

1 Convex Hull Approach for Determining Rock Representative  
2 Elementary Volume for Multiple Petrophysical Parameters using  
3 Pore-scale Imaging and Lattice-Boltzmann modelling.

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5 **S.M.Shah\*, F.Gray, J.Yang, J.P.Crawshaw, and E.S.Boek**

6 **Qatar Carbonates and Carbon Storage Research Centre (QCCSRC)**  
7 **Department of Chemical Engineering, Imperial College London, London SW7 2AZ, UK**

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9 Corresponding author: \*Saurabh M Shah ([saurabh.shah10@imperial.ac.uk](mailto:saurabh.shah10@imperial.ac.uk))  
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11 **Highlights**

- 12 • Qualitative and quantitative method to capture heterogeneity at pore-scale  
13 • Multiple petrophysical parameters to determine Representative Element Volume  
14 • Enhancing computational efficiency to calculate petrophysical properties  
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27 **Abstract**

28 In the last decade, the study of fluid flow in porous media has developed considerably due to  
29 the combination of X-ray Micro Computed Tomography (micro-CT) and advances in  
30 computational methods for solving complex fluid flow equations directly or indirectly on  
31 reconstructed three-dimensional pore space images. In this study, we calculate porosity and  
32 single phase permeability using micro-CT imaging and Lattice Boltzmann (LB) simulations  
33 for 8 different porous media: beadpacks (with bead sizes 50 $\mu$ m and 350  $\mu$ m), sandpacks  
34 (LV60 and HST95), sandstones (Berea, Clashach and Doddington) and a carbonate (Ketton).  
35 Combining the observed porosity and calculated single phase permeability, we shed new light  
36 on the existence and size of the Representative Element of Volume (REV) capturing the  
37 different scales of heterogeneity from the pore-scale imaging. Our study applies the concept  
38 of the ‘Convex Hull’ to calculate the REV by considering the two main macroscopic  
39 petrophysical parameters, porosity and single phase permeability, simultaneously. To further  
40 enhance computational efficiency we note that the area of the convex hull (for well-chosen  
41 parameters such as the log of the permeability and the porosity) decays exponentially with  
42 sub-sample size so that only a few small simulations are needed to determine the system size  
43 needed to calculate the parameters to high accuracy (small convex hull area). Finally we  
44 propose using a characteristic length such as the pore size to choose an efficient absolute  
45 voxel size for the numerical rock.

46 **Keywords**

47 Representative Element Volume, porosity, single phase permeability, pore-scale, convex hull

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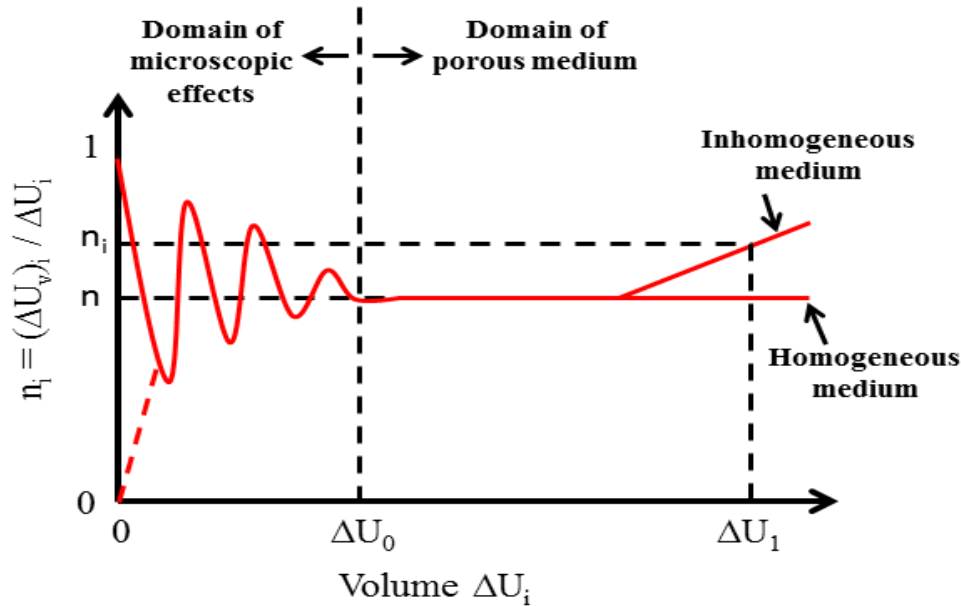
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## 56        **1. Introduction**

57    The physics of fluid flow through complex porous media has important applications in  
58    petroleum and reservoir engineering, including the displacement of oil, gas and water in  
59    hydrocarbon reservoirs and is of particular interest to understand the trapping of CO<sub>2</sub> for  
60    carbon storage applications (Fredrich, 1999; Andrew, Bijeljic, & Blunt, 2013; Shah, Yang,  
61    Crawshaw, Gharbi, & Boek, 2013). In the past, many researchers have attempted to relate  
62    fluid transport properties such as permeability to the bulk porosity and specific surface area,  
63    but complexity arises in predicting permeability accurately (Bear, 1972; Walsh & Brace,  
64    1984; Mostaghimi, Blunt, & Branko, 2013). Fluid transport properties depend critically on  
65    the size, shape and connectivity of the pore space and geometry of the porous medium.  
66    However, there is no accurate formula which can correlate permeability with bulk porosity  
67    without ambiguity. This motivated research in pore-scale imaging and modelling to obtain  
68    detailed information about the geometry of complex porous media and modelling the fluid  
69    flow at the pore-scale using different numerical simulation methods to predict the  
70    permeability accurately (Blunt, Jackson, Piri, & Valvatne, 2002; Valvatne & Blunt, 2004;  
71    Dong & Blunt, 2009; Boek & Venturoli, 2010; Yang, Crawshaw, & Boek, 2013; Shah,  
72    Crawshaw, & Boek, 2016). Pore-scale imaging and modelling is developing quickly and has  
73    now become a routine service in the petroleum industry, principally to understand  
74    displacement processes and to predict single phase and relative permeability (Blunt, et al.,  
75    2013). The fundamental problem in pore-scale imaging and modelling is how to represent  
76    and model the different range of scales encountered in porous media, starting from the  
77    unresolved sub-resolution micro-porosity. Bear [1972] has explained the concept of  
78    Representative Element of Volume (REV), qualitatively taking into consideration a  
79    macroscopic property, such as porosity. The REV is the minimum volume that can represent  
80    a particular macroscopic property of the sample. Figure (1) shows a graph to define the REV,  
81    where  $\Delta U_i$  is defined as a volume in a porous medium, and is considered to be much larger  
82    than a single pore or grain.  $\Delta U_v$  is the volume of void space, and the fractional porosity is  
83    defined by  $n_i$ , as the ratio of void space to volume. As shown in Figure (1), there are minimal  
84    fluctuations of porosity as a function of volume at large values of  $\Delta U_i$ . As the volume  
85    decreases, fluctuations in the porosity increase, specifically as  $\Delta U_i$  approaches the size of a  
86    single pore, which has a fractional porosity of 1. Therefore the REV is defined by the term  
87     $\Delta U_0$ , above which fluctuations of porosity are minimal, and below which fluctuations of

88 porosity are significant. The determination of the volume  $\Delta U_i$  is related to the different length  
 89 scales varying from pore-scale to core scale to continuum scale (Crawshaw & Boek, 2013).

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92 Figure 1 Schematic diagram showing the measured property varies with the sample volume and the domain of the  
 93 Representative Element Volume (REV) (Crawshaw & Boek, 2013).

94 Pore-scale techniques have to answer questions such as: “What is the actual size of an REV?  
 95 Does the size of the REV vary for different rock types? Are the REVs similar or significantly  
 96 different for different quantities at a given location? How do the transport and structural  
 97 properties such as permeability and porosity vary with scale?” (Zhang, Zhang, Chen, & Soll,  
 98 2000). The above listed questions were partly answered by Bear [1972], Bosl et al. [1998],  
 99 Pan et al. [2001], Zhang et al. [2000], Keehm [2003], Peng et al. [2012], Peng et al. [2014]  
 100 and Mostaghimi et al. [2013].

