

PEAK VERTICAL FLOOR ACCELERATIONS OF TALL STEEL STRUCTURES

BY

GEORGIAN ADRIAN TUTUIANU  
B.S., University of New Hampshire, 2011

THESIS

Submitted to the University of New Hampshire  
in Partial Fulfillment of  
the Requirements for the Degree of

Master of Science  
in  
Civil Engineering

September, 2019

This thesis/dissertation was examined and approved in partial fulfillment of the requirements for the degree of

Master of Science in Civil Engineering by:

Thesis/Dissertation Director, Dr. Erin S. Bell,  
Associate Professor of Civil Engineering

Dr. Raymond A. Cook, Associate Professor of Civil  
Engineering

Dr. Kyle P. Kwiatkowski, Assistant Professor of  
Civil Engineering

On May 29<sup>th</sup> 2019

Approval signatures are on file with the University of New Hampshire Graduate School.

## ACKNOWLEDGEMENTS

This work was supported by my adviser Dr. Ricardo Medina of the University of New Hampshire as well as the UNH Civil Engineering Department. Over the years the teaching and research assistantships I received were instrumental in allowing me to complete this work. I would like to specifically thank my advisor Dr. Ricardo Medina for his dedication, patience and valuable guidance as well as the rest of my defense committee consisting of Dr. Erin Bell, Dr. Raymond Cook and Dr. Kyle Kwiatkowski. My fellow graduate students also deserve recognition for their well-placed criticism, perspective and ideas. In particular, Miguel Negrete-Padilla, Shokoufeh Zargar, Annika Mathiasson, Antonio Garcia Palencia, and Sam White. I would also like to thank Dr. Farzin Zareian whom I've never personally met but whose work has been essential in helping me to quickly evaluate and successfully iterate the seismic design of my building. Finally, I would like to thank my friends and family who've been supporting me along the way in every non-technical way possible.

## TABLE OF CONTENTS

ACKNOWLEDGEMENTS .....	ii
TABLE OF CONTENTS .....	iii
LIST OF TABLES .....	v
LIST OF FIGURES .....	vii
LIST OF ACRONYMS .....	x
INTRODUCTION .....	1
1.1 Background .....	1
1.2 Importance .....	6
1.3 Objective, Scope and Contribution of This Work .....	11
1.4.1 Response Spectrum Analysis Methods .....	14
1.4.2 NSC Dynamic Characterization through Experimentation and Instrumentation.....	17
1.4.3 Simplified Design Methods Proposed for Building Codes .....	20
1.4.4 Previous Work Overview .....	21
1.5 Vertical Design of NSCs Seismic Provisions per ASCE 7-10 .....	23
20-STORY STRUCTURE DESIGN .....	24
2.1 Introduction.....	24
2.2 Materials .....	26
2.3 Design Loads .....	27
2.3.1 Design Dead Loads .....	27
2.3.2 Design Live Loads .....	28
2.3.3 Live Load Reduction.....	28
2.3.4 Lateral Loads.....	28
2.4 Load Combinations .....	29
2.5 Seismic SMRF E-W Frame Design .....	30
2.5.1 SMRF, Site Properties, Importance Factor & Risk Category .....	30
2.5.2 Design Spectral Acceleration and Design Response Spectrum .....	31
2.5.3 Modal Response Spectrum Analysis.....	33
2.5.4 Perimeter Beam Design.....	37

2.5.5 Reduced Beam Section (RBS) Design .....	43
2.5.6 Perimeter Frame Column Design .....	46
2.5.7 Panel Zone and Doubler Plates .....	56
2.5.8 P- $\Delta$ Effects .....	59
2.6 Gravity System Design .....	62
2.6.1 Gravity Beam Design .....	62
2.6.2 Gravity Column Design .....	65
MODELING AND ANALYSIS .....	68
3.1 Structural Analysis Software .....	68
3.2 Computational Model and Meshing .....	68
3.3 Ground Motion Selection .....	73
3.4 Linear Modal Time History and Response Spectrum Analysis .....	73
RESULTS & DISCUSSION .....	75
4.1 Floor Response Spectra .....	75
4.2 Comparison with Studies on the LA SAC 20-story Structure .....	88
4.3 Evaluation of ASCE 7-10 Design Vertical Acceleration .....	101
CONCLUSION .....	104
5.1 Summary & Final Remarks .....	104
5.2 Future Work Considerations .....	106
APPENDIX A .....	107
A.1 ELF Summary .....	107
A.2 Wind Loading Summary .....	108
APPENDIX B .....	110
APPENDIX C .....	116
APPENDIX D .....	141
LIST OF REFERENCES .....	148

## LIST OF TABLES

Table 1: Three Major Categories of NSCs [1] [2] [3]. .....	3
Table 2: Acceleration or Deformation-Sensitive Components [3]. .....	5
Table 3: Building Material Specification and Properties.....	26
Table 4: Estimated Dead Loads for a Typical Floor.....	27
Table 5: Final Design Dead Loads.....	28
Table 6: Design Response Spectrum as a Function of Fundamental Period. ....	32
Table 7: Effective Modal Mass in the E-W Direction. ....	34
Table 8: Effective Modal Mass in the N-S Direction. ....	35
Table 9: Interior Left Girders of E-W Frame Final Design and Checks. ....	38
Table 10: Interior Right Girders of E-W Frame Final Design and Checks. ....	39
Table 11: Exterior Left Girders of E-W Frame Final Design and Checks. ....	40
Table 12: Exterior Right Girders of E-W Frame Final Design and Checks. ....	41
Table 13: Girders of E-W Frame Seismic Compactness Checks. ....	42
Table 14: E-W Frame Drift Limit Check.....	43
Table 15: RBS Design Coefficients and Factored Moments and Shear. ....	45
Table 16: Demand to Capacity Ratios for the Column Face Moment, Shear and Moment at Center of RBS. ....	46
Table 17: Exterior Column Factored Axial Force, Moment and Governing Axial & Moment Interaction Equation from the AISC Steel Construction Manual [43]. ....	48
Table 18: Exterior Column Final Factored Axial Force with Overstrength Consideration.....	49
Table 19: Exterior Column Seismic Compactness Checks.....	50
Table 20: Strong Column Weak Beam Check for Exterior Columns.....	51
Table 21: Interior Column Factored Axial Force, Moment and Governing Axial & Moment Interaction Equation from the AISC Steel Construction Manual [43]. ....	52
Table 22: Interior Column Final Factored Axial Force with Overstrength Consideration.....	53

Table 23: Interior Column Seismic Compactness Checks.....	54
Table 24: Strong Column Weak Beam Check for Interior Columns.....	55
Table 25: Panel Zone and Doubler Plating of Exterior Columns.....	58
Table 26: Panel Zone and Doubler Plating of Interior Columns. ....	59
Table 27: Stability Coefficient Check.....	61
Table 28: Typical Composite Floor Beam Flexural, Shear and Deflection Checks. ....	64
Table 29: Interior Column Strength Checks. ....	66
Table 30: Interior Column Strength Checks. ....	67
Table 31: Effective Modal Mass Percent in the Z Direction. ....	70
Table 32: Geometric Properties of the Composite Deck from AutoCAD.....	71
Table 33: General FRS Categories. ....	76

## LIST OF FIGURES

Figure 1: (a) Primary structural system (b) Secondary and primary structural systems [2] .....	2
Figure 2: Bookshelf damage from the New Zealand 2010 earthquake [5]. .....	6
Figure 3: Ceiling damage from the New Zealand 2010 earthquake [5]. .....	7
Figure 4: Staircase damage from the New Zealand 2011 earthquake [6]. .....	7
Figure 5: Typical cost breakdown of NSCs, building contents, and structural components [2]. ...	8
Figure 6: E-W and N-S elevation views of the 20-story office building. The special steel moment frames are highlighted in green. ....	25
Figure 7: Plan view of the 20-story office building. The special steel moment frames are highlighted in green. ....	26
Figure 8: Seismic force vs. lateral deformation [47]. .....	30
Figure 9: ASCE 7 design response spectrum [40]. .....	31
Figure 10: Design response spectrum for the office building. ....	33
Figure 11: RBS example with plan view of dimension cuts [51]. .....	44
Figure 12: Critical design sections of RBS moment connection [51]. .....	44
Figure 13: Beams yielding before columns in a three-story building. Figure is modified. [52]. .	47
Figure 14: Panel zone location and forces acting on it [53]. .....	56
Figure 15: Cross-section of composite steel deck [57]. .....	62
Figure 16: Typical gravity floor beam used for design. ....	63
Figure 17: (Top) Cross-section of composite floor deck with ribs perpendicular to steel beam [51]. (Bottom) Cross-section of effective width of W21X68 steel section [51]. ....	64
Figure 18: Tributary area and location of gravity columns. ....	65
Figure 19: Effect of mesh size on the summed total dynamic vertical mass participation. ....	69
Figure 20: Shell element. ....	71
Figure 21: Floor plan of the building with response spectrum curve indicators. ....	74
Figure 22: Floor plan with floor point classification. ....	76



Figure 23: 20 <sup>th</sup> story floor response spectra for selected locations.....	77
Figure 24: 15 <sup>th</sup> story floor response spectra for selected locations.....	79
Figure 25: 10 <sup>th</sup> story floor response spectra for selected locations.....	79
Figure 26: 5 <sup>th</sup> story floor response spectra for selected locations.....	80
Figure 27: Ground floor response spectra.....	80
Figure 28: Median PVFA values. ....	82
Figure 29: Median PVFA values classified by location in floor plan.....	83
Figure 30: Median PFA values at exterior and interior columns.....	84
Figure 31: Median PFA/PGA values by location in floor plan. ....	86
Figure 32: Median PFA/PGA values on the exterior and interior columns.....	87
Figure 33: Median PFA/PGA values for the SAC 20-story office building. [4].....	89
Figure 34: Median PVFA values produced by the ground motions used in Pekcan et al. study..	91
Figure 35: Roof plan view, 20-story office building used in Pekcan et al. study.....	92
Figure 36: Median PVFA, simplified 20-story stick model. ....	95
Figure 37: Median PVFA, simplified 15-story stick model. ....	96
Figure 38: Median PVFA, simplified 10-story stick model. ....	96
Figure 39: Median PVFA, simplified 5-story stick model. ....	97
Figure 40: Median PVFA/PGA, all stick models. ....	98
Figure 41: Median PFA/PGA values for all the building which Pekcan et al. investigated.....	99
Figure 42: Median PVFA values. 20-story building with infinitely rigid columns.....	100
Figure 43: Mean and 84 <sup>th</sup> percentile PVFA values for columns.....	102
Figure 44: Mean and 84 <sup>th</sup> percentile PVFA for the slab sections. ....	103

## ABSTRACT

### PEAK VERTICAL FLOOR ACCELERATIONS OF TALL STEEL STRUCTURES

By

Georgian Tutuianu

University of New Hampshire, September 2019

To meet modern day challenges structural engineers must properly design not only the primary structural elements of buildings but increasingly the secondary elements too. Damage or failure of nonstructural components (NSCs) and their attachments can present large economic losses, impaired building services and functionality, as well as life safety and emergency egress concerns. To properly design these components, it is important to accurately estimate their maximum acceleration demands including horizontal and vertical components of acceleration. In an effort to better understand vertical acceleration demands of rigid NSCs in multistory buildings and assess the building code provisions a 20-story office building, that is representative of a typical structure, is designed. Vertical acceleration demands are characterized through the use of floor acceleration spectra which are obtained for various points on the plan floor by running elastic modal time histories using 106 recorded ground motions. The main findings of this study are that peak vertical floor acceleration (PVFA) demands vary in plan due to the out of plane flexibility of the floor. Points in the mid portions of the floor slab experience much higher accelerations than points at column locations. The vertical seismic force design provisions of ASCE 7-10 underestimates the PVFA in a majority of the points found in the floor plan at least 50% of the time. A comparison and discussion between these results and the findings of a recent study out of the University of Reno is provided.

## LIST OF ACRONYMS

$\Delta t$	Dynamic time step
$\rho$	Seismic redundancy factor
$\Omega_0$	Overstrength factor
C1	Corner column
$C_d$	Deflection amplification factor
CQC	Complete quadratic combination
ELF	Equivalent lateral force
E-W	East-West direction
f	Fundamental frequency
$F_a$	Short period site coefficient
FEMA	Federal Emergency Management Agency
FFE	Furniture, Fixtures, Equipment,
$F_p$	ASCE 7 vertical seismic design force
FRS	Floor Response Spectra
$F_v$	Long period site coefficient
G1	Largest gravity column
G2	Smallest gravity column
h	Vertical thickness of shell
H	Mean roof height of the structure
$h_r$	Steel metal deck rib height
$H_s$	The total height of the steel metal deck
HVAC	Heating Ventilation Air Conditioning
LA	Los Angeles
LFRS	Lateral Force Resisting Systems
LRFD	Load Resistance Factor Design

MCE <sub>R</sub>	Risk Targeted Maximum Considered Earthquake
MDOF	Multiple Degree of Freedom
MEP	Mechanical, Electrical, and Plumbing
NBCC	National Building Code of Canada
NEES	Network for Earthquake Engineering Simulation
NEHRP	National Earthquake Hazards Reduction Program
N-S	North-South direction
NSCs	Nonstructural Component(s)
PEER NGA	Pacific Earthquake Engineering Research Next Generation Attenuation
PFA	Peak Floor Acceleration
PGA	Peak Ground Acceleration
PHFA	Peak Horizontal Floor Acceleration
PSA	pseudo spectral acceleration
PVFA	Peak Vertical Floor Acceleration
R	Response modification coefficient
RBS	Reduced beam section
RSA	Response Spectrum Analysis
S <sub>1</sub>	One second period acceleration at site
S <sub>a</sub>	Spectral Acceleration
SAC	Joint venture partners between the Structural Engineers Association of California, the Applied Technology Council, and Consortium of Universities for Research in Earthquake Engineering
SCWB	Strong Column Weak Beam
S <sub>D1</sub>	One second period design acceleration
SDOF	Single Degree of Freedom
S <sub>DS</sub>	Short period design acceleration
SMRF	Steel Moment Resisting Frame

$S_r$	Steel metal deck rib spacing
$S_s$	Short period acceleration at site
$T$	Fundamental period
$T_0$	Constant acceleration transition period
$T_L$	Long period
$t_s$	Slab height beyond the rib height in the steel metal deck
$T_s$	Constant velocity transition period
$UZ$	Modal Mass participation, % in vertical
$W_p$	Weight of nonstructural component
$W_r$	Steel metal deck rib width
$X$	Cartesian coordinate in the plan East-West direction, positive to the right
$Y$	Cartesian coordinate in the plan North-South direction, positive up
$Z$	Cartesian coordinate in the vertical direction, positive up
$z$	Story height
$z/H$	Story height relative to the total building height

# CHAPTER 1

## INTRODUCTION

### **1.1 Background**

Modern buildings are comprised of structural and nonstructural components (NSCs). The structural components are primarily elements such as floor slabs, decking or sheathing, floor beams, girders, joists, trusses, columns, posts, pillars, bracing, shear walls, and any other elements which directly resist gravity and lateral forces. These elements are referred to as primary structural systems. In contrast, NSCs are defined as all the rest of the portions and contents of a building not explicitly designated as belonging to the primary structural system and they are broadly referred to as secondary systems. These secondary systems while not directly part of the gravity or lateral force resisting system may still be subject to strong seismic forces which must be resisted through their anchorage or attachments to the primary system or through their own structural characteristics [1]. The distinction between primary structural and secondary systems can be observed from the following figure where the same structure is detailed with (a) only the primary structural system and (b) the secondary system on top of the primary structural system.

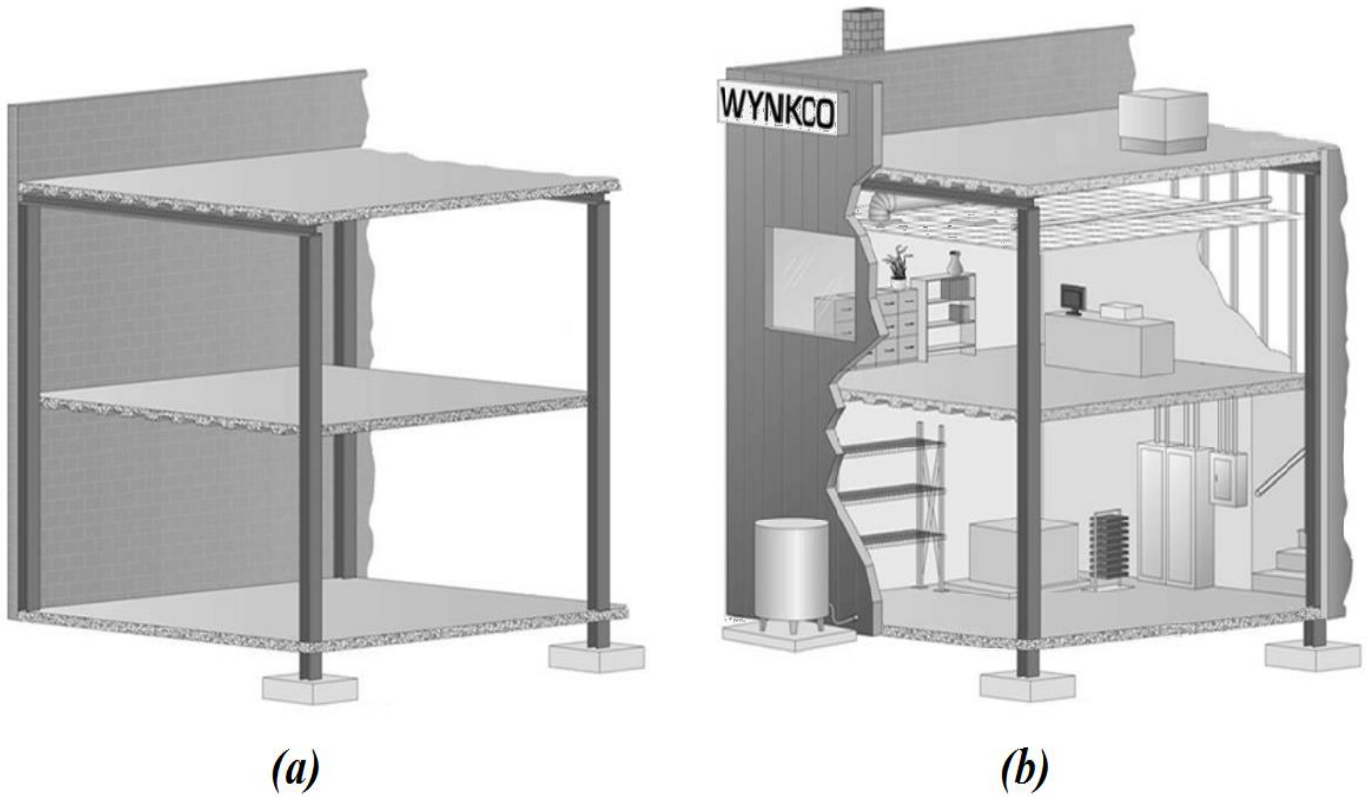


Figure 1: (a) Primary structural system (b) Secondary and primary structural systems [2]

This definition of secondary systems results in a wide variety of components covered under the nonstructural designation. Broadly, NSCs fall into three major categories including [2]:

- 1.) Architectural Components
- 2.) Mechanical, Electrical, and Plumbing (MEP) Components
- 3.) Furniture, Fixtures, Equipment, (FFE) and Contents

See Table 1 for a non-exhaustive list of examples from each of the categories.

Table 1: Three Major Categories of NSCs [1] [2] [3].

<b>Architectural Components</b>	<b>Mechanical, Electrical, and Plumbing Components</b>	<b>Furniture, Fixtures, Equipment, and Contents</b>
Storefronts	Pumps, Turbines, Generators, Engines and Motors	Desks
Glazing	Motor Control Centers	Books, Book Cases and Shelving
Cladding Systems	Control Panels	Industrial Storage Racks
Veneers	Transformers	File Cabinets
Partitions	Emergency Power Systems	Wall Mounted TV's and Monitors
Suspended Ceilings	Distribution Panels	Medical Records
Chimneys	Piping, Ductwork, Conduits	Retail Merchandise
Elevator Penthouses	Storage Tanks and Pressure Vessels	Specialty Equipment: Kitchen and Machine Shop
Heliports	Antennas	Industrial Chemicals and Hazardous Materials
Lighting Systems	Smoke Stacks	Museum Artifacts
Parapets	Cranes	Collectables
Fences	Cooling Towers	
Stairways	Fans	
Signboards	Chillers	
Architectural Ornamentation	Air Handling Units	
	Computers and Data Acquisition Systems	
	Radar and Object Tracking Devices	
	Escalators	

Within these three categories NSCs can be further classified based on the type of seismic response they exhibit: whether or not the component is sensitive to excessive acceleration, deformation, or both. Deformation-sensitive components are items that are susceptible to being damaged by racking or excessive story drift deformation. This category typically includes components that run vertically through the building such as glass or curtain walls. Acceleration-sensitive components are items that are susceptible to being damaged by shifting, overturning or toppling over. This category includes items such as suspended ceilings or HVAC equipment. It



should be noted that from a dynamics point of view the acceleration that a component experiences in reality is the result of the component-floor system-structure interaction. Generally, this interaction produces component acceleration demands that may be greatly amplified compared to the earthquake-induced peak ground acceleration (PGA) at the site. This is especially true if the component period in any of the three orthogonal directions (x,y,z) is close to the modal period of the floor system or structure in the corresponding direction [4]. Examples of components that are primarily characterized as being either acceleration-or deformation-sensitive are shown in Table 2 below, which is obtained from ASCE 41-06 Seismic Rehabilitation of Existing Buildings [3]. The remainder of this study will focus on acceleration-sensitive components.

Table 2: Acceleration or Deformation-Sensitive Components [3].

<b>Component</b>	<b>Acceleration</b>	<b>Deformation</b>
EXTERIOR SKIN		X
Veneer (Including Stone & Marble)		X
Glass Blocks		X
Prefabricated Panels		X
PARTITIONS		X
CEILINGS		
Directly Applied to Structure	X	
Dropped Furred Gypsum Board	X	
Suspended Lath and Plaster		X
Suspended Integrated Ceilings		X
PARAPETS & APPENDAGES	X	
CANOPIES & MARQUEES	X	
CHIMNEYS & STACKS	X	
STAIRS	X	
MECHANICAL EQUIPMENT	X	
Boilers, Heaters and Furnaces	X	
Manufacturing and Processing Equipment	X	
HVAC	X	
STORAGE VESSELS	X	
PRESSURE PIPING	X	
FIRE SUPPRESSION PIPING	X	
DUCTWORK	X	

## 1.2 Importance

A small sample of what damage to nonstructural components may look like is presented in the figures shown below. Figure 2 and Figure 3 show the damage a library sustained by the magnitude 7.1 earthquake off the coast of New Zealand in 2010. Figure 4 shows collapsed precast concrete staircases in a multistory precast concrete building damaged in the same New Zealand earthquake.

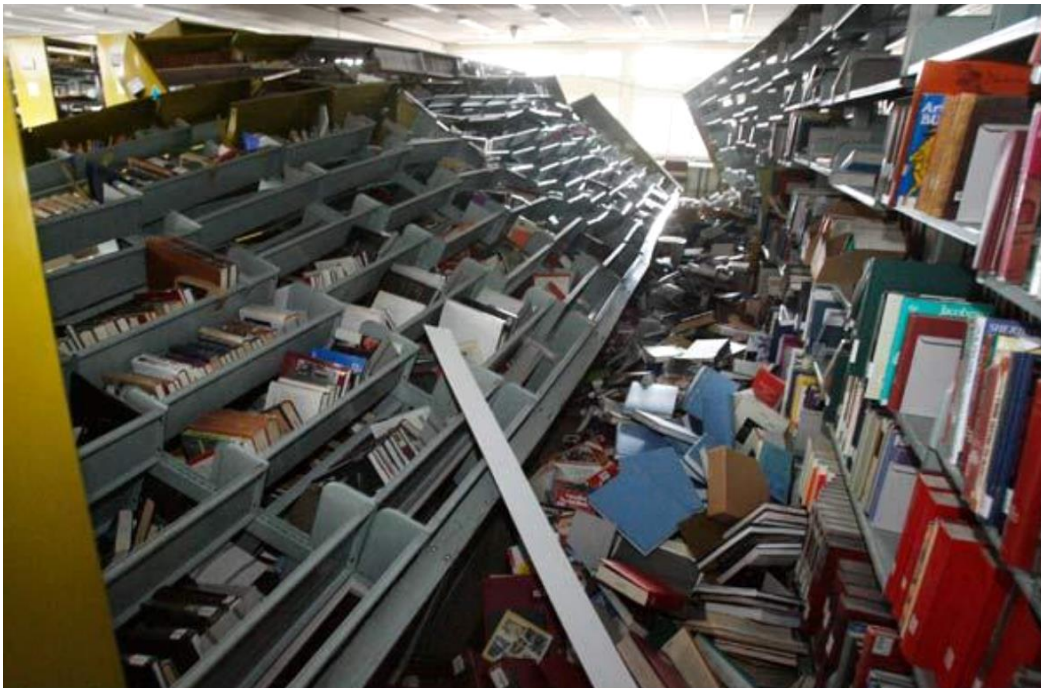


Figure 2: Bookshelf damage from the New Zealand 2010 earthquake [5].



Figure 3: Ceiling damage from the New Zealand 2010 earthquake [5].



Figure 4: Staircase damage from the New Zealand 2011 earthquake [6].

Nonstructural components are important to civil and structural engineers because during a strong seismic event damage to these components may result in any or all of the following:

*1.) Significant Financial Losses*

The number and type of NSCs is ever expanding due to technological advancements. In fact these secondary systems are so numerous and so essential to everyday modern living that they can comprise between 75-85% of the total construction cost of commercial buildings. As shown in Figure 5, from Whittaker and Soong 2003 [7], the nonstructural components of a building represent the largest cost in terms of total construction cost for typical office, hotel and hospital type buildings.

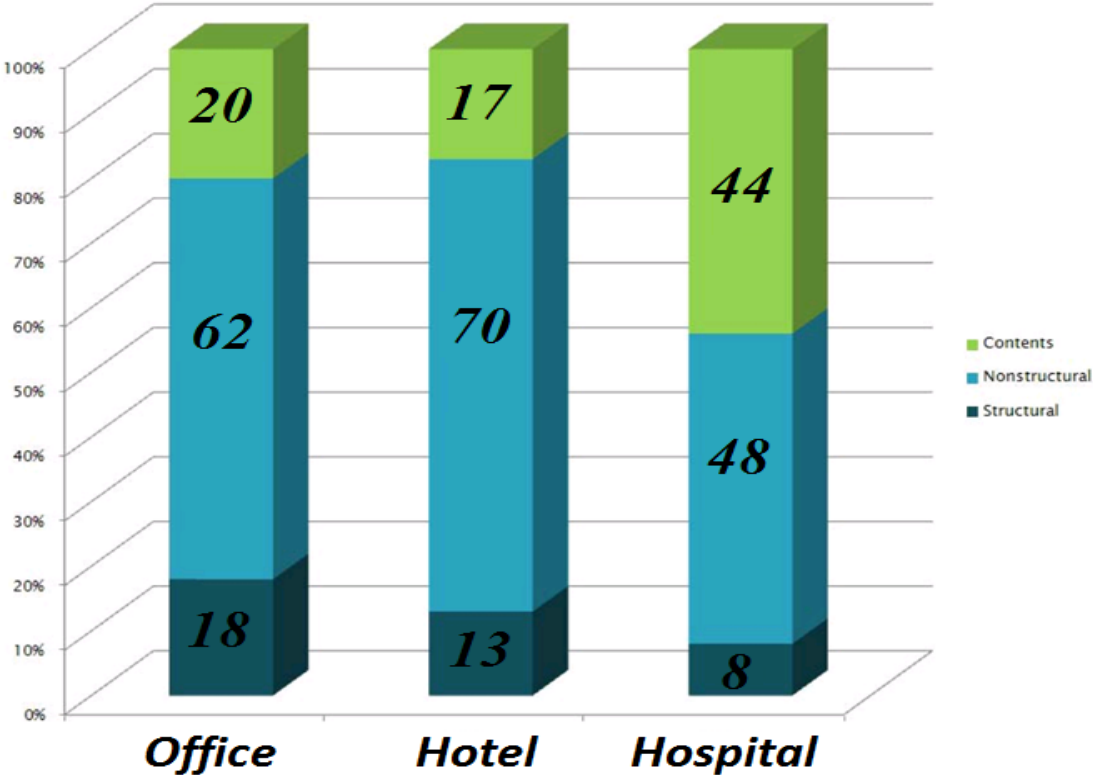


Figure 5: Typical cost breakdown of NSCs, building contents, and structural components [2].

Since NSCs contribute such a large portion of the total construction cost of buildings; building operators and owners have a very large financial incentive to protect their assets especially considering that in some cases damage to these components from earthquakes have resulted in repair and replacement costs exceeding the total cost of the building itself [1]. While it is generally difficult to put a precise monetary value on the cost of nonstructural damage from earthquakes due to the way structural and nonstructural costs are lumped together by building owners and tenants when making insurance claims, a reasonable estimate puts nonstructural losses from recent earthquake events in developed countries at approximately 50% or more of total earthquake losses [8]. For example, of the approximate \$6.3 billion of direct economic loss to non-residential buildings that occurred due to the 1994 Northridge earthquake in California, about \$5.2 billion was due to nonstructural damage [9].

## *2.) Disruption of Essential Services and Business Operations*

After a strong seismic event, essential equipment may be damaged or entirely destroyed and debris caused by falling objects and overturned furniture may critically impair or hinder the performance of essential facilities such as fire and police stations, hospitals, emergency command centers, communication facilities, power stations, and water treatment and supply plants [1]. Furthermore, in the aftermath of a significant seismic event, these obstructions may prevent or greatly diminish the ability of emergency services including firefighters, paramedics and other first responders to adequately target and administer aid to disaster victims in an efficient manner [1].

Businesses may also incur large indirect financial losses from having to close down operations while clean up and repair efforts are undertaken. For example, as a result of the 2004 Niigata earthquake in Japan, the semiconductor plant belonging to Sanyo Electric Company had to be closed down for several months due to damage to its machinery. This resulted in over \$690 million in repairs and lost income for the Sanyo Electric Company [8].

### *3.) Life Safety and Injury Concerns*

Aside from emergency responders not being able to quickly get into or through a building because of fallen debris or overturned furniture and other building contents; the uninjured building occupants may not be able to quickly get out because of those same obstructions. For example it could be very difficult to impossible to escape a multiple story building if the staircase damage is extensive like it was from the February 2011 earthquake which struck New Zealand see Figure 4. Furthermore, the risk of personal injury or death resulting from heavy falling debris should not be underestimated. For example, a student was struck and killed by a falling precast panel while walking out of a parking garage during the 1987 Whittier Narrows earthquake in California [1]. To further illustrate the hazards of falling debris on February 22, 2011 as a bus passed along Colombo Street in central Christchurch, New Zealand a magnitude 6.3 earthquake struck, sending masonry crashing down from buildings and killing 12 people in the street. Eight of the dead were the driver and passengers on the bus, and the other four were pedestrians [10]. Fortunately, by better understanding the seismic behavior of nonstructural components and building contents, structural engineers can reduce these economic and life safety risks the public faces through properly designing supports and anchorage systems for nonstructural components.

### **1.3 Objective, Scope and Contribution of This Work**

Recent earthquake events underscore the need to avoid or reduce the potential hazards to human life, safety and property that damaged NSCs pose. To meet this challenge the seismic demands on acceleration-sensitive components must be better understood and quantified. Since earthquakes produce accelerations in all three orthogonal directions, NSCs must be analyzed and properly anchored or constrained in both horizontal and vertical directions. Unfortunately, there have been very few studies that evaluate the vertical component of ground motion with respect to NSC performance, and even fewer studies incorporating three dimensional analytical building models. These 3-D models are important because in order to assess vertical component acceleration demands that affect NSCs attached to floors or ceilings, the out-of-plane flexibility of the floor diaphragm needs to be accurately captured. The most recent and noteworthy study that explicitly takes into account the out-of-plane floor flexibility is the 2012 work conducted by Pekcan et al. [4] That study focuses on conducting ground motion simulations on 3-D nonlinear steel moment frame buildings ranging from 3, 9 and 20 stories in height. However, based on the author's current knowledge there is no study that explicitly models the composite beam and floor slab connection. For instance, Pekcan et al. [4] uses an "equivalent shell" formulation where the secondary beam and the concrete slab section stiffnesses are lumped into an equivalent shell thickness. Furthermore, even when the vertical component of ground motion has been incorporated in a 3-D building analysis either experimentally or analytically, only a few number of ground motions have been used. For example, Pekcan et al. [4] uses only 21 ground motion recordings.



Therefore, the main objective of this thesis is to evaluate the vertical acceleration demands of elastic NSCs, supports, and attachments attached to a building exposed to a set of 106 recorded ground motions with various frequency contents, intensities, and durations. The quantification of vertical component acceleration demands includes:

- a) Floor acceleration amplification with respect to the PGA
- b) Vertical component acceleration amplification with respect to maximum vertical floor acceleration
- c) The variation of vertical component acceleration demands along the height of the structure
- d) The spatial variation of vertical component acceleration demands at a given floor level

#### *Contribution of This Work*

Vertical component acceleration demands are obtained via response history analysis on a 20-story office building using SAP2000 [11]. This building is designed to current building code standards including ASCE7-10 and the 2010 AISC Seismic Provisions and it is located in Los Angeles, California. This typical 20-story office building not only allows for an evaluation of results with respect to those obtained by Pekcan et al. [4] but also provides insight into the vertical seismic response of NSC attached to tall special moment resisting frame structures. In an effort to provide a reasonable model of the floor system the composite behavior of the steel beam and concrete floor is modeled separately as opposed to using an equivalent shell thickness. The floor system in this study is relatively more flexible than most conventional floor systems in order to provide a conservative (upper bound) estimate of the influence of higher mode effects on vertical component acceleration demands. The NSC acceleration demands are evaluated

statistically using central values (i.e., medians) and a measure of dispersion (i.e., standard deviation of the natural logarithm of the values). Statistically representative NSC vertical acceleration demands are evaluated with respect to estimated design values from ASCE 7-10.

The remainder of this chapter further presents recent work in the field of acceleration-sensitive NSCs and provides an overview of the ASCE 7-10 NSC design provisions. Chapter 2 addresses the design of the 20-story office building. Chapter 3 discusses the analytical computational model and analysis procedures. Chapters 4 and 5 present the major results and conclusions of this study.

#### **1.4 Literature Survey and Previous Work Related to Quantifying Seismic Behavior of NSC**

There has been considerable effort towards understanding, and quantifying NSC behavior in the last couple of decades. This section highlights some of the most relevant work conducted during the past decade. Villaverde [1] describes this research being focused in three primary areas:

- 1.) Conducting and refining various methods of seismic analysis by using linear or nonlinear models; producing the acceleration response for a point on the primary structure where the NSC is attached by running either earthquake time histories or by directly using the ground acceleration spectrum (e.g., response spectrum analysis methods),
- 2.) NSC dynamic characterization through the use of component instrumentation and shake table tests or in-situ forced vibration loading,
- 3.) Proposing simplified design methods to be incorporated in building codes.

The next sections will give an overview of recent studies in these research areas and describe some of their merits and limitations.

#### **1.4.1 Response Spectrum Analysis Methods**

Villaverde [1] states that standard methods of analyzing NSCs in tandem with their supporting structures generally result in a system with an excessive number of degrees of freedom and large differences in the values of its various masses, stiffnesses and damping constants. As a result, the conventional methods of analysis become computationally expensive, potentially inaccurate, and inefficient. For example, a modal analysis exhibits difficulties in the computation of natural frequencies and mode shapes, and a step-by-step integration method may become sensitive to the selected integration time step.

Furthermore, a computational model combining both the structural system and each individual NSC may be too impractical since during preliminary design, the supporting structure would have to be reanalyzed every time a change is introduced to each nonstructural element. From a logistical point of view this approach has further problems since normally structures and nonstructural elements are designed by different teams at different times, which is not necessarily best practice. Therefore, problems of scheduling and efficiency become nontrivial issues.

In an effort to avoid the analysis of a combined system and overcome the aforementioned difficulties researchers have proposed simpler analysis approaches [1] for horizontal component acceleration demands. One such approach comes from Miranda and Taghavi [12]. They develop an approximate method to estimate floor acceleration demands in multistory buildings

responding elastically to earthquake ground motions. This simplified method approximates the dynamic characteristics of buildings by modeling them as equivalent continuum structures consisting of a combination of a flexural beam and a shear beam. This approach allows the development of closed-form solutions for mode shapes, period ratios, and modal participation factors. Using modal analysis the acceleration demands in the building are computed from these approximate dynamic properties. In Miranda and Reinoso [13] this simplified approach is evaluated by comparing peak floor acceleration demands and acceleration time histories to those recorded during earthquakes in six instrumented high-rise buildings. The method is also used to develop approximate floor spectra and these are compared to spectra computed with recorded motions. They conclude that this simplified method produces relatively good results compared to the instrumented records.

Miranda and Taghavi [14] also conducted a parametric study of the interaction between the primary structure and the secondary components on floor response acceleration spectra. This is important because the standard methods for computing acceleration response curves do not explicitly take into account the dynamic interaction between the primary and secondary system masses. The researchers varied the height of the primary structure, the component mass and damping ratio and as well as its location over the height of the building. They conclude that neglecting the interaction in general leads to an overestimation of the seismic demand on secondary systems and therefore to an overly conservative design. Furthermore, a component to primary mass ratio less than 1% will yield reasonably accurate floor spectra results compared to taking into account the interaction between masses.

A number of other researchers have studied the effects of nonlinear primary systems including shear walls [15] and moment resisting frames [16] attached to linear secondary systems on horizontal acceleration response spectra. Villaverde and Chaudhuri [17] performed a parametric study to investigate the impact of building nonlinearity on the seismic response of NSCs. They conducted their investigation by using response history analysis with earthquake ground motion time histories on steel moment resisting frames attached to linear and nonlinear single-degree-of-freedom nonstructural components. Their main conclusions are in line with previous nonlinear studies [15] [16] namely that in general, the nonlinear behavior of the supporting structures reduces the seismic response of the nonstructural components in comparison with the linear counterparts. However, they find that in a few cases, the NSC response is actually amplified however, in most cases NSCs may be designed based on a linear response analysis.

Historically researchers have focused on the horizontal component of floor acceleration and the research efforts previously described are no exception. This is because generally (except in the near field and at short natural periods) horizontal spectral acceleration dominates the vertical component [18] [19], and there is an implicit (yet unproven) assumption that designing components supports and attachments for gravity loading will provide a sufficient margin of safety against damage caused by vertical accelerations. Very recently though in order to better understand NSC behavior some researchers have investigated the effects of three dimensional earthquake loading. Pekcan et al. [20] generated both horizontal and vertical acceleration spectra in linearly elastic concrete buildings and concluded that the vertical component accelerations were significant and in some cases even exceeded the horizontal component accelerations. That work partly motivated Pekcan et al. [4] [21] to perform nonlinear finite element analyses on four

steel moment frame buildings ranging from 3, 9 and 20 stories in height to study vertical component acceleration demands. Three of the four buildings in their study came from a SAC Joint Venture steel project investigation lead by Krawinkler and Gupta [22]. These SAC structures were designed with the 1994 Uniform Building Code [23] and the 1995 FEMA 267 Guidelines [24]. As described previously, Pekcan et al. [4] used an equivalent shell method which combined the thicknesses of the steel beam and concrete floor slab in order to model the composite behavior of the floor system. These structures were simultaneously exposed to the three components of earthquake ground motion (two orthogonal and one vertical) from 21 recorded earthquake motions. The main findings of the 2012 study are in line with other previous works on the effect of nonlinear behavior of the primary structure on the horizontal component of acceleration-sensitive NSC response. Namely, the acceleration response of NSCs is reduced by the nonlinear behavior of the primary system by changes in period, and increased ductility. It was also shown that the acceleration varies nonlinearly along the height of the building. In contrast to this finding the researchers discovered that in the vertical direction the acceleration response is independent of structural period, level of ductility, and relative height of the component location in the building. However, vertical component acceleration demands showed a strong dependence on the out-of-plane flexibility of the floor system. Variation and amplification of vertical floor acceleration demands were observed away from the columns and towards the middle of the open bay sections of the floor system. These results were used to evaluate the current code provisions for estimating peak vertical floor accelerations.

#### **1.4.2 NSC Dynamic Characterization through Experimentation and Instrumentation**

Other approaches, aside from theoretical methods to better understanding and quantifying NSC behavior involve shake table and forced vibration tests. While there have been numerous tests

conducted in order to seismically qualify equipment and other NSCs there have not been very many experiments whose direct aim is to further investigate the seismic behavior of NSCs or to verify the analytical findings of previous studies [1]. Despite this observation the last decade has seen a shift in this trend. For example, Christoph Adam [23] conducted a small scale shake table test of a three story nonlinear shear frame with an attached NSC and compared the results to what a numerical analysis would produce for the same set up. Again, the acceleration demands of the NSC were in agreement with what more recent analytical studies predicted namely that these demands are smaller than in the linear case.

Reinhorn et al. [24] also employed shake table tests but their work focused specifically on the testing and qualification of suspended ceilings and their accessories. They verify their experimental setup and procedures and conclude by proposing new formulations for quantifying required response spectrum in the vertical direction. Furthermore, they propose an alternative testing protocol for seismic qualification NSCs with multi-point attachments for future consideration. This study is unique in that it experimentally quantifies NSC behavior explicitly in the vertical direction while the majority of research involving shake tables typically focus on the horizontal component of acceleration for NSCs.

Other prominent shake table tests implement the use of very large shake tables which are used to study both the structural behavior of full scale building and as well as the attached nonstructural components. For example Panagiotou et al. [25] use the Large High Performance Outdoor Shake Table at the University of California San Diego to investigate the forces on and performance of suspended pipes and their anchorages in a full scale seven story building exposed to several

strong earthquake ground motions. The results of this experiment were the quantification of anchor forces and horizontal floor accelerations. The authors also provide evidence for reconsidering the current seismic anchor loading protocol. While strong vertical floor accelerations were observed and vertical accelerometers were in place during this study, this data was not recorded. A full scale shake table investigation which did record vertical acceleration data can be found in the work of Soroushian et al [26]. That study employed the large E-Defense shake table to test a full scale five story steel moment frame building under 2- and 3-D ground motions. Ceiling and piping system NSC were attached to the building and outfitted with accelerometers. The tests were conducted while the structure was equipped with base isolators and while the base was fixed. The preliminary results include the following: vertical floor accelerations caused damage to the ceiling attachments and drop panels and that lateral bracing including compression may not improve the seismic response and damage of the ceilings. For another example of the use of large shake table tests the reader is referred to Matsuoka et al. [27], who used the E-Defense shake table to test a full scale four story building outfitted with NSCs until collapse and observe seismic performance and damage.

