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# AN OBJECT ORIENTED DOMAIN ANALYSIS OF ECOSYSTEM MODELING

by

Ronald Lee Righter B. A., Elizabethtown College, 1972

Presented in Partial Fulfillment of the Requirements

for the Degree of

Master of Computer Science

The University of Montana

1993

Approved by

Chairman, Board of Examiners

MARC

Dean, Graduate School

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ProQuest LLC. 789 East Eisenhower Parkway P.O. Box 1346 Ann Arbor, MI 48106 - 1346 An Object-Oriented Domain Analysis of Ecosystem Modeling

Director: Ray Ford

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An object-oriented methodology is used as the basis for a domain analysis of computerbased ecosystem modeling. Requirements analysis of the application domain serves as the basis for domain analysis, which produces a hierarchy of classes, each characterized by a set of properties. The hypothesis that such an analysis could provide a useful set of knowledge about the domain is tested.

Requirements analysis of the application domain identifies several representations of spatial phenomena and a set of significant modeling processes. A particular representation of spatial phenomena is chosen as the basis for domain analysis. A classification of 23 key modeling processes identifies several types of operations: data acquisition, cartographic transformation, creation of higher level model structure from undifferentiated datasets, algebraic manipulation of models to derive new variables, interpolation and extrapolation of data values, process simulation, and enhancement of models for visual display and analysis.

Domain analysis produces a set of class specifications, a set of diagrams showing the relationships among classes, and a set of diagrams illustrating how each key modeling activity can be performed in the context of the class hierarchy. The hierarchy contains 169 classes, which are divided into twelve groups: root entities, spatial entities, ecosystem entities, ecosystem descriptor entities, classification entities, operations, data acquisition entities, descriptor entities, window entities, software entities, documentation entities, and human entities.

Diagrams are successfully completed, depicting the execution of 19 of the 23 key modeling processes. The hypothesis is considered to be successfully validated. Suggestions for future work are made.

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This thesis is an attempt to integrate the results of a year and a half journey through fields far removed from computer science. This document is an illustrated account of that journey; it is hoped that the material presented here will be useful in the construction of the Ecosystem Information System, and will be useful to ecosystem scientists who are receptive enough to listen to a visitor who wandered through their world for a time.

iii

## Table of Contents

•

Abstract	ii
Acknowledgements	
Table of Contents	
List of Tables	vii
List of Figures	viii
Chapter I. Problem Statement	1
A. Introduction	1
B. Ecosystem Research	1
C. Data and Software Management Problems	2
D. Ecosystem Information System	3
Chapter II. Hypothesis	4
A. Statement of Hypothesis	4
B. The Nature of Complex Systems	4
C. The Nature of System Decomposition	5
D. The Object Model	5
E. Requirements Analysis	8
F. Domain Analysis	9
G. The Object-Oriented Methodology in this Thesis	10
Chapter III. Requirements Analysis	11
A. Introduction	11

B. The Real World	, 11
C. Models of Reality	13
D. How Models are Used	16
E. Data Acquisition	18
1. Remotely Sensed Data	18
2. Ground Based Sampling	20
F. Model Transformations	21
1. Cartographic Transformations	<b>2</b> 1
2. Partitioning Transformations	23
3. Re-Partitioning Transformations	30
4. Deriving Missing Values	31
5. Deriving Missing Variables	32
6. EcoModel Assignment	34
8. Image Enhancement	35
G. Summary of Requirements Analysis	37
Chapter IV. Domain Analysis	38
A. Introduction	38
B. Class Relationships and Interfaces	38
1. Spatial Entities	39
2. Ecosystem Entities	47
3. Operations	54
C. Object Scenario Diagrams	57
D. Summary of Domain Analysis	62

Chapter V. Hypothesis Evaluation	64
Chapter VI. Conclusions	66
Appendix I. Class / Relationship Diagrams	67
Appendix II. Class Specifications	101
Appendix III. Scenarios - Object Diagrams	169

Bibliography	189

List of Tables

NumberNamePage number1.Scenario Completion Table58

# List of Figures

<u>Number</u>	Name	<u>Page number</u>
1.	Spatial Model Diagram 1	39
2.	Spatial Model Specification	40
3.	Spatial Entity Specification	41
4.	Spatial Model Diagram 2	41
5.	Point Model Specification	42
6.	Overlay Specification	42
7.	Overlay Diagram	43
8.	Categorical Overlay Specification	44
9.	Categorical Overlay Diagram	45
10.	Categorical Region Specification	46
11.	Categorical SubRegion Specification	46
12.	Categorical Point Specification	47
13.	Ecosystem Diagram	48
14.	Ecosystem Entity Specification	48
15.	Ecosystem Model Specification	48
16.	Ecosystem Model Diagram	49
17.	Topographic Model Specification	50
18.	<b>Regional Model Specification</b>	50
19.	Ecosystem Region Specification	50
20.	Cover Type Model Specification	51
21.	Cover Type Model Diagram	51
22.	Cover Type Region Specification	53
23.	Ecosystem Landunit Specification	53
24.	Cover Type Subregion Specification	53
25.	Operation Diagram	55
26.	Operation Specification	55
27.	Model Operation Specification	55
28.	Cluster Analysis Specification	56
29.	Spectral Classification Specification	56
30.	Cluster Analysis Scenario Diagram	<b>5</b> 9
31.	Spectral Classification Scenario Diagram	60

.

.

#### CHAPTER I

#### PROBLEM STATEMENT

#### Introduction

Researchers in the ecological sciences are developing techniques for modeling and analyzing ecosystems using digital computers. The increasing power of the computer allows researchers to work at larger spatial scales and finer spatial resolutions than was previously possible. Modeling efforts can also be carried out at varying time scales, ranging from static views of an ecosystem to century long modeling of some processes. Workers in this application domain must be well-versed in a number of disciplines. Primary among them are plant science, ecosystem ecology, community ecology, climatology, meteorology and hydrology. Understanding of fundamental geographic principles is indispensable, as many of the datasets that researchers work with are two-dimensional representations of phenomena that occur in three-dimensional space.

#### Ecosystem Research

Modeling and analysis of ecological phenomena can be carried out for more than one purpose. In some cases, researchers use ecosystem simulation models for hypothesis testing. In other cases, model outputs are used by land managers in their decision-making process. At the University of Montana, several labs are engaged in different aspects of ecosystem modeling. The Wildlife Spatial Analysis Lab (WSAL) at the Montana Cooperative Wildlife Research Unit is responsible for the Montana Gap Analysis project (MT-GAP). Gap Analysis is a nationwide effort by the U. S. Fish and Wildlife Service to idenfity and protect biodiversity using a computerized geographic information system (GIS). The Numerical Terradynamic Simulation Group (NTSG) in the School of Forestry is partially funded by NASA and does ecosystem simulation on spatial scales ranging from

1

the continental to a single watershed.

#### Data and Software Management Problems

The focus of this thesis will be the modeling requirements for the MT-GAP and NTSG projects. The research efforts in both labs overlap, and both projects use many of the same datasets and software tools. Additionally, both labs share many of the same problems. A major problem is the enormous size and number of datasets utilized in some projects. For example, a Thematic Mapper image from the Landsat satellite will typically require 350 to 400 MB of storage. The MT-GAP project requires 31 of these images to cover the state of Montana. The size and number of these datasets presents a formidable data management and processing problem. Researchers must often devise *ad hoc* and sometimes unsatisfactory solutions to these problems.

Many different software tools - both commercial off the shelf (COTS) and custommade - are used in ecosystem modeling. Two particular types of software package have proven especially useful. Geographic Information Systems (GIS) facilitate the acquisition, management, analysis and display of data relating to phenomena located in geographic space. Image Processing (IP) systems are used to analyze digital data that is collected from remote-sensing devices such as satellites and aircraft. Commercial products of both types are used extensively in both WSAL and NTSG. These products, however, usually are developed for fairly large markets and thus emphasize functionality that is in fairly widespread demand. Workers who are doing cutting edge research and/or dealing with unique problems may find that their software and data management needs often exceed the capacity of commercially-available software. For this reason, in-house software and data management tools are widely used for many modeling and analytical problems. Construction of these software tools often requires considerable investment of time from ecological researchers, and therefore is a distraction from the scientific work they might

2

rather be doing. Additionally, these tools sometimes are of an *ad hoc* nature. That is, they are sometimes built as limited solutions to a particular problem, and therefore may not be applicable in a broader context.

#### **Ecosystem Information System**

The Ecosystem Information System (EIS) was conceived as a remedy to many of these data management and processing problems (Ford92). EIS will allow researchers working in a distributed environment (i.e., in physically separate labs) to share data and software. EIS will provide a researcher with a mechanism to browse a collection of datasets and software (both COTS and in-house), and obtain the information necessary to use the data and software in an appropriate manner. A critical step in the development of EIS is construction of a hierarchical description of the entities (software and data) available in the participating labs. Construction of this hierarchy is a first step in the development of any non-trivial, ecosystem database. The EIS hierarchy will therefore serve as a guide for researchers who need to find what datasets and software tools are available for their work. It will also provide a context for further software development by facilitating reuse of existing software designs and implementations. The construction of this hierarchy is the primary objective of this thesis.

#### CHAPTER II

#### **HYPOTHESIS**

#### Statement of Hypothesis

Our hypothesis is that a domain analysis model can effectively describe the entities and relationships between entities that are found in this application domain. The technical basis for our modeling work is an object-oriented modeling methodology. In this chapter we will describe object-orientation and domain analysis; we will also specify the criteria by which we will validate our hypothesis.

#### The Nature of Complex Systems

In what is one of the primary references in the object-oriented software development literature, Booch describes the nature of complex systems that include software components (Booch92). He describes industrial-strength software as software for which "it is intensely difficult, if not impossible, for the individual developer to comprehend all the subtleties of design." (Booch92, pp. 13). This is true of software systems designed for the modeling and analysis of geographical data. Booch characterizes a complex system as one that has a number of attributes, such as the following.

1) A complex system is in the form of a hierarchy in which a particular subsystem is itself composed of subsystems.

2) Hierarchic systems are usually composed of only a few different kinds of subsystems that are organized in various patterns.

3) Relationships among separate components are weaker than relationships among the internal parts of a particular component.

From these attributes, Booch derives a canonical form for a complex system. Such a system must be viewed from two perspectives, each of which is formalized as a hierarchy.

4

The *part of* hierarchy is based on decomposing the system into parts. A component in the *part of* hierarchy is made of sub-components which are found below it in the hierarchy. The *kind of* hierarchy is based upon generalization of properties. A component in this hierarchy has properties common to all components below it in the hierarchy. Booch refers to these hierarchies as object structure and class structure, respectively.

#### The Nature of System Decomposition

A key notion in the design of software is that of *decomposition*. A complex software problem can be broken into smaller pieces, each of which can be dealt with independently. Booch describes two approaches to decomposition -- algorithmic and object-oriented. *Algorithmic* decomposition divides a system into units, each of which represents a major step in a process. Each of these units can also be decomposed algorithmically. A more recent approach is *object-oriented* decomposition. Here each unit represents a key abstraction in the application domain. In this approach, the world is viewed as a collection of semi-autonomous entities that interact to exhibit higher level behaviors. Booch says that although both approaches are valuable, object-oriented systems tend to be smaller, more resilient, and less risky to develop, because their development can more easily be implemented incrementally.

#### The Object Model

There are four essential elements for the object model (Booch92, pp. 39-40) The first is *abstraction*, which "denotes the essential characteristics of an object that distinguish it from all other kinds of objects and thus provide crisply defined conceptual boundaries, relative to the perspective of the viewer." Abstraction provides information about what an object does while it conceals the means by which the object performs operations. The abstraction of an object provides an interface for the object, and identifies its essential behavior. The behavior of an object includes operations it performs on other objects, as

well as operations that other objects perform upon it. An object that uses the resources of another object is that object's *client*. An object's *protocol* is the set of operations that its clients may perform upon it.

The second element of the object model is *encapsulation*, defined as "the process of hiding all the details of an object that do not contribute to its essential characteristics." (Booch92, pp. 46) Abstraction and encapsulation are complementary concepts. Encapsulation, also known as information hiding, prevents clients from seeing the inside view or implementation of an object.

*Modularity* is "the property of a system that has been decomposed into a set of cohesive and loosely coupled modules." (Booch92, pp. 52) A module is a higher level abstraction than a class. It is a construct used in system design and implementation, and serves as a way to manage source code. *Coupling* is the measure of the strength of association between modules or classes. A strongly coupled system is harder to understand than one with weaker coupling. *Cohesiveness* measures the degree of connectivity between the elements of a module or class.

The last of the major concepts of the object model is *hierarchy*, which is "a ranking or ordering of abstractions." (Booch92, pp. 54)

Another attribute of object-oriented models is *persistence*, described by Booch as "the property of an object through which its existence transcends time (i.e., the object continues to exist after its creator ceases to exist) and/or space (i.e., the object's location moves from the address space in which it was created)" (Booch92, pp. 70). Though some advocates of object-oriented design consider persistence as an essential aspect of objectoriented systems, Booch considers it a minor aspect of the object model. In this application domain, persistence through time is obviously important. Virtually all software tools used by researchers (both COTS and custom-made) provide some mechanism for storing objects permanently. This mechanism may be a simple "write to disk" or may involve recording entities in a database management system. For software that functions in a distributed environment, persistence in space is critical as well.

Booch next characterizes an *object*, which is a concept fundamental to the objectoriented methodology, as an entity with state, behavior and identity. The concept of state embraces all the properties of an object where a property is a distinctive feature or quality that helps to make the object unique. Properties have a value, which may be a simple quantity or a reference to another object. An object's behavior determines how its state changes in response to the actions of other objects. Behavior also controls the way in which an object acts upon other objects. Identity is the property of an object that makes it unique. A set of objects that share a common structure and a common behavior is called a *class*. An object is an instance of a class.

In Booch's view there are two kinds of relationships among objects -- using and containing. In using relationships, an object uses another object. Objects involved in this kind of relationship play one of three roles. Actors use other objects, but are never themselves used. Servers are used by other objects, but never themselves use other objects. Finally, an agent is an object that can be both an actor and a server. In containing relationships, one object contains other objects.

Relationships among classes are more involved. Booch describes three basic kinds. Generalization, or kind of, relationships indicate sharing of properties. Aggregation, or part of, relationships indicate structural relationships. Finally, a semantic connection between otherwise unrelated classes is an association. Booch's methodology provides four relationships among classes. Inheritance relationships are the most powerful and can be used to express generalization, i.e., that a class shares the structure or behavior defined in one or more other classes, called superclasses. An inheriting class is called a subclass. Inheritance is the relationship used to build the kind of hierarchy discussed earlier. Using relationships among classes can be of two types. A class can use another class in its *interface* or in its *implementation*. Instantiation relationships indicate that an instance of a class involved in this relationship cannot be created without creating instances of the other class in the relationship. Finally, *metaclass* relationships allow classes to be seen as objects. A metaclass is a class whose instances are themselves classes.

Booch states that no single diagram or model can capture all the details of a system. His methodology requires construction of two kinds of models - logical and physical. The *logical* model depicts classes, objects and the relationships between them. The *physical* model depicts higher level subdivision of the system into modules and the allocation of processes to processors, then processors to competing demands. Logical models are built first, and then used as a basis for construction of the physical models. In this work, we will build only logical models, according to the two stages of the Booch methodology as discussed in White (White93) -- requirements analysis and domain analysis.

#### **Requirements** Analysis

Requirements analysis is essentially the process of determining what the customer expects from the system that is being built. Among the products are a clear definition of a system's reason for being and a statement of overall goals. This stage comprises a contract between developer and user, recognizing that the contract will evolve over time. In some design methodologies, the only formal product of this stage is a simple statement of the primary functions of the system. In our modeling effort, however, system requirements will be described in more detail, with summaries of many of the kinds of modeling and analysis activities the system must support.

#### Domain Analysis

*Domain* analysis is the process of building an object-oriented model of the portions of the real-world enterprise that are relevant to the system being designed. White says it is through this process that developers gain the detailed knowledge of the domain needed to have the system carry out its required functions. Domain analysis identifies all major objects in the domain, including state components and major operations. The result is a central model containing all system semantics. White says this process focuses on "resolving that bewildering set of aliases, contradictory requirements, obscure policy, and varying styles of explanation and communication into a ... structure that will map directly to final implementation." (White93, pp. 7) Our domain analysis will produce three sets of deliverables:

1) class-relationship diagrams, which identify the key classes and relationships among classes in the domain;

2) class specifications, which contain all semantic definitions of the classes, attributes and key operations; and

3) object-scenario diagrams, which illustrate how the objects will interact to carry out key system functions.

White suggests the following sequence for domain analysis. First define classes, then identify major relationships between classes and objects. Next, identify key attributes. At this point, identify properties shared among classes to produce a class hierarchy, then identify operations. Finally, validate the model by appropriate means, and repeat the steps above to refine the model.

We will use the object-scenario diagrams produced by domain analysis to evaluate our model with respect to our hypothesis. That is, if we can successfully build an objectscenario diagram for each scenario identified during requirements analysis, we will have validated our hypothesis.

#### The Object-Oriented Methodology in this Thesis

The object-oriented methodology can be employed in several ways for this analysis. We will discuss two distinct approaches and then present a third approach, which will serve as the basis for our work. In the first approach, we can examine the collection of spatial datasets, software and other tools used by ecosystem modelers, then construct an object model depicting the nature of these objects and the relationships among them. In this approach we make no reference to the ecosystem. Our work falls more strictly under the umbrella of conventional software modeling and design. Our model will be limited because it will not capture much of the semantics of the application domain.

In the second approach we apply the object-oriented methodology to the ecosystem itself. In this case we view the ecosystem as a collection of interrelated and interacting objects (i.e., as a complex system). In this case our work falls into the domain of ecosystem modeling. This approach is being pursued by a number of ecosystem researchers (Silvert93, Raper93, Bennett93, and Klanika93). It is not our intention to build an object-oriented model of an ecosystem. Instead we will model the datasets, software and tools used in ecosystem modeling, while recognizing the ecosystem as the focus of concern.

Our approach will be as follows. We will view the ecosystem as a complex system (Booch89). The system is composed of interrelated objects. Ecosystem scientists study the objects and relationships comprising this system. As part of their research activities, scientists build models of such systems. They acquire data to serve as input and validation for their models by sampling the ecosystem. Modeling transformations, implemented in software, are used to derive new models from existing models. Scientists document their research efforts and rely on documentation of research by others.

#### CHAPTER III

#### **REQUIREMENTS ANALYSIS**

#### Introduction

Requirements analysis will provide a detailed summary of the key entities and processing operations carried out in the domain of ecosystem modeling. This material will be used as the basis for a model of the application domain.

#### The Real World

Ecosystem researchers study phenomena, both natural and human. Phenomena can be of two types, *continuous* and *discrete*. Continuous phenomena have a numerical value at every point of the earth's surface. Examples are precipitation and elevation. We assume that discrete phenomenon are bounded in three-dimensional space. Examples are roads, rivers, lakes and buildings. Phenomena that have a non-numerical value at every point on the surface fall into a gray area. In many cases, these phenomena are the product of human activity, e.g. land ownership, land use and political territory. In other cases they can only be measured after expert analysis of data, e.g. vegetation community type.

We measure phenomena at four levels, as summarized in (Muehrcke78). Nominal is the most primitive and is used strictly for classification. We may subdivide a set of data into areas of equal vegetation type, where each type is represented by a unique numerical value. Ordinal measurements indicate a ranking on a continuum, with each group having a value. Interval and ratio measurements indicate magnitude. In the case of an interval measure, like temperature on the Celsius or Fahrenheit scales, the numbers used don't have an absolute value. Hence, the value zero in an interval measure has no real world significance. Ratio is similar to interval in that the value indicates magnitude on a scale. However, the zero is a meaningful value. Precipitation is a ratio measure. Nominal measurements are sometimes referred to as qualitative, while ordinal, interval and ratio measurements are known as quantitative. We use the term *categorical* in place of nominal, and the term *numerical* in place of interval and ratio. We do not treat the ordinal level of measurement in our work.

Phenomena in the real world are associated with entities or structures. These entities are sometimes identifiable features of the natural and human landscape. In other cases they are the product of analysis and modeling carried out by experts in a particular application domain. Burrough says that "all geographical data can be reduced to three basic topological concepts - the point, the line and the area. Every geographical phenomenon can in principle be represented by a point, line or area plus a label saying what it is." (Burrough86, pp. 13) Unwin (Unwin81) discusses point, line and area entities, and also discusses the surface. A surface is a collection of points and a scalar field characterizes the surface. A scalar field is a contiguous set of positions, each of which has an associated scalar value, characterized by a magnitude measure. Thus, magnitude values represent a function of scalar field position. Unwin describes an example of a contour map of a mountain, where altitude is a function of  $\langle x, y \rangle$  position. He says two critical assumptions have already been made. "The first is that of continuity, that is a z value exists (or can be imagined to exist) everywhere on the surface, and that there are no sharp discontinuities.... Second, it is assumed that the field is single-valued, that is only one value of z is present at each location." (Unwin81, pp. 154). Based on these assumptions, a scalar field can be used to approximate a surface corresponding to the surface of the earth. The two conditions above are not always perfectly met, especially in mountainous areas, but this shortcoming is often overlooked for modeling purposes. Using these assumptions allows other continuous phenomena to be treated as surfaces of some type.

We can find structure in the real world by partitioning areas into subunits. We

recognize two kinds of partitioning - spatial and value. We partition an area spatially by dividing it into spatially contiguous areas. In other words, we can identify spatially contiguous sets of points as sub-areas, each with a particular geographic extent. This kind of partitioning is often used to isolate a small area for focused analysis or to provide an organizational framework for archiving and management of large spatial models. Value partitioning is used to find a more complex kind of structure. We place in one partition all areas that are of common value for a particular phenomenon. Generally, researchers choose one phenomenon as the basis for structure. They then develop criteria and a methodology for evaluating the chosen phenomenon. The result of evaluation yields a surface broken into value partitions. In somewhat more formal terms, spatial partitioning divides a set of points into spatially contiguous subsets. Value partitioning is carried out by isolating one phenomenon, and partitioning a set of points into possibly disjoint subsets that are equivalence classes with respect to the value of that phenomenon.

#### Models of Reality

Scientists build models of reality to facilitate their research. We define a model as an abstract representation of reality. Models can be of two kinds - spatial and temporal. Spatial models are static views of the real world; that is, they either describe the state of the ecosystem at a particular instant, or they summarize state values over a particular time interval. Spatial models represent phenomena in n dimensions. We limit ourselves to two-dimensional spatial models. Temporal models contain a logic that simulates system activity and produces an ordered set of spatial models called a time series. A particular time series has a temporal scale and resolution. Temporal scale is the time period represented by the series, whereas temporal resolution, also called time step, indicates the time interval between the spatial models comprising the series.

Geographic information systems and image processing systems utilize two differ-

ent characterizations of spatial data -- *raster* and *vector*. The raster model assumes a regular grid that divides a surface into cells of uniform size, sometimes called pixels, each of which represents a discrete area of the surface. Each cell is referenced by unique  $\langle x, y \rangle$ coordinates. Raster cells are spatially contiguous, and in most applications are of a standard square shape. Burrough (Burrough86) summarizes the advantages and disadvantages of the raster model. He says the data structure is simple, permitting easy simulation and analysis operations. However, this model requires that large amounts of data be stored, and will lose information about the phenomenon if the resolution of the phenomenon is smaller than the raster cell size. Any model of spatial data must be able to store topological information, that is, a description of the spatial relationships between objects. Topological information is implicit in the raster model at the level of the individual cell, in the sense that neighbors are easily identified by simple functions on  $\langle x, y \rangle$  coordinates. However, for more abstract raster objects, such as groups of cells, topological information must be explicitly managed.

The vector model is based on three kinds of entities. A *node* represents point entities, an *arc* represents a line entity defined by start and end nodes and a *polygon* represents an area defined by a closed collection of arcs. The vector model gives what is sometimes called a continuous representation of reality. This means that the spatial location of nodes, arcs and polygons corresponds to their location in the real world to a certain level of precision. Each object (node, arc, polygon) on a vector layer is given a unique identifier which serves as the primary key into a relational table. Burrough (Burrough86) summarizes the advantages and disadvantages of the vector model as follows. The vector model gives a truer representation of real world entities and for sparse phenomenon provides a much more compact data structure than the raster model. However, the data structures required by vector models are complex, making many important modeling and analysis operations very difficult to implement.

The vector model can store topological information on the objects that comprise a surface. Aronoff (Aronoff89) describes the ARC-NODE model in which topological data is store for all arcs, nodes and polygons on a vector layer. Polygon topology defines a polygon in terms of the arcs by which it is bounded. Node topology defines a node in terms of the arcs in which the node is either a start or end point. Finally, arc topology identifies the start and end nodes for each arc, as well as the polygons to the left and right of the arc. While we recognize the importance of these traditional views of spatial data, we seek a representation that allows us to ignore the distinction between vector and raster.

The spatial representation that we use in this work is that of a model of the geographic database (Burrough86). Although the term geographic database implies that this model relates to data in a spatial modeling/analysis system, we can apply this model to entities and phenomena in the real world. Burrough's model provides a means of bridging the gap between the real world and the software systems used in the application domain. Implicit in Burrough's model is a view of the earth's surface as an infinite set of points, each of which has a set of attributes. Each attribute represents a phenomenon. Attributes representing continuous phenomena are present at every point on the surface. Attributes representing discrete phenomena are present only where those phenomena occur. In other words, an attribute representing streams is present only at points that lie in the stream. We will call this representation of reality the *point model*.

Burrough's model also uses a structure called an *overlay*. An overlay is a scalar field which represents the value of exactly one attribute for a particular area. There is a unique overlay for every attribute for a given area. If we examine a particular overlay, we find a structure that Burrough calls a *region*. A region is a set of  $\langle x,y \rangle$  positions that share a value for a particular attribute. A region is composed of one or more spatially contig-

uous areas. The smallest region is one  $\langle x, y \rangle$  position. The region is therefore an equivalence class with respect to one attribute.

In the work here we refine Burrough's model in several ways. Firstly, we will describe two kinds of overlays -- *numerical overlays* hold values on the numerical measurement level and *categorical overlays* hold values at the categorical level. Secondly, we note that Burrough does not treat the spatially contiguous areas that comprise a region as meaningful entities. However, these entities are spatially unique objects and should be treated as semantically meaningful. We call these entities subregions and recognize two kinds. Linear subregions are one-dimensional and are composed of at least two points, while areal subregions are two-dimensional and may be as small as one point. We realize that geometrically a point is a subspace of area "zero" in a larger two-dimensional space. In modeling terms, each point is assumed to have a non-zero area corresponding to its spatial resolution. Thus we treat the point as similar to the cell in the traditional raster model. We define a four-tiered overlay structure. The foundational structure is the point, the second level of structure is provided by the subregion, the third tier by the region and the top level by the overlay.

#### How Models are Used

We discuss here a subset of the key modeling activities carried out by MT-GAP and NTSG projects. In subsequent sections, we will expand on these descriptions and describe other modeling activities.

Gap analysis (Scott93) is intended to provide a more proactive approach to biodiversity protection than has been available in the past. The process relies on spatial models of spectral reflectance, topography, land ownership, land use and other phenomena. These foundational models are analyzed to predict land cover types and wildlife distributions. These higher level models are used to identify geographical areas that are important to the survival and well being of various species and communities. A vegetation model is fundamental to biodiversity assessment, because the vegetation at a site reflects many physical and biological factors that are significant to plant and animal species.

The MT-GAP project uses many traditional image processing and GIS analysis techniques, as well as modeling and analytical methods developed by the project staff. (Ma 93) discuss modeling activities being used on the Montana project to map existing vegetation and land cover. Remotely-sensed reflectance data recorded by Landsat TM scanner is used to identify units of land with similar spectral pattern. Land units smaller than five acres (i.e., the minimum map unit) are removed by absorbing them into adjacent land units. Topography is modeled for the remaining units. A subset of these units are sampled in the field to determine plant cover type and is used to develop a characterization for each cover type, called a signature. The signature is used to label the cover type of each land unit in the model by cover type.