101 The concept of “statistical REV” was proposed by Zhang et al. (2000) to assess the size of the  
 102 REV more efficiently, comparing the results obtained from crushed glass beads and  
 103 sandstone with the outcome that the size of an REV varies spatially and depends on the  
 104 quantity being represented. Keehm [2003] found that to predict the absolute and relative  
 105 permeability of porous media, a minimum REV of size  $L = 20a$  is needed, where  $a$  is the  
 106 mean pore size of the porous medium using analysis of 2D thin sections. Mostaghimi et al.  
 107 [2013] demonstrated that the REV for permeability is larger than for static properties, such as  
 108 porosity and specific surface area. They also found that the REV for carbonate rocks appears

109 to be larger than the image size considered. However these previous studies only partly  
110 address issues regarding the concept of REV for pore-scale imaging and modelling and show  
111 its limitations. In this study we will address the correlation of REV with pore size and  
112 introduce a method by which the REV can be established for multiple parameters,  
113 considering porosity and permeability as an example.

114 We will now discuss the concepts of homogeneity and heterogeneity related to porous media  
115 studies. Homogeneity is defined qualitatively as the characteristic that a physical property has  
116 the same value in different elemental volumes regardless of their location (Olea, 1991).  
117 Therefore, the terms heterogeneity and homogeneity are dependent on the model or sample  
118 volume of the measured physical property (Nordahl & Ringrose, 2008). In this study, we  
119 systematically investigate the relation between two important macroscopic properties,  
120 porosity and absolute permeability, using pore-scale imaging and modelling techniques, to  
121 predict the representative element volume (REV). We use the mathematical concept of the  
122 Convex Hull,  $C_H$  to investigate the relation between porosity and permeability and examine  
123 the effects of rock sample heterogeneity and increasing sample size. The main aim is to  
124 explore this relation for 8 different types of porous materials, ranging from beadpacks to  
125 sandpacks to sandstones to carbonate rocks in terms of increasing heterogeneity and  
126 quantitatively determine the size of the REV for each. The approach could be extended to  
127 more complex flow calculations in porous media such as two-phase relative permeability and  
128 capillary pressure prediction.

## 129 **2. Pore-scale Imaging and Modelling**

130 The problem of REV determination in porous media can be quantitatively addressed using X-  
131 ray micro computed tomography (micro-CT), which is a widely used 3D imaging technique  
132 to obtain 3D images of porous media (Zhang, Zhang, Chen, & Soll, 2000). In addition, we  
133 use recent advances in computational methods for solving flow equations in complex  
134 geometries (Blunt, Jackson, Piri, & Valvatne, 2002; Blunt, et al., 2013; Boek & Venturoli,  
135 2010; Yang & Boek, 2013). Pore-scale images of the rocks can be obtained using micro-CT  
136 equipment using laboratory and synchrotron sources. Spanne et al. [1994] and Auzerais et al.  
137 [1996] used micro-CT to obtain 3D voxel data of sandstone at a voxel resolution of around  
138  $7.5\mu\text{m}$ . Blunt et al. (2013) have obtained data for carbonate samples at different voxel  
139 resolutions ranging from  $2.68\mu\text{m}$  to  $13.7\mu\text{m}$ . The reconstructed pore geometries from micro-  
140 CT have been used for the prediction of petrophysical properties including permeability,

141 porosity and formation factor (Arns, Knackstedt, Pinczewski, & Martys, 2004; Knackstedt, et  
142 al., 2006; Shah, Crawshaw, & Boek, Micro-Computed Tomography Pore-scale Study of Flow  
143 in Porous Media:Effect of Voxel Resolution, 2016).

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145 In this study, we compute absolute permeability using the Lattice Boltzmann (LB) method.  
146 This model is particularly suited to direct numerical simulation on pore-space images because  
147 of its ability to handle complex boundaries accurately. Moreover, the LB method does not  
148 require extracting a simplified network of flow paths, as in network modelling (Zhang,  
149 Zhang, Chen, & Soll, 2000), and so is able to give accurate permeability results in highly  
150 heterogeneous media. The LB model describes the fluid as a velocity distribution of particle  
151 distribution function at each node. These undergo streaming and collision steps according to a  
152 discrete form of the Boltzmann equation, and can be shown to recover the incompressible  
153 Navier-Stokes equations (Chen, Wang, Shan, & Doolen, 1992). The single-phase D3Q19  
154 lattice Boltzmann (LB) model with a multiple-relaxation-time (MRT) operator is used in our  
155 code ( (Yang, Crawshaw, & Boek, 2013).

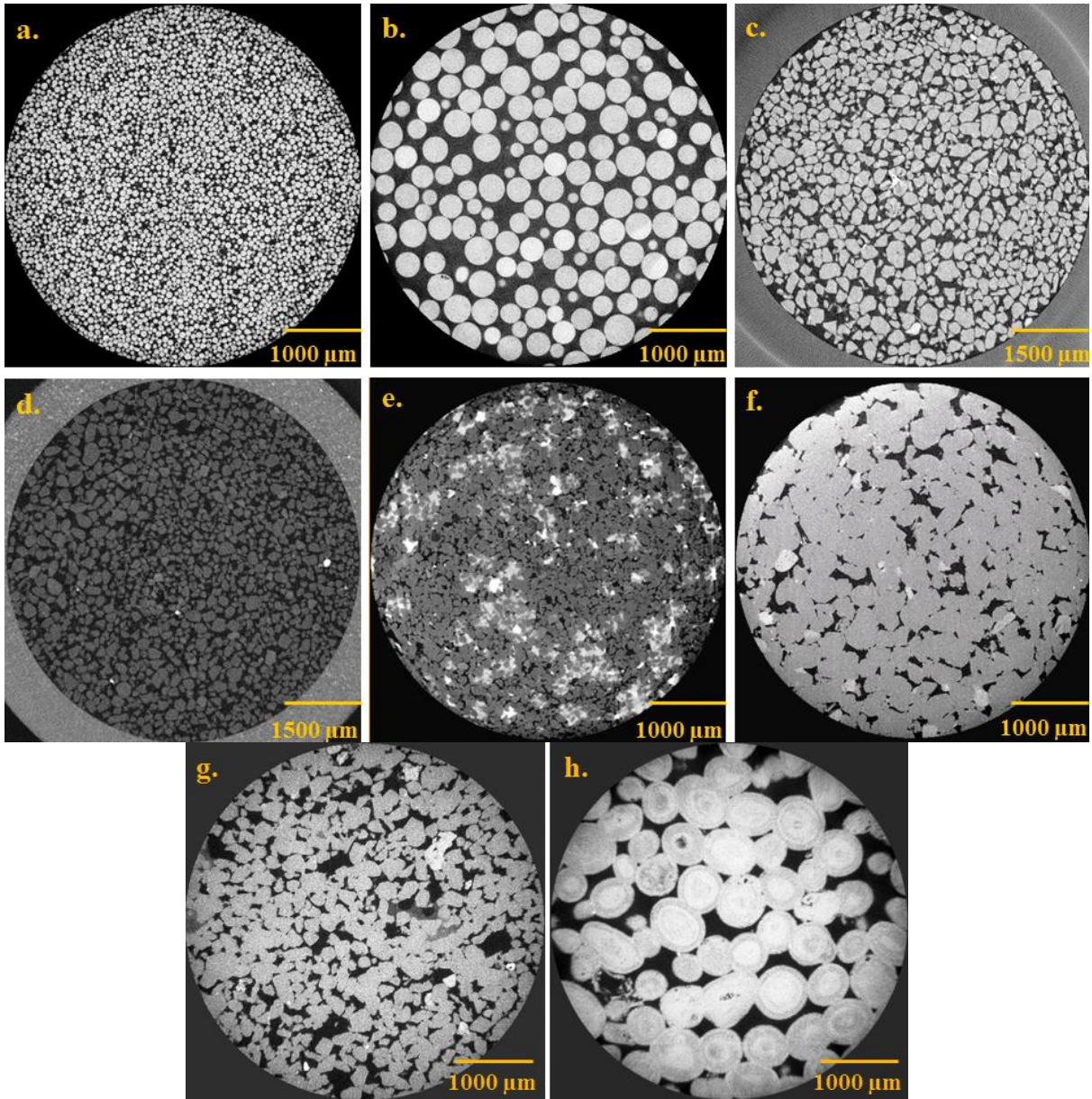
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### 157 **3. Methods and Techniques**

