

# A very low offset voltage auto-zero stabilized CMOS operational amplifier

Daniel DZAHINI (1), Hamid Ghazlane (2)

(1) Institut des Sciences Nucléaires  
53 avenue des Martyrs, 38026 Grenoble Cédex France

(2) Centre National de l'Énergie, des Sciences et des Techniques Nucléaires  
65, rue Tensift, Rabat Morocco

## Abstract:

A high precision operational amplifier has been developed in a standard  $.8\mu$  CMOS process. A continuous time auto-zero stabilized architecture was used, that leads to a typical input offset voltage less than  $2\mu\text{V} - 100\text{nV}/^\circ\text{C}$ . The amplifier with its output buffer consumes  $5\text{mW}$  at a supply voltage of  $\pm 2.5\text{V}$ . The gain bandwidth product is  $2\text{MHz}$  while the slew rate is respectively  $-6\text{V}/\mu\text{s}$  and  $+8.8\text{V}/\mu\text{s}$  on  $10\text{pF}$  with  $10\text{k}\Omega$  load. This amplifier is suitable for the control of large dynamic ( $>10\text{E}5$ ) calibration signal, and for very low signal instrumentation.

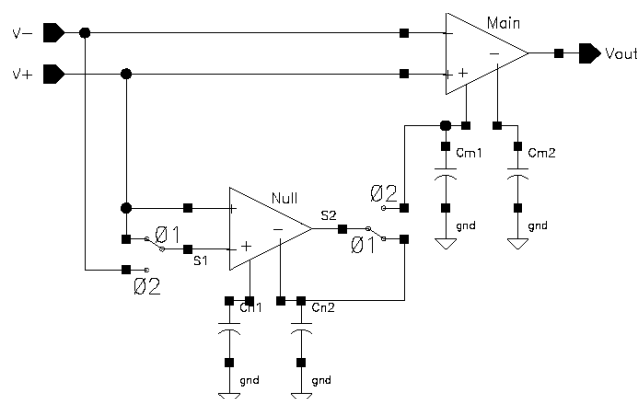


figure 1: Auto zero amp, block diagram

## I) INTRODUCTION

Offset is a very important parameter for many applications: high energy physics calibration systems, low signal sensor interfaces, high accuracy instrumentation. A careful layout design could be combined with internal trimming to reduce the offset from a few mV down to around  $100\mu\text{V}$ . The screening steps required for such a strategy could take a long time and consequently would be very expensive. Moreover, in many applications, one has a concern with the offset drift (with the time, temperature, power supply etc..).

Therefore auto-zero stabilization architecture is a more efficient and elegant solution to the offset cancellation. CMOS technology is suitable for such a design, due to its analog switch capabilities, lower power architectures and low cost.

In this paper, is presented the design of an auto-zero amplifier in a CMOS standard process using a folded cascode architecture.

## II) AUTO-ZERO AMPLIFIER: OVERVIEW

A continuous auto zero amplifier requires two internal amplifiers. The block diagram is shown in figure 1. The so called 'Main amplifier' is unswitched and continuously available for the incoming signal amplification.

There are two alternating successive phases for the offset cancellation. During the first one, the 'Null' amplifier is disconnected from the signal path for its auto correction. A correction signal  $V_{cn}$  is generated and held on  $C_n$  external capacitors connected at the the auxiliary inputs.

During the second phase, the Null amplifier is reconnected to the Main and senses its input offset. Another correction voltage  $V_{cm}$  is generated this way and stored on capacitor  $C_m$  for the Main amplifier correction.

Each internal amplifier could be modeled with two differential inputs: a primary and an auxiliary one as in figure 2 .

