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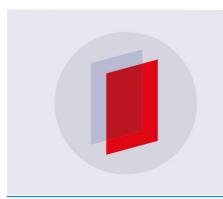


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### Polarisation control for optical nanofibres by imaging through a single lens

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#### Abstract

We present a simple method for controlling the polarisation state of light at the waist of a singlemode optical nanofibre. The method consists of complete polarisation compensation based on imaging scattered light from inherent inhomogeneities both on the fibre surface and in the glass material itself. In contrast to the recently reported protocol exploiting two imaging systems oriented at 45° to each other, our method requires only one lens and a video camera. It is particularly useful for nanofibre-based applications with severe geometric constraints, such as inside vacuum chambers for experiments with cold atoms. The measured fidelity of the achieved control is about 98% using lenses with moderate numerical apertures.

Keywords: nanofibre, polarisation control, scattering

(Some figures may appear in colour only in the online journal)

#### 1. Introduction

Single-mode optical nanofibres are heavily used in various experiments and applications across classical and quantum optics, atomic physics, and photonics [1-3]. In many cases, it is important to know the polarisation of the guided-mode at the ultrathin waist region. Until very recently, there was no way of measuring or controlling the polarisation at the waist, except for the trivial cases of horizontal or vertical states, which are identifiable by scattering imaging [4-6]. It was impossible to reliably set circularly polarised states, let alone arbitrary elliptically polarised ones, at the nanofibre waist.

Solving this issue, we have recently developed a reliable method for complete control of the polarisation state at the waist of a single-mode nanofibre [7]. The method relies on the fact that, in adiabatically tapered fibres, polarisation transformations are restricted to 3D rotations of the Poincaré sphere,  $\mathcal{P}$ . Then, by placing a free-space polarisation compensator (PC) before the fibre, one can reverse any unknown transformation, thereby achieving equality between an arbitrary input state,  $s_{in}$ , and the state at the nanofibre waist,  $s_w$ (see figure 1(a), where the (x, y, z) frame originates at the waist centre and the input beam propagates towards z > 0).

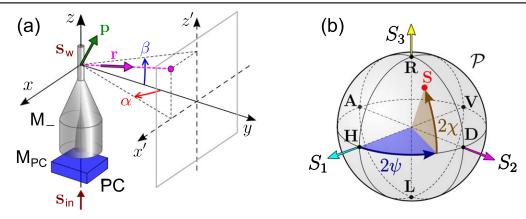
Light in a completely polarised state is characterised by a Stokes vector  $\mathbf{s} = (1, S_1, S_2, S_3) = (1, \cos 2\psi \cos 2\chi)$  $\sin 2\psi \cos 2\chi$ ,  $\sin 2\chi$ ), which can be represented on  $\mathcal{P}$  as a point, **S**, with angular coordinates  $2\psi$  and  $2\chi$ , see figure 1(b). Using the Stokes-Mueller formalism [8], the polarisation compensation results in

$$\mathbf{s}_{\rm w} = M_- M_{\rm PC} \, \mathbf{s}_{\rm in} = \mathbf{s}_{\rm in},\tag{1}$$

where  $M_{\rm PC}$  and  $M_{-}$  are the 4  $\times$  4 real-valued Mueller matrices of the compensator and the down-taper fibre section before the waist, respectively.

The key to our method is to sequentially map two different states from the input to the waist. Importantly, they must be non-orthogonal, i.e. they must not form an angle of  $m\pi$  (where *m* is an integer) on  $\mathcal{P}$ . In our previous work [7], this was realised by monitoring the directional coupling of light into a probe nanofibre crossed at right angles to the sample nanofibre. The coupling allowed us to identify the H (or V) state and another one, close to R (or L). Joos et al recently achieved polarisation control with a comparable

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**Figure 1.** (a) Light escaping from a single-mode nanofibre due to scattering on a point-like inhomogeneity can be defined by the dipole momentum, p, which depends on the local polarisation state,  $\mathbf{s}_{w}$ . (b) We describe a polarisation state as a point **S** on the Poincaré sphere,  $\mathcal{P}$ .

precision, using a different pair of non-orthogonal states: **H** and **D** [9]. These states were identified by monitoring the inhomogeneity-induced scattering from a nanofibre using two imaging systems oriented at  $45^{\circ}$  with respect to each other. This approach has an important benefit of being contactless, but its implementation in real experiments with nanofibres may be difficult. In this paper, we report on what may be the simplest realisation of complete polarisation control for single-mode nanofibres, namely, via scattering imaging through a single lens.

