## **SCIENTIFIC REPORTS** natureresearch

### **OPEN**

# **Comparison of surgical outcomes between integrated robotic and conventional laparoscopic surgery for distal gastrectomy: a propensity score matching analysis**

**Chul Kyu Roh1,4, SeoheeChoi 1, Won Jun Se[o](http://orcid.org/0000-0003-3447-7790) 1,5, MinahCho 1, YoonYoungChoi 1,2, Taeil Son 1,2, Woo Jin Hyung 1,2 & Hyoung-Il Kim 1,2,3\***

**This study was aimed to compare the surgical outcomes between conventional laparoscopic distal gastrectomy (CLDG) and integrated robotic distal gastrectomy (IRDG) which used both Single-Site platform and fuorescence image-guided surgery technique simultaneously. Retrospective data of 56 patients who underwent IRDG and 152 patients who underwent CLDG were analyzed. Propensity score matching analysis was performed to control selection bias using age, sex, American Society of Anesthesiologists score, and body mass index. Fifty-one patients were selected for each group. Surgical success was defned as the absence of open conversion, readmission, major complications, positive resection margin, and inadequate lymph node retrieval (<16). Patients characteristics and surgical outcomes of IRDG group were comparable to those of CLDG group, except longer operation time (159.5 vs. 131.7min;** *P***<0.001), less blood loss (30.7 vs. 73.3mL;** *P***=0.004), higher number of retrieved lymph nodes (LNs) (50.4 vs. 41.9 LNs;** *P***= 0.025), and lower readmission rate (2.0 vs. 15.7%;** *P***=0.031). Surgical success rate was higher in IRDG group compared to CLDG group (98.0 vs. 82.4%;** *P***=0.008). In conclusion, this study found that IRDG provides the benefts of higher number of retrieved LNs, less blood loss, and lower readmission rate compared with CLDG in patients with early gastric cancer.**

Laparoscopic distal gastrectomy has been widely used to treat early gastric cancer (EGC)<sup>1</sup>. This procedure provides advantages of minimally invasive surgery (MIS) over open gastrectomy with decreasing postoperative pain, pulmonary complications, hospital stay, and improving quality of  $life^{2-4}$ . In recent years, robotic surgery has been used as an alternative to laparoscopy for gastrectom  $y^5$  $y^5$ . However, studies have shown that surgical outcomes of robotic gastrectomy were comparable to those of laparoscopic gastrectomy $6-9$ .

Conventionally, robotic surgery provides potential benefts over laparoscopic surgery, such as EndoWrist instruments, and an ergonomic console system. In addition to these conventional benefts of robotic surgery, recent robotic surgical systems are equipped with Single-Site platform (Intuitive Surgical, Sunnyvale, CA, USA) and fluorescence imaging technology (Firefly). The Single-Site platform allows to reduce the number of ports during robotic surgery for abdominal organ<sup>[10,](#page-7-6)11</sup>. Fluorescence image-guided surgery shows the possibility of adequate lymphadenectomy through visualization of lymphatic channel and lymph node  $(LN)^{12}$ . Our institution reported the surgical outcomes of robotic gastrectomy using Single-Site platform<sup>13</sup> and Firefly technology<sup>[14](#page-7-10)</sup>, however, these technologies have never been applied simultaneously in an integrated procedure.

It was hypothesized that a robotic system integrated with both Single-Site platform and fuorescence imaging technology improve surgical outcomes. Single-Site platform can reduce the number of trocars since one video scope, two robotic arms, and one assistant port are introduced into the abdominal cavity via a single port. Tis

<sup>1</sup>Department of Surgery, Yonsei University College of Medicine, Seoul, Korea. <sup>2</sup>Gastric Cancer Center, Yonsei Cancer Center, Seoul, Korea. <sup>3</sup>Open NBI Convergence Technology Research Laboratory, Severance Hospital, Yonsei Cancer Center, Yonsei University College of Medicine, Seoul, Korea. <sup>4</sup>Present address: Department of Surgery, Ajou University School of Medicine, Suwon, Korea. <sup>5</sup>Present address: Department of Surgery, Korea University College of Medicine, Seoul, Korea. \*email: [cairus@yuhs.ac](mailto:cairus@yuhs.ac)

may minimize surgical trauma associated with multiple trocar insertions. Fluorescence imaging can help identify lymphatics during operation. Visualization of lymphatics increase the number of retrieved LNs, which is a surrogate marker for oncological safety, and reduce injury to adjacent pancreatic tissue and vessels during lymphadenectomy.

