1	Behavioral reactions of brown bears to approaching humans in Fennoscandia
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15 Summary

16 Human disturbance causes behavioral responses in wildlife, including large carnivores.

Previous research in Scandinavia has documented that brown bears (Ursus arctos) show a 17 variety of behavioral reactions to different human activities. We investigated how proximity 18 to human settlements and roads, as proxies of human influence, affected brown bears' 19 reactions to encountering humans. We analyzed experimental approaches to GPS collared 20 bears, 18 males and 23 single females, in Sweden (n = 148 approaches) and Finland (n = 33), 21 22 conducted between 2004 and 2012. The bears in Finland inhabited areas with higher human density compared to Sweden. However, the proportion of bears staying or moving when 23 approached and the flight initiation distances were similar in both countries. In Sweden, the 24 flight responses were not dependent on human densities or roads inside the bears' home 25 ranges or the distances from the bears to roads and settlements. Brown bears in Fennoscandia 26 27 live in areas with relatively low human population densities, but in many areas with high forestry road densities. Our results show that bears' flight reactions were consistent between 28 29 areas, which is an important message for management, reinforcing previous studies that have 30 documented human avoidance by bears at very different spatial and temporal scales.

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Keywords: experimental human disturbance, Finland, flight initiation distance, flight
 responses, human density, road density, Sweden

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35 Introduction

Wildlife generally react to and avoid human activities. However, behavioral responses vary in relation to factors such as the individuals' previous experience, physical condition, age, degree of gregariousness, antipredator strategies, type of disturbance, and time of day when it occurs (e.g., Whittaker and Knight 1998, Beale and Monaghan 2004a, Stankowich 2008,

Vincze et al. 2016, Tablado and Jenni 2017). Human disturbance can have short- and longterm effects, such as changes in distribution and activity patterns, and reduced breeding
success (Beale and Monaghan 2004b, Stankowich 2008 and references therein).

Moving away from or avoiding areas with human activity is indeed an antipredator
response, with disturbance perceived as predation risk by the responding animal (e.g., Gill et
al. 1996, Lima 1998, Frid and Dill 2002). Antipredator responses reduce risk and are therefore
crucial in modulating animal behavior (e.g., Deecke et al. 2002). Nevertheless, risk avoidance
implies costs, which animals try to minimize while maximizing survival (e.g., Gill et al. 1996,
Lima 1998).

49 Mammalian carnivores can be especially vulnerable to human disturbance (e.g., George and Crooks 2006). Large carnivores, such as brown bears (Ursus arctos), show spatial and 50 temporal reactions to a variety of human activities across their wide distribution range in 51 52 North America (e.g., Gibeau et al. 2002, Nielsen et al. 2004, Rode et al. 2006) and Europe (e.g., Naves et al. 2003, Nellemann et al. 2007, Ordiz et al. 2017). In Scandinavia, as 53 54 elsewhere, most brown bear mortality is caused by humans (Sahlén et al. 2006, Bischof et al. 2009) and mortality risk is higher closer to villages and roads (Steyaert et al. 2016). Not 55 surprisingly, brown bears generally select for rugged areas far from people (Nellemann et al. 56 57 2007). Bears' resting sites are concealed by denser vegetation when bears are closer to villages and during daytime compared to nighttime, suggesting that bears perceive and react 58 to proximity to people, especially in summer-autumn, when human activities outdoors are 59 most common (Ordiz et al. 2011). Bears' stress levels are also higher when they are closer to 60 humans (Støen et al. 2015). 61

Brown bears have been expanding in Scandinavia in the last century following a severe population decline, from approximately 130 bears around 1930 to ~3,000 bears in recent times (Swenson et al. 1995, Swenson et al. 2017), and some people express concern about

human safety in the forest. Similarly, in Finland there were only about 150 bears by the 65 66 1960's (Pulliainen 1983), and the population reached 1,150-1,950 bears in 2009 (Wikman 2010, Kopatz et al. 2014). Therefore, to better understand bear behavior and to inform 67 management agencies and the public about the reactions of bears to casual encounters with 68 outdoor users (hikers, berry or mushroom pickers, hunters, etc.), we have conducted several 69 studies in Sweden that included experimental approaches to radio-collared bears. Most bears 70 71 react by moving away, which holds for both single bears (Moen et al. 2012) and females with 72 cubs (Sahlén et al. 2015). After the encounters, bears become more nocturnal (Ordiz et al. 2013), as they do when bear hunting seasons start (Ordiz et al. 2012), and when they live in 73 areas with higher road densities (Ordiz et al. 2014). That is, the behavioral reaction of the 74 bears goes beyond their initial flight after encountering a person, which can change bears' 75 daily activity patterns for several days (Ordiz et al. 2013). 76

