functors $\underline{\alpha} : \underline{F} \rightarrow \underline{G}$ is smooth (resp. quasi-smooth) in $sc\text{Sp}$.*

Proof. [Pri5] Lemma 1.36. □

The following Lemma will provide many examples of functors which are quasi-smooth but not smooth.

Lemma 1.17. *If $F \rightarrow G$ is a quasi-smooth map of functors $F, G : s\mathcal{C}_\Lambda \rightarrow \mathbb{S}$, and $K \rightarrow L$ is a cofibration in \mathbb{S} , then*

$$F^L \rightarrow F^K \times_{G^K} G^L$$

is quasi-smooth.

Proof. This is an immediate consequence of the fact that \mathbb{S} is a simplicial model category, following from axiom SM7, as given in [GJ] §II.3. □

The following lemma is a consequence of standard properties of fibrations and trivial fibrations in \mathbb{S} .

Lemma 1.18. *If $F \rightarrow G$ is a quasi-smooth map of functors $F, G : s\mathcal{C}_\Lambda \rightarrow \mathbb{S}$, and $H \rightarrow G$ is any map of functors, then $F \times_G H \rightarrow H$ is quasi-smooth.*

Definition 1.19. A map $\alpha : F \rightarrow G$ of functors $F, G : \mathcal{C}_\Lambda \rightarrow \mathbb{S}$ is said to be smooth (resp. quasi-smooth, resp. trivially smooth) if for all surjections $A \rightarrow B$ in \mathcal{C}_Λ , the maps

$$F(A) \rightarrow F(B) \times_{G(B)} G(A)$$

are surjective fibrations (resp. fibrations, resp. trivial fibrations).

Proposition 1.20. *A map $\alpha : F \rightarrow G$ of left-exact functors $F, G : \mathcal{C}_\Lambda \rightarrow \mathbb{S}$ is smooth if and only if the maps $F_n \xrightarrow{\alpha_n} G_n$ of functors $F_n, G_n : \mathcal{C}_\Lambda \rightarrow \text{Set}$ are all smooth.*

Proof. [Pri5] Proposition 1.39. □

Proposition 1.21. *If a morphism $F \xrightarrow{\alpha} G$ of left-exact functors $F, G : s\mathcal{C}_\Lambda \rightarrow \mathbb{S}$ is such that the maps*

$$\theta : F(A) \rightarrow F(B) \times_{G(B)} G(A)$$

are surjective fibrations for all acyclic small extensions $A \rightarrow B$, then $\underline{\alpha} : \underline{F} \rightarrow \underline{G}$ is quasi-smooth (resp. smooth) if and only if θ is a fibration (resp. surjective fibration) for all small extensions $A \rightarrow B$.

Proof. [Pri5] Proposition 1.63. □

Definition 1.22. We will say that a morphism $\alpha : F \rightarrow G$ of quasi-smooth objects of $sc\text{Sp}$ is a weak equivalence if, for all $A \in s\mathcal{C}_\Lambda$, the maps $\pi_i F(A) \rightarrow \pi_i G(A)$ are isomorphisms for all i .

1.4. Quotient spaces.

Definition 1.23. Given functors $X : s\mathcal{C}_\Lambda \rightarrow \mathbb{S}$ and $G : s\mathcal{C}_\Lambda \rightarrow s\mathbf{Gp}$, together with a right action of G on X , define the quotient space by

$$[X/G]_n = (X \times^G WG)_n = X_n \times G_{n-1} \times G_{n-2} \times \dots \times G_0,$$

with operations as standard for universal bundles (see [GJ] Ch. V). Explicitly:

$$\begin{aligned} \partial_i(x, g_{n-1}, g_{n-2}, \dots, g_0) &= \begin{cases} (\partial_0 x * g_{n-1}, g_{n-2}, \dots, g_0) & i = 0; \\ (\partial_i x, \partial_{i-1} g_{n-1}, \dots, (\partial_0 g_{n-i}) g_{n-i-1}, g_{n-i-2}, \dots, g_0) & 0 < i < n; \\ (\partial_n x, \partial_{n-1} g_{n-1}, \dots, \partial_1 g_1) & i = n; \end{cases} \\ \sigma_i(x, g_{n-1}, g_{n-2}, \dots, g_0) &= (\sigma_i x, \sigma_{i-1} g_{n-1}, \dots, \sigma_0 g_{n-i}, e, g_{n-i-1}, g_{n-i-2}, \dots, g_0). \end{aligned}$$

The space $[\bullet/G]$ is also denoted $\bar{W}G$, and is a model for the classifying space BG of G . Note replacing WG with any other fibrant cofibrant contractible G -space EG will give the same properties.

Lemma 1.24. *If $G : s\mathcal{C}_\Lambda \rightarrow s\mathbf{Gp}$ is smooth, then $\bar{W}G$ is smooth.*

Proof. For any surjection $A \rightarrow B$, we have $G(A) \rightarrow G(B)$ fibrant and surjective on π_0 , which by [GJ] Corollary V.6.9 implies that $\bar{W}G(A) \rightarrow \bar{W}G(B)$ is a fibration. If $A \rightarrow B$ is also acyclic, then everything is trivial by properties of \bar{W} and G . \square

Remark 1.25. Observe that this is our first example of a quasi-smooth functor which is not a right Quillen functor for the simplicial model structure. The definitions of smoothness and quasi-smoothness were designed with $\bar{W}G$ in mind.

Lemma 1.26. *If X is quasi-smooth, then so is $[X/G] \rightarrow \bar{W}G$.*

Proof. This follows from the observation that for any fibration (resp. trivial fibration) $Z \rightarrow Y$ of G -spaces, $[Z/G] \rightarrow [Y/G]$ is a fibration (resp. trivial fibration). \square

Corollary 1.27. *If X is quasi-smooth and G smooth, then $[X/G]$ is quasi-smooth.*

Proof. Consider the fibration $X \rightarrow [X/G] \rightarrow \bar{W}G$. \square

1.5. Cohomology and obstructions. Given a quasi-smooth morphism $\alpha : F \rightarrow G$ in $sc\mathbf{Sp}$, there exist k -vector spaces $H^i(F/G)$ for all $i \in \mathbb{Z}$.

By [Pri5] Corollary 1.46, these have the property that for any simplicial k -vector space V with finite-dimensional normalisation,

$$\pi_m(F(k \oplus V) \times_{G(k \oplus V)} \{0\}) \cong H^{-m}(F/G \otimes V),$$

where $V^2 = 0$ and

$$H^i(F/G \otimes V) := \bigoplus_{n \geq 0} H^{i+n}(F/G) \otimes \pi_n(V).$$

If $G = \bullet$ (the one-point set), we write $H^j(F) := H^j(F/\bullet)$.

We now have the following characterisation of obstruction theory:

Theorem 1.28. *If $\alpha : F \rightarrow G$ in $sc\mathbf{Sp}$ is quasi-smooth, then for any small extension $e : I \rightarrow A \xrightarrow{f} B$ in $s\mathcal{C}_\Lambda$, there is a sequence of sets*

$$\pi_0(fA) \xrightarrow{f_*} \pi_0(fB \times_{GB} GA) \xrightarrow{o_e} H^1(F/G \otimes I)$$

exact in the sense that the fibre of o_e over 0 is the image of f_ . Moreover, there is a group action of $H^0(F/G \otimes I)$ on $\pi_0(fA)$ whose orbits are precisely the fibres of f_* .*

For any $y \in F_0A$, with $x = f_*y$, the fibre of $FA \rightarrow FB \times_{GB} GA$ over x is isomorphic to $\ker(\alpha : FI \rightarrow GI)$, and the sequence above extends to a long exact sequence

$$\begin{aligned} \cdots &\xrightarrow{f_*} \pi_n(FB \times_{GB} GA, x) \xrightarrow{o_e} H^{1-n}(F/G \otimes I) \xrightarrow{\partial_e} \pi_{n-1}(FA, y) \xrightarrow{f_*} \cdots \\ \cdots &\xrightarrow{f_*} \pi_1(FB \times_{GB} GA, x) \xrightarrow{o_e} H^0(F/G \otimes I) \xrightarrow{-*y} \pi_0(FA). \end{aligned}$$

Proof. [Pri5] Theorem 1.45. □

Corollary 1.29. *A map $\alpha : F \rightarrow G$ of quasi-smooth $F, G \in scSp$ is a weak equivalence if and only if the maps $H^j(\alpha) : H^j(F) \rightarrow H^j(G)$ are all isomorphisms.*

Corollary 1.30. *If $\alpha : F \rightarrow G$ is quasi-smooth in $scSp$, then α is smooth if and only if $H^i(F/G) = 0$ for all $i > 0$.*

Proposition 1.31. *Let $X, Y, Z : sC_\Lambda \rightarrow \mathbb{S}$ be left-exact functors, with $X \xrightarrow{\alpha} Y$ and $Y \xrightarrow{\beta} Z$ quasi-smooth. There is then a long exact sequence*

$$\cdots \xrightarrow{\partial} H^j(X/Y) \rightarrow H^j(X/Z) \rightarrow H^j(Y/Z) \xrightarrow{\partial} H^{j+1}(X/Y) \rightarrow H^{j+1}(X/Z) \rightarrow \cdots$$

Proof. [Pri5] Proposition 1.61. □

1.6. Model structures.

Theorem 1.32. *There is a simplicial model structure on $scSp$, for which the fibrations are quasi-smooth morphisms, and weak equivalences between quasi-smooth objects are those given in Definition 1.22.*

Proof. This is [Pri5] Theorem 2.14. □

Thus the homotopy category $\text{Ho}(scSp)$ is equivalent to the category of quasi-smooth objects in $scSp$, localised at the weak equivalences of Definition 1.22.

Definition 1.33. Given any morphism $f : X \rightarrow Z$, we define $H^n(X/Z) := H^n(\hat{X}/Z)$, for $X \xrightarrow{i} \hat{X} \xrightarrow{p} Z$ a factorisation of f with i a geometric trivial cofibration, and p a geometric fibration.

