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Abstract

Understanding how multiprotein complexes function in cells requires detailed quantitative understanding of their association and dissociation kinetics. Analysis of the heterogeneity of binding lifetimes enables the interrogation of the various intermediate states formed during the reaction. Single-molecule fluorescence imaging permits the measurement of reaction kinetics inside living organisms with minimal perturbation. However, poor photophysical properties of fluorescent probes limit the dynamic range and accuracy of measurements of off rates in live cells. Time-lapse single-molecule fluorescence imaging can partially overcome the limits of photobleaching; however, limitations of this technique remain uncharacterized. Here, we present a structured analysis of which timescales are most accessible using the time-lapse imaging approach and explore uncertainties in determining kinetic subpopulations. We demonstrate the effect of shot noise on the precision of the measurements as well as the resolution and dynamic range limits that are inherent to the method. Our work provides a convenient implementation to determine theoretical errors from measurements and to support interpretation of experimental data.

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1 Identification of multiple kinetic populations of DNA-binding

2 proteins in live cells

3 **Running title: Measuring binding lifetimes in cells**

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- 15

16 **ABSTRACT**

17 Understanding how multi-protein complexes function in cells requires detailed quantitative 18 understanding of their association and dissociation kinetics. Analysis of the heterogeneity of 19 binding lifetimes enables interrogation of the various intermediate states formed during the 20 reaction. Single-molecule fluorescence imaging permits the measurement of reaction kinetics 21 inside living organisms with minimal perturbation. However, poor photo-physical properties 22 of fluorescent probes limit the dynamic range and accuracy of measurements of off rates in live 23 cells. Time-lapse single-molecule fluorescence imaging can partially overcome the limits of 24 photobleaching, however, limitations of this technique remain uncharacterized. Here, we 25 present a structured analysis of which timescales are most accessible using the time-lapse

26 imaging approach and explore uncertainties in determining kinetic sub-populations. We 27 demonstrate the effect of shot noise on the precision of the measurements, as well as the 28 resolution and dynamic range limits that are inherent to the method. Our work provides a 29 convenient implementation to determine theoretical errors from measurements and to support 30 interpretation of experimental data.

31 STATEMENT OF SIGNIFICANCE

32 Measuring lifetimes of interactions between DNA-binding proteins and their substrates is 33 important for understanding how they function in cells. In principle, time-lapse imaging of 34 fluorescently-tagged proteins using single-molecule methods can be used to identify multiple 35 sub-populations of DNA-binding proteins and determine binding lifetimes lasting for several tens of minutes. Despite this potential, currently available guidelines for the selection of 36 37 binding models are unreliable, and the practical implementation of this approach is limited. Here, using experimental and simulated data we identify the minimum size of the dataset 38 39 required to resolve multiple populations reliably and measure binding lifetimes with desired 40 accuracy. This work serves to provide a guide to data collection, and measurement of DNA-41 binding lifetimes from single-molecule time-lapse imaging data.

42 **INTRODUCTION**

Understanding fundamental processes of life requires characterization of the kinetics of interactions between biological molecules. At single-molecule levels, these systems often exhibit kinetic heterogeneity that is inherent to the presence of multiple intermediate states (1-17). Advances in single-molecule imaging have enabled the detection and characterization of heterogeneous sub-populations in reactions conducted *in vitro* as well as, *in vivo*. Ultimately, these investigations enable the construction of detailed molecular mechanisms to explain how various biomolecular interactions proceed.

50 Compared to *in vitro* studies, live-cell investigations offer the key advantage of studying 51 biochemical reactions at physiological conditions that can be difficult to reconstitute. Single-52 molecule live-cell imaging commonly relies on fluorescent proteins that are genetically fused to the protein of interest (Fig. 1A) (18-22). Tracking the fluorescence signal of thousands of 53 54 molecules, one molecule at a time, enables the building of physical models, from which 55 physical parameters such as diffusion constants and detachment rates from DNA can be 56 determined. Where detachment rates are concerned, the trajectory lengths of thousands of 57 molecules are aligned to obtain a cumulative residence time distribution (CRTD). At the single-58 molecule level, the dissociation of a protein from its substrate is a stochastic process. This 59 phenomenon can be adequately described as a two-state kinetic model with the interconversion 60 of populations being modelled as a Poisson process. The resulting CRTD can be fit to 61 exponential functions to obtain decay rates. In the case of a fluorescently tagged protein where loss of fluorescence is attributable to either dissociation, or photobleaching of the 62 63 chromophore, the decay rate represents a combination of dissociation rates and photobleaching 64 rate (Fig. 1B-C) (23).



65

66 FIGURE 1 Experimental approach for characterizing kinetic heterogeneity of protein binding 67 in live cells using single-molecule fluorescence imaging. (A) The protein of interest is tagged 68 with a fluorescent protein. When the protein binds to DNA substrate, its fluorescence signal 69 appears as a diffraction-limited focus that can be tracked in real time. Subsequent dissociation 70 results in the disappearance of the focus and a redistribution of fluorescence signal throughout 71 the cell. Yellow outlines illustrate the bacterial cell membrane. (B) The loss of fluorescence is 72 attributable to either dissociation, or photobleaching of the chromophore. (C) Cumulative 73 residence time distribution (CRTD) constructed from binding durations of thousands of 74 molecules. Fitting the exponential function (Eq. 1) to CRTD yields an effective rate k_{eff} , which 75 is the sum of off rate (k_{off}) of the protein of interest and photobleaching rate (k_b) of the 76 fluorescent probe (23). (D) To deconvolute k_b and k_{off} , excitation and integration durations (τ_{int}) 77 can be spaced with various dark intervals (τ_d). (E) Through exponential analyses, CRTDs 78 obtained at various intervals result in $k_{eff}\tau_{tl}$ plots which are indicators of kinetic heterogeneity 79 (23). A single kinetic population yields a straight line whereas deviations from linear fits indicate the presence of a second kinetic sub-population. For a single kinetic population, the 80 81 slope is the off rate and y-intercept is proportional to the photobleaching rate.

82 Photobleaching, a result of fluorescent proteins being damaged upon exposure to excitation 83 sources, leads to the loss of fluorescence signal (24). Under excitation conditions that guarantee good signal-to-background ratios, fluorescent proteins can only stay 'on' for a few frames 84 during continuous acquisitions. This limited visualization window reflects the 'photon budget' 85 86 (25). Thus, when photobleaching occurs faster than the dissociation process, lifetime measurements are limited by the photobleaching rate. To overcome this problem and extend 87 the observation time, the observation time window can be expanded by temporally spacing the 88 89 photon budget using stroboscopic imaging (26). In this method, a dark interval (τ_d) is inserted

90 between integration time (τ_{int}), effectively scaling the observation time with a factor of τ_{tl}/τ_{int} 91 $(\tau_{tl} = \tau_{int} + \tau_d)$. Instead of using one dark interval, Gebhardt and co-workers (2013) developed 92 an approach involving 'time-lapse illumination with a fixed integration time, interspersed with 93 dark periods of varying duration' in which fluorescence acquisitions are collected at a series of 94 time-lapse intervals (Fig. 1D) (23, 27). This method has also been variously referred to as 'time-95 lapse imaging' (28), 'time-lapse illumination with different dark times' (29), 'time-lapse 96 imaging at multiple timescales' (30) and 'stroboscopic single particle tracking PALM' (31). 97 For the purpose of brevity, and to distinguish from a time-lapse imaging mode with a single 98 dark interval, we have adopted the term 'interval imaging' in our lab (32). Briefly, the approach 99 works as follows: First, several movies (each with a unique dark interval) are collected while 100 keeping the photon budget constant (in practice this is achieved by keeping the number of 101 frames constant across all the movies). In cases where the copy number of the tagged protein 102 is high and single-molecule imaging conditions may be difficult to attain, the cellular 103 fluorescence is first photobleached such that only single-molecule fluorescence is observable. 104 Subsequently, using particle tracking algorithms that enable measurements of lifetimes of 105 bound molecules within a specified localization radius, a CRTD can be compiled. Fitting the 106 CRTDs to effective rates (k_{eff}), one can obtain the so-called $k_{eff}\tau_{tl}$ plot which is linear for mono-107 exponential distributions (Fig. 1E) (23). In this case, since the photobleaching rate is 108 maintained constant across all conditions, it can be read off from the intercept on the Y-axis. 109 A population of molecules dissociating with a finite and measurable off rate manifests as a 110 straight line, where the slope reports on the off rate of the dissociation kinetics. A mixed 111 population composed of species dissociating with multiple lifetimes manifests as a deviation 112 from the linear fit (Fig. 1E) (23). Fitting the experimental data to a model describing mixed 113 populations can then be used to extract the relative amplitudes and rates of the various 114 populations. This power to deconvolute the photobleaching rate from multiple off rates has

been successfully harnessed to dissect the kinetic heterogeneity of various DNA binding
proteins including transcription factors and DNA replication and repair proteins in live cells
(23, 27-33).