77 Whereas the research summarized above shows a solid pattern of bears' avoidance of people, it was conducted in areas with low human densities. There is a need for research on 78 79 bear reactions to humans also in areas with higher human densities, because the range of brown bears has been expanding in Fennoscandia, with bears moving into more human-80 dominated landscapes (Swenson et al. 1998, Kojola and Heikkinen 2006). It is possible that 81 82 bears relax their behavioral responses if they encounter humans more often and eventually habituate to their proximity. This could in turn make encounters with bears more dangerous, if 83 they do not move away as consistently as we have documented so far (Moen et al. 2012, 84 Sahlén et al. 2015). 85

In this study, we have conducted experimental approaches of radio-collared bears in Sweden and Finland to assess whether bears' behavioral responses, i.e., flight reactions, change in relation to the level of human activity. We used distance to roads and human settlements from the bears' initial sites and the densities of human population and roads in

bears' home ranges as proxies for human activity. We also controlled for variables that
influence the bears' flight reactions, i.e., bear behavior (if it was active or passive when
approached), vegetation concealment, season of the year, and individual characteristics of the
bears (Moen et al. 2012, Ordiz et al. 2013, Sahlén et al. 2015). As previous studies show that
brown bears in Scandinavia avoid humans on different scales, we did not expect to see a
reduced behavioral response of bears encountered by people due to living in areas with higher
human or road densities, but a consistent pattern of human avoidance by the bears.

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98 Methods

99 Study areas

The experimental approaches were conducted in Sweden and Finland. The study area in 100 southcentral Sweden (61.5°N 15° E, Gävleborg and Dalarna counties) consists of bogs and 101 102 heavily managed coniferous forest of mainly Scots pine (Pinus sylvestris) and Norway spruce (Picea abies). There are few main roads in the area, but a dense network of gravel roads (1.0 103 \pm 0.8 km/km², mean \pm SD) (Road map: Swedish National Land Survey). The human 104 105 population in the area is low, 3.6 - 6.2 inhabitants/km² in the four municipalities where the study was conducted (Statistics Sweden). The whole study area is located below the 106 timberline, which is at approximately 750 m a.s.l. (Dahle and Swenson 2003). Temperatures 107 108 in the study area average -7° C in January and 15° C in July (Swedish Meteorological and Hydrological Institute 2017a, b). The density of bears in the study area was estimated to ~30 109 bears/1000 km^2 (Solberg et al. 2006). 110

The study area in central and southeastern Finland ($62.5^{\circ}N 27^{\circ}E$) also consists of bogs and managed coniferous forest of Scots pine and Norway spruce. Altitudes range from 75 to 200 m a.s.l, all below the timberline. Temperatures average -8° C in January and 17° C in July (Finnish Meteorological Institute). There is a dense network of roads in the area (1.5 ± 1.1

km/km²) (National Land Survey of Finland), and the average human population is higher than 115 in the Swedish study area (11.3 - 16.2 inhabitants/km²) (Statistics Finland 2008). An estimate 116 of the bear density in the study area is ≥ 6 bears/1000 km² (Wikman 2010). The bears are 117 hunted in the fall in both areas, with hunting quotas averaging about 10% of the estimated 118 populations in recent years, i.e., ~300 bears are annually harvested in Sweden (National 119 Veterinary Institute 2017) and ~100 in Finland (The Finnish Wildlife Agency 2017). 120

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Bears and the experimental approaches

We analyzed 148 experimental approaches between humans and adult solitary brown bears 122 (9 males and 21 females) conducted in Sweden from 2006 to 2009, and 33 approaches on 123 solitary bears (9 males and 2 females) carried out in the Finnish study area from 2004 to 2012. 124 The bears were either followed from birth, being captured with previously known mothers, or 125 their age was determined through cross-section of the premolar roots (Matson et al. 1993). 126 127 Bears were from four to twenty years old in Sweden, and three to eleven years old in Finland. In Sweden, we approached the bears between one and six times per season, with a minimum 128 129 of 13 days and maximum of 92 days between each approach. Most of the bears in Sweden 130 were approached during one season (n = 18), although some were approached during two (n = 18) 10) or three seasons (n = 2). We approached the bears in Finland with a minimum of seven 131 days and maximum of 50 days between the approaches. The bears in Finland were 132 approached between one and six times per season, during one (n = 9) or three (n = 2) seasons. 133 The bears were captured and equipped with GPS Plus-3 or GPS Pro-4 neck collars 134 (VECTRONIC Aerospace GmbH, Berlin, Germany) and a VHF transmitter implant (IMP 135 400L) (Telonics, USA) in Sweden, and Tracker GSM/GPS without VHF (Tracker Inc., 136 Oulunsalo, Finland) in Finland (see Sundell et al. (2006) and Arnemo et al. (2007) for details). 137 The females in Finland were equipped with the same collar as the Swedish bears. Handling 138 was approved by the Swedish Ethical Committee on Animal Research and the Swedish 139

140 Environmental Protection Agency in Sweden, and the National Animal Experiment Board and141 the Finnish Ministry of Agriculture and Forestry in Finland.

