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# The effects of intraspecific density-dependence on species richness and species abundance distributions

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#### Abstract

<sup>8</sup> Species richness and patterns of abundance result from the interplay between niche differences, realized as intraspecific density-dependence (IDD), and so-called neutral
<sup>10</sup> processes that arise when species fitnesses are similar. This paper presents an extension of neutral models that incorporates delays in IDD that could result from resource-mediated
<sup>12</sup> competition or through a pathogen pool. These delays reduce standing species richness and qualitatively change the shape of species abundance distributions and render them
<sup>14</sup> consistent with the hollow curve shape even in the presence of strong IDD.

#### 1. Introduction

The neutral theory of ecology challenges the common perception that highly speciose communities are governed by differences between species (Hubbell 2001; Adler et al. 2007).
In this theory, both individuals and species are treated as equivalent, and biodiversity and community composition result from random walks of species abundance generalized
to include different birth and death rates and immigration or speciation (Chave 2004).
Coexistence depends on a balance between species input and species extinction (Zillio and 2007), and high levels of species richness depend on these species having relatively equal fitnesses (Chesson 2000; Adler et al. 2007)

<sup>24</sup> Coexistence via nearly equal fitness contrasts with coexistence through stabilizing mechanisms (intraspecific density-dependence, or IDD) whereby species gain an advantage
<sup>25</sup> by being rare (Chesson 2000). Several reviews have found evidence for improved performance when a species is locally rare (Harms et al. 2000; Peters 2003; Wills et al. 2006), although
<sup>28</sup> the ecological mechanisms remain largely unknown. An advantage of rarity could result, for

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example, from specialized pathogens (Janzen 1970; Connell 1971), or specialized resource <sup>30</sup> use (Chesson 2000).

Comparing the predictions of models dominated by neutral processes with those
<sup>32</sup> dominated by stabilizing mechanisms remains contentious (McGill et al. 2006). For
example, Volkov et al. (2005) developed a model of IDD and claimed that its predictions
<sup>34</sup> could not be distinguished from those of dispersal limitation, while a later analysis found
that dispersal limitation fits data better (Chave et al. 2006).

Many other factors can and have been added to this story. Spatial factors addressed include local dispersal (Chave et al. 2002; Holyoak and Loreau 2006; Economo and Keitt
<sup>38</sup> 2008) and its interaction with localized IDD (Chave 2004; Adler and Muller-Landau 2005), along with different scales of intraspecific and interspecific competition (Murrell and Law
<sup>40</sup> 2003). Temporal factors include environmental stochasticity (Allen and Savage 2007), environmental heterogeneity (Snyder and Chesson 2003), and recruitment fluctuation (Kelly
<sup>42</sup> and Bowler 2002). Heterogeneity has been studied both within (Clark et al. 2007) and among species (Zhou and Zhang 2008). One recent review in this area referred to this
<sup>44</sup> proliferation of theories and the absence of falsifying tests as a "collective scientific failure" (McGill et al. 2007).

Some of the contention regarding the predictions of models results from a heavy emphasis on the shapes of species abundance distributions (SAD) whose structure might be
insufficiently elaborate to distinguish among theories. A theory is certainly wrong if it fails to predict the apparently universal empirical law that the SAD appears to be decreasing
and concave up, with many rare species and few common (McGill et al. 2007). However, much more detail about the identities of species and their abundances over time might be

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<sup>52</sup> what is needed to distinguish among the possible many theories that pass this qualitative test (McGill et al. 2007).

In this spirit, other authors have emphasized the need for theories that synthesize 54 existing theoretical approaches, particularly models that combine neutral processes and stabilizing mechanisms, and derive broadly testable predictions (Holyoak and Loreau 2006). 56 This paper adds a new element, extending existing models of IDD within local communities to include delayed IDD. Many forms of competition are mediated through resources, and 58 thus the negative effect of a species on itself might depend more on the past than on the current density. This work thus seeks to link experiments showing that the strength of IDD 60 is important for the abundance of particular species (Comita et al. 2010) with the delays that characterize the strength of competition. To my knowledge, delayed intraspecific density-dependence has not been treated in models of this sort. The paper examines the effects that delays have on the species richness and on the qualitative shape of the SAD, and introduces a framework that can be used to match these broad observations with detailed information on the strength and mechanisms of density-dependence in individual species.

