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► **To cite this version:**

| Roland Hildebrand. On the algebraic structure of the copositive cone. 2020. hal-02463279

HAL Id: hal-02463279

<https://hal.archives-ouvertes.fr/hal-02463279>

Preprint submitted on 31 Jan 2020

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On the algebraic structure of the copositive cone

Roland Hildebrand *

January 18, 2020

Abstract

We decompose the copositive cone \mathcal{COP}^n into a disjoint union of a finite number of open subsets $S_{\mathcal{E}}$ of algebraic sets $Z_{\mathcal{E}}$. Each set $S_{\mathcal{E}}$ consists of interiors of faces of \mathcal{COP}^n . On each irreducible component of $Z_{\mathcal{E}}$ these faces generically have the same dimension. Each algebraic set $Z_{\mathcal{E}}$ is characterized by a finite collection $\mathcal{E} = \{(I_{\alpha}, J_{\alpha})\}_{\alpha=1, \dots, |\mathcal{E}|}$ of pairs of index sets. Namely, $Z_{\mathcal{E}}$ is the set of symmetric matrices A such that the submatrices $A_{I_{\alpha} \times J_{\alpha}}$ are rank-deficient for all α . For every copositive matrix $A \in S_{\mathcal{E}}$, the index sets I_{α} are the minimal zero supports of A . If u^{α} is a corresponding minimal zero of A , then J_{α} is the set of indices j such that $(Au^{\alpha})_j = 0$. We call the pair (I_{α}, J_{α}) the extended support of the zero u^{α} , and \mathcal{E} the extended minimal zero support set of A . We provide some necessary conditions on \mathcal{E} for $S_{\mathcal{E}}$ to be non-empty, and for a subset $S_{\mathcal{E}'}$ to intersect the boundary of another subset $S_{\mathcal{E}}$.

Keywords: copositive matrix, minimal zero, facial structure, algebraic sets

1 Introduction

An element A of the space \mathcal{S}^n of real symmetric $n \times n$ matrices is called *copositive* if $x^T A x \geq 0$ for all vectors $x \in \mathbb{R}_+^n$. The set of such matrices forms the *copositive cone* \mathcal{COP}^n . This cone plays an important role in non-convex optimization, as many difficult optimization problems can be reformulated as conic programs over \mathcal{COP}^n . For a detailed survey of the applications of this cone see, e.g., [7, 2, 3, 10].

In [6] the local structure of the cone \mathcal{COP}^n around a given copositive matrix A was considered. In particular, the cone of feasible directions and the tangent cone at A and the minimal face of A have been computed. These objects have a description in terms of the minimal zeros of A .

A zero u of a copositive matrix A is a non-zero nonnegative vector such that $u^T A u = 0$ [4, 1]. The support $\text{supp } u$ of a zero $u = (u_1, \dots, u_n)^T \in \mathbb{R}_+^n$ is the subset of indices $j \in \{1, \dots, n\}$ such that $u_j > 0$. A zero u of A is called *minimal* if there is no zero v of A such that $\text{supp } v \subset \text{supp } u$ holds strictly [8]. The *minimal zero support set*, i.e., the ensemble $\text{supp } \mathcal{V}_{\min}^A$ of minimal zero supports of a copositive matrix A is a characteristic that yields a finite classification of the matrices in \mathcal{COP}^n . However, this classification is quite coarse, e.g., the set of matrices $A' \in \mathcal{COP}^n$ which share the minimal zero support set with A may have a description by different ensembles of equalities and inequalities around different points.

Here we make a further step in the study of the local properties of \mathcal{COP}^n . While the paper [6] focussed on the infinitesimal structure of \mathcal{COP}^n near a given matrix A , in this work we consider finite neighbourhoods of A . To this end we propose a finer characteristic of copositive matrices, still leading to a finite classification, namely their *extended minimal zero support set*. In addition to the minimal zero supports of the matrix A this object contains the *complementary index sets* of its minimal zeros. Here the complementary index set $\text{comp } u$ of a zero u of A is defined as the set of indices j such that $(Au)_j = 0$. Here we show that the set $S_{\mathcal{E}}$ of matrices $A' \in \mathcal{COP}^n$ which share the extended minimal zero support set \mathcal{E} with A is an *open* subset of some explicit algebraic set $Z_{\mathcal{E}} \subset \mathcal{S}^n$. As such it is described by the same set of polynomial equations at every point, which yields a complete and homogeneous characterization of its local structure.

The proposed decomposition of \mathcal{COP}^n into subsets $S_{\mathcal{E}}$ is compatible with the facial structure of the cone. For every face $\mathcal{F} \subset \mathcal{COP}^n$, the interior points of \mathcal{F} all belong to the same subset $S_{\mathcal{E}}$, and hence each $S_{\mathcal{E}}$ can be represented as a disjoint union of such facial interiors. Moreover, for each subset $S_{\mathcal{E}}$ we construct

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a coefficient matrix with entries polynomial in the elements of $A \in S_{\mathcal{E}}$ such that the solution space of the homogeneous linear system of equations with this coefficient matrix is the linear hull of the minimal face of A . As a consequence, on each irreducible component of the algebraic set $Z_{\mathcal{E}}$ the minimal faces of $A \in S_{\mathcal{E}}$ have generically the same dimension, with possibly higher dimensions on some algebraic subset.