1.6.1. Homotopy representability.

Definition 1.34. Define the category \mathcal{S} to consist of functors $F : sC_\Lambda \rightarrow \mathbb{S}$ satisfying the following conditions:

- (A0) $F(k)$ is contractible.
- (A1) For all small extensions $A \twoheadrightarrow B$ in sC_Λ , and maps $C \rightarrow B$ in sC_Λ , the map $F(A \times_B C) \rightarrow F(A) \times_{F(B)}^h F(C)$ is a weak equivalence, where \times^h denotes homotopy fibre product.
- (A2) For all acyclic small extensions $A \twoheadrightarrow B$ in sC_Λ , the map $F(A) \rightarrow F(B)$ is a weak equivalence.

Say that a natural transformation $\eta : F \rightarrow G$ between such functors is a weak equivalence if the maps $F(A) \rightarrow G(A)$ are weak equivalences for all $A \in sC_\Lambda$, and let $\text{Ho}(\mathcal{S})$ be the category obtained by formally inverting all weak equivalences in \mathcal{S} .

Remark 1.35. We may apply the long exact sequence of homotopy to describe the homotopy groups of homotopy fibre products. If $f : X \rightarrow Z$, $g : Y \rightarrow Z$ in \mathbb{S} and $P = X \times_{\frac{h}{Z}} Y$, the map $\theta : \pi_0(P) \rightarrow \pi_0(X) \times_{\pi_0(Z)} \pi_0(Y)$ is surjective. Moreover, $\pi_1(Z, *)$ acts transitively on the fibres of θ over $* \in \pi_0 Z$.

Take $v \in \pi_0(P)$ over $*$. Then there is a connecting homomorphism $\partial : \pi_n(Z, *) \rightarrow \pi_{n-1}(P, v)$ for all $n \geq 1$, giving a long exact sequence

$$\cdots \xrightarrow{\partial} \pi_n(P, v) \rightarrow \pi_n(X, v) \times \pi_n(Y, v) \xrightarrow{f \cdot g^{-1}} \pi_n(Z, *) \xrightarrow{\partial} \pi_{n-1}(P, v) \cdots$$

Theorem 1.36. *There is a canonical equivalence between the geometric homotopy category $\mathrm{Ho}(sc\mathrm{Sp})$ and the category $\mathrm{Ho}(\mathcal{S})$.*

Proof. This is [Pri5] Theorem 2.30. □

1.6.2. *Equivalent formulations.* If k is a field of characteristic 0, then we may work with dg algebras rather than simplicial algebras.

Definition 1.37. Define $dg\mathcal{C}_\Lambda$ to be the category of Artinian local differential \mathbb{N}_0 -graded graded-commutative Λ -algebras with residue field k .

Definition 1.38. Define a map $A \rightarrow B$ in $dg\mathcal{C}_\Lambda$ to be a small extension if it is surjective and the kernel I satisfies $I \cdot \mathfrak{m}(A) = 0$.

Definition 1.39. Define $sDG\mathrm{Sp}$ to be the category of left exact functors from $dg\mathcal{C}_\Lambda$ to \mathbb{S} .

Definition 1.40. Say a map $X \rightarrow Y$ in $sDG\mathrm{Sp}$ is quasi-smooth if for all small extensions $f : A \rightarrow B$ in $dg\mathcal{C}_\Lambda$, the morphism

$$X(A) \rightarrow Y(A) \times_{Y(B)} X(B)$$

is a fibration in \mathbb{S} , which is moreover a trivial fibration if f is acyclic.

Definition 1.41. We will say that a morphism $\alpha : F \rightarrow G$ of quasi-smooth objects of $sDG\mathrm{Sp}$ is a weak equivalence if, for all $A \in s\mathcal{C}_\Lambda$, the maps $\pi_i F(A) \rightarrow \pi_i G(A)$ are isomorphisms for all i .

Proposition 1.42. *There is a model structure on $sDG\mathrm{Sp}$, for which the fibrations are quasi-smooth morphisms, and weak equivalences between quasi-smooth objects are those given in Definition 1.41.*

Proof. This is [Pri5] Proposition 4.12. □

Most of the constructions from $s\mathcal{C}_\Lambda$ carry over to $dg\mathcal{C}_\Lambda$. However, there is no straightforward analogue of Definition 1.15.

Definition 1.43. Define the normalisation functor $N : s\mathcal{C}_\Lambda \rightarrow dg\mathcal{C}_\Lambda$ by mapping A to its associated normalised complex NA , equipped with the Eilenberg-Zilber shuffle product (as in [Qui]).

Definition 1.44. Define $\mathrm{Spf} N^* : sDG\mathrm{Sp} \rightarrow sc\mathrm{Sp}$ by mapping $X : dg\mathcal{C}_\Lambda \rightarrow \mathbb{S}$ to the composition $X \circ N : s\mathcal{C}_\Lambda \rightarrow \mathbb{S}$. Note that this is well-defined, since N is left exact.

Theorem 1.45. $\mathrm{Spf} N^* : sDG\mathrm{Sp} \rightarrow sc\mathrm{Sp}$ is a right Quillen equivalence.

Proof. This is [Pri5] Theorem 4.18. □

In particular, this means that $\mathrm{Spf} N^*$ maps quasi-smooth morphisms to quasi-smooth morphisms, and induces an equivalence $\mathbf{R}\mathrm{Spf} N^* : \mathrm{Ho}(sDG\mathrm{Sp}) \rightarrow \mathrm{Ho}(sc\mathrm{Sp})$.

Now assume that $\Lambda = k$.

Theorem 1.46. $\mathrm{Ho}(sDG\mathrm{Sp})$ is equivalent to the category of L_∞ -algebras localised at tangent quasi-isomorphisms (as considered in [Kon]). This is also equivalent to the category of DGLAs (see §A.1) localised at quasi-isomorphisms.

Proof. Combine [Pri5] Proposition 4.42 and Corollary 4.57. □

2. MONADS AND COMONADS

2.1. Algebras and coalgebras.

Definition 2.1. A monad (or triple) on a category \mathcal{B} is a monoid in the category of endofunctors of \mathcal{B} (with the monoidal structure given by composition of functors). A comonoid (or cotriple) is a comonoid in the category of endofunctors of \mathcal{B} .

The following is standard:

Lemma 2.2. *Take an adjunction*

$$\mathcal{A} \begin{array}{c} \xrightarrow{G} \\ \top \\ \xleftarrow{F} \end{array} \mathcal{E}$$

with unit $\eta : \text{id} \rightarrow GF$ and co-unit $\varepsilon : FG \rightarrow \text{id}$. Then $\top := GF$ is a monad with unit η and multiplication $\mu := G\varepsilon F$, while $\perp := FG$ is a comonad, with co-unit ε and comultiplication $\Delta := F\eta G$.

Definition 2.3. Given a monad (\top, μ, η) on a category \mathcal{E} , define the category \mathcal{E}^\top of \top -algebras to have objects

$$\top E \xrightarrow{\theta} E,$$

such that $\theta \circ \eta_E = \text{id}$ and $\theta \circ \top\theta = \theta \circ \mu_E$.

A morphism

$$g : (\top E_1 \xrightarrow{\theta} E_1) \rightarrow (\top E_2 \xrightarrow{\phi} E_2)$$

of \top -algebras is a morphism $g : E_1 \rightarrow E_2$ in \mathcal{E} such that $\phi \circ \top g = g \circ \theta$.

We define the comparison functor $K : \mathcal{A} \rightarrow \mathcal{E}^\top$ by

$$B \mapsto (UFUB \xrightarrow{U\varepsilon_B} UB)$$

on objects, and $K(g) = U(g)$ on morphisms.

Definition 2.4. The adjunction

$$\mathcal{A} \begin{array}{c} \xrightarrow{U} \\ \top \\ \xleftarrow{F} \end{array} \mathcal{E},$$

is said to be monadic (or tripleable) if $K : \mathcal{D} \rightarrow \mathcal{E}^\top$ is an equivalence.

Examples 2.5. Intuitively, monadic adjunctions correspond to algebraic theories, such as the adjunction

$$\text{Ring} \begin{array}{c} \xrightarrow{U} \\ \top \\ \xleftarrow{\mathbb{Z}[-]} \end{array} \text{Set},$$

between rings and sets, U being the forgetful functor. Other examples are k -algebras over k -vector spaces, or groups over sets.

Definition 2.6. Dually, given a comonad $(\perp, \Delta, \varepsilon)$ on a category \mathcal{A} , we define the category \mathcal{A}_\perp of \perp -coalgebras by

$$(\mathcal{A}_\perp)^{\text{opp}} := (\mathcal{A}^{\text{opp}})^{\perp^{\text{opp}}},$$

noting that \perp^{opp} is a monad on the opposite category \mathcal{A}^{opp} . The adjunction of Lemma 2.2 is said to be comonadic (or cotripleable) if the adjunction on opposite categories is monadic.

Example 2.7. If X is a topological space (or any site with enough points) and X' is the set of points of X , let $u : X' \rightarrow X$ be the associated morphism. Then the adjunction $u^{-1} \dashv u_*$ on sheaves is comonadic, so the category of sheaves on X is equivalent to $u^{-1}u_*$ -coalgebras in the category of sheaves (or equivalently presheaves) on X' .

A more prosaic example is that for any ring A , the category of A -coalgebras is comonadic over the category of A -modules.

