1 Fullerene-like structures of Cretaceous crinoids reveal topologically limited skeletal

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There are few cases where numbers or types of possible phenotypes are known, although vast 12 state spaces have been postulated. Rarely applied in this context, graph theory and topology 13 enable enumeration of possible phenotypes and evolutionary transitions. Here, we generate 14 15 polyhedral calvx graphs for the Late Cretaceous, stemless crinoids *Marsupites testudinarius* and Uintacrinus socialis (Uintacrinoidea Zittel) revealing structural similarities to carbon 16 fullerene and fulleroid molecules (respectively). The U. socialis calyx incorporates numerous 17 plates (e.g. graph vertices $|V| \ge 197$), which are small, light, low-density and have 4 to 8 18 sides. Therefore, the corresponding number of possible plate arrangements (number of 19 polyhedral graphs) is large (>> 1×10^{14}). Graph vertices representing plates with sides > 6 20 introduce negative Gaussian curvature (surface saddle points) and topological instability, 21 increasing buckling risk. However, observed numbers of vertices for Uintacrinus do not 22 allow more stable pentaradial configurations. In contrast, the Marsupites calyx dual graph has 23 17 faces that are pentagonal or hexagonal. Therefore, it is structurally identical to a carbon 24 fullerene, specifically C30-D5h. Corresponding graph restrictions result in constraint to only 25

26	three structural options (fullerene structures C30-C2v 1, C30-C2v 2 and C30-D5h). Further
27	restriction to pentaradial symmetry allows only one possibility: the Marsupites phenotype.
28	This robust, stable topology is consistent with adaptation to predation pressures of the
29	Mesozoic marine revolution. Consequently, the most plausible evolutionary pathway between
30	unitacrinoid phenotypes was a mixed heterochronic trade-off to fewer, larger calyx plates.
31	Therefore, topological limitations radically constrained uintacrinoid skeletal possibilities but
32	thereby aided evolution of a novel adaptive phenotype.
33	Keywords
34	Evolution, graph theory, echinoderms, morphological state space, morphospace, constraint.
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36	Crinoids are a taxonomic class of extant echinoderms (Ausich et al. 1999), first
37	known from the Ordovician Period, branching off early in echinoderm phylogeny (Comeau et
38	al. 2017; Wright & Toom 2017) and retaining many characteristics thought to be primitive
39	for the echinoderms as a whole (Oji & Twitchett 2015). Phylogenetically, echinoderms are
40	bilaterians placed in clade Ambulacraria, the sister group to the chordates. Ancestral bilateral
41	symmetry (Zamora et al. 2012) is retained today in echinoderm larvae and has been
42	secondarily derived in some groups (e.g. irregular echinoid sea urchins) (Omori et al. 2018).
43	However, among many echinoderms, including early crinoids (Guensburg et al. 2015; Omori
44	et al. 2018), metamorphosis results in a typically pentaradial adult (with fivefold rotational
45	symmetry) arguably the most modified bilaterian body plan (Zamora et al. 2012; Byrne et al.
46	2016). Like most other echinoderms, crinoids are primarily (though not exclusively) benthic
47	(living on, or burrowing within, the seafloor). Considering both fossil and extant
48	representatives, most crinoids had a basal holdfast (for attachment to the substrate) and a
49	stalk elevating the calyx, which includes the fixed plates (below the free arms) and contains
50	the major organs and mouth (Ausich et al. 1999). However, some show extreme divergence

51 from this ground-plan. These included the stemless Cretaceous uintacrinoids, of genera 52 Uintacrinus and Marsupites. These are thought to be closely related, as phylogenetic sister 53 groups (Milsom et al. 1994), currently classified as two families Uintacrinidae Zittel, 1879 54 and Marsupitidae d'Orbigny, 1852 which together form the superfamily Uintacrinoidea (Zittel 1879, placed within order Comatulida (Hess & Messing 2011). Uintacrinoids are closely 55 associated with the chalk substrate of the Cretaceous shallow seas (Table S1). They had a 56 57 global distribution (Gale et al. 1995, 2008) and joint temporal range of ~86-78 Ma, from the Santonian to Campanian stages of the Late Cretaceous period (Gale et al. 2008; Hess & 58 59 Messing 2011), though Uintacrinus and the later appearing Marsupites coexisted for less than 1 million years (Milsom et al. 1994). Both genera possessed long feeding arms and an 60 enlarged, close-to-spherical calyx, composed of 16 large plates in Marsupites but many more, 61 62 small plates in Uintacrinus (Figs. 1-2). This expanded calyx is thought to have functioned as a chalk, soft-sediment, stabiliser (Milsom et al. 1994; Hess & Messing 2011; Gorzelak et al. 63 2017) or pelagic floatation chamber (Bather 1896; Springer 1901; Seilacher & Hauff 2004). 64 Extreme structural modification into these evolutionarily unusual, free-living forms is, 65 therefore, a potential adaptive response to the soft, chalk substrate conditions of the 66 Cretaceous seas and/or high and increasing (Kerr & Kelley 2015) predation pressure (Meyer 67 & Macurda 1977; Bottjer & Jablonski 1988) of the Mesozoic Marine Revolution (Baumiller 68 et al. 2010; Gorzelak et al. 2016), a time of marine evolutionary radiation and ecological 69 70 restructuring (Buatois et al. 2016). However, these unusual and functionally controversial 71 morphologies have not previously been analysed within a quantitative framework. One method which enables the formal analysis and quantification of biological 72 structures such as the crinoid calyx, is the use of graph (network) theory and topology. This 73

falls within the broader field of theoretical (and particularly mathematical) morphology (e.g.

