

1 **Hybrid Approach Combining Modelling and Measurement for Fatigue**
2 **Damage Estimation of Welded Connections in Bridges**

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2 **Damage Estimation of Welded Connections in Bridges**

3 The fatigue life of structural steel bridges is governed by the time history of in-situ
4 stresses at its fatigue-critical structural details under service conditions. However,
5 these stresses are often not directly and accurately measurable due to the complex
6 geometry of the detail or due to access restrictions. This paper proposes a novel
7 methodology to address this challenge. The methodology infers stresses at fatigue-
8 critical locations by combining in-situ strain measurements taken further away
9 from a critical location in a full-scale bridge. Strains measured at various points
10 around the physical welded connection are used to compute the forces and
11 moments applied at the connection. These forces are then applied to a finite
12 element model of the connection to predict the stresses that are required to evaluate
13 the hot spot stresses. The developed methodology is illustrated for a welded
14 connection in a full-scale bridge. Results show that the predicted time history of
15 hot spot stress is accurate and much more realistic than those obtained from
16 numerical simulations. Also, the study demonstrates that the proposed
17 methodology is applicable for interpreting measurements from full-scale bridges
18 and can be integrated within a measurement interpretation platform for continuous
19 bridge monitoring.

20 Keywords: Steel bridges; structural health monitoring; fatigue damage; hot spot
21 stress; numerical modelling

22 **Introduction**

23 Metallic bridges of all ages, including those that are approaching or have exceeded their
24 design service life and those that are relatively new having been built over the last few
25 decades, are vulnerable to fatigue damage. Fatigue damage is progressive damage due to
26 cyclic loading and is a concern mainly at locations of high stresses such as connections
27 in civil structures (Sun et al., 2019). Fatigue risk is particularly high for old bridges due
28 to a combination of much greater traffic volumes in recent years and significant age-
29 related deterioration (Marques et al., 2018; Zhou, 2006). A comprehensive survey by
30 Olofsson et al. (2005) examining the age profile of existing steel railway bridges in

1 Europe shows that more than 70% of these bridges are over 50 years old, and about 30%
2 of them are over 100 years old. The UK has over 6,000 metallic bridges, which are over
3 50 years old, with fatigue as the principal risk to their structural integrity (Adasooriya et
4 al., 2014). Thus, the reliable assessment of the remaining fatigue life of steel bridges is
5 of great importance both nationally and internationally for making decisions regarding
6 rehabilitation and replacement of existing bridges (Yang et al., 2018; Yan et al., 2017).

7 Significant research has gone toward evaluating effectively and accurately the
8 remaining fatigue life of metallic bridges. These have focused on evaluating the stress
9 time history induced by loading, and then using it to evaluate the cumulative fatigue
10 damage using an established damage model such as Miner's rule (Miner, 1945) and
11 relevant S-N curves derived from laboratory fatigue tests. The majority of the current
12 approaches rely on fatigue design rules to derive the stress time histories and have two
13 key limitations (Zhou et al., 2007; Wang et al., 2015). First, these approaches are based
14 on the nominal stress, which does not take into account the local stress concentration
15 effects in a specific weld detail (Park et al., 2014). These approaches are hence unreliable,
16 particularly for large structures with complex details for which accurately estimating the
17 nominal stress is often difficult (Ye et al. 2012). Second, current approaches exaggerate
18 greatly the actual applied live loads and in turn the stress cycles, resulting in overly
19 conservative estimates of the remaining fatigue life (Lee et al., 2016; Kashefi et al. 2010).
20 For many bridges, these approaches even give a remaining fatigue life that is negative
21 implying that the bridge has theoretically failed in fatigue while in reality the structure is
22 still in service without any visible evidence of fatigue cracking (Kwon et al., 2012). The
23 unnecessary retrofits or repairs necessitated by such conservative assessment procedures
24 significantly increase bridge maintenance costs (Rashidi et al., 2011).

1 An alternative method proposed in several standards such as Eurocodes is the hot
2 spot stress approach. It is applicable particularly to connections for which the nominal
3 stress cannot be evaluated accurately because of geometric and/or loading complexities
4 (Chen et al., 2016; Liu et al., 2014; Melaku et al., 2017). This is typical in many welded
5 connections in metallic bridges, which is the primary focus of this paper although
6 presented ideas are applicable also to other types of connections. It should however be
7 noted that the hot spot stress method is not applicable in certain geometrical scenarios,
8 and local approaches based on finite element method such as the effective notch method
9 may be used in such cases. As the focus of this paper is on the hot spot stress method,
10 these local approaches are not discussed here.

11 The International Institute of Welding (IIW) (Hobbacher, 2016) prescribes rules
12 and recommendations on the process of computation of the hot spot stress through
13 modelling. The hot spot stress approach has two key advantages over the nominal stress
14 methods. First, it explicitly accounts for stress concentration effects in the locality of the
15 weld toe by considering the construction details of the connection. Second, the reduced
16 stress scatter in plates thinner than 25mm implies that only a small number of S-N curves,
17 corresponding to only the different weld types are required for fatigue life evaluation, as
18 the construction details of the connection are already considered in the hot spot stress
19 evaluation. However, this approach still results in overly conservative estimates of
20 remaining fatigue life since it uses design daily traffic loads which are often much larger
21 than those from actual traffic on bridges (Aygül et al., 2012). For plates with thicknesses
22 larger than 25 mm, the application of both nominal stress and hot spot stress methods can
23 be challenging due to the difficulty in accounting for size effects.

24 With recent advances in sensing technology, in-situ strain measurements have
25 been increasingly employed for assessing the remaining fatigue life of steel bridges

1 (Helmerich et al., 2007; Zhou et al., 2007). These have been shown to be more reliable
2 than assessments based on stress predictions purely from numerical simulations (Ye et
3 al., 2012; Lee et al., 2016; Schumacher et al., 2006). However, most studies rely on
4 measurements of nominal stress in a main member rather than the local, concentrated
5 stress at a weld detail (Cardini & DeWolf, 2009; Kwon et al., 2012; Seo, Phares, Lu,
6 Wipf, & Dahlberg, 2013). The influence of local (i.e., concentrated) stresses is only
7 indirectly taken into account by using S-N curves that are obtained via experimental
8 testing for specific weld details. There is also the possibility of the structural detail and
9 load type not falling under one of the design classes provided in the codes. In such a
10 scenario, bespoke laboratory tests may be required to generate the S-N curves and this
11 can be a challenge since the testing procedure is expensive and time consuming.

12 Other studies have attempted to obtain nominal strains and stresses farther away
13 of a fatigue-critical locations (Ni et al., 2010). The nominal stresses are multiplied by a
14 Stress Concentration Factor (SCF) to take into account the stress concentration and
15 dimension effects. This approach is known as a modified nominal stress method in many
16 codes and standards such as Eurocodes (EN 1993-1-9 2005). Pasquier et al. (2016)
17 proposed a methodology that enables evaluating hot spot stresses in hollow section joints
18 using finite element models of the bridge that were identified based on measurements
19 from static load tests. These models were used to predict internal stresses, namely axial,
20 shear and bending stresses in the bridge elements, for traffic loads detected using a weigh
21 in-motion (WIM) system. The predicted stresses were then used to compute hot spot
22 stresses through stress amplification with SCFs. However, computing the SCFs, which
23 determine directly the reliability of the modified nominal stress method, is not
24 straightforward. A recent comprehensive review by (Saini et al., 2016) examining SCFs
25 of welded joints of metallic structures concluded that accurately computing these

1 parameters is difficult due to their dependence on loading conditions which are generally
2 unknown. Schumacher et al. (2006) showed that SCF values are typically conservative
3 using the case of tubular joints. Moreover, since the stresses were not measured in-situ
4 but predicted through models of the bridge, effects of modelling uncertainties such as
5 environmental conditions (e.g. temperature) and local conditions such as actual speed and
6 location of vehicle, and road profile may persist.

7 This paper proposes a novel methodology for evaluating in-situ hot spot stress
8 histories that overcomes the above-mentioned drawbacks. It integrates field
9 measurements of strains taken from around a welded plate detail with a numerical model
10 of the connection to evaluate the in-situ hot spot stresses. The measured strains are used
11 to compute the axial, shear and bending forces that are applied to the connection. By
12 applying these forces to the model, it will capture the local effects such as dynamic
13 amplification of load that play a major role in fatigue life. Also, unlike the modified
14 nominal stress method, knowledge of the SCF is not required but its effect is instead
15 explicitly accounted for within the modelling process. This paper investigates the
16 proposed methodology on a fatigue-sensitive welded detail (web-gap) in a specific full-
17 scale bridge.