2.2. Bialgebras. As in [VO] §IV, take a category \mathcal{B} equipped with both a monad (\top, μ, η) and a comonad (\perp, Δ, γ) , together with a distributivity transformation $\lambda : \top\perp \rightrightarrows \perp\top$ for which the following diagrams commute:

$$\begin{array}{ccc}
 \begin{array}{ccc}
 \top\perp & \xrightarrow{\lambda} & \perp\top \\
 \top\Delta \Downarrow & & \Delta\top \Downarrow \\
 \top\perp^2 & \xrightarrow{\lambda\perp} \perp\top\perp \xrightarrow{\perp\lambda} & \perp^2\top
 \end{array} & &
 \begin{array}{ccc}
 \top\perp & \xrightarrow{\lambda} & \perp\top \\
 \Uparrow \mu\perp & & \Uparrow \perp\mu \\
 \top^2\perp & \xrightarrow{\top\lambda} \top\perp\top \xrightarrow{\lambda\top} & \perp\top^2
 \end{array} \\
 \\
 \begin{array}{ccc}
 \top\perp & \xrightarrow{\lambda} & \perp\top \\
 \searrow \top\gamma & & \swarrow \gamma\top \\
 & \top &
 \end{array} & &
 \begin{array}{ccc}
 \top\perp & \xrightarrow{\lambda} & \perp\top \\
 \swarrow \eta\perp & & \searrow \perp\eta \\
 & \perp &
 \end{array}
 \end{array}$$

Definition 2.8. Given a distributive monad-comonad pair (\top, \perp) on a category \mathcal{B} , define the category $\mathcal{B}_{\perp}^{\top}$ of bialgebras as follows. The objects of $\mathcal{B}_{\perp}^{\top}$ are triples (α, B, β) with $(\top B \xrightarrow{\alpha} B)$ an object of \mathcal{B}^{\top} and $B \xrightarrow{\beta} \perp B$ an object of \mathcal{B}_{\perp} , such that the composition $(\beta \circ \alpha) : \top B \rightarrow \perp B$ agrees with the composition

$$\top B \xrightarrow{\top\beta} \top\perp B \xrightarrow{\lambda} \perp\top B \xrightarrow{\perp\alpha} \perp B.$$

A morphism $f : (\alpha, B, \beta) \rightarrow (\alpha', B', \beta')$ is a morphism $f : B \rightarrow B'$ in \mathcal{B} such that $\alpha' \circ \top f = f \circ \alpha$ and $\beta' \circ f = \perp f \circ \beta$.

To understand how the data $(\top, \perp, \eta, \mu, \gamma, \Delta, \lambda)$ above occur naturally, note that by [VO] §IV or [Pri2] §2, these data are equivalent to a diagram

$$\begin{array}{ccc}
 & \xrightarrow{U} & \\
 \mathcal{D} & \xleftarrow{\top} & \mathcal{E} \\
 & \xrightarrow{F} & \\
 \uparrow G & & \uparrow G \\
 \mathcal{A} & \xrightarrow{\top} & \mathcal{B} \\
 & \xleftarrow{F} & \\
 \downarrow V & & \downarrow V
 \end{array}$$

with $F \dashv U$ monadic, $G \vdash V$ comonadic and U, V commuting with everything (although G and F need not commute). The associated monad is $\top = UF$, and the comonad $\perp = VG$. Distributivity ensures that $\mathcal{D} \simeq \mathcal{E}^{\top} \simeq (\mathcal{B}_{\perp})^{\top}$ and $\mathcal{D} \simeq \mathcal{A}_{\perp} \simeq (\mathcal{B}^{\top})_{\perp}$. In other words, $\mathcal{D} \simeq \mathcal{B}_{\perp}^{\top}$.

Example 2.9. If X is a topological space (or any site with enough points) and X' is the set of points of X , let \mathcal{D} be the category of sheaves of rings on X . If \mathcal{B} is the category of sheaves (or equivalently presheaves) of sets on X' , then the description above characterises \mathcal{D} as a category of bialgebras over \mathcal{B} , with the comonad being $u^{-1}u_*$ for $u : X' \rightarrow X$, and the monad being the free polynomial functor.

3. CONSTRUCTING SDCs

Recall the definition of an SDC:

Definition 3.1. A simplicial deformation complex E^{\bullet} consists of smooth left-exact functors $E^n : \mathcal{C}_{\Lambda} \rightarrow \text{Set}$ for each $n \geq 0$, together with maps

$$\begin{aligned}
 \partial^i : E^n &\rightarrow E^{n+1} & 1 \leq i \leq n \\
 \sigma^i : E^n &\rightarrow E^{n-1} & 0 \leq i < n,
 \end{aligned}$$

an associative product $*$: $E^m \times E^n \rightarrow E^{m+n}$, with identity $1 : \bullet \rightarrow E^0$, where \bullet is the constant functor $\bullet(A) = \bullet$ (the one-point set) on \mathcal{C}_{Λ} , such that:

- (1) $\partial^j \partial^i = \partial^i \partial^{j-1} \quad i < j.$
- (2) $\sigma^j \sigma^i = \sigma^i \sigma^{j+1} \quad i \leq j.$
- (3) $\sigma^j \partial^i = \begin{cases} \partial^i \sigma^{j-1} & i < j \\ \text{id} & i = j, i = j + 1. \\ \partial^{i-1} \sigma^j & i > j + 1 \end{cases}$
- (4) $\partial^i(e) * f = \partial^i(e * f).$
- (5) $e * \partial^i(f) = \partial^{i+m}(e * f), \text{ for } e \in E^m.$
- (6) $\sigma^i(e) * f = \sigma^i(e * f).$
- (7) $e * \sigma^i(f) = \sigma^{i+m}(e * f), \text{ for } e \in E^m.$

From the viewpoint of homotopical algebra, there is a more natural way of characterising the smoothness criterion for E^\bullet . Analogously to [GJ] Lemma VII.4.9, we define matching objects by $M^{-1}E := \bullet$, $M^0E := E^0$, and for $n > 0$

$$M^n E = \{(e_0, e_1, \dots, e_n) \in (E^n)^{n+1} \mid \sigma^i e_j = \sigma^{j-1} e_i \forall i < j\}.$$

Proposition 3.2. *The canonical maps $\underline{\sigma} : E^{n+1} \rightarrow M^n E$, given by $e \mapsto (\sigma^0 e, \sigma^1 e, \dots, \sigma^n e)$, are all smooth, for $n \geq 0$.*

Proof. Since E^n is smooth, by the Standard Smoothness Criterion (e.g. [Man1] Proposition 2.17) it suffices to show that this is surjective on tangent spaces. The tangent space of $M^n E$ consists of $(n+1)$ -tuples $\gamma_i \in C^n(E)$ satisfying $\sigma^i \gamma_j = \sigma^{j-1} \gamma_i$, for $i < j$. For any cosimplicial complex C^\bullet , there is a decomposition of the associated cochain complex as $C^n = N_c^n(C) \oplus D^n(C)$, where $N_c^n(C) = \bigcap_{i=0}^{n-1} \ker \sigma^i$, and $D^n(C) = \sum_{i=1}^n \partial^i C^{n-1}$. Moreover $\underline{\sigma} : D^n \rightarrow M^{n-1}C$ is an isomorphism, giving the required surjectivity. \square

Definition 3.3. Given an SDC E , recall from [Pri2] that the Maurer-Cartan functor $\text{MC}_E : \mathcal{C}_\Lambda \rightarrow \text{Set}$ is defined by

$$\text{MC}_E(A) = \{\omega \in E^1(A) : \omega * \omega = \partial^1(\omega)\}.$$

The group $E^0(A)$ acts on this by conjugation, and we define $\mathfrak{Def}_E(A)$ to be the groupoid with objects $\text{MC}_E(A)$ and morphisms given by $E^0(A)$ via this action. We say that an SDC *governs* a deformation problem if \mathfrak{Def}_E is equivalent to the associated deformation functor.

Definition 3.4. Recall that $C^\bullet(E)$ denotes the tangent space of E^\bullet , i.e. $C^n(E) = E^n(k[\epsilon])$ for $\epsilon^2 = 0$. This has the natural structure of a cosimplicial complex, by [Pri2], and we set $H^i(E) := H^i(C^\bullet(E))$.

3.1. SDCs from bialgebraic structures.

Definition 3.5. Recall from [Pri4] that Δ_{**} is defined to be the subcategory of the ordinal number category Δ containing only those non-decreasing morphisms $f : \mathbf{m} \rightarrow \mathbf{n}$ with $f(0) = 0, f(m) = n$. We define a monoidal structure on this category by setting $\mathbf{m} \otimes \mathbf{n} = \mathbf{m} + \mathbf{n}$, with

$$(f \otimes g)(i) = \begin{cases} f(i) & i \leq m \\ g(i - m) + n & i \geq m, \end{cases}$$

for $f : \mathbf{m} \rightarrow \mathbf{n}$.

Definition 3.6. As in [Pri4], define monoidal structures on $\text{Set}^{\Delta_{**}}$ and $\mathbb{S}^{\Delta_{**}}$ by setting

$$(X \otimes Y)^n := \coprod_{a+b=n} X^a \otimes Y^b,$$

where $\alpha : 1 \rightarrow \top_v$ and $\varepsilon : \perp_h \rightarrow 1$ are the unit and counit of the respective adjunctions.

Write $E_{\mathcal{D}/\mathcal{B}}^*(D) := E_{\mathcal{D}/\mathcal{B}}^*(\text{id}_D)$. Note that uniform triviality of \mathcal{B} ensures that these constructions are independent of the choices of lift, since any other choice is isomorphic.

Lemma 3.10. $E_{\mathcal{D}/\mathcal{B}}(f)(A)$ has the natural structure of a cosimplicial complex.

For every pair of composable morphisms f, g in $\mathcal{D}(k)$ between such objects, there is a product

$$E_{\mathcal{D}/\mathcal{B}}(f)(A) \otimes E_{\mathcal{D}/\mathcal{B}}(g)(A) \rightarrow E_{\mathcal{D}/\mathcal{B}}(f \circ g)(A)$$

in $\text{Set}^{\Delta^{**}}$, functorial in A .

Proof. It follows from Proposition 3.7 that $E_{\mathcal{D}/\mathcal{B}}(f)(A) \in \text{Set}^{\Delta^{**}}$, with operations

$$\begin{aligned} \partial^i(x) &= \perp_v^{i-1} V \alpha_{G \perp_v^{n-i} B} \circ x \circ \top_h^{i-1} U \varepsilon_{F \top_h^{n-i} B}, \quad 0 < i \leq n \\ \sigma^i(x) &= \perp_v^i \gamma_{\perp_v^{n-i-1} B} \circ x \circ \top_h^i \eta_{\top_h^{n-i-1} B}, \quad 0 \leq i < n, \end{aligned}$$

for $\eta : 1 \rightarrow \top_h$ and $\gamma : \perp_v \rightarrow 1$ the respective unit and co-unit. The multiplication also follows from Proposition 3.7.

