



1 Article

2 Impact of pile punching on adjacent piles: Insights 3 from a 3D coupled SPH-FEM analysis

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13 **Abstract:** Pile punching (or driving) affects the surrounding area where piles and the adjacent
14 piles can be displaced out of their original positions due to horizontal loads, leading to hazardous
15 outcomes. This paper presents a 3D coupled Smoothed Particle Hydrodynamics and Finite
16 Element Method (SPH-FEM) model, which was established to investigate pile punching and its
17 impact on adjacent piles subjected to lateral loads. This approach handles the large distortions by
18 avoiding mesh tangling and remeshing, contributing greatly high computational efficiency. The
19 SPH-FEM model was validated against field measurements. Results of this study indicated that
20 the soil type in which piles were embedded affected the interaction between piles during the pile
21 punching. A comprehensive parametric study was carried out to evaluate the impact of soil
22 properties on the displacement of piles due to the punching of an adjacent pile. It was found that
23 the interaction between piles was comparatively weak when the piles were driven in stiff clays;
24 while the pile-soil interactions were much more significant in sandy soils and soft clays.

25 **Keywords:** Pile punching; field measurement; smoothed particle hydrodynamics; finite element
26 method; lateral displacement
27

28 1. Introduction

29 Piles are commonly used as foundations for many major structures in civil engineering to
30 transfer the heavy loads, for which shallow foundations may not be economical and feasible. In
31 engineering practice, piles are often designed only for carrying vertical loading, as typically the
32 vertical loads are significantly larger than the horizontal loads such as wind loading. However,

34 activities [1, 2]. The lateral soil movement generated by the installation of a pile close to existing piles
35 will induce additional deflection and bending moment to the adjacent existing pile. Thus, the lateral
36 response of pile foundation is also essential in the designing of structures where lateral dynamic
37 loads exist. Unlike the axial load capacity of a pile, the determination of its lateral load capacity is
38 much more complicated because the soil-pile interaction affects the pile deflection [3, 4].

39 When the punching hammer strikes a pile head, a stress wave is generated within the pile that
40 travels along the pile, during which a part of the energy is transmitted into the soil at the soil-pile
41 interface [5-8]. Thus, the pile punching affects the surrounding area where piles are installed, and
42 the adjacent piles can be displaced from their original positions. Additionally, the vibrations
43 induced by pile punching can damage structures and cause discomfort to the people in the
44 proximity of pile punching. Thus, the prediction of the ground vibration from pile punching and

45 study of its impact on adjacent piles are crucial to prevent the possible damages on nearby
46 environment and structures.

47 Previous studies have focused on the driving efficiency of piles, and only few investigations of
48 vibrations due to pile punching and their effects on the nearby structures are available [9-13].
49 Nowadays, Finite Element Method (FEM) analysis has become a promising approach to study the
50 problems in soil-pile interaction. It is known that the soil in the vicinity of the pile can be subjected
51 to large deformations (as a result of pile penetration), the FEM analysis therefore should have a
52 capability of considering large deformations [14]. Thus, researchers have used different techniques
53 to simulate the pile driving such as lumped parameter models, Material Point Method (MPM), and
54 continuum FEM models using Arbitrary Lagrangian-Eulerian (ALE) method. However, in most
55 previous FEM analysis, the installation of piles has not been explicitly modeled and 2-D
56 axisymmetric models are often used [8, 15-19].

57 Apparently, those 2D analyses cannot incorporate the radial and three-dimensional
58 components of interaction. Thus, they are not well suitable for understanding the pile-soil-pile
59 interaction in a real environment. As such, to unveil the real interaction mechanism a 3D FEM
60 analysis is needed. However, these 3D models have rarely been available in literature since the 3D
61 FEM analysis requires a considerable computational effort for generating input and interpretation
62 of results. Also, the impact mechanism underlying the dynamic interaction between adjacent piles
63 in the process of pile punching is still not clear, although some investigations are available [20, 21].

64 Another limitation of FEM in the application of large deformation problems is that the use of
65 conventional Lagrangian meshes will result in mesh tangling, leading to severe numerical
66 instabilities. Smoothed Particle Hydrodynamics (SPH) method has a strong ability to solve dynamic
67 problems involving large deformation. On the other hand, it is not as good as the FEM in terms of
68 computational time and boundary conditions. In this regard, coupled SPH-FEM method can be
69 effectively used of two kinds of algorithms for the simulation of large deformation problems by
70 eliminating the limitations in those two algorithms. *Today vast number of FE codes are available
71 that are capable of analyzing challenging engineering problems. The selection of an appropriate FE
72 code is dependent on the type of problem and computational cost. LS-DYNA is an explicit code
73 developed for the dynamic analysis of nonlinear problems that requires small time steps. LS-DYNA
74 was found to be the most preferred choice for this kind of analysis due to the capability of solving
75 the problems involving large deformation, easy application of SPH method and the vast variety of
76 material models available for concrete and soil.*

77 The objective of this study is to develop an efficient 3D coupled numerical model to probe the
78 impact of pile punching on adjacent piles. The 3D coupled SPH-FEM model was generated based
79 on the particle approximation approach and calibrated against field experiments. The established
80 SPH-FEM model was then used to investigate the mechanism underlying the pile interactions due
81 to the impact of pile punching.

