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► To cite this version:

María Anguiano. Homogenization of parabolic problems with dynamical boundary conditions of reactive-diffusive type in perforated media. 2019. hal-02394935

HAL Id: hal-02394935

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Submitted on 5 Dec 2019

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Homogenization of parabolic problems with dynamical boundary conditions of reactive-diffusive type in perforated media

María ANGUIANO¹

Abstract

This paper deals with the homogenization of the reaction-diffusion equations in a domain containing periodically distributed holes of size ε , with a dynamical boundary condition of *reactive-diffusive* type, i.e., we consider the following nonlinear boundary condition on the surface of the holes

$$\nabla u_\varepsilon \cdot \nu + \varepsilon \frac{\partial u_\varepsilon}{\partial t} = \varepsilon \delta \Delta_\Gamma u_\varepsilon - \varepsilon g(u_\varepsilon),$$

where Δ_Γ denotes the Laplace-Beltrami operator on the surface of the holes, ν is the outward normal to the boundary, $\delta > 0$ plays the role of a surface diffusion coefficient and g is the nonlinear term. We generalize our previous results (see [3]) established in the case of a dynamical boundary condition of *pure-reactive* type, i.e., with $\delta = 0$. We prove the convergence of the homogenization process to a nonlinear reaction-diffusion equation whose diffusion matrix takes into account the reactive-diffusive condition on the surface of the holes.

AMS classification numbers: 35B27, 35K57

Keywords: Homogenization, perforated media, reaction-diffusion systems, dynamical boundary conditions, surface diffusion

1 Introduction and setting of the problem

In a recent article (see [3]) we addressed the problem of the homogenization of the reaction-diffusion equations with a dynamical boundary condition of *pure-reactive* type in a domain perforated with holes. The present article is devoted to the generalization of that previous study to the case of a dynamical boundary condition of *reactive-diffusive* type, i.e., we add to the dynamical boundary condition a Laplace-Beltrami correction term. The interest of such a correction for the modeling of parabolic problems has been pointed out in Goldstein [9]. In particular, a dynamical boundary condition of *reactive-diffusive* type accounts for (see [9, Section 3]) a heat source on the boundary that can depend on the heat flow along the boundary, the heat flux across the boundary and the temperature at the boundary. Let us introduce the model we will be involved with in this article.

The geometrical setting. Let Ω be a bounded connected open set in \mathbb{R}^N ($N \geq 2$), with smooth enough boundary $\partial\Omega$. Let $Y = [0, 1]^N$ be the representative cell in \mathbb{R}^N and F an open subset of Y with smooth enough boundary ∂F , such that $\bar{F} \subset Y$. We denote $Y^* = Y \setminus \bar{F}$.

For $k \in \mathbb{Z}^N$ and $\varepsilon \in (0, 1]$, each cell $Y_{k,\varepsilon} = \varepsilon k + \varepsilon Y$ is similar to the unit cell Y rescaled to size ε and $F_{k,\varepsilon} = \varepsilon k + \varepsilon F$ is similar to F rescaled to size ε . We denote $Y_{k,\varepsilon}^* = Y_{k,\varepsilon} \setminus \bar{F}_{k,\varepsilon}$. We denote by F_ε the set of all the holes contained in Ω , i.e. $F_\varepsilon = \cup_{k \in K} \{F_{k,\varepsilon} : \bar{F}_{k,\varepsilon} \subset \Omega\}$, where $K := \{k \in \mathbb{Z}^N : Y_{k,\varepsilon} \cap \Omega \neq \emptyset\}$.

Let $\Omega_\varepsilon = \Omega \setminus \bar{F}_\varepsilon$. By this construction, Ω_ε is a periodically perforated domain with holes of the same size as the period. Remark that the holes do not intersect the boundary $\partial\Omega$. Let $\partial F_\varepsilon = \cup_{k \in K} \{\partial F_{k,\varepsilon} : \bar{F}_{k,\varepsilon} \subset \Omega\}$. So

$$\partial\Omega_\varepsilon = \partial\Omega \cup \partial F_\varepsilon.$$

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Position of the problem. The prototype of the parabolic initial-boundary value problems that we consider in this article is

$$\left\{ \begin{array}{ll} \frac{\partial u_\varepsilon}{\partial t} - \Delta u_\varepsilon + \kappa u_\varepsilon = 0 & \text{in } \Omega_\varepsilon \times (0, T), \\ \nabla u_\varepsilon \cdot \nu + \varepsilon \frac{\partial u_\varepsilon}{\partial t} = \varepsilon \delta \Delta_\Gamma u_\varepsilon - \varepsilon g(u_\varepsilon) & \text{on } \partial F_\varepsilon \times (0, T), \\ u_\varepsilon = 0, & \text{on } \partial \Omega \times (0, T), \\ u_\varepsilon(x, 0) = u_\varepsilon^0(x), & \text{for } x \in \Omega_\varepsilon, \\ u_\varepsilon(x, 0) = \psi_\varepsilon^0(x), & \text{for } x \in \partial F_\varepsilon, \end{array} \right. \quad (1)$$

where $u_\varepsilon = u_\varepsilon(x, t)$, $x \in \Omega_\varepsilon$, $t \in (0, T)$ and $T > 0$. The first equation states the law of standard diffusion in Ω_ε , $\Delta = \Delta_x$ denotes the Laplacian operator with respect to the space variable and $\kappa > 0$ is a given constant. The boundary equation (1)₂ is multiplied by ε to compensate the growth of the surface by shrinking ε , where the value of u_ε is assumed to be the trace of the function u_ε defined for $x \in \Omega_\varepsilon$, Δ_Γ denotes the Laplace-Beltrami operator on ∂F_ε , ν denotes the outward normal to ∂F_ε , and $\delta > 0$ is a given constant. The term $\nabla u_\varepsilon \cdot \nu$ represents the interaction domain-boundary, while $\delta \Delta_\Gamma$ stands for a boundary diffusion. We assume that the function $g \in C(\mathbb{R})$ is given, and satisfies that there exists the exponent q such that

$$2 \leq q < +\infty, \text{ if } N = 2 \quad \text{and} \quad 2 \leq q \leq \frac{2N}{N-2}, \text{ if } N > 2, \quad (2)$$

and constants $\alpha_1 > 0$, $\alpha_2 > 0$, $\beta > 0$, and $l > 0$, such that

$$\alpha_1 |s|^q - \beta \leq g(s)s \leq \alpha_2 |s|^q + \beta, \quad \text{for all } s \in \mathbb{R}, \quad (3)$$

$$(g(s) - g(r))(s - r) \geq -l(s - r)^2, \quad \text{for all } s, r \in \mathbb{R}, \quad (4)$$

and

$$(g(s) - g(r))(s - r) \leq l(s - r)^2, \quad \text{for all } s, r \in \mathbb{R}. \quad (5)$$

Finally, we also assume that

$$u_\varepsilon^0 \in L^2(\Omega), \quad \psi_\varepsilon^0 \in L^2(\partial F_\varepsilon), \quad (6)$$

are given.

Depending of δ , two classes of boundary conditions are modeled by (1). For $\delta > 0$, we have boundary conditions of *reactive-diffusive* type, and for $\delta = 0$ the boundary conditions are *purely reactive*. In [3], we consider the homogenization of the problem (1) with $\delta = 0$ and we obtain rigorously a nonlinear parabolic problem with zero Dirichlet boundary condition and with extra-terms coming from the influence of the dynamical boundary conditions as the homogenized model. Though the results of the present article are similar to those of [3], the generalization of their proof is not trivial. Some new technical results are required in order to carry out the machinery of [3]. Due to the presence of Laplace-Beltrami operator in the boundary condition, the variational formulation of the reaction-diffusion equation is different that in [3]. We have to work in the space

$$W_\delta = \{(v, \gamma_0(v)) \in H^1(\Omega_\varepsilon) \times H^1(\partial F_\varepsilon)\}, \quad \delta > 0, \quad (7)$$

where γ_0 denotes the trace operator $v \mapsto v|_{\partial \Omega_\varepsilon}$, and where we define by $H^1(\partial F_\varepsilon)$ the completion of $C^1(\partial F_\varepsilon)$ with respect to the induced norm by the inner product

$$((\phi, \psi))_{\partial F_\varepsilon} := \int_{\partial F_\varepsilon} \phi \psi \, d\sigma + \delta \int_{\partial F_\varepsilon} \nabla_\Gamma \phi \cdot \nabla_\Gamma \psi \, d\sigma, \quad \forall \phi, \psi \in C^1(\partial F_\varepsilon),$$

where ∇_Γ denotes the tangential gradient on ∂F_ε and $d\sigma$ denotes the natural volume element on ∂F_ε . The estimates of [3] did not allow to cover this case and new estimates are needed to deal with problem (1). In order to prove estimates in H^2 -norm, we have to combine estimates for general elliptic boundary value problems with interpolation properties of Sobolev spaces (see Lemma 4.2). On the other hand, in order to pass to the limit, as $\varepsilon \rightarrow 0$, for the term which involve the tangential gradient ∇_Γ we make use of a convergence result based on a technique introduced by Vanninathan [16] for the Steklov problem which transforms surface integrals into

volume integrals. This convergence result can be used taking into account the estimates in H^2 -norm. Several technical results are merely quoted, and we refer [3] for their proof. We present here a new result concerning the local problem, which involves the orthogonal projection (denoted by P_Γ), the tangential gradient (denoted by ∇_Γ) and the tangential divergence (denoted by div_Γ) on the boundary of the unit cell. More precisely, using the so-called energy method introduced by Tartar [15] and considered by many authors (see, for instance, Cioranescu and Donato [5]), we prove the following:

