

Behavioural investors in conic market models*

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Abstract

We treat a fairly broad class of financial models which includes markets with proportional transaction costs. We consider an investor with cumulative prospect theory preferences and a non-negativity constraint on portfolio wealth. The existence of an optimal strategy is shown in this context in a class of generalized strategies.

1 Introduction

In this paper we continue the investigations of [CR17] where behavioural investors were studied in a model with price impact. In the current work we treat the case of conic models, see [KS09], which subsume foreign exchange markets as well as multi-asset markets with proportional transaction costs.

The mathematical difficulty stems from the fact that behavioural preferences lack concavity and involve probability distortions, see [KT79], [Qui82], [TK92]. Hence, instead of almost sure techniques, we need to employ weak convergence in the arguments. In Theorem 3.2 below we establish the existence of optimizers in a suitable class of generalized strategies. We rely on results of [Jak97], see Theorem 4.1 below.

In Section 2 we present our model. In Section 3 we construct optimal strategies for investment problems with behavioural preferences. Section 4 collects auxiliary material.

2 Conic market model

We will assume throughout the paper that trading takes place continuously in the time interval $[0, 1]$. Let $(\Omega, \mathcal{F}, (\mathcal{H}_t)_{t \in [0,1]}, P)$ be a filtered probability space, where the filtration is complete and right-continuous, \mathcal{H}_0 is trivial. The notation EX will refer to the expectation of the random variable X . If there is ambiguity about the probability measure then $E_Q X$ will denote the expectation of X under the probability Q . Similarly, $\text{Law}(X)$ denotes the law of X and $\text{Law}_Q(X)$ refers to its law under Q . When x, y are vectors in the same Euclidean space then the concatenation xy denotes their scalar product, $|x|$ is the Euclidean norm.

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In the sequel we will need that the filtration is of a specific type and that the probability space is large enough.

Assumption 2.1. *There exists a càdlàg \mathbb{R}^m -valued process Y with independent increments such that \mathcal{H}_t is the P -completion of $\sigma(Y_u, 0 \leq u \leq t)$, for $t \in [0, 1]$.*

For $m \in \mathbb{N}$, we denote by \mathcal{D}^m the space of \mathbb{R}^m -valued RCLL functions on $[0, 1]$ equipped with Skorohod's topology, see Chapter 3 of [Bil99].

Remark 2.2. The Borel-field of \mathcal{D}^m is generated by the coordinate mappings $x \in \mathcal{D}^m \rightarrow x(t) \in \mathbb{R}^m$, $t \in [0, 1]$, see Theorem 12.5 of [Bil99]. It follows that the function $\omega \in \Omega \rightarrow Y(\omega) \in \mathcal{D}^m$ is a random variable and so is $\omega \rightarrow {}^t Y(\omega) \in \mathcal{D}^m$, for all $t \in [0, 1]$, where ${}^t Y$ is the process defined as $({}^t Y)_u = Y_u 1_{[0,t)} + Y_t 1_{[t,1]}$, $u \in [0, 1]$. Furthermore, $\mathcal{H}_t = \sigma({}^t Y)$, for all $t \in [0, 1]$.

Assumption 2.3. *There exists a random variable U that is uniformly distributed on $[0, 1]$ and independent of \mathcal{H}_1 .*

Let us define the augmented filtration $\mathcal{F}_t := \mathcal{H}_t \vee \sigma(U)$, $t \in [0, 1]$. Standard arguments show that \mathcal{F}_t , $t \in [0, 1]$ also satisfies the usual hypotheses of completeness and right-continuity.

We now recall the market model presented in Subsection 3.6.3 of [KS09]. Let ξ_t^k , $t \in [0, 1]$, be \mathcal{H} -adapted \mathbb{R}^d -valued processes for each $k \in \mathbb{N}$ such that, for a.e. ω and for all t , only finitely many terms of the sequence $\xi_t^k(\omega)$, $k \in \mathbb{N}$ differ from 0. Let $G_t(\omega)$, $t \in [0, 1]$, $\omega \in \Omega$ denote the polyhedral cone generated by $\xi_t^k(\omega)$, $k \in \mathbb{N}$. We assume that $\mathbb{R}_+^d \subset G_t$ a.s. for each $t \in [0, 1]$. Let the dual cones be defined by $G_t^*(\omega) := \{x \in \mathbb{R}^d : xy \geq 0 \text{ for all } y \in G_t(\omega)\}$. We imagine that $G_t(\omega)$ represents the set of solvent positions in d financial assets at time t in the state of the world $\omega \in \Omega$.

