

Title	Effective stretching position for the supraspinatus muscle evaluated by shear wave elastography in vivo
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1 **Title**

2 Effective stretching position for the supraspinatus muscle evaluated by shear wave
3 elastography in vivo

4

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22 **Ethical Committee approval**

23 This study has been approved by the Ethics Committee of the Kyoto University

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25

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29

30 **Conflict of Interest**

31 None.

32

33 **Abstract**

34 **Background:**

35 Stretching is useful for increasing flexibility in clinical and athletic situations. Although
36 several authors have recommended various stretching techniques for the supraspinatus
37 muscle, there is no consensus on the effective stretching position owing to a lack of
38 quantitative analysis in vivo. This study used ultrasonic shear wave elastography in vivo to
39 verify the effective stretching positions for the supraspinatus muscle.

40 **Methods:**

41 The study participants were 15 healthy male volunteers. The shear elastic modulus, used as
42 the index of supraspinatus muscle elongation, was computed using ultrasonic shear wave
43 elastography. The shear elastic modulus was measured at neutral position and maximum
44 internal rotation in 9 positions: 0° elevation, 90° abduction, 90° flexion, maximum extension,
45 maximum horizontal adduction at 45° and 90° elevation, and maximum horizontal abduction
46 at 20°, 45°, and 90° elevation.

47 **Results:**

48 The shear elastic moduli were significantly greater in maximum internal rotation at maximum
49 horizontal abduction with 45° and 90° elevation and maximum internal rotation at maximum
50 extension than those in the other positions. There were no significant differences in the shear
51 elastic moduli among these 3 positions.

52 **Conclusions:**

53 This study demonstrated that maximum internal rotation at maximum extension, maximum
54 internal rotation at maximum horizontal abduction with 90° elevation, and maximum internal
55 rotation at maximum horizontal abduction with 45° elevation are effective stretching
56 positions for the supraspinatus muscle.

57

58 **Keywords**

59 ultrasonic shear wave elastography

60 shear elastic modulus

61 supraspinatus muscle

62 stretching

63 shoulder

64 rehabilitation

65

66 **Level of evidence**

67 Basic Science Study, Biomechanics, Imaging.

68

69 **Introduction**

70 Stretching is useful for increasing flexibility in clinical and athletic situations. Many
71 previous studies have reported on the effects of stretching^{7, 9, 11, 18, 26} but few studies have
72 reported the method or position used to create an effective stretch^{24, 30}. Because the shoulder
73 joint has multiple degrees of freedom and a large range of motion, the method used to stretch
74 shoulder muscles needs to be investigated.

75 Many studies have reported the relationship between the 3-dimensional shoulder position
76 and the moment arm^{16, 17, 32} and torque-vector directions^{2, 37} of each shoulder muscle.
77 Therefore, the 3-dimensional shoulder position must be considered when devising effective
78 methods for stretching the shoulder muscles.

79 Several authors have recommended various stretching positions for each individual
80 muscle^{6, 10, 31, 36}, but there is no consensus on the effective stretching positions owing to a lack
81 of an in vivo quantitative analysis. The cross-body stretch and the sleeper stretch are well
82 known and commonly used for posterior shoulder tightness²², but the effect of stretching on
83 individual muscles and other tissues is unclear.

84 In previous cadaveric studies, the effective stretching position for the shoulder muscles and
85 joint capsule was simulated and quantitatively analyzed^{13, 23-25}. Clinicians are in great need of
86 an in vivo quantitative analysis of the effect of stretching on individual muscles, but
87 conventionally, it has been difficult to measure the evaluation index of stretching on
88 individual muscles. In human studies, passive torque-angle measurements are widely used to
89 noninvasively examine muscle stretch and passive muscle force^{27, 33, 34}. However,
90 torque-angle measurements are affected by many structures crossing the joint, such as
91 synergistic muscles, aponeuroses, tendons, joint capsules, and ligaments, and cannot be used
92 to identify the effect of an individual muscle. Therefore, passive torque-angle measurements

93 are not specific to the passive stretching response of individual muscles, especially for the
94 muscles of the shoulder joint.

95 A new ultrasound-based technology, called ultrasonic shear wave elastography, has been
96 developed that reliably and noninvasively measures soft tissue viscoelastic properties¹. Many
97 studies have quantitatively assessed the muscle shear elastic modulus *in vivo* and *in vitro*^{4, 14,}
98 ^{15, 19, 21}.

