

# Patching Circuit Design Based on Reserved CLBs

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**Abstract**—The new approach to patching circuit design that allows masking any logical gate faults of combinational circuit (combinational part of sequential circuit)  $C$  is considered. It is supposed that only one gate may be fault. There are reserved Configurable Logic Blocks (CLBs) based on Look Up Tables (LUTs) that may mask a gate fault being included into the circuit through Multiplexer (MUX). The suggested approach to patching circuit design in contrast with currently in use allows keeping performance of a fault free circuit. It is suggested to include MUXs in those internal poles of circuit  $C$  that may have hard detectable faults. Experimental results showed that masking LUT based circuits are as a rule, rather simple.

**Keywords**—stuck-at faults, arbitrary faults, test patterns, incompletely specified Boolean functions, patching circuit design.

## I. INTRODUCTION

The growing size, density and complexity of modern VLSI chips are contributing to increase hardware faults and design errors in the silicon, decreasing the manufacturing yield and increasing the design cycle [1]. There has been investigated several practical techniques to increase the yield of VLSIs [2-4]. A general technique is to add space redundancy, e.g., Triple Modular Redundancy (TMR). If we are considering only manufacturing defects, another possible way to increase the yield is Double Modular Redundancy (DMR). In this case we select a module without a defect between identical modules after the VLSI test. Embedded FPGAs have also been used for yield improvement [5-6]. However, the above methods have disadvantages: area overhead and/or performance degradation. In [7, 8] the different approaches to increase the yield with lower overhead have been proposed. There has been used a circuit obtained from a conventional logic circuit from gates by replacing its sub-circuits with Look-Up Tables (LUTs) and Multiplexers (MUXs). Then, if we detect some defects (by the VLSI test), we reconfigure the functionality of some LUTs and MUXs to bypass the defects (single stuck-at faults). This kind of circuits is called Partially Programmable Circuits (PPCs) since some of their parts are programmable. The approach is based on the representation of the sub-circuit behavior of a combinational circuit by the incompletely specified Boolean function. In [9] SAT-based rectification and debugging method based on using PPCs for combinational circuits with LUTs is presented. In [10] a patchable

hardware architecture where functional modifications are achieved by introducing memory elements in a circuit is proposed.

In [11] the method using compact (with two Reduced Ordered Binary Decision Diagrams – ROBDDs) implementation of an incompletely specified Boolean function to mask any gate fault for one output combinational circuit is suggested. It applies a multiplexer in each combinational circuit branch. When the fault of a gate is detected, the proper replacing sub-circuit from reserved Configurable Logic Blocks (CLBs) is constructed. Its output is connected with the circuit through the closest multiplexer in the branch point. The sub-circuit masks either the arbitrary fault of the gate which output is the branch point or the arbitrary fault of any gate for which this branch-point is the closest one but its own output is not a branch point.

In this paper the above mentioned method [11] was spread to multi output combinational circuits (combinational parts of sequential circuits). The strategy of choosing internal poles for including multiplexors is suggested. Unlike the approaches [7-9] our approach allows keeping performance of a fault free circuit.

In Section II implementations of the incompletely specified Boolean function for single and multi output circuits are considered. In Section III the ways of masking faults are discussed. The experimental results are presented in Section IV.

## II. IMPLEMENTATION OF THE INCOMPLETELY SPECIFIED BOOLEAN FUNCTION FOR SINGLE AND MULTI OUTPUT CIRCUITS

Let  $v$  be a selected internal node of a combinational single output circuit  $C$  consisting of gates. The problem of a selection of poles we will discuss later. Correlate  $v$  to a multiplexer (MUX). Pole  $v$  (output of a fault free gate) is connected with one MUX input. If the gate with output pole  $v$  is fault then the output of the special masking sub-circuit is connected with another MUX input. The sub-circuit consisting of CLBs masks any logical fault of the gate. Describe a derivation of a masking sub-circuit. Note that the sub-circuit is implementation of incompletely specified Boolean function corresponding to pole  $v$ . Let  $f$  be the completely specified Boolean function that is implemented by the fault free sub-circuit with the output pole  $v$  and inputs coinciding with inputs of circuit  $C$ . Correlate stuck-at

