

QMDPCA {QMDPCA}

Quadratic Moving Dynamic Principal Component Analysis for Non- Stationary Multivariate Time Series

## Description

This function reduce the dimension of non-stationary (and stationary) multivariate time series by performing eigenanalysis on the quadratic moving cross-covariance matrix of the extended data matrix up to some specified lag. Notice that the following libraries are needed to be installed before using the MDPCA function: library(roll); library(expm).

## Usage

```
QMDPCA(x,w,1)
```

## Arguments

**x**  
a T-by-m data matrix, where the rows are "T" time points, and the columns are "m" variables

**w**  
window width (i.e. window length)

**l**  
number of lagged series to be included in the calculation of QMDPCA

## Value

**xdata**  
returns the extended data matrix of x

**F**  
returns the quadratic moving cross-covariance matrix of the extended data matrix xdata

**Lambda**  
returns the eigenvalues of the matrix F

**U**  
returns the eigenvectors of the matrix F

## Note

step1: Build the extended data matrix (i.e. xdata) and obtain the eigenvalues and eigenvectors of its quadratic moving cross-covariance matrix. step2: Transfer extended data matrix (i.e. xdata) using eigenvectors (i.e. U) that correspond to the largest eigenvalues (i.e. Lambda). For example, if we find the first two eigenvalues to be large enough, then we can choose the corresponding two eigenvectors to obtain the final results (i.e. two QMDPCs). See the examples below.

## Author(s)

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## References

Alshammri, F. and Pan, J. (2020). Quadratic Moving dynamic principal component analysis for non-stationary multivariate time series. Manuscript submitted for publication.

## Examples

```
##This is Example 2 of Alshammri and Pan (2020).
##The data matrix X is a non-stationary time series with m=5 and T=1000.
m=5;T=1000
# Generate x_t
X=mat.or.vec(m,T)
a1=arima.sim(list(order=c(1,1,1),ar=0.55,ma=-0.8),n=T,sd=1)
X[1,]=a1[2:(T+1)]
a2=arima.sim(list(order=c(1,1,1),ar=-0.65,ma=0.45),n=T,sd=1)
X[2,]=a2[2:(T+1)]
a3=arima.sim(list(order=c(1,1,1),ar=0.45,ma=1.6),n=T,sd=1)
X[3,]=a3[2:(T+1)]
a4=arima.sim(list(order=c(1,1,1),ar=-0.8,ma=-0.9),n=T,sd=1)
X[4,]=a4[2:(T+1)]
a5=arima.sim(list(order=c(1,1,1),ar=0.85,ma=-2.2),n=T,sd=1)
X[5,]=a5[2:(T+1)]
X=t(X)
X=ts(X)
##Apply QMDPCA with 100 window length and one lagged series.
Analysis=QMDPCA(X,100,1)
U=Analysis$U
Lambda=Analysis$Lambda
F=Analysis$F
xdata=Analysis$xdata
##For example, if we find the first two eigenvalues to be large enough, then we can choose the corresponding two eigenvectors to obtain the final results (i.e. two QMDPCs)
sum(Lambda[1:2])/sum(Lambda) #percentage of variability explained by the first 2 QMDPCs
Transform=xdata%*%U[,1:2]
##Final results (i.e. two QMDPCs)
Transform=ts(Transform)
```

[Package *QMDPCA* version 0.1.0 [Index](#)]