



Effect of Vibrating Footing on a Nearby Static – Load Footing

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Received 21 April 2019; Accepted 28 July 2019

Abstract

This paper presents an experimental study on the dynamic response of square footings under effect of dynamic load comes from adjacent footing called the (source of vibration) which is excited by a known vibration source placed on the top of it, the objective is to study the effect of dynamic motion of the source of vibration on a nearby footing, called second footing, both footings rest on collapsible soil (gypseouse soil) with gypseouse content (60%). The study is performed through wide experimental program in dry and soaked condition. The first footing (source vibration) and the second footing have dimensions (80×80×40), (100×100×40) mm respectively and are manufactured from steel, then the two footings placed centrally over soil after prepared it in layers' form in steel container with (1000×500×500) mm. The first footing exposed to vertical harmonic loading by using a rotating mass type mechanical oscillator to gives a similar effect of the dynamic loads, the second footing loaded with static weight only, under the dynamic excitation. The tests are conducted under dynamic response for three frequencies (10, 20, 30) Hz, the movement (displacement amplitude, velocity, and acceleration) of the second footing studied by varying spacing between the footings. The results showed that the amplitude of displacement, velocity, and acceleration for the second footing decreases when the spacing between footing increase. In addition, the value of these parameters at dry state is greater than its value at soaked state.

Keywords: Dynamic Load; Machine Foundation; Model Test; Square Footing; Vibration.

1. Introduction

The Dynamic loads can be generated from moving vehicles, heavy machines, or by move the train, etc. which causing the foundations to behave in a various mode under these loads. The problem of interaction between nearby foundations is of preponderant practical importance, as in many status foundations confront in fact are not secluded and they predominating interact with each other depending on of their close spacing, which may oftentimes be causing damage to structures in both strong and serviceability especially, under dynamic condition. Because of that, a need is to take out a simplified method to study the effect of foundations subjected to dynamic excitement on adjacent foundations. For single isolated foundation many researchers conducted a number of studies onset from the (simple spring-mass-dashpot) system to the (rigorous elastic half space model) proposed by many researchers like [1-3]. Analytical and numerical studies conducted to understand the dynamic interaction of foundations in a group and the soil-structure interaction behavior under dynamic loading such as [4-6].

The gypseous soil is one type of the collapsible soils; it covers wide areas in Iraq. This soil has high bearing capacity in dry state, but it subsides (collapses) upon saturation due to dissolving of cementation and particle bonding. Therefore, structures supported on unstable soil should be guarded against such danger. These problems are usually have led to

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 <http://dx.doi.org/10.28991/cej-2019-03091367>



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cracking, tilting and collapsing the related structure [7]. This type of soil covers about 31.7% in Iraq with different gypsum content ranging from 10-70% [8].

Chen (2015) researched the cross-cooperation issue among multi-establishments on a straight viscoelastic medium at little shear strains. In the examination, the establishments are discretized into various sub square-components. The dynamic reaction inside each sub-component is depicted by the Green's capacity. Consolidating the removal limit condition and the power balance of the establishments, it gets the dynamic impedance and consistence elements of the establishments. Broad outcomes for two unbending roundabout establishments put at various detachments are introduced. Parametric investigations are done on the dynamic collaboration among adjoining establishments and illustrative the outcomes for a few firmly dispersed establishments [9].

Abhijeet and Priyanka (2016) examined the dynamic cooperation impact of firmly separated square establishments under machine vibration through an exploratory examination, number of enormous scale model tests were directed in the field, the dynamic association of various blends of two-balance get together was researched by actuating vertical symphonious burden on one of the footings (dynamic balance), where the other balance (uninvolved balance) was stacked with the static weight as it were. The dynamic balance was energized with various sizes of dynamic stacking and the reaction was recorded for both the footings, set at various clear separating (S).

They were seen that the inactive balance experiences reverberation because of the dynamic excitation on the dynamic balance, which happens, notwithstanding, with a stage slack from the resounding recurrence of the dynamic balance. This stage slack is observed to be an indispensable parameter in characterizing the dynamic collaboration of a gathering of footings. The stage slack is seen to diminish with abatement in the dispersing between the footings, the variety of transmission proportion is by and large connected with a base and a most extreme point [10].

Chen (2016) performed parametric investigation on the dynamic cooperation between neighbouring establishments. The impacts of separation and arrangement course between establishments have been analysed. He detailed that the consequences of establishments adjusted along various heading showed that the impedance capacities because of the comparing loads on the establishment itself, change pretty much nothing. The coupling impedance works because of the relating loads on different establishments, are emphatically influenced by the establishment arrangement heading. The impedance of an establishment in an establishment bunch at bigger recurrence and separation will in general be that of single establishment [11].

Sbartai (2016) directed an examination on the dynamic cooperation for two neighboring unbending establishments implanted in a viscoelastic soil layer. The technique which has been utilized is the limit component strategy (BEM) to define the arrangement, at that point to deciding the consistence elements of the two adjoining establishments concerning their dispersing, substratum profundity, masses, shapes, installing, load force, and frequencies of excitation. The examination of the exhibited investigation showed that the impact of a few parameters on the dynamic communication reaction of two nearby establishments is no immaterial. Specifically, the predominant impact of certain parameters, for example, the heterogeneity of the dirt, state of the establishments, and the heap force, contrasted with different ones is plainly uncovered [12].

Keawsawasvong and Teerapong (2017), researched the dynamic communication between two inflexible rectangular establishments and a multi-layered poroelastic medium exposed to time-symphonious vertical stacking, it accepted the contact surface between the establishment and the layered medium to be smooth and completely penetrable, and the contact surface was discretized into various square components. It is discovered that the impedance capacities are obviously impacted by the recurrence of excitation and the separation between the two establishments [13].

Han et al. (2017) explored the dynamic association between at least two adjoining establishments laying on the outside of a stratified soil. Parametric investigation was done to explain the impacts of layer profundity, soil damping, dividing between adjoining establishments, masses and minute in activities of supporting structures and the wave engendering speed on the dynamic conduct of three-dimensional (3D) establishment soil-establishment communication (FSFI). Likewise, numerical precedents are given to confirm the exactness and computational dependability of the proposed methodology. He referenced the interfaces between the establishments and the dirt should be discretized and there is no restriction on the thickness or on the quantity of soil layers to be considered and study demonstrated the numerical outcomes got are exceptionally precise [14].

Ali et al. (2018) displayed the aftereffects of the dynamic investigation of a four-chamber blower establishment. The establishment square backings a four-chamber dress-rand blower, suction and release bottles. What's more, by utilizing a three-dimensional limited component model of the dirt establishment framework to decide the dynamic reaction of the dirt establishment framework and to survey the establishment reaction under the connected powerful stacking forced by the blower wrench. The dynamic examination is performed by (1) performing eigenvalue investigation of the establishment square, considering the impact of the dirt establishment connection to decide the dirt establishment characteristic frequencies and modular support variables, and (2) performing constrained reaction of the establishment

under connected crankshaft unbalance burden to decide the constrained reaction adequacy of the dirt establishment framework [15].