Assumption 2.4. *There is a family of \mathcal{H} -adapted continuous processes ζ_t^k , $t \in [0, 1]$, $k \in \mathbb{N}$ such that $G_t^*(\omega)$ is generated by $\zeta_t^k(\omega)$, $k \in \mathbb{N}$ and only finitely many terms of this sequence differ from 0, for a.e. ω and for every t .*

Although the dual generators ζ^k , $k \in \mathbb{N}$ are assumed to be continuous processes, the above assumption allows them to depend on a driving process Y with possibly discontinuous paths (consider e.g. a stochastic volatility model with jumps in the volatility).

The following assumption requires that there is efficient friction in the market, see page 158 of [KS09].

Assumption 2.5. *Fore each $t \in [0, 1]$ and for a.e. $\omega \in \Omega$, $\text{int } G_t^*(\omega) \neq \emptyset$.*

Let \mathcal{D} denote the set of \mathcal{H} -adapted martingales Z_t , $t \in [0, 1]$ such that $Z_t \in \text{int } G_t^*$ and $Z_{t-} \in \text{int } G_{t-}^*$ a.s. for each $t \in [0, 1]$. The next assumption is essentially condition **B** on page 160 of [KS09], it stipulates that there is a rich enough class of objects in \mathcal{D} .

Assumption 2.6. *Assume that \mathcal{D} is nonempty. For each $s \in [0, 1]$, and for each \mathcal{H}_s -measurable random variable ξ if $\xi Z_s \geq 0$ for all $Z \in \mathcal{D}$ then $\xi \in G_s$ a.s.*

For an \mathbb{R}^d -valued \mathcal{F}_t -adapted càdlàg process X with bounded variation we denote by $\|X\|$ its total variation process (scalar-valued) and let \dot{X} denote the

pathwise Radon-Nykodim derivative of X with respect to $\|X\|$, this can be chosen to be an \mathbb{R}^d -valued process. Let \mathcal{X}^0 denote the family of \mathcal{F} -adapted processes with bounded variation X such that $X_0 = 0$ and $\dot{X}_t \in -G_t$ a.s. for all $t \in [0, 1]$. These processes represent the evolution of portfolio positions in a self-financing way, starting from initial position 0.

For each integer $k \geq 1$, consider \mathcal{C}^k , the space of \mathbb{R}^k -valued continuous functions on the unit interval. This is a separable Banach space with the supremum norm. Let \mathfrak{M}^{2d} denote the Banach space of $2d$ -tuples of finite signed measures on $\mathcal{B}([0, 1])$. This is the dual space of \mathcal{C}^{2d} with the total variation norm, henceforth denoted by $\|\cdot\|_1$. However, in the sequel we equip \mathfrak{M}^{2d} with the weak-* topology in the natural dual pairing between \mathcal{C}^{2d} and \mathfrak{M}^{2d} .

Remark 2.7. Let us notice that if $X \in \mathcal{X}^0$ then, for each $\omega \in \Omega$, $X(\omega)$ can be naturally identified with an element of \mathfrak{M}^{2d} . Indeed, we may consider

$$\overline{X}^{2j-1}(\omega)(A) := \int_A (\dot{X}_t^j)^+ d\|X\|_t(\omega), \quad A \in \mathcal{B}([0, 1]), \quad j = 1, \dots, d,$$

and

$$\overline{X}^{2j}(\omega)(A) := \int_A (\dot{X}_t^j)^- d\|X\|_t(\omega), \quad A \in \mathcal{B}([0, 1]), \quad j = 1, \dots, d.$$

Furthermore, we claim that the mapping $\overline{X} : \Omega \rightarrow \mathfrak{M}^{2d}$ is \mathcal{F}_1 -measurable. Indeed, it suffices to show that for each continuous $\phi : [0, 1] \rightarrow \mathbb{R}^d$, the mapping $\omega \rightarrow \int_0^1 \phi(u) (\dot{X}_u^j)^+ d\|X\|_u(\omega)$ is \mathcal{F}_1 -measurable for each $j = 1, \dots, d$ (similarly for $(\dot{X}_u^j)^-$), which is clear since X is càdlàg and adapted. By similar arguments, $\omega \rightarrow {}^t \overline{X}(\omega)$ is \mathcal{F}_t -measurable, for every $t \in [0, 1]$, where ${}^t \overline{X}(\omega)(A) := \overline{X}(\omega)(A \cap [0, t])$. We will identify X with \overline{X} in the sequel: when we write X it may refer to either the stochastic process or to the \mathfrak{M}^{2d} -valued random variable. A similar identification of ${}^t X$ with ${}^t \overline{X}$ will also be used.