99 The occurrence of shoulder injuries are associated with the supraspinatus (SSP) muscle and
100 infraspinatus muscle because these muscles contribute to the dynamic stability of the
101 shoulder joint³⁵. We targeted the SSP because there is more evidence of reliability and
102 validity using elastography on measuring the SSP^{8, 12, 28} rather than infraspinatus muscle.
103 Specifically, researchers have reported the link between a tight SSP and abduction
104 contracture⁵.

105 Several authors have recommended effective stretching positions for the SSP based on
106 their knowledge of anatomy and kinesiology^{6, 10, 31, 36}. The positions recommended for
107 stretching the SSP are fully adducting the arm behind the back⁶, positioning the arm behind
108 the back while maintaining medial rotation¹⁰, extension, adduction, and internal rotation
109 (IR)³⁶, and placing the hand behind the back and reaching up between the shoulder blades³¹.
110 Despite these recommendations, there is no consensus on the effective stretching positions.
111 One cadaveric study recommended positioning the arm at abduction with extension as the
112 most effective stretching position for the SSP²⁴. Subsequent research has not been performed
113 *in vivo*; therefore, an *in vivo* quantitative analysis is needed to determine the effective SSP
114 stretching positions. The purpose of the present study was to quantitatively verify the
115 effective SSP stretching positions using ultrasonic shear wave elastography *in vivo*.

116 **Materials and Methods**

117 We conducted this experimental study in accordance with the Declaration of Helsinki.

118

119 2.1. Participants

120 An a priori power analysis was conducted using G*Power software version 3.1 (Heinrich
121 Heine University, Dusseldorf, Germany). We estimated that a sample size of 14 participants
122 was required based on a 0.25 effect size, 0.05 α level, and 0.8 desired power level. Therefore,
123 15 healthy men (mean \pm standard deviation; age: 23.4 ± 3.0 years, height: 172.9 ± 3.0 cm,
124 weight: 66.3 ± 6.0 kg) were included. Participants with a history of neuromuscular disease or
125 musculoskeletal injury involving the upper extremities were excluded. All participants were
126 informed of the purpose and methods of the study before providing written consent.

127

128 2.2. Data Collection

129 Shear wave speed was measured by an Aixplorer ultrasound system using an SL10-2
130 linear array transducer (Supersonic Imagine, Aix-en-Provence, France) to assess the shear
131 elastic modulus of the SSP in the nondominant shoulder. We examined the nondominant side
132 to determine the influence of the shoulder position on the shear elastic modulus of the SSP,
133 because some volunteers had experience participating in overhead sports.

134 An ultrasound probe was placed 20 mm above the midpoint between the acromial angle
135 and the root of the spine of scapula. The ultrasound images were used to align the probe
136 parallel to the SSP muscle fiber orientation as much as possible (Figure 1). Participants were
137 instructed to sit relaxed on a chair. To consistently position each participant, all procedures
138 were performed by the same 3 testers. One tester measured the shear wave speed, the second
139 fixed the participant's thorax, and the third changed the arm positions (Figure 2). To

140 minimize the measurement error, the shear elastic modulus was measured twice in the same
141 position.

142 As many measurement positions were selected as possible while preventing patient fatigue
143 and confounding results from stretching. The shear elastic modulus of the SSP was measured
144 in the 10 arm positions under the following conditions: neutral position to evaluate the effect
145 of stretching (reference), arm positions, including horizontal adduction to compare the effect
146 of horizontal abduction, which was recommended in a previous study, and different
147 combinations of varying shoulder joint angles, including horizontal adduction to detect
148 motions that emphasized SSP stretching in the 3 shoulder motions. Actual measurement
149 positions are IR at 0° elevation (Ele0), IR at 90° abduction (Abd90), IR at 90° flexion (Fle90),
150 IR at maximum extension (Ext), IR at maximum horizontal adduction with 90° elevation
151 (Ele90HAd), IR at maximum horizontal adduction with 45° elevation (Ele45HAd), IR at
152 maximum horizontal abduction with 20° elevation (Ele20HAb), IR at maximum horizontal
153 abduction with 45° elevation (Ele45HAb), IR at maximum horizontal abduction with 90°
154 elevation (Ele90HAb), and a neutral rotation at 0° elevation (Rest).

