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MECHANICAL ADHESION OF SiO₂ THIN FILM ON A POLYMERIC SUBSTRATE UNDER COMPRESSIVE STRESS

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Abstract

To ensure good adhesion between a 200 nm silicon dioxide layer and a 4.5 μm thick hardcoat polymeric coating, a better understanding of mechanisms of adhesion at this interface is needed. To reach this purpose, quantification of adhesion is performed by analyzing SiO₂ buckle morphologies generated under compressive stress. This adhesion test was chosen for its representativeness of defects observed in real life. Interfacial toughness can be determined by applying Hutchinson & Suo model. This analytical model involves accurate value of elastic modulus E_f of SiO₂ thin film. Small dimensions at stake make characterization of elastic modulus challenging. First part of the study focuses on using both nano-indentation and AFM to attempt assessment of SiO₂ thin film elastic modulus. Results showed significant influence of substrate for both techniques. Impact on mechanical properties between SiO₂ thin films with different intrinsic stresses was also investigated and suggests that higher density of SiO₂ thin film leads to higher elastic modulus. Compression tests resulted in formation of straight-sided buckles that evolve into telephone cords upon unloading. Numerical simulation and Digital Image Correlation were implemented to ensure homogeneous strain of substrate and favor regular distribution of buckles. Values of energy release rates of SiO₂ / Hardcoat range from 2.7 J/m² to 8.9 J/m², depending on moduli values found on wafer or lens substrate.

Keywords: Oxide thin film, polymer substrate, mechanical properties, adhesion

1. Introduction

Ophthalmic lenses are made of plastic polymeric substrates usually coated with functional treatments composed of 5 to 15 layers, ranging from micrometers to nanometers. The first treatment consists of a primer, conferring impact resistance properties to the lens. A hardcoat with nanoparticles, is then deposited on top of this primer, bringing anti-scratch properties to the system. Both primer and hardcoat are within the micrometer scale and are deposited by wet chemical methods. Nanometric anti-reflective stacks are then evaporated onto the hardcoat by vapor deposition technology, to enhance wearers' comfort. Interface quality is essential to ensure stability and durability of ophthalmic multi-layer. In fact, insufficient adhesion between layers causes higher susceptibility to emergence of defects or delamination. Occurrence of these phenomena affects wearers' comfort and has tremendous impact on products' lifetime. Therefore, it is essential to develop a method enabling quantitative assessment of interface quality, which will ultimately enable higher product reliability.

General behavior of whole system must be fully characterized. To reduce the complexity of this characterization, focus is first placed on studying the interface between the anti-reflective stack and the hardcoat. More specifically, this paper centers around the SiO₂ thin film / hardcoat interface, which is particularly sensitive because of mechanical and dimensional contrast between both parts.

This entails studying both materials composing each layer and interface. Interface quality can be evaluated through quantification of adhesion energy. Over 300 adhesion tests are referenced in the literature by Mittal (1995). Techniques commonly used on similar structures – 200 nm thick rigid thin film on soft substrate –

include cross cut, peel, scratch, 3-point and 4-point bending, Superlayer, Lasat, bulge, tensile and compression tests. Among these numerous techniques, several methods have been implemented to study adhesion of SiO₂ thin film on polymeric substrate. Fateh (2013) performed cross-cut tests to rank adhesion of mixed metal oxide (TiO₂/SiO₂) thin films on polycarbonate substrate. Lian (1995) used a tape test to evaluate peel strength of SiO₂ (100 nm) on PMMA to be between 56 to 552 g.cm⁻¹, depending on deposition conditions and surface treatments. Tadanaga (1996) also chose peel adhesion test, but was limited by fracture of Nylon-6 substrate before interfacial delamination. Amendola (2008) performed scratch tests to determine critical load of 3.4 mN ± 0.2 mN for a 100 nm SiO₂ layer delamination from untreated polymeric AcryLite™ substrate. Letterier (1997) performed tensile tests on a 12 μm PET substrate coated with 100 nm SiO_x (x = 1.6). Depending on occurrence of thermal treatment, interfacial shear strength of SiO₂ / PET ranges from 66.8 MPa to 75.5 MPa. Litteken (2003) uses 4-point bending adhesion test to estimate energy release rate G_c of 200 nm thick SiO₂ thin film deposited on 0.25 μm polymeric PAE SiLK™ substrate. The authors measured an adhesion value of 12 J/m², which is higher than bulk fracture resistance of SiO₂ and suggests plastic deformation.