Theorem 1.1 (Main Theorem). *Under the assumptions (2)–(6), assume that $g \in C^1(\mathbb{R})$. Let $(u_\varepsilon, \psi_\varepsilon)$ be the unique solution of the problem (1), where $\psi_\varepsilon(t) = \gamma_0(u_\varepsilon(t))$ a.e. $t \in (0, T]$. Then, as $\varepsilon \rightarrow 0$, we have*

$$\tilde{u}_\varepsilon(t) \rightarrow u(t) \quad \text{strongly in } L^2(\Omega), \quad \forall t \in [0, T],$$

where $\tilde{\cdot}$ denotes the extension to $\Omega \times (0, T)$ and u is the unique solution of the following problem

$$\begin{cases} \left(\frac{|Y^*|}{|Y|} + \frac{|\partial F|}{|Y|} \right) \frac{\partial u}{\partial t} - \text{div}(Q\nabla u) + \frac{|Y^*|}{|Y|} \kappa u + \frac{|\partial F|}{|Y|} g(u) = 0, & \text{in } \Omega \times (0, T), \\ u(x, 0) = u_0(x), & \text{for } x \in \Omega, \\ u = 0, & \text{on } \partial\Omega \times (0, T). \end{cases} \quad (8)$$

The homogenized matrix $Q = ((q_{i,j}))$, $1 \leq i, j \leq N$, which is symmetric and positive-definite, is given by

$$q_{i,j} = \frac{1}{|Y|} \left(\int_{Y^*} (e_i + \nabla_y w_i) \cdot (e_j + \nabla_y w_j) dy + \delta \int_{\partial F} (P_\Gamma e_i + \nabla_\Gamma w_i) \cdot (P_\Gamma e_j + \nabla_\Gamma w_j) d\sigma(y) \right), \quad (9)$$

where w_i , $1 \leq i \leq N$, is the unique solution of the cell problem

$$\begin{cases} -\text{div}_y (e_i + \nabla_y w_i) = 0, & \text{in } Y^*, \\ (e_i + \nabla_y w_i) \cdot \nu = \delta \text{div}_\Gamma (P_\Gamma e_i + \nabla_\Gamma w_i), & \text{on } \partial F, \\ w_i \text{ is } Y\text{-periodic}, \end{cases} \quad (10)$$

where e_i is the i element of the canonical basis in \mathbb{R}^N .

Remark 1.2. *Note that in the case $\delta = 0$ (i.e., in absence a surface diffusion coefficient), the homogenized equation (8) is exactly the equation obtained in [3].*

The homogenization of problems which involve the Laplace-Beltrami operator has been considered in recently articles, but using techniques different from those used in the present article. In particular, in [10], Graf and Peter extend the convergence results for the boundary periodic unfolding operator to gradients defined on manifolds. These results are then used to homogenize a system of five coupled reaction-diffusion equations, three of which are defined on a manifold, including diffusion on a biological membrane, modeled as a Riemannian manifold, which is described by the Laplace-Beltrami operator. In [1], Amar and Gianni state a new property of the unfolding operator regarding the unfolded tangential gradient. This property is used to homogenize a model for the heat conduction in two disjoint conductive phases with a linear dynamical boundary condition which involves the Laplace-Beltrami operator in the separating interface. An error estimate for this model, under extra regularity assumptions on the data, can be found in Amar and Gianni [2]. More recently, in [8], Gahn derives some general two-scale compactness results for coupled bulk-surface problems and applies these results to an elliptic problem with a non dynamical boundary condition, which involves the Laplace-Beltrami operator, in a multi-component domain.

The article is organized as follows. In Section 2, we introduce suitable functions spaces for our considerations. Especially, we consider some fundamentals from differential geometry as the tangential gradient and the tangential divergence. To prove the main result, in Section 3 we prove the existence and uniqueness of solution of (1), *a priori* estimates are established in Section 4 and some compactness results are proved in Section 5. Finally, the proof of Theorem 1.1 is established in Section 6.

2 Functional setting

Notation. We denote by $(\cdot, \cdot)_{\Omega_\varepsilon}$ (respectively, $(\cdot, \cdot)_{\partial F_\varepsilon}$) the inner product in $L^2(\Omega_\varepsilon)$ (respectively, in $L^2(\partial F_\varepsilon)$), and by $|\cdot|_{\Omega_\varepsilon}$ (respectively, $|\cdot|_{\partial F_\varepsilon}$) the associated norm. We also denote $(\cdot, \cdot)_{\Omega_\varepsilon}^N$ the inner product in $(L^2(\Omega_\varepsilon))^N$.

If $r \neq 2$, we will also denote $(\cdot, \cdot)_{\Omega_\varepsilon}$ (respectively, $(\cdot, \cdot)_{\partial F_\varepsilon}$) the duality product between $L^{r'}(\Omega_\varepsilon)$ and $L^r(\Omega_\varepsilon)$ (respectively, the duality product between $L^{r'}(\partial F_\varepsilon)$ and $L^r(\partial F_\varepsilon)$). We will denote $|\cdot|_{r, \Omega_\varepsilon}$ (respectively $|\cdot|_{r, \partial F_\varepsilon}$) the norm in $L^r(\Omega_\varepsilon)$ (respectively in $L^r(\partial F_\varepsilon)$).

By $\|\cdot\|_{\Omega_\varepsilon}$ we denote the norm in $H^1(\Omega_\varepsilon)$, which is associated to the inner product

$$((u, v))_{\Omega_\varepsilon} := (u, v)_{\Omega_\varepsilon} + (\nabla u, \nabla v)_{\Omega_\varepsilon}, \quad \forall u, v \in H^1(\Omega_\varepsilon),$$

and by $\|\cdot\|_{\Omega_\varepsilon, T}$ we denote the norm in $L^2(0, T; H^1(\Omega_\varepsilon))$. By $\|\cdot\|_\Omega$ we denote the norm in $H^1(\Omega)$ and by $|\cdot|_{r, \Omega, T}$, we denote the norm in $L^r(0, T; L^r(\Omega))$.

We denote by γ_0 the trace operator $u \mapsto u|_{\partial\Omega_\varepsilon}$, which belongs to $\mathcal{L}(H^1(\Omega_\varepsilon), H^{1/2}(\partial\Omega_\varepsilon))$.

We introduce, for any $s > 1$, the space $H^s(\Omega_\varepsilon)$, which is naturally embedded in $H^1(\Omega_\varepsilon)$, and it is a Hilbert space equipped with the norm inherited, which we denote by $\|\cdot\|_{H^s(\Omega_\varepsilon)}$.

Moreover, we denote by $H_{\partial\Omega}^r(\Omega_\varepsilon)$ and $H_{\partial\Omega}^r(\partial\Omega_\varepsilon)$, for $r \geq 0$, the standard Sobolev spaces which are closed subspaces of $H^r(\Omega_\varepsilon)$ and $H^r(\partial\Omega_\varepsilon)$, respectively, and the subscript $\partial\Omega$ means that, respectively, traces or functions in $\partial\Omega_\varepsilon$, vanish on this part of the boundary of Ω_ε , i.e.

$$H_{\partial\Omega}^r(\Omega_\varepsilon) = \{v \in H^r(\Omega_\varepsilon) : \gamma_0(v) = 0 \text{ on } \partial\Omega\},$$

and

$$H_{\partial\Omega}^r(\partial\Omega_\varepsilon) = \{v \in H^r(\partial\Omega_\varepsilon) : v = 0 \text{ on } \partial\Omega\}.$$

Analogously, for $r \geq 2$, we denote

$$L_{\partial\Omega}^r(\partial\Omega_\varepsilon) := \{v \in L^r(\partial\Omega_\varepsilon) : v = 0 \text{ on } \partial\Omega\}.$$

Let us notice that, in fact, we can consider the given ψ_ε^0 as an element of $L_{\partial\Omega}^2(\partial\Omega_\varepsilon)$.

Let us consider the space

$$H_q := L^q(\Omega_\varepsilon) \times L_{\partial\Omega}^q(\partial\Omega_\varepsilon), \quad \forall q \geq 2,$$

with the natural inner product $((v, \phi), (w, \varphi))_{H_q} = (v, w)_{\Omega_\varepsilon} + \varepsilon(\phi, \varphi)_{\partial F_\varepsilon}$, which in particular induces the norm $\|(\cdot, \cdot)\|_{H_q}$ given by

$$\|(v, \phi)\|_{H_q}^q = |v|_{\Omega_\varepsilon}^q + \varepsilon|\phi|_{\partial F_\varepsilon}^q, \quad (v, \phi) \in H_q.$$

For the sake of clarity, we shall omit to write explicitly the index q if $q = 2$, so we denote by H the Hilbert space

$$H := L^2(\Omega_\varepsilon) \times L_{\partial\Omega}^2(\partial\Omega_\varepsilon).$$

For functions $u \in H_{\partial\Omega}^1(\Omega_\varepsilon)$ which satisfy $\Delta u \in L_{\partial\Omega}^2(\Omega_\varepsilon)$, we have

$$\int_{\Omega_\varepsilon} \Delta u v dx = - \int_{\Omega_\varepsilon} \nabla u \cdot \nabla v dx + \int_{\partial F_\varepsilon} \nabla u \cdot \nu v d\sigma(x), \quad \forall v \in H_{\partial\Omega}^1(\Omega_\varepsilon).$$

Tangential gradient and Laplace-Beltrami operator. We recall here, for the reader's convenience, some well-known facts on the tangential gradient ∇_Γ and the Laplace-Beltrami operator Δ_Γ . We refer to Sokolowski and Zolesio [13] for more details and proofs.