155 The arm positions were defined based on the globe system³. In this study, horizontal
156 adduction and horizontal abduction were defined as forward and backward changes of the
157 plane of elevation. Elevation of the humerus in the 90°, 0°, and -90° planes was defined as
158 flexion, abduction, and extension, respectively. The arm positions were defined as a
159 combination of 3 shoulder motions. The sequence in which the arm was moved into the
160 measurement position was elevation, subsequently horizontal abduction/adduction, and lastly,
161 rotation. For elevation, the shoulder joint was moved to 45° or 90° abduction, as measured by
162 a goniometer, and this angle was fixed during the subsequent 2 motions using a mark on a
163 vertical pole to indicate the height of the elbow. For Ele20HAb, the position was defined by
164 moving the elbow into the horizontal abduction position (ie, toward the participant's back)

165 with the elbow contacting the thorax as much as possible without necessarily maintaining the
166 height of the elbow at 20° elevation. For horizontal and rotational motion, the shoulder joint
167 was moved to the maximum range of motion the individual could tolerate without discomfort
168 or pain. The arm positions were performed in random order to preclude any effect of the
169 measurement sequence

170

171 2.3. Data Analysis

172 The mean shear wave propagation speed (m/s) within the region of interest was
173 automatically calculated. The shear elastic modulus (G) can be calculated using the shear
174 wave speed (c_s) through the following equation²⁹:

$$175 \quad G = \rho c_s^2$$

176 where ρ is the muscle mass density and is assumed to be 1,000 kg/m³.

177 Measurement reliability was assessed using the intraclass correlation coefficient ($ICC_{1,1}$)
178 with a 95% confidence interval. Comparison of the shear elastic modulus among the
179 measurement positions was assessed using the mean value \pm standard deviation.

180 A 1-way repeated measures analysis of variance was used to determine the difference in
181 the shear elastic modulus of the SSP among the stretching positions. When a significant main
182 effect was observed, the difference among positions was determined using the Bonferroni
183 post hoc test. Statistical significance was defined using an $\alpha = 0.05$ for all tests. Statistical
184 analyses were performed using IBM SPSS Statistics 22.0 software (IBM, Armonk, NY,
185 USA).

186 **Results**

187 Reliability of the shear elastic modulus was assessed using the ICC with a 95% confidence
188 interval (Table I). The ICC ranged from 0.81 for Ele90HAd to 0.98 for Rest. The shear elastic
189 modulus at Rest was 8.7 ± 3.5 kPa and moduli in other positions are provided in Table II. The
190 mean shear elastic modulus was highest at Ext, followed by Ele90HAb, Ele45HAb,
191 Ele45HAd, Abd90, Ele20HAb, Ele90HAd, Fle90, Rest, and Ele0 (Fig. 3).

192 Repeated measures analysis of variance revealed a significant effect on the shear elastic
193 modulus. Bonferroni post hoc tests indicated that the shear elastic moduli in 3 positions (Ext,
194 Ele90HAb, and Ele45HAb) were significantly greater than those in the other 7 positions (Fig.
195 3). Only these 3 positions had shear elastic moduli that were significantly greater than that at
196 Rest (Table II), and there were no significant differences in shear elastic moduli among these
197 3 positions. Differences in shear elastic moduli among the other 7 positions were not
198 significant.

199 **Discussion**

200 The results of this study show that the shear elastic moduli in Ext, Ele90HAb, and
201 Ele45HAb were significantly greater than those in the other 7 positions. This suggests that
202 these 3 positions are more effective stretching positions for the SSP than the other 7 positions.
203 To the best of our knowledge, this is the first report to investigate the effective SSP stretching
204 positions using quantitative analysis with ultrasonic shear wave elastography in vivo.

205 In this study, the ICC ranged from 0.81 to 0.98 for all positions. ICCs in this range rank as
206 “almost perfect” reliability according to the criteria of Landis²⁰. Therefore, we consider the
207 data in this study reliable. The Rest position was the most reproducible position and,
208 therefore, the shear elastic modulus in that position had the highest reliability. In contrast, the
209 shear elastic modulus in Ele90HAd demonstrated the lowest reliability among the 10
210 positions.

211 The shear elastic moduli in Ext, Ele90HAb, and Ele45HAb were significantly greater than
212 that in Rest, suggesting that these 3 positions are effective SSP stretching positions. In
213 contrast, the shear elastic moduli in Ele0, Abd90, Fle90, Ele90HAd, Ele45HAd, and
214 Ele20HAb did not differ significantly from that in Rest, suggesting that these positions are
215 not effective SSP stretching positions. All effective stretching positions found in this study
216 include elevation, horizontal abduction, and maximum IR.

