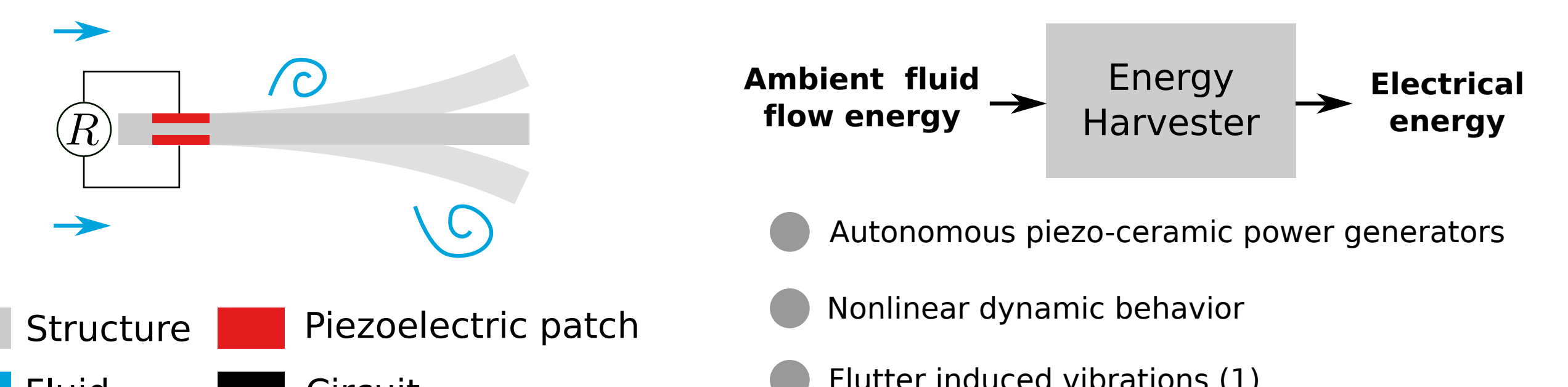


Toward fluid-structure-piezoelectric simulations applied to flow-induced energy harvesters

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1 Flow Induced Energy Harvesting

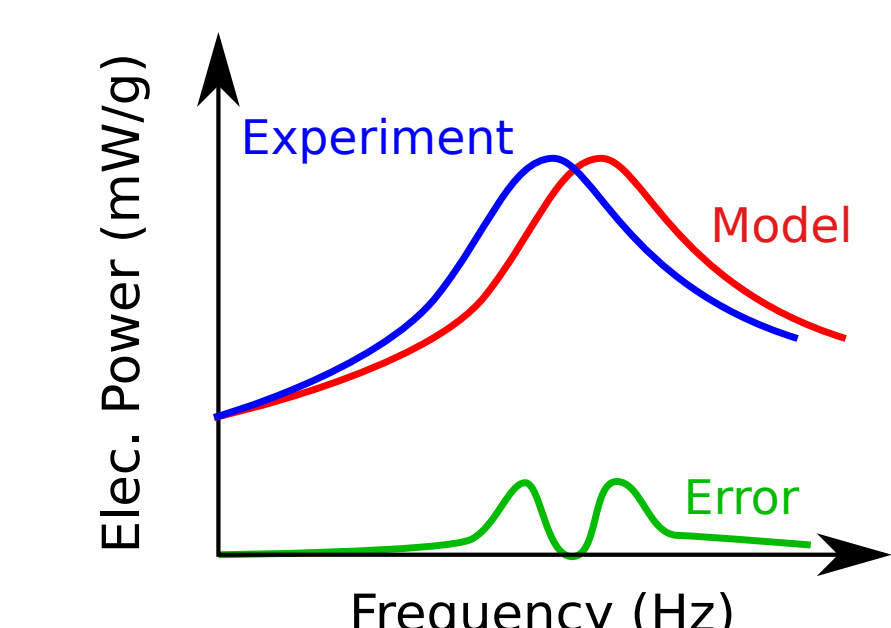


Ambient fluid flow energy → Energy Harvester → Electrical energy

- Autonomous piezo-ceramic power generators
- Nonlinear dynamic behavior
- Flutter induced vibrations (1)

