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A Compact and Low-Profile Tunable Loop Antenna Integrated With Inductors

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Abstract—We present a frequency-tunable, compact loop antenna which consists of a transmission line on a ground plane, two shorting posts, and two inductors which are serially connected between the posts and the edge of the transmission line. By properly choosing the inductance of the inductors, the operating frequency of the antenna can be controlled without seriously sacrificing fractional bandwidth. To demonstrate the operating mechanism, the equivalent circuit of this antenna is included. The characteristics of the antenna with various inductors integrated are also investigated. Fabricated antennas show that the operating frequency can be shifted from 2.07 GHz to 1.2 GHz using off-the-shelf inductors. Using two 33-nH inductors achieves an antenna with an electrical size as small as $0.118\lambda \times 0.013\lambda \times 0.047\lambda$. The validity of this antenna is demonstrated by experimental results.

Index Terms—Compact antenna, frequency tunable antenna, inductor, loop antenna.

I. INTRODUCTION

S IMPLE, small antennas with low profile and light weight are increasingly necessary as wireless communication devices become compact and the demand for low-frequency applications increases. Traditional techniques for miniaturizing antennas include lengthening the current path using shorting pins [1], slots [2], and meander lines [3], or lengthening the electrical dimension by employing a high dielectric material [4]. However, these techniques cause inescapable problems, such as narrowing bandwidth, increasing cross polarization level, and decreasing radiation efficiency. A circular-disk-loaded monopole antenna [5], which uses electromagnetic coupling and a folded conical helical antenna [6], has been reported to increase the bandwidth with compact size. However, these structures are complicated to fabricate.

In this letter, we propose a simple, lightweight, compact frequency-tunable loop antenna. This antenna structure consists of two rectangular substrates, two posts, and two inductors (Fig. 1). By altering the inductor values, the operating frequency can be

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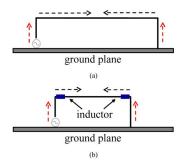


Fig. 1. Configuration of a loop antenna mounted on a ground plane and its current distribution. (a) Without an inductor. (b) With inductors.

shifted and the input impedance can be easily matched without degrading the fractional input impedance bandwidth. In Section II, we discuss an idea for miniaturizing a loop antenna by integrating inductors and introduce the configuration of the proposed antenna. The equivalent circuit model of the antenna is presented in Section III. In Section IV, we investigate the characteristics of the antenna with varying inductor pairs. In Section V, we present the measured results to validate the simulated results, and we conclude this paper in Section VI.

II. CONSIDERATION OF MINIATURIZING LOOP ANTENNA AND CONFIGURATION OF PROPOSED ANTENNA

Fig. 1(a) shows a loop antenna mounted on a ground plane. The directions of current distributions on two vertical wires are the same, so both can contribute radiation. The current flows on the horizontal wire in opposite directions; these currents keep a resonance condition, but do not contribute to the radiation. Therefore, if we put inductors on the horizontal wire in order to give a phase delay with a small wire length, we can reduce the horizontal wire length. The induced phase delay from the integrated inductors keeps the resonance condition so that a current distribution of the conventional loop antenna is expected. We present this concept of a miniaturized antenna in Fig. 1(b). Note that the currents are highly concentrated on the edge of the upper horizontal wire to generate a large phase delay for a given inductance.

To implement this miniaturization idea, we have designed a 3-D loop antenna with two inductors as shown in Fig. 2. This antenna consists of an upper layer and a bottom layer, which are rectangular substrates of permittivity ε_r . The distance between layers is h. The bottom layer acts as a ground plane of length gl (= $line_L + 10$ mm) and width gw (= $line_w + 15$ mm). A transmission line with length $line_L$ and width $line_w$ is placed

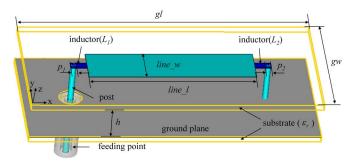


Fig. 2. Configurations of the proposed antenna.

