

Electronic Communications of the EASST  
Volume 68 (2014)



Proceedings of the  
8th International Workshop on Graph-Based Tools  
(GraBaTs 2014)

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14 pages

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ECEASST Home Page: <http://www.easst.org/eceasst/>

ISSN 1863-2122

# A Modular and Statically Typed Effectful Stack for Custom Graph Traversals

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**Abstract:** Programmers often have to implement custom graph traversals by hand as either there are no suitable text-book algorithms for their tasks, or their problems are too complex for a pure querying language that lacks modularity or static typing. Our new Scala-based graph traversal language uses an effectful stack that adapts monads and type classes. Arbitrary graph effect computations and graph processing rules can be defined and composed in a modular and statically typed way. Custom graph traversals become expressible in a concise notation, run both in-memory and on graph databases, and also allow for parallelization. We evaluate the usability of our approach by detecting occurrences of an anti-pattern in a Java source code archive. Our approach outperforms the well-known *Gremlin* approach due to parallelization.

**Keywords:** graph, modular, monad, Scala, statically typed, traversal language

## 1 Introduction

When working with graph-based data, programmers often have to implement graph traversals and transformations by hand, as known graph libraries, query languages, or traversal frameworks seem inapplicable. A flexible and concise way to implement custom graph traversals is to use a general programming language and a workflow-like programming pattern, e.g., Scala ([scala-lang.org](http://scala-lang.org)) collection library, Java 8 streams, or *TinkerPop Gremlin* ([tinkerpop.com](http://tinkerpop.com)) graph traversal language. All those approaches use fluent interfaces [Fow10] that are based on method chaining and data flow programming. We illustrate this with the property graph model in Fig. 1, an object-oriented representation of a directed, labeled and attributed pseudo-graph that is widely used in graph based systems [RN10], e.g., *Neo4j* ([neo4j.org](http://neo4j.org)) and *TinkerPop*.

The property graph model is advantageous for custom graph traversals as it represents graphs as collections of vertices and edges. Fig. 2 holds code for a `successors` traversal that is based on Scala's `Set` collection class. Starting from a set of vertices in (a), `flatMap` applies the one-to-many *value compu-*

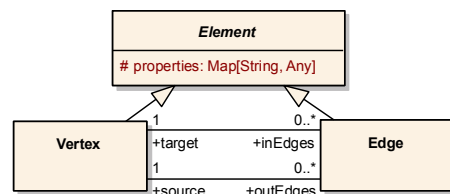


Figure 1: Property graph model.

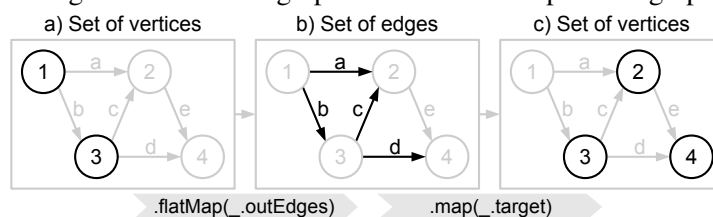


Figure 2: A `successors` graph traversal with Scala `Set`.

*tation* to each vertex to compute a set of outgoing edges (b). With a one-to-one transformation, `map` then transforms this set into a set of vertices (c) that contains all the successors of all the initial vertices. With Scala's syntax enhancements, we can shorten the code to `vertices.successors` which indicates the strength of our internal domain-specific language (DSL) for custom graph traversals.

Unfortunately, working with graphs often includes two types of tasks that break this short workflow pattern. **Effect computations** gather additional information during the traversal or influence its result. For example, *gather-the-current-traversal-path* or *do-not-visit-twice* are effects that are applied after each traversal step (e.g. `successors`). **Processing rules** influence the traversal order. The above example uses a breadth-first search (BFS) order, but often we need a depth-first search (DFS) order or have to run traversals in parallel.

Without a DSL, complex code is needed to freely compose such tasks for custom graph traversals. Our new graph traversal language that builds upon a so-called effectful stack provides a solution for this problem. Its main attributes are modularity and static typing. **Modularity** allows to *compose* arbitrary effect computations and processing rules that influence a graph traversal. It also makes effect computation results *accessible* in a structured way. **Static typing** allows to define effects in a way that lets the compiler decide statically whether an effect has to be applied to a traversal and which implementation fits best to the current data set. For example, a *gather-the-current-traversal-path* effect only gathers vertices along a traversal, but it can be skipped on edges for better performance. Our DSL is based on the object-functional programming language Scala. It leverages monads [Mog89] and type classes [WB89] but modifies them for improved modularity and static typing.

Sec. 2 briefly introduces monads and sketches our contributions. Then we address different interest groups: Sec. 3 is for effect programmers who *define* effects. Sec. 4 explains *how* the stack infrastructure makes effects available to query programmers, targeted in Sec. 5, who *uses* the traversal language. Section 6 covers related work. Sec. 7 holds an evaluation.