Choice of appropriate method to access adhesion is made according to compatibility with system under study, repeatability, ease of implementation, cost effectiveness and representativeness of defects observed in real life versus defects generated by mechanical tests. Chosen method should not only allow ranking of adhesion, but also give information on critical interfacial stress or even adhesion energy. Preliminary testing consisted in attempting to generate spontaneous delamination of studied SiO₂ thin film using a Zirconium Superlayer. This trial was ineffective, which attests a strong adhesion at SiO₂ / Hardcoat interface. Pull-off tests and three-point bending experiments have also been performed. Results located weakest interface at SiO₂ thin film / adhesive and SiO₂ thin film / stiffener interface respectively. This exposes challenge of finding appropriate stiffener or adhesive for strong adhesion interface. This is the reason why pull-off tests and three-point bending experiments were not favored. Considering specifications required for choice of adhesion test and preliminary testing, compression tests appear to be the most promising to characterize our structure. Compression tests of metallic thin film on polymeric substrate are indeed largely used in the literature to characterize thin film adhesion, as studied by Coupeau (1999), Cleymand (2002), Xue (2014), Cordill (2014) or Jia (2013). Few authors have applied compression adhesion tests to non-metallic thin films. Abdallah (2006) studied buckle morphologies of 400 nm thick Si₃N₄ deposited on hardcoat on top of AcryLite™ substrate. Evaluation of interfacial properties of oxide thin film deposited on polymeric substrate by compression tests have not been implemented yet and sets the framework of the present study. Buckling of SiO₂ thin film has already been proven possible in the literature. Nicu (1999) and Fang (1999) have independently generated buckling of free-standing SiO₂ micro-bridges in order to determine residual stress of thin film. Considering mechanical contrast between SiO₂ thin film and polymeric substrate, inducing interfacial delamination of system under compressive stress is theoretically feasible. Besides, this technique has the advantage of applying uniaxial stress without mechanical contact in the area under observation.

As mentioned earlier, emphasis is also placed on determining mechanical behavior of each material as mechanical properties are needed to fully understand fracture energies. Nano-indentation, largely influenced by Oliver and Pharr (1992) is widely used to determine mechanical properties of both bulk materials and thin films deposited on substrate. However, impact of substrate is inevitable for thin films of a couple of nanometers thick. To limit this effect, corrections of substrate's influence using FEA exist, as studied by Li (2009) and Hay (2011). Another approach consists in using an alternative technique with better surface detection which results in a more confined interaction volume, which is expected to lead to a lower impact of substrate. AFM is a particularly well suited technique for topography and surface roughness information. Nevertheless, several studies have used AFM, Hopf (2014) and Trtik (2012), to extract mechanical properties of sample of interest. Elastic modulus can indeed be determined using DMT contact model with slope of retract curve. As mentioned earlier, this alternative method to characterize elastic modulus has the advantage of having higher sensitiveness to surface detection compared to nanoindenter. However, limitations of mechanical characterization by AFM include sensitiveness to topography, cantilever spring constant and tip contact area uncertainties. In the present study, elastic modulus of SiO₂ thin film deposited on Si wafer and ophthalmic lens substrate are characterized by both nano-indentation and AFM Peak Force® method. Micro-compression results to quantify SiO₂ / hardcoat adhesion, are also presented.

2. *Materials and Methods*

2.1. *Multilayer system under study*

SiO₂ Type A and SiO₂ Type B are deposited by evaporation under vacuum whether on silicon wafer (280 μm thick and 2 inches diameter wafers from ITME) or on top of standard ophthalmic structure: 4.5 μm composite polymer referred to as hardcoat, on a 2 mm polycarbonate substrate. That is a total of four sample configurations, as represented in Figure 1.

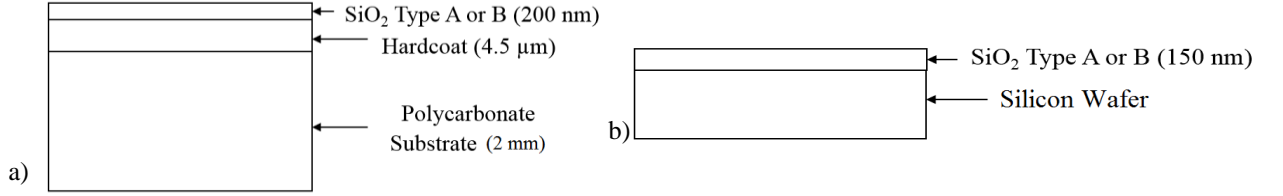


Figure 1: Samples' Configuration a) on polymeric substrate b) on Silicon Wafer substrate

Deposition of both types of SiO₂ layers is conducted under a pressure of 8.10^{-5} to 1.5×10^{-4} mbar, similarly to Roisin (2012). Difference between SiO₂ Type A and B results from supply of gas during deposition: SiO₂ Type A is deposited along with oxygen gas whereas SiO₂ Type B deposition does not involve introduction of additional gas. This difference in process was proven to effectively generate different levels of intrinsic stress within SiO₂ layers, due to increase of porosity related to gas scattering during deposition, as suggested by Scherer (1996).

