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## Organic-Matter Loading Determines Regime Shifts and Alternative States in an Aquatic Ecosystem

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*(Article begins on next page)*

1 BIOLOGICAL SCIENCES: Ecology

2

3 **Organic-matter loading determines regime shifts and alternative states in an**  
4 **aquatic ecosystem**

5

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14

15 Author contributions: A.M.E. and N.J.G. designed the experiment: J.S., B.B., and A.M.E.  
16 executed the experiment: J.S., B.B., N.J.G, and A.M.E. wrote the paper.

17

18 **Slow changes in underlying state variables can lead to “tipping points” – rapid transitions**  
19 **between alternative states (“regime shifts”) in a wide range of complex systems. Tipping**  
20 **points and regime shifts routinely are documented retrospectively in long time series of**  
21 **observational data. Experimental induction of tipping points and regime shifts is rare, but**  
22 **could lead to new methods for detecting impending tipping points and forestalling regime**  
23 **shifts. Using controlled additions of detrital organic matter (dried, ground arthropod prey),**  
24 **we experimentally induced a shift from aerobic to anaerobic states in a miniature aquatic**  
25 **ecosystem – the self-contained pools that form in leaves of the carnivorous northern pitcher**  
26 **plant, *Sarracenia purpurea*. In un-fed controls, the concentration of dissolved oxygen ([O<sub>2</sub>])**  
27 **in all replicates exhibited regular diurnal cycles associated with daytime photosynthesis**  
28 **and nocturnal plant respiration. In low prey-addition treatments, the regular diurnal**  
29 **cycles of [O<sub>2</sub>] were disrupted, but a regime shift was not detected. In high prey-addition**  
30 **treatments, the variance of the [O<sub>2</sub>] time series increased until the system tipped from an**  
31 **aerobic to an anaerobic state. In these treatments, replicate [O<sub>2</sub>] time series predictably**  
32 **crossed a tipping point at ~45h as [O<sub>2</sub>] was decoupled from diurnal cycles of photosynthesis**  
33 **and respiration. Increasing organic-matter loading led to predictable changes in [O<sub>2</sub>]**  
34 **dynamics, with high loading consistently driving the system past a well-defined tipping**  
35 **point. The *Sarracenia* microecosystem functions as a tractable experimental system in**  
36 **which to explore the forecasting and management of tipping points and alternative**  
37 **regimes.**

38

39 **Keywords:** Aerobic, alternative states, anaerobic, model system, photosynthesis, regime shift,

40 *Sarracenia purpurea*, tipping point

41 \body

42 “Regime shifts” are rapid, often unexpected shifts in the dynamics of a system caused by slow,  
43 usually directional changes in an underlying state variable (1, 2). In common usage, regime shifts  
44 reflect a shift from a more “desirable” state of the system to a less desirable one (3, 4). Regime  
45 shifts have been observed in a wide range of financial, physical, and biological systems (4), and  
46 accurate predictions and methods to avert tipping points and ameliorate the negative effects of  
47 regime shifts or even reverse them is a central focus of contemporary research in many fields (4-  
48 7).

49 A classic example of an ecological regime shift of broad societal concern is the shift from  
50 a clear, oligotrophic lake to a murky, eutrophic one. The basic mechanism of eutrophication is  
51 well-understood (2, 3). Increases in limiting nutrients, especially nitrogen and phosphorous (8),  
52 boost primary production by algae and phytoplankton (9). This increase in producer biomass  
53 cannot be controlled by grazers, leading to increased shading and turbidity (10). Oxygen levels  
54 drop as microbes decompose this biomass, often leading to population declines of grazers and  
55 predators and the collapse of aquatic “green” (i.e., producer-controlled) food webs (11). A  
56 similar sequence can occur if there is an excess of allochthonous inputs of organic matter  
57 (detritus) into “brown” (i.e., donor-controlled) aquatic ecosystems (12).

58 A key feature of regime shifts is that feedbacks among state variables (3, 13) and  
59 relationships between state variables or “drivers” (*e.g.*, carbon, nitrogen, phosphorus, or other  
60 critical energy or nutrient sources) and measured response variables (*e.g.*, turbidity, dissolved O<sub>2</sub>  
61 concentration, or food-web structure) can differ dramatically before and after a state change (14).  
62 For example, in oligotrophic lakes, concentrations of nitrogen (N) and phosphorus (P) are well  
63 correlated with producer biomass, but these correlations break down in eutrophic lakes (15). In

64 oligotrophic lakes, excess phosphorus is absorbed by benthic sediments and its release back into  
65 the water column is slow (16). But if the concentration of P in the water is continuously elevated,  
66 it can cross a threshold – a “tipping point” – beyond which the rate of phosphorus (P) recycling  
67 between lake sediments and the water column increases rapidly (16), leading to eutrophication.  
68 However, subsequent reductions of P in the water of eutrophic lakes do not shift the lake back to  
69 an oligotrophic state because, in the eutrophic state, P recycling no longer uniquely controls the  
70 state of the system (17).

71         A large body of theoretical work has identified a number of statistical early-warning  
72 indicators for a tipping point, defined as the point in time when a system shifts from one regime  
73 to another (7). Less attention has been paid to systematic changes in the dynamics of systems on  
74 either side of a tipping point (8), although demonstrating that alternative states exist in a system  
75 is necessary to reliably conclude that a tipping point has been passed (14). The emphasis on  
76 tipping points is perhaps unsurprising because if a tipping point can be detected far enough in  
77 advance, then a regime shift may be averted (3–6). However, modeling studies have shown that  
78 the lead time required to avert a regime shift can be unacceptably long (5, 6), so additional  
79 attention must be paid to understanding dynamics both before and after state changes as a first  
80 step towards determining how to manage or reverse them (*e.g.*, 18, 19). The now-standard  
81 retrospective analyses of lengthy time series of observational data can identify tipping points,  
82 illustrate that an early warning was available if it had been looked for, and document alternative  
83 states (1, 3-4, 20). Prospective forecasting, however, requires a different approach.

84         Experimental induction of regime shifts would provide a workable platform from which  
85 researchers could generate detailed knowledge of initial and final states and the tipping point in  
86 between them. An experimental system also would facilitate the development, testing, and

87 analysis of early-warning indicators of tipping points, prospective interventions to delay or  
88 prevent regime shifts, and methods to shift the system between alternative states. Unfortunately,  
89 such experiments are rare (2), and mathematical modeling of tipping points and regime shifts has  
90 far outpaced available empirical data (7, 21). However, three recent microcosm studies have  
91 experimentally induced tipping points in populations of single species of microorganisms and  
92 tested whether ‘critical slowing down’ (*csd*) of population density indicates a rapidly  
93 approaching tipping point (22-24). These studies revealed that signals of a tipping point could be  
94 detected as early as eight generations before a transcritical threshold was crossed (22), that  
95 systemic stochasticity could reduce the signal-to-noise ratio in early-warning indicators of  
96 tipping points (23), and that fold bifurcations in system dynamics occurred as a catastrophic  
97 threshold between different system states was crossed (24). Although consistent with theoretical  
98 predictions, these studies on single species in highly simplified environments are not easily  
99 extrapolated to eutrophic aquatic ecosystems.

100 In this study, we experimentally induced a tipping point and a regime shift from an  
101 aerobic to an anaerobic state in an entire aquatic ecosystem: the aquatic assemblage of microbes  
102 and invertebrates found in the leaves of the northern pitcher plant, *Sarracenia purpurea* (25).  
103 This *Sarracenia* “microecosystem” is ideal for studying tipping points and regime shifts for three  
104 reasons. First, it is a naturally occurring, yet tractable and replicable experimental system in  
105 which water-filled pitchers host a well-characterized, five-trophic level, detritus-based food web  
106 (26, 27). Second, its carbon (photosynthetic) and nutrient-cycling dynamics are well  
107 characterized and understood (28–30), so mechanistic linkages can be made between organic-  
108 matter loading (*i.e.*, prey addition) and persistence of, or transitions between, aerobic and  
109 anaerobic states (See SI Appendix, a model of the *Sarracenia* system). Finally, because it

110 naturally exists in both aerobic and anaerobic states, the *Sarracenia* system can be viewed as a  
111 model system for understanding eutrophication in freshwater ponds and lakes, which have  
112 provided some of the best examples of tipping points and regime shifts. Most systems studied so  
113 far, including the *Sarracenia* system, can shift between regimes or eventually recover from  
114 apparently catastrophic shifts (19). Moreover, our perception of the apparent long-term stability  
115 of many systems may not reflect the underlying drivers of system change (14). For these reasons,  
116 we avoid here the use of the word *stable* in “alternative stable state”, and instead focus on the  
117 statistical properties of systems that emerge from controlled and replicated experiments.

118

### 119 **The *Sarracenia* microecosystem**

120 *Sarracenia purpurea* is a widespread, long-lived, perennial, North American carnivorous plant  
121 (31). The plant has pitcher-shaped leaves that open during the growing season, fill with  
122 rainwater, and capture invertebrate prey, primarily ants (32). This resource base of captured prey  
123 supports a five-trophic level food web that includes bacteria, protozoa, the bdelloid rotifer  
124 *Habrotrocha rosa* Donner, and larvae of several obligate Diptera (25, 33, 34). The *Sarracenia*  
125 food web has been characterized as a processing chain commensalism (33), but the top predators  
126 in the system—larvae of the pitcher-plant mosquito, *Wyeomyia smithii* (Coq.), and the pitcher-  
127 plant flesh-fly, *Fletcherimyia fletcheri* (Aldrich)—are not critical for breakdown of prey and  
128 translocation of nutrients to the plant; the microbes by themselves efficiently decompose and  
129 mineralize nearly all of the captured prey biomass (29).

130         Depending on the photosynthetic activity of the plant, the quality and quantity of  
131 captured prey, and the structure of the food web within the pitcher, the oxygen content of the  
132 liquid in pitcher in the field can vary greatly from well-oxygenated to nearly anaerobic (See SI  
133 Appendix, a model of the *Sarracenia* system). In aerobic conditions, captured prey is rapidly

134 shredded by larvae of the pitcher-plant midge *Metriocnemus knabii* Coq. and subsequently  
135 processed by aerobic bacteria whose populations are regulated by higher trophic levels in the  
136 food web (35). The respired carbon dioxide from the food web is taken up by the plant, which in  
137 turn releases oxygen back into the water as it photosynthesizes (28). In contrast, anaerobic  
138 conditions occur following a rapid accumulation of excess prey (often from a single pulsed input;  
139 *e.g.* (36)) that cannot be processed with sufficient speed by the animal food web (See SI  
140 Appendix, fig. S2). The daily input of O<sub>2</sub> to the aquatic microecosystem from plant  
141 photosynthesis and diffusion from the atmosphere cannot compensate for the slower breakdown  
142 of prey by anaerobic microbes, and concentration of dissolved O<sub>2</sub> remains at persistent low  
143 levels. In other words, when prey input is excessive, the *Sarracenia* ecosystem resembles lakes,  
144 streams, estuaries, and other aquatic ecosystems that have experienced increased biological  
145 oxygen demand following eutrophication (9, 12, 26).

