

Assessment of Rice Growth Conditions in a Semi-arid Region of India Using the Generalized Radar Vegetation Index Derived from RADARSAT-2 Polarimetric SAR Data

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Abstract

Rice growth monitoring using Synthetic Aperture Radar (SAR) is recognized as a promising approach for tracking the development of this important crop. Accurate spatio-temporal information of rice inventories is required for water resource management, production risk occurrence, and yield forecasting. This research investigates the potential of the proposed Generalized volume scattering model based Radar Vegetation Index (GRVI) for monitoring rice growth at different phenological stages. The GRVI is derived using the concept of a geodesic distance (GD) between Kennaugh matrices projected on a unit sphere. We utilized this concept of GD to quantify a similarity measure between the observed Kennaugh matrix (representation of observed Polari-

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metric SAR information) and the Kennaugh matrix of a generalized volume scattering model (a realization of scattering media). The similarity measure is then modulated with a factor estimated from the ratio of the minimum to the maximum GD between the observed Kennaugh matrix and the set of elementary targets: trihedral, cylinder, dihedral, and narrow dihedral. In this work, we utilize a time series of C-band quad-pol RADARSAT-2 observations over a semi-arid region in Vijayawada, India. Among the several rice cultivation practices adopted in this region, we analyze the growth stages of Direct seeded rice (DSR) and conventional Transplanted rice (TR) with the GRVI and crop biophysical parameters viz., Plant Area Index – PAI. The GRVI is compared for both rice types against the Radar Vegetation Index (RVI) proposed by Kim and van Zyl. A temporal analysis of the GRVI with crop biophysical parameters at different phenological stages confirms its trend with the plant growth stages. Also, the linear regression analysis confirms that the GRVI outperforms RVI with significant correlations with PAI ($r \geq 0.83$ for both DSR and TR). In addition, PAI estimations from GRVI show promising retrieval accuracy with Root Mean Square Error (RMSE) $< 1.05 \text{ m}^2 \text{ m}^{-2}$ and Mean Absolute Error (MAE) $< 0.85 \text{ m}^2 \text{ m}^{-2}$.

Keywords: Rice, GRVI, SAR Polarimetry, direct seeded rice, RVI

1. Introduction

Rice (*Oryza sativa*) is the major crop grown in the Indian subcontinent of Asia. The majority of the rice cultivars are grown during the monsoon season (July to November), i.e., *Kharif* season. Despite available rain, in many regions, rice production is significantly affected by the early or late arrival of

6 monsoon. In particular, farmers have been cultivating rice for decades in the
7 rainfed regions of the Krishna and Guntur districts of India which fall under
8 the semi-arid climatic zone. However, instead of traditional transplanted rice
9 cultivation practices, direct seeding of rice is gaining attention and is being
10 promoted under Integrated Crop Management (ICM) government policies in
11 the semi-arid region of these districts (APAgriculture, 2018; NIBIO, 2012).

12 Rice production strongly depends on the crop establishment period, which
13 affects the critical phenological stages (tillering, flowering, and grain filling
14 periods) (Mahajan et al., 2009; Lampayan et al., 2015). Thus, it is essen-
15 tial to monitor the temporal dynamics of plant growth over a large spatial
16 extent. Despite promising results reported from optical remote sensing, the
17 implementation of optical sensing for mapping and monitoring of rice during
18 the monsoon season is problematic given the persistent presence of clouds.
19 As such, the exploitation of Synthetic Aperture Radar (SAR) has drawn
20 considerable attention for rice monitoring in the monsoon season, given the
21 ability of microwaves to acquire data regardless of cloud cover and the sensi-
22 tivity of SAR signal to dielectric and geometric properties of targets (Le Toan
23 et al., 1997; Inoue et al., 2002; Chakraborty et al., 2005; Wang et al., 2009;
24 Kuenzer and Knauer, 2013). Recognizing the role of SAR systems for opera-
25 tional monitoring of rice, international initiatives have been launched includ-
26 ing the Asian Rice Crop Estimation and Monitoring (Asia-RiCE) under the
27 Group on Earth Observations Global Agriculture Monitoring (GEOGLAM)
28 framework (Nelson et al., 2014; Oyoshi et al., 2016). Recent studies are also
29 turning their attention towards developing processing chains in cloud-based
30 platforms to evaluate the potential and transferability of operational crop

31 characterization at regional scales with the availability of operational SAR
32 systems (Mandal et al., 2018; Singha et al., 2019).

33 Polarimetric SAR can provide a rich source of data to track temporal dy-
34 namics of vegetation conditions (Wiseman et al., 2014; De Bernardis et al.,
35 2015; McNairn and Shang, 2016; Wang et al., 2016; Steele-Dunne et al., 2017;
36 McNairn et al., 2018). In exploiting SAR sensors (ALOS-2, RADARSAT-
37 2, and TerraSAR-X), several researchers have reported the potential of crop
38 growth monitoring by relating the associated physical scattering mechanisms
39 from the vegetation canopy to phenology (Lopez-Sanchez et al., 2012, 2014;
40 Torbick et al., 2017; Canisius et al., 2018). Several studies further utilized
41 the dynamics of scattering response for phenology estimation (Lopez-Sanchez
42 et al., 2014; Rossi and Erten, 2014; Vicente-Guijalba et al., 2014; Yuzugullu
43 et al., 2015, 2017; He et al., 2018). Retrieval of biophysical parameters for
44 rice, using backscatter coefficients of different polarizations (HH, HV, VH,
45 and VV), has also been demonstrated with acceptable estimation accura-
46 cies (Kumar et al., 2013; Yang et al., 2014; Inoue et al., 2014). Several
47 studies have reported on the use of backscatter intensity ratios, the pedestal
48 height, polarization fraction, and polarimetric decomposition parameters as
49 a proxy for crop growth monitoring (Bouvet et al., 2009; Jiao et al., 2011;
50 Blaes et al., 2006; Cable et al., 2014; McNairn and Shang, 2016).

51 Similar to spectral indices that are well established in optical remote
52 sensing, a vegetation index derived from SAR data could be an alterna-
53 tive, especially for crop growth monitoring during periods of cloud cover.
54 In this direction, Kim and van Zyl (2009) introduced the Radar Vegetation
55 Index (RVI) which uses a measure of scattering randomness within vegeta-

56 tion targets. RVI is expected to increase (within the range of 0-1) as volume
57 scattering increases due to development of canopy elements.

58 A few studies have attempted to utilize the RVI for crop growth moni-
59 toring and biophysical parameter estimation (Kim et al., 2012, 2014; Huang
60 et al., 2016). Kim et al. (2012) evaluated the RVI for estimating the Vege-
61 tation Water Content (VWC) of rice and soybeans, tracking these crops for
62 the entire growing season using ground-based multi-frequency scatterome-
63 ters. For both crops, the RVI followed the temporal trend of VWC, with
64 the index increasing up to the heading stage then decreasing until harvest.
65 However, it was observed that the dynamic range of RVI was low (0.35–0.50),
66 in contrast to the significant variation in backscatter intensities during the
67 growth cycle of these crops. Canisius et al. (2018) analyzed the correlation
68 of RVI with the effective Leaf Area Index (LAI) and height of canola and
69 wheat. The RVI showed comparatively a higher sensitivity to the crop height
70 dataset, only when smoothing was performed to suppress the high-frequency
71 noise of temporal RVI.

72 As an alternative to utilizing the RVI as a proxy for crop condition, scat-
73 tering models are often used to track plant phenological changes through
74 a growing season. PolSAR scattering models have been utilized in the lit-
75 erature (Antropov et al., 2011; Sato et al., 2011; Jagdhuber et al., 2012;
76 Xie et al., 2017) to approximate the scattering behaviour within a resolu-
77 tion cell of SAR observations. The changes in the scattering behaviour with
78 plant phenology could be used as a technique to track crop growth condi-
79 tion (Jiao et al., 2011; Lopez-Sanchez et al., 2014; Canisius et al., 2018).
80 In our recent study, Ratha et al. (2019) proposed a novel radar vegetation

81 index which utilizes the generalized volume scattering model (GVSM) for
82 PolSAR data to characterize vegetation growth (Antropov et al., 2011). The
83 generalized volume scattering model based radar vegetation index (GRVI)
84 utilizes the geodesic distance between two Kennaugh matrices projected on
85 unit sphere (Ratha et al., 2017). Unlike the RVI, which models the vege-
86 tation layer as an aggregation of randomly oriented dipoles (Kim and van
87 Zyl, 2009), the GRVI offers flexibility to choose the parameters describing
88 the volume scattering component (Antropov et al., 2011). It is important
89 to note that the generalized volume scattering model and the GRVI formu-
90 lation intrinsically takes into account the elementary scattering components
91 (surface and double bounce) using the co-polarized ratio and the correlation
92 coefficient, respectively.

93 The GRVI was implemented to characterize wheat and soybeans with a
94 multi-temporal RADARSAT-2 dataset (Ratha et al., 2019). The GRVI trend
95 followed the growth development of both crops, with VWC and Plant Area
96 Index (PAI) increasing as the crops developed. A strong correlation (>0.76)
97 was observed between the GRVI and these growth indicators, for both wheat
98 and soybeans through their vegetative stages. The GRVI outperformed RVI
99 in terms of correlation with these biophysical parameters. This study sug-
100 gested that for monitoring crop growth using SAR data, it is advantageous
101 to integrate information from a generalized volume scattering model to form
102 a vegetation index. This insight is particularly crucial for rice crop where
103 the scattering power is dominated by both volume and double bounce mech-
104 anisms. Unlike other crop types (e.g., canola, soybean, wheat) where the
105 volume scattering is often used as a proxy for canopy development (more

106 random scatterers), the scattering mechanism is more complex for rice due
107 to its canopy architecture (vertical stems and erectophile leaf distribution)
108 and the underlying inundated field condition (or saturated soil).