The Numerical Terradynamic Simulation Group studies ecosystem processes at watershed and larger scales by using a suite of temporal modeling tools. We limit our discussion to the Regional Hydro-Ecological Simulation System (RHESSys) which has been developed by NTSG (Nemani92). RHESSys is comprised of submodels called Forest-BGC, Basin, MtClim and TopModel. Forest-BGC is a process model that simulates the cycling of carbon, water and nitrogen through forest ecosystems. The model requires topographic and soil parameters, along with an estimate of vegetation canopy density. The simulation is driven by climate data that is extrapolated from a weather station to the study site. Seven state variables are modeled on a daily time step: evaporation, transpiration, snowpack, soil water, stream discharge, photosynthesis and maintenance respiration. The remaining state variables are updated once a year: growth and decomposition respiration, nitrogen loss, available carbon and nitrogen, and carbon and nitrogen in leaves, stems,

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roots, soil and litter. A topographic landunit called a hillslope is used as the simulation unit, reflecting the strong relationship between the hillslope and forest cover patterns in mountainous regions. The submodel, Basin, is used to partition the study area into hillslopes, so that each hillslope is partitioned into areas of similar soil-water dynamics. MtClim is used to extrapolate climate data, generally on a daily time interval for the period for which the simulation is to run. TopModel (Bevan79) simulates water flow in moderate to steep topography.

The execution of a RHESSys simulation proceeds as follows. Basin partitions the study area into topographically-defined simulation units. MtClim provides climate data for each simulation unit. Next, Forest-BGC is run on each simulation unit and results are integrated across the hillslope. TopModel provides a robust model of hydrology, providing estimates of stream discharge in terms of timing and quantity, and of soil moisture patterns. These patterns are especially important in determining rates of evapotranspiration and photosynthesis.

#### Data Acquisition

#### Remotely Sensed Data

Before information about the real world can be used for modeling and analytical purposes, some method(s) for sampling the real world must be devised. A great deal of the data used in ecosystem modeling is sampled remotely -- i.e., from high above the earth -- and over large areas virtually simultaneously. Two primary vehicles for remote sensing are utilized today -- aircraft and satellites. The use of aerial photography from aircraft mounted cameras has long been a source of data about the earth, used to generate maps and other representations of the earth's surface. The use of satellite imagery is newer, but rapidly growing in importance in a wide range of applications.

Two of the products from aerial photography that are used in the MT-GAP project

and NTSG research will be discussed here. First is the *digital elevation model* (DEM) which describes the elevation of points in a regular grid on the earth's surface. A similar product is called a *digital terrain model* (DTM). Burrough (Burrough86) uses the term digital elevation model in a broader context to refer to any digital representation of the elevation of the earth's surface. He uses the term *altitude matrix* for the particular kind of elevation representation that is commonly available as an actual DEM or DTM dataset. The altitude matrix has an elevation value at each intersection point of a regular grid. The U. S. Geological Survey describes three methods used in the collection of elevation data for the agency 7.5 minute DEM product (USGS86).

1) Elevation data is interpolated from digital representations of hypsography (contour lines).

2) A stereo-pair of aerial photographs are processed using a method called terrain profiling, and the resulting data is interpolated to a regular grid.

3) The Gestalt Photo Mapper is used to examine a stereo-pair of aerial photographs and sample the terrain on a regular grid.

The second product of aerial photography discussed here is a *hydrography* overlay. Hydrographic features are bodies of water, such as lakes, springs, marshes, ponds, streams, and wells. A map generated from an aerial photograph is used as source material for the digital representation of hydrographic features. The hydrography overlay is formed by digitizing the map, either manually or automatically.

Satellite based monitoring of the earth has been carried out for several decades. The LANDSAT series of satellites has provided remote sensing capabilities by carrying scanners that record electromagnetic radiation reflected off the earth's surface at various wavelengths (ERDAS91, Lillesand79). The term *scanner* is typically used to describe an entire data acquisition system. A satellite may carry more than one scanner. Each scanner carries a sensor, which records radiated energy and converts it to a signal suitable for further use. Each sensor contains a number of detectors. The current generation of LAND-SAT satellites carries the Thematic Mapper (TM) scanner system, which records radiation from seven bands of the electromagnetic spectrum. Three bands, the lowest in terms of wavelength recorded, are in the visible spectrum. One band is in the near infrared, which lies just beyond visible red. Another two bands lie in the mid infrared range, and the final band is in the thermal infrared. The width in microns of each band is called the *spectral* resolution. A sensor's spatial resolution is the size of the smallest object detectable by the sensor. The spatial resolution of TM data is 30 meters for every band, except band 6, which has a resolution of 120 meters. The data captured by TM scanners is initially processed by Earth Observation Satellite Corp. (EOSAT). The result is a dataset with all bands converted to a 30 meter resolution, called a *satellite scene*. Individual scenes vary in size. The Missoula scene is a 7000 by 7000 grid of cells representing approximately 13 million acres. The temporal resolution of TM data (that is, the time interval between separate recordings of a particular area) is sixteen days. A sensor also has a radiometric *resolution* which indicates the number of values the signal transmitted to the earth can have. The TM sensor has a radiometric resolution of 256, i.e., the data values are encoded in 8 bits.

#### Ground Based Sampling

Ground-based sampling of data has been used in the MT-GAP project and in ecosystem simulation by NTSG to measure climatic phenomena. Although climate is a continuous phenomenon, current technology is limited in remote sensing of this data. Therefore, ground observations are necessary. For climate modeling, researchers at NTSG generally use data collected by the National Weather Service at primary and secondary meteorological stations, and archived at the National Climate Data Center, by the National Oceanic and Atmospheric Administration (NOAA) is useful for climate modeling. Interpolation and extrapolation of this data are the subject of considerable modeling activity and will be discussed later.

Ground-based sampling also provides data that can be used to complement analyses that are based on remotely-sensed data. This practice, called *ground truthing*, provides an empirical check on the methods used by modelers. Field workers examine plots and record observations appropriate to the purpose of a particular study. In some cases a standard *sampling system* may be used. For example, MT-GAP utilized the Ecodata sampling system developed by the U.S. Forest Service. The Ecodata system provides over twenty field forms for recording particular observations and attributes of a site.

#### Model Transformations

#### Cartographic Transformations

Robinson, et al., (Robinson53), define *cartography* in the broad sense as work in which the use of maps is of fundamental importance. The term map must be used with care because researchers use hard copy maps only part of the time. Most of the time they work with digital representations of maps using the data models discussed in the previous section. Robinson, et al., (Robinson53), describe five conceptions of cartography, only one of which -- the geometric focus -- is important in this discussion. The aim of cartography in this view is the creation of cartographic models of reality that are used for measurement and analysis of phenomenon. The emphasis here is on accuracy of measurement. This of course is the primary concern of scientists studying earth resources and the natural environment.

The process of representing the three-dimensional surface of the earth on a twodimensional hardcopy map or a flat computer monitor requires the use of a *map projection*. The act of projection involves the application of a function to the three-dimensional data in order to render it in two-dimensions. There are many such transformation functions. The spatial location of real-world entities is given in the *geographic coordinate system* using latitude and longitude. At this stage there is no projection system involved. After projection into two-dimensions, a *rectangular coordinate system* is used for referencing spatial locations. Some accuracy is always lost in a projection transformation. The fidelity of geographic data can be analyzed in four ways -- representation of angles, areas, distances and directions. Each projection system preserves fidelity in some of these areas better than others. The analyst must decide which projection system will best suit the needs of the analysis, based on the nature of the data, the characteristics of the study area and the purpose of the analysis. For a given study, one projection system is usually chosen as the standard. All input overlays (raster and vector) are converted to the same projection system. During the conversion from one projection to another, the analyst must provide parameters that will guide the transformation process.

Overlays representing the same geographic area must also be referenced to the same coordinate system. The same geographic location will thus be represented by the same map coordinates in both overlays. *Registration* is the procedure used to accomplish this goal. In absolute registration, different overlays are registered to a common coordinate system. In relative registration, one overlay is used as a base, or master, to which the other overlays, called slaves, are registered. The registration process typically takes three steps. First, a set of features (generally point entities) that can be identified on all the overlays are isolated. Second, the coordinates of these points are recorded. Finally, a function is generated to transform coordinates on each slave into the appropriate coordinates on the master overlay.

When performing projection transformations or registration on overlays with a regular point distribution, it is often necessary to *resample* the surface. A resampling

algorithm generates a new value for a particular point by performing a calculation on the values of its neighbors. The product of resampling is an overlay with newly calculated values for all points. Resampling is often necessary after projection or registration because the functions that transform the surface distort the regular grid of points. There are a number of possible resampling algorithms, e.g., nearest neighbor, bilinear interpolation and cubic convolution. Resampling may also be used to change the spatial resolution of the points on an overlay to match the resolution of another overlay.

#### Partitioning Transformations

#### Introduction

Ecosystem modelers seek out a basic structure to use as the focus of modeling activities. The structure must be semantically meaningful - that is, it must correspond to a real world entity. Primitive overlay objects (i.e., points) may represent objects of special significance to modelers (e.g., wildlife sightings, spring locations). Usually however, overlay points are arbitrarily chosen as part of a grid of points to represent an area, and do not have this semantic meaning to ecosystem modelers. The analyst must aggregate these points into semantically meaningful units. Two methods of doing this are used by MT-GAP and NTSG : *classification* based on spectral value, which generates a surface divided into spectral land units, and *topographic partitioning*, which subdivides the surface into spatially contiguous areas representing the natural terrain.

Classification and topographic partitioning are important components of modeling because they allow researchers to seek out higher levels of structure than exist in raw data. The problem common to all classification activities is: given a set of unclassified objects, describe a set of appropriate classes, then decide which class each object should be assigned. Classification and topographic partitioning are typically treated separately, in spite of the fact that topographic partitioning can be viewed as a subtype of classification. That is, the partitioning of a surface into topographic land units involves examining a collection of points and placing each one into a topographic landunit, just as spectral classification requires that each point be placed into a spectral class. However, the literature on classification typically excludes topographic partitioning. Both these methods are discussed further in sections below.

#### Classification

Burrough (Burrough86) provides two characterizations of classification methods. First he distinguishes *univariate* and *multivariate* classifications. Univariate classifications are based upon a single variable, or attribute. Multivariate classifications are based upon multiple variables. Secondly, Burrough distinguishes four different methods of generating class intervals. *Exogenous* class intervals are related to the data being classified, but are not derived from that data. They are often standard classification schemes in a discipline (e.g., land cover type, soil class). *Arbitrary* class intervals are selected without a clear aim, while *serial* intervals are chosen so that they relate to each other mathematically. Sub categories of the serial interval include class intervals based upon 1) normal percentiles, 2) a proportion of standard deviation centered on the mean, and 3) equal intervals on both arithmetic and non-arithmetic scales. *Idiographic* intervals reflect the nature of the data set being classified; there is a unique set of intervals for each set of data classified. Therefore, comparison between different data sets that are classified independently is difficult, if not impossible.

A third subdivision of classification focuses on the nature of the classes into which objects are placed. The classes can be based either on traditional or fuzzy set theory. Fedrizzi discusses fuzzy set theory noting that "analysis and modeling of real world phenomenon or processes must take into account an inherent uncertainty." (Fedrizzi87, pp. 13) He notes that in some cases, this uncertainty is due to vagueness, i.e., a lack of clearcut boundaries of the set of objects to which a label is applied. As originally described by Zadeh (Zadeh65), all sets can be described by a characteristic function whose value indicates whether the object belongs to the set. In traditional, or crisp, set theory the function maps every candidate object to a membership value of one or zero (i.e., the characteristic function value corresponds to either true or false). Fuzzy set theory uses a membership function which maps object membership into the real number interval zero to one, also called a *possibility value*. As an example, imagine a set of cover type classes into which we must sort landunits. Using traditional set theor, we generate a definition for each class corresponding to a characteristic function. We apply this function to each landunit, and the function returns a zero or one to indicate whether or not the land unit belongs to the class. We apply the characteristic function for each class to the landunit until either 1) we find a return value of one, or 2) we have exhausted all classes. If we exhaust all possibilities without finding a member, the landunit remains unclassified. Approaching the same classification problem using fuzzy set theory, we start by deriving a fuzzy membership function for each cover type class. As above, we apply the function for each class to each landunit. The interval between zero and one contains an infinite number of real numbers; therefore the set of potential possiblity values returned by a membership function is theoretically infinite. Thus, we usually find that a landunit has non-zero possibility values for more than one class. The process of *de-fuzzification* is used to select among several candidate classes.

Data cannot be classified until a set of classes, called in science a *class scheme* or *class system*, has been defined. The process of characterizing the classes into which objects will be placed is called *training*. An analyst must not only identify the set of classes; he/she must also define each class in terms of the dataset to be classified, so that the classification process will be straightforward. Training can be of two kinds. *Unsupervised* 

training examines the set of unclassified objects to determine the structure inherent in the data. This structure is used as the basis for class definitions. Unsupervised training is also called *cluster analysis* and can utilize one of four standard algorithms - sequential, statistical, isodata and rgb clustering (ERDAS91). Sequential clustering not only trains, but also classifies all points in the image. The other three clustering algorithms require the analyst to subsequently classify the image points. Cluster analysis may be an interactive process and may be repeated a number of times until the analyst is satisfied with the number of classes and their definitions. *Supervised training* requires the analyst to have *a priori* knowledge of the data set or the area represented by the image. One such source of knowledge is ground truthing. A *training sample* is a set of image points which comprise a discernible pattern that may represent a class. A *training site* is the geographic area represented by a training sample. A training sample can be used to generate a *signature*, or set of statistics that characterizes a class. Signatures can also be generated during cluster analysis.

The actual classification process requires the analyst to choose a *decision rule* that will be used to determine which class a given object is assigned to. Four decision rules are commonly used: parallelepiped, minimum distance, mahanobis distance and maximum likelihood (ERDAS91).

## **MT-GAP Classification Methods**

The role of classification in the GAP project is described in (Ma93). Firstly, points in a TM scene are classified into *spectral class*. The product of this classification is a partitioning of the study area into regions, each representing a spectral class. Each is composed of a number of subregions (i.e., an aggregate of points) which serve as modeling units. The data is classified into spectral groups, or classes, that simulate the color composite of TM channels 3, 4 and 5. These bands record the visible red, near-infrared and mid-infrared wavelengths and are commonly used for visualization and feature identification in image processing. The algorithm identifies by similarity of color, groups of similar points in three-dimensional spectral space. Within each color group, brightness subgroups are identified. These sub-groups are the clusters or classes into which all the points in the image are classified. Training and classification are combined in a two-pass process called "corr\_dist" (Ma93). The data is trained in the first pass by randomly sampling the set of points comprising the image. Each sampled point is examined to determine if it is distinct from the previous samples, if any, to form a new cluster. If so, this newly examined point is stored in a *spectral bank* holding those points that characterize the clusters identified so far. In the second pass of the process, each point in the image is examined with respect to the "training points" stored in the *spectral bank*. Each point is labeled using the Euclidean Distance decision rule.

In the second stage of classification, the subregions produced by spectral classification become the objects of classification (i.e., instead of individual points). This is a traditional set-theoretic approach to cover type classification which utilizes the nearest member group algorithm (Ma93). Each subregion is "located" in *n*-space, where *n* equals the number of spectral and biophysical parameters used in the training and classification. The cover type for a subregion of unknown class is the cover type of the nearest labeled subregion. The class intervals used here are exogenous, and make use of a standard land cover type classification scheme. Before classification, the analyst conducts supervised training, using ground-sampled data collected at training sites. For each training site, the cover type is determined. Next, each region (i.e., a set of training sites that have the same cover type) is characterized in terms of spectral and biophysical parameters including: mean values for all seven TM bands, mean elevation, gradient and aspect. Summary climate statistics on both a yearly and growing season basis can be derived, but have not been used to date in cover type classification.

We can extend the cover type classification process beyond that used in this traditional approach by the following fuzzy set-theoretic method. For each cover type, all training sites are analyzed and summary statistics are generated for each parameter. Thus we have a signature for each *<cover type, parameter >* pair. The signature is used to derive a fuzzy set membership function. This  $m \ge n$  set of functions (where m equals the number of cover types, and n equals the number of parameters) is applied to each unclassified subregion. The product is an  $m \ge n$  matrix of possibility values for each unclassified unit. Conceptually, the matrix represents a set of rules, with one rule for each cover type. More precisely, each of m rules is a conjunction of n statements (one for each attribute). If all the statements in a given rule are true (that is, if the possibility value for all attributes is greater than zero), then the rule has a value greater than zero. We therefore derive the "truth" value of a rule by taking the minimum of all its component possibility values. At the end of evaluation, the cover type for a modeling unit, is the type whose rule has the greatest "truth" value.

### **Topographic Partitioning**

The second approach to generation of landunits suitable for modeling is topographic partitioning. Band, et al., (Band90,92) discuss the theoretical background of this approach and a widely used algorithm they have developed to perform such partitioning. The fundamental unit for this work is the drainage basin, which is viewed as a fundamental topographic concept in geomorphology, hydrology and landscape ecolo gy. Using topography as the focus for ecological modeling offers three advantages: 1) the drainage basin has well-defined internal and external boundaries, 2) topography is more stable than either vegetation or soils, and 3) a set of unambiguous, mutually exclusive and spatially exhaustive objects can be defined from a model of topography. An object model of the watershed is used in which the watershed is viewed as a partition of hillslopes and stream networks. "The watershed representation follows a formal geomorphic model that defines the consistent ordering and hierarchy of the topographic objects, enabling higher order processing of drainage basin structure and attribute information (Band90, p. 787). The drainage basin is seen as a collection of hillslope facets bounded by the stream and divide links.

A digital elevation model is used as the basic input to the partitioning process. Topographic information, such as gradient and aspect, is derived from the DEM. Initially, the area inside the watershed is viewed as a tree, rooted at the outlet point for the watershed. Each point in the watershed is a node on the tree. Each point has an arbitrary number of descendants. The number of descendants of point A indicates how many points are upstream of point A. The points which have no descendants (i.e., the leaves on the tree), indicate the watershed's ridgelines. Ridgelines are both external, marking the boundary of the watershed, and internal, marking the divides between catchments. The watershed is partitioned into hillslopes by pruning the tree. Thus, all points with fewer than a user-specified number of descendants are eliminated. The remaining points represent a model of the drainage's stream network. This network is comprised of the remaining drainage lines and junction points. In graph-theoretic terms, these structures are called edges or arcs, and vertices or nodes, respectively. The hillslope is defined as the aggregate of all points which exist on one side of a drainage line up to the ridgeline. If the watershed is to be partitioned at a coarser level, the tree is pruned at higher levels.

This topographic model is characterized as a three-tiered structure (Band90). The first level contains data overlays with point based data (i.e., elevation, gradient, aspect, drainage area). Above this level is the extracted stream network, and above this is the basin structure.

## <u>Re-partitioning Transformations</u>

Partitioning operations (in particular, overlay classification) often produce an overlay with a very large number of small subregions. A high concentration of small units is commonly called "salt and pepper", or simply "noise". Some of these units may be only one point in size. This amount of detail may make any further modeling operations very compute-intensive. It also makes visualization and examination by eye much more difficult. Additionally, the units may also be too small to have meaning in an application domain. For example, Gap analysis is meant to serve as a coarse filter to identify areas above a certain size (typically 100 acres) that are potentially important habitats for native terrestrial vertebrates (Scott93). Thus, modeling units with size below this level should be aggregated somehow.

There are two common operations that perform this function. The first is commonly available in most GIS packages, and involves passing a window, called a *filter*, across the overlay. Aronoff (Aronoff89) classifies this operation as a *neighborhood operation*. The neighborhood around each point is examined and a function applied. The return value of the function becomes the value of the point. The name of the filter describes in general terms the nature of the function. For example, the *majority filter* has been used on MT-GAP to eliminate "salt and pepper" on classified imagery (Ma93). The return value from this filter is the class identifier that occurs most often in the neighborhood. The resulting overlay will have fewer subregions.

A second re-partitioning method merges any subregions below a user specified size with an appropriate neighboring unit. A modeling unit that is to be merged will be swallowed by one of its neighbors, which is selected according to a user specified function for selecting one of the set of possible neighbors.

## Deriving Missing Values

Burrough (Burrough86, pp. 146-147) defines *interpolation* as the "procedure of estimating the value of properties at unsampled sites within the area covered by existing point observations" and *extrapolation* as the procedure of "estimating the value of a property at sites outside the area covered by existing observations." We interpolate by finding a model of variation and applying it to the surface. These models can be of two types. In the discrete model, we interpolate by drawing boundaries on the surface. We can use external landscape features to delineate landscape units, utilize edge-seeking algorithms or employ Thiessen polygons. All these methods assume that the important variation occurs at the boundaries defining landscape units. The second kind of interpolation model is continuous and utilizes the gradual change of values. These methods use a model that can be described by a smooth, mathematically defined surface. They are of two types, global and local. Global models are constructed from observations at all points and don't accommodate local features. Examples are trend surface analysis and Fourier series. Local models are constructed from neighborhood observations. Examples are splines and moving averages, also known as inverse distance weighting.

An important use of interpolation and extrapolation on MT-GAP and NTSG projects is as a method for modeling climate. Climate is a continuous phenomenon that is sampled at irregularly distributed locations. Researchers must often develop a model of climate for a specific location that has no directly-measured climate data. Climate data has been utilized by MT-GAP to aid in cover type classification, and is used in RHESSys to drive ecosystem simulation. Ecosystem modeling requires that this sparsely sampled data be used to infer climate conditions at many unsampled points. The primary modeling logic has been developed at the NTSG lab, in a software package called Mountain Microclimate Simulation Model, or MtClim (Hungerford89). MtClim extrapolates climate data from a

site where climate data has been measured, called a *base met station*, to a *study site* where climate values are unknown. The extrapolation uses topographic data for the study site (i.e., elevation, gradient and aspect) and a model of sun-earth geometry to compute incident short-wave radiation. The base station data describes maximum and minimum temperatures and precipitation on a daily time step for a time period selected by the modeler. The input data is drawn from the Climatological Data Summary from NOAA containing data for National Weather Service (NWS) weather stations from the late 19th century to the present. MtClim logic produces data describing maximum and minimum temperatures, dew point, shortwave radiation and precipitation for a study site.

Recent enhancements of MtClim allow NWS data from a number of base stations within a radius of the study site to be used to improve predictions of the conditions at the study site. This new logic interpolates from surrounding base stations and produces a *vir*tual met station, which occupies the same two-dimensional location as the study site. The interpolation uses a weighted average method, by determining the radius of the window and the maximum number of NWS stations to use for interpolation of any one virtual station. For each virtual station, the n (where n is the maximum number of stations to use in the weighting) nearest NWS stations within the window are selected and inverse distance weighting is used to generate a weight to apply to each chosen NWS station. If no stations are found within the window radius, the nearest station at any distance is used. For each attribute to be interpolated, and for each time step, the appropriate data value is weighted and a sum performed to derive the data value for the virtual station. MTCLIM is subsequently used to extrapolate from the virtual station to the study site.

### Deriving Missing Variables

Overlays containing values at the numerical measurement level can be used as operands in algebraic operations. An operation can have as operands two overlays or one overlay and a scalar value. The result of the algebraic expression is of course another overlay. We call this kind of operation *overlay algebra*. We discuss two examples of overlay algebra in the two following sections.

Soils data is required as input for various ecosystem simulations, including RHESSys. Commonly used soil attributes include *soil water capacity* and *soil transmissivity*. Soil water capacity measures the quantity of water the soil can retain per unit of land. Soil transmissivity is *soil depth* times *hydraulic conductivity*, i.e., the capacity of water to migrate through soil. Hydraulic conductivity is typically estimated from soil texture.

Many ecosystem simulations use an abstraction of actual ground cover to estimate the density of the vegetation canopy. Remotely sensed spectral reflectance is the data source typically used for this estimation. Before using the data on these overlays to estimate vegetation parameters, the analyst must compensate for two limitations of the datasets. The level of reflectance detected by the sensor is affected by dust, gases and aerosols in the atmosphere between the ground and the sensor. A widely-used technique for dealing with this phenomenon is known as the clear-lake strategy (White92). Certain objects, such as deep, clear lakes, absorb all incoming radiation. The point on each overlay with the lowest reflectance value is assumed to be a clear lake that reflects no radiation. Therefore, any reflectance value at that point is assumed to be a product of atmospheric effects. Overlay algebra is used to subtract the value at that point from all points on the overlay. The resulting dataset is taken to be atmosphere corrected. Overlay algebra is also used to compensate for the effects of sun angle. Satellite scenes are often recorded at a time when the sun angle is low enough to cast shadows across the landscape. These shadows interfere with proper imagery interpretation.

After this corrective work, overlay algebra is performed on three overlays, each

representing a unique spectral band. The product of this operation is the estimate of land cover, called the *normalized difference vegetation index* (NDVI). A regression model is used to transform NDVI values into values for another abstraction called *leaf area index* (LAI) (Nemani92, White92). LAI can be measured on the ground, by dividing the total leaf surface area in a tree canopy by the ground surface area under the canopy. Ground measurements can be compared with the estimates from satellite imagery. Thus LAI serves a critical role for ecosystem modelers who rely on satellite imagery. LAI is measured in two forms: *projected LAI* estimates the leaf area on one side of a leaf and is used primarily in broadleaf forests and croplands, while *all-sided LAI* is used in needleleaf forests where the leaves are not flat. However, several transformations must be applied to the raw imagery in order to generate NDVI. First the data must be adjusted for the spectral reflectance produced by the atmosphere, called atmospheric radiance. Secondly the data must be corrected for the effects of sun angle on the image.

#### EcoModel Assignment

Often during modeling operations, values must be derived for attributes that describe the ecosystem units in an ecosystem model. An overlay describing a particular attribute on a point by point basis is processed to obtain representative values (e.g., the mean) for each ecosystem unit. A value is extracted from each point that falls within the ecosystem unit of interest, and a mean value is calculated. For example, preparation for execution of the dynamic simulation Forest BGC requires that representative values be computed for five attributes: elevation, gradient, aspect, available soil water and leaf area index. A topographic model serves as a template; that is, the model is "laid over" the five overlays containing values for the above attributes. For each hillslope in the topographic model, a mean value is computed for each of the five parameters. This procedure is implemented in a process called "TopCart". A similar procedure is used to generate an ecosystem model for MT-GAP by performing spectral classification of the numerical overlays representing the area of interest. In order to classify each landunit by cover type and to facilitate further modeling activity, sets of representative values are derived for topographic, spectral and climate attributes. The topographic attributes include elevation, gradient and aspect. Average values per land unit are also generated for each of the seven bands of TM data, as well as a set of summary statistics developed from climate simulation.

### Image Enhancement

Images (or overlays) often need to be modified to facilitate data interpretation. This process is called *image enhancement* and is often used for feature extraction. The techniques used depend on the nature of the data and the objective of analysis. We discuss the two categories of image enhancement that are used on single-band imagery (in our model, a single overlay). Our experience is that image enhancement operations are performed on overlays containing elevation or reflectance data. However, in theory any numerical overlay could be the subject of image enhancement operations.

Spectral enhancement deals with values of individual points in the overlay. Spectral enhancement is usually used to make certain features stand out by increasing the contrast in the image. A *linear contrast stretch* takes an overlay and modifies the values of individual points to take full advantage of the capacity of the display device. In most raw overlays, the data values fall within a narrow range. By "stretching" this range to fit that of the display device, contrast is enhanced. The operation can be described as a linear function that maps raw data values to enhanced data values. The operation uses the mean, standard deviation, and other overlay statistics. The range of the raw data is calculated by taking a distance from the mean measured in units of standard deviation. The minimum and maximum values are not used, because these measures are not usually representative of the data. In *non-linear contrast stretching* the function that describes the enhancement is non-linear. Again, it maps raw data values to enhanced data values. *Histogram equalization* is one kind of non-linear contrast stretch. This operation redistributes point data values so that there are approximately the same number of pixels with each value within a range.

Spatial enhancement determines the value of a given point by examining the values of its neighbors. A critical concept here is that of spatial frequency, which describes the difference between the lowest and highest data values of a neighboring set of points. An overlay in which all points have the same value has zero spatial frequency. An overlay in which alternating points have values at the highest and lowest ends of the range of data values has high spatial frequency. Convolution filtering averages the values of small sets of points across an overlay, and is used to change the spatial frequency of the overlay. A convolution kernel is a matrix (generally, a 3 x 3 matrix) of numbers that serve as the coefficients of a function that computes a weighted average. The kernel is placed on the overlay, centered on the point for which we wish to compute an enhanced data value. The return value of the function becomes the enhanced value. An entire overlay can easily be enhanced by passing the kernel across the surface, centering it on each point in turn. Convolution kernels which increase spatial frequency are called high-pass kernels and those which decrease spatial frequency are called *low-pass kernels*. A special kind of kernel is zero-sum, in which the existing spatial frequency is exaggerated. Zero-sum kernels are often called edge detectors because the resulting image often consists only of edges and zeroes. High-pass kernels serve as edge enhancers in that they highlight the edges between homogeneous groups of points. Unlike edge detectors they don't necessarily elimate other features.

# Summary of Requirements Analysis

Our detailed analysis of the key abstractions and modeling operations used in ecosystem modeling provides the foundation for further analysis. Specifically, the entities and processes identified in requirements analysis will serve as the key components of a domain analysis model that is presented in the following chapter and in the appendices.

