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MAPPING MOVEMENT:

A Study of Existing and Potential Methods

By

Craig C. Bacino

B.F.A., University of Iowa, 1974

Presented in partial fulfillment of the requirements

for the degree of

Masters of Arts

University of Montana

1986

Approved by

Chairman, Board of Examiners

man Dean, Graduate School

dure 12, 1986

Date

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Bacino, Craig C., M.A., June 1986

Geography

Mapping Movement: A Study of Existing and Potential Methods (136pp.)

Director: Paul B. Wilson

The purpose of this thesis is to create new methods for mapping movement. As a first step, existing methods are surveyed; spatial interaction maps are identified in the literature, collected, cataloged, and classified according to criteria based on map symbolism. The classification scheme proves to be a useful tool for both familiarization with existing mapping methods and to facilitate the design of new methods.

After surveying existing methods, four new methods are developed using interstate migration data for the period 1975-80 published by the U.S. Bureau of Census. They include the following: Map 1, the classless choropleth dot map, an alternative method for producing classless choropleth maps without sophisticated computer techniques; Map 2, the nodal region flow map, designed to fill a vacant category created by the classification scheme; Map 3, the connectivity network map, designed to represent a familiar topic (interstate migration) in a different perspective using an existing mapping method; Map 4, the surface relief flow map, an attempt to symbolize movement explicitly without using flow lines.

A social survey is then conducted in which a small sample of respondents evaluate the four maps in terms of their form, content, and In the survey respondents gain familiarity with each map by utility. answering questions concerning map content. Respondents then record their opinions about each map's form, content, and utility. Map 1 is very accurately read and also well received by respondents. This method is potentially the most utilitarian of the four designed in the thesis. Map 2 is the most popular with map users due to its use of familiar symbols (flow Map 3 is easily read but the concept of connectivity, applied to lines). interstate migration, proves to be a handicap in it acceptance by respondents. Map 4 proves to be readable but it has a dichotomy of appeal to users. The apparent three-dimensional surface of the map, produced by a computer plotter, attracts the interest of some map users but repels others.

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Chapter 1

INTRODUCTION

Movement is a condition common to all things on the earth. Known to geographers as spatial interaction, movement of things is studied in order to learn the reasons causing it, to forecast its occurrence, and to plan for problems it may cause in the future. Maps are tools geographers use to study and analyze spatial problems. In addition to depicting geographic distributions, maps of spatial interaction are also faced with the problem of depicting changes in the distribution of things within time intervals and the changes between time intervals. The branch of cartography which produces such maps is relatively new and is an attractive area for research.

Thematic Cartography Defined

Cartography is generally subdivided into two branches: topographic and thematic. Topographic cartography produces maps which depict surface features such as rivers, lakes, mountains, and coastlines. General cultural features such as administrative boundaries, cities, and roads are often included in topographic maps as points of reference.

Thematic cartography¹, on the other hand, produces maps which depict one or more special subjects in a geographic context. Depicting data in map form allows users to view and analyze geographic relationships which may not be apparent otherwise. The special subjects for thematic maps may be drawn from both physical and cultural geography and may be qualitative or quantitative in nature.² Average annual precipitation, soil types, vegetative cover, population density, average sales price per house, and traffic patterns are a few examples of the unlimited range of subjects dealt with by thematic maps.

Reasons for Thematic Maps

It is an understatement to say a map is a picture worth ten thousand words. When dealing with a large amount of geographic data, one of the most stimulating and efficient representations is a map. Maps are interesting to look at; they format geographic data into a spatial context. An incredible amount of information can be compiled onto a map, saving the person faced with the task of analyzing columns and rows of data the trouble of visualizing spatial distributions and relationships.³

¹Thematic cartography is also referred to as statistical cartography (Raisz), special, and applied cartography (Imhof). Erwin Raisz, <u>Principles of Cartography</u> (New York: McGraw-Hill Book Company, 1962), p. 195.; Eduard Imhof, "Tasks and Methods of Theoretical Cartography," in <u>International Yearbook</u> of <u>Cartography</u>, ed. by Eduard Imhof (Gutersloh: C. Bertelsmann Verlag, 1963), p. 15.

²Qualitative description identifies things by class, kind, and other non-numerical characteristics. Quantitative description identifies things by numerical characteristics such as number and size.

³Tufte states that "highly detailed maps portray 100,000 to 150,000 bits (of information) per square inch.". He further cites that "the average U. S. Geological Survey topographic quadrangle... is estimated to contain over 100 million bits of information, or about 250,000 per square inch.". Further examples of bits of information contained in maps are found in Edward R. Tufte, <u>The Visual Display of</u> <u>Quantitative Information</u> (Cheshire, Connecticut: Graphics Press, 1983), pp. 26, 29, 30, 168.

Despite all of the information maps are able to condense into a single graphic depiction, they still are not always able to show all the details. Imagine the impossibility and absurdity of mapping the sales price per house for each house in a medium- or large-sized city. Generalization is a process which abstracts a subject of study by dropping out details in favor of presenting a broader picture. Since the physical and technical limitations of thematic maps often necessitate the generalization of data, they serve as excellent tools for portraying abstractions. Because thematic maps display abstractions of data in a geographical context, they often present viewers with a new perspective of a subject.

Development of Thematic Maps

Compared to topographic mapping, which dates back to antiquity, thematic mapping is a relatively recent cartographic development. As one might expect, the origin and development of thematic mapping closely parallels that of the systematic sciences, the sources of special subjects for thematic maps.⁴ Topics in the newly developing systematic sciences were first mapped by scientists such as Edmund Halley, Alexander von Humboldt, and John Snow in the 17th, 18th, and 19th centuries respectively.⁵ Rapid scientific and technological advances in

⁴The "beginning of the scientific revolution" and the appearance of specialized fields of study, the systematic sciences, occured in the 17th and 18th centuries respectively. The development of scientific thought in general and of geography in particular are discussed in the chapter "What Was New?" in Preston E. James and Geoffery J. Martin, <u>All Possible Worlds</u> (New York: John Wiley & Sons, 1981), pp. 135-61.

⁵John Noble Wilford, <u>The Mapmakers</u> (New York: Vintage Books, 1982), pp. 313-14.

computer science during the past two decades have been adopted by cartographers, helping advance the frontiers of thematic cartography. Considering the variety of subjects that thematic cartography serves, the relative newness of the discipline, and the recent developments in mapping technology, the potential for research and experimentation is unlimited.

Thematic Cartography and Spatial Interaction

Thematic maps are used as tools for understanding many geographical concepts. One of these concepts, spatial interaction, is pertinent to all geographic phenomena. Spatial interaction is plainly defined as flow or "physical movement of something, between two places."⁶ The 'something' that moves can be physical objects such as people, manufactured goods, and glaciers, or abstract things such as information and ideas. Some examples of spatial interaction are migration, commuting, tourism, commercial trade, flow of glacial ice, mail, telephone calls, and gossip. Various models in geography and other disciplines attempt to define and predict the movement of things between places.

Since dynamism is a condition of spatial interaction, cartographers are faced with the problem of depicting movement with static cartographic symbols. Cartographers use letters, numbers, points, lines, and areas in depicting spatial interaction. Used properly, these symbols are compatible with the depiction of movement.

⁶Peter Haggett, <u>Geography: A Modern Synthesis</u> (3rd ed.; New York: Harper & Row, Publishers, 1983), p. 442.

Statement of Problem

The goal of this thesis is to design and evaluate several new methods for mapping spatial interaction. Effectiveness of the methods is evaluated by interviewing a small population familiar with graphics or spatial interaction.

Interstate migration of people in the United States over the period 1975-80 is used as a case study in the thesis. The particular case study is chosen somewhat arbitrarily. Any number of topics in spatial interaction could serve as the basis for the design of new mapping methods. A desirable characteristic of methods produced in this thesis is their utility in mapping a number of topics rather than being limited to a single topic. It is assumed that methods produced for depicting interstate migration will also be applicable to other topics in spatial interaction. Interstate migration is chosen in large part because of the availability and accessibility of the data.

Methodology

The approach used to design new methods for depicting spatial interaction may be divided into four parts: survey of existing spatial interaction maps, analysis of migration data, design of mapping methods, and evaluation of those methods.

A survey of existing maps is undertaken to determine not only what types of maps exist, but also to determine what potential map types exist. To find out what types of maps already exist prevents duplication of research. Defining the potential types of maps that may exist directs the path of research. Methods for producing maps defined by these potential types are designed and evaluated in the chapters which follow.

Analysis of migration data and design of new mapping methods should be studied concurrently due to the mutual influence each exerts upon the other. To proceed with one process exclusive of consideration for the other is to be ignorant of the interdependence of the two. Data analysis proceeds with an eye toward evaluating each cartographic technique. Migration data are stored into a computer input file which is used by various programs for analysis. As data are processed into forms compatible with each cartographic technique, the mapping methods are designed. Cartographic techniques range from traditional pen and ink drafting to more contemporary computer printing and plotting.

Following map design, a social survey is conducted to compile opinions concerning the effectiveness of maps produced in the thesis. A small sample of those with expertise in graphics and those who may use maps of spatial interaction, such as demographers and planners, are questioned about the content and form of each map. Visual appearance as well as utility is evaluated.

Chapter 2

A SURVEY OF SPATIAL INTERACTION MAPS

This chapter surveys maps that depict spatial interaction. The endeavor begins as a search for sources of such maps; examples of them are then collected, cataloged, and classified according to criteria based on the various kinds of map symbols employed. Several of these different kinds of maps are shown in the thesis, and their symbolization systems are displayed as examples to illustrate the various classification criteria. A number of cartographic methods which have been used to depict spatial interaction are identified from the population of maps collected by the survey.

The purpose of identifying existing methods of depicting spatial interaction is to facilitate the development of new mapping methods. In the process of building the classification scheme which follows later in this chapter, spatial interaction maps are subdivided into numerous types. The logic of the classification provides a category for every spatial interaction map. Some classes, or categories, have numerous examples of maps which fit into them; others have very few; some have none. Where categories exist but no maps are found which fit, then the possibility of creating new mapping methods exists. This is only one way the new mapping techniques discussed in the next chapter are developed. Other ways the classification scheme is used to develop mapping techniques are discussed at the end of this chapter.

Sources For Maps of Spatial Interaction

The problem of mapping spatial interaction is only one part of the total universe of mapping geographic phenomena. Being such a specific cartographic problem, mapping spatial interaction receives little direct attention in the literature of cartography. References to spatial interaction maps in cartography textbooks usually are found under the name, "flow maps"⁷ or "linear data."⁸ Such textbooks consider the problem of mapping spatial interaction from the viewpoint of representing linear flows between places. This is an effective method for mapping the given problem, yet other methods exist and potential methods need to be explored.

Rather than use the literature of cartography as the major source of maps, a more productive approach is to direct the survey toward the literature dealing with spatial interaction. Since movement is universal, many disciplines are concerned with spatial interaction. Map examples involving the movement of people, animals, goods, and services may be drawn from the literature of human geography, zoology, entymology, sociology, history, and economics to mention only a few. The variety of map sources lends diversity to the map examples in the survey and produces a more complete list of spatial interaction maps.

⁷Willard C. Brinton, <u>Graphic Presentation</u> (New York City: Brinton Associates, 1939), pp. 216-30; Erwin Raisz, <u>Principles of Cartography</u> (New York: McGraw-Hill Book Company, 1962), pp. 218-19; Phillip C. Muehrcke, <u>Map Use: Reading, Analysis, and Interpretation</u> (Madison, Wisconsin: JP Publications, 1978), p. 78

⁸Arthur Robinson, Randall Sale, and Joel Morrison, <u>Elements of Cartography</u> (4th ed.; New York: John Wiley & Sons, 1978), p. 78; David J. Cuff and Mark T. Mattson, <u>Thematic Maps: Their Design and</u> Production (New York: Methuen & Co., 1982), p. 43

Library of Congress subject headings are used to locate sources containing maps of spatial interaction.⁹ Additional sources for maps are atlases, journals, and textbooks of both spatial interaction and cartography. Bibliographic entries under the various subject headings are examined for a description of the contents and the presence of maps. From these entries, and the other sources mentioned, a hand-picked group of maps is collected. Since the maps are collected for the purpose of building a classification scheme, they are selected on the basis of whether or not each newly discovered map represents a unique class of maps. Conceivably, collecting examples of spatial interaction maps could continue indefinitely. In order to know when to stop, the requisite question to be asked may be: "Is the population of maps collected so far representative of the entire universe of spatial interaction maps?". In this survey, map collection and classification are concurrent processes. Maps are collected and criteria for classification are simultaneously developed. An intuitive feeling for the diversity of spatial interaction maps is acquired while collecting the group. Map collection ends and a working classification scheme can be developed when new map types are found only rarely in the literature. It should be noted that because collection and classification are concurrent processes in this study, the task of classification can never be complete. Since the universe of spatial interaction maps can never be completely known, revisions may be needed as exceptions to the scheme are found. As an ongoing process, revisions to the classification scheme will provide

⁹A list of subject headings used in the survey can be found in Appendix A.

the means for further exploration of mapping methods.

Classification Rationale

Once a number of spatial interaction maps are collected, can each map be considered unique? If each map is considered unique, with characteristics unrelated to all other maps in the group, no comparisons can be made among them. This is not the case, however, because similarities do exist among the maps. Classification is integral to the survey because it brings order to the population of maps that is collected. Classification, according to characteristics developed later in the thesis, establishes similarities and differences among the maps and makes it possible to consider the population as coherent groups of maps rather than as a collection of individual maps. Grigg succinctly states the purpose of classification:

- 1. To give names to things.
- 2. To transmit information.
- 3. To make inductive generalizations.¹⁰

Before classification of maps is possible, a basic understanding of graphic communication, especially the process of map making, is necessary. Graphic communication, or graphicacy, is one of the four modes of human intelligence and

¹⁰David Grigg, "The Logic of Regional Systems," <u>Annals of the Association of American Geographers</u>, Vol. 55 (September, 1965), 469.

communication noted by Balchin.¹¹ Graphicacy is fluency in communication of spatial information using graphic methods such as cartography, computer-graphics, photography, diagrams, and charts.

What is the process that produces maps? Cartographic communication, a form of graphic communication, includes the ability to make maps as well as the ability to read maps. Making maps involves several steps and requires knowledge of concepts and skills such as: objectives of the map, intended audience of the map, data collection and analysis, data symbolization, map design, and production methods. Map making is composed of cartographic input elements, interpretation and processing by the cartographer, and output elements. Four steps, or levels of processing represents increasing involvement by the cartographer in the map making process and also increasing abstraction of the phenomenon under study. Understanding the process of map making helps define the characteristics of maps and develop the criteria for use in classifiying maps.

Classification may proceed by either logical subdivision of a group toward individuality, or by agglomeration of individuals into groups. Agglomerative techniques of classification are usually based on measurable quantitative

¹¹The other three modes of human intelligence and communication are numeracy (fluency in numerical communication), literacy (fluency in written communication), and articulacy (fluency in verbal communication). See W. G. V. Balchin, "Graphicacy," <u>The American Cartographer</u>, Vol.3, No.1 (1976), 33.

	INPUT	INTERPRETATION/PROCESSING	OUTPUT
	(elements)	(processes)	(abstractions)
STEP 1	Phenomena >>>>>	> Knowledge of: objectives, audience,	>>> Raw Data
STEP 2	Raw Data >>>>>>	> data collection and analysis, symboliza-	>>> Analyzed Data
STEP 3	Analyzed Data >>	> tion, design, and production.	>>> Symbolized Data
STEP 4	Symbolized Data	>	>>> Map

Figure 2-1: The process of map making, a part of cartographic communication characteristics of the individuals to be grouped.¹² Since individuals are assembled into subgroups, and subgroups are further assembled into groups of higher order, the agglomerative technique obviously works best if the entire population is known at the onset of classification. New and different individuals are likely to upset the logic of a classification scheme created by an agglomerative technique to the extent that devising a new scheme may be necessary to accommodate them. Conversely, classification by logical subdivision is based on the qualitative characteristics of a population which may not be known in its entirety. As subgroups with new characteristics are identified, new classes are created to accommodate them. In this way new individuals may fit into an existing subgroup or a new subgroup may be created for that purpose. Logical subdivision may, however, create classes that have no members. Maps in these classes exist only

¹²R. J. Johnson, <u>Classification in Geography</u>, Concepts and Techniques in Modern Geography, No.6. (Norwich: Geo Abstracts, 1975), p. 5.; Robert H. Stoddard, <u>Field Techniques and Research Methods in</u> Geography (Dubuque, Iowa: Kendall/Hunt Publishing Company, 1982), p. 283.

in the logic of the classification system. These "empty" classes, discussed later in this chapter, provide one means for exploring new mapping methods.

Creating a classification scheme evokes the inevitable question, "When should the process stop?". When does logical subdivision of the population of maps end? Subdivision could proceed until a separate class exists for each existing spatial interaction map. Classification is a subjective process used as a tool for specialized purposes. Consequently, the point where classification ceases is subjective depending upon its purpose. One objective of this chapter is to look for theoretical classes of spatial interaction maps where no or only a few maps are found. Classification by subdivision stops when two conditions are met: when specialized criteria for classification describing maps of spatial interaction have been used in the scheme, and when vacant classes of maps are created.

Criteria for Classification

The criteria established for classifying maps describe characteristics of map symbolism rather than characteristics of spatial interaction. The thesis does not focus on analysis of spatial interaction but uses analysis as a tool in the design of mapping methods. The question asked in classification is "How does the map depict spatial interaction?" rather than, "What are the characteristics of interaction shown by the map?." Classification progresses from criteria describing map characteristics in general to criteria which are specific to maps of spatial interaction.

Three criteria are used to develop the classification scheme for maps of

spatial interaction.

- 1. Form of symbolism
- 2. Scale of symbolism
- 3. Movement symbolism

Each of these is discussed in the sections which follow.

Form of symbolism

Symbols used by cartographers to represent data include letters, numerals, points, lines, and areas. Letters are usually used by cartographers to symbolize qualitative data of either a positional, linear, or areal nature. Numerals are used to symbolize quantitative data also of either a positional, linear, or areal nature (Figure 2-2 and 2-5). Point symbols are graphic devices usually used to represent positional data such as buildings, oil wells, mountain peaks, or cities (Figure 2-12). Occasionally, point symbols are used to represent data common to areas, such as states (Figure 2-3 and 2-4). Line symbols are graphic devices used to represent geographic data of various dimensions in nature. Contour lines are line symbols which represent the elevations at a number of data points. Obviously, line symbols may represent linear data such as rivers and roads. Line symbols may also represent data which show movement between areas (Figure 2-11). Area symbols are graphic devices used to symbolize data common to areas or geographic regions (Figure 2-6, 2-7, and 2-10).