The main purpose of this contribution is to provide new tools for the study of the facial structure and especially the extreme rays of the copositive cone, which play a crucial role, e.g., in the verification of the exactness of computationally tractable relaxations of the copositive cone.

The remainder of the paper is structured as follows. In Section 1.1 we provide some notations and formal definitions. In Section 2 we prove our main result (Theorem 2.2) on the decomposition of the cone \mathcal{COP}^n into relatively open subsets according to the extended minimal zero support set. In Section 3 we derive some properties of the subsets and the extended minimal zero support set, in particular related to the facial structure of \mathcal{COP}^n . We provide some necessary conditions on \mathcal{E} for $S_{\mathcal{E}}$ to be non-empty (Lemma 3.2), and for a subset $S_{\mathcal{E}'}$ to intersect the boundary of another subset $S_{\mathcal{E}}$ (Lemma 3.3). In Section 3.1 we provide some examples of subsets $S_{\mathcal{E}}$. In Section 4 we list some open problems related to our decomposition.

1.1 Notations and definitions

The space of real symmetric matrices of size $n \times n$ will be denoted by \mathcal{S}^n .

For an index set $I \subset \{1, \dots, n\}$, denote by \bar{I} its complement $\{1, \dots, n\} \setminus I$.

We shall denote vectors with lower-case letters and matrices with upper-case letters. For a matrix A and a vector u of compatible dimension, the i -th element of the matrix-vector product Au will be denoted by $(Au)_i$. Inequalities $u \geq \mathbf{0}$ on vectors will be meant element-wise, where we denote by $\mathbf{0} = (0, \dots, 0)^T$ the all-zeros vector. Similarly we denote by $\mathbf{1} = (1, \dots, 1)^T$ the all-ones vector. Let $\Delta = \{u \in \mathbb{R}_+^n \mid \mathbf{1}^T u = 1\}$ be the standard simplex.

For a subset $I \subset \{1, \dots, n\}$ we denote by A_I the principal submatrix of A whose elements have row and column indices in I , i.e. $A_I = (A_{ij})_{i,j \in I} \in \mathcal{S}^{|I|}$. For subsets $I, J \subset \{1, \dots, n\}$ we denote by $A_{I \times J}$ the submatrix of A whose elements have row indices in I and column indices in J . Similarly for a vector $u \in \mathbb{R}^n$ we define the sub-vector $u_I = (u_i)_{i \in I} \in \mathbb{R}^{|I|}$.

For a nonnegative vector $u \in \mathbb{R}_+^n$ we define its *support* as $\text{supp } u = \{i \in \{1, \dots, n\} \mid u_i > 0\}$.

A zero u of a copositive matrix A is called *minimal* if there exists no zero v of A such that the inclusion $\text{supp } v \subset \text{supp } u$ holds strictly. We shall denote the set of minimal zeros of a copositive matrix A by \mathcal{V}_{\min}^A and the ensemble of supports of the minimal zeros of A by $\text{supp } \mathcal{V}_{\min}^A$. To each index set I there exists at most one minimal zero $u \in \Delta$ of A with $\text{supp } u = I$ [8, Lemma 3.5], hence the minimal zero support set $\text{supp } \mathcal{V}_{\min}^A$ is in bijective correspondence to the minimal zeros of A which are contained in Δ .

We now introduce the extended minimal zero support set of a copositive matrix.

Definition 1.1. Let $A \in \mathcal{COP}^n$ and let u be a zero of A . The *complementary index set* $\text{comp } u$ of u is the index set $\{j \mid (Au)_j = 0\} = \overline{\text{supp}(Au)}$. The *extended support* $\text{esupp } u$ of u is the pair $(\text{supp } u, \text{comp } u)$ of index sets. The *extended minimal zero support set* $\text{esupp } \mathcal{V}_{\min}^A$ is the ensemble of extended supports of the minimal zeros of A .

By [5, Lemma 2.5] we have that $\text{supp } u \subset \text{comp } u$ for every zero u of a copositive matrix A .

Let $\mathcal{E} = \{(I_{\alpha}, J_{\alpha})\}_{\alpha=1, \dots, m}$ be a finite collection of pairs of index sets. Define the set

$$S_{\mathcal{E}} = \{A \in \mathcal{COP}^n \mid \text{esupp } \mathcal{V}_{\min}^A = \mathcal{E}\}$$

of copositive matrices having extended minimal zero support set \mathcal{E} . Then the whole copositive cone \mathcal{COP}^n decomposes into a disjoint union of a finite number of such subsets $S_{\mathcal{E}}$. We shall also associate to \mathcal{E} the set

$$Z_{\mathcal{E}} = \{A \in \mathcal{S}^n \mid A_{I_{\alpha} \times J_{\alpha}} \text{ is rank deficient } \forall \alpha = 1, \dots, m\}.$$

Clearly $Z_{\mathcal{E}}$ is algebraic, given by the zero locus of a finite number of determinantal polynomials in the elements of A .