The aim of study was to compare the short-term surgical outcomes between integrated robotic distal gastrectomy (IRDG) and conventional laparoscopic distal gastrectomy (CLDG). A collective terminology of surgical success was defned to assess the quality of surgery.

#### **Methods**

**Study design and patients.** A robotic gastric surgery procedure which uses both Single-Site platform and fuorescence image-guided technology was started at our institution in July 2015. Since then, based on patient preference, both laparoscopic and robotic gastrectomy procedures have been performed. Patients were ofered the choice to undergo robotic or laparoscopic gastrectomy. Each patient was given a detailed explanation for each type of surgery and chose the type of surgery before operation. Written informed consent for surgery was obtained from all patients. Between July 2015 and July 2017, 277 consecutive patients underwent IRDG ( $n=65$ ) or CLDG ( $n=212$ ) gastrectomy. All cases of gastrectomy were performed by a single surgeon (KHI). Patients who underwent total gastrectomy (n = 18), proximal gastrectomy (n = 28), completion total gastrectomy (n = 1), and combined resection  $(n=22)$  were excluded to compare perioperative outcomes of distal gastrectomy. In total, 208 patients were included in our analysis. Among these patients, 56 underwent IRDG while 152 underwent CLDG. The Institutional Review Board of Severance Hospital approved this study and waived the need for written informed consent from the participants (IRB No: 4-2017-0810).

**Integrated robotic distal gastrectomy.** In this study, integrated robotic surgery was defned as using of fuorescence imaging technology and Single-Site platform in robotic surgery.

*Endoscopic indocyanine green injection.* Indocyanine green (ICG, Dongindang Pharmaceutical Co., Siheung, Korea) was used as a near-infrared (NIR) fuorescent contrast agent for intraoperative fuorescence imaging. ICG solution was endoscopically injected into submucosal layer at four sites (0.6 mL at each site, for a total ICG amount of 3mg) around primary tumor on the day before surgery (Fig. [1](#page-2-0)), and metal clip was placed for tumor localization.

*Single-Site platform.* The da Vinci Si or Xi Systems (Intuitive Surgical, Sunnyvale, CA, USA) were used to integrate Single-Site and Firefy technologies. Reduced-port robotic gastrectomy using Single-Site platform for Si system has been described previously<sup>13</sup>. In this paper, surgical procedures are described for Xi systems. Figure [2A](#page-3-0) illustrates schematic assignment of robot arms for Single-Site. A 12-mm port (XCEL, Ethicon Endo-surgery, Cincinnati, OH, USA) was inserted along the right fank, and an 8-mm straight cannula (470,002, Intuitive Surgical) was inserted in a port-in-port manner docked on the frst robotic arm for equipping ultrasonic shears (Harmonic ACE Curved Shears, 480,275, Intuitive Surgical). Single-Site port positioned at umbilical site had four lumens for instruments. Needle Driver (EndoWrist Needle Driver, 478,115, Intuitive Surgical) was inserted through a 5-mm curved cannula (478,072, Intuitive Surgical) docked on the second robotic arm. A 10-mm accessory port (10-mm Accessory Cannula, 428,076, Intuitive Surgical) was inserted to Single-Site port for assistance. The da Vinci Xi 30° Endoscope (470,027, Intuitive Surgical) was inserted through an 8-mm camera cannula (478,063, Intuitive Surgical) docked on the third robotic arm. Cadiere Forceps (EndoWrist Grasper, 478,055, Intuitive Surgical) was inserted through a 5.0-mm curved cannula (478,071, Intuitive Surgical) docked on the fourth robotic arm. Figure [2B](#page-3-0) shows the external view of robot arms installed for operation.

*Firefly technology.* The Firefly system was used for fluorescence image-guided lymphadenectomy (Fig. [3](#page-4-0)). Fluorescence image provides real-time and image-guided identifcation of lymphatic drainage using NIR technology. Fluorescence imaging improves visual acuity, precision, and control of lymphadenectomy by providing surgeons with a view of lymphatic drainage that is superior to that of the naked eye. D1 imlymphadenectomy (dissection of group D1 and number 8a, 9 LNs) was performed according to the Korean and Japanese gastric cancer treatment guidelines<sup>[15](#page-7-11),[16](#page-7-12)</sup>.