109 In the research presented here, we utilize the GRVI for monitoring rice
110 growth at different phenological stages. A time-series quad-pol RADARSAT-
111 2 dataset over a semi-arid region of India is available for a comparative as-
112 sessment of GRVI and RVI. This study assesses GRVI for estimating crop
113 biophysical parameter. The rest of the paper is organized as follows: Sec-
114 tion 2 briefly describes the study area and the dataset used for the analysis.
115 Section 3 explains in detail the methodology proposed used in this study.
116 Section 4 discusses the results with the main conclusions of this research
117 summarized in Section 5.

118 **2. Study area and dataset**

119 This research is conducted over the Joint Experiment for Crop Assessment
120 and Monitoring (JECAM) test site in Vijayawada, India, as shown in Fig. 1.
121 The Vijayawada test site covers the Krishna and Guntur districts in the state
122 of Andhra Pradesh, India. Within this state, roughly 63% of the geographical
123 area falls in a semi-arid climatic zone (Rao et al., 2013). The test site covers
124 an area of approx. 50×25 km² and is characterized by three major annual
125 crops—rice, sugarcane, and cotton. These crops are grown in two distinct
126 seasons— monsoon or *kharif* (June-November) and winter or *rabi* (December-
127 March). The flat topography and the dominance of agriculture make this site
128 particularly attractive for SAR based research. A detailed description of the
129 test site is provided in Mandal et al. (2019b).

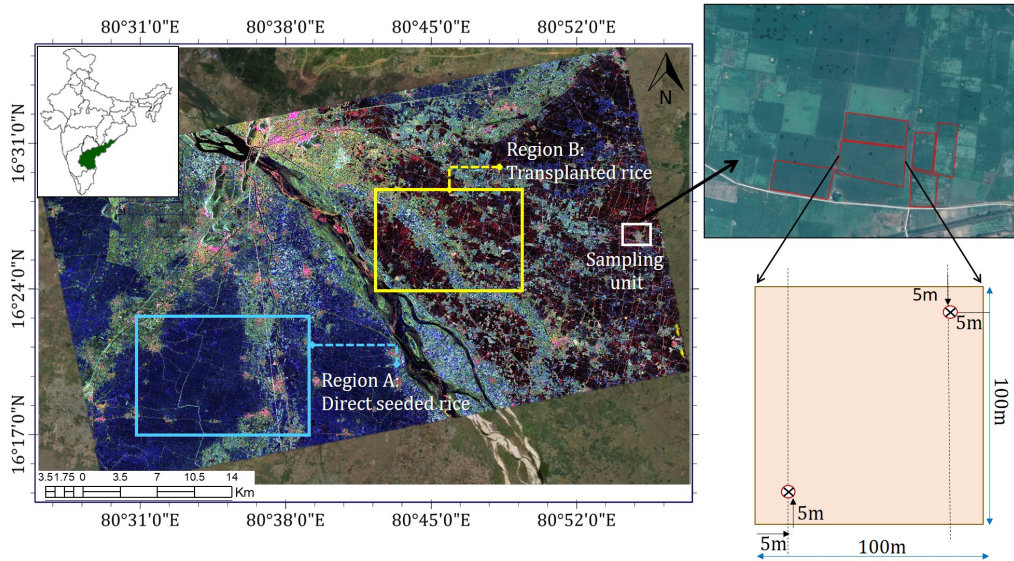


Figure 1: The JECAM-Vijayawada (Andhra Pradesh) India test site with a RADARSAT-2 PauliRGB image of 29th July 2018. Two distinct regions for direct seeded rice (Region A in cyan box) and transplanted rice (Region B in yellow box) are marked within the test area of 50 km \times 25 km. A layout of a sampling unit (white box) is highlighted at the right.

130 The research presented in this manuscript focuses on rice cultivation dur-
 131 ing the *khariif* season, within the JECAM test site. In particular, two major
 132 rice cultivation techniques, i.e., transplanted rice (TR) and direct seeded
 133 rice (DSR) are being practiced (NIBIO, 2012; APAgriculture, 2018). In
 134 traditional farming, rice is primarily grown by transplanting seedlings into
 135 flooded puddled fields. The TR cultivation requires large volumes of water
 136 (approx. 150 cm of total irrigation water) for puddling and further mainte-
 137 nance of standing-water conditions (Singh et al., 2001). Alternatively, the
 138 DSR cultivation is being promoted in this region (Fig. 1), which includes
 139 alternate wetting and drying instead of a persistent standing-water condi-
 140 tion (Mahajan et al., 2013). The DSR method of cultivation reduces water

141 consumption by approximately 30% by eliminating the nursery raising, pud-
142 dling, transplanting, and initial standing-water condition during the early
143 tillering stage (Balasubramanian and Hill, 2002; Cabangon et al., 2002).

144 *2.1. In-situ sampling strategy*

145 Field campaigns were conducted in the *khariif* season to track different rice
146 growth stages from June to November 2018. During the campaign, in-situ
147 measurements were collected of crops and soil for 75 agricultural fields. The
148 nominal size of each field is around 100 m×100 m. In each sampling field, soil
149 moisture was measured at two sampling locations, arranged in two parallel
150 transects along the row direction, as shown in Fig. 1. Each transect was
151 separated by approximately 80 m. Soil moisture was measured at each point
152 using a theta-probe. However, it is important to note that soil underlying the
153 rice canopy was saturated during most of the growing season due to frequent
154 irrigation and rainfall events.

155 In each field, vegetation sampling was conducted at two points (Fig. 1)
156 corresponding to the soil sampling locations. Vegetation sampling included
157 the measurement of PAI, plant height, density, and phenology through non-
158 destructive approaches. The PAI was estimated from photographs using the
159 concept of hemispherical digital photography (Jonckheere et al., 2004; Weiss
160 et al., 2004). During each of the measurement day, ten photos were taken
161 along two transects which are separated by 2m in each sampling point, using a
162 wide-angle lens mounted on a digital camera. These photos record the geom-
163 etry of the plant canopy obstructing the field of view against the soil surface.
164 All images were post-processed using the CanEYE software (INRA, 2017) to
165 provide an estimate of PAI. The phenological growth of rice is usually ex-

166 pressed with three major stages: vegetative, reproductive, and maturation or
 167 ripening. Each of these stages has particular morphological changes and vari-
 168 ations in the biophysical parameters. These phenological developments were
 169 indicated in terms of a quantitative measure using the BBCH (Biologische
 170 Bundesanstalt Bundessortenamt und Chemische Industrie) scale by visual
 171 inspection (Bleiholder et al., 2001). The detailed description of vegetation
 172 and soil sampling strategies can be found in the field campaign report (Man-
 173 dal et al., 2019b).

174 2.2. SAR dataset

175 During the campaign, seven RADARSAT-2 images were acquired in Fine
 176 Wide quad-pol mode (FQW) as given in Table 1. The selection of acquisition
 177 dates was based on in-situ measurement periods. All these acquisitions were
 in quad-pol mode with a scene center incidence angle of 35.2° .

Table 1: Specification of C-band quad-pol RADARSAT-2 acquisitions over the test site during the field campaign

Acquisition date	Beam mode	Incidence angle range (.deg)	Orbit	In-situ measurements
05-07-2018	FQ15W	33.7 - 36.7	Ascending	04 Jul., 05 Jul.
29-07-2018	FQ15W	33.7 - 36.7	Ascending	01 Aug., 02 Aug.
22-08-2018	FQ15W	33.7 - 36.7	Ascending	22 Aug., 23 Aug.
15-09-2018	FQ15W	33.7 - 36.7	Ascending	14 Sep., 15 Sep.
09-10-2018	FQ15W	33.7 - 36.7	Ascending	08 Oct., 09 Oct.
02-11-2018	FQ15W	33.7 - 36.7	Ascending	02 Nov., 03 Nov.
26-11-2018	FQ15W	33.7 - 36.7	Ascending	25 Nov., 26 Nov.

178

179 **3. Methodology**

180 *3.1. GRVI Formulation*

In PolSAR theory, the Radar Vegetation Index (RVI) proposed by Kim and van Zyl (2009) uses the eigenvalue spectrum obtained from the coherency \mathbf{T} matrix (van Zyl, 2011). It is expressed as (1):

$$RVI = \frac{4 \min(\lambda_1, \lambda_2, \lambda_3)}{\lambda_1 + \lambda_2 + \lambda_3} \quad (1)$$

181 where λ_i denotes the i -th eigenvalue of \mathbf{T} , $i = 1, 2, 3$.

In PolSAR scattering theory, the 4×4 real Kennaugh matrix \mathbf{K} for incoherent targets is expressed in terms of the elements of the coherency matrix \mathbf{T} as,

$$\mathbf{K} = \begin{bmatrix} \frac{T_{11}+T_{22}+T_{33}}{2} & \Re(T_{12}) & \Re(T_{13}) & \Im(T_{23}) \\ \Re(T_{12}) & \frac{T_{11}+T_{22}-T_{33}}{2} & \Re(T_{23}) & \Im(T_{13}) \\ \Re(T_{13}) & \Re(T_{23}) & \frac{T_{11}-T_{22}+T_{33}}{2} & -\Im(T_{12}) \\ \Im(T_{23}) & \Im(T_{13}) & -\Im(T_{12}) & \frac{-T_{11}+T_{22}+T_{33}}{2} \end{bmatrix} \quad (2)$$

182 where \Re and \Im denote the real and imaginary part of a complex number.