2 Openness of $S_{\mathcal{E}}$ in $Z_{\mathcal{E}}$

In this section we prove our main result, which states that the sets $S_{\mathcal{E}}$ of matrices sharing the same extended minimal zero support set \mathcal{E} are open in the relative topology of the algebraic set $Z_{\mathcal{E}}$.

Lemma 2.1. *Let $\mathcal{E} = \{(I_{\alpha}, J_{\alpha})\}_{\alpha=1, \dots, m}$ be a collection of pairs of index sets. Then $S_{\mathcal{E}} \subset Z_{\mathcal{E}}$.*

Proof. We have to show that whenever a matrix $A \in \mathcal{COP}^n$ has extended minimal zero support set \mathcal{E} , its sub-matrices $A_{I_{\alpha} \times J_{\alpha}}$ are rank deficient for all $\alpha = 1, \dots, m$. First note that $I_{\alpha} \subset J_{\alpha}$, and hence $A_{I_{\alpha} \times J_{\alpha}}$ is rank deficient if and only if its transpose has a non-zero right kernel vector. Such a kernel vector is readily provided by the sub-vector $u_{I_{\alpha}}^{\alpha}$, where u^{α} is a minimal zero of A having support I_{α} . This completes the proof. \square

Theorem 2.2. *Let $A \in \mathcal{COP}^n$ be a copositive matrix and let $\mathcal{E} = \{(I_{\alpha}, J_{\alpha})\}_{\alpha=1, \dots, m}$ be the extended minimal zero support set of A . Then there exists a neighbourhood $U \subset \mathcal{S}^n$ of A such that $U \cap S_{\mathcal{E}} = U \cap Z_{\mathcal{E}}$.*

Proof. Assume for the sake of contradiction that there exists a sequence $A_k \in Z_{\mathcal{E}} \setminus S_{\mathcal{E}}$ of matrices converging to A .

Let $u^{\alpha} \in \Delta$ be the minimal zero of A with support I_{α} and complementary index set J_{α} , $\alpha = 1, \dots, m$. By [8, Lemma 3.7] the submatrix $A_{I_{\alpha}}$ is positive semi-definite of co-rank 1. The 1-dimensional kernel of this submatrix is generated by the element-wise positive sub-vector $u_{I_{\alpha}}^{\alpha}$.

By definition the submatrix $B_{I_{\alpha}}$ is rank deficient for every matrix $B \in Z_{\mathcal{E}}$, i.e., its co-rank is at least 1. Since the co-rank is upper semi-continuous, it can be at most 1 for all submatrices $(A_k)_{I_{\alpha}}$ except possibly a finite number. Without loss of generality we may assume that the co-rank of $(A_k)_{I_{\alpha}}$ equals 1 for all k , and hence has a 1-dimensional kernel. Since $(A_k)_{I_{\alpha}} \rightarrow A_{I_{\alpha}}$, this kernel tends to the 1-dimensional subspace generated by the sub-vector $u_{I_{\alpha}}^{\alpha} > \mathbf{0}$. Let us choose vectors v_k^{α} with support $\text{supp } v_k^{\alpha} \subset I_{\alpha}$ such that the sub-vectors $(v_k^{\alpha})_{I_{\alpha}}$ generate the kernel of $(A_k)_{I_{\alpha}}$ and $v_k^{\alpha} \rightarrow u^{\alpha}$. Without loss of generality we may assume that all sub-vectors $(v_k^{\alpha})_{I_{\alpha}}$ are element-wise positive, i.e., that $v_k^{\alpha} \geq \mathbf{0}$ and $\text{supp } v_k^{\alpha} = I_{\alpha}$, and that $v_k^{\alpha} \in \Delta$.

The submatrix $A_{I_{\alpha}}$ has $|I_{\alpha}| - 1$ positive and one zero eigenvalue. Since $(A_k)_{I_{\alpha}} \rightarrow A_{I_{\alpha}}$ and the submatrices $(A_k)_{I_{\alpha}}$ have exactly one zero eigenvalue, the other eigenvalues of $(A_k)_{I_{\alpha}}$ must be positive for all k sufficiently large. Hence we may assume without loss of generality that the submatrices $(A_k)_{I_{\alpha}}$ are positive semi-definite for all k . It follows by [8, Lemma 3.7] that $(v_k^{\alpha})_{I_{\alpha}}$ is a minimal zero of the submatrix $(A_k)_{I_{\alpha}}$.