fault 0 ( $\sigma = 0$ ) and stuck-at fault 1 ( $\sigma = 1$ ) to pole  $v$ . We use these faults to represent the incompletely specified Boolean function describing behavior of the sub-circuit being included in circuit  $C$ . The real fault of the gate with output pole  $v$  may be arbitrary. In [12, 13] the method of finding all test patterns for fault  $\sigma = 0$  ( $\sigma = 1$ ) and presenting them by the ROBDD is suggested. It is based on results obtained in [14].

Let  $f_v^0$  be the function that represents all test patterns for fault  $\sigma = 0$  at pole  $v$ . Let  $f_v^1$  be the function that represents all test patterns for fault  $\sigma = 1$  at pole  $v$ . Let  $\varphi(X)$  be the function implemented by circuit  $C$  and  $\zeta(X, v)$ ,  $X = \{x_1, \dots, x_n\}$ , be the function implemented by the sub-circuits of circuit  $C$  in which pole  $v$  is considered as the input variable along with a set  $X$  and the output coincides with circuit  $C$  output:  $\zeta(X, f) = \varphi(X)$ . We conclude that any test pattern for the fault  $\sigma = 0$  ( $\sigma = 1$ ) at pole  $v$  turns function  $f$  ( $\bar{f}$ ) into 1 and turns function  $\varphi(X)$  either into 1 or into 0. Moreover changing the value at pole  $v$  from 1 to 0 (from 0 to 1) for fault  $\sigma = 0$  ( $\sigma = 1$ ) generates changing the value at circuit  $C$  output from 1 to 0 if the test pattern turns fault free circuit  $C$  output into 1 and from 0 to 1 if the test pattern turns fault free circuit  $C$  output into 0.

Note that if a Boolean vector of length  $n$  turns function  $f$  into 0 (into 1), then it cannot be a test pattern for fault  $\sigma = 0$  ( $\sigma = 1$ ) at pole  $v$ .

They say  $f$  includes  $g$  ( $g$  is an implicant of  $f$ ),  $g \leq f$ , if for any Boolean vector  $\alpha$  of length  $n$  from the condition  $g(\alpha) = 1$  follows the condition  $f(\alpha) = 1$ . For fault  $\sigma = 0$  we have:  $f_v^0 \leq f$ , for fault  $\sigma = 1$ :  $f_v^1 \leq \bar{f}$ .

Let the condition  $f_v^0 \leq \varepsilon \leq \bar{f}_v^1$  for the function  $\varepsilon$  takes place.

**Theorem 1.**  $\zeta(X, f) = \zeta(X, \varepsilon)$ , that is changing the function  $f$  for the function  $\varepsilon$  does not alter function  $\varphi(X)$ .

Let the function  $\gamma$  be as follows:  $f_v^1 \leq \gamma \leq \bar{f}_v^0$ .

**Theorem 2.**  $\zeta(X, f) = \zeta(X, \bar{\gamma})$ , that is changing the function  $f$  for the function  $\bar{\gamma}$  does not alter the function  $\varphi(X)$ .

Explain Theorems 1, 2 using the Venn diagrams in Fig. 1.

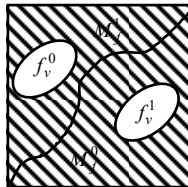


Fig. 1. Representation of the incompletely specified Boolean function for pole  $v$

All spots of the rectangle represent all Boolean vectors of length  $n$ . These spots are divided into on-set  $M_f^1$  and

off-set  $M_f^0$  of completely specified function  $f$  by wavy line.