Vicencio and Nicholas (2018) assessed the impact of Structure-Soil-Structure Interaction (SSSI) between two structures given various parameters of the structures, between structure dispersing, and soil type. He proposed a two-dimensional straightforward discrete nonlinear model and depicted this by a lot of nonlinear differential conditions of movement. The outcomes demonstrated that there are both horrible and helpful setups of the two structures that produce significant contrasts between nonlinear SSSI and nonlinear SSI (the uncoupled structure case). He referenced that the unfavourable impacts of SSSI can be increasingly articulated when the nonlinear soil conduct is accepted [16].

Andersen (2018) examined the significance of dynamic structure–soil–structure association (SSSI) for structures with at least two establishments, it led the investigation of such polypod establishments in recurrence space, thinking about the range (0 – 50) Hz and utilizing Green's function for wave engendering in layered soil. The standardized powerful solidness' identified with individual establishments and cross-coupling between two establishments are introduced [17].

Keawsawasvong et al. (2019), exhibited an examination on the dynamic association issue including firmly dispersed establishments under shaking vibrations. It is discovered that shaking vibrations of the stacked establishment could be considered as a solitary establishment when the separation between the contiguous establishments is twice more noteworthy than their width. Despite what might be expected, an emptied establishment would in any case experience a transmitted vitality disseminated from a stacked establishment notwithstanding when the separation between them increments [18].

Therefore, lack of experimental studies on the behavior of foundation which are adjacent to the machine foundations encouragement to take up the present's investigation, that gives an explanation of the dynamic interference effect between two closely spaced square footings resting on gypseuse soil by conducting small scale model experimental.

The development in the cities as a result of the urgent need to use machines and equipment, and these devices are considered as main sources of vibrations which transfer through soil and effect on their engineering properties. So the objectives of the current work are investigating experimentally the dynamic response of foundation resting on a gypseuse sandy soil under the effect of dynamic load installed on the adjacent foundation in both state (dry and soaked). The dynamic response includes displacement amplitude, velocity of vibration, and the acceleration.

This paper presents a study on dynamic response of one footing with static load nearby another footing with dynamic load as (source of vibration) and dynamic loading applied on top of it, both footing have square shape, on a gypseuse soil. The present's investigation deals with the effect of the vibrations of the first footing on the neighboring footing. Both foundations are resting on surface soil.

1.1. Definition of Problem

Two closely spaced square placed on gypseuse soil (in both state dry and soaked) as shown in Figure 1. The load intensity below the first footings (source of vibration) was maintained as (6 kN/m²), the second footing is placed with intensity of load equal to (30 kN/m²) and (S) represents the spacing between the two footings. The objective is to determine the dynamic response of the second footing (displacement amplitude, velocity, acceleration), due to the application of dynamic excitation on the top of the first footing.

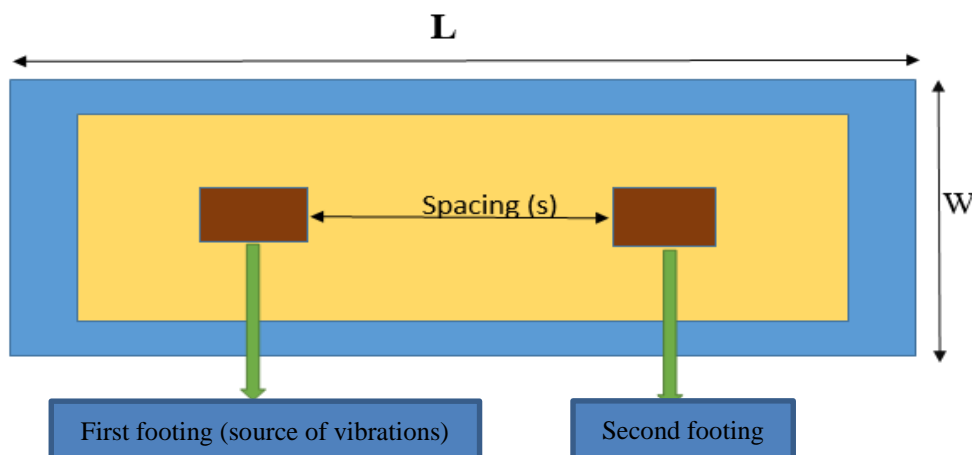


Figure 1. Layout of experimental model

2. Materials and Methods

2.1. Apparatuses of Model

The apparatuses of model include the followings:

- 1) Steel box with dimension (1000x500x300) mm.
- 2) Two footings with dimensions (80x80x40) mm, for first footing as a machine foundation, (100x100x40) mm, for second footing which manufactured from steel both footings have square shape.
- 3) Mechanical oscillator.
- 4) Piezoelectric accelerometer.
- 5) Two dial gauge.
- 6) Variable frequency drive.
- 7) Vibration meter.
- 8) Digital tachometer.
- 9) Computer device.
- 10) Steel Mold.
- 11) Water tank.
- 12) Dial gauge.
- 13) Static weight.
- 14) Ac automatic voltage regulator.
- 15) Camera stand

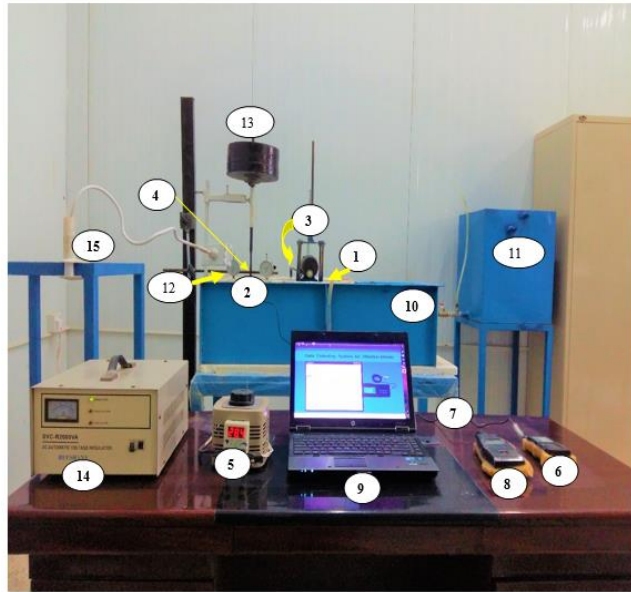


Figure 2. The model with apparatuses

2.2. Test Setup

After reviewing the previous studies presented by various researchers, such as [19 -24], the experimental model setup was designed, on the analysis of foundations under effect of the harmonic vibrations. A two steel square footings, the first with dimensions (100x100x40) mm as a machine foundation (vibration source), the second footing with dimensions (80x80x40) mm subjected to static load only. Circular weights (20kg in mass) of 25cm in diameter used for loading the second footing statically, a rotating mass mechanical oscillator instead over the first footing to produce a varying dynamic load. The mechanical oscillator be composed of a rotating discs made from steel, with diameter (60) mm and, thickness (10) mm. A small eccentricity mass (me) is put on rotating disc at an eccentricity (e) of (20) mm, from the axis of rotation. In this study, one type of eccentric settings is used with value (60) gm.

A varying speed DC motor is used to turn on the (mechanical oscillator) at different frequency with ranging from (100rpm – 11000) rpm. A speed controller unit is placed outside the model to control the speed of the DC motor.

The Piezoelectric accelerometer which was connected directly to computerized digital vibration meter (6063) model, which was in turn interfaced to the computer for displaying the dynamic response as displacement amplitude, velocity or acceleration is set before the test.



