Sphere-valued harmonic maps with surface energy and the K_{13} problem

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Abstract

We consider an energy functional motivated by the celebrated K_{13} problem in the Oseen-Frank theory of nematic liquid crystals. It is defined for spherevalued functions and appears as the usual Dirichlet energy with an additional surface term.

It is known that this energy is unbounded from below and our aim has been to study the local minimizers. We show that even having a critical point in a suitable energy space imposes severe restrictions on the boundary conditions. Having suitable boundary conditions makes the energy functional bounded and in this case we study the partial regularity of the global minimizers.

1 Introduction

In this paper we study critical points of the following energy functional

$$\mathbb{E}[n] = \int_{\Omega} \frac{K}{2} |\nabla n|^2 \, dx + \tilde{K}_{13} \int_{\partial \Omega} ((n \cdot \nabla)n) \cdot \nu \, d\sigma \tag{1.1}$$

for maps $n: \Omega \subset \mathbb{R}^d \to \mathbb{R}^d$ with |n(x)| = 1 a.e. in $\overline{\Omega}$ where

$$K > 0, \tilde{K}_{13} \in \mathbb{R}$$

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and $\Omega \subset \mathbb{R}^d$ with $d \in \{2, 3\}$ is a C^2 domain and ν denotes the exterior unit-normal.

This functional is motivated by the K_{13} problem in the Oseen-Frank theory of liquid crystals. More details about the physical relevance of this problem are provided in the next subsection, Section 1.1.

It has been known since 1985 thanks to the work of C. Oldano and G. Barbero [14] that there exists a domain $\Omega \subset \mathbb{R}^3$ and a sequence $\{n_k\}_{k \in \mathbb{N}} \subset C^{\infty}(\Omega; \mathbb{S}^2)$ such that $\mathbb{E}[n_k] \to -\infty$ as $k \to \infty$. Thus one cannot understand the physical meaning of the energy in the standard way, i.e. from the point of view of global energy minimizers. However it is conceivable that the energy might still have nontrivial local energy-minimizers and this has been the starting point of this work.

A first question is then to understand what is the space in which to look for local minimizers. In order to understand this one can start by noting that for $n \in C^2(\Omega, \mathbb{S}^{d-1})$ an integration by parts allows to rewrite the energy as:

$$\mathbb{E}[n] = \int_{\Omega} \frac{K}{2} |\nabla n|^2 \, dx + \tilde{K}_{13} \int_{\Omega} \sum_{\alpha,\beta=1}^d \left(\frac{\partial n_\alpha}{\partial x_\beta} \frac{\partial n_\beta}{\partial x_\alpha} + n_\beta \frac{\partial^2 n_\alpha}{\partial x_\alpha \partial x_\beta} \right) \, dx$$

A minimal requirement for the functional space is that the energy makes sense for functions in it. Thus a natural choice is:

$$\mathscr{A} := W^{1,2}(\Omega; \mathbb{S}^{d-1}) \cap W^{2,1}(\Omega; \mathbb{S}^{d-1})$$

$$(1.2)$$

In this space one can consider various boundary conditions, which would make the space smaller. However we surprisingly have that there are severe constraints on what the boundary conditions could be:

THEOREM 1.1. Let $\Omega \subset \mathbb{R}^d$, d = 2, 3 be an open bounded set with C^1 boundary and with unit-norm exterior normal denoted ν . Consider the energy \mathbb{E} as defined in (1.1).

Let \bar{n} be a critical point of \mathbb{E} in the functional space \mathscr{A} defined in (1.2). Then we have

$$\bar{n}(x) \cdot \nu(x) \in \{0, \pm 1\}, \text{ for almost all } x \in \partial \Omega$$
 (1.3)

The most interesting case is the one when $\bar{n}(x) \cdot \nu(x) = 0$ for almost all $x \in \partial \Omega$ and in dimension d = 3 as this allows for a certain level of freedom at the boundary. Then one can show that the energy \mathbb{E} reduces to:

$$\mathbb{G}[n] := \int_{\Omega} K \sum_{\alpha,\beta=1}^{3} \frac{\partial n_{\alpha}}{\partial x_{\beta}} \frac{\partial n_{\alpha}}{\partial x_{\beta}} - \tilde{K}_{13} \int_{\partial \Omega} \sum_{\alpha,\beta=1}^{3} \frac{\partial \nu_{\beta}}{\partial x_{\alpha}} n_{\beta} n_{\alpha}.$$
(1.4)

This energy makes sense in the large functional space $W^{1,2}(\Omega, \mathbb{S}^2)$ and it is easily shown to be bounded from below and lower semicontinuous. Thus one can now consider minimizing \mathbb{G} over the function space of $W^{1,2}$ functions with tangential boundary conditions:

$$\mathcal{U} := \{ u \in W^{1,2}(\Omega, \mathbb{S}^2) : \operatorname{Trace}(u) \in \mathcal{T} \}$$
(1.5)

where

 $\mathcal{T} := \{ \gamma \in H^{\frac{1}{2}}(\partial\Omega, \mathbb{S}^2) : \gamma(x) \cdot \nu(x) = 0 \text{ for almost every } x \in \partial\Omega \}.$ (1.6)

A first issue to consider is wether or not this functional space is non-empty as the topological constraint might make it empty, as shown by the *"Hairy Ball" Theorem.* Fortunately in our case the regularity at the boundary is weaker than continuous and we have:

PROPOSITION 1.2. Let Ω be a bounded C^2 domain in \mathbb{R}^3 . Then the space \mathcal{U} defined in (1.5) is non-empty.

Standard arguments provide the existence of a global minimizer. In general this minimizer might not be continuous at the boundary for topological reasons (think of the example of the "Hairy Ball" theorem). It is then of interest to look into the matter of partial regularity for the global minimizers of \mathbb{G} in the space \mathcal{U} . This is related to the works of R. Hardt and F. Lin in [7] and later that of Scheven [15] who considered partially constrained boundary conditions, though only for the Dirichlet functionals. We look into this through a method combining the two approaches in the works mentioned above and taking into account the effect of the surface energy. We can thus show:

THEOREM 1.3. Let $\Omega \subset \mathbb{R}^3$ be a C^2 domain. Then a global energy minimizer of the energy \mathbb{G} (defined in (1.4)) in the space (1.5) is continuous on $\overline{\Omega} \setminus Z$ where Z is a set of one-dimensional Hausdorff measure equal to zero.

The paper is organized as follows: in the next section physical background is provided, to be followed in Section 2 by the example of Barbero and Oldano showing the unboundedness of the energy functional, and then the proof of Theorem 1.1. In the last part, Section 3, we prove Proposition 1.2 and then Theorem 1.3. The appendices contain a number of technical lemmas and the list of notations.

1.1 Physical motivation

Nematic liquid crystals are the simplest yet the most used type of liquid crystals, with wide-ranging applications, particularly in displays. The simplest and most comprehensive model used for describing the stationary patterns is related to the Oseen-Frank energy (see for instance [21]) :

$$\mathbb{E}_{OF}[n] = \int_{\Omega} K_1 |\nabla \cdot n|^2 + K_2 |n \cdot (\nabla \times n)|^2 + K_3 |n \times (\nabla \times n)|^2 dx \qquad (1.7)$$
$$+ \int (K_2 + K_{24}) (\operatorname{tr}(\nabla n)^2 - (\nabla \cdot n)^2) + K_{13} \nabla \cdot ((\nabla \cdot n)n) dx$$

$$-\int_{\Omega} (K_2 + K_{24}) (\operatorname{tr}(\nabla n)^2 - (\nabla \cdot n)^2) + K_{13} \nabla \cdot ((\nabla \cdot n)n) \, dx$$
(1.8)

where the vector n is unit-length. Using the identity, valid for $n \in C^1(\Omega; \mathbb{S}^2)$:

$$\operatorname{tr}(\nabla n)^2 + |n \cdot (\nabla \times n)|^2 + |n \times (\nabla \times n)|^2 = |\nabla n|^2$$

we have that for "equal elastic constants" $K_1 = K_2 = K_3$ the Oseen-Frank energy reduces to

$$\tilde{\mathbb{E}}_{OF}[n] = \int_{\Omega} K_2 |\nabla n|^2 + K_{24}(\operatorname{tr}(\nabla n)^2 - (\nabla \cdot n)^2) + K_{13} \nabla \cdot ((\nabla \cdot n)n) \, dx$$

The K_{24} term is a null-Lagrangian as we have (see for instance [21],[1]):

$$\int_{\Omega} K_{24}(\operatorname{tr}(\nabla n)^2 - (\nabla \cdot n)^2) \, dx = \int_{\Omega} \nabla \cdot ((n \cdot \nabla)n - (\nabla \cdot n)n) \, dx$$
$$= \int_{\partial \Omega} \left[(n \cdot \nabla)n - (\nabla \cdot n)n \right] \cdot \nu \, d\sigma = \int_{\partial \Omega} D_t n : n \otimes \nu - \operatorname{tr}(D_t n)n \cdot \nu \, d\sigma$$

where $D_t n := \nabla n - \nu \otimes \frac{\partial n}{\partial \nu}$ is a differential operator that involves only tangential derivatives, thus its value depends only on the boundary conditions.

The K_{13} term is different as it can be expressed as a surface integral, but the surface integral *does not depend only on tangential derivatives*. However, we can remove the tangential contribution to the K_{13} term as follows:

$$K_{24}(\operatorname{tr}(\nabla n)^{2} - (\nabla \cdot n)^{2}) + K_{13}\nabla \cdot ((\nabla \cdot n)n) = (K_{24} - K_{13})(\operatorname{tr}(\nabla n)^{2} - (\nabla \cdot n)^{2}) + K_{13}(\operatorname{tr}(\nabla n)^{2} - (\nabla \cdot n)^{2}) + K_{13}\nabla \cdot ((\nabla \cdot n)n) = \tilde{K}_{24}(\operatorname{tr}(\nabla n)^{2} - (\nabla \cdot n)^{2}) + K_{13}\nabla \cdot ((n \cdot \nabla)n)$$
(1.9)

thus the energy \mathbb{E} that we consider in (1.1) contains the essential terms capturing the difficulty of the physical K_{13} problem namely that the energy is unbounded from below. The results we obtain in the next section are relevant to the full physical Oseen-Frank energy, with suitable adaptations.

2 Constraints on the boundary conditions

2.1 The unboundedness of the energy functional

We show now, by following the example provided in E.Virga's book [21] and inspired by [14] that the energy \mathbb{E} can become unbounded from below, so no global minimizers can exist. Let Ω be the domain in \mathbb{R}^3 given by $\Omega := \{(x, y, z) : x, y \in (0, l), z \in (-d, +d)\}$ and consider the functions $n_{\varepsilon}(x, y, z) := (\cos(\rho_{\varepsilon}(z)), 0, \sin(\rho_{\varepsilon}(z)))$ with $\rho_{\varepsilon}(z)$ given by:

$$\rho_{\varepsilon}(z) := \begin{cases} \rho_0 + \varepsilon - \frac{1}{\varepsilon^3} (z - d + \varepsilon^2)^2 & \text{if } z \in [d - \varepsilon^2, d], \\ \rho_0 + \varepsilon & \text{if } z \in (-d + \varepsilon^2, d - \varepsilon^2), \\ \rho_0 + \varepsilon - \frac{1}{\varepsilon^3} (z + d - \varepsilon^2)^2 & \text{if } z \in [-d, -d + \varepsilon^2]. \end{cases}$$

A calculation gives that $n_{\varepsilon} \in \mathscr{A}$ and

$$\mathbb{E}[n_{\varepsilon}] := 4l^2 \left(\frac{K}{3} - K_{13} \frac{\sin(2\rho_0)}{2\varepsilon}\right).$$

Therefore if we choose ρ_0 such that $\sin(\rho_0) > 0$ then we get

$$\mathbb{E}[n_{\varepsilon}] \to -\infty$$

proving that \mathbb{E} is unbounded from below in the function space \mathscr{A} (for this specific domain Ω).

2.2 Critical points

Theorem 1.1 is proved by studying the first variations of the energy \mathbb{E} in \mathscr{A} . First we will prove some lemmas; note that in Lemma 2.1 it is important that we are working with $\bar{n} \in W^{2,1}(\Omega, \mathbb{S}^2)$ (hence $-\Delta \bar{n} - \bar{n} |\nabla \bar{n}|^2 \in L^1(\Omega)$).

LEMMA 2.1. Let \bar{n} be a critical point of the energy \mathbb{E} in the function space \mathscr{A} . Then \bar{n} satisfies the equation

$$\sum_{\alpha,\beta,\gamma=1}^{d} \int_{\partial\Omega} \left(\varphi_{\beta,\alpha} \bar{n}_{\alpha} - \varphi_{\gamma,\alpha} \bar{n}_{\gamma} \bar{n}_{\alpha} \bar{n}_{\beta} \right) \nu_{\beta} dS = 0$$

for all $\varphi \in C^{\infty}(\overline{\Omega}, \mathbb{R}^3)$ such that $\varphi = 0$ on $\partial\Omega$.

Proof. Let \bar{n} be a critical point of \mathbb{E} in \mathscr{A} . First, let $\psi \in C_c^{\infty}(\Omega, \mathbb{R}^3)$ and set $\bar{n}^{\varepsilon} := \frac{\bar{n} + \varepsilon \psi}{|\bar{n} + \varepsilon \psi|}$, then $\bar{n}_{\alpha}^{\varepsilon} = \bar{n}_{\alpha} + \varepsilon (\psi_{\alpha} - \bar{n}_{\alpha} \bar{n}_{\beta} \psi_{\beta}) + O(\varepsilon^2)$ as $\varepsilon \to 0$ and a standard calculation gives

$$\frac{d}{d\varepsilon} \mathbb{E}[\bar{n}^{\varepsilon}]\Big|_{\varepsilon=0} = K \int_{\Omega} \nabla \bar{n} \cdot \nabla \psi - |\nabla \bar{n}|^2 n \cdot \psi dx = 0.$$

We now use the fact that $\bar{n} \in W^{2,1}(\Omega, \mathbb{S}^2)$ to perform an integration by parts, giving

$$\frac{d}{d\varepsilon}\mathbb{E}[\bar{n}^{\varepsilon}]\Big|_{\varepsilon=0} = K \int_{\Omega} \left(-\Delta \bar{n} - |\nabla \bar{n}|^2 \bar{n}\right) \cdot \psi dx = 0.$$

As ψ can be chosen arbitrarily and $-\Delta \bar{n} - \bar{n} |\nabla \bar{n}|^2 \in L^1(\Omega)$, for variations in the interior of Ω we obtain the harmonic map equation for maps into spheres: $\Delta \bar{n} + |\nabla \bar{n}|^2 \bar{n} = 0$ holding almost everywhere.

Next, let $\varphi \in C^{\infty}(\bar{\Omega}, \mathbb{R}^3)$ such that $\varphi = 0$ on $\partial\Omega$ and set $\bar{n}^{\varepsilon} = \frac{\bar{n} + \varepsilon \varphi}{|\bar{n} + \varepsilon \varphi|}$. Recalling that we have $\bar{n}^{\varepsilon}_{\alpha} = \bar{n}_{\alpha} + \varepsilon(\varphi_{\alpha} - \bar{n}_{\alpha}\bar{n}_{\beta}\varphi_{\beta}) + O(\varepsilon^2)$ we obtain on the boundary the following:

$$\begin{aligned} \frac{d}{d\varepsilon}\Big|_{\varepsilon=0}\nu_{\beta}\left(\bar{n}_{\alpha}^{\varepsilon}\partial_{\alpha}\bar{n}_{\beta}^{\varepsilon}\right) &= \nu_{\beta}\left(\left(\varphi_{\alpha}-\bar{n}_{\alpha}\bar{n}_{\beta}\varphi_{\beta}\right)\partial_{\alpha}\bar{n}_{\beta}+\bar{n}_{\alpha}\partial_{\alpha}\left(\varphi_{\beta}-\bar{n}_{\beta}\bar{n}_{\gamma}\varphi_{\gamma}\right)\right) \\ &= \nu_{\beta}\left(\varphi_{\alpha}\partial_{\alpha}\bar{n}_{\beta}+\bar{n}_{\alpha}\partial_{\alpha}\varphi_{\beta}-\bar{n}_{\alpha}\partial_{\alpha}\left(\bar{n}_{\beta}\bar{n}_{\gamma}\right)\varphi_{\gamma}-\bar{n}_{\alpha}\bar{n}_{\beta}\bar{n}_{\gamma}\partial_{\alpha}\varphi_{\gamma}\right) \\ &= \nu_{\beta}\left(+\bar{n}_{\alpha}\partial_{\alpha}\varphi_{\beta}-\bar{n}_{\alpha}\bar{n}_{\beta}\bar{n}_{\gamma}\partial_{\alpha}\varphi_{\gamma}+\varphi_{\alpha}\left(\partial_{\alpha}\bar{n}_{\beta}-\bar{n}_{\sigma}\partial_{\sigma}\left(\bar{n}_{\beta}\bar{n}_{\alpha}\right)\right)\right) \\ &= \nu_{\beta}\left(+\bar{n}_{\alpha}\partial_{\alpha}\varphi_{\beta}-\bar{n}_{\alpha}\bar{n}_{\beta}\bar{n}_{\gamma}\partial_{\alpha}\varphi_{\gamma}\right)\end{aligned}$$

where for the second equality we used that |n| = 1 hence $n_{\beta}\partial_{\alpha}n_{\beta} = 0$. For the last equality we used that φ is zero on the boundary.

Using the last calculation we get:

$$\begin{split} \frac{d}{d\varepsilon} \mathbb{E}[\bar{n}^{\varepsilon}]\Big|_{\varepsilon=0} &= K \int_{\Omega} \nabla \bar{n} \cdot \nabla \varphi - |\nabla \bar{n}|^2 \bar{n} \cdot \varphi dx + K_{13} \sum_{\alpha,\beta,\gamma=1}^d \int_{\partial \Omega} \left(\varphi_{\beta,\alpha} \bar{n}_{\alpha} - \varphi_{\gamma,\alpha} \bar{n}_{\gamma} \bar{n}_{\alpha} \bar{n}_{\beta}\right) \nu_{\beta} dS \\ &= K \int_{\Omega} \left(-\Delta \bar{n} - |\nabla \bar{n}|^2 \bar{n}\right) \cdot \varphi dx + K_{13} \sum_{\alpha,\beta,\gamma=1}^d \int_{\partial \Omega} \left(\varphi_{\beta,\alpha} \bar{n}_{\alpha} - \varphi_{\gamma,\alpha} \bar{n}_{\gamma} \bar{n}_{\alpha} \bar{n}_{\beta}\right) \nu_{\beta} dS \\ &= K_{13} \sum_{\alpha,\beta,\gamma=1}^d \int_{\partial \Omega} \left(\varphi_{\beta,\alpha} \bar{n}_{\alpha} - \varphi_{\gamma,\alpha} \bar{n}_{\gamma} \bar{n}_{\alpha} \bar{n}_{\beta}\right) \nu_{\beta} dS, \end{split}$$

which proves the lemma (note that in passing from the first to second line we used that $\varphi = 0$ on the boundary, and from the second to third that $-\Delta \bar{n} - \bar{n} |\nabla \bar{n}|^2 = 0$).

We now prove an analogue of the fundamental lemma of the Calculus of Variations.

LEMMA 2.2. Let $d \in \{2,3\}$, $\Omega \subset \mathbb{R}^d$ be a C^1 domain and $g \in L^{\infty}(\partial\Omega, \mathbb{R})$. Suppose that

$$\int_{\partial\Omega} \frac{\partial\varphi}{\partial\nu} g(x) dS(x) = 0$$
(2.1)

for all $\varphi \in C^{\infty}(\overline{\Omega}, \mathbb{R})$ such that $\varphi|_{\partial\Omega} = 0$, where $\nu(x)$ is the unit norm to $\partial\Omega$ at x. Then

g(x) = 0

for almost all points $x \in \partial \Omega$.