For each initial position $x \in G_0$, we furthermore define $\mathcal{A}(x) := \{X \in \mathcal{X}^0 : x + X_t \in G_t \text{ a.s. for all } t \in [0, 1]\}$, the portfolio value processes which never become insolvent.

Remark 2.8. Investment decisions will be based on the augmented filtration \mathcal{F} . It is pointed out in [CR15] that by using a uniform U (independent of \mathcal{H}_1) for randomizing the strategies an investor can increase her satisfaction, however, further randomizations are pointless. See Remarks 22 and 23 of [CR17] and Section 5 of [CR15] for detailed explanations. Unlike other studies, we assume that the “dual process” Z is \mathcal{H} -adapted, since information from U does not weaken market viability.

We fix a function $\ell : \mathcal{D}^m \times \mathbb{R}^d \rightarrow \mathbb{R}$ (interpreted as a *liquidation function*) which transfers the terminal portfolio position into cash. We assume that it is continuous. The liquidation value of a position $x \in \mathbb{R}^d$ is $\ell(Y, x)$ (so it depends on the market situation via Y).

3 Optimal investments

For $z \in \mathbb{R}$ we denote $z^+ := \max\{z, 0\}$, $z^- := \max\{-z, 0\}$. Let $u_+, u_- : \mathbb{R}_+ \rightarrow \mathbb{R}_+$ be continuous, increasing functions such that $u_{\pm}(0) = 0$. Let $w_+, w_- :$

$[0, 1] \rightarrow [0, 1]$ be continuous with $w_{\pm}(0) = 0$, $w_{\pm}(1) = 1$. Functions u_{\pm} express the agent's attitude towards gains and losses while w_{\pm} are functions distorting the probabilities of events, see [TK92], [CR15].

We define, for any random variable $X \geq 0$,

$$V_+(X) := \int_0^{\infty} w_+(P(u_+(X) \geq y)) dy,$$

and

$$V_-(X) := \int_0^{\infty} w_-(P(u_-(X) \geq y)) dy.$$

For each real-valued random variable X with $V_+(X^+) < \infty$ we set

$$V(X) := V_+(X^+) - V_-(X^-).$$

Assumption 3.1. *The function u_+ is bounded from above.*

Assumption 3.1 could be substantially relaxed at the price of requiring stronger assumptions about \mathfrak{D} but this would significantly complicate the arguments. Let W be an \mathcal{H}_1 -measurable d -dimensional random variable representing a reference point for the investor in consideration. Notice that under Assumption 3.1 the functional $V(\ell(Y, X_1 - W))$ is well-defined for every $X \in \mathcal{A}(x)$.

The quantity $V(\ell(Y, X_1 - W))$ expresses the satisfaction of an agent with CPT preferences when (s)he has a portfolio process X , see [JZ08, CR15] for more detailed discussions. Positive $\ell(Y, X_1 - W)$ means outperforming the benchmark W , negative $\ell(Y, X_1 - W)$ means falling short of it. Doob's theorem implies that there is a measurable $h : \mathcal{D}^m \rightarrow \mathbb{R}^d$ such that $W = h(Y)$.

We aim to find an optimal investment strategy, i.e. $X^\dagger \in \mathcal{A}(x)$ with

$$V(\ell(Y, X_1^\dagger - W)) = \sup_{X \in \mathcal{A}(x)} V(\ell(Y, X_1 - W)).$$

The next theorem is our main result on the existence of optimizers for behavioural investors in conic models.