Figure 3. Devices used for measuring vibration response

The digital tachometer (DT-2234A+) model was used to ensure that there is no change in the frequencies. Two-dial gauge are used to determine the settlement of the second footing during operation model by Place them on the edges of the footing.



Figure 4. Digital tachometer

2.3. Preparation and Test Procedure

The soil in this research was taken from Governorate located north of Iraq, namely Tikrit, has been carried out for the testing program; see Figure 5. Table 1 shows the physical properties of the soil and Table 2 shows the chemical properties. Figures 6 and 7 revealed the results of the laboratory tests carried out on the soil sample used in current study. Water content test is conduct at temperature (45) °C to prevent losing crystal of gypseous soil. The sample of gypseous soil of gypseous content of (60%) are classified as moderately severe (ASTM D5533-2003). The gypseous soil (passing sieve no.4) placed in the steel container in six layers with a uniform field density using the hummer device. The surface checked and leveled by a bubble ruler (balance) device. Both footings are placed centrally over the prepared soil.

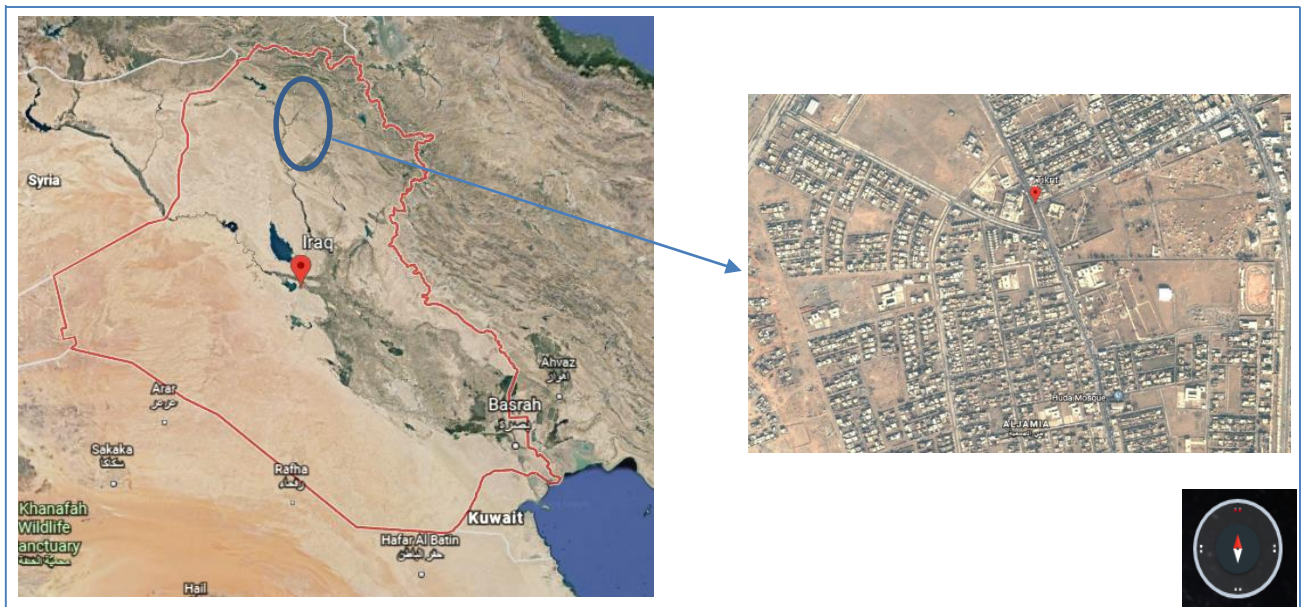


Figure 5. The location of the soil sample

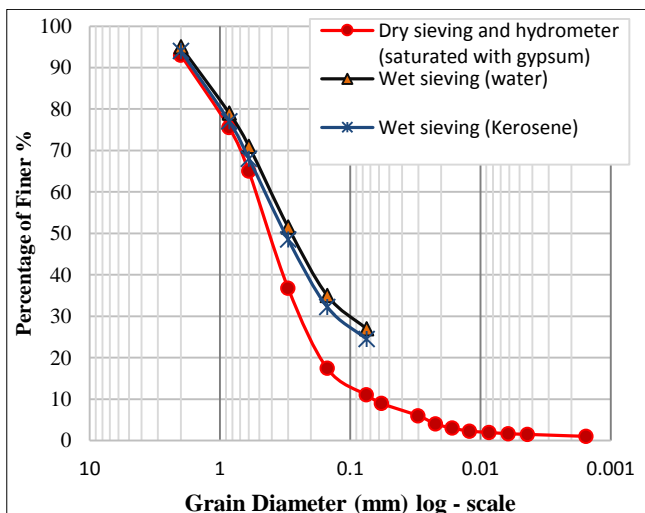


Figure 6. Grain size distribution for gypseous soil

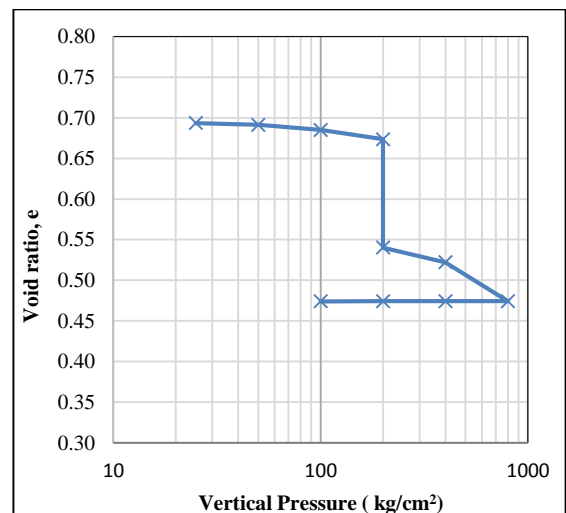


Figure 7. Results of single oedometer collapse test for sample soil used

Table 1. Physical property of gypseous soil which is used for testing

Test	Properties	Value	Specification
Atterberg's limits	Specific Gravity (Gs)	2.41	ASTM D 854 (2006)
	Liquid limit (L.L) %	21.1	
	Plastic limit (P.L) %	N.P	ASTM D4316-84
	Plasticity Index (P.I)	N.P	
Compaction characteristics	Max. dry density (KN/m ³)	16.23	ASTM 698-00
	Optimum Moisture content %	12.33	
	Water content %	2.8	ASTM D2216-02
Grain size analysis	D10 (mm)	0.07	
	D30 (mm)	0.14	
	D60 (mm)	0.35	
	Coefficient of uniformity, Cu	5	ASTM D422-02
	Coefficient of curvature, Cc	0.8	
	Passing sieve No. 200 (%) (using kerosene)	24	
	Classification of soil based on (USCS)	SM	
Direct Shear Test	The collapse potential	7.9	ASTM D5533-2003
	Angle of Internal Friction (ϕ) in dry	38	
	Soil Cohesion (C) (KN/mm ²) in dry	14	ASTM D 3080-98
	Angle of Internal Friction (ϕ) in soaked	34	
	Soil Cohesion (C) (KN/mm ²) in soaked	5	
	Test unit weight (kN/m ³), γ_d test	15	
	Field density ((kN/m ³), γ_{field})	14.6	ASTM D1556-07

Table 2. Results of chemical properties of gypseous soil used for testing (BS 1377: 1990, Part 3)

Composition	Value %
Total soluble salts (T.S.S.) %	67.2
Gypsum content %	60
Sulphate content (SO ₃) %	30.5
Organic matters (O.M) %	0.22
Chloride content (CL) %	0.062
pH value	8.1

Proper care is taken to keep the center of gravity of system and the footings to lie in the same vertical line with center of gravity of the container. After studying results reached by the researchers and carried out some preliminary tests, time of one hour for the duration of the tests chosen, 30 minutes' operation test for the dry state and 30 minutes for the test under soaking condition, it is important to mention that for the test under soaking condition, steel container left for (24) hours to be sure that soil was completely soaked, and in the second day the test is continue.