Hutchinson et al [28] subjected a full-scale building to forced vibration loading through the use of roof mounted linear and eccentric mass shakers. This building was also instrumented with an interior monitoring system which recorded the dynamic response of a variety of NSCs including a bench and shelf furnishing system, furnishing mounted equipment, and piping systems. The main test result findings highlight the importance of considering the transmissibility characteristics of building furnishings when estimating building NCS dynamic response.



In an effort to specifically measure the performance of NSCs and/or qualify them for use in buildings the University of Buffalo in association with the Network for Earthquake Engineering Simulation (NEES) have constructed a nonstructural component simulator with the ability to replicate, under controlled laboratory conditions, the effects of strong seismic shaking on distributed nonstructural systems located at the upper levels of multistory buildings. Furthermore, this testing equipment allows for assessing the seismic interactions between displacement and acceleration-sensitive nonstructural subsystems, providing a more realistic procedure for the seismic fragility assessment of combined nonstructural systems. The simulator can subject full-scale nonstructural specimens to accelerations of up to 3g, peak velocities of 100 in/s and displacements in the range of  $\pm 40$  in, enveloping the peak seismic responses recorded at the upper levels of multistory buildings during historical earthquakes. It has been successfully used in assessing the performance of partition wall subsystems Filiatrault et al. [29] as well as a typical emergency room setup Filiatrault et al [30].

### **1.4.3 Simplified Design Methods Proposed for Building Codes**

Significant research effort from structural engineers and researchers from around the world has been put forward in evaluating, verifying, and making proposals to improve the nonstructural component design sections of various building codes. Specifically, a number of studies have targeted the distribution of peak horizontal floor acceleration (PHFA) in nonlinear moment frames [31] [32] [33] [34] [16] [35] [21]. These studies use the same general procedure by running time histories on nonlinear primary steel frame structures and they only really differ in their proposed design simplifications. For example Hutchinson et al. [32] proposes an equation to estimate the vertical distribution of PHFA amplification with respect to the ground peak acceleration value. That equation is primarily based on the height of the building and empirical

constants whereas other researchers [21] proposes a modification based on the period of the primary supporting structure.

Another noteworthy study comes from Canada. Shooshtari et al. [36] propose a method for generating floor response spectra from uniform hazard spectra for western and eastern Canadian cities. The focus of their investigation was to bring design floor response spectra up to date with the National Building Code of Canada 2005 which evaluates seismic hazard data on the basis of uniform hazard spectra.

#### **1.4.4 Previous Work Overview**

While research into new analytical methods for NSC analysis was initially motivated by the shortcomings of standards approaches including modal analysis and explicit time integration techniques, modern analytical methods have relieved many of these problems. It has been demonstrated that dynamic analyses based on a special set of load- dependent Ritz vectors yield more accurate results than the use of the same number of natural mode shapes. Ritz vectors provide a better modal mass participation factor, which enables the analysis to run faster, with the same level of accuracy [37]. Currently available commercial packages such as SAP2000 and ETABS and open source packages such as OpenSees [40] employ fast nonlinear analysis methods to efficiently and accurately produce reliable seismic analyses of structures [38].

The reliability of these modern analysis packages has led to numerous studies by researchers into the seismic behavior of NSC both in terms of linear and nonlinear primary structure behavior. This effort has enhanced and strengthened the state of the art when it comes to the design and analysis of these components. However, the majority of these studies have been conducted on

two dimensional buildings and concentrated on the in-plane behavior of components namely the horizontal direction of acceleration as a function of building height. However, it is important to remember that buildings experience all three components of earthquake ground motions. Pekcan et al. [20] and Panagiotou et al. [25] express a need to better understand all three directions of NSC behavior, but only very recently has there been any substantial analytical work undertaken including the vertical direction and considering three dimensional effects [4] [21].

On the experimental side, despite the nonstructural component simulator at the University of Buffalo's impressive capabilities it is both financially and logistically limiting since it is not practical to run a series of simulations consisting of a multitude of different earthquake ground motions. This latter criticism is valid for not only the simulator but also the shake table and forced vibration tests of both small-and full-scale buildings.

Despite the many simplified design formulations of the amplification of horizontal acceleration demands building codes have been slow to adopt changes. For example, ASCE 7-10 [42] uses a linear amplification factor based on the height of the building to calculate the floor acceleration at a particular story when many of the previous studies also integrate the building period for this calculation in order to get a more realistic PHFA distribution along the building height. When it comes to the estimation of vertical component accelerations, a more rudimentary approach is used, as described in the next section.

### **1.5 Vertical Design of NSCs Seismic Provisions per ASCE 7-10**

Chapter 13 of ASCE 7-10 details the seismic requirements for nonstructural components. NSCs must resist concurrent horizontal and vertical seismic forces. In the vertical direction the code requires that components must resist the following design force formula:

$$F_p = \pm 0.2 S_{DS} W_p \quad (1.1)$$

Where:

$F_p$  : Vertical Seismic Design Force, kip.

$S_{DS}$  : Short Period Design Earthquake Spectral Response Acceleration, gravity (g).

$W_p$  : Weight of Component, kip.

In design practice this force is applied to the center mass of the component. This formula assumes that there is no component amplification with respect to the PGA, and no variation of vertical component acceleration demands with period of the component or the building, and that there is no floor to ground amplification in plan or relative to the height of the building. The building code assumes that because buildings are typically very stiff in the vertical direction, their dynamic vertical response will be equivalent to that of a rigid body. Furthermore, building codes assume that the component frequencies are such that they do not resonate with the vertical frequencies of the floor or roof system.

## CHAPTER 2

### 20-STORY STRUCTURE DESIGN

#### **2.1 Introduction**

In order to evaluate whether or not the vertical design formula from ASCE 7-10 (equation 1.1) accurately captures the magnitude and variation of vertical NSC acceleration demands throughout the building both in plan and elevation requires the use of a multi-story building. For this purpose a typical 20-story office building assumed to be located in Los Angeles, California is considered. This particular building choice allows this work to be evaluated with respect to the results of Pekcan et al. [4], which also simulated vertical ground motions in a 20-story office building. This particular choice of building height is also close to the practical design limits of what is possible for steel moment resisting frame (SMRF) sections since column W shapes tend to get very deep and heavy towards the bottom of the building in the first couple of stories when the building is at or exceeds 20 stories in height [39].

This 20-story office building is equipped with steel moment resisting frame lateral force resisting systems (LFRS) in both the East-West (E-W) and North-South (N-S) directions. The SMRF systems are designed with reduced beam sections (RBS). The floor system consists of a steel metal deck made composite with a concrete slab through shear studs. This office building is designed according to load resistance factor design (LRFD) specifications, ASCE/SEI 7–2010 [40], ANSI/AISC 341-2010 [41], and AISC 2010 [42]. The building geometry including the

number of stories, story height, column layout and floor plan, as well as the soil site properties are all based on an archetype model used in FEMA P695 [39]. As seen from Figure 7 the building footprint in plan view is 140 by 100 feet in the E-W and N-S directions, respectively. Figure 6 shows the full profile view of the building including the height which is 262 feet from the base to the roof. The first story of the building is 15 feet tall while all other stories are at a height of 13 feet.

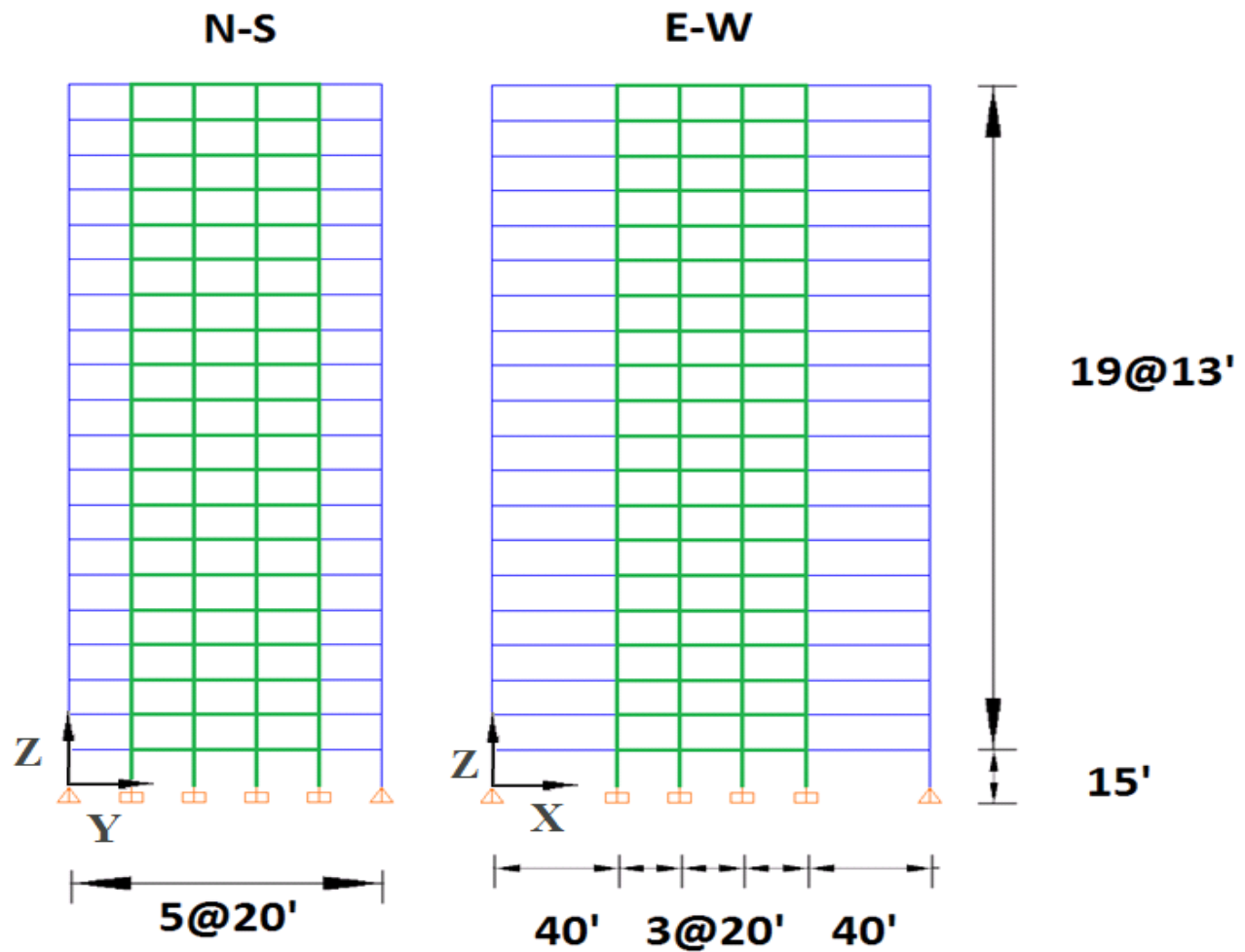


Figure 6: E-W and N-S elevation views of the 20-story office building. The special steel moment frames are highlighted in green.

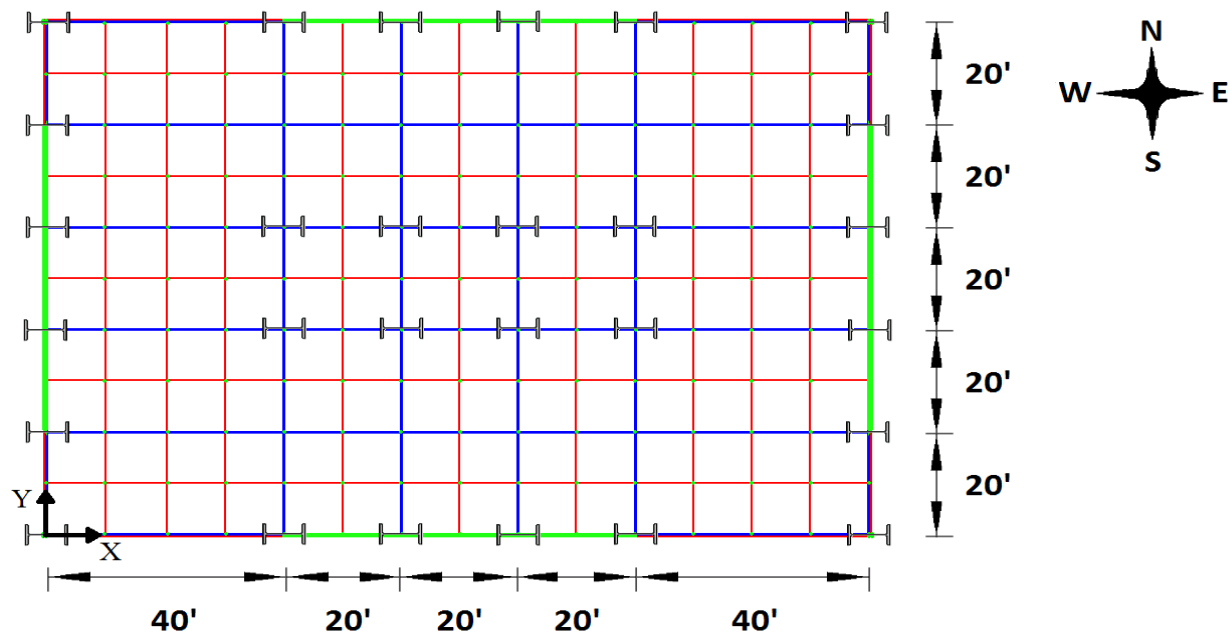


Figure 7: Plan view of the 20-story office building. The special steel moment frames are highlighted in green.

## 2.2 Materials

The structural steel material properties and specifications are obtained from the AISC Steel Construction Manual Tables 2-3 and 2-5 [43]. The material specifications for the rest of the building are outlined in the following table:

Table 3: Building Material Specification and Properties.

Material	Specification	Grade, $F_y$ (ksi)	Fracture Stress, $F_u$ (ksi)	Ratio of Expected to Min Yield Stress, $R_y$	Modulus of Elasticity, $E$ (ksi)	Elements
Steel	A992	50	65	1.1	29,000	Beams Columns
Steel	A108	36	65		29,000	Shear Studs
Steel	A653 [44]	37	52		29,000	Metal Deck
Concrete	Normal Weight	3			3,122	Slab

## 2.3 Design Loads

The design loading for dead, live and seismic load cases is obtained from ASCE 7-10 [40], ASC Steel Deck Technical Floor Deck Specifications [45], and engineering judgment.

### 2.3.1 Design Dead Loads

Dead loads are primarily calculated based on material volumes and material unit weights as well as obtained from technical documents and engineering judgment. Unit weights used for concrete and steel are 150 pcf and 490 pcf respectively. See Table 4 for a summary of typical floor dead loads.

Table 4: Estimated Dead Loads for a Typical Floor.

Typical Floor Loading	Load	Units	Tributary Area	Units	Weight, (kip)
4" Normal Weight Concrete Slab [45]	38	psf	14,000	ft <sup>2</sup>	527
18 ga. Steel Metal Deck [45]	5	psf	14,000	ft <sup>2</sup>	71
Interior Partitions	10*	psf	14,000	ft <sup>2</sup>	140
Floor Beams	75	plf	960	ft	72
Girders (Average)	100	plf	480	ft	48
Columns (Average)	200	plf	364	ft	73
Miscellaneous (Flooring & Ceiling, MEP, Fireproofing etc.)	12	psf	14,000	ft <sup>2</sup>	168
Exterior Cladding	25	psf	6,240	ft <sup>2</sup>	156

\* Note that interior partitions are 20 psf for design dead load but 10 for seismic dead load as per ASCE 7-10 12.7.2 [40].

Typical floor seismic dead load totals to approximately 1,255 kips which distributes uniformly in plan to 90 psf. For design dead load the uniformly distributed weight comes to 100 psf. See the following table for final design dead loads.



Table 5: Final Design Dead Loads.

Typical Loading	Load (psf)
Gravity Dead Load	70
Interior Partitions (Seismic/Gravity)	10/20
Cladding	25
Seismic Dead Load	90

### 2.3.2 Design Live Loads

Occupancy and roof live loads are based on Table 4-1 Minimum Uniformly Distributed Live Loads from ASCE 7-10 [40]. The occupancy live load for the office building is 50 psf and the roof live load is 20 psf.

### 2.3.3 Live Load Reduction

Occupancy live loads are reduced for  $K_{LL}A_T \geq 400 \text{ ft}^2$  according to the following ASCE 7 formula:

$$L = L_0 \left[ 0.25 + \frac{15}{\sqrt{K_{LL}A_T}} \right] \quad (2.1)$$

Where:

$L$  : Reduced Distributed Live Load, psf.

$L_0$  : Unreduced Distributed Live Load, psf.

$K_{LL}$  : Live Load Element Factor, unitless.

$A_T$  : Tributary Area,  $\text{ft}^2$ .

### 2.3.4 Lateral Loads

Earthquake loads acting on the structure are obtained through the use of design spectra and by performing modal response spectrum analysis (RSA) per section 12.9 of ASCE 7-10 [40].

Wind loads acting on the structure are obtained by following the direction procedure outline in Table 27.2-1 in ASCE 7-10 [40].

## 2.4 Load Combinations

The load case combinations governing the design of this structure are from Chapter 2.3.2 and Chapter 12.4.3.2 ASCE 7-10 [40]. The governing lateral load case is seismic. The base shear due to seismic loads in the North-South direction is 1243 kips which is slightly larger than the 1233 kips due to wind loading. The overturning moment due to seismic is approximately 249,000 kip-ft vs. 173,000 kip-ft for wind. See Appendix A for additional information about wind loading. For the seismic load cases a redundancy factor  $\rho$  equal to 1 is used in accordance with section 12.3.4.2. When required, the overstrength factor  $\Omega_0$  is considered in the governing load combinations. From the load combinations available the relevant combinations are the following:

$$1. \quad 1.4D \quad (2.2)$$

$$2. \quad 1.2D + 1.6L + 0.5L_r \quad (2.3)$$

$$3. \quad 1.2D + 0.5L + 1.6L_r \quad (2.4)$$

$$4. \quad 1.2D + 0.5L + 0.5L_r \quad (2.5)$$

$$5. \quad (1.2 + 0.2S_{DS})D + 0.5L \pm \rho E \quad (2.6)$$

$$6. \quad (0.9 - 0.2S_{DS})D + 0.5L \pm \rho E \quad (2.7)$$

## 2.5 Seismic SMRF E-W Frame Design

### 2.5.1 SMRF, Site Properties, Importance Factor & Risk Category

This section summarizes the design of the E-W frame. The corresponding calculations and results for the N-S frame can be found in Appendix C. The design properties of the SMRF frame are obtained from Table 12.2-1 Design Coefficients and Factors for Seismic Force Resisting Systems. The response modification coefficient,  $R$ , is taken as 8 and is used to set the minimum acceptable strength at which the structure will develop its first significant yielding [46]. The overstrength factor  $\Omega_0$  is 3 and it is a quantification of the additional strength over the design strength a structure has due to full plastic hinge formation, actual material yield strength instead of nominal yield strength, and other redundancies built into design codes and common engineering practice. The deflection amplification factor  $C_d$  is 5.5 and it multiplies the calculated elastic deformations in order to estimate the deformations likely to result from the design ground motion [47]. Figure 8 from NEHRP Seismic Provisions provides a visual interpretation of the aforementioned factors.

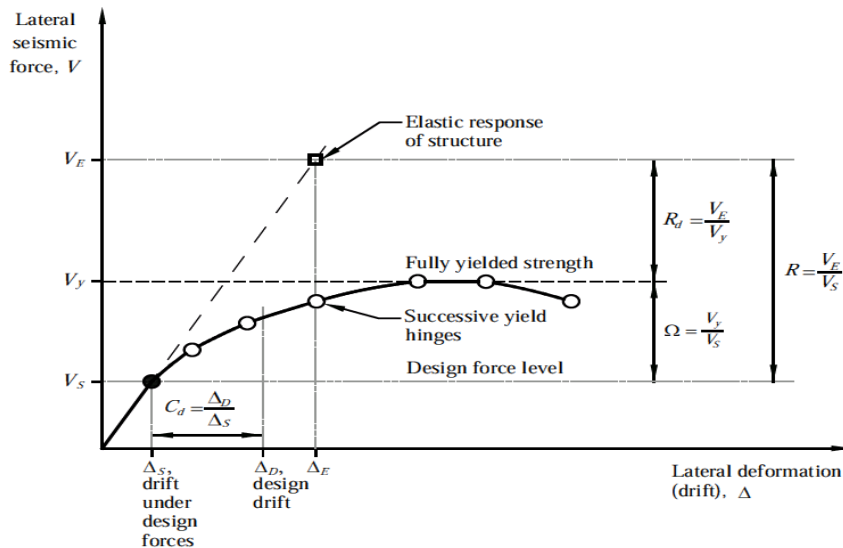


Figure 8: Seismic force vs. lateral deformation [47].

Based on Table 1.5-1 Risk Category of Buildings and Other Structures from ASCE 7-10 [40] the office building falls within risk category II with a corresponding seismic importance factor,  $I$ , of 1.0. In lieu of a detailed geotechnical investigation into the site soil properties, and in the absence of soil information which would require a higher class designation section 11.4.2 of ASCE 7 [40] allows the site classification to be conservatively designated as Site Class D.

### 2.5.2 Design Spectral Acceleration and Design Response Spectrum

For this building the risk-targeted maximum considered earthquake (MCE<sub>R</sub>) spectral response acceleration at short periods,  $S_s$ , and at 1 second period,  $S_1$ , is taken to be 1.5g and 0.6g respectively. The design earthquake spectral response acceleration parameter at short period,  $S_{DS}$ , and at 1 second period,  $S_{D1}$  are obtained from the following equations:

$$S_{DS} = \frac{2}{3} F_a S_s \quad (2.8)$$

$$S_{D1} = \frac{2}{3} F_v S_1 \quad (2.9)$$

Where  $F_a$  and  $F_v$  are the short and long period site coefficients obtained as 1.0 and 1.5 from tables 11.4-1 and 11.4-2 out of ASCE 7 [40]. Thus,  $S_{DS}$  and  $S_{D1}$  are calculated to be 1.0g and 0.6g. These spectral accelerations are used to define the design response spectrum according to the following figure:

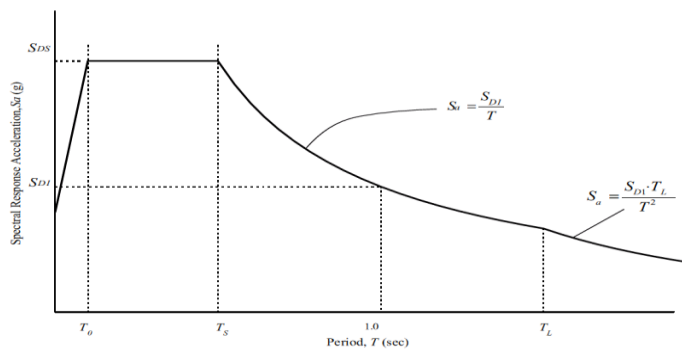


Figure 9: ASCE 7 design response spectrum [40].

Where:

$S_a$  : Spectral Response Acceleration, g.

$T$  : Fundamental Period of the Structure, s.

$T_0 = 0.2 \frac{S_{D1}}{S_{DS}}$  : Constant Acceleration Transition Period, s.

$T_s = \frac{S_{D1}}{S_{DS}}$  : Constant Velocity Transition Period, s.

$T_L$  : Constant Displacement Transition Period also Long Period, s.

Table 6: Design Response Spectrum as a Function of Fundamental Period.

Spectral Acceleration, $S_a$ (g)	Fundamental Period, $T$ (s)
$\left[0.4 + 0.6 \frac{T}{T_0}\right] S_{DS}$	$T \leq T_0$
$S_{DS}$	$T_0 \leq T \leq T_s$
$\left[\frac{1}{T}\right] S_{D1}$	$T_s \leq T \leq T_L$
$\left[\frac{T_L}{T^2}\right] S_{D1}$	$T \geq T_L$

Adhering to the aforementioned process yields the following design response spectrum for this 20-story building and is shown in Figure 10.

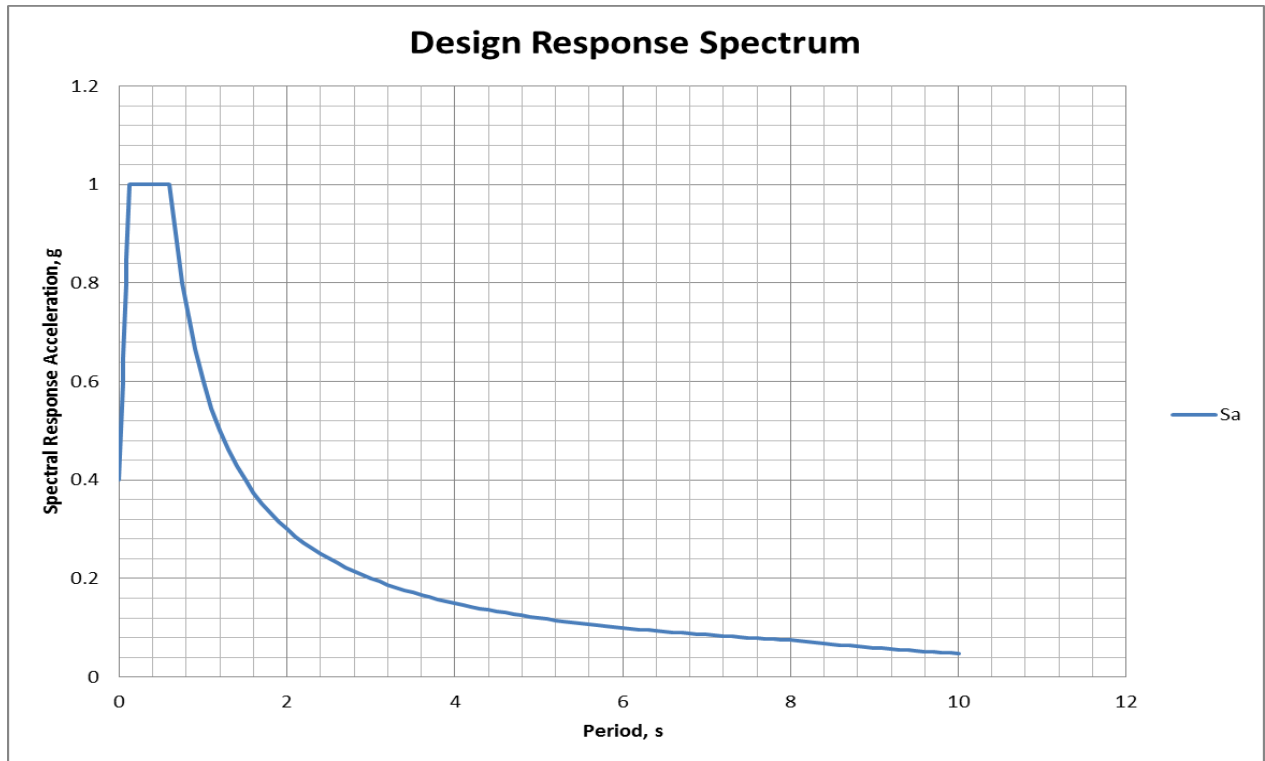


Figure 10: Design response spectrum for the office building.

### 2.5.3 Modal Response Spectrum Analysis

The availability of a design response spectrum permits the building to be analyzed using a dynamic analysis approach such as the modal response spectrum method (RSA). RSA requires the design response spectrum to be scaled by the factor ( $I/R$ ). ASCE 7-10 requires that the member forces determined through response spectrum analysis be scaled so that the total applied lateral force in any direction is not less than 80% of the base shear calculated using the equivalent-lateral force (ELF) method for regular structures nor 100% for irregular structures. This scaling requirement was introduced to ensure that assumptions used in building the analytical model do not result in excessively flexible representations of the structure and, consequently, an underestimate of the required strength [46]. In this method, an MDOF structure is decomposed into N number of single-degree-of-freedom systems, each having its own mode

shape and natural period of vibration. The number of modes available is equal to the number of dynamic degrees of freedom of the structure. However, the analysis must include a minimum number of modes of vibration in order to capture the participation of at least 90% of the structural effective mass in each of the three orthogonal directions. As can be seen from the following tables produced by the analysis software package ETABS [48] more than 90% of the effective mass is captured in the analysis model.

Table 7: Effective Modal Mass in the E-W Direction.

Mode	Period (s)	Frequency (Hz)	UX	$\Sigma$ UX	RY	$\Sigma$ RY	RZ	$\Sigma$ RZ
1	5.494	0.18	75.687	75.7	99.8173	99.817	80.399	80.4
2	1.781	0.56	12.141	87.8	0.0091	99.826	9.857	90.3
3	1.001	1.00	4.204	92.0	0.1467	99.973	1.846	92.1
4	0.659	1.52	2.321	94.4	0.0092	99.982	0.378	92.5
5	0.470	2.13	1.481	95.8	0.0088	99.991	0.073	92.6
6	0.355	2.82	1.020	96.9	0.0012	99.992	0.045	92.6
7	0.279	3.58	0.732	97.6	0.0043	99.997	0.107	92.7
8	0.224	4.46	0.561	98.1	0.0004	99.997	0.314	93.0
9	0.182	5.48	0.459	98.6	0.0015	99.998	0.690	93.7
10	0.146	6.86	0.518	99.1	0.0006	99.999	1.778	95.5
11	0.108	9.28	0.513	99.6	0.0008	100	2.354	97.8
12	0.069	14.40	0.361	<b>100</b>	0.0002	<b>100</b>	1.838	<b>99.7</b>

Table 8: Effective Modal Mass in the N-S Direction.

Mode	Period (s)	Frequency (Hz)	UY	ΣUY	RX	ΣRX	RZ	ΣRZ
1	4.578	0.22	72.775	72.8	99.6035	99.604	64.448	64.4
2	1.468	0.68	12.529	85.3	0.0394	99.643	12.208	76.7
3	0.866	1.15	5.687	91.0	0.2859	99.929	6.585	83.2
4	0.579	1.73	2.765	93.8	0.0520	99.981	4.073	87.3
5	0.422	2.37	1.515	95.3	0.0103	99.991	2.881	90.2
6	0.323	3.10	1.026	96.3	0.0007	99.992	2.447	92.6
7	0.261	3.84	0.859	97.2	0.0040	99.996	2.387	95.0
8	0.213	4.69	0.663	97.8	0.0003	99.996	1.968	97.0
9	0.176	5.67	0.506	98.3	0.0014	99.997	1.382	98.4
10	0.141	7.10	0.594	98.9	0.0008	99.998	1.217	99.6
11	0.105	9.51	0.664	99.6	0.0014	100	0.126	99.7
12	0.069	14.45	0.415	<b>100</b>	0.0002	<b>100</b>	0	<b>99.7</b>

For a given direction of earthquake ground motion loading, any dynamic response quantity  $r(t)$  such as internal member forces, base shear, overturning moment etc. can be computed by summing the contributions of all modes in the following manner [49] [50]:

$$r(t) = \sum_{j=1}^N r_j^{st} A_j(t) \quad (2.10)$$

Where:

$r(t)$  : Specific Dynamic Response Quantity of Interest, variable units.

$r_j^{st}$  : Static Response of Mode  $j$  due to External Static Load Pattern  $S_j$ , variable units.

$S_j$  : Equivalent Spatial Load Vector, mass.

$A_j(t)$  : Pseudo-acceleration Response of the  $j$ th Mode Linearly Independent SDOF System,  $\text{ft/s}^2$ .

However, for design purposes the peak modal dynamic response is of particular interest therefore, equation 2.10 becomes [49] [50]:



$$r_{j,max} = r_j^{st} S_a \quad (2.11)$$

Where:

$r_{j,max}$  : Maximum Specific Dynamic Response Quantity of Interest for Mode  $j$ , variable units.

$S_a$  : Pseudo-acceleration Response Obtained from a Response Spectra, ft/s<sup>2</sup>.

Since the peak response quantity for each mode is determined based on the corresponding spectral acceleration and because the direction and time of occurrence of the maximum acceleration are not evident while creating a response spectrum, there is no way to recombine modal responses exactly such that the maximum response would be identical to that of a response history analysis. However, statistical combination of modal responses produces sufficiently accurate estimates of displacements and component forces for design purposes [47]. The modal combination rule used in this work is the complete quadratic combination (CQC) which comes from random vibration theory and is briefly described below [50].

$$r_{o,CQC} = (\sum_{i=1}^N \sum_{k=1}^N \rho_{ik} r_{io} r_{ko})^{1/2} \quad (2.12)$$

Where:

$r_{o,CQC}$  : Maximum Dynamic Response Quantity of Interest Based on CQC Rule, variable units.

$\rho_{ik}$  : Modal Correlation Coefficient between Modes  $i$  and  $k$ , unitless.

$r_{io}$  : Maximum Dynamic Response Quantity of Interest for Mode  $i$ , variable units.

$r_{ko}$  : Maximum Dynamic Response Quantity of Interest for Mode  $k$ , variable units.

The modal correlation coefficients can be calculated from the following formula produced by

Der Kiureghian:

$$\rho_{ik} = \frac{8\zeta^2(1+\beta_{ik})\beta_{ik}^{3/2}}{(1-\beta_{ik}^2)^2 + 4\zeta^2\beta_{ik}(1+\beta_{ik})^2} \quad (2.13)$$

Where:

$\rho_{ik}$  : Modal Correlation Coefficient between Modes  $i$  and  $k$ , unitless.

$\zeta$  : Percent Damping Ratio, unitless.

$\beta_{ik}$  : Frequency Ratio of Mode  $i$  and Mode  $k$ ,  $\omega_i/\omega_k$ , unitless.

#### 2.5.4 Perimeter Beam Design

Once the building has been analyzed and the maximum earthquake loads are obtained from the RSA method and combined with the other design loads through load combinations, the individual members can be iteratively designed. The frame columns and girders are designed simultaneously and both are designed to meet the AISC Steel Construction Manual Standards [43], and the AISC Seismic Provisions for Structural Steel Buildings [41]. The girders are designed in the following process: the initial design is based on assuming W36 column shapes and then computing the required beam moment of inertia to resist estimated story shears, and code drift limits. From here the ETABS® analytical model is analyzed under design loads and checked for strength capacity and drift limits until satisfactory member sizes are achieved. Final beam sizes, compactness, strength and inter-story drift checks for the E-W frame are shown in Table 9-Table 14.

Table 9: Interior Left Girders of E-W Frame Final Design and Checks.

Floor	Section	$M_{u,max}$ (kip-in)	$V_{u,max}$ (kip)	Flexure	Shear	Flexure $\leq 1$ Shear $\leq 1$
20	W24X94	1,831	14.16	0.160	0.041	OK
19	W24X62	1,950	15.73	0.283	0.054	OK
18	W24X62	2,324	19.19	0.337	0.066	OK
17	W24X62	2,494	21.23	0.362	0.073	OK
16	W24X146	4,477	38.78	0.238	0.088	OK
15	W24X146	4,480	38.29	0.238	0.087	OK
14	W24X146	4,598	39.22	0.244	0.089	OK
13	W24X146	4,778	40.77	0.254	0.093	OK
12	W24X146	4,992	42.61	0.265	0.097	OK
11	W24X131	4,874	41.90	0.293	0.102	OK
10	W24X131	5,024	44.15	0.302	0.108	OK
9	W24X131	5,170	45.68	0.311	0.111	OK
8	W24X131	5,411	49.04	0.325	0.120	OK
7	W24X131	5,539	50.30	0.333	0.123	OK
6	W24X131	5,610	51.01	0.337	0.124	OK
5	W24X146	6,452	57.55	0.343	0.131	OK
4	W24X146	6,723	60.57	0.357	0.138	OK
3	W24X146	6,727	59.76	0.358	0.136	OK
2	W24X146	6,404	56.98	0.340	0.130	OK
1	W24X146	5,132	44.12	0.273	0.100	OK

Table 10: Interior Right Girders of E-W Frame Final Design and Checks.

Floor	Section	$M_{u,max}$ (kip-in)	$V_{u,max}$ (kip)	Flexure	Shear	Flexure $\leq 1$ Shear $\leq 1$
20	W24X94	616	21.90	0.054	0.063	OK
19	W24X62	974	23.46	0.141	0.081	OK
18	W24X62	1,340	26.92	0.195	0.093	OK
17	W24X62	1,559	28.95	0.226	0.100	OK
16	W24X146	2,407	46.50	0.128	0.106	OK
15	W24X146	2,491	46.00	0.132	0.105	OK
14	W24X146	2,730	46.93	0.145	0.107	OK
13	W24X146	3,063	48.49	0.163	0.110	OK
12	W24X146	3,451	50.32	0.183	0.115	OK
11	W24X131	3,706	49.50	0.223	0.121	OK
10	W24X131	4,091	50.78	0.246	0.124	OK
9	W24X131	4,431	51.22	0.266	0.125	OK
8	W24X131	4,977	54.10	0.299	0.132	OK
7	W24X131	5,263	54.80	0.316	0.134	OK
6	W24X131	5,527	54.86	0.332	0.134	OK
5	W24X146	6,289	61.40	0.334	0.140	OK
4	W24X146	6,285	62.49	0.334	0.142	OK
3	W24X146	5,939	64.30	0.316	0.146	OK
2	W24X146	5,581	61.94	0.297	0.141	OK
1	W24X146	4,173	49.95	0.222	0.114	OK

Table 11: Exterior Left Girders of E-W Frame Final Design and Checks.

Floor	Section	$M_{u,max}$ (kip-in)	$V_{u,max}$ (kip)	Flexure	Shear	Flexure $\leq 1$ Shear $\leq 1$
20	W24X94	1,348	12.5	0.118	0.036	OK
19	W24X62	1,584	14.5	0.230	0.050	OK
18	W24X62	1,931	17.9	0.280	0.062	OK
17	W24X62	2,265	21.2	0.329	0.073	OK
16	W24X146	3,933	38.4	0.209	0.087	OK
15	W24X146	3,931	38.2	0.209	0.087	OK
14	W24X146	4,115	39.9	0.219	0.091	OK
13	W24X146	4,374	42.3	0.233	0.096	OK
12	W24X146	4,658	45.0	0.248	0.102	OK
11	W24X131	4,687	45.1	0.282	0.110	OK
10	W24X131	4,925	47.3	0.296	0.115	OK
9	W24X131	5,090	48.7	0.306	0.119	OK
8	W24X131	5,713	54.8	0.343	0.134	OK
7	W24X131	5,821	55.8	0.350	0.136	OK
6	W24X131	5,863	56.1	0.352	0.137	OK
5	W24X146	6,044	57.7	0.321	0.131	OK
4	W24X146	6,040	58.4	0.321	0.133	OK
3	W24X146	5,713	54.7	0.304	0.125	OK
2	W24X146	5,266	50.3	0.280	0.115	OK
1	W24X146	3,574	33.7	0.190	0.077	OK

Table 12: Exterior Right Girders of E-W Frame Final Design and Checks.

Floor	Section	$M_{u,max}$ (kip-in)	$V_{u,max}$ (kip)	Flexure	Shear	Flexure $\leq 1$ Shear $\leq 1$
20	W24X94	1,348	18.3	0.118	0.053	OK
19	W24X62	1,584	20.3	0.230	0.070	OK
18	W24X62	1,931	23.7	0.280	0.082	OK
17	W24X62	2,265	27.0	0.329	0.093	OK
16	W24X146	3,933	44.1	0.209	0.100	OK
15	W24X146	3,931	44.0	0.209	0.100	OK
14	W24X146	4,115	45.7	0.219	0.104	OK
13	W24X146	4,374	48.1	0.233	0.110	OK
12	W24X146	4,658	50.8	0.248	0.116	OK
11	W24X131	4,687	50.9	0.282	0.124	OK
10	W24X131	4,925	53.1	0.296	0.129	OK
9	W24X131	5,090	54.5	0.306	0.133	OK
8	W24X131	5,713	60.6	0.343	0.148	OK
7	W24X131	5,821	61.6	0.350	0.150	OK
6	W24X131	5,863	61.9	0.352	0.151	OK
5	W24X146	6,044	63.5	0.321	0.145	OK
4	W24X146	6,040	61.3	0.321	0.140	OK
3	W24X146	5,713	60.5	0.304	0.138	OK
2	W24X146	5,266	56.1	0.280	0.128	OK
1	W24X146	3,574	39.9	0.190	0.091	OK

Table 13: Girders of E-W Frame Seismic Compactness Checks.

Floor	Section	$\frac{1}{2} \frac{b_f}{t_f}$	Flange Thickness Ratio Flexure $\leq 7.22$	$\frac{h}{t_w}$	Web Thickness Ratio $\leq 59$	$\frac{h}{t_w}$	Web Thickness Ratio Shear $\leq 53.95$
20	W24X94	5.18	OK	20.95	OK	20.95	OK
19	W24X62	5.97	OK	25.05	OK	25.05	OK
18	W24X62	5.97	OK	25.05	OK	25.05	OK
17	W24X62	5.97	OK	25.05	OK	25.05	OK
16	W24X146	5.92	OK	16.6	OK	16.6	OK
15	W24X146	5.92	OK	16.6	OK	16.6	OK
14	W24X146	5.92	OK	16.6	OK	16.6	OK
13	W24X146	5.92	OK	16.6	OK	16.6	OK
12	W24X146	5.92	OK	16.6	OK	16.6	OK
11	W24X131	6.7	OK	17.8	OK	17.8	OK
10	W24X131	6.7	OK	17.8	OK	17.8	OK
9	W24X131	6.7	OK	17.8	OK	17.8	OK
8	W24X131	6.7	OK	17.8	OK	17.8	OK
7	W24X131	6.7	OK	17.8	OK	17.8	OK
6	W24X131	6.7	OK	17.8	OK	17.8	OK
5	W24X146	5.92	OK	16.6	OK	16.6	OK
4	W24X146	5.92	OK	16.6	OK	16.6	OK
3	W24X146	5.92	OK	16.6	OK	16.6	OK
2	W24X146	5.92	OK	16.6	OK	16.6	OK
1	W24X146	5.92	OK	16.6	OK	16.6	OK

Table 14: E-W Frame Drift Limit Check.