The canonical object of $\text{MC}(E_{\mathcal{D}/\mathcal{B}}(\text{id}_D)(\Lambda))$ corresponding to D gives an element $\omega_D \in E_{\mathcal{D}/\mathcal{B}}(\text{id}_D)(\Lambda)^1$ and we then enhance the structure above to give a cosimplicial structure by setting

$$\partial^0 x := \omega_{D'} * x \quad \partial^{n+1} x = x * \omega_D,$$

for $x \in E_{\mathcal{D}/\mathcal{B}}(f)(A)^n$. □

Definition 3.11. Given an SDC E , and a simplicial set X , define an SDC E^X by

$$(E^X)^n = (E^n)^{X_n}.$$

For $x \in X_{n+1}$, $y \in Y_{n+1}$, $z \in X_{m+n}$, $1 \leq i \leq n$, $0 \leq j < n$, $e \in (E^X)^n$ and $f \in (E^X)^m$, we define the operations by

$$\begin{aligned} \partial^i(e)(x) &:= \partial^i(e(\partial_i x)) \\ \sigma^j(e)(y) &:= \sigma^j(e(\sigma_j y)), \\ (f * e)(z) &:= f((\partial_{m+1})^n z) * e((\partial_0)^m z). \end{aligned}$$

Definition 3.12. Let $\mathbf{C}_{\mathcal{D}/\mathcal{B}}^\bullet(f)$ be the tangent space of $E_{\mathcal{D}/\mathcal{B}}(f)$. This is a vector space over k , and we define

$$\text{Ext}_{\mathcal{D}/\mathcal{B}}^*(f) := \mathbf{H}^*(\mathbf{C}_{\mathcal{D}/\mathcal{B}}^\bullet(f));$$

this construction is closely related to Van Osdol's bicohomology ([VO]).

Lemma 3.13. If X is a finite simplicial set, then

$$\mathbf{H}^n(E^X) \cong \bigoplus_{i+j=n} \mathbf{H}^i(E) \otimes \mathbf{H}^j(X, k).$$

Proof. Since X is finite, $\mathbf{C}^\bullet(E^X) \cong \mathbf{C}^\bullet(E) \otimes k^X$, and the result now follows from the Künneth formula. □

Definition 3.14. Given a small category \mathbb{I} and an \mathbb{I} -diagram $\mathbb{D} : \mathbb{I} \rightarrow \mathcal{D}(k)$, define the SDC $E_{\mathcal{D}/\mathcal{B}}^\bullet(\mathbb{D})$ by

$$E_{\mathcal{D}/\mathcal{B}}^n(\mathbb{D}) = \prod_{\substack{i_0 \xrightarrow{f_1} i_1 \xrightarrow{f_2} \dots \xrightarrow{f_n} i_n \\ \text{in } \mathbb{I}}} E^n(\mathbb{D}(f_n \circ f_{n-1} \circ \dots \circ f_0)) = \prod_{x \in B\mathbb{I}_n} E^n(\mathbb{D}(\partial_1^{n-1} x)),$$

where $B\mathbb{I}$ is the nerve of \mathbb{I} (so $B\mathbb{I}_0 = \text{Ob}(\mathbb{I})$, $B\mathbb{I}_1 = \text{Mor}(\mathbb{I})$), and $\partial_1^{-1} := \sigma_0$.

We define the operations by the formulae of Definition 3.11.

Theorem 3.15. *The SDC $E_{\mathcal{D}/\mathcal{B}}^\bullet(\mathbb{D})$ governs deformations of the diagram $\mathbb{D} : \mathbb{I} \rightarrow \mathcal{D}(k)$.*

Proof. This follows immediately from [Pri4] Lemma 1.37, which characterises objects of \mathfrak{Def}_E as diagrams from \mathbb{I} to a category equivalent to $\mathcal{D}(A)$. \square

Lemma 3.16. *Given a diagram $\mathbb{D} : \mathbb{I} \rightarrow \mathcal{D}(k)$, the cohomology groups $H^*(E_{\mathcal{D}/\mathcal{B}}^\bullet(\mathbb{D}))$ are given by hypercohomology of the bicomplex*

$$\prod_{i \in \text{Ob } \mathbb{I}} C_{\mathcal{D}/\mathcal{B}}^\bullet(\mathbb{D}(i)) \xrightarrow{f^* - f_*} \dots \rightarrow \prod_{\substack{i_0 \xrightarrow{f_1} i_1 \xrightarrow{f_2} \dots \xrightarrow{f_n} i_n \\ \text{in } N_n \mathbb{I}}} C_{\mathcal{D}/\mathcal{B}}^\bullet(\mathbb{D}(f_n \circ f_{n-1} \circ \dots \circ f_0)) \rightarrow \dots,$$

where $N_n \mathbb{I} \subset B_n \mathbb{I}$ consists of non-degenerate simplices, or equivalently strings of non-identity morphisms.

Proof. Since $C^\bullet(E_{\mathcal{D}/\mathcal{B}}^\bullet(\mathbb{D}))$ is the diagonal of the bicosimplicial complex

$$[m, n] \mapsto \prod_{\substack{i_0 \xrightarrow{f_1} i_1 \xrightarrow{f_2} \dots \xrightarrow{f_n} i_n \\ \text{in } \mathbb{I}}} C_{\mathcal{D}/\mathcal{B}}^m(\mathbb{D}(f_n \circ f_{n-1} \circ \dots \circ f_0)),$$

the Eilenberg-Zilber theorem implies that it is homotopy equivalent to the total complex of the associated binormalised complex. The vertical normalisation is just given by replacing $B_n \mathbb{I}$ with $N_n \mathbb{I}$. \square

Example 3.17. If we define \mathcal{D} and \mathcal{B} as in Example 3.8.3, then the category of flat schemes over A is a full subcategory of $\mathcal{D}(A)$, closed under deformations. Therefore Theorem 3.15 constructs an SDC governing deformations of a diagram of schemes.

For a morphism $f : (X, \mathcal{O}_X) \rightarrow (Y, \mathcal{O}_Y)$ in $\mathcal{D}(k)^{\text{opp}}$, the reasoning of [Pri2] §3.2 adapts to show that

$$\text{Ext}_{\mathcal{D}/\mathcal{B}}^*(f) = \mathbb{E}xt_{\mathcal{O}_Y}^*(\mathbf{L}_\bullet^{Y/k}, \mathbf{R}f_* \mathcal{O}_X) = \mathbb{E}xt_{\mathcal{O}_X}^*(f^* \mathbf{L}_\bullet^{Y/k}, \mathcal{O}_X),$$

where $\mathbf{L}_\bullet^{Y/k}$ is the cotangent complex of [Ill].

3.3. Constrained deformations. We now consider a generalisation of §3.2, by taking a small diagram

$$\mathbb{D} : \mathbb{I} \rightarrow \mathcal{D}(k),$$

a subcategory $\mathbb{J} \subset \mathbb{I}$, and $\widetilde{\mathbb{D}}|_{\mathbb{J}} : \mathbb{J} \rightarrow \mathcal{D}(k)$ lifting $\mathbb{D}|_{\mathbb{J}}$. We wish to describe deformations of \mathbb{D} which agree with $\widetilde{\mathbb{D}}|_{\mathbb{J}}$ on \mathbb{J} . Note that when $\mathbb{I} = (0 \rightarrow 1)$ and $\mathbb{J} = \{1\}$, this is the type of problem considered in [FM] and [Ran].

Proposition 3.18. *Given a \mathbb{I} -diagram $\mathbb{D} : \mathbb{I} \rightarrow \mathcal{D}(k)$, with $\widetilde{\mathbb{D}}|_{\mathbb{J}}$ as above, the groupoid of deformations of \mathbb{D} fixing $\widetilde{\mathbb{D}}|_{\mathbb{J}}$ is governed by the SDC*

$$E_{\mathcal{D}/\mathcal{B}}^\bullet(\mathbb{D}) \times_{E_{\mathcal{D}/\mathcal{B}}^\bullet(\mathbb{D}|_{\mathbb{J}})} \bullet,$$

where $\bullet \rightarrow E_{\mathcal{D}/\mathcal{B}}^\bullet(\mathbb{D}|_{\mathbb{J}})$ is defined by the object of $\text{MC}(E_{\mathcal{D}/\mathcal{B}}^\bullet(\mathbb{D}|_{\mathbb{J}}))$ corresponding to $\widetilde{\mathbb{D}}|_{\mathbb{J}}$.

Proof. By Theorem 3.15, it suffices to show that $\mathfrak{Def}(E_{\mathcal{D}/\mathcal{B}}^\bullet(\mathbb{D}) \times_{E_{\mathcal{D}/\mathcal{B}}^\bullet(\mathbb{D}|_{\mathbb{J}})} \bullet)$ is equivalent to the 2-fibre product

$$\mathfrak{Def}(E_{\mathcal{D}/\mathcal{B}}^\bullet(\mathbb{D})) \times_{\mathfrak{Def}(E_{\mathcal{D}/\mathcal{B}}^\bullet(\mathbb{D}|_{\mathbb{J}}))}^h (\{\widetilde{\mathbb{D}}|_{\mathbb{J}}\}, \text{id}).$$

We know that the functor MC preserves inverse limits, so

$$\text{MC}(E_{\mathcal{D}/\mathcal{B}}^\bullet(\mathbb{D}) \times_{E_{\mathcal{D}/\mathcal{B}}^\bullet(\mathbb{D}|_{\mathbb{J}})} \{\widetilde{\mathbb{D}}|_{\mathbb{J}}\}) = \text{MC}(E_{\mathcal{D}/\mathcal{B}}^\bullet(\mathbb{D})) \times_{\text{MC}(E_{\mathcal{D}/\mathcal{B}}^\bullet(\mathbb{D}|_{\mathbb{J}}))} \{\widetilde{\mathbb{D}}|_{\mathbb{J}}\}.$$

Since $E^0(\mathbb{D})(A) \rightarrow E^0(\mathbb{D}|_{\mathbb{J}})(A)$ is also surjective (by smoothness), we see that

$$\mathfrak{Def}(E^\bullet(\mathbb{D}) \times_{E^\bullet(\mathbb{D}|_{\mathbb{J}})} \{\widetilde{\mathbb{D}}|_{\mathbb{J}}\}) \simeq \mathfrak{Def}(E_{\mathcal{D}/\mathcal{B}}^\bullet(\mathbb{D})) \times_{\mathfrak{Def}(E^\bullet(\mathbb{D}|_{\mathbb{J}}))}^h (\{\widetilde{\mathbb{D}}|_{\mathbb{J}}\}, \text{id}).$$

□

Example 3.19. Given a morphism $f : X \rightarrow Y$ of schemes over k , and a flat formal deformation \mathfrak{Y} of Y over Λ , we may consider deformations of X over \mathfrak{Y} , or equivalently deformations of this diagram fixing \mathfrak{Y} . Define the diagram \mathbb{D} to be $f^\sharp : (\mathcal{O}_Y, Y) \rightarrow (\mathcal{O}_X, X)$ in the category $\mathcal{D}(k)$ of example 3.8.3, and let $\widetilde{\mathbb{D}}|_{\mathbb{J}}$ be the object $(\mathcal{O}_{\mathfrak{Y}}, \mathfrak{Y})$ of $\mathcal{D}(\Lambda)$. Proposition 3.18 then gives an SDC

$$E := E_{\mathcal{D}/\mathcal{B}}^\bullet(\mathbb{D}) \times_{E_{\mathcal{D}/\mathcal{B}}^\bullet(\mathbb{D}|_{\mathbb{J}})} \bullet$$

governing this problem.