2.2. Mechanical properties of SiO₂ thin film

- *Determination of intrinsic stress*

Compressive intrinsic stress of SiO₂ Type A on glass strip (60 mm x 5 cm x 150 μm) was measured to be roughly -100 MPa, compared to -400 MPa for SiO₂ Type B. Bending curvature of glass strip was measured before deposition of SiO₂ thin film on KLA Tencor P16+. Glass strip was then placed into evaporation under vacuum chamber (glass strip being only clamped on one end, the other end remaining free) to receive deposition of SiO₂ thin film. Another measurement of glass strip's bending curvature was performed 2 hours after deposition. Compressive intrinsic stresses are then calculated using Stoney's equation. Stoney (1909) uses bending curvature of glass strip before and after deposition of SiO₂ thin film:

$$\sigma_f = -E_s \frac{h_s^2}{(1-\nu_s)h_f} \frac{1}{R} \quad (1)$$

Where E_s is Young modulus of substrate, h_s and h_f are substrate and film thickness respectively, ν_s is substrate's Poisson coefficient and R is radius of curvature.

- *Nano-indentation*

Four sample configurations were characterized with a Nanoscope XP III from MTS, using a DCM measuring head and Berkovich diamond tip. A matrix of 30 indents separated by 30 μm, was created for each configuration. Before carrying out nano-indentation tests, tip area was first calibrated with a sample of fused silica. Continuous Stiffness Mode (CSM) which consists in overlapping a small amplitude oscillation at 75 Hz to a load controlled system, was used. Using Oliver and Pharr (1992) model, both elastic modulus and hardness can be extracted directly from nano-indentation curve, plotting load versus displacement into surface.

- *AFM*

Four sample configurations were characterized by AFM using Peak Force® QNM mode on a Bruker's Dimension Icon. AFM tip radius has been calibrated using fused silica of known elastic modulus. Cantilever's spring constant of 436 N/m has been given by tip provider. Cantilever with high spring constant has been chosen for its suitability with hard materials. Several Peak Force values have been tested to determine the optimal Peak Force to apply on this specific sample. Using DMT model, developed by Derjaguin et al. (1975), elastic modulus can be determined with slope of retract curve, Poisson coefficient of film ν , radius of indenter R and indentation depth δ .

$$F - F_{adh} = \frac{4}{3} \frac{E}{(1-\nu)} \sqrt{R} \delta^{3/2} \quad (2)$$

2.3. Adhesion test

2.3.1. Experimental set-up

- *Compression stage*

Configuration of SiO₂ Type A and B on lens structure was tested. Micro-compression tests were performed on a Deben stage with a 5 kN load cell, used under compression mode (Figure 2). Motor speed was set to 0.2 mm/min. Buckling phenomena were observed and recorded using an Olympus BX51W1 optical microscope with a magnification of 5. Observation area under these conditions was 1.7 x 2.3 mm². Since displacement measurement is not close to sample and test apparatus inevitably undergoes deformations, preliminary tests are needed to estimate true strain of substrate to generate buckling on sample SiO₂ B. A strain of 5.3%, below softening point (Figure 2c), was measured by video extensometer from each clamping jaw and seems to be sufficient to buckle studied SiO₂ thin film.