### 2. Model and simulation

### Model of delayed intraspecific density-dependence

Consider the random variable N describing the number of members of a species in <sup>70</sup> a single patch. In the absence of delays, assume that the number increases by 1 at rate  $(\phi N + m)p(N)$  where  $\phi$  is per capita fecundity, m the rate of immigration, and p(N) gives <sup>72</sup> the density-dependent probability of offspring or immigrant survival (table 1). The number decreases by 1 at rate  $\mu N$  where  $\mu$  is the per capita death rate, where all rates can be

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thought of as being in years. The probability  $q_n$  that species has n members follows the master equation

$$\frac{dq_n}{dt} = (\phi(n-1) + m)p(n-1)q_{n-1} - ((\phi n + m)p(n) + \mu n)q_n + \mu(n+1)q_{n+1}$$

for  $n \ge 0$  (with  $q_{-1} = 0$  to avoid births into the 0 class). Although most of the results are general for any decreasing function p(n), I describe IDD with the form

$$p(n) = \frac{1}{1+bn} \tag{1}$$

- where b gives the strength of IDD. Because this function is multiplied by fecundity, we can set p(0) = 1 without loss of generality.
- At equilibrium, this set of equations can be solved sequentially for  $q_{n+1}$  in terms of  $q_n$ for n > 0 as

$$(\phi n + m)p(n)q_n = \mu(n+1)q_{n+1}.$$
(2)

Then we can solve for q<sub>0</sub> because these probabilities must add up to 1. This is a special case of a more general analysis (Allouche and Kadmon 2009), and could be approximated
using the methods presented in Adler & Muller-Landau (2005).

To model delayed IDD, replace the current abundance n in the function p(n) with p(x)<sup>86</sup> where x is an effective population size that decays toward the actual population size with time constant  $\tau$  according to the differential equation

$$\frac{dx}{dt} = \frac{n-x}{\tau}.$$
(3)

For example, if delayed IDD acts through specialized pathogens, τ is the average time that those pathogens remain viable in the absence of hosts. The value τ = 0 reduces to the case
with no delay.

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Table 1: Parameters used in the model and simulations

Symbol	Description	Values used in simulations
$n^*$	population where births balance deaths	5
$\mu$	per capita rate of death	Chosen to balance births near $n^*$
au	time constant of delayed IDD	0.1, 1, 10, 100, 1000
b	strength of IDD	0,  0.1,  0.5,  1
$\phi$	per capita fecundity	1
m	immigration rate	0.001, 0.01
J	number of adults per patch	100
tsteps	number of time steps in simulation	20000

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The model tracks probability density functions  $g_n(x)$  describing the distribution of effective population x when the species has actual population n. These probability density functions obey the advection equation

$$\frac{\partial g_n}{\partial t} + \frac{1}{\tau} \frac{\partial (n-x)g_n}{\partial x} = (\phi(n-1) + m)p(x)g_{n-1} - ((\phi n+m)p(x) + \mu n)g_n + \mu(n+1)g_{n+1}.$$
 (4)

 $_{\rm 94}~$  At equilibrium, this reduces to the differential equation

$$\frac{1}{\tau}\frac{d}{dx}(n-x)g_n(x) = (\phi(n-1)+m)p(x)g_{n-1}(x) - ((\phi n+m)p(x)+\mu n)g_n(x) + \mu(n+1)g_{n+1}(x).$$
(5)

Letting  $g_n(x)$  represent the solution of this equation, the unconditional probability that a species has n members  $q_n$  is

$$q_n = \int_{x=0}^{\infty} g_n(x) dx$$

subject to the constraint that

$$\sum_{n=0}^{\infty} q_n = 1.$$

## Moment analysis

I define  $\bar{p}_n$  as the mean offspring survival when population size is n, given by

$$\bar{p}_n = \frac{\int_{x=0}^{\infty} p(x) g_n(x) dx}{q_n}.$$
(6)