Points, lines, and areas which appear on a map may be described as pictoral symbols, in contrast to letters (literal symbols) and numerals (numerical symbols). In much the same way that the images in a painting are visually integrated by a

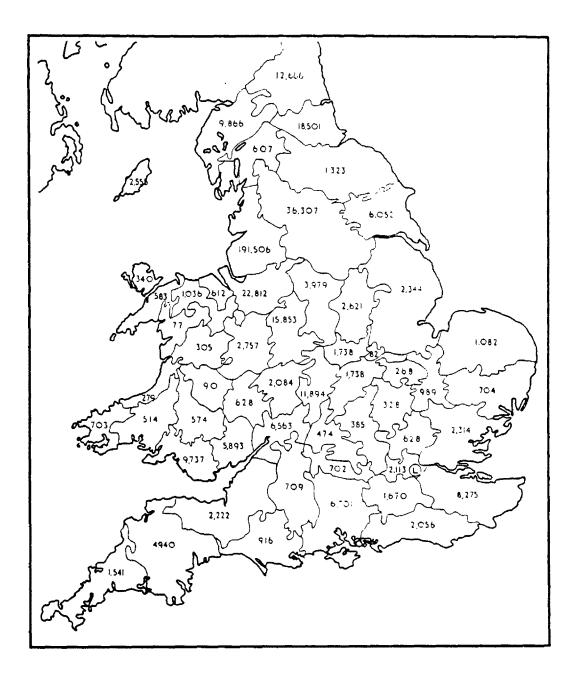


Figure 2-2: Irish migrants in Great Britian¹³

viewer, and in contrast to images in a written text which are read sequentially, a

¹³Arthur Redford, <u>Labour Migration in England, 1800–1850</u> (2nd. ed.; Manchester: Manchester University Press, 1964), p. 194.

map representing data with pictoral symbols can be read as a whole. The graphic elements listed by Robinson¹⁴ (hue, value, size, shape, spacing or pattern, orientation, and location) can be varied for point, line, and area symbols, to change both their appearance and their meaning. Increased size of the point symbols (spheres) used in Figure 2~3 represents a larger number of student migrants. The meaning of letter and numeral symbols is not changed by variations in these graphic elements. By altering the graphic elements, point, line, and area symbols may produce maps that show distribution and movement of things more readily than maps using only letters or numerals. The maps in Figures 2–2 and 2–3 convey similiar information, yet Figure 2–3 creates a greater visual impact by allowing the viewer to picture the distribution of migrating students in the fifty states at a glance.

All graphic symbols, especially line symbols, are used in maps of spatial interaction. All geographic phenomena are perceived to possess a distinct spatial form, either positional, linear, areal, or volumetric. In thematic mapping, the way spatial data are depicted depends upon the interpretation of the cartographer. Symbolization is the process of changing data into graphic form (Figure 2–1). The process is subjective; cartographers may chose to represent data and phenomena with various graphic forms. This is illustrated by the maps appearing in Figures 2–4 and 2–5. Point symbolism is used to portray migration to and from the state of Utah over a period of time in Figure 2–4. The point symbols (small human

¹⁴Arthur H. Robinson, et al. Elements of Cartography (5th ed.; New York: John Wiley & Sons, 1984), pp. 141-43.

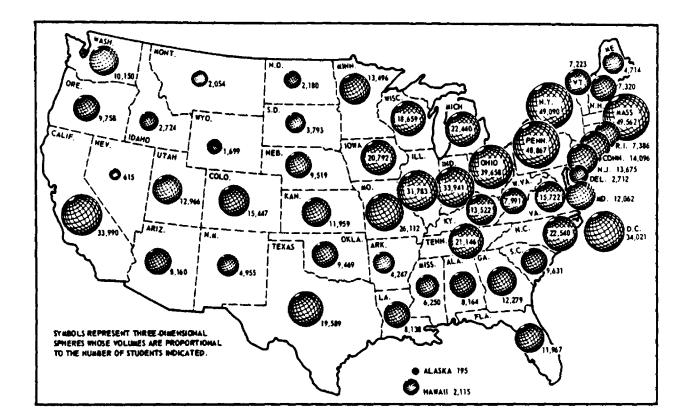


Figure 2-3: Student in-migration, U.S., 1963¹⁵

figures) display the origins, destinations, and quantity of migrants either leaving or entering Utah from every other state in the contiguous United States. Essentially the same type information found in Figure 2-4 is depicted for North Dakota in Figure 2-5; but in this instance, line symbols are used rather than point symbols. Origins, destinations, and quantity of migrants are all symbolized by lines.

¹⁵Charles S. Gossman, <u>Migration of College and University Students in the United States</u> (Seattle: University of Washington Press, 1968), p. 17.

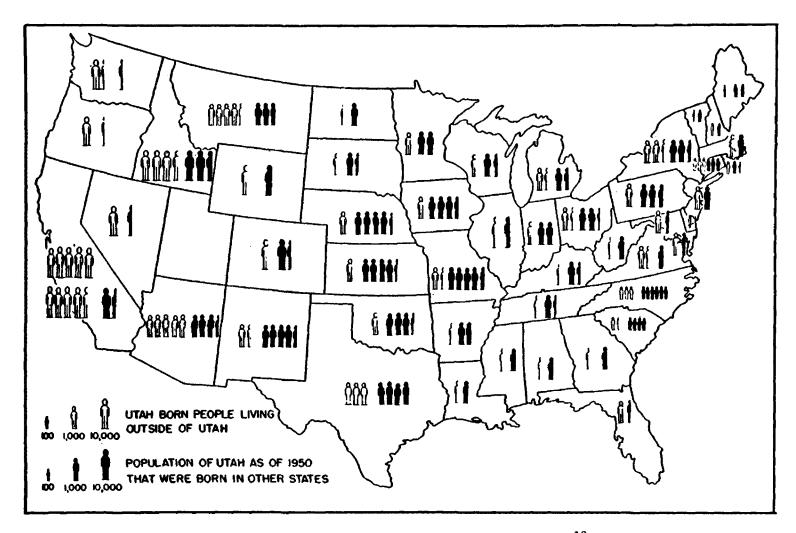


Figure 2-4: In- and out-migrants, Utah, to 1950¹⁶

¹⁶Elroy Nelson Utah's Economic Patterns, Salt Lake City: University of Utah Press, 1956, p. 5

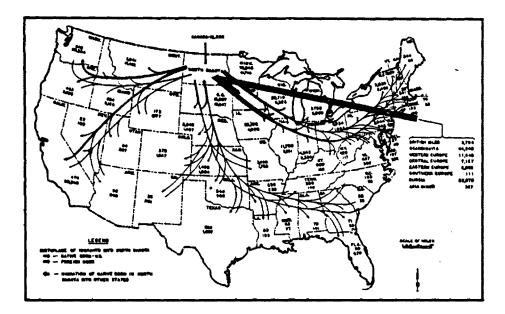


Figure 2-5: Migration to and from North Dakota: 1920-1930¹⁷

All maps employ symbolism of one or more forms. Each form of symbolism possesses certain characteristics which the cartographer must choose between in order to produce maps which are both effective and accurate.

¹⁷Willard C. Brinton, <u>Graphic Presentation</u> (New York City: Brinton Associates, 1939), p. 220.

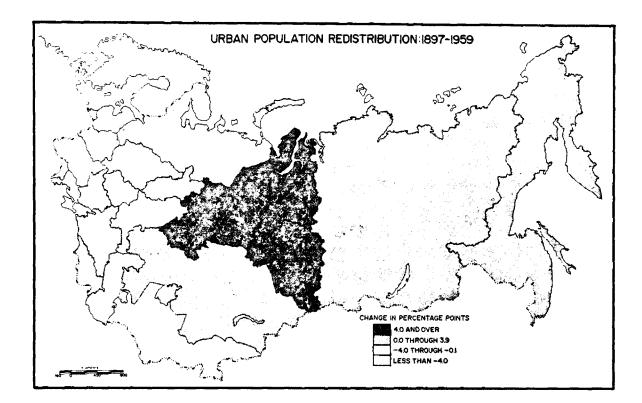


Figure 2-6: Population redistribution, USSR, 1897-1959¹⁸

¹⁸Robert A. Lewis and Richard H. Rowland, "Urbanization in Russia and the USSR: 1897-1966," <u>Annals of the Association of American Geographers</u>, Vol. 59, No. 4 (December, 1969), 786.

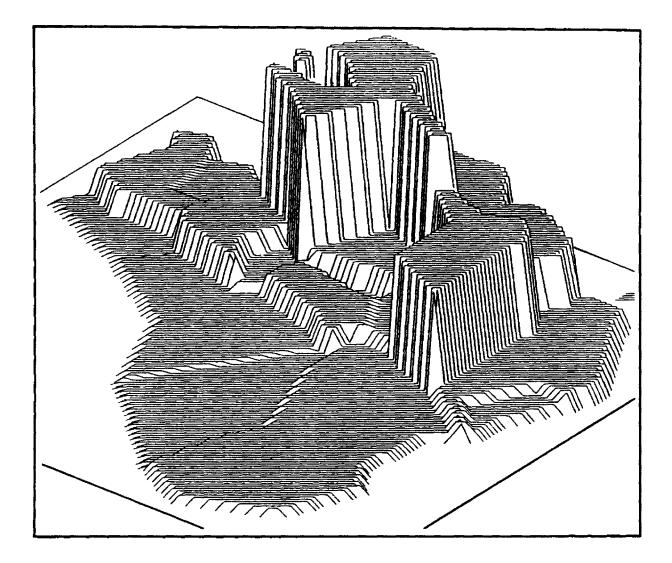


Figure 2-7: Rate of growth by region, Ecuador, 1945-75¹⁹

¹⁹Daniel R. Vining, "The Growth of Core Regions in the Third World," <u>Scientific American</u>, Vol. 252, No. 4, April, 1985, p. 45.

Scale of symbolism

Symbolism represents geographic phenomena on three scales of increasing precision: nominal, ordinal, and interval/ratio. Nominal scale symbolism differentiates mapped phenomena by qualitative characteristics. Roads, rivers, gas pipelines, oil pipelines, and power transmission lines may all be shown with different types of lines on the same map. The process is known as nominal scaling. The geographic phenomena are divided into categories on the basis of kind only, no quantities are involved. Figure 2–8 provides an example of the use of nominal scale symbolization.

Ordinal scale symbolism depicts the rank order of classes into which the data are grouped. Grouping data into classes and the ranking of classes is done according to either qualitative or quantitative characteristics of the data.

Qualitative rank ordering involves establishing a qualitative hierarchy according to inherent characteristics of the data and creating a class for each level in the hierarchy. Data are then grouped into the classes most fitting to their qualitative characteristics. As administrative units, settlements can be grouped into classes defined by state capitals, county seats, and towns. The hierarchy, or rank of settlements, is determined by the level of government located in a settlement.

In Figure 2-9, quantitative rank ordering creates classes with numerical intervals into which the data are grouped according to their quantitative value. In the process of grouping, and during the subsequent symbolizing of groups, the exact quantitative identities of the data values are replaced by the more general

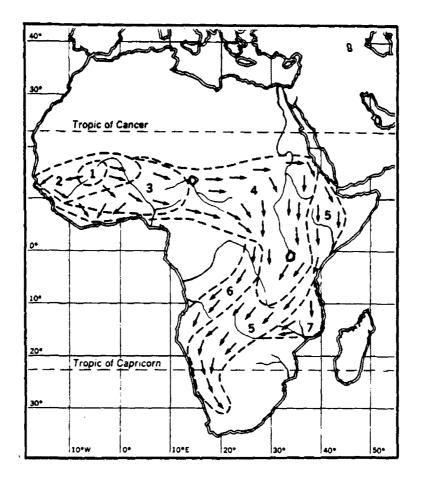


Figure 2-8: Increase and spread of locust in Africa, 1928-34²⁰ interval identities of the classes into which they are grouped. Settlements are grouped according to the quantitative characteristic of population size in Figure 2-9. After grouping and symbolizing, the rank order of settlement size can be determined for settlements of different classes, but not for settlements within a single class.

²⁰Robert T. Orr, <u>Animals in Migration</u> (London: Collier-Macmillan Ltd., 1970), p. 9

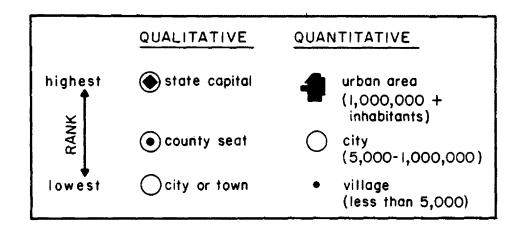


Figure 2-9: Ordinal symbolism, qualitative and quantitative rank

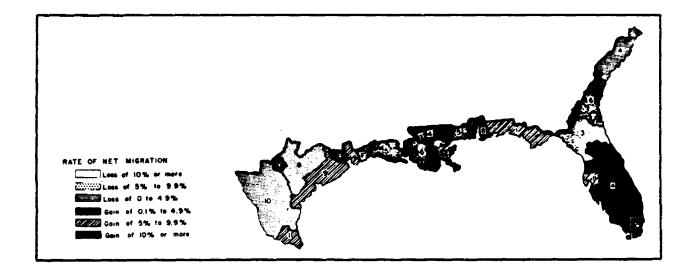


Figure 2-10: Net migration by regions, Gulf Coast states, 1935-1940²¹

Interval/ratio scaling and symbolization differentiate things by units of

²¹Donald J. Bogue, Henry S. Shyrock Jr., and Siegfried A. Hoermann, <u>Subregional Migration in the</u> <u>United States, 1935-40</u>, Vol. 1: <u>Streams of Migration Between Subregions</u> [Oxford, Ohio: Scripps Foundation, Miami University, 1957), p. 86.

quantitative measurement. Interval/ratio symbolism is scaled to fit the individual data values, in contrast to ordinal symbolization which is scaled to the values of classes intervals. Theoretically, exact data values can be retrieved from a map using interval/ratio scale symbolization. Quantitative characteristics are represented on an interval/ratio scale by altering the shape, size, value, or other graphic element of the symbols employed. In Figure 2–11, line symbols are scaled in size (width) to the number of migrants.

The scale of symbolization of the data on a map is an important consideration in the process of mapmaking. It is determined by the data compiled, the map audience, and the intended uses of the map. As such, the scale of symbolization is used as a criterion in classifying maps of spatial interaction.

Movement symbolism

One property of maps is their ability to represent phenomena in a spatial context; that is, they show where things are located. A specialized property of spatial interaction maps is their ability to represent movement from places, to places, and between places. When making such maps, cartographers compile data and select an appropriate form of symbolism and scale of symbolization in order to represent movement.

Movement may be symbolized in spatial interaction maps either implicitly or explicitly. Maps that implicitly depict movement symbolize the location of a place or places involved in spatial interaction without actually showing the path of movement with lines, arrows, or other symbols. For example, in Figure 2–12, only the place of origin of migrants is shown. Neither verbal nor graphic descriptions

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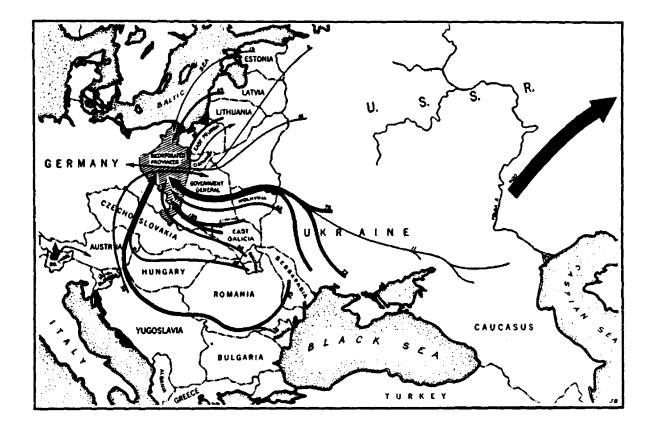


Figure 2-11: Transfer of German minorities, 1939-1945²² are made concerning the destinations of the migrants.

Implicit depiction of movement by a map may include both the place of origin and the place of destination. An example of this is the map in Figure 2-4 that shows both the destinations of out-migrants and the sources of in-migrants for the state of Utah. This map implicitly depicts movement since no graphic

²²Joseph B. Schechtman, <u>European Population Transfers</u> (New York: Oxford University Press, 1946), p. 254.

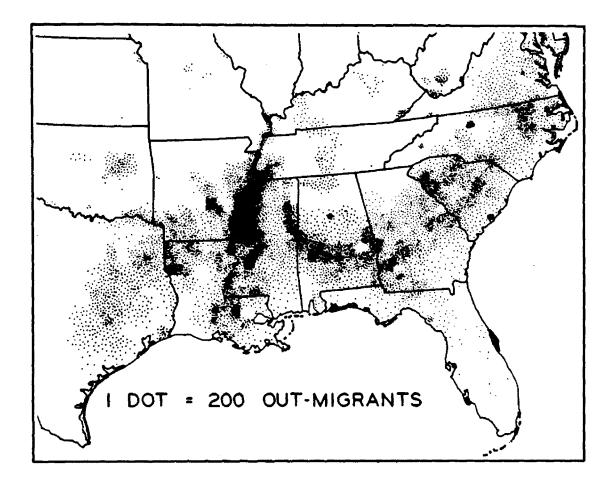


Figure 2-12: Nonwhite out-migrants, southern U.S., 1940-1950²³ connections are made between origins and destinations. The implicit depiction of interaction works because map readers have the ability to infer movement even though it is not explicitly depicted by symbols.