Proof. We prove for the case d = 3, the case d = 2 is a simpler version. Let $x_0 \in \partial \Omega$ be an arbitrary Lebesgue point of g and let $\psi : (-\varepsilon, \varepsilon)^2 \to \partial \Omega$ be a coordinate patch such that $\psi(0,0) = x_0$. If we choose $\varepsilon > 0$ sufficiently small then the map

$$\begin{aligned} H: [0,\varepsilon) \times (-\varepsilon,\varepsilon) \times (-\varepsilon,\varepsilon) &\to \Omega\\ (r,s,t) &\to [\psi(s,t) - r\nu(s,t)] \end{aligned}$$

(where $\nu(s,t) = \frac{\psi_s \times \psi_t}{\|\psi_s \times \psi_t\|}$ is the unit normal to $\partial\Omega$ at $\psi(s,t)$) provides a C^1 homeomorphism from $(0,\varepsilon) \times (-\varepsilon,\varepsilon) \times (-\varepsilon,\varepsilon)$ onto a relative neighbourhood $U := H([0,\varepsilon) \times (-\varepsilon,\varepsilon) \times (-\varepsilon,\varepsilon))$ of x_0 . For $\delta > 0$ small define the maps

$$\varphi_{\delta}(x) = \begin{cases} 0 & \text{if } x \notin U \\ \left(\frac{\varepsilon}{2\delta}\right)^2 \gamma\left(r, \frac{s\varepsilon}{2\delta}, \frac{t\varepsilon}{2\delta}\right) & \text{if } x \in U, \text{ where } x = \psi(s, t) - r\nu(s, t). \end{cases}$$

where

$$\gamma: [0,\varepsilon) \times (-\varepsilon,\varepsilon) \times (-\varepsilon,\varepsilon) \to \mathbb{R}$$

is smooth and 0 if $(r, s, t) \notin [0, \frac{\varepsilon}{2}) \times \left(-\frac{\varepsilon}{2}, \frac{\varepsilon}{2}\right) \times \left(-\frac{\varepsilon}{2}, \frac{\varepsilon}{2}\right)$. Then we have

$$\int_{\partial\Omega} \frac{\partial\varphi_{\delta}}{\partial\nu} g(x)dx = -\int_{-\delta}^{\delta} \int_{-\delta}^{\delta} \left(\frac{\varepsilon}{2\delta}\right)^2 \frac{\partial\gamma\left(r,\frac{s\varepsilon}{2\delta},\frac{t\varepsilon}{2\delta}\right)}{\partial r} g(\psi(s,t)) \|\psi_s \times \psi_t\| \, dsdt = 0$$

Using the change of variables $\sigma = \frac{s\varepsilon}{2\delta}$ and $\theta = \frac{t\varepsilon}{2\delta}$, we get

$$\int_{-\frac{\varepsilon}{2}}^{\frac{\varepsilon}{2}} \int_{-\frac{\varepsilon}{2}}^{\frac{\varepsilon}{2}} \frac{\partial \gamma \left(r, \sigma, \theta\right)}{\partial r} g\left(\psi\left(\frac{2\delta\sigma}{\varepsilon}, \frac{2\delta\theta}{\varepsilon}\right)\right) \|\psi_s\left(\frac{2\delta\sigma}{\varepsilon}, \frac{2\delta\theta}{\varepsilon}\right) \times \psi_t\left(\frac{2\delta\sigma}{\varepsilon}, \frac{2\delta\theta}{\varepsilon}\right) \|d\sigma d\theta = 0.$$

$$(2.2)$$

On the other hand we have:

$$\begin{split} \left| \int_{-\frac{\varepsilon}{2}}^{\frac{\varepsilon}{2}} \int_{-\frac{\varepsilon}{2}}^{\frac{\varepsilon}{2}} \frac{\partial \gamma}{\partial r}(0,s,t) \left(g\left(\psi\left(\frac{2\delta s}{\varepsilon},\frac{2\delta t}{\varepsilon}\right)\right) \left\|\psi_{s}\times\psi_{t}\left(\frac{2\delta s}{\varepsilon},\frac{2\delta t}{\varepsilon}\right)\right\| - g\left(\psi\left(0,0\right)\right) \left\|\psi_{s}\times\psi_{t}\left(0,0\right)\right\| \right) ds dt \\ \leq \left| \int_{-\frac{\varepsilon}{2}}^{\frac{\varepsilon}{2}} \int_{-\frac{\varepsilon}{2}}^{\frac{\varepsilon}{2}} \frac{\partial \gamma}{\partial r}(0,s,t) \left\|\psi_{s}\times\psi_{t}\left(\frac{2\delta s}{\varepsilon},\frac{2\delta t}{\varepsilon}\right)\right\| \left(g\left(\psi\left(\frac{2\delta s}{\varepsilon},\frac{2\delta t}{\varepsilon}\right)\right) - g\left(\psi\left(0,0\right)\right)\right) dt ds \right| \\ + \left| \int_{-\frac{\varepsilon}{2}}^{\frac{\varepsilon}{2}} \int_{-\frac{\varepsilon}{2}}^{\frac{\varepsilon}{2}} \frac{\partial \gamma}{\partial r}(0,s,t) g\left(\psi\left(0,0\right)\right) \left(\left\|\psi_{s}\times\psi_{t}\left(\frac{2\delta s}{\varepsilon},\frac{2\delta t}{\varepsilon}\right)\right\| - \left\|\psi_{s}\times\psi_{t}\left(0,0\right)\right\|\right) dt ds \right| \\ := I + II \end{split}$$

Using Cauchy- Schwartz inequality, a change of variables and the fact that $x_0 = \psi(0,0)$ is a Lebesgue point, we have

$$\begin{split} I &\leq \left(\int_{-\frac{\varepsilon}{2}}^{\frac{\varepsilon}{2}} \int_{-\frac{\varepsilon}{2}}^{\frac{\varepsilon}{2}} \left(\frac{\partial\gamma}{\partial r}(0,s,t)\right)^2 \left\|\psi_s \times \psi_t\left(\frac{2\delta s}{\varepsilon},\frac{2\delta t}{\varepsilon}\right)\right\| dt ds\right)^{\frac{1}{2}} \\ &\times \left(\int_{-\frac{\varepsilon}{2}}^{\frac{\varepsilon}{2}} \int_{-\frac{\varepsilon}{2}}^{\frac{\varepsilon}{2}} \left(g\left(\psi\left(\frac{2\delta s}{\varepsilon},\frac{2\delta t}{\varepsilon}\right)\right) - g\left(\psi\left(0,0\right)\right)\right)^2 \left\|\psi_s \times \psi_t\left(\frac{2\delta s}{\varepsilon},\frac{2\delta t}{\varepsilon}\right)\right\| dt ds\right)^{\frac{1}{2}} \\ &= \left(\int_{-\frac{\varepsilon}{2}}^{\frac{\varepsilon}{2}} \int_{-\frac{\varepsilon}{2}}^{\frac{\varepsilon}{2}} \left(\frac{\partial\gamma}{\partial r}(0,s,t)\right)^2 \left\|\psi_s \times \psi_t\left(\frac{2\delta s}{\varepsilon},\frac{2\delta t}{\varepsilon}\right)\right\| dt ds\right)^{\frac{1}{2}} \\ &\times \left(\frac{\varepsilon^2}{4\delta^2} \int_{-\delta}^{\delta} \int_{-\delta}^{\delta} \left(g\left(\psi\left(\sigma,\tau\right)\right) - g\left(\psi\left(0,0\right)\right)\right)^2 \left\|\psi_s \times \psi_t\left(\sigma,\tau\right)\right\| dt ds\right)^{\frac{1}{2}} \to 0 \text{ as } \delta \to 0. \end{split}$$

Next, as ψ_t, ψ_s and $\frac{\partial \gamma}{\partial r}$ are continuous functions, we can use dominated convergence theorem to yield

$$II = \left| \int_{-\frac{\varepsilon}{2}}^{\frac{\varepsilon}{2}} \int_{-\frac{\varepsilon}{2}}^{\frac{\varepsilon}{2}} \frac{\partial \gamma}{\partial r}(0, s, t) g\left(\psi\left(0, 0\right)\right) \left(\left\| \psi_s \times \psi_t\left(\frac{2\delta s}{\varepsilon}, \frac{2\delta t}{\varepsilon}\right) \right\| - \left\| \psi_s \times \psi_t\left(0, 0\right) \right\| \right) \, dt ds \right|$$

$$\to 0 \text{ as } \delta \to 0.$$

We therefore have

$$g(x_0)\|\psi_s \times \psi_t(0,0)\| \int_{-\frac{\varepsilon}{2}}^{\frac{\varepsilon}{2}} \int_{-\frac{\varepsilon}{2}}^{\frac{\varepsilon}{2}} \frac{\partial\gamma}{\partial r}(0,s,t) \, ds dt = \lim_{\delta \to 0} \int_{\partial\Omega} \frac{\partial\varphi_\delta}{\partial\nu} g(x) \, dx = 0$$

as $\delta \to 0$.

Choosing $\gamma(r, s, t) = r \cdot a(s)b(t)$, where $a, b: (-\varepsilon, \varepsilon) \to \mathbb{R}$ are smooth and satisfy

- $a(s), b(t) \ge 0$,
- a(s), b(t) > 0 for $s, t \in \left(-\frac{\varepsilon}{3}, \frac{\varepsilon}{3}\right)$,
- a(s), b(t) = 0 for $s, t \notin (-\frac{\varepsilon}{2}, \frac{\varepsilon}{2})$.

Then we have

$$\int_{-\frac{\varepsilon}{2}}^{\frac{\varepsilon}{2}} \int_{-\frac{\varepsilon}{2}}^{\frac{\varepsilon}{2}} \frac{\partial \gamma}{\partial r}(0,s,t) \, ds dt = \int_{-\frac{\varepsilon}{2}}^{\frac{\varepsilon}{2}} \int_{-\frac{\varepsilon}{2}}^{\frac{\varepsilon}{2}} a(s)b(t) \, ds dt > 0$$

and $g(x_0) = 0$ as required.

We can now proceed with the proof of Theorem 1.1.

Proof. [of Theorem 1.1] First we consider d = 2. Let \bar{n} be a critical point of \mathbb{E} in \mathscr{A} . By lemma 2.1 \bar{n} satisfies the equation

$$\int_{\partial\Omega} \sum_{\beta,\alpha=1}^{d} \varphi_{\beta,\alpha} \bar{n}_{\alpha} \left(\nu_{\beta} - \bar{n}_{\beta} \langle \bar{n}, \nu \rangle \right) dS = 0, \qquad (2.3)$$

for all $\varphi \in C^{\infty}(\Omega, \mathbb{R}^3)$ such that $\varphi = 0$ on $\partial\Omega$. Let $\nu(x) = (\nu_1(x), \nu_2(x))$ be the unit vector to $\partial\Omega$ at x and $\tau(x)$ be a unit tangent to $\partial\Omega$ at x. Then at $x \in \partial\Omega$ we have

$$\bar{n} = \langle \bar{n}, \nu \rangle \nu + \langle \bar{n}, \tau \rangle \tau. \tag{2.4}$$

plugging this into (2.3) gives

$$0 = \int_{\partial\Omega} \sum_{\beta,\alpha=1}^{d} \varphi_{\beta,\alpha} \left(\langle \bar{n}, \nu \rangle \nu_{\alpha} + \langle \bar{n}, \tau \rangle \tau_{\alpha} \right) \left(\nu_{\beta} - \bar{n}_{\beta} \langle \bar{n}, \nu \rangle \right) dS.$$

Since $\varphi = 0$ on $\partial \Omega$ we have $\frac{\partial \varphi_{\beta}}{\partial \tau} = \varphi_{\beta,\alpha} \cdot \tau_{\alpha} = 0$. Hence (2.3) simplifies to

$$0 = \int_{\partial\Omega} \sum_{\beta=1}^{d} \frac{\partial \varphi_{\beta}}{\partial \nu} \langle \bar{n}, \nu \rangle \left(\nu_{\beta} - \bar{n}_{\beta} \langle \bar{n}, \nu \rangle \right) dS.$$
(2.5)

If d = 3 then for any point $x_0 \in \partial \Omega$ one can choose in a neighbourhood of x_0 two unit vector fields P, Q such that $P \times Q = \nu$ and $\langle P, Q \rangle = 0$. Then by writing

$$\bar{n} = \langle \bar{n}, \nu \rangle \nu + \langle \bar{n}, P \rangle P + \langle \bar{n}, Q \rangle Q$$

and using a partition of unity to use this into (2.3) we get that (2.5) holds for d = 3. By setting $\varphi_i \equiv 0$ for $i \neq \beta$ in (2.5), we get

$$\int_{\partial\Omega} \frac{\partial\varphi}{\partial\nu} \langle \bar{n}, \nu \rangle \left(\nu_{\beta} - \bar{n}_{\beta} \langle \bar{n}, \nu \rangle \right) dS = 0$$

for $\beta = 1, 2, 3$ and for all $\varphi \in C^{\infty}(\Omega, \mathbb{R})$ such that $\varphi|_{\partial\Omega} = 0$. By Lemma 2.2, we conclude that

$$\langle \bar{n}, \nu \rangle \left(\nu_{\beta} - \bar{n}_{\beta} \langle \bar{n}, \nu \rangle \right) = 0 \text{ for } \beta = 1, \dots, d.$$
 (2.6)

Fix an arbitrary point $x \in \partial \Omega$. If $\langle \bar{n}(x), \nu(x) \rangle = 0$ then we are done. Otherwise suppose $\langle \bar{n}(x), \nu(x) \rangle \neq 0$, and then we must have

$$(\nu_{\beta} - \bar{n}_{\beta} \langle \bar{n}, \nu \rangle) = 0$$
 for $\beta = 1, \dots, d$.

Since $\langle \bar{n}, \nu \rangle \neq 0$

$$\bar{n}_{\beta} = \frac{\nu_{\beta}}{\langle \bar{n}, \nu \rangle}$$
 for $\beta = 1 \dots d$,

which implies

$$egin{aligned} &\langle ar{n},
u
angle &= \sum_{eta=1}^d rac{
u_eta}{\langle ar{n},
u
angle}
u_eta \ &= rac{\langle
u,
u
angle}{\langle ar{n},
u
angle} \ &= rac{\langle
u,
u
angle}{\langle ar{n},
u
angle} \ &= rac{1}{\langle ar{n},
u
angle}. \end{aligned}$$

Hence

$$\langle \bar{n}, \nu \rangle^2 = 1$$

and therefore

$$\langle \bar{n},\nu\rangle=\pm 1.$$

3 Partial regularity for tangential boundary conditions

We restrict from now on our attention to the case when the boundary conditions are tangential, i.e. $n(x) \cdot \nu(x) = 0$ for all $x \in \partial \Omega$, where ν is the outward pointing unit normal.

We note that for any vector v that is tangent to $\partial \Omega$ at x we have

$$\frac{d\langle n(x), \nu(x) \rangle}{dv} := \sum_{\alpha=1}^{3} \frac{\partial \langle n(x), \nu(x) \rangle}{\partial x^{\alpha}} v^{\alpha} = 0.$$

as $\langle n(x), \nu(x) \rangle$ is constant in the *v* direction. That is tangential derivatives of $\langle n(x), \nu(x) \rangle$ are zero for all $x \in \partial \Omega$. Hence, as n(x) is a tangent vector to $\partial \Omega$ at $x \in \partial \Omega$, we have

$$\sum_{\alpha,\beta=1}^{d} n^{\alpha} \frac{\partial n^{\beta}}{\partial x^{\alpha}} \nu^{\beta} = \sum_{\alpha=1}^{d} n^{\alpha} \frac{\partial (n \cdot \nu)}{\partial x^{\alpha}} - \sum_{\alpha,\beta=1}^{d} \frac{\partial \nu^{\beta}}{\partial x^{\alpha}} n^{\beta} n^{\alpha}$$
$$= -\sum_{\alpha,\beta=1}^{d} \frac{\partial \nu^{\beta}}{\partial x^{\alpha}} n^{\beta} n^{\alpha}.$$

Therefore, for maps with tangential boundary conditions we can write $\mathbb E$ as

$$\mathbb{G}[n] := \int_{\Omega} K \sum_{\alpha,\beta=1}^{d} \frac{\partial n^{\alpha}}{\partial x^{\beta}} \frac{\partial n^{\alpha}}{\partial x^{\beta}} - K_{13} \int_{\partial \Omega} \sum_{\alpha,\beta=1}^{d} \frac{\partial \nu^{\beta}}{\partial x^{\alpha}} n^{\beta} n^{\alpha}.$$

This energy makes sense for maps in $W^{1,2}(\Omega, \mathbb{S}^2)$, and so we now focus on the slightly simpler task of minimizing \mathbb{G} over the function space

$$\mathcal{U} := \{ u \in W^{1,2}(\Omega, \mathbb{S}^2) : \operatorname{Trace}(u) \in \mathcal{T} \}$$
(3.1)

where

$$\mathcal{T} := \{ \gamma \in H^{\frac{1}{2}}(\partial\Omega, \mathbb{S}^2) : \gamma(x) \cdot \nu(x) = 0 \text{ for almost every } x \in \partial\Omega \}.$$
(3.2)

Given the topological constraints associated with having tangential boundary conditions the first issue is to show that the function space \mathcal{U} is non-empty. This will be addressed in the next subsection, while in the last subsection we will prove a partial regularity result for the minimizers.

3.1 Function Space is non empty

In this section we consider Ω to be a bounded domain of class C^2 and study whether or not the function space \mathcal{U} defined through (3.1),(3.2) is non-empty.

If, for instance, $\partial\Omega$ is the torus then there exist smooth maps in \mathcal{T} that have smooth extensions to the solid torus $\mathbb{B}\times\mathbb{S}^1$ and hence \mathcal{U} would be non empty. However, if $\partial\Omega$ is \mathbb{S}^2 then the "Hairy Ball Theorem" tells us that there are no continuous maps in \mathcal{T} and so it is not immediate that \mathcal{U} is non empty. Fortunately, since $H^{\frac{1}{2}}$ in dimension two is larger than the space of continuous functions we are able to show that \mathcal{T} and \mathcal{U} are still non-empty even when $\partial\Omega$ a general C^2 surface.¹

To this end we use an extension Theorem from [6] (stated as Theorem 3.6 in the following) which tells us that a function in \mathcal{T} can be extended to a function in \mathcal{U} . This means to show \mathcal{U} is non empty we only need to show that \mathcal{T} is non empty. To do this we construct a function that belongs to \mathcal{T} through a sequence of lemmas. We remark that a map $\gamma \in H^{\frac{1}{2}}(\partial\Omega, \mathbb{S}^2)$ is in \mathcal{T} if and only if $\gamma(x) \in T_x \partial\Omega$ for almost every $x \in \partial\Omega$, where $T_x \partial\Omega$ is the tangent space to $\partial\Omega$ at x.

In Lemma 3.1 below we will give necessary and sufficient conditions to extend a vector field from the boundary of a manifold N to its interior. Before we can state Lemma 3.1 we must first introduce some notation:

If U is a C^2 manifold embedded in \mathbb{R}^d , let $T_x U$ be the tangent space to U at $x \in U$. Let g be a smooth vector field on U, i.e a smooth map $g: U \to \mathbb{R}^d$ such that $g(x) \in T_x U$ for every $x \in U$. Then let ind(g, U) denote the index of g on U (we refer the reader to [9],[18] or [3] for detailed properties of ind(g, U)).

If U is a manifold with boundary we define

$$\partial_{-}U[g] := \{ x \in \partial U : g(x) \cdot \nu(x) < 0 \},\$$

where $\nu(x)$ is the outward-pointed unit normal to U at x.

Furthermore, we recall that if U is a compact surface then its Euler characteristic $\chi(U)$ can be related to its topological genus k through the formula

$$\chi(U) = 2(1-k).$$

LEMMA 3.1. Let N be a C^1 manifold with boundary embedded in \mathbb{R}^d and $g \in C^{\infty}(\partial N, \mathbb{R}^d)$ such that

$$g(x) \in T_x(\partial N) \text{ and } |g(x)| = 1.$$
(3.3)

Then g admits an extension to a continuous field $V : N \to \mathbb{R}^d$ such that, for every $x \in N, V(x) \in T_x N, |V(x)| = 1$ and $V|_{\partial N} = g$ if and only if

$$ind(g, \partial_{-}N[g]) = \chi(N). \tag{3.4}$$

Proof. Let $g \in C^{\infty}(\partial N, \mathbb{R}^d)$ such that (3.3) and (3.4) hold. Let X be the topological double of N, that is, the manifold obtained by glueing two copies of N along their boundaries (see [10] example 3.80 for a detailed construction of X). By modifying the value of d if needed we can assume that X is embedded in \mathbb{R}^d .

¹We just need C^2 regularity for using Theorem 3.6, for all the other results of the section it would suffice to have C^1 .

