# CONFIGURATION OF COIL ENDS FOR MULTIPOLE MAGNETS $\dagger$ 

L. JACKSON LASLETT, S. CASPI, and M. HELM<br>Lawrence Berkeley Laboratory, University of California, Berkeley, CA 94720

(Received October 15, 1986)


#### Abstract

Configurations are proposed and illustrated for terminating the "cosine $\phi$ " windings of an ideal ironfree dipole magnet so as to preserve the quality of the internal field integrated (vs $z$ ) through the entire magnet. The end windings are placed on a cylindrical surface of the same radius as that on which the conductors lie in the central (2-D) portion of the structure. The desired pure dipole quality of the integrated field is then assured by requiring that the $z$-component of current, after projection onto the $y-z$ plane, shall have in that plane a density distribution whose integral is independent of $y$. As a result of the analysis, end-winding configurations that satisfy this requirement are proposed in which each conductor filament follows through the end region a locus whose $y-z$ projection is of the form $z\left(y ; y_{0}\right)=f\left(y_{0}\right)-f\left(y-y_{0}\right)$, with $f(0)=0$, wherein $y_{0}$ serves as an index to identify the location of the filament in the central (2-D) portion of the structure. Simple solutions of this nature are indicated in which the function $f$ has the form $f\left(y-y_{0}\right)=k\left[\left(y-y_{0}\right) / a\right]^{p}$ for windings on the surface of a cylinder of radius $a$, with $p<1$ (and preferably $p \leqq \frac{1}{2}$ ) to ensure a smooth transition into the end region. The straightforward extension of these results to configurations for the production of integrated fields of higher multipolarity is also indicated.


## 1. INTRODUCTION

Two-dimensional magnet designs are well-known in which at any radius the density of axial current ideally is continuously proportional to the cosine of a multiple ( $m$ ) of the azimuth angle. The resulting internal magnetic field is then characterized by a $z$-directed vector potential that is likewise directly proportional to $\cos m \phi$. (Thus, with $m=1$ we obtain a constant, $y$-directed magnetic field; for $m=2$, a pure quadrupole field; etc.) The issue of interest here concerns the ways in which the windings may be terminated at the ends of such a 2-D design in order that the integrated field (integrated through and beyond the full 3-D structure) shall retain the desired harmonic purity. It is the intention that, in this examination, the termination windings shall be restricted to the radius (or radii) that they individually occupy in the 2-D portion of the design. Under these conditions, the magnetostatic problem for the integrated field becomes reduced to a 2-D problem in which the source distribution at the winding radius is given explicitly in terms solely of the longitudinal integral of the axial component of the current (presuming we may assume the longitudinal invariance of any surrounding highly permeable ferromagnetic shell that may be present). ${ }^{1}$

[^0]It will be recognized that the windings of typical large magnet structures, including some superconducting designs now under consideration, may be formed in practice from a limited number of current blocks (of different angular extent), separated by wedges (each of suitable angular extent) that carry no current. Adjustment of the available angular parameters of such a discrete design then can serve to suppress to zero (or to acceptably small values) a certain number of undesired Fourier components of the current distribution, and thus correspondingly to suppress the associated multipole harmonics in the integrated magnetic field. The means for suitably terminating the individual winding blocks of such a discrete design can be guided only qualitatively by the analysis to be presented here, but a multiblock design can benefit from the opportunity to commence the termination of the separate blocks individually at suitably chosen distinct longitudinal locations. The treatment of continuous winding distributions, as considered specifically here, may thus in practice find its direct application chiefly in the design of terminations for correction windings (e.g., to the design of short-circuited, superconducting, self-correction coils, or possibly in the use of printed-circuit techniques). Such applications may then most frequently relate to windings of higher than dipole (or quadrupole) multipolarity.