The oval inside of  $M_f^1$  area presents the on-set of function

$f_v^0$  corresponding to a set of all test patterns for fault  $\sigma = 0$

at pole  $v$  of circuit  $C$ . The oval inside of  $M_f^1$  area presents

the on-set of function  $f_v^1$  corresponding to a set of all test patterns for fault  $\sigma = 1$  at pole  $v$  of circuit  $C$ . The dashed part of the rectangle is don't care area of the incompletely specified Boolean function. The on-set and the off-set of this function are represented with the on sets of functions  $f_v^0$ ,  $f_v^1$ , correspondingly. Taking into consideration Theorems 1, 2, when masking fault, we may choose the circuit that implements either function  $\varepsilon$ , or function  $\bar{\gamma}$ . Both these functions may be represented with the corresponding ROBDDs. The chosen ROBDD may be covered with CLBs (to get the circuit whose behavior is represented by this ROBDD) in the way described in [15].

*Proposition 1.* The behavior of any sub-circuit of single output combinational circuit  $C$  is described with incompletely specified Boolean function  $f_{inc}$ . The on-set of  $f_{inc}$  is represented by the on-set of function  $f_v^0$  and the off-set of  $f_{inc}$  is represented by the on-set of function  $f_v^1$ .

This proposition takes place for any internal pole of a single output circuit  $C$ . For finding a minimum masking circuit realization we can use one of the heuristic algorithm ROBDD minimization for incompletely specified Boolean functions, for instance [16]. Let  $f^*(X)$  be the completely specified function that realizes the incompletely specified function (presented by  $f_v^0$  and  $f_v^1$ ) and has minimized ROBDD size. Use ROBDD of function  $f^*$  to mask the fault of the gate with output pole  $v$ .

The example of two output circuit  $C$  is given in Fig. 2. Consider the one output sub-circuit of circuit  $C$  corresponding to output  $F(1)$ .

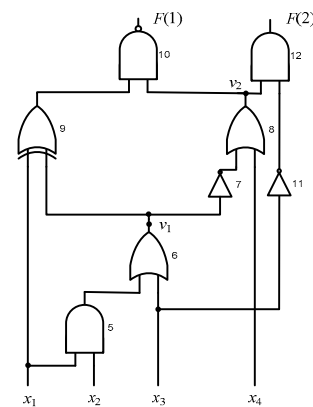


Fig. 2. The combinational circuit  $C$

Extract functions  $f_v^0(1)$ ,  $f_v^1(1)$ ,  $f(1)$ ,  $f^*(1)$  for pole  $v_1$ . Represent incompletely specified function with K-map in Fig. 3a. Here the on-set is represented with 1s, the off-set is represented with 0s and don't care set is represented with asterisks. Mark elements of the on-set for function  $f^*(1)$  by

circles. For pole  $v_1$  function  $f^*(1)$  coincides with  $f(1)$ . The ROBDD of  $f(1)$  has minimized number of nodes (Fig. 3b).

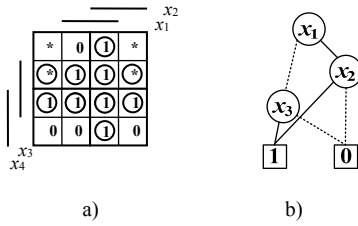


Fig. 3. a) K-maps of the functions for pole  $v_1$ ; b) ROBDD for  $f^* = f$

Extract functions  $f_v^0(1)$ ,  $f_v^1(1)$ ,  $f(1)$ ,  $f^*(1)$  for pole  $v_2$ . Represent the incompletely specified function with K-map in Fig. 4a. In this case the size of the ROBDD for function  $f^*(1)$  is less in comparison with the ROBDD for  $f(1)$  (Fig. 4b-c).