pioneered by (Thompson 1942; Raup & Michelson 1965)), which also links to other methods

76 such as geometric morphometrics (e.g. landmark analysis) and morphospace analyses (which 77 place forms along theoretical spatial axes) (Dera et al. 2008; Rasskin-Gutman & Esteve-Altava 2014). Graph theory, specifically, enables enumeration and generation of theoretical 78 79 structural possibilities for elements (represented by vertices, V) and their connections (represented by edges, E) in a graph (G = V, E). Topology additionally considers the 80 geometry of such mathematical structures in physical space (Cromwell 1997). Graph theory 81 82 and topology provide laws for structures and structural transitions that can be physically realized, with several fundamental theorems initially proposed by Leonhard Euler in the 18th 83 84 century (Cromwell 1997). Though, so far, comparatively rarely applied to the analysis of biological phenotypes, graph theory has extremely wide potential applicability (as it can be 85 used to evaluate connections between essentially any type of entity) and has been used, for 86 87 example, to analyse skeletal structures of both invertebrates (including echinoderms (Zachos 88 2009; Saucède et al. 2015)) and vertebrates (Laffont et al. 2011).

These techniques therefore enable enumeration of physically possible morphologies, 89 by placing biologically realistic conditions on the types of graphs permitted (as detailed 90 below) and counting the different (non-isomorphic) possibilities. This is particularly valuable 91 because it gives an otherwise rare (Donoghue & Ree 2000) opportunity to explore the number 92 of possible phenotypes (the size of a morphological state space), facilitating the exploration 93 94 of mathematical and physical constraints on biological evolution (e.g. mathematical or 95 physical limits on the types or numbers of biological forms that are theoretically possible). Enumeration of structural possibilities using graph theory thereby also offers an explicit 96 method to determine the number of possible morphological character states. This is of key 97 98 utility for new efforts to outline probabilistic models of morphological evolution, for example by forming the denominator for a phylogenetic transition probability (Hoyal Cuthill 2015). 99 The concept of the state space is theoretically linked to that of the morphospace, which (given 100

the definitions of each term above) can be considered as a sub-type of state space which
specifically visualises both the number of morphological possibilities and projected locations
of given forms within it. A graph theoretic approach has previously been used, for example,
to analyse connections between labelled plates of the apical disc, the upper part of the
echinoid test (Laffont *et al.* 2011; Saucède *et al.* 2015). A topological approach, additionally
considering the properties of graphs when embedded in physical space, has also been used,
for example, to model the growth of the echinoid test through life (Zachos 2009).

Here, we generate complete, unlabelled graphs of calyx structure for the unusual Late 108 109 Cretaceous crinoids Uintacrinus and Marsupites, which we show to have informative structural and topological similarities to the carbon fullerenes, which are polyhedral, trivalent 110 carbon molecules (Schwerdtfeger et al. 2015) which, like the calyx of Marsupites, have 111 graphs with only pentagonal or hexagonal faces. This graph theoretic approach allows us to 112 enumerate all physically realisable structural alternatives for uintacrinoid skeletons, given 113 biophysically relevant graph conditions of increasing restrictiveness (specifically graphs 114 constrained to be: planar, polyhedral, fullerene and pentameral, with D5h symmetry). This 115 thereby extends previous approaches considering graphs that are not guaranteed to be 116 physically realizable (e.g. planar graphs of isolated parts of the test (Saucède et al. 2015)) to 117 enumerate the number of possible graphs that could be actually realized as physical structures 118 (e.g. polyhedral calyces). The latter conditions on the graphs, such as pentameral symmetry 119 120 in particular, are strongly motivated by modes of echinoderm growth. We then utilise theoretical work on the structure of carbon fullerenes and the related, but often less 121 topologically stable, fulleroid molecules (Schwerdtfeger et al. 2015) to discuss the 122 topological stability of alternative calyx skeletal structures and the implications for their 123 function and evolution. 124

125 METHOD

126 *Graph analysis*

Graph theoretic analyses were performed to determine possible combinations of skeletal plate adjacencies (structures) for uintacrinoid calyces. This approach considers the number of possible, different (non-isomorphic) arrangements of a given number of plates (i.e. possible calyx structures), without reference to specific spatial locations of plates. These analyses used unlabelled graphs, which represent structures without reference to the identity of individual elements, removing the requirement for plate homologies to be known *a priori* (e.g. (Saucède *et al.* 2015)).

134 Skeletal graphs

To analyse the possible structural arrangements of uintacrinoid calyces, we modelled 135 calyx theoretical structures using a skeletal graph G (G = V, E). This graph has a specified 136 number |V| of vertices V and a corresponding number |E| of edges E (representing potential 137 vertex adjacencies) (Saucède et al. 2015). Skeletal graphs were constructed with reference to 138 observations of plate numbers and adjacencies in specific fossil specimens (primarily from 139 the species Marsupites testudinarius and Uintacrinus socialis Table S1). Each calvx plate 140 was initially represented using a vertex and each plate adjacency represented by an edge 141 connecting the vertices that represent adjacent plates. 142

143 Graph constraints

Alternative structural arrangements for uintacrinoid calyces were then enumerated and explored by applying biophysically motivated mathematical conditions on the allowed graphs, which were based on observations of the studied species. To do this, we placed a hierarchical series of mathematical conditions on the skeletal graphs (Table 1), which correspond to biophysical constraints on theoretical calyx structures (combinations of possible plate adjacencies which could be simultaneously realised).