## 2 General Concept

### 2.1 Monads

In Sec. 1 we implemented custom graph traversals by means of (but not limited to) Scala collection classes. This workflow pattern is powerful as it offers monad [Mog89] methods like `map` and `flatMap` that bring three different computations and processing rules to graph traversals. (1) **Value computations** are distinct steps of a graph traversal, e.g., the `_.outEdges` and `_.target` functions in Fig. 2. Both require that `flatMap` and `map` apply methods of the property graph model to each vertex or edge in the current collection. (2) There can be additional **effect computations** that are implicitly applied along a traversal. For example in Fig. 2, the `Set` collection automatically removes duplicate elements after each step, such that in (c) vertex ② only occurs once, although both edges *a* and *c* target it. With a `List` collection instead, the results of the `map` operation would be concatenated and hence, vertex ② would occur twice. (3) Collection monads can have **processing rules**. In Fig. 2, the traversal automatically skips empty collections and runs in BFS order. Other traversal orders like DFS or even parallel execution order are possible by simply inserting a `.view` or `.par` in front of the `flatMap` operation.

## 2.2 Basic Idea

The basic idea is to use a collection monad's workflow pattern, but to add missing task-related additional effect computations. We illustrate this by adding two typical effect computations to the `successors` example. First, a *gather-the-current-traversal-path* effect traces the path that led to the current vertex in a traversal, for instance in a cycle detection. Second, a *do-not-visit-twice* effect assures that vertices are only visited once. Vertex ③ is in the result set of Fig. 2 although it is among the initial vertices and hence visited twice.

As such additional effect computations are cumbersome to implement with extra code, our DSL brings them into the easy to understand workflow (see Fig. 3). First, the user lifts the needed effects into the collection. We provide appropriate `.path` and `.visit` syntax enhancements for that. As a result, each vertex is wrapped into a path object  $P$  that holds and represents the path that led to

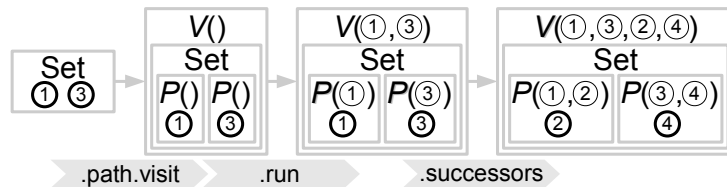


Figure 3: `successors` with additional  $P$  and  $V$  effects.

The collection of those path objects is wrapped into a visit object  $V$  that holds a set of already visited vertices and represents the corresponding effect computation. Instead of a pure value collection (vertices, bold in Fig. 3), the user now gets a nested object comprising a collection, values, and effects ( $P$  and  $V$ ). We call such an object an effectful stack. In a second step, the user applies value computations with `flatMap` and `map` – or even better with predefined syntax enhancements like `.run` or `.successors`. The former explicitly performs all effect computations in the stack without a value computation. It adds the initial vertices to the set of already visited vertices in  $V$  and adds each current vertex to the current traversal path in each  $P$ . From this point on, effect computations are implicitly performed after each value computation that is applied to the stack. Fig. 3 shows this for the `successors` step that internally applies value computations with `flatMap` and `map` to the stack. Both operations also automatically trigger the effect computations afterwards. Thus, each path effect  $P$  adds its new vertex to its internal path list, previously visited vertices are removed from the collection, and remaining vertices are added to the set of already visited vertices. Hence, in contrast to Fig. 2, vertex ③ is no longer in the resulting vertex set.

In order to get such an effectful stack, we can use monads and monad transformers [LHJ95]. Monads allow for the implementation of effect computations and monad transformers combine several monads into a new one. Unfortunately, due to their powerful but also restrictive interface (`flatMap`), they cannot be combined as freely as we would need them for custom graph traversals. Our DSL brings arbitrary effects in any combination into the stack.

## 2.3 Contributions

Below we will show how to express *arbitrary* effects in a modular and statically typed way such that they can be combined together with collection classes to an effectful stack. For free composability of more than a restricted set of simple effects, novel and slightly impure monad transformers are needed that allow for a modular and statically typed effect definition. Moreover,

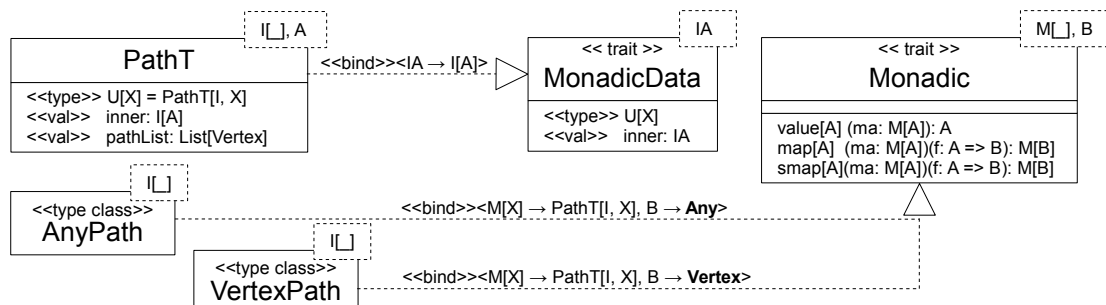


Figure 4: Schema of a PathT monadic class.

we present how such effects can be added to a stack without affecting the simple signature of flatMap and map too much, so that the basic query programmer can still apply operations to collections without noticing the effect processing that is being triggered under the hood – and that of course is implemented efficiently by our effect engine.

### 3 Classes with Monadic Effects

A design goal of our DSL is that an effect programmer can pre-define effect computations for the query programmer to later use them without having to know how the effects are implemented. This section is mainly of interest for the effect programmer.