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159 The detailed 3D micro-CT image acquisition procedure is presented by Shah et al. [2015].  
160 Figure 2 shows 2D cross sections of 3D voxel data for 8 different porous materials, including  
161 beadpacks of two different bead sizes, two sandpacks, three sandstones and one carbonate.  
162 The 3D images for all the samples were subsequently segmented into binary images based on  
163 a 2D histogram segmentation analysis by using marker seeded watershed algorithm within  
164 the program Avizo Fire 8.0 (Visual Sciences Group, Burlington, MA, USA) (Shah,  
165 Crawshaw, & Boek, Micro-Computed Tomography Pore-scale Study of Flow in Porous  
166 Media:Effect of Voxel Resolution, 2016). 3D images of beadpacks, sandpacks, sandstones  
167 and carbonate samples were first cropped into 3D cubic images. The exact image dimensions,  
168 properties and details are summarized in Table 1.

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173 Figure 2 Two-dimensional cross sections of three dimensional micro-CT images of different samples. (a) Beadpack with  
 174 grain size 50 μm. (b) Beadpack with grain size 350 μm. (c) LV60 sandpack (d) HST95 sandpack (e) Berea sandstone (f)  
 175 Clashach sandstone (g) Doddington sandstone (h) Ketton carbonate. In all figures, the pore space is shown in dark.

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184 Table 1: Summary of the rocks and images studied in this paper. Porosity and single phase  
 185 permeability obtained from computation.

Sample	Source/ Scanner	Image Size, Voxels	Voxel Size ( $\mu\text{m}$ )	Porosity <sup>†</sup> (%)	Single Phase Permeability <sup>†</sup> (mD)
Beadpack -50 $\mu\text{m}$	Micro-CT	700 <sup>3</sup>	4.21	28.5	1474
Beadpack- 350 $\mu\text{m}$ <sup>a</sup>	Synchrotron	700 <sup>3</sup>	5.35	36.40	95400
LV60 sandpack <sup>b</sup>	Micro-CT	400 <sup>3</sup>	7.24	30.55	11860
HST95 sandpack <sup>b</sup>	Micro-CT	400 <sup>3</sup>	7.89	30.27	5235
Berea sandstone	Micro-CT	700 <sup>3</sup>	4.52	9.52	57.9
Clashach sandstone	Micro-CT	700 <sup>3</sup>	4.52	10.78	448
Doddington sandstone	Micro-CT	700 <sup>3</sup>	4.52	16.35	2442
Ketton carbonate	Micro-CT	700 <sup>3</sup>	4.52	13.04	5648

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<sup>†</sup> Computed from the destined voxels using Lattice Boltzmann code  
<sup>a</sup> Data obtained from Kamaljit Singh through personal communication  
<sup>b</sup> (Dong & Blunt, 2009)

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192 The experimental (total) porosity and single-phase permeability were measured on each of  
 193 the cylindrical core samples except beadpacks and sandpacks. The total porosity was  
 194 measured using bulk volume measurements and single phase permeability was measured  
 195 using the Darcy flow equation. The fluid was injected at constant flow rate and the pressure  
 196 drop across the length of the sample was monitored using a high precision pressure  
 197 transducer. A flow cell was designed to accurately measure the single phase permeability of  
 198 the core samples at three different flow rates (Gharbi & Blunt, 2012). Note that these  
 199 measurements are for the whole sample volume and not only the scanned region. The  
 200 experimental porosity and single phase permeability of each sample are presented in Table 2.

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210 Table 2: Experimental Petrophysical properties of the rocks considered in the present study

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Samples	Length [mm]	Diameter [mm]	Experimental Porosity [%]	Experimental Permeability [mD]
LV60 sandpack**	-	-	37.00 ±0.2	32000 ±300
HST95 sandpack**	-	-	33.4	7900
Berea sandstone	15.2	5	11.17 ±0.4	17.5 ±0.7
Clashach sandstone	11.6	5	11.02 ±0.2	365 ±116
Doddington sandstone	17.8	6	18.41 ±0.5	2362 ±221
Ketton carbonate	15.1	5	19.02 ±0.1	4271 ±300

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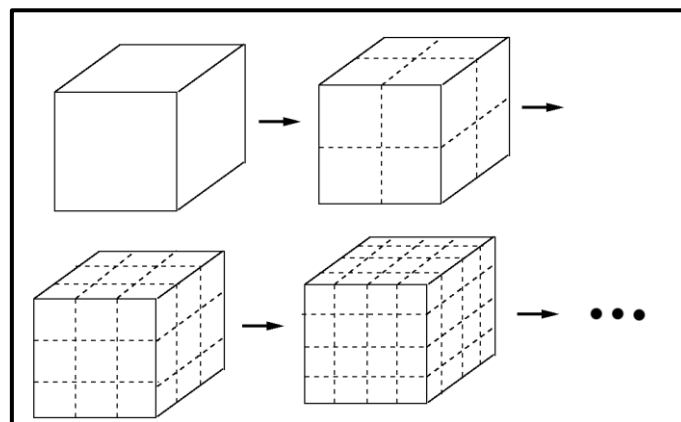
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215 \*\* Experimental porosity was measured on a packed column using bulk volume measurement and experimental brine  
 216 permeability was measured on a packed column by injecting brine at a constant flowrate (Pentland, 2010).

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218 The pore geometries of the porous samples are partitioned into several sub-domains which  
 219 are of the same size (Figure 2). For example, we consider 3D micro-CT data of a Doddington  
 220 sandstone sample consisting of  $700^3$  voxels with  $4.5\mu\text{m}$  voxel resolution representing a  
 221 physical area of 3.15 mm. We then perform this subsampling procedure with each of the 6  
 222 sub-domain sizes given in Table 3. The division of the geometry into different voxels or  
 223 image sizes is done in x-, y- and z- directions. The statistical distribution of parameters  
 224 obtained from individual subsamples allows for the characterisation of the sample REV.

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227 Figure 3 An example of domain partition. The scanned sample was divided into  $n^3$  sub-domains which have the same size.

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229 For the LB flow simulation, we impose a body-force throughout the domain or sub-domain  
 230 and periodic boundary conditions at the inlet and outlet faces, iterating the flow-field until it  
 231 reaches steady-state. Then, the single phase permeability is obtained from Darcy’s law. For  
 232 smaller sub-domains, there is no guarantee of convergence of the velocity field and therefore  
 233 the simulation continues for up to 50,000 LB time-steps. The sub-volume is discounted if the  
 234 velocity field does not converge by this limit. The calculation was run on a Tesla K20 GPU  
 235 with a 5GB memory but in cases where the sub-volume calculation required more memory  
 236 than this, the calculation was deferred to CPUs. The calculated LB single phase permeability  
 237 varies significantly for sub-domains therefore we normalise the permeability independently  
 238 for each porous sample by  $k' = \frac{k_{\text{sub-domain}}}{k_{\text{total}}}$  where  $k_{\text{sub-domain}}$  is the calculated LB permeability  
 239 of the particular single sub-domain size [mD],  $k_{\text{total}}$  is the calculated LB permeability of the  
 240 whole domain ( $700^3$  voxel) [mD] and  $k'$  is the normalised dimensionless permeability.

