



Smart, I. E., Cuthill, I. C., & Scott-Samuel, N. E. (2020). In the corner of the eye: camouflaging motion in the peripheral visual field. *Proceedings of the Royal Society B: Biological Sciences*, 287(1918), [20192537]. https://doi.org/10.1098/rspb.2019.2537

Peer reviewed version

Link to published version (if available): 10.1098/rspb.2019.2537

Link to publication record in Explore Bristol Research PDF-document

This is the author accepted manuscript (AAM). The final published version (version of record) is available online via The Royal Society at https://royalsocietypublishing.org/doi/10.1098/rspb.2019.2537. Please refer to any applicable terms of use of the publisher.

# University of Bristol - Explore Bristol Research General rights

This document is made available in accordance with publisher policies. Please cite only the published version using the reference above. Full terms of use are available: http://www.bristol.ac.uk/pure/user-guides/explore-bristol-research/ebr-terms/

1					
2					
3					
4	In the corner of the eye: camouflaging motion in the peripheral visual field				
5					
6					
7	Ioan E. Smart1*, Innes C. Cuthill1, Nicholas E. Scott-Samuel2				
8					
9					
10					
11	1 School of Biological Sciences, University of Bristol, Bristol, BS8 1TQ, UK				
12	2 School of Psychological Science, University of Bristol, Bristol, BS8 1TU, UK				
13					
14					
15	* Corresponding author				
16	Email: loan.E.Smart@Gmail.com				
17					
18	Accepted for publication in Proceedings of the Royal Society B				
19	Acceptance date: 10/12/2019				

### 20 Abstract

21 Most animals need to move, and motion will generally break camouflage. In many instances, 22 most of the visual field of a predator does not fall within a high-resolution area of the retina 23 and so, when an undetected prey moves, that motion will often be in peripheral vision. We 24 investigate how this can be exploited by prey, through different patterns of movement, to 25 reduce the accuracy with which the predator can locate a cryptic prey item when it 26 subsequently orients towards a target. The same logic applies for a prey species trying to 27 localise a predatory threat. Using human participants as surrogate predators, tasked with 28 localising a target on peripherally viewed computer screens, we quantify the effects of 29 movement (duration and speed) and target pattern. We show that, while motion is certainly detrimental to camouflage, should movement be necessary, some behaviours and surface 30 31 patterns reduce that cost. Our data indicate that the phenotype that minimises localisation 32 accuracy is unpatterned, having the mean luminance of the background, does not utilise a 33 startle display prior to movement, and has short (below saccadic latency), fast movements. 34 [182 words]

35

36 **Keywords**: Motion camouflage; defensive coloration; visual search; peripheral vision;

37 position perception

### 38 **1. Introduction**

39 If motion breaks camouflage [1, 2], exploring the determinants of detection of a single 40 moving target in central vision can be considered trivial. However, the peripheral visual field 41 is generally a region of diminished resolution [3], so detection of motion need not guarantee 42 successful targeting of a prey that subsequently stops and resumes crypsis. Localisation of a 43 camouflaged target in the periphery is arguably a more ecologically valid characterisation of 44 the early stages of predation than testing detection ability within central vision: there is a low 45 probability that a predator will be looking directly at a concealed prey item at the moment 46 that it starts to move and, by the time attention is focused on the prey, it may have stopped 47 moving and returned to a static camouflaged state. The same holds true for a prey trying to 48 locate a stalking predator.

49 Previous research on camouflage has focussed predominantly upon the effectiveness of 50 strategies in the absence of motion [4-7], although see [8]. Camouflage operates by 51 exploiting a predator's perceptual system, making detection difficult (e.g. by reducing the 52 signal at the stage of lower-level visual processing), and/or manipulating a predator's 53 cognitive mechanisms so that identification is difficult (acting at a higher-level of information 54 processing) [6, 7, 9]. Movement, a salient cue, allows an observer to segregate an object 55 from the background through relative motion information [10, 11]. Movement appears to be 56 incompatible with camouflage, resulting in the general consensus that motion breaks 57 camouflage [1, 2, 8]. However, an organism must often move, whether to get to a point of 58 refuge, a feeding site, or a mating prospect.

Here, using human observers, we investigate a common situation when predators are foraging but have yet to detect a prey item, or a prey item is vigilant in the face of predation risk: the target is most likely to be detected, via its motion, in the predator's peripheral visual field, with attention subsequently brought to bear on it [12]. Localising and responding to a stimulus in the periphery is complicated by the need to take into account cortical transmission and processing delays, as well as those associated with the preparation and 65 execution of motor actions [13]. Studies on humans suggest that the perceived position of a moving target is predicted via motion extrapolation, and that localisation is affected by the 66 67 time it takes for the observer to move their eyes toward the target (i.e. the saccadic latency) 68 [13]. Many species use saccades alongside fixations to perceive their environment; typically, 69 these are eye-saccades but can also be head-saccades, in the case of birds, or body-70 saccades, in the case of insects [14]. Furthermore, many species have a region of the visual 71 field that has a high concentration of cone photoreceptors (e.g. area centralis) [see 14, 15; 72 table 3 pg. 187], giving good visual acuity; as eccentricity from this region increases 73 photoreceptor density, and thus acuity, decreases. Amongst other things, the fixate-saccade 74 strategy allows an organism to divert the higher-resolution region of its visual field toward an 75 object [14]. What prey movement strategies might minimise the probability of localisation, 76 and does surface patterning affect this? Here, we focus on two key parameters of transient 77 movement (duration and speed) and their interaction with surface pattern. In addition, we 78 included a flash manipulation, where a highly conspicuous display occurs before target 79 movement. Some, otherwise cryptic, insects reveal conspicuous underwings when they fly. 80 These are usually considered to be displays that startle a predator or interfere with 81 identification [16-19] when the predator has already detected the prey and is initiating an 82 attack. Here, we explore a different possible advantage that occurs when prey movement 83 occurs in peripheral vision: gaze may be 'anchored' upon the initial location by a highly 84 salient but transient display, and subsequent movement masked due to a flash-lag effect [20] or sensory overload [21]. Instead of exploring the effectiveness of motion camouflage 85 86 strategies with regards to impeding capture, as in motion dazzle experiments [22-28], we 87 aim to explore the phenotype's effects on localisation.