## CHAPTER IV

## DOMAIN ANALYSIS

#### Introduction

We present here the results of our domain analysis, consisting of three sets of documents: class relationship diagrams, class specifications and object diagrams depicting key scenarios. These documents are contained in full in Appendices I to III. In this chapter we discuss key aspects of our analysis, using elements from all three sets of documents.

## **Class Relationships and Interfaces**

We begin with a discussion of class interfaces and relationships. The purpose here is to characterize the key abstractions in the application domain, and describe the relationships between these abstractions. The notation we use is discussed in (Booch89). Each class name is in boldface and class attribute and operation names are in italics.

Our complete class hierarchy contains 169 classes, making it difficult to show in a single diagram. To simplify this discussion, we subdivide classes into twelve sets, each occupying a section of the hierarchy and focusing on a related set of entities. These sets are root, spatial, ecosystem, ecosystem descriptors, operations, classification, data acquisition, descriptors, windows, software, documentation, and humans.

We discuss in this chapter classes and relationships from the groups: spatial entitites, ecosystem entities and modeling operations. We have chosen these groups to discuss at length because they lie at the heart of our domain analysis model. Ecosystem modeling is fundamentally an activity in which operations are performed upon spatial representations of ecosystems. Thus, if we confine our discussion here to a subset of our hierarchy, it is sensible to choose those classes and relationships that represent the most significant entities we have discovered.

### Spatial Entities

The most significant set of abstractions we have found are those that describe phenomena in two-dimensional space. These entities are geometric objects that provide the foundation upon which ecosystem models are created.

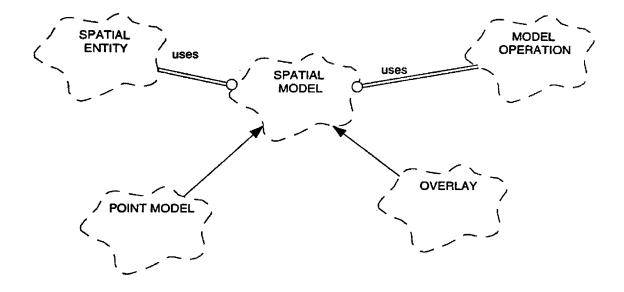




Figure 1 portrays a key class, spatial model, using as a class symbol an amorphous shape with dashed borders. Spatial model is a subclass of spatial entity, and the parent class for two subclasses - point model and overlay. The parent-subclass relationship is represented by a solid arrow from the child to the parent class.

Spatial model is also involved in a "using" relationship with class model operation, which is indicated by a double line from "using" to "used" class with a hollow circle adjacent to the "using" end. This notation indicates that the "used" class is referenced in the interface of the "using" class - either as a formal parameter to an operation or as a data field. In the case where two classes use each other, we have hollow circles on both ends of the line.

#### class

name	Spatial Model
parent	Spatial Entity
attributes	
spatial scale	String
geographic coordinate system	String
projection	<b>Projection System</b>
consuming operation	Spatial Model Consumer
producing operation	Model Operation
operations	
Get spatial scale (void)	return String
Set spatial scale (String)	return void
Return projection (void)	return Projection System

#### end class

#### Figure 2

The interface of class **spatial model** is shown in Figure 2. The class definition contains class name, parent class, attributes and operations. **Spatial model** has five attributes. Attributes are indicated by attribute name, followed by the type of the attribute. In cases where the attribute is an object of a class (i.e., rather than a simple data type), the type name will be the name of the class. In this case, the attributes of **spatial model** refer to two classes that describe processing operations discussed in requirements analysis, and these references provide the history of a particular object by providing a trace of the sequence of processing steps used to create it.

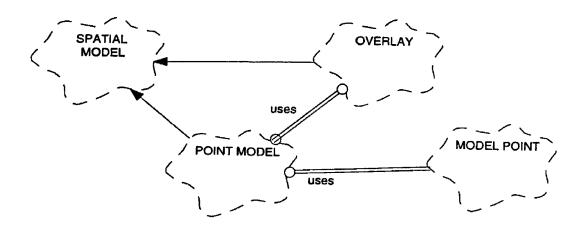
We have followed the advice of White (White93) in providing operations for our classes. We have modeled standard store and retrieve methods for all attributes that are simple data values (e.g. types Number, String) as operations. Names in parentheses are

formal paremeters for an operation and indicate the type of arguments required by the operation. The word "return" in the specification is followed by the type of the value returned by the operation. The word void means that we require as an argument, or return from an operation, no value.

class	
name	Spatial Entity
parent	Entity
attributes	
number points	Number
area	Number
perimeter	Number
operations	
end class	

## Figure 3

The definition of **spatial entity**, the parent class of **spatial model**, is shown in Figure 3. **Spatial entity** has attributes that describe the number of points contained in the entity, its area and perimeter. Based on the parent/subclass relation, these attributes and operations defined for **spatial entity** are inherited by all subclasses of **spatial entity**.





Our concept of spatial model is refined in Figure 4. The subclasses overlay and point model of spatial model are shown here, along with a "using" relationship between point model and model point.

class	
name	Point Model
parent	Spatial Model
attributes	
model point	SET < Model Point >
number overlays	Number
overlay	SET < Overlay >
operations	
Iterate over points (void)	return Model Point
Sample points (void)	return Model Point
and alara	

end class

# Figure 5

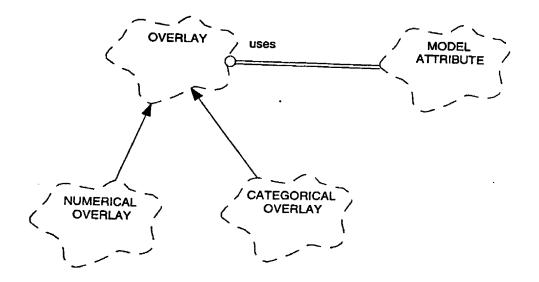
Figure 5 shows the specification for **point model**. The bracket notation used in the type designation for attribute *model point* indicates that the value will be a set of objects of the class or type named inside the brackets. This notation is used in cases where more than one object of a "used" class can exist in a class interface.

class	
name	Overlay
parent	Point Model
attributes	
number of regions	Number
number of subregions	Number
number of points	Number
data name	Model Attribute
containing model	Point Model
consuming operation	Overlay Consumer
operations	

end class

Figure 6

Figure 6 contains the specification for overlay. The first three attributes indicate the number of overlay substructures that are contained in a particular overlay. The attribute, *containing model*, allows access to the **point model** that contains the **overlay**, and therefore to the other **overlay** objects in the model. *Data name* labels the data in the overlay.



## Figure 7

Figure 7 shows two subclasses of overlay, numerical overlay and categorical overlay, along with a using relationships between model attribute and overlay. Model attribute labels the overlay with the name of the data attribute it represents. Objects of numerical overlay hold data at the numerical measurement level, while categorical overlay objects hold values that are class identifiers. We distinguish between these two subclasses of overlay because of differences in the set of operations that are meaningful in the two cases. That is, numerical overlays can be used in overlay algebra, while such operations performed on categorical data are meaningless. Categorical overlay objects

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are also involved in relationships, discussed later, in which numerical overlay instances cannot take part.

It would be possible to create a subclass of **numerical overlay** or **categorical overlay** for each kind of data that these structures can hold, i.e., subclasses for elevation, gradient and aspect. However, we believe that the differences between **overlays** holding these three kinds of data do not require the creation of a separate class for each. The behaviors which are semantically meaningful are determined by the measurement level of the data. We view these three **overlays** as objects of class numerical overlay. Thus, we believe that subclasses **numerical overlay** and **categorical overlay** are adequate.

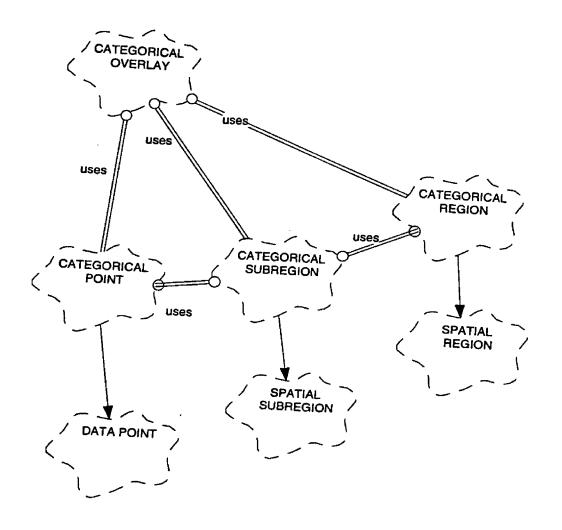
class

name	Categorical Overlay	
parent	Overlay	
attributes		
regions	SET < Categorical Region >	
subregions	SET < Categorical SubRegion >	
points	SET < Categorical Point >	
consuming operation	Categorical Consumer	
eco model	Ecosystem Model	
operations		
Iterate over points (void)	return Categorical Point	
Iterate over subregions (void)	return Categorical Subregion	
Iterate over regions (void)	return Categorical Region	
Sample points (void)	return Categorical Point	

end class

## Figure 8

The interface of categorical overlay is depicted in Figure 8. The attribute *eco model* is a reference to a higher level model which is built upon the categorical overlay. Categorical overlays are the product of a partitioning operation, and are often used as the basis upon which higher level modeling structure is built. We have called these higher level models, ecosystem models, and will discuss them later in this chapter. The operation *iterate* is provided for all three sets of overlay components represented by the attributes *regions*, *subregions* and *points*. The interface for **numerical overlay** is not shown here. It differs from **categorical overlay** in two ways. First, references to **categorical point**, **categorical subregion** and **categorical region** are replaced by **numerical point**, **numerical subregion** and **numerical region**. Second, a set of algebraic operations (e.g., add, sub-tract, multiply and divide) are permitted on **numerical overlay** and its components.





class		
name		Categorical Region
parent	t	Spatial Region
attribu	utes	
subre	gions	SET < Categorical Subregion >
operat	tions	
Iterat	e over subregions (void)	return Categorical Subregion
end class		

#### Figure 10

class	
name	Categorical Subregion
parent	Spatial Subregion
attributes	
points	Categorical Point
containing region	Categorical Region
neighbors	SET < Categorical Subregion >
operations	
Iterate over points	return Categorical Point
end class	

#### Figure 11

Figure 9 depicts the using and parent/subclass relationships of the overlay abstraction, as proposed in our requirements analysis. Class categorical region, shown in Figure 10, is a subclass of spatial region. Categorical subregion, shown in Figure 11, is a subclass of spatial subregion. Objects of categorical subregion are the spatially contiguous areas that comprise the "polygon mesh" on the overlay surface. An attribute, *containing region*, refers to the categorical region in which the categorical subregion is contained. This reference to the spatially enclosing objects can be used to move from subregion to region, and query attributes of the region, or to visit other subregions that are part of the same region.

Point objects, which have no area and perimeter, are not subclasses of spatial

entity. Point objects form a separate class hierarchy descended from class named entity. We do not show the interfaces for the ancestors of categorical point here because the semantics of this set of objects is much simpler than the other classes we have discussed. Instead, we summarize the attributes inherited from ancestors. Categorical point inherits two objects of class coordinate - a geographic coordinate and a spatial coordinate - and a numerical value indicating spatial resolution. The specification for categorical point is shown in Figure 12.

class	
name	Categorical Point
parent	Data Point
attributes	
data	Number
containing subregion	Categorical Subregion
operations	
end class	

Figure 12

Data contained by an overlay is actually held by the point objects comprising the overlay. The reference to the enclosing categorical subregion serves the same function as the pointer to region does in the interface of categorical subregion.

## Ecosystem Entities

**Ecosystem entities** are used to build the higher level structures often used in ecosystem modeling. Whereas the **spatial entities** described above are essentially geometric objects, the **ecosystem entities** have a richer semantics reflecting the information scientists obtain about the real world.

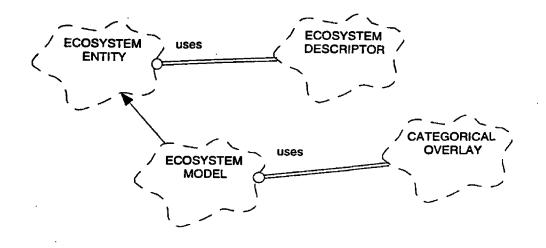
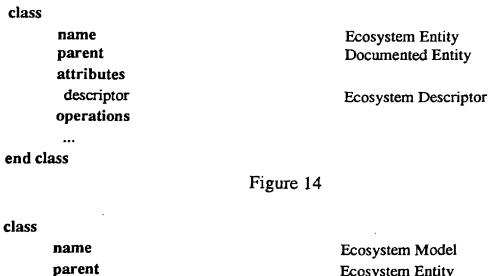


Figure 13



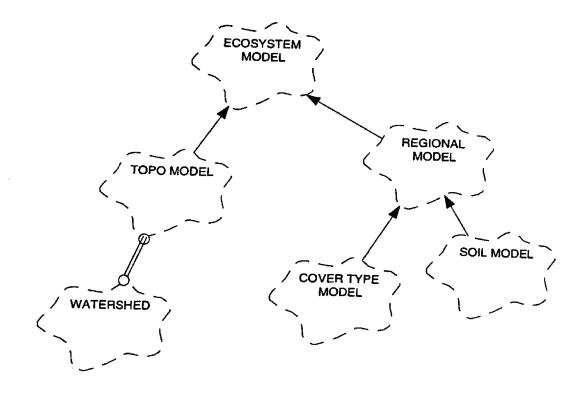
parentEcosystem EntityattributesEcosystem EntityfoundationCategorical Overlayconsuming operationEcosystem Model Consumeroperationsreturn Categorical Overlay

end class

...

Figure 15

Figure 13 depicts ecosystem model, its parent ecosystem entity and ecosystem descriptor, along with a using relationship from ecosystem model to categorical overlay. Figure 14 contains the specification for ecosystem entity. An object of class ecosystem descriptor can be attached to any ecosystem entity in order to provide information on topography, vegetation, climate and other aspects of the entity. The interface of ecosystem model is shown in Figure 15. We do not model attributes describing geometric properties for this class because this information is already available on the corresponding categorical overlay. The operation *Return foundation*, in the interface for ecosystem model, allows access to the categorical overlay upon which the ecosystem model is based.





class
name Topographic Model
parent Ecosystem Model
attributes
number watersheds Number
watersheds SET < Watershed >
operations
...
end class

# Figure 17

class		
	name	Regional Model
	parent	Ecosystem Model
	attributes	
	number regions	Number
	operations	
	•••	
end cl	ass	

Figure 18

class
name Ecosystem Region
parent Ecosystem Region
Ecosystem Entity
attributes
number points Number
area Number
perimeter Number
number subregions Number
operations

...

end class

class		
name		Cover Type Model
parent		Regional Model
attributes		
regions		SET < Cover Type Region >
subregio	ns	SET < Cover Type Sub region >
consumi	ng operation	Cover Type Model Consumer
class sch	eme	Cover Class Scheme
operations	5	

end class

...



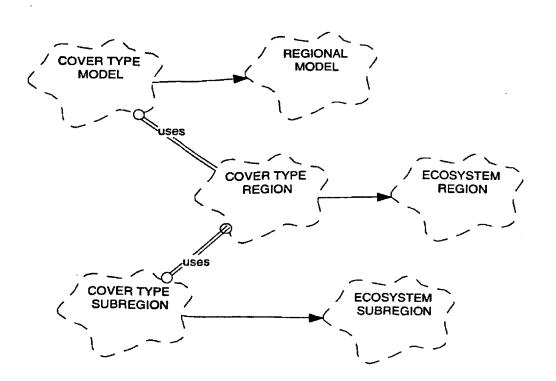




Figure 16 portrays the class hierarchy descended from ecosystem model. A topographic model doesn't have region/subregion structure; instead it may consist of one or more watersheds as illustrated in the specification in Figure 17. Figure 18 presents the interface of regional model, which does have the region/subregion structure. The interface of ecosystem region is shown in Figure 19. Generally, we do not provide attributes to describe the geometric properties of ecosystem entity and its subclasses because the geometry of these entities can be obtained from the components of the categorical overlay on which the model is built. However, the number, size and shape of regions on an ecosystem model will almost never be the same as on the corresponding categorical overlay. For example, a partitioning operation (e.g., spectral classification) will examine all points on a set of numerical overlays and create a categorical overlay where each point has a class identifier. Our categorical overlay can be described as a "polygon mesh" of categorical subregions, each occupying a spatially contiguous area. A second partitioning operation (e.g., cover type classification) will examine each categorical subregion and classifty it into a cover type class. It is extremely unlikely that all categorical subregions that fall in the same spectral class, will also fall in the same cover type class. Therefore, we provide attributes number points, area, perimeter and number subregions in the interface of ecosystem region to reflect our understanding of the difference in region "structure" between categorical overlays and ecosystem models. Figure 20 shows the interface of a subclass of regional model, cover type model, which characterizes land in terms of vegetative cover type. The attribute *class scheme* is a reference to an object of class cover class scheme, which is used to classify the model into cover type regions. Figure 21 illustrates the parent/subclass and using relationships of cover type model.

class
name
Cover Type Region
Parent
Ecosystem Region
attributes
subregions
describing class
Operations
...
end class

## Figure 22

The interface for cover type region is presented in Figure 22. The attribute *describing class* refers to the specific cover type class that describes this region. A cover type class referenced by an object of cover type region must be contained in the cover class scheme to which the cover type model refers. The attribute *subregions* is the set of cover type subregions which comprise cover type region.

name		Ecosystem Landunit
parent		Ecossytem Entity
attributes		
foundation		Categorical Subregion
virtual climate station		Virtual Met Station
operations		
end class		
	Figure 23	
class		
name		Cover Type Subregion
parent		Ecosystem Landunit
attributes		
containing region		Cover Type Region
operations		

Figure 24

The classes describing the spatially contiguous portions of an ecosystem model are subclasses of **ecosystem landunit**, whose specification is shown in Figure 23. The attribute *foundation* indicates a mapping of the **cover type subregion** from corresponding unit on the **categorical overlay**. *Virtual climate station* is the product of interpolation of climate data in MtClim, discussed in requirements analysis. As illustrated in Figure 24, class **cover type subregion** adds to the properties inheritied from **ecosystem landunit**, the attribute *containing region*.

#### <u>Operations</u>

The modeling and analysis operations discussed in requirements analysis define the characteristics of a set of objects. In an object-oriented methodology, operations are seen as properties of individual classes, and not usually as objects in their own right. We do model some operations in class interfaces, but have found that these operations tend to be limited in scope. Significant operations have a larger and more complex logic that prevents them from being modeled on individual classes. Booch (Booch89) uses the term mechanism to describe a set of object behaviors that together achieve a more complex task than any one object could in isolation. We provide diagrams depicting several of these mechanisms later in this chapter. First we present class diagrams for several modeling operations.

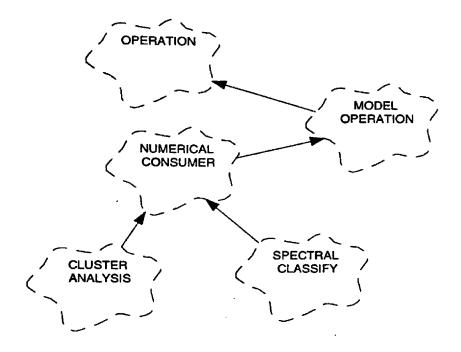
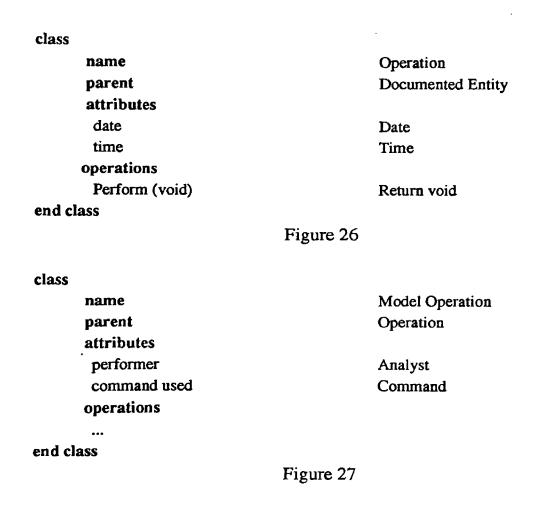


Figure 25



class name **Cluster Analysis** parent Numerical Consumer attributes output bank Spectral Bank output scheme Spectral Scheme operations ... end class Figure 28 class name Spectral Classification parent Numerical Consumer attributes input scheme Spectral Scheme input bank Spectral Bank output overlay Categorical Overlay operations ... end class

Figure 29

Figure 25 shows a portion of the hierarchy containing classes representing operations. Classes operation and model operation have simple interfaces as shown in Figures 26 and 27. The behavior perform in the interface of operation initiates execution; attributes *date* and *time* record the date and time of execution. Model operation contains the attribute *performer* to indicate which analyst carries out the operation; *command used* records the software command utilized. The interfaces of two subclasses of model operation, cluster analysis and spectral classification, are presented in Figure 28 and 29. Both cluster analysis and spectral classification are children of class numerical consumer (i.e., they take numerical overlays as input). Cluster analysis (Figure 28) contains references to two objects produced during execution: spectral bank is a class of

objects used in the spectral classification algorithm described in requirements analysis, and spectral scheme is a subclass of class scheme. Spectral classification (Figure 29) uses the spectral scheme and the spectral bank generated in cluster analysis and the input numerical overlay to produce a categorical overlay partitioned by spectral class.

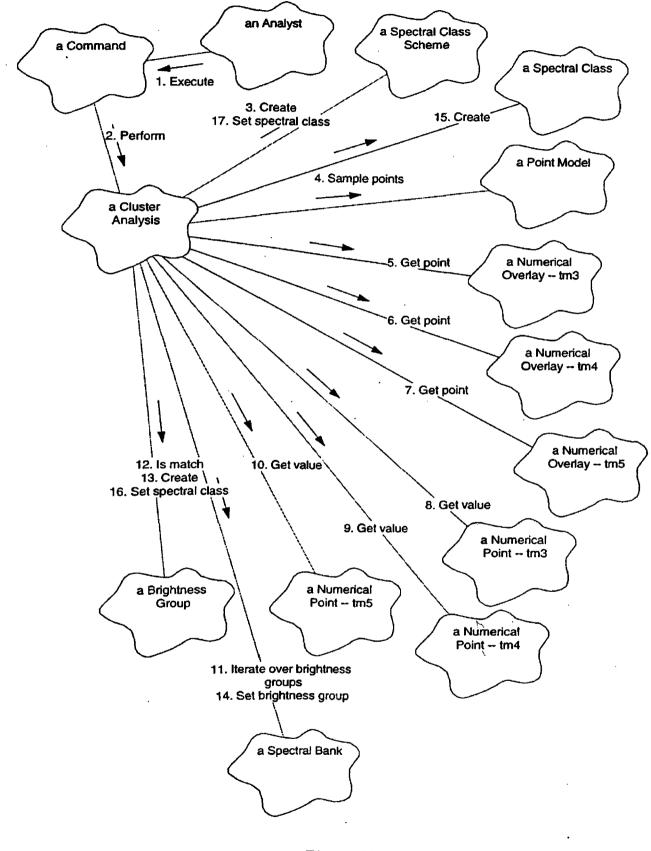
## **Object Scenario Diagrams**

It is with the illustration of scenarios that the analysis model comes to life for those who work in the application domain. Scenarios demonstrate how the activites performed by analysts are carried out by showing how objects work together to perform more complex behavior than they could in isolation. These collaborative arrangements are called mechanisms in (Booch89). Twenty three scenarioshave been identified from the material discussed in requirements analysis (Table 1). Nineteen have been successfully constructed and are depicted in full in Appendix III. The four scenarios which were not successfully constructed have a higher level logic than the scenarios for which construction was successful. The scenarios which were not constructed are discussed in Chapter 5. In this chapter we illustrate and discuss two scenarios that have been constructed.. We place object names in double quotes and use single underlining to highlight operation names.

Figure 30 is the object diagram depicting cluster analysis. Objects are indicated by amorphous shapes with solid borders, with the object name inside the shape. Solid lines between objects indicate that one object uses another. In other words, the object "a Cluster Analysis" uses object "a Numerical Point - tm3". The message <u>Get value</u> triggers an operation that is part of the interface of the class being called. Thus the interface of class **numerical point** must contain an operation called <u>Get value</u>. The passing of this message will cause "a Numerical Point - tm3" to carry out that operation and return a value.

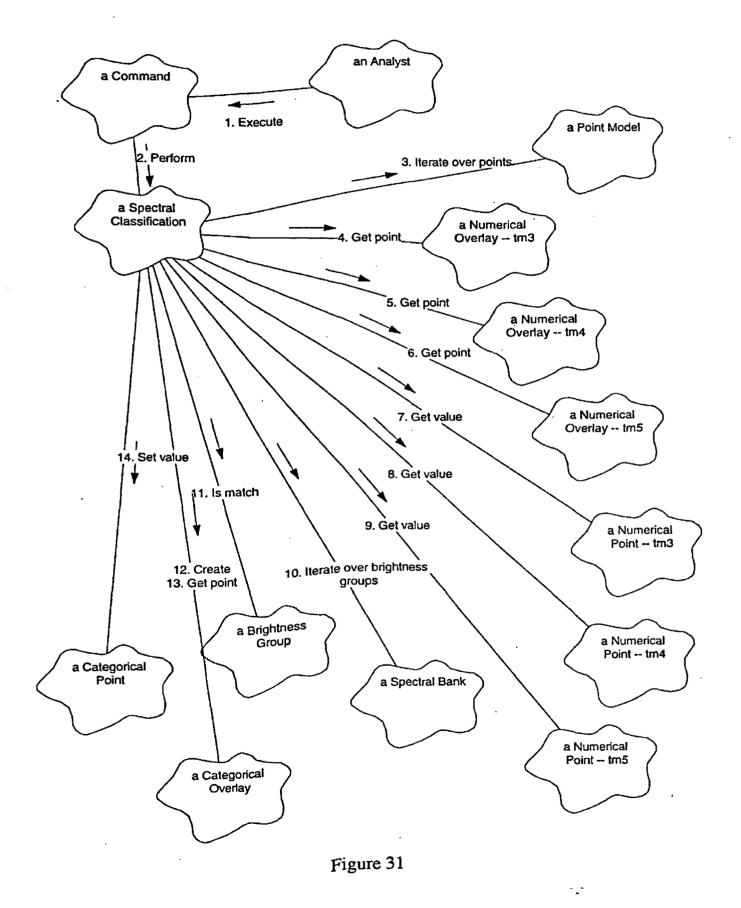
# SCENARIO LIST

<u>Scenario Name</u>	Constructed
Registration	Yes
Resample	Yes
Projection Transformation	No
Convolution	Yes
Contrast Stretch	Yes
Overlay Algebra	Yes
Interpolation	Yes
MtClim	No
Merge	Yes
Majority Filter	Yes
EcoModel Assignment	Yes
Cluster Analysis	Yes
Spectral Classification	Yes
Cover Training - traditional	Yes
Cover Training - fuzzy	Yes
Cover Classification - traditional	Yes
Cover Classification - fuzzy	Yes
Topographic Partitioning	No
Forest BGC	No
Elevation Data Acquisition	Yes
Spectral Data Acquisition	Yes
Climate Data Acquisition	Yes
Field Data Acquisition	Yes



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Figure 30



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All scenarios begin with object "an Analyst" passing the message <u>Execute</u> to "a Command", which in turn passes the message <u>Perform</u> to an object representing the modeling operation depicted in the scenario. "A Cluster analysis" passes message <u>Create</u> to "a Spectral Class Scheme" and the message <u>Sample points</u> to "a Point Model". The message Get point is passed to each of the three **numerical overlays** being sampled. <u>Get value</u> is sent to each of the **numerical points** being sampled. The message <u>Iterate over brightness</u> <u>groups</u> is passed to "a Spectral Bank". The values of each sampled point are passed to "a Brightness Group" with the message <u>Is match</u>, which returns a value indicating whether the newly sampled point represents the same class as "a Brightness group". If the point represents a new **brightness group**, then an object of class **brightness group** is created, and the reference to this **brightness group** is set in "a Spectral Bank". Finally, "a Spectral Class" is created and linked to the newly created "a Brightness Group". This process continues through all sample points.

The object "a cluster analysis" is the executive (i.e., the controlling entity) in this mechanism since it controls the sequence of messages and makes decisions based on values returned from other objects. The object representing an operation will serve as the executive in all of our scenarios.

In Figure 31, the scenario for spectral classification is shown. "A spectral classification" passes message <u>Iterate over points</u> to "a Point Model". The messages <u>Get point</u> and <u>Get value</u> are used to obtain the values for the **numerical overlays** being used in the classification. For each point, the message <u>Iterate over brightness groups</u> is sent to "a Spectral Bank". The message <u>Is match</u>, sent to each **brightness group**, until a match is found. An object of class **categorical overlay** is created, a reference to the appropriate **categorical point** is obtained, and the message <u>Set value</u> assigns the appropriate class identifier to the point.