217 In clinical rehabilitation and sports, the cross-body stretch and the sleeper stretch have
218 been widely used to improve posterior shoulder tightness. These positions are similar to the
219 Ele90HAd and Fle90 positions used in this study. However, the shear elastic moduli in
220 Ele90HAd and Fle90 were not significantly different compared with that in Rest. Our results
221 suggest that horizontal abduction is more important than horizontal adduction for stretching
222 the SSP. In other words, the arm is positioned not in front but in the back of the body to
223 stretch the SSP effectively. In previous studies, the SSP has been found to have an IR

224 moment arm at 90° of humeral elevation in the sagittal plane¹⁷. In the position in which SSP
225 has an IR moment arm, contraction of SSP leads to IR. In other words, to stretch the SSP at
226 90° humeral elevation in the sagittal plane, the humerus must be externally rotated, not
227 internally rotated.

228 Because differences in the shear elastic moduli among Ext, Ele90HAb, and Ele45HAb
229 were not significant, we could not identify the most effective stretching position. The shear
230 elastic moduli in Ext, Ele90HAb, and Ele45HAb were significantly greater than that in
231 Ele20HAb. It is likely that higher elevation of the humerus behind the body is important to
232 stretch the SSP.

233 Some of the following SSP stretching positions have been recommended: fully adducting
234 the arm behind the back⁶, positioning the arm behind the back while maintaining medial
235 rotation¹⁰, and placing the hand behind the back and reaching up between the shoulder
236 blades³¹. In terms of the distance between the elbow and the back, these 3 recommended
237 positions are similar to the Ele20HAb position used in this study. Judging from the results of
238 this study, these 3 positions need to emphasize elevation to effectively stretch the SSP.
239 Previous studies evaluated other factors, such as muscle contraction, pressure to the muscle,
240 traction on the bone, and posture of the whole body, in addition to shoulder position. These
241 factors may influence the effect of stretching. In contrast, Ylinen³⁶ recommended extension,
242 adduction, and IR. When compared with elevation, this position is an effective SSP stretch. In
243 terms of the importance of elevation and horizontal abduction, our results are similar to those
244 of the quantitative analysis using cadavers reported by Muraki et al.²⁴ All of our test positions,
245 except for Rest, included maximum IR. Whether maximum IR is necessary or not will require
246 further study.

247 This study had several limitations. First, all of the participants in this study were healthy
248 young men. Sex, age, and differences in sport and disease experience may affect the shear

249 elastic modulus of the shoulder muscles; therefore, we need to be careful when using these
250 results for therapy and training in clinical or athletic settings.

251 Second, we allowed the free movement of the scapula when positioning the humerus.
252 Measuring the movement of the scapula may produce more accurate results. In addition to the
253 shoulder position, most of the previous authors examined muscle contraction, pressure to the
254 muscle, traction on the bone, and posture of the whole body. However, the focus of the
255 current study was to evaluate the influence of the shoulder position only. Examining the
256 influence of these other factors will be necessary in future studies.

257 We only evaluated the SSP in this study. Further measurements targeting the infraspinatus
258 and other muscles should be conducted. By clarifying effective positions in multiple muscles,
259 we may be able to determine the position needed to stretch multiple muscles simultaneously
260 or to selectively stretch 1 muscle.

261

262 **Conclusions**

263 This study used quantitative analysis to determine the effective stretching positions for the
264 SSP muscle, using ultrasonic shear wave elastography in vivo. Our results suggest that
265 maximum internal rotation at maximum extension, maximum internal rotation at maximum
266 horizontal abduction with 90° elevation, and maximum internal rotation at maximum
267 horizontal abduction with 45° elevation are effective stretching positions for the SSP muscle.