### 88 **2. Methods**

#### 89 (a) Setup

90 The control program was written in Matlab (The Mathworks Inc. Natick, MA) with the
91 Psychophysics Toolbox extensions [29-31]. The experiment used two gamma-corrected

92 21.5" iiyama ProLite B2280HS monitors (Iiyama; Hoofddorp Netherlands), with a refresh rate
93 of 60 Hz, a resolution of 1200 x 1080 pixels, and a mean luminance of 64 cd/m<sub>2</sub>, controlled
94 by an iMac (Apple; California, US). The screens were positioned so that the centre of each
95 one was 50 cm from the subject and at an angle of 65° from a fixation cross on a third, not
96 gamma corrected, central screen. At 50 cm each pixel subtended 1.7 arcmin.

97 During each trial, the participant was shown a square target (48 x 48 pixels), which 98 appeared, moved, and then disappeared. Targets could appear on either the left or right 99 screen (the central screen only displayed the fixation cross). The target moved in a 100 sequence that was dictated by a combination of two movement factors (duration and speed), 101 a pattern factor (see figure 1), and a flash factor (see below for details). Within each trial the 102 target would move on a background generated by a 1/f function [32], representing a generic 103 textured background to which visual systems are hypothesised to be adapted [33]. Spectral 104 analysis of natural scenes shows that amplitude is inversely related to spatial frequency, f: 105 hence the 1/f function [33]. The background was generated afresh every trial. After a random 106 latency (a uniform distribution from 1-3 s, in 0.5 s increments), the target appeared in the 107 centre of one of the two screens at random (probability 0.5), and then moved in a random 108 direction (discrete uniform distribution in the range 1-360°) in a manner determined by the 109 factorial combination of factors described below. The target then disappeared, the non-target 110 screen turned plain grey and the cursor appeared in the centre of the target screen, which 111 retained its 1/f background. In this way, it was unambiguous to the participant on which 112 screen the target had moved; the task was to localise where it had stopped.

Duration of movement (*duration*) had three levels that were designed to bracket saccadic latency for our human observers [34]: 100, 200 & 400 ms. Speed had three levels that were designed to provide a range of velocities (relatively slower and relatively faster) around data on movement speeds of *Zootoca vivipara* [see 35]: 10, 20 and 35 deg/s. A speed of 35, rather than 40 deg/s, was chosen so that targets always remained on the screen. Patterning had three levels (figure 1): black (*Black;* luminance = 0 cd/m<sub>2</sub>), grey (*meanLum*; luminance = 64 cd/m<sub>2</sub>) and background matching (*BG*; 1/f function, luminance = 66 cd/m<sub>2</sub>). The
background matching function used the same algorithm as that which created the
background. Finally, the target could flash briefly prior to movement (maximum luminance =
113cd/m<sub>2</sub>). This flash factor had three levels: display for 80 ms, 50 ms or not presented at
all. The flash was designed to simulate a startle display [16]. It was added prior to movement
to explore its putative effect on masking the target's end location.

### 125 (b) Task

126 After the target had finished moving and disappeared, participants clicked a mouse-127 controlled on-screen cursor (an 8-pixel radius red circle) on the target's estimated final 128 location. The locations of the centre of the target and the cursor were recorded every frame. 129 On each trial, localisation error was computed as the pixel distance between the centre of 130 the target at its final location and the centre of the cursor at the location where it was clicked. 131 The response time for the participant to click the cursor, from the moment at which the target 132 started moving, was also recorded for each trial. Each participant completed six practice 133 trials followed by 162 test trials, which were broken into three blocks of 54. Therefore, 134 participants received all conditions (3 x 3 x 3) on both screens. Participants were free to 135 take a break between blocks but, in practice, seldom paused for more than a few seconds. 136 The combination of movement and pattern for each trial was independently randomised for 137 every participant. Each trial was completed with the room lights off and with headphones on 138 (to minimise distractions). There were 18 unpaid participants (10 female, ages 18-28), with 139 normal/corrected-to-normal vision, who were naïve to the aims of the experiment. Ethical 140 approval was obtained through the Faculty of Science Research Ethics Committee of the 141 University of Bristol. All participants were briefed and gave their informed written consent, in 142 accordance with the Declaration of Helsinki.

### 143 (c) Statistical analyses

144 Statistical analyses were performed using R (R Foundation for Statistical Computing,

145 www.R-project.org). Both pixel error (*error*) and response time (*RT*) were distributed log-

normally, and so were log10-transformed prior to fitting linear mixed models [function Imer in
the Ime4 package: 36]. Participant was fitted as a random effect, with fixed effects *speed*, *duration, pattern, screen* and *flash*. Initially all fixed main effects and their interactions were
fitted, followed by backwards stepwise elimination of non-significant terms (based on
likelihood ratio tests), starting with the highest order interactions (see electronic
Supplementary Material). Within-factor effects were explored using Tukey-type p-values [R
package multcomp: 37].