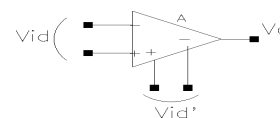


figure 2 Internal amplifier model

The output signal can be expressed as:

$$V_o(s) = A(s) \cdot V_{id} + A'(s) \cdot V'_{id} + A(s) \cdot V_{os}$$

With the assumption that the primary and auxiliary inputs are combined in the first stage of the amplifier, their respective dominant poles will be very closed. Then we could define a constant ratio  $\alpha$  between the open loop gains:

$$\alpha = A_0(s) / A'(s)$$

Consider now the full auto-zero amplifier in a feedback loop as in figure 3 ,where  $V_{osm}$  and  $V_{osn}$  are respectively the

residual offset of the Main and Null internal amplifiers. During phase  $\phi_1$ ,  $S_1$  short-circuit the Null amplifier and its output charges the capacitor  $C_n$  via  $S_2$  to the  $V_{c_n}$  value .

$$V_{c_n} = -\frac{A_n}{1+A'_n} V_{os_n} + \Delta V_{c_n} \cong -\alpha_n V_{os_n} + \Delta V_{c_n}$$

$\Delta V_{c_n}$  is a perturbation voltage related to the charge injection , noise etc..

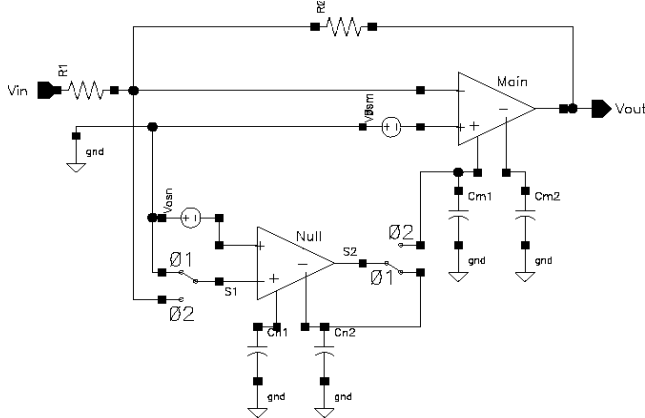


Figure:3 Simulation configuration

During the phase  $\phi_2$ , the Null amplifier senses the offset of the Main and stores the resulting control voltage  $V_{cm}$  on the capacitor  $C_m$ .

In a feedback configuration as shown in figure 3 one obtains  $V_{out} = A_m(V^+ - V^- - V_{os_m}) + A'_m V_{c_m}$  and

$$V_{c_m} = A_n(V^+ - V^- - V_{os_n}) - A'_n V_{c_n} \cong A_n(V^+ - V^-) - \alpha_n V_{os_n} - A'_n \Delta V_{c_n}$$

In the case  $V_{out}=0$  and  $V_+ - V_- = Vos(2)$  (offset during the phase  $\phi_2$ ), one can deduce

$$V_{os}(2) \cong \frac{\alpha_m V_{os_m} + \alpha_n V_{os_n}}{A_n} + \frac{\Delta V_{c_n}}{\alpha_n}$$

with (  $A_n A'_m \gg A_m$  )

During the next  $\phi_1$  phase, the offset will become.

$$V_{os}(1) = V_{os}(2) - \frac{\Delta V_{c_m}}{\alpha_m} \text{ leading into:}$$

$$V_{os}(1) = \frac{(\alpha_m/\alpha_n)V_{os_m} + V_{os_n}}{A'_n} + \frac{\Delta V_{c_n}}{\alpha_n} - \frac{\Delta V_{c_m}}{\alpha_m}$$

After many iterations of phases  $\phi_1$  and  $\phi_2$  the offset will decrease progressively; its maximum value is:

$$V_{os}^{max} = \frac{a V_{os_m}^{max} + V_{os_n}^{max}}{A'_n} + \frac{\Delta V_{c_n}}{\alpha_n} + \frac{\Delta V_{c_m}}{a \alpha_n}$$

where  $a = \alpha_m/\alpha_n$  . It could be shown that the optimum offset value is reached when  $\alpha_m$  and  $\alpha_n$  are defined as:

$$\frac{\alpha_m}{\alpha_n} = \sqrt{\frac{\Delta V_{c_m} \cdot V_{os_n}^{max}}{\Delta V_{c_n} \cdot V_{os_m}^{max}}} \quad \text{and} \quad \alpha_n = \sqrt{\frac{A_n \Delta V_{c_n}}{V_{os_n}^{max}}}$$

### III) INTERNAL AMPLIFIER

The schematic of each of the internal amplifiers is shown in figure 4. The general architecture is the folded cascode which provides a high open loop dc gain.