146

## 147 **Results and Discussion**

148 In un-fed controls, dissolved oxygen concentration ([O<sub>2</sub>], expressed in percent, where percent O<sub>2</sub>  
149 in the atmosphere = 20.95 ≡ 1.26 g/L O<sub>2</sub> at 25 °C at Harvard Forest, 334 m above sea level) in all  
150 replicates exhibited a regular diurnal cycle associated with daytime photosynthesis and nocturnal  
151 plant respiration (Fig. 1A; See SI Appendix, fig. S1). In all of these control time series, there also  
152 was a slight trend towards increasing [O<sub>2</sub>] over the course of each 4-day experiment (See SI  
153 Appendix, fig. S6). In the two lowest prey-addition treatments (0.125 mg ml<sup>-1</sup> d<sup>-1</sup> or 0.25 mg ml<sup>-1</sup>  
154 d<sup>-1</sup> added nutrients), diurnal cycles of [O<sub>2</sub>] became irregular and illustrated a complex pattern of  
155 fluctuations (Fig. 1B, 1C). At the two highest prey-addition treatments (0.5 mg ml<sup>-1</sup> d<sup>-1</sup> or 1.0 mg  
156 ml<sup>-1</sup> d<sup>-1</sup> added nutrients), the diurnal cycle of [O<sub>2</sub>] was restored, albeit with a greatly diminished



157 amplitude and at a substantially lower overall [O<sub>2</sub>] level (Fig. 1D, 1E). The frequency  
158 distribution of day-time [O<sub>2</sub>] was distinctly multimodal (Fig. 2), and depended on prey additions,  
159 not PAR, which was unimodal with a single day-time mode of 388 μmol m<sup>-2</sup> s<sup>-1</sup> (See SI  
160 Appendix, fig. S10-S12, table S2). As in many other systems, these prominent modes are most  
161 parsimoniously explained as resulting from nonlinear responses of the pitcher-plant  
162 microecosystem to variation in prey availability and its subsequent decomposition (See SI  
163 Appendix, analysis of frequency distribution of daytime oxygen concentration). In short,  
164 experimental additions of organic-matter created and sustained aerobic and anaerobic states, and  
165 initiated a transition from aerobic to anaerobic states.

166         A loess model effectively detrended and de-cycled the control time-series data of [O<sub>2</sub>],  
167 yielding nearly constant residuals in these time series (Fig. 1F; See SI Appendix, fig. S13-S16).  
168 The [O<sub>2</sub>] time series of all prey-addition treatments still exhibited some periodicity relative to the  
169 controls (Fig. 1G-1J), but quantitative analysis of structural changes—different regimes—in each  
170 time series revealed statistically-significant break points only in the two highest prey-addition  
171 treatments (0.5 mg ml<sup>-1</sup> d<sup>-1</sup> and 1.0 mg ml<sup>-1</sup> d<sup>-1</sup> added nutrients). In each of these two treatments,  
172 tipping points were detected in five of six replicates (temporal locations of individual time series  
173 indicated by the vertical cyan lines in Fig. 1I, 1J; break points of the averaged time series  
174 indicated by the vertical red lines in Fig. 1I, 1J). The break point in the two highest prey-addition  
175 treatments occurred on average 44.6 hours after the start of the feeding experiment and differed  
176 between treatments on average by only 114 minutes ( $t_{[4]} = 0.8655$ ,  $p = 0.4$ , paired  $t$ -test), in spite  
177 of a doubling of the food addition rate. These results suggest that there is a threshold  
178 concentration of organic-matter loading at ≈0.5 mg ml<sup>-1</sup> d<sup>-1</sup> that can reliably induce a tipping  
179 point and regime shift in the *Sarracenia* microecosystem.

180 In addition to differences in time-series dynamics, the statistical moments and trends of  
181 the [O<sub>2</sub>] time series differed significantly among the four prey-addition treatments and the  
182 controls (Fig. 3; Table 1). With increasing prey-addition, there were decreases in the skewness  
183 and temporal trends of [O<sub>2</sub>] (Fig. 3) and the variance of the [O<sub>2</sub>] time series increased with  
184 increasing prey additions up until the system shifted from an aerobic to an anaerobic state (See  
185 SI Appendix, fig. S16). Within the 0.5 mg ml<sup>-1</sup> d<sup>-1</sup> prey-addition treatment—the lowest feeding  
186 level for which we observed a state change—the time-series mean was significantly higher ( $t_{[5]} =$   
187 8.84,  $P < 0.001$ ) before the regime shift than afterward, and the temporal trend in [O<sub>2</sub>] shifted  
188 from declining before the system shifted from aerobic to anaerobic to flat after the regime shift  
189 ( $t_{[5]} = 3.76$ ,  $P = 0.007$ ) (compare the colored box plots in Fig. 3). A statistically stronger, but  
190 qualitatively similar result was found in the 1.0 mg ml<sup>-1</sup> d<sup>-1</sup> prey-addition treatment: all three  
191 statistical moments were higher, and the temporal trend in [O<sub>2</sub>] was significantly more negative,  
192 before the regime shift than after it (mean:  $t_{[5]} = 7.28$ ,  $P < 0.001$ ; variance:  $t_{[5]} = 5.46$ ,  $P = 0.001$ ;  
193 skewness:  $t_{[5]} = 4.93$ ,  $P = 0.002$ ; slope:  $t_{[5]} = 3.39$ ,  $P = 0.01$ ). We note, however, that these  
194 patterns do not necessarily indicate *csd*. Deterministic dynamics could cause manipulated  
195 microecosystems to simply diverge further from the controls, leading to an increase in variance  
196 that would be unrelated to *csd*. Thus, evidence for *csd* would be better identified from analysis of  
197 individual time series or of replicate time series within each treatment (see SI Appendix,  
198 supplemental analysis of time-series data).

199 The relationship between [O<sub>2</sub>] and light available for photosynthesis—the primary driver  
200 of O<sub>2</sub> production by the plant—differed between the two states (Fig. 1K-1O; See SI Appendix,  
201 fig. S13, S14). In the un-fed controls, the trajectory in phase space was virtually identical for all  
202 4 days of the time series (Fig. 1K), and illustrated normal diurnal cycling of photosynthesis and

203 respiration. As the prey-addition rate was increased, the replicated trajectories became more  
204 separated for the early and later parts of each time series (Fig. 1L, 1M). At the two highest  
205 feeding levels, the different regimes were distinctly separated (either side of the red circle in Fig.  
206 1N, 1O). Such changes in the relationships between drivers and response on either side of a  
207 tipping point are consistent with theoretical and empirical studies of alternative states in  
208 ecological systems (14, 18, 19).

209

## 210 **Conclusions**

211 The results presented here illustrate that, with modest organic-matter loading, we can predictably  
212 induce a regime shift in a fully functioning, multi-trophic, detritus-based (donor-controlled)  
213 ecological system. Although there was some variability between replicate ecosystems receiving  
214 the same prey additions, the variance within treatments was relatively small, and the system  
215 responded in characteristic and repeatable ways to increases in the feeding rate (Fig. 1, 2; See SI  
216 Appendix, fig. S12, S14). These results suggest that organic-matter loading not only triggers the  
217 state change from the aerobic to the anaerobic state, but that decomposition of prey (35) and  
218 biological oxygen demand are the primary drivers that control the dynamics both before and after  
219 a tipping point (Fig. 3; See SI Appendix, fig. S3, S8-S10).

220 The experimental induction of alternative states in the *Sarracenia* microecosystem  
221 provides some support for theoretical predictions of increasing variance in time series prior to a  
222 regime shift. More importantly, however, this study highlights the possibilities of a tractable  
223 experimental system with which to explore tipping points, regime shifts, and alternative states.  
224 Future work with this system will involve identifying biologically based early-warning indicators  
225 of tipping points. We hypothesize that such biomarkers, including genomic and proteomic

226 markers derived from microbial activity (37), can provide more lead time for intervention than  
227 measurements of traditional environmental variables such as  $[O_2]$ , which may be easier to  
228 measure but are themselves driven by underlying biological processes.

229

## 230 **Materials and Methods**

231 We explored the dynamics of aerobic to anaerobic state changes in the pitcher-plant system using  
232 mathematical modeling (See SI Appendix, a model of the *Sarracenia* system) and a controlled  
233 greenhouse experiment. Replicate *Sarracenia purpurea* pitchers were inoculated with liquid  
234 collected from field plants that contained the naturally-occurring bacterial community. We then  
235 varied the prey fed to each pitcher and continuously monitored the concentration of dissolved  
236 oxygen  $[O_2]$ . Each individual *Sarracenia* leaf functioned as an independent ecosystem in which  
237 the response of an environmental variable (dissolved  $[O_2]$ ) was monitored as a function of an  
238 environmental driver (organic-matter addition). We report  $[O_2]$  as a percent. The percent  $O_2$  in  
239 the atmosphere = 20.95. The greenhouse at Harvard Forest in which we did the experiment is at  
240 334 m above sea level, where the atmospheric pressure is 0.964 that of sea level. Thus, the  
241 atmospheric density of  $O_2$  in the greenhouse at 25 °C (within 0.5 ° of the average air and pitcher-  
242 fluid temperatures during the experiment – see below) = 1.26 g/L.

243 **Experimental Treatments** Pitcher plants were purchased from Meadowview  
244 Biological Station (Woodward, Virginia, USA) in 2010, and maintained in the Harvard Forest  
245 greenhouse for two years before the experiments were initiated in June 2012. For each of six  
246 experimental trials, we randomly selected five plants and used the most recent fully-formed  
247 pitcher (leaf) on each plant as the focal pitcher for a randomly-assigned treatment. We filled the  
248 focal pitcher on each plant with pitcher fluid collected on the first day of each trial from pitchers

249 growing in a naturally occurring *S. purpurea* population at Tom Swamp Bog in Petersham, MA  
250 (42°30' N, 72°11' W), 6 km from the greenhouse. To remove macrobes and debris larger than 30  
251  $\mu\text{m}$  in diameter, pitcher fluid was filtered first through sterile Whatman filter paper (Whatman  
252 International Ltd, Maidstone, England), and then through sterile BioRadpolyprep  
253 chromatography columns (Bio-Rad Laboratories, Richmond, CA). Focal pitchers were filled to  
254 slightly below their rim with homogenized filtrate. Focal pitchers varied in volume from four to  
255 18 ml, and the volume of pitcher fluid dispensed into each leaf was recorded. Non-focal pitchers  
256 on each plant were filled with deionized water.

257         At noon each day for four consecutive days, treated plants were fed an aliquot (0.125,  
258 0.25, 0.5, or 1.0  $\text{mg ml}^{-1} \text{d}^{-1}$ ) of dried, finely-ground vespid wasp (*Dolichovespula maculata*  
259 (Fabr.)) tissue that has a % C = 51.5, a C:N ratio of 5.99 : 1 and N:P:K ratios (10.7 : 1.75 : 1.01)  
260 nearly identical to those of ant species (C:N = 5.9; N:P:K = 12.1 : 1.52 : 0.93) that are the most  
261 common prey item of pitcher plants (30). Dissolved oxygen concentration in the pitcher fluid  
262 was measured at 1-s intervals with D-166MT-1S microelectrodes (Lazar Research Laboratories,  
263 Los Angeles, CA); 1-minute averages were recorded with a CR-1000 data logger (Campbell  
264 Scientific, Logan, Utah). Each day when the plants were fed, oxygen electrodes were  
265 recalibrated following the manufacturer's instructions. Temperature in the pitcher fluid and the  
266 surrounding air were measured simultaneously with thermistors (mean air temperature = 25.45  
267  $^{\circ}\text{C}$ ; mean water temperature = 25.18  $^{\circ}\text{C}$ ), and photosynthetically active radiation (PAR:  $\mu\text{mol m}^{-2} \text{s}^{-1}$ )  
268 was measured 5 cm below the tops of the plants with an LI-190SA PAR sensor (Li-COR,  
269 Lincoln, NE).