By definition the submatrix $B_{J_{\alpha} \times I_{\alpha}}$ is rank deficient for every matrix $B \in Z_{\mathcal{E}}$, which by virtue of the inclusion $I_{\alpha} \subset J_{\alpha}$ implies that it has a non-zero right kernel vector. This kernel vector is also in the kernel of the principal submatrix $B_{I_{\alpha}}$. However, the kernel of $(A_k)_{I_{\alpha}}$ is 1-dimensional and generated by the sub-vector $(v_k^{\alpha})_{I_{\alpha}}$. Therefore $(v_k^{\alpha})_{I_{\alpha}}$ is also in the kernel of $(A_k)_{J_{\alpha} \times I_{\alpha}}$, and $(A_k v_k^{\alpha})_{J_{\alpha}} = \mathbf{0}$. On the other hand, we have $A_k v_k^{\alpha} \rightarrow A u^{\alpha}$, and hence we may assume without loss of generality that $\text{supp}(A u^{\alpha}) \subset \text{supp}(A_k v_k^{\alpha})$ for all k . Since $\text{comp } u^{\alpha} = J_{\alpha}$ by assumption, we obtain $\text{supp}(A_k v_k^{\alpha}) = J_{\alpha}$.

If $A_k \in \mathcal{COP}^n$, then by the preceding v_k^{α} is a minimal zero of A_k with extended support (I_{α}, J_{α}) .

Let us show that indeed $A_k \in \mathcal{COP}^n$ except for possibly a finite number of indices k . For each k , consider the problem

$$\min_{w \in \Delta} \frac{1}{2} w^T A_k w. \quad (1)$$

Assume for the sake of contradiction that there exists a sub-sequence of matrices A_k converging to A , which for brevity will also be denoted by A_k , such that the optimal value γ_k of problem (1) is negative for all k . Let $w_k^* \in \Delta$ be the corresponding optimizers. Without loss of generality we may pass to a sub-sequence $\{w_k^*\}$ which converges to some vector $u^* \in \Delta$. Then $0 > 2\gamma_k = (w_k^*)^T A_k w_k^* \rightarrow (u^*)^T A u^*$, and we must have $(u^*)^T A u^* \leq 0$. However, the matrix A is copositive, which implies $(u^*)^T A u^* \geq 0$ and hence u^* is a zero of A . Define the index sets $I = \text{supp } u^*$, $J = \text{comp } u^*$, and note that $I \subset J$. Since $w_k^* \rightarrow u^*$, we may assume without loss of generality that $I \subset \text{supp } w_k^*$ for all k .

By [8, Corollary 3.4] the zero u^* can be represented as a sum of minimal zeros of A . Equivalently, u^* is a convex combination of the minimal zeros u^{α} , and there exist nonnegative numbers η_{α} , $\sum_{\alpha=1}^m \eta_{\alpha} = 1$, such that $u^* = \sum_{\alpha=1}^m \eta_{\alpha} u^{\alpha}$. Note that $\text{supp } u^* = \bigcup_{\alpha: \eta_{\alpha} > 0} I_{\alpha}$.

We have $\mathbf{0} = (A u^*)_J = \sum_{\alpha=1}^m \eta_{\alpha} (A u^{\alpha})_J$. However, $A u^{\alpha} \geq \mathbf{0}$ for all α by [1, p.200]. Therefore $(A u^{\alpha})_J = \mathbf{0}$ and as a consequence $J \subset J_{\alpha}$ and thus also $(A_k v_k^{\alpha})_J = \mathbf{0}$ for all α such that $\eta_{\alpha} > 0$. For

each k , define $v_k = \sum_{\alpha=1}^m \eta_\alpha v_k^\alpha$. Then $v_k \in \Delta$ for all k , and $\text{supp } v_k = \bigcup_{\alpha: \eta_\alpha > 0} \text{supp } v_k^\alpha = \bigcup_{\alpha: \eta_\alpha > 0} I_\alpha = I$. Moreover, $(A_k v_k)_J = \sum_{\alpha=1}^m \eta_\alpha (A_k v_k^\alpha)_J = \mathbf{0}$. It follows that $v_k^T A_k v_k = (v_k)_I^T (A_k v_k)_I = 0$.

Let us consider the first order optimality condition at w_k^* . It states that for each k there exists a nonnegative vector $\lambda_k \in \mathbb{R}_+^n$ and a number μ_k such that

$$\frac{\partial}{\partial w} \left(\frac{1}{2} w^T A_k w - \lambda_k^T w + \mu_k (1 - \mathbf{1}^T w) \right) = A_k w - \lambda_k - \mu_k \mathbf{1} = \mathbf{0}$$

at $w = w_k^*$, and $\lambda_k^T w_k^* = 0$. Multiplying from the left by w_k^* , we obtain

$$0 = (w_k^*)^T A_k w_k^* - (w_k^*)^T \lambda_k - \mu_k \mathbf{1}^T w_k^* = 2\gamma_k - \mu_k,$$

and hence

$$\lambda_k = A_k w_k^* - \mu_k \mathbf{1} = A_k w_k^* - 2\gamma_k \mathbf{1}.$$

Passing to the limit on both sides and taking into account $2\gamma_k \rightarrow (u^*)^T A u^* = 0$, we obtain $\lim_{k \rightarrow \infty} \lambda_k = A u^*$. Without loss of generality we may hence assume that $\text{supp}(A u^*) \subset \text{supp } \lambda_k$ for all k . It follows that $\text{supp } w_k^* \subset \text{supp } \lambda_k \subset \text{supp}(A u^*) = J$.