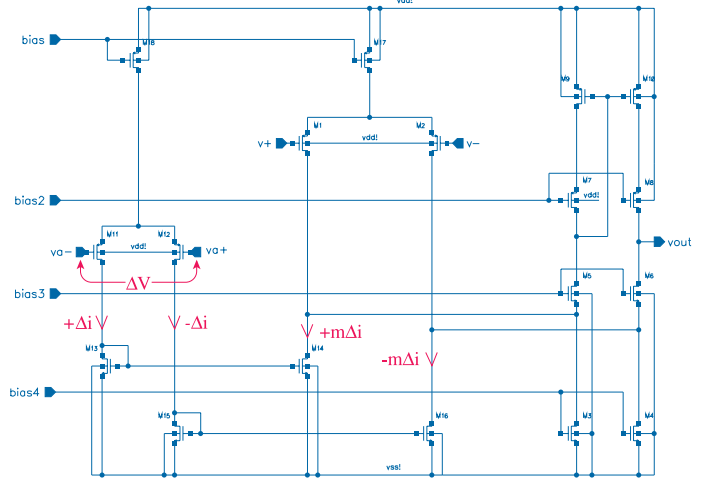


Figure 4: Internal amplifier schematic

The offset depends on how well the quiescent current is balanced through the input differential stage. This balance is controlled via the auxiliary inputs ( $V_{a+}$ ,  $V_{a-}$ ). To improve the bandwidth, a high-swing cascode current mirror is used in the amplification stage ( $M_7$ – $M_{10}$ ).

An additional common source output stage has been added to the Main amplifier to enhance its driving capability: the output impedance of such a buffer was found around  $400\Omega$ . The open loop gain (from the primary inputs to the buffer output) is more than 100dB.

The auto zero architecture shown in figure 3 has been simulated in the following configuration:

- feedback gain =100
- initial offset to be compensated =  $\pm 10\text{mV}$
- Clock frequency = 100Hz

This simulation demonstrates how the compensation is performed step by step until the offset is closed to noise.

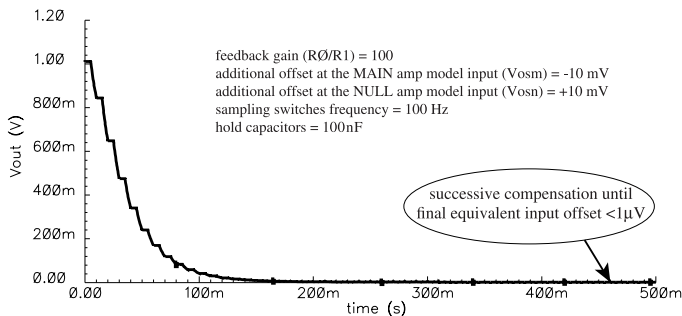


Figure 5: offset compensation step by step

#### IV) EXPERIMENTAL RESULTS

This amplifier has been designed in a standard  $.8\mu\text{m}$ . process, and produced via a multi project center. 5 prototypes have been tested. The mean value found for the offset is less than  $2\mu\text{V}$ .

An evaluation of the drift with the temperature is shown in figure 6. Neither the min nor the max characteristic is linear. But one could see a medium value for the drift around  $100\text{nV}/^\circ\text{C}$ .