118 However, limitations arising from the practical implementation of this elegant method remain 119 uncharacterized. In particular, we address the following questions: 1) What is the minimum 120 number of observations needed to determine the binding lifetime of a species within a specified 121 confidence? 2) For a given experimental setup, what is the dynamic range in binding lifetimes 122 that can be detected? 3) How many populations can be resolved? and 4) What limits the ability 123 to reliably resolve multiple populations? We consider four cases below to answer these 124 questions. This study serves to provide a practical guide to realize the power as well as 125 limitations of practical implementations of the interval imaging approach to measure 126 intracellular binding kinetics of fluorescently tagged proteins.

127 METHODS

128 Rationale and model

129 For an introduction to the method, we direct the reader to seminal work by Gebhardt and co-130 workers who have developed and demonstrated the time-lapse imaging approach discussed 131 here (23). Here, we first summarize the theoretical development to establish the context of the 132 problem for this report. Consider a system containing 'A' number of fluorescently tagged 133 DNA-bound proteins, wherein the proteins dissociate from DNA with a single off rate (k_{off}). 134 Upon exposure to excitation photon sources, the fluorescent proteins exhibit photobleaching with a rate $k_{\rm b}$, resulting in the loss of fluorescence signal. Additionally, dissociation contributes 135 136 to the loss of fluorescent foci as protein molecules move out of the localization radius. Since 137 dissociation and photobleaching are independent, and both are Poisson processes, the loss of 138 observations as a function of time *t* can be described as:

$$f_1(t) = A\exp(-(k_b + k_{off})t)$$
 (1, ref. (23))

Observation times of genetically expressible fluorescent proteins are severely limited to the duration of a few acquisition frames due to photobleaching, limiting measurements of longlived binding events (34). To extend observation times, the frame rate can be reduced by inserting a dark interval (τ_d) after a short integration time (τ_{int}). Scaling the photobleaching rate appropriately, Eq. 1 then becomes:

$$f_2(t) = A\exp(-(k_b\tau_{int}/\tau_{tl} + k_{off})t)$$
 (2, ref. (23))

where the time-lapse time τ_{tl} is the sum of τ_{int} and τ_d . The sum of two decay rates k_b and k_{off} can be approximated with an effective decay rate (k_{eff}):

$$k_{\rm eff} = k_{\rm b} \tau_{\rm int} / \tau_{\rm tl} + k_{\rm off} \qquad (3, \rm ref. (23))$$

146 Rearrangement of Eq. 3 yields:

$$k_{\rm eff}\tau_{\rm tl} = k_{\rm b}\tau_{\rm int} + k_{\rm off}\tau_{\rm tl} \qquad (4, \rm ref. (23))$$

147 As $k_{b}\tau_{int}$ is maintained constant at a certain imaging condition, $k_{eff}\tau_{tl}$ increases linearly with τ_{tl} , 148 with the coefficient (slope) k_{off} .

149 In systems with two sub-populations each dissociating at different rates k_{off1} and k_{off2} , Eq. 2 150 then becomes:

$$f_{3}(t) = A \Big(B \exp(-(k_{\rm b} \tau_{\rm int} / \tau_{\rm tl} + k_{\rm off1}) t)$$

$$+ (1 - B) \exp(-(k_{\rm b} \tau_{\rm int} / \tau_{\rm tl} + k_{\rm off2}) t) \Big)$$
(5, ref. (23))

- 151 where B (0 < B < 1) and (1 B) are the amplitudes of k_{off1} and k_{off2} sub-populations respectively.
- 152 Similarly, a system with three kinetic sub-populations can be described by:

$$f_{4}(t) = A \Big(B_{1} \exp(-(k_{b}\tau_{int}/\tau_{tl} + k_{off1})t)$$

$$+ B_{2} \exp(-(k_{b}\tau_{int}/\tau_{tl} + k_{off2})t)$$

$$+ (1 - B_{1} - B_{2}) \exp(-(k_{b}\tau_{int}/\tau_{tl} + k_{off3})t) \Big)$$
(6, ref. (29))

- 153 where B_1 , B_2 (0 < B_1 , B_2 < 1 and B_1 + B_2 < 1) and (1 B_1 B_2) represent the amplitudes of k_{off1} ,
- 154 k_{off2} and k_{off3} sub-populations respectively.

156 **Experimental considerations**

157 The specifics of the experimental setup for different model organisms should be tailored to 158 requirements for the respective system. However, to provide the reader with a starting point, 159 we describe the experimental configuration used in our lab to measure binding lifetimes of 160 DNA-repair proteins labelled with the fluorescent protein, YPet in the model organism 161 Escherichia coli (E. coli) (see Fig. S1 and ref. (32)). Bacterial cells in early exponential phase 162 are loaded into a custom-built flow cell made up a glass coverslip and a quartz top. The bottom 163 coverslip is functionalized with (3-Aminopropyl)triethoxysilane (APTES, Alfa Aesar, USA) 164 to facilitate cell adhesion to the surface of the coverslip. The temperature of the flow cell is 165 kept constant at 30 °C. Cells are supplied with aerated rich defined media (EZ rich defined medium supplemented with glucose, Teknova) to maintain fast growth. YPet is excited with 166 167 514-nm laser (Sapphire LP laser, Coherent, USA) in near-TIRF configuration (35) at a power density of 71 W/cm² (measured directly above the inverted objective). Fluorescent signal is 168 169 recorded using an electron-multiplying (EM)-CCD camera (Photometrics Evolve, 170 Photometrics, USA), with an EM gain of 1,000. The camera exposure time is 0.1 s and time-171 lapse imaging is acquired with a 10-s τ_{tl} set (Table S2). Typically, a time-lapse imaging 172 experiment lasts three to five hours and in generally four to ten experiments are required to 173 obtain more than a thousand binding events at each τ_{tl} .

Resolution of binding events in bacterial cells expressing copy numbers of fluorescent proteins in excess of ~ 20 copies per cell is challenging due to the limitations of particle tracking algorithms to resolve closely spaced foci. Further, distinguishing bound molecules from freely diffusive molecules in the cytosol is also challenging when copy numbers are high. In this case, to enable reliable observation of single- molecule cells are exposed to continuous illumination such that the majority of the emitters are darkened or photo-bleached, and only stochastically 180 reactivated emitters are observed in single-molecule imaging conditions (36).

181 This setup allows us to unambiguously detect single-molecule foci using a relative signal-to-182 background ratio between six and eight. Foci detected in at least two consecutive frames within 183 a 300-nm (3 pixels) radius are defined as a binding event. For each τ_{tl} , all binding events are 184 combined, and bootstrapping analysis is performed by randomly selecting with replacements 185 80% of all binding events. CRTDs are constructed from bootstrapped samples and are fit to 186 exponential models to obtain $k_{eff}\tau_{tl}$ plots, as well as k_b and τ .

187 Simulating concurrent dissociation and photobleaching

188 In order to maintain full control of the kinetic variables, we chose to perform simulations of 189 the experiment. Simulations of exponential distributions and curve-fitting were performed with 190 custom-written program in MATLAB (The MathWorks, Natick, MA). We simulated 191 exponential distributions (Eq. 2,5,6) using the *exprnd* function in MATLAB (Supplementary 192 Notes). This function generates exponentially distributed random numbers with a specified 193 decay constant. Here, each number returned by exprnd function represents the lifetime of a 194 simulated 'trajectory'. For the purposes of this work, we have not accounted for blinking of 195 bound molecules that may yield prematurely truncated binding events. Accommodation of such 196 a feature will require reasonable estimates of FP blinking under the conditions of the 197 experiment that will be unique to the fluorescent probe used. To simulate a sub-population of 198 molecules dissociating with a specified off rate, a set of trajectories was generated and binned 199 to produce histograms with ten bins, whose edges correspond to frame times (integer multiples 200 of τ_{tl}). The *exprnd* function was iterated until the counts of the first bin exceeded the number 201 of binding events in that sub-population (typically between three and six iterations, see Fig. 202 S2). To simulate experiments where multiple sub-populations are present, each sub-population 203 was simulated in defined proportions and all trajectories were pooled together. Finally, to 204 generate the CRTDs, we rejected molecules in the first bin (0 to τ_{tl}) and only carried forward observations from τ_{tl} to $10\tau_{tl}$ to the next step in accordance with our definition of a binding 205 206 event (or trajectories), *i.e.*, the observation must be present in two consecutive frames.

To simulate uncertainty in each simulation sample, ten rounds of bootstrapping were performed, each involved randomly sampling 80% of the simulated population. Next, fitting was performed on each bootstrapped CRTDs (henceforth referred simply as CRTDs). First, the CRTD at each τ_{tl} was fit to a mono-exponential model to obtain k_{eff} (Eq. 2, 3 and Fig. 1C). These values for k_{eff} , corresponding to the number of τ_{tl} , were then used to construct the $k_{\text{eff}}\tau_{\text{tl}}$ plot. Error bands in these plots represent standard deviations from ten bootstrapped samples.

