# Factoring Polynomials and Groebner Bases 

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# FACTORING POLYNOMIALS AND GRÖBNER BASES 

A Dissertation<br>Presented to the Graduate School of Clemson University

$\qquad$

In Partial Fulfillment
of the Requirements for the Degree
Doctor of Philosophy
Mathematics

by<br>Yinhua Guan<br>August 2009

Accepted by:
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## Abstract

Factoring polynomials is a central problem in computational algebra and number theory and is a basic routine in most computer algebra systems (e.g. Maple, Mathematica, Magma, etc). It has been extensively studied in the last few decades by many mathematicians and computer scientists. The main approaches include Berlekamp's method (1967) based on the kernel of Frobenius map, Niederreiter's method (1993) via an ordinary differential equation, Zassenhaus's modular approach (1969), Lenstra, Lenstra and Lovasz's lattice reduction (1982), and Gao's method via a partial differential equation (2003). These methods and their recent improvements due to van Hoeij (2002) and Lecerf et al (20062007) provide efficient algorithms that are widely used in practice today.

This thesis studies two issues on polynomial factorization. One is to improve the efficiency of modular approach for factoring bivariate polynomials over finite fields. The usual modular approach first solves a modular linear equation (from Berlekamp's equation or Niederreiter's differential equation), then performs Hensel lifting of modular factors, and finally finds right combinations. An alternative method is presented in this thesis that performs Hensel lifting at the linear algebra stage instead of lifting modular factors. In this way, there is no need to find the right combinations of modular factors, and it finds instead the right linear space from which the irreducible factors can be computed via gcd. The main advantage of this method is that extra solutions can be eliminated at the early stage of computation, so improving on previous Hensel lifting methods.

Another issue is about whether random numbers are essential in designing efficient algorithms for factoring polynomials. Although polynomials can be quickly factored by randomized polynomial time algorithms in practice, it is still an open problem whether there exists any deterministic polynomial time algorithm, even if generalized Riemann hypothesis (GRH) is assumed. The deterministic complexity of factoring polynomials is studied here from a different point of view that is more geometric and combinatorial in nature. Tools used include Gröbner basis structure theory and graphs, with connections to combinatorial designs. It is shown how to compute deterministically new Gröbner bases from given Göbner bases when new polynomials are added, with running time polynomial in the degree of the original ideals. Also, a new upper bound is given on the number of ring extensions needed for finding proper factors, improving on previous results of Evdokimov (1994) and Ivanyos, Karpinski and Saxena (2008).

## Dedication

This work is dedicated to my family.

## Acknowledgments

I am truly grateful for all the instruction, encouragement, infinite patience and inspiring ideas from my advisor Professor Shuhong Gao during my studies as a Ph.D candidate in Clemson University. It has been a great pleasure to discuss problems with him who is very knowledgeable, very friendly, working hard and with sense of humor. I also want to thank the financial support that I have received from the National Science Foundation and from mathematical department.

I would like to thank my committee, Prof. H. Maharaj, Prof. Gretchen L Matthews, Prof. Hui Xue, Prof. Elena S Dimitrova for their advice, instruction of classes, encouragement and support. I have learned a lot from them. Additional thanks is due to Prof. Beth Novick, Prof. Peter C Kiessler and Prof. Hyesuk K Lee for their support, Prof. Robert Taylor for the teaching opportunity, and Prof. Joel Brawley for great teaching and support. And I want to thank Susan Zhang for her care and encouragement.

I would also like to thank Mingfu Zhu, Yunwei Cui, Raymond A Heindl, Jang-Woo Park, Qi Zheng for inspiring talks and friendship. Also I should thank Artur Gorka, Yang Yang, Zhe Sun, Hua Zhang, Ping Yan, Qing Xu, Zendong Wan, Ru Chen, Jun Gao, Hong Dong, Guang Zeng, Rui Wang, who have been great friends through my years in Clemson, also friends from badminton team and chinese soccer team.

I owe much to my parents, Xingying He and Faen Guan, my older sister Yuhua Yang and older brother Honghua Guan, and my lovely nephew and niece. They always
have faith in me with unconditional love, especially my sister. My honor belongs to them as well.

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## Chapter 1

## Introduction

### 1.1 Factoring polynomials

Factoring polynomials is a central problem in computer algebra with applications in mathematics and engineerings. For univariate polynomial factorization, we have probabilistic methods by Berlekamp (1967) and Neiderreiter (1993). Hensel lifting method was first presented by Zassenhaus (1969) for factoring in $\mathbb{Q}[x]$. A.K. Lenstra, H.W. Lenstra and Lovász (1982) introduced lattice reduction and gave the first polynomial time algorithm for factoring in $\mathbb{Q}[x]$. Then Chistov (1984), A. K. Lenstra (1984) and Kaltofen (1982) showed that multivariate polynomials over fintie fields can be factored in polynomial time. Gao and Lauder (2002) proved that Hensel lifting method for polynomial time in $\mathbb{F}_{q}[x, y]$ is fast on average (almost linear). Van Hoeij (2002) improved the LLL lattice reduction method for factoring in $\mathbb{Q}[x]$ whose key idea is to recombine the logarithmic derivatives of lifted factors and use a small lattice. And Belabas, von Hoeij and Kluners (2002) generalized Hoeij's method from $\mathbb{Q}$ to more general global fields including $\mathbb{K}(y)[x]$. Gao (2003) gave a PDE approach to factor $f \in \mathbb{K}[x, y]$ requiring that $p>2 n^{2}-1$, where $c h a r=p$ and $n$ is the total degree of $f$ and also works for absolute factorization and mumerical factor-
ing over $\mathbb{R}$ or $\mathbb{C}$ (coefficients of $f$ are approximate). Lecerf (2006) presented, when the field characterisitc is zero or sufficiently large, recombination algorithms which only cost subquadratic time in term of the total degree, and Lecerf (2007) gave a new recombination algorithm that works for fields of any characteristic and lifts only to the total degree.

We are interested in two aspects, efficient bivariate polynomial factorization and deterministic algorithms for univariate polynomial factorization over finite fields.

Suppose $\mathbb{K}$ is a commutative field containing $\mathbb{F}_{q}$ with characteristic $p$. Let $f \in$ $\mathbb{K}[x, y]$ be square free. Suppose

$$
\begin{equation*}
f=f_{1} f_{2} \cdots f_{r} \tag{1.1}
\end{equation*}
$$

where $f_{i} \in \mathbb{K}[x, y]$ are irreducible and distinct. We want to find these irreducible factors. The basic idea of current approaches can be summarized by the following diagram:

$$
\begin{gathered}
f \in \mathbb{K}[x, y] \\
\downarrow \in \mathbb{K}[y] /(\phi(y))[x] \\
\downarrow \bmod ^{2} \phi(y) \\
f \equiv f_{1}^{(1)} f_{2}^{(1)} \cdots f_{s}^{(1)} \bmod \phi(y) \\
\downarrow \\
\downarrow \equiv f_{1}^{(m)} f_{2}^{(m)} \cdots f_{s}^{(m)} \bmod \phi(y)^{m} \\
\downarrow \\
\downarrow \\
f_{1}, f_{2}, \cdots, f_{r}
\end{gathered}
$$

It is possible that $f$ is irreducible but $f(\bmod \phi(y))$ has many factors for all $\phi(y)$. Thus the combination stage could have exponential running time. For example, the follow-
ing polynomial is irreducible

$$
f(x, y)=\prod_{i=1}^{n}(x-i)+y \cdot g(x, y)
$$

But, if $\phi(y)=y$, we have

$$
f(x, y) \equiv \prod_{i=1}^{n}(x-i) \quad(\bmod \phi(y))
$$

For another example, the following polynomial is irreducible

$$
f(x, y)=\prod(x \pm \sqrt{y} \pm \sqrt{y+1} \pm \cdots \pm \sqrt{y+t-1}) \in \mathbb{F}_{q}[x, y]
$$

where the product is over all choices of + and - . However, for every irreducible $\phi(y) \in$ $\mathbb{F}_{q}[y]$, the irreducible factors of $f \bmod \phi(y)$ all have degrees $\leq 2$.

In the worst case, it needs to try $2^{n}$ combinations. In practice, however most polynomials have only a small number of modular irreducible factors. So the above approach is efficient for most polynomials.

In our approach, we want to use a solution basis for modified Berlekamp equation (1.4) or Neiderreiter equation (1.5) to find factors. The question is how to find a solution space (1.8) for any of these two equations. When $\mathbb{K}=\mathbb{F}_{q}$, each of the equations is a linear system over $\mathbb{F}_{q}$, with the coefficients of $h$ as unknowns. The system can be solved by any fast algorithms in the literature. In the case when $\mathbb{K}$ is a function field, say $\mathbb{K}=\mathbb{F}_{q}(x)$. We show how to find the solutions via Hensel lifting. The details will be presented in chapter 2.

We are also interested in the deterministic complexity of factoring polynomials over finite fields. Given any polynomial $f \in \mathbb{F}_{q}[x]$ of degree $n$, we want to find a proper factor of $f$. There exist several randomized algorithms to factor $f$ over $\mathbb{F}_{q}$ with complexity
in polynomial time $(\log q, \operatorname{deg} f)^{O(1)}$, see for examples, Berlekamp (1970), Cantor and Zassenhaus (1981), von zur Gathen and Shoup (1992), Kaltofen and Shoup (1998). Nevertheless, it is still an open problem whether there exist any deterministic algorithm running in polynomial time in $n$ and $\log p$.

It is a major open problem in computer science whether $P=R P$. Recall that $P$ is the collection of problems that can be solved by deterministic algorithms in polynomial time, $R P$ is the collection of problems that can be solved by randomized algorithms in polynomial time. The main issue is whether random numbers are necessary in efficient computing. For a simple example, consider the following problem. Given a prime $p$, find a quadratic nonresidue $a \in \mathbb{F}_{p}\left(a \neq b^{2}(\bmod p)\right.$ for all $\left.b \in \mathbb{F}_{p}\right)$. This can be solved by the following algorithm.

Randomized algorithm: Find a quadratic nonresidue
Input: $\quad p$ a prime
Output: $\quad$ "Failure" or $a \in \mathbb{F}_{p}$ a quadratic nonresidue
Step1: Pick $a \in \mathbb{F}_{p} \backslash\{0\}$ at random
Step2: Compute $b:=a^{\frac{p-1}{2}}(\bmod p)$
Step3: If $b=1$ then output "Failure", otherwise output $a$
The algorithm outputs a quadratic nonresidue $a \in \mathbb{F}_{p}$ with probability $1 / 2$. Run the algorithm 100 times to get a quadratic nonresidue in $\mathbb{F}_{p}$ with probability $1-2^{-100}$.

However, we don't know any deterministic algorithm for this problem. A simple approach is to test $a=1,2,3, \cdots$ until a quadratic nonresidue is found. The problem is to find a good bound for the smallest quadratic nonresidue mod $p$. Under extended Riemann Hypothesis (ERH), N.C. Ankeny (1952), Y. Wang (1959), E. Bach (1990) gave a upper bound $2 \log ^{2} p$. Hence, under GRH, there exists a deterministic polynomial time algorithm to find a quadratic nonresidue.

Berlekamp algorithm reduces general polynomials in $\mathbb{F}_{q}[x]$ deterministically to poly-
nomials that are separable and split completely. It can be shown that factoring quadratic polynomials is equivalent to finding a quadratic nonresidue in $\mathbb{F}_{p}$. We do not know any deterministic polynomial time algorithm for factoring quadratic polynomials without assuming GRH. Bach, von zur Gathen and Lenstra (2001) proved that it is polynomial time if $\phi_{K}(p)$ is smooth for some $k$ where $\phi_{k}(x)$ is the $k$-th cyclotomic polynomial. Ronyai [Ronyai92] proved that under GRH $f$ can be factord in polynomial time modulo $p$ in deterniminstic polynomial time except for finitely many primes $p$ if $\mathbb{Q}[x] / f$ is a Galois extension. This result extends previous work of Huang (1991), Evdokimov (1989) and Adleman, Manders and Miller (1977). Evdokimov (1994) gave a subexponential-time algorithms in $n^{\log n}$ and $\log q$ under GRH. Gao (1996) showed that hard-to-factor polynomials must be square balanced. Recently, Ivanyos, Karpinski and Saxena (2008) demonstrate the level $r$ in Evdokimov's algorithm (1994) can be reduced to $\frac{\log n}{1.5}$ and gave the first deterministic polynomial time algorithm to find a nontrivial factor of a polynomial of prime degree $n$ where $(n-1)$ is a smooth number.

Evdokimov (1992) gave an exponential deterministic polynomial time algorithm with complexity $\left(n^{\log _{2} n} \log q\right)^{O(1)}$ to factor $f$ into irreducible factors over $k$, assuming GRH (generalized Riemann Hypothesis) and $f$ of degree $n$ over an explicitly given finite field $k$ of cardinality $q$. Ivanyos, Karpinski and Saxena (2008) showed it only needs to extend $\frac{\log _{2} n}{\log _{4} 8}$ levels instead of $\log _{2} n$ in Evdokimov (1992). We continue this line of research for deterministic polynomial time algorithms under GRH and reduce the levels by a constant as stated in the following theorem 3.5.13 in Chapter 3.

Theorem 1.1.1. Let $\ell(n)$ be the extension needed to find a factor of polynomial of degree $n$, then $\ell(n) \leq \frac{\log _{2} n}{\log _{4} 12}$.

### 1.2 Basic theory for factoring univariate polynomials

In this section, we give a brief survey of results that are essential for factoring univariate polynomials. In chapter 2, we shall show how to use these results for factoring bivariate polynomials.

Let $\mathbb{K}$ be a commutative field containing $\mathbb{F}_{q}$ with characteristic $p$. Let $f \in \mathbb{K}[x]$ be squarefree and suppose it factors as

$$
\begin{equation*}
f=f_{1} f_{2} \cdots f_{r} \tag{1.2}
\end{equation*}
$$

where $f_{i} \in \mathbb{K}[x]$ are irreducible and distinct, which we want to find. There are several methods to do this, each of them reduces the problem to a linear algebra problem. More precisely, Berlekamp's method finds all $g \in \mathbb{K}[x]$ satisfying $\operatorname{deg}(g) \leq \operatorname{deg}(f)$,

$$
\begin{equation*}
g^{q} \equiv g \quad(\bmod f) \tag{1.3}
\end{equation*}
$$

which is equivalent to

$$
\begin{equation*}
h^{q} \equiv\left(f^{\prime}\right)^{q-1} h \quad(\bmod f) \tag{1.4}
\end{equation*}
$$

Note that (1.3) and (1.4) are equivalent only if $f$ is squarefree, in fact

$$
h=g \cdot f^{\prime} \quad(\bmod f)
$$

Niederreiter's method considers the differential equation

$$
\begin{equation*}
H^{(q-1)}\left(\frac{h}{f}\right)=\left(\frac{h}{f}\right)^{q}, \tag{1.5}
\end{equation*}
$$

where $H^{(q-1)}$ is the $(q-1)$-th Hasse derivative on $\mathbb{F}_{q}[x]$ defined by

$$
H^{(q-1)}\left(x^{i}\right)=\binom{i}{q-1} x^{i-(q-1)} .
$$

Also, Wan considers the equation

$$
\begin{equation*}
\psi_{q}\left(f^{q-1} x h\right)=(x h)^{[q]} \tag{1.6}
\end{equation*}
$$

where

$$
g^{[q]}=\sum a_{i}^{q} x^{i},
$$

if $g=\sum a_{i} x^{i} \in \bar{K}((x))$, and $\psi_{q}$ is the $\mathbb{K}$-linear operator on $\mathbb{K}((x))$ defined by

$$
\psi_{q}\left(x^{u}\right)=\left\{\begin{array}{cl}
x^{u / q}, & \text { if } q \mid u \\
0, & \text { otherwise }
\end{array}\right.
$$

Theorem 1.2.1 (Niederreiter 1993). Let $f \in \mathbb{K}[x]$ be squarefree with $r$ distinct irreducible factors as in (1.2). Then $\operatorname{dim}_{\mathbb{F}_{q}}\left(N_{f}\right)=r$, and every $h$ to (1.5) is of the form:

$$
h=\sum_{i=1}^{r} \lambda_{i} E_{i}
$$

where $\lambda_{i} \in \mathbb{F}_{q}$ and $E_{i}=\frac{f}{f_{i}} f_{i}^{\prime}$ for $1 \leq i \leq r$.

Proof. Each irreducible factors $f_{i}$ can be written as

$$
f_{i}=\prod_{j=1}^{\ell}\left(x-\beta_{i j}\right), \quad \beta_{i j} \in \overline{\mathbb{K}}, \quad 1 \leq i \leq r .
$$

We order the elements $\beta_{i j}$ 's as $\left(\beta_{1}, \beta_{2}, \cdots, \beta_{n}\right)$. Then $\beta_{1}, \beta_{2}, \ldots, \beta_{n}$ are distinct and are all
the roots of $f$ in the algebraic closure of $\mathbb{K}$. Hence

$$
f=c \prod_{i=1}^{n}\left(x-\beta_{i}\right)
$$

where $c \in \mathbb{K}$ is the leading coefficient of $f$. Since $\operatorname{deg}_{x}(h)<\operatorname{deg}_{x}(f)$, we have

$$
\begin{equation*}
\frac{h}{f}=\sum_{i=1}^{n} \frac{b_{i}}{x-\beta_{i}}, \tag{1.7}
\end{equation*}
$$

where $b_{i}=\frac{h\left(\beta_{i}\right)}{f^{\prime}\left(\beta_{i}\right)} \in \overline{\mathbb{K}}, 1 \leq i \leq n$. Hence

$$
H^{(q-1)}\left(\frac{h}{f}\right)=\sum_{i=1}^{n} H^{(q-1)}\left(\frac{b_{i}}{x-\beta_{i}}\right)=\sum_{i=1}^{n} \frac{-b_{i}}{x^{q}-\beta_{i}^{q}},
$$

So (1.4) becomes

$$
\sum_{i=1}^{n} \frac{-b_{i}}{x^{q}-\beta_{i}^{q}}+\sum_{i=1}^{n} \frac{b_{i}^{q}}{x^{q}-\beta_{i}^{q}}=0
$$

which implies that $b_{i}=b_{i}^{q}$, i.e. $b_{i} \in \mathbb{F}_{q}$ for $1 \leq i \leq n$.
If $\beta_{i}$ and $\beta_{j}$ are conjugates over $\mathbb{K}$, i.e. if they are roots of the same irreducible factor of $f \in \mathbb{K}[x]$, then there exists an $\sigma \in \operatorname{Gal}(\overline{\mathbb{K}} / \mathbb{K})$ such that $\sigma\left(\beta_{i}\right)=\beta_{j}$. Hence

$$
b_{i}=\sigma\left(b_{i}\right)=\sigma\left(\frac{h\left(\beta_{i}\right)}{f^{\prime}\left(\beta_{i}\right)}\right)=\frac{h\left(\sigma\left(\beta_{i}\right)\right)}{f^{\prime}\left(\sigma\left(\beta_{i}\right)\right)}=\frac{h\left(\beta_{i}\right)}{f^{\prime}\left(\beta_{i}\right)}=b_{j},
$$

Thus $b_{i}=b_{j}$ whenever $\beta_{i}$ and $\beta_{j}$ are roots of the same irreducible factor of $f$.
For each irreducible factor $f_{i}$ of $f$, we group the terms in (1.7) where $\beta_{j}$ is a root of $f_{i}$ and let $\lambda_{i}$ be the common value of these $b_{j}$. Then

$$
\frac{h}{f}=\sum_{i=1}^{r} \lambda_{i} \sum_{\beta: \text { root of } f_{i}} \frac{1}{x-\beta}=\sum_{i=1}^{r} \lambda_{i} \frac{1}{f_{i}} \frac{\partial f_{i}}{\partial x} .
$$

Therefore

$$
h=\sum_{i=1}^{r} \lambda_{i} \frac{f}{f_{i}} \frac{\partial f_{i}}{\partial x}
$$

as claimed by the theorem.
Since $f_{i}$ 's are distinct, we see that $E_{i}$ 's are linearly independent over $\mathbb{F}_{q}$. This proves that $E_{1}, E_{2}, \cdots, E_{r}$ form a basis over $\mathbb{F}_{q}$ for the solution space.