To define the above mentioned path and visit we need: first, a data type that represents an effect computation on the stack and that holds intermediate effect computation results. And second, the actual implementation of the effect in a modular and statically typed way. For both, we extend monad transformers (that are also monads) and type classes. The latter offer ad-hoc polymorphism and decouple a data type from its monad implementation so that the compiler can statically choose the right type-dependent code for an effect.

We introduce *monadic classes* that are based on Scala’s `implicit` feature [OMO10] and make it straightforward to implement new effects as shown in Fig. 4. The effect programmer simply implements the data type and the type class of an effect and automatically inherits all that is needed for the effectful stack.

#### 3.1 Data Type

MonadicData prescribes how an effect programmer has to define effects. This is advantageous over pure monads that usually do not prescribe a distinct data structure at all. The task is to make effects *composable* and its intermediate computations results *accessible* within an effectful stack.

For **composability** data types must resemble monad transformers. In Fig. 4 the data type PathT (T for transformer) represents a path effect computation. The type parameter I[\_] represents a unary nested data type; A is the current value type, e.g., a vertex or an edge. MonadicData enforces that sub-classes define their unary type representation using the abstract type member U[X]. Thus, the compiler can later use it to select suitable type classes (Sec. 3.2). The unary type representation of PathT is U[X]=PathT[I, X] where I is the unary

type of a nested monadic class. This results in a multi-layered stack of monadic classes where each stacked data type has its unary type projection that uses the value type of the bottom data type as its type parameter.

For type-safe **accessibility** to the whole structure of a multi-layered monadic class, a data type has to implement the `inner` attribute declared in `MonadicData`. In the example, `path=ma.inner.inner.pathList` gives access to the `pathList` attribute even if `PathT` is nested in two other monadic classes. As the `MonadicData`'s type parameter `IA` binds the `inner` attribute to `I[A]` and as it holds the concrete type of the nested data type, access to all monadic classes is type-safe. The `pathList` attribute can also be accessed without explicitly denoting any calls of `inner`, which the compiler can insert implicitly without loss of type-safety.

### 3.2 Type Class

A type class implements an effect's computational part. We improve a pure functional monad transformer's type class [CB14] with both an easier implementation (with focus to our effectful stack) and statically typing (to improve performance and type safety).

The effect programmer has to fulfill the interface `Monadic`. It has two type parameters: `M[_]` is the unary type projection of the monadic classes' data type. For example, a type class `AnyPath` for `PathT` in Fig. 4 has to use the binding `M[X]=PathT[I, X]`. The second type parameter `B` is bound to `Any`. What is new is that the compiler loads them implicitly if needed. It also loads the type classes of all inner monadic classes that then can be used in a monadic type class implementation. Hence, a type class sees the unary type projection of the inner monadic class as its type parameter `I[_]`.

To **ease implementation** a type class only has to implement `map`, `smap`, and a `value` function. A pure structural map (`smap`) is needed for a value computation without effect computation. A type class also needs a `value` function to access the base value of a multi-layered monadic class. In a pure monad with more layers it gets more unlikely that `flatMap` can be called with a function of type `A=>M[N[O[P[...[B]]]]]` instead of just `A=>M[B]`. Instead `Monadic` exploits that for graph traversals it suffices to have one-to-one transformations (`map` and `smap`) of the form `A=>B` or one-to-many transformations (`flatMap`) like `A=>C[B]` with an arbitrary collection type `C`. Sec. 4.3 shows how our stack infrastructure automatically reduces the latter to one-to-one transformations.

Multiple parameter type classes [Jon00] improve **static typing**. A problem of pure monads is that although a type class is chosen at compile time, there is still pattern matching. For example, `map` of `PathT` only has to append the result of the value computation `f:A=>B` to its recorded path list if `B` is of type `Vertex`. Otherwise it has no effect. Pure monads would have to use slow runtime pattern matching on the type of `B`. To solve this problem `Monadic` has the target type `B` as an extra type parameter. As `map` then returns type `B` we can provide statically selectable type class instances. Two type classes for `PathT` are in Fig. 4. `VertexPath` for `B` is bound to `Vertex` (for path computation) and `AnyPath` for `B` is bound to `Any` (default/no effect).

The strength of multiple parameter type classes becomes even more apparent for monadic classes that work on collection types instead of single value types. The monadic class `VisitT` in Fig. 5 rejects all pre-visited vertices from the resulting collection. A mutable (and synchronized) `HashSet` attribute `visited` is used for that purpose. Beside the obligatory effect-free default

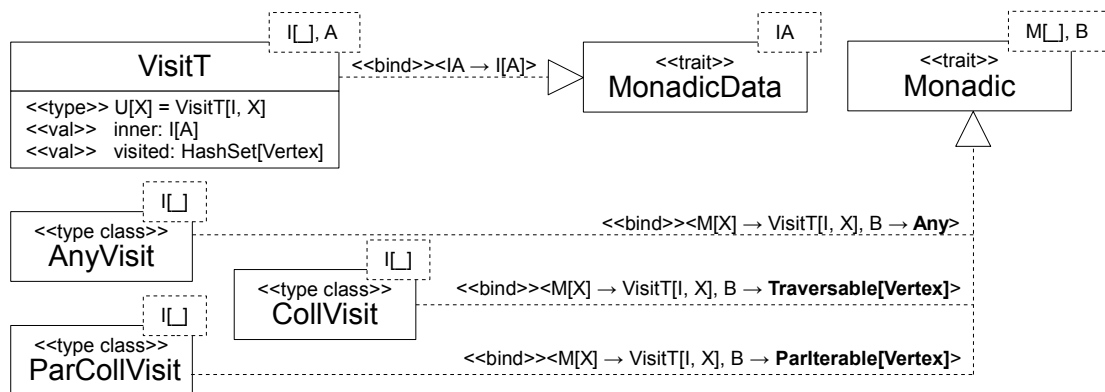


Figure 5: Schema of a `VisitT` monadic class.