150 *Planar graphs*

A reasonable initial restriction is that echinoderm skeletal graphs should be planar (Saucède *et al.* 2015) (meaning the graph can be embedded on a plane without crossing edges (Schwerdtfeger *et al.* 2015)). A further, biologically realistic and appropriate condition for this analysis of theoretical structural possibilities is that echinoderm skeletal graphs should be simple (unweighted, undirected and without edge loops) and connected (every vertex is connected by an edge to at least one other vertex). The latter condition is required since, articulated skeletons in the studied taxa do not have isolated, disconnected plates.

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Polyhedral skeletal graphs

159 Beyond this, realistic graphs of certain echinoderm skeletal structures should be polyhedral. This includes the enlarged, spheroidal calyces of Uintacrinus and Marsupites. A 160 polyhedron can be defined simply as a solid, three dimensional shape bounded by a given 161 number of polygonal faces (F) (Cromwell 1997). Through duality, every convex polyhedron 162 with |F| = n faces can be represented by a polyhedral graph with |V| = n vertices and vice 163 versa (Duijvestijn & Federico 1981; Grünbaum 2003). A polyhedral graph is simple, 3-164 vertex-connected (remains connected if fewer than 3 vertices are removed) and planar. 165 Enumeration of all polyhedral graphs with a given number of vertices therefore enables the 166 enumeration of all different structural arrangements which theoretically are physically 167 realizable as polyhedra. Unfortunately, there is no known general formula to calculate the 168 number of possible polyhedral graphs from the number of vertices, edges or faces 169 170 (Duijvestijn & Federico 1981). However, polyhedral graphs can be constructed algorithmically and counted for specified numbers of vertices (within general computational 171 limits) (Brinkmann & McKay 2007). Other structures such as echinoid tests could also be 172 considered within this framework of polyhedral graph enumeration. For example, polyhedral 173 graphs can map to maximal planar (triangulated) graphs (Stojanović 2016), a computational 174 structure used to model plate growth and movement in developing echinoids (Zachos 2009). 175

Numbers of possible polyhedral graphs (Table 1) were calculated for specified 176 numbers of vertices in the program plantri Version 4.5, Brinkmann and McKay, 2011 177 (https://users.cecs.anu.edu.au/~bdm/plantri/) (Brinkmann & McKay 2007). Plantri 178 algorithmically generates planar graphs under specified conditions and counts the numbers of 179 distinct isomorphism classes. This process is computationally intensive and for larger 180 numbers of plates (Table 1) individual analyses had a run-time of one to two weeks on a 181 182 desktop PC. The command plantri -p |V| was used to generate all non-isomorphic, 3connected, planar, simple graphs (convex polytopes), where |V| is the number of vertices in a 183 184 skeletal graph. The numbers of possible non-isomorphic fullerene graphs and their symmetry groups were enumerated using the plantri command fullgen |V| (Brinkmann & Dress 1997; 185 Brinkmann & McKay 2007). 186

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Dual graphs

For any polyhedral graph, e.g. with vertices representing skeletal plates, a dual graph can be constructed (Schwerdtfeger *et al.* 2015) with vertices representing plate corners. A graph and its dual have the same number of edges. For any polyhedral graph, Euler's formula relates the number of edges (|E|), vertices (|V|) and faces (|F|): |V| - |E| + |F| = 2. The skeletal dual graph for *Marsupites*, in which vertices represent plate corners, was constructed in Matlab using a script written by J.F.H.C (Supplementary Computer Code). Graphs were constructed and visualised using the program Gephi (Bastian *et al.* 2009).

195 Specimen selection and data collection

196 All available specimens of *Marsupites* and *Uintacrinus* were examined at the Sedgwick

197 Museum of Earth Sciences, University of Cambridge, the Natural History Museum, London

and the Booth Museum of Natural History, Brighton. The specimen set on which this study is

199 specifically based comprised thirty well-articulated calyx specimens plus sixty-two

200 disarticulated (isolated) plate specimens (Table S1). Nine, three dimensionally preserved

specimens of *Marsupites* were selected for 3D laser and photosurface scanning using a Next
Engine HD Pro scanner at the Sedgwick Museum to aid visualisation and examination of
morphology (specimen numbers B24289, B65206, B3871, B3874-75, B3877-78, B3915,

204 B3917).

205 Plate measurement methodology

Measurements (Tables S-S3) were taken from the 62 disarticulated calyx plates, from M. 206 207 testudinarius or U. socialis, held in the Sedgwick Museum of Earth Sciences. Plate thickness was measured using digital calipers with an accuracy of 0.01 mm, with five measurements 208 209 around the edge used to calculate the average thickness of each plate. The surface area of one side of the plate (outer) was measured from digital photographs using a Matlab script written 210 by J.F.H.C. Plate weight was measured using digital scales with an accuracy of 0.001 g. Plate 211 bounding volume was estimated as upper surface area × thickness. Weight/bounding volume 212 (g/mm³) was then calculated giving a measure of plate bounding density (which we note is 213 214 distinct from other possible measures such as internal stereom density e.g. (Gorzelak et al. 2017). 215

216 *Statistical analysis*

217 Statistical analyses of measurements from 62 disarticulated uintacrinoid plates (Table S3, Table S4) were performed using the program Past Paleontological Statistics version 3.14 218 (Hammer et al. 2001). These tested for differences between M. testudinarius and U. socialis 219 in mean plate thickness (mm), weight (g), area (mm²), volume (mm³) and bounding density 220 (weight/bounding volume, g/mm³). Shapiro-Wilk's tests (Table S4) established whether data 221 were normally distributed (with $p \ge 0.05$). Where data were normally distributed, two-sample 222 t-tests were used to determine if means were significantly different (with p < 0.05). 223 Otherwise, non-parametric Mann-Whitney U tests were used to test medians. 224