Theorem 1.2.2. Let $f \in \mathbb{K}[x]$ be squarefree with $r$ distinct irreducible factors. Then (1.4), (1.5) and (1.6) have the same solution space.

$$
\begin{equation*}
H=\{h \in \mathbb{K}[x]: h \text { satisfies (1.4) }\} . \tag{1.8}
\end{equation*}
$$

### 1.3 Geometric structure of Gröbner bases

We assume $f$ is squarefree that splits completely over finite fields. Let $S$ be the set of roots of $f$. We construct ideals extended from $\langle f(x)\rangle$ and varieties extended from $S$. We show how to use Gröbner bases structure theorem to decompose these ideals and varieties, and how those might lead to proper factors of $f$ which is to be factored.

In the following, we describe a correspondence between the geometric structure of the variety of a zero-dimensional radical ideal and its Gröbner basis under elimination order. This will be one of the main tools to split polynomial system.

Let $\mathbb{F}$ be any field. For any ideal $I \subset \mathbb{F}\left[x_{1}, x_{2}, \cdots, x_{n}\right]$, let $V(I)$ be the set of common solutions of $I$ in $\overline{\mathbb{F}}^{n}$. We call $V(I)$ the variety of $I$. For an ideal $I$, we are interested in the structure of its variety $V(I)$. In particular, we want to know the number of extensions of particular solutions.

For a set of points $V \in \overline{\mathbb{F}}^{n}$, we say $\left(a_{1}, a_{2}, \cdots, a_{i-1}\right)$ is a partial point of $V$, for any $2 \leq i \leq n$, if there exist $a_{i}, \cdots, a_{n}$ such that $\left(a_{1}, a_{2}, \cdots, a_{i-1}, a_{i}, \cdots, a_{n}\right)$ is a point in $V$.

Definition 1.3.1. Let $V \subset \overline{\mathbb{F}}^{n}$ and $\left(a_{1}, a_{2}, \cdots, a_{i-1}\right)$ is a partial point in $V$. We define the fiber size of above $\left(a_{1}, a_{2}, \cdots, a_{i-1}\right)$ to be

$$
\#\left\{b \in \overline{\mathbb{F}}:\left(a_{1}, \cdots, a_{i-1}, b\right) \text { is a partial point in } V\right\} .
$$

We say fibre sizes of $V$ at level $i$ to be the fibre sizes above all partial points $\left(a_{1}, a_{2}, \cdots, a_{i-1}\right)$ of $V$.

We define a projection map $\pi$ as follows. Let a set of points $V \subset \overline{\mathbb{F}}^{n}$.

$$
\begin{aligned}
& \pi: \quad V \rightarrow \overline{\mathbb{F}}^{n-1} \\
& \quad\left(a_{1}, a_{2}, \cdots, a_{n-1}, a_{n}\right) \mapsto\left(a_{1}, a_{2}, \cdots, a_{n-1}\right)
\end{aligned}
$$

Let $W=\pi(V)$. Given first $n-1$ coordinates of a point from $V$, we denote

$$
\pi^{-1}\left(a_{1}, \cdots, a_{n-1}\right)=\left\{b \in \overline{\mathbb{F}}:\left(a_{1}, \cdots, a_{n-1}, b\right) \in V\right\}
$$

According to distinct fibre sizes above $n-1$ level, $V$ can be partitioned by one to one correspondence as

$$
V=P_{1} \cup \cdots \cup P_{r}
$$

where any two points $u, v \in P_{i}$ have the property that $\pi(u)$ and $\pi(v)$ share a common fibre size $m_{i}, 1 \leq i \leq r$.

Example 1.3.2. Suppose we have the following points: $P=\{(0,0,1),(0,0,4),(0,0,2)$ $,(0,4,0),(2,2,3),(2,3,1),(3,1,2),(3,1,3)\}$. The fiber sizes are $(0,0),\left|\pi^{-1}(0,0)\right|=3$, $\pi^{-1}(3,1)=2, \pi^{-1}(0,4)=1, \pi^{-1}(2,2)=1, \pi^{-1}(2,3)=1$. So $P_{2}=\pi(P)=\{(0,0)\} \cup$ $\{(3,1)\} \cup\{(0,4),(2,2),(2,3)\}$.


Figure 1.1: Points Structure

## Definition 1.3.3. (Uniform).

We say that the set $V$ is uniform at level $i$ or above level $i-1$, if the fibre size of any partial point $\left(a_{1}, \cdots, a_{i-1}\right)$ in $V$ is a constant.

If it is uniform for each level to the next, we say the points are totally uniform.
Now we give an example that all fiber sizes are the same as follows.

Example 1.3.4. Points are $\{(1,2),(1,3),(2,3),(2,4),(3,4),(3,5),(4,1),(4,5),(5,1),(5,2)\}$. All fiber sizes of $\pi(s), s \in P_{2}$ are 2. We say that it is uniform from level 1 to level 2 in this case.


Figure 1.2: Regular graph

The variety of a radical zero-dimensional ideal $I, V(I)$ has an partition according to fiber sizes. Can we tell about Gröbner basis of $I$ from the information of fibre sizes of $V(I)$, or vice verse? The main theorem of Gao, Rodrigues, and Stroomer (2003) answered this question.

Theorem 1.3.5 (Gao, Rodrigues, and Stroomer 2003). Let $\mathbb{F}$ be a perfect field, I a zerodimensional radical ideal in $\mathbb{F}\left[x_{1}, x_{2}, \cdots, x_{n}\right]$, and $P_{n}$ the set of points of $V(I)$ in $\overline{\mathbb{F}}^{n}$. Assume the fibre sizes in $P_{n}$ are $0<m_{1}<m_{2}<\cdots<m_{r}$. Let $G$ be any minimal Gröbner basis for I under an elimination order for $x_{n}$, i.e. $x_{n}>x_{1}, x_{2}, \cdots, x_{n-1}$. View the elements of $G$ as polynomials in $x_{n}$ with coefficients in $\mathbb{F}\left[x_{1}, x_{2}, \ldots, x_{n-1}\right]$, and group polynomials in $G$ by their degrees in $x_{n}$ as follows.

$$
G=G_{0} \cup G_{1} \cup G_{2} \cdots \cup G_{t},
$$

where $G_{i}$ denotes all polynomials in $G$ with a common degree in $x_{n}$. Then
(1). $t=r$, and the degree of $x_{n}$ in $G_{i}$ is $m_{i}, 1 \leq i \leq r$.
(2). For $1 \leq i \leq r$, let $L c_{<m_{i}}(G) \subset \mathbb{F}\left[x_{1}, x_{2}, \ldots, x_{n-1}\right]$ denote the leading coefficients of the polynomials in

$$
G_{0} \cup G_{m_{1}} \cup G_{m_{2}} \cdots \cup G_{m_{i-1}}
$$

Let $P_{n-1}=\pi\left(P_{n}\right), P_{n-1, i}=\left\{A \in P_{n-1}| | \pi^{-1}(A)=m_{i}\right\}$, and

$$
P_{n-1, \geq i}=P_{n-1, i} \cup P_{n-1, i+1} \cdots \cup P_{n-1, r} .
$$

Then $L c_{<m_{i}}(G)$ is a Gröbner basis for I s.t. $V(I)=P_{n-1, \geq m_{i}}$ for $1 \leq i \leq r$.

Remark 1: One simple conclusion made from the theorem is that points projected with fibre size $\geq m_{i}$ vanish all of those leading coefficients of terms with $\operatorname{deg}_{x_{n}}<m_{i}$ in the Groeber Basis $G$. The coefficient of the polynomial in $G$ with highest degree in $x_{n}$ is 1 .

Remark 2: Under the elimination order on $x_{n}$, the degree in $x_{n}$ of the items in the minimal Gröbner basis are exactly the fibre sizes of $\pi(V(I))$.

Example 1.3.6. Let $P=\{(1,3,1),(1,3,2),(1,1,1),(2,1,3),(2,1,2),(2,4,1)\}$.


Figure 1.3: An example
$P_{2}=\pi_{3}(P)=\{(1,3),(1,1),(2,1),(2,4)\}$. Then $P_{2}=S_{1} \cup S_{2} . S_{1}=\{(1,3),(2,1)\}$, $m_{1}=2 ; S_{2}=\{(1,1),(2,4)\}, m_{2}=1$. So fiber sizes from 2-level to 3-level of $P$ are 1 and 2. Let $I=I(P)$. Under elimination order $x_{1}<x_{2}<x_{3}$, the Gröbner Basis consists of the following polynomials:

$$
\begin{aligned}
& g_{0}=x^{2}-3 x+2 \\
& g_{1}=y^{2}-x y-3 y+x+2 \\
& g_{2}=(2 x+y-5) z-y-2 x+5 \\
& g_{3}=3 z^{2}-6 x z-3 z-2 x y+2 y+14 x-8
\end{aligned}
$$

So the leading terms are $\left\{x^{2}, y^{2}, z, z^{2}\right\} . z$ and $z^{2}$ 's degree are 1 and 2, exactly the fiber sizes of $P_{2}$. And $I_{0}=\left\{g_{0}, g_{1}\right\}$ is a Gröbner basis for $P_{2}, I_{1}=\left\{g_{0}, g_{1}, 2 x+y-5\right\}$ is a Gröbner basis for $I\left(S_{1}\right)$ according to the theorem 1.3.5. By using quotient operation, we can compute a Gröbner basis for The ideal generated by $S_{2}$, since $I\left(S_{2}\right)=I_{0}: I_{1}$.

Example 1.3.7. Suppose I has the following Gröbner basis $\{(x-1)(x-2),(x-2) y+$ $\left.1, y^{2}-1\right\}$ under lex order $x<y$. And fibre sizes of $x$ are 1 and 2 because the degree of $y$ is 1 and 2.

Given an ideal $I$, let $P=V(I)$. If under elimination order on $x_{n}$, it is uniform from $\pi_{n}(P)$ to $P$, then $I$ has a minimal Gröbner basis of the form, $G=G_{0} \cup g$, where $L T(g)=x_{n}^{m}, m$ is a constant. If $P$ is totally uniform under lex order $x_{1} \prec x_{2} \prec \cdots, \prec x_{n}$, then $G=\left\{g_{1}\left(x_{1}\right), x_{2}^{m_{2}}+g_{2}\left(x_{1}, x_{2}\right), \cdots, x_{n}^{m_{n}}+g_{n}\left(x_{1}, x_{2}, \cdots, x_{n}\right)\right\}$ where $x_{i}^{m_{i}}$, s is the
leading term of $i$-th polynomial.

Example 1.3.8. Let $P=\{(1,4,1),(1,4,2),(1,4,4),(1,2,1),(1,2,2),(1,2,5)$,
$(2,3,1),(2,3,4),(2,3,3),(2,2,7),(2,2,2),(2,2,3)\}$.


Figure 1.4: An uniform case

Using lex order with $x \leq y \leq z$, the reduced Gröbner basis $G$ of $I(P)$ is given by the polynomials below:

$$
\begin{aligned}
& g_{0}=x^{2}-3 x+2 \\
& g_{1}=y^{2}-x y-2 x-7 y+10 \\
& g_{2}=2 z^{3}+(7 x y-6 y-22 x+4) z^{2}+(-41 x y+38 y+130 x-90) z+58 x y-56 y-180 x+156
\end{aligned}
$$

As stated in theorem 1.3.5, $L c_{<m_{i}}(G)$ is a Gröbner basis for $P_{n-1, \geq m_{i}}$ for $1 \leq i \leq$ $r . I\left(L c_{<m_{i}}(G)\right) \subset I\left(L c_{<m_{i+1}}(G)\right)$. So, we can use quotient to compute the ideal vanished at points with fibre size exactly $m_{i}$.

If $I$ is not uniform, by the structure theorem, then not all leading coefficients are constants. In this case, we can refine the ideal. For example, in example 1.3.6 $G_{0}=$ $\left\{x^{2}-3 x+2, y^{2}-x y-3 y+x+2\right\} . G_{1}=\left\{g_{0}, g_{1}, 2 x+y-5\right\}=\left\{x^{2}-3 x+2,2 x+y-5\right\}$ is a Gröbner basis for $I\left(S_{1}\right)$ with fibre sizes bigger than 1.Variety of $G_{1}$ is $S_{1}=\{(1,3),(2,1)\}$. $J_{1}=I_{0}: I\left(S_{1}\right)=I\left(x^{2}-3 x+2, y-3 x+2\right)$, which is exactly the ideal vanishes on points set $S_{2}=\{(1,1),(2,4)\}$ with fibre size exactly 1 . We can write $I$ as an intersection $I=I\left(x^{2}-3 x+2, y-3 x+2, z-1\right) \cap I\left(x^{2}-3 x+2,2 x+y-5, z^{2}-2 x z-z+4 x-2\right)$.

Theorem 1.3.9. For each $1 \leq i \leq r, J_{i}$ is a Gröbner Basis for the points in $S=\pi(P)$ that are projections of fibres of size exactly $m_{i}$. Then

$$
J_{i}=<G_{i-1}>:<G_{i}>.
$$

We will show this can be computed in deterministic polynomial time in Section 3.2.

Example 1.3.10. Let's consider the example 1.3.6. $G_{0}=\left\{x^{2}-3 x+2, y^{2}-x y-3 y+x+2\right\}$.
Let $I_{0}=I\left(G_{0}\right)$ with $V\left(I_{0}\right)=V\left(P_{2}\right)=\{(1,3),(1,1),(2,1),(2,4)\}$.
And $G_{1}=\left\{g_{0}, g_{1}, 2 x+y-5\right\}=\left\{x^{2}-3 x+2,2 x+y-5\right\}$ is a Gröbner basis for $I\left(S_{1}\right)$ with fibre sizes bigger than 1.Variety of $G_{1}$ is $S_{1}=\{(1,3),(2,1)\} . J_{1}=I_{0}$ : $I\left(S_{1}\right)=I\left(x^{2}-3 x+2, y-3 x+2\right)$, which is exactly the ideal vanishes on points set $S_{2}=\{(1,1),(2,4)\}$ with fibre size exactly 1.

## Chapter 2

## Factoring bivariate polynomials via lifting linear spaces

We present a new modular approach that does not need any recombination of factors. Instead of lifting modular factors we lift the linear space of solutions and get complete factorization directly from lifted solutions.

### 2.1 Lifting Berlekamp's linear spaces

From now on, we assume $f \in \mathbb{F}_{q}[y][x]$. To solve (1.4), let $\phi(y) \in \mathbb{F}_{q}[y]$ be irreducible, we consider

$$
h^{q} \equiv\left(f^{\prime}\right)^{q-1} h \quad(\bmod f, \phi(y))
$$

where

$$
h=\sum_{i=0}^{n-1} a_{i}(y) x^{i}, \operatorname{deg}_{y} a_{i}(y)<\operatorname{deg}_{y} \phi(y) .
$$

This is a linear system over $\mathbb{F}_{q}$ with $N$ unknowns and $N$ equations respectively, where $N=n \operatorname{deg}_{y} \phi(y)$.

Theorem 2.1.1. let $\phi(y) \in \mathbb{F}_{q}[y]$ be irreducible such that $f(\bmod \phi)(y)$ is square free. Let
$m \geq 1$ and $h_{0} \in \mathbb{F}_{q}[x, y]$ such that

$$
h_{0}^{q} \equiv\left(f^{\prime}\right)^{q-1} h_{0} \quad\left(\bmod f(x, y), \phi^{m}(y)\right)
$$

Then there exists a unique $g \in \mathbb{F}_{q}[y][x]$ such that $\operatorname{deg}_{y}(g)<\operatorname{deg}(\phi), \operatorname{deg}_{x}(g)<n$, and

$$
\left(h_{0}+g \phi^{m}\right)^{q} \equiv\left(f^{\prime}\right)^{q-1}\left(h_{0}+g \phi^{m}\right) \quad\left(\bmod f(x, y), \phi^{m+1}(y)\right)
$$

In fact

$$
g \equiv \frac{h_{0}^{q}-\left(f^{\prime}\right)^{q-1} h_{0}}{\phi^{m}} \frac{1}{\left(f^{\prime}\right)^{q-1}} \quad(\bmod f, \phi(y))
$$

Remark: Since $h_{0}^{q} \equiv\left(f^{\prime}\right)^{q-1} h_{0}\left(\bmod f, \phi^{m}(y)\right), h_{0}^{q}-\left(f^{\prime}\right)^{q-1} h_{0} \bmod \left(f, \phi^{m+1}\right)$ is divisible by $\phi^{m}$. So it is $h_{0}^{q} \equiv\left(f^{\prime}\right)^{q-1} h_{0}$ is computed $\left(\bmod f, \phi^{m+1}(y)\right)$ first, then divided by $\phi^{m}$. The quotient is then multiplied with the other term modulo $(f, \phi(y))$. Also $\left(f^{\prime}\right)^{q-1}$ only needs to be computed $\bmod (f, \phi(y))$ once.