Second, the CRTDs for all τ_{tl} were fit to objective functions based on Eq. 2, 5 and 6 (global fitting, see Supplementary Notes). The list of parameters, initial conditions, bound constraints, termination criteria and algorithm is presented in Table S1. Throughout the paper, *A* was set as a local parameter to mimic experimental conditions where counts may be different across τ_{tl} , even though this often leads to less accurate results compared to when *A* was set as a global parameter (Fig. S3B-C).

For each simulation, outcomes from globally fitting the ten bootstrapped CRTDs were averaged and reported. To determine uncertainty in the estimate, we repeated the simulation a hundred times. The standard deviations of the binding lifetime (σ_{τ}) from a hundred simulations using the same conditions was calculated according to Eq. 7.

$$\sigma_{\tau} = \left(\sum_{i=1}^{100} (\tau_i - \langle \tau \rangle)^2 / 100 \right)^{1/2}$$
(7)

223 where $\langle \tau \rangle$ denotes the true binding lifetime, which is calculated by $1/\langle k_{off} \rangle$.

Unless otherwise stated, $k_b \tau_{int}$ was fixed at 0.7 to mimic experimental values obtained in our published work (32). Four sets of τ_{tl} were used: 10-s τ_{tl} , 100-s τ_{tl} , the three- and five- τ_{tl} sets (Table S2).

228 **RESULTS**

Influence of experimental sample size on uncertainty of the estimate of thebinding lifetime

231 First, we set out to investigate whether the size of the experimental data set influences the 232 uncertainty in the error estimate of the outcomes from global fitting, such as the binding lifetime τ and photobleaching rate k_b . This can be achieved by randomly selecting a fraction of 233 234 experimental data (3%-30%) at each τ_{tl} , following by bootstrapping and global fitting. Toward 235 this goal, we revisited published data from our laboratory where interval imaging was used to 236 determine dissociation kinetics of the transcription-repair coupling factor Mfd from DNA in 237 live E. coli (32). The entire dataset (100%) contains between 1,000 to 2,000 trajectories (counts 238 lasting at least two frames) at each τ_{tl} (Fig. 2A, right-most panel). Representative CRTDs 239 following sub-sampling the experimental dataset (3%, 10% and 30%) at each τ_{tl} are shown in 240 (Fig. 2A). While the $k_{eff}\tau_{tl}$ plot derived from the whole dataset resembles a straight line, 241 deviations from linear fits in $k_{eff}\tau_{tl}$ plots can be seen when only a sub-set of experimental data 242 was used (Fig. 2B).

To determine the uncertainties in k_b and τ as a result of under-sampling, we repeated the subsampling a hundred times and k_b and τ values were obtained from global fitting using Eq. 2 (Fig. 2C-D). Here, uncertainties in the estimates of k_b and τ are smallest when the entire data set is used (2% and 5% respectively, Fig. 2C-D), and as expected, increase with decreasing number of counts (Fig. 2C-D). For k_b , uncertainties increase from 3% to 10% as the percentage of experimental data drop from 30% to 3% while uncertainties in determining binding lifetimes increase from 8% to 35% (Fig. 2C-D).

250 Fitting individual CRTD to mono-exponential model to obtain $k_{eff}\tau_{tl}$ plots has been suggested

251 to be used as a guide to determine kinetic heterogeneity (23). Our analysis demonstrates that 252 deviation from linear fits in the $k_{\rm eff}\tau_{\rm tl}$ plots can potentially simply reflect under-sampling. Since 253 deviations from linear fits in $k_{\rm eff}\tau_{\rm tl}$ plots can also be used to guide the choice of bi- and tri-254 exponential models (23), a fundamental question that faces users is, what governs the choice 255 of exponential model? What is the minimum size of data, for which a multi-exponential model 256 is appropriate for consideration? Are deviations in the $k_{eff}\tau_{tl}$ plots reliable indicators for the 257 choice of model? To explore these questions in greater detail, we chose to perform simulations 258 that permit us to retain full control of the model parameters, and overcome practical limitations 259 of generating large data sets from microscopy experiments.



FIGURE 2 Determination of the photobleaching rate and binding lifetime from sub-sampling experimental data presented in ref (32). (A) Representative CRTDs when only 3%, 10% or 30% of experimental trajectories were randomly selected. Counts can be approximated as yintercepts of exponential fits of CRTDs. The CRTD from the full dataset (right most panel) is

reproduced from ref. (32). (B) $k_{eff}\tau_{tl}$ plots of the corresponding CRTDs (above). Shaded error 265 266 bands are standard deviations from ten bootstrapped samples. (C) Scatter plots show distributions of k_b obtained using global fitting 100 subsets of the experimental data at the 267 268 indicated fraction. Each point represents the average of results from ten bootstrapped samples. (D) Scatter plots show distributions of τ obtained using global fitting 100 subsets of the 269 270 experimental data at the indicated fraction. Similarly, each point represents the average of 271 results from ten bootstrapped samples. Red bars and boxes represent means and standard 272 deviations of the fitting outcomes of 100 subsets of the dataset respectively. The experimentally 273 measured value of $\tau = 17.9 \pm 0.9$ s for the entire data set is reproduced from ref (32).

Case I: Influence of the size of the data set on the measured lifetime for a single dissociating species

276 We first explored the relationship between the number of counts (*n*) at each τ_{tl} and uncertainties in estimates of binding lifetimes from mono-exponential distributions. To this end, we 277 simulated a population of molecules dissociating with k_{off} of 0.1 s⁻¹, corresponding to a binding 278 lifetime $\langle \tau \rangle$ of 10 s, and photobleaching rate k_b of 7 s⁻¹ (see Methods). While τ_{int} was constant 279 at 0.1 s, τ_{tl} was varied from 0.1 s to 10 s (Table S2). These values of k_b , $\langle \tau \rangle$, τ_{int} and τ_{tl} were 280 initially chosen to closely match experimental values used in our published work (see Fig. 2 281 and ref. (32)). The theoretical $k_{\text{eff}}\tau_{\text{tl}}$ plot is shown as the dashed line (Fig. 3A). At $n = 1 \times 10^3$ 282 observations (Fig. 3A), the $k_{\rm eff}\tau_{\rm tl}$ plot deviates noticeably from the theoretical line (purple 283 curve). However, as *n* increases, the error bands reduce, and the plots closely resemble straight 284 lines (purple curves, Fig. 3B-D). At 1×10^5 observations, linearly fitting the $k_{\text{eff}}\tau_{\text{tl}}$ plot (Fig. 3D) 285 yielded a slope of 0.1 and y-intercept of 0.6992, reflecting the specified k_{off} (0.1 s⁻¹) and $k_b \tau_{int}$ 286 (0.7). As expected, mono-exponential distributions with the same $k_b \tau_{int}$ but smaller off rate (k_{off} 287 = 0.01 s⁻¹) or without off rate ($k_{off} = 0 \text{ s}^{-1}$) yielded lines with smaller slope (Fig. 3A-D, green 288 curves) or essentially flat lines (Fig. 3A-D, black curves). 289



FIGURE 3 Determination of binding lifetimes from mono-exponential distributions. (A-D) 291 $k_{\rm eff}\tau_{\rm tl}$ plots of mono-exponential distributions with $k_{\rm b}\tau_{\rm int}$ of 0.7 and $k_{\rm off}$ of 0.1 s⁻¹ (purple curves), 292 0.01 s⁻¹ (green curves) or 0 s⁻¹ (black curves). Panels A-D reflect $k_{\rm eff}\tau_{\rm tl}$ plots obtained from 293 simulations containing number of observations (n) equaling (A) $1x10^3$, (B) $3x10^3$, (C) $1x10^4$ 294 295 or (D) 1x10⁵ counts in the first bin (see Methods). (A) Dashed lines correspond to theoretical $k_{\rm eff}\tau_{\rm tl}$ plots at the specified $k_{\rm off}$ values. Shaded error bands are standard deviations from ten 296 bootstrapped samples. (E) Scatter plots show distributions of τ obtained using global fitting 297 from 100 simulated samples for each *n* value. Red bars represent the mean values. (Inset) The 298 relative error in determining τ ($\sigma_{\tau}/\langle \tau \rangle$) reduces with $n^{-1/2}$ for increasing *n*. Dashed line is the 299 linear fit to six data points. (F) Coefficient in function of $\sigma_{\tau}/\langle \tau \rangle$ versus $n^{-1/2}$ at various $\langle \tau \rangle$. 300 The sharp increase in coefficients for $\langle \tau \rangle$ larger than 50 s indicates larger uncertainties in 301 measuring slow processes when the maximum τ_{tl} is limited to 10 s. 302

304 To characterize the uncertainty (standard deviation, σ_{τ}) in the estimate of the binding lifetime, 305 we repeated the simulation a hundred times for each value of n and determined τ using global 306 fitting (Fig. 3E). As expected for shot noise (37), the relative error $\sigma_{\tau}/\langle \tau \rangle$ is proportional to 307 the inverse of the square root of *n* with a coefficient of 3.8 (Fig. 3E, inset). Importantly, the 308 coefficient fluctuates between 3.7 and 5.7 for $\langle \tau \rangle \leq 50$ s, but rises sharply for $\langle \tau \rangle$ greater than 50 s (Fig. 3F). This result demonstrates that the uncertainty in estimating lifetime of long-lived 309 310 binding events becomes arbitrarily large when the extended lifetime of the fluorophore (by 311 introduction of τ_d) becomes comparable to the binding lifetime. In principle, this limit can be readily overcome by simply selecting larger τ_{tl} values; indeed, simulations of mono-312 exponential distributions of long-lived binding events ($\tau = 100$ s) indicated that σ_{τ} is lower at 313 314 lower values of *n*, when τ_{tl} is extended to 100 s, compared to 10 s (Fig. S3).