18 The paper is organised as follows. It first describes the hot spot stress approach as
19 used in current practice. Then it presents the novel methodology and explains how it can
20 support reliable evaluation of the hot spot stresses. The methodology is subsequently
21 illustrated using strain measurements from the Bascule Bridge in Exeter/UK.

22 **Hot spot stress approach**

23 A comprehensive description of the hot spot stress approach is given in (Lee et al., 2010)
24 and (Hobbacher, 2009). In this paper, only a brief description of this approach, as required
25 to understand the proposed methodology, is given.

1 **Hot spot stress:** A location in a welded detail where fatigue cracking is most likely to
2 initiate (e.g. due to abrupt structural discontinuity) is commonly called a hot spot. The
3 stress at this location is referred to as the hot spot stress. The onset of fatigue failure at a
4 hot spot is determined by the time history of hot spot stresses. In a welded connection,
5 hot spots are usually at weld toes. The stress at the weld toe including the nonlinear notch
6 effects is referred to as the notch stress. The notch stress, can be decomposed into three
7 components: membrane stress σ_{mem} , shell bending stress σ_{ben} , and a nonlinear stress
8 component σ_{nlp} due to the weld toe singularity. The hot spot stress includes only the linear
9 stress components - σ_{mem} and σ_{ben} , and can be obtained from in-situ strain measurements
10 or through numerical modelling. The nonlinear stress component σ_{nlp} , is included
11 indirectly when using S-N curves that are obtained from laboratory fatigue tests (Radaj,
12 1990) for each weld type/local geometry to estimate the fatigue life.

13 **Evaluation of hot spot stress:** The International Institute of Welding (IIW) recommends
14 consideration of stresses at two types of hot spots - type *a* and type *b*. Figure 1 shows the
15 two types of hot spots in some typical weld details. Type *a* corresponds to hot spots on
16 the plate surface, and *b* corresponds to those on the plate edge. The hot spot stress at these
17 locations can be obtained using either surface stress extrapolation or linearization of stress
18 in the through thickness direction (Niemi et al., 2006). Due to their relative ease of
19 application, surface stress extrapolation methods are more popular in practice and are also
20 employed in this study. In surface stress extrapolation methods, the hot spot stress is
21 evaluated using the strains measured at certain reference locations adjacent to the hot
22 spot. To avoid nonlinearities, these locations are located outside of the region affected by
23 the weld toe notch singularity.

24 [Inserting Figure 1 approximately here]

1 For hot spots of type a on a plate having thickness t , the hot spot stress $\sigma_{hs,a}$ is computed
 2 as shown below through linear extrapolation of the stresses, $\sigma_{0.4t}$ and $\sigma_{1.0t}$, predicted at
 3 distances $0.4t$ and $1.0t$ respectively away from the weld toe (Figure 2).

$$4 \quad \sigma_{hs,a} = 1.67\sigma_{0.4t} - 0.67\sigma_{1.0t} \quad (1)$$

5 The hot spot stress $\sigma_{hs,b}$ for locations of type b is computed using a linearized
 6 approximation of a quadratic stress profile that is represented by the stresses - σ_{4mm} ,
 7 σ_{8mm} and σ_{12mm} , predicted on the plate edge at distances 4mm, 8mm and 12mm
 8 respectively from the weld toe. The corresponding equation is as follows.

$$9 \quad \sigma_{hs,b} = 3\sigma_{4mm} - 3\sigma_{8mm} + \sigma_{12mm} \quad (2)$$

10 In contrast to the stress profiles for hot spots of type a , the stress profile near the weld toe
 11 for a hot spot of type b is independent of the thickness of the plate, and hence Equation
 12 (2) hence does not have any terms related to t . However this equation is applicable only
 13 as long as the plate thickness is less than 25 mm. When evaluating $\sigma_{hs,b}$ for welded joints
 14 with plate thicknesses larger than 25mm, an empirical thickness correction factor that
 15 diminishes the fatigue strength also needs to be included (Niemi et al., 2006).

16 [Inserting Figure 2 approximately here]

17 **Proposed methodology**

18 This study proposes a hybrid methodology for deriving the in-service hot stress
 19 time-history through a combination of in-situ strain measurements and numerical
 20 modelling. This methodology, which is illustrated in Figure 3, is based on the approach
 21 proposed in Kwad et al. (2017), and works broadly as follows.

1 For a given steel bridge, the first step is to identify its fatigue-critical connections.
2 This can be done using a global finite element model (FEM) of the bridge that is validated
3 using a controlled load test. Then local FEMs are developed for the identified fatigue-
4 critical connections. The local FEMs are linear elastic models that comprise all the
5 connection components (e.g. stiffener, weld) along with small portions of the structural
6 elements that are part of the connection. For example, the local FEM of a main beam-
7 cross beam connection, which is the type of connection investigated in this paper, will
8 include small portions of the intersecting beams in addition to the connection
9 components. Simultaneously a field measurement plan is developed and implemented for
10 the fatigue-critical connections. The measurement plan will include installing strain
11 gauges on the structural elements relevant to the connection in a manner that will enable
12 evaluating the time history of internal forces that are transferred via the connection. These
13 force time histories are then applied to the local FEM to evaluate the time-histories of
14 stresses at relevant locations as necessary to compute the hot spot stress time histories
15 using Equations (1) and (2). These stress time histories are then used for fatigue damage
16 assessment using existing methods. Thus, in principle, if the strain gauges are left to
17 collect measurements continuously, then the fatigue life of the critical details can be
18 monitored continuously via this approach.

19 [Inserting Figure 3 approximately here]

20 The key elements in the methodology are now explained in detail.

21 **Global FEM:** This is a numerical model of the full-scale bridge that is capable of
22 predicting accurately its global deformation response. This model may be derived
23 initially using structural drawings of the bridge, and later updated and validated using
24 measurements from field testing.

1 **Local FEM:** This model essentially simulates the structural behaviour of the connection
2 and includes therefore the connection and the structural elements that intersect at the
3 connection. In this study, the structural elements are main beams and cross beams. These
4 are not modelled fully but only a short length as required to ensure stress concentration
5 effects from the connection are absent at the boundaries.

6 The local FEM is created according to the IIW recommendations (Niemi et al.,
7 2006) on the application of the hot spot stress approach. The IIW recommends the use of
8 8-noded shell or 20-noded solid elements, both of which allow for a linear stress
9 distribution through the thickness. The element mesh in the area close to the hot spot must
10 be refined to a degree such that the local stress gradients are captured accurately. Also,
11 the mesh should have nodes at locations where stresses are required according to
12 Equations (1) or (2). If shell elements are used, the weld geometry is usually omitted from
13 the model even though this simplification may underestimate the stiffness of the weld.
14 The stress at a reference location as required for Equations (1) and (2) is either

- 15 (1) the predicted maximum principal stress at the corresponding location in the model
16 if the stress vector is oriented within 60° of the normal to a weld toe, or else
17 (2) the normal stress that is oriented in the direction normal to the weld toe.

18 Defining suitable boundary conditions for the local FEM is critical to ensure
19 model predictions are reliable. This study evaluates three different boundary conditions
20 and their influence on the performance of the overall methodology (see Section *Local*
21 *FEM*).

22 **Deployment of monitoring system:** Measuring strain histories for fatigue life assessment
23 require a modern data acquisition system with sufficient data storage and a high sampling
24 rate (~ 100 Hz) to capture dynamic effects of loading. Strain gauges also have to be

1 installed in a manner that will allow evaluating the internal forces at locations
2 corresponding to the boundary of the local FEM. For each beam intersecting at the
3 connection, sufficient number of strain gauges are required to enable computing the three
4 main internal forces - bending moment (about its major axis), axial force and shear force.
5 In main girder – cross beam connections, such as those in plate girder bridges like the
6 Bascule Bridge that is considered as a case study in this paper, torsion and bending effects
7 about the minor axis can be assumed negligible (Håkansson & Wallerman, 2015) due to
8 the following reasons. The cross beams in such bridges are essentially simply supported
9 between the main girders (Haghani, Al-Emrani, & Heshmati, 2012) and therefore impose
10 no torsion on the main girders. Axial forces are also unlikely in the cross beams due to
11 the lack of lateral forces on the bridge; hence there will be negligible minor axis bending
12 effects in the main girder. Consequently, the following two sets of strain gauges will
13 generally suffice: (i) strain gauges at the top and bottom flanges of the cross-section to
14 capture bending effects, and (ii) a rosette near the neutral axis to capture shear effects.
15 Measurements from these gauges will enable computing the exact location of the neutral
16 axis, and subsequently the bending moment, shear force and axial force through simple
17 Euler-Bernoulli beam bending assumptions. For bridges where torsion and minor axis
18 bending effects are significant, additional strain gauges can be used to evaluate the
19 relevant force and moment components.