Lemma 3.16 implies that the tangent complex $C^\bullet(E)$ is the mapping cone of $C_{\mathcal{D}/\mathcal{B}}^\bullet(\mathcal{O}_X, X) \rightarrow C_{\mathcal{D}/\mathcal{B}}^\bullet(f^\sharp)$, so by Example 3.17, the cohomology of this SDC is given by

$$H^*(E) \cong \mathbb{E}xt_{\mathcal{O}_X}^*(\text{cone}(f^* \mathbf{L}_\bullet^{Y/k} \rightarrow \mathbf{L}_\bullet^{X/k}), \mathcal{O}_X) \cong \mathbb{E}xt_{\mathcal{O}_X}^*(\mathbf{L}_\bullet^{X/Y}, \mathcal{O}_X).$$

Example 3.20. We could go further, and let \mathbb{E} be a diagram $Z \xrightarrow{g} X \xrightarrow{f} Y$ over k , with a fixed formal deformation $\widetilde{gf} : \mathfrak{Z} \rightarrow \mathfrak{Y}$ of fg over Λ . Governing this deformation problem, we get another SDC

$$F := E_{\mathcal{D}/\mathcal{B}}^\bullet(Z \xrightarrow{g} X \xrightarrow{f} Y) \times_{E_{\mathcal{D}/\mathcal{B}}^\bullet(Z \xrightarrow{gf} Y)} \{\mathfrak{Z} \xrightarrow{\widetilde{gf}} \mathfrak{Y}\}.$$

Now, $C^\bullet(F) = \ker(C^\bullet(E_{\mathcal{D}/\mathcal{B}}(\mathbb{E})) \rightarrow C^\bullet(E_{\mathcal{D}/\mathcal{B}}(\mathbb{E}|_{\mathbb{J}})))$, and Lemma 3.16 implies that $C^\bullet(E_{\mathcal{D}/\mathcal{B}}(\mathbb{E}))$ is homotopy equivalent to the total complex of

$$C_{\mathcal{D}/\mathcal{B}}^\bullet(Z) \times C_{\mathcal{D}/\mathcal{B}}^\bullet(X) \times C_{\mathcal{D}/\mathcal{B}}^\bullet(Y) \rightarrow C_{\mathcal{D}/\mathcal{B}}^\bullet(g) \times C_{\mathcal{D}/\mathcal{B}}^\bullet(fg) \times C_{\mathcal{D}/\mathcal{B}}^\bullet(f) \rightarrow C_{\mathcal{D}/\mathcal{B}}^\bullet(fg),$$

while $C^\bullet(E_{\mathcal{D}/\mathcal{B}}(\mathbb{E}|_{\mathbb{J}}))$ is homotopy equivalent to the total complex of

$$C_{\mathcal{D}/\mathcal{B}}^\bullet(Z) \times C_{\mathcal{D}/\mathcal{B}}^\bullet(Y) \rightarrow C_{\mathcal{D}/\mathcal{B}}^\bullet(fg),$$

so $C^\bullet(F)$ is homotopy equivalent to the total complex of

$$C_{\mathcal{D}/\mathcal{B}}^\bullet(X) \rightarrow C_{\mathcal{D}/\mathcal{B}}^\bullet(g) \times C_{\mathcal{D}/\mathcal{B}}^\bullet(f) \rightarrow C_{\mathcal{D}/\mathcal{B}}^\bullet(fg).$$

By Example 3.17,

$$H^* \ker(C_{\mathcal{D}/\mathcal{B}}^\bullet(X) \rightarrow C_{\mathcal{D}/\mathcal{B}}^\bullet(f)) \cong \mathbb{E}xt_{\mathcal{O}_X}^*(\mathbf{L}_\bullet^{X/Y}, \mathcal{O}_X)$$

$$H^* \ker(C_{\mathcal{D}/\mathcal{B}}^\bullet(g) \rightarrow C_{\mathcal{D}/\mathcal{B}}^\bullet(fg)) \cong \mathbb{E}xt_{\mathcal{O}_X}^*(\mathbf{L}_\bullet^{X/Y}, \mathbf{R}g_* \mathcal{O}_Z),$$

and these isomorphisms combine to give

$$H^*(F) \cong \mathbb{E}xt_{\mathcal{O}_X}^*(\mathbf{L}_\bullet^{X/Y}, \text{cone}(\mathcal{O}_X \rightarrow \mathbf{R}g_* \mathcal{O}_Z)[-1]).$$

Note that this more accurately captures the higher structure than the SDC of [Pri2] §3.3, whose cohomology had $g_* \mathcal{O}_Z$ in place of $\mathbf{R}g_* \mathcal{O}_Z$ above.

4. EXTENDED DEFORMATION FUNCTORS FROM SDCs

Given an SDC E , the aim of this section is to extend the classical deformation groupoid $\mathfrak{Def}_E : \mathcal{C}_\Lambda \rightarrow \text{Grpd}$ of [Pri2] from \mathcal{C}_Λ to the whole of $s\mathcal{C}_\Lambda$. Groupoids turn out to be too restrictive for our purposes, so we will define a simplicial set-valued functor $\text{Def}_E : s\mathcal{C}_\Lambda \rightarrow \mathbb{S}$ extending the classifying space $B\mathfrak{Def}_E$ of the deformation groupoid.

For a monad \mathbb{T} , the obvious extension of the functor describing deformations of a \mathbb{T} -algebra is the functor of deformations of a strong homotopy \mathbb{T} -algebra. Strong homotopy

algebras were defined by Lada in [CLM] to characterise the structures arising on deformation retracts of \top -algebras in topological spaces, but the description works over any simplicial category. This motivates the following definition:

Definition 4.1. Given an SDC E , define the Maurer-Cartan functor $\text{MC}_E : s\mathcal{C}_\Lambda \rightarrow \text{Set}$ by

$$\text{MC}_E(A) \subset \prod_{n \geq 0} E^{n+1}(A^{I^n}),$$

consisting of those $\underline{\omega}$ satisfying:

$$\begin{aligned} \omega_m(s_1, \dots, s_m) * \omega_n(t_1, \dots, t_n) &= \omega_{m+n+1}(s_1, \dots, s_m, 0, t_1, \dots, t_n); \\ \partial^i \omega_n(t_1, \dots, t_n) &= \omega_{n+1}(t_1, \dots, t_{i-1}, 1, t_i, \dots, t_n); \\ \sigma^i \omega_n(t_1, \dots, t_n) &= \omega_{n-1}(t_1, \dots, t_{i-1}, \min\{t_i, t_{i+1}\}, t_{i+2}, \dots, t_n); \\ \sigma^0 \omega_n(t_1, \dots, t_n) &= \omega_{n-1}(t_2, \dots, t_n); \\ \sigma^{n-1} \omega_n(t_1, \dots, t_n) &= \omega_{n-1}(t_1, \dots, t_{n-1}), \\ \sigma^0 \omega_0 &= 1, \end{aligned}$$

where $I := \Delta^1$.

- Remarks 4.2.* (1) One way to think of this construction is that, if we start with an element $\omega \in E^1$ such that $\sigma^0 \omega = 1$, then there are 2^n elements generated by ω in each E^{n+1} . To see this correspondence, take a vector in $\{0, 1\}^n$, then substitute “ $\omega*$ ” for each 0, and “ ∂^1 ” for each 1, adding a final ω . These elements will be at the vertices of an n -cube, and ω_n is then a homotopy between them.
- (2) Lada’s definition of a strong homotopy algebra differs slightly in that it omits all of the degeneracy conditions except $\sigma^0 \omega_0 = 0$. Our choices are made so that we work with normalised, rather than unnormalised, cochain complexes associated to a cosimplicial complex. Since these are homotopy equivalent, both constructions will yield weakly equivalent deformation functors, even if we remove all degeneracy conditions.
- (3) In [Pri4] Proposition 3.9 it is shown that $\underline{\text{MC}}$ has a precise homotopy-theoretical interpretation as the derived functor associated to the functor sending an SDC E and $A \in \mathcal{C}_\Lambda$ to the set $\text{MC}_E(A)$ from Definition 3.3. In the scenario of §3, it follows from the results of [Pri4] that for $A \in s\mathcal{C}_\Lambda$, $\text{MC}_E(A)$ is the set of objects of the Segal space of strong homotopy bialgebras over the object being deformed.

Proposition 4.3. $\text{MC}_E : s\mathcal{C}_\Lambda \rightarrow \text{Set}$ is quasi-smooth. Moreover, if $f : E \rightarrow F$ is a morphism of SDCs such that the maps $f^n : E^n \rightarrow F^n$ are smooth for all n , then $\text{MC}_E \rightarrow \text{MC}_F$ is quasi-smooth.