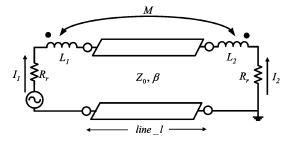


Fig. 3. Equivalent circuit model of the proposed antenna.

on the upper layer. At the end of the transmission line, two posts connect the transmission line through the ground plane. The diameters of the posts are p_1 and p_2 . Two inductors (L_1, L_2) are integrated between the posts and the transmission line.

III. EQUIVALENT CIRCUIT

The derived equivalent circuit of the proposed antenna (Fig. 3) illustrates the operating mechanism of the antenna. The straight transmission line of length *line_l* and width *line_w* is simply modeled as a transmission line, with length *line_l* and width *line_w* with characteristic impedance Z_0 and propagation constant β . Since the two posts are the main radiation elements, the posts are modeled as a radiation resistance R_r and R_r makes the response of the circuit more broadband. Although several mutual inductive couplings occur between inductors on the equivalent circuit, only the mutual inductive coupling (M) between L_1 and L_2 is considered for simplification.

To verify the equivalent circuit of the antenna, the results from a full-wave simulation and those from circuit simulation are compared in Table I. For full-wave analysis, CST's MWS full-wave simulator was used. For circuit analysis, Agilent's ADS was used. The parameters are set as h = 3 mm, $line_l = 20 \text{ mm}$, $line_w = 1 \text{ mm}$, $p_1 = 0.3 \text{ mm}$, $p_2 = 0.5 \text{ mm}$, and $\varepsilon_r = 1$. Resonant frequency (f_0) , input impedance at resonant frequency (Z_r) , and input impedance bandwidth (BW) are summarized in Table I for several different values of L_1 and L_2 .

The case of $L_1 = 0$ and $L_2 = 0$ (Table I) corresponds to the structure without the lumped inductors. The R_r of the equivalent circuit can be determined by comparing the input impedance of the full-wave results when $L_1 = L_2 = 0$. The input impedance of the full-wave analysis in this case is 6 Ω (Table I). Therefore, due to the symmetry of the structure, we set each R_r of the equivalent circuit to 3 Ω , and used this value of R_r for different values of L_1 and L_2 . Note that we only changed the physically

TABLE I

Comparison of the Results From Full-Wave Analysis and the Results From Circuit Analysis L_1 , L_2 : Inductance of Integrated Inductor (NH), M: Mutual Coupling (NH), f_0 : Resonance Frequency (GHz), Z_r : Input Impedance at Resonance Frequency (Ω), BW: -10 dB Input Impedance Bandwidth (MHz). N/A: Not Available

		Full-wave analysis				Circu	it analysi	s
L_{I}	L_2	f_0	Z_r	BW	M	f_0	Z_r	BW
0	0	6.13	6.0	n/a	0	7.50	6.0	n/a
1	1	5.36	5.8	n/a	1	5.72	6.0	n/a
10	1	4.07	17.0	n/a	2	4.00	20.0	n/a
20	1	3.62	52.6	36.5	3	3.78	56.8	38
1	10	3.95	3.90	n/a	2	4.20	3.6	n/a
1	20	3.52	3.45	n/a	3	3.79	3.2	n/a

TABLE II
SUMMARY OF THE RESULTS FROM FULL-WAVE ANALYSIS WITH
DIFFERENT PAIRS OF L_1 AND L_2 . $h = 10 \text{ mm}$, $line_l = 20 \text{ mm}$,
line $w = 1 \text{ mm} n_{e} = 0.3 \text{ mm} n_{e} = 0.5 \text{ mmAND} \varepsilon = 1$

L_{I}	L_2	f_0	Z_r	BW (%)	$line_l \times line_w \times h$
0	0	4.36	42.66	8.20	$0.291~\lambda \times 0.014~\lambda \times 0.145~\lambda$
14	10	2.77	54.57	3.33	$0.185 \ \lambda \times 0.009 \ \lambda \times 0.092 \ \lambda$
30	30	1.93	51.14	2.42	$0.129~\lambda \times 0.006~\lambda \times 0.064~\lambda$
65	100	1.23	48.35	2.09	$0.082~\lambda \times 0.004~\lambda \times 0.041~\lambda$
110	220	0.91	54.30	2.16	$0.061\;\lambda\times0.003\;\lambda\times0.030\;\lambda$
190	400	0.74	54.60	2.20	$0.049 \ \lambda \times 0.002 \ \lambda \times 0.025 \ \lambda$

possible values of M and selected the M value to match the results from the full-wave analysis to those from the circuit analysis.