Let S a smooth surface with normal unit vector ν . For every $v \in L^2(S)$, we can define an element $P_\Gamma v \in L^2(S)$ such that $v \cdot \nu = 0$ a.e. on S , where $P_\Gamma(y)$ for $y \in S$ is the orthogonal projection on the tangent space at $y \in S$, i.e., it holds that

$$P_\Gamma(y)v(y) = v(y) - v(y) \cdot \nu(y)\nu(y) \quad \text{for a.e. } y \in S.$$

Let $\phi \in C^1(S)$, there exist a tubular neighborhood U of S and an extension $\tilde{\phi} \in C^1(U)$ of ϕ . We define the tangential gradient of ϕ on S by

$$\nabla_{\Gamma}\phi := P_{\Gamma}\nabla\tilde{\phi} = \nabla\tilde{\phi} - \nabla\tilde{\phi} \cdot \nu\nu \quad \text{on } S.$$

We emphasize that this definition is independent of the chosen extension of ϕ .

Let $\Phi \in C^1(S)^N$, then there exists an extension $\tilde{\Phi} \in C^1(U)^N$ (U as above a suitable neighborhood of S) and we define the tangential divergence of Φ on S by

$$\operatorname{div}_{\Gamma}\Phi := \nabla_{\Gamma} \cdot \Phi := \nabla \cdot \tilde{\Phi} - D\tilde{\Phi}\nu \cdot \nu \quad \text{on } S,$$

where $D\tilde{\Phi}$ is the Jacobi-matrix of $\tilde{\Phi}$.

Now, we consider the surface ∂F_{ε} . First, an equivalent definition of the Sobolev space $H^1(\partial F_{\varepsilon})$ on ∂F_{ε} is given. We introduce the inner product

$$((\phi, \psi))_{\partial F_{\varepsilon}} := (\phi, \psi)_{\partial F_{\varepsilon}} + \delta(\nabla_{\Gamma}\phi, \nabla_{\Gamma}\psi)_{\partial F_{\varepsilon}}, \quad \forall \phi, \psi \in C^1(\partial F_{\varepsilon}), \quad \delta \geq 0,$$

and denote by $\|\cdot\|_{\partial F_{\varepsilon}}$ the induced norm. The Sobolev space $H^1(\partial F_{\varepsilon})$ is the closure of the space $C^1(\partial F_{\varepsilon})$ with respect to the norm induced by the inner product. Therefore, the space $C^1(\partial F_{\varepsilon})$ is dense by definition in the space $H^1(\partial F_{\varepsilon})$. An equivalent definition of $H^1(\partial F_{\varepsilon})$ can be given via local coordinates or distributional meaning, see, for instance, Strichartz [14].

By definition, for every $\phi \in H^1(\partial F_{\varepsilon})$ there exists $\nabla_{\Gamma}\phi \in L^2(\partial F_{\varepsilon})$ with $\nabla_{\Gamma}\phi \cdot \nu = 0$ a.e. on ∂F_{ε} , the tangential gradient in the distributional sense.

We introduce, for any $s > 1$, the space $H^s(\partial F_{\varepsilon})$, which is naturally embedded in $H^1(\partial F_{\varepsilon})$, equipped with the norm inherited, which we denote by $\|\cdot\|_{H^s(\partial F_{\varepsilon})}$.

For all $\psi \in H^1(\partial F_{\varepsilon})$ and $v \in C^1(\partial F_{\varepsilon})$ such that $v \cdot \nu = 0$ a.e. on ∂F_{ε} , we have the Stokes formula (see Proposition 2.58 in [13])

$$\int_{\partial F_{\varepsilon}} \nabla_{\Gamma}\psi \cdot v \, d\sigma = - \int_{\partial F_{\varepsilon}} \psi \operatorname{div}_{\Gamma} v \, d\sigma. \quad (11)$$

Let $h \in H^2(\partial F_{\varepsilon})$, then we have $\nabla_{\Gamma}h \in H^1(\partial F_{\varepsilon})$ such that $\nabla_{\Gamma}h \cdot \nu = 0$ a.e. on ∂F_{ε} . The Laplace-Beltrami operator Δ_{Γ} on ∂F_{ε} is defined as follows

$$\Delta_{\Gamma}h = \operatorname{div}_{\Gamma}(\nabla_{\Gamma}h) \quad \forall h \in H^2(\partial F_{\varepsilon}).$$

Hence $\Delta_{\Gamma}h \in L^2(\partial F_{\varepsilon})$, and from (11) it follows that the element $\Delta_{\Gamma}h \in L^2(\partial F_{\varepsilon})$ is uniquely determined by the integral identity

$$\int_{\partial F_{\varepsilon}} \Delta_{\Gamma}h \psi \, d\sigma = - \int_{\partial F_{\varepsilon}} \nabla_{\Gamma}h \cdot \nabla\psi \, d\sigma \quad \forall \psi \in H^1(\partial F_{\varepsilon}). \quad (12)$$

If $\psi \in H^1(\partial F_{\varepsilon})$, then there exists (see [13, Chapter 2, Section 2.20]) an element $\vartheta \in H^{3/2}(\Omega_{\varepsilon})$, the extension of ψ , and

$$\vartheta|_{\partial F_{\varepsilon}} = \psi, \quad \text{furthermore} \quad \nabla\vartheta \cdot \nu = 0 \quad \text{on } \partial F_{\varepsilon}. \quad (13)$$

Therefore $\nabla\vartheta = \nabla_{\Gamma}\psi$ on ∂F_{ε} . It should be noted that on the right-hand side of (12) there is the scalar product of vector fields $\nabla_{\Gamma}h$ and $\nabla_{\Gamma}\psi$ tangent to ∂F_{ε} .

On the other hand, if ψ is a smooth function defined in an open neighbourhood of ∂F_{ε} in Ω , then (see [13, Chapter 2, Section 2.20])

$$\nabla_{\Gamma}h \cdot (\nabla\psi|_{\partial F_{\varepsilon}}) = \nabla_{\Gamma}h \cdot \nabla_{\Gamma}\psi$$

because of

$$(\nabla\psi \cdot \nu\nu) \cdot \nabla_{\Gamma}h = 0.$$

Hence, if ψ is the restriction to ∂F_ε of a given function ψ defined in Ω , then

$$\int_{\partial F_\varepsilon} \Delta_\Gamma h \psi \, d\sigma = - \int_{\partial F_\varepsilon} \nabla_\Gamma h \cdot \nabla \psi \, d\sigma \quad \forall \psi \in H^2(\Omega). \quad (14)$$

The space W_δ . We now introduce, as anticipated in the introduction, the space W_δ given in (7). For all $\delta \geq 0$, we define

$$V_{\partial\Omega}^\delta = \{v \in H^1(\Omega_\varepsilon) : v|_{\partial F_\varepsilon} \in H^1(\partial F_\varepsilon), v = 0 \text{ on } \partial\Omega\},$$

with the inner product

$$((u, v))_{V_{\partial\Omega}^\delta} := ((u, v))_{\Omega_\varepsilon} + \varepsilon((u|_{\partial F_\varepsilon}, v|_{\partial F_\varepsilon}))_{\partial F_\varepsilon},$$

which induces the norm

$$\|u\|_{V_{\partial\Omega}^\delta}^2 := \int_{\Omega_\varepsilon} (|u(x)|^2 + |\nabla u(x)|^2) \, dx + \varepsilon \int_{\partial F_\varepsilon} (|u(x)|^2 + \delta |\nabla_\Gamma u(x)|^2) \, d\sigma(x).$$

Note that for any $f \in V_{\partial\Omega}^\delta$, we have $f \in H_{\partial\Omega}^1(\Omega_\varepsilon)$ so that $f|_{\partial F_\varepsilon}$ makes sense in the trace sense. The space $V_{\partial\Omega}^\delta$ is topologically isomorphic to $H^1(\Omega_\varepsilon) \times H_{\partial\Omega}^1(\partial\Omega_\varepsilon)$ if $\delta > 0$, and $V_{\partial\Omega}^0 = H_{\partial\Omega}^1(\Omega_\varepsilon)$.

For all $\delta \geq 0$, we define the linear space

$$W_\delta := \{(v, \gamma_0(v)) \in V_{\partial\Omega}^\delta\}.$$

Clearly, $W_\delta \subset H$ densely since the trace operator acting on function $H^1(\Omega_\varepsilon)$ and into $H^{1/2}(\partial\Omega_\varepsilon)$ is bounded and onto, and W_δ is a Hilbert space with respect to the inner product inherited from $V_{\partial\Omega}^\delta$, $\delta \geq 0$. Thus, by definition we can identify

$$W_\delta = \{(v, \gamma_0(v)) \in H^1(\Omega_\varepsilon) \times H_{\partial\Omega}^1(\partial\Omega_\varepsilon)\},$$

for each $\delta > 0$, and

$$W_0 = \{(v, \gamma_0(v)) \in H^1(\Omega_\varepsilon) \times H_{\partial\Omega}^{1/2}(\partial\Omega_\varepsilon)\}.$$

3 Existence and uniqueness of solution

Along this paper, we shall denote by C different constants which are independent of ε . We state in this section a result on the existence and uniqueness of solution of problem (1). First, we observe that it is easy to see from (3) that there exists a constant $C > 0$ such that

$$|g(s)| \leq C \left(1 + |s|^{q-1}\right), \quad \text{for all } s \in \mathbb{R}. \quad (15)$$