The GRVI proposed in Ratha et al. (2019) uses a similarity measure between the observed \mathbf{K} and the Kennaugh matrix, \mathbf{K}_v associated with the generalized volume scattering model (Antropov et al., 2011), which is used

as a reference model for the scattering from vegetation (3):

$$\mathbf{K}_v = \frac{1}{\frac{3(1+\gamma)}{4} - \frac{\sqrt{\gamma}}{6}} \begin{bmatrix} \frac{3}{2}(1+\gamma) - \frac{\sqrt{\gamma}}{3} & \gamma - 1 & 0 & 0 \\ \gamma - 1 & \frac{1}{2}(1+\gamma) + \frac{\sqrt{\gamma}}{3} & 0 & 0 \\ 0 & 0 & \frac{1}{2}(1+\gamma) + \frac{\sqrt{\gamma}}{3} & 0 \\ 0 & 0 & 0 & \frac{1}{2}(1+\gamma) - \sqrt{\gamma} \end{bmatrix} \quad (3)$$

The GVSM proposed in Antropov et al. (2011) is represented by two parameters: γ and ρ , which correspond to the co-polarized ratio and the correlation coefficient (fixed at $\rho = 1/3$), respectively. The similarity measure is derived from the geodesic distance (Ratha et al., 2018) between observed \mathbf{K} and a reference Kennaugh matrix \mathbf{K}_i :

$$f_i = 1 - \text{GD}(\mathbf{K}, \mathbf{K}_i), \quad (4)$$

where GD denotes the geodesic distance between two Kennaugh matrices \mathbf{K}_1 and \mathbf{K}_2 on the unit sphere. It is defined as:

$$\text{GD}(\mathbf{K}_1, \mathbf{K}_2) = \frac{2}{\pi} \cos^{-1} \frac{\text{Tr}(\mathbf{K}_1^T \mathbf{K}_2)}{\sqrt{\text{Tr}(\mathbf{K}_1^T \mathbf{K}_1)} \sqrt{\text{Tr}(\mathbf{K}_2^T \mathbf{K}_2)}} \quad (5)$$

183 where Tr denotes the trace of a matrix and the superscript T denotes the
184 matrix transpose. The $2/\pi$ factor is used to normalize its range to $[0, 1]$.

In the formulation of GRVI (6), the similarity measure, f_v (7) between the generalized volume scattering model \mathbf{K}_v and the observed Kennaugh matrix \mathbf{K} is obtained using the geodesic distance $\text{GD}_v = \text{GD}(\mathbf{K}, \mathbf{K}_v)$. A modulating parameter β is introduced in (7) which is the ratio of minimum to maximum geodesic distances between \mathbf{K} and elementary targets: trihedral

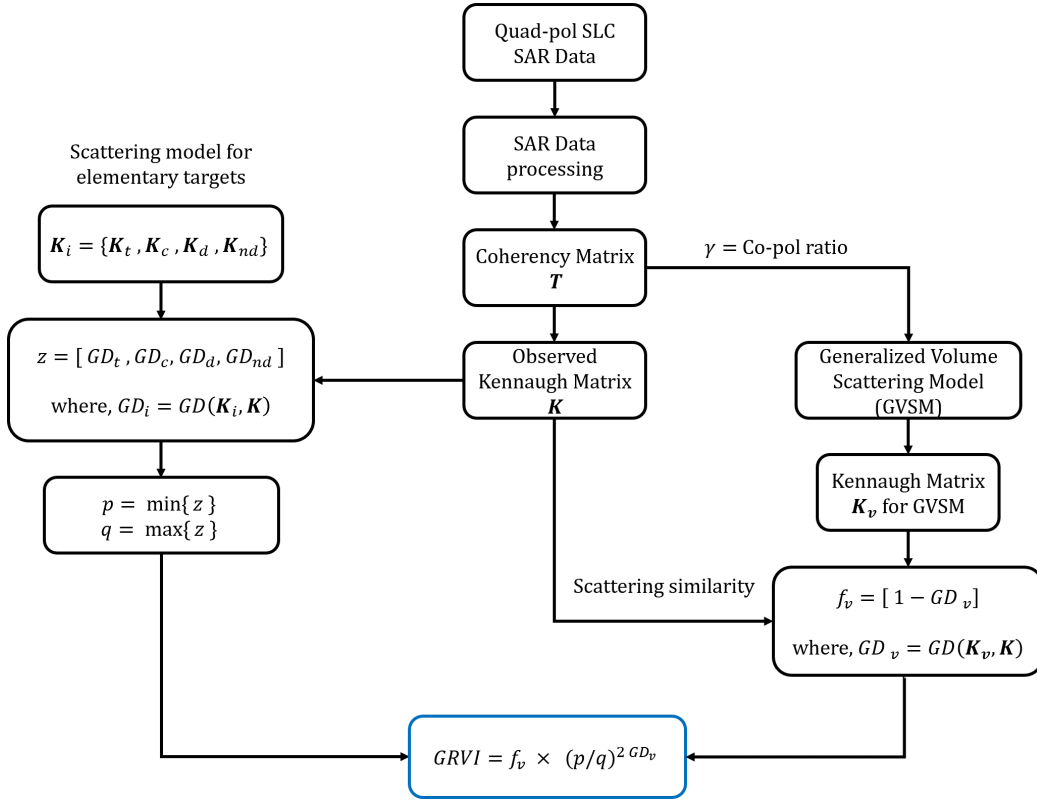


Figure 2: Schematic workflow for the Generalized volume scattering model based Radar Vegetation Index (GRVI) formulation.

(\mathbf{K}_t) , cylinder (\mathbf{K}_c) , dihedral (\mathbf{K}_d) , and narrow dihedral (\mathbf{K}_{nd}) as given in (8). The Kennaugh matrix forms of these elementary targets are shown

in Ratha et al. (2019).

$$\text{GRVI} = \beta f_v, \quad 0 \leq \text{GRVI} \leq 1, \quad (6)$$

$$f_v = (1 - \text{GD}_v), \quad \beta = \left(\frac{p}{q}\right)^{2\text{GD}_v}, \quad (7)$$

$$p = \min \begin{bmatrix} \text{GD}(\mathbf{K}, \mathbf{K}_t) \\ \text{GD}(\mathbf{K}, \mathbf{K}_c) \\ \text{GD}(\mathbf{K}, \mathbf{K}_d) \\ \text{GD}(\mathbf{K}, \mathbf{K}_{nd}) \end{bmatrix}, \quad q = \max \begin{bmatrix} \text{GD}(\mathbf{K}, \mathbf{K}_t) \\ \text{GD}(\mathbf{K}, \mathbf{K}_c) \\ \text{GD}(\mathbf{K}, \mathbf{K}_d) \\ \text{GD}(\mathbf{K}, \mathbf{K}_{nd}) \end{bmatrix} \quad (8)$$

185 The two extreme cases of GRVI viz., $\text{GRVI} = 0$ and $\text{GRVI} = 1$ correspond
 186 to $\mathbf{K} \in \{\mathbf{K}_t, \mathbf{K}_c, \mathbf{K}_d, \mathbf{K}_{nd}\}$ and $\mathbf{K} = \mathbf{K}_v$, respectively. A schematic workflow
 187 of the GRVI is provided in Fig. 2.

188 3.2. Preprocessing of SAR data

189 In this study, seven RADARSAT-2 images (Table 1) were acquired in
 190 SLC format. The RADARSAT-2 SLC product in FQ15W beam mode has
 191 range and azimuth pixel spacing of 4.73 m and 5.11 m, which correspond to
 192 a nominal resolution equal to 5.2 m and 7.6 m in ground-range and azimuth
 193 directions, respectively (Slade, 2018). The full-polarimetric images are mul-
 194 tilooked by 2×2 (in the range and azimuth) to generate the coherency matrix
 195 \mathbf{T} , with the spatial resolution of 10.4 m and 15.2 m. The elements of the \mathbf{T}
 196 matrix are then used to calculate the Kennaugh matrix \mathbf{K} as discussed in
 197 Sec. 3.1. The GRVI images are generated from the derived \mathbf{K} for each acqui-
 198 sition over a 7×7 moving overlapping window. The GRVI images are then
 199 co-registered using ground control points (GCP) with an RMSE ≤ 0.54 m

200 and geocoded with an output pixel size of 10 m and 10 m on the ground. A
201 comparative analysis is performed for the full crop season between GRVI and
202 RVI. The RVI obtained from the \mathbf{T} matrix over a 7×7 moving overlapping
203 window is co-registered using GCPs with an RMSE of approx. 0.53 m. The
204 GRVI and RVI values for each sampling location (point measurements) are
205 extracted over a 3×3 window.

206 4. Results and discussion

207 The vegetation indices (both the GRVI and RVI) for different sampling
208 sites are generated from the RADARSAT-2 quad-pol data set, and the tem-
209 poral analysis is performed at different growth stages for TR and DSR. Figs. 3
210 and 10 plot the temporal trends of GRVI and RVI, averaged for the two sam-
211 pling points in each plot. Furthermore, the correlation of radar vegetation
212 indices with PAI ($\text{m}^2 \text{m}^{-2}$) is analyzed for each rice type. In total, 102 sam-
213 ples from 20 TR fields and 200 samples from 41 DSR fields are used for the
214 correlation analysis (Fig. 8 and 12). The significance tests are performed
215 along with the correlation analysis. Linear regression models are also devel-
216 oped for PAI estimation, with independent training and validation datasets
217 using these vegetation indices.