20 ***Hot spot stress evaluation:*** The internal forces computed for each measurement time-
21 step are applied as loading to the local FEM of the connection. The local FEM is used to
22 predict the stresses at the reference locations as required to compute the hot spot stress
23 σ_{hs} using Equations (1) and (2). Since the local FEM is a linear elastic model with stresses
24 related linearly to the applied loads, individual FEM runs are not required for determining
25 the stresses due to internal forces and moments evaluated from each measurement time-

1 step. This can be accomplished through the use of load scaling factors (LSF) – $S_{M,i}$, $S_{V,i}$,
 2 $S_{A,i}$, which are essentially the stresses produced at a reference location i by an internal
 3 force – namely a bending moment M , a shear force V or an axial force A of unit magnitude.
 4 The stress $\sigma_{i,j}$ at a reference location i due to the internal forces M_j , V_j and A_j , evaluated
 5 for a measurement time step j , is therefore computed by superposing together the
 6 individual stresses $\sigma_{M,i,j}$, $\sigma_{V,i,j}$ and $\sigma_{A,i,j}$, produced by the three internal forces, assuming
 7 linear behaviour, as shown using the following equations.

$$8 \quad \sigma_{M,i,j} = M_j S_{M,i} \quad (6)$$

$$9 \quad \sigma_{V,i,j} = V_j S_{V,i} \quad (7)$$

$$10 \quad \sigma_{A,i,j} = A_j S_{A,i} \quad (8)$$

$$11 \quad \sigma_{i,j} = \sigma_{M,i,j} + \sigma_{V,i,j} + \sigma_{A,i,j} \quad (9)$$

12 $\sigma_{i,j}$ computed at reference locations i for a time step j are used in Equations (1) and (2) to
 13 determine the corresponding hot spot stress $\sigma_{hs,j}$. The time history of hot spot stresses is
 14 then used to assess fatigue damage using Miner's rule (Miner, 1945) and appropriate S -
 15 N curves.

16 ***Fatigue damage assessment:*** The σ_{hs} time history produced is converted into equivalent
 17 cyclic stress time history through a cycle counting algorithm. This will enable creating a
 18 stress histogram representing the number of stress cycles within various stress ranges.
 19 This study uses the well-known Rainflow counting method (ASTM E1049 - 85, 2005).
 20 Then suitable S-N curves that describe the fatigue resistance of the detail are adopted
 21 from Eurocode 3 (EN 1993-1-9, 2005), British Standard BS 7608:1993 and (IIW 2016).

1 The fatigue damage D (the total damage from all stresses that are applied to the detail) is
 2 evaluated using damage accumulation models. This study uses Miner's (Miner, 1945)
 3 linear damage accumulation model as described by the equation below.

$$4 \quad D = \frac{n_1}{N_1} + \frac{n_2}{N_2} + \frac{n_3}{N_3} + \dots = \sum^n \frac{n_i}{N_i} \leq 1.0 \quad (3)$$

5 where k is the number of stress ranges considered in the damage accumulation model. n_i
 6 is the number of stress cycles falling within stress range $\Delta\sigma_{ri}$ and is obtained using
 7 Rainflow counting on the σ_{hs} time history. N_i denotes the number of resisting stress cycles
 8 of the detail for stress range $\Delta\sigma_{ri}$ and is determined from the S-N curve relationships in
 9 Eurocode 3 (EN 1993-1-9, 2005) as follows.

$$10 \quad N_i = N_o \cdot \left(\frac{\Delta\sigma_C}{\Delta\sigma_{ri}} \right)^3, \quad (N_o = 2 \times 10^6, \quad \Delta\sigma_{ri} \geq \Delta\sigma_D) \quad (4)$$

$$11 \quad N_i = N_o \cdot \left(\frac{\Delta\sigma_C}{\Delta\sigma_{ri}} \right)^5, \quad (N_o = 5 \times 10^6, \quad \Delta\sigma_L < \Delta\sigma_{ri} \leq \Delta\sigma_D) \quad (5)$$

12 $\Delta\sigma_C$ and N_o are constants corresponding to the fatigue strength and fatigue life for a stress
 13 range $\Delta\sigma_{ri}$ on the S-N curve. $\Delta\sigma_D$ and $\Delta\sigma_L$ are constant-amplitude fatigue limit and
 14 fatigue threshold respectively. Fatigue failure is said to occur when $D = 1.0$. D can also
 15 be used to arrive at an estimate of the remaining fatigue life of the component based on
 16 the current loading conditions. It should be noted that partial safety factors for fatigue
 17 resistance are not considered in this study.

18 **Case study– Bascule Bridge**

19 ***Bridge description***

20 The Bascule Bridge in Exeter, UK (Figure 4) was built in 1972, and carries the

1 northbound carriageway of A379, a major trunk road, over the Exeter Canal. It is a
2 movable bridge with lifting hangers, a counterweight and hydraulic cylinders on both
3 sides of the bridge that enable it to be raised and lowered to allow boats to pass through.
4 The bridge supports one-way traffic of significant volume with a posted maximum speed
5 limit of 40 mph. The bridge uses a twin-main beam system that is classified as fracture
6 critical AASHTO (American Association of State Highway and Transportation Officials,
7 2010) since the fatigue failure of a single connection can lead to bridge collapse or closure
8 of the bridge for repair.

9 The bridge has a simply supported span of length 17.28m. It consists of two rolled
10 main girders, 17 cross beams and a composite aluminium deck. The cross beams are 8.12
11 m long and spaced at 970 mm intervals.

12 [Inserting Figure 4 approximately here]

13 The total width of the bridge is 8.12 m with two lanes that are 3.35 m wide each
14 and a 2 m wide footway on one side of the bridge. The longitudinal beams and cross
15 beams are steel rolled sections having the cross-section geometries detailed in Table 1.
16 The longitudinal beams are spaced 8.2 m apart.

17 [Inserting Table 1 approximately here]

18 The Bascule Bridge has 34 beam – beam connections corresponding to where the
19 17 cross beams are connected to the two main girders. This type of connection, commonly
20 used in steel girder bridges, is known to be susceptible to distortion-induced fatigue
21 cracking. In each of these connections, double vertical stiffener plates 13 mm thick are
22 welded to the web of the main girder (inside and outside of the web girder) using a fillet
23 weld, and the inside stiffener is connected to the cross-beam via a series of bolts as shown
24 in Figures 5 (a) and (b).

25 [Inserting Figure 5 approximately here]

1 Prior to the mid-1980s, steel girder bridges had cross beams that were joined to
2 the main girder via transverse connection stiffeners. The stiffeners were welded to the
3 main girder web but with a gap near the tension flange. This practice was intended to
4 avoid introducing localized strains in the tension flanges that could eventually result in
5 the formation of fatigue cracks. As a result, a small length of the girder web, extending
6 from the extreme edge of the stiffener to the tension flange, was left unsupported as
7 illustrated in the Figure 5 (b). Differential deflection between the main girders of the
8 bridge under live loading results in cross beam either pulling or pushing the girder web
9 (out-of-plane distortion). The consequence is a high level of cyclic secondary stress in
10 the web gap area that eventually will generate fatigue cracking as illustrated in Figure 5
11 (c). Connor & Fisher (Connor & Fisher, 2006) found that close to 90% of all fatigue
12 cracking problems in steel bridges in the USA were due to out-of-plane distortion of
13 fatigue sensitive details. Fisher and Roy (2015) provide a more detailed discussion on the
14 out-of-plane distortion manifesting in web-gap regions.

15 ***Global numerical model of the bridge***

16 A global FEM for the Bascule Bridge using 28,496 nodes and 26,891 shell elements was
17 developed and validated by Kwad et al. (Kwad et al., 2017). Measurement data from a
18 controlled quasi static loading test using a truck of known loading was used to calibrate
19 the global FEM. The model has been shown to provide reliable stress results for both
20 static and dynamic loading (Kwad et al., 2017). Full details of the model are not presented
21 here for reasons of brevity but are available from (Kwad et al., 2017).