Definition 3.1. A weak solution of (1) is a pair of functions $(u_\varepsilon, \psi_\varepsilon)$, satisfying

$$u_\varepsilon \in C([0, T]; L^2(\Omega_\varepsilon)), \quad \psi_\varepsilon \in C([0, T]; L_{\partial\Omega}^2(\partial\Omega_\varepsilon)), \quad \text{for all } T > 0, \quad (16)$$

$$u_\varepsilon \in L^2(0, T; H^1(\Omega_\varepsilon)), \quad \text{for all } T > 0, \quad (17)$$

$$\psi_\varepsilon \in L^2(0, T; H_{\partial\Omega}^1(\partial\Omega_\varepsilon)) \cap L^q(0, T; L_{\partial\Omega}^q(\partial\Omega_\varepsilon)), \quad \text{for all } T > 0, \quad (18)$$

$$\gamma_0(u_\varepsilon(t)) = \psi_\varepsilon(t), \quad \text{a.e. } t \in (0, T], \quad (19)$$

$$\begin{cases} \frac{d}{dt}(u_\varepsilon(t), v)_{\Omega_\varepsilon} + \varepsilon \frac{d}{dt}(\psi_\varepsilon(t), \gamma_0(v))_{\partial F_\varepsilon} + (\nabla u_\varepsilon(t), \nabla v)_{\Omega_\varepsilon} + \kappa(u_\varepsilon(t), v)_{\Omega_\varepsilon} \\ + \varepsilon \delta (\nabla_\Gamma \psi_\varepsilon(t), \nabla_\Gamma \gamma_0(v))_{\partial F_\varepsilon} + \varepsilon (g(\psi_\varepsilon(t)), \gamma_0(v))_{\partial F_\varepsilon} = 0 \\ \text{in } \mathcal{D}'(0, T), \text{ for all } v \in H^1(\Omega_\varepsilon) \text{ such that } \gamma_0(v) \in H_{\partial\Omega}^1(\partial\Omega_\varepsilon) \cap L_{\partial\Omega}^q(\partial\Omega_\varepsilon), \end{cases} \quad (20)$$

$$u_\varepsilon(0) = u_\varepsilon^0, \quad \text{and} \quad \psi_\varepsilon(0) = \psi_\varepsilon^0. \quad (21)$$

We have the following result.

Theorem 3.2. *Under the assumptions (2)–(4) and (6), there exists a unique solution $(u_\varepsilon, \psi_\varepsilon)$ of the problem (1). Moreover, this solution satisfies the energy equality*

$$\frac{1}{2} \frac{d}{dt} (|(u_\varepsilon(t), \psi_\varepsilon(t))|_H^2) + |\nabla u_\varepsilon(t)|_{\Omega_\varepsilon}^2 + \kappa |u_\varepsilon(t)|_{\Omega_\varepsilon}^2 + \varepsilon \delta |\nabla_\Gamma \psi_\varepsilon(t)|_{\partial F_\varepsilon}^2 + \varepsilon (g(\psi_\varepsilon(t)), \psi_\varepsilon(t))_{\partial F_\varepsilon} = 0, \quad (22)$$

a.e. $t \in (0, T)$.

Proof. On the space W_δ we define a continuous symmetric linear operator $A_\delta : W_\delta \rightarrow W'_\delta$, given by

$$\langle A_\delta((v, \gamma_0(v))), (w, \gamma_0(w)) \rangle = (\nabla v, \nabla w)_{\Omega_\varepsilon} + \kappa (v, w)_{\Omega_\varepsilon} + \varepsilon \delta (\nabla_\Gamma \gamma_0(v), \nabla_\Gamma \gamma_0(w))_{\partial F_\varepsilon},$$

for all $(v, \gamma_0(v)), (w, \gamma_0(w)) \in W_\delta$.

We observe that A_δ is coercive. In fact, we have

$$\begin{aligned} \langle A_\delta((v, \gamma_0(v))), (v, \gamma_0(v)) \rangle + |(v, \gamma_0(v))|_H^2 &\geq \min\{1, \kappa\} \|v\|_{\Omega_\varepsilon}^2 + \varepsilon \delta |\nabla_\Gamma \gamma_0(v)|_{\partial F_\varepsilon}^2 + |v|_{\Omega_\varepsilon}^2 + \varepsilon |\gamma_0(v)|_{\partial F_\varepsilon}^2 \\ &\geq \min\{1, \kappa\} \|(v, \gamma_0(v))\|_{W_\delta}^2, \end{aligned}$$

for all $(v, \gamma_0(v)) \in W_\delta$.

Let us denote

$$V_1 = W_\delta, \quad A_1 = A_\delta, \quad V_2 = L^2(\Omega_\varepsilon) \times L^q_{\partial\Omega}(\partial\Omega_\varepsilon), \quad A_2(v, \phi) = (0, \varepsilon g(\phi)).$$

From (15) one deduces that $A_2 : V_2 \rightarrow V'_2$.

With this notation, and denoting $V = V_1 \cap V_2$, $p_1 = 2$, $p_2 = q$, $\vec{u}_\varepsilon = (u_\varepsilon, \psi_\varepsilon)$, one has that (16)–(21) is equivalent to

$$\vec{u}_\varepsilon \in C([0, T]; H), \quad \vec{u}_\varepsilon \in \bigcap_{i=1}^2 L^{p_i}(0, T; V_i), \quad \text{for all } T > 0, \quad (23)$$

$$(\vec{u}_\varepsilon)'(t) + \sum_{i=1}^2 A_i(\vec{u}_\varepsilon(t)) = 0 \quad \text{in } \mathcal{D}'(0, T; V'), \quad (24)$$

$$\vec{u}_\varepsilon(0) = (u_\varepsilon^0, \psi_\varepsilon^0). \quad (25)$$

Applying a slight modification of [11, Chapter 2, Theorem 1.4], it is not difficult to see that problem (23)–(25) has a unique solution. Moreover, \vec{u}_ε satisfies the energy equality

$$\frac{1}{2} \frac{d}{dt} |\vec{u}_\varepsilon(t)|_H^2 + \sum_{i=1}^2 \langle A_i(\vec{u}_\varepsilon(t)), \vec{u}_\varepsilon(t) \rangle_i = 0 \quad \text{a.e. } t \in (0, T),$$

where $\langle \cdot, \cdot \rangle_i$ denotes the duality product between V'_i and V_i . This last equality turns out to be just (22). \square

4 A priori estimates

In this section we obtain some energy estimates for the solution of (1). By (22) and taking into account (3), we have

$$\frac{d}{dt} (|(u_\varepsilon(t), \psi_\varepsilon(t))|_H^2) + 2 \min\{1, \kappa\} \|u_\varepsilon(t)\|_{\Omega_\varepsilon}^2 + 2\varepsilon \delta |\nabla_\Gamma \psi_\varepsilon(t)|_{\partial F_\varepsilon}^2 + 2\alpha_1 \varepsilon |\psi_\varepsilon(t)|_{q, \partial F_\varepsilon}^q \leq 2\beta \varepsilon |\partial F_\varepsilon|, \quad (26)$$

where $|\partial F_\varepsilon|$ denotes the measure of ∂F_ε .

We observe that the linear term $\Delta_\Gamma u_\varepsilon$ in the boundary condition is coercive, so that this term is of no real significance to the energy estimates and only enhances the regularity of the solution. Therefore, the following result is a direct consequence of (22), (26) and results contained in [3, Section 4].

Lemma 4.1. *Under the assumptions (2)–(4) and (6), assume that $g \in \mathcal{C}^1(\mathbb{R})$. Then, for any initial condition $(u_\varepsilon^0, \psi_\varepsilon^0) \in W_\delta \cap H_q$, there exists a constant C independent of ε , such that the solution u_ε of the problem (1) satisfies*

$$\begin{aligned} \|u_\varepsilon\|_{\Omega_\varepsilon, T} &\leq C, \quad \sup_{t \in [0, T]} \|u_\varepsilon(t)\|_{\Omega_\varepsilon} \leq C, \quad \|u'_\varepsilon\|_{\Omega_\varepsilon, T} \leq C, \\ \sqrt{\varepsilon} |\gamma_0(u_\varepsilon)|_{\partial F_\varepsilon} &\leq C, \quad |u'_\varepsilon|_{\Omega_\varepsilon} \leq C, \quad \sqrt{\varepsilon} |\gamma_0(u'_\varepsilon)|_{\partial F_\varepsilon} \leq C. \end{aligned} \quad (27)$$

In the following result, we enhance the regularity of the solution.

Lemma 4.2. *Assume the assumptions in Lemma 4.1 and (5). Then, for any initial condition $(u_\varepsilon^0, \psi_\varepsilon^0) \in W_\delta \cap H_q$, there exists a constant C independent of ε , such that the solution u_ε of the problem (1) satisfies*

$$\|u_\varepsilon\|_{H^2(\Omega_\varepsilon)} \leq C. \quad (28)$$

Proof. In order to obtain the estimates for the H^2 -norm, we rewrite (for every fixed t) problem (1) as a second-order nonlinear elliptic boundary value problem:

$$\left\{ \begin{array}{ll} -\Delta u_\varepsilon + \kappa u_\varepsilon = h_1(t) := -\frac{\partial u_\varepsilon}{\partial t} & \text{in } \Omega_\varepsilon, \\ -\varepsilon \delta \Delta_\Gamma u_\varepsilon + \varepsilon \lambda u_\varepsilon + \nabla u_\varepsilon \cdot \nu = \varepsilon h_2(t) := -\varepsilon g(u_\varepsilon) - \varepsilon \frac{\partial u_\varepsilon}{\partial t} + \varepsilon \lambda u_\varepsilon & \text{on } \partial F_\varepsilon, \\ u_\varepsilon = 0 & \text{on } \partial \Omega, \end{array} \right. \quad (29)$$

where λ is some positive constant.