Story	Story Drift	Drift Limit	Drift Check $\leq 0.02$
20	0.011	0.020	OK
19	0.014	0.020	OK
18	0.015	0.020	OK
17	0.015	0.020	OK
16	0.015	0.020	OK
15	0.015	0.020	OK
14	0.016	0.020	OK
13	0.016	0.020	OK
12	0.017	0.020	OK
11	0.018	0.020	OK
10	0.018	0.020	OK
9	0.018	0.020	OK
8	0.018	0.020	OK
7	0.018	0.020	OK
6	0.018	0.020	OK
5	0.017	0.020	OK
4	0.017	0.020	OK
3	0.016	0.020	OK
2	0.014	0.020	OK
1	0.008	0.020	OK

### 2.5.5 Reduced Beam Section (RBS) Design

Frame girders are also designed with reduced beam sections (RBS) in accordance to the Steel Construction Manual [43] and by following a procedure outlined in STEEL TIPS Design of RBS Moment Frame Connections [51] (Figure 11). The idea is that by removing sections of the top and bottom flanges of the beam by cutting a depth  $c$  into the beam over a length  $b$  at a distance  $a$  from the face of the column the moment on the face of the column is drastically reduced compared to a non RBS beam-column moment connection type. This will protect the connection area, more specifically, the welds from detrimental stress concentrations. The  $a, b$ , and  $c$  specifications are based on a percent of the beam flange width,  $b_f$  and the depth of section  $d$ . These percentages are constant for all of the girders. See Figure 11 for a depiction of a typical



RBS section. Furthermore, by reducing the strength of the beam at a discrete location away from the column the likelihood of a plastic hinge forming first at the beam-column connection instead of at the reduced beam section under an intense seismic event is significantly reduced.

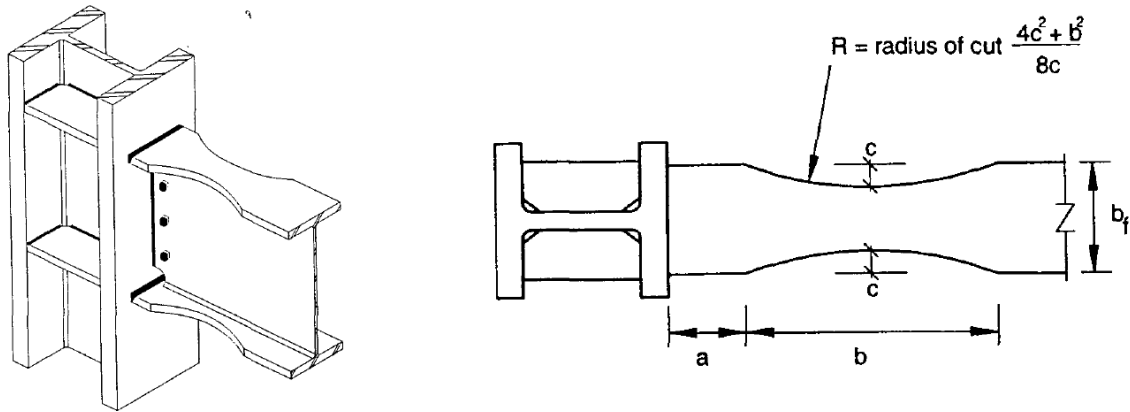


Figure 11: RBS example with plan view of dimension cuts [51].

The critical areas of the RBS design are the moment and shear at the center of the reduced beam section ( $M_{RBS}$  and  $V_{RBS}$  respectively) as well as the moment at the face of the column  $M_f$ . These are shown in Figure 12. They are checked against the girder plastic moment capacity,  $M_p$ , and as well as the RBS plastic moment,  $M_{p,RBS}$ , and the girder shear capacity  $V_n$ . See the following table for a typical RBS design strength checks.

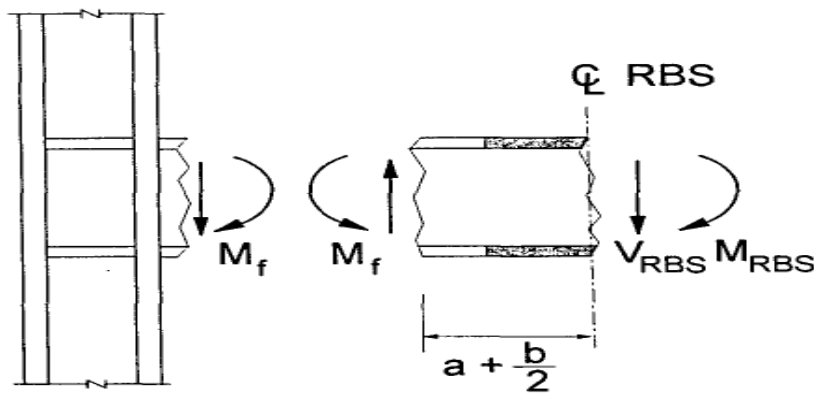


Figure 12: Critical design sections of RBS moment connection [51].

Table 15: RBS Design Coefficients and Factored Moments and Shear.

Floor	Section	a (in)	b (in)	c (in)	$M_{u,RBS}$ (kip-in)	$V_{u,RBS}$ (kip)	$M_{u,f}$ (kip-in)
20	W24X94	5.62	18.20	2.25	1,034	122	12,035
19	W24X62	4.36	17.75	1.75	1,320	79	7,718
18	W24X62	4.36	17.75	1.75	1,747	79	7,716
17	W24X62	4.36	17.75	1.75	1,923	79	7,716
16	W24X146	8.00	18.50	3.20	3,195	197	19,418
15	W24X146	8.00	18.50	3.20	3,345	196	19,409
14	W24X146	8.00	18.50	3.20	3,622	195	19,395
13	W24X146	8.00	18.50	3.20	3,994	195	19,379
12	W24X146	8.00	18.50	3.20	4,430	193	19,359
11	W24X131	8.00	18.35	3.20	4,604	171	17,191
10	W24X131	8.00	18.35	3.20	5,025	170	17,168
9	W24X131	8.00	18.35	3.20	5,474	169	17,162
8	W24X131	8.00	18.35	3.20	5,851	170	17,173
7	W24X131	8.00	18.35	3.20	6,131	171	17,187
6	W24X131	8.00	18.35	3.20	6,384	172	17,202
5	W24X146	8.00	18.50	3.20	7,602	196	19,397
4	W24X146	8.00	18.50	3.20	7,542	194	19,375
3	W24X146	8.00	18.50	3.20	7,358	193	19,350
2	W24X146	8.00	18.50	3.20	6,915	192	19,339
1	W24X146	8.00	18.50	3.20	5,521	192	19,328

Table 16: Demand to Capacity Ratios for the Column Face Moment, Shear and Moment at Center of RBS.

Floor	$\frac{M_{u,f}}{M_p}$	$\frac{M_{u,f}}{M_p} \leq 1$	$\frac{V_{u,RBS}}{V_{n,RBS}}$	$\frac{V_{u,RBS}}{V_{n,RBS}} \leq 1$	$\frac{M_{u,RBS}}{M_{p,RBS}}$	$\frac{M_{u,RBS}}{M_{p,RBS}} \leq 1$
20	0.86	OK	0.35	OK	0.13	OK
19	0.92	OK	0.27	OK	0.25	OK
18	0.92	OK	0.27	OK	0.33	OK
17	0.92	OK	0.27	OK	0.36	OK
16	0.84	OK	0.45	OK	0.25	OK
15	0.84	OK	0.45	OK	0.26	OK
14	0.84	OK	0.45	OK	0.29	OK
13	0.84	OK	0.44	OK	0.32	OK
12	0.84	OK	0.44	OK	0.35	OK
11	0.84	OK	0.42	OK	0.41	OK
10	0.84	OK	0.41	OK	0.45	OK
9	0.84	OK	0.41	OK	0.49	OK
8	0.84	OK	0.41	OK	0.52	OK
7	0.84	OK	0.42	OK	0.54	OK
6	0.85	OK	0.42	OK	0.57	OK
5	0.84	OK	0.45	OK	0.60	OK
4	0.84	OK	0.44	OK	0.60	OK
3	0.84	OK	0.44	OK	0.58	OK
2	0.84	OK	0.44	OK	0.55	OK
1	0.84	OK	0.44	OK	0.44	OK

### 2.5.6 Perimeter Frame Column Design

The perimeter frame columns that form part of the moment-resisting frame are all W36 shapes. Other shapes ranging from W14 to W33 were considered however, in order to meet the strong column weak beam (SCWB) moment ratio check from the AISC Seismic Provisions [41] and because large girders are required to meet code drift limitations for such a tall structure this frame design requires deep and heavy column shapes. Overall, the SCWB moment ratio controls the column member sizes for this frame. In the presence of seismic forces this check tries to ensure that columns are stronger relative to beams such that any yielding that occurs or any plastic hinges that form will first take place in the beams rather than the columns thereby

avoiding undesirable story mechanisms that may potentially lead to a global collapse scenario for the floors above the column story failure. Figure 13 shows a depiction of a beam-hinge mechanism for a moment resisting frame properly designed based on SCWB criteria. The red dots are where plastic hinges are located.

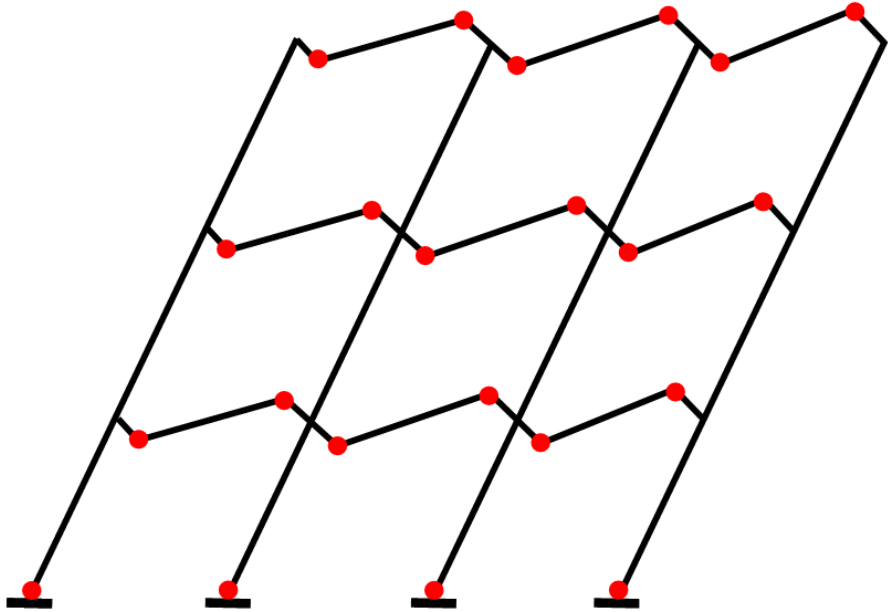


Figure 13: Beams yielding before columns in a three-story building. Figure is modified. [52].

The SCWB ratio is calculated by the following equation. See Table 20 for SCWB checks for the frame.

$$\frac{\sum M_{pc}^*}{\sum M_{pb}^*} > 1 \tag{2.14}$$

Where:

$\sum M_{pc}^*$  : The Sum of the Projections of the Nominal Flexural Strength of the Columns, kip-in.

$\sum M_{pb}^*$ : The Sum of the Projections of the Expected Nominal Flexural Strength of the Beams at Plastic Hinge Locations, kip-in.

Column design follows these steps: the initial design is based on assuming W36 shapes such that calculated drift limits and SCWB criteria are met based on estimated story shears following a design approach used by a former graduate student Josh Clayton. Then, the ETABS analytical model is analyzed under design loads and checked for strength capacity, drift limits and strong column weak beam (SCWB) ratio checks until satisfactory member sizes are achieved. See the following tables for final exterior and interior column sizes, compactness, strength and SCWB checks for the E-W frame.

Table 17: Exterior Column Factored Axial Force, Moment and Governing Axial & Moment Interaction Equation from the AISC Steel Construction Manual [43].

Floor	Section	$P_u$	$M_u$	EQ H1-1a/b	H1-1a/b $\leq 1$
20	W36X170	109	729	0.059	OK
19	W36X170	222	1,032	0.12	OK
18	W36X170	339	1,583	0.184	OK
17	W36X170	458	2,271	0.248	OK
16	W36X170	582	1,932	0.314	OK
15	W36X194	707	1,819	0.334	OK
14	W36X194	834	1,907	0.394	OK
13	W36X194	965	2,051	0.456	OK
12	W36X194	1,099	2,169	0.519	OK
11	W36X194	1,236	2,477	0.584	OK
10	W36X194	1,377	2,830	0.651	OK
9	W36X231	1,523	3,227	0.545	OK
8	W36X231	1,672	3,318	0.598	OK
7	W36X231	1,824	3,640	0.652	OK
6	W36X231	1,978	4,220	0.707	OK
5	W36X330	2,140	4,627	0.534	OK
4	W36X330	2,295	4,779	0.573	OK
3	W36X330	2,454	5,682	0.613	OK
2	W36X330	2,610	7,474	0.652	OK
1	W36X330	2,755	18,279	0.712	OK

Table 18: Exterior Column Final Factored Axial Force with Overstrength Consideration.

Floor	Section	$P_u$	$\frac{P_u}{P_c}$	$\frac{P_u}{P_c} \leq 1$
20	W36X170	118	0.064	OK
19	W36X170	245	0.133	OK
18	W36X170	382	0.207	OK
17	W36X170	523	0.283	OK
16	W36X170	694	0.375	OK
15	W36X194	864	0.408	OK
14	W36X194	1,037	0.490	OK
13	W36X194	1,219	0.576	OK
12	W36X194	1,409	0.666	OK
11	W36X194	1,604	0.758	OK
10	W36X194	1,807	0.855	OK
9	W36X231	2,019	0.722	OK
8	W36X231	2,240	0.801	OK
7	W36X231	2,467	0.882	OK
6	W36X231	2,698	0.965	OK
5	W36X330	2,950	0.736	OK
4	W36X330	3,204	0.800	OK
3	W36X330	3,455	0.863	OK
2	W36X330	3,697	0.923	OK
1	W36X330	3,906	1.009	OK*

\* Note: The axial demand to capacity ratio for the first story is slightly exceeded however it is acceptable by common engineering practice.

Table 19: Exterior Column Seismic Compactness Checks

Floor	Section	$\frac{1}{2} \frac{b_f}{t_f}$	Flange Thickness Ratio Flexure $\leq 7.22$	$\frac{h}{t_w}$	$\frac{h}{t_w}$ Limit	Web Thickness Ratio $\leq$ Limit
20	W36X170	5.45	OK	47.7	56.4	OK
19	W36X170	5.45	OK	47.7	53.6	OK
18	W36X170	5.45	OK	47.7	51.5	OK
17	W36X170	5.45	OK	47.7	50.6	OK
16	W36X170	5.45	OK	47.7	49.5	OK
15	W36X194	4.80	OK	42.4	49.2	OK
14	W36X194	4.80	OK	42.4	48.3	OK
13	W36X194	4.80	OK	42.4	47.4	OK
12	W36X194	4.80	OK	42.4	46.4	OK
11	W36X194	4.80	OK	42.4	45.4	OK
10	W36X194	4.80	OK	42.4	44.4	OK
9	W36X231	6.55	OK	42.2	45.1	OK
8	W36X231	6.55	OK	42.2	44.2	OK
7	W36X231	6.55	OK	42.2	43.3	OK
6	W36X231	6.55	OK	42.2	42.4	OK
5	W36X330	4.49	OK	31.4	45.2	OK
4	W36X330	4.49	OK	31.4	44.6	OK
3	W36X330	4.49	OK	31.4	43.9	OK
2	W36X330	4.49	OK	31.4	43.2	OK
1	W36X330	4.49	OK	31.4	42.6	OK

Table 20: Strong Column Weak Beam Check for Exterior Columns.

Floor	Section	$\sum M_{pc}^*$	$\sum M_{pb}^*$	SCWB Ratio	Check > 1
19	W36X170	71,056	9,157	7.76	OK
18	W36X170	66,741	9,151	7.29	OK
17	W36X170	62,314	9,153	6.81	OK
16	W36X170	57,384	22,980	2.50	OK
15	W36X194	63,514	22,992	2.76	OK
14	W36X194	57,957	22,963	2.52	OK
13	W36X194	52,166	22,929	2.28	OK
12	W36X194	46,079	22,888	2.01	OK
11	W36X194	39,792	20,309	1.96	OK
10	W36X194	33,288	20,261	1.64	OK
9	W36X231	46,519	20,249	2.30	OK
8	W36X231	39,089	20,273	1.93	OK
7	W36X231	31,486	20,300	1.55	OK
6	W36X231	23,733	20,333	1.17	OK
5	W36X330	65,638	23,083	2.84	OK
4	W36X330	56,849	23,037	2.47	OK
3	W36X330	48,187	22,985	2.10	OK
2	W36X330	39,822	22,962	1.73	OK
1	W36X330	31,817	22,940	1.39	OK



Table 21: Interior Column Factored Axial Force, Moment and Governing Axial & Moment Interaction Equation from the AISC Steel Construction Manual [43].

Floor	Section	$P_u$	$M_u$	EQ H1-1a/b	H1-1a/b $\leq$ 1
20	W36X160	87	987	0.043	OK
19	W36X160	173	1,689	0.096	OK
18	W36X160	259	2,530	0.154	OK
17	W36X210	345	4,649	0.182	OK
16	W36X210	440	4,164	0.191	OK
15	W36X210	533	3,780	0.309	OK
14	W36X210	624	3,903	0.353	OK
13	W36X210	714	4,066	0.398	OK
12	W36X210	801	4,094	0.439	OK
11	W36X210	885	4,432	0.486	OK
10	W36X210	965	4,689	0.531	OK
9	W36X210	1,043	5,190	0.578	OK
8	W36X210	1,122	5,341	0.617	OK
7	W36X210	1,198	5,573	0.658	OK
6	W36X210	1,273	6,140	0.707	OK
5	W36X210	1,339	5,926	0.729	OK
4	W36X210	1,402	6,054	0.756	OK
3	W36X231	1,470	6,820	0.667	OK
2	W36X231	1,538	7,439	0.703	OK
1	W36X231	1,606	12,938	0.861	OK

Table 22: Interior Column Final Factored Axial Force with Overstrength Consideration.

Floor	Section	$P_u$	$\frac{P_u}{P_c}$	$\frac{P_u}{P_c} \leq 1$
20	W36X160	89	0.052	OK
19	W36X160	174	0.101	OK
18	W36X160	257	0.149	OK
17	W36X210	343	0.149	OK
16	W36X210	447	0.194	OK
15	W36X210	546	0.237	OK
14	W36X210	644	0.280	OK
13	W36X210	738	0.321	OK
12	W36X210	829	0.360	OK
11	W36X210	914	0.397	OK
10	W36X210	994	0.432	OK
9	W36X210	1,070	0.465	OK
8	W36X210	1,151	0.500	OK
7	W36X210	1,228	0.534	OK
6	W36X210	1,301	0.566	OK
5	W36X210	1,357	0.590	OK
4	W36X210	1,410	0.613	OK
3	W36X231	1,462	0.523	OK
2	W36X231	1,513	0.541	OK
1	W36X231	1,560	0.579	OK

Table 23: Interior Column Seismic Compactness Checks

Floor	Section	$\frac{1}{2} \frac{b_f}{t_f}$	Flange Thickness Ratio Flexure $\leq 7.22$	$\frac{h}{t_w}$	$\frac{h}{t_w}$ Limit	Web Thickness Ratio $\leq$ Limit
20	W36X160	5.88	OK	49.9	56.7	OK
19	W36X160	5.88	OK	49.9	54.5	OK
18	W36X160	5.88	OK	49.9	52.3	OK
17	W36X210	4.49	OK	39.1	52.2	OK
16	W36X210	4.49	OK	39.1	51.4	OK
15	W36X210	4.49	OK	39.1	50.8	OK
14	W36X210	4.49	OK	39.1	50.2	OK
13	W36X210	4.49	OK	39.1	49.6	OK
12	W36X210	4.49	OK	39.1	49.0	OK
11	W36X210	4.49	OK	39.1	48.4	OK
10	W36X210	4.49	OK	39.1	47.9	OK
9	W36X210	4.49	OK	39.1	47.4	OK
8	W36X210	4.49	OK	39.1	46.9	OK
7	W36X210	4.49	OK	39.1	46.3	OK
6	W36X210	4.49	OK	39.1	45.8	OK
5	W36X210	4.49	OK	39.1	45.4	OK
4	W36X210	4.49	OK	39.1	45.0	OK
3	W36X231	6.55	OK	42.2	45.4	OK
2	W36X231	6.55	OK	42.2	45.0	OK
1	W36X231	6.55	OK	42.2	44.6	OK

Table 24: Strong Column Weak Beam Check for Interior Columns.

Floor	Section	$\sum M_{pc}^*$	$\sum M_{pb}^*$	SCWB Ratio	Check > 1
19	W36X160	68,124	18,160	3.75	OK
18	W36X160	65,519	18,155	3.61	OK
17	W36X210	87,322	18,194	4.80	OK
16	W36X210	84,655	45,811	1.85	OK
15	W36X210	81,467	45,793	1.78	OK
14	W36X210	78,354	45,764	1.71	OK
13	W36X210	75,332	45,730	1.65	OK
12	W36X210	72,427	45,689	1.59	OK
11	W36X210	69,594	40,578	1.72	OK
10	W36X210	67,017	40,530	1.65	OK
9	W36X210	64,600	40,518	1.59	OK
8	W36X210	62,020	40,542	1.53	OK
7	W36X210	59,546	40,569	1.47	OK
6	W36X210	57,209	40,602	1.41	OK
5	W36X210	55,518	45,767	1.21	OK
4	W36X210	53,803	45,722	1.18	OK
3	W36X231	65,293	45,643	1.43	OK
2	W36X231	63,573	45,602	1.39	OK
1	W36X231	60,470	45,579	1.33	OK

### 2.5.7 Panel Zone and Doubler Plates

Once the frame column and beams are sized the beam-column intersection known as the panel zone depicted below must be checked for adequate shear strength under column axial load.

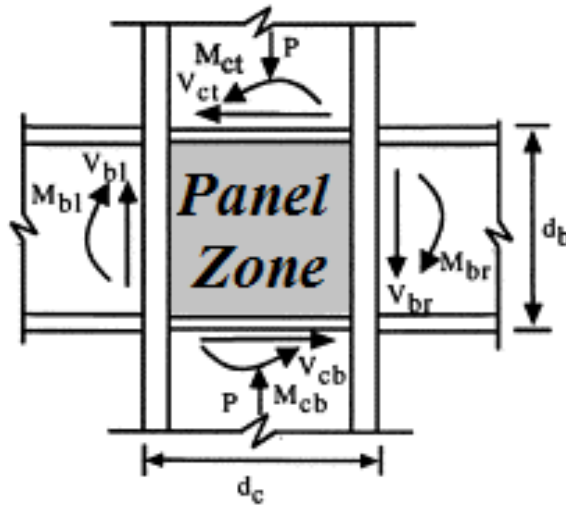


Figure 14: Panel zone location and forces acting on it [53].

The panel zone is important because when a moment frame is subject to strong lateral loads, high shear forces develop. When these forces result in plastic deformations the panel zone exhibits stable hysteretic behavior thus becoming a good source of seismic energy dissipation [54].

However, yielding in beams at RBS connections may not be achieved and the desirable beam-hinge mechanism not obtained. The panel zone is checked according to the requirements from AISC 360-10 Specification for Structural Steel Buildings [42]. The governing equations are the following:

For  $P_r \leq 0.75P_c$

$$R_n = 0.60F_y d_c t_w \left[ 1 + \frac{3b_{cf} t_{cf}^2}{d_b d_c t_w} \right] \quad (2.15)$$

For  $P_r > 0.75P_c$

$$R_n = 0.60F_y d_c t_w \left[ 1 + \frac{3b_{cf} t_{cf}^2}{d_b d_c t_w} \right] \left( 1.9 - 1.2 \frac{P_r}{P_c} \right) \quad (2.16)$$

Where:

$R_n$  : The Available Strength for Web Panel Zone Shear Yielding, kip.

$F_y$ : Specified Minimum Yield Stress of the Column Web, ksi.

$d_c$ : Depth of Column, in.

$d_b$ : Depth of Beam, in.

$t_w$ : Thickness of Column Web, in.

$b_{cf}$ : Width of Column Flange, in.

$t_{cf}$ : Thickness of Column Flange, in.

$P_r$ : Required Axial Strength, kip.

$P_c$ : Axial Yield Strength of the Column, kip.

If the panel zone does not meet these strength checks then it is reinforced with steel plates on both sides of the column web called doubler plates. Table 25: Panel Zone and Doubler Plating of Exterior Columns.

Table 26 summarize the panel zone strength checks and doubler plate requirements and dimensions.

Table 25: Panel Zone and Doubler Plating of Exterior Columns.

Floor	Beam Section	Column Section	$R_u$	$R_n$	Doubler Plate?
20	W24X94	W36X170	431	792	No
19	W24X62	W36X170	281	794	No
18	W24X62	W36X170	281	794	No
17	W24X62	W36X170	281	794	No
16	W24X146	W36X170	688	791	No
15	W24X146	W36X194	688	908	No
14	W24X146	W36X194	688	908	No
13	W24X146	W36X194	688	908	No
12	W24X146	W36X194	688	908	No
11	W24X131	W36X194	614	908	No
10	W24X131	W36X194	614	908	No
9	W24X131	W36X231	614	928	No
8	W24X131	W36X231	614	928	No
7	W24X131	W36X231	614	928	No
6	W24X131	W36X231	614	928	No
5	W24X146	W36X330	688	1,361	No
4	W24X146	W36X330	688	1,361	No
3	W24X146	W36X330	688	1,361	No
2	W24X146	W36X330	688	1,361	No
1	W24X146	W36X330	705	1,361	No

Table 26: Panel Zone and Doubler Plating of Interior Columns.

Floor	Beam Section	Column Section	R <sub>u</sub> (kip)	R <sub>n</sub> (kip)	Doubler Plate?	Side Plate Thickness (in)	Total Plate Thickness (in)
20	W24X94	W36X160	862	748	Yes	1/16	0.125
19	W24X62	W36X160	562	749	No	0	0
18	W24X62	W36X160	562	749	No	0	0
17	W24X62	W36X210	563	1,000	No	0	0
16	W24X146	W36X210	1,376	996	Yes	3/16	0.375
15	W24X146	W36X210	1,376	996	Yes	3/16	0.375
14	W24X146	W36X210	1,376	996	Yes	3/16	0.375
13	W24X146	W36X210	1,376	996	Yes	3/16	0.375
12	W24X146	W36X210	1,376	996	Yes	3/16	0.375
11	W24X131	W36X210	1,229	997	Yes	2/16	0.250
10	W24X131	W36X210	1,229	997	Yes	2/16	0.250
9	W24X131	W36X210	1,229	997	Yes	2/16	0.250
8	W24X131	W36X210	1,229	997	Yes	2/16	0.250
7	W24X131	W36X210	1,229	997	Yes	2/16	0.250
6	W24X131	W36X210	1,229	997	Yes	2/16	0.250
5	W24X146	W36X210	1,376	996	Yes	3/16	0.375
4	W24X146	W36X210	1,376	996	Yes	3/16	0.375
3	W24X146	W36X231	1,376	928	Yes	4/16	0.500
2	W24X146	W36X231	1,376	928	Yes	4/16	0.500
1	W24X146	W36X231	1,410	928	Yes	4/16	0.500

### 2.5.8 P-Δ Effects

In a severe earthquake, steel frame structures have the potential to collapse in a sidesway mode due to P- Δ effects. These effects are caused by vertical gravity loads acting on the deformed configuration of the structure [55]. In order to determine whether or not the individual member forces of the frame require P-Δ amplifications the stability coefficient equation from ASCE 7-10 is used. This equation is as follows:

$$\theta = \frac{P_x \Delta I_e}{V_x h_{sx} C_d} \leq \frac{0.5}{\beta C_d} \leq 0.25 \quad (2.17)$$



Where:

$\theta$  : Stability Coefficient Factor, unitless.

$P_x$ : Total Vertical Design Load at and Above Level x, kip.

$\Delta$ : Design Story Drift, in.

$I_e$ : Importance Factor, unitless.

$V_x$ : Seismic Shear Force Acting between Levels x and x-1, kip.

$h_{sx}$ : Story Height Below Level x, in.

$C_d$ : Deflection Amplification Factor, unitless.

$\beta$ : Ratio of Shear Demand to Shear Capacity for the Story between Levels x and x-1, unitless.

When the stability coefficient is less than 0.10, P-Δ amplifications are not considered. For this frame the all stories have a stability factor less than 0.10 as can be seen from the following table:

Table 27: Stability Coefficient Check.

Story	$\theta$	$\theta_{\max}$	$\theta \leq 0.10 \leq \theta_{\max}$
20	0.03	0.25	OK
19	0.03	0.25	OK
18	0.03	0.20	OK
17	0.02	0.25	OK
16	0.02	0.25	OK
15	0.02	0.25	OK
14	0.02	0.25	OK
13	0.02	0.25	OK
12	0.02	0.25	OK
11	0.02	0.25	OK
10	0.02	0.25	OK
9	0.02	0.25	OK
8	0.02	0.24	OK
7	0.02	0.23	OK
6	0.01	0.23	OK
5	0.01	0.24	OK
4	0.01	0.23	OK
3	0.01	0.22	OK
2	0.01	0.21	OK
1	0.01	0.25	OK

## **2.6 Gravity System Design**

The steel moment resisting frame is designed to withstand the combination of design dead and live loads as well as the design level earthquake forces and resist excessive lateral deformations. However, the remaining frame elements in the building must still be designed including interior and perimeter beams and columns. It is assumed that the steel perimeter moment resisting frames resist the lateral forces therefore, these other frame elements must only resist their own tributary gravity loads including design dead and live loads.

### **2.6.1 Gravity Beam Design**

The floor system is comprised of a concrete slab cast in a steel ribbed deck made composite to steel beams through steel shear studs. The composite floor system depicted below spans in the North-South direction and is designed in accordance to the composite design specifications of ASCI 360-10 [42] and by following a design procedure in STEEL TIPS LRFD Composite Beam Design with Metal Deck [56]. The steel beams are connected to columns through shear connections such that there is negligible or relatively small moment transfer.

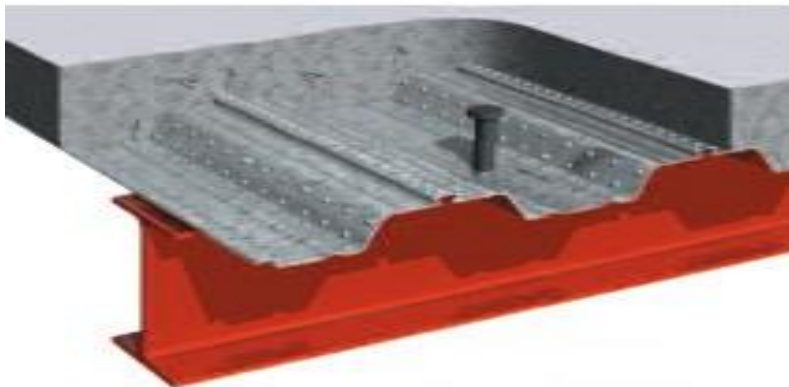


Figure 15: Cross-section of composite steel deck [57].

The floor is designed such that the critical beam-slab section is evaluated, sized and used for rest of the floor sections. The other beam section design calculations can be found in Appendix C. A typical floor beam is depicted below in the plan view of the building.

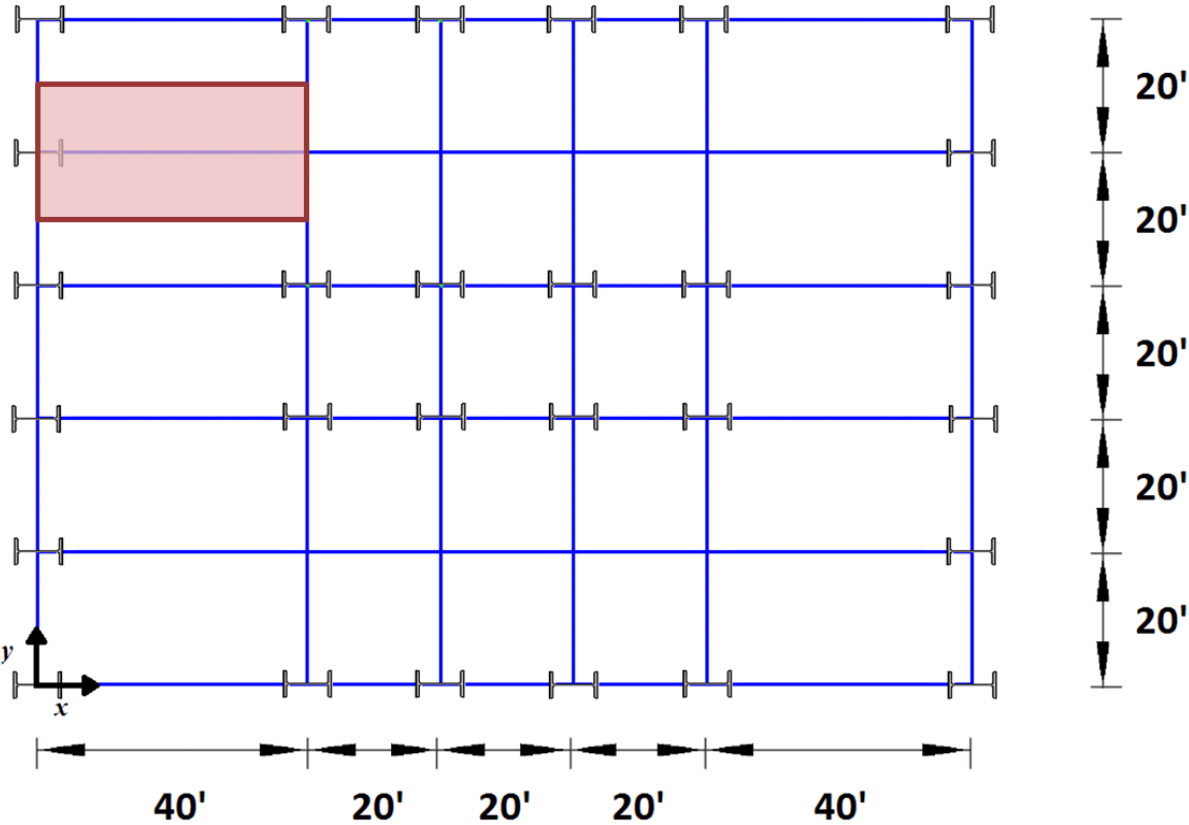


Figure 16: Typical gravity floor beam used for design.

All gravity floor beams are W21X68 with doubled up  $\frac{3}{4}$ " shear studs at 12" on center. The concrete slab has a 28 day compressive strength of 3,000 psi. The metal deck runs perpendicular to the steel beams. It is made out of 18 gage steel sheets and has a rib width,  $W_r$ , of 5 inches. The rib spacing,  $S_r$ , is 12 inches. The rib height,  $h_r$ , is 2 inches and the slab height beyond the rib height,  $t_s$ , is also 2 inches thus giving a total nominal slab depth of 4 inches. The shear studs are

3.5 inches long denoted by  $H_s$  with a half inch of clear cover. Figure 17 shows profile and section views for metal deck, shear stud and slab dimensions.

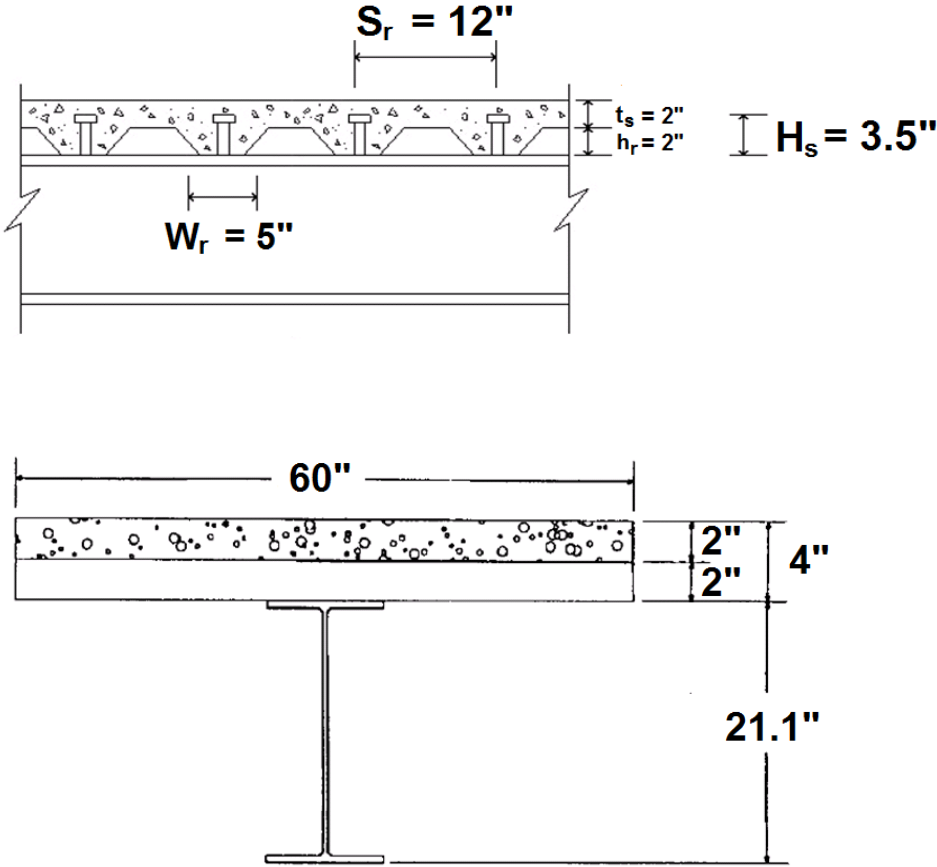


Figure 17: (Top) Cross-section of composite floor deck with ribs perpendicular to steel beam [51]. (Bottom) Cross-section of effective width of W21X68 steel section [51].

The composite section flexure, shear and deflection checks are summarized in the following table:

Table 28: Typical Composite Floor Beam Flexural, Shear and Deflection Checks.

Section	$M_u$ (kip-ft)	$\phi M_N$ (kip-ft)	$V_u$ (kip)	$\phi V_N$ (kip)	Deflection (inches)	L/360 (inches)	Check Limit
W21X68	756	820	76	272	1.324	1.333	OK

## 2.6.2 Gravity Column Design

Gravity columns are designed according to ASCE 360-10 [42] for design dead and live loads. The live loads are reduced according to ASCE 7-10. There are three column lines including two interior and a corner all with differing tributary areas. All of the columns connect to floor beams through shear connections. Only the column with tributary area  $G_1$  will be shown here (see Figure 18) while the rest of the column checks can be found in Appendix C.

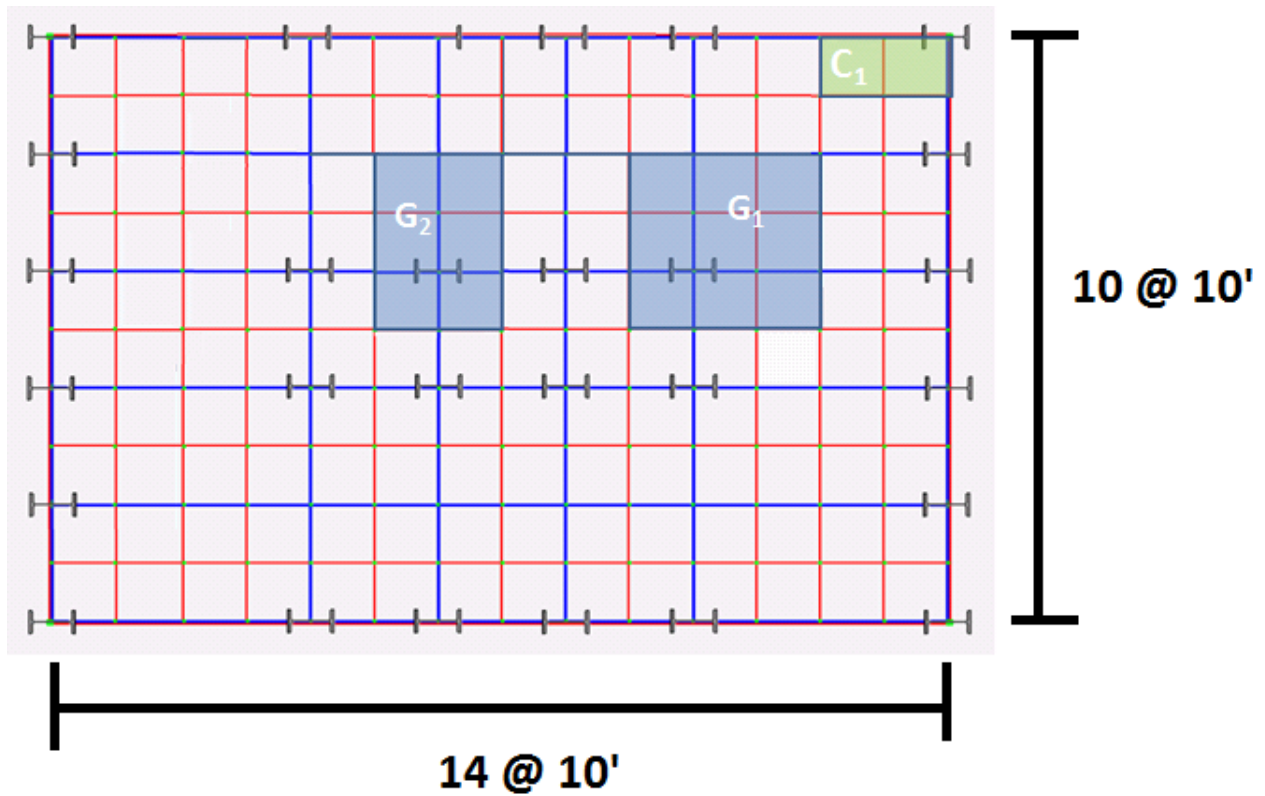


Figure 18: Tributary area and location of gravity columns.

Table 29: Interior Column Strength Checks.