Let us now introduce a parameter $\tau \geq 0$ and consider the vector $w_k(\tau) = (1 - \tau)v_k + \tau w_k^*$. By virtue of $(w_k^*)^T A_k v_k = (w_k^*)^T (A_k v_k)_J = 0$ the value of the objective function of problem (1) on this vector equals

$$\frac{1}{2} w_k^T(\tau) A_k w_k(\tau) = \frac{1}{2} \left((1 - \tau)^2 v_k^T A_k v_k + 2\tau(1 - \tau)(w_k^*)^T A_k v_k + \tau^2 (w_k^*)^T A_k w_k^* \right) = \tau^2 \gamma_k.$$

Recall that $I = \text{supp } v_k \subset \text{supp } w_k^*$ and hence the minimal face of w_k^* in Δ contains the vector v_k . Since $w_k^* = w_k(1)$ is in the relative interior of its minimal face, there exists $\tau > 1$ such that $w_k(\tau)$ is also in this face and hence in Δ . However, $\tau^2 \gamma_k < \gamma_k$ for such τ , contradicting that γ_k is the minimum of the objective function over Δ .

Thus we may assume that $A_k \in \mathcal{COP}^n$ for all k . It remains to show that $\text{esupp } \mathcal{V}_{\min}^{A_k} = \mathcal{E}$ for all sufficiently large k . The minimal zeros v_k^α of A_k ensure that $\mathcal{E} \subset \text{esupp } \mathcal{V}_{\min}^{A_k}$. Let us show the opposite inclusion.

Suppose for the sake of contradiction that there exists a pair of index sets (\hat{I}, \hat{J}) which is not contained in \mathcal{E} and such that A_k has a minimal zero $\hat{u}_k \in \Delta$ with extended support (\hat{I}, \hat{J}) for sufficiently large k . Without loss of generality assume that $\hat{u}_k \rightarrow \hat{u} \in \Delta$. Then $0 = \hat{u}_k^T A_k \hat{u}_k \rightarrow \hat{u}^T A \hat{u}$, and \hat{u} must be a zero of A with $\text{supp } \hat{u} \subset \hat{I}$. Hence there exists a minimal zero u^α of A such that $I_\alpha \subset \text{supp } \hat{u} \subset \hat{I}$. However, every A_k possesses a minimal zero with support I_α , namely v_k^α . By the minimality of \hat{u}_k we then must have $\hat{I} = I_\alpha$ and $\hat{u}_k = v_k^\alpha$, contradicting the assumption $(\hat{I}, \hat{J}) \notin \mathcal{E}$.

Thus $A_k \in \mathcal{S}_\mathcal{E}$ for sufficiently large k , which completes the proof of the theorem. \square

The theorem implies that in a neighbourhood of any copositive matrix $A \in \mathcal{COP}^n$ with $\text{esupp } \mathcal{V}_{\min}^A = \mathcal{E}$, the structure of the set $\mathcal{S}_\mathcal{E}$ of copositive matrices sharing the extended minimal zero support set with A is completely described by the polynomial relations determining the algebraic set $Z_\mathcal{E}$. We have the following result.

Corollary 2.3. *Let $\mathcal{E} = \{(I_\alpha, J_\alpha)\}_{\alpha=1, \dots, m}$ be an arbitrary collection of pairs of index sets. Then $\mathcal{S}_\mathcal{E}$ is an open subset in the relative topology of the algebraic set $Z_\mathcal{E}$.*

Proof. If $\mathcal{S}_\mathcal{E} = \emptyset$, then the assertion of the corollary is trivial. In the opposite case it follows from Theorem 2.2. \square

3 Properties of the subsets $\mathcal{S}_\mathcal{E}$

In this section we establish some properties of the extended minimal zero support set and the corresponding subsets $\mathcal{S}_\mathcal{E}$, in particular in relation to the facial structure of \mathcal{COP}^n .

First we consider the action of the automorphism group of \mathcal{COP}^n on the decomposition into subsets $\mathcal{S}_\mathcal{E}$.

Lemma 3.1. *The decomposition of \mathcal{COP}^n into subsets $S_{\mathcal{E}}$ is invariant under scaling $A \mapsto DAD$ by positive definite diagonal matrices and equivariant under the action $A \mapsto PAP^T$ of the symmetric group S_n .*

Proof. Let u be a minimal zero of $A \in \mathcal{COP}^n$ with extended support (I, J) .