On the day of the approach in Sweden, the bears' GPS collars were scheduled to send 142 positions every minute for three hours; one hour before the approach started and two hours 143 after. The position data in Sweden was collected into the Wireless Remote Animal 144 Monitoring (Dettki et al. 2013) database system for data validation and management. In 145 146 Finland, the collars were scheduled to send positions every 25 seconds at the start of the 147 approach, resulting in a poorer determination of pre-encounter behavior than in Sweden, and the interval of positions was gradually increased to 24 hours after the bear was passed by the 148 149 observers. The females' collars were scheduled to send positions every minute. The approaches in Sweden were conducted between 10:00 and 16:00 local time, when most bears 150 usually rest (Moe et al. 2007). The approaches in Finland were conducted between 08:00 and 151 152 19:00 local time. Prior to the approaches, the bears in Sweden were located based on triangulation of the VHF-signals from the neck collars and the implant. In Finland, bears' 153 154 locations before the approach were obtained from GPS positions in real time. The approaches were conducted by one to six people (1.9 \pm 0.7 observers), hereafter referred to as the 155 observers, who mimicked hikers and talked to each other during the encounters. If only one 156 157 observer conducted the approach, this person talked to him- or herself during the approach. The observers started the approaches 841 ± 336 m from the bear in Sweden and 952 ± 455 m 158 in Finland, walked towards it, passing the initial sites at 57 ± 67 m in Sweden and 52 ± 21 m 159 in Finland (the goal was passing the bears at approximately 50 m). During the approaches, the 160 bear's location and movement were monitored using VHF-tracking equipment in Sweden and 161 by observing the GPS positions on a computer by another observer who was in telephone 162 contact with the observers in the field in Finland. After passing the bear, the observers 163 continued walking away (approximately 500 m), keeping a distance to the bear to avoid 164

disturbing it a second time. The track of the observers in Sweden was registered with 165 positions every 10 m using a hand-held GPS receiver and the observers' track in Finland was 166 recorded with a GPS GSM device, similar to the bear collar (Benefon ESC!, Benefon Oyj, 167 168 Salo, Finland), set for sending positions every 20 seconds. Based on the GPS positions, bears were categorized as either 'passive', most typically 169 resting in a daybed, or 'active', e.g., foraging or moving around. If the diameter of the 170 positions in the control period, from start of minute positioning to the start of the approach, 171 172 did not exceed 70 m (min: 6 m, max: 68 m), the bears were judged as 'passive' (Moen et al. 2012, Sahlén et al. 2015). Bears were considered 'active' if the diameter exceeded 70 m (min; 173 174 80 m, max; 1728 m), and the positions indicated movement in the time before approach (Moen et al. 2012, Sahlén et al. 2015). This was visually checked in ArcGIS 10.1 (ESRI 175 2012). Some bears changed their activity during the control period, and the new activity level 176 177 was the basis for the analysis.

178 Site visits after encounters

In Sweden, field personnel visited both the initial site (IS), where the bear stayed prior to 179 the encounter, and the second site (SS), where the bear settled down after being disturbed, a 180 few days after the approaches were conducted. We located daybeds, verified by presence of 181 bear hair, and used this as the center of the IS of the passive bears and SS. For passive bears 182 without confirmed daybeds, the center of the cluster of GPS positions was defined as the IS, 183 and the last position before the approach started was defined as the IS for active bears. As a 184 proxy for concealment, the horizontal vegetation cover was measured as sighting distance 185 (Ordiz et al. 2009) in both IS and SS. The average sighting distance of the four cardinal 186

directions gave a sighting distance for each of the sites (see Ordiz et al. (2009) and Moen etal. (2012) for more details).

189 Data management and analysis

We calculated the speed between the bears' successive GPS positions and identified the 190 reactions to the encounters using statistical quality control (Montgomery 2005) and an 191 estimated upper control limit (UCL) for the control period, as described in Moen et al. (2012); 192 193 flight reaction identified for passive bears when movement was > 33.5 m/min (> 2.01 km/h), and for active bears with movement > 101.3 m/min (> 6.08 km/h). The flight initiation 194 distance (FID) was defined as the distance from the observer to the bears' last position prior 195 196 to an increased movement, i.e., where the speed between the bear's two successive GPS positions exceeded the activity-specific UCL and the bear left the initial site. This was also 197 checked visually in ArcGIS 10.1 (ESRI 2012). We did not include approaches where the 198 199 positions were missing for more than two minutes around the disturbance event; therefore, 19 approaches were excluded from the analysis of FID. Three bears left their IS without 200 201 exceeding the activity-specific UCL, hence no FID was registered. 202 Passing distance was calculated as the shortest distance between the IS and the observer, regardless of whether the bear was still in the IS when it was passed by the observer. The 203 204 minimum distance from the observer to the bear (distance to observer) was calculated as the shortest distance from the observer to the bear during the encounter. If the bear was at the IS, 205 distance to observer was calculated as distance from observer to IS. When a FID was recorded 206 and the bear settled down in a SS before the end of the scheduled minute positioning, the 207 distance between the position of FID and SS was defined as distance moved (DM). The 208 difference between time of FID and the first position in SS was defined as the time the bears 209 spent moving after disturbance (TSM). The method of data collection was different in 210 Finland, which resulted in fewer GPS positions after the observer passed the bears' initial 211