218 4.1. Transplanted rice (TR)

219 The temporal responses of GRVI over the phenological stages of trans-
220 planted rice fields are shown in Fig. 3. From the TR fields, 8 representative
221 fields (field numbers: 024, 044, 063, 141, 151, 153, 174, 113) distributed
222 throughout the region are used for the temporal analysis. These analyses
223 are also supported with in-situ measurements of PAI. A primary qualitative

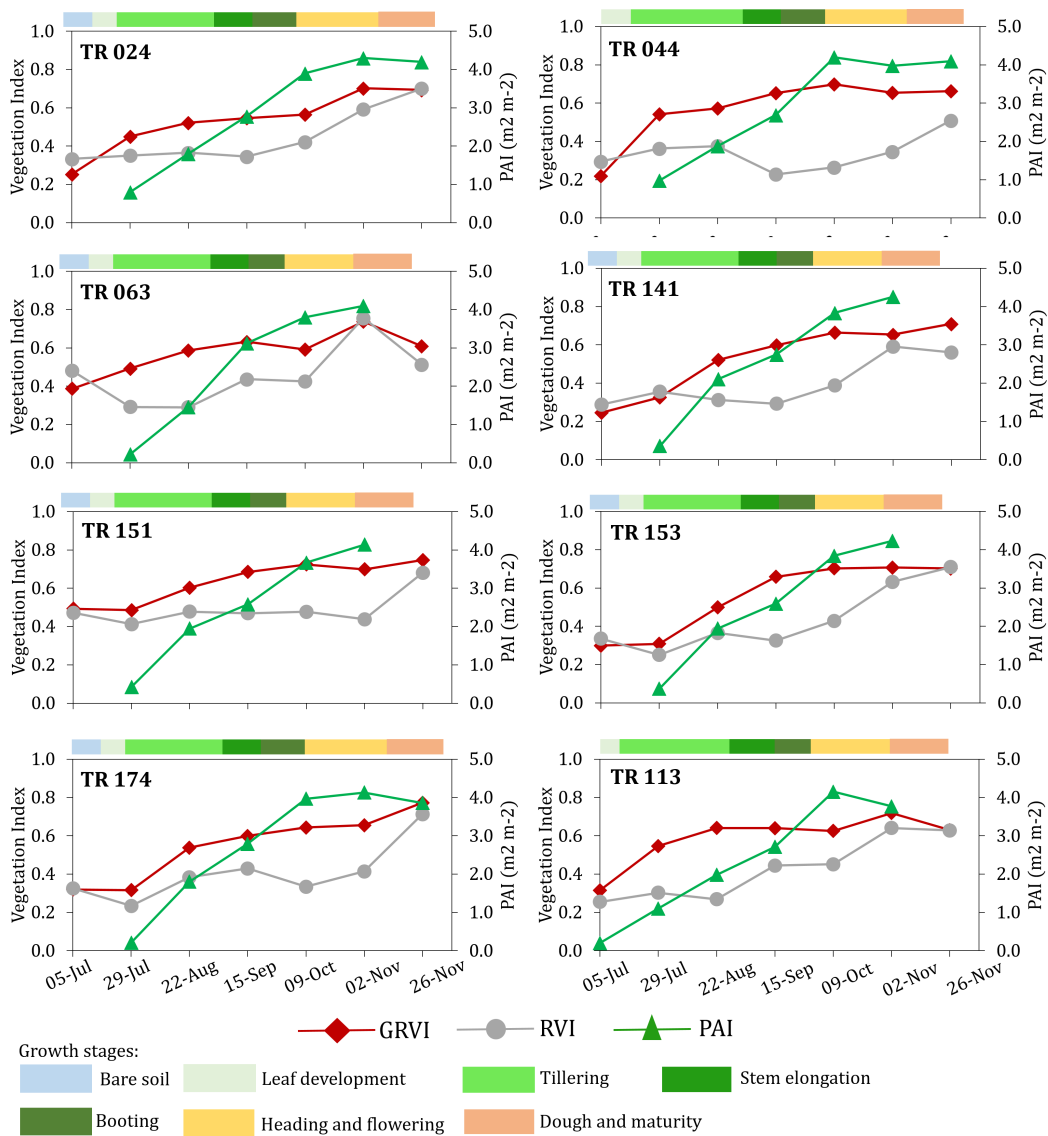


Figure 3: Temporal pattern of GRVI and RVI for transplanted rice (TR) fields at different growth stages. The in-situ measurements of Plant Area Index (PAI, $m^2 m^{-2}$) are plotted on the secondary axis for each field.

224 analysis indicates that the growth trends of rice are similar irrespective of
 225 field numbers; PAI increases as the rice crop develops.

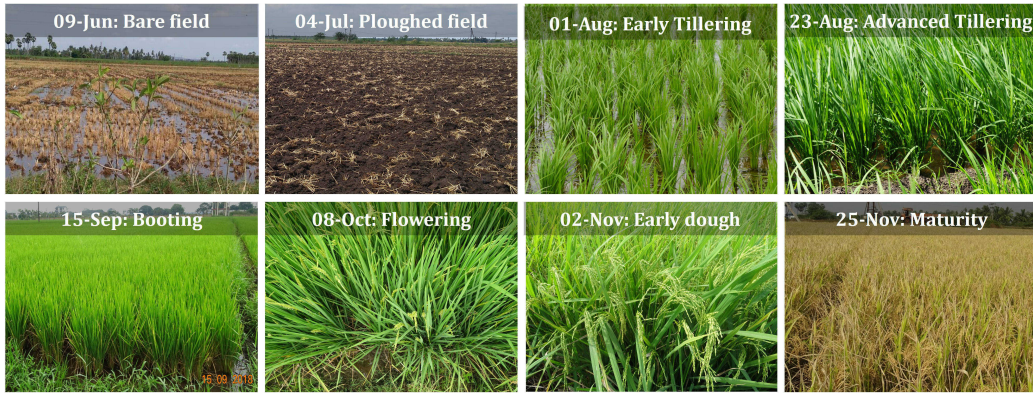


Figure 4: Field conditions of a transplanted rice (TR) during the campaign.

226 At the field preparation stage (on 05 July), although the plant develop-
 227 ment has not yet started (Fig. 4), both the GRVI and RVI values are high
 228 (within a range of 0.25-0.35). Theoretically, for the bare field condition (sim-
 229 ilar to a trihedral type scattering) the GRVI lies close to zero (Ratha et al.,
 230 2019). However, the relatively high values of the indices are likely due to
 231 soil roughness as compared to the 5.6 cm C-band wavelength. The in-situ
 232 measurements confirmed that the soil roughness was high due to the tillage
 233 operations.

234 With crop establishment completed by 29 July, the GRVI values start to
 235 increase monotonically. At the early tillering stage (29 July), the magnitude
 236 of GRVI is $\lesssim 0.4$ for the majority of the plots. However, for TR044 and
 237 TR113, a sharp increase in GRVI (up to 0.57) is observed on 29 July. This
 238 increase may be due to development of more number of tillers as these fields
 239 were more advanced with an active tillering stage with $PAI \sim 1.0 \text{ m}^2 \text{ m}^{-2}$.
 240 The GRVI continues to increase on 22 August when the majority of rice
 241 fields are in their active to the end of the tillering stage. These high GRVI

242 values may be due to the high degree of randomness in scattering from the
243 canopy elements during the tillering stages. Also, the underlying water may
244 contribute to both the volume and even-bounce scattering components.

245 The GRVI values reached a maximum (approx. 0.75) when the crop ad-
246 vanced to its heading and flowering stages on 09 October. The in-situ mea-
247 surements reported PAI of up to approximately $4.2 \text{ m}^2 \text{ m}^{-2}$. This increase in
248 the GRVI values indicates the dominance of volume scattering in the fields
249 which might increase the similarity between the observed \mathbf{K} and the \mathbf{K}_v of
250 the GVSM. However, changes in GRVI values after the heading stage are
251 not apparent. During the dough and maturity stages, the GRVI values are
252 still high, which may be a function of volume scattering from the upper
253 canopy elements of rice. During the heading to maturity stages of rice with
254 ears emerging, multiple scattering dominates within the total backscattered
255 power in C-band (Kumar and Rao, 2015). Similar observations with volume
256 scattering power for the temporal response of rice are reported in Li et al.
257 (2012). The volume scattering power derived from the Freeman-Durden de-
258 composition applied to RADARSAT-2 is stable from the heading to maturity
259 stage of rice. The high entropy values ($H \sim 0.8$) and an average scattering
260 type α of approximately 50° is also in accordance with these observations
261 during these growth stages (Li et al., 2012).

262 Another important aspect for rice monitoring is the lodging effect, which
263 is pronounced during the reproductive to maturity stage. Lodging effects
264 are often due to heavy grains load, loosening stem strength, and high wind.
265 Representative fields in this category where lodging was observed are TR141
266 and DSR205 in November. The GRVI values in the temporal plots also

267 indicate this effect with comparatively lower values than the high vegetative
 268 stage (09 Oct).

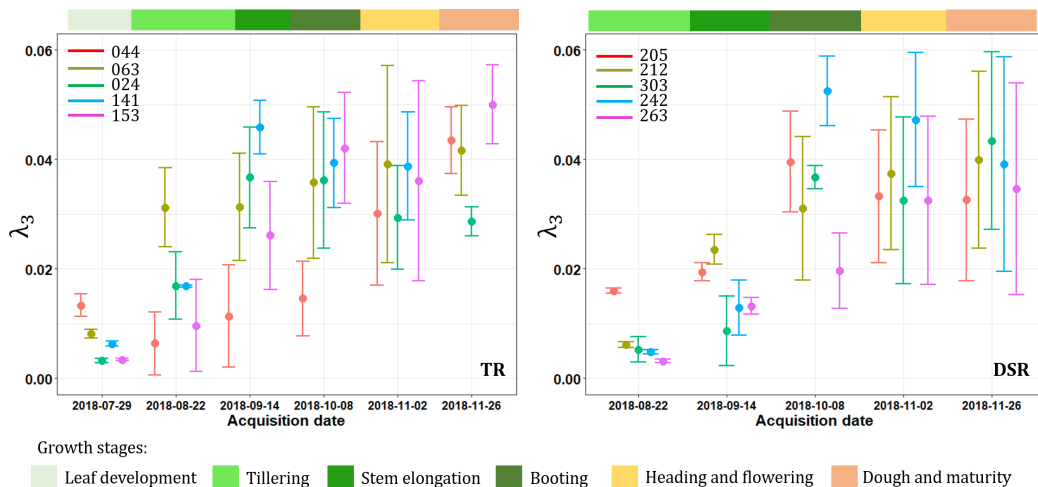


Figure 5: Temporal pattern of third eigenvalue (λ_3) derived from coherency matrix (T) for transplanted rice (TR) and direct seeded rice (DSR) fields at different growth stages.