#### Summary of Domain Analysis

The appendices to this document contain the complete results of domain analysis: a set of class/relationship diagrams (Appendix I), a set of formal class specifications (Appendix II) and a set of object scenarios (Appendix III).

Although this chapter focuses on three groups of classes -- spatial entities, ecosystem entities and operations -- there are many significant entities in those groups that are not described. For example, a set of relationships and operations are defined to give a point or subregion access to its neighbors in "modeling space". Additionally, many of the classes describing operations are not described here. However, a great deal of similarity among these classes leads us to conclude that depicting the interfaces of a few key classes in the operation portion of the hierarchy is adequate for the overview provided in this chapter. A significant class group that we do not discuss deals with classification entities. This class group includes the components of class schemes, the parent/subclass hierarchy depicting different kinds of class (e.g., cover type class, soil class), and the many entities used in the classification operations described in requirements analysis. Although this class group is important, many of its members are discussed in our treatment of spatial and ecosystem entities and model operations. Additional class groups include ecosystem descriptor entities, data acquisition entities, and window and descriptor entities. The remaining class groups - software, documentation and humans - are less central to this discussion. They represent the human actors that carry out modeling operations, the tools that make those operations possible, and the knowledge used in support of, and obtained during, modeling activities. However, the classes and relationships describing spatial and ecosystem entities, modeling operations and classification entities provide the core of significant abstraction in this domain.

The object scenario diagrams (Appendix III) show how the classes defined in this analysis will actually be used in performing the key processing operations used by ecosystem modelers. This is where the "action" is, in understanding how an object-oriented approach to modeling can contribute to our knowledge of a specific application domain.

#### CHAPTER V

### HYPOTHESIS EVALUATION

We have constructed scenarios depicting most of the processes discussed in our requirements analysis. These scenarios show how modeling processes can be carried out given the structure revealed in our class hierarchy. During scenario construction, we found that two actions were necessary with respect to the hierarchy -- we had to modify the interface of class by adding attributes and operations, and less often, we created a new class.

The only scenarios not completed -- for the extrapolation of climate data performed by MtClim, the simulation of ecosystem processes by Forest BGC, projection transformation and topographic partitioning -- are for processes for which the available literature discusses the internal logic in adequate detail. In the interest of providing a concise characterization of the domain, we did not incorporate this knowledge into our requirements analysis. In general, the classes depicted in the domain analysis model, with the exception of classes representing key modeling activities, are "primitive" in nature. That is, the logic of their behavior is at a fairly simple level. Many of the modeling activities for which scenarios have been successfully constructed have a higher level logic than these "primitive" classes. However, in these cases, the "logic gap" between the modeling activities captured in Mtclim, Forest BGC and topographic partitioning exhibit a logic that is considerably higher than that of the classes used in these activities. This greater "logic gap" prevented scenario construction in these cases.

We believe that many of the scenario construction problems associated with Mt-

clim and topographic partitioning can be handled by decomposing these high-level operations into procedural components. MtClim (Hungerford89) is composed of four sub processes which compute solar radiation, temperature, humidity and precipitation. Each of these sub-processes can be modeled as component operations of class **mtclim**. Topographic partitioning consists of three major sub-processes. The first defines the drainage by recursively examing points in the **watershed** to determine, for each point, the number of upstream points. Secondly, the **stream network** must be delineated, and thirdly the **watershed** must be partitioned into **hillslopes**. Each of these sub-processes can be represented as a component of class **topo partition**.

Forest BGC is a complex operation that computes flows of carbon, nitrogen and water through forest ecosystems. The procedural decomposition discussed above for Mt-Clim and topographic partitioning may not be appropriate in this case. Instead, a deeper examination of the logic of this modeling activity may be needed before a productive approach can be found. In particular, the treatment of the compartments, state variables, state equations and flows comprising Forest BGC may yield an object-oriented model that can be applied to a wide range of process models.

We conclude that our ability to define scenarios for most processes, without radically changing our existing hierarchy, indicates that our domain model is capable of supporting the necessary modeling activities, and is resilient enough to absorb many changes. The fact that not all necessary scenarios are constructed here is not a failure of our modeling methodology or of the concept of domain analysis. Rather it reflects that even more detailed evaluation of some parts of the application domain may be necessary for the more detailed requirements analysis needed in the development of a particular application. We believe our success in scenario construction where our requirements analysis provides adequate information constitutes proof of our hypothesis.

#### CHAPTER VI

## CONCLUSIONS

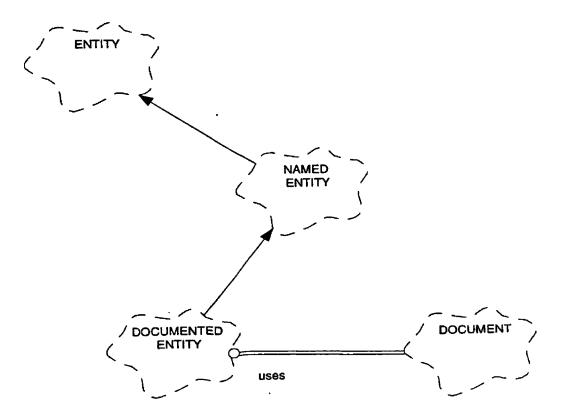
In keeping with the principles of the spiral model of design (Boehm88), this work is essentially our "first draft" in the attempt to provide a comprehensive view of ecosystem modeling and will no doubt be challenged, revised, and extended in future work. It has been suggested that the hierarchy be extended so that **numerical** and **categorical overlay** subclasses are defined on the basis of data content (e.g., class elevation overlay, aspect overlay). Currently, an overlay containing elevation data is an object of class **numerical overlay**. This extension would provide a much richer set of class names that reflect more closely the terminology used by workers in this application domain. We believe that our handling of modeling processes is a useful approach, but we are aware that additional work is needed, especially in cases where a significant level of human judgement is involved (e.g., supervised training). Additionally, a deeper examination of ecosystem process modeling is needed to adequately handle the needs of process modelers.

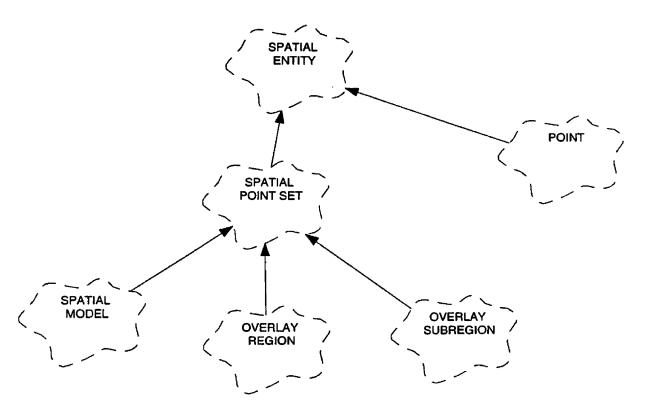
The work presented here provides a graphical and textual model of the domain of ecosystem modeling. This depiction of the modeling entities used by ecosystem modelers will serve as the foundation of the information design for the Ecosystem Information System (EIS) and will help them to better manage the models, software, modeling activities, and other tools used in their daily work. We hope that this work will help modelers working in this application domain to increase their productivity and facilitate the advance of their discipline.

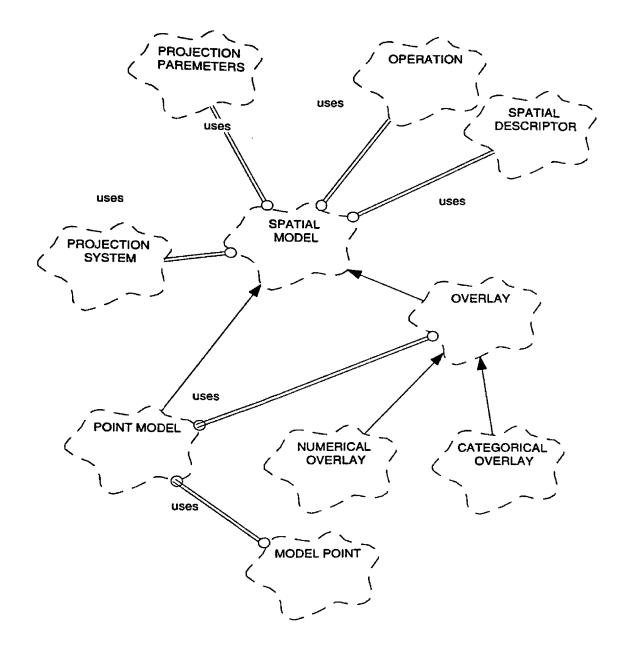
# APPENDIX I CLASS AND RELATIONSHIP DIAGRAMS

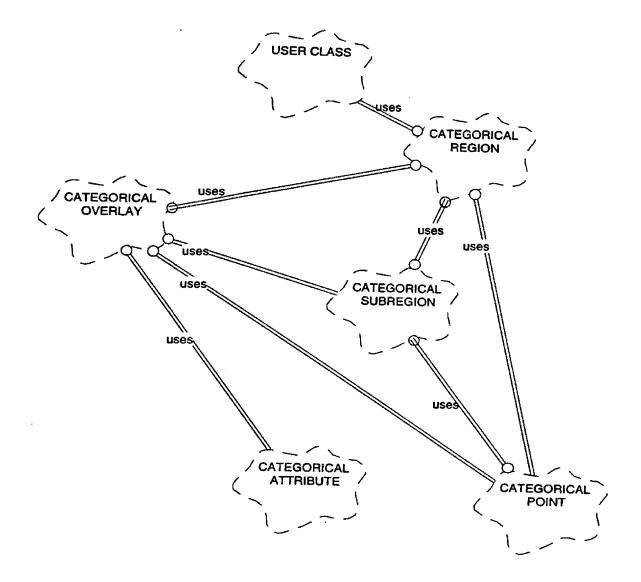
## TABLE OF CONTENTS

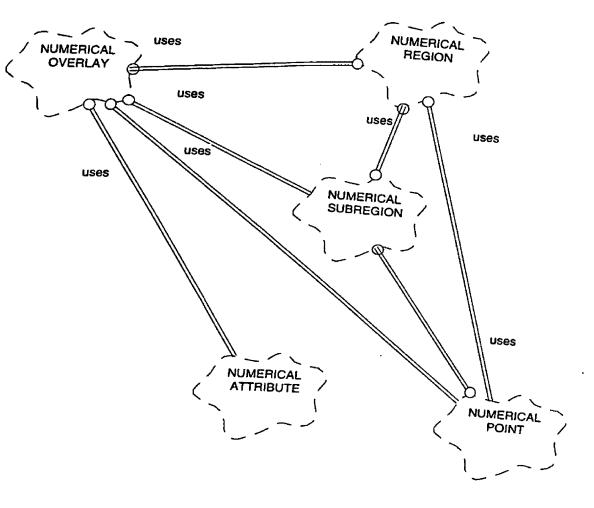
<u>Class</u> Group Name	p <u>age number</u>
1a. Root Entities	68
1b. Spatial Entities	69
1c. Ecosystem Entities	75
1d. Ecosystem Descriptor Entities	80
1e. Operation Entities	81
1f. Classification Entities	90
1g. Data Acquisition Entities	93
1h. Descriptor Entities	95
1i. Window Entities	96
1j. Software Entities	97
1k. Document Entities	99
11. Human & Group Entities	100

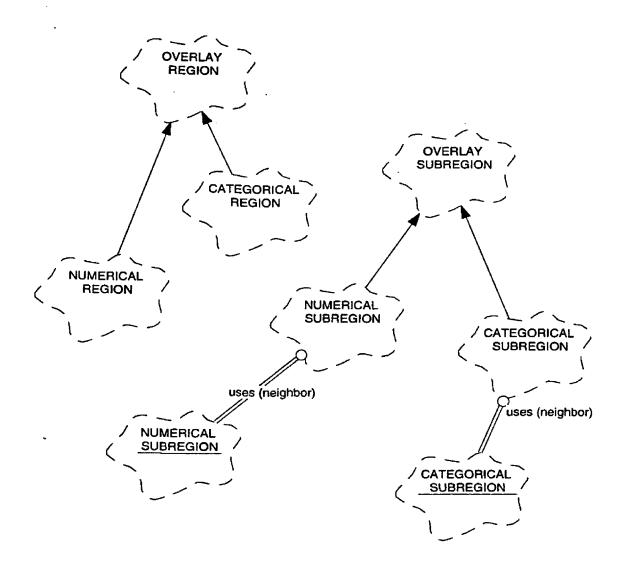


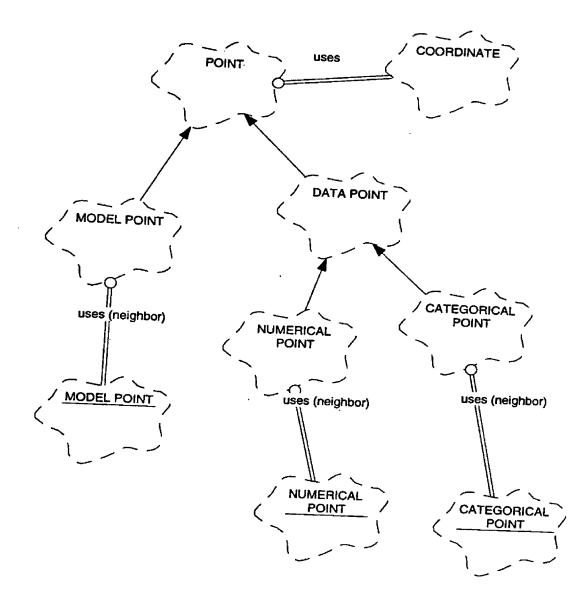


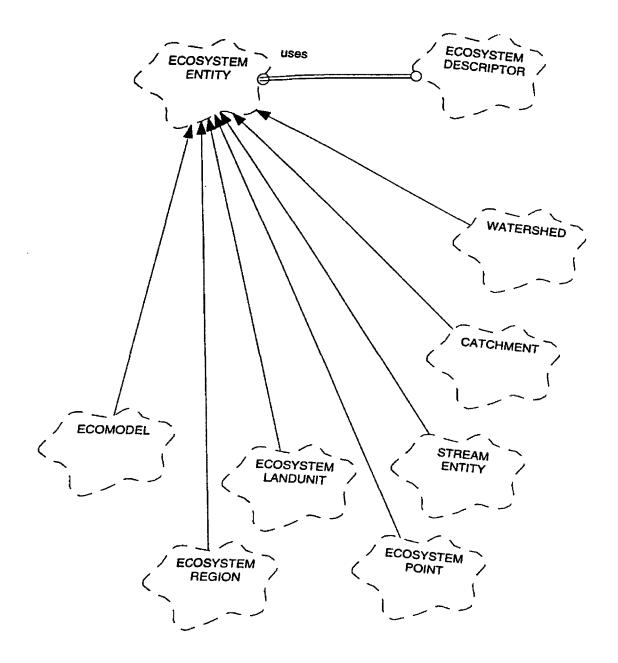


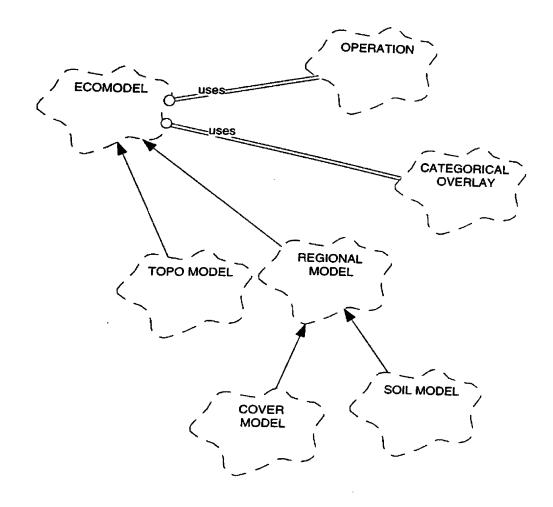


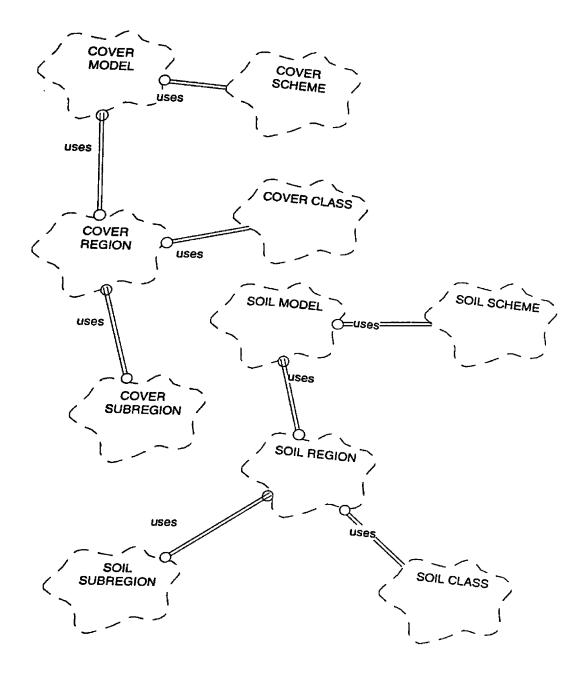




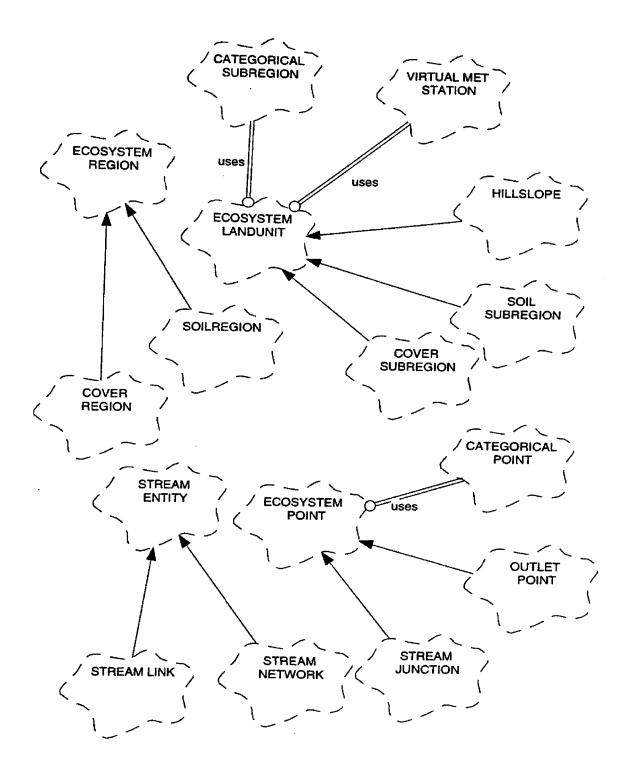


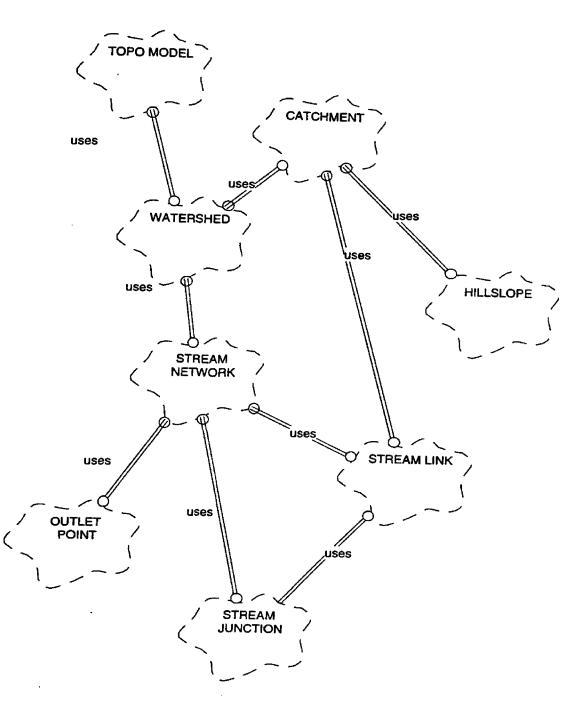


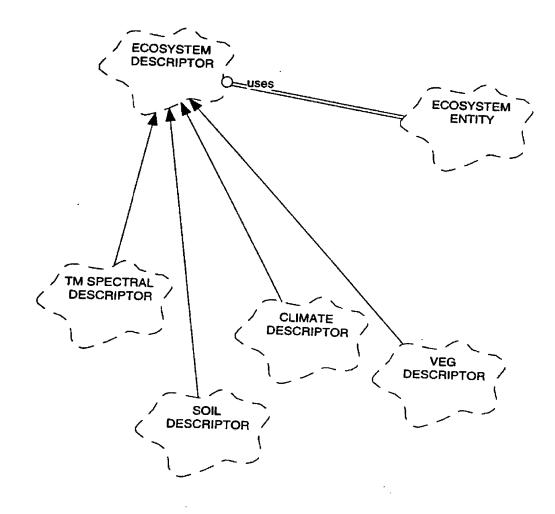


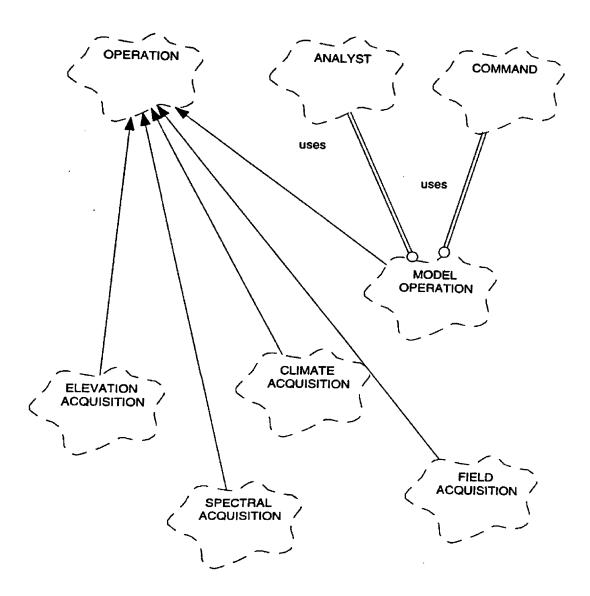


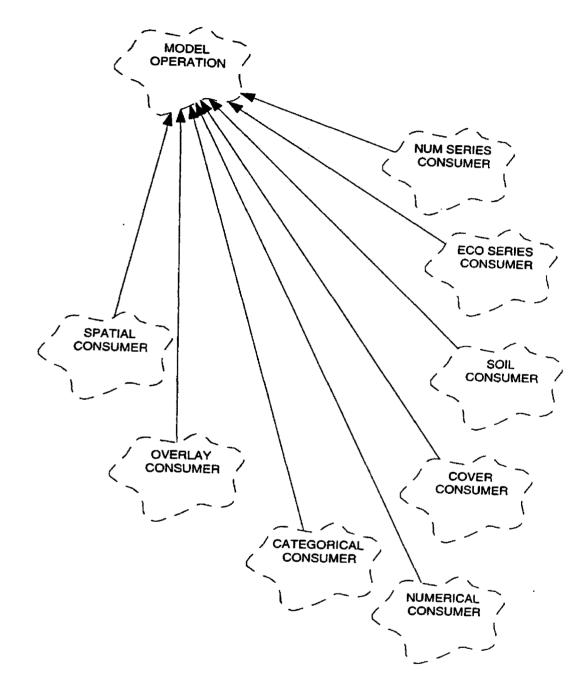
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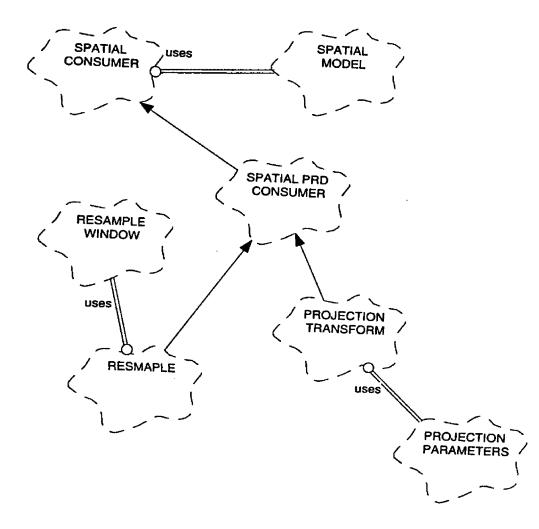


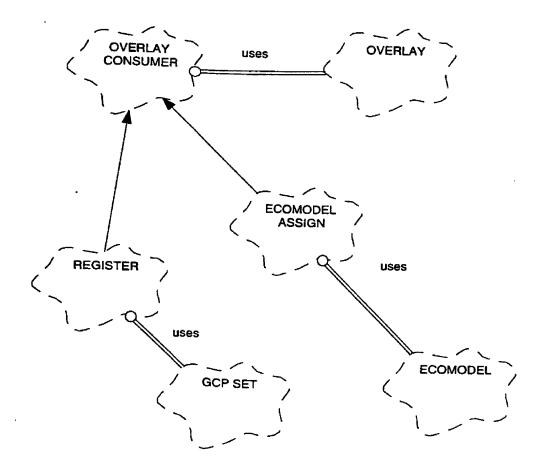




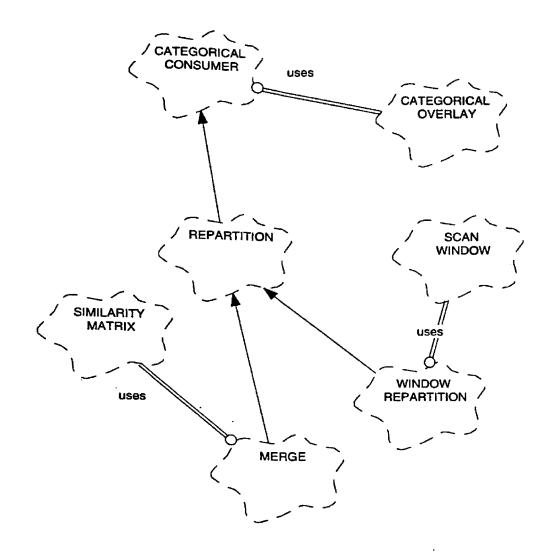


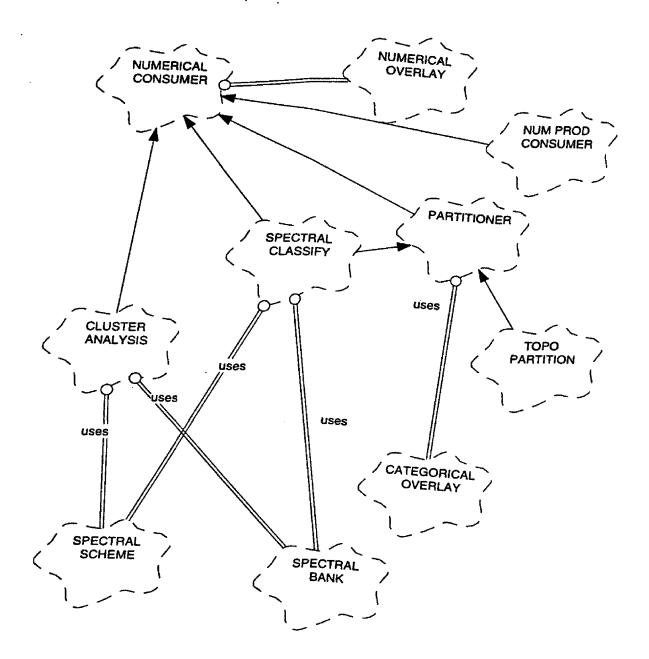


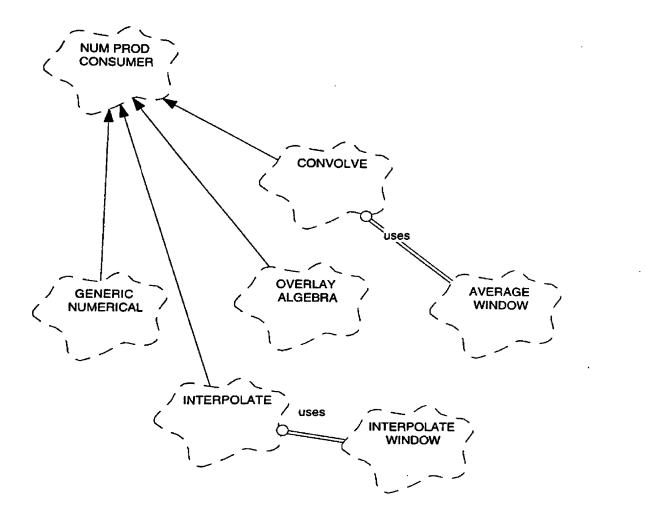


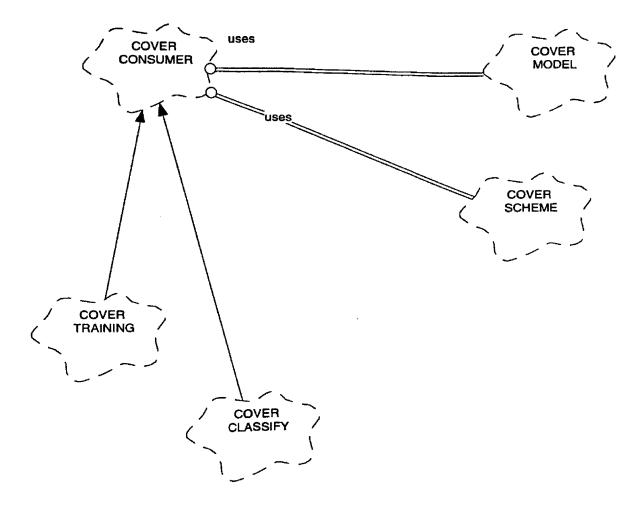


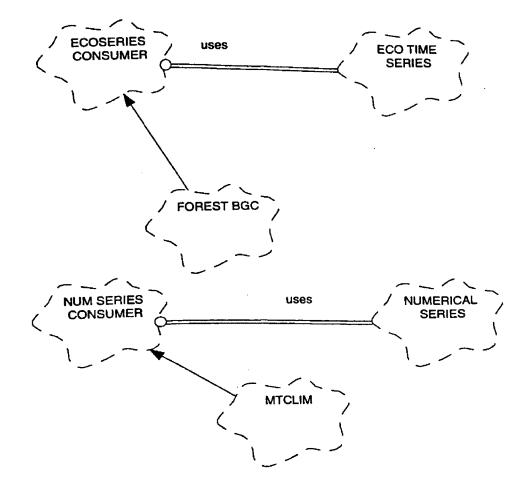
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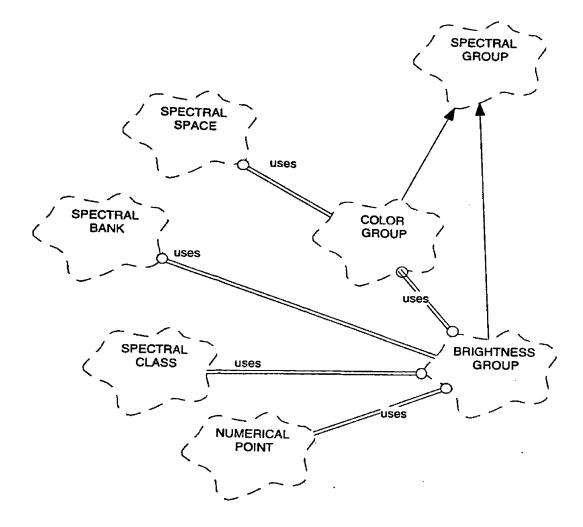