■ Structure ■ Piezoelectric patch
■ Fluid ■ Circuit

2 Research objectives



Maximize the power output
Minimize the fatigue exposure

- Model and predict the nonlinear dynamic behavior (2)
- Quantify the sensibility under changing conditions
- Allow just-in-time feedback : construct on-line approximations

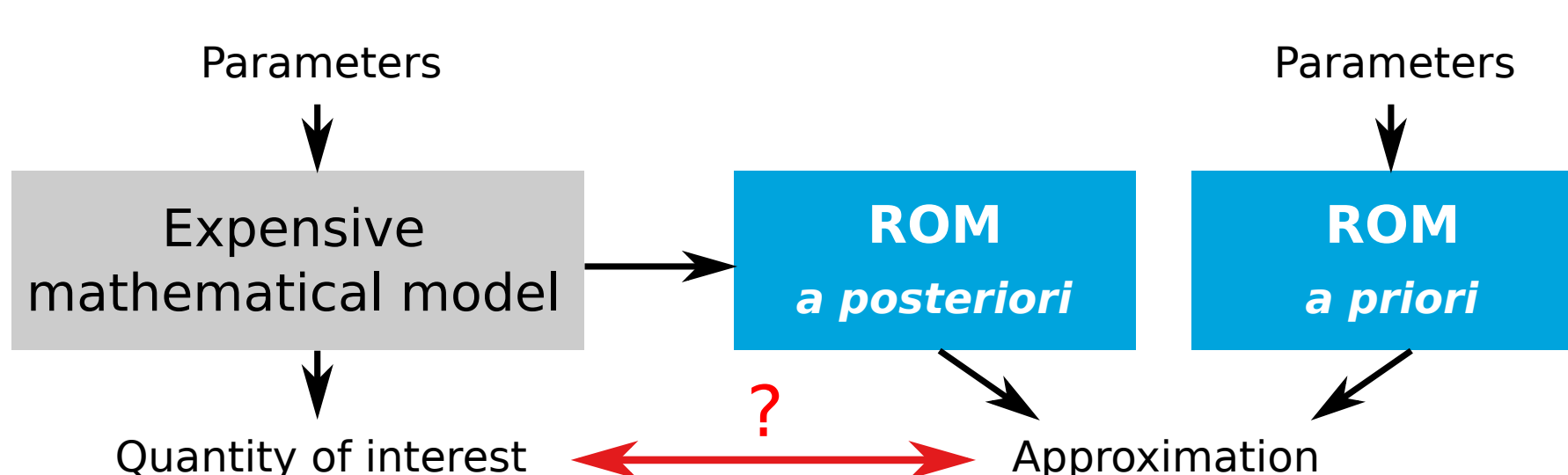
3 Problems

- Complex multiphysics phenomena
- Numerous fields (displacement, velocity, pressure, intensity ...)
- Increasing number of parameters
- Nonlinear behaviors (geometrical nonlinearity, fluid dynamic)

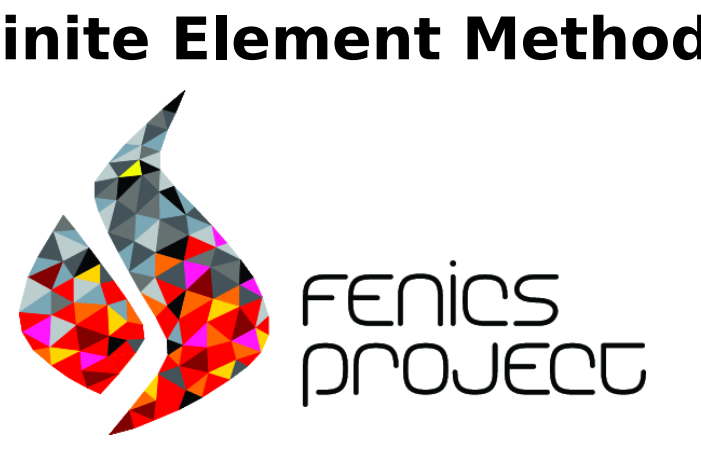
?