## 2. GEOMETRIC DESCRIPTION

We shall commence with an examination of the manner in which one may undertake the termination of " $\cos \phi$ " windings, so as to preserve the pure dipole character of the integrated internal field. We accordingly require that the longitudinal integral of the current shall have the same azimuthal dependence as the ideal azimuthal distribution employed in the 2-D portion of the design. It is convenient in this case to describe explicitly the character of suitable solutions by specifying the locations of filament loci in the end regions when viewed in a transverse projection onto the $y-z$ plane (Fig. 1).
In such a $y-z$ projection, we require that the $z$-component of current shall have, in that plane, a density distribution whose integral is independent of $y$, since


FIGURE 1 The $y-z$ projection of an illustrative termination for an integrated dipole field. The transition region lies between $z_{F}$ and $z_{s}$, and within that region the loci of individual current filaments are represented by $z\left(y ; y_{0}\right)$. A representative path of integration at constant $y$ is illustrated here for $y / a=0.4$. The path of integration extends from $z_{F}(y)$ (corresponding to $\left.y_{0} / a=0\right)$, through $z_{s}(y)$ (corresponding to $y_{0}=y$ ), to the reference plane $z=z_{p}$. The filament loci shown here were drawn specifically for a type of transition considered in detail in Section 3.2.2, with $p=\frac{1}{2}$ and $k=1.5 a$.
the factor $d(a \phi) / d y=1 / \cos \phi$ transforms the reference $\cos \phi$ distribution into a constant density with respect to the projected coordinate $y=a \sin \phi$. Solutions for such projected loci, $z\left(y ; y_{0}\right)$, for windings situated on a radius $a$ in the end regions, are discussed in the following section. Such solutions can then be equivalently expressed, if desired, in terms of an alternative projection of the current filaments onto a "developed" (or $w-z$ ) view (e.g., Fig. 3, below). As will be noted later, solutions expressed in this latter form can conveniently be generalized to provide analogous means for terminating the $\cos m \phi$ windings of structures designed to provide fields of higher multipolarity.

## 3. TERMINATION OF THE $\cos \phi$ WINDINGS OF DIPOLE MAGNETS

### 3.1. Analysis

In the straight (2-D) portion of a $\cos \phi$ winding, $d I / d(a \phi)=J_{z_{0}} \cos \phi$ with $J_{z_{0}}=$ constant. With $y=a \sin \phi$, the $z$-component of current density, when viewed in the $y-z$ plane, then assumes the constant value $d I / d y=J_{z_{0}}$, independent of $y$, in the 2-D region. As we have noted previously for the termination of $\cos \phi$ windings, the current filaments shall, accordingly, be so disposed in the end regions that in a $y-z$ projection the $z$-component of current shall have in that plane a density distribution whose integral, vs $z$ at constant $y$, is independent of $y$. The loci of such end windings may be described in this projection by a function $z\left(y ; y_{0}\right)$, where $y_{0}$ serves as an indexing parameter to denote the value of $y=a \sin \phi$ at which the filament under consideration originates in the 2-D portion of the assembly. Such a filament departs from the straight region at $z_{s}\left(y_{0}\right)=z\left(y_{0} ; y_{0}\right)$. The integration of $J_{z(\text { Projected) }}$ extends in the transition region at constant $y$ between $z_{F}(y)=z(y ; 0)$ and $z_{s}(y)$, and continues in the straight region to some reference location $z_{p}$ (Fig. 1).

We thus require that

$$
\int_{z_{F}}^{z_{s}} \underbrace{}_{\text {at } y \text { const }} J_{z(\text { Projected })} d z+\left(z_{p}-z_{s}\right) J_{z_{0}}
$$

shall be constant (independent of $y$ ).
By noting that at $y=0$ we may make the identification $z_{F}=z_{s}=0$, we can then identify the constant mentioned above as having the value $z_{p} J_{z_{0}}$. As a result we may write the requirement in the simple form

$$
\int_{z_{F}}^{z_{s}} \underbrace{J_{z(\text { Projected) }}}_{\text {at } y \text { const }} d z=z_{s} J_{z_{0}},
$$

identically in $y$.
For the integration at constant $y$ through the transition region, the value of $J_{z \text { (Projected) }}$ differs from the constant projected value in the 2-D region by the factor $\partial y_{0} /\left.\partial y\right|_{z \text { const }}$. The requirement for an integrated dipole field thus becomes
expressed explicitly as