### 2.2 Lifting Niederreiter's linear spaces

Lifting via Niederreiter's equation is much more complicated, we will show how this can be done in polynomial time.. We consider Niederreiter' differential equation (1.5) Let

$$
h=\sum_{i=0}^{n-1} a_{i} x^{i}, \quad f^{q-1}=\sum_{j=0}^{(q-1) n} b_{j} x^{j}
$$

where $a_{i}, b_{j} \in \mathbb{F}_{q}[y]$. We can rewrite (1.5) as

$$
\sum_{i=0}^{n-1} b_{l q+q-1-i} \cdot a_{i}=a_{l}^{q}, \quad 0 \leq l \leq n-1,
$$

or equivalently,

$$
\left(\begin{array}{llll}
b_{q-1} & b_{q-2} & \cdots & b_{q-n} \\
b_{2 q-1} & b_{2 q-2} & \cdots & b_{2 q-n} \\
\vdots & \vdots & \vdots & \vdots \\
b_{(n-1) q-1} & b_{(n-1) q-2} & \cdots & b_{(n-1) q-n} \\
b_{n q-1} & b_{n q-2} & \cdots & b_{n q-n}
\end{array}\right)\left(\begin{array}{l}
a_{0} \\
a_{1} \\
\vdots \\
a_{n-2} \\
a_{n-1}
\end{array}\right)=\left(\begin{array}{c}
a_{0}^{q} \\
a_{1}^{q} \\
\vdots \\
a_{n-2}^{q} \\
a_{n-1}^{q}
\end{array}\right) .
$$

We show how to compute this matrix in the appendix.

Lemma 2.2.1. Let $\mathbb{K}$ be any field containing $\mathbb{F}_{q}$ and $g \in K[x]$ such that $\operatorname{gcd}\left(g, g^{\prime}\right)=1$. Then, for any $w \in K[x]$ with $\operatorname{deg} w<\operatorname{deg} g=n$, there exists a unique $h \in K[x]$ with $\operatorname{deg} h<n$ such that

$$
\begin{equation*}
H^{(q-1)}\left(\frac{h}{g}\right)=\left(\frac{w}{g}\right)^{q} \tag{2.1}
\end{equation*}
$$

Proof. Since $\operatorname{gcd}\left(g, g^{\prime}\right)=1, g$ is separable. Let $K_{g}$ be the splitting field of $g$ over $K$. Let $\beta_{1}, \cdots, \beta_{n}$ be the $n$ distinct roots of $g$ in $K_{g}$. Then

$$
\frac{w}{g}=\sum_{i=1}^{n} \frac{w_{i}}{x-\beta_{i}}
$$

where $w_{i}=\frac{w\left(\beta_{i}\right)}{g^{\prime}\left(\beta_{i}\right)}$. So

$$
\left(\frac{w}{g}\right)^{q}=\sum_{i=1}^{n} \frac{w_{i}^{q}}{x^{q}-\beta_{i}^{q}} .
$$

By interpolation, there is an $h \in K_{g}[x]$ such that $\operatorname{deg} h<n$ and $h\left(\beta_{i}\right)=w_{i}^{q} g^{\prime}\left(\beta_{i}\right), 1 \leq i \leq$ $n$. Then

$$
\frac{h}{g}=\sum_{i=1}^{n} \frac{h_{i}}{x-\beta_{i}}, \text { where } h_{i}=\frac{h\left(\beta_{i}\right)}{g^{\prime}\left(\beta_{i}\right)}=w_{i}^{q} \quad 1 \leq i \leq n
$$

Note that

$$
H^{(q-1)}\left(\frac{h}{g}\right)=\sum_{i=1}^{n} H^{(q-1)}\left(\frac{h_{i}}{x-\beta_{i}}\right)=\sum_{i=1}^{n} \frac{w_{i}^{q}}{\left(x-\beta_{i}\right)^{q}}=\left(\frac{w}{g}\right)^{q} .
$$

i.e. $h$ satisfies (2.1).

We need to show that $h \in K[x]$. Since $\operatorname{gcd}\left(g, g^{\prime}\right)=1, K_{g}$ is Galois over $K$. Hence, for any $\beta \in K_{g}$, we have $\beta \in K$ iff $\sigma(\beta)=\beta$ for all $\sigma \in \operatorname{Gal}\left(K_{g} / K\right)$. Now each $\sigma \in \operatorname{Gal}\left(K_{g} / K\right)$ extends to a unique a ring isomorphism of $K_{g}[x]$ that fixes all polynomials in $K[x]$. Applying $\sigma$ to (2.1), we see that $\sigma(h)$ is another solution in $K_{g}[x]$. The uniqueness argument below shows that $\sigma(h)=h$ for all $\sigma \in \operatorname{Gal}\left(K_{g} / K\right)$, hence $h \in K[x]$.

It remains to prove the uniqueness of $h$. In fact, we prove the uniqueness for $h \in$ $K_{g}[x]$. Let $u, v \in K_{g}[x]$ be any two solutions to (2.1) with $\operatorname{deg}(u)<n$ and $\operatorname{deg}(v)<n$. Then

$$
H^{(q-1)}\left(\frac{u}{g}\right)=H^{(q-1)}\left(\frac{v}{g}\right) .
$$

Expanding $u / g$ and $v / g$ into partial fractions (similar to $h / g$ above), we see that $u\left(\beta_{i}\right)=$ $v\left(\beta_{i}\right)$ for $1 \leq i \leq n$. Since both $u$ and $v$ have degrees less than $n$, it follows that $u=v$. This completes the proof.

Theorem 2.2.2. For any $m \geq 1$, and $h_{0} \in \mathbb{F}_{q}[y][x]$ such that

$$
\begin{equation*}
H^{(q-1)}\left(\frac{h_{0}}{f}\right) \equiv\left(\frac{h_{0}}{f}\right)^{q} \quad\left(\bmod \phi^{m}\right) \tag{2.2}
\end{equation*}
$$

There exists a unique $h_{1} \in \mathbb{F}_{q}[y][x]$ such that $\operatorname{deg}_{y}\left(h_{1}\right)<\operatorname{deg}(\phi), \operatorname{deg}_{x}\left(h_{1}\right)<n$, and

$$
\begin{equation*}
H^{(q-1)}\left(\frac{h_{0}+h_{1} \phi^{m}}{f}\right) \equiv\left(\frac{h_{0}+h_{1} \phi^{m}}{f}\right)^{q} \quad\left(\bmod \phi^{m+1}\right) \tag{2.3}
\end{equation*}
$$

Furthermore, let

$$
\begin{equation*}
u(x)=\frac{1}{\phi^{m}}\left(h_{0}^{q}-H^{(q-1)}\left(h_{0} f^{q-1}\right)\right) \in \mathbb{F}_{q}[y]\left[x^{q}\right] . \tag{2.4}
\end{equation*}
$$

Then

$$
\begin{equation*}
h_{1}(x)=\frac{u(x)}{f^{\prime}(x)^{q-1}} \quad(\bmod f(x), \phi(y)) . \tag{2.5}
\end{equation*}
$$

Proof. Expanding (2.3), gives

$$
H^{(q-1)}\left(\frac{h_{0}}{f}\right)+\phi^{m} H^{(q-1)}\left(\frac{h_{1}}{f}\right) \equiv\left(\frac{h_{0}}{f}\right)^{q}+\phi^{q m}\left(\frac{h_{1}}{f}\right)^{q} \quad\left(\bmod \phi^{m+1}\right)
$$

So

$$
\frac{1}{\phi^{m}}\left(\left(\frac{h_{0}}{f}\right)^{q}-H^{(q-1)}\left(\frac{h_{0}}{f}\right)\right) \equiv H^{(q-1)}\left(\frac{h_{1}}{f}\right) \quad(\bmod \phi)
$$

which we write as

$$
\begin{equation*}
\frac{u}{f^{q}} \equiv H^{(q-1)}\left(\frac{h_{1}}{f}\right) \quad(\bmod \phi) \tag{2.6}
\end{equation*}
$$

where

$$
\begin{equation*}
u(x)=\frac{1}{\phi^{m}}\left(h_{0}^{q}-H^{(q-1)}\left(h_{0} f^{q-1}\right)\right) \in \mathbb{F}_{q}[y]\left[x^{q}\right] . \tag{2.7}
\end{equation*}
$$

Now there exists unique $w \in \mathbb{F}_{q}[y] /(\phi(y))[x]$ such that $w^{q} \equiv u(\bmod \phi)$, hence (2.6) is equivalent to

$$
H^{(q-1)}\left(\frac{h_{1}}{f}\right) \equiv\left(\frac{w}{f}\right)^{q} \quad(\bmod \phi)
$$

By Lemma 2.2.1 where $K=\mathbb{F}_{q}[y] /(\phi(y))$, there exists a unique $h_{1} \in \mathbb{F}_{q}[y] /(\phi(y))[x]$ that satisfying (2.3). In fact $h=h_{1}$ is the unique polynomial such that

$$
\frac{h}{f}=\sum_{i=1}^{n} \frac{h_{i}}{x-\beta_{i}},
$$

where $h_{i}=\frac{h\left(\beta_{i}\right)}{f^{\prime}\left(\beta_{i}\right)}=w_{i}^{q}$ and $w_{i}=\frac{w\left(\beta_{i}\right)}{f^{\prime}\left(\beta_{i}\right)}$. This means that

$$
h\left(\beta_{i}\right)=\frac{w\left(\beta_{i}\right)^{q}}{f^{\prime}\left(\beta_{i}\right)^{q-1}}=\frac{u\left(\beta_{i}\right)}{f^{\prime}\left(\beta_{i}\right)^{q-1}} .
$$

Therefore, we have

$$
h_{1}(x)=\frac{u(x)}{f^{\prime}(x)^{q-1}} \quad(\bmod f(x), \phi(y)) .
$$

Theorem 2.2.3. For any $m \geq 1$, and $h_{0} \in \mathbb{F}_{q}[y][x]$ such that

$$
\begin{equation*}
H^{(q-1)}\left(\frac{h_{0}}{f}\right) \equiv\left(\frac{h_{0}}{f}\right)^{q} \quad\left(\bmod \phi^{m}\right) \tag{2.8}
\end{equation*}
$$

There exists a unique $g_{m} \in \mathbb{F}_{q}[y][x]$ such that $\operatorname{deg}_{y}\left(g_{m}\right)<\operatorname{deg}(\phi), \operatorname{deg}_{x}\left(g_{m}\right)<n$, and

$$
H^{(q-1)}\left(\frac{h_{0}+g_{m} \phi^{m}}{f}\right) \equiv\left(\frac{h_{0}+g_{m} \phi^{m}}{f}\right)^{q} \quad\left(\bmod \phi^{m+1}\right)
$$

Furthermore, let

$$
\begin{equation*}
u(x)=\frac{1}{\phi^{m}}\left(h_{0}^{q}-H^{(q-1)}\left(h_{0} f^{q-1}\right)\right) \in \mathbb{F}_{q}[y]\left[x^{q}\right] . \tag{2.9}
\end{equation*}
$$

Then

$$
\begin{equation*}
g_{m}(x)=\frac{u(x)}{f^{\prime}(x)^{q-1}} \quad(\bmod f(x), \phi(y)) \tag{2.10}
\end{equation*}
$$

### 2.3 Lifting bound

In [Lecerf, 2007], Lecerf proved that it only needs to lift the solutions to degree at most $d_{y}+1$ in $y$, where $d_{y}$ is the degree of $y$, with differentiation with respect to $x$. Let

$$
\frac{h}{f}=\sum_{i=1}^{n} \frac{\rho_{i}}{x-\phi_{i}},
$$

where $\phi_{i}$ are the distinct roots of $f$ in $\overline{\mathbb{F}}_{q}[[y]]$. If $h$ is a solution, then

$$
\frac{\partial}{\partial y} \rho_{i}=0, \quad \forall i
$$

It is equivalent with the condition that $h$ satisfies $D(h)=0$, i.e. $h \in \operatorname{ker}(D)$, where $D$ is defined as

$$
\begin{aligned}
D: & \mathbb{K}[y, x]_{d_{y}, d_{x}-1} \longrightarrow \mathbb{K}[y, x]_{3 d_{y}, 3 d_{x}-3} \\
& g \mapsto\left(\frac{\partial g}{\partial y} \frac{\partial f}{\partial x}-\frac{\partial g}{\partial x} \frac{\partial f}{\partial y}\right) \frac{\partial f}{\partial x}-\left(\frac{\partial^{2} f}{\partial x y} \frac{\partial f}{\partial x}-\frac{\partial^{2} f}{\partial x^{2}} \frac{\partial f}{\partial y}\right) g .
\end{aligned}
$$

And if $h \in \operatorname{ker} D$, then $\mathcal{N}_{f}(h) \in \mathbb{K}\left[x^{p}, y^{p}\right]_{d_{x}-1, d_{y}}$, where $\mathcal{N}_{f}$ is defined as follows.

$$
\begin{aligned}
\mathcal{N}_{f}: & \mathbb{K}[x, y]_{d_{x}-1, d_{y}} \longrightarrow \mathbb{K}\left[x^{p}, y\right]_{d_{x}-1, p d_{x}}, \\
& g \mapsto g^{p}-H^{(p-1)}\left(f^{p-1} g\right) .
\end{aligned}
$$

For $h \in \mathbb{F}_{q}[x, y]$ with $\operatorname{deg}_{x} h<d_{x}, \operatorname{deg}_{y} h \leq d_{y}$ and $h \in \operatorname{ker} D$. If

$$
h^{p}-H^{(p-1)}\left(f^{q-1} h\right) \equiv 0 \quad(\bmod \psi(y)),
$$

where $\psi(y)$ is any polynomial have $d_{y}+1$ distinct roots in $K$, then $h$ is a true solution.
Theorem 2.3.1 (Lecerf 2007). Let the characteristic of $\mathbb{K}$ be $p>0$ and $g \in \operatorname{ker}(D)$. Let $S$
be an arbitrary set of size $d_{y}+1$. For all $a \in S$, if $\operatorname{Res}_{x}\left(f, \frac{\partial f}{\partial x}\right) \neq 0$ and $\mathcal{N}_{f}(g)(x, a)=0$, then $g$ is a solution to (1.5).

### 2.4 The algorithm of finding a solution basis

Define Berlekamp map as:

$$
\begin{aligned}
\mathcal{B}_{f}: & \mathbb{K}[x, y]_{d_{x}-1, d_{y}} \longrightarrow \mathbb{K}(x)[y] /(f) \\
& h \mapsto h^{q}-\left(f^{\prime}\right)^{q-1} h,
\end{aligned}
$$

that is, for $h \in \mathbb{K}[x, y]_{d_{x}-1, d_{y}}$,

$$
\mathcal{B}_{f}(h)=h^{q}-\left(f^{\prime}\right)^{q-1} h \quad(\bmod f)
$$

In the following algorithm, we mean bad solutions by those with total degree higher than $f$.

## Algorithm 1: Find a solution basis

Input: $f \in \mathbb{K}[x][y], \phi(y) \in \mathbb{K}[y]$ such that $\left(\operatorname{Res}_{x}\left(f, \frac{\partial f}{\partial x}\right)(x, a) \neq 0\right.$
$(\bmod \phi(y))$, and $m$ s.t. $\operatorname{deg}\left(\phi^{m}\right) \geq d_{y}+1$
Output: A solution basis for $N_{f}$

1. Find a basis of solutions of $g$ of $\mathcal{B}_{f}(g)=0(\bmod f, \phi(y))$, say
$G=\left\{g_{1}, \cdots, g_{r}\right\} ;$
2. For $i=1,2 \cdots, m-1$ do
2.1. Lift each $g_{i}$ in $G$ to a solution $\hat{g}$ in $\mathbb{K}[x, y] /<f, \phi^{i+1}>$;
2.2. Use total degree to get rid of bad solutions via Gauss elimination ;
2.3. Update $G$, suppose $G=\left\{\hat{g}_{1}, \cdots, \hat{g}_{t}\right\}$;

## End do ;

3. Check $D(g)=0, \forall g \in G$. Get rid of bad solutions via Gauss elimination ;

Suppose a good basis is $H=\left\{h_{1}, \cdots, h_{r}\right\}$;
4. Find a squarefree polynomial $\psi(y)$ of degree $d_{y}+1$ in $y$ satisfying
$\operatorname{Res}_{x}\left(f, f^{\prime}\right) \neq 0(\bmod \psi(y)) ;$
5. Check $\mathcal{B}_{f}(g) \equiv 0(\bmod f, \psi), g \in H$. Get rid of bad solutions via Gauss elimination and find a basis as output.

Proposition 2.4.1. The algorithm (1) gives correct solution space $N$.
Proof. After we lift to $\left(y^{d_{y}+1}\right)$ and check with the map $D$, we have solutions of $N_{f}$, also belong to $\mathbb{K}\left[x^{p}, y^{p}\right]$. Then we choose $d_{y}+1$ many value for $y$ to check the solutions. By theorem 2.3.1, $g$ s a true solution.

Since solutions modulo $\phi^{m+1}$ can be obtained uniquely by lifting solutions modulo $\phi^{m}$ for each $m \geq 1$. And we don't need to lift each solution, but instead lifting any basis
of solutions to high powers of $\phi$. In each level of lifting, if there are some elements in the basis whose total degree is greater than that of $f$, we eliminate them and update the basis by getting rid of those ones with high degree. We lift $m$ many times and obtain a basis $\left\{b_{1}, b_{2}, \cdots, b_{s}\right\}$. Compute for each $i \in\{1,2, \cdots, s\}$,

$$
\begin{equation*}
t_{i}=b_{i}^{q}-H^{(q-1)}\left(b_{i} f^{q-1}\right) \quad\left(\bmod f(x), \phi_{1}(y)\right) . \tag{2.11}
\end{equation*}
$$

If $b_{i}$ is a solution for (1.5), then (2.11) should be 0 . Thus we eliminate $\left\{t_{1}, t_{2}, \cdots, t_{s}\right\}$ by linear combination to find a set of coefficients $l_{i}=\left\{l_{i 1}, \cdots, l_{i s}\right\}$ such that $\sum_{k=1}^{s} l_{i k} t_{k}=0$. Then from the proposition, we claim that

$$
\left\{\sum_{k=1}^{s} l_{1 k} b_{k}, \cdots, \sum_{k=1}^{s} l_{r k} b_{k}\right\}
$$

is the right basis for (1.5).
Remark: Lecerf's method uses the map $D$ to do recombination and $\mathcal{N}_{f}$ or $\mathcal{B}_{f}$ to check. When characteristic is not high enough or zero, he uses $\mathcal{N}_{f}$ to do more combination. Our way is to use modified berlekamp's equation to solve solution space without recombination and lift the solution basis, but use the map $D$ to check solutions.