Let $U \subset X$ be a tubular neighbourhood of ∂N such that the nearest point projection $\pi : U \to \partial N$ is well defined. Let $\varphi : X \to \mathbb{R}$ be a smooth function such that $\varphi|_{\partial N} = 1$ and $\varphi|_{X \setminus U} = 0$. Then let $\tilde{G} : X \to \mathbb{R}^d$ be the extension of g defined by

$$\tilde{G}(x) := \begin{cases} Proj_{T_{xX}} \left(g(\pi(x)) \right) \varphi(x) \text{ for } x \in X \cap U, \\ 0 \text{ for } x \in X \setminus U, \end{cases}$$

where $Proj_{T_xX}(y)$ is the projection of y onto T_xX . As $0 \notin \tilde{G}(\partial N)$, by the Transitivity Theorem (see [2] Theorem 14.6), there exists a smooth tangent vector field F on Xsuch that F has finitely many zeros in N and $F|_{\partial N} = g$. Define $P_{\partial N}F$ to be the map

$$P_{\partial N}F(x) := Proj_{T_x \partial N}(F(x)) \text{ for } x \in \partial N$$

and for a continuous vector field $v: N \to \mathbb{R}^d$, define $\partial_-N[v]$ is to be the set

$$\partial_{-}N[v] := \{ x \in \partial N : v(x) \cdot \nu(x) < 0 \}.$$

By Morse's Index Formula (see [12]) and the stability of the index we have

$$ind(F, N) = ind(\tilde{G}, N)$$

= $\chi(N) - ind(P_{\partial N}\tilde{G}, \partial_{-}N[P_{\partial N}\tilde{G}])$
= $\chi(N) - ind(g, \partial_{-}N[g])$
= 0.

We now just need to modify F such that |F| > 0 on N. Up to a continuous transformation, we can assume that all the zeros are contained in one coordinate patch $D \subset N$, with chart $\phi : \overline{D} \to \overline{B^d(0,1)}$ such that $\phi(\partial D) = \partial B^d(0,1)$, where $B^d(0,1)$ is the ball in \mathbb{R}^d centred at 0 with radius 1. Let $\tilde{F} : B^d(0,1) \to \mathbb{R}^d$ be the map defined as

$$\tilde{F}(x) := F(\phi^{-1}(x))$$

and assume that $|\tilde{F}| > 0$ in $B^d(0,1) \setminus B^d(0,\frac{1}{2})$. Then,

$$0 = ind(\tilde{F}, B^d(0, 1)) = deg\left(\frac{F}{|F|}, \partial D; \mathbb{S}^{d-1}\right)$$

It can now be shown, as proved in [8], that there exists a harmonic field $\psi : B^d(0,1) \to \mathbb{S}^{d-1}$ such that $\psi|_{\partial B^d(0,1)} = \frac{\tilde{F}}{|\tilde{F}|}$. Finally, we define our extension:

$$V(x) = \begin{cases} \frac{F(x)}{|F(x)|} & \text{if } x \in N \setminus D, \\ \psi(\phi(x)) & \text{if } x \in D. \end{cases}$$

V is continuous and smooth everywhere apart from ∂D .

Remark: Note that in the above construction we get a vector field on N that is smooth almost everywhere.

We now relate the $H^{\frac{1}{2}}$ to a space whose norm is easier to compute, the $W^{1,p}$ space:

LEMMA 3.2. Let $U \subset \mathbb{R}^2$ be an open set with C^1 boundary and $u \in W^{1,p}(U, \mathbb{S}^2)$ for $1 . Then <math>u \in H^{\frac{1}{2}}(U, \mathbb{S}^2)$.

In order to prove this we use the following Propositions from [20] (or [13]):

THEOREM 3.3. Let $p \in [1, \infty)$ and $s \in (0, 1)$. Let Ω be an open set in \mathbb{R}^n of class C^1 with bounded boundary and $u \in W^{1,p}(\Omega, \mathbb{R})$. Then

$$||u||_{W^{s,p}(\Omega)} \le C ||u||_{W^{1,p}(\Omega)}$$

for some positive constant $C = C(n, s, p) \ge 1$.

and

THEOREM 3.4. Let $p \in [1, +\infty)$, $s \in (0, 1)$ and $\Omega \subseteq \mathbb{R}^n$ be an open set of class C^1 with bounded boundary. Then $W^{s,p}(\Omega)$ is continuously embedded in $W^{s,p}(\mathbb{R}^n)$, namely there exists $C = C(n, \Omega)$ such that for any $u \in W^{s,p}(\Omega)$ there exists $\tilde{u} \in W^{s,p}(\mathbb{R}^n)$ such that $\tilde{u}|_{\Omega} = u$ and

 $\|\tilde{u}\|_{W^{s,p}(\mathbb{R}^n)} \le C \|u\|_{W^{s,p}(\Omega)}.$

We also use the interpolation lemma from [11]

THEOREM 3.5. For all $u \in W^{s,q}(\mathbb{R}^n) \cap L^{\infty}(\mathbb{R}^n)$ there holds the inequality

$$\|u\|_{W^{\theta s, q/\theta}(\mathbb{R}^n)} \le c(n) \left(\frac{q}{q-1}\right)^{\theta} \left(\frac{1-s}{1-\theta}\right)^{\frac{\theta}{q}} \|u\|_{W^{s, q}(\mathbb{R}^n)}^{\theta} \|u\|_{L^{\infty}}^{1-\theta}$$

where $0 < s < 1, 1 < q < \infty$, and $0 < \theta < 1$.

We can now prove Lemma 3.2.

Proof. [Lemma 3.2] Let $1 and <math>u \in W^{1,p}(U)$. By Theorem 3.3 we have that $u \in W^{\frac{2}{3},p}(U)$. Let $\tilde{u} \in W^{\frac{2}{3},p}(\mathbb{R}^2)$ be the extension given by Theorem 3.4. By setting $s = \frac{2}{3}, \theta = \frac{3}{4}$ and $q = \frac{3}{2}$ in Theorem 3.5 we have

$$\begin{split} \|u\|_{H^{\frac{1}{2}}(U)} &\leq \|\tilde{u}\|_{H^{\frac{1}{2}}(\mathbb{R}^{2})} = \|\tilde{u}\|_{W^{\frac{2}{3},\frac{3}{4},2}(\mathbb{R}^{2})} \leq C \|\tilde{u}\|_{W^{\frac{2}{3},\frac{3}{2}}(\mathbb{R}^{2})}^{\frac{3}{4}} \|u\|_{L^{\infty}(\mathbb{R}^{2})}^{\frac{1}{4}} \\ &\leq C \|u\|_{W^{\frac{3}{4},\frac{3}{2}}(U)}^{\frac{3}{4}} \|u\|_{L^{\infty}(\mathbb{R}^{2})}^{\frac{1}{4}} \leq C \|u\|_{W^{1,\frac{3}{2}}(U)}^{\frac{3}{4}} \|u\|_{L^{\infty}(\mathbb{R}^{2})}^{\frac{1}{4}} < \infty. \end{split}$$

In order to prove Proposition 1.2 we use an extension theorem from [6], which we state here for the reader's convenience.

THEOREM 3.6. If $1 , <math>\Omega$ is a bounded C^2 domain in \mathbb{R}^m , and N is a compact C^2 submanifold of \mathbb{R}^k with $\pi_0(N) = \pi_1(N) = \dots \pi_{[p]-1}(N) = 0$, then any function $\eta \in W^{1-1/p,p}(\partial\Omega, N)$ admits an extension $\omega \in W^{1,p}(\Omega, N)$.

We are now in a position to prove Proposition 1.2

Proof. [**Proposition 1.2**] Let Ω be a C^2 domain such that $\partial \Omega$ is a surface of genus k. Then we have that

$$\chi(\partial\Omega) = 2(1-k).$$

We first show that the map $\varphi: B^2(0,1) \to \mathbb{S}^1$ defined by

$$\varphi(x^1, x^2) = \left(\frac{-x^2}{\sqrt{(x^1)^2 + (x^2)^2}}, \frac{x^1}{\sqrt{(x^1)^2 + (x^2)^2}}\right)$$

is in $W^{1,p}(B^2(0,1),\mathbb{S}^1)$. Then $|\nabla \varphi| = \frac{1}{|x|}$ and we have: thus

$$\int_{B^2(0,1)} |\nabla \varphi|^p dx \le C \int_0^1 r^{1-p} dr$$

which is finite for $1 , hence <math>\varphi \in W^{1,p}(B^2(0,1), \mathbb{S}^1)$ for 1 .

For $i = 1 \dots |\chi(\partial \Omega)|$ let (U_i, ψ_i) be coordinate patches on $\partial \Omega$ such that $\bigcap_{i=1}^{|\chi(\partial \Omega)|} U_i = \emptyset$. Using

$$\varphi(x^1, x^2) = \left(\frac{-x^2}{\sqrt{(x^1)^2 + (x^2)^2}}, \frac{x^1}{\sqrt{(x^1)^2 + (x^2)^2}}\right),$$

or

$$\tilde{\varphi}(x^1, x^2) = \left(\frac{x^2}{\sqrt{(x^1)^2 + (x^2)^2}}, \frac{-x^1}{\sqrt{(x^1)^2 + (x^2)^2}}\right)$$

we can put a unit vector field, v_i , on each U_i such that the map $V : \bigcup U_i \to \mathbb{S}^2$ defined by

$$v(x) := v_i(x)$$
 if $x \in U_i$

satisfies

ind
$$\left(v\Big|_{\partial(\cup U_i)}, \partial_{\neg}(\partial\Omega \setminus \cup U_i)\right)[v]\right) = \chi(\partial\Omega).$$

Using Lemma 3.1 we can now extend V to a vector field on $\partial\Omega$ that is smooth on $\partial\Omega \setminus \bigcup U_i$. Since φ and $\tilde{\varphi}$ are both in $W^{1,p}(\partial\Omega, \mathbb{S}^2)$ for 1 the map <math>V is in $W^{1,p}(\partial\Omega, \mathbb{S}^2)$. Then by Lemma 3.2 we have that $V \in H^{\frac{1}{2}}(\partial\Omega, \mathbb{S}^2)$, it follows that $V \in \mathcal{T}$ and hence \mathcal{T} is non empty. Using Theorem 3.6 we can now conclude that the function space \mathcal{T} is non empty. \Box

3.2 Regularity of Minimizers

We prove that a minimizer, u, of \mathbb{G} in \mathcal{U} is continuous on $\Omega \setminus Z$, where Z is some subset of Ω with zero one-dimensional Hausdorff measure. We show that for $x \in \Omega \setminus Z$ the rescaled energy

$$\mathbb{E}_r[u] := r^{-1} \int_{\Omega \cap C(a,r)} |\nabla u|^2 dx$$

decays suitably fast as r tends to 0. Continuity of u then follows by Morrey's Lemma (see for example [19] Chapter 18). Our proof of the energy decay is based on the work of Schoen and Uhlenbeck [16] and the papers by Hardt and Lin [6], [7].

We give a brief outline of the proof here. For a given domain Ω we construct a map $Q: \Omega \to SO(3)$ (depending only on $\partial\Omega$) such that for an arbitrary map $u \in \mathcal{U}$ we have that Q(x)u(x) lies on the equator of \mathbb{S}^2 for almost all $x \in \partial\Omega$. This transforms our tangential boundary conditions into a partially constrained boundary condition as in [7], so we can adapt some of the results there in order to prove a Hybrid inequality (Lemma 3.11). The proof of the energy decay (Lemma 3.12 and Theorem 3.13) is then done by contradiction. We assume there exists a sequence of minimizers, u_i , and domains, Ω_i , that do not have energy decay but do satisfy $\varepsilon_i = \int_{\Omega_i} |\nabla u_i|^2 dx \to 0$ as $i \to \infty$. We then form the blow-up sequence $\varepsilon_i^{-1}(u_i - \overline{u}_i)$ that converges weakly to a blow up function v. We then prove some estimates on v by showing it is harmonic. These estimates are then transferred to the u_i using the Hybrid inequality in order to get a contradiction.

3.2.1 Scaling and notations

In order to apply Morrey's Lemma we must investigate how our energy scales. For $x \in \mathbb{R}^3$ define the cylinder $C(x, r) := \{y \in \mathbb{R}^3 : |(y^1, y^2) - (x^1, x^2)| < r, |y^3 - x^3| < r\}$. Let

$$\varphi \in C^2(\mathbb{R}^2, \mathbb{R}) \text{ with } \varphi(0) = 0 = |\nabla \varphi(0)|, \operatorname{Lip}(\varphi) \le 1$$
 (3.5)

and define

$$\Omega_{\varphi} := \{ (x^1, x^2, x^3) \in C(0, 1) : x^3 < \varphi(x^1, x^2) \} \\ = \{ x \in \mathbb{R}^3 : \left| (x^1, x^2) \right| < 1 \text{ and } -1 < x^3 < \varphi(x^1, x^2) \}$$

For a domain $\Omega \subset \mathbb{R}^3$, $a \in \partial \Omega$ there exists R > 0, $h \in SO(3)$ and $\varphi_{R,a} \in C^2(\mathbb{R}^2, \mathbb{R})$ such that $\varphi_{R,a}(0) = 0 = |\nabla \varphi_{R,a}(0)|$, $\operatorname{Lip}(\varphi_{R,a}) \leq 1$ and

$$\Omega_{\varphi_{R,a}} = \{h^{-1}[(y-a)/R] : y \in C(a,R) \cap \Omega\}$$

For $0 < r \leq R$, let $\varphi_{r,a} = \varphi_{R,a}(\frac{rx}{R})$, then for $u \in \mathcal{U}$, the expression $n_{r,a}(x) = n[rh(x) + a]$ defines a function in $W^{1,2}(\Omega_{\varphi_{r,a}}, \mathbb{S}^2)$ whose trace, γ , on $\partial\Omega_{\varphi_{r,a}} \setminus \partial C(0, 1)$ satisfies $\gamma(x) \cdot (h \cdot \nu(x)) + a) = 0$ almost everywhere. We note that

$$\mathbb{E}_{1}(u_{r,a}) = \int_{\Omega_{\varphi} \cap C(0,1)} |\nabla u_{r,a}(x)|^{2} dx = r^{-1} \int_{\Omega_{\varphi} \cap C(a,r)} |\nabla u|^{2} dx$$
$$\operatorname{Lip}(\varphi_{r,a}) = \operatorname{Lip}(\varphi_{R,a}) R^{-1} r$$

$$\|\varphi_{r,a}\|_{C^2} := \max_{|\alpha|=2} \sup_{x \in \mathbb{R}^2} \left| \frac{\partial^{|\alpha|} \varphi_{r,a}(x)}{\partial x^{\alpha}} \right| = R^{-2} r^2 \|\varphi_{R,a}\|_{C^2}.$$

For convenience we collect the notations of various domains we will use

Using these notations we define the energy, \mathbb{G}_{φ} , for a map $u \in W^{1,2}(\Omega_{\varphi}, \mathbb{S}^2)$ to be

$$\mathbb{G}_{\varphi}[u] := \int_{\Omega_{\varphi}} |\nabla u|^2 \, dx - K_{13} \int_{G_{\varphi}} u^{\alpha} u^{\beta} \frac{\partial \nu^{\beta}}{\partial x^{\alpha}} \, dx.$$

3.2.2 A Useful Projection

Given φ as above we will construct a map

$$Q: \Omega_{\varphi} \to SO(3)$$

such that if

$$u \in \mathcal{U}_{\varphi} := \{ u \in W^{1,2}(\Omega_{\varphi}, \mathbb{S}^2) : \operatorname{Trace}(u) \in \mathcal{T}_{\varphi} \}$$

where

$$\mathcal{T}_{\varphi} = \{ \gamma \in H^{\frac{1}{2}}(G_{\varphi}, \mathbb{S}^2) : \gamma(x) \cdot \nu(x) = 0 \text{ almost everywhere } \}.$$

then the map w(x) := Q(x)u(x) is in the function space

$$\mathscr{E}_{\varphi} = \{ v \in W^{1,2}(\Omega_{\varphi}, \mathbb{S}^2) : \operatorname{Trace}(v) \in \tilde{\mathbb{S}}^1 \},\$$

where $\tilde{\mathbb{S}}^1 = \{ (x^1, x^2, x^3) \in \mathbb{S}^2 : x^3 = 0 \}.$

We construct Q as follows: let $x \in G_{\varphi}$ and let $\nu(x)$ be the unit norm to G_{φ} at x. Define Q(x) to be the rotation about the axis $\nu(x) \times (0, 0, 1)$ through the angle τ given by $\cos(\tau) = \nu(x) \cdot (0, 0, 1)$. Explicitly Q is given by

$$Q(x) := \begin{bmatrix} \frac{\varphi_{x^2}^2 + \varphi_{x^1}^2 \cos(\tau)}{\varphi_{x^1}^2 + \varphi_{x^2}^2} & -\frac{\varphi_{x^1}\varphi_{x^2}(1 - \cos(\tau))}{\varphi_{x^1}^2 + \varphi_{x^2}^2} & \frac{\varphi_{x^1}\sin(\tau)}{(\varphi_{x^1}^2 + \varphi_{x^2}^2)^{\frac{1}{2}}} \\ -\frac{\varphi_{x^1}\varphi_{x^2}(1 - \cos(\tau))}{\varphi_{x^1}^2 + \varphi_{x^2}^2} & \frac{\varphi_{x^1}^2 + \varphi_{x^2}^2 \cos(\tau)}{\varphi_{x^1}^2 + \varphi_{x^2}^2} & \frac{\varphi_{x^2}\sin(\tau)}{(\varphi_{x^1}^2 + \varphi_{x^2}^2)^{\frac{1}{2}}} \\ -\frac{\varphi_{x^1}\sin(\tau)}{(\varphi_{x^1}^2 + \varphi_{x^2}^2)^{\frac{1}{2}}} & -\frac{\varphi_{x^2}\sin(\tau)}{(\varphi_{x^1}^2 + \varphi_{x^2}^2)^{\frac{1}{2}}} & \cos(\tau) \end{bmatrix}, \quad (3.6)$$

where $\varphi_{x_i} = \frac{\partial \varphi}{\partial x_i}$, $\cos(\tau) = (\varphi_{x^1}^2 + \varphi_{x^2}^2 + 1)^{-\frac{1}{2}}$ and $\sin(\tau) = \sqrt{\frac{\varphi_{x^1}^2 + \varphi_{x^2}^2}{\varphi_{x^1}^2 + \varphi_{x^2}^2 + 1}}$. Then for $x = (x^1, x^2, x^3) \in \Omega_{\varphi}$ define

$$Q(x) = Q((x^1, x^2, \varphi(x^1, x^2)))$$

It is straightforward to check that $Q \in C^1(\Omega_{\varphi}, SO(3))$. We now find some bounds on the entries of Q that will be useful throughout our proof.