270         We ran six of these 4-day experimental trials. Each run consisted of five plants assigned  
271 randomly to one of five different prey-addition levels (0 [unfed controls], 0.125, 0.25, 0.5, 1.0

272 mg ml<sup>-1</sup> d<sup>-1</sup>) and represented a temporal block to control for unmonitored changes in the  
273 greenhouse environment through the course of the summer. Plants were assigned randomly to  
274 treatments, interspersed randomly in trays on greenhouse tables, and treated identically in all  
275 respects other than the prey-addition level they received. Total sample size over the six replicate  
276 temporal blocks was 30 plants. There was no significant block (trial) effect on any of the test  
277 statistics (Table 1).

278 **Data Analysis** For each of the 30 plants, we generated a time series of 1-minute averages  
279 of [O<sub>2</sub>] and PAR; lengths of the time series ranged 5734-5862 observations. To facilitate  
280 averaging across replicates, we truncated the terminal observations in each series to match the  
281 shortest time series (5734 min). During daily feeding and recalibration, the [O<sub>2</sub>] series was  
282 interrupted; we used linear interpolation to fill in these missing values, which constituted < 2%  
283 of each time series.

284 Statistical detection and analysis of tipping points and alternative states normally is done  
285 on detrended and de-cycled time series of standardized data (7). We centered and scaled  
286 individual measurements  $x_i$  ( $i = 1$  to  $t$ ;  $t = 5734$ ) of [O<sub>2</sub>] in each time series as:  $z_i = \frac{x_i - \bar{x}}{\sigma_x}$ . In  
287 time-series analyses, data are typically detrended and de-cycled by fitting smoother functions to  
288 a series and then calculating residuals from the fitted trend line (38). In this study, however, the  
289 control time series represents the explicit null hypothesis against which state changes due to  
290 organic-matter additions are properly measured. Thus, rather than detrending each time series in  
291 isolation, for comparative purposes we detrended the time series of data from the prey-addition  
292 treatments relative to the time-series data from the control plant within each block. Detrending  
293 against the controls is important because, in the absence of organic-matter loading, the [O<sub>2</sub>]  
294 series for the *Sarracenia* micro-ecosystem exhibits diurnal periodicity (Figure 1A), reflecting the

295 daily cycle of plant photosynthesis and respiration (28). Such periodicity can obscure early-  
296 warning indicators of tipping points (39). We fit a smoothed local regression model to each of  
297 the standardized control series, using the loess function in the stats library of R (version  
298 2.13.1). We then de-cycled and detrended data from the enriched series by subtracting the  
299 predicted (loess) values of the standardized control time series from the observed, standardized  
300 values of each time series of fed pitchers. Alternative analyses of the raw time series and of time  
301 series that were detrended and de-cycled individually (as opposed to relative to the controls) are  
302 presented in SI Appendix (See SI Appendix, supplemental analysis of time-series data). These  
303 supplemental analyses gave results that were qualitatively similar to those based on a detrending  
304 of each food-addition time series relative to the control series.

305 We used the strucchange library in R (40) to test statistically for the presence of break  
306 points in each of the time series (including the controls). strucchange should be applied to  
307 detrended, de-cycled series; a time series without breaks is flat (slope = 1) and has mean  
308 (intercept) = 0. strucchange then applies a moving window across a time series to identify the  
309 optimal number of break points (change in intercept) on the basis of the residual sum of squares  
310 and Bayesian information criterion; the latter imposes a penalty for the identification of multiple  
311 breakpoints, and the optimal number of breakpoints may = 0. We used a conservative 2-standard  
312 deviation criterion to distinguish statistically significant break points (14). Break points were  
313 identified for time series only in the two highest prey-addition treatments, and for these we used  
314 a simple *t*-test to compare the average time to the breakpoint.

315 Following the approach of Dakos et al. (7), we examined metric-based indicators of  
316 tipping points in each time series. For the [O<sub>2</sub>] residuals of each time series, we estimated the  
317 statistical moments (mean, variance, skewness) and the least-square regression slope of the

318 residuals versus time (a simple index of a linear temporal trend). Models of tipping points  
319 suggest that there should be an increase in the variance (See SI Appendix, fig. S16), or skewness  
320 as a breakpoint is approached (7); evidence for critical slowing down (*csd*) is best assessed by  
321 analyzing individual time series and replicate time series within each treatment (See SI  
322 Appendix, supplemental analysis of time-series data). We first used a randomized block  
323 ANOVA to test for the effect of prey-addition level on each metric calculated for the entire time  
324 series (Table 1). Next, for the two highest prey-addition treatments that exhibited statistical  
325 breakpoints, we used a matched-pairs one-sample *t*-test to test for the effects of pre- *versus* post-  
326 breakpoint differences in each metric.

327         In addition to the break-point tests and comparisons of statistical metrics, we visually  
328 examined plots of [O<sub>2</sub>] as a function of PAR (as in ref. 14). These plots trace the temporal  
329 dynamics of both variables simultaneously over the 4-day time series, and illustrate the  
330 separation of the time series into distinctive alternative states in the fed treatments. Fig. 1  
331 illustrates residuals of [O<sub>2</sub>] as a function of PAR; Fig. S14 illustrates the [O<sub>2</sub>] – PAR relationship  
332 for raw [O<sub>2</sub>] data.

333         **Data Availability**     All raw data and R code for the analyses, and Mathematic code for  
334 the *Sarracenia* model are available from the Harvard Forest Data Archive  
335 (<http://harvardforest.fas.harvard.edu/data-archive>), dataset HF205.

336

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424

## Figure Legends

425 **Fig. 1.** Analysis of the time series of dissolved oxygen concentration ( $[O_2]$ , in percent; on this  
426 scale, atmospheric  $[O_2] = 20.95 \equiv 1.26$  g/L in our greenhouse) in *Sarracenia* microecosystems as  
427 a function of experimental organic-matter loading through prey addition: 0 (control), 0.125, 0.25,  
428 0.5, or 1.0 mg ml<sup>-1</sup> d<sup>-1</sup> dry mass of ground wasps ( $n = 5734$  observations of  $[O_2]$  per replicate  
429 within each treatment). **(A–E)** Mean raw data  $[O_2]$  time-series (blue line) and 95 % confidence  
430 intervals (grey region) for each treatment across six replicates. **(F–J)** Mean de-cycled and  
431 detrended time-series (blue line) and 95 % confidence intervals (grey region) for each treatment  
432 across six replicates. The five vertical cyan lines show the break points for the  $[O_2]$  residuals of  
433 each replicate (1 of the 6 replicates did not display a significant break point); the vertical red line  
434 in each treatment shows the break point for the mean of all the series within a treatment. **(K–O)**  
435 Relationships between the primary environmental driver (photosynthetically active radiation  
436  $[PAR, \text{in } \mu\text{mol m}^{-2} \text{s}^{-1}]$ ) and average (residual)  $[O_2]$ . Different color lines corresponding to the  
437 four days of each trial run. Dark blue represents day one, light blue represents day two, mustard  
438 represents day three, and brown represents day four. The red circles in plots **N** and **O** indicate the  
439 times of the switches from aerobic to anaerobic states in the two highest prey-addition  
440 treatments.

441

442 **Fig. 2.** Frequency distributions (number of minutes between 0900 and 1500 hours) of  $[O_2]$  in the  
443 five different prey-addition treatments. The red triangles indicate the location of 4 modes in the  
444 joint distribution identified with normal mixture modeling and model-based clustering (See SI  
445 Appendix, fig. S12). The first identified mode (at 1.682 %  $O_2$ ) corresponds to the mode for the  
446 distributions of the two highest prey-addition treatments (0.5 and 1.0 mg ml<sup>-1</sup> d<sup>-1</sup>); the second

447 (7.554 %) corresponds to the mode of the distribution of the intermediate prey-addition treatment  
448 (0.25 mg ml<sup>-1</sup> d<sup>-1</sup>); the third (12.146%) corresponds to the mode for the lowest prey-addition  
449 treatment (0.125 mg ml<sup>-1</sup> d<sup>-1</sup>); and the fourth (16.272 %) corresponds to the mode for the  
450 distribution of the controls.

451 **Fig. 3.** Box-plots of statistical moments and least-squares regression slope coefficients of the  
452 time series of [O<sub>2</sub>]. Grey boxes represent replicates from treatments with no breakpoints (0,  
453 0.125, 0.25 mg ml<sup>-1</sup> d<sup>-1</sup> added nutrients). Blue and brown boxes represent the values for these  
454 variables in each of the two different states of the system induced by the higher levels of organic-  
455 matter loading (0.5 and 1.0 mg ml<sup>-1</sup> d<sup>-1</sup> added prey). See Table 1 for statistical summaries of  
456 treatment effects.

## Supporting Online Material

# Organic-matter loading determines regime shifts and alternative states in an aquatic ecosystem

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## 1. A model of the *Sarracenia* system

### 1.1 Equations

Classical (and still widely-used) models for oxygen dynamics in lakes and streams are linear and lack feedbacks (1). In contrast, the detritus-based, pitcher-plant (*Sarracenia purpurea* L.) food web (including the bacteria) occurs in a pool of water inside a living (and photosynthesizing) plant, providing an opportunity for (nonlinear) feedbacks between the food web and the plant itself (2).

Scheffer et al. (3) described a minimal model for a system that can exhibit alternative (stable) states and hysteresis between them:

$$\frac{dx}{dt} = a - bx + rf(x). \quad (\text{Equation S1})$$

In Equation S1,  $x$  is the ecosystem property of interest,  $a$  is an environmental factor that promotes  $x$ ,  $b$  is the decay rate of  $x$  in the system, and  $r$  is the rate at which  $x$  recovers as a function  $f$  of property  $x$ . We apply this model to the pitcher-plant system, in which the ecosystem property of interest,  $x$  (concentration of dissolved oxygen [O<sub>2</sub>] in mg ml<sup>-1</sup>) is a function of interactions between the plant and its decomposing prey ( $w$ ):

$$\frac{dx}{dt} = A - f(w, x) + g(x).$$

By analogy with Equation S1,  $A$  is the environmental factor that promotes oxygenation in the pitcher-plant liquid,  $f(w, x)$  is the decay (loss) rate of oxygen in the pitcher-plant liquid, and  $g(x)$  is a positive feedback loop by which oxygen concentration in the pitcher fluid recovers as a function of available oxygen, which increases from photosynthesis, but decreases from plant and animal respiration.

The full model is a pair of coupled equations:

$$x_{t+1} = \frac{a_t \cdot \sin(2\pi ft)}{A(t)} - \left\{ m + a_t \left[ \frac{w_{t-1}}{K_w + w_{t-1}} \right] \right\} + \frac{D_t(x_t)}{g(x_t)} \quad (\text{Equation S2})$$

$$a_{t+1} = a_t \times \left\{ \frac{a'_{max} - a'_{min}}{1 + \exp(-s \cdot n_t - d)} + a'_{min} \right\}$$

We discuss each of  $A$ ,  $f(\bullet)$ , and  $g(\bullet)$  in turn; individual terms are summarized in Table S1.



**Table S1** – Interpretation and units of terms in the model of oxygen dynamics within pitcher-plant fluid (Equation S2).