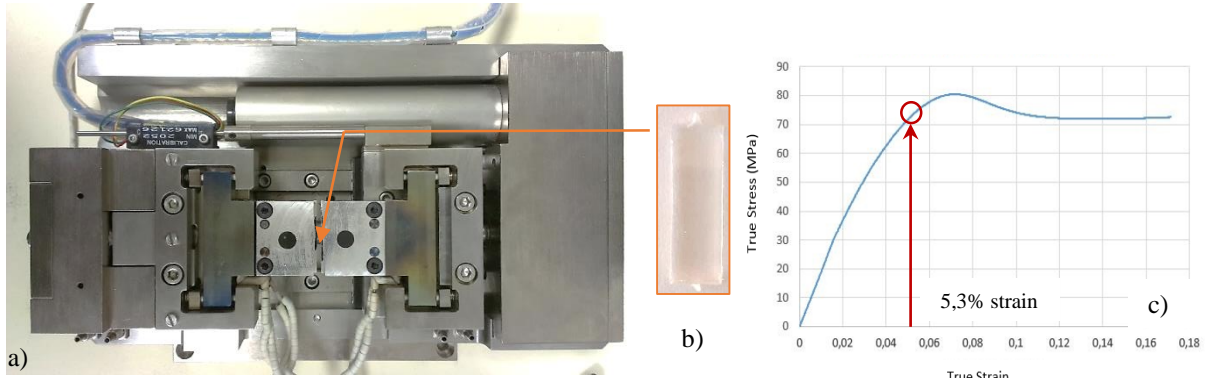


Figure 2 : Experimental set-up of compression test a) Compression stage b) Compression sample c) compression curve

- *Dimensions of sample*

Buckling of compressed beams analytical calculations were made to define geometries in order to avoid buckling of substrate. As reported by Fanchon (2016), slenderness λ is defined as followed:

$$\lambda = \frac{L}{\sqrt{\frac{I}{S}}} = \frac{L}{\sqrt{\frac{bh^3}{12}}} \quad (3)$$

With L , length of sample along the compression axis, I moment of inertia equals $\frac{bh^3}{12}$

For sample dimension of (Length: 15 mm, Width: 5 mm, Thickness: 2 mm), slenderness was calculated to be 8.7, which was then compared to critical slenderness λ_c :

$$\lambda_c = \pi \sqrt{\frac{E}{R_e}} \quad (4)$$

With E , elastic modulus of polycarbonate substrate and R_e , its yield strength. Elastic modulus of polycarbonate and yield strength was determined to be 2300 MPa and 34 MPa respectively, which gives a critical slenderness of 26. As $\lambda < \lambda_c$, buckling of substrate is not expected with these sample dimensions. Samples were then precision machined on a Charly Robot milling machine, with a 2 mm diameter milling cutter.

- *Homogeneity of deformation*

Inhomogeneity on the surface can occur due to friction phenomenon between sample and clamping jaws. To determine homogeneous area of the examined surface, a finite element model of macroscopic polycarbonate substrate was built. A 3D quasi-static mechanical model was used to simulate full sample with infinite friction with clamping jaws (the most unfavorable case). Polycarbonate substrate is modeled with an elasto-plastic law ($E = 2.3 \text{ GPa}$, $\nu = 0.37$, $\sigma_y = 34 \text{ MPa}$). Boundary displacement along \vec{y} was used as load and applied on top face while bottom face remained clamped. Part was meshed with 20-node quadratic brick with reduced integration elements (C3DR20 in Abaqus® FEM software). Results of numerical model (Figure 3) give deviation from

homogeneity of stress of less than 1 MPa within the area of interest. As stress state is sufficiently homogeneous, we could expect a regular distribution of buckles in the observed zone.

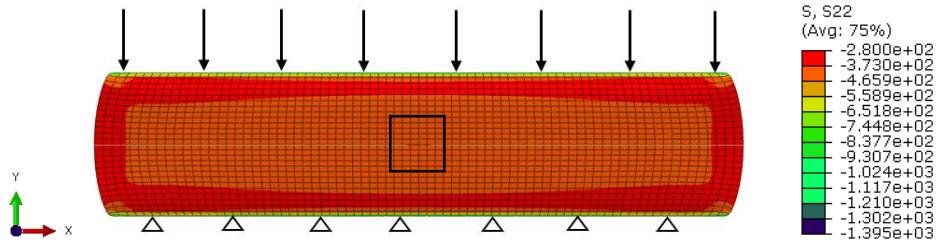


Figure 3: Stress along the compression axis (*arrows* represent direction of applied displacement, *triangles* represent clamping condition of bottom face and *rectangles* represent area of interest)

- *Determination of local strain with Digital Image Correlation*

Strain field in substrate subjected to uniaxial compressive deformation is studied by Digital Image Correlation using 2M cameras coupled with ARAMIS software. A subset size of 20 pixels with a step of 10×10 pixels is chosen. Strain field within area of interest, marked in grey in Figure 4 is 5.2 ± 0.2 % at strain levels necessary to study buckling phenomenon. Small standard deviation measured ensures strain homogeneity of 95% in the observation area.