LEMMA 3.7. Let Q, φ be defined as above, then we have

$$\sup\{|Q(x)n - n| : x \in \Omega_{\varphi}, n \in \mathbb{S}^2\} \le 9\mathrm{Lip}(\varphi).$$

Proof. Let $x \in G_{\varphi}$ and $n \in \mathbb{S}^2$. We have $|Q(x)n - n| \leq \sum_{i=1}^3 |(Q(x)n - n)_i|$, where $(Q(x)n - n)_i$ is the i^{th} component of Q(x)n - n. We find bounds on each component individually.

$$\left| (Q(x)n - n)_1 \right| = \left| \left(\frac{\varphi_{x^2}^2 + \varphi_{x^1}^2 \cos(\tau) - \varphi_{x^1}^2 - \varphi_{x^2}^2}{\varphi_{x^1}^2 + \varphi_{x^2}^2} \right) n_1 - \frac{\varphi_{x^1} \varphi_{x^2} (1 - \cos(\tau)) n_2}{\varphi_{x^1}^2 + \varphi_{x^2}^2} + \varphi_{x_1} \cos(\tau) n_3 \right|$$

Writing $\varphi_{x^1}(x) = r \cos(t), \varphi_{x^2}(x) = r \sin(t)$ for appropriate $r \in (0, \infty), t \in [0, 2\pi)$ we have

$$|(Q(x)n - n)_1| \le \left| \frac{r^2 \cos^2(t) \left((r^2 + 1)^{-\frac{1}{2}} - 1 \right)}{r^2} \right| + \left| \frac{r^2 \cos(t) \sin(t) \left(1 - (r^2 + 1)^{-\frac{1}{2}} \right)}{r^2} \right| + |r|$$

$$\le 2r + r$$

$$\le 3 \text{Lip}(\varphi)$$

We can get a similar estimate for $(Q(x)n - n)_2$ and $(Q(x)n - n)_3$, hence

$$|Q(x)n - n| \le 9\mathrm{Lip}(\varphi).$$

Lemma 3.8.

$$\sup\left\{ \left| \frac{\partial Q_{ij}(x)}{\partial x^k} \right| : i, j, k \in \{1, 2, 3\}, x \in \Omega_{\varphi} \right\} < 6 \left\| \varphi \right\|_{C^2}$$

Proof. Let $x \in \Omega_{\varphi}$, we find bounds on each $\frac{\partial Q_{ij}(x)}{\partial x^k}$, write $\varphi_{x^1}(x) = r \sin(t), \varphi_{x^2}(x) = r \cos(t)$.

$$\begin{aligned} \left| \frac{\partial Q_{11}(x)}{\partial x^k} \right| &= \left| \frac{\varphi_{x^1}^2 \frac{\partial \cos(\tau)}{\partial x^k}}{(\varphi_{x^1}^2 + \varphi_{x^2}^2)} + 2 \left[\frac{\varphi_{x^2x^k} \varphi_{x^1}^2 \varphi_{x^2} (1 - \cos(\tau)) + \varphi_{x^1x^\alpha} \varphi_{x^1} \varphi_{x^2}^2 (\cos(\tau) - 1)}{(\varphi_{x^1}^2 + \varphi_{x^2}^2)^2} \right] \right| \\ &\leq \left| \frac{\varphi_{x^1}^2 (\varphi_{x^1} \varphi_{x^1x^k} + \varphi_{x^2} \varphi_{x^2x^k})}{(\varphi_{x^1}^2 + \varphi_{x^2}^2) (\varphi_{x^1}^2 + \varphi_{x^2}^2 + 1)^{\frac{3}{2}}} \right| + 2 \left\| \varphi \right\|_{C^2} \left[\left| \frac{\sin^2(t) \cos(t) (1 - \cos(\tau))}{r} \right| \right. \\ &+ \left| \frac{\sin(t) \cos(t) (1 - \cos(\tau))}{r} \right| \right] \\ &\leq 2 \left\| \varphi \right\|_{C^2} \operatorname{Lip}(\varphi) + 4 \left\| \varphi \right\|_{C^2} \operatorname{Lip}(\varphi) \end{aligned}$$

By the symmetry of Q, $\frac{\partial Q_{22}}{\partial x^k}$ will have the same bound. Next, bounding $\frac{\partial Q_{12}}{\partial x^k}$;

$$\begin{aligned} \left| \frac{\partial Q_{12}}{\partial x^k} \right| &= \left| \frac{(\varphi_{x^1 x^k} \varphi_{x^2} + \varphi_{x^1} \varphi_{x^2 x^k})(\cos(\tau) - 1)}{\varphi_{x^1}^2 + \varphi_{x^2}^2} + 2 \frac{\varphi_{x^1} \varphi_{x^2}(\varphi_{x^1} \varphi_{x^1 x^k} + \varphi_{x^2} \varphi_{x^2 x^k})(1 - \cos(\tau))}{(\varphi_{x^1}^2 + \varphi_{x^2}^2)^2} - \frac{\varphi_{x^1} \varphi_{x^2}(\varphi_{x^1} \varphi_{x^1 x^k} + \varphi_{x^2} \varphi_{x^2 x^k})}{(\varphi_{x^1}^2 + \varphi_{x^2}^2)(\varphi_{x^1}^2 + \varphi_{x^2}^2 + 1)^{\frac{3}{2}}} \right| \\ &\leq \|\varphi\|_{C^2} r^2 \left(\left| \frac{r \cos(t)}{r^2} \right| + \left| \frac{r \sin(t)}{r^2} \right| \right) + 2r^4 \|\varphi\|_{C^2} \left(\left| \frac{r \cos(t)}{r^4} \right| + \left| \frac{r \sin(t)}{r^4} \right| \right) \right) \\ &\leq 6 \|\varphi\|_{C^2} \operatorname{Lip}(\varphi) \\ &\leq 6 \|\varphi\|_{C^2} . \end{aligned}$$

Again, by the symmetry of Q, $\frac{\partial Q_{21}}{\partial x^k}$ will have the same bounds. We have

$$\begin{aligned} \left| \frac{\partial Q_{13}}{\partial x^k} \right| &= \left| \frac{\varphi_{x^1 x^k}}{(\varphi_{x^1}^2 + \varphi_{x^2}^2 + 1)^{\frac{1}{2}}} - \frac{\varphi_{x^1}(\varphi_{x^1}\varphi_{x^1 x^k} + \varphi_{x^2}\varphi_{x^2 x^k})}{(\varphi_{x^1}^2 + \varphi_{x^2}^2 + 1)^{\frac{3}{2}}} \right| \\ &\leq \|\varphi\|_{C^2} + 2 \|\varphi\|_{C^2} \operatorname{Lip}(\varphi)^2 \\ &\leq 3 \|\varphi\|_{C^2} \end{aligned}$$

and $\frac{\partial Q_{23}}{\partial x^k}$, $\frac{\partial Q_{31}}{\partial x^k}$, $\frac{\partial Q_{32}}{\partial x^k}$ will have the same bounds. Finally,

$$\begin{vmatrix} \frac{\partial Q_{33}}{\partial x^k} \end{vmatrix} = \begin{vmatrix} \frac{\varphi_{x^1} \varphi_{x^1 x^k} + \varphi_{x^2} \varphi_{x^2 x^k}}{(\varphi_{x^1}^2 + \varphi_{x^2}^2 + 1)^{\frac{3}{2}}} \\ \leq 2 \operatorname{Lip}(\varphi) \|\varphi\|_{C^2} \\ \leq 2 \|\varphi\|_{C^2} .$$

This gives the result with K = 6.

LEMMA 3.9.

$$\sup\{Q_{ij}(x): i, j \in \{1, 2, 3\} \text{ and } x \in \Omega_{\varphi}\} = 1$$

Proof. First we note that $Q_{11}(0) = 1$ and so $1 \leq \sup\{Q_{ij}(x) : i, j \in \{1, 2, 3\}, x \in \Omega_{\varphi}\}$. Next we calculate

$$|Q_{11}(x)| \leq \frac{\varphi_{x^2}^2}{\varphi_{x^1}^2 + \varphi_{x^2}^2} + \frac{\varphi_{x^1}^2}{\varphi_{x^1}^2 + \varphi_{x^2}^2} = 1$$

$$|Q_{12}(x)| \leq \left| \frac{\varphi_{x^2} \varphi_{x^1} (1 - \cos(\tau))}{\varphi_{x^1}^2 + \varphi_{x^2}^2} \right| \leq \left| \frac{2\varphi_{x^2} \varphi_{x^1}}{\varphi_{x^1}^2 + \varphi_{x^2}^2} \right| \leq 1$$

$$|Q_{13}(x)| \leq \left| \frac{\varphi_{x^1}}{(\varphi_{x^1}^2 + \varphi_{x^2}^2 + 1)^{\frac{1}{2}}} \right| \leq |\varphi_{x^1}| \leq 1$$

$$|Q_{33}(x)| = |\cos(\tau)| \leq 1$$

The other terms are similar or the same.

3.2.3 **Proof of Partial Regularity**

We will use the projection Q and the following extension Lemma from [7] in order to prove a Hybrid Inequality. Note that the following lemma is stated for balls rather than cylinders.

LEMMA 3.10. There are positive constants δ , q and c such that, if $0 < \varepsilon < 1$, $\xi \in \mathbb{R}^3$, and $\eta \in W^{1,2}(\Omega_{\varphi} \cap \partial \mathbb{B}, \mathbb{S}^2)$ satisfies the small oscillation condition

$$\left[\int_{\Omega_{\varphi}\cap\partial\mathbb{B}} |\nabla_{tan}\eta|^2 d\mathcal{H}^2\right] \left[\int_{\Omega_{\varphi}\cap\partial\mathbb{B}} |\eta-\xi|^2 d\mathcal{H}^2 + \int_{\partial(\Omega_{\varphi}\cap\partial\mathbb{B})} |\eta-\xi|^2 d\mathcal{H}^1\right] \le \delta^2 \varepsilon^q \quad (3.7)$$

and if $\eta|_{\partial\Omega_{\varphi}\cap\partial\mathbb{B}}$ has image in \mathbb{S}^1 , then there exists a function $\omega \in W^{1,2}(\Omega_{\varphi}\cap\mathbb{B},\mathbb{S}^2)$, $\omega|_{\Omega_{\varphi}\cap\partial\mathbb{B}} = \eta, \omega|_{G_{\varphi}}$ has image in \mathbb{S}^1 and

$$\int_{\Omega_{\varphi} \cap \mathbb{B}} |\nabla \omega|^2 dx \le \varepsilon \int_{\Omega_{\varphi} \cap \partial \mathbb{B}} |\nabla_{tan} \eta|^2 d\mathcal{H}^2 + c\varepsilon^{-q} \left[\int_{\Omega_{\varphi} \cap \partial \mathbb{B}} |\eta - \xi|^2 d\mathcal{H}^2 + \int_{\partial(\Omega_{\varphi} \cap \partial \mathbb{B})} |\eta - \xi|^2 d\mathcal{H}^1 \right]$$

Proof. For a proof see Theorem 3.1 in [7].

We can now prove our main ingredient:

Lemma 3.11. [Hybrid inequality] There exists positive constants c_1, c_2 and q such that if $0 \leq \lambda \leq 1$, φ is as above, u is a minimizer of \mathbb{G}_{φ} amongst maps in \mathcal{U}_{φ} with fixed trace on H_{φ} such that $\int_{\Omega_{\varphi}} |\nabla u|^2 dx < c_1 \lambda^{\frac{q}{2}}$, $\operatorname{Lip}(\varphi) \leq c_1 \lambda^{\frac{q}{2}}$ and $\|\varphi\|_{C^2} \leq c_1 \lambda^{\frac{q}{2}}$, then

$$\begin{split} \left(\frac{1}{2}\right)^{-1} \int_{\Omega_{\varphi}\cap C\left(0,\frac{1}{4}\right)} \left|\nabla u\right|^{2} dx &\leq \lambda \left(\left\|\varphi\right\|_{C^{2}}^{2} + \int_{\Omega_{\varphi}\cap C(0,1)} \left|\nabla u\right|^{2} dx\right) \\ &+ \lambda^{-q} c_{2} \left(\operatorname{Lip}(\varphi)^{2} + \int_{\Omega_{\varphi}\cap C(0,1)} \left|u - \overline{u}\right|^{2} dx\right) \\ &+ \lambda^{-q} c_{2} \int_{G_{\varphi}\cap C(0,1)} \left|u - \overline{u}\right|^{2} d\mathcal{H}^{2} + c_{2} \left\|\varphi\right\|_{C^{2}}^{2}. \end{split}$$

$$where \ \overline{\overline{u}} := \mathcal{H}^{2} (G_{\varphi})^{-1} \int_{G_{\varphi}} u d\mathcal{H}^{2}. \end{split}$$

Proof. As we have the set inclusions $C(0, \frac{1}{4}) \subset B^3(0, \frac{1}{2})$ and $\mathbb{B} \subset C(0, 1)$ it suffices to prove the inequality

$$\left(\frac{1}{2}\right)^{-1} \int_{\Omega_{\varphi} \cap \mathbb{B}_{\frac{1}{2}}} |\nabla u|^2 dx \leq \lambda \left(\|\varphi\|_{C^2}^2 + \int_{\Omega_{\varphi} \cap \mathbb{B}} |\nabla u|^2 dx \right)$$

$$+ \lambda^{-q} c_2 \left(\operatorname{Lip}(\varphi)^2 + \int_{\Omega_{\varphi} \cap \mathbb{B}} \left| u - \overline{u} \right|^2 dx \right)$$

$$+ \lambda^{-q} c_2 \int_{G_{\varphi} \cap \mathbb{B}} \left| u - \overline{u} \right|^2 d\mathcal{H}^2 + c_2 \left\|\varphi\|_{C^2}^2 .$$

Let u be a map satisfying the assumptions of the Lemma. We aim to apply Lemma 3.10 to the map Q(x)u(x). In order to do this we must check the map Q(x)u(x) satisfies the small oscillation condition (3.7). We first bound

$$\begin{aligned} |\nabla(Q(x)u(x))|^2 &= \sum_{i,k,l=1}^3 \left(\frac{\partial(Q_{ij}u^j)}{\partial x^k}\right)^2 \\ &= \sum_{i,j,k} \left(\frac{\partial Q_{ij}}{\partial x^k}u^j + \frac{\partial u^j}{\partial x^k}Q_{i,j}\right)^2 \\ &\leq 2\sum_{i,j,k} \left[\left(\frac{\partial Q_{ij}}{\partial x^k}u^j\right)^2 + \left(\frac{\partial u^j}{\partial x^k}Q_{ij}\right)^2 \right] \\ &\leq 2\sum_{i,k} \left[\sum_{j=1}^3 \left(\frac{\partial Q_{i,j}}{\partial x^k}\right)^2 \sum_{l=1}^3 (u^l)^2 + \sum_{m=1}^3 \left(\frac{\partial u^m}{\partial x^k}\right)^2 \sum_{n=1}^3 (Q_{in})^2 \right] \\ &\leq 18 \left(||\varphi||_{C^2}^2 + |\nabla u|^2 \right) \end{aligned}$$
(3.8)

by Lemma 3.8 and 3.9.

As in [5], we note that for an increasing function $\eta:[0,1]\to\mathbb{R}$ we have

$$\mathcal{L}^{1}(\{s: \eta'(s) \ge 8(\eta(1) - \eta(0))\}) \le \frac{1}{8}.$$

Hence we can find $\sigma \in \left[\frac{\sqrt{2}}{2}, 1\right]$ such that $u|_{\Omega_{\varphi} \cap \partial B^{3}(0,\sigma)} \in W^{1,2}(\Omega_{\varphi} \cap \partial B^{3}(0,\sigma), \mathbb{S}^{2}),$

$$\int_{\Omega_{\varphi}\cap\partial B^{3}(0,\sigma)} \left| Qu - \overline{\overline{u}} \right|^{2} d\mathcal{H}^{2} + \int_{\partial (B^{3}(0,\sigma)\cap G_{\varphi})} \left| Qu - \overline{\overline{u}} \right|^{2} d\mathcal{H}^{1} \leq 8 \left[\int_{\Omega_{\varphi}\cap \mathbb{B}} \left| Qu - \overline{\overline{u}} \right|^{2} dx + \int_{G_{\varphi}} \left| Qu - \overline{\overline{u}} \right|^{2} d\mathcal{H}^{2} \right]$$

$$(3.9)$$

and

$$\int_{\Omega_{\varphi} \cap \partial B^{3}(0,\sigma)} |\nabla_{tan}(Qu)|^{2} d\mathcal{H}^{2} \leq 8 \int_{\Omega_{\varphi} \cap \mathbb{B}} |\nabla(Qu)|^{2} dx.$$
(3.10)

By Lemma A.3 in the Appendix, there exists a constant c independent of φ such that

$$\int_{\Omega_{\varphi}\cap\mathbb{B}} |u - \overline{\overline{u}}|^2 dx \le c \int_{\Omega_{\varphi}\cap\mathbb{B}} |\nabla u|^2 dx$$
$$\int_{G_{\varphi}} |u - \overline{\overline{u}}|^2 d\mathcal{H}^2 \le c \int_{\Omega_{\varphi}\cap\mathbb{B}} |\nabla u|^2 dx.$$
(3.11)

Combining inequalities (3.8), (3.9), (3.10), (3.11) and Lemma 3.7 we have

$$\begin{split} \left(\int_{\Omega_{\varphi} \cap \partial B^{3}(0,\sigma)} |\nabla_{tan}(Qu)|^{2} d\mathcal{H}^{2} \right) \left(\int_{\partial(B^{3}(0,\sigma) \cap G_{\varphi})} |Qu - \overline{u}|^{2} d\mathcal{H}^{1} + \int_{\Omega_{\varphi} \cap \partial B^{3}(0,\sigma)} |Qu - \overline{u}|^{2} d\mathcal{H}^{2} \right) \\ &\leq 64 \left(\int_{\Omega_{\varphi} \cap \mathbb{B}} |\nabla(Qu)|^{2} dx \right) \left(\int_{G_{\varphi}} |Qu - \overline{u}|^{2} d\mathcal{H}^{2} + \int_{\Omega_{\varphi} \cap \mathbb{B}} |Qu - \overline{u}|^{2} dx \right) \\ &\leq 2304 \left(||\varphi||_{C^{2}}^{2} \mathcal{L}^{3}(\Omega_{\varphi} \cap \mathbb{B}) + \int_{\Omega_{\varphi} \cap \mathbb{B}} |\nabla u|^{2} dx \right) \times \\ &\left(\int_{\Omega_{\varphi} \cap \mathbb{B}} |Qu - u|^{2} + |u - \overline{u}|^{2} dx + \int_{G_{\varphi}} |Qu - u|^{2} + |u - \overline{u}|^{2} d\mathcal{H}^{2} \right) \\ &\leq 2304c \left(||\varphi||_{C^{2}}^{2} + \int_{\Omega_{\varphi} \cap \mathbb{B}} |\nabla u|^{2} dx \right) \times \\ &\left(\operatorname{Lip}(\varphi) \mathcal{H}^{2}(G_{\varphi}) + \operatorname{Lip}(\varphi) \mathcal{L}^{3}(\Omega_{\varphi}) + 2c \int_{\Omega_{\varphi} \cap \mathbb{B}} |\nabla u|^{2} dx \right) \\ &\leq c \left(||\varphi||_{C^{2}}^{2} + \int_{\Omega_{\varphi} \cap \mathbb{B}} |\nabla u|^{2} dx \right) \left(\operatorname{Lip}(\varphi) + \int_{\Omega_{\varphi} \cap \mathbb{B}} |\nabla u|^{2} dx \right) \end{split}$$

where c has absorbed all constants. Note that as

$$\mathcal{L}^{3}(\Omega_{\varphi} \cap \mathbb{B}) \leq \mathcal{L}^{3}(\mathbb{B}) \text{ and } \mathcal{H}^{2}(G_{\varphi}) \leq \int_{\mathbb{B}^{2}} 1 + |\nabla \varphi|^{2} dx \leq 2\mathcal{L}^{2}(\mathbb{B}^{2})$$
 (3.12)

the constant c can be chosen to not depend on the domain. Defining $\varepsilon := a\lambda$, for some 0 < a < 1 to be chosen later, and choosing c_1 such that $c_1^2 < a^q \frac{\delta^2}{c}$, where $\delta > 0$ is the constant from Lemma 3.10, we have

$$\left(\int_{\Omega_{\varphi}\cap\partial B^{3}(0,\sigma)} |\nabla_{tan}(Qu)|^{2} d\mathcal{H}^{2}\right) \left(\int_{\partial(B^{3}(0,\sigma)\cap G_{\varphi})} |Qu-\overline{\overline{u}}|^{2} d\mathcal{H}^{1} + \int_{\Omega_{\varphi}\cap\partial B^{3}(0,\sigma)} |Qu-\overline{\overline{u}}|^{2} d\mathcal{H}^{2}\right) \leq c_{1}^{2}\lambda^{q}c \leq \varepsilon^{q}\delta^{2}.$$

It now follows that Qu satisfies the small oscillation condition of Lemma 3.10. Therefore, there exists $\omega \in W^{1,2}(\Omega_{\varphi} \cap B^{3}(0,\sigma), \mathbb{S}^{2})$ such that $\omega|_{\Omega_{\varphi} \cap \partial B^{3}(0,\sigma)} = Qu|_{\Omega_{\varphi} \cap \partial B^{3}(0,\sigma)}$, $\omega|_{G_{\varphi}\cap B^{3}(0,\sigma)}\in \tilde{\mathbb{S}}^{1}$ and

$$\begin{split} \int_{\Omega_{\varphi}\cap B^{3}(0,\sigma)} |\nabla\omega|^{2} dx &\leq c\varepsilon \int_{\Omega_{\varphi}\cap\partial B^{3}(0,\sigma)} |\nabla_{tan}Qu|^{2} d\mathcal{H}^{2} \\ &+ c\varepsilon^{-q} \left[\int_{\Omega_{\varphi}\cap\partial B^{3}(0,\sigma)} \left|Qu - \overline{\overline{u}}\right|^{2} d\mathcal{H}^{2} + \int_{\partial(\Omega_{\varphi}\cap\partial B^{3}(0,\sigma))} \left|Qu - \overline{\overline{u}}\right|^{2} d\mathcal{H}^{1} \right]. \end{split}$$

Using (3.8), (3.9), (3.10), (3.11), (3.12) and Lemma 3.7 we bound

where c has absorbed all constants.