22 ***Local FEM***

23 The fatigue-critical connection (Figure 6) in the bridge consist of an assembly of a main
24 girder, cross beam and vertical web stiffener. The ANSYS® parametric design language

1 (APDL) is used to build a local FEM model of the connection. 20-noded solid elements
2 are used, since the weld can be easily modelled with prismatic elements, to model the
3 cross beams, main beams and vertical stiffener. A fine mesh is adopted, and weld
4 geometry is modelled. The welded connection is assumed to be fully rigid within the local
5 FEM. This assumption is acceptable as the large number of heavy bolts and weld in this
6 connection are likely to make the connection behave in a rigid manner (Zamiri Akhlaghi,
7 2009). To comply with the IIW recommendations (Hobbacher 2016), the size of the
8 elements is 8 mm x 8 mm (i.e. $0.4t \times 0.4t$) at type 'a' hotspots and 20 mm x 20 mm (i.e.
9 $t \times t$) for adjacent elements where t represents the base plate thickness and is equal to 20
10 mm. Materials are assumed linear elastic and isotropic (Elastic modulus of steel = 205
11 GPa and Poisson's ratio = 0.3). The local FEM mesh consists of 54,509 elements with a
12 total of 79,081 nodes. The running time for a typical analysis is approximately 5 minutes
13 on a PC with 8 GB of RAM.

14 [Inserting Figure 6 approximately here]

15 The connection is designed to transfer forces from the cross beam, which are
16 created by the vehicles traveling on the bridge deck, to the main (longitudinal) girder.
17 These forces are the key determinant of the stresses at the weld in this connection, and
18 the monitoring system is designed to capture these forces. The internal forces – A, V and
19 M, namely, the axial force, shear force and bending moment, that are computed from the
20 measured strain data will be applied as loading to the local FEM and the global FEM as
21 appropriate.

22 Defining the boundary conditions for the local FEM can be challenging.
23 Therefore, three different boundary conditions that vary in the level of complexity are
24 attempted to evaluate which one simulates closely the real conditions and provides
25 satisfactory balance between accuracy and computational effort.

1 (1) BC1: In *BC1*, the ends of the main girder are modelled as pinned supports.

2 Therefore, all translational and rotational degrees of freedom at the node at the
3 neutral axis on the two ends of the main beam on either side of the connection
4 with cross-beam are fixed. No constraint is applied on the end of the cross beam.

5 (2) BC2: In *BC2*, the ends of the main girder and the cross-beam are assumed to be

6 on supports that offer partial fixity by using 3 translational and 3 rotational springs
7 with stiffness corresponding to the resistance offered by the rest of the bridge. The
8 COMBINE14 spring element available in ANSYS is used to model the springs.

9 The global FEM is used to identify the stiffness of the springs. A coupling
10 technique available in ANSYS is adopted that uses zero point-mass elements as
11 master nodes to translate the stiffness of the springs to all the nodes along the
12 boundaries of the local FEM.

13 (3) BC3: In *BC3*, a well-known shell-to-solid sub-modelling technique available in

14 ANSYS is employed to transfer displacements from the global FEM for the
15 measured internal forces to the local FEM (Alencar, de Jesus, Calçada, & Silva,
16 2018).

17 To find the load scaling factors (LSF), stress responses are computed for
18 individual unit internal forces, i.e. 1 kNm, 1 kN and 1 kN. The predicted values of the
19 normal stress component (inner side of the web gap of the main beam) oriented in the
20 normal direction to the weld toe at the reference locations for each of the applied forces
21 (Figure 7), are the LSFs. These forces are applied separately at the end of the modelled
22 cross beam at a distance of 1040 mm from the connection, which coincides with the
23 physical location of strain gauges on the full-scale bridge. Table 2 presents magnitudes
24 of LSFs of the main girder-cross beam connection for the three types of boundary
25 conditions.

1 [Inserting Figure 7 approximately here]

2 [Inserting Table2 approximately here]

3 ***Field instrumentation of connection***

4 A monitoring system consisting of 8 weldable strain gauges with 5.84 mm (0.72”) active
5 grid length, a data logger and a power source is used to collect the strain data. The sensors
6 are installed at locations corresponding to the boundary of the local FEM. The locations
7 of the strain gauges in the connection are indicated in Figures 8 (a) and (b), in which the
8 rivets are not sketched for clarity. The strain gauges SG 3 to SG-7 represent those installed
9 on the cross beam. These are installed to evaluate the internal forces transferred by the
10 weld. SG 8 is the gauges placed on the main beam at distances 400 mm from the vertical
11 stiffener to capture strains developed in the main girder. SG- 1 and SG 2 are the gauges
12 placed at distances $0.4t$ (8 mm) and $1t$ (20 mm) from the weld toe at the end of the vertical
13 stiffener. These are the reference locations at which stresses are required to compute the
14 stress at a hot spot of type *a* according to the IIW recommendations. The locations of
15 these gauges on the full-scale bridge are shown in Figure 8 (c).

16 [Inserting Figure 8 approximately here]

17 Strain gauges are used to record the response of the bridge to in service live loads
18 at a sampling rate of 2000 Hz for a period of 6 hours. 2000 Hz is a much higher sampling
19 rate than required for this task but this was used as the instrumentation offered this
20 capability. The purpose of the monitoring was to measure directly the strains caused by
21 the site-specific traffic. For visual clarity and to enable comparison between measured
22 and predicted data, the figures in this section and the next however present data for a
23 duration of only 35 seconds when a heavy vehicle passed over the bridge.

1 *Validation of local FEM*

2 Noise in strain measurements is first eliminated using a low-pass filter with a cut-off
3 frequency of 150 Hz as shown in Figure 9. This frequency was, through a trial and error
4 process, identified as the minimum frequency below which filtering would adversely
5 affect the stress peaks caused by the traffic. The trough in the measurements is due to the
6 passage of a heavy vehicle.

7 [Inserting Figure 9 approximately here]

8 Filtered strain measurements from sensors SG-1, SG-3 to SG-7 and SG-8 are
9 multiplied by modulus of elasticity of steel ($E = 205 \text{ GPa}$) to get the stress response. The
10 calculated stresses from sensors SG-3 to SG-7 are converted into time history of internal
11 forces using Euler-Bernoulli beam theory equations. Figure 10 shows the magnitudes of
12 computed internal forces, namely bending moments, axial and shear forces for the
13 considered 35 second duration. All three internal forces are used in conjunction with the
14 local FEM discussed in section *Local FEM* to determine the stress time history at 8 mm
15 from the weld toe of the connection.

16 [Inserting Figure 10 approximately here]

17 These force time histories and the LSFs, discussed in section *Local FEM*, are used
18 in Equations (6) to (9) to predict individual stresses at the two reference locations and
19 main beam location (i.e. location of the SG-8). Figure 11 shows the time history of
20 predicted $\sigma_{8 \text{ mm}}$, the stress at the reference location at a distance of 8 mm from the weld
21 toe, when using boundary conditions *BC1*, *BC2* and *BC3* in the local FEM. The figure
22 also presents the time history of measured stresses at this location as computed using
23 strain measurements from sensor SG-1.

24 [Inserting Figure 11 approximately here]

1 The plots show that the local FEM is sensitive to the chosen boundary conditions.
2 This sensitivity can be captured by examining the difference between the predicted
3 stresses for the duration when the bridge is crossed by a heavy vehicle. The peak
4 compressive stress obtained using *BC3* in the local FEM is more realistic than predicted
5 using *BC1* and *BC2*. The stresses predicted by the local FEM using *BC1* and *BC2* agree
6 to a certain degree with the experimental measurements with a mean error of only 3.5%
7 and 5.9% over the 35 second period, respectively. However, when using *BC3*, the mean
8 error is only 2.6%.

9 Strain measurements from sensor SG-8 are also used to resolve the uncertainty in
10 boundary conditions in the local FEM. Figure 12 presents the time history of measured
11 stresses at this location as computed using strain measurements from sensor SG-8. The
12 figure also shows the stresses predicted by the local FEM using *BC1*, *BC2* and *BC3* at the
13 location of the SG-8. The stresses predicted by the local FEM using *BC3* is almost the
14 same as the measured stresses with a mean error of only 2.5% over the 35 second period.
15 However, when using *BC1* and *BC2*, the mean errors are over 59% and 3.8%,
16 respectively.