#### 153 **3 Results**

Four extremely short response times (under 0.3 s) were outliers (> 5 standard deviations 154 155 from the mean on the log-transformed scale, when the next lowest was 1.5 standard 156 deviations) and from one participant; these were considered to be premature, accidental, 157 mouse clicks. Five data points were also considered to be response errors because the 158 mouse click was off the target screen (possible, as the mouse could be moved to the central 159 and non-target screens). These nine values comprised only 0.3% of the data and were 160 removed. Localisation error is the primary response variable, but a detailed analysis of 161 response times can be found in the Supplementary Material.

162 For localisation error, the final model showed significant main effects of the *flash* factor ( $\chi_2$  = 163 7.44, df = 2, p = 0.0242), and screen side ( $\chi_2$  = 5.84, df = 1, p = 0.0157), on the participant's 164 localisation accuracy, with no interactions between these and other factors (Fig. 2 and 165 Supplementary Material). Tukey-type pair-wise tests indicated that no flash had a 166 significantly larger error than a flash of 50 ms (z = 2.388, p = 0.0446) and a similar, but non-167 significant, difference from an 80 ms flash (z = 2.325, p = 0.0523); 50 ms and 80 ms flashes 168 were not significantly different (z = 0.063, p = 0.9978). The effects of the *flash* factor can be 169 seen in figure 2. The main effects of screen showed a slightly (2.7%) lower localisation error 170 on the right screen, which suggests a bias that could be attributed to eye preference [38].

171 Additionally, the model showed that there were significant interactions between the duration 172 of movement and the speed of movement ( $\chi_2 = 11.00$ , df = 4, p = 0.0266), and the duration 173 of movement and the pattern on the target ( $\chi_2 = 11.24$ , df = 4, p = 0.0240). To understand 174 these interactions, the data were split by the factor *duration* and the effects of speed and 175 pattern assessed for each level. At the shortest duration, 100 ms, there was no significant effect of pattern (Fig. 2;  $\chi_2$  = 1.30, df = 2, p = 0.5219), but at 200 ms there was ( $\chi_2$  =10.75, df 176 177 = 2, p = 0.0046), with mean luminance having the greatest error, significantly greater than 178 black (z = 3.28, p = 0.0030), but not background matching (z = 1.75, p = 0.1872). Black and 179 background matching did not differ (z = 1.52, p = 0.2802). At 400 ms there was also a 180 significant effect of pattern ( $\chi_2$  = 19.39, df = 2, p < 0.0001), mean luminance again having 181 the greatest error, significantly greater than black (z = 4.41, p < 0.0001), but not background 182 matching (z = 2.047, p = 0.1013). Background matching also had a greater error than black 183 (z = 2.371, p = 0.0467). Regarding the interaction between duration and speed, at 100 ms 184 there was a significant effect of speed ( $\chi_2$  = 22.39, df = 2, p < 0.0001), with a greater error 185 for 35 deg/s than for 10 or 20 deg/s (z = 4.60, p < 0.0001 and z = 3.34, p = 0.0024186 respectively); 10 and 20 deg/s did not differ (z = 1.26, p = 0.4155). At 200 ms there was also 187 a significant effect of speed ( $\chi_2$  = 34.69, df = 2, p < 0.0001), error increased progressively with speed (Fig.2; 10 vs 20 deg/s: z = 2.47, p = 0.0364; 20 vs 35 deg/s: z = 3.44, p = 0.0017; 188 189 10 vs 35 deg/s: z = 5.91, p < 0.0001). At 400 ms there was also a significant effect of speed 190  $(\chi_2 = 16.93, df = 2, p = 0.0002)$ , with a greater error for 20 and 35 deg/s than for 10 deg/s (z 191 = 3.83, p < 0.0001 and z = 3.25, p = 0.0033 respectively); 20 and 35 deg/s did not differ (z = 192 0.57, p = 0.8355).

Modelling for response time indicated a significant interaction between pattern and flash when the stimulus moved for 100 ms, with pattern only having a significant effect in the no flash condition (Supplementary Material). Specifically, mean luminance had longer response times than background matching or black patterning, which did not differ. At 200 ms there was a significant effect of flash, with the no flash condition having a longer response time than the flash conditions. At 400 ms there was a significant effect of speed, where anincrease in speed increased the response time.

### 200 4. Discussion

201 Unless already detected and fixated, a prey item seeking to avoid a predator, or a predator 202 seeking to approach prey undetected, is likely to be moving within the peripheral visual field. 203 Our data indicate that for such a moving target to minimise its localisation, it should move 204 briefly and guickly, and it should be unpatterned, with similar luminance to the background. A 205 first-order stimulus is defined by intensity differences between target and background, while 206 a second-order stimulus is defined by a difference in some other property, (e.g. contrast or 207 pattern). Matching the mean luminance of the target and background pushes the stimulus 208 towards being second-order, and is well known that such stimuli are far weaker than their 209 first-order counterparts [e.g. 39, 40]. A conspicuous flash, such as a startle display, prior to 210 movement does not anchor the predator's saccade to the initial location. In fact, it is 211 detrimental: localisation errors are slightly lower and, for short motion durations, response 212 times considerably shorter, if motion is preceded by a flash. In all treatments, the estimated 213 direction of the target's motion was usually judged fairly accurately, but participants overshot 214 its stopping place (Supplementary Material), for the most difficult targets by more than three 215 body lengths (Figure 2; a 150+ pixel error when the width of the target is 48 pixels). This sort 216 of biased error is frequently observed in motion estimation tasks and is known as 217 representational momentum [13, 41]. In our experiment, greater speed led to greater 218 overshoot, particularly for short duration movements (Fig. 2).

Brief movement was the best strategy to increase localisation error, with the greatest errors happening when the duration was shorter than the saccadic latency (100-200 ms) [15, 34, 42-45]. Little information is gathered whilst the eyes are saccading [46], and thus stopping

before a viewer has had time to complete a saccade and fixate is advantageous.