82 **2. Establishment of the 3D SPH-FEM model for pile punching**

83 SPH is a mesh-free Lagrangian method which employs a finite number of particles that carry
84 individual mass to represent the material and form the computational domain [22]. Because of its
85 ability to handle large distortions by avoiding mesh tangling and remeshing, the SPH method can
86 be efficiently used for the simulation of dynamic problems involving large deformation [23].
87 Although SPH has great advantages in simulating many problems in engineering and science, SPH
88 is much expensive in terms of computation time (especially for 3D model) due to large number of
89 small particles would be required and the time step would become very small. Thus, coupling the
90 SPH and Lagrangian FEM mesh is a potentially good solution to overcome the element distortion,
91 and as well as to maintain good computational efficiency. In this study, SPH particles are used to
92 model the soil domain at near field, while the conventional FEM is used to model the intermediate
93 and far-field soil medium and the piles.

94 In the SPH formulation, two basic steps are involved, namely kernel approximation and
95 particle approximation. The first step is kernel approximation, where a spatial distance between

96 particles is covered by a smooth length over which their properties are smoothed by a smoothing
 97 kernel function. The integral representation of smoothing kernel function and its derivative are
 98 described as [24]:

$$f(x) = \int_{\Omega} f(x')W(x-x',h)dx' \quad (1)$$

$$\nabla f(x) = - \int_{\Omega} f(x')\nabla W(x-x',h)dx' \quad (2)$$

99 where W is the smoothing kernel function, h is the smoothing length, Ω is the problem domain
 100 and f is a field function.

101 The commercial software LS-DYNA was used for simulations throughout this study. It
 102 employs following cubic B-spline smoothing function, and it has been proven to be accurate and
 103 efficient [24].

$$W(x,h) = \frac{c}{h^n} \begin{cases} 1 - \frac{3}{2}x^2 + \frac{3}{4}x^3 & \rightarrow x \leq 1 \\ \frac{1}{4}(2-x)^3 & \rightarrow 1 < x \leq 2 \\ 0 & \rightarrow x > 2 \end{cases} \quad (3)$$

104 Smoothing length, h , is an important parameter in the SPH method because it determines the
 105 influence area of the smoothing function, W , for each particle [24]. Since the mass of particle in SPH
 106 is assumed to be constant, the smoothing length associated with particles should vary accordingly
 107 with density. Although using variable smoothing length increase the accuracy of the results, it will
 108 increase the computational time. In this study, the smoothing length coefficient was set to be 1.05.

109 In the second step that is particle approximation step, the computational domain is discretized
 110 with a set of initial distribution of particles that carry an individual mass. The field variables on a
 111 particle are estimated by a summation of the values over the nearest neighbor particles [24].

112 In the study, the particle approximation was used to generate the SPH-FEM model. The
 113 governing equations for SPH particles can be written as:

$$\frac{d\rho_i}{dt} = \rho_i \sum_{j=1}^N \frac{m_j}{\rho_j} (v_i^\alpha - v_j^\alpha) \frac{\partial W_{ij}}{\partial X_i^\alpha} \quad (4)$$

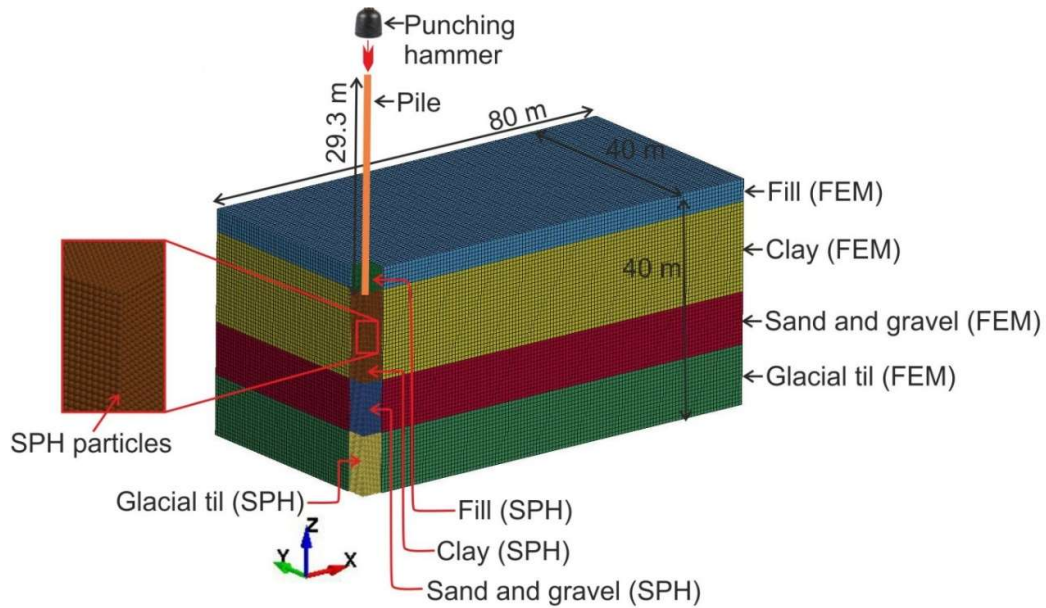
$$\frac{dv_i^\alpha}{dt} = \sum_{j=1}^N m_j \left(\frac{\sigma_i^{\alpha\beta}}{\rho_j^2} + \frac{\sigma_j^{\alpha\beta}}{\rho_j^2} + \Pi_{ij} \right) \frac{\partial W_{ij}}{\partial X_i^\beta} \quad (5)$$