226 **RESULTS**

227 Observed variation in skeletal structure

228 The structure of the calyx in Marsupites testudinarius was consistent between observed specimens, consisting of 1 centrale plate, plus 3 plate circlets comprising 5 229 infrabasal, 5 basal, and 5 radial plates (dicyclic form, with 2 circlets below the radials 230 (Ausich et al. 1999)). In contrast, Uintacrinus socialis shows intra-specific variability in the 231 232 number of cup plates (Springer 1901), with 1 to 5 presumed infrabasals reported to be present in approximately half (Rasmussen 1978) of specimens (e.g. Fig. S1) and absent in the 233 234 remainder (monocylic form, with only 2 cup plate circlets e.g. Fig. 2) (Springer 1901; Rasmussen 1978). In Marsupites, the central plate is always approximately pentagonal, 235 followed by sequential circlets of pentagonal infrabasals, hexagonal basals, and radials 236 described as pentagonal (Rasmussen 1978), plus a tegmen opening modelled as pentagonal 237 based on its five radial plate adjacencies (Fig. 1). The consistency of this arrangement gives 238 Marsupites its striking structural regularity. However in Uintacrinus socialis, plate shape 239 varies strongly, even among plates of the cup (centrale, infrabasal, basals and radials), within 240 and between individuals (Fig. 2, Fig. S1; Plate II of (Springer 1901)). The fixed calyx of U. 241 socialis specimen number B11572, for example, contains plates with 4, 5, 6, 7 and 8 sides 242 (Fig. 2). Therefore, fundamental features of calyx structure do not appear to have been fixed 243 within this Uintacrinus species or its populations (a phenomenon also observed during extant 244 245 crinoid development (Comeau et al. 2017)). These features include the number of cup circlets, their monocyclic versus dicyclic arrangement, and calyx plate shapes. These detailed 246 observations, primarily from the species *M. testudinarius* and *U. socialis* (Table S1), are 247 248 consistent with the wider morphological descriptions for these genera (Rasmussen 1978; Hess & Messing 2011), indicating that these observations are informative with regard to the 249 morphological evolution of each genus in its entirety. 250

Exceptional specimens of *Marsupites* preserve at least 3 (Fig. S2) to 6 (Rasmussen 1978) articulated interbrachial plates between the radials and arms (and 1-3 intersecundibrachs are additionally reported for some specimens) (Rasmussen 1978). Thus in the context of the wider skeleton, the radial plates can be seen to contact at least 7 neighbouring plates (comparable to *Uintacrinus*, Fig. 2), although they remain close to pentagonal in shape (Figs. 1, S2).

257 Numbers of possible skeletal graphs

258 Planar graphs

Planar graphs appropriately represent skeletal structures in which plates contact only at their lateral edges (Saucède *et al.* 2015), for example the calyces of the crinoids *Marsupites* and *Uintacrinus*. We note, however, that not all echinoderm skeletons may be realistically represented by planar graphs. For example, clypeasteroid echinoid tests include internal supports which connect oral and apical plates (requiring representation by a non-planar graph) (Nebelsick *et al.* 2015). The number of possible planar graphs is extremely large for even moderate numbers of plate vertices (Table 1).

266 Polyhedral skeletal graphs

The entire fixed calyx of *Marsupites* has been considered to comprise 16 polygonal 267 cup plates (Milsom et al. 1994), with an additional dorsal opening, in life likely covered by a 268 tegmen membrane typical of post-Palaeozoic crinoids. While not found preserved in 269 270 Marsupites, a carbonized tegmen with calcite grains has been observed in Uintacrinus (Milsom et al. 1994). Frequently, in otherwise well-preserved Marsupites fossils, all other 271 plates, above the radials, are disarticulated (e.g. Fig. 1). This calyx structure can therefore be 272 represented using a polyhedral graph (physically realizable as a polyhedron) with 17 vertices 273 and 45 edges (Fig. 1C). Each vertex represents a calyx plate (or the one tegmen) and edges 274 represent their adjacencies. The degree (number of incident edges) of each plate vertex 275

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corresponds both to the number of neighbouring plates and the number of plate sides. Given 17 vertices, the number of possible polyhedral graphs is 6.4×10^{12} (Table 1). 277

In contrast, the fixed calyx of Uintacrinus has been considered to contain far more 278 plates than Marsupites (Fig. 2), with fixed brachial plates, up to the 8th secundibrachial, and 279 fixed pinnules, beginning from the 2nd secundibrachial (Milsom et al. 1994). Unlike 280 281 Marsupites, articulated Uintacrinus fossils are usually flattened so that the complete calyx cannot be viewed in three-dimensions in any single specimen (although many of the 282 specimens available in museum collections are otherwise exceptionally preserved) (Springer 283 284 1901). While this makes the precise number of calyx plates difficult to determine with certainty, in any Uintacrinus specimen, at least 197 can be inferred based on specimens with 285 exceptionally good preservation (Figs. 2-3, Table S2, Figs. S3-S5). This number of vertices 286 exceeds general computational limit for algorithmic generation of polyhedral graphs 287 (Brinkmann & McKay 2007). However, at 18 plate vertices (for comparison against the 17 288 vertices for *Marsupites*) the number of possible polyhedral graphs is already 1×10^{14} (Table 289 1), showing that the space of possible polyhedral graph structures becomes far larger for 290 291 calyx plate numbers exceeding those of Marsupites.