223 Considering that the fixate-saccade strategy is ubiquitous, this suggests that the prevalence 224 of the intermittent motion observed in many animals [35, 47-54], which is often attributed to

225 the benefits of image stabilisation for the prey species itself [35, 52, 53, 55], could instead (or 226 additionally) serve to reduce a predator's ability to localise a prey [35, 52]. Avery et al. [35] 227 has shown that in the lizard Zootoca vivipara, normal movement operates in bursts that 228 broadly correspond to human saccadic latency and, further, a movement speed that 229 approximately corresponds to 20 deg/s. In organisms that are successful at stationary 230 camouflage, can change colour [56], or have different appearances through a "flicker-fusion" 231 effect [57], saltatory locomotion could be particularly advantageous. In our experiment, the 232 phenotype that induced the greatest localisation error was plain, with the mean luminance of 233 the background, rather than background-matching in pattern. Cuttlefish that are camouflaged 234 when stationary have been observed to change to a plain colour when moving [56], 235 consistent with what we would predict from our results. Although, for short (100 ms) duration 236 movements, the pattern of the target had no effect on localisation error (Fig. 2), this was at 237 the cost of a far longer response time in the absence of an alerting flash.

238 Our data show that it is more advantageous to move guickly to reduce localisation accuracy 239 [24]. This seems counter to the typical slow movements used by military operatives [58, 59] 240 and stalking predators [60] and could suggest an alternative; namely, darting between 241 periods of stationary camouflage or refuges/protective cover. There is a significant 242 interaction between the movement duration and the target's movement speed, with 243 increased speed above 20 deg/s having no additional benefit for 400 ms movements. 244 However, this could be an artefact of targets nearing the screen edge in the fast/long-245 duration combination of treatments, such that the extent of over-estimation was constrained. 246 A flash before movement does not 'anchor' the viewer's fixation upon the target's starting 247 point. Instead, it appears that the flash cues the viewer to divert their attention towards the 248 target and primes them for the motion that follows, and could hence accelerate the saccade 249 to locate the target in central vision [61]. This contradicts multiple accounts in the literature 250 that deem highly salient patterns as having a startle effect [62-66]; these are proposed to 251 operate by overloading the perceptual mechanisms of the predator with sensory information, so that a prey animal can escape [21]. However, in the current study the target appears in
peripheral vision, away from the focus of attention, and so a startle effect would be unlikely.
Also, our results do not support the idea that motion, and subsequent localisation, is masked
due to a flash-lag effect. This is likely due to motion continuing beyond the flash-lag
processing time and, in order to be effective, flashing should correspond with cessation of
movement [17, 18].

The response time data support the conclusions of localisation error, indicating that shorter durations with mean luminance patterning and no flash prior to movement take longer to localise. Target speed had a limited effect on response time when durations were short, but response time increased progressively with target speed when the duration of movement was longer (400 ms), indicating increased uncertainty even when the moving target was in central vision.

264 Whilst motion is certainly detrimental to camouflage [1, 2] should movement be necessary 265 some behaviours and surface colour patterns reduce that cost [56]. Within the parameters 266 set by our experiment, the phenotype that minimises detection and localisation is 267 unpatterned, has mean background luminance, does not utilise a startle display (no flash) 268 prior to movement, and has short (below saccadic latency), fast movements. It is feasible 269 that predator attention is drawn to the first instance of movement and, subsequently, 270 predators could sit-and-wait for additional movement. However, this presupposes that the 271 predator was able to recognise the source of movement as potential prey, which may not be 272 the case. Additionally, it may not be beneficial for the predator to sit-and-wait for subsequent 273 movement from an uncertain source; continuing to actively search the environment may be 274 more beneficial. Furthermore, we must consider how noisy environments can be (e.g. foliage 275 in the wind) and the impact that this may have upon localisation of a moving target [8]. This 276 experiment highlights the importance of addressing ecological problems, whilst also 277 considering the perceptual differences that different regions of the visual field permit. Whilst 278 there are almost certainly quantitative differences across species, the qualitative effects

279 should remain the same. If we consider the ubiquity of the fixate-saccade strategy [14], and 280 the distribution of photoreceptors that results in a high-resolution region surrounded by an 281 area where resolution drops with increasing eccentricity, we could expect these results to 282 occur in many other species. So, while the speed and mechanism (eye, head or body 283 movement) will no doubt differ between humans and other species, the pattern of results 284 should hold generally. In particular, because limited information is acquired during a viewer's 285 gaze shift, to reduce the probability of being located accurately an animal should move and 286 stop before it can be fixated, and limit the amount of visual information available while 287 moving with colouration that approximates the mean luminance of the background and lacks 288 patterning. It would be very difficult to carry out similar experiments with non-human 289 subjects; we chose humans because it allowed us to be very specific in what we required 290 our observers to do, and what we measured. Our results show that the ability of a (model) 291 predator to localise a target presented in peripheral vision is influenced by different 292 components of movement (duration and speed) and target pattern; motion does not always 293 break camouflage.

294 Ethics

Participants gave their informed written consent in accordance with the Declaration of
Helsinki, and the Ethical Committee of the Faculty of Science, University of Bristol, approved
the experiment.

### 298 Data accessibility

All data are available from Dryad doi: to be completed upon publication.

### 300 Authors' contributions

- 301 All authors conceived and designed the experiment; I.E.S. and N.S.S. programmed the
- 302 experiment; I.E.S. carried out the experiment; I.E.S. and I.C.C. analysed the data; I.E.S.
- 303 wrote the first draft of the manuscript with subsequent contributions by all authors.

#### 304 Competing interests

305 The authors declare no competing interests.

### 306 Acknowledgements

- 307 We are grateful to everyone in CamoLab (<u>www.camolab.com</u>) for discussions and advice.
- 308 We also thank all the participants involved, who were not financially remunerated. We thank
- 309 the three anonymous referees and editors for their helpful comments.