$$
\int_{z_{F}}^{z_{s}} \underbrace{\left.\frac{\partial y_{0}}{\partial y}\right|_{z \text { const }}}_{\text {at } y \text { const }} d z=z_{s}
$$

identically in $y$. (We note that in the course of the integration, at a constant value of $y$, the value of $y_{0}$ at which the integrand is evaluated ranges from $y_{0}=0$ to $y_{0}=y$.) It is convenient to rewrite the requirement exhibited above in terms of an integral in which $y_{0}$ serves as the variable of integration. We note that

$$
\left.\frac{\partial y_{0}}{\partial y}\right|_{z \text { const }}=-\left[\left.\frac{\partial z}{\partial y}\right|_{y_{0} \text { const }}\right] /\left[\left.\frac{\partial z}{\partial y_{0}}\right|_{y \text { const }}\right]
$$

so that the requirement of interest becomes

$$
\int_{y_{0}=0}^{y_{0}=y}\left[-\left.\frac{\partial z}{\partial y}\right|_{y_{0} \text { const }}\right] d y_{0}=z_{s},
$$

identically in $y$.
We now propose a solution of the form $z\left(y ; y_{0}\right)=z_{s}\left(y_{0}\right)-f\left(y-y_{0}\right)$ for any particular filament (characterized by the "index" $y_{0}$ ) in the transition region. We shall take $f(0)$ to be zero in the interests of continuity and, to avoid "kinks," it will be desirable that $1 / f^{\prime}(0)=0$. For a function of this form,

$$
-\left.\frac{\partial z}{\partial y}\right|_{y_{0} \text { const }}=f^{\prime}\left(y-y_{0}\right)
$$

and the integral relation written at the conclusion of the preceding paragraph becomes

$$
\begin{gathered}
\int_{y_{0}=0}^{y_{0}=y} f^{\prime}\left(y-y_{0}\right) d y_{0}=z_{s}, \\
-\left.f\left(y-y_{0}\right)\right|_{y_{0}=0} ^{y_{0}=y}=z_{s},
\end{gathered}
$$

or

$$
f(y)=z_{s} .
$$

We have thus only to require that $z_{s}(y)=f(y)$ [and, correspondingly, $z_{s}\left(y_{0}\right)=$ $f\left(y_{0}\right)$ ] and write the solution as

$$
z\left(y ; y_{0}\right)=f\left(y_{0}\right)-f\left(y-y_{0}\right)
$$

The transition region is bounded by

$$
z_{s}(y)=f(y)
$$

and by

$$
\begin{aligned}
z_{F}(y) & =z(y ; 0) \\
& =-f(y) \\
& =-z_{s}(y)
\end{aligned}
$$

resulting in boundary curves that are symmetrically situated about $z=0$.

### 3.2. Examples

For solutions of the type suggested in the preceding section, one may choose the function $f$ with considerable freedom [but subject to the constraint $f(0)=0$ ]. The transition region at $y$ then lies between the symmetrical limits $z_{F}(y)=-z_{s}(y)$ and $z_{s}(y)$, where $z_{s}(y)=f(y)$. Within that region, individual current filaments characterized by an index parameter $y_{0}$ are described by $z\left(y ; y_{0}\right)=f\left(y_{0}\right)-f(y-$ $y_{0}$ ).

We present below several examples of such solutions that provide an integrated internal field of a pure dipole character. In each such case, the description of the specific termination is initially introduced with respect to the $y-z$ projection of filament loci, as specified by the function $z\left(y ; y_{0}\right)=f\left(y_{0}\right)-f\left(y-y_{0}\right)$. For each case, it is possible and informative also to specify transition loci in a "developed" ( $w-z$ ) plane. By this development, we mean a development of the cylindrical surface $r=a$ (on which the windings lie), centered about the polar location $\phi=\pi / 2$ or $y=a$, so that, with

$$
\begin{aligned}
y & =a \sin \phi \\
w & =a\left(\frac{\pi}{2}-\phi\right)
\end{aligned}
$$

or

$$
\cos w / a=y / a
$$

filament loci in the transition region may be described by

$$
z=f\left(a \cos \frac{w_{0}}{a}\right)-f\left(a \cos \frac{w}{a}-a \cos \frac{w_{0}}{a}\right) .
$$