The number of possible polyhedral graphs therefore remains very large (> 6 trillion) 292 for uintacrinoid calyx graphs (Table 1). However, applying this biologically realistic 293 condition nonetheless reveals an enormous narrowing of structural possibilities. Relative to 294 the vast state-space of planar graphs, restriction to polyhedral graphs leads to a reduction of at 295 least 13 in the order of magnitude of the state space (Table 1). 296

Fullerene graphs 297

The Marsupites calyx graph (Fig. 1C, Table S5) has 17 plate vertices and 45 edges. 298 This specific graph has been studied in other mathematical contexts where it is known as the 299 Errera graph (Hutchinson & Wagon 1998). Its dual graph (Fig. 1D, Table S6) is a polyhedral, 300

trivalent graph (in which each vertex has degree 3), with 17 faces, 30 vertices and 45 edges
(Fig. 1D). This graph also represents a carbon fullerene molecule, C30-D5h, which has a
single fivefold rotational symmetry axis (D5 symmetry group) and a perpendicular mirror
plane (D5h symmetry group (Cromwell 1997)). There are three possible, non-isomorphic
fullerene graphs with 30 vertices (Table 1, fullerenes C30-C2v 1, C30-C2v 2 and C30-D5h,
with the two fullerenes of group C2v having twofold symmetry).

307 The calyx of U. socialis contains plates with 4 to 8 sides (Figs. 2-3, Table S7). Therefore, not all fixed calyx plates are pentagons or hexagons. Consequently, the 308 309 Uintacrinus calyx dual graph is more comparable to a fulleroid graph (which allows faces with any number of sides greater than 5 (Kardoš 2007; Schwerdtfeger et al. 2015), although 310 occasional plates with four sides (e.g. Figs. 2, S3) deviate from an exact correspondence with 311 fulleroid structures. With the condition of only pentagonal or hexagonal faces removed, the 312 number of possible skeletal structures can again be considered using the number of possible 313 polyhedral graphs (Table 1). 314

315 Measurements of plate size, weight and density

Measurements of 62 disarticulated calyx plates showed that, on average, plates of U. socialis were significantly smaller than those of M. testudinarius in terms of area, thickness and estimated volume. They were also lighter in weight and lower in estimated bounding density (weight/bounding volume, g/mm³, Table S3).

320 **DISCUSSION**

321 Comparisons between Uintacrinus and Marsupites

322 *Marsupites* and *Uintacrinus* show marked similarities in overall skeletal structure. 323 These similarities include the presence of articulated interbrachial plates in exceptional 324 specimens of *Marsupites*, which are therefore comparable in location and numbers of 325 contacts to those fixed into the calyx of *Uintacrinus*. Indeed, Rasmussen grouped these

interbrachials of *Marsupites* as calyx plates, while noting that they met the brachials with 326 loose sutures. Furthermore, among some, and particularly small, specimens of Uintacrinus 327 socialis, the number of fixed interbrachial calyx plates (below the first fixed pinnules) is 328 comparatively low, overlapping that seen in Marsupites (e.g. 5-6 in Plate VI Fig. 4 of 329 (Springer 1901)). In contrast, other, larger specimens show a greater number of 330 interbrachials, as well as interradials. For example, 12 interbrachials are visible below the 331 332 first fixed pinnule in U. socialis specimen B11572 (Fig. 2). This indicates a growth trajectory in which interbrachial plates continue to be added during growth and development throughout 333 334 life (Springer 1901; Rasmussen 1978). The structure of the arms is also similar in the two genera, supporting a close phylogenetic relationship (Milsom et al. 1994), with arms 335 branching once at the same inferred position (the second primibrach (Rasmussen 1978)), and 336 complete pinnulation reported from the outer 2nd secundibrachs (Rasmussen 1978; Milsom et 337 al. 1994) (although pinnules are not as well preserved in even well-articulated Marsupites 338 fossils, e.g. Fig. S2, as in Uintacrinus, e.g. Fig. 2). 339

However, Marsupites and Uintacrinus show contrasting strategies in the composition 340 of the fixed calyx. *Uintacrinus* has a fixed calyx of greater maximum size (at \leq 75 mm in 341 diameter (Rasmussen 1978)) with more plates, while individual plates are smaller, lighter and 342 less dense (weight/bounding volume, g/mm³, Table S3). The slightly smaller calyx of 343 *Marsupites* (at ≤ 60 mm in diameter (Rasmussen 1978)) is instead mainly composed of 344 considerably larger and more robust cup plates (Fig. 1). For example, the cup plates represent 345 approximately 20% of the distance between the centrale and distal interbrachial (below the 346 first fixed pinnule) in U. socialis (Fig. 2), but 80% in M. testudinarius (Fig. S2). The two 347 genera also differ in the structure of the calyx cup, which is fixed to a dicyclic arrangement in 348 Marsupites (with 2 plate circlets below the radials (Ausich et al. 1999) but polymorphic, with 349 both monocyclic (1 sub-radial plate circlet) and dicyclic arrangements present in Uintacrinus 350

351 (Rasmussen 1978), even among intraspecific specimens (e.g. of *U. socialis*) from the same
352 locality (Springer 1901).