315 Therefore, we propose that accurate measurements of lifetime of long-lived binding events 316 require significant increases in either the number of observations (*n*) or the length of τ_{tl} for a 317 fixed photobleaching rate. However, it should be noted that extension of τ_{tl} up to 100 s may 318 not be experimentally feasible for all systems. In our work involving bacterial live-cell imaging 319 in rich media, cell growth and division on the timescale of imaging limit the tracking binding 320 events lasting on the timescale of tens of minutes. Practical limitations imposed by the model 321 organism, growth conditions and choice of fluorescent protein dictate optimal experimental 322 design.

Further, we anticipated that photobleaching rate also contributes to σ_{τ} as faster photobleaching reduces observation times. To examine the effect of $k_{\rm b}\tau_{\rm int}$, we performed a comprehensive set of simulations with the 10-s $\tau_{\rm tl}$ set (Table S2) and $k_{\rm b}\tau_{\rm int}$ varying from 0.007 to 2.1 ($k_{\rm b}$ from 0.07 to 70 s⁻¹ and $\tau_{\rm int}$ from 0.01 to 0.1 s). We obtained the relationship between σ_{τ}/τ , *n* and $k_{\rm b}\tau_{\rm int}$ as 327 in Eq. 8.

$$\frac{\sigma_{\tau}}{\tau} = \frac{(2.7379k_{\rm b}\tau_{\rm int})^2}{n^{1/2}} \tag{8}$$

This formula describes the lower bound of errors as other sources of practical errors, such as localization uncertainties and experimental variations, have not been considered. The minimum number of observations required to determine τ ($\langle \tau \rangle \leq 50$ s) with a given uncertainty is therefore:

$$n = (\tau/\sigma_{\tau})^2 \times (2.7379k_b\tau_{\rm int})^4 \tag{9}$$

For example, when $k_b \tau_{int}$ is 0.7, the number of observations required to achieve relative error of 10% in the estimate of τ (where $\langle \tau \rangle \leq 50$ s) is about 1350 (see Fig. 3E). This equation also highlights the importance of using fluorophores with high photo-stability: a two-fold increase in k_b needs to be compensated by a 16-fold increase in *n*.

336 **Case II: Detection of two species with resolvable lifetimes**

337 Next, we examined the situation where a second kinetic sub-population is present in the system. 338 A second population with a faster off rate yields $k_{\rm eff}\tau_{\rm tl}$ plots that deviate from straight lines (23). 339 However, as we demonstrate deviations can also be a result of shot noise at low n (see Fig. 2B) 340 and Fig. 3A-D). To identify the minimum n at which one can determine with a specified 341 confidence that a bi-exponential model is appropriate, we simulated CRTDs using Eq. 5. First, we performed simulations with off rates that are an order of magnitude apart: $k_{off1} = 0.1 \text{ s}^{-1}$ 342 (intermediate rate) and $k_{off2} = 1 \text{ s}^{-1}$ (fast rate). The amplitude *B* of the intermediate dissociating 343 344 population was varied from 10% to 90% (Fig. 4).



346

347 FIGURE 4 Determination of binding lifetimes and amplitudes from bi-exponential 348 distributions with an intermediate rate (k_{off1}) and a fast rate ($k_{off2} = 10 k_{off1}$). (A-D) $k_{eff}\tau_{t1}$ plots of bi-exponential distributions with $k_{b}\tau_{int}$ of 0.7, k_{off1} and k_{off2} of 0.1 and 1.0 s⁻¹ respectively, 349 with (A) 10^3 , (B) $3x10^3$, (C) 10^4 or (D) 10^5 observations. The amplitude of k_{off1} (B) is 10% 350 (orange), 25% (purple), 50% (green) or 90% (black). Shaded error bars are standard deviations 351 352 from ten bootstrapped samples. (E-G) Heatmaps show errors in estimates of B, τ_1 and τ_2 353 obtained using global fitting of 100 simulated distributions for each n value (see Fig. S4 for 354 distributions).

355 When the majority of the population dissociates with the intermediate rate k_{off1} (B = 90%), the

356 $k_{\text{eff}\tau_{tl}}$ plots resemble those of mono-exponential distribution with the single k_{off} of 0.1 s⁻¹

357 (compare Fig. 4A-D, black curves and Fig. 3A-D). As before, increasing the number of

358 observations significantly improved the quality of the $k_{eff}\tau_{tl}$ plots (Fig. 4A-D). These 359 simulations reveal that a short-lived second sub-population does not manifest as a visible 360 feature in the $k_{\rm eff}\tau_{\rm tl}$ plots when it is present only to the extent of 10% in the observations. To 361 examine if the two populations could be resolved with global fitting using the bi-exponential 362 model, we determined binding lifetimes and amplitudes from 100 simulations (Fig. S4). 363 Unsurprisingly, we found that the accuracies and precisions of determining B, τ_1 and τ_2 increase with *n*. While estimation of τ_1 is robust (Fig. 4F, Fig. S4B), global fitting of CRTDs to the bi-364 365 exponential model at low counts suffers from a bias towards the fast dissociating subpopulation, with its amplitude being overestimated and τ_2 being underestimated (Fig. 4E, G, 366 Fig. S4A, C). This bias is observed to a lesser extent when k_{off1} is present at 75% or 50% (Fig. 367 368 4E-G, Fig. S4).

369 As the amplitude of the fast dissociating sub-population increased (B equal to 25% or 10%), 370 fewer observations were found at long intervals. Insufficient counts resulted in missing data points at these τ_{tl} ($\tau_{tl} \ge 5$ s) in $k_{eff}\tau_{tl}$ plots at low counts (10³ and 3x10³, Fig. 4A-B). However, 371 the $k_{\rm eff}\tau_{\rm tl}$ plots extended to the full $\tau_{\rm tl}$ range of 10 s when *n* increases to 10⁴ and 10⁵ (Fig. 4C-372 373 D). As expected, deviations from straight lines were found in the 0-5 s regime, reflecting the 374 presence of the fast dissociating sub-population. Since contributions from the fast dissociating 375 sub-population drop sharply at long timescales, the $k_{\rm eff}\tau_{\rm tl}$ plots converge to the straight line 376 exhibited by mono-exponential distributions with k_{off1} (Fig. 4C-D). Further analysis by integrating the area under the peaks in the 0-to-5 s region shows the area increases 377 378 exponentially with the amplitude of the fast dissociating sub-population (Fig. S5). When the 379 fast dissociating sub-population represents the majority, the accuracy and precision in 380 determining *B*, τ_1 and τ_2 also increase with *n* (Fig. 4E-G, Fig. S4).

381 Based on the observation that accurate measurements of long-lived binding events require the

extension of τ_{t1} to greater than 10 s, we anticipated that resolving two kinetic sub-populations [one with a slow rate (k_{off1} of 0.01 s⁻¹; $\langle \tau_1 \rangle = 100$ s) and an intermediate rate (k_{off2} of 0.1 s⁻¹; $\langle \tau_2 \rangle = 10$ s)] is challenging when the largest τ_{t1} is 10-s. Consistent with this, the $k_{eff}\tau_{t1}$ plots in the 0-10s range appear linear (Fig. 5A-C), resembling those of mono-exponential distributions. Hence, we attempted to fit the CRTDs at 10⁵ counts to mono-exponential model (Eq. 2), yielding apparent binding lifetimes (τ^*) that lie between $\langle \tau_1 \rangle$ and $\langle \tau_2 \rangle$ (Fig. 5D). Fitting mean τ^* vs. *B* to exponential function results in Equation 10:

$$\tau^* = \langle \tau_2 \rangle e^{\log(\langle \tau_1 \rangle / \langle \tau_2 \rangle) B} \tag{10}$$

389 Thus, *B* can be derived from
$$\tau^*$$
 where $\langle \tau_1 \rangle$ and $\langle \tau_2 \rangle$ are known.

From the simulations, fitting the CRTDs with *n* less than $3x10^4$ to the bi-exponential model yields unreliable results (Fig. 5E-G, Fig. S6). Across various amplitudes of k_{off1} , the species with lifetime τ_1 , is often underestimated and corresponds to τ^* at that amplitude (compare Fig. 5F to Fig. 5D). Similarly, τ_2 is also underestimated, but eventually approaches $\langle \tau_2 \rangle$ of 10 s when *n* reached 10⁶ counts and the amplitude of k_{off2} sub-population is more than 25% (Fig. 5G).