The development associated with transformation from circumferential location $a \phi$ on the circular cylinder to the developed plane is distortion free, since $|d w / d(a \phi)|=1$.
3.2.1. The Lambertson-Coupland termination. This termination, although characterized by a distinct kink imposed on the windings at the onset of the termination, is of a simple character described elsewhere. ${ }^{2}$ In this example, the
function $f$ is such that

$$
\begin{aligned}
z_{s} & =\frac{y}{\tan \alpha}, \\
z\left(y ; y_{0}\right) & =\frac{y_{0}}{\tan \alpha}-\frac{y-y_{0}}{\tan \alpha} \\
& =\frac{2 y_{0}-y}{\tan \alpha}
\end{aligned}
$$

(That this disposition of windings satisfies the desired condition for the integral of $J_{z}$ is evident directly from the $y-z$ projection of Fig. 2a; in that projection, the $z$-component of current density within the transition region becomes modified by the factor $1 / 2$, which is precisely compensated by the longitudinal interval required for the $z$ integration to the coil edge at $z_{F}$.)

The equation for filament loci in the developed $w-z$ plane is obtained immediately by the substitution $y=a \cos w / a$ :

$$
z=\frac{\left(2 \cos w_{0} / a-\cos w / a\right) a}{\tan \alpha}
$$

with the limiting locus (for a filament originating virtually in the median plane $\phi=0$ and shown by a dashed line on Fig. 2b) described in that region by

$$
z_{F}=-\frac{a \cos w / a}{\tan \alpha}
$$

(a)


FIGURE 2 (a) Lateral $(y-z)$ projection of current windings situated on the surface of a circular cylinder of radius $a$, for the Lambertson-Coupland termination (drawn for $\alpha=52.5^{\circ}$ ). The reference surface-current density of $z$-directed currents is proportional to $\cos \phi$ on the surface of the cylinder; such currents appear to have a constant density in this projection, since $d(a \sin \phi) / d(a \phi)=\cos \phi$. (b) Developed ( $w-z$ ) projection of some current windings for the same Lambertson-Coupland termination.


FIGURE 2 (contd.)
3.2.2. Terminations employing the function $f(y)=k(y / a)^{p}$. Terminations of the type defined by

$$
z_{s}(y)=f(y)=k(y / a)^{p},
$$

with

$$
z\left(y ; y_{0}\right)=k\left[\left(\frac{y_{0}}{a}\right)^{p}-\left(\frac{y-y_{0}}{a}\right)^{p}\right]
$$

include, as a special case $(p=1)$, the Lambertson-Coupland termination described in the preceding example. By imposition of the restriction $0<p<1$, one can avoid the discontinuity of slope that, in the Lambertson-Coupland termination, was experienced by current filaments at the point of entry into the transition region. Although, in the work that follows, we shall make some reference to cases for which the index $p$ is close to unity, it will be recognized that it can be advisable to restrict this index to the range $0<p \leqq 1 / 2$ in order to avoid an infinite curvature for the filament loci immediately upon their entry into the transition region. With $-\Delta z \propto(\Delta y)^{p}$, we can write $\Delta y \propto(-\Delta z)^{1 / p}$ and $(\Delta y)^{\prime} \propto$ $(-\Delta z)^{(1 / p)-1}$, so that the restriction $0<p<1$ suffices to ensure that $(\Delta y)^{\prime} \rightarrow 0$ as $|\Delta z| \rightarrow 0$. Because $(\Delta y)^{\prime \prime} \propto(-\Delta z)^{(1 / p)-2}$, however, the further restriction $p \leqq 1 / 2$ appears desirable so that the curvature will remain finite as $|\Delta z| \rightarrow 0$.