In this investigation, eccentric settings ($m_e = 60$ gm) is used to simulate dynamic load. The oscillator is then operated slowly through a motor by using speed control unit to prevent sudden application of high dynamic load. Thus, the first footing subjected to vibration in the vertical direction.

The dynamic response (displacement amplitude, velocity, acceleration) of the second footing are measured and recorded at the same time using Piezoelectric accelerometer and two dial gauge, are placed, previously on top and edge of the second footing to obtain a foundation response, the operating frequency of (600, 1200, 1800) rpm equivalent to (10, 20, 30) Hz is considered in the present study, the response parameters were recorded every 5 minutes during operation test duration.

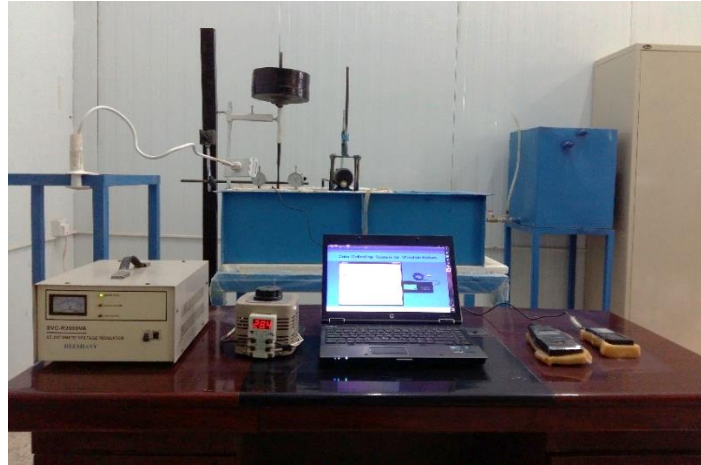


Figure 8. Laboratory Model Testing

3. Results and Discussion

In the present study, the dynamic response of square footing is investigated under dynamic exciting force which originated from a nearby footing as a machine foundation.

After verifying the stability of foundations under the static load, the dynamic analysis for the second footing is carried out by exciting the first footing with vertical load intensity created by the machine vibration. The displacement amplitude, velocity, and acceleration at different spacing between the two footings ($S=B$, $S=2B$, $S=3B$) are measured which the two footings are erected on gypseouse soil for both state (dry and soaking) in presence of the dynamic excitation applied on the first foundation. The dynamic response of the second footing for three frequencies (10, 20, 30) Hz at different spacing between footings is shown in Figures 9-14.

3.1. Displacement Amplitude

In Figures 9 and 10 the maximum and minimum displacement amplitude plotted against the frequency, for three frequencies (as mentioned above) at dry and soaking state, we note that the magnitude of the displacement amplitude at ($S = B$) increases when the operation frequency increases for both state (dry and soaking). For the maximum amplitude at dry and soaking state, this increasing is slight when goes from 10 Hz to 20 Hz and be larger when goes to 30 Hz. On other hand, the minimum amplitude shows increases just slightly when goes form 10 Hz to 20 Hz or 30 Hz at dry state but at soaking, its doubled in value.

At soaking state, it is observed that there is a decreasing in magnitude of the displacement amplitude compare with dry state for the three frequencies, this decreasing after soaking can be attributed to presence of water, whom acting as a wave inhibitor. The energy of the vibrations generated from the first footing became lower during transmission through soil at soaking condition causing decreasing in the displacement amplitude of the second footing.

At ($S=2B$), here finds decreasing in values of the maximum and minimum displacement amplitude compare with magnitude of the displacement amplitude at ($S=B$) for both state (dry and soaking). This is because the wave of vibration cut off a longer distance when it travels from the source (the first footing) to the receiver (the second footing). In other word, increasing the spacing led to decreases the displacement amplitude, the propagated of vibrations through the soil leads to a decrease in the energy of those vibrations.

At ($S=3B$), for the maximum displacement amplitude at dry state, the magnitude increased by half when goes from 10 Hz to 20 Hz and increased by two and a half times in value at 30 Hz. For the minimum displacement amplitude, the value has doubled from 10 Hz to 20 Hz or 30 Hz.