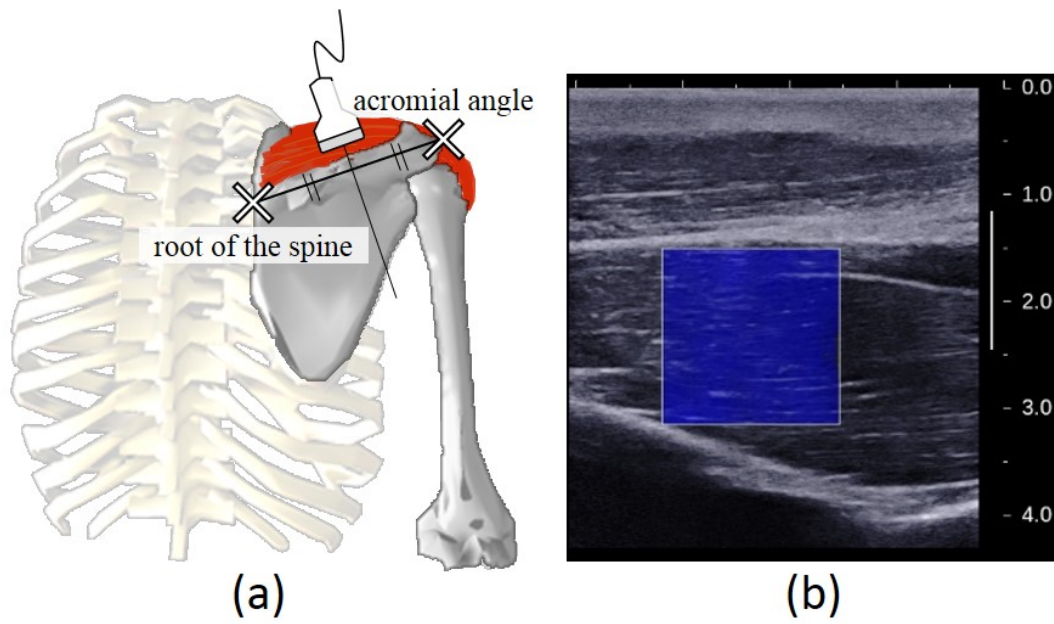
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- 372

373 **Figure and Table Legends.**



374

375 **Figure 1** Position and angle of the probe during measurement. (a) An ultrasound probe was
376 placed 20 mm above the midpoint between the acromial angle and the root of the spine of
377 scapula. (b) The ultrasound images were used to align the probe parallel to the supraspinatus
378 muscle fiber orientation as much as possible.

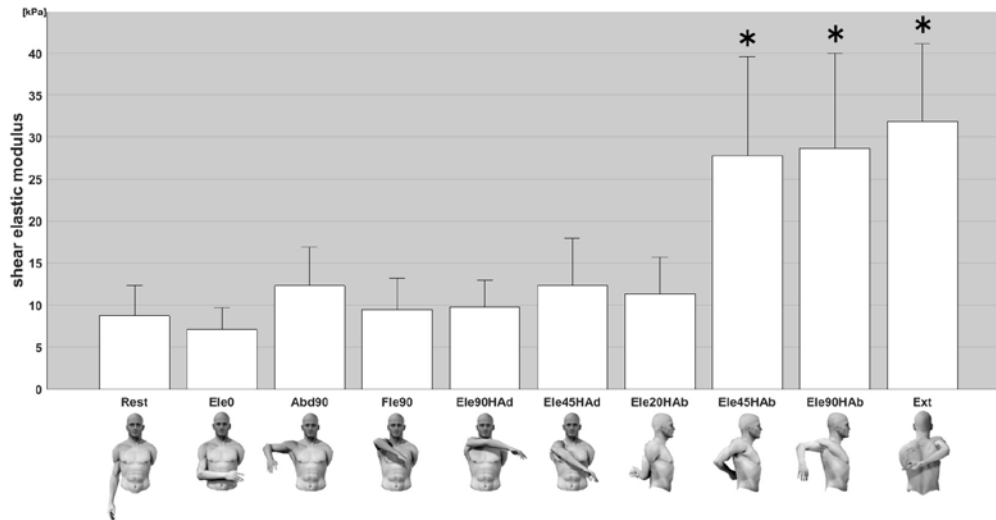
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381 **Figure 2** Experimental setup. Participants were instructed to sit relaxed on a chair. To
382 consistently position each participant, all procedures were performed by the same 3 testers:
383 the first tester measured the shear wave speed, the second fixed the participant's thorax, and
384 the third changed the arm positions.