Proof. This follows immediately from [Pri4] Lemma 3.8. □

Definition 4.4. By [Pri1] Lemma 1.5, E^0 is a group, which we denote by G_E . Observe that G_E acts on MC_E by $(g, \omega) \mapsto g * \omega * g^{-1}$. We now define the deformation functor $\text{Def}_E : s\mathcal{C}_\Lambda \rightarrow \mathbb{S}$ by $\text{Def}_E := [\underline{\text{MC}}_E / \underline{G}_E]$, for \underline{X} as in Definition 1.15, and $[-, -]$ the homotopy quotient of §1.4.

Proposition 4.5. If $A \in \mathcal{C}_\Lambda$, then $\text{Def}_E(A)$ is just the classifying space $B\mathcal{D}\text{ef}_E(A) \in \mathbb{S}$ of the deformation groupoid $\mathcal{D}\text{ef}_E(A)$ from Definition 3.3.

Proof. Take $\underline{\omega} \in \text{MC}_E(A)$. Since $A \in \mathcal{C}_\Lambda$, $A^K = A$ for all connected simplicial sets K , so $E^{n+1}(A^{I^n}) = E^{n+1}(A)$, and $\omega_n = \omega_0^{*(n+1)}$, with the Maurer-Cartan relations reducing to

$$\partial^1 \omega_0 = \omega_0 * \omega_0 \quad \sigma^0 \omega_0 = 1.$$

These are precisely the conditions defining the Maurer-Cartan space $\mathrm{MC}_E(A)$ of Definition 3.3, and $\mathfrak{Def}_E(A)$ is the groupoid given by the action of $E^0(A)$ on $\mathrm{MC}_E(A)$, as required. \square

Proposition 4.6. *The functor Def_E is quasi-smooth. More generally, if $f : E \rightarrow F$ is a morphism of SDCs, such that $f^n : E^n \rightarrow F^n$ is smooth for all n , then $\mathrm{Def}_E \rightarrow \mathrm{Def}_F$ is quasi-smooth.*

Proof. This follows immediately from Corollary 1.27. \square

Proposition 4.7. *The cohomology groups $H^j(\mathrm{Def}_E)$ are isomorphic to the groups $H^{j+1}(E)$ from Definition 3.4.*

Proof. This follows immediately from [Pri4] Corollary 4.9. \square

4.1. Deformations of morphisms. The problem which we now wish to consider is that of deforming a morphism with fixed endpoints. Assume that we have a category-valued functor $\mathcal{D} : \mathcal{C}_\Lambda \rightarrow \mathrm{Cat}$. Fix objects D, D' in $\mathcal{D}(\Lambda)$, and a morphism f in $\mathcal{D}(k)$ from D to D' . The deformation problem which we wish to consider is to describe, for each $A \in \mathcal{C}_\Lambda$, the set of morphisms $f_A : D \rightarrow D'$ in $\mathcal{D}(A)$ deforming f . This amounts to taking the special case $\mathbb{I} = (0 \rightarrow 1)$ and $\mathbb{J} = \{0, 1\}$ in §3.3.

Now assume that we have a diagram of functors from \mathcal{C}_Λ to Cat as in §3, and consider the cosimplicial complex F^\bullet in Sp given by $F^\bullet := E_{\mathcal{D}/\mathcal{B}}^\bullet(f)$ from Lemma 3.10.

On $s\mathcal{C}_\Lambda$, we now define a deformation functor

$$\mathrm{Def}_F(A) \subset \prod_{n \geq 0} \underline{F}^n(A)^{\Delta^n},$$

associated to F , to consist of those $\underline{\theta}$ satisfying:

$$\begin{aligned} \partial^i \theta_n &= \epsilon_{n+1-i}^* \theta_{n+1} \\ \sigma^i \theta_n &= \eta_{n-1-i}^* \theta_{n-1}, \end{aligned}$$

for face maps $\epsilon_i : \Delta^n \rightarrow \Delta^{n+1}$ and degeneracy maps $\eta_i : \Delta^n \rightarrow \Delta^{n-1}$ defined as in [Wei] Ch.8. N

Proposition 4.8. *Def_F is quasi-smooth, and $H^i(\mathrm{Def}_F) \cong H^i(F)$.*

Proof. The first statement follows from [GJ] §VII.5, which shows that the total space functor Tot from cosimplicial simplicial sets to simplicial sets is right Quillen. The description of cohomology is straightforward. \square

Proposition 4.9. *If \mathbb{I} is the category $(0 \xrightarrow{m} 1)$, let $\mathbb{D} : \mathbb{I} \rightarrow \mathcal{D}(k)$ be the functor given by $\mathbb{D}(0) = D, \mathbb{D}(1) = D'$ and $\mathbb{D}(m) = f$, then there is a canonical weak equivalence*

$$\mathrm{Def}_F \simeq \mathrm{Def}(E_{\mathcal{D}/\mathcal{B}}(\mathbb{D}) \times_{E_{\mathcal{D}/\mathcal{B}}(D) \times E_{\mathcal{D}/\mathcal{B}}(D')} \bullet),$$

where $\bullet \rightarrow E_{\mathcal{D}/\mathcal{B}}(D) \times E_{\mathcal{D}/\mathcal{B}}(D')$ is defined by the object $(D, D') \in \mathrm{MC}(E^\bullet(D) \times E^\bullet(D'))(\Lambda)$.

Thus Def_F governs deformations of f which fix D, D' .

Proof. Let $C := E_{\mathcal{D}/\mathcal{B}}(\mathbb{D}) \times_{E_{\mathcal{D}/\mathcal{B}}(D) \times E_{\mathcal{D}/\mathcal{B}}(D')} \bullet$. By [Pri4] Lemma 5.10, there are canonical equivalences $\underline{\mathrm{MC}}(C)(A) \simeq \mathrm{Def}(F)(A)$, so we need only observe that $C^0 = 1$, so $\mathrm{Def}(C) = \underline{\mathrm{MC}}(C)$. The final statement then follows from Proposition 3.18. \square

4.1.1. *Deforming identity morphisms.* If we now consider deformations of the morphism $\text{id}_D : D \rightarrow D$, write F for the cosimplicial complex $E_{\mathcal{D}/\mathcal{B}}^\bullet(\text{id}_D)$ governing deformations of id_D , and E for the SDC describing deformations of D , as defined in [Pri2] §2 (or just by taking the special case $\mathbb{I} = \bullet$ of Definition 3.14). Note that $E^n = F^n$, with the operations agreeing whenever they are defined on both. If we write $e := \partial^0 1 \in F^1$, note that we also have $\partial^0 f = e * f$ and $\partial^{n+1} f = f * e$ for $f \in F^n$.

This gives us an isomorphism $C^\bullet(E) \cong C^\bullet(F)$, and hence $H^n(\text{Def}_E) = H^{n+1}(E) \cong H^{n+1}(\text{Def}_F)$.

Proposition 4.10. *Under the scenario above, the simplicial set $\text{Def}_F(A)$ is weakly equivalent to the loop space $\Omega \text{Def}_E(A)$ of $\text{Def}_E(A)$ over the point $\omega_D \in \text{Def}_D(\Lambda)$. This equivalence is functorial in $A \in s\mathcal{C}_\Lambda$*

Proof. Define the SDC PE to be the fibre of $\text{ev}_0 : E^I \rightarrow E$ over the constants $\{e^n\}$. It follows from Lemma 3.13 that the cohomology groups of PE are all 0. Now define the SDC ΩE to be the fibre of $\text{ev}_1 : PE \rightarrow E$ over $\{e^n\}$.

By Proposition 4.9, Def_F is weakly equivalent to $\text{Def}(\Omega E)$. By Proposition 4.6, $\text{Def}_{PE} \rightarrow \text{Def}_E$ is quasi-smooth, and the fibre is $\text{Def}_{\Omega E}$. Since Def_{PE} is contractible, this means that $\text{Def}_{\Omega E}$ is homotopic to the loop space of Def_E . \square

Remark 4.11. Note that we can describe ΩE entirely in terms of the structure on F , since

$$(\Omega E)^n = (F^n)^n,$$

with

$$\begin{aligned} \partial^i(f_1, \dots, f_n) &= (\partial^i f_1, \partial^i f_2, \dots, \partial^i f_i, \partial^i f_i, \dots, \partial^i f_n) \\ \sigma^i(f_1, \dots, f_n) &= (\sigma^i f_1, \sigma^i f_2, \dots, \sigma^i f_i, \sigma^i f_{i+2}, \dots, \sigma^i f_n) \\ (g_1, \dots, g_m) * (f_1, \dots, f_n) &= (g_1 * e^n, \dots, g_m * e^n, e^m * f_1, \dots, e^m * f_n). \end{aligned}$$

Now, given any smooth object $F \in c\text{Sp}$, we may regard F as a cosimplicial complex of smooth objects in Sp (as in [Pri5] Definition 1.20), and then

$$\underline{F} = \text{Def}(F) \simeq \text{Def}(\Omega E).$$

This means that we cannot expect derived deformation functors coming from SDCs to have any more structure than arbitrary deformation functors.

Remark 4.12. In the case of Hochschild cohomology, the deformation functor of a morphism $R \xrightarrow{f} S$ of associative algebras can be defined over the category of Artinian associative algebras, rather than just \mathcal{C}_Λ . This means that the Lie bracket $H^i(f) \times H^j(f) \rightarrow H^{i+j+1}(f)$ defined in [Pri5] §5.2 extends to an associative cup product. If $f = \text{id}_R$ is an identity, then we know that the Lie bracket vanishes (since Def_f is a loop space, by Proposition 4.9), which is why the cup product becomes commutative. Of course, we also have the bracket $H^i(\text{id}_R) \times H^j(\text{id}_R) \rightarrow H^{i+j}(\text{id}_R)$ associated to the deformation functor of the object R .

APPENDIX A. COMPARISON WITH [Pri2]

Now assume that $\Lambda = k$, a field of characteristic 0. In [Pri5], an equivalence was given between the homotopy category of \mathbb{Z} -graded DGLAs and $\text{Ho}(sc\text{Sp})$. Under the equivalences of Theorems 1.46 and 1.36, this equivalence sends a DGLA to its associated deformation functor in the sense of [Man2] (by [Pri5] Remark 4.46).