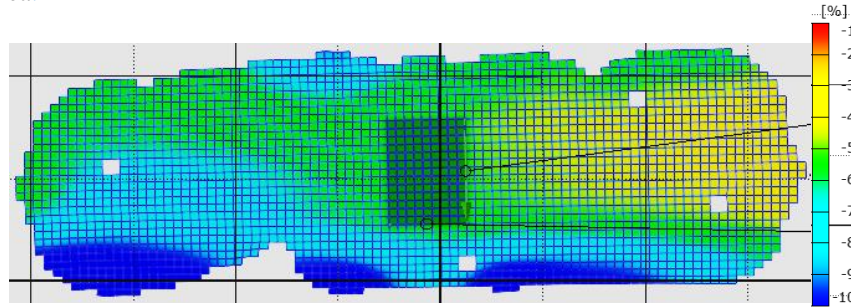


Figure 4: Digital Image Correlation measured of strain homogeneity during a compression test. Maximum variation in the observation area reaches 0.2 %

2.3.2. Analytical model for straight-sided buckles

The critical compressive biaxial stress at the onset buckling σ_{B0} is expressed as followed:

$$\sigma_{B0} = \frac{\pi^2}{12} \frac{E_f}{1-\nu^2} \left(\frac{h}{b}\right)^2 \quad (5)$$

where h is thickness of film, b is half width of buckle and E_f is plane strain modulus of film, as stated by Moon (2004). Energy release rate G along the sides of the buckle can be estimated by studying on one hand, the average energy per area in the unbuckled state U_0 and on the other hand, the average energy per area in the buckled state U , through the relation: $G = U_0 - U$. Expressed differently, the energy release rate G is the energy per area needed to separate SiO_2 thin film from substrate over the width of buckle and is defined as:

$$G = G_0 \left(1 - \frac{\sigma_{B0}}{\sigma_r}\right)^2 \quad (6)$$

with G_0 , the available energy per area stored in the unbuckled film:

$$G_0 = \frac{(1-\nu_f^2)\sigma_r^2 h}{2E_f} \quad (7)$$

with σ_r , the residual stress in the buckled plate:

$$\sigma_r = \frac{3}{4} \sigma_{B0} \left(\frac{\delta^2}{h^2} + 1\right) \quad (8)$$

with δ , height of buckle.

The total stress in the film is defined as the sum of internal residual stress due to process σ_i , and of externally applied stress $\Delta\sigma_{xx}$, generated during the experiment, as stated by Jia (2013):

$$\Delta\sigma_{xx} = \frac{E_f}{E_s} \frac{1-\nu_f\nu_s}{\nu_f^2} \sigma_{ext} \quad (9)$$

Where E_f and ν_f , E_s and ν_s are elastic modulus and Poisson's ratio of film and substrate respectively, σ_{ext} the external stress applied to substrate during testing.

3. Results and Discussion

3.1. Elastic Modulus of SiO₂ thin film

As shown in Figure 5, modulus of hardcoat is measured to be between 6 – 7 GPa by nano-indentation. It can be noted that modulus is relatively stable over a wide range of indentation depths; except for the first 10 nm, where surface detection can be particularly sensitive on a composite polymer. On the contrary, rapid evolution of modulus of SiO₂ thin film as a function of displacement into surface is observed. This confirms that substrate's influence has a considerable impact on SiO₂ thin film's modulus measurement.

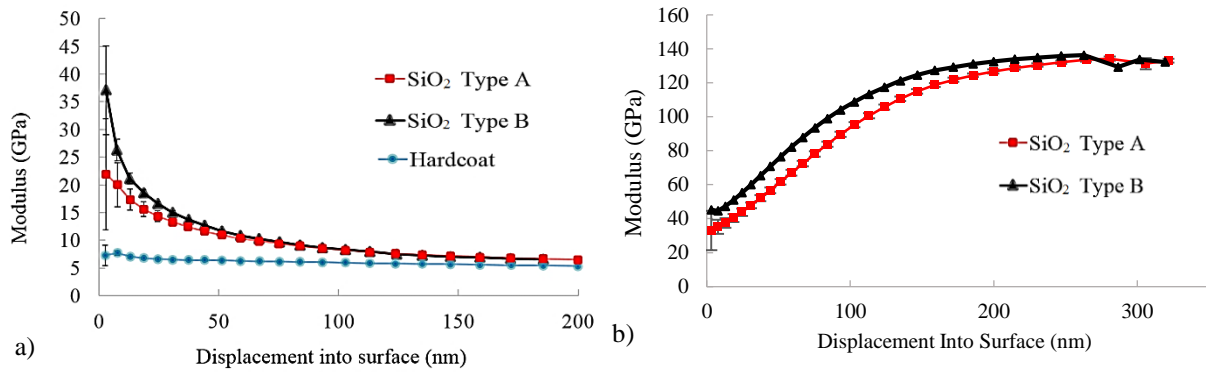


Figure 5: Moduli of SiO₂ film deposited on hardcoat on polycarbonate substrate (a) and on silicon Wafer (b)