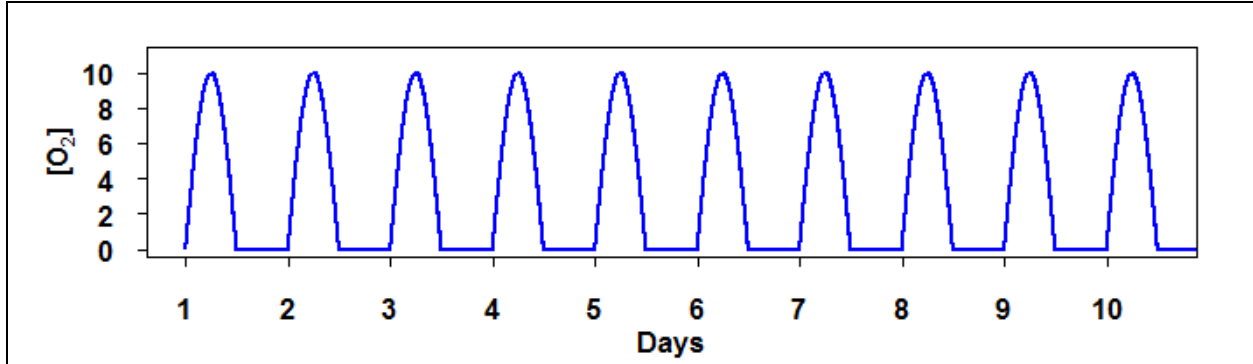
Term	Meaning	Units
$a_t$	maximum amount of oxygen infused at mid-day (amplitude of sine wave for diurnal release of O <sub>2</sub> )	mg/L initialized at $a_0 = 10$
$a'_{min}, a'_{max}$	minimum or maximum possible augmentation of photosynthesis as a result of nutrient uptake from organic-matter decomposition	mg/L set at $a'_{min} = 0, a'_{max} = 2$
$d$	inflection point of the sigmoidal curve relating additional nutrients to augmentation of photosynthesis by organic-matter decomposition	mg set at $d = 0.5$
$D_t$	Recovery of oxygen as a function of available oxygen (diffusion) and photosynthesis (augmented by bacterial activity), offset by respiration	mg/L
$f$	constant adjusting sine wave of diurnal release of O <sub>2</sub> for frequency of measurements	1/ $t$ set at $f = 1/1440$
$K_w$	half-saturation constant for prey consumption	mg/min one of $K_w = 0.1, 0.01, \text{ or } 0.001$
$m$	amount of oxygen used for basal metabolism of bacteria	mg/L $m = 1$
$n_t$	quantity of nutrients released from organic-matter decomposition; it is a function of $w_t$ and $x_t$	mg/L
$s$	steepness of the sigmoidal curve relating additional nutrients to augmentation of photosynthesis by organic-matter decomposition	dimensionless
$t$	time (frequency of model iterations)	minutes
$w_t$	mass of prey at time $t$	mg
$x_t$	concentration of oxygen in the pitcher fluid	mg/L

## 1.2 Details of the model

**A** – The proximal environmental factor  $A(t)$ , which determines baseline oxygen concentration, is diurnal photosynthesis: pitcher-plant leaves take up CO<sub>2</sub> from the water and release O<sub>2</sub> back into it (4, 5). We approximate diurnal release of O<sub>2</sub> (in mg/L) as a zero-truncated sine wave (Figure S1), with a daily peak at mid-day and no O<sub>2</sub> release at night:

$$A(t) = a \cdot \sin(2\pi ft) \quad (\text{Equation S2.1})$$

where  $a$  is amplitude (equal to the maximum amount of oxygen infused at midday). The constant  $f$  within the sine function adjusts for frequency of measurements (iterations in the model), which we make every minute ( $t$  is in units of minutes). Hence,  $f = 1/1440$  (the reciprocal of number of minutes per day). Without loss of generality, we initialize  $a = 10$  (see below, Equation S2.5), start our time series at sunrise ( $t = 1$ ), set day-length at 12 hours, and truncate  $A(t) = 0$  at night, *i.e.*, for  $t \in \{720, 1440\}$ .

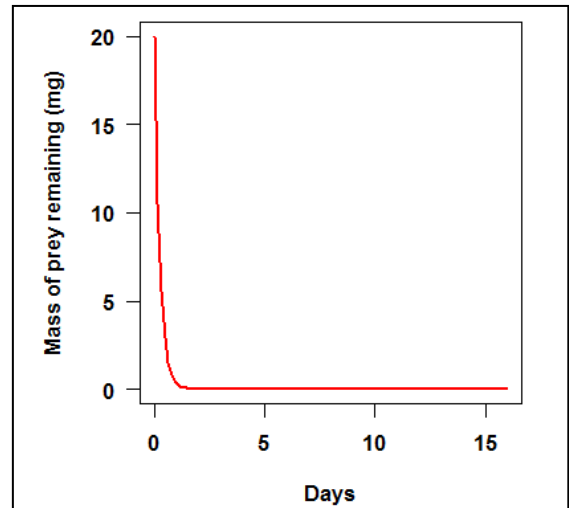


**Figure S1** – Simulated infusion of  $O_2$  into a pitcher-plant leaf due to diurnal photosynthesis (A) in Equation S2.1.

$f(w, x)$  – Oxygen is lost from the system rapidly as prey is consumed by bacteria; this respiration is equivalent to biological oxygen demand (BOD). Because both aerobic and anaerobic bacteria will digest organic matter with more-or-less equal efficiency (6), we assume sufficient, equilibrated numbers of bacteria to process prey at a fixed, negative exponential rate:

$$w(t + 1) = ae^{-b[w(t)]} \quad (\text{Equation S2.2})$$

This model is sensible because easily digested parts of prey, such as fat bodies, are processed first, whereas difficult to digest parts, such as chitin, break down more slowly and are processed later (7); field observations suggest that a single 75- $\mu\text{g}$  wasp can be completely consumed over a 48-hour period in a pitcher with 5 ml of liquid. Thus, in our initial model runs, we set  $a = 20 \text{ mg}$  and  $b = 4 \text{ (mg mg}^{-1} \text{ d}^{-1})$  (Figure S2).

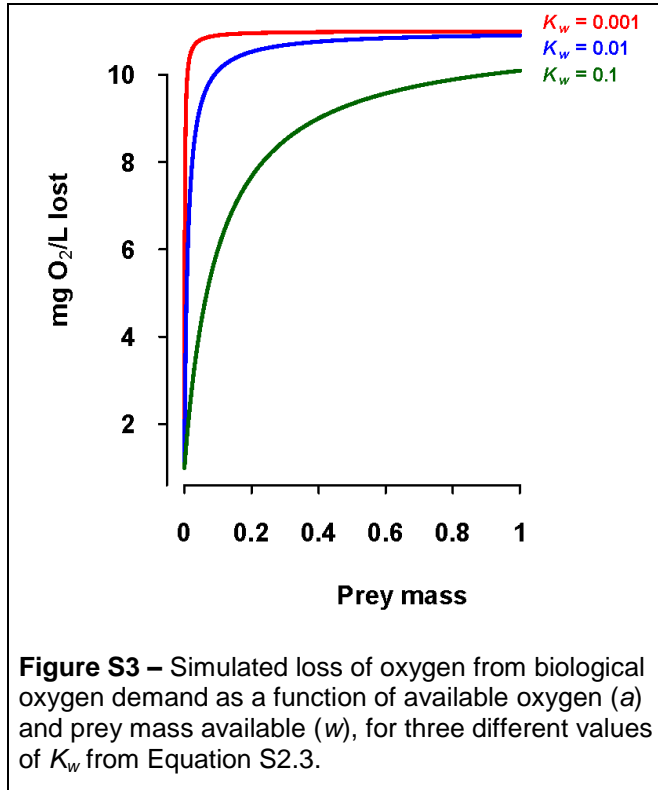


**Figure S2** – Simulated decomposition of prey, assuming a single wasp can be consumed in 48 hours in a 5-ml pitcher, from Equation S2.2.

We model oxygen lost from the system due to prey consumption ( $= 1 - \text{BOD}$ ) to be a saturating (Holling Type-II) function of prey remaining, which itself is a function of the maximum amount of oxygen infused at midday ( $a$  from Equation S2.1, iteratively augmented by  $a'$  as detailed below using Equations S2.4 and S2.5); the mass of prey remaining ( $w$ ); a half-saturation constant for prey consumption ( $K_w$ ), which determines how much prey is leftover each day and would be carried over to the next day; and the amount of oxygen used for basal metabolism of bacteria ( $m$ ):

$$O_2 \text{ lost}(t) = f(w, x, t) = m + a \left[ \frac{w(t-1)}{K_w + w(t-1)} \right] \quad (\text{Equation S2.3})$$

In our initial model runs, we set  $m = 1$  and  $K_w = 0.1, 0.01, \text{ or } 0.001$  (Figure S3).



**g(x)** – Oxygen is replenished in the system in three ways. First, there is some diffusion from the atmosphere into the pitcher fluid. Second, there is oxygen production through daily photosynthesis (2). Because diffusion only happens at the surface of the pitcher fluid, and the “mouth” area of the pitcher is nearly 10× smaller than the surface area of the pitcher itself (8), the amount of oxygen replenished by diffusion is likely to be much less than that provided by photosynthesis; in our model runs, we considered only replenishment from photosynthesis (Equation S2.1).

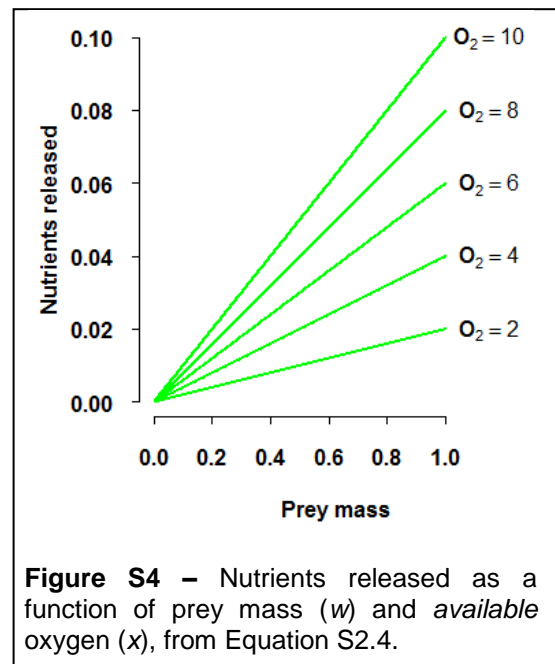
Most importantly, there is a positive feedback loop described by the  $a_{t+1}$  term in Equation S2 that relates prey mineralization to the uptake of mineralized

nutrients by the plant, and the use of these nutrients to increase photosynthetic rate (9). Dead insect prey (ground wasps in our experiment) is a mixture of carbon and mineral nutrients (the C:N ratio is  $\approx 6:1$ ). As prey are broken down and mineralized, nutrients are slowly released by the bacteria and in turn, these nutrients (especially ammonia) are taken up readily by the plant (5). Numerous observations and experiments have demonstrated that carnivorous plants are nutrient (primarily nitrogen) limited (10), and that photosynthetic rates of pitcher plants are enhanced following prey additions (10). We model these processes with a pair of equations.

First, the amount of nutrients released,  $n$ , is a function of prey mass ( $w$ ) and available oxygen ( $x$ ) used by bacteria to break down and mineralize the prey (Figure S4):

$$n(t) = \frac{w(t)x(t)}{c} \quad (\text{Equation S2.4})$$

where  $c$  is a scaling constant (we set  $c = 100$ ).