Can we construct a Reduced Order Model to approximate a nonlinear multiphysics problem ?

4 Methodology



Numerical tool (3)
Finite Element Method



5 High fidelity model+FEniCS

Fluid

Incompressible
Newtonian
Homogeneous
Isotropic
Low Reynolds number
Moving mesh

Structure

Elastic
Homogeneous
Isotropic
Finite strain

Piezo + circuit

Linear electromechanica
Resistor circuit

Example : Steady-Navier Stokes - 2D Lid driven cavity

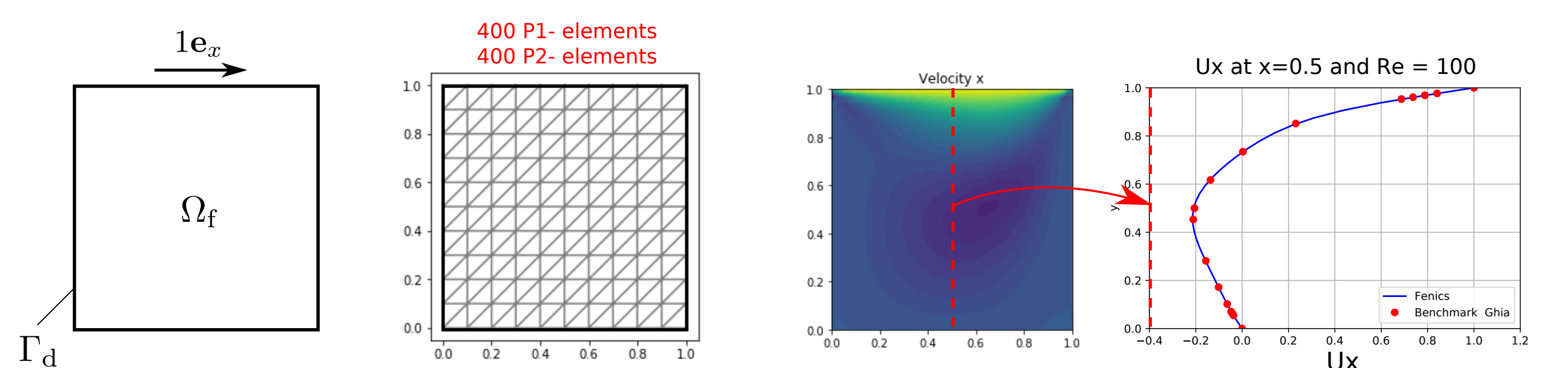
- Strong form (velocity - pressure)
- Weak form (velocity - pressure)

$$\nabla \cdot \mathbf{v} = 0 \text{ in } \Omega_f$$

$$\mathbf{v} \cdot \nabla \mathbf{v} + \nabla p - \frac{1}{\text{Re}} \nabla^2 \mathbf{v} = \mathbf{0} \text{ in } \Omega_f$$

$$\mathbf{v} = \mathbf{v}_d \text{ on } \Gamma_d$$

$$c(\mathbf{v}, \mathbf{v}, \delta \mathbf{v}) - b(p, \delta \mathbf{v}) + \frac{1}{\text{Re}} a(\mathbf{v}, \delta \mathbf{v}) = 0 \forall \delta \mathbf{v}$$

$$b(\mathbf{v}, \delta p) = 0 \forall \delta p$$


6 Reduced Order Modelling

A priori approaches

Proper Generalized Decomposition (5)

Example : Steady Navier-Stokes

- Series of separated functions variables products

$$\mathbf{v}(\mathbf{X}, \text{Re}) \simeq \sum_{i=1}^N \Lambda_i(\mathbf{X}) \lambda_i(\text{Re}) + \mathbf{v}^*$$