### 2.5 Finding factors from a solution basis

Let $h(x, y)$ be any solution of (1.5), then

$$
f=\prod_{\lambda \in \mathbb{F}_{q}} \operatorname{gcd}\left(f, h-\lambda f^{\prime}\right)
$$

Use all $h$ from a solution basis for (1.5), we can find all factors of $f$.
Algorithm 2: Find factors
Input: $f \in \mathbb{K}[x][y]$, solutions $h_{1}, \cdots, h_{r}$ and $\phi(y)$,
Output: factors of $f$.
${ }_{1}$ Let $S=\{f\}$;
2 foreach $1 \leq i \leq r$ do
3 Solve $\lambda$ from $\operatorname{Res}_{x}\left(f, h_{i}-\lambda f^{\prime}\right) \equiv 0(\bmod \phi)$, for each $h_{i}$;
4 foreach root $\lambda$ of $h_{i}$ and each $g \in S$ do
$5 \quad$ compute $\operatorname{gcd}\left(g, h_{i}-\lambda f^{\prime}\right)$;
$6 \quad$ Update $S$ by replace g by g 's factors from $\operatorname{gcd}\left(g, h_{i}-\lambda f^{\prime}\right)$;
7 end
8 end
9 Let $f=\prod_{i=1}^{r} s_{i}$, for all $s_{i} \in S$;
10 Suppose $\operatorname{deg}_{x} \phi^{m}>d_{x}+1$;
11 Lift the factorization $f \equiv \prod_{s_{i} \in S} s_{i}$, to degree of $\phi^{m}$;

### 2.6 An example

We consider the following polynomials

$$
f=x^{p}-x+y^{p-1} \in \mathbb{F}_{p}[x, y]
$$

with total degree $d=p$. This polynomial, also can be written as $y^{p-1}-x(x-1) \cdots(x-$ $p+1)$, is irreducible, but splits completely $\bmod y$.

Our example below shows that we only need to lift up to $y^{d+1}$ to get the right linear space.

Let $p=5$.

$$
f=x^{5}-x+y^{4} \in \mathbb{F}_{p}[x, y] .
$$

The solutions basis $\bmod y^{m}, 1 \leq m \leq 6$, are as follows:

| $\bmod y$ | $\bmod y^{2}$ | $\bmod y^{3}$ | $\bmod y^{4}$ | $\bmod y^{5}$ | $\bmod y^{6}$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $-x$ | $-x$ | $-x$ | $-x$ | $y^{4}-x$ | $y^{4}-x$ |
| $2 x^{2}$ | $2 x^{2}$ | $2 x^{2}$ | $2 x^{2}$ | $y^{4} x+2 x^{2}$ | $y^{4} x+2 x^{2}$ |
| $3 x^{3}$ | $3 x^{3}$ | $3 x^{3}$ | $3 x^{3}$ | $y^{4} x^{2}+3 x^{3}$ | $y^{4} x^{2}+3 x^{3}$ |
| $x^{4}$ | $x^{4}$ | $x^{4}$ | $x^{4}$ | $y^{4} x^{3}+x^{4}$ | $y^{4} x^{3}+x^{4}$ |
| 1 | 1 | 1 | 1 | 1 | 1 |

The last row indicates that $h=1$ is a true solution, and we can get rid of $\left\{y^{4} x+2 x^{2}, y^{4} x^{2}+3 x^{3}, y^{4} x^{3}-\right.$ because their total degree is bigger than that of $f$. Next we check with maps $D$ and $\mathcal{B}_{f}$. Consider the basis $\bmod y^{6}, H_{5}=\left\{y^{4}-x, y^{4} x+2 x^{2}, y^{4} x^{2}+3 x^{3}, y^{4} x^{3}+x^{4}, 1\right\}$.

$$
\begin{array}{ll}
h_{51}=y^{4}-x & \Rightarrow D\left(h_{51}\right)=0, \\
h_{52}=y^{4} x+2 x^{2} & \Rightarrow D\left(h_{52}\right)=-y^{7}, \\
h_{53}=y^{4} x^{2}+3 x^{3} & \Rightarrow D\left(h_{53}\right)=-2 x y^{7}, \\
h_{54}=y^{4} x^{3}+x^{4} & \Rightarrow D\left(h_{54}\right)=-3 x^{2} y^{7}, \\
h_{55}=1 & \Rightarrow D\left(h_{55}\right)=0,
\end{array}
$$

So the new basis is $\left\{y^{4}-x, 1\right\} \cdot \mathcal{B}\left(y^{4}-x\right)=\left(y^{4}-x\right)^{5}-\left(y^{4}-x\right)=y^{40}=y^{4.5} \neq 0$. So 1 is the only factor, hence $f$ is irreducible.

### 2.7 Appendix: Computing coefficient matrix

The Niederreiter equation (1.5) is equivalent with

$$
H^{(q-1)}\left(f^{q-1} h\right)=h^{q} .
$$

Since

$$
H^{(q-1)}\left(x^{i}\right)=\left\{\begin{array}{cl}
x^{i-q+1} & \text { if } i \equiv q-1 \quad(\bmod q) \\
0 & \text { otherwise }
\end{array}\right.
$$

(1.5) and (1.6) turn out to be the same linear system over $\mathbb{F}_{q}$, so they are equivalent.

To write the equation (1.6) into a matrix form, suppose

$$
h=\sum_{i=0}^{n-1} a_{i} x^{i}, \quad f^{q-1}=\sum_{j=0}^{(q-1) n} b_{j} x^{j}
$$

where $a_{i}, b_{j} \in \mathbb{F}_{q}[y]$. Then for $0 \leq k \leq n-1$, since $h^{[q]}=\sum_{i=0}^{n-1} a_{i}^{q} x^{i}$, we have
$\psi_{q}\left(f^{q-1} x h\right)=\psi_{q}\left(\sum_{i=0}^{n(q-1)} b_{i} x^{i} \cdot x \cdot \sum_{k=0}^{n-1} a_{k} x^{k}\right)=\sum_{l=0}^{n-1} \psi_{q}\left(\sum_{i=0}^{n-1} b_{l q+q-1-i} x^{l q+q-1-i} \cdot x \cdot a_{i} x^{i}\right)$.

Since

$$
\begin{gathered}
\psi_{q}\left(f^{q-1} x h\right)=x h(x), \\
\psi_{q}\left(\sum_{i=0}^{n-1} b_{l q+q-1-i} x^{l q+q-1-i} \cdot x \cdot a_{i} x^{i}\right)=\sum_{i=0}^{n-1} b_{l q+q-1-i} \cdot a_{i} \cdot x^{l+1}=x \cdot a_{l}^{q} x^{l},
\end{gathered}
$$

which we can write as:

$$
\sum_{i=0}^{n-1} b_{l q+q-1-i} \cdot a_{i}=a_{l}^{q}, \quad 0 \leq l \leq n-1
$$

$$
\left(\begin{array}{cccc}
b_{q-1} & b_{q-2} & \cdots & b_{q-n}  \tag{2.12}\\
b_{2 q-1} & b_{2 q-2} & \cdots & b_{2 q-n} \\
\vdots & \vdots & \vdots & \vdots \\
b_{(n-1) q-1} & b_{(n-1) q-2} & \cdots & b_{(n-1) q-n} \\
b_{n q-1} & b_{n q-2} & \cdots & b_{n q-n}
\end{array}\right)\left(\begin{array}{c}
a_{0} \\
a_{1} \\
\vdots \\
a_{n-2} \\
a_{n-1}
\end{array}\right)=\left(\begin{array}{c}
a_{0}^{q} \\
a_{1}^{q} \\
\vdots \\
a_{n-2}^{q} \\
a_{n-1}^{q}
\end{array}\right)
$$

We will show how to solve this system in the implementation section.
Note that, for any $g \in \mathbb{K}[x]$, we have $\left(g / f^{p}\right)^{\prime}=g^{\prime} / f^{p}$. By induction, it follows that

$$
\begin{equation*}
\left(\frac{h}{f}\right)^{(p-1)}=\left(\frac{h f^{p-1}}{f^{p}}\right)^{(p-1)}=\frac{\left(h f^{p-1}\right)^{(p-1)}}{f^{p}} \tag{2.13}
\end{equation*}
$$

Then the equation (1.5) is equivalent to

$$
\begin{equation*}
\left(h f^{p-1}\right)^{(p-1)}+h^{p}=0 . \tag{2.14}
\end{equation*}
$$

To write the equation (2.14) into a matrix form, suppose

$$
h=\sum_{i=0}^{n-1} a_{i} x^{i}, \quad f^{p-1}=\sum_{j=0}^{(p-1) n} b_{j} x^{j},
$$

where $a_{i}, b_{j} \in \mathbb{F}$. Then

$$
g=h f^{p-1}=\sum_{k=0}^{m} c_{k} x^{k} \in \mathbb{F}[x]
$$

where

$$
c_{k}=\sum_{i+j=k} a_{i} b_{j}
$$

For any $k$,

$$
\left(x^{k}\right)^{(p-1)}=k(k-1) \cdots(k-(p-1)+1) x^{k-(p-1)} .
$$

If $k \not \equiv-1(\bmod p)$, then $\left(x^{k}\right)^{(p-1)}=0$ in $\mathbb{F}[x]$. Otherwise when $k \equiv-1(\bmod p)$,

$$
\left(x^{k}\right)^{(p-1)}=-x^{k-(p-1)}=-x^{d p}, \text { where } d=(k-(p-1)) / p
$$

So

$$
g^{(p-1)}=\left(\sum_{k=0}^{m} c_{k} x^{k}\right)^{(p-1)}=\sum_{\ell=0}^{\left\lfloor\frac{m-(p-1)}{p}\right\rfloor}-c_{\ell p+p-1} x^{\ell p}
$$

Therefore the equation (2.14) is equivalent to the following system of equations:

$$
c_{k p+p-1}=a_{k}^{p}, \quad 0 \leq k \leq n-1
$$

namely,

$$
\sum_{i=0}^{n-1} a_{i} b_{k p+p-1-i}=a_{k}^{p}, \quad 0 \leq k \leq n-1
$$

where $b_{i}=0$, if $i>n(p-1)$, or $i<0$. Then the above equation can be written as :

$$
\left(\begin{array}{cccc}
b_{q-1} & b_{q-2} & \cdots & b_{q-n} \\
b_{2 q-1} & b_{2 q-2} & \cdots & b_{2 q-n} \\
\vdots & \vdots & \vdots & \vdots \\
b_{(n-1) q-1} & b_{(n-1) q-2} & \cdots & b_{(n-1) q-n} \\
b_{n q-1} & b_{n q-2} & \cdots & b_{n q-n}
\end{array}\right)\left(\begin{array}{c}
a_{n-1} \\
a_{n-2} \\
\vdots \\
a_{1} \\
a_{0}
\end{array}\right)=\left(\begin{array}{c}
a_{0}^{p} \\
a_{1}^{p} \\
\vdots \\
a_{n-2}^{p} \\
a_{n-1}^{p}
\end{array}\right)
$$

For a given $f \in \mathbb{K}[x]$, one can expand $f^{q-1}$ to get the coefficients $b_{i}$ in (2.12). This is fine for small $q$, but too expensive for large $q$. We now show a faster algorithm for computing the required $n^{2}$ coefficients for the matrix without computing all the $n(q-1)+1$ coefficients of $f^{q-1}$.

We first introduce a convolution product of vectors. Let $u=\left(u_{n-1}, u_{n-2}, \cdots, u_{0}\right)$,
$v=\left(v_{0}, v_{1}, \cdots, v_{n-1}\right)$. We define

$$
u * v^{T}=\left(u_{n-1}, u_{n-2}, \cdots, u_{0}\right) *\left(\begin{array}{c}
v_{0}  \tag{*}\\
v_{1} \\
\vdots \\
v_{n-1}
\end{array}\right)=\left(\begin{array}{c}
c_{0} \\
c_{1} \\
\vdots \\
c_{n-1}
\end{array}\right)=c^{T}
$$

where

$$
c_{i}=u_{i} v_{0}+u_{i-1} v_{1}+\cdots+u_{0} v_{i} . \quad 0 \leq i \leq n-1 .
$$

Equivalently, if we denote $u(x)=\sum_{i=0}^{n-1} u_{i} x^{i}, v(x)=\sum_{j=0}^{n-1} v_{j} x^{j}$, and $c(x)=\sum_{i=0}^{\infty} c_{i} x^{i}$, then $(*)$ is equivalent to

$$
c(x) \equiv u(x) v(x) \quad\left(\bmod x^{n}\right)
$$

This means that the convolution $u * v^{T}$ is equivalent to one polynomial multiplication.

## Suppose $f=f_{0}+f_{1} x+\cdots+f_{n} x^{n} \in \mathbb{F}[x]$. We compute the $b_{i}^{\prime}$ s by using the inverse

 of $f$. Suppose$$
\frac{1}{f}=\sum_{i=0}^{\infty} w_{i} \cdot x^{i}, \quad w_{i} \in \mathbb{K}
$$

We assume $w_{i}=0$, if $i<0$. Then

$$
f^{q-1}=f^{q} \cdot \frac{1}{f}=\left(\sum_{i=0}^{n} f_{i}^{q} x^{i q}\right)\left(\sum_{i=0}^{\infty} w_{i} \cdot x^{i}\right)=\sum_{i=0}^{n(q-1)}\left(\sum_{t=0}^{\left\lfloor\frac{i}{q}\right\rfloor} f_{t}^{q} \cdot w_{i-t q}\right) \cdot x^{i} .
$$

So, the coefficient $b_{k q-j}$ of $x^{k q-j}$ in $f^{q-1}$ can be written as:

$$
b_{k q-j}=w_{k q-j} \cdot f_{0}^{q}+w_{(k-1) q-j} \cdot f_{1}^{q}+\cdots+w_{q-j} \cdot f_{k-1}^{q}, \quad 1 \leq k \leq n, \quad 1 \leq j \leq n
$$

that is,

$$
\left(\begin{array}{c}
b_{q-j} \\
b_{2 q-j} \\
\vdots \\
b_{n q-j}
\end{array}\right)=\left(f_{n-1}^{q}, f_{n-2}^{q}, \cdots, f_{0}^{q}\right) *\left(\begin{array}{c}
w_{q-j} \\
w_{2 q-j} \\
\vdots \\
w_{n q-j}
\end{array}\right) .
$$

Denote $V\left(f^{q}\right)$ by $\left(f_{n-1}^{q}, f_{n-2}^{q}, \cdots, f_{0}^{q}\right)$, and

$$
B=\left(\begin{array}{cccc}
b_{q-1} & b_{q-2} & \cdots & b_{q-n} \\
b_{2 q-1} & b_{2 q-2} & \cdots & b_{2 q-n} \\
\vdots & \vdots & \vdots & \vdots \\
b_{(n-1) q-1} & b_{(n-1) q-2} & \cdots & b_{(n-1) q-n} \\
b_{n q-1} & b_{n q-2} & \cdots & b_{n q-n}
\end{array}\right)
$$

and let

$$
W=\left(\begin{array}{cccc}
w_{q-1} & w_{q-2} & \cdots & w_{q-n} \\
w_{2 q-1} & w_{2 q-2} & \cdots & w_{2 q-n} \\
\vdots & \vdots & \vdots & \vdots \\
w_{(n-1) q-1} & w_{(n-1) q-2} & \cdots & w_{(n-1) q-n} \\
w_{n q-1} & w_{n q-2} & \cdots & w_{n q-n}
\end{array}\right)
$$

Then

$$
\begin{equation*}
B=V\left(f^{q}\right) * W \tag{2.15}
\end{equation*}
$$

We next show how to compute the matrix

$$
W^{\star}=\left(\begin{array}{cccc}
w_{q-n} & w_{q-n+1} & \cdots & w_{q-1} \\
w_{2 q-n} & w_{2 q-n+1} & \cdots & w_{2 q-1} \\
\vdots & \vdots & \ddots & \vdots \\
w_{n q-n} & w_{n q-n+1} & \cdots & w_{n q-1}
\end{array}\right) .
$$

Since $\frac{1}{f}=\sum_{i=0}^{\infty} w_{i} \cdot x^{i}, f \cdot \sum_{i=0}^{\infty} w_{i} \cdot x^{i}=1$. We can set $f_{0}=1$. The coefficient of $x^{k}$ of $1,(k>0)$, is zero, so

$$
\sum_{i=0}^{\min (n, k)} w_{k-i} f_{i}=0
$$

equivalently

$$
w_{k}=-\sum_{i=\max (0, k-n)}^{k-1} w_{i} f_{k-i} .
$$

When $k \geq n$,

$$
\begin{equation*}
w_{k}=-\sum_{i=k-n}^{k-1} w_{i} f_{k-i} \tag{2.16}
\end{equation*}
$$

For $k \geq 0$, let $W_{k}=\left(w_{k}, w_{k+1}, \cdots, w_{k+n-1}\right)$. and let

$$
M=\left(\begin{array}{cccccc}
0 & 0 & 0 & 0 & \cdots & -f_{n} \\
1 & 0 & 0 & 0 & \cdots & -f_{n-1} \\
0 & 1 & 0 & \cdots & 0 & -f_{n-2} \\
\vdots & \vdots & \ddots & \ddots & \ddots & \vdots \\
0 & 0 & \cdots & 1 & 0 & -f_{2} \\
0 & 0 & 0 & \cdots & 1 & -f_{1}
\end{array}\right)
$$

Then (2.16) gives us a recursion relation:

$$
W_{k+1}=W_{k} \cdot M, \quad k \geq 0
$$

By induction, we see that

$$
W_{k+q}=W_{k} \cdot M^{q}, \quad k \geq 0
$$

It remains to show how to compute $M^{q}$. Let $f^{*}$ be the reciprocal of $f$, i.e. $f^{*}(x)=$ $\sum_{i=0}^{n} f_{n-i} x^{i}$. Define a map $\psi: \mathbb{F}[x] \rightarrow \mathbb{F}^{n}$ as follows. For any $h(x) \in \mathbb{F}[x]$, suppose $h(x) \equiv h_{0}+h_{1} x+\cdots+h_{n-1} x^{n-1}\left(\bmod f^{*}\right)$. Then

$$
\rho(h(x))=\left(h_{0}, h_{1}, \cdots, h_{n-1}\right)^{T} .
$$

## Theorem 2.7.1.

$$
M^{j}=\left(\rho\left(x^{j}\right), \rho\left(x^{j+1}\right), \cdots, \rho\left(x^{j+n-1}\right)\right) .
$$

Proof. For any $h(x) \in \mathbb{F}[x]$ and suppose $\rho(h(x))=\left(h_{0}, h_{1}, \cdots, h_{n-1}\right)^{T}$. We first show that

$$
\rho(h(x) \cdot x)=M \cdot \rho(h(x)) .
$$

Let $X=\left(1, x, \cdots, x^{n-1}\right)$. Note that

$$
\begin{aligned}
h(x) \cdot x & =\sum_{i=0}^{n-1} h_{i} \cdot x^{i+1} \\
& \equiv \sum_{i=0}^{n-2} h_{i} \cdot x^{i+1}-h_{n-1} \cdot \sum_{i=0}^{n-1} f_{n-i} x^{i} \quad\left(\bmod f^{*}(x)\right) \\
& \equiv\left[\left(0, h_{0}, \cdots, h_{n-3}, h_{n-2}\right)-h_{n-1}\left(f_{n}, f_{n-1}, \cdots, f_{1}\right)\right] \cdot X^{T} \\
& \equiv X \cdot M \cdot h \quad\left(\bmod f^{*}(x)\right) .
\end{aligned}
$$

That is, for any $h \in \mathbb{F}[x]$,

$$
\rho(h(x) \cdot x)=M \cdot h=M \cdot \rho(h(x)) .
$$

By induction,

$$
\begin{equation*}
\rho\left(h(x) \cdot x^{j}\right)=M^{j} \rho(h(x)), \quad \forall j \geq 1 . \tag{2.17}
\end{equation*}
$$

Particularly, for $h(x)=x^{i}, 0 \leq i \leq n-1$, then $\rho(h(x))=(0, \cdots, 0,1,0, \cdots)$.

$$
\rho\left(x^{i+j}\right)=M^{j} \cdot \rho\left(x^{i}\right)=M^{j} \cdot(0,0, \cdots, 1,0, \cdots)^{T},
$$

which means $\rho\left(x^{i+j}\right)$ is the $(i+j+1)$ st row of $M^{j}, 0 \leq i+j \leq n-1$.