269 The increase in RVI values is less apparent during the vegetative stage
 270 of the rice crop, as compared to GRVI. The dynamic range of RVI through
 271 the rice growth period is also lower when compared with the range associ-
 272 ated with GRVI. An issue to consider with RVI is its formulation from the
 273 eigenvalue spectrum. The numerator in (1) i.e., third eigenvalue, λ_3 is more
 274 affected by noise rather than changes with vegetation randomness. It is also
 275 apparent from Fig. 5 that the standard deviation of λ_3 increases as the rice
 276 crop advances from the early tillering stage (22 August) to dough and ma-
 277 turity, although its mean value increases with PAI and plant growth. The
 278 structural heterogeneity of plants during the reproductive to maturity stage
 279 might lead to a spatial variance within a plot (Yuzugullu et al., 2018). He
 280 et al. (2018) also reported similar heterogeneity in the backscatter signal,

281 which was influenced by the planting density of rice.

282 Compared to radar vegetation indices, the variations in the backscatter
283 intensities in different polarization channels are apparent during different
284 growth stages. In order to check the consistency of C-band measurements
285 for the current acquisitions, we evaluated the backscatter intensities in co-
286 (HH, VV) and cross-pol (HV) channels, as shown in Fig. 6 and 11. These
287 investigations exclusively on the temporal trends of backscatter intensities
288 with plant growth are not new. However, they constitute the principal of
289 most of the experiments carried out in the literature for rice mapping and
290 monitoring with radar data.

291 For transplanted rice, it is observed that the backscatter intensity in co-
292 pol channels (HH and VV) are very low on 29 July in majority of the fields,
293 as shown in Fig. 6. It is likely due to low vegetation growth during the
294 early leaf development stage and the underlying inundated field condition.
295 The backscatter powers increased during the tillering and stem elongation
296 stage. The double-bounce scattering mechanism becomes stronger due to
297 the interaction between the rice stems and the underlying water surface.
298 This means a lower backscatter power in the VV polarization channel be-
299 cause of its stronger attenuation than HH resulting from the vertical rice
300 plants. This difference between the co-pol channels was reported by their
301 ratio in (Lopez-Sanchez et al., 2014). Concerning the cross-pol response,
302 it indicated lower value than the co-pol channels, but also exhibits a high
303 growth as plants canopy develops. From the heading stage onward, the vari-
304 ation of the backscattering intensities is less pronounced than the previous
305 phenological stages. The backscatter responses slowly decrease for both po-

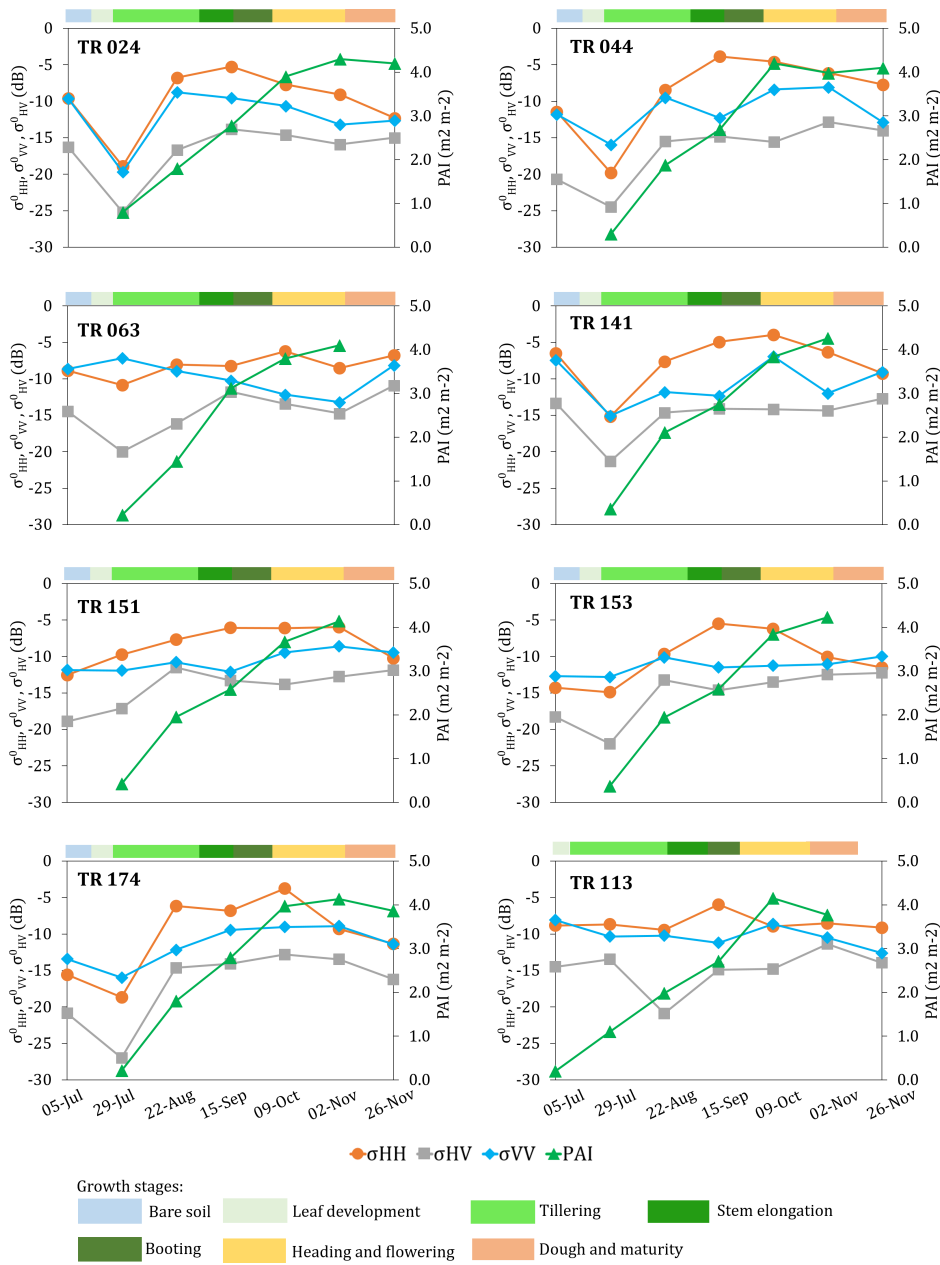


Figure 6: Temporal pattern of backscatter intensities in the HH, VV, and HV channels for transplanted rice (TR) fields at different growth stages. The in-situ measurements of Plant Area Index (PAI, m² m⁻²) are plotted on the secondary axis for each field.

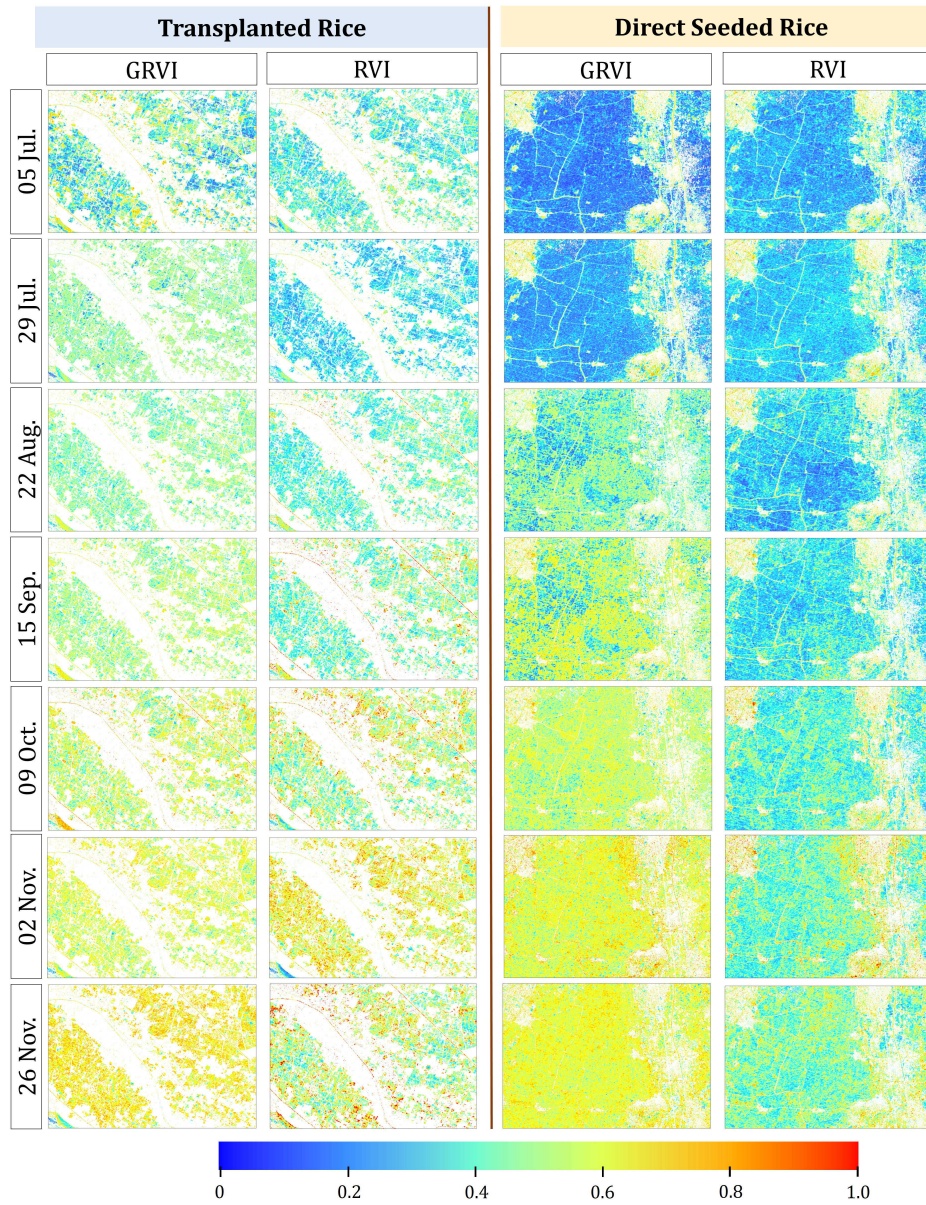


Figure 7: GRVI and RVI maps over the test site for seven acquisitions (05 Jul., 29 Jul., 22 Aug., 15 Sep., 09 Oct., 02 Nov., and 26 Nov.) of RADARSAT-2. Two subsets (Region A and Region B, in Fig. 1) are highlighted for the direct seeded rice and transplanted rice.