100 Integrating equation 5 over all x gives

$$(\phi n + m)\bar{p}_n q_n = \mu(n+1)q_{n+1} \tag{7}$$

This requires assuming that

$$\lim_{x \to \infty} (n-x)g_n(x) = ng_n(0) = 0.$$

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The first term reduces to zero under the assumption that  $g_n(x)$  decays sufficiently quickly to zero, as can be expected when reproduction is a decreasing function of population size and as is observed in simulations. The second term is exactly zero when n = 0, and we necessarily have that  $g_n(0) = 0$  for n > 0 because the density always flows away from x = 0for any positive n. Equation 7 matches equation 2 except that only the average survivorship matters.

Similarly, define  $\bar{N}_n$  as the mean effective population when actual population size is n, given by

$$\bar{N}_n = \frac{\int_{x=0}^{\infty} x g_n(x) dx}{q_n}.$$
(8)

With small values of  $\tau$ , we expect  $\bar{N}_n \approx n$ .

Multiplying both sides of equation 5 by x and integrating gives

$$\frac{\bar{N}_n - n}{\tau} q_n = (\phi(n-1) + m) \int_{x=0}^{\infty} x p(x) g_{n-1}(x) dx - \mu n \int_{x=0}^{\infty} x g_n(x) dx - (\phi n + m) \int_{x=0}^{\infty} x p(x) g_n(x) dx + \mu(n+1) \int_{x=0}^{\infty} x g_{n+1}(x) dx.$$

112 Again, we must assume that  $g_n(x)$  decays sufficiently quickly to zero for large x. Defining

$$\Delta_n = \bar{N}_n - n \tag{9}$$

and expanding integrals around x = n, we find that

$$\frac{\Delta_n}{\tau}q_n \approx (\phi(n-1)+m)p(n-1)((n-1)+p(n-1)\Delta_{n-1})q_{n-1}-\mu n(n+\Delta_n)q_n - (\phi n+m)p(n)(n+p(n)\Delta_n)q_n + \mu(n+1)(n+1+\Delta_{n+1})q_{n+1}.$$

This assumes that  $g_n(x)$  is strongly peaked near x = n, an assumption only appropriate for small values of  $\tau$ . I used the form of p(x) given in equation 1 to simplify the derivatives.

Substituting the recursive relationship between the  $q_n$ 's (equation 7), this can be written entirely in terms of factors of  $q_n$  that cancel, leading, after some algebra, to

$$\frac{\Delta_n}{\tau} \approx (\phi n + m)p(n) - \mu n + (\phi n + m)p(n)(\Delta_{n+1} - \Delta_n) - \mu n(\Delta_n - \Delta_{n-1}).$$
(10)

<sup>118</sup> I present here only results from the first order approximate values of  $\Delta_n$  of

$$\tilde{\Delta_n} = \tau((\phi n + m)p(n) - \mu n), \tag{11}$$

valid when  $\tau$  is small. With this approximation,

$$\tilde{N}_n = n + \tau((\phi n + m)p(n) - \mu n).$$
(12)

This equation describes a balance between growth and decline, with mean effective size greater than actual size when n is small, and less than actual size when n is relatively large.

#### Simulation

The simulation, implemented in R (R Development Core Team 2007), tracks the <sup>124</sup> abundance of a single species as a random walk in the population size N. However, in the presence of delays, the rate of transitions due to births changes over time. Suppose the <sup>126</sup> species has just entered the state with population size n and effective population size  $x_0$ . It leaves that population at rate

$$U(t) = (\phi n + \mu n)p(x(t)) + \mu n.$$

Here x(t) is the solution of equation 3 given by

$$x(t) = e^{-\frac{t}{\tau}} x_0 + (1 - e^{-\frac{t}{\tau}})n.$$

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The probability S(t) that no event has occurred obeys the differential equation

$$\frac{dS}{dt} = -((\phi n + \mu n)p(x(t)) + \mu n)S$$

with initial condition S(0) = 1 and solution

$$S(t) = e^{-\int_0^t U(s)ds}.$$

The time until the next event can be found by solving for the time t when S(t) is equal to a random number r chosen uniformly from [0, 1], or equivalently where  $\int_0^t U(s)ds = -\log(r)$ . With the choice of p(x) given by equation 1, we can integrate U(s) explicitly to give

$$\frac{(\phi n + m)\tau}{1 + bn} \left(\frac{t}{\tau} + \log\left(\frac{b(x_0 - n)e^{-\frac{t}{\tau}} + (1 + bn)}{1 + bx_0}\right)\right) + (\mu n + m)t = -\log(r).$$

At the time t when the next event occurs, the population increases with probability proportional to  $(\phi n + m)p(x(t))$  and decreases with probability proportional to  $\mu n$ .