*Surgical wound closure afer IRDG.* A closed suction drain was inserted through a 12-mm port site in the right fank. Afer drain placement, the umbilical wound for Single-Site was closed in layers as follows. First, the peritoneum and fascia layer were closed interruptedly with Polyglactin 910 (VICRYL Plus) 1–0 sutures. Next, for the umbilical wound, subcuticular sutures of both sides of the skin were performed using Polyglactin 910 (VICRYL Plus) 4–0 sutures. Figure [4](#page-4-1) photograph shows the umbilical wound and inserted drain afer IRDG.

**Conventional laparoscopic distal gastrectomy.** The CLDG was performed in standardized surgical procedures as previously described<sup>17,18</sup>. The extent of lymphadenectomy was  $D1+$  as done in IRDG. The reconstruction type was determined according to the location of tumor. Reconstruction method was performed by intracorporeal anastomosis.

**Postoperative management and complication assessment.** Both groups received the same postoperative management. Patient-controlled analgesia was used for postoperative pain control until postoperative day 2. Oral analgesics were initiated on postoperative day 3. Using the visual analog scale (VAS), postoperative pain was scored from 0 to 10. Pain score was recorded 30minutes postoperatively in the post anesthesia care unit (PACU) and recorded at 3, 6, 12, 24, and 48hours postoperatively in the ward. Sips of water on postoperative day



<span id="page-2-0"></span>**Figure 1.** Endoscopic indocyanine green injection. (**A**) Submucosal injection of indocyanine green at the day before surgery (**B**) Post-injection view.

2 were followed by clear liquid diet on postoperative day 3. Sof diet was allowed on the evening of postoperative day 3. The Clavien-Dindo classification was used to evaluate 30-day postoperative morbidity and mortality<sup>19</sup>.

**Surgical success.** In previous studies, it was considered a surgical failure if the following events were observed during the perioperative period<sup>[20,](#page-8-2)21</sup>. (1) conversion to laparoscopic or open surgery for any reasons, (2) harvesting an inadequate number of LNs (defned as <116), (3) positive resection margin, (4) 30-day major postoperative complications defined as grade III or higher according to the Clavien-Dindo classification<sup>19</sup>, or (5) outpatient complications leading to readmission. Any unplanned visit to the emergency department within 90 days afer index hospitalization was also regarded as readmission. A low occurrence of these events was considered a prerequisite for successful surgery, ensuring surgical and oncological safety.

**Propensity score matching.** Propensity score matching (PSM) analysis was performed to reduce potential selection bias with the following covariates: age, sex, American Society of Anesthesiologists (ASA) score, and body mass index (BMI). Individual propensity scores were calculated using a logistic regression model, and patients between the two groups were matched using the nearest-neighbor matching algorithm (ratio=r1:1 without replacement) with a caliper width of 0.1 standard deviation of the propensity score<sup>22</sup>. After PSM, 102 patients (51 patients each for IRDG and CLDG groups) were analyzed to compare surgical outcomes.

**Statistical analysis.** Data were analyzed using IBM SPSS version 23.0 (SPSS Inc., Chicago, IL, USA). Continuous variables were analyzed with paired t test. Chi square test or Fisher's exact test were performed for categorical variables. Statistical significance was defined as P-value  $<\!0.05.$ 

#### **Results**

**Patient demographics.** Table [1](#page-5-0) lists the clinicopathological characteristics of IRDG and CLDG groups before and afer PSM. Before PSM, IRDG group was younger than CLDG group (56.4 vs. 61.8 years; *P*=0.020). Afer PSM, matched group showed no signifcant diference in baseline characteristics.



<span id="page-3-0"></span>**Figure 2.** Reduced-port robotic gastrectomy. (**A**) Schematic illustration of reduced-port robotic distal gastrectomy using da Vinci Xi. (**B**) External view afer installation Figure 2A is produced by MID (Medical Illustration & Design), a part of the Medical Research Support Services of Yonsei University College of Medicine, which is available under the Creative Commons Attribution 4.0 International License. ([https://](https://creativecommons.org/licenses/by/4.0/) [creativecommons.org/licenses/by/4.0/\)](https://creativecommons.org/licenses/by/4.0/). DOF, degrees of freedom.