sites. DM and TSM were therefore only calculated for the bears in the Swedish study area. In
Sweden, two bears were encountered twice during one experiment, and DM and TSM were
not included in the analysis. One bear left after the end of the encounter, and this was not
included in the analysis of FID, DM, or TSM. In cases where the positioning prior to the
approaches was insufficient, we could not decide on the activity level of the bear, and the
encounters were not included in the analysis of FID, DM or TSM.

218 We used linear regression to analyze which variables affected whether bears stayed or moved when encountered, and their FID, DM, and TSM in Sweden. We included horizontal 219 vegetation cover (sighting distance) at IS, the bears' age and sex, activity pattern prior to the 220 221 encounter, season, number of observers, and passing distance or distance to observer as potential explanatory variables (Table 1), following previous studies (Moen et al. 2012, Ordiz 222 et al. 2013, Sahlén et al. 2015). Horizontal vegetation cover (sighting distance) at SS was also 223 224 included in the analysis of DM and TSM. The annual study periods were divided into preberry season (< 15 July) and berry season (\geq 15 July), which accounts for seasonality in bear 225 226 phenology and intensity of outdoor human activities (Ordiz et al. 2013). 227 In addition, variables that could describe how bears perceive human disturbance in the area around the IS and in their home ranges were included (Table 1). Based on maps from 228

229 Statistics Sweden and Swedish National Land Survey in Sweden, and National Land Survey

of Finland in Finland, we calculated the distances from the bears' IS and SS to the closest

road and the closest settlement using ArcGis 10.1 (ESRI 2012). Distance from IS and SS to

the closest settlement was highly correlated (r > 0.90), hence we only used distance from IS to

settlements in the regression models for DM and TSM.

The R package 'adehabitatHR' (Calenge 2006) was used to calculate the home range
kernels for each bear and year, based on half-hour GPS positions from the bears, using "href"
as the smoothing parameter (Calenge 2015). We calculated the home range kernels with

percentage levels of 50, 60, 70, 80, 90, and 95%. Densities of roads (km road/km²) and human 237 population (inhabitants/km²) were identified within each home range level using PostGIS 238 2.2.2 (http://postgis.net/) and GEOSTAT 1 km² population grid for 2006 (Eurostat) for density 239 of inhabitants and property map from 2016 (Swedish National Land Survey) for road density. 240 We could not identify a significant difference in the variation of road density between the 241 different levels of home range kernels (Levene's test: p = 0.63) (R package 'car': Fox and 242 Weisberg 2011) (50% level: 1.06 ± 0.03 km road/km² (mean \pm SE), 60% level: 1.09 ± 0.03 243 km road/km², 70% level: 1.12 ± 0.03 km road/km², 80% level: 1.12 ± 0.03 km road/km², 90% 244 level: 1.14 ± 0.02 km road/km², 95% level: 1.14 ± 0.02 km road/km²), so we used the 95% 245 home range kernels in the analysis. Similarly, we could not identify a significant difference in 246 the variation of human population density between the different levels of home range kernels 247 (Levene's test: p = 0.96) (50% level: 0.14 ± 0.03 inhabitants/km² (mean \pm SE), 60% level: 248 0.17 ± 0.05 inhabitants/km², 70% level: 0.18 ± 0.05 inhabitants/km², 80% level: 0.19 ± 0.04 249 inhabitants/km², 90% level: 0.2 ± 0.04 inhabitants/km², 95% level: 0.22 ± 0.06 250 inhabitants/km²), and we also used the 95% home range kernel here. 251 We compared how close the bears' ISs were to settlements and roads in Sweden and 252 Finland. We also tested if bears' FIDs where similar or not, and if approached bears stayed or 253 254 moved away similarly in both countries. However, the method of data collection in Finland was different, which did not allow us to identify the bears' home ranges, hence we did not 255 calculate the densities of roads or human population within the home ranges, and we did not 256 include the data from Finland in the regression models to explore which variables affected the 257 flight reactions of bears. 258