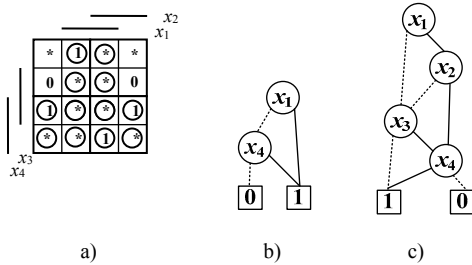


Fig. 4. a) K-maps of the functions for pole  $v_2$ ; b) ROBDD for  $f^*(1)$ ; c) ROBDD for  $f(1)$

Consider a multi output circuit  $C$ . If all paths of internal pole  $v$  are connected with the same output we have the situation has already been considered.

Let the paths of pole  $v$  be connected with the different outputs of circuit  $C$ :  $i_1, \dots, i_s$ . In this case we may obtain two ROBDDs for each incompletely specified Boolean function  $f_{inc}(i_j)$  corresponding to  $i_j$  output of circuit  $C$ ,  $i_j \in \{i_1, \dots, i_s\}$ . Its on-set is represented by the on-set of function  $f_v^0(i_j)$  and the off-set is represented by the on-set of function  $f_v^1(i_j)$ . These on-sets are represented by the proper ROBDDs derived from the single output sub-circuit with  $i_j$  output and considered pole  $v$  in above mentioned way.

Then we form ROBDD ( $f_v^0$ ) having executed the disjunction operation over ROBDDs representing functions  $f_v^0(i_1), \dots, f_v^0(i_s)$  and ROBDD ( $f_v^1$ ) having executed the disjunction operation over ROBDDs representing functions  $f_v^1(i_1), \dots, f_v^1(i_s)$ . At last, we derive ROBDD representing function  $f^*$  for pole  $v$ . The obtained ROBDD we may use for masking arbitrary fault of the gate with output pole  $v$ .

Illustrate this algorithm on two output circuit  $C$  from Fig. 2. Extract functions  $f_v^0(2)$ ,  $f_v^1(2)$  for pole  $v_2$  (functions  $f_v^0(1)$ ,  $f_v^1(1)$  has already been extracted above). Represent incompletely specified function for pole  $v_2$  and output  $F(2)$  with K-map in Fig. 5a. Fig. 5b shows incompletely specified function for pole  $v_2$  common for all

outputs of the circuit  $C$ ,  $f_v^1 = f_v^1(1) \vee f_v^1(2)$  (on-set),  $f_v^0 = f_v^0(1) \vee f_v^0(2)$  (off-set).

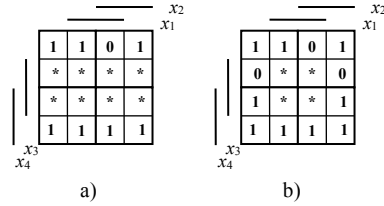


Fig. 5. a) K-map of the incompletely specified function for pole  $v_2$  and output  $F(2)$ ; b) K-map of the incompletely specified function common for all outputs which is presented by  $f_v^1$  and  $f_v^0$

In Fig. 6a K-map for function  $f^*$  is shown. For pole  $v_2$  common for all outputs function  $f^*$  coincides with  $f$ . The ROBDD of  $f^*$  has minimized number of nodes (Fig. 6b).

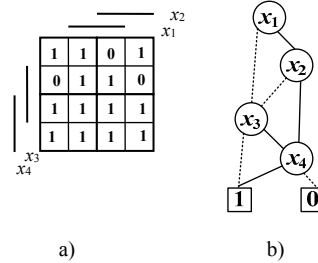


Fig. 6. a) K-map for  $f^*$ ; b) ROBDD for  $f^*$

In the end of this section consider some special cases for additional optimization.

Let one of the functions  $f_v^1$  or  $f_v^0$  be equal to 0. The function  $f_v^1 = 0$ . This situation is represented by the Venn diagram of Fig. 7a. This means that the function  $\varepsilon$  may be changed for the constant 1. As a result we may mask the considered gate fault by a connection of the proper MUX input with a power source.

The function  $f_v^0 = 0$ . This situation is represented by the Venn diagram of Fig. 7b. This means that the function  $\gamma$  may be changed for the constant 1. As a result we may mask the considered gate fault by a connection of the corresponding MUX input with a ground.