Theorem 3.2. *Let Assumptions 2.1, 2.3, 2.4, 2.5, 2.6 and 3.1 be valid. Fix $x \in G_0$. There exists $X^\dagger \in \mathcal{A}(x)$ such that*

$$V(\ell(Y, X_1^\dagger - W)) = \sup_{X \in \mathcal{A}(x)} V(\ell(Y, X_1 - W)).$$

Remark 3.3. Let $u : \mathbb{R}^d \rightarrow \mathbb{R}$ be continuous and bounded from above. The arguments in the proof below can also establish that there is $X^\dagger \in \mathcal{A}(x)$ such that

$$Eu(X_1^\dagger) = \sup_{X \in \mathcal{A}(x)} Eu(X_1).$$

Proof of Theorem 3.2. Let $X(n) \in \mathcal{A}(x)$, $n \in \mathbb{N}$ be such that

$$V(\ell(Y, X_1(n) - W)) \rightarrow \sup_{X \in \mathcal{A}(x)} V(\ell(Y, X_1 - W)), \quad n \rightarrow \infty.$$

Applying Lemma 3.6.4 of [KS09] to the set $\{X(n), n \in \mathbb{N}\}$ with the choice $\kappa := |x|$, there exists a probability measure $Q \sim P$ such that $\sup_{n \in \mathbb{N}} E_Q \|X(n)\|_1 <$

∞^1 . Let $c_n, n \in \mathbb{N}$ be an arbitrary sequence of positive real numbers converging to 0. Letting $\varepsilon > 0$, the Markov inequality yields

$$\lim_{n \rightarrow \infty} Q(c_n \|X(n)\|_1 \geq \varepsilon) \leq \lim_{n \rightarrow \infty} c_n E_Q[\|X(n)\|_1] / \varepsilon = 0.$$

In other words, $c_n \|X(n)\|_1$ converges to 0 in Q -probability and hence in P -probability as well by the equivalence of Q and P . Lemma 3.9 of [Kal02] shows that the sequence of \mathbb{R} -valued random variables $\|X(n)\|_1, n \in \mathbb{N}$ is tight.

For any $r > 0$, the set $\{m \in \mathfrak{M}^{2d} : \|m\|_1 \leq r\}$ is weak-* compact by the Banach-Alaoglu theorem hence the \mathfrak{M}^{2d} -valued sequence $X(n)$ is tight. So is the sequence $(X(n), Y)$. Applying Theorem 4.1, there exist a probability space (O, \mathcal{O}, R) and $\mathfrak{M}^{2d} \times \mathcal{D}^m$ -valued random variables $(\tilde{X}(n), Y(n))$ that converge R -a.s. to (X^*, Y^*) along a subsequence (for which we keep the same notation) and $\text{Law}_R(\tilde{X}(n), Y(n)) = \text{Law}(X(n), Y), n \in \mathbb{N}$. By subtracting a further subsequence we may and will also assume that

$$\tilde{X}_1(n) \rightarrow X_1^* \text{ in law as } n \rightarrow \infty. \quad (1)$$

For each $k \in \mathbb{N}$, let $f_k : \mathcal{D}^m \rightarrow \mathcal{C}^d$ be such that $\zeta^k = f_k(Y)$. Such functions exist by Doob's lemma. Passing to a further subsequence through a diagonal argument, we may and will assume that, for each $k \in \mathbb{N}$, $\zeta^k(n) := f_k(Y(n)) \rightarrow \zeta^{*k} := f_k(Y^*)$ R -a.s. in \mathcal{C}^d when $n \rightarrow \infty$ by Lemma 4.4 and by the fact that each $Y(n)$ has the same law (on \mathcal{D}^m). Analogously, we may and will assume $W(n) := h(Y(n)) \rightarrow W^* := h(Y^*)$ R -a.s. in \mathbb{R}^d .

Let us define the analogue of the functionals V_{\pm}, V , for non-negative random variables X on (O, \mathcal{O}, R) .

$$V_+^R(X) := \int_0^\infty w_+(R(u_+(X) \geq y)) dy,$$

and

$$V_-^R(X) := \int_0^\infty w_-(R(u_-(X) \geq y)) dy.$$

For each real-valued random variable X on (O, \mathcal{O}, R) with $V_+^R(X^+) < \infty$ we set

$$V^R(X) := V_+^R(X^+) - V_-^R(X^-).$$

Assumption 3.1 and the reverse Fatou lemma imply that

$$V^R(\ell(Y^*, X_1^* - W^*)) \geq \limsup_n V^R(\ell(Y(n), X_1(n) - W(n))), \quad (2)$$

so $V^R(\ell(Y^*, X_1^* - W^*)) \geq \sup_{X \in \mathcal{A}(x)} V(\ell(Y, X_1 - W))$.