Remark: Let $j=q$, then

$$
M^{q}=\left(\rho\left(x^{q}\right), \rho\left(x^{q+1}\right), \cdots, \rho\left(x^{q+n-1}\right)\right) .
$$

Consider the matrix $W^{*}$. First compute the first row of $W^{*}$,

$$
\left(w_{q-n}, w_{q-n+1}, \cdots, w_{q-1}\right)
$$

by the equation

$$
\left(w_{q-n}, w_{q-n+1}, \cdots, w_{q-1}\right)=\left(w_{0}, w_{1}, \cdots, w_{n-1}\right) M^{q-n}
$$

Each row of $W$ can be obtained by multiplying the previous row in $W$ by $M^{q}$. The complexity for computing $x^{q}\left(\bmod f^{*}\right)$ is $\tilde{O}(n \log q)$, for $x^{i} \cdot x^{q}\left(\bmod f^{*}\right)$ is $O\left(n^{2}\right)$. So the complexity for $M^{q}$ is $\tilde{O}\left(n \log q+n^{2}\right)$.

After $W^{*}$ is obtained, we can compute $B$ by (2.15) in polynomial time.

## Chapter 3

## Deterministic factoring via Gröbner bases

### 3.1 Introduction

In this chapter, we concentrate on the deterministic complexity of factoring univariate polynomials over finite fields with help of Gröbner bases and combinatorics. In Chapter 1, we have defined fibre size which measures the geometric structure of point sets, and we described the structure theorem of Gröbner bases. This gives us a deterministic algorithm to decompose ideals when fibre sizes are not constant. In the following sections, we use Gröbner basis structure theorem to design deterministic algorithms for factoring univariate polynomials.

The chapter is organized as follows. In Section 3.2, we show how to compute Göbner bases of certain ideals in deterministic polynomial time. More precisely, suppose we are given a Göbner basis of a zero-dimensional ideal $I$ in $\mathbb{F}_{q}\left[x_{1}, x_{2}, \cdots, x_{m}\right]$. For any polynomial $h$, we show that there is a deterministic polynomial time algorithm for computing Göbner bases for $\langle I, h\rangle$ and $(I: h)$ in deterministic polynomial time. We will use this algorithm to compute Göbner bases for all the ideals rising in our method. This result is interesting as it might be useful for general Göbner basis computation.

In Section 3.3, we describe an algorithm to compute $r$-th roots of elements in extension rings of $\mathbb{F}_{q}$, provided we are given an $r$-th nonresidue $\eta$ in $\mathbb{F}_{q}$ which can be found in deterministic polynomial time under ERH.

In Section 3.4, we use this deterministic algorithm for computing square roots to introduce a tool called square selector and show how it splits ideals.

In Section 3.5, we describe how to use square selectors to decompose various ideals. More precisely, let $f \in \mathbb{F}_{p}[x]$ be a squarefree polynomial of degree $n$ with all roots lying in $\mathbb{F}_{p}$. Let $S \subset \mathbb{F}_{p}$ be the set of roots of $f$. Define

$$
S^{[m]}=\left\{\left(a_{1}, \cdots, a_{m}\right): a_{i} \in S, a_{i} \neq a_{j}, \text { if } i \neq j\right\}
$$

We asocciate a tournament graph to each point in $S^{[m]}$ and partition $S^{m}$ according tournament graphs. We study the symmetry of this partition and show how it is related to combinatorial designs and the factorization of $f$. In particular, when $m=2$, we can decompose $f$ if $S$ is not square balanced, and for when $m=3$, we show how a connection with Hadamard designs. As a consequence, we obtain a bound on the number of extensions needed to get a proper factor of $f$, thus improve a previous result of Ivanyos, karpinski and Saxena (2008).

### 3.2 Computing Gröbner bases

Let $I$ be a 0 -dimensional radical ideal in $R=\mathbb{F}\left[x_{1}, \cdots, x_{m}\right]$. Suppose we know a Gröbner basis for $I$ with respect to some term order. If we join a polynomial $h \in R$ to $I$, then the Gröbner basis of the new ideal $\langle I, h\rangle$ may be dramatically different. Is it possible to take advantage of this extra information (i.e. the Gröbner basis of $I$ ) to get a polynomial
time algorithm for the new ideal? Also, how to compute a Gröbner basis for the colon ideal

$$
(I: h)=\{g \in R: g h \in I\} .
$$

We show below that the Gröbner bases for both ideals can indeed be computed efficiently. More precisely, we prove the following theorem and the desired algorithms will be clear from the proof.

Theorem 3.2.1. Let $I \subset R=\mathbb{F}\left[x_{1}, \cdots, x_{m}\right]$ be a 0 -dimensional ideal with a Gröbner basis $G=\left\{g_{1}, g_{2}, \cdots, g_{t}\right\}$ under some term order. For any $h \in R$, we have
(1). $\operatorname{dim}_{\mathbb{F}} R / I=\operatorname{dim}_{\mathbb{F}} R /\langle I, h\rangle+\operatorname{dim}_{\mathbb{F}} R /(I: h) ;$ and
(2). if $h$ is given reduced modulo $G$, then Gröbner bases for $\langle I, h\rangle$ and $(I: h)$ can be computed deterministically in time polynomial in $m N$ where $N=\operatorname{dim}_{\mathbb{F}} R / I$ is the degree of $I$.

Proof. Since we know a Gröbner basis for $I$, we can find the standard monomial basis for $R / I$ :

$$
B(I)=\left\{X^{\alpha_{1}}, X^{\alpha_{2}}, \cdots, X^{\alpha_{N}}=1\right\}
$$

where we assume the monomials are in decreasing order (under the given term order). Then $B(I)$ is a linear basis for $R / I$ over $\mathbb{F}$. Suppose

$$
\begin{equation*}
h \cdot X^{\alpha_{i}} \equiv \sum_{j=1}^{N} a_{i j} X^{\alpha_{j}} \quad(\bmod G) \tag{3.1}
\end{equation*}
$$

where $a_{i j} \in \mathbb{F}$, that is,

$$
h \cdot\left(\begin{array}{c}
X^{\alpha_{1}} \\
X^{\alpha_{2}} \\
\cdots \\
X^{\alpha_{N}}
\end{array}\right) \equiv A\left(\begin{array}{c}
X^{\alpha_{1}} \\
X^{\alpha_{2}} \\
\cdots \\
X^{\alpha_{N}}
\end{array}\right)(\bmod G)
$$

where $A=\left(a_{i j}\right)_{N \times N}$ over $\mathbb{F}$. It is important to note that, in the congruence equations above and below as well, when we say " $a \equiv b(\bmod G)$ " we mean $a$ can be reduced to $b$ by long division under the given term order. We know from Gröbner basis theory that $G$ is a Gröbner basis for $I$ iff every polynomial in $I$ can be reduced to 0 by $G$.

Apply Gauss elimination to rows of $A$ with elimination in order starting from the last column to the first column. Then we get an $N \times N$ matrix $M$ such that $M A$ is of the following row echelon form

$$
M A=\left(\begin{array}{cccccc}
0 & u_{1 n_{1}} & * & * & \cdots & u_{1 N} \\
0 & 0 & u_{2 n_{2}} & * & \cdots & u_{2 N} \\
\vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\
0 & 0 & 0 & u_{\ell n_{\ell}} & \cdots & u_{\ell N} \\
0 & 0 & 0 & 0 & \cdots & 0 \\
\vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\
0 & 0 & 0 & 0 & \cdots & 0
\end{array}\right),
$$

where $\ell$ is the rank of $A$ and $1 \leq n_{1}<n_{2}<\cdots<n_{\ell} \leq N$. Let $M_{1}$ be the first $\ell$ rows of
$M$ and let

$$
M_{1}\left(\begin{array}{c}
h_{1} \\
h_{2} \\
\ldots \\
h_{N}
\end{array}\right)=M_{1} A\left(\begin{array}{c}
X^{\alpha_{1}} \\
X^{\alpha_{2}} \\
\ldots \\
X^{\alpha_{N}}
\end{array}\right)=\left(\begin{array}{c}
u_{1}(x) \\
u_{2}(x) \\
\ldots \\
u_{\ell}(x)
\end{array}\right)
$$

where $u_{i}(x)=\sum_{j=n_{i}}^{N} u_{i j} X^{\alpha_{j}}$. We claim that

$$
G_{1}=G \cup\left\{u_{1}(x), \cdots, u_{\ell}(x)\right\}
$$

form a Gröbner basis for $\langle I, h\rangle$ and $\operatorname{dim}_{\mathbb{F}}\left(R /\left\langle G_{1}\right\rangle\right)=N-\ell$. In fact, for any $g \in\langle I, h\rangle$, we have

$$
g=g_{0}+g_{1} h, \quad \text { for some } g_{0} \in I, g_{1} \in \mathbb{F}\left[x_{1}, \cdots, x_{m}\right] .
$$

By using $G$ to reduce $g$, we may assume that

$$
g \equiv V \cdot h \quad(\bmod G)
$$

where $V=\sum_{i=1}^{N} v_{i} X^{\alpha_{i}}$ for some $v_{i} \in \mathbb{F}$. Then

$$
\begin{aligned}
g & \equiv\left(v_{1}, v_{2}, \cdots, v_{N}\right) h\left(X^{\alpha_{1}}, \cdots, X^{\alpha_{N}}\right)^{T} \quad(\bmod G) \\
& \equiv\left(v_{1}, v_{2}, \cdots, v_{N}\right) A\left(X^{\alpha_{1}}, \cdots, X^{\alpha_{N}}\right)^{T} \\
& \equiv\left(v_{1}, v_{2}, \cdots, v_{N}\right) M^{-1} \cdot M A\left(X^{\alpha_{1}}, \cdots, X^{\alpha_{N}}\right)^{T} \\
& \equiv\left(v_{1}, v_{2}, \cdots, v_{N}\right) M^{-1} \cdot\left(u_{1}, \cdots, u_{\ell}, 0, \cdots, 0\right)^{T}
\end{aligned}
$$

Let $\left(v_{1}, v_{2}, \cdots, v_{N}\right) M^{-1}=\left(c_{1}, c_{2}, \cdots, c_{\ell}, \cdots, c_{N}\right) \in \mathbb{F}^{N}$. Then

$$
\begin{equation*}
g \equiv \sum_{i=1}^{\ell} c_{i} u_{i}(x) \quad(\bmod G) \tag{3.2}
\end{equation*}
$$

This shows that every $g \in\langle I, h\rangle$ can be reduced to zero by $G_{1}$. Therefore $G_{1}$ is a Gröbner basis for $\langle I, h\rangle$.

Next we prove that $\operatorname{dim}_{\mathbb{F}}(R /\langle I, h\rangle)=N-\ell$. Since $G_{1}$ is a Gröbner basis for $\langle I, h\rangle$, we have

$$
\operatorname{dim}_{\mathbb{F}}(R /\langle I, h\rangle)=\# B\left(G_{1}\right)
$$

where $B\left(G_{1}\right)$ denotes the set of monomials not divisible by any leading term of polynomials in $G_{1}$. Note that the leading term of $u_{i}$ is $X^{\alpha_{n_{i}}}$, which belongs to $B(I)=$ $\left\{X^{\alpha_{1}}, \cdots, X^{\alpha_{N}}\right\}$. It suffices to prove that, for each $j \in\{1,2, \cdots, N\} \backslash\left\{n_{1}, \cdots, n_{\ell}\right\}$, the term $X^{\alpha_{j}}$ is not the leading term of any polynomial $g \in\langle I, h\rangle$. Suppose otherwise, that is, there is a polynomial $g \in\langle I, h\rangle$ with $\operatorname{lt}(g)=X^{\alpha_{j}}$. By reducing $g$ modulo $G$, we may assume that $g$ is linear combination of terms in $B(I)$. However, by (3.2), $g$ should be a linear combination of $u_{1}, \ldots, u_{\ell}$. This is impossible, as the leading term of $g$ is different from those of $u_{i}$ 's and the $u_{i}$ 's are in echelon form.

It remains to show how to get a Gröbner basis for $(I: h)$. Let $M_{2}$ be the last $t=N-\ell$ rows of $M$ and let

$$
M_{2}\left(\begin{array}{c}
X^{\alpha_{1}} \\
\ldots \\
X^{\alpha_{N}}
\end{array}\right)=\left(\begin{array}{c}
w_{1}(x) \\
\ldots \\
w_{t}(x)
\end{array}\right)
$$

We claim that

$$
G_{2}=G \cup\left\{w_{1}(x), \cdots, w_{t}(x)\right\}
$$

generates $(I: h)$. In fact, we know from the row echelon from of $M A$ that $M_{2} A=0_{\ell \times N}$.

Hence

$$
h\left(\begin{array}{c}
w_{1}(x) \\
\ldots \\
w_{t}(x)
\end{array}\right) \equiv M_{2} h\left(\begin{array}{c}
X^{\alpha_{1}} \\
\ldots \\
X^{\alpha_{N}}
\end{array}\right) \equiv M_{2} A\left(\begin{array}{c}
X^{\alpha_{1}} \\
\ldots \\
X^{\alpha_{N}}
\end{array}\right)=0 \quad(\bmod G)
$$

We see that $G_{2} \subset(I: h)$. To show $G_{2}$ is a generating set for $(I: h)$, we only need to show that, for any $g \in R$ such that $g h \in I$, we have $g \in\left\langle G_{2}\right\rangle$. Suppose

$$
g \equiv g_{1} X^{\alpha_{1}}+g_{2} X^{\alpha_{2}}+\cdots+g_{N} X^{\alpha_{N}} \quad(\bmod G) .
$$

Let $\left(b_{1}, \cdots, b_{N}\right)=\left(g_{1}, \cdots, g_{N}\right) M^{-1}$. Then
$g h \equiv\left(b_{1}, \cdots, b_{N}\right) M X^{\alpha} h \equiv\left(b_{1}, \cdots, b_{N}\right) M A X^{\alpha}=\left(b_{1}, \cdots, b_{N}\right)\left(u_{1}, \cdots, u_{\ell}, 0_{1 \times t}\right)^{T} \quad(\bmod G)$.

Since $g h \in I$, we have $g h \equiv 0(\bmod G)$, that is, $\sum_{i=1}^{\ell} b_{i} u_{i} \equiv 0(\bmod G)$. As $u_{1}, \cdots$, $u_{\ell}$ are linearly independent $\bmod G$, we see that $b_{1}=\cdots=b_{\ell}=0$. Hence

$$
\begin{aligned}
g & \equiv\left(g_{1}, \cdots, g_{N}\right) X^{\alpha} \\
& \equiv\left(b_{1}, \cdots, b_{N}\right) M X^{\alpha} \\
& \equiv\left(b_{\ell+1}, \cdots, b_{N}\right) M_{2} X^{\alpha} \\
& \equiv \sum_{i=1}^{t} b_{\ell+i} w_{i}(x) \quad(\bmod G) .
\end{aligned}
$$

Therefore, each $g \in(I: h)$ is congruent to a linear combination of $w_{i}(x)$ 's modulo $G$. We can use row operations to reduce $M_{2}$ to a row echelon form $M_{2}^{*}$ such that $M_{2}^{*} X^{\alpha}$ has $m$ distinct leading terms in $B(I)$. So $\left\{G, M_{2}^{*} X^{\alpha}\right\}$ is a Gröbner basis for $(I: h)$. Also, we have $\operatorname{dim}_{\mathbb{F}} R /(I: h)=\ell$, since it is impossible that a polynomial $g \in(I: h)$ is linear combination of $M_{2}^{*} X^{\alpha}$ and at the same time have leading term different from those of $M_{2}^{*} X^{\alpha}$.

Finally, note that the matrix $A=\left(a_{i j}\right)$ in (3.1) can be computed deterministically in time polynomial in $m$ and $N$, using border basis. As Gauss eliminations can done in polynomial time in $N$, (2) follows.

### 3.3 Computing $\eta$-square roots

In this section, we introduce an algorithm in [Gao 2001] how to compute an $r$-th root of an arbitrary element, say $A$, in $R$ for any prime $r$. If $r$ is coprime to $q-1$ then $A^{s}$ is an $r$-th root of $A$ where $s r \equiv 1(\bmod q-1)$. So it is suffices to show that $r$ is prime and can divide $q-1$. Suppose $q-1=r^{e} w$ where $r \nmid w$. Let $\eta$ be a given $r^{e}$-th root of unity in $\mathbb{F}_{q}$. And under GRH, we can compute $\eta$ in polynomial time, see in [wang 1959] and [Bach 1997]. Note that $r$-th root of $A$ exists only if $A=0$ or $A^{\frac{(q-1)}{r}}=1$. We write $A=\eta^{u} B$ for some $u \leq r^{e}$ and $B \in \mathbb{F}_{q}$. Suppose $B^{w}=1$. Then $A^{1 / r}$ exists iff $r \mid u$.

We want to find an $r$-th root of $A$. If $A$ is not invertible in $R$, we can decompose $R$ to be two parts, one of them is $R_{A}=\{C A: C \in R\}$. Let $I$ be the identity element of $R_{1}$, then $A \dot{I}$ is invertible in $R_{1}$. An $r$-th root of $A \dot{I}$ in $R_{1}$ is an $r$-th root of $A$ in $R$. Thus we can assume that $A$ is invertible in $R$.