We multiply the first equation of (29) scalarly in $L^2(\Omega_\varepsilon)$ by u_ε , we integrate by parts and we have

$$|\nabla u_\varepsilon|_{\Omega_\varepsilon}^2 + \kappa |u_\varepsilon|_{\Omega_\varepsilon}^2 + \varepsilon \delta |\nabla_\Gamma \gamma_0(u_\varepsilon)|_{\partial F_\varepsilon}^2 + \varepsilon \lambda |\gamma_0(u_\varepsilon)|_{\partial F_\varepsilon}^2 = (h_1, u_\varepsilon)_{\Omega_\varepsilon} + \varepsilon (h_2, \gamma_0(u_\varepsilon))_{\partial F_\varepsilon}. \quad (30)$$

Using Young's inequality, we obtain

$$(h_1, u_\varepsilon)_{\Omega_\varepsilon} \leq |h_1|_{\Omega_\varepsilon} |u_\varepsilon|_{\Omega_\varepsilon} \leq \frac{1}{2\kappa} |h_1|_{\Omega_\varepsilon}^2 + \frac{\kappa}{2} |u_\varepsilon|_{\Omega_\varepsilon}^2,$$

and

$$(h_2, \gamma_0(u_\varepsilon))_{\partial F_\varepsilon} \leq |h_2|_{\partial F_\varepsilon} |\gamma_0(u_\varepsilon)|_{\partial F_\varepsilon} \leq \frac{1}{2\lambda} |h_2|_{\partial F_\varepsilon}^2 + \frac{\lambda}{2} |\gamma_0(u_\varepsilon)|_{\partial F_\varepsilon}^2,$$

and by (30), we can deduce that there exists a positive constant C such that

$$\|u_\varepsilon\|_{\Omega_\varepsilon}^2 + \varepsilon |\gamma_0(u_\varepsilon)|_{\partial F_\varepsilon}^2 \leq C (|h_1|_{\Omega_\varepsilon}^2 + \varepsilon |h_2|_{\partial F_\varepsilon}^2),$$

and, in particular, we have

$$\|u_\varepsilon\|_{\Omega_\varepsilon} \leq C (|h_1|_{\Omega_\varepsilon} + \sqrt{\varepsilon} |h_2|_{\partial F_\varepsilon}). \quad (31)$$

Using now the estimates for general elliptic boundary value problems (see [12, Chapter 2, Remark 7.2]) to the first equation of (29) with $s = 2$, $m = 1$ and $j = 0$, we have

$$\|u_\varepsilon\|_{H^2(\Omega_\varepsilon)} \leq C (|h_1|_{\Omega_\varepsilon} + \|\varepsilon \gamma_0(u_\varepsilon)\|_{H^{3/2}(\partial F_\varepsilon)}). \quad (32)$$

Analogously, applying this estimate to the second equation in (29), we deduce

$$\|\varepsilon \gamma_0(u_\varepsilon)\|_{H^2(\partial F_\varepsilon)} \leq C (\varepsilon |h_2|_{\partial F_\varepsilon} + |\partial_\nu u_\varepsilon|_{\partial F_\varepsilon}), \quad (33)$$

where by $\partial_\nu u_\varepsilon$ we denote $\nabla u_\varepsilon \cdot \nu$. Taking into account (33) in (32), we can deduce

$$\|u_\varepsilon\|_{H^2(\Omega_\varepsilon)} \leq C (|h_1|_{\Omega_\varepsilon} + \varepsilon |h_2|_{\partial F_\varepsilon} + |\partial_\nu u_\varepsilon|_{\partial F_\varepsilon}). \quad (34)$$

By the Trace Theorem in $H^{7/4}(\Omega_\varepsilon)$ (see [12, Chapter 1, Theorem 9.4]), we have

$$|\partial_\nu u_\varepsilon|_{\partial F_\varepsilon} \leq C \|u_\varepsilon\|_{H^{7/4}(\Omega_\varepsilon)},$$

and by interpolation inequality (see [12, Chapter 1, Remark 9.1]) with $s_1 = 1$, $s_2 = 2$ and $\theta = 3/4$, we can deduce

$$|\partial_\nu u_\varepsilon|_{\partial F_\varepsilon} \leq C \|u_\varepsilon\|_{\Omega_\varepsilon}^{1/4} \|u_\varepsilon\|_{H^2(\Omega_\varepsilon)}^{3/4}.$$

By Young's inequality, with the conjugate exponents 4 and 4/3, we get

$$|\partial_\nu u_\varepsilon|_{\partial F_\varepsilon} \leq C \|u_\varepsilon\|_{\Omega_\varepsilon} + c \|u_\varepsilon\|_{H^2(\Omega_\varepsilon)}, \quad (35)$$

where the positive constant c can be arbitrarily small. Then, taking into account (35) in (34), we have

$$\|u_\varepsilon\|_{H^2(\Omega_\varepsilon)} \leq C (|h_1|_{\Omega_\varepsilon} + \varepsilon |h_2|_{\partial F_\varepsilon} + \|u_\varepsilon\|_{\Omega_\varepsilon}),$$

and using (31), we can deduce the following estimate for the H^2 -norm

$$\|u_\varepsilon\|_{H^2(\Omega_\varepsilon)} \leq C (|h_1|_{\Omega_\varepsilon} + \sqrt{\varepsilon} |h_2|_{\partial F_\varepsilon}). \quad (36)$$

According to the second estimate in (27), we have

$$|h_1|_{\Omega_\varepsilon} \leq C. \quad (37)$$

We observe that under the condition (5), we have that $g'(s) \leq l$, $\forall s \in \mathbb{R}$, and we can deduce that

$$\sqrt{\varepsilon} |g(\gamma_0(u_\varepsilon))|_{\partial F_\varepsilon} \leq \sqrt{\varepsilon} |g(\gamma_0(u_\varepsilon)) - g(0)|_{\partial F_\varepsilon} + \sqrt{\varepsilon} |g(0)|_{\partial F_\varepsilon} \leq \sqrt{\varepsilon} l |\gamma_0(u_\varepsilon)|_{\partial F_\varepsilon} + \sqrt{\varepsilon} |g(0)|_{\partial F_\varepsilon}^{1/2}.$$

Taking into account that $|\partial F_\varepsilon| \leq C\varepsilon^{-1}$ (see [3, Lemma 4.2]) and using the first estimate in (27), we obtain

$$\sqrt{\varepsilon} |g(\gamma_0(u_\varepsilon))|_{\partial F_\varepsilon} \leq C,$$

which, together with the first and third estimates in (27), we can deduce

$$\sqrt{\varepsilon} |h_2|_{\partial F_\varepsilon} \leq C. \quad (38)$$

Finally, taking into account (37)-(38) in (36), we obtain (28). \square

The extension of u_ε to the whole $\Omega \times (0, T)$: since the solution u_ε of the problem (1) is defined only in $\Omega_\varepsilon \times (0, T)$, we need to extend it to the whole $\Omega \times (0, T)$ to be able to state the convergence result. In order to do that, we use the well-known extension result given by Cioranescu and Saint Jean Paulin [7]. Taking into account Lemma 4.1, the following result is a direct consequence of results contained in [3, Corollary 4.8].

Corollary 4.3. *Assume the assumptions in Lemma 4.1. Then, there exists an extension \tilde{u}_ε of the solution u_ε of the problem (1) into $\Omega \times (0, T)$, such that*

$$\begin{aligned} \|\tilde{u}_\varepsilon(t)\|_{\Omega, T} &\leq C, \quad |\tilde{u}_\varepsilon|_{q, \Omega, T} \leq C, \\ \sup_{t \in [0, T]} \|\tilde{u}_\varepsilon(t)\|_{\Omega} &\leq C, \\ |\tilde{u}'_\varepsilon|_{q, \Omega, T} &\leq C, \end{aligned} \quad (39)$$

where the constant C does not depend on ε .

5 A compactness result

In this section, we obtain some compactness results about the behavior of the sequence \tilde{u}_ε satisfying the *a priori* estimates given in Corollary 4.3.

By $\chi_{\Omega_\varepsilon}$ we denote the characteristic function of the domain Ω_ε . Due to the periodicity of the domain Ω_ε , from Theorem 2.6 in Cioranescu and Donato [6] one has, for $\varepsilon \rightarrow 0$, that

$$\chi_{\Omega_\varepsilon} \xrightarrow{*} \frac{|Y^*|}{|Y|} \quad \text{weakly-star in } L^\infty(\Omega), \quad (40)$$

where the limit is the proportion of the material in the cell Y .

Let ξ_ε be the gradient of u_ε in $\Omega_\varepsilon \times (0, T)$ and let us denote by $\tilde{\xi}_\varepsilon$ its extension with zero to the whole of $\Omega \times (0, T)$, i.e.

$$\tilde{\xi}_\varepsilon = \begin{cases} \xi_\varepsilon & \text{in } \Omega_\varepsilon \times (0, T), \\ 0 & \text{in } (\Omega \setminus \overline{\Omega_\varepsilon}) \times (0, T). \end{cases} \quad (41)$$

Proposition 5.1. *Under the assumptions in Lemma 4.1, there exists a function $u \in L^2(0, T; H_0^1(\Omega)) \cap L^q(0, T; L^q(\Omega))$ (u will be the unique solution of the limit system (8)) and a function $\xi \in L^2(0, T; L^2(\Omega))$ such that for all $T > 0$,*

$$\tilde{u}_\varepsilon(t) \rightharpoonup u(t) \quad \text{weakly in } H_0^1(\Omega), \quad \forall t \in [0, T], \quad (42)$$

$$\tilde{u}_\varepsilon(t) \rightarrow u(t) \quad \text{strongly in } L^2(\Omega), \quad \forall t \in [0, T], \quad (43)$$

$$g(\tilde{u}_\varepsilon(t)) \rightarrow g(u(t)) \quad \text{strongly in } L^{q'}(\Omega), \quad \forall t \in [0, T], \quad (44)$$

$$\tilde{\xi}_\varepsilon \rightharpoonup \xi \quad \text{weakly in } L^2(0, T; L^2(\Omega)), \quad (45)$$

$$\tilde{\xi}_\varepsilon \rightharpoonup \xi \quad \text{weakly in } L^2(\Omega), \quad \forall t \in [0, T], \quad (46)$$

where $\tilde{\xi}_\varepsilon$ is given by (41).