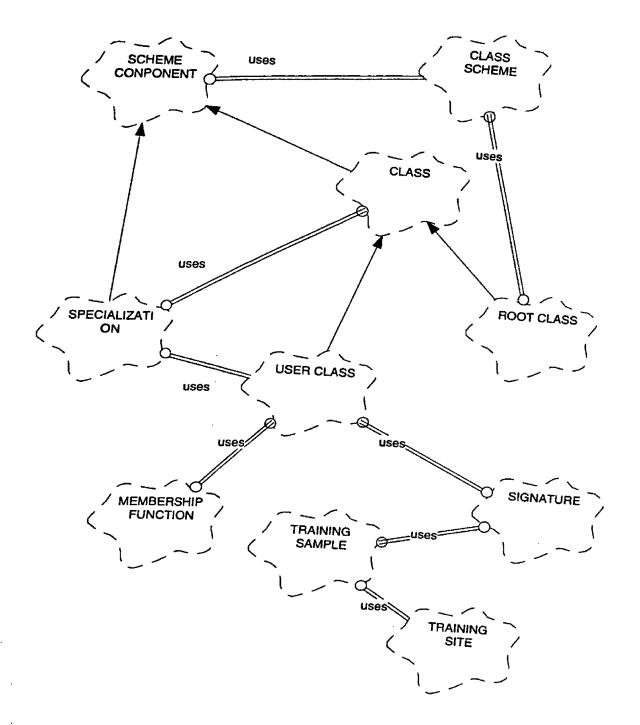


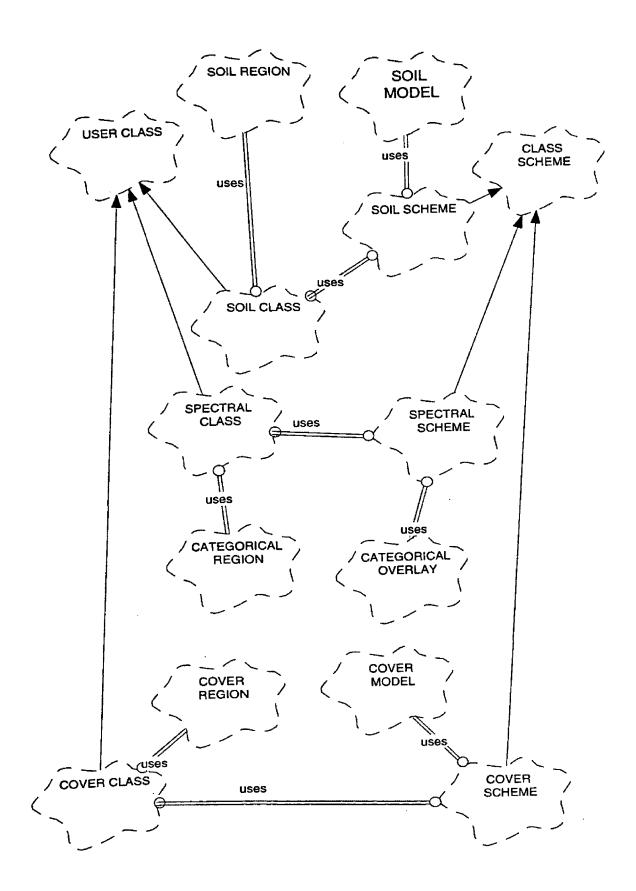


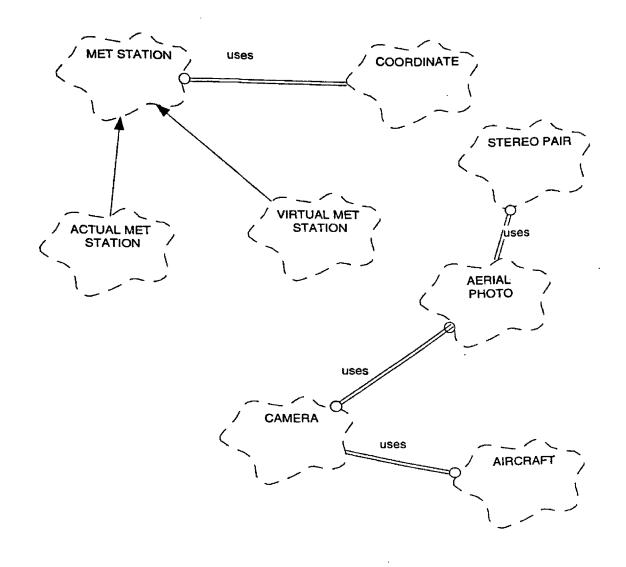


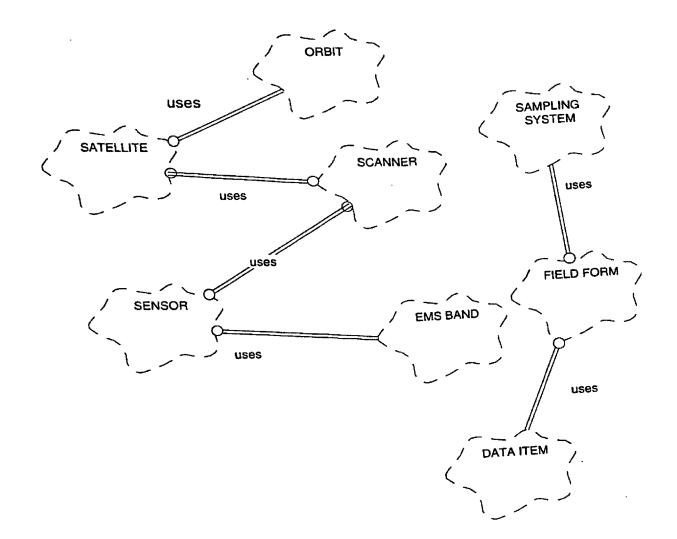


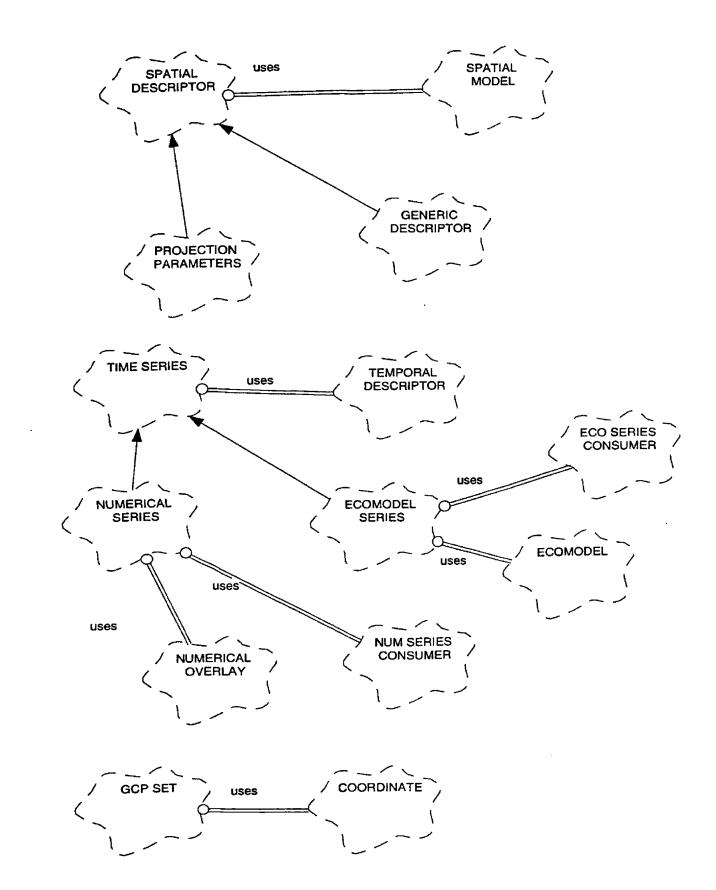


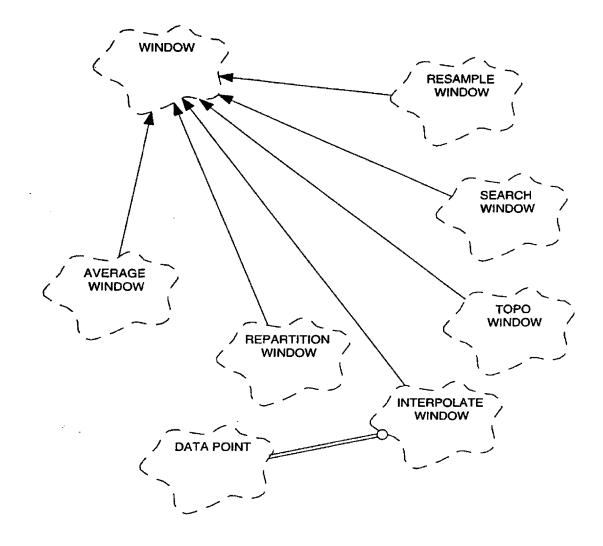


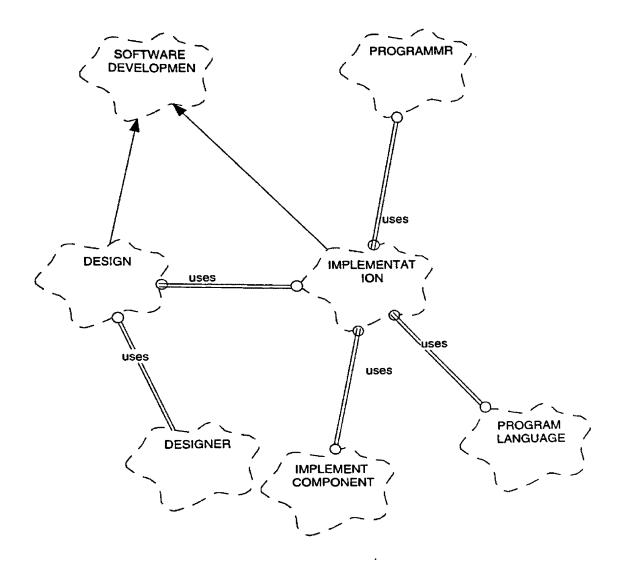


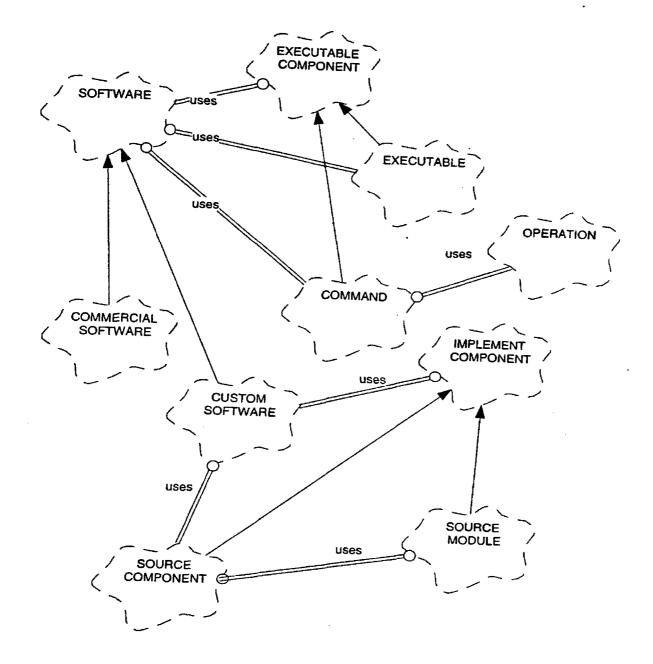


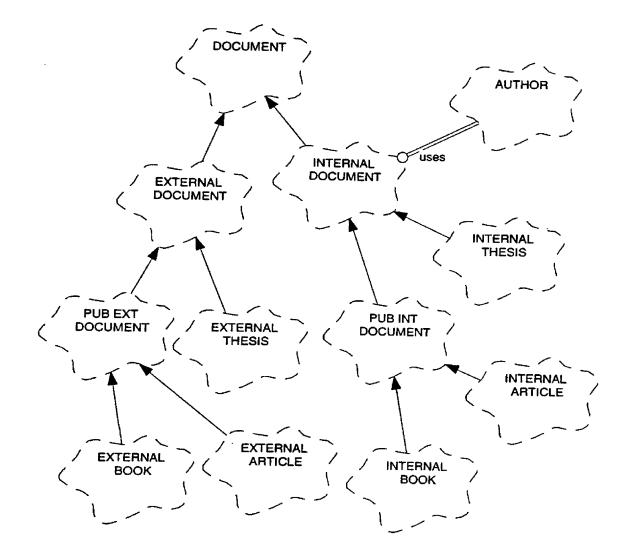


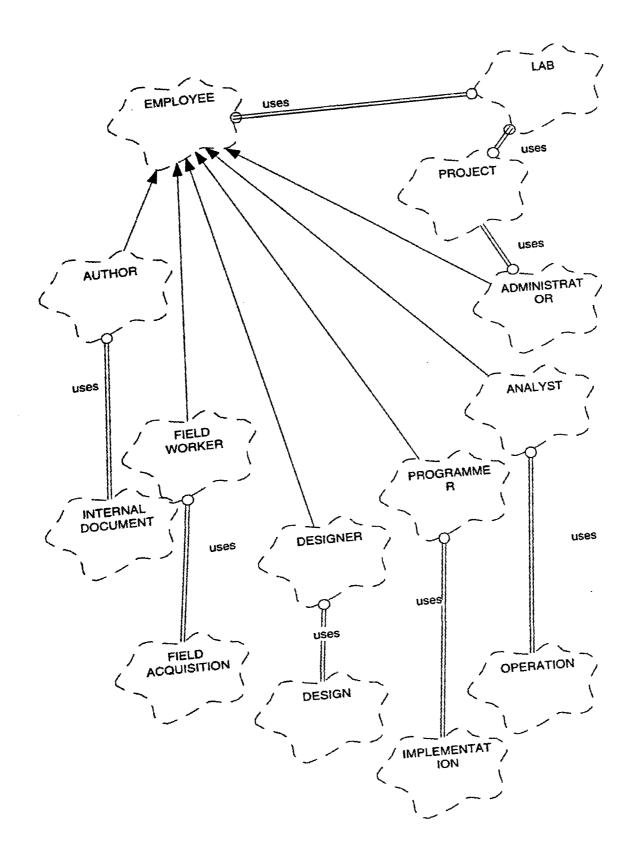












## **APPENDIX 2**

## CLASS SPECIFICATIONS

## TABLE OF CONTENTS

<u>Class</u> Group Name	p <u>age number</u>
2a. Root Classes	102
2b. Spatial Classes	103
2c. Ecosystem Classes	112
2d. Ecosystem Descriptor Classes	121
2e. Operation Classes	124
2f. Classification Classes	136
2g. Data Acquisition Classes	145
2h. Descriptor Classes	152
2i. Window Classes	155
2j. Software Classes	157
2k. Documentation Classes	162
21. Human Classes	165

## 2a. Root Classes

class {	ENTITY		
	/* attributes */ /* none */		
	/* operations */		
	Create Destroy		(void) ; (void) ;
};			
class {	NAMED_ENTITY : public	ENTITY	
	/* attributes */ STRING STRING		name;
			description ;
	/* operations */		
	STRING void		Get_name (void);
	STRING		Set_name (STRING); Get_description (void);
	void		Set_description (STRING);
};			
class {	DOCUMENTED_ENTITY	: public	NAMED_ENTITY
	/* attributes */ SET < DOCUMENT >		documents;
	/* operations */		
	DOCUMENT		Iterate_over_documents (void);
};			

class {	SPATIAL_ENTITY : public		DOCUMENTED_ENTITY
•	/* attributes */		
	NUMBER		area;
	NUMBER		perimeter;
	/* operations */		
	NUMBER		Get_area (void);
	void		Set_area (NUMBER) ;
	NUMBER		Get_perimeter (void);
	void		Set_perimeter (NUMBER);
};			
class {	SPATIAL_POINT_ENTITY	: public	SPATIAL_ENTITY
·	/* attributes */		
	NUMBER		number_points;
	/* operations */		
	NUMBER		Get_number_points (void);
	void		Set_number_points (NUMBER);
}:			

class SPATIAL\_MODEL

ł

/\* attributes \*/ STRING STRING STRING PROJECTION\_SYSTEM PROJECTION\_PARAMETERS SET < SPATIAL\_MODEL\_CONSUMER > OPERATION SET < SPATIAL\_DESCRIPTOR >

/\* operations \*/ STRING void STRING void STRING void PROJECTION\_SYSTEM void

PROJECTION\_PARAMETERS void

SPATIAL\_MODEL\_CONSUMER OPERATION void SPATIAL\_DESCRIPTOR SPATIAL\_POINT\_SET

spatial\_scale ;
geog\_coord\_system ;
point\_distribution ;
projection\_system ;
projection\_parameters ;
consuming\_operations ;
producing\_operation ;
spatial\_descriptors ;

Get\_spatial\_scale (void); Set\_spatial\_scale (STRING); Get\_geog\_coord\_system (void); Set\_geog\_coord\_system (STRING); Get\_point\_distribution (void); Set\_point\_distribution (STRING); Get\_projection\_system (void); Set\_projection\_system (PROJECTION\_SYSTEM); Get\_projection\_parameters (void); Set\_projection\_parameters (PROJECTION\_PARAMETERS); Iterate\_over\_consuming\_operations (void); Get\_producing\_operation (void); Set\_producing\_operation (OPERATION); Iterate\_over\_spatial\_descriptors

class POINT\_MODEL : public

/* attributes */ SET < MODEL_POINT > NUMBER NUMBER SET < OVERLAY >	<pre>model_points ; number_numerical_overlays ; number_categorical_overlays ; overlays ;</pre>
/* operations */	
MODEL_POINT	Iterate_over_model_points (void);
NUMBER	Get_number_numerical_overlays (void);
void	Set_number_numerical_overlays (NUMBER);
NUMBER	Get_number_categorical_overlays (void);
void	Set_number_categorical_overlays (NUMBER);
OVERLAY	Iterate_over_overlays (void);
MODEL_POINT	Get_point (COORDINATE);
void	Set_point (MODEL_POINT);
MODEL_POINT	Sample_points (void0;

};

ł

class OVERLAY : public

SPATIAL\_MODEL

{

/\* attributes \*/ NUMBER NUMBER NUMBER POINT\_MODEL SET < OVERLAY\_CONSUMER >

/\* operations \*/ NUMBER void NUMBER void NUMBER void POINT\_MODEL void Get\_number\_regions (void); Set\_number\_regions (NUMBER); Get\_number\_subregions (void); Set\_number\_subregions (NUMBER); Get\_number\_points (void); Set\_number\_points (NUMBER); Get\_point\_model (void);

Set\_point\_model (POINT\_MODEL);

number\_regions;

number\_points;

contained\_in;

number\_subregions;

consuming\_operations;

};

class NUMERICAL\_OVERLAY

/\* attributes \*/ SET < NUMERICAL\_REGION > SET < NUMERICAL\_SUBREGION > SET < NUMERICAL\_POINT > NUMERICAL\_ATTRIBUTE SET < NUMERICAL\_CONSUMER >

/\* operations \*/ NUMERICAL\_REGION NUMERICAL\_SUBREGION NUMERICAL\_POINT NUMERICAL\_ATTRIBUTE void

NUMERICAL\_CONSUMER NUMERICAL\_OVERLAY NUMERICAL\_OVERLAY NUMERICAL\_OVERLAY NUMERICAL\_OVERLAY NUMERICAL\_POINT void NUMERICAL\_POINT

### OVERLAY

regions ; subregions ; points ; describing\_attribute ; consuming\_operations ;

Iterate\_over\_regions (void); Iterate\_over\_subregions (void); Iterate\_over\_points (void); Get\_describing\_attribute (void); Set\_describing\_attribute (NUMERICAL\_ATTRIBUTE); Iterate\_over\_consuming\_operations (void); Add (NUMERICAL\_OVERLAY); Subtract (NUMERICAL\_OVERLAY); Multiply (NUMERICAL\_OVERLAY); Divide (NUMERICAL\_OVERLAY); Get\_point (COORDINATE); Set\_point (NUMERICAL\_POINT); Sample\_points (void);

};

{

#### CATEGORICAL\_OVERLAY : public **OVERLAY** /\* attributes \*/ SET < CATEGORICAL\_REGION > regions; SET < CATEGORICAL\_SUBREGION > subregions; SET < CATEGORICAL\_POINT > points : CATEGORICAL\_ATTRIBUTE describing\_attribute; SET < CATEGORICAL\_CONSUMER > consuming\_operations; /\* operations \*/ CATEGORICAL\_REGION Iterate\_over\_regions (void); CATEGORICAL\_SUBREGION Iterate\_over\_subregions (void); CATEGORICAL\_POINT Iterate\_over\_points (void); CATEGORICAL\_ATTRIBUTE Get\_describing\_attribute (void); void Set\_describing\_attribute CATEGORICAL\_CONSUMER CATEGORICAL\_POINT Get\_point (COORDINATE); void CATEGORICAL\_POINT Sample\_points (void);

};

class

ſ

class	OVERLAY_REGION	: public	SPATIAL_POINT_ENTITY
ι	/* attributes */		
	NUMBER		number_subregions;
	/* operations */		
	NUMBER		Get_number_subregions (void);
	void		Set_number_subregions (NUMBER);
1.			

};

(CATEGORICAL\_ATTRIBUTE); Iterate\_over\_consuming\_operations (void); Set\_point (CATEGORICAL\_POINT);

class CATEGORICAL\_REGION : public

ł

/\* attributes \*/ CATEGORICAL\_OVERLAY SET < CATEGORICAL\_SUBREGION > SET < CATEGORICAL\_POINT > USER\_CLASS

/\* operations \*/ CATEGORICAL\_OVERLAY void

CATEGORICAL\_SUBREGION CATEGORICAL\_POINT USER\_CLASS void void

};

class NUMERICAL\_REGION : public

{

/\* attributes \*/ NUMERICAL\_OVERLAY SET < NUMERICAL\_SUBREGION > SET <NUMERICAL\_POINTS >

/\* operations \*/ NUMERICAL\_OVERLAY void

NUMERICAL\_SUBREGION NUMERICAL\_POINT

};

OVERLAY\_REGION

containing\_overlay; subregions; points; class;

Get\_containing\_overlay (void); Set\_containing\_overlay (CATEGORICAL\_OVERLAY); Iterate\_over\_subregions (void); Iterate\_over\_points (void); Get\_class (void); Set\_class (USER\_CLASS); Set\_subregion (CATEGORICAL\_SUBREGION);

### OVERLAY\_REGION

containing\_overlay; subregions; points;

Get\_containing\_overlay (void); Set\_containing\_overlay (NUMERICAL\_OVERLAY); Iterate\_over\_subregions (void); Iterate\_over\_points (void);

class {	OVERLAY_SUBREGION : public	SPATIAL_POINT_ENTITY
·	/* attributes */ NUMBER	number_neighbors;
	/* operations	
	NUMBER	Get_number_neighbors (void);
	void	Set_number_neighbors (NUMBER);
};		
class {	CATEGORICAL_SUBREGION : public	OVERLAY_SUBREGION
-	/* attributes */	
	CATEGORICAL_REGION	containing_region;
	SET < CATEGORICAL_POINT >	points;
	SET <categorical_subregion></categorical_subregion>	neighbors;
	/* operations */	
	CATEGORICAL_REGION void	Get_containing_region (void); Set_containing_region
		(CATEGORICAL_REGION);
	CATEGORICAL_POINT	Iterate_over_points (void);
	CATEGORICAL_SUBREGION	Iterate_over_neighbors (void);
};		
class	NUMERICAL_SUBREGION : public SPATIAL_	POINT_SET
{	/* attributes */	
	NUMERICAL_REGION	containing_region;
	SET < NUMEGORICAL_POINT >	points;
	SET < NUMERICAL_SUBREGION >	neighbors;
	/* operations */	
•	NUMERICAL_REGION	Get_containing_region (void);
	void	Set_containing_region
		(NUMERICAL_REGION);
	NUMERICAL_POINT	Iterate_over_points (void);
	NUMERICAL_SUBREGION	Iterate_over_neighbors (void);
};		

109

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class {	POINT	: public	SPATIAL_ENT	ΙΤΥ
l	/* attributes */			
	COORDINATE			coord ;
	/* operations */			
	COORDINATE			Get_coord (void);
};	void			Set_coord (COORDINATE);
class	DATA_POINT	public :	POINT	
{				
	/* attributes */			
	NUMBER			value;
	/* operations */			
	NUMBER			Get_value (void);
};	void			Set_value (NUMBER);
•••				
class	NUMERICAL_I	POINT	: public	DATA_POINT
{	/* attributes */			
	NUMERICAL_	SUBREGION		containing_subregion;
	/* operations */			
	NUMERICAL_S	SUBREGION		Get_containing_subregion (void);
	void			Set_containing_subregion
	NUDADED			(NUMERICAL_SUBREGION); Add (NUMERICAL_POINT);
	NUMBER NUMBER			Subtract (NUMERICAL_POINT);
	NUMBER			Multiply (NUMERICAL_POINT);
	NUMBER			Divide (NUMERICAL_POINT);
};				

.