Suppose D is a positive definite diagonal matrix. Then $D^{-1}u$ is a minimal zero of the diagonally scaled matrix $DAD \in \mathcal{COP}^n$. It is easily seen that the extended support of $D^{-1}u$ is again (I, J) . Hence A and DAD have the same extended minimal zero support set and reside in the same subset $S_{\mathcal{E}}$.

On the other hand, let $P \in S_n$ be a permutation matrix. Then Pu is a minimal zero of the permuted matrix PAP^T . However, the extended support (\tilde{I}, \tilde{J}) of Pu is obtained from (I, J) by element-wise application of the permutation P . Hence the extended minimal zero support set of PAP^T is obtained from \mathcal{E} by the element-wise action of P .

This completes the proof. \square

We have the following simple properties.

Lemma 3.2. *Let $\mathcal{E} = \{(I_{\alpha}, J_{\alpha})\}_{\alpha=1, \dots, m}$ be a collection of pairs of index sets such that $S_{\mathcal{E}} \neq \emptyset$. Then for every α, β we have $I_{\alpha} \subset J_{\beta}$ if and only if $I_{\beta} \subset J_{\alpha}$. Moreover, $I_{\alpha} \subset J_{\alpha}$ for all α . If $\alpha \neq \beta$, then $I_{\alpha} \not\subset I_{\beta}$.*

Proof. Let $A \in S_{\mathcal{E}}$ and let u^{α} be minimal zeros of A with $\text{supp } u^{\alpha} = I_{\alpha}$, $\alpha = 1, \dots, m$. We shall show that the inclusion $I_{\beta} \subset J_{\alpha}$ is equivalent to the relation $(u^{\beta})^T A u^{\alpha} = 0$.

Indeed, since $u^{\beta} \geq \mathbf{0}$ and $A u^{\alpha} \geq \mathbf{0}$, the relation $(u^{\beta})^T A u^{\alpha} = 0$ is equivalent to $\text{supp } u^{\beta} \cap \text{supp}(A u^{\alpha}) = I_{\beta} \cap \overline{J_{\alpha}} = \emptyset$. This in turn is equivalent to $I_{\beta} \subset J_{\alpha}$.

By the symmetry of the condition $(u^{\beta})^T A u^{\alpha} = 0$ with respect to an exchange of α, β we obtain the first claim of the lemma.

The second claim follows from the relation $(u^{\alpha})^T A u^{\alpha} = 0$.

The last assertion holds by the minimality property of the supports I_{α} of the minimal zeros u^{α} . \square

If the set $S_{\mathcal{E}}$ is non-empty and not the zero set $\{\mathbf{0}\}$, then it has a boundary, which by Corollary 2.3 is a subset of $Z_{\mathcal{E}} \setminus S_{\mathcal{E}}$. Since \mathcal{COP}^n is closed, this boundary consists of copositive matrices, and hence of elements of other subsets $S_{\mathcal{E}'}$ with $\mathcal{E}' \neq \mathcal{E}$. The following result describes a relation between the two collections $\mathcal{E}', \mathcal{E}$.

Lemma 3.3. *Let $\mathcal{E} = \{(I_{\alpha}, J_{\alpha})\}_{\alpha=1, \dots, m}$ be a collection of pairs of index sets, and let $A_k \in S_{\mathcal{E}}$ be a sequence of matrices tending to some limit $A \in S_{\mathcal{E}'}$, $\mathcal{E}' = \{(I'_{\alpha'}, J'_{\alpha'})\}_{\alpha=1, \dots, m'}$. Then for every $\alpha = 1, \dots, m$ there exists $\alpha' \in \{1, \dots, m'\}$ such that $I'_{\alpha'} \subset I_{\alpha}$, $J_{\alpha} \subset J'_{\alpha'}$. In particular, we have $Z_{\mathcal{E}'} \subset Z_{\mathcal{E}}$.*

Proof. Let $u_k \in \Delta$ be the minimal zero of A_k with extended support (I_{α}, J_{α}) . Assume without loss of generality that $u_k \rightarrow u \in \Delta$. We have $0 = u_k^T A_k u_k \rightarrow u^T A u$, and hence u is a zero of A . Moreover, $\text{supp } u \subset \text{supp } u_k = I_{\alpha}$. On the other hand, $A_k u_k \rightarrow A u$, and hence $\text{supp}(A u) \subset \text{supp}(A_k u_k) = \overline{J_{\alpha}}$. It follows that $J_{\alpha} \subset \text{comp } u$.

The zero u of A can be decomposed as a sum of minimal zeros of A [8, Corollary 3.4], $u = \sum_{\alpha'} u^{\alpha'}$ with the extended support of the minimal zero $u^{\alpha'}$ being $(I'_{\alpha'}, J'_{\alpha'}) \in \mathcal{E}'$. Note also that $A u = \sum_{\alpha'} A u^{\alpha'}$. Now both $u^{\alpha'}$ and $A u^{\alpha'}$ are nonnegative vectors, and hence $I'_{\alpha'} = \text{supp } u^{\alpha'} \subset \text{supp } u$, $\text{supp}(A u^{\alpha'}) \subset \text{supp}(A u)$ for all α' appearing in the sum, the second inclusion being equivalent to $\text{comp } u \subset J'_{\alpha'}$.