Find $t$ and $s$ such that $s r^{e}+t w=1$. Then

$$
A=A^{t w} A^{s r^{e}}
$$

We only need to find an $r$-th root of $A^{t w}$. Denote $A^{t w}=A_{1}$. Since $A_{1}^{r e}=1$, we can use Pohlig and Hellman's algorithm to find $k, u$ such that

$$
A_{1}^{r^{k}}=\eta^{u} .
$$

If $k=0$, then $\eta^{u / r}$ is an $r$-th root of $A_{1}$. Otherwise, we can find a zero divisor of R and decompose $R$ as follows. Since $A_{1}^{r k-1} \eta^{-u / r} \notin \mathbb{F}_{q}$ but $\left(A_{1}^{r^{k-1}} \eta^{-u / r}\right)^{r}=1, A_{1}^{r^{k-1}} \eta^{-u / r}$ is an $r$-th root of unity. So there are $r+1$ distinct $r$-th roots of unity in $R$, i.e. $1, \zeta, \cdots, \zeta^{r-1}$, where $\zeta=\eta^{r^{e-1}}$. So there exists some $1 \leq i \leq r$ such that $A_{1}^{r^{k-1}} \eta^{-u / r}-\zeta^{i}$ is a zero divisor in $R$. We find this $i$ by checking. Let $D=A_{1}^{r^{k-1}} \eta^{-u / r}-\zeta^{i}$, and R can be decomposed to the direct sum of two subrings

$$
R_{1}=R D=\{D C: C \in R\}, R_{2}=\{C \in R: D C=0\} .
$$

Then $A_{1}=A_{11}+A_{12}$, where $A_{11} \in R_{1}$ and $A_{12} \in R_{2}$. And proceed recursively in $R_{1}$ and $R_{2}$ to compute $r$-th roots of $A_{11}$ and $A_{12}$. The whole process can be done in time polynomial in $r$, nand $\log q$.

We denote this algorithm as $\sigma_{r}$. Then $\sigma_{r}$ has properties as belows.

Proposition 3.3.1 (Gao 2001). Given a primitive $r^{l}$-th root $\eta$ of unity in $\mathbb{F}_{q}$ where $q-1=$ $r^{l} Q, l \geq 1$ and $\operatorname{gcd}(r, Q)=1$, the algorithm $\sigma_{r}$ runs in polynomial time in $r, \log q$ and $n=\operatorname{dim}$ R. Furthermore, $\sigma_{r}$ has the following properties:
(a) $\sigma_{r}(a A)=\sigma_{r}(a) A$, if $A \in R$ is idempotent, i.e. $A^{2}=A$.
(b) $\sigma_{r}(A+B)=\sigma_{r}(A)+\sigma_{r}(B)$, if $A, B \in R$ are orthogonal, i.e. $A B=0$.
(c) Let $\mu_{1}, \cdots, \mu_{n}$ be primitive idempotents in $R$ and $A=\sum_{i=1}^{n} a_{i} \mu_{i}$, where $a_{i} \in \mathbb{F}_{q}$, then

$$
\sigma_{r}(A)=\sum_{i=1}^{n} \sigma_{r}\left(a_{i}\right) \mu_{i} .
$$

(d) Let $a=\eta^{c} \theta$ where $\theta \in \mathbb{F}_{q}$ with $\theta^{Q}=1$ and $1 \leq c<r^{l}$. Then $\sigma_{r}\left(a^{r}\right)=a$ iff $c<r^{l-1}$.

An element $a \in \mathbb{F}_{q}$ is called an $\eta$-square if $\sigma_{2}\left(a^{2}\right)=a$.

Lemma 3.3.2. Let $\eta \in \mathbb{F}_{q}$ of order $2^{l}$ where $2^{l}$ is the highest power of 2 dividing $q-1$. Then, for any $a \in \mathbb{F}_{q}$,

$$
\sigma_{2}\left(a^{2}\right)=\left\{\begin{aligned}
a, & \text { if a is a } \eta \text {-square } \\
-a, & \text { otherwise } .
\end{aligned}\right.
$$

Proof. Suppose $a=\eta^{m} a_{1}$, where $a_{1}$ has odd order and $m<2^{l}$ has binary representation as

$$
m=2^{l-1} m_{l-1}+2^{l-2} m_{l-2}+\cdots+2 m_{1}+m_{0}
$$

where $m_{i} \in\{0,1\}, 0 \leq i \leq l-1$. Then

$$
a^{2}=\eta^{2 m} a_{1}^{2}=\eta^{2^{l-1} m_{l-2}+\cdots+2^{2} m_{1}+2 m_{0}} a_{1}^{2},
$$

thus

$$
\sigma_{2}\left(a^{2}\right)=\eta^{2^{l-2} m_{l-2}+\cdots+2 m_{1}+m_{0}} a_{1}= \begin{cases}a, & \text { if } m_{l-1}=0 \\ -a, & \text { if } m_{l-1}=1\end{cases}
$$

where we used the fact that $\eta^{2^{l-1}}=-1$.
Example 3.3.3. In $R=\mathbb{F}_{p}$ where $p \equiv 3(\bmod 4)$, we have $\sigma_{2}(b)=b^{\frac{p+1}{4}}$, if $b \in \mathbb{F}_{p}$ is a square. Here the nonresidue $\eta$ is -1 . One can check that

$$
\sigma_{2}\left(a^{2}\right)=\left\{\begin{aligned}
a, & \text { if a is a square in } \mathbb{F}_{p} \\
-a, & \text { otherwise }
\end{aligned}\right.
$$

Lemma 3.3.4. Let $f=\prod_{i=1}^{n}\left(x-a_{i}\right)$ where $a_{i} \in \mathbb{F}_{p}$ are distinct. Let

$$
\xi_{i}=\frac{f(x)}{\left(x-a_{i}\right) f^{\prime}\left(a_{i}\right)} \in \mathbb{F}_{p}[x], 1 \leq i \leq n .
$$

Let $R_{1}=\mathbb{F}_{p}[x, y] /<f(x), f(y)>$. Then

$$
\sigma\left((x-y)^{2}\right) \equiv \sum_{1 \leq i, j \leq n} \sigma\left(\left(a_{i}-a_{j}\right)^{2}\right) \xi_{i}(x) \xi_{j}(y) \quad(\bmod \langle f(x), f(y)\rangle)
$$

Proof. Note that

$$
\xi_{i}\left(a_{j}\right)= \begin{cases}0, & \text { if } i \neq j \\ 1, & \text { if } i=j\end{cases}
$$

We see that $\xi_{i}$ are primitive idempotents modulo $f(x)$, and

$$
x \equiv a_{1} \xi_{1}+\cdots+a_{n} \xi_{n} \quad(\bmod f(x))
$$

Then $R_{1}$ has a basis consists of $\left\{\xi_{i}(x) \xi_{j}(y): 1 \leq i, j \leq n\right\}$ and

$$
\begin{aligned}
x & \equiv a_{1} \xi_{1}(x)+\cdots+a_{n} \xi_{n}(x)=\sum_{1 \leq i, j \leq n} a_{i} \xi_{i}(x) \xi_{j}(y) \quad(\bmod \langle f(x), f(y)\rangle), \\
y & \equiv a_{1} \xi_{1}(y)+\cdots+a_{n} \xi_{n}(y)=\sum_{1 \leq i, j \leq n} a_{i} \xi_{i}(x) \xi_{j}(y) \quad(\bmod \langle f(x), f(y)\rangle)
\end{aligned}
$$

By using the property of primitive idempotent, we can write in $R_{1}$,

$$
x-y=\sum_{1 \leq i, j \leq n}\left(a_{i}-a_{j}\right) \xi_{i}(x) \xi_{j}(y) .
$$

So

$$
\sigma\left((x-y)^{2}\right)=\sum_{1 \leq i, j \leq n} \sigma\left(\left(a_{i}-a_{j}\right)^{2}\right) \xi_{i}(x) \xi_{j}(y)
$$

The coefficients $\sigma\left(\left(a_{i}-a_{j}\right)^{2}\right)$ are computed implicitly without knowing the basis $\xi_{i}(x), \xi_{j}(y)$.

### 3.4 The square selector

We now introduce a useful tool for splitting ideals. In the following proof, we shall use the following property: For any radical ideal $I$ and any $f, g \in \mathbb{F}_{p}\left[x_{1}, x_{2}, \cdots, x_{m}\right]$, we have

$$
f \equiv g \quad(\bmod I) \operatorname{iff} f(A)=g(A), \forall A \in V(I)
$$

Lemma 3.4.1. Let $I \subseteq \mathbb{F}_{p}\left[x_{1}, x_{2}, \cdots, x_{m}\right]$ be a 0 -dimensional radical ideal with all solutions lying in $\mathbb{F}_{p}^{m}$. Fix any $1 \leq i \neq j \leq m$. Let

$$
\begin{equation*}
h\left(x_{i}, x_{j}\right)=\frac{1}{2}\left(x_{i}+x_{j}+\sigma\left(\left(x_{i}-x_{j}\right)^{2}\right)\right) \in R=\mathbb{F}_{p}\left[x_{1}, x_{2}, \cdots, x_{m}\right] / I, \tag{3.3}
\end{equation*}
$$

where $\sigma$ is the deterministic algorithm described in the previous section for computing square root in $R$, with a given quadratic nonresidue $\eta \in \mathbb{F}_{p}$. Let $J=\left\langle I, x_{i}-h\right\rangle$. Then

$$
V(J)=\left\{\left(a_{1}, \cdots, a_{m}\right) \in V(I) \mid a_{i}-a_{j} \text { is } \eta \text {-square }\right\} .
$$

That is, $V(J)$ is the subset of points $A=\left(a_{1}, \cdots, a_{m}\right) \in V(I)$ such that $a_{i}-a_{j}$ is $\eta$-square $\operatorname{in} \mathbb{F}_{p}$.

Proof. Let $V(I)=\left\{A_{1}, \cdots, A_{t}\right\} \subset \mathbb{F}_{p}^{m}$. There exist polynomials $\xi_{1}, \cdots, \xi_{t} \in \mathbb{F}_{p}\left[x_{1}, \cdots, x_{n}\right]$ such that

$$
\xi_{i}\left(A_{j}\right)= \begin{cases}1, & \text { if } i=j \\ 0, & \text { if } i \neq j\end{cases}
$$

Then $\xi_{i}$ 's are the primitive idempotents in $R$ satisfying the properties:

$$
\xi_{i} \xi_{j}= \begin{cases}\xi_{i}, & \text { if } i=j \\ 0, & \text { if } i \neq j\end{cases}
$$

Let $A_{i}=\left(a_{i 1}, a_{i 2}, \cdots, a_{i m}\right) \in \mathbb{F}_{p}^{m}, 1 \leq i \leq t$. By the condition for two polynomials to be congruent modulo $I$, we have

$$
x_{j} \equiv \sum_{k=1}^{t} a_{k j} \xi_{k} \quad(\bmod I), \quad 1 \leq j \leq m
$$

By Proposition 3.3.1, we have

$$
h\left(x_{i}, x_{j}\right) \equiv \sum_{k=1}^{t} h\left(a_{k i}, a_{k j}\right) \xi_{k} \quad(\bmod I)
$$

So

$$
x_{i}-h\left(x_{i}, x_{j}\right) \equiv \sum_{k=1}^{t}\left(a_{k i}-h\left(a_{k i}, a_{k j}\right)\right) \xi_{k} \quad(\bmod I)
$$

Note that, for any $\eta$-square $c$ in $\mathbb{F}_{p}$, we have $(\sigma(c))^{2}=c$. Hence, for $a, b \mathbb{F}_{p}$,

$$
h(a, b)= \begin{cases}a, & \text { if } a-b \text { is an } \eta \text {-square } \\ b, & \text { if } b-a \text { is an } \eta \text {-square }\end{cases}
$$

It follows that the value of $x_{i}-h\left(x_{i}, x_{j}\right)$ at $A_{k}$ is

$$
\left(x_{i}-h\left(x_{i}, x_{j}\right)\right)\left(A_{k}\right)=a_{k i}-h\left(a_{k i}, a_{k j}\right)= \begin{cases}0, & \text { if } a_{k i}-a_{k j} \text { is an } \eta-\text { square } \\ a_{k i}-a_{k j} \neq 0, & \text { otherwise }\end{cases}
$$

That is, $A_{k} \in V(J)$ iff $a_{k i}-a_{k j}$ is an $\eta$-square.
Corollary 3.4.2. With the same assumption as in Lemma 3.4.1. Let $J_{1}=<I, x_{i}-h>$ and $J_{2}=<I, x_{j}-h>$ Then $I=J_{1} \cap J_{2}$.

The above corollary does not give a proper decomposition of $I$ only when either all $a_{k i}-a_{k j}$ are $\eta$-squares or all $a_{k i}-a_{k j}$ are not $\eta$-squares. We call the polynomial $h\left(x_{i}, x_{j}\right)$ in the equation (3.3) a square selector. Note that such a square selector can be computed
deterministically in time polynomial in the dimension of the ring $R$ over $\mathbb{F}_{p}$ (provided a quadratic nonresidue $\eta \in \mathbb{F}_{p}$ is given). Also, by Theorem 3.2.1, when a Gröbner basis for $I$ is known, Gröbner bases for $J_{1}$ and $J_{2}$ can be computed in deterministic polynomial time.

### 3.5 Geometric structure and factoring

### 3.5.1 Partition and tournament graphs of points

For any point $A=\left(a_{1}, \cdots, a_{m}\right) \in \mathbb{F}_{p}^{m}$, where $a_{i}$ 's are distinct, we associate it with a directed graph $G_{A}$ as follows: The vertex set is $\{1,2, \cdots, m\}$ and, for each $1 \leq i \neq j \leq m$, there is an edge from $i$ to $j$ iff $a_{i}-a_{j}$ is an $\eta$-square. $G_{A}$ is called the squareness graph of $A$. Since $a_{i}-a_{j}$ is an $\eta$-square iff $a_{j}-a_{i}$ is not an $\eta$-square, the squareness graph of a point is a tournament graph, that is, there is exactly one directed edge between each pair $i$ and $j$.

In the following, we represent the squareness graph of a point by a binary string. For $a \in \mathbb{F}_{p}$, define

$$
\delta(a)= \begin{cases}0, & \text { if } a \text { is an } \eta \text {-square } \\ 1, & \text { otherwise }\end{cases}
$$

Then, for any point $A=\left(a_{1}, \cdots, a_{m}\right) \in \mathbb{F}_{p}^{m}$, define

$$
\delta(A)=\left(\delta\left(a_{1}-a_{2}\right) \delta\left(a_{1}-a_{3}\right) \delta\left(a_{2}-a_{3}\right) \cdots \delta\left(a_{1}-a_{m}\right) \delta\left(a_{2}-a_{m}\right) \cdots \delta\left(a_{m-1}-a_{m}\right)\right)
$$

which has length $\ell=\binom{m}{2}$.
Let $f(x)=\prod_{a \in S}(x-a)$ where $S \subset \mathbb{F}_{p}$ is a subset of cardinality $n$. For each $a \in S$, define

$$
B_{a}(S)=\{b \in S: a-b \text { is an } \eta \text {-square and } b \neq a\}
$$

and

$$
\bar{B}_{a}(S)=\{b \in S: a-b \text { is not an } \eta \text {-square }\} .
$$

Example 3.5.1. Let $A=(a, b, c, d)$ satisfy

$$
a \in S, b \in B_{a}, c \in B_{a} \cap B_{b}, d \in B_{a} \cap B_{b} \cap B_{c} .
$$

Then its squareness graph is depicted as Figure 3.1


Figure 3.1: $\delta(A)=(000000)$

Example 3.5.2. Let $A=(a, b, c, d)$ satisfy

$$
a \in S, b \in B_{a}, c \in \bar{B}_{a} \cap B_{b}, d \in B_{a} \cap B_{b} \cap \bar{B}_{c} .
$$

Then its squareness graph is depicted as Figure 3.2


Figure 3.2: $\delta(A)=(010001)$

Define

$$
S^{[m]}=\left\{\left(a_{1}, \cdots, a_{m}\right): a_{i} \in S, a_{i} \neq a_{j} \text { if } i \neq j\right\}
$$

We partition $S^{[m]}$ into subsets according to their squareness graphs. More precisely, for any
$\tau \in\{0,1\}^{\ell}$, where $\ell=\binom{m}{2}$, define

$$
P_{\tau}=\left\{A \in S^{[m]}: \delta(A)=\tau\right\} .
$$

Then

$$
S^{[m]}=\bigcup_{\tau} P_{\tau} .
$$

Let $I_{\tau} \subseteq \mathbb{F}_{p}\left[x_{1}, \cdots, x_{n}\right]$ the vanishing ideal of $P_{\tau}$. The next lemma shows that we can get a Gröbner basis for $I_{\tau}$ polynomial time.

Lemma 3.5.3. Given $f(x)=\prod_{a \in S}(x-a)$, where $S \subseteq \mathbb{F}_{p}$ has size $n$, and any tournament graph $\tau$ on $\{1,2, \cdots, m\}$, a Gröbner basis for the vanishing ideal of $P_{\tau}$ can be computed deterministically in time polynomial in $\log p$ and $n^{m}$.

Proof. let $I=\left\langle f\left(x_{1}\right), \cdots, f\left(x_{m}\right)\right\rangle$ with dimension $n^{m}$. Then $\left\{f\left(x_{1}\right), \cdots, f\left(x_{m}\right)\right\}$ is Gröbner basis for $I$ under any order. By lemma 3.2.1, we can compute $I:\left(x_{i}-x_{j}\right)$ for each pair $x_{i}$ and $x_{j}$ in polynomial time in $n^{m} \log p$. So we can compute

$$
I: \prod_{1 \leq i \neq j \leq m}\left(x_{i}-x_{j}\right)
$$

iteratively. Also, we can compute $h\left(x_{i}, x_{j}\right) \in \mathbb{F}_{p}\left[x_{1}, \cdots, x_{n}\right] / I$ in polynomial time by $\sigma$-algorithm. For every pair $x_{i}, x_{j}$, if there is an edge from $x_{i}$ to $x_{j}$ in $\tau$, we compute

$$
I:=\left\langle I, x_{i}-h\left(x_{i}, x_{j}\right)\right\rangle,
$$

else

$$
I:=\left\langle I, x_{j}-h\left(x_{i}, x_{j}\right)\right\rangle .
$$

Thus we get a vanishing ideal of $P_{\tau}$ in deterministic polynomial time in $\left\{\log p, n^{m}\right\}$.

If $P_{\tau}$ is not uniform, we can decompose it by the structure theorem 1.3.5. In the following, we discuss when all the $P_{\tau}$ can be uniform for small $m$. Then we talk about the symmetry properties among different $P_{\tau}$ 's.

### 3.5.2 Uniformness and Hadamard design

In this section, we discuss when $P_{\tau}$ are uniform and a connection to combinatorial designs.