Floor	Design $P_u$ (kips)	ETABS $P_u$ (kips)	Section	$\frac{P_u}{\phi P_n}$	$\frac{P_u}{\phi P_n} \leq 1$
20	137	129	W14X53	0.32	OK
19	276	266	W14X53	0.64	OK
18	412	402	W14X53	0.95	OK
17	549	539	W14X74	0.75	OK
16	686	676	W14X74	0.93	OK
15	823	814	W14X90	0.79	OK
14	960	951	W14X90	0.92	OK
13	1,096	1,089	W14X109	0.87	OK
12	1,233	1,227	W14X109	0.97	OK
11	1,370	1,365	W14X132	0.89	OK
10	1,507	1,504	W14X132	0.98	OK
9	1,644	1,642	W14X159	0.87	OK
8	1,780	1,781	W14X159	0.95	OK
7	1,917	1,920	W14X176	0.92	OK
6	2,054	2,060	W14X176	0.98	OK
5	2,191	2,199	W14X211	0.87	OK
4	2,328	2,339	W14X211	0.93	OK
3	2,464	2,478	W14X257	0.80	OK
2	2,601	2,618	W14X257	0.85	OK
1	2,738	2,758	W14X257	0.92	OK

Table 30: Interior Column Strength Checks.

Floor	Section	$\frac{1}{2} \frac{b_f}{t_f}$	Flange Thickness Ratio Flexure $\leq 13.49$	$\frac{h}{t_w}$	Web Thickness Ratio $\leq 35.9$
20	W14X53	6.11	OK	30.9	OK
19	W14X53	6.11	OK	30.9	OK
18	W14X53	6.11	OK	30.9	OK
17	W14X74	6.43	OK	25.4	OK
16	W14X74	6.43	OK	25.4	OK
15	W14X90	10.21	OK	25.9	OK
14	W14X90	10.21	OK	25.9	OK
13	W14X109	8.49	OK	21.7	OK
12	W14X109	8.49	OK	21.7	OK
11	W14X132	7.14	OK	17.7	OK
10	W14X132	7.14	OK	17.7	OK
9	W14X159	6.55	OK	15.3	OK
8	W14X159	6.55	OK	15.3	OK
7	W14X176	5.99	OK	13.7	OK
6	W14X176	5.99	OK	13.7	OK
5	W14X211	5.06	OK	11.6	OK
4	W14X211	5.06	OK	11.6	OK
3	W14X257	4.23	OK	9.71	OK
2	W14X257	4.23	OK	9.71	OK
1	W14X257	4.23	OK	9.71	OK



## CHAPTER 3

### MODELING AND ANALYSIS

#### **3.1 Structural Analysis Software**

In order to accurately capture component acceleration demands through floor response spectra, the out-of-plane flexibility of the floor must be realistically modeled. To achieve this goal, a three-dimensional model must be used. For this purpose, the 20-story building is modeled and designed three-dimensionally using ETABS v9.7.3 [58]. ETABS is used over other structural analysis packages because it is specifically created for modeling, designing and analyzing buildings rather than a general all-purpose finite element package. While ETABS is great for general structural modeling and analysis, SAP2000 v15 [11] has a better user interface when it comes to advanced structural analysis capabilities. However, modeling buildings in SAP2000 is not as efficient or intuitive as it is in ETABS. Since Computers and Structures Inc. produces both of these software packages, the 20-story building was easily modeled, and designed in ETABS and then the final design was exported to SAP2000 in order to generate response spectrum curves in a more efficient manner.

#### **3.2 Computational Model and Meshing**

The base of the steel moment frames are assumed to be fixed while the rest of the columns are considered as pin connections. The building is comprised of frame (line) elements for the beams and columns. The beam-column connections of the interior gravity frames are shear connections. The only connections to have moment resistance are the beam-column connections in the

perimeter steel moment frames. Each column frame element is discretized into two elements for a total of three nodes. The model is modified so that columns are further discretized to 10 elements and response spectra for a selected number of time histories are compared to the two element discretization to check the need for further meshing. The result of this comparison is a 2% difference in response spectra acceleration values between the two column meshes. In an effort to reduce computational time, the two element mesh is used over the higher resolution mesh. The floor system is meshed at five foot intervals. The beam and slab are both meshed at the same five foot interval so that connectivity is preserved. Various meshes at 10-, 5-, and 2.5-foot intervals are also considered and evaluated by looking at the summed dynamic vertical modal mass participation. These evaluations are plotted in Figure 19..

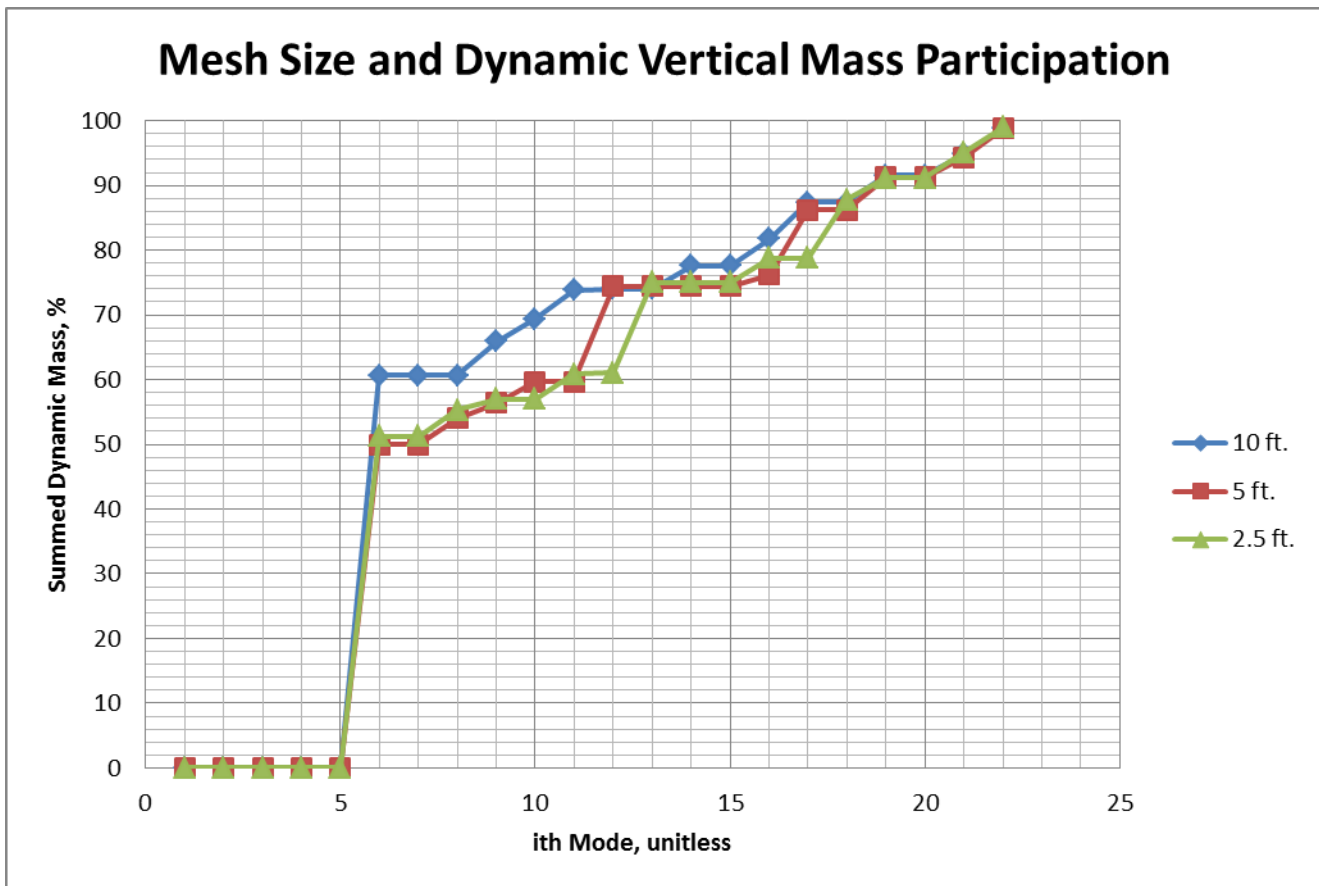


Figure 19: Effect of mesh size on the summed total dynamic vertical mass participation.

As can be seen from Figure 19, the finer meshes at 5 and 2.5 feet give approximately the same shape and cumulative modal mass participation. However, the computational time required to run one simulation at the 2.5 foot mesh is about 6 and 2 times longer than compared to the 10 and 5 foot meshes respectively. Furthermore, the fundamental vertical mode which occurs at mode 6 changes very little between the 5 and 2.5 foot meshes resulting in fundamental frequency values of 2.19 Hz and 2.23 Hz respectively (2% relative difference). Therefore, additional meshing refinements do not yield significant differences in the dynamic behavior of the building model. The final dynamic characteristics of the building in the vertical direction are as follows:

Table 31: Effective Modal Mass Percent in the Z Direction.

Mode	Period (s)	Frequency (Hz)	UZ	$\Sigma$ UZ
6	0.457	2.19	49.94	49.9
8	0.396	2.53	4.05	54.0
9	0.387	2.59	2.37	56.4
10	0.380	2.63	3.34	59.7
12	0.316	3.17	14.74	74.4
16	0.217	4.60	1.79	76.3
17	0.171	5.87	9.94	86.2
19	0.145	6.91	5.13	91.3
21	0.103	9.69	3.02	94.3
22	0.051	19.57	4.49	<b>98.8</b>

Four thin shell elements with 6 degrees of freedom are used in order to model the out-of-plane flexibility of the floor. SAP2000 allows the user to input different shell thicknesses in order to provide different in-plane and out-of-plane element stiffnesses. AutoCAD is used in order to determine the appropriate thickness of an equivalent shell floor system. Note that only the concrete filled sections of the metal deck including the ribs are used to find an equivalent rectangular section. The steel beams are not used in this calculation. AutoCAD is used to turn a

drawing obtained from ASC Steel Deck [59] of the assumed cross-section of the composite metal deck designed for this study into a region, and then obtain its geometric properties. These can be seen in the following table.

Table 32: Geometric Properties of the Composite Deck from AutoCAD.

Geometric Property	Symbol	Value	Units
Horizontal Length	$L_X$	238	in
Area	$A$	696	in <sup>2</sup>
Perimeter	$P$	545	in
X Centroid	$\bar{X}$	119	in
Y Centroid	$\bar{Y}$	2.36	in
XY Inertia	$I_{XY}$	169,765	in <sup>4</sup>
X Inertia	$I_{X,0}$	804	in <sup>4</sup>
Y Inertia	$I_{Y,0}$	3,275,613	in <sup>4</sup>
X Radius Gyration	$r_X$	2.31	in
Y Radius Gyration	$r_Y$	137	in

A shell element having an in-plane thickness of 2.9 inches and a bending thickness of 3.4 inches produces a floor system with equivalent geometric parameters. The percent difference of the moment of inertia around the x axis between the actual floor system and the equivalent shell system is less than 1% at 0.04%. SAP2000® gives the user the ability to choose between thick and thin shell stiffness formulations. A general rule of thumb in determining whether to use thick or thin shells depends on the depth to minimum in-plan-orthogonal side ratio [60].

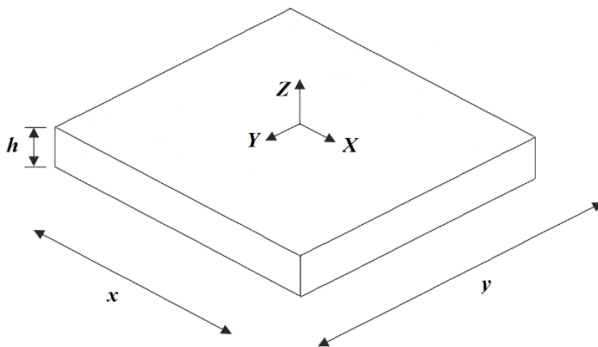


Figure 20: Shell element.

$$\text{Thin Shells: } \frac{h}{\text{minimum}(x \text{ or } y)} < \frac{1}{10} \quad (3.1)$$

$$\text{Thick Shells: } \frac{h}{\text{minimum}(x \text{ or } y)} > \frac{1}{10} \quad (3.2)$$

Where:

$h$  : Vertical Thickness of Shell, in.

$x$  : Shell Length Along X Direction, in.

$y$  : Shell Length Along Y Direction, in.

For this study modeling the floor system with the thin shells is a valid assumption due to equation 3.1 controlling for example  $\frac{3.435''}{60''} = 0.05725 < 0.10$ . Each floor level is assigned its own rigid diaphragm in the z plane. This is because floor systems in buildings exhibit composite behavior due to the concrete, rebar, and beams tying everything together. In an effort to model the floor as realistically as possible, the deck is raised above the beams. In the SAP2000 model this is done by lowering the frames through the use of insertion points. Insertion points allow the beam-slab connection to remain compatible with respect to displacements thereby allowing the beam-slab to deform together achieving the assumed composite behavior.

### **3.3 Ground Motion Selection**

Ground motion acceleration time histories are selected using the Pacific Earthquake Engineering Research Next Generation Attenuation (PEER NGA) [61] strong motion database. The criteria for selection is as follows: ground motions with a moment magnitude ranging from 6.5 to 8, excluding acceleration recording at dam abutments, source-to-fault-rupture distance between 0 and 30 kilometers, and soil site class D. These specifications produce 106 unscaled ground motions which are detailed in Appendix B.

### **3.4 Linear Modal Time History and Response Spectrum Analysis**

To solve the equation of motion for each ground motion at every time instance SAP2000 uses linear modal methods instead of a direct integration scheme. For this study this method is preferable since this is an elastic analysis. In order to ensure an accurate solution for each mode when conducting the linear modal time history analysis, the time step  $\Delta t$  must be sufficiently small. A general rule of thumb is that the following equation should be satisfied: [62]

$$\Delta t \leq 0.1T_N \quad (3.3)$$

Where:

$\Delta t$  : Time Step, s.

$T_N$  : Highest Mode Period, s.

For this study  $\Delta t \leq 0.1(0.0511) \leq 0.00511$  seconds. The time step for each ground motion run is at 0.005 or less seconds; thus, meeting the requirement. Once the linear modal time history for each ground motion has been performed, response spectrum curves can be generated. These

curves produce the maximum acceleration experienced by a NSC modeled as a single-degree-of-freedom (SDOF) system plotted against the frequency of the component. In an effort to take advantage of the symmetry of the floor plan to reduce the total number of data points to generate floor response spectra, only the locations depicted by the purple and yellow circles in Figure 21 are used.

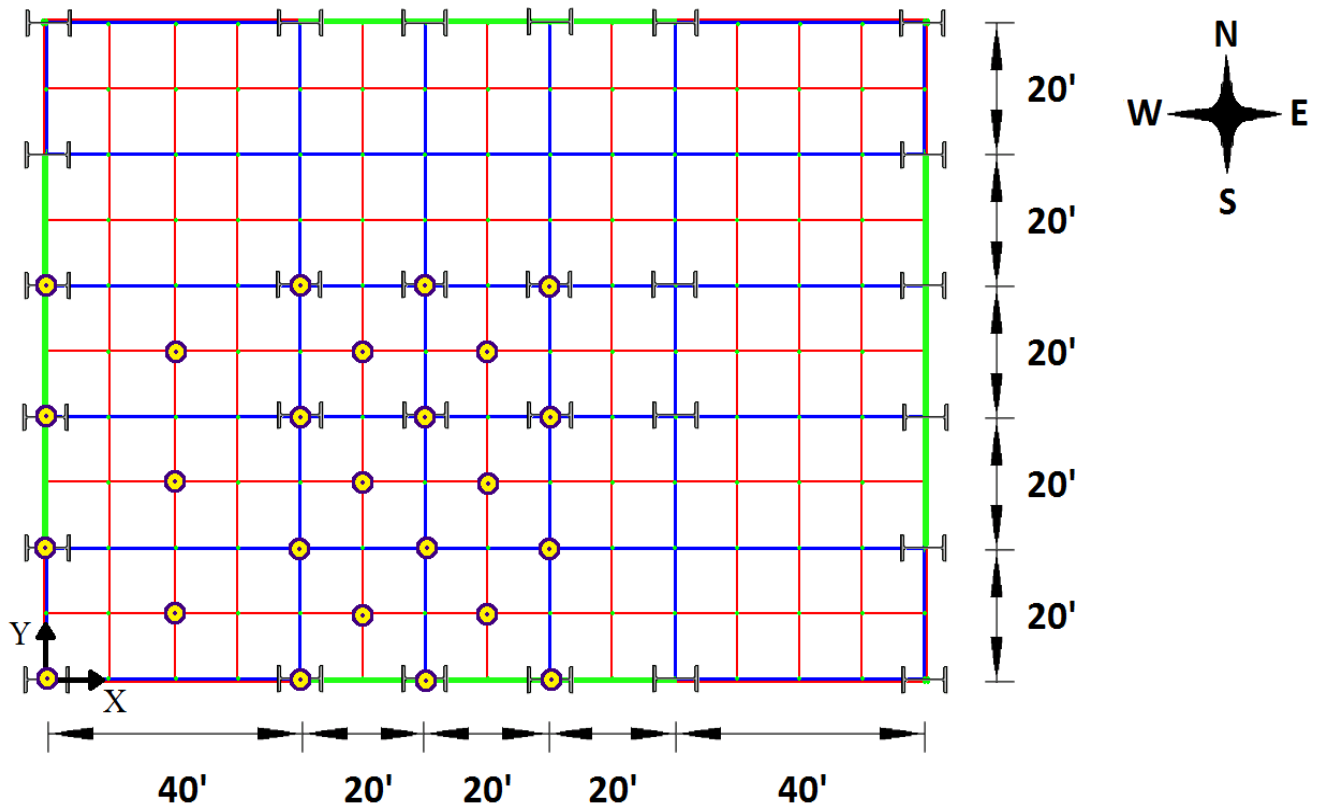


Figure 21: Floor plan of the building with response spectrum curve indicators.

The response spectrum curves generated for these points assume 5% of critical damping. These curves will be presented and discussed in the next chapter.

## CHAPTER 4

### RESULTS & DISCUSSION

This chapter presents typical floor acceleration response spectra gathered from running various ground motions. At certain locations throughout the floor plan and along the height of the building median peak vertical floor accelerations are calculated and presented. By visualizing the magnitude of the acceleration along the height of the building this work can be directly compared to both similar work and to the design requirements of ASCE 7-10.

#### **4.1 Floor Response Spectra**

The floor acceleration response spectrum (FRS) for a floor system are important because they are useful in design when the period of the component is known (it is usually provided by the manufacturer) since the FRS gives the maximum corresponding acceleration the particular component will experience due to a particular earthquake ground motion. This maximum acceleration is then turned into a maximum inertial force using the mass of the component. This seismic force then allows engineers to properly design the anchorage of the component and complete their design.

In order to develop the FRS the vertical component of acceleration from a suite of 106 strong ground motions is used to excite the building using SAP2000 v15. FRS are obtained at discrete points located throughout the building. These points are broken down and classified based on plan view location. These categories include whether the component is located on an exterior or interior column line or whether it is located in the middle of a large versus small slab section.



The large bays are 40ft in length and the smaller slab sections are 20ft in length. See Figure 22 for the breakdown:

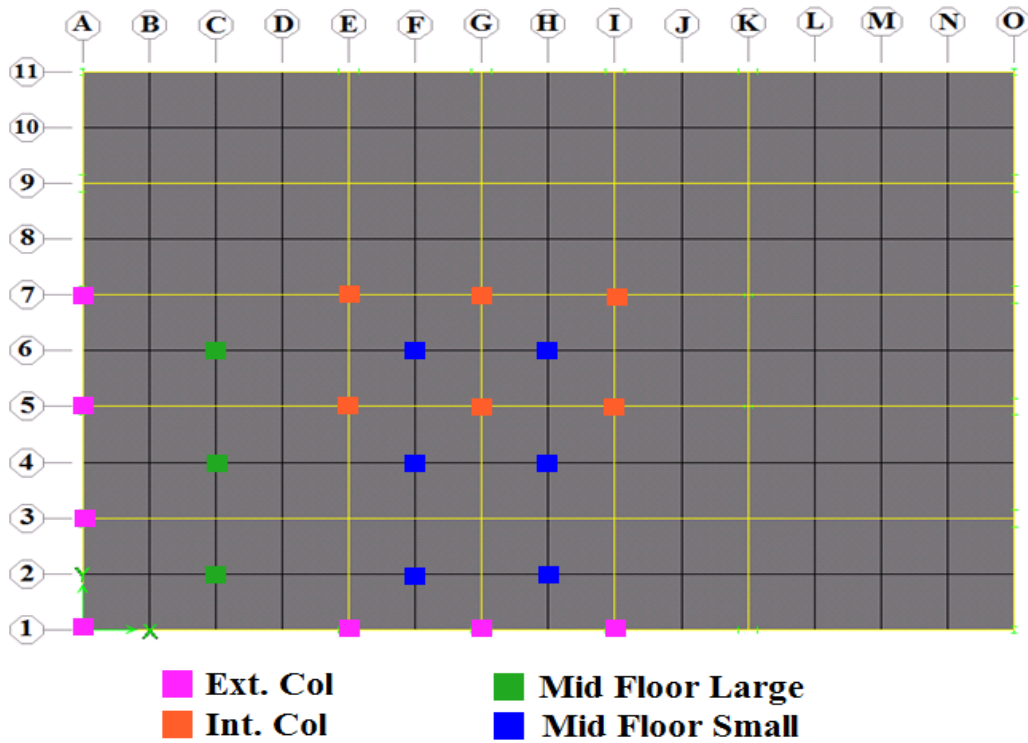


Figure 22: Floor plan with floor point classification.

These points also have alphabetic and numeric descriptions based on the figure from above:

Table 33: General FRS Categories.

Classification	Points	Description
Mid Large	C6, C4, C2	Middle of the 40 foot bay
Mid Small	F6, F4, F2 H6, H4, H2	Middle of the 20 foot bay
Ext. Col	A1, A3, A5, A7 E1, G1, I1	On an exterior column
Int. Col	E7, E5, G7, G5, I7, I5	On an interior column

The following floor response spectrum graphs depict the median response of the points on the floor, which are grouped into the aforementioned categories, to the ground motions.

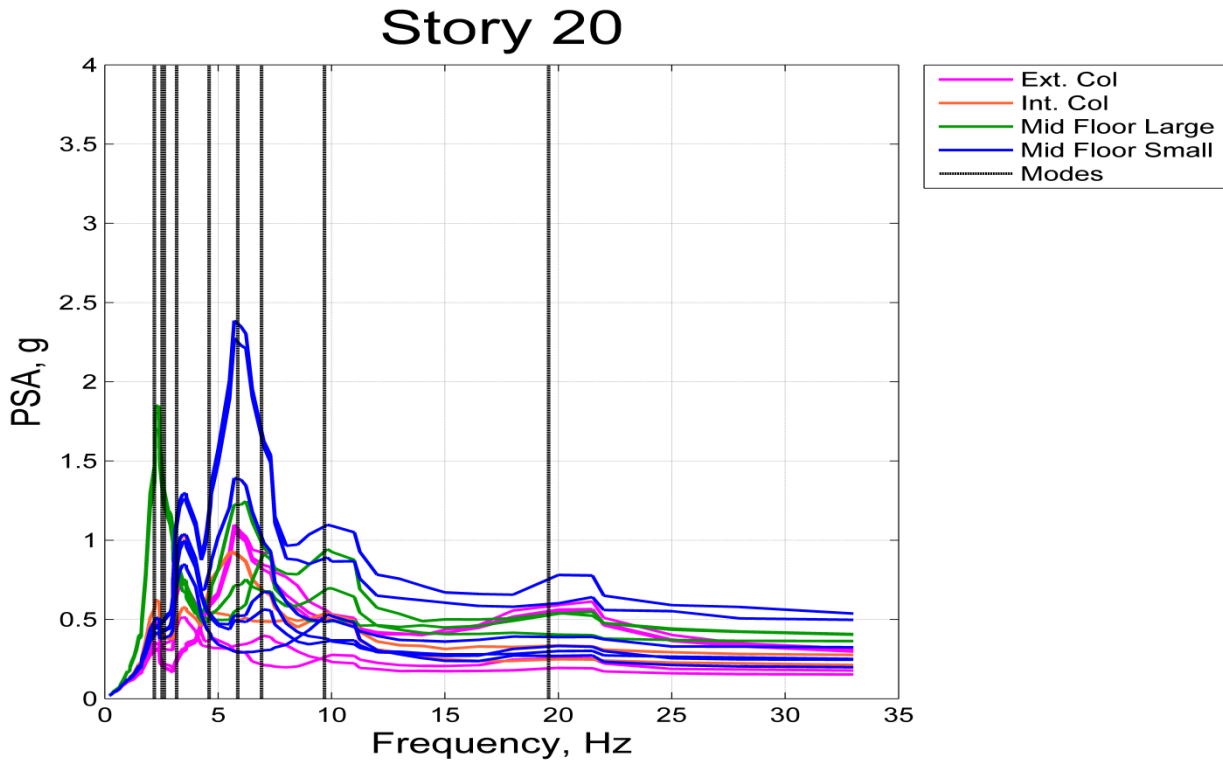


Figure 23: 20<sup>th</sup> story floor response spectra for selected locations.

# Story 15

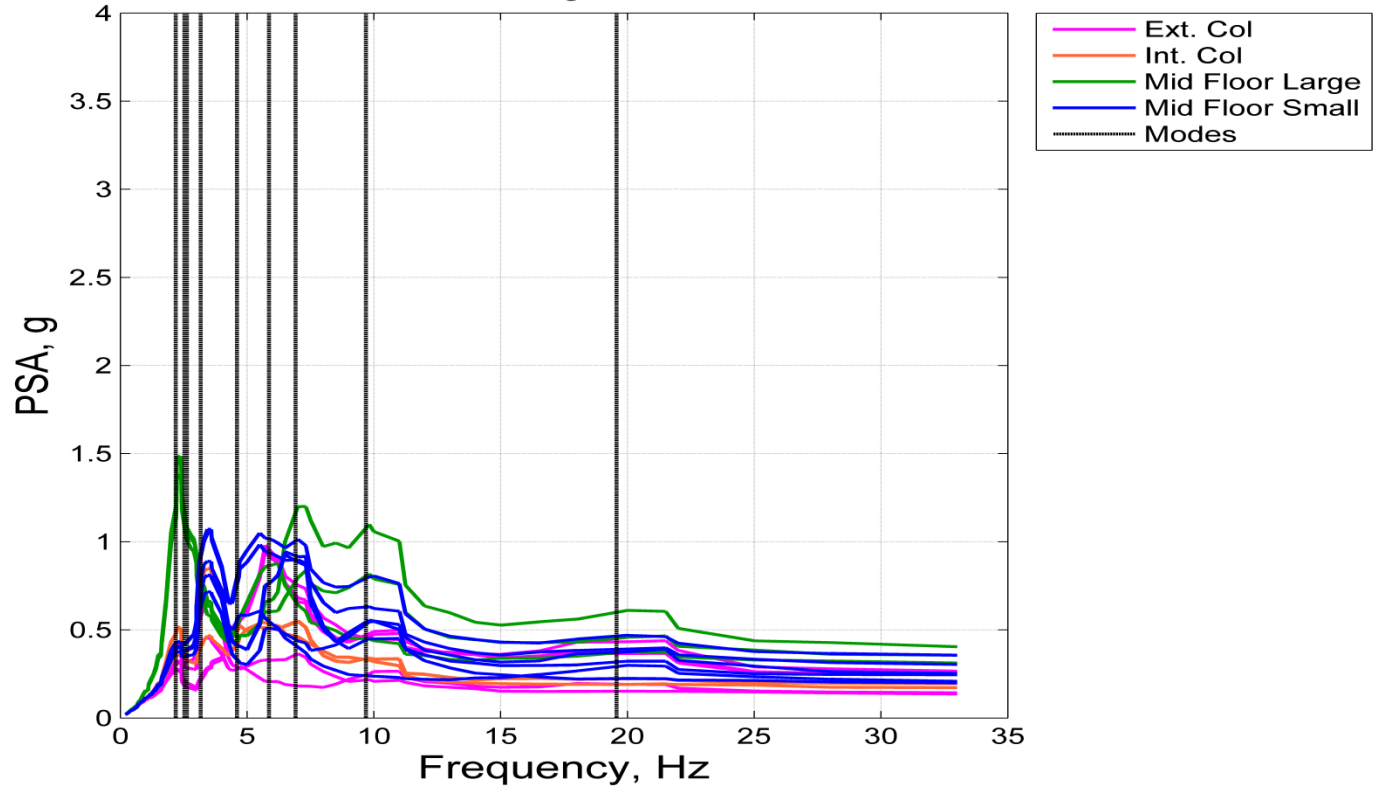


Figure 24: 15<sup>th</sup> story floor response spectra for selected locations.

# Story 10

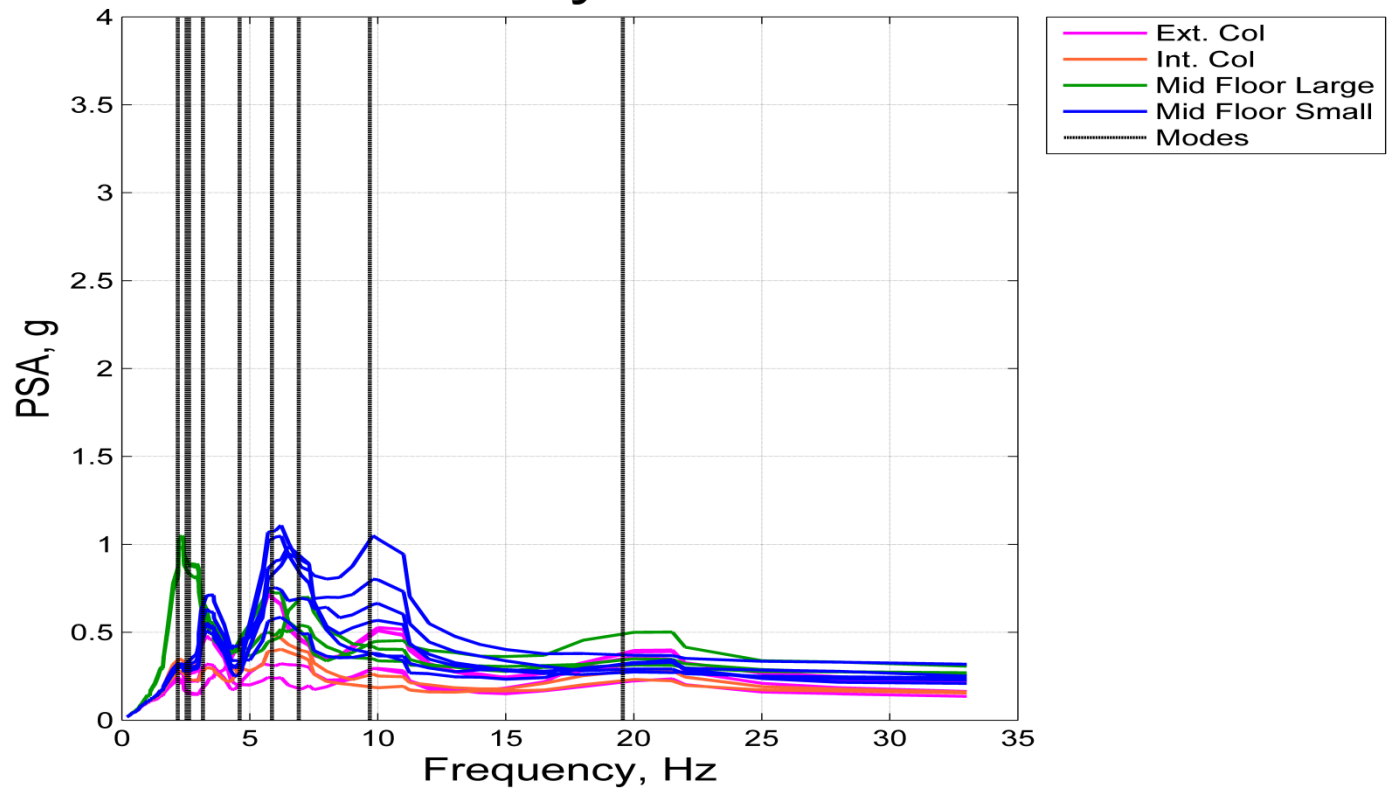


Figure 25: 10<sup>th</sup> story floor response spectra for selected locations.

# Story 5

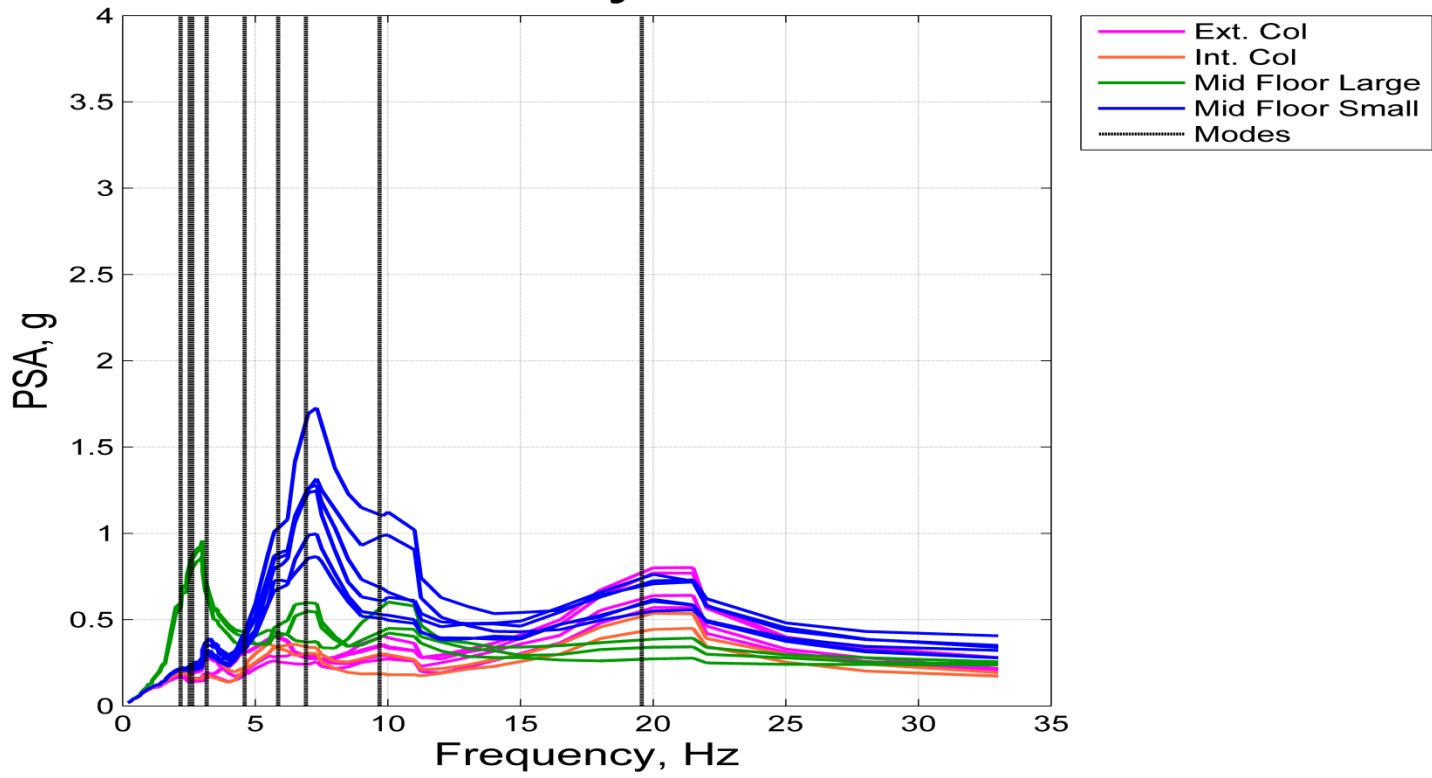


Figure 26: 5<sup>th</sup> story floor response spectra for selected locations.

# Ground Level

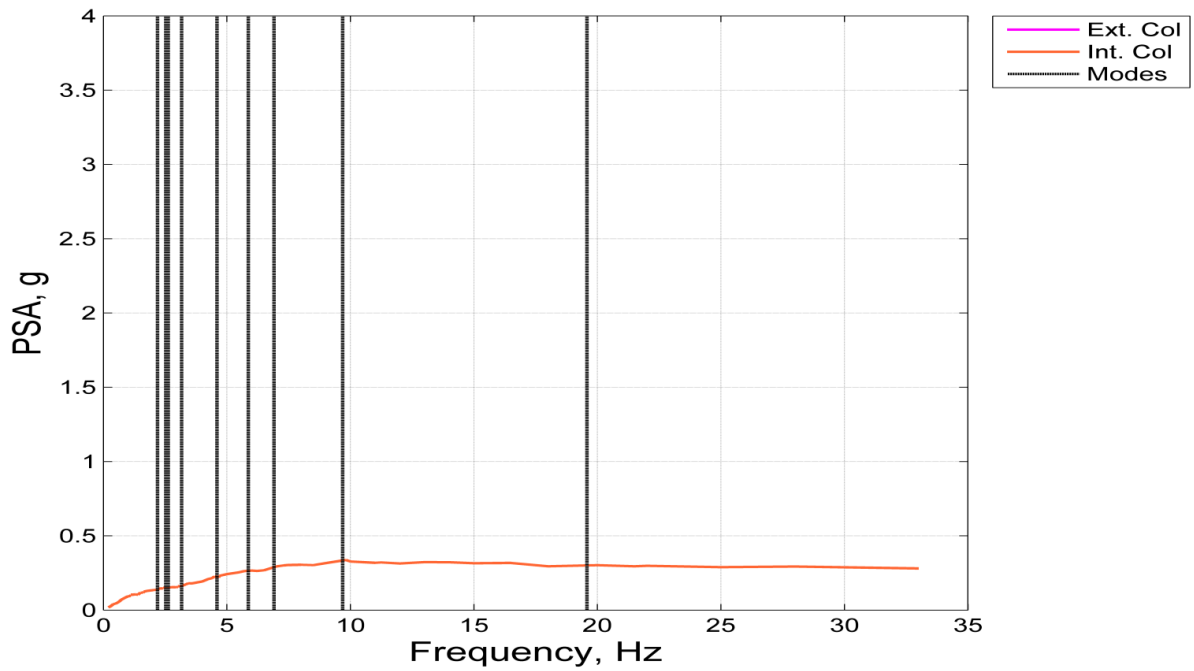


Figure 27: Ground floor response spectra.

As can be seen from the plots both the exterior and interior columns and some of the larger open slab sections of the floor see an increase in acceleration around 22 Hz. This frequency is close to the 22<sup>nd</sup> mode (19.6 Hz) of the structure; the last vertical mode considered in the analysis. The 22<sup>nd</sup> mode shape corresponds to columns moving out of phase with the interior slab sections which may explain the increase in floor response spectral acceleration.

The acceleration is greatest in the bottom floors of the building then recedes towards the middle and picks back up towards the roof level. This acceleration increase throughout the height of the structure may be the result of component frequencies interacting with the higher mode frequencies of the ground motions used in this study. The ground motions here have an average highest usable frequency of approximately 40Hz. Therefore, the frequency range beyond the last vertical mode is approximately 20Hz. It is possible that frequencies in this range have a disproportionate effect on the acceleration response of components compared to lower frequencies since it has been reported that vertical component accelerations are sensitive to higher modes.

From the ground floor to the roof the slab sections see an increase in acceleration in the first 10 Hz as the floor height increases. The vertical lines in Figure 23 through Figure 27 represent the modal frequencies in the vertical direction as shown in Table 31. In the Figures above, many of the peaks in acceleration of the slab sections coincide with the vertical frequencies of the structure. A good example of this is found in Figure 25, the 10<sup>th</sup> floor, where the larger slab section has peaks coinciding with the 1,2,3,4 and 6<sup>th</sup> modes. The remaining story FRS figures can be seen in Appendix D.

The peak vertical floor acceleration (PVFA) is also important because typically components are well anchored to the floor, columns, or walls of the primary structure since in most cases equipment is desired to remain stationary. The PVFA is taken at 33 Hz and can be seen along the height of the building in the following figures.

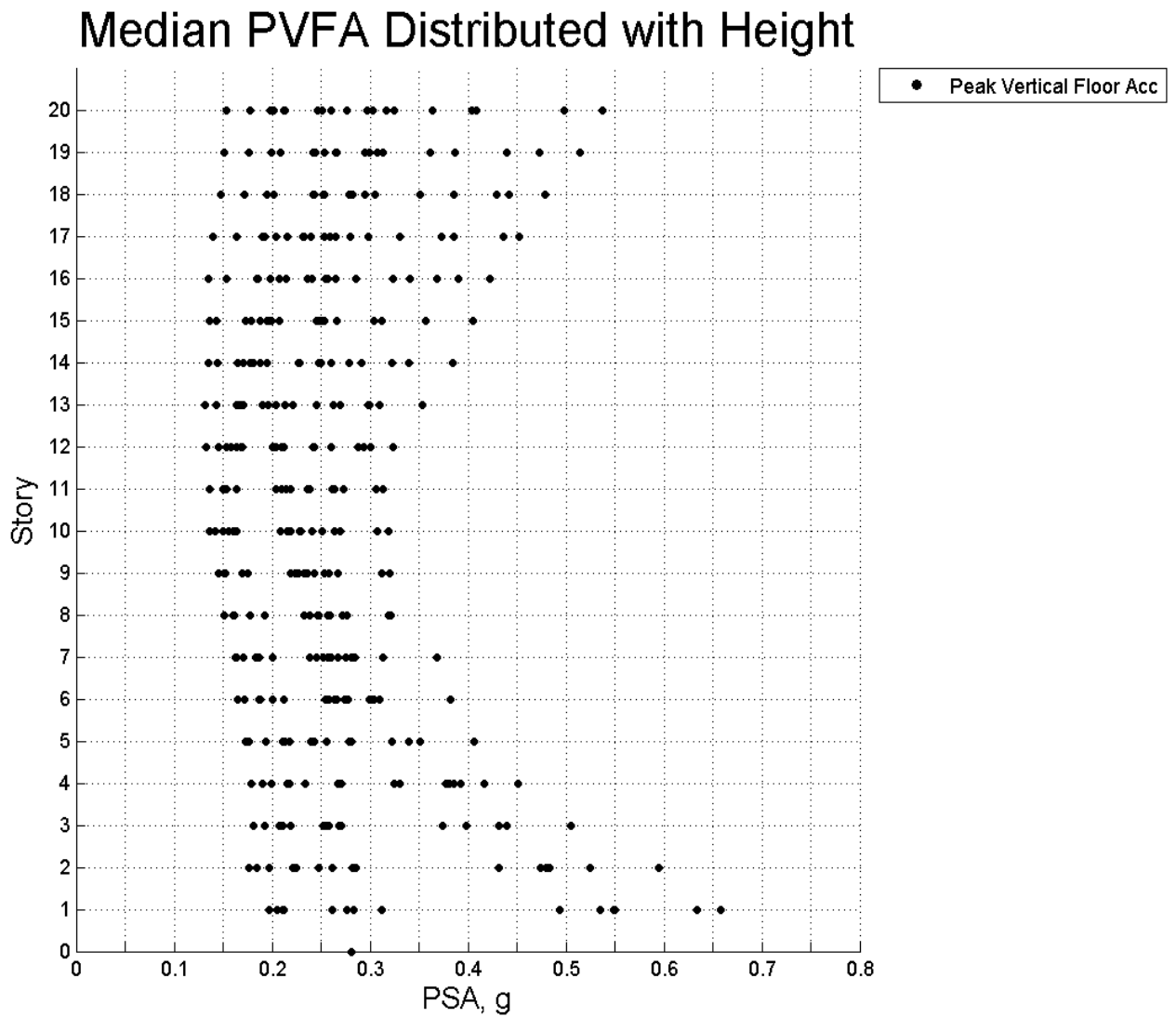


Figure 28: Median PVFA values.