`AnyVisit`, Fig. 5 also depicts `CollVisit` and `ParCollVisit` that are selected statically if a value computation results in a collection of vertices. Their `map` functions filter the vertex collection, reject pre-visited vertices, and otherwise add them to the `HashSet`.

Together with monadic data types, monadic type classes provide the necessary modularity that allows the query programmer to freely combine the desired effect computations. The next section shows how the effects are combined to an effectful stack.

## 4 Effectful Stack

How predefined effect computations are combined to an effectful stack is mainly of interest to readers who want to know the details. Sec. 4.1 describes the multi-level nature of our stack for both effect and query programmers. Only effect programmers have to define syntax enhancements (Sec. 4.2) to offer an effect for query programmers who only need rudimentary knowledge about the stack to trigger all effect computations and uniform stack operations (Sec. 4.3).

### 4.1 Stack Levels

The multi-level stack in Fig. 6 allows a modular composition of monadic classes and collections. It consists of arbitrary different stack levels depending on the needed graph transformation complexity. Each level can hold multiple layers of monadic classes to support the combination of effects within a level. For demonstration, the shown 5 levels suffice.

Level	Stack Content	Type $S[A]$	Example
4	Monadic Class $M4^*$	$M4[M3[C[M[A]]]]$	$\text{RepeatT}^\dagger[\text{VisitT}^\dagger[\dots]]$
3	Monadic Class $M3^*$	$M3[C[M[A]]]$	$\text{VisitT}^\dagger[\text{Set}[\dots]]$
2	Collection C	$C[M[A]]$	$\text{Set}[\text{PathT}^\dagger[\text{Vertex}]]$
1	Monadic Class $M^*$	$M[A]$	$\text{PathT}^\dagger[\text{Vertex}]$
0	Value A	A	Vertex

\* Can comprise multiple layers to support multiple effects.

† A unary type projection of the shown type.

Figure 6: Schema of a multi-level stack  $S[A]$ .

As effects work on distinct stack levels, an effect programmer needs to know about those levels. Level 1 represents one-to-one transformations using monadic classes (cf. `PathT`) that work on single values of a level 0 type `A`. To support multiple values and one-to-many transformations,



```

1 | implicit def vSyntax[T](t: T)(implicit v: StackType[T, Vertex]) = new {
2 |   def successors(implicit S1: Stack[T, v.A0, Edge], S2: ...) = ...   }

```

Figure 7: Syntactic sugar for multi-level stacks.

level 2 adds a collection class that works on level 1 types ( $M[A]$ ). To allow for many-to-many transformations, monadic effects that work on top of collections live on stack level 3. They wrap a collection class into another multi-layered monadic class  $M3$  that works on the collection type  $C[M[A]]$ . For example in  $S[A]=\text{VisitT}[\text{Id}, \text{Set}[\text{PathT}[\text{Id}, A]]]$   $\text{VisitT}$  has the  $\text{Set}$  collection as its value type that holds  $\text{PathT}$  monadic classes for value type  $A$ . Hence, the whole stack is of type  $S[A]$ .  $\text{Id}$  is a pre-defined data-type-free special monadic class that has to be used on the bottom of each multi-layered monadic class. In order to support repetitions of many-to-many transformations, we use stack level 4 to put another multi-layered monadic class  $M4$  on top of a level 3 stack to work on types  $M3[C[M[A]]]$ , see Sec. 5.2 for the rationale.

## 4.2 Syntactic Sugar for Multi-Level Stacks

Recall that the `successors` shorthand works on a vertex collection (Sec. 1). As the effect programmer needs such a syntax enhancement mechanism for all types of effectful stacks, e.g. a vertex based stack, we provide an easy to use implementation pattern that is based on `StackType` and `Stack` which we pre-define, see Figs. 7 and 8. The method `vSyntax` (line 1) takes an object of type  $T$  that can be decomposed into an effectful stack based on `Vertex`. `vSyntax` results in an anonymous class comprising all syntax enhancements (e.g. `successors`) that are applicable to such a stack. This is ensured if the compiler finds a type class instance for `StackType` (line 1). The definition of `StackType` in Fig. 8 that comes with predefined type class instances for each stack level (0 to 4). They decompose a given type  $T$  into an effectful stack and ensure that  $T$  can be seen as  $S[A]$  with  $A$  being a sub-type of a given type  $A00$ . The type members  $A0$ – $A4$  are filled with the concrete value types of the stack. For example,  $A0$  is the level 0 value type  $A$ ,  $A1$  is the level 1 value type  $M[A]$ , etc. The type members  $U0$ – $U4$  provide unary type projections for those value types, e.g.  $U1[X]=M[X]$ , etc. Thus, it suffices to implement a `successors` traversal step only once for all stack combinations.