353 *Uintacrinoid calyx graphs and similarity to carbon fullerenes*

Fullerenes are carbon molecules in which each carbon atom bonds to 3 others, forming cage-like structures with often near-spherical, polyhedral shapes (such as C₆₀, buckminsterfullerene) (Schwerdtfeger *et al.* 2015). Therefore, fullerene graphs are trivalent graphs (each vertex has 3 incident edges) composed of only pentagon and hexagon faces (Schwerdtfeger *et al.* 2015), as is the *Marsupites* calyx. Consequently, the same graph (Fig. 1D) represents both the carbon fullerene C₃₀-D5h (with 30 vertices representing carbon atoms) and the calyx of *Marsupites* (with 30 vertices representing plate corners).

These observations allow us to explore counterfactual possibilities for calyx structure. 361 For example, we might ask how many pentagonal versus hexagonal plates Marsupites could 362 have, while maintaining the observed composition of only pentagons or hexagons. In fact, 363 there is only one possible composition. According to Euler's theorem there must be exactly 364 12 pentagons in any polyhedron composed of only pentagons or hexagons (Schwerdtfeger et 365 al. 2015). Twelve is, therefore, the number of pentagonal plates observed in the Marsupites 366 calyx (with 1 centrale, 5 infrabasals, 5 radials, closed by the 1 tegmen opening, each with 5 367 sides (Rasmussen 1978)). This results from Euler's polyhedral formula (|V| - |E| + |F| = 2). 368 From this we can also see that, for a polyhedron with 17 faces which are either pentagons or 369 370 hexagons, there must be exactly 5 hexagons (17 - 12 = 5). Correspondingly, 5 hexagonal basal plates are observed in *Marsupites*, and can also be seen in other dicyclic crinoids 371 including some specimens of Uintacrinus and the cladid Eoparisocrinus siluricus (e.g. Fig. 372 28 of (Ausich et al. 1999)). Given only pentagonal and hexagonal plates, other compositions, 373 for example a polyhedral calyx made up of 17 pentagonal plates, are simply not physically 374 possible. 375

We can then ask how many combinatorially different ways there are to make a 376 polyhedron composed of 12 pentagonal and 5 hexagonal faces. This corresponds to the 377 number of possible, non-isomorphic fullerene graphs with 30 vertices, which is just 3 378 (fullerenes C30-C2v 1, C30-C2v 2 and C30-D5h). Of these, the number with 5-fold rotational 379 symmetry is one (the D5h symmetry group, with the two fullerenes of group C2v having 380 twofold symmetry). This is the structure observed for the calyx of Marsupites and the 381 382 fullerene C30-D5h. While pentaradial symmetry is not universal among echinoderms, it is ancient (established by the early Cambrian (Smith & Zamora 2013)) and widely expressed, 383 384 for example in the frequent occurrence of 5 radials, 5 arms, 5 water vascular canals, 5 ambulacral food grooves, and 5 oral plates (Rasmussen 1978; Ausich et al. 1999), indicating 385 a strong constraint on echinoderm morphology throughout most of their evolutionary history. 386

The calyx of U. socialis was observed to contain plates with 4 to 8 sides (Figs. 2-3, 387 Table S7). Therefore, not all fixed calyx plates are pentagons or hexagons (as was the case 388 for Marsupites). The total number of pentagonal plates (e.g. 63 in Fig. 3) also greatly exceeds 389 the 12 allowed for fullerene dual graphs. Consequently, the dual graph for the U. socialis 390 calyx is more comparable to a fulleroid graph, a generalisation of a fullerene graph to allow 391 faces with any number of sides greater than 5 (Kardoš 2007; Schwerdtfeger et al. 2015). 392 However, we note that U. socialis calyces were observed to have occasional plates with four 393 sides (e.g. Figs. 2, S3) thereby deviating from an exact correspondence with fulleroid 394 395 structures. Without the restriction to only pentagonal or hexagonal faces (which was observed in *Marsupites* but not *Uintacrinus*), the number of possible calyx structures for *Uintacrinus* 396 corresponds to the number of possible polyhedral graphs, with a consequent increase in the 397 398 number of structural possibilities compared to fullerene graphs only (Table 1).

The introduction of vertices with greater than 6 sides in the calyx of *Uintacrinus*causes negative Gaussian curvature (the product of the minimal and maximal curvatures

around a point). Negative Gaussian curvature, which gives the calyx graph a wavy surface 401 with saddle-shaped areas (Figs. 2-3), reduces structural stability (Schwerdtfeger et al. 2015) 402 403 for example due to uneven distribution of strain which can cause local buckling (Liang & Mahadevan 2009). In line with this expectation from topological principles, the calyx of 404 Marsupites (which has a topologically stable fullerene structure) is often preserved three-405 dimensionally (e.g. Fig. 1) whereas for Uintacrinus (which shows more topologically 406 407 unstable structures) all articulated calyces held in the examined museum collections were crushed flat (e.g. Fig. 2). This difference in topological stability is particularly notable given 408 409 that the Cretaceous was a time when new crushing predators such as crabs were diversifying (Tsang et al. 2014). The calyx provides the external protection for all major organs of the 410 crinoid and its structural integrity is of vital importance. Why does the calyx of Uintacrinus 411 412 not then consist of a topologically more stable combination of only pentagonal and hexagonal 413 plates, analogous to large fullerene molecules? An answer emerges from the mathematical properties of polyhedra (as well as the echinoderm plate addition process). For some numbers 414 of vertices equal to or less than those observed in *Uintacrinus* (Table 1), not all possible 415 fullerenes have a 5-fold rotational symmetry axis (e.g. C30-C2v discussed above), additional 416 perpendicular mirror plane (D5h symmetry group), or even any symmetry axis at all (e.g. the 417 C1 symmetry group (Cromwell 1997)). Structures without D5 symmetry are incompatible 418 with plate addition that maintains the pentameral rotational axis dominant among 419 420 echinoderms. Structures without D5h symmetry will also lack the mirror symmetry seen 421 along the oral-aboral axis of the *Marsupites* calyx. Unlike *M. testudinarius* (in which all studied specimens had the same complement of calyx plates), U. socialis specimens appear to 422 423 have continued to add calyx plates throughout life. Therefore large numbers of plates, as observed in the calyx of Uintacrinus (Table 1), preclude the possession and continuous 424 maintenance of a biologically appropriate fullerene structure. 425