**Surgical outcomes.** As shown in Table [2,](#page-6-0) the mean operative time was longer in IRDG group than in CLDG group (before matching: 157.8 vs. 125.7 min; *P*<0.001, afer matching: 159.5 vs. 131.7 min; *P*<0.001). IRDG group was associated with a signifcantly less estimated blood loss (before matching: 32.4 vs. 68.2mL; P<0.001, after matching: 30.7 vs. 73.3 mL;  $P=0.004$ ) and higher mean number of retrieved LNs (before matching: 50.6 vs. 44.6 LNs; *P*=0.030, afer matching: 50.4 vs. 41.9 LNs; *P*=0.025) than CLDG group.

Changes in serum levels of C-reactive protein (CRP), amylase, and lipase were examined on postoperative days 0, 1, 3, and postoperative weeks 4. Serum levels of CRP were higher in IRDG group than in CLDG group on postoperative day 1 (before matching: 38.3 vs. 30.1mg/L; *P*=0.017, afer matching: 39.0 vs. 27.2mg/L; *P*=0.002). There were no differences in serum levels of amylase and lipase between the two groups. The amount of drainage was signifcantly less in IRDG group than in CLDG group on postoperative day 0 (before matching: 83.0



**Figure 3.** Fluorescence guided lymph node dissection. (**A**) Lymph nodes in white light. (**B**) fuorescence image visualizing lymph node.

<span id="page-4-0"></span>

<span id="page-4-1"></span>**Figure 4.** Surgical wound. A drain is inserted via right trocar site. Umbilicus was closed with subcuticular suture.

vs. 113.4 mL;  $P = 0.002$ , after matching: 87.3 vs. 110.1 mL;  $P = 0.045$ ). Visual analog scales at each postoperative period were not statistically diferent between the two groups.

The readmission rate was significantly lower in IRDG group than in CLDG group (after matching: 98.0 vs. 84.3%;  $P = 0.031$ ). The incidence of in-hospital and out-patient complications were similar between the two groups. There was no operative mortality either group within postoperative 30 days.

**Surgical success.** Surgical success rate was signifcantly higher in IRDG group compared to CLDG group, regardless of matching (Table [3,](#page-7-14) before matching: 98.2 vs. 89.5%; *P* = 0.046, afer matching: 98.0 vs. 82.4%; *P*=0.008). In IRDG group, surgical failure occurred in only one patient, who was readmitted due to complication identifed in outpatient clinic. Except for this one instance, there was no surgical failure in IRDG group regarding major complications, inadequate retrieved LNs (<16), conversion operation, or positive margin.

#### **Discussion**

To the best of our knowledge, this study is the first clinical outcome report of robotic surgery integrating Single-Site platform and Firefly technology for reduced-port surgery and fluorescence image-guided lymphadenectomy, respectively. The surgical outcomes following IRDG were notable to those of CLDG in terms of retrieved LNs, estimated blood loss, and readmission, but unfavorable in operation time. Other parameters, including complications, bowel recovery, drainage characteristics, and pain score, did not difer signifcantly

<span id="page-5-0"></span>

Table 1. Clinicopathological characteristics of patients. Data are expressed as mean  $\pm$  standard deviation or as number (percent). IRDG, integrated robotic distal gastrectomy; CLDG, conventional laparoscopic distal gastrectomy; BMI, body mass index; ASA, American Society of Anesthesiologists; SD, standard deviation. \* pT, depth of invasion. † pN, lymph node involvement. **‡** Stage, according to the 8th edition of the American Joint Committee on Cancer staging system for gastric cancer<sup>32</sup>.

between the two groups. However, regarding the proportion of patients with surgical success, IRDG showed a signifcantly higher success rate than CLDG.