241 Table 3 Division of sub-domain voxel size from the whole domain of  $700^3$  with calculated linear dimensions from the voxel  
 242 resolution for Doddington sandstone sample.

Doddington sandstone Resolution – 4.5 $\mu\text{m}$	Sub-domain $700^3$ voxels	Linear dimension [ $\mu\text{m}$ ]
1	50 x 50 x 50	225
2	100 x 100 x 100	450
3	150 x 150 x 150	650
4	200 x 200 x 200	900
5	250 x 250 x 250	1125
6	300 x 300 x 300	1350
7	350 x 350 x 350	1575

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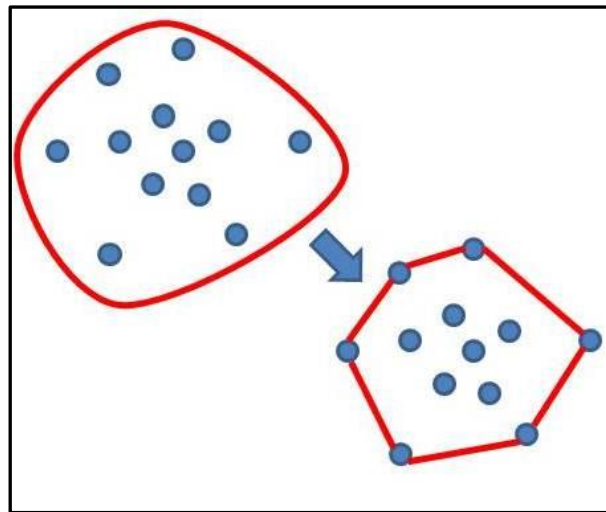
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#### 246 **4. Results and Discussion**

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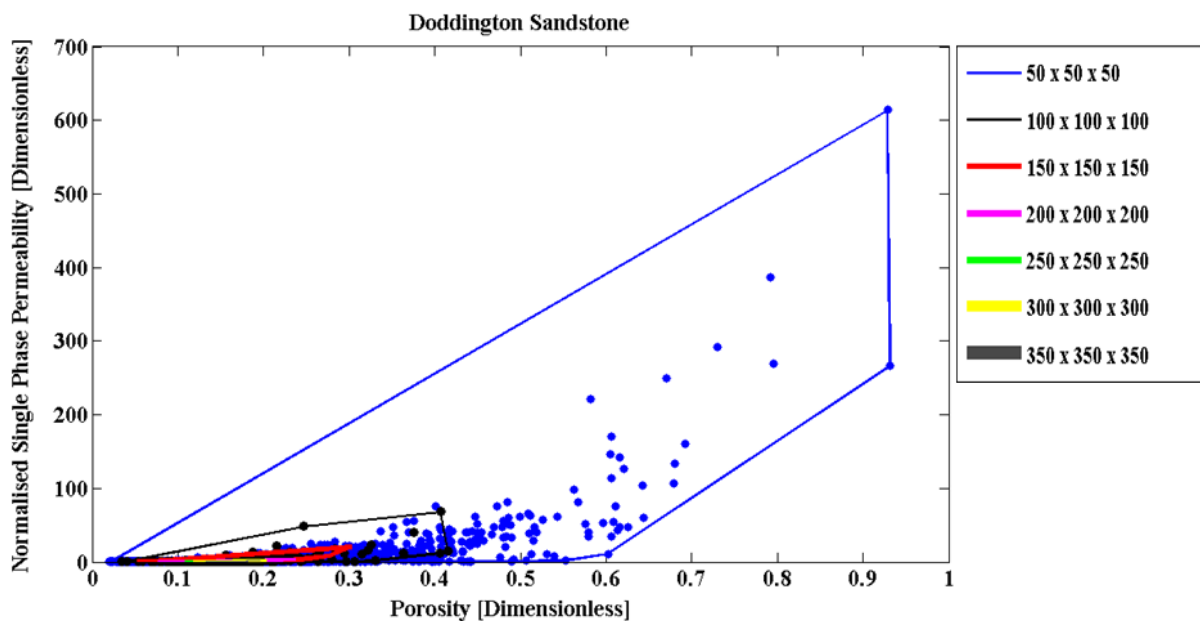
248 The porosity and single phase permeability for each sub-domain is calculated and used to  
 249 obtain the ‘Convex Hull’ for that domain size. The concept of the convex hull was explained  
 250 by Andrew (1979). Let us imagine the points S as being pegs; the convex hull of S is the

251 shape of a rubber band stretched around the pegs. The formal way to define the convex hull  
 252 of S is the smallest convex polygon that contains all the points of S as shown in figure 4.  
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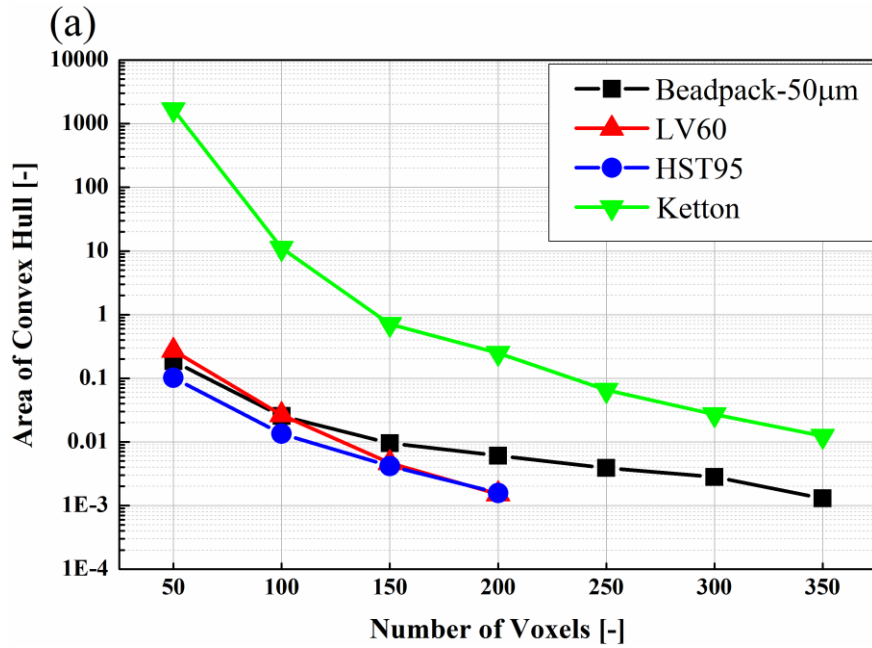
254  
 255 Figure 4. Example explaining the definition of convex hull of set of points S.

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 257 The process of obtaining a convex hull for each sub-domain was repeated for each of the 7  
 258 samples. Figure (5) shows the calculated porosity and single-phase permeability together with  
 259 the corresponding convex hulls for Doddington sandstone, for different sub-domains varying  
 260 from  $50^3$  to  $350^3$  voxels. Next we calculate the area of the resulting convex hulls and plot  
 261 these against the domain size in voxels, shown in Figure 6 for all the samples.