Let us invoke Lemma 4.5 with the choice $\tilde{\phi} := X^*, \tilde{H} := Y^*$ and $H := Y$. We get a \mathcal{F}_1 -measurable random element $X^\dagger := \phi \in \mathfrak{M}^{2d}$ satisfying $\text{Law}(X^\dagger, Y) = \text{Law}_R(X^*, Y^*)$. Let us fix $0 \leq t < u \leq 1$. We recall that ${}^t X(n)$ is independent from $Y_u - Y_t$, or equivalently,

$$\text{Law}({}^t X(n), Y_u - Y_t) = \text{Law}({}^t X(n)) \otimes \text{Law}(Y_u - Y_t).$$

¹In [KS09], Z and X are adapted to the same filtration \mathcal{H} . Here, we allow X to be a \mathcal{F} -adapted process but this causes no problem.

By construction, $\text{Law}({}^tX(n), Y_u - Y_t) = \text{Law}_R({}^t\tilde{X}(n), Y_u(n) - Y_t(n))$. This implies also

$$\text{Law}_R({}^t\tilde{X}(n), Y_u(n) - Y_t(n)) = \text{Law}_R({}^t\tilde{X}(n)) \otimes \text{Law}_R(Y_u(n) - Y_t(n)).$$

Passing to the limit as $n \rightarrow \infty$,

$$\text{Law}_R({}^tX^*, Y_u^* - Y_t^*) = \text{Law}_R({}^tX^*) \otimes \text{Law}_R(Y_u^* - Y_t^*),$$

which implies independence of ${}^tX^\dagger \in \mathfrak{M}^{2d}$ from ${}^tY \in \mathcal{D}^m$ as well where $({}^tY)_s := 0$ if $0 \leq s \leq t$ and $({}^tY)_s := Y_s - Y_t$, $t < s \leq 1$.

Since Y is clearly a measurable function of $({}^tY, {}^tY) \in \mathcal{D}^m \times \mathcal{D}^m$, applying Lemma 4.3 with the choice $\mathfrak{b} := {}^tY$ and $\mathfrak{a} := (U, {}^tY)$ we get that ${}^tX^\dagger$ is \mathcal{F}_t -measurable, for all t .

The set $\mathcal{L} := \{Z_1 : Z \in \mathfrak{D}\}$ is a subset of the separable metric space $L^1(P)$ hence it is also separable. Let $\{Z_1^k, k \in \mathbb{N}\}$ be a countable dense subset of \mathcal{L} . For each $k \in \mathbb{N}$, there exist measurable functions $g_{k,s} : \mathcal{D}^m \rightarrow \mathbb{R}^d$ such that $E[Z_1^k | \mathcal{H}_s] = g_{k,s}(Y)$. Let ξ be an \mathcal{H}_s -measurable random variable. By the density of the family $\{Z_1^k, k \in \mathbb{N}\}$ and Assumption 2.6, if $\xi g_{k,s}(Y) \geq 0$ a.s. for each k then $\xi \in G_s$ a.s. Indeed, let Z be an arbitrary element of \mathfrak{D} and $Z_1^{k_n}, n \in \mathbb{N}$ be a sequence in the dense subset such that $Z_1^{k_n} \rightarrow Z_1$ in $L^1(P)$, and hence, $E[Z_1^{k_n} | \mathcal{H}_s] \rightarrow E[Z_1 | \mathcal{H}_s]$ in $L^1(P)$ as well. One can extract a subsequence $k_{n_l}, l \in \mathbb{N}$ along which almost sure convergence holds, i.e. $g_{k_{n_l},s}(Y) \rightarrow Z_s$, P -a.s. Therefore, the fact $\xi g_{k_{n_l},s}(Y) \geq 0$ a.s. for each l implies $\xi Z_s \geq 0$ a.s. and then $\xi \in G_s$ a.s. by Assumption 2.6.