### 310 FUNDING

- 311 This research was supported by the Engineering & Physical Sciences Research Council UK,
- 312 grant EP/M006905/1 to NSS, ICC and R.J. Baddeley.

### 313 **REFERENCES**

- 1. Hall J.R., Cuthill I.C., Baddeley R., Shohet A.J., Scott-Samuel N.E. 2013
- 315 Camouflage, detection and identification of moving targets. *Proceedings of the Royal Society*

316 *of London B: Biological Sciences* **280**(1758). (doi:10.1098/rspb.2013.0064).

317 2. Ioannou C.C., Krause J. 2009 Interactions between background matching and motion

during visual detection can explain why cryptic animals keep still. *Biology Letters* 5(2), 191-

319 193.

- 320 3. Rosenholtz R. 2016 Capabilities and limitations of peripheral vision. *Annual Review*
- 321 *of Vision Science* **2**(1), 437-457. (doi:10.1146/annurev-vision-082114-035733).
- 322 4. Stevens M., Ruxton G.D. 2019 The key role of behaviour in animal camouflage.
- 323 Biological Reviews **94**(1), 116-134.
- 324 5. Cuthill I.C. 2019 Camouflage. *Journal of Zoology* **308**(2), 75-92.
- 325 (doi:10.1111/jzo.12682).
- 326 6. Merilaita S., Scott-Samuel N.E., Cuthill I.C. 2017 How camouflage works.
- 327 Philosophical Transactions of the Royal Society of London B: Biological Sciences **372**(1724).
- 328 (doi:10.1098/rstb.2016.0341).

329 7. Stevens M., Merilaita S. 2011 *Animal camouflage: mechanisms and function*. New
330 York, Cambridge University Press.

Cuthill I.C., Matchette S.R., Scott-Samuel N.E. 2019 Camouflage in a dynamic world.
 *Current Opinion in Behavioral Sciences* **30**, 109-115. (doi:10.1016/j.cobeha.2019.07.007).

Osorio D., Cuthill I.C. 2015 Camouflage and perceptual organization in the animal
 kingdom. In *The Oxford Handbook of Perceptual Organisation* (ed. Wagemans J.), pp. 843 862. Oxford, Oxford University Press.

10. Regan D. 2000 Human perception of objects: early visual processing of spatial form

337 defined by luminance, color, texture, motion, and binocular disparity. Sunderland, MA,

338 Sinauer Associates.

339 11. Rushton S.K., Bradshaw M.F., Warren P.A. 2007 The pop out of scene-relative

object movement against retinal motion due to self-movement. *Cognition* **105**(1), 237-245.

341 (doi:10.1016/j.cognition.2006.09.004).

342 12. Carrasco M. 2011 Visual attention: the past 25 years. *Vision Research* 51(13), 1484343 1525.

13. van Heusden E., Rolfs M., Cavanagh P., Hogendoorn H. 2018 Motion extrapolation

345 for eye movements predicts perceived motion-induced position shifts. *Journal of* 

346 *Neuroscience* **38**(38), 8243-8250. (doi:10.1523/JNEUROSCI.0736-18.2018).

14. Land M. 2019 Eye movements in man and other animals. *Vision research* 162, 1-7.
(doi:10.1016/j.visres.2019.06.004).

349 15. Walls G.L. 1942 *The vertebrate eye and its adaptive radiation*. Michigan, US,
350 Cranbrook Institute of Science.

351 16. Umbers K.D., Lehtonen J., Mappes J. 2015 Deimatic displays. *Current Biology* 25(2),
352 R58-R59. (doi:10.1016/j.cub.2014.11.011).

35317.Murali G. 2018 Now you see me, now you don't: dynamic flash coloration as an

antipredator strategy in motion. *Animal Behaviour* **142**, 207-220.

355 (doi:10.1016/j.anbehav.2018.06.017).

- 356 18. Loeffler-Henry K., Kang C., Yip Y., Caro T., Sherratt T.N. 2018 Flash behavior
- increases prey survival. *Behavioral Ecology* **29**(3), 528-533. (doi:10.1093/beheco/ary030).
- 358 19. Hailman J.P. 1977 Optical signals: animal communication and light. Bloomington &

359 London, Indiana University Press.

- 360 20. Nijhawan R. 1994 Motion extrapolation in catching. *Nature* **370**, 256-257.
- 361 (doi:10.1038/370256b0).
- 362 21. Stevens M. 2016 Cheats and deceits: how animals and plants exploit and mislead.
- 363 1<sub>st</sub> ed. Oxford, Oxford University Press.
- 364 22. Hughes A.E., Troscianko J., Stevens M. 2014 Motion dazzle and the effects of target
- 365 patterning on capture success. BMC Evolutionary Biology 14(201). (doi:10.1186/s12862-
- 366 014-0201-4).
- 367 23. Hogan B.G., Cuthill I.C., Scott-Samuel N.E. 2016 Dazzle camouflage, target tracking,
  368 and the confusion effect. *Behavioral Ecology* 27(5), 1547-1551.
- 369 (doi:10.1093/beheco/arw081).
- 370 24. Stevens M., Yule D.H., Ruxton G.D. 2008 Dazzle coloration and prey movement.
- 371 *Proceedings of the Royal Society of London B: Biological Sciences* **275**(1651), 2639-2643.
- 372 (doi:10.1098/rspb.2008.0877).
- 373 25. Stevens M., Searle W.T.L., Seymour J.E., Marshall K.L., Ruxton G.D. 2011 Motion
- dazzle and camouflage as distinct anti-predator defenses. *BMC Biology* **9**(81).
- 375 (doi:10.1186/1741-7007-9-81).
- 376 26. Scott-Samuel N.E., Baddeley R., Palmer C.E., Cuthill I.C. 2011 Dazzle camouflage
  377 affects speed perception. *PloS One* 6(6), e20233. (doi:10.1371/journal.pone.0020233).
- 378 27. Hämäläinen L., Valkonen J., Mappes J., Rojas B. 2015 Visual illusions in predator-
- prey interactions: birds find moving patterned prey harder to catch. *Animal Cognition* **18**(5),
- 380 1059-1068. (doi:10.1007/s10071-015-0874-0).
- 381 28. von Helversen B., Schooler L.J., Czienskowski U. 2013 Are stripes beneficial?
- 382 Dazzle camouflage influences perceived speed and hit rates. *PloS One* **8**(4), e61173.
- 383 (doi:10.1371/journal.pone.0061173).