### 3.5.2.1 $m=2$ : Square balanced sets

For $m=2$, we have $\tau=0$ or 1 . Then

$$
\begin{equation*}
S^{[2]}=P_{0} \cup P_{1}, \tag{3.4}
\end{equation*}
$$

where

$$
P_{0}=\left\{(a, b): a \in S, b \in B_{a}\right\} \text { and } P_{1}=\left\{(a, b): a \in S, b \in \bar{B}_{a}\right\}
$$

Note that the set $S^{[2]}$ corresponds to the ring

$$
R=\mathbb{F}_{p}[x, y] /\left\langle f(x), \frac{f(y)-f(x)}{y-x}\right\rangle
$$

The vanishing ideals of $P_{0}$ and $P_{1}$ are

$$
J_{0}=\left\langle f(x), \frac{f(y)-f(x)}{y-x}, x-h(x, y)\right\rangle, \quad J_{1}=\left\langle f(x), \frac{f(y)-f(x)}{y-x}, y-h(x, y)\right\rangle
$$

We call $S$ square balanced if $P_{0}$ is uniform, that is, $\left|B_{a}\right|$ is the same for all $a \in S$.
Lemma 3.5.4. (a). If $S$ is square balanced, then $\left|B_{a}\right|=\frac{n-1}{2}$ for all $a \in S$; and
(b). $P_{0}$ is uniform iff $P_{1}$ is uniform.

Proof. (a). For any $a, b \in S$, either $a \in B_{b}$ or $b \in B_{a}$. Since $a \in B_{b}$ is equivalent to $b \in \bar{B}_{a}$, that is, either $(a-b)$ or $(b-a)$ is $\eta$-square but not both. There are $\binom{n}{2}$ square relations of the form $b \in B_{a}$. So

$$
\sum_{a \in S}^{n}\left|B_{a}\right|=n(n-1) / 2
$$

If $\left|B_{a}\right|=\lambda$, for all $a$, then $\left|B_{a}\right|=\frac{n-1}{2}$.
(b). Note that

$$
S=\left\{B_{a}\right\} \cup\left\{\bar{B}_{a}\right\} \cup\{a\} .
$$

If $P_{0}$ is uniform, then $\left|B_{a}\right|=\frac{n-1}{2}$ for all $a$, so $\left|\bar{B}_{a}\right|=\frac{n-1}{2}$. That is, $P_{1}$ is uniform. Similarly for the reverse direction.

Corollary 3.5.5. If the size of $S$ is even, then $S$ can not be square balanced. So a factor of $f$ can be found in deterministic polynomial time.

Now assume $S$ is square balanced. The Gröbner basis of $I_{0}=\langle I, x-h(x, y)\rangle$ under elimination order $x \prec y$ is of the form $\left\langle f(x), g_{0}(x, y)\right\rangle$, where the leading term of $g_{0}(x, y)$ is $y^{(n-1) / 2}$. The Gröbner basis of $I_{1}=\langle I, y-h(x, y)\rangle$ under elimination order $x \prec y$ is of the form $\left\langle f(x), g_{1}(x, y)\right\rangle$, where the leading term of $g_{1}(x, y)$ is $y^{(n-1) / 2}$ by lemma (3.5.4) as well. Then

$$
\begin{equation*}
I=\left\langle f(x), g_{0}(x, y)\right\rangle \cap\left\langle f(x), g_{1}(x, y)\right\rangle . \tag{3.5}
\end{equation*}
$$

### 3.5.2.2 $m=3$ : Hadamard designs

$S^{[3]}$ can be partitioned into the following union according to the squareness graphs:

$$
S^{3}=\bigcup_{\tau \in\{0,1\}^{3}} P_{\tau}
$$

where

$$
\begin{array}{ll}
P_{000}=\left\{\left(a \in S, b \in B_{a}, c \in B_{a} \cap B_{b}\right)\right\}, & P_{001}=\left\{\left(a \in S, b \in B_{a}, c \in B_{a} \cap \bar{B}_{b}\right)\right\}, \\
P_{010}=\left\{\left(a \in S, b \in B_{a}, c \in \bar{B}_{a} \cap B_{b}\right)\right\}, & P_{011}=\left\{\left(a \in S, b \in B_{a}, c \in \bar{B}_{a} \cap \bar{B}_{b}\right)\right\}, \\
P_{100}=\left\{\left(a \in S, b \in \bar{B}_{a}, c \in B_{a} \cap B_{b}\right)\right\}, & P_{101}=\left\{\left(a \in S, b \in \bar{B}_{a}, c \in B_{a} \cap \bar{B}_{b}\right)\right\}, \\
P_{110}=\left\{\left(a \in S, b \in \bar{B}_{a}, c \in \bar{B}_{a} \cap B_{b}\right)\right\}, & P_{111}=\left\{\left(a \in S, b \in \bar{B}_{a}, c \in \bar{B}_{a} \cap \bar{B}_{b}\right)\right\} .
\end{array}
$$

We discuss below possible symmetry properties of this partition.

Lemma 3.5.6. Suppose $P_{000}$ is uniform. Then $\left|B_{a} \cap B_{b}\right|=(n-3) / 4$ for $a \in S$ and $b \in B_{a}$.

Proof. $P_{000}$ is uniform means that $S$ and $B_{a}$ are all square balanced for all $a \in S$. By lemma 3.5.4, $\left|B_{a}\right|=\frac{n-1}{2}$, thus

$$
\left|B_{a} \cap B_{b}\right|=\frac{\left|B_{a}\right|-1}{2}=\frac{n-3}{4},
$$

for every $a \in S, b \in B_{a}$.

Lemma 3.5.7. If $P_{000}$ is uniform, then $P_{\tau}$ is uniform for all $\tau \in\{0,1\}^{3}$.
Proof. Suppose $P_{000}$ is uniform and $\lambda=\frac{n-3}{4}$. First we show that $P_{100}$ is uniform. Since $P_{000}$ is uniform, we have

$$
\left|B_{a} \cap B_{b}\right|=\lambda, \forall a \in S, b \in B_{a}
$$

which is the same as

$$
\left|B_{b} \cap B_{a}\right|=\lambda, \forall b \in S, a \in \bar{B}_{b} .
$$

By renaming the variables, we have

$$
\left|B_{a} \cap B_{b}\right|=\lambda, \forall a \in S, b \in \bar{B}_{a},
$$

which means that $P_{100}$ is uniform. Now we show that $P_{001}$ is uniform. For any $b \in B_{a}$,

$$
\left|B_{a}\right|=\left|B_{a} \cap B_{b}\right|+\left|B_{a} \cap \bar{B}_{b}\right|+|\{b\}|=\frac{n-1}{2} .
$$

Since $\left|B_{a} \cap B_{b}\right|=\frac{n-3}{4}$ by lemma 3.5.6, we have $\left|B_{a} \cap \bar{B}_{b}\right|=\frac{n-3}{4}$. So $P_{001}$ is uniform. It is similar to show $P_{011}, P_{101}, P_{111}$ are uniform. Next we show $P_{010}=\frac{n+1}{4}$. Since $a \notin B_{b}$, we have

$$
\left|B_{b}\right|=\left|B_{a} \cap B_{b}\right|+\left|\bar{B}_{a} \cap B_{b}\right|=\frac{n-1}{2},
$$

but $\left|B_{a} \cap B_{b}\right|=\frac{n-3}{4}$, thus

$$
\left|\bar{B}_{a} \cap B_{b}\right|=\frac{n+1}{4} .
$$

It is similar to show $P_{110}$ is uniform.

The correspondence of $P_{\tau}$ and its fibre sizes at each level are listed as follows:

$$
\begin{aligned}
& \\
& P_{000}=\left\{\left(a \in S, b \in B_{a}, c \in B_{a} \cap B_{b}\right)\right\}: \\
& P_{001}=\left\{\left(a \in S, b \in B_{a}, c \in B_{a} \cap \bar{B}_{b}\right)\right\}: \\
& P_{010}=\{(a \in S \\
& \frac{n-1}{2}
\end{aligned} \frac{n-1}{2} \frac{n-3}{4} \begin{array}{llll}
\frac{n-3}{4} \\
P_{011}=\left\{\left(a \in S, b \in B_{a}, c \in \bar{B}_{a} \cap \bar{B}_{b}\right)\right\}: & n & \frac{n-1}{2} & \frac{n-3}{4} \\
P_{100}=\left\{\left(a \in S, b \in \bar{B}_{a}, c \in B_{a} \cap B_{b}\right)\right\}: & n & \frac{n-1}{2} & \frac{n-3}{4} \\
P_{101}=\left\{\left(a \in S, b \in \bar{B}_{a}, c \in B_{a} \cap \bar{B}_{b}\right)\right\}: & n & \frac{n-1}{2} & \frac{n+1}{4} \\
P_{110}=\left\{\left(a \in S, b \in \bar{B}_{a}, c \in \bar{B}_{a} \cap B_{b}\right)\right\}: & n & \frac{n-1}{2} & \frac{n-3}{4} \\
P_{111}=\left\{\left(a \in S, b \in \bar{B}_{a}, c \in \bar{B}_{a} \cap \bar{B}_{b}\right)\right\}: & n & \frac{n-1}{2} & \frac{n-3}{4}
\end{array}
$$

In combinatorial design theory, a system of subsets $B_{i}, 1 \leq i \leq n$, of a set $S$ with cardinality $n$ is called a Hadamard design of order $n$, if

$$
\left|B_{i}\right|=\frac{n-1}{2}, 1 \leq i \leq n,
$$

and

$$
\left|B_{i} \cap B_{j}\right|=\frac{n-3}{4}, 1 \leq i<j \leq n .
$$

For many values of $n$, there exist Hadamard design of order $n$. We give two examples.

Example 3.5.8. Let $n$ be a prime with $m \equiv 3(\bmod 4)$, and $S=\mathbb{Z} /(n)$. For $0 \leq a \leq$ $n-1$, define

$$
B_{a}=\left\{b \in S: a-b \text { is square in } \mathbb{F}_{n}\right\}
$$

Then $B_{a}$ 's form an Hadamard design of order $n$.

Example 3.5.9. Let $n=2^{\ell}-1$ and $S=\mathbb{F}_{2}^{\ell} \backslash\{(0,0, \cdots, 0)\}$. For each $a=\left(a_{1}, \cdots, a_{\ell}\right) \in$
$S$, define

$$
B_{a}=\left\{b=\left(b_{1}, \cdots, b_{\ell}\right) \in S: a_{1} b_{1}+\cdots+a_{\ell} b_{\ell}=0\right\} .
$$

Then one can check that

$$
\left|B_{a}\right|=\frac{n-1}{2}, \text { and }\left|B_{a} \cap B_{b}\right|=\frac{n-3}{4} \text { for all } a \neq b \text {. }
$$

Since Hadamard designs exist, it is possible that all the eight $P_{\tau}$ are uniform. Here's a concrete example.

Example 3.5.10. Let

$$
\begin{aligned}
P= & \{[1,2,3],[1,3,4],[1,4,2],[2,3,6],[2,5,3],[2,6,5],[3,4,7], \\
& {[3,6,4],[3,7,6],[4,2,5],[4,5,7],[4,7,2],[5,1,3],[5,3,7], } \\
& {[5,7,1],[6,1,4],[6,4,5],[6,5,1],[7,2,6],[7,1,2],[7,6,1]\} . }
\end{aligned}
$$

Then

$$
\begin{aligned}
& B_{1}=\{2,3,4\}, B_{2}=\{3,5,6\}, B_{3}=\{4,6,7\}, B_{4}=\{2,5,7\}, \\
& B_{5}=\{1,3,7\}, B_{6}=\{1,4,5\}, B_{7}=\{1,2,6\},
\end{aligned}
$$

and

$$
\begin{aligned}
& B_{1} \cap B_{2}=\{3\} \quad B_{1} \cap B_{3}=\{4\} \quad B_{1} \cap B_{4}=\{2\} \\
& B_{2} \cap B_{3}=\{6\} \quad B_{2} \cap B_{5}=\{3\} \quad B_{2} \cap B_{6}=\{5\} \\
& B_{3} \cap B_{4}=\{7\} \quad B_{3} \cap B_{6}=\{4\} \quad B_{3} \cap B_{7}=\{6\} \\
& B_{4} \cap B_{2}=\{5\} \quad B_{4} \cap B_{5}=\{7\} \quad B_{4} \cap B_{7}=\{2\} \\
& B_{5} \cap B_{1}=\{3\} \quad B_{5} \cap B_{3}=\{7\} \quad B_{5} \cap B_{7}=\{1\} \\
& B_{6} \cap B_{1}=\{4\} \quad B_{6} \cap B_{5}=\{1\} \quad B_{6} \cap B_{5}=\{2\} \\
& B_{7} \cap B_{1}=\{2\} \quad B_{7} \cap B_{2}=\{6\} \quad B_{7} \cap B_{6}=\{1\}
\end{aligned}
$$

Now we show that it is possible to further partition some of the $P_{\tau}$ via another
symmetry property. Note that $P_{010}$ and $P_{101}$ have an automorphism $\sigma_{3}$ mapping $(x, y, z)$ to $(y, z, x)$. By Ronyai lemma as follows, $P_{010}$ and $P_{101}$ can be decomposed. Consider $P_{010}$. The squareness graph of $P_{010}$ is a 3 -cycle. This means $P_{010}$ is invariant under the map: $(a, b, c) \mapsto(b, c, a)$. This induces an automorphism in $\mathbb{F}_{p}[x, y, z] / I_{3}$. We will show $P_{010}$ can be decomposed to at least 3 disjoint parts. First of all, $P_{010}$ can not be empty, otherwise by

$$
\left|B_{b}\right|=\left|B_{a} \cap B_{b}\right|+\left|\bar{B}_{a} \cap B_{b}\right|=\frac{n-1}{2},
$$

if $\left|\bar{B}_{a} \cap B_{b}\right|=0$, that means

$$
\left|B_{a} \cap B_{b}\right|=\left|B_{b}\right| .
$$

But $a \in B_{b}, a$ is not in $B_{a}, B_{a} \cap B_{b} \subsetneq B_{b}$, contradiction.

Lemma 3.5.11 (Ronyai 1992). Let $A$ be an algebra over $\mathbb{F}_{p}$ with dimension $t$. Given $a$ nontrivial automorphism of $A$, we can find in deterministic time $(t+\log p)^{o(1)}$ an ideal $I \subsetneq A$.

Since $P_{010}$ has an automorphsim, we apply Ronyai lemma to decompose the vanishing ideal of $P_{010}$ to subideals until each corresponding split variety doesn't have an automorphism on itself .

Lemma 3.5.12. Suppose $S$ is square balanced and $P_{010}$ has a finest partition by applying Ronyai's lemma as

$$
P_{010}=Q_{1} \cup Q_{2} \cup \cdots \cup Q_{t} .
$$

Then $3 \mid t$.

Proof. If $\exists i$ such that $\sigma_{3}\left(Q_{i}\right) \cap Q_{i} \neq \emptyset$, then we can decompose $Q_{i}$, contradicts. So for any $Q_{i}$, there exist $Q_{\ell}$ and $Q_{k}$ such that

$$
\sigma_{3}\left(Q_{i}\right)=Q_{\ell}, \text { and } \sigma_{3}^{2}\left(Q_{i}\right)=Q_{k}
$$

So $3 \mid t$.

Suppose $P_{010}$ can be partitioned to at least 3 parts as

$$
P_{010}=P_{21} \cup P_{22} \cup P_{23} .
$$

For each point $(a, b, c) \in P_{21},(b, c, a) \in P_{22}$ and $(c, a, b) \in P_{23}$. So three parts have the same size. We consider 4 cases of the structure of $P_{2 i}$ 's, $1 \leq i \leq 3$.

1, $P_{2 i}$ is not uniform at first level, we can factor $f$.

2, $P_{2 i}$ is not uniform at second level or can be decomposed at second level, then we can reduce $\frac{n-1}{2}$ to $\frac{n-1}{4}$.
3. If $P_{2 i}$ remains uniform at first and second levels but not in the third level, for some $i$. And the fibre sizes at first and second levels are $n, \frac{n-1}{2}$ respectively. Then we can also reduce $\frac{n-1}{2}$ to $\frac{n-1}{4}$.

4, If $P_{2 i}$ remains uniform at all levels but not in the third level, for some $i$. And the fibre sizes are $n, \frac{n-1}{2}$ respectively. Then let the third level fibre size be $k$ such that:

$$
n \frac{n-1}{2} \frac{n+1}{4}=3 n \frac{n-1}{2} k .
$$

So $k=\frac{n+1}{12}$.

To conclude, in all four cases, we can either decompose $f$, or reduce $n$ to $\frac{n-1}{4}$ by doing one extension, or reduce $n$ to $\frac{n+1}{12}$ by doing two extension. So we can reduce the levels needed to find a factor of $f$ from $\log n$ to $\frac{\log n}{\log _{4} 12}$.

Compared to the extension needed in Evdokimov (1992), we reduce the levels of extension as follows.

Theorem 3.5.13. Let $\ell(n)$ be the extension needed to find a factor of polynomial of degree $n$, then $\ell(n) \leq \frac{\log _{2} n}{\log _{4} 12}$.

Proof. By previous argument, that $\ell(n)=1+\ell(n / 4)$ or $\ell(n)=2+\ell(n / 12)$. So $\ell(n) \leq$ $2+\ell(n / 12)$.

This result reduces the number of extensions $\frac{\log _{2} n}{\log _{4} 8}$ in [Ivanyos, karpinski, and Saxena, 2008].

### 3.5.2.3 $m=4$ : transitive patterns

For every $\tau$ and $\sigma \in S_{m}$, where $S_{m}$ is the permutation group on $m$ many elements, define $\sigma(\tau)$ to be a new graph with vertices $\{1,2, \cdots, m\}$ and edges defined as follows. For two vertices $i, j$ in $\sigma(\tau)$, there is an edge from $i$ to $j$ iff there is an edge from $\sigma^{-1}(i)$ to $\sigma^{-1}(j)$ in $\tau . \sigma(\tau)=\tau\left(\sigma\left(x_{1}, x_{2}, \cdots, x_{m}\right)\right)$ is a new square relation generated from $\tau$. We call the whole class as $\operatorname{Trans}(\tau)$.

Example 3.5.14. For $\sigma \in S_{m}$, and any point $A=\left(a_{1}, \cdots, a_{m}\right), \sigma(A)=\left(a_{\sigma(1)}, \cdots, a_{\sigma(m)}\right)$.