110

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class CATEGORICAL\_POINT : public

ſ

/\* attributes \*/ CATEGORICAL\_SUBREGION

/\* operations \*/ CATEGORICAL\_SUBREGION void

};

class MODEL\_POINT { /\* attributes \*/ POINT\_MODEL

> /\* operations \*/ POINT\_MODEL void

VALUE\_POINT

containing\_subregion;

Get\_containing\_subregion (void); Set\_containing\_subregion (CATEGORICAL\_SUBREGION);

POINT

: public

containing\_point\_model;

Get\_point\_model (void); Set\_point\_model (POINT\_MODEL);

2c. Ecosystem Classes

class {	ECOSYSTEM_ENTITY	: public	DOCUMENTED_ENTITY
	/* attributes */ SET < ECOSYSTEM DESCRIPTO	OR >	ecosystem_descriptors;
};	/* operations */ ECOSYSTEM_DESCRIPTOR		Iterate_over_ecosystem_descriptors (void);
class {	ECOMODEL : public	ECOSYSTEM_I	ENTITY
t	/* attributes */ NUMBER CATEGORICAL_OVERLAY OPERATION SET < ECOMODEL_CONSUME	R >	number_landunits; corresponding_overlay; producer; ecomodel_consumers;
,	/* operations */ NUMBER void CATEGORICAL_OVERLAY void OPERATION void ECOSYSTEM_MODEL_CONSUL	MER	Get_number_landunits (void); Set_number_landunits (NUMBER); Get_correspondin_overlay (void); Set_corresponding_overlay (CATEGORICAL_OVERLAY); Get_producer (void); Set_producer (OPERATION); Iterate_over_ecosystem_model_consumers (void);
};			
class {	REGIONAL_MODEL	: public	ECOMODEL
	/* attributes */ NUMBER		number_regions;
};	/* operations */ NUMBER void		Get_number_regions (void); Set_number_regions (NUMBER);

class SOIL\_MODEL : public

REGIONAL\_MODEL

{

/\* attributes \*/ SET < SOIL\_REGION > SOIL\_CLASS\_SCHEME SET < SOIL\_MODEL\_CONSUMER >

/\* operations \*/ SOIL\_REGION SOIL\_CLASS\_SCHEME void

SOIL\_MODEL\_CONSUMER

### };

class COVER\_MODEL : public REGIONAL\_MODEL
{
 /\* attributes \*/
 SET < COVER\_REGION > cover
 COVER\_REGION > cover
 cover

COVER\_CLASS\_SCHEME SET < COVER\_MODEL\_CONSUMER > SET < COVER\_SUBREGION > SET < COVER\_SUBREGION >

/\* operations \*/ COVER\_REGION COVER\_CLASS\_SCHEME void

COVER\_MODEL\_CONSUMER COVER\_SUBREGION COVER\_SUBREGION soil\_regions ;
describing\_class\_scheme ;
soil\_model\_consumers ;

Iterate\_over\_soil\_regions (void); Get\_soil\_class\_scheme (void); Set\_soil\_class\_scheme (SOIL\_CLASS\_SCHEME); Iterate\_over\_soil\_model\_consumers (void);

cover\_regions ;
describing\_class\_scheme ;
cover\_model\_consumers ;
training\_sites ;
cover\_subregions ;

Iterate\_over\_cover\_regions (void); Get\_cover\_class\_scheme (void); Set\_cover\_class\_scheme (COVER\_CLASS\_SCHEME); Iterate\_cover\_model\_consumers (void); Iterate\_over\_training\_sites (void); Iterate\_over\_cover\_subregions (void);

class {	TOPO_MODEL : public	ECOMODEL	
ι	/* attributes */ NUMBER SET < WATERSHED >		number_watersheds; watersheds;
.};	/* operations */ NUMBER void WATERSHED		Get_number_watersheds (void); Set_number_watersheds (NUMBER); Iterate_over_watersheds (void);
class {	ECOSYSTEM_REGION	: public	ECOSYSTEM_ENTITY
ι	/* attributes */ NUMBER		number_subregions;
};	/* operations */ NUMBER void		Get_number_subregions (void); Set_number_subregions (NUMBER);
class	COVER_REGION	: public	ECOSYSTEM_REGION
{	/* attributes */ COVER_MODEL SET < COVER_SUBREGION > COVER_CLASS		<pre>containing_model ; cover_subregions ; describing_class ;</pre>
	/* operations */ COVER_MODEL void COVER_SUBREGION COVER_CLASS void void		Get_containing_model (void); Set_containing_model (COVER_MODEL); Iterate_over_cover_subregions (void); Get_cover_class (void); Set_cover_class (COVER_CLASS); Set_cover_subregion (COVER_SUBREGION);

};

•

class {	SOIL_REGION : public	ECOSYSTEM_	REGION
L	/* attributes */		
	SOIL_MODEL		containing_model;
	SET < SOIL_SUBREGION >		soil_subregions;
	SOIL_CLASS		describing_class;
	/* operations */		
	SOIL_MODEL		Get_containing_model (void);
	void		Set_containing_model (SOIL_MODEL);
	SOIL_SUBREGION		Iterate_over_soil_subregions (void);
	SOIL_CLASS		Get_soil_class (void) ;
	void		Set_soil_class (SOIL_CLASS);
};			
class {	ECOSYSTEM_LANDUNIT	: public	ECOSYSTEM_ENTITY
·	/* attributes */		
	CATEGORICAL_SUBREGION		categorical_subregion;
	VIRTUAL_MET_STATION		virtual_climate;
	/* operations */		
	CATEGORICAL_SUBREGION		Get_categorical_subregion (void);
	void		Set_categorical_subregion
			(CATEGORICAL_SUBREGION),
	VIRTUAL_MET_STATION		Get_virtual_met_station (void);
	void		Set_virtual_climate
			(VIRTUAL_MET_STATION);
};			
class {	COVER_SUBREGION	: public	ECOSYSTEM_LANDUNIT
-	/* attributes */		
	COVER_REGION		containing_region;
	/* operations */		
	COVER_REGION		Get_region (void);

Set\_region (COVER\_REGION);

};

void

•

class	SOIL_SUBREGION	: public	ECOSYSTEM_LANDUNIT
L	/* attributes */		
	SOIL_REGION		containing_region;
	/* operations */		
	SOIL_REGION		Get_containing_region (void);
	void		Set_containing_region (SOIL_REGION);
};			
class {	WATERSHED : public	ECOSYSTEM_	ENTITY
-	/* attributes */		
	TOPO_MODEL		containing_model;
	SET < CATCHMENT >		catchments;
	STREAM_NETWORK		stream_network;
	/* operations */		
	TOPO_MODEL		Get_containing_model (void);
	void		Set_containing_model (TOPO_MODEL);
	CATCHMENT		Iterate_over_catchments (void);
	STREAM_NETWORK		Get_stream_network (void);
	void		Set_stream_network
			(STREAM_NETWORK);

116

.

/* attributes */	
WATERSHED	containing_watershed;
HILLSLOPE	left_hillslope ;
HILLSLOPE	right_hillslope;
STREAM_LINK	stream_link ;
/* operations */	
WATERSHED	Get_containing_watershed (void);
void	Set_containing_watershed
	(WATERSHED);
HILLSLOPE	Get_left_hillslope (void);
void	Set_left_hillslope (HILLSLOPE);
HILLSLOPE	Get_right_hillslope (void);
void	Set_right_hillslope (HILLSLOPE);
STREAM_LINK	Get_stream_link (void);
void	Set stream link (STREAM LINK);

};

class {	HILLSLOPE	: public	ECOSYSTEM_LANDU	NIT
-	/* attributes */ CATCHMENT		contair	ning_catchment;
	/* operations */ CATCHMENT void		Set_co	ontaining_catchment (void); ntaining_catchment CATCHMENT);

class STREAM\_ENTITY : public ECOSYSTEM\_ENTITY

{

};

Ł

};

class

```
/* attributes */
NUMBER
                                             length;
NUMBER
                                             order;
/* operations */
NUMBER
                                             Get_length (void);
void
                                             Set_length (NUMBER);
NUMBER
                                             Get_order (void);
void
                                             Set_order (NUMBER);
                              : public
                                             STREAM_ENTITY
STREAM_NETWORK
/* attributes */
WATERSHED
                                             containing_watershed;
OUTLET_POINT
                                             outlet_point;
SET < STREAM_JUNCTION >
                                             stream_junctions;
SET < STREAM_LINK >
                                             stream_links;
                                             number_junctions;
NUMBER
NUMBER
                                             number_links;
/* operations */
WATERSHED
                                              Get_containing_watershed (void);
void
                                              Set_containing_watershed
                                                  (WATERSHED);
                                             Get_outlet_point (void);
OUTLET_POINT
                                              Set_outlet_point (OUTLET_POINT);
voiđ
                                              Iterate_over_stream_junctions (void);
STREAM_JUNCTION
                                              Iterate_over_stream_links (void);
STREAM_LINK
                                              Get_number_junctions (void);
NUMBER
                                              Set_number_junctions (NUMBER);
void
                                              Get_number_links (void);
NUMBER
                                              Set_number_links (NUMBER) ;
void
```

class STREAM\_LINK : public

### STREAM\_ENTITY

/* attributes */	
STREAM_JUNCTION	
STREAM_JUNCTION	
CATCHMENT	
STREAM_NETWORK	

/\* operations \*/ STREAM\_JUNCTION void STREAM\_JUNCTION void CATCHMENT void STREAM\_NETWORK void flows\_to; flows\_from; containing\_catchment; containing\_network;

Get\_flows\_to (void); Set\_flows\_to (STREAM\_JUNCTION); Get\_flows\_from (void); Set\_flows\_from (STREAM\_JUNCTION); Get\_catchment (void); Set\_catchmetn (CATCHMENT); Get\_containing\_network (void); Set\_containing\_network (STREAM\_NETWORK);

};

ł

class {	ECOSYSTEM_POINT	: public	ECOSYSTEM_ENTITY
	/* attributes */ CATEGORICAL_POINT		categorical_point;
	/* operations */ CATEGORICAL_POINT void		Get_categorical_point (void); Set_categorical_point (CATEGORICAL_POINT);

class {	STREAM_JUNCTION	: public	ECOSYSTEM_POINT
·	/* attributes */ STREAM_NETWORK NUMBER SET < STREAM_LINK > STREAM_LINK		<pre>containing_stream_network ; number_inflows ; inflows ; outflow ;</pre>
	/* operations */ STREAM_NETWORK void		Get_containing_stream_network (void); Set_containing_stream_network (STREAM_NETWORK);
	NUMBER void STREAM_LINK		Get_number_inflows (void); Set_number_inflows (NUMBER); Iterate_over_inflows (void);
	STREAM_LINK void		Get_outflow (void); Set_outflow (STREAM_LINK);
};			
class {	OUTLET_POINT	: public	ECOSYSTEM_POINT
-	/* attributes */ STREAM_NETWORK		containing_stream_network;
};	/* operations */ STREAM_NETWORK void		Get_containing_stream_network (void); Set_containing_stream_network (STREAM_NETWORK);
• •			

# 2d. Ecosystem Descriptor Classes

class {	ECOSYSTEM_DESCRIPTOR : public	DOCUMENTED_ENTITY
	/* attributes */	
	ECOSYSTEM_ENTITY	described_ecosystem_entity;
	/* operations */	
	ECOSYSTEM_ENTITY	Get_described_ecosystem_entity (void);
	void	Set_described_ecosystem_entity (ECOSYSTEM_ENTITY);
};		
class {	TM_SPECTRAL_DESCRIPTOR : public	ECOSYSTEM_DESCRIPTOR
•	/* attributes */	
	NUMBER	tm_1 ;
	NUMBER	tm_2 ;
	NUMBER	tm_3 ;
	NUMBER	tm_4 ;
	NUMBER	tm_5;
	NUMBER	tm_6;
	NUMBER	tm_7 ;
	/* operations */	
	NUMBER	Get_tm_1 (void);
	void	Set_tm_1 (NUMBER);
	NUMBER	Get_tm_2 (void);
	void	Set_tm_2 (NUMBER);
	NUMBER	Get_tm_3 (void);
	void	Set_tm_3 (NUMBER);
	NUMBER	Get_tm_4 (void);
	void	Set_tm_4 (NUMBER);
	NUMBER	Get_tm_5 (void);
	void	Set_tm_5 (NUMBER);
	NUMBER	Get_tm_6 (void);
	void	Set_tm_6 (NUMBER);
	NUMBER	Get_tm_7 (void);
	void	Set_tm_7 (NUMBER);

•

class SOIL\_DESCRIPTOR

{

/* attributes */	
NUMBER	depth;
NUMBER	texture;
NUMBER	hydraulic_conductivity;
NUMBER	transmissivity ;
NUMBER	water_capacity;
NUMBER	available_water;
NUMBER	temperature;
NUMBER	carbon;
NUMBER	nitrogen ;
/* operations */	
NUMBER	Get_depth (void);
void	Set_depth (NUMBER);
NUMBER	Get_texture (void);
void	Set_texture (NUMBER);
NUMBER	Get_hydraulic_conductivity (void);
void	Set_hydraulic_conductivity (NUMBER);
NUMBER	Get_transmissivity (void);
void	Set_transmissivity (NUMBER);
NUMBER	Get_water_capacity (void);
void	Set_water_capacity (NUMBER);
NUMBER	Get_available_water (void);
void	Set_available_water (NUMBER);
NUMBER	Get_temperature (void);
void	Set_temperature (NUMBER);
NUMBER	Get_carbon (void);
void	Set_carbon (NUMBER);
NUMBER	Get_nitrogen (void);
void	Set_nitrogen (void);

class {	CLIMATE_DESCRIPTOR	: public	LANDUNIT_DESCRIPTOR
1	/* attributes */		
	NUMBER		maximum_temperature;
	NUMBER		minimum_temperature;
	NUMBER		dew_point;
	NUMBER		shortwave_radiation;
	NUMBER		precipitation;
	/* operations */		
	NUMBER		Get_maximum_temperature (void);
	void		Set_maximum_temperature (NUMBER);
	NUMBER		Get_minimum_temperature (void);
	void		Set_minimum_temperature (NUMBER);
	NUMBER		Get_dew_point (void);
	void		Set_dew_point (NUMBER);
	NUMBER		Get_shortwave_radiation (void);
	void		Set_shortwave_radiation (NUMBER);
	NUMBER		Get_precipitation (void);
	void		Set_precipitation (NUMBER);
};			
class {	VEG_DESCRIPTOR	: public	ECOSYSTEM_DESCRIPTOR
	/* attributes */		
	NUMBER		gross_primary_production;
	NUMBER		net_primary_production;
	NUMBER		maintenance_carbon;
	NUMBER		growth_carbon;
	/* operations */		
	NUMBER		Get_gross_primary_production (void);
	void		Set_gross_primary_production (NUMBER);
	NUMBER		Get_net_primary_production (void);
	void		Set_net_primary_production (NUMBER);
	NUMBER		Get_maintenance_carbon (void);
	void		Set_maintenance_carbon (NUMBER);
			Set_maintenance_carbon (NUMBER); Get_growth_carbon (void);
	void		

};

2e. Operation Classes

class {	OPERATION : public	DOCUMENTEI	D_ENTITY
ı	/* attributes */ DATE TIME		date_performed; time_performed;
};	/* operations */ DATE void TIME void void		Get_date_performed (void); Set_date_performed (DATE); Get_time_performed (void); Set_time_performed (TIME); Perform (void);
class {	MODEL_OPERATION	: public	OPERATION
	/* attributes */		
	ANALYST		performed_by;
	COMMAND		used_command;
};	/* operations */ ANALYST void COMMAND void		Get_analyst (void); Set_analyst (ANALYST); Get_command (void); Set_command (COMMAND);
class	SPATIAL_CONSUMER : public	MODEL_OPER	ATION
{	/* attributes */ SPATIAL_MODEL		input;
};	/* operations */ SPATIAL_MODEL void		Get_input (void); Set_input (SPATIAL_MODEL);

class SPATIAL\_PRD\_CONSUMER : public SPATIAL\_CONSUMER ł /\* attributes \*/ SPATIAL\_MODEL output; /\* operations \*/ SPATIAL\_MODEL Get\_output (void); void Set\_output (SPATIAL\_MODEL); }; PROJECTION\_TRANSFORM : public SPATIAL\_PRD\_CONSUMER class ł /\* attributes \*/ **PROJECTION\_PARAMETERS** parameters; /\* operations \*/ PROJECTION\_PAREMETERS Get\_paramters (void); void Set\_parameters (PROJECTION\_PAREMETERS); 1; class RESAMPLE : public SPATIAL\_PRD\_CONSUMER ſ /\* attributes \*/ RESAMPLE\_WINDOW window; /\* operations \*/ Get\_window (void); RESAMPLE\_WINDOW Set\_window (RESAMPLE\_WINDOW); void }; class OVERLAY\_CONSUMER : public MODEL\_OPERATION ł /\* attributes \*/ **OVERLAY** input; /\* operations \*/ **OVERLAY** Get\_overlay (void); Set\_overlay (OVERLAY); void

};

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class {	REGISTER : public	OVERLAY_CONSUMER	
ſ	/* attributes */ OVERLAY GCP_SET OVERLAY		<pre>input_slave ; ground_control_points ; output_slave ;</pre>
	/* operations */ OVERLAY void GCP_SET void		Get_input_slave (void); Set_input_slave (OVERLAY); Get_ground_control_points (void); Set_ground_control_points (GCP_SET);
	OVERLAY		Get_output_slave (void);
};	void		Set_output_slave (OVERLAY);
class {	ECOMODEL_ASSIGN	: public	OVERLAY_CONSUMER
	/* attributes */ ECOMODEL		output;
	/* operations */ ECOMODEL void		Get_output (void) ; Set_output (ECOMODEL) ;
};	Vold		Sci_ouput (Ecomobel),
class {	CATEGORICAL_CONSUMER	: public	MODEL_OPERATION
t	/* attributes */ CATEGORICAL_OVERLAY		input;
};	/* operations */ CATEGORICAL_OVERLAY void		Get_input (void); Set_input (CATEGORICAL_OVERLAY);

class {	REPARTITION : public	CATEGORICAL	_CONSUMER
	/* attributes */ CATEGORICAL_OVERLAY		output;
1.	/* operations */ CATEGORICAL_OVERLAY void		Get_output (void); Set_output (CATEGORICAL_OVERLAY);
}; class M	IERGE : public	REPARTITION	
{	/* attributes */ SIMILARITY_MATRIX		similarity_matrix;
};	/* operations */ SIMILARITY_MATRIX void		Get_similarity_matrix (void); Set_similarity_matrix SIMILARITY_MATRIX);
class	WINDOW_REPARTITION	: public	REPARTITION
{	/* attributes */ REPARTITION_WINDOW		window;
};	/* operations */ REPARTITION_WINDOW void		Get_scan_window (void); Set_scan_window (REPARTITION_WINDOW);
		. muhlio	MODEL_OPERATION
class {	NUMERICAL_CONSUMER /* attributes */ NUMERICAL_OVERLAY	: public	input;
};	/* operations */ NUMERICAL_OVERLAY void		Get_input (void); Set_input (NUMERICAL_OVERLAY);

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class {	NUMERICAL_PROD_CONSUMER		: public	NUMERICAL_CONSUMER
	/* attributes */ NUMERICAL_OVERLAY		output;	
};	/* operations */ NUMERICAL_OVERLAY void		Get_output ( Set_output (	(void); NUMERICAL_OVERLAY);
	CONVOLUTION : public	NUMERICA	L_PROD_CONS	SUMER
L	/* attributes */ AVERAGE_WINDOW		window;	
};	/* operations */ AVERAGE_WINDOW void		Get_windov Set_window	v (void) ; v (AVERAGE_WINDOW) ;
class	OVERLAY_ALGEBRA	: public	NUMERIC	AL_PROD_CONSUMER
{	/* attributes */ NUMERICAL_OVERLAY		addend;	
};	/* operations */ NUMERICAL_OVERLAY void		Get_addend Set_addend	(void); (NUMERICAL_OVERLAY);
class	INTERPOLATE : public	NUMERICA	AL_PROD_CONS	SUMER
{	/* attributes */ INTERPOLATE_WINDOW		window;	
	/* operations */ INTERPOLATE_WINDOW void		Get_window Set_window (INTE)	• • •

class {	GENERIC_NUMERICAL	: public	NUMERICAL_PROD_CONSUMER
L	/* attributes */ STRING		operation_type;
};	/* operations */ STRING void		Get_operation_type (void); Set_operation_type (STRING);
class {	PARTITIONER : public	NUMERICAL_0	CONSUMER
1	/* attributes */ CATEGORICAL_OVERLAY		output;
};	/* operations */ CATEGORICAL_OVERLAY void		Get_output (void) ; Set_output (CATEGORICAL_OVERLAY) ;
class	SPECTRAL_CLASSIFICATION	: public	PARTITIONER
{	/* attributes */ SPECTRAL_SCHEME SPECTRAL_BANK CATEGORICAL_OVERLAY		<pre>input_class_scheme ; input_spectral_bank ; output ;</pre>
	/* operations */ SPECTRAL_SCHEME void		Get_input_class_scheme (void); Set_input_class_scheme (SPECTRAL_SCHEME);
	SPECTRAL_BANK void		Get_input_spectral_bank (void); Set_input_spectral_bank (SPECTRAL_BANK);
	CATEGORICAL_OVERLAY void		Get_categorical_overlay (void); Set_categorical_overlay (CATEGORICAL_OVERLAY);
};			· · _ · _ · ,

class {	CLUSTER_ANALYSIS	: public	NUMERICAL_CONSUMER
t	/* attributes */ SPECTRAL_BANK SPECTRAL_SCHEME		output_bank ; output_scheme ;
};	/* operations */ SPECTRAL_BANK void SPECTRAL_SCHEME void		Get_output_spectral_bank (void); Set_output_spectral_bank (SPECTRAL_BANK); Get_output_class_scheme (void); Set_output_class_scheme (SPECTRAL_SCHEME);
class {	TOPO_PARTITION	: public	PARTITIONER
1	/* attributes */ NUMERICAL_OVERLAY CATEGORICAL_OVERLAY /* operations */ NUMERICAL_OVERLAY		<pre>output_digital_area_transform ; output_partitions ; Get_output_digital_area_transform (void) ;</pre>
	void CATEGORICAL_OVERLAY void		Set_output_digital_area_transform (NUMERICAL_OVERLAY); Get_output_partitions (void); Set_output_partitions (CATEGORICAL_OVERLAY);
};			
class {	COVER_CONSUMER	: public	MODEL_OPERATION
	/* attributes */ COVER_MODEL COVER_SCHEME		input_model ; input_scheme ;
};	/* operations */ COVER_MODEL void COVER_SCHEME void		Get_input_model (void); Set_input_model (COVER_MODEL); Get_input_scheme (void); Set_input_scheme (COVER_SCHEME);

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class {	COVER_TRAINING	: public	COVER_CONSUMER
1	/* attributes */ COVER_SCHEME		output_scheme;
};	/* operations */ COVER_SCHEME void		Get_output_scheme (COVER_SCHEME) ; Set_output_scheme (COVER_SCHEME) ;
class {	COVER_CLASSIFY	: public	COVER_CONSUMER
1	/* attributes */ COVER_MODEL		output_model;
};	/* operations */ COVER_MODEL void		Get_output_model (void) ; Set_output_model (COVER_MODEL) ;
class	SOIL_CONSUMER	: public	MODEL_OPERATION
ł	/* attributes */ SOIL_MODEL SOIL_SCHEME		<pre>input_model ; input_scheme ;</pre>
};	/* operations */ SOIL_MODEL void SOIL_SCHEME void		Get_input_model(void); Set_inputt_model (SOIL_MODEL); Get_input_scheme (void); Set_input_scheme (SOIL_SCHEME);

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class {	SOIL_TRAINING	: public	SOIL_CONSUMER		
	/* attributes */ SOIL_SCHEME		output_scheme ;		
};	/* operations */ SOIL_SCHEME void		Get_output_scheme (SOIL_SCHEME) ; Set_output_scheme (SOIL_SCHEME) ;		
class {	SOIL_CLASSIFY	: public	SOIL_CONSUMER		
·	/* attributes */ SOIL_MODEL		output_model;		
};	/* operations */ SOIL_MODEL void		Get_output_model (void); Set_output_model(SOIL_MODEL);		
class {	ECOSERIES_CONSUMER	: public	MODEL_OPERATION		
·	/* attributes */ ECOMODEL_TIME_SERIES		input;		
	/* operations */ ECOMODEL_TIME_SERIES void		Get_input (void) ; Set_input (ECOMODEL_TIME_SERIES) ;		
}; class	FOREST_BGC : public ECOSERIES_CONSUMER				
{	/* attributes */ ECOMODEL_TIME_SERIES		output;		
	/* operations */ ECOMODEL_TIME_SERIES void		Get_output (void) ; Set_output (ECOMODEL_TIME_SERIES) ;		
};					

class {	NUMSERIES_CONSUMER	: public	MODEL_OPERATION
	/* attributes */ NUMERICAL_TIME_SERIES		input;
}	/* operations */ NUMERICAL_TIME_SERIES void		Get_input (void) ; Set_input (NUMERICAL_TIME_SERIES) ;
class {	MTCLIM : public	NUMSERIES	_CONSUMER
t	/* attributes */ NUMERICAL_TIME_SERIES		output;
Ъ.	/* operations */ NUMERICAL_TIME_SERIES void		Get_output (void) ; Set_output (NUMERICAL_TIME_SERIES) ;
}; class	ELEVATION_ACQUISITION	: public	OPERATION
{	/* attributes */ STEREO_PAIR NUMERICAL_OVERLAY ANALYST		<pre>air_photo_pair ; output_elevation_model ; performed_by ;</pre>
	/* operations */ STEREO_PAIR void NUMERICAL_OVERLAY void ANALYST void		Get_air_photo_pair (void); Set_air_photo_pair (STEREO_PAIR); Get_output_elevation_model (void); Set_outptu_elevation_model (NUMERICAL_OVERLAY); Get_analyst (vodi); Set_analyst (ANALYST);
1.			