To keep populations from increasing without bound in cases where the strength b of density dependence is low, the probability of increase is multiplied by  $1 - \frac{n}{J}$  with J acting as a maximum population size. The death rate  $\mu$  was chosen so that the birth/immigration rate with  $n = x = n^*$  is equal to  $\mu n^*$  for a "target" value  $n^*$ . This value should be approximately where  $\bar{N}_n = n$  (equation 12).

The values of  $q_n$  can be estimated from the simulation by adding up the total time spent with population n. To estimate  $g_n(x)$ , I choose a grid of values of x in the range from 0 to the maximum n observed. At each value, the time spent near x when the population is n is proportional to  $\frac{\tau}{|n-x|}$ , and these times are added up over all intervals when the effective population size crossed x with actual population n. To avoid dividing by zero, the if grid of x values avoids the integers. UU IR Author Manuscript

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Then  $\bar{p}_n$  and  $\bar{N}_n$  can be found by integrating over each simulated interval with population size n. If the population begins with effective population  $x_j$ , ends at  $x'_j$  and runs for a time  $\Delta t_j$ , the mean effective population size is

$$\widehat{\bar{N}_n} = \frac{\sum_j \int_0^{\Delta t_j} x(t) dt}{\sum_j \Delta t_j}.$$

150 With x(t) given by equation 3, this reduces to

$$\widehat{\bar{N}_n} = \frac{\sum_j (x_j - x'_j)\tau + n\Delta t_j}{\sum_j \Delta t_j}$$

Similarly, the estimated average survivorship when at population  $n, \hat{p_n}$ , is

$$\widehat{p_n} = \frac{\sum_j \int_0^{\Delta t_j} p(x(t)) dt}{\sum_j \Delta t_j}$$

<sup>152</sup> which can be rewritten as

$$\widehat{\widehat{p}_n} = \frac{\sum_j \frac{\tau}{1+bn} \log(\frac{1+bx'_j}{1+bx_j}) + \frac{\Delta t_j}{1+bn}}{\sum_j \Delta t_j}.$$
(13)

To estimate species abundances, species are sampled to have abundance from the 154 estimated distribution of  $q_n$  (Etienne et al. 2007). Let  $N_k$  represent the number of members of species k, with  $N_k = n$  with probability  $q_n$ . Define  $\tilde{N}_k$  as the probability distribution 156 restricted to  $N_k > 0$ , with probability distribution

$$\Pr(\tilde{N}_k = n) = \frac{q_n}{1 - q_0}.$$

The total population size T after sampling S species is

$$T = \sum_{k=1}^{S} \tilde{N}_k,$$

<sup>158</sup> with expectation

 $\mathcal{E}(T) = \mathcal{E}(S)\mathcal{E}(\tilde{N}).$ 

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Setting E(T) = J, we find that

$$E(S) = \frac{J}{E(\tilde{N})} = \frac{J(1-q_0)}{E(N)}.$$
(14)

<sup>160</sup> On average, the number of species sampled before filling a site depends only on the expected population size of each species and the probability that a species is present.

#### 3. Results

For small values of  $\tau$ , simulated values of the probability density functions  $g_n(x)$  are <sup>164</sup> centered around  $x \approx n$ , while with large  $\tau$  they become highly skewed and centered around  $n^*$  for n > 0 (Figure 1). In this latter case, the effective size is relatively large when <sup>166</sup> the actual population is small, and relatively small when the actual population is large (Figure 2). This creates a flattening of offspring survival as a function of population size <sup>168</sup> that reduces the advantage of rarity (Figure 3).