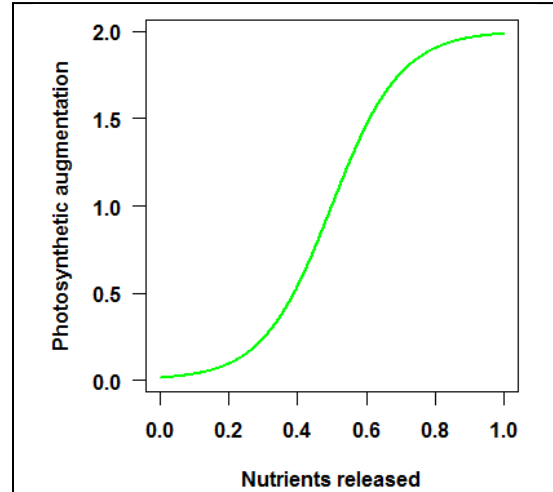
Because nutrients taken up by the plant could be used to make additional enzymes involved in photosynthesis (8), we model uptake as a sigmoidal, saturating relationship between additional nutrients and an augmentation of the peak rate of photosynthesis ( $a$ ) in Equation S2.1 (Figure S5).

$$a'(t) = \frac{a'_{max} - a'_{min}}{1 + \exp[-s * n(t) - d]} + a'_{min} \quad (\text{Equation S2.5a})$$

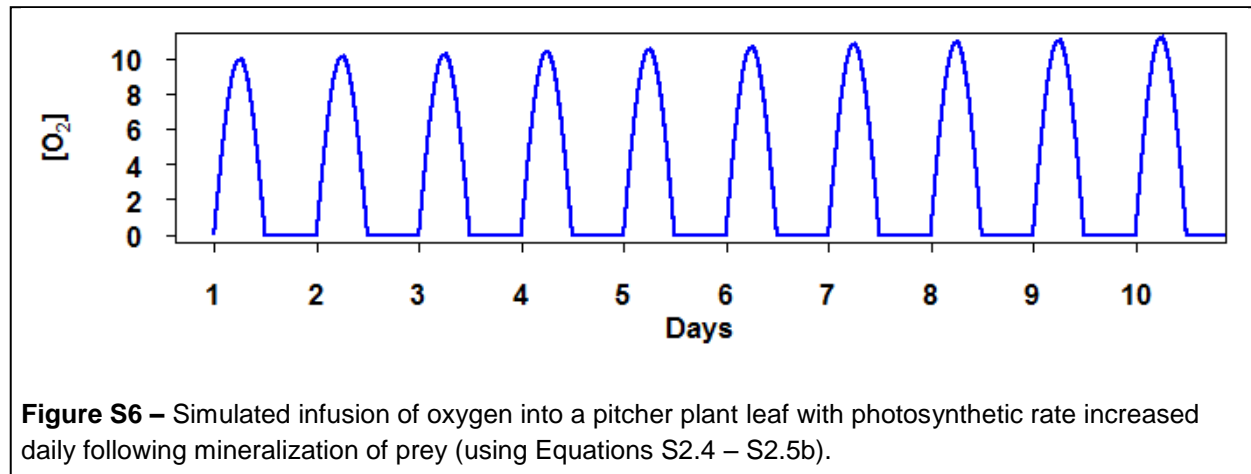
$$a(t + 1) = a(t) \times a'(t) \quad (\text{Equation S2.5b})$$

In Equation S2.5a,  $a'_{min}$  is the minimum possible augmentation of photosynthesis, which we initially set = 0;  $a'_{max}$  is the maximum possible augmentation, which we initially set = 2,  $s$  is the steepness of the increase (= 10), and  $d$  is the inflection point of the curve (= 0.5). Augmentation evolves as leftover prey (*i.e.*, prey not completely broken down on one day) accumulates (within the  $n(t)$  term) and is further mineralized.

Equation S2.5b iteratively updates the maximum possible photosynthetic rate ( $a$  in Equation S2.1). Because this mineralization and conversion is assumed to be a slow process, the update occurs only once each day, as shown in Figure S6.



**Figure S5** – Modeled (Equation S2.5a) effects of nutrients released by decomposition of prey on augmentation factor ( $a'$ ) by which maximum photosynthetic rate  $a$  (in Equation S2.1) would be increased.

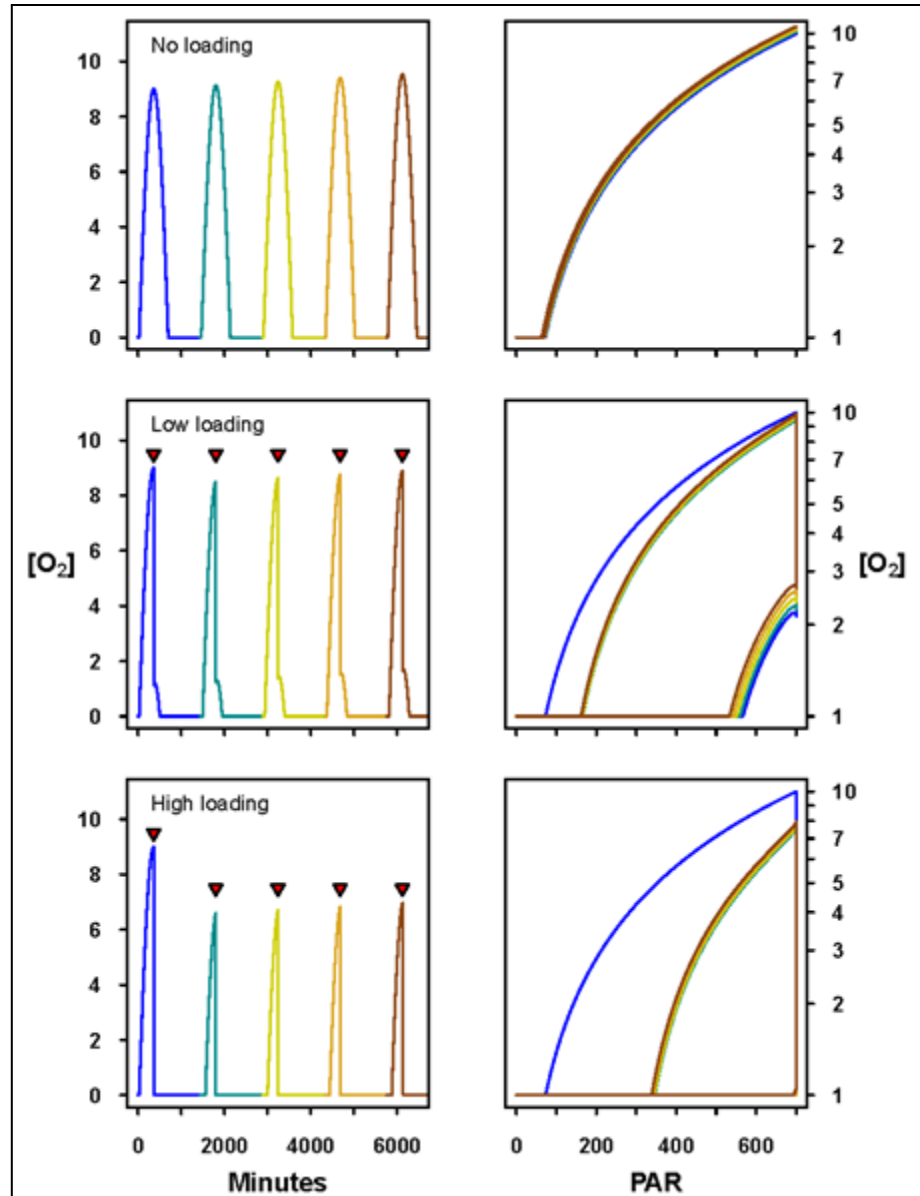


**Figure S6** – Simulated infusion of oxygen into a pitcher plant leaf with photosynthetic rate increased daily following mineralization of prey (using Equations S2.4 – S2.5b).

### 1.3 Model behavior

Model behavior for three levels of organic-matter loading – none, low, and high – and three levels of half-saturation constants  $K_w$  (from Equation S2.3; see Figure S3) are shown in Figures S7-S9. Model

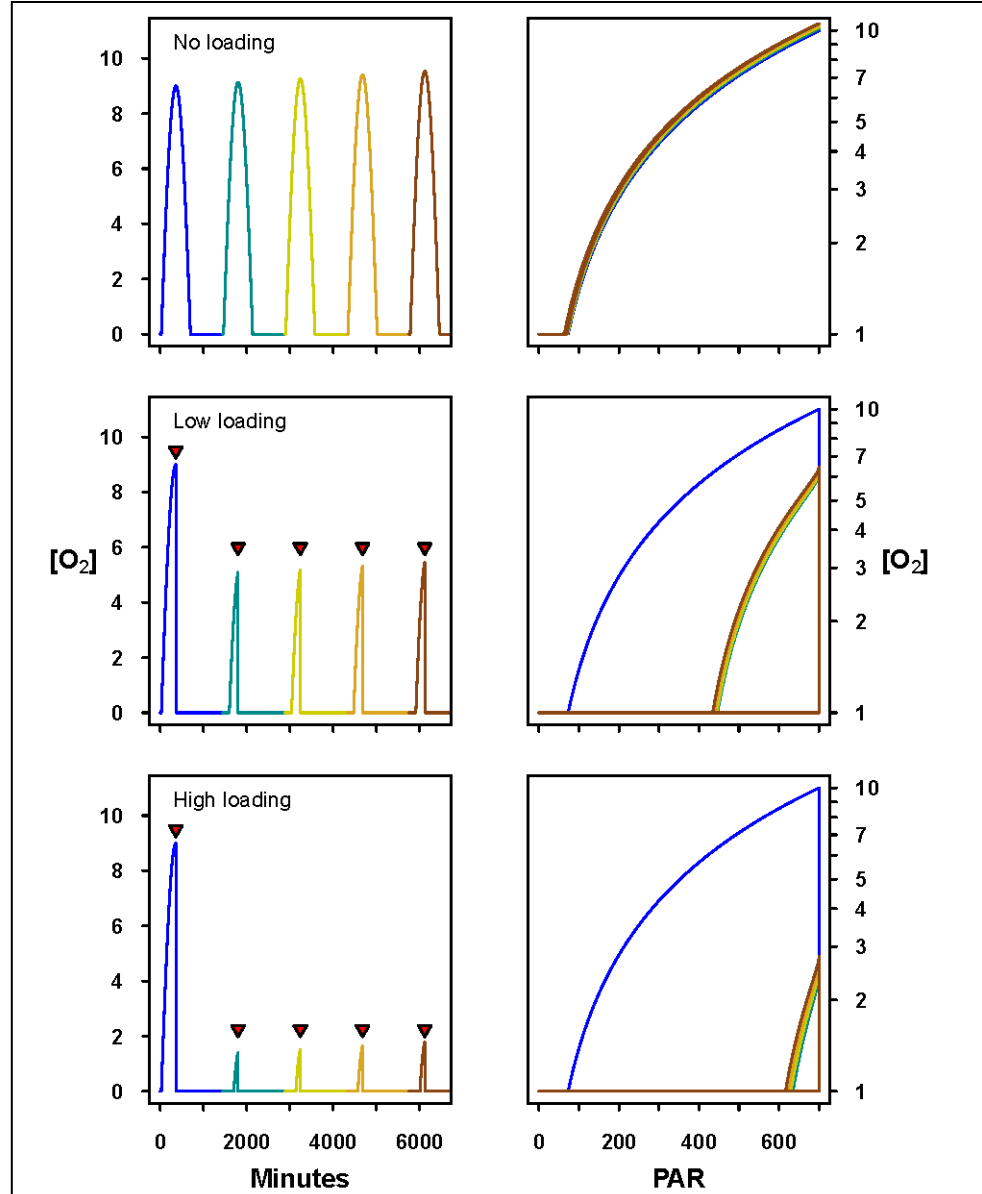
runs began at sunrise (0600 hrs) and prey was added at noon (red triangles in Figure S7). Five days of runs are shown using different colors for each day. Because we modeled both PAR and oxygen evolution (photosynthesis) using a sine wave, there is a gradual and continuous increase or decrease in  $[O_2]$  with diurnal PAR in the control (no prey addition). This differs from the behavior of real plants, in which photosynthesis would follow a Michaelis-Menten-type function with rapid saturation (and which could be modeled as a square wave). We also neglect stochasticity in the system. Regardless of whether photosynthesis is modeled as a sine wave or a square wave, when prey is added, two alternative states (alternate attractors) are visible, with a strong tipping point following