Moreover, if we suppose (5), then

$$g(\tilde{u}_\varepsilon(t)) \rightharpoonup g(u(t)) \quad \text{weakly in } W_0^{1,q'}(\Omega), \quad \forall t \in [0, T]. \quad (47)$$

Proof. Taking into account Lemma 4.1, we have that (42)-(45) and (47) are a direct consequence of results contained in [3, Proposition 5.1]. In order to prove (46), we observe that by the estimate (39), for each $t \in [0, T]$, we have that $\tilde{\xi}_\varepsilon$ is bounded in $L^2(\Omega)$, and since we have (45), we can deduce (46). \square

Because we have the linear term $\Delta_\Gamma u_\varepsilon$ in the boundary condition, in order to pass to the limit in the integral which involves this term, we need the following result.

Proposition 5.2. *Under the assumptions in Lemma 4.2, there exists a function $\xi \in L^2(0, T; H_0^1(\Omega))$ such that for all $T > 0$,*

$$\tilde{\xi}_\varepsilon \rightharpoonup \xi \quad \text{weakly in } H_0^1(\Omega), \quad \forall t \in [0, T], \quad (48)$$

where $\tilde{\xi}_\varepsilon$ is given by (41).

Proof. From the estimate (28) and (41), we have $\|\tilde{\xi}_\varepsilon\|_\Omega \leq C$. Then, we see that the sequence $\{\tilde{\xi}_\varepsilon\}$ is bounded in $H_0^1(\Omega)$, and hence, up a sequence and by (46), we can deduce (48). \square

6 Homogenized model: proof of Theorem 1.1

In this section, we identify the homogenized model.

We multiply system (1) by a test function $v \in \mathcal{D}(\Omega)$, integrating by parts and taking into account (14) and (41), we have

$$\begin{aligned} \frac{d}{dt} \left(\int_{\Omega} \chi_{\Omega_\varepsilon} \tilde{u}_\varepsilon(t) v dx \right) + \varepsilon \frac{d}{dt} \left(\int_{\partial F_\varepsilon} \gamma_0(u_\varepsilon(t)) v d\sigma(x) \right) + \int_{\Omega} \tilde{\xi}_\varepsilon \cdot \nabla v dx + \kappa \int_{\Omega} \chi_{\Omega_\varepsilon} \tilde{u}_\varepsilon(t) v dx \\ + \varepsilon \delta \int_{\partial F_\varepsilon} \nabla_{\Gamma} \gamma_0(u_\varepsilon(t)) \cdot \nabla v d\sigma(x) + \varepsilon \int_{\partial F_\varepsilon} g(\gamma_0(u_\varepsilon(t))) v d\sigma(x) = 0, \end{aligned}$$

in $\mathcal{D}'(0, T)$.

We consider $\varphi \in C_c^1([0, T])$ such that $\varphi(T) = 0$ and $\varphi(0) \neq 0$. Multiplying by φ and integrating between 0 and T , we have

$$\begin{aligned} -\varphi(0) \left(\int_{\Omega} \chi_{\Omega_\varepsilon} \tilde{u}_\varepsilon(0) v dx \right) - \int_0^T \frac{d}{dt} \varphi(t) \left(\int_{\Omega} \chi_{\Omega_\varepsilon} \tilde{u}_\varepsilon(t) v dx \right) dt \\ - \varepsilon \varphi(0) \left(\int_{\partial F_\varepsilon} \gamma_0(u_\varepsilon(0)) v d\sigma(x) \right) - \varepsilon \int_0^T \frac{d}{dt} \varphi(t) \left(\int_{\partial F_\varepsilon} \gamma_0(u_\varepsilon(t)) v d\sigma(x) \right) dt \\ + \int_0^T \varphi(t) \int_{\Omega} \tilde{\xi}_\varepsilon \cdot \nabla v dx dt + \kappa \int_0^T \varphi(t) \int_{\Omega} \chi_{\Omega_\varepsilon} \tilde{u}_\varepsilon(t) v dx dt \\ + \varepsilon \delta \int_0^T \varphi(t) \int_{\partial F_\varepsilon} \nabla_{\Gamma} \gamma_0(u_\varepsilon(t)) \cdot \nabla v d\sigma(x) dt + \varepsilon \int_0^T \varphi(t) \int_{\partial F_\varepsilon} g(\gamma_0(u_\varepsilon(t))) v d\sigma(x) dt = 0. \end{aligned} \quad (49)$$

For the sake of clarity, we split the proof in three parts. Firstly, we pass to the limit, as $\varepsilon \rightarrow 0$, in (49) in order to get the limit equation satisfied by u . Secondly we identify ξ making use of the solutions of the cell-problems (10), and finally we prove that u is uniquely determined.

Step 1. In order to pass to the limit, as $\varepsilon \rightarrow 0$, we reason as in [3, Theorem 6.1] for all the terms except the term which involve the tangential gradient ∇_{Γ} . Exactly, for the integrals on Ω we only require to use Proposition 5.1 and the convergence (40) and for the integrals on the boundary of the holes we make use of a convergence result based on a technique introduced by Vanninathan [16] for the Steklov problem which transforms surface integrals into volume integrals, which was already used as a main tool to homogenize the non homogeneous Neumann problem for the elliptic case by Cioranescu and Donato [5]. For the term which involve the tangential gradient, we also use this technique together with Proposition 5.2.

By Definition 3.2 in Cioranescu and Donato [5], let us introduce, for any $h \in L^{s'}(\partial F)$, $1 \leq s' \leq \infty$, the linear form μ_h^ε on $W_0^{1,s}(\Omega)$ defined by

$$\langle \mu_h^\varepsilon, \varphi \rangle = \varepsilon \int_{\partial F_\varepsilon} h \left(\frac{x}{\varepsilon} \right) \varphi(x) d\sigma(x), \quad \forall \varphi \in W_0^{1,s}(\Omega),$$

with $1/s + 1/s' = 1$. It is proved in Lemma 3.3 in Cioranescu and Donato [5] that

$$\mu_h^\varepsilon \rightarrow \mu_h \quad \text{strongly in } (W_0^{1,s}(\Omega))', \quad (50)$$

where $\langle \mu_h, \varphi \rangle = \mu_h \int_{\Omega} \varphi(x) dx$, with

$$\mu_h = \frac{1}{|Y|} \int_{\partial F} h(y) d\sigma(y).$$

In the particular case in which $h \in L^\infty(\partial F)$ or even when h is constant, we have

$$\mu_h^\varepsilon \rightarrow \mu_h \quad \text{strongly in } W^{-1,\infty}(\Omega).$$

We denote by μ_1^ε the above introduced measure in the particular case in which $h = 1$. Notice that in this case μ_h becomes $\mu_1 = |\partial F|/|Y|$.

For the term which involve the tangential gradient, we proceed as follows. Taking into account (13), there exists an element $\vartheta_\varepsilon \in H^{3/2}(\Omega_\varepsilon)$, the extension of $\gamma_0(u_\varepsilon(t))$, such that $\nabla \vartheta_\varepsilon = \nabla_\Gamma \gamma_0(u_\varepsilon(t))$ on ∂F_ε . Then, we can deduce

$$\varepsilon \int_{\partial F_\varepsilon} \nabla_\Gamma \gamma_0(u_\varepsilon(t)) \cdot \nabla v d\sigma(x) = \varepsilon \int_{\partial F_\varepsilon} \nabla \vartheta_\varepsilon \cdot \nabla v d\sigma(x) = \langle \mu_1^\varepsilon, \tilde{\xi}_\varepsilon \cdot \nabla v \rangle,$$

where $\tilde{\xi}_\varepsilon$ is given by (41). Note that using (50) with $s = 2$ and taking into account (48), we can deduce, for $\varepsilon \rightarrow 0$,

$$\varepsilon \int_{\partial F_\varepsilon} \nabla_\Gamma \gamma_0(u_\varepsilon(t)) \cdot \nabla v d\sigma(x) = \langle \mu_1^\varepsilon, \tilde{\xi}_\varepsilon \cdot \nabla v \rangle \rightarrow \mu_1 \int_\Omega \xi \cdot \nabla v dx = \frac{|\partial F|}{|Y|} \int_\Omega \xi \cdot \nabla v dx, \quad \forall v \in \mathcal{D}(\Omega),$$

which integrating in time and using Lebesgue's Dominated Convergence Theorem, gives

$$\varepsilon \int_0^T \varphi(t) \int_{\partial F_\varepsilon} \nabla_\Gamma \gamma_0(u_\varepsilon(t)) \cdot \nabla v d\sigma(x) dt \rightarrow \frac{|\partial F|}{|Y|} \int_0^T \varphi(t) \left(\int_\Omega \xi \cdot \nabla v dx \right) dt. \quad (51)$$

Therefore, using the proof of the main Theorem in [3] and (51), we pass to the limit, as $\varepsilon \rightarrow 0$, in (49), and we obtain

$$\begin{aligned} & -\varphi(0) \left(\frac{|Y^*|}{|Y|} + \frac{|\partial F|}{|Y|} \right) \left(\int_\Omega u(0)v dx \right) - \left(\frac{|Y^*|}{|Y|} + \frac{|\partial F|}{|Y|} \right) \int_0^T \frac{d}{dt} \varphi(t) \left(\int_\Omega u(t)v dx \right) dt \\ & \quad + \int_0^T \varphi(t) \int_\Omega \xi \cdot \nabla v dx dt + \kappa \frac{|Y^*|}{|Y|} \int_0^T \varphi(t) \int_\Omega u(t)v dx dt \\ & \quad + \delta \frac{|\partial F|}{|Y|} \int_0^T \varphi(t) \int_\Omega \xi \cdot \nabla v dx dt + \frac{|\partial F|}{|Y|} \int_0^T \varphi(t) \int_\Omega g(u(t))v dx dt = 0. \end{aligned}$$

Hence, ξ verifies

$$\left(\frac{|Y^*|}{|Y|} + \frac{|\partial F|}{|Y|} \right) \frac{\partial u}{\partial t} - \left(1 + \delta \frac{|\partial F|}{|Y|} \right) \operatorname{div} \xi + \frac{|Y^*|}{|Y|} \kappa u + \frac{|\partial F|}{|Y|} g(u) = 0, \quad \text{in } \Omega \times (0, T). \quad (52)$$

Step 2. It remains now to identify ξ . We shall make use of the solutions of the cell problems (10). For any fixed $i = 1, \dots, N$, let us define

$$\Psi_{i\varepsilon}(x) = \varepsilon \left(w_i \left(\frac{x}{\varepsilon} \right) + y_i \right) \quad \forall x \in \Omega_\varepsilon, \quad (53)$$

where $y = x/\varepsilon$.