17 [Inserting Figure 12 approximately here]

18 From Figures 10, 11 and 12, it can be concluded that the predicted stress at the
19 weld region is mainly due to shear in the cross beam. Stresses induced by moment in the
20 cross beam are very small and can be neglected for this connection. For the kind of detail
21 analysed in this study, the vertical load (shear) from the cross-beam should typically cause
22 compression on both sides of the girder web. However, the strain measurements show
23 that there is compression on the inside face and tension on the outside face of the web
24 gap of the girder and this is potentially due to distortion effects. Distortion-induced
25 fatigue cracking is a consequence of cyclically applied small and local deformations that

1 are normally out-of-plane. According to the field measurements, the stress between the
2 connection plate and the web welds is large enough to result in fatigue cracking.

3 The results also show that the local FEM using boundary condition $BC3$ is found
4 to be appropriate for simulating the local stresses induced by real traffic. Using the local
5 FEM with boundary conditions $BC3$, the time history of hot spot stress σ_{hs} is computed
6 for the duration of the monitoring. Strain measurements from sensors SG-1 and SG-2 are
7 used to derive the measured time history of the hot spot stress at the weld toe. The
8 measured and predicted hot spot stress are compared for a 35-second duration when a
9 heavy vehicle passes over the bridge causing significant stress in the connection. These
10 stresses are given in Table 3.

11 [Inserting Table 3 approximately here]

12 The results reveal that there is good agreement between the hot spot stresses
13 obtained using the proposed methodology and its counterpart from the measured strain
14 under real-life loading. The mean percentage error in the predicted stress relative to the
15 measured hot spot stress values is calculated, for the chosen 35 seconds as well as the full
16 duration of monitoring (6 hours). It is observed to be less than 4.1% for the selected 35
17 seconds, and less than 6.96% for the whole monitoring period. The range of these errors
18 is less than the $\pm 10\%$ error ranges given for hot spot stresses obtained based solely on
19 finite element analysis (Heshmati, 2012). Although these errors are in an acceptable
20 range, a sensitivity analysis is conducted and described in the next section to identify the
21 most suitable finite element mesh and element type configuration for this application.

22 ***Effects of mesh size:*** The effect of mesh size can be inferred from computing the hot spot
23 stress as recommended by the BSI standards (BSI, 2014), i.e. using Equation (1). For
24 stress analysis based on measured strains or finite element models of a relatively fine
25 mesh, the BSI standards recommend the use of linear extrapolation of stresses at distances

1 0.4t (i.e. 8 mm) and 1.0t (i.e. 20 mm) from the weld toe. Using this equation, hot spot
2 stress for different mesh sizes are calculated and compared in Table 4. It is found that the
3 model when using a fine mesh provides accurate results. Table 4 also shows clearly that
4 the plate surface stresses in the web gap region near the stiffener plate are underestimated
5 with a coarse mesh. The Table shows that a mesh composed of 4 mm or 8 mm can be
6 adopted to obtain a reasonable solution to avoid unnecessary complexity and
7 computational effort. Consequently, the local FEM developed in this research
8 successfully evaluates the hot spot stress at the weld toe and is appropriate for simulating
9 the local stress values induced by the real traffic.

10 [Inserting Table 4 approximately here]

11 **Fatigue damage assessment based on hot spot stress**

12 In this section, we show how the proposed fatigue stress evaluation procedure can become
13 part of a fatigue damage assessment method using the connection in the Bascule Bridge
14 as a case study. As described in section *Validation of local FEM*, the strain time history
15 from SG-3 to SG-7 and local FEM (*BC3* case, 4 mm mesh size) are used to evaluate the
16 hot spot stress at the connection under real traffic loading. Stress cycles are then counted
17 using the Rainflow algorithm (ASTM E1049 - 85 2005). Figure 13 shows the time history
18 of hot spot stresses for the entire 6 hours duration for which monitoring was conducted.
19 Figure 14 shows the stress histogram obtained after using the Rainflow algorithm.

20 [Inserting Figure 13 approximately here]

21 [Inserting Figure 14 approximately here]

22 Fatigue damage assessment requires the S-N curve for the connection. In
23 Eurocode 3 (EN 1993-1-9 2005), the fatigue strength of hot spot stress range is
24 represented by two curves with respect to typical weld detail categories. The category is
25 designated by the fatigue strength $\Delta\sigma_C$ at 2 million cycles. The S-N curve in Eurocode 3

1 (EN 1993-1-9 2005) is expressed in Equation (4) and (5). Figure 15 shows the S-N curve
2 provided in the Table B.1 Eurocode 3 (EN 1993-1-9 2005) for the detail category 100,
3 which covers connections such as non load-carrying fillet welds in the Bascule Bridge.
4 Using the linear damage accumulation model, as proposed by Miner's rule (Miner, 1945)
5 and expressed in Equation (3), cumulative fatigue damage is then evaluated from the
6 histogram derived from the hot spot stress time history.

7 [Inserting Figure 15 approximately here]

8 It should be noted that all stress ranges below the fatigue threshold $\Delta\sigma_L$ are
9 omitted in the damage accumulation. Table 5 contains the damage ratios obtained for
10 each stress range and also the cumulative fatigue damage - 1.25×10^{-5} , for the considered
11 monitoring period.

12 [Inserting Table 5 approximately here]

13 Based on the field measurements, the maximum range of hot spot stress – 78 MPa
14 (Table 5), exceeds the CAFL at the instrumented location. Therefore, the longitudinal
15 girder of the bridge must be considered to have a finite fatigue life and the remaining
16 fatigue life of the bridge have to be estimated. As the bridge has been monitored only for
17 a short duration (6 hrs in total), the author acknowledges that the derived stress histogram
18 is not sufficient to evaluate the remaining fatigue life of the bridge (Connor & Fisher,
19 2006); this requires data from a much longer monitoring duration (at least a week with
20 24hrs per day). However, the goal here is only to illustrate that the proposed fatigue stress
21 evaluation method can support an approach for fatigue damage assessment, and the
22 measured data is sufficient for this purpose.

23 **Conclusions**

24 This paper investigates the following hypothesis: detailed finite element models of
25 fatigue-critical connections and in-service strain measurements that capture the shear,

1 flexure, and axial demands of the modelled connections can be combined to estimate
2 accurately the in-situ hot spot. This enables much more reliable assessment of fatigue life
3 than possible by current methods that employ artificial strain histories predicted for code-
4 specified loads. The paper specifically focuses on investigating this hypothesis for the
5 fatigue-sensitive web-gap welded details in ladder-type bridge decks. However, the
6 presented ideas are applicable to riveted/bolted connections in this type of steel bridges.
7 Conclusions from this research are as follows.

- 8 (1) The hot spot strains predicted by the proposed hybrid approach of combining
9 measurements with numerical modelling is within 4% of the field measured
10 strains. This demonstrates that the real stresses at fatigue critical details can be
11 evaluated using the proposed methodology.
- 12 (2) The choice of boundary conditions plays an important role in the performance of
13 the local FEM. Boundary condition *BC3* that uses the sub-modelling approach to
14 link the global FEM and the local FEM leads to the best stress predictions.
- 15 (3) In the Bascule Bridge, the predicted stress at the weld region is mainly due to
16 internal shear forces in the cross beam. The internal moment is found to have a
17 negligible effect on the hot spot stress.
- 18 (4) Continuous fatigue monitoring based on the proposed approach can support real-
19 time fatigue damage evaluation in bridges as shown using the Bascule bridge with
20 measurements for one day.

21 This research is based on data collected from short monitoring periods. Further
22 long-term field monitoring is essential to prove robustness of methodology and to identify
23 the effects of seasonal variations in ambient conditions and loading. Future work in the
24 field of service-life prediction of existing steel bridges should consider inclusion of
25 environmental conditions and existing deterioration such as corrosion. Consideration of

1 these conditions may improve both the quality and accuracy of remaining fatigue life
2 assessments of existing steel bridges. Investigate ideas to extrapolate fatigue damage
3 results generated for one instrumented connection to other un-instrumented connections
4 through using global response measurements.

5

6 **Disclosure statement**

7 No potential conflict of interest was reported by the authors.

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12 **Table 1.** Geometrical characteristics of the main girders and cross beams.