396

FIGURE 5 Determination of binding lifetimes and amplitudes from bi-exponential 397 distributions with a slow rate (k_{off1}) and an intermediate rate ($k_{off2} = 10k_{off1}$). (A-C) $k_{eff}\tau_{tl}$ plots 398 of bi-exponential distributions with $k_{\rm b}\tau_{\rm int}$ of 0.7, $k_{\rm off1}$ and $k_{\rm off2}$ of 0.01 and 0.1 s⁻¹ respectively, 399 with (A) 10^3 , (B) 10^4 or (C) 10^5 observations. The amplitude of k_{off1} (B) is 10% (orange), 25% 400 401 (purple), 50% (green) or 90% (black). Shaded error bars are standard deviations from ten bootstrapped samples. (D) Scatter plots show distribution of apparent τ (τ^*) obtained from 402 fitting of 100 simulated bi-exponential distributions at a specified B and 10^5 counts to mono-403 404 exponential model. Line is exponential fit between the average of τ^* (red bars) and B. (E-G) 405 Heatmaps show errors in estimates of B, τ_1 and τ_2 obtained using global fitting of 100 simulated 406 distributions for each *n* value (see Fig. S6 for distributions).

408 On the other hand, when the above distributions were simulated using the 100-s τ_{t1} set, 409 deviations from straight lines in $k_{eff}\tau_{t1}$ plots were observed in the 0-30s regime and when *B* is 410 smaller than 75% (Fig. S7A). In this case, as expected, accuracies in determining *B*, τ_1 and τ_2 411 follow the same trends as discussed in Fig. 4 (Fig. S7B-D).

412 **Case III: Detection of two species with closely matched lifetimes**

413 Due to the resolution limit that is inherent to exponential analysis (34), we anticipated the 414 ability to resolve rates that are closely spaced would reduce. To test this hypothesis, we 415 simulated bi-exponential distributions with rates that are only three-fold apart: an intermediate rate k_{off1} of 0.1 s⁻¹ and a fast rate k_{off2} of 0.3 s⁻¹. Under conditions that yield sufficient 416 observations at long intervals ($n \ge 10^4$), examination of the $k_{\text{eff}}\tau_{\text{tl}}$ plots often fails to identify the 417 418 presence of multiple sub-populations in the form of deviation from straight lines (Fig. 6A-D). Only when the fast rate is present at 90%, can deviations be observed in the form of a broad 419 420 convex spanning from 0 to 10 s (orange curves, Fig. 6C-D). Fitting to Eq. 5 yields unreliable 421 results for *B* and τ_2 for $n \le 10^4$ (Fig. 6E, G, Fig. S8A, C) whereas the accuracy in determining τ_1 requires 3 x10³ observations or $\langle B \rangle$ to be larger than 25% (Fig. 6F, Fig. S8B). Fitting CRTDs 422 at low counts ($n < 10^4$) to the bi-exponential model should be avoided as one often obtains two 423 424 kinetics sub-populations with artificially enhanced rate separation and substantial amplitudes, regardless of the true amplitudes (Fig. 6E-G, Fig. S8). 425



426

427 FIGURE 6 Determination of binding lifetimes and amplitudes from bi-exponential 428 distributions with closely spaced rates ($k_{off2} = 3k_{off1}$). (A-D) $k_{eff}\tau_{t1}$ plots of bi-exponential 429 distributions with $k_b\tau_{int}$ of 0.7, k_{off1} and k_{off2} of 0.1 and 0.3 s⁻¹ respectively, with (A) 10³, (B) 430 $3x10^3$, (C) 10^4 or (D) 10^5 observations. The amplitude of k_{off1} (*B*) is 10% (orange), 25% 431 (purple), 50% (green) or 90% (black). Shaded error bars are standard deviations from ten 432 bootstrapped samples. (E-G) Heatmaps show errors in estimates of *B*, τ_1 and τ_2 obtained using 433 global fitting of 100 simulated distributions for each *n* value (see Fig. S8 for distributions).

435 **Case IV: Detection of three species**

The resolution limit as well as dynamic range limit that we demonstrated above raise the 436 437 question if tri-exponential distributions can be faithfully resolved under the specified experimental condition (ranges of τ_{tl} and *n*). To address this issue, we simulated tri-exponential 438 439 distributions (Eq. 6), with off rates spanning two orders of magnitude (0.01, 0.1 and 1 s⁻¹), 440 using the 100-s τ_{tl} set. The diversity in $k_{eff}\tau_{tl}$ plots obtained by varying B_1 and B_2 is illustrated in Fig. 7A. Three kinetic sub-populations are apparent when B_1 is a third of B_2 and B_2 in turn 441 is a third of B_3 $(1 - B_1 - B_2)$. We further characterized uncertainties in amplitudes and binding 442 lifetimes obtained using global fitting to the tri-exponential model (Methods). In general, 443 444 accuracy in determining the amplitudes and lifetimes improves with increasing n (Fig. 7B-F, 445 Fig. S9). However, when the slowly dissociating sub-population dominates $(B_1 = 9/13)$, increasing n does not yield more accurate estimates. As in the case of the bi-exponential 446 447 simulations, we observed consistent biases towards faster binding lifetimes (Fig. S9).



FIGURE 7 Determination of binding lifetimes and amplitudes from tri-exponential 450 distributions with a slow rate (k_{off1}), an intermediate rate ($k_{off2} = 10k_{off1}$) and a fast rate ($k_{off3} =$ 451 $10k_{off2}$), using the 100-s τ_{tl} set. From left to right, five panels in each row correspond to different 452 amplitudes of each sub-population (displayed on top). (A) $k_{eff}\tau_{tl}$ plots of tri-exponential 453 distributions with $k_b \tau_{int}$ of 0.7, k_{off1} , k_{off2} and k_{off3} of 0.01, 0.1 and 1 s⁻¹ respectively, with 10⁶ 454 observations. Shaded error bands are standard deviations from ten bootstrapped samples. (B-455 456 F) Heatmaps show errors in estimates of B_1 , B_2 , τ_1 , τ_2 and τ_3 obtained using global fitting of 100 simulated distributions at various pre-set values of B_1 and B_2 (see Fig. S9 for distributions). 457

458

459 The choice of τ_{tl}

460 Given a finite amount of experimental time, should one sample with more τ_{tl} values (increase N_{interval}) or obtain more observations (increase n) with a set containing fewer τ_{tl} values? To 461 identify the optimum choice of τ_{tl} , we simulated bi-exponential distributions with an 462 intermediate rate ($k_{off1} = 0.1 \text{ s}^{-1}$) and a fast rate ($k_{off2} = 1 \text{ s}^{-1}$) using a τ_{t1} set containing either 463 three (N_3) or five (N_5) τ_{tl} values, ranging from 0.1 to 10 s (Table S2). Since fitting outcomes 464 are unreliable in the three τ_{tl} set (compare Fig. S10 to Fig. S11), we decided to examine the 465 simulations with the five τ_{tl} set further. These simulations yielded $k_{eff}\tau_{tl}$ plots that closely 466 467 resemble those in Fig. 4 (see Fig. 8A-D) and similarly, deviations from straight lines are also 468 reliable indicators of kinetic heterogeneity when B is less than 90%. As expected, estimates of 469 *B*, τ_1 and τ_2 are more accurate with larger *n* (Fig. S10).

470 Compared the simulations using the five τ_{tl} and the 10-s τ_{tl} (11 τ_{tl} values) sets for the same *n*, 471 errors of estimates are almost always smaller in simulated distributions with the 10-s τ_{tl} set $(\sigma_{11}/\sigma_5 < 1, \text{ see Fig. 8E})$. By extension of Eq. 8, error ratios (σ_{11}/σ_5) smaller than $1/\sqrt{(11/5)}$ or 472 473 0.67 indicate the benefit of increasing N_{interval} outweighs the benefit of increasing n with the 474 five τ_{tl} set whereas error ratios larger than 0.67 represent redundancy in τ_{tl} . Redundancy in τ_{tl} 475 was observed in some cases when the intermediate dissociating sub-population is the majority (B between 75% and 90%) (Fig. 8E). However, when the majority dissociates with the fast rate 476 477 (*B* between 10% and 50%), the benefit of sampling with more τ_{tl} is clear ($\sigma_{11}/\sigma_5 < 0.67$), especially with $n \ge 10^4$. Thus, we concluded the net benefit of increasing N_{interval} is greater than 478 479 increasing the number of counts with a set of fewer τ_{tl} values.