## 4.3 Multi-Level Stack Operations

Both effect and query programmers need traversals like `map`, `smap`, and `flatMap` that work on an effectful stack instead of just value collections. We provide such operations within the predefined `Stack` type class (Fig. 8) that solve the problem of how to implement such common operations for an effectful stack. The `successors` method in line 2 of Fig. 7 internally uses `map` and `flatMap` (not shown) and needs the type class instances  $S1$  and  $S2$  that both provide the statically typed stack implementations.  $S1$  is based on the `StackType`'s type  $v.A0$  (line 1) and ends in an edge-based stack after calling `flatMap`.  $S2$  is based on the result type of  $S1$  and ends in a vertex-based stack after calling `map`.

The `map` and `smap` functions of a `Stack` are straightforward to implement. A schematic body of a `map` function for a level 4 stack type class instance that accepts a value computation  $f$  of type  $A \Rightarrow B$  is (we use a recursive naming scheme –  $m4m3cma$  is a multi-layered monadic



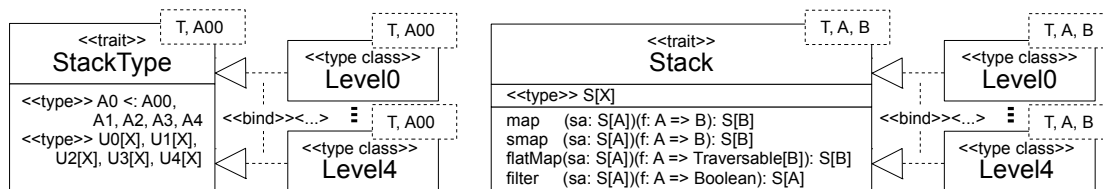


Figure 8: StackType and Stack type class.

class data type on stack level 4, that has a value type `m3cma`, that has a value type `cma`, that ...):  
`M4.map(m4m3cma) (m3cma => M3.map(m3cma) (cma => cma.map(ma => M.map(ma) (f)))`

Due to their collection-based nature `flatMap` and `filter` cannot be implemented by monadic classes alone. Their code differs from a `map`'s code in the collection part on stack level 2:

```
cma => cma.flatMap(ma => f(M.value(ma))).map(b => M.map(ma) (a => b))
```

Unwrapping each value on stack level 1 with the `value` function and later re-wrapping into the level 1 monadic class `M` makes `flatMap` more expensive than `(s)map` (see Sec. 7.1).

## 5 Stack-based Traversal Steps

Query programmers only have to know about the existence of monadic classes and only deal with their data types and pre-defined syntactic sugar. We provide syntax enhancements and additional effect computations to simplify expressing custom graph traversals.

### 5.1 Traversal Steps using Stack Operations

The pre-defined syntactic sugar for traversal steps in Table 1 is available on all stacks with the denoted value types. For example, `predecessors` is similar to `successors` of Sec. 4.2, but computes all adjacent vertices that are reachable via incoming edges. `values` is a shortcut for unwrapping all level 0 values and produces a collection of type `C[A]`. `run` performs a `map(a=>a)` on an arbitrary stack and triggers all effects in the stack without an explicit value computation (cf. Sec. 2.2). `bfs`, `dfs`, and `par` select an execution order. `toList` and `toSet` change the collection type, the latter purges duplicates after each step.

Table 1: Traversal steps using stack operations.

Step	Description
Level 0 value type: Vertex	
<code>successors</code>	All vertices reachable via out-or incoming edges
Level 0 value type: Any	
<code>values</code>	All level 0 values
<code>run</code>	Trigger all effect computations
Level 2 value type: a collection	
<code>bfs</code> , <code>dfs</code> , <code>par</code>	Change traversal order
<code>toList</code> , <code>toSet</code>	Change collection type

### 5.2 Traversal Steps using Monadic Classes

We provide pre-defined monadic classes (see Table 2).

**Value-based Monadic Classes:** The `path` syntax enhancement lifts `PathT` (Fig. 4) into stack level 1. `CountT` can be used for faster cycle detection at the expense of a higher memory footprint. It holds a map of vertex/counter pairs and increases a counter whenever a vertex is visited. A counter above 1 indicates a cycle. Access to the map is in constant time, whereas with

`PathT` it takes a linear iteration over the path list. `CountT` and `PathT` demonstrate the ability to define and to use effect computation in a modular way.

**Collection-based Monadic Classes:** In addition to stack operations like `map` and `filter`, there are corresponding monadic classes `MapT` and `FilterT` for implicit graph transformations and filtering (cf. `context`). They apply effect computations continuously after each traversal step.

The statement below continuously applies the pre-defined edge filter `dependsOn` to the traversal and turns a multi-relational graph into a single-relational one:

```
vertices.context(dependsOn).successors.successors.successors
```

Since `FilterT` works on the value level we also provide `mfilter1` to express filter operations that are based on effect computations. It takes a filter function of type `M[A] => Boolean` instead of `A => Boolean`. The monadic class `GatherT` gathers elements of type `T`. As it only works on collections, it has to reside on levels 3 or 4.

**Stack-based Monadic Classes:** The stack level 4 (Fig. 6) is necessary for effect computations that are based on whole stacks, e.g. a repetition of traversal steps. We offer the `RepeatT` monadic class that takes a function of type `T => T` and performs a *repeat-until-end* effect computation until the collection on stack level 2 is empty. To repeatedly apply the `successors` step to a level 3 stack one writes: `vertices.visit.repeat(_.successors).run`

Table 2: Traversal steps using monadic classes.