114 where m is the mass, ρ is the density and v is the velocity. $\sigma^{\alpha\beta}$ is the total stress tensor, X is the
 115 spatial coordinate of the particle, t is the time, W is the smoothing kernel function and Π is the
 116 Monaghan artificial viscosity.

117 The study first simulated and validated the experiment conducted by Nilson [25]. Nilson [25]
 118 recorded series of ground vibration measurements using the vibration sensors arranged at 10, 20
 119 and 40 m distance from a pile drive. A reinforced concrete pile with a square cross-section of 270
 120 mm x 270 mm and the length of 29.3 m were used in his experiment. The soil profile in the test area
 121 was 3 m of surface fill deposited on 12 m thick layer of medium stiff clay and a layer of 7 m thick
 122 sand on glacial till. Fig. 1 shows the generated 3D SPH-FEM model for pile punching which consists
 123 of pile and soils. Symmetric modelling capabilities play an important role in numerical analysis to
 124 save the computational effort [26, 27]. However, in certain cases, the symmetric boundary
 125 conditions cannot be applied due to presence of nonsymmetries in loading, material and boundary
 126 conditions [28]. Considering the symmetries of the boundary conditions and applied loadings, only
 127 a quarter of the model was developed to reduce the computational cost in this study.

128 The domain of the soil was modelled with four different layers of soil to simulate the
 129 geotechnical soil profile at the test site and then was set to be 80 m long, 40 m wide and 40 m high.
 130 SPH particles were used to model the soils where large deformation is expected to occur near the
 131 driven pile. A preliminary analysis was carried out to determine the best size of the soil domain to
 132 model with SPH particles. It was found that the numerical instabilities are occurred due to large
 133 element distortion when the domain is too small. In contrast, larger domain for SPH soil domain

134 led to high computational cost. Higher accuracy of the analysis is ensured by using 0.5 m x 0.5 m
 135 size of the SPH soil domain around the pile. Eight-node solid elements with reduced integration
 136 and hourglass control were used to model the pile and soils in the far-field.
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138

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Figure 1. A quarter symmetrical 3D SPH-FEM model for pile punching.

140 The soil close to the driven pile was modeled with SPH particles and the rest of the model was
 141 modeled with the conventional Lagrangian meshes. With an equal distance of 10 mm between SPH
 142 particles at all axes, 270,000 particles were created to model the soils in the near field. The driven
 143 pile was modeled with solid elements with 25 mm edge length. The rest of the model was created
 144 using solid elements with the 250 mm mesh. The developed model has 437,090 solid elements.
 145 Nodes in the symmetry boundaries were fixed against translational displacements normal to the
 146 symmetry plane. The bottom of the mesh was modeled as fixed in all directions to prevent the
 147 boundary from moving in any direction. Non-reflecting boundaries are applied to the other
 148 surfaces, except the top surface which has the free boundary condition. A symmetry boundary was
 149 applied to those SPH particles at the symmetry planes using
 150 *BOUNDARY_SPH_SYMMETRY_PLANE.

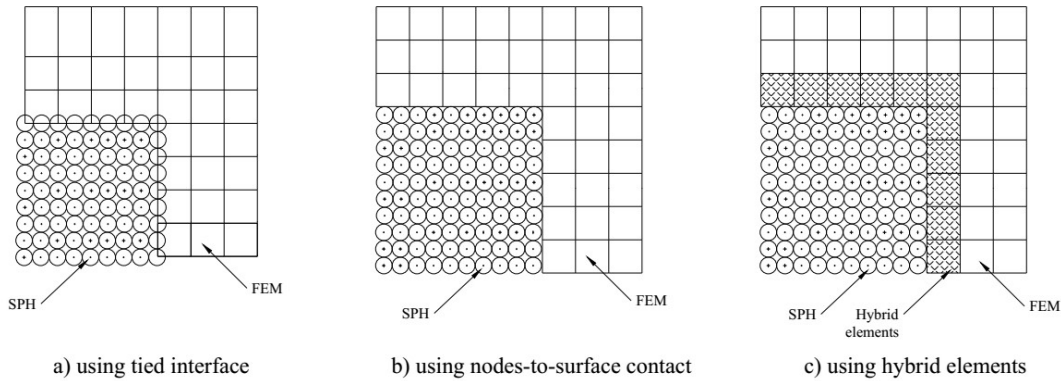
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152 Four different soil layers have been simulated in this SPH-FEM model. Thus, the model
 153 consisted of four different SPH parts with different soil densities. There exist various methods that
 154 can handle the interactions between different SPH parts. The standard SPH interpolation functions
 155 can be used to handle the interaction between SPH parts. No contact definitions are needed and
 156 multiple SPH parts are treated as one part in the standard SPH interpolation. However, when the
 157 densities and masses of neighboring particles vary largely within the smoothing length, the
 158 standard SPH interpolation gives false values on the smoothing quantities of a particle. Muller et al.
 159 [29] showed that when the density ratio larger than 10, the interaction between SPH parts cannot be
 160 realistically simulated using the standard SPH interpolation. The instabilities due to large density
 161 ratios across the interfaces can be avoided by introducing a penalty based node to node contact
 162 algorithm for the interaction between two SPH parts. However, when the two SPH parts have
 163 similar density and material properties, the standard SPH interpolation method has better accuracy
 164 around the interfaces [30]. Since the soil densities do not vary significantly, the standard SPH
 165 interpolation interaction was used in the present study. To activate this, CONT parameter in
 166 *CONTROL_SPH was set to 0, and no contacts were defined between those SPH parts.