306 larizations during the maturity stage as the rice plants gradually wither and
 307 water content decreases. The temporal trends at different polarization chan-
 308 nels plotted in Fig. 4 agree with the well-known response from rice fields at
 309 C-band radar systems, which are reported in literature (Le Toan et al., 1997;
 310 Inoue et al., 2002; Bouvet et al., 2009; Lopez-Sanchez et al., 2011, 2014).

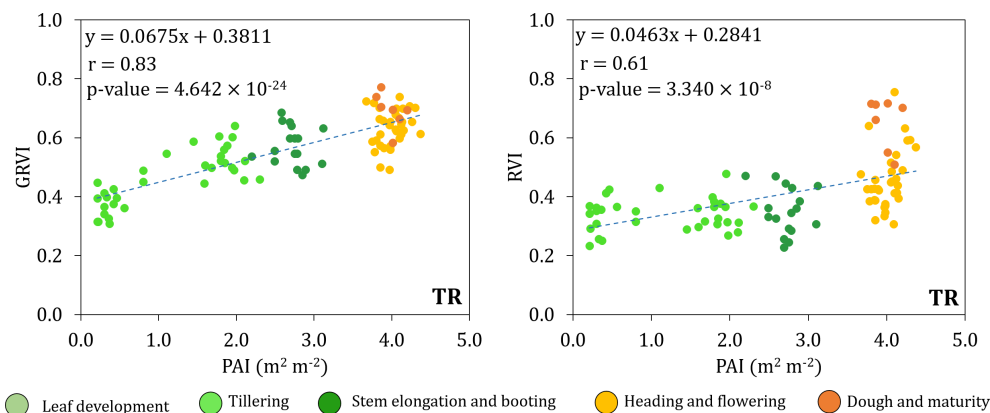


Figure 8: Correlations (r) between vegetation indices (GRVI and RVI) and plant area index (PAI, m^2m^{-2}) for transplanted rice (TR). Samples from several phenological stages are highlighted by different colours.

311 The GRVI maps for the seven acquisition dates are shown in Fig. 7 over a
 312 subset of the test site (Region-B in Fig. 1). Both spatial and temporal vari-
 313 ability is observed in these maps, which are similar to the temporal behavior
 314 of transplanted rice, as shown in Fig. 3. The qualitative comparison between
 315 RVI and GRVI maps for the seven acquisition dates (Fig. 7 over a subset
 316 of the test site Region-B) confirms the superior performance of GRVI. The
 317 correlation analysis of GRVI and RVI with PAI is shown in Fig. 8 for differ-
 318 ent phenological stages of transplanted rice. The correlation coefficient (r)
 319 of GRVI with PAI is 0.83, higher than that of RVI ($r = 0.61$). In particular,
 320 GRVI outperforms RVI for the period from tillering to booting with stronger

321 correlation, as lower variance associated with GRVI. As the transplanted rice
322 starts heading and moves to maturity, a higher variance is observed for RVI.
323 As previously stated, this higher variance may be due to the noisy values
324 associated with λ_3 . Variations in the vegetation indices during later growth
325 stages may be explained by scattering from the upper canopy layer along
326 with the saturation of PAI.

327 *4.2. Direct Seeded Rice (DSR)*

328 Direct seeding of the rice crop is gaining importance in the semi-arid
329 regions of India. Differences in extent, timing, and duration of standing
330 water in DSR plots, as compared to that of conventional TR cultivated plots,
331 will impact SAR scattering characteristics. DSR cultivation begins with
332 the preparation of a smooth seedbed for direct sowing, in order to promote
333 proper seed establishment (Fig. 9). The temporal response of GRVI over
334 the phenological stages of DSR fields are shown in Fig. 10. Amongst several
335 DSR fields, 8 representative fields (field numbers: 205, 212, 242, 253, 271,
336 285, 263 and 303), distributed throughout the region, are presented. The
337 response of GRVI is compared to that of RVI, with in-situ measured PAI
338 aiding in the interpretation of these results. As with the TR cultivation, the
339 growth trends of DSR plots are similar irrespective of the field numbers; an
340 increase of PAI with crop development.

341 It is apparent from Fig. 10 that GRVI increases monotonically as crop
342 establishment is completed by 22 August. Here, it is important to note
343 that crop development to tillering is delayed in DSR (up to 15 September)
344 as compared to TR. Unlike seedling transplanted from the nursery-bed to
345 main plots flooded with water in TR cultivation, for DSR plants emerge



Figure 9: Field conditions of a direct seeded rice (DSR) during the campaign.

346 directly from the sown seeds in the main plot. Hence, crop establishment
 347 and accumulation of peak PAI are generally delayed. This delay is apparent
 348 in the temporal PAI plots shown in Fig. 10.

349 At the early tillering stage (on 22 August) the magnitude of GRVI is <0.4
 350 for the majority of the plots. GRVI continues to increase during the vege-
 351 tative stage and ends at booting around 09 October. GRVI values reach a
 352 maximum (approx. 0.62-0.75) at heading and flowering stages on 02 Novem-
 353 ber. The in-situ measurements of PAI during this period confirm an increase
 354 in PAI to approximately $4.3 \text{ m}^2 \text{ m}^{-2}$. However, changes in GRVI values after
 355 the heading stage are not apparent (02 November). Also, during the dough
 356 and maturity stages, both the GRVI and RVI values are inconsistent among
 357 different fields. The GRVI maps over a subset of the test site (Region-A
 358 in Fig. 1) also qualitatively confirm variability both in spatial and temporal
 359 scale (Fig. 7). Moreover, the changes indicated by GRVI are more apparent
 360 in the DSR region than the TR area, which may be due to complex scattering
 361 phenomena in TR fields given the presence of standing water.

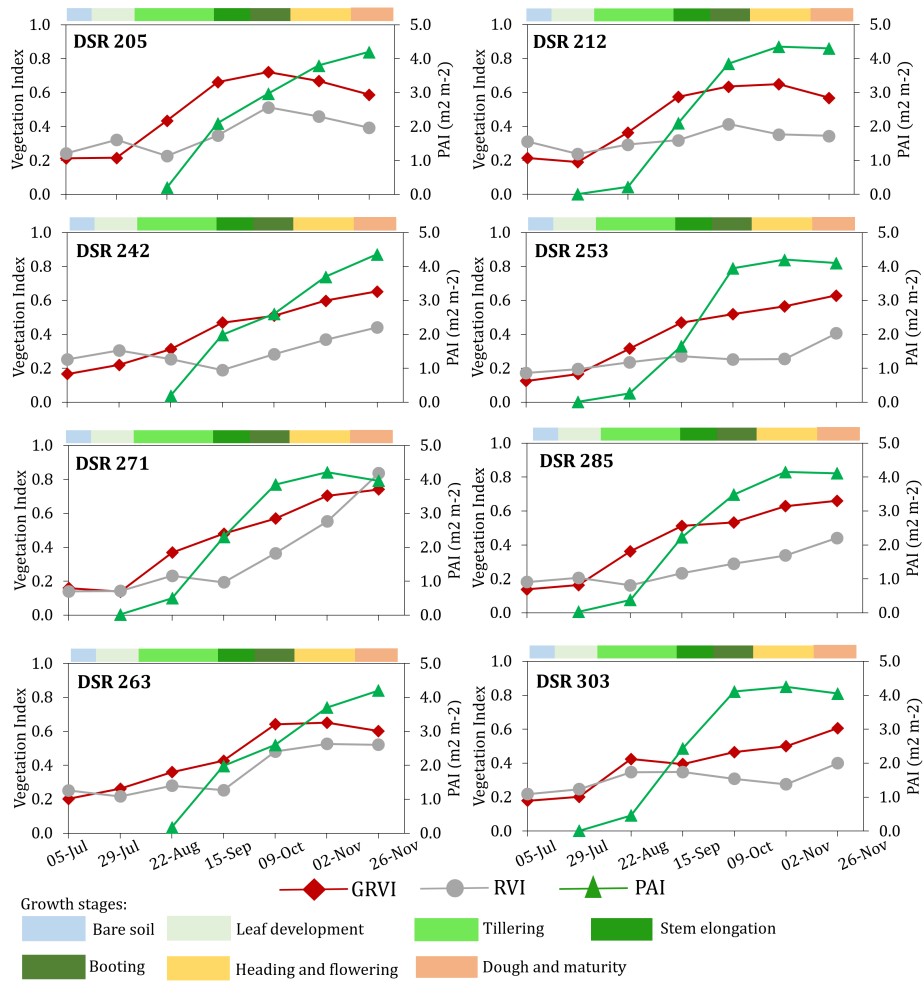


Figure 10: Temporal pattern of GRVI and RVI for direct seeded rice (DSR) fields at different growth stages. The in-situ measurements of PAI, $m^2 m^{-2}$ are plotted in secondary axis for each field.