#### 2. Methods

We assume that the scattering originates from point-like dipolar sources randomly distributed both on the surface and in the bulk of the nanofibre. They are naturally present in optical nanofibres and probably represent nanoscale surface imperfections [10] and bulk material inhomogeneities which do not alter polarisation of the guided light. As we previously found when using a probe nanofibre, the polarisation state,  $s_w$ , is maintained throughout the whole waist region [7].

Let us consider a source located at the coordinate origin and having an electric dipole moment, **p**. The time-averaged intensity, dP, radiated into a small solid angle along a radius vector  $\mathbf{r} = (\sin \alpha \cos \beta, \cos \alpha \cos \beta, \sin \beta)$  (with  $\alpha$  and  $\beta$ being angular coordinates in the (x, y) and (y, z) planes, as defined in figure 1(a)) can be expressed as [11]:

$$dP \propto |(\mathbf{r} \times \mathbf{p}) \times \mathbf{r}|^2.$$
 (2)

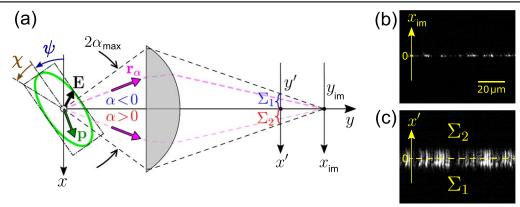
Unlike free-space beams, guided modes in optical nanofibres may have a significant component of the electric field, *E*, along the *z* axis [12]. This component, corresponding to  $\beta \neq 0$ , reduces the brightness difference between scattering images for **H** and **V** states [6]. Fortunately, this effect can be eliminated by a linear polariser with its axis oriented parallel to *x*. In this study, we place such a polariser in front of the imaging camera, thereby limiting the detectable scattering to  $\beta = 0$ . The considered dipole momenta are restricted to the (*x*, *y*) plane and are linked to the polarisation state as follows:

$$\mathbf{p}(\psi, \chi) \propto \sqrt{1 + \cos 2\psi} \cos 2\chi \ \mathbf{e}_x + \frac{\sin 2\psi \cos 2\chi + i \sin 2\chi}{\sqrt{1 + \cos 2\psi} \cos 2\chi} \ \mathbf{e}_y, \tag{3}$$

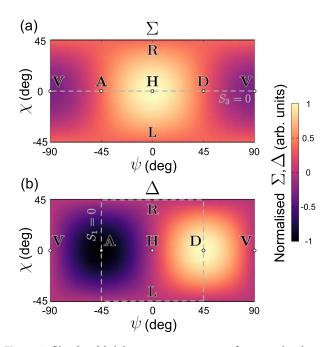
where  $\mathbf{e}_y$  and  $\mathbf{e}_y$  are unit vectors along *x* and *y*, respectively. In earlier work [9], the **H** and **D** polarisations were identified by monitoring the scattering intensities at  $\alpha_{\rm H} = 0$  and  $\alpha_{\rm D} = 45^{\circ}$ , using two imaging systems at these angles. In fact, the same approach was reported earlier in the context of few-mode ultrathin fibres [13]. In contrast, in the work reported herein, we demonstrate that the angular dependence of *dP* can be resolved simply by collecting scattered light along various  $\mathbf{r}_{\alpha}$  with a convex lens, as sketched in figure 2(a), where the polarisation state corresponds to the ellipse drawn by the tip of the electric field vector in the (*x*, *y*) plane.

A subwavelength nanofibre waist appears in a diffractionlimited sharp image (at  $y = y_{im}$ ) as a line of Airy discs, see figure 2(b), where hardly any difference in brightness for  $x_{im} < 0$  and  $x_{im} > 0$  is noticeable when the polarisation varies. In contrast, a blurred image captured in the (x', y') plane (figure 2(c)) shows clearly different brightness sums,  $\Sigma_1$  and  $\Sigma_2$  (corresponding to x' < 0 and x' > 0), for certain polarisation states. The sums can be found by integration of equation (2) (with **p** taken from equation (3)) over the relevant angular range:  $-\alpha_{max} < \alpha < 0$  for  $\Sigma_1$  and  $0 < \alpha < \alpha_{max}$  for  $\Sigma_2$ , where  $\alpha_{max}$  is the maximal half-angle of the cone of light that can enter the lens.