Structural element	Depth (mm)	Top flange width (mm)	Top flange thickness (mm)	Bottom flange width (mm)	Bottom flange thickness (mm)	Web thickness (mm)
Main girder	926	304	32	304	32	20
Cross beam	523	208	13	208	13	10

13

14 **Table 2.** Calculated load scale factors (LSFs) for the three types of boundary conditions
 15 of the connection

Boundary condition type	Load scale factor (LSF)	Stress (SY) at 8 mm from weld toe $\sigma_{0.4t}$ (MPa)	Stress (SY) at 20 mm from weld toe $\sigma_{1.0t}$ (MPa)
<i>BCI</i>	$S_{M,i}$	0.062	0.064
	$S_{V,i}$	-1.143	-0.470

	$S_{A,i}$	0.105	0.161
<i>BC2</i>	$S_{M,i}$	0.069	0.078
	$S_{V,i}$	-1.410	-0.935
	$S_{A,i}$	-1.710	-0.942
<i>BC3</i>	$S_{M,i}$	0.101	0.220
	$S_{V,i}$	-1.480	-0.980
	$S_{A,i}$	-3.990	-3.200

1

2 **Table 3.** The measured and predicted hot spot stress of the connection when a heavy
3 vehicle passed over the bridge

Connection type	$\sigma_{8\text{mm}}$ from local FEM (MPa)	$\sigma_{20\text{ mm}}$ from local FEM (MPa)	Hot spot stress σ_{hs} based on strain measurements (MPa)	Hot spot stress σ_{hs} based on proposed methodology (MPa)
Vertical stiffener to the beam web	12.00	7.96	14.71	14.10

4

5 **Table 4:** Measured and predicted hot spot stress error comparison of the connection
6 when a heavy vehicle passed over the bridge with different mesh sizes.

Mesh size	Predicted hot spot stress (MPa)	Error (%)
20	6.52	55.60
10	12.66	13.95
8	14.10	4.10
4	14.44	1.84
2	14.54	1.20
1	14.60	1.00
0.5	14.91	-1.40

7

8 **Table 5:** Cumulative fatigue damage (D) evaluated over two days (6 h period).

$\Delta \sigma_{ri}$ [MPa]	n_i	N_i	$D = \frac{n_i}{N_i}$
30	64	42.7E+07	0.15E-06
34	49	22.8E+07	0.21E-06
38	47	13.1E+07	0.36E-06
42	29	79.3E+07	0.37E-06
46	38.5	5.03E+07	0.77E-06
50	45.5	3.32E+07	1.37E-06
54	33	2.26E+07	1.46E-06
58	25.5	1.58E+07	1.61E-06
62	21	1.13E+07	1.85E-06
66	11	0.83E+07	1.32E-06
70	4.5	0.62E+07	0.73E-06
74	10	0.48E+07	2.08E-06
78	5	0.41E+07	1.21E-06
Total Cumulative fatigue damage			1.25E-5

1

2

3 **Figure 1:** Hot spots of types *a* and *b* (Hobbacher 2016) with the arrows indicating the
4 directions of the loads at the connection.

5 **Figure 2:** Evaluation of the hot spot stress at a hot spot of type *a* through linear
6 extrapolation (Hobbacher 2016).

7 **Figure 3:** Overview of the proposed methodology for stress time history/fatigue
8 damage evaluation at directly monitored details.

9 **Figure 4:** Bascule Bridge overview.

10 **Figure 5:** (a) The cross beam is attached to the vertical web-stiffener of the girder by
11 bolts, (b) Layout and dimensions of the cross beam-main girder beam connection and

1 (c) Differential deflection of bridge girders results in high local bending stresses in
2 unstiffened web gaps.

3 **Figure 6:** Local FEM of the fatigue critical connection.

4 **Figure 7:** Extrapolation path of considered stresses at web gap region (y-axis represents
5 the vertical direction).

6 **Figure 8:** (a) Schematic of weldable strain gauges installed to top, bottom flanges and
7 mid web of cross beam (front view), (b) Schematic showing locations of weldable strain
8 gauges in web gap near weld region of main girder (side view) and (c) Weldable strain
9 gauges installed in web gap near the stiffener (see Figure 5).

10 **Figure 9:** Raw strains measured over a 35 second duration by sensor SG-1, and after
11 filtering using a lowpass filter with a cut-off frequency of 150 Hz.

12 **Figure 10:** Internal moments and shear forces computed over a 35 second duration
13 using strains from sensors SG-3 to SG-7.

14 **Figure 11:** Comparison of the time history (35 sec) of stresses measured by sensor SG-
15 1 with that of stresses predicted by local FEM with boundary condition *BC1*, *BC2* and
16 *BC3*.

17 **Figure 12:** Comparison of the time history (35 sec) of stresses measured by sensor SG-
18 8 with that of stresses predicted by local FEM with boundary condition *BC1*, *BC2* and
19 *BC3*.

20 **Figure 13:** Hot spot stress time history (6 h).

21 **Figure 15:** SN characteristic curve Detail 100 ($\Delta\sigma_c = 100$ MPa).

22 **Figure 14:** Histogram of measured data – (6 h).

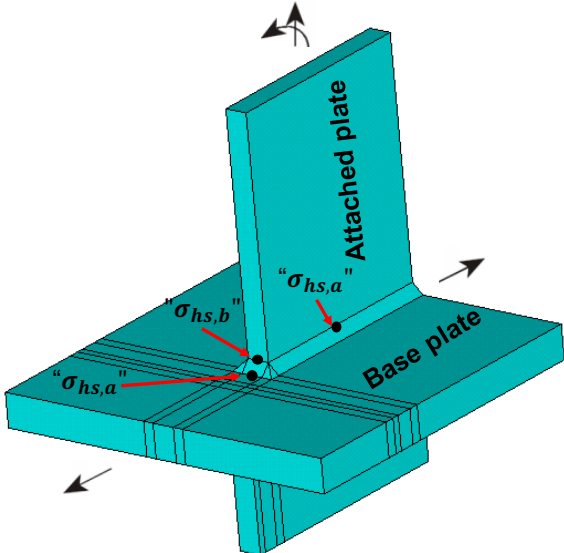
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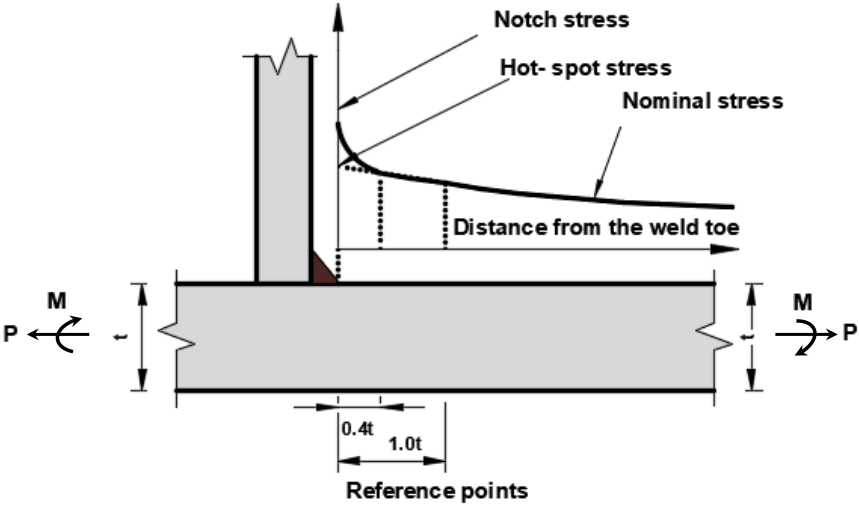
Figure 1:

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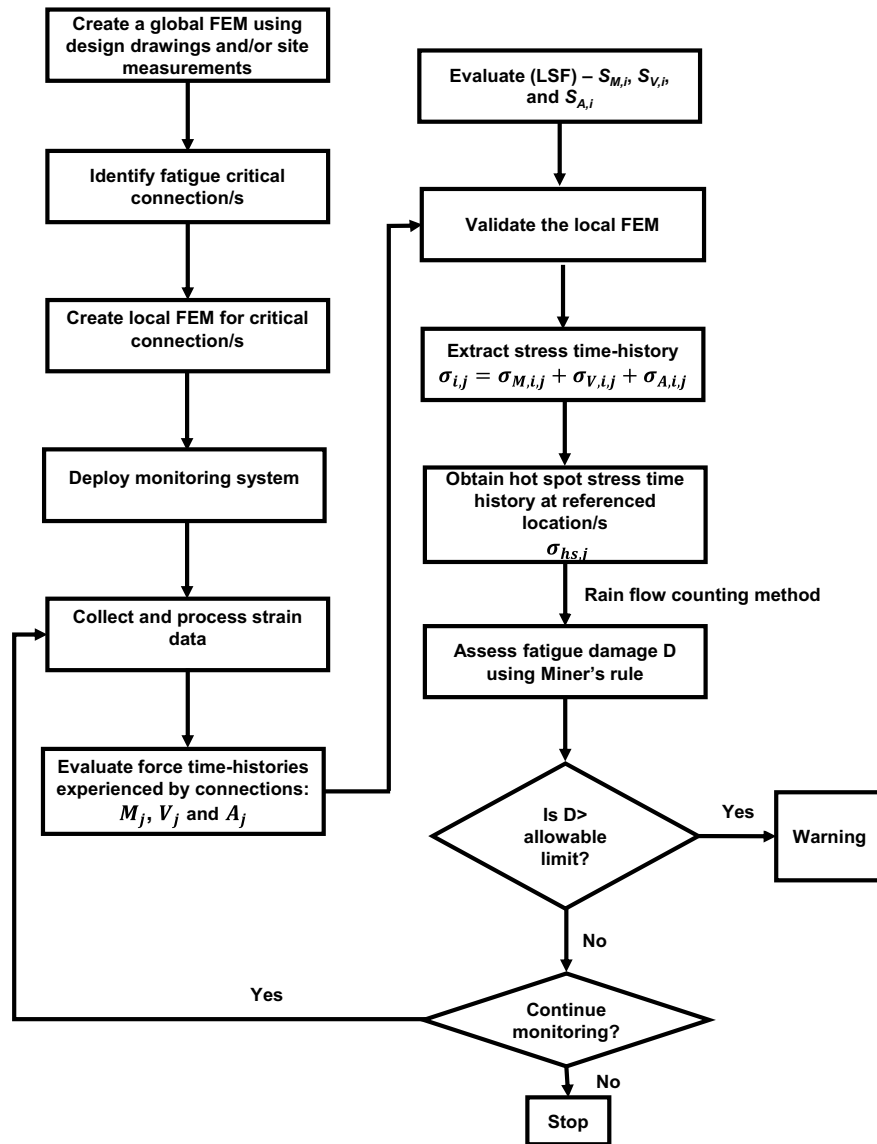
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Figure 2:

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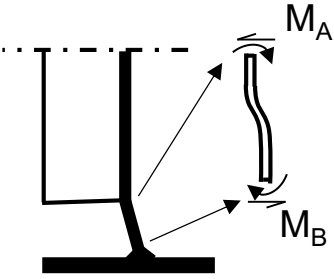
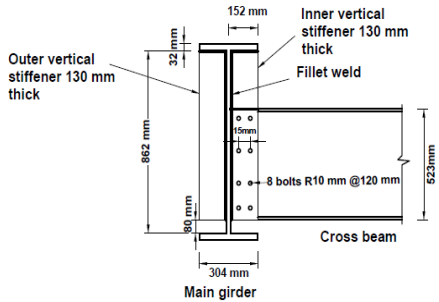
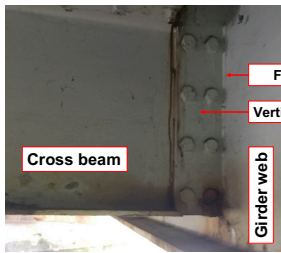
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2 **Figure 3:**



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4 **Figure 4:**

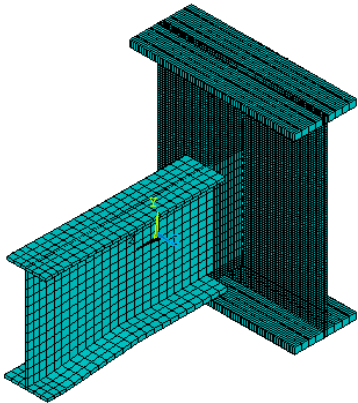


(a)

(b)

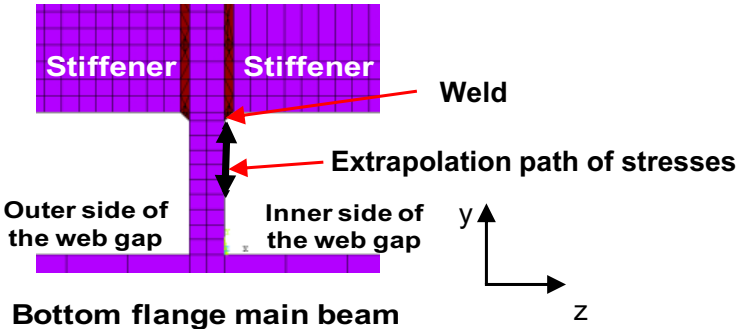
(c)

1 Figure 5:



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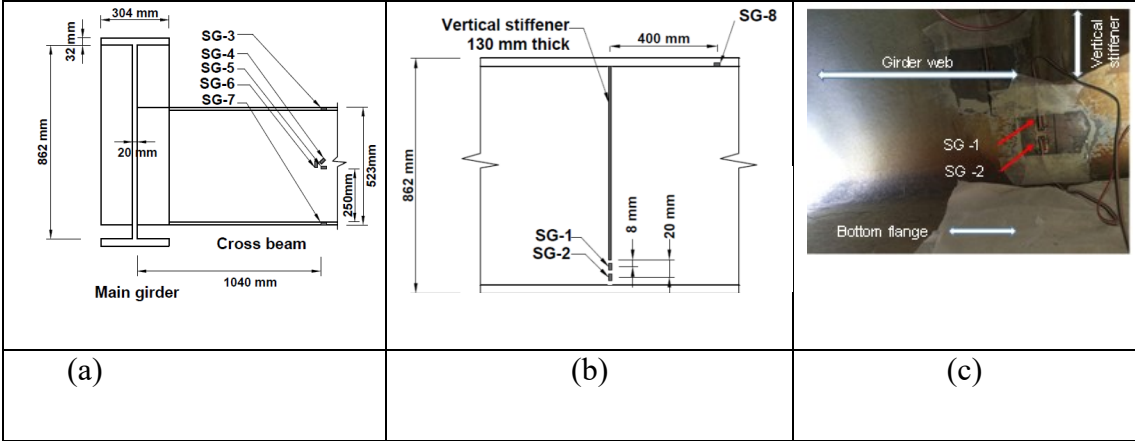
3 Figure 6:



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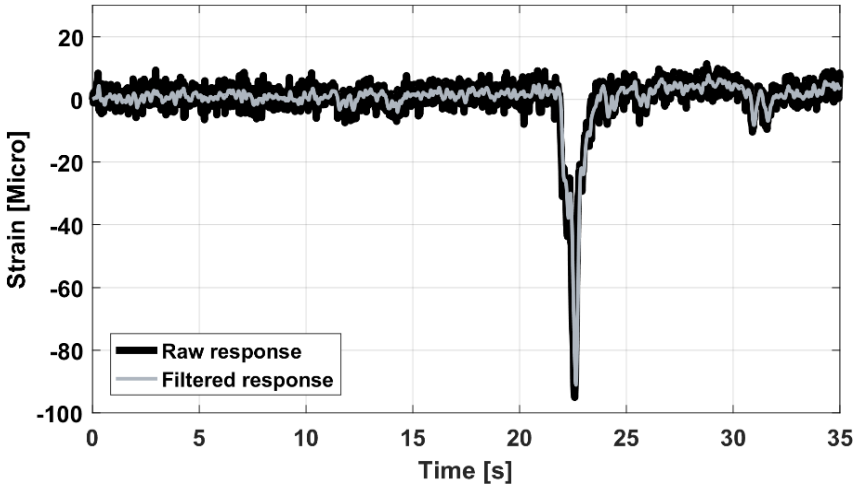
5 Figure 7:

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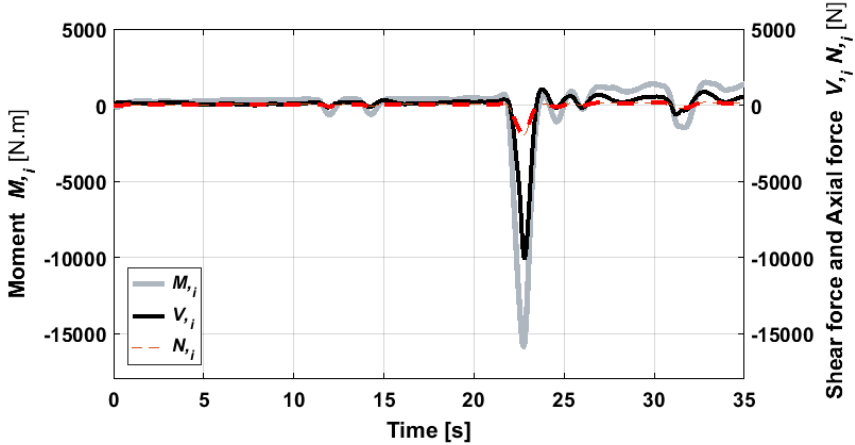
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2 **Figure 8:**