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387 **Figure 3** Shear elastic moduli of the supraspinatus muscle in each measurement position. The

388 error bar shows the standard deviation. *Indicates that the shear elastic moduli in Ext,

389 Ele90HAb, and Ele45HAb were significantly greater than those in the other 7 positions:

390 Ele45HAb–Rest ($P = .002$), Ele45HAb–Abd90 ($P = .011$), Ele45HAb–Fle90 ($P = .005$),

391 Ele45HAb–Ele90HAd ($P = .002$), Ele45HAb–Ele45HAd ($P = .047$), Ele45HAb–Ele20HAb

392 ($P = .007$), Ele90HAb–Rest ($P = .001$), Ele90HAb–Abd90 ($P = .013$), Ele90HAb–Fle90

393 ($P = .001$), Ele90HAb–Ele90HAd ($P = .001$), Ele90HAb–Ele20HAd ($P = .002$), and the other

394 positions ($P < .001$). Rest, neutral rotation at 0° elevation; Ele0, maximum internal rotation at

395 0° elevation; Abd90, maximum internal rotation at 90° abduction; Fle90, maximum internal

396 rotation at 90° flexion; Ele90HAd, maximum internal rotation at maximum horizontal

397 adduction with 90° elevation; Ele45HAd, maximum internal rotation at maximum horizontal

398 adduction with 45° elevation; Ele20HAb, maximum internal rotation at maximum horizontal

399 abduction with 20° elevation; Ele45HAb, maximum internal rotation at maximum horizontal

400 abduction with 45° elevation, Ele90HAb, maximum internal rotation at maximum horizontal

401 abduction with 90° elevation; Ext, maximum internal rotation at maximum extension.

402

403 **Table I** Intraclass correlation coefficient in each measurement position.

Position	ICC [95% CI]
Rest	0.98 [0.95, 0.99]
Ele0	0.85 [0.61, 0.94]
Abd90	0.93 [0.80, 0.97]
Fle90	0.84 [0.60, 0.94]
Ele90HAd	0.81 [0.53, 0.93]
Ele45HAd	0.93 [0.80, 0.97]
Ele20HAb	0.96 [0.90, 0.99]
Ele45HAb	0.97 [0.91, 0.99]
Ele90HAb	0.94 [0.83, 0.98]
Ext	0.93 [0.81, 0.98]

404 ICC, intraclass correlation coefficient; CI, confidence interval; Rest, neutral rotation at 0°
 405 elevation; Ele0, maximum internal rotation at 0° elevation; Abd90, maximum internal
 406 rotation at 90° abduction; Fle90, maximum internal rotation at 90° flexion; Ele90HAd,
 407 maximum internal rotation at maximum horizontal adduction with 90° elevation; Ele45HAd,
 408 maximum internal rotation at maximum horizontal adduction with 45° elevation; Ele20HAb,
 409 maximum internal rotation at maximum horizontal abduction with 20° elevation; Ele45HAb,
 410 maximum internal rotation at maximum horizontal abduction with 45° elevation; Ele90HAb,
 411 maximum internal rotation at maximum horizontal abduction with 90° elevation; Ext,
 412 maximum internal rotation at maximum extension.

413

414 **Table II** Shear elastic modulus of the supraspinatus muscle in each measurement position.

Position	Mean \pm S.D. [kPa]	p value (Comparison with Rest)
Rest	8.7 \pm 3.5	-
Ele0	7.1 \pm 2.6	>0.999
Abd90	12.3 \pm 4.4	0.725
Fle90	9.4 \pm 3.6	>0.999
Ele90HAd	9.8 \pm 3.0	>0.999
Ele45HAd	12.4 \pm 5.4	>0.999
Ele20HAb	11.3 \pm 4.2	>0.999
Ele45HAb	27.8 \pm 11.4	0.002
Ele90HAb	28.7 \pm 11.0	0.001
Ext	31.9 \pm 8.9	< 0.001

415 SD, standard deviation; Rest, neutral rotation at 0° elevation; Ele0, maximum internal
 416 rotation at 0° elevation; Abd90, maximum internal rotation at 90° abduction; Fle90,
 417 maximum internal rotation at 90° flexion; Ele90HAd, maximum internal rotation at
 418 maximum horizontal adduction with 90° elevation; Ele45HAd, maximum internal rotation at
 419 maximum horizontal adduction with 45° elevation; Ele20HAb, maximum internal rotation at
 420 maximum horizontal abduction with 20° elevation; Ele45HAb, maximum internal rotation at
 421 maximum horizontal abduction with 45° elevation; Ele90HAb, maximum internal rotation at
 422 maximum horizontal abduction with 90° elevation; Ext, maximum internal rotation at
 423 maximum extension.