The $y-z$ projection shown in Fig. 1 illustrates a termination of the type considered here, with $p=1 / 2$ and $k=1.5 a$. The substitution $\cos w / a=y / a$ leads to the specifications for constructing the developed $w-z$ view (Fig. 3):

$$
\begin{aligned}
& z_{s}=-z_{F}=k(\cos w / a)^{1 / 2} \\
& z=k\left[\left(\cos \frac{w_{0}}{a}\right)^{1 / 2}-\left(\cos \frac{w}{a}-\cos \frac{w_{0}}{a}\right)^{1 / 2}\right] .
\end{aligned}
$$



FIGURE 3 Developed view ( $w$ vs $z$ ) of the termination for which a $y-z$ projection was shown as Fig. $1 ; z_{s}(y)=-z_{F}(y)=f(y)=k(y / a)^{1 / 2}$, with $k=1.5 a$, while $\cos w / a=y / a$. The boundaries of the transition region for this case form a nearly circular curve in this developed view (see text).


FIGURE 4 Side projections, $y$ vs $z$, of terminations for which $z_{s}(y)=(y / a)^{p}$, using $p=0.25,0.50$, 0.75 , and 1.00 , and with $k=2$. With $p=1.0$, the configuration assumes the form of the Lambertson-Coupland termination.

It is seen from Fig. 3 that the case illustrated there is such that the boundaries of the transition region together form a nearly circular curve-as a result of the choice $k / a=1.5(\cong \pi / 2)$.

For the type of termination considered in the present example, there is no choice of the parameters ( $p$ and $k / a$ ) that will result in the boundaries of the transition region having a precisely circular form in a developed view. We will demonstrate below, however, that a design in which these boundaries do have a circular form can be constructed, if desired, which differs only slightly from a design of the present type (with $p=1 / 2$ and $k / a=\pi / 2$ ).

To conclude the present discussion of terminations defined by $z_{s}(y)=f(y)=$ $k(y / a)^{p}$, we present a sequence of diagrams to illustrate such terminations for $p=0.25 . p=0.50, p=0.75$, and $p=1.00$. Such figures show, for each case, (i) a side projection (Fig. 4, $y$ vs $z$ ), (ii) a top projection (Fig. 5, $x=\sqrt{a^{2}-y^{2}}$ vs $z$, not a $w-z$ developed view), and (iii) an isometric view (Fig. 6). The appearance of a kink in the windings will be evident for $p>1 / 2$ at the points of entry into the transition region. We are indebted to R. S. Digennaro for the preparation of these diagrams.


FIGURE 5 Top views, $x$ vs $z$, of the terminations for which side projections are shown in Fig. 4.


FIGURE 6 Isometric views of the terminations shown by the projected views of Figs. 4 and 5.
3.2.3. Termination with a circular (or elliptical) boundary in the developed view. We noted previously that (as illustrated by Fig. 3) a termination of the type defined by

$$
\begin{aligned}
z_{s}(y)=-z_{F}(y)=f(y) & =k(y / a)^{1 / 2} \\
& =k\left(\cos \frac{w}{a}\right)^{1 / 2}
\end{aligned}
$$

results in a boundary for the termination that is approximately circular (or elliptical, depending upon the choice of the longitudinal scale factor $k$ ) in the developed view. Because of the freedom that may be exercised in the choice of the function $f$, however, one may, if desired, so choose this function that the transition will be bounded in this $w-z$ development precisely by a circular or elliptical curve:

$$
z_{s}=-z_{F}=b\left[\left(\frac{\pi}{2}\right)^{2}-\left(\frac{w}{a}\right)^{2}\right]^{1 / 2}=b\left[\left(\frac{\pi}{2}\right)^{2}-\left(\cos ^{-1} \frac{y}{a}\right)^{2}\right]^{1 / 2},
$$