By periodicity

$$\tilde{\Psi}_{i\varepsilon} \rightharpoonup x_i \quad \text{weakly in } H^1(\Omega),$$

where $\tilde{\cdot}$ denotes the extension to Ω given by Cioranescu and Saint Jean Paulin [7]. Then, by Rellich-Kondrachov Theorem, we can deduce

$$\tilde{\Psi}_{i\varepsilon} \rightarrow x_i \quad \text{strongly in } L^2(\Omega). \quad (54)$$

Let $\nabla \Psi_{i\varepsilon}$ be the gradient of $\Psi_{i\varepsilon}$ in Ω_ε . Denote by $\widetilde{\nabla \Psi_{i\varepsilon}}$ the extension by zero of $\nabla \Psi_{i\varepsilon}$ inside the holes. From (53), we have

$$\widetilde{\nabla \Psi_{i\varepsilon}} = \nabla_y \widetilde{(w_i + y_i)} = \widetilde{\nabla_y w_i(y)} + e_i \chi_{Y^*},$$

and taking into account [4, Corollary 2.10], we have

$$\widetilde{\nabla \Psi}_{i\varepsilon} \rightharpoonup \frac{1}{|Y|} \int_{Y^*} (e_i + \nabla_y w_i(y)) dy \quad \text{weakly in } L^2(\Omega). \quad (55)$$

Let $\nabla_\Gamma \gamma_0(\Psi_{i\varepsilon})$ be the tangential gradient of $\gamma_0(\Psi_{i\varepsilon})$ on ∂F_ε and we denote by μ_h^ε the above introduced measure in the particular case in which $h\left(\frac{x}{\varepsilon}\right) = \nabla_\Gamma \gamma_0(\Psi_{i\varepsilon}(x))$.

From (53), we have

$$\nabla_\Gamma \gamma_0(\Psi_{i\varepsilon}) = P_\Gamma e_i + \nabla_\Gamma w_i(y),$$

where $P_\Gamma e_i$ is defined on ∂F and the tangential gradient of w_i is given by

$$\nabla_\Gamma w_i := P_\Gamma \nabla_y \tilde{w}_i = \nabla_y \tilde{w}_i - \nabla_y \tilde{w}_i \cdot \nu \nu \quad \text{on } \partial F,$$

where \tilde{w}_i is an extension of w_i .

In this case, μ_h becomes

$$\mu_h = \frac{1}{|Y|} \int_{\partial F} (P_\Gamma e_i + \nabla_\Gamma w_i(y)) d\sigma(y).$$

Then, using (50), we obtain

$$\varepsilon \int_{\partial F_\varepsilon} \nabla_\Gamma \gamma_0(\Psi_{i\varepsilon}(x)) \varphi(x) d\sigma(x) = \langle \mu_h^\varepsilon, \varphi \rangle \rightarrow \langle \mu_h, \varphi \rangle = \mu_h \int_\Omega \varphi(x) dx, \quad \forall \varphi \in W_0^{1,s}(\Omega). \quad (56)$$

On the other hand, it is not difficult to see that $\Psi_{i\varepsilon}$ satisfies

$$\begin{cases} -\operatorname{div}(\nabla \Psi_{i\varepsilon}) = 0, & \text{in } \Omega_\varepsilon, \\ \nabla \Psi_{i\varepsilon} \cdot \nu = \varepsilon \delta \operatorname{div}_\Gamma(\nabla_\Gamma \Psi_{i\varepsilon}), & \text{on } \partial F_\varepsilon. \end{cases} \quad (57)$$

Let $v \in \mathcal{D}(\Omega)$. Multiplying the first equation in (57) by $v u_\varepsilon$, integrating by parts over Ω_ε and taking into account (14), we get

$$\begin{aligned} & - \varepsilon \delta \int_{\partial F_\varepsilon} \nabla_\Gamma \gamma_0(\Psi_{i\varepsilon}) \cdot \nabla v \gamma_0(u_\varepsilon) d\sigma(x) - \varepsilon \delta \int_{\partial F_\varepsilon} \nabla_\Gamma \gamma_0(\Psi_{i\varepsilon}) \cdot \nabla_\Gamma \gamma_0(u_\varepsilon) v d\sigma(x) \\ & = \int_{\Omega_\varepsilon} \nabla \Psi_{i\varepsilon} \cdot \nabla v u_\varepsilon dx + \int_{\Omega_\varepsilon} \nabla \Psi_{i\varepsilon} \cdot \nabla u_\varepsilon v dx. \end{aligned} \quad (58)$$

On the other hand, we multiply system (1) by the test function $v \Psi_{i\varepsilon}$, integrating by parts over Ω_ε and taking into account (14), we obtain

$$\begin{aligned} & \frac{d}{dt} \left(\int_\Omega \chi_{\Omega_\varepsilon} \tilde{u}_\varepsilon v \tilde{\Psi}_{i\varepsilon} dx \right) + \varepsilon \frac{d}{dt} \left(\int_{\partial F_\varepsilon} \gamma_0(u_\varepsilon) v \gamma_0(\Psi_{i\varepsilon}) d\sigma(x) \right) + \int_{\Omega_\varepsilon} \nabla u_\varepsilon \cdot \nabla v \Psi_{i\varepsilon} dx + \int_{\Omega_\varepsilon} \nabla u_\varepsilon \cdot \nabla \Psi_{i\varepsilon} v dx \\ & + \kappa \int_\Omega \chi_{\Omega_\varepsilon} \tilde{u}_\varepsilon v \tilde{\Psi}_{i\varepsilon} dx + \varepsilon \delta \int_{\partial F_\varepsilon} \nabla_\Gamma \gamma_0(u_\varepsilon) \cdot \nabla v \gamma_0(\Psi_{i\varepsilon}) d\sigma(x) + \varepsilon \delta \int_{\partial F_\varepsilon} \nabla_\Gamma \gamma_0(u_\varepsilon) \cdot \nabla_\Gamma \gamma_0(\Psi_{i\varepsilon}) v d\sigma(x) \\ & + \varepsilon \int_{\partial F_\varepsilon} g(\gamma_0(u_\varepsilon)) v \gamma_0(\Psi_{i\varepsilon}) d\sigma(x) = 0, \end{aligned}$$

in $\mathcal{D}'(0, T)$. Using (58), we have

$$\begin{aligned} & \frac{d}{dt} \left(\int_\Omega \chi_{\Omega_\varepsilon} \tilde{u}_\varepsilon v \tilde{\Psi}_{i\varepsilon} dx \right) + \varepsilon \frac{d}{dt} \left(\int_{\partial F_\varepsilon} \gamma_0(u_\varepsilon) v \gamma_0(\Psi_{i\varepsilon}) d\sigma(x) \right) + \int_{\Omega_\varepsilon} \nabla u_\varepsilon \cdot \nabla v \Psi_{i\varepsilon} dx - \int_{\Omega_\varepsilon} \nabla \Psi_{i\varepsilon} \cdot \nabla v u_\varepsilon dx \\ & - \varepsilon \delta \int_{\partial F_\varepsilon} \nabla_\Gamma \gamma_0(\Psi_{i\varepsilon}) \cdot \nabla v \gamma_0(u_\varepsilon) d\sigma(x) + \kappa \int_\Omega \chi_{\Omega_\varepsilon} \tilde{u}_\varepsilon v \tilde{\Psi}_{i\varepsilon} dx + \varepsilon \delta \int_{\partial F_\varepsilon} \nabla_\Gamma \gamma_0(u_\varepsilon) \cdot \nabla v \gamma_0(\Psi_{i\varepsilon}) d\sigma(x) \\ & + \varepsilon \int_{\partial F_\varepsilon} g(\gamma_0(u_\varepsilon)) v \gamma_0(\Psi_{i\varepsilon}) d\sigma(x) = 0, \end{aligned}$$

in $\mathcal{D}'(0, T)$.