The advantages of IRDG found in this study were higher number of retrieved LNs and less blood loss compared to CLDG. The number of retrieved LNs is considered a surrogate marker for long-term outcomes and intraoperative bleeding during gastrectomy is known to be related to the risk of tumor recurrence<sup>[23–](#page-8-5)[25](#page-8-6)</sup>. Therefore, the large number of retrieved LNs and low bleeding during surgery suggest that IRDG might be safely used in gastric cancer surgery in terms of oncological aspect. Intraoperative bleeding is also associated with the formation of peritoneal adhesion, which is related to equilibrium disturbance between coagulation and fibrinolysis $26.27$ . Even in the absence of previous serosal injury, intraoperative bleeding causes postoperative peritoneal adhesion, a major cause of postoperative complications. However, despite less intraoperative bleeding in robotic gastrectomy, previous studies have shown similar complication rates between conventional robotic and laparoscopic gastrectomy[28](#page-8-9),[29](#page-8-10). In this study, grade II or higher complication rates were lower in the IRDG group, while it was not statistically significant. Therefore, large-scale prospective study should be performed to confirm that reducing intraoperative blood loss in IRDG may improve postoperative morbidity.

Shortcomings of IRDG found in this study were relatively longer operation time and CRP elevation. Because longer operation time is a common drawback of robot surgery<sup>[30,](#page-8-11)31</sup>, operation time of this study is acceptable. However, CRP level was higher on postoperative day 1 compared to CLDG group. It implies that less invasive surgery through less port site is not efective enough to compensate for longer operation time yet. Tis study compared the initial experience of IRDG to that of fully optimized CLDG. The learning effect and optimization of IRDG procedures might improve operation time and associated CRP levels.

Surgical success defned in this study was adapted to compare surgical quality following procedures of robot and laparoscopy $20,21$  $20,21$  $20,21$ . Since robotic and laparoscopic surgery belong to the same area of minimally invasive surgery, providing surgical benefts that signifcantly surpass the laparoscopic surgery is a big hurdle for robotic surgery. Tus, collective terminology of surgical success was used to combine the rare unfavorable events in diferent domains into single parameter. Individual events related with surgical quality, such as complications and inadequate LN retrieval may be insufficient to show significant differences since the number of individual events

<span id="page-6-0"></span>

**Table 2.** Comparison of perioperative surgical outcomes. Data are expressed as mean  $\pm$  standard deviation or as number (percent). IRDG, integrated robotic distal gastrectomy; CLDG, conventional laparoscopic distal gastrectomy; SD, standard deviation; POD, postoperative day; W, week; CRP, C-reactive protein; PACU, post anesthesia care unit. \* Intra-abdominal fuid collection, aferent loop syndrome, omental infarction. **†** Internal herniation. **‡** Intra-abdominal fuid collection in two patients, aferent loop syndrome, omental infarction, and internal herniation. **§** Duodenal stump leakage.

is very rare. As a combined parameter, surgical success might be efective for comparing the surgical quality of robotic and laparoscopic surgery in this study.

There were several limitations in this study. Due to the retrospective nature of the study, there was a risk of bias in the selection of the patient, even though the patients were matched to balance the two groups.In addition, although IRDG showed some advantages over CLDG in surgical outcomes, which factors, among robot, fuorescence imaging, and reduced-port, contribute to favorable surgical outcomes is still elusive. Therefore, analyzing

<span id="page-7-14"></span>

**Table 3.** Comparison of surgical success. Data are expressed as number (percent). IRDG, integrated robotic distal gastrectomy; CLDG, conventional laparoscopic distal gastrectomy; LN, lymph.

three factors and comparing them one by one may help determine the contribution of each factor. In addition, there were no results for scar assessment, such as satisfaction for surgical wound or body image. Currently, there has been no study evaluating patient aesthetic satisfaction or quality of life after undergoing reduced-port gastrectomy. Improved aesthetic result or quality of life could be potential benefts of reduced-port gastrectomy. Ongoing prospective study will provide more information on integrated surgery (NCT03396354).

In conclusion, IRDG using the Single-Site platform and fluorescence image-guided lymphadenectomy appears to provide potential benefts in surgical outcomes compared to CLDG for patients with early gastric cancer, relating to retrieved LNs, intraoperative bleeding, readmission, and surgical success.

#### **Data availability**

The datasets generated during and/or analyzed during the current study are available from the corresponding author on reasonable request.