Fix $k \in \mathbb{N}$ for a moment. Since $X_s(n) \in G_s$, obviously $X_s(n)g_{k,s}(Y) \geq 0$ P -a.s. for each $n \in \mathbb{N}$. Hence, we obtain $\tilde{X}_s(n)g_{k,s}(Y(n)) \geq 0$, R -a.s. for all n . By construction, $\tilde{X}(n)$ tends to X^* R -a.s. in \mathfrak{M}^{2d} (equipped with the weak-* topology). Moreover, from the properties of weak convergence of probabilities on \mathbb{R} we know that, for R -a.e. ω , $\lim_{n \rightarrow \infty} \tilde{X}_s(n)(\omega) = X_s^*(\omega)$ for every $s \in [0, 1] \setminus I(\omega)$ where $I(\omega)$ is a countable set. Fubini's theorem then implies that there is a fixed set T of Lebesgue measure 0 such that for $s \notin T$, $\lim_{n \rightarrow \infty} \tilde{X}_s(n) = X_s^*$ R -a.e. By (1) we may assume that $1 \notin T$.

An application of Lemma 4.4 gives $X_s^*g_{k,s}(Y^*) \geq 0$, R -a.s. for every $s \in [0, 1] \setminus T$. Notice that $X_s^\dagger = j(U, Y)$ for some $j : [0, 1] \times \mathcal{D}^m \rightarrow \mathbb{R}$ is $\mathcal{B}([0, 1]) \otimes \mathcal{G}_s$ -measurable where \mathcal{G}_s is generated by the coordinate mappings of \mathcal{D}^m up to s .

This means that for

$$B := \bigcap_{k \in \mathbb{N}} \{(u, y) : j(u, y)g_{k,s}(y) \geq 0\}$$

we have $[\text{Leb} \times \text{Law}(Y)](B) = 1$. But then, for Leb-a.e. u , for Law(Y)-a.e. y ,

$$j(u, y)g_{k,s}(y) \geq 0, \quad k \in \mathbb{N},$$

which implies $j(u, Y)Z_s^k \geq 0$ a.s. for Leb-a.e. u and for each $k \in \mathbb{N}$. Noting that $j(u, Y)$ is \mathcal{H}_s -measurable, Assumption 2.6 gives $j(u, Y) \in G_s$, for Leb-a.e. u . This means $X_s^\dagger \in G_s$ a.s.

Fix now some $t \in T$ and let $s_n, n \in \mathbb{N}$ be a sequence in $[0, 1] \setminus T$ such that $s_n \downarrow t$. Right-continuity implies that $X_t^\dagger \xi_t^k = \lim_{n \rightarrow \infty} X_{s_n}^\dagger \xi_{s_n}^k \geq 0$. We thus conclude that $X_s^\dagger \in G_s$ a.s. for all $s \in [0, 1]$.

To prove $\dot{X}_t^\dagger \in -G_t$, it suffices to show that the integrals $\int_0^\cdot \zeta_t^k dX_t^\dagger$, $k \in \mathbb{N}$ are non-increasing, by Lemma 4.6. Indeed, from $\dot{X}_t(n) \in -G_t$ for all $t \in [0, 1]$, it follows that

$$\int_s^t \zeta_u^k dX_u(n) \leq 0, P\text{-a.s.}$$

for any $0 \leq s < t \leq 1$. Lemma 4.7 gives us

$$\int_s^t \zeta_u^k(n) d\tilde{X}_u(n) \leq 0, R\text{-a.s.}$$

Again, the facts that $\tilde{X}(n)$ tends to X^* R -a.s. in \mathfrak{M}^{2d} and $\zeta^k(n) := f_k(Y(n))$ tends to $\zeta^{*k} := f_k(Y^*)$ R -a.s. in \mathfrak{C}^{2d} imply

$$\int_s^t \zeta_u^{*k} dX_u^* \leq 0, R\text{-a.s.}$$

Thus,

$$\int_s^t \zeta_u^k dX_u^\dagger \leq 0, P\text{-a.s.}$$

that is, $\int_0^\cdot \zeta_t^k dX_t^\dagger$ is non-increasing.

The previous arguments show $X^\dagger \in \mathcal{A}(x)$. As $\text{Law}(X^\dagger, Y) = \text{Law}_R(X^*, Y^*)$,

$$\text{Law}_R(X_1^* - W^*) = \text{Law}(X_1^\dagger - W),$$

and (2) shows that X^\dagger is the maximizer we have been looking for. \square

4 Auxiliary results

We denote by $\mathcal{B}(\mathbf{Z})$ the Borel-field of a topological space \mathbf{Z} . A sequence of probabilities μ_k , $k \in \mathbb{N}$ on $\mathcal{B}(\mathbf{Z})$ is said to be *tight* if, for all $\varepsilon > 0$, there is a compact set $K(\varepsilon) \subset \mathbf{Z}$ such that, for all k , $\mu_k(\mathbf{Z} \setminus K(\varepsilon)) < \varepsilon$. Take $\mathbf{Z} := \mathfrak{M}^{2d} \times \mathcal{D}^m$.