Resonant frequencies (f_0) , input impedance at $f_0(Z_r)$, and input impedance bandwidths (BWs) (BW, if it is available) from the circuit analysis agree well with those from full-wave analysis for different values of L_1 and L_2 except when $L_1 = L_2 =$ 0. As the value of L_1 increases from 1 nH to 20 nH, f_0 decreases and Z_r increases. On the other hand, as the value of L_2 increases, f_0 and Z_r decrease simultaneously. Hence, Z_r can be easily matched to 50 Ω , and the antenna size can be reduced by properly choosing the values of L_1 and L_2 . Note that when L_1 is 20 nH and L_2 is 1 nH, the input impedance is matched to 50 Ω and the input impedance BW is 36.45 MHz.

IV. FULL-WAVE ANALYSIS

To demonstrate the circuit characteristics in the previous section, we designed several antennas for different L_1 and L_2 combinations which guarantee good input impedance matching. We summarize f_0, Z_r , BW, and the electric size in Table II. The parameters are set as h = 10 mm, line I = 20 mm, $line_w = 1$ mm, $p_1 = 0.3$ mm, $p_2 = 0.5$ mm, and $\varepsilon_r = 1$.

When $L_1 = L_2 = 0$, f_0 is 4.36 GHz and BW is 8.2%. When $L_1 = 14$ nH and $L_2 = 10$ nH, f_0 is 2.77 GHz and BW is 3.33%, which is lower than when $L_1 = L_2 = 0$. As the values of L_1 and L_2 increase, f_0 decreases with good impedance matching. This means that the operating frequency of the proposed antenna can be controlled by L_1 and L_2 without changing antenna dimensions. Note that even though f_0 decreases (the antenna is miniaturized), the fractional bandwidth is kept almost constant from

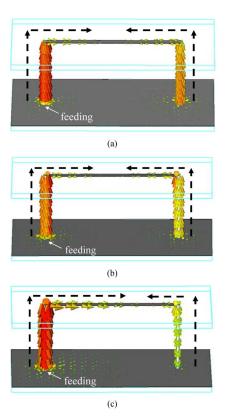


Fig. 4. Surface current distribution for different inductor pairs. (a) $L_1 = L_2 = 0$ nH at 4.36 GHz. (b) $L_1 = L_2 = 30$ nH at 1.93 GHz. (c) $L_1 = 110$ nH, $L_2 = 220$ nH at 0.91 GHz.

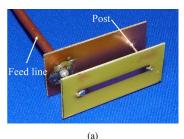
the third to the sixth row in Table II. This characteristic is very desirable. As the operating frequency decreases by integrating high inductance inductors, a distributed shunt capacitor between the upper horizontal wire and the bottom ground plane is also increased in the fixed physical dimension. The increased capacitance compensates for the increased inductance of the lumped inductors and for the stored magnetic energy. Therefore, the bandwidth of this antenna can be kept constant. This characteristic is a key advantage of the proposed antenna.

To verify the current directions of Fig. 1, we present simulated current distributions at f_0 for different inductors pairs in Fig. 4. The current distributions are almost kept unchanged, although higher inductance inductors are integrated. A current null position on the upper line slightly shifts in Fig. 4(c), but the amount of the shift is not much compared to the decrease in operating frequency.

V. FABRICATION AND MEASUREMENT RESULTS

To validate the simulation results, we fabricated several proposed antennas with different combinations of L_1 and L_2 . Fig. 5 shows the fabricated antennas with and without inductors. The design parameters are *line_l* = 28 mm, *line_w* = 3 mm, h =11.2 mm, and $p_1 = p_2 = 0.9$ mm. We use an FR4 substrate of 0.8-mm thickness, and LQW18A series Murata coil inductors.