Satisfy Dirichlet BC

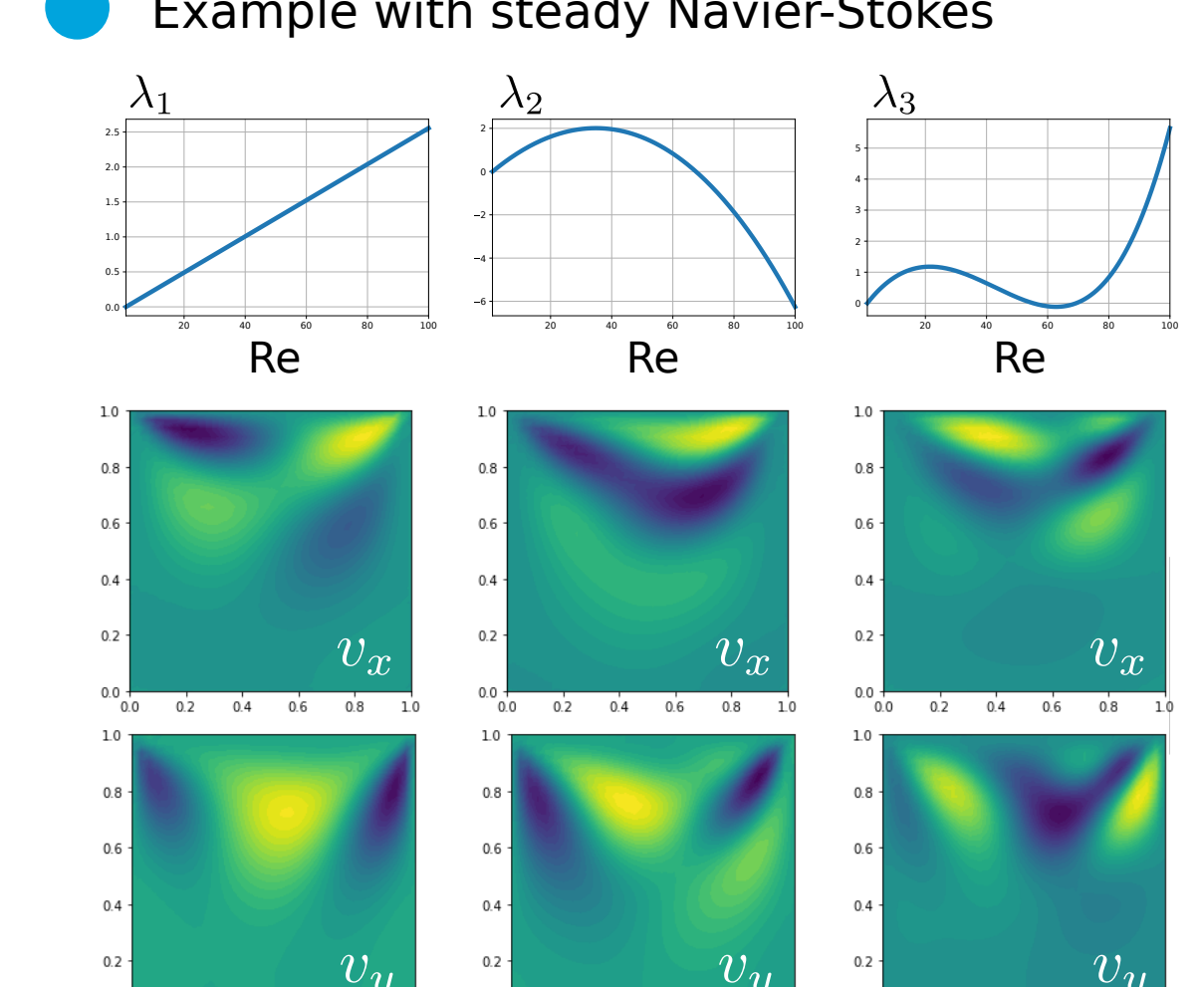
$$p(\mathbf{X}, \text{Re}) \simeq \sum_{i=1}^N \theta_i(\mathbf{X}) \lambda_i(\text{Re})$$

- For each i-th modes : Greedy Algorithm (GA)