The first assertion of the lemma now readily follows.

Now if the submatrix $B_{J' \times I'}$ of some matrix $B \in \mathcal{S}^n$ has a non-zero right kernel vector, then also $B_{J \times I}$ has a non-zero right kernel vector whenever $I' \subset I$, $J \subset J'$. This proves the second assertion. \square

We now pass to the properties related to the facial structure of \mathcal{COP}^n .

Lemma 3.4. *All matrices in the relative interior of a face $\mathcal{F} \subset \mathcal{COP}^n$ belong to the same subset $S_{\mathcal{E}}$. The matrices in the boundary of the face \mathcal{F} do not belong to the subset $S_{\mathcal{E}}$.*

Proof. Let A in the relative interior of \mathcal{F} have extended minimal zero support set $\mathcal{E} = \{(I_{\alpha}, J_{\alpha})\}_{\alpha=1, \dots, m}$, and let u^{α} be minimal zeros of A with support I_{α} . Note that \mathcal{F} is the minimal face of A . By [6, Theorem 17] the linear hull of \mathcal{F} is given by all matrices $B \in \mathcal{S}^n$ such that $(B u^{\alpha})_{J_{\alpha}} = \mathbf{0}$ for all $\alpha = 1, \dots, m$. Hence this linear hull is a subset of $Z_{\mathcal{E}}$. Thus by virtue of Theorem 2.2 there exists a neighbourhood U of A such that $U \cap \mathcal{F} \subset S_{\mathcal{E}}$.

It follows that the extended minimal zero support set is locally constant on the interior of the face \mathcal{F} . This implies the first assertion of the lemma.

On the other hand, suppose for the sake of contradiction that $A' \in \partial\mathcal{F} \cap S_{\mathcal{E}}$. Then again by Theorem 2.2 there exists a neighbourhood U' of A' in the linear hull of \mathcal{F} such that $U' \subset S_{\mathcal{E}}$ and hence $U' \subset \mathcal{COP}^n$. This contradicts the assumption $A' \in \partial\mathcal{F}$ and proves the second assertion of the lemma. \square

Corollary 3.5. *Each of the subsets $S_{\mathcal{E}} \subset \mathcal{COP}^n$ is a disjoint union of relative interiors of faces of \mathcal{COP}^n .*

Proof. The corollary follows from Lemma 3.4 and the fact that relative interiors of different faces do not intersect. \square

We shall need the following auxiliary result.

Lemma 3.6. *Let M be a $k \times k$ matrix of rank $k - 1$ and with left kernel vector having a non-zero first element. Denote $I_i = \{1, \dots, k\} \setminus \{i\}$, $i = 1, \dots, k$. Then the right kernel of M is generated by the vector $u \in \mathbb{R}^k$ with elements $u_i = (-1)^i \det M_{I_1 \times I_i}$.*

Proof. By assumption the first row of M is a linear combination of the other $k - 1$ rows. Since the matrix M is of rank $k - 1$, the remaining $k - 1$ rows are linearly independent and at least one of the determinants defining the elements of u is non-zero. Let the vector $v = (v_1, \dots, v_k)^T$ generate the right kernel of M .

Now replace the elements of the first row of M by independent variables x_1, \dots, x_k and let $f(x) = -\sum_{i=1}^k u_i x_i$ be the determinant of the so-modified matrix. This determinant is zero if and only if the vector $x = (x_1, \dots, x_k)$ is a linear combination of the other rows of the matrix. In this case v is a right kernel vector of the matrix, and $\sum_{i=1}^k v_i x_i = 0$. Thus v must be proportional to u , which completes the proof. \square

Let now $A \in \mathcal{COP}^n$ be arbitrary and let \mathcal{E} be the extended minimal zero support set of A . Let \mathcal{F} be the minimal face of A . As mentioned in the proof of Lemma 3.4, its linear hull is given by the solution space of a linear homogeneous system of equations with the non-zero coefficients being the positive elements of the minimal zeros of A . By Lemma 3.6, these elements can be expressed by polynomials in the elements of the matrix A . Moreover, the linear system has the same form for all matrices in $S_{\mathcal{E}}$.

Therefore the dimension of the minimal face of a matrix $A \in S_{\mathcal{E}}$ is given by the column rank defect of a matrix depending polynomially on A . We obtain the following result.