Fig. 6 shows the measured and simulated return losses of the proposed antennas with three different inductor pairs ($L_1 = 0$ nH, $L_2 = 0$ nH), ($L_1 = 10$ nH, $L_2 = 5.6$ nH), and ($L_1 = 33$ nH), $L_2 = 33$ nH). This figure demonstrates that the proposed antenna's operating frequency can be controlled using



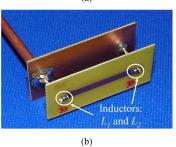


Fig. 5. Fabricated proposed antennas. (a) Without inductor. (b) With inductor.

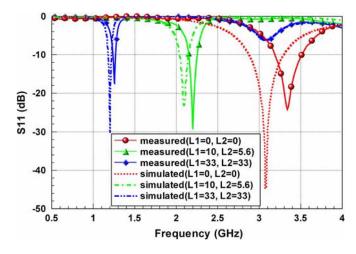


Fig. 6. Measured return loss with different inductor pairs.

simple passive devices. As the inductor pairs increase from (10 nH, 5.6 nH) to (33 nH, 33 nH), the measured center operating frequencies decrease from 2.19 to 1.26 GHz, which is very similar to the changes in the simulated ones (i.e., 2.07 and 1.2 GHz). When $L_1 = 10$ nH and $L_2 = 5.6$ nH, the measured input impedance bandwidth is 102 MHz (4.7%) and the simulated bandwidth is 101 MHz (4.9%). When $L_1 = 33$ nH and $L_2 =$ 33 nH, the measured impedance bandwidth is 28 MHz (2.2%) and the simulated bandwidth is 33 MHz (2.8%). The minor differences between the measured and simulated results might be due to fabrication error since the fabrications are not optimized. Note that the electrical dimension $line_l \times line_w \times h$ of the fabricated antenna with $L_1 = 33$ nH and $L_2 = 33$ nH, is only $0.118\lambda \times 0.013\lambda \times 0.047\lambda$. If a combination of higher inductance inductors is used, the size can be further decreased without degrading the fractional bandwidth.

The radiation patterns of the fabricated antenna with $L_1 = 10$ nH and $L_2 = 5.6$ nH at 2.21 GHz were measured using 5° resolution in an anechoic chamber, and the measured and simulated patterns at the y-z plane are presented in Fig. 7. The co-pol

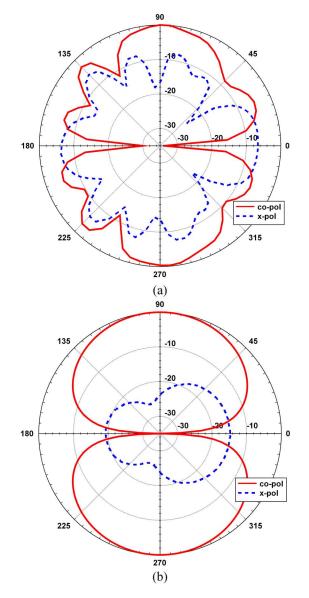


Fig. 7. Radiation patterns at 2.21 MHz (y-z plane). (a) Measured. (b) Simulated. ($L_1 = 10$ nH, $L_2 = 5.6$ nH, co-pol: E_{θ} , x-pol: E_{Φ}).

and the x-pol in the figure are E_{θ} and E_{Φ} , respectively. Nulls in the co-pol occur at 0° and 180°. This radiation characteristic occurs because the dominant radiation elements are two vertical posts. The component of E_{Φ} is measured as relatively large, because the small ground plane causes radiation on the coaxial feeding line of the fabricated antenna. The measured radiation efficiency is 33.3%.

VI. CONCLUSION

In this letter, we have proposed a new technique for miniaturization loop antennas by integrating two inductors. The results show that the resonant frequency decreases and the input resistance increases as L_1 is increased, but that resonant frequency and input resistance decrease as L_2 is increased. These characteristics allow the antenna to have the tunable operating frequency and make the antenna electromagnetically small. Moreover, the key advantage of this antenna is its constant fraction input impedance bandwidth across its entire tunable frequency range.

The measured results are compared to the simulations, and show good agreement with the simulated results. One of the fabricated antennas only has a $0.118\lambda \times 0.013\lambda \times 0.047\lambda$ electrical size at 1.2 GHz.

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