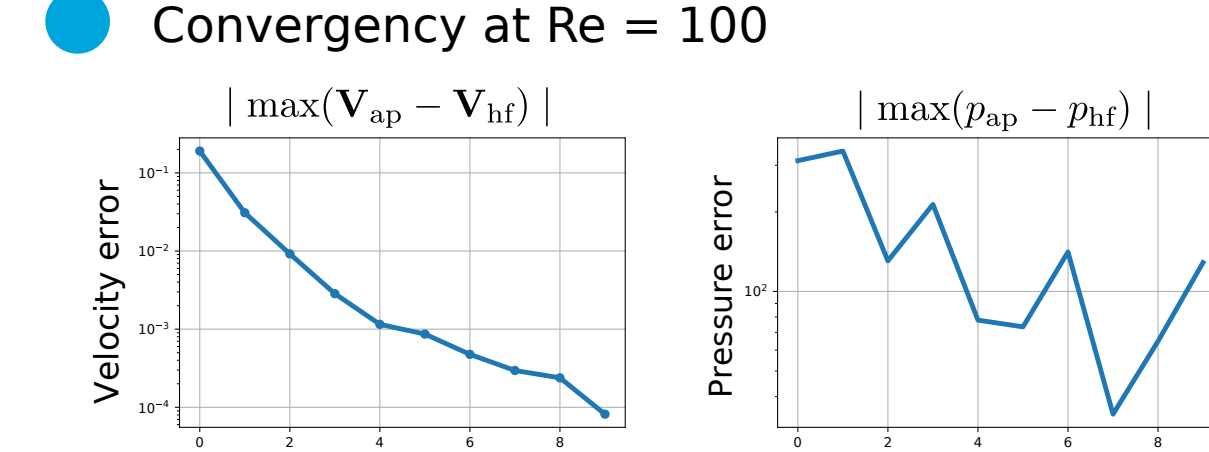
Spatial problem
 (Λ_i, θ_i)

Parametric problem
 λ_i

Example with steady Navier-Stokes



- Convergency at Re = 100



Modal Basis (6)

Example : Linearized hydroelasticity

Incompressible
Potential flow
Homogeneous
Isotropic

Elastic
Homogeneous
Isotropic
Linearized

- In vacuo eigenvalue problem

$$\mathbf{K}\mathbf{U} + \mathbf{M}\ddot{\mathbf{U}} = \mathbf{0}$$

- Induced fluid load approximation

$$\mathbf{K}\mathbf{U} + \mathbf{M}\ddot{\mathbf{U}} = \mathbf{f}$$

$$\mathbf{f} = \sum_{i=1}^N \underbrace{\mathbf{f}_k(\mathbf{U})}_{\text{displacement}} + \underbrace{\mathbf{f}_d(\dot{\mathbf{U}})}_{\text{velocity}} + \underbrace{\mathbf{f}_a(\ddot{\mathbf{U}})}_{\text{acceleration}}$$

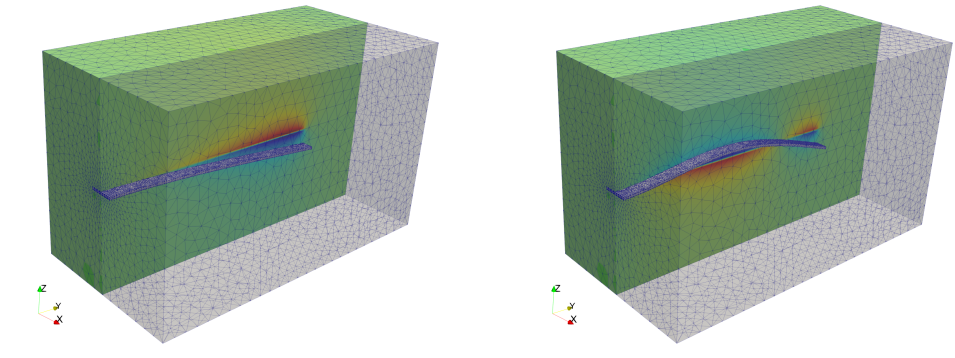
added stiffness added damping added mass