However, in [Pri2], a functor \mathcal{E} was constructed from \mathbb{N}_0 -graded DGLAs to SDCs, and Definition 4.4 then gives us an associated object of $sc\text{Sp}$. The purpose of this appendix is to show that the two constructions are consistent with each other.

A.1. DGLAs.

Definition A.1. A differential graded Lie algebra (DGLA) is a graded vector space $L = \bigoplus_i L^i$ over k , equipped with operators $[\cdot, \cdot] : L \times L \rightarrow L$ bilinear and $d : L \rightarrow L$ linear, satisfying:

- (1) $[L^i, L^j] \subset L^{i+j}$.
- (2) $[a, b] + (-1)^{\bar{a}\bar{b}}[b, a] = 0$.
- (3) $(-1)^{\bar{c}\bar{a}}[a, [b, c]] + (-1)^{\bar{a}\bar{b}}[b, [c, a]] + (-1)^{\bar{b}\bar{c}}[c, [a, b]] = 0$.
- (4) $d(L^i) \subset L^{i+1}$.
- (5) $d \circ d = 0$.
- (6) $d[a, b] = [da, b] + (-1)^{\bar{a}}[a, db]$

Here \bar{a} denotes the degree of a , mod 2, for a homogeneous.

A DGLA is said to be nilpotent if the lower central series $\Gamma_n L$ (given by $\Gamma_1 L = L$, $\Gamma_{n+1} L = [L, \Gamma_n L]$) vanishes for $n \gg 0$.

Definition A.2. Given a nilpotent Lie algebra \mathfrak{g} , define $\hat{\mathcal{U}}(\mathfrak{g})$ to be the pro-unipotent completion of the universal enveloping algebra of \mathfrak{g} , regarded as a pro-object in the category of algebras. As in [Qui] Appendix A, this is a pro-Hopf algebra, and we define $\exp(\mathfrak{g}) \subset \hat{\mathcal{U}}(\mathfrak{g})$ to consist of elements g with $\varepsilon(g) = 1$ and $\Delta(g) = g \otimes g$, for $\varepsilon : \hat{\mathcal{U}}(\mathfrak{g}) \rightarrow k$ the augmentation (sending \mathfrak{g} to 0), and $\Delta : \hat{\mathcal{U}}(\mathfrak{g}) \rightarrow \hat{\mathcal{U}}(\mathfrak{g}) \otimes \hat{\mathcal{U}}(\mathfrak{g})$ the comultiplication.

Since k is assumed to have characteristic 0, exponentiation gives an isomorphism from \mathfrak{g} to $\exp(\mathfrak{g})$, so we may regard $\exp(\mathfrak{g})$ as having the same elements as \mathfrak{g} , but with multiplication given by the Campbell–Baker–Hausdorff formula.

Definition A.3. Given a nilpotent DGLA L^\bullet , define the Maurer-Cartan set by

$$\text{MC}(L) := \{\omega \in L^1 \mid d\omega + \frac{1}{2}[\omega, \omega] = 0 \in \bigoplus_n L^2\}$$

Define the gauge group $\text{Gg}(L)$ by $\text{Gg}(L) := \exp(L^0)$, which acts on $\text{MC}(L)$ by the gauge action

$$g(\omega) = g \cdot \omega \cdot g^{-1} - dg \cdot g^{-1},$$

where \cdot denotes multiplication in the universal enveloping algebra of L . That $g(\omega) \in \text{MC}(L)$ is a standard calculation (see [Kon] or [Man1]).

Definition A.4. A morphism $f : L \rightarrow M$ of DGLAs is said to be a quasi-isomorphism if $H^*(f) : H^*(L) \rightarrow H^*(M)$ is an isomorphism.

Proposition A.5. *There is a model structure on the category of \mathbb{Z} -graded DGLAs, in which weak equivalences are quasi-isomorphisms, and fibrations are surjections. This category is Quillen-equivalent to the model category $s\text{DGSp}$ of Definition 1.39.*

Proof. [Pri5] Lemma 3.24 and Corollary 4.57. □

A.2. Cosimplicial groups.

Definition A.6. Given an \mathbb{N}_0 -graded DGLA L , let DL be its denormalisation. This becomes a cosimplicial Lie algebra via the Eilenberg-Zilber shuffle product. Explicitly:

$$D^n L := \bigoplus_{\substack{m+s=n \\ 1 \leq j_1 < \dots < j_s \leq n}} \partial^{j_s} \dots \partial^{j_1} L^m,$$

where we define the ∂^j and σ^i using the simplicial identities, subject to the conditions that $\sigma^i L = 0$ and $\partial^0 v = dv - \sum_{i=1}^{n+1} (-1)^i \partial^i v$ for all $v \in L^n$.

We now have to define the Lie bracket $\llbracket -, - \rrbracket$ from $D^n L \otimes D^n L$ to $D^n L$. Given a finite set I of strictly positive integers, write $\partial^I = \partial^{i_s} \dots \partial^{i_1}$, for $I = \{i_1, \dots, i_s\}$, with $1 \leq i_1 < \dots < i_s$. The Lie bracket is then defined on the basis by

$$\llbracket \partial^I v, \partial^J w \rrbracket := \begin{cases} \partial^{I \cap J} (-1)^{(J \setminus I, I \setminus J)} [v, w] & |v| = |J \setminus I|, |w| = |I \setminus J|, \\ 0 & \text{otherwise,} \end{cases}$$

where for disjoint sets S, T of integers, $(-1)^{(S, T)}$ is the sign of the shuffle permutation of $S \sqcup T$ which sends the first $|S|$ elements to S (in order), and the remaining $|T|$ elements to T (in order). Note that this description only works for $0 \notin I \cup J$.

Definition A.7. Now recall from [Pri2] §4.2, that the functor $\mathcal{E} : DGLA \rightarrow SDC$ from \mathbb{N}_0 -graded DGLAs to SDCs is defined by

$$\mathcal{E}(L)^n(A) = \exp(D^n(L) \otimes \mathfrak{m}_A),$$

making $\mathcal{E}(L)$ into a cosimplicial complex of group-valued functors. To make it an SDC, we must define a $*$ product. We do this as the Alexander-Whitney cup product

$$g * h = (\partial^{m+n} \dots \partial^{m+2} \partial^{m+1} g) \cdot (\partial^0)^m h,$$

for $g \in \mathcal{E}(L)^m$, $h \in \mathcal{E}(L)^n$.

Definition A.8. Given a cosimplicial simplicial group G , define $\underline{MC}(G) \in \mathbb{S}$ by $\underline{MC}(G) \subset \prod_{n \geq 0} (G^{n+1})^{\Delta^n}$, satisfying the conditions of [Pri3] Lemma 3.3, i.e. the elements $\omega_n \in (G^{n+1})^{\Delta^n}$ satisfy

$$\begin{aligned} \partial_i \omega_n &= \begin{cases} \partial^{i+1} \omega_{n-1} & i > 0 \\ (\partial^1 \omega_{n-1}) \cdot (\partial^0 \omega_{n-1})^{-1} & i = 0, \end{cases} \\ \sigma_i \omega_n &= \sigma^{i+1} \omega_{n+1}, \\ \sigma^0 \omega_n &= 1. \end{aligned}$$

Define $MC : scGp \rightarrow \text{Set}$ by $MC(G) = \underline{MC}(G)_0$.

There is an adjoint action of G^0 on $\underline{MC}(G)$, given by

$$(g * \omega)_n = (\partial_0 (\partial^1)^{n+1} (\sigma_0)^{n+1} g) \cdot \omega_n \cdot (\partial^0 (\partial^1)^n (\sigma_0)^n g^{-1}),$$

as in [Pri3] Definition 3.8.

We then define $\text{Del}(G)$ to be the homotopy quotient $\text{Del}(G) = [\underline{MC}(G)/G^0] \in \mathbb{S}$.

Let \exp denote exponentiation of a nilpotent Lie algebra (giving a unipotent group).

Corollary A.9. *Given an \mathbb{N}_0 -graded DGLA L , the deformation functor $\text{Def}(\mathcal{E}(L)) \in scSp$ is weakly equivalent to the functor*

$$A \mapsto \text{Del}(\exp(DL \otimes \mathfrak{m}(A))).$$

Proof. The SDC $\mathcal{E}(L)$ corresponds to $A \mapsto \mathcal{E}(\exp(DL \otimes \mathfrak{m}(A)))$ in the notation of [Pri4] §3.1, so the result is an immediate consequence of [Pri4] Proposition 6.11. \square

Corollary A.10. *For L as above, $\text{Def}(\mathcal{E}(L))$ is weakly equivalent in the model category $scSp$ to the functor $A \mapsto [\text{MC}(\exp(DL \otimes \mathfrak{m}(A)))/\exp(L^0 \otimes \mathfrak{m}(A_0))]$.*

Proof. [Pri5] Lemma 2.26 implies that $\text{MC}(\exp(DL \otimes \mathfrak{m}(A))) \rightarrow \underline{MC}(\exp(DL \otimes \mathfrak{m}(A)))$ defines a weak equivalence in $scSp$ (although the former is not fibrant), and similarly for $L^0 \otimes \mathfrak{m}(A_0) \rightarrow L^0 \otimes \mathfrak{m}(A)$, so we get a weak equivalence on passing to the homotopy quotient. \square

A.3. The final comparison.

Definition A.11. Given an \mathbb{N}_0 -graded DGLA L , define $\text{Del}(L) \in sDG\text{Sp}$ to be the functor $\text{Del}(L) : dg\mathcal{C}_k \rightarrow \mathbb{S}$ given by the homotopy quotient

$$A \mapsto [\text{MC}(\text{Tot}^\Pi(L \otimes N\mathfrak{m}(A)))/\exp(L^0 \otimes \mathfrak{m}(A_0))]$$

with respect to the gauge action of Definition A.3.