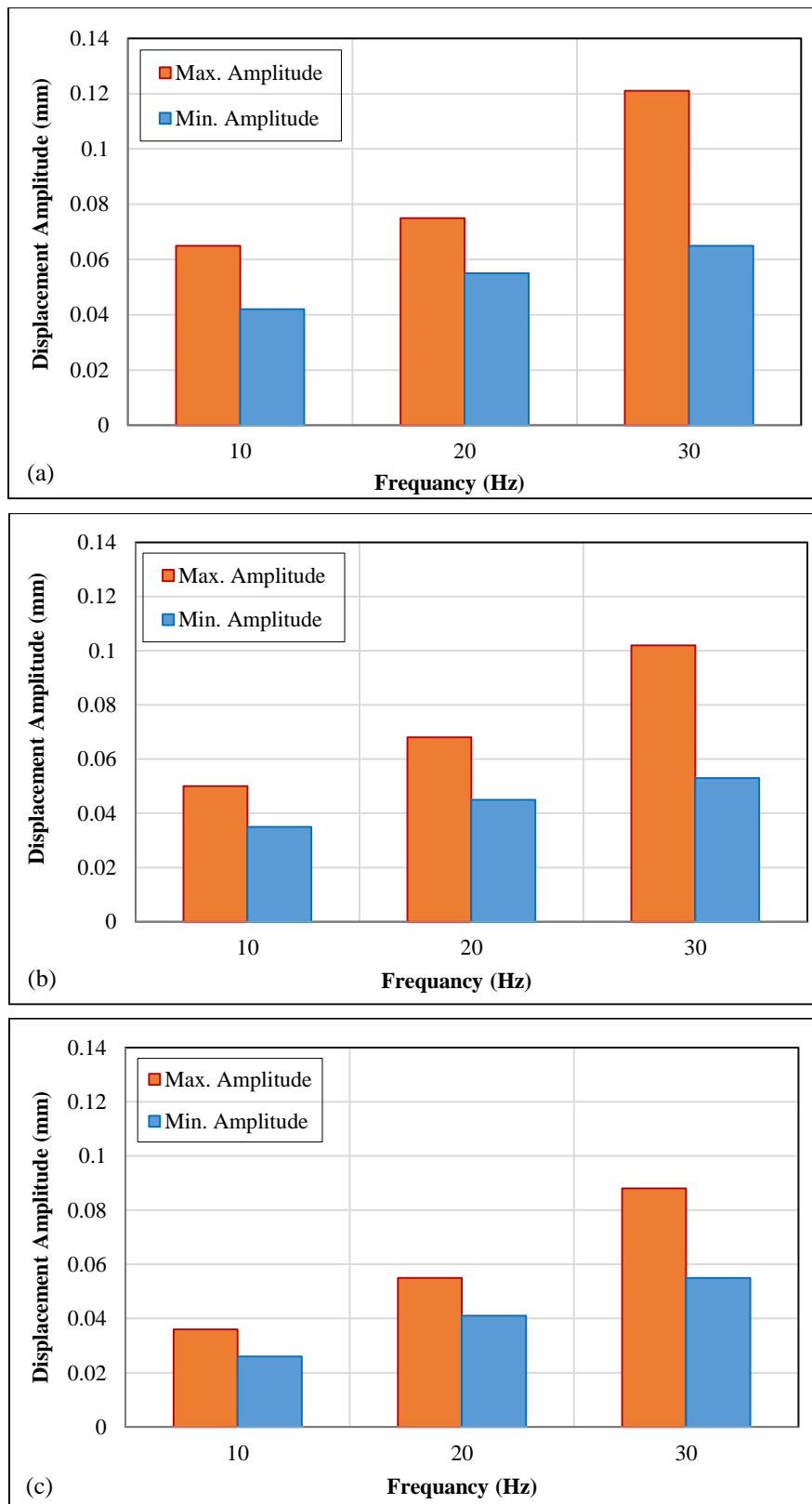


Figure 9. The displacement amplitude versus frequency for different spacing (s), (a) at S=B, (b) at S=2B, (c) at S=3B for dry condition

At soaking state, there is a decreasing in magnitude of displacement amplitude compare with dry state. The maximum displacement amplitude shows slight increase when goes from 10 Hz to 20 Hz, but doubled in magnitude when moves to 30 Hz. The minimum displacement amplitude shows different behavior, the magnitude of amplitude increases doubled when goes from 10 Hz to 20 Hz and increased by three times in value at 30 Hz.

Here observes the magnitude of the displacement amplitude decreased in comparison with magnitude amplitude at (S=B), and (S=2B) for both state (dry and soaked).

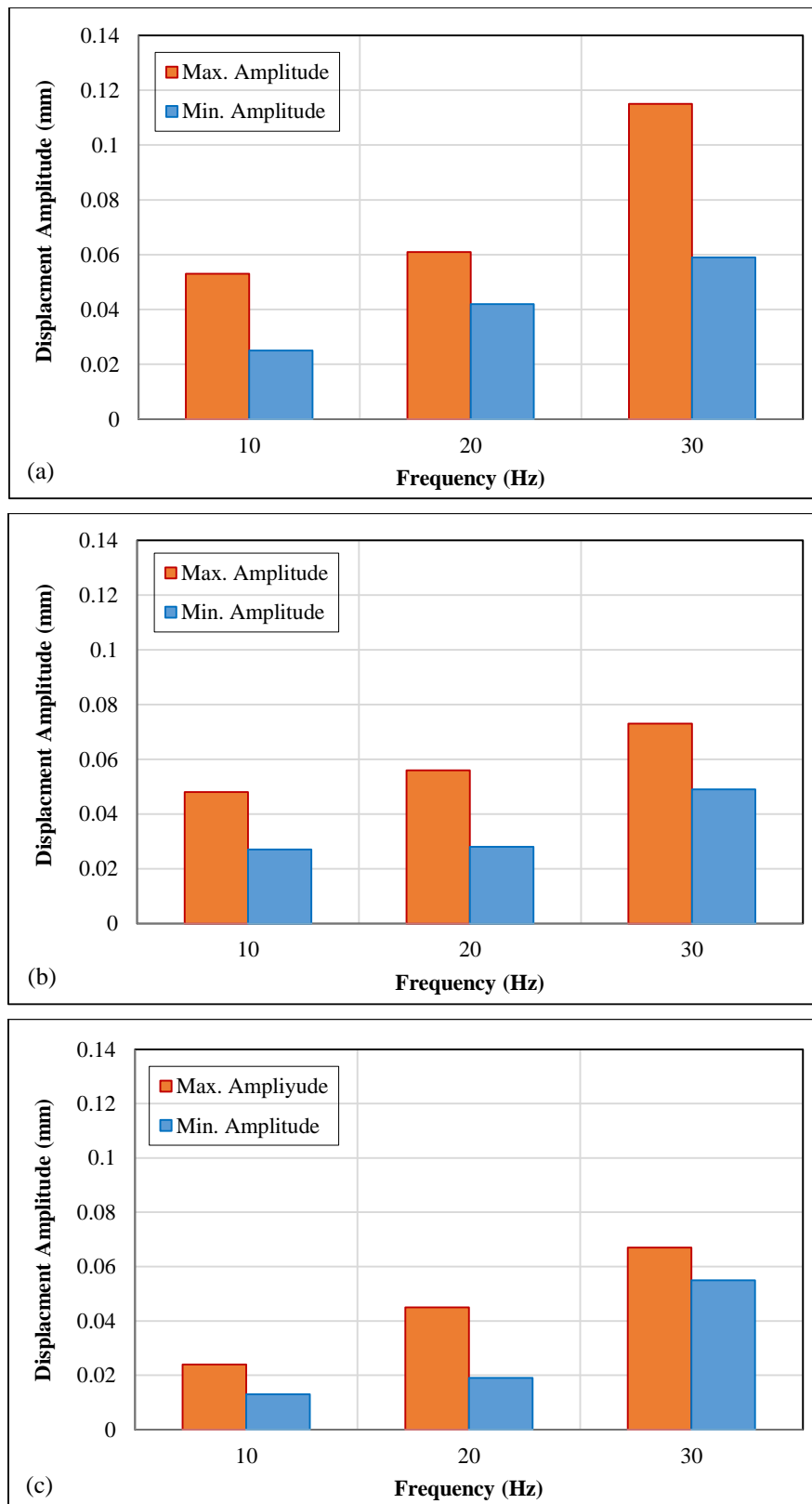


Figure 10. The displacement amplitude versus frequency for different spacing (s), (a) at S=B, (b) at S=2B, (c) at S=3B for soaked condition.

As a result, it can mention the general remarks as followings:

- The displacement amplitude at soaked state less than the displacement amplitude at dry state for all frequencies.
- The displacement amplitude, increase when frequency increase, regardless whether the state is wet or dry.
- As a logic, the maximum displacement amplitude reduced when the spacing between the two footings increase, in both soaked and dry specimen.

3.2. Velocity of Vibrations

Figures 11 and 12 show the relationship between the maximum and minimum velocity versus the frequency which are recorded for three spacing ($S=B$, $S=2B$, $S=3B$) on dry and soaked soil basis, it can be seen that maximum and minimum velocity diverge with increases of frequency, and converge with increased of spacing between the two footings for both state (dry and soaked).