Table 1. Overview of the potential explanatory variables included in the regression models to analyze flight reactions of brown bears in Sweden. The response variables were stayed or moved, flight initiation distance (FID), distance moved after being disturbed (DM), and time spent moving after being disturbed (TSM). Activity = activity of the bear prior to the encounter; passive (0) or active (1), Age = age of bear in years, Sex = sex of the bear; male (0) or female (1), Sighting distance in IS or SS = Sighting distance at initial site (IS) or second site (SS) in m, i.e., horizontal vegetation cover at the site, Season = pre-berry season (0) or berry season (1), Passing distance = closest distance from observer to initial site in m, Distance to observer = minimum distance between observer and bear
 during the encounter in m, Number of observers = number of observers conducting the encounter,

268 Distance to settlements from IS = distance from initial site to the closest settlement in m, Distance to

road from IS or SS = distance from initial site (IS) or second site (SS) to the closest road in m, Road HR = km road/km² within the bear's 95% home range kernel, Human HR = density of human

HR = km road/km² within the bear's 95% home range kernel, Human HR = density of hu population as inhabitants/km² within the bear's 95% home range kernel.

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Response variable	Exploratory variables			
Stayed or moved	Activity + Age + Sex + Sighting distance in IS + Season + Number of observers +			
Distance to observer + Distance to settlements from IS + Distance to road from				
	Road HR + Human HR			
FID	Activity + Age + Sex + Sighting distance in IS + Season + Number of observers +			
	Passing distance + Distance to settlements from IS + Distance to road from IS + Road			
	HR + Human HR			
DM and TSM	Activity + Age + Sex + Sighting distance in IS + Sighting distance in SS + Season +			
	Number of observers + Distance to observer + Distance to settlements from IS +			
	Distance to road from IS + Distance to road from SS + Road HR + Human HR			

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274 We used generalized linear mixed models with a binomial link function in 'glmer' in R package 'lme4' (Bates et al. 2015) to analyze which factors explained that bears stayed or 275 moved when encountered. We used linear mixed models with function 'lmer' in R package 276 'lme4' (Bates et al. 2015) to analyze FID, DM, and TSM, which were all log transformed to 277 account for left-skewed distributions. Using the function 'dredge' in R package 'MuMIn' 278 279 (Barton 2017), possible candidate models for each of the flight responses were identified after standardizing the continuous variables to a mean of 0 and SD of 1 (Grueber et al. 2011) using 280 package 'standardize' (Eager 2017). The random factor bear ID was used for all of the 281 282 response variables. We calculated variance inflation factors (VIF) for the regression models for the different response variables, and they did not show sign of multicollinearity among 283 variables. We did not identify any correlation between the covariates at r > 0.6. 284 Because there were several candidate models with $\Delta AICc < 2$ for the models with the 285 response variables stayed or moved, DM and TSM, we averaged each set of models with the 286 function 'model.avg' in package 'MuMIn' (Barton 2017), and we report the outcome of the 287 full average models (Burnham and Anderson 2002, Grueber et al. 2011). We interpreted the 288 direction of the effects of the parameters included in the models with the 95% confidence 289

intervals (CI) of the effect sizes (β). When the 95% CI did not include zero, the effect had a
positive or negative effect on the response variable (Arnold 2010). We used R software (R
Core Team 2018) for all statistical analysis.

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294 **Results**

In Sweden, the bears' ISs were 20.0 ± 8.6 km (mean \pm SD) (n = 147) from the closest

settlement, and 0.35 ± 0.21 km from the closest road. In Finland, the bears' ISs were $11.8 \pm$

6.2 km (n = 20) from the closest settlement, and 0.25 ± 0.13 km from the closest road, i.e.,

distances from IS to settlements (Wilcoxon rank-sum test: W = 2256, p-value = 0.0001) and

distances from IS to roads (Wilcoxon rank-sum test: W = 1876, p-value = 0.046) were shorter

in Finland than in Sweden. On average, the home range kernels (95%) of the bears

approached in Sweden had a density of 1.1 ± 0.1 km road/km² and a human population

density of 0.2 ± 0.4 inhabitants/km².

In Sweden, bears stayed in their IS in 40 encounters and moved away in 107, and they 303 stayed in seven cases and moved away in 16 in Finland. The proportion of bears that stayed 304 and moved was not significantly different in Sweden and Finland (Fisher's Exact test for 305 count data: p-value = 0.803, n = 170). In Sweden, bears moved away more often during the 306 307 berry season than before, and with a higher number of approaching observers. The 95% CI of the effect estimates of other variables included the zero value, and therefore the direction of 308 the effect on the response was unclear (Tables 2 and 1A). Here we provide the results of the 309 model averaging for each response variable. The sets of top candidate models ($\Delta AICc < 2$ 310 compared to the model with the lowest AICc for each response variable) are in Appendix 1. 311 Table 2. Results from the generalized linear mixed regression (binomial link function) explaining the 312 factors that influenced whether bears stayed (0) or moved (1), with test statistics (full average) for the 313 averaged models with $\Delta AICc < 2$. The bears were experimentally approached in southcentral Sweden 314 in 2006-2009 (n = 118). The continuous variables are scaled to 1 SD. See Table 1 for explanation of 315