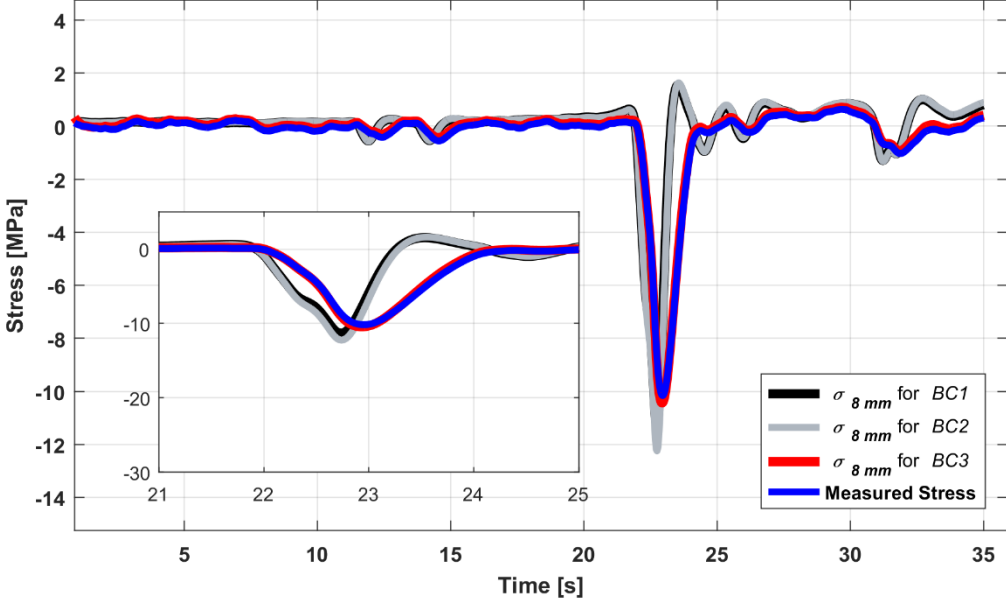
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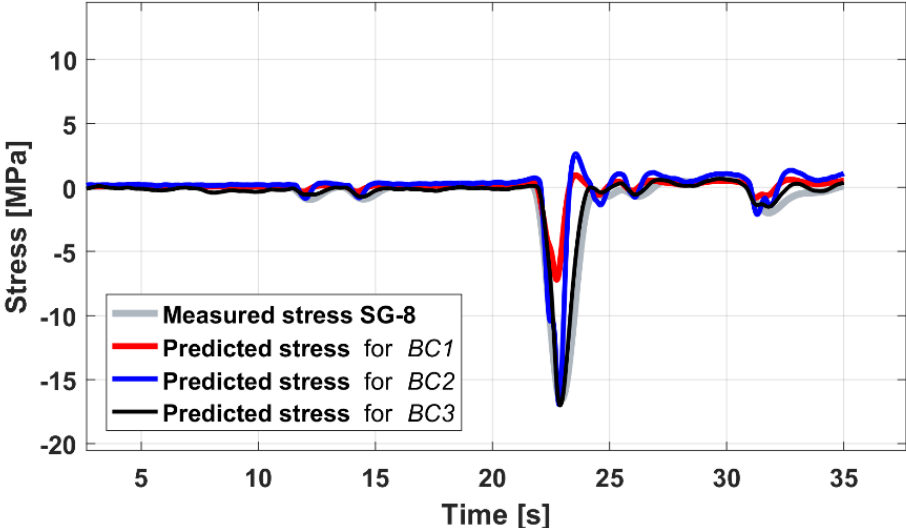
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6 **Figure 10:**



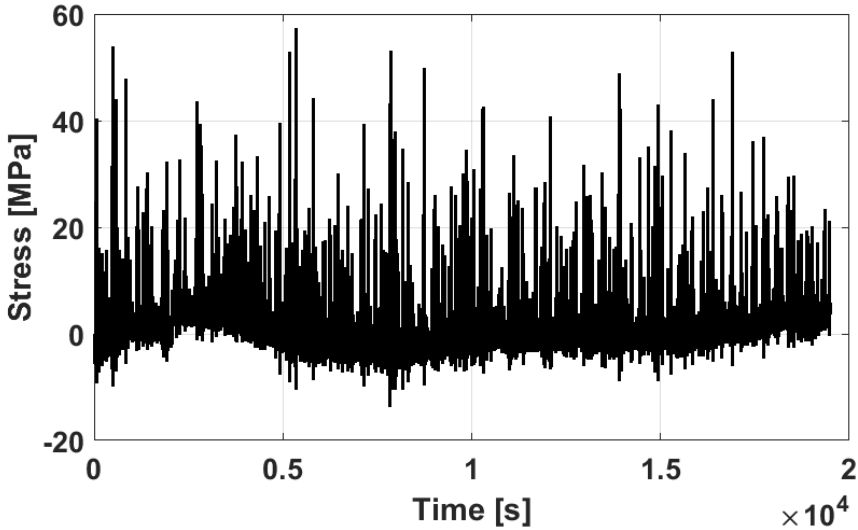
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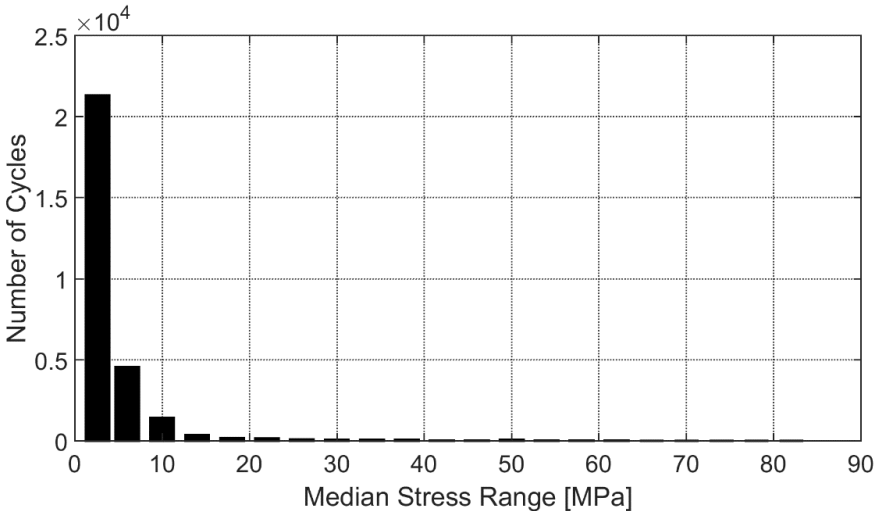
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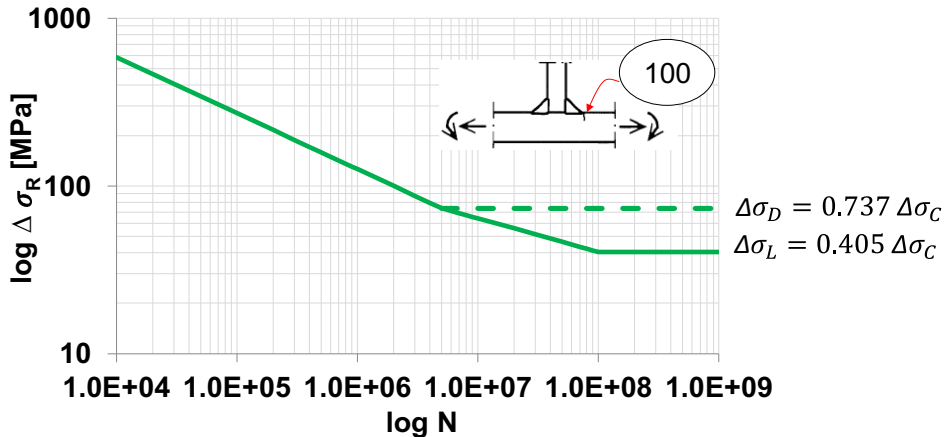
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2 **Figure 13:**



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4 **Figure 14:**



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6 **Figure 15:**