384 29. Brainard D.H. 1997 The Psychophysics Toolbox. *Spatial Vision* **10**, 433-436.

385 (doi:10.1163/156856897X00357).

386 30. Kleiner M., Brainard D., Pelli D. 2007 What's new in Psychtoolbox-3. *Perception*387 36(Suppl)(14).

388 31. Pelli D.G. 1997 The VideoToolbox software for visual psychophysics: transforming
389 numbers into movies. *Spatial Vision* **10**(4), 437-442.

390 32. Yearsley J. 2004 Generate AR1 spatial data. See <u>http://www.mathworks</u>

391 *com/matlabcentral/fileexchange/5099-generate-ar1-spatial-data*.

392 33. Olshausen B.A., Field D.J. 1996 Natural image statistics and efficient coding.

393 *Network: Computation in Neural Systems* **7**(2), 333-339. (doi:10.1088/0954-898X\_7\_2\_014).

394 34. Gilchrist I. 2011 Saccades. In *The Oxford handbook of eye movements* (eds.

Liversedge S., Gilchrist I., Everling S.), pp. 85-94. New York, Oxford University Press.

396 35. Avery R.A., Mueller C.F., Smith J.A., Bond D.J. 1987 The movement patterns of

397 lacertid lizards: speed, gait and pauses in *Lacerta vivipara*. *Journal of Zoology* **211**(1), 47-63.

398 (doi:10.1111/j.1469-7998.1987.tb07452.x).

399 36. Bates D., Maechler M., Bolker B., Walker S. 2015 Fitting linear mixed-effects models
400 using Ime4. *Journal of Statistical Software* 67(1), 1-48. (doi:10.18637/jss.v067.i01).

401 37. Bretz F., Westfall P., Hothorn T. 2010 *Multiple comparisons using R*. 1<sub>st</sub> ed. New
402 York, Chapman and Hall/CRC.

403 38. Ehrenstein W.H., Arnold-Schulz-Gahmen B.E., Jaschinski W. 2005 Eye preference

404 within the context of binocular functions. *Graefe's Archive for Clinical and Experimental* 

405 *Ophthalmology* **243**(9), 926-932. (doi:10.1007/s00417-005-1128-7).

Smith A., Ledgeway T. 1998 Sensitivity to second-order motion as a function of
temporal frequency and eccentricity. *Vision research* 38(3), 403-410. (doi:10.1016/S00426989(97)00134-X).

409 40. Scott-Samuel N.E., Georgeson M.A. 1999 Does early non-linearity account for

410 second-order motion? Vision research **39**(17), 2853-2865. (doi:10.1016/S0042-

411 6989(98)00316-2).

- 412 41. Freyd J.J., Finke R.A. 1984 Representational momentum. *Journal of Experimental*
- 413 Psychology: Learning, Memory, and Cognition 10(1), 126-132. (doi:10.1037/0278-
- 414 7393.10.1.126).
- 415 42. Yarbus A. 1967 *Movements of the eyes*. London, Pion.
- 416 43. Land M.F., Nilsson D.-E. 2012 *Animal eyes*. 2nd ed. New York, Oxford University
  417 Press.
- 418 44. Land M.F. 1999 Motion and vision: why animals move their eyes. *Journal of*419 *Comparative Physiology A* **185**(4), 341-352. (doi:10.1007/s003590050393).
- 420 45. Land M.F. 2011 Oculomotor behaviour in vertebrates and invertebrates. In *The*
- 421 Oxford handbook of eye movements (eds. Liversedge S., Gilchrist I., Everling S.), pp. 3-15.
- 422 New York, Oxford University Press.
- 423 46. Matin E. 1974 Saccadic suppression: a review and an analysis. *Psychological*424 *Bulletin* 81(12), 899-917. (doi:10.1037/h0037368).
- 425 47. Weihs D. 1974 Energetic advantages of burst swimming of fish. *Journal of*
- 426 *Theoretical Biology* **48**(1), 215-229. (doi:10.1016/0022-5193(74)90192-1).
- 427 48. Fleishman L.J. 1985 Cryptic movement in the vine snake *Oxybelis aeneus*. *Copeia*428 **1985**(1), 242-245. (doi:10.2307/1444822).
- 429 49. Rayner J. 1985 Bounding and undulating flight in birds. *Journal of Theoretical Biology*430 **117**(1), 47-77. (doi:10.1016/S0022-5193(85)80164-8).
- 431 50. Jackson R.R., Olphen A.V. 1992 Prey-capture techniques and prey preferences of
- 432 Chrysilla, Natta and Siler, ant-eating jumping spiders (Araneae, Salticidae) from Kenya and
- 433 Sri Lanka. *Journal of Zoology* **227**(1), 163-170. (doi:10.1111/j.1469-7998.1992.tb04351.x).
- 434 51. Buskey E.J., Coulter C., Strom S. 1993 Locomotory patterns of microzooplankton:
- 435 potential effects on food selectivity of larval fish. *Bulletin of Marine Science* **53**(1), 29-43.
- 436 52. Kramer D.L., McLaughlin R.L. 2001 The behavioral ecology of intermittent
- 437 locomotion. *American Zoologist* **41**(2), 137-153. (doi:10.1093/icb/41.2.137).
- 438 53. McAdam A.G., Kramer D.L. 1998 Vigilance as a benefit of intermittent locomotion in
- 439 small mammals. *Animal Behaviour* **55**(1), 109-117. (doi:10.1006/anbe.1997.0592).

