The Readout Driver for the ATLAS Muon Endcap Trigger and its architecture and design language techniques

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Muon Endcap trigger chambers (TGC) readout for 1 of 16 octants



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Input data characteristics

- 100 KHz L1A rate on 13 links \rightarrow many small messages
- Data dominated by cavern background, but still low occupancy:
 - ~10 uncorrelated hits per octant per L1A
 - ~1.5 charged particles per octant per L1A giving correlated tracklets
 - huge uncertainty in simulation of cavern background \rightarrow safety factor of 10 needed
 - input data is partially zero-suppressed so dominated by headers
 - → headers needed to confirm synchronization of all trigger-readout ASICs
- Zero-suppression \rightarrow variable length records
- Data includes output from trigger logic stages: on-chamber coincidence ASICs, HipT ASICs and Sector Logic
- Estimate input bandwidth of 22MB/sec per octant, without safety factor
- Tracklets (2-out-3, 3-out-of-4 coincidences from correlated background and real muons!) are needed to monitor the coincidence logic

ROD – required functions

- Receive TTC information and queue expected event L1A IDs
- Collect event fragments from several Front End links corresponding to each of the L1A Event IDs
- Detect and recover from input link errors and data errors
- Assert RODBUSY to the ATLAS CTP module when necessary, but as infrequently as possible
- Extract hit and trigger data from zero-suppressed bit map
- Provide sampled full events, hits and tracklets to the ROD Crate Processor for monitoring the system
- Format events into ATLAS standard ROB format
- Send the data to the ROB and/or Rod Crate Processor
 - Respond to flow control signals from the ROB
- Requirements for calibration and monitoring

TGC ROD prototype block diagram



- Xilinx extra memory Virtex FPGA, 405EM
- VME 6U
- 3 programmable clocks
 any frequency 1–100MHz using PLL
- 4 daughter boards for FE links
 - G-link + opto-transceiver
 - S-link compatible connector and mechanics
 - Optional TX chip on the board
- 1 S-Link connector for ROB connection
- LVDS or NIM inputs for TTC signals
- General enough architecture to use also as source of simulated data for testing
- 1MB ZBT SRAM
 - not yet needed or used (yet) for ROD
 - used by xmitter for fake event store
- 3.3V, 1.8V power generated on the board from 5V
- Service PLD



Main relevant features of Virtex FPGA

- XCV405EM: 'extra memory', today: 'moderate size'
- 10800 logic cells, i.e. flip-flops
- Large amount of embedded, "block", dual port RAM
 - 70KB (140 × $\frac{1}{2}$ KB width-configurable RAM blocks)
- 4 global clocks and 8 DLLs
- Low skew lines for clocks from each G-link deserializer
- Logic Cells can also be used as dual port memory (16x1 each)
- Abundant routing resources allow wide (16 and 32 bit) data paths



Architectural elements

Design implemented using:

- graphic tools that produce VHDL
- VHDL
- Xilinx cores for FIFOs
- Handel-C with VHDL output

Synthesized together by Leonardo

Handel-C – overview

- C syntax
 - Variables and arrays are registers, or memory (internal or external)
- Additions from Occam language for Transputers:
 - par/seq indicate blocks of statements to be executed in parallel or in seq
 - channels for thread-to-thread synchronization via passing messages
 - thread of first chan I/O is suspended until second thread executes chan O/I, then xfer takes place (in one clock) and both threads continue
- Easy to make large number of variable latency parallel threads & synchronize them
- timing model: Every assignment takes one and only one clock
- advantages
 - hi level. can express procedures easily, forces synchronous design
 - rich macros help create multiple instances of HW
 - recursive macros enable building repetitive structures
- still not for linear sequential software programmers
 - need to understand the specific FPGA architecture, HW concurrency, how structures and algorithms synthesize, timing constraints
- produces VHDL or EDIF, can interface to VHDL and Xilinx cores

Embedded FIFOs

- Allow pipeline with stages with variable latency
 - Each pipeline stage has fluctuations in its execution time and amount of output
 - Unlike a registered pipeline where each stage is one clock
- FIFOs bridge different clock domains:
 - One domain per Front End link: deserializer output clock. Defined: 40MHz
 - Main design clock: rate is a parameter: depends on design's longest path
 - S-Link output: defined maximum of 32MHz
 - TTC: 40MHz
 - VME: undefined and asynchronous
 - All inside one FPGA means FIFOs must be embedded in FPGA
- Different FE links can have different input FIFO depths, depending on the occupancy of the chambers read out
- All internal FIFO occupancies readable via VMEbus for monitoring
 - resolution of one item