FIGURE 8 Determination of binding lifetimes and amplitudes from bi-exponential distributions using a τ_{tl} set containing five τ_{tl} values (Table S2), an intermediate rate ($k_{off1} = 0.1$ s⁻¹) and a fast rate ($k_{off2} = 1 \text{ s}^{-1}$). (A-D) $k_{eff}\tau_{tl}$ plots of bi-exponential distributions with (A) 10³, (B) 3x10³, (C) 10⁴ or (D) 10⁵ observations. The amplitude of k_{off1} (*B*) is 10% (orange), 25% (purple), 50% (green) or 90% (black). Shaded error bands are standard deviations from ten bootstrapped samples. (E) Bar plots show ratios of error estimates obtained from simulations with eleven and five τ_{tl} values at the same *n*. Blue: *B*, green: τ_1 , yellow: τ_2 .

488

489 **DISCUSSION**

In this work, we used experimental and simulated data to explore the influence of shot noise, resolution limit and dynamic range limit on resolving multiple kinetic sub-populations in single-molecule time-lapse imaging experiments (Fig. 9). Within the dynamic range and resolution limit, determination of binding lifetimes and amplitudes in mono-exponential and multi-exponential distributions are reliable in general, especially with at least 10⁴ counts.



495

496 FIGURE 9 Dynamic range and resolution limits in resolving multiple populations using the 497 time-lapse imaging technique with photobleaching-prone fluorescent probes. Dynamic range 498 limit is a function of photobleaching rate (k_b) and the maximum τ_{tl} (τ_{tl_max}) used in experimental 499 conditions. τ_{n-1} is the longest binding lifetime in a multi-exponential distribution within pairs 490 of off rates k_n and k_{n-1} . Orange zones indicate conditions where errors in estimates of τ and the 491 amplitude are high.

As showed in Eq. 8, the relative error in τ determination scales with the square of $k_b\tau_{int}$ and the inverse square root of *n*. This emphasizes the importance of choosing imaging conditions to minimize $k_b\tau_{int}$ as a two-fold increase in $k_b\tau_{int}$ needs to be compensated by a 16-fold increase in *n*. A balance has to be struck here to ensure good signal-to-background ratio, a prerequisite for reliable particle tracking. These findings also highlight the importance of developing and using fluorophores with higher photo-stability and brightness for live-cell applications as these would greatly reduce uncertainties in measurements. In practice, the choice of fluorescent protein should be made with great care, as fluorescent proteins often exhibit undesirableproperties that limit their utility (38-42).

Errors obtained from repeating the experiments can be an underestimation compared to inherent errors conferred by shot noise when fitting is ill-conditioned (43), which is often the case when minimizing using multi-objective functions (44). Therefore, reports of binding lifetimes measurements using these time-lapse imaging approaches should clearly state $k_b \tau_{int}$ from fitting and *n* from experimental data. This would enable a theoretical error estimation of τ and avoid over-interpretation of experimental results.

We found $k_{eff}\tau_{tl}$ plots useful for guiding the fitting model when the number of counts is 517 sufficiently large (more than 10^4) as deviations from straight lines faithfully reflect 518 519 heterogeneity in binding kinetics. The reverse is not necessarily true. Good linear fits, seen at 520 large *n* values, can reflect one of the following three scenarios: (i) the absence of multiple populations, (ii) sub-populations with off rates that are within the resolution limit, or (iii) sub-521 522 populations where the off rate of one population lies beyond the dynamic range. This dynamic range is determined by the photobleaching rate and the maximum τ_{tl} used in the experiment. 523 524 When the mono-exponential model is used to fit those data, an apparent binding lifetime τ^* , whose value lies between the two true binding lifetimes, is obtained. While sub-optimal, τ^* 525 526 depends on the proportion of molecules in each kinetic sub-population: a larger presence of the 527 fast dissociating sub-population yields smaller τ^* . This in turn can report on change in binding kinetics when the biology is manipulable – for instance with binding partners or drugs. 528

529 Can statistical information such as reduced χ^2 be used to decide the model that best describes 530 the data? Computing these criteria requires the determination of the degree of freedom, which 531 still needs to be analytically derived for the non-linear models used in this method (45-48). 532 Instead of using statistical criteria, the selection of the fitting model using $k_{eff}\tau_{tl}$ plot can be 533 complemented with experimental design. For example, in case where a bi-exponential model is invoked, it might be tempting to attribute sub-populations to molecules performing certain 534 535 activities such as binding of DNA repair proteins to a damaged or non-damaged substrate. 536 These hypotheses can be tested using structure-function mutants in which one or few catalytic 537 activities are inhibited, hence, yielding predictable changes in $k_{\rm eff}\tau_{\rm tl}$ plots and fitting results. 538 Finally, where possible, we recommend approaches that utilize multiple experimental designs 539 to reproducibly observe or enrich the hypothesized populations.

540 SOFTWARE

541 Our algorithms are freely available as open source MATLAB codes from 542 https://github.com/hanngocho/off-rate-simulation.

543 SUPPORTING INFORMATION

544 The supplementary information is available following publication.

545 AUTHOR CONTRIBUTIONS

H.N.H., H.G. and A.M.v.O. designed research. H.N.H. wrote the codes, conducted the
simulations and wrote the first draft. D.Z. contributed to the codes, with support from J.K. H.G.
and A.M.v.O revised the manuscript and supervised research.

549

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Supplementary Information for

Identification of multiple kinetic populations of DNA-binding proteins in live cells

Running title: Measuring binding lifetimes in cells

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Supplementary table

Table S1. Initial conditions, constraints and termination tolerance used in global fitting. n_0 is the minimum number of counts in the second bin across τ_{tl} .

Model	Initial conditions	Bound constraints	Termination tolerance	Algorithm	MATLAB function
Mono (Eq. 2)	$k_{\rm b} = 1 {\rm s}^{-1}$ $k_{\rm off} = 1 {\rm s}^{-1}$	$k_{\rm b} > 0 \ {\rm s}^{-1}$ 0 s ⁻¹ < $k_{\rm off} < 1/\tau_{\rm int} \ {\rm s}^{-1}$	10 ⁻⁶	trust-region- reflective	lsqnonlin
Bi (Eq. 5)	$k_{\rm b} = 1 {\rm s}^{-1}$ $k_{\rm off1} = 1 {\rm s}^{-1}$ B = 0.5 $k_{\rm off2} = 2 {\rm s}^{-1}$	$k_{\rm b} > 0$ $10^{-3} {\rm s}^{-1} < k_{\rm off1} < 1/\tau_{\rm int} {\rm s}^{-1}$ $1/n_0 < B < 1 - 1/n_0$ $10^{-3} {\rm s}^{-1} < k_{\rm off2} < 1/\tau_{\rm int} {\rm s}^{-1}$	10 ⁻⁶	trust-region- reflective	Isqnonlin
Tri (Eq. 6)	$k_{\rm b} = 1 {\rm s}^{-1}$ $k_{\rm off1} = 0.05$ ${\rm s}^{-1}$ $B_1 = 0.3$ $k_{\rm off2} = 0.5 {\rm s}^{-1}$ $B_2 = 0.3$ $k_{\rm off2} = 5 {\rm s}^{-1}$	$k_{\rm b} > 0 {\rm s}^{-1}$ $10^{-3} {\rm s}^{-1} < k_{\rm off1} < 1/\tau_{\rm int} {\rm s}^{-1}$ $1/n_0 < B_1 < 1 - 1/n_0$ $10^{-3} {\rm s}^{-1} < k_{\rm off2} < 1/\tau_{\rm int} {\rm s}^{-1}$ $1/n_0 < B_2 < 1 - 1/n_0$ $10^{-3} {\rm s}^{-1} < k_{\rm off3} < 1/\tau_{\rm int} {\rm s}^{-1}$ $B_1 + B_2 < 1 - 2/n_0$	10 ⁻⁹	trust-region- reflective	fmincon

Table S2. The τ_{ti} sets used in the study.

τ _{tl} sets	τ_{tl} values (s)
10-s	0.1, 0.2, 0.3, 0.4, 0.6, 1, 2, 3, 5, 8, 10
100-s	0.1, 0.3, 0.7, 1, 3, 7, 10, 30, 70, 100
Three-	0.1, 1, 10
Five-	0.1, 0.3, 1, 3, 10

Supplementary figures



Figure S1. Schematic of experimental setups in single-molecule live-cell imaging. Bacteria expressing fluorescently labelled proteins are loaded in a flow cell with a constant supply of media at 30 °C. The fluorescent label (YPet) is excited with 514-nm light and fluorescence signal is recorded with an electron-multiplying CCD camera.



 N_1 - the number of molecules in k_{off1} sub-population (A x B_1)

Figure S2. Schematic of the simulation of the cumulative residence time distribution (CRTD) at a specified τ_{tl} . The molecules were generated by a random number generator to produce a group of numbers following an exponential distribution (defined by k_{off1} , k_b , τ_{int} and τ_{tl}) (see Eq. 4-6 in main text). The number generator function was called a few times (typically 3-6) until the number of molecules in the first bin (n_1) of the histogram exceeded the user-specified number of molecules (N_1 , $N_1 = A \times B$ in mono-exponential distribution, or $N_1 = A \times B_1$ in multiple-exponential distribution). The k_{off2} and k_{off3} subpopulations were simulated in the same manner. Then, molecules from all simulated sub-populations were pooled and subject to bootstrapping analysis to construct the bootstrapped CRTDs (referred simply as CRTDs). This procedure was repeated for all specified values of τ_{tl} . The global fitting was performed on CRTDs from all τ_{tl} , using a CRTD for each τ_{tl} .