# Median Peak Vertical Floor Acceleration

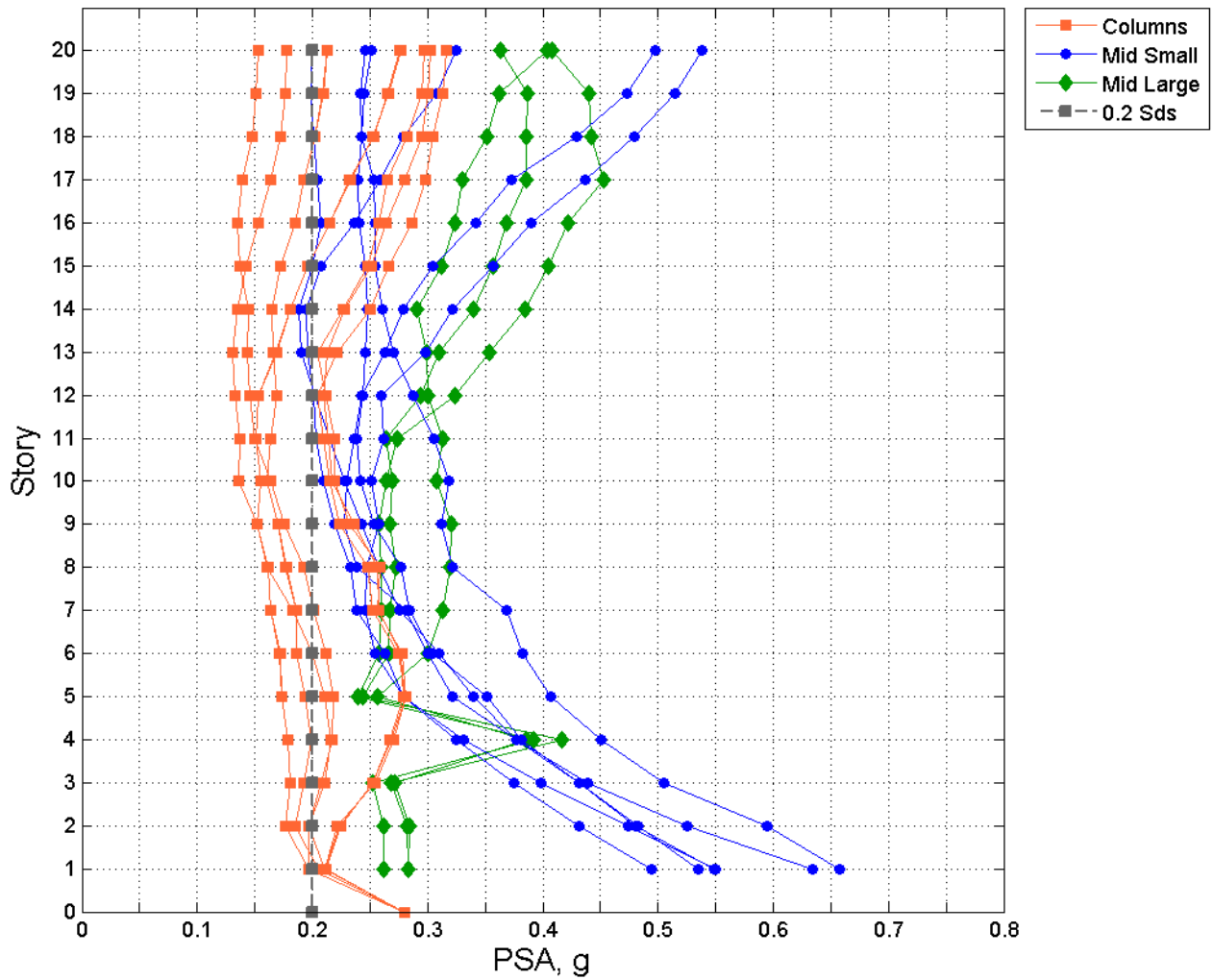


Figure 29: Median PVFA values classified by location in floor plan.



## Median PVFA Per Column

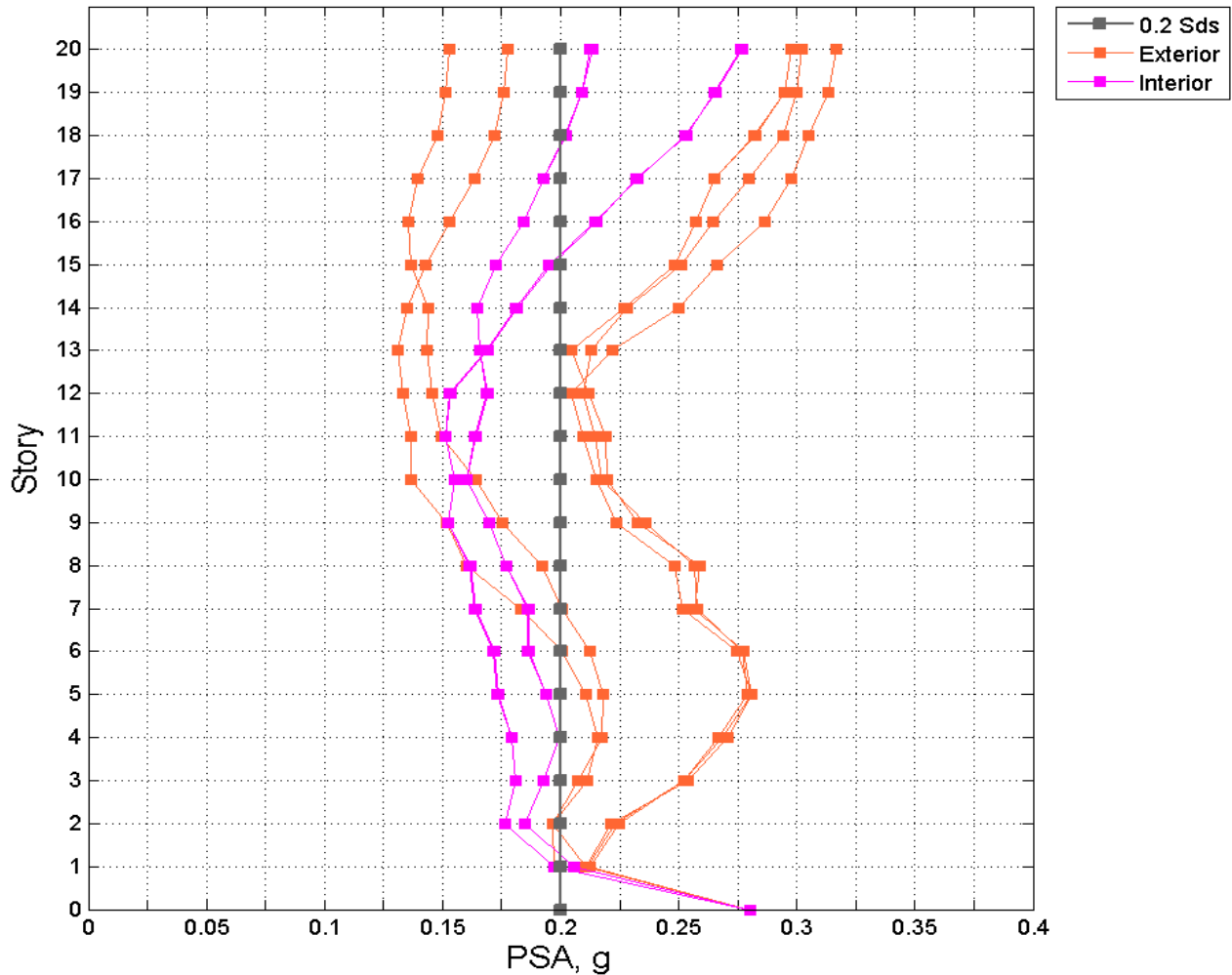


Figure 30: Median PFA values at exterior and interior columns.

Generally, the larger slab sections see an increasing trend in the median peak vertical floor accelerations (PVFA) except for the roof and the discontinuity in the 4<sup>th</sup> story. This large increase in acceleration in the 4<sup>th</sup> floor exists for all of the large slab sections. It is also found only in the larger slab sections. On the other hand, the smaller slab sections experience large accelerations at the bottom and top of the structure producing a “C” shaped response over the whole height. The median PVFA of points on the smaller slab sections tends to be much larger than all of the other sections. The only exceptions to this observation are in floors 7 through 11

where the larger slab sections dominate all but one of the smaller slab sections and in floors 11 through 17 where the larger slab section accelerations tend to overcome the smaller section response. In the remaining top floors of the building the small slab sections dominate and approach the large levels found in the bottom stories. The column accelerations over the height of the building do not resemble either the small or large slab sections and there are differences even between the interior and exterior columns. In the exterior columns accelerations are generally larger which may be due to the fact that generally, the exterior columns are larger and stiffer W sections. About half of the column PVFA fall below the ASCE 7-10 design limitation of  $0.20S_{ds}$  which for this case becomes 0.20 g and is shown in Figure 29 and Figure 30 as a vertical line. The vast majority of all mid slab section points are greater than the prescribed ASCE 7-10 limit. This suggests that the limit required by ASCE 7-10 may be unconservative.

The horizontal earthquake design force equation from ASCE 7-10 incorporates a component that accounts for ground and floor amplification over the height. The code uses a linear characterization over the height where the roof level experiences the highest amplification. The underlying assumption is that, buildings are very stiff in the vertical direction and as a result ASCE 7-10 does not require a similar component which amplifies the ground to floor acceleration when estimating design vertical earthquake forces. To investigate whether this 20-story building experiences ground amplification throughout the height, all of the peak vertical acceleration values have been normalized to the peak ground acceleration.

# Median PFA/PGA with Height

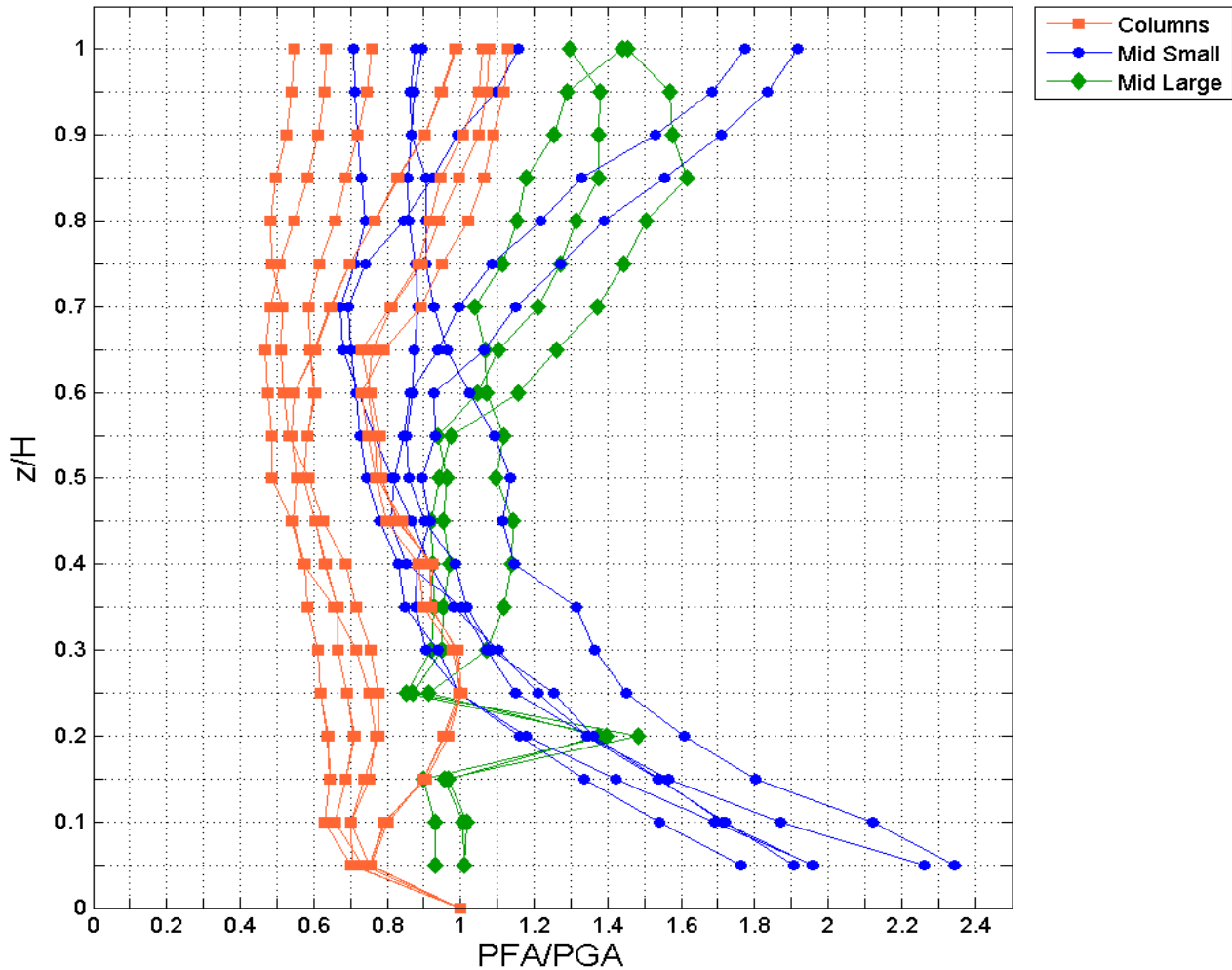


Figure 31: Median PFA/PGA values by location in floor plan.

## Median PFA/PGA per Column

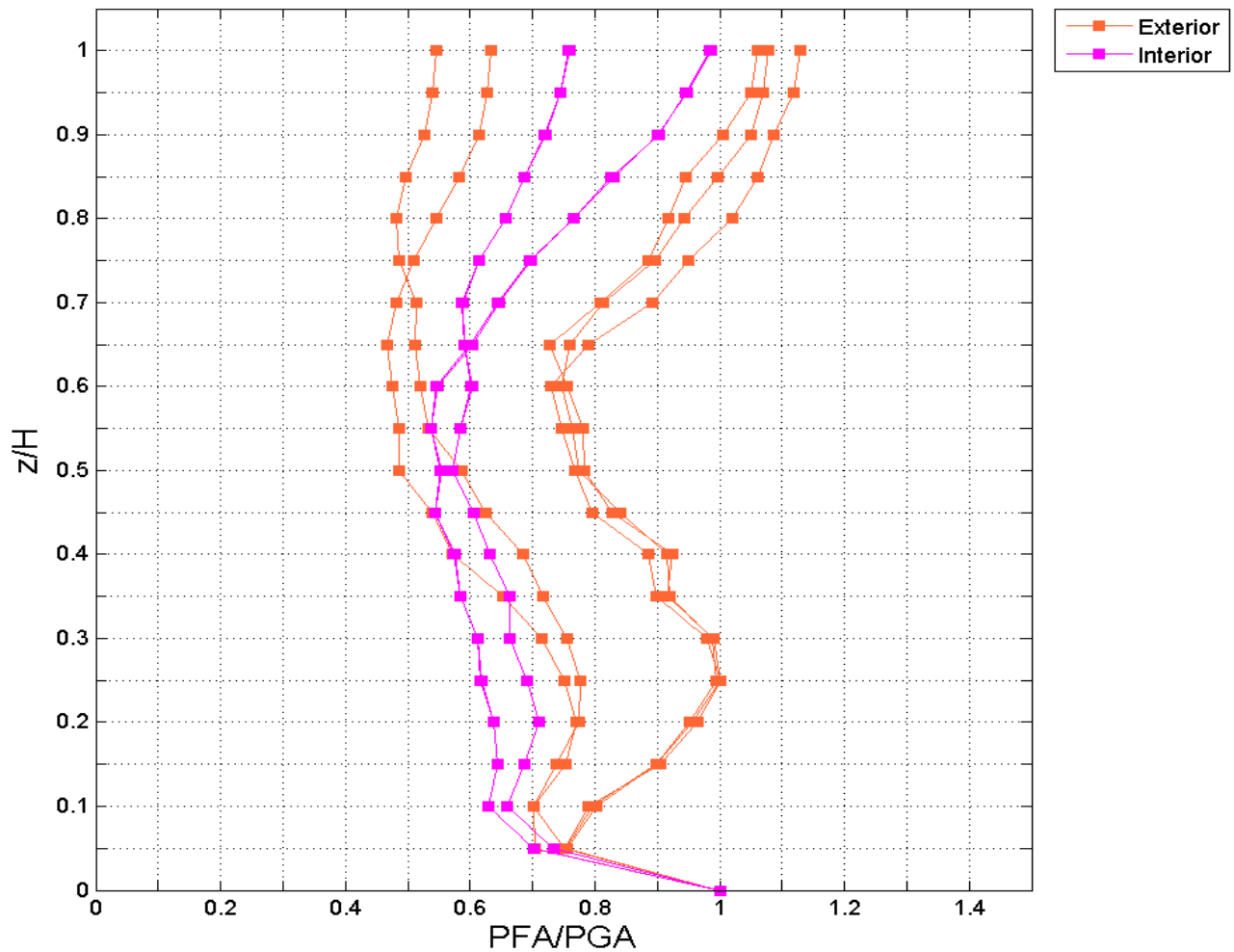


Figure 32: Median PFA/PGA values on the exterior and interior columns.

It can be seen from Figure 31 and Figure 32 the ratio of PVFA/PGA changes over the height of the building. While column acceleration demands increase in the very top floors the interior column demands never overcome the ground acceleration whereas some exterior columns do overcome the ground acceleration by approximately 10% for a PGA of 0.281g. The large and small slab sections median PVFA/PGA ratios vary from about 0.7 to 2.3. The largest values amplified with respect to ground are found in the smaller slab section. These sections are stiffer because of shorter unsupported lengths, which attract larger accelerations.

## **4.2 Comparison with Studies on the LA SAC 20-story Structure**

Peak vertical floor acceleration demands for columns are similar to those obtained from Pekcan et al. [4] For instance, the variation of PFVA/PGA along the height of the building shows an increasing trend that can be observed in the upper stories as seen in Figure 33. This trend is consistent with the one observed in this study (Figures 31 to 32). Median values compare reasonably well too. However, PVFA/PGA ratios for the LA office building are between 0.5 and 1.1, whereas values around 1.0 are observed for the SAC 20-story structure (see Figure 33).

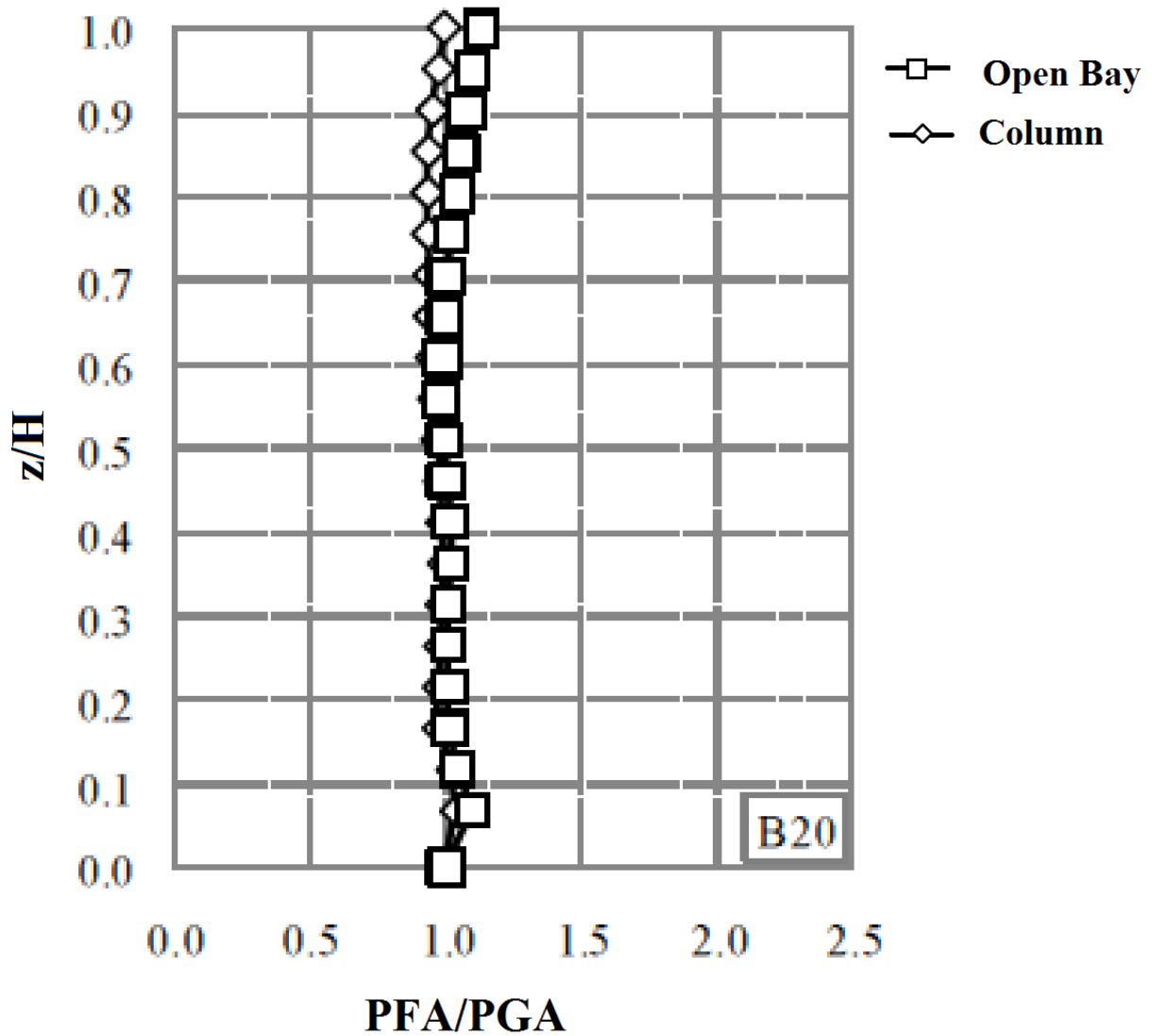


Figure 33: Median PFA/PGA values for the SAC 20-story office building. [4]

The similarity and uniformity between the column and slab vertical accelerations lead Pekcan et al. [4] to conclude that the column “axial stiffness is sufficiently great to provide essentially rigid body motion in the vertical direction.” However, the slab accelerations normalized to ground for the building presented in this study take on a “C” shape over the height with slab to ground median amplification values between 0.5 and 2.4. The SAC building on the other hand has a

height wise shape resembling a straight line with an acceleration range approximately between 1 and 1.1.

This discrepancy may be explained by differences in the plan layout, column sections, floor diaphragm out-of-plane flexibilities, as well as the approach taken to model the floor system.

Figure 34 presents results obtained from statistics on the smaller group of ground motion recordings used by Pekcan et al. [4] It can be seen that values and trends in the variation of vertical acceleration responses are still consistent with the ones obtained using the larger ground motion set in this study.

# Median Peak Vertical Floor Acceleration

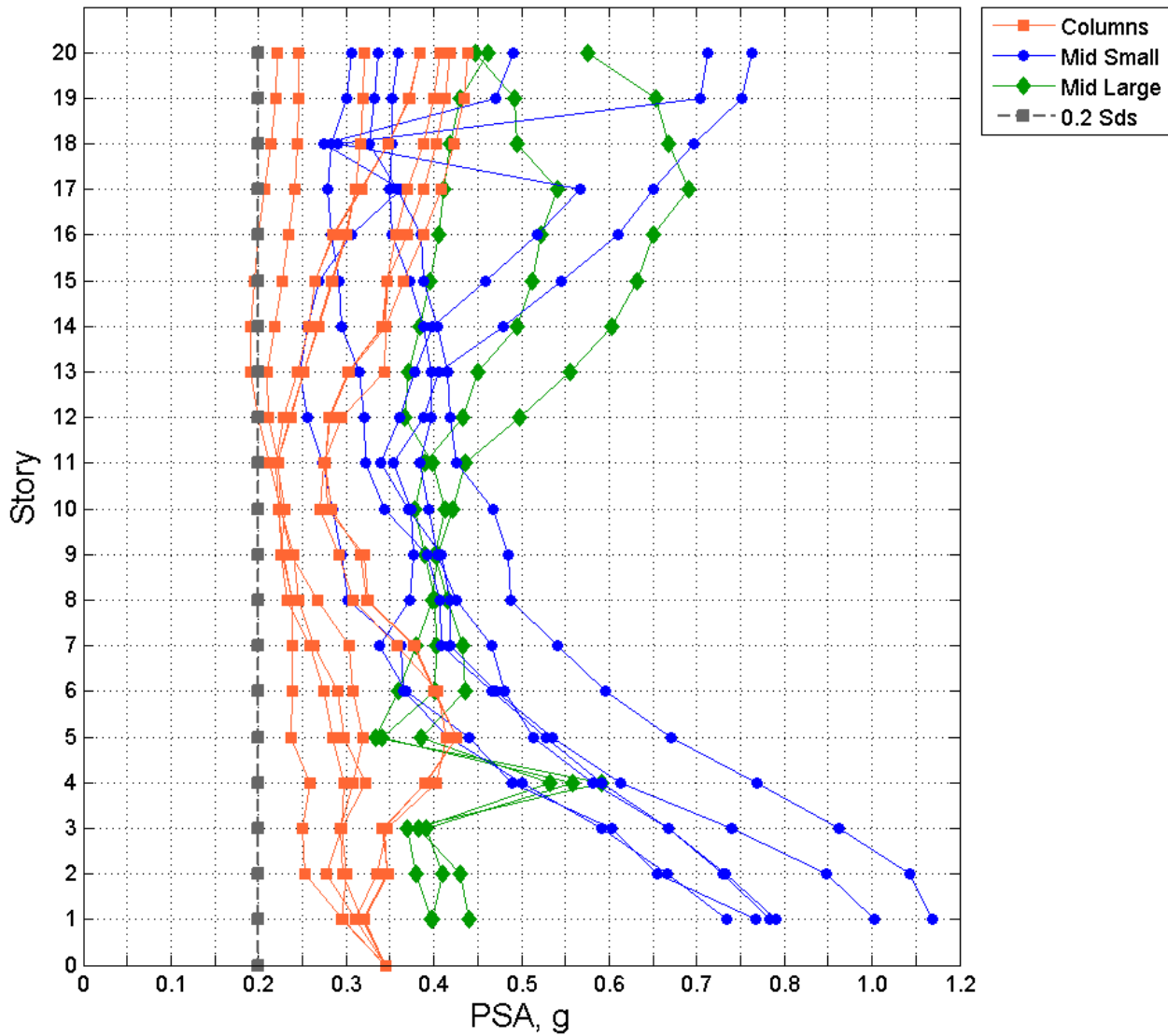


Figure 34: Median PVFA values produced by the ground motions used in Pekcan et al. study.

A closer look at Figure 34 indicates that using the ground motions from the University of Nevada- Reno study produces median vertical floor acceleration demands that are slightly larger than the median results of the 106 ground motions used in this study. This is due to the smaller sample size; however, the trends in the variation of floor accelerations along the height are still consistent between the two data sets.



Differences between the two office buildings plan view floor layout may help explain some of the differences found in these two studies. The layout of the SAC office building is 6 bays at 20 foot in the East-West direction and 5 bays at 20 foot in the North-South direction. The bays are uniform and the overall aspect ratio of the SAC office building is 1.2. The floor plan is relatively uniform and the median PFA/PGA values shown in Figure 33 are also fairly uniform along the height of the building.

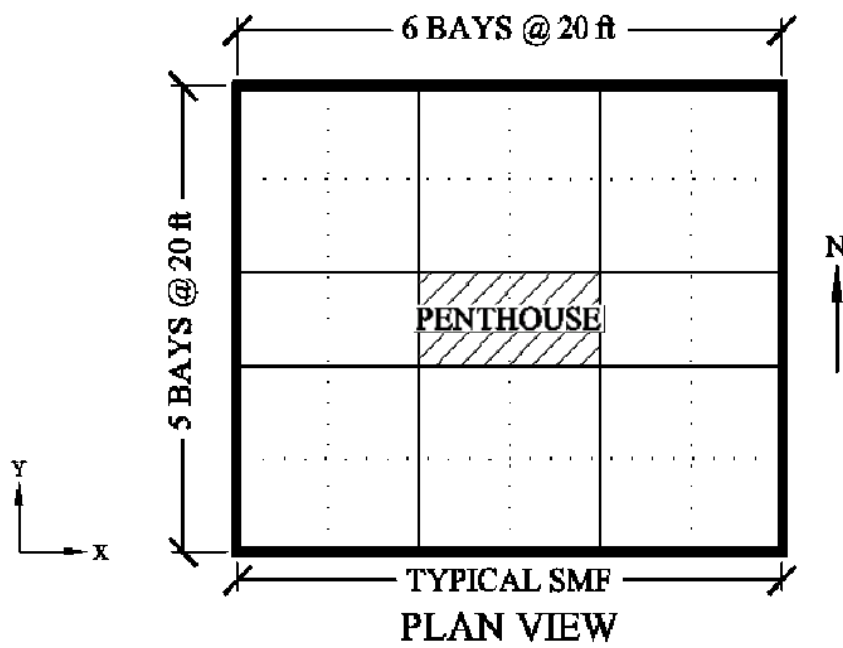


Figure 35: Roof plan view, 20-story office building used in Pekcan et al. study.

In this study the bay size is nonuniform (20-by-20 and 40-by-20 foot). The out-of-plane stiffness of the shorter bay is approximately 2.08 times greater than the out-of-plane stiffness of the larger bay. This stiffness comparison rests on many simplifying assumptions such as analyzing the concrete bays as simply supported (at all edges) rectangular plates bending out-of-plane under uniform loading. This nonuniformity in the out-of-plane stiffness of the floor may partially explain the lack of uniformity in the PVFA results from Figure 31.

The larger slab sections, rather than the smaller ones with the exact same dimensions, more closely resemble the 20-by-20 foot section acceleration responses of the SAC building. The SAC building has more bays, and hence, more columns. Since vertical inertia forces are transferred to the floor system through the columns, an increase in the number of columns may provide a more uniform “loading” to the floor, thereby yielding floor acceleration results that are more similar to the column output.

Differences in the overall dynamic characteristics between the buildings may also help explain the differences in vertical acceleration values. The SAC building has a fundamental period of approximately 3.9 seconds while building considered in this study has a fundamental period of 5.5 seconds. This building is more flexible when it comes to the vertical direction as well with a fundamental period of 0.46 seconds (2.2 Hz) while the SAC building has 0.28 second (3.6 Hz) vertical fundamental period. The largest frequency obtained for the structure used in this study is of 19.6 Hz, which corresponds to mode 22. This frequency is lower than the highest corner frequency used to correct the ground motion recordings used in this study (i.e., 20 to 60 Hz.) However, if the building were more rigid, as it is the case for the SAC building; then, it would have higher modes with higher frequencies. In that case, it is conceivable that some ground motions may not have the frequency content to adequately excite the whole structure or certain higher modes that have significant modal mass contributions. Therefore, the estimated vertical floor accelerations may be smaller. Admittedly, without an effective modal mass breakdown for the SAC building analysis, it is difficult to evaluate whether higher mode effects may explain some of the differences in acceleration results.

Another relevant difference between the two buildings is the design of the floor system and how it is modeled. The SAC building analysis uses shell elements with large thicknesses in order to account for the composite action between the floor slab and secondary beams, and hence, does not explicitly model the secondary beams. The actual mass of the system is manually added to each node. In principle, this method of modeling should reasonably capture the out-of-plane flexibility and the global dynamic behavior of the floor system. However, by refining the model through the use of separate beam and slab elements, as well as by ensuring compatibility through displacement constraints, the local dynamic behavior of the model could be greatly improved. With these changes, the mass of the system is more realistically distributed. Improvements in the local dynamic behavior of the model will be reflected in more realistic floor response spectra (FRS). The latter more refined approach is used in this report and may also help explain the differences in acceleration results when compared to the Pekcan et al. [4] study.

There is also evidence to suggest that for shorter buildings, the PVFA shows an increasing trend that contrasts the uniform vertical acceleration found in very axially stiff column systems. Based on the floor plan of the 20-story office building used in this study, a series of simplified multiple-degree-of-freedom (MDOF) systems (i.e., stick models) having various building heights including 5, 10, 15, and 20 stories are modeled. These stick models lump the entire floor mass at one level and frame elements are used to connect all of the masses. The vertical stiffness of each story frame is taken as the summation of the in-plan column properties (i.e., the total cross-sectional area of each column at each story level.) While these models are simple, they can be used to provide a general idea of column dynamic behavior with little computational time. A 27-ground motion subset of the total 106 set is used on each model and floor response spectra are

obtained. The PVFA is plotted against the height of each building and all stories show an increasing trend with height (Figure 36 to Figure 40).

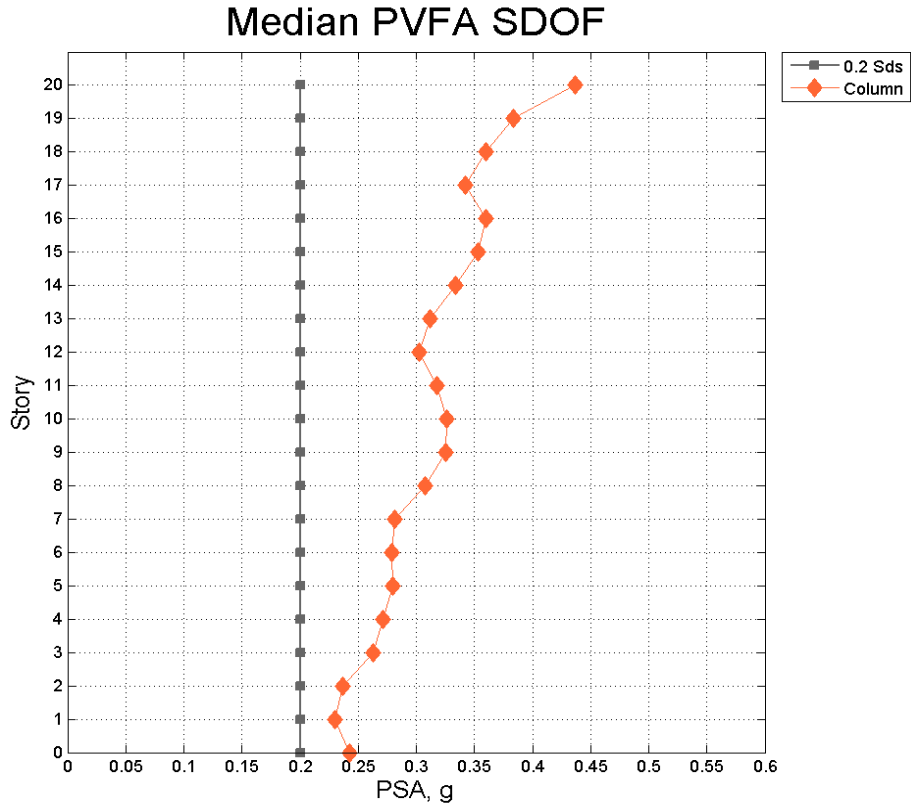


Figure 36: Median PVFA, simplified 20-story stick model.

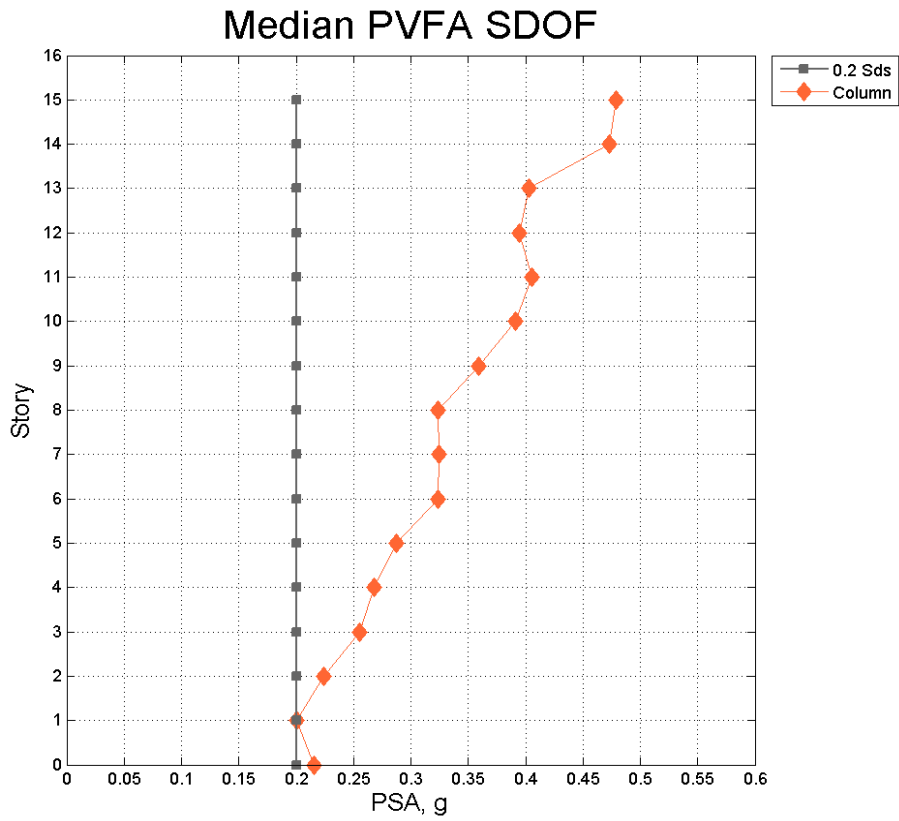


Figure 37: Median PVFA, simplified 15-story stick model.

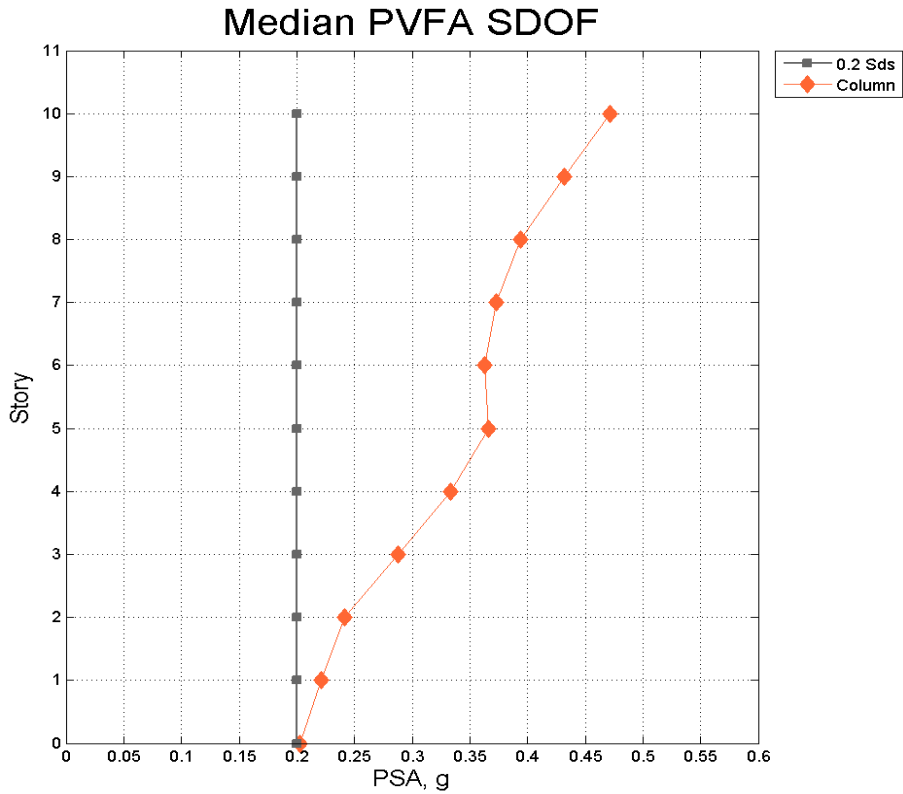


Figure 38: Median PVFA, simplified 10-story stick model.

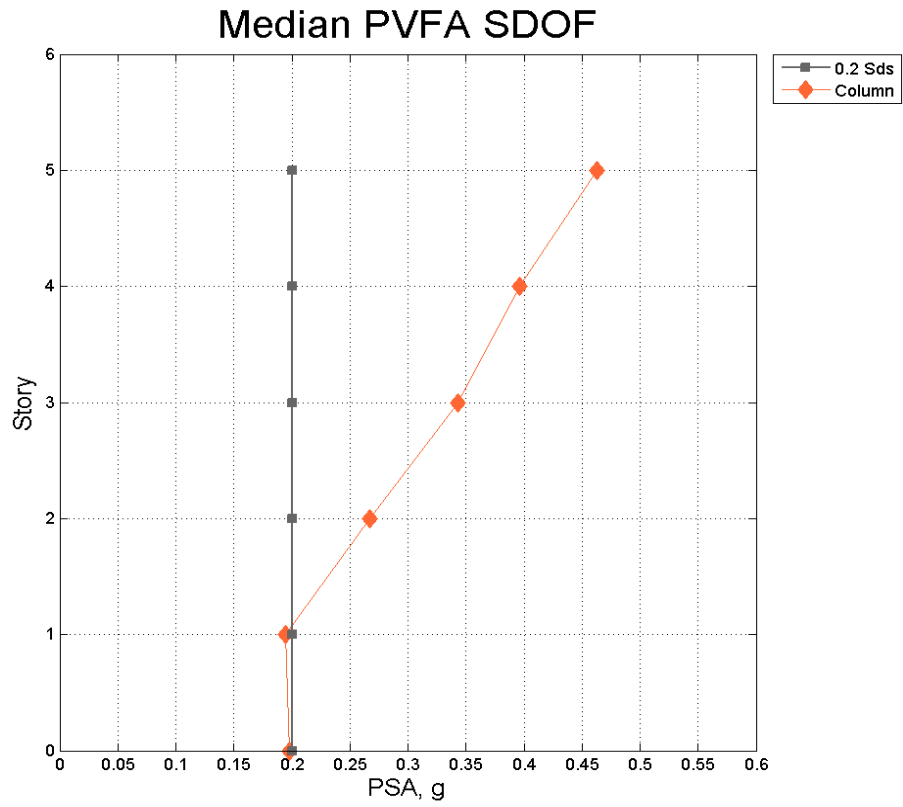


Figure 39: Median PVFA, simplified 5-story stick model.