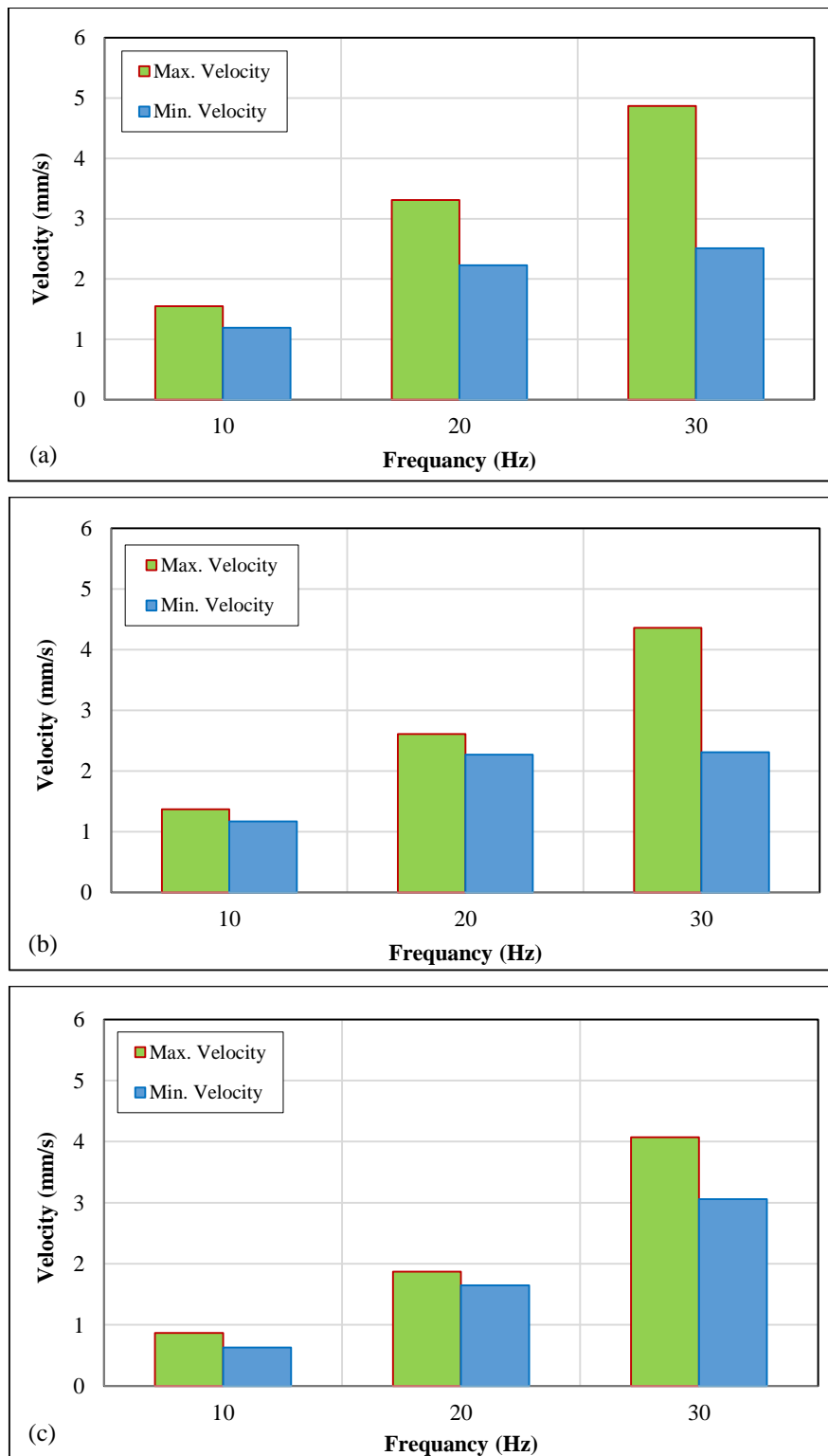


Figure 11. The velocity versus frequency for different spacing (s), (a) at $S=B$, (b) at $S=2B$, (c) at $S=3B$ for dry condition

The value of the velocity of the second footing increases with the increase the frequency of the first footing, on the other hand, the magnitude of the velocity decreased with increasing the spacing between the two footings, that's because the propagated of vibrations through the soil leads to a decrease in the energy of those vibrations and therefor decrease

the velocity of vibrations. In addition, the value of velocity at dry state is greater than its value at soaked state, because of the presence of water in soil (whom acting as a wave inhibitor), causing decreasing in energy of vibration and that led to decrease in velocity of vibration for the second footing

As a result, it can mention the general remarks as followings:

- The velocity of vibrations at dry state greater than the velocity of vibrations at soaking state for all frequencies.
- The velocity of vibrations, increase when frequency increase, regardless whether the state is wet or dry.
- The velocity of vibrations reduced when the spacing between the two footings increase, in both soaked and dry specimen.

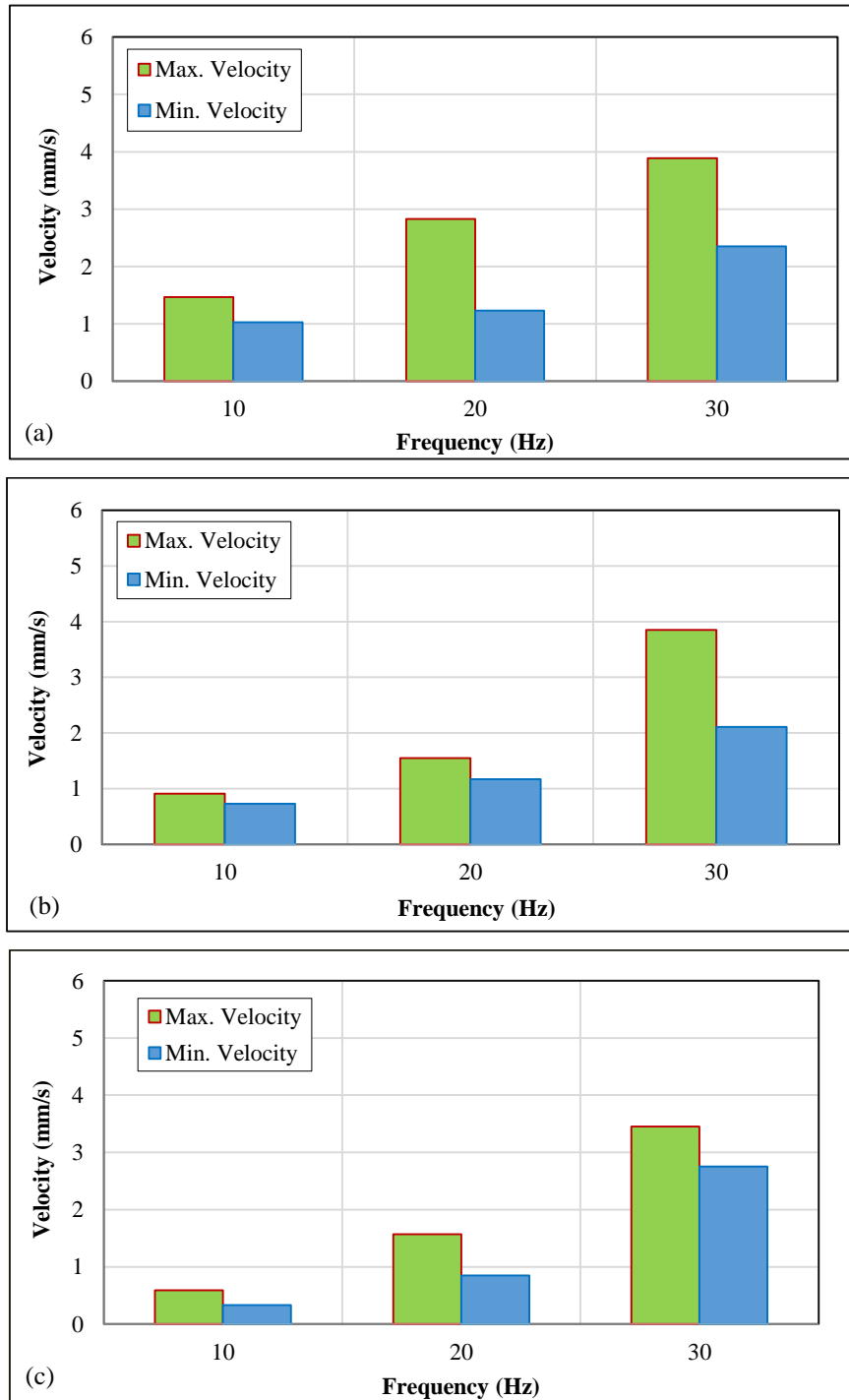


Figure 12. The velocity versus frequency for different spacing (s), (a) at S=B, (b) at S=2B, (c) at S=3B for soaked condition