426 Evolutionary and Functional Implications

Based on these observations and graph theoretic analyses, we can evaluate the most 427 likely evolutionary pathways to uintacrinoid morphologies. This is conceptually equivalent to 428 reconstructing character states for the hypothetical ancestor of Uintacrinus and Marsupites, 429 within a phylogenetic framework involving consideration of state transition probabilities. 430 Given the evidence for continued plate addition throughout life, it is developmentally 431 432 plausible that Uintacrinus represents an extreme extension of an ontogenetic trajectory of calyx plate addition, with a large number of smaller, lighter plates conferring a highly 433 434 spherical, lightweight calyx. Such adaptations are compatible with both previously proposed functions, either as a benthic stabiliser on soft sediment (Milsom et al. 1994; Hess & Messing 435 2011; Gorzelak et al. 2017) or pelagic floatation chamber (Bather 1896; Springer 1901; 436 Seilacher & Hauff 2004). However, we show that in *Uintacrinus* (relative to *Marsupites*) 437 calyx expansion occurred by increased plate number despite a cost to structural stability. This 438 emphasises the importance of an exceptionally large and lightweight calyx to *Uintacrinus*, 439 potentially providing a point in favour of a free-living, pelagic habit for this genus (Bather 440 1896; Springer 1901; Seilacher & Hauff 2004). In addition, some calyx plates of Uintacrinus 441 show deep excavations and asymmetric thickening (Fig. S6), reducing their average bounding 442 density (weight/bounding volume, g/mm³, Table S3) and therefore the overall weight of the 443 calyx. 444

Relative to *Uintacrinus*, *Marsupites* represents a reduction in calyx plate number at maturity, indicating possible evolution by paedomorphic heterochrony (evolution in the timing of development, i.e. heterochrony, that produces juvenile-like characteristics in the adult (McNamara 1986)). Alongside this reduction in plate number, *Marsupites* also displays comparatively extended growth of individual plates, a possible example of peramorphic heterochrony (evolution that increases the relative extent of development in the adult

(McNamara 1986)). Overall, therefore, mixed heterochrony (Alba 2002) could have resulted 451 in a more robust calyx composed of fewer, larger plates, via modification of the timing of 452 453 developmental processes of plate addition and growth that were inherited from their most recent common ancestor and/or are shared more widely among crinoids and other 454 echinoderms (Comeau et al. 2017). Further to this, topological considerations suggest that the 455 fixed calyx of Marsupites is more structurally stable than that of Uintacrinus, which exhibits 456 457 negative Gaussian curvature. Moreover, the reduction in maximum calyx plate number in Marsupites relative to Uintacrinus leads to a radical decrease in the number of structural 458 459 possibilities and a differing number of stable options (Table 1). Specifically, a transition from the large number of calyx plates observed in Uintacrinus to the small number observed in 460 Marsupites results in a comparatively high probability that a topologically stable fullerene 461 structure with pentaradial symmetry is available e.g. 1 in 3 considering all possible fullerene 462 graphs (Table 1). In contrast, a transition in the opposite direction (from a small to large 463 number of calyx plates) can result in a zero probability of accessing a stable fullerene 464 structure with pentaradial symmetry (Table 1). Therefore, a simple reduction in calyx plate 465 number would have made the evolution of the more stable structural configuration of 466 Marsupites relatively likely on probabilistic grounds. 467

In general, biological evolution is capable of remarkable increases in complexity 468 (Szathmáry and Smith 1995), although decreases in complexity often occur when opposing 469 470 selection pressures are reduced (with evolutionary reductions in parasites and cave-dwelling fish providing famous examples (Porter & Crandall 2003)). Indeed, both Uintacrinus and 471 Marsupites possessed a calyx structure which is larger and, in Uintacrinus at least, 472 considerably more complex than their previously inferred phylogenetic sister-group (Milsom 473 et al. 1994), the comatulid crinoid genus Comatula (which also shows a highly reduced 474 stalk). This indicates, for example, that evolution of the shared uintacrinoid morphology 475