167

Three different methods have been involved in the coupling of SPH particles and conventional
 FEM meshes [26, 31]. The first method is SPH particles tied to the corresponding surfaces of FEM

168 meshes as shown in Fig. 2(a). If the SPH particles are not tied to the FEM mesh as shown in Fig.
 169 2(b), the interaction between them is achieved by the penalty based nodes to surface contact. The
 170 third method uses hybrid elements as transit layers between SPH particles and FEM meshes as
 171 shown in Fig. 2(c). The tied interfaces between SPH particles and FEM elements (Fig. 2a) were
 172 employed in this study to couple the soil model with SPH particles and FEM elements.



174 **Figure 2.** Coupling of SPH and FEM meshes.

175 The interaction between the SPH and FEM elements of the driven pile was defined using
 176 penalty based algorithms, *CONTACT_AUTOMATIC_NODES_TO_SURFACE in LS-DYNA. The
 177 slave part was defined with SPH particles and the master part was defined with finite elements (i.e.
 178 the driven pile). In this method, when a slave node is in contact with the master surface, a restoring
 179 force is applied to prevent the penetration, which is directly proportional to the penetration into the
 180 solid element. Thus, when solid elements interacted with SPH particles, the SPH-FEM coupling
 181 enabled the stress transfer at the interface without penetration of SPH particles. The restoring force,
 182 F , is defined by in Eq. (6).

183
$$F = k \cdot d \cdot n \quad (6)$$

184 where k is the linear spring constant, d is the penetration distance and n is the surface normal
 185 vector.

186 The impact of the hammer was applied on the pile head as an impulse using a rectangle
 187 function for force versus time. The applied load on the top surface of the pile was derived from the
 188 mass of the hammer, m , and the height of the fall, h , as given in Eq. (7).

189
$$I = \sqrt{2gh} \cdot m \cdot \eta \quad (7)$$

190 where I is the impact momentum, g is the gravitational acceleration and η is the effective ratio
 191 due to the damping of the cushion. In this study, η was taken as 0.9 for the calculations.

192 In this study, *MAT_CONCRETE_DAMAGE_REL3 (MAT_72R3) material model was used to
 193 model the concrete pile. The advantage of this model is that the unconfined compressive strength
 194 and density are the two parameters that are required in the automatic parameter generation to
 195 simulate the concrete behavior [4]. The concrete density, compressive strength of concrete, and
 196 Poisson's ratio were considered as 2400 kg/m³, 25 MPa, and 0.3, respectively. Each soil layer was
 197 modelled with *MAT_MOHR_COULOMB (MAT_173) material model and the material parameters
 198 for each soil layer are listed in Table 1.

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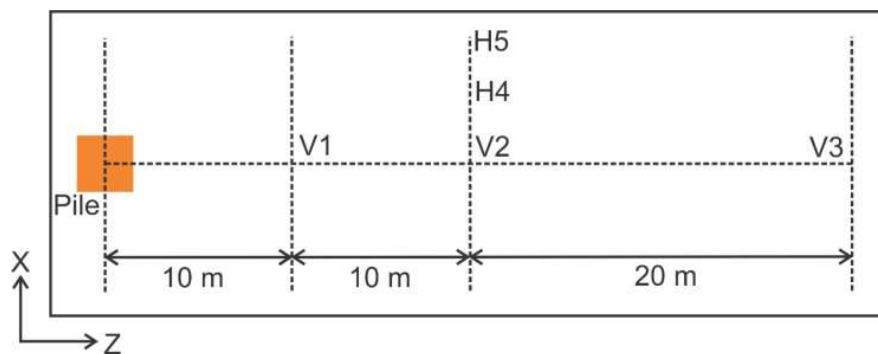
Table 1. Material parameters for each soil layer.