In the absence of IDD (b = 0), the duration of the delay  $\tau$  has no effect on the mean observed species richness. At small values of  $\tau$ , positive IDD leads to increased biodiversity by creating an advantage of rarity (Figure 4). At large values of  $\tau$ , however, standing species richness is reduced by IDD. When populations are close to extinction, they tend to have a relatively large effective population size (Figure 1), and thus a higher probability of extinction than in the absence of IDD.

The approximation given by equation 14 accurately predicts diversity (Figure 5), by <sup>176</sup> using only the simulated mean values of E(N) and  $q_0$ . Using instead the simulated values  $\bar{p}_n$ for the mean offspring survival probabilities, we can compute the values of  $q_n$  (equation 7), <sup>178</sup> giving a reasonable, although less accurate approximation.



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Fig. 3.—





15

10

S

0.1

b = 0 b = 0.1

b = 0.5

1

10

τ

100

1000

b = 1

Species richness

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Predicted species richness

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In the absence of delays, strong IDD (b = 0.5 or b = 1) creates unrealistic species abundance distributions that have most species with intermediate abundance (Figure 6). However, the inclusion of delays alters these shapes to more realistic concave up shapes. The species abundance distribution with strong delayed IDD differs from those in the absence of IDD (b = 0) in having a longer tail that generates the lower species richness.

#### 4. Discussion

This paper presents a model for studying the species richness and species abundance
distribution (SAD) in local communities structured by intraspecific density-dependence
(IDD) described by a function relating current local abundance of a species to survival of its
offspring. In the absence of delays, IDD increases species richness, but only slightly. Strong
IDD, however, can create an SAD with an unrealistic mode at intermediate population size
(Figure 6).

Delayed IDD leads to a systematic change in the shape of the SAD to have a mode <sup>192</sup> at the rarest species (Figure 6). If delayed IDD is a general description of both long-lived pathogens and of niche differentiation through resource dynamics, the fact that it can <sup>194</sup> correct the unrealistic deficiency of rare species generated by models with strong IDD argues that delays are worthy of further consideration.

The basic equation presented in this paper can be extended to include heterogeneity among species through differences in their parameter values, particularly the strength of
IDD or the duration of the delay, although including interspecific competition is much more difficult. These models would be appropriate for more detailed fitting to empirical
data (McGill et al. 2006). In the context of discrete patches, the immigration *m* for each





15

Population size

0.30

0.20

0.10

0.00

0

5

Population size

Frequency



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species could be adjusted to match its long-term abundance in the metacommunity (Hubbell
202 2001) or model differences in dispersal among species. The model can also be extended
to address the tradeoff between competition and mortality (Adler and Mosquera 2000) by
choosing certain species to have higher fecundity and modifying the death rate to differ
between species.

The description of IDD does not include an explicit mechanism, and focuses only a single age class. A more mechanistic model that included the effects of heterospecific
competitors (Alonso et al. 2008) would help in creating a more realistic implementation of delayed IDD. For example, specialized predators could play a key role in these
dynamics (Levin et al. 1977).

How stochasticity, whether through changes in the environment (Allen and Savage
2007) or in recruitment (Kelly and Bowler 2002), can be subsumed into this approach is unclear. However, the dominant effect of mean survival (equation 7) argues that at least the
first form of environmental noise might be tractable. These extensions might be possible to address with the diffusion approximation (Allen and Savage 2007), although those methods
would be challenging to use when species differ.

Understanding the role of space could take several paths (Levin 1974). First, in most
real ecosystems patches are an abstraction. How the parameters of the survival function,
particularly the parameter b that describes IDD, depend on the choice of patch size could be
derived from the mechanism of interaction. Second, the survival function could be derived
from a description of the scale and type of both dispersal and interaction (Murrell and Law
2003), a step missing from our earlier analysis of the Janzen-Connell hypothesis (Adler and
Muller-Landau 2005). The intriguing phenomenon of diversity repellers and accumulators,

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species that have local neighborhoods with relatively low or high biodiversity (Wiegand et al. 2007) might cast light on this problem. Finally, local dispersal among patches in
a spatially realistic metapopulation (Adler and Nuernberger 1994) can have substantial effects on diversity (Chave et al. 2002).