If  $f_v^1 = 0$  and  $f_v^0 = 0$  we have:  $\zeta(X, 1) = \zeta(X, 0)$  that is the variable  $v$  is unessential. In this case the fault gate does not change the function  $\phi(X)$ . There is no need to mask such fault.

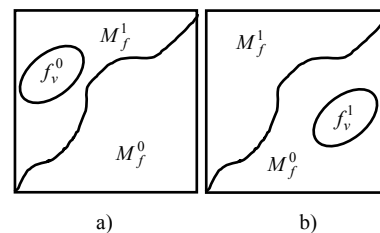


Fig. 7. Representation of the incompletely specified Boolean function for pole  $v$ : a)  $f_v^1 = 0$ ; b)  $f_v^0 = 0$

### III. MASKING FAULTS

ROBDD presentation of function  $f^*$  derived either for single or multi output combinational circuit  $C$  is covered by LUT based CLBs. In partly, covering one internal pole  $v$  of ROBDD we need one output LUT with three inputs.

Consider sub-circuit  $C_v^{**}$  of circuit  $C$  with output  $v$ . The sub-circuit inputs are either the closest to  $v$  branch points of circuit  $C$  or circuit  $C$  inputs. Let a fault gate with the output pole  $w$  belong to the sub-circuit and be not its branch-point. We also admit any logical fault of the gate with output pole  $w$ . Change the sub-circuit implementing function  $f$  corresponding to the pole  $v$  for the proper masking sub-circuit implementing function  $f^*$  in above mentioned way. As the sub-circuit with output pole  $w$  is a part of the sub-circuit with output pole  $v$  implementing function  $f$ , the fault gate with output pole  $w$  is also be masked. Note that there are no branch-points between poles  $v$  and  $w$ . This means that any fault of the gate with output pole  $w$  does not affect any gates beyond the path connecting  $v$  and  $w$ .

Thus masking the fault of the gate with output pole  $v$  we mask the fault of the gate with output pole  $w$  at the same time.

We suggest choosing internal poles  $v_1, \dots, v_r$  in circuit  $C$  so that their incompletely specified Boolean functions are weakly determined. Let the percentage of don't care values of the functions be not less threshold  $h$ . This means that faults of gates with outputs  $v_1, \dots, v_r$  are considered as hard detectable.

Note that each selected pole originates the sub-circuit  $C_v^{**}$ . If any of outputs  $v_1, \dots, v_r$  is the output of the gate of other sub-circuit of this kind, we exclude this pole from a consideration to cut the number of MUXs. As a result we get more short set of internal poles and call it  $v_1, \dots, v_r$ .

*Proposition 2. Any hard detectable fault of gate of circuit  $C$  may be masked with using the chosen set of poles  $v_1, \dots, v_r$ .*

Thus if a fault gate in circuit  $C$  is found, a developer decides either this fault may be masked by the CLB sub-circuit or circuit  $C$  must be redesigned. The decision depends on a complexity of the masking sub-circuit and its other characteristics.

We may consider several combinational (sequential) circuits and the proper array of reserved CLBs. For each circuit (combinational part of sequential circuit)  $C$  we find a set of internal nodes to include MUXs. Input poles of each circuit  $C$  are correlated with primary inputs (primary outputs) poles of CLBs array so that these poles of different circuits don't intersect. We may estimate maximal complexity of masking sub-circuit for each circuit  $C$  and total number of primary input (primary output) poles to choose the proper CLBs array.

The idea of this approach is represented in Fig. 8.