Two factors help the viewer to infer this movement. First, the map title

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²³George J. Demko, Harold M. Rose, and George A. Schnell, <u>Population Geography: A Reader</u> (New York: McGraw-Hill Book Company, 1970), p. 403.

ordinarily states that the subject of the map has to do with some aspect of spatial interaction. Second, the geographic context of point, line, and area symbols provides clues which lead to the conclusion that movement has occurred. Even though no graphic connections are made between places of origin and places of destination, the viewer has the ability to read the map and make mental geographic connections between the symbols. The map viewer may be able to infer specific movements between places depicted by this type of map. Even though very specific, detailed, geographic movements of commodities are implied by some maps, the reader still has the ability to infer the movements involved.²⁴

Maps that explicitly depict movement symbolize the geographic connection between interacting places by placing line symbols (flow lines) between them. Appropriately, cartographers refer to this type of map as a flow map.²⁵ The map viewer need not mentally establish geographic connections between the two places since the symbols do the job explicitly. Flow lines depict movement of phenomena between places on a map. The viewer visually follows the flow lines connecting the places and conceptualizes the interaction between them. If a line connecting two places is not directed (not an arrow), then the viewer cannot

²⁴For examples of maps depicting detailed, specific movements implicitly see: U. S. Department of the Interior, "Shipments of Commodities by Manufacturers: 1963," <u>The National Atlas</u> (Washington D. C.: Government Printing Office, 1970), p. 240.; D. P. Bickmore and M. A. Shaw, "U. K. Overseas Trade: Exports to and Imports from Commonwealth and Foreign Countries," <u>The Atlas of Britian and Northern Ireland</u> (Oxford: Clarendon Press, 1963), p. 171.

²⁵Willard C. Brinton, <u>Graphic Presentation</u> (New York City: Brinton Associates, 1939), p. 216.; G. C. Dickinson, <u>Statistical Mapping and the Presentation of Statistics</u> (2nd ed.; London: Edward Arnold Publishers Ltd., 1973), p. 66-7.; Arthur Robinson, Randall Sale, and Joel Morrison, <u>Elements of</u> Cartography (4th ed.; New York: John Wiley & Sons, 1978), p. 242-43.

differentiate which place is the origin and which is the destination of movement. An example of this type of explicit symbolization is shown in Figure 2~13.

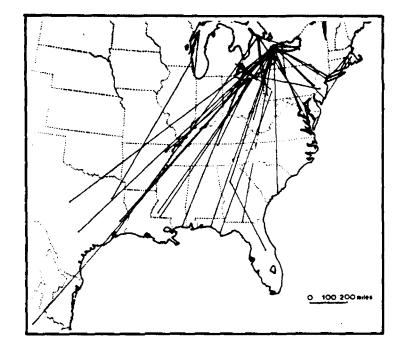


Figure 2-13: Release and capture points of Monarch butterflies²⁶

More detailed movement may be shown by simply making lines into arrows. Arrows direct the viewer's eye from place of origin to destination. Interaction depicted in this way is no longer general movement between places but is directed movement (Figures 2-5, 2-8, and 2-11).

Flow lines may depict absolute paths of interaction, as in traffic flow maps,

²⁶C. G. Johnson, <u>Migration and Dispersal of Insects by Flight</u> (London: Methuen & Co. Ltd., 1969), p. 571.

or they may depict conceptual paths of interaction (Figure 2-11). In the case of conceptual paths of interaction, placement of flow lines may be entirely a consideration of graphic design. Lines then serve only to connect places; their paths are irrelevant.

A Classification Scheme

As described earlier in this chapter, the process of developing a classification scheme, or similiarity tree, and the collection of those maps occurs simultaneously. The procedure begins by consulting the sources to find maps of spatial interaction. As maps are encountered in the literature, they are examined to see if they depict a topic in spatial interaction. If not, they are placed in the category "all other maps" (Figure 2–14). If they do depict spatial interaction, they are placed in a group which is then further subdivided by the classification criteria described in previous passages: the form of symbolism, the scale of symbolism, and whether movement is symbolized implicitly or explicitly.

The first step is to examine spatial interaction maps to determine which form of symbolism is used to depict movement: letter or numeral symbols, point symbols, line symbols, or area symbols. Some maps use more than one form of symbolism. Examples are commonly found which combine numeral and point symbols (Figure 2-3), numeral and line symbols (Figure 2-11), and line and area symbols (Figure 2-15) to name a few. Maps using multiple forms of symbolism are classified by that form which most readily displays the interaction taking

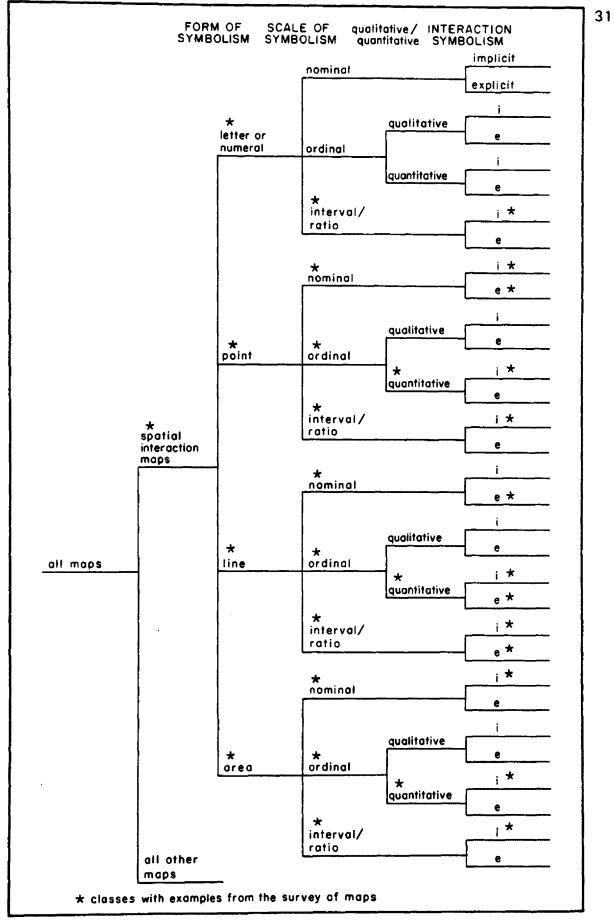


Figure 2-14: Classification tree for spatial interaction maps

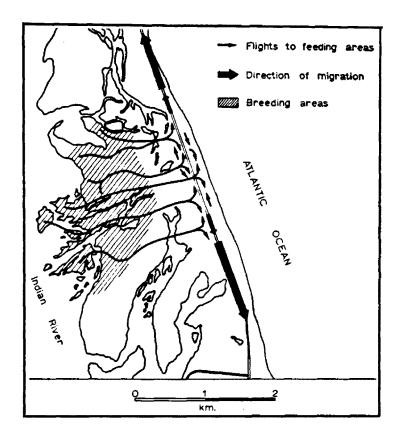


Figure 2-15: Direction of flights for butterflies, Florida²⁷

place.²⁸

After the principal form of symbolism is determined, then maps are examined to determine whether the scale of symbolization is nominal, ordinal-qualitative,

²⁷C. G. Johnson, <u>Migration and Dispersal of Insects by Flight</u> (London: Methuen & Co. Ltd., 1969), p. 443.

²⁸Including the various combinations of multiple forms of symbolism would make a single classification tree too unwieldly. The third level of subdivision in such a tree would have at least fifteen classes, rather than the four classes present at the same level of subdivision in Figure 2-14.

ordinal-quantitative, or interval/ratio. Following this, it is seen if the interaction symbolism depicts movement implicitly or explicitly. Classes in the tree are filled as classification of maps proceeds. No running total of maps in classes at the lowest level of subdivision is kept. One assumption in the classification process is that some classes at the lowest level of subdivision would remain unfilled by maps. This is found to be the case as only thirteen of the thirty-two possible classes are filled by examples of maps found in the literature.

The unfilled, or empty, categories in the classification tree provide the most straightforward means for exploring the possiblity of new mapping methods. In the following chapter, one of the maps (Map 2, a nodal region flow map) is designed to fill such a category.²⁹ Map 2 uses line symbolism, qualitative ordinal scale symbolization, and an explicit depiction of interaction. This category in the classification tree is unfilled by the group of maps collected by the survey.

All maps examined in the process of classification which depict movement explicitly are found to use only line symbolism for that purpose. Can other forms of symbolism besides lines effectively represent movement explicitly? Map 4, a surface relief flow map, explores this problem in the following chapter. In this map, the size (height) of area symbolism is altered, creating an apparent gradient between contiguous states, to represent the direction of net migration.

Categories which are filled in the tree may also call attention to potentially different methods for mapping spatial interaction. Figure 2-7 fills the category

²⁹Map 1, Map 2, Map 3, and Map 4 are introduced on page 39 of the following chapter. They appear on pages 46, 56, 64, and 69 respectively.

defined by area symbolism, ratio scale symbolization, and implicit depiction of interaction. Ratio scale symbolization of in-migration in Figure 2-7 is achieved by altering the size (height) of area symbolism. A new mapping method, one which makes a map that fits into the same category as Figure 2-7, may use variations of a graphic element other than size. In Chapter 3, Map 1, a classless choropleth dot map, is designed which also uses area symbolism. Ratio scale symbolization is achieved by Map 1, however, by altering the graphic element *spacing* (pattern) for dots inside area symbols.

Figure 2-16 shows a standard airline route map using line symbolism, nominal scale symbolization, and explicit interaction symbolization. In Chapter 3, U.S. interstate migration is represented by Map 3, a connectivity network map. Map 3 is essentially the same type of map as Figure 2-16, but mapping migration in this way requires devising a special method for abstracting the data.

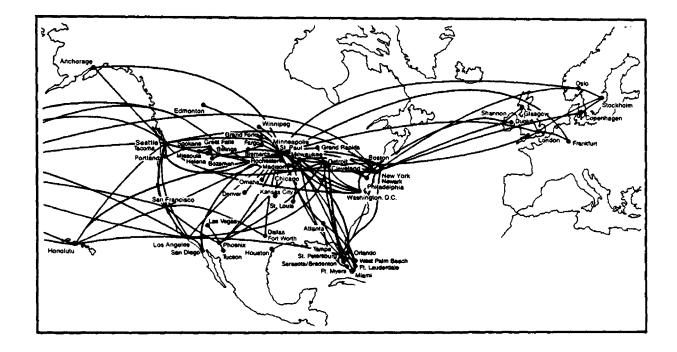


Figure 2-16: Standard airline route map³⁰

³⁰Northwest Orient, System Timetable Effective March 2, 1986, p. 2.

Chapter 3

ANALYSIS AND DESIGN

Analysis of migration data and design of mapping methods to display these data are the objectives of this chapter. The two are organized so that they proceed concurrently. Four mapping methods are designed which fit into several of the various classes of maps defined by the classification scheme in Chapter 2. Each of these mapping methods will be discussed in the passages which follow. They include Map 1, the classless choropleth dot map; Map 2, the nodal region flow map; Map 3, the connectivity network map; and Map 4, the surface relief flow map. Data analysis involves manipulating and abstracting the data into forms compatible with the types of maps produced.

Migration Data

Sources

In 1983 the Census Bureau published a special report titled, <u>State of</u> <u>Residence in 1975 by State of Residence in 1980</u>.³¹ This document is the principle source of information for the maps produced later in this thesis. It contains the volume of interstate migration between all of the states, plus the District of

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³¹U.S. Department of Commerce, Bureau of the Census, <u>State of Residence in 1975 by State of</u> <u>Residence in 1980</u>, Supplementary Report, 1980 Census of Population, (Washington D.C.: Government Printing Office, 1983)

Columbia, for the five-year period between 1975 and 1980. These interstate movements are represented by 2550 data values. A matrix of the original census data is shown in Table B-1, Appendix B. Migration data for the time intervals 1935-40, 1949-50, 1955-60, and 1965-70 are represented in one of the maps. The data for these periods are not listed in the appendix, but sources for them are provided in the bibliography.³²

U.S. migration data are chosen as the basis for the design of the new mapping methods for two reasons. First, most people are familiar with the map of the United States. Familiarity with the study area should facilitate viewing and interpreting the resulting maps. Secondly, both the general topic of spatial interaction and the more specific topic of interstate migration are important in a society as mobile as that of the United States. New methods of cartographically representing migration may be of interest to those in the social sciences, history, planning, commerce, and travel and tourism.

³²U.S. Bureau of the Census, <u>Sixteenth Census of the United States:</u> 1940 Population, Internal Migration 1935 to 1940, Color and Sex of Migrants. (Washington D.C.: U.S. Government Printing Office, 1943), pp. 27–118.; U.S. Bureau of the Census, <u>U.S. Census of the Population:</u> 1950 Vol. IV, <u>Special Reports</u>, Part 4, Chapter B, Population Mobility – States and State Economic Areas. (Washington D.C.: U.S. Government Printing Office, 1956), p. 33.; U.S. Bureau of the Census, <u>U.S. Census of Population:</u> 1960. Subject Reports. Mobility for States and State Economic Areas Final Report PC(2)-2B. (Washington D.C.: U.S. Government Printing Office, 1963), pp. 72–77.; U.S. Bureau of the Census, <u>U.S. Census of Population:</u> 1970. Supplementary Report. Interstate Migration by State: 1970 PC(S1)-48. (Washington D.C.: U.S. Government Printing Office, 1973), pp. 316–20.

Data analysis

Analysis of the data is one step in the process of making new maps for depicting spatial interaction. Manipulating large quantities of census data is facilitated by the use of automated data processing techniques available at the University of Montana. All migration data values are stored in a file using the DECSYSTEM-20 mainframe computer. Data are formatted into a matrix for ease in handling and analysis. Once stored, the data are easily accessed for input into personally written computer programs. A short, one-page computer program written in BASIC+2, which is used for analysis of data, is listed in Appendix C and discussed in the appropriate section later in this chapter. A personal computer is adequate for data handling and analysis of this type.

Map 1, The Classless Choropleth Dot Map

Traditional choropleth maps

Choropleth maps (Greek: choro~place, plethos~quantity) depict either quantity or quality of a phenomenon within the boundaries of established areas. These areas are usually administrative units such as counties, states, or countries for which data have been gathered. The traditional choropleth map "always uses a sequence of shades or tones (values) applied to the areas" in the process of symbolization.³³ For quantitative choropleth maps, this sequence of values, or

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³³David J. Cuff and Mark T. Mattson, <u>Thematic Maps: Their Design and Production</u> (New York: Methuen & Co., 1982), p. 36

variation in some other graphic element, is usually proportional to the quantitative value of the phenomena within given areas. Darker values are normally associated with greater intensities of the phenomenon in the areas depicted. Qualitative choropleth maps may employ some other rationale for organizing graphic elements of the symbolism employed.

In the process of analysis and mapping, areas are grouped into several classes, usually numbering between three and eight. The process of classification strives for maximum homogeneity within classes and maximum heterogeneity between classes. In practicality, the number of classes depicted in choropleth maps is more often than not determined by the number of values discernible by the human eye. In the field of map perception, a considerable amount of research has been conducted and various opinions exist concerning this subject. A comprehensve discussion of selecting class intervals³⁴ and the efficacy of class intervals³⁵ is beyond the scope of this thesis.

Migration ratio by state is the subject for the design of the first mapping method. The migration ratio, r, is simply the per capita migration, including both in- and out-migration, for a state over a period of time. The value of r increases in direct proportion to the migration per capita for a state. This ratio, r, is defined

³⁴George F. Jenks and Michael R. C. Coulson, "Class Intervals for Statistical Maps," <u>International</u> Yearbook of Cartography, Vol. 3, 1963, (Gutersloh, Germany: C. Bertelsmann Verlag, 1963), pp. 119-33.

³⁵Michael W. Dobson, "Choropleth Maps Without Class Intervals?: A Comment," <u>Geographical</u> <u>Analysis</u>, Vol. 4, No. 4 (October, 1973), pp. 358-360; Jean-Claude Muller, "Perception of Continuously Shaded Maps," <u>Annals of the Association of American Geographers</u>, Vol. 69, No. 2, (June, 1979), pp. 240-49.

by the equation

$$r = (m_0 + m_i) / p_t$$

where r is the migration ratio for a state, m_0 is all out-migration from the state, m_i is all in-migration to the state, and p_t is the total population of the state. Table 3-1 contains migration data for all states in the U.S. used in calculating r, the migration ratio.

For comparison to the first mapping method, a traditional choropleth map employing a sequence of gray is presented in Figure $3-1.^{36}$ For this map, data are grouped into four classes in the following manner: first, the data are normalized by taking the log of each state's r value; second, normalized r values are then grouped into classes with equal steps.

Classless choropleth maps

The idea of classless choropleth maps is not new.³⁷ Tobler purports that classless choropleth maps are "now technologically feasible to produce. . . by using automatic map drawing equipment".³⁸ Line symbolism is drawn by a computer plotter in densities proportional to the ratios of the phenomenon for areas of the map (Figure 3-2).

³⁶For a full discussion of the first mapping method, see the section titled "Mapping method" which appears on page 48.

³⁷Classless choropleth maps are also known as unclassed choropleth maps; B. D. Dent, <u>Principles of</u> Thematic Map Design (Reading, Massachusetts: Addison-Wesley, 1985), p. 208.

³⁸W. R. Tobler, "Choropleth Maps Without Class Intervals?," <u>Geographical Analysis</u>, Vol. V, No.3 (July, 1973), 262.