- 440 54. Bian X., Elgar M.A., Peters R.A. 2015 The swaying behavior of *Extatosoma tiaratum*:
- 441 motion camouflage in a stick insect? *Behavioral Ecology* **27**(1), 83-92.
- 442 (doi:10.1093/beheco/arv125).
- 443 55. Miller P.L. 1979 A possible sensory function for the stop—go patterns of running in
- 444 phorid flies. *Physiological Entomology* **4**(4), 361-370. (doi:10.1111/j.1365-
- 445 3032.1979.tb00628.x).
- 446 56. Zylinski S., Osorio D., Shohet A. 2009 Cuttlefish camouflage: context-dependent
- 447 body pattern use during motion. *Proceedings of the Royal Society of London B: Biological*
- 448 *Sciences* **276**(1675), 3963-3969. (doi:10.1098/rspb.2009.1083).
- 449 57. Umeton D., Read J.C., Rowe C. 2017 Unravelling the illusion of flicker fusion. *Biology*450 *Letters* 13(2). (doi:10.1098/rsbl.2016.0831).
- 451 58. Brunyé T.T., Martis S.B., Kirejczyk J.A., Rock K. 2019 Camouflage pattern features
- 452 interact with movement speed to determine human target detectability. Applied Ergonomics
- 453 **77**, 50-57. (doi:10.1016/j.apergo.2019.01.004).
- 454 59. Brunyé T.T., Martis S.B., Horner C., Kirejczyk J.A., Rock K. 2018 Visual salience and
- 455 biological motion interact to determine camouflaged target detectability. Applied Ergonomics
- 456 **73**, 1-6. (doi:10.1016/j.apergo.2018.05.016).
- 457 60. Curio E. 1976 *The ethology of predation*. 1st ed. Berlin, Springer.
- 458 61. Ludwig C.J. 2011 Saccadic decision-making. In *The Oxford handbook of eye*
- *movements* (eds. Liversedge S., Gilchrist I., Everling S.), pp. 425-438. New York, Oxford
  University Press.
- 461 62. Vallin A., Jakobsson S., Lind J., Wiklund C. 2006 Crypsis versus intimidation—anti-
- 462 predation defence in three closely related butterflies. *Behavioral Ecology and Sociobiology*
- 463 **59**(3), 455-459. (doi:10.1007/s00265-005-0069-9).
- 464 63. Vallin A., Jakobsson S., Lind J., Wiklund C. 2005 Prey survival by predator
- intimidation: an experimental study of peacock butterfly defence against blue tits.
- 466 *Proceedings of the Royal Society of London B: Biological Sciences* **272**(1569), 1203-1207.
- 467 (doi:10.1098/rspb.2004.3034).

- 468 64. Langridge K.V. 2009 Cuttlefish use startle displays, but not against large predators.
- 469 *Animal Behaviour* **77**(4), 847-856. (doi:10.1016/j.anbehav.2008.11.023).
- 470 65. Langridge K.V., Broom M., Osorio D. 2007 Selective signalling by cuttlefish to
- 471 predators. *Current Biology* **17**(24), R1044-R1045. (doi:10.1016/j.cub.2007.10.028).
- 472 66. Olofsson M., Eriksson S., Jakobsson S., Wiklund C. 2012 Deimatic display in the
- 473 European swallowtail butterfly as a secondary defence against attacks from great tits. *PLoS*
- 474 *One* **7**(10), e47092. (doi:10.1371/journal.pone.0047092).



476

477 Figure 1 - The target patterning that was used (a) background matching, created using

478 a 1/f function; (b) black; (c) grey (mean luminance). Below each target is an example of

479 how the target would appear on a background. A red outline has been added to

480 highlight the position of the target on the background (not present during the

481 experiment).

482



Pattern - BG - meanLum - minLum

484

Figure 2 - The mean error associated with the participant's ability to localise a moving object with different movement and patterning conditions, with 95% confidence intervals based on the fitted model (N=18 participants). Different combinations of movement and patterning conditions can be navigated via the panelling. The phenotype with the strongest effect has mean luminance, does not utilise a flash and has short, fast movements. Further, note that the width of the target is 48 pixels, and therefore the aforementioned phenotype is missed by more than three body lengths.

## Smart et al. Supplementary Material

Table S1. Location error: model simplification steps, starting with a full model (five fixed effects and all possible interactions).

Step	Term removed	$\chi^2$	df	р
1	Flash:Pattern:Screen:Duration:Speed	13.77	16	0.6161
2	Flash:Screen:Duration:Speed	3.36	8	0.9095
3	Flash:Pattern:Duration:Speed	11.05	16	0.8062
4	Flash:Pattern:Screen:Speed	4.59	8	0.8002
5	Flash:Pattern:Speed	1.68	8	0.9894
6	Flash:Pattern:Screen:Duration	7.66	8	0.4672
7	Flash:Screen:Duration	0.12	4	0.9983
8	Flash:Pattern:Screen	1.22	4	0.8749
9	Flash:Pattern:Duration	5.61	8	0.6913
10	Flash:Duration:Speed	9.62	8	0.2931
11	Flash:Duration	1.24	4	0.8723
12	Flash:Pattern	5.40	4	0.2484
13	Flash:Screen:Speed	6.30	4	0.1780
14	Flash:Screen	0.28	2	0.8697
15	Flash:Speed	2.63	4	0.6222
16	Pattern:Screen:Duration:Speed	11.53	8	0.1737
17	Pattern:Screen:Duration	0.89	4	0.9259
18	Pattern:Duration:Speed	5.16	8	0.7401
19	Screen:Duration:Speed	4.24	4	0.3746
20	Screen:Duration	1.33	2	0.5134
21	Pattern:Screen:Speed	8.85	4	0.0650
22	Screen:Speed	0.33	2	0.8489
23	Pattern:Screen	1.11	2	0.5741
24	Pattern:Speed	7.45	4	0.1139

The initial (saturated) model was ~ Flash\*Pattern\*Screen\*Duration\*Speed + (1 | Subject). Significance was assessed using likelihood ratio tests.