Soil type	Layer thickness (m)	Density (kg/m ³)	Elastic shear modulus (MPa)	Poisson's ratio	Friction angle (°)	Cohesion (kPa)
Fill (slag and sand)	3	1900	76	0.3	35	14
Clay	12	1600	36	0.495	20	30
Sand and gravel	7	1800	112.5	0.3	40	10
Glacial till	18	1900	304	0.3	40	10

203 3. Model calibration

204 In the calibration process, the SPH-FEM model was run in two steps. The first step was stress
 205 initialization to induce steady initial in-situ gravity stresses in the soils using the
 206 *CONTROL_DYNAMIC_RELAXATION option in LS-DYNA. The impact load on the pile was then
 207 applied as the second phase after the dynamic relaxation phase. The soil-pile interactions and
 208 ground vibrations were analysed in the second phase.

209 Calibration of the coupled SPH-FEM modelling technique was carried out against field tests [7,
 210 25]. Massarsch and Fellenius [7] presented the results of punching one test pile obtained from a
 211 series of field test carried out by Nilson [25] in Sweden. The test pile was a reinforced concrete pile
 212 with a square cross-section of 270 mm x 270 mm. The bulk density and the impedance of the pile
 213 were 2400 kg/m³ and 714 kNs/m, respectively. The total length of the pile was 29.3 m. The pile
 214 punching involved a 4000 kg weight hammer falling 0.4 m per blow. Ground vibrations were
 215 measured at a horizontal distance of 10, 20 and 40 m from the driven pile as shown in Fig. 3. In the
 216 field test by Nilson [25], the geophones were used to measure the particle velocities vertically (V1,
 217 V2 and V3) and horizontally in the radial (H4) and transverse (H5) directions of wave propagation.
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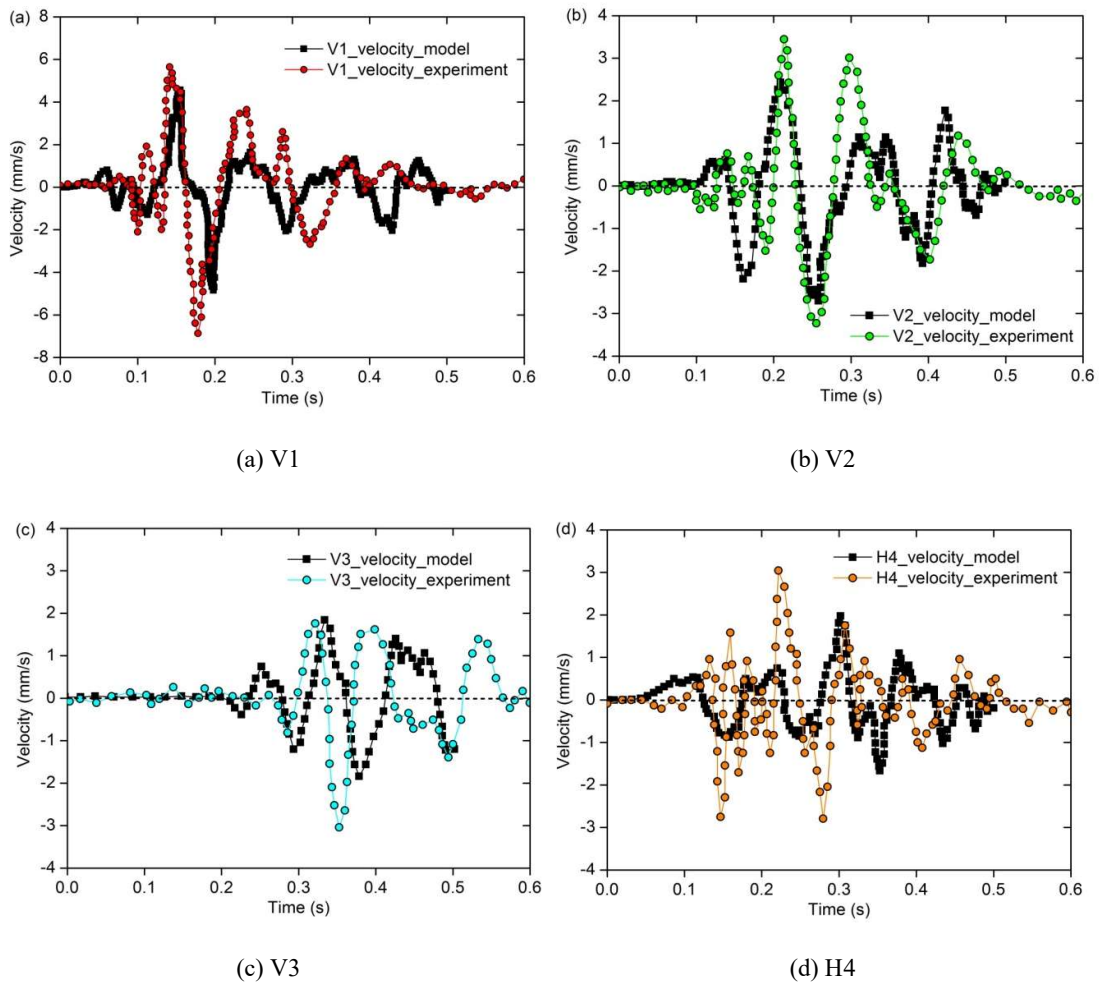


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220 **Figure 3.** The arrangement of geophones during punching of the test pile [7].