- 316 the variables. β is the effect size and SE the standard error.
- 317

Parameter	β	SE	95% CI
Intercept	-1.631	0.864	(-3.342, 0.080)
Season (pre-berry season $= 0$, berry season $= 1$)	1.659	0.502	(0.664, 2.654)
Number of observers	0.762	0.382	(0.006, 1.519)
Distance to observer	-0.093	0.186	(-0.459, 0.274)
Human HR	0.068	0.180	(-0.286, 0.422)
Road HR	0.050	0.144	(-0.234, 0.334)
Distance to road from IS	0.014	0.082	(-0.148, 0.176)
Activity (passive = 0 , active = 1)	-0.037	0.232	(-0.494, 0.421)

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- Average FID for bears that left before the observer passed the bear was 87 m \pm 72 m (median
- 320 = 63 m, n = 78) in Sweden and $120 \text{ m} \pm 129 \text{ m}$ (median = 69 m, n = 11) in Finland. FID was
- not significantly different in the two countries (Wilcoxon rank-sum test: W = 393, p-value =
- 322 0.658) (Fig. 1). FID for bears in Sweden increased with longer sighting distance, i.e., less
- 323 concealment at initial sites and longer passing distance (Table 3).



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- Figure 1: Distribution of flight initiation distances (in meters) in Finland (n = 11) and Sweden (n = 78) following experimental approaches conducted from 2004 to 2012 on radio-collared brown bears, when the bears left their initial sites before the observers passed them.
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Table 3. Results from the linear mixed regression of flight initiation distance (FID), with test statistics for the model with $\Delta AICc < 2$. The bears were experimentally approached in southcentral Sweden in 2006-2009 (n = 72). FID was log transformed. The continuous variables were scaled to 1 SD. See

Table 1 for explanation of the variables. β is the effect size and SE the standard error.

333

	AICc	ΔAICc	Model weight	β	SE	95% CI
Model: FID ~ Sighting distance in IS	190.2	0.00	1			
+ Passing distance				0.001	0.100	(0.211.0.207)
Intercept Sighting distance in IS				-0.001	0.106	(-0.211, 0.207)
Signing distance in IS				0.542	0.097	(0.132, 0.334)
				0.433	0.074	(0.20), 0.042)
5 Bears in Sweden that moved a	way fro	m the ini	tial site when e	encounter	ed, mov	ed on
6 average $1,002 \pm 809$ m (n = 87) in	n 22 ± 2	21 min (n	= 69). DM wa	s longer :	for active	e than for
7 passive bears, with more conceal	ment in	IS, and v	vith more obser	rvers (Ta	bles 4 an	nd 2A). For
8 TSM, the CI of the variables incl	uded in	the mode	el included zero	o, i.e., no	ne of the	variables
9 had a clearly negative or positive	effect o	on the res	ponse (Tables	5 and 3A	.).	
0 Table 4. Results from the linear mix	ed regres	ssion of d	istance moved (I	DM), with	ı test stati	stics (full
1 average) for the averaged models wi	th ΔĂIC	c < 2. The	e bears were exp	erimental	ly approa	ched in
2 southcentral Sweden in 2006-2009 (n = 71).	DM is log	g transformed. T	he continu	uous varia	ables are
3 scaled to 1 SD. See Table 1 for expla	anation o	of the vari	ables. B is the ef	fect size a	and SE th	e standard
4 error.			···· ··· · · · · · · · · · · · · · · ·			
5						
Parameter			β	SE		95% CI
Intercept			-1.186	0.4	19	(-2.018, -0.354)
Activity (passive = 0 , active = 1)			0.918	0.3	24	(0.270, 1.566)
Sex (male = 0, female = 1)			0.410	0.3	15	(-0.213, 1.032)
Sighting distance in IS			-0.326	0.1	12	(-0.550, -0.102)
Number of observers			0.279	0.1	30	(0.110, 0.620)
Number of observers			0.378	0.1	50	(0.118, 0.639)

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Table 5. Results from the linear mixed regression of time spent moving after disturbance (TSM), with

test statistics (full average) for the averaged models with $\Delta AICc < 2$. The bears were experimentally

approached in southcentral Sweden in 2006-2009 (n = 63). TSM is log transformed. The continuous

350 variables are scaled to 1 SD. See Table 1 for explanation of the variables. β is the effect size and SE

the standard error.