Step	Monadic Class	Description
Monadic class on stack level 1:		
<code>path</code>	<code>PathT</code>	Path computation
<code>count</code>	<code>CountT</code>	Count vertex visits
Monadic class on stack level 3:		
<code>context (T =&gt; Boolean)</code>	<code>FilterT</code>	Implicitly filter <code>T</code> s
<code>mfilter1 (M[A] =&gt; B)</code>	<code>FilterT</code>	Impl. filter <code>M[A]</code> s
<code>gather (T =&gt; Boolean)</code>	<code>GatherT</code>	Gather <code>T</code> values
<code>visit</code>	<code>VisitT</code>	Visit vertices once
Monadic class on stack level 3 or 4:		
<code>repeat (T =&gt; T)</code>	<code>RepeatT</code>	Repeat until end

## 6 Related Work

Query programmers can choose from many approaches but often only graph traversal languages are suitable for custom graph traversals. The reasons are first, that *graph libraries* like *JUNG* ([jung.sourceforge.net](http://jung.sourceforge.net)), *SNAP* ([snap.stanford.edu/snap](http://snap.stanford.edu/snap)), or *TinkerPop Furnace* are often only specialized to single-relational graphs, work in-memory but not on databases, expect a different data format, or do not provide the desired functionality. Second, *graph query languages* like *Neo4j Cypher* or *SPARQL* ([w3.org/TR/rdf-sparql-query](http://w3.org/TR/rdf-sparql-query)) are often external DSLs, come with a concise declarative syntax, but also a limited functionality [Woo12]. Query languages are cumbersome to use for traversals that rely on custom traversal orders as it is difficult to influence their internal processing order and optimization technique. On the other hand, *graph traversal languages* or frameworks like the *Neo4j Traverser API* or *TinkerPop Gremlin* combine the advantages of both prementioned worlds and allow for the definition of custom graph traversals in a concise way.

Closest to our effectful stack is *TinkerPop Gremlin*. It is also an internal DSL, extends its host language syntax (Groovy) with graph traversal operations, and hence overcomes the limitations of query languages. Compared to our approach *Gremlin*'s modularity is not always sufficient. For example, *Gremlin* is bound to a DFS traversal order due to its pipe-based architecture. To switch to BFS or parallel execution order a different backend is needed that comes with further requirements. It is also cumbersome to continuously apply implicit graph transformations to

see a multi-relational graph as single-relational for easier implementation. Due to *Gremlin*'s dynamically-typed nature, it is also difficult to access the results of additional effects during a traversal in a structured and statically typed way and it allows to apply traversal steps even on inappropriate types. The query programmer often only discovers errors at runtime and has to guess if a query is correct or not. A Scala-based *Gremlin* dialect merely provides a front-end to the existing framework that we consider also untyped.

Pure functional programming on graphs is slower than imperative codes [Erw97], but our object-functional approach performs much better. King [Kin96] combines pure functional graph algorithms with state monads but does not offer syntax enhancements. Erkok [Erk02] describes value recursion on monads but omits effect recursion that we need for RepeatT. Schrijvers and Oliveira [SO11] suggest the use of so-called zippers and views to provide modular monadic components. While being purely functional, zippers mask layers within a monad stack and are an alternative to our object-oriented multiple-parameter type class. But as they do not consider collection monads in their stack, zippers are unsuitable for graph traversals.

## 7 Evaluation

Sec. 7.1 evaluates the runtime overhead caused by the effectful stack infrastructure that uses multiple wrapper classes and type class instances. Statically typed monadic type class instances are faster than untyped ones (Sec. 7.2). Sec. 7.3 benchmarks a detection of dependency cycles in several real-world Java codes (see Table 3). We extracted the corresponding vertices and edges with the help of the *ASM* library ([asm.ow2.org](http://asm.ow2.org)).

For all our measurements we mask outliers by taking the best out of 10 measurements on a Windows 7 x64 PC with 16 GB RAM and a quad-core CPU with hyperthreading (8 cores) and a nominal 3.5 GHz. Test programs use Scala 2.10.1 and run on a Java SE 7u25 (x64) VM. We use *Gremlin* 2.3.0 and Groovy 2.0.7. 12 GB have been allocated for Java to minimize garbage collection runs.

Table 3: Java codes used for the evaluation.

ID	Project	Element Count	
		vertices	edges
A	Cobertura 2.0 <sup>α</sup>	12,310	26,385
B	Squirrel SQL Client 3.5.0 <sup>α</sup>	24,617	57,105
C	Apache Ant 1.9.1 <sup>α</sup>	44,801	103,580
D	Eclipse Debug UI 3.8.2 <sup>β</sup>	76,904	195,227
E	Eclipse JDT UI 3.8.2 <sup>β</sup>	340,378	896,326
F	Scala Compiler 2.10.1 <sup>γ</sup>	562,122	1,555,970
<b>Combined Java codes:</b>		1,061,132	2,834,593

<sup>α</sup>: [sourceforge.net](http://sourceforge.net), <sup>β</sup>: [eclipse.org](http://eclipse.org), <sup>γ</sup>: [scala-lang.org](http://scala-lang.org)

### 7.1 Infrastructure Runtime Overhead

Although all parts of an effectful stack influence the runtime, we are interested in the infrastructure overhead caused just by monadic classes, the multi-level stack, and the type class instances created and executed at runtime. Hence, we work with effect-free IdT monadic classes and a list collection with an effect-free flatMap operation.