- Reduced problem with reduced added operators

$$\mathbf{U} \simeq \sum_{i=1}^N \kappa_i \mathbf{U}_i$$

$$\mathbf{K}_{fs} \kappa + \mathbf{D}_{fs} \dot{\kappa} + \mathbf{M}_{fs} \ddot{\kappa} = \mathbf{0}$$

- Example with hydroelasticity (beam in water)



f1 = 185 Hz f2 = 1163 Hz
 f1a = 95 Hz f2a = 605 Hz

Discussions

- Appropriate method / weakly nonlinear problems
- Subjected to the curse of dimensionality
- Tests with moving meshes on-going

Discussions

- Overcome the curse of dimensionality
- No convergency of the pressure for now
- Tests with time intergration on-going

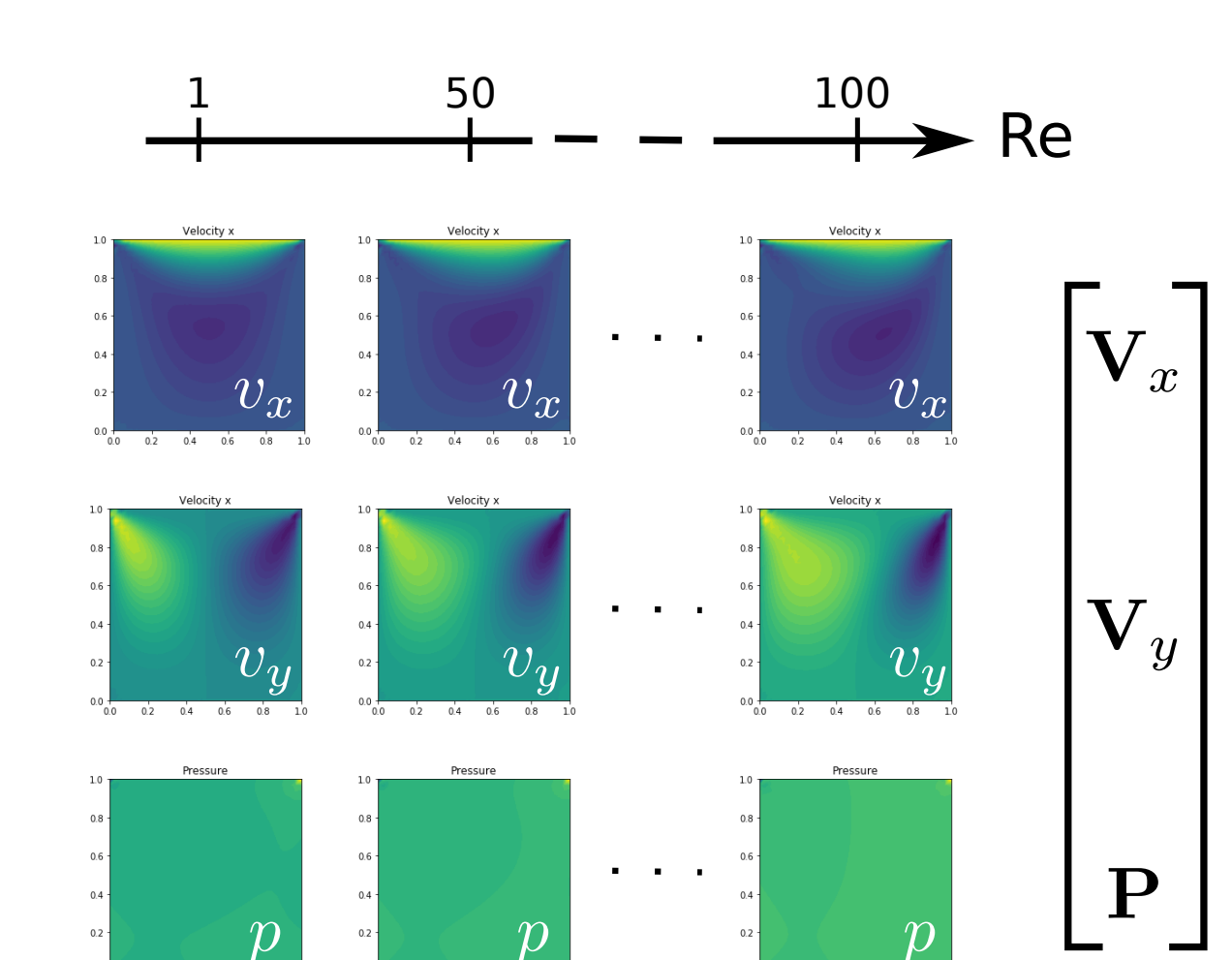
Discussions

- Give valuable physical information
- Necessitates restriction of hypotheses
- Linearization around flow on-going