We now use the inverse of the matrix Q(x) in order to get a map that belongs to \mathcal{U}_{φ} . For a given point $x \in \partial \Omega_{\varphi}$ the matrix $[Q(x)]^{-1}$ is given by $Q(x)^{T}$, thus using the symmetry of Q we can write $[Q(x)]^{-1}$ out explicitly as

$$[Q(x)]^{-1} = \begin{bmatrix} Q_{11}(x) & Q_{12}(x) & -Q_{13}(x) \\ Q_{21}(x) & Q_{22}(x) & -Q_{23}(x) \\ -Q_{31}(x) & -Q_{32}(x) & Q_{33}(x) \end{bmatrix},$$

where $Q_{ij}(x)$ are the entries of the matrix Q(x). By the same calculations as before the map $x \mapsto [Q(x)]^{-1}$ is C^1 and satisfies the bound

$$\left|\nabla([Q(x)]^{-1}\omega(s))\right|^{2} \le 18\left(\|\varphi\|_{C^{2}}^{2} + c|\nabla\omega|^{2}\right).$$
(3.14)

Moreover, as $\omega|_{G_{\varphi}\cap B^{3}(0,\sigma)} \in \tilde{\mathbb{S}}^{1}$ we have $\tilde{w}(x) := [Q(x)]^{-1}\omega(x) \in \mathcal{U}_{\Omega_{\varphi}\cap B^{3}(0,\sigma)}$ and $\tilde{w}(x)|_{\Omega_{\varphi}\cap\partial B^{3}(0,\sigma)} = u|_{\Omega_{\varphi}\cap\partial B^{3}(0,\sigma)}.$

Using that $\sigma > \frac{1}{2}$ and the minimality of u we have

$$\begin{split} &\int_{\Omega_{\varphi}\cap B^{3}(0,\frac{1}{2})} |\nabla u|^{2} dx - K_{13} \int_{G_{\varphi}\cap B^{3}(0,\frac{1}{2})} u^{\alpha} u^{\beta} \frac{\partial \nu^{\alpha}}{\partial x^{\beta}} d\mathcal{H}^{2} \\ &\leq \int_{\Omega_{\varphi}\cap B^{3}(0,\sigma)} |\nabla u|^{2} dx - K_{13} \int_{G_{\varphi}\cap B^{3}(0,\sigma)} u^{\alpha} u^{\beta} \frac{\partial \nu^{\alpha}}{\partial x^{\beta}} d\mathcal{H}^{2} \\ &+ K_{13} \left[\int_{G_{\varphi}\cap B^{3}(0,\sigma)} u^{\alpha} u^{\beta} \frac{\partial \nu^{\alpha}}{\partial x^{\beta}} d\mathcal{H}^{2} - \int_{G_{\varphi}\cap B^{3}(0,\frac{1}{2})} u^{\alpha} u^{\beta} \frac{\partial \nu^{\alpha}}{\partial x^{\beta}} d\mathcal{H}^{2} \right] \\ &\leq \int_{\Omega_{\varphi}\cap B^{3}(0,\sigma)} |\nabla \tilde{w}|^{2} dx \\ &+ K_{13} \left[\int_{G_{\varphi}\cap B^{3}(0,\sigma)} \left(u^{\alpha} u^{\beta} - \tilde{w}^{\alpha} \tilde{w}^{\beta} \right) \frac{\partial \nu^{\alpha}}{\partial x^{\beta}} d\mathcal{H}^{2} - \int_{G_{\varphi}\cap B^{3}(0,\frac{1}{2})} u^{\alpha} u^{\beta} \frac{\partial \nu^{\alpha}}{\partial x^{\beta}} d\mathcal{H}^{2} \right] \end{split}$$

which implies the inequality

$$\int_{\Omega_{\varphi}\cap B^{3}(0,\frac{1}{2})} |\nabla u|^{2} dx \leq \int_{\Omega_{\varphi}\cap B^{3}(0,\sigma)} |\nabla \tilde{w}|^{2} dx + K_{13} \left[\int_{G_{\varphi}\cap B^{3}(0,\sigma)} \left(u^{\alpha} u^{\beta} - \tilde{w}^{\alpha} \tilde{w}^{\beta} \right) \frac{\partial \nu^{\alpha}}{\partial x^{\beta}} d\mathcal{H}^{2} \right].$$

Next we apply (3.14) and (3.13), choose $a < \frac{1}{18c}$ and substitute $\varepsilon = a\lambda$ to get the bound

$$\begin{split} \int_{\Omega_{\varphi}\cap B^{3}(0,\sigma)} |\nabla \tilde{w}|^{2} dx &\leq \int_{\Omega_{\varphi}\cap B^{3}(0,\sigma)} 18 \left(\left\|\varphi\right\|_{C^{2}}^{2} + c|\nabla \omega|^{2} \right) dx \\ &\leq 18 \left(c\varepsilon \left(\left\|\varphi\right\|_{C^{2}}^{2} + \int_{\Omega_{\varphi}\cap \mathbb{B}} |\nabla u|^{2} dx \right) \right) \\ &+ c\varepsilon^{-q} \left[\operatorname{Lip}(\varphi)^{2} + \int_{\Omega_{\varphi}} \left|u - \overline{u}\right|^{2} dx + \int_{G_{\varphi}} \left|u - \overline{u}\right|^{2} d\mathcal{H}^{2} \right] \right) \\ &+ 18 \left\|\varphi\right\|_{C^{2}}^{2} \mathcal{L}^{3}(\Omega_{\varphi}) \\ &\leq \lambda \left(\left\|\varphi\right\|_{C^{2}}^{2} + \int_{\Omega_{\varphi}\cap \mathbb{B}} |\nabla u|^{2} dx \right) \\ &+ \lambda^{-q} c_{2} \left(\operatorname{Lip}(\varphi)^{2} + \int_{\Omega_{\varphi}\cap \mathbb{B}} \left|u - \overline{u}\right|^{2} dx + \int_{G_{\varphi}} \left|u - \overline{u}\right|^{2} d\mathcal{H}^{2} \right) \\ &+ c_{2} \left\|\varphi\right\|_{C^{2}}^{2}. \end{split}$$

On the other hand, as u and \tilde{w} are both \mathbb{S}^2 valued, we have

$$K_{13}\left[\int_{G_{\varphi}\cap B^{3}(0,\sigma)} \left(u^{\alpha}u^{\beta} - \tilde{w}^{\alpha}\tilde{w}^{\beta}\right) \frac{\partial\nu^{\alpha}}{\partial x^{\beta}} d\mathcal{H}^{2}\right] \leq |K_{13}| \int_{G_{\varphi}\cap B^{3}(0,\sigma)} \left|u^{\alpha}u^{\beta} - \tilde{w}^{\alpha}\tilde{w}^{\beta}\right| \left|\frac{\partial\nu^{\alpha}}{\partial x^{\beta}}\right| d\mathcal{H}^{2}$$
$$\leq c \int_{G_{\varphi}\cap B^{3}(0,\sigma)} \left|\frac{\partial\nu^{\alpha}}{\partial x^{\beta}}\right| d\mathcal{H}^{2}.$$

A straight forward calculation gives

$$\frac{\partial\nu}{\partial x^{\beta}} = \left[\frac{\left(-\varphi_{x^{1},x^{\beta}},-\varphi_{x^{2},x^{\beta}},0\right)}{\left(\varphi_{x^{1}}^{2}+\varphi_{x^{2}}^{2}+1\right)^{\frac{1}{2}}} - \frac{\left(\varphi_{x^{1},x^{\beta}}\varphi_{x^{1}}+\varphi_{x^{2},x^{\beta}}\varphi_{x^{2}}\right)\left(-\varphi_{x^{1}},-\varphi_{x^{2}},1\right)}{\left(\varphi_{x^{1}}^{2}+\varphi_{x^{2}}^{2}+1\right)^{\frac{3}{2}}}\right]$$

hence

$$\left|\frac{\partial\nu^{\alpha}}{\partial x^{\beta}}\right| \leq 3 \left\|\varphi\right\|_{C^{2}}.$$

Recalling that $\mathcal{H}^2(G_{\varphi})$ is bounded for all φ we complete the proof.

Lemma 3.12. [Energy Improvement] There are positive constants ε , c and $\theta < 1$ such that if φ is as in (3.5), u is a minimizer of \mathbb{G}_{φ} amongst maps in \mathcal{U}_{φ} with fixed trace on H_{φ} and $\int_{\Omega_{\varphi}} |\nabla u|^2 dx \leq \varepsilon^2$, then

$$\frac{1}{\theta} \int_{C(0,\theta)\cap\Omega_{\varphi}} |\nabla u|^2 dx \le \theta \max\{\int_{\Omega_{\varphi}} |\nabla u|^2 dx, c \left(\operatorname{Lip}(\varphi) + \|\varphi\|_{C^2}\right)\}$$
(3.15)

Proof. Suppose, for a contradiction, that for fixed $0 < \theta < 1$ there are sequences $(u_i), (\varphi_i), (\varepsilon_i)$ such that u_i is minimizing in Ω_{φ_i} and $\varepsilon_i^2 = \int_{\Omega_{\varphi_i}} |\nabla u_i|^2 dx \to 0$ as $i \to \infty$, but

$$\frac{1}{\theta} \int_{C(0,\theta)\cap\Omega_{\varphi_i}} |\nabla u_i|^2 dx > \theta \max\left\{ \int_{\Omega_{\varphi_i}} |\nabla u_i|^2 dx, i \left(\operatorname{Lip}(\varphi_i) + \|\varphi_i\|_{C^2} \right) \right\}.$$

This implies that

$$\frac{1}{\theta} \int_{C(0,\theta)\cap\Omega_{\varphi_i}} |\nabla u_i|^2 dx > \theta \varepsilon_i^2, \tag{3.16}$$

$$\frac{\operatorname{Lip}(\varphi_i)}{\varepsilon_i^2} \to 0, \qquad (3.17)$$

$$\frac{\|\varphi_i\|_{C^2}}{\varepsilon_i^2} \to 0. \tag{3.18}$$

We now consider the normalised functions

$$v_i = \varepsilon_i^{-1} (u_i - \overline{\overline{u}}_i).$$

Then, by Lemma A.3, the sequence $\left\{ \|v_i\|_{W^{1,2}(\Omega_{\varphi_i})} \right\}_{i=1}^{\infty}$ is a bounded sequence in \mathbb{R} . As each v_i is defined on a different domain we extend them all to a common domain using the extension Lemma A.1 that can be found in the appendix. Let $\mathcal{C} = \{x \in \mathbb{R}^3 : |(x^1, x^2)| < 1 \text{ and } -1 < x^3 < \frac{1}{2}\}$. Then there exists, by Lemma A.1, a constant c, that is independent of i, and functions $\widehat{v}_i \in W^{1,2}(\mathcal{C})$ such that $v_i = \widehat{v}_i|_{\Omega_{\varphi_i}}$ and

$$\left\|\widehat{v}_{i}\right\|_{W^{1,2}(\mathcal{C})} \leq c \left\|v_{i}\right\|_{W^{1,2}(\Omega_{\varphi_{i}})}$$

(note that $\Omega_{\varphi_i} \subset \mathcal{C}$ for *i* sufficiently large and so we assume $\Omega_{\varphi_i} \subset \mathcal{C}$ for all *i*). As $\widehat{v_i}$ is bounded in $W^{1,2}(\mathcal{C})$ there exists $\widehat{v} \in W^{1,2}(\mathcal{C})$ such that $\widehat{v_i}$ converges weakly (on a subsequence) to \widehat{v} in $W^{1,2}(\mathcal{C})$. Define $v \in W^{1,2}(\Omega_0)$ as $v := \widehat{v}|_{\Omega_0}$.

We claim that the function v is harmonic. In order to see this we first note that as u_i are minimizers and $u_i(x) \cdot \nu(x) = 0$ for $x \in \partial G_{\varphi_i}$ we have that u_i satisfies

$$\int_{\Omega_{\varphi_i}} \langle \nabla u_i, \nabla \zeta \rangle - |\nabla u_i|^2 u_i \cdot \zeta dx = 0, \qquad (3.19)$$

for all $\zeta \in C_0^{\infty}(\Omega_{\varphi_i})$. Let $\zeta \in C^{\infty}(\mathbb{R}^3)$ be such that $spt(\zeta) \subset \Omega_0$. Then for sufficiently large *i* we have $spt(\zeta) \subset \Omega_{\varphi_i}$. Observing that $\nabla u_i = \varepsilon_i \nabla v_i$, substituting this into (3.19) and dividing by ε_i yields

$$0 = \int_{\Omega_{\varphi_i}} \langle \nabla v_i, \nabla \zeta \rangle - \varepsilon_i |\nabla v_i|^2 u_i \cdot \zeta dx.$$

Using the uniform bounds on $|\nabla v_i|^2$, u_i and ζ , we see that the second term tends to 0 as $i \to \infty$. As $spt(\zeta) \subset \Omega_0 \subset \mathcal{C}$ and we have that $spt(\zeta) \subset \Omega_{\varphi_i} \subset \mathcal{C}$ for i large enough, we can use the weak convergence of \hat{v}_i to \hat{v} to get

$$0 = \lim_{i \to \infty} \int_{\Omega_{\varphi_i}} \langle \nabla v_i, \nabla \zeta \rangle - \varepsilon_i |\nabla v_i|^2 u_i \cdot \zeta dx$$
$$= \lim_{i \to \infty} \left[\int_{\mathcal{C}} \langle \nabla v_i, \nabla \zeta \rangle dx \right] + 0$$
$$= \int_{\mathcal{C}} \langle \nabla v, \nabla \zeta \rangle dx$$
$$= \int_{\Omega_0} \langle \nabla v, \nabla \zeta \rangle dx.$$

Therefore v is harmonic in Ω_0 .

We now examine the behaviour of v on G_0 and we will show that v is regular up to the boundary. In order to do so we introduce the following subspaces of \mathbb{S}^2 :

$$\Sigma_x^i := \{ y \in \mathbb{S}^2 : y \cdot \nu(x^1, x^2, \varphi_i(x^1, x^2)) = 0 \}$$

$$\Sigma_0 := \{ y \in \mathbb{S}^2 : y \cdot (0, 0, 1) = 0 \}.$$

Claim: $v(x) \in \operatorname{Tan}(\Sigma_0, a)$ for \mathcal{H}^2 almost everywhere $x \in G_0$.

Proof of Claim: For each *i* let Q_i be the projection defined by (3.6) (that now depends on *i*). Let $\tilde{u}_i : \Omega_0 \to \mathbb{S}^2$ be the functions defined by

$$\tilde{u}_i(x) := u_i(\tilde{x}_i), \quad \text{where } \tilde{x}_i := (x^1, x^2, x^3 + \varphi_i(x^1, x^2)).$$

and \tilde{v}_i to be the functions

$$\tilde{v}_i = \varepsilon_i^{-1} (\tilde{u}_i - \overline{\overline{u}}_i).$$

Note that for almost every $x \in \Omega_0$ we have $\tilde{v}_i(x) \to v(x)$. As $u_i(x) \in \Sigma_x^i$ for almost every $x \in G_{\varphi_i}$, we have $Q_i(\tilde{x}_i) \cdot \tilde{u}_i(x) \in \Sigma_0$ for almost every $x \in G_0$. Then for almost every $x \in G_0$ we have

$$\operatorname{dist}(\overline{\overline{u}}_i, \Sigma_0)^2 \le \left| Q_i(\tilde{x}_i)\tilde{u}_i(x) - \overline{\overline{u}}_i \right|^2.$$

Averaging this over G_0 and using Lemma 3.7, relation (3.17) and the Poincaré inequalities gives

$$\operatorname{dist}(\overline{\overline{u}}_{i}, \Sigma_{0})^{2} \leq \left[\mathcal{H}^{2}(G_{0})\right]^{-1} \int_{G_{0}} \left|Q_{i}(x)\tilde{u}_{i} - \overline{\overline{u}}_{i}\right|^{2} d\mathcal{H}^{2}$$

$$\leq 2\left[\mathcal{H}^{2}(G_{0})\right]^{-1} \left(\int_{G_{0}} \left|Q_{i}(\tilde{x}_{i})\tilde{u}_{i}(x) - \tilde{u}_{i}(x)\right|^{2} + \left|\tilde{u}_{i} - \overline{\overline{u}}_{i}\right|^{2} \mathcal{H}^{2}\right)$$

$$\leq c\varepsilon_{i}^{2}. \tag{3.20}$$

Hence, for *i* sufficiently large, there is a unique nearest point a_i of $\overline{\overline{u}}_i$ on Σ_0 . As $(\overline{\overline{u}}_i)_{i\in\mathbb{N}}$ is a bounded sequence in \mathbb{R}^3 it has a subsequence converging to some $a \in \mathbb{R}^3$. Also $\varepsilon_i^{-1} |\overline{\overline{u}}_i - a_i| = \frac{\operatorname{dist}(\overline{\overline{u}}_i, \Sigma_0)}{\varepsilon_i} \leq \frac{\sqrt{c}\varepsilon_i}{\varepsilon_i} = \sqrt{c}$, is bounded. Thus on subsequence we have

$$\lim_{i \to \infty} \overline{\overline{u}}_i = a \in \Sigma_0 \text{ and } \lim_{i \to} \varepsilon_i^{-1} (\overline{\overline{u}}_i - a_i) = w \in \mathbb{R}^3.$$

As $(\overline{\overline{u}}_i - a_i) \in \operatorname{Nor}(\Sigma_0, a_i)$ and $a_i \to a$ we have $w \in \operatorname{Nor}(\Sigma_0, a)$. For almost every $x \in G_0, \tilde{v}_i(x) \to v(x)$ as $i \to \infty$. For such an x and i sufficiently large we have that

$$(x^1, x^2, x^3 + \varphi_i(x^1, x^2)) \in G_{\varphi_i}$$

and hence $\tilde{u}_i(x) \in \Sigma^i_{\tilde{x}_i}$. We compute

$$\lim_{i \to \infty} \varepsilon_i^{-1} (Q_i(x) \tilde{u}_i(x) - \overline{\overline{u}}_i) = \lim_{i \to \infty} \left(\varepsilon_i^{-1} (Q_i(x) \tilde{u}_i(x) - \tilde{u}_i(x)) + \varepsilon_i^{-1} (\tilde{u}_i(x) - \overline{\overline{u}}_i) \right)$$
$$= \lim_{i \to \infty} \varepsilon_i^{-1} (Q_i(x) \tilde{u}_i(x) - \tilde{u}_i(x)) + v(x),$$

using Lemma 3.7

$$\lim_{i \to \infty} \varepsilon_i^{-1} |Q_i(x)\tilde{u}_i(x) - \tilde{u}_i(x)| \le \lim_{i \to \infty} c \frac{\operatorname{Lip}(\varphi_i)}{\varepsilon_i} = 0.$$

Thus

$$\lim_{i \to \infty} \varepsilon_i^{-1} \left(Q_i(x) \tilde{u}_i(x) - \overline{\overline{u}}_i \right) = v(x) \text{ for almost every } x \in G_0.$$

As $\varepsilon_i^{-1}(Q_i(x)\tilde{u}_i(x) - a_i)$ approaches a vector in $\operatorname{Tan}(\Sigma_0, a)$ and $w \in \operatorname{Nor}(\Sigma_0, a)$, we have

$$\varepsilon_i^{-1}(\tilde{u}_i(x) - a_i) \cdot \varepsilon_i^{-1}(\overline{\overline{u}}_i - a_i) \to 0 \text{ as } i \to \infty.$$

Thus

$$v(x) \cdot (-w) = \lim_{i \to} \varepsilon_i^{-1} (\tilde{u}_i(x) - \overline{\overline{u}}_i) \cdot \varepsilon_i^{-1} (a_i - \overline{\overline{u}}_i)$$

$$= \lim_{i \to} \left(\varepsilon_i^{-1} (\tilde{u}_i(x) - a_i) \varepsilon_i^{-1} (a_i - \overline{\overline{u}}_i) \right) \cdot \varepsilon_i^{-1} (a_i - \overline{\overline{u}}_i)$$

$$= |w|^2.$$

By averaging over G_0 we deduce $|w|^2 = \overline{\overline{v}}(-w) = 0$, hence

$$v(x) = v(x) + w$$

= $\lim_{i \to \infty} \varepsilon_i^{-1}(Q_i(x)\tilde{u}_i(x) - \overline{\overline{u}}_i) + \lim_{i \to \infty} \varepsilon_i^{-1}(\overline{\overline{u}}_i - a_i)$
= $\lim_{i \to \infty} \varepsilon_i^{-1}(Q_i(x)\tilde{u}_i(x) - a_i) \in \operatorname{Tan}(\Sigma_0, a).$

This proves the claim.

Next we decompose $v = v^{\top} + v^{\perp}$, where $v^{\top} \in \operatorname{Tan}(\Sigma_0, a)$ and $v^{\perp} \in \operatorname{Nor}(\Sigma_0, a)$. We deduce that both v^{\top} and v^{\perp} are Harmonic inside Ω_0 and that v^{\perp} is regular up to G_0 because it satisfies the boundary condition

$$v^{\perp} = 0$$
 on G_0 .