The stack operation determines which functions of the monadic classes are called, especially on level 1. For example, the map operation in Sec. 4.3 is only called per level 1 monadic class, whereas flatMap uses value and map in addition to a collection-based map. The complexity of filter/foreach lies between map and flatMap. Hence, to evaluate we group

stack operations according to their complexity and measure the overhead for `map/smap` (using `map(_.outEdges.size)`), `filter/foreach` (using `filter(Class)`), and `flatMap` (using `flatMap(_.outEdges)`) on a vertex set. We also distinguish level 1 and level 3 monadic classes. For example, a simple `map` operation on a level 3 stack has to trigger all level 1 monadic classes within the collection, whereas a level 3 monadic class is triggered only once.

Table 4 shows the results of our measurements. As a worst case scenario, we used all vertices of the combined projects A–F (Table 3) and a level 2 effective stack using a vertex list (in a list, `flatMap` has no additional effect after a step) with the shown number of level 1 IdT monadic classes in it. We applied each of the mentioned functions to the stack once. On the large graph, we can see the influence of multiple level 1 monadic classes. `map` causes little infrastructure overhead, about 0.6% per monadic class layer, whereas `filter` (8.4%) and `flatMap` (18%) are more costly. The last line of Table 4 shows that parallelization boosts performance for a computation with three monadic classes (3x IdT). We also measured the overhead of level 3 and level 4 monadic classes, but as they only produce overhead per traversal step, the vertex count does not matter and the runtime overhead (about 0%) can be ignored.

Table 4: Infrastructure runtime overhead.

IdT	map [s]		filter [ms]		flatMap [s]	
0x	3.70		63.2		3.68	
1x	3.71	+0.2%	68.5	+8.4%	4.36	+18%
2x	3.73	+0.8%	69.2	+9.5%	4.46	+21%
3x	3.75	+1.4%	70.2	+11%	4.61	+25%
3x, PAR	1.15	-69%	22.7	-64%	1.62	-56%

The percentages refer to the line 0x in which a pure collection is used and no stack overhead is applied.

## 7.2 Advantages of Static Typing

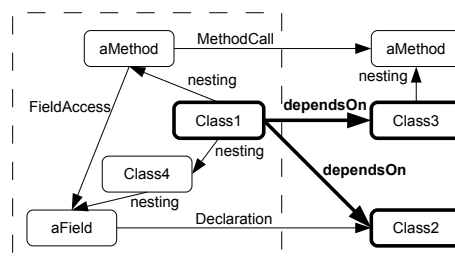
To illustrate the advantage of statically typed monadic type class instances over untyped monad type class instances, we compare the runtime of a graph traversal that uses `VisitT` to a monad-based implementation. We again traverse the combined Java code graph of projects A–F with:

```
vertex.visit.repeat(_.successors).run
```

The statement starts at the project’s `CodeBase` vertex and traverses in BFS order to each vertex once. With `VisitT` this takes 5.63 seconds which is 16.5% faster than the monad-based code (6.56 seconds). Hence, in addition to a productivity gain due to bug detection at compile-time, statically typed monadic classes also have a performance advantage, mainly due to static code selection instead of runtime pattern matching.

## 7.3 Dependency Cycle Detection

We now benchmark a custom graph traversal that detects dependency cycles in Java code, which is an anti-pattern to good software [MT06]. Fig. 9 holds an example code graph. Cycles among top level types (not nested within other types) are the anti-pattern. The code in Fig. 10 finds the first 10 disjunct elementary cycles [Joh75] that consist of at least 4 different vertices. This code works in two steps:


 Figure 9: Some `dependsOn` edges between top level types.



```

1 | def step1(v: Vertex): Vertex = { val s = v.repeat(..gather(CodeElement).run,
2 |   ..successors(nesting)).run.gathered; ... v }
3 | val cycles = { val cMap = HashMap[Set[Vertex], List[Vertex]]()
4 |   vertices.map(step1).count.path.run.context(dependsOn).mfilter1(ma =>
5 |     (cMap.size < 10) && !((ma.count == 2) && addCycle(ma.cycle))).
6 |   repeat(..successors).run;      /* return found cycles: */ cMap.values }

```

Figure 10: Finding elementary cycles with the effectful stack.

**Step 1** computes the dependencies between top level types and persist them temporarily by means of new edges of type `dependsOn`. In Fig. 9 the top level type `Class1` depends on `Class2` and `Class3`, as at least one of its members has a dependency to a member of each of the target classes. As `Class4` is not a top level type it is not a dependence for `Class1`. This is coded in Lines 1–2 of Fig. 10. The method `step1` expects a top level type vertex and gathers in `s` all its nested code elements (using pre-defined vertex filters `CodeElement` and `nesting`). Note the additional `GatherT` monadic class. We lift it into stack level 4 (`RepeatT`) to make all visited vertices available in the `gathered` attribute. Afterwards (not shown) the function traverses over existing dependencies to all dependent code elements and gathers their top level types. We then create new `dependsOn` edges between the vertex `v` and all of those top level type vertices (without creating any self-loops). `step1` returns its input vertex `v` in line 2 as it performs an in-place transformation. Later, line 4 applies the `step1` method to all vertices once, using the effectful stack’s `map` operation.