## Median PFA/PGA SDOF Systems

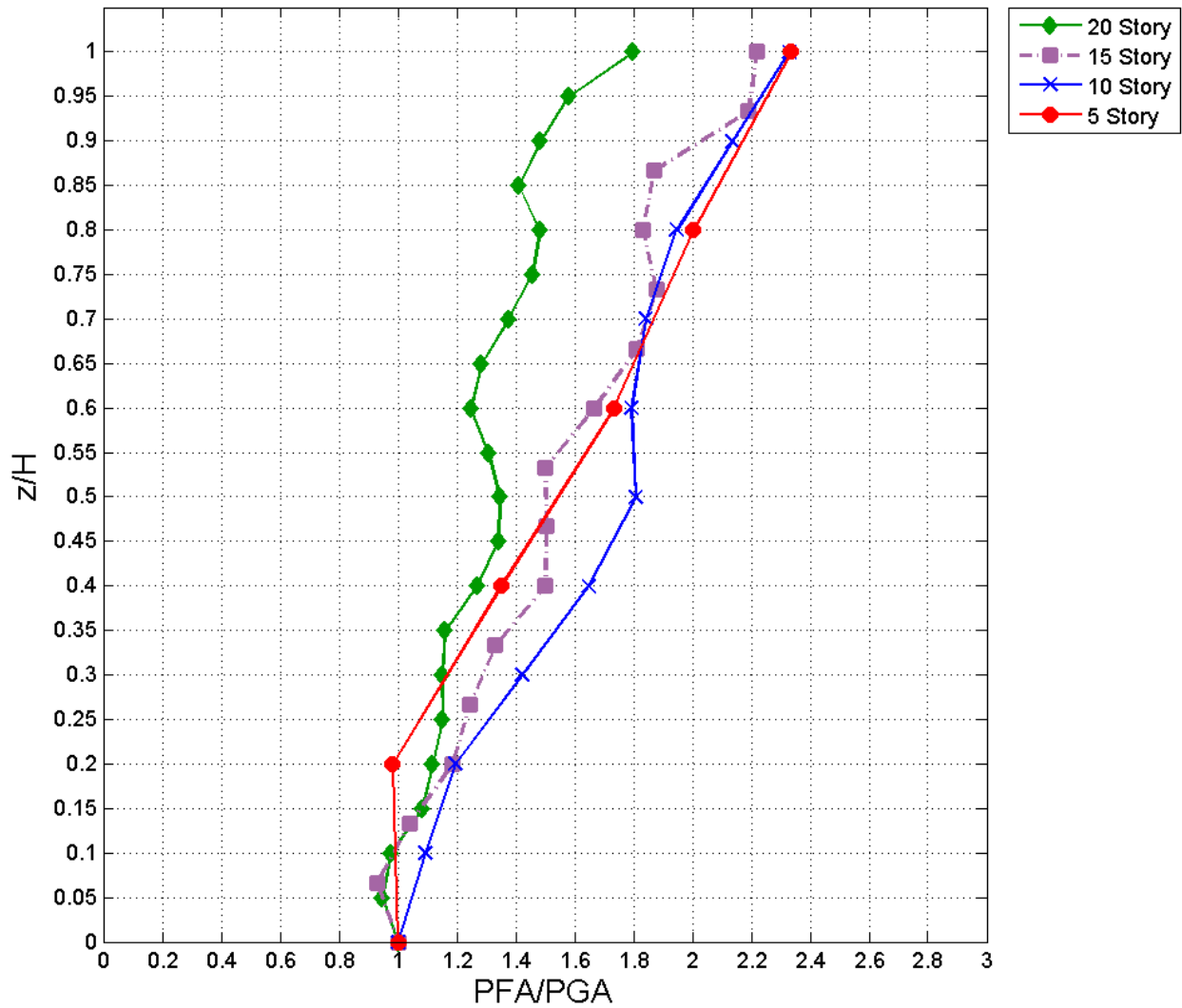


Figure 40: Median PVFA/PGA, all stick models.

As can be seen from the figures above, all of the models show a similar increasing acceleration trend along the height of the building with roof vertical acceleration values ranging from 1.8 to 2.3 times the PGA. The shorter story buildings from the /university of Nevada-Reno study including the 3- and 9-story structures show a similar trend (Figure 41).

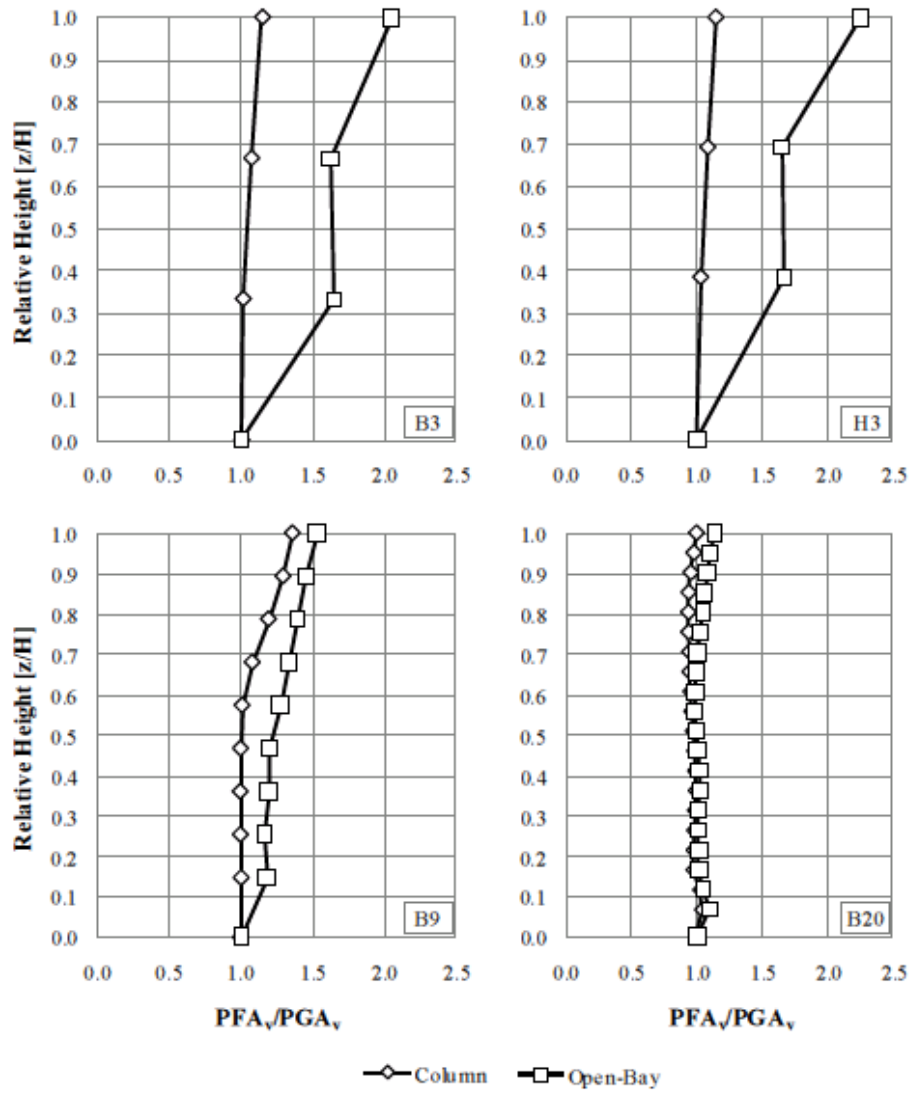


Figure 41: Median PFA/PGA values for all the building which Pekcan et al. investigated.



# Median Peak Vertical Floor Acceleration

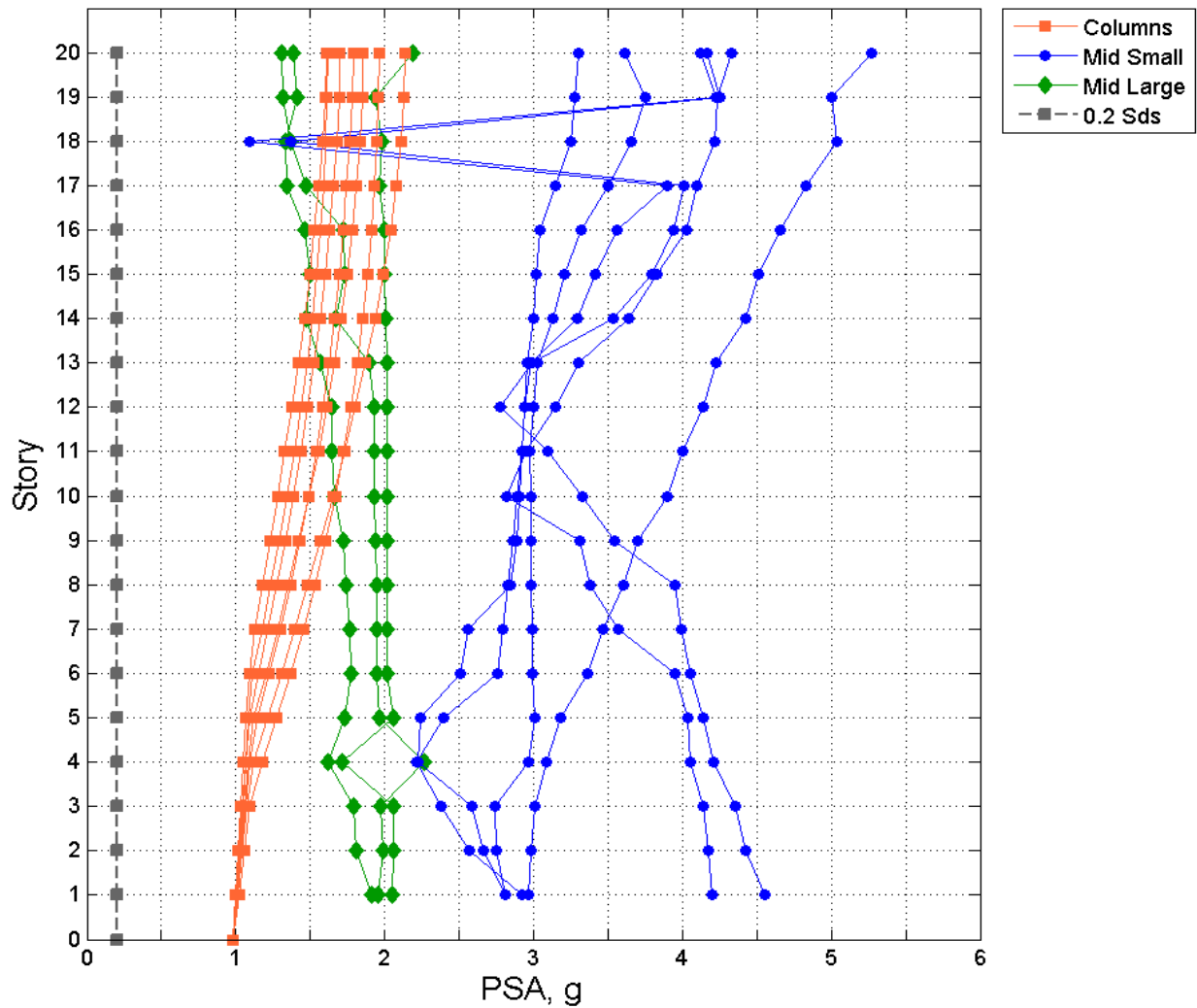


Figure 42: Median PVFA values. 20-story building with infinitely rigid columns.

A model with infinitely rigid columns was also developed in this study to evaluate the effect that column rigidity has on the results. PVFA results corresponding to this case demonstrate that when columns are infinitely rigid, column and slab vertical accelerations are different and do not overlap as depicted in Figure 42, which shows results for a set of 18 randomly selected ground motions.

Vertical acceleration values become more uniform for example all of the interior and exterior columns exhibit nearly identical behavior. The large slab section accelerations are almost entirely constant until about the 16<sup>th</sup> floor. They also overlap with the column accelerations in the upper stories and not at the bottom stories as it is the case for the SAC building (see Figure 42). The “C” shape acceleration profile evident in the small slab sections of the model with finite column flexibilities is replaced by a much more uniform pattern. The discontinuity found in the 18<sup>th</sup> story of the small slab section is most likely explained by the small sample size of ground motions. The infinitely rigid column model is broadly consistent with the flexible column model in that the largest accelerations are found at the small slab sections. The infinitely rigid column model also suggests that column and large slab section accelerations increase towards the higher floors.

### **4.3 Evaluation of ASCE 7-10 Design Vertical Acceleration**

As can be seen from the following figures, the design vertical floor acceleration of  $0.2S_{ds}$  is exceeded at least 50% of the time for the majority of the cases investigated in this study. When 84<sup>th</sup> percentile responses are evaluated (mean + one standard deviation), it is evident that the prescribed value of  $0.2S_{ds}$  significantly underestimates the expected PVFA demands.

Furthermore there is a high degree of variability in the acceleration values. For example, the 84<sup>th</sup> percentile column values range from being 0.13 to 0.42 g larger than the median values.

Similarly, the slab 84<sup>th</sup> percentile acceleration values range from 0.19 to 0.88 g larger than the median values. This variation is due to the record-to-record variability (i.e., aleatory variability) present in the analyses. Based on this case study, the  $0.2S_{ds}$  code provision tends to significantly

underestimate the peak vertical floor acceleration in this structure, which highlights the need for additional studies on floor acceleration demands in buildings.

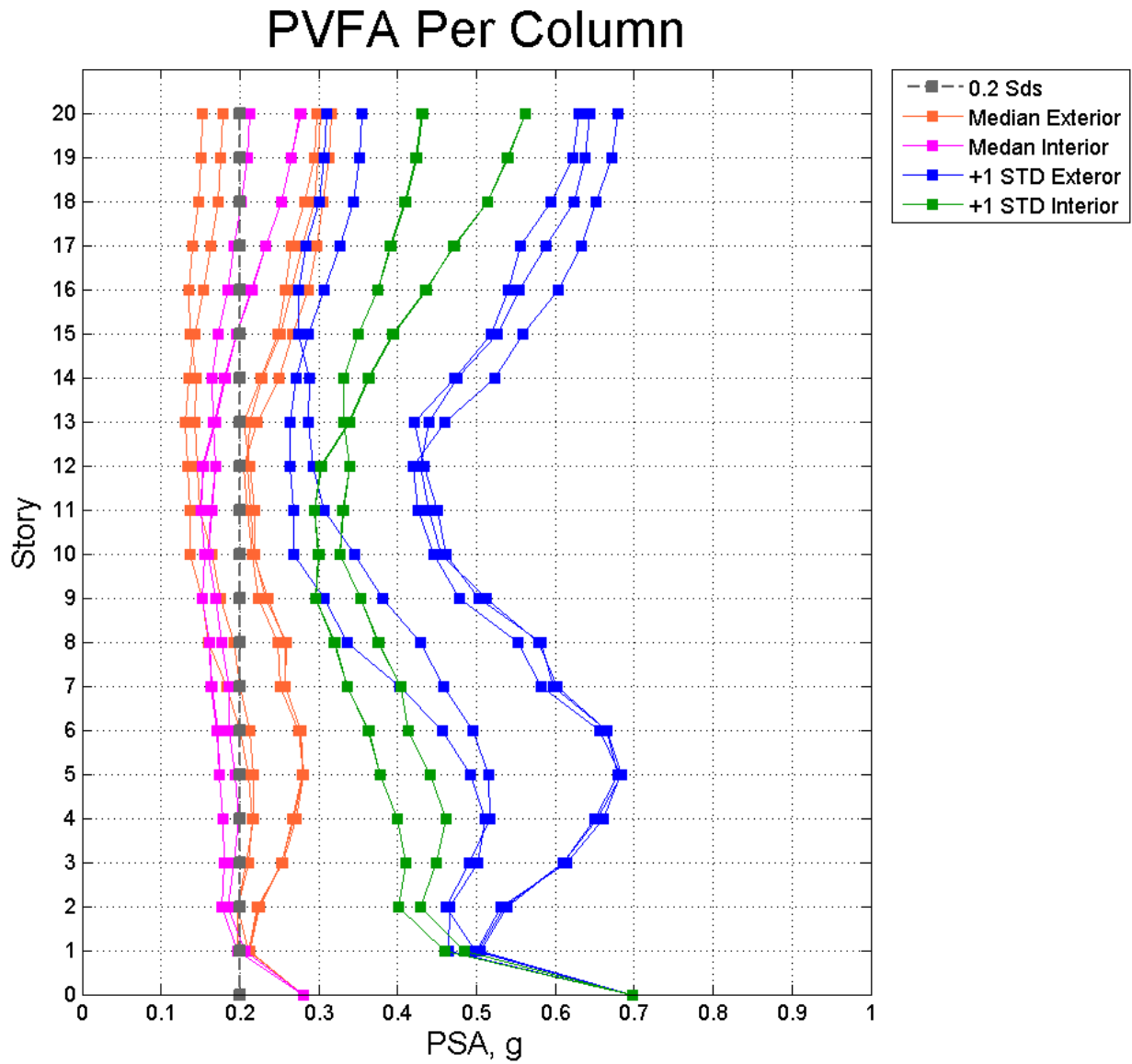


Figure 43: Mean and 84<sup>th</sup> percentile PVFA values for columns.

# Slab Section PVFA

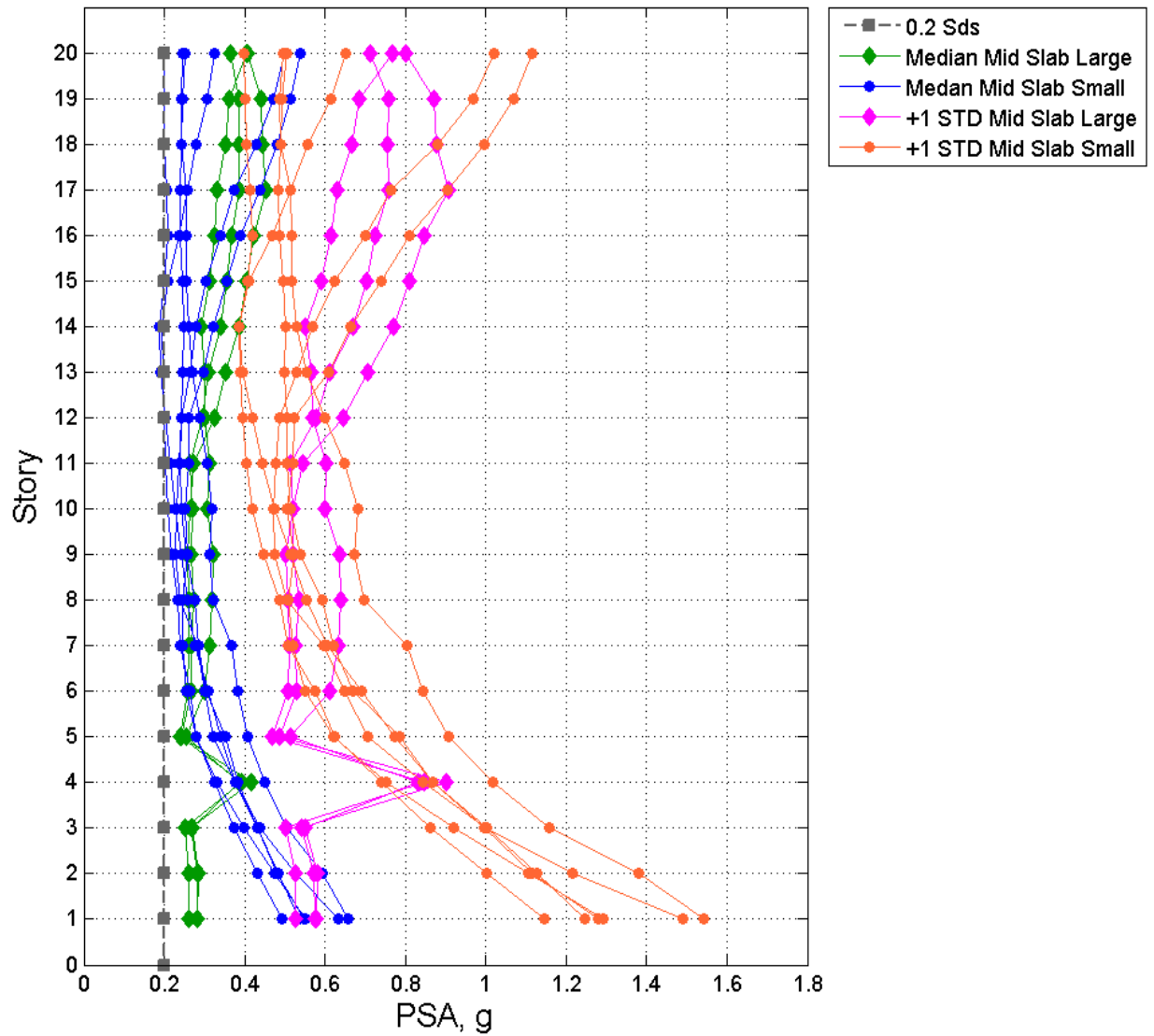


Figure 44: Mean and 84<sup>th</sup> percentile PVFA for the slab sections.

## CHAPTER 5

### CONCLUSION

#### **5.1 Summary & Final Remarks**

With the emergence of Performance-Based Design methods in the last two decades, society and building owners demand higher building performance standards to minimize casualties, injuries, direct losses, indirect losses due to business interruption, and loss of functionality of essential facilities. These increasing demands relate to normal operating conditions, as well as during and post extreme events including earthquakes. In order to meet these expectations, structural engineers must properly design and analyze not only the primary structural elements but also architectural, mechanical, electrical components and contents. Apart from clean up and replacement cost, inadequate performance of nonstructural elements, their supports and attachments to the primary structure, may hinder egress, result in the loss of life, and or disrupt normal building operations and services for a significant period of time. Engineers rely on buildings codes and load standards such as ASCE 7-10 for the design of NSCs. However, historically, minimal attention has been placed on understanding and quantifying floor vertical acceleration demands on NSCs. Past earthquakes have shown that the vertical component of ground motion is important to prevent failure of components such as suspended ceilings, staircases among others.

In an effort to better understand vertical acceleration demands on rigid NSCs in multistory buildings and evaluate the adequacy of building code provisions, a 20-story office building located in Los Angeles, California is designed. Vertical acceleration demands are characterized through the use of floor acceleration spectra that are obtained for various points on the plan floor of the elastic primary structure exposed to a set of 106 recorded vertical ground motions. The main observations and results of this study are as follows:

- 1.) Peak vertical floor acceleration demands vary in plan and are strongly dependent on the out-of-plane flexibility of the floor system.
- 2.) The highest vertical acceleration demands occur at smaller floor slab sections, followed by locations at larger floor slab sections, and then, smaller demands are obtained at column locations.
- 3.) The smaller slab sections have a “C” shape acceleration profile over the height of the building with median PVFA/PGA values ranging from 0.19 to 0.66 g.
- 4.) The median vertical acceleration profile for larger floor slab sections tend to increase in the upper floors of the building with PVFA.PGA values ranging from 0.24 to 0.45 g.
- 5.) Generally, exterior columns experience higher vertical accelerations than interior columns with median PVFA/PGA values ranging from 0.13 to 0.32 g. Interior column acceleration range from 0.15 to 0.28 g.
- 6.) Shorter story buildings tend to have increasing vertical floor acceleration profiles.
- 7.) The ASCE 7-10 vertical seismic force design provision that estimates seismic forces based on  $0.2S_{ds}$  underestimates the peak vertical floor acceleration by 68% for the majority of the points found in the floor plan at least 50% of the time. This code equation significantly underestimates the 84<sup>th</sup> percentile peak vertical floor acceleration demands.

Thus, the ASCE 7-10 equation for estimation of component vertical floor accelerations should be further evaluated analytically and experimentally with additional structures and ground motions.

## **5.2 Future Work Considerations**

The work presented here only focuses on one building. In order to further characterize vertical acceleration demands research efforts should concentrate on a parametric study with varying building designs including various concrete deck thicknesses, floor and slab aspect ratios, number of columns and their locations, column stiffness, nonlinear effects, story height and most importantly varying the primary structure beyond the steel moment frame type to include other types of lateral load resisting systems, materials, and configurations. Furthermore, practicing structural engineering designers who are designing acceleration sensitive equipment should understand ASCE 7-10 may be unconservative and they should use engineering judgment to quantify their design demands.

APPENDIX A

CONTROLLING LATERAL LOAD CASE

**A.1 ELF Summary**

Table A.1.1: ELF Seismic Criteria.

Seismic Criteria	Symbol	Value	Units
Importance Factor	$I$	1	--
Short Period Design Acceleration	$S_{DS}$	1	g
One Second Period Design Acceleration	$S_{DI}$	0.6	g
Distribution Exponent	$k$	1.95	--
Seismic Response Coefficient	$C_S$	0.044	--
Effective Seismic Weight	$W$	28,254	kip
Base Shear	$V$	1,243	kip

Table A.1.2: Equivalent Lateral Forces and Moments.

Story $x$	Elevation $h_x$	Story Weight $w_x$	$w_x h_x^k$	$w_x h_x^k / \sum w_x h_x^k$	$F_x$	$M_x$
--	ft	kip	kip-ft	--	kips	kip-ft
20	262	1,338	71,248,037	0.130	161	42,308
19	249	1,416	68,262,801	0.124	155	38,524
18	236	1,416	61,471,163	0.112	139	32,880
17	223	1,416	55,027,445	0.100	125	27,812
16	210	1,416	48,932,549	0.089	111	23,290
15	197	1,416	43,187,431	0.079	98	19,283
14	184	1,416	37,793,113	0.069	86	15,761
13	171	1,416	32,750,690	0.060	74	12,693
12	158	1,416	28,061,342	0.051	64	10,049
11	145	1,416	23,726,344	0.043	54	7,797
10	132	1,416	19,747,089	0.036	45	5,908
9	119	1,416	16,125,106	0.029	37	4,349
8	106	1,416	12,862,092	0.023	29	3,090
7	93	1,416	9,959,950	0.018	23	2,099
6	80	1,416	7,420,847	0.014	17	1,346
5	67	1,416	5,247,293	0.010	12	797
4	54	1,416	3,442,275	0.006	8	421



3	41	1,416	2,009,465	0.004	5	187
2	28	1,416	953,635	0.002	2	61
1	15	1,428	283,972	0.001	1	10
Total		28,254	548,512,639	1	<b>1,243</b>	<b>248,662</b>

## A.2 Wind Loading Summary

Table A.2.1: Wind Loading Directional Procedure Criteria.

Seismic Criteria	Symbol	Value	Units
Wind Loading Direction	--	North - South	--
Risk Category	--	II	--
Basic Wind Speed*	$V$	110	mph
Exposure Category	--	B	--
Enclosure Classification	--	Enclosed	--
Wind Directionality Factor	$k_d$	0.85	--
Topographic Factor	$K_{zt}$	1	--
Gust Effect Factor	$G$	0.937	--
Fundamental Natural Frequency	$n_1$	0.218	Hz
Damping Ratio	$\delta$	0.05	--

\* Note: according to the wind provisions in ASCE 7-10 Los Angeles is located in a “Special Wind Region”. The basic wind speed used herein is assumed to be the wind speed predominantly found throughout the rest of California.

Table A.2.2: Wind Forces and Moments in the North – South Direction.

Story $x$	Elevation $h_x$	Tributary Wind Area per Story $A_x$	Total Net Wind Pressure*	Story Force $F_x$	Overturning Moment $M_x$
--	ft	kip	psf	kip	kip-ft
20	262	910	39.1	35.5	9,314
19	249	1,820	38.8	70.6	17,576
18	236	1,820	38.4	69.9	16,494
17	223	1,820	38.0	69.2	15,423
16	210	1,820	37.6	68.4	14,364
15	197	1,820	37.1	67.6	13,319
14	184	1,820	36.7	66.8	12,287
13	171	1,820	36.2	65.9	11,269
12	158	1,820	35.7	65.0	10,267
11	145	1,820	35.2	64.0	9,280
10	132	1,820	34.6	63.0	8,310

9	119	1,820	34.0	61.8	7,359
8	106	1,820	33.3	60.6	6,426
7	93	1,820	32.6	59.3	5,515
6	80	1,820	31.8	57.8	4,627
5	67	1,820	30.9	56.2	3,765
4	54	1,820	29.8	54.3	2,933
3	41	1,820	28.6	52.1	2,134
2	28	1,820	27.0	49.2	1,378
1	15	1,960	25.1	49.3	739
0	0	1,050	24.8	26.1	0
<b>Total</b>				<b>1,233</b>	<b>172,779</b>

\* Note: the total net wind pressure is the summation of the average leeward and windward pressure over the tributary area of each story.

## APPENDIX B

### GROUND MOTIONS

#### **B.1 Ground Motion Summary**

The ground motions used in this study are selected based on the following criteria:

Table B.1.1: Ground motion selection criteria.

<b>Ground Motion Characteristics</b>	<b>Value</b>	<b>Units</b>
Moment Magnitude	6.5 - 8	
Source Distance	0 - 30	km
Site Class	D	
Average Soil Shear Wave Velocity	183-365	m/s

Table B.1.2: Ground motion table heading description.

<b>Title</b>	<b>Description</b>
Number	Ground motion number in set. There are 106 ground motions.
NGA #	Unique number assigned to each ground record by PEER.
Event	Name of the earthquake event
Station	The name of the station where the ground motion was recorded
Year	The year the earthquake event took place
Mag.	The moment magnitude of the earthquake event
Mech.	Type of Fault Mechanism. Available mechanisms are: 1: Strike-Slip, 2: Normal, 3: Normal-Oblique, 4: Reverse, 5: Reverse-Oblique.
Pulse	Binary code to indicate if the unscaled ground motions have a velocity pulse. 0: No pulse like record 1: Pulse like record
Tp (sec)	Period of the velocity pulse.
D5-95 (sec)	Significant duration, the time needed to build up between 5 and 95 percent of the Arias intensity
Rjb (km)	Joyner-Boore distance to rupture plane
Rrup (km)	Closest distance to rupture plane
V <sub>s30</sub> (m/s)	Average shear velocity in the upper 30 meters of sediments
Lowest Usable Frequency (Hz)	The recommended lowest usable frequency for analysis due to record filtering.
Highest Usable Frequency (Hz)	The recommended highest usable frequency for analysis due to record filtering.

Table B.1.3: Ground motions and their characteristics.

Note: The \* indicates that there are 3 total acceleration records from the same monitoring station.

Number	NGA #	Event	Station	Year	Mag.	Lowest Usable Frequency (Hz)	Highest Usable Frequency (Hz)
1	68	San Fernando	LA - Hollywood Stor FF	1971	6.61	0.25	35
2	158	Imperial Valley	Aeropuerto Mexicali	1979	6.53	0.06	
3	159	Imperial Valley	Agrarias	1979	6.53	0.06	
4	160	Imperial Valley	Bonds Corner	1979	6.53	0.12	40
5	161	Imperial Valley	Brawley Airport	1979	6.53	0.12	40
6	162	Imperial Valley	Calexico Fire Station	1979	6.53	0.25	40
7	163	Imperial Valley	Calipatria Fire Station	1979	6.53	0.12	40
8	165	Imperial Valley	Chihuahua	1979	6.53	0.06	
9	167	Imperial Valley	Compuertas	1979	6.53	0.25	
10	169	Imperial Valley	Delta	1979	6.53	0.06	
11	170	Imperial Valley	EC County Center FF	1979	6.53	0.12	40
12	171	Imperial Valley	EC Meloland Overpass FF	1979	6.53	0.12	40
13	172	Imperial Valley	El Centro Array #1	1979	6.53	0.12	40
14	173	Imperial Valley	El Centro Array #10	1979	6.53	0.12	40
15	174	Imperial Valley	El Centro Array #11	1979	6.53	0.25	40
16	175	Imperial Valley	El Centro Array #12	1979	6.53	0.12	40
17	176	Imperial Valley	El Centro Array #13	1979	6.53	0.25	40
18	179	Imperial Valley	El Centro Array #4	1979	6.53	0.12	40
19	180	Imperial Valley	El Centro Array #5	1979	6.53	0.12	40
20	181	Imperial Valley	El Centro Array #6	1979	6.53	0.12	40
21	182	Imperial Valley	El Centro Array #7	1979	6.53	0.12	40
22	183	Imperial Valley	El Centro Array #8	1979	6.53	0.12	40
23	184	Imperial Valley	El Centro Differential Array	1979	6.53	0.12	40
24	185	Imperial Valley	Holtville Post Office	1979	6.53	0.12	40
25	187	Imperial Valley	Parachute Test Site	1979	6.53	0.12	40
26	189	Imperial Valley	SAHOP Casa Flores	1979	6.53	0.25	
27	190	Imperial Valley	Superstition Mtn Camera	1979	6.53	0.12	40
28	192	Imperial Valley	Westmorland Fire Sta	1979	6.53	0.12	40
29	290	Irpinia, Italy	Mercato San Severino	1980	6.9	0.38	30
30	721	Superstition Hills	El Centro Imp. Co. Cent	1987	6.54	0.12	40
31	728	Superstition Hills	Westmorland Fire Sta	1987	6.54	0.12	35
32	729	Superstition Hills	Wildlife Liquef. Array	1987	6.54	0.12	50
33	730	Spitak, Armenia	Gukasian	1988	6.77	0.62	25
34	737	Loma Prieta	Agnews State Hospital	1989	6.93	0.25	30
35	752	Loma Prieta	Capitola	1989	6.93	0.25	48

Table B.1.3 (continued): Ground motions and their characteristics.

Number	NGA #	Event	Station	Year	Mag.	Lowest Usable Frequency (Hz)	Highest Usable Frequency (Hz)
36	754	Loma Prieta	Coyote Lake Dam (Downst)	1989	6.93	0.12	30
37	764	Loma Prieta	Gilroy - Historic Bldg.	1989	6.93	0.25	38
38	766	Loma Prieta	Gilroy Array #2	1989	6.93	0.25	40
39	767	Loma Prieta	Gilroy Array #3	1989	6.93	0.12	33
40	768	Loma Prieta	Gilroy Array #4	1989	6.93	0.25	28
41	770	Loma Prieta	Gilroy Array #7	1989	6.93	0.25	40
42*	778	Loma Prieta	Hollister Diff. Array	1989	6.93	0.12	40
43	806	Loma Prieta	Sunnyvale - Colton Ave.	1989	6.93	0.12	40
44	821	Erzican, Turkey	Erzincan	1992	6.69	0.12	
45	829	Cape Mendocino	Rio Dell Overpass - FF	1992	7.01	0.07	23
46	850	Landers	Desert Hot Springs	1992	7.28	0.07	23
47	880	Landers	Mission Creek Fault	1992	7.28	0.11	
48	881	Landers	Morongo Valley	1992	7.28	0.28	
49	882	Landers	North Palm Springs	1992	7.28	0.28	
50	900	Landers	Yermo Fire Station	1992	7.28	0.07	23
51	949	Northridge	Arleta - Nordhoff Fire Sta	1994	6.69	0.12	23
52	953	Northridge	Beverly Hills - 14145 Mulhol	1994	6.69	0.25	30
53	959	Northridge	Canoga Park - Topanga Can	1994	6.69	0.06	30
54	960	Northridge	Canyon Country - W Lost Cany	1994	6.69	0.12	30
55	978	Northridge	Hollywood - Willoughby Ave	1994	6.69	0.16	30
56	985	Northridge	LA - Baldwin Hills	1994	6.69	0.16	23
57	987	Northridge	LA - Centinela St	1994	6.69	0.25	30
58	988	Northridge	LA - Century City CC North	1994	6.69	0.14	23
59	995	Northridge	LA - Hollywood Stor FF	1994	6.69	0.2	23
60	998	Northridge	LA - N Westmoreland	1994	6.69	0.25	30
61	1003	Northridge	LA - Saturn St	1994	6.69	0.12	30
62	1044	Northridge	Newhall - Fire Sta	1994	6.69	0.12	23
63	1045	Northridge	Newhall - W Pico Canyon Rd.	1994	6.69	0.12	30
64	1063	Northridge	Rinaldi Receiving Sta	1994	6.69	0.11	30
65	1077	Northridge	Santa Monica City Hall	1994	6.69	0.14	23
66	1082	Northridge	Sun Valley - Roscoe Blvd	1994	6.69	0.12	30
67	1084	Northridge	Sylmar - Converter Sta	1994	6.69	0.41	
68	1087	Northridge	Tarzana - Cedar Hill A	1994	6.69	0.1	23
69	1106	Kobe, Japan	KJMA	1995	6.9	0.06	
70	1107	Kobe, Japan	Kakogawa	1995	6.9	0.12	

Table B.1.3 (continued): Ground motions and their characteristics.

Number	NGA #	Event	Station	Year	Mag.	Lowest Usable Frequency (Hz)	Highest Usable Frequency (Hz)
71	1113	Kobe, Japan	OSAJ	1995	6.9	0.06	
72	1116	Kobe, Japan	Shin-Osaka	1995	6.9	0.12	23
73	1119	Kobe, Japan	Takarazuka	1995	6.9	0.36	40
74	1120	Kobe, Japan	Takatori	1995	6.9	0.36	
75	1158	Kocaeli, Turkey	Duzce	1999	7.51	0.24	20
76	1176	Kocaeli, Turkey	Yarimca	1999	7.51	0.09	50
77	1180	Chi-Chi, Taiwan	CHY002	1999	7.62	0.04	50
78	1194	Chi-Chi, Taiwan	CHY025	1999	7.62	0.06	50
79	1195	Chi-Chi, Taiwan	CHY026	1999	7.62	0.05	33
80	1203	Chi-Chi, Taiwan	CHY036	1999	7.62	0.06	50
81	1209	Chi-Chi, Taiwan	CHY047	1999	7.62	0.04	50
82	1238	Chi-Chi, Taiwan	CHY092	1999	7.62	0.06	24
83	1244	Chi-Chi, Taiwan	CHY101	1999	7.62	0.05	50
84	1246	Chi-Chi, Taiwan	CHY104	1999	7.62	0.06	50
85	1481	Chi-Chi, Taiwan	TCU038	1999	7.62	0.06	50
86	1483	Chi-Chi, Taiwan	TCU040	1999	7.62	0.04	50
87	1498	Chi-Chi, Taiwan	TCU059	1999	7.62	0.04	30
88	1500	Chi-Chi, Taiwan	TCU061	1999	7.62	0.05	50
89	1502	Chi-Chi, Taiwan	TCU064	1999	7.62	0.04	50
90	1503	Chi-Chi, Taiwan	TCU065	1999	7.62	0.07	50
91	1513	Chi-Chi, Taiwan	TCU079	1999	7.62	0.25	50
92	1536	Chi-Chi, Taiwan	TCU110	1999	7.62	0.05	50
93	1537	Chi-Chi, Taiwan	TCU111	1999	7.62	0.05	50
94	1538	Chi-Chi, Taiwan	TCU112	1999	7.62	0.06	40
95	1540	Chi-Chi, Taiwan	TCU115	1999	7.62	0.06	50
96	1542	Chi-Chi, Taiwan	TCU117	1999	7.62	0.04	50
97	1543	Chi-Chi, Taiwan	TCU118	1999	7.62	0.06	50
98	1547	Chi-Chi, Taiwan	TCU123	1999	7.62	0.05	50
99	1553	Chi-Chi, Taiwan	TCU141	1999	7.62	0.06	50
100	1602	Duzce, Turkey	Bolu	1999	7.14	0.06	
101	1605	Duzce, Turkey	Duzce	1999	7.14	0.1	50
102*	1615	Duzce, Turkey	Lamont 1062	1999	7.14	0.06	50

Table B.1.4: Reno ground motions and their characteristics.

Number	NGA #	Event	Station	Year	Mag.	Lowest Usable Frequency (Hz)	Highest Usable Frequency (Hz)
1	68	San Fernando	LA - Hollywood Stor FF	1971	6.61	0.25	35
2	125	Friuli- Italy	Tolmezzo	1976	6.5	0.125	30
3	169	Imperial Valley	Delta	1979	6.53	0.0625	
4	174	Imperial Valley	El Centro Array #11	1979	6.53	0.25	40
5	721	Superstition Hills	El Centro Imp. Co. Cent	1987	6.54	0.125	40
6	752	Loma Prieta	Capitola	1989	6.93	0.25	48
7	767	Loma Prieta	Gilroy Array #3	1989	6.93	0.125	33
8	829	Cape Mendocino	Rio Dell Overpass - FF	1992	7.01	0.07	23
9	848	Landers	Coolwater	1992		0.125	30
10	900	Landers	Yermo Fire Station	1992	7.28	0.07	23
11	953	Northridge	Beverly Hills - 14145 Mulhol	1994	6.69	0.1625	30
12	960	Northridge	Canyon Country - W Lost Cany	1994	6.69	0.0625	30
13	1111	Kobe- Japan	Nishi-Akashi	1995	6.9	0.125	23
14	1116	Kobe- Japan	Shin-Osaka	1995	6.9	0.125	23
15	1148	Kocaeli- Turkey	Arcelik	1999	7.51	0.0875	50
16	1158	Kocaeli- Turkey	Duzce	1999	7.51	0.237	20
17	1244	Chi-Chi- Taiwan	CHY101	1999	7.62	0.0375	50
18	1485	Chi-Chi- Taiwan	TCU045	1999		0.025	50
19	1602	Duzce- Turkey	Bolu	1999	7.14	0.0625	
20	1633	Manjil, Iran	Abbar	1990		0.13	20
21	1787	Hector Mine	Hector	1999	7.13	0.025	53



## APPENDIX C

### N-S SEISMIC FRAME, GRAVITY BEAMS & COLUMN DESIGN

#### C.1 Perimeter Frame Design Summary

Table C.1.1: Interior Left Girders of N-S Frame Final Design and Checks.