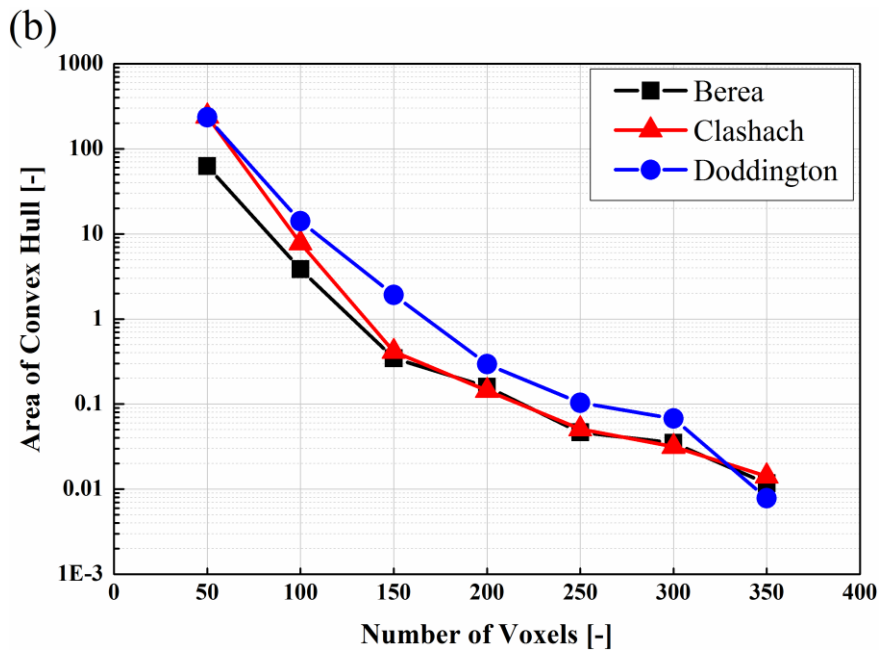


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 264 Figure 5. The concept of convex hull applied to the plotted values of porosity and single-phase permeability  
 265 calculated using LB method for different divided sub-domains varying from  $50^3$  to  $350^3$  voxels. The data is  
 266 shown for a Doddington sandstone sample.

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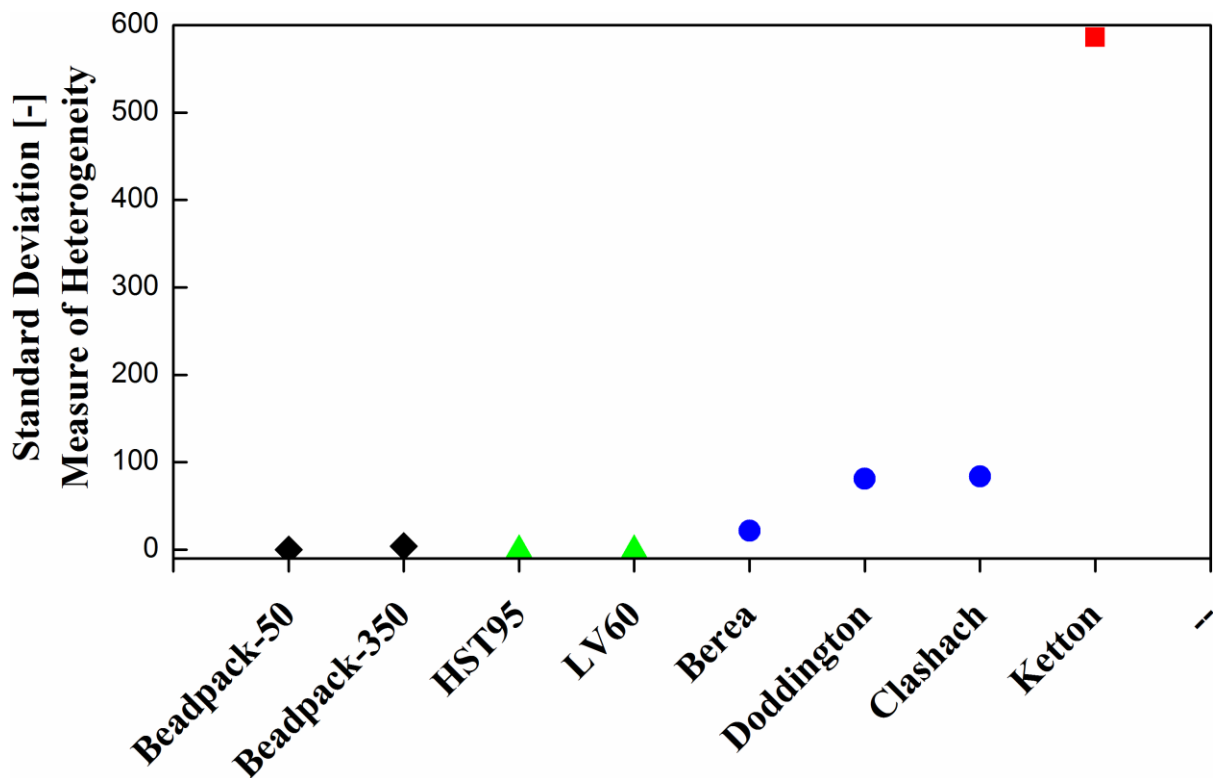
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273 Figure 6. The calculated area of convex hull for domain sizes ranging from  $50^3$  to  $350^3$  voxels is shown for beadpack,  
274 sandpacks and carbonate in figure (a), for sandstones in figure (b). The REV size for each sample can be determined by  
275 choosing an acceptable area for the convex hull, for example 0.5 will be used here, and reading the corresponding system  
276 size.

277 From Figures 5 and 6, we observe that the area of the convex hull systematically decreases as  
278 the size of the sub-domain increases from  $50^3$  to  $350^3$  voxels for each of the rock types. The  
279 REV is then estimated by choosing a value of the area of the convex hull area below which

280 the variations of both parameters are acceptable, for example 0.5. From figures 6 (a) and (b)  
 281 we can then determine the REV size for beadpacks, sandpacks, sandstones and carbonate  
 282 rock types. The beadpacks and the two sandpacks samples, LV60 and HST95, converge  
 283 faster than sandstones and carbonate needs only a sub-domain greater than  $50^3$  voxels (or 250  
 284  $\mu\text{m}$  in linear dimensions). Using the same hull area threshold of 0.5, the REV size for Berea  
 285 and Clashach sandstone comes to  $150^3$  voxels ( $750\mu\text{m}$ ), while for Doddington it is somewhat  
 286 larger, around  $200^3$  voxels ( $904\mu\text{m}$ ). The REV size for Ketton is greater than  $150^3$  voxels  
 287 ( $750\mu\text{m}$ ).

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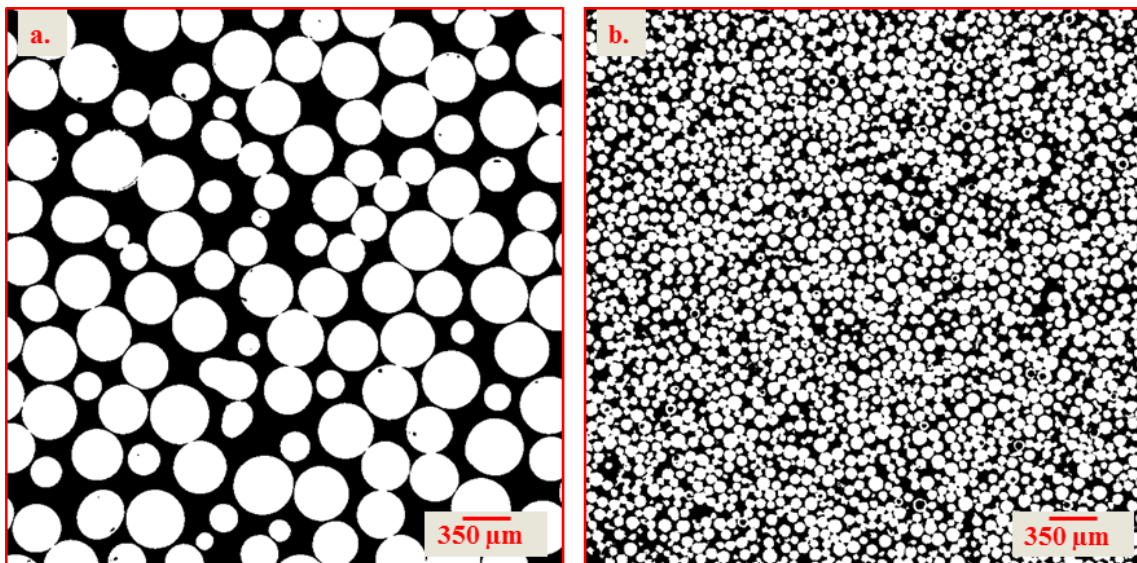
291 Figure 7. Standard deviation values for the calculated convex hull area for each rock sample as a function of  
 292 heterogeneity. Black indicates beadpacks, green indicates sandpacks, blue indicates sandstones and red indicate carbonate  
 293 samples.