Example 3.5.15. Consider $S^{4}$. Let $\tau_{1}=(000000)$. Then $\operatorname{Trans}\left(\tau_{1}\right)=$

$$
\left(\begin{array}{llll}
(000000) & (000001) & (000011) & (000111) \\
(001000) & (001010) & (001011) & (001111) \\
(110000) & (110100) & (110101) & (110111) \\
(111000) & (011010) & (111110) & (111111) \\
(011000) & (100001) & (011110) & (011111) \\
(100000) & (111100) & (100101) & (100111)
\end{array}\right)
$$



Figure 3.3: Graph all $\tau$ 's from $\operatorname{Trans}\left(\tau_{1}\right)$ which doesn't have cycle Let $\tau_{2}=(010001)$. Then $\operatorname{Trans}\left(\tau_{2}\right)=$
$\left(\begin{array}{llll}(010001) & (010011) & (000100) & (000110) \\ (101010) & (101011) & (001100) & (001101) \\ (010100) & (010101) & (110010) & (110011) \\ (101100) & (101110) & (111001) & (111011) \\ (010010) & (010110) & (011001) & (011101) \\ (101001) & (101101) & (100010) & (100110)\end{array}\right)$


Figure 3.4: Graph for all $\tau$ from $\operatorname{Trans}\left(\tau_{2}\right)$ which have two cycles

Let $\tau_{3}=(000010)$. Then $\operatorname{Trans}\left(\tau_{2}\right)=$
$\left(\begin{array}{l}(000010) \\ (001001) \\ (110001) \\ (111010) \\ (011100) \\ (100100) \\ (010111) \\ (101111)\end{array}\right)$


Figure 3.5: Graph for all $\tau$ 's from $\operatorname{Trans}\left(\tau_{3}\right)$ which have one cycle Let $\tau_{4}=(010000)$. Then $\operatorname{Trans}\left(\tau_{4}\right)=$

$$
\left(\begin{array}{l}
(010000) \\
(000101) \\
(001110) \\
(110110) \\
(111101) \\
(011011) \\
(100011) \\
(101000)
\end{array}\right)
$$



Figure 3.6: Graph for all $\tau$ 's from $\operatorname{Trans}\left(\tau_{4}\right)$ which have one cycle

Then $S^{4}$ an be decomposed into $2^{6}$ components. That is

$$
S^{4}=\bigcup_{\tau \in \operatorname{Trans}\left(\tau_{i}\right), 1 \leq i \leq 4} P_{\tau},
$$

where $P_{\tau}=\left\{p \in S^{4}: p\right.$ satisfies square relation $\left.\tau\right\}$.

Lemma 3.5.16. Let $G$ be a tournament graph on $n$ vertices. If Auto $(G)=\{1\}$, then we can get $n!$ graphs by permuting vertices of $G$.

We say a point set $P_{\tau}$ is uniform, if it is uniform from $i$-th coordinator to $i+1$-th coordinator, $1 \leq i \leq m-1$.

Lemma 3.5.17. If $P_{000000}$ is uniform, then $P_{100000}$ is uniform.

Proof. We just show the first one. Let $\tau$ be uniform. That is, there is a constant $C$ such that

$$
\left|B_{a} \cap B_{b} \cap B_{c}\right|=C, \forall a \in S, b \in B_{a}, c \in B_{a} \cap B_{b} .
$$

By exchanging and rename $a$ and $b$ in $\left\{b \in S, a \in \bar{B}_{b}, c \in B_{b} \cap B_{a}\right\}$ to be

$$
a \in S, b \in \bar{B}_{a}, c \in B_{a} \cap B_{b} .
$$

Then we proved $((0$ or 1$) 00000)$ is uniform.

Lemma 3.5.18. $P_{\sigma(\tau)}=\sigma\left(P_{\tau}\right)=\left\{\sigma(p): A \in P_{\tau}\right\}$. Let $\sigma$ be a permutation fixing $m$, i.e

$$
\sigma(1,2, \cdots, m-1, m)=(\sigma(1), \cdots, \sigma(m-1), m)
$$

Then $P_{\tau}$ is uniform at level $m$ iff $P_{\sigma(\tau)}$ is uniform at level $m$.

Proof. By definition, $\sigma(A)=\left(a_{\sigma(1)}, \cdots, a_{\sigma(m-1)}, a_{m}\right)$, for any $A \in P_{\tau}$. Then

$$
\left(a_{1}, \cdots, a_{m-1}, a_{m}\right) \in P_{\tau} \operatorname{iff}\left(a_{\sigma(1)}, \cdots, a_{\sigma(m-1)}, a_{m}\right) \in P_{\sigma(\tau)} .
$$

This implies that

$$
a_{m} \in \pi^{-1}\left(a_{1}, \cdots, a_{m-1}\right) \text { iff } a_{m} \in \pi^{-1}\left(a_{\sigma(1)}, \cdots, a_{\sigma(m-1)}\right) .
$$

So

$$
\pi^{-1}\left(a_{1}, \cdots, a_{m-1}\right)=\pi^{-1}\left(a_{\sigma(1)}, \cdots, a_{\sigma(m-1)}\right) .
$$

Hence the same fibre size.

Lemma 3.5.19. If $P_{000000}$ is uniform, then $P_{\tau}$ is uniform for all $\tau$ ' $s \in \operatorname{Trans}\left(\tau_{1}\right)$ are uniform.

Proof. By lemma 3.5.18, we know all $P_{\tau}$ 's where $\tau$ 's are in the same column in $\operatorname{Trans}\left(\tau_{1}\right)$ are equivalent to be uniform. So we only need to show that $P_{\tau}$ 's, where $\tau$ 's from the first row, are uniform. They are $P_{000001}, P_{000011}, P_{000111}$ are uniform. We first show that if $P_{000000}$ is uniform, then $P_{000001}$ is uniform. Since $c \in B_{a} \cap B_{b}$,

$$
B_{a} \cap B_{b} \cap B_{c}+B_{a} \cap B_{b} \cap \bar{B}_{c}+\{c\}=B_{a} \cap B_{b},
$$

for all $a \in S, b \in B_{a}$, and $c \in B_{a} \cap B_{b} . P_{000000}$ is uniform implies that

$$
\left|B_{a} \cap B_{b}\right|=\frac{n-3}{4},\left|B_{a} \cap B_{b} \cap B_{c}\right|=\frac{n-7}{8} .
$$

Thus

$$
\left|B_{a} \cap B_{b} \cap \bar{B}_{c}\right|=\frac{n-7}{8},
$$

for all $a \in S, b \in B_{a}$, and $c \in B_{a} \cap B_{b}$. Then

$$
\left|B_{a} \cap B_{b} \cap \bar{B}_{d}\right|=\frac{n-7}{8},
$$

for all $a \in S, b \in B_{a}$, and $d \in B_{a} \cap B_{b}$. Since $(a, b, d, c) \in P_{000001}, P_{000001}$ is uniform.
Next we show that $P_{000011}$ is uniform. $(a, c, d, b) \in P_{000011}$, we need to show that $\left|B_{a} \cap \bar{B}_{c} \cap \bar{B}_{d}\right|=\frac{n-7}{8}$.

$$
B_{a} \cap \bar{B}_{c} \cap B_{d}+B_{a} \cap B_{c} \cap B_{d}=B_{a} \cap B_{d},
$$

since $c$ is not in $B_{a} \cap B_{d}$. So

$$
B_{a} \cap \bar{B}_{c} \cap B_{d}=\frac{n+1}{8},
$$

where $d \in B_{a} \cap \bar{B}_{c}$. We apply this to the next equation,

$$
B_{a} \cap \bar{B}_{c} \cap B_{d}+B_{a} \cap \bar{B}_{c} \cap \bar{B}_{d}=B_{a} \cap \bar{B}_{c},
$$

since $d$ not in $B_{a} \cap \bar{B}_{c}$, we get

$$
\left|B_{a} \cap \bar{B}_{c} \cap \bar{B}_{d}\right|=\frac{n-7}{8},
$$

for all $c \in B_{a}, d \in B_{a} \cap B_{c}$. Thus we get $P_{000011}$ is uniform and $B_{a} \cap \bar{B}_{d}$ is square balanced, for $d \in B_{a}$.

Finally, we show that $P_{000111}$ is uniform. $(b, c, d, a) \in P_{000111}$. Similarly, we have an equation,

$$
\bar{B}_{b} \cap \bar{B}_{c} \cap \bar{B}_{d}+B_{b} \cap \bar{B}_{c} \cap \bar{B}_{d}=\bar{B}_{c} \cap \bar{B}_{d}
$$

since $b \in \bar{B}_{c} \cap \bar{B}_{d}$. By previous result,

$$
\left|B_{b} \cap \bar{B}_{c} \cap \bar{B}_{d}\right|=\frac{n-7}{8},
$$

we have

$$
\left|\bar{B}_{b} \cap \bar{B}_{c} \cap \bar{B}_{d}\right|=\frac{n-7}{8},
$$

for all $c \in B_{b}, d \in B_{b} \cap B_{c}$. So we proved $P_{000111}$ is uniform.

Remark: From this proof, we notice that $B_{a} \cap B_{b}$ is square balanced implies that $B_{a} \cap \bar{B}_{b}$ and $\bar{B}_{a} \cap \bar{B}_{b}$ are both square balanced for all $b \in B_{a}$.

Remark: It is worth noting that if at second level, all components are uniform, then $\lambda_{1}=B_{a} \cap B_{b}=\frac{n-3}{4}, \lambda_{2}=\bar{B}_{a} \cap B_{b}=\frac{n+1}{4}$, we have $\lambda_{2}=\lambda_{1}+1$. Then one of them must be even number. By Roanyai lemma, either $B_{a} \cap B_{b} \cap B_{c}$ or $\bar{B}_{a} \cap B_{b} \cap B_{c}$, where $\left.a \in S, b \in B_{a}, c \in B_{a} \cap B\right) b$, can not be uniform, so can be further decomposed.

In Cheng, Huang (2000), it is pointed out that $B_{a} \cap B_{b} \cap B_{c}$ can not be uniform for all $a \in S, b \in B_{a}, c \in B_{a} \cap B_{b}$ based on a result in Muller, Pelant (1974). But the result is without the restricted condition $b \in B_{a}, c \in B_{a} \cap B_{b}$, so the number of levels to proceed in Cheng, Huang (2000) $n^{\frac{\log n+O(1)}{3}}$ is not right.

### 3.5.3 Super square balanced schemes

In Section, we have already get a decomposition of $S^{[m]}$ as

$$
S^{[m]}=\bigcup_{\tau} P_{\tau} .
$$

In this section, we introduce several splitting tools to further refine this decomposition. More precisely, we have

- Tool A: Use Ronyai lemma to decompose if there is an automorphism.
- Tool B: Change lex order in Gröbner bases.
- Tool C: Self extension.
- Tool D: Cross extension.

Tool A. is based on the following lemma.

Lemma 3.5.20 (Ronyai 1992). Let $A$ be an algebra over $\mathbb{F}_{p}$ with dimension $t$. Given a nontrivial automorphism of $A$, we can find a nontrivial ideal of $A$ in deterministic time $(t+\log p)^{o(1)}$ an ideal $I \subsetneq A$.

To factor $f$, we may be able to make different fibre sizes among the points of $f$. So we need to find ways to change the ideal to be not uniform.

Tool B. uses the fact that an ideal is not necessary to be strong uniform to split ideal. Given a variety in uniform under certain order, say $x_{1}<x_{2}<\cdots<x_{n}$. If we change the order to be a new one, say $x_{i_{1}}<x_{i_{2}}<\cdots<x_{i_{n}}$, it is with high possibility that it won't be uniform.

Example 3.5.21. Consider the example 1.3.8. If we change the term order to be $z<y<x$, then it is not uniform as more as showed as follows.


Figure 3.7: An example which is not uniform

And the Gröbner basis is

$$
\begin{aligned}
g_{0}= & z^{6}-22 z^{5}+190 z^{4}-820 z^{3}+1849 z^{2}-2038 z+840 \\
g_{1}= & (z-1)(z-2)(z-3)(z-4) y-2(z-1)(z-2)(z-3)(z-4) \\
g_{2}= & (z-1)\left(y^{2}-3 / 2 y z^{2}+17 / 2 y z-17 y+1 / 3 z^{4}-17 / 3 z^{3}+110 / 3 / 3 z^{2}-248 / 3 z+100\right. \\
g_{3}= & (y-2)(y-3)(y-4) \\
g_{4}= & (z-2) x-y^{2}+y z^{3}-13 / 2 y z^{2}+25 / 2 y z-y-5 / 18 z^{5}+59 / 12 z^{4}-605 / 18 z^{3}+ \\
& 417 / 4 z^{2}-2585 / 18 z+184 / 3 \\
g_{5}= & (y-2)(x+y-5) \\
g_{6}= & (x-1)(x-2)=x^{2}-3 x+2
\end{aligned}
$$

The leading terms are $\left\{z^{6}, y z^{4}, y^{2} z, y^{3}, x z, x y, x^{2}\right\}$. The $L C\left(g_{1}\right)$ is $(z-1)(z-2)(z-$ $3)(z-4)$, it is a factor of $g_{0}$ as well as $L C\left(g_{2}\right)=(z-1)$.

But there may be cases that changing order can not help.

Definition 3.5.22. (Strong uniform). We say an ideal I or its variety is strong uniform, if the points of the ideal is uniform under all lex order $x_{i_{1}}<x_{i_{2}}<\cdots<x_{i_{n}}$.

Example 3.5.23. Let

$$
\begin{aligned}
P= & \{[1,2,3],[1,3,4],[1,4,2],[2,3,6],[2,5,3],[2,6,5],[3,4,7], \\
& {[3,6,4],[3,7,6],[4,2,5],[4,5,7],[4,7,2],[5,1,3],[5,3,7], } \\
& {[5,7,1],[6,1,4],[6,4,5],[6,5,1],[7,2,6],[7,1,2],[7,6,1]\} . }
\end{aligned}
$$

Computing in $\mathbb{Z}_{103}$ and using lex order $z<y<x$, the reduced Gröbner basis is

$$
\begin{aligned}
g_{0}= & z^{7}-28 z^{6}+13 z^{5}-3 z^{4}-29 z^{3}-51 z^{2}-13 z+7 \\
g_{1}= & y^{3}-14 y^{2} z^{6}-34 y^{2} z^{5}+7 y^{2} z^{4}+y^{2} z^{3}-15 y^{2} z^{2}+21 y^{2} z+16 y^{2}-49 y z^{6}+48 y z^{5} \\
& -19 y z^{4}+38 y z^{3}-13 y z^{2}+44 y z-45 y+51 z^{6}-36 z^{5}-5 z^{4}+13 z^{3}+8 z^{2}+2 z-37 \\
g_{2}= & x-41 y^{2} z^{6}+y^{2} z^{5}+14 y^{2} z^{3}+18 y^{2} z^{2}+29 y^{2} z+32 y^{2}+22 y z^{6}-23 y z^{5}-43 y z^{4}+ \\
& 30 y z^{3}-23 y z^{2}-44 y z+12 y-2 z^{6}-36 z^{5}-45 z^{4}-33 z^{3}+51 z^{2}-17 z+23
\end{aligned}
$$

And the structure of $P$ is as follows:


Figure 3.8: A strong uniform case

It is obvious that under different lex order the Gröbner basis remains the same under permutation of variables.

Tool C. is described as follows.

Lemma 3.5.24 (Self-extension). Let $I_{(X, y)}$ be any radical ideal in $\mathbb{F}_{p}[X, y]$ where $X=$ $\left(x_{1}, \cdots, x_{t}\right)$. Define

$$
\hat{I}=<I_{(X, y)}, I_{(X, z)}, y-h(y, z)>:(y-z) \subset \mathbb{F}_{p}[X, y, z] .
$$

Then

$$
V(\hat{I})=\left\{(\alpha, b, c):(\alpha, b) \in V\left(I_{(X, y)}\right),(\alpha, c) \in V\left(I_{(X, z)}\right), \text { and } c \in B_{b}\right\}
$$

Hence $V(\hat{I})$ is uniform from $(X, y)$ to $z$ iff $\pi_{y}^{-1}(\alpha)$ is square balanced for each $\alpha$.

We describe tool D in the following lemma.

Lemma 3.5.25 (Cross-extension). Let $I_{1}(X, y)$ and $I_{2}(X, y)$ be two radical ideals in $\mathbb{F}_{p}[X, y]$, where $X=\left(x_{1}, \cdots, x_{t}\right)$, that are coprime and

$$
I_{1} \cap \mathbb{F}_{p}[X]=I_{2} \cap \mathbb{F}_{p}[X] .
$$

Define

$$
\hat{I}=<I_{1}\left((X, y), I_{2}(X, z), y-h(y, z)>\mathbb{F}_{p}[X, y, z] .\right.
$$

Then

$$
\left.V(\hat{I})=\left\{(\alpha, b, c):(\alpha, b) \in V\left(I_{1}\right)\right),(\alpha, c) \in V\left(I_{2}\right), \text { and } c \in B_{b}\right\} .
$$

If $V(\hat{I})$ is not uniform at level $z$, we can decompose $V\left(I_{1}(X, y)\right)$ (equivalently $I_{1}(X, y)$ ).

For any partition

$$
S^{[m]}=P_{1} \bigcup P_{2} \cdots \bigcup P_{t},
$$

we say $I\left(P_{i}\right)=\left\langle f^{\prime}(x), g(x, y), \cdots\right\rangle$ ( as a generic position )is homogeneous if $f^{\prime}(x)=$ $f(x)$. we apply tools $A$ to $D$ to each component or pair of components. We will stop if we find a factor of $f(x)$, that is $\exists P_{i}$ is not homogeneous.

Definition 3.5.26. Super square balanced scheme is defined to be any partition

$$
S^{[m]}=P_{1} \bigcup P_{2} \cdots \bigcup P_{t}
$$

that can not be split further by any of the tools $A$ to $D$, while all $P_{i}$ 's are homogeneous.

Conjecture 3.5.27. Super square balanced schemes do not exist for some constant $m$ which implies that we can get a factor of $f(x)$ in deterministic polynomial time.

## Chapter 4

## Future work

In this short section, we mention a few major open problems that are related to the topics of the thesis and deserve future studies.

As a bivariate polynomial factorization is a special case for primary decomposition, we are wondering is there any advantage to use Hensel lifting technique on primary decomposition. We have the first problem as follows.

Research problem 1. Can our lifting technique be used for algorithms for primary decomposition?

Jean-Charles Faugére (1999), (2002) (F4, F5) provided efficient algorithms for computing Gröbner bases. Compared to methods used in their algorithms, We can use our method described in the proof of theorem 3.2.1 of computing Gröbner basis for $\langle I, h\rangle$ from Gröbner basis of $I$ by adding one polynomial to speed up algorithms in Jean-Charles Faugére (2002). that is our

Research problem 2. Use our result on $\langle I, h\rangle$ to speed up algorithms for computing Gröbner bases for general ideals (say F4, F5)?

As discussed in Section 3.5.2.3, we are interested in the geometry properties of tournament graphs for $m=4,5, \cdots$, which may help to reduce the levels needed to find a proper factor of $f(x)$, even for some constant $m$. That is the following problem.

Research problem 3. Existence of super square balanced schemes

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