Lemma 3.7. *Let \mathcal{E} be a collection of pairs of index sets, and let C be an irreducible component of the algebraic set $Z_{\mathcal{E}}$ such that $S = C \cap S_{\mathcal{E}} \neq \emptyset$. Then the dimension of the minimal face of a matrix $A \in S$ is constant over S , with the possible exception of an algebraic subset of lower dimension where the dimension of the face is higher.*

Proof. The column rank defect of a matrix is determined by which of its minors are zero or not. In our case these minors are polynomials in the elements of A , and hence they either identically vanish on C or their zero set is an algebraic subset of lower dimension. On this subset the column rank defect can only increase. \square

In particular, each component of $S_{\mathcal{E}}$ either does not contain any extremal matrix, or all matrices in the component are extremal with the possible exception of an algebraic subset of lower dimension. This makes the decomposition proposed in this paper especially well-suited for the study of the extremal matrices of \mathcal{COP}^n .

3.1 Examples

In this section we provide some explicit examples of subsets $S_{\mathcal{E}}$.

Interior of \mathcal{COP}^n : The largest subset for any order n is the subset S_{\emptyset} , which equals the interior of the cone. In this case $Z_{\emptyset} = S^n$. This example shows that the boundary of $S_{\mathcal{E}}$ may be as complicated as the copositive cone itself.

Generic points in $\partial\mathcal{COP}^n$: On open dense subset of the boundary $\partial\mathcal{COP}^n$ must be defined by subsets $S_{\mathcal{E}}$ of dimension $\frac{n(n+1)}{2} - 1$. The corresponding algebraic set $Z_{\mathcal{E}}$ is determined by a single polynomial

equation. In this case we must have $\mathcal{E} = \{(I, I)\}$ for some non-empty index set I , and the corresponding equation amounts to $\det A_I = 0$.

Zero subset: The unique 0-dimensional subset $S_{\mathcal{E}}$ is the point $\{\mathbf{0}\}$, with $\mathcal{E} = \{(\{i\}, \{1, \dots, n\})\}_{i=1, \dots, n}$.

Orbit of the Horn matrix: A non-trivial example of a subset $S_{\mathcal{E}}$ is the set of matrices

$$D \begin{pmatrix} 1 & -1 & 1 & 1 & -1 \\ -1 & 1 & -1 & 1 & 1 \\ 1 & -1 & 1 & -1 & 1 \\ 1 & 1 & -1 & 1 & -1 \\ -1 & 1 & 1 & -1 & 1 \end{pmatrix} D \in \mathcal{COP}^5, \quad D = \text{diag}(d_1, \dots, d_5) \succ 0.$$

In this case the extended minimal zero support set is given by

$$\mathcal{E} = \{(\{1, 2\}, \{5, 1, 2, 3\}), (\{2, 3\}, \{1, 2, 3, 4\}), (\{3, 4\}, \{2, 3, 4, 5\}), (\{4, 5\}, \{3, 4, 5, 1\}), (\{5, 1\}, \{1, 2, 3, 4\})\}.$$

Matrices with circulant zero support set: The previous example can be generalized to arbitrary order n . The corresponding copositive matrices have been studied in [9].

Let $\mathcal{E} = \{(\overline{\{1, 2, 3\}}, \overline{\{2\}}), \dots, (\overline{\{n, 1, 2\}}, \overline{\{1\}})\}$, $n \geq 5$, where the pairs of index sets in \mathcal{E} are obtained from each other by a circular shift of the indices $1, \dots, n$. Then $S_{\mathcal{E}}$ is an algebraic manifold of dimension $\frac{n(n-3)}{2}$ consisting of extremal exceptional copositive matrices [9, Theorem 6.3].

Let $\mathcal{E} = \{(\overline{\{1, 2\}}, \overline{\{1, 2\}}), \dots, (\overline{\{n, 1\}}, \overline{\{n, 1\}})\}$, $n \geq 5$, where the pairs of index sets in \mathcal{E} are obtained from each other by a circular shift of the indices $1, \dots, n$. Then $S_{\mathcal{E}}$ is an algebraic manifold of dimension $\frac{n(n-1)}{2}$ consisting of exceptional copositive matrices, which can be extremal only for odd n [9, Theorem 6.1].

4 Open problems

In this contribution we mainly studied the local properties of the sets $S_{\mathcal{E}}$. However, natural questions on the global structure of the decomposition arise.

- Are the subsets $S_{\mathcal{E}}$ irreducible, or even algebraic manifolds?
- If $S_{\mathcal{E}'}$ intersects the boundary of $S_{\mathcal{E}}$, does it follow that it is contained in this boundary?
- Does the decomposition into subsets $S_{\mathcal{E}}$ define on \mathcal{COP}^n the structure of a stratified algebraic manifold?

Another line of research is to find stronger necessary or sufficient conditions on a collection \mathcal{E} of pairs of index sets for the subset $S_{\mathcal{E}}$ to be non-empty.

Convex duality implies that every face of the copositive cone has a complementary face in its dual, the completely positive cone \mathcal{CP}^n . Any subset $S_{\mathcal{E}}$ hence corresponds to a subset of \mathcal{CP}^n , consisting of the interiors of the faces which are complementary to the faces in $S_{\mathcal{E}}$. A similar analysis can then be performed for the completely positive cone.

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