#### Analysis of response time

The final model contained a significant two-way interaction between duration and speed ( $\chi^2$  = 29.88, df = 4, p < 0.0001), and a three-way interaction between duration, pattern and the flash prior to the target moving (( $\chi^2$  = 21.74, df = 8, p = 0.0054) (Fig. S1; Table S2). To explore the nature of these interactions the data were split by duration, and models fitted with speed, pattern, flash and the two-way interaction between the latter two factors. For 100 ms movements, speed was not significant ( $\chi^2$  = 0.67, df = 2, p = 0.7150), but the pattern x flash interaction was ( $\chi^2$  = 26.14, df = 4, p < 0.0001). Analysing the flash conditions separately, with no flash, pattern was significant ( $\chi^2$  = 26.29, df = 2, p < 0.0001), with the mean luminance pattern having longer response times than black (z = 4.70, p < 0.0001) and background matching (z = 4.32, p < 0.0001), with the latter two treatments not differing (z = 0.40, p = 0.9170). However, when movement was preceded by a flash, there was no significant effect of pattern (50 ms:  $\chi^2$  = 2.75, df = 2, p = 0.2530; 80 ms:  $\chi^2$  = 0.16075, p = 0.9228).

For 200 ms movements, the pattern:flash interaction was not significant ( $\chi^2 = 3.33$ , df = 4, p = 0.5039). So, removing this term and simplifying the model sequentially, neither pattern ( $\chi^2 = 4.79$ , df = 2, p = 0.0914) or speed ( $\chi^2 = 5.58$ , df = 2, p = 0.0613) were significant, but flash was ( $\chi^2 = 35.03$ , df = 2, p < 0.0001), with response times longer for no flash than when a flash preceded movement (no flash vs 50 ms flash: z = 4.28, p < 0.0001; no flash vs 80 ms flash: z = 5.74, p < 0.0001; 50 ms vs 80 ms flash: z = 1.46, p = 0.3080).

For 400 ms movements, the pattern x flash interaction was not significant ( $\chi^2 = 4.10$ , df = 4, p = 0.3927). So, removing this term and simplifying the model sequentially, neither pattern ( $\chi^2 = 0.48$ , df = 2, p = 0.7865) or flash ( $\chi^2 = 4.95$ , df = 2, p = 0.0841) were significant, but speed was ( $\chi^2 = 70.92$ , df = 2, p < 0.0001), with response times increasing with target speed (10 vs 20 deg/s: z = 3.565, p = 0.0011; 10 vs 35: z = 8.53, p < 0.0001; 20 vs 35: z = 4.98, p < 0.0001).



Figure S1 - The response time for participants trying to localise a moving object with different movement and patterning conditions, with 95% confidence intervals based on the fitted model (N=18 participants). Different combinations of movement and patterning conditions can be navigated via the panelling. The phenotype with the strongest effect has mean luminance, does not utilise a flash and has short and/or fast movements.

Table S2. Response time: model simplification steps, starting with a full model (five
fixed effects and all possible interactions).

Step	Term removed	$\chi^2$	df	р
1	Flash:Pattern:Screen:Duration:Speed	16.29	16	0.4333
2	Flash:Screen:Duration:Speed	2.26	8	0.9720
3	Pattern:Screen:Duration:dotShift	5.67	8	0.6846
4	Pattern:Screen:Duration	1.22	4	0.8746
5	Flash:Pattern:Duration:dotShift	13.46	8	0.6389
6	Pattern:Duration:dotShift	4.27	8	0.8321
7	Flash:Screen:Duration:dotShift	9.86	8	0.2749
8	Flash:Screen:Duration	1.21	4	0.8756
9	Screen:Duration:dotShift	3.27	8	0.5130
10	Screen:Duration	0.35	2	0.8375
11	Flash:Duration:dotShif	11.36	4	0.1821
12	Flash:Pattern:Screen:dotShift	13.94	4	0.0835
13	Flash:Pattern:Screen	2.95	4	0.5655
14	Flash:Pattern:dotShift	9.11	8	0.3331
15	Pattern:Screen:dotShift	5.75	4	0.2187
16	Pattern:Screen	1.32	2	0.5165
17	Pattern:dotShift	7.67	4	0.1046
18	Flash:Screen:dotShift	8.04	4	0.0902
19	Flash:Screen	0.21	2	0.9018
20	Screen:dotShift	3.51	2	0.1725
21	Screen	0.03	1	0.8599
22	Flash:dotShift	7.55	4	0.1096

The initial (saturated) model was ~ Flash\*Pattern\*Screen\*Duration\*Speed + (1 | Subject). Significance was assessed using likelihood ratio tests.



Figure S2 – Angular error (relative to the target's trajectory) plotted against the logtransformed localisation error (distance from target) in pixels for participants trying to localise a moving object with different movement and patterning conditions (N=18 participants). Different combinations of movement and patterning conditions can be navigated via the panelling.