Variable length data records in FIFOs

- Zero-suppression means variable length records
- Better design if data readers know in advance how much data they will read per fragment
- Use a 2nd control FIFO
 - Write N data words to the data FIFO
 - Write "N" and any flags to the control FIFO
- Reader waits for available item in the control FIFO
- (almost) all FIFOs in the ROD design are data/control FIFO pairs

Thread-to-thread pipes

- Thread-to-thread communication
 - Extension of channels to depth of more than one item
- All FIFOs in the ROD design implemented by a "pipe" object:
 - Can read and write on every clock
 - Read-on-empty and full-on-write conditions block (stall) the invoking thread until not-empty or not-full.
 - Writes intended to execute on the same clock as the pipe xfer are guaranteed to do so:
 - Stall **after** write if FIFO now full
 - E.g. par {pipe_write(hitpipe, hitid); hitid++;}
 (example of instantiating a counter)
 - Can test empty, full and count anytime
 - Can generate Service Call to host CPU on ~empty, almost-full
 - Could histogram count for occupancy monitor

Multiple "execution units" – fragment farm

- Data volume varies from link to link and from event to event
- 13 links but need only ~4 fragment processors (FP) for required throughput
- Can instantiate *n*<13 fragment processors for 13 links
- Each fragment processor is a separate thread
 - implemented in Handel-C by 'array of functions'
- Dispatcher thread allocates each fragment to a fragment processor on the-fly
 - Use one channel per FP to receive link ID of fragment to process
 - Use another channel to acknowledge completion/ready-for-more
 - One output FIFO per fragment processor
- Another thread receives the acknowledges and updates list of free FPs
- Reduces silicon resources: number of FIFOs and logic cells
- Requires multiplexing sources to FPs, but

reduces multiplexing from FPs to output FIFO

Service calls – SVCs

- Send a signal from FPGA HW thread to a SW process on host CPU
 - Different signal IDs for different HW thread SW process pairs
- Exceptional conditions requiring host CPU intervention
 - e.g. FIFO almost full or unrecoverable loss of event synchronization
- Allows any number of outstanding SVCs, but only one of each type
- Scenario
 - Polling loop over all conditions posts SVCID to VME register
 - Use **chan** to serialize posting
 - Interrupt host CPU
 - host interrupt handler reads SVCID and acks by clearing SVCID reg
 - host interrupt handler sends signal to process subscribed to this SVCID
 - host interrupt handler is now ready for another SVC
 - Process performs service, e.g. empties FIFO
 - Process writes "done" acknowledge for this SVCID to SVCACK reg
 - This SVCID can now be issued again

FPGA-to-host CPU pipes

- Some pipes have their read port on the VMEbus
 - Sampled full event, hit, tracklet and message pipes
 - Host interrupted by Service Call on ~empty or almost-full
 - SVCID indicates which pipe needs service
- Exceptions, messages and debug info
 - Message pipe is written with severity/exception code and 3 bytes of data
 - Each exception is counted, logged & perhaps serviced by the host SW
 - Processes can dump values for debugging
 - Writes to this pipe can be put anywhere in a thread
 - soon: add arbitration to serialize writes from different threads

Handel-C – advantages

- More advantageous when:
 - Processing path depends on data content
 - Design needs to be frequently adapted to demand for functionality or changing requirements
 - Ultimate performance not paramount
 - Complex arithmetic or logical algorithms
 - Many special cases and possible exceptional conditions or errors
- Less advantageous when:
 - Pipelines with fixed length of data \rightarrow deterministic latency
 - Pipeline stages are of fixed length, e.g. single clock
 - Few, or only simple, sequential data dependencies
 - i.e. mostly, operations are done in parallel

Integration and performance

ROD in the TGC Slice Test in Japan -- Nov 2001





Online Software

- Pentium SBC running Linux in VME crate (Universe chip)
 - ATLAS VME driver
- ATLAS online system packages implemented
 - Run Control and Process Manager
 - Error message utility
 - Information Service: dataflow statistics error counts
 - IGUI
 - DAQ to DCS communication
 - configuration of FE electronics parameters and thresholds at Start-of-Run
 - simple use of configDB
- full readout path using KLOE buffer manager to event format checker and smart dump

Trigger rate performance



- Used fake events from a realistic simulation using average occupancies from FLUKA simulation 'AV5' (by I. Dawson)
- uncorrelated (neutral)
 & correlated (charged)
 background
- 2 Front End links processed in series on 1 fragment processor
 - both strips & wires

Final prototype ROD



The end Bon appetit!