To verify the regularity of v^{\top} up to G_0 we show v^{\top} satisfies the Neumann boundary condition

$$\frac{\partial}{\partial x_m} v^\top = 0 \text{ on } G_0$$

in a weak sense, i.e

$$\int_{\Omega_0} \nabla v \cdot \nabla \xi \, dx = 0$$

for any $\xi \in C^{\infty}(\overline{\Omega_0}, \operatorname{Tan}(\Sigma_0, a))$ with $(\partial \Omega_0 \setminus G_0) \cap \operatorname{Spt}(\xi) = \emptyset$. For this purpose choose an open neighbourhood U of Σ_0 in \mathbb{R}^3 such that every point $y \in U$ has a unique nearest point on Σ_0 . For $x \in G_{\varphi_i}$ and $y \in U$, define the 1-dimensional subspaces of \mathbb{R}^3 as

$$T_i(x,y) = \{t(y \times \nu_i(x)) + y : t \in \mathbb{R}\}.$$

Then for $x = (x^1, x^2, x^3) \in \Omega_{\varphi_i}$ and $y \in U$, define

$$T_i(x,y) := T_i((x^1, x^2, \varphi_i(x^1, x^2)), y).$$

We then have that $\{T_i(x, y) : x \in \Omega_{\varphi_i}, y \in U\}$ is a smooth field of 1 dimensional subspaces such that

$$T_i(x,y) \subseteq \operatorname{Tan}(\mathbb{S}^2,y) \text{ for } x \in G_{\varphi_i}, y \in \mathbb{S}^2 \cap U$$

and

$$T_i(x,y) = \operatorname{Tan}(\Sigma_x^i, y) \text{ for } x \in G_{\varphi_i} \text{ and } y \in \Sigma_x^i$$

Next, define $\Pi_i : \Omega_{\varphi_i} \times U \times \mathbb{R}^3 \to \mathbb{R}^3$ such that for $(x, y, z) \in \Omega_{\varphi_i} \times U \times \mathbb{R}^3$, $\Pi_i(x, y, z)$ is the orthogonal projection of z onto $T_i(x, y)$. Explicitly Π_i is given by

$$\Pi_{i}(x, y, z) = \frac{\left[(y \times \nu_{i}(x)) \otimes (y \times \nu_{i}(x))\right] z}{|y \times \nu_{i}(x)|^{2}} + y.$$
(3.21)

We have the following bounds on the derivatives of Π_i :

$$\left|\frac{\partial \Pi_i(x,y,z)}{\partial x^j}\right| < C\varepsilon_i^2 |z|, \qquad \left|\frac{\partial \Pi_i(x,y,z)}{\partial z^j}\right| \le 1, \qquad \left|\frac{\partial \Pi_i(x,y,z)}{\partial y^j}\right| < C|z|, \quad (3.22)$$

the proof these bounds can be found in Lemma B.1 of the appendix.

We are now in a position to show that

$$\int_{\Omega_0} \nabla v \cdot \nabla \xi dx = 0.$$

We use the cut off function

$$\lambda_{\delta}(t) := \begin{cases} 1 & \text{if } 0 \le t \le \frac{\delta}{2}, \\ 2 - 2\delta^{-1}t & \text{if } \frac{\delta}{2} < t \le \delta, \\ 0 & \text{if } \delta < t. \end{cases}$$

to define

$$\xi_i(x) = \lambda_{\delta_i}(\operatorname{dist}(u_i(x), \Sigma_0)) \cdot \Pi_i(x, u_i(x), \xi(x)),$$

where δ_i will be determined later. We have

$$\begin{cases} \xi_i(x) \in \operatorname{Tan}(\mathbb{S}^2, u_i(x)) \text{ for } x \in \Omega_{\varphi_i}, \\ \xi_i(x) \in \operatorname{Tan}(\Sigma_x^i, u_i(x)) \text{ for } x \in G_{\varphi_i}. \end{cases}$$

Next, for $x \in \overline{\Omega}_{\varphi_i}$ let $u_i^t(x)$ be the solution of

$$\begin{cases} \left(\frac{d}{dt}\right) u_i^t(x) = \xi_i(x), \\ u_i^0(x) = u_i(x). \end{cases}$$

Then $u_i^t \in W^{1,2}(\Omega_{\varphi_i}, \mathbb{S}^2)$ with $\frac{d}{dt}u_i^t \in \operatorname{Tan}(\Sigma_x^i, u_i(x))$ for $x \in G_{\varphi_i}$, hence $u_i^t(x) \in \Sigma_x^i$ for $x \in G_{\varphi_i}$ and $u_i^t(x) = u_i(x)$ for $x \in \partial\Omega_{\varphi_i} \setminus G_{\varphi_i}$. The minimality of u_i implies that

$$0 = \frac{d}{dt} \Big|_{t=0} \int_{\Omega_{\varphi_i}} |\nabla u_i^t(x)|^2 dx - K_{13} \int_{G_{\varphi_i}} u_i^{t,\alpha} u_i^{t,\beta} \frac{\partial \nu^{\beta}}{\partial x^{\alpha}} d\mathcal{H}^2$$

= $2 \int_{\Omega_{\varphi_i}} \nabla u_i \nabla \xi_i dx - K_{13} \int_{G_{\varphi_i}} \xi_i^{\alpha} u_i^{\beta} \frac{\partial \nu^{\beta}}{\partial x^{\alpha}} + \xi_i^{\beta} u_i^{\alpha} \frac{\partial \nu^{\beta}}{\partial x^{\alpha}} d\mathcal{H}^2.$

Let $A_i = \{x \in \overline{\Omega}_{\varphi_i} : |u_i(x) - \overline{\overline{u}}_i|^2 \ge \frac{\delta_i^2}{4}\}$. We have

$$\int_{A_i} \frac{\delta_i^2}{4} \, dx \le \int_{A_i} \left| u_i(x) - \overline{\overline{u}}_i \right|^2 \, dx \le \int_{\Omega_{\psi_i}} \left| u_i(x) - \overline{\overline{u}}_i \right|^2 \, dx \le c \int_{\Omega_{\psi_i}} \left| \nabla u_i \right|^2 \, dx \le c \varepsilon_i^2$$

and hence

$$\mathcal{L}^3(A_i) \le 4c\varepsilon_i^2 \delta_i^{-2}. \tag{3.23}$$

Setting $B_i = \Omega_{\varphi_i} \setminus A_i$ we have

$$\begin{split} \left| \int_{\Omega_{\varphi_i}} \nabla v_i \cdot \nabla \xi \, dx \right| &= \varepsilon_i^{-1} \left| \int_{\Omega_{\varphi_i}} \nabla u_i \cdot \nabla \xi - \nabla u_i \cdot \nabla \xi_i \, dx \right. \\ &+ \frac{K_{13}}{2} \int_{G_{\varphi_i}} \xi_i^{\alpha} u_i^{\beta} \frac{\partial \nu^{\beta}}{\partial x^{\alpha}} + \xi_i^{\beta} u_i^{\alpha} \frac{\partial \nu^{\beta}}{\partial x^{\alpha}} \, d\mathcal{H}^2 \right| \\ &\leq \varepsilon_i^{-1} \left| \int_{A_i} \nabla u_i \cdot (\nabla \xi - \nabla \xi_i) \, dx \right| + \varepsilon_i^{-1} \left| \int_{B_i} \nabla u_i \cdot (\nabla \xi - \nabla \xi_i) \, dx \right| \\ &= U_i + \varepsilon_i^{-1} \left| \frac{K_{13}}{2} \int_{G_{\varphi_i}} \xi_i^{\alpha} u_i^{\beta} \frac{\partial \nu^{\beta}}{\partial x^{\alpha}} + \xi_i^{\beta} u_i^{\alpha} \frac{\partial \nu^{\beta}}{\partial x^{\alpha}} \, d\mathcal{H}^2 \right| \\ &\leq I_i + II_i + c\varepsilon_i^{-1} \mathcal{H}^2(G_{\varphi_i}) \|\varphi_i\|_{C^2}. \end{split}$$

We have that $\varepsilon_i^{-1} c \mathcal{H}^2(G_{\varphi_i}) \|\varphi_i\|_{C^2} \to 0$ as $i \to \infty$ and so we must show that $I_i, II_i \to 0$ as $i \to 0$.

 $I_i \rightarrow 0$

Using Hölder we have

$$I_{i} \leq \varepsilon_{i}^{-1} \left(\int_{A_{i}} |\nabla u_{i}|^{2} dx \right)^{\frac{1}{2}} \left(2 \left(\int_{A_{i}} |\nabla \xi|^{2} dx + \int_{A_{i}} |\nabla \xi_{i}|^{2} dx \right) \right)^{\frac{1}{2}} \\ \leq \varepsilon_{i}^{-1} (\varepsilon_{i}^{2})^{\frac{1}{2}} \left(2 (c \varepsilon_{i}^{2} \delta_{i}^{-2}) + 2 \int_{A_{i}} |\nabla \xi_{i}|^{2} dx \right) \quad (\text{ as } |\nabla \xi(x)| < c \text{ for some } c). \quad (3.24)$$

$$(3.25)$$

We now focus on $|\nabla \xi_i|^2$. Writing

 $\Pi_i(x, y, z) = \left(\Pi_i^1(x, y, z), \Pi_i^2(x, y, z), \Pi_i^3(x, y, z)\right), \quad u_i = (u_i^1, u_i^2, u_i^3) \quad \text{and } \xi = (\xi^1, \xi^2, \xi^3),$

we have

$$\begin{split} \left| \frac{\partial \xi_i^k}{\partial x^j} \right|^2 &= \left| \frac{\partial}{\partial x^j} \left(\lambda_{\delta_i} (\operatorname{dist}(u_i(x), \Sigma_0)) \Pi_i^k(x, u_i(x), \xi(x))) \right|^2 \\ &= \left| \lambda_{\delta_i}' (\operatorname{dist}(u_i(x), \Sigma_0)) \left(\sum_{l=1}^3 \frac{\partial u_i^l(x)}{\partial x^j} \frac{\partial (\operatorname{dist}(u_i(x), \Sigma_0))}{\partial x^l} \right) \Pi_i^k(x, u_i(x), \xi(x)) \right. \\ &\quad + \lambda_{\delta_i} (\operatorname{dist}(u_i(x), \Sigma_0)) \frac{\partial}{\partial x^j} \left(\Pi_i^k(x, u_i(x), \xi(x)) \right) \right|^2 \\ &\leq c \delta_i^{-1} \left| \sum_{l=1}^3 \frac{\partial u_i^l(x)}{\partial x^j} \right|^2 + 2 \left| \sum_{l=1}^3 \left[\frac{\partial \Pi_i^k(x, u_i(x), \xi(x))}{\partial x^j} \delta_{lj} \right. \\ &\quad + \frac{\partial \Pi_i^k(x, u_i(x), \xi(x))}{\partial y^l} \frac{\partial u_i^l(x)}{\partial x^j} + \frac{\partial \Pi_i^k(x, u_i(x), \xi(x))}{\partial z^l} \frac{\partial \xi^l(x)}{\partial x^j} \right] \right|^2 \\ &\leq c \delta_i^{-1} \sum_{l=1}^3 \left| \frac{\partial u_i^l(x)}{\partial x^j} \right|^2 + c \sum_{l=1}^3 \left| \frac{\partial \Pi_i^k}{\partial x^l}(x, u_i(x), \xi(x)) \right|^2 + c \sum_{l=1}^3 \left| \frac{\partial \xi^l(x)}{\partial x^j} \right|^2 +$$

where in the last line we have used (3.22). Summing this inequality over j, k, using

the estimates (3.22), (3.23) and the fact that $\int_{\Omega_{\varphi_i}} |\nabla u|^2 dx = \varepsilon_i^2$ yields

$$\begin{split} \int_{A_i} |\nabla \xi_i|^2 dx &= \int_{A_i} \sum_{i,j=1}^3 \left| \frac{\partial \xi_i^k(x)}{\partial x^j} \right|^2 dx \\ &\leq \int_{A_i} \sum_{i,j=1}^3 \left[c \delta_i^{-1} \sum_{l=1}^3 \left| \frac{\partial u_i^l}{\partial x^j} \right|^2 + c \sum_{l=1}^3 \left| \frac{\partial \Pi_i^k(x, u_i(x), \xi(x))}{\partial x_l} \right|^2 \\ &+ c \sum_{l=1}^3 \left| \frac{\partial u_i^l(x)}{\partial x^j} \right|^2 + c \sum_{l=1}^3 \left| \frac{\partial \xi^l(x)}{\partial x^j} \right|^2 \right] dx \\ &\leq c \delta_i^{-1} \varepsilon_i^2 + c \varepsilon_i^2 + c \varepsilon_i^2 + c \varepsilon_i^2 \delta_i^{-2} \\ &\leq c \delta_i^{-1} \varepsilon_i^2 + 4 c \varepsilon_i^2 \delta_i^{-2} (c+c) + c \varepsilon_i^2. \end{split}$$
(3.26)

Therefore, by combining (3.24) and (3.26) we get

$$I_i \le 2(c\varepsilon_i^2 \delta_i^{-1}) + c\delta_i^{-1}\varepsilon_i^2 + 4c\varepsilon_i^2 \delta_i^{-2}(c\varepsilon_i^2 + c) + c\varepsilon_i^2 \to 0 \text{ as } i \to \infty,$$

providing $\delta_i = \varepsilon_i^{\frac{1}{3}} b$, where b is a constant to be chosen later. We now show $II_i \to 0$. Recall that for $x \in B_i$ we have $|u_i(x) - \overline{\overline{u}}_i| \leq \frac{\delta_i}{4}$ and so for $x \in B_i$

$$\operatorname{dist}(u_i(x), \Sigma_0) \leq \operatorname{dist}(u_i(x), \overline{\overline{u}}_i) + \operatorname{dist}(\overline{\overline{u}_i}, \Sigma_0)$$
$$\leq \frac{\delta_i}{4} + c\varepsilon_i \qquad \text{(by inequality 3.20)}$$
$$\leq \frac{\delta_i}{2} \qquad (\text{ providing } \delta_i = 4c\varepsilon_i^{\frac{1}{3}}).$$

For $x \in B_i$ we have

$$\xi_i(x) = \lambda_{\delta_i}(\operatorname{dist}(u_i(x), \Sigma_0)) \cdot \Pi_i(x, u_i(x), \xi(x))$$

= $\Pi_i(x, u_i(x), \xi(x)).$

As
$$\xi \in \operatorname{Tan}(\Sigma_0, a)$$
 we have $\xi(x) = \Pi_i(0, a, \xi(x))$, hence
 $\varepsilon_i^{-1} \left| \int_{B_i} \nabla u_i \left(\nabla \xi - \nabla \xi_i \right) dx \right| = \varepsilon_i^{-1} \left| \int_{B_i} \nabla u_i \left(\nabla \Pi_i(0, a, \xi) - \nabla \Pi_i(x, u_i(x), \xi) \right) dx \right|$
 $\leq \varepsilon_i^{-1} \left| \int_{B_i} \nabla u_i \left(\nabla \Pi_i(0, a, \xi) - \nabla \Pi_i(0, \overline{\overline{u}}_i, \xi) \right) dx \right|$
 $:=III_i$
 $+ \varepsilon_i^{-1} \left| \int_{B_i} \nabla u_i \left(\nabla \Pi_i(x, u_i(x), \xi) - \nabla \Pi_i(0, \overline{\overline{u}}_i, \xi) \right) dx \right|$
 $:=IV_i$

We now show that III_i and IV_i both go to zero separately. Using Hölder's inequality and Lemma B.2 from the appendix we estimate

$$\begin{split} III_{i} &\leq \varepsilon_{i}^{-1} \left(\int_{B_{i}} |\nabla u_{i}|^{2} dx \right)^{\frac{1}{2}} \left(\int_{B_{i}} \left(\nabla \Pi_{i}(0, a, \xi) - \nabla \Pi_{i}(0, \overline{u}_{i}, \xi) \right)^{2} dx \right)^{\frac{1}{2}} \\ &= \left[\int_{B_{i}} \left| \sum_{j,k=1}^{3} \left(\frac{\partial \Pi_{i}^{k}(0, a, \xi)}{\partial x^{j}} - \frac{\partial \Pi_{i}^{k}(0, \overline{u}_{i}, \xi)}{\partial x^{j}} \right) \right|^{2} dx \right]^{\frac{1}{2}} \\ &= \left[\int_{B_{i}} \left| \sum_{j,k=1}^{3} \left(\sum_{l=1}^{3} \frac{\partial \Pi_{i}^{k}}{\partial z_{l}} (0, a, \xi) \frac{\partial \xi^{l}}{\partial x^{j}} - \frac{\partial \Pi_{i}^{k}}{\partial z_{l}} (0, \overline{u}_{i}, \xi) \frac{\partial \xi^{l}}{\partial x^{j}} \right) \right|^{2} dx \right]^{\frac{1}{2}} \\ &\leq \left[\int_{B_{i}} c \left| a - \overline{u}_{i} \right| dx \right]^{\frac{1}{2}} \to 0 \text{ as } i \to \infty. \end{split}$$

$$\begin{split} IV_i &= \varepsilon_i^{-1} \left| \int_{B_i} \nabla u_i \cdot \left[\nabla \Pi_i(x, u_i, \xi) - \nabla \Pi_i(0, \overline{\overline{u}}_i, \xi) \right] \, dx \right| \\ &\leq \left[2 \underbrace{\int_{B_i} \left| \nabla \Pi_i(x, u_i, \xi) - \nabla \Pi_i(x, \overline{\overline{u}}_i, \xi) \right|^2 dx}_{:=V_i} + \underbrace{\int_{B_i} \left| \nabla \Pi_i(x, \overline{\overline{u}}_i, \xi) - \nabla \Pi_i(0, \overline{\overline{u}}_i, \xi) \right|^2 dx}_{:=VI_i} \right]^{\frac{1}{2}} \\ &= (2(V_i + VI_i))^{\frac{1}{2}} \end{split}$$

If we can show $V_i, VI_i \to 0$ then $IV_i \to 0$ and hence $II_i \to 0$. Using Lemma B.2 and

(3.22) we have

$$\begin{split} V_{i} &= \int_{B_{i}} \left| \nabla \Pi_{i}(x, u_{i}, \xi) - \nabla \Pi_{i}(x, \overline{\overline{u}}_{i}, \xi) \right|^{2} dx \\ &= \int_{B_{i}} \sum_{j,k=1}^{3} \left| \sum_{l=1}^{3} \delta_{lj} \left(\frac{\partial \Pi_{i}^{k}}{\partial x_{l}}(x, u_{i}, \xi) - \frac{\partial \Pi_{i}^{k}}{\partial x_{l}}(x, \overline{\overline{u}}_{i}, \xi) \right) + \sum_{l=1}^{3} \frac{\partial u_{i}^{l}}{\partial x^{j}} \frac{\partial \Pi_{i}^{k}}{\partial y_{l}}(x, u_{i}, \xi) \\ &+ \sum_{l=1}^{3} \frac{\partial \xi_{l}}{\partial x^{j}} \left(\frac{\partial \Pi_{i}^{k}}{\partial z_{l}}(x, u_{i}, \xi) - \frac{\partial \Pi_{i}^{k}}{\partial z_{l}}(x, \overline{\overline{u}}_{i}, \xi) \right) \right|^{2} dx \\ &\leq \int_{B_{i}} c\varepsilon_{i}^{2} + c\varepsilon_{i}^{2} + c |u_{i}(x) - \overline{\overline{u}}_{i}|^{2} dx + c \int_{\Omega_{\varepsilon_{i}}} |\nabla u_{i}|^{2} dx \\ &\leq \int_{B_{i}} 2c\varepsilon_{i}^{2} + c\delta_{i}^{2} dx + c\varepsilon_{i}^{2} \to 0. \end{split}$$

Finally,

$$VI_{i} = \int_{B_{i}} \left| \nabla \Pi_{i}(x, \overline{\overline{u}}_{i}, \xi) - \nabla \Pi_{i}(0, \overline{\overline{u}}_{i}, \xi) \right|^{2} dx$$
$$= \int_{B_{i}} \sum_{j,k=1}^{3} \left| \sum_{l=1}^{3} \delta_{jl} \frac{\partial \Pi_{i}^{k}}{\partial x_{l}}(x, \overline{\overline{u}}_{i}, \xi) + \sum_{l=1}^{3} \frac{\partial \xi_{l}}{\partial x^{j}} \left(\frac{\partial \Pi_{i}^{k}}{\partial z_{l}}(x, \overline{\overline{u}}_{i}, \xi) - \frac{\partial \Pi_{i}^{k}}{\partial z_{l}}(0, \overline{\overline{u}}_{i}, \xi) \right) \right|^{2}.$$

Using Lemma B.3 we have

$$\left|\frac{\partial \Pi_i^k}{\partial z_l}(x, y, z) - \frac{\partial \Pi_i^k}{\partial z_l}(0, y, z)\right| \le c |\nu_i(x) - \nu_i(0)| \le c \operatorname{Lip}(\varphi_i) \le c\varepsilon_i.$$