Figure 3 shows the simulation results for  $\Sigma = \Sigma_1 + \Sigma_2$ and  $\Delta = \Sigma_1 - \Sigma_2$ , normalised by their maxima ( $\alpha_{max} = 30^\circ$ was set). As one can see,  $\Sigma$  has the global maximum (minimum) at horizontal (vertical) polarisation, consistent with earlier studies [5, 6, 9]. In turn,  $\Delta$  has the global maximum (minimum) at a diagonal (antidiagonal) linear polarisation, oriented at +45° (-45°) with respect to x. It is worth mentioning that around the **R** and **L** states, the spin–orbit coupling in the dipole emission is expected to produce small shifts of the apparent position of the emitter [14]. However, these shifts do not exceed  $\lambda/(2\pi)$  (with  $\lambda$  being the wavelength), and thus are not resolvable in our experimental setup. In addition, the polarisation around the extrema of  $\Sigma$  and  $\Delta$  is



**Figure 2.** (a) In the (x, y) plane, the power radiated along  $\mathbf{r}_{\alpha} = \mathbf{r}(\alpha, 0)$  depends on the polarisation state,  $\mathbf{s}_{w}$ . A convex lens collects scattered light within an angular range  $|\alpha| < \alpha_{max}$ , and allows one to estimate the power difference for  $\alpha > 0$  and  $\alpha < 0$ . For this purpose, the net power,  $\Sigma_1$  and  $\Sigma_2$ , with x' < 0 and x' > 0, respectively, should be measured. (b), (c) For a point source,  $\Sigma_1$  and  $\Sigma_2$  cannot be distinguished in the sharp image (b) located at  $y = y_{im}$ . Therefore, the blurred image (c) in the (x', y') plane should be considered.

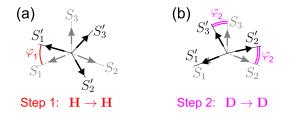


**Figure 3.** Simulated brightness measurements of a scattering image for polarisation states covering the whole  $\mathcal{P}$  sphere. (a) The summation signal,  $\Sigma = \Sigma_1 + \Sigma_2$ . (b) The difference signal,  $\Delta = \Sigma_1 - \Sigma_2$  (b).

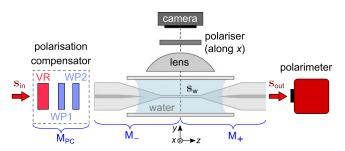
close to linear, in which case the spin-orbit coupling is negligible.

Based on the simulation results, we perform the polarisation compensation in two steps:

- (i) Tilting the S<sub>1</sub>' axis of the rotated sphere, P', by an angle φ<sub>1</sub> (figure 4(a)). This is achieved by setting s<sub>in</sub> = H and locating the maximum of Σ (corresponding to s<sub>w</sub> = H) while allowing s<sub>w</sub> to move freely on P' by means of a pair of waveplates, WP1 and WP2 in figure 5.
- (ii) Rolling of the  $S'_2$  and  $S'_3$  axes about  $S'_1 = S_1$  by an angle  $\varphi_2$  (figure 4(b)). For this purpose, we set  $\mathbf{s}_{in} = \mathbf{D}$  and locate the maximum of  $\Delta$  (corresponding to  $\mathbf{s}_w = \mathbf{D}$ ) by adjusting the retardance of a variable retarder, VR, having its optical axis parallel to *x*. Under this condition,



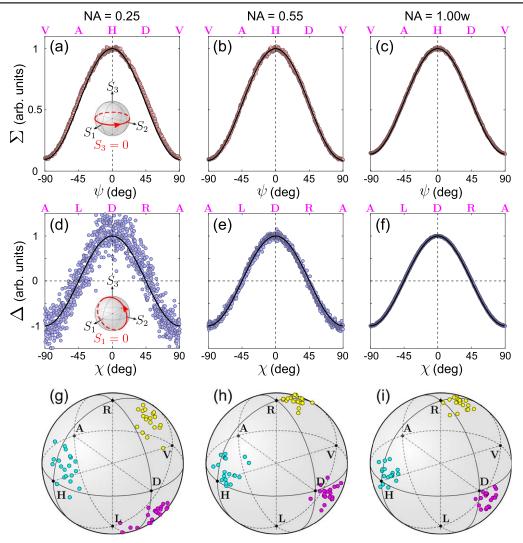
**Figure 4.** Polarisation compensation consists of two steps: (a) mapping  $\mathbf{H} \to \mathbf{H}$  to the nanofibre waist by rotating WP1 and WP2 in order to find the maximum of  $\Sigma$ ; (b) mapping  $\mathbf{D} \to \mathbf{D}$  by adjusting the retardance of VR to find the maximum of  $\Delta$ .