Models to correct substrate's impact relying on FEA to precisely determine contact radius, have not been implemented as it requires mechanical properties of material to characterize. It should be noted that moduli obtained for indentation depths below 20 nm are susceptible to surface detection errors. Above 30 nm indentation depth, substrate's influence becomes significant. Moduli are therefore averaged for indentation depths between 20 and 30 nm, even though impact of substrate is already existent and acknowledged (Table 1).

Table 1: Elastic moduli of SiO₂ Type A and B deposited on Wafer and ophthalmic lens, obtained by nano-indentation

Substrate	Young Modulus (GPa) SiO ₂ A	Young Modulus (GPa) SiO ₂ B
Silicon Wafer	46 ± 2	58 ± 1
Ophthalmic lens (hardcoat on Polycarbonate)	14 ± 1	17 ± 0

On both Si wafer and lens substrates, SiO₂ Type A and B are differentiable. Modulus of SiO₂ Type B is 26% higher than modulus of SiO₂ Type A on Si wafer. The same trend is observed for lens substrate, difference being slightly lower (21%). Scherer (1996) showed that intrinsic stress is linked to *local density* – without porosity taken into account - through Si-O-Si deformation; diminution of bond angle at the O atom site, being related to increase in intrinsic stress. This could explain difference observed between SiO₂ Type A and B; change of material density leads to a higher intrinsic stress and also to the modification of mechanical properties. Even

though this range is extremely wide, we can conclude that true value SiO₂ lies somewhere between 14 GPa and 46 GPa for SiO₂ Type A and between 17 GPa and 58 GPa for SiO₂ Type B. Scherer (1996) also determined moduli of 120 nm SiO₂ thin film deposited by electron-beam evaporation on glass substrate. Values range from 35 GPa for deposition without additional gas (similar to SiO₂ Type A) to 48 GPa (similar to SiO₂ Type B) for deposition with oxygen, which is within the range of moduli measured.

Moduli of SiO₂ thin film measured on Si wafer are significantly higher (~250%) than those on lens. According to curves presented on Figure 5, elastic moduli of SiO₂ are overestimated on Si wafer and underestimated on lens substrate. Aside from contribution of substrate's influence, outgassing of lens substrate may explain lower moduli compared to those found on Si wafer. Moreover, during deposition, thermal stress could be generated on polymer substrate due to heat load of electron beam. Given that coefficient of thermal expansion of SiO₂ and polymer are significantly different, this may result in change of dimension of polymeric substrate, which might ultimately impact SiO₂ modulus value. Another explanation could come from difference of microstructure between SiO₂ layers deposited on two substrates of different nature.

Characterization of mechanical properties by AFM were performed using a Peak Force value of 1000 nN, which has been chosen to have an elastic deformation value around 2 nm, corresponding to 1% thickness of SiO₂ layer. Deformation depth was estimated to be 1.9 ± 0.3 nm. This was obtained by analyzing deformation map over the same $1 \mu\text{m}^2$ area. Modulus and its standard deviation for each sample configuration are summarized in Table 2.

Table 2: Elastic moduli of SiO₂ Type A and B deposited on Wafer and ophthalmic lens, obtained by AFM

Substrate	Young Modulus (GPa) SiO ₂ A	Young Modulus (GPa) SiO ₂ B
Silicon Wafer	48 ± 9	64 ± 14
Ophthalmic lens (hardcoat on Polycarbonate)	22 ± 3	23 ± 3

Mean values are calculated for each four conditions from 262144 (512x512) approach-retract curves. Modulus of SiO₂ Type B is 33% (48 ± 9 GPa) higher than modulus of SiO₂ Type A (64 ± 14 GPa) on Si wafer when modulus of SiO₂ Type B is 5% (22 ± 3 GPa) higher than modulus of SiO₂ Type A (23 ± 3 GPa) on polymeric lens substrate. Taking into account the high standard deviation values due to surface heterogeneities at the nanometer scale, moduli of SiO₂ A and B, could be considered similar. The higher standard deviations on moduli values could come from topographic crosslink modifying the effective contact area, resulting in erroneous calculi from DMT model. Roughness (R_a) of SiO₂ film on Si wafer was measured to be below 1 nm. On the other hand, SiO₂ moduli on silicon wafer are significantly higher than SiO₂ moduli on ophthalmic lens. This suggests that moduli of thin film are still impacted by substrate, even though deformation depth was found to be roughly 2 nm. Hypothesis can be made on AFM tip's oscillation at 1 kHz, which may affect behavior of viscoelastic hardcoat underneath SiO₂ thin film on lens structure, causing differences observed on moduli between the two substrates.