221 Three monitoring points on the soil surface at 10, 20 and 40 m distances from the driven pile
 222 were defined using the *DATABASE_HISTORY_NODE option in LS-DYNA. LS-DYNA offers
 223 options to extract the all nodal time history data from the nodal output. Velocity-time histories of
 224 the ground vibration at these monitoring points were extracted to compare with the experimental
 225 results. Figs. 4 shows a comparison of the ground vibration results from the 3D SPH-FEM analysis
 226 and field measurements (at the pile depth of 3 m). The plots show broad agreements of the results
 227 (in terms of waveforms at the monitoring points) from the calibrated SPH-FEM model and the
 228 experiment. A common observation is that the numerical results for peak velocities at the

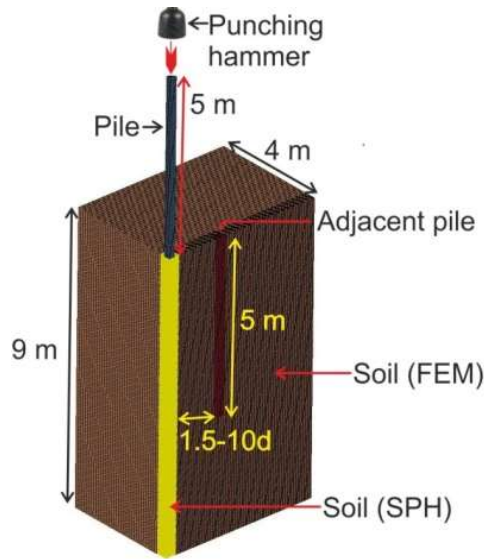
229 monitoring points are slightly lower than the field test results, which is probably due to the fact that
 230 a simplified ground profile was used in the SPH-FEM model. Moreover, due to the lack of
 231 information on the hammer impact function, a rectangular function was used in the SPH-FEM
 232 analysis to apply the hammer impact on the pile head. This might be another possible reason for the
 233 discrepancies observed between the numerical results and field test results. Even though the results
 234 from the calibrated SPH-FEM model are somewhat lower than the field measurements, it still can
 235 be seen that the simulated results are in good agreement with the field monitoring results, which
 236 provides adequate confidence for using the established SPH-FEM model to study the pile punching
 237 effects on adjacent piles.



238 **Figure 4.** Velocity at various locations (Fig 3): comparison between results from the calibrated model
 239 and field experiment.

240 **4. Case study: Impact of pile punching on an adjacent pile**

241 The impact of pile punching on an adjacent pile was investigated using the established 3D
 242 SPH-FEM model. In the model, a 5 m long pile with 200 mm diameter circular cross-section was
 243 additionally generated (Fig. 5). The pile punching in clayey soil and sandy soil were considered in
 244 the study. The soil was idealised as homogeneous and isotropic material. Note that the influence of
 245 water table was not considered. The driven and the adjacent piles as well as soil were modelled
 246 using the same material models described in Section 2. The material properties for the clay, sand
 247 and concrete piles are given in Section 2. The interaction between the adjacent pile and surrounding
 248 soil was modelled by using AUTOMATIC_SURFACE_TO_SURFACE contact option in LS-DYNA.
 249 This assumes contact at the surface and enables transfer of stresses between solid elements.

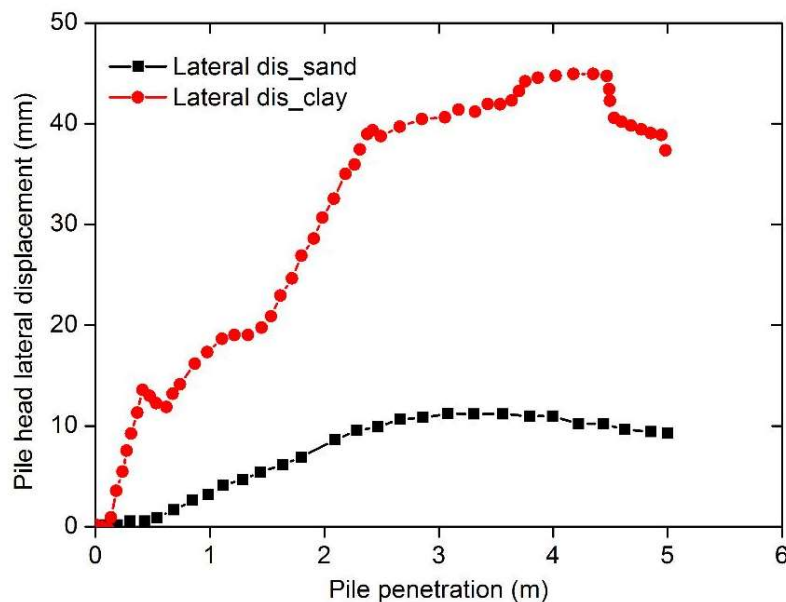


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251 **Figure 5.** 3D SPH-FEM model for investigating the impact of pile punching on an adjacent pile.