Floor	Section	$M_{u,max}$ (kip-in)	$V_{u,max}$ (kip)	Flexure	Shear	Flexure $\leq 1$ Shear $\leq 1$
20	W27X146	1,495	10.4	0.072	0.023	OK
19	W27X94	1,791	14.5	0.143	0.039	OK
18	W27X94	2,350	19.5	0.188	0.052	OK
17	W27X94	2,372	20.5	0.190	0.055	OK
16	W33X221	4,176	35.0	0.108	0.048	OK
15	W33X221	4,303	34.8	0.112	0.048	OK
14	W33X221	4,568	36.7	0.118	0.050	OK
13	W33X221	4,873	40.7	0.126	0.056	OK
12	W33X221	5,393	45.7	0.140	0.063	OK
11	W27X194	4,756	41.5	0.167	0.073	OK
10	W27X194	5,259	46.2	0.185	0.081	OK
9	W27X194	5,809	50.7	0.205	0.089	OK
8	W27X194	6,097	53.1	0.215	0.093	OK
7	W27X194	6,181	54.0	0.218	0.094	OK
6	W27X194	5,849	51.0	0.206	0.089	OK
5	W33X291	8,398	71.1	0.161	0.079	OK
4	W33X291	8,059	69.0	0.154	0.076	OK
3	W33X291	8,029	69.8	0.154	0.077	OK
2	W33X291	7,715	67.8	0.148	0.075	OK
1	W33X291	6,358	55.7	0.122	0.062	OK

Table C.1.2: Interior Right Girders of N-S Frame Final Design and Checks.

Floor	Section	$M_{u,max}$ (kip-in)	$V_{u,max}$ (kip)	Flexure	Shear	Flexure $\leq 1$ Shear $\leq 1$
20	W27X146	788	42	0.038	0.090	OK
19	W27X94	1,592	51	0.127	0.138	OK
18	W27X94	2,649	75	0.212	0.202	OK
17	W27X94	3,064	80	0.245	0.214	OK
16	W33X221	3,650	85	0.095	0.116	OK
15	W33X221	3,833	86	0.099	0.118	OK
14	W33X221	4,591	102	0.119	0.140	OK
13	W33X221	4,768	100	0.124	0.137	OK
12	W33X221	5,295	102	0.137	0.140	OK
11	W27X194	5,740	102	0.202	0.179	OK
10	W27X194	6,464	107	0.228	0.188	OK
9	W27X194	6,533	106	0.230	0.185	OK
8	W27X194	7,568	115	0.267	0.201	OK
7	W27X194	7,908	113	0.278	0.197	OK
6	W27X194	8,554	115	0.301	0.201	OK
5	W33X291	9,070	117	0.174	0.129	OK
4	W33X291	9,955	124	0.191	0.137	OK
3	W33X291	10,272	128	0.197	0.142	OK
2	W33X291	10,446	130	0.200	0.144	OK
1	W33X291	8,508	111	0.163	0.123	OK

Table C.1.3: Exterior Left Girders of N-S Frame Final Design and Checks.

Floor	Section	$M_{u,max}$ (kip-in)	$V_{u,max}$ (kip)	Flexure	Shear	Flexure $\leq 1$ Shear $\leq 1$
20	W27X146	1,541	14	0.074	0.031	OK
19	W27X94	1,842	17	0.147	0.045	OK
18	W27X94	2,273	21	0.182	0.056	OK
17	W27X94	2,575	24	0.206	0.065	OK
16	W33X221	5,132	50	0.133	0.068	OK
15	W33X221	4,874	47	0.126	0.065	OK
14	W33X221	4,990	48	0.129	0.066	OK
13	W33X221	5,628	55	0.146	0.075	OK
12	W33X221	6,185	60	0.160	0.082	OK
11	W27X194	5,246	51	0.185	0.088	OK
10	W27X194	5,692	55	0.200	0.096	OK
9	W27X194	5,904	57	0.208	0.099	OK
8	W27X194	6,039	58	0.213	0.102	OK
7	W27X194	6,049	58	0.213	0.102	OK
6	W27X194	5,696	55	0.201	0.096	OK
5	W33X291	8,007	78	0.153	0.086	OK
4	W33X291	7,464	73	0.143	0.081	OK
3	W33X291	7,478	73	0.143	0.081	OK
2	W33X291	6,960	68	0.133	0.075	OK
1	W33X291	5,410	53	0.104	0.058	OK

Table C.1.4: Exterior Right Girders of N-S Frame Final Design and Checks.

Floor	Section	$M_{u,max}$ (kip-in)	$V_{u,max}$ (kip)	Flexure	Shear	Flexure $\leq 1$ Shear $\leq 1$
20	W27X146	18,500	235	0.886	0.509	OK
19	W27X94	7,082	129	0.566	0.344	OK
18	W27X94	6,464	107	0.517	0.287	OK
17	W27X94	-1,872	29	-0.150	0.077	OK
16	W33X221	-1,337	21	-0.035	0.028	OK
15	W33X221	-1,328	21	-0.034	0.028	OK
14	W33X221	3,196	56	0.083	0.077	OK
13	W33X221	23,775	279	0.616	0.383	OK
12	W33X221	10,734	131	0.278	0.180	OK
11	W27X194	24,626	280	0.867	0.489	OK
10	W27X194	3,189	74	0.112	0.129	OK
9	W27X194	26,362	294	0.928	0.514	OK
8	W27X194	11,347	150	0.400	0.262	OK
7	W27X194	9,070	117	0.319	0.204	OK
6	W27X194	-832	20	-0.029	0.034	OK
5	W33X291	-594	14	-0.011	0.016	OK
4	W33X291	-375	12	-0.007	0.013	OK
3	W33X291	5,340	67	0.102	0.074	OK
2	W33X291	31,221	344	0.598	0.381	OK
1	W33X291	14,236	160	0.273	0.177	OK

Table C.1.5: Girders of N-S Frame Seismic Compactness Checks.

Floor	Section	$\frac{1}{2} \frac{b_f}{t_f}$	Flange Thickness Ratio Flexure $\leq 7.22$	$\frac{h}{t_w}$	Web Thickness Ratio $\leq 59$	$\frac{h}{t_w}$	Web Thickness Ratio Shear $\leq 53.95$
20	W27X146	7.16	OK	19.70	OK	19.70	OK
19	W27X94	6.70	OK	24.75	OK	24.75	OK
18	W27X94	6.70	OK	24.75	OK	24.75	OK
17	W27X94	6.70	OK	24.75	OK	24.75	OK
16	W33X221	6.20	OK	19.25	OK	19.25	OK
15	W33X221	6.20	OK	19.25	OK	19.25	OK
14	W33X221	6.20	OK	19.25	OK	19.25	OK
13	W33X221	6.20	OK	19.25	OK	19.25	OK
12	W33X221	6.20	OK	19.25	OK	19.25	OK
11	W27X194	5.24	OK	15.90	OK	15.90	OK
10	W27X194	5.24	OK	15.90	OK	15.90	OK
9	W27X194	5.24	OK	15.90	OK	15.90	OK
8	W27X194	5.24	OK	15.90	OK	15.90	OK
7	W27X194	5.24	OK	15.90	OK	15.90	OK
6	W27X194	5.24	OK	15.90	OK	15.90	OK
5	W33X291	4.60	OK	15.50	OK	15.50	OK
4	W33X291	4.60	OK	15.50	OK	15.50	OK
3	W33X291	4.60	OK	15.50	OK	15.50	OK
2	W33X291	4.60	OK	15.50	OK	15.50	OK
1	W33X291	4.60	OK	15.50	OK	15.50	OK

Table C.1.6: N-S Frame Drift Limit Check.

Floor	Floor Drift	Drift Limit	Drift Check $\leq 0.02$
20	0.0108	0.02	OK
19	0.0140	0.02	OK
18	0.0155	0.02	OK
17	0.0140	0.02	OK
16	0.0129	0.02	OK
15	0.0129	0.02	OK
14	0.0132	0.02	OK
13	0.0136	0.02	OK
12	0.0149	0.02	OK
11	0.0162	0.02	OK
10	0.0168	0.02	OK
9	0.0170	0.02	OK
8	0.0170	0.02	OK
7	0.0164	0.02	OK
6	0.0145	0.02	OK
5	0.0121	0.02	OK
4	0.0114	0.02	OK
3	0.0107	0.02	OK
2	0.0094	0.02	OK
1	0.0055	0.02	OK

Table C.1.7: RBS Design Coefficients and Factored Moments and Shear.

Floor	Section	a (in)	b (in)	c (in)	$M_{u,RBS}$ (kip-in)	$V_{u,RBS}$ (kip)	$M_{u,f}$ (kip-in)
20	W27X146	8.75	20.55	3.50	1,806	218	22,097
19	W27X94	6.25	20.18	2.50	2,101	136	13,635
18	W27X94	6.25	20.18	2.50	2,539	136	13,643
17	W27X94	6.25	20.18	2.50	2,859	174	14,259
16	W33X221	9.88	25.43	3.95	5,243	649	47,991
15	W33X221	9.88	25.43	3.95	4,947	525	45,208
14	W33X221	9.88	25.43	3.95	5,064	675	48,584
13	W33X221	9.88	25.43	3.95	5,685	466	43,864
12	W33X221	9.88	25.43	3.95	6,169	677	48,631
11	W27X194	8.75	21.08	3.50	5,408	403	31,814
10	W27X194	8.75	21.08	3.50	5,825	373	31,236
9	W27X194	8.75	21.08	3.50	6,005	305	29,916
8	W27X194	8.75	21.08	3.50	6,143	302	29,855
7	W27X194	8.75	21.08	3.50	6,155	303	29,886
6	W27X194	8.75	21.08	3.50	5,809	339	30,578
5	W33X291	9.94	26.10	3.98	7,731	878	64,776
4	W33X291	9.94	26.10	3.98	7,212	711	60,944
3	W33X291	9.94	26.10	3.98	7,392	892	65,097
2	W33X291	9.94	26.10	3.98	6,927	619	58,826
1	W33X291	9.94	26.10	3.98	5,474	896	65,201

Table C.1.8: Demand to Capacity Ratios for the Column Face Moment, Shear and Moment at Center of RBS.

Floor	$\frac{M_{u,f}}{M_p}$	$\frac{M_{u,f}}{M_p} \leq 1$	$\frac{V_{u,RBS}}{V_{n,RBS}}$	$\frac{V_{u,RBS}}{V_{n,RBS}} \leq 1$	$\frac{M_{u,RBS}}{M_{p,RBS}}$	$\frac{M_{u,RBS}}{M_{p,RBS}} \leq 1$
20	0.87	OK	0.47	OK	0.29	OK
19	0.89	OK	0.36	OK	0.33	OK
18	0.89	OK	0.36	OK	0.33	OK
17	0.93	OK	0.47	OK	0.32	OK
16	1.02	OK*	0.89	OK	0.81	OK
15	0.96	OK	0.72	OK	0.36	OK
14	1.03	OK*	0.93	OK	0.89	OK
13	0.93	OK	0.64	OK	0.22	OK
12	1.03	OK*	0.93	OK	0.90	OK
11	0.92	OK	0.71	OK	0.47	OK
10	0.90	OK	0.65	OK	0.44	OK
9	0.86	OK	0.53	OK	0.32	OK
8	0.86	OK	0.53	OK	0.32	OK
7	0.86	OK	0.53	OK	0.32	OK
6	0.88	OK	0.59	OK	0.31	OK
5	1.02	OK*	0.97	OK	0.90	OK
4	0.96	OK	0.79	OK	0.40	OK
3	1.02	OK*	0.99	OK	0.94	OK
2	0.92	OK	0.69	OK	0.20	OK
1	1.02	OK*	0.99	OK	0.94	OK

\* Note: The demand to capacity ratio is slightly exceeded however it is acceptable by common engineering practice.



Table C.1.9: Exterior Column Factored Axial Force, Moment and Governing Axial & Moment Interaction Equation from the AISC Steel Construction Manual.

Floor	Section	$P_u$	$M_u$	EQ H1-1a/b	H1-1a/b $\leq$ 1
20	W36X160	77	690	0.044	OK
19	W36X160	155	1,368	0.089	OK
18	W36X160	236	2,475	0.136	OK
17	W36X160	316	3,003	0.182	OK
16	W36X160	408	2,555	0.230	OK
15	W36X210	499	2,746	0.211	OK
14	W36X210	590	2,965	0.250	OK
13	W36X210	684	2,804	0.290	OK
12	W36X210	782	2,560	0.331	OK
11	W36X210	878	3,249	0.378	OK
10	W36X210	978	3,654	0.421	OK
9	W36X256	1,084	4,222	0.379	OK
8	W36X256	1,191	4,606	0.416	OK
7	W36X256	1,299	5,277	0.454	OK
6	W36X256	1,405	6,849	0.491	OK
5	W36X361	1,529	6,029	0.345	OK
4	W36X361	1,645	5,866	0.371	OK
3	W36X361	1,763	6,118	0.397	OK
2	W36X361	1,880	7,451	0.424	OK
1	W36X361	1,987	13,599	0.462	OK

Table C.1.10: Exterior Column Final Factored Axial Force with Overstrength Consideration.

Floor	Section	$P_u$	$\frac{P_u}{P_c}$	$\frac{P_u}{P_c} \leq 1$
20	W36X160	92	0.053	OK
19	W36X160	192	0.110	OK
18	W36X160	303	0.174	OK
17	W36X160	413	0.237	OK
16	W36X160	561	0.316	OK
15	W36X210	704	0.298	OK
14	W36X210	850	0.360	OK
13	W36X210	1,002	0.424	OK
12	W36X210	1,168	0.495	OK
11	W36X210	1,324	0.570	OK
10	W36X210	1,493	0.643	OK
9	W36X256	1,675	0.585	OK
8	W36X256	1,864	0.651	OK
7	W36X256	2,055	0.718	OK
6	W36X256	2,239	0.782	OK
5	W36X361	2,476	0.558	OK
4	W36X361	2,703	0.609	OK
3	W36X361	2,929	0.660	OK
2	W36X361	3,151	0.710	OK
1	W36X361	3,344	0.778	OK

Table C.1.11: Exterior Column Seismic Compactness Checks

Floor	Section	$\frac{1}{2} \frac{b_f}{t_f}$	Flange Thickness Ratio Flexure $\leq 7.22$	$\frac{h}{t_w}$	$\frac{h}{t_w}$ Limit	Web Thickness Ratio $\leq$ Limit
20	W36X160	5.88	OK	49.9	57.0	OK
19	W36X160	5.88	OK	49.9	55.0	OK
18	W36X160	5.88	OK	49.9	52.9	OK
17	W36X160	5.88	OK	49.9	51.6	OK
16	W36X160	5.88	OK	49.9	50.8	OK
15	W36X210	4.49	OK	39.1	51.0	OK
14	W36X210	4.49	OK	39.1	50.4	OK
13	W36X210	4.49	OK	39.1	49.8	OK
12	W36X210	4.49	OK	39.1	49.1	OK
11	W36X210	4.49	OK	39.1	48.5	OK
10	W36X210	4.49	OK	39.1	47.8	OK
9	W36X256	3.53	OK	33.8	48.4	OK
8	W36X256	3.53	OK	33.8	47.8	OK
7	W36X256	3.53	OK	33.8	47.2	OK
6	W36X256	3.53	OK	33.8	46.7	OK
5	W36X361	4.15	OK	28.6	48.4	OK
4	W36X361	4.15	OK	28.6	47.9	OK
3	W36X361	4.15	OK	28.6	47.5	OK
2	W36X361	4.15	OK	28.6	47.0	OK
1	W36X361	4.15	OK	28.6	46.6	OK

Table C.1.12: Strong Column Weak Beam Check for Exterior Columns.

Floor	Section	$\sum M_{pc}^*$	$\sum M_{pb}^*$	SCWB Ratio	Check > 1
19	W36X160	69,252	16,170	4.28	OK
18	W36X160	65,683	16,019	4.10	OK
17	W36X160	62,149	16,033	3.88	OK
16	W36X160	60,702	50,413	1.20	OK
15	W36X210	82,164	50,672	1.62	OK
14	W36X210	77,168	50,790	1.52	OK
13	W36X210	71,913	50,740	1.42	OK
12	W36X210	66,203	50,699	1.31	OK
11	W36X210	58,064	35,100	1.65	OK
10	W36X210	52,502	35,121	1.49	OK
9	W36X256	70,481	35,300	2.00	OK
8	W36X256	64,138	35,296	1.82	OK
7	W36X256	57,715	35,374	1.63	OK
6	W36X256	51,529	35,469	1.45	OK
5	W36X361	106,306	69,001	1.54	OK
4	W36X361	97,765	69,087	1.42	OK
3	W36X361	89,232	69,077	1.29	OK
2	W36X361	80,894	69,073	1.17	OK
1	W36X361	70,932	69,062	1.03	OK

Table C.1.13: Interior Column Factored Axial Force, Moment and Governing Axial & Moment Interaction Equation from the AISC Steel Construction Manual.

Floor	Section	$P_u$	$M_u$	EQ H1-1a/b	H1-1a/b $\leq$ 1
20	W36X150	86	733	0.052	OK
19	W36X150	171	2,080	0.105	OK
18	W36X150	256	3,349	0.157	OK
17	W36X282	343	6,166	0.100	OK
16	W36X282	442	5,090	0.128	OK
15	W36X282	537	4,733	0.155	OK
14	W36X282	632	5,114	0.183	OK
13	W36X330	729	5,356	0.180	OK
12	W36X330	824	4,715	0.203	OK
11	W36X330	913	5,854	0.227	OK
10	W36X330	1,001	6,676	0.249	OK
9	W36X330	1,084	6,898	0.269	OK
8	W36X330	1,167	7,522	0.290	OK
7	W36X330	1,249	8,355	0.310	OK
6	W36X330	1,330	10,652	0.331	OK
5	W36X395	1,411	9,148	0.290	OK
4	W36X395	1,487	8,934	0.306	OK
3	W36X441	1,570	9,780	0.288	OK
2	W36X441	1,652	10,931	0.303	OK
1	W36X441	1,731	17,334	0.327	OK

Table C.1.14: Interior Column Final Factored Axial Force with Overstrength Consideration.

Floor	Section	$P_u$	$\frac{P_u}{P_c}$	$\frac{P_u}{P_c} \leq 1$
20	W36X150	90	0.055	OK
19	W36X150	175	0.107	OK
18	W36X150	258	0.158	OK
17	W36X282	346	0.101	OK
16	W36X282	469	0.136	OK
15	W36X282	583	0.168	OK
14	W36X282	693	0.200	OK
13	W36X330	811	0.200	OK
12	W36X330	927	0.229	OK
11	W36X330	1,025	0.255	OK
10	W36X330	1,121	0.279	OK
9	W36X330	1,207	0.300	OK
8	W36X330	1,290	0.321	OK
7	W36X330	1,371	0.341	OK
6	W36X330	1,450	0.360	OK
5	W36X395	1,533	0.315	OK
4	W36X395	1,613	0.332	OK
3	W36X441	1,696	0.311	OK
2	W36X441	1,772	0.325	OK
1	W36X441	1,839	0.348	OK

Table C.1.15: Interior Column Seismic Compactness Checks

Floor	Section	$\frac{1}{2} \frac{b_f}{t_f}$	Flange Thickness Ratio Flexure $\leq 7.22$	$\frac{h}{t_w}$	$\frac{h}{t_w}$ Limit	Web Thickness Ratio $\leq$ Limit
20	W36X150	6.38	51.9	56.6	46.6	OK
19	W36X150	6.38	51.9	54.3	47.0	OK
18	W36X150	6.38	51.9	52.0	47.5	OK
17	W36X282	5.29	36.2	54.0	47.9	OK
16	W36X282	5.29	36.2	52.5	48.4	OK
15	W36X282	5.29	36.2	51.7	46.7	OK
14	W36X282	5.29	36.2	51.2	47.2	OK
13	W36X330	4.49	31.4	51.2	47.8	OK
12	W36X330	4.49	31.4	50.8	48.4	OK
11	W36X330	4.49	31.4	50.5	47.8	OK
10	W36X330	4.49	31.4	50.1	48.5	OK
9	W36X330	4.49	31.4	49.7	49.1	OK
8	W36X330	4.49	31.4	49.4	49.8	OK
7	W36X330	4.49	31.4	49.0	50.4	OK
6	W36X330	4.49	31.4	48.7	51.0	OK
5	W36X395	3.82	26.3	49.3	50.8	OK
4	W36X395	3.82	26.3	49.1	51.6	OK
3	W36X441	3.48	23.6	49.4	52.9	OK
2	W36X441	3.48	23.6	49.1	55.0	OK
1	W36X441	3.48	23.6	48.8	57.0	OK

Table C.1.16: Strong Column Weak Beam Check for Interior Columns.

Floor	Section	$\sum M_{pc}^*$	$\sum M_{pb}^*$	SCWB Ratio	Check > 1
19	W36X150	64,646	32,231	2.01	OK
18	W36X150	62,017	32,097	1.93	OK
17	W36X282	131,794	33,485	3.94	OK
16	W36X282	134,829	110,665	1.22	OK
15	W36X282	130,672	105,709	1.24	OK
14	W36X282	126,606	111,976	1.13	OK
13	W36X330	150,032	103,458	1.45	OK
12	W36X330	145,721	112,301	1.30	OK
11	W36X330	135,617	74,665	1.82	OK
10	W36X330	132,237	73,542	1.80	OK
9	W36X330	129,186	71,007	1.82	OK
8	W36X330	126,248	70,883	1.78	OK
7	W36X330	123,380	71,023	1.74	OK
6	W36X330	120,574	72,486	1.66	OK
5	W36X395	161,940	150,436	1.08	OK
4	W36X395	158,882	143,797	1.10	OK
3	W36X441	181,710	151,555	1.20	OK
2	W36X441	178,840	140,197	1.28	OK
1	W36X441	169,777	151,955	1.12	OK



Table C.1.17: Panel Zone and Doubler Plating of Exterior Columns.

Floor	Beam Section	Column Section	$R_u$ (kip)	$R_n$ (kip)	Doubler Plate?	Side Plate Thickness (in)	Total Plate Thickness (in)
20	W27X146	W36X160	689	743	No	0	0
19	W27X94	W36X160	431	744	No	0	0
18	W27X94	W36X160	432	744	No	0	0
17	W27X94	W36X160	451	744	No	0	0
16	W33X221	W36X160	1,151	735	Yes	4/16	0.500
15	W33X221	W36X210	1,085	974	Yes	1/16	0.125
14	W33X221	W36X210	1,166	974	Yes	2/16	0.250
13	W33X221	W36X210	1,052	974	Yes	1/16	0.125
12	W33X221	W36X210	1,167	974	Yes	2/16	0.250
11	W27X194	W36X210	975	986	No	0	0
10	W27X194	W36X210	957	986	No	0	0
9	W27X194	W36X256	917	1,194	No	0	0
8	W27X194	W36X256	915	1,194	No	0	0
7	W27X194	W36X256	916	1,194	No	0	0
6	W27X194	W36X256	937	1,194	No	0	0
5	W33X291	W36X361	1,522	1,451	Yes	1/16	0.125
4	W33X291	W36X361	1,432	1,451	No	0	0
3	W33X291	W36X361	1,529	1,451	Yes	1/16	0.125
2	W33X291	W36X361	1,382	1,451	No	0	0
1	W33X291	W36X361	1,590	1,451	Yes	1/16	0.125

Table C.1.18: Panel Zone and Doubler Plating of Interior Columns.

Floor	Beam Section	Column Section	R <sub>u</sub> (kip)	R <sub>n</sub> (kip)	Doubler Plate?	Side Plate Thickness (in)	Total Plate Thickness (in)
20	W27X146	W36X150	1,379	708	Yes	5/16	0.625
19	W27X94	W36X150	863	709	Yes	2/16	0.250
18	W27X94	W36X150	863	709	Yes	2/16	0.250
17	W27X94	W36X282	902	1,122	No	0	0
16	W33X221	W36X282	2,303	1,094	Yes	9/16	1.125
15	W33X221	W36X282	2,169	1,094	Yes	8/16	1.000
14	W33X221	W36X282	2,331	1,094	Yes	9/16	1.125
13	W33X221	W36X330	2,105	1,304	Yes	6/16	0.750
12	W33X221	W36X330	2,334	1,304	Yes	8/16	1.000
11	W27X194	W36X330	1,949	1,336	Yes	5/16	0.625
10	W27X194	W36X330	1,914	1,336	Yes	5/16	0.625
9	W27X194	W36X330	1,833	1,336	Yes	4/16	0.500
8	W27X194	W36X330	1,829	1,336	Yes	4/16	0.500
7	W27X194	W36X330	1,831	1,336	Yes	4/16	0.500
6	W27X194	W36X330	1,874	1,336	Yes	4/16	0.500
5	W33X291	W36X395	3,044	1,616	Yes	10/16	1.250
4	W33X291	W36X395	2,864	1,616	Yes	9/16	1.125
3	W33X291	W36X441	3,059	1,849	Yes	9/16	1.125
2	W33X291	W36X441	2,764	1,849	Yes	7/16	0.875
1	W33X291	W36X441	3,181	1,849	Yes	10/16	1.250

Table C.1.19: Stability Coefficient Check.

Story	$\theta$	$\theta_{\max}$	$\theta \leq 0.10 \leq \theta_{\max}$
20	0.03	0.25	OK
19	0.02	0.25	OK
18	0.02	0.25	OK
17	0.02	0.25	OK
16	0.01	0.25	OK
15	0.01	0.25	OK
14	0.01	0.25	OK
13	0.01	0.25	OK
12	0.01	0.25	OK
11	0.01	0.25	OK
10	0.01	0.25	OK
9	0.01	0.25	OK
8	0.01	0.25	OK
7	0.01	0.25	OK
6	0.01	0.25	OK
5	0.01	0.25	OK
4	0.01	0.25	OK
3	0.01	0.25	OK
2	0.01	0.25	OK
1	0.00	0.25	OK

## C.2 Gravity System Design Summary

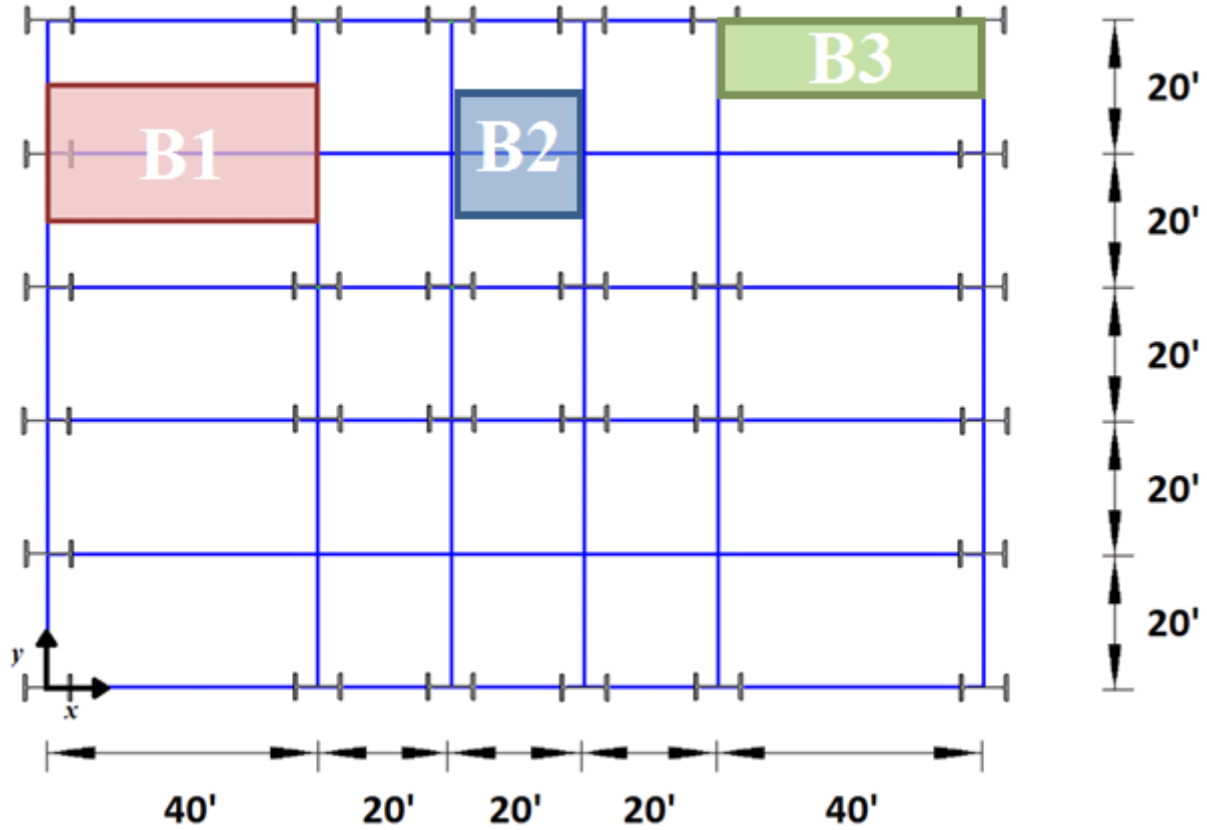


Figure C.2.1: Typical gravity beams.

Table C.2.1: Typical Composite Floor Beam Flexural, Shear and Deflection Checks.

Gravity Beam	Section	$M_u$ (kip-ft)	$\phi M_N$ (kip-ft)	$V_u$ (kip)	$\phi V_N$ (kip)	Deflection (inches)	$L/360$ (inches)	Check Limit
B1	W21X68	756	820	76	272	1.324	1.333	OK
B2	W21X68	200	820	40	272	0.110	1.333	OK
B3	W21X68	478	820	48	272	1.191	1.333	OK

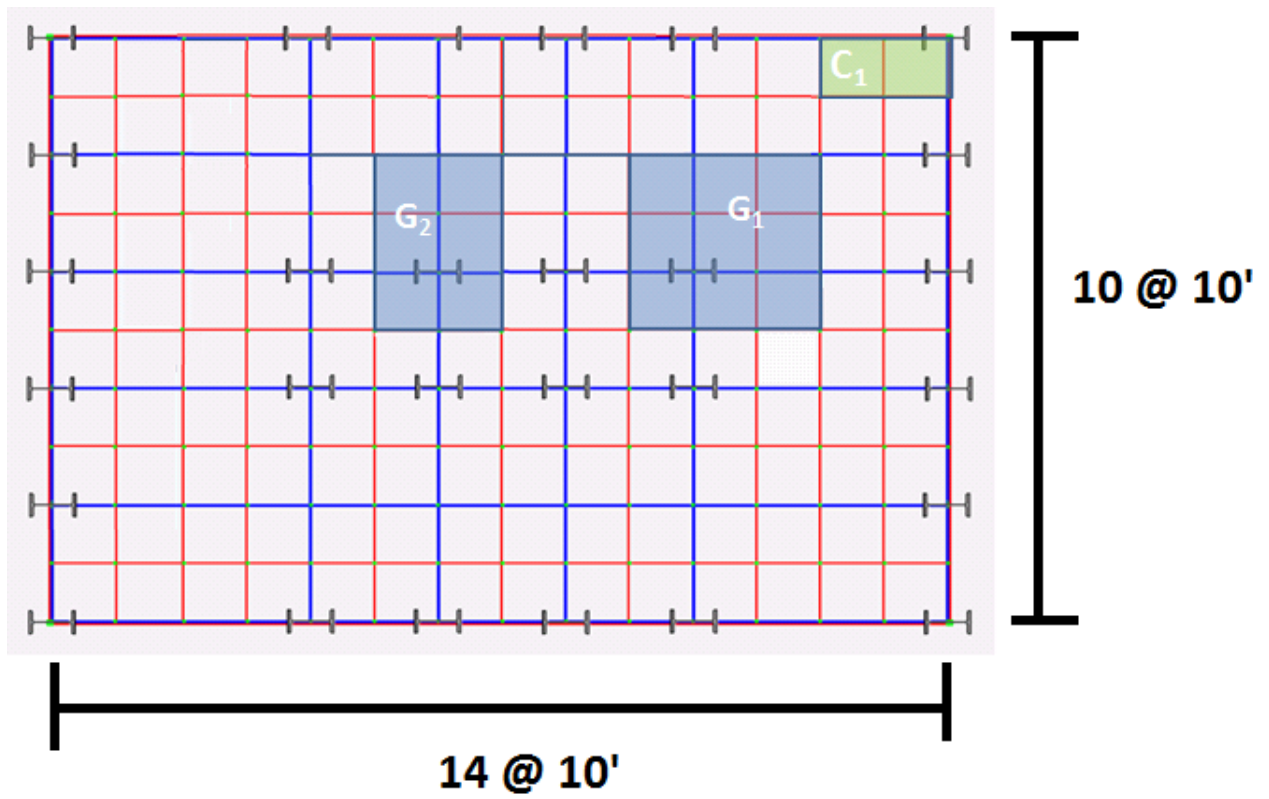


Figure C.2.2: Tributary area and location of gravity columns.

Table C.2.2: Interior Column G2 Strength Checks.

Floor	Design $P_u$ (kips)	Section	$\frac{P_u}{\phi P_n}$	$\frac{P_u}{\phi P_n} \leq 1$
20	80	W14X48	0.205	OK
19	160	W14X48	0.411	OK
18	240	W14X48	0.616	OK
17	320	W14X53	0.739	OK
16	400	W14X53	0.923	OK
15	480	W14X74	0.653	OK
14	560	W14X74	0.762	OK
13	640	W14X90	0.611	OK
12	720	W14X90	0.688	OK
11	800	W14X99	0.695	OK
10	880	W14X99	0.765	OK
9	960	W14X120	0.686	OK
8	1040	W14X120	0.744	OK
7	1120	W14X145	0.652	OK
6	1200	W14X145	0.699	OK
5	1280	W14X176	0.613	OK
4	1360	W14X176	0.651	OK
3	1440	W14X193	0.628	OK
2	1520	W14X193	0.663	OK
1	1600	W14X193	0.723	OK

Table C.2.3: Interior Column G2 Limit Checks.

Floor	Section	$\frac{1}{2} \frac{b_f}{t_f}$	Flange Thickness Ratio Flexure $\leq 13.49$	$\frac{h}{t_w}$	Web Thickness Ratio $\leq 35.9$
20	W14X48	6.75	OK	33.6	OK
19	W14X48	6.75	OK	33.6	OK
18	W14X48	6.75	OK	33.6	OK
17	W14X53	6.11	OK	30.9	OK
16	W14X53	6.11	OK	30.9	OK
15	W14X74	6.43	OK	25.4	OK
14	W14X74	6.43	OK	25.4	OK
13	W14X90	10.21	OK	25.9	OK
12	W14X90	10.21	OK	25.9	OK
11	W14X99	9.36	OK	23.5	OK
10	W14X99	9.36	OK	23.5	OK
9	W14X120	7.82	OK	19.3	OK
8	W14X120	7.82	OK	19.3	OK
7	W14X145	7.11	OK	16.8	OK
6	W14X145	7.11	OK	16.8	OK
5	W14X176	5.99	OK	13.7	OK
4	W14X176	5.99	OK	13.7	OK
3	W14X193	5.45	OK	12.8	OK
2	W14X193	5.45	OK	12.8	OK
1	W14X193	5.45	OK	12.8	OK

Table C.2.4: Corner Column C1 Strength Checks.

Floor	Design $P_u$ (kips)	Section	$\frac{P_u}{\phi P_n}$	$\frac{P_u}{\phi P_n} \leq 1$
20	51	W14X48	0.13	OK
19	105	W14X48	0.27	OK
18	159	W14X48	0.41	OK
17	212	W14X48	0.55	OK
16	266	W14X48	0.68	OK
15	320	W14X48	0.82	OK
14	374	W14X48	0.96	OK
13	428	W14X61	0.71	OK
12	482	W14X61	0.80	OK
11	536	W14X61	0.89	OK
10	590	W14X61	0.98	OK
9	644	W14X74	0.88	OK
8	698	W14X74	0.95	OK
7	753	W14X82	0.93	OK
6	808	W14X82	1.00	OK
5	862	W14X90	0.82	OK
4	912	W14X90	0.87	OK
3	967	W14X109	0.76	OK
2	1,022	W14X109	0.81	OK
1	1,078	W14X109	0.89	OK



Table C.2.5: Corner Column C1 Limit Checks.

Floor	Section	$\frac{1 b_f}{2 t_f}$	Flange Thickness Ratio Flexure $\leq 13.49$	$\frac{h}{t_w}$	Web Thickness Ratio $\leq 35.9$
20	W14X48	6.75	OK	33.6	OK
19	W14X48	6.75	OK	33.6	OK
18	W14X48	6.75	OK	33.6	OK
17	W14X48	6.75	OK	33.6	OK
16	W14X48	6.75	OK	33.6	OK
15	W14X48	6.75	OK	33.6	OK
14	W14X48	6.75	OK	33.6	OK
13	W14X61	7.75	OK	30.4	OK
12	W14X61	7.75	OK	30.4	OK
11	W14X61	7.75	OK	30.4	OK
10	W14X61	7.75	OK	30.4	OK
9	W14X74	6.43	OK	25.4	OK
8	W14X74	6.43	OK	25.4	OK
7	W14X82	5.91	OK	22.4	OK
6	W14X82	5.91	OK	22.4	OK
5	W14X90	10.21	OK	25.9	OK
4	W14X90	10.21	OK	25.9	OK
3	W14X109	8.49	OK	21.7	OK
2	W14X109	8.49	OK	21.7	OK
1	W14X109	8.49	OK	21.7	OK

## APPENDIX D

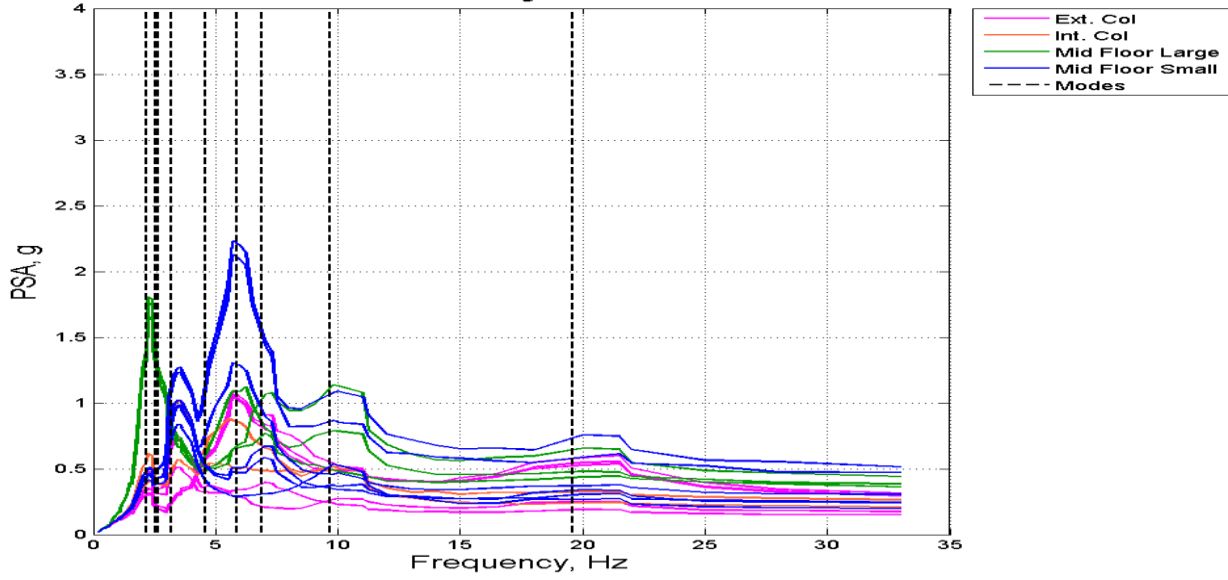
### FRS CONTINUED

#### **D.1 FRS Figure Summary**

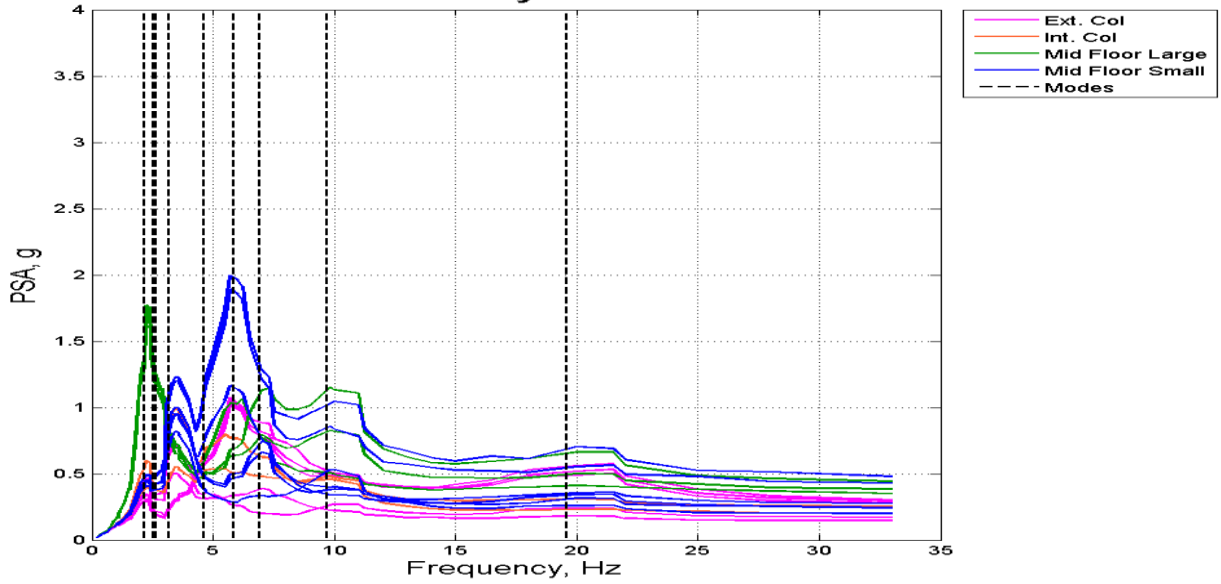
In order of appearance:

- Figure D.1.1: FRS for story 19
- Figure D.1.2: FRS for story 18
- Figure D.1.3: FRS for story 17
- Figure D.1.4: FRS for story 16
- Figure D.1.5: FRS for story 14
- Figure D.1.6: FRS for story 13
- Figure D.1.7: FRS for story 12
- Figure D.1.8: FRS for story 11
- Figure D.1.9: FRS for story 9
- Figure D.1.10: FRS for story 8
- Figure D.1.11: FRS for story 7
- Figure D.1.12: FRS for story 6
- Figure D.1.13: FRS for story 4
- Figure D.1.14: FRS for story 3
- Figure D.1.15: FRS for story 2
- Figure D.1.16: FRS for story 1