352

Parameter	β	SE	95% CI
Intercept	2.217	0.405	(1.415, 3.019)
Number of observers	0.246	0.168	(-0.086, 0.579)
Sighting distance in IS	-0.062	0.117	(-0.293, 0.169)
Sex (male = 0, female = 1)	0.055	0.172	(-0.285, 0.396)

353

354 **Discussion**

Our experimental approaches of brown bears in Sweden and Finland showed similar flight 355 reactions by the bears in both countries. The distance from bears' initial sites to settlements 356 and roads were shorter in Finland than in Sweden, reflecting the higher densities of human 357 358 population and roads in the study area in Finland. Nevertheless, the bears' responses showed a consistent pattern of human avoidance. The proportion of bears that stayed at their initial sites 359 and the FID of the bears that moved were not different in Sweden and Finland. This 360 361 consistency in bear behavior can be explained by several reasons. First, the bear populations in Sweden and Finland show similar historical trends, with recent population recovery after 362 centuries of intense persecution (Pulliainen 1983, Swenson et al. 1995, Wikman 2010, Kopatz 363 364 et al. 2014, Swenson et al. 2017). Second, bears are managed as game species in both countries, with similar annual levels of legal hunting (National Veterinary Institute 2017, The 365 Finnish Wildlife Agency 2017), as explained in Methods. Third, it has also been suggested 366 367 that some flight responses to disturbance, e.g., FID, are species-specific and therefore responses may be predictable and repeatable at different sites (Blumstein et al. 2003). In 368 369 addition, large carnivores living in human-dominated landscapes are generally elusive, likely 370 as a response to long-term human persecution, and European bears are no exception (Ordiz et al. 2011, Zedrosser et al. 2011). 371

372 We were able to analyze, at a finer scale, if human-related variables influenced the bears' behavioral responses when they were approached in Sweden. The human-related variables 373 road density and human population density inside home ranges of the approached bears, and 374 distances to roads from the bears' initial sites when they were approached, were retained in 375 376 the final, averaged model for the flight response variable stayed/moved (Table 2). However, the 95% CI of the effect estimates of those variables included zero, i.e., they explained some 377 378 variation in the bears' flight response, but the direction of their effects was not clear. The human population density inside the home ranges of the approached bears in Sweden (0.2 \pm 379

0.4 inhabitants/km²) was lower than the average human population density in the study area 380 generally (3.6 - 6.2 inhabitants/km²). However, the road density inside the home ranges (1.1 \pm 381 0.1 km road/km²) was virtually identical to the average values in the study area $(1.0 \pm 0.8 \text{ km})$ 382 road/ km²). The low human densities and the lack of variation in road density may help 383 explain the low effect of the human-related variables in these analyses. Regarding human 384 density, bears avoid humans on the landscape scale, residing far from people (Nellemann et 385 al. 2007), even if human density is generally low in our study area. Regarding road density, it 386 reflects the dense network of forest roads built over the years to harvest the coniferous forest, 387 and these roads are virtually impossible for bears to avoid, given their large home ranges. 388 389 Previous research helps interpret these results as well. Whereas proximity to settlements did not influence how diurnal or nocturnal daily bear movements were, bears moved primarily in 390 the nocturnal and twilight hours and less during daytime in areas with higher road density, 391 392 compared to areas with no roads (Ordiz et al. 2014). In fact, roads have many negative effects on wildlife, e.g., causing direct mortality and favoring human activity (e.g., Trombulak and 393 394 Frissell 2000), and the road network is indeed an impediment for Scandinavian bear movements (Bischof et al. 2017). Nevertheless, in the present study, we worked in an area 395 with high and very constant gravel road density, and this lack of variation likely explains the 396 relatively low magnitude of the road effect on the bears' flight responses. 397 Bears moved more often from their initial sites when approached in the berry season (≥ 15 398

July), a period when bears spend most time foraging ("hyperphagia") and human activity levels are generally higher, than in the pre-berry season (Table 2), when the bear mating season occurs and there are fewer human activities outdoors (Ordiz et al. 2011). Previous research in Sweden has also shown that the bears' behavioral reactions are accentuated in summer, compared to spring. For instance, bears seek denser vegetation cover in summer to avoid human activities, including hunting (Ordiz et al. 2011, Ordiz et al. 2012). Number of

observers was important for whether the bears stayed or moved away and for DM. The effects
of human disturbance on wildlife reflect perceived predation risk, which has often been
shown to vary, as in our case, with factors such as the distance between humans and animals
and with the number of humans causing disturbance (Beale and Monaghan 2004b).