Received: 1 February 2019; Accepted: 30 December 2019; Published online: 16 January 2020

#### **References**

- <span id="page-7-0"></span>1. Antonakis, P. T., Ashrafan, H. & Isla, A. M. Laparoscopic gastric surgery for cancer: where do we stand? *World J. Gastroenterol.* **20**, 14280–14291, <https://doi.org/10.3748/wjg.v20.i39.14280>(2014).
- <span id="page-7-1"></span>2. Kim, H. H. *et al*. Morbidity and mortality of laparoscopic gastrectomy versus open gastrectomy for gastric cancer: an interim report–a phase III multicenter, prospective, randomized Trial (KLASS Trial). *Ann. Surg.* **251**, 417–420, [https://doi.org/10.1097/](https://doi.org/10.1097/SLA.0b013e3181cc8f6b) [SLA.0b013e3181cc8f6b](https://doi.org/10.1097/SLA.0b013e3181cc8f6b) (2010).
- 3. Kim, Y. W. *et al*. Long-term outcomes of laparoscopy-assisted distal gastrectomy for early gastric cancer: result of a randomized controlled trial (COACT 0301). *Surg. Endosc.* **27**, 4267–4276,<https://doi.org/10.1007/s00464-013-3037-x>(2013).
- <span id="page-7-2"></span>4. Takiguchi, S. *et al*. Laparoscopy-assisted distal gastrectomy versus open distal gastrectomy. A prospective randomized single-blind study. *World J. Surg.* **37**, 2379–2386,<https://doi.org/10.1007/s00268-013-2121-7>(2013).
- <span id="page-7-3"></span>5. Woo, Y. *et al*. Robotic gastrectomy as an oncologically sound alternative to laparoscopic resections for the treatment of early-stage gastric cancers. *Arch. Surg.* **146**, 1086–1092, <https://doi.org/10.1001/archsurg.2011.114> (2011).
- <span id="page-7-4"></span>6. Marano, A. *et al*. Robotic versus Laparoscopic versus Open Gastrectomy: A Meta-Analysis. *J. Gastric Cancer* **13**, 136–148, [https://](https://doi.org/10.5230/jgc.2013.13.3.136) [doi.org/10.5230/jgc.2013.13.3.136](https://doi.org/10.5230/jgc.2013.13.3.136) (2013).
- 7. Kim, H. I. *et al*. Multicenter Prospective Comparative Study of Robotic Versus Laparoscopic Gastrectomy for Gastric Adenocarcinoma. *Ann. Surg.* **263**, 103–109,<https://doi.org/10.1097/SLA.0000000000001249> (2016).
- 8. Hong, S. S. *et al*. Can Robotic Gastrectomy Surpass Laparoscopic Gastrectomy by Acquiring Long-Term Experience? A Propensity Score Analysis of a 7-Year Experience at a Single Institution. *J. Gastric Cancer* **16**, 240–246,<https://doi.org/10.5230/jgc.2016.16.4.240>  $(2016)$
- <span id="page-7-5"></span>9. Cianchi, F. *et al*. Robotic vs laparoscopic distal gastrectomy with D2 lymphadenectomy for gastric cancer: a retrospective comparative mono-institutional study. *BMC Surg.* **16**, 65,<https://doi.org/10.1186/s12893-016-0180-z>(2016).
- <span id="page-7-6"></span>10. Angus, A. A., Sahi, S. L. & McIntosh, B. B. Learning curve and early clinical outcomes for a robotic surgery novice performing robotic single site cholecystectomy. *Int. J. Med. Robot. + computer Assist. surgery: MRCAS* **10**, 203–207, [https://doi.org/10.1002/](https://doi.org/10.1002/rcs.1540) [rcs.1540](https://doi.org/10.1002/rcs.1540) (2014).
- <span id="page-7-7"></span>11. Bae, S. U., Jeong, W. K., Bae, O. S. & Baek, S. K. Reduced-port robotic anterior resection for lef-sided colon cancer using the Da Vinci single-site platform. *Te international journal of medical robotics + computer assisted surgery: MRCAS*, [https://doi.org/10.1002/](https://doi.org/10.1002/rcs.1677) [rcs.1677](https://doi.org/10.1002/rcs.1677) (2015).
- <span id="page-7-8"></span>12. Hachey, K. J. *et al*. Safety and feasibility of near-infrared image-guided lymphatic mapping of regional lymph nodes in esophageal cancer. *J. Torac. Cardiovasc. Surg.* **152**, 546–554, <https://doi.org/10.1016/j.jtcvs.2016.04.025> (2016).
- <span id="page-7-9"></span>13. Lee, S. *et al*. Safety and feasibility of reduced-port robotic distal gastrectomy for gastric cancer: a phase I/II clinical trial. *Surg. Endosc.* **31**, 4002–4009,<https://doi.org/10.1007/s00464-017-5435-y>(2017).
- <span id="page-7-10"></span>14. Kwon, I. G., Son, T., Kim, H. I. & Hyung, W. J. Fluorescent lymphography-guided lymphadenectomy during robotic radical gastrectomy for gastric cancer. *JAMA Surg.* **154**, 150–158,<https://doi.org/10.1001/jamasurg.2018.4267> (2019).
- <span id="page-7-11"></span>15. Lee, J. H. *et al*. Clinical practice guidelines for gastric cancer in Korea: an evidence-based approach. *J. Gastric Cancer* **14**, 87–104, <https://doi.org/10.5230/jgc.2014.14.2.87>(2014).