3.3. The Acceleration

The maximum and minimum acceleration versus the frequency are shown in Figures 13 and 14, which are recorded for three spacing of (B) (S=B, S=2B, S=3B) for dry and soaked condition. the trend of behavior for maximum and

minimum acceleration is similar in dry and soaked condition, it can be seen the value of the acceleration increases with increase the frequency in both state (dry and soaking) and decreases with increase the spacing between the footings. The effects of increasing the spacing between the footings on the magnitude of acceleration are similar to the effect on displacement amplitude and velocity, increasing the spacing led to decreases the acceleration, that's because the propagated of vibrations through the soil leads to a decrease in the energy of those vibrations (as mention earlier) and therefor decrease the acceleration. In addition, we observe the magnitude of the acceleration at dry state is greater than its value at soaked state.

At dry state, the maximum and minimum acceleration shows increases in magnitude of the acceleration almost linearly when goes from 10 Hz to 20 Hz or 30 Hz, at spacing (1B). The same goes when spacing increase to (2B) and (3B). And here observed, the gap between the maximum and minimum increases when the frequency increase and the gap decreases when the spacing between the two footings increases. See Figure 13.

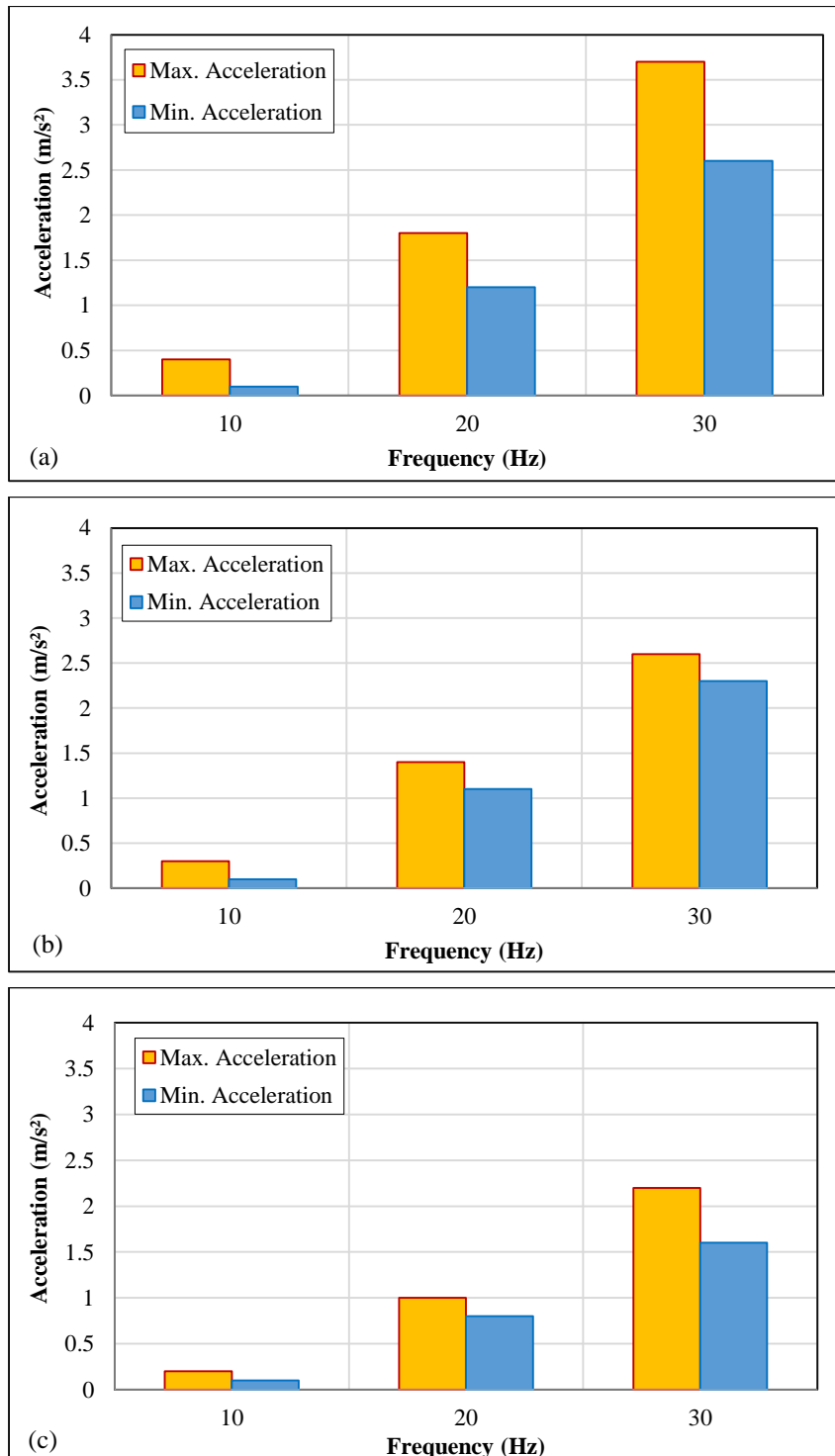


Figure 13. The Acceleration versus frequency for different spacing (s), (a) at S=B, (b) at S=2B, (c) at S=3B for dry condition

At soaking state, for the maximum and minimum acceleration, the rate of increase in acceleration just slightly when goes form 10 Hz to 20 Hz, but for 30 Hz is about higher than a double value, this applies to the magnitude of acceleration at a spacing of 1B, 2B, and 3B. The gap between the maximum and minimum acceleration increases when increasing the frequency and decreases with increases the spacing between the two footings. The values of the acceleration at soaked state for three frequencies (10, 20, 30) Hz at spacing of 1B, 2B, and 3B, recorded decreasing compared with their values at dry state because of the presence of water in soil whom acting as a wave inhibitor (as mentioned earlier), and it, increase when frequency increase, regardless whether the state is wet or dry. The acceleration reduced when the spacing between the two footings increase, in both soaked and dry specimen, see Figure 14.