Therefore

$$VI_i \leq \int_{B_i} c\varepsilon_i^2 + c\varepsilon_i \, dx \to 0 \text{ as } i \to 0,$$

and thus we have shown

$$\int_{\Omega_0} \nabla v \cdot \nabla \xi \, dx = 0.$$

It now follows that v^{\perp} and v^{\top} extend by even and odd reflections to functions harmonic on C. Thus, since $\overline{v} = 0$ and $\int_{\Omega_0} |\nabla v|^2 dx \leq 1$, we have

$$r^{-3} \int_{C(0,r)\cap\Omega_0} |v|^2 dx \le cr^2 \int_{\Omega_0} |v|^2 dx$$
$$\le cr^2 \int_{\Omega_0} |\nabla v|^2 dx$$
$$\le cr^2. \tag{3.27}$$

The first inequality follows from standard linear elliptic theory (similar to the proof of Lemma 2.2 in [5]) and the second follows using Lemma A.3. The second inequality of (3.27) along with the Poincaré inequality and trace theory also implies

$$r^{-4} \int_{C(0,r)\cap G_0} |v|^2 d\mathcal{H}^2 \le r^{-3} \|v\|_{H^{\frac{1}{2}}(C(0,r)\cap G_0)}^2 \le cr^2.$$
(3.28)

We now use Vitali convergence Theorem (Theorem A.2) to show that $||v_i||_{L^2(\Omega_{\varphi_i})} \rightarrow ||v||_{L^2(\Omega_0)}$. As $\hat{v_i}$ converges weakly in $W^{1,2}(\mathcal{C})$ to \hat{v} , we have that $\hat{v_i}$ converges strongly in $L^2(\mathcal{C})$ (on a subsequence) to \hat{v} . Hence we have

$$\widehat{v}_i \mathbb{1}_{\Omega_{\varphi_i}}(x) \to v \mathbb{1}_{\Omega_0}(x)$$

for \mathcal{L}^3 almost everywhere $x \in \mathcal{C}$, where $\mathbb{1}_{\Omega_{\varphi_i}}$ and $\mathbb{1}_{\Omega_0}$ are the indicator functions of Ω_{φ_i} and Ω_0 respectively. Using the Sobolev embedding Theorem we have

$$\|v_i\|_{L^3(\Omega_{\varphi_i})} \le \|\widehat{v}_i\|_{L^3(\mathcal{C})} \le C' \|\widehat{v}_i\|_{W^{1,2}(\mathcal{C})} \le C'C \|v_i\|_{W^{1,2}(\Omega_{\varphi_i})} \le K.$$
(3.29)

Let $E \subset C$ be an arbitrary measurable set. Then Hölders inequality and inequality (3.29) yields

$$\int_{E} \left| \widehat{v}_{i} \mathbb{1}_{\Omega_{\varphi_{i}}} \right|^{2} dx \leq \left(\int_{E} \left| \widehat{v}_{i} \mathbb{1}_{\Omega_{\varphi_{i}}} \right|^{3} dx \right)^{\frac{2}{3}} \mathcal{L}^{3}(E)^{\frac{1}{3}}$$
$$\leq K^{\frac{2}{3}} \left(\mathcal{L}^{3}(E) \right)^{\frac{1}{3}}.$$

Therefore for any $\epsilon > 0$ there exists a $\delta > 0$ such that $\int_E |\widehat{v}_i \mathbb{1}_{\Omega_{\varphi_i}}|^2 dx \leq \epsilon$ for all *i* and all $E \subset \mathcal{C}$ such that $\mathcal{L}^3(E) < \delta$. Hence $|v_i \mathbb{1}_{\Omega_{\varphi_i}}|^2$ is uniformly integrable. Thus by Vitali convergence Theorem we get

$$\int_{\mathcal{C}} \left| \left| \widehat{v}_i \mathbb{1}_{\Omega_{\varphi_i}} \right|^2 - \left| v \mathbb{1}_{\Omega_0} \right|^2 \right| dx \to 0$$

Therefore for any $\theta < r < 1$ we have

$$\left| \int_{\Omega_{\varphi_i} \cap C(0,r)} |v_i|^2 \, dx - \int_{\Omega_0 \cap C(0,r)} |v|^2 \, dx \right| \le c\theta^2 \le cr^2 \tag{3.30}$$

for sufficiently large *i*. We also have $||v_i||_{L^2(G_{\varphi_i})} \to ||v||_{L^2(G_0)}$, hence for sufficiently large *i* we have

$$\left| \int_{G_{\varphi_i} \cap C(0,r)} |v_i|^2 d\mathcal{H}^2 - \int_{G_0 \cap C(0,r)} |v|^2 d\mathcal{H}^2 \right| \le c\theta^2 \le cr^2.$$
(3.31)

Combining (3.27), (3.28), (3.30) and (3.31) we arrive at

$$\int_{\Omega_{\varphi_i}\cap C(0,r)} \left| u_i - \overline{\overline{u}}_i \right|^2 dx \le \varepsilon_i^2 \left(cr^2 + \int_{\Omega_0 \cap C(0,r)} \left| v \right|^2 dx \right) \le c\varepsilon_i^2 r^2 \tag{3.32}$$

and similarly

$$\int_{G_{\varphi_i}\cap C(0,r)} \left| u_i - \overline{\overline{u}}_i \right|^2 d\mathcal{H}^2 \le c\varepsilon_i^2 r^2.$$
(3.33)

We now use the Hybrid inequality (Lemma 3.11) and the scaling discussed in section 3.2.1 in order to to contradict our assumption that $\frac{1}{\theta} \int_{C(0,\theta)\cap\Omega} |\nabla u_i|^2 dx > \theta \varepsilon_i^2$. For each *i* we apply the Hybrid inequality to the scaled function $(u_i)_{4\theta}$ to obtain

$$\begin{split} \frac{1}{2\theta} \int_{C(0,\theta)\cap\Omega_{\varphi_{i}}} |\nabla u_{i}|^{2} dx \\ &\leq \lambda \left(\left\| (\varphi_{i})_{4\theta} \right\|_{C^{2}}^{2} + \frac{1}{4\theta} \int_{C(0,4\theta)\cap\Omega_{\varphi_{i}}} |\nabla u_{i}|^{2} dx \right) \\ &+ \lambda^{-q} c \left(\operatorname{Lip}((\varphi_{i})_{4\theta})^{2} + \int_{C(0,4\theta)\cap\Omega_{\varphi_{i}}} |u_{i} - \overline{u}_{i}|^{2} dx + \int_{C(0,4\theta)\cap G_{\varphi_{i}}} |u_{i} - \overline{u}_{i}|^{2} d\mathcal{H}^{2} \right) \\ &+ c \left\| (\varphi_{i})_{4\theta} \right\|_{C^{2}}^{2} \\ &\leq \lambda \left[(4\theta)^{2} \left\| \varphi_{i} \right\|_{C^{2}}^{2} + \frac{1}{4\theta} \int_{C(0,4\theta)\cap\Omega_{\varphi_{i}}} |\nabla u_{i}|^{2} dx \right] \\ &+ \lambda^{-q} c \left((4\theta)^{2} \operatorname{Lip}(\varphi_{i})^{2} + \int_{C(0,4\theta)\cap\Omega_{\varphi_{i}}} |u_{i} - \overline{u}_{i}|^{2} dx + \int_{C(0,4\theta)\cap G_{\varphi_{i}}} |u_{i} - \overline{u}_{i}|^{2} d\mathcal{H}^{2} \right) \\ &+ c (4\theta)^{2} \left\| \varphi_{i} \right\|_{C^{2}}. \end{split}$$

Iterating this (k-1) more times (where k is an integer to be chosen later) gives

$$\begin{aligned} \frac{1}{2\theta} \int_{C(0,\theta)\cap\Omega_{\varphi_i}} |\nabla u_i|^2 \, dx &\leq \lambda^k (4^k \theta)^{-1} \int_{\Omega_{\varphi_i}\cap C(0,4^k \theta)} |\nabla u_i|^2 \, dx \\ &+ \sum_{j=1}^k \lambda^j (4^j \theta)^2 \, \|\varphi_i\|_{C^2}^2 \\ &+ \sum_{j=1}^k \lambda^{-q} \lambda^{j-1} \left((4^j \theta)^2 \mathrm{Lip}(\varphi_i)^2 + \int_{C(0,4^j \theta)\cap\Omega_{\varphi_i}} |u_i - \overline{u}_i|^2 \, dx \right) \\ &+ \int_{C(0,4^j \theta)\cap G_{\varphi_i}} |u_i - \overline{u}_i|^2 \, d\mathcal{H}^2 \right) \\ &+ \sum_{j=1}^k \lambda^{j-1} (4^j \theta)^2 \, \|\varphi_i\|_{C^2}^2 \, .\end{aligned}$$

Let k be an integer such that $4^k \theta \le 1 \le 4^{k+1} \theta$, then using (3.32) and (3.33) we have for i large enough

$$\frac{1}{2\theta} \int_{C(0,\theta)\cap\Omega_{\varphi_i}} |\nabla u_i|^2 dx \le 4\lambda^k \varepsilon_i^2 + \sum_{j=1}^k \theta^2 \varepsilon_i^2 (16\lambda)^j + \lambda^{-q-1} \varepsilon_i^2 \sum_{j=1}^k \left[(16\lambda)^j \theta^2 + 2c\theta^2 (16\lambda)^j \right] + \lambda^{-1} \varepsilon_i^2 \theta^2 \sum_{j=1}^k (16\lambda)^j \\\le 4\lambda^k \varepsilon_i^2 + \lambda^{-l} c\theta^2 (1-16\lambda)^{-1} \varepsilon_i^2$$

where $l = \max\{q+1, 1\}$ and c has absorbed all other constants. Set $\lambda = \theta^{\frac{3}{k}}$, then providing $\theta < \frac{1}{4}$ we have $\lambda^k = \theta^3 < \frac{\theta}{16}$. Next, as $k \to \infty$ as $\theta \to 0$, we may fix $\theta < \frac{1}{4}$ sufficiently small such that

 $16c\theta < \theta^{\frac{3l}{k}}.$

Note that for θ sufficiently small we have $\lambda < \frac{1}{32}$ which implies $(1 - 16\lambda)^{-1} \le 2$ then

$$\lambda^{-l}c\theta^2(1-16\lambda)^{-1} = \theta^{-\frac{3l}{k}}c\theta^2(1-16\lambda)^{-1}$$
$$\leq \frac{c\theta^2}{16c\theta}(1-16\lambda)^{-1}$$
$$\leq \frac{\theta}{8}.$$

Therefore

$$\frac{1}{2\theta} \int_{C(0,\theta)\cap\Omega_{\varphi_i}} \left|\nabla u_i\right|^2 dx < \left(\frac{\theta}{4} + \frac{\theta}{8}\right)\varepsilon_i^2 = \frac{3\theta}{8}\varepsilon_i^2,$$

contradicting our choice of u_i, φ_i .

Theorem 3.13 (Energy Decay). Suppose Ω is a C^2 domain in \mathbb{R}^3 and take $a \in \partial \Omega$. If $u \in \mathcal{U}$ is a minimizer of \mathbb{G} in \mathcal{U} with $\int_{\Omega \cap C(a,R)} |\nabla u|^2 dx \leq \varepsilon^2 R$, then

$$\int_{\Omega \cap C(a,r)} |\nabla u|^2 \, dx \le r^2 R^{-1} \theta^{-2} \max\{\varepsilon^2, c(R+R^2)\}$$

for $0 < r \leq R$, a suitable $\theta \in (0, 1)$ and c a constant depending on Ω .

Proof. We apply inequality (3.15) to the scaled function $v^1(x) = u_{\theta R,a}(x)$ to get that for a $\theta \in (0, 1)$ as in Lemma 3.12 we have:

$$\frac{1}{R\theta} \int_{C(a,R\theta)\cap\Omega} |\nabla u(x)|^2 dx = \int_{C(a,1)\cap\Omega} |\nabla u_{R\theta,a}(x)|^2 dx$$

$$= \frac{1}{\theta} \int_{C(a,\theta)\cap\Omega} |\nabla u_{R,a}(x)|^2 dx$$

$$\leq \theta \max\{\int_{C(a,1)\cap\Omega} |\nabla u_{R,a}(x)|^2 dx, c \left(\operatorname{Lip}(\varphi_{R,a}) + \|\varphi_{R,a}\|_{C^2}\right)\}$$

$$\leq \theta \max\{\int_{C(a,1)\cap\Omega} |\nabla u_{R,a}(x)|^2 dx, c \left(R\operatorname{Lip}(\varphi) + R^2 \|\varphi\|_{C^2}\right)\}.$$

Then, inductively, for $k \in \mathbb{N}$ we get that

$$(\theta^{k-1}R)^{-1} \int_{C(a,\theta^{k-1}R)\cap\Omega} |\nabla u|^2 dx \le \theta^{k-1} \max\{\varepsilon^2, c\left(R\mathrm{Lip}(\varphi) + R^2 \|\varphi\|_{C^2}\right)\}$$

hence

$$\begin{aligned} (\theta^k R)^{-1} \int_{C(a,\theta^k R)\cap\Omega} |\nabla u|^2 dx &= \frac{1}{\theta} \int_{C(a,\theta)\cap\Omega} |\nabla u_{\theta^{k-1}R,a}|^2 dx \\ &\leq \theta \max\left\{ \int_{C(a,1)} |\nabla u_{\theta^{k-1}R,a}|^2 dx, c\left(\operatorname{Lip}(\varphi_{\theta^{k-1}R,a}) + \left\|\varphi_{\theta^{k-1}R,a}\right\|_{C^2}\right) \right\} \\ &\leq \theta \max\left\{ \left[\theta^{k-1} \max\left\{ \varepsilon^2, c\left(R\operatorname{Lip}(\varphi) + R^2 \left\|\varphi\right\|_{C^2}\right) \right\} \right], \\ &\quad c\left((\theta^{k-1}R)\operatorname{Lip}(\varphi) + (\theta^{k-1}R)^2 \left\|\varphi\right\|_{C^2}\right) \right\} \\ &= \theta^k \max\left\{ \varepsilon^2, c\left(R\operatorname{Lip}(\varphi) + R^2 \left\|\varphi\right\|_{C^2}\right) \right\}. \end{aligned}$$

Hence the inequality

$$(\theta^k R)^{-1} \int_{C(a,\theta^k R)\cap\Omega} |\nabla u|^2 dx \le \theta^k \max\left\{\varepsilon^2, c\left(R \operatorname{Lip}(\varphi) + R^2 \|\varphi\|_{C^2}\right)\right\}$$

holds for all $k \in \mathbb{N}$. Next, choose k such that $\theta^{k+1}R \leq r < \theta^k R$. Then

$$r^{-1} \int_{C(a,r)\cap\Omega} |\nabla u|^2 dx \leq \theta^{-1} (\theta^k R)^{-1} \int_{C(a,\theta^k R)\cap\Omega} |\nabla u|^2 dx$$

$$\leq \theta^{-1} \theta^k \max\left\{\varepsilon^2, c\left(R \operatorname{Lip}(\varphi)^2 + R^2 \|\varphi\|_{C^2}^2\right)\right\}$$

$$\leq \theta^{-1} (\theta^{-1} R^{-1} r) \max\left\{\varepsilon^2, c\left(R \operatorname{Lip}(\varphi)^2 + R^2 \|\varphi\|_{C^2}^2\right)\right\}$$

$$\leq \theta^{-2} R^{-1} r \max\left\{\varepsilon^2, c(R + R^2)\right\}.$$

Proof. [of Theorem 1.3]

We note that we just need to look into partial regularity on the boundary, because in the interior of Ω the energy behaves like that of the standard harmonic map for which the regularity theory is classical (see [17]). Indeed, let \bar{n} be a minimizer of \mathbb{G} and take an arbitrary open set ω with $\bar{\omega} \subset \Omega$. Let n_{ω} be a minimizer of $\int_{\omega} |\nabla n|^2 dx$ in $W^{1,2}(\omega; \mathbb{S}^2)$ with boundary condition $\bar{n}|_{\omega}$. Then defining $\tilde{n}(x) := \begin{cases} n(x) & \text{for } x \in \Omega \setminus \omega \\ n_{\omega}(x) & \text{for } x \in \omega \end{cases}$ we have that \tilde{n} is a minimizer of \mathbb{G} and thus all the arguments for harmonic maps can be applied to it in ω .

The main point of our work in this last section has been to obtain the energy decay near the boundary, namely Theorem 3.13 before. For a point where the rescaled energy is small enough the standard Morrey lemma shows that the estimate thus obtained implies Hölder regularity. Standard covering arguments show then the set of singularity points, those where the renormalized energy is not small, is of zero one-dimensional Hausorf measure (see for instance [7]).

Appendices

A Some Lemmas for Partial Regularity

We prove two lemmas that will be useful in the proof of the partial regularity. They are standard results for a fixed domain but we need them to hold with certain constants independent of the domains. The first is an extension lemma and it is standard (see for instance [4] Chapter 4), but we reproduce a proof for the readers convenience. Its main point is to show that the extension map can be chosen in a manner that depends only on the upper bound of the Lipschitz constant of the boundary.

LEMMA A.1. Let $\varphi : \mathbb{R}^2 \to \mathbb{R}$ be a Lipschitz map such that $\varphi(0) = |\nabla \varphi(0)|^2 = 0$ and Lip $(\varphi) \leq \frac{1}{5}$. Then if $f \in W^{1,2}(\Omega_{\varphi})$, there exists $\widehat{f} \in W^{1,2}(\mathcal{C})$ such that $\widehat{f} = f$ on Ω_{φ} and

$$\left| \widehat{f} \right| _{W^{1,2}(C(0,1))} \le c \| f \|_{W^{1,2}(\Omega_{\varphi})}$$

where c is independent of φ , f and we denote $\mathcal{C} := \{x \in \mathbb{R}^3 : |(x^1, x^2)| < 1 \text{ and } -1 < x^3 < \frac{1}{2}\}$ respectively $\Omega_{\varphi} := \{(x^1, x^2, x^3) \in C(0, 1) : x^3 < \varphi(x^1, x^2)\}.$

Proof. Fix φ and define

$$U := \mathcal{C} \setminus \overline{\Omega}_{\varphi}$$

For simplicity we write $x' := (x^1, x^2)$. First suppose that $f \in C^1(\overline{\Omega}_{\varphi})$ and set

$$\begin{cases} \widehat{f}(x) = f(x) \text{ if } x \in \overline{\Omega_{\varphi}}, \\ \widehat{f}(x) = f(x', -x^3 + 2\varphi(x')) \text{ if } x \in \overline{U}. \end{cases}$$

We note that $f = \widehat{f}$ on $\Omega_{\varphi} \cap \mathcal{C}$ and we claim that

$$\left\| \widehat{f} \right\|_{W^{1,2}(U)} \le c_1 \| f \|_{W^{1,2}(\Omega_{\varphi})}.$$

To see this let $\psi \in C_c^1(U)$ and $\{\varphi_k\}_{k=1}^\infty$ be a sequence of C^∞ functions such that

$$\begin{cases} \varphi_k \leq \varphi \\ \varphi_k \to \varphi \text{ uniformly} \\ D\varphi_k \to D\varphi \text{ almost everywhere} \\ \sup_k \|D\varphi_k\|_{L^{\infty}} < \infty. \end{cases}$$

Then for j = 1, 2 we have

$$\begin{split} \int_{U} \widehat{f} \frac{\partial \psi}{\partial x^{j}} dx &= \int_{U} f(x', 2\varphi(x') - x^{3}) \frac{\partial \psi}{\partial x^{j}} dx \\ &= \lim_{k \to \infty} \int_{U} f(x', 2\varphi_{k}(x') - x^{3}) \frac{\partial \psi}{\partial x^{j}} dx \\ &= -\lim_{k \to \infty} \int_{U} \left(\frac{\partial f}{\partial x^{j}} (x', 2\varphi_{k}(x') - x^{3}) + 2 \frac{\partial f}{\partial x^{3}} (x', 2\varphi_{k}(x') - x^{3}) \frac{\partial \varphi_{k}}{\partial x^{j}} (x') \right) \psi dx \\ &= - \int_{U} \left(\frac{\partial f}{\partial x^{j}} (x', 2\varphi(x') - x^{3}) + 2 \frac{\partial f}{\partial x^{3}} (x', 2\varphi(x') - x^{3}) \frac{\partial \varphi}{\partial x^{j}} (x') \right) \psi dx \end{split}$$

In the same way we can compute

$$\int_{U} \widehat{f} \frac{\partial \psi}{\partial x^{3}} dx = \int_{U} \frac{\partial f}{\partial x^{3}} (x', 2\varphi(x') - x^{3}) \psi dx.$$

Then, by a change of variables and using the fact $\operatorname{Lip}(\varphi) \leq \frac{1}{5}$ we get

$$\int_{U} \left| Df(x', 2\varphi(x') - x^3) \right|^2 dx \le c_1 \int_{\Omega_{\varphi}} \left| Df \right|^2 dx, \tag{A.1}$$

for some appropriate c_1 that is independent of f and φ . This proves the claim and moreover also shows that $\|\hat{f}\|_{W^{1,2}(\mathcal{C})} \leq c_1 \|f\|_{W^{1,2}(\Omega_{\varphi})}$. The result for a general $f \in W^{1,2}(\Omega_{\varphi})$ can now be achieved via density. \Box

For the proof of the next lemma we will use Vitali convergence theorem which we state here for the readers convenience

THEOREM A.2 (Vitali Convergence Theorem). Let (X, \mathcal{F}, μ) be a positive measure space. Let $f_n : X \to \mathbb{R}, \forall n \in \mathbb{N}$ and $f : X \to \mathbb{R}$ be measurable functions such that:

- a. $\mu(X) < \infty$
- b. $\{f_n\}_{n\in\mathbb{N}}$ is uniformly integrable
- c. $f_n(x) \to f(x)$ almost everywhere as $n \to \infty$
- d. $|f(x)| < \infty$ almost everywhere

then the following hold

i.
$$f \in L^1(\mu)$$

ii. $\lim_{n\to\infty} \int_X |f_n - f| d\mu = 0$

We now use this and lemma A.1 to prove the following Poincaré inequality. Its main point is to check that the constant in the inequality can be chosen uniformly for all the domains we consider.