We consider $\varphi \in C_c^1([0, T])$ such that $\varphi(T) = 0$ and $\varphi(0) \neq 0$. Multiplying by φ and integrating between 0 and T , we have

$$\begin{aligned}
 & -\varphi(0) \left(\int_{\Omega} \chi_{\Omega_\varepsilon} \tilde{u}_\varepsilon(0) v \tilde{\Psi}_{i\varepsilon} dx \right) - \int_0^T \frac{d}{dt} \varphi(t) \left(\int_{\Omega} \chi_{\Omega_\varepsilon} \tilde{u}_\varepsilon(t) v \tilde{\Psi}_{i\varepsilon} dx \right) dt \\
 & -\varepsilon \varphi(0) \left(\int_{\partial F_\varepsilon} \gamma_0(u_\varepsilon(0)) v \gamma_0(\Psi_{i\varepsilon}) d\sigma(x) \right) - \varepsilon \int_0^T \frac{d}{dt} \varphi(t) \left(\int_{\partial F_\varepsilon} \gamma_0(u_\varepsilon(t)) v \gamma_0(\Psi_{i\varepsilon}) d\sigma(x) \right) dt \\
 & \quad + \int_0^T \varphi(t) \int_{\Omega} \tilde{\xi}_\varepsilon \cdot \nabla v \tilde{\Psi}_{i\varepsilon} dx dt - \int_0^T \varphi(t) \int_{\Omega} \widetilde{\nabla \Psi}_{i\varepsilon} \cdot \nabla v \tilde{u}_\varepsilon dx dt \\
 & -\varepsilon \delta \int_0^T \varphi(t) \int_{\partial F_\varepsilon} \nabla_{\Gamma} \gamma_0(\Psi_{i\varepsilon}) \cdot \nabla v \gamma_0(u_\varepsilon) d\sigma(x) dt + \kappa \int_0^T \varphi(t) \int_{\Omega} \chi_{\Omega_\varepsilon} \tilde{u}_\varepsilon v \tilde{\Psi}_{i\varepsilon} dx dt \\
 & \quad + \varepsilon \delta \int_0^T \varphi(t) \int_{\partial F_\varepsilon} \nabla_{\Gamma} \gamma_0(u_\varepsilon) \cdot \nabla v \gamma_0(\Psi_{i\varepsilon}) d\sigma(x) dt \\
 & \quad + \varepsilon \int_0^T \varphi(t) \int_{\partial F_\varepsilon} g(\gamma_0(u_\varepsilon)) v \gamma_0(\Psi_{i\varepsilon}) d\sigma(x) dt = 0.
 \end{aligned} \tag{59}$$

Now, we have to pass to the limit, as $\varepsilon \rightarrow 0$. We will focus on the terms which involve the gradient and the tangential gradient. Taking into account (54), we reason as in [3, Theorem 6.1] for the others terms.

Firstly, using (46), (54) and Lebesgue's Dominated Convergence Theorem, we have

$$\int_0^T \varphi(t) \int_{\Omega} \tilde{\xi}_\varepsilon \cdot \nabla v \tilde{\Psi}_{i\varepsilon} dx dt \rightarrow \int_0^T \varphi(t) \int_{\Omega} \xi \cdot \nabla v x_i dx dt,$$

and by (43), (55) and Lebesgue's Dominated Convergence Theorem, we obtain

$$\int_0^T \varphi(t) \int_{\Omega} \widetilde{\nabla \Psi}_{i\varepsilon} \cdot \nabla v \tilde{u}_\varepsilon dx dt \rightarrow \frac{1}{|Y|} \int_0^T \varphi(t) \int_{\Omega} \left(\int_{Y^*} (e_i + \nabla_y w_i) dy \right) \cdot \nabla v u dx dt.$$

On the other hand, using (42) and (56), we can deduce

$$\varepsilon \delta \int_{\partial F_\varepsilon} \nabla_{\Gamma} \gamma_0(\Psi_{i\varepsilon}) \cdot \nabla v \gamma_0(u_\varepsilon) d\sigma(x) \rightarrow \frac{\delta}{|Y|} \int_{\Omega} \left(\int_{\partial F} (P_{\Gamma} e_i + \nabla_{\Gamma} w_i) d\sigma(y) \right) \cdot \nabla v u dx,$$

which integrating in time and by Lebesgue's Dominated Convergence Theorem, we obtain

$$\varepsilon \delta \int_0^T \varphi(t) \int_{\partial F_\varepsilon} \nabla_{\Gamma} \gamma_0(\Psi_{i\varepsilon}) \cdot \nabla v \gamma_0(u_\varepsilon) d\sigma(x) dt \rightarrow \frac{\delta}{|Y|} \int_0^T \varphi(t) \int_{\Omega} \left(\int_{\partial F} (P_{\Gamma} e_i + \nabla_{\Gamma} w_i) d\sigma(y) \right) \cdot \nabla v u dx dt.$$

Similarly to the proof of (51) together with (54), we have

$$\varepsilon \delta \int_0^T \varphi(t) \int_{\partial F_\varepsilon} \nabla_{\Gamma} \gamma_0(u_\varepsilon) \cdot \nabla v \gamma_0(\Psi_{i\varepsilon}) d\sigma(x) dt \rightarrow \delta \frac{|\partial F|}{|Y|} \int_0^T \varphi(t) \int_{\Omega} \xi \cdot \nabla v x_i dx dt.$$

Therefore, when we pass to the limit in (59), we obtain

$$\begin{aligned}
 & -\varphi(0) \left(\frac{|Y^*|}{|Y|} + \frac{|\partial F|}{|Y|} \right) \left(\int_{\Omega} u(0) v x_i dx \right) - \left(\frac{|Y^*|}{|Y|} + \frac{|\partial F|}{|Y|} \right) \int_0^T \frac{d}{dt} \varphi(t) \left(\int_{\Omega} u(t) v x_i dx \right) dt \\
 & + \int_0^T \varphi(t) \int_{\Omega} \xi \cdot \nabla v x_i dx dt - \frac{1}{|Y|} \int_0^T \varphi(t) \int_{\Omega} \left(\int_{Y^*} (e_i + \nabla_y w_i) dy \right) \cdot \nabla v u dx dt \\
 & - \frac{\delta}{|Y|} \int_0^T \varphi(t) \int_{\Omega} \left(\int_{\partial F} (P_{\Gamma} e_i + \nabla_{\Gamma} w_i) d\sigma(y) \right) \cdot \nabla v u dx dt + \kappa \frac{|Y^*|}{|Y|} \int_0^T \varphi(t) \int_{\Omega} u v x_i dx dt \\
 & + \delta \frac{|\partial F|}{|Y|} \int_0^T \varphi(t) \int_{\Omega} \xi \cdot \nabla v x_i dx dt + \frac{|\partial F|}{|Y|} \int_0^T \varphi(t) \int_{\Omega} g(u(t)) v x_i dx dt = 0.
 \end{aligned}$$

Using Green's formula and equation (52), we have

$$\begin{aligned}
 & - \int_0^T \varphi(t) \int_{\Omega} \xi \cdot \nabla x_i v dx dt + \frac{1}{|Y|} \int_0^T \varphi(t) \int_{\Omega} \left(\int_{Y^*} (e_i + \nabla_y w_i) dy \right) \cdot \nabla u v dx dt \\
 & + \frac{\delta}{|Y|} \int_0^T \varphi(t) \int_{\Omega} \left(\int_{\partial F} (P_{\Gamma} e_i + \nabla_{\Gamma} w_i) d\sigma(y) \right) \cdot \nabla u v dx dt - \delta \frac{|\partial F|}{|Y|} \int_0^T \varphi(t) \int_{\Omega} \xi \cdot \nabla x_i v dx dt = 0.
 \end{aligned}$$

The above equality holds true for any $v \in \mathcal{D}(\Omega)$ and $\varphi \in C_c^1([0, T])$. This implies that

$$- \left(1 + \delta \frac{|\partial F|}{|Y|} \right) \xi \cdot \nabla x_i + \frac{1}{|Y|} \left(\int_{Y^*} (e_i + \nabla_y w_i) dy \right) \cdot \nabla u + \frac{\delta}{|Y|} \left(\int_{\partial F} (P_{\Gamma} e_i + \nabla_{\Gamma} w_i) d\sigma(y) \right) \cdot \nabla u = 0,$$

in $\Omega \times (0, T)$. We conclude that

$$\left(1 + \delta \frac{|\partial F|}{|Y|} \right) \operatorname{div} \xi = \operatorname{div} (Q \nabla u), \tag{60}$$

where $Q = ((q_{ij}))$, $1 \leq i, j \leq N$, is given by

$$q_{ij} = \frac{1}{|Y|} \left(\int_{Y^*} (e_i + \nabla_y w_i) \cdot e_j dy + \delta \int_{\partial F} (P_{\Gamma} e_i + \nabla_{\Gamma} w_i) \cdot P_{\Gamma} e_j d\sigma(y) \right).$$

Observe that if we multiply system (10) by the test function w_j , integrating by parts over Y^* , we obtain

$$\int_{Y^*} (e_i + \nabla_y w_i) \cdot \nabla_y w_j dy + \delta \int_{\partial F} (P_{\Gamma} e_i + \nabla_{\Gamma} w_i) \cdot \nabla_{\Gamma} w_j d\sigma(y) = 0,$$

then we conclude that q_{ij} is given by (9).

Step 3. Finally, thanks to (52) and (60), we observe that u satisfies the first equation in (8). A weak solution of (8) is any function u , satisfying

$$u \in C([0, T]; L^2(\Omega)), \quad \text{for all } T > 0,$$

$$u \in L^2(0, T; H_0^1(\Omega)) \cap L^q(0, T; L^q(\Omega)), \quad \text{for all } T > 0,$$

$$\left(\frac{|Y^*|}{|Y|} + \frac{|\partial F|}{|Y|} \right) \frac{d}{dt} (u(t), v) + (Q \nabla u(t), \nabla v) + \frac{|Y^*|}{|Y|} \kappa(u(t), v) + \frac{|\partial F|}{|Y|} (g(u(t)), v) = 0, \quad \text{in } \mathcal{D}'(0, T),$$

for all $v \in H_0^1(\Omega) \cap L^q(\Omega)$, and

$$u(0) = u_0.$$

Applying a slight modification of [11, Chapter 2, Theorem 1.4], we obtain that the problem (8) has a unique solution, and therefore Theorem 1.1 is proved.

Remark 6.1. *It is worth remarking that if we consider a nonlinear term $f(u_\varepsilon)$ in the first equation in (1) which satisfies the same assumption than g , we obtain Theorem 1.1 with a additional term $\frac{|Y^*|}{|Y|}f(u)$ in the first equation in (8).*

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