**Figure 5.** The optical setup showing the imaging system and the three-element compensator. Using a two-step compensation procedure based on a scattering image, we achieve  $M_{\rm PC} = M_{-}^{-1}$ , and thus  $\mathbf{s}_{\rm w} = \mathbf{s}_{\rm in}$  for any input polarisation.

 $\mathbf{s}_{w}$  is restricted to the circular trajectory in the  $S_{1} = 0$  plane. In the unwrapped  $\Delta(\psi, \chi)$  map shown in figure 3(b), this trajectory appears as the dashed square.

Our experimental setup is illustrated in figure 5. The nanofibre is produced by controlled heating and pulling [15] of a commercial single-mode step-index glass fibre (Thorlabs SM980G80, cut-off vacuum wavelength  $0.92 \pm 0.05 \mu$ m). The cylindrical waist region, of radius  $a = 0.33 \pm 0.04 \mu$ m, is connected to taper regions having conical profiles with a half-apex angle of 3 mrad. Such a small angle provides adiabatic coupling between the weakly guided modes of the untapered fibre and the strongly guided ones of the waist [16, 17]. We verified the adiabaticity by checking that the



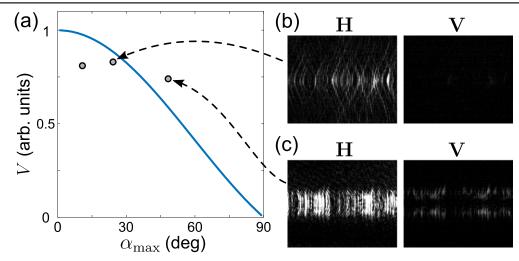
**Figure 6.** (a)–(c) Normalised summation scattering signal,  $\Sigma$ , measured with lenses of different NA, versus  $\psi$ . Inset in (a): the probed circular trajectory on  $\mathcal{P}$ , corresponding to the dashed line in figure 3(a). Solid lines: fit to the simulated  $\Sigma(\psi, 0)$ , with adjustable  $\alpha_{max}$ . (d)–(f) Normalised difference signal,  $\Delta$ , versus  $\chi$ . Inset: the probed circle on  $\mathcal{P}$ , corresponding to the dashed line in figure 3(b). Solid lines: simulated  $\Delta(\pm \pi/4, \chi)$ . All data shown in (a)–(f) were collected after the polarisation compensation. (g)–(i) Statistics of the polarisation control assessed by measuring  $\mathbf{s}_{out}$  for  $\mathbf{s}_{in}$  equal to  $\mathbf{H}$ ,  $\mathbf{D}$ , or  $\mathbf{R}$  (cyan, magenta, and yellow markers, respectively).

fibre maintains at least 97% transmission at the working vacuum wavelength of  $\lambda = 1.064 \,\mu\text{m}$  throughout the pulling process. The fibre was coupled to a collimated Gaussian laser beam (Ventus, Laser Quantum Ltd.) with an optical power not exceeding 10 mW.

The above two-step polarisation compensation procedure is performed by means of PC, which consists of a pair of quarter-wave plates (WP1 and WP2) and a variable retarder (VR, liquid crystal type, Thorlabs, LCC1111-C). To assess *precision* of the polarisation control, we record the output state,  $\mathbf{s}_{out} = M_+ \mathbf{s}_w$ , by a free-space polarimeter (Thorlabs, PAX1000IR). The transformation matrix,  $M_-$ , is varied by stressing the input pigtail of the tapered fibre with a threepaddle fibre polarisation controller (FPC, not shown).

In order to protect a newly fabricated nanofibre from dust, the waist and taper regions were immersed in a drop of deionized water sandwiched between two parallel glass slides.