**Step 2** searches for cycles among top level types using only `dependsOn` edges until an abort criterion is met (lines 3–6). First, we create a `HashMap` for the found elementary cycles that are represented as a vertex list and stored using this `Set` representation in order to filter out isomorphic cycles. Second, we lift all necessary effects into the stack in line 4: `CountT`, `PathT`, and `FilterT` (using `context`). We do not need a `VisitT` as there is no need to filter out previously visited vertices. Instead we need to detect a cycle first and then filter out already visited vertices. We use another `FilterT` for that in lines 4–5. It returns **false** if we already found 10 cycles or if the current vertex was already visited on its traversal path. In the latter case, the `count` attribute of `CountT` equals to 2 and the `addPath` function (not shown, but always returns **true**) checks if the found cycle has an appropriate length and adds it to `cMap` if necessary. Line 6 contains the core traversal function that repeats a `successors` step until the level 2 collection is empty and hence until we collected 10 relevant cycles or we reached the end of the graph. The last statement returns the found `cycles`.

On a *Neo4j* 1.9.2 database we get the results in Table 5 when applying both traversal steps to each project A–F. Table 5(a) shows the measurements for step 1 in milliseconds. As expected, the BFS runtime (average is set to 100% in the last column) grows proportional with the project graph size (all projects have a similar edge/vertex ratio of about 2.45). Parallelization (insert `.par` before `map` in line 4) speeds up the runtime by about a factor of 4 on average. It only takes 24% of the sequential BFS effort. As step 1 has to transform the whole graph, DFS order (insert `.dfs` before `map` in line 4) has the same runtime, even when parallelized. Hence, *Gremlin* cannot benefit from its pipe-based architecture and shows slower results.

Table 5(b) shows both the number of `dependsOn` edges that step 1 inserts into the graphs and the ratio of the projects’ total edge counts and the `dependsOn` edge counts. The ratios of

projects A and F are well below average. The ratio directly influences the runtime of step 2 as a high `dependsOn` density makes cycles more likely.

Table 5(c) shows the measurements for step 2 in seconds (for DFS order in milliseconds) that were run in BFS (set to 100%), BFS+PAR, and DFS order. As cycle detection is a DFS problem, DFS order is much faster (on average 0.3% of the BFS runtime) even with parallelization engaged for BFS. There are two outliers in the DFS performance. As project A has no cycle that fits the requirements, the whole graph has to be traversed which results in a bad DFS performance. In project F the DFS runtime is better than in project E due to the low edge ratio, even if the total graph size of F is twice that of project E.

The total runtimes to find dependency cycles in two steps are in Table 5(d). As *Gremlin* cannot parallelize step 1 and is also slower in step 2, our effectful stack performs much better. Moreover, the *Gremlin* code needs about 70% more code (measured using compiler tokens) than our monadic graph stack approach. This use case also clearly shows the advantages of the free combinability of any traversal order with parallelization, simply by adding `dfs/par` traversal steps to a query. Our effectful stack allows to add necessary effect computations in a modular way, e.g. path computations, as they are fully interoperable with all traversal orders.

## 8 Conclusion

This paper presents an effectful stack for custom graph traversals that allows for the modular application of additional effect computations and processing rules. We leverage the concepts of monads, monad transformers, and type classes, but modify them into monadic classes to achieve modular composability of multi-layered monadic classes that also provide structured access to their data. Monadic classes are easy to implement and statically typed. The latter speeds things up as only necessary effects are executed. Monadic classes are combined with collection monads into an effectful stack. Syntax enhancements ease modifying and working with this stack. The infrastructure runtime overhead of our effectful stack is low. We showed the applicability of our ideas by finding an anti-pattern (elementary cycles) in real-world Java codes. With the ability of running traversals in parallel we outperform a *Gremlin* version of this analysis.

Table 5: Runtime for finding elementary cycles.

a) Time measurements for step 1 [ms]

	A	B	C	D	E	F	avg.
<b>Effectful Stack</b>							
BFS	61	107	201	453	2,421	4,857	100%
BFS,PAR	20	37	65	121	576	1,127	24%
DFS	60	107	199	452	2,416	4,872	100%
<b>Gremlin</b>	192	378	647	1,113	4,596	9,269	200%

b) Count of `dependsOn` edges created in step 1

	A	B	C	D	E	F	
<b>Count</b>	740	3,384	7,972	17,496	70,042	22,970	
<b>Ratio %</b>	2.80	5.93	7.70	8.96	7.81	1.48	

c) Time measurements for step 2 (BFS/PAR in [s], others [ms])

	A	B	C	D	E	F	avg.
<b>Effectful Stack</b>							
BFS	0.08	0.84	4.52	8.64	47.3	11.6	100%
BFS,PAR	0.05	0.21	1.12	2.04	11.9	2.49	24%
DFS	61.7	7.0	12.3	15.1	51.7	45.5	0.3%
<b>Gremlin</b>	173	22.4	37.5	45.2	159	142	0.8%

d) Best accumulation of steps 1 and 2 [ms]

	A	B	C	D	E	F	avg.
<b>Effectful Stack</b>							
	82	44	77	136	628	1,173	100%
<b>Gremlin</b>	365	400	685	1,158	4,755	9,411	784%





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