Corollary A.12. *Given an \mathbb{N}_0 -graded DGLA L , the deformation functor $\text{Def}(\mathcal{E}(L)) \in sc\text{Sp}$ is weakly equivalent to $\mathbf{RSpf} N^*\text{Del}(L)$, for $\mathbf{RSpf} N^*$ as in Theorem 1.45.*

Proof. By Corollary A.9, it suffices to show that the functors $\text{Del}(L)$ and $A \mapsto \text{Del}(\exp(DL \otimes \mathfrak{m}(A)))$ are weakly equivalent in $sc\text{Sp}$. It follows from [Pri5] Lemma 2.26 that the latter is weakly equivalent to

$$A \mapsto [\text{MC}(\exp(DL \otimes \mathfrak{m}(A)))/\exp(L^0 \otimes \mathfrak{m}(A_0))],$$

which is not fibrant in general. Now, [Pri4] Theorem 6.23 implies that this is isomorphic to

$$A \mapsto [\text{MC}(\text{Tot}^\Pi(L \otimes N\mathfrak{m}(A)))/\exp(L^0 \otimes \mathfrak{m}(A_0))],$$

which is just $\text{Spf} N^*\text{Del}(L)$. [Pri5] Lemma 1.62 then implies that $\mathbf{RSpf} N^*F \cong \text{Spf} N^*F$ for all levelwise quasi-smooth functors F . \square

Definition A.13. Define $DGdg\mathcal{C}_k$ to be the category of Artinian local $\mathbb{N}_0 \times \mathbb{N}_0$ -graded graded-commutative Λ -algebras A_\bullet with differential of bidegree $(1, -1)$ and residue field k . Let $dgDG\text{Sp}$ be the category of left-exact Set-valued functors on $DGdg\mathcal{C}_k$.

Proposition A.14. *Under the equivalence of Proposition A.5, an \mathbb{N}_0 -graded DGLA L corresponds to the deformation functor $\text{Def}(\mathcal{E}(L)) \in sc\text{Sp}$ of Definition 4.4.*

Proof. The equivalence of [Pri5] Corollary 4.57 is given by a functor $\mathbf{RSpf} D^* : \text{Ho}(sDG\text{Sp}) \rightarrow \text{Ho}(dgDG\text{Sp})$, together with a functor

$$\text{Spf Tot}^* \text{MC} : DG_{\mathbb{Z}}\text{LA} \rightarrow dgDG\text{Sp},$$

on \mathbb{Z} -graded DGLAs, given by

$$\text{Spf Tot}^* \text{MC}(L)(A) = \text{MC}(\text{Tot} L \otimes \mathfrak{m}(A)).$$

By Corollary A.12, it suffices to show that the objects $\mathbf{RSpf} D^*\text{Del}(L)$ and $\text{Spf Tot}^* \text{MC}(L)$ are weakly equivalent in $dgDG\text{Sp}$.

Taking $A \in DGdg\mathcal{C}_k$, it follows from the definitions that $\text{Spf} D^*\text{Del}(L)(A)$ consists of maps $\text{Spf}(DA) \rightarrow \text{MC}(L) \times^{\exp(L^0)} W(\exp(L^0))$ in $sDG\text{Sp}$, where $DA \in (dg\mathcal{C}_k)^\Delta$ is defined by cosimplicial denormalisation, and $\text{Spf}(DA) \in sDG\text{Sp}$ is the functor $dg\mathcal{C}_k \rightarrow \mathbb{S}$ given in level n by $\text{Hom}_{dg\mathcal{C}_k}(D^n A, -)$.

Thus

$$\text{Spf} D^*\text{Del}(L)(A) \subset \text{MC}(\text{Tot} L \otimes A^0) \times \text{MC}(D(\exp(L^0 \otimes A_\bullet^0)))$$

consists of pairs (ω, g) with $g * \partial_{DA}^0 \omega = \partial_{DA}^1 \omega$, corresponding in level n to the map

$$\begin{aligned} (\text{Spf} D^n A) &\rightarrow \text{MC}(L) \times \exp(L^0)^n \\ (\omega, g) &\mapsto (\omega, (\partial^2)^{n-1} g, \partial^0 (\partial^2)^{n-2} g, \dots, (\partial^0)^{n-1} g). \end{aligned}$$

By [Pri4] Theorem 6.23, we know that $\text{MC}(D(\exp(L^0 \otimes A_\bullet^0))) \cong \text{MC}(L^0 \otimes A_\bullet^0)$, giving us $\gamma \in \text{MC}(L^0 \otimes A_\bullet^0)$. Note that $g = \exp(\gamma)$, so

$$g * \partial_{DA}^0 \omega = \partial_{DA}^0 \omega + [\gamma, \omega],$$

with all higher terms vanishing, since $\sigma^0 \gamma = 0$, so $[[\gamma, [\gamma, v]]] = 0$ for all v (and in particular when $v = \partial_{DA}^0 \omega$).

Thus we have

$$\mathrm{Spf} D^* \mathrm{Del}(L)(A) = \{(\omega, \gamma) : \omega \in \mathrm{MC}(\mathrm{Tot} L \otimes A^0), \gamma \in \mathrm{MC}(L^0 \otimes A_0^\bullet), [\gamma, \omega] + d_{c,A}\omega = 0\},$$

where $d_{c,A}$ is the cochain differential on A

Now look at $\gamma + \omega \in (\mathrm{Tot}(L \otimes A))^1$. The equations combine to show that $\alpha := \gamma + \omega$ lies in $\mathrm{MC}(\mathrm{Tot}(L \otimes A))$, since

$$d\alpha + [\alpha, \alpha] = (d_L\omega + d_A^s\omega + [\omega, \omega]) + (d_A\gamma + [\gamma, \gamma]) + ([\gamma, \omega] + d_{A,c}\omega) = 0,$$

where d_A^s is the chain differential on A .

Thus we have defined a map

$$\psi : \mathrm{Spf} D^* \mathrm{Del}(L) \rightarrow \mathrm{Spf} (\mathrm{Tot}^\Pi)^* \mathrm{MC}(L).$$

In fact, we have shown that

$$\mathrm{Spf} D^* \mathrm{Del}(L)(A) \cong \mathrm{MCTot}((L \otimes A^0) \times_{(L^0 \otimes A^0)} (L^0 \otimes A_0)),$$

and [Pri5] Lemma 4.13 then implies that ψ is a weak equivalence (with similar reasoning to [Pri5] Lemma 2.26).

Finally, note that this gives cohomology groups (as defined in Definition 1.33) $\mathrm{H}^n(\mathrm{Spf} D^* \mathrm{Del}(L)(A)) \cong \mathrm{H}^{n+1}(L)$, and that

$$\mathrm{H}^n(\mathbf{R}\mathrm{Spf} D^* \mathrm{Del}(L)) \cong \mathrm{H}^n(\mathrm{Del}(L)) \cong \mathrm{H}^{n+1}(L)$$

since the equivalence of [Pri5] Proposition 4.57 preserves cohomology groups. Therefore the morphism $\mathrm{Spf} D^* \mathrm{Del}(L) \rightarrow \mathbf{R}\mathrm{Spf} D^* \mathrm{Del}(L)$ is also a weak equivalence by Corollary 1.29, and this completes the proof. \square

REFERENCES

- [CLM] Frederick R. Cohen, Thomas J. Lada, and J. Peter May. *The homology of iterated loop spaces*. Springer-Verlag, Berlin, 1976. Lecture Notes in Mathematics, Vol. 533.
- [FM] D. Fiorenza and M. Manetti. L_∞ structures on mapping cones. *Algebra Number Theory*, 1(3):301–330, 2007. arXiv math.QA/0601312.
- [GJ] Paul G. Goerss and John F. Jardine. *Simplicial homotopy theory*, volume 174 of *Progress in Mathematics*. Birkhäuser Verlag, Basel, 1999.
- [Gro] Alexander Grothendieck. Technique de descente et théorèmes d’existence en géométrie algébrique. II. Le théorème d’existence en théorie formelle des modules. In *Séminaire Bourbaki, Vol. 5*, pages Exp. No. 195, 369–390. Soc. Math. France, Paris, 1995.
- [Ill] Luc Illusie. *Complexe cotangent et déformations. I*. Springer-Verlag, Berlin, 1971. Lecture Notes in Mathematics, Vol. 239.
- [Kon] Maxim Kontsevich. Topics in algebra — deformation theory. Lecture Notes, available at <http://www.math.brown.edu/~abrmovic/kontsdef.ps>, 1994.
- [Man1] Marco Manetti. Deformation theory via differential graded Lie algebras. In *Algebraic Geometry Seminars, 1998–1999 (Italian) (Pisa)*, pages 21–48. Scuola Norm. Sup., Pisa, 1999. arXiv math.AG/0507284.
- [Man2] Marco Manetti. Extended deformation functors. *Int. Math. Res. Not.*, (14):719–756, 2002.
- [Pri1] J. P. Pridham. Deforming l -adic representations of the fundamental group of a smooth variety. *J. Algebraic Geom.*, 15(3):415–442, 2006.
- [Pri2] J. P. Pridham. Deformations of schemes and other bialgebraic structures. *Trans. Amer. Math. Soc.*, 360(3):1601–1629, 2008.
- [Pri3] J. P. Pridham. Pro-algebraic homotopy types. *Proc. London Math. Soc.*, 97(2):273–338, 2008. arXiv math.AT/0606107 v8.
- [Pri4] J. P. Pridham. The homotopy theory of strong homotopy algebras and bialgebras. arXiv:0908.0116v1 [math.AG], submitted, 2009.
- [Pri5] J. P. Pridham. Unifying derived deformation theories. arXiv:0705.0344v4 [math.AG], submitted, 2009.
- [Qui] Daniel Quillen. Rational homotopy theory. *Ann. of Math. (2)*, 90:205–295, 1969.
- [Ran] Ziv Ran. Lie atoms and their deformations. *Geom. Funct. Anal.*, 18(1):184–221, 2008. arXiv:math/0412204v7.
- [VO] Donovan H. Van Osdol. Bicohomology theory. *Trans. Amer. Math. Soc.*, 183:449–476, 1973.

- [Wei] Charles A. Weibel. *An introduction to homological algebra*. Cambridge University Press, Cambridge, 1994.