Table 3-1: Migration ratio by state, 1975-80.

s State	^m i IN-MIGRATION	^M O OUT-MIGRATION	Pt POPULATION	r Ratio
ME	112670	106420	1124660	. 19
NH	158633	113868	920610	.30
VT	68055	60596	511456	.25
MA	375613	542597	5737037	. 16
RI	77907	92955	947 154	. 18
CT	270848	345300	3107576	.20
NY	624078	1721275	17558072	.13
NJ	539089	764394	7364823	. 18
PA	573592	837775	11863895	.12
OH	570115	931195	10797630	. 14
IN	384207	467014	5490224	.16
IL	642389	1095726	11426518	. 15
MI	440213	687167	9262078	.12
WI	290020	327998	4705767	.13
MN	274941	318299	4075970	. 15
IA	213026	272704	2913808	. 17
MO	429001	452378	4916686	. 18
ND	75988	86699	652717	.25
SD	70504	90019	690768	.23
NE	152520	180993	1569825	.21
KS	275485	288142	2363679	.24
DE	73839	83060	594338	.26
MD	411716	486469	4216975	.21
DC	98137	170630	638333	.42
VA	694880	630442	5346818	.25
WV	155865	150576	1949644	. 16
NC	538400	451156	5881766	.16
SC	331687	265013	3121820	. 19
GA	581553	450430	5463105	. 19
FL	1801362	978135	9746324	.29
КҮ	302827	279889	3660777	. 16
TN	450858	347872	4591120	.17
AL	319954	272714	389388 8	. 15
MS	213197	215407	2520638	. 17

table continued on following page

Table 3-1, continued

s m _o m _o P _t STATE IN-MIGRATION OUT-MIGRATION POPULATION	r RATIO
AR 262214 206074 2286435	.20
LA 324666 278116 4205900	. 14
OK 382721 265903 3025290	.21
TX 1436237 862230 14229191	.16
MT 108314 106796 786690	.27
ID 170218 125840 943935	.31
WY 120161 72803 469557	.41
CO 551339 422654 2889964	.34
NM 206948 176868 1302894	.29
AZ 598368 352680 2718215	•35
UT 203062 136664 1461037	.23
NV 234606 121917 800493	.45
WA 621101 340684 4132156	.23
OR 412552 245696 2633105	.25
CA 1877289 1782831 23667902	. 15
AK 105570 121650 401851	.57
HI 149919 173741 964691	- 34

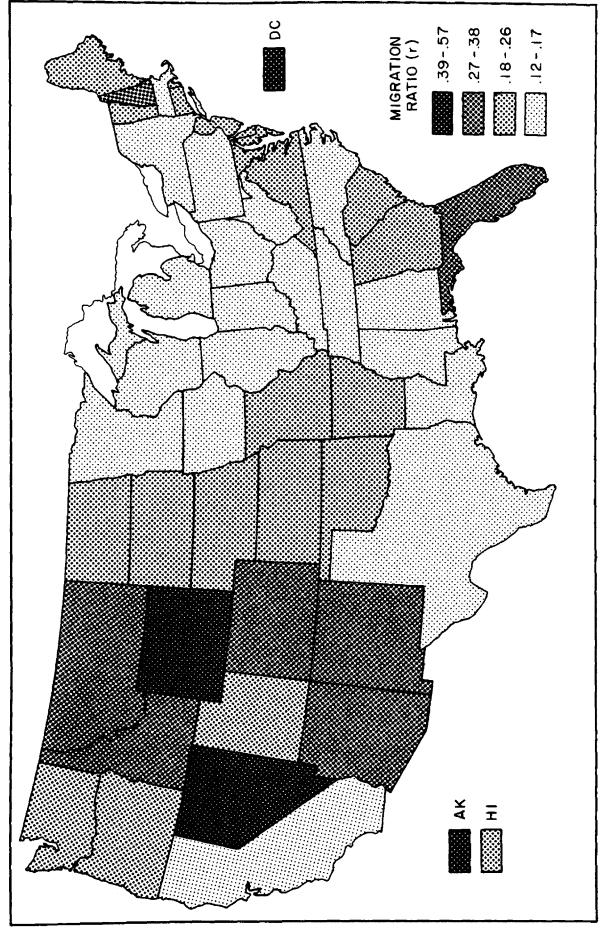


Figure 3-1: Traditional choropleth map using values

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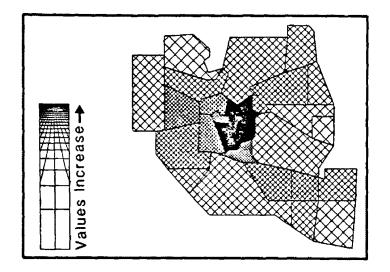


Figure 3-2: Classless choropleth map drawn by a computer plotter³⁹

More recent work with this cartographic problem produces gray tones by facsimile in proportion to quantitative values.⁴⁰ Classless choropleth maps do not group data into class intervals; rather, symbolism is scaled in proportion to the exact quantitative value for each choropleth area. For example, potentially, there are fifty-one discrete data values for migration within the U.S. because there are census data for fifty states and the District of Columbia. A classless choropleth map will display varying shades for as many of those states as actually have

³⁹David J. Cuff and Mark T. Mattson, <u>Thematic Maps</u>: <u>Their Design and Production</u> (New York: Methuen & Co., 1982), p. 37

⁴⁰The facsimile method produces continuous tones, either electronically or photographically, in proportion to areal data values. Jean-Claude Muller and John L. Honsaker, "Choropleth Map Production by Facsimile," <u>The Cartographic Journal</u>, Vol. 15, No. 1 (June, 1978), 14-19.

different values of migration.

The mapping method

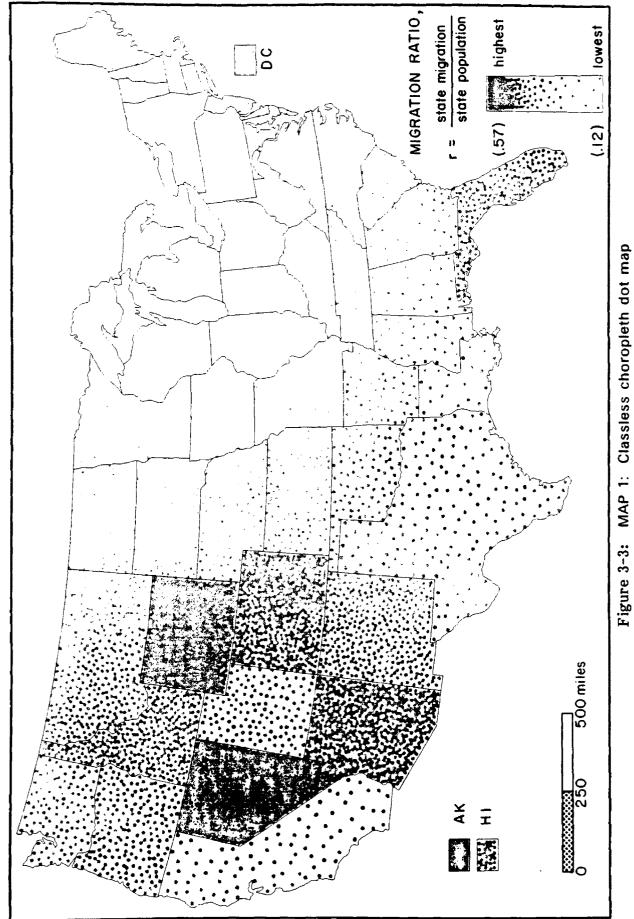
Map 1, the classless choropleth dot map, uses variations in the density of dots in place of the traditional values to depict migration characteristics for each state. Dots have long been used by cartographers as a form of point symbolism on maps. The distribution dot map in Figure 2–12, and the "pointillism" described by Jenks⁴¹ are examples of dots used as point symbols. Actually, the shades used to represent different classes in many traditional choropleth maps are printed as geometric patterns of minute black or colored dots which the viewer mentally blends into grays or shades of a color. As the proportion of inked area on the map surface increases, darker grays or shades of a color are perceived by the viewer.

Three characteristics of dots are considered in making a dot map. These characteristics, which apply to both the standard distribution dot map and Map 1, are:

- 1. Number of dots.
- 2. Size of dots.
- 3. Pattern of dots on the map.

For a distribution dot map, the number of dots is directly proportional to the number of things represented. In Figure 2-12, there is one dot located at the place of origin for every 500 out-migrants. In Map 1, the density of dots is

⁴¹George F. Jenks, "'Pointillism' as a Cartographic Technique," <u>The Professional Geographer</u>, Vol. 5, No. 5 (September, 1953), 4-6.



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proportional to the migration ratio, r, for each state (Figure 3-3). The number of dots in each state is directly proportional to *both* the migration ratio, r, and state size, a. Figure 3-4 illustrates how variations in either the migration ratio or area size affects the number of dots used to represent the ratio for an area.

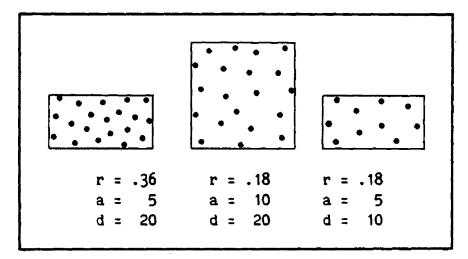


Figure 3-4: Variations in ratio, r, area, a, and dot number, d

The combination of size and number of dots determines what portion of mapped area is covered with dots. Calculating both size and number of dots is an empirical process, determined by both the range of migration ratio values and the range of state sizes. Values of r, shown in Table 3-2, range from .12 to .56 with most of them clustered between .12 and .20. In order that the dot density be visibly distinctive, a relatively bold dot size, .80mm, is used. Three considerations affect the formula used for calculating the number of dots, d,: small states with

small r values must have at least one dot; states with high r values must not have excessive overlapping of dots; and differentiation should be possible for dot densities representing very small variations in r. For this map of the U.S., the formula for calculating dot number per state is

$$d = (a(r^{2.5})) / 1500$$

where d is the calculated number of dots to be placed in the map area, a is state size in thousands of square miles, and r is the state migration ratio. The exponent 2.5 is determined experimentally to increase the difference in dot densities representing states with small differences in migration ratio (e.g. r = .15 and r = .16). The denominatior 1500 which is also determined experimentally, establishes the maximum and minimum number of dots per state on the map.

A distribution dot map and a choropleth dot map are distinguishable because the patterns of dots are different in each instance. A distribution dot map depicts the location of phenomena in an area with accurately positioned dots on the map. The cartographer determines the location of phenomena in the compilation stage of map making and positions the dots accordingly on the map. Ideally, the distribution of dots on the map mimics the location of phenomena in the field. In a classless choropleth dot map, the distribution of dots in no way reflects the location of phenomena in the field. Rather, the dots are positioned in either a random or uniform pattern inside of each region or state (Figure 3-5).

Data sources used for compiling state size should be chosen with care. Values listed for the size of a state may differ significantly from one source to another. For example, Goode's World Atlas lists values for state size using state

Table 3-2:	Number	of	dots	per	state
	Number		4013	P01	State

S	a	r	d
State	Area	Ratio	Dots
	(in 1000's		per state
	square miles)		
ME	33.2	. 19	35
VT	9.6	.25	20
MA	8.3	. 16	6
RI	1.2	. 18	1
CT	5.0	.20	6
NY	49.6	.13	20
NJ	7.8	. 18	7
PA	45.3	. 12	15
OH	41.2	. 14	20
IN	36.3	. 16	25
IL	56.4	. 15	33
MI	58.2	.12	19
WI	56.2	.13	23
MN	84.0	. 15	49
IA	56.3	.17	44
MO	69.7	. 18	64
ND	70.6	.25	147
SD	77.0	.23	130
NE	77.2	.21	104
KS	82.3	.24	155
DE	2.1	.26	5
MD	10.6	.21	14
DC	0.1	.42	1
VA	40.8	.25	85
WV	24.1	. 16	17
NC	53.6	. 16	37
SC	31.1	. 19	33
GA	58.9	. 19	62
FL	58.6	.29	177
КY	40.4	. 16	28
TN	42.2	.17	34
AL	51.6	. 15	30
MS	47.7	. 17	38

table continued on following page

Table 3-2, continued

s	a	r	đ
State	Area	Ratio	Dots
	(in 1000's		per state
	square miles)		
AR	53.1	.20	63
LA	48.5	- 14	24
OK	69.9	.21	94
TX	267.3	. 16	183
MT	147.1	.27	372
ID	83.6	.31	298
WY	97.9	.41	703
CO	104.2	.34	468
NM	121.7	.29	367
AZ	113.9	• 35	550
UT	84.9	.23	144
NV	110.5	.45	1001
WA	68.1	.23	115
OR	97.0	.25	202
CA	158.7	. 15	9 2
AK	586.4	.57	9589
HI	6.5	.34	2 9

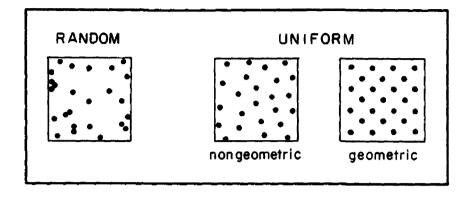


Figure 3-5: Patterns of dot distribution

boundaries that extend into adjacent large bodies of water, such as the political boundaries of the Great Lake states.⁴² State size determined in this way can be quite different from state size determined by using the physical boundaries, shorelines, of these states.

Map 2, The Nodal Region Flow Map

Nodal regions of migration with inherent flow of migrants between nodes are explicitly depicted by the second mapping method (Map 2, the nodal region flow map). This method, employing rudimentary analytical and mapping techniques, efficiently synthesizes and displays migration data. Graph methods used in combination with linear symbolism are part of this method.

⁴²Edward B. Espenshade, Jr., ed., <u>Goode's World Atlas</u> (17th ed.; Chicago: Rand McNally & Company, 1986), pp. 241-45.

Nodal regions

Nodal or functional regions contain networks in which movement of things, such as goods, people, or information, focuses upon central locations or nodes.

The functional region, also called the nodal region, is a coherent structure of areal units organized into a functioning system by lines of movement or influence that converge on a central node or trunk.⁴³

A node is any place, or relatively confined areal unit, that has a unique geographic identity separate from other places. Depending upon the geographic scale of study, a node could be a neighborhood, city, county, state, or nation. The hierarchy of nodes in a region is ordinarily comprised of central and peripheral nodes. The central node is the dominant place in a region in terms of the functional association, or movement of phenomenon, that defines the region. Several levels of peripheral nodes may exist within the hierarchy of the region. Linkages, or routes, of movement in the region are structured in such a way that each peripheral node directs its dominant flow of migrants toward a larger node next higher up in the hierarchy of the region. In this example, the nodal region is defined by the interstate migration of people, and nodes are characterized by the states of the United States.

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⁴³Jesse H. Wheeler, Jr., J. Trenton Kostbade, and Richard S. Thoman, <u>Regional Geography of the</u> World (3rd ed.; New York: Holt, Rinehart and Winston, Inc., 1969), p. 4.

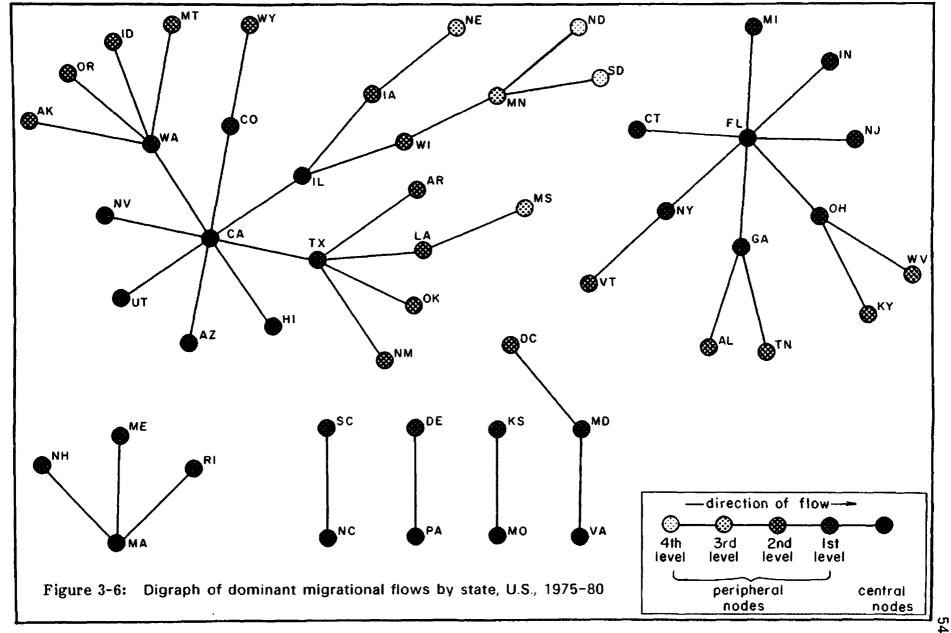
Graphs and matrices

Matrix and graph methods are used to analyze spatial characteristics of the network in a nodal region. A directed graph, or digraph, depicting interstate migration in the United States is shown in Figure 3–6. Digraphs depict not only linkages between nodes but also direction of flow along linkages. The graph of a network can be used to build a numerical matrix representing the network. Similarily, a graph can be constructed from a numerical matrix. The matrix of interstate migration values displayed in Table B–1, Appendix B is used to construct the digraph in Figure 3–6.

Linkages are determined by the largest movement, or flow, of migrants from each node. Each state is linked, in the forward direction, to only one other state. This single forward linkage from each state is to the state to which it sends its largest flow of out-migrants. For example, the matrix in Table B-1 shows Texas to be linked in the forward direction to California.

Hierarchy is determined by the relative functional size of the nodes. Functional size is found by ranking states according to the size of their inmigrating population. The central state of a regional network sends its largest flow of out-migrants to a state functionally smaller in size. Forward linkage is not depicted for central states as they are the largest nodes in the regions and occupy the top of the nodal heirarchy. Peripheral states are linked in the forward direction to states larger in functional size. Third order peripheral states are linked in the forward direction to second order peripheral states. Second order peripheral states are linked in the forward direction to first order peripheral states. Illinois,

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Wisconsin, Minnesota, and North Dakota are first, second, third, and fourth order peripheral states, respectively. California is the central state of that regional migrational network.

The mapping method

The geometry of graphed networks is topological (Figure 3-6). Unlike other geometries used by geographers, topology is not concerned with geographical properties such as distance, orientation, and shape.⁴⁴ Topology presents a highly abstracted geometrical view of spatial structures "concerned with the preservation of certain non-metrical relationships such as proximity, separation, order, enclosure, continuity, and contiguity or connectedness."⁴⁵ Transforming the graphed network in Figure 3-6 onto a base map adds geographic characteristics to the graphed data. The geographic nature of maps is the distinguishing characteristic between cartography and graphics in general. Cartographic depiction is both topological and topographical, within limitations. The graphed nodal regions are shown in map form in Map 2 (Figure 3-7).

The method of mapping used to produce Map 2 lends itself to use in a graphic which depicts a time series by employing multiple maps within a single display. A time series is the display of "data gathered over a period of time,

⁴⁴A brief discussion of the geometries used by geographers is found in John P. Cole and Cuchlaine A. M. King, <u>Quantitative Geography</u> (London: John Wiley & Sons Ltd., 1968), pp. 69-71.

⁴⁵William J. Coffey, <u>Geography, Towards a General Spatial Systems Approach</u> (London: Methuen & Co. Ltd., 1981), p. 120.