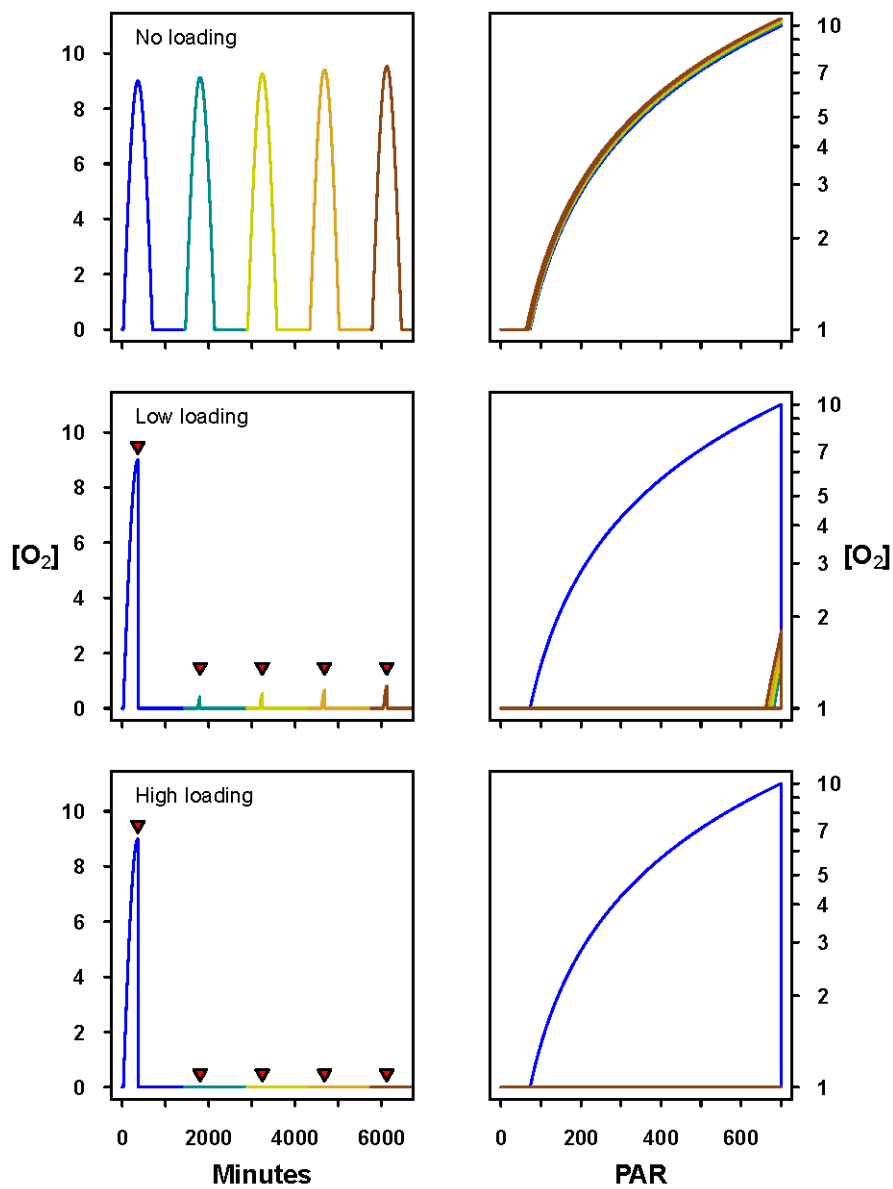
**Figure S7** – Dynamics of the pitcher-plant model (Equations S1 – S2.5), for three levels of prey loading (none, low, high prey additions) with prey half-saturation constant  $K_w$  (Equation S3) = 0.1. The left column shows the diurnal oxygen concentration for the three prey-additions, with timing of prey addition indicated by inverted red triangles. The rapid drop in  $[O_2]$  following prey addition is caused by high BOD, but the recovery is equally rapid because of the high value of  $K_w$ . Each 24-hour segment in the time series is illustrated with a different color (day 1 = blue, day 5 = brown). The right column shows the corresponding relationship between  $[O_2]$  and PAR for each time series.

prey addition. The magnitude of the half-saturation constant controls in large part the difference between the control (aerobic) state and the alternative (anaerobic) state, because it determines how much organic matter is not broken down and is carried over to the next day for additional decomposition. A large half-saturation constant (Figure S7) results in prey being broken down rapidly and the

system recovering relatively quickly. As the half-saturation constant decreases, immediate oxygen loss (BOD) increases (Figure S3), and the system collapses rapidly into an anaerobic state (Figure S9).



**Figure S8** – Dynamics of the pitcher-plant model (Equations S1 – S2.5), for three levels of prey loading (none, low, high prey additions) with prey half-saturation constant  $K_w$  (Equation S3) = 0.01. The left column shows the diurnal oxygen concentration for the three prey-additions, with timing of prey addition indicated by inverted red triangles. The rapid drop following prey addition is caused by high BOD, but the recovery is slowed because of the lower value of  $K_w$ . Each 24-hour segment in the time series is illustrated with a different color (day 1 = blue, day 5 = brown). The right column shows the corresponding relationship between  $[O_2]$  and PAR for each time series.



**Figure S9** – Dynamics of the pitcher-plant model (Equations S1 – S2.5), for three levels of prey loading (none, low, high prey additions) with prey half-saturation constant  $K_w$  (Equation S3) = 0.001. The left column shows the diurnal oxygen concentration for the three prey-additions, with timing of prey addition indicated by inverted red triangles. The rapid drop following prey addition is caused by high BOD, but the recovery is even slower than in Fig S8 rapid because of the very low value of  $K_w$ . Each 24-hour segment in the time series is illustrated with a different color (day 1 = blue, day 5 = brown). The right column shows the corresponding relationship between  $[O_2]$  and PAR for each time series. As in Figure S8, there is a clear second attractor in this example. In the high organic-matter loading simulation (bottom), the second attractor is a tight point at the lower right corner of the plot, not even a small cycle (as in the low organic-matter loading simulation).

### 1.3 Programming and availability of code

The model was coded in Mathematica v8.0. Model code is available from the Harvard Forest Data Archive, dataset HF-205 (<http://harvardforest.fas.harvard.edu/data-archive>).

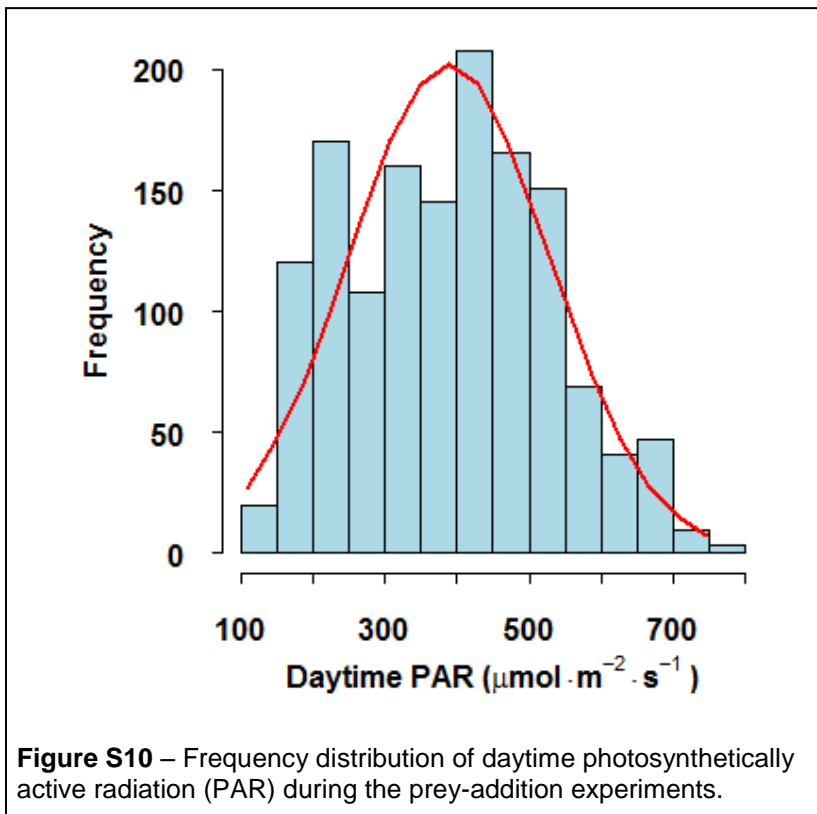
## 2. Additional statistical analyses

### 2.1 Analysis of frequency distribution of daytime oxygen concentration

The combined frequency distribution of a system can illustrate how it is affected by environmental drivers. If the underlying environmental driver is unimodal, then multiple modes of the frequency distribution suggest locations of the basins of attraction of alternative states of the system (11-12).

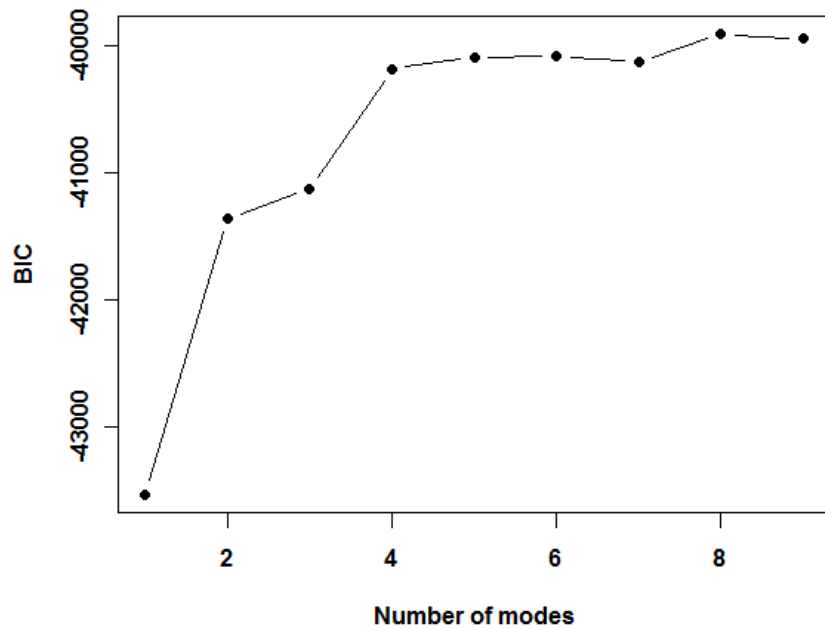
In our experimental system, baseline  $[O_2]$  is controlled by the plant's photosynthesis, and the primary environmental driver is photosynthetically active radiation (PAR) (Equation S2.1 and Figure S2.1, above). Daytime PAR during our experiment was unimodal (Figure S10), but Fig. 1 and Fig. S13 (next section) in the main text illustrate that the “normal” relationship between diurnal PAR and diurnal  $[O_2]$  breaks down as prey (organic matter) is added to the aquatic *Sarracenia* microecosystem.