Theorem 4.1. *Let μ_k , $k \in \mathbb{N}$ be a tight sequence of measures on $\mathcal{B}(\mathbf{Z})$. Then there is a subsequence k_j , $j \in \mathbb{N}$ and a probability space on which there exist \mathbf{Z} -valued random variables ξ , ξ_j , with $\text{Law}(\xi_j) = \mu_{k_j}$, $j \in \mathbb{N}$ and $\xi_j \rightarrow \xi$ a.s., $j \rightarrow \infty$.*

Proof. This follows as in Corollary 3 and Example 5 of [CR17], using results of [Jak97], . \square

Remark 4.2. Note that the space \mathbf{Z} is not metrizable so the well-known versions of Skorohod's representation theorem (see e.g. Lemma 4.30 in [Kal02]) are not applicable.

Lemma 4.3. *Let (A, \mathcal{A}) , (B, \mathcal{B}) be measurable spaces and $j : A \times B \rightarrow \mathbb{R}$ a measurable mapping. Let (\mathbf{a}, \mathbf{b}) be an $A \times B$ -valued random variable. If $\sigma(j(\mathbf{a}, \mathbf{b}), \mathbf{a})$ is independent of \mathbf{b} then $j(\mathbf{a}, \mathbf{b})$ is $\sigma(\mathbf{a})$ -measurable.*

Proof. See Lemma 29 of [CR17]. \square

We also recall Théorème 1 of [BÉK⁺98].

Lemma 4.4. *Let A, B be separable metric spaces and $\xi_n \in A$, $n \in \mathbb{N}$ a sequence of random variables converging to $\xi \in A$ in probability such that $\text{Law}(\xi_n)$ is the same for all n . Then for each measurable $h : A \rightarrow B$ the random variables $h(\xi_n)$ converge to $h(\xi)$ in probability (hence also a.s. along a subsequence). \square*

Lemma 4.5. *Let B be a measurable space. Let H, \tilde{H} be random elements in B with identical laws, defined on the probability spaces (Ξ, \mathcal{E}, R) , $(\tilde{\Xi}, \tilde{\mathcal{E}}, \tilde{R})$, respectively. Let $\tilde{\phi}$ be a random element in \mathbf{Z} , defined on $(\tilde{\Xi}, \tilde{\mathcal{E}}, \tilde{R})$. Let U be independent of H with uniform law on $[0, 1]$. There exists a measurable function $f : B \times [0, 1] \rightarrow \mathbf{Z}$ such that $\phi = f(H, U)$ satisfies $\text{Law}_R(H, \phi) = \text{Law}_{\tilde{R}}(\tilde{H}, \tilde{\phi})$.*

Proof. Notice that the topological space \mathbf{Z} is the union of its closed, increasing subspaces A_n , $n \in \mathbb{N}$ which are Polish spaces (with appropriate metrics). Now use Lemma 31 of [CR17]. \square

We give a criterion of admissibility for \dot{X} .

Lemma 4.6. *A \mathcal{F} -adapted process X of bounded variation satisfying $\dot{X}_t \in -G_t$ for all $t \in [0, 1]$ if and only if the integrals $\int_0^t \zeta_t^k dX_t$ are non-increasing, for all $k \in \mathbb{N}$.*

Proof. Identical to the proof of Lemma 3.6.1 of [KS09]. \square

Lemma 4.7. *Let Y, \tilde{Y} be càdlàg processes, X, \tilde{X} bounded variation processes defined on two probability spaces (Ξ, \mathcal{E}, R) , $(\tilde{\Xi}, \tilde{\mathcal{E}}, \tilde{R})$, respectively. Assume that (\tilde{Y}, \tilde{X}) has the same law as (Y, X) . Let $f : \mathcal{D}^m \rightarrow \mathbb{C}^d$ be measurable. Then for all $0 \leq s < t \leq 1$, it holds that*

$$\text{Law}_{\tilde{R}} \left(\int_s^t f(\tilde{Y})_u d\tilde{X}_u \right) = \text{Law}_R \left(\int_s^t f(Y)_u dX_u \right). \quad (3)$$

Proof. We approximate f by step functions and then pass to the limit. \square

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