3.2. Mechanical adhesion of thin films by micro-compression

3.2.1. Phenomenological aspects

Initiation and instantaneous propagation of buckles, as well as cracking, were observed during application of compressive stress on SiO₂ Type B on lens sample. During the unloading phase, a progressive conversion from straight-sided buckles into telephone cords morphologies was observed. The occurrence of telephone cords during unloading is commonly seen, as reported by Moon (2004) and is consistent with stability diagram of unilateral buckling patterns established by Parry (2006). Concomitance of buckling and cracking (Figure 6) during testing can be explained with hypothesis on mechanisms of their initiations. It is assumed that given sufficient energy, initiation of buckling, followed by its widening, seems to be the logical sequence of events. However, in areas where adhesion is stronger, buckle enlargement seems more difficult than growth of buckle height. This is likely to generate important bending curvatures that eventually lead to cracking. Therefore, we can formulate the hypothesis that occurrence of buckle or cracking can give information on adhesion at a very local level. Ratio of buckles to cracks populations was estimated to be approximately 2 over an observation area of $1.7 \times 2.3 \text{ mm}^2$.

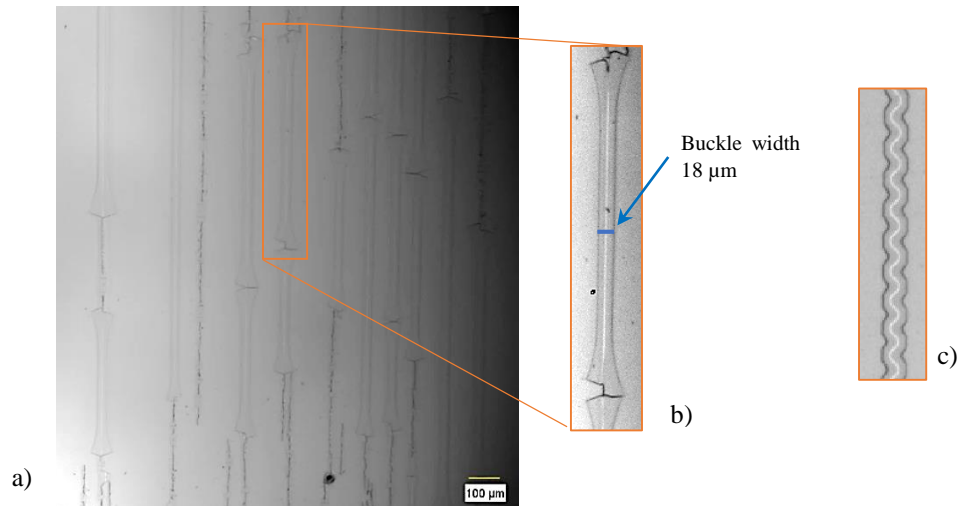


Figure 6: (a) Concomitance of buckles and cracks observed on SiO₂ Type B, (b) measurement of a buckle width, (c) example of a telephone cord associated to the unloading of sample

As for SiO₂ Type A, observation of buckle morphologies was hindered by inhomogeneous strain of substrate. Higher compressive stress was indeed needed to see emergence of buckles. At this strain level, polycarbonate substrate is well past softening point, causing strain localization and making results difficult to analyze. This behavior conforms with smaller compressive intrinsic stress being unfavorable to generation of buckles.

3.2.2. Identification of delaminated area

Identification of layer that buckles has been made on a specimen where telephone cords have been removed by tape, in order to release the interface. Step height of delaminated areas, identified with AFM, was found to be 200 nm which corresponds to thickness of SiO₂. Profile analysis of chemical composition over a delaminated area shows increased quantity of silicon and oxygen and decreased quantity of carbon on higher zones (Figure 7). These analyses strongly suggest delamination at the SiO₂ / Hardcoat interface and support validation of micro-compressive testing as an effective adhesion test to solicit interface of interest.