1;

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class SPECTRAL\_ACQUISITION : public

/\* attributes \*/ SENSOR POINT\_MODEL NUMBER NUMBER

/\* operations \*/

SENSOR void POINT\_MODEL void

#### };

class CLIMATE\_ACQUISITION : public
{
 /\* attributes \*/
 NWS\_MET\_STATION

NWS\_MET\_STATION NUMERICAL\_OVERLAY CLIMATE\_RECORDER

/\* operations \*/ NWS\_MET\_STATION void

NUMERICAL\_OVERLAY void

CLIMATE\_RECORDER void

};

OPERATION

sensor; output\_spectral\_model; solar\_zenith; solar\_azimuth;

Get\_sensor (void) ; Set\_sensor (SENSOR) ; Get\_output\_spectral\_model (void) ; Set\_output\_spectral\_model (POINT\_MODEL) ;

#### OPERATION

climate\_station ;
output\_climate\_model ;
data\_recorder ;

Get\_climate\_station (void); Set\_climate\_station (NWS\_MET\_STATION); Get\_output\_climate\_model (void); Set\_output\_climate\_model (NUMERICAL\_OVERLAY); Get\_data\_recorder (void); Set\_data\_recorder (CLIMATE\_RECORDER); class FIELD\_ACQUISITION

ł

/\* attributes \*/ FIELD\_WORKER SAMPLING\_SYSTEM AERIAL\_PHOTO TRAINING\_SITE FIELD\_FORM

/\* operations \*/ FIELD\_WORKER void SAMPLING\_SYSTEM void

AERIAL\_PHOTO void TRAINING\_SITE void FIELD\_FORM void field\_worker; sampling\_system; air\_photo; training\_sitet; field\_form;

Get\_field\_worker (void); Set\_field\_worker (FIELD\_WORKER); Get\_sampling\_system (void); Set\_sampling\_system SAMPLING\_SYSTEM); Get\_air\_photo (void); Set\_air\_photo (AERIAL\_PHOTO); Get\_training\_site (void); Set\_training\_site (TRAINING\_SITE); Get\_field\_form (void); Set\_field\_form (FIELD\_FORM) l;

};

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## 2f. Classification Classes

#### class SPECTRAL\_SPACE : public DOCUMENTED\_ENTITY ł /\* attributes \*/ NUMBER dimensionality; SET < COLOR\_GROUP > color\_groups; /\* operations \*/ NUMBER Get\_dimensionality (void); void Set\_dimensionality (NUMBER); COLOR\_GROUP Iterate\_over\_color\_groups (void); }; SIGNATURE : public DOCUMENTED\_ENTITY class ł /\* attributes \*/ value : NUMBER TRAINING\_SAMPLE derived\_from; characterized\_class; USER\_DEFINED\_CLASS /\* operations \*/ NUMBER Get\_value (void); Set\_value (NUMBER); void Get\_training\_sample (void); TRAINING\_SAMPLE Set\_training\_sample void (TRAINING\_SAMPLE); Get\_characterized\_class (void); USER\_DEFINED\_CLASS Set\_characterized\_class void (USER\_DEFINED\_CLASS); Compute\_value (NUMBER); void Is\_match (NUMBER); BOOLEAN

class {	SPECTRAL_BANK : public	DOCUMENTED	D_ENTITY
•	/* attributes */		
	SET < BRIGHTNESS_GROUP>		brightness_groups;
	/* operations */		
	BRIGHTNESS_GROUP void		Iterate_over_brightness_groups (void); Set_brightness_group (BRIGHTNESS_GROUP);
};			
class {	SPECTRAL_GROUP	: public	DOCUMENTED_ENTITY
	/* attributes */		
	NUMBER /* operations */		correlation_coefficient;
	NUMBER		Get_correlation_coefficient (void);
	void		Set_correlation_coefficient (NUMBER);
};			
class {	COLOR_GROUP : public	SPECTRAL_GE	ROUP
Ľ	/* attributes */		
	NUMBER		number_brightness_groups;
	SET < BRIGHTNESS_GROUP >		brightness_groups;
	/* operations */		
	NUMBER		Get_number_brightness_groups (void);
	void		Set_number_brightness_groups (NUMBER);
	BRIGHTNESS_GROUP		Iterate_over_brightness_groups (void);
};			

## class BRIGHTNESS\_GROUP : public SPECTRAL\_GROUP

ł

/\* attributes \*/ COLOR\_GROUP containing\_color\_group; SPECTRAL\_CLASS spectral\_class; NUMERICAL\_POINT point\_1 ; NUMERICAL\_POINT point\_2; NUMERICAL POINT point\_3; /\* operations \*/ COLOR\_GROUP Get\_containing\_color\_group (void); void Set\_containing\_color\_group (COLOR\_GROUP); SPECTRAL\_CLASS Get\_spectral\_class (void); void Set\_spectral\_class (SPECTRAL CLASS); NUMERICAL\_POINT Get\_point\_1 (void); Set\_point\_1 (NUMERICAL POINT) : void NUMERICAL\_POINT Get\_point\_2 (void); Set\_point\_2 (NUMERICAL\_POINT); void NUMERICAL\_POINT Get\_point\_3 (void); void Set\_point\_3 (NUMERICAL\_POINT) ; Is\_match BOOLEAN (NUMBER, NUMBER, NUMBER);

class TRAINING\_SAMPLE : public DOCUMENTED\_ENTITY
{
 /\* attributes \*/
 SET < TRAINING\_SITE > training\_sites ;
 SIGNATURE signature ;
 /\* operations \*/
 TRAINING\_SITE Iterate\_over\_training\_sites (void) ;
 SIGNATURE Get\_signature (void) ;

Set\_signature (SIGNATURE);

};

void

## class SIMILARITY\_MATRIX : public

{

/\* attributes \*/ MATRIX < SIMILARITY >

/\* operations \*/ SIMILARITY

void

#### };

{

## class SIMILARITY : public

### DOCUMENTED\_ENTITY

NUMBER USER\_DEFINED\_CLASS USER\_DEFINED\_CLASS

/\* operations \*/ NUMBER void USER\_CLASS void

USER\_CLASS void

};

value ;
from\_class ;
to\_class ;

Get\_value (void); Set\_value (NUMBER); Get\_from\_class (void); Set\_from\_class (USER\_CLASS); Get\_to\_class (void); Set\_to\_class (USER\_CLASS);

DOCUMENTED\_ENTITY

similarities;

Get\_similarity (USER\_CLASS, USER\_CLASS); Set\_similarity (USER\_CLASS, USER\_CLASS);

class {	MEMBERSHIP_FUNCTION	: public	DOCUMENTED_ENTITY
ť	/* attribute */ STRING		attribute_defined ;
	USER_DEFINED_CLASS		class_defined;
	FUNCTION		function;
	/* operations */		
	STRING		Get_attribute_defined (void);
	void		Set_attribute_defined (STRING);
	USER_CLASS void		Get_class_defined (void); Set_class_defined (USER_CLASS);
	FUNCTION		Get_function (void);
	void		Set_function (FUNCTION);
	NUMBER		Compute_possibility (NUMBER);
};			
class	SCHEME_COMPONENT	: public DOCU	MENTED_ENTITY
{	At a standard at 1		
	/* attributes */ CLASS_SCHEME		containing_class_scheme;
			containing_onuss_contente,
	/* operations */		
	CLASS_SCHEME		Get_containing_class_scheme (void);
	void		Set_containing_class_scheme (CLASS_SCHEME);
};			
, ,			
class	CLASS : public	CLASS_SCHE	ME_COMPONENT
ł	/* attributes */		
	SPECIALIZATION		child_specialization;
	NUMBER		number_children ;
	NUMBER		id ;
	/* operations */		
	SPECIALIZATION		Get_child_specialization (void);
	void		Set_child_specialization
			(SPECIALIZATION);
	NUMBER void		Get_id (void) ; Set_id (NUMBER
};	VOIU		

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class {	ROOT_CLASS : public	CLASS	
ι	/* attributes */		
	CLASS_SCHEME		containing_class_scheme;
	/* operations */		
	CLASS_SCHEME		Get_containing_class_scheme (void);
	void		Set_containing_class_scheme CLASS_SCHEME);
};			,
class {	USER_CLASS : public	CLASS	
-	/* attributes */		
	SPECIALIZATION		parent_specialization;
	SIGNATURE		signature ;
	MEMBERSHIP_FUNCTION		membership_function;
	/* operations */		
	SPECIALIZATION		Get_parent_specialization (void);
	void		Set_parent_specialization
			(SPECIALIZATION);
	SIGNATURE		Get_signature (void) ;
	void		Set_signature (SIGNATURE);
	MEMBERSHIP_FUNCTION		Get_membership_function (void);
	void		Set_membership_function
			(MEMBERSHIP_FUNCTION);
};			
class	SOIL_CLASS :	public	USER_DEFINED_CLASS
{			
	/* attributes */ SOIL_REGION		described_region;
	SOIL_REGION		
	/* operations */		
	SOIL_REGION		Get_described_region (void);
	void		Set_described_region (SOIL_REGION);
};			

class	COVER_CLASS : public	USER_DEFINED_CLASS	
{	/* attributes */ COVER_REGION		described_region;
};	/* operations */ COVER_REGION void		Get_described_region (void) ; Set_described_region (COVER_REGION) ;
class {	SPECTRAL_CLASS	: public	USER_DEFINED_CLASS
l	/* attributes */ CATEGORICAL_REGION		described_region;
	/* operations */ CATEGORICAL_REGION void		Get_described_region (void) ; Set_described_region (CATEGORICAL_REGION) ;
}; class	SPECIALIZATION	: public	CLASS_SCHEME_COMPONENT
{	/* attributes */ CLASS USER_DEFINED_CLASS		parent_class ; child_class ;
);	/* operations */ CLASS void USER_DEFINED_CLASS void		Get_parent_class (void); Set_parent_class (CLASS); Get_child_class (void); Set_child_class (USER_DEFINED_CLASS);

class {	CLASS_SCHEME	: public	DOCUMENTED_ENTITY
t	/* attributes */ ROOT_CLASS		root ;
};	/* operations */ ROOT_CLASS void		Get_root (void); Set_root (ROOT_CLASS);
class	SOIL_SCHEME : public	CLASS_SCHE	ME
{	/* attributes */ SOIL_MODEL SET < SOIL_CLASS > /* operations */		described_model; classes;
};	SOIL_MODEL void SOIL_CLASS void		Get_described_model (void) ; Set_described_model (SOIL_MODEL) ; Iterate_over_classes (void) ; Set_class (SOIL_CLASS) ;
class	COVER_SCHEME	: public	CLASS_SCHEME
{	/* attributes */ COVER_MODEL SET < COVER_CLASS >		described_model; classes;
};	/* operations */ COVER_MODEL void COVER_CLASS void		Get_described_model (void) ; Set_described_model (COVER_MODEL) ; Iterate_over_classes (void) ; Set_class (COVER_CLASS) ;

class SPECTRAL\_SCHEME

/\* attributes \*/ CATEGORICAL\_OVERLAY SET < SPECTRAL\_CLASS >

/\* operations \*/ CATEGORICAL\_OVERLAY void

SPECTRAL\_CLASS void

described\_overlay;
clases;

Get\_described\_overlay (void) ; Set\_described\_overlay (CATEGORICAL\_OVERLAY) ; Iterate\_over\_classes (void) ; Set\_class (SPECTRAL\_CLASS) ;

ł

class	MET_STATION : public	DOCUMENTED_ENTITY	
{	/* attributes */ NUMBER COORDINATE		elevation ; coord ;
};	/* operations */ NUMBER void COORDINATE void		Get_elevation (void); Set_elevation (NUMBER); Get_coord (void); Set_coord (COORDINATE);
class {	ACTUAL_MET_STATION	: public	MET_STATION
t	/* attributes */ DATE DATE		start_date ; end_date ;
	/* operations */ DATE void DATE void		Get_start_date (void) ; Set_start_date (DATE) ; Get_end_date (void) ; Set_end_date (DATE) ;
};	VIRTUAL_MET_STATION	: public	MET_STATION
class {	/* attributes */ DATE	. puone	date_generated;
			cate_generates ,
	/* operations */ DATE void		Get_date_generated (void); Set_date_generated (DATE);
};			

.

. ·

class {	AIRCRAFT : public	DOCUMENT	TED_ENTITY
-	/* attribute */		
	CAMERA		carries;
	/* operations */		
	CAMERA		Get_camera (void);
	void		Set_camera (CAMERA);
};			
class	AERIAL_PHOTO	: public	DOCUMENTED_ENTITY
{			
	/* attributes */		
	STRING		type ;
	STRING		scale;
	DATE		acquisition_date;
	TIME		acquisition_time;
	CAMERA		camera;
	/* operations */		
	STRING		Get_type (void);
	void		Set_type (STRING);
	STRING		Get_scale (void);
	void		Set_scale (STRING);
	DATE		Get_acquisition_date (void);
	void		Set_acquisition_date (DATE);
	TIME		Get_acquisition_time (void);
	void		Set_acquisition_time (TIME);
	CAMERA		Get_camera (void);
	void		Set_camera (CAMERA);
};			

{

/* attributes */	
DATE	launch_date;
NUMBER	life_expectancy;
NUMBER .	ground_track_speed;
NUMBER	orbital_period;
NUMBER	ground_track_distance;
SCANNER	scanner;
ORBIT	orbit ;
/* operations */	
DATE	Get_launch_date (void);
void	Set_launch_date (DATE);
NUMBER	Get_life_expectancy (void);
void	Set_life_expectancy (NUMBER);
NUMBER	Get_ground_track_speed (void);
void	Set_ground_track_speed (NUMBER);
NUMBER	Get_orbital_period (void);
void	Set_orbital_period (NUMBER);
NUMBER	Get_ground_track_distance (void);
void	<pre>Set_ground_track_distance (NUMBER);</pre>
SCANNER	Get_scanner (void);
void	Set_scanner (SCANNER);
ORBIT	Get_orbit (void);
void	Set_orbit (ORBIT);

class	ORBIT	: public	DOCUMENTED_I	ENTITY
ł	/* attributes *			
	NUMBER		a	ltitude ;
	NUMBER		ir	nclination_angle;
	/* operations *			
	NUMBER		C	Get_altitude (void);
	void		S	Set_altitude (NUMBER);
	NUMBER		C	<pre>Get_inclination_angle (void);</pre>
	void		S	Set_inclination_angle (NUMBER)
};				
class	SCANNER : pu	ıblic	DOCUMENTED_	ENTITY
{	/* attributes */			
	NUMBER		S	can_angle;
	NUMBER			nstantaneous_field_of_view;
	NUMBER			wath_width;
	SATELLITE			carried_on;
	SENSOR			carries;
	SERVER			,
	/* operations */	,		
	NUMBER		C	Get_scan_angle (void);
	void		S	Set_scan_angle (NUMBER);
	NUMBER			Get_instantaneous_field_of_view (void);
	void		S	Set_instantaneous_field_of_view (NUMBER);
	NUMBER		C	Get_swath_width (void);
	void		S	Set_swath_width (NUMBER);
	SATELLITE		C	Get_satellite (void);
	void		S	Set_satellite (SATELLITE) ;
	SENSOR		C	Get_sensor (void);
	void		S	Set_sensor (SENSOR);
};				

•

class {	SENSOR	: public	DOCUMENTEI	D_ENTITY
ι	/* attributes */ STRING NUMBER SET < EMS_BA SCANNER	AND >		<pre>temporal_resolution ; radiometric_resolution ; ems_bands ; scanner ;</pre>
};	/* operations */ STRING void NUMBER void EMS_BAND SCANNER void POINT_MODE			Get_temporal_resolution (void); Set_temporal_resolution (STRING); Get_radiometric_resolution (void); Set_radiometric_resolution (NUMBER); Iterate_over_ems_bands (void); Get_scanner (void); Set_scanner (SCANNER); Read_data (void);
class {	EMS_BAND	: public	DOCUMENTEI	D_ENTITY
·	/* attributes */ STRING			spectral_resolution;
};	/* operations */ STRING void			Get_spectral_resolution (void); Set_spectral_resolution (STRING);
class {	FIELD_FORM	: public	DOCUMENTEI	D_ENTITY
·	/* attributes */ SAMPLING_SY DATA_ITEM	YSTEM		sampling_system ; data ;
	/* operations */ SAMPLING_ST void	YSTEM		Get_sampling_system (void); Set_sampling_system (SAMPLING_SYSTEM);
	DATA_ITEM void			Get_data_item (void); Set_data_item (DATA_ITEM);
};				

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class	SAMPLING_SYSTEM	: public	DOCUMENTED_ENTITY
{			
	/* attributes */		
	STRING		developer;
	/* operations */		
	STRING		Get_developer (void);
	void		Set_developer (STRING);
};			-
class	DATA_ITEM : public	DOCUMENTE	D_ENTITY
{	·		
	/* attributes */		
	STRING		data_type;
	NUMBER		value;
	/* operations */		
	STRING		Get_data_type (void);
	void		Set_data_type (STRING);
			Get_value (void);
	NUMBER		Get_value (volu),
	NUMBER void		Set_value (NUMBER);

. .

## 2h. Descriptor Classes

class	SPATIAL_DESCRIPTOR : publi	c	DOCUMENTEI	D_ENTITY
ł	/* attributes */			
	SPATIAL_MODEL		described_mode	1;
	/* operations */			
	SPATIAL_MODEL void		Get_described_r	
	Void		Set_described_n (SPATIAL)	_MODEL);
};				
class {	PROJECTION_PARAMETERS : publi	с	SPATIAL_DES	CRIPTOR
L.	/* attributes */			
	NUMBER		easting;	
	NUMBER		northing;	
	/* operations */			
	NUMBER		Get_easting (voi	id) ;
	void		Set_easting (NU	MBER);
	NUMBER		Get_northing (v	
	void		Set_northing (vo	oid);
};				
class {	GENERIC_SPATIAL_DESCRIPTOR		: public	SPATIAL_DESCRIPTOR
	/* attributes */			
	STRING		descriptor_type	•
	STRING		descriptor_value	e;
	/* operations */	•		
	STRING		Get_desc_value	(void);
	void		Set_desc_value	(STRING);
	STRING		Get_desc_type (	
	void		Set_desc_type (	STRING);
};				

class {	TEMPORAL_DESCRIPTOR	: public	DOCUMENTED_ENTITY
-	/* attributes */		
	STRING		temporal_descriptor_type;
	STRING		temporal_descriptor_value;
	TIME_SERIES		described_time_series;
	/* operations */		
	STRING		Get_temporal_descriptor_type (void);
	void		Set_temporal_descriptor_type (STRING);
	STRING		Get_temporal_descriptor_type (void);
	void		Set_temporal_descriptor_type (STRING);
};			
class	GCP_SET	: public	DOCUMENTED_ENTITY
{			
	/* attributes */		<b>1</b> ' <b>1</b>
	SET < COORDINATE >		coordinate_set_1;
	SET < COORDINATE >		coordinate_set_2;
	/* operations */		
	COORDINATE		Iterate_over_coordinates;
	FUNCTION		Compute_transformation (void);
};			
class	TIME_SERIES : public	DOCUMENTE	D_ENTITY
{			
	/* attributes */		
	TEMPORAL_DESCRIPTOR		temporal_scale;
	TEMPORAL_DESCRIPTOR		temporal_resolution;
	/* operations */		
	TEMPORAL_DESCRIPTOR		Get_temporal_scale (void);
	void		Set_temporal_scale
			(TEMPORAL_DESCRIPTOR);
	TEMPORAL_DESCRIPTOR		Get_temporal_resoluiton (void);
	void		Set_temporal_resolution
			(TEMPORAL_DESCRIPTOR);
};			

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class {	NUMERICAL_TIME_SERIES : public	TIME_SERIES
	/* attributes */ SET < NUMERICAL_OVERLAY > SET < NUMERICAL_SERIES_CONSUMER >	numerical_overlays; consuming_operations;
};	/* operations */ NUMERICAL_OVERLAY NUMERICAL_SERIES_CONSUMER	Iterate_over_numerical_overlays (void); Iterate_over_consuming_operations (void);
class {	ECOMODEL_TIME_SERIES : public	TIME_SERIES
t	/* attributes */ SET < ECOMODEL > SET < ECOMODEL_SERIES_CONSUMER >	ecomodels; consuming_operations;
};	/* operations */ ECOMODEL ECOMODEL_SERIES_CONSUMER	Iterate_over_ecomodels (void); Iterate_over_consuming_operations (void);
class {	COORDINATE : public ENTITY	
t	/* attributes */ NUMBER NUMBER STRING /* operations */ NUMBER void NUMBER void STRING void STRING void	<pre>x_coord ; y_coord ; coord_type ; Get_x_coord (void) ; Set_x_coord (NUMBER) ; Get_y_coord (void) ; Set_y_coord (NUMBER) ; Get_coord_type (void) ; Set_coord_type (STRING) ;</pre>
];		

-

2i. Window Classes

.

class {	WINDOW	: public	DOCUMENTED_ENTITY
•	/* attributes */		
	NUMBER		dimension_in_x;
	NUMBER		dimension_in_y;
			,
	/* operations */		
	NUMBER		Get_dimension_in_x (void);
	void		Set_dimension_in_x (NUMBER);
	NUMBER		Get_dimension_in_y (void);
	void		<pre>Set_dimension_in_y (NUMBER) ;</pre>
};			
class	AVERAGE_WINDOW	: public	WINDOW
ł	the extension of		
	/* attributes */ MATRIX		coefficient matrix
	NUMBER		—
	NUMBER		mean;
	/* operations */		
	MATRIX		Get_coefficient_matrix (void);
	void		Set_coefficient_matrix (MATRIX);
	NUMBER		Get_value (void);
	NUMBER		Set_value (NUMBER);
	NUMBER		Compute_mean (MATRIX);
};			
class	REPARTITION_WINDOW	: public	WINDOW
{		. public	
ı	/* attributes */		
	NUMBER		majority;
	NUMBER		minority;
	/* operations */		
	NUMBER		Get_majority (void);
	void		Set_majority (NUMBER);
	NUMBER		Get_minority (void);
	void		Set_minority (NUMBER);
	NUMBER		Calculate_majority (void);
	NUMBER		Calculate_minority (void);
1:			

class {	TOPO_WINDOW	: public	WINDOW
L	/* attributes */		
	NUMBER		gradient;
	NUMBER		aspect;
	/* operations */		
	NUMBER		Get_gradient (void);
	void		Set_gradient (NUMBER);
	NUMBER		Get_aspect (void);
	void		Set_aspect (NUMBER);
	NUMBER		Calculate_gradient (void);
	NUMBER		Calculate_aspect (void);
};			
class	SEARCH_WINDOW	: public	WINDOW
{			
	/* attributes */		
	NUMBER		number_points;
	/* operations */		
	NUMBER		Get_number_points (void);
	void		Set_number_points (NUMBER);
	POINT		Get_nearest_neighbor (void);
};			
class II	NTERPOLATE_WINDOW	: public	WINDOW
{			
	/* attributes */		
	SET < NUMERICAL_POINT>	target_points;	
	NUMBER		value;
	/* operations */		
	NUMERICAL_POINT		Iterate_over_target_points (void);
	NUMBER		Get_value (void);
	void		Set_value (NUMBER);
	void		Compute_weight (void);
};			

.

2j. Software Classes

class {	SOFTWARE_DEVELOPMENT	: public	DOCUMENTED_ENTITY
	/* attributes */		
	DATE		start_date;
	DATE		end_date;
	/* operations */		
	DATE		Get_start_date (void);
	void		Set_start_date (DATE) ;
	DATE		Get_end_date (void);
	void		Set_end_date (DATE) ;
};			
class {	DESIGN : public	SOFTWARE_I	DEVELOPMENT
·	/* attributes */		
	SET < DESIGNER >		designers;
	SET < IMPLEMENTIONS >		implementations;
	/* operations */		

DESIGNERterate\_over\_designers (void);IMPLEMENTATIONIterate\_over\_implementations (void);

۰.

class **IMPLEMENTATION** : public SOFTWARE\_DEVELOPMENT

- /\* attributes \*/ SET < PROGRAMMER > DESIGN IMPLEMENTED\_COMPONENT SET < PROGRAMMING\_LANGUAGE >
  - /\* operations \*/ PROGRAMMER DESIGN void IMPLEMENTATION\_COMPONENT void

PROGRAM\_LANGUAGE

programmers; design; product; programming\_languages;

Iterate\_over\_programmers (void); Get\_design (void); Set\_design (DESIGN); Get\_implementation\_component (void); Set\_implementation\_component (IMPLEMENTATION COMPONENT); Iterate\_over\_programming\_languages (void);

};

ł

.

class {	SOFTWARE	: public	DOCUMENTED_ENTITY
L	/* attributes */		
	STRING		version_numb
	STRING		revision_num
	EXECUTABLI	3	executable;

/\* operations \*/ STRING void STRING void EXECUTABLE void COMMAND

SET < COMMAND >

};

## DOOLD REAFTER ENTERN

ber ; iber; commands;

Get\_version\_number (void); Set\_version\_number (STRING); Get\_revision\_number (void); Set\_revision\_number (STRING); Get\_executable (void); Set\_executable (EXECUTABLE); Iterate\_over\_commands (void);

class	CUSTOM_SOFTWARE	: public	SOFTWARE
- <b>-</b> (	/* attributes */		
	SOURCE_COMPONENT		source;
			,
	/* operations */		
	SOURCE_COMPONENT		Get_source (void);
	void		Set_source (SOURCE_COMPONENT)
};			
class	COMMERCIAL_SOFTWARE	: public	SOFTWARE
{	/* attributes */		
	STRING		producer;
	STRING		vendor;
	NUMBER		cost;
	/* operations */		
	STRING		Get_producer (void);
	void		Set_producer (STRING);
	STRING		Get_vendor (void);
	void		Set_vendor (STRING);
	NUMBER		Get_cost (void);
	void		Set_cost (NUMBER);
};			
class {	IMPLEMENTED_COMPONEN	T : public	DOCUMENTED_ENTITY
l	/* attributes */		
	CUSTOM_SOFTWARE		containing_software;
	/* operations */		
	CUSTOM_SOFTWARE		Get_containing_software (void);
	void		Set_containing_software
			(CUSTOM_SOFTWARE);
};			

•

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class	SOURCE_COMPONENT	: public	IMPLEMENTATION_COMPONENT
{	/* attributes */ SET < SOURCE_MODULE >		source_modules;
};	/* operations */ SOURCE_MODULE		Iterate_over_source_modules (void);
class	SOURCE_MODULE	: public	IMPLEMENTATION_COMPONENT
{	/* attributes */ SOURCE_COMPONENT		ontaining_source_component;
	/* operations */ SOURCE_COMPONENT void		Get_containing_source_component (void); Set_containing_source_component (SOURCE_COMPONENT);
};			(,
class {	EXECUTABLE_COMPONENT	: public	DOCUMENTED_ENTITY
·	/* attributes */ SOFTWARE		containing_software;
};	/* operations */ SOFTWARE void		Get_software (void) ; Set_software (SOFTWARE) ;
class	COMMAND : public	EXECUTABLE	COMPONENT
ł	/* attributes */ OPERATION		operation_used_for;
];	/* operations */ OPERATION void		Get_operation_used_for (void); Set_operation_used_for (OPERATION);

class {	EXECUTABLE : public	EXECUTABLE_	COMPONENT
•	/* attributes */		
	DATE		creation_date;
	/* operations */		
	DATE		Get_creation_date (void);
	voiđ		Set_creation_date (DATE);
};			
class	PROGRAMMING_LANGUAGE	: public	DOCUMENTED_ENTITY
ι	/* attributes */		
	SET < IMPLEMENTATION >		implementations;
	/* operations */		
	IMPLEMENTATION		Iterate_over_implementations (vodi);
};			

.

# 2k. Documentation Classes

class	DOCUMENT : public	NAMED_ENTI	ТҮ
ł	/* attributes */ NUMBER		length ;
<b>1</b> .	/* operations */ NUMBER void		Get_length (void) ; Set_length (NUMBER) ;
};			
class {	EXTERNAL_DOCUMENT	: public	DOCUMENTED_ENTITY
1	/* attributes */ STRING		writer ;
	/* operations */ STRING void		Get_writer (void) ; Set_writer (STRING) ;
};			
class	PUB_EXT_DOCUMENT	: public	EXTERNAL_DOCUMENT
{	/* attributes */ DATE		publication_date;
	/* operations */ DATE void		Get_publication_date (void) ; Set_publication_date (DATE) ;
};			
class	EXTERNAL_BOOK	: public	PUB_EXT_DOCUMENT
{	/* attributes */ STRING		publisher ;
};	/* operations */ STRING void		Get_publisher (void) ; Set_publisher (STRING) ;

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class {	EXTERNAL_ARTICLE	: public	PUB_EXT_DOCUMENT
ι	/* attributes */ STRING		journal;
	/* operations */ STRING void		Get_journal (void); Set_journal (STRING);
};			
class {	EXTERNAL_THESIS	: public	EXTERNAL_DOCUMENT
•	/* attributes */		
	STRING		degree;
	/* operations */		
	STRING		Get_degree (void);
	void		Set_degree (STRING);
};			
class {	INTERNAL_DOCUMENT : put	blic	DOCUMENT
class {	INTERNAL_DOCUMENT : put	blic	DOCUMENT
		blic	DOCUMENT writers ;
	/* attributes */ SET <author></author>	blic	
	/* attributes */ SET <author> /* operations */</author>	blic	writers ;
{	/* attributes */ SET <author></author>	blic	
	/* attributes */ SET <author> /* operations */ AUTHOR</author>		writers ; Iterate_over_writers (void) ;
{ }; class	/* attributes */ SET <author> /* operations */</author>	blic : public	writers ;
{ };	/* attributes */ SET <author> /* operations */ AUTHOR PUB_INT_DOCUMENT</author>		writers ; Iterate_over_writers (void) ;
{ }; class	/* attributes */ SET <author> /* operations */ AUTHOR</author>		writers ; Iterate_over_writers (void) ;
{ }; class	<pre>/* attributes */ SET <author> /* operations */ AUTHOR PUB_INT_DOCUMENT /* attributes */ DATE</author></pre>		writers ; Iterate_over_writers (void) ; INTERNAL_DOCUMENT
{ }; class	<pre>/* attributes */ SET <author> /* operations */ AUTHOR PUB_INT_DOCUMENT /* attributes */ DATE /* operations */</author></pre>		<pre>writers; Iterate_over_writers (void); INTERNAL_DOCUMENT publication_date;</pre>
{ }; class	<pre>/* attributes */ SET <author> /* operations */ AUTHOR PUB_INT_DOCUMENT /* attributes */ DATE /* operations */ DATE /* operations */ DATE</author></pre>		<pre>writers; Iterate_over_writers (void); INTERNAL_DOCUMENT publication_date; Get_publication_date (void);</pre>
{ }; class	<pre>/* attributes */ SET <author> /* operations */ AUTHOR PUB_INT_DOCUMENT /* attributes */ DATE /* operations */</author></pre>		<pre>writers; Iterate_over_writers (void); INTERNAL_DOCUMENT publication_date;</pre>

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.

class {	INTERNAL_BOOK	: public	PUB_INT_DOCUMENT
	/* attributes */ STRING		publisher;
};	/* operations */ STRING void		Get_publisher (void) ; Set_publisher (STRING) ;
class {	INTERNAL_ARTICLE	: public	PUB_INT_DOCUMENT
ı	/* attributes */ STRING		journal;
};	/* operations */ STRING void		Get_journal (void); Set_journal (STRING);
class {	INTERNAL_THESIS	: public	INTERNAL_DOCUMENT
l	/* attributes */ STRING		degræ;
};	/* operations */ STRING void		Get_degree (void) ; Set_degree (STRING) ;

class	EMPLOYEE	: public	NAMED_ENTITY
{			
	/* attributes */		
	STRING		home_address;
	STRING		home_phone;
	STRING		office;
	STRING		office_phone;
	STRING		email;
	STRING		fax ;
	DATE		birth_date;
	DATE		hire_date;
	LAB		employed_in;
	/* operations */		
	STRING		Get_home_address (void);
	void		Set_home_address (STRING);
	STRING		Get_home_phone (void);
	void		Set_home_phone (STRING);
	STRING		Get_office (void);
	void		Set_office (STRING);
	STRING		Get_office_phone (void);
	void		<pre>Set_office_phone (STRING);</pre>
	STRING		Get_email (void);
	void		Set_email (STRING);
	STRING		Get_fax (void);
	void		Set_fax (STRING);
	DATE		Get_birth_date (void);
	void		Set_birth_date (DATE);
	DATE		Get_hire_date (void);
	void		Set_hire_date (DATE);
	LAB		Return_lab (void);
1 ·			

class {	ADMINISTRATOR	: public	EMPLOYEE
	/* attributes */ SET < PROJECT> LAB		projects; administers;
};	/* operations */ PROJECT LAB		Iterate_over_projects (void); Return_lab (void);
class	AUTHOR : public	EMPLOYEE	
t	/* attributes */ SET < INTERNAL_DOCUMENT	documents;	
};	/* operations */ INTERNAL_DOCUMENT		Iterate_over_documents (void);
class {	ANALYST : public	EMPLOYEE	
( );	/* attributes */ SET < OPERATION >		operations;
	/* operations */ OPERATION		Iterate_over_operations (void);
class {	PROGRAMMER : public	EMPLOYEE	
	/* attributes */ SET < IMPLEMENTATION >		implementations;
};	/* operations */ IMPLEMENTATION		Iterate_over_implementation (void);

.