Figure S3. Scatter plots show distributions of τ obtained using global fitting on 100 simulated monoexponential ($\langle \tau \rangle = 100$ s) for each *n* value. (A) Simulation using the 10-s τ_{tl} set. (B) Simulation using the 100-s τ_{tl} set. (C) Simulated data from (B) were globally fitted with the amplitude as the global parameter. Apart from this panel, all global fittings in this study were performed with *A* as the local parameter. Red bars represent the averages.



Figure S4. Determination of time constants and amplitudes from bi-exponential distributions with an intermediate rate (k_{off1}) and a fast rate ($k_{off2} = 10k_{off1}$). (A-C) Scatter plots show distributions of *B*, τ_1 and τ_2 obtained using global fitting from 100 simulated distributions for each *n* value. Each panel corresponds to a pre-set *B*, which increases from 10%, 25%, 50%, 75% to 90% from left to right. In each panel, *n* increases from 10³ (1e3) to 10⁵ (1e5). Dashed lines and red bars represent the true values and the average respectively. Orange shades represent distributions where σ_B is larger than 0.1 or σ_{τ}/τ is larger than 20%. To enhance visibility, outliers (less than 5% when present) were omitted from scatter plots.



Figure S5. Bi-exponential distributions with an intermediate rate ($k_{off1} = 0.1 \text{ s}^{-1}$) and a fast rate ($k_{off2} = 1 \text{ s}^{-1}$) with infinite counts. (A) Representative k_{effTt} plots at 20 amplitudes of k_{off2} . From top to bottom, the amplitude reduces from 95% to 5%. (B) Integrated peak areas as a function of k_{off2} amplitudes (open circles). Line is the exponential fit to data points (R²: 0.9996). The peak area is calculated as the difference between areas under the k_{effTt} plots and the area under the line $y = 0.7 + 0.1\tau_{tl}$.



Figure S6. Determination of time constants and amplitudes from bi-exponential distributions with a slow rate ($k_{off1} = 0.01 \text{ s}^{-1}$) and an intermediate rate ($k_{off2} = 0.1 \text{ s}^{-1}$). (A-C) Scatter plots show distributions of *B*, τ_1 and τ_2 obtained from fitting of 100 simulated distributions to bi-exponential model. Each panel corresponds to a pre-set amplitude of *B*, which increases from 10%, 25%, 50%, 75% to 90% from left to right. In each panel, *n* increases from 10³ (1e3) to 10⁶ (1e6). Dashed lines and red bars represent the true values and the average respectively. Orange shades represent distributions where σ_B is larger than 0.1 or σ_{τ}/τ is larger than 20%. To enhance visibility, outliers (less than 5% when present) were omitted from scatter plots.



Figure S7. Determination of time constants and amplitudes from bi-exponential distributions with a slow rate (k_{off1}) and an intermediate rate ($k_{off2} = 10k_{off1}$), simulated using the 100-s τ_{tl} set. (A) $k_{eff}\tau_{tl}$ plots of bi-exponential distributions with $k_{b}\tau_{int}$ of 0.7, k_{off1} and k_{off2} of 0.01 and 0.1 s⁻¹ respectively, with 10⁵ observations. The amplitude of k_{off1} (B, shown on top) increases from left to right (10% to 90%). Shaded error bands are standard deviations from ten bootstrapped samples. (B-D) Scatter plots show distributions of B, τ_1 and τ_2 obtained from fitting of 100 simulated distributions to bi-exponential model. Each panel corresponds to a pre-set amplitude of B, which increases from 10%, 25%, 50%, 75% to 90% from left to right. In each panel, n increases from 10³ (1e3) to 10⁶ (1e6). Dashed lines and red bars represent the true values and the average respectively. Orange shades represent distributions where σ_B is larger than 0.1 or σ_t/τ is larger than 20%. To enhance visibility, outliers (less than 5% when present) were omitted from scatter plots.



Figure S8. Determination of binding lifetimes and amplitudes from bi-exponential distributions with closely spaced rates ($k_{off2} = 3k_{off1}$). (A-C) Scatter plots show distributions of *B*, τ_1 and τ_2 obtained from fitting of 100 simulated distributions for each *n* value. Each panel corresponds to a pre-set *B*, which increases from 10%, 25%, 50%, 75% to 90% from left to right. In each panel, *n* increases from 10³ (1e3) to 10⁵ (1e5). Dashed lines and red bars represent the true values and the average respectively. Orange shades represent distributions where σ_B is larger than 0.1 or σ_{τ}/τ is larger than 20%. To enhance visibility, outliers (less than 5% when present) were omitted from scatter plots.



Figure S9. Determination of binding lifetimes and amplitudes from tri-exponential distributions with a slow rate (k_{off1}), an intermediate rate ($k_{off2} = 10k_{off1}$) and a fast rate ($k_{off3} = 10k_{off2}$), using the 100-s τ_{t1} set. From left to right, five panels in each row correspond to different amplitudes of each sub-population (displayed on top). (A-E) Scatter plots show distributions of amplitudes (B_1 and B_2), τ_1 , τ_2 and τ_3 obtained using global fitting 100 simulated samples. In each panel, *n* increases from 10³ (1e3) to 10⁶ (1e6). Dashed lines and red bars represent the true values and the averages respectively. Orange shades represent distributions where σ_B is larger than 0.1 or σ_{τ}/τ is larger than 20%. To enhance visibility, outliers (less than 5% when present) were omitted from scatter plots.



Figure S10. Determination of time constants and amplitudes from bi-exponential distributions simulated with the five τ_{tl} set, and an intermediate rate ($k_{off1} = 0.1 \text{ s}^{-1}$) and a fast rate ($k_{off2} = 1 \text{ s}^{-1}$). (A-C) Scatter plots show distributions of *B*, τ_1 and τ_2 obtained from fitting of 100 simulated distributions to bi-exponential model. Each panel corresponds to a pre-set amplitude of *B*, which increases from 10%, 25%, 50%, 75% to 90% from left to right. In each panel, *n* increases from 10³ (1e3) to 10⁵ (1e5). Dashed lines and red bars represent the true values and the average respectively. Orange shades represent distributions where σ_B is larger than 0.1 or σ_{τ}/τ is larger than 20%. To enhance visibility, outliers (less than 5% when present) were omitted from scatter plots.



Figure S11. Determination of time constants and amplitudes from bi-exponential distributions simulated with the three τ_{tl} set, and an intermediate rate ($k_{off1} = 0.1 \text{ s}^{-1}$) and a fast rate ($k_{off2} = 1 \text{ s}^{-1}$). (A-C) Scatter plots show distributions of *B*, τ_1 and τ_2 obtained from fitting of 100 simulated distributions to bi-exponential model. Each panel corresponds to a pre-set amplitude of *B*, which increases from 10%, 25%, 50%, 75% to 90% from left to right. In each panel, *n* increases from 10³ (1e3) to 10⁵ (1e5). Dashed lines and red bars represent the true values and the average respectively. Orange shades represent distributions where σ_B is larger than 0.1 or σ_{τ}/τ is larger than 20%. To enhance visibility, outliers (less than 5% when present) were omitted from scatter plots.

Supplementary Notes

1. Simulation of a set of binding events whose lifetimes follow an exponential distribution with user-defined mean

```
function [counts, each molecule] = simulate res time(mu,edges,n count)
%% Inputs:
%% mu: mean of exponential distribution for a particular \tau_{t1}
88
     edges: bin edges of histograms
88
    n count: the number of counts for a particular 	au_{t1}
%% Outputs:
88
   counts: vector describing CRTD
88
     each molecule: vector containing all random number corresponding to
                   lifetimes of binding events
응응
each molecule = [];
counts = zeros(10,1);
%% generate a set of random numbers corresponding to lifetimes of binding
%% events until counts in the first bin exceed user-defined counts
while counts(1) < n count</pre>
% single iteration of the exprnd function
   sim = exprnd(mu,round(n count/2.71),1);
% construct the histogram with edges corresponding to frame times
% N is a vector containing counts in all bins [from the latest iteration]
    [N,~] = histcounts(sim,edges);
   counts = counts + N'; % add counts to the previous iterations
% combine lifetimes of binding events to existing population from previous
% iteration of the exprnd function
   each molecule = [each molecule; sim];
end
end % end of the function
```