Under these conditions, we assume that scattering occurs only on point-like, randomly distributed inherent surface or bulk inhomogeneities of the fibre [6, 9]. The imaging system, pointed towards y < 0, comprises a lens, a video camera (Thorlabs, DCC1545M, interfaced with a computer through LabVIEW), and a linear polariser (having its axis parallel to x), added in order to maximise the visibility parameter,  $V = (\Sigma_{\text{max}} - \Sigma_{\text{min}})/(\Sigma_{\text{max}} + \Sigma_{\text{min}})$ . We used microscope objective lenses with different numerical apertures (NA): 0.25 (Olympus PlanN, 10× magnification), 0.55 (Zeiss LD EC Epiplan-Neofluar,  $50 \times$ ), and 1.00w (water immersion, Zeiss Plan-Apochromat,  $63 \times$ ). Depending on the lens, neutral filters with attenuations of 10-20 dB were placed in front of the camera sensor, to prevent it from saturation. For each of the three tested lenses, we first obtain a sharp image of the nanofibre waist, and then shift the sample towards the camera (y > 0) by a few percent of the objective's working distance.



**Figure 7.** (a) Visibility parameter as a function of  $\alpha_{max}$ . Solid line: simulation; markers: experiment (from table 1). (b), (c) Scattering images for the **H** and **V** states corresponding to the extrema of  $\Sigma$ .

**Table 1.** Statistics for the polarisation control with objective lenses of various NA. For each cloud of points on the Poincaré sphere, we obtained the angular spread,  $\hat{\varphi}$  (average deviation from the central point), and the fidelity, *F* (cosine of  $\hat{\varphi}$ ).

		Н		D		R		
NA	$\alpha_{\max}$	$\hat{\varphi}$	F	$\hat{\varphi}$	F	$\hat{\varphi}$	F	V
0.25	10.8°	15.2°	0.97	20.7°	0.94	10.0°	0.98	0.81
0.55	24.2°	11.4°	0.98	$7.8^{\circ}$	0.99	5.1°	0.98	0.83
1.00w	48.3°	7.7°	0.99	11.5°	0.98	11.3°	0.98	0.74

#### 3. Experimental results

Figure 6 summarises the experimental results of this work. After performing the two-step compensation procedure (figure 4), we tested the simulation results for input polarisation states,  $\mathbf{s}_{in}$ , following the circular trajectories at the intersections between  $\mathcal{P}$  and the plane  $S_3 = 0$  (figures 6(a)–(c)) or  $S_1 = 0$  (figures 6(d)–(f)). These cases correspond to tilted linear ( $-\pi/2 < \psi < \pi/2$ ,  $\chi = 0$ ) and elliptical ( $\psi = \pm \pi/4$ ,  $-\pi/2 < \chi < \pi/2$ ) polarisations, with the principal states being labelled above the plots.

As evident from figures 6(a)–(c),  $\Sigma$  is virtually independent of NA. By contrast, the noise level in  $\Delta$  is very sensitive to NA: the standard deviation of  $\Delta(\chi)$  from the model (solid lines in figures 6(d)–(f)), is approximately proportional to  $\alpha_{\text{max}}^{-1}$ . Interestingly,  $\mathbf{D} \rightarrow \mathbf{D}$  mapping is feasible even with a lens having  $\alpha_{\text{max}}$  much smaller than 45°, which was the angle between the two imaging directions in earlier studies [9, 13].

The statistics of the polarisation control is shown in figures 6(g)-(i) and summarised in table 1. For each lens, we performed the polarisation compensation at 20 random settings of the FPC and measured the output polarisation states,  $\mathbf{s}_{out}$ , with the input set at  $\mathbf{H}$ ,  $\mathbf{D}$ , or  $\mathbf{R}$ . The obtained clouds of points for  $\mathbf{H}$  are shifted from the input state by about 10° on average. This shift appears due to the uncompensated transformation described by the matrix  $M_+$  which was constant

throughout the measurements. The other two principal states, **D** and **R**, also exhibit a similar shift, which is larger for NA = 0.25 due to the corresponding higher noise in  $\Delta(\chi)$ .

The measured visibility parameter, V (see table 1), is roughly consistent with the simulations reported in [9]. In our case, the linear density of scatterers on the nanofibre waist is about 0.8  $\mu$ m<sup>-1</sup> (as measured with the NA = 1.00w lens). This corresponds to a linear density of 1.23 per unit of optical resolution taken as  $1.22\lambda/(2n \sin \alpha_{max}) = 0.65 \mu$ m, where *n* is the refractive index of the medium (1.34 for water). According to our simulations, visibility decreases with  $\alpha_{max}$ , see figure 7. Indeed, a lens with high NA would capture some light from the sides of the radiation pattern even if the dipole moment were perpendicular to the axis of the imaging system (i.e.  $s_w = V$ ). In order to artificially increase V for the  $H \rightarrow H$  mapping step, one can crop the camera image to the paraxial region, effectively reducing  $\alpha_{max}$ .