- <span id="page-7-12"></span>16. Japanese Gastric Cancer. A. Japanese gastric cancer treatment guidelines 2014 (ver. 4). *Gastric Cancer* **20**, 1–19, [https://doi.](https://doi.org/10.1007/s10120-016-0622-4) [org/10.1007/s10120-016-0622-4](https://doi.org/10.1007/s10120-016-0622-4) (2017).
- <span id="page-7-13"></span>17. Hyung, W. J., Song, C., Cheong, J. H., Choi, S. H. & Noh, S. H. Factors infuencing operation time of laparoscopy-assisted distal subtotal gastrectomy: analysis of consecutive 100 initial cases. *Eur. J. surgical oncology: J. Eur. Soc. Surgical Oncol. Br. Assoc. Surgical Oncol.* **33**, 314–319, <https://doi.org/10.1016/j.ejso.2006.11.010>(2007).
- <span id="page-8-0"></span>18. Song, J. *et al*. Recurrence following laparoscopy-assisted gastrectomy for gastric cancer: a multicenter retrospective analysis of 1,417 patients. *Ann. Surg. Oncol.* **17**, 1777–1786,<https://doi.org/10.1245/s10434-010-0932-4> (2010).
- <span id="page-8-1"></span>19. Dindo, D., Demartines, N. & Clavien, P. A. Classifcation of surgical complications: a new proposal with evaluation in a cohort of 6336 patients and results of a survey. *Ann. Surg.* **240**, 205–213,<https://doi.org/10.1097/01.sla.0000133083.54934.ae>(2004).
- <span id="page-8-2"></span>20. Kim, H. I., Park, M. S., Song, K. J., Woo, Y. & Hyung, W. J. Rapid and safe learning of robotic gastrectomy for gastric cancer: multidimensional analysis in a comparison with laparoscopic gastrectomy. *Eur. J. surgical oncology: J. Eur. Soc. Surgical Oncol. Br. Assoc. Surgical Oncol.* **40**, 1346–1354, <https://doi.org/10.1016/j.ejso.2013.09.011>(2014).
- <span id="page-8-3"></span>21. Yang, S. Y. *et al*. Surgical Outcomes Afer Open, Laparoscopic, and Robotic Gastrectomy for Gastric Cancer. *Ann. Surg. Oncol.* **24**, 1770–1777, <https://doi.org/10.1245/s10434-017-5851-1> (2017).
- <span id="page-8-4"></span>22. Agoritsas, T., Merglen, A., Shah, N. D., O'Donnell, M. & Guyatt, G. H. Adjusted Analyses in Studies Addressing Therapy and Harm: Users' Guides to the Medical Literature. *JAMA* **317**, 748–759,<https://doi.org/10.1001/jama.2016.20029>(2017).
- <span id="page-8-5"></span>23. Kamei, T., Kitayama, J., Yamashita, H. & Nagawa, H. Intraoperative blood loss is a critical risk factor for peritoneal recurrence afer curative resection of advanced gastric cancer. *World J. Surg.* **33**, 1240–1246,<https://doi.org/10.1007/s00268-009-9979-4> (2009).
- 24. Liang, Y. X. *et al*. Impact of intraoperative blood loss on survival afer curative resection for gastric cancer. *World J. Gastroenterol.* **19**, 5542–5550, <https://doi.org/10.3748/wjg.v19.i33.5542>(2013).
- <span id="page-8-6"></span>25. Arita, T. *et al*. Increase in peritoneal recurrence induced by intraoperative hemorrhage in gastrectomy. *Ann. Surg. Oncol.* **22**, 758–764,<https://doi.org/10.1245/s10434-014-4060-4> (2015).
- <span id="page-8-7"></span>26. Ryan, G. B., Grobety, J. & Majno, G. Postoperative peritoneal adhesions. A study of the mechanisms. *Am. J. Pathol.* **65**, 117–148 (1971).
- <span id="page-8-8"></span>27. Maciver, A. H., McCall, M. & James Shapiro, A. M. Intra-abdominal adhesions: cellular mechanisms and strategies for prevention. *Int. J. Surg.* **9**, 589–594,<https://doi.org/10.1016/j.ijsu.2011.08.008>(2011).
- <span id="page-8-9"></span>28. Shen, W. *et al*. Robotic versus laparoscopic gastrectomy for gastric cancer: comparison of short-term surgical outcomes. *Surg Endosc*, <https://doi.org/10.1007/s00464-015-4241-7> (2015).
- <span id="page-8-10"></span>29. Lee, J. *et al*. Robotic distal subtotal gastrectomy with D2 lymphadenectomy for gastric cancer patients with high body mass index: comparison with conventional laparoscopic distal subtotal gastrectomy with D2 lymphadenectomy. *Surg. Endosc.* **29**, 3251–3260, <https://doi.org/10.1007/s00464-015-4069-1> (2015).
- <span id="page-8-11"></span>30. Shen, W. S., Xi, H. Q., Chen, L. & Wei, B. A meta-analysis of robotic versus laparoscopic gastrectomy for gastric cancer. *Surg. Endosc.* **28**, 2795–2802,<https://doi.org/10.1007/s00464-014-3547-1> (2014).
- <span id="page-8-12"></span>31. Suda, K. *et al*. Potential advantages of robotic radical gastrectomy for gastric adenocarcinoma in comparison with conventional laparoscopic approach: a single institutional retrospective comparative cohort study. *Surg. Endosc.* **29**, 673–685, [https://doi.](https://doi.org/10.1007/s00464-014-3718-0) [org/10.1007/s00464-014-3718-0](https://doi.org/10.1007/s00464-014-3718-0) (2015).
- <span id="page-8-13"></span>32. Amin, M. B. *et al*. AJCC cancer staging manual. 8th ed. New York: Springer International Publishing (2017).