FIGURE 7 Plots in the $w-z$ developed plane of the boundary to the transition region, for (a) $z_{s} / a=(\pi / 2)(\cos w / a)^{1 / 2}$ and (b) for the circular form $z_{s} / a=\left[(\pi / 2)^{2}-(w / a)^{2}\right]^{1 / 2}$, shown only for $w \geqq 0$.
for which the loci of the individual filaments in the $y-z$ projection are now given by
$z\left(y ; y_{0}\right)=b\left\{\left[\left(\frac{\pi}{2}\right)^{2}-\left(\cos ^{-1} \frac{y_{0}}{a}\right)^{2}\right]^{1 / 2}-\left[\cos ^{-1}\left(\frac{y_{0}}{a}\right)^{2}-\cos ^{-1}\left(\frac{y}{a}\right)^{2}\right]^{1 / 2}\right\}$.
Such alternative forms for $z_{s}$ are compared in Figs. 7 and 8. The form

$$
z_{s}=-z_{F}=b\left[\left(\frac{\pi}{2}\right)^{2}-\left(\frac{w}{a}\right)^{2}\right]^{1 / 2}
$$

describes a circular boundary in the $w-z$ developed plane if one makes the assignment $b=a$, as is illustrated by curve (b) in Fig. 7. A similar, but not strictly identical, curve (that also passes through the points $z=0, w / a= \pm \pi / 2$ and $z / a= \pm \pi / 2, w=0)$ is obtained from the form $z_{s}=-z_{F}=k(\cos w / a)^{1 / 2}$ with $k=(\pi / 2) a$, as is illustrated by curve (a) of Fig. 7. Figure 8 depicts these same alternative forms for the boundary $z_{s}$ in the $y-z$ projection.


FIGURE 8 Plots, in the transverse $y-z$ projection, of the boundaries $z_{s}$ illustrated in Fig. 7. These boundaries are described in the present projection by (a) $z_{s} / a=(\pi / 2)(y / a)^{1 / 2}$ and (b) $z_{s} / a=[(\pi /$ $\left.2)^{2}-\left(\cos ^{-1} y / a\right)^{2}\right]^{1 / 2}$. The latter case is such as leads to a circular boundary in the $w-z$ developed plane depicted in Fig. 7.

## 4. TERMINATION OF WINDINGS FOR FIELDS OF HIGHER MULTIPOLARITY

### 4.1. Generalization of the Dipole Results

Methods of terminating 2-D $\cos m \phi$ windings so as to maintain the harmonic purity of the integrated internal field are readily devised by extension of the procedure described earlier for termination of the $\cos \phi$ windings of dipole magnets. As Lambertson has pointed out, this extension may be performed most directly by reference to the $w-z$ development.

With a $\cos m \phi$ winding present in the 2-D region, one chooses as the center for constructing the development of a $w-z$ plane the point $\phi=\pi / 2 m$ (that constitutes one of the "poles" of the 2-D $\cos m \phi$ winding) and writes the developed coordinate $w$ as

$$
w=a\left(\frac{\pi}{2 m}-\phi\right) \quad\left(-\frac{\pi}{2 m} a \leqq w \leqq \frac{\pi}{2 m} a\right) .
$$

(The value of $y$, of course, remains given by $y=a \sin \phi$.) An acceptable type of termination for a $2-\mathrm{D} \cos \phi$ winding, expressible in the form

$$
z=f\left(a \cos \frac{w_{0}}{a}\right)-f\left(a \cos \frac{w}{a}-a \cos \frac{w_{0}}{a}\right) \quad(m=1)
$$

becomes

$$
z=f\left(a \cos \frac{m w_{0}}{a}\right)-f\left(a \cos \frac{m w}{a}-a \cos \frac{m w_{0}}{a}\right)
$$

See Fig. 9 as an illustration of such a termination for a $\cos 2 \phi$ (quadrupole)


FIGURE 9 Illustration of the formation of a developed view for terminating $\cos 2 \phi$ windings so as to preserve the quadrupole character of the integrated internal field.
winding. The boundary of the termination is then represented by

$$
\begin{aligned}
z_{s}=-z_{F} & =f\left(a \cos \frac{m w}{a}\right) \\
& =f(a \sin m \phi)
\end{aligned}
$$

The termination thus obtained in the developed plane is simply a replica of the analogous termination for a $\cos \phi$ winding, scaled down in the $w$ direction by the factor $1 / m$, and identical terminations are also to be constructed about the remaining poles at $\phi=3 \pi / 2 m, 5 \pi / 2 m$, etc.