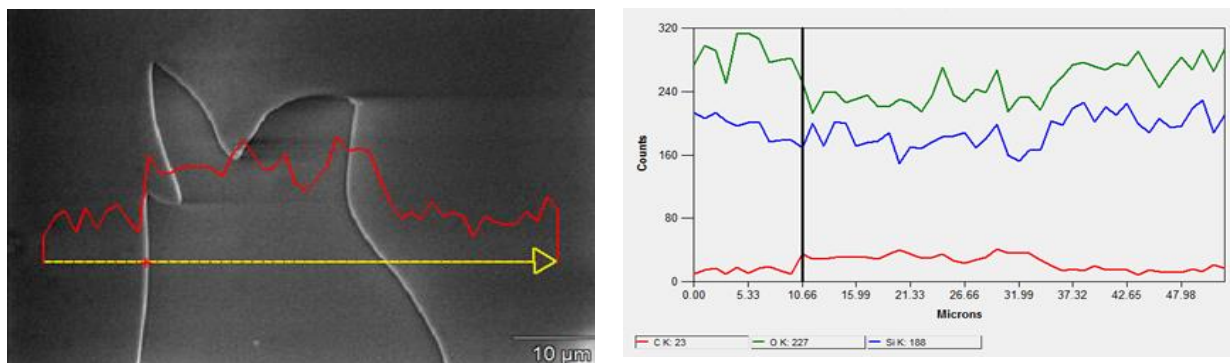


Figure 7: EDS characterization of a delaminated area (Carbon: Red curve, Oxygen: Green curve and Silicon: Blue curve)

3.2.3. Quantification of adhesion

Half-width of uncracked buckles averaged over 15 measurements is $b = 18 \pm 2$ micrometers, using ImageJ software. Height of telephone cord observed in post-mortem specimen was estimated to be 2.2 micrometers by AFM (Figure 8). The measured height after unloading is underestimate which results in a minimization of calculated energy release rate according to equation (8). This gives values of energy release rates ranging from 2.7 J/m² to 8.9 J/m². This underestimated fracture energy is in the same order of magnitude as bulk fracture resistance of SiO₂, between 5 and 8 J/m² as reported by Litteken (2003), which could suggest contribution of plastic energy. Calculated energy release rates are within the range of adhesion energies found in the literature by Xue (2014), for example, 0.8 to 1.2 J/m² for Au on PI and 6.5 J/m² for ITO on Acrylite™.

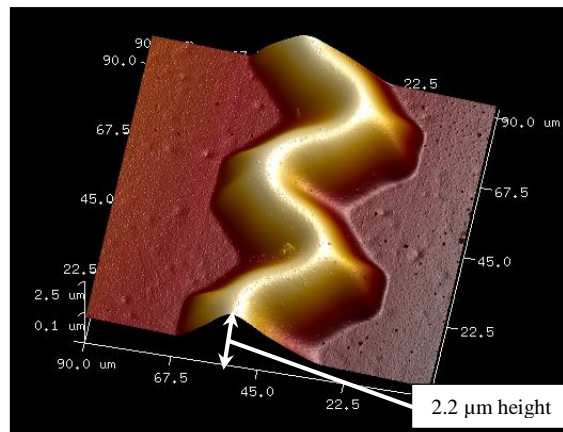


Figure 8: AFM characterization of a telephone cord obtained after unloading

Conclusion

Elastic moduli of SiO₂ Type A and B were determined by nano-indentation, giving results ranging between 46 and 58 GPa for Si wafer substrate and 14 and 17 GPa for polymeric lens substrate. Same measurements were carried out using AFM. Moduli found are 48 and 64 GPa for Si wafer substrate and 22 and 23 GPa for polymeric lens substrate. Modulus of SiO₂ Type B was found to be roughly 20% higher than SiO₂ Type A, by nano-indentation. Regarding the high standard deviation of moduli measured by AFM, no significant difference between elastic moduli of SiO₂ Type A and B was observed by AFM on both substrates. However, an important difference between moduli of SiO₂ on lens and on Si wafer was observed. This exposes unexpected influence of substrate on mechanical measurements using AFM, which has been hypothetically attributed to impact of Peak Force high frequency oscillations on viscoelastic substrates. Step height of delaminated areas measured by AFM along with EDS profiles over delaminated area obtained after micro-compressive tests, strongly suggest that delamination occurred at the interface of interest. This gives values of energy release rates ranging from 2.7 J/m² to 8.9 J/m², depending on moduli values found on wafer or lens substrate. Despite wide variation range, values are compatible with bibliographical results. Broader perspectives consist of simulating the micro-compressive adhesion test. Simulation is indeed the only method known to access information such as plastic dissipation or local strain, allowing better analysis of fracture energies.

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