LEMMA A.3. Let $\varphi : \mathbb{R}^2 \to \mathbb{R}$ be a Lipschitz map such that $\varphi(0) = |\nabla \varphi(0)|^2 = 0$ and Lip $(\varphi) \leq \frac{1}{2}$. Then there exists C > 0, independent of φ , such that for all $u \in W^{1,2}(\Omega_{\varphi})$ we have the Poincaré type inequality

$$\int_{\Omega_{\varphi}} \left| u - \overline{\overline{u}} \right|^2 dx \le C \int_{\Omega_{\varphi}} |\nabla u|^2 dx$$

where $\overline{\overline{u}} := \mathcal{H}^2(G_{\varphi})^{-1} \int_{G_{\varphi}} u d\mathcal{H}^2$.

Proof. We argue by contradiction and assume that for all $i \in \mathbb{N}$ there exist $\varphi_i, u_i \in W^{1,2}(\Omega_{\varphi_i})$ such that

$$\frac{\int_{\Omega_{\varphi_i}} |\nabla u_i|^2 dx}{\int_{\Omega_{\varphi_i}} |u_i - \overline{\overline{u}}_i|^2 dx} < \frac{1}{i}$$

Define the functions $v_i := (u_i - \overline{\overline{u}}_i) \left(\int_{\Omega_{\varphi_i}} |u_i - \overline{\overline{u}}_i|^2 dx \right)^{-\frac{1}{2}}$. Then we have

$$\int_{\Omega_{\varphi_i}} |\nabla v_i|^2 dx \le \frac{1}{i} \qquad \text{and} \qquad \int_{\Omega_{\varphi_i}} |v_i|^2 dx = 1$$

As $|\nabla \varphi_i| < \frac{1}{2}$, there exists a subsequence (not relabelled) such that $\varphi_i \to \varphi$ uniformly for some φ .

By Lemma A.1 there exist functions $\hat{v}_i \in W^{1,2}(\mathcal{C})$ such that $\|\hat{v}_i\|_{W^{1,2}(\mathcal{C})} \leq c \|v_i\|_{W^{1,2}(\Omega_{\varphi_i})}$ and by inspecting the proof there exists constant c_1 such that $\|\nabla \hat{v}_i\|_{L^2(\mathcal{C})} \leq c_1 \|\nabla v_i\|_{L^2(\Omega_{\varphi_i})}$. It follows that there exists $\hat{v} \in W^{1,2}(\mathcal{C})$ such that \hat{v}_i converge weakly in $W^{1,2}$ to \hat{v} , but as $\|\nabla \hat{v}_i\|_{L^2(\mathcal{C})} \to 0$ we have that $\hat{v} \equiv k$ for some constant k. We now investigate the behaviour of \hat{v} on G_{φ} where we recall that $G_{\varphi} := \partial \Omega_{\varphi} \setminus \partial C(0, 1)$. We have

$$\begin{aligned} \left| \int_{G_{\varphi_i}} v_i d\mathcal{H}^2 - \int_{G_{\varphi}} \widehat{v} d\mathcal{H}^2 \right| &\leq \left| \int_{G_{\varphi_i}} (v_i - \widehat{v}) \, d\mathcal{H}^2 \right| + \left| \int_{G_{\varphi_i}} \widehat{v} \, d\mathcal{H}^2 - \int_{G_{\varphi}} \widehat{v} \, d\mathcal{H}^2 \right| \\ &\leq \left\| v_i - \widehat{v} \right\|_{H^{\frac{1}{2} - \varepsilon}(G_{\varphi_i})} + \left| \int_{G_{\varphi_i}} \widehat{v} \, d\mathcal{H}^2 - \int_{G_{\varphi}} \widehat{v} \, d\mathcal{H}^2 \right| \\ &\leq \left\| v_i - \widehat{v} \right\|_{H^{1 - \varepsilon}(\Omega_{\varphi_i})} + \left| \int_{G_{\varphi_i}} \widehat{v} \, d\mathcal{H}^2 - \int_{G_{\varphi}} \widehat{v} \, d\mathcal{H}^2 \right| \\ &\leq \left\| \widehat{v}_i - \widehat{v} \right\|_{H^{1 - \varepsilon}(\mathcal{C})} + \left| \int_{G_{\varphi_i}} \widehat{v} \, d\mathcal{H}^2 - \int_{G_{\varphi}} \widehat{v} \, d\mathcal{H}^2 \right| \end{aligned}$$

As we have $\|\hat{v}_i\|_{H^1(\mathcal{C})}$ bounded uniformly we have that $\hat{v}_i \to \hat{v}$ in $H^{1-\varepsilon}(\mathcal{C})$ and since also $\varphi_i \to \varphi$ uniformly the above tends to 0. Then

$$0 = \int_{G_{\varphi_i}} v_i d\mathcal{H}^2 \to \int_{G_{\varphi}} \widehat{v} d\mathcal{H}^2, \qquad (A.2)$$

which implies that $\hat{v} \equiv 0$.

However, we claim that

$$1 = \lim_{i \to \infty} \int_{\Omega_{\varphi_i}} |v_i|^2 dx = \int_{\Omega_{\varphi}} |v|^2 dx \tag{A.3}$$

which would contradict $\hat{v} \equiv 0$.

To prove (A.3) we use Vitali convergence Theorem. First as \hat{v}_i converges strongly in $L^2(\mathcal{C})$ to \hat{v} we have

$$\widehat{v}_i(x)\mathbb{1}_{\Omega_{\varphi_i}}(x) \to \widehat{v}(x)\mathbb{1}_{\Omega_{\varphi}}(x)$$

for almost every $x \in \mathcal{C}$.

We now show that the sequence of functions $\{|\hat{v}_i \mathbb{1}_{\Omega_{\varphi_i}}|^2\}$ are uniformly integrable. Note that by the Sobolev inequalities, there exists c_2 such that $\|\hat{v}_i\|_{L^3(\mathcal{C})} \leq c_2 \|\hat{v}_i\|_{W^{1,2}(\mathcal{C})}$ hence as \hat{v}_i is bounded in $W^{1,2}(\mathcal{C})$ it is also a bounded sequence in $L^3(\mathcal{C})$, say $\|\hat{v}_i\|_{L^3(\mathcal{C})} \leq c_3$. Fix $\varepsilon > 0$ we want to show that there exists $\delta > 0$ such that $\int_E |\hat{v}_i \mathbb{1}_{\Omega_{\varphi_i}}|^2 dx < \varepsilon$ whenever $E \subset \mathcal{C}$ and $\mathcal{L}^3(E) < \delta$. With this in mind for $E \subset \mathcal{C}$ we estimate

$$\begin{split} \int_{E} \left| \widehat{v}_{i} \mathbb{1}_{\Omega_{\varphi_{i}}} \right|^{2} dx &\leq \left(\int_{E} \left| \widehat{v}_{i} \mathbb{1}_{\Omega_{\varphi_{i}}} \right|^{3} dx \right)^{\frac{2}{3}} \left(\int_{E} dx \right)^{\frac{1}{3}} \\ &\leq \left\| \widehat{v}_{i} \right\|_{L^{3}(\mathcal{C})}^{2} \mathcal{L}^{3}(E)^{\frac{1}{3}} \\ &\leq c_{3} \mathcal{L}^{3}(E)^{\frac{1}{3}} \end{split}$$

thus by setting $\delta = \varepsilon^3/c_3$ we have shown $\{|\hat{v}_i \mathbb{1}_{\Omega_{\varphi_i}}|^2\}$ are uniformly integrable. We can now conclude using Vitali convergence Theorem that

$$\lim_{i \to \infty} \int_{\mathcal{C}} \left| \left| \widehat{v}_i \mathbb{1}_{\Omega_{\varphi_i}} \right|^2 - \left| \widehat{v} \mathbb{1}_{\Omega_{\varphi}} \right|^2 \right| dx = 0$$

which implies (A.3) and completes the proof.

B Some bounds on the Projection (3.21)

We prove some bounds on the derivatives of the projection $\Pi_i: \Omega_{\varphi_i} \times U \times \mathbb{R}^3 \to \mathbb{R}^3$ defined by

$$\Pi_i(x, y, z) = \frac{\left[(y \times \nu_i(x)) \otimes (y \times \nu_i(x))\right] z}{\left|y \times \nu_i(x)\right|^2} + y_i(z)$$

where Ω_{φ_i} and U are as in the proof of Lemma 3.12.

LEMMA B.1. Providing U is sufficiently small then there exists C > 0 such that for large i the projection Π_i satisfies the bounds

$$\left|\frac{\partial \Pi_i(x,y,z)}{\partial x^j}\right| < C\varepsilon_i^2 |z|, \qquad \left|\frac{\partial \Pi_i(x,y,z)}{\partial z^j}\right| \le 1, \qquad \left|\frac{\partial \Pi_i(x,y,z)}{\partial y^j}\right| < C|z|.$$

Proof. Writing $y = (y^1, y^2, y^3)$ a straight forward calculation yields

$$\begin{aligned} \frac{\partial \Pi_{i}}{\partial y^{j}}(x,y,z) &= \frac{z \cdot \left(\left(\delta_{1j}, \delta_{2j}, \delta_{3j}\right) \times \nu_{i}(x)\right)\left(y \times \nu_{i}(x)\right)}{|y \times \nu_{i}(x)|^{2}} \\ &+ \frac{z \cdot \left(y \times \nu_{i}(x)\right)\left(\left(\delta_{1j}, \delta_{2j}, \delta_{3j}\right) \times \nu_{i}(x)\right)\right)}{|y \times \nu_{i}(x)|^{2}} \\ &- \frac{2\left(\left(y \times \nu_{i}(x)\right) \cdot \left(\left(\delta_{1j}, \delta_{2j}, \delta_{3j}\right) \times \nu_{i}(x)\right)\right)\left(z \cdot \left(y \times \nu_{i}(x)\right)\right)\left(y \times \nu_{i}(x)\right)}{|y \times \nu_{i}(x)|^{4}} \\ &+ \left(\delta_{1j}, \delta_{2j}, \delta_{3j}\right)\end{aligned}$$

$$\frac{\partial \Pi_i}{\partial z^j}(x, y, z) = \frac{\left[(y \times \nu_i(x)) \otimes (y \times \nu_i(x))\right](\delta_{1j}, \delta_{2j}, \delta_{3j})}{\left|y \times \nu_i(x)\right|^2}$$

$$\frac{\partial \Pi_{i}}{\partial x^{j}}(x,y,z) = \frac{z \cdot \left(y \times \frac{\partial \nu_{i}(x)}{\partial x^{j}}\right) (y \times \nu_{i}(x))}{|y \times \nu_{i}(x)|^{2}} + \frac{z \cdot (y \times \nu_{i}(x)) \left(y \times \frac{\partial \nu_{i}(x)}{\partial x^{j}}\right)}{|y \times \nu_{i}(x)|^{2}} - \frac{2 \left((y \times \nu_{i}(x)) \cdot \left(y \times \frac{\partial \nu_{i}(x)}{\partial x^{j}}\right)\right) (z \cdot (y \times \nu_{i}(x))) (y \times \nu_{i}(x))}{|y \times \nu_{i}(x)|^{4}}$$

where

$$\frac{\partial\nu}{\partial x^{j}} = \left[\frac{\left(-\varphi_{x^{1}x^{j}}, -\varphi_{x^{2}x^{j}}, 0\right)}{\left(\varphi_{x^{1}}^{2} + \varphi_{x^{2}}^{2} + 1\right)^{\frac{1}{2}}} - \frac{\left(\varphi_{x^{1}x^{j}}\varphi_{x^{1}} + \varphi_{x^{2}x^{j}}\varphi_{x^{2}}\right)\left(-\varphi_{x^{1}}, -\varphi_{x^{2}}, 1\right)}{\left(\varphi_{x^{1}}^{2} + \varphi_{x^{2}}^{2} + 1\right)^{\frac{3}{2}}}\right].$$

We observe that if U is sufficiently small and i sufficiently large then there exists constants $c_1, c_2 > 0$ such that $c_1 < |y \times \nu_i(x)| < c_2$. This, along with the inequality (3.18), gives

$$\left|\frac{\partial \Pi_i(x,y,z)}{\partial x^j}\right| < C\varepsilon_i^2 |z|, \qquad \left|\frac{\partial \Pi_i(x,y,z)}{\partial z^j}\right| \le 1, \qquad \left|\frac{\partial \Pi_i(x,y,z)}{\partial y^j}\right| < C|z|.$$

We next prove a bound on the difference of two projections onto two different lines.

LEMMA B.2. Let $y_1, y_2 \in U$, $x \in \Omega_{\varphi_i}$ and $z \in \mathbb{R}^3$. Then we have the bound

$$\left|\frac{\partial \Pi_i}{\partial z^j}(x,y^1,z) - \frac{\partial \Pi_i}{\partial z^j}(x,y^2,z)\right| \le \left|y^1 - y^2\right|.$$

Proof. First, by writing $\Lambda_j = (\delta_{1j}, \delta_{2j}, \delta_{3j})$ we have

$$\frac{\partial \Pi_i}{\partial z^j}(x, y, z) = \frac{(y \times \nu_i(x)) \otimes (y \times \nu_i(x))\Lambda_j}{|y \times \nu_i(x)|^2}$$
$$= A(y, x)\Lambda_j,$$

where $A(x,y) = \frac{(y \times \nu_i(x)) \otimes (y \times \nu_i(x))}{|y \times \nu_i(x)|^2} \in \mathbb{M}^{3 \times 3}$. We consider the linear map $h : \mathbb{R}^3 \to \mathbb{R}^3$ $z \mapsto (A(y^1, x) - A(y^2, x))z$,

and calculate the operator norm of h. Note that the map $v \mapsto A(x, y)v$ is the projection of v onto the line spanned by $(y \times \nu_i(x))$. We assume that the plane spanned by $(y^1 \times \nu_i(x))$ and $(y^2 \times \nu_i(x))$ to be \mathbb{R}^2 with

$$((y^1 \times \nu_i(x)) = (1, 0, 0) \text{ and } (y^2 \times \nu_i(x)) = (\cos(\tau), \sin(\tau), 0),$$

where τ is the angle between $(y^1 \times \nu_i(x))$ and $(y^2 \times \nu_i(x))$. Then

$$A(y^{1}, x) - A(y^{2}, x) = \begin{bmatrix} 1 - \cos^{2}(\tau) & -\cos(\tau)\sin(\tau) & 0\\ -\cos(\tau)\sin(\tau) & -\sin^{2}(\tau) & 0\\ 0 & 0 & 0 \end{bmatrix}$$

We can find the operator norm of this by finding the largest eigenvalue. A calculation yields

$$\|h\|_{op} = |\sin(\tau)|$$

Using elementary geometry we have

$$\sin(\tau) \le \frac{|(y^1 \times \nu_i(x)) - (y^2 \times \nu_i(x))|}{|y^1 \times \nu_i(x)|}$$
$$\le |y^1 - y^2|.$$

Therefore

$$\left| \left(\frac{(y^1 \times \nu_i(x)) \otimes (y^1 \times \nu_i(x))}{|(y^1 \times \nu_i(x))|^2} - \frac{(y^2 \times \nu_i(x)) \otimes (y^2 \times \nu_i(x))}{|(y^2 \times \nu_i(x))|^2} \right) \Lambda_j \right| \le |\Lambda_j| |\sin(\tau)| \le |y^1 - y^2|.$$

Using similar reasoning one can also prove the following.

LEMMA B.3. There exists C > 0 such that

$$\left|\frac{\partial \Pi_i^k}{\partial z_l}(x, y, z) - \frac{\partial \Pi_i^k}{\partial z_l}(0, y, z)\right| \le C |\nu_i(x) - \nu_i(0)|,$$

for all $x \in \Omega_{\varphi_i}$, $y \in U$ and $z \in \mathbb{R}^3$.

Proof. We first calculate that

$$\left| \frac{\partial \Pi_i^k}{\partial z_l}(x, y, z) - \frac{\partial \Pi_i^k}{\partial z_l}(0, y, z) \right| = \\ \left| \frac{(y \times \nu_i(x)) \otimes (y \times \nu_i(x))\Lambda_j}{|y \times \nu_i(x)|^2} - \frac{(y \times \nu_i(0)) \otimes (y \times \nu_i(0))\Lambda_j}{|y \times \nu_i(0)|^2} \right|$$

This is the difference between two projections on to two different lines, hence by the same reasoning as in the proof of Lemma B.2 we obtain

$$\left|\frac{\partial \Pi_i^k}{\partial z_l}(x, y, z) - \frac{\partial \Pi_i^k}{\partial z_l}(0, y, z)\right| \le c|\nu_i(x) - \nu_i(0)|$$

as required.

C Notation

- $\mathbb{E}[n] = \int_{\Omega} \frac{K}{2} |\nabla n|^2 dx + K_{13} \int_{\partial \Omega} ((n \cdot \nabla)n) \cdot \nu d\sigma$
- $\mathscr{A} := W^{1,2}(\Omega; \mathbb{S}^{d-1}) \cap W^{2,1}(\Omega; \mathbb{S}^{d-1})$
- $\Omega \subset \mathbb{R}^n$ a is C^2 domain (See Theorem 1.1)
- ν unit-norm exterior normal.
- $\mathcal{T} := \{ \gamma \in H^{\frac{1}{2}}(\partial\Omega, \mathbb{S}^2) : \gamma(x) \cdot \nu(x) = 0 \text{ for almost every } x \in \partial\Omega \}$
- $\mathcal{U} := \{ u \in W^{1,2}(\Omega, \mathbb{S}^2) : \operatorname{Trace}(u) \in \mathcal{T} \}$

•
$$\mathbb{G}[n] := \int_{\Omega} K \sum_{\alpha,\beta=1}^{d} \frac{\partial n^{\alpha}}{\partial x^{\beta}} \frac{\partial n^{\alpha}}{\partial x^{\beta}} - K_{13} \int_{\partial \Omega} \sum_{\alpha,\beta=1}^{d} \frac{\partial \nu^{\beta}}{\partial x^{\alpha}} n^{\beta} n^{\alpha}.$$

•
$$\|\varphi_{r,a}\|_{C^2} := \max_{|\alpha|=2} \sup_{x \in \mathbb{R}^2} \left| \frac{\partial^{|\alpha|}\varphi_{r,a}(x)}{\partial x^{\alpha}} \right|$$

• $C(x,r) := \{y \in \mathbb{R}^3 : |(y^1,y^2) - (x^1,x^2)| < r, |y^3 - x^3| < r\}$

•
$$\Omega_{\varphi} = \{(x^1, x^2, x^3) \in C(0, 1) : x^3 < \varphi(x^1, x^2)\}$$

•
$$\Omega_0 := \{ (x^1, x^2, x^3) \in C(0, 1) : x^3 < 0 \}$$

- $G_{\varphi} = \partial \Omega_{\varphi} \setminus \partial C(0,1)$
- $G_0 = \partial \Omega_0 \setminus \partial C(0,1)$
- $H_{\varphi} = \partial \Omega_{\varphi} \cap \partial C(0,1)$

- $H_0 = \partial \Omega_0 \cap \partial C(0, 1)$
- $\mathbb{G}_{\varphi}[u] := \int_{\Omega_{\varphi}} |\nabla u|^2 dx K_{13} \int_{G_{\varphi}} u^{\alpha} u^{\beta} \frac{\partial \nu^{\beta}}{\partial x^{\alpha}} dx.$
- $B^d(0,1)$ is the ball in \mathbb{R}^d centred at 0 with radius 1.

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