We do not claim that the observed flight responses by the bears in Fennoscandia provide a 409 full picture of their perceived predation risk. For instance, in the absence of visible behavioral 410 411 responses, physiological responses have been documented for several species (e.g., Fowler 1999). Stress can cause a reduction in fitness, which can be due to higher metabolic needs in 412 response to increased heart rate after disturbance (e.g., Beale and Monaghan 2004b). In 413 414 Sweden, previous research has shown that bears have higher stress levels, measured in terms of heart rate variability, when they are closer to people than when they are farther away 415 416 (Støen et al. 2015). Bears also change daily movement patterns for several days after 417 disturbance, therefore altering optimal foraging and resting times (Ordiz et al. 2013). As in previous studies (Moen et al. 2012, Ordiz et al. 2013, Sahlén et al. 2015), we 418 419 experienced no aggressive reactions by bears towards the observers, neither in Sweden nor in 420 Finland, reinforcing the pattern of human avoidance by European brown bears. At the fine scale, bears rely on vegetation concealment or flee (Moen et al. 2012, Sahlén et al. 2015, this 421 422 study) and at the landscape scale, bears spend most of the time far from human settlements (Nellemann et al. 2007). 423

Our study in Fennoscandia includes the lowest human densities across the distribution
range of brown bears in Europe, but bear populations also thrive in eastern and southern
Europe with much higher human densities (Swenson et al. 2000). Although bears and other
large carnivores are generally elusive, as described above, behavioral reactions to approaching
humans might differ if encounters occur more often, as they may do in areas with a higher
human population and outdoor activity elsewhere than in Fennoscandia. Our results provide

important knowledge about bear reactions encountering people in the forest, but similar
studies might be needed in other areas to reveal potential differences and similarities in large
carnivore behavior when facing different human densities, activities and alternative
management scenarios; e.g., bears are hunted in several European countries, but they are
protected in southern Europe (Swenson et al. 2000).

435 Management implications

With expanding bear populations, bears are expected to settle closer to humans, and an 436 important message to managers is that the bears' behavior to approaching humans does not 437 seem to change solely based on the density of humans or roads in the bears' home ranges. 438 439 Also, the lack of aggressive reactions by bears to observers on one hand, and the effects of 440 human disturbance on bear behavior, which may cause fitness reduction as the ultimate cost 441 of disturbance (Gill et al. 2001), on the other hand, are important messages for managers. In human-dominated landscapes, conservation-oriented management of large carnivores under 442 hunting regimes, such as bears in Sweden and Finland, should aim to quantify and eventually 443 444 account for the subtle, indirect effects of hunting and other human activities that cause disturbance, in addition to pay attention to more intuitive, lethal demographic effects (Frank et 445 al. 2017, Bischof et al. 2018). 446

447

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644 Appendix 1

- 645 Sets of top candidate models, with $\Delta AICc < 2$ compared to the model with the lowest AICc for each
- response variable, for flight reactions of brown bears experimentally approached in southcentral
- 647 Sweden.

648

- 649 Table 1A: Best candidate models ($\Delta AICc < 2$) following generalized linear mixed regression
- (binominal link function) explaining the factors that influenced whether brown bears stayed (0) or
- moved away (1) when approached by humans in southcentral Sweden, from 2006 to 2009 (n = 118).
- The continuous variables were scaled to 1 SD. See Table 1 for explanation of the variables.
- 653

Model	AICc	ΔAICc	weight
Season + Number of observers	134.41	0.00	0.21
Season + Number of observers + Distance to observer	134.99	0.58	0.16
Season + Number of observers + Human HR	135.24	0.83	0.14
Season + Number of observers + Road HR	135.49	1.08	0.12
Season + Number of observers + Distance to observer + Human HR	135.94	1.53	0.10
Season + Number of observers + Distance to road from IS	136.11	1.70	0.09
Season + Number of observers + Distance to observer + Road HR	136.18	1.78	0.09
Season + Number of observers + Activity	136.21	1.80	0.09

654

655

Table 2A. The best candidate models ($\Delta AICc < 2$) following linear mixed regression explaining

distance moved (DM) for bears when approached by humans in southcentral Sweden from 2006 to

2009 (n = 71). The bears left their initial sites before the observers passed them. DM is log

transformed. The continuous variables are scaled to 1 SD. See Table 1 for explanation of the variables.

660

Model	AICc	ΔAICc	weight
Activity + Sex + Sighting distance in IS + Number of observers	202.93	0.00	0.55
Activity + Sighting distance in IS + Number of observers	204.51	1.58	0.25
Activity + Sex + Sighting distance in IS + Number of observers + Season	204.87	1.94	0.21

661 662

663 Table 3A. The best candidate models ($\Delta AICc < 2$) following linear mixed regression explaining time 664 spent moving after disturbance (TSM) for bears when approached by humans in southcentral Sweden

from 2006 to 2009 (n = 63). The bears left their initial sites before the observers passed them. TSM is

log transformed. The continuous variables are scaled to 1 SD. See Table 1 for explanation of the

667 variables.

668

Model	AICc	ΔAICc	weight
Number of observers	167.62	0.00	0.37
Number of observers + Sighting distance in IS	168.31	0.68	0.26
NULL	168.74	1.12	0.21
Number of observers + Sex	169.26	1.64	0.16