252 A parametric study was carried out to investigate the lateral response of an adjacent pile in
 253 clayey soil and sandy soil due to pile punching, by varying the clear spacing between the piles from
 254 1.5 to $10d$ (d is the pile diameter). The impact of the hammer was applied on the pile head as an
 255 impulse using a rectangle force function with time. A load of amplitude 3285 kPa and duration 0.1 s
 256 was applied to the pile head. The period of the hammer blow was considered as 0.5 s.

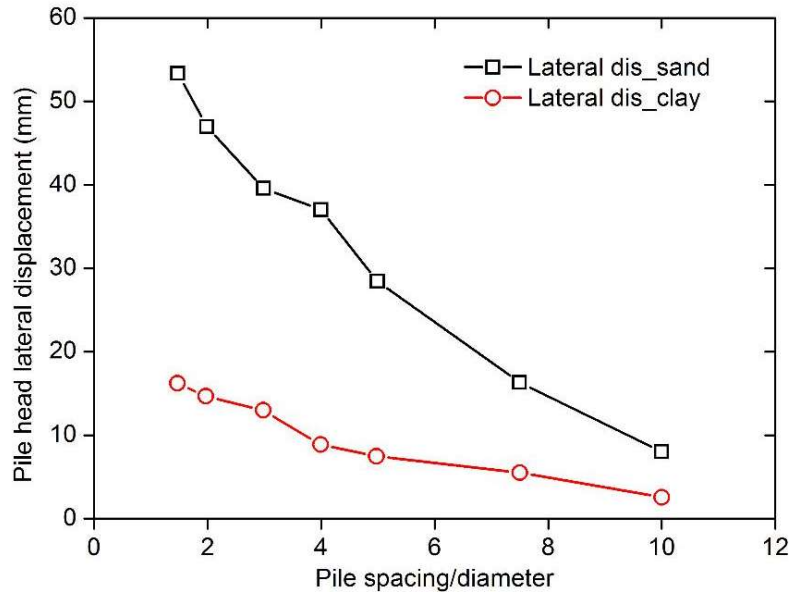
257 Fig. 6 depicts the numerical results for lateral displacement of the head of the adjacent pile
 258 against the penetration depth of the driven pile when the clear spacing is 4 times the pile diameter.
 259 It can be seen from Fig. 6 that the lateral displacement at the head of the adjacent pile initially
 260 increased, followed by a slight decrease as the penetration depth of the driven pile increased. Also,
 261 note that the lateral displacement of the head of the adjacent pile was smaller for a driven pile in a
 262 clayey soil compared to sandy soil. In sandy soil, the displacement of the soil was larger due to the
 263 weak bond between the soil particles. Thus, it might be the reason why the adjacent piles are
 264 expected to have a larger displacement when the piles are driven in sandy soil.



265

266 **Figure 6.** Pile head lateral displacement of the adjacent pile against penetration of the pile.

267 Fig. 7 shows the impact of the pile spacing on the lateral displacement of the head of the
 268 adjacent pile. As expected, as the clear spacing between piles increased, lateral displacement of the
 269 adjacent pile decreased. It was also observed that the lateral pile head displacement decreased from
 270 16 to 2 mm as the clear spacing between piles increased from 1.5 to 10d when the pile were
 271 embedded in the clayey soil. However, in sandy soil, the pile displacement decreased from 54 to 8
 272 mm as the clear spacing between piles increased from 1.5 to 10d. Thus, the interaction between piles
 273 was considerably higher in sandy soil than that in clayey soil.



274

275

Figure 7. Pile head lateral displacement of the adjacent pile against pile spacing.

276 A parametric sensitivity study was further carried out for different soil elastic modulus and
 277 soil density. Soil density was varied from 1600 to 2200 kg/m³, while the elastic modulus of soil was
 278 varied from 10 to 100 MPa to represent very soft to stiff clay soil. Fig. 8 shows the lateral
 279 displacement at the head of the adjacent pile against the clear spacing between piles for different
 280 soil densities. As can be seen, the density of the soil affected the lateral displacement of the adjacent
 281 pile. As the soil density increased, the lateral displacement of the head of the adjacent pile caused
 282 by pile punching decreased. This is because the pile is subjected to higher inertial force when it is
 283 driven in the soil which has high density.