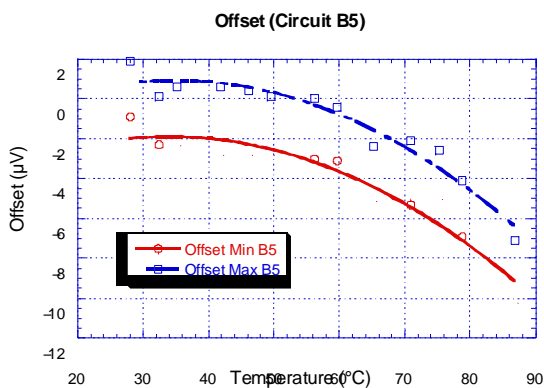


Figure 6: Offset drift with the temperature.

Figure 7 shows the equivalent input noise voltage spectrum measured while the total power dissipation was set at  $5\text{mW}$  (including the output buffer), and the supply voltage was  $\pm 2.5\text{V}$ .

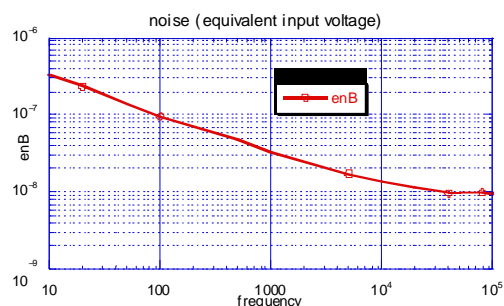


Figure 7: Equivalent input noise voltage.

We show the large signal pulse response in the following figures 8 and 9, where the feedback gain was set to 10, on a  $10\text{K}\Omega/10\text{pF}$  load.

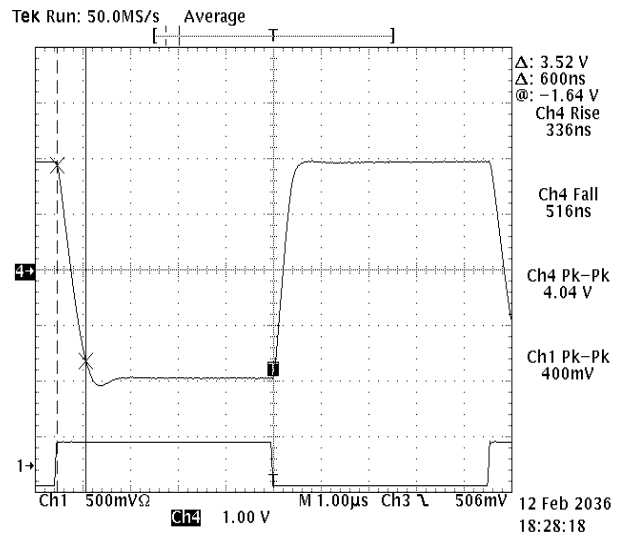


Figure 8: Negative Slew-rate= $6\text{V}/\mu\text{s}$

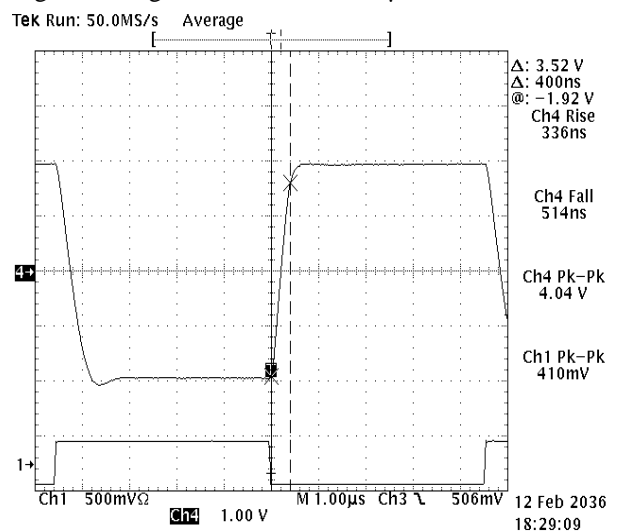


Figure 9: Positive Slew-rate =  $8.8\text{V}/\mu\text{s}$

#### IV) CONCLUSION

We have described the architecture of an auto-zero amplifier. Very promising results for the first prototypes are presented. This circuit is an important cell which will be used in the next future to develop a large dynamic integrated calibration circuit.