The number of modes in the combined frequency distribution of  $[O_2]$  of the different treatments was identified with normal mixture modeling and model-based clustering using the mclust package in R, version 3.4 (13). With 7090 total observations, the Bayesian Information Criterion (BIC) identified 4-9 modes as equally plausible (Figure S11); BIC declined rapidly with fewer modes (Figure S11). Thus, parsimony suggests that the overall distribution would be best fit with a four-modal distribution (Figures S12; Table S2).

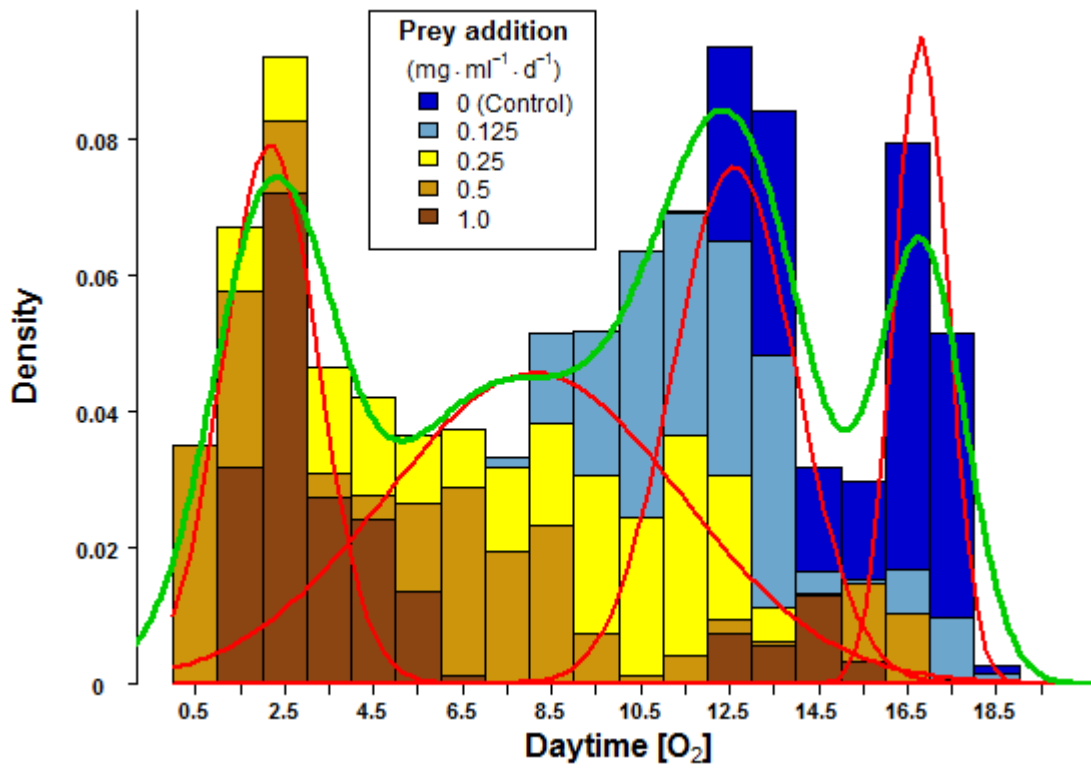


**Figure S10** – Frequency distribution of daytime photosynthetically active radiation (PAR) during the prey-addition experiments.





**Figure S11** – BIC of the number of modes in the joint frequency distribution of  $[O_2]$ .



**Figure S12** – Probability density functions (red) for each of the modes identified in the joint distribution of  $[O_2]$  in the prey-addition experiments. The best-fit (based on BIC) overall probability density function (green) has four modes.

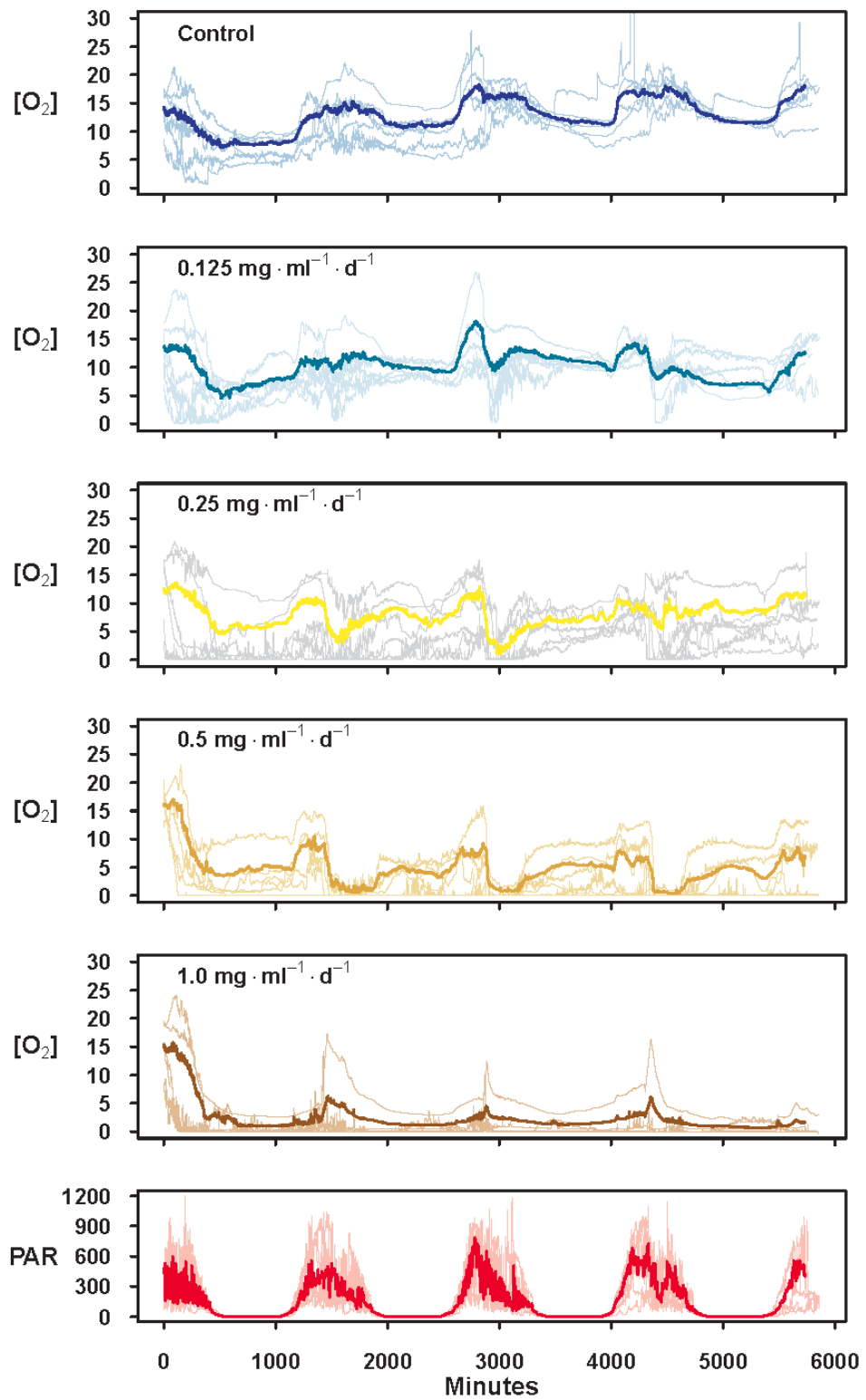
**Table S2** – Best-fit combinations of normal distributions fitted to the frequency distribution of [O<sub>2</sub>] in the prey-addition experiment (Fig. S12).

Mode	$\mu$	$\sigma$	proportion
1	1.682	1.070	0.21
2	7.554	3.322	0.38
3	12.146	1.378	0.26
4	16.272	0.605	0.15

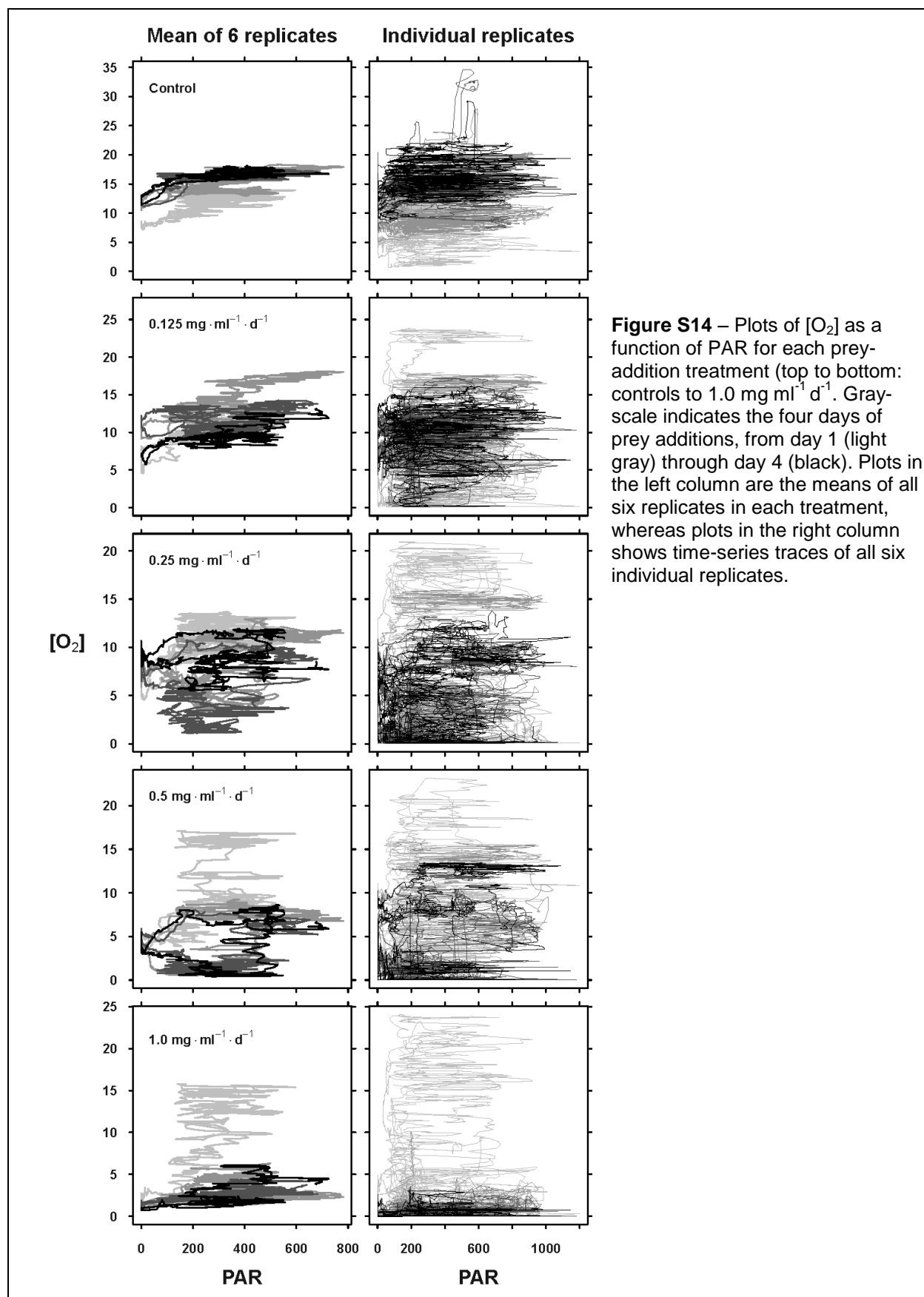
## 2.2 Supplemental analysis of time-series data

The time-series analysis presented in Figure 1 of the main text presents means and confidence intervals of raw data (main text Figures 1A-1E) and then time-series analysis of residuals following detrending relative to the controls. Although detrending relative to the controls does allow for comparisons among the effects of different prey-addition treatments, observed increases in temporal variance following such detrending are not evidence for critical slowing down (*csd*). Rather, evidence for *csd* should be sought by analysis of individual time series or of replicate time series within a given treatment. Here we illustrate the raw data, followed by analysis of individual time series detrended and decycled relative to themselves.