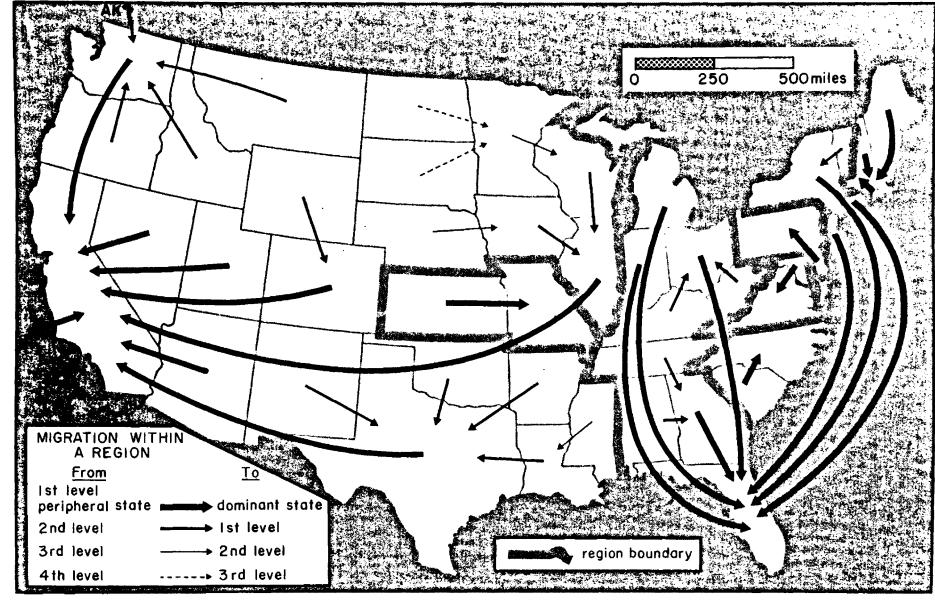


Figure 3-7: MAP 2: Nodal region flow map

usually at regular intervals."⁴⁶ Time is an integral component of spatial interaction. The nodal region map in Figure 3-7 depicts flow in a network of migration within an interval of time. The time series display in Figure 3-8 depicts both the flow in migrational networks within an interval of time and the geographic changes in nodal regions between periods of time. Simplicity in data analysis and map compilation allows the synthesis of a large quantity of migration data into a single graphic display. Figure 3-8 incorporates over 10,000 migration data values (2,550 values for each time interval) within a single graphic display.

Map 3, The Connectivity Network Map

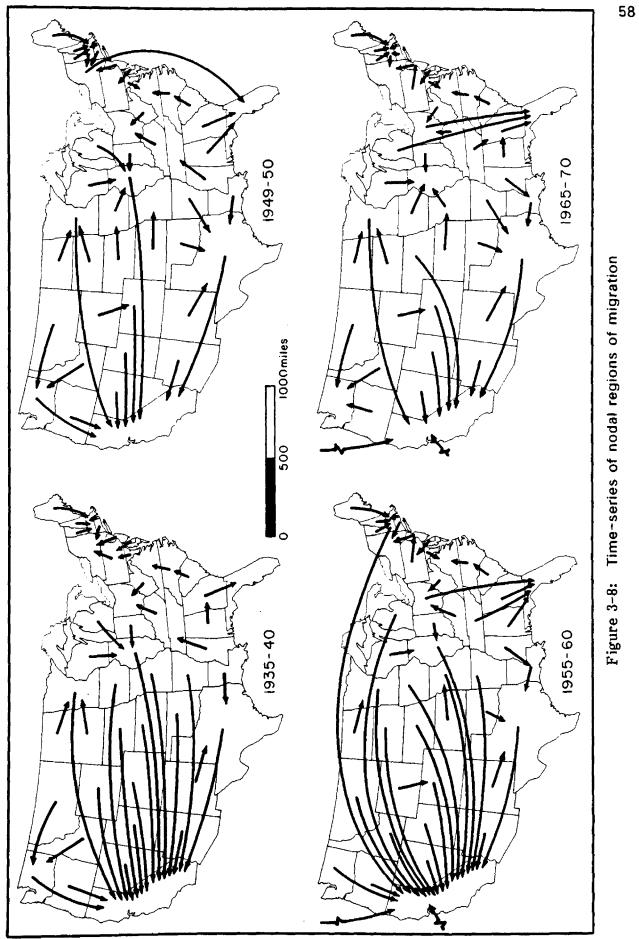
The third mapping method, which is illustrated by Map 3, the connectivity network map (Figure 3-10), uses line symbolism to explicitly depict the interstate migration of people in the United States. A method for abstracting the migration data using automated techniques is presented.

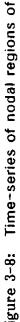
The mathematics of connectivity

Connectivity is a mathematical concept in topology used to describe linkages, or routes of two-way movement between nodes in a network.⁴⁷ A connectivity network has a maximum number of linkages, *l*, between nodes, defined by:

⁴⁶Haggett, Peter. <u>Geography: A Modern Synthesis</u> (New York: Harper & Row, Publishers, 1983), p. 590.

⁴⁷Ronald Abler, John S. Adams and Peter Gould, <u>Spatial Organization</u> (Englewood Cliffs, New Jersey: Prentice-Hall, Inc., 1971), pp. 255-68.





$$l = (n^2 - n) / 2$$

where n is the number of nodes in the network. The connectivity of a network ranges from total nonconnectivity, no linkages between nodes, to complete connectivity, the maximum number of linkages possible.

Symbolizing migration linkages between states with line symbols poses substantial graphic problems. Topologically, the network of migration in the U.S. is completely connected. The matrix of migration values in Table B-1, Appendix B shows linkages of migration to exist between each state and every other state in the United States. In this case, representing complete migration connectivity in map form is folly because of the impracticality of placing that much line symbolism on one map. The maximum number of migration linkages between states and the number of lines necessary to symbolize them for Map 3 is 1275.

> $l = (51^2 - 51) / 2$ l = 1275.

Coffey expresses the need for abstraction in the scientific process:

In geography, as well as in science generally, it is often desirable to consider a problem at a higher level of abstraction so as to gain further insight into the more general relationships that exist among phenomena.⁴⁸

Abstraction of the migration data is necessary in analyzing this problem of connectivity in order to display main migrations of people between states.

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⁴⁸William J. Coffey, <u>Geography, Toward a General Spatial Systems Approach</u> (London: Methuen & Co. Ltd., 1981), p. 118.

The mapping method

Developing a measure of the strength of migration linkages between states and establishing a threshold value for linkages is necessary in order to cartographically depict a connectivity network of migration in the United States. The strength of the linkages between states is determined as a ratio in order to avoid a bias in linkages toward states with large migrating populations. The value representing strength of linkage between two states; k, is defined by the equation

$$k = m_a$$
 to $b + m_b$ to $a / m_{ao} + m_{bo}$

where $m_{a to b}$ is the migration from state a to state b, $m_{b to a}$ is the migration from state b to state a, m_{ao} is the total out-migration from state a, and m_{bo} is the total out-migration from state b. Linkage strength between two states, k, increases as the number of migrants between them increases. Two states with a strong migration linkage are Washington and Oregon.

These two states send a high percentage of the sum of their out-migrating populations to each other. In contrast, North Dakota and Oklahoma have a much weaker migration linkage.

These two states send a relatively small percentage of the sum of their outmigrating populations to each other.

A computer program titled <u>kvalues.b20</u>, shown in Appendix C, calculates linkage values for pairs of states. A file containing the total migration for pairs of states and a file containing the total out-migration for each state are input into the program and stored in matrix form. Linkage values, k, are calculated for all pairs of states using simple loop structures in BASIC+2 programming language (FOR/NEXT statements). Calculated linkage values are then output into another computer file, <u>percent.in</u>. This file is input into a program which formats the linkage values into a matrix and prints them out as hard copy.

A threshold value for linkage strength, for which connectivity is depicted by the network map, is determined in large part by cartographic limitations. The mutual dependence of data and technique sometimes limits cartographic processes.⁴⁹ Just as the number of classes chosen for a choropleth map is limited by the number of values discernible by the human eye, so is the number of linkages limited by the number of flow lines that can be displayed without confusion on the base map. Table 3-3 displays linkage strength values, k, the

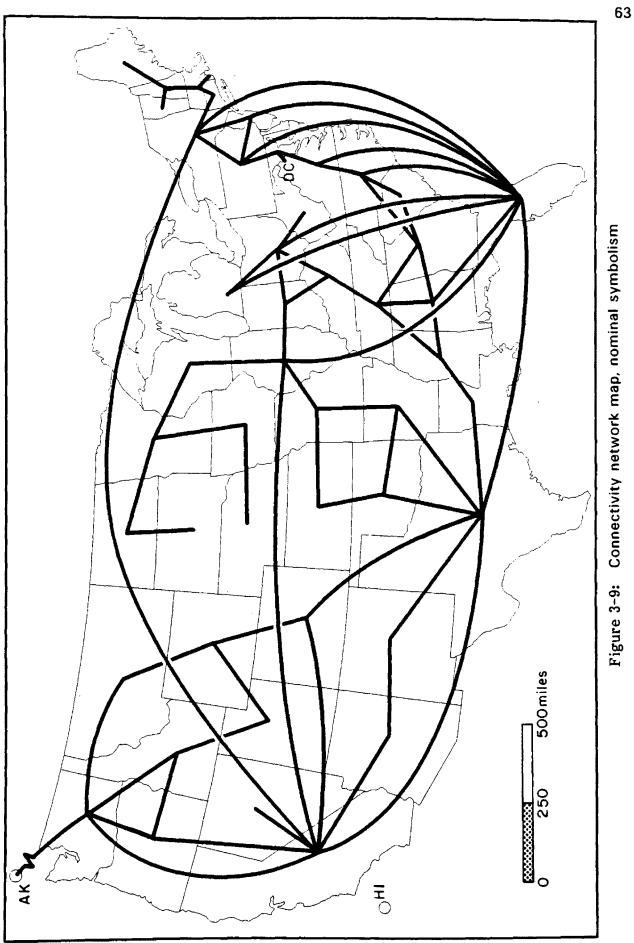
⁴⁹Arthur H. Robinson, <u>The Look of Maps</u> (Madison, Wisconsin: The University of Wisconsin Press, 1952), p. 21.

cumulative percent of migration, c, that each k value represents, and the cumulative number of linkages, or flow lines needed on the map, for each k value.

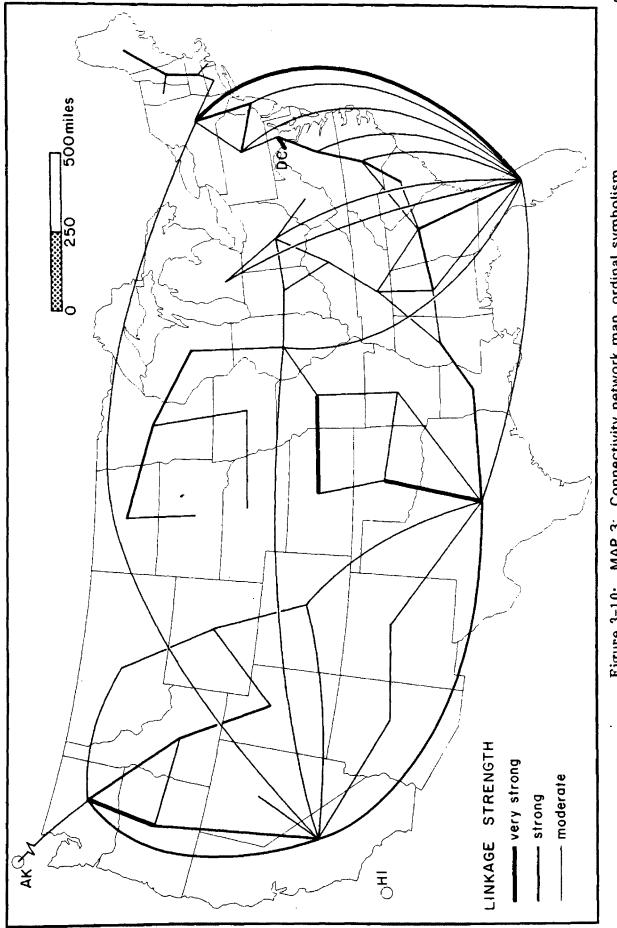
Table 3-3: Linkage strength linkages for U.S. migration, 1975-80.

k	С	t
LINKAGE	CUMULATIVE PERCENT	NUMBER OF
STRENGTH	OF MIGRATION	LINKAGES
.22	00.6	1
. 15	03.2	3
. 14	04.4	5
.13	08.0	10
. 12	10.6	12
.11	15.1	20
. 10	16.0	23
.09	19.9	31
.08	23.0	40
.07	28.4	55
.06	36.9	75
th	reshold value of k fo	r
graphically	representing migrati	on linkages
.05	45.8	109
.04	54.9	151
.03	65.0	216
.02	79.9	355
.01	96.3	821

Migration linkages with strength of .06 and greater are represented in Figures 3–9 and 3–10, but those with a strength below .06 are not depicted. A threshold value for k of .06 is chosen for these maps because it is felt that 75 is the maximum number of flow lines these particular maps can clearly display. Displaying 151 or even 109 flow lines may be counterproductive to representing interstate migration patterns. Additional empirical research into the topic of line symbolism and map readability may yield valuable information.



Connectivity network map, nominal symbolism Figure 3-9:



MAP 3: Connectivity network map, ordinal symbolism Figure 3-10:

These connectivity network maps abstract migration between states in much the same way that transportation connectivity between towns and cities is depicted by road maps. A map of the U.S. Interstate System depicts a relatively sparse transportation network linking few U.S. towns and cities. Considering all U.S. towns and cities, a map of interstate highways depicts a network closer to total nonconnectivity than to complete connectivity. Including U.S. highways in the above map increases the number of linkages and the number of towns and cities linked with the transportation network. Further inclusion of state highways and county roads increases connectivity of the transportation network of U.S. towns and cities even more.

Interpretation

A linear link between states on a connectivity map represents migration between those states. Figures 3-9 and 3-10 reveal distinct patterns of interstate migration. Some states are frequently linked within the network (California and Florida) while other states are totally unlinked within the network (Hawaii and Delaware). Questions arise such as "Why are noncontiguous states sometimes linked?"; "Why are contiguous states sometimes unlinked?"; "Why are some states without any linkages?"; "Why are some states frequently linked within the network?". Viewing and interpreting the connectivity network map may best be done with Ullman's model of spatial interaction.⁵⁰ Linkages between Florida and northern states may be due to the large number of retirement age people migrating south during the years 1975-80 seeking a more comfortable environment. Intervening opportunities for people in Nebraska and Kansas may affect the interstate migration between those two states. Obviously, transferability is a major factor in the relatively unconnected conditions for Alaska and Hawaii.

Map 4, The Surface Relief Flow Map

Net migration and barriers to migration between contiguous states are depicted by the last mapping method. Explicit depiction of net migration between contiguous states is accomplished without using line symbolism by altering the graphic element *size* (height) of the area symbolism on the map. The concept of connectivity described in the previous section is used to develop this mapping method. Automated mapping techniques produce two different maps in the process of creating Map 1, the surface relief flow map. A third map, produced using traditional techniques using flow lines, is included for comparison.

⁵⁰The determinants of spatial interaction postulated by Ullman are complementarity, intervening opportunity, and transferability. <u>Complementarity</u> describes the condition where a surplus of things occurs in one place and a deficit of the same occurs in another place, acting as a stimulus to interaction between those places. If, however, <u>intervening opportunities</u> for supply or demand exist, the course of interaction may be affected. The third factor, <u>transferability</u>, describes resistance to interaction between places. Time and cost are two transferability factors. Edward Ullman, <u>American</u> Commodity Flow (Seattle: University of Washington Press, 1957), pp. 20-27.

Explicit depiction of flow

The survey of maps of spatial interaction conducted in Chapter 2 finds movement between two places to be depicted either implicitly or explicitly. All maps of spatial interaction examined and classified as explicit are found to symbolize movement with flow lines. (See Figures 2–11, 2–5, and 2–13). Figure 3–11 depicts net migration between contiguous states, in a traditional manner, with flow lines.

Symbolizing net migration between contiguous states without flow lines is accomplished by two means. First, contiguity of states is broken where migration between those states is below a certain threshold value. The concept of linkage strength, k, developed in mapping method number three is used to determing contiguity of states in Map 4. The threshold value used for Map 3, is also used for Map 4. Second, the net flow of migration is symbolized by a gradient created by the apparent differnces in the relief surfaces of states. Figure 3-12 depicts net flow of migrants following the gradient created by the apparent differences in the heights of the relief surfaces of contiguous states. SYMAP and ASPEX, two computer software packages, are used in conjunction with each other to create three-dimensional perspective maps.⁵¹ In addition to width (x-dimension) and length (y-dimension), height (z-dimension) is used to describe each state area in

⁵¹The Synagraphic Mapping System (SYMAP) and Automated Surface Perspectives (ASPEX) are used to produce Figures 3-15 and 3-12, respectively. Mark Hanson, <u>ASPEX User's Reference Manual</u> (Cambridge, Massachusetts: Laboratory for Computer Graphics and Spatial Analysis, Graduate School of Design, Harvard University, 1978); Allan H. Schmidt and Eric D. Teicholz, <u>SYMAP User's Reference Manual</u> (5th ed.; Cambridge, Massachusetts: Laboratory for Computer Graphics and Spatial Analysis, Graduate School of Design, Harvard University, 1978).