ł /\* attributes \*/ SET < DESIGN > designs; /\* operations \*/ DESIGN Iterate\_over\_designs (void); }; class FIELD\_WORKER : public **EMPLOYEE** ł /\* attributes \*/ SET < FIELD\_DATA\_ACQUISITION > field\_data\_acquisitions; /\* operations \*/ FIELD\_DATA\_ACQUISITION Iterate\_over\_field\_data\_acquisitions (void); }; DOCUMENTED\_ENTITY : public class LAB ł /\* attributes \*/ lab\_address; STRING lab\_phone; STRING lab\_email; STRING lab\_fax; STRING projects; SET < PROJECT > employees; SET < EMPLOYEE > /\* operations \*/ Get\_lab\_address (void); STRING Set\_lab\_address (STRING); void Get\_lab\_phone (void); STRING Set\_lab\_phone (STRING); void Get\_lab\_email (void); STRING Set\_lab\_email (STRING); void Get\_lab\_fax (void); STRING void Set\_lab\_fax (STRING); PROJECT Iterate\_over\_projects (void); EMPLOYEE Iterate\_over\_employees (void);

**EMPLOYEE** 

};

class

DESIGNER

: public

class {	PROJECT	: public	DOCUMENTED_ENTITY	
ſ	/* attributes */ STRING LAB		funding_source; managed_by;	
	/* operations */ STRING void LAB		Get_funding_source (void); Set_funding_source (STRING); Return_lab (void);	
};				

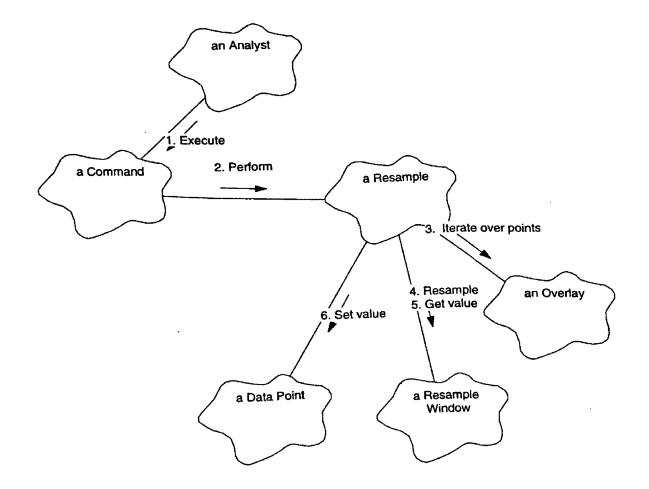
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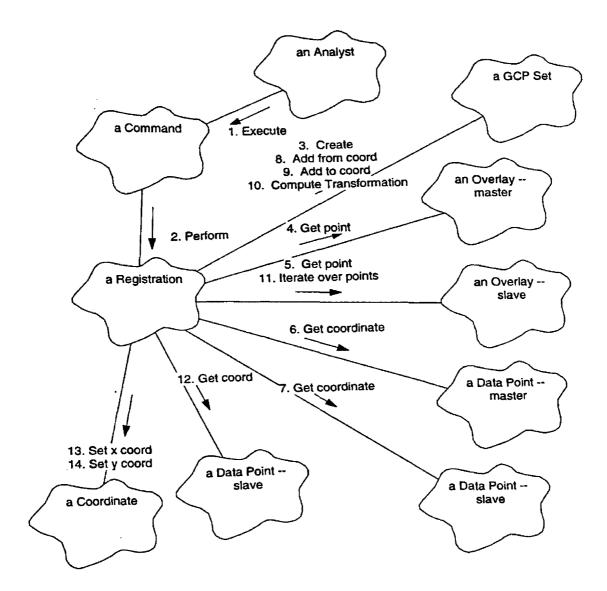
## APPENDIX III SCENARIOS

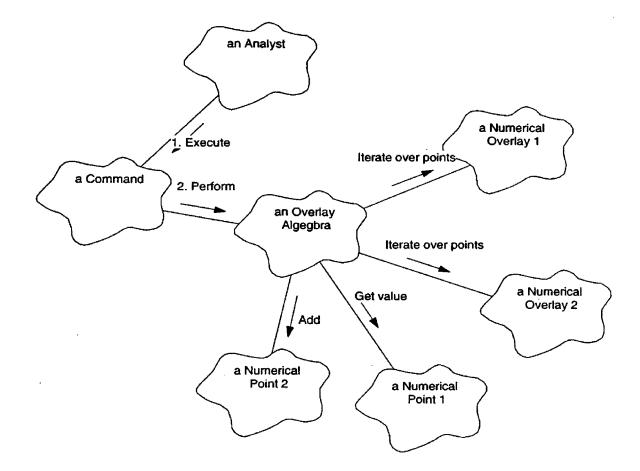
## TABLE OF CONTENTS

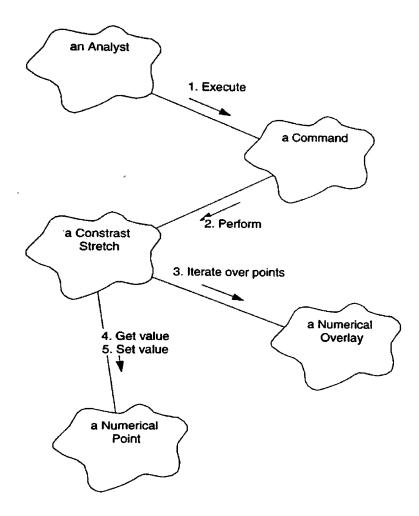
Scenario Name	p <u>age number</u>
1. Resampling	170
2. Registration	171
3. Overlay Algebra	172
4. Contrast Stetch	173
5. Convolution	174
6. Interpolation	175
7. EcoModel Assignment	176
8. Cluster Analysis	177
9. Spectral Classification	178
10. Cover Training traditional set theory	179
11. Cover Classification traditional set theory	180
12. Cover Training fuzzy set theory	181
13. Cover Classification fuzzy set theory	182
14. Merge	183
15. Majority Filter	184
16. Elevation Data Acquisition	- 185
17. Spectral Data Acquisition	186
18. Climate Data Acquisition	187
19. Field Data Acquisition	188
-	

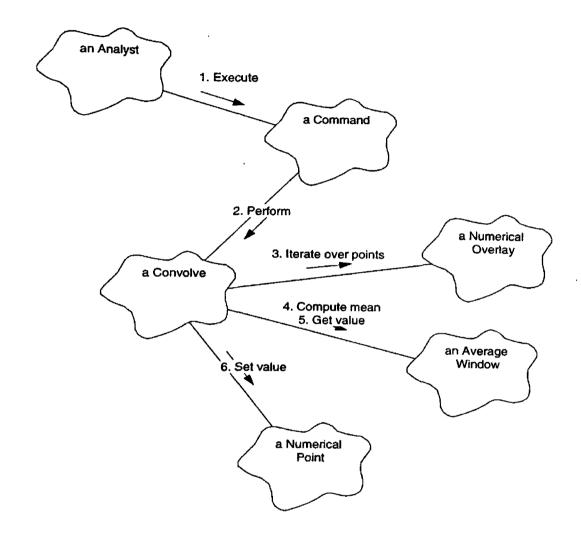
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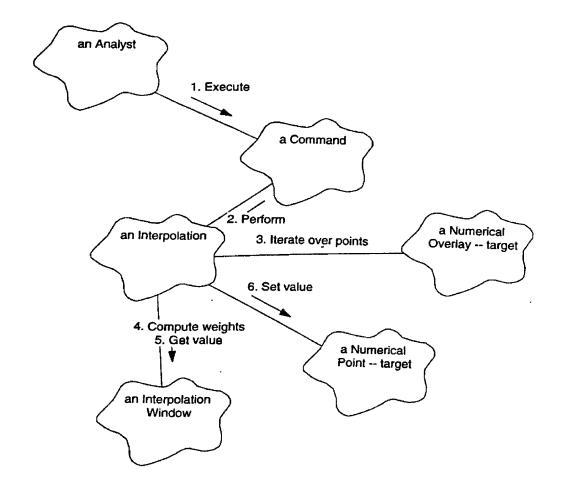


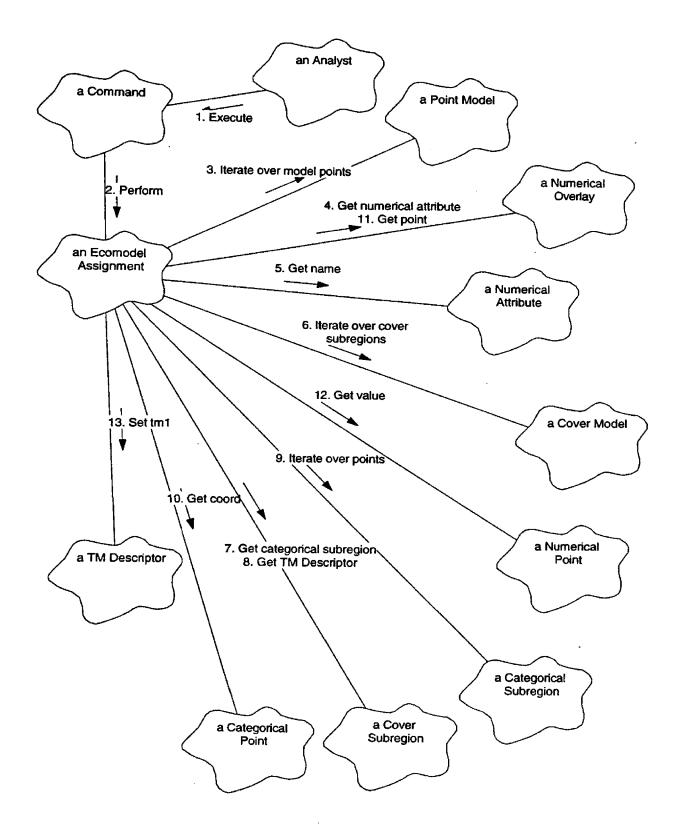




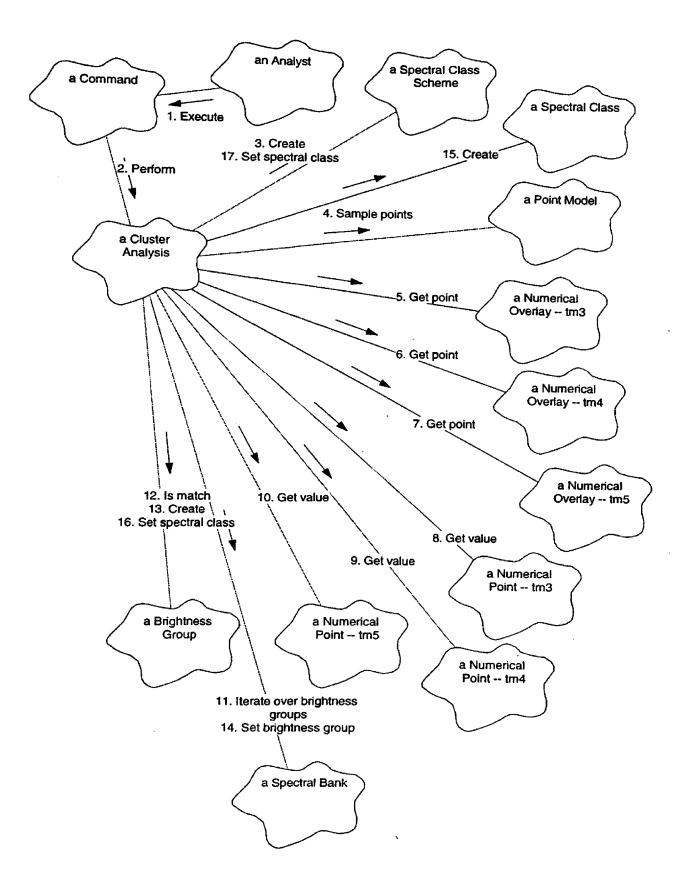




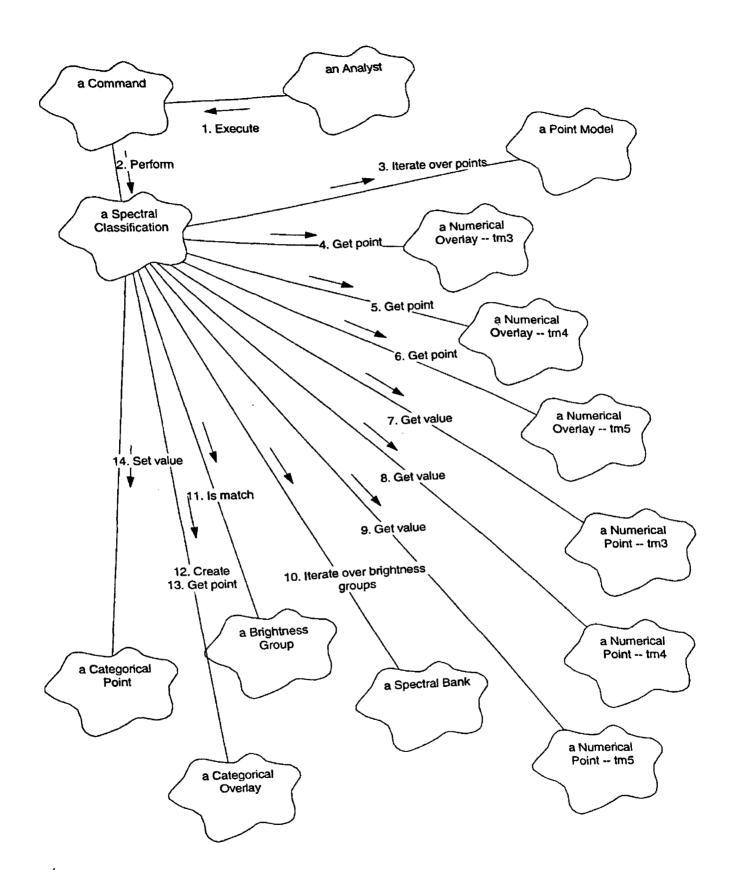


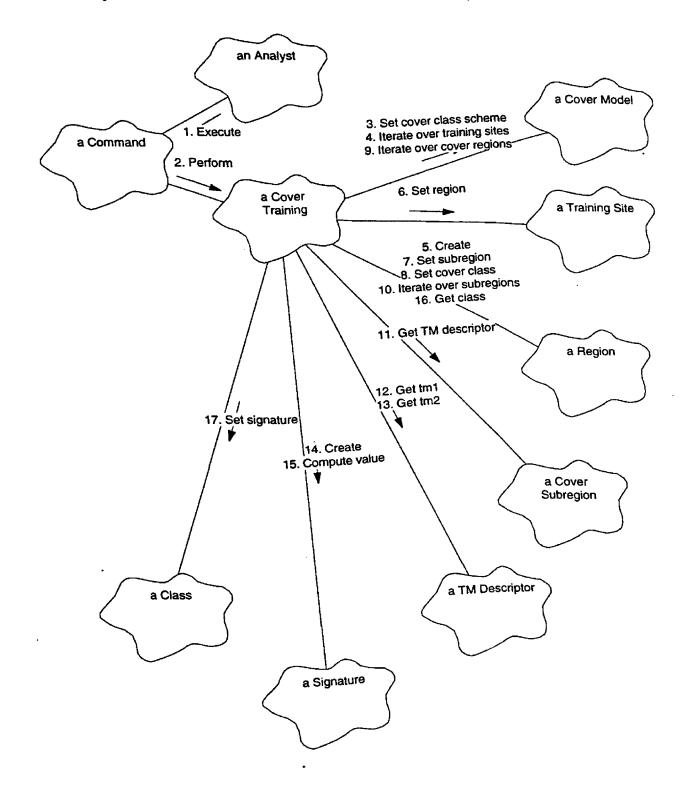


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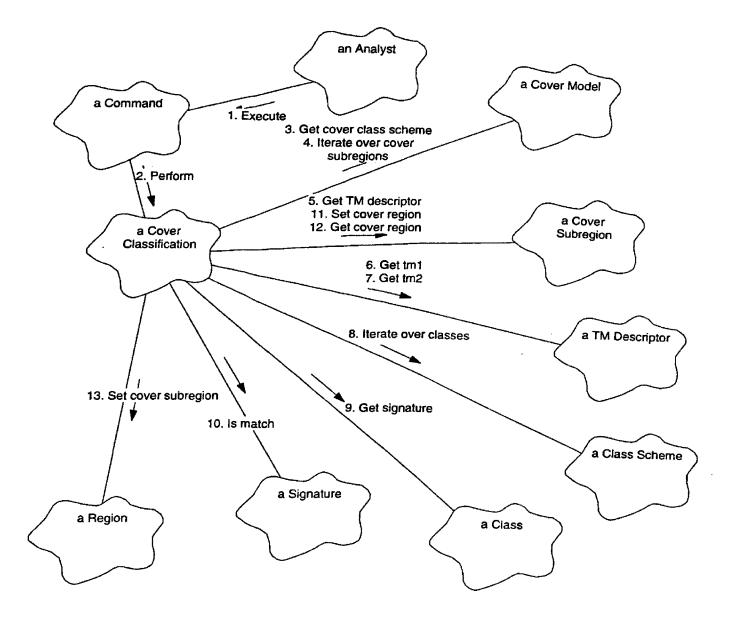


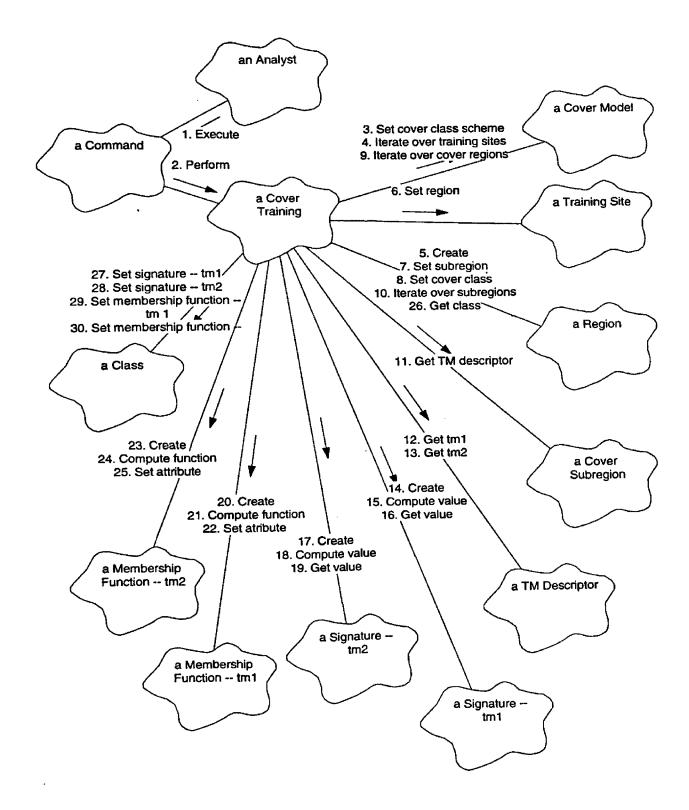
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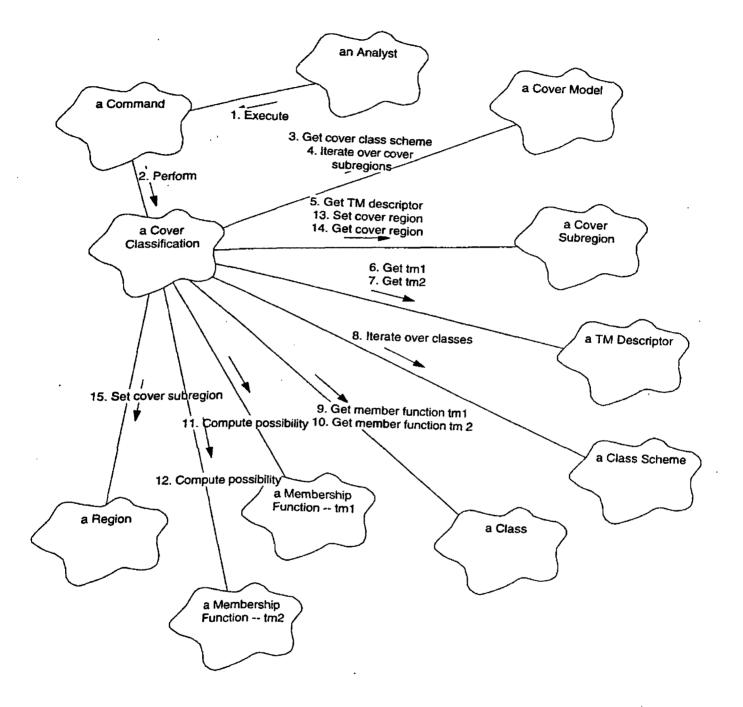


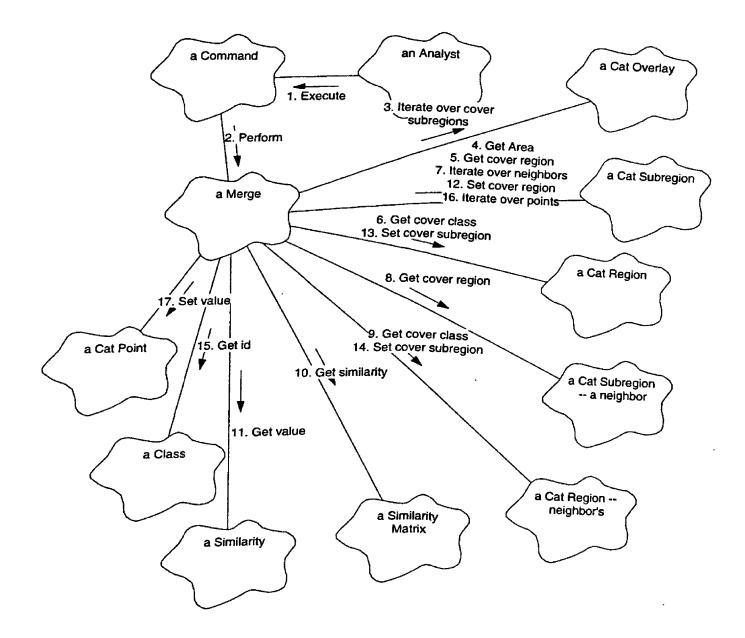


179

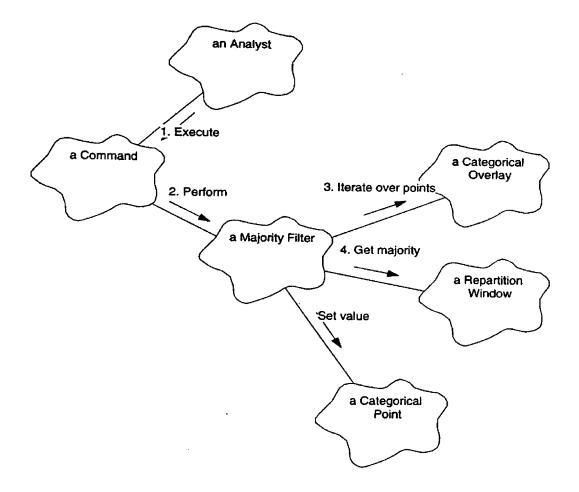


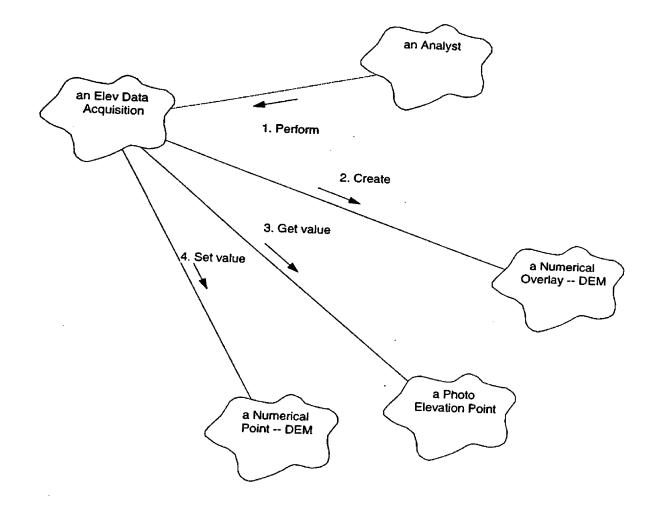




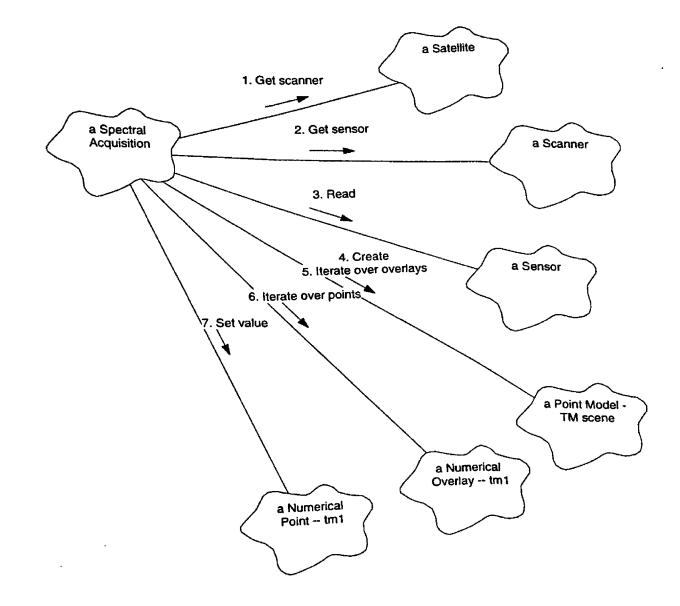


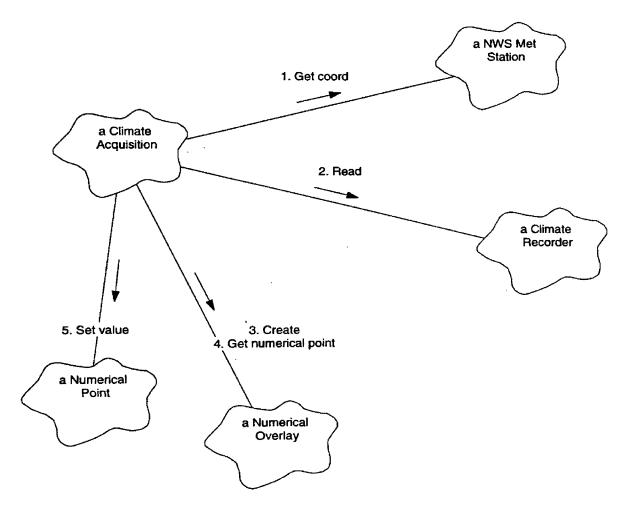
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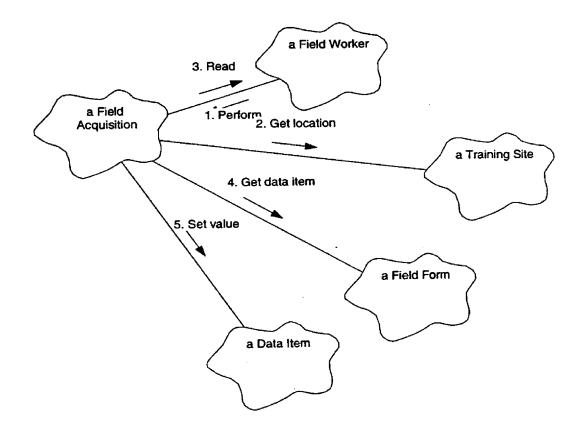


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189

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