2. Simulation of mono-, bi- or tri-exponential distribution across all τ_{ti}

```
%% Inputs:
88
   ttl: vector containing the set of time-lapse intervals
           photobleaching rate (unit: s^{-1})
88
     kb:
    tint: camera integration time
88
    koff1: user-defined off rate 1
88
    koff2: user-defined off rate 2
88
88
    koff3: user-defined off rate 3
    B(1): amplitude of the first kinetic sub-population
88
88
    B(2): amplitude of the second kinetic sub-population
응응
     n count total: user-defined counts for each simulation
%% Outputs:
88
    bin: matrix containing CRTDs for all time-lapse intervals
     d.data: contains the simulated population at a particular time-
88
88
     lapse interval
for i = 1:length(ttl)
                      % simulate CRTD for each time-lapse interval
    time = ttl(i)*(0:10)'; % determine frame times for binning
    %% define exponential distribution for each sub-population
    keff1 = (kb*tint/ttl(i) + koff1); % effective rate 1
    % mean of the exponential distribution of the first sub-population
    mu1 = 1/keff1;
    keff2 = (kb*tint/ttl(i) + koff2); % effective rate 2
    % mean of the exponential distribution of the second sub-population
    mu2 = 1/keff2;
    keff3 = (kb*tint/ttl(i) + koff3); % effective rate 3
    % mean of the exponential distribution of the third sub-population
    mu3 = 1/keff3;
    %% determine the number of counts for each sub-population based
    %% on the amplitudes B1 and B2
    % counts of the first kinetic sub-population
    n count1 = round(B(1)*n count total);
    % counts of the second kinetic sub-population
    n count2 = round(B(2)*n count total);
    % counts of the third kinetic sub-population
    n count3 = n count total - n count1 - n count2;
    % bin1, bin2 and bin3 are vectors containing CRTDs of koff1, koff2 and
    % koff3 sub-population respectively
    % population1, population2 and population3 are vectors containing
    % simulated koff1, koff2 and koff3 sub-population respectively.
    bin2 = zeros(10,1); population2 = [];
    bin3 = zeros(10,1); population3 = [];
    % simulate koff1 sub-population
    [bin1, population1] = simulate res time(mul,time,n count1);
    % simulate koff2 sub-population
    if n_count2 > 1
          [bin2, population2] = simulate res time(mu2,time,n count2);
    end
    % simulate koff3 sub-population
    if n count3 > 1
         [bin3, population3] = simulate res time(mu3,time,n count3);
    end
    % combine CRTDs from sub-population CRTDs
           bin(:,i) = bin1 + bin2 + bin3;
    % combine simulated population from simulated sub-populations
    d(i).data = [population1; population2; population3];
end
```

3. Global fitting

```
function [p out] = globalFit(i model, X, Y, tint)
%% Inputs:
88
     i model = 1 - mono-exponential model
     i model = 2 - bi-exponential model
22
88
     i model = 3 - tri-exponential model
88
     X: matrix containing frame times of all time-lapse intervals
22
           - row: frame times corresponding to one time-lapse interval
응응
           - column: increase in frame times
응응
     Y: matrix containing simulated CRTDs of all time-lapse intervals
응응
     tint: camera integration time
응응
    para: initial conditions
응응
       - mono-exponential model: [kb, koff1, counts]
88
       - bi-exponential model: [kb, koff1, B1, koff2, counts]
       - tri-exponential model: [kb, koff1, B1, koff2, B2, koff3, counts]
88
88
    lb: lower constraints
88
       - mono-exponential model: [kb, koff1, counts]
22
       - bi-exponential model: [kb, koff1, B1, koff2, counts]
88
       - tri-exponential model: [kb, koff1, B1, koff2, B2, koff3, counts]
응응
    ub: upper constraints
88
       - mono-exponential model: [kb, koff1, counts]
88
       - bi-exponential model: [kb, koff1, B1, koff2, counts]
응응
       - tri-exponential model: [kb, koff1, B1, koff2, B2, koff3, counts]
%% Outputs:
%% p out: vector containing outcomes of global fitting
88
           - p(1): kb
응응
           - p(2): koff1
응응
           - p(3): B1
응응
           - p(4): koff2
응응
           - p(5): B2
           - p(6): koff3
88
88
           - p(7): 1 - B1 - B2
88
           - p(8)-p(end): counts at time 0 for all time-lapse intervals
%% Known Parameters
ttl = X(:,1); % vector containing all time-lapse intervals
a_para = Y(:,1); % Initialize the vector for counts at time 0
weights = ones(size(X)); % fitting weights
lower B = 1/min(a para(a para>0)); % the lower bound for the amplitudes
upper koff = 1/tint; % the upper bound for off rates
if i model == 1 % fitting to mono-exponential function
    para = [1, 1, a para']; % initial conditions: kb, koff1, counts
    lb = [0, 0, zeros(size(ttl))']; % lower bounds: kb, koff1, counts
     % upper bounds: kb, koff1, counts
    ub = [Inf,upper_koff, Inf*ones(size(ttl))'];
    % define function to minimize
    f1 = Q(p) (
                 (model(i_model,p,X,tint,ttl)-Y).*weights);
    opts = optimset('Display', 'off');
    % Global fitting using the lsqnonlin function
     [p] = lsqnonlin(f1,para,lb,ub,opts);
    p_out = [p(1:2),1,zeros(1,4),p(3:end)];
elseif i model == 2 % fitting to bi-exponential function
    para = [1, 1, 0.5, 2, a_para'];
         = [0, 1e-3, lower_B, 1e-3, zeros(size(ttl))'];
    lb
         = [Inf, upper_koff, 1-lower_B, upper_koff, Inf*ones(size(ttl))'];
    ub
    \% define function to minimize
                 (model(i_model,p,X,tint,ttl)-Y).*weights);
    f1 = @(p)(
    opts = optimset('Display', 'off');
```

```
% Global fitting using the lsqnonlin function
     [p] = lsqnonlin(f1,para,lb,ub,opts);
      & assign the smaller off rate to be koff1
      p \text{ temp} = \text{sortrows}([p(2) \ p(3); \ p(4) \ (1 - p(3))]);
      p temp = p temp';
      p_out = [p(1), p_temp(:)', zeros(1,2), p(5:end)];
elseif i model == 3
      para = [1, 0.05, 0.3, 0.5, 0.3, 5, a para'];
      lb
           = [0, 1e-3, lower B, 1e-3, lower B, 1e-3, zeros(size(ttl))'];
      ub
           = [Inf, upper_koff, 1-lower_B, upper_koff, 1-lower_B, upper_koff,
            Inf*ones(size(ttl))'];
      % define function to minimize
      f1 = @(p) ( sum(sum((model(i model,p,X,tint,ttl)-Y).^2.*weights,2 )));
      opts = optimoptions('fmincon', 'MaxFunctionEvaluations', 10000,...
            'MaxIter', 3000, 'Algorithm', 'interior-point', 'StepTolerance',
            1.0000e-9);
      b = 1-2*lower B;
      A = [0,0,1,0,1,0,zeros(1,size(a para,1))];
      % Global fitting using the fmincon function
      [p] = fmincon(f1,para,A,b,[],[],lb,ub,[],opts);
      % assign the smallest off rate to be koff1 and the second smallest to
      % be koff2
      p temp = sortrows([p(2) p(3); p(4) p(5); p(6) (1-p(3)-p(5))]);
      p temp = p temp';
      p_out = [p(1),p_temp(:)',p(7:end)];
end
```

end % end of function

4. Define fitting models

```
function f = model(i model,para,X,tint,ttl)
%% Inputs:
22
     i model = 1 - mono-exponential model
     i model = 2 - bi-exponential model
88
     i model = 3 - tri-exponential model
88
     para: global parameters
응응
     X: frame times
응응
     tint: camera integration times
88
88
     ttl: time-lapse time
% ampl: vector containing counts for all time-lapse intervals
p = tint./ttl; p = p(:);
if i model == 1
   kb = para(1);
   koff1 = para(2);
   ampl = para(3:end);
   % mono-exponential model
   f = (ampl'*ones(1, size(X, 2))).*
       (exp(-((kb.*p + koff1)*ones(1,size(X,2))).*X));
elseif i model == 2 % bi-exponential model
   kb = para(1);
   koff1 = para(2);
   B1 = para(3);
   koff2 = para(4);
   ampl = para(5:end);
   % bi-exponential model
   f = (ampl'*ones(1,size(X,2))).*(B1.*exp(-((kb.*p + koff1)*
     ones(1,size(X,2))).*X)+(1-B1).*exp(-(kb.*p + koff2)*
     ones(1,size(X,2)).*X));
```

```
elseif i_model == 3
    kb = para(1);
    koff1 = para(2); B1 = para(3);
    koff2 = para(4); B2 = para(5);
    koff3 = para(6);
    ampl = para(7:end);
    % tri-exponential model
    f = (ampl'*ones(1,size(X,2))).*
        (B1.*exp(-((kb.*p + koff1) * ones(1,size(X,2))).*X)
            + B2.* exp( -(kb.*p + koff2)*ones(1,size(X,2)).*X)+
            (1-B1-B2).* exp( -(kb.*p + koff3)*ones(1,size(X,2)).*X ));
end
```

```
end % end of function
```