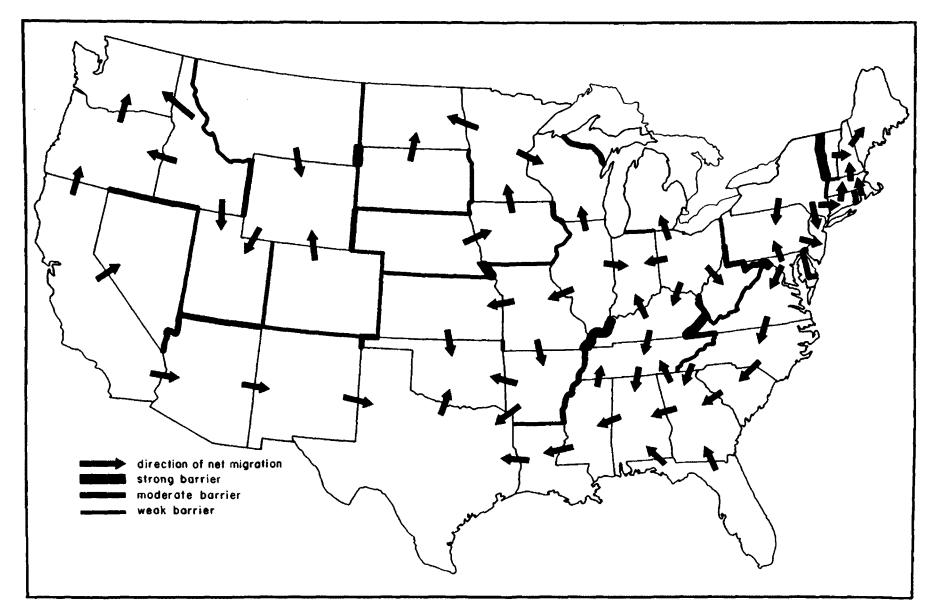


Figure 3-11: Net migration, contiguous states, using flow lines

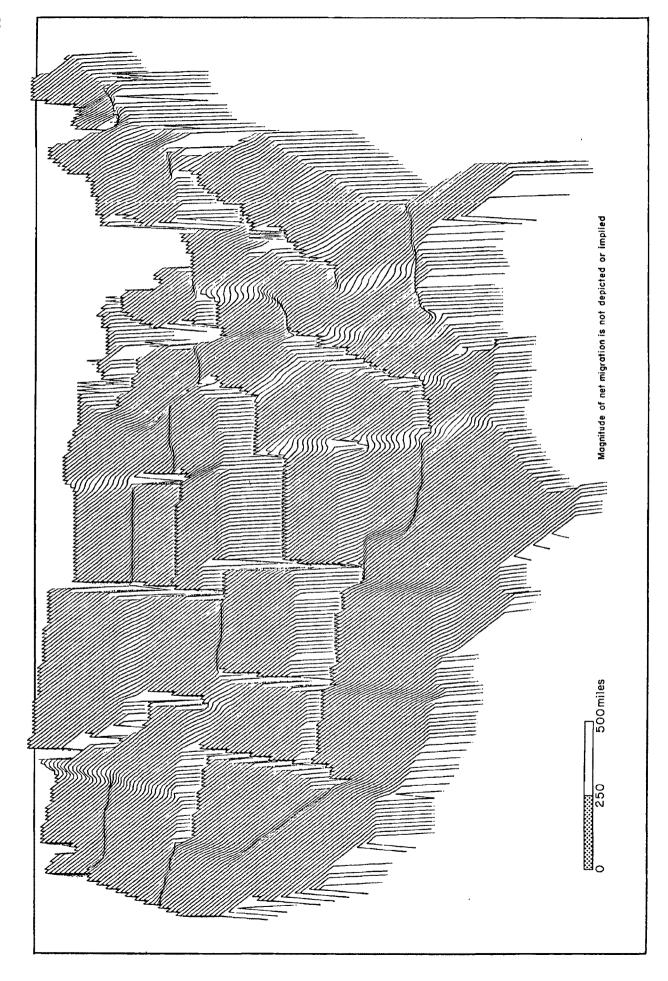


Figure 3-12: MAP 4: Surface relief flow map

the ASPEX computer program. A computer plotter draws state areas with heights corresponding to the z-dimension values assigned to them in the program. The direction of net flow between contiguous states is from the state symbolized by the higher relief surface to the state symbolized by the lower relief surface. A scheme showing direction of net flow is presented in Figure 3-13.

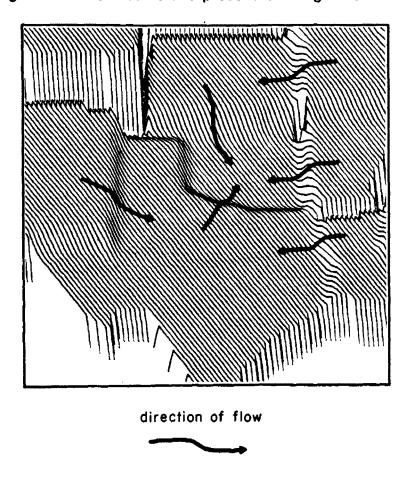


Figure 3-13: Symbolization of direction of net flow

Data analysis involves determining both the strength of migration linkages and the direction of net migration between contiguous states. Where the strength of migration linkages falls below .06, barriers to migration are interpreted to exist and contiguity between states is broken. Values of k below .06 are grouped into three classes; .01-.02, .03-.04, and .05-.06, representing strong, moderate, and weak barriers to migration, respectively. Barriers to migration are depicted on the map as breaks in the continuity of the area symbolism (Figure 3-15) or as breaks in the relief surface (Figure 3-12) which are proportional in width to the intensity of the migration barrier. Linkage strength, barrier intensity, and corresponding map barrier width are listed in Table 3-4.

Table 3-4: Linkage strength and corresponding barrier characteristics

k linkage strength	i barrier intensity	mapped barrier width	
.0102	strong	8 mm	
.0304	moderate	6 mm	
.0506	weak	4 mm	

Barriers are plotted on a working base map by redrawing state boundaries. Gaps are drawn in proportion to barrier intensity. Figure 3-14 illustrates redrawn state boundaries to reflect barriers of migration between South Dakota and neighboring states. Data points along redrawn state boundaries are digitized on an inverted Cartesian coordinate system for entry into the mapping program. The

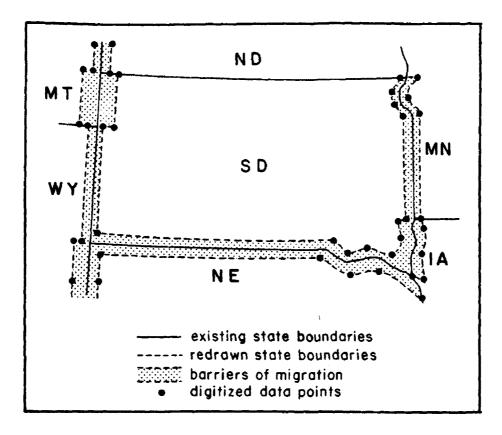
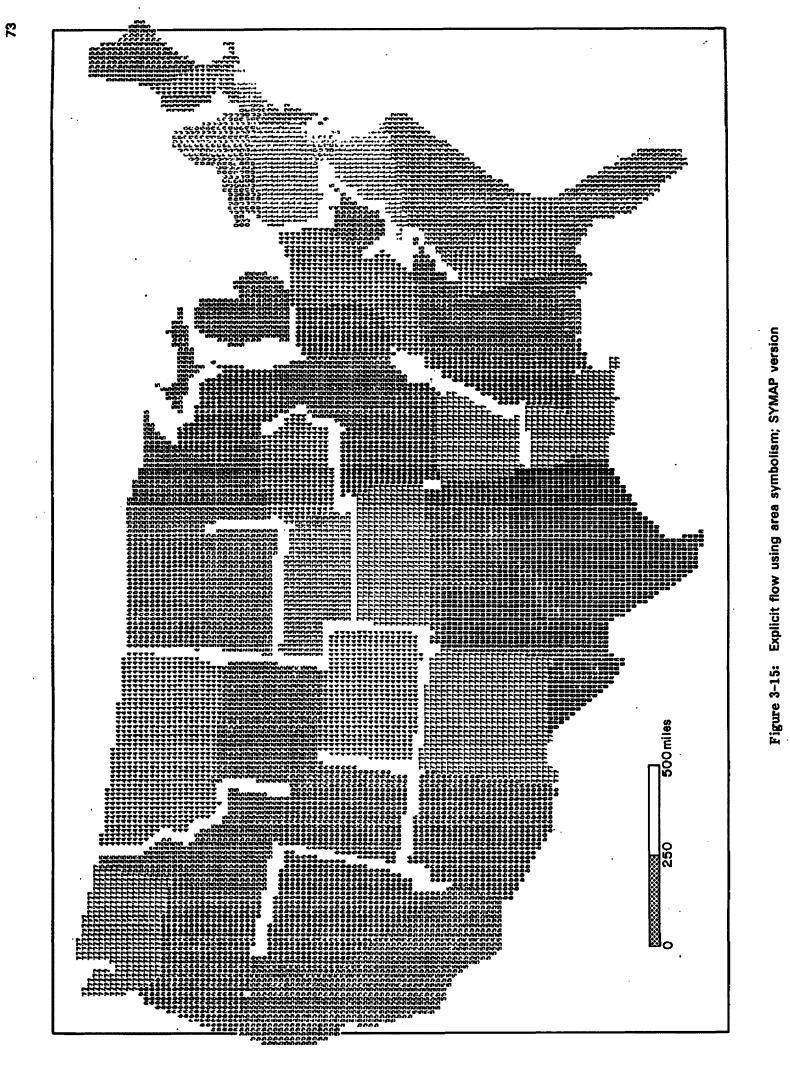


Figure 3-14: Working base map with redrawn state boundaries SYMAP mapping program serves as an intermediate step in the final production of the surface relief flow map. The SYMAP version, shown in Figure 3-15, uses area symbolism (overprinted characters) formed by a line printer. The ASPEX program transforms the two-dimensional area symbolism in Figure 3-15 into the threedimensional relief surfaces in Figure 3-12 using a computer plotter.

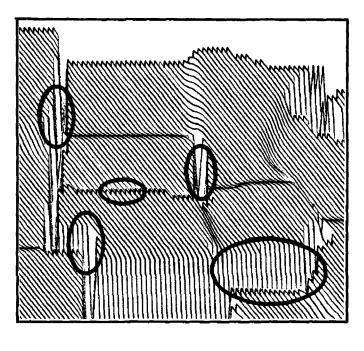
Interpretation

Barrier intensities are more discernible in Figure 3-15 than in Figure 3-12. In Map 4 interstate barriers are differentiated from interstate flows of migrants by



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being more angular at their edges. A smoothing function⁵² in the ASPEX program is used to achieve this effect. Examples of barriers between contiguous states are shown in Figure 3-16.



barriers

Figure 3-16: Symbolization of barriers between contiguous states

In the surface relief flow map (Figure 3-12), direction of net migration is seen to occur from California to Arizona, Texas to Oklahoma, and from New York to Pennsylvania. Neither magnitude of flow between contiguous states nor net

⁵²Computer mapping smoothing techniques eliminate abrupt transitions in the surface representing the z-dimension values of the data. Each z-value is compared to adjacent z-values and is modified to more closely resemble them in value. As a result, the three-dimensional relief surface representing data z-values is smoothed in appearance. See Arthur Robinson, Randall Sale, and Joel Morrison, <u>Elements of Cartography</u> (4th ed.; New York: John Wiley & Sons, 1978), pp. 163-68.; Mark Hanson, <u>ASPEX User's Reference Manual</u> (Cambridge, Massachusetts: Laboratory for Computer Graphics and Spatial Analysis, 1978), pp. 80-81.

flow between noncontiguous states is implied by the surface relief flow map. It is noted that in representing migration, some states are close to the level of their neighbors (Oregon and Washington), but some are at a higher level (Idaho and Washington). This apparent contradiction is unavoidable when representing the data with this method. It is assumed that the disclaimer on the map stating "Magnitude of net migration is not depicted or implied" will serve to avoid erroneous conclusions by map viewers.

One problem with both maps is the loss of detail in smaller states, such as those found in New England. This problem exists with other mapping methods but is magnified in the case of Map 4 by the relatively low resolution inherent in the computer mapping program. A larger-scale inset of problem map areas, where possible, is one solution to this problem. Another problem arises where a state is contiguous to a number of other states, such as is the case with Tennessee. Tennessee is contiguous to eight states and poses a problem in mapping without flow lines. The solution here divides Tennessee into two segments; a western one-third and an eastern two-thirds.

The surface relief flow map depicts several characteristics of migration. Barrier patterns are identified, such as the northern Rocky Mountains, the lower Mississippi River, and the Appalachian Mountains. Regions of net migration between contiguous states are identified along the Atlantic-Gulf coast states, Pacific coast states, and North Central states. Also, certain states such as Utah, Nebraska, and West Virginia appear relatively isolated in terms of contiguous migration.

Chapter 4

EVALUATION

The Social Survey

Objectives

The processes and functions which probably will occur between the eye and the mind of a (map) reader must be predicted and analyzed if the technique is to be properly evaluated. To do so is difficult to say the least.⁵³

An evaluation of the maps produced in this thesis is necessary to discover their effectiveness and utility. A social survey is designed and administered to a small group of map users after which their responses are compiled, analyzed, and displayed. The results are used to understand the successful and unsuccessful characteristics of the four mapping methods described in the previous chapter. The social survey collects facts and opinions from the selected group of respondents concerning Maps 1, 2, 3, and 4. This information is then analyzed to help determine the effectiveness and utility of the maps and to help understand why they do or do not work.

⁵³Arthur Robinson, <u>The Look of Maps: An Examination of Cartographic Design</u> (Madison, Wisconsin: University of Wisconsin Press, 1952), p. 20.

Form and organization of the survey

A booklet of questions, Maps 1, 2, 3, and 4, and a reference map for locating the states of the United States comprise the social survey. A copy of the survey is displayed in Appendix D. Both questionnaire and personal interview techniques are used in the survey. The survey is organized in the following manner. Initially, an explanation of the purpose of the survey, of the rationale for selecting respondents, and of the structure of the survey is given to respondents in the Introduction. Part 1, comprised of structured questions regarding the content of each map, comes next (pages 2, 5, 8, and 11 of the survey). Questions about map content are asked first so the respondents can become familiar with each map by using it. Part 2, comprised of both structured questions (pages 3, 6, 9, and 12) and personal interview questions (pages 4, 7, 10, and 13), seeks the respondents' opinions about each map. Structured questions concerning the form of the maps use the semantic differential technique for recording opinions.⁵⁴ Respondents record their opinions about characteristics of each map along a scale between polar opposite word pairs such as unique-conventional, valuable-worthless, and clear-confusing. The six questions in this part of the survey are identical for all four maps. Part 2 has a second section which consists of open-ended questions asked of the respondents in a personal interview. Respondents are able to voice,

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⁵⁴With the semantic differential technique, responses are recorded along a scale defined at either end by polar opposite word pairs describing a characteristic of the map. The respondent is able to record opinions on the scale in one of seven positions in a continuum between the polar opposite word pairs. See Charles H. Backstrom and Gerald D. Hursh, <u>Survey Research</u> (Northwestern University Press, 1963), p. 77.

in their own words, both favorable and unfavorable impressions of either the form or the content of each map. Part 3 of the survey (page 14) asks respondents to rank the four maps highest to lowest according to two criteria: ease of interpretation and visual appearance. Part 4 (page 15) asks background information about the respondents: area of expertise, frequency of map use, education, and current occupation.

Respondents

Based on two assumptions, a 'purposeful' sample of respondents is chosen to evaluate the maps.⁵⁵ The audience of these maps is assumed to be limited to individuals with specialized knowledge of spatial interaction, such as demographers, historians, planners, and geographers. It is also assumed that the most significant evaluation of these maps can be done by either those persons familiar with graphic and cartographic design or those persons who use maps regularly.

⁵⁵Respondents chosen to evaluate the four maps are Dan Obermeyer, community planner; Harold Bockemuehl, professor, geography; Bette Williamson, cartographic technician, U.S. Forest Service; Major Frederick Moench, assistant professor, military science; Dick Lane, instructor/statistician; H. Duane Hampton, professor, history; John McQuiston, professor, sociology; David James, assistant professor, art; and Karen Rausch, travel agent. All are from the community or the University of Montana, Missoula, Montana.

Survey method

The social survey is designed to be conducted personally, by appointment. Respondents are given a copy of the questionnaire booklet, the four maps, and a reference map for locating states. They begin by answering the structured questions in Parts 1 and 2, which are designed to be self-administered. After these questions are completed, the open-ended interview questions of Part 2 are asked of the respondent by the interviewer. Responses to questions are recorded by the interviewer in the form of hand-written notes. This procedure of questioning is then repeated in sequence for Maps 2, 3, and 4. Next, Parts 3 and 4 are then completed by the respondent following the same procedures used for Part 1 and the first section of Part 2. The interviewer is present throughout the survey to answer any questions which may arise.

Results and Analysis

Part 1, Structured content questions

The purpose of Part 1 is to test whether the maps convey the information to map users that is intended. Toward this end the survey respondents are asked questions about the dot density (Map 1), the heirarchy of movement within regions (Map 2), state connectivity (Map 3), and the direction of net migration (Map 4). Map 1

For Map 1, the classless choropleth dot map, respondents are asked in page 2 of the survey to differentiate migration ratios for several pairs of states (question 1) and for one group of four states (question 2). Pairs of states such as North Dakota-South Dakota and Kentucky-Tennessee are chosen on the basis of variations between them concerning a number of characteristics: contiguity, difference in the migration ratio, difference in the size (area), and the difference in the density of dots used to symbolize the migration ratio. The results to these questions are displayed in Figure 4–1. The percentage of questions answered correctly for Part 1, Map 1, listed by respondent, ranges from 100% correct to 25% correct, with a mean score of 69%. There are two possible explanations as to why the mean score for responses to Map 1 is comparatively low. Respondent #4 scored low by writing in the answer "same" for six of the eight state pairs listed in question 1. These answers are considered incorrect. A second explanation is that the questions in Part 1, Map 1 are harder to answer than the questions asked in Part 1 for the other maps.

Tables 4-1 and 4-2 present the responses to question 1, Part 1, Map 1, in more detail. The state pairs listed in question 1, the variations in characteristics between states in the pairs, and the percentage of respondents choosing the correct state (the state with the higher r value) are listed in Table 4-1. As an example, the pair of states, Washington-Georgia, are not contiguous, they have migration ratios of .23 and .19, respectively; they have state areas of 68,000 square miles and 59,000 square miles, respectively; they have a difference in area of 9,000

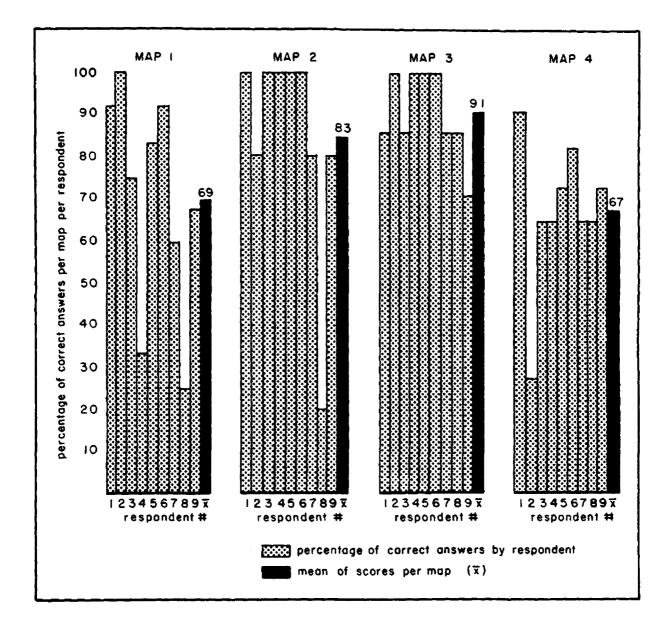


Figure 4-1: Percentage of answers correct, by map and respondent, Part 1 square miles; and their migration ratios are symbolized with 115 dots and 62 dots, respectively. For this state pair, all respondents (100%) correctly chose Washington as having the higher migration ratio. Correlation coefficients, r_{c} , between values in Column 7 (Table 4-1) and values derived from data in Columns

3, 4, 5, and 6 (Table 4-1) are shown in Table 4-2.⁵⁶ The correlation coefficients in Table 4-2 suggest that accuracy in reading a classless choropleth dot map decreases (Column 7, Table 4-1) as the size of the states decreases (Column 4, Table 4-1) and as the number of dots per state decreases (Column 6, Table 4-1). Map reading accuracy may be increased for a classless choropleth dot map by experimenting with the size and number of dots per state and by experimenting with different types of base maps which alter the relative sizes of the states (Figure 5-2).