#### **Acknowledgements**

The authors would like to thank MID (Medical Illustration & Design), a part of the Medical Research Support Services of Yonsei University College of Medicine, for all artistic support related to this work. Tis work was supported by grant from a National Research Foundation of Korea (NRF) funded by the Korean government (MSIP) (No. 2016R1A2B4014984). Te auhors thank BioScience Writers ([https://www.biosciencewriters.com\)](https://www.biosciencewriters.com) for English language editing.

#### **Author contributions**

C.K. Roh and H.I. Kim designed and developed the protocol. S. Choi, W.J. Seo and M. Cho acquired the data. Y.Y. Choi, T. Son, W.J. Hyung, and H.I. Kim contributed to the administrative, technical or material support. All authors wrote and reviewed the manuscript.

#### **Competing interests**

H.I. Kim was funded by the grant from a National Research Foundation of Korea (NRF). The authors declare no other competing interests.

#### **Additional information**

**Correspondence** and requests for materials should be addressed to H.-I.K.

**Reprints and permissions information** is available at [www.nature.com/reprints.](http://www.nature.com/reprints)

**Publisher's note** Springer Nature remains neutral with regard to jurisdictional claims in published maps and institutional afliations.

**Open Access** This article is licensed under a Creative Commons Attribution 4.0 International  $\odot$ License, which permits use, sharing, adaptation, distribution and reproduction in any medium or format, as long as you give appropriate credit to the original author(s) and the source, provide a link to the Creative Commons license, and indicate if changes were made. The images or other third party material in this article are included in the article's Creative Commons license, unless indicated otherwise in a credit line to the material. If material is not included in the article's Creative Commons license and your intended use is not permitted by statutory regulation or exceeds the permitted use, you will need to obtain permission directly from the copyright holder. To view a copy of this license, visit [http://creativecommons.org/licenses/by/4.0/.](http://creativecommons.org/licenses/by/4.0/)

© The Author(s) 2020