involved an increase in the number of adult cup plate circlets from the monocylic form in 476 adult comatulids (larvally dicyclic), to polymorphic dicyclic/monocyclic forms in adult 477 Uintacrinus and stably dicyclic form in Marsupites. However, with regard to the principal 478 difference between Uintacrinus and Marsupites calyx morphologies (the number of non-cup 479 plates incorporated into the calyx), we show that an increase in calyx plate number and, 480 consequently, structural complexity is accompanied by a decrease in the number of 481 482 topologically stable options (Table 1). Consequently, on mathematical and biophysical grounds, the probability of forward transition (from the absence to presence of fixed 483 484 interradial calyx plates) might be considered to be lower than the probability of backward transition (to the less complex and more stable calyx configuration, lacking fixed 485 interradials). This would then support a Uintacrinus-like ancestral morphology for the 486 uintacrinoids. This is consistent with an increase in the structural strength of the calyx in 487 Marsupites, and potentially a concomitant return to a more benthic life-habit (Milsom et al. 488 1994; Hess & Messing 2011; Gorzelak et al. 2017), in response to Late Cretaceous predation 489 pressures during the 'Mesozoic Marine Revolution'. The alternative, under equal transition 490 probabilities (though less consistent with a monocylic-polymorphic-dicyclic cup transition), 491 would suggest that the Marsupites morphology was ancestral, with Uintacrinus as a 492 secondary attempt at even more extreme calyx expansion, despite the associated costs to 493 structural stability. Ultimately, both of these unique morphological strategies were to 494 495 disappear with the extinction of both *Uintacrinus* and *Marsupites* by the late Campanian stage of the Late Cretaceous Period (Gale et al. 2008; Hess & Messing 2011). 496

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628	

629 FIGURE CAPTIONS

630

631 Figure 1. Calyx graphs for the Cretaceous crinoid *Marsupites testudinarius*. Aboral (A)

and lateral (**B**) views, from laser and photosurface scans of Sedgwick Museum of Earth

633 Sciences specimen number B24289, Upper Chalk, UK. Scale bar 1 cm (B). Letters indicate

634 plate names: C centrale, I infrabasal, B basal, R radial, T tegmen opening. Unlabelled graph

- 635 (C) and dual graph (D) of calyx structure. (C) 17 vertices (white-filled circles) represent the
- 636 16 calyx plates and tegmen. (**D**) 30 vertices (black circles) represent plate corners. The 45
- 637 connecting edges (lines) represent vertex adjacencies. The *Marsupites* calyx dual graph (**D**)

has the same structure as the carbon fullerene molecule C_{30} -D5h and all faces are pentagons

- 639 or hexagons. For visualisation, graph vertices (C-D) were positioned using a Yifan-Hu layout
- 640 in the program Gephi (Bastian *et al.* 2009).



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Figure 2. Calyx of Uintacrinus socialis. (A) Photograph of Sedgwick Museum of Earth 643 Sciences specimen number B11572, Niobrara Chalk, USA, with diagram of plates. Scale bar 644 1 cm. (B) Plate types: cup dark grey, fixed brachials (arms) white, interbrachials/fixed 645 pinnules mid grey, interradials/fixed pinnules light grey. (C) Number of sides of each plate: 4 646 white, 5 light grey, 6 mid grey, 7 dark grey, 8 black. 647



Figure 3. Calyx graph for juvenile *Uintacrinus socialis* (A). The calyx graph has a total of 650 197 vertices, representing plates, and 585 edges, representing plate adjacencies. (B) Vertex 651 degrees correspond to numbers of plate adjacencies and sides (with all vertices included). (A) 652 Graph visualisation, vertex positions generated as for Fig. 1. Tegmen vertex and its 40 653 654 incident edges removed for visual clarity (vertex colours show degree with all vertices included; Table S7). Plate adjacency pattern based on examination of specimens 1, (Springer 655 1901) plate VI fig. 4, 2, B11572 (Fig. 2) and 3 (Figs. S3-S4). Adjacency patterns inferred 656

from individual 2D compressed specimens (maximum 2 interambulacral regions visible)
combined and rotationally duplicated to close graph in 3D. Cup structure based on specimens
1-3 (extent of fixed calyx 1, aboral interbrachials and interradials 1-2, fixed pinnules 3).
Double size nodes (and colour version, red outlines) indicate plates incorporated into the
fixed calyx of *Marsupites* and cup of *Uintacrinus*.







677 relevant graph constraints.

Graph condition and corresponding biological constraintPo	ossible graphs general formula/ lgorithm)	Genus	Number of vertices (<i>V</i>)	Vertex identity	Number of possible graphs (for V vertices)
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Planar graphs	$\leq 30.061^{ V }$ (Bonichon <i>et al.</i>	Marsupites	17	Plates	$\leq 1.34 \times 10^{25}$
Arrangements of plates contacting only at lateral	2006)	Uintacrinus	197		$\leq 1.47 \times 10^{291}$
edges Polyhedral graphs	Algorithmic (Brinkmann & McKay 2007)	Marsupites	17		6.4×10^{12}
Polyhedra: 3D structures bounded by polygonal faces		Uintacrinus	197		Above computational limits: >> 1×10^{14} for $ V = 18$
Fullerene graphs	Algorithmic (Brinkmann & Dress 1997; Brinkmann & McKay 2007)	Marsupites	30	Plate corners	3
Polyhedra with only pentagon and hexagon faces		Uintacrinus	390 300		Above computational limits: > 933,265,811 for $ V = 300$
Pentameral fullerene graphs with mirror plane (D5h)	Algorithmic (Brinkmann & Dress 1997; Brinkmann & McKay 2007)	Marsupites	30		1
Fullerene structure with pentameral rotational symmetry and mirror plane		Uintacrinus	390 300		Above computational limits: 0 for $ V = 300$

Numbers of possible graphs refer to the number of different (non-isomorphic), unlabelled

679 graphs possible with a given number of vertices.

680

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686

687 DATA ARCHIVING STATEMENT

- 688 Additional supporting information is provided at the Dryad Digital Repository including
- 689 Tables S1-S7, Figs S1-S6 and Supplementary Computer Code:
- 690 429https://datadryad.org/review?doi=doi:10.5061/dryad.cc1v570.