Map 2

In Part 1, Map 2, the nodal region flow map, respondents are questioned on whether or not they recognize the existence of discrete regions of migration that are portrayed on the map (questions 1, 4, and 5) and whether or not they understand the hierarchy of movement within each region (questions 2 and 3). Figure 4~1 shows the respondents' mean score for Part 1, Map 2, to be the second highest mean score for the four maps (mean = 83).

⁵⁶Coefficients are calculated using the Pearson Product Moment Coefficient of Correlation method; John W. Alexander and Lay James Gibson, <u>Economic Geography</u> (2nd ed.; Englewood Cliffs, New Jersey: Prentice-Hall, Inc., 1979), p. 433.

Table 4-1: State pairs; scores; characteristics, question 1, Part 1, Map 1

1 STATE PAIRS	2 CONTIG- UOUS	•	4 STATE AREAS in 1000's sq. mi.)	5 DIFFERENCE IN AREA (in 1000's sq. mi.)	6 # OF DOTS IN STATES	7 PERCENT CHOOSING CORRECT STATE
WA/GA	no	.23/.19	68/59	09	115/62	100
ND/SD	yes	.25/.23	71/77	06	147/130	78
ID/FL	no	.31/.29	84/59	25	2 98/177	78
CA/CT	no	.15/.20	159/05	154	92/06	78
KY/TN	yes	.16/.17	40/42	02	28/34	67
DE/MD	yes	.26/.21	02/11	09	05/14	56
MA/RI	yes	.16/.18	08/01	07	06/01	56
NH/NM	no	.30/.29	09/122	113	31/367	44

Table 4-2: Correlation coefficients (r_c)

	DIFFERENCE IN STATE	DIFFERENCE IN STATE	SIZE OF SMALLER	FEWER NUMBER OF DOTS IN
	RATIOS	AREAS	STATE	STATE PAIR
PERCENT CORRECT FOR STATE PAIR	.36	.18	.70*	_ 44

* Correlation significant at the .05 level of significance.

Map 3

In Part 1, Map 3, the connectivity network map, respondents are asked questions about the connectivity of states (questions 1, 2, 3, and 5) and about the strength of linkages between states (question 4). Scores for Map 3 range from 100% to 71%, with a mean score of 91%, the highest mean score for Part 1 for all the maps (Figure 4–1). A possible explanation for the high scores of respondents for both Map 2 and Map 3 lies in the ordinal scale of symbolization used. Maps 2 and 3 symbolize data values grouped into only four and three classes, respectively. In contrast, Map 1 represents 24 discrete data values with ratio scale symbolization. Differentiating between three or four different line symbols is much easier than differentiating between the variations in dot densities representing the twenty-four discrete data values. Had Maps 2 and 3 used ratio scale symbolization of the data, the mean scores for those maps in Part 1 would most likely have been similiar, or lower than, the mean score for Map 1.

Map 4

Respondents are asked to determine the direction of net migration between contiguous states in Map 4 by differentiating between the apparent heights of the relief surfaces of states (question 1). Question 2 is used to determine the respondents' understanding of the scale of symbolization. The percentage of correct answers for Map 4 ranges from 92% to 27%, with a mean score of 67% (Figure 4-1). This is the lowest mean score for Part 1 of all four maps. Possible reasons for this low score are discussed in the results of the personal interview responses. It is interesting to note that four of the nine respondents answered

question 2 incorrectly, assuming that the map represented quantities of migrants, despite a disclaimer in the margin stating otherwise. These respondents obviously interpreted differences in the levels of the states to represent differences in quantities of migrants. This mistake could be expected as apparent threedimensional symbolism is normally scaled on the interval/ratio level.

Part 2, structured opinion questions

In the first section of Part 2, respondents are asked the same six structured opinion questions about each of the four maps (pages 3, 6, 9, and 12 of the survey). Opinions are recorded by respondents on a scale in one of seven discrete positions between polar opposite words describing some aspect of the maps. These questions deal with the symbolism used in the maps (questions 1, 2, 3, and 4), the readability of the maps (question 5), and the interpretation of map contents (question 6). Figure 4-2 displays four linear profiles, each representing the mean response for each question for each map. It is noted that opinions in Part 2 of the survey are recorded on an ordinal scale of measurement, in one of seven classes represented by integer values. Differentiation between opinions recorded in the same class (i.e. the same integer value) is not possible. Therefore, when representing the data in Part 2 it is necessary to use the same classes that were used to collect it. Failure to use significant figures in representing the mean value would be to misrepresent data recorded on the ordinal scale as data recorded on the ratio scale of measurement.⁵⁷

⁵⁷Robert H. Stoddard, <u>Field Techniques and Research Methods in Geography</u> (Dubuque, Iowa: Kendall/ Hunt Publishing Company, 1982), p. 48.

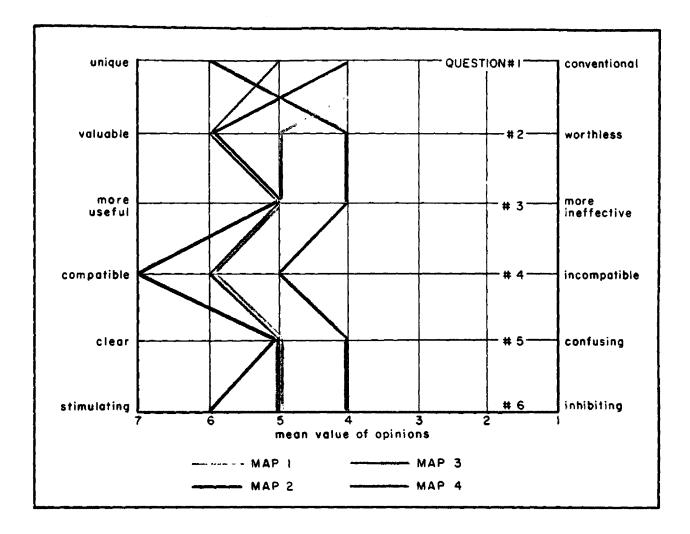


Figure 4-2: Profile of mean of opinions for Part 2 questions, by map

Surprisingly, but maybe not so surprisingly, the dots in Map 1 are perceived to be the most conventional use of symbolism of all four maps (question 1). Some respondents may have confused the appearance of a classless choropleth dot map with the appearance of distribution dot maps. Only the geographer/cartographer in the sample of respondents rated the use of symbolism as unique (7) in Map 2. As expected, Map 4 is rated as the most unique use of symbolism (mean = 6).

In question 2, Maps 2 and 3, both employing ordinal scale symbolization, are ranked highest for purposes of analyzing migration. It is seen in the results of Part 1 that respondents were most successful in answering the question for Maps 2 and 3. Those maps which are more easily read by viewers apparently are more useful to them.

In answering question 3, respondents feel quantitative values could make Maps 1, 2, and 3 more useful (mean = 5). The demographer in the group of respondents definitely feels that including quantitative values would make Maps 1, 2, and 3 more useful. It was seen in the results of question 2, Part 1, Map 4 that almost half of the respondents assumed Map 4 to be quantitative in nature.

The flow lines (arrows) on Map 2 are perceived by respondents as unquestionably the most compatible form of symbolism for representing migration (mean = 7). Only in Map 2 is the direction of movement between places symbolized in the traditional manner using arrows. Ironically the attempt to depict direction of movement without arrows appearing in Map 4 is seen as the least compatible symbolization of migration. Since Map 4 is the most experimental in its symbolization of movement, this reaction by respondents is not a surprise.

In terms of readability (question 5), Maps 1, 2, and 3 rank equal (mean = 5) with Map 4 ranking lower (mean = 4). Respondents find Maps 1, 2, and 3 equally easy to read even though their mean scores in Part 1 are 69%, 83%, and 91%, respectively. This suggests that map readers may understand how to read a given map without being able to perceive small differences in its symbolization (i.e. Map

When evaluating the responses to question 6, Map 2 emerges as the the most stimulating for interpreting migration. Maps 1 and 3 are less stimulating; Map 4 is the least stimulating. As suggested in the results to question 4, respondents may feel most comfortable when reading spatial interaction maps when the movement is symbolized in the traditional manner using arrows. Map 4 forces readers to interpret the pattern of movement from an unfamiliar method of symbolization.

Part 2, personal interview opinion questions

Part 1 and the first section of Part 2 occur at the beginning of the questioning sequence to provide respondents ample opportunity to develop opinions regarding the maps. The personal interview section of Part 2 follows allowing respondents to voice their opinions in a format which would allow the maps to be compared and discussed in the following passages.

Map 1

The strong point of Map 1 voiced by respondents is the use of symbolism. Dot density is an efficient way to depict the comparative migration ratios of states. One goal of this mapping method is to allow viewers to visually construct regions of migration based upon areas of similiar dot density. Two comments, one favorable and the other unfavorable, support this goal of the mapping method. "Regional impression of ratio is possible with this map."⁵⁸ Regions such as the

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⁵⁸Comment by Dick Lane.

states of the Midwest, the Great Plains, the Rocky Mountains are somewhat visually homogeneous because of the relatively similiar dot densities found throughout each. Another comment, "The Midwest visually blends together in dot density,"⁵⁹ also reinforces the characteristic of this method which allows viewers to distinguish regions of relatively homogeneous migration ratio. Distinctions can be made between dot densities within these "regions," something which is not possible with traditional choropleth maps (Figure 3-1).

Manipulating the number of dots per state and the size of dots to increase readability may be limited by a minimum effective dot size. One respondent stated, "The bold dots are striking,"⁶⁰ suggesting that reducing dot size beyond some undefined minimum size may have deleterious effects when comparing dot densities.

Dot patterns, either random, uniform geometric, or uniform nongeometric, identify another factor in the effectiveness of the mapping method. "The haphazard (uniform nongeometric) dot pattern may not be the best dot pattern."⁶¹ More rigorous experimentation with dot patterns is necessary to determine the extent of their effect on readability.

Content is of concern to respondents in viewing Map 1. The desire to distinguish migration ratio, r, as either in-migration, out-migration, or total

⁵⁹Comment by John McQuiston.

⁶⁰Comment by Bette Williamson.

⁶¹Comment by Dick Lane.

migration is expressed repeatedly.

Map 2

The respondents are more likely to have greater familiarity with the form and use of the symbolization for Map 2 than any of the others. Directed flow lines (arrows) are frequently used symbols on spatial interaction maps. Recurring interview comments about Map 1 are "clean, simple, uncluttered," "not noisy," "straightforward," and "reads clean." The map, however, uses many flow lines, more than forty lines in all.

One obstacle to reading Map 2 is its content, an opinion voiced several times in the interviews. Respondents are concerned about the terms "dominant" and "peripheral" and about how the hierarchy of migration within the nodal regions is defined. Two respondents expressed the desirability of including absolute numbers of migrants in the symbolization.

Map 3

As with Map 1, the conceptual framework of Map 3, connectivity, is seen as being esoteric to respondents and is voiced as a major concern among the interview comments. "I'm not sure I know what it (the map) means."⁶² "The content is unclear." "What is the message of the map?" "The map is readable,

however."⁶³ "This map exists for itself; it is Dada."⁶⁴ The concept of connectivity applied to migration may be esoteric, but its form is familiar in the thematic maps of other topics in spatial interaction. The type of map displayed in Figure 2-16 illustrates the connectivity of international cities by an airline.⁶⁵ Other problems with the content of Map 3 were a desire to discern both the direction of migration and absolute numbers of migrants.

The general form is seen as "clean looking" and "uncluttered" despite the map having seventy-five flow lines superimposed on a linear base map. Minor improvements in form, such as more contrast in line weights and heavier state outlines, are suggested.

Map 4

A variety of contradictory interview comments describe Map 4, most of them concerning its form. "Some parts are very easy to read." "Very difficult to interpret." "Roughly easy to follow the pattern of flow." "I like the looks of it." "It makes you kind of blurry-eyed." "Visually disturbing." "Intriguing." More comments were made about this map than about any of the other maps.

The parallel diagonal lines that form the relief surfaces are a major obstacle

⁶³Comment by Dick Lane.

⁶⁴Comment by John McQuiston. Dada refers to a movement in art in the early twentieth century "based on deliberate irrationality, anarchy, cynicism, and negation of the laws of beauty and social organization."; Webster's Third New International Dictionary of the English Language Unabridged, 1967.

⁶⁵Karen Rausch, a travel agent, immediately noticed the similiarity between Map 3 and airline route maps, saying "This looks like an airline map!"

in viewing the map. The lines are variously described as "eye-tiring," "hard to look at up close," "creating an optical illusion effect," and " the map starts to move," when the pattern of migration is interpreted from the map.

One of the comments, comparing the viewing of Map 4 to the viewing of stereo aerial photographs, may best summarize the problem most respondents had in interpreting this map. The viewer usually does not immediately discern variations in surface relief, but must instead train himself to see them. After viewing Map 4 for a period of time, variations in the relief surfaces become discernible and the concept of flow from high to low surfaces becomes apparent.⁶⁶

Part 3, Rank Ordering of the Maps

Part 3 of the questionnaire asks respondents to rank, highest to lowest, all four maps according to the two criteria – ease of interpretation and visual appearance. Histograms in Figures 4–3 and 4–4 display the results of respondents' rankings.

For ease of interpretation, Map 2 is ranked first and second most frequently while Map 4 is ranked third and fourth most frequently. No respondents rank Map 4 either first or second in ease of interpretation. A similiar pattern occurs when the maps are ranked in terms of visual appearance. Map 2 is ranked first and second most frequently while Map 4 is ranked fourth most frequently, suggesting that ease of interpretation is closely associated with visual appearance. Curiously, Map 4 is ranked first in visual appearance by three of the respondents. Apparently

⁶⁶From H. Duane Hampton.

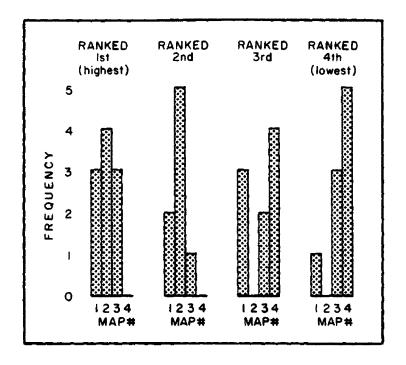


Figure 4-3: Frequency of ranking for 'ease of interpretation'

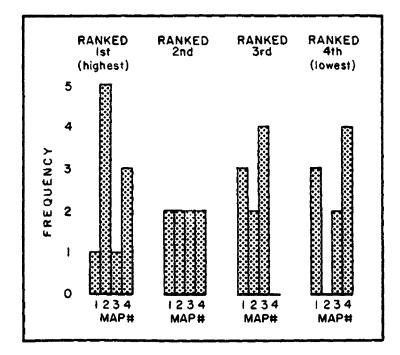


Figure 4-4: Frequency of ranking for 'visual appearance'

it has a dichotomy of appeal to respondents; it is either strongly received or strongly rejected. This dichotomy of appeal is supported by impressions recorded in the interview section of the survey.

Part 4, Background Information

The questions in Part 4 are included in order to obtain background information about the group of survey respondents: area of expertise, frequency of map use, level of education, and current occupation. Area of expertise for the respondents is evenly divided between those with knowledge in graphics or cartographics and those with knowledge in the geographic movement of people. Responses indicate that they are frequent map users with eight of the nine respondents using maps weekly or daily.

Chapter 5

CONCLUSIONS

Considering the number of ways it is used in this thesis, and considering the numerous potential ways it may be used, the classification scheme developed in Chapter 2 provides unlimited means for exploring new methods to map spatial interaction. In the process of classifying the group of maps collected in the survey, it is seen that spatial interaction maps depict movement either implicitly or explicitly. All maps which explicitly depict movement between places are seen to do so with line symbolism (flow lines). Since no other form of symbolism is used for this purpose, the classification scheme developed in this thesis presents the problem of explicitly representing interaction without line symbolism. Map 4, the surface relief flow map, is only one solution to this problem. Many more potential solutions exist when all of the forms of symbolism found in thematic cartography are considered.

The classification scheme proves to be useful in a second way by showing that graphic elements such as size, value, and spacing (pattern) may be altered for a form of symbolism, thus providing new methods for mapping. Area symbols in Figure 2-7 are altered in size (height) to give ratio scale symbolization of the data. The symbolism in Figure 3-2 is altered by varying the spacing (pattern) of lines within areas. Map 1, the classless choropleth dot map, alters the spacing of dots within areas. The method used to produce Map 1 is an attractive alternative to

anyone wishing to make a classless choropleth map, but is without access to sophisticated computer mapping equipment.⁶⁷

The process of classification familiarizes the mapmaker with a variety of map types. These maps types may be used to represent familiar topics, such as interstate migration, with new and different perspectives. Figure 2–16 serves as the model for the connectivity network map of interstate migration in this thesis. After a method for manipulating migration data is developed, the maps in Figures 3–9 and 3–10 are produced.

Finally, vacant classes in the scheme invite the design of mapping methods that will produce maps to fill them. Map 2, the nodal region flow map, fills such a void in the classification scheme. Only one of the thirteen vacant classes in the scheme (Figure 2–14) is filled by mapping methods explored in this thesis, leaving a number of mapping opportunities open to future research in thematic cartography.