The raw time series and the mean for each prey-addition treatment and the diurnal cycle in photosynthetically available radiation (PAR:  $\mu\text{mol m}^{-2} \text{s}^{-1}$ ) are shown in Figure S13. As suggested by Figures 1A-1E in the main text, the differences among replicates are generally small (except for one replicate within the highest prey-addition treatment), and variance among treatments exceeds variance within treatments (main text Table 1). The diurnal re-oxygenation of the pitcher-plant fluid predominantly associated with photosynthesis (and PAR; bottom time series in Figure S13) is clear in the controls, but falls apart to different degrees in the four prey-addition treatments. This is seen more clearly in the plots of [O<sub>2</sub>] as a function of PAR (Figure S14; these plots of raw [O<sub>2</sub>] show qualitatively similar, albeit more exaggerated, patterns as seen in Figures 1K-1O of the main text, in which we plotted the residuals (relative to controls) of [O<sub>2</sub>] as a function of PAR).

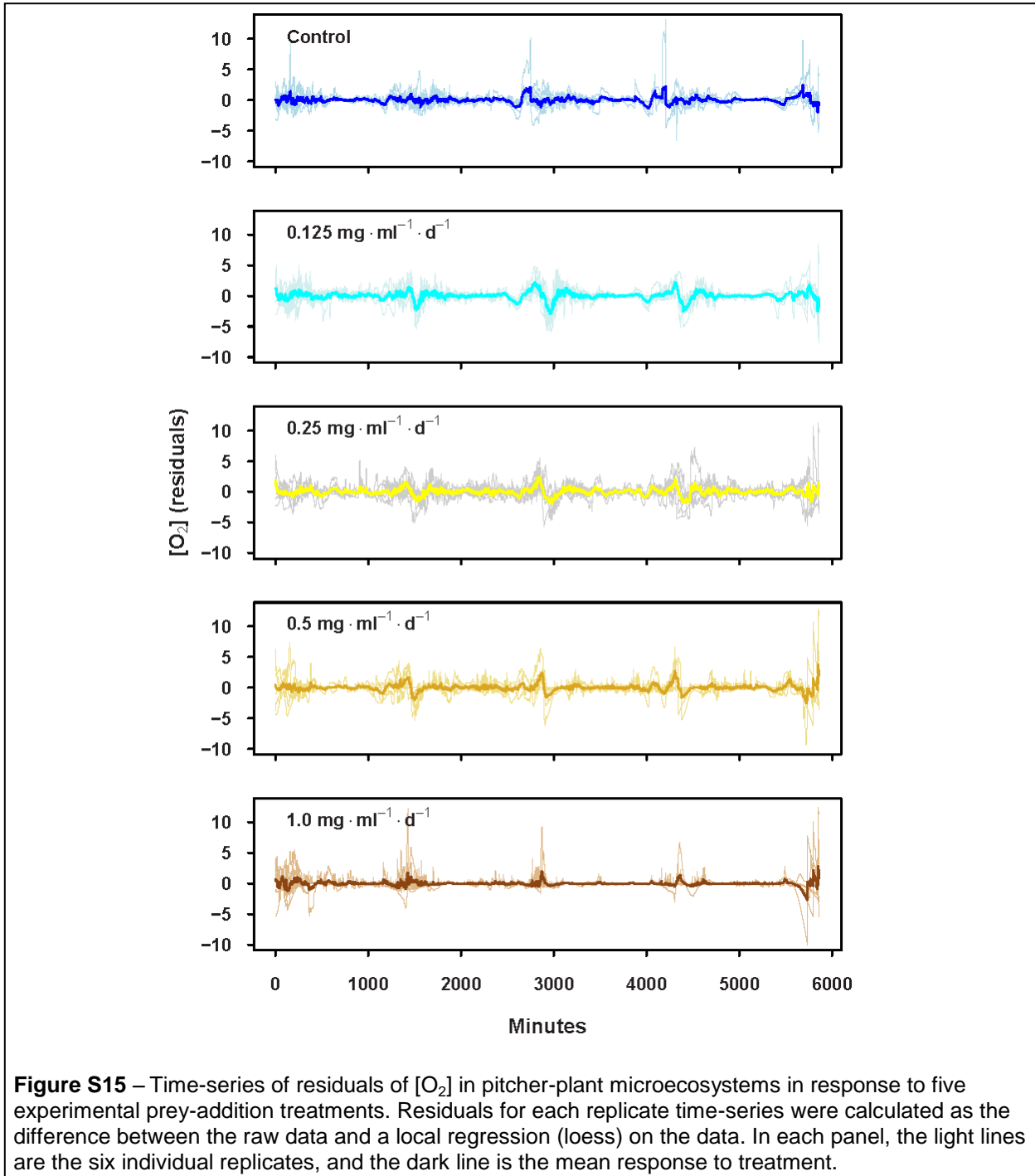


**Figure S13** – Untransformed time series of [O<sub>2</sub>] in pitcher-plant microecosystems in response to five experimental prey-addition treatments (top five panels) and PAR (lowest panel). In each panels, the light lines are the six individual replicates, and the dark line is the mean response to treatment.

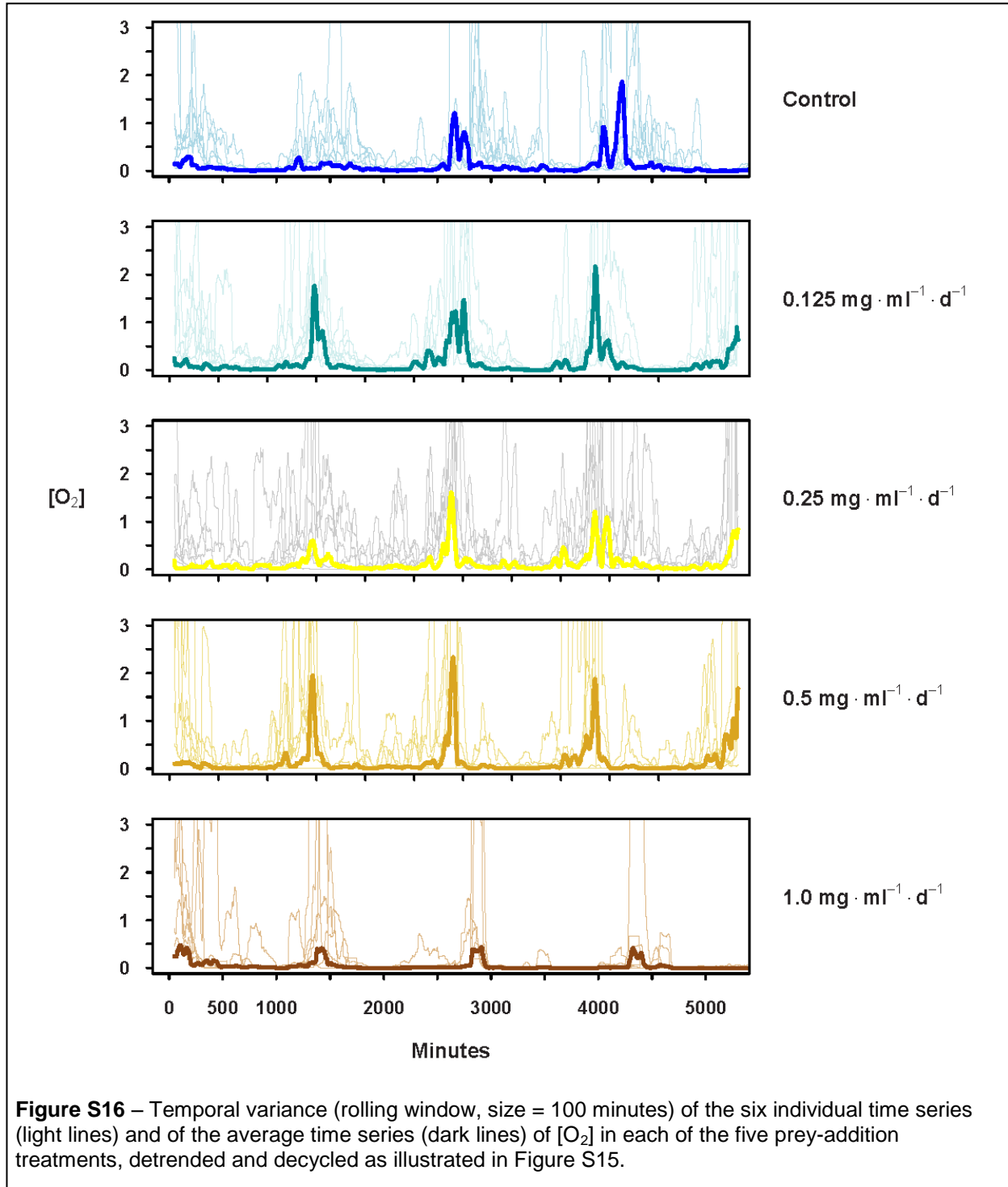


**Figure S14** – Plots of [O<sub>2</sub>] as a function of PAR for each prey-addition treatment (top to bottom: controls to 1.0 mg ml<sup>-1</sup> d<sup>-1</sup>). Gray-scale indicates the four days of prey additions, from day 1 (light gray) through day 4 (black). Plots in the left column are the means of all six replicates in each treatment, whereas plots in the right column shows time-series traces of all six individual replicates.

Each individual time-series from a given replicate was detrended and decycled using local regression (*loess* in R), with the span set = 0.125. We chose this moving window (12.5% of the data) because it corresponds to approximately 12 hours and appropriately smooths a daytime (or night-time) cycle. The individual traces and the averages for each treatment are shown in Figure S15. As expected, all such detrended and decycled time series have mean  $\approx 0$ , and periodicity was eliminated from all of the time series because of the chosen span for the local regression.



Last, we examined changes in the temporal variance of the detrended and decycled time series (Figure S16) as a potential indicator of *csd* (11).



Although Figure S16 illustrates daily noise in  $[O_2]$  associated with biological oxygen demand following daily prey addition (Equation S2.3 and Figure S3), that quickly dissipates in the control treatment (no prey addition). The three intermediate prey additions show more variance across the time series, as well as a pronounced uptick in variance towards the end of the experiment. In contrast, the highest prey addition treatment (bottom panel of Figure S16) shows little change in variance after the first day. In this treatment, variance is highest on the first day, suggesting that the treatment tipped the system into a new regime after either the first feeding (0 minutes in Figure S16) or the second feeding (1441 minutes in Figure S16).

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