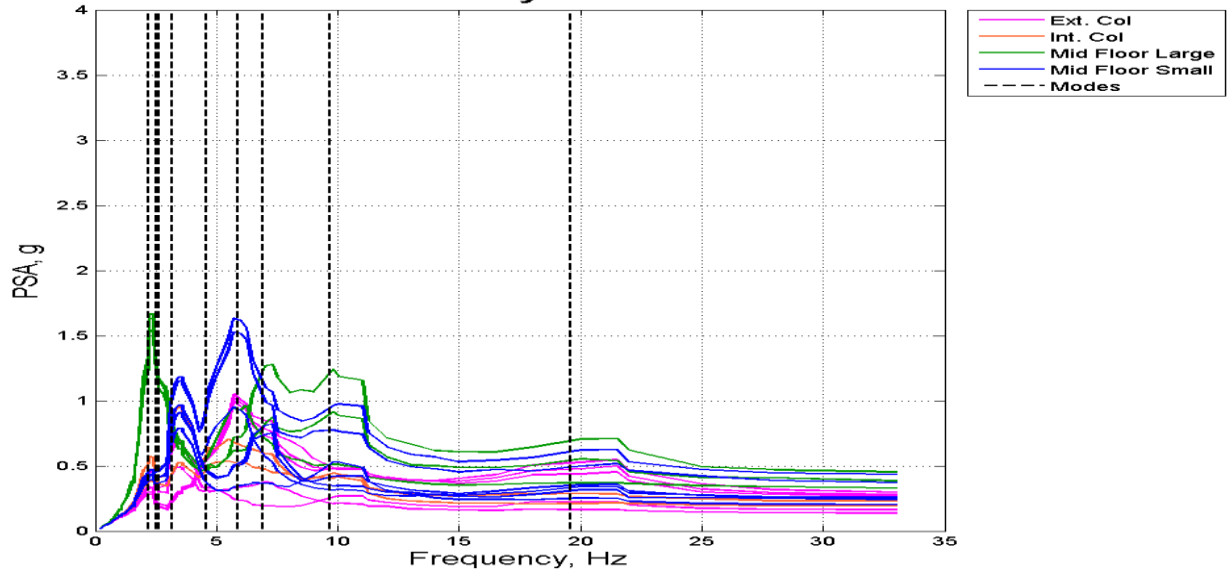
### Story 19



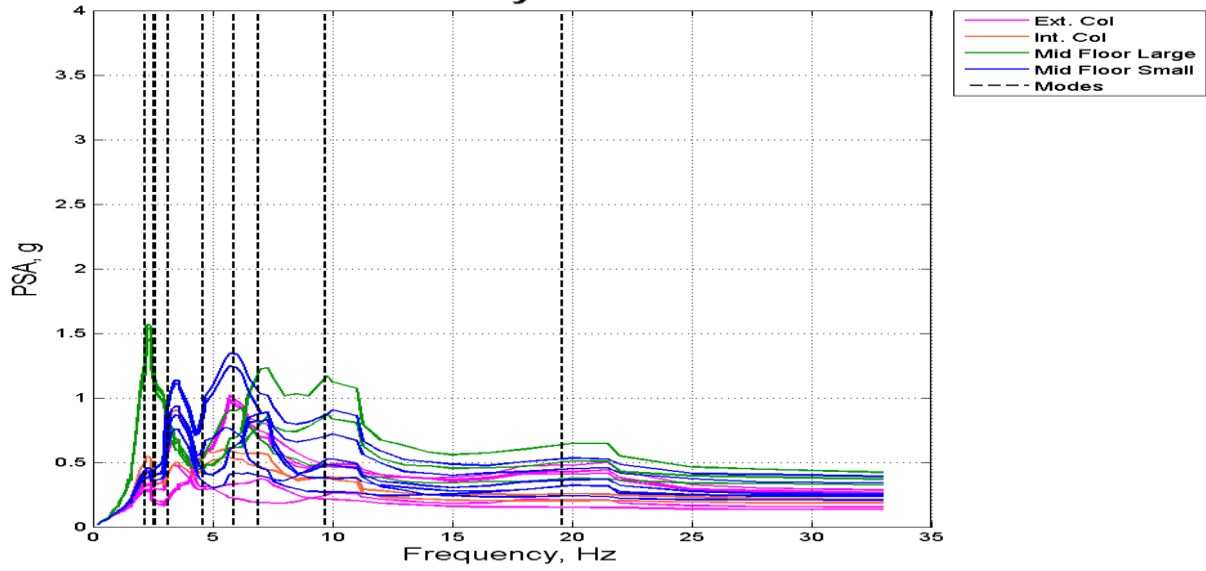
### Story 18



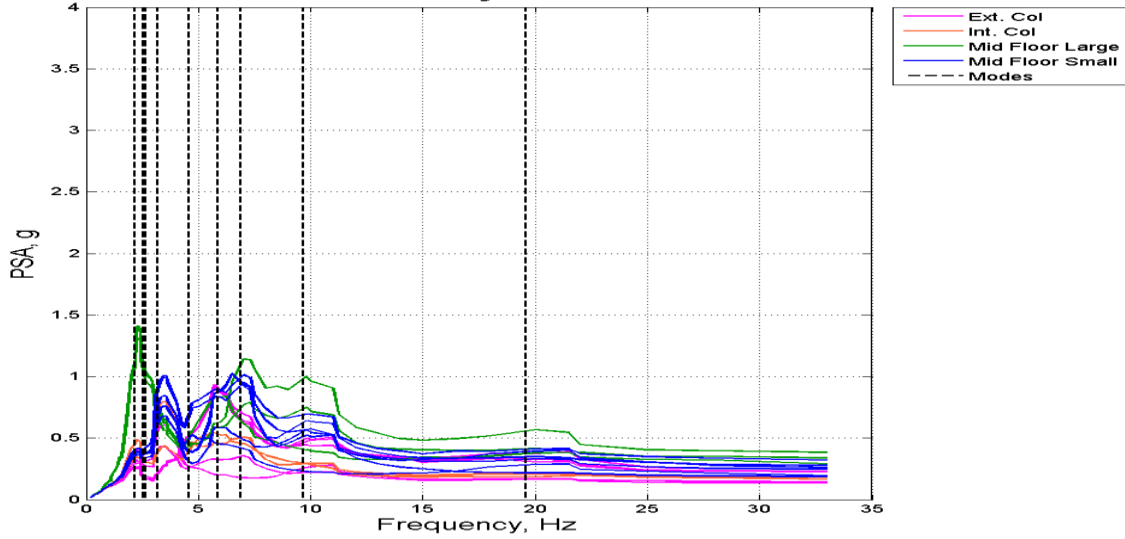
### Story 17



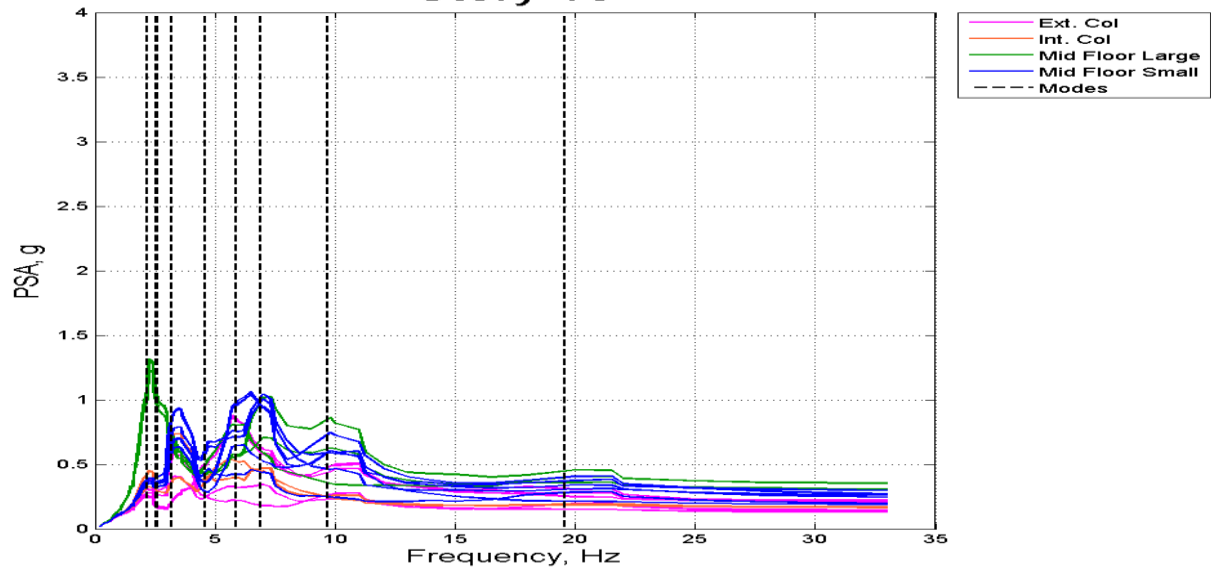
### Story 16



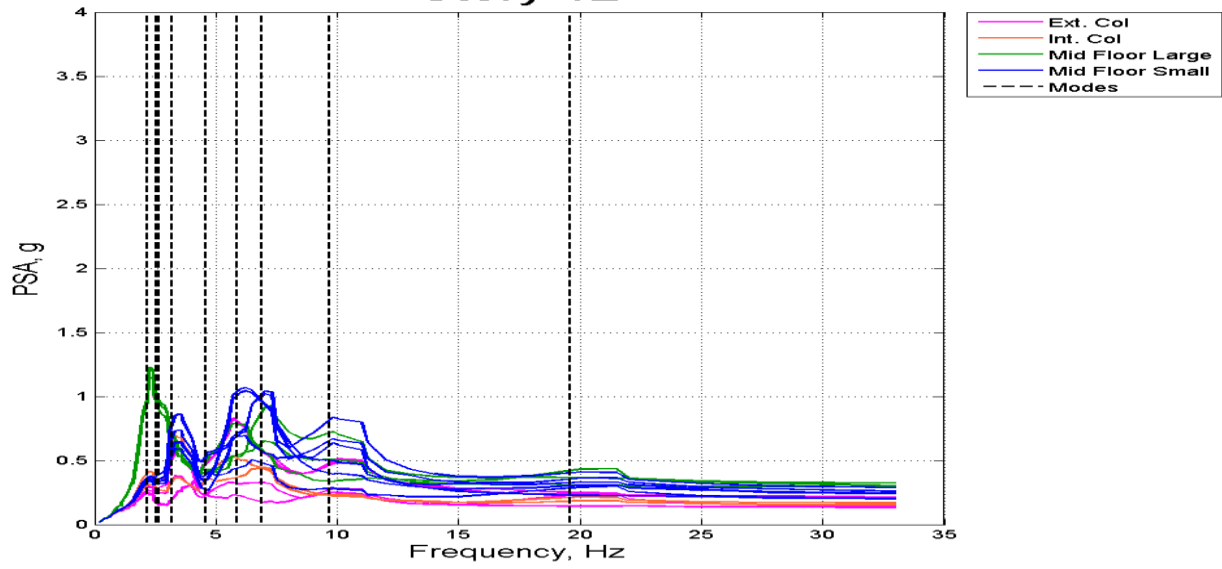
### Story 14



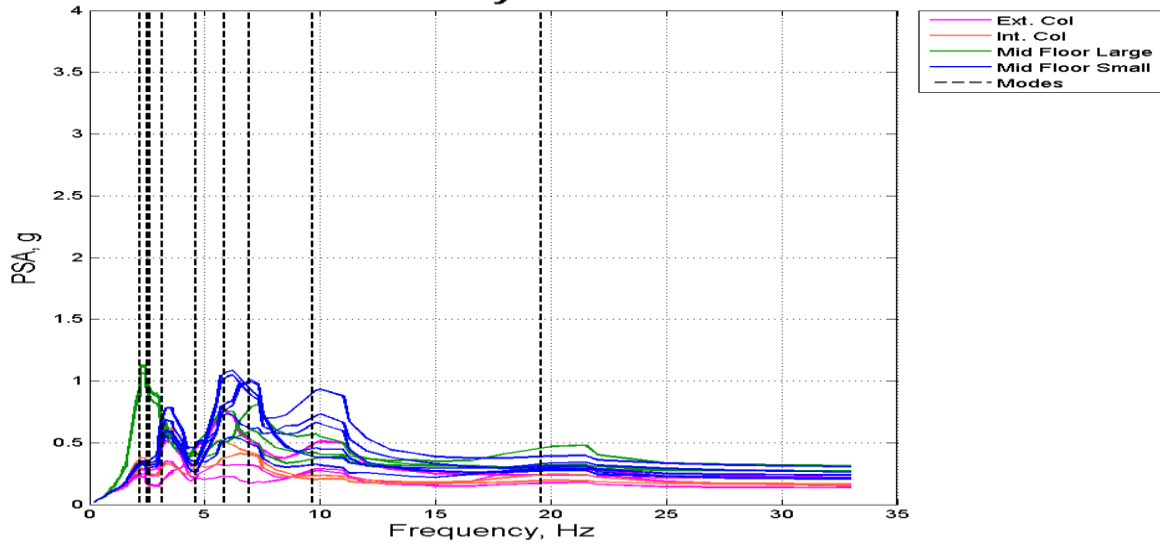
### Story 13



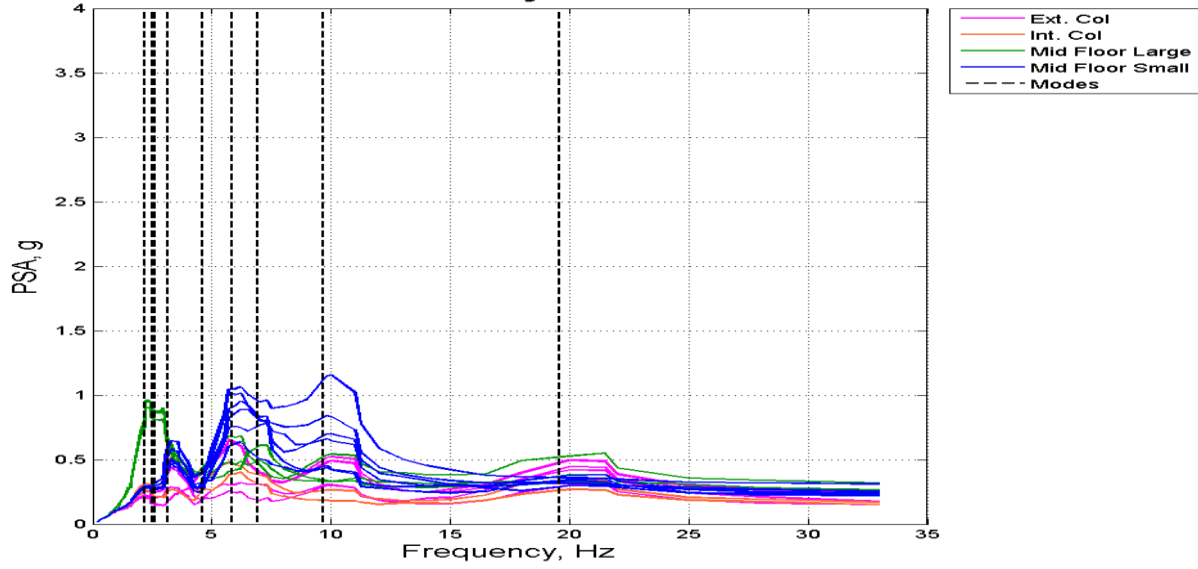
### Story 12



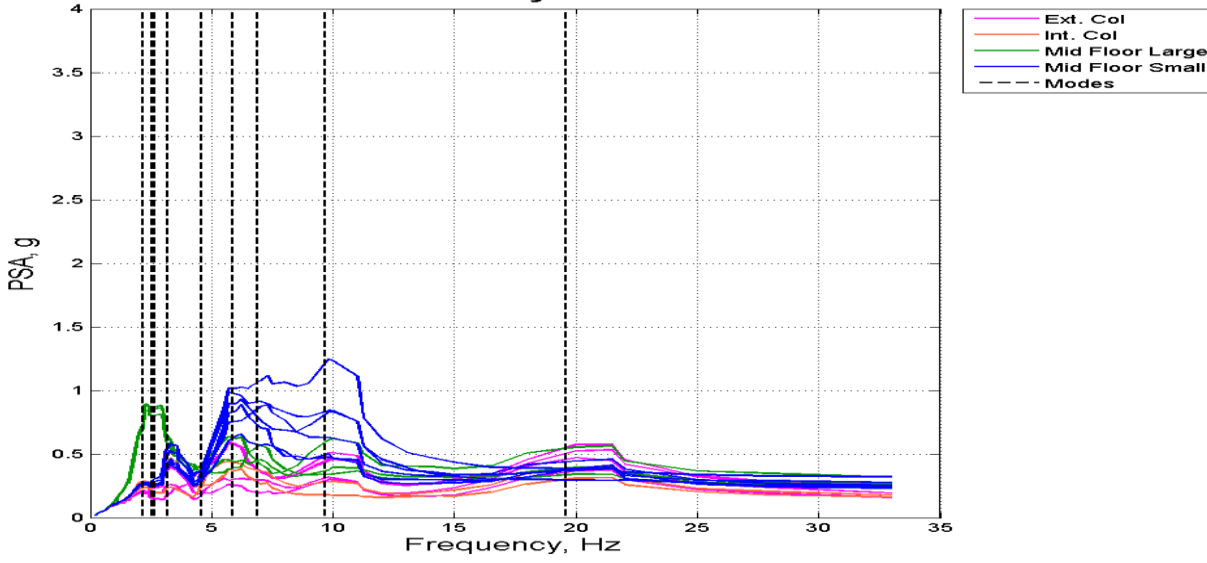
### Story 11



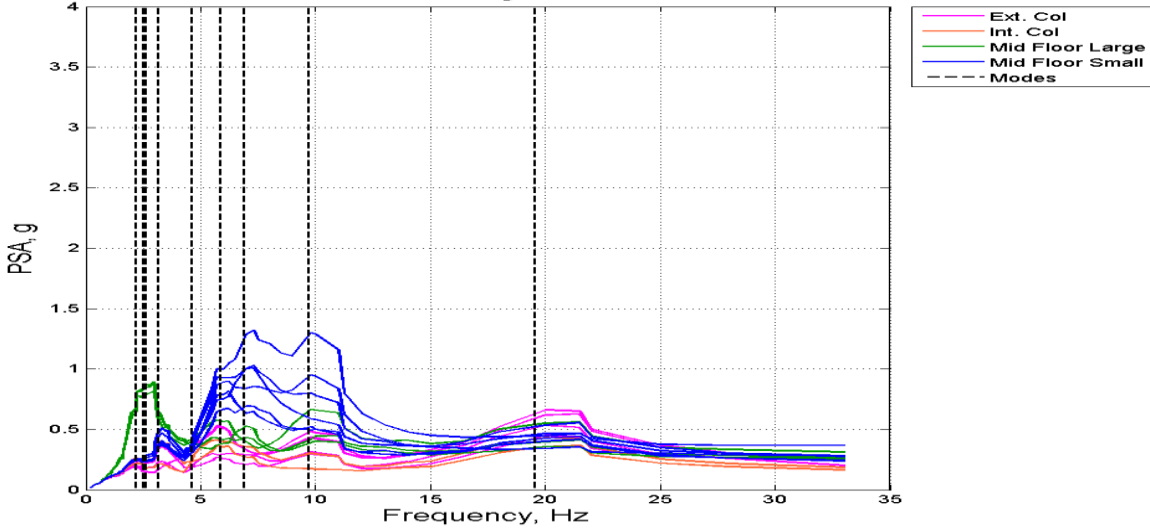
### Story 9



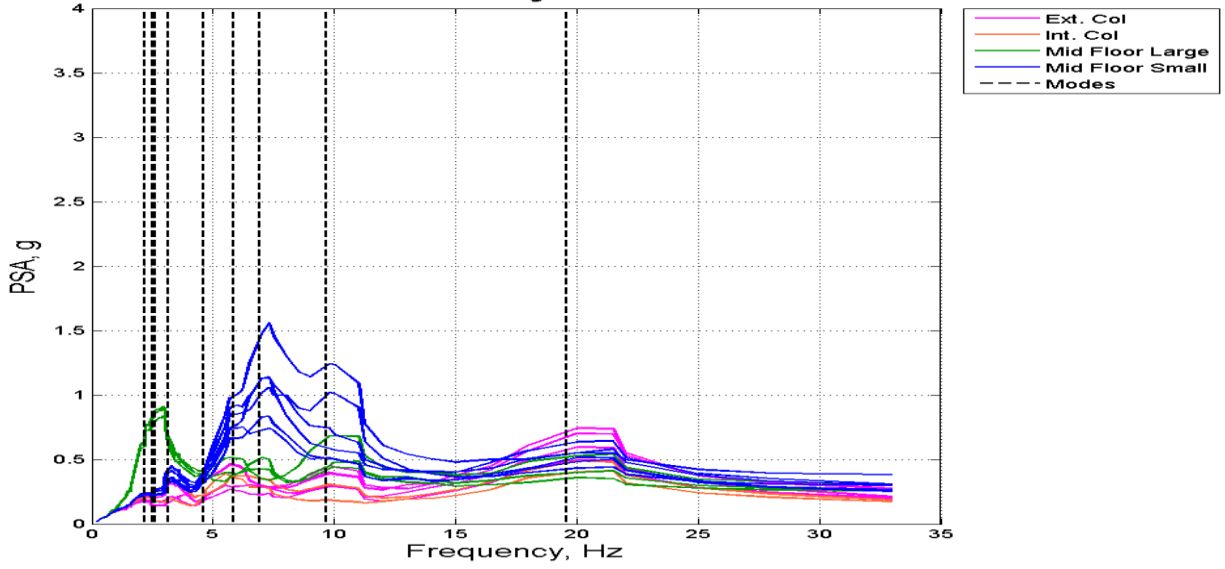
### Story 8



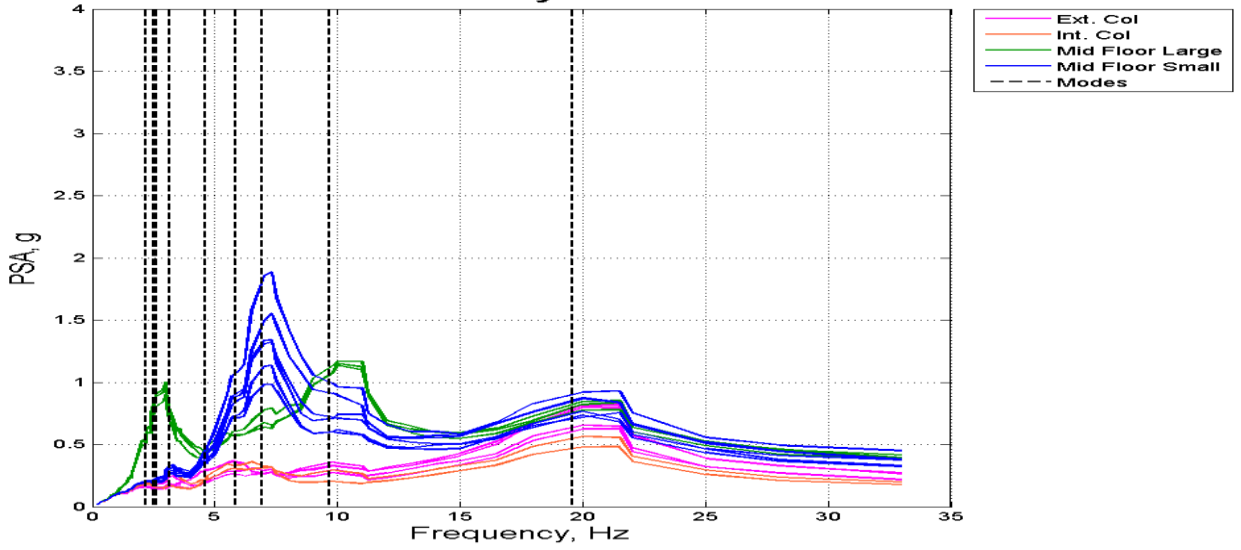
### Story 7



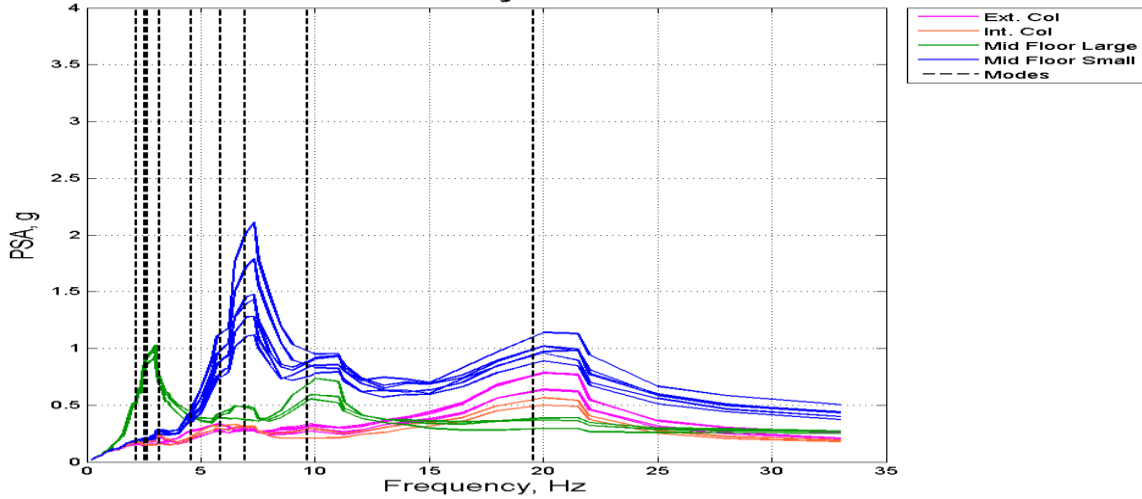
### Story 6

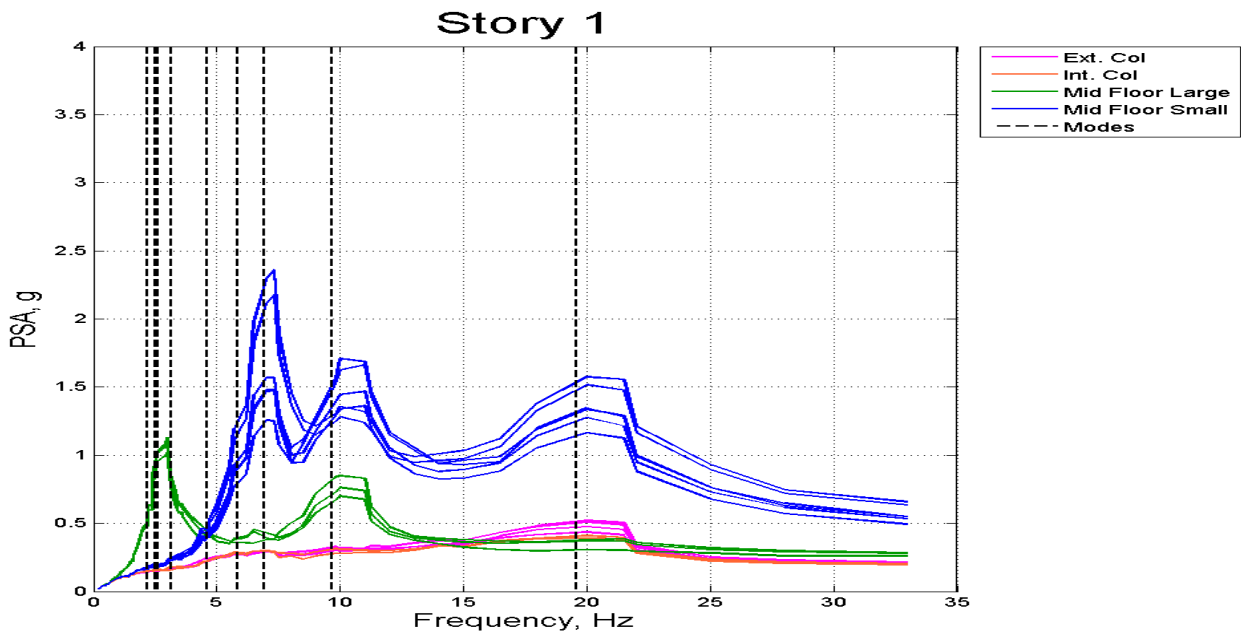
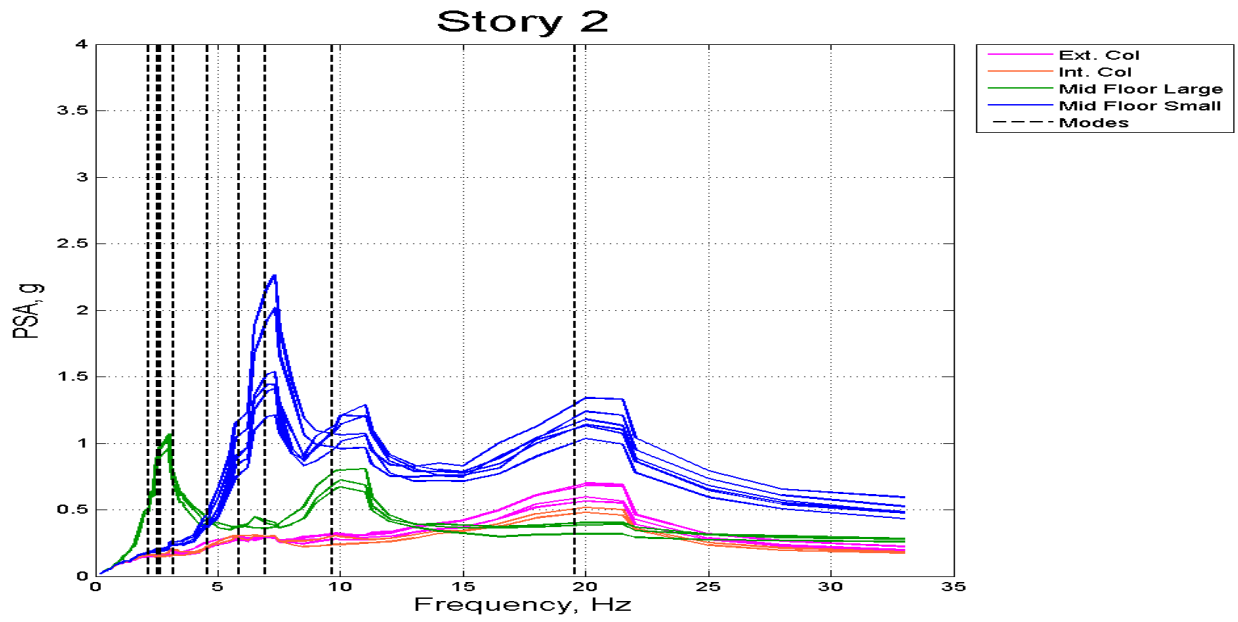


### Story 4



### Story 3







## LIST OF REFERENCES

- [1] R. Villaverde, "Seismic Design of Secondary Structures: State of the Art," *Structural Engineering*, vol. 123, no. 8, pp. 1011-1019, August 1997.
- [2] A. T. Council, "Reducing The Risks of Nonstructural Earthquake Damage-A Practical Guide," Washington, D.C., 2011.
- [3] A. S. o. C. Engineers, "Seismic Rehabilitation of Existing buildings," Reston, Virginia, 2007.
- [4] G. P. A. E. Z. A. M. I. E. M. Joseph D. Wieser, "Assessment of Floor Accelerations in Yielding Buildings," Reno, Nevada, October 5, 2012.
- [5] R. P. Dhakal, "Damage To Nonstructural Components And Contents In 2010 Darfield Earthquake," *Bulletin of the New Zealand Society for Earthquake Engineering*, vol. 43, no. 4, pp. 404-411, December 2010.
- [6] S. P. Weng Yuen Kam, "General Building Performance in Christchurch Central Business District," Christchurch, New Zealand, November 2011.
- [7] T. S. Andrew Whittaker, "An Overview of Nonstructural Components Research at Three U.S. Earthquake Engineering Research Centers," in *Proceedings of Seminar on Seismic Design Performance, and Retrofit of Nonstructural Components in Critical Facilities, Applied Technology Council, ATC-29-2*, Redwood City, California, 2003.
- [8] A. T. Council, "Reducing the Risks of Nonstructural Earthquake Damage," Washington, D.C., February 29, 2008.
- [9] A. T. Council, "Proceedings of Seminar on Seismic Design, Performance, and Retrofit of Nonstructural Components in Critical Facilities," in *ATC 29-2 Seminar on Seismic Design, Performance, and Retrofit of Nonstructural Components in Critical Facilities*, Redwood City, California, 2003.
- [10] P. Chapman, February 2 2012. [Online]. Available: <http://www.telegraph.co.uk/news/worldnews/australiaandthepacific/newzealand/9056031/Briton-died-in-crushed-bus-in-New-Zealands-Christchurch-earthquake.html>.

- [11] C. a. S. Inc., *SAP2000 Version 15.0.0*, 2011.
- [12] S. T. Eduardo Miranda, "Approximate floor acceleration demands in multistory buildings. I: Formulation," *Structural Engineering*, vol. 131, no. 2, pp. 203-211, February 2005.
- [13] E. M. Eduardo Reinoso, "Estimation of Floor Acceleration Demands in High-Rise Buildings During Earthquakes," *The Structural Design of Tall and Special Buildings*, vol. 14, no. 2, pp. 107-130, April 2005.
- [14] E. M. Shahram Taghavi, "Effect of Interaction Between Primary and Secondary Systems on Floor Response Spectra," *The 14th World Conference on Earthquake Engineering*, October 2008.
- [15] R. M. Joshua Clayton, "Proposed Method for Probabilistic Estimation of Peak Component Acceleration Demands," *Earthquake Spectra*, vol. 28, no. 1, pp. 55-72, February 2012.
- [16] R. S. K. K. Ricardo Medina, "Floor Response Spectra for Light Components Mounted on Regular Moment Resisting Frame Structures," *Engineering Structures*, vol. 28, pp. 1927-1940, May 2006.
- [17] R. V. Samit Ray Chaudhuri, "Effect of Building Nonlinearity on Seismic Response of Nonstructural Components: A Parametric Study," *Structural Engineering*, vol. 134, no. 4, pp. 661-670, April 2008.
- [18] K. C. Yousef Bozorgnia, "The Vertical-to-Horizontal Response Spectral Ratio and Tentative Procedures for Developing Simplified V/H and Vertical Design Spectra," *Earthquake Engineering*, vol. 8, no. 2, pp. 175-207, 2004.
- [19] B. S. S. Council, "NEHRP Recommended Seismic Provisions for New Buildings and Other Structures," Washington, D.C., 2009.
- [20] A. I. W. S. G. Pekcan, "Nonstructural System Response to Vertical Excitation and Implications for Seismic Design and Qualification," in *ATC-29-2 Seminar on Seismic Design, Performance, and Retrofit of Nonstructural Components in Critical Facilities*, Los Angeles, California, 2003.
- [21] G. P. A. Z. A. I. M. M. Joseph Wieser, "Floor Accelerations in Yielding Special Moment Resisting Frame Structures," *Earthquake Spectra*, vol. 29, no. 3, pp. 987-1002, August 2013.

- [22] H. K. Akshay Gupta, "Seismic Demands for Performance Evaluation of Steel Moment Resisting Frame Structures," Stanford, CA, June 1999.
- [23] C. Adam, "Dynamics of Elastic-Plastic Shear Frames with Secondary Structures: Shake Table and Numerical Studies," *Earthquake Engineering and Structural Dynamics*, vol. 30, pp. 257-277, 2001.
- [24] K.-P. R. G. M. Andrei Reinhorn, "Modeling and Seismic Evaluation of Nonstructural Components: Testing Frame for Experimental Evaluation of Suspended Ceiling Systems," Reno, Nevada, 2010.
- [25] M. P. J. R. J. S. L. F. U. B. H. G. Matthew Hoehler, "Performance of Suspended Pipes and Their Anchorages During Shake Table Testing of a Seven Story Building," *Earthquake Spectra*, vol. 25, no. 1, pp. 71-91, February 2009.
- [26] K. R. M. M. E. S. T. S. T. O. L. T. A. Z. G. M. D. A. Siavash Soroushian, "Seismic Response of Ceiling/Sprinkler Piping Nonstructural Systems in NEES TIPS/NEES Nonstructural/NIED Collaborative Tests on a Full Scale 5 Story Building," *Structures Congress*, pp. 1315-1326, March 2012.
- [27] K. S. S. Y. Y. S. M. A. Y. Matsuoka, "Non-Structural Component Performance in 4 Story Frame Tested to Collapse," *14th World Conference on Earthquake Engineering*, October 2008.
- [28] D. N. F. K. K. D. Tara Hutchinson, "Vibration Studies of Nonstructural Components and Systems Within a Full Scale Building," *Earthquake Spectra*, vol. 26, no. 2, pp. 327-347, May 2010.
- [29] R. D. G. M. A. F. Rodrigo Retamales, "NEESR Nonstructural Grand Challenge Project Simulation of the Seismic Performance of Nonstructural Systems Experimental Phase 1: Seismic Performance of Partition Wall Subsystems," Buffalo, New York, 2006.
- [30] G. M. A. R. M. P. S. W. R. R. Andre Filiatrault, "Preliminary Report Seismic Performance Assessment of a Full Scale Hospital Emergency Room," Buffalo, New York, 2008.
- [31] J. I. R. A. J. C. M. E. Rodriguez, "Earthquake Induced Floor Horizontal Accelerations in Buildings," *Earthquake Engineering and Structural Dynamics*, vol. 31, pp. 693-718, 2002.

- [32] T. H. Samit Ray Chaudhuri, "Distribution of Peak Horizontal Floor Acceleration For Estimating Nonstructural Element Vulnerability," in *13th World Conference on Earthquake Engineering*, Vancouver, B.C., Canada, 2004.
- [33] R. Villaverde, "Simple Method to Estimate the Seismic Nonlinear REsponse of Compoenets in Buildings," *Engineering Structures*, vol. 28, no. 8, pp. 1209-1221, July 2006.
- [34] L. M. L. E. S. E. E. M. M. P. Singh, "Seismic Design Forces. I: Rigid Nonstrcutural Components," *Structural Engineering*, vol. 132, no. 10, pp. 1524-1532, October 2006.
- [35] A. S. M. H. Akhlaghi, "Height-Wise Distribution of Peak Horizontal Floor Acceleration (PHFA)," in *14th World Conference on Earthquake Engineering*, Beijing, China, 2008.
- [36] M. S. N. N. S. F. M. Shooshtari, "Floor Response Spectra for Seismic Design of Operational and Functional Components of Concrete Buildings in Canada," *Canadian Journal of Civil Engineering*, vol. 37, pp. 1590-1599, October 2010.
- [37] E. L. Wilson, *Static & Dynamic Analysis of Structures: A Physical Approach with Emphasis on Earthquake Engineering*, 4th ed., Berkely, California: Computers and Structures, 2010.
- [38] M. Abell, June 2012. [Online]. Available: <https://wiki.csiamerica.com/display/kb/Ritz+vs.+Eigen+vectors>.
- [39] A. T. C. (ATC), "Quantification of Building Seismic Performance Factors," Redwood City, California, June 2009.
- [40] A. 7-10, "Minimum Design Loads for Buildings and other Structures," Reston, Virginia, 2010.
- [41] A. 341-1, "Seismic Provisions for Structural Steel Buildings," Chicago, Illinois , 2010.
- [42] A. I. o. S. Construction, *Specifications for Structural Steel Buildings*, 2nd ed., Chicago, Illinois: AISC, 2010.
- [43] AISC, "American Steel Construction Manual," Chicago, Illinois, 2005.
- [44] A. International, August 2013. [Online]. Available: [http://www.unitedmetalproducts.info/downloads/ASTM\\_A\\_653\\_REDLINE.pdf](http://www.unitedmetalproducts.info/downloads/ASTM_A_653_REDLINE.pdf).
- [45] A. S. Deck, August 2013. [Online]. Available: <http://www.ascsd.com/files/FloorDeck.pdf>.

- [46] E. L. W.F. Chen, *Earthquake Engineering for Structural Design*, Boca Raton, Florida: Taylor & Francis Group, LLC, 2006.
- [47] B. S. S. Council, "NEHRP Recommended Seismic Provisions for New Buildings and Other Structures," Washington D.C., 2009.
- [48] I. Computers & Structures, "ETABS Nonlinear version 9.7.3," 2011.
- [49] D. R. Medina, *CiE 887: Lecture 21 Modal Response Spectral Analysis*, 2012.
- [50] A. K. Chopra, *Dynamics of Structures*, 4th ed., Upper Saddle River, New Jersey: Prentice Hall, 2012.
- [51] J. M. a. M. E. Kevin Moore, "Design of RBS Moment Frame Connections," Moraga, California, August 1999.
- [52] R. Sudisman, September 2013. [Online]. Available: <http://rangasudisman.files.wordpress.com/2009/02/untitled21.jpg>.
- [53] a. M. D. E. Kee Dong Kim, "Monotonic and cyclic loading models for panel zones in steel moment frames," *Journal of Constructional Steel Research*, Vols. Volume 58, Issues 5–8, 2002, no. 5–8, p. 605–635, 2002.
- [54] S. P. S. a. A. Amidi, "Seismic Behavior of Steel Frames with Deformable Panel Zones," *Journal of Structural Engineering*, vol. 121 , no. No. 1, pp. 35-36, January 1998.
- [55] H. K. J. O. M. a. S. M. A. Ronald O. Hamburger, "Seismic Design of Steel Special Moment Frames," National Institute of Standards and Technology, Gaithersburg, Maryland, June 2009.
- [56] R. Vogel, "LRFD-Composite Beam Design With Metal Deck," Lafayette, California, March 1991.
- [57] T. B. Products, September 2013. [Online]. Available: <http://www.tegral.com/index.php?page=Comflor>.
- [58] C. a. S. Inc., *ETABS Version 9.7.3*, 2011.
- [59] A. S. Deck, October 2013. [Online]. Available: <http://www.ascsd.com/floor.html>.
- [60] I. Tsukrov, *ME 986 Advanced Finite Element Analysis Notes*, October 25, 2012.

- [61] P. NGA, "Pacific Earthquake Engineering Research Next Generation Attenuation," 2013.
- [62] A. K. Chopra, Dynamics of Structures, 4th ed., H. Stark, Ed., Upper Saddle River, New Jersey: Pearson, 2012.
- [63] T. M. Inc., *MATLAB Version 2011b*, 2011.
- [64] N. I. o. S. a. T. (NEHRP), "Evaluation of the FEMA P695 Methodology for Quantification of Building Seismic Performance Factors," Redwood City, California, November 2010.