Research to produce new mapping methods may focus on one specific category in the classification tree, developing it in more detail. The classification tree in Figure 5-1 is expanded in detail for those maps which use area symbolism scaled at the interval/ratio level. After developing the tree in more detail, map collection may be appropriate in order for the mapmaker to become familiar with what examples exist in the literature. Then, systematically, the mapmaker may experiment with each graphic element listed in the tree to develop different

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⁶⁷See Chapter 3, Classiess choropleth maps.

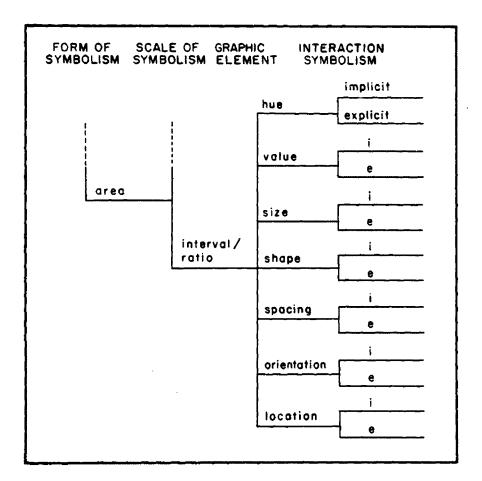


Figure 5-1: Expanded map classification tree

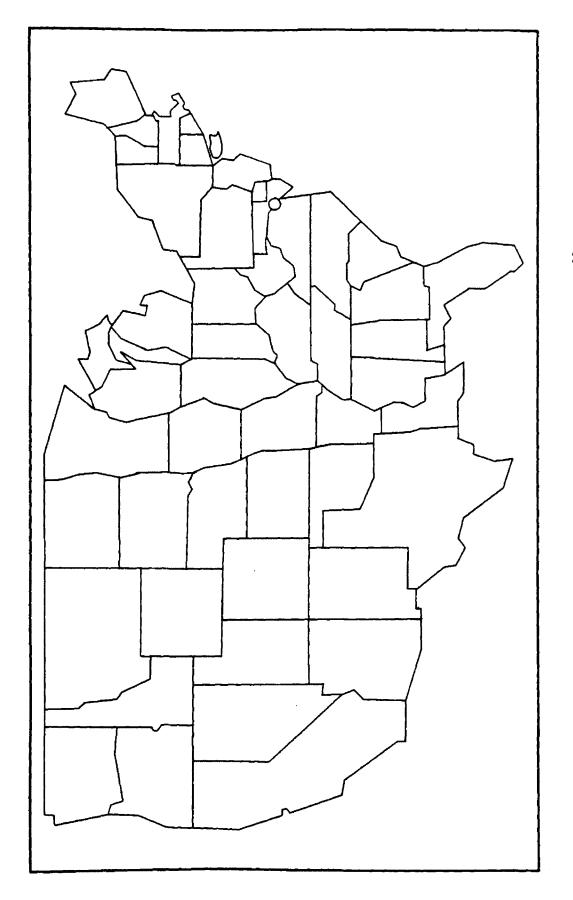
mapping techniques. Another area for future research is to expand the classification tree to include multiple forms of symbolism.

In many ways, Map 1, the classless choropleth dot map, is a successful map.

It is likely to be the most utilitarian of the four maps. As a choropleth mapping method, its uses include the representation of a variety of geographic topics in addition to spatial interaction. A classless choropleth dot map is easy to produce, requiring little more equipment than drafting pens and a hand-held calculator.

The method is very successful in representing small differences in the values of areal data. Users of Map 1 are able to discern extremely small variations between the pattern of dots in the states. For the pair of states, Kentucky-Tennessee, in question 1, Part 1, Map 1, six of the respondents correctly chose Tennessee as having the higher migration ratio of the two states. The other three respondents did not choose Kentucky, but rather chose to indicate the two states as having equal migration ratios. The difference in migration ratio between these two states is only one percent (1%). For comparisons made between states small in size, however, map reading accuracy is seen to decrease. A cartogram which increases the relative sizes of small states, such as Rhode Island and Connecticut, may make the dot densities of small areas more readable. Experimentation with cartograms such as the one displayed in Figure 5-2 may improve the readability of both classless and classed choropleth maps.

Well received by respondents in their form, Maps 2 and 3, the nodal region flow map and the connectivity network map, respectively, are successful in several ways. Respondents like the way these maps look. Line symbolism is unambiguous in representing movement. In Maps 2 and 3, movement is made even less ambiguous by the careful organization and layout of the line symbolism. Whenever possible, lines are not allowed to cross each other. When lines must





68 Girl Scout Pocket Planner 1986.

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cross, the shortest line is broken to help the users perceive long distance movements. Straight lines are used to connect contiguous states; curved lines are used to connect noncontiguous states. It is for these reasons that most respondents see Maps 2 and 3 as "clean and uncluttered." Further experimentation with this type of line symbolism, such as using terminal points at the vertices in the connectivity network map, may help to improve readability.

The nodal region flow map may be useful in representing a number of different types of regions defined by the flow of such things as people, products, money, or communications. This type of map is not likely to be displayed alone, however, outside of a supporting text as most map readers other than professional geographers are probably not familiar with the concept of nodal regions. For similiar reasons, it is unlikely that Map 3 would be displayed outside of a supporting text. The abstract concept of connectivity, applied to the topic of migration, is foreign to most users. Respondents are able to read Map 3 easily, but do not understand the meaning of what they read. As a result, this map may have little use except as a tool for specialized purposed in spatial analysis.

Map 4, the surface relief flow map, is most successful in eliciting reactions from users. It is a fascinating map for some, objectionable to others. None of the users are ambivalent towards it. The form of the apparent third dimension, once perceived by users, is the main factor in the dichotomy of attitudes towards Map 4. The apparent third dimension is created by a series of diagonal, parallel lines drawn by a computer plotter. Most map users regard these lines as an optical nuisance. This attitude is reflected in the interview responses presented in Chapter 4. Other methods may be used to produce an apparent third dimension, such as relief shading or computer programs that plot two sets of parallel lines at various angles to one another forming a network of parallelograms and rectangles which convey the impression of a three-dimensional image. Experimentation with these methods for mapping an apparent third dimension may make the surface relief flow map easier to look at, easier to read, and more acceptable to users.

Users are reasonably successful in reading the direction of flow between large states on Map 4. Problems arise, however, in representing flow between small states. Much of the detail of state shape and state relief in these areas is lost due to the low resolution of the computer mapping program. A solution to this problem is to map regions with small states separately, at a larger scale. The method used to produce Map 4 is complicated, time-consuming, and requires access to specialized computer hardware and software. For these reasons, uses of this mapping method are likely to be limited.

Appendix A

SOURCES FOR MAPS

Library of Congress Subject Headings

Air travel Airways Animal migration Animal orientation Bats - Migration Birds - Migration Cities and Towns - Growth City traffic College student mobility Commerce Commercial products Communication Communications and traffic Communications, Military Emigration and immigration Fishes - Dispersal Fishes - Migration Geography, Commercial Geography, Economic Geopolitics Graduate student mobility Insects - Migration Labor mobility Land settlement

Man - Migrations Migrant labor Migration, Internal Migrations of nations Migratory locust Military geography Movement of animals Network analysis Population density Population geography Postal service Railroads Residential mobility Roads Rural-Urban migration Shipment of goods Shipping Student mobility Telecommunications Tourism Trade routes Traffic engineering Transportation

Appendix B

MIGRATION DATA

Interstate Migration, United States, 1975-1980

Migration data for the interstate movement of people for the five-year period, 1975-1980, are listed in the following four pages. States of origin are listed in the columns along the top of the matrix. States of destination are listed in the rows along the left-hand edge of the matrix. The number of migrants from the state of origin to the state of destination is listed in the matrix. Table B-1: Matrix of interstate migration, U.S., 1975-80

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Table B-1, continued

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Table B-1, continued

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Appendix C

BASIC+2 COMPUTER PROGRAM FOR DATA ANALYSIS

kvalues.b20

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00100	rem	kvalues.b20; Craig Bacino; U of Montana
00200	rem	November, 1985
00300	rem	
00400	rem	THIS PROGRAM CALCULATES CONNECTIVITY VALUES,
00500	rem	k, FOR ALL PAIRS OF STATES.
00600	rem	TOTAL NUMBER OF MIGRANTS BETWEEN IS INDEXED
00700	rem	TO K VALUES FOR ALL PAIRS OF STATES.
00800	rem	
00900		dim tm(51,51)
01000		dim e(51)
01100	rem	tm = total migration between two states
01200	rem	e = the total out-migration from a state
01300	rem	k = the connectivity value between two states
01400	rem	<pre>tmig80.in: input file listing total migration</pre>
01500	rem	between pairs of states
01600	rem	ststats.in: input file with state names and
01700	rem	migration data
01800	rem	percent.in: input file holding k values and
01900	rem	indexed number of migrants
02000	rem	
02100		open "tmig80.in" for input as file #1
02200		open "ststats.in" for input as file #2
02300		for $i = 1$ to 51
02400		input #2,a \$, b,c,d,e
02500		let $e(i) = e$
02600		for j = 1 to 51
02700		input #1,tm
02800		let tm(i,j) = tm
02900		next j
03000		next i

03100	close #2
03200	close #1
03300 rem	
03400	open "percent.in" for output as file #3
03500	for $i = 1$ to 51
03600	for j = 1 to 51
03700	let k = tm(i,j) / (e(i) + e(j))
03800	print #3, using ".#############;k;
03900	print #3, ",";
04000	print #3,tm(i,j)
04100	next j
04200	next i
04300	close #3
04400 rem	<i>'</i>
04500	end

Appendix D

SOCIAL SURVEY

The social survey used in Chapter 4 is reproduced on the following pages of Appendix D.

INTRODUCTION

No.____

The purpose of this survey is to evaluate the effectiveness of maps depicting migration. The maps are part of an MA thesis (Department of Geography, University of Montana) that devises methods for depicting the interstate migration of people in the United States. Respondents have been chosen on the basis of their knowledge and expertise in either graphics/cartographics or the geographic movement of people. Survey results will be incorporated into the thesis. Respondents may be quoted within the thesis in a chapter on map evaluation.

Four maps are to be evaluated in this survey. Questions concerning the maps are divided into four parts:

- * Part 1 asks questions about the content of each map. Map title and legend should provide sufficient information for reading each map and answering the questions. Respondents should not be overly concerned about answering all questions correctly. Some questions are purposely made difficult to answer. The purpose of the survey is to evaluate the maps, not the respondent.
- * Part 2 asks questions about the form of each map after the respondent has had the opportunity to use the map in Part 1.
- * Part 3 asks the respondent to rank the four maps, highest to lowest, in both 'EASE OF INTERPRETATION' and 'VISUAL APPEARANCE'.
- * Part 4 collects background information about the respondent.

** PLEASE TURN THE PAGE **

MAP 1, Classless Choropleth Dot Map.

PART 1

FLORIDA – TEXAS

- NORTH DAKOTA SOUTH DAKOTA
 - KENTUCKY TENNESSEE
 - DELAWARE MARYLAND
- MASSACHUSETTS RHODE ISLAND
 - WASHINGTON GEORGIA
 - IDAHO FLORIDA
 - CALIFORNIA CONNECTICUT
- NEW HAMPSHIRE NEW MEXICO
- 2) Rank the following four states from highest to lowest migration ratio:

WISCONSIN		highest
CALIFORNIA		
NEW JERSEY		
LOUISIANA		lowest
** PLEASE	TURN THE PAGE	**

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MAP 1, continued

PART 2

1) Use of symbolism in this map is:

unique ______ conventional

2) Considering that quantitative measurements of migration cannot be derived from this map, for purposes of analysis the map is:

valuable_____worthless

3) Including quantitative values in the presentation would make the map more:

useful_____ineffective

4) Symbolism on this map and the topic of migration are:

compatible_____incompatible

****CONTINUED ON FOLLOWING PAGE****

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- 6) For interpreting the pattern of migration, this map is: stimulating _______ inhibiting

** STOP **

GENERAL IMPRESSIONS OF MAP 1

PART 2, continued

Having used the map, what are your FAVORABLE impressions of this map?

What are your UNFAVORABLE impressions of this map?

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5

MAP 2, Nodal Region Flow Map

PART 1

1) What is the dominant state of the largest (in area) region of migration?

2) Which of the following states is a first level peripheral state?

IOWA ILLINOIS VIRGINIA

MINNESOTA

3) Migrants from which 2nd level peripheral state flow into the above 1st level peripheral state?

NEBRASKA
WISCONSIN
MARYLAND
NORTH DAKOTA

4) Each region of migration is contiguous.

TRUE ____ FALSE

****CONTINUED OF THE FOLLOWING PAGE****

5) If the answer for #4 is FALSE, then name the dominant state of a noncontiguous region of migration.

****** PLEASE TURN THE PAGE ******

.

MAP 2, continued

6

PART 2

1) Use of symbolism in this map is:

unique______conventional

2) Considering that quantitative measurements of migration cannot be derived from this map, for purposes of analysis the map is:

valuable_____worthless

3) Including quantitative values in this map would make the map more:

useful_____ineffective

4) Symbolism on this map and the topic of migration are:

compatible_____incompatible

****CONTINUED ON THE FOLLOWING PAGE****

5) Using only map title and legend, reading the map is:

6) For interpreting the pattern of migration, this map is:

stimulating______inhibiting

.

** STOP **

7

GENERAL IMPRESSIONS OF MAP 2

PART 2, continued

No.____

Having used the map, what are your FAVORABLE impressions of this map?

What are your UNFAVORABLE impressions of this map?

MAP 3, Connectiviey Network Map

PART 1

1) Which of the following states is most isolated (unconnected) in the migration network?

ALASKA
DELAWARE
MICHIGAN
MAINE

2) Individual states with the most migration linkages tend to be in which half of the U.S.?

NORTHERN ____ SOUTHERN

3) There are more migration linkages between contiguous states for which section of the U.S.? (sections are delineated in yellow)

NORTHEAST SOUTHEAST

4) Very strong migration linkages occur more frequently between contiguous states than between non-contiguous states.

TRUE _____ FALSE

CONTINUED ON THE FOLLOWING PAGE

5) Rank the three states with the greatest number of migration linkages.

greatest number of linkages
______ second greatest number of linkages
______ third greatest number of linkages

****** PLEASE TURN THE PAGE ******

MAP 3, continued

PART 2

1) Use of symbolism in this map is:

unique______conventional

2) Considering that quantitative measurements of migration cannot be derived from this map, for purposes of analysis the map is:

valuable_____worthless

3) Including quantitative values in the presentation would make the map more:

useful_____ineffective

4) Symbolism on this map and the topic of migration are:

compatible _____incompatible

****CONTINUED ON THE FOLLOWING PAGE****

- 5) Using only map title and legend, reading this map is:
- 6) For interpreting the pattern of migration, this map is:

stimulating______inhibiting

** STOP **

GENERAL IMPRESSIONS OF MAP 3

PART 2, continued

Having used the map, what are your FAVORABLE impressions of this map?

What are your UNFAVORABLE impressions of this map?

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MAP 4, Surface Relief Flow Map

PART 1

IDAHO WASHINGTON (flow from ID to WA)

IDAHO MONTANA (barrier)

NEW MEXICO	TEXAS
OHIO	PENNSYLVANIA
GEORGIA	FLORIDA
SOUTH DAKOTA	WYOMING
KENTUCKY	ILLINOIS
NEW HAMPSHIRE	VERMONT
NEBRASKA	SOUTH DAKOTA
NEW YORK	PENNSYLVANIA
NEBRASKA	IOWA
VIRGINIA	NORTH CAROLINA

****CONTINUED ON THE FOLLOWING PAGE****

2) Which is greater?

net migration from IDAHO to WASHINGTON

____ net migration from IDAHO to OREGON

cannot tell from this map

****** PLEASE TURN THE PAGE ******

MAP 4, continued

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PART 2

1) Use of symbolism in this map is:

unique______conventional

2) Considering that quantitative measurements of migration cannot be derived from this map, for purposes of analysis the map is:

valuable_____worthless

3) Including quantitative values in this map would make the map more:

useful_____ineffective

4) Symbolism on this map and the topic of migration are:

compatible_____incompatible

****CONTINUED ON THE FOLLOWING PAGE****

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5) Using only map title and legend, reading this map is:

clear_____confusing

** STOP **

GENERAL IMPRESSIONS OF MAP 4

PART 2, continued

Having used the map, what are your FAVORABLE impressions of this map?

What are your UNFAVORABLE impressions of this map?

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RANK ORDERING OF MAPS

PART 3

Rank the maps, by identifying number (Map 2, etc.) according to:

EASE OF INTERPRETATION VISUAL APPEARANCE
highest
highe

****** PLEASE TURN THE PAGE ******

BACKGROUND INFORMATION

PART 4

1) For which one of the following is your knowledge/ expertise more extensive?

____ graphics/cartographics

____ geographic movement of people

2) Do you use maps?

____ daily ____ yearly

____ weekly ____ never

____ monthly

3) Level of education:

____ HS ____ BA ____ MA ____PHD

4) Current occupation:

** THE END **

Thank you for your participation in this survey.

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END Job THESIS Reg #2288 for GEOG.BACINO-C Date 5-Jun-86 21:42:16 Monitor: UofM DECSYSTEM-2065 (DECA), TOPS-20 Moni **END** * * * LPTSPL Run Log * * * LPTSPL version 104(2676) UofM DECSYSTEM-2065 (DECA), TOPS-20 Moni 19:29:15 LPDAT 19:29:15 LPDAT Job THESIS sequence #738 on Printer 2 at 5-Jun-86 19:29:15 Starting File PS2:<SCRATCH>THESIS.X27.3 19:29:16 LPMSG Finished File PS2: <SCRATCH>THESIS, X27.3 21:42:16 LPMSG Summary: 436 Pages of Output 21:42:16 LPEND 146 Disk Pages Read 21:42:16 LPEND 77.980 Seconds CPU Time Used 21:42:16 LPEND \$ 30.52 [Approximate] Printer Charges 21:42:16 LPEND 2.26 [Approximate] Printer Balance 21:42:16 LPEND \$

Date 5-Jun~86 21:42:16 Monitor: UofM DECSYSTEM-2065 (DECA), TOPS-20 Moni **END**