### 4.2. Confirmatory Calculation

The results just cited for termination of $\cos m \phi$ windings can be checked, if desired, by direct reference to the configuration as described in the $w-z$ plane. To perform such a confirmatory calculation by reference to the $w-z$ plane, we first note that the transformation between $a d \phi$ and $w$ is distortion-free, so that in the $w-z$ plane the reference $J_{z}$ of the 2-D region is proportional to $\cos m \phi$ and hence to $\sin m w / a$. We then need only to verify that in the $w-z$ plane, the projected $J_{z}$ component, upon integration at constant $w$ (constant $y$ ) through the end region (and the approaches thereto), will lead to a result proportional to $\sin m w / a$.

Within the transition region of the $w-z$ plane, the $z$-component of current becomes modified, from the value $J_{0} \sin m w_{0} / a$ that applies at $w_{0}$ in the "straight" (2-D) region, through multiplication by $\partial w_{0} /\left.\partial w\right|_{z \text { const }}$ to become

$$
J_{0}\left(\sin \frac{m w_{0}}{a}\right)\left[\frac{\partial w_{0}}{\partial w}\right]_{z}
$$

The integration at constant $w$ through the transition portion of the end region


FIGURE 10 Sketch illustrating a path of integration, at constant $w$, in the $w-z$ surface. At $z=z_{s}=f(a \cos m w / a), w_{0}=w ;$ at $z=z_{F}=-f(a \cos m w / a), w_{0}=\pi a / 2 m$.
then becomes (see Fig. 10)

$$
\int_{z_{F}}^{z_{s}} \underbrace{J_{0}\left(\sin \frac{m w_{0}}{a}\right)\left[\frac{\partial w_{0}}{\partial w}\right]_{z}}_{\text {at } w \text { const }} d z=\int_{w_{b}=w}^{(\pi / 2 m) a} \underbrace{J_{0}\left(\sin \frac{m w_{0}}{a}\right)\left[\frac{\partial z}{\partial w}\right]_{w_{0}}}_{\text {at } w \text { const }} d w_{0}
$$

and, when supplemented by the integral over the approach to the transition region, provides the total

$$
\begin{aligned}
J_{0}\left(\sin \frac{m w}{a}\right) & {\left[f(a)-f\left(a \cos \frac{m w}{a}\right)\right] } \\
& \quad+\int_{w b=w}^{(\pi / 2 m) a} m J_{0} \sin \frac{m w}{a} \sin \frac{m w_{0}}{a} f^{\prime}\left(a \cos \frac{m w}{a}-a \cos \frac{m w_{0}}{a}\right) d w_{0} \\
= & J_{0}\left(\sin \frac{m w}{a}\right)\left[f(a)-f\left(a \cos \frac{m w}{a}\right)\right] \\
& \quad+\left.J_{0} \sin \frac{m w}{a} f\left(a \cos \frac{m w}{a}-a \cos \frac{m w_{0}}{a}\right)\right|_{w b=w} ^{(\pi / 2 m) a} \\
= & J_{0}\left(\sin \frac{m w}{a}\right)\left[f(a)-f\left(a \cos \frac{m w}{a}\right)\right]+J_{0} \sin \frac{m w}{a} f\left(a \cos \frac{m w}{a}\right)[\operatorname{since} f(0)=0] \\
= & J_{0} f(a)\left(\sin \frac{m w}{a}\right)
\end{aligned}
$$

and hence is found to be proportional to $\sin m w / a$ (as required).

## REFERENCES

1. R. B. Meuser, IEEE Trans. Nucl. Sci. NS-18, 677 (1971).
2. The type of termination suggested by Lambertson arose in consideration of possible magnet designs for the ESCAR project at the Lawrence Berkeley Laboratory. Reference to this suggestion, and to a related Rutherford Laboratory report [J. H. Coupland, RHEL/R 203 (1970)], is made in F. E. Mills and G. H. Morgan, "A Flux Theorem for the Design of Magnet Coil Ends," Particle Accelerators 5, 227 (1973).

[^0]:    $\dagger$ This work was supported by the Director, Office of Energy Research, Office of High Energy and Nuclear Physics, High Energy Physics Division, U.S. Department of Energy, under Contract No. DE-AC03-76SF00098.