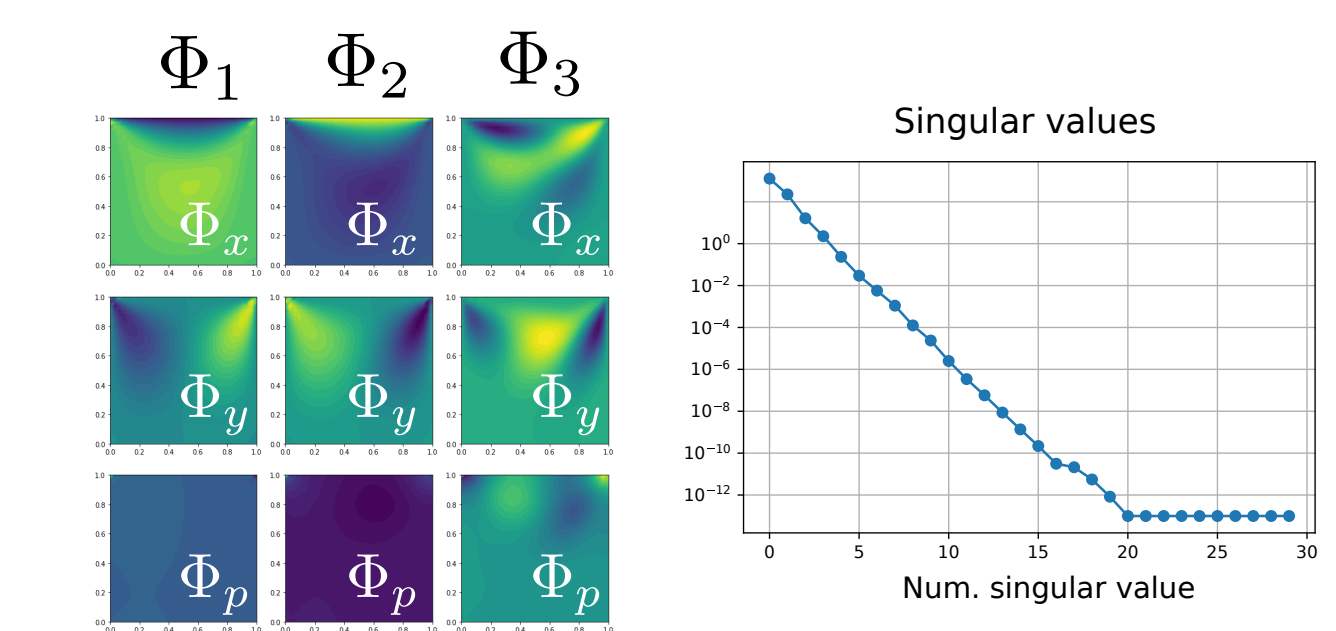
A posteriori approaches (ex: Steady Navier-Stokes)

Snapshots (velocity - pressure)

1 50 100 → Re



Proper Orthogonal Decomposition (4)



7 Conclusion - Work in Progress

Work done

- Learn and use FEniCS
- Solve Navier-Stokes problems
- Linearized hydroelasticity
- A posteriori reduction : POD
- A priori reduction : PGD

Work in progress

- Fluid - Time integration
- Fluid - Structure : ALE formulation
- Fluid - Structure : Aeroelasticity
- Structure : Velocity formulation
- Comparison between POD-PGD-MB

Outlook

- Add piezoelectricity equations
- Investigate structural models (beam - plates)
- Design an experimental set-up (7)
- Generate a data-base of F-S-P simulations
- Machin Learning

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