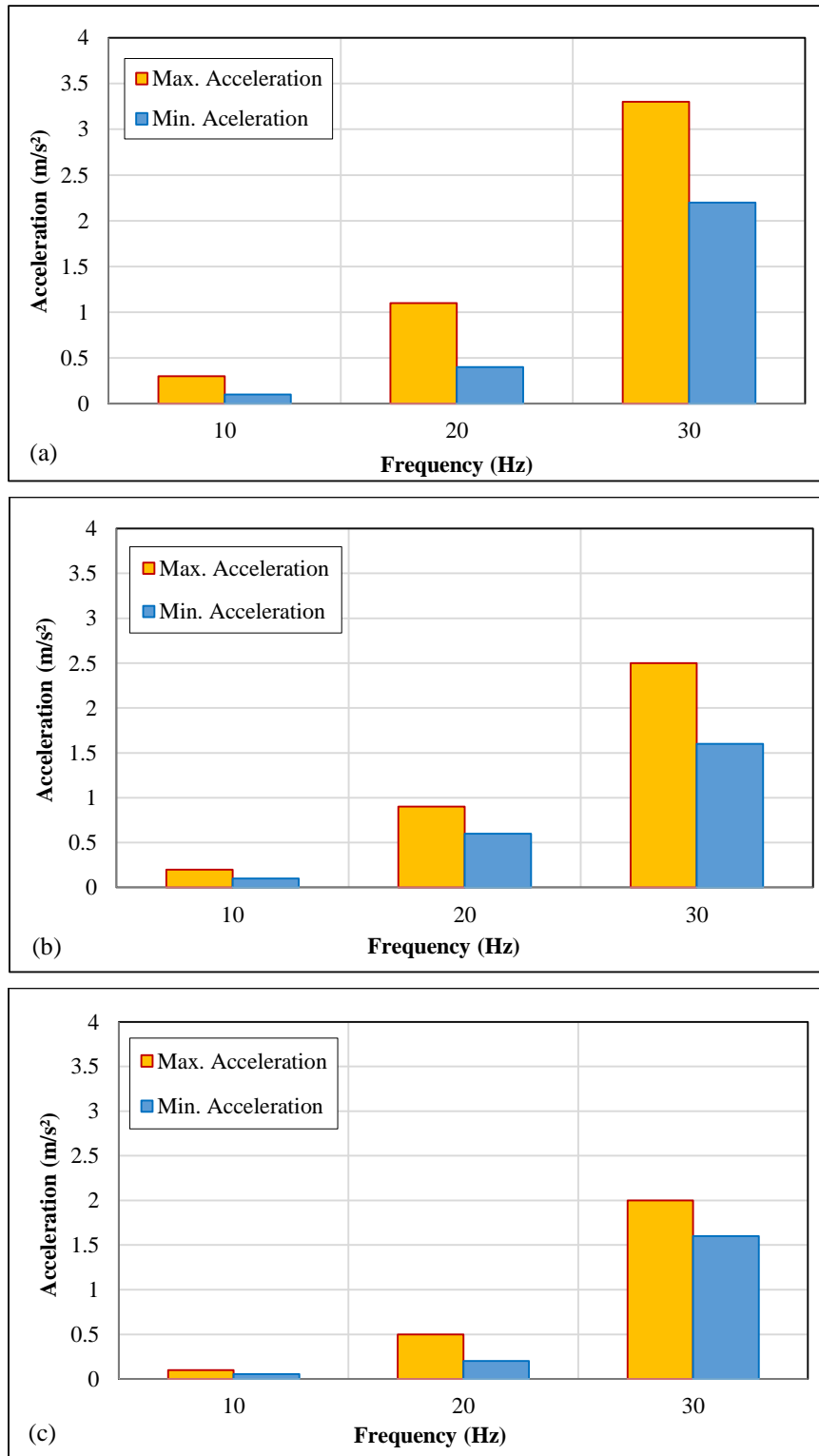


Figure 14. The Acceleration versus frequency for different spacing (s), (a) at S=B, (b) at S=2B, (c) at S=3B for soaking condition

4. Conclusions

4.1. Displacement Amplitude

- The magnitude of displacement amplitude of the foundation under effect of dynamic load comes from adjacent foundation (both foundations erected on gypseouse soil) increases with increase the operation frequency.
- The value of amplitude at dry state is greater than its value at soaked state.
- The displacement amplitude decrease with increases the spacing between the two footings. The reduction in value of displacement amplitude when the spacing between the two footings increased from 1B to 2B at frequency of 10Hz is 15.3 % at dry state, and 21% at soaking state. and when the spacing increased from 1B to 3B, the reduction is 44.6% and 52.9% at dry and soaking state respectively, at frequency of 20 Hz, the displacement amplitude decreased by (9.35% and 13.8%) at dry and soaking state respectively, when spacing increased from 1B to 2B and decreased by (13.3% and 22.4%) at dry and soaking respectively, when spacing increased from 1B to 3B. For the frequency of 30 Hz, the reduction is 15.7% at dry state and 36.5% at soaking state when the spacing increased from 1B to 2B, and when the spacing increased from 1B to 3B, the displacement amplitude decreased by (19% and 41.7%) at dry and soaking condition respectively.

4.2. Velocity of Vibrations

- The velocity of vibrations of foundation (loaded with static weight) nearby another foundation which subjected to dynamic load (both foundations erected on gypseouse soil) increases with the augments of operation frequency.
- The magnitude of the velocity at dry state is greater than its value at soaked state
- The value of the velocity decreases with the increase of spacing between the two footings. The reduction in value of velocity of vibrations when the spacing between the two footings increased from 1B to 2B at frequency of 10 Hz is 11.6 % at dry state, and 38% at soaking state. and when the spacing increased from 1B to 3B, the reduction is 43.8% and 59.8% at dry and soaking state respectively, at frequency of 20 Hz, the velocity of vibrations decreased by (21.3% and 45%) at dry and soaking state respectively, when spacing increased from 1B to 2B and decreased by (43% and 48.7%) at dry and soaking respectively, when spacing increased from 1B to 3B. For Frequency of 30 Hz, the reduction is 2% at dry state and 1% at soaking state when the spacing increased from 1B to 2B, and when the spacing increased from 1B to 3B, the velocity of vibrations decreased by (10% and 11.5%) at dry and soaking condition respectively.

4.3. Acceleration

- The acceleration of the foundation under effect of dynamic load comes from adjacent foundation on gypseous soil decreases with decreases the operation frequency.
- The value of the acceleration at soaking state is lower than its value at dry state.
- The value of the acceleration decreases with the increase of spacing between the two footings. The reduction in magnitude of acceleration when the spacing between the two footings increased from 1B to 2B at frequency of 10 Hz is 24 % at dry state, and 30% at soaking state. and when the spacing increased from 1B to 3B, the reduction is 51% and 59% at dry and soaking state respectively, at frequency of 20 Hz, the acceleration decreased by (22.2% and 18%) at dry and soaking state respectively, when spacing increased from 1B to 2B, and decreased by (45.1% and 54.5%) at dry and soaking respectively, when spacing increased from 1B to 3B. For Frequency of 30 Hz, the reduction is 29.7% at dry state and 24.2% at soaking state when the spacing increased from 1B to 2B, and when the spacing increased from 1B to 3B, the acceleration decreased by (32.4% and 27.3%) at dry and soaking condition respectively.

5. Acknowledgement

I would like to express deep gratitude to my supervisor Assist. Prof. Dr. Waad A. Zakaria for encouragement and significant suggestions, which improved this work. So, I'm greatly indebted to him. Appreciation and thanks are also extended to the all staff of Civil engineering department, and the staff of Soil Mechanics Laboratory, Diyala University, Iraq.

6. Conflicts of Interest

The authors declare no conflict of interest.

7. References

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