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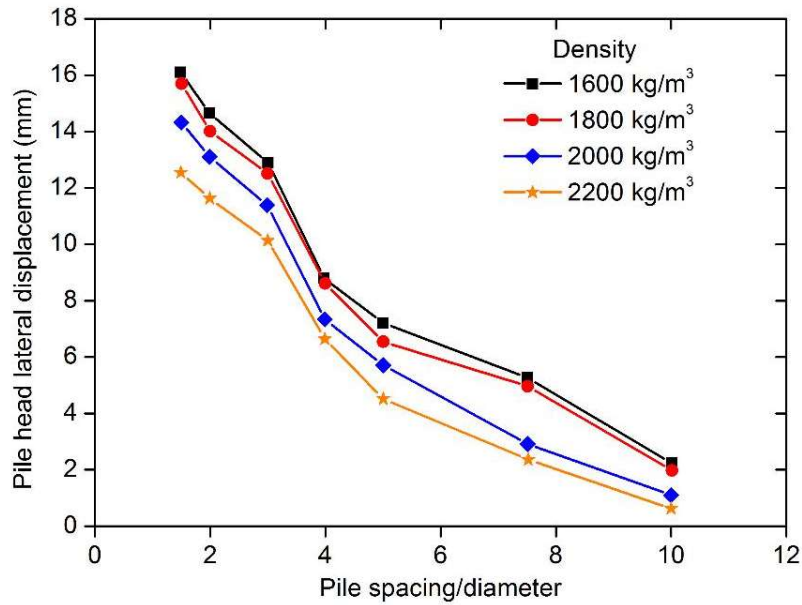
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Fig. 9 shows lateral displacement at the head of the adjacent pile against the clear spacing
 between piles for different soil elastic modulus. The elastic modulus of the soil also significantly
 affected the lateral displacement of the adjacent pile during the pile punching. The lateral
 displacement of the head of the adjacent pile caused by pile punching increased as the elastic
 modulus of soil decreased. Although there is some match in the initial slopes of the lateral
 displacement curves, it indicates a considerable difference when the pile spacing to diameter
 ratio greater than 3. In stiff clays, it was observed that the impact of pile punching on adjacent
 existing pile is comparatively less. Thus, it is clear that the interaction between piles becomes
 less when the piles are driven in stiff soils.

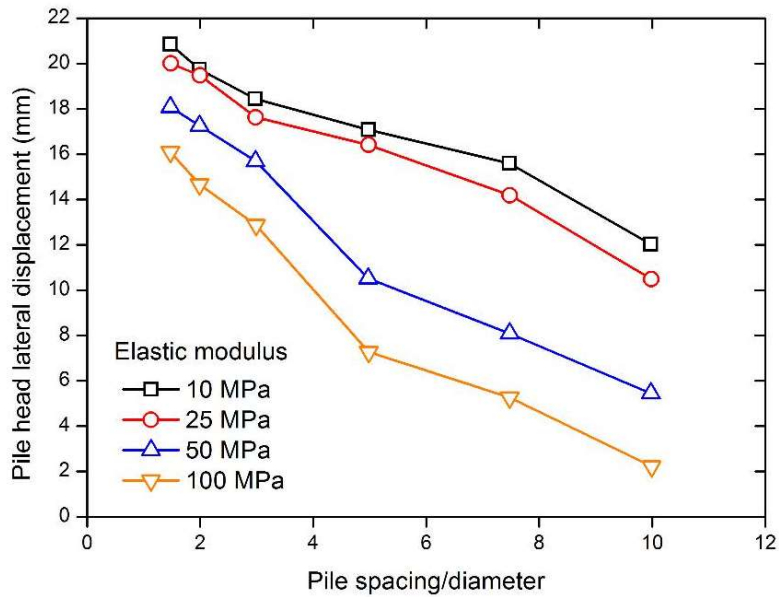
Moreover, Table 2 summarises the numerical results for the lateral displacement of the head
 and tip of the adjacent pile when the clear spacing is 3 times the pile diameter. Tilt of the adjacent
 pile was calculated as the ratio of head displacement relative to the tip displacement of the pile to
 pile length. In all the cases, it was observed that the tilt of the adjacent pile is insignificant. The
 maximum tilt of 0.00304 (i.e. about 1/329) was obtained for the very loose sand which has elastic
 modulus of 10 MPa. The results show that tilt of pile decreases when the pile is installed in a dense

299 or hard soil. Also, it is clear that the installation of a pile close to an existing pile will induce an
300 overall lateral displacement of the adjacent pile rather than tilting.



301

302 **Figure 8.** Pile head lateral displacement of the adjacent pile against pile spacing for different soil
303 densities.



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305 **Figure 9.** Pile head lateral displacement of the adjacent pile against pile spacing for different soil
306 elastic modulus.

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Table 2. Lateral displacement of the head and tip of the adjacent pile (The clear spacing is 3 times the pile diameter)

Analyses case		Pile head displacement (mm)	Pile tip displacement (mm)	Tilt of pile
Varied parameter	Value			
Soil density (kg/m ³)	1600	12.8	4.3	0.00170
	1800	12.5	4.5	0.00160
	2000	11.5	4.8	0.00134
	2200	10.1	4.9	0.00104
Elastic modulus (MPa)	10	18.4	3.2	0.00304
	25	17.6	2.9	0.00294
	50	15.8	3.5	0.00246
	100	12.8	4.3	0.00170

313 5. Conclusions

314 In this study, the impact caused by pile punching on an adjacent pile was investigated using a
315 3D well-established SPH-FEM model; the model was calibrated against field measurements. A
316 comprehensive parametric sensitivity study was performed to evaluate the impact of soil properties
317 on the displacement of a pile due to the punching of an adjacent pile, by varying the elastic
318 modulus of the soil, soil density and spacing between piles. It was found that the lateral
319 displacement of an adjacent pile (due to pile punching) increased with the decrease in soil elastic
320 modulus, soil density and the spacing between the piles. The interaction between piles became
321 weaker when the piles are driven in stiff soils. Results also show that the lateral displacement at the
322 head of an adjacent pile was fairly significant for piles driven into sandy soil.

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