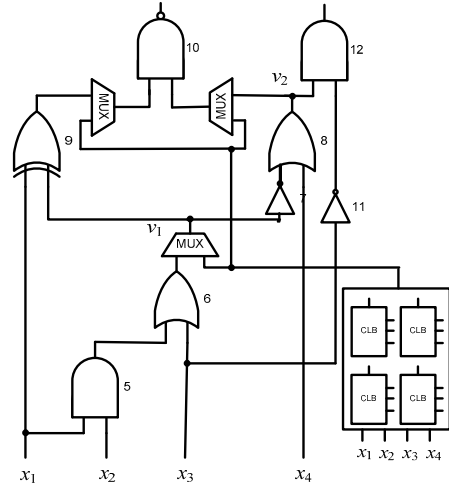


Fig. 8. Patching circuit design

### IV. EXPERIMENTAL RESULTS

We have used MCNC Benchmark circuits for experiments. The experimental results are shown in Table 1. Here is  $N_{in}$  – a number of inputs;  $N_{out}$  – a number of outputs;  $Avg\_ratio$  – an average characteristic of the incompleteness among of all functions corresponding to internal lines of the circuit, this value characterizes a possibility of a circuit simplification;  $H$  – some threshold;  $Pole$  – name of internal pole;  $Ratio$  – characteristic of the incompleteness of function corresponding to the chosen internal pole of the circuit;  $ROBDD_{f^*}$  – the size (the number of tree inputs LUTs) of the ROBDD for  $f^*$ ,  $f^*$  is the one of the best implementation of the incompletely specified Boolean function, the ROBDD for  $f^*$  was produced by using function `Cudd_bddMinimize` from CUDD package. A threshold choice in each case is individual. If ratio of incompleteness for pole  $v$  is higher than the threshold we consider the fault on pole  $v$  as hard detectable. Experimental results showed that ROBDDs representing function  $f^*$  for poles with don't care values not less the given threshold are rather simple.

### V. CONCLUSION

The original approach to masking arbitrary gate faults of combinational circuits based on inserting fault free sub-circuit through MUX in the proper points of the given combinational circuits (combinational part of sequential circuit)  $C$  is developed. The sub-circuit is derived by covering the corresponding ROBDDs by CLBs. The ROBDD represents one of the realizations of the incompletely specified Boolean function. The incompletely specified Boolean function corresponds to a chosen pole, in partly, pole correlated with hard detectable faults. When the hard detectable fault of a gate is detected (it may be any logical fault), the proper replacing sub-circuit from reserved CLBs is constructed. Its output is connected with the proper circuit  $C$  through the multiplexer which is the closest to the pole. Such approach may increase delays of the paths crossing this MUX and, consequently, decrease a circuit performance as a whole. It is possible to mask faults in several circuits, but not more one fault in each of them. If all circuits are found fault free the suggested approach in

TABLE I. EXPERIMENTAL RESULTS

Circuit	N in	N out	Avg ratio	H	Pole	Ratio	BDD f*
b9	41	21	0.0105516	0.15	r3	0.162735	1
comparator	8	3	0.643029	0.9	[11]	0.90625	1
					[12]	0.90625	1
					[17]	0.90625	1
C17	5	2	0.21875	0.3	19GAT(7)	0.375	3
cmb	16	4	0.867461	0.995	n0	0.997192	3
					o0	0.995132	4
					q0	0.996857	3
					r0	0.994904	4
					t0	0.973511	14
					u0	0.953003	18
cm163a	16	5	0.41778	0.7	l0	0.703125	2
cm162a	14	5	0.318848	0.5	l0	0.5625	3
					n0	0.5	2
x2	10	7	0.26875	0.34	j0	0.34375	2
cu	14	11	0.239665	0.3	a1	0.328125	17
					f1	0.333984	9
					g1	0.338867	7
					j1	0.328125	3
pcler8	27	17	0.490513	0.496	a2	0.496094	3
					d2	0.498047	3
					f2	0.498047	2
					g2	0.496094	4
9symml	9	1	0.91865	0.985	25	0.988281	4
					28	0.988281	3
					31	0.986328	4
					32	0.986328	4
					35	0.986328	3

comparison with [7-9] does not decrease performance of the circuits.

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