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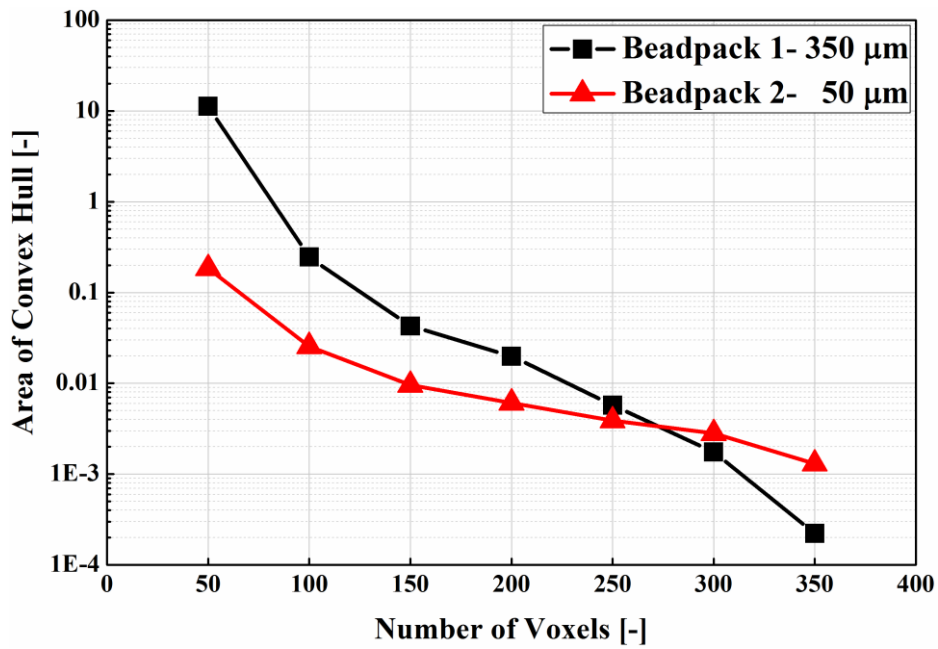
295 Another quantitative measure of heterogeneity is defined here as the standard deviation of the  
 296 calculated area of the convex polygon for the entire sub-divided domain varying from  $50^3$  to  
 297  $350^3$  voxels. Figure 7 shows this measure of heterogeneity for the entire library of rocks used  
 298 in this study. Comparing the standard deviations, to understand the heterogeneity of the rock  
 299 across the whole domain of  $700^3$  voxels, we observe that the calculated values of the standard  
 300 deviation are very small and constant for beadpacks and two sandpacks, LV60 and HST 95.

301 For beadpacks and sandpacks, the calculated standard deviations vary within a small range,  
302 whereas sandstone and carbonate rocks show a significant variation in the calculated standard  
303 deviation for different rock samples indicating the heterogeneity across the whole domain of  
304  $700^3$  voxels.

305 The REV sizes determined above suggest that we can capture a typical length scale of  
306 heterogeneity. However, this estimated REV size, although useful to estimate the size of  
307 simulation required for parameter estimation, does not allow a satisfactory ranking of sample  
308 heterogeneity. To illustrate this issue, consider two bead packs, of different grain size that are  
309 otherwise identical, as shown in Figure 8. The permeability/porosity convex hull areas of the  
310 two bead packs, shown in Figure 9, are very different, but intuitively both are equally  
311 homogeneous. Hence, there is a need to introduce a new scaling factor for sub-domain or  
312 voxel size to optimize the convex hull process to obtain a more satisfying description of the  
313 heterogeneity.



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315 Figure 8. Binarized two-dimensional cross-sections of the three dimensional data set of Bead packs with (a) Grain size =  
316  $350\mu\text{m}$  and (b) Grain size =  $50\mu\text{m}$  respectively. White colour represents the grain space and black colour indicates the pore  
317 space



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319 Figure 9. Calculated area of convex hull for voxel sizes ranging from  $50^3$  to  $350^3$  is shown for two bead packs with grain  
 320 sizes  $350\mu\text{m}$  and  $50\mu\text{m}$ .

321 The origin of the characteristic length is open to choice and the grain size is commonly used  
 322 in the literature (Kameda & Dvorkin, 2004). However, while this may be appropriate for  
 323 estimation of mechanical properties, the average pore diameter is a more natural choice for  
 324 fluid flow parameters. The average pore diameter for all the samples was estimated using the  
 325 maximum ball algorithm approach where spheres are grown in the pore space of segmented  
 326 3D micro-CT data, centred on each pore voxel (Dong & Blunt, 2009). Table 4 shows the  
 327 calculated mean pore size for the library of rock images used in this study.

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336 Table 4 Mean pore size for all samples estimated by the maximum ball algorithm.

Sample	Mean Pore Size ( $\mu\text{m}$ )
Beadpack – 50 $\mu\text{m}$	20.02
Beadpack – 350 $\mu\text{m}$	56.44
LV60 sandpack	47.5
HST95 sandpack	34.76
Berea sandstone	20.98
Clashach sandstone	34.92
Doddington sandstone	37.18
Ketton carbonate	57.18

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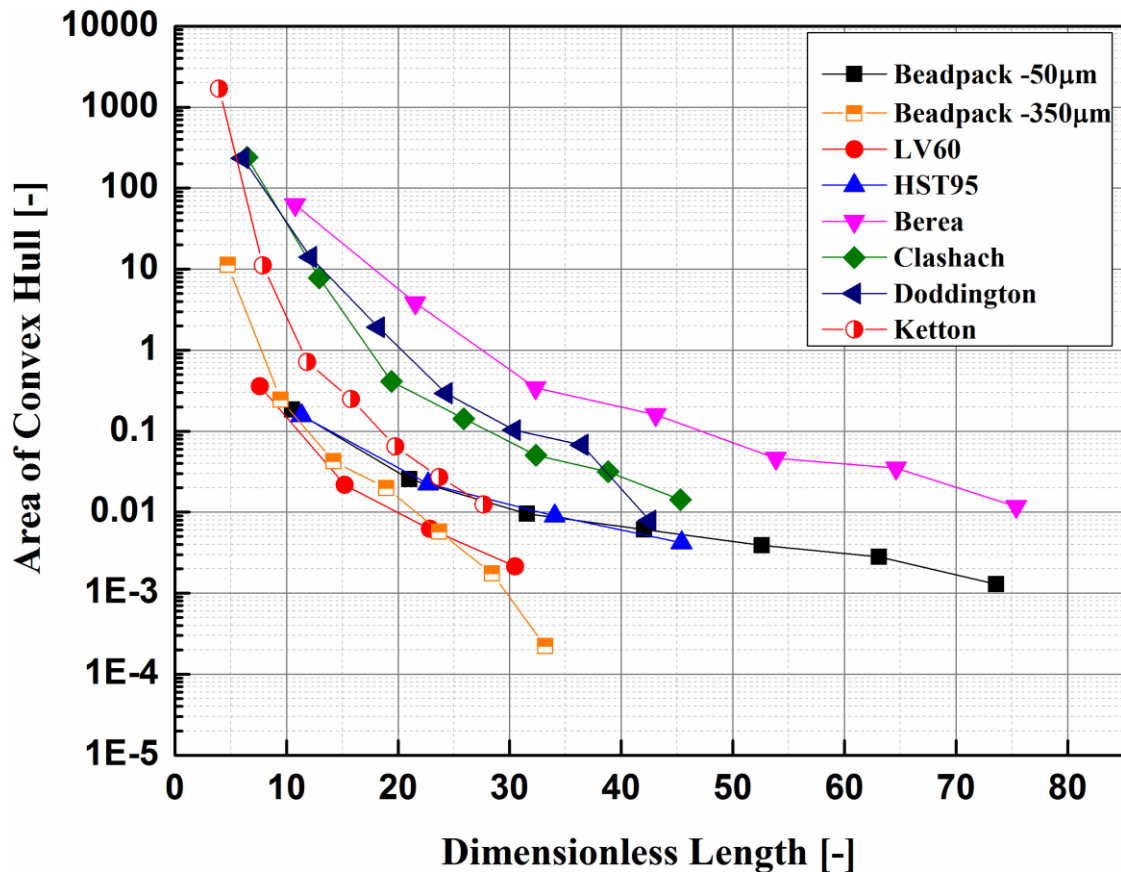
338 We have scaled the sub-domain sizes for all the samples by the corresponding mean pore size  
 339 and Figure 10 shows the convex hull areas plotted against the resulting dimensionless length.  
 340 The scaling resolves several issues in the comparison of relative heterogeneity. In the earlier  
 341 analysis Ketton, a well-sorted oolitic limestone with almost spherical grains, appeared more  
 342 heterogeneous than the sandstones, whereas Figure 10 shows that this was mostly due to the  
 343 large pore size of Ketton which now falls close to the group of sandpacks. The other  
 344 carbonate samples show how the different range of heterogeneity is captured as the scaled  
 345 voxel size increases. These are found to converge much more slowly than homogeneous  
 346 sandpacks and sandstone. Estailades carbonate fails to converge even for a  $350^3$  domain size  
 347 and would require a larger volume to capture the heterogeneity. This therefore represents the  
 348 most heterogeneous sample for the entire rock library studied.