362 Similar to the TR backscatter signal, the DSR plots also indicate backscat-
 363 ter intensity variations with phenological stages (Fig. 11). However, during
 364 the early leaf development stage, the backscatter powers are notably higher
 365 than the majority of TR fields. It is likely due to the delayed plant de-
 366 velopment up to tillering stage. The in-situ measurements also confirm a

367 delayed accumulation of peak PAI for DSR fields. This delay is apparent in
 368 the temporal PAI and backscatter intensity plots shown in Fig. 11.

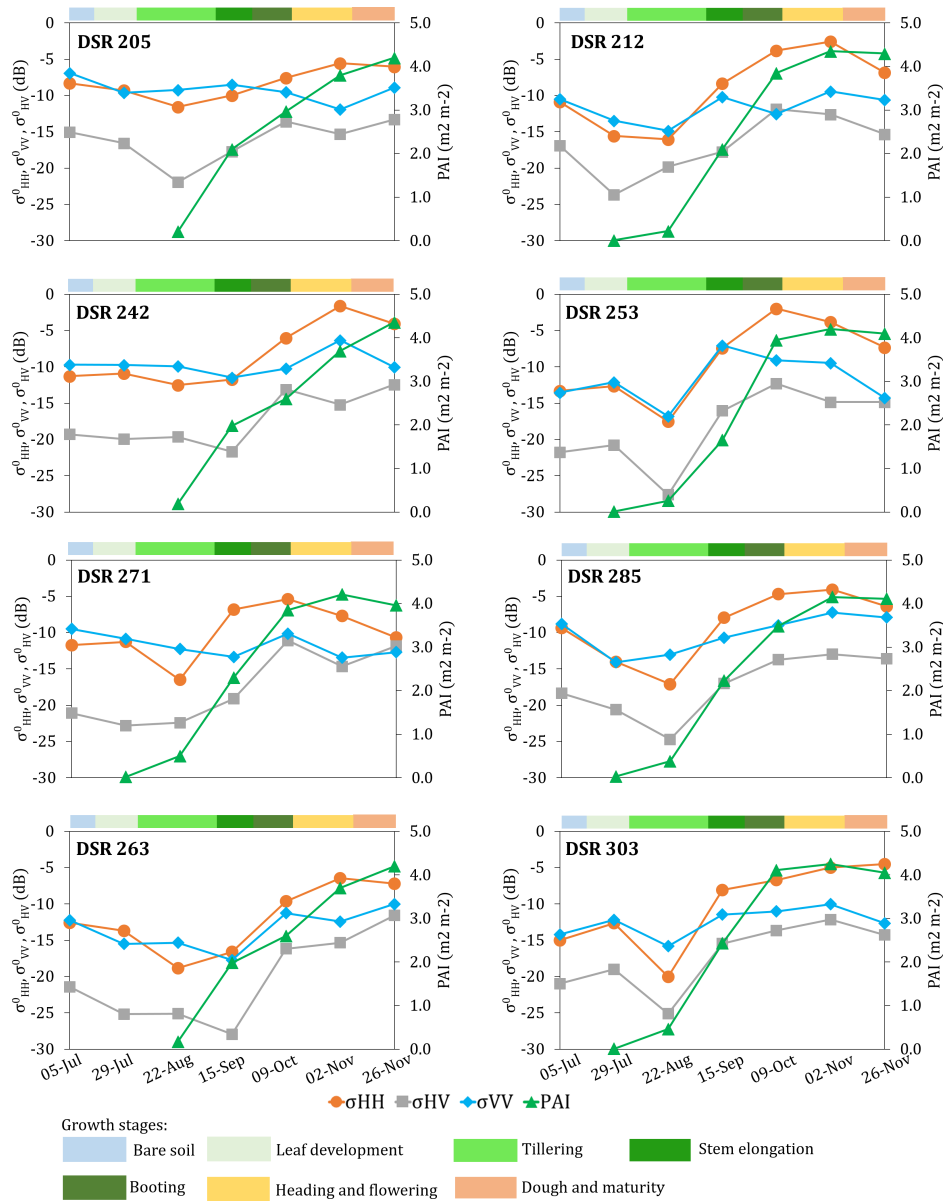


Figure 11: Temporal pattern of backscatter intensities in the HH, VV, and HV channels for direct seeded rice (DSR) fields at different growth stages. The in-situ measurements of Plant Area Index (PAI, m² m⁻²) are plotted on the secondary axis for each field.

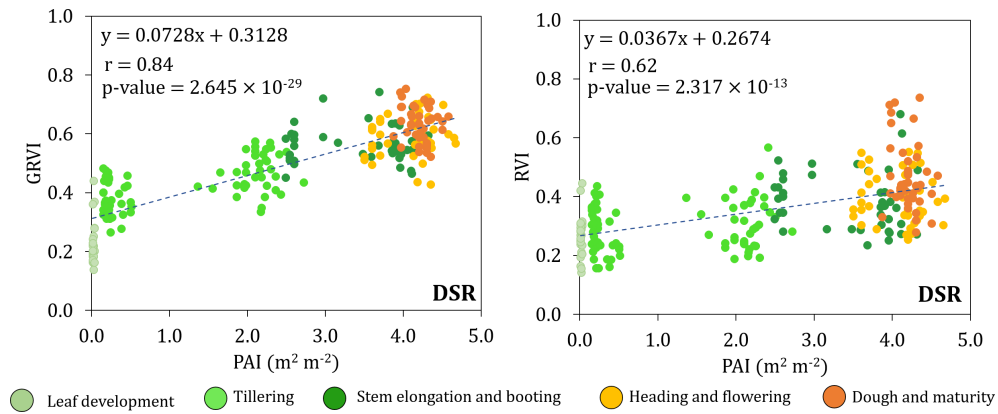


Figure 12: Correlations (r) between vegetation indices (GRVI and RVI) with plant area index (PAI, m^2m^{-2}) for direct seeded rice (DSR). Samples from several phenological stages are highlighted in different colours.

369 Increases in RVI throughout the phenological stages of rice development
 370 are different when compared to GRVI. The dynamic range of RVI is lower
 371 relative to GRVI, throughout the entire growing period. As well, the corre-
 372 lation analysis of GRVI shows its competence with RVI as given in Fig. 12.
 373 The correlation coefficient (r) of GRVI with PAI is 0.84, significantly higher
 374 than the correlation between RVI and PAI ($r = 0.62$). The GRVI of DSR
 375 fields is more sensitive to the changes in PAI, relative to RVI, as was also
 376 observed with the responses from the TR fields. This improved sensitivity
 377 was particularly noted for the tillering to booting stages. As the DSR crop
 378 advanced from the heading to maturity stages, the responses associated with
 379 RVI had higher variance. This increased variance is likely due to the nature
 380 of λ_3 , as shown in Fig. 5. It is worth mentioning that in addition to volume
 381 scattering, the double bounce scattering mechanism is also one of the major
 382 contributors to the total backscatter power given the erectophile geometry
 383 of rice crops. This characteristic may lead to low signal to noise ratio (SNR)

384 for the third eigenvalue. On the other hand, the GRVI suitably takes into
385 account the GVSM parameters along with the modulation parameter β (7)
386 to better capture changes in the crop morphology.

387 *4.3. Potential of TR and DSR discrimination*

388 In addition to the temporal dynamics of vegetation indices, it is also inter-
389 esting to evaluate the characterization capability of VIs for both rice types.
390 The literature reports that techniques to characterize rice growth depend
391 primarily on the detection of the backscattered signal from the underlying
392 water at the start of the growing season (Le Toan et al., 1997; Nelson et al.,
393 2014; Mandal et al., 2018). These techniques are typical of transplanted rice
394 (TR) cultivation. In contrast, the DSR cultivation includes alternate wet-
395 ting and drying of the soil, without extended periods of standing water. This
396 difference in the cultivation practice is challenging to characterize with SAR
397 backscatter coefficients (Fikriyah et al., 2019).

398 In principle, it would be possible to characterize differences between cul-
399 tivation practices early in the rice growing season. Even though limited
400 investigations have focused on the discrimination of rice cultivation practices
401 using SAR, it is imperative to focus on the period of land preparation to
402 the tillering and stem elongation stages (Choudhury and Chakraborty, 2006;
403 Yang et al., 2017; Phan et al., 2018).

404 A recent study by Fikriyah et al. (2019), using C-band dual-pol Sentinel-1
405 backscatter intensities, demonstrated that TR and DSR cultivation practices
406 could be discriminated. In our experiment, even though the correlation of
407 PAI with vegetation indices for TR is similar to that of DSR, the sensitivity of
408 GRVI to PAI varies among phenological stages as shown in Fig. 3 and 10. The

409 spatio-temporal maps (Fig. 7) also highlight variations between TR and DSR
410 regions at early growing to late vegetative stages. However, the vegetation
411 indices appeared similar for TR and DSR fields during heading to maturity
412 stages. Nevertheless, the discrimination capability of GRVI is superior to
413 that of RVI for qualitative assessment of rice cultivation practices.

414 4.4. PAI estimation from vegetation indices

415 The retrieval of PAI from PolSAR observations is of significant impor-
416 tance for in-season monitoring of crop growth. The PAI is correlated directly
417 with canopy foliage and structure (Jonckheere et al., 2004), which is a valu-
418 able indicator of crop condition. The PAI estimation from the vegetation
419 indices is achieved via linear regression. Other researchers (Becker-Reshef
420 et al., 2010; Jiao et al., 2011; Kogan et al., 2013; Liao et al., 2018) have
421 utilized linear regression for the operational scalability of remote sensing
422 products for vegetation monitoring. In spite of their localized application,
423 linear regression techniques are often the preferred approach owing to their
424 limited data requirements and simplicity to implement. Conversely, a higher-
425 order polynomial may lead to an over-fitting problem that would likely fail
426 to generalize on the test data set. Nevertheless, considering that the correla-
427 tions between the GRVI and PAI are high (> 0.80) for both the TR and DSR
428 (Fig. 8 and 12), the application of linear regression would be a cost-effective
429 approach for PAI estimation from the GRVI.