The focus on pure IDD ignores the fact that density-dependent factors, such as 228 pathogens, tend not to affect only a single species but spill over to similar or closely-related species (Gilbert and Webb 2007), although comprehensive data are still lacking (Freckleton 230 and Lewis 2006). At least one study has found that a slight majority of species are affected equally by all others, and that the rest are affected most by neighbors of the same species, 232 family, or guild (Uriarte et al. 2004). To address this, the models could be extended most simply by focusing on cases with species assigned to two or more types. Probability of 234 survival could be a function of both the number of conspecifics and "contypics." More generally, one could imagine a matrix describing the effects different species have on 236 each other, much like the matrix of distances between patches in a spatially realistic metapopulation model (Adler and Nuernberger 1994). 238

The results presented here are based on the underlying distribution of abundance rather than samples (Chave 2004). Given that this underlying distribution cannot be computed explicitly, deriving the distribution of samples will almost certainly have to be done numerically. However, estimating the parameters of the underlying model from empirical data via maximum likelihood may be possible using hierarchical methods (Clark 2007).

A particular application somewhat removed from those addressed in this literature 246 provides further motivation for delays. Some viruses, such as the rhinoviruses that cause

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the majority of common colds, have high serotypic diversity (Savolainen et al. 2002), with an entire new clade having been recently discovered (Lee et al. 2007). Preliminary models 248 with the neutral theory (Koppelman and Adler 2005) achieved relatively good fits to classic data on abundances (Monto et al. 1987), but neglected the key way that viruses interact: 250 through specific and non-specific immune memory. A dynamical model showed that the details of immune interactions among viruses can play a key role in influenza (Ferguson 252 et al. 2003), and data are emerging that describe the immunological interactions between different viral strains (Gern et al. 1997). Genetic sequencing is making viral diversity highly 254 accessible, and challenges us to develop both empirical and theoretical methods to deal with complex networks of delayed interactions. Furthermore, the more rapid turnover of species 256 or serotypes in viruses could use the temporal changes in abundance of particular types to estimate the effects of delays. 258

Delays also play a key role in maintaining the diversity of ideas, which are governed <sup>260</sup> by a complex balance between positive and negative feedbacks (Durrett and Levin 2005). New, or seemingly new, ideas have a certain appeal due to the advantage of rarity, while <sup>262</sup> extensions of older and more established ideas have an appeal derived from their familiarity and more rapid acceptance (Ehrlich and Levin 2005). Those rare scholars and teachers who <sup>264</sup> maintain an effective working memory for past ideas along with a quick appreciation of the <sup>265</sup> best new ideas buffer research from extreme conservatism or faddishness, and act to sustain <sup>266</sup> a healthy and robust community of ideas.

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Figure 1: Smoothed densities of simulated  $g_n(x)$ , the probability density of an effective size of x for a given actual population, with strong IDD b = 1 and two values of  $\tau$ . The dashed line shows  $g_0(x)$ , and the solid lines sequentially show  $g_1(x)$  up through  $g_8(x)$ .

Figure 2: Simulated (solid dots) and predicted (solid lines) values of the mean effective population size  $\bar{N}_n$  compared with the line of equality (dashed diagonal line). The low order approximation breaks down for values of  $\tau > 1$ .

Figure 3: Simulated (thick line) values of the mean survival probability  $\bar{p}_n$  for different strengths of IDD *b* and delays  $\tau$ , compared with the values of the survival function p(n) that would obtain in the absence of delays (dashed lines).

Figure 4: Species richness as a function of b, the strength of IDD, and the duration of the delay  $\tau$ . Each value generated by simulation of the system with given parameters for 20,000 steps.

- Figure 5: Comparison of diversity sampled from simulation with two predictions from statistics derived from simulation: based solely on the mean population size and the probability of extinction (equation 14, solid dots), and based on the values of  $q_n$ derived from equation 7 using estimated values of  $\bar{p}_n$  (equation 13).
- Figure 6: Species abundance distributions as a function of the strength of IDD b and the duration of the delay  $\tau$ .

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