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350 Figure 10 also shows that simply relating the REV to pore size is insufficient as the data do  
 351 not collapse onto a master curve now system size is scaled by pore size. Keeping our choice  
 352 of acceptable hull area at 0.5, only Clashach and Doddington fall close to the  $L = 20a$   
 353 relationship proposed by Keehm (Keehm, 2003). The beadpacks and sandpacks, on the other  
 354 hand, reach the threshold around  $10a$  and Ketton carbonate around  $12a$ . The more complex  
 355 Berea sandstone requires around  $35a$ .

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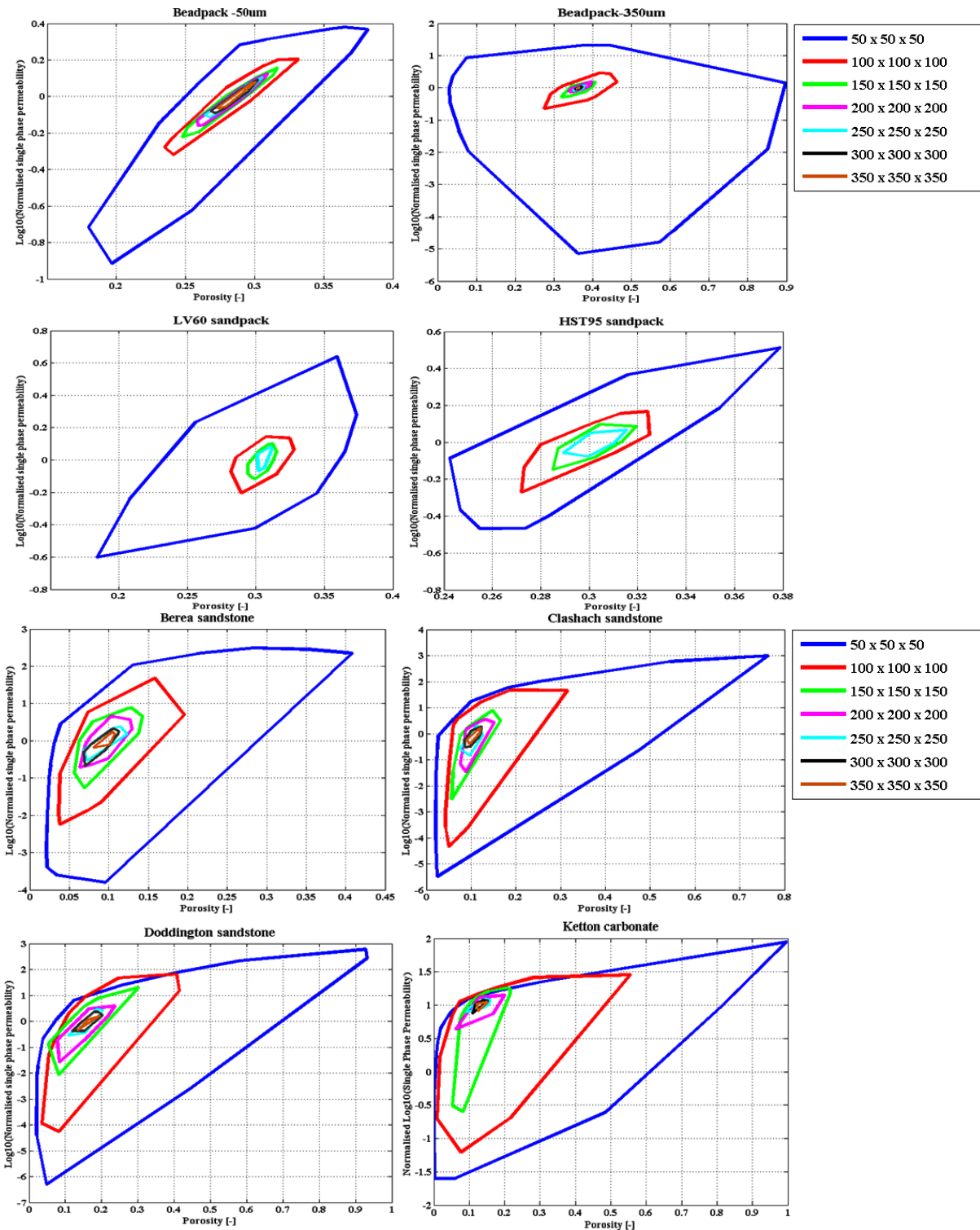
359 Figure 10. Porosity/permeability convex area against dimensionless for the entire rock library.

360 In the examples above, the permeability ranges over several orders of magnitude.  
 361 Consequently the variance to small permeability has little impact on the area of the convex  
 362 hull, as can be seen in Figure 5 where the shape of the hull becomes rather linear as the  
 363 system size is increased. A more evenly weighted convex hull can be made when the log of  
 364 the permeability is taken first for each of the sub-sampled system sizes and then normalised  
 365 with respect to the log of the permeability calculated from the largest system size. This is  
 366 shown, again for the Doddington sandstone, in Figure 11 where the hull retains its two-  
 367 dimensional shape at intermediate system sizes.

368

369 Note that there is evidence for a correlation between permeability and porosity in figure 11 as  
 370 the hull tends towards a line with a finite slope at large system size. In this case the porosity  
 371 and permeability converge at a similar rate, as the hull would tend towards either a vertical or  
 372 horizontal line if one variable reached a stationary value before the other as the system size  
 373 was increased. This implies that the REV for permeability and porosity are similar in the

374 Beadpack-50 $\mu$ m sample. However this behaviour was not universal, particularly for the other  
 375 samples.



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379 Figure 11. Convex hull of Log<sub>10</sub>(K) against porosity. (a) Beadpack 50  $\mu$ m. (b) Beadpack 350  $\mu$ m. (c) HST95 sandpack (d)  
 380 LV60 sandpack (e) Berea sandstone (f) Clashach sandstone (g) Doddington sandstone (h) Ketton carbonate.