430 Independent samples are used for training and testing of the regression
431 model. In total 118 samples (from 24 fields) and remaining 80 samples (from
432 16 fields) of DSR are used for training and validation, respectively. In the
433 case of TR cultivation, 65 samples from 12 fields are used for training with the

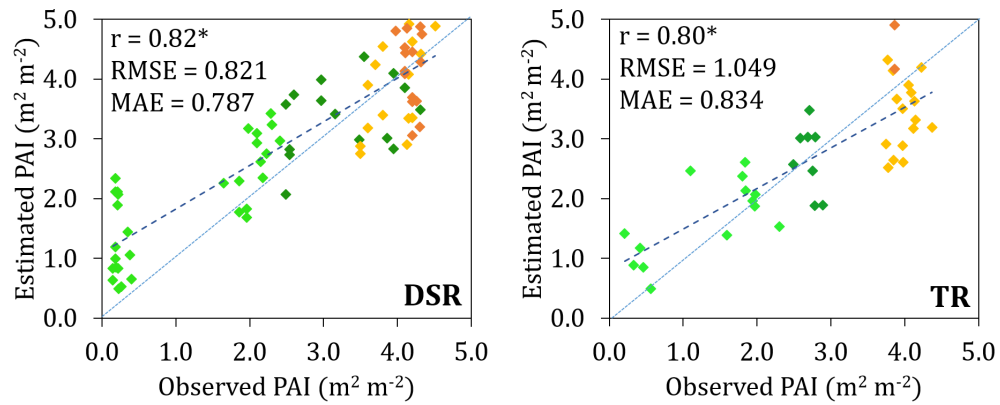
434 remaining 42 samples from 8 fields reserved for validation. It is important to
 435 note that the training and validation points are sampled from all phenological
 436 stages of rice. However, PAI values $<0.15 \text{ m}^2 \text{ m}^{-2}$ are not considered for
 437 training and validation of the model as these samples are likely to be affected
 438 by the underlying soil at the very early plant growth stages.

439 A k-fold (k=3 in this case) cross-validation is performed while estimating
 440 PAI from the radar vegetation indices. In the cross-validation experiment,
 441 the samples are split into multiple pairs of training and test sets. Here it
 442 is important to note that with multi-temporal observations for each in-situ
 443 sampling location, the split of the dataset is based on field numbers. Hence,
 444 random sampling from the entire temporal dataset is not desirable. The PAI
 445 estimation accuracy is assessed for both the DSR and TR cases, with each
 446 having three validation datasets (Table 2). Among them, the best result is
 447 taken for representation in Fig. 13 with a 1:1-plot for GRVI and RVI provided
 448 separately. The accuracy of the PAI retrieval is measured by the correlation
 449 coefficient (r), Root Mean Square Error (RMSE), and Mean Absolute Error
 450 (MAE).

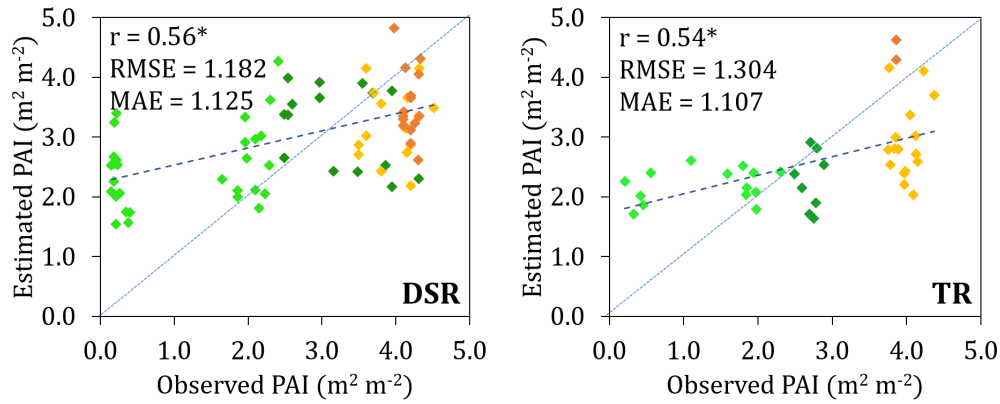
Table 2: Error estimates for PAI retrieval from GRVI using k-fold cross validation techniques for three validation dataset

Rice type	Error estimates	Validation set-1	Validation set-2	Validation set-3
DSR	r	0.810	0.823	0.798
	RMSE	0.835	0.821	0.852
	MAE	0.779	0.787	0.801
TR	r	0.803	0.805	0.789
	RMSE	1.049	1.051	1.102
	MAE	0.834	0.836	0.857

451 For GRVI, the estimated PAI closely follows the 1:1 line with $r = 0.82$,
 452 $\text{RMSE} = 0.821 \text{ m}^2 \text{ m}^{-2}$, and $\text{MAE} = 0.787 \text{ m}^2 \text{ m}^{-2}$ for DSR. The errors of



(a) PAI estimates from GRVI



(b) PAI estimates from RVI

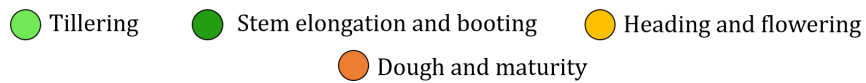


Figure 13: Validation of retrieved and observed Plant Area Index (PAI, m^2m^{-2}) retrieval for direct seeded rice (DSR) and transplanted rice (TR) using radar vegetation indices (GRVI and RVI). Samples from several phenological stages are highlighted in different colours. The correlation coefficient (r) values are significant with p -value < 0.05 for all these four cases.

453 estimation are comparatively higher (RMSE = $1.049 \text{ m}^2 \text{ m}^{-2}$, and MAE =
 454 $0.834 \text{ m}^2 \text{ m}^{-2}$) in the case of TR. In comparison to GRVI, the errors asso-
 455 ciated with estimates of PAI are higher when using RVI, regardless of rice

456 type. Correlation coefficients are also low for both DSR ($r = 0.56$) and TR
457 ($r = 0.54$) cases. Higher dispersion of PAI estimates are observed with RVI
458 throughout the entire range. This estimation error with PAI may have prop-
459 agated from the training phase of the linear regression model between RVI
460 and PAI.

461 Although PAI is more accurately estimated using GRVI, overestimation
462 occurs in the early vegetative stages of both the rice types. At this early
463 stage, the backscatter response is dominated by soil moisture due to low
464 leaf area (Ulaby et al., 1984). This phenomenon is also reported for PAI
465 estimation in the early stages of wheat (Mandal et al., 2019a; Ratha et al.,
466 2019). On the other hand, the estimation accuracy of PAI derived from
467 GRVI improves during more advanced stages, e.g., tillering to booting stage.
468 At a high canopy density, this improved performance is likely due to the
469 dominant volume scattering component generated from multiple interactions
470 of the radar wave with stems, leaves, and the underlying soil (Brown et al.,
471 2003).

472 **5. Conclusion**

473 The potential of using the Generalized volume scattering model based
474 Radar Vegetation Index (GRVI) for determining rice growth condition from
475 C-band SAR has been examined in this research. The temporal analysis of
476 the GRVI derived from quad-pol RADARSAT-2 data suggests that this veg-
477 etation index follows crop growth development, i.e., increasing as the Plant
478 Area Index (PAI) of rice increases. Correlation analysis is performed be-
479 tween the radar vegetation indices (RVI and GRVI) and PAI using samples

480 from several phenological stages of rice. These results indicate that GRVI is
481 highly correlated with rice development, as compared to RVI. Unlike RVI,
482 the GRVI follows the advancement of plant growth stages until full canopy
483 development, and as plant area accumulates. In addition, the dynamic range
484 of RVI is less than that of GRVI when rice advances from an early vegetative
485 to heading stage. It also confirms the improved characterization potential of
486 GRVI compared to RVI. Qualitatively, the improved range and sensitivity of
487 GRVI to rice development is observed in the spatio-temporal maps produced
488 using this index. PAI is accurately estimated using a linear regression model
489 for GRVI with promising error estimates for both the Direct Seeded Rice
490 (DSR) and Transplanted Rice (TR). The correlation between the observed
491 and estimated PAI from the GRVI-PAI linear regression model indicates a
492 higher correlation coefficient ($r > 0.80$) for both rice type. The error esti-
493 mates (RMSE and MAE) are also lower than that of the PAI estimates from
494 an RVI-PAI model. Moreover, unlike RVI, the GRVI is able to distinguish
495 between DSR and TR fields.

496 The application of GRVI, derived from C-band quad-pol SAR data, would
497 be of interest for operational monitoring of rice production. Due to its sim-
498 plistic and tractable formulation, the GRVI could be implemented at larger
499 spatial scales. However, a reduced swath coverage and temporal revisit fre-
500 quency associated with these quad-pol measurements would challenge opera-
501 tional activity. Nonetheless, a similar concept for the derivation of vegetation
502 index based on the geodesic distance can be extended for dual and compact-
503 pol SAR data. Considering the operational missions of Sentinel-1, NISAR,
504 RCM, SAOCOM, and upcoming RISAT-1A, it would be important to devise

505 a proxy for vegetation growth indicators with geodesic distance-based indices
506 for these imaging modes.

507 Considering the results presented here, a SAR-based vegetation index
508 could provide an essential source of data for rice growth monitoring, in regions
509 where optical data acquisitions are hindered due to persistent cloud cover.
510 Further testing of this index is warranted and could be accomplished under a
511 collaborative framework for cross-site experiment setups like the SAR inter-
512 comparison experiment within the Joint Experiment for Crop Assessment
513 and Monitoring (JECAM) network and the Asian Rice Crop Estimation and
514 Monitoring (Asia-RiCE) initiatives.

515 *Disclosures*

516 No potential conflict of interest is reported by the authors.

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