#### 4. Discussion

We quantitatively estimate the precision by the measured angular spread,  $\hat{\varphi}$  (average deviation from the central point in a cloud), and the corresponding fidelities,  $F = \cos \hat{\varphi}$ , see table 1. These angular spreads are a few times larger than those obtained with the polarisation control using two crossed nanofibres [7]. Yet, the scattering-based compensation performed with higher NA lenses provides a minimum fidelity of 98% (the maximum  $\hat{\varphi}$  of 11°), which is sufficiently high for many polarisation-sensitive applications. It is worth noting that the measured angular deviations on the Poincaré sphere are expressed in terms of  $2\psi$  and  $2\chi$ , and, therefore, the corresponding angular deviations of the polarisation ellipse would be half the size. Consequently, our compensation method has about two times smaller errors with respect to the previous study [9], which employed two imaging systems for scattering detection.

This improvement can be attributed to the fact that optical elements in our PC have a fixed angle (close to 90°) with respect to the beam axis, *z*. By contrast, operation of the Berek compensator applied in [9] involves tilting the optical axis to *z*. This leads to substantial lateral displacements of the beam (e.g. up to 150  $\mu$ m for the model 5540 from Newport), and, consequently, affects its coupling to the fibre pigtail. As a result, the optical power in the nanofibre depends on the compensator setting. Since the Berek plate is introduced after the  $\mathbf{H} \rightarrow \mathbf{H}$  step, only the  $\mathbf{D} \rightarrow \mathbf{D}$  mapping is affected by variability of coupling efficiency. Still, this may result in a systematic error and diminish the overall *accuracy* of the polarisation control.

In fact, our three-element PC can be further improved. The pair of quarter-wave plates (WP1, WP2) applied for  $\mathbf{H} \rightarrow \mathbf{H}$  mapping could be replaced with any set of polarisation optics covering the whole Poincaré sphere. For instance, a three-paddle FPC from Thorlabs or a single-paddle type from KS Photonics are good alternatives, as they provide smoother trajectories on the sphere and faster convergence to  $\mathbf{H}$ . For the quickest and most precise mapping, one should consider automatic devices such as the thermal electronic inline FPC from Phoenix Photonics. In the second step of the compensation, the precision and speed could be enhanced by switching to an automatic scan of the VR retardance, which goal can be readily achieved with an electro-optic modulator interfaced with a computer.

A direct application of the reported method will be in experiments where a single-mode optical nanofibre is integrated into an ensemble of cold atoms in ultrahigh vacuum. Implementation of the method is straightforward: the video camera in the imaging system (commonly used for alignment and characterisation of magneto-optical traps) should be equipped with a linear polariser (as in figure 5) and moved slightly closer to the lens in order to achieve a blurred image of the nanofibre, then the two-step compensation procedure can be realised by adjusting a PC and monitoring the summation and difference signals from the camera. In ultrahigh vacuum systems, imaging arms typically have NA < 0.3 [18] corresponding to  $\alpha_{\rm max} \approx 17^{\circ}$ . According to our experimental results (table 1), even such a modest numerical aperture is expected to provide polarisation control with 95%-98% fidelity. It could be further improved by using short-focus aspheric lenses, which easily reach NA = 0.5 although one must consider field-of-view constraints for imaging of the atom cloud.

#### 5. Conclusion

We have realised complete polarisation control for guided light at the waist of a single-mode optical nanofibre by imaging of scattered light from inherent surface and bulk inhomogeneities of the fibre. We split the image into two parts bordered by the fibre axis and monitor the sum and difference of the net brightness in these parts. This allows us to perform the previously developed two-step polarisation compensation procedure, in a contactless manner, using a simple imaging system comprising a convex lens and a video camera. As a result of the compensation, an arbitrary polarisation state translates from free-space to the nanofibre waist without any change. Our numerical simulations are supported by experimental results obtained for a cylindrical nanofibre waist immersed in water for protection from dust. Statistical studies revealed that lenses with higher NA provide higher fidelities (equivalently, smaller errors) of the polarisation control. We expect the reported method to be particularly useful for atomnanofibre hybrid systems where the polarisation of light at the fibre waist is critical. For instance, our method could be applied in novel atom trapping schemes [19, 20], and for demonstrations of chiral optical forces [21] and quadrupole transitions in atomic ensembles [22].

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