381

382 Interestingly, plotting the convex hull area of the log(k), porosity space against the  
 383 dimensionless length, improves the exponential decay fit as is shown in Figure 12 (a) for  
 384 beadpacks, sandpacks, carbonate and Figure 12 (b) for sandstones rocks respectively. They  
 385 are all linear on a log (area of convex hull) – linear (length) graph. This suggest a further gain  
 386 in computational efficiency to be made by only computing the parameters for small system  
 387 sizes and using the resulting exponential to extrapolate REV. Table 5 shows the predicted  
 388 exponential decay constant and the pre-factor predicted from the exponential decay fit to  
 389 obtain quantitative data for all the rocks studied using

390

$$391 \quad A = ae^{kl}, (k < 0) \quad (1)$$

392 where,

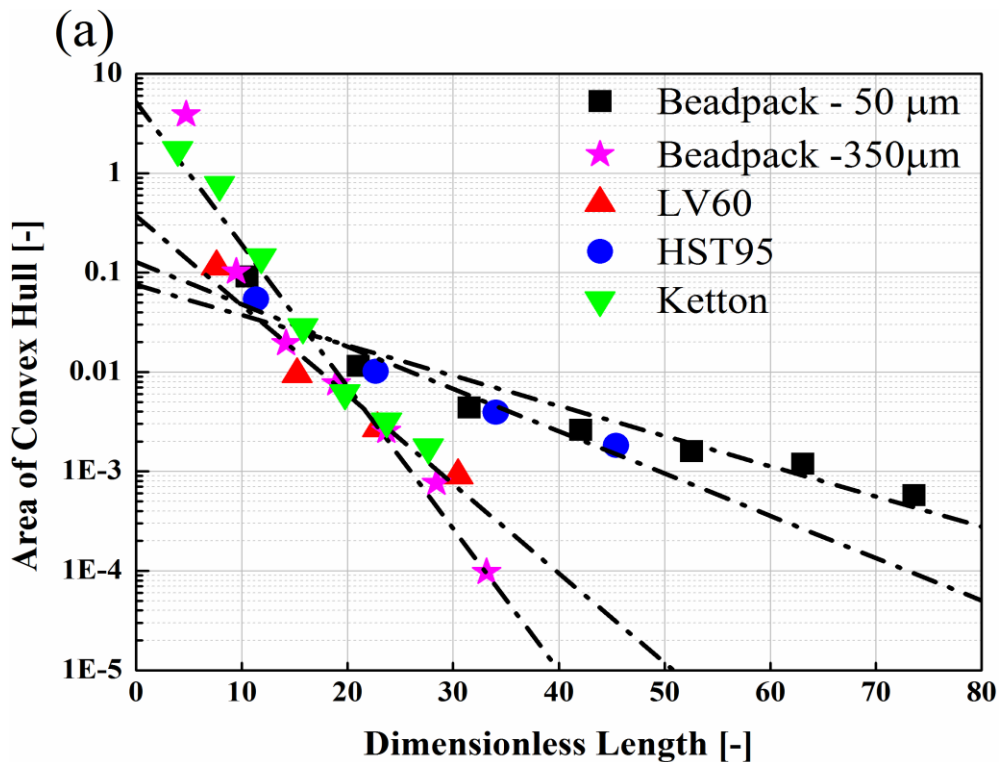
393 A = Convex hull area

394 a = Exponential pre-factor constant

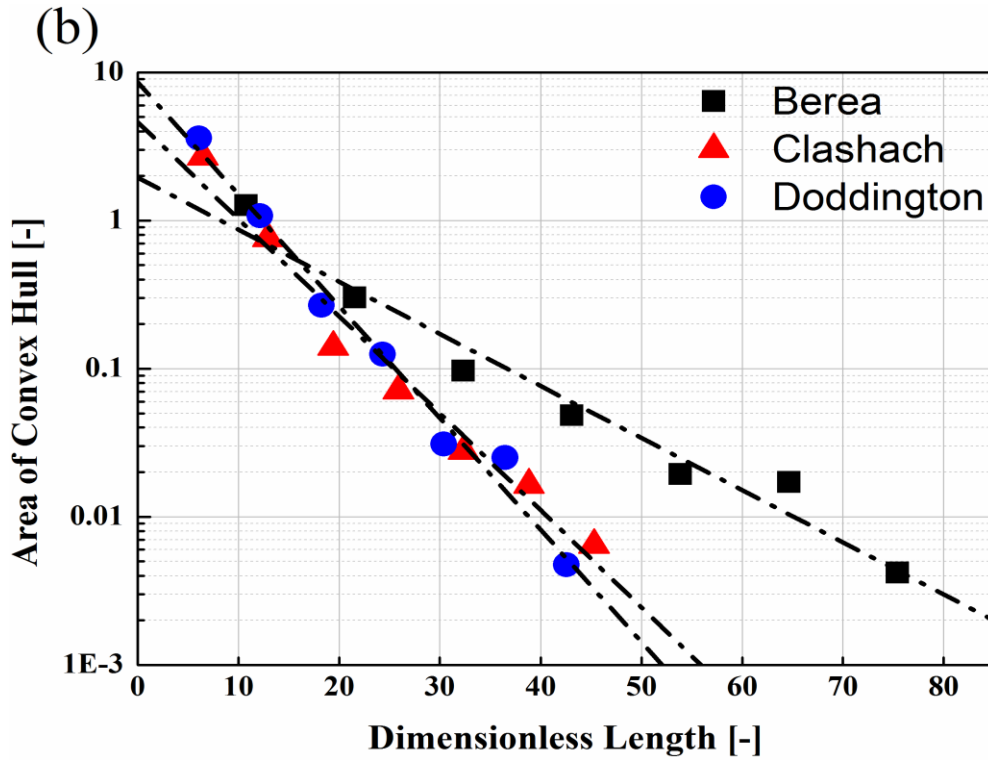
395 k = Exponential decay constant

396 l = dimensionless length

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400 Figure 12. Logarithmic area of convex hull showing exponential decay (dash line, black colour) when plotted against  
 401 dimensionless length. (a) Beadpacks, sandpacks and carbonate samples. (b) Sandstone samples.

402

403 Table 5 Predicted exponential pre-factor and decay constant for the different rocks studied.

Sample	Exponential pre-factor constant	Exponential decay constant	R <sup>2</sup>
Beadpack-50µm	0.0752	-0.07	0.8966
Beadpack-350µm	5.164	-0.329	0.9512
LV60 sandpack	0.3725	-0.207	0.9575
HST95 sandpack	0.128	-0.098	0.9656
Berea sandstone	1.95	-0.081	0.968
Clashach sandstone	4.6473	-0.151	0.9721
Doddington sandstone	8.5826	-0.174	0.984
Ketton carbonate	5.8244	-0.314	0.9754

404

405 The values of the exponential pre-factor and decay constant in Table 4 show a systematic  
 406 trend for the different rocks studied. The decay constant for Berea is -0.08 and about -0.17 for  
 407 Doddington sandstone. This means that the decay is slower for a heterogenous rock (Berea)  
 408 than for a relatively homogenous rock (Doddington and Clashach). This in turn suggests that

409 a critical value of the REV is reached more quickly (at smaller dimensionless length) for  
410 homogenous than for more heterogenous sandstones. This is what we expect qualitatively  
411 (see Figure 10), but now we can quantify this for different rocks by providing the value of the  
412 decay exponent and the pre-factor from the exponential fit.

## 413 **5. Conclusions**

414 We quantified the degree of heterogeneity for different rock samples by sampling the  
415 porosity and permeability at different sub-volume sizes and using the convex hull concept. In  
416 the past, the REV size was determined from individual macroscopic properties such as  
417 porosity, permeability and specific surface area, but here we are computing an REV size  
418 based on two parameters combined. By scaling the volume dimension with an average pore-  
419 diameter, a quantitative measure of REV size was obtained from the convergence behaviour  
420 of the convex hull area as the volume considered increased. It was found that this  
421 convergence behaviour can be extrapolated from a few data points from small sub-volume  
422 sizes on a logarithmic scale, potentially reducing the computational workload required in  
423 REV determination with this method. The convex hull technique can in principle be extended